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# An EWMA Sign Chart for dispersion with exact Run Length properties 

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#### Abstract

The EWMA Sign control chart is a distribution-free scheme used for monitoring shifts in the location parameter during process monitoring. In this work, we propose a modified Phase II EWMA chart based on a general Sign statistic, capable of monitoring shifts in the process variability. Regarding the determination of the proposed chart's in- and out-of-control Run Length properties, Markov chain methods are used in combination with a continuous transformation of the suggested general Sign statistic. Our results show the power of the proposed method regarding the proposed chart's exact Run Length properties and its efficiency in detecting shifts in the process variability.


## KEYWORDS

distribution-free; Sign statistic; Markov chain; EWMA control chart; variability

## 1. Introduction

Control charts have been widely used in manufacturing industries, as a powerful tool for the on-line monitoring of a process. Shewhart [1] is considered as the pioneer of control charts, introducing schemes capable of monitoring relative large shifts in the process mean ( $\bar{X}$ chart) or the variability ( $R$ and $S$ charts). Additionally, when shifts of small magnitude occur in the process parameters, Cumulative Sum (CUSUM, see Page in [2]) or Exponentially Weighted Moving Averge (EWMA, see Roberts in [3]) charts are preferable due to their superiority in early shift detection. In general, in the design of conventional control charts as the ones mentioned above, it is assumed that the distribution of the observations collected over time is known, with the most common choice being that of normal distribution. However, in practice, either the assumption of, say, normal distribution is violated or practitioners do not want to use a specific distribution model for their process. As a result, designing schemes capable of monitoring shifts in the process without any knowledge of the
observations' underlying distribution, has drawn the researchers' attention and led to nonparametric (or distribution-free) control charts. In particular, with regard to monitoring process location, nonparametric tests such as the Sign Test are used for detecting shifts in the process median without the knowledge of the distribution of the quality characteristic of interest (see, [4], [5], [6], [7], [8], [9], [10]). Similarly, several nonparametric control charts have been introduced in the literature for detecting shifts in the process variability, such as Shewhart-type (see, [11], [12], [13], [14]) or EWMA and CUSUM schemes (see, [15], [16], [17], [18], [19]). For a comprehensive overview of existing univariate and multivariate nonparametric control charts the reader is advised to refer to [20] and [21].

With respect to the design of a phase II control chart, for Shewhart-type schemes, their Run Length (RL) properties, such as the Average Run Length (ARL) and the Standard Deviation Run Length (SDRL), are obtained by assuming that the random variable RL follows a geometric distribution. On the other hand, for EWMA and CUSUM-type schemes, their RL properties are usually computed using the Markov chain method of Brook and Evans in [22]. However, as recent studies have shown (see, Wu et al. in [23] and Perdikis et al. in [24]), the method of Brook and Evans [22] does not always provide a reliable approximation of the RL properties of a nonparametric EWMA or CUSUM control chart. More specifically, due to the discrete nature of the statistics whose values are monitored (for example the sign statistic), the method of Brook and Evans [22] leads to unreliable results regarding the chart's in-control and out-of-control ARL values. As a solution to this problem, Castagliola et al. in [25], following the approach of Rakitzis et al. in [26]), proposed an EWMA-type scheme (denoted as the CEWMA SN chart) in which the charting statistic, at each sampling point is an integer, and by adding some simple modifications in the Markov chain method, it was possible to determine the exact in- and out-of-control ARL values. Additional studies based on the approach of Castagliola et al. (2019) in [25] can also be found in [27] and [28]. Recently, Wu et al. in [23], proposed a new method, in which the initial discrete random variable to be monitored is turned into a continuous one, as a mixture of normally distributed random variables. Based on their findings, their proposed method, yields steady ARL values and it guarantees a reliable and accurate approximation of chart's RL properties.

In this work, we aim to present a new nonparametric control chart for monitoring the process variability. In particular, a generalization of the charting statistic used by Amin et al. in [11] will be introduced for the design of the proposed scheme and detailed guidelines to practitioners will be given regarding the chart's optimal design parameters. Additionally, we will provide a methodology that will guarantee the chart's exact RL properties. More specifically, as it will be proven in the following sections, the proposed control chart is distribution-free meaning that its statistical design does not require any knowledge about the underlying distribution and it has reliable and steady ARL values.

This paper is organised as follows: In Section 2, a brief review on the theoretical properties of the nonparametric Shewhart chart, introduced by Amin et al. in [11], based on the Sign-type statistic for dispersion is presented and a general version of this statistic is suggested. Additionally, in Section 3, a modified EWMA chart based on the Sign statistic for monitoring shifts in the process variability is introduced and in Section 4, the efficiency of the method of Brook and Evans [22] is tested for the compu-
tation of the proposed chart's RL properties. In Section 5, a Kernel-based methodology is used in order to improve the proposed chart's in- and out-of-control RL properties. Moreover, in Section 6, the out-of-control performance of the proposed chart is investigated and its performance is compared with other schemes for monitoring process variability. Finally, in Section 7 an illustrative example is provided while in Section 8 conclusions along with suggestions for future research work are given.

## 2. The Interquantile Range Sign statistic for dispersion

Suppose that, at each sampling point $t$, a random sample $\left\{X_{t, 1}, X_{t, 2}, \ldots, X_{t, n}\right\}$ of size $n$ is collected, where $X_{t, j}, j=1,2, \ldots, n$, follows an unknown continuous distribution with corresponding cumulative distribution function (c.d.f.) $F_{X}(x \mid \sigma)$. The parameter $\sigma$ corresponds to the standard deviation of the distribution, that is the parameter of interest. It is assumed that $\sigma=\sigma_{0}$ when the process is in-control and $\sigma=\sigma_{1}=\tau \sigma_{0}$ when the process is out-of-control. The parameter $\tau$ reflects the shift magnitude in the process variability, i.e. $\tau \in(0,1)$ corresponds to a decrease in the variability (usually associated to a process improvement) while $\tau \in(1,+\infty)$ corresponds to an increase in the variability (usually associated to a process deterioration).

Let $X_{p_{0} / 2}$ and $X_{1-p_{0} / 2}$ be the $p_{0} / 2$ and $1-p_{0} / 2$ quantiles of $F_{X}\left(x \mid \sigma_{0}\right)$, i.e. when the process is in-control, where $p_{0} \in(0,1)$ is a parameter considered to be known (or pre-specified). By definition, $X_{p_{0} / 2}$ and $X_{1-p_{0} / 2}$ are such that $F_{X}\left(X_{p_{0} / 2} \mid \sigma_{0}\right)=p_{0} / 2$, $F_{X}\left(X_{1-p_{0} / 2} \mid \sigma_{0}\right)=1-p_{0} / 2$ and and we directly deduce that

$$
p_{0}=1-F_{X}\left(X_{1-p_{0} / 2} \mid \sigma_{0}\right)+F_{X}\left(X_{p_{0} / 2} \mid \sigma_{0}\right) .
$$

When the process shifts from $\sigma_{0}$ to $\sigma_{1}$, the corresponding probability is defined as

$$
p_{1}=1-F_{X}\left(X_{1-p_{0} / 2} \mid \sigma_{1}\right)+F_{X}\left(X_{p_{0} / 2} \mid \sigma_{1}\right) .
$$

If $\sigma_{1}<\sigma_{0}$ (decrease in the variability) then we have $p_{1}<p_{0}$ and if $\sigma_{1}>\sigma_{0}$ (increase in the variability) then we have $p_{1}>p_{0}$. Consequently, a shift from $\sigma_{0}$ to $\sigma_{1}$ in one direction is similar to a shift from $p_{0}$ to $p_{1}$ in the same direction. This suggests a simple distribution-free Shewhart-type Sign chart for monitoring shifts in the process variability based on the following statistic

$$
\mathrm{SD}_{t}=\sum_{j=1}^{n} D_{t, j}
$$

where

$$
D_{t, j}=\left\{\begin{array}{ll}
1, & \text { if } X_{t, j}<X_{p_{0} / 2} \text { or } X_{t, j}>X_{1-p_{0} / 2} \\
0, & \text { if } X_{t, j}=X_{p_{0} / 2} \text { or } X_{t, j}=X_{1-p_{0} / 2} . \\
-1, & \text { if } X_{p_{0} / 2}<X_{t, j}<X_{1-p_{0} / 2}
\end{array} .\right.
$$

Note that, due to the continuous nature of the variables to be monitored, the condition $D_{t, j}=0$ is not supposed to hold in practice. Similarly with the theoretical properties of the traditional Sign statistic for testing changes in the median, the $\mathrm{SD}_{t}$
statistic belongs to $\{-n,-n+2, \ldots, n-2, n\}$. In addition, let us define the random variable $A_{t}=\frac{\mathrm{SD}_{t}+n}{2}$ as the number of observations less than $X_{p_{0} / 2}$ or larger than $X_{1-p_{0} / 2}$. By definition, this random variable $A_{t}$ follows a binomial distribution $\operatorname{Bin}(n, p)$ with parameters $n$ and $p \in\left\{p_{0}, p_{1}\right\}$ (depending on whether the process is inor out-of-control). Therefore, we obtain the c.d.f. $F_{\mathrm{SD}_{t}}(s \mid n, p)$ of $\mathrm{SD}_{t}$ with the help of the c.d.f. $F_{\mathrm{Bin}}(\cdot \mid n, p)$ of the $\operatorname{Bin}(n, p)$ as

$$
F_{\mathrm{SD}_{t}}(s \mid n, p)=F_{\mathrm{Bin}}\left(\left.\frac{s+n}{2} \right\rvert\, n, p\right), s \in\{-n,-n+2, \ldots, n-2, n\} .
$$

In addition, the mean $\mathrm{E}\left(\mathrm{SD}_{t}\right)$ and the variance $\mathrm{V}\left(\mathrm{SD}_{t}\right)$ are given by

$$
\begin{align*}
& \mathrm{E}\left(\mathrm{SD}_{t}\right)=2 \mathrm{E}\left(A_{t}\right)-n=n(2 p-1),  \tag{1}\\
& \mathrm{V}\left(\mathrm{SD}_{t}\right)=4 \mathrm{~V}\left(A_{t}\right)=4 n p(1-p) . \tag{2}
\end{align*}
$$

In general, in existing works related with nonparametric Shewhart schemes based on the Interquantile Range Sign statistic ([11]), a fixed value of $p_{0}=0.5$ has being considered regardless of the shift magnitude to be detected. Pawar et al. in [29] proposed a nonparametric upper-sided Shewhart chart for dispersion, based on the $\mathrm{SD}_{t}$ statistic where the value of $p_{0}$ is allowed to vary. During the design phase of their scheme, for different values of $p_{0}$, they examined the chart's out-of-control performance. Note that, Pawar et al.[29] only considered values of $\tau>1$ (i.e., the case of increasing shifts in process variability). In this work, we aim to introduce an EWMA chart based on the $\mathrm{SD}_{t}$ statistic and investigate the optimal value of $p_{0}$ for efficiently monitoring a process and detecting a specific shift (increase or decrease) of magnitude $\tau$ in the in-control variability $\sigma_{0}$.

## 3. The D-SN EWMA chart for dispersion

The nonparametric EWMA chart based on the Sign statistic was originally introduced by Graham et al. in [5] as a control scheme capable of detecting shifts in the process median. Using the Markov chain approach of Brook and Evans in [22], they computed its optimal design parameters and presented its out-of-control performance under different continuous distributions. In this work, we will present an extended version of the Sign EWMA chart presented in [5] for monitoring shifts in the process variability. In particular, based on the design of the standard Sign EWMA scheme introduced in [5], instead of using the Sign statistic, we will use the $\mathrm{SD}_{t}$ statistic, previously presented in Section 2, for monitoring shifts in the process dispersion.

### 3.1. Charting statistic and control limits

The plotting statistic for the two-sided EWMA chart based on the $\mathrm{SD}_{t}$ statistic suggested in the previous Section (to be denoted as the D-SN EWMA chart) will be computed by the following recursive formula as:

$$
\begin{equation*}
Z_{t}=\lambda \mathrm{SD}_{t}+(1-\lambda) Z_{t-1}, Z_{0}=\mathrm{E}_{0}\left(\mathrm{SD}_{t}\right), \tag{3}
\end{equation*}
$$

with $\lambda \in(0,1]$ and $\mathrm{E}_{0}\left(\mathrm{SD}_{t}\right)$ is the in-control mean of $\mathrm{SD}_{t}$. For an indication of a shift in the process dispersion, a signal will be given if the value of the charting statistic $Z_{t}$ lies outside the interval [LCL, UCL] where LCL and UCL are the asymptotic (or steady-state) upper and lower control limits computed as:

$$
\begin{align*}
& \mathrm{LCL}=\mathrm{E}_{0}\left(\mathrm{SD}_{t}\right)-K \sqrt{\mathrm{~V}_{0}\left(\mathrm{SD}_{t}\right)} \times \sqrt{\frac{\lambda}{2-\lambda}}, \\
& \mathrm{UCL}=\mathrm{E}_{0}\left(\mathrm{SD}_{t}\right)+K \sqrt{\mathrm{~V}_{0}\left(\mathrm{SD}_{t}\right)} \times \sqrt{\frac{\lambda}{2-\lambda}}, \tag{4}
\end{align*}
$$

where $K>0$ is a coefficient to be fixed. When the process is in-control, the corresponding in-control mean $\mathrm{E}_{0}\left(\mathrm{SD}_{t}\right)$ and variance $\mathrm{V}_{0}\left(\mathrm{SD}_{t}\right)$ of $\mathrm{SD}_{t}$ are obtained by substituting $p=p_{0}$ in (1) and (2) respectively. Therefore, the control limits can be rewritten as:

$$
\begin{aligned}
& \mathrm{LCL}=n\left(2 p_{0}-1\right)-2 K \sqrt{\frac{\lambda n p_{0}\left(1-p_{0}\right)}{2-\lambda}}, \\
& \mathrm{UCL}=n\left(2 p_{0}-1\right)+2 K \sqrt{\frac{\lambda n p_{0}\left(1-p_{0}\right)}{2-\lambda}} .
\end{aligned}
$$

It should be clarified that the values of the quantiles $X_{p_{0} / 2}$ and $X_{1-p_{0} / 2}$ do not have any impact on the in-control design of the control chart. In particular, the determination of the control limits, and the pair $(\lambda, K)$ only depend on the sample size $n$ and the value of $p_{0}$ which is a value to be fixed by the practitioner (more details regarding the determination of this value are provided in the following Sections). Of course, we may argue the fact that the chart's operation during phase II requires the values of the quantiles to be known or at least estimated (during phase I), similarly to what happens with any parametric or nonparametric scheme. However, their values does not affect the chart's RL properties. Without loss of generality in the rest of this work, we assume that these quantiles are known.

### 3.2. RL properties

In order to obtain the RL properties of the proposed scheme, following the same design of a conventional EWMA chart (parametric or not), the "standard" method of Brook and Evans [22] will be used and its robustness will be investigated. In particular, it is assumed that the operation of the EWMA control chart can be well represented through a discrete-time Markov chain where the control limit interval [LCL, UCL] is divided into $2 m+1$ subintervals of width $2 \Delta$ where $\Delta=\frac{\text { UCL-LCL }}{4 m+2}$. Additionally, for each transient state $j=\{-m, \ldots, 0, \ldots m\}$, the corresponding $j$-th midpoint is defined as $H_{j}=\frac{\mathrm{LCL}+\mathrm{UCL}}{2}+2 j \Delta$. Then, the transition probability matrix $\mathbf{P}$ for the two-sided

D-SN EWMA chart is computed as:

$$
\mathbf{P}=\left(\begin{array}{cc}
\mathbf{Q} & \mathbf{r} \\
\mathbf{0}^{\top} & 1
\end{array}\right)=\left(\begin{array}{cccccccc}
Q_{-m,-m} & \ldots & Q_{-m,-1} & Q_{-m, 0} & Q_{-m, 1} & \ldots & Q_{-m, m} & r_{-m} \\
\vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \\
Q_{-1,-m} & \ldots & Q_{-1,-1} & Q_{-1,0} & Q_{-1,1} & \ldots & Q_{-1, m} & r_{-1} \\
Q_{0,-m} & \ldots & Q_{0,-1} & Q_{0,0} & Q_{0,1} & \ldots & Q_{0, m} & r_{0} \\
Q_{1,-m} & \ldots & Q_{1,-1} & Q_{1,0} & Q_{1,1} & \ldots & Q_{1, m} & r_{1} \\
\vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \\
Q_{m,-m} & \ldots & Q_{m,-1} & Q_{m, 0} & Q_{m, 1} & \ldots & Q_{m, m} & r_{m} \\
0 & \ldots & 0 & 0 & 0 & \ldots & 0 & 1
\end{array}\right)
$$

where $\mathbf{Q}$ is the $(2 m+1,2 m+1)$ matrix of transient probabilities, $\mathbf{0}^{\boldsymbol{\top}}=(0,0, \ldots, 0)$ and $\mathbf{r}=\mathbf{1}-\mathbf{Q} 1$. Let $\mathbf{q}=\left(q_{-m}, \ldots, q_{0}, \ldots, q_{m}\right)^{\boldsymbol{\top}}$ be the $(2 m+1,1)$ vector of initial probabilities associated with the $2 m+1$ transient states. In particular, this vector contains the probabilities that the charting statistic $Z_{t}$ starts in a given state. Therefore, we use $\mathbf{q}=(0, \ldots, 1, \ldots, 0)^{\top}$ where the value 1 at the $m$-th entry, corresponds to $Z_{0}=\mathrm{E}_{0}\left(\mathrm{SD}_{t}\right)$ stating that the process starts at state $m$. That is, the initial value for the EWMA statistic in (3) is the in-control mean of $\mathrm{SD}_{t}$ Finally, the transient probabilities, $Q_{j, k}$ are obtained as:

$$
\begin{align*}
Q_{j, k} & =\mathrm{P}\left(Z_{t} \text { is in state } k \mid Z_{t-1} \text { is in state } j\right) \\
& =\mathrm{P}\left(H_{k}-\Delta \leq Z_{t} \leq H_{k}+\Delta \mid Z_{t-1}=H_{j}\right) . \tag{5}
\end{align*}
$$

Using the definition of the charting statistic, $Z_{t}$, defined in (3), and substituting into (5), the transient probabilities, $Q_{j, k}$ are equal to:

$$
\begin{aligned}
Q_{j, k} & =\mathrm{P}\left(H_{k}-\Delta \leq \lambda \mathrm{SD}_{t}+(1-\lambda) Z_{t-1} \leq H_{k}+\Delta \mid Z_{t-1}=H_{j}\right) \\
& =\mathrm{P}\left(\frac{H_{k}-\Delta-(1-\lambda) H_{j}}{\lambda} \leq \mathrm{SD}_{t} \leq \frac{H_{k}+\Delta-(1-\lambda) H_{j}}{\lambda}\right) \\
& =F_{\operatorname{Bin}}\left(\left.\frac{\frac{H_{k}+\Delta-(1-\lambda) H_{j}}{\lambda}+n}{2} \right\rvert\, n, p\right)-F_{\operatorname{Bin}}\left(\left.\frac{\frac{H_{k}-\Delta-(1-\lambda) H_{j}}{\lambda}+n}{2} \right\rvert\, n, p\right),
\end{aligned}
$$

where $p \in\left\{p_{0}, p_{1}\right\}$. It is clear that when $p=p_{0}$ we are referring to the in-control ARL and when $p=p_{1}$ we are referring to the out-of-control one.

Finally, for a sufficient large number of subintervals $2 m+1$ the ARL and SDRL values can be accurately evaluated using the following classical formulas from the Markov chain theory (see, for instance [30,31])

$$
\begin{aligned}
\mathrm{ARL} & =\mathbf{q}^{\top}(\mathbf{I}-\mathbf{Q})^{-1} \mathbf{1} \\
\mathrm{SDRL} & =\sqrt{2 \mathbf{q}^{\top}(\mathbf{I}-\mathbf{Q})^{-2} \mathbf{Q} \mathbf{1}+\operatorname{ARL}(1-\mathrm{ARL})} .
\end{aligned}
$$

## 4. Numerical analysis

The investigation of the proposed chart's RL properties, will be examined under several symmetric and asymmetric distributions trying to cover a large variety of cases including heavily-tailed distributions. In particular, following the semi-parametric design presented by Castagliola et al. in [32], the robustness of the chart's RL properties will be tested under a benchmark of 18 Johnson's type distributions.

### 4.1. Johnson Distributions

Generally, the c.d.f. $F_{Z}(\ldots)$ of a Johnson's-type distribution with parameters $a, b>0$, $c$ and $d>0$ is defined as:

- bounded on $[c, c+d]$ (denoted as B in Table 1) with $F_{Z}(x)$ equal to:

$$
F_{Z}(x)=F_{\mathrm{N}}\left(a+b \ln \left(\frac{x-c}{c+d-x}\right)\right), x \in[c, c+d]
$$

- unbounded on $(-\infty, \infty)$ (denoted as U in Table 1) with $F_{Z}(x)$ equal to:

$$
F_{Z}(x)=F_{\mathrm{N}}\left(a+b \sinh ^{-1}\left(\frac{x-c}{d}\right)\right), x \in(-\infty, \infty)
$$

where $F_{\mathrm{N}}(\ldots)$ is the c.d.f. of the standard normal distribution.
In Table 1, 18 cases of the Johnson's family distributions are presented. Moreover, for each distribution, the corresponding values of the parameters $a, b, c, d$, have been selected in order to satisfy $\operatorname{med}(Z)=0$ (for the median) and $\sigma(Z)=1$ (for the standard-deviation). The cases $\# 1-\# 6$ approximately match some well known symmetric distributions. In particular, case $\# 1$ is close to the Uniform distribution, case $\# 2$ is close to the Triangular distribution while case $\# 3$ almost corresponds to the Standard Normal distribution. Additionally, cases $\# 4-\# 6$ are close to the Student $t$ distribution with 10,6 and 5 degrees of freedom, respectively. Finally, the remaining 12 cases, under different values for the skewness $\gamma_{3}>0$ and kurtosis $\gamma_{4}>0$ aim to cover a large variety of asymmetric and heavily-tailed distributions. For more details, a graphical representation of these distribution is provided page 116 in [32].

### 4.2. Effect of the number of subintervals

In this Section, we aim to investigate the effect of the number of subintervals in the RL properties of our proposed chart when the method of Brook and Evans [22] is being used. Generally, in cases where the statistic to be monitored is a continuous one (for instance, in parametric EWMA control charts based on the $\bar{X}$ statistic), for a relatively large number of subintervals (say $2 m+1 \approx 201$ ), the method of Brook and Evans [22] provides a reliable approximation of the chart's RL properties such

Table 1.: Benchmark of 18 Johnson's type distributions.

| case | $\gamma_{3}$ | $\gamma_{4}$ | type | $a$ | $b$ | $c$ | $d$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | 0 | -1.2 | B | 0 | 0.64646 | -1.81530 | 3.63060 |
| 2 | 0 | -0.6 | B | 0 | 1.39830 | -3.10970 | 6.21950 |
| 3 | 0 | 0 | U | 0 | 100 | 0 | 100 |
| 4 | 0 | 1 | U | 0 | 2.3212 | 0 | 2.10940 |
| 5 | 0 | 3 | U | 0 | 1.6104 | 0 | 1.31180 |
| 6 | 0 | 6 | U | 0 | 1.3493 | 0 | 1 |
| 7 | 2 | 4.3 | B | 1.7464 | 0.69076 | -0.48932 | 6.6213 |
| 8 | 2 | 6.1 | B | 3.3279 | 1.227 | -1.0016 | 16.088 |
| 9 | 2 | 7.9 | U | -4.85600 | 1.8044 | -1.41900 | 0.19332 |
| 10 | 2 | 10.8 | U | -1.0444 | 1.432 | -0.65538 | 0.82361 |
| 11 | 2 | 16.7 | U | -0.52977 | 1.2093 | -0.33154 | 0.73314 |
| 12 | 2 | 25.5 | U | -0.34371 | 1.0892 | -0.2023 | 0.63054 |
| 13 | 5 | 39.9 | B | 3.3715 | 0.74593 | -0.27094 | 25.150 |
| 14 | 5 | 52.6 | B | 5.2193 | 0.98134 | -0.47316 | 97.043 |
| 15 | 5 | 65.3 | U | -4.01870 | 1.0864 | -0.56652 | 0.02806 |
| 16 | 5 | 86 | U | -0.75701 | 0.98744 | -0.32033 | 0.37954 |
| 17 | 5 | 128.7 | U | -0.43187 | 0.90797 | -0.18538 | 0.37543 |
| 18 | 5 | 192.1 | U | -0.29868 | 0.85558 | -0.12122 | 0.34029 |

as the ARL or the SDRL. However, recent studies have shown that, computing the RL properties of a nonparametric EWMA chart via the "conventional" method of Brook and Evans [22] does not always guarantee an optimal design because the ARL and the SDRL values are strongly affected by the number of subintervals $2 m+1$. For instance, Wu et al. [23] investigated the design of a distribution-free EWMA chart based on a Sign-type statistic and proved that the number of subintervals $2 m+1$ significantly affects the ARL values. Additionally, Perdikis et al. [24] showed that in the design of an EWMA chart based on the Wilcoxon Signed Rank statistic, the ARL values are also affected by the number of subintervals. Based on our numerical analysis, the same behavior appears on the proposed scheme. More specifically, in Table 2(top), using the standard approach of Brook and Evans [22] the corresponding in-control ARL values are computed for different combinations of $n=\{12,20\}$ and $p_{0}=\{0.3,0.5,0.6,0.8\}$. The values of $\lambda=0.2$ and $K=2.85$ have been chosen only for illustration purposes. From Table 2 it can be clearly concluded that, regardless the value of $n$ or $p_{0}$, the $\mathrm{ARL}_{0}$ is affected by the number of subintervals instead of converging to the exact value of the ARL as the number of subintervals increases. As an example, if we take a closer look when $\left(n=12, p_{0}=0.3\right)$ the ARL ranges from 349.6 to 395.5 while the exact ARL, value approximated through a Monte Carlo simulation of $10^{5}$ iterations, is around 382 (see bottom row denoted "sim").

Additionally, in Table 3 (top), using the same values for the parameters ( $\lambda, K$ ), the out-of-control ARL values are presented for $\tau=1.1, p_{0}=0.5$ and $n=5$ under the Benchmark of 18 Johnson's type distributions illustrated in Table 1. Similarly, in Table 4 (top) the corresponding ARL values are presented for $\tau=0.9, p_{0}=0.5$ and $n=5$. Note that, $\tau=1.1$ corresponds to a small increase and $\tau=0.9$ corresponds to a small decrease in the variability. For each case, the corresponding out-of-control probabilities are computed as:

$$
\begin{equation*}
p_{1}=1-F_{Z}\left(X_{1-p_{0} / 2} \mid a, b, \tau c, \tau d\right)+F_{Z}\left(X_{p_{0} / 2} \mid a, b, \tau c, \tau d\right) \tag{6}
\end{equation*}
$$

From Tables 3 (top) and 4 (top) we may conclude that a very similar pattern also occurs for the out-of-control ARL values regardless the underlying distribution. As a result, using the standard method of Brook and Evans [22], practitioners are not
able to compute the exact in- and out-of-control ARL values of this chart and, as a consequence, they are not able to find a suitable pair of $(\lambda, K)$ to guarantee the chart's optimal performance.

## 5. The D-SN-C EWMA chart for dispersion (The "continuousified" approach)

From the results presented in section 3, we noticed that the ARL values obtained with the classical method of Brook and Evans [22] may not always lead to steady results regarding the design of an EWMA chart based on the $\mathrm{SD}_{t}$ statistic. The primary goal is to design an EWMA scheme for dispersion in which the ARL values will remain unaffected by the number of subintervals. Wu et al. [23] proposed the "continuousify" method, which suggests the transformation of any discrete charting statistic into a continuous one; the transformed statistic is a mixture of weighted Normal r.v. In particular, they showed that this transformation not only improves significantly the chart's RL properties but it also enables practitioners to optimize the chart's parameters in order to achieve in-control ARL value exactly equal to the desired one (say 370.4). Recently, many authors used this method for the design of several nonparametric EWMA control charts and they proved the superiority of the "continuousify" method (see [33],[34]). As a consequence, motivated by these results in the related literature, we will use this technique for the design of our proposed chart (to be denoted as the D-SN-C EWMA chart).
Let $X_{t}, t=1,2, \ldots$ be a sequence of i.i.d. discrete random variables, each of them defined on $\Psi=\left\{\psi_{1}, \psi_{2}, \ldots\right\}$ with corresponding p.m.f. function $f_{X}(\psi \mid \boldsymbol{\theta})$ where $\boldsymbol{\theta}$ denotes the vector of parameters. As stated in [23], $X$ can be transformed into a new continuous random variable (denoted as $X_{t}^{*}$ ), defined as a mixture of normally distributed random variables $Y_{t}^{*}$ where, for each $\psi_{t} \in \Psi, Y_{t}^{*} \sim N\left(\psi_{t}, h\right)$. Then, the corresponding p.m.f. $f_{X^{*}}(x \mid \boldsymbol{\theta})$ and c.d.f. $F_{X^{*}}(x \mid \boldsymbol{\theta})$ of $X_{t}^{*}$ will be computed as:

$$
\begin{aligned}
& f_{X^{*}}(x \mid \boldsymbol{\theta})=\sum_{\psi \in \Psi} f_{X}(\psi \mid \boldsymbol{\theta}) f_{\mathrm{N}}(x \mid \psi, h), \\
& F_{X^{*}}(x \mid \boldsymbol{\theta})=\sum_{\psi \in \Psi} f_{X}(\psi \mid \boldsymbol{\theta}) F_{\mathrm{N}}(x \mid \psi, h),
\end{aligned}
$$

where $f_{\mathrm{N}}(x \mid \psi, h)$ and $F_{\mathrm{N}}(x \mid \psi, h)$ are the p.d.f. and c.d.f. of the $\operatorname{Normal}(\psi, h)$ distribution, respectively, where $h>0$ is the "continuousified" parameter and it is a value to be fixed. For more details regarding the definition or similar applications of the "continuousify"method the reader is refereed to [33],[34]. For our proposed "continuousified" two-sided Sign EWMA chart for dispersion instead of using $\mathrm{SD}_{t}$, a new continuous statistic will be used, denoted as $\mathrm{SD}_{t}^{*}$. Since the domain in which $\mathrm{SD}_{t}$ is
defined is $\Psi=\{-n,-n+2, \ldots, n-2, n\}$, the statistic $\mathrm{SD}_{t}$ will be transformed into:

$$
\mathrm{SD}_{t}^{*}= \begin{cases}\mathrm{SD}_{t,-n}^{*} \sim \mathrm{~N}(-n, h), & \text { if } \mathrm{SD}_{t}=-n \\ \mathrm{SD}_{t,-n+2}^{*} \sim \mathrm{~N}(-n+2, h), & \text { if } \mathrm{SD}_{t}=-n+2 \\ \vdots & \vdots \\ \mathrm{SD}_{t, 0}^{*} \sim \mathrm{~N}(0, h), & \text { if } \mathrm{SD}_{t}=0 \\ \vdots & \vdots \\ \mathrm{SD}_{t, n-2}^{*} \sim \mathrm{~N}(n-2, h), & \text { if } \mathrm{SD}_{t}=n-2 \\ \mathrm{SD}_{t, n}^{*} \sim \mathrm{~N}(n, h), & \text { if } \mathrm{SD}_{t}=n\end{cases}
$$

Additionally, the c.d.f. $F_{\mathrm{SD}_{t}^{*}}(s \mid n, p)$ of $\mathrm{SD}_{t}^{*}$ will be defined for $s \in \mathbb{R}$ and will be equal to

$$
\begin{equation*}
F_{\mathrm{SD}_{t}^{*}}(s \mid n, p)=\sum_{\psi \in \Psi} f_{\operatorname{Bin}}\left(\left.\frac{\psi+n}{2} \right\rvert\, n, p\right) F_{\mathrm{N}}(s \mid \psi, h) . \tag{7}
\end{equation*}
$$

Finally, as for the computation of the mean and variance of $\mathrm{SD}_{t}^{*}$, following the definitions of the mean and variance of a continuous random variable, it can be easily proven that (see, Appendix):

$$
\begin{align*}
\mathrm{E}\left(\mathrm{SD}_{t}^{*}\right) & =\mathrm{E}\left(\mathrm{SD}_{t}\right),  \tag{8}\\
\mathrm{V}\left(\mathrm{SD}_{t}^{*}\right) & =\mathrm{V}\left(\mathrm{SD}_{t}\right)+h^{2} \tag{9}
\end{align*}
$$

Regarding the charting statistic of the proposed two-sided D-SN-C EWMA chart, it will be simply defined as:

$$
\begin{equation*}
Z_{t}^{*}=\lambda \mathrm{SD}_{t}^{*}+(1-\lambda) Z_{t-1}^{*}, Z_{0}^{*}=\mathrm{E}_{0}\left(\mathrm{SD}_{t}^{*}\right) \tag{10}
\end{equation*}
$$

Lastly, in the expressions presented in (4), if we substitute the mean and variance by the equations (8) and (9), the new control limits LCL and UCL, denoted as LCL* and UCL* respectively, of our proposed scheme will be:

$$
\begin{align*}
& \mathrm{LCL}^{*}=n\left(2 p_{0}-1\right)-K \sqrt{\frac{\lambda\left(4 n p_{0}\left(1-p_{0}\right)+h^{2}\right)}{2-\lambda}},  \tag{11}\\
& \mathrm{UCL}^{*}=n\left(2 p_{0}-1\right)+K \sqrt{\frac{\lambda\left(4 n p_{0}\left(1-p_{0}\right)+h^{2}\right)}{2-\lambda}} . \tag{12}
\end{align*}
$$

In order to verify the efficiency of the proposed chart in terms of its stability for the computation of the ARL values, in Tables 2 and 3 (bottom), besides the ARL values already obtained by the classical method of Brook and Evans [22], the corresponding ARL values obtained via the "continuousify" method are presented. For the in-control case (Table 2), we may conclude that, regardless the values of $n$ and $p_{0}$, the use of the continuous transformation in the discrete statistic to be monitored, provides a great improvement. More specifically, for every combination of ( $n, p_{0}$ ), the corresponding ARL values become stable really quickly even for small values of $2 m+1 \approx 51$. Similarly with the in-control cases, from Tables 3 and 4, it can be concluded that the advantages
of the "continuousify" method are also present in the out-of-control cases. In particular, for all the 18 distributions, the ARL values without the "continuousify" method are not stable and depend on the number of subintervals. On the other hand, by using the continuous transformation the ARL values become stable and seem to be unaffected by the number of subintervals. Regarding the value of the "continuousify" parameter $h$, as it has already been shown in [23] and [24], as soon as this parameter is not too small or not too large (say $h \approx 0.2$ ) the results are not seriously affected. In Table 5, for different combinations of the sample size, $n \in\{7,13,18,22\}$, and a pre-specified probability, $p_{0} \in\{0.4,0.5,0.6,0.7,0.8\}$, the corresponding in-control ARL values of the D-SN-C EWMA chart are presented for $h \in\{0.1,0.15, \ldots, 0.3\}$. Based on the results from Table 5 it is clear that $h$ does not significantly affect the results as only some minor differences exist in the first decimal place for small values of $2 m+1$. As a result, setting a value of $h=0.2$ is suggested. It should be noted that from Tables 3 and 4 we may see that the ARL values obtained with the "continuousify" method are a bit larger than those obtained by simulation. This is logical as the control limits obtained with the "continuousify" method are a bit larger than those obtained without the "continuousify" method due to the extra term $h$. This is the price to pay in order to obtain reliable ARL values.

## 6. Optimization of the D-SN-C EWMA chart

In this section we aim to investigate how the value of $p_{0}$ (i.e. the value that needs to be fixed during the design phase of the chart) affects the chart's out-of-control performance. In particular, we will investigate the impact of varying values of $p_{0}$ (instead of being set to $p_{0}=0.5$ ) under different shift magnitudes and underlying distributions. In Table 6 the chart's out-of-control performance is presented for $p_{0} \in\{0.1,0.5,0,7\}$ for the distributions listed in Table 1. For illustration purposes the values of the design parameters are randomly selected and equal to ( $\lambda=0.2, K=2.75, n=10, h=0.2$ ). From the results presented in Table 6 it is clear that the initial value of $p_{0}$ significantly affects the chart's out-of-control performance. For instance, when $\tau=0.25$, for every case, the minimum $\mathrm{ARL}_{1}$ is reached when $p_{0}=0.7$. On the other hand, when $\tau=2$, the minimum $\mathrm{ARL}_{1}$ is reached when $p_{0}=0.1$. As a consequence, different initial values for $p_{0}$ lead to different results. It is clear that, depending on the shift magnitude to be detected, the initial value of $p_{0}$ affects the chart's out-of-control performance.

Ideally, when a priori information for the sample's underlying distribution is known, practitioners are able to optimize the vector ( $\lambda, K, p_{0}$ ) for a given shift magnitude $\tau$. Nevertheless, this is a strict assumption and it is rarely hold in practice. Moreover, let us keep in mind that the primary motivation of using a nonparametric control chart is the fact that any knowledge of the sample's distribution is not needed. Consequently, in order to provide a practical implementation and general guidelines to practitioners regarding the "optimal" value of $p_{0}$ an extensive numerical analysis will be performed for different distributions. In particular, the out-of-control performance of the proposed chart will be examined under the benchmark of the 18 Johnson's type distributions listed in Table 1, for different sample sizes and shifts in the process variability. As already stated, we want to investigate, for a variety of distributions, the impact of $p_{0}$ to the chart's optimal out-of-control performance. All the computations regarding the in-control and the out-of-control performance of the chart as well as the determination of the charts' design parameters were made
via the Markov chain method of Brook and Evans [22], in combination with the "continusify" method of Wu et al. [23] as presented in section 5. The knowledge of the underlying distribution for the out-of-control case is needed only for computing the probability $p_{1}$ (see equation (6)) which is associated with the shift magnitude $\tau$. The motivation for this analysis is to examine, for different type of distributions (symmetric/asymmetric), how the optimal value of $p_{0}$ varies and to provide guidelines to practitioners about how to select the value of this parameter. This is something that has not been investigated so far in the literature. All the computations have been performed in $R$ [37], on a computer with an $\operatorname{Intel}(\mathrm{R})$ Core(TM) i7-7500U CPU. No additional packages have been used except those in the base R edition. The source code is available to the reader upon request. Finally, regarding the optimization procedure, for each distribution, the following steps based on a simple but efficient grid search method have been followed.

- Step 1: First we have to define the domain of where the design parameters $p_{0}$ and $\lambda$ will be defined during the searching algorithm. In general, for EWMA schemes, large (small) values of $\lambda$ are preferable for detecting large (small) shifts in the process variability. So it is logical to define $\lambda \in\{0.05,0.1, \ldots, 0.95\}$. As for the candidate values of $p_{0}$ of course we may argue with the fact that $p_{0}$ could take any value in the interval $(0,1)$. However, without loss of generality, it can be simplified by letting $p_{0}$ take only a discrete set of values; say $p_{0} \in\{0.05,0.15, \ldots, 0.95\}$. This discretisation (which can be regarded as a 'grid search') is justified by the fact that, in practice, only easy-to-manage values of $p_{0}$ are meant to be used (for instance, $p_{0}=0.5$ in the original definition of the sign statistic, as already remarked).
- Step 2: For each combination of $p_{0}$ and $\lambda$, we have to properly define the value of $K$ in order to satisfy a desired in-control ARL equal to $\mathrm{ARL}_{0}=370.4$ . In particular, for every combination of $p_{0} \in\{0.05,0.15, \ldots, 0.95\}$ and $\lambda \in$ $\{0.05,0.1, \ldots, 0.95\}$, using the "continusify" method of Wu et al. [23] as presented in section 5 we compute the corresponding value for $K$ under the condition that $\mathrm{ARL}_{0}=370.4$ by setting the number of sub-intervals to be equal to $2 m+1=151$. Note that, the number $2 m+1=151$ has been chosen in order to not be too large but large enough to guarantee the stability of the results. Of course, practitioners can also set any value for $2 m+1>151$.
- Step 3: Lastly, we should find the optimal values of $p_{0}, \lambda, K$, which minimise the out-of-control ARL for a given shift magnitude. In particular, for each shift $\tau \in\{0.25,0.5,0.75,0.95,1.25,1.5,1.75,1.95,2\}$, among all the combinations of $\left(p_{0}, \lambda, K\right)$ computed in Step 2, the optimal vector of $\left(p_{0}^{*}, \lambda^{*}, K^{*}\right)$ is chosen which gives the smallest out-of-control ARL at a specific shift $\tau$.

In Tables 7 and 8 the optimal combinations of $\left(\lambda^{*}, K^{*}\right)$ (first line of each block) are presented, along with the corresponding out-of-control ARL values (second line) and the corresponding pairs of $\left(p_{0}^{*}, p_{1}\right)$ (third line) for $n=10$ (Table 7) and $n=20$ (Table 8). It should be clarified that $p_{0}^{*}$ defines the suggested quantiles for the test for dispersion (i.e., the test statistic $\mathrm{SD}_{t}$ ) for a specific value of $\tau$. Also, it is related to the in-control case (i.e. when $p=p_{0}^{*}$ we are referring to an in-control process while when, $p \neq p_{0}^{*}$ the process is out-of-control). Our conclusions are the following:

- For large decreases in the process variability (e.g., $\tau=0.25$ ), it can be seen that, for $p_{0}^{*}>0.6$, the corresponding out-of-control ARL values are $\mathrm{ARL}_{1} \approx 1$. On the other hand, for large increases $(\tau=2)$, small values for $p_{0}^{*}$ are preferable. For
instance, from Table 7 it can be seen that, when $\tau=0.25$, the optimal value of $p_{0}$ is $p_{0}^{*} \geq 0.7$. On the other hand, $p_{0}^{*}=0.1$ for large increases (i.e. $\tau=2$ ).
- For moderate decreases in the variability (such as $\tau=0.5$ or 0.75 ), from Table 7 we may see that $p_{0}^{*}$ takes values between 0.3 and 0.6 . On the other hand, for moderate increases in the variability ( $\tau=1.5$ or 1.75 ), the optimal value of $p_{0}$ is $p_{0}^{*} \leq 0.2$ for all the cases.
- Finally, for small decreases (such as $\tau=0.95$ ) or increases $(\tau=1.25)$ the optimal value of $p_{0}$ ranges from 0.05 to 0.25 .
- Similarly, from Table 8 we may see that all the above statements are also valid for $n=20$.
From the results presented above, it can be concluded that as the value of $\tau$ increases then the optimal value for $p_{0}$ decreases. As a general guideline to practitioners, we advise to use $p_{0} \approx 0.2$ for a monitoring scheme that aims at the quick detection of small increases/decreases. For moderate shifts, we suggest $p_{0} \approx 0.6$. Finally, setting $p_{0} \approx 0.1$ and $p_{0} \approx 0.7$ can be considered as a reasonable choice for detecting large decreases and increases respectively in the process variability.


### 6.1. Performance comparisons

In Table 9 the out-of-control performance of the D-SN-C EWMA chart is compared with three parametric Shewhart-type control charts for monitoring the process variability for $n \in\{5,20,30\}$ under the normal distribution. In particular, the D-SN-C EWMA chart is compared with the modified $R$ and $S$ charts proposed by Zhang in [36] and an enhanced $R$ chart proposed by Khoo and Lim in [35]. For each case, the proposed chart is optimized as explained in Section 6 assuming a normal distribution. It can be clearly seen that, regardless the sample size or the shift magnitude $\tau$, the D-SN-C EWMA chart has the best performance among its competitors. It should be noted that, for small to moderate decreases $(0.5<\tau<0.9)$ or increases ( $1.1<\tau<1.5$ ), the proposed chart's corresponding ARL $_{1}$ values, are significantly smaller, compared with its parametric counterparts. For instance, for $n=20$, and $\tau=0.9$ the ARL ${ }_{1}$ values for the Zhang's $R$ and $S$ charts and Khoo and Lim's $R$ chart are $188.04,174.67$ and 232.12 , respectively, while for the proposed chart it is $\mathrm{ARL}_{1}=26.21$. Similarly, when $\tau=1.1$ the ARL $_{1}$ values for the Zhang's $R$ and $S$ chart and Khoo and Lim's R chart are 127.59, 78.82 and 139.9, respectively, while for the proposed chart it is $\mathrm{ARL}_{1}=24.47$. As a result, the D-SN-C EWMA chart, can be considered as an efficient choice for monitoring small shifts in the process variance.

Additonally, we compared the performance of the proposed chart with the nonparametric Shewhart-type chart based on the interquantile sign statistic (to be denoted as Shewhart S-SD chart) as introduced by Pawar at al. in [29], under different cases of the Johnson-type distributions introduced above. For both schemes (Shewhart and EWMA), for a given member from the family of Johnson's distributions, we optimised each chart in terms of the value $p_{0}$ and computed the quantity

$$
\begin{equation*}
\frac{\mathrm{ARL}_{1}^{\mathrm{EWMA}}-\mathrm{ARL}_{1}^{\mathrm{Sh}}}{\mathrm{ARL}_{1}^{\mathrm{Sh}}} \times 100 \% \tag{13}
\end{equation*}
$$

where $\mathrm{ARL}_{1}^{\mathrm{Sh}}$ (resp. $\mathrm{ARL}_{1}^{\mathrm{EWMA}}$ ) is the out-of-control performance, in terms of $A R L$, of the Shewhart S-SD (resp. D-SN-C EWMA) chart, at a given shift in process
variability. These differences are presented in Table 10 for $n=20$. From the results in Table 10 we deduce that the proposed EWMA chart outperforms the Shewhart S-SD chart, regardless the sample size, the shift magnitude or the underlying distribution.. Practically speaking, for large increases $(\tau>2)$ or decreases $(\tau \rightarrow 0)$ in the process variability, these two schemes have similar performance but for small shifts the D-SN-C chart is clearly superior.

Furthermore, except for comparisons with the Shewhart chart of Pawar et al. in [29], we provide next, comparisons with another competitive nonparametric EWMA chart for monitoring the process variability, Specifically, we compare the proposed EWMA chart with the EWMA chart of Yang and Arnold in [17], which is based on the arcsin transformation. We will refer to this chart as the AC-EWMA chart. The out-of-control performance of the AC-EWMA chart is derived by using the same setup as the authors did in [17] (see, Table 9 in [17], page, 2758) assuming Standard Normal and Double Exponential distributions. For the design parameters of the proposed D-SN-C EWMA chart, we set $\lambda=0.2, K=2.855$ and $p_{0}=0.2$. We have to note that the choice of $p_{0}=0.2$ is based on the results presented in Section 6. In particular, we showed that, for a symmetric underlying distribution, setting $p_{0} \approx 0.2$ significantly improves the ability of the chart to detect small to moderate shifts in the process dispersion. From Table 11, we may see that the proposed chart has better performance regardless the shift magnitude and, therefore, it should be considered as an effective scheme to detect shifts in the process variability.

## 7. An illustrative example

In this section, an example with two different scenarios is presented, in order to show a practical Phase II implementation of the operation of the proposed D-SN-C EWMA chart. The datasets for each scenario, which have been originally introduced in [38], are presented in Table A1 and plotted in Figures 2 and 3, respectively. Both datasets consists of 30 subgroups of size $n=5$ where the first 20 subgroups are the same for both scenarios and are randomly generated from the $\mathrm{N}(20,0.1)$ distribution. Moreover, the last 10 subgroups in Figure 2 are generated from the $\mathrm{N}(20,0.2)$ distribution while the last 10 subgroups in Figure 3 are generated from the N $(20,0.05)$ distribution.

Let us consider a realistic situation, from the point of view of a practitioner, in which we do not have any a priori information regarding the underlying distribution nor the in-control values of the mean and variance for both cases. We only have at our disposal a reference in-control sample of size $n=30$ and we are interested in monitoring increases (first scenario) and decreases (second scenario) in the process variability. Before we proceed to the phase II implementation of the control chart our primary goal is to:

- determine the value of $p_{0}$ as well as the value of the pair $(\lambda, K)$
- estimate the quantiles $X_{p_{0} / 2}$ and $X_{1-p_{0} / 2}$.

From the histogram presented in Figure 1 we may see that the in-control reference sample is bell-shaped. Additionally, from the numerical analysis presented in Section 6 , we conclude that, for symmetric distributions (or equivalently for cases with light
asymmetry), setting $p_{0} \approx 0.05$ and $\lambda \in[0.2,0.5]$ can be considered as a reasonable choice for detecting moderate increases in the process variability. Similarly for monitoring a moderate decrease in the process variability setting $p_{0} \approx 0.45$ and $\lambda \approx 0.2$ can be considered as a reasonable choice. As a consequence, for the current scenarios, the vector of parameters $\left(p_{0}^{*}, \lambda^{*}, K^{*}\right)$ for detecting an increase in the process dispersion is chosen to be ( $p_{0}^{*}=0.05, \lambda^{*}=0.25, K^{*}=3.424$ ) with the corresponding control limits LCL* $=-5.789$, UCL* $=-3.212$ computed using (11) and (12) presented in Section 5 where the value of the "continuousify" parameter is set to $h=0.2$. Similarly, for detecting a decrease in the process dispersion we choose the vector ( $p_{0}^{*}=0.5, \lambda^{*}=0.25, K^{*}=2.823$ ) and the control limits are equal to $\mathrm{LCL}^{*}=-2.395, \mathrm{UCL}^{*}=2.395$.

Regarding the determination of the quantiles of interest for each scenario the simplest way is to estimate them from the reference sample through the inverse of its empirical distribution. In particular, for $p_{0}=0.5$ the estimates of the $X_{p_{0} / 2}$ and $X_{1-p_{0} / 2}$ are equal to $\hat{X}_{0.25}=19.96594$ (the theoretical values assuming normality is 19.8651) and $\hat{X}_{0.75}=20.0928$ (the theoretical value assuming normality is 20.1349). Similarly, for $p_{0}=0.05$ the estimates of the $X_{p_{0} / 2}$ and $X_{1-p_{0} / 2}$ are equal to $\hat{X}_{0.025}=19.8436$ and $\hat{X}_{0.975}=20.2296$. (the theoretical values assuming normality are 19.60801 and 20.39199).

Finally, the corresponding values of $\mathrm{SD}_{t}, \mathrm{SD}_{t}^{*}$ and $Z_{t}^{*}$ are presented in Table 12. From Figure 4, it can be seen that the proposed chart can efficiently detect the increase in the process variability at the 25th sampling point. Similarly, for the second scenario, which corresponds to a decrease in the process variability (Figure 5), we may see that the D-SN-C EWMA chart also detects this shift at the 25th sampling point.


Figure 1.: Histogram of the reference sample

## 8. Conclusions

In this paper, we introduced a nonparamteric EWMA control chart based on a general extension of the Sign statistic, called as the D-SN-C EWMA chart, for monitoring shifts in the process variability. For the computation of the chart's RL properties, the "continuousify" method of Wu et al. [23] has been used, ensuring that the ARL values can be accurately and effectively calculated. Additionally, the


Figure 2.: Dataset for the first example


Figure 3.: Dataset for the second example
chart's out-of-control performance has been examined under a benchmark of 18 Johnson's type distributions covering a wide range of symmetric and asymmetric distributions. Based on our results, when the value of the in-control parameter $p_{0}$ is optimized (instead of being pre-defined), the chart's out-of-control performance is significantly improved; more precisely, values of $p_{0} \approx 0.2$ are found to be preferable for small decreases ( $\tau \approx 0.95$ ) or increases ( $\tau \approx 1.25$ ). Additionally, for large decreases ( $\tau \approx 0.25$ ) or increases ( $\tau \approx 2$ ) in the process variability, large ( $p_{0} \approx 0.7$ ) or small values ( $p_{0} \approx 0.05$ ) of $p_{0}$ are respectively the optimal ones. As a consequence, the proposed chart can be considered as a reliable technique which provides to the practitioners robust information regarding its in- and out-of-control RL properties.

The current work can be extended in several directions. In particular, the "continuousify" method could be applied in EWMA schemes where other nonparametric statistics are considered such as the Mann-Whitney, or the Ansari-Bradley statistics. Additionally, it would also be interesting to examine the performance of the proposed EWMA chart based on the general Sign statistic under the presence of ties in the pop-


Figure 4.: The D-SN-C EWMA chart for the Phase II data presented in Figure 2


Figure 5.: The D-SN-C EWMA chart for the Phase II data presented in Figure 3
ulation. Finally, the method of Wu et al. [23] could be extended in distribution-free EWMA charts designed for monitoring bivariate processes.

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## Appendix

Let $\mathrm{E}_{N}(X)=\mu$ and $\mathrm{V}_{N}(X)=h^{2}$ denote the mean and variance of a random variable, X , from a Normal distribution. Then the mean of $\mathrm{SD}_{t}^{*}$, is computed as:

$$
\begin{aligned}
\mathrm{E}\left(\mathrm{SD}_{t}^{*}\right) & =\int_{-\infty}^{\infty} s \times f_{\mathrm{SD}_{t}^{*}}\left(s \mid n, p_{1}\right) d s \\
& =\int_{-\infty}^{\infty} s \times \sum_{\psi \in \Psi} f_{\operatorname{Bin}}\left(\left.\frac{\psi+n}{2} \right\rvert\, n, p_{1}\right) \times f_{\mathrm{N}}(s \mid \psi, h) d s \\
& =\sum_{\psi \in \Psi}\left[f_{\operatorname{Bin}}\left(\left.\frac{\psi+n}{2} \right\rvert\, n, p_{1}\right) \times \int_{-\infty}^{\infty} s \times f_{\mathrm{N}}(s \mid \psi, h) d s\right] \\
& =\sum_{\psi \in \Psi}\left[f_{\operatorname{Bin}}\left(\left.\frac{\psi+n}{2} \right\rvert\, n, p_{1}\right) \times \mathrm{E}_{N}(s)\right] \\
& =\sum_{\psi \in \Psi}\left[f_{\operatorname{Bin}}\left(\left.\frac{\psi+n}{2} \right\rvert\, n, p_{1}\right) \times \psi\right] \\
& =\mathrm{E}\left(\mathrm{SD}_{t}\right)
\end{aligned}
$$

Similarly, using the fact that $\mathrm{E}\left(\mathrm{SD}_{t}^{*}\right)=\mathrm{E}\left(\mathrm{SD}_{t}\right)$ the variance of $\mathrm{SD}_{t}^{*}$ is computed as:

$$
\begin{aligned}
\mathrm{V}\left(\mathrm{SD}_{t}^{*}\right) & =\mathrm{E}\left(\mathrm{SD}_{t}^{*}\right)^{2}-\left(\mathrm{E}\left(\mathrm{SD}_{t}^{*}\right)\right)^{2} \\
& =\int_{-\infty}^{\infty} s^{2} \times f_{\mathrm{SD}_{t}^{*}}\left(s \mid n, p_{1}\right) d s-\left(\mathrm{E}\left(\mathrm{SD}_{t}^{*}\right)\right)^{2} \\
& =\int_{-\infty}^{\infty} s^{2} \times \sum_{\psi \in \Psi}\left[f_{\mathrm{SD}}\left(\left.\frac{\psi+n}{2} \right\rvert\, n, p_{1}\right) \times f_{\mathrm{N}}(s \mid \psi, h)\right] d s-\left(\mathrm{E}\left(\mathrm{SD}_{t}\right)\right)^{2} \\
& =\sum_{\psi \in \Psi}\left[f_{\operatorname{Bin}}\left(\left.\frac{\psi+n}{2} \right\rvert\, n, p_{1}\right) \times \int_{-\infty}^{\infty} s^{2} \times f_{\mathrm{N}}(s \mid \psi, h) d s\right]-\left(\mathrm{E}\left(\mathrm{SD}_{t}\right)\right)^{2} \\
& =\sum_{\psi \in \Psi}\left[f_{\operatorname{Bin}}\left(\left.\frac{\psi+n}{2} \right\rvert\, n, p_{1}\right) \times \mathrm{E}_{N}\left(s^{2}\right)\right]-\left(\mathrm{E}\left(\mathrm{SD}_{t}\right)\right)^{2} \\
& =\sum_{\psi \in \Psi}\left[f_{\operatorname{Bin}}\left(\left.\frac{\psi+n}{2} \right\rvert\, n, p_{1}\right) \times\left(\mathrm{V}_{N}(s)+\left(\mathrm{E}_{N}(s)\right)^{2}\right)\right]-\left(\mathrm{E}\left(\mathrm{SD}_{t}\right)\right)^{2} \\
= & \sum_{\psi \in \Psi}\left[f_{\operatorname{Bin}}\left(\left.\frac{\psi+n}{2} \right\rvert\, n, p_{1}\right) \times\left(h^{2}+\psi^{2}\right)\right]-\left(\mathrm{E}\left(\mathrm{SD}_{t}\right)\right)^{2} \\
= & h^{2} \times \sum_{\psi \in \Psi} f_{\operatorname{Bin}}\left(\left.\frac{\psi+n}{2} \right\rvert\, n, p_{1}\right)+\sum_{\psi \in \Psi} \psi^{2} \times f_{\operatorname{Bin}}\left(\left.\frac{\psi+n}{2} \right\rvert\, n, p_{1}\right)-\left(\mathrm{E}\left(\mathrm{SD}_{t}\right)\right)^{2} \\
= & h^{2}+\mathrm{E}\left(\mathrm{SD}_{t}\right)^{2}-\left(\mathrm{E}\left(\mathrm{SD}_{t}\right)\right)^{2} \\
= & h^{2}+\mathrm{V}\left(\mathrm{SD}_{t}\right) .
\end{aligned}
$$

Table A1.: Phase II samples of $t=1,2, \ldots 20$ subgroups of size $n=5$

| Subgroup |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| First 20 subgroups for both examples |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| $X_{t, j}$ | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 | 15 | 16 | 17 | 18 | 19 | 20 |
| 1 | 20.083 | 20.028 | 19.950 | 19.889 | 19.941 | 20.020 | 20.101 | 20.022 | 20.049 | 20.169 | 20.099 | 19.978 | 20.135 | 19.878 | 20.130 | 20.010 | 20.086 | 19.888 | 20.000 | 19.885 |
| 2 | 20.115 | 20.129 | 19.900 | 20.043 | 19.996 | 20.072 | 20.109 | 20.009 | 20.013 | 19.808 | 19.923 | 20.052 | 20.011 | 19.917 | 20.120 | 20.096 | 20.124 | 19.931 | 19.974 | 20.107 |
| 3 | 19.990 | 19.954 | 19.940 | 20.003 | 20.009 | 20.182 | 19.846 | 20.018 | 20.110 | 20.110 | 20.045 | 20.038 | 19.911 | 19.925 | 20.124 | 19.906 | 20.140 | 19.903 | 20.078 | 20.004 |
| 4 | 20.022 | 20.080 | 20.133 | 19.800 | 19.853 | 20.132 | 20.198 | 20.047 | 19.893 | 20.029 | 19.985 | 20.097 | 19.913 | 19.988 | 19.801 | 20.108 | 20.057 | 20.003 | 20.135 | 20.067 |
| 5 | 19.995 | 20.049 | 19.976 | 20.113 | 19.906 | 20.099 | 19.905 | 19.962 | 19.857 | 19.913 | 19.852 | 20.031 | 19.781 | 20.058 | 19.962 | 19.891 | 20.111 | 19.878 | 19.885 | 20.197 |
| Last 10 subgroups for example 1 (Figure 2) |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| $X_{t, j}$ | 21 | 22 | 23 | 24 | 25 | 26 | 27 | 28 | 29 | 30 |  |  |  |  |  |  |  |  |  |  |
| 1 | 19.843 | 20.038 | 20.077 | 20.031 | 19.650 | 20.265 | 20.028 | 20.162 | 20.000 | 20.544 |  |  |  |  |  |  |  |  |  |  |
| 2 | 20.142 | 19.709 | 20.046 | 20.190 | 19.396 | 20.085 | 20.139 | 19.949 | 20.093 | 19.865 |  |  |  |  |  |  |  |  |  |  |
| 3 | 19.757 | 19.872 | 20.154 | 19.903 | 19.969 | 20.201 | 19.824 | 19.859 | 19.901 | 19.857 |  |  |  |  |  |  |  |  |  |  |
| 4 | 20.184 | 20.016 | 20.083 | 19.669 | 19.955 | 20.238 | 19.779 | 20.395 | 19.836 | 20.262 |  |  |  |  |  |  |  |  |  |  |
| 5 | 20.178 | 20.205 | 20.248 | 20.049 | 20.102 | 20.048 | 19.824 | 19.615 | 19.918 | 19.838 |  |  |  |  |  |  |  |  |  |  |
| Last 10 subgroups for example 2 (Figure 3) |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| $X_{t, j}$ | 21 | 22 | 23 | 24 | 25 | 26 | 27 | 28 | 29 | 30 |  |  |  |  |  |  |  |  |  |  |
| 1 | 20.044 | 20.044 | 20.097 | 20.049 | 20.018 | 19.994 | 19.957 | 20.044 | 20.047 | 19.942 |  |  |  |  |  |  |  |  |  |  |
| 2 | 20.046 | 20.037 | 19.859 | 20.001 | 20.003 | 20.038 | 20.009 | 19.969 | 20.051 | 19.975 |  |  |  |  |  |  |  |  |  |  |
| 3 | 20.058 | 19.966 | 19.983 | 20.085 | 20.076 | 20.001 | 20.018 | 20.009 | 19.931 | 20.041 |  |  |  |  |  |  |  |  |  |  |
| 4 | 20.104 | 20.046 | 19.944 | 19.986 | 20.087 | 20.016 | 20.071 | 20.090 | 19.974 | 20.008 |  |  |  |  |  |  |  |  |  |  |
| 5 | 19.969 | 19.998 | 19.979 | 20.018 | 20.070 | 19.996 | 19.939 | 20.055 | 20.015 | 19.973 |  |  |  |  |  |  |  |  |  |  |

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Table 2.: In-control values of ARL for the D-SN EWMA and D-SN-C EWMA charts when $\lambda=0.2, K=2.85$ and $h=0.2$ under different combinations of $\left(n, p_{0}\right)$.

|  | ( $n=12, p_{0}=0.3$ ) |  | ( $n=12, p_{0}=0.5$ ) |  | ( $\left.n=12, p_{0}=0.9\right)$ |  | ( $\left.n=12, p_{0}=0.8\right)$ |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $2 m+1$ | D-SN EWMA | D-SN-C EWMA | D-SN EWMA | D-SN-C EWMA | D-SN EWMA | D-SN-C EWMA | D-SN EWMA | D-SN-C EWMA |
| 51 | 364.3 | 379.6 | 418.1 | 382.6 | 371.9 | 380.3 | 386.6 | 363.7 |
| 61 | 349.6 | 380.6 | 372.9 | 382.6 | 361.8 | 381.4 | 378.2 | 364.3 |
| 71 | 394.1 | 381.1 | 382.9 | 383.1 | 380.6 | 381.9 | 368.0 | 364.7 |
| 81 | 381.3 | 381.4 | 399.6 | 383.4 | 389.2 | 382.2 | 366.7 | 364.9 |
| 91 | 385.5 | 381.6 | 397.7 | 383.6 | 399.1 | 382.5 | 371.0 | 365.1 |
| 101 | 386.0 | 381.7 | 386.6 | 383.8 | 385.6 | 382.6 | 371.1 | 365.3 |
| 111 | 385.7 | 381.8 | 389.5 | 383.9 | 380.1 | 382.7 | 365.7 | 365.3 |
| 121 | 382.3 | 381.9 | 388.3 | 384.0 | 371.8 | 382.8 | 368.8 | 365.4 |
| 131 | 378.1 | 381.9 | 391.8 | 384.1 | 388.1 | 382.9 | 365.1 | 365.5 |
| 141 | 386.0 | 382.0 | 372.5 | 384.1 | 391.8 | 382.9 | 358.9 | 365.5 |
| 151 | 382.9 | 382.0 | 375.5 | 384.2 | 381.2 | 383.0 | 366.8 | 365.6 |
| 161 | 380.7 | 382.0 | 375.8 | 384.2 | 382.7 | 383.0 | 359.2 | 365.6 |
| 171 | 381.5 | 382.1 | 372.7 | 384.2 | 381.5 | 383.1 | 361.6 | 365.6 |
| 181 | 395.5 | 382.1 | 382.2 | 384.3 | 386.8 | 383.1 | 367.7 | 365.6 |
| 191 | 383.5 | 382.1 | 382.6 | 384.3 | 378.1 | 383.1 | 362.8 | 365.7 |
| 201 | 377.6 | 382.1 | 386.1 | 384.3 | 381.5 | 383.1 | 358.2 | 365.7 |
| $\operatorname{sim}$ | (382) |  | (383.1) |  | (382.5) |  | (364.5) |  |
|  | ( $n=20, p_{0}=0.3$ ) |  | ( $n=20, p_{0}=0.5$ ) |  | ( $n=20, p_{0}=0.6$ ) |  | ( $n=20, p_{0}=0.8$ ) |  |
| $2 m+1$ | D-SN EWMA | D-SN-C EWMA | D-SN EWMA | D-SN-C EWMA | D-SN EWMA | D-SN-C EWMA | D-SN EWMA | D-SN-C EWMA |
| 51 | 392.2 | 371.7 | 347.4 | 370.7 | 358.9 | 372.4 | 359.7 | 360.7 |
| 61 | 386.9 | 373.2 | 381.8 | 375.4 | 385.1 | 375.3 | 365.1 | 361.7 |
| 71 | 385.7 | 372.7 | 372.0 | 375.4 | 389.0 | 375.5 | 348.1 | 361.7 |
| 81 | 378.1 | 372.9 | 384.4 | 375.9 | 397.3 | 375.8 | 349.6 | 361.9 |
| 91 | 378.9 | 373.1 | 376.9 | 376.1 | 383.8 | 375.9 | 360.4 | 362.4 |
| 101 | 372.3 | 373.2 | 382.1 | 376.2 | 357.1 | 375.9 | 360.0 | 362.5 |
| 111 | 358.0 | 373.3 | 377.8 | 376.3 | 379.3 | 376.0 | 361.1 | 362.6 |
| 121 | 382.8 | 373.3 | 389.0 | 376.4 | 380.6 | 376.1 | 360.5 | 362.7 |
| 131 | 372.5 | 373.4 | 375.3 | 376.5 | 380.6 | 376.2 | 355.9 | 362.8 |
| 141 | 365.9 | 373.4 | 372.5 | 376.5 | 374.1 | 376.2 | 371.3 | 362.8 |
| 151 | 369.7 | 373.4 | 368.5 | 376.5 | 382.9 | 376.2 | 364.2 | 362.9 |
| 161 | 371.5 | 373.5 | 375.2 | 376.6 | 372.5 | 376.3 | 369.4 | 362.9 |
| 171 | 361.3 | 373.5 | 376.8 | 376.6 | 380.5 | 376.3 | 362.8 | 362.9 |
| 181 | 378.1 | 373.5 | 376.6 | 376.6 | 377.1 | 376.3 | 361.7 | 363.0 |
| 191 | 377.2 | 373.5 | 375.1 | 376.6 | 374.5 | 376.3 | 370.7 | 363.0 |
| 201 | 377.1 | 373.5 | 377.3 | 376.7 | 378.5 | 376.3 | 368.5 | 363.0 |
| sim | (372.7) |  | (375.6) |  | (376.2) |  | (360.06) |  |

Table 3.: $\mathrm{ARL}_{1}$ values as a function of the number of subintervals $2 m+1$ for the twosided D-SN EWMA chart (top) and two-sided D-SN-C EWMA chart (bottom) with $h=0.2$ when $\lambda=0.2, K=2.85, n=5$ and $\tau=1.1$ for the $\# 1-\# 18$ distributions listed in Table 1.

| D-SN EWMA chart |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $2 m+1$ | \#1 | \#2 | \#3 | \#4 | \#5 | \#6 | \#7 | \#8 | \#9 | \#10 | \#11 | \#12 | \#13 | \#14 | \#15 | \#16 | \#17 | \#18 |
| 51 | 158.6 | 182.1 | 188.8 | 193.7 | 198.7 | 202.8 | 164.6 | 180.9 | 185.4 | 194.8 | 202.3 | 207.3 | 168.5 | 176.9 | 179.2 | 200.8 | 211.4 | 217.2 |
| 61 | 178.9 | 206.4 | 214.3 | 220.1 | 226.1 | 230.9 | 185.9 | 205.0 | 210.4 | 221.4 | 230.3 | 236.3 | 190.5 | 200.3 | 203.0 | 228.6 | 241.1 | 248.1 |
| 71 | 162.6 | 187.1 | 194.2 | 199.3 | 204.6 | 208.8 | 168.8 | 185.8 | 190.6 | 200.4 | 208.3 | 213.6 | 173.0 | 181.7 | 184.1 | 206.8 | 217.9 | 224.0 |
| 81 | 170.9 | 196.8 | 204.3 | 209.7 | 215.3 | 219.7 | 177.5 | 195.5 | 200.6 | 210.9 | 219.3 | 224.8 | 181.9 | 191.1 | 193.6 | 217.6 | 229.4 | 235.8 |
| 91 | 174.9 | 201.8 | 209.6 | 215.2 | 221.1 | 225.8 | 181.7 | 200.5 | 205.7 | 216.5 | 225.3 | 231.1 | 186.3 | 195.9 | 198.5 | 223.5 | 235.9 | 242.7 |
| 101 | 176.3 | 203.3 | 211.1 | 216.8 | 222.7 | 227.3 | 183.2 | 201.9 | 207.2 | 218.0 | 226.8 | 232.7 | 187.7 | 197.3 | 200.0 | 225.1 | 237.4 | 244.2 |
| 111 | 172.0 | 198.3 | 205.9 | 211.4 | 217.1 | 221.6 | 178.7 | 197.0 | 202.1 | 212.6 | 221.1 | 226.8 | 183.1 | 192.5 | 195.0 | 219.4 | 231.4 | 238.0 |
| 121 | 179.5 | 207.3 | 215.3 | 221.1 | 227.2 | 232.0 | 186.6 | 205.9 | 211.3 | 222.4 | 231.5 | 237.5 | 191.2 | 201.1 | 203.8 | 229.7 | 242.4 | 249.4 |
| 131 | 167.2 | 192.6 | 199.9 | 205.2 | 210.7 | 215.1 | 173.7 | 191.3 | 196.3 | 206.4 | 214.6 | 220.1 | 177.9 | 187.0 | 189.4 | 213.0 | 224.5 | 230.9 |
| 141 | 169.9 | 195.7 | 203.1 | 208.5 | 214.1 | 218.5 | 176.5 | 194.4 | 199.4 | 209.7 | 218.0 | 223.6 | 180.8 | 190.0 | 192.5 | 216.4 | 228.1 | 234.6 |
| 151 | 163.9 | 188.6 | 195.7 | 200.8 | 206.2 | 210.4 | 170.2 | 187.3 | 192.2 | 202.0 | 210.0 | 215.3 | 174.4 | 183.1 | 185.5 | 208.4 | 219.6 | 225.8 |
| 161 | 174.7 | 201.4 | 209.2 | 214.7 | 220.6 | 225.2 | 181.5 | 200.1 | 205.3 | 216.0 | 224.7 | 230.5 | 186.0 | 195.5 | 198.1 | 222.9 | 235.1 | 241.8 |
| 171 | 170.4 | 196.3 | 203.8 | 209.2 | 214.9 | 219.4 | 177.0 | 195.0 | 200.1 | 210.5 | 218.9 | 224.5 | 181.4 | 190.6 | 193.1 | 217.2 | 229.0 | 235.5 |
| 181 | 169.1 | 194.8 | 202.2 | 207.5 | 213.1 | 217.5 | 175.6 | 193.4 | 198.5 | 208.7 | 217.0 | 222.6 | 179.9 | 189.1 | 191.6 | 215.4 | 227.1 | 233.5 |
| 191 | 173.2 | 199.6 | 207.3 | 212.8 | 218.6 | 223.2 | 179.9 | 198.3 | 203.5 | 214.1 | 222.7 | 228.4 | 184.4 | 193.8 | 196.4 | 221.0 | 233.1 | 239.7 |
| 201 | 172.2 | 198.4 | 206.0 | 211.4 | 217.1 | 221.7 | 178.9 | 197.1 | 202.2 | 212.7 | 221.2 | 226.8 | 183.3 | 192.6 | 195.2 | 219.5 | 231.4 | 238.0 |
| sim | 170.0 | 198.0 | 202.5 | 209.5 | 216.1 | 218.9 | 175.9 | 194.8 | 200.9 | 212.2 | 220.0 | 226.0 | 181.9 | 192.0 | 193.8 | 218.5 | 230.3 | 237.0 |
| D-SN-C EWMA chart |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |


| $2 m+1$ | \#1 | \#2 | \#3 | \#4 | \#5 | \#6 | \#7 | \#8 | \#9 | \#10 | \#11 | \#12 | \#13 | \#14 | \#15 | \#16 | \#17 | \#18 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 51 | 171.0 | 196.8 | 204.3 | 209.6 | 215.2 | 219.7 | 177.6 | 195.5 | 200.6 | 210.8 | 219.2 | 224.8 | 181.9 | 191.1 | 193.6 | 217.5 | 229.3 | 235.7 |
| 61 | 171.2 | 197.1 | 204.6 | 210.0 | 215.6 | 220.1 | 177.8 | 195.8 | 200.9 | 211.2 | 219.6 | 225.2 | 182.2 | 191.4 | 193.9 | 217.9 | 229.7 | 236.2 |
| 71 | 171.4 | 197.3 | 204.8 | 210.2 | 215.8 | 220.3 | 178.0 | 196.0 | 201.1 | 211.4 | 219.8 | 225.4 | 182.3 | 191.6 | 194.1 | 218.1 | 229.9 | 236.4 |
| 81 | 171.5 | 197.4 | 204.9 | 210.3 | 216.0 | 220.4 | 178.1 | 196.1 | 201.2 | 211.5 | 219.9 | 225.6 | 182.5 | 191.7 | 194.2 | 218.3 | 230.1 | 236.6 |
| 91 | 171.5 | 197.5 | 205.0 | 210.4 | 216.1 | 220.5 | 178.2 | 196.2 | 201.3 | 211.6 | 220.0 | 225.7 | 182.5 | 191.8 | 194.3 | 218.4 | 230.2 | 236.7 |
| 101 | 171.6 | 197.6 | 205.1 | 210.5 | 216.1 | 220.6 | 178.2 | 196.2 | 201.3 | 211.7 | 220.1 | 225.7 | 182.6 | 191.8 | 194.4 | 218.4 | 230.3 | 236.8 |
| 111 | 171.6 | 197.6 | 205.1 | 210.5 | 216.2 | 220.7 | 178.2 | 196.3 | 201.4 | 211.8 | 220.2 | 225.8 | 182.6 | 191.9 | 194.4 | 218.5 | 230.3 | 236.8 |
| 121 | 171.7 | 197.6 | 205.1 | 210.6 | 216.2 | 220.7 | 178.3 | 196.3 | 201.4 | 211.8 | 220.2 | 225.8 | 182.6 | 191.9 | 194.4 | 218.5 | 230.4 | 236.9 |
| 131 | 171.7 | 197.7 | 205.2 | 210.6 | 216.2 | 220.7 | 178.3 | 196.3 | 201.4 | 211.8 | 220.2 | 225.9 | 182.7 | 191.9 | 194.5 | 218.6 | 230.4 | 236.9 |
| 141 | 171.7 | 197.7 | 205.2 | 210.6 | 216.3 | 220.8 | 178.3 | 196.4 | 201.5 | 211.8 | 220.3 | 225.9 | 182.7 | 191.9 | 194.5 | 218.6 | 230.4 | 236.9 |
| 151 | 171.7 | 197.7 | 205.2 | 210.6 | 216.3 | 220.8 | 178.3 | 196.4 | 201.5 | 211.9 | 220.3 | 225.9 | 182.7 | 192.0 | 194.5 | 218.6 | 230.5 | 237.0 |
| 161 | 171.7 | 197.7 | 205.2 | 210.6 | 216.3 | 220.8 | 178.3 | 196.4 | 201.5 | 211.9 | 220.3 | 225.9 | 182.7 | 192.0 | 194.5 | 218.6 | 230.5 | 237.0 |
| 171 | 171.7 | 197.7 | 205.2 | 210.7 | 216.3 | 220.8 | 178.4 | 196.4 | 201.5 | 211.9 | 220.3 | 225.9 | 182.7 | 192.0 | 194.5 | 218.6 | 230.5 | 237.0 |
| 181 | 171.7 | 197.7 | 205.3 | 210.7 | 216.3 | 220.8 | 178.4 | 196.4 | 201.5 | 211.9 | 220.3 | 225.9 | 182.7 | 192.0 | 194.5 | 218.7 | 230.5 | 237.0 |
| 191 | 171.7 | 197.8 | 205.3 | 210.7 | 216.3 | 220.8 | 178.4 | 196.4 | 201.5 | 211.9 | 220.3 | 226.0 | 182.7 | 192.0 | 194.5 | 218.7 | 230.5 | 237.0 |
| 201 | 171.7 | 197.8 | 205.3 | 210.7 | 216.3 | 220.8 | 178.4 | 196.4 | 201.5 | 211.9 | 220.3 | 226.0 | 182.7 | 192.0 | 194.5 | 218.7 | 230.5 | 237.0 |
| $p_{1}$ | 0.5463 | 0.5411 | 0.5398 | 0.5388 | 0.5378 | 0.5371 | 0.5449 | 0.5414 | 0.5404 | 0.5386 | 0.5371 | 0.5362 | 0.5440 | 0.5422 | 0.5417 | 0.5374 | 0.5355 | 0.5344 |

Table 4.: $\mathrm{ARL}_{1}$ values as a function of the number of subintervals $2 m+1$ for the twosided D-SN EWMA chart (top) and two-sided D-SN-C EWMA chart (bottom) with $h=0.2$ when $\lambda=0.2, K=2.85, n=5$ and $\tau=0.9$ for the $\# 1-\# 18$ distributions listed in Table 1

| D-SN EWMA chart |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $2 m+1$ | \#1 | \#2 | \#3 | \#4 | \#5 | \#6 | \#7 | \#8 | \#9 | \#10 | \#11 | \#12 | \#13 | \#14 | \#15 | \#16 | \#17 | \#18 |
| 51 | 120.2 | 149.7 | 158.3 | 164.4 | 170.7 | 175.7 | 121.4 | 146.2 | 152.9 | 165.4 | 175.0 | 181.3 | 125.6 | 139.1 | 142.7 | 173.0 | 186.3 | 193.3 |
| 61 | 134.2 | 168.5 | 178.5 | 185.7 | 193.1 | 198.9 | 135.6 | 164.4 | 172.2 | 186.8 | 198.1 | 205.5 | 140.5 | 156.1 | 160.3 | 195.7 | 211.4 | 219.7 |
| 71 | 122.6 | 153.4 | 162.3 | 168.6 | 175.2 | 180.4 | 124.0 | 149.7 | 156.6 | 169.7 | 179.7 | 186.3 | 128.3 | 142.3 | 146.0 | 177.6 | 191.5 | 198.9 |
| 81 | 128.7 | 161.2 | 170.6 | 177.3 | 184.3 | 189.8 | 130.1 | 157.3 | 164.6 | 178.4 | 189.0 | 196.0 | 134.7 | 149.5 | 153.5 | 186.8 | 201.5 | 209.3 |
| 91 | 131.2 | 164.7 | 174.5 | 181.5 | 188.8 | 194.5 | 132.6 | 160.7 | 168.3 | 182.7 | 193.7 | 200.9 | 137.3 | 152.6 | 156.7 | 191.4 | 206.7 | 214.9 |
| 101 | 132.3 | 166.1 | 175.9 | 182.9 | 190.2 | 196.0 | 133.8 | 162.1 | 169.7 | 184.1 | 195.2 | 202.4 | 138.6 | 153.9 | 158.1 | 192.8 | 208.2 | 216.4 |
| 111 | 129.3 | 162.1 | 171.7 | 178.5 | 185.6 | 191.2 | 130.7 | 158.2 | 165.6 | 179.6 | 190.4 | 197.4 | 135.3 | 150.3 | 154.3 | 188.1 | 203.1 | 211.0 |
| 121 | 134.4 | 169.0 | 179.1 | 186.3 | 193.8 | 199.7 | 135.9 | 164.9 | 172.7 | 187.5 | 198.9 | 206.4 | 140.8 | 156.5 | 160.8 | 196.5 | 212.3 | 220.7 |
| 131 | 125.9 | 157.7 | 166.9 | 173.5 | 180.3 | 185.7 | 127.3 | 153.9 | 161.0 | 174.5 | 185.0 | 191.7 | 131.8 | 146.2 | 150.1 | 182.7 | 197.2 | 204.8 |
| 141 | 127.9 | 160.2 | 169.6 | 176.3 | 183.2 | 188.7 | 129.3 | 156.3 | 163.6 | 177.4 | 187.9 | 194.8 | 133.9 | 148.6 | 152.5 | 185.7 | 200.3 | 208.1 |
| 151 | 123.7 | 154.6 | 163.6 | 170.0 | 176.7 | 181.9 | 125.0 | 150.9 | 157.9 | 171.1 | 181.2 | 187.8 | 129.4 | 143.5 | 147.3 | 179.0 | 193.1 | 200.5 |
| 161 | 131.3 | 164.7 | 174.3 | 181.3 | 188.5 | 194.2 | 132.7 | 160.7 | 168.2 | 182.4 | 193.4 | 200.6 | 137.4 | 152.6 | 156.7 | 191.1 | 206.3 | 214.4 |
| 171 | 128.2 | 160.6 | 170.0 | 176.8 | 183.8 | 189.3 | 129.6 | 156.7 | 164.1 | 177.9 | 188.6 | 195.5 | 134.2 | 148.9 | 152.9 | 186.3 | 201.0 | 208.9 |
| 181 | 127.3 | 159.4 | 168.7 | 175.4 | 182.3 | 187.8 | 128.6 | 155.6 | 162.8 | 176.5 | 187.0 | 193.9 | 133.2 | 147.8 | 151.7 | 184.8 | 199.4 | 207.2 |
| 191 | 130.1 | 163.2 | 172.8 | 179.7 | 186.8 | 192.5 | 131.5 | 159.2 | 166.7 | 180.8 | 191.7 | 198.8 | 136.2 | 151.3 | 155.3 | 189.4 | 204.5 | 212.5 |
| 201 | 129.6 | 162.3 | 171.9 | 178.7 | 185.7 | 191.3 | 131.0 | 158.4 | 165.8 | 179.8 | 190.6 | 197.6 | 135.6 | 150.5 | 154.5 | 188.2 | 203.2 | 211.1 |
| sim | 128.7 | 162.8 | 172.2 | 178.0 | 184.1 | 190.6 | 130.6 | 157.8 | 166.4 | 178.0 | 190.0 | 197.7 | 135.8 | 150.0 | 154.1 | 188.1 | 202.5 | 212.0 |
| D-SN-C EWMA chart |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |



| $p_{1}$ | 0.4431 | 0.4515 | 0.4536 | 0.4550 | 0.4564 | 0.4575 | 0.4435 | 0.4506 | 0.4523 | 0.4553 | 0.4574 | 0.4587 | 0.4448 | 0.4487 | 0.4497 | 0.4569 | 0.4597 | 0.4611 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |

Table 5.: $\mathrm{ARL}_{0}$ values of the two-sided D-SN-C EWMA chart for $\lambda=0.2, K=2.85$ and for fixed values of $h=\{0.1,0.15, \ldots, 0.3\}$ and different combinations of $\left(n, p_{0}\right)$.


|  <br>  <br>  <br>  |  |
| :---: | :---: |
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| $\stackrel{\%}{\circ}$ |  <br>  |
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| งู่ |  <br>  |
| $\stackrel{3}{6}$ |  <br>  |
| $\bigcirc$ |  <br>  |
| $\stackrel{7}{+}$ |  |

Table 6.: $\mathrm{ARL}_{1}$ values for $\lambda=0.2, K=2.75, n=10, h=0.2$ under the benchmark of the 18 Johnson distributions for different shifts using $p_{0}=\{0.1,0.5,0,7\}$

| Cases |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\tau=0.25$ |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| $p_{0}$ | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 | 15 | 16 | 17 | 18 |
| 0.1 | 4.95 | 4.95 | 4.95 | 4.95 | 4.97 | 5.00 | 4.95 | 4.96 | 4.97 | 4.99 | 5.03 | 5.08 | 5.11 | 5.07 | 5.06 | 5.12 | 5.22 | 5.30 |
| 0.2 | 3.00 | 3.00 | 3.00 | 3.00 | 3.00 | 3.01 | 3.00 | 3.00 | 3.00 | 3.01 | 3.02 | 3.04 | 3.09 | 3.04 | 3.03 | 3.06 | 3.11 | 3.16 |
| 0.5 | 2.00 | 2.00 | 2.00 | 2.00 | 2.00 | 2.00 | 2.00 | 2.00 | 2.00 | 2.00 | 2.00 | 2.00 | 2.00 | 2.00 | 2.00 | 2.00 | 2.00 | 2.01 |
| 0.7 | 1.00 | 1.02 | 1.09 | 1.16 | 1.23 | 1.29 | 1.16 | 1.09 | 1.08 | 1.20 | 1.30 | 1.37 | 1.21 | 1.15 | 1.14 | 1.32 | 1.44 | 1.50 |
| $\tau=0.75$ |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 0.1 | 4.95 | 6.25 | 8.67 | 11.22 | 14.28 | 17.01 | 7.46 | 7.79 | 8.30 | 13.38 | 17.99 | 21.50 | 9.50 | 8.99 | 8.83 | 20.68 | 27.42 | 31.79 |
| 0.2 | 3.00 | 5.05 | 6.38 | 7.54 | 8.83 | 9.91 | 4.66 | 5.05 | 5.78 | 8.22 | 10.14 | 11.51 | 5.12 | 4.94 | 5.05 | 10.74 | 13.44 | 15.10 |
| 0.5 | 4.79 | 6.48 | 7.05 | 7.48 | 7.94 | 8.33 | 4.63 | 6.18 | 6.63 | 7.54 | 8.28 | 8.79 | 4.82 | 5.67 | 5.91 | 8.14 | 9.23 | 9.86 |
| 0.7 | 9.11 | 10.20 | 10.52 | 10.75 | 11.01 | 11.22 | 8.93 | 9.99 | 10.27 | 10.75 | 11.16 | 11.44 | 9.06 | 9.65 | 9.81 | 10.98 | 11.61 | 11.97 |
| $\tau=2$ |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 0.1 | 1.12 | 1.42 | 1.58 | 1.72 | 1.88 | 2.01 | 1.32 | 1.48 | 1.55 | 1.80 | 2.03 | 2.20 | 1.42 | 1.48 | 1.50 | 2.06 | 2.42 | 2.64 |
| 0.2 | 1.57 | 1.84 | 1.95 | 2.03 | 2.13 | 2.21 | 1.79 | 1.90 | 1.94 | 2.08 | 2.22 | 2.33 | 1.87 | 1.91 | 1.92 | 2.23 | 2.45 | 2.59 |
| 0.5 | 2.96 | 3.14 | 3.20 | 3.24 | 3.29 | 3.33 | 3.12 | 3.18 | 3.20 | 3.27 | 3.33 | 3.38 | 3.18 | 3.19 | 3.19 | 3.34 | 3.43 | 3.49 |
| 0.7 | 5.06 | 5.19 | 5.22 | 5.25 | 5.28 | 5.31 | 5.18 | 5.21 | 5.23 | 5.27 | 5.31 | 5.34 | 5.22 | 5.22 | 5.22 | 5.31 | 5.37 | 5.40 |

Table 7.: Out-of-control performance for the proposed chart along with the corresponding optimal parameters for $n=10$

| case | $=0.25$ | $\tau=0.5$ | $\tau=0.75$ | $\tau=0.95$ | $\tau=1.25$ | $\tau=1.5$ | $\tau=1.75$ | $\tau=1.95$ | $=2.0$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| \#1 | (0.75,2.845) | (0.75,2.845) | (0.3,2.908) | (0.05,2.478) | (0.3,3.349) | (0.3,3.349) | (0.35,3.434) | (0.8,3.755) | (0.8,3.755) |
|  | $\begin{gathered} 1 \\ (0.5,0) \end{gathered}$ | $\begin{gathered} 1.12 \\ (0.5,0.0130) \end{gathered}$ | $\begin{gathered} 4.26 \\ (0.25,0.018) \end{gathered}$ | $\begin{gathered} 27.22 \\ (0.05,0.014) \end{gathered}$ | $\begin{gathered} 2.88 \\ (0.05,0.233) \end{gathered}$ | $\begin{gathered} 1.61 \\ (0.05,0.364) \end{gathered}$ | $\begin{gathered} 1.27 \\ (0.05,0.457) \end{gathered}$ | $\begin{gathered} 1.15 \\ (0.05,0.514) \end{gathered}$ | $\begin{gathered} 1.13 \\ (0.05,0.526) \end{gathered}$ |
| \#2 | (0.75,2.845) | (0.65,2.867) | (0.15,2.791) | (0.05,2.481) | (0.15,2.93) | (0.3,3.349) | (0.3,3.349) | (0.3,3.349) | (0.3,3.349) |
|  | $\begin{gathered} 1 \\ (0.5,0) \end{gathered}$ | $\begin{gathered} 2.66 \\ (0.5,0.150) \end{gathered}$ | $\begin{gathered} 9.11 \\ (0.25,0.107) \end{gathered}$ | $\begin{gathered} 106.13 \\ (0.15,0.125) \end{gathered}$ | $\begin{gathered} 7.11 \\ (0.05,0.139) \end{gathered}$ | $\begin{gathered} 2.92 \\ (0.05,0.231) \end{gathered}$ | $\begin{gathered} 1.93 \\ (0.05,0.313) \end{gathered}$ | $\begin{gathered} 1.59 \\ (0.05,0.369) \end{gathered}$ | $\begin{gathered} 1.53 \\ (0.05,0.382) \end{gathered}$ |
| \#3 | (0.65,2.88) | (0.4,2.89) | (0.1,2.691) | (0.05,2.483) | (0.1,2.722) | (0.25,3.244) | (0.3,3.349) | (0.3,3.349) | (0.3,3.349) |
|  | $\begin{gathered} 1.05 \\ (0.6,0.0359) \end{gathered}$ | $\begin{gathered} 3.07 \\ (0.5,0.177) \end{gathered}$ | $10.99$ | $131.57$ | $10.33$ | $3.97$ | $2.43$ | $1.92$ | $\begin{aligned} & 1.83 \\ & 5,0.327) \end{aligned}$ |
| \#4 | (0.7,2.876) | (0.4,2.89) | (0.1,2.695) | (0.05,2.49) | (0.15,2.829) | (0.2,2.929) | (0.3,3.349) | (0.3,3.349) | (0.3,3.349) |
|  | $\begin{gathered} 1.11 \\ (0.6,0.057) \end{gathered}$ | $\begin{gathered} 3.34 \\ (0.5,0.193) \end{gathered}$ | $\begin{gathered} 12.22 \\ (0.35,0.221) \end{gathered}$ | $\begin{gathered} 145.23 \\ (0.3,0.27) \end{gathered}$ | $\begin{gathered} 12.77 \\ (0.1,0.176) \end{gathered}$ | $\begin{gathered} 5.01 \\ (0.1,0.252) \end{gathered}$ | $\begin{gathered} 2.97 \\ (0.05,0.228) \end{gathered}$ | $\begin{gathered} 2.27 \\ (0.05,0.276) \end{gathered}$ | $\begin{gathered} 2.15 \\ (0.05,0.287) \end{gathered}$ |
| \#5 | (0.65,2.88) | (0.4,2.89) | (0.1,2.695) | (0.05,2.486) | (0.1,2.697) | (0.2,2.929) | (0.4,3.239) | (0.4,3.239) | (0.4,3.239) |
|  | 1.19 $(0.0078)$ | 3.62 $(0.5,0.208)$ | 13.44 $(0.350 .29)$ | 156.8 $(0.350 .327)$ | 15.23 $(0.15 .0231)$ | ${ }_{5}^{5.86}$ | 3.51 <br> 0.109 | 2.64 | 2.49 |
|  | $(0.6,0.078)$ | $(0.5,0.208)$ | (0.35,0.229) | $(0.35,0.327)$ | $(0.15,0.231)$ | (0.1,0.235) | (0.1,0.299) | (0.1,0.345) | (0.1,0.356) |
| \#6 | (0.7,2.876) | (0.35,2.889) | (0.1,2.689) | (0.05,2.486) | (0.1,2.697) | (0.2,2.88) | (0.4,3.096) | (0.4,3.239) | (0.4,3.239) |
|  | $\begin{gathered} 1.25 \\ (0.6,0.092) \end{gathered}$ | $\begin{gathered} 3.81 \\ (0.55,0.268) \end{gathered}$ | $\begin{gathered} 14.3 \\ (0.4,0.281) \end{gathered}$ | $\begin{gathered} 164.51 \\ (0.35,0.328) \end{gathered}$ | $\begin{gathered} 16.93 \\ (0.15,0.225) \end{gathered}$ | $\begin{gathered} 6.47 \\ (0.15,0.296) \end{gathered}$ | $\begin{gathered} 3.92 \\ (0.15,0.359) \end{gathered}$ | $\begin{gathered} 2.93 \\ (0.1,0.327) \end{gathered}$ | $\begin{gathered} 2.75 \\ (0.1,0.337) \end{gathered}$ |
| \#7 | (0.75,3.052) | (0.65,2.88) | (0.2,2.832) | (0.05,2.487) | (0.25,3.244) | (0.3,3.349) | (0.35,3.434) | (0.35,3.434) | (0.35,3.434) |
|  | 1.11 $(0.750 .183)$ | 1.93 | 5.6 $(0.350 .136)$ | 40.16 $(0.10 .062)$ | 3.52 $(0.050$ | 1.99 | 1.55 | 1.38 $(0.050 .4195)$ | 1.35 <br> $(0.05$ |
|  | (0.75,0.183) | $(0.6,0.194)$ | (0.35,0.136) | (0.1,0.062) | (0.05,0.205) | (0.05,0.306) | (0.05,0.376) | (0.05,0.4195) | $(0.05,0.429)$ |
| \#8 | (0.7,3.039) | (0.65,2.867) | (0.15,2.783) | (0.05,2.481) | (0.2,3.107) | (0.3,3.349) | (0.3,3.349) | (0.3,3.349) | (0.3,3.349) |
|  | $\begin{gathered} 1.08 \\ (0.75,0.164) \end{gathered}$ | $\begin{gathered} 2.54 \\ (0.5,0.143) \end{gathered}$ | $\begin{gathered} 8.71 \\ (0.3,0.145) \end{gathered}$ | $\begin{gathered} 98.21 \\ (0.15,0.124) \end{gathered}$ | $\begin{gathered} 6.47 \\ (0.05,0.146) \end{gathered}$ | $\begin{gathered} 2.85 \\ (0.05,0.235) \end{gathered}$ | $\begin{gathered} 1.98 \\ (0.05,0.307) \end{gathered}$ | $\begin{gathered} 1.66 \\ (0.05,0.355) \end{gathered}$ | $\begin{gathered} 1.6 \\ (0.05,0.366) \end{gathered}$ |
| \#9 | (0.95,2.848) | (0.4,2.89) | (0.1,2.691) | (0.05,2.489) | (0.15,2.93) | (0.3,3.349) | (0.3,3.349) | (0.3,3.349) | (0.3,3.349) |
|  | $\begin{gathered} 1.1 \\ (0.7,0.118) \end{gathered}$ | $\begin{gathered} 2.86 \\ (0.5,0.162) \end{gathered}$ | $\begin{gathered} 10.01 \\ (0.3,0.158) \end{gathered}$ | $\begin{gathered} 117.81 \\ (0.2,0.175) \end{gathered}$ | $\begin{gathered} 8.27 \\ (0.05,0.129) \end{gathered}$ | $\begin{gathered} 3.39 \\ (0.05,0.210) \end{gathered}$ | $\begin{gathered} 2.22 \\ (0.05,0.280) \end{gathered}$ | $\begin{gathered} 1.81 \\ (0.05,0.329) \end{gathered}$ | $\begin{gathered} 1.74 \\ (0.05,0.340) \end{gathered}$ |
| \#10 | (0.65,2.88) | (0.4,2.89) | (0.1,2.695) | $(0.05,2.49)$ | (0.15,2.829) | (0.2,2.929) | (0.4,3.239) | (0.4,3.239) | (0.4,3.239) |
|  | $1.19$ | $\begin{gathered} 3.43 \\ \hline .5 .199) \end{gathered}$ | $\begin{gathered} 12.6 \\ (0.35 .0 .224) \end{gathered}$ | $148.82$ | $13.88$ | $5.35$ | $3.22$ | $2.46$ | $\begin{gathered} 2.33 \\ (0.1 .0 .370) \end{gathered}$ |
|  | (0.6,0.077) | (0.5,0.199) | (0.35,0.224) | (0.3,0.277) | (0.1,0.172) | (0.1,0.245) | (0.1, 0.311$)$ | (0.1,0.359) | (0.1,0.370) |
| \#11 | $(0.65,2.88)$ 1.28 | $(0.35,2.889)$ 3.8 | $(0.1,2.689)$ 14.28 | $(0.05,2.49)$ 164.24 | $(0.1,2.697)$ 17.08 | $(0.2,2.88)$ 6.51 | $(0.4,3.096)$ 3.95 | $(0.4,3.239)$ 2.96 | $(0.4,3.239)$ 2.78 |
|  | $\begin{gathered} 1.28 \\ (0.6,0.097) \end{gathered}$ | $\begin{gathered} 3.8 \\ (0.55,0.267) \end{gathered}$ | $\begin{gathered} 14.28 \\ (0.4,0.280) \\ \hline \end{gathered}$ | $\begin{gathered} 164.24 \\ (0.4,0.378) \end{gathered}$ | $\begin{gathered} 17.08 \\ (0.15,0.224) \end{gathered}$ | $\begin{gathered} 6.51 \\ (0.15,0.295) \end{gathered}$ | $\begin{gathered} 3.95 \\ (0.15,0.358) \end{gathered}$ | $\begin{gathered} 2.96 \\ (0.1,0.325) \end{gathered}$ | $\begin{gathered} 2.78 \\ (0.1,0.335) \end{gathered}$ |
| \#12 | (0.7,3.039) | (0.35,2.889) | (0.1,2.694) | (0.05,2.49) | (0.1,2.695) | (0.2,2.88) | (0.25,2.939) | (0.4,3.096) | (0.4,3.096) |
|  | $\begin{gathered} 1.34 \\ (0.75 .0 .266) \end{gathered}$ | $\begin{gathered} 4.04 \\ (0.55,0.278) \end{gathered}$ | $\begin{gathered} 15.3 \\ (0.45 .0 .334) \end{gathered}$ | 172.13 | 18.96 | $\begin{gathered} 7.28 \\ (0.15 .0 .284) \end{gathered}$ | 4.37 | 3.27 | $\begin{aligned} & 3.08 \\ & 15,0.397) \end{aligned}$ |
|  |  | (0.5,0.278) | (0,0.334) | (0.4,0.379) | (0.2,0.278) | (0.15,0.28 | 15,0.3 | 15,0.387) | (0.3,3.349) |
| \#13 | 1.13 | (0.62 | 11 | 48.37 | 3.95 | 2.19 | 1.7 | 1.52 | 1.48 |
|  | (0.75,0.194) | (0.6,0.201) | (0.35,0.148) | (0.1,0.066) | (0.05,0.191) | (0.05,0.283) | (0.05,0.346) | (0.05,0.384) | (0.05,0.393) |
| \#14 | (0.75,3.052) | (0.5,2.886) | (0.15,2.783) | (0.05,2.487) | (0.25,3.244) | (0.3,3.349) | (0.3,3.349) | $(0.3,3.349)$ | (0.3,3.349) |
|  | 1.1 | 2.35 | 7.65 | 78.08 | 5.31 | 2.58 | 1.89 | 1.63 | 1.58 |
|  | (0.75,0.179) | $(0.55,0.175)$ | (0.3,0.132) | (0.1,0.07) | (0.05,0.162) | (0.05,0.252) | (0.05,0.318) | (0.05,0.361) | (0.05,0.370) |
| \#15 | (0.75,3.052) | (0.5,2.886) | (0.15,2.783) | (0.05,2.487) | (0.2,3.107) | (0.3,3.349) | (0.3,3.349) | (0.3,3.349) | (0.3,3.349) |
|  | 1.09 | 2.46 | 8.21 | 89.88 | 5.91 | 2.74 | 1.96 | 1.67 | 1.62 |
|  | (0.75,0.175) | $(0.55,0.185)$ | (0.3,0.139) | (0.1,0.07) | (0.05,0.153) | (0.05,0.241) | (0.05,0.309) | (0.05,0.3528) | (0.05,0.362) |
| \#16 | (0.75,3.052) | (0.35,2.889) | (0.1,2.694) | (0.05,2.490) | (0.1,2.695) | (0.2,2.880) | (0.4,3.096) | (0.4,3.096) | (0.4,3.096) |
|  | 1.28 | 3.78 | 14.17 | 162.79 | 17.22 | 6.6 | ${ }^{4}$ | 3.01 | 2.84 |
|  | (0.75,0.250) | (0.55,0.2664) | (0.45,0.328) | (0.4,0.378) | (0.2,0.283) | $(0.15,0.294)$ | (0.15,0.357) | (0.15,0.401) | (0.15,0.411) |
| \#17 | (0.7,3.039) | (0.35,2.886) | (0.1,2.694) | (0.05,2.487) | (0.1,2.696) | (0.2,2.855) | (0.3,2.940) | (0.4,3.096) | (0.4,3.096) |
|  | 1.39 | 4.23 | 16.21 | 178.51 | 20.93 | 8.07 | 4.83 | 3.64 | 3.42 |
|  | (0.75,0.279) | $(0.6,0.340)$ | (0.45,0.338) | (0.45,0.430) | $(0.25,0.329)$ | $(0.2,0.339)$ | (0.2,0.398) | (0.15,0.370) | (0.15,0.380) |
| \#18 | (0.7,3.039) | (0.35,2.886) | (0.1,2.689) | (0.05,2.487) | (0.05,2.49) | (0.2,2.855) | (0.25,2.905) | (0.35,2.971) | (0.35,2.971) |
|  | 1.45 | 4.49 | 17.31 | 185.84 | 22.91 | 8.92 | 5.27 | 3.96 | 3.74 |
|  | (0.75,0.293) | (0.6,0.3495) | (0.5,0.393) | (0.45,0.430) | (0.3,0.379) | (0.2,0.330) | (0.2,0.3867) | (0.2,0.426) | (0.2,0.436) |

Table 8.: Out-of-control performance for the proposed chart along with the corresponding optimal parameters for $n=20$

| case | $\tau=0.25$ | $\tau=0.5$ | $\tau=0.75$ | $\tau=0.95$ | $\tau=1.25$ | $\tau=1.5$ | $\tau=1.75$ | $\tau=1.95$ | $\tau=2.0$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| \#1 | (0.65,2.948) | (0.65,2.948) | (0.4,2.949) | (0.05,2.487) | (0.5,3.4) | (0.55,3.445) | (0.45,3.357) | (0.5,3.4) | (0.5,3.4) |
|  | $\begin{gathered} 1 \\ (0.35,0) \\ \hline \end{gathered}$ | $\begin{gathered} 1 \\ (0.35,0) \\ \hline \end{gathered}$ | $\begin{gathered} 2.35 \\ (0.25,0.018) \\ \hline \end{gathered}$ | $\begin{gathered} 15.84 \\ (0.05,0.014) \\ \hline \end{gathered}$ | $\begin{gathered} 1.73 \\ (0.05,0.233) \\ \hline \end{gathered}$ | $\begin{gathered} 1.1 \\ (0.05,0.364) \\ \hline \end{gathered}$ | $\begin{gathered} 1.02 \\ (0.05,0.457) \\ \hline \end{gathered}$ | $\begin{gathered} 1 \\ (0.05,0.514) \\ \hline \end{gathered}$ | $\begin{gathered} 1 \\ (0.05,0.526) \\ \hline \end{gathered}$ |
| \#2 | (0.65,2.948) | (0.7,2.937) | (0.25,2.888) | (0.05,2.489) | (0.25,3.075) | $(0.5,3.4)$ | $(0.6,3.49)$ | (0.55,3.445) | (0.55,3.445) |
|  | $\begin{gathered} 1 \\ (0.35,0) \end{gathered}$ | $\begin{gathered} 1.38 \\ (0.4,0.0613368) \end{gathered}$ | $\begin{gathered} 5.3 \\ (0.25,0.107) \end{gathered}$ | $\begin{gathered} 58.21 \\ (0.1,0.0792381) \end{gathered}$ | $\begin{gathered} 4.31 \\ (0.05,0.139) \end{gathered}$ | $\begin{gathered} 1.75 \\ (0.05,0.231) \end{gathered}$ | $\begin{gathered} 1.22 \\ (0.05,0.313) \end{gathered}$ | $\begin{gathered} 1.09 \\ (0.05,0.369) \end{gathered}$ | $\begin{gathered} 1.07 \\ (0.05,0.382) \end{gathered}$ |
| \#3 | (0.7,2.947) | (0.7,2.931) | (0.2,2.847) | (0.05,2.49) | (0.2,2.966) | (0.5,3.4) | (0.5,3.4) | (0.55,3.445) | (0.55,3.445) |
|  | $\begin{gathered} 1 \\ (0.35,0) \end{gathered}$ | $\begin{gathered} 1.67 \\ (0.45,0.130) \end{gathered}$ | $\begin{gathered} 6.46 \\ (0.3,0.167) \end{gathered}$ | $\begin{gathered} 76.22 \\ (0.2,0.177) \end{gathered}$ | $\begin{gathered} 6.28 \\ (0.05,0.116) \end{gathered}$ | $\begin{gathered} 2.38 \\ (0.05,0.191) \end{gathered}$ | $\begin{gathered} 1.48 \\ (0.05,0.263) \end{gathered}$ | $\begin{gathered} 1.22 \\ (0.05,0.314) \end{gathered}$ | $\begin{gathered} 1.18 \\ (0.05,0.327) \end{gathered}$ |
| \#4 | (0.7,2.931) | (0.7,2.93) | (0.15,2.793) | (0.05,2.49) | (0.2,2.888) | (0.5,3.181) | (0.5,3.4) | (0.55,3.445) | (0.55,3.445) |
|  | $\begin{gathered} 1 \\ (0.45,0.01) \end{gathered}$ | $\begin{gathered} 1.86 \\ (0.5,0.193) \end{gathered}$ | $\begin{gathered} 7.22 \\ (0.35,0.221) \end{gathered}$ | $\begin{gathered} 87.22 \\ (0.25,0.227) \end{gathered}$ | $\begin{gathered} 7.76 \\ (0.1,0.176) \\ \hline \end{gathered}$ | $\begin{gathered} 3 \\ (0.1,0.252) \end{gathered}$ | $\begin{gathered} 1.78 \\ (0.05,0.228) \end{gathered}$ | $\begin{gathered} 1.39 \\ (0.05,0.276) \end{gathered}$ | $\begin{gathered} 1.33 \\ (0.05,0.287) \end{gathered}$ |
|  | (0.75,2.927) | (0.7,2.93) | (0.15,2.792) | (0.05,2.489) | (0.2,2.867) | (0.3,3.004) | (0.55,3.21) | (0.55,3.21) | (0.55,3.21) |
| \#5 | $\begin{gathered} 1 \\ (0.5,0.034) \end{gathered}$ | $\begin{gathered} 2.06 \\ (0.5,0.208) \end{gathered}$ | $\begin{gathered} 7.9 \\ (0.4,0.276) \end{gathered}$ | $\begin{gathered} 96.79 \\ (0.3,0.278) \end{gathered}$ | $\begin{gathered} 9.22 \\ (0.15,0.231) \end{gathered}$ | $\begin{gathered} 3.54 \\ (0.1,0.235) \end{gathered}$ | $\begin{gathered} 2.07 \\ (0.1,0.299) \end{gathered}$ | $\begin{gathered} 1.59 \\ (0.1,0.345) \end{gathered}$ | $\begin{gathered} 1.52 \\ (0.1,0.356) \end{gathered}$ |
| \#6 | (0.75,2.927) | (0.7,2.931) | (0.15,2.792) | (0.05,2.489) | (0.15,2.802) | (0.3,2.946) | (0.55,3.21) | (0.55,3.21) | (0.55,3.21) |
|  | $\begin{gathered} 1.01 \\ (0.5,0.045) \\ \hline \end{gathered}$ | $\begin{gathered} 2.19 \\ (0.55,0.268) \\ \hline \end{gathered}$ | $\begin{gathered} 8.4 \\ (0.4,0.281) \\ \hline \end{gathered}$ | $\begin{gathered} 103.28 \\ (0.35,0.328) \\ \hline \end{gathered}$ | $\begin{gathered} 10.28 \\ (0.15,0.225) \\ \hline \end{gathered}$ | $\begin{gathered} 3.92 \\ (0.15,0.296) \\ \hline \end{gathered}$ | $\begin{gathered} 2.32 \\ (0.1,0.282) \\ \hline \end{gathered}$ | $\begin{gathered} 1.75 \\ (0.1,0.327) \\ \hline \end{gathered}$ | $\begin{gathered} 1.66 \\ (0.1,0.337) \\ \hline \end{gathered}$ |
| \#7 | (0.85,2.969) | (0.7,2.937) | (0.35,2.92) | (0.05,2.487) | (0.5,3.4) | (0.55,3.445) | (0.55,3.445) | (0.5,3.4) | (0.5,3.4) |
|  | $\begin{gathered} 1 \\ (0.7,0.146) \end{gathered}$ | $\begin{gathered} 1.19 \\ (0.6,0.194) \end{gathered}$ | $\begin{gathered} 3.25 \\ (0.35,0.136) \end{gathered}$ | $\begin{gathered} 22.66 \\ (0.05,0.022) \end{gathered}$ | $\begin{gathered} 2.1 \\ (0.05,0.205) \end{gathered}$ | $\begin{gathered} 1.25 \\ (0.05,0.306) \end{gathered}$ | $\begin{gathered} 1.08 \\ (0.05,0.376) \end{gathered}$ | $\begin{gathered} 1.04 \\ (0.05,0.419) \end{gathered}$ | $\begin{gathered} 1.03 \\ (0.05,0.429) \end{gathered}$ |
| \#8 | (0.75,2.927) | (0.75,2.927) | (0.25,2.888) | (0.05,2.489) | (0.25,3.075) | (0.5,3.4) | (0.55,3.445) | (0.5,3.4) | (0.5,3.4) |
|  | $\begin{gathered} 1 \\ (0.5,0.034) \end{gathered}$ | $\begin{gathered} 1.38 \\ (0.5,0.143) \end{gathered}$ | $\begin{gathered} 5.09 \\ (0.25,0.103) \end{gathered}$ | $\begin{gathered} 53.13 \\ (0.1,0.078) \\ \hline \end{gathered}$ | $\begin{gathered} 3.94 \\ (0.05,0.146) \end{gathered}$ | $\begin{gathered} 1.71 \\ (0.05,0.235) \end{gathered}$ | $\begin{gathered} 1.25 \\ (0.05,0.307) \end{gathered}$ | $\begin{gathered} 1.12 \\ (0.05,0.355) \end{gathered}$ | $\begin{gathered} 1.1 \\ (0.05,0.366) \end{gathered}$ |
| \#9 | (0.75,2.927) | (0.75,2.927) | (0.2,2.847) | (0.05,2.49) | (0.2,2.966) | (0.5,3.4) | (0.5,3.4) | (0.6,3.49) | (0.5,3.4) |
|  | $\begin{gathered} 1 \\ (0.5,0.030) \\ \hline \end{gathered}$ | $\begin{gathered} 1.53 \\ (0.5,0.162) \\ \hline \end{gathered}$ | $\begin{gathered} 5.84 \\ (0.3,0.158) \\ \hline \end{gathered}$ | $\begin{gathered} 66.68 \\ (0.15,0.127) \end{gathered}$ | $\begin{gathered} 5.02 \\ (0.05,0.129) \\ \hline \end{gathered}$ | $\begin{gathered} 2.03 \\ (0.05,0.210) \\ \hline \end{gathered}$ | $\begin{gathered} 1.37 \\ (0.05,0.280) \\ \hline \end{gathered}$ | $\begin{gathered} 1.17 \\ (0.05,0.329) \\ \hline \end{gathered}$ | $\begin{gathered} 1.15 \\ (0.05,0.340) \\ \hline \end{gathered}$ |
| \#10 | (0.7,2.931) | (0.7,2.93) | (0.15,2.793) | (0.05,2.489) | (0.2,2.867) | (0.3,3.004) | (0.55,3.21) | (0.55,3.445) | (0.55,3.445) |
|  | $\begin{gathered} 1 \\ (0.55,0.054) \end{gathered}$ | $\begin{gathered} 1.93 \\ (0.5,0.1991) \end{gathered}$ | $\begin{gathered} 7.44 \\ (0.35,0.224) \end{gathered}$ | $\begin{gathered} 90.67 \\ (0.3,0.277) \end{gathered}$ | $\begin{gathered} 8.4 \\ (0.15,0.236) \end{gathered}$ | $\begin{gathered} 3.23 \\ (0.1,0.245) \end{gathered}$ | $\begin{gathered} 1.91 \\ (0.1,0.311) \end{gathered}$ | $\begin{gathered} 1.49 \\ (0.05,0.260) \end{gathered}$ | $\begin{gathered} 1.42 \\ (0.05,0.270) \end{gathered}$ |
| \#11 | (0.7,2.931) | (0.7,2.931) | (0.15,2.792) | (0.05,2.489) | (0.15,2.799) | (0.3,2.946) | (0.45,3.038) | (0.55,3.21) | (0.55,3.21) |
|  | $\begin{gathered} 1.01 \\ (0.55,0.071) \end{gathered}$ | $\begin{gathered} 2.19 \\ (0.55,0.267) \end{gathered}$ | $\begin{gathered} 8.38 \\ (0.4,0.280) \end{gathered}$ | $\begin{gathered} 103.09 \\ (0.35,0.328) \end{gathered}$ | $\begin{gathered} 10.32 \\ (0.2,0.284) \end{gathered}$ | $\begin{gathered} 3.94 \\ (0.15,0.295) \end{gathered}$ | $\begin{gathered} 2.34 \\ (0.15,0.358) \end{gathered}$ | $\begin{gathered} 1.77 \\ (0.1,0.325) \end{gathered}$ | $\begin{gathered} 1.67 \\ (0.1,0.335) \end{gathered}$ |
| \#12 | (0.75,2.929) | (0.65,2.939) | (0.15,2.792) | (0.05,2.489) | (0.15,2.799) | (0.35,2.953) | (0.45,3.038) | (0.65,3.038) | (0.65,3.038) |
|  | $\begin{gathered} 1.02 \\ (0.55,0.083) \end{gathered}$ | $\begin{gathered} 2.34 \\ (0.6,0.332) \end{gathered}$ | $\begin{gathered} 9.02 \\ (0.4,0.286) \end{gathered}$ | $\begin{gathered} 110.36 \\ (0.4,0.379) \end{gathered}$ | $\begin{gathered} 11.48 \\ (0.2,0.278) \\ \hline \end{gathered}$ | $\begin{gathered} 4.39 \\ (0.2,0.350) \\ \hline \end{gathered}$ | $\begin{gathered} 2.58 \\ (0.15,0.344) \end{gathered}$ | $\begin{gathered} 1.97 \\ (0.2,0.453) \end{gathered}$ | $\begin{gathered} 1.86 \\ (0.2,0.463) \end{gathered}$ |
| \#13 | (0.8,3.001) | (0.7,2.937) | (0.35,2.92) | (0.05,2.489) | (0.5,3.4) | (0.55,3.445) | (0.55,3.445) | (0.5,3.4) | (0.5,3.4) |
|  | $\begin{gathered} 1 \\ (0.75,0.194) \end{gathered}$ | $\begin{gathered} 1.22 \\ (0.6,0.201) \end{gathered}$ | $\begin{gathered} 3.56 \\ (0.35,0.148) \end{gathered}$ | $\begin{gathered} 27.16 \\ (0.1,0.066) \end{gathered}$ | $\begin{gathered} 2.37 \\ (0.05,0.191) \end{gathered}$ | $\begin{gathered} 1.35 \\ (0.05,0.283) \end{gathered}$ | $\begin{gathered} 1.13 \\ (0.05,0.346) \end{gathered}$ | $\begin{gathered} 1.07 \\ (0.05,0.384) \end{gathered}$ | $\begin{gathered} 1.06 \\ (0.05,0.393) \end{gathered}$ |
| \#14 | (0.6,2.959) | (0.75,2.929) | (0.3,2.911) | (0.05,2.489) | (0.45,3.357) | (0.5,3.4) | (0.55,3.445) | (0.6,3.49) | (0.5,3.4) |
|  | $\begin{gathered} 1 \\ (0.7,0.1459) \end{gathered}$ | $\begin{gathered} 1.3 \\ (0.55,0.175) \end{gathered}$ | $\begin{gathered} 4.46 \\ (0.3,0.132) \end{gathered}$ | $\begin{gathered} 42.1 \\ (0.1,0.074) \end{gathered}$ | $\begin{gathered} 3.24 \\ (0.05,0.162) \end{gathered}$ | $\begin{gathered} 1.56 \\ (0.05,0.252) \end{gathered}$ | $\begin{gathered} 1.21 \\ (0.05,0.318) \end{gathered}$ | $\begin{gathered} 1.1 \\ (0.05,0.361) \end{gathered}$ | $\begin{gathered} 1.09 \\ (0.05,0.370) \end{gathered}$ |
| \#15 | (0.65,2.948) | (0.75,2.929) | (0.25,2.885) | (0.05,2.489) | (0.25,3.075) | (0.5,3.4) | (0.55,3.445) | (0.55,3.445) | (0.55,3.445) |
|  | $\begin{gathered} 1 \\ (0.65,0.111) \end{gathered}$ | $\begin{gathered} 1.36 \\ (0.55,0.185) \end{gathered}$ | $\begin{gathered} 4.81 \\ (0.3,0.139) \\ \hline \end{gathered}$ | $\begin{gathered} 48.16 \\ (0.1,0.076) \end{gathered}$ | $\begin{gathered} 3.62 \\ (0.05,0.153) \end{gathered}$ | $\begin{gathered} 1.65 \\ (0.05,0.241) \end{gathered}$ | $\begin{gathered} 1.24 \\ (0.05,0.309) \end{gathered}$ | $\begin{gathered} 1.12 \\ (0.05,0.3529) \end{gathered}$ | $\begin{gathered} 1.1 \\ (0.05,0.362) \end{gathered}$ |
| \#16 | (0.75,2.929) | (0.65,2.939) | (0.15,2.792) | (0.05,2.489) | (0.15,2.799) | (0.3,2.946) | (0.45,3.038) | (0.55,3.21) | (0.55,3.21) |
|  | $\begin{gathered} 1.02 \\ (0.55,0.083) \\ \hline \end{gathered}$ | $\begin{gathered} 2.16 \\ (0.6,0.32) \\ \hline \end{gathered}$ | $\begin{gathered} 8.34 \\ (0.4,0.280) \end{gathered}$ | $\begin{gathered} 102.38 \\ (0.35,0.328) \\ \hline \end{gathered}$ | $\begin{gathered} 10.4 \\ (0.2,0.283) \\ \hline \end{gathered}$ | $\begin{gathered} 4 \\ (0.15,0.294) \\ \hline \end{gathered}$ | $\begin{gathered} 2.37 \\ (0.15,0.357) \\ \hline \end{gathered}$ | $\begin{gathered} 1.8 \\ (0.1,0.321) \\ \hline \end{gathered}$ | $\begin{gathered} 1.71 \\ (0.1,0.331) \\ \hline \end{gathered}$ |
| \#17 | (0.7,2.937) | (0.65,2.939) | (0.15,2.792) | (0.05,2.489) | (0.1,2.697) | (0.3,2.927) | (0.45,3.038) | (0.6,3.028) | (0.6,3.028) |
|  | $\begin{gathered} 1.04 \\ (0.6,0.130) \end{gathered}$ | $\begin{gathered} 2.47 \\ (0.6,0.340) \end{gathered}$ | $\begin{gathered} 9.57 \\ (0.45,0.338) \end{gathered}$ | $\begin{gathered} 116.03 \\ (0.4,0.380) \end{gathered}$ | $\begin{gathered} 12.65 \\ (0.25,0.329) \end{gathered}$ | $\begin{gathered} 4.86 \\ (0.2,0.339) \end{gathered}$ | $\begin{gathered} 2.89 \\ (0.15,0.329) \end{gathered}$ | $\begin{gathered} 2.14 \\ (0.2,0.440) \end{gathered}$ | $\begin{gathered} 2.02 \\ (0.2,0.450) \end{gathered}$ |
|  | (0.95,2.876) | (0.45,2.935) | (0.15,2.792) | (0.05,2.489) | (0.1,2.698) | (0.3,2.918) | (0.4,2.971) | (0.6,3.028) | (0.6,3.028) |
| \#18 | $\begin{gathered} 1.05 \\ (0.65,0.181) \\ \hline \end{gathered}$ | $\begin{gathered} 2.65 \\ (0.6,0.349) \\ \hline \end{gathered}$ | $\begin{gathered} 10.25 \\ (0.45,0.343) \\ \hline \end{gathered}$ | $\begin{gathered} 123.14 \\ (0.4,0.381) \\ \hline \end{gathered}$ | $\begin{gathered} 13.75 \\ (0.3,0.379) \\ \hline \end{gathered}$ | $\begin{gathered} 5.33 \\ (0.25,0.391) \\ \hline \end{gathered}$ | $\begin{gathered} 3.16 \\ (0.2,0.386) \\ \hline \end{gathered}$ | $\begin{gathered} 2.34 \\ (0.2,0.426) \\ \hline \end{gathered}$ | $\begin{gathered} 2.2 \\ (0.2,0.436) \\ \hline \end{gathered}$ |

Table 9.: Out-of-control performance of the D-SN-C EWMA chart versus several parametric control charts when the underling distribution is the Normal for $n=\{5,20,30\}$


Table 10.: Performance comparisons between the Shewhart and EWMA Sign charts for dispersion when $n=20$ using (13)

| case | $\tau=0.5$ | $\tau=0.75$ | $\tau=0.95$ | $\tau=1.25$ | $\tau=1.5$ | $\tau=1.75$ | $\tau=1.95$ | $\tau=2.0$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | 32.90 | -80.88 | -77.24 | -70.16 | -45.00 | -25.53 | -21.05 | -15.33 |
| 2 | 3.51 | -79.62 | -65.92 | -64.73 | -40.19 | -18.29 | -14.44 | -6.71 |
| 3 | -14.29 | -79.92 | -59.70 | -64.97 | -43.44 | -18.15 | -10.04 | 1.03 |
| 4 | 39.46 | -79.93 | -79.22 | -72.06 | -47.43 | -27.41 | -22.01 | -15.97 |
| 5 | -0.41 | -79.28 | -64.57 | -64.06 | -40.54 | -16.48 | -12.69 | -4.65 |
| 6 | -22.19 | -80.09 | -57.02 | -66.05 | -46.22 | -21.05 | -11.97 | -0.46 |
| 7 | 37.93 | -79.43 | -81.17 | -73.16 | -48.49 | -28.64 | -22.84 | -16.44 |
| 8 | -29.65 | -80.37 | -54.84 | -67.48 | -49.64 | -25.30 | -15.65 | -3.27 |
| 9 | -35.89 | -79.89 | -52.17 | -68.64 | -52.85 | -30.71 | -21.13 | -8.66 |

Table 11.: Performance comparisons in terms of the $\mathrm{ARL}_{1}$ values between the ACEWMA and D-SN-C EWMA charts for when $n=10$

D-SN-C EWMA AC-EWMA D-SN-C EWMA AC-EWMA

| $\tau$ |  | Normal |  | Double Exponential |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  |  |
| 1 | 370.4 | 370.50 |  | 370.4 | 370.50 |
| 1.2 | 17.64 | 46.52 |  | 30.69 | 18.50 |
| 1.4 | 6.62 | 12.06 |  | 10.62 | 17.10 |
| 1.6 | 4.25 | 7.60 |  | 6.30 | 16.10 |
| 1.8 | 3.28 | 5.42 |  | 4.61 | 9.80 |
| 2 | 2.77 | 4.37 |  | 3.74 | 5.30 |
| 2.2 | 2.47 | 3.76 |  | 3.22 | 4.80 |
| 2.4 | 2.26 | 3.38 |  | 2.87 | 4.40 |
| 2.6 | 2.12 | 3.13 |  | 2.63 | 3.70 |
| 2.8 | 2.01 | 2.97 |  | 2.45 | 3.40 |
| 3 | 1.93 | 2.85 |  | 2.31 | 3.10 |

Table 12.: Values of $\mathrm{SD}_{t}, \mathrm{SD}_{t}^{*}, Z_{t}^{*}$ of each subgroups for the two scenarios

| Subgroup | scenario plotted in Figure 4 |  |  | $\underline{\text { scenario plotted in Figure } 5}$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | $\mathrm{SD}_{t}$ | $\mathrm{SD}_{t}^{*}$ | $Z_{t}^{*}$ | $\mathrm{SD}_{t}$ | $\mathrm{SD}_{t}^{*}$ | $Z_{t}^{*}$ |
| 1 | -5 | -5.023 | -4.631 | -3 | -3.148 | -0.787 |
| 2 | -5 | -4.784 | -4.669 | -1 | -0.777 | -0.785 |
| 3 | -5 | -4.816 | -4.706 | 3 | 2.522 | 0.042 |
| 4 | -3 | -2.952 | -4.267 | 1 | 1.375 | 0.375 |
| 5 | -5 | -5.137 | -4.485 | 1 | 0.747 | 0.468 |
| 6 | -5 | -5.047 | -4.625 | 1 | 1.078 | 0.621 |
| 7 | -5 | -5.130 | -4.752 | 5 | 5.146 | 1.752 |
| 8 | -5 | -4.806 | -4.765 | -3 | -2.942 | 0.578 |
| 9 | -5 | -5.109 | -4.851 | 1 | 0.944 | 0.670 |
| 10 | -3 | -3.271 | -4.456 | 3 | 3.107 | 1.279 |
| 11 | -5 | -4.958 | -4.581 | 1 | 1.182 | 1.255 |
| 12 | -5 | -4.820 | -4.641 | -3 | -3.028 | 0.184 |
| 13 | -3 | -2.773 | -4.174 | 3 | 3.020 | 0.893 |
| 14 | -5 | -5.028 | -4.388 | 1 | 1.037 | 0.929 |
| 15 | -3 | -2.857 | -4.005 | 5 | 5.050 | 1.959 |
| 16 | -5 | -5.274 | -4.322 | 3 | 3.345 | 2.306 |
| 17 | -5 | -5.194 | -4.540 | 1 | 0.893 | 1.952 |
| 18 | -5 | -5.212 | -4.708 | 3 | 2.997 | 2.214 |
| 19 | -5 | -4.823 | -4.737 | -1 | -1.235 | 1.351 |
| 20 | -5 | -4.951 | -4.790 | 1 | 0.448 | 1.126 |
| 21 | -1 | -0.563 | -3.733 | -3 | -3.037 | 0.085 |
| 22 | -3 | -3.125 | -3.581 | -5 | -4.742 | -1.122 |
| 23 | -3 | -3.179 | -3.481 | 1 | 1.081 | -0.571 |
| 24 | -3 | -2.744 | -3.296 | -5 | -5.418 | -1.783 |
| 25 | -1 | -0.938 | -2.707 | -5 | -4.948 | -2.574 |
| 26 | -1 | -0.996 | -2.279 | -5 | -5.247 | -3.242 |
| 27 | 1 | 0.907 | -1.483 | -1 | -1.121 | -2.712 |
| 28 | -1 | -0.683 | -1.283 | -5 | -5.285 | -3.355 |
| 29 | -3 | -3.576 | -1.856 | -3 | -3.095 | -3.290 |
| 30 | 1 | 1.194 | -1.093 | -3 | -3.178 | -3.262 |

