

Processing of hyperspectral aerial images to characterize the bathymetry of rivers

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METHODS FOR ECOHYDRAULICS: REMOTE SENSING



International Association for Hydro-Environment Engineering and Research



Poland Young Professionals Network



Processing of hyperspectral aerial images to characterize the bathymetry of rivers

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Context: What is hyperspectral imagery?

- Traditional colour images :
 - → A small number of broad spectral bands
 - → Summarize the spectra over a large spectral range to recreate what we can see

- Hyperspectral imaging :
 - \rightarrow A high number of narrow spectral bands
 - \rightarrow Samples the spectra with a precision similar to lab spectroscopy measurements





Context: How does it retrieve river bathymetry?

• Optical model based on Beer-Lambert Law

→ The intensity measured by the sensor (I_{sensor}) is a function of the initial brightness (I_{sun}) , water depth (d) and of the optical properties of the water column (c).

$$I_{sensor} = I_{sun}e^{-cd}$$

 \rightarrow The goal is to identify the band combination that is the less sensitive to changes in c and the best correlated to d. Bathymetric model for the aircraft images at medium flow



Context: The Ain River as a study site

- The Ain River: a meandering gravel-bed river in France
 - \rightarrow Low Flow: 16 m³/s
 - \rightarrow Mean Annual Flow: 120 m³/s
- Accurate bathymetric information is crucial to stakeholders
 - \rightarrow Channel incision is propagating downstream following historical damming in the 20th century
 - \rightarrow Restoration projects such as gravel injection are attempting to mitigate this
 - => Our aim on the Ain River was to assess the accuracy of hyperspectral-based bathymetric models and the portability of local models to large reaches

200 km

Paris

Context: Existing datasets on the Ain River

Hyperspectral data over the same river for different sensors, extents and discharges

Sensor	Vector	Spatial Resolution	Spectral Resolution	Discharge	Date	Secteur
Specim AISA Fenix	Airplane	1 m	360 bands [380 – 2500 nm]	127 m³/s	29/09/15	Ain River (20 km)
Rikola-2	UAV	6 cm	16 bands [500 – 845 nm]	27 m³/s	27/09/15	Local Reach (350 m)
Headwall Hyperspec	UAV	2.5 cm	480 bands [169 – 1200 nm]	100 m³/s	18/11/21	Local Reach (120 m)

A 2D numeric bathymetric model

 \rightarrow Covers the study site with as a grid with 2 – 3 metres resolution (200k+ points)

→ Enables adjusting depths according to a desired discharge

• Field data acquired with a Differential GPS in 2013

 \rightarrow Less coverage, but provides additional validation data (320 points)

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Methodology: correlating spectra to depth

- 1°) Increasing the dimensionality of the data
- 2°) Testing the linear relationship to depth for all bands and band combinations
- 3°) Assessing the accuracy of a given model

> Models are calibrated on short reaches and assessed for the full extent of the data which is higher for the airplane campaign



Application: Mapping over large extents



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Application: Change monitoring

Bathymetric changes between 2015 and 2021 for a short reach of the Ain River

Airplane Campaign (2015) Resolution: 1 m UAV Campaign (2021) Resolution: 2.5 cm Difference (2021-2015) Resolution: 2.5 cm



Limitations: clusters of errors

- Sources of errors :
 - 1. Pool areas (< 5% of the river reach)
 - > Poor accuracy in the data for calibration and validation
 - 2. Glint and turbulence at the water surface
 - 3. Vegetation shadowing
 - 4. Changes in riverbed or water column properties

> Sensitivity is dependent on wavelength combination







Limitations: sensitivity to the calibration data

Reach 1 : site of the initial calibration

Reach 2 : site from the map of errors

R² values for Numerator/Denominator as a predictor of bathymetry





- Hyperspectral remote-sensing is promising for bathymetric retrieval
 - \rightarrow It can provide accurate bathymetric maps for a given discharge
 - → Attempts at large scale mapping and change detection were successful

 \rightarrow Campaigns acquired under mean annual flow conditions (less than ideal conditions for optical models) were successful

• Specific reproducibility issues must be assessed

→ Acquiring data for a wider range of depths, turbidity conditions and lithology to better understand limitations

 \rightarrow How to choose the best model for the river rather than for the calibration data

Thank you for your attention!