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MULTI-DOMAIN FEM-BEM COUPLING FOR ACOUSTIC SCATTERING

MARCELLA BONAZZOLI AND XAVIER CLAEYS

ABSTRACT. We model time-harmonic acoustic scattering by an object composed of piece-wise homogeneous parts and an arbitrarily heterogeneous part. We propose and analyze new formulations that couple, adopting a Costabel-type approach, boundary integral equations for the homogeneous subdomains with domain variational formulations for the heterogeneous subdomain. This is an extension of Costabel FEM-BEM coupling to a multi-domain configuration, with cross-points allowed, i.e. points where three or more subdomains abut. While generally just the exterior unbounded subdomain is treated with the BEM, here we wish to exploit the advantages of BEM whenever it is applicable, that is, for all the homogeneous parts of the scattering object. Our formulation is based on the multi-trace formalism, which initially was introduced for acoustic scattering by piece-wise homogeneous objects; here we allow the wavenumber to vary arbitrarily in a part of the domain. We prove that the bilinear form associated with the proposed formulation satisfies a Gårding coercivity inequality, which ensures stability of the variational problem if it is uniquely solvable. We identify conditions for injectivity and construct modified versions immune to spurious resonances.

1. INTRODUCTION

The efficient simulation of wave propagation problems in time-harmonic regime remains a computational challenge that is still the subject of intensive research effort. Propagation media are generally heterogeneous, which is reflected by arbitrarily varying coefficients in the equations. Classical numerical methods to perform simulations in heterogeneous media usually rely on volume-type discretization schemes such as finite elements. In many situations of practical relevance, material coefficients are piece-wise constant in certain parts of the computational domain, and this feature can be exploited to reformulate the problem by means of boundary integral operators as an equation defined only on the boundary, called Boundary Integral Equation (BIE). Indeed, boundary element methods, which are discretization schemes for BIEs, yield a significant reduction in the number of unknowns, higher accuracy at least away from the boundary, and better robustness to high frequency compared with finite elements. In addition, boundary integral operators can naturally deal with unbounded domains, provided that the boundary is bounded.

This is the general idea of Finite Element Method - Boundary Element Method (FEM-BEM) coupling, which aims at taking advantage of the versatility of the finite element method and the computational efficiency of the boundary element method. There already exists a well established literature on the numerical analysis

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of FEM-BEM coupling, in particular for time-harmonic acoustic problems, with several possible FEM-BEM strategies including the Johnson-Nédélec coupling [14], the Bielak-McCamy coupling [3] or the symmetric Costabel coupling [11, 12]; see e.g. [1] for an overview of the three approaches. Another possible strategy relies on substructuring domain decomposition and FETI-BETI methods [15, 2, 20, 6]. In the present contribution, we wish to focus on the Costabel coupling, which appears interesting from a numerical analysis perspective because it naturally leads to Gårding coercivity estimates.

Except for those related to domain decomposition, many of the contributions dedicated to FEM-BEM coupling consider a simple geometric configuration where the computational domain is subdivided into two parts separated by a single interface: one interior heterogeneous part and one exterior homogeneous part. Multi-domain configurations involving more than two subdomains are also of interest, most of which involve the presence of cross-points, i.e. points where three subdomains or more are adjacent. In the present contribution, we design and analyze FEM-BEM formulations in multi-domain configurations potentially involving the presence of cross-points by means of the Multi-Trace Formalism (MTF), introduced in [7, 9, 8] for piece-wise constant coefficients. Indeed, MTF allows for a clean treatment of cross-points from the perspective of function spaces, and proves here to be perfectly fitted to the Costabel coupling, leading to FEM-BEM formulations satisfying Gårding inequalities and thus to stability and quasi-optimal convergence results of conforming discretization methods.

This article is organized as follows. First, we present the acoustic scattering transmission problem in Section 2, we recall the definitions of trace spaces and operators in Section 3, and classical results of potential and boundary integral operator theory in Section 4. Then in Section 5 we introduce a functional setting suited for the multi-domain configuration. After revisiting the classical Costabel coupling in Section 6 for two subdomains, in Section 7 we propose a first multi-domain coupling formulation, called single-trace FEM-BEM formulation, followed by a combined field version in Section 8 that is immune to spurious resonances. The single-trace FEM-BEM formulation is preparatory to the more flexible multi-trace FEM-BEM formulation, which is derived and analyzed in Section 9. Finally, a multi-trace combined field FEM-BEM formulation is designed in Section 10.

2. THE TRANSMISSION PROBLEM

We start by presenting in detail the problem under study. We consider a non-overlapping domain decomposition

$$(2.1) \quad \mathbb{R}^d = \overline{\Omega}_\Sigma \cup \overline{\Omega}_0 \cup \dots \cup \overline{\Omega}_n,$$

where each subdomain will only be assumed Lipschitz regular [17, Def. 3.28] and connected, and all subdomains except Ω_0 are bounded. In addition, $\mathbb{R}^d \setminus \overline{\Omega}_\Sigma$ will also be assumed connected (so that Ω_Σ does not contain any hole). An example of such a configuration is given in Figure 1. We emphasize that in such a geometrical setting the presence of cross-points (red points in Figure 1) is allowed.

We consider a wave propagation problem where the characteristics of the propagation medium are described by a function $\kappa: \mathbb{R}^d \rightarrow \mathbb{R}_+$ modelling an effective wavenumber that varies in accordance with the above subdomain decomposition:

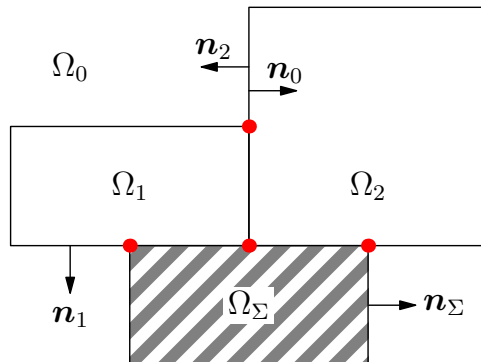


FIGURE 1. Example of geometric setting: composite medium with Ω_Σ arbitrarily heterogeneous. Cross-points (red dots) are allowed.

we assume that

$$\begin{aligned} \kappa(\mathbf{x}) &= \kappa_j \quad \forall \mathbf{x} \in \Omega_j, \quad j = 0 \dots n, \\ &\text{with } \kappa_j \in (0, +\infty). \end{aligned}$$

On the contrary, in the subdomain Ω_Σ the wavenumber $\kappa(\mathbf{x}) = \kappa_\Sigma(\mathbf{x})$ is not assumed constant and may vary, with $\kappa(\mathbf{x}) > 0 \quad \forall \mathbf{x} \in \Omega_\Sigma$.

Let the incident field $U_{\text{inc}} \in H_{\text{loc}}^1(\mathbb{R}^d)$ satisfy $\Delta U_{\text{inc}} + \kappa_0^2 U_{\text{inc}} = 0$ in \mathbb{R}^d , and let $f \in L^2(\mathbb{R}^d)$ be supported in Ω_Σ . We are interested in solving the following problem modelling a wave propagating in a heterogeneous medium

$$(2.2) \quad \begin{aligned} &\text{Find } U \in H_{\text{loc}}^1(\mathbb{R}^d) \text{ such that} \\ &\Delta U + \kappa^2 U = -f \quad \text{in } \mathbb{R}^d \\ &U - U_{\text{inc}} \text{ is } \kappa_0\text{-outgoing radiating.} \end{aligned}$$

In this problem, the third condition refers to the classical Sommerfeld radiation condition, see e.g. [19, §2.6.5]: any function V is said to be k -outgoing radiating if $\lim_{\rho \rightarrow \infty} \int_{\partial B_\rho} |\partial_\rho V - \imath k V|^2 d\sigma_\rho = 0$, where $\imath = \sqrt{-1}$, B_ρ is the ball centered at the origin of radius ρ and ∂_ρ denotes the radial derivative. By standard results of scattering theory, Problem (2.2) admits a unique solution, see e.g. [10, 17, 16].

To solve such a problem, a standard numerical approach would rely on finite elements. The computational efficiency could be improved by taking advantage of the piece-wise constant material characteristics in the subdomains Ω_j . In the present contribution, we wish to develop a multi-domain FEM-BEM coupling strategy, where the wave equation is treated by means of boundary integral operators in those parts of the computational domain where material characteristics are constant. Compared to most of the existing literature on FEM-BEM coupling, an important novelty in the present contribution lies in providing a rigorous analysis also in the presence of cross-points. Let us introduce notations for boundaries and interfaces:

$$(2.3) \quad \Gamma_j := \partial\Omega_j, \quad \Sigma := \partial\Omega_\Sigma, \quad \Gamma := \cup_{j=0}^n \Gamma_j \text{ (the "skeleton").}$$

The first step toward a multi-domain FEM-BEM formulation of boundary value problem (2.2) consists in decomposing the wave equation according to (2.1), and

imposing transmission conditions at interfaces:

$$\begin{aligned}
(2.4) \quad & \Delta U + \kappa_\Sigma^2(\mathbf{x})U = -f \quad \text{in } \Omega_\Sigma \\
& \Delta U + \kappa_j^2 U = 0 \quad \text{in } \Omega_j \\
& U|_{\Gamma_j} - U|_{\Gamma_k} = 0 \\
& \partial_{\mathbf{n}_j} U|_{\Gamma_j} + \partial_{\mathbf{n}_k} U|_{\Gamma_k} = 0 \\
& U|_{\Gamma_j} - U|_\Sigma = 0 \\
& \partial_{\mathbf{n}_j} U|_{\Gamma_j} + \partial_{\mathbf{n}_\Sigma} U|_\Sigma = 0 \\
& U - U_{\text{inc}} \text{ is } \kappa_0\text{-outgoing radiating.}
\end{aligned}$$

Here, all traces are taken from the interior of subdomains, and $\mathbf{n}_j, j = 0 \dots n$ (resp. \mathbf{n}_Σ) are the unit normal vector fields on Γ_j directed toward the exterior of Ω_j (resp. Ω_Σ); Neumann traces are defined by $\partial_{\mathbf{n}_j} U|_{\Gamma_j} := \mathbf{n}_j \cdot \nabla U|_{\Gamma_j}$ (resp. $\partial_{\mathbf{n}_\Sigma} U|_\Sigma := \mathbf{n}_\Sigma \cdot \nabla U|_\Sigma$).

3. TRACE SPACES AND OPERATORS

Discussing transmission conditions requires paying thorough attention to function spaces, trace spaces and operators. In all this section, Ω refers to a generic Lipschitz domain that is either bounded or such that $\mathbb{R}^d \setminus \bar{\Omega}$ is bounded, and \mathbf{n}_Ω is the unit normal vector field on $\partial\Omega$ systematically directed toward the exterior of Ω .

First of all, we use classical notations for the following elementary functional spaces of volume functions:

$$\begin{aligned}
(3.1) \quad & \mathbf{H}^1(\Omega) := \{ V \in L^2(\Omega) \mid \nabla V \in L^2(\Omega) \}, \\
& \mathbf{H}(\text{div}, \Omega) := \{ \mathbf{v} \in L^2(\Omega)^d \mid \text{div}(\mathbf{v}) \in L^2(\Omega) \}, \\
& \mathbf{H}^1(\Delta, \Omega) := \{ V \in \mathbf{H}^1(\Omega) \mid \Delta V \in L^2(\Omega) \}.
\end{aligned}$$

They are equipped with their canonical norms $\|V\|_{\mathbf{H}^1(\Omega)}^2 := \|V\|_{L^2(\Omega)}^2 + \|\nabla V\|_{L^2(\Omega)}^2$, $\|\mathbf{v}\|_{\mathbf{H}(\text{div}, \Omega)}^2 := \|\mathbf{v}\|_{L^2(\Omega)^d}^2 + \|\text{div}(\mathbf{v})\|_{L^2(\Omega)}^2$, and $\|V\|_{\mathbf{H}^1(\Delta, \Omega)}^2 := \|V\|_{\mathbf{H}^1(\Omega)}^2 + \|\Delta V\|_{L^2(\Omega)}^2$. With these norms, the spaces (3.1) admit a Hilbert structure. If $\mathbf{H}(\Omega)$ is any of the spaces above, we set $\mathbf{H}_{\text{loc}}(\bar{\Omega}) := \{ V \mid \varphi V \in \mathbf{H}(\Omega) \forall \varphi \in \mathcal{C}_c^\infty(\mathbb{R}^d) \}$, where $\mathcal{C}_c^\infty(\mathbb{R}^d)$ is the space of \mathcal{C}^∞ functions with compact support.

We introduce the *interior Dirichlet trace operator* γ_{D}^Ω and the *interior Neumann trace operator* γ_{N}^Ω , defined for smooth functions $\varphi \in \mathcal{C}^\infty(\mathbb{R}^d)$ by

$$\begin{aligned}
\gamma_{\text{D}}^\Omega(\varphi) &:= \varphi|_{\partial\Omega}, \\
\gamma_{\text{N}}^\Omega(\varphi) &:= \mathbf{n}_\Omega \cdot \nabla \varphi|_{\partial\Omega}.
\end{aligned}$$

These definitions are extended by density and continuity to trace operators $\gamma_{\text{D}}^\Omega : \mathbf{H}_{\text{loc}}^1(\bar{\Omega}) \rightarrow \mathbf{H}^{1/2}(\partial\Omega)$, $\gamma_{\text{N}}^\Omega : \mathbf{H}_{\text{loc}}^1(\Delta, \bar{\Omega}) \rightarrow \mathbf{H}^{-1/2}(\partial\Omega)$, where the Dirichlet trace space $\mathbf{H}^{1/2}(\partial\Omega)$ is defined as the completion of $\{\varphi|_{\partial\Omega}, \varphi \in \mathcal{C}^\infty(\mathbb{R}^d)\}$ with respect to the Slobodeckii norm (see e.g. [17, Chap. 2])

$$\|\varphi\|_{\mathbf{H}^{1/2}(\partial\Omega)}^2 := \int_{\partial\Omega \times \partial\Omega} \frac{|\varphi(\mathbf{x}) - \varphi(\mathbf{y})|^2}{|\mathbf{x} - \mathbf{y}|^d} d\sigma(\mathbf{x}, \mathbf{y}),$$

and the Neumann trace space $H^{-1/2}(\partial\Omega)$ is the dual space of $H^{1/2}(\partial\Omega)$. The corresponding duality pairing will be denoted by $\langle p, v \rangle_{\partial\Omega} \equiv \langle v, p \rangle_{\partial\Omega} := p(v)$ for $v \in H^{1/2}(\partial\Omega)$ and $p \in H^{-1/2}(\partial\Omega)$, and we shall take

$$\|p\|_{H^{-1/2}(\partial\Omega)} := \sup_{v \in H^{1/2}(\partial\Omega) \setminus \{0\}} \frac{|\langle p, v \rangle_{\partial\Omega}|}{\|v\|_{H^{1/2}(\partial\Omega)}}$$

as norm for the Neumann trace space. We also introduce operators and spaces for *pairs* of Dirichlet and Neumann traces, defined by $\gamma^\Omega(V) := (\gamma_D^\Omega(V), \gamma_N^\Omega(V))$ and

$$(3.2) \quad \begin{aligned} \gamma^\Omega &:= (\gamma_D^\Omega, \gamma_N^\Omega): H^1(\Delta, \bar{\Omega}) \rightarrow \mathbb{H}(\partial\Omega) \quad \text{where} \\ \mathbb{H}(\partial\Omega) &:= H^{1/2}(\partial\Omega) \times H^{-1/2}(\partial\Omega). \end{aligned}$$

In contrast with Dirichlet and Neumann trace operators $\gamma_D^\Omega, \gamma_N^\Omega$, the trace operator γ^Ω is not really standard, but we shall use it abundantly for much more compact notation in our subsequent analysis. The space of pairs of Dirichlet-Neumann traces $\mathbb{H}(\partial\Omega)$ will be equipped with the Cartesian product norm $\|(v, q)\|_{\mathbb{H}(\partial\Omega)}^2 := \|v\|_{H^{1/2}(\partial\Omega)}^2 + \|q\|_{H^{-1/2}(\partial\Omega)}^2$. It is put in duality with itself through the following bilinear pairing

$$(3.3) \quad [(u, p), (v, q)]_{\partial\Omega} := \langle u, q \rangle_{\partial\Omega} - \langle p, v \rangle_{\partial\Omega}$$

for all $(u, p), (v, q) \in \mathbb{H}(\partial\Omega)$. We underline that no complex conjugation comes into play in this definition. Note that throughout the paper Dirichlet traces are denoted by u, v, w and Neumann traces by p, q, r , while capital letters like U, V are used to indicate scalar functions on volume domains, and small bold letters like $\mathbf{v}, \mathbf{p}, \mathbf{q}$ are used for vector fields. In this section and the following one, we use gothic symbols $\mathbf{u}, \mathbf{v}, \mathbf{w}$ to denote pairs of Dirichlet-Neumann traces, that is elements of $\mathbb{H}(\partial\Omega)$. We have the inequality $\|[\mathbf{u}, \mathbf{v}]_{\partial\Omega}\| \leq \|\mathbf{u}\|_{\mathbb{H}(\partial\Omega)} \|\mathbf{v}\|_{\mathbb{H}(\partial\Omega)}$ for all $\mathbf{u}, \mathbf{v} \in \mathbb{H}(\partial\Omega)$.

Setting $\theta(v, q) := (-v, q)$, we state simple identities that will be used several times in the following: for all $\mathbf{u} = (u, p), \mathbf{v} = (v, q) \in \mathbb{H}(\partial\Omega)$

$$(3.4) \quad [\mathbf{u}, \theta(\mathbf{v})]_{\partial\Omega} = \langle u, q \rangle_{\partial\Omega} + \langle p, v \rangle_{\partial\Omega},$$

$$(3.5) \quad [\mathbf{u}, \theta(\mathbf{v})]_{\partial\Omega} - [\mathbf{u}, \mathbf{v}]_{\partial\Omega} = 2\langle p, v \rangle_{\partial\Omega},$$

$$(3.6) \quad [\mathbf{u}, \theta(\mathbf{v})]_{\partial\Omega} + [\mathbf{u}, \mathbf{v}]_{\partial\Omega} = 2\langle u, q \rangle_{\partial\Omega}.$$

Together with the operators $\gamma_D^\Omega, \gamma_N^\Omega, \gamma^\Omega$, for which traces are taken from the interior of the domain Ω , similar operators can be defined for traces taken from the *exterior* of Ω , and will be denoted by

$$\begin{aligned} \gamma_{D,c}^\Omega &: H_{\text{loc}}^1(\mathbb{R}^d \setminus \Omega) \rightarrow H^{1/2}(\partial\Omega), \\ \gamma_{N,c}^\Omega &: H_{\text{loc}}^1(\Delta, \mathbb{R}^d \setminus \Omega) \rightarrow H^{-1/2}(\partial\Omega), \\ \gamma_c^\Omega &:= (\gamma_{D,c}^\Omega, \gamma_{N,c}^\Omega): H_{\text{loc}}^1(\Delta, \mathbb{R}^d \setminus \Omega) \rightarrow \mathbb{H}(\partial\Omega). \end{aligned}$$

When considering the trace operator $\gamma_{N,c}^\Omega$, the normal vector is still directed toward the exterior of Ω . Finally, we will also need to form *jump and average traces*:

$$(3.7) \quad [\gamma^\Omega] := \gamma^\Omega - \gamma_c^\Omega, \quad \{\gamma^\Omega\} := (\gamma^\Omega + \gamma_c^\Omega)/2.$$

In the context of the multi-domain configuration (2.3), for the sake of brevity, we shall write γ_D^j (resp. $\gamma_N^j, \gamma^j, \gamma_{D,c}^j, \gamma_{N,c}^j, \gamma_c^j$) instead of $\gamma_D^{\Omega_j}$ (resp. $\gamma_N^{\Omega_j}, \gamma^{\Omega_j}, \gamma_{D,c}^{\Omega_j}, \gamma_{N,c}^{\Omega_j}, \gamma_c^{\Omega_j}$). We shall adopt a similar convention for traces on Σ , writing γ_*^Σ instead of $\gamma_*^{\Omega_\Sigma}$ with $*$ = D, N and so on.

4. REVIEW OF POTENTIAL AND BOUNDARY INTEGRAL OPERATORS

In this section, setting compact notations, we recall classical results related to boundary integral formulations for the Helmholtz equation in Lipschitz domains. For more details and proofs refer for instance to [21, Chap. 3]. As in the previous section, we introduce these notations for a generic domain Ω (either bounded or the complement of a bounded domain).

Let the function $\mathcal{G}_\kappa: \mathbb{R}^d \setminus \{0\} \rightarrow \mathbb{C}$ be the κ -outgoing radiating fundamental solution or Green kernel for the Helmholtz operator $-\Delta - \kappa^2$, for a given constant wavenumber κ . In particular for $\mathbb{R}^d = \mathbb{R}^3$ we have $\mathcal{G}_\kappa(\mathbf{x}) = \exp(i\kappa|\mathbf{x}|)/(4\pi|\mathbf{x}|)$. For any $\mathbf{x} \in \mathbb{R}^d \setminus \partial\Omega$, and any $\mathbf{v} = (v, q) \in \mathbb{H}(\partial\Omega)$, define *potential operators*¹

$$\begin{aligned} \text{SL}_\kappa^\Omega(q)(\mathbf{x}) &:= \int_{\partial\Omega} q(\mathbf{y}) \mathcal{G}_\kappa(\mathbf{x} - \mathbf{y}) d\sigma(\mathbf{y}), \\ \text{DL}_\kappa^\Omega(v)(\mathbf{x}) &:= \int_{\partial\Omega} v(\mathbf{y}) \mathbf{n}_\Omega(\mathbf{y}) \cdot (\nabla \mathcal{G}_\kappa)(\mathbf{x} - \mathbf{y}) d\sigma(\mathbf{y}) \\ &= - \int_{\partial\Omega} v(\mathbf{y}) \mathbf{n}_\Omega(\mathbf{y}) \cdot \nabla_{\mathbf{y}}(\mathcal{G}_\kappa(\mathbf{x} - \mathbf{y})) d\sigma(\mathbf{y}), \\ \mathbf{G}_\kappa^\Omega(\mathbf{v})(\mathbf{x}) &:= \text{DL}_\kappa^\Omega(v)(\mathbf{x}) + \text{SL}_\kappa^\Omega(q)(\mathbf{x}), \end{aligned}$$

where the first two operators are called single and double layer potentials. The total potential \mathbf{G}_κ^Ω maps continuously $\mathbb{H}(\partial\Omega)$ into² $\text{H}_{\text{loc}}^1(\Delta, \overline{\Omega}) \times \text{H}_{\text{loc}}^1(\Delta, \mathbb{R}^d \setminus \Omega)$ (see [21, Thm. 3.1.16]), so that the traces of $\mathbf{G}_\kappa^\Omega(\mathbf{v})$ are properly defined. This operator can be used to write a representation formula for the solution to the homogeneous Helmholtz equation in terms of the Dirichlet and Neumann traces of the solution (see [21, Thm. 3.1.6]):

Proposition 4.1 (Representation formulas). *Let $U \in \text{H}_{\text{loc}}^1(\overline{\Omega})$ satisfy $-\Delta U - \kappa^2 U = 0$ in Ω . If Ω is unbounded, assume in addition that U is κ -outgoing radiating. Then we have the representation formula*

$$(4.1) \quad \mathbf{G}_\kappa^\Omega(\gamma^\Omega(U))(\mathbf{x}) = 1_\Omega(\mathbf{x})U(\mathbf{x}).$$

Similarly, let $V \in \text{H}_{\text{loc}}^1(\mathbb{R}^d \setminus \Omega)$ satisfy $-\Delta V - \kappa^2 V = 0$ in $\mathbb{R}^d \setminus \overline{\Omega}$, as well as the Sommerfeld radiation condition if Ω is bounded. Then we have

$$(4.2) \quad \mathbf{G}_\kappa^\Omega(\gamma_c^\Omega(V))(\mathbf{x}) = -1_{\mathbb{R}^d \setminus \Omega}(\mathbf{x})V(\mathbf{x}).$$

Here, 1_Ω (resp. $1_{\mathbb{R}^d \setminus \Omega}$) is the characteristic function of Ω (resp. $\mathbb{R}^d \setminus \Omega$). In addition to the representation formulas above, the potential operator \mathbf{G}_κ^Ω satisfies the so-called *jump relations* [21, Thm. 3.3.1], which describe the relationship between interior and exterior traces of \mathbf{G}_κ^Ω . Here we express these relations through the following synthetic identity

$$(4.3) \quad [\gamma^\Omega] \circ \mathbf{G}_\kappa^\Omega = \text{Id},$$

¹Note that the choice of sign in the double layer potential differs from the one usually adopted in the literature, in order to maintain symmetry in the definition of \mathbf{G}_κ^Ω (and consequently in the representation formula).

²Here we consider that $V \in \text{H}_{\text{loc}}^1(\Delta, \overline{\Omega}) \times \text{H}_{\text{loc}}^1(\Delta, \mathbb{R}^d \setminus \Omega)$ if and only if $V|_\Omega \in \text{H}_{\text{loc}}^1(\Delta, \overline{\Omega})$ and $V|_{\mathbb{R}^d \setminus \overline{\Omega}} \in \text{H}_{\text{loc}}^1(\Delta, \mathbb{R}^d \setminus \Omega)$.

where Id is the identity map in $\mathbb{H}(\partial\Omega)$ and the jump $[\cdot]$ is defined in (3.7). Any $U = \mathbf{G}_\kappa^\Omega(\mathbf{u})$ for $\mathbf{u} \in \mathbb{H}(\partial\Omega)$ is a κ -outgoing radiating solution to the homogeneous Helmholtz equation in Ω with wavenumber κ , hence we can apply to it the representation formula (4.1). Taking the interior traces of this formula leads to $\gamma^\Omega \circ \mathbf{G}_\kappa^\Omega(\gamma^\Omega \circ \mathbf{G}_\kappa^\Omega(\mathbf{u})) = \gamma^\Omega \circ \mathbf{G}_\kappa^\Omega(\mathbf{u})$ and since \mathbf{u} was chosen arbitrarily in $\mathbb{H}(\partial\Omega)$, this finally rewrites

$$(4.4) \quad (\gamma^\Omega \circ \mathbf{G}_\kappa^\Omega)^2 = (\gamma^\Omega \circ \mathbf{G}_\kappa^\Omega)$$

which is a synthetic form of the four classical *interior Calderón identities*. The operator $\gamma^\Omega \circ \mathbf{G}_\kappa^\Omega$ is a continuous projector, called the *interior Calderón projector* of Ω . This actually provides a characterization of traces of solutions to the homogeneous Helmholtz equation, which are called Cauchy data (see [21, §3.6]):

Proposition 4.2 (Definition and characterization of Cauchy data). *We define the space of Cauchy data of Ω*

$$(4.5) \quad \mathcal{C}_\kappa(\Omega) := \{ \gamma^\Omega(U) \in \mathbb{H}(\partial\Omega) \mid U \in \mathbf{H}_{\text{loc}}^1(\overline{\Omega}), -\Delta U - \kappa^2 U = 0 \text{ in } \Omega, \\ \text{and } U \text{ is } \kappa\text{-outgoing radiating if } \Omega \text{ is unbounded} \}.$$

The range of the interior Calderón projector $\gamma^\Omega \circ \mathbf{G}_\kappa^\Omega$ coincides with $\mathcal{C}_\kappa(\Omega)$. More precisely, for any $\mathbf{u} \in \mathbb{H}(\partial\Omega)$ we have $\gamma^\Omega \circ \mathbf{G}_\kappa^\Omega(\mathbf{u}) = \mathbf{u} \iff \mathbf{u} \in \mathcal{C}_\kappa(\Omega)$.

Analogous results, obtained by taking exterior traces of the representation formula (4.2), hold for exterior Cauchy data.

Applying traces to potential operators yields *boundary integral operators*: in our compact notation we will use

$$(4.6) \quad \mathbf{A}_\kappa^\Omega := \{ \gamma^\Omega \} \circ \mathbf{G}_\kappa^\Omega,$$

where the average $\{ \cdot \}$ is defined in (3.7). The operator \mathbf{A}_κ^Ω continuously maps $\mathbb{H}(\partial\Omega)$ into $\mathbb{H}(\partial\Omega)$. It consists in a 2×2 matrix of boundary integral operators (double layer, single layer, hypersingular and adjoint double layer operators, see e.g. [21, §3.6]). We shall not need to refer individually to any of its entries during the forthcoming analysis. Simple consequences of the jump relations (4.3) are

$$(4.7) \quad \gamma^\Omega \circ \mathbf{G}_\kappa^\Omega = \mathbf{A}_\kappa^\Omega + \text{Id}/2,$$

$$(4.8) \quad \gamma_c^\Omega \circ \mathbf{G}_\kappa^\Omega = \mathbf{A}_\kappa^\Omega - \text{Id}/2.$$

So, identity (4.4) implies $(\mathbf{A}_\kappa^\Omega)^2 = \text{Id}/4$. The operator \mathbf{A}_κ^Ω for various domains Ω will play a pivotal role in the forthcoming analysis. We now recall a few facts that are well established in the literature. First, this operator satisfies a generalized Gårding inequality:

Proposition 4.3 (Generalized Gårding inequality). *Recall the operator $\theta(v, q) := (-v, q)$. There exist a compact operator $\mathcal{K}: \mathbb{H}(\partial\Omega) \rightarrow \mathbb{H}(\partial\Omega)$ and a constant $\alpha > 0$ such that for all $\mathbf{u} \in \mathbb{H}(\partial\Omega)$ we have*

$$\text{Re} \{ [(\mathbf{A}_\kappa^\Omega + \mathcal{K})\mathbf{u}, \theta(\bar{\mathbf{u}})]_{\partial\Omega} \} \geq \alpha \|\mathbf{u}\|_{\mathbb{H}(\partial\Omega)}^2.$$

Although well known (see for example [22, Thm. 3.9]), the proof of this result is instructive, so we include it in Proposition A.1 in the appendix. Next, remarkable *symmetry properties* were proved in [8, Lemma 3.6–3.7] for the operators \mathbf{A}_κ^Ω : for any $\mathbf{u}, \mathbf{v} \in \mathbb{H}(\partial\Omega)$ we have

$$[\mathbf{A}_\kappa^\Omega(\mathbf{u}), \mathbf{v}]_{\partial\Omega} = [\mathbf{A}_\kappa^\Omega(\mathbf{v}), \mathbf{u}]_{\partial\Omega}.$$

Finally, we recall a useful result about the sign of the imaginary part of the quadratic form $\mathbf{u} \mapsto [\mathbf{A}_\kappa^\Omega(\mathbf{u}), \bar{\mathbf{u}}]_{\partial\Omega}$:

Proposition 4.4. *Assume that either $\Omega \subset \mathbb{R}^d$ is bounded or $\mathbb{R}^d \setminus \Omega$ is bounded. Then for all $\mathbf{u} \in \mathbb{H}(\partial\Omega)$, we have $\text{Im}\{[\mathbf{A}_\kappa^\Omega(\mathbf{u}), \bar{\mathbf{u}}]_{\partial\Omega}\} \geq 0$.*

The proof of this result can be deduced for example from the positivity of the capacity operator stated in [19, Thm. 5.3.5]. However, since we are not able to find a definitive proof in the current literature, we provide it in Proposition A.2 in the appendix.

Once again, in the context of the multi-domain configuration (2.3), we shall write \mathbf{G}_κ^j instead of $\mathbf{G}_\kappa^{\Omega_j}$, and \mathbf{A}_κ^j instead of $\mathbf{A}_\kappa^{\Omega_j}$.

5. TRACE SPACES FOR MULTI-DOMAIN SCATTERING

Taking a cue from previous contributions about multi-trace formalism, we introduce a few notations for function spaces and traces specific to multi-domain configurations. A natural trace space on the skeleton Γ (2.3) is the *multi-trace space* defined as the Cartesian product of local trace spaces on the subdomains boundary:

$$(5.1) \quad \mathbb{H}(\Gamma) := \mathbb{H}(\Gamma_0) \times \cdots \times \mathbb{H}(\Gamma_n),$$

recalling that in (3.2) we have set $\mathbb{H}(\Gamma_j) := \mathbf{H}^{1/2}(\Gamma_j) \times \mathbf{H}^{-1/2}(\Gamma_j)$. The multi-trace space above is equipped with the Cartesian product norm defined by

$$\begin{aligned} \|\mathbf{v}\|_{\mathbb{H}(\Gamma)}^2 &:= \|\mathbf{v}_0\|_{\mathbb{H}(\Gamma_0)}^2 + \cdots + \|\mathbf{v}_n\|_{\mathbb{H}(\Gamma_n)}^2 \\ \text{for } \mathbf{v} &= (\mathbf{v}_0, \dots, \mathbf{v}_n) \in \mathbb{H}(\Gamma). \end{aligned}$$

Throughout the paper we use gothic symbols $\mathbf{u}, \mathbf{v}, \mathbf{w}$ to denote tuples of Dirichlet-Neumann traces, with a subscript indicating the pair of traces on a certain subdomain boundary. The trace operators γ^j local to subdomains can be bundled to form a *global trace operator* on the skeleton Γ

$$(5.2) \quad \gamma(U) := (\gamma^0(U), \dots, \gamma^n(U)),$$

which naturally maps continuously onto the multi-trace space $\gamma: \mathbf{H}^1(\Delta, \Omega_0) \times \cdots \times \mathbf{H}^1(\Delta, \Omega_n) \rightarrow \mathbb{H}(\Gamma)$. Moreover, the multi-trace space (5.1) is naturally equipped with the non-degenerate bilinear pairing $[\cdot, \cdot]_\Gamma: \mathbb{H}(\Gamma) \times \mathbb{H}(\Gamma) \rightarrow \mathbb{C}$ defined by

$$[\mathbf{u}, \mathbf{v}]_\Gamma := [\mathbf{u}_0, \mathbf{v}_0]_{\Gamma_0} + \cdots + [\mathbf{u}_n, \mathbf{v}_n]_{\Gamma_n}$$

$$\text{for any } \mathbf{u} = (\mathbf{u}_0, \dots, \mathbf{u}_n) \in \mathbb{H}(\Gamma),$$

$$\mathbf{v} = (\mathbf{v}_0, \dots, \mathbf{v}_n) \in \mathbb{H}(\Gamma).$$

We also need to introduce a subspace of (5.1) consisting in tuples of traces that comply with Dirichlet and Neumann transmission conditions through each interface $\Gamma_j \cap \Gamma_k$: the so-called *single-trace space* $\mathbb{X}(\Gamma) \subset \mathbb{H}(\Gamma)$ is a closed subspace of $\mathbb{H}(\Gamma)$ defined as follows

$$(5.3) \quad \begin{aligned} \mathbb{X}(\Gamma) &:= \{(u_j, p_j)_{j=0, \dots, n} \in \mathbb{H}(\Gamma) \mid \exists V \in \mathbf{H}^1(\mathbb{R}^d), \mathbf{q} \in \mathbf{H}(\text{div}, \mathbb{R}^d) \\ &\text{such that } u_j = V|_{\Gamma_j} \text{ and } p_j = \mathbf{n}_j \cdot \mathbf{q}|_{\Gamma_j} \forall j = 0, \dots, n\}. \end{aligned}$$

In contrast to other articles about multi-trace formalism such as [9, 7], Definition 5.3 for $\mathbb{X}(\Gamma)$ stems from the decomposition $\mathbb{R}^d \setminus \Omega_\Sigma = \Omega_0 \cup \cdots \cup \Omega_n$, which is *not* a partition of the full space \mathbb{R}^d , i.e. the subdomain Ω_Σ is assumed non-empty here. Because of this, the single-trace space $\mathbb{X}(\Gamma)$ obeys a modified polarity identity

involving a residual term localized on Σ . This property, stated in the following proposition, will play a crucial role in the forthcoming analysis.

Proposition 5.1 (Modified polarity identity). *For any $\mathbf{u} = (u_j, p_j)_{j=0, \dots, n} \in \mathbb{X}(\Gamma)$ stemming from the traces $u_j = V|_{\Gamma_j}$ and $p_j = \mathbf{n}_j \cdot \mathbf{q}|_{\Gamma_j}$ of some $V \in H^1(\mathbb{R}^d)$, $\mathbf{q} \in H(\text{div}, \mathbb{R}^d)$, define*

$$(5.4) \quad \mathbb{T}(\mathbf{u}) := (V|_{\Sigma}, \mathbf{n}_{\Sigma} \cdot \mathbf{q}|_{\Sigma}).$$

Then $\mathbb{T}(\mathbf{u})$ does not depend on the particular liftings V, \mathbf{q} , and the formula above defines a continuous and surjective operator $\mathbb{T}: \mathbb{X}(\Gamma) \rightarrow \mathbb{H}(\Sigma)$ satisfying the modified polarity identity

$$(5.5) \quad [\mathbf{u}, \mathbf{v}]_{\Gamma} = -[\mathbb{T}(\mathbf{u}), \mathbb{T}(\mathbf{v})]_{\Sigma} \quad \forall \mathbf{u}, \mathbf{v} \in \mathbb{X}(\Gamma).$$

This proposition was established in [8, Prop. 3.1 and Prop. 3.2]. The operator \mathbb{T} should be understood as a trace operator on Σ . Subsequently, we shall decompose the operator \mathbb{T} into Dirichlet and Neumann components, setting $\mathbb{T}(\mathbf{u}) = (\mathbb{T}_D(\mathbf{u}), \mathbb{T}_N(\mathbf{u}))$, with $\mathbb{T}_D: \mathbb{X}(\Gamma) \rightarrow H^{1/2}(\Sigma)$ and $\mathbb{T}_N: \mathbb{X}(\Gamma) \rightarrow H^{-1/2}(\Sigma)$ continuous. The modified polarity identity leads to a variational characterization of $\mathbb{X}(\Gamma)$:

Lemma 5.2 (Variational characterization of $\mathbb{X}(\Gamma)$). *For any $\mathbf{u} \in \mathbb{H}(\Gamma)$, we have $\mathbf{u} \in \mathbb{X}(\Gamma)$ if and only if $[\mathbf{u}, \mathbf{v}]_{\Gamma} = 0$ for all $\mathbf{v} \in \mathbb{X}(\Gamma)$ satisfying $\mathbb{T}(\mathbf{v}) = 0$.*

Proof. First, as a direct application of Proposition 5.1, for any $\mathbf{u} \in \mathbb{X}(\Gamma)$ and any $\mathbf{v} \in \mathbb{X}(\Gamma)$ with $\mathbb{T}(\mathbf{v}) = 0$, we have $[\mathbf{u}, \mathbf{v}]_{\Gamma} = -[\mathbb{T}(\mathbf{u}), 0]_{\Sigma} = 0$.

Reciprocally, take an arbitrary $\mathbf{u} \in \mathbb{H}(\Gamma)$, and assume that $[\mathbf{u}, \mathbf{v}]_{\Gamma} = 0$ for all $\mathbf{v} \in \mathbb{X}(\Gamma)$ satisfying $\mathbb{T}(\mathbf{v}) = 0$. Consider $U_j \in H^1(\Omega_j)$, $\mathbf{p}_j \in H(\text{div}, \Omega_j)$ such that $\mathbf{u} = (U_j|_{\Gamma_j}, \mathbf{n}_j \cdot \mathbf{p}_j|_{\Gamma_j})_{j=0, \dots, n}$, and define $U \in L^2(\mathbb{R}^d \setminus \Omega_{\Sigma})$ and $\mathbf{p} \in L^2(\mathbb{R}^d \setminus \Omega_{\Sigma})^d$ by $U|_{\Omega_j} := U_j$ and $\mathbf{p}|_{\Omega_j} := \mathbf{p}_j$.

We need to prove that $U \in H^1(\mathbb{R}^d \setminus \overline{\Omega}_{\Sigma})$ and $\mathbf{p} \in H(\text{div}, \mathbb{R}^d \setminus \overline{\Omega}_{\Sigma})$ to conclude. We prove the result only for U , since the proof proceeds in a completely analogous manner for \mathbf{p} . It suffices to show the existence of $C > 0$ such that

$$\left| \int_{\mathbb{R}^d \setminus \Omega_{\Sigma}} U \text{div}(\boldsymbol{\varphi}) \, d\mathbf{x} \right| \leq C \|\boldsymbol{\varphi}\|_{L^2(\mathbb{R}^d)} \quad \forall \boldsymbol{\varphi} \in \mathcal{C}_K^{\infty}(\mathbb{R}^d \setminus \overline{\Omega}_{\Sigma})^d,$$

where $\mathcal{C}_K^{\infty}(\mathbb{R}^d \setminus \overline{\Omega}_{\Sigma}) := \{V \in \mathcal{C}^{\infty}(\mathbb{R}^d) \mid \text{supp}(V) \text{ bounded}, V = 0 \text{ in } \Omega_{\Sigma}\}$. Pick $\boldsymbol{\varphi} \in \mathcal{C}_K^{\infty}(\mathbb{R}^d \setminus \overline{\Omega}_{\Sigma})^d$ arbitrary and set $\mathbf{v} = (0, \mathbf{n}_j \cdot \boldsymbol{\varphi}|_{\Gamma_j})_{j=0, \dots, n}$. By construction we have $\mathbf{v} \in \mathbb{X}(\Gamma)$ and $\mathbb{T}(\mathbf{v}) = 0$, since $\mathbf{n}_{\Sigma} \cdot \boldsymbol{\varphi}|_{\Sigma} = 0$. Next, decomposing the integral according to $\mathbb{R}^d \setminus \Omega_{\Sigma} = \overline{\Omega}_0 \cup \dots \cup \overline{\Omega}_n$, and using the identity $[\mathbf{u}, \mathbf{v}]_{\Gamma} = 0$, we have $\int_{\mathbb{R}^d \setminus \Omega_{\Sigma}} U \text{div}(\boldsymbol{\varphi}) \, d\mathbf{x} = \sum_{j=0}^n \int_{\Omega_j} U_j \text{div}(\boldsymbol{\varphi}) \, d\mathbf{x} = -\sum_{j=0}^n \int_{\Omega_j} \boldsymbol{\varphi} \cdot \nabla U_j \, d\mathbf{x}$, which leads to the conclusion. \square

Let us point out that any tuple $(u_j, p_j)_{j=0, \dots, n} \in \mathbb{X}(\Gamma)$ satisfies $u_j = u_k$ and $p_j = -p_k$ on $\Gamma_j \cap \Gamma_k$. This observation and Lemma 5.2 lead to alternative ways of writing the transmission conditions:

Lemma 5.3 (Characterizations of transmission conditions). *For any $U \in L_{\text{loc}}^2(\mathbb{R}^d)$ such that $U|_{\Omega_{\Sigma}} \in H_{\text{loc}}^1(\Delta, \Omega_{\Sigma})$ and $U|_{\Omega_j} \in H_{\text{loc}}^1(\Delta, \Omega_j)$, $j = 0 \dots, n$, we have that U satisfies the transmission conditions of Problem (2.4), that is, $U \in H_{\text{loc}}^1(\Delta, \mathbb{R}^d)$ if and only if*

$$(5.6) \quad \gamma(U) \in \mathbb{X}(\Gamma) \quad \text{and} \quad \mathbb{T}(\gamma(U)) = \gamma^{\Sigma}(U),$$

or equivalently

$$(5.7) \quad [\gamma(U), \mathbf{v}]_\Gamma + [\gamma^\Sigma(U), \mathbf{T}(\mathbf{v})]_\Sigma = 0 \quad \text{for all } \mathbf{v} \in \mathbb{X}(\Gamma).$$

Proof. For characterization (5.6), it is enough to combine the observation above with the definitions of \mathbf{T} in (5.4) and of the global trace operator (5.2).

Now, we prove that (5.7) is a variational reformulation of (5.6). A direct application of the modified polarity identity (5.5) shows that (5.6) implies (5.7). Conversely, suppose that (5.7) holds true. In particular, if we take $\mathbf{v} \in \mathbb{X}(\Gamma)$ with $\mathbf{T}(\mathbf{v}) = 0$, then $[\gamma(U), \mathbf{v}]_\Gamma = 0$ for all $\mathbf{v} \in \mathbb{X}(\Gamma)$ with $\mathbf{T}(\mathbf{v}) = 0$. According to Lemma 5.2, this implies that $\gamma(U) \in \mathbb{X}(\Gamma)$. Moreover, considering now a generic $\mathbf{v} \in \mathbb{X}(\Gamma)$ and applying the polarity identity (5.5) to the first term of (5.7), we get

$$-[\mathbf{T}(\gamma(U)), \mathbf{T}(\mathbf{v})]_\Sigma + [\gamma^\Sigma(U), \mathbf{T}(\mathbf{v})]_\Sigma = 0 \quad \text{for all } \mathbf{v} \in \mathbb{X}(\Gamma),$$

that yields $\mathbf{T}(\gamma(U)) = \gamma^\Sigma(U)$ because \mathbf{T} surjectively maps $\mathbb{X}(\Gamma)$ onto $\mathbb{H}(\Sigma)$. \square

This characterization of transmission conditions motivates the introduction of a variant of the single-trace space involving the additional subdomain boundary Σ :

$$(5.8) \quad \tilde{\mathbb{X}}(\Gamma) := \{ (\mathbf{u}, \mathbf{T}(\mathbf{u})) \mid \mathbf{u} \in \mathbb{X}(\Gamma) \},$$

which stems from the decomposition of the full space $\mathbb{R}^d = \bar{\Omega}_0 \cup \dots \cup \bar{\Omega}_n \cup \bar{\Omega}_\Sigma$ as in [7]. With this space we can rephrase once more: U satisfies the transmission conditions of Problem (2.4) if and only if $(\gamma(U), \gamma^\Sigma(U)) \in \tilde{\mathbb{X}}(\Gamma)$.

Remark 5.4. A crucial procedure to construct an element of $\tilde{\mathbb{X}}(\Gamma)$ is the following. Given j and a function $V \in H^1_{\text{loc}}(\Delta, \mathbb{R}^d \setminus \Omega_j)$, we set $\mathbf{v}_k = \gamma^k(V)$ for $k \neq j$, $\mathbf{v}_j = \gamma^j_c(V)$ and $\mathbf{v}_\Sigma = \mathbf{T}(\mathbf{v}) = \gamma^\Sigma(V)$; then $(\mathbf{v}_0, \dots, \mathbf{v}_n, \mathbf{v}_\Sigma) \in \tilde{\mathbb{X}}(\Gamma)$.

We conclude this section by introducing a variational space adapted to the presence of heterogeneities in Ω_Σ , namely

$$(5.9) \quad \mathbb{X}(\Sigma, \Gamma) := \{ (U, \mathbf{u}) \in H^1(\Omega_\Sigma) \times \mathbb{X}(\Gamma) \mid \gamma^\Sigma_D(U) = \mathbf{T}_D(\mathbf{u}) \},$$

i.e. we impose that on Σ the Dirichlet trace of a ‘‘heterogeneous’’ component U defined in Ω_Σ matches the Dirichlet trace $\mathbf{T}_D(\mathbf{u})$ of a single-trace tuple \mathbf{u} defined on the skeleton Γ . This is clearly a closed subspace of $H^1(\Omega_\Sigma) \times \mathbb{X}(\Gamma)$ for the inherited Cartesian product norm given by $(U, \mathbf{u}) \mapsto (\|U\|_{H^1(\Omega_\Sigma)}^2 + \|\mathbf{u}\|_{\mathbb{H}(\Gamma)}^2)^{1/2}$.

6. REVIEW OF THE CLASSICAL COSTABEL COUPLING

We revisit the classical Costabel symmetric coupling [11, §7][12], writing the formulation in the compact notation introduced in the previous sections. This will also allow the reader to get more acquainted with our notation.

The classical Costabel coupling gives a symmetric variational formulation of the transmission problem (2.4) in the case $n = 0$, i.e. $\mathbb{R}^d = \bar{\Omega}_0 \cup \bar{\Omega}_\Sigma$, $\Gamma = \Gamma_0 = \Sigma$ (see Figure 2), which combines direct³ boundary integral equations for Ω_0 with a domain variational formulation for Ω_Σ . Note that in our presentation, in contrast to what is usually done in the literature, for Ω_0 we take its own outward-pointing normal vector \mathbf{n}_0 ; this choice is more suitable in view of the extension to the multi-domain case. In the two-subdomain case of the present section we have $\mathbb{X}(\Gamma) = \mathbb{H}(\Gamma) = \mathbb{H}(\Gamma_0) = \mathbb{H}(\Sigma)$ and $\mathbb{X}(\Sigma, \Gamma) = \{ (V, (\gamma^\Sigma_D(V), p)) \mid V \in H^1(\Omega_\Sigma), p \in H^{-1/2}(\Sigma) \}$, so

³A boundary integral equation is of direct type if its unknowns are Dirichlet/Neumann traces of the solution to the related boundary value problem.

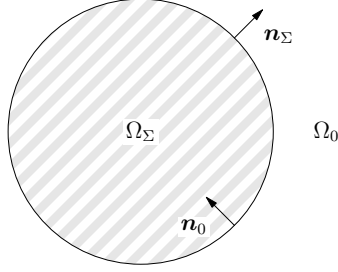


FIGURE 2. Geometric setting for the classical Costabel coupling.

$\mathbb{X}(\Sigma, \Gamma)$ is naturally isomorphic to $H^1(\Omega_\Sigma) \times H^{-1/2}(\Sigma)$, which is the space where Costabel coupling is usually posed.

Now consider $U \in H_{\text{loc}}^1(\mathbb{R}^d)$ solution to the transmission problem (2.4). We are going to reformulate this problem equivalently in terms of the pair

$$(6.1) \quad \begin{aligned} (U|_{\Omega_\Sigma}, \mathbf{u}) &\in \mathbb{X}(\Sigma, \Gamma) \\ \text{where } \mathbf{u} &= \gamma^0(U). \end{aligned}$$

Thus, the Dirichlet transmission condition $\gamma_D^\Sigma(U) = \gamma_D^0(U)$ shall be enforced strongly through the choice of $\mathbb{X}(\Sigma, \Gamma)$ as variational space (recall its definition in (5.9)). To reformulate (2.4) variationally, we first deal with the Helmholtz equation satisfied by U in Ω_Σ . Pick an arbitrary test pair $(V, \mathbf{v}) \in \mathbb{X}(\Sigma, \Gamma)$ and, after multiplying the equation by V , apply Green's formula in Ω_Σ . This leads to a variational identity involving a boundary term:

$$(6.2) \quad \begin{aligned} a_\Sigma(U, V) - \langle \gamma_N^\Sigma(U), \gamma_D^\Sigma(V) \rangle_\Sigma &= F_\Sigma(V) \\ \text{where } a_\Sigma(U, V) &:= \int_{\Omega_\Sigma} (\nabla U \cdot \nabla V - \kappa_\Sigma^2(x)UV) \, d\mathbf{x} \\ F_\Sigma(V) &:= \int_{\Omega_\Sigma} fV \, d\mathbf{x}. \end{aligned}$$

Next, to rewrite the boundary term, we observe that $\gamma_D^\Sigma(V) = \mathbb{T}_D(\mathbf{v})$ because $(V, \mathbf{v}) \in \mathbb{X}(\Sigma, \Gamma)$, and $\gamma_N^\Sigma(U) = \mathbb{T}_N(\mathbf{u})$ by the Neumann transmission condition and (6.1). Hence, recalling the operator $\theta(v, q) := (-v, q)$, we apply identity (3.5), together with the polarity property (5.5) using $\mathbf{u}, \mathbf{v} \in \mathbb{X}(\Gamma)$, so that we obtain

$$\begin{aligned} -\langle \gamma_N^\Sigma(U), \gamma_D^\Sigma(V) \rangle_\Sigma &= -\langle \mathbb{T}_N(\mathbf{u}), \mathbb{T}_D(\mathbf{v}) \rangle_\Sigma \\ &= -[\mathbb{T}(\mathbf{u}), \theta(\mathbb{T}(\mathbf{v}))]_\Sigma / 2 + [\mathbb{T}(\mathbf{u}), \mathbb{T}(\mathbf{v})]_\Sigma / 2 \\ &= +[\mathbf{u}, \theta(\mathbf{v})]_\Gamma / 2 + [\mathbb{T}(\mathbf{u}), \mathbb{T}(\mathbf{v})]_\Sigma / 2. \end{aligned}$$

Therefore, Equation (6.2) becomes

$$(6.3) \quad a_\Sigma(U, V) + [\mathbf{u}, \theta(\mathbf{v})]_\Gamma / 2 + [\mathbb{T}(\mathbf{u}), \mathbb{T}(\mathbf{v})]_\Sigma / 2 = F_\Sigma(V).$$

Now, we wish to exploit boundary integral operators in Ω_0 . Since U_{inc} solves the homogeneous Helmholtz equation with wavenumber κ_0 in $\Omega_\Sigma = \mathbb{R}^d \setminus \bar{\Omega}_0$ and $\gamma^0(U_{\text{inc}}) = \gamma_c^0(U_{\text{inc}})$, the ‘‘exterior’’ representation formula (4.2) is applicable to U_{inc} in Ω_0 and yields $\gamma^0 \mathbf{G}_{\kappa_0}^0(\gamma^0(U_{\text{inc}})) = \gamma^0 \mathbf{G}_{\kappa_0}^0(\gamma_c^0(U_{\text{inc}})) = 0$. As $U - U_{\text{inc}}$ solves the homogeneous Helmholtz equation in Ω_0 and satisfies the associated κ_0 -radiation condition, the representation formula (4.1) is applicable to $U - U_{\text{inc}}$ in Ω_0 and yields

$\gamma^0(U - U_{\text{inc}}) = \gamma^0 \mathbf{G}_{\kappa_0}^0(\gamma^0(U - U_{\text{inc}})) = \gamma^0 \mathbf{G}_{\kappa_0}^0(\gamma^0(U))$. Then, making use of (4.7) and $\mathbf{u} = \gamma^0(U)$, we get

$$(6.4) \quad \mathbf{u}/2 = \mathbf{A}_{\kappa_0}^0(\mathbf{u}) + \gamma^0(U_{\text{inc}}).$$

This is a reformulation of the Helmholtz equation satisfied by U in Ω_0 based on both Dirichlet and Neumann traces of the representation formula; note that, in contrast to the present Costabel coupling, the Johnson-Nédélec coupling would involve just the Dirichlet one. Plugging (6.4) into (6.3), we finally obtain the variational formulation of the *Costabel symmetric coupling* posed in $\mathbb{X}(\Sigma, \Gamma)$:

$$(6.5) \quad \boxed{\begin{array}{l} \text{find } (U, \mathbf{u}) \in \mathbb{X}(\Sigma, \Gamma) \text{ such that} \\ a_{\Sigma}(U, V) + [\mathbf{A}_{\kappa_0}^0(\mathbf{u}), \theta(\mathbf{v})]_{\Gamma} + [\mathbf{T}(\mathbf{u}), \mathbf{T}(\mathbf{v})]_{\Sigma}/2 \\ = F_{\Sigma}(V) - [\gamma^0(U_{\text{inc}}), \theta(\mathbf{v})]_{\Gamma} \quad \forall (V, \mathbf{v}) \in \mathbb{X}(\Sigma, \Gamma). \end{array}}$$

Let $\mathbf{a}_{\mathbb{C}}: \mathbb{X}(\Sigma, \Gamma) \times \mathbb{X}(\Sigma, \Gamma) \rightarrow \mathbb{C}$ designate the bilinear form on the left-hand side of (6.5). The bilinear form $a_{\Sigma}(\cdot, \cdot)$ satisfies a Gårding inequality, as well as $[\mathbf{A}_{\kappa_0}^0(\cdot), \theta(\cdot)]_{\Gamma}$ (see Proposition 4.3). Hence, since $\text{Re}\{[\mathbf{T}(\mathbf{v}), \mathbf{T}(\overline{\mathbf{v}})]_{\Sigma}\} = 0$, we conclude, as in [13], that $\mathbf{a}_{\mathbb{C}}(\cdot, \cdot)$ satisfies a *Gårding inequality*: there exist a compact bilinear form $\mathbf{k}: \mathbb{X}(\Sigma, \Gamma) \times \mathbb{X}(\Sigma, \Gamma) \rightarrow \mathbb{C}$ and a constant $\beta > 0$ such that

$$\begin{aligned} \text{Re}\{ \mathbf{a}_{\mathbb{C}}((V, \mathbf{v}), \overline{(V, \mathbf{v})}) + \mathbf{k}((V, \mathbf{v}), \overline{(V, \mathbf{v})}) \} \\ \geq \beta(\|V\|_{\mathbb{H}^1(\Omega_{\Sigma})}^2 + \|\mathbf{v}\|_{\mathbb{H}(\Gamma)}^2) \end{aligned}$$

for all $V \in \mathbb{H}^1(\Omega_{\Sigma})$, $\mathbf{v} \in \mathbb{H}(\Gamma)$. As a consequence, the operator induced by $\mathbf{a}_{\mathbb{C}}$ is of Fredholm type with index 0 (see [17, Theorem 2.33]), i.e. it is bijective if and only if it is injective.

The classical Costabel coupling may be affected by the *spurious resonances* phenomenon, that is, the formulation fails to possess a unique solution for the wavenumbers κ_0 whose square is an interior Dirichlet eigenvalue of $-\Delta$ on Ω_{Σ} , i.e. κ_0 belongs to

$$\mathfrak{S}(\Delta, \Omega_{\Sigma}) := \{ \kappa \in \mathbb{C} \mid \exists W \in \mathbb{H}_0^1(\Omega_{\Sigma}) \setminus \{0\} \text{ such that } -\Delta W = \kappa^2 W \text{ in } \Omega_{\Sigma} \}.$$

Example 6.1 (Spurious resonances). Let $\kappa_0 \in \mathfrak{S}(\Delta, \Omega_{\Sigma})$ and $W \in \mathbb{H}^1(\Omega_{\Sigma}) \setminus \{0\}$ such that $-\Delta W = \kappa_0^2 W$ in Ω_{Σ} and $W = 0$ on Σ . In particular $\gamma_{\text{D}}^{\Sigma}(W) = \gamma_{\text{D},c}^0(W) = 0$. Then, setting $U = 0$ and $\mathbf{u} = \gamma_c^0(W)$, we have $(U, \mathbf{u}) \in \mathbb{X}(\Sigma, \Gamma)$. Moreover, by the “exterior” representation formula (4.2) we have $\mathbf{G}_{\kappa_0}^0(\gamma_c^0(W)) = 0$ in Ω_0 , and together with (4.7) we obtain $\mathbf{A}_{\kappa_0}^0(\gamma_c^0(W)) = 0 - \gamma_c^0(W)/2$. Therefore, by the polarity property (5.5) and identity (3.6)

$$\begin{aligned} a_{\Sigma}(U, V) + [\mathbf{A}_{\kappa_0}^0(\mathbf{u}), \theta(\mathbf{v})]_{\Gamma} + [\mathbf{T}(\mathbf{u}), \mathbf{T}(\mathbf{v})]_{\Sigma}/2 \\ = 0 + [\mathbf{A}_{\kappa_0}^0(\gamma_c^0(W)), \theta(\mathbf{v})]_{\Gamma} - [\gamma_c^0(W), \mathbf{v}]_{\Gamma}/2 \\ = -[\gamma_c^0(W), \theta(\mathbf{v})]_{\Gamma}/2 - [\gamma_c^0(W), \mathbf{v}]_{\Gamma}/2 = -\langle \gamma_{\text{D},c}^0(W), q \rangle_{\Gamma} = 0 \end{aligned}$$

for all $(V, \mathbf{v}) \in \mathbb{X}(\Sigma, \Gamma)$, with $\mathbf{v} = (v, q)$. This indicates that (U, \mathbf{u}) is a non-trivial solution to (6.5) with homogeneous right-hand side $F_{\Sigma} \equiv 0$, $U_{\text{inc}} = 0$.

It turns out that $\kappa_0 \in \mathfrak{S}(\Delta, \Omega_{\Sigma})$ is also a necessary condition for the presence of spurious resonances. To prove this, we need the following equivalence result between the Costabel coupling formulation (6.5) and the transmission problem (2.4) with $n = 0$.

Proposition 6.2 (Equivalence). *If $\tilde{U} \in H_{\text{loc}}^1(\mathbb{R}^d)$ solves (2.4) with $n = 0$, then the pair $(U, \mathbf{u}) = (\tilde{U}|_{\Omega_\Sigma}, \gamma^0(\tilde{U}))$ solves (6.5). Reciprocally, if $(U, \mathbf{u}) \in \mathbb{X}(\Sigma, \Gamma)$ solves (6.5), then the solution to (2.4) with $n = 0$ is given by*

$$(6.6) \quad \begin{aligned} \tilde{U}(\mathbf{x}) &:= U(\mathbf{x}) && \text{for } \mathbf{x} \in \Omega_\Sigma, \\ \tilde{U}(\mathbf{x}) &:= (\mathbf{G}_{\kappa_0}^0(\mathbf{u}) + U_{\text{inc}})(\mathbf{x}) && \text{for } \mathbf{x} \in \Omega_0. \end{aligned}$$

Proof. The first implication stems from the derivation of (6.5), so we only need to examine the other implication. First of all, $(\tilde{U} - U_{\text{inc}})|_{\Omega_0} = \mathbf{G}_{\kappa_0}^0(\mathbf{u})$ is κ_0 -outgoing radiating in Ω_0 , see e.g. [10, Theorem 3.2]. Second, \tilde{U} satisfies the Helmholtz equation in Ω_0 since it is satisfied by U_{inc} by definition and also by the potentials, see e.g. [10, §2.4]. If we take $(V, 0) \in H_0^1(\Omega_\Sigma) \times \{0\} \subset \mathbb{X}(\Sigma, \Gamma)$ as test function in (6.5), we obtain $a_\Sigma(U, V) = a_\Sigma(\tilde{U}, V) = F_\Sigma(V)$, so \tilde{U} satisfies Helmholtz equation also in Ω_Σ , and there only remains to prove that \tilde{U} complies with the transmission conditions of (2.4) through $\Gamma \equiv \Sigma$.

Now, considering a generic $(V, \mathbf{v}) \in \mathbb{X}(\Sigma, \Gamma)$ where $V \in H^1(\Omega_\Sigma)$ (not necessarily $V \in H_0^1(\Omega_\Sigma)$), and integrating by parts, we obtain

$$(6.7) \quad a_\Sigma(\tilde{U}, V) - \langle \gamma_N^\Sigma \tilde{U}, \gamma_D^\Sigma V \rangle_\Gamma = F_\Sigma(V) \quad \forall V \in H^1(\Omega_\Sigma).$$

By (6.6) and (4.7), we have $\gamma^0(\tilde{U}) = \mathbf{A}_{\kappa_0}^0(\mathbf{u}) + \mathbf{u}/2 + \gamma^0(U_{\text{inc}})$. Then, plugging (6.7) and the latter identity into (6.5) leads to

$$\begin{aligned} \langle \gamma_N^\Sigma \tilde{U}, \gamma_D^\Sigma V \rangle_\Gamma + [\mathbf{A}_{\kappa_0}^0(\mathbf{u}), \theta(\mathbf{v})]_\Gamma + [\mathbf{T}(\mathbf{u}), \mathbf{T}(\mathbf{v})]_\Sigma / 2 &= -[\gamma^0(U_{\text{inc}}), \theta(\mathbf{v})]_\Gamma \\ \langle \gamma_N^\Sigma \tilde{U}, \gamma_D^\Sigma V \rangle_\Gamma + [\gamma^0(\tilde{U}) - \mathbf{u}/2, \theta(\mathbf{v})]_\Gamma + [\mathbf{T}(\mathbf{u}), \mathbf{T}(\mathbf{v})]_\Sigma / 2 &= 0 \end{aligned}$$

that is, by the polarity property (5.5) and identity (3.6) writing $\mathbf{u} = (u, p)$, $\mathbf{v} = (v, q)$, the latest equality writes

$$\begin{aligned} \langle \gamma_N^\Sigma \tilde{U}, \gamma_D^\Sigma V \rangle_\Gamma + [\gamma^0(\tilde{U}), \theta(\mathbf{v})]_\Gamma &= [\mathbf{u}, \theta(\mathbf{v})]_\Gamma / 2 + [\mathbf{u}, \mathbf{v}]_\Gamma / 2 \\ \langle \gamma_N^\Sigma \tilde{U}, \gamma_D^\Sigma V \rangle_\Gamma - \langle u, q \rangle_\Gamma - [\theta \circ \gamma^0(\tilde{U}), \mathbf{v}]_\Gamma &= 0. \end{aligned}$$

Since $(U, \mathbf{u}) \in \mathbb{X}(\Sigma, \Gamma)$ we have $u = \mathbf{T}_D(\mathbf{u}) = \gamma_D^\Sigma(U) = \gamma_D^\Sigma(\tilde{U})$. Similarly, for the test pair we have $(V, \mathbf{v}) \in \mathbb{X}(\Sigma, \Gamma)$, hence $\gamma_D^\Sigma(V) = \mathbf{T}_D(\mathbf{v}) = v$. As a consequence, $\langle \gamma_N^\Sigma \tilde{U}, \gamma_D^\Sigma V \rangle_\Gamma - \langle u, q \rangle_\Gamma = -[\gamma^\Sigma(\tilde{U}), \mathbf{v}]_\Gamma$ and, finally, we obtain $[\gamma^\Sigma(\tilde{U}) + \theta \circ \gamma^0(\tilde{U}), \mathbf{v}]_\Gamma = 0$ for all $\mathbf{v} = (v, q) \in H^{1/2}(\Gamma) \times H^{-1/2}(\Gamma)$. This implies that $\gamma^\Sigma(\tilde{U}) = -\theta \circ \gamma^0(\tilde{U})$, which also rewrites $\gamma_D^0(\tilde{U}) = \gamma_D^\Sigma(\tilde{U})$ and $\gamma_N^0(\tilde{U}) = -\gamma_N^\Sigma(\tilde{U})$. \square

Corollary 6.3 (Injectivity condition). *Let $(U, \mathbf{u}) \in \mathbb{X}(\Sigma, \Gamma)$, solve (6.5) with $F_\Sigma \equiv 0$ and $U_{\text{inc}} = 0$. Then $U = 0$. If $\kappa_0 \notin \mathfrak{S}(\Delta, \Omega_\Sigma)$ we also have $\mathbf{u} = 0$ necessarily.*

Proof. By the equivalence proposition, $\tilde{U} \in H_{\text{loc}}^1(\mathbb{R}^d)$ defined by (6.6) satisfies the transmission problem (2.4) with $n = 0$, which is well posed, so $\tilde{U} = 0$. Since $\tilde{U}|_{\Omega_\Sigma} = U$, we get $U = 0$. Denoting $\mathbf{u} = (u, p)$, we then have $u = \mathbf{T}_D(\mathbf{u}) = \gamma_D^\Sigma(U) = 0$ because $(U, \mathbf{u}) \in \mathbb{X}(\Sigma, \Gamma)$. Moreover, since $\tilde{U}|_{\Omega_0} = \mathbf{G}_{\kappa_0}^0(\mathbf{u})$, we obtain $\mathbf{G}_{\kappa_0}^0(\mathbf{u})(\mathbf{x}) = 0$, that is $\mathbf{SL}_{\kappa_0}^0(p)(\mathbf{x}) = 0$ for $\mathbf{x} \in \Omega_0$. Therefore $\gamma_D^0 \mathbf{SL}_{\kappa_0}^0(p) = 0$, which implies $p = 0$ given $\kappa_0 \notin \mathfrak{S}(\Delta, \Omega_\Sigma)$ (see [21, Theorem 3.9.1]). \square

We refer to [13] for a combined field integral equation FEM-BEM formulation immune to spurious resonances.

7. SINGLE-TRACE FEM-BEM FORMULATION

In this section we shall revisit the analysis presented in the previous section, this time considering multi-domain configurations ($n \geq 1$ with potential cross-points) instead of a simple two-domain setting. This will lead to a first coupling variational formulation for the transmission problem (2.4) in the targeted multi-domain configuration. We combine a domain variational formulation in Ω_Σ with the boundary integral formulation on Γ called Single-Trace Formulation (STF), first analyzed in [22]. The Costabel coupling lends itself well to match the STF since it is based on the full set of Calderón identities, from which the STF arises. In [8, §4] the STF was revisited and adapted to the case with an impenetrable part represented by the domain Ω_Σ ; the present analysis, where Ω_Σ is a heterogeneous part, bears several similarities to the analysis in [8].

As in the previous section, let us start with a function U unique solution to the transmission problem (2.4). We are going to reformulate this transmission problem in terms of the pair

$$(7.1) \quad \begin{aligned} (U|_{\Omega_\Sigma}, \mathbf{u}) &\in \mathbb{X}(\Sigma, \Gamma) \\ \text{where } \mathbf{u} &= \gamma(U) = (\gamma^0(U), \dots, \gamma^n(U)). \end{aligned}$$

Here, except for the Neumann condition through Σ that writes $\gamma_N^\Sigma(U) = \mathbf{T}_N(\mathbf{u})$, the transmission conditions shall be enforced strongly by the choice of $\mathbb{X}(\Sigma, \Gamma)$ as variational space. Now pick an arbitrary pair $(V, \mathbf{v}) \in \mathbb{X}(\Sigma, \Gamma)$ and apply Green's formula in Ω_Σ . Here again we obtain the following variational identity

$$(7.2) \quad \begin{aligned} a_\Sigma(U, V) - \langle \gamma_N^\Sigma(U), \gamma_D^\Sigma(V) \rangle_\Sigma &= F_\Sigma(V) \\ \text{where } a_\Sigma(U, V) &:= \int_{\Omega_\Sigma} \nabla U \cdot \nabla V - \kappa_\Sigma^2(\mathbf{x})UV \, d\mathbf{x} \\ F_\Sigma(V) &:= \int_{\Omega_\Sigma} fV \, d\mathbf{x}. \end{aligned}$$

Because the test pair (V, \mathbf{v}) is chosen in $\mathbb{X}(\Sigma, \Gamma)$, we must have $\gamma_D^\Sigma(V) = \mathbf{T}_D(\mathbf{v})$. Taking account of the Neumann transmission condition through Σ , and applying identity (3.5) together with the polarity property (5.5) using $\mathbf{u}, \mathbf{v} \in \mathbb{X}(\Gamma)$, we have

$$(7.3) \quad \begin{aligned} -\langle \gamma_N^\Sigma(U), \gamma_D^\Sigma(V) \rangle_\Sigma &= -\langle \mathbf{T}_N(\mathbf{u}), \mathbf{T}_D(\mathbf{v}) \rangle_\Sigma \\ &= -[\mathbf{T}(\mathbf{u}), \theta(\mathbf{T}(\mathbf{v}))]_{\Sigma/2} + [\mathbf{T}(\mathbf{u}), \mathbf{T}(\mathbf{v})]_{\Sigma/2} \\ &= +[\mathbf{u}, \Theta(\mathbf{v})]_{\Gamma/2} + [\mathbf{T}(\mathbf{u}), \mathbf{T}(\mathbf{v})]_{\Sigma/2} \end{aligned}$$

where $\Theta(\mathbf{v}) := (\theta(\mathbf{v}_0), \dots, \theta(\mathbf{v}_n))$ for $\mathbf{v} = (\mathbf{v}_0, \dots, \mathbf{v}_n) \in \mathbb{H}(\Gamma)$, so that we have $\theta \circ \mathbf{T} = \mathbf{T} \circ \Theta$. Plugging the previous identity into (7.2) leads to

$$(7.4) \quad a_\Sigma(U, V) + [\mathbf{u}, \Theta(\mathbf{v})]_{\Gamma/2} + [\mathbf{T}(\mathbf{u}), \mathbf{T}(\mathbf{v})]_{\Sigma/2} = F_\Sigma(V).$$

Following for Ω_0 the same argumentation as in Section 6, we have $\gamma^0 G_{\kappa_0}^0(\gamma^0(U_{\text{inc}})) = \gamma^0 G_{\kappa_0}^0(\gamma_c^0(U_{\text{inc}})) = 0$, and $\gamma^0(U - U_{\text{inc}}) = \gamma^0 G_{\kappa_0}^0(\gamma^0(U - U_{\text{inc}})) = \gamma^0 G_{\kappa_0}^0 \gamma^0(U)$. Hence $\gamma^0(U) = \gamma^0 G_{\kappa_0}^0 \gamma^0(U) + \gamma^0(U_{\text{inc}})$, which by (4.7) also rewrites $\gamma^0(U)/2 = \mathbf{A}_{\kappa_0}^0 \gamma^0(U) + \gamma^0(U_{\text{inc}})$. Moreover, since U verifies the Helmholtz equation with constant wavenumber κ_j in Ω_j , $j = 1, \dots, n$, the representation formula (4.1) yields $\gamma^j(U) = \gamma^j G_{\kappa_j}^j(\gamma^j(U))$, that is, by (4.7), $\gamma^j(U)/2 = \mathbf{A}_{\kappa_j}^j \gamma^j(U)$. With the notation

$\mathbf{u} = \gamma(U) = (\gamma^0(U), \dots, \gamma^n(U))$, we have obtained

$$(7.5) \quad \begin{aligned} \mathbf{u}/2 &= \mathbf{A}(\mathbf{u}) + \mathbf{u}^{\text{inc}} \\ \text{where } \mathbf{A} &:= \text{diag}(\mathbf{A}_{\kappa_0}^0, \dots, \mathbf{A}_{\kappa_n}^n) \\ \mathbf{u}^{\text{inc}} &:= (\gamma^0(U_{\text{inc}}), 0, \dots, 0). \end{aligned}$$

We draw the attention of our reader on the strong analogy between (7.5) and (6.4), the essential difference being that we are now dealing with multiple subdomains, i.e. $\Omega_0, \dots, \Omega_n$ instead of only Ω_0 . Now plugging (7.5) into the second term in the left-hand side of (7.4) leads to the *single-trace FEM-BEM formulation*:

$$(7.6) \quad \boxed{\begin{aligned} &\text{Find } (U, \mathbf{u}) \in \mathbb{X}(\Sigma, \Gamma) \text{ such that} \\ &a_\Sigma(U, V) + [\mathbf{A}(\mathbf{u}), \Theta(\mathbf{v})]_\Gamma + [\mathbf{T}(\mathbf{u}), \mathbf{T}(\mathbf{v})]_\Sigma/2 \\ &= F_\Sigma(V) - [\mathbf{u}^{\text{inc}}, \Theta(\mathbf{v})]_\Gamma \quad \forall (V, \mathbf{v}) \in \mathbb{X}(\Sigma, \Gamma). \end{aligned}}$$

Noticing the strong similarities between (7.6) and (6.5), we have just derived a generalization of the Costabel coupling (6.5) to multi-domain settings.

The link between the single-trace FEM-BEM formulation (7.6) and the transmission problem (2.4) is examined in the following proposition.

Proposition 7.1 (Equivalence). *If $\tilde{U} \in H_{\text{loc}}^1(\mathbb{R}^d)$ solves (2.4), then the pair $(U, \mathbf{u}) = (\tilde{U}|_{\Omega_\Sigma}, \gamma(\tilde{U}))$ solves (7.6). If $(U, \mathbf{u}) \in \mathbb{X}(\Sigma, \Gamma)$ solves (7.6), then the solution to (2.4) is given by*

$$(7.7) \quad \begin{aligned} \tilde{U}(\mathbf{x}) &:= U(\mathbf{x}) \quad \text{for } \mathbf{x} \in \Omega_\Sigma, \\ \tilde{U}(\mathbf{x}) &:= \mathbf{G}_{\kappa_j}^j(\mathbf{u}_j)(\mathbf{x}) + U_{\text{inc}}(\mathbf{x})1_{\Omega_0}(\mathbf{x}) \quad \text{for } \mathbf{x} \in \Omega_j, j = 0, \dots, n. \end{aligned}$$

Proof. We will follow closely the proof of Proposition 6.2 established for the case $n = 0$, except that we now have multiple subdomains Ω_j . By similar arguments as in the beginning of that proof, it remains only to show that \tilde{U} given by (7.7) complies with the transmission conditions of (2.4). For that we will use their characterization given by Lemma 5.3.

Considering an arbitrary test pair $(V, \mathbf{v}) \in \mathbb{X}(\Sigma, \Gamma)$, and applying Green's formula in Ω_Σ leads to

$$(7.8) \quad a_\Sigma(U, V) - \langle \gamma_N^\Sigma \tilde{U}, \gamma_D^\Sigma V \rangle_\Sigma = F_\Sigma(V) \quad \forall V \in H^1(\Omega_\Sigma).$$

On the other hand, by applying the trace operator γ^j on the second line of (7.7) and using (4.7), we get $\gamma^0(\tilde{U}) = \mathbf{A}_{\kappa_0}^0(\mathbf{u}_0) + \mathbf{u}_0/2 + \gamma^0(U_{\text{inc}})$ and $\gamma^j(\tilde{U}) = \mathbf{A}_{\kappa_j}^j(\mathbf{u}_j) + \mathbf{u}_j/2$ for $j = 1 \dots n$, that is, in compact notation, $\gamma(\tilde{U}) = \mathbf{A}(\mathbf{u}) + \mathbf{u}/2 + \mathbf{u}^{\text{inc}}$. Now we plug this and (7.8) into (7.6), so we obtain

$$(7.9) \quad \langle \gamma_N^\Sigma \tilde{U}, \gamma_D^\Sigma V \rangle_\Sigma + [\gamma(\tilde{U}), \Theta(\mathbf{v})]_\Gamma - [\mathbf{u}, \Theta(\mathbf{v})]_\Gamma/2 + [\mathbf{T}(\mathbf{u}), \mathbf{T}(\mathbf{v})]_\Sigma/2 = 0 \\ \text{for all } (V, \mathbf{v}) \in \mathbb{X}(\Sigma, \Gamma).$$

By the polarity identity (5.5) and (3.6) we can write

$$\begin{aligned} -[\mathbf{u}, \Theta(\mathbf{v})]_\Gamma/2 + [\mathbf{T}(\mathbf{u}), \mathbf{T}(\mathbf{v})]_\Sigma/2 &= [\mathbf{T}(\mathbf{u}), \mathbf{T}(\Theta(\mathbf{v}))]_\Sigma/2 + [\mathbf{T}(\mathbf{u}), \mathbf{T}(\mathbf{v})]_\Sigma/2 \\ &= \langle \mathbf{T}_D(\mathbf{u}), \mathbf{T}_N(\mathbf{v}) \rangle_\Sigma, \end{aligned}$$

so (7.9) becomes

$$\begin{aligned} \langle \gamma_N^\Sigma \tilde{U}, \gamma_D^\Sigma V \rangle_\Sigma + \langle T_D(\mathbf{u}), T_N(\mathbf{v}) \rangle_\Sigma + [\gamma(\tilde{U}), \Theta(\mathbf{v})]_\Gamma = 0 \\ \text{for all } (V, \mathbf{v}) \in \mathbb{X}(\Sigma, \Gamma). \end{aligned}$$

Moreover, since $(U, \mathbf{u}) \in \mathbb{X}(\Sigma, \Gamma)$ and $\tilde{U}|_{\Omega_\Sigma} = U$, we have $T_D(\mathbf{u}) = \gamma_D^\Sigma(U) = \gamma_D^\Sigma(\tilde{U})$, and also $\gamma_D^\Sigma(V) = T_D(\mathbf{v})$ because $(V, \mathbf{v}) \in \mathbb{X}(\Sigma, \Gamma)$. Therefore, by (3.4) and $\theta \circ T = T \circ \Theta$, we conclude that

$$[\gamma^\Sigma(\tilde{U}), T(\Theta(\mathbf{v}))]_\Sigma + [\gamma(\tilde{U}), \Theta(\mathbf{v})]_\Gamma = 0 \quad \text{for all } \mathbf{v} \in \mathbb{X}(\Gamma).$$

Thanks to the variational characterization (5.7), since Θ is an automorphism, we conclude that \tilde{U} satisfies the transmission conditions of Problem (2.4). \square

The bilinear form $a_\Sigma(\cdot, \cdot)$ satisfies a Gårding inequality, as well as $[A(\cdot), \Theta(\cdot)]_\Gamma$, see [22, §4.1] and [8, Proposition 4.2]. In addition we have $\text{Re}\{[T(\mathbf{v}), T(\bar{\mathbf{v}})]_\Sigma\} = 0$. From these remarks we conclude that $\mathfrak{a}_{\text{STF}}: \mathbb{X}(\Sigma, \Gamma) \times \mathbb{X}(\Sigma, \Gamma) \rightarrow \mathbb{C}$ defined as the bilinear form on the left-hand side of (7.6) satisfies a *Gårding inequality*.

Proposition 7.2 (Gårding inequality). *There exist a compact bilinear form $\mathfrak{k}: \mathbb{X}(\Sigma, \Gamma) \times \mathbb{X}(\Sigma, \Gamma) \rightarrow \mathbb{C}$ and a constant $\beta > 0$ such that*

$$\text{Re}\{\mathfrak{a}_{\text{STF}}((V, \mathbf{v}), (\bar{V}, \bar{\mathbf{v}})) + \mathfrak{k}((V, \mathbf{v}), (\bar{V}, \bar{\mathbf{v}}))\} \geq \beta(\|V\|_{\mathbb{H}^1(\Omega_\Sigma)}^2 + \|\mathbf{v}\|_{\mathbb{H}(\Gamma)}^2)$$

for all $(V, \mathbf{v}) \in \mathbb{X}(\Sigma, \Gamma)$.

As a consequence, the operator induced by $\mathfrak{a}_{\text{STF}}$ is of Fredholm type with index 0 (see [17, Theorem 2.33]), that is, formulation (7.6) has a unique solution for all $f \in L^2(\Omega_\Sigma)$, $U_{\text{inc}} \in \mathbf{H}_{\text{loc}}^1(\mathbb{R}^d)$ if and only if for $F_\Sigma \equiv 0$, $\mathbf{u}^{\text{inc}} = 0$ it only has the trivial solution. Other important consequences of the Gårding inequality are, again *in the case of injectivity* (see [21, Theorems 4.2.9, 4.2.8]): stability of the variational formulation (7.6) in the sense of an inf-sup condition; for Galerkin equations discretizing (7.6), the validity of a discrete inf-sup condition, which implies well-posedness for the Galerkin equations and a quasi-optimal convergence of the Galerkin solutions to the exact solution.

7.1. Spurious resonances. Unfortunately, like the classical Costabel coupling, the single-trace FEM-BEM formulation (7.6) may be affected by the spurious resonances phenomenon, that is, the associated operator may be not injective, whereas the transmission problem (2.4) is always well-posed. Here we examine in which situations the spurious resonances phenomenon occurs. The following proposition identifies the injectivity condition, which depends on the wavenumbers *and* on the geometric configuration. This condition turns out to be the same as in [8, Theorem 4.8], which dealt with a partially impenetrable composite medium.

Proposition 7.3 (Injectivity condition). *Let $(U, \mathbf{u}) \in \mathbb{X}(\Sigma, \Gamma)$ solve formulation (7.6) with $F_\Sigma \equiv 0$, $\mathbf{u}^{\text{inc}} = 0$. Then $U = 0$. We also have $\mathbf{u} = 0$ if the following additional condition is satisfied:*

$$(7.10) \quad \begin{aligned} \Sigma \not\subset \Gamma_j \quad \text{or} \quad \kappa_j \notin \mathfrak{S}(\Delta, \Omega_\Sigma) \\ \text{for all } j = 0, \dots, n. \end{aligned}$$

In the case where Condition (7.10) does not hold, there exists $\mathbf{u} \in \mathbb{X}(\Gamma) \setminus \{0\}$ such that $(0, \mathbf{u}) \in \mathbb{X}(\Sigma, \Gamma)$ solves (7.6) with $F_\Sigma \equiv 0$, $\mathbf{u}^{\text{inc}} = 0$.

Proof. By the equivalence Proposition 7.1, the function \tilde{U} defined in (7.7) solves the homogeneous transmission problem (2.4), which is well-posed, so $\tilde{U} = 0$. In particular, $U = \tilde{U}|_{\Omega_\Sigma} = 0$, and $\mathsf{T}_D(\mathbf{u}) = \gamma_D^\Sigma U = 0$. Employing test functions $(V, \mathbf{v}) \in \mathbb{X}(\Sigma, \Gamma)$ with $\gamma_D^\Sigma V = \mathsf{T}_D(\mathbf{v}) = 0$ in formulation (7.6) with $F_\Sigma \equiv 0$, $\mathbf{u}^{\text{inc}} = 0$, we obtain that \mathbf{u} satisfies

$$[\mathbf{A}(\mathbf{u}), \Theta(\mathbf{v})] = 0, \quad \forall \mathbf{v} \in \mathbb{X}(\Gamma) \text{ with } \mathsf{T}_D(\mathbf{v}) = 0,$$

i.e. $\mathbf{u} \in \mathbb{X}(\Gamma)$ satisfies $\mathsf{T}_D(\mathbf{u}) = 0$ and $[\mathbf{A}(\mathbf{u}), \mathbf{v}] = 0, \forall \mathbf{v} \in \mathbb{X}(\Gamma)$ with $\mathsf{T}_D(\mathbf{v}) = 0$, which is exactly the setting of [8, Lemma 4.5, Lemma 4.6]. As a consequence also [8, Corollary 4.7] holds true: if $\Sigma \not\subset \Gamma_j$ for all $j = 0, \dots, n$, then for any choice of $\kappa_j > 0$ we have $\mathbf{u} = 0$. We also obtain that, if $\Sigma \subset \Gamma_j$ for a $j \in \{0, \dots, n\}$, then $\kappa_j \notin \mathfrak{S}(\Delta, \Omega_\Sigma)$ implies $\mathbf{u} = 0$, thanks to the reasoning in the third bullet in the proof of [8, Theorem 4.8], which relies on [8, Lemma 4.5, Lemma 4.6].

Next, assuming that Condition (7.10) does not hold i.e. $\Sigma \subset \Gamma_i$ and $\kappa_i \in \mathfrak{S}(\Delta, \Omega_\Sigma)$ for a certain $i \in \{0, \dots, n\}$, we construct $\mathbf{u} \neq 0$ such that $(0, \mathbf{u})$ solves (7.6) with $F_\Sigma \equiv 0$, $\mathbf{u}^{\text{inc}} = 0$. Since $\Sigma \subset \Gamma_i$, by the geometric considerations in the first bullet in the proof of [8, Theorem 4.8], we get that Ω_Σ is exactly one bounded connected component of $\mathbb{R}^d \setminus \overline{\Omega}_i$, and in particular Ω_Σ is completely separated from the other subdomains Ω_j , $j \neq i$:

$$(7.11) \quad \overline{\Omega}_\Sigma \cap \bigcup_{j=0, j \neq i}^n \overline{\Omega}_j = \emptyset.$$

Since $\kappa_i \in \mathfrak{S}(\Delta, \Omega_\Sigma)$, there exists $W \in \mathbf{H}^1(\Omega_\Sigma) \setminus \{0\}$ such that $-\Delta W - \kappa_i^2 W = 0$ in Ω_Σ and $W = 0$ on Σ . We consider $U^* = 0 \in \mathbf{H}^1(\Omega_\Sigma)$, $u_i = 0 \in \mathbf{H}^{1/2}(\Gamma_i)$, and $p_i \in \mathbf{H}^{-1/2}(\Gamma_i)$ with $p_i = 0$ on $\Gamma_i \setminus \Sigma$ and $p_i = -\gamma_N^\Sigma W$ on Σ . We set $\mathbf{u}_i^* = (u_i, p_i)$ and $\mathbf{u}_j^* = (0, 0)$ for $j \neq i, j = 0, \dots, n$, thus by construction and (7.11), we have $\mathbf{u}^* \in \mathbb{X}(\Gamma)$ and $\mathsf{T}_D(\mathbf{u}^*) = u_i = 0 = \gamma_D^\Sigma U^*$, that is $(U^*, \mathbf{u}^*) \in \mathbb{X}(\Sigma, \Gamma)$. If we evaluate the left-hand side of formulation (7.6) in (U^*, \mathbf{u}^*) we get: given any $(V, \mathbf{v}) \in \mathbb{X}(\Sigma, \Gamma)$

$$\begin{aligned} & [\mathbf{A}_{\kappa_i}^i(\mathbf{u}_i^*), \theta(\mathbf{v}_i)]_{\Gamma_i} - \langle \mathsf{T}_N(\mathbf{u}^*), \mathsf{T}_D(\mathbf{v}) \rangle_\Sigma / 2 = \\ & [\gamma^i \mathbf{G}_{\kappa_i}^i(\mathbf{u}_i^*), \theta(\mathbf{v}_i)]_{\Gamma_i} - [\mathbf{u}_i^*, \theta(\mathbf{v}_i)]_{\Gamma_i} / 2 - \langle \mathsf{T}_N(\mathbf{u}^*), \mathsf{T}_D(\mathbf{v}) \rangle_\Sigma / 2 = \\ & [\gamma^i \mathbf{SL}_{\kappa_i}^i(p_i), \theta(\mathbf{v}_i)]_{\Gamma_i} - \langle p_i, v_i \rangle_{\Gamma_i} / 2 + \langle p_i, v_i \rangle_\Sigma / 2, \end{aligned}$$

where we have used (4.7), and (7.11) to write $\mathsf{T}_D(\mathbf{v}) = v_i$, $\mathsf{T}_N(\mathbf{u}^*) = -p_i$. Now, the last two terms cancel each other out since by construction $p_i = 0$ on $\Gamma_i \setminus \Sigma$. For the same reason in the first term $\mathbf{SL}_{\kappa_i}^i(p_i) = \mathbf{SL}_{\kappa_i}^\Sigma(p_i)$. Moreover, by the representation formula (4.1) on Ω_Σ , for $\mathbf{x} \in \mathbb{R}^d \setminus \overline{\Omega}_\Sigma$ we have

$$0 = \mathbf{G}_{\kappa_i}^\Sigma(\gamma^\Sigma W)(\mathbf{x}) = \mathbf{SL}_{\kappa_i}^\Sigma(\gamma_N^\Sigma W)(\mathbf{x}) = -\mathbf{SL}_{\kappa_i}^\Sigma(p_i)(\mathbf{x}),$$

therefore $\gamma^i \mathbf{SL}_{\kappa_i}^i(p_i) = 0$ and (U^*, \mathbf{u}^*) is a non-trivial solution to formulation (7.6). \square

Note that Corollary 6.3 for the classical Costabel coupling is a particular case of the previous proposition, where $\Sigma \subset \Gamma_0$. In the multi-domain configuration, surprising situations can arise, as shown in the next example.

Example 7.4. Consider the transmission problem (2.4) with $n = 1$, i.e. $\mathbb{R}^d = \overline{\Omega}_0 \cup \overline{\Omega}_1 \cup \overline{\Omega}_\Sigma$, but suppose that $\kappa_0 = \kappa_1$ so that the interface $\Gamma_0 \cap \Gamma_1$ is ‘‘artificial’’. In fact, the material configuration is the same as in the classical Costabel coupling,

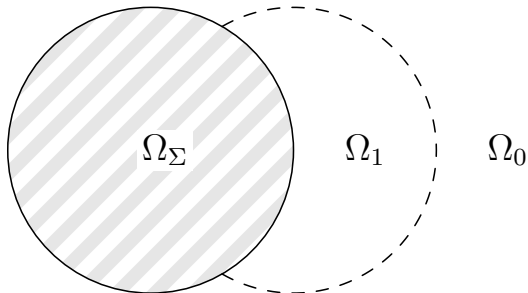


FIGURE 3. Situation without spurious resonances.

which is affected by spurious resonances if $\kappa_0 \in \mathfrak{S}(\Delta, \Omega_\Sigma)$. On the contrary, if we assume that $\text{mes}(\Sigma \cap \Gamma_0) > 0$ and $\text{mes}(\Sigma \cap \Gamma_1) > 0$ as in Figure 3, so that $\Sigma \not\subset \Gamma_1$ and $\Sigma \not\subset \Gamma_0$, then, no matter which is the value of κ_0 , the corresponding single-trace FEM-BEM formulation (7.6) does not have spurious resonances!

8. SINGLE-TRACE COMBINED FIELD FEM-BEM FORMULATION

We have shown that the single-trace FEM-BEM formulation (7.6) is affected by spurious resonances when $\Sigma \subset \Gamma_i$ and $\kappa_i \in \mathfrak{S}(\Delta, \Omega_\Sigma)$ for a certain $i \in \{0, \dots, n\}$. As a remedy, we modify the boundary integral formulation on Γ by adapting the approach of Combined Field Integral Equations (CFIE), first introduced in [5] for direct integral equations. The basic idea behind the CFIE approach is that Helmholtz boundary value problems with Robin (also called impedance) boundary conditions are always uniquely solvable, in contrast to interior pure Dirichlet (or pure Neumann) problems. The classical CFIEs thus rely on complex combinations of Dirichlet and Neumann traces, but neglecting the fact that they belong to different functional spaces; here, we adopt regularized CFIEs (see e.g. [4]), in which suitable compact operators map between Dirichlet and Neumann traces.

For the transmission problem (2.4) with $n = 0$, a variational formulation based on regularized CFIEs and the Costabel coupling was proposed in [13]. Here, to extend to the multi-domain case this coupling formulation immune to spurious resonances, we adopt a procedure inspired by [8, §5] (where Ω_Σ represented an impenetrable part of the medium).

8.1. Regularizing operator and trace transformation operator. The main step to obtain a combined field formulation that fixes (7.6) is to pick test functions satisfying generalized Robin conditions on Σ . These conditions are based on a linear *regularizing operator* $M: H^{-1/2}(\Sigma) \rightarrow H^{+1/2}(\Sigma)$ that satisfies

$$(8.1a) \quad M \text{ is compact,}$$

$$(8.1b) \quad \text{Im}\{\langle M\varphi, \bar{\varphi} \rangle_\Sigma\} > 0 \quad \forall \varphi \in H^{-1/2}(\Sigma) \setminus \{0\}.$$

For instance, if \tilde{M} is any second order strongly coercive real symmetric surface differential operator on Σ , then $M = \imath\tilde{M}$ matches the two conditions above.

Example 8.1. A convenient concrete choice for such an operator was proposed in [4, §4]: $M = \imath(-\Delta_\Sigma + \text{Id})^{-1}: H^{-1}(\Sigma) \rightarrow H^1(\Sigma)$, where Δ_Σ denotes the Laplace-Beltrami operator on the closed surface Σ . In this case, compactness of M :

$H^{-1/2}(\Sigma) \rightarrow H^{1/2}(\Sigma)$ follows from the continuity of $M: H^{-1}(\Sigma) \rightarrow H^1(\Sigma)$ and the compact embeddings $H^{-1/2}(\Sigma) \subset H^{-1}(\Sigma)$ and $H^1(\Sigma) \subset H^{1/2}(\Sigma)$.

Invoking the duality of the spaces $H^{1/2}(\Sigma)$ and $H^{-1/2}(\Sigma)$, we can also define the adjoint regularizing operator $M^*: H^{-1/2}(\Sigma) \rightarrow H^{1/2}(\Sigma)$ by

$$\langle M^*p, q \rangle_\Sigma := \langle Mq, p \rangle_\Sigma \quad \text{for all } p, q \in H^{-1/2}(\Sigma).$$

Note that M^* satisfies properties (8.1a)-(8.1b) if and only if M does. Now, given a regularizing operator M , we define the subspace of $H^1(\Omega_\Sigma) \times \mathbb{X}(\Gamma)$ satisfying generalized Robin conditions on Σ :

$$(8.2) \quad \mathbb{X}_M(\Sigma, \Gamma) := \{ (V, \mathbf{v}) \in H^1(\Omega_\Sigma) \times \mathbb{X}(\Gamma) \mid \mathbf{T}_D(\mathbf{v}) = M\mathbf{T}_N(\mathbf{v}) + \gamma_D^\Sigma(V) \}.$$

Please note the relationship between the space above and $\mathbb{X}(\Sigma, \Gamma)$ defined in (5.9), whose elements satisfy instead a Dirichlet matching across Σ . In fact, as shown in the lemma below, the space $\mathbb{X}_M(\Sigma, \Gamma)$ can be obtained as the image of the space $\mathbb{X}(\Sigma, \Gamma)$ through a trace transformation operator. Its definition involves the regularizing operator M , and a bounded extension operator $E_\Sigma: H^{1/2}(\Sigma) \rightarrow H^1(\mathbb{R}^d)$ that provides a right inverse of the trace operator γ_D^Σ (see e.g. [17, Lemma 3.36]). Then, we define the *trace transformation operator*

$$(8.3) \quad \begin{aligned} \mathbf{R}: H^1(\Omega_\Sigma) \times \mathbb{X}(\Gamma) &\rightarrow H^1(\Omega_\Sigma) \times \mathbb{X}(\Gamma) \\ \mathbf{R}(V, \mathbf{v}) &:= (V, \mathbf{v} + \mathbf{C}(\mathbf{v})) \\ \text{with } \mathbf{C}(\mathbf{v}) &:= (\gamma_D^j \circ E_\Sigma \circ M \circ \mathbf{T}_N(\mathbf{v}), 0)_{j=0}^n, \end{aligned}$$

where $\mathbf{C}: \mathbb{X}(\Gamma) \rightarrow \mathbb{X}(\Gamma)$ inherits compactness from M . Since $\mathbf{C}^2 = 0$, we have $\mathbf{R}^{-1}(V, \mathbf{v}) = (V, \mathbf{v} - \mathbf{C}(\mathbf{v}))$, and \mathbf{R} is an isomorphism. We can prove the following lemma, which is a variant of [8, Lemma 5.2].

Lemma 8.2 (Trace transformation). $\mathbf{R}(\mathbb{X}(\Sigma, \Gamma)) = \mathbb{X}_M(\Sigma, \Gamma)$.

Proof. Since $\mathbf{T}_D \circ \gamma \circ E_\Sigma = \text{Id}$ (where γ is the global trace operator defined in (5.2)), we have $\mathbf{T}_D \mathbf{C} = M\mathbf{T}_N$. Note also that $\mathbf{T}_N \mathbf{C} = 0$. Therefore, if $(V, \mathbf{v}) \in \mathbb{X}(\Sigma, \Gamma)$ we have $\mathbf{T}_D(\mathbf{v} + \mathbf{C}(\mathbf{v})) = \gamma_D^\Sigma(V) + M\mathbf{T}_N(\mathbf{v}) = \gamma_D^\Sigma(V) + M\mathbf{T}_N(\mathbf{v} + \mathbf{C}(\mathbf{v}))$, which shows that $\mathbf{R}(\mathbb{X}(\Sigma, \Gamma)) \subset \mathbb{X}_M(\Sigma, \Gamma)$. Now let $(V, \mathbf{v}) \in \mathbb{X}_M(\Sigma, \Gamma)$, then $\mathbf{T}_D(\mathbf{v} - \mathbf{C}(\mathbf{v})) = M\mathbf{T}_N(\mathbf{v}) + \gamma_D^\Sigma(V) - M\mathbf{T}_N(\mathbf{v}) = \gamma_D^\Sigma(V)$. Hence $\mathbf{R}^{-1}(\mathbb{X}_M(\Sigma, \Gamma)) \subset \mathbb{X}(\Sigma, \Gamma)$. \square

8.2. The formulation. In order to obtain the new combined field formulation, we proceed in a manner similar to Section 7, this time choosing test pairs (V', \mathbf{v}') in $\mathbb{X}_M(\Sigma, \Gamma)$ instead of $\mathbb{X}(\Sigma, \Gamma)$. Again the transmission problem (2.4) with solution $U \in H_{\text{loc}}^1(\mathbb{R}^d)$ will be reformulated as a coupled problem with solution

$$(8.4) \quad \begin{aligned} (U|_{\Omega_\Sigma}, \mathbf{u}) &\in \mathbb{X}(\Sigma, \Gamma) \\ \text{where } \mathbf{u} &= \gamma(U) = (\gamma^0(U), \dots, \gamma^n(U)). \end{aligned}$$

For $(V', \mathbf{v}') \in \mathbb{X}_M(\Sigma, \Gamma)$, applying Green's formula in Ω_Σ leads to $a_\Sigma(U, V') - \langle \gamma_N^\Sigma(U), \gamma_D^\Sigma(V') \rangle_\Sigma = F_\Sigma(V')$, as in Section 7. Next, we transform the boundary term following steps similar to (7.3), but with an extra term since here $\gamma_D^\Sigma(V') = \mathbf{T}_D(\mathbf{v}') - M\mathbf{T}_N(\mathbf{v}')$:

$$\begin{aligned} -\langle \gamma_N^\Sigma(U), \gamma_D^\Sigma(V') \rangle_\Sigma &= -\langle \mathbf{T}_N(\mathbf{u}), \mathbf{T}_D(\mathbf{v}') \rangle_\Sigma + \langle \mathbf{T}_N(\mathbf{u}), M\mathbf{T}_N(\mathbf{v}') \rangle_\Sigma \\ &= [\mathbf{u}, \Theta(\mathbf{v}')]_\Gamma / 2 + [\mathbf{T}(\mathbf{u}), \mathbf{T}(\mathbf{v}')]_\Sigma / 2 + \langle \mathbf{T}_N(\mathbf{u}), M\mathbf{T}_N(\mathbf{v}') \rangle_\Sigma, \end{aligned}$$

that is, by the boundary integral representations in the subdomains $\Omega_0, \dots, \Omega_n$ summarized by (7.5),

$$(8.5) \quad \begin{aligned} & - \langle \gamma_N^\Sigma(U), \gamma_D^\Sigma(V') \rangle_\Sigma \\ & = [A(u), \Theta(v')]_\Gamma + [u^{\text{inc}}, \Theta(v')]_\Gamma + [T(u), T(v')]_{\Sigma/2} + \langle T_N(u), MT_N(v') \rangle_\Sigma. \end{aligned}$$

Now, according to the parametrization of $\mathbb{X}_M(\Sigma, \Gamma)$ in Lemma 8.2, we have $(V', v') = R(V, v) = (V, (\text{Id} + C)v)$ for $(V, v) \in \mathbb{X}(\Sigma, \Gamma)$, and this representation can be injected into (8.5):

$$\begin{aligned} - \langle \gamma_N^\Sigma(U), \gamma_D^\Sigma(V) \rangle_\Sigma & = [A(u), \Theta(v)]_\Gamma + [A(u), \Theta C(v)]_\Gamma + [u^{\text{inc}}, \Theta(\text{Id} + C)v]_\Gamma \\ & \quad + [T(u), T(v)]_{\Sigma/2} + [T(u), TC(v)]_{\Sigma/2} + \langle T_N(u), T_D C(v) \rangle_\Sigma, \end{aligned}$$

where for the last term we have used $MT_N = T_D C$ and $T_N C = 0$. Moreover, by (3.5) and (5.5) we can rewrite the sum of the last two terms in the equation above as

$$[T(u), TC(v)]_{\Sigma/2} + \langle T_N(u), T_D C(v) \rangle_\Sigma = [T(u), \theta TC(v)]_{\Sigma/2} = -[u, \Theta C(v)]_\Gamma / 2.$$

In conclusion, summing up and defining the source term $\tilde{u}^{\text{inc}} \in \mathbb{H}(\Gamma)$ and the bilinear form $c: \mathbb{X}(\Gamma) \times \mathbb{X}(\Gamma) \rightarrow \mathbb{C}$

$$(8.6) \quad \begin{aligned} [\tilde{u}^{\text{inc}}, v]_\Gamma & := [u^{\text{inc}}, \Theta(\text{Id} + C)v]_\Gamma, \\ c(v, v) & := [(A - \text{Id}/2)v, \Theta C v]_\Gamma, \end{aligned}$$

we obtain the formulation

$$(8.7) \quad \boxed{\begin{aligned} & \text{Find } (U, u) \in \mathbb{X}(\Sigma, \Gamma) \text{ such that} \\ & a_\Sigma(U, V) + [A(u), \Theta(v)]_\Gamma + c(u, v) + [T(u), T(v)]_{\Sigma/2} \\ & = F_\Sigma(V) - [\tilde{u}^{\text{inc}}, v]_\Gamma \quad \forall (V, v) \in \mathbb{X}(\Sigma, \Gamma), \end{aligned}}$$

which we dub *single-trace combined field FEM-BEM formulation* because the test pairs that we have considered for its derivation comply with an impedance condition on the boundary, see (8.2).

Formulation (8.7) differs from (7.6) by terms involving the operator C only, which is compact. Hence, a *Gårding inequality* analogue to Proposition 7.2 also holds for (8.7). The additional benefit of using (8.2) is to eliminate the spurious resonance phenomenon and to yield systematic unique solvability. To prove this, we start by establishing an intermediate lemma.

Lemma 8.3. *Let $(U, u) \in \mathbb{X}(\Sigma, \Gamma)$ solve formulation (8.7) with $F_\Sigma \equiv 0$, $\tilde{u}^{\text{inc}} = 0$. Then we have*

$$(8.8) \quad \begin{aligned} \langle \gamma_N^\Sigma(U) - T_N(u), \gamma_D^\Sigma(V) \rangle_\Sigma + [(A - \text{Id}/2)u, \Theta(v)]_\Gamma & = 0 \\ \forall (V, v) \in \mathbb{X}_M(\Sigma, \Gamma). \end{aligned}$$

Proof. The proof essentially consists in rewinding the derivation of (8.7) in reverse order. First of all, observe that for $V \in H_0^1(\Omega_\Sigma)$ we have $(V, 0) \in \mathbb{X}(\Sigma, \Gamma)$. With this choice of test pairs we obtain $a_\Sigma(U, V) = 0$ for all $V \in H_0^1(\Omega_\Sigma)$, which leads to $\Delta U + \kappa_\Sigma^2 U = 0$ in Ω_Σ . As a consequence we have $a_\Sigma(U, V) = \langle \gamma_N^\Sigma(U), \gamma_D^\Sigma(V) \rangle_\Sigma$ for any $V \in H^1(\Omega_\Sigma)$. Coming back to (8.7) with homogeneous right-hand side, we obtain

$$\begin{aligned} 0 & = \langle \gamma_N^\Sigma(U), \gamma_D^\Sigma(V) \rangle_\Sigma + [A(u), \Theta(v)]_\Gamma + c(u, v) + [T(u), T(v)]_{\Sigma/2} \\ & \quad \forall (V, v) \in \mathbb{X}(\Sigma, \Gamma). \end{aligned}$$

Next plugging the definition of \mathbf{c} provided by (8.6) into the expression above, for a given $(V, \mathbf{v}) \in \mathbb{X}(\Sigma, \Gamma)$ we obtain

$$(8.9) \quad 0 = \langle \gamma_N^\Sigma(U), \gamma_D^\Sigma(V) \rangle_\Sigma + [(A - \text{Id}/2)\mathbf{u}, \Theta(\text{Id} + C)\mathbf{v}]_\Gamma \\ + [\mathbf{u}, \Theta(\mathbf{v})]_\Gamma / 2 + [\mathbb{T}(\mathbf{u}), \mathbb{T}(\mathbf{v})]_\Sigma / 2.$$

Next, since $\mathbf{u}, \mathbf{v} \in \mathbb{X}(\Gamma)$, we have $[\mathbf{u}, \Theta(\mathbf{v})]_\Gamma = -[\mathbb{T}(\mathbf{u}), \theta\mathbb{T}(\mathbf{v})]_\Sigma$. By (3.5), we conclude that $[\mathbf{u}, \Theta(\mathbf{v})]_\Gamma + [\mathbb{T}(\mathbf{u}), \mathbb{T}(\mathbf{v})]_\Sigma = -2\langle \mathbb{T}_N(\mathbf{u}), \mathbb{T}_D(\mathbf{v}) \rangle_\Sigma$. In addition, we have $\mathbb{T}_D(\mathbf{v}) = \gamma_D^\Sigma(V)$ since $(V, \mathbf{v}) \in \mathbb{X}(\Sigma, \Gamma)$. Plugging this into (8.9) leads to the identity

$$0 = \langle \gamma_N^\Sigma(U) - \mathbb{T}_N(\mathbf{u}), \gamma_D^\Sigma(V) \rangle_\Sigma + [(A - \text{Id}/2)\mathbf{u}, \Theta(\text{Id} + C)\mathbf{v}]_\Gamma \\ \forall (V, \mathbf{v}) \in \mathbb{X}(\Sigma, \Gamma).$$

To finish the proof there only remains to apply Lemma 8.2 \square

Proposition 8.4 (Injectivity). *Let $(U, \mathbf{u}) \in \mathbb{X}(\Sigma, \Gamma)$ solve formulation (8.7) with $F_\Sigma \equiv 0$, $\tilde{\mathbf{u}}^{\text{inc}} = 0$. Then $U = 0$, $\mathbf{u} = 0$.*

Proof. Consider the space $\mathbb{X}_M(\Gamma) := \{ \mathbf{v} \in \mathbb{X}(\Gamma) \mid \mathbb{T}_D(\mathbf{v}) = M\mathbb{T}_N(\mathbf{v}) \}$ and observe that we have $(0, \mathbf{v}) \in \mathbb{X}_M(\Sigma, \Gamma)$ for any $\mathbf{v} \in \mathbb{X}_M(\Gamma)$. As a consequence we can apply Lemma 8.3 above choosing $(V, \mathbf{v}) = (0, \mathbf{v})$ with $\mathbf{v} \in \mathbb{X}_M(\Gamma)$, so we obtain that

$$[(A - \text{Id}/2)\mathbf{u}, \Theta(\mathbf{v})]_\Gamma = 0 \quad \forall \mathbf{v} \in \mathbb{X}_M(\Gamma).$$

Let us denote $\mathbf{w} := (A - \text{Id}/2)\mathbf{u}$. Considering any $\mathbf{v} \in \mathbb{X}(\Gamma)$ such that $\mathbb{T}(\mathbf{v}) = 0$, we have $\Theta(\mathbf{v}) \in \mathbb{X}(\Gamma)$ with $\mathbb{T}(\Theta(\mathbf{v})) = 0$ so that $\Theta(\mathbf{v}) \in \mathbb{X}_M(\Gamma)$ and $[\mathbf{w}, \mathbf{v}]_\Gamma = [(A - \text{Id}/2)\mathbf{u}, \Theta \circ \Theta(\mathbf{v})]_\Gamma = 0$. Applying Lemma 5.2, we conclude that $\mathbf{w} \in \mathbb{X}(\Gamma)$. So, by (5.5), $[\mathbb{T}(\mathbf{w}), \theta\mathbb{T}(\mathbf{v})]_\Sigma = 0 \quad \forall \mathbf{v} \in \mathbb{X}_M(\Gamma)$, that is $\langle \mathbb{T}_D(\mathbf{w}) + M^*\mathbb{T}_N(\mathbf{w}), \mathbb{T}_N(\mathbf{v}) \rangle_\Sigma = 0 \quad \forall \mathbf{v} \in \mathbb{X}_M(\Gamma)$, which implies $\mathbb{T}_D(\mathbf{w}) = -M^*\mathbb{T}_N(\mathbf{w})$, as \mathbb{T}_N is surjective. From this and by (8.1b) we conclude that

$$0 \leq 2 \text{Im}\{ \langle M^*\mathbb{T}_N(\mathbf{w}), \mathbb{T}_N(\overline{\mathbf{w}}) \rangle_\Sigma \} \\ = -2 \text{Im}\{ \langle \mathbb{T}_D(\mathbf{w}), \mathbb{T}_N(\overline{\mathbf{w}}) \rangle_\Sigma \} \\ = -\text{Im}\{ [\mathbb{T}(\mathbf{w}), \mathbb{T}(\overline{\mathbf{w}})]_\Sigma \} = \text{Im}\{ [\mathbf{w}, \overline{\mathbf{w}}]_\Gamma \}.$$

Moreover, by construction, since $A^2 = \text{Id}/4$, we have $(A + \text{Id}/2)\mathbf{w} = (A + \text{Id}/2)(A - \text{Id}/2)\mathbf{u} = 0$, so we can write $[\mathbf{w}, \overline{\mathbf{w}}]_\Gamma / 2 = -[A(\mathbf{w}), \overline{\mathbf{w}}]_\Gamma$. Therefore, we deduce that $0 \leq \text{Im}\{ \langle M^*\mathbb{T}_N(\mathbf{w}), \mathbb{T}_N(\overline{\mathbf{w}}) \rangle_\Sigma \} = -\text{Im}[A(\mathbf{w}), \overline{\mathbf{w}}]_\Gamma \leq 0$ by applying Proposition 4.4 for the last inequality. Hence $\text{Im}\{ \langle M^*\mathbb{T}_N(\mathbf{w}), \mathbb{T}_N(\overline{\mathbf{w}}) \rangle_\Sigma = 0$. Next (8.1b) yields $\mathbb{T}_N(\mathbf{w}) = 0$ and, since $\mathbb{T}_D(\mathbf{w}) = -M^*\mathbb{T}_N(\mathbf{w})$, we finally obtain $\mathbb{T}(\mathbf{w}) = 0$. This implies that $[\mathbf{w}, \Theta(\mathbf{v})]_\Gamma = -[\mathbb{T}(\mathbf{w}), \theta\mathbb{T}(\mathbf{v})]_\Sigma = 0 \quad \forall \mathbf{v} \in \mathbb{X}(\Gamma)$, which rewrites

$$[(A - \text{Id}/2)\mathbf{u}, \mathbf{v}]_\Gamma = 0 \quad \forall \mathbf{v} \in \mathbb{X}(\Gamma).$$

Therefore, the second term in (8.8) vanishes for all $(V, \mathbf{v}) \in \mathbb{X}_M(\Sigma, \Gamma)$, and by Lemma 8.3 we conclude that $\gamma_N^\Sigma(U) = \mathbb{T}_N(\mathbf{u})$, which implies $\gamma^\Sigma(U) = \mathbb{T}(\mathbf{u})$ since $(U, \mathbf{u}) \in \mathbb{X}(\Sigma, \Gamma)$ by assumption. On the other hand we have

$$0 = [(A - \text{Id}/2)\mathbf{u}, \mathbf{v}]_\Gamma = [(A + \text{Id}/2)\mathbf{u}, \mathbf{v}]_\Gamma - [\mathbf{u}, \mathbf{v}]_\Gamma \\ = [(A + \text{Id}/2)\mathbf{u}, \mathbf{v}]_\Gamma + [\mathbb{T}(\mathbf{u}), \mathbb{T}(\mathbf{v})]_\Sigma = [(A + \text{Id}/2)\mathbf{u}, \mathbf{v}]_\Gamma \\ \text{for all } \mathbf{v} \in \mathbb{X}(\Gamma) \text{ such that } \mathbb{T}(\mathbf{v}) = 0.$$

From this last equality, applying Lemma 5.2, we obtain that $(A + \text{Id}/2)\mathbf{u} \in \mathbb{X}(\Gamma)$. Moreover, since we established that $\mathbb{T}(\mathbf{u}) = \gamma^\Sigma(U)$ and $\mathbb{T}(\mathbf{w}) = \mathbb{T}((A - \text{Id}/2)\mathbf{u}) = 0$,

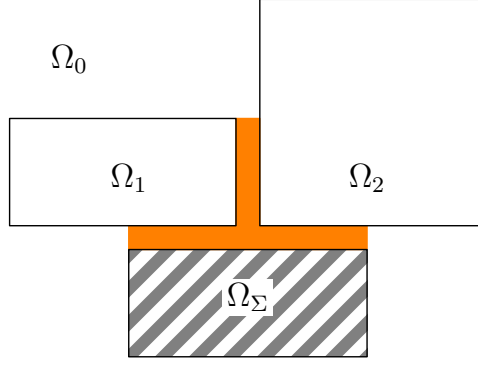


FIGURE 4. Illustration of the gap idea.

we obtain

$$\mathbb{T}((\mathbf{A} + \mathbf{Id}/2)\mathbf{u}) = \mathbb{T}(\mathbf{w}) + \mathbb{T}(\mathbf{u}) = \gamma^\Sigma(U).$$

Finally, let us define $\tilde{U} \in L^2_{\text{loc}}(\mathbb{R}^d)$ by $\tilde{U}(\mathbf{x}) = U(\mathbf{x})$ for $\mathbf{x} \in \Omega_\Sigma$, and $\tilde{U}(\mathbf{x}) = \mathbf{G}_{\kappa_j}^j(\mathbf{u}_j)(\mathbf{x})$ for $\mathbf{x} \in \Omega_j, j = 0, \dots, n$. By construction we have

$$\begin{aligned} \Delta \tilde{U} + \kappa_\Sigma^2 \tilde{U} &= 0 \quad \text{in } \Omega_\Sigma \\ \Delta \tilde{U} + \kappa_j^2 \tilde{U} &= 0 \quad \text{in } \Omega_j \quad \forall j = 0 \dots n \\ \tilde{U} &\text{ is } \kappa_0\text{-outgoing radiating.} \end{aligned}$$

Let us prove that \tilde{U} satisfies the Neumann and Dirichlet transmission conditions through the skeleton of the subdomain partition. Using (4.7), we have established that $\gamma(\tilde{U}) = (\gamma^j \mathbf{G}_{\kappa_j}^j(\mathbf{u}_j))_{j=0 \dots n} = (\mathbf{A} + \mathbf{Id}/2)\mathbf{u} \in \mathbb{X}(\Gamma)$ on the one hand, and

$$\mathbb{T}(\gamma(\tilde{U})) = \mathbb{T}((\mathbf{A} + \mathbf{Id}/2)\mathbf{u}) = \gamma^\Sigma(U) = \gamma^\Sigma(\tilde{U}).$$

Hence, by Lemma 5.3 we see that \tilde{U} is solution to the transmission problem (2.4) with zero right-hand side. Since this boundary value problem admits a unique solution $\tilde{U} \equiv 0$, we get $U = 0$, $\mathbb{T}(\mathbf{u}) = \gamma^\Sigma(U) = 0$ and $(\mathbf{A} + \mathbf{Id}/2)\mathbf{u} = 0$, which implies in particular

$$\begin{aligned} \mathbf{u} &\in \mathbb{X}(\Gamma) \text{ with } \mathbb{T}(\mathbf{u}) = 0 \\ \text{and } [\mathbf{A}(\mathbf{u}), \mathbf{v}]_\Gamma &= 0 \quad \forall \mathbf{v} \in \mathbb{X}(\Gamma). \end{aligned}$$

According to [22, Thm. 4.1] or [7, Prop. A.1], the homogeneous formulation above has a unique solution, hence finally $\mathbf{u} = 0$. \square

9. MULTI-TRACE FEM-BEM FORMULATION

Single-trace formulations are not very flexible because the spaces $\mathbb{X}(\Sigma, \Gamma)$ and $\mathbb{X}(\Gamma)$ contain the transmission conditions in strong form, which constitutes an obstacle to operator preconditioning [9]. Multi-trace formulations are designed to tackle this issue. The heuristic idea is to apply the single-trace FEM-BEM formulation (7.6) to gap configurations with vanishing gap, see Figure 4.

In the gap setting (Figure 4, right), where the gap is filled with the same propagation medium as Ω_0 , the boundary of Ω_0 can be partitioned as $\Gamma_0 = \cup_{j=1}^n \Gamma_j \cup \Sigma$,

and $\mathbb{X}(\Sigma, \Gamma)$ is isomorphic to the space $\mathbb{H}^1(\Omega_\Sigma) \times \widehat{\mathbb{H}}(\Gamma)$, where the *multi-trace space* $\widehat{\mathbb{H}}(\Gamma)$, introduced in [8, §6.1], is defined as

$$\widehat{\mathbb{H}}(\Gamma) := \mathbb{H}(\Gamma_1) \times \cdots \times \mathbb{H}(\Gamma_n) \times \mathbb{H}^{-1/2}(\Sigma).$$

The isomorphism is given by the map $s: (U, \mathbf{u}) \mapsto (U, (\mathbf{u}_1, \dots, \mathbf{u}_n, \mathbb{T}_N(\mathbf{u})))$, whose inverse, in the gap setting, is the map $t: (U, (\hat{\mathbf{u}}_1, \dots, \hat{\mathbf{u}}_n, p_\Sigma)) \mapsto (U, (\tilde{\mathbf{u}}_0, \hat{\mathbf{u}}_1, \dots, \hat{\mathbf{u}}_n))$, where

$$\tilde{\mathbf{u}}_0(\mathbf{x}) := \begin{cases} \phi(\hat{\mathbf{u}}_j)(\mathbf{x}), & \mathbf{x} \in \Gamma_j, j = 1, \dots, n, \\ \phi(\gamma_\Sigma^\Sigma U, p_\Sigma)(\mathbf{x}), & \mathbf{x} \in \Sigma. \end{cases} \quad \text{with } \phi(u, p) := (u, -p).$$

The multi-trace space $\widehat{\mathbb{H}}(\Gamma)$ differs from the multi-trace space $\mathbb{H}(\Gamma)$ introduced in §5 since it does not contain any contribution on Γ_0 ; instead, it includes Neumann traces on Σ . It will enter the functional framework for the global multi-trace formulation, also for general geometrical settings, such as in Figure 4, left. Note that the unknown traces are doubled on each interface that separates two (bounded) subdomains, hence the attribute *multi-trace*. We equip the space $\widehat{\mathbb{H}}(\Gamma)$ with the standard norm of the Cartesian product:

$$\|\hat{\mathbf{v}}\|_{\widehat{\mathbb{H}}(\Gamma)}^2 := \|\hat{\mathbf{v}}_1\|_{\mathbb{H}(\Gamma_1)}^2 + \cdots + \|\hat{\mathbf{v}}_n\|_{\mathbb{H}(\Gamma_n)}^2 + \|q_\Sigma\|_{\mathbb{H}^{-1/2}(\Sigma)}^2, \\ \text{for } \hat{\mathbf{v}} = (\hat{\mathbf{v}}_1, \dots, \hat{\mathbf{v}}_n, q_\Sigma) \in \widehat{\mathbb{H}}(\Gamma).$$

The dual space of $\widehat{\mathbb{H}}(\Gamma)$ is the space $\check{\mathbb{H}}(\Gamma) := \mathbb{H}(\Gamma_1) \times \cdots \times \mathbb{H}(\Gamma_n) \times \mathbb{H}^{1/2}(\Sigma)$, and we adopt the skew-symmetric duality pairing

$$\langle \hat{\mathbf{u}}, \hat{\mathbf{v}} \rangle := [\hat{\mathbf{u}}_1, \hat{\mathbf{v}}_1]_{\Gamma_1} + \cdots + [\hat{\mathbf{u}}_n, \hat{\mathbf{v}}_n]_{\Gamma_n} + \langle u_\Sigma, q_\Sigma \rangle_\Sigma,$$

for $\hat{\mathbf{u}} = (\hat{\mathbf{u}}_1, \dots, \hat{\mathbf{u}}_n, u_\Sigma) \in \check{\mathbb{H}}(\Gamma)$, $\hat{\mathbf{v}} = (\hat{\mathbf{v}}_1, \dots, \hat{\mathbf{v}}_n, q_\Sigma) \in \widehat{\mathbb{H}}(\Gamma)$.

For notational convenience it is useful to introduce also the space $\widehat{\widehat{\mathbb{H}}}(\Gamma) := \mathbb{H}(\Gamma_1) \times \cdots \times \mathbb{H}(\Gamma_n) \times \mathbb{H}(\Sigma)$, with the skew-symmetric duality pairing

$$\langle \hat{\hat{\mathbf{u}}}, \hat{\hat{\mathbf{v}}} \rangle := [\mathbf{u}_1, \mathbf{v}_1]_{\Gamma_1} + \cdots + [\mathbf{u}_n, \mathbf{v}_n]_{\Gamma_n} + [\mathbf{u}_\Sigma, \mathbf{v}_\Sigma]_\Sigma,$$

for $\hat{\hat{\mathbf{u}}} = (\mathbf{u}_1, \dots, \mathbf{u}_n, \mathbf{u}_\Sigma)$, $\hat{\hat{\mathbf{v}}} = (\mathbf{v}_1, \dots, \mathbf{v}_n, \mathbf{v}_\Sigma) \in \widehat{\widehat{\mathbb{H}}}(\Gamma)$.

9.1. Derivation of the formulation. The multi-trace FEM-BEM formulation can be seen as the single-trace FEM-BEM formulation (7.6) applied to gap configurations with vanishing gap. However, it is difficult to study the vanishing gap limit with a rigorous mathematical argument. Following the idea in [7, §8], the multi-trace formulation is rather obtained by trying to eliminate from the single-trace formulation (7.6) all the contributions on Γ_0 . Essentially this is achieved by exploiting repeatedly the modified polarity identity (5.5) and the variational characterization of transmission conditions (5.7).

We first reshape the right-hand side of formulation (7.6), more precisely the term $-[\mathbf{u}^{\text{inc}}, \Theta(\mathbf{v})]_\Gamma$, where $\mathbf{u}^{\text{inc}} = (\gamma^0 U_{\text{inc}}, 0, \dots, 0)$. Since $U_{\text{inc}} \in \mathbb{H}_{\text{loc}}(\Delta, \mathbb{R}^d)$, we can apply (5.7) to write, for $\mathbf{v} \in \mathbb{X}(\Gamma)$ (from which $\Theta(\mathbf{v}) \in \mathbb{X}(\Gamma)$),

$$\begin{aligned} -[\mathbf{u}^{\text{inc}}, \Theta(\mathbf{v})]_\Gamma &= -[\gamma^0 U_{\text{inc}}, \theta(\mathbf{v}_0)]_{\Gamma_0} + [\gamma(U_{\text{inc}}), \Theta(\mathbf{v})]_\Gamma + [\gamma^\Sigma U_{\text{inc}}, \mathbb{T}(\Theta(\mathbf{v}))]_\Sigma \\ (9.1) \quad &= \sum_{j=1}^n [\gamma^j U_{\text{inc}}, \theta(\mathbf{v}_j)]_{\Gamma_j} + [\gamma^\Sigma U_{\text{inc}}, \theta \mathbb{T}(\mathbf{v})]_\Sigma. \end{aligned}$$

Next, we focus on the left-hand side of formulation (7.6). By (5.5) we write

$$\begin{aligned}
(9.2) \quad & [A(\mathbf{u}), \Theta(\mathbf{v})]_{\Gamma} = [A(\mathbf{u}), \Theta(\mathbf{v})]_{\Gamma} + ([\mathbf{u}, \Theta(\mathbf{v})]_{\Gamma} + [\mathbb{T}(\mathbf{u}), \mathbb{T}(\Theta(\mathbf{v}))]_{\Sigma})/2 \\
& = \sum_{j=0}^n [(A_{\kappa_j}^j + \text{Id}/2)\mathbf{u}_j, \theta(\mathbf{v}_j)]_{\Gamma_j} + [\mathbb{T}(\mathbf{u}), \mathbb{T}(\Theta(\mathbf{v}))]_{\Sigma}/2 \\
& = [\gamma^0 \mathbf{G}_{\kappa_0}^0(\mathbf{u}_0), \theta(\mathbf{v}_0)]_{\Gamma_0} + \sum_{j=1}^n [(A_{\kappa_j}^j + \text{Id}/2)\mathbf{u}_j, \theta(\mathbf{v}_j)]_{\Gamma_j} + [\mathbb{T}(\mathbf{u}), \mathbb{T}(\Theta(\mathbf{v}))]_{\Sigma}/2,
\end{aligned}$$

where we have brought out the term with contributions on Γ_0 that needs to be rewritten, and applied (4.7). Now, since $(\mathbf{u}, \mathbb{T}(\mathbf{u})) \in \tilde{\mathbb{X}}(\Gamma)$ (see definition (5.8)), [7, Lemma 8.1] yields

$$\sum_{j=0}^n \mathbf{G}_{\kappa_0}^j(\mathbf{u}_j)(\mathbf{x}) + \mathbf{G}_{\kappa_0}^{\Sigma}(\mathbb{T}(\mathbf{u}))(\mathbf{x}) = 0 \quad \text{for } \mathbf{x} \in \Omega_0,$$

thus, taking interior traces on Γ_0 and testing against $\theta(\mathbf{v}_0)$, we get

$$(9.3) \quad [\gamma^0 \mathbf{G}_{\kappa_0}^0(\mathbf{u}_0), \theta(\mathbf{v}_0)]_{\Gamma_0} = - \sum_{j=1}^n [\gamma^0 \mathbf{G}_{\kappa_0}^j(\mathbf{u}_j), \theta(\mathbf{v}_0)]_{\Gamma_0} - [\gamma^0 \mathbf{G}_{\kappa_0}^{\Sigma}(\mathbb{T}(\mathbf{u})), \theta(\mathbf{v}_0)]_{\Gamma_0}.$$

We wish to examine each term on the right-hand side of (9.3). To this purpose, take an arbitrary $j = 1, \dots, n$ and follow the procedure described in Remark 5.4 to construct the element $\tilde{\mathbf{w}} = (\mathbf{w}, \mathbf{w}_{\Sigma}) = (\mathbf{w}_0, \dots, \mathbf{w}_n, \mathbf{w}_{\Sigma}) \in \tilde{\mathbb{X}}(\Gamma)$ defined as

$$\mathbf{w}_q := \gamma^q \mathbf{G}_{\kappa_0}^j(\mathbf{u}_j) \quad \text{if } q \neq j, \quad \mathbf{w}_j := \gamma_c^j \mathbf{G}_{\kappa_0}^j(\mathbf{u}_j), \quad \mathbf{w}_{\Sigma} := \mathbb{T}(\mathbf{w}) = \gamma^{\Sigma} \mathbf{G}_{\kappa_0}^j(\mathbf{u}_j).$$

So, by (5.5) we have, for $\mathbf{v} \in \mathbb{X}(\Gamma)$, $[\mathbf{w}, \Theta(\mathbf{v})]_{\Gamma} + [\mathbf{w}_{\Sigma}, \mathbb{T}(\Theta(\mathbf{v}))]_{\Sigma} = 0$, that is, after splitting,

$$\begin{aligned}
[\gamma^0 \mathbf{G}_{\kappa_0}^j(\mathbf{u}_j), \theta(\mathbf{v}_0)]_{\Gamma_0} &= - \sum_{q=1, q \neq j}^n [\gamma^q \mathbf{G}_{\kappa_0}^j(\mathbf{u}_j), \theta(\mathbf{v}_q)]_{\Gamma_q} \\
&\quad - [\gamma_c^j \mathbf{G}_{\kappa_0}^j(\mathbf{u}_j), \theta(\mathbf{v}_j)]_{\Gamma_j} - [\gamma^{\Sigma} \mathbf{G}_{\kappa_0}^j(\mathbf{u}_j), \mathbb{T}(\Theta(\mathbf{v}))]_{\Sigma},
\end{aligned}$$

and in a similar way, using again the construction in Remark 5.4, we obtain

$$[\gamma^0 \mathbf{G}_{\kappa_0}^{\Sigma}(\mathbb{T}(\mathbf{u})), \theta(\mathbf{v}_0)]_{\Gamma_0} = - \sum_{q=1}^n [\gamma^q \mathbf{G}_{\kappa_0}^{\Sigma}(\mathbb{T}(\mathbf{u})), \theta(\mathbf{v}_q)]_{\Gamma_q} - [\gamma_c^{\Sigma} \mathbf{G}_{\kappa_0}^{\Sigma}(\mathbb{T}(\mathbf{u})), \mathbb{T}(\Theta(\mathbf{v}))]_{\Sigma}.$$

Then, substituting the last two expressions in (9.3) we get

$$\begin{aligned}
[\gamma^0 \mathbf{G}_{\kappa_0}^0(\mathbf{u}_0), \theta(\mathbf{v}_0)]_{\Gamma_0} &= \sum_{j=1}^n \left(\sum_{q=1, q \neq j}^n [\gamma^q \mathbf{G}_{\kappa_0}^j(\mathbf{u}_j), \theta(\mathbf{v}_q)]_{\Gamma_q} + [\gamma^{\Sigma} \mathbf{G}_{\kappa_0}^j(\mathbf{u}_j), \mathbb{T}(\Theta(\mathbf{v}))]_{\Sigma} \right) \\
&+ \sum_{q=1}^n [\gamma^q \mathbf{G}_{\kappa_0}^{\Sigma}(\mathbb{T}(\mathbf{u})), \theta(\mathbf{v}_q)]_{\Gamma_q} + \sum_{j=1}^n [\gamma_c^j \mathbf{G}_{\kappa_0}^j(\mathbf{u}_j), \theta(\mathbf{v}_j)]_{\Gamma_j} + [\gamma_c^{\Sigma} \mathbf{G}_{\kappa_0}^{\Sigma}(\mathbb{T}(\mathbf{u})), \mathbb{T}(\Theta(\mathbf{v}))]_{\Sigma}.
\end{aligned}$$

Finally, we plug the equation above into the initial rewriting (9.2) and, recalling that by (4.8) $\gamma_c^j \mathbf{G}_{\kappa_0}^j = \mathbf{A}_{\kappa_0}^j - \text{Id}/2$, we obtain

$$\begin{aligned} [\mathbf{A}(\mathbf{u}), \Theta(\mathbf{v})]_{\Gamma} &= \sum_{j=1}^n [(\mathbf{A}_{\kappa_j}^j + \text{Id}/2)\mathbf{u}_j, \theta(\mathbf{v}_j)]_{\Gamma_j} + [\mathbf{T}(\mathbf{u}), \mathbf{T}(\Theta(\mathbf{v}))]_{\Sigma}/2 \\ &\quad + \sum_{j=1}^n [(\mathbf{A}_{\kappa_0}^j - \text{Id}/2)\mathbf{u}_j, \theta(\mathbf{v}_j)]_{\Gamma_j} + [(\mathbf{A}_{\kappa_0}^{\Sigma} - \text{Id}/2)\mathbf{T}(\mathbf{u}), \mathbf{T}(\Theta(\mathbf{v}))]_{\Sigma} \\ &\quad + \sum_{j=1}^n \left(\sum_{q=1, q \neq j}^n [\gamma^q \mathbf{G}_{\kappa_0}^j(\mathbf{u}_j), \theta(\mathbf{v}_q)]_{\Gamma_q} + [\gamma^{\Sigma} \mathbf{G}_{\kappa_0}^j(\mathbf{u}_j), \mathbf{T}(\Theta(\mathbf{v}))]_{\Sigma} \right) \\ &\quad + \sum_{q=1}^n [\gamma^q \mathbf{G}_{\kappa_0}^{\Sigma}(\mathbf{T}(\mathbf{u})), \theta(\mathbf{v}_q)]_{\Gamma_q}, \end{aligned}$$

that is, simplifying,

$$\begin{aligned} (9.4) \quad [\mathbf{A}(\mathbf{u}), \Theta(\mathbf{v})]_{\Gamma} &= \sum_{j=1}^n [(\mathbf{A}_{\kappa_j}^j + \mathbf{A}_{\kappa_0}^j)\mathbf{u}_j, \theta(\mathbf{v}_j)]_{\Gamma_j} + [\mathbf{A}_{\kappa_0}^{\Sigma} \mathbf{T}(\mathbf{u}), \theta \mathbf{T}(\mathbf{v})]_{\Sigma} \\ &\quad + \sum_{j=1}^n \left(\sum_{q=1, q \neq j}^n [\gamma^q \mathbf{G}_{\kappa_0}^j(\mathbf{u}_j), \theta(\mathbf{v}_q)]_{\Gamma_q} + [\gamma^{\Sigma} \mathbf{G}_{\kappa_0}^j(\mathbf{u}_j), \theta \mathbf{T}(\mathbf{v})]_{\Sigma} \right) \\ &\quad + \sum_{q=1}^n [\gamma^q \mathbf{G}_{\kappa_0}^{\Sigma}(\mathbf{T}(\mathbf{u})), \theta(\mathbf{v}_q)]_{\Gamma_q}. \end{aligned}$$

To sum up, if we define the continuous linear operator $\hat{\hat{\mathbf{A}}}: \hat{\hat{\mathbb{H}}}(\Gamma) \rightarrow \hat{\hat{\mathbb{H}}}(\Gamma)$ as

$$(9.5) \quad \hat{\hat{\mathbf{A}}} := \begin{bmatrix} \mathbf{A}_{\kappa_1}^1 + \mathbf{A}_{\kappa_0}^1 & \gamma^1 \mathbf{G}_{\kappa_0}^2 & \cdots & \gamma^1 \mathbf{G}_{\kappa_0}^n & \gamma^1 \mathbf{G}_{\kappa_0}^{\Sigma} \\ \gamma^2 \mathbf{G}_{\kappa_0}^1 & \mathbf{A}_{\kappa_2}^2 + \mathbf{A}_{\kappa_0}^2 & & \gamma^2 \mathbf{G}_{\kappa_0}^n & \gamma^2 \mathbf{G}_{\kappa_0}^{\Sigma} \\ \vdots & & \ddots & & \vdots \\ \gamma^n \mathbf{G}_{\kappa_0}^1 & \gamma^n \mathbf{G}_{\kappa_0}^2 & & \mathbf{A}_{\kappa_n}^n + \mathbf{A}_{\kappa_0}^n & \gamma^n \mathbf{G}_{\kappa_0}^{\Sigma} \\ \gamma^{\Sigma} \mathbf{G}_{\kappa_0}^1 & \gamma^{\Sigma} \mathbf{G}_{\kappa_0}^2 & \cdots & \gamma^{\Sigma} \mathbf{G}_{\kappa_0}^n & \mathbf{A}_{\kappa_0}^{\Sigma} \end{bmatrix}$$

and for compact notation we set

$$\begin{aligned} \hat{\hat{\mathbf{u}}} &:= (\mathbf{u}_1, \dots, \mathbf{u}_n, (\gamma_{\text{D}}^{\Sigma} U, \mathbf{T}_{\text{N}}(\mathbf{u}))), \quad \hat{\hat{\mathbf{v}}} := (\mathbf{v}_1, \dots, \mathbf{v}_n, (\gamma_{\text{D}}^{\Sigma} V, \mathbf{T}_{\text{N}}(\mathbf{v}))), \\ \hat{\hat{\mathbf{f}}} &:= (\gamma^1 U_{\text{inc}}, \dots, \gamma^n U_{\text{inc}}, \gamma^{\Sigma} U_{\text{inc}}), \end{aligned}$$

using the transformed expressions (9.4) and (9.1), where we additionally replace $\mathbf{T}_{\text{D}}(\mathbf{u}) = \gamma_{\text{D}}^{\Sigma} U$, $\mathbf{T}_{\text{D}}(\mathbf{v}) = \gamma_{\text{D}}^{\Sigma} V$, we have found that the single-trace FEM-BEM formulation (7.6) is equivalent to

find $(U, \mathbf{u}) \in \mathbb{X}(\Sigma, \Gamma)$ such that

$$\begin{aligned} a_{\Sigma}(U, V) + \|\hat{\hat{\mathbf{A}}}(\hat{\hat{\mathbf{u}}}), \Theta(\hat{\hat{\mathbf{v}}})\| + \frac{1}{2} \left[\left(\begin{array}{c} \gamma_{\text{D}}^{\Sigma} U \\ \mathbf{T}_{\text{N}}(\mathbf{u}) \end{array} \right), \left(\begin{array}{c} \gamma_{\text{D}}^{\Sigma} V \\ \mathbf{T}_{\text{N}}(\mathbf{v}) \end{array} \right) \right]_{\Sigma} \\ = F_{\Sigma}(V) + \|\hat{\hat{\mathbf{f}}}, \Theta(\hat{\hat{\mathbf{v}}})\| \quad \forall (V, \mathbf{v}) \in \mathbb{X}(\Sigma, \Gamma). \end{aligned}$$

This new expression does not have any contributions on Γ_0 , except for $\mathbf{T}_{\text{N}}(\mathbf{u})$, $\mathbf{T}_{\text{N}}(\mathbf{v}) \in \mathbf{H}^{-1/2}(\Sigma)$ that in particular depend on p_0, q_0 . In the spirit of [7, §9] and the discussion at the beginning of this section, we now replace the functional space $\mathbb{X}(\Sigma, \Gamma)$ by the space with decoupled traces $\mathbf{H}^1(\Omega_{\Sigma}) \times \hat{\hat{\mathbb{H}}}(\Gamma)$, which is a more

flexible functional setting. In particular, we replace $\mathbb{T}_N(\mathbf{u}), \mathbb{T}_N(\mathbf{v})$ by some $p_\Sigma, q_\Sigma \in \mathbb{H}^{-1/2}(\Sigma)$. Then, we define the *global multi-trace FEM-BEM formulation*

$$(9.6) \quad \boxed{\begin{aligned} & \text{find } (U, \hat{\mathbf{u}}) \in \mathbb{H}^1(\Omega_\Sigma) \times \widehat{\mathbb{H}}(\Gamma), \hat{\mathbf{u}} = (\hat{u}_1, \dots, \hat{u}_n, p_\Sigma), \text{ such that} \\ & a_\Sigma(U, V) + \{\widehat{\mathbb{A}}(\hat{\mathbf{u}}), \Theta(\hat{\mathbf{v}})\} + \frac{1}{2} \left[\begin{pmatrix} \gamma_D^\Sigma U \\ p_\Sigma \end{pmatrix}, \begin{pmatrix} \gamma_D^\Sigma V \\ q_\Sigma \end{pmatrix} \right]_\Sigma \\ & = F_\Sigma(V) + \{\widehat{\mathbb{f}}, \Theta(\hat{\mathbf{v}})\} \quad \forall (V, \hat{\mathbf{v}}) \in \mathbb{H}^1(\Omega_\Sigma) \times \widehat{\mathbb{H}}(\Gamma), \hat{\mathbf{v}} = (\hat{v}_1, \dots, \hat{v}_n, q_\Sigma) \\ & \text{where } \hat{\mathbf{u}} := (\hat{u}_1, \dots, \hat{u}_n, (\gamma_D^\Sigma U, p_\Sigma)), \quad \hat{\mathbf{v}} := (\hat{v}_1, \dots, \hat{v}_n, (\gamma_D^\Sigma V, q_\Sigma)), \\ & \quad \widehat{\mathbb{f}} := (\gamma^1 U_{\text{inc}}, \dots, \gamma^n U_{\text{inc}}, \gamma^\Sigma U_{\text{inc}}). \end{aligned}}$$

Note that $\widehat{\mathbb{A}}$, defined in (9.5), is a full-matrix operator with off-diagonal terms $\gamma^q \mathbf{G}_{\kappa_0}^j$, $\gamma^\Sigma \mathbf{G}_{\kappa_0}^j$, $\gamma^q \mathbf{G}_{\kappa_0}^\Sigma$ that couple all subdomains with all other subdomains, hence the attribute *global*. The attribute *multi-trace* comes from the fact that the unknown traces are doubled on each interface that separates two (bounded) subdomains.

The expanded expression for the multi-trace FEM-BEM formulation (9.6) reads:

$$(9.7) \quad \begin{aligned} & \text{find } (U, \hat{\mathbf{u}}) \in \mathbb{H}^1(\Omega_\Sigma) \times \widehat{\mathbb{H}}(\Gamma), \hat{\mathbf{u}} = (\hat{u}_1, \dots, \hat{u}_n, p_\Sigma), \text{ such that} \\ & a_\Sigma(U, V) + \sum_{j=1}^n [(A_{\kappa_j}^j + A_{\kappa_0}^j) \hat{u}_j, \theta(\hat{v}_j)]_{\Gamma_j} + \left[A_{\kappa_0}^\Sigma \begin{pmatrix} \gamma_D^\Sigma U \\ p_\Sigma \end{pmatrix}, \theta \begin{pmatrix} \gamma_D^\Sigma V \\ q_\Sigma \end{pmatrix} \right]_\Sigma \\ & + \sum_{j=1}^n \left(\sum_{q=1, q \neq j}^n [\gamma^q \mathbf{G}_{\kappa_0}^j(\hat{u}_j), \theta(\hat{v}_q)]_{\Gamma_q} + \left[\gamma^\Sigma \mathbf{G}_{\kappa_0}^j(\hat{u}_j), \theta \begin{pmatrix} \gamma_D^\Sigma V \\ q_\Sigma \end{pmatrix} \right]_\Sigma \right) \\ & + \sum_{q=1}^n \left[\gamma^q \mathbf{G}_{\kappa_0}^\Sigma \begin{pmatrix} \gamma_D^\Sigma U \\ p_\Sigma \end{pmatrix}, \theta(\hat{v}_q) \right]_{\Gamma_q} + \frac{1}{2} \left[\begin{pmatrix} \gamma_D^\Sigma U \\ p_\Sigma \end{pmatrix}, \begin{pmatrix} \gamma_D^\Sigma V \\ q_\Sigma \end{pmatrix} \right]_\Sigma \\ & = F_\Sigma(V) + \sum_{j=1}^n [\gamma^j U_{\text{inc}}, \theta(\hat{v}_j)]_{\Gamma_j} + \left[\gamma^\Sigma U_{\text{inc}}, \theta \begin{pmatrix} \gamma_D^\Sigma V \\ q_\Sigma \end{pmatrix} \right]_\Sigma \end{aligned}$$

for all $(V, \hat{\mathbf{v}}) \in \mathbb{H}^1(\Omega_\Sigma) \times \widehat{\mathbb{H}}(\Gamma), \hat{\mathbf{v}} = (\hat{v}_1, \dots, \hat{v}_n, q_\Sigma)$.

Remark 9.1. Note that in the case $n = 0$ of a single (heterogeneous) scatterer the multi-trace formulation (9.6) reduces to the Costabel coupling (6.5), just as the single-trace formulation (7.6). Indeed, in this case $\mathbb{R}^d = \overline{\Omega}_0 \cup \overline{\Omega}_\Sigma$ and $\widehat{\mathbb{H}}(\Gamma) = \mathbb{H}^{-1/2}(\Sigma)$. Then the expanded expression (9.7) simply becomes: find $(U, p_\Sigma) \in \mathbb{H}^1(\Omega_\Sigma) \times \mathbb{H}^{-1/2}(\Sigma)$ such that

$$\begin{aligned} & a_\Sigma(U, V) + \left[A_{\kappa_0}^\Sigma \begin{pmatrix} \gamma_D^\Sigma U \\ p_\Sigma \end{pmatrix}, \begin{pmatrix} -\gamma_D^\Sigma V \\ q_\Sigma \end{pmatrix} \right]_\Sigma + \frac{1}{2} \left[\begin{pmatrix} \gamma_D^\Sigma U \\ p_\Sigma \end{pmatrix}, \begin{pmatrix} \gamma_D^\Sigma V \\ q_\Sigma \end{pmatrix} \right]_\Sigma = \\ & F_\Sigma(V) + \left[\gamma^\Sigma U_{\text{inc}}, \begin{pmatrix} -\gamma_D^\Sigma V \\ q_\Sigma \end{pmatrix} \right]_\Sigma \quad \forall (V, q_\Sigma) \in \mathbb{H}^1(\Omega_\Sigma) \times \mathbb{H}^{-1/2}(\Sigma). \end{aligned}$$

Moreover, set $\mathbf{u} = (u_0, p_0) = (\gamma_D^\Sigma U, -p_\Sigma)$ and $\mathbf{v} = (v_0, q_0) = (\gamma_D^\Sigma V, -q_\Sigma)$, so that $(U, \mathbf{u}) \in \mathbb{X}(\Sigma, \Gamma)$ and $(V, \mathbf{v}) \in \mathbb{X}(\Sigma, \Gamma)$. Note that $\mathbb{T}(\mathbf{u}) = (\gamma_D^\Sigma U, p_\Sigma)$, $\mathbb{T}(\mathbf{v}) = (\gamma_D^\Sigma V, q_\Sigma)$, and $\gamma^\Sigma U_{\text{inc}} = (\gamma_D^0 U_{\text{inc}}, -\gamma_N^0 U_{\text{inc}})$. We can also write

$$A_{\kappa_0}^\Sigma \begin{pmatrix} \gamma_D^\Sigma U \\ p_\Sigma \end{pmatrix} = A_{\kappa_0}^\Sigma \begin{pmatrix} u_0 \\ -p_0 \end{pmatrix} = \begin{pmatrix} \{\gamma_D^0\} \\ -\{\gamma_N^0\} \end{pmatrix} \circ \begin{pmatrix} -\mathbf{G}_{\kappa_0}^0 \begin{pmatrix} u_0 \\ p_0 \end{pmatrix} \end{pmatrix} = \begin{pmatrix} -\{\gamma_D^0\} \\ \{\gamma_N^0\} \end{pmatrix} \circ \mathbf{G}_{\kappa_0}^0(\mathbf{u}),$$

so we get: find $(U, \mathbf{u}) \in \mathbb{X}(\Sigma, \Gamma)$ such that

$$a_\Sigma(U, V) + \left[\begin{pmatrix} -\{\gamma_D^0\} \\ \{\gamma_N^0\} \end{pmatrix} \circ \mathbf{G}_{\kappa_0}^0(\mathbf{u}), \begin{pmatrix} -v_0 \\ -q_0 \end{pmatrix} \right]_\Gamma + \frac{1}{2}[\mathbb{T}(\mathbf{u}), \mathbb{T}(\mathbf{v})]_\Sigma = \\ F_\Sigma(V) + \left[\begin{pmatrix} \gamma_D^0 U_{\text{inc}} \\ -\gamma_N^0 U_{\text{inc}} \end{pmatrix}, \begin{pmatrix} -v_0 \\ -q_0 \end{pmatrix} \right]_\Gamma \quad \forall (V, \mathbf{v}) \in \mathbb{X}(\Sigma, \Gamma),$$

and also the signs turn out to agree with those in formulation (6.5).

9.2. Properties of the multi-trace FEM-BEM formulation. The relationship between the multi-trace FEM-BEM formulation (9.6) and the transmission problem (2.4) is examined in the following proposition.

Proposition 9.2 (Link with the transmission problem). *If $(U, \hat{\mathbf{u}}) \in \mathbf{H}^1(\Omega_\Sigma) \times \widehat{\mathbb{H}}(\Gamma)$, $\hat{\mathbf{u}} = (\hat{\mathbf{u}}_1, \dots, \hat{\mathbf{u}}_n, p_\Sigma) \in \widehat{\mathbb{H}}(\Gamma)$, solve (9.6), then the solution to (2.4) is given by*

$$(9.8) \quad \begin{aligned} \tilde{U}(\mathbf{x}) &:= U(\mathbf{x}) \quad \text{for } \mathbf{x} \in \Omega_\Sigma, \\ \tilde{U}(\mathbf{x}) &:= \left(U_{\text{inc}} - \mathbf{G}_{\kappa_0}^\Sigma \begin{pmatrix} \gamma_D^\Sigma U \\ p_\Sigma \end{pmatrix} - \sum_{j=1}^n \mathbf{G}_{\kappa_0}^j(\hat{\mathbf{u}}_j) \right)(\mathbf{x}) \quad \text{for } \mathbf{x} \in \Omega_0, \\ \tilde{U}(\mathbf{x}) &:= \mathbf{G}_{\kappa_j}^j(\hat{\mathbf{u}}_j)(\mathbf{x}) \quad \text{for } \mathbf{x} \in \Omega_j, j = 1, \dots, n. \end{aligned}$$

Proof. First of all, $(\tilde{U} - U_{\text{inc}})|_{\Omega_0} = -\mathbf{G}_{\kappa_0}^\Sigma(\gamma_D^\Sigma U, p_\Sigma) - \sum_{j=1}^n \mathbf{G}_{\kappa_0}^j(\hat{\mathbf{u}}_j)$ is κ_0 -outgoing radiating in Ω_0 , see e.g. [10, Theorem 3.2]. It is also clear that \tilde{U} satisfies the Helmholtz equation in Ω_j , $j = 1, \dots, n$ since it is satisfied by the potentials (see e.g. [10, §2.4]), and in Ω_0 since it is also satisfied by U_{inc} by definition. By testing (9.6) with $V \in \mathbf{H}_0^1(\Omega_\Sigma)$, $\hat{\mathbf{v}} = 0$, we get $a_\Sigma(U, V) = a_\Sigma(\tilde{U}, V) = F_\Sigma(V)$, so \tilde{U} satisfies the Helmholtz equation also in Ω_Σ . The property that remains to be verified is the transmission conditions: by characterization (5.7) it is sufficient to show that for all $\mathbf{v} \in \mathbb{X}(\Gamma)$ we have $[\gamma(\tilde{U}), \mathbf{v}]_\Gamma + [\gamma^\Sigma(\tilde{U}), \mathbb{T}(\mathbf{v})]_\Sigma = 0$, i.e., by definition of \tilde{U} ,

$$(9.9) \quad \left[\gamma^0 U_{\text{inc}} - \gamma^0 \mathbf{G}_{\kappa_0}^\Sigma \begin{pmatrix} \gamma_D^\Sigma U \\ p_\Sigma \end{pmatrix} - \sum_{j=1}^n \gamma^0 \mathbf{G}_{\kappa_0}^j(\hat{\mathbf{u}}_j), \mathbf{v}_0 \right]_{\Gamma_0} + \\ + \sum_{j=1}^n [\gamma^j \mathbf{G}_{\kappa_j}^j(\hat{\mathbf{u}}_j), \mathbf{v}_j]_{\Gamma_j} + [\gamma^\Sigma U, \mathbb{T}(\mathbf{v})]_\Sigma = 0.$$

We fix an arbitrary $\mathbf{v} \in \mathbb{X}(\Gamma)$ and denote $\mathbf{v}_* := (\mathbf{v}_1, \dots, \mathbf{v}_n, \mathbb{T}_N(\mathbf{v})) \in \widehat{\mathbb{H}}(\Gamma)$. Since $\tilde{U}|_{\Omega_\Sigma} = U$ satisfies the Helmholtz equation in Ω_Σ , integrating by parts we get

$$(9.10) \quad a_\Sigma(U, V) - F_\Sigma(V) = \langle \gamma_N^\Sigma U, \gamma_D^\Sigma V \rangle_\Sigma \quad \forall V \in \mathbf{H}^1(\Omega_\Sigma).$$

Moreover, by (4.7)-(4.8), we have

$$(9.11) \quad \mathbf{A}_{\kappa_j}^j + \mathbf{A}_{\kappa_0}^j = \gamma^j \mathbf{G}_{\kappa_j}^j + \gamma_c^j \mathbf{G}_{\kappa_0}^j, \quad j = 1, \dots, n, \quad \mathbf{A}_{\kappa_0}^\Sigma = \gamma_c^\Sigma \mathbf{G}_{\kappa_0}^\Sigma + \text{Id}/2.$$

Thus, if we test formulation (9.6) (or its expanded form (9.7)) with V satisfying $\gamma_D^\Sigma V = \mathbb{T}_D(\mathbf{v})$ and with $\hat{\mathbf{v}} = \mathbf{v}_*$, using (9.10)-(9.11), we obtain

$$\begin{aligned}
(9.12) \quad 0 &= \langle \gamma_N^\Sigma U, \mathbb{T}_D(\mathbf{v}) \rangle_\Sigma + \sum_{j=1}^n ([\gamma^j \mathbf{G}_{\kappa_j}^j(\hat{\mathbf{u}}_j), \theta(\mathbf{v}_j)]_{\Gamma_j} + [\gamma_c^j \mathbf{G}_{\kappa_0}^j(\hat{\mathbf{u}}_j), \theta(\mathbf{v}_j)]_{\Gamma_j}) \\
&+ \left[\gamma_c^\Sigma \mathbf{G}_{\kappa_0}^\Sigma \left(\begin{array}{c} \gamma_D^\Sigma U \\ p_\Sigma \end{array} \right), \mathbb{T}(\Theta(\mathbf{v})) \right]_\Sigma + \frac{1}{2} \left[\left(\begin{array}{c} \gamma_D^\Sigma U \\ p_\Sigma \end{array} \right), \mathbb{T}(\Theta(\mathbf{v})) \right]_\Sigma \\
&+ \sum_{j=1}^n \left(\sum_{q=1, q \neq j}^n [\gamma^q \mathbf{G}_{\kappa_0}^j(\hat{\mathbf{u}}_j), \theta(\mathbf{v}_q)]_{\Gamma_q} + [\gamma^\Sigma \mathbf{G}_{\kappa_0}^j(\hat{\mathbf{u}}_j), \mathbb{T}(\Theta(\mathbf{v}))]_\Sigma \right) \\
&+ \sum_{q=1}^n \left[\gamma^q \mathbf{G}_{\kappa_0}^\Sigma \left(\begin{array}{c} \gamma_D^\Sigma U \\ p_\Sigma \end{array} \right), \theta(\mathbf{v}_q) \right]_{\Gamma_q} + \frac{1}{2} \left[\left(\begin{array}{c} \gamma_D^\Sigma U \\ p_\Sigma \end{array} \right), \mathbb{T}(\mathbf{v}) \right]_\Sigma \\
&- \sum_{j=1}^n [\gamma^j U_{\text{inc}}, \theta(\mathbf{v}_j)]_{\Gamma_j} - [\gamma^\Sigma U_{\text{inc}}, \mathbb{T}(\Theta(\mathbf{v}))]_\Sigma,
\end{aligned}$$

that is, gathering terms conveniently, $0 = t_1 + t_2 + t_3 + t_4 + t_5$, where

$$\begin{aligned}
t_1 &= \sum_{j=1}^n [\gamma^j \mathbf{G}_{\kappa_j}^j(\hat{\mathbf{u}}_j), \theta(\mathbf{v}_j)]_{\Gamma_j} \\
t_2 &= \langle \gamma_N^\Sigma U, \mathbb{T}_D(\mathbf{v}) \rangle_\Sigma + \frac{1}{2} \left[\left(\begin{array}{c} \gamma_D^\Sigma U \\ p_\Sigma \end{array} \right), \mathbb{T}(\Theta(\mathbf{v})) \right]_\Sigma + \frac{1}{2} \left[\left(\begin{array}{c} \gamma_D^\Sigma U \\ p_\Sigma \end{array} \right), \mathbb{T}(\mathbf{v}) \right]_\Sigma \\
t_3 &= \sum_{j=1}^n \left([\gamma_c^j \mathbf{G}_{\kappa_0}^j(\hat{\mathbf{u}}_j), \theta(\mathbf{v}_j)]_{\Gamma_j} + \sum_{q=1, q \neq j}^n [\gamma^q \mathbf{G}_{\kappa_0}^j(\hat{\mathbf{u}}_j), \theta(\mathbf{v}_q)]_{\Gamma_q} + [\gamma^\Sigma \mathbf{G}_{\kappa_0}^j(\hat{\mathbf{u}}_j), \mathbb{T}(\Theta(\mathbf{v}))]_\Sigma \right) \\
t_4 &= \left[\gamma_c^\Sigma \mathbf{G}_{\kappa_0}^\Sigma \left(\begin{array}{c} \gamma_D^\Sigma U \\ p_\Sigma \end{array} \right), \mathbb{T}(\Theta(\mathbf{v})) \right]_\Sigma + \sum_{q=1}^n \left[\gamma^q \mathbf{G}_{\kappa_0}^\Sigma \left(\begin{array}{c} \gamma_D^\Sigma U \\ p_\Sigma \end{array} \right), \theta(\mathbf{v}_q) \right]_{\Gamma_q} \\
t_5 &= - \sum_{j=1}^n [\gamma^j U_{\text{inc}}, \theta(\mathbf{v}_j)]_{\Gamma_j} - [\gamma^\Sigma U_{\text{inc}}, \mathbb{T}(\Theta(\mathbf{v}))]_\Sigma.
\end{aligned}$$

First of all, note that the term t_2 simplifies into $[\gamma^\Sigma U, \mathbb{T}(\Theta(\mathbf{v}))]_\Sigma$, which is exactly the last term of the sought equation (9.9), but with \mathbf{v} replaced by $\Theta(\mathbf{v})$. In order to treat the other terms we will employ the polarity identity (5.5) and the procedure described in Remark 5.4 three times. First, for a given $j = 1, \dots, n$, we have $(\gamma^0 \mathbf{G}_{\kappa_0}^j(\hat{\mathbf{u}}_j), \dots, \gamma_c^j \mathbf{G}_{\kappa_0}^j(\hat{\mathbf{u}}_j), \dots, \gamma^n \mathbf{G}_{\kappa_0}^j(\hat{\mathbf{u}}_j), \gamma^\Sigma \mathbf{G}_{\kappa_0}^j(\hat{\mathbf{u}}_j)) \in \tilde{\mathbb{X}}(\Gamma)$, thus

$$\begin{aligned}
(9.13) \quad &[\gamma_c^j \mathbf{G}_{\kappa_0}^j(\hat{\mathbf{u}}_j), \theta(\mathbf{v}_j)]_{\Gamma_j} + \sum_{q=1, q \neq j}^n [\gamma^q \mathbf{G}_{\kappa_0}^j(\hat{\mathbf{u}}_j), \theta(\mathbf{v}_q)]_{\Gamma_q} + [\gamma^\Sigma \mathbf{G}_{\kappa_0}^j(\hat{\mathbf{u}}_j), \mathbb{T}(\Theta(\mathbf{v}))]_\Sigma \\
&= -[\gamma^0 \mathbf{G}_{\kappa_0}^j(\hat{\mathbf{u}}_j), \theta(\mathbf{v}_0)]_{\Gamma_0}.
\end{aligned}$$

Second, we have $(\gamma^0 \mathbf{G}_{\kappa_0}^\Sigma(\gamma_D^\Sigma U, p_\Sigma), \dots, \gamma^n \mathbf{G}_{\kappa_0}^\Sigma(\gamma_D^\Sigma U, p_\Sigma), \gamma_c^\Sigma \mathbf{G}_{\kappa_0}^\Sigma(\gamma_D^\Sigma U, p_\Sigma)) \in \tilde{\mathbb{X}}(\Gamma)$, thus

$$(9.14) \quad \begin{aligned} & \sum_{q=1}^n \left[\gamma^q \mathbf{G}_{\kappa_0}^\Sigma \left(\begin{array}{c} \gamma_D^\Sigma U \\ p_\Sigma \end{array} \right), \theta(\mathbf{v}_q) \right]_{\Gamma_q} + \left[\gamma_c^\Sigma \mathbf{G}_{\kappa_0}^\Sigma \left(\begin{array}{c} \gamma_D^\Sigma U \\ p_\Sigma \end{array} \right), \mathbb{T}(\Theta(\mathbf{v})) \right]_{\Sigma} \\ & = - \left[\gamma^0 \mathbf{G}_{\kappa_0}^\Sigma \left(\begin{array}{c} \gamma_D^\Sigma U \\ p_\Sigma \end{array} \right), \theta(\mathbf{v}_0) \right]_{\Gamma_0}. \end{aligned}$$

Third, we have $(\gamma^0 U_{\text{inc}}, \dots, \gamma^n U_{\text{inc}}, \gamma^\Sigma U_{\text{inc}}) \in \tilde{\mathbb{X}}(\Gamma)$, thus

$$(9.15) \quad \sum_{j=1}^n [\gamma^j U_{\text{inc}}, \theta(\mathbf{v}_j)]_{\Gamma_j} + [\gamma^\Sigma U_{\text{inc}}, \mathbb{T}(\Theta(\mathbf{v}))]_{\Sigma} = -[\gamma^0 U_{\text{inc}}, \theta(\mathbf{v}_0)]_{\Gamma_0}.$$

Now, use (9.13) summed over $j = 1, \dots, n$, (9.14), (9.15) to replace respectively t_3, t_4, t_5 , therefore (9.12) becomes

$$\begin{aligned} 0 &= \sum_{j=1}^n [\gamma^j \mathbf{G}_{\kappa_j}^j(\hat{\mathbf{u}}_j), \theta(\mathbf{v}_j)]_{\Gamma_j} - \sum_{j=1}^n [\gamma^0 \mathbf{G}_{\kappa_0}^j(\hat{\mathbf{u}}_j), \theta(\mathbf{v}_0)]_{\Gamma_0} - \left[\gamma^0 \mathbf{G}_{\kappa_0}^\Sigma \left(\begin{array}{c} \gamma_D^\Sigma U \\ p_\Sigma \end{array} \right), \theta(\mathbf{v}_0) \right]_{\Gamma_0} \\ & \quad + [\gamma^0 U_{\text{inc}}, \theta(\mathbf{v}_0)]_{\Gamma_0} + [\gamma^\Sigma U, \mathbb{T}(\Theta(\mathbf{v}))]_{\Sigma}, \end{aligned}$$

that is exactly the sought equation (9.9), but with \mathbf{v} replaced by $\Theta(\mathbf{v})$, which is not a problem since Θ is an automorphism. \square

As suggested by the gap idea, also the multi-trace FEM-BEM formulation (9.6) satisfies a *Gårding inequality*:

Proposition 9.3 (Gårding inequality). *Let $\mathbf{a}_{\text{MTF}} : (\mathbf{H}^1(\Omega_\Sigma) \times \hat{\mathbb{H}}(\Gamma)) \times (\mathbf{H}^1(\Omega_\Sigma) \times \hat{\mathbb{H}}(\Gamma)) \rightarrow \mathbb{C}$ designate the bilinear form on the left-hand side of (9.6). There exist a compact bilinear form $\mathbf{k} : (\mathbf{H}^1(\Omega_\Sigma) \times \hat{\mathbb{H}}(\Gamma)) \times (\mathbf{H}^1(\Omega_\Sigma) \times \hat{\mathbb{H}}(\Gamma)) \rightarrow \mathbb{C}$ and a constant $\beta > 0$ such that*

$$\text{Re}\{\mathbf{a}_{\text{MTF}}((V, \hat{\mathbf{v}}), (\bar{V}, \bar{\hat{\mathbf{v}}})) + \mathbf{k}((V, \hat{\mathbf{v}}), (\bar{V}, \bar{\hat{\mathbf{v}}}))\} \geq \beta(\|V\|_{\mathbf{H}^1(\Omega_\Sigma)}^2 + \|\hat{\mathbf{v}}\|_{\hat{\mathbb{H}}(\Gamma)}^2)$$

for all $(V, \hat{\mathbf{v}}) \in \mathbf{H}^1(\Omega_\Sigma) \times \hat{\mathbb{H}}(\Gamma)$.

Proof. We need to examine

$$\mathbf{a}_{\text{MTF}}((V, \hat{\mathbf{v}}), (\bar{V}, \bar{\hat{\mathbf{v}}})) = a_\Sigma(V, \bar{V}) + \|\hat{\hat{\mathbf{A}}}(\hat{\mathbf{v}}), \Theta(\bar{\hat{\mathbf{v}}})\| + \frac{1}{2} \left[\left(\begin{array}{c} \gamma_D^\Sigma V \\ q_\Sigma \end{array} \right), \left(\begin{array}{c} \gamma_D^\Sigma \bar{V} \\ \bar{q}_\Sigma \end{array} \right) \right]_{\Sigma},$$

where $\hat{\mathbf{v}} := (\hat{\mathbf{v}}_1, \dots, \hat{\mathbf{v}}_n, (\gamma_D^\Sigma V, q_\Sigma))$. As already mentioned, a_Σ satisfies a Gårding inequality as in [18, Lemma 3.2], and

$$\text{Re} \left\{ \frac{1}{2} \left[\left(\begin{array}{c} \gamma_D^\Sigma V \\ q_\Sigma \end{array} \right), \left(\begin{array}{c} \gamma_D^\Sigma \bar{V} \\ \bar{q}_\Sigma \end{array} \right) \right]_{\Sigma} \right\} = 0.$$

For the remaining term $\|\hat{\hat{\mathbf{A}}}(\hat{\mathbf{v}}), \Theta(\bar{\hat{\mathbf{v}}})\|$, we proceed exactly as in the proof of [8, Proposition 6.3], except that $\hat{\mathbf{v}}_{n+1} := (\gamma_D^\Sigma V, q_\Sigma)$ in the present case. Indeed, note that the first concise equality at the beginning of the proof of [8, Proposition 6.3] fits exactly the expression of $\hat{\hat{\mathbf{A}}}$. Thus we obtain that, for the case $\kappa_0 = \dots = \kappa_n = \iota$, there exists $\tilde{\beta} > 0$ such that

$$\text{Re} \|\hat{\hat{\mathbf{A}}}(\hat{\mathbf{v}}), \Theta(\bar{\hat{\mathbf{v}}})\| \geq \tilde{\beta} \sum_{j=1}^{n+1} \|\hat{\mathbf{v}}_j\|_{\hat{\mathbb{H}}(\Gamma_j)}^2 = \tilde{\beta} \left(\|\hat{\mathbf{v}}\|_{\hat{\mathbb{H}}(\Gamma)}^2 + \|\gamma_D^\Sigma V\|_{\mathbf{H}^{1/2}(\Sigma)}^2 \right),$$

which leads to the desired conclusion since a change of the wavenumbers $\kappa_0, \dots, \kappa_n$ only induces a compact perturbation of the integral operators appearing in $\widehat{\mathbb{A}}$ (see e.g. [21, Lemma 3.9.8]). \square

Again, in the case of injectivity all the nice consequences recalled below Proposition 7.2 would follow from the Gårding inequality. Hence in the following proposition we examine the injectivity condition for the multi-trace FEM-BEM formulation (9.6). Note that the gap configuration falls exactly within the case $\Sigma \subset \Gamma_0$, in which spurious resonances affect the single-trace FEM-BEM formulation (7.6) if $\kappa_0 \in \mathfrak{S}(\Delta, \Omega_\Sigma)$ (recall Proposition 7.3), so the following result is not surprising.

Proposition 9.4 (Injectivity condition). *Let $(U, \hat{\mathbf{u}}) \in \mathbf{H}^1(\Omega_\Sigma) \times \widehat{\mathbb{H}}(\Gamma)$ solves formulation (9.6) with $F_\Sigma \equiv 0$, $\hat{\mathbf{f}} = 0$. Then $U = 0$. We also have $\hat{\mathbf{u}} = 0$ if $\kappa_0 \notin \mathfrak{S}(\Delta, \Omega_\Sigma)$. If $\kappa_0 \in \mathfrak{S}(\Delta, \Omega_\Sigma)$, there exists $\hat{\mathbf{u}} \in \widehat{\mathbb{H}}(\Gamma) \setminus \{0\}$ such that $(0, \hat{\mathbf{u}}) \in \mathbf{H}^1(\Omega_\Sigma) \times \widehat{\mathbb{H}}(\Gamma)$ solves (9.6) with $F_\Sigma \equiv 0$, $\hat{\mathbf{f}} = 0$.*

Proof. By Proposition 9.2, the function \widetilde{U} defined in (9.8) solves the homogeneous transmission problem (2.4), which is well-posed, so $\widetilde{U} = 0$. In particular, $U = \widetilde{U}|_{\Omega_\Sigma} = 0$ and $\gamma_D^\Sigma U = 0$. Therefore, if we test formulation (9.6) with $F_\Sigma \equiv 0$, $\hat{\mathbf{f}} = 0$ using test functions $V \in \mathbf{H}_0^1(\Omega_\Sigma)$ (and $\hat{\mathbf{v}} = (\hat{\mathbf{v}}_1, \dots, \hat{\mathbf{v}}_n, q_\Sigma) \in \widehat{\mathbb{H}}(\Gamma)$), we obtain

$$\llbracket \widehat{\mathbb{A}}(\hat{\mathbf{u}}), \Theta(\hat{\mathbf{v}}) \rrbracket = 0, \text{ with } \hat{\mathbf{u}} = (\hat{u}_1, \dots, \hat{u}_n, (0, p_\Sigma)), \quad \hat{\mathbf{v}} = (\hat{v}_1, \dots, \hat{v}_n, (0, q_\Sigma)),$$

which reduces to $\llbracket \widehat{\mathbb{A}}(\hat{\mathbf{u}}), \Theta(\hat{\mathbf{v}}) \rrbracket = 0$, where $\widehat{\mathbb{A}}$ is the operator defined in [8, Equation (6.3)]. Then $\hat{\mathbf{u}} \in \ker(\widehat{\mathbb{A}})$ and, by [8, Proposition 6.4], if $\kappa_0 \notin \mathfrak{S}(\Delta, \Omega_\Sigma)$ we get $\hat{\mathbf{u}} = 0$.

Now we show that $\kappa_0 \notin \mathfrak{S}(\Delta, \Omega_\Sigma)$ is also a necessary condition. If $\kappa_0 \in \mathfrak{S}(\Delta, \Omega_\Sigma)$, by [21, Theorem 3.9.1] we know that $\ker(\gamma_D^\Sigma \mathbf{SL}_{\kappa_0}^\Sigma) \neq \{0\}$, and we consider $p \in \ker(\gamma_D^\Sigma \mathbf{SL}_{\kappa_0}^\Sigma) \setminus \{0\}$. As $\gamma_D^\Sigma \mathbf{SL}_{\kappa_0}^\Sigma(p) = 0$, by jump relations (4.3) we have $\gamma_{D,c}^\Sigma \mathbf{SL}_{\kappa_0}^\Sigma(p) = 0$, and, since the exterior Helmholtz boundary value problem is well-posed, we get $\mathbf{SL}_{\kappa_0}^\Sigma(p)(\mathbf{x}) = 0$ for $\mathbf{x} \in \mathbb{R}^d \setminus \Omega_\Sigma$. Therefore $\gamma^q \mathbf{SL}_{\kappa_0}^\Sigma(p) = 0$ for all $q = 1, \dots, n$ and $\gamma_{N,c}^\Sigma \mathbf{SL}_{\kappa_0}^\Sigma(p) = 0$. In particular, using (4.8),

$$\mathbf{A}_{\kappa_0}^\Sigma \begin{pmatrix} 0 \\ p \end{pmatrix} = \gamma_c^\Sigma \mathbf{SL}_{\kappa_0}^\Sigma(p) + \frac{1}{2} \begin{pmatrix} 0 \\ p \end{pmatrix} = \begin{pmatrix} 0 \\ p/2 \end{pmatrix}.$$

Then, if we evaluate the left-hand side of formulation (9.6) in $U^* = 0$, $\hat{\mathbf{u}}^* = (0, \dots, 0, p)$ we have

$$\sum_{q=1}^n [\gamma^q \mathbf{SL}_{\kappa_0}^\Sigma(p), \theta(\hat{\mathbf{v}}_q)]_{\Gamma_q} + \left[\begin{pmatrix} 0 \\ p/2 \end{pmatrix}, \begin{pmatrix} -\gamma_D^\Sigma V \\ q_\Sigma \end{pmatrix} \right]_\Sigma + \frac{1}{2} \left[\begin{pmatrix} 0 \\ p \end{pmatrix}, \begin{pmatrix} \gamma_D^\Sigma V \\ q_\Sigma \end{pmatrix} \right]_\Sigma = 0,$$

for all $(V, \hat{\mathbf{v}}) \in \mathbf{H}^1(\Omega_\Sigma) \times \widehat{\mathbb{H}}(\Gamma)$, and we have found a non trivial solution. \square

Comparing the injectivity conditions in Proposition 7.3 and Proposition 9.4, we see that in the case $\Sigma \subset \Gamma_0$, if the single-trace formulation (7.6) suffer from spurious resonances then so does the multi-trace formulation (9.6); on the other hand, in the case $\Sigma \not\subset \Gamma_0$, there are wavenumbers κ_0 for which the multi-trace formulation (9.6) breaks down, while the single-trace formulation (7.6) remains injective. If the single-trace formulation (7.6) fails to be injective because $\Sigma \subset \Gamma_1$ and $\kappa_1 \in \mathfrak{S}(\Delta, \Omega_\Sigma)$, but $\kappa_0 \notin \mathfrak{S}(\Delta, \Omega_\Sigma)$, the multi-trace formulation (9.6) is instead well-posed. Note

that we could write a multi-trace formulation based on an other subdomain than Ω_0 , say Ω_i , loosely speaking by filling the gap with the same medium as Ω_i .

10. MULTI-TRACE COMBINED FIELD FEM-BEM FORMULATION

We have shown that the multi-trace FEM-BEM formulation (9.6) is affected by spurious resonances when $\kappa_0 \in \mathfrak{S}(\Delta, \Omega_\Sigma)$. Again, as a remedy, we adapt the approach of combined field integral equations. More precisely, as the standard multi-trace FEM-BEM formulation (9.6) was obtained by manipulating the standard single-trace FEM-BEM formulation (7.6), similarly we will obtain a combined field multi-trace FEM-BEM formulation by manipulating the combined field single-trace FEM-BEM formulation (8.7). Since the difference between (7.6) and (8.7) lies only in the compact bilinear form \mathfrak{c} and in the right-hand side with $\hat{\mathbf{u}}^{\text{inc}}$ defined in (8.6), we just need to elaborate these terms.

As in [8, §6.4] we first derive the formulation *in the gap setting*, and we look for

$$\widehat{\mathfrak{c}}: (\mathbb{H}^1(\Omega_\Sigma) \times \widehat{\mathbb{H}}(\Gamma))^2 \rightarrow \mathbb{C} \quad \text{such that} \quad \widehat{\mathfrak{c}}((U, \hat{\mathbf{u}}), (V, \hat{\mathbf{v}})) = \mathfrak{c}(\mathbf{u}, \mathbf{v})$$

where $(U, \hat{\mathbf{u}}), (V, \hat{\mathbf{v}}) \in \mathbb{H}^1(\Omega_\Sigma) \times \widehat{\mathbb{H}}(\Gamma)$ correspond respectively to $(U, \mathbf{u}), (V, \mathbf{v}) \in \mathbb{X}(\Sigma, \Gamma)$ under the isomorphism defined at the beginning of §9. Observe that in the gap setting, where $\Sigma \subset \partial\Omega_0$, the extension operator \mathbf{E}_Σ can be picked to map into functions whose support is inside $\Omega_0 \cup \overline{\Omega}_\Sigma$, so that $\gamma_D^j \circ \mathbf{E}_\Sigma = 0$ for $j \neq 0$ and the operator \mathbf{C} in (8.3), essentially, maps into $\mathbb{H}^{1/2}(\Sigma)$. Then, applying also (4.8),

$$\begin{aligned} \mathfrak{c}(\mathbf{u}, \mathbf{v}) &= \sum_{j=0}^n \left[\gamma_c^j \mathbf{G}_{\kappa_j}^j(\mathbf{u}_j), \theta(\mathbf{C}\mathbf{v})_j \right]_{\Gamma_j} = [\gamma_c^0 \mathbf{G}_{\kappa_0}^0(\mathbf{u}_0), \theta(\mathbf{C}\mathbf{v})_0]_{\Gamma_0} \\ &= - \langle \gamma_N^\Sigma \mathbf{G}_{\kappa_0}^0(\mathbf{u}_0), \mathbf{M}\mathbf{T}_N(\mathbf{v}) \rangle_\Sigma, \end{aligned}$$

where we have used the definition of \mathbf{C} , $\gamma_{N,c}^0 = -\gamma_N^\Sigma$, $\gamma_D^0 = \gamma_D^\Sigma$, $\gamma_D^\Sigma \circ \mathbf{E}_\Sigma = \text{Id}$. Moreover, since $(U, \mathbf{u}) \in \mathbb{X}(\Sigma, \Gamma)$, in the gap setting \mathbf{u}_0 equals $\phi(\mathbf{u}_j)$ on each Γ_j , $j = 1, \dots, n$, and equals $\phi(\gamma_D^\Sigma U, \mathbf{T}_N(\mathbf{u}))$ on Σ , that reflects exactly the isomorphism defined at the beginning of §9. This implies $\mathbf{G}_{\kappa_0}^0(\mathbf{u}_0) = -\mathbf{G}_{\kappa_0}^\Sigma(\gamma_D^\Sigma U, \mathbf{T}_N(\mathbf{u})) - \sum_{j=1}^n \mathbf{G}_{\kappa_0}^j(\mathbf{u}_j)$. Therefore, for $\hat{\mathbf{u}} = (\hat{\mathbf{u}}_1, \dots, \hat{\mathbf{u}}_n, p_\Sigma) \in \widehat{\mathbb{H}}(\Gamma)$, $\hat{\mathbf{v}} = (\hat{\mathbf{v}}_1, \dots, \hat{\mathbf{v}}_n, q_\Sigma) \in \widehat{\mathbb{H}}(\Gamma)$, we get

$$\widehat{\mathfrak{c}}((U, \hat{\mathbf{u}}), (V, \hat{\mathbf{v}})) := \left\langle \mathbf{M}^* \gamma_N^\Sigma \mathbf{G}_{\kappa_0}^\Sigma \begin{pmatrix} \gamma_D^\Sigma U \\ p_\Sigma \end{pmatrix}, q_\Sigma \right\rangle_\Sigma + \sum_{j=1}^n \langle \mathbf{M}^* \gamma_N^\Sigma \mathbf{G}_{\kappa_0}^j(\hat{\mathbf{u}}_j), q_\Sigma \rangle_\Sigma.$$

Now, summing the term in (9.6) that derives from $[\mathbf{A}(\mathbf{u}), \Theta(\mathbf{v})]_\Gamma$ we write

$$\llbracket \widehat{\mathbf{A}}(\hat{\mathbf{u}}), \Theta(\hat{\mathbf{v}}) \rrbracket + \widehat{\mathfrak{c}}((U, \hat{\mathbf{u}}), (V, \hat{\mathbf{v}})) = \llbracket \widehat{\mathbf{A}}_{\mathbf{M}}(\hat{\mathbf{u}}), \Theta(\hat{\mathbf{v}}) \rrbracket$$

where

$$\begin{aligned} \hat{\mathbf{u}} &:= (\hat{\mathbf{u}}_1, \dots, \hat{\mathbf{u}}_n, (\gamma_D^\Sigma U, p_\Sigma)), \quad \hat{\mathbf{v}} := (\hat{\mathbf{v}}_1, \dots, \hat{\mathbf{v}}_n, (\gamma_D^\Sigma V, q_\Sigma)), \quad \text{and} \\ \widehat{\mathbf{A}}_{\mathbf{M}} &:= \begin{bmatrix} \mathbf{A}_{\kappa_1}^1 + \mathbf{A}_{\kappa_0}^1 & \gamma^1 \mathbf{G}_{\kappa_0}^2 & \cdots & \gamma^1 \mathbf{G}_{\kappa_0}^n & \gamma^1 \mathbf{G}_{\kappa_0}^\Sigma \\ \gamma^2 \mathbf{G}_{\kappa_0}^1 & \mathbf{A}_{\kappa_2}^2 + \mathbf{A}_{\kappa_0}^2 & & \gamma^2 \mathbf{G}_{\kappa_0}^n & \gamma^2 \mathbf{G}_{\kappa_0}^\Sigma \\ \vdots & & \ddots & & \vdots \\ \gamma^n \mathbf{G}_{\kappa_0}^1 & \gamma^n \mathbf{G}_{\kappa_0}^2 & & \mathbf{A}_{\kappa_n}^n + \mathbf{A}_{\kappa_0}^n & \gamma^n \mathbf{G}_{\kappa_0}^\Sigma \\ (\gamma_D^\Sigma + \mathbf{M}^* \gamma_N^\Sigma) \mathbf{G}_{\kappa_0}^1 & (\gamma_D^\Sigma + \mathbf{M}^* \gamma_N^\Sigma) \mathbf{G}_{\kappa_0}^2 & \cdots & (\gamma_D^\Sigma + \mathbf{M}^* \gamma_N^\Sigma) \mathbf{G}_{\kappa_0}^n & \mathbf{A}_{\kappa_0}^\Sigma + (\mathbf{M}_0^* \gamma_N^\Sigma) \mathbf{G}_{\kappa_0}^\Sigma \end{bmatrix}. \end{aligned}$$

Note that $\widehat{\mathbf{A}}_{\mathbf{M}}$ differs from $\widehat{\mathbf{A}}$ only in the Dirichlet traces on Σ in the last line.

In a similar way, for the right-hand side $-\llbracket \tilde{\mathbf{u}}^{\text{inc}}, \mathbf{v} \rrbracket_{\Gamma} = -\llbracket \mathbf{u}^{\text{inc}}, \Theta(\text{Id} + \mathbf{C})(\mathbf{v}) \rrbracket_{\Gamma}$, we get

$$\llbracket \mathbf{u}^{\text{inc}}, \Theta \mathbf{C}(\mathbf{v}) \rrbracket_{\Gamma} = \llbracket \gamma^0 U_{\text{inc}}, \theta(\mathbf{C}\mathbf{v})_0 \rrbracket_{\Gamma_0} = -\langle \gamma_N^{\Sigma} U_{\text{inc}}, \mathbf{M} \mathbf{T}_N(\mathbf{v}) \rangle_{\Sigma} = -\langle \mathbf{M}^* \gamma_N^{\Sigma} U_{\text{inc}}, \mathbf{T}_N(\mathbf{v}) \rangle_{\Sigma}$$

and combining with the term in (9.6) that derives from $-\llbracket \mathbf{u}^{\text{inc}}, \Theta(\mathbf{v}) \rrbracket_{\Gamma}$ we write

$$\hat{\mathbf{f}}_{\mathbf{M}} := \left(\gamma^1 U_{\text{inc}}, \dots, \gamma^n U_{\text{inc}}, \left(\gamma_{\mathbf{D}}^{\Sigma} + \mathbf{M}^* \gamma_N^{\Sigma} \right) U_{\text{inc}} \right).$$

In conclusion we define the *global multi-trace combined field FEM-BEM formulation*

$$(10.1) \quad \boxed{\begin{array}{l} \text{find } (U, \hat{\mathbf{u}}) \in \mathbf{H}^1(\Omega_{\Sigma}) \times \hat{\mathbb{H}}(\Gamma), \hat{\mathbf{u}} = (\hat{\mathbf{u}}_1, \dots, \hat{\mathbf{u}}_n, p_{\Sigma}), \text{ such that} \\ a_{\Sigma}(U, V) + \llbracket \hat{\mathbf{A}}_{\mathbf{M}}(\hat{\mathbf{u}}), \Theta(\hat{\mathbf{v}}) \rrbracket + \frac{1}{2} \left[\left(\begin{array}{c} \gamma_{\mathbf{D}}^{\Sigma} U \\ p_{\Sigma} \end{array} \right), \left(\begin{array}{c} \gamma_{\mathbf{D}}^{\Sigma} V \\ q_{\Sigma} \end{array} \right) \right]_{\Sigma} \\ = F_{\Sigma}(V) + \llbracket \hat{\mathbf{f}}_{\mathbf{M}}, \Theta(\hat{\mathbf{v}}) \rrbracket \quad \forall (V, \hat{\mathbf{v}}) \in \mathbf{H}^1(\Omega_{\Sigma}) \times \hat{\mathbb{H}}(\Gamma), \hat{\mathbf{v}} = (\hat{\mathbf{v}}_1, \dots, \hat{\mathbf{v}}_n, q_{\Sigma}) \\ \text{where } \hat{\mathbf{u}} := (\hat{\mathbf{u}}_1, \dots, \hat{\mathbf{u}}_n, (\gamma_{\mathbf{D}}^{\Sigma} U, p_{\Sigma})), \quad \hat{\mathbf{v}} := (\hat{\mathbf{v}}_1, \dots, \hat{\mathbf{v}}_n, (\gamma_{\mathbf{D}}^{\Sigma} V, q_{\Sigma})). \end{array}}$$

Even if we have derived this formulation in the gap setting, it is still valid in a general geometric configuration such as Figure 4, left. This will be justified in what follows. We first show which is the relationship of its solutions with the solutions to the standard multi-trace FEM-BEM formulation (9.6).

Proposition 10.1. *A solution to the combined field multi-trace FEM-BEM formulation (10.1) is also a solution to the standard multi-trace FEM-BEM formulation (9.6).*

Proof. Let $(U, \hat{\mathbf{u}})$ be a solution to formulation (10.1). Then if we take test functions $V = 0$, $\hat{\mathbf{v}} = (0, \dots, 0, q_{\Sigma})$ with some $q_{\Sigma} \in \mathbf{H}^{-1/2}(\Sigma)$ (thus $\gamma_{\mathbf{D}}^{\Sigma} V = 0$, $\hat{\mathbf{v}} = (0, \dots, 0, (0, q_{\Sigma}))$), it yields

$$\begin{aligned} \left\langle \sum_{j=1}^n (\gamma_{\mathbf{D}}^{\Sigma} + \mathbf{M}^* \gamma_N^{\Sigma}) \mathbf{G}_{\kappa_0}^j(\hat{\mathbf{u}}_j) + (\{\gamma_{\mathbf{D}}^{\Sigma}\} + \mathbf{M}^* \gamma_N^{\Sigma}) \mathbf{G}_{\kappa_0}^{\Sigma} \left(\begin{array}{c} \gamma_{\mathbf{D}}^{\Sigma} U \\ p_{\Sigma} \end{array} \right), q_{\Sigma} \right\rangle_{\Sigma} + \frac{1}{2} \langle \gamma_{\mathbf{D}}^{\Sigma} U, q_{\Sigma} \rangle_{\Sigma} \\ = \langle (\gamma_{\mathbf{D}}^{\Sigma} + \mathbf{M}^* \gamma_N^{\Sigma}) U_{\text{inc}}, q_{\Sigma} \rangle_{\Sigma} \quad \forall q_{\Sigma} \in \mathbf{H}^{-1/2}(\Sigma), \end{aligned}$$

and, since

$$\left\langle \{\gamma_{\mathbf{D}}^{\Sigma}\} \mathbf{G}_{\kappa_0}^{\Sigma} \left(\begin{array}{c} \gamma_{\mathbf{D}}^{\Sigma} U \\ p_{\Sigma} \end{array} \right), q_{\Sigma} \right\rangle_{\Sigma} = \left\langle \gamma_{\mathbf{D}}^{\Sigma} \mathbf{G}_{\kappa_0}^{\Sigma} \left(\begin{array}{c} \gamma_{\mathbf{D}}^{\Sigma} U \\ p_{\Sigma} \end{array} \right), q_{\Sigma} \right\rangle_{\Sigma} - \frac{1}{2} \langle \gamma_{\mathbf{D}}^{\Sigma} U, q_{\Sigma} \rangle_{\Sigma},$$

we obtain

$$\left\langle (\gamma_{\mathbf{D}}^{\Sigma} + \mathbf{M}^* \gamma_N^{\Sigma}) \left(U_{\text{inc}} - \sum_{j=1}^n \mathbf{G}_{\kappa_0}^j(\hat{\mathbf{u}}_j) - \mathbf{G}_{\kappa_0}^{\Sigma} \left(\begin{array}{c} \gamma_{\mathbf{D}}^{\Sigma} U \\ p_{\Sigma} \end{array} \right) \right), q_{\Sigma} \right\rangle_{\Sigma} = 0 \quad \forall q_{\Sigma} \in \mathbf{H}^{-1/2}(\Sigma).$$

Therefore, if we introduce

$$(10.2) \quad W := U_{\text{inc}} - \sum_{j=1}^n \mathbf{G}_{\kappa_0}^j(\hat{\mathbf{u}}_j) - \mathbf{G}_{\kappa_0}^{\Sigma} \left(\begin{array}{c} \gamma_{\mathbf{D}}^{\Sigma} U \\ p_{\Sigma} \end{array} \right),$$

this means $\gamma_{\mathbf{D}}^{\Sigma} W = -\mathbf{M}^* \gamma_N^{\Sigma} W$. Moreover, W solves $-\Delta W - \kappa_0^2 W = 0$ in Ω_{Σ} , so by Green's formula

$$\int_{\Omega_{\Sigma}} (|\nabla W|^2 - \kappa_0^2 |W|^2) d\mathbf{x} = -\langle \gamma_N^{\Sigma} \overline{W}, \mathbf{M}^* \gamma_N^{\Sigma} W \rangle_{\Sigma},$$

and taking the imaginary part, since $\kappa_0 \in \mathbb{R}$, we obtain $0 = -\text{Im}\{\langle M\gamma_N^\Sigma \overline{W}, \gamma_N^\Sigma W \rangle_\Sigma\}$, that implies $\gamma_N^\Sigma W = 0$ by property (8.1b) of M . As a consequence $\gamma_D^\Sigma W = -M^*\gamma_N^\Sigma W = 0$. The conclusion $\gamma_D^\Sigma W = 0$ finishes the proof because, looking at the definition of W , this corresponds exactly to the equation in formulation (9.6) associated with the Dirichlet component of the last line of $\widehat{\widehat{A}}$ and $\widehat{\widehat{f}}$, which represents the only difference between formulations (9.6) and (10.1). \square

A corollary of this proposition is that if (U, \hat{u}) satisfies formulation (10.1), then the unique solution to the transmission problem (2.4) is given by \widetilde{U} in (9.8). This justifies considering formulation (10.1) for *general geometric settings*.

Moreover, by the compactness of M , the block operator $\widehat{\widehat{A}}_M$ is a compact perturbation of $\widehat{\widehat{A}}$, so a *Gårding inequality* analogue to Proposition 9.3 still holds, and the induced operator is of Fredholm type with index 0. Therefore, in the case of injectivity, all the good properties recalled below Proposition 7.2 follow. As desired, the combined field formulation (10.1) is immune to spurious resonances for any choice of the positive wavenumbers κ_j :

Proposition 10.2 (Injectivity). *Let $(U, \hat{u}) \in H^1(\Omega_\Sigma) \times \widehat{\mathbb{H}}(\Gamma)$ solve formulation (10.1) with $F_\Sigma \equiv 0$, $\widehat{\widehat{f}}_M = 0$. Then $U = 0$, $\hat{u} = 0$.*

Proof. Since $\widehat{\widehat{f}}_M = 0$ we have $U_{\text{inc}} = 0$. As a consequence proceeding as in the beginning of the proof of Proposition 10.1 leads to considering $W := -\sum_{j=1}^n G_{\kappa_0}^j(\hat{u}_j) - G_{\kappa_0}^\Sigma(\gamma_D^\Sigma U, p_\Sigma)$ and, following the same argumentation as above, this function satisfies $\gamma_N^\Sigma(W) = 0$. According to the definition of $\widehat{\widehat{A}}_M$, this implies

$$\widehat{\widehat{A}}_{+M}(\hat{u}) = \widehat{\widehat{A}}(\hat{u}) = \widehat{\widehat{A}}_{-M}(\hat{u})$$

since the terms involving M^* in the last row of the definition of $\widehat{\widehat{A}}_M$ vanish. Next, by Proposition 10.1, (U, \hat{u}) solves also formulation (9.6), so by Proposition 9.4 we get $U = 0$ and $\gamma_D^\Sigma U = 0$. Now, if we test formulation (10.1) (with $F_\Sigma \equiv 0$, $\widehat{\widehat{f}}_M = 0$) using test functions $V \in H_0^1(\Omega_\Sigma)$ (and $\hat{v} = (\hat{v}_1, \dots, \hat{v}_n, q_\Sigma) \in \widehat{\mathbb{H}}(\Gamma)$), we obtain $\{\{\widehat{\widehat{A}}_M(\hat{u}), \Theta(\hat{v})\}\} = 0$ hence

$$\{\{\widehat{\widehat{A}}_{-M}(\hat{u}), \Theta(\hat{v})\}\} = 0$$

with $\hat{u} = (\hat{u}_1, \dots, \hat{u}_n, (0, p_\Sigma))$, $\hat{v} = (\hat{v}_1, \dots, \hat{v}_n, (0, q_\Sigma))$. Note that this reduces to $\{\{\widehat{\widehat{A}}_M(\hat{u}), \Theta(\hat{v})\}\} = 0$ for all $\hat{v} \in \widehat{\mathbb{H}}(\Gamma)$, where $\widehat{\widehat{A}}_M$ is defined in [8, Equation (6.21)] and is injective by [8, Proposition 6.7]. Then $\hat{u} = 0$. \square

APPENDIX A. PROPERTIES OF THE BLOCK BOUNDARY INTEGRAL OPERATOR A_κ^Ω

We prove here two useful properties of the boundary integral operator A_κ^Ω in (4.6) since we could not find detailed proofs in the literature.

Proposition A.1 (Generalized Gårding inequality). *Set $\theta(v, q) := (-v, q)$. Let Ω be a generic Lipschitz domain that is either bounded or such that $\mathbb{R}^d \setminus \overline{\Omega}$ is bounded. Then, there exist a compact operator $\mathcal{K}: \mathbb{H}(\partial\Omega) \rightarrow \mathbb{H}(\partial\Omega)$ and a constant $\alpha > 0$ such that for all $\mathbf{u} \in \mathbb{H}(\partial\Omega)$ we have*

$$\text{Re} \{[(A_\kappa^\Omega + \mathcal{K})\mathbf{u}, \theta(\overline{\mathbf{u}})]_{\partial\Omega}\} \geq \alpha \|\mathbf{u}\|_{\mathbb{H}(\partial\Omega)}^2.$$

Proof. Since a change of the wavenumber κ only induces a compact perturbation of \mathbf{A}_κ^Ω [21, Lemma 3.9.8], it suffices to prove the result for the case $\kappa = \iota$, where $\iota = \sqrt{-1}$. Set $\psi := \mathbf{G}_\kappa^\Omega(\mathbf{u})$, then we write $\mathbf{A}_\kappa^\Omega(\mathbf{u}) = \{\gamma^\Omega\} \psi$ and by the jump relations (4.3) we have $\mathbf{u} = [\gamma^\Omega] \psi$. Therefore

$$[\mathbf{A}_\kappa^\Omega(\mathbf{u}), \theta(\bar{\mathbf{u}})]_{\partial\Omega} = [\{\gamma^\Omega\} \psi, \theta[\gamma^\Omega] \bar{\psi}]_{\partial\Omega} = \frac{1}{2} [(\gamma^\Omega + \gamma_c^\Omega) \psi, \theta(\gamma^\Omega - \gamma_c^\Omega) \bar{\psi}]_{\partial\Omega} = m_1 + m_2$$

where

$$\begin{aligned} m_1 &= \frac{1}{2} [\gamma^\Omega \psi, \theta \gamma^\Omega \bar{\psi}]_{\partial\Omega} - \frac{1}{2} [\gamma_c^\Omega \psi, \theta \gamma_c^\Omega \bar{\psi}]_{\partial\Omega}, \\ m_2 &= \frac{1}{2} [\gamma_c^\Omega \psi, \theta \gamma^\Omega \bar{\psi}]_{\partial\Omega} - \frac{1}{2} [\gamma^\Omega \psi, \theta \gamma_c^\Omega \bar{\psi}]_{\partial\Omega}. \end{aligned}$$

We have $\text{Re}(m_2) = 0$, indeed

$$\begin{aligned} \text{Re} \{ [\gamma_c^\Omega \psi, \theta \gamma^\Omega \bar{\psi}]_{\partial\Omega} \} &= \text{Re} \left\{ \overline{[\gamma_c^\Omega \psi, \theta \gamma^\Omega \bar{\psi}]_{\partial\Omega}} \right\} \\ &= \text{Re} \{ [\gamma_c^\Omega \bar{\psi}, \theta \gamma^\Omega \psi]_{\partial\Omega} \} = \text{Re} \{ [\gamma^\Omega \psi, \theta \gamma_c^\Omega \bar{\psi}]_{\partial\Omega} \}, \end{aligned}$$

where the last equality is an application of the property $[\mathbf{u}, \theta(\mathbf{v})]_{\partial\Omega} = [\mathbf{v}, \theta(\mathbf{u})]_{\partial\Omega}$ for $\mathbf{u}, \mathbf{v} \in \mathbb{H}(\partial\Omega)$. To deal with $\text{Re}(m_1)$, observe that we have $\text{Re} \{ [\mathbf{v}, \theta(\bar{\mathbf{v}})]_{\partial\Omega} \} = \text{Re} \{ \langle v, \bar{q} \rangle_{\partial\Omega} + \langle \bar{v}, q \rangle_{\partial\Omega} \} = 2 \text{Re} \{ \langle v, \bar{q} \rangle_{\partial\Omega} \}$ for $\mathbf{v} = (v, q) \in \mathbb{H}(\partial\Omega)$. Thus

$$\begin{aligned} \frac{1}{2} \text{Re} \{ [\gamma^\Omega \psi, \theta \gamma^\Omega \bar{\psi}]_{\partial\Omega} \} &= \text{Re} \{ \langle \gamma_D^\Omega \psi, \gamma_N^\Omega \bar{\psi} \rangle_{\partial\Omega} \} \\ &= \text{Re} \left\{ \int_{\Omega} (|\nabla \psi|^2 + \psi \Delta \bar{\psi}) d\mathbf{x} \right\} = \|\psi\|_{\mathbb{H}^1(\Omega)}^2, \end{aligned}$$

where we integrated by parts and lastly used the fact that ψ is a solution to the Helmholtz equation with $\kappa = \iota$, so that $\Delta \psi = \psi$. Similarly, we get

$$-\frac{1}{2} \text{Re} \{ [\gamma_c^\Omega \psi, \theta \gamma_c^\Omega \bar{\psi}]_{\partial\Omega} \} = \|\psi\|_{\mathbb{H}^1(\mathbb{R}^d \setminus \Omega)}^2,$$

therefore

$$\text{Re} \{ [\mathbf{A}_\kappa^\Omega(\mathbf{u}), \theta(\bar{\mathbf{u}})]_{\partial\Omega} \} = \|\psi\|_{\mathbb{H}^1(\Omega)}^2 + \|\psi\|_{\mathbb{H}^1(\mathbb{R}^d \setminus \Omega)}^2.$$

Now, note that

$$\|\psi\|_{\mathbb{H}^1(\Delta, \Omega)}^2 = \|\psi\|_{\mathbb{H}^1(\Omega)}^2 + \|\Delta \psi\|_{L^2(\Omega)}^2 = \|\psi\|_{\mathbb{H}^1(\Omega)}^2 + \|\psi\|_{L^2(\Omega)}^2 \leq 2\|\psi\|_{\mathbb{H}^1(\Omega)}^2,$$

and by the continuity of the trace operators, there exists $C > 0$ such that

$$\begin{aligned} \|\gamma_D^\Omega V\|_{\mathbb{H}^{1/2}(\partial\Omega)}^2 + \|\gamma_N^\Omega V\|_{\mathbb{H}^{-1/2}(\partial\Omega)}^2 &\leq C \|V\|_{\mathbb{H}^1(\Delta, \Omega)}^2 \quad \forall V \in \mathbb{H}^1(\Delta, \Omega), \\ \|\gamma_{D,c}^\Omega V\|_{\mathbb{H}^{1/2}(\partial\Omega)}^2 + \|\gamma_{N,c}^\Omega V\|_{\mathbb{H}^{-1/2}(\partial\Omega)}^2 &\leq C \|V\|_{\mathbb{H}^1(\Delta, \mathbb{R}^d \setminus \Omega)}^2 \quad \forall V \in \mathbb{H}^1(\Delta, \mathbb{R}^d \setminus \Omega). \end{aligned}$$

Therefore

$$\begin{aligned} \text{Re} \{ [\mathbf{A}_\kappa^\Omega(\mathbf{u}), \theta(\bar{\mathbf{u}})]_{\partial\Omega} \} &= \|\psi\|_{\mathbb{H}^1(\Omega)}^2 + \|\psi\|_{\mathbb{H}^1(\mathbb{R}^d \setminus \Omega)}^2 \\ &\geq \frac{1}{2C} \left(\|\gamma_D^\Omega \psi\|_{\mathbb{H}^{1/2}(\partial\Omega)}^2 + \|\gamma_{D,c}^\Omega \psi\|_{\mathbb{H}^{1/2}(\partial\Omega)}^2 + \|\gamma_N^\Omega \psi\|_{\mathbb{H}^{-1/2}(\partial\Omega)}^2 + \|\gamma_{N,c}^\Omega \psi\|_{\mathbb{H}^{-1/2}(\partial\Omega)}^2 \right) \\ &\geq \frac{1}{4C} \left(\|(\gamma_D^\Omega - \gamma_{D,c}^\Omega) \psi\|_{\mathbb{H}^{1/2}(\partial\Omega)}^2 + \|(\gamma_N^\Omega - \gamma_{N,c}^\Omega) \psi\|_{\mathbb{H}^{-1/2}(\partial\Omega)}^2 \right) = \frac{1}{4C} \|\mathbf{u}\|_{\mathbb{H}(\partial\Omega)}^2, \end{aligned}$$

where we used the triangular inequality and the jump relations (4.3). \square

Proposition A.2. *Assume that either $\Omega \subset \mathbb{R}^d$ is bounded or $\mathbb{R}^d \setminus \Omega$ is bounded. Then for all $\mathbf{u} \in \mathbb{H}(\partial\Omega)$, we have $\text{Im}\{[\mathbf{A}_\kappa^\Omega(\mathbf{u}), \bar{\mathbf{u}}]_{\partial\Omega}\} \geq 0$.*

Proof. Assume first that $\mathbb{R}^d \setminus \Omega$ is bounded, pick an arbitrary $\mathbf{u} \in \mathbb{H}(\partial\Omega)$ and set $\psi(\mathbf{x}) := \mathbf{G}_\kappa^\Omega(\mathbf{u})(\mathbf{x})$. We have $[\gamma^\Omega(\psi)] = \mathbf{u}$ according to the jump formula (4.3) and, on the other hand, $\{\gamma^\Omega(\psi)\} = \mathbf{A}_\kappa^\Omega(\mathbf{u})$ according to definition (4.6). As a consequence, developing the expression $2[\mathbf{A}_\kappa^\Omega(\mathbf{u}), \bar{\mathbf{u}}]_{\partial\Omega} = [\gamma^\Omega(\psi) + \gamma_c^\Omega(\psi), \gamma^\Omega(\bar{\psi}) - \gamma_c^\Omega(\bar{\psi})]_{\partial\Omega}$, yields

$$\begin{aligned} 2[\mathbf{A}_\kappa^\Omega(\mathbf{u}), \bar{\mathbf{u}}]_{\partial\Omega} &= [\gamma^\Omega(\psi), \gamma^\Omega(\bar{\psi})]_{\partial\Omega} - [\gamma_c^\Omega(\psi), \gamma_c^\Omega(\bar{\psi})]_{\partial\Omega} \\ &\quad + [\gamma_c^\Omega(\psi), \gamma^\Omega(\bar{\psi})]_{\partial\Omega} - [\gamma^\Omega(\psi), \gamma_c^\Omega(\bar{\psi})]_{\partial\Omega} \\ (A.1) \quad &= [\gamma^\Omega(\psi), \gamma^\Omega(\bar{\psi})]_{\partial\Omega} - [\gamma_c^\Omega(\psi), \gamma_c^\Omega(\bar{\psi})]_{\partial\Omega} \\ &\quad + 2 \operatorname{Re}\{[\gamma_c^\Omega(\psi), \gamma^\Omega(\bar{\psi})]_{\partial\Omega}\}. \end{aligned}$$

Next observe that each of the first two terms in the right-hand side above takes the form $[\mathbf{v}, \bar{\mathbf{v}}]_{\partial\Omega}$ and satisfies $[\bar{\mathbf{v}}, \mathbf{v}]_{\partial\Omega} = [\bar{\mathbf{v}}, \mathbf{v}]_{\partial\Omega} = -[\mathbf{v}, \bar{\mathbf{v}}]_{\partial\Omega}$ which means that they are pure imaginary numbers, i.e. $i[\mathbf{v}, \bar{\mathbf{v}}]_{\partial\Omega} \in \mathbb{R}$. As a consequence

$$\begin{aligned} (A.2) \quad 2i \operatorname{Im}\{[\mathbf{A}_\kappa^\Omega(\mathbf{u}), \bar{\mathbf{u}}]_{\partial\Omega}\} &= +[\gamma^\Omega(\psi), \gamma^\Omega(\bar{\psi})]_{\partial\Omega} \\ &\quad - [\gamma_c^\Omega(\psi), \gamma_c^\Omega(\bar{\psi})]_{\partial\Omega}. \end{aligned}$$

We examine each term in the right-hand side of this identity. Both ψ and $\bar{\psi}$ satisfy a homogeneous Helmholtz equation in $\mathbb{R}^d \setminus \bar{\Omega}$ and, since it is a bounded domain, we can apply Green's formula in $\mathbb{R}^d \setminus \bar{\Omega}$. This implies that the second term in the right-hand side of (A.2) vanishes:

$$\begin{aligned} [\gamma_c^\Omega(\psi), \gamma_c^\Omega(\bar{\psi})]_{\partial\Omega} &= \int_{\partial\Omega} \gamma_{\mathbf{D},c}^\Omega(\psi) \gamma_{\mathbf{N},c}^\Omega(\bar{\psi}) - \gamma_{\mathbf{N},c}^\Omega(\psi) \gamma_{\mathbf{D},c}^\Omega(\bar{\psi}) d\sigma \\ &= \int_{\mathbb{R}^d \setminus \bar{\Omega}} \psi(\Delta \bar{\psi} + \kappa^2 \bar{\psi}) - \bar{\psi}(\Delta \psi + \kappa^2 \psi) d\mathbf{x} = 0. \end{aligned}$$

To study the first term in (A.2) choose $\rho > 0$ large enough to have $\mathbb{R}^d \setminus \Omega \subset \mathbf{B}_\rho$ where \mathbf{B}_ρ refers to the open ball of center 0 and radius ρ . Applying Green's formula in $\Omega \cap \mathbf{B}_\rho$ gives

$$\begin{aligned} [\gamma^\Omega(\psi), \gamma^\Omega(\bar{\psi})]_{\partial\Omega} &= \int_{\partial\Omega} \gamma_{\mathbf{D}}^\Omega(\psi) \gamma_{\mathbf{N}}^\Omega(\bar{\psi}) - \gamma_{\mathbf{N}}^\Omega(\psi) \gamma_{\mathbf{D}}^\Omega(\bar{\psi}) d\sigma \\ &= \int_{\Omega \cap \mathbf{B}_\rho} \psi(\Delta \bar{\psi} + \kappa^2 \bar{\psi}) - \bar{\psi}(\Delta \psi + \kappa^2 \psi) d\mathbf{x} \\ &\quad + \int_{\partial\mathbf{B}_\rho} \bar{\psi} \partial_\rho \psi - \psi \partial_\rho \bar{\psi} d\sigma_\rho \end{aligned}$$

where $\partial_\rho \psi$ refers to the Neumann trace on $\partial\mathbf{B}_\rho$ and $d\sigma_\rho$ is the surface measure on $\partial\mathbf{B}_\rho$. The volume terms vanish because $\Delta \psi + \kappa^2 \psi = 0$ in Ω . Multiplying this identity by $-i\kappa$ then leads to

$$\begin{aligned} -i\kappa[\gamma^\Omega(\psi), \gamma^\Omega(\bar{\psi})]_{\partial\Omega} &= \int_{\partial\mathbf{B}_\rho} i\kappa \bar{\psi} \partial_\rho \psi + i\kappa \psi \partial_\rho \bar{\psi} d\sigma_\rho = 2 \operatorname{Re}\left\{ \int_{\partial\mathbf{B}_\rho} i\kappa \psi \partial_\rho \bar{\psi} d\sigma \right\} \\ &= - \int_{\partial\mathbf{B}_\rho} |\partial_\rho \psi - i\kappa \psi|^2 d\sigma + \int_{\partial\mathbf{B}_\rho} |\partial_\rho \psi|^2 + \kappa^2 |\psi|^2 d\sigma \\ &\geq - \int_{\partial\mathbf{B}_\rho} |\partial_\rho \psi - i\kappa \psi|^2 d\sigma. \end{aligned}$$

Since this inequality must hold for any $\rho > 0$ large enough, we can pass to the limit $\rho \rightarrow \infty$ and, taking account of Sommerfeld's radiation condition satisfied by $\psi = \mathbf{G}_\kappa^\Omega(\mathbf{u})$, we finally conclude that $\text{Im}\{[\mathbf{A}_\kappa^\Omega(\mathbf{u}), \bar{\mathbf{u}}]_{\partial\Omega}\} = -i[\gamma^\Omega(\psi), \gamma^\Omega(\bar{\psi})]_{\partial\Omega}/2 \in [0, +\infty)$.

To conclude the proof, let us consider the case where Ω is bounded, and denote $\Omega^c := \mathbb{R}^d \setminus \bar{\Omega}$. Because $\mathbf{n}_{\Omega^c} = -\mathbf{n}_\Omega$, we conclude that $\gamma^{\Omega^c} = -\theta \circ \gamma_c^\Omega$, $\gamma_c^{\Omega^c} = -\theta \circ \gamma^\Omega$, and $\mathbf{G}_\kappa^{\Omega^c} = \mathbf{G}_\kappa^\Omega \circ \theta$, and hence $\mathbf{A}_\kappa^{\Omega^c} = -\theta \circ \mathbf{A}_\kappa^\Omega \circ \theta$. The domain Ω^c is unbounded, so we can apply the first part of the present proof, which finally yields

$$\begin{aligned} \text{Im}\{[\mathbf{A}_\kappa^{\Omega^c}(\mathbf{u}), \bar{\mathbf{u}}]_{\partial\Omega}\} &= -\text{Im}\{[\theta \circ \mathbf{A}_\kappa^{\Omega^c} \circ \theta(\mathbf{u}), \bar{\mathbf{u}}]_{\partial\Omega}\} \\ &= +\text{Im}\{[\mathbf{A}_\kappa^{\Omega^c} \circ \theta(\mathbf{u}), \overline{\theta(\mathbf{u})}]_{\partial\Omega}\} \geq 0. \end{aligned}$$

□

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