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# Maximal operators on hyperbolic triangles 

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#### Abstract

We characterize the boundedness properties on the spaces $L^{p}\left(\mathbb{H}^{2}\right)$ of the maximal operator $M_{\mathcal{B}}$ where $\mathcal{B}$ is an arbitrary family of hyperbolic triangles stable by isometries.


## 1 Introduction

The theory of maximal operators have a long history in analysis and those objects are still intensively studied today: in a measured metric space $(X, \mu, d)$, it is common to consider the centered Hardy-Littlewood maximal operator $M^{c}$ defined as

$$
M^{c} f(x):=\sup _{r>0} \frac{1}{\mu(B(x, r))} \int_{B(x, r)}|f|
$$

or its non non-centered version $M$ defined as

$$
M f(x):=\sup _{x \in B \in \mathcal{Q}} \frac{1}{\mu(B)} \int_{B}|f|
$$

Here, we have denoted by $\mathcal{Q}$ the family containing all the balls of the space $X$.
In the Euclidean space $\mathbb{R}^{n}$ endowed with the Lebesgue measure, the operator $M$ and $M^{c}$ are pointwise comparable (i.e. for any function $f$ and $x \in \mathbb{R}^{n}$, we have $\left.M^{c} f(x) \simeq_{n} M f(x)\right)$ and both operators have weak-type $(1,1)$.

Theorem 1 (Maximal Theorem in $\mathbb{R}^{n}$ ). For any $f$ and $t>0$, one has the following estimate

$$
|\{M f>t\}|_{n} \lesssim n \int_{\mathbb{R}^{n}} \frac{|f|}{t}
$$

It is well known that the proof of Theorem 1 relies on the classic Vitali's covering Theorem. Also by interpolation arguments with $p=\infty$, we immediately obtain that the operators $M$ and $M^{c}$ are bounded from $L^{p}$ to $L^{p}$ for any $p>1$. Such an estimate coupled with classic arguments of measure theory yield the following Theorem of differentiation.

Theorem 2 (Lebesgue's Theorem of differentiation). For any locally integrable function $f$, we have almost everywhere the following identity

$$
f(x)=\lim _{r \rightarrow 0} A_{r} f(x)
$$

Here, $A_{r} f(x)$ stands for the average of $f$ on a ball (or a cube) centered at the point $x$ or radius $r$.

If the centered or non centered version maximal operator behave in the same fashion in the Euclidean space the story is quite different on non-compact symmetric spaces. Precisely, let $\mathbb{G}$ be a non-compact connected semisimple Lie group with finite center, $\mathbb{K}$ a maximal compact subgroup and consider the noncompact symmetric space

$$
\mathbb{X}=\mathbb{G} / \mathbb{K}
$$

equipped with its natural $\mathbb{G}$-invariant measure $\mu$ and distance $d$. The case of the centered Hardy-Littlewood operator $M^{c}$ in this setting has been studied in [8] by Stromberg.

Theorem 3 (Stromberg). On $(\mathbb{X}, \mu, d)$, the centered Hardy-Littlewood operator $M^{c}$ has weak-type $(1,1)$.

In contrast with the Euclidean space, one cannot use covering argument on non-compact symmetric space since the growth of the volume of the balls are exponential. To deal with this difficulty, Stromberg uses a local-global strategy to decompose the operator $M^{c}$ and to detail its optimal boundedness property. On the other hand, the non-centered operator $M$ has been studied by Ionescu in [6].

Theorem 4 (Ionescu). On $(\mathbb{K}, \mu, d)$, the non-centered Hardy-Littlewood operator $M$ is bounded from $L^{p}$ to $L^{p}$ in the sharp range of exponents $p \in(2, \infty]$.

The proof of Ionescu relies on the relation between the boundedness property of maximal operator and the covering property of the geometric family that defines it. Precisely, in a measured metric space ( $X, \mu, d$ ), given an arbitrary family $\mathcal{B}$ of measurable sets of finite measure (the geometric data) one can define the maximal operator $M_{\mathcal{B}}$ associated as

$$
M_{\mathcal{B}} f(x):=\sup _{x \in R \in \mathcal{B}} \frac{1}{\mu(R)} \int_{R}|f| .
$$

Here, we have implicitly supposed that we have

$$
X=\bigcup_{R \in \mathcal{B}} R
$$

In [4], Cordoba and Fefferman say that such a family $\mathcal{B}$ satisfies the covering property $V_{q}$ for $q \in(1, \infty)$ if given any finite family $\left\{R_{i}: i \in I\right\}$ included in $\mathcal{B}$, there exists a subfamily $J \subset I$ such that we have

$$
\mu\left(\bigcup_{i \in I} R_{i}\right) \lesssim \mu\left(\bigcup_{j \in J} R_{j}\right)
$$

and also

$$
\left\|\sum_{j \in J} \mathbb{1}_{R_{j}}\right\|_{L^{p}(\mu)} \lesssim \mu\left(\bigcup_{j \in J} R_{j}\right)^{\frac{1}{q}}
$$

They proved then the following.
Theorem 5 (Cordoba and R. Fefferman). The family $\mathcal{B}$ satisfies the covering property $V_{q}$ if and only if the associated maximal operator $M_{\mathcal{B}}$ has weak-type $(p, p)$ i.e. if for any $f$ and $t>0$, one has

$$
\mu\left(\left\{M_{\mathcal{B}} f>t\right\}\right)^{\frac{1}{p}} \lesssim \frac{\|f\|_{L^{p}(\mu)}}{t} .
$$

Here we have supposed that $\frac{1}{p}+\frac{1}{q}=1$.
Hence, in regards of Theorems 3 and 4, one can see that the geometry deeply influence the behavior of $M^{c}$ or $M$. Let us consider a slightly different problematic: in a fixed measured metric space $(X, \mu, d)$ and with this general definition of a maximal operator $M_{\mathcal{B}}$, one can wonder what happens when the family $\mathcal{B}$ is composed of more complex geometric objects than balls? With appropriate geometric restrictions on the family $\mathcal{B}$, this problematic can unravel deep phenomena of the underlying space $X$ and the interaction of the elements of the family $\mathcal{B}$.

Let us give an example in the Euclidean plane $\mathbb{R}^{2}$ : given an arbitrary set of directions $\Omega \subset \mathbb{S}^{1}$, consider the directional family $\mathcal{R}_{\Omega}$ composed of every rectangles whose longest side makes an angle $\omega \in \Omega$ with the $O x$-axis and denote by $M_{\Omega}$ the maximal operator associated to this family. Those directional maximal operators have been intensively studied in the past decades (see for examples [1], [3] and [7]) and it was only after a long serie of different works that Bateman classified in [2] the behavior of directional maximal operators on the $L^{p}$ spaces for $1<p<\infty$. We give some examples before stating Bateman's Theorem:

- if the set of directions $\Omega$ is finite, then the maximal operator $M_{\Omega}$ is bounded on $L^{p}$ for any $p>1$.
- if we consider the set of directions $\Omega_{\mathrm{lac}}=\left\{\frac{\pi}{2^{k}}: k \geq 1\right\}$, then the maximal operator $M_{\Omega_{\text {lac }}}$ is bounded on $L^{p}$ for any $p>1$, see [7]. The proof relies on Fourier analysis techniques
- if we consider the set of directions $\Omega_{\operatorname{lin}}=\left\{\frac{\pi}{k}: k \geq 1\right\}$, then the maximal operator $M_{\Omega_{\text {lin }}}$ is not bounded on $L^{p}$ for any $p<\infty$. The proof relies on the construction of a so-called Perron's tree which is a concrete realization of a Kakeya blow in the plane.
- if we consider a classic ternary Cantor set $\Omega_{\text {Cantor }}$ embedded into $\mathbb{S}^{1}$, then the maximal operator $M_{\Omega_{\text {Cantor }}}$ is not bounded on $L^{p}$ for any $p<\infty$, see [3]. As for $\Omega_{\text {lin }}$, the proof relies on the realization of a Kakeya blow in the plane but via a sophisticated random construction.

Here, we have used the term Kakeya blow to designate the following geometric obstruction of the Euclidean space (we denote by $\mathcal{R}$ the family containing every plane rectangle in $\mathbb{R}^{2}$ ).

Theorem 6 (Kakeya blow with $\mathcal{R}$ ). Given any large constant $A \gg 1$, there exists a finite family of rectangles

$$
\left\{R_{i}: i \in I\right\} \subset \mathcal{R}
$$

such that we have

$$
\left|\bigcup_{i \in I} T R_{i}\right| \geq A\left|\bigcup_{i \in I} R_{i}\right|
$$

Here, we have denoted by $T R$ the rectangle $R$ translated along its longest side by its own length

This Theorem has several applications in analysis and is related to the traditional Kakeya problem. For example, C. Fefferman used a more refined version of this property in order to disprove the famous Ball multiplier Theorem: see [5] which also contains a proof of Theorem 6 . For an arbitrary set of directions $\Omega \subset \mathbb{S}^{1}$, let us state Bateman's Theorem which indicates that the correct notion to consider is finiteness lacunarity. We invite the reader to look at Bateman's paper [2] for a precise definition of this notion.

Theorem 7 (Bateman). We have the following alternative:

- if the set of directions $\Omega$ is finitely lacunary then $M_{\Omega}$ is bounded on $L^{p}$ for any $p>1$.
- if the set of directions $\Omega$ is not finitely lacunary then it is possible to make a Kakeya blow with the family $\mathcal{R}_{\Omega}$ and in particular, $M_{\Omega}$ is not bounded on $L^{p}$ for any $p<\infty$.

In this text, we investigate this problematic in the hyperbolic plane $\mathbb{H}^{2}$ endowed with its natural measure $\mu$ and where $\mathcal{B}$ is a family included in $\mathcal{T}$ - the family containing all the geodesic triangles of $\mathbb{H}^{2}$ - and where in addition $\mathcal{B}$ is stable by isometries of $\mathbb{H}^{2}$. Since we are able to completely determine the behavior of the operator $M_{\mathcal{B}}$, it seems interesting to study less regular geometric families and the following example seems pertinent. We fix a point $\omega \in \partial \Vdash^{2}$ and we consider the family of curves $\mathcal{G}_{\omega}$ which contains every geodesics that goes to $\omega$ at infinite and also the family $\mathcal{H}_{\omega}$ which contains every horocycles tangent to $\omega$ : given two geodesics $d \neq d^{\prime} \in \mathcal{G}_{\omega}$ and two horocycles $h \neq h^{\prime} \in \mathcal{H}_{\omega}$, we consider the open bounded set $P\left(d, d^{\prime}, h, h^{\prime}\right)$ whose border is delimited by the four curves $d, d^{\prime}, h$ and $h^{\prime}$ and then we define the family

$$
\mathcal{P}_{\omega}=\left\{P\left(d, d^{\prime}, h, h^{\prime}\right): d \neq d^{\prime} \in \mathcal{G}_{\omega}, h \neq h^{\prime} \in \mathcal{H}_{\omega}\right\}
$$

What can be said about the maximal operator

$$
M_{\mathcal{P}_{\omega}}: L^{\infty} \rightarrow L^{\infty}
$$

associated to the family $\mathcal{P}_{\omega}$ ? Can we expect boundedness property analogue to the strong maximal operator ? Thereafter, given an arbitrary family $\Omega \subset \partial H^{2}$, one can consider the family

$$
\mathcal{P}_{\Omega}=\bigcup_{\omega \in \Omega} \mathcal{P}_{\omega}
$$

What can be said about the operator $M_{\mathcal{P}_{\Omega}}$ associated to this family? Does its behavior depend on $\Omega$ in the same fashion that in the Euclidean case? We will return to those questions later.

## 2 Results

As said earlier, we are interested by families composed of geodesic triangles which are invariant under the action of isometries. In the following, we denote by by $G$ the group of isometries of $\mathbb{H}^{2}$ and by $\mathcal{T}$ the family containing all geodesic triangles in $\mathbb{H}^{2}$. A family $\mathcal{B}$ included in $\mathcal{T}$ and invariant by $G$ is parameterized by the angles exhibited by the triangles it contains: if we denote by $\boldsymbol{\alpha}_{T}$ the set of angles of the triangle $T$ and that we let $A_{\mathcal{B}}:=\left\{\boldsymbol{\alpha}_{T}: T \in \mathcal{B}\right\}$ then, because $\mathcal{B}$ is invariant under $G$, we precisely have

$$
\mathcal{B}=\left\{T \in \mathcal{T}: \boldsymbol{\alpha}_{T} \in A_{\mathcal{B}}\right\}
$$

We consider the simplex $S$ of admissible angles which is defined as

$$
S:=\left\{\boldsymbol{\alpha} \in\left(\mathbb{R}_{+}\right)^{3}: s(\boldsymbol{\alpha}) \leq \pi\right\}
$$

where $s(\boldsymbol{\alpha}):=\alpha_{1}+\alpha_{2}+\alpha_{3}$. We are going to decompose the simplex $S$ in three disjoint parts $S_{1}, S_{2}$ and $S_{3}$ according to the eccentricity function $p$ defined as

$$
p(\boldsymbol{\alpha}):=\alpha_{1} \alpha_{2} \alpha_{3}
$$

Precisely we define:

- $S_{0}:=\{\boldsymbol{\alpha} \in S: s(\boldsymbol{\alpha})<\pi, p(\boldsymbol{\alpha})>0\}$
- $S_{1}:=\{\boldsymbol{\alpha} \in S: s(\boldsymbol{\alpha})=\pi, p(\boldsymbol{\alpha})>0\}$,
- $S_{2}:=\{\boldsymbol{\alpha} \in S: s(\boldsymbol{\alpha})<\pi, p(\boldsymbol{\alpha})=0\}$,
- and $S_{3}:=\{\boldsymbol{\alpha} \in S: s(\boldsymbol{\alpha})=\pi, p(\boldsymbol{\alpha})=0\}$

The functions $s$ and $p$ have simple geometric interpretations: on one hand for any triangle $T$, one has

$$
\mu(T)=\pi-s\left(\boldsymbol{\alpha}_{T}\right)
$$

and on the other hand, $p\left(\boldsymbol{\alpha}_{T}\right)$ represents the eccentricity of the triangle $T$, its thickness. We can now state our main result.

Theorem 8. Let $\mathcal{B}$ be a family of hyperbolic triangles stable by isometries and recall its set of angle is defined as $A:=\left\{\boldsymbol{\alpha}_{T}: T \in \mathcal{B}\right\}$. We have the following alternatives:

- (I) if $\bar{A} \subset S_{0}$, then the operator $M_{\mathcal{B}}$ is bounded from $L^{1}$ to $L^{1}$ i.e. there exists a constant $C_{\mathcal{B}}<\infty$ such that for any function $f$ we have

$$
\left\|M_{\mathcal{B}} f\right\| \leq C_{\mathcal{B}}\|f\|_{L^{1}(\mu)}
$$

- (II) if $\bar{A} \subset S_{1}$ and $\bar{A} \cap S_{1} \neq \emptyset$, then the operator $M_{\mathcal{B}}$ has weak-type $(1,1)$ i.e. there exists a constant $C_{\mathcal{B}}<\infty$ such that for any function $f$ and $t>0$, the following estimate holds

$$
\mu\left(\left\{M_{\mathcal{B}} f>t\right\}\right) \leq C_{\mathcal{B}} \frac{\|f\|_{L^{1}(\mu)}}{t}
$$

- (III) if $\bar{A} \cap S_{2} \neq \emptyset$, then for any non zero function $f$, there exists a positive constant $c>0$ depending on $f$ and $\mathcal{B}$ such that for any $y \in \mathbb{H}^{2}$, one has

$$
M_{\mathcal{B}} f(y)>c
$$

- (IV) if $\bar{A} \cap S_{3} \neq \emptyset$, then for any large constant $C \gg 1$, there exists a bounded set $E$ in $\uplus^{2}$ satistying

$$
\mu\left(\left\{M_{\mathcal{B}} \mathbb{1}_{E} \geq \frac{1}{4}\right\}\right) \geq C \mu(E)
$$

The proof of Theorem 8 will be done in different parts and relies on different ideas: in contrast with the work of Stromberg [8], we exclusively use geometric techniques. To begin with, if $\bar{A} \subset S_{0}$, then the operator $M_{\mathcal{B}}$ is controlled by

$$
T: f(x) \rightarrow \frac{1}{B(x, r)} \int_{B(x, r)}|f|
$$

where the radius $r$ is independent of $x$. Such an operator $T$ is bounded from $L^{1}$ to $L^{1}$ and since $M_{\mathcal{B}} \leq T$, the conclusion comes easily. If $\bar{A} \subset S_{1}$ and $\bar{A} \cap S_{1} \neq \emptyset$, this means that the triangles in the family $\mathcal{B}$ cannot become arbitrarily thin. Hence, one can compare each of them to ball whose radius is uniformly bounded and this will allow us to prove the desired weak-type estimate thanks to a covering argument à la Vitali.

In the case where $\bar{A} \cap S_{2} \neq \emptyset$, the family $\mathcal{B}$ contains triangles that tend to become partly ideal. We prove that given any pair of point $\left(x_{0}, y\right)$ one can always catch the point $y$ and a small ball centered at $x_{0}$ with partly ideal triangles and this will allow us to prove that the maximal function $M_{\mathcal{B}} f$ of any non zero function is uniformly bounded by below. This effect is specific to the hyperbolic plane $\mathbb{H}^{2}$ and cannot be observed in the Euclidean space with classic convex sets.

Finally, if $\bar{A} \cap S_{3} \neq \emptyset$ then the family $\mathcal{B}$ contains arbitrarily thin triangles that tend to become Euclidean. We will be able to construct the desired set $E$ by considering local families of triangles: we will prove that their images by the exponential map contain enough Euclidean triangles in an arbitrary tangent space $T_{x_{0}} H^{2}$ which will allow us to exploit a Kakeya-type set of the Euclidean plane.

## 3 Thick triangles (I)

We suppose that we have $\bar{A} \subset S_{0}$. For any $x \in \mathbb{H}^{2}$, consider the family $\mathcal{B}(x)$ defined as

$$
\mathcal{B}(x):=\{T \in \mathcal{B}: x \in T\} .
$$

In other words, $\mathcal{B}(x)$ is composed of every triangles $T$ in $\mathcal{B}$ which contains the point $x$. We claim the following.

Claim 1. If $\bar{A} \subset S_{0}$ then there exists $r=r(\mathcal{B})>0$ such that for any $T \in \mathcal{B}(x)$, one has $T \subset B(x, r)$ and also $\mu(T) \simeq_{\mathcal{B}} \mu(B(x, r))$.

With this proposition at hands, the conclusion comes easily: for any $f$, we have

$$
\int_{\mathbb{H}^{2}} M_{\mathcal{B}} f(x) d \mu(x) \lesssim \mathcal{B} \int_{\mathbb{H}^{2} \times H^{2}}|f|(y) \mathbb{1}_{d(x, y) \leq r} d \mu(y) d \mu(x) .
$$

Indeed for any $x \in \mathbb{H}^{2}$, there exists $T \in \mathcal{B}(x)$ such that

$$
M_{\mathcal{B}} f(x) \leq \frac{2}{\mu(T)} \int_{T}|f| \lesssim \mathcal{B}^{\int_{B(x, r)}|f|}
$$

since we have $T \subset B(x, r)$ and that both sets have comparable volume. Using Fubini we obtain as expected

$$
\int_{\mathbb{H}^{2}} M_{\mathcal{B}} f(x) d \mu(x) \lesssim \mathcal{B}\|f\|_{L^{1}(\mu)} .
$$

## 4 Thick triangles (II)

We suppose that the family $\mathcal{B}$ satisfies $\bar{A} \subset S_{1}$ and $\bar{A} \cap S_{1} \neq \emptyset$. This condition means that the eccentricity of a triangle in $\mathcal{B}$ is uniformly bounded by below but we do not have control on its volume now. The following Claim holds.
Claim 2. For any triangle $T \in \mathcal{B}$, there exists a ball $B(T)$ containing $T$ and satisfying

$$
\mu(B(T)) \simeq_{\mathcal{B}} \mu(T)
$$

In particular, there exists a constant $R<\infty$ only depending on $\mathcal{B}$ such that

$$
\sup _{T \in \mathcal{B}} \operatorname{diam}(B(T))<R
$$

We recall now the Vitali covering Theorem which is valid in metric space.

Theorem 9 (Vitali covering Theorem). Given any family $\mathcal{F}$ of balls whose radius is uniformly bounded by a constant $R<\infty$, there exists a sub-family $\mathcal{F}^{\prime} \subset \mathcal{F}$ satisfying the following properties: on one hand the balls of $\mathcal{F}^{\prime}$ are pairwise disjoint and on the other hand, one has

$$
\bigcup_{B \in \mathcal{F}} B \subset \bigcup_{B^{\prime} \in \mathcal{F}^{\prime}} 5 B^{\prime}
$$

Here $5 B$ stands for the ball $B(x, 5 r)$ if $B=B(x, r)$.
With Claim 2 and Theorem 9 at hands, we can prove that $M_{\mathcal{B}}$ has weaktype $(1,1)$. We fix $f$ a function on $\mathbb{H}^{2}$ and $t>0$ : by definition the level set $\left\{M_{\mathcal{B}} f>t\right\}$ is the union of the triangles $T$ belonging to $\mathcal{B}$ satisfying

$$
\int_{T}|f|>\mu(T) t
$$

We denote by $\mathcal{F}$ this family of triangles and we apply Claim 2 for each $T$ in $\mathcal{F}$ and then we apply Theorem 9 to each balls $B(T)$. This gives us a subfamily $\mathcal{F}^{\prime}$ of $\mathcal{F}$ satisfying the following inclusion

$$
\left\{M_{\mathcal{B}} f>t\right\} \subset \bigcup_{T^{\prime} \in \mathcal{F}^{\prime}} 5 B\left(T^{\prime}\right)
$$

and moreover, the balls $B\left(T^{\prime}\right)$ for $T^{\prime} \in \mathcal{F}^{\prime}$ are pairwise disjoint. Since all the balls considered have a radius uniformly bounded, we have

$$
\mu\left(5 B\left(T^{\prime}\right)\right) \simeq_{\mathcal{B}} \mu\left(B\left(T^{\prime}\right)\right)
$$

and so the following estimate holds

$$
\mu\left(\bigcup_{T^{\prime} \in \mathcal{F}^{\prime}} 5 B\left(T^{\prime}\right)\right) \leq \sum_{T^{\prime} \in \mathcal{F}^{\prime}} \mu\left(5 B\left(T^{\prime}\right)\right) \lesssim \mathcal{B} \sum_{T^{\prime} \in \mathcal{F}^{\prime}} \mu\left(B\left(T^{\prime}\right)\right)
$$

Now we also have $\mu\left(B\left(T^{\prime}\right)\right) \simeq_{\mathcal{B}} \mu\left(T^{\prime}\right)$ and so we obtain

$$
\sum_{T^{\prime} \in \mathcal{F}^{\prime}} \mu\left(B\left(T^{\prime}\right)\right) \lesssim_{\mathcal{B}} \sum_{T^{\prime} \in \mathcal{F}^{\prime}} \frac{1}{t} \int_{B\left(T^{\prime}\right)}|f| .
$$

Since the balls $B^{\prime}$ are pairwise disjoint we obtain as expected

$$
\mu\left(\left\{M_{\mathcal{B}} f>t\right\}\right) \lesssim_{\mathcal{B}} \frac{1}{t} \int|f| .
$$

## 5 Partly ideal triangles

We suppose now that the family $\mathcal{B}$ satisfies $\bar{A} \cap S_{2} \neq \emptyset$. We fix an element $\boldsymbol{\alpha} \in \bar{A} \cap S_{2}$ and without loss of generality we suppose that it is of the form $\boldsymbol{\alpha}=\left(0, \alpha_{2}, \alpha_{3}\right)$. We prove the following Proposition.


Figure 1: An illustration of the proof of Theorem 1.


Figure 2: The existence of the sequence $\left\{T_{k}: k \geq 1\right\}$ comes from the fact that $\alpha$ belongs to $\bar{A}$.

Proposition 1. For any $x_{0} \in \mathbb{H}^{2}$, there exists $r>0$ such that for any $y \in \mathbb{H}^{2}$, there is a triangle $T$ satisfying $\boldsymbol{\alpha}_{T}=\left(0, \alpha_{2}, \alpha_{3}\right), y \in T$ and $B\left(x_{0}, r\right) \subset T$.

Proof. Let $x_{0} \in \mathbb{H}^{2}$ and consider a triangle $T_{0}$ of angles $\left(0, \alpha_{2}, \alpha_{3}\right)$. As the action of $G$ on $\mathbb{H}^{2}$ is transitive, we may assume that $T_{0}$ contains $x_{0}$ in its interior: fix then $r>0$ such that $T_{0}$ contains the ball $B\left(x_{0}, r\right)$.

Given any point $y \in \mathbb{H}^{2}$, its orbit under the stabilizer of $x_{0}$ is exactly the circle $C\left(x_{0}, d\left(x_{0}, y\right)\right)$. As $T_{0}$ has at least one angle equal to 0 by hypothesis, it
is noncompact and intersect nontrivially $C\left(x_{0}, d\left(x_{0}, y\right)\right)$. Hence there is $g \in G$ such that $g\left(x_{0}\right)=x_{0}$ and $g(y) \in T_{0}$ i.e. $y \in T:=g^{-1} T_{0}$ and we have

$$
B\left(x_{0}, r\right) \subset T
$$

Proposition 1 yields the conclusion as follow. Consider a non zero function $f$ on $\mathbb{H}^{2}$ : there exists a ball $B\left(x_{0}, r\right)$ such that $\int_{B\left(x_{0}, r\right)}|f|>0$ and by a standard compactness argument, we can choose $r$ to be arbitrarily small. We fix any point $y$ in $\mathbb{H}^{2}$ and we apply Theorem 1 which gives us a triangle $T$ satisfying $\boldsymbol{\alpha}_{T}=\left(0, \alpha_{2}, \alpha_{3}\right), y \in T$ and $B\left(x_{0}, r\right) \subset T$. To conclude, it suffices to observe that since $\boldsymbol{\alpha} \in \bar{A} \cap S_{2}$, there exists a sequence of triangles $\left\{T_{k}: k \geq 1\right\} \subset \mathcal{B}$ such that each of them contain $y$ and satistying

$$
\int_{T_{k}}|f| \rightarrow \int_{T}|f| .
$$

In particular we have

$$
M_{\mathcal{B}} f(y) \geq \frac{1}{\mu(T)} \int_{T}|f| \geq \frac{1}{\pi} \int_{B\left(x_{0}, r\right)}|f|
$$

This yields the desired conclusion since the integral $\int_{B\left(x_{0}, r\right)}|f|$ is independant of the point $y$ (it only depends on $f$ and $\mathcal{B}$ ).

## 6 Thin and small triangles

We suppose now that the family $\mathcal{B}$ satisfies $\bar{A} \cap S_{3} \neq \emptyset$. We are going to prove that for any constant $C \gg 1$, there exists a bounded set $E$ in $\Vdash^{2}$ satisfying

$$
\mu\left(\left\{M_{\mathcal{B}} \mathbb{1}_{E} \geq \frac{1}{4}\right\}\right) \geq C \mu(E)
$$

In particular, this property implies that the operator $M_{\mathcal{B}}$ is not bounded on the space $L^{p}\left(\mathbb{H}^{2}\right)$ for any $p<\infty$. To construct the set $E$, the idea is to make a Kakeya blow with the triangles of the family $\mathcal{B}$ : this is possible precisely because the family $\mathcal{B}$ contains triangles which are arbitrarily thin and almost Euclidean. To make this argument rigorous, we need to work in a tangent space $T_{x_{0}} \Vdash^{2}$ and to precisely describe the image of small triangles in a neighborhood of $x_{0}$ by the exponential map.

We introduce the following notation: given two triangles $T$ and $T^{\prime}$ (Euclidean or hyperbolic), we note

$$
T \sim T^{\prime}
$$

if there is an isometry $g$ such that $T=g\left(T^{\prime}\right)$. In the following, we fix any point $x_{0} \in H^{2}$ and let $\exp _{x_{0}}$ be the exponential map between $H^{2}$ and $T_{x_{0}} \Vdash^{2}$. We also
suppose that we work in a neighborhood $B\left(x_{0}, r\right)$ of $x_{0}$ so small that we have the following estimate for any open set $U \subset B\left(x_{0}, r\right)$ and with $h=\frac{1}{1000}$

$$
(1-h)\left|\exp _{x_{0}}(U)\right| \leq \mu(U) \leq(1+h)\left|\exp _{x_{0}}(U)\right|
$$

We consider local families of triangles: given any $r>0$ and a triangle $T$, we consider the following family of triangles

$$
\mathcal{L}_{r}(T):=\left\{T^{\prime} \in \mathcal{T}: T^{\prime} \sim T, T^{\prime} \subset B\left(x_{0}, r\right)\right\}
$$

Because we want to be able to move our triangle $T$ in the ball $B\left(x_{0}, r\right)$, we assume that we have

$$
\frac{r}{10}>\operatorname{diam}(T)
$$

The following proposition states that in the Euclidean plane, a maximal operator defined on a local family of thin triangles can exploit a Kakeya-type set.


Figure 3: Representation of a local family $\mathcal{L}_{r}(T)$ in the Euclidean plane.

Proposition 2. For any large constant $C \gg 1$, there exists $0<\epsilon \ll 1$ such that if $T_{i}$ is an Euclidean triangle thin enough (i.e. satisfying $p\left(\boldsymbol{\alpha}_{T_{i}}\right)<\epsilon$ ) then any maximal operator $M_{\mathcal{L}_{r}\left(T_{i}\right)}$ defined on a non empty local family

$$
\mathcal{L}_{r}\left(T_{i}\right):=\left\{T^{\prime} \in \mathcal{T}: T^{\prime} \sim T, T^{\prime} \subset B(0, r)\right\}
$$

admits a Kakeya-type set $F$ included in $B\left(x_{0}, r\right)$ satisfying

$$
\left|\left\{M_{\mathcal{L}_{r}\left(T_{i}\right)} \mathbb{1}_{F} \geq \frac{1}{4}\right\}\right| \geq C|F|
$$

Proposition 2 is a well-known fact in the literature and we omit its proof. To conclude the proof of Theorem 8, we need the following proposition which simply states that given a local family generated by a small triangle $T$ in $\mathbb{H}^{2}$, its image under the exponential maps is compatible with a local family generated by a triangle $T_{i}$ which is close to $T$ according to their sets of angles.

Proposition 3. Fix an arbitrary precision $\delta>0$ : there exists $0<r, \epsilon \ll 1$ (which can be taken arbitrarily small) such that for any set of angles $\boldsymbol{\alpha}_{0} \in S$ satisfying $\left|\pi-s\left(\boldsymbol{\alpha}_{0}\right)\right| \leq \epsilon$, there exists a set of Euclidean angles $\boldsymbol{\alpha}_{1}$ satisfying $\left\|\boldsymbol{\alpha}_{0} / \boldsymbol{\alpha}_{1}-1\right\|_{1} \leq \delta$ and such that for any triangle $T$ included in $B\left(x_{0}, r\right)$ and satisfying

$$
\boldsymbol{\alpha}_{T}=\boldsymbol{\alpha}_{0}
$$

there exists an Euclidean triangle $\varphi(T)$ which depends on $T$ satisfying

$$
\begin{array}{r}
\varphi(T) \subset \exp _{x_{0}}(T) \\
|\varphi(T)| \geq \frac{1}{10}|T| \\
\boldsymbol{\alpha}_{\varphi(T)}=\boldsymbol{\alpha}_{1} . \tag{3}
\end{array}
$$

Finally, there exists $0<r^{\prime} \ll 1$ such that the following inclusion holds

$$
\emptyset \neq \mathcal{L}_{r^{\prime}}(\varphi(T)) \subset \varphi\left(\mathcal{L}_{r}(T)\right)
$$

Proof. As it is well known, the differential at 0 of the exponential map is the identity. Hence given $\epsilon>0$, there is $r>0$ sich that the restriction of the exponential map to $B(0, r)$ is $(1+\epsilon)$ bilipschitz and quasiconformal. In particular, $\exp _{x_{0}}$ will be uniformly close to an isometry, so the preimage of a hyperbolic triangle $T$ in $B\left(x_{0}, r\right)$ with angles $\boldsymbol{\alpha}_{0}$ will contain a Euclidean triangle with angles $\boldsymbol{\alpha}_{1}$ satisfying $\left\|\boldsymbol{\alpha}_{1} / \boldsymbol{\alpha}_{0}-1\right\|_{1} \leq \epsilon$. Taking $\epsilon$ small enough will give exactly the claimed properties.


Figure 4: Given a triangle $T$ close to $x_{0}$, we claim that its image $\exp _{x_{0}}(T)$ contains a triangle $\varphi(T)$ which is not too small compared to $T$ and which is also thin enough.


Figure 5: We also claim that the image of the local family $\mathcal{L}_{r}(T)$ under the exponential will contain a local family $\mathcal{L}_{r^{\prime}}(\varphi(T))$ : this second family is now contained in the Euclidean plane and so we can use Propostion 2.

With Propositions 2 and 3 at hands, we can conclude the proof of Theorem 8. Fix a large constant $C \gg 1$ and let $\epsilon \ll 1$ as in Proposition 2. Because we suppose that $\bar{A} \cap S_{3} \neq \emptyset$, we can choose an set of angles $\boldsymbol{\alpha}_{0} \in A$ such that if $\boldsymbol{\alpha}_{1}$ is the set of Euclidean angles as described in Proposition 3, then

$$
p\left(\boldsymbol{\alpha}_{1}\right)<\epsilon
$$

In this situation, the local family $\mathcal{L}_{r^{\prime}}(\varphi(T))$ given by Proposition 3 satisfies the condition of Proposition 2: hence there exists a Kakeya-type set $F$ satisfying

$$
\left|\left\{M_{\mathcal{L}_{r^{\prime}}(\varphi(T))} \mathbb{1}_{F} \geq \frac{1}{4}\right\}\right| \geq C|F|
$$

Define now the set $E$ in $\Vdash^{2}$ as the pre-image of $F$ by the exponential map

$$
E:=\exp _{x_{0}}^{-1}(F)
$$

and let us see why we can exploit the set $E$ with the maximal operator $M_{\mathcal{B}}$. Fix $\varphi\left(T^{\prime}\right)$ in $\mathcal{L}_{r^{\prime}}(\varphi(T))$ such that

$$
\left|\varphi\left(T^{\prime}\right) \cap F\right| \geq \frac{1}{4}\left|\varphi\left(T^{\prime}\right)\right|
$$

and observe that in $\mathbb{H}^{2}$ we have

$$
\mu\left(T^{\prime} \cap E\right) \simeq\left|\exp _{x_{0}}\left(T^{\prime} \cap E\right)\right| \geq\left|\varphi\left(T^{\prime}\right) \cap F\right| \geq \frac{1}{4}\left|\varphi\left(T^{\prime}\right)\right| \simeq \frac{1}{40} \mu\left(T^{\prime}\right)
$$

Finally, the following estimate follows by inclusion

$$
\mu\left(\left\{M_{\mathcal{B}} \mathbb{1}_{E} \geq \frac{1}{40}\right\}\right) \geq \mu\left(\bigcup_{T^{\prime}} T^{\prime}\right) \simeq\left|\bigcup_{T^{\prime}} \varphi\left(T^{\prime}\right)\right| \geq C|E| \simeq C \mu(F)
$$

This concludes the last part of the proof of Theorem 8

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