

Sensitivity analysis on numerical simulation of the weld pool shape in TIG welding

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▶ To cite this version:

Xiao-Fei Kong, Olivier Asserin, Stephane Gounand, Philippe Gilles, Jean-Michel Bergheau, et al.. Sensitivity analysis on numerical simulation of the weld pool shape in TIG welding. 9th International Conference on Trends in Welding Research, ASM, Jun 2012, Chicago (Illinois), United States. hal-04108154

HAL Id: hal-04108154 https://hal.science/hal-04108154

Submitted on 30 May 2023 $\,$

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Xiaofei KONG, Olivier ASSERIN, Stéphane GOUNAND, Philippe GILLES, Jean-Michel BERGHEAU et Marc MEDALE

9th International Trends in Welding Research Conference

08 June 2012



Introduction

Model

Physical model Mathematical model Numerical model

Results and analyses Influence of the free surface Numerical sensitivity

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Contexts and challenges



The TIG welding in the nuclear industry

- Assembly of the nuclear components with large thickness by TIG welding
- Ensure quality and reliability of the weldment

Benefits of the simulation of welding

- Welding process design,
- Prediction of the deformations and the residual stresses, interpretation of the technological test,
- Help in understanding the limiting factors in the welding,
- Reduce the number of experiments.



3D Simulation of the weld pool for the TIG welding taking into account the free surface and the welding speed, and with the filler metal in the next step.

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Physical phenomena in the weld pool





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Importance of the various forces

Quantity of power :

Power of the Marangoni force : ∫_Γ F_{Marangoni} · u dΓ ≈ 10⁻⁴ W
Power of the arc drag force : ∫_Γ F_{Arc_drag} · u dΓ ≈ 10⁻⁴ W
Power of the Lorentz force : ∫_Ω F_{Lorentz} · u dΩ ≈ 10⁻⁵ W
Power of the Buoyancy force : ∫_Ω F_{Buoyancy} · u dΩ ≈ 10⁻⁷ ∽ 10⁻⁶ W

$$\begin{array}{l} \mbox{Main forces}: F_{Marangoni} \mbox{ and } F_{Arc_drag} \\ \hline P_{Arc_drag} \\ \hline P_{Marangoni} \mbox{ } \approx 1, \ \hline P_{Lorentz} \\ \hline P_{Marangoni} \mbox{ } \approx 0.1, \ \hline P_{Buoyancy} \\ \hline P_{Marangoni} \mbox{ } \approx 0.01. \end{array}$$

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Developed Model

Hypothesis

- A laminar, Newtonian fluid of the liquid metal and a stationary state
- Boussinesq approximation
- Free surface of the weld pool
- Variation of $\frac{\partial \gamma}{\partial T}$ and thermophysical properties depending on temperature
- The constant speed v_s of welding, the equation solved in a reference frame moving with the heat source

Effect not modelled

- Lorentz force
- Metal evaporation

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Conservation equations and boundary conditions

- Continuity $\nabla \cdot \mathbf{v} = \mathbf{0}$
- Momentum : $\rho(\nabla \mathbf{v}).(\mathbf{v} \mathbf{v}_s) + \nabla p \nabla.\mu(\nabla \mathbf{v} + \nabla^T \mathbf{v}) = \mathbf{f}_{\mathsf{Buoyancy}} + \mathbf{f}_{\mathsf{Extinction}}$
- Energy : $\rho c_{\rho}(\nabla h).(\mathbf{v} \mathbf{v}_{s}) = \nabla . \lambda \nabla T$



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Hybrid approach 2D axisymmetric arc model + 3D weld pool model

2D arc model provides the arc source



Radial evolution of the pressure of the arc







Radial evolution of the arc drag force

Radial evolution of the heat source



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Two different simulations : with and without free surface



Calculated weld pool without free surface

Calculated weld pool with free surface

Model	$\begin{array}{c} T_{max} \\ (K) \end{array}$	$\begin{array}{c} u_{max} \\ (m.s^{-1}) \end{array}$			$\begin{array}{c} \text{Width} \\ (mm) \end{array}$	$\begin{array}{c} \text{Depth} \\ (mm) \end{array}$	Volume (mm^3)
With free surface Without free surface	$2486 \\ 2706$	$0.31 \\ 0.18$	0.32 0.23	$0.15 \\ 0.06$	$3.60 \\ 3.60$	$2.36 \\ 1.50$	$70.6 \\ 51.7$

Weld pool characteristics with and without free surface

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Influence of the free surface on the temperature field of the bottom surface



With free surface

Temperature field with and without free surface

Difference of the temperature field on the bottom surface

- $\Delta T_{max} = 135 \ ^{\circ}C$
- The weld pool length is larger in the model with free surface

5.3

Comparison between the simulation and the experiment

Welding torch			workpiece IR camera
Current	Voltage	Arc length	Welding speed
(A)	(V)	(mm)	(mm/s)
150	10	2	2.5



• The calculated penetration and weld shape in the model with free surface agree well with the experiment.

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Design of numerical experiments

Tests	Pressure (Pa)	Heat flux (W)	Welding speed (mm/s)
1	326	1021	2
2	407	1021	2
3	326	1276	2
4	326	1276	2.5
5	407	1021	2.5
6	407	1276	2
7	407	1276	2.5
8	326	1021	2.5

Regression model for the sensitivity analysis

- $y = a_1 + a_2 X_P + a_3 X_F + a_4 X_V + a_5 X_P X_F + a_6 X_P X_V + a_7 X_F X_V + a_8 X_P X_F X_V$
- y the response, X_p, X_F, X_V the factors (pressure, heat flux and welding speed).

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Contributions of the different factors

Factors	Penetration P	Width <i>L</i>	P/L	Volume of the pool
X _P	54.01	0.06	92.62	3.80
X_F	42.00	79.26	2.7	64.91
X_{ν}	2.41	20.49	2.7	8.79
$X_P X_F$	0,13	0,06	0.06	6.00
$X_P X_V$	0.02	0.06	0.06	6.30
$X_F X_v$	0,33	0,00	0.50	2.50
$X_P X_F X_V$	1.11	0,06	1.38	7.69

- Trends consistent with those of the literature,
- In progress : validation of the model by correlations with the corresponding experimental tests.



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Conclusions and perspectives

Conclusions :

- The model taking into account the free surface predicts better the weld pool shape than the model without the free surface,
- Numerical sensitivity analysis of the influence of the free surface, the welding speed, the heat flux and the quantity of sulfur composition.

Perspectives :

- Simulation of the metal evaporation,
- Simulation of the filler metal.

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Thank you for your attention !