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► **To cite this version:**

Shangrong Lin, Zhongmin Hu, Yingping Wang, Xiuzhi Chen, Bin He, et al.. Underestimated Interannual Variability of Terrestrial Vegetation Production by Terrestrial Ecosystem Models. *Global Biogeochemical Cycles*, 2023, 37 (4), 10.1029/2023gb007696 . hal-04087238

HAL Id: hal-04087238

<https://hal.science/hal-04087238v1>

Submitted on 3 May 2023

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Global Biogeochemical Cycles®



RESEARCH ARTICLE

10.1029/2023GB007696

Shangrong Lin and Zhongmin Hu contributed equally to this work.

Key Points:

- Current terrestrial ecosystem models (TEMs) substantially underestimate the interannual variability (IAV) of gross primary production (GPP) in comparison to observations at global flux sites
- The IAV of GPP in TEMs is strongly depended on leaf area index (LAI), which is one of the causes for the underestimation of IAV in GPP and the simulated IAV in LAI from TEMs is much less than the observation
- Precisely characterizing the contribution of vegetation physiological changes may improve the performance of predicting IAV in GPP from TEMs

Supporting Information:

Supporting Information may be found in the online version of this article.

Correspondence to:

W. Yuan,
yuanwp3@mail.sysu.edu.cn

Citation:

Lin, S., Hu, Z., Wang, Y., Chen, X., He, B., Song, Z., et al. (2023). Underestimated interannual variability of terrestrial vegetation production by terrestrial ecosystem models. *Global Biogeochemical Cycles*, 37, e2023GB007696. <https://doi.org/10.1029/2023GB007696>

Received 11 JAN 2023
Accepted 20 MAR 2023

Author Contributions:

Conceptualization: Shangrong Lin, Zhongmin Hu, Yingping Wang, Wenping Yuan

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Underestimated Interannual Variability of Terrestrial Vegetation Production by Terrestrial Ecosystem Models

Shangrong Lin^{1,2} , Zhongmin Hu^{2,3} , Yingping Wang⁴ , Xiuzhi Chen^{1,2} , Bin He⁵ , Zhaoliang Song⁶ , Shaobo Sun⁶ , Chaoyang Wu⁷ , Yi Zheng^{1,2} , Xiaosheng Xia¹ , Liyang Liu⁸, Jing Tang^{9,10} , Qing Sun¹¹ , Fortunat Joos¹¹, and Wenping Yuan^{1,2} 

¹School of Atmospheric Sciences, Guangdong Province Data Center of Terrestrial and Marine Ecosystems Carbon Cycle, Sun Yat-sen University, Zhuhai, China, ²Southern Marine Science and Engineering Guangdong Laboratory (Zhuhai), Guangdong, China, ³College of Ecology and Environment, Hainan University, Haikou, China, ⁴CSIRO, Oceans and Atmosphere, Aspendale, VIC, Australia, ⁵College of Global Change and Earth System Science, Beijing Normal University, Beijing, China, ⁶Institute of Surface-Earth System Science, School of Earth System Science, Tianjin University, Tianjin, China, ⁷The Key Laboratory of Land Surface Pattern and Simulation, Institute of Geographical Sciences and Natural Resources Research, Chinese Academy of Sciences, Beijing, China, ⁸Laboratoire des Sciences du Climat et de l'Environnement, IPSL, CEA-CNRS-UVSQ, Université Paris-Saclay, Gif-sur-Yvette, France, ⁹Department of Physical Geography and Ecosystem Science, Lund University, Lund, Sweden, ¹⁰Department of Biology, University of Copenhagen, Copenhagen, Denmark, ¹¹Climate and Environmental Physics, Physics Institute, University of Bern, Bern, Switzerland

Abstract Vegetation gross primary production (GPP) is the largest terrestrial carbon flux and plays an important role in regulating the carbon sink. Current terrestrial ecosystem models (TEMs) are indispensable tools for evaluating and predicting GPP. However, to which degree the TEMs can capture the interannual variability (IAV) of GPP remains unclear. With large data sets of remote sensing, in situ observations, and predictions of TEMs at a global scale, this study found that the current TEMs substantially underestimate the GPP IAV in comparison to observations at global flux towers. Our results also showed the larger underestimations of IAV in GPP at nonforest ecosystem types than forest types, especially in arid and semiarid grassland and shrubland. One cause of the underestimation is that the IAV in GPP predicted by models is strongly dependent on canopy structure, that is, leaf area index (LAI), and the models underestimate the changes of canopy physiology responding to climate change. On the other hand, the simulated interannual variations of LAI are much less than the observed. Our results highlight the importance of improving TEMs by precisely characterizing the contribution of canopy physiological changes on the IAV in GPP and of clarifying the reason for the underestimated IAV in LAI. With these efforts, it may be possible to accurately predict the IAV in GPP and the stability of the global carbon sink in the context of global climate change.

1. Introduction

Terrestrial vegetation production is a critical component of the global carbon cycle and plays an important role in regulating terrestrial carbon sinks (Beer et al., 2010; Jung et al., 2017). In particular, interannual variability (IAV) in vegetation production substantially regulates terrestrial carbon sinks (Desai et al., 2010), atmospheric CO₂ concentration (Yuan et al., 2019), and the climate system (Poulter et al., 2014). For example, previous studies indicated that the IAV in global gross vegetation production strongly correlates with IAV in atmospheric CO₂ concentration (Reichstein et al., 2013). With the rising frequency of extreme climate events, vegetation production shows an increasing interannual fluctuation (Reichstein et al., 2013; Zscheischler, Mahecha, et al., 2014; Zscheischler, Michalak, et al., 2014), which also indicates a decreasing stability of ecosystem carbon sinks (Messori et al., 2019; Zscheischler, Mahecha, et al., 2014; Zscheischler, Michalak, et al., 2014). With more frequent climate extremes under climate change (Seneviratne et al., 2012), the impact of IAV in gross primary production (GPP) is likely to increase (Reichstein et al., 2013). Thus, a better understanding of the performance of modeled IAV in GPP will help inferring how carbon sinks and sources will change across regions in the future (Z. Li et al., 2020; Poulter et al., 2014).

Terrestrial ecosystem models (TEMs) are an irreplaceable tool for estimating and predicting the terrestrial carbon sink and its IAV (Friedlingstein et al., 2020). However, there are substantial differences in the simulated IAV in gross vegetation production from various ecosystem models (Cai et al., 2014; M. Chen et al., 2017). For example, a recent study showed large differences of IAV (characterized by the standard deviation in annual GPP,

Data curation: Bin He, Yi Zheng, Xiaosheng Xia, Liyang Liu, Jing Tang, Qing Sun
Funding acquisition: Wenping Yuan
Investigation: Bin He
Methodology: Shangrong Lin
Supervision: Zhaoliang Song, Chaoyang Wu, Wenping Yuan
Validation: Shangrong Lin
Writing – original draft: Shangrong Lin, Zhongmin Hu, Yingping Wang, Xiuzhi Chen, Shaobo Sun, Wenping Yuan
Writing – review & editing: Shangrong Lin, Zhongmin Hu, Wenping Yuan

ranging from 1.38 to 5.89 Pg C yr⁻¹) in simulated GPP over 11 TEMs (Zheng et al., 2020). Similarly, O’Sullivan et al. (2020) found that the global average variance of IAV in GPP simulated by TEMs is almost 1.21 Pg C yr⁻¹, which is larger than the one obtained from satellite-based models (1.01 Pg C yr⁻¹) and machine-learning models (0.34 Pg C yr⁻¹). In addition, when tested against site-based observations in terms of IAV in GPP, TEMs typically perform very poorly (Keenan et al., 2012; Verma et al., 2015). For example, Keenan et al. (2012) tested 16 TEMs and three remote sensing products against the measurements at 11 long-term eddy covariance sites and found that none of the models reproduced the observed IAV in GPP. Therefore, Earth System Models, which have integrated the TEMs, may induce large uncertainties for reproducing IAV of gross vegetation production as well as the terrestrial carbon cycle in the future (Bonan & Doney, 2018; Winkler et al., 2019).

Simulated IAV in GPP remains highly uncertain and is related to the poor representation of model formulation (Dietze et al., 2011). In general, the simulated IAV in GPP derived from TEMs highly depends on two sources, including (a) changes in physiological processes such as growing season length, and photosynthesis rates (X. Luo et al., 2019; MacBean et al., 2018; Xia et al., 2015; Zscheischler et al., 2016) and (b) changes in vegetation structural variable, that is, leaf area index (J. M. Chen et al., 2019; S. Chen et al., 2019; Hu et al., 2018). Although most of the key carbon cycle processes have been integrated into models, there are large challenges in reproducing IAV in GPP because of the complicated processes and responses to environmental variables (Verma et al., 2015; Zheng et al., 2020). The physiological responses of vegetation to environmental changes are instantaneous (Liu et al., 2021; X. Luo et al., 2019; Zscheischler et al., 2016), but the structural responses are lagged (Bastos et al., 2020; Bertrand et al., 2011; A. Zhao et al., 2020; Q. Zhao et al., 2020). For example, although the canopy structure of Amazon forests shows slight changes over the years, the photosynthetic rate largely differs across years (Saleska et al., 2016; Wu et al., 2017). Magney et al. (2019) showed similar results in temperate forests. The understanding of the differential changes in physiology and structure in anomalous climate conditions have not yet been applied to improve model predictive skills (Hu et al., 2018), which may be the main cause for the low predictive skills for reproducing IAV in GPP.

This study aims to evaluate the performance of TEMs for reproducing IAV in GPP against observations at eddy covariance towers globally and to investigate the relationships of IAV in GPP with meteorological variables and leaf area index to understand its environmental and physiological controls. Specific objectives are to (a) evaluate the modeling capabilities of TEMs for simulating IAV in GPP based on global observations, (b) examine the performance of TEMs for reproducing vegetation structural changes, and (c) quantify the impacts of vegetation physiological and structural changes on IAV in GPP.

2. Materials and Methods

2.1. Terrestrial Ecosystem Models

This study included nine TEM data sets from the TRENDY v10 ensemble since 2000 (Friedlingstein et al., 2022): Community Atmosphere Biosphere Land Exchange (CABLE-POP, Haverd et al., 2017, hereafter CABLEP), Community Land Model (CLM, Lawrence et al., 2019), Dynamic Land Ecosystem Model (DLEM, Tian et al., 2015), Interactions between Surface, Biosphere, and Atmosphere (IBSA, Delire et al., 2020), Integrated Biosphere Simulator (IBIS, Yuan et al., 2014), Lund-Potsdam-Jena General Ecosystem Simulator (LPJ-GUESS, Smith et al., 2014, hereafter LPJG), Land surface Processes and eXchanges (LPX, Lienert & Joos, 2018), Organizing Carbon and Hydrology in Dynamic Ecosystems (ORCHIDEEv3, Vuichard et al., 2019, hereafter ORCHIDEE), and Vegetation Integrated Simulator for Trace gases (VISIT, Kato et al., 2013). We used the simulations in model experiments with varying CO₂ concentrations and climate (i.e., S2 experiment), which are close to the scenarios in the real world. The simulation in S2 experiment considers variability in CO₂ and climate, with the assumption that land cover type is stable compared to S3 experiment (Friedlingstein et al., 2022). All TEMs from the TRENDY v10 were driven by CRUJRA data set with a coarse spatial resolution of 0.5° × 0.5° (see Section 2.2). In addition, we run four TEMs (i.e., IBIS, LPJG, LPX, and ORCHIDEE) driven by site-based meteorological measurements to investigate whether the coarse spatial resolution of climate forcing impacted the model performance when reproducing IAV in GPP.

The annual GPP and LAI were averaged from monthly simulations during the growing season. This study defined the growing season at those months with a mean temperature was above 0°C based on the Climatic Research Unit Japanese Reanalysis (CRU-JRA, <http://catalogue.ceda.ac.uk/uuid/863a47a6d8414b6982e1396c69a9efe8>)

Table 1
Investigated Sites in This Study (Detailed Site Information Could Be Found in Table S1 in Supporting Information S1)

	Sites	Site-years	Mean annual temperature (°C)	Mean annual precipitation (mm)
ENF	53	457	−3.2–14.2	523–1,316
EBF	15	103	10.7–26.1	650–4,000
DBF	27	228	0.3–15.1	563–2,275
MF	12	70	1.3–15.8	408–2,100
SAV	16	141	15.8–21.9	240–1,449
GRA	49	374	−9.7–8.7	93–1,100
SHR	15	106	−14.3–27.2	220–588
CRO	24	207	7.6–18.0	470–1150

Note. We chose eight types of major biomes including evergreen needleleaf forest (ENF), evergreen broadleaf forest (EBF), deciduous broadleaf forest (DBF), mixed forest (MF), savanna (SAV), grassland (GRA), shrub (SHR), and cropland (CRO).

data set. Since the spatial resolution of GPP and LAI varies among models, we resampled all the TEM simulated GPP and LAI into a $0.5^\circ \times 0.5^\circ$ spatial resolution.

2.2. Climate and Satellite Data

The meteorological forcing data in TRENDY v10 ensemble is CRUJRA data set, which is a gridded land surface blend of the CRU and the JRA data sets with a spatial resolution of $0.5^\circ \times 0.5^\circ$. We chose air temperature (TEMP), shortwave radiation (SW), precipitation (PRE), and vapor pressure deficit (VPD) to examine the responses of GPP to climate change. VPD was calculated based on air temperature and actual vapor pressure derived from this data set (Yuan et al., 2019). All the annual meteorological variables were calculated as the average from only the growing season data.

To compare modeled LAI with observation-based LAI data, we utilized the satellite-based 500-m spatial resolution LAI product Global Land Surface Satellite (GLASS, Liang et al., 2021) based on Moderate-resolution Imaging Spectroradiometer (MODIS) observations. This product is generated with physical inversion techniques using the general regression neural networks (GRNNs) method. The GRNNs are trained with fused reflectance values for

each MODIS biome and CYCLOPES LAI products. Research has shown that the GLASS-LAI product is in good agreement with ground measured LAI (Fang et al., 2013; Xiao et al., 2014, 2017; B. Xu et al., 2018). The upscale ground measured LAI also showed that the GLASS-LAI product is more accurate than the other existing LAI product in most biomes, so it can be used as a proxy for annual LAI observations (B. Xu et al., 2018). We aggregated the annual LAI observation as the mean LAI values from GLASS-LAI product during the growing season (defined as months with mean air temperature higher than 0°C).

2.3. Data Set at the Eddy Covariance Sites

The IAV in GPP from eddy covariance (EC) sites observation in FLUXNET 2015 (Pastorello et al., 2020), Integrated Carbon Observation System (ICOS, <https://www.icos-cp.eu/data-products/2G60-ZHAK>), AmeriFlux (<https://ameriflux.lbl.gov/sites/site-search/>), OzFlux (<https://data.ozflux.org.au/portal/home.jsp>), and AsiaFlux (<https://db.cger.nies.go.jp/asiafluxdb/>), was treated as the observation of IAV in GPP in this study. The annual GPP was aggregated from the daytime partition method (GPP_DT_VUT_REF) derived from month GPP data during the growing season. The effective annual GPP, aggregated with more than 10 months of GPP data with its quality control tag >0.8 . We excluded the sites with less than 4 years of effective annual GPP, so a total of 211 EC sites including 1686 site-years data were selected (Table 1 and Table S1 in Supporting Information S1). Eight types of major biomes including evergreen needleleaf forest (ENF), evergreen broadleaf forest (EBF), deciduous broadleaf forest (DBF), mixed forest (MF), savanna (SAV), grassland (GRA), shrub (SHR), and cropland (CRO) were selected to evaluate the IAV in GPP at the sites. All TEMs simulated GPP for each ecosystem type individually within a given $0.5 \times 0.5^\circ$ grid, and we compared the simulations of the corresponding ecosystem types against the GPP derived from EC site measurements.

Since the TEMs in TRENDY v10 ensemble are driven by the coarse spatial resolution climate data, the meteorological conditions may differ from those at the flux sites and lead to uncertainties in the evaluation of IAV in GPP of the models. Therefore, we compared IAV in the site-measured meteorology data (i.e., SW, VPD, PRE and TEMP) with the CRU-JRA data at the selected sites.

2.4. Calculating Interannual Variability

Because the magnitudes of simulated LAI and GPP vary across TEMs (Zhang & Ye, 2021; A. Zhao et al., 2020; Q. Zhao et al., 2020) and have an annual trend, quantitative methods (i.e., anomalies and standard deviations) of IAV used in previous research (M. Chen et al., 2017; O'Sullivan et al., 2020; Yuan et al., 2009) are not applicable to this study. We evaluated the IAV of each variable for each site or grid by calculating the coefficient of variation

(CV) with annual detrended data, which has been found to be an effective measure of IAV (Cao et al., 2003). We used a linear annual detrending method to remove the annual trend from the data:

$$X_{\text{detrend,year}} = X_{\text{year}} - X_{\text{trend,year}} + X_{\text{mean}} \quad (1)$$

$$X_{\text{trend,year}} = k \times \text{year} + b \quad (2)$$

where X_{year} is the original annual variable with annual trend; $X_{\text{trend,year}}$ represents the trend of each year, whose the coefficients (k , b) in Equation 2 are fitted by a linear function with year as input and X_{year} as output. We used X_{mean} , which is averaged from X_{year} , to denote the magnitude of the variable. The detrended variable in each year is represented by $X_{\text{detrend,year}}$. The IAV, indicated by CV, in each variable (CV_x) was calculated from the detrended data:

$$CV_x = \frac{\sqrt{\frac{\sum (X_{\text{detrend,year}} - X_{\text{mean}})^2}{N}}}{X_{\text{mean}}} \quad (3)$$

where N is the total number of investigated years in each site or grid. In different vegetation types and TEMs, the magnitudes of GPP can be quite different (Zhang & Ye, 2021), so using a ratio (i.e., CV) between standard deviation of GPP and average GPP can better quantify the fluctuation of GPP over many years across regions and models (Dong et al., 2022).

2.5. Evaluating the Relationship Between Structural Changes and GPP

To evaluate how the structural changes (i.e., LAI) affect GPP, we used 211 FLUXNET sites locations to extract the annual LAI and GPP from both observed and simulated data. To estimate the influence of annual structural change to GPP, we derived the correlation (indicated by Pearson's correlation coefficient, r) between annual detrended LAI and annual aggregated GPP at each EC site. To assess the spatial pattern of IAV of LAI to GPP, we used a linear fitting method to compare CV in LAI versus CV in GPP at the EC sites. We derived CV in GLASS-LAI as observation and CV in TEMs' LAI as simulation to compare the discrepancy in the IAV in LAI at a global scale.

2.6. Separating Contributions of Structural and Physiological Changes on IAV in GPP

A machine learning model based on random forest (RF) was used to quantify the contributions of vegetation physiological and structural changes on IAV in GPP. First, we developed an RF model to reproduce IAV in GPP derived from TEMs and observed GPP at EC sites, which included the impacts of physiological and structural changes in vegetation. This study defined the structural change of vegetation as the LAI changes, and thus the contribution of structural changes to IAV in GPP is the contribution of LAI changes with other environmental variables remaining constant. The contribution of physiological changes to IAV in GPP was quantified as the impacts of meteorological variables (Peng et al., 2021; Wu et al., 2017; Zscheischler et al., 2016). We included four meteorological variables (annual mean air temperature, vapor pressure deficit, shortwave radiation and annual total precipitation) to quantify the contributions of physiological changes. To avoid the impacts of long-term changes on IAV, we used detrended meteorological variables, LAI and GPP, to develop the RF model using the "randomForest" package in R modified by Liaw and Wiener (2002). We constructed the RF model at each EC site and each pixel and randomly chose 70% of the data for training and the remaining 30% of the data for validation, and repeated this process 200 times. The simulated GPP by the RF model (GPP_{ALL}) were the mean values of all validated data in each year.

Next, to quantify the contributions of physiological and structural changes to IAV in GPP, we conducted two model experiments by holding meteorological variables and LAI constant to simulate GPP, indicated as GPP_{METO} and GPP_{LAI0} , respectively. The contributions of physiological and structural changes to IAV in GPP were calculated as follows:

$$\text{Con}_p = \frac{(\text{MSE}_{\text{LAI0}} - \text{MSE}_{\text{ALL}})}{\text{MSE}_{\text{ALL}}} \times 100\% \quad (4)$$

$$\text{MSE}_{\text{ALL}} = \frac{\sum (GPP_{\text{ALL}} - GPP_{\text{ORI}})^2}{N} \quad (5)$$

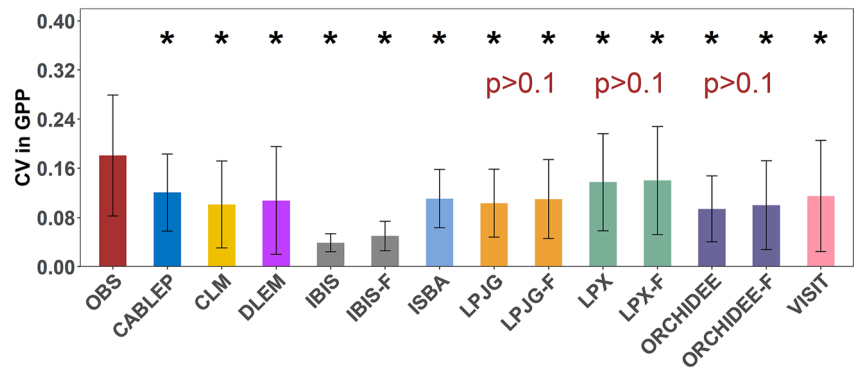


Figure 1. Comparison of the coefficient of variation of observed and simulated gross primary production (GPP) averaged from 211 eddy covariance sites. The asterisks (*) indicate statistically significant differences ($p < 0.05$) between observations (OBS) and simulations. The error bars represent the standard deviation in each model. The series of IBIS-F, LPJG-F, LPX-F, and ORCHIDEE-F indicated the interannual variability (IAV) in GPP driven by site-based meteorology data. The p -value in red color represented the paired t -test between IAV in GPP from TRENDY v10 ensemble and IAV in GPP driven by site-based meteorology data.

$$MSE_{LAI0} = \frac{\sum (GPP_{LAI0} - GPP_{ORI})^2}{N} \quad (6)$$

where GPP_{ALL} is the simulated GPP by the RF model driven by changing meteorological variables and LAI with time; GPP_{ORI} is the observed GPP at EC sites or simulated GPP by nine TEMs; Con_p indicates the contribution of physiological changes to IAV in GPP. The contribution of structural changes (Con_s) can be calculated by replacing GPP_{LAI0} to GPP_{MET0} in Equations 4 and 6. According to the above methods, we calculated the Con_p and Con_s at the site level and global scale based on nine terrestrial models from 2000 to 2020. Both Con_p and Con_s are affected by the magnitude of the input variables and GPP models; therefore, we calculated the relative contribution ratio from Con_p divided by Con_s to characterize the principal driver (i.e., physiological or structural change) of IAV in GPP from observations and simulations.

3. Results

3.1. IAV in GPP From TEMs

The TEMs underestimated the IAV (indicated by the coefficient of variation, CV) in GPP against the observations at eddy covariance (EC) sites. The mean CV values of simulated annual GPP by nine TEMs from TRENDY data set ranged from 0.04 to 0.15, all of which were significantly lower than the mean CV in the observed GPP (i.e., 0.18) (Figure 1). The GPP simulations by four TEMs (i.e., IBIS, LPJG, LPX, and ORCHIDEE), driven by site-based meteorology measurements, also showed a significant underestimation compared with the IAV in GPP observed from EC sites. In addition, both observations and simulations showed that the CV in GPP steadily decreased logarithmically with mean annual precipitation, suggesting that the IAV in GPP was larger in drier ecosystems ($p < 0.05$, Figure 2).

Further, we examine the model performance for simulating IAV in GPP for various ecosystem types and geographical regions. At nearly all ecosystem types, almost all TEMs underestimated the IAV in GPP compared with the IAV in observed GPP (Figure 3). The CV differences, defined as CV in simulated GPP minus CV in observed GPP, indicated significantly lower CV values of simulated GPP than those of observed GPP across almost all ecosystem types (Figure 3). The results showed the larger underestimates of CV in GPP by TEMs at nonforest ecosystem types (i.e., SAV, GRA, SHR, CRO) than four forest types (Figure S1 in Supporting Information S1). In

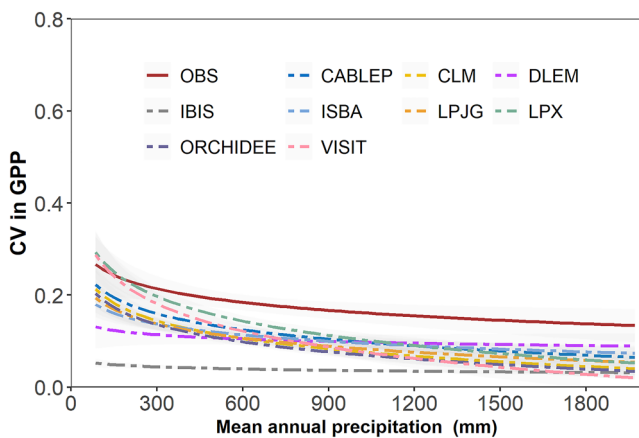


Figure 2. Spatial patterns of interannual variations in gross primary production (GPP) over 211 eddy covariance sites along the mean annual precipitation gradient. The solid line indicates the regression line of observed GPP (OBS) based on the eddy covariance measurements, and the other dashed lines indicate the regression lines of simulations by nine terrestrial ecosystem models. All the regression correlation is significant with $p < 0.05$.

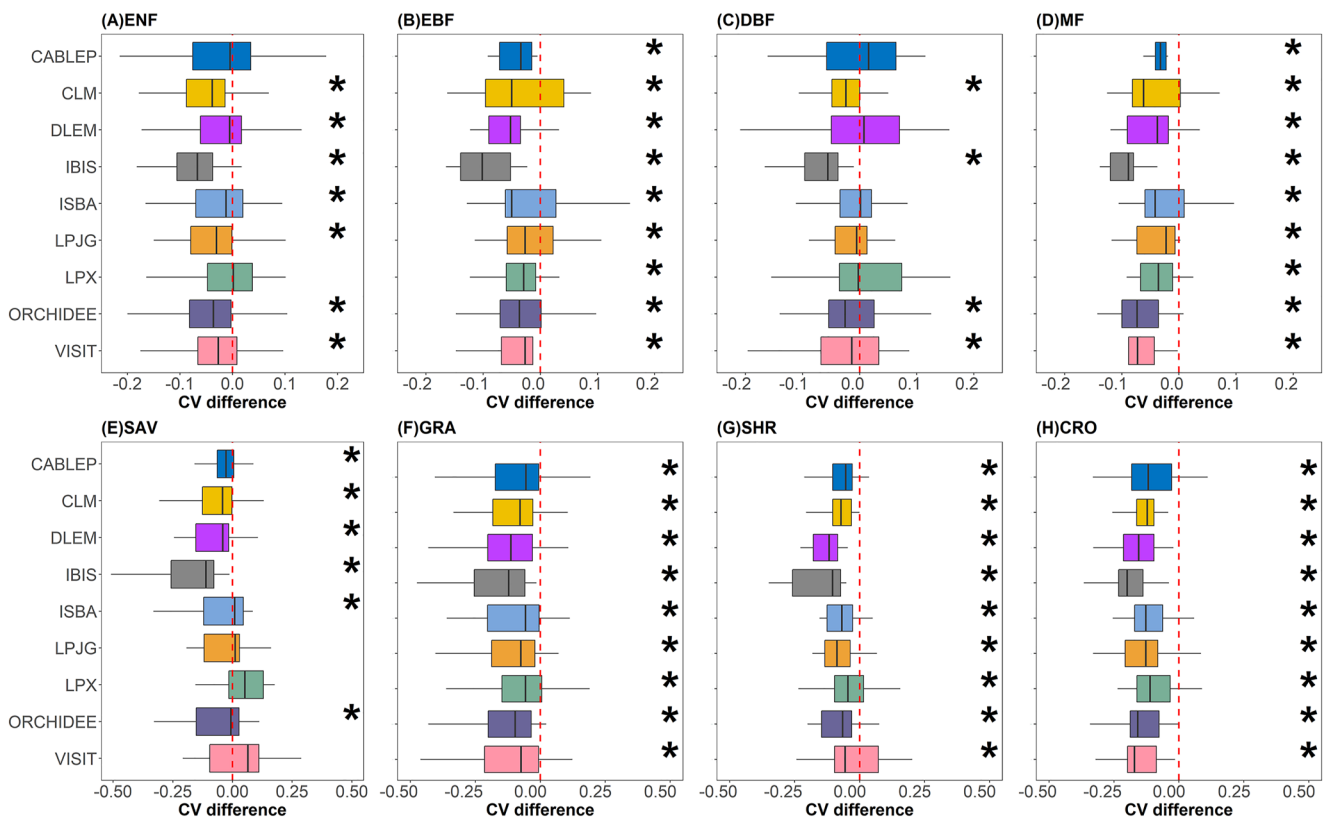


Figure 3. Difference of coefficient of variation (CV) in gross primary production between simulations and observations at eight vegetation types. The red dashed line in the middle represents the CV difference equals to zero. The asterisks (*) indicate statistically significant differences ($p < 0.05$) between simulated CV and observed CV. The abbreviations of each subplot: ENF, evergreen needleleaf forest; EBF, evergreen broadleaf forest; DBF, deciduous broadleaf forest; MF, mixed forest; SAV, savanna; GRA, grassland; SHR, shrubland; and CRO, cropland.

addition, the results also found that the TEMs underestimated the IAV in GPP at various geographical regions including Asia, Oceania, Europe, North America, South America, Northern Hemisphere, and Southern Hemisphere (Figure S3 in Supporting Information S1).

3.2. IAV in GPP Depends on IAV in LAI in TEMs

To investigate the reason for the underestimations of IAV by TEMs, we first examined the how variance of vegetation structure affects annual GPP. Our results showed that the models overestimated the dependence of GPP on LAI. On average, over all investigated sites, the correlation coefficient (r) between simulated annual LAI and annual GPP ranges from 0.60 to 0.95 for seven models (Figure 4a) except for LPJG and LPX. On the contrary, the averaged r between satellite-based LAI and observed GPP was only 0.13. In general, larger IAV in LAI simulations led to higher IAV in GPP (Figure 4b). However, the observed IAV in GPP had a weak correlation ($r = 0.2$) with IAV in LAI over all investigated sites (Figure 4b). The simulated IAV in GPP derived from most models are significantly and positively correlated with LAI at more than 50% of the EC sites (Figure 4c) except for LPJG and LPX. In comparison, the CV of the observed GPP showed weak correlations with LAI. Only at 13% of the sites, the satellite-based LAI showed a significant correlation to IAV in the observed GPP (Figure 4c). In addition, the strong correlations between simulated GPP and LAI by nine TEMs were also found at the global scale (Figure 5).

To distinguish which biome's IAV in GPP is more dependent on IAV in LAI, we compared the annual LAI and GPP at each site across eight major biomes (Figure 6). The site observation data showed that the correlation (r) between annual LAI and annual GPP was weak (~ 0.2) at most biomes. However, most TEMs showed high correlation ($r > 0.5$) between annual LAI and annual GPP at all biomes, expect for IBIS, LPJG, and LPX.

The TEMs show the strong dependence of IAV in GPP on LAI (i.e., structural variation), but they underestimate the IAV in LAI compared to satellite-based LAI derived from the GLASS-LAI data set (Figure 7), which may

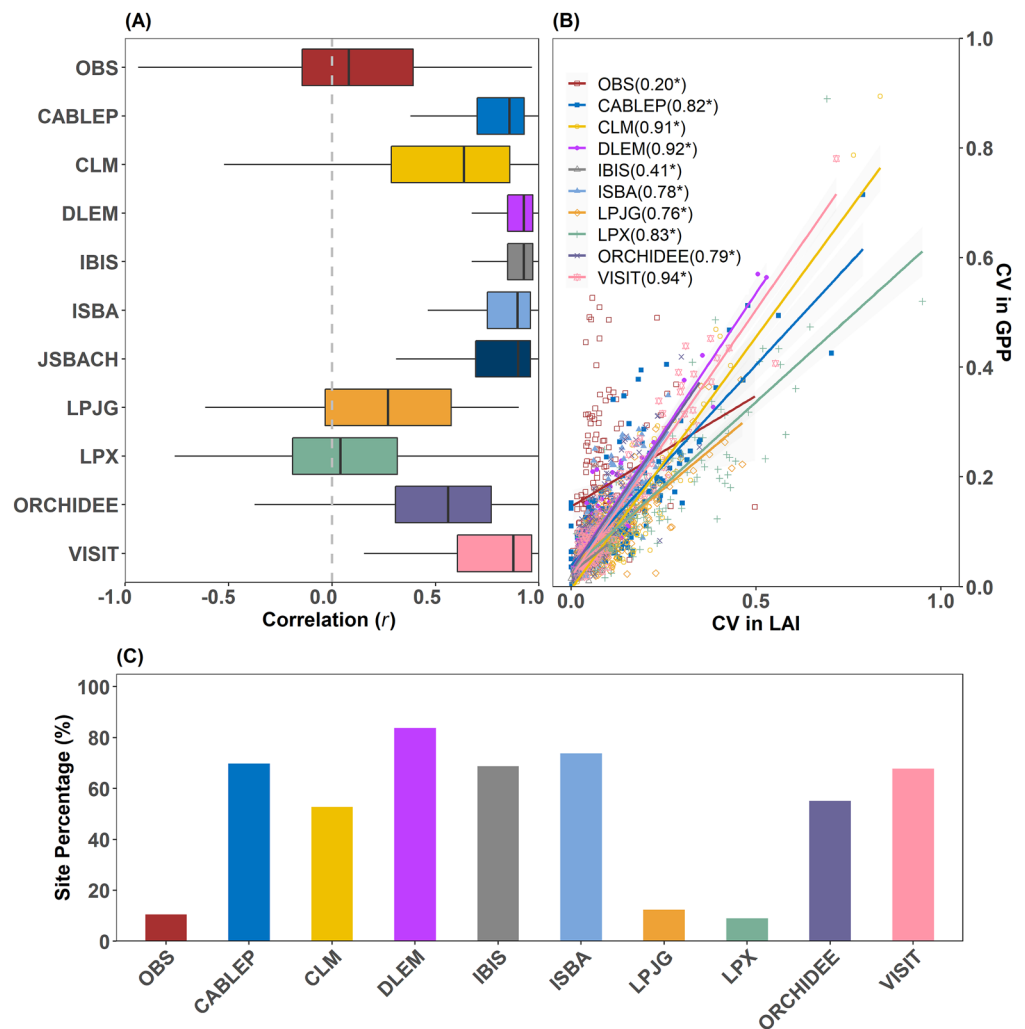


Figure 4. Comparison of correlations of interannual variability in gross primary production (GPP) and leaf area index (LAI) at 211 eddy covariance sites. (a) Boxplot of correlation coefficient (r) between annual GPP and annual LAI. OBS indicates the correlations of observed GPP and satellite-based LAI. The correlations of nine models were calculated between GPP and LAI simulations by model. (b) Correlations of coefficient of variation (CV) in GPP and CV in LAI derived from observations and simulations. The numbers between parentheses show the correlation coefficients r ; asterisks represent the statistical significance of $p < 0.05$. Each dot represents the CV in LAI and CV in GPP at a FLUXNET site location. (c) The proportion of sites with significant ($p < 0.05$) correlations between annual LAI and annual GPP within the 211 EC sites.

be one of the most important reasons for underestimating IAV in GPP by TEMs. The global mean satellite-based CV of LAI was 0.23, which was much higher than the CV of simulated LAI by nine TEMs (Figure 7). GLASS-LAI reached its maximal global area proportion when its CV in LAI equals to 0.14. On contrary, the peaks of CV in the simulated LAI by TEMs were much lower; only the ISBA and LPJG showed their largest global area proportion at a CV in LAI around 0.06, while other models did not show the available peak of CV in the simulated LAI (Figure 7).

3.3. Contribution of Physiological Changes to IAV in GPP

This study further compared the relative contribution of physiological changes (Con_p) and structural changes (Con_s) to IAV in GPP. Both Con_p and Con_s depended on the magnitude of GPP; therefore, the absolute values of Con_p and Con_s were not comparable due to different magnitudes of observed and simulated GPP. Thus, the contribution ratio between Con_p and Con_s was calculated to indicate the relative contribution of physiological and structural changes. The contribution ratio derived from observations at 211 EC sites was 5.3, suggesting that

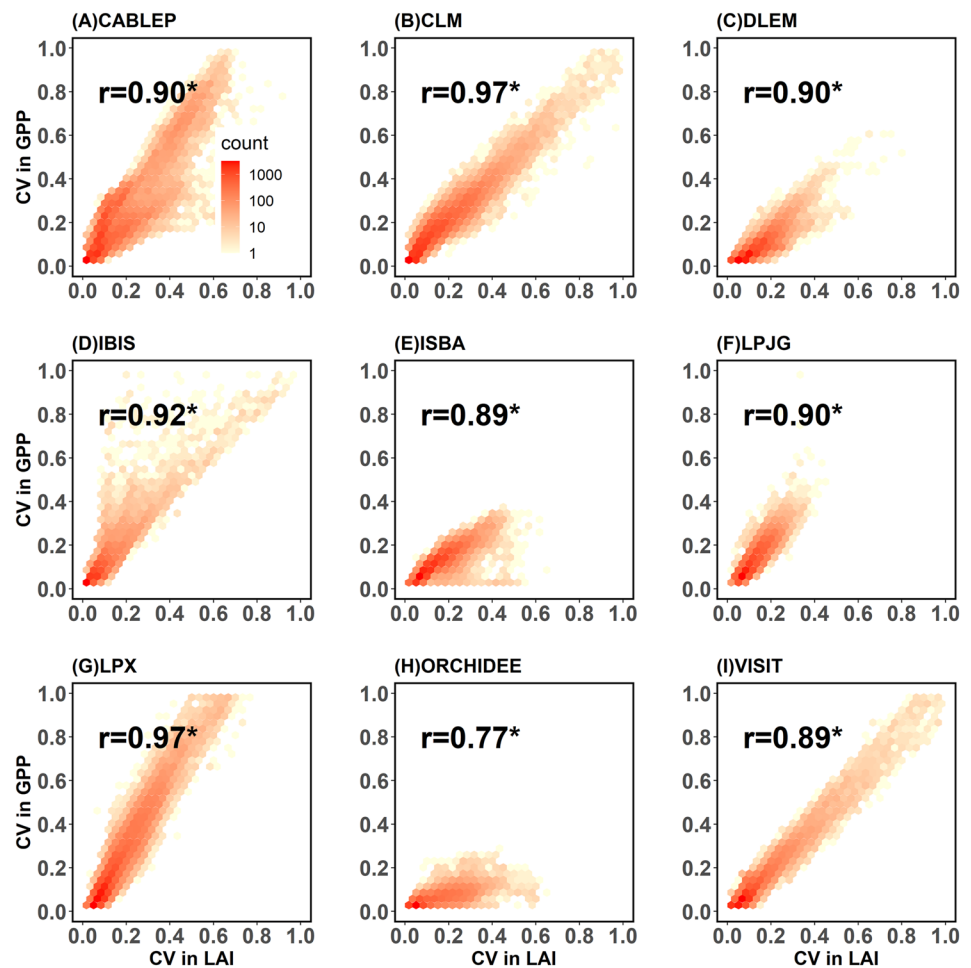


Figure 5. Density plots of correlations between coefficient of variation (CV) in leaf area index and CV in gross primary production over global vegetated pixels in terrestrial ecosystem models. Correlation coefficient (r) with an asterisk represents $p < 0.05$.

the contribution of physiological changes to IAV in GPP was five times that of structural changes (Figure 8a). However, the contribution ratios derived from simulations from TEMs ranged from 2.7 to 4.9, which were significantly lower than the observations (i.e., 5.3) expect for LPJG and LPX. Among these models, only LPJG and LPX predicted large contribution ratios (i.e., 5.1 and 5.4), which were close to the ratio derived from observations. Similarly, at the global scale, all models showed a similar contribution ratio to those at the EC sites (Figure 8b).

4. Discussions

4.1. Underestimation of GPP Interannual Variability by TEMs and Its Causes

We found that most TEMs underestimated the IAV in GPP. Other lines of evidence support our conclusion (Stocker et al., 2019; Zhang et al., 2019). For example, Zhang et al. (2019) demonstrated the low sensitivity of TEMs to climate change, resulting in underestimates of the effect of El Niño/Southern Oscillation on global GPP. Considering that IAV in GPP explained a significant proportion of IAV in the magnitude of net ecosystem production (NEP) (Yuan et al., 2009), the underestimation of IAV in GPP may result in overestimating the stability of the terrestrial carbon sink. More importantly, the terrestrial carbon sink substantially controls the interannual variations in atmospheric CO₂ growth rates (He et al., 2021). Therefore, underestimating IAV in GPP may also potentially result in underestimating the IAV in atmospheric CO₂.

Our results suggest that the overestimated coupling between LAI and GPP, in combination with underestimated IAV in LAI, caused the underestimation of GPP variability by the models (Figures 4–7). Simulated high coupling

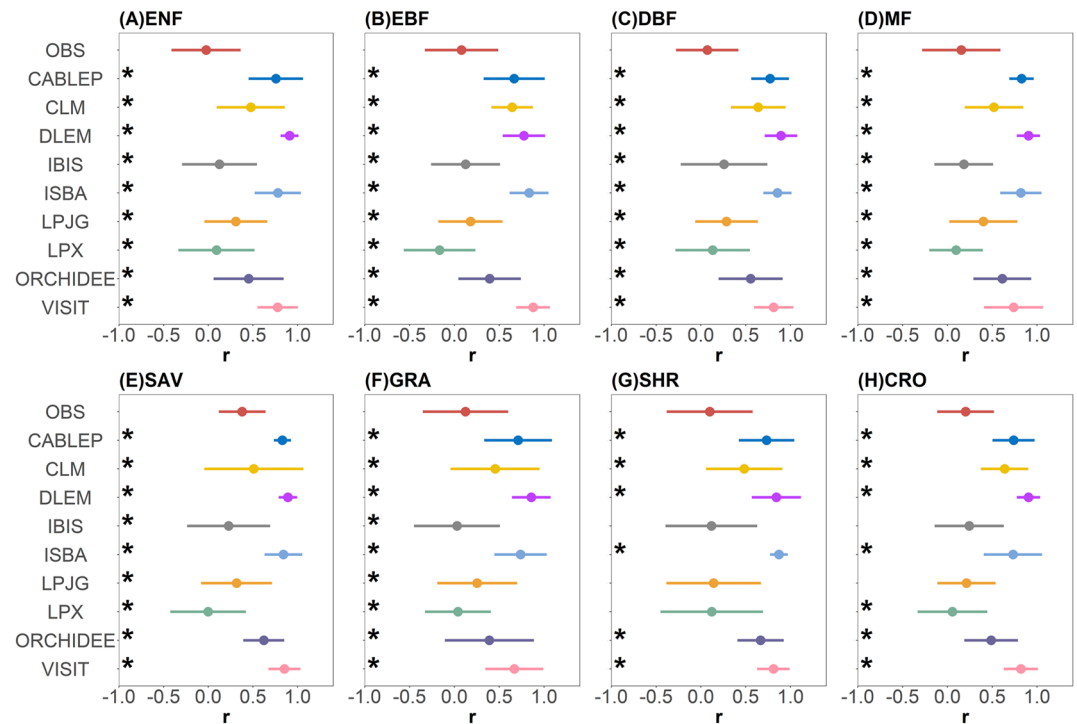


Figure 6. The relationship between annual leaf area index and annual gross primary production at site level among biomes derived from flux site observations (OBS) and simulations (TRENDY v10 ensemble). The asterisks represent the statistical significance of $p < 0.05$ between model simulations and observations. The abbreviations of each subplot: ENF, evergreen needleleaf forest; EBF, evergreen broadleaf forest; DBF, deciduous broadleaf forest; MF, mixed forest; SAV, savanna; GRA, grassland; SHR, shrubland; and CRO, cropland.

between LAI and GPP by models has been reported in previous research (J. M. Chen et al., 2019; S. Chen et al., 2019; Higuchi et al., 2005; Wang et al., 2011). However, our finding is consistent with observations showing that vegetation structure (i.e., LAI) has limited impacts compared to physiological changes (Hu et al., 2018; Liu et al., 2021; Walther et al., 2016). Studies suggested that intra-seasonal changes in meteorological conditions

can significantly affect plant leaf photosynthesis but not LAI, which, consequently affects the annual amount of GPP (Zscheischler et al., 2016). For example, Doughty et al. (2019) found that a physiological change indicator, solar induced fluorescence, detected a decrease in GPP during drought years and seasons; however, LAI and vegetation index have a limited response to such conditions (X. Li & Xiao, 2020). In addition, meteorological conditions often exhibit time-lag effects on canopy structure, which might be another reason for the decoupling between GPP and LAI (Bertrand et al., 2011; Mulder et al., 2017; Sherry et al., 2008). However, few models can reproduce the time-lag effects observed in terrestrial ecosystems (Wen et al., 2019).

The models predicted lower contributions of canopy physiology on IAV in GPP than observations (Figure 8). Many studies based on observations highlighted the large contributions of physiological changes to IAV in GPP (Messori et al., 2019; Migliavacca et al., 2017; Musavi et al., 2016). Changes in annual GPP because of variations in canopy physiology have been widely reported (Desai, 2010; Zscheischler et al., 2016). A recent study showed a worldwide impact of atmospheric water demand on IAV in GPP by affecting plant stomatal conductance (He et al., 2021). In addition, biotic factors such as plant composition and stand age can also influence IAV in GPP via plant physiology (Polley et al., 2013). For example, Musavi et al. (2017) reported that an increase in stand age and species richness could increase the complementary

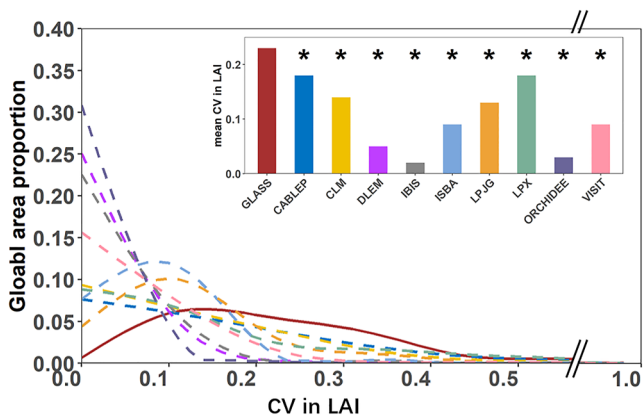


Figure 7. Comparison between the coefficient of variation (CV) of satellite-based leaf area index (LAI) (Global Land Surface Satellite [GLASS]) and simulated LAI by nine terrestrial ecosystem models. Y-axis shows area percentage of the corresponding CV in LAI. The inset shows the mean CV of LAI derived from satellite data set and nine ecosystem models. The asterisks (*) indicate the statistically significant differences ($p < 0.05$) between CV in GLASS-LAI and CV in simulated LAI over global vegetated area.

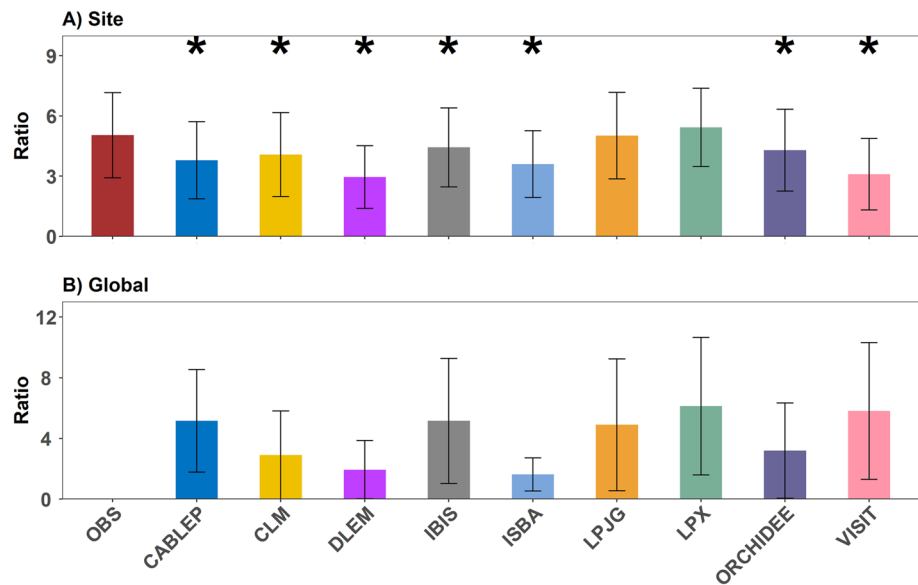


Figure 8. The contribution ratio of physiological and structural changes to interannual variability (IAV) in gross primary production (GPP) averaged at 211 eddy covariance sites (a) and global scale (b). OBS indicates the ratio derived from observations at 211 EC sites. The asterisks (*) indicate statistically significant differences ($p < 0.05$) between model simulation and observation. A higher ratio indicates larger contribution of physiological change to the IAV of GPP. Since there is no globally spatial continuously benchmark of IAV in GPP, the ratio in global observation is absent.

use of nutrients and water, leading to lower IAV in GPP. In summary, our results highlight the importance of reproducing physiological contributions to IAV in GPP (Baldocchi et al., 2018; Keenan et al., 2012).

This study used the coefficient of variance (CV) to indicate IAV in GPP. Standard deviation (SD) and mean value (mean) jointly determine the CV value. This study suggests that the current TEMs underestimate IAV (i.e., lower CV in GPP simulations) (Figure 1), and the lower SD or higher mean of GPP simulations may result in lower CV. Therefore, it is necessary to analyze the dominant cause for underestimating CV. We analyzed the mean magnitude of GPP and LAI for each ecosystem type. Basically, GPP simulations of all TEMs are comparable with the GPP observations (Figure S4 in Supporting Information S1), and over most ecosystem types, the mean values of GPP simulations are lower than observations. This result indicates that a lower SD in the simulation is the main cause for underestimating the CV of GPP, and not the overestimated mean values of GPP.

4.2. Implications of Underestimated GPP Interannual Variability by TEMs

This study highlighted the underestimation of IAV in GPP by the state-of-the-art TEMs, which may result in underestimated IAV in NEP (Yuan et al., 2009). However, recent research showed that the TEMs have good performance of reproducing IAV in NEP at continental scale (Ciais et al., 2019; Piao et al., 2020). NEP is differences between GPP and ecosystem respiration (ER). Therefore, model parameterization is mostly going to improve the model performance for NEP but not GPP or ER, and which is the most important variable because it directly indicates the ecosystem carbon budget. Previous studies have shown that the NEP simulations of various TEMs are quite close, but there are large differences for GPP or ER (Jian et al., 2022; Lu et al., 2021), which implies that the uncertainties in GPP and ER simulations may result in a good performance of NEP. Our study found an underestimation of IAV in GPP by most investigated TEMs, implying that these ecosystem models may have large uncertainty in reproducing IAV in ER. Therefore, it is urgently necessary to investigate the model performance of the IAV in GPP, ER, and NEP.

Our results also showed the larger underestimations of IAV in GPP at nonforest ecosystem types than forest types, especially in arid and semiarid grassland and shrubland (Figures 2 and 3, Figure S1 in Supporting Information S1). A previous study reported that IAV in global carbon sink was driven by gross vegetation production of semiarid lands in the Southern Hemisphere (Poulter et al., 2014). For example, about 80% of the global gross vegetation production anomaly in 2011, an exceptional year with a large land carbon sink, can be explained by only three

main semiarid regions: Australia, temperate South America and southern Africa (Poulter et al., 2014). For arid ecosystems, the water stress is the most important factor for determining the IAV of vegetation growth (Hu et al., 2022). For example, H. J. Xu et al. (2019) reported that summer precipitation primarily controlled the IAV in desert GPP. Therefore, it is important to improve the model performance for reproducing the impacts of water stress on gross vegetation production. On the one hand, the current models need to accurately incorporate the impacts of water stress on vegetation growth processes (Franks et al., 2018). It is also another challenge to represent the diverse responses of vegetation growth to water stress (Grossiord et al., 2020).

4.3. Improvement of TEMs for Simulating Interannual Variability of GPP

There are plenty of methods that may help reproducing IAV in GPP. The most important way is to improve the algorithms for representing environmental regulations of GPP, especially for these environmental variables which highly dominate vegetation growth over large and global scales. Several recent studies highlighted that atmospheric water demand is an important environmental variable for determining global gross vegetation production (He et al., 2021; Lu et al., 2022). For example, from 1982 to 2015, about 70% of the global vegetated area showed a negative correlation of IAV between vegetation growth and atmospheric vapor pressure deficit (VPD) (He et al., 2021). Our study includes nine state-of-the-art TEMs, most of which use physiological-based model to simulate photosynthesis (Farquhar et al., 1980; Haverd et al., 2017; Ito, 2003; Raczka et al., 2021), and two of them (i.e., IBIS, ISBA) use a semi-empirical model (De Pue et al., 2022; Yuan et al., 2014). Although these two types of models incorporate the impacts of VPD on photosynthesis, a recent study showed that these TEMs failed to reproduce the impacts of VPD on gross vegetation production (Yuan et al., 2019). Numerous studies suggested that stomatal conductance declines under high VPD until a given VPD threshold, leading to a cascade of subsequent impacts including photosynthesis reduction, higher risks of carbon starvation and hydraulic failure (Bunce, 2006; Franks et al., 1997). However, there is no consensus on which robust mechanisms drives stomatal closure in response to rising VPD as these mechanisms are varying among environmental gradients and plant functional types (Grossiord et al., 2020). Therefore, the TEMs should better quantify the impact of VPD on stomatal conductance (Franks et al., 2018).

In addition, model-data comparison can play an important role in improving model performance, which may transfer our understandings of the differential changes in photosynthesis response to climate change to improving model predictive skills (Y. Q. Luo et al., 2012). Specifically, to improve models' ability to simulate IAV in GPP, it is urgent to understand the process mechanisms by means of substantial field or laboratory control experiments, underlying the responses of IAV in GPP to environmental changes and comparing the model algorithms with these process-based understandings to improve them accordingly (S. Li et al., 2019; Lu et al., 2021). In addition, there is a need to conduct a data assimilation to further minimize model errors and model-data mismatches. In general, the integration of models, observations, experiments, and process understandings should help improve models' reproduction of IAV in GPP at various scales.

5. Conclusion

In this study, we compared IAV in GPP from the flux tower observations to that from TEM simulations. We found that all the TEMs substantially underestimate the IAV in simulated GPP in comparison to observations, especially in nonforest sites such as grassland and shrubland. There are two main reasons for the underestimation of IAV in GPP from TEMs. On one hand, IAV in canopy structure (i.e., LAI) strongly drives the IAV in GPP from TEMs. However, IAV in model-simulated LAI are much less than them from observations. On the other hand, the TEMs underestimate the changes of canopy physiology response to climate change, resulting in an underestimation of IAV in GPP. Our results suggest that the future versions of TEM to precisely characterize the contribution of canopy physiological changes on the IAV in GPP and clarify the reason for the underestimated variability in LAI. With these efforts, it may be possible to accurately predict the IAV in GPP and the stability of the global carbon sink in the context of global climate change.

Data Availability Statement

The TRENDY v10 ensemble can be accessed with requests from the data hub of the Global Carbon Budget (<https://globalcarbonbudgetdata.org/index.html>). The GPP data from flux sites are available with requests from FLUXNET2015 data set (<https://fluxnet.org/data/fluxnet2015-dataset/>), Integrated Carbon Observation System

(ICOS, <https://www.icos-cp.eu/data-products/2G60-ZHAK>), AmeriFlux (<https://ameriflux.lbl.gov/sites/site-search/>), OzFlux (<https://data.ozflux.org.au/portal/home.jsp>), AsiaFlux (<https://db.cger.nies.go.jp/asiafluxdb/>), and ChinaFLUX (<http://www.nesdc.org.cn/theme/index?projectId=612458897e28172cbed3d77a>). Some of the data links can be found at the Table S1 in Supporting Information S1. The meteorology data are available at the Climatic Research Unit Japanese Reanalysis (CRU-JRA, <http://catalogue.ceda.ac.uk/uuid/863a47a6d-8414b6982e1396c69a9efe8>). The GLASS-LAI product is available from the website of GLASS product (<http://www.glass.umd.edu/Download.html>).

Acknowledgments

This work was supported by the Guangdong Major Project of Basic and Applied Basic Research (2020B0301030004). Shangrong Lin was funded by the National Natural Science Foundation of China, Grant 42101319, the Fundamental Research Funds for the Central Universities, and Sun Yat-sen University (2021qntd29). This work used eddy covariance data acquired and shared by the FLUXNET community, including these networks: AmeriFlux, AfriFlux, AsiaFlux, CarboAfrica, CarboEuropeIP, CarboItaly, CarboMont, ChinaFlux, Fluxnet-Canada, GreenGrass, ICOS, KoFlux, LBA, NECC, OzFlux-TERN, TCOS-Siberia, and USCCC. The FLUXNET eddy covariance data processing and harmonization was carried out by the European Fluxes Database Cluster, AmeriFlux Management Project, and Fluxdata project of FLUXNET, with the support of CDIAC and ICOS Ecosystem Thematic Center, and the OzFlux, ChinaFlux and AsiaFlux offices. We also thank the PIs from global carbon budget project for providing the TRENDY v10 data.

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