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# $L^{\mathbf{2}}$ Hypocoercivity methods for kinetic Fokker-Planck equations with factorised Gibbs states 

Emeric Bouin, Jean Dolbeault, and Luca Ziviani


#### Abstract

This contribution deals with $L^{2}$ hypocoercivity methods for kinetic Fokker-Planck equations with integrable local equilibria and a factorisation property that relates the Fokker-Planck and the transport operators. Rates of convergence in presence of a global equilibrium, or decay rates otherwise, are estimated either by the corresponding rates in the diffusion limit, or by the rates of convergence to local equilibria, under moment conditions. On the basis of the underlying functional inequalities, we establish a classification of decay and convergence rates for large times, which includes for instance sub-exponential local equilibria and subexponential potentials.


MSC (2020): Primary: 82C40. Secondary: 35H10, 35K65, 35Q84, 76P05, 35P15.

Key words: Hypocoercivity, linear kinetic equations, entropy - entropy production inequalities, FokkerPlanck operator, transport operator, diffusion limit, Nash inequality, Caffarelli-Kohn-Nirenberg inequality, Hardy-Poincaré inequality, weighted Poincaré inequality, Poincaré inequality

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## 1 Introduction

Hypocoercivity refers to the method developed by C. Villani in order to capture large time asymptotics in kinetic equations, see [32, 36], which borrows ideas from Hörmander's hypoelliptic theory and from the carré du champ method introduced by D. Bakry and M. Emery in [4]. For this reason, the Fisher information plays an important role and, to some extent, we can consider it as an $\mathrm{H}^{1}$-theory. Here we shall focus more on the notion of $\mathrm{L}^{2}$-hypocoercivity inspired by [26] and introduced in [20,21] in a simple case of a kinetic Fokker-Planck equation, which puts the emphasis on the underlying diffusion limit. The heuristic idea is simple: while the Fokker-Planck diffusion operator controls the rate of convergence towards local equilibria in the velocity space, the equilibration of the spatial density (its convergence to the spatial density of a global equilibrium or its decay when no such equilibrium exists) can be interpreted as a diffusion in the position space, at least in a certain parabolic scaling, which results of the interplay of the diffusion in the velocity direction and the transport and the mixing in the phase space induced by the transport operator. The advantage of this approach is that rates are fully determined by the functional inequalities associated to the diffusion operator on the velocity space and to the diffusion limit in the position space.

[^0]This paper is organized as follows. We start by recalling the abstract $\mathrm{L}^{2}$ hypocoercivity method in Theorem 1 before applying it to the framework of non-Maxwellian local equilibria and a compatible transport operator in Corollary 1. Although an adaptation of the standard theory in presence of microscopic and macroscopic coercivity associated respectively to the Fokker-Planck operator and the diffusion limit, this result is new and covers for instance the case of relativistic transport. This framework is also well adapted to situations with weaker notions of coercivity corresponding to either an external potential with slower growth at infinity or to local equilibria with fatter tails than the Maxwellian. After reviewing various families of interpolation inequalities which dictate the asymptotic behaviours of the solutions to the Fokker-Planck equations, we extend the $\mathrm{L}^{2}$ hypocoercivity method to the kinetic Fokker-Planck equations and establish a classification in terms the (microscopic) local equilibria and the (macroscopic) equilibria associated with the Fokker-Planck diffusion limit.

Reviewing extensively the literature on the asymptotic behaviour of the solutions of Fokker-Planck, degenerate Fokker-Planck and kinetic Fokker-Planck equations goes beyond our scope. Let us simply quote some papers directly related to our methods, with more details to be given later.

Concerning Fokker-Planck equations, coercivity for the diffusion operator means spectral gap and Poincaré inequality, and thus exponential decay of the solutions. This is a basic example of application of the carré du champ method: see [5]. Weak Poincaré inequalities are natural in the absence of spectral gaps as explained in [6] and have been quite systematically explored: see [35, 3, 29] and earlier references therein. However, such methods require strong assumptions on the initial data. This is the reason why we adopt an alternative approach based on moments and weighted functional inequalities, where the extreme case corresponds to Nash's inequality in absence of an external potential. See Table 1.

As for kinetic Fokker-Planck equations, hypocoercivity primarily refers to the method exposed in [36]. We can also quote [34] for a detailed presentation of the commutator method and of Bakry-Emery type computations applied to estimates of the relaxation to equilibrium. More results and further references can also be found in [19]. In [28] S. Hu and X. Wang introduced a weak hypocoercivity approach à la Villani, using a weak Poincaré inequality, and proved subexponential convergence to equilibrium. This was later extended to a class of degenerate diffusion processes in [24] by M. Grothaus and F.-Y. Wang using weak Poincaré inequalities for the symmetric and antisymmetric part of the generator, with non-exponential rates of convergence. In the same vein, C. Cao proved quantitative convergence rates for the kinetic Fokker-Planck equation with more general confinement forces in [16, 17].

Alternatively the method of [21] was extended to cases without potentials in [10] while cases of weak or very weak potentials were considered respectively in [9] and [11]. Here the idea is to introduce moments and weighted interpolation inequalities to prove non-exponential decay or convergence rates. In these papers the effort has been mostly focused on the role of the external potential and fat tail local equilibria were not taken into consideration. However, it is known from [30] that fat-tail local equilibria can be responsible of a fractional diffusion limit, which may govern decay rates in the case without external potential as shown in [8], but this is not always the case. Non-Maxwellian local equilibria have been less explored than the Maxwellian case, but one has to mention [14, 15] for such an extension of the earlier works [1, 18], with slightly different methods based on weak norms, Lions' lemma and time-averages.

## 2 From microscopic and macroscopic coercivity to hypocoercivity

Let us start by an expository section which collects some known results and introduces our present purpose.
Let us consider the general evolution equation

$$
\begin{equation*}
\frac{d F}{d t}+\mathrm{T} F=\mathrm{L} F \tag{1}
\end{equation*}
$$

where $F$ is the density of a probability distribution defined on a real or complex Hilbert space $\mathscr{H}$ with scalar product $\langle\cdot, \cdot\rangle$ and norm $\|\cdot\|$. We assume that T and L are two linear operators, respectively anti-Hermitian and Hermitian: $\mathrm{T}^{*}=-\mathrm{T}$ and $L^{*}=\mathrm{L}$, where * denotes the adjoint with respect to $\langle\cdot, \cdot\rangle$. We are interested in the decay rate of $F$ or in the convergence to a steady state $F_{\star}$. We assume that $F_{\star}$ is unique, up to normalization. Since (1) is linear, we can always replace $F$ by $F-F_{\star}$ and study the convergence to 0 of an eventually sign changing function $F$. We have in mind that L is an elliptic degenerate operator. If $\Pi$ is the orthogonal projection onto the kernel of L , we assume that L has the microscopic coercivity property in the sense that it is coercive on $(1-\Pi) \mathscr{H}$, where 1 is here a shorthand notation for the identity that will make sense in the functional setting of interest. In other words, we claim that

$$
\begin{equation*}
\frac{1}{2} \frac{d}{d t}\|F\|^{2}=\langle\mathrm{L} F, F\rangle \leq-\lambda_{m}\|(1-\Pi) F\|^{2} \tag{H1}
\end{equation*}
$$

for some $\lambda_{m}>0$. This is not enough to conclude that $\|F(t, \cdot)\|$ decays exponentially as we have no decay rate on $\operatorname{Ker}(\mathrm{L})$, but if the operators L and T do not commute, we can hope that some of the decay properties on $(1-\Pi) \mathscr{H}$ are transferred on $\Pi \mathscr{H}$. This points towards the computation of various commutators and the whole machinery of Hörmander's hypoellipticity theory. A micro/macro approach offers a simpler framework, that has the advantage of clarifying the role played by various functional inequalities in estimating decay rates of $F$. The underlying ideas rely on the formal macroscopic limit of the scaled evolution equation

$$
\varepsilon \frac{d F}{d t}+\mathrm{T} F=\frac{1}{\varepsilon} \mathrm{~L} F
$$

on the Hilbert space $\mathscr{H}$, which is a typical parabolic scaling when $\varepsilon$ is a small parameter. Using a formal expansion of a solution $F_{\varepsilon}=F_{0}+\varepsilon F_{1}+\varepsilon^{2} F_{2}+O\left(\varepsilon^{3}\right)$ as $\varepsilon \rightarrow 0_{+}$and solving the equation order by order, we obtain

$$
\begin{array}{ll}
\text { at order } O\left(\varepsilon^{-1}\right): & \mathrm{L} F_{0}=0, \\
\text { at order } O\left(\varepsilon^{0}\right): & \mathrm{T} F_{0}=\mathrm{L} F_{1}, \\
\text { at order } O\left(\varepsilon^{1}\right): & \frac{d F_{0}}{d t}+\mathrm{T} F_{1}=\mathrm{L} F_{2} .
\end{array}
$$

The first and second equation respectively read as $F_{0}=\Pi F_{0}$ and $F_{1}=-(\mathrm{T} \Pi) F_{0}$. After projection on $\operatorname{Ker}(\mathrm{L})$, the third equation becomes $\frac{d}{d t}\left(\Pi F_{0}\right)-\Pi \mathrm{T}(\mathrm{T}) F_{0}=\Pi\left\llcorner F_{2}=0\right.$ that we can also write as

$$
\begin{equation*}
\frac{\partial F_{0}}{\partial t}+(\mathrm{T} \Pi)^{*}(\mathrm{~T} \Pi) F_{0}=0 \tag{2}
\end{equation*}
$$

Assuming macroscopic coercivity, i.e., the property that the operator $(\mathrm{T} \Pi)^{*}(\mathrm{~T} \Pi)$ is coercive on $(1-\Pi) \mathscr{H}$, we obtain

$$
\begin{equation*}
\frac{1}{2} \frac{d}{d t}\left\|F_{0}\right\|^{2}=-\left\|(\mathrm{T} \Pi) F_{0}\right\|^{2} \leq-\lambda_{M}\left\|F_{0}\right\|^{2} \tag{H2}
\end{equation*}
$$

for some $\lambda_{M}>0$. In order to derive (2), we implicitly used the fact that all terms are of order $\varepsilon$, which relies on the parabolic macroscopic dynamics condition

$$
\begin{equation*}
\Pi Т П F=0 . \tag{H3}
\end{equation*}
$$

As in the hypocoercivity method of [21], let us consider the operator

$$
\mathrm{A}:=\left(1+(\mathrm{T} \Pi)^{*}(\mathrm{~T} \Pi)\right)^{-1}(\mathrm{~T} \Pi)^{*}
$$

where the $(\mathrm{T} \Pi)^{*}(\mathrm{~T} \Pi)$ term is of course reminiscent of (2), and, the Lyapunov functional, or entropy,

$$
\mathrm{H}[F]:=\frac{1}{2}\|F\|^{2}+\delta \operatorname{Re}\langle\mathrm{A} F, F\rangle .
$$

The parameter $\delta>0$, to be determined, as to be thought as a small parameter so that $\mathrm{H}[F]$ is a perturbation of $\frac{1}{2}\|F\|^{2}$. The following estimate is by now classical but deserves some emphasis. Let us consider $G=\mathrm{A} F$, i.e., the solution of $(\mathrm{T} \Pi)^{*} F=G+(\mathrm{T} \Pi)^{*} \mathrm{~T} \Pi G$. As in [21, Lemma 1], by a Cauchy-Schwarz inequality, we learn that

$$
\begin{aligned}
\langle\mathrm{TA} F, F\rangle=\left\langle G,(\mathrm{~T} \Pi)^{*} F\right\rangle=\|G\|^{2}+\|\mathrm{T} \Pi G\|^{2} & =\|\mathrm{A} F\|^{2}+\|\mathrm{TA} F\|^{2} \\
& \leq\|\mathrm{TA} F\|\|(\operatorname{Id}-\Pi) F\| \leq \frac{1}{2 \mu}\|\mathrm{TA} F\|^{2}+\frac{\mu}{2}\|(\mathrm{Id}-\Pi) F\|^{2}
\end{aligned}
$$

Applied with either $\mu=1 / 2$ or $\mu=1$, this estimate proves that $\|\mathrm{A} F\| \leq \frac{1}{2}\|(\operatorname{Id}-\Pi) F\|$ and $\|\mathrm{TA} F\| \leq$ $\|(\operatorname{Id}-\Pi) F\|$ Incidentally, this proves that

$$
\begin{align*}
& |\langle\mathrm{TA} F, F\rangle|=|\langle\mathrm{TA} F,(\operatorname{Id}-\Pi) F\rangle| \leq\|(\operatorname{Id}-\Pi) F\|^{2}  \tag{3a}\\
& |\langle\mathrm{~A} F, F\rangle| \leq \frac{1}{2}\|\Pi F\|\|(\operatorname{Id}-\Pi) F\| \leq \frac{1}{4}\|F\|^{2} \tag{3b}
\end{align*}
$$

We read from (3b) that $\mathrm{H}[F]$ and $\|F\|^{2}$ are equivalent with

$$
\frac{2-\delta}{4}\|F\|^{2} \leq \mathrm{H}[F] \leq \frac{2+\delta}{4}\|F\|^{2}
$$

However, the twist introduced in $\mathrm{H}[F]$ by $\langle\mathrm{A} F, F\rangle$ makes it exponentially decaying in $t$ if $F$ solves (1). We can indeed compute

$$
-\frac{d}{d t} \mathrm{H}[F]=\mathrm{D}[F]
$$

where

$$
\begin{equation*}
\mathrm{D}[F]:=-\langle\mathrm{L} F, F\rangle+\delta\langle\operatorname{AT} \Pi F, F\rangle-\delta(\operatorname{Re}\langle\mathrm{TA} F, F\rangle-\operatorname{Re}\langle\mathrm{AT}(1-\Pi) F, F\rangle+\operatorname{Re}\langle\mathrm{AL} F, F\rangle) \tag{4}
\end{equation*}
$$

By (H1), we know that $-\langle L F, F\rangle \geq \lambda_{m}\|(1-\Pi) F\|^{2}$. On the other hand, (H2) amounts to

$$
\left\langle(\mathrm{T} \Pi)^{*}(\mathrm{~T} \Pi) F, F\right\rangle \geq \lambda_{M}\|F\|^{2} \quad \text { if } \quad F \in \operatorname{Ker}(\mathrm{~L})
$$

and, by construction, the operator $A$ is therefore such that

$$
\begin{equation*}
\langle\operatorname{AT\Pi F}, F\rangle \geq \frac{\lambda_{M}}{1+\lambda_{M}}\|\Pi F\|^{2} \tag{5}
\end{equation*}
$$

The first two terms in the definition of $D[F]$ can be combined to prove that

$$
\begin{equation*}
\mathrm{D}[F] \geq \lambda_{m}\|(1-\Pi) F\|^{2}+\frac{\delta \lambda_{M}}{1+\lambda_{M}}\|\Pi F\|^{2}-\delta(\operatorname{Re}\langle\mathrm{TA} F, F\rangle-\operatorname{Re}\langle\mathrm{AT}(1-\Pi) F, F\rangle+\operatorname{Re}\langle\mathrm{AL} F, F\rangle) \tag{6}
\end{equation*}
$$

Under the additional assumption that the last term in the above identity involves only bounded auxiliary operators in the sense that

$$
\begin{equation*}
\|\mathrm{AT}(1-\Pi) F\|+\|\mathrm{AL} F\| \leq C_{M}\|(1-\Pi) F\|, \tag{H4}
\end{equation*}
$$

one obtains the entropy - entropy production inequality

$$
\mathrm{D}[F] \geq \lambda \mathrm{H}[F]
$$

for some explicit constant $\lambda>0$. The precise statement goes as follows. It has been established in [21] in the case of a real Hilbert space $\mathscr{H}$ and extended to complex Hilbert spaces in [10].

Theorem $1([10,21])$ Let L and T be closed linear operators in the complex Hilbert space $(\mathcal{H},\langle\cdot, \cdot\rangle)$. We assume that L is Hermitian and T is anti-Hermitian, and that $(\mathrm{H} 1)-(\mathrm{H} 4)$ hold for some positive constants $\lambda_{m}$, $\lambda_{M}$, and $C_{M}$. Then there is some $\delta_{\star} \in(0,2) \cap\left(0, \lambda_{m}\right)$ such that, for any $\delta \in\left(0, \delta_{\star}\right)$, there are explicit constants $\lambda>0$ and $\mathscr{C}>1$ for which, if $F$ solves $(1)$ with initial datum $F_{0} \in \mathcal{H}$, then

$$
\begin{equation*}
\mathrm{H}[F(t, \cdot)] \leq \mathrm{H}\left[F_{0}\right] e^{-\lambda t} \quad \text { and } \quad\|F(t, \cdot)\|^{2} \leq \mathscr{C} e^{-\lambda t}\left\|F_{0}\right\|^{2} \quad \forall t \geq 0 \tag{7}
\end{equation*}
$$

The estimates of $\lambda>0$ and $\mathscr{C}>1$ in [10, Proposition 4] have been improved in [2, Proposition 2] as follows. With $X:=\|(\mathrm{Id}-\Pi) F\|$ and $Y:=\|\Pi F\|$. Using (3b), we read from (3b) that

$$
\mathrm{H}[F] \leq \frac{1}{2}\left(X^{2}+Y^{2}\right)+\frac{\delta}{2} X Y
$$

while it follows from (6), (3a) and (H4) that

$$
\mathrm{D}[F]-\lambda \mathrm{H}[F] \geq\left(\lambda_{m}-\delta-\frac{\lambda}{2}\right) X^{2}-\delta\left(C_{M}+\frac{\lambda}{2}\right) X Y+\left(\frac{\delta \lambda_{M}}{1+\lambda_{M}}-\frac{\lambda}{2}\right) Y^{2}
$$

With $K_{M}:=\frac{\lambda_{M}}{1+\lambda_{M}}<1$ and $\delta_{\star}:=\frac{4 K_{M} \lambda_{m}}{4 K_{M}+C_{M}^{2}}<\lambda_{m}$, a simple discriminant condition shows that for any $\delta \in\left(0, \delta_{\star}\right)$, the right-hand side is nonnegative for the largest (positive) solution of

$$
\delta^{2}\left(C_{M}+\frac{\lambda}{2}\right)^{2}-4\left(\lambda_{m}-\delta-\frac{\lambda}{2}\right)\left(\frac{\delta \lambda_{M}}{1+\lambda_{M}}-\frac{\lambda}{2}\right)=0
$$

We refer to [2] for further details and to [23] for more considerations on the functional framework.
In the framework of kinetic equations, T and L are respectively the transport operator and the collision operator acting on a distribution function $f(t, x, v)$ where $t \geq 0$ is the time, $x$ is the position and $v$ is the velocity. To fix ideas, we shall assume that $x, v \in \mathbb{R}^{d}$ and consider

- a transport operator defined by the Poisson bracket as

$$
\begin{equation*}
\mathrm{T} f:=\nabla_{v} \mathscr{E} \cdot \nabla_{x} f-\nabla_{x} \mathscr{E} \cdot \nabla_{v} f \tag{8}
\end{equation*}
$$

corresponding to the Hamiltonian energy

$$
(x, v) \mapsto \mathscr{E}(x, v):=\frac{1}{\beta}\langle v\rangle^{\beta}+\phi(x),
$$

where $\phi$ denotes an external, given potential,

- a collision operator of Fokker-Planck type given by

$$
\begin{equation*}
\mathrm{L} f:=\nabla_{v} \cdot\left(\nabla_{v} f+v\langle v\rangle^{\beta-2} f\right) \tag{9}
\end{equation*}
$$

Here we use the notation

$$
\langle v\rangle:=\sqrt{1+|v|^{2}} .
$$

Unless $\beta=2$, our choice of the usual transport operator differs from the transport operator corresponding to Newton's equations, namely $v \cdot \nabla_{x}-\nabla_{x} \phi \cdot \nabla_{v}$, which has been widely studied in the literature. Our purpose is to study the asymptotic behaviour of the solution of

$$
\begin{equation*}
\frac{\partial f}{\partial t}+\mathrm{T} f=\mathrm{L} f, \quad f(t=0, \cdot \cdot)=f_{0} \tag{10}
\end{equation*}
$$

with $T$ and $L$ given respectively by (8) and (9) as $t \rightarrow+\infty$. With these choices and under the condition that $e^{-\phi}$ is integrable, a remarkable property is that the Gibbs state

$$
\begin{equation*}
f_{\star}(x, v):=\frac{1}{Z} e^{-\mathscr{E}(x, v)} \quad \text { where } \quad Z=\int_{\mathbb{R}^{d}} e^{-\phi} d x \int_{\mathbb{R}^{d}} e^{-\frac{1}{\beta}\langle v\rangle^{\beta}} d v \tag{11}
\end{equation*}
$$

is a stationary solution of mass $\left\|f_{\star}\right\|_{L^{1}\left(\mathbb{R}^{d} \times \mathbb{R}^{d}, d x d v\right)}=1$. As a consequence, $f_{\star}$ is local equilibrium, i.e., belongs to $\operatorname{Ker}(\mathrm{L})$ which is generated by the functions

$$
\begin{equation*}
f_{\rho}(x, v)=\frac{\rho(x) e^{-\frac{1}{\beta}\langle v\rangle^{\beta}}}{\int_{\mathbb{R}^{d}} e^{-\frac{1}{\beta}\langle v\rangle^{\beta}} d v} \tag{12}
\end{equation*}
$$

The property $\mathrm{T} f_{\star}=\mathrm{L} f_{\star}=0$ sometimes appears in the physics literature as a factorization property. As for the Hilbert space, let us consider $\mathrm{L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d}, d \mu\right)$ where

$$
d \mu=\frac{d x d v}{f_{\star}(x, v)}
$$

The orthogonal projector onto $\operatorname{Ker}(\mathrm{L})$ is defined as the projection on local equilibria by

$$
\Pi f=f_{\rho}(x, v) \quad \text { where } \quad \rho=\int_{\mathbb{R}^{d}} f d v
$$

Notice that $f$ and $f_{\rho}$ have the same spatial density because $\int_{\mathbb{R}^{d}} f_{\rho} d v=\rho$. Under the assumption that the measure $e^{-\phi} d x$ admits a Poincaré inequality, that is, there is some positive constant $\lambda_{\phi}$ for which

$$
\begin{equation*}
\int_{\mathbb{R}^{d}}|\nabla u|^{2} e^{-\phi} d x \geq \lambda_{\phi} \int_{\mathbb{R}^{d}}|u|^{2} e^{-\phi} d x \quad \forall u \in \mathscr{D}\left(\mathbb{R}^{d}\right) \quad \text { such that } \quad \int_{\mathbb{R}^{d}} u e^{-\phi} d x=0 \tag{13}
\end{equation*}
$$

Theorem 1 applies as follows.
Corollary 1 Assume that $\phi$ is such that (13) holds for some $\lambda_{1}>0$ and $\beta \geq 1$. If $f$ solves (10) for some nonnegative function $f_{0} \in \mathrm{~L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d}, d \mu\right)$ with $\left\|f_{0}\right\|_{L^{1}\left(\mathbb{R}^{d} \times \mathbb{R}^{d}, d x d v\right)}=1$, then for some $\delta>0$, there exists $\lambda>0$ and $\mathscr{C}>1$ such that (7) holds with $\|\cdot\|=\|\cdot\|_{L^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d}, d \mu\right)}$.

The case $\beta=2$ is by now standard and covered in various papers: see [20,21] for an $\mathrm{L}^{2}$ hypocoercivity approach and $[27,25,26]$ as well as references therein for earlier results based on hypoelliptic methods. To our knowledge the case $\beta \neq 2$ has not been studied yet by $\mathrm{L}^{2}$-hypocoercivity methods, but convergence results are known from [18, 15] using other methods. Of particular interest in physics is the case $\beta=1$ where $\mathscr{E}$ is the standard energy for relativistic particles, up to physical constants (mass and speed of light are taken equal to $1)$, while the corresponding $L$ operator is not much more than a caricature of a relativistic collision operator. Concerning $L$ and from the point of view of phenomenological models, it is however interesting to consider local equilibria given by (12) and it makes sense to assume that stationary solutions have the factorization property. Throughout this paper, we will make this simplifying assumption.

The strategy of the proof of Corollary 1 goes as follows. With $\beta \geq 1$, we have the Poincaré inequality: there is some $\lambda_{m}>0$ such that, for all $g \in \mathrm{~L}^{2}\left(\mathbb{R}^{d}, e^{-\frac{1}{\beta}\langle v\rangle^{\beta}} d v\right)$ such that $\int_{\mathbb{R}^{d}} g e^{-\frac{1}{\beta}\langle v\rangle^{\beta}} d v=0$, we have

$$
\begin{equation*}
\int_{\mathbb{R}^{d}}|\nabla g|^{2} e^{-\frac{1}{\beta}\langle v\rangle^{\beta}} d v \geq \lambda_{m} \int_{\mathbb{R}^{d}}|g|^{2} e^{-\frac{1}{\beta}\langle v\rangle^{\beta}} d v \tag{14}
\end{equation*}
$$

This is for instance a consequence of Persson's lemma based on the observation that $\psi(v):=\frac{1}{\beta}\langle v\rangle^{\beta}$ is such that

$$
\liminf _{|v| \rightarrow+\infty}\left(\frac{1}{4}|\nabla \psi(v)|^{2}-\frac{1}{2} \Delta \psi(v)\right)>0
$$

See for instance [12, Appendix A.1] for details. As a consequence, (H1) holds. The macroscopic coercivity condition (H2) follows from (13). The parabolic macroscopic dynamics condition (H3) is a simple consequence of the definitions of $T$ and $\Pi$. Hence the only assumption that deserves some attention is (H4), which is obtained by elliptic estimates. A detailed proof is given in Section 4.6.

In the framework of (8) and (9), an elementary computation shows that (2) written for $f_{\rho}$ defined by (12) reduces to the Fokker-Planck equation

$$
\begin{equation*}
\frac{\partial \rho}{\partial t}=\sigma(\Delta \rho+\nabla \cdot(\rho \nabla \phi)) \tag{15}
\end{equation*}
$$

with diffusion coefficient $\sigma$ given in terms of $\beta$ by

$$
\begin{equation*}
\sigma=\frac{1}{d} \int_{\mathbb{R}^{d}}|v|^{2}\langle v\rangle^{2 \beta-4} e^{-\frac{1}{\beta}\langle v\rangle^{\beta}} d v \tag{16}
\end{equation*}
$$

In order to simplify the discussion, we shall assume that

$$
\phi(x)=\frac{1}{\alpha}\langle x\rangle^{\alpha} \quad \forall x \in \mathbb{R}^{d}
$$

Corollary 1 corresponds to $\alpha \geq 1$. Our purpose is to investigate the decay rates of (10) in terms of $\beta>0$ and $\alpha>0$. Let us start by studying the asymptotic behaviour of a solution $\rho$ of (15) depending on the various cases for the potential $\phi$. For completeness, we will also consider the limit case as $\alpha \rightarrow 0$ and distinguish several cases depending on whether we take $\phi=0$ a.e., or, depending on $\gamma>0$,

$$
\phi(x)=\gamma \log \langle x\rangle \quad \forall x \in \mathbb{R}^{d} .
$$

## 3 Fokker-Planck equations with various external potentials, moments and functional inequalities

We collect some results on the asymptotic behaviour of the solutions of (15) as $t \rightarrow+\infty$ based on various functional inequalities. In this section we omit the discussion of optimality cases and estimates on sharp constants in the functional inequalities. By default, constants in the inequalities are always taken to their optimal value. Table 1 collects the results in a synthetic picture, although without all details on the assumptions.

### 3.1 Strong confinement case: Poincaré inequality

If $\phi(x)=\frac{1}{\alpha}\langle x\rangle^{\alpha}$ with $\alpha \geq 1$, then (13) holds with $\lambda_{\phi}=\lambda_{M}>0$. We apply it to $u=\rho / e^{-\phi}$. A solution $\rho$ of (15) with initial datum $\rho_{0}$ at $t=0$ satisfies

$$
\frac{d}{d t}\|\rho(t, \cdot)\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d}, e^{\phi} d x\right)}^{2}=-2 \sigma\|\nabla \rho(t, \cdot)\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d}, e^{\phi} d x\right)}^{2} \leq-2 \lambda_{M} \sigma\|\rho(t, \cdot)\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d}, e^{\phi} d x\right)}^{2}
$$

which yields the estimate

$$
\|\rho(t, \cdot)\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d}, e^{\phi} d x\right)}^{2} \leq\left\|\rho_{0}\right\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d}, e^{\phi} d x\right)}^{2} e^{-2 \lambda_{M} \sigma t} \quad \forall t \geq 0
$$

### 3.2 Weak confinement case: weighted Poincaré inequality

The following results are taken from [9, Appendices A and B ]. We assume here that $\alpha \in(0,1)$ and consider a solution of (15) with nonnegative initial datum $\rho_{0} \in \mathrm{~L}^{1}\left(\mathbb{R}^{d}, d x\right)$ such that $\left\|\rho_{0}\right\|_{\mathrm{L}^{1}\left(\mathbb{R}^{d}\right)}=1$. The function $u=\rho e^{\phi}$ is a solution of the Ornstein-Uhlenbeck equation (also known as the backward Kolmogorov equation)

$$
\begin{equation*}
\frac{\partial u}{\partial t}=\sigma(\Delta u-\nabla \phi \cdot \nabla u) . \tag{17}
\end{equation*}
$$

With $k \geq 0$, let us compute
$\frac{d}{d t} \int_{\mathbb{R}^{d}}|u(t, x)|^{2}\langle x\rangle^{k} e^{-\phi} d x+2 \sigma \int_{\mathbb{R}^{d}}\left|\nabla_{x} u(t, x)\right|^{2}\langle x\rangle^{k} e^{-\phi} d x \leq \int_{\mathbb{R}^{d}}\left(a_{k}-b_{k}\langle x\rangle^{\alpha-2}\right)|u(t, x)|^{2}\langle x\rangle^{k} e^{-\phi} d x$ for some $a_{k} \in \mathbb{R}, b_{k} \in(0,+\infty)$. As a consequence, there exists a constant $\mathcal{K}(k)>0$ such that

$$
\int_{\mathbb{R}^{d}}\langle x\rangle^{k}|\rho(t, x)|^{2} e^{\phi} d x \leq \mathcal{K}(k) \int_{\mathbb{R}^{d}}\langle x\rangle^{k}\left|\rho_{0}\right|^{2} e^{\phi} d x \quad \forall t \geq 0
$$

See [9, Proposition 4 and Appendix B.2] for details. With $k=0$, we notice that $a_{0}=b_{0}=0$ and use the weighted Poincaré inequality

$$
\begin{equation*}
\int_{\mathbb{R}^{d}}\left|\nabla_{x} u(t, x)\right|^{2} e^{-\phi} d x \geq \mathscr{C}_{\alpha}^{\mathrm{wP}} \int_{\mathbb{R}^{d}}|u(t, x)-\bar{u}|^{2} \frac{e^{-\phi}}{\langle x\rangle^{2(1-\alpha)}} d x \quad \text { where } \quad \bar{u}=\frac{\int_{\mathbb{R}^{d}} u e^{-\phi} d x}{\int_{\mathbb{R}^{d}} e^{-\phi} d x} \tag{18}
\end{equation*}
$$

(notice that the average $\bar{u}$ is computed with respect to the measure of the l.h.s.) to prove that

$$
\frac{d}{d t} \int_{\mathbb{R}^{d}}|u(t, x)-\bar{u}|^{2} e^{-\phi} d x=-2 \sigma \int_{\mathbb{R}^{d}}\left|\nabla_{x} u(t, x)\right|^{2} e^{-\phi} d x \leq-2 \sigma \mathscr{C}_{\alpha}^{\mathrm{wP}} \int_{\mathbb{R}^{d}}|u(t, x)-\bar{u}|^{2} \frac{e^{-\phi}}{\langle x\rangle^{2(1-\alpha)}} d x
$$

With $k \geq 2(1-\alpha)$ and $\theta=k /(k+2(1-\alpha))$, Hölder's inequality

$$
\int_{\mathbb{R}^{d}}|u-\bar{u}|^{2} e^{-\phi} d x \leq\left(\int_{\mathbb{R}^{d}}|u-\bar{u}|^{2} \frac{e^{-\phi}}{\langle x\rangle^{2(1-\alpha)}} d x\right)^{\theta}\left(\int_{\mathbb{R}^{d}}|u-\bar{u}|^{2}\langle x\rangle^{k} e^{-\phi} d x\right)^{1-\theta}
$$

allows us to prove that

$$
\int_{\mathbb{R}^{d}}\left|\rho(t, x)-\rho_{\star}(x)\right|^{2} e^{\phi} d x \leq\left(\left\|\rho_{0}-\rho_{\star}\right\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d}, e^{\phi} d x\right)}^{-4(1-\alpha) / k}+\frac{4(1-\alpha) \sigma \mathscr{C}_{\alpha}^{\mathrm{wP}}}{k \mathcal{K}_{*}^{2(1-\alpha) / k}} t\right)^{-\frac{k}{2(1-\alpha)}} \quad \forall t \geq 0
$$

with $\mathcal{K}_{*}:=\mathcal{K}(k)^{2} \int_{\mathbb{R}^{d}}\langle x\rangle^{k}\left|\rho_{0}\right|^{2} e^{\phi} d x+\int_{\mathbb{R}^{d}}\langle x\rangle^{k} e^{-\phi} d x\left\|\rho_{0}\right\|_{\mathrm{L}^{1}\left(\mathbb{R}^{d}\right)}^{2}$.

### 3.3 Weak confinement, a limit case: Hardy-Poincaré inequality

The results in this case are new. In the limit as $\alpha \rightarrow 0_{+}$, we can assume that $\phi(x)=\gamma \log \langle x\rangle$ with $\gamma>d$ so that $f_{\star}$ defined by (11) is integrable. Let $u=\rho e^{\phi}$ be a solution of (17). With $k \geq 0$, let us compute

$$
\begin{align*}
\frac{d}{d t} \int_{\mathbb{R}^{d}}|u(t, x)|^{2}\langle x\rangle^{k} e^{-\phi} d x & +2 \sigma \int_{\mathbb{R}^{d}}\left|\nabla_{x} u(t, x)\right|^{2}\langle x\rangle^{k} e^{-\phi} d x \\
=k & \int_{\mathbb{R}^{d}}|u(t, x)|^{2}\langle x\rangle^{k-2}\left(d+(k-\gamma-2) \frac{|x|^{2}}{\langle x\rangle^{2}}\right) e^{-\phi} d x \\
& \leq k \int_{\mathbb{R}^{d}}|u(t, x)|^{2}\langle x\rangle^{k-2}\left(d+k-\gamma-2-(k-\gamma-2)\langle x\rangle^{-2}\right) e^{-\phi} d x \tag{19}
\end{align*}
$$

By arguing as in [9, Proposition 4 and Appendix B.2], this is enough to prove that there exists a constant $\mathcal{K}(k)>0$ such that

$$
\int_{\mathbb{R}^{d}}\langle x\rangle^{k}|u(t, x)|^{2} e^{-\phi} d x \leq \mathcal{K}(k) \int_{\mathbb{R}^{d}}\langle x\rangle^{k}\left|\rho_{0}\right|^{2} e^{\phi} d x \quad \forall t \geq 0
$$

if $k \in(\gamma-d, \gamma+2-d)$. Notice that a better range of $k$ can be obtained as follows. Since $\langle x\rangle^{k} e^{-\phi}=\langle x\rangle^{k-\gamma}$, we learn from [7,22] that for some positive constant $\mathscr{C}_{\gamma-k}^{\mathrm{HP}}$, we have the Hardy-Poincaré inequality

$$
\begin{equation*}
\int_{\mathbb{R}^{d}}\left|\nabla_{x} u\right|^{2}\langle x\rangle^{k} e^{-\phi} d x \geq \mathscr{C}_{\gamma-k}^{\mathrm{HP}} \int_{\mathbb{R}^{d}}|u-\bar{u}|^{2}\langle x\rangle^{k-2} e^{-\phi} d x \tag{20}
\end{equation*}
$$

for an appropriate choice of $\bar{u}$ depending on $k-\gamma$. In any case, Inequality (19) written with $k=0$, that is,

$$
\frac{d}{d t} \int_{\mathbb{R}^{d}}|u(t, x)-\bar{u}|^{2} e^{-\phi} d x \leq-2 \sigma \int_{\mathbb{R}^{d}}\left|\nabla_{x} u(t, x)\right|^{2} e^{-\phi} d x
$$

and then (20) combined with Hölder's inequality applied as in the case of the weighted Poincaré inequality (with $\alpha=0$ ) show that

$$
\int_{\mathbb{R}^{d}}\left|\rho(t, x)-\rho_{\star}(x)\right|^{2} e^{\phi} d x \leq \int_{\mathbb{R}^{d}}\left|\rho_{0}-\rho_{\star}\right|^{2} e^{\phi} d x(1+c t)^{-\frac{k}{2}} \quad \forall t \geq 0
$$

for some constant $c$ which depends on $d, \gamma, \sigma, k, \int_{\mathbb{R}^{d}}\left|\rho_{0}\right|^{2}\langle x\rangle^{k-\gamma} d x$ and $\left\|\rho_{0}\right\|_{\mathrm{L}^{1}\left(\mathbb{R}^{d}\right)}^{2}$.

### 3.4 Very weak confinement case: Caffarelli-Kohn-Nirenberg inequality

According to [11, Theorem 1], if $1 \leq \gamma<d$ and $\phi(x)=\gamma \log \langle x\rangle$, a solution $\rho$ of (15) with nonnegative initial datum $\rho_{0} \in \mathrm{~L}^{1}\left(\mathbb{R}^{d},\langle x\rangle^{k} d x\right) \cap \mathrm{L}^{2}\left(\mathbb{R}^{d}, e^{\phi} d x\right)$ with $k=\max \{2, \gamma / 2\}$ satisfies the estimate

$$
M_{k}(t):=\int_{\mathbb{R}^{d}}\langle x\rangle^{k} \rho(t, x) d x \leq 2^{\frac{k-2}{2}}\left(M_{0}+\left(\left(M_{k}(0)-M_{0}\right)^{2 / k}+2 \sigma(d+k-2-\gamma) M_{0}^{2 / k} t\right)^{k / 2}\right)
$$

With $e^{-\phi}=\langle x\rangle^{-\gamma}$ and $u=\rho\langle x\rangle^{\gamma}$, a solution $u$ of (17) satisfies the estimate

$$
\frac{d}{d t} \int_{\mathbb{R}^{d}}|u(t, x)|^{2}\langle x\rangle^{-\gamma} d x=-2 \sigma \int_{\mathbb{R}^{d}}|\nabla u(t, x)|^{2}\langle x\rangle^{-\gamma} d x
$$

Combined with the inhomogeneous Caffarelli-Kohn-Nirenberg inequality

$$
\int_{\mathbb{R}^{d}}|u|^{2}\langle x\rangle^{-\gamma} d x \leq \mathscr{C}_{k, \gamma}^{\mathrm{CKN}}\left(\int_{\mathbb{R}^{d}}|\nabla u|^{2}\langle x\rangle^{-\gamma} d x\right)^{a}\left(\int_{\mathbb{R}^{d}} u\langle x\rangle^{k-\gamma} d x\right)^{2(1-a)} \quad \text { with } \quad a=\frac{d+2 k-\gamma}{d+2+2 k-\gamma}
$$

this proves the decay estimate

$$
\|\rho(t, \cdot)\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d}, e^{\phi} d x\right)}^{2} \leq\left\|\rho_{0}\right\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d}, e^{\phi} d x\right)}^{2}(1+c t)^{-\frac{d-\gamma}{2}} \quad \forall t \geq 0
$$

where the constant $c$ depends on $d, \gamma, \sigma,\left\|\rho_{0}\right\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d}, e^{\phi} d x\right)}, M_{0}=\left\|u_{0}\right\|_{1}$, and $M_{k}(0)=\left\||x|^{k} \rho_{0}\right\|_{1}$. See [11] for further details.

### 3.5 No potential case: Nash's inequality

We assume that $\phi=0$ so that (15) is the standard heat equation. By Nash's inequality

$$
\|u\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d}\right)} \leq \mathscr{C}_{\mathrm{Nash}}\|\nabla u\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d}\right)}^{\frac{d}{d+2}}\|u\|_{\mathrm{L}^{1}\left(\mathbb{R}^{d}\right)}^{\frac{2}{d+2}} \quad \forall u \in \mathrm{H}^{1}\left(\mathbb{R}^{d}, d x\right)
$$

a solution $\rho$ of (15) with initial datum $\rho_{0}$ at $t=0$ satisfies

$$
\frac{d}{d t}\|\rho(t, \cdot)\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d}\right)}^{2}=-2 \sigma\|\nabla \rho(t, \cdot)\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d}\right)}^{2}
$$

Hence $y(t):=\|\rho(t, \cdot)\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d}\right)}^{2}$ solves the differential inequality $y^{\prime} \leq-2 \sigma \mathscr{C}_{\text {Nash }^{-1}}\left\|\rho_{0}\right\|_{\mathrm{L}^{1}\left(\mathbb{R}^{d}\right)}^{-\frac{4}{d}} y^{1+\frac{2}{d}}$ which, after integration, yields the estimate

$$
\|\rho(t, \cdot)\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d}\right)}^{2} \leq\left(\left\|\rho_{0}\right\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d}\right)}^{-4 / d}+\frac{4 \sigma}{d \mathscr{C}_{\text {Nash }}}\left\|\rho_{0}\right\|_{\mathrm{L}^{1}\left(\mathbb{R}^{d}\right)}^{-4 / d} t\right)^{-d / 2} \quad \forall t \geq 0
$$

### 3.6 A short summary

In case of the Fokker-Planck equation (15), Table 1 summarizes what is known on decay rates based on moment estimates and interpolation inequalities. Cases in gray will be further considered in the case of kinetic equations.

| Potential | $\phi=0$ | $\phi(x)=\gamma \log \langle x\rangle$ <br> $\gamma<d$ | $\phi(x)=\gamma \log \langle x\rangle$ <br> $\gamma>d$ | $\phi(x)=\frac{1}{\alpha}\langle x\rangle^{\alpha}$ <br> $\alpha \in(0,1)$ | $\phi(x)=\frac{1}{\alpha}\langle x\rangle^{\alpha}$ <br> $\alpha \geq 1$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Inequality | Nash | Caffarelli-Kohn- <br> Nirenberg | Hardy-Poincaré | Weighted <br> Poincaré | Poincaré |
| Asymptotic <br> behavior | $t^{-d / 2}$ <br> decay | $t^{-(d-\gamma) / 2}$ <br> decay | $t^{-k / 2}$ <br> convergence | $t^{-\frac{k}{2(1-\alpha)}}$ <br> convergence | $e^{-\lambda t}$ <br> convergence |
| References | $[33]$ | $[11]$ |  | $[9]$ | $(*)$ |

Table 1 Short summary of the behaviours as $t \rightarrow+\infty$ of the solution of (15) depending on the choice of $\phi$, with some references. On the left side ( $\phi=0$ or $\gamma<d$ ), there is no global stationary solution and we study decay rates. On the right side, we investigate the convergence rates to a global stationary solution. Under additional or different constraints on the initial data, other behaviours can be obtained based for instance on weak Poincaré inequalities: see [35, Theorem 2.1], [3, Theorem 1.4] and [29].
(*) The use of the Poincaré inequality in relation with the Fokker-Planck equation has a long history, which we cannot cover entirely here: we can for instance refer to [33], and to [5, Chapter 4] for an overview in the context of Markov processes.

## 4 Kinetic Fokker-Planck equations and hypocoercivity results

### 4.1 State of the art

Some known results are collected in Table 2. They are exclusively concerned with the classical transport operator

$$
\mathrm{T} f:=v \cdot \nabla_{x} f-\nabla_{x} \phi \cdot \nabla_{v} f
$$

i.e., coincide with our framework if $\beta=2$ (at the level of the transport operator).

| Potential | $\phi=0$ | $\phi(x)=\frac{1}{\alpha}\langle x\rangle^{\alpha}$ <br> $\alpha \in(0,1)$ | $\phi(x)=\frac{1}{\alpha}\langle x\rangle^{\alpha}$ <br> $\alpha \geq 1$, or $\mathbb{T}^{d}$ <br> Macro Poincaré |
| :---: | :---: | :---: | :---: |
| $\psi(v)=\frac{1}{\beta}\langle v\rangle^{\beta}$ <br> $\beta \geq 1$ <br> Micro Poincaré | $t^{-d / 2}$ <br> decay <br> $[10]$ | $e^{-t^{b}}, b<1$ <br> $\beta=2$ <br> convergence <br> $[16]$ | $e^{-\lambda t}$ <br> convergence <br> $[26,32,20,21$, <br> $31,1,18,14,15]$ |
| $\psi(v)=\frac{1}{\beta}\langle v\rangle^{\beta}$ <br> $\beta \in(0,1)$ | $t^{-\zeta}$ <br> $\zeta=\min \left\{\frac{d}{2}, \frac{\ell}{2(1-\beta)}\right\}$ <br> $\operatorname{decay,[9]}$ | $t^{-\zeta}$ <br> convergence <br> $[13]$ | $t^{-\zeta}$ <br> convergence <br> $[13]$ |
| Limit as $\beta \rightarrow 0_{+}$ <br> $\psi(v)=$ <br> $-(d+\varepsilon) \log \langle v\rangle$ | $\varepsilon \in(0,2)$ <br> fractional dif- <br> fusion limit, [8] | [13] | $-\zeta$ if $\varepsilon>2$ <br> convergence <br> $[13]$ |

Table 2 Rough classification of the asymptotic behaviour of the solutions of $\partial_{t} f+v \cdot \nabla_{x} f-\nabla_{x} \phi \cdot \nabla_{v} f=f_{\star} \nabla_{v}\left(f_{\star}^{-1} \nabla_{v} f\right)$ as $t \rightarrow+\infty$ where $f_{\star}(x, v)=Z^{-1} \exp (-\phi(x)-\psi(v))$. Additional assumptions on the initial datum $f_{0}=f(t=0, \cdot, \cdot)$ are needed: for instance in the case $\alpha \geq 1$ and $\beta \in(0,1)$, the initial datum is such that $f_{0} \in \mathrm{~L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d},\langle\nu\rangle^{(1-\beta) \sigma} d \mu\right)$. In the case $\phi=0$ and $\beta \in(0,1)$, we assume that $f_{0} \in \mathrm{~L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d},\langle\nu\rangle^{\ell / 2} d \mu\right)$. If $\alpha \in(0,1)$ and $\beta \in(0,1)$, using the weak Poincaré inequality requires specific bounds. Further cases and more detailed assumptions can be found in the references collected above.

In Table 2, if $\beta \geq 1$, Micro Poincaré refers to a Poincaré inequality written in the velocity variable $v$, which controls the convergence towards a local equilibrium while, Macro Poincaré refers to a Poincaré inequality written in the position variable $x$, which controls the convergence of the solution in the macroscopic or diffusion limit, towards a global equilibrium, or to 0 if there is no such equilibrium. Cases in gray will be further considered in the case of the transport operator given by (8).

### 4.2 Notation and basic observations

From here on, we assume that $\psi(v)=\frac{1}{\beta}\langle v\rangle^{\beta}$ and $\phi(x)=\frac{1}{\alpha}\langle x\rangle^{\alpha}$ for some $\beta>0$ and $\alpha>0$. With the notation

$$
\rho_{\star}:=\frac{e^{-\phi}}{\int_{\mathbb{R}^{d}} e^{-\phi} d x}, \quad \rho_{f}:=\int_{\mathbb{R}^{d}} f d v \quad \text { and } \quad u_{f}:=\frac{\rho_{f}}{\rho_{\star}}
$$

and a transport operator given by (8), we can write

$$
\left.\Pi f=\rho_{f} \frac{e^{-\psi}}{\int_{\mathbb{R}^{d}} e^{-\psi} d v}=u_{f} f_{\star}, \quad \operatorname{T} \Pi f=\langle v\rangle^{\beta-2}\left(v \cdot \nabla_{x} u_{f}\right) f_{\star} \quad \text { and } \quad \Pi \mathrm{T} f=\left(\nabla_{x} \cdot \int_{\mathbb{R}^{d}} v\langle\nu\rangle\right\rangle^{\beta-2} f d v\right) \frac{f_{\star}}{\rho_{\star}} .
$$

If $f=u f_{\star} \in \operatorname{Ker}(\mathrm{L})$ and $\sigma$ is defined by (16), then

$$
(\mathrm{T})^{*}(\mathrm{~T}) f=-\frac{\sigma}{\rho_{\star}} \nabla_{x} \cdot\left(\rho_{\star} \nabla_{x} u\right) f_{\star}=-\sigma\left(\Delta_{x} u-\nabla_{x} \phi \cdot \nabla_{x} u\right) f_{\star},
$$

Solving $g=\left(1+(\mathrm{T} \Pi)^{*}(\mathrm{~T} \Pi)\right)^{-1} f$ means that $g=u f_{\star}$ where $u=u_{g}$ solves

$$
u-\sigma\left(\Delta_{x} u-\nabla_{x} \phi \cdot \nabla_{x} u\right)=u_{f} .
$$

### 4.3 Main result

Our goal is to get a classification similar to the results summarized in Table 2 for $\beta \neq 2$ in the transport operator defined by (8), i.e., with $\mathrm{T} f:=\nabla_{v} \mathscr{E} \cdot \nabla_{x} f-\nabla_{x} \mathscr{E} \cdot \nabla_{v} f$. As far as we know, this transport operator has not been studied yet in the framework of hypocoercivity methods, except for some recent results in the bounded domain case in [1,14] or when $\alpha \geq 1$ in [18,15] which are based on weak norms and Lions' lemma.

Theorem 2 Let $f=f(t, x, v)$ be a solution of (10) with transport and collision operators given respectively by (8) and (9) for some $\beta>0$ and $\alpha>0$. With $f_{\star}$ defined by (11), we assume that the initial datum satisfies

$$
\begin{equation*}
0 \leq f_{0} \leq C f_{\star} \tag{21}
\end{equation*}
$$

for a suitable constant $C>0$. Depending on $\beta$ and $\alpha$, we have the following convergence and decay estimates.

1. Assume $\beta \geq 1$ and $\alpha \geq 1$. Then there exist constants $\mathscr{C}>0$ and $\lambda>0$ such that any solution $f$ of (10) with initial datum $f_{0} \in \mathrm{~L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d}, d \mu\right)$ satisfies

$$
\left\|f-f_{\star}\right\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d}, d \mu\right)}^{2} \leq \mathscr{C} e^{-\lambda t}\left\|f_{0}-f_{\star}\right\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d}, d \mu\right)}^{2} \quad \forall t \geq 0 .
$$

2. Assume $\beta \in(0,1)$ and $\alpha \geq 1$. Then there exists a constant $\mathscr{C}_{\ell}>0$ such that any solution $f$ of (10), with initial datum $f_{0} \in \mathrm{~L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d},\langle\nu\rangle^{\ell} d \mu\right)$ for some $\ell>0$, satisfies

$$
\left\|f-f_{\star}\right\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d}, d \mu\right)}^{2} \leq \mathscr{C}_{\ell}(1+t)^{-\frac{t}{2(1-\beta)}}\left\|f_{0}-f_{\star}\right\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d}, d \mu\right)}^{2} \quad \forall t \geq 0 .
$$

3. Assume $\beta \geq 1$ and $\alpha \in(0,1)$. Then there exists a constant $\mathscr{C}_{k}>0$ such that any solution $f$ of (10), with initial datum $f_{0} \in \mathrm{~L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d},\langle x\rangle^{k} d \mu\right)$ for some $k>0$, satisfies

$$
\left\|f-f_{\star}\right\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d}, d \mu\right)}^{2} \leq \mathscr{C}_{k}(1+t)^{-\frac{k}{2(1-\alpha)}}\left\|f_{0}-f_{\star}\right\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d}, d \mu\right)}^{2} \quad \forall t \geq 0 .
$$

4. Assume $\beta \in(0,1)$ and $\alpha \in(0,1)$. Then there exist a constant $\mathscr{C}_{k, \ell}>0$ such that any solution $f$ of (10), with initial datum $f_{0} \in \mathrm{~L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d},\langle x\rangle^{k} d \mu\right) \cap \mathrm{L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d},\langle\nu\rangle^{\ell} d \mu\right)$ for some $k>0$ and $\ell>0$, satisfies

$$
\left\|f-f_{\star}\right\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d}, d \mu\right)}^{2} \leq \mathscr{C}_{\mathrm{k}^{\prime} \ell}(1+t)^{-\zeta}\left\|f_{0}-f_{\star}\right\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d}, d \mu\right)}^{2} \quad \forall t \geq 0 .
$$

where $\zeta=\min \left\{\frac{k}{2(1-\alpha)}, \frac{\ell}{2(1-\beta)}\right\}$
5. Assume $\beta \geq 1$ and $\phi=0$. Then there exist a constant $\mathscr{K}>0$ depending on $\left\|f_{0}\right\|_{L^{1}\left(\mathbb{R}^{d} \times \mathbb{R}^{d}, d x d v\right)}$ such that any solution $f$ of $(10)$, with initial datum $f_{0} \in \mathrm{~L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d}, d \mu\right)$, satisfies

$$
\|f\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d}, d \mu\right)}^{2} \leq \mathscr{K}(1+t)^{-\frac{d}{2}}\left\|f_{0}\right\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d}, d \mu\right)}^{2} \quad \forall t \geq 0
$$

6. Assume $\beta \in(0,1)$ and $\phi=0$. Then there exist a constant $\mathscr{K}_{\ell}>0$ such that any solution $f$ of (10), with initial datum $f_{0} \in \mathrm{~L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d},\langle v\rangle^{\ell} d \mu\right)$ for some $\ell>0$, satisfies

$$
\|f\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d}, d \mu\right)}^{2} \leq \mathscr{K}_{\ell}(1+t)^{-\zeta}\left\|f_{0}\right\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d}, d \mu\right)}^{2} \quad \forall t \geq 0
$$

where $\zeta=\min \left\{\frac{d}{2}, \frac{\ell}{2(1-\beta)}\right\}$.
In the statement of Theorem 2, even if it is not specified, the constants may depend on norms of $f_{0}$. Assumption (21) is a simplifying assumption which can be removed in various cases: see for instance [21, 31, 16, 9]. It allows an immediate conservation of moments along the flow, see Lemma 3 below.

| Potential | $\phi=0$ | $\phi(x)=\frac{1}{\alpha}\langle x\rangle^{\alpha}$ <br> $\alpha \in(0,1)$ | $\phi(x)=\frac{1}{\alpha}\langle x\rangle^{\alpha}$ <br> $\alpha \geq 1$ |
| :---: | :---: | :---: | :---: |
| $\psi(v)=\frac{1}{\beta}\langle v\rangle^{\beta}$ <br> $\beta \geq 1$ <br> Micro Poincaré | $t^{-d / 2}$ | decay | $t^{-\frac{k}{2(1-\alpha)}}$ <br> convergence |
| $\psi(v)=\frac{1}{\beta}\langle v\rangle^{\beta}$ <br> $\beta \in(0,1)$ | $t^{-\min \left\{\frac{d}{2}, \frac{\ell}{2(1-\beta)}\right\}}$ <br> convergence | $e^{-\lambda t}$ <br> convergence |  |
| $t^{-\min \left\{\frac{k}{2(1-\alpha)}, \frac{\ell}{2(1-\beta)}\right\}}$ | $t^{-\frac{k}{2(1-\beta)}}$ <br> convergence | convergence |  |

Table 3 Summary of the results of Theorem 2. See the statement for the precise meaning of the rates and the assumptions.

### 4.4 An estimate of the entropy production

Let us introduce the weighted norm defined by

$$
\|f\|_{\beta}:=\|f\|_{L^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d},\langle v\rangle^{-2(1-\beta)+} d \mu\right)}
$$

where $(1-\beta)_{+}$denotes the positive part of $1-\beta$. As a consequence $\|f\|_{2}$ denotes the standard norm with no weight and we keep using the notation $\langle\cdot, \cdot\rangle$ for the associated scalar product. We can rephrase the Poincaré inequality (14) corresponding to the case $\beta \geq 1$, and the weighted Poincaré inequality (18) rewritten in the variable $v$ with $\beta \in(0,1)$ instead of $\alpha$ and $\lambda_{m}=\mathscr{C}_{\beta}$, as

$$
-\langle\mathrm{L} f, f\rangle \geq \lambda_{m}\|(1-\Pi) f\|_{\beta}^{2}
$$

In the language of Theorem 1, this inequality replaces $(\mathrm{H} 1)$ while $(\mathrm{H} 3)$ is still satified. Next we use the notation of Section 2 for $A, H$ and $D$, with $T$ and $L$ given respectively by (8) and (9).

Lemma 1 For any $\beta>0$, there is a positive constant $\kappa$ such that

$$
\begin{equation*}
\mathrm{D}[f] \geq \kappa\left(\|(1-\Pi) f\|_{\beta}^{2}+\langle А Т \Pi f, \Pi f\rangle\right) \tag{22}
\end{equation*}
$$

Proof We recall that by (4), D is defined as

$$
\mathrm{D}[f]:=-\langle\mathrm{L} f, f\rangle+\delta\langle\operatorname{AT} \Pi f, f\rangle-\delta(\operatorname{Re}\langle\operatorname{TA} f, f\rangle-\operatorname{Re}\langle\operatorname{AT}(1-\Pi) f, f\rangle+\operatorname{Re}\langle\operatorname{AL} f, f\rangle) .
$$

In order to prove Lemma 1, we have to give estimates on the last three terms using $\|(1-\Pi) f\|_{\beta}$ and $\langle\operatorname{AT\Pi } \Pi, \Pi f\rangle$. We obtain these estimates in four steps, as follows.
Step 1. Expressions of $\langle\operatorname{AT} \Pi f, \Pi f\rangle$. We consider the function $u=u(x)$ implicitly defined by $u f_{\star}=(1+$ $\left.(T \Pi)^{*}(T \Pi)\right)^{-1} \Pi f$, that is,

$$
\begin{equation*}
u-\frac{\sigma}{\rho_{\star}} \nabla_{x} \cdot\left(\rho_{\star} \nabla_{x} u\right)=\frac{\rho_{f}}{\rho_{\star}} . \tag{23}
\end{equation*}
$$

We deduce from

$$
\operatorname{AT\Pi } f=\left(1+(\mathrm{T} \Pi)^{*}(\mathrm{~T} \Pi)\right)(\mathrm{T} \Pi)^{*}(\mathrm{~T} \Pi) f=\Pi f-\left(1+(\mathrm{T} \Pi)^{*}(\mathrm{~T} \Pi)\right)^{-1} f=\Pi f-u f_{\star}=\left(\frac{\rho_{f}}{\rho_{\star}}-u\right) f_{\star}
$$

and (23) that

$$
\langle\boldsymbol{A} \Pi f, \Pi f\rangle=-\sigma \int_{\mathbb{R}^{d}}\left(\nabla_{x} \cdot\left(\rho_{\star} \nabla_{x} u\right)\right) \rho_{f} d x=-\sigma \int_{\mathbb{R}^{d}} \nabla_{x} \cdot\left(\rho_{\star} \nabla_{x} u\right)\left(u-\frac{\sigma}{\rho_{\star}} \nabla_{x} \cdot\left(\rho_{\star} \nabla_{x} u\right)\right) d x,
$$

that is,

$$
\begin{equation*}
\langle\operatorname{AT} \Pi f, \Pi f\rangle=\sigma \int_{\mathbb{R}^{d}}\left|\nabla_{x} u\right|^{2} \rho_{\star} d x+\sigma^{2} \int_{\mathbb{R}^{d}}\left|\nabla_{x} \cdot\left(\rho_{\star} \nabla_{x} u\right)\right|^{2} \rho_{\star}^{-1} d x . \tag{24}
\end{equation*}
$$

Testing (23) with $u \rho_{\star}$, we learn after an integration by parts that

$$
\int_{\mathbb{R}^{d}}|u|^{2} \rho_{\star} d x+\sigma \int_{\mathbb{R}^{d}}|\nabla u|^{2} \rho_{\star} d x=\int_{\mathbb{R}^{d}} u \rho_{f} d x \leq\left(\int_{\mathbb{R}^{d}}|u|^{2} \rho_{\star} d x\right)^{1 / 2}\|\Pi f\|
$$

where the inequality arises from a Cauchy-Schwarz estimate using $\|\Pi f\|^{2}=\int_{\mathbb{R}^{d}}\left|\rho_{f}\right|^{2} \rho_{\star}^{-1} d x$. Hence

$$
\begin{equation*}
\int_{\mathbb{R}^{d}}|u|^{2} \rho_{\star} d x \leq\|\Pi f\|^{2} \quad \text { and } \quad \sigma \int_{\mathbb{R}^{d}}|\nabla u|^{2} \rho_{\star} d x \leq\|\Pi f\|^{2} . \tag{25}
\end{equation*}
$$

Step 2. An estimate of $|\langle T A f, f\rangle|$. We know from (3a) that $|\langle T A f, f\rangle| \leq\|(1-\Pi) f\|_{2}^{2}$ if $\beta \geq 1$. With $\sigma$ defined by (16), we claim that

$$
\begin{equation*}
|\operatorname{Re}\langle\operatorname{TA} f, f\rangle| \leq \frac{1}{\sigma}\|(1-\Pi) f\|_{\beta}^{2} \tag{26}
\end{equation*}
$$

also holds if $\beta \in(0,1)$. In this later case, let us consider the function $w=w(x)$ implicitly defined by $w f_{\star}=\mathrm{A} f$, that is, the solution of

$$
w-\frac{\sigma}{\rho_{\star}} \nabla_{x} \cdot\left(\rho_{\star} \nabla_{x} w\right)=-\frac{1}{\rho_{\star}} \nabla_{x} \cdot \int_{\mathbb{R}^{d}} v\langle v\rangle^{\beta-2} f d v .
$$

Testing with $w \rho_{\star}$ we obtain

$$
\sigma \int_{\mathbb{R}^{d}}\left|\nabla_{x} w\right|^{2} \rho_{\star} d x \leq \int_{\mathbb{R}^{d}}|w|^{2} \rho_{\star} d x+\sigma \int_{\mathbb{R}^{d}}\left|\nabla_{x} w\right|^{2} \rho_{\star} d x=\int_{\mathbb{R}^{d}} \nabla_{x} w \cdot\left(\int_{\mathbb{R}^{d}} v\langle v\rangle^{\beta-2} f d v\right) d x .
$$

By applying the Cauchy-Schwarz inequality and after squaring, we obtain

$$
\sigma^{2} \int_{\mathbb{R}^{d}}\left|\nabla_{x} w\right|^{2} \rho_{\star} d x \leq \int_{\mathbb{R}^{d}}\left(\int_{\mathbb{R}^{d}} v\langle v\rangle^{\beta-2}(1-\Pi) f d v\right)^{2} \rho_{\star}^{-1} d x \leq\|(1-\Pi) f\|_{\beta}^{2}
$$

using $|v| /\langle\nu\rangle \leq 1$ so that $\int_{\mathbb{R}^{d}}|\nu|^{2}\langle\nu\rangle^{-2} e^{-\psi} d v / \int_{\mathbb{R}^{d}} e^{-\psi} d v \leq 1$. Altogether, we prove (26) with

$$
\left\|\mathrm{TA} f\langle v\rangle^{(1-\beta)_{+}}\right\|_{2}^{2}=\left\|\mathrm{T}\left(w f_{\star}\right)\langle v\rangle^{(1-\beta)_{+}}\right\|_{2}^{2}=\left.\iint_{\mathbb{R}^{d} \times \mathbb{R}^{d}} \frac{v}{\langle v\rangle} \cdot \nabla_{x} w\right|^{2}\langle v\rangle^{2(\beta-1)_{+}} f_{\star} d x d v \leq \frac{1}{\sigma^{2}}\|(1-\Pi) f\|_{\beta}^{2}
$$

Step 3. We claim that, for some explicit constant $C_{\beta}>0$,

$$
\begin{equation*}
|\operatorname{Re}\langle\operatorname{AL}(1-\Pi) f, f\rangle| \leq \frac{C_{\beta}}{\sigma}\|(1-\Pi) f\|_{\beta}\langle\operatorname{AT} \Pi f, \Pi f\rangle \tag{27}
\end{equation*}
$$

This follows from a direct computation. Consider $u=u(x)$ defined by (23) and observe that $\mathrm{A}^{*} \Pi f=\mathrm{T}\left(u f_{\star}\right)$. Then $\langle\operatorname{AL}(1-\Pi) f, \Pi f\rangle=\left\langle(1-\Pi) f, \operatorname{LT}\left(u f_{\star}\right)\right\rangle$. Since

$$
\operatorname{LT}\left(u f_{\star}\right)=\mathrm{L}\left(\langle v\rangle^{\beta-2} v \cdot \nabla_{x} u f_{\star}\right)=\left(\xi(v) \cdot \nabla_{x} u\right) f_{\star}
$$

where $\xi(v):=\nabla_{v} \cdot \operatorname{Hess}_{v}(\psi)-\nabla_{v} \psi \cdot \operatorname{Hess}_{v}(\psi)$ is a vector valued function of $v$, it follows that

$$
\left\|\operatorname{LT}\left(u f_{\star}\right)\langle v\rangle^{(1-\beta)_{+}}\right\|_{2}^{2} \leq C_{\beta} \int_{\mathbb{R}^{d}}\left|\nabla_{x} u\right|^{2} \rho_{\star} d x \quad \text { with } \quad C_{\beta}=\int_{\mathbb{R}^{d}} \frac{|\xi(v)|^{2}\langle v\rangle^{2(1-\beta)_{+}} e^{-\psi}}{\int_{\mathbb{R}^{d}} e^{-\psi} d v} d v
$$

Then (27) follows from (24).
Step 4. We claim that, for some explicit constant $C>0$,

$$
\begin{equation*}
|\langle\mathrm{AT}(1-\Pi) f, \Pi f\rangle| \leq C\|(1-\Pi) f\|_{\beta}\langle\mathrm{AT} \Pi f, \Pi f\rangle^{1 / 2} \tag{28}
\end{equation*}
$$

With $u=u(x)$ defined by (23), we have (AT) ${ }^{*} \Pi f=-\mathrm{T}^{2}\left(u f_{\star}\right)$ and

$$
\langle\mathrm{AT}(1-\Pi) f, \Pi f\rangle=\left\langle(1-\Pi) f,-\mathrm{T}^{2}\left(u f_{\star}\right)\right\rangle .
$$

Using the expression (8) for T , a computation yields

$$
\mathrm{T}^{2}\left(u f_{\star}\right)=\left(\nabla_{\nu} \psi \cdot \operatorname{Hess}_{x}(u) \cdot \nabla_{v} \psi-\nabla_{x} u \cdot \operatorname{Hess}_{v}(\psi) \cdot \nabla_{x} \phi\right) f_{\star}
$$

Adding and subtracting $\left(\nabla_{v} \psi \cdot \nabla_{x} u\right)\left(\nabla_{v} \psi \cdot \nabla_{x} \phi\right)$, we can rewrite

$$
\mathrm{T}^{2}\left(u f_{\star}\right)=\nabla_{v} \psi \cdot\left(\operatorname{Hess}(u)-\nabla_{x} u \otimes \nabla_{x} \phi\right) \cdot \nabla_{v} \psi f_{\star}-\nabla_{x} u \cdot\left(\operatorname{Hess}(\psi)-\nabla_{v} \psi \otimes \nabla_{v} \psi\right) \cdot \nabla_{x} \phi f_{\star}
$$

where $\nabla_{x} u \otimes \nabla_{x} \phi$ and $\nabla_{v} \psi \otimes \nabla_{v} \psi$ are respectively the matrices with entries $\left(\partial_{x_{i}} u \partial_{x_{j}} \phi\right)_{i, j}$ and $\left(\partial_{v_{i}} \psi \partial_{v_{j}} \psi\right)_{i, j}$. We estimate independently the two terms in the expression of $\mathrm{T}^{2}\left(u f_{\star}\right)$.
(1) The second term is estimated by

$$
\begin{aligned}
\| \nabla_{x} u \cdot\left(\operatorname{Hess}(\psi)-\nabla_{\nu} \psi \otimes \nabla_{v} \psi\right) & \cdot \nabla_{x} \phi f_{\star}\langle v\rangle^{(1-\beta)_{+}} \|_{2}^{2} \\
& \leq \iint_{\mathbb{R}^{d} \times \mathbb{R}^{d}}\left|\nabla_{x} u\right|^{2}\left|\operatorname{Hess}(\psi)-\nabla_{v} \psi \otimes \nabla_{v} \psi\right|^{2}\left|\nabla_{x} \phi\right|^{2}\langle v\rangle^{2(1-\beta)_{+}} f_{\star} d x d v \\
& \leq C_{\beta, 2} \int_{\mathbb{R}^{d}}\left|\nabla_{x} u\right|^{2}\left|\nabla_{x} \phi\right|^{2} \rho_{\star} d x
\end{aligned}
$$

where $C_{\beta, 2}=\int_{\mathbb{R}^{d}}\left|\operatorname{Hess}(\psi)-\nabla_{v} \psi \otimes \nabla_{v} \psi\right|^{2}\langle v\rangle^{2(1-\beta)_{+}} e^{-\psi} d v / \int_{\mathbb{R}^{d}} e^{-\psi} d v$. Using the fact that $\left|\nabla_{x} \phi\right|^{2}$ is bounded for $\alpha \in(0,1)$ and [21, Lemma 8] if $\alpha \geq 1$, there is some constant $c_{\alpha}>0$ such that the solution of (23) satisfies

$$
\begin{equation*}
\int_{\mathbb{R}^{d}}\left|\nabla_{x} u\right|^{2}\left|\nabla_{x} \phi\right|^{2} \rho_{\star} d x \leq c_{\alpha} \int_{\mathbb{R}^{d}}\left|\nabla_{x} u\right|^{2} \rho_{\star} d x \tag{29}
\end{equation*}
$$

which, after using (24), is enough to obtain the bound

$$
\left\|\nabla_{x} u \cdot\left(\operatorname{Hess}(\psi)-\nabla_{v} \psi \otimes \nabla_{v} \psi\right) \cdot \nabla_{x} \phi f_{\star}\langle v\rangle^{(1-\beta)_{+}}\right\|_{2}^{2} \leq \frac{c_{\alpha} C_{\beta, 2}}{\sigma}\|(1-\Pi) f\|_{\beta}\langle\operatorname{AT} \Pi f, \Pi f\rangle^{1 / 2}
$$

(2) For the first term, we have

$$
\begin{aligned}
\| \nabla_{\nu} \psi \cdot\left(\operatorname{Hess}(u)-\nabla_{x} u \otimes \nabla_{x} \phi\right) & \cdot \nabla_{v} \psi f_{\star}\langle v\rangle^{(1-\beta)_{+}} \|_{2}^{2} \\
& \leq \iint_{\mathbb{R}^{d} \times \mathbb{R}^{d}}\left|\nabla_{v} \psi\right|^{4}\left|\operatorname{Hess}(u)-\nabla_{x} u \otimes \nabla_{x} \phi\right|^{2}\langle v\rangle^{2(1-\beta)_{+}} f_{\star} d x d v \\
& \leq C_{\beta, 3} \int_{\mathbb{R}^{d}}\left|\operatorname{Hess}(u)-\nabla_{x} u \otimes \nabla_{x} \phi\right|^{2} \rho_{\star} d x
\end{aligned}
$$

where $C_{\beta, 3}=\int_{\mathbb{R}^{d}}\left|\nabla_{v} \psi\right|^{4}\langle v\rangle^{2(1-\beta)_{+}} e^{-\psi} d v / \int_{\mathbb{R}^{d}} e^{-\psi} d v$. Notice that $\operatorname{Hess}(u)-\nabla_{x} u \otimes \nabla_{x} \phi$ is the matrix with entries $\partial_{x_{i} x_{j}} u-\partial_{x_{i}} u \partial_{x_{j}} \phi=\partial_{x_{i}}\left(\rho_{\star} \partial_{x_{j}} u\right) \rho_{\star}^{-1}$ for $i, j=1, \ldots, d$. Hence

$$
\begin{align*}
\int_{\mathbb{R}^{d}} \mid & \operatorname{Hess}(u)-\left.\nabla_{x} u \otimes \nabla_{x} \phi\right|^{2} \rho_{\star} d x=\sum_{i, j=1}^{d} \int_{\mathbb{R}^{d}}\left(\partial_{x_{i}}\left(\rho_{\star} \partial_{x_{j}} u\right)\right)^{2} \rho_{\star}^{-1} d x \\
& =\int_{\mathbb{R}^{d}}\left|\nabla_{x} \cdot\left(\rho_{\star} \nabla_{x} u\right)\right|^{2} \rho_{\star}^{-1} d x+\int_{\mathbb{R}^{d}}\left|\nabla_{x} u\right|^{2} \Delta_{x} \phi \rho_{\star} d x-\int_{\mathbb{R}^{d}} \operatorname{Hess}(\phi): \nabla_{x} u \otimes \nabla_{x} u \rho_{\star} d x . \tag{30}
\end{align*}
$$

To prove (30), it is indeed enough to notice that

$$
\int_{\mathbb{R}^{d}}\left(\partial_{x_{i}}\left(\rho_{\star} \partial_{x_{j}} u\right)\right)^{2} \rho_{\star}^{-1} d x=-\int_{\mathbb{R}^{d}} \partial_{x_{i}} \phi \partial_{x_{j}} u\left(\partial_{x_{i}}\left(\rho_{\star} \partial_{x_{j}} u\right)\right) d x+\int_{\mathbb{R}^{d}} \partial_{x_{i} x_{j}}^{2} u\left(\partial_{x_{i}} u\left(\rho_{\star} \partial_{x_{j}} u\right)\right) d x
$$

By integrating by parts, the two integrals are

$$
\begin{aligned}
\int_{\mathbb{R}^{d}} \partial_{x_{i} x_{j}}^{2} u\left(\partial_{x_{i}} u\left(\rho_{\star} \partial_{x_{j}} u\right)\right) d x & =\int_{\mathbb{R}^{d}} \partial_{x_{i} x_{i}}^{2} u\left(\partial_{x_{j}} u\left(\rho_{\star} \partial_{x_{j}} u\right)\right) d x \\
-\int_{\mathbb{R}^{d}} \partial_{x_{i}} \phi \partial_{x_{j}} u\left(\partial_{x_{i}}\left(\rho_{\star} \partial_{x_{j}} u\right)\right) d x & =\int_{\mathbb{R}^{d}} \partial_{x_{i} x_{i}}^{2} \phi \partial_{x_{j}} u\left(\rho_{\star} \partial_{x_{j}} u\right) d x+\int_{\mathbb{R}^{d}} \partial_{x_{i}} \phi \partial_{x_{i} x_{j}}^{2} u\left(\rho_{\star} \partial_{x_{j}} u\right) d x \\
& =\int_{\mathbb{R}^{d}} \partial_{x_{i} x_{i}}^{2} \phi \partial_{x_{j}} u\left(\rho_{\star} \partial_{x_{j}} u\right) d x-\int_{\mathbb{R}^{d}} \partial_{x_{i}} \phi \partial_{x_{i}} u \partial_{x_{j}}\left(\rho_{\star} \partial_{x_{j}} u\right) d x \\
& -\int_{\mathbb{R}^{d}} \partial_{x_{j} x_{i}}^{2} \phi \partial_{x_{i}} u\left(\rho_{\star} \partial_{x_{j}} u\right) d x
\end{aligned}
$$

Putting everything together, we get

$$
\begin{aligned}
\int_{\mathbb{R}^{d}}\left(\partial_{x_{i}}\left(\rho_{\star} \partial_{x_{j}} u\right)\right)^{2} \rho_{\star}^{-1} d x=\int_{\mathbb{R}^{d}} \partial_{x_{i} x_{i}}^{2} \phi\left(\partial_{x_{j}} u\right)^{2} \rho_{\star} d x & +\int_{\mathbb{R}^{d}} \partial_{x_{i}}\left(\rho_{\star} \partial_{x_{i}} u\right) \partial_{x_{j}}\left(\rho_{\star} \partial_{x_{j}} u\right) d x \\
& -\int_{\mathbb{R}^{d}} \partial_{x_{j} x_{i}}^{2} \phi \partial_{x_{i}} u \partial_{x_{j}} u \rho_{\star} d x
\end{aligned}
$$

and (30) is obtained by summing over $i$ and $j$. Finally all integrals are estimated by $\langle А Т \Pi f, \Pi f\rangle$ using (24) and the improved Poincaré inequality (29), which completes the proof of (28).
In all cases, we conclude that $\left\|T^{2}\left(u f_{\star}\right)\langle v\rangle^{(1-\beta)_{+}}\right\|_{2}^{2} \leq C\langle\operatorname{AT} \Pi f, \Pi f\rangle$ using (24), for some explicit constant $C>0$. This completes the proof of (28).

Conclusion. By (26), (27) and (28), we control $|\langle\operatorname{TA} f, f\rangle|,|\operatorname{Re}\langle\mathrm{AL}(1-\Pi) f, f\rangle|$ and $|\langle\mathrm{AT}(1-\Pi) f, \Pi f\rangle|$. A discriminant condition on $\delta$ completes the proof of Lemma 1 as in the proof of Theorem 1.

### 4.5 Moment estimates

Lemma 2 Let $u=u(x)$ be defined in terms of $f$ as in (23) and assume For any $k \geq 0$, there exists a constant $C_{k}>0$ such that

$$
\begin{equation*}
M_{k}:=\int_{\mathbb{R}^{d}}|u|^{2}\langle x\rangle^{k} \rho_{\star} d x \leq C_{k} \iint_{\mathbb{R}^{d} \times \mathbb{R}^{d}}|\Pi f|^{2}\langle x\rangle^{k} f_{\star}^{-1} d x d v . \tag{31}
\end{equation*}
$$

Proof The case $k=0$ is true from (25). By squaring equation (23) and testing with $\langle x\rangle^{k} \rho_{\star}$, we obtain

$$
\int_{\mathbb{R}^{d}} u^{2}\langle x\rangle^{k} \rho_{\star} d x+2 \sigma \int_{\mathbb{R}^{d}} \nabla_{x}\left(u\langle x\rangle^{k}\right) \cdot \nabla_{x} u \rho_{\star} d x+\sigma^{2} \int_{\mathbb{R}^{d}}\left|\nabla_{x}\left(\rho_{\star} \nabla_{x} u\right)\right|^{2} \frac{\langle x\rangle^{k}}{\rho_{\star}} d x=\int_{\mathbb{R}^{d}} \rho_{f}^{2} \frac{\langle x\rangle^{k}}{\rho_{\star}} d x .
$$

Moreover, after an integration by parts, we have

$$
\begin{aligned}
2 \sigma \int_{\mathbb{R}^{d}} \nabla_{x}\left(u\langle x\rangle^{k}\right) \cdot \nabla_{x} u \rho_{\star} d x & =2 \sigma \int_{\mathbb{R}^{d}}\left|\nabla_{x} u\right|^{2}\langle x\rangle^{k} \rho_{\star} d x-\sigma \int_{\mathbb{R}^{d}}|u|^{2}\left(\Delta_{x}\langle x\rangle^{k}-\nabla_{x}\langle x\rangle^{k} \cdot \nabla_{x} \phi\right) \rho_{\star} d x \\
& =2 \sigma \int_{\mathbb{R}^{d}}\left|\nabla_{x} u\right|^{2}\langle x\rangle^{k} \rho_{\star} d x-\sigma k(k+d-2) M_{k-2}+\sigma k(k-2) M_{k-4} \\
& +\sigma k M_{k+\alpha-2}-\sigma k M_{k+\alpha-4} .
\end{aligned}
$$

After dropping the positive terms we get

$$
M_{k} \leq \int_{\mathbb{R}^{d}} \frac{\rho_{f}^{2}}{\rho_{\star}}\langle x\rangle^{k} d x+\sigma k(k+d-2) M_{k-2}+\sigma k M_{k+\alpha-4} .
$$

Inequality (31) follows by induction and interpolation.
Under the simplifying assumption (21), we also obtain moment estimates directly for the distribution function $f$. Here there is space for improvements.
Lemma 3 Let $f=f(t, x, v)$ be a solution of (10) with transport and collision operators given respectively by (8) and (9) for some $\beta>0$ and $\alpha>0$. Assume that the initial datum $f_{0}$ satisfies the bound (21). Then for any $k>0$ and for any $\ell>0$ there exist positive constants $C_{k}$ and $C_{\ell}$ such that, for any $t \geq 0$

$$
\begin{align*}
J_{k}(t) & :=\iint_{\mathbb{R}^{d} \times \mathbb{R}^{d}}|f(t, x, v)|^{2}\langle x\rangle^{k} f_{\star}^{-1} d x d v \leq C_{k},  \tag{32}\\
K_{\ell}(t) & :=\iint_{\mathbb{R}^{d} \times \mathbb{R}^{d}}|f(t, x, v)|^{2}\langle v\rangle^{\ell} f_{\star}^{-1} d x d v \leq C_{\ell} . \tag{33}
\end{align*}
$$

Proof Since $f_{\star}$ is a stationary solution, the maximum principle yields

$$
f(t, \cdot \cdot) \leq C f_{\star} \quad \forall t \geq 0 .
$$

Therefore (32) and (33) follow by taking

$$
C_{k}=C^{2} \iint_{\mathbb{R}^{d} \times \mathbb{R}^{d}} f_{\star}\langle x\rangle^{k} d x d v \quad \text { and } \quad C_{\ell}=C^{2} \iint_{\mathbb{R}^{d} \times \mathbb{R}^{d}} f_{\star}\langle v\rangle^{\ell} d x d v .
$$

This completes the proof of Lemma 3.
Notice that, with the elementary estimates

$$
\begin{array}{lr}
2^{\frac{k}{2}-1}\left(1+r^{k}\right) \leq\langle r\rangle^{k} \leq 1+r^{k} & \text { if } \\
1+r^{k} \leq\langle r\rangle^{k} \leq 2^{\frac{k}{2}-1}\left(1+r^{k}\right) & \text { if } \quad k \geq 2,
\end{array}
$$

we have the simple moment estimate

$$
\begin{aligned}
& M_{k, \eta}:=\int_{\mathbb{R}^{d}}\langle x\rangle^{k} e^{-\frac{1}{\eta}\langle x\rangle^{\eta}} d x \leq \max \left\{1,2^{\frac{k}{2}-1}\right\}\left|\mathbb{S}^{d-1}\right| \int_{0}^{\infty} r^{d-1}\left(1+r^{k}\right) e^{-\frac{r^{\eta}}{\eta}} d r \\
&=\left\{1,2^{\frac{k}{2}-1}\right\} \frac{2 \pi^{\frac{d}{2}}}{\Gamma\left(\frac{d}{2}\right)} \eta^{\frac{d-\eta}{\eta}}\left(\Gamma\left(\frac{d}{\eta}\right)+\eta^{\frac{k}{\eta}} \Gamma\left(\frac{d+k}{\eta}\right)\right)
\end{aligned}
$$

for any $k>0$ and as a consequence, $f_{\star}$ defined by (11) with $Z=M_{0, \beta} M_{0, \alpha}$ is such that

$$
\iint_{\mathbb{R}^{d} \times \mathbb{R}^{d}}\langle x\rangle^{k} f_{\star} d x d v=\frac{M_{k, \alpha}}{M_{0, \alpha}} \quad \text { and } \quad \iint_{\mathbb{R}^{d} \times \mathbb{R}^{d}}\langle v\rangle^{\ell} f_{\star} d x d v=\frac{M_{k, \beta}}{M_{0, \beta}}
$$

### 4.6 Proof of Theorem 2

In this section we will work in the framework of Theorem 2, i.e. we will consider a solution $f=f(t, x, v)$ to the kinetic Fokker-Planck equation (10) with initial datum $0 \leq f_{0} \leq C f_{\star}$, for a certain $C>0$. As sign plays no role, up to replacing $f$ with $f-f_{\star}$ when $f_{\star}$ is integrable, we may assume that

$$
\begin{equation*}
\iint_{\mathbb{R}^{d} \times \mathbb{R}^{d}} f(t, x, v) d x d v=0 \quad \forall t \geq 0 \tag{34}
\end{equation*}
$$

We distinguish various cases depending on the values of $\beta$ and $\alpha$.

## - Case $\beta \geq 1$ and $\alpha \geq 1$

Thanks to Lemma 1, we have

$$
\mathrm{D}[f] \geq \kappa\left(\|(1-\Pi) f\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d}, d \mu\right)}^{2}+\langle\mathrm{A} \Pi f, \Pi f\rangle\right)
$$

for some $\kappa>0$. Because of the assumption $\alpha \geq 1$ the operator $(\mathrm{T})^{*}(\mathrm{~T} \Pi)$ is coercive, that is $(\mathrm{H} 2)$ hold. As a consequence we also have (5), i.e.,

$$
\langle\operatorname{AT} \Pi f, \Pi f\rangle \geq \frac{\lambda_{M}}{1+\lambda_{M}}\|\Pi f\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d}, d \mu\right)}^{2}
$$

Therefore

$$
\mathrm{D}[f] \geq \frac{\kappa \lambda_{M}}{1+\lambda_{M}}\|f\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d}, d \mu\right)}^{2}
$$

holds for some $\kappa>0$, which gives exponential convergence:

$$
\|f(t, \cdot, \cdot)\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d}, d \mu\right)}^{2} \leq \frac{4}{2-\delta} \mathrm{H}[f(t, \cdot, \cdot)] \leq \frac{4}{2-\delta} \mathrm{H}\left[f_{0}\right] e^{-\lambda t} \quad \text { where } \quad \lambda=\frac{\kappa \lambda_{M}}{1+\lambda_{M}}
$$

Exactly the same proof applies in the case of Corollary 1, with $\lambda_{M}$ now given by the Poincare inequality associated with the measure $e^{-\phi} d x$, of which the case $\phi(x)=\frac{1}{\alpha}\langle x\rangle^{\alpha}$ with $\alpha \geq 1$ is a special case.

## - Case $\beta \in(0,1)$ and $\alpha \geq 1$

In this case, on the one hand we still have macroscopic coercivity (H2) due to the fact that $\alpha \geq 1$, but on the other hand, a loss of weight now appears for the microscopic component because of $\beta \in(0,1)$. Inequality (22) now reads as

$$
\mathrm{D}[f] \geq \kappa\left(\|(1-\Pi) f\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d},\langle v\rangle^{-2(1-\beta)} d \mu\right)}^{2}+\frac{\lambda_{M}}{1+\lambda_{M}}\|f\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d}, d \mu\right)}^{2}\right)
$$

In order to recover the $L^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d}, d \mu\right)$ norm we need to interpolate with the conservation of moments. Let $\ell>0$ and notice that $f_{0} \in \mathrm{~L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d},\langle v\rangle^{\ell} d \mu\right)$ by our assumption on the initial datum (21). Setting $a=\ell /(\ell+2(1-\beta))$, by Hölder's inequality and Lemma 3, we have

$$
\begin{aligned}
\|(1-\Pi) f\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d}, d \mu\right)}^{2} & \leq\|(1-\Pi) f\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d},\langle v\rangle^{-2(1-\beta)} d \mu\right)}^{2 a}\|(1-\Pi) f\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d},\langle v\rangle^{\ell} d \mu\right)}^{2(1-a)} \\
& \leq\|(1-\Pi) f\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d},\langle v\rangle^{-2(1-\beta)} d \mu\right)}^{2 a} K_{\ell}(t)^{1-a} \\
& \leq C_{\ell}^{1-a}\|(1-\Pi) f\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d},\langle v\rangle^{-2(1-\beta)} d \mu\right)}^{2 a}
\end{aligned}
$$

As a consequence, for a certain constant $C>0$ we have

$$
\mathrm{D}[f] \geq C\left(\|(1-\Pi) f\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d}, d \mu\right)}^{2\left(1+\frac{2(1-\beta)}{\ell}\right)}+\|\Pi f\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d}, d \mu\right)}^{2}\right) \geq C\|f\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d}, d \mu\right)}^{2\left(1+\frac{2(1-\beta)}{\ell}\right)}
$$

By the Bihari-LaSalle estimate, we finally have

$$
\mathrm{H}[f] \leq \mathrm{H}\left[f_{0}\right]\left(1+C \mathrm{H}\left[f_{0}\right]^{\frac{2(1-\beta)}{\ell}} t\right)^{-\frac{\ell}{2(1-\beta)}} .
$$

## - Case $\beta \geq 1$ and $\alpha \in(0,1)$

In this case we have the symmetrical situation compared to the previous one. The dissipation of entropy is

$$
\mathrm{D}[f] \geq \kappa\left(\|(1-\Pi) f\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d}, d \mu\right)}^{2}+\langle\mathrm{AT} \Pi f, \Pi f\rangle\right)
$$

where now $\langle\operatorname{AT} \Pi f, \Pi f\rangle$ does not produce macroscopic coercivity, but is given in terms of $u$ by (24). Fix $k>0$ and assume that $f_{0} \in \mathrm{~L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d},\langle x\rangle^{k} d \mu\right)$, then from Lemma 2 and 3 , we have that the moments $M_{k}(t)=\int_{\mathbb{R}^{d}}|u|^{2}\langle x\rangle^{k} \rho_{\star} d x$ are uniformly bounded in time. With $b=k /(k+2(1-\alpha)) \in(0,1)$, using Hölder's inequality and the weighted Poincaré inequality with non-classical average of [9, Cor. 10], we obtain

$$
\begin{aligned}
\|\Pi f\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d}, d \mu\right)}^{2} & =\int_{\mathbb{R}^{d}}|u|^{2} \rho_{\star} d x+2 \sigma \int_{\mathbb{R}^{d}}\left|\nabla_{x} u\right|^{2} \rho_{\star} d x+\sigma^{2} \int_{\mathbb{R}^{d}}\left|\nabla_{x} \cdot\left(\rho_{\star} \nabla_{x} u\right)\right|^{2} \rho_{\star} d x \\
& \leq\left(\int_{\mathbb{R}^{d}}|u|^{2}\langle x\rangle^{-2(1-\alpha)} \rho_{\star} d x\right)^{b}\left(\int_{\mathbb{R}^{d}}|u|^{2}\langle x\rangle^{k} \rho_{\star} d x\right)^{1-b}+2\langle\mathrm{AT} \Pi f, \Pi f\rangle \\
& \leq\left(\mathscr{C}_{\alpha}^{\mathrm{wP}}\right)^{b}\left(\int_{\mathbb{R}^{d}}\left|\nabla_{x} u\right|^{2} \rho_{\star} d x\right)^{b}\left(\int_{\mathbb{R}^{d}}|u|^{2}\langle x\rangle^{k} \rho_{\star} d x\right)^{1-b}+2\langle\mathrm{AT} \Pi f, \Pi f\rangle \\
& \leq C\langle\mathrm{AT} \Pi f, \Pi f\rangle^{b}+2\langle\operatorname{AT} \Pi f, \Pi f\rangle=: \Phi(\langle\mathrm{AT} \Pi f, \Pi f\rangle)
\end{aligned}
$$

where $C$ depends on $\mathscr{C}_{\alpha}^{\text {wP }}$ and the bound on $\left\|f_{0}\right\|_{L^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d},\langle x\rangle^{k} d \mu\right)}$. In the weighted Poincaré inequality we used (34), hence $\int_{\mathbb{R}^{d}} u \rho_{\star} d x=\iint_{\mathbb{R}^{d} \times \mathbb{R}^{d}} f d x d v=0$. Now we have

$$
\begin{aligned}
\mathrm{H}[f] \leq \frac{2+\delta}{4}\|f\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d}, d \mu\right)}^{2} & \leq \frac{2+\delta}{4}\left(\|(1-\Pi) f\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d}, d \mu\right)}^{2}+\Phi(\langle\mathrm{AT} \mathrm{\Pi} f, \Pi f\rangle)\right) \\
& \leq \frac{2+\delta}{4} \Phi\left(\|(1-\Pi) f\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d}, d \mu\right)}^{2}+\langle\mathrm{AT} \Pi f, \Pi f\rangle\right) \\
& \leq \frac{2+\delta}{4} \Phi\left(\kappa^{-1} \mathrm{D}[f]\right) .
\end{aligned}
$$

Therefore the decay of $\mathrm{H}[f]$ is estimated by the decay of the solution $z(t)$ of

$$
z^{\prime}=\frac{d z}{d t}=-\kappa \Phi^{-1}\left(\frac{4 z}{2+\delta}\right), \quad z(0)=\mathrm{H}\left[f_{0}\right]
$$

In view of the expression of $\Phi$, we conclude that $z$ monotonically converges to 0 as $t \rightarrow+\infty$ and, as a consequence $z^{\prime}$ also converges to 0 . This implies that after some time $t_{0} \geq 0$, we have

$$
\Phi\left(-\kappa^{-1} z^{\prime}\right) \leq C\left(-\kappa^{-1} z^{\prime}\right)^{b}
$$

Where $C$ denotes a positive constant that may change from line to line. Altogether, we end up with the differential inequality

$$
z^{\prime} \leq-C z^{1 / b}
$$

Integrating and using $\frac{b}{1-b}=\frac{k}{2(1-\alpha)}$, we obtain that $z(t) \leq C(1+t)^{-\frac{k}{2(1-\alpha)}}$.

## - Case $\beta \in(0,1)$ and $\alpha \in(0,1)$

If $\beta \in(0,1)$ and $\alpha \in(0,1)$ we have neither microscopic coercivity nor macroscopic coercivity. The dissipation of entropy is

$$
\mathrm{D}[f] \geq \kappa\left(\|(1-\Pi) f\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d},\langle v\rangle^{-2(1-\beta)} d \mu\right)}^{2}+\langle\operatorname{AT} \Pi f, \Pi f\rangle\right)
$$

and we have to interpolate with moments in both variables $x$ and $v$. As in the previous cases, we have

$$
\|\Pi f\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d}, d \mu\right)}^{2} \leq C\langle\mathrm{AT} \Pi f, \Pi f\rangle^{b}+2\langle\mathrm{AT} \Pi f, \Pi f\rangle=\Phi(\langle\mathrm{AT} \Pi f, \Pi f\rangle)
$$

and

$$
\|(1-\Pi) f\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d}, d \mu\right)}^{2} \leq C\|(1-\Pi) f\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d},\langle v\rangle^{-2(1-\beta)} d \mu\right)}^{2 a}=: \Psi\left(\|(1-\Pi) f\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d},\langle v\rangle^{-2(1-\beta)} d \mu\right)}^{2}\right)
$$

with $a=\frac{\ell}{\ell+2(1-\beta)}$ and $b=\frac{k}{k+2(1-\alpha)}$. As above we have

$$
\begin{aligned}
\mathrm{H}[f] & \leq \frac{2+\delta}{4}\left(\Psi\left(\|(1-\Pi) f\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d},\langle v\rangle^{-2(1-\beta)} d \mu\right)}^{2}\right)+\Phi(\langle\mathrm{A} \Pi \Pi, \Pi f\rangle)\right) \\
& \leq \frac{2+\delta}{4}\left(\Psi\left(\kappa^{-1} \mathrm{D}[f]\right)+\Phi\left(\kappa^{-1} \mathrm{D}[f]\right)\right)
\end{aligned}
$$

Notice that the function $t \mapsto \Psi(t)+\Phi(t)$ is increasing, concave and $\Psi(0)+\Phi(0)=0$. Moreover we have

$$
\frac{d}{d t} \mathrm{H}[f(t, \cdot, \cdot)] \leq-\kappa(\Psi+\Phi)^{-1}\left(\frac{4}{2+\delta} \mathrm{H}[f(t, \cdot, \cdot)]\right) .
$$

As a consequence, $\mathrm{H}[f(t, \cdot, \cdot)]$ can be estimated by the solution $z$ of

$$
z^{\prime}=-\kappa(\Psi+\Phi)^{-1}\left(\frac{4 z}{2+\delta}\right)
$$

For the same reasons as before, $z^{\prime}$ converges to 0 as $t \rightarrow+\infty$. Using the explicit expressions of $\Phi$ and $\Psi$, we see that there exists some $t_{0} \geq 0$ such that, for any $t \geq t_{0}$,

$$
(\Psi+\Phi)\left(-\kappa^{-1} z^{\prime}\right) \leq C\left(-\kappa^{-1} z^{\prime}\right)^{\zeta}
$$

for some $C>0$, where $\zeta=\min \{a, b\}$. This inequality leads to $z^{\prime} \leq-C z^{1 / \zeta}$ and therefore to

$$
z(t) \leq C(1+t)^{-\min \left\{\frac{k}{2(1-\alpha)}, \frac{\ell}{2(1-\beta)}\right\} \quad \forall t \geq 0}
$$

by the Bihari-LaSalle estimate.

- Case $\beta \geq 1$ and $\phi=0$

In absence of a global equilibrium, we can still consider (22) written with $\rho_{\star}=1$. Identity (24) now reads as

$$
\langle А Т \Pi f, \Pi f\rangle=\sigma \int_{\mathbb{R}^{d}}\left|\nabla_{x} u\right|^{2} d x+\sigma^{2} \int_{\mathbb{R}^{d}}\left|\Delta_{x} u\right|^{2} d x
$$

Because of Nash's inequality and the conservation of mass, we have

$$
\begin{aligned}
\|\Pi f\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d}, d \mu\right)}^{2} & =\|u\|_{\mathrm{L}^{2}(d x)}^{2}+2 \sigma\left\|\nabla_{x} u\right\|_{\mathrm{L}^{2}(d x)}^{2}+\sigma^{2}\left\|\Delta_{x} u\right\|_{\mathrm{L}^{2}(d x)}^{2} \\
& \leq C_{N a s h}\|u\|_{\mathrm{L}^{1}(d x)}^{\frac{4}{d+2}}\left\|\nabla_{x} u\right\|_{\mathrm{L}^{2}(d x)}^{\frac{2 d}{d+2}}+2\langle\mathrm{AT} \Pi f, \Pi f\rangle \\
& \leq C\langle\mathrm{AT} \Pi f, \Pi f\rangle \frac{d}{d+2}+2\langle\mathrm{AT} \Pi f, \Pi f\rangle
\end{aligned}
$$

In the asymptotic regime of small $\|\Pi f\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d}, d \mu\right)}^{2}$, we have

$$
\langle А Т \Pi f, \Pi f\rangle \geq C\|\Pi f\|^{2\left(1+\frac{2}{d}\right)}
$$

for some suitable constant $C>0$, and

$$
\mathrm{D}[f] \geq C\left(\|(1-\Pi) f\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d}, d \mu\right)}^{2}+\|\Pi f\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d}, d \mu\right)}^{2\left(1+\frac{2}{d}\right)}\right) \geq C\|f\|^{2\left(1+\frac{2}{d}\right)}
$$

By the Bihari-LaSalle estimate, we can finally conclude

$$
\mathrm{H}[f(t, \cdot, \cdot)] \leq \mathrm{H}\left[f_{0}\right]\left(1+C \mathrm{H}\left[f_{0}\right]^{\frac{2}{d}} t\right)^{-\frac{d}{2}} \forall t \geq 0
$$

- Case $\beta \in(0,1)$ and $\phi=0$

We proceed as in the previous case. The macroscopic part obeys the same estimate

$$
\langle А Т \Pi f, \Pi f\rangle \gtrsim C\|\Pi f\|^{2\left(1+\frac{2}{d}\right)} .
$$

The microscopic component has to be interpolated with moments:

$$
\|(1-\Pi) f\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d}, d \mu\right)}^{2} \leq C\|(1-\Pi) f\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d},\langle v\rangle^{-2(1-\beta)} d \mu\right)}^{2 b}
$$

We conclude that, as $\|f\|_{L^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d}, d \mu\right)} \rightarrow 0$,

$$
\mathrm{D}[f] \geq C\left(\|(1-\Pi) f\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d}, d \mu\right)}^{2\left(1+\frac{2(1-\beta)}{k}\right)}+\|\Pi f\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d}, d \mu\right)}^{2\left(1+\frac{2}{d}\right)}\right) \geq C\|f\|_{\mathrm{L}^{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d}, d \mu\right)}^{2\left(1+\frac{1}{\zeta}\right)}
$$

where $\zeta=\min \left\{\frac{k}{2(1-\beta)}, \frac{d}{2}\right\}$. By the Bihari-LaSalle estimate we conclude

$$
\mathrm{H}[f] \leq \mathrm{H}\left[f_{0}\right]\left(1+C \mathrm{H}\left[f_{0}\right]^{\frac{1}{\zeta}} t\right)^{-\zeta}
$$

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