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# CONVERGENCE OF MESSAGE PASSING GRAPH NEURAL NETWORKS WITH GENERIC AGGREGATION ON LARGE RANDOM GRAPHS

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ABSTRACT. We study the convergence of message passing graph neural networks on random graph models to their continuous counterpart as the number of nodes tends to infinity. Until now, this convergence was only known for architectures with aggregation functions in the form of normalized means, or, equivalently, of an application of classical operators like the adjacency matrix or the graph Laplacian. We extend such results to a large class of aggregation functions, that encompasses all classically used message passing graph neural networks, such as attention-based message passing, max convolutional message passing, (degree-normalized) convolutional message passing, or moment-based aggregation message passing. Under mild assumptions, we give non-asymptotic bounds with high probability to quantify this convergence. Our main result is based on the McDiarmid inequality. Interestingly, this result does not apply to the case where the aggregation is a coordinate-wise maximum. We treat this case separately and obtain a different convergence rate.

## 1. Introduction

Graph Neural Networks (GNNs) [Scarselli et al., 2009, Gori et al., 2005] are deep learning architectures largely inspired by Convolutional Neural Networks, that aim to extend convolutional methods to signals on graphs. Indeed, in many domains the measured data live on a graph structure: examples for which GNNs have achieved state-of-the-art performance include molecules, proteins and node clustering [Gilmer et al., 2017, Chen et al., 2019, Fout et al., 2017]. Nevertheless, it has been observed that GNNs have limitations, both in practice [Wu et al., 2019, Hu et al., 2020] and in their theoretical understanding [Morris et al., 2024]. Hence, the design of more reliable and powerful architectures is a current active and fast evolving area of research.

From a theoretical perspective, a large part of the literature has focused on the *expressive power* of GNNs, i.e., what class of functions can GNNs approximate. This notion is fundamental in classical Deep Learning and is related to the so-called *Universal Approximation Theorem* [Kurt and Hornik, 1991, Cybenko, 1989].

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Studying the expressive power of GNNs is however more involved, as they are by definition designed to be invariant or equivariant to the relabelling of nodes in a graph (see Sec. 3). Hence, in Xu et al. [2019] the authors relate their expressivity to the *graph isomorphism problem*, that is, deciding if two graphs are permutation of one another, a long-standing combinatorial problem in graph theory. The main avenue to analyze the expressive power of GNNs compares their performances to the traditional Weisfeiler-Lehman algorithm (WL) [Weisfeiler and Leman, 1968], which process is very similar to the message-passing paradigm at the core of GNNs. Hence, by construction, basic GNNs are at most as powerful as WL [Xu et al., 2019]. From this point, a lot of effort has been made on designing innovative GNN architectures to outperform the classical WL [Maron et al., 2019b,a, Keriven and Peyré, 2019, Vignac et al., 2020, Papp and Wattenhofer, 2022, Morris et al., 2020].

Nevertheless, while this combinatorial approach is worth considering for reasonably small graphs, its relevance in the context of large graphs is somewhat limited. Two real large graphs may share similar patterns, but will never be isomorphic, one main simple reason being that they most likely do not even share the same number of nodes. Large graphs are better described by some global properties such as edge density or number of communities. To that extent, the privileged mathematical tools are random graph models [Crane, 2018, Goldenberg et al., 2010]. A generic family of models of interest to study GNNs on large graphs is the class of Latent Position Models [Keriven et al., 2020, 2021, Ruiz et al., 2020, 2021a, Levie et al., 2021, Maskey et al., 2022]. Such random graphs first sample node latent variables randomly from a probability space  $(\mathcal{X}, P)$ , and then decides the adjacency between two nodes via the sampling of a connectivity kernel  $W : \mathcal{X}^2 \rightarrow [0, 1]$  between their associated latent variables. This encompasses models like stochastic block models [Lei and Rinaldo, 2015] (SBM) or graphon models [Lovász, 2012], depending on how exactly we define the edge appearance procedure.

The key idea in studying GNNs on large random graphs is to embed the discrete problem into a continuous setting for which we expect to understand their properties with more ease. For instance, some authors derived new properties of geometric stability on large random graphs [Keriven et al., 2020, Levie et al., 2021, Ruiz et al., 2021b], which are known to be key in other deep models [Mallat, 2012] but cannot easily be characterized on fixed deterministic graphs. Large random graphs also shed light on the expressive power of GNNs [Keriven et al., 2021] in a different manner than the discrete WL test, and some models are indeed proved to be more powerful than others [Keriven and Vaiter, 2023]. To study GNNs on large random graphs, we match the GNN to a “continuous” counterpart, referred to as a continuous-GNN (cGNN) [Keriven et al., 2020, Ruiz et al., 2021a]. While the discrete GNN propagates a signal over the nodes of the graph, the cGNN propagates *a mapping over the latent space*  $\mathcal{X}$ . Such a map can be interpreted as a signal over the graph where the “continuum” of nodes would be all the points of  $\mathcal{X}$ . Then, as the random graph grows large, the GNN must behave similarly to its cGNN counterpart. To justify this, it is necessary to describe the cGNN as a limit of GNNs on random graphs and to ensure that the GNN converges to the cGNN as the number of nodes increases [Keriven et al., 2020, Maskey et al., 2022]. This convergence problem is precisely the focus of the present work.

The duality of the convolutional product has led to two ways of defining GNNs. On the one hand, convolution as a pointwise product of frequencies in the Fourier domain has justified the design of so-called Spectral Graph Neural Networks [Defferrard et al., 2016] (SGNNs), in which one introduces a graph Fourier transform through a chosen graph shift operator [Tremblay et al., 2018] to legitimate the use of polynomial filters. On the other hand, the spatial interpretation sees the convolution as local aggregations of neighborhood information, leading to Message Passing Neural Networks (MPGNNs) [Gilmer et al., 2017, Kipf and Welling, 2017, Corso et al., 2020]. The message passing paradigm consists of iteratively updating each node via the **aggregation** of messages from each of its neighbors. This framework is often favored due to its inherent flexibility: messages and aggregation functions are unconstrained as long as they stay invariant to node reordering, i.e., as long as they match on isomorphic graphs. Besides, SGNNs layers are mostly made of polynomials of graph shift operators which are a form of message passing, defined by a choice of graph shift operator and a polynomial degree. As such, SGNNs can be seen as a subcase of the more versatile message-passing framework.

**Contributions.** In this paper, we study the convergence toward a continuous counterpart of MPGNNs with a **generic aggregation function** [Corso et al., 2020], whereas previous work [Keriven et al., 2020, 2021, Ruiz et al., 2021b, Maskey et al., 2022] are restricted to SGNNs or MPGNNs with specific aggregations. We use a simple version of the Latent Space Model where random graphs are totally connected and weighted accordingly the sampling of the kernel  $W$  at the latent positions. Our main result, Theorem 5.11, states that for MPGNNs having a Lipschitz-type regularity, the discrete network on a large random graph is close to its continuous counterpart with high probability. We quantify this convergence via a non asymptotic bound based on the McDiarmid concentration inequality for multivariate functions of independent random variables. A special treatment is given to the case where the aggregation is a coordinate-wise maximum [Fey and Lenssen, 2019]. For that particular case, Theorem 5.11 does not hold. Thus, we provide another proof of convergence based on a specific concentration inequality, in Theorem 5.17. This results in a significantly different theoretical convergence rate.

**Related work.** The closest related works to ours are the results from Keriven et al. [2020, 2021], where they establish convergence of SGNN on Latent Position random graphs. We also mention Maskey et al. [2022] that studies a particular case of MPGNN on large random graphs, where the aggregation is defined to be a mean normalized by the degree of the node. The present paper can be considered as a direct extension of both these works in the setting of MPGNNs with generic aggregation.

Further, the concept of limit of a SGNN on large random graphs has shown fruitful to tackle several problems. For instance, multiple works from different authors, among which Keriven et al. [2020], Maskey et al. [2023b], Levie et al. [2021], Ruiz et al. [2021b], Cerviño et al. [2023], have focus on stability to deformation or transferability. The idea being that, since the same GNN can be applied to any graph, no matter its size or structure, we expect the outputs to be close on similar graphs, which is particularly relevant for large random graphs drawn from the same (or almost same) model. Concerning the expressive power on large graphs, Keriven et al. [2020, 2021] exploit their convergence theorems to propose a description of

the function space that SGNNs on random graphs can approximate in Keriven and Vaiter [2023] and derive certain properties of universality. About other topics related to the learning procedure such as generalization as well as oversmoothing, the authors in Maskey et al. [2022] derive a generalization bound that gets tighter for large graphs, while the results described in Keriven [2022] make use of Latent Position random graphs to search a threshold between beneficial finite smoothing and oversmoothing.

Beyond random graphs, large (dense) graphs can be described through the theory of graphons [Lovász, 2012]. Indeed, with the so-called cut metric, the space of all graphs can be completed to obtain a compact space: the space of graphons, in which any graphon is a limit of discrete graphs. Several works aim to characterize the convergence of GNNs on large graphs with these mathematical tools. In Ruiz et al. [2020], Maskey et al. [2023a], the authors define limits of graph polynomial filters of SGNNs designed from graph shift operators as integral operators *w.r.t.*, the underlying graphon, and make use of the theory of self adjoint operators and Hilbert spaces to study them. More recently, authors in Böker et al. [2023] consider a continuous version of the WL test via graphon estimation to study expressive power and the paper Levie [2023] is devoted to extend the concept of sampling graphs from graphon to sampling graph signals from graphon signals.

Outline. In Section 2, we give some basic definitions. In Section 3 we define MPGNNs with a generic aggregation function, that is, any function on sets used to gather and combine neighborhood information in the message-passing paradigm. In Section 4 we introduce continuous-MPGNNs (cMPGNNs) which are the counterpart of discrete MPGNNs that propagate a function over a compact probability space, alongside a connectivity kernel. As a discrete MPGNN must be coherent with graph isomorphism, we give mild conditions under which the cMPGNN is coherent with respect to some notion of probability space isomorphism. In Section 5, we focus on MPGNNs when applied on random graphs and describe what class of cMPGNN would be their natural limit. Our main result is Theorem 5.11: it provides necessary conditions under which the discrete network converges to its continuous counterpart. We make use of the McDiarmid concentration inequality to derive a non asymptotic bound with high probability of the deviation between the outputs of the MPGNN and its limit cMPGNN. Overall, we conclude that a sufficient condition of convergence is for the aggregation to have sharp bounded differences. All along the paper, we illustrate our concepts on classical GNN examples from the basic Graph Convolutional Network to the more sophisticated Graph Attentional Network [Veličković et al., 2017]. We give a particular treatment to the case of the maximum aggregation. Indeed, its behavior turns out to be significantly different than the other examples and do not fit into the class of MPGNNs having sharp bounded differences. Nevertheless, in Theorem 5.17 we make use of other specific concentration bounds to prove another non asymptotic bound between max MPGNN and its limit cMPGNN, with a significantly different convergence rate.

## 2. Notations and Definitions

We start by introducing the notations that will hold throughout the paper. The letter  $d$  (and its derivatives  $d_0, d^{(0)}, \dots$ ) will represent the dimension of a real vector space, the letter  $n$  will denote the number of nodes in a graph, and  $L$  will refer

to the total number of layers in a deep architecture. Whenever we need to index something relatively to the vertices of a graph, we use a subscript indexation (e.g.,  $z_i$ ) and in the case of layers, we employ a parenthesized superscript (e.g.,  $z^{(l)}$ ).

We fix a positive integer  $d$  and  $(\mathbb{R}^d, \|\cdot\|_\infty, \mathbb{B}(\mathbb{R}^d))$  the  $d$ -dimensional real vector space endowed with the infinite norm  $\|x\|_\infty = \max_i |x_i|$  as well as its Borel sigma algebra. Except when specified differently, any topological concept, such as balls, continuity, *etc.*, will be considered relatively to the norm  $\|\cdot\|_\infty$ . All along this paper,  $\mathcal{X}$  is a compact subset of  $\mathbb{R}^d$  and  $\mathbb{B}(\mathcal{X})$  its Borel sigma algebra defined as the sigma algebra generated by the  $U \cap \mathcal{X}$ , for the open sets  $U$  of  $\mathbb{R}^d$ .

The group of permutations of  $\{1, \dots, n\}$  is denoted as  $\mathfrak{S}_n$ . If  $x = (x_1, \dots, x_n)$  is an  $n$ -tuple and  $\sigma$  an element of  $\mathfrak{S}_n$ , we define the  $n$ -tuple  $\sigma \cdot x$  as  $\sigma \cdot x = (x_{\sigma^{-1}(1)}, \dots, x_{\sigma^{-1}(n)})$ .

The set of bijections  $\phi$  of  $\mathcal{X}$  such that both  $\phi$  and  $\phi^{-1}$  are measurable is a group for the composition of functions. We call it the group of automorphisms of  $\mathcal{X}$  and denote it as  $\text{Aut}(\mathcal{X})$ . We denote as  $\mathcal{P}(\mathcal{X})$  the set of probability measures on  $(\mathcal{X}, \mathbb{B}(\mathcal{X}))$ . For a measure  $P \in \mathcal{P}(\mathcal{X})$  and a bijection  $\phi \in \text{Aut}(\mathcal{X})$ , the push forward measure of  $P$  through  $\phi$  is defined as  $\phi_{\#}P(A) = P(\phi^{-1}(A))$  for all  $A$  in  $\mathbb{B}(\mathcal{X})$ . Since this makes the group  $\text{Aut}(\mathcal{X})$  acting on the set of probability measures on  $\mathcal{X}$ , we also use the notation  $\phi \cdot P = \phi_{\#}P$ , which is standard for a (left) group action. For the same reason, we shall use the notation  $\phi \cdot f = f \circ \phi^{-1}$  and  $\phi \cdot W = W(\phi^{-1}(\cdot), \phi^{-1}(\cdot))$  whenever  $f$  is a measurable function on  $\mathcal{X}$  and  $W$  is a bivariate measurable function on  $\mathcal{X} \times \mathcal{X}$ .

For  $P \in \mathcal{P}(\mathcal{X})$ , the space  $L_P^\infty(\mathcal{X}, \mathbb{R}^p)$  is the space of essentially bounded (equivalence classes of) maps from  $\mathcal{X}$  to  $\mathbb{R}^p$  endowed with the norm  $\|f\|_{P, \infty} = \text{ess sup}_{x \in \mathcal{X}, P} \|f(x)\|_\infty$ . When there is no ambiguity on  $P$ , the norm  $\|\cdot\|_{P, \infty}$  is noted  $\|\cdot\|_\infty$ . The space  $\mathcal{C}(\mathcal{X}, \mathbb{R}^p)$  is made of the continuous functions from  $\mathcal{X}$  to  $\mathbb{R}^p$ . Since  $\mathcal{X}$  is compact, any continuous map is bounded thus essentially bounded, which makes  $\mathcal{C}(\mathcal{X}, \mathbb{R}^p)$  a subspace of  $L_P^\infty(\mathcal{X}, \mathbb{R}^p)$ .

Sets are represented between braces  $\{\cdot\}$ , whereas multisets, that is, sets in which an element is allowed to appear twice or more, are represented by double braces  $\{\!\!\{\cdot\}\!\!\}$ . We define the sampling operator the following way. If  $f : \mathcal{E}_0 \rightarrow \mathcal{E}_1$  and  $X = (x_1, \dots, x_n) \in \mathcal{E}_0^n$ :

$$(2.1) \quad S_X f = (f(x_1), \dots, f(x_n)) \in \mathcal{E}_1^n.$$

## 2.1. Graph-related definitions

In this subsection, we introduce the concepts of discrete graph, graph signal and graph isomorphism.

**Graph.** A non oriented weighted graph  $G$  with  $n$  vertices is defined by a triplet  $(V, E, w)$ , where  $V = \{v_1, \dots, v_n\}$  is a finite set called the set of vertices (or nodes) and  $E$  is the set of edges. The set of neighbors of a vertex  $v_i$  in  $G$  is referred to as  $\mathcal{N}_G(v_i)$  or simply  $\mathcal{N}(v_i)$  when the underlying graph is clear from the context. The weight function  $w$  assigns a nonnegative number to each edge. It is often represented by a symmetric function  $w : V^2 \rightarrow \mathbb{R}^+$  and the abbreviation  $w_{i,j}$  is used to denote the weight  $w(v_i, v_j) = w(v_j, v_i)$  where  $\{v_i, v_j\} \in E$ . In this paper,

“graph” will always mean “undirected and weighted graph”. The set of graphs defined on the vertex set  $V$  is denoted as  $\mathcal{G}(V)$ .

Graph signal. Given a graph  $G \in \mathcal{G}(V)$ , where  $|V| = n$ , a signal on  $G$  is a map from the set of vertices  $V$  to  $\mathbb{R}^d$  that assigns a  $d$ -dimensional vector  $z_i$  to each vertex  $v_i$ . The images from all vertices are stacked into a matrix  $Z$  of size  $n \times d$ . Abusing notations, we may not distinguish between the map and its image  $Z$ , the latter being also named the signal.

Graph isomorphism. Two graphs  $G_1 = (V, E_1, w_1)$  and  $G_2 = (V, E_2, w_2)$  in  $\mathcal{G}(V)$ , where  $|V| = n$ , are said to be isomorphic if there is a permutation  $\sigma \in \mathfrak{S}_n$  such that  $E_2 = \{\{v_i, v_j\} \mid \{v_{\sigma^{-1}(i)}, v_{\sigma^{-1}(j)}\} \in E_1\}$  and  $w_2(v_i, v_j) = w_1(v_{\sigma^{-1}(i)}, v_{\sigma^{-1}(j)})$ . In this case, we note  $G_2 = \sigma \cdot G_1$ . Moreover, if  $Z$  is a signal on  $G_1$  and  $\sigma \in \mathfrak{S}_n$ ,  $\sigma \cdot Z$  is an isomorphic signal on the graph  $\sigma \cdot G_1$ .

## 2.2. Random Graph Models

Random graph model and random graphs. A *random graph model* is a couple  $(W, P)$  where  $P$  is a Borel probability measure on the compact set  $\mathcal{X} \subset \mathbb{R}^d$  and  $W : \mathcal{X} \times \mathcal{X} \mapsto [0, 1]$  is a symmetric measurable function called *connectivity kernel*. A random graph model is used to generate random graphs as follows. Given a positive integer  $n$ , we first draw  $n$  independent and identically distributed random variables from the distribution  $P$ , represented by  $X_1, \dots, X_n$ , which form the vertex set of the graph. The random graph is then fully connected and has weight function  $W$ :

$$X_1, \dots, X_n \stackrel{iid}{\sim} P, \quad w_{i,j} = w_{j,i} = W(X_i, X_j).$$

Often,  $W$  is decreasing with the distance between the  $X_i$ , such that nodes with similar latent variables have stronger connections: classical examples include the Gaussian kernel  $W(X, X') = e^{-\frac{\|X-X'\|^2}{2\sigma^2}}$  or the so-called  $\varepsilon$ -graphs  $W(X, X') = \mathbb{1}_{\|X-X'\| \leq \varepsilon}$ . When convenient, we will use the short notation  $X = (X_1, \dots, X_n)$  for the tuple of the vertices of a random graph. We call  $\mathcal{G}_n(W, P)$  the distribution from which random graphs with  $n$  nodes are drawn. We bring the reader’s attention to the fact that in the above definition, a random graph is always fully connected *but* edges may have a weight equal to zero (e.g. for  $\varepsilon$ -graphs). Also note that, in the rest of the paper, we generally do not put any assumptions on the model  $(W, P)$ , except when using max-aggregation (Exemples 5-e and Sec. 5.2.2), where we assume that  $W$  is Lipschitz-continuous in addition to some conditions on the probability space  $(\mathcal{X}, P)$  (see Definition 5.15).

Another common model [Keriven et al., 2020, Lei and Rinaldo, 2015] is to add a Bernoulli distribution on edges, similarly to SBM models, in order to model unweighted random graphs, potentially with prescribed expected sparsity. It is not done here for the sake of simplicity. In the literature, weighted random graphs without Bernoulli edges are routinely used to analyze machine learning algorithms [Von Luxburg et al., 2008, Maskey et al., 2022], as they essentially model the underlying phenomena of interest in many cases.

Random Graph Model isomorphism. Two probability measures  $P_1$  and  $P_2$  on  $\mathcal{X}$  are said isomorphic if there is some  $\phi$  in  $\text{Aut}(\mathcal{X})$  such that  $P_2 = \phi_{\#} P_1$ . Similarly, two random graph models  $(W_1, P_1)$  and  $(W_2, P_2)$  on  $\mathcal{X}$  are said to be isomorphic if there is a  $\phi$  in  $\text{Aut}(\mathcal{X})$  such that  $(W_2, P_2) = (\phi \cdot W_1, \phi \cdot P_1)$ , in this case, we will note  $(W_2, P_2) = \phi \cdot (W_1, P_1)$ .

### 3. Message Passing Graph Neural Networks (MPGNNs)

A multilayer MPGNN iteratively propagates a signal over a graph. At each step, the current representation of every node's neighbors are gathered, transformed, and combined to update the node's representation. Broadly speaking, a MPGNN can be defined as a collection of  $L$  applications  $(F^{(l)})_{1 \leq l \leq L}$  that act as follows. Let  $G \in \mathcal{G}(V)$  be a graph with  $n$  nodes, and  $Z = Z^{(0)} \in \mathbb{R}^{n \times d_0}$  be a signal on it. At each layer, denoting  $Z^{(l)}$  as the current state of the signal,  $Z^{(l+1)}$  is computed node-wise by:

$$(3.1) \quad z_i^{(l+1)} = F^{(l+1)} \left( z_i^{(l)}, \left\{ \left( z_j^{(l)}, w_{i,j} \right) \right\}_{v_j \in \mathcal{N}(v_i)} \right) \in \mathbb{R}^{d_{l+1}}.$$

So  $Z^{(l+1)}$  is an  $n \times d_{l+1}$  matrix. In (3.1), the  $F^{(l)}$  take as arguments a vector, which is the current node's representation, and a multiset of *pairs*. Each pair is composed of a node from the neighborhood of the running node, along with the corresponding edge weight. In the literature, the  $F^{(l)}$  are often referred to as *aggregations* [Jegelka, 2022]. Their main property is to ignore the order in which the neighborhood information is collected, through the use of a multiset.

Depending on the context, the final output of the MPGNN may be a signal over the graph, or a single vector representation for the entire graph. Following the literature, we call these two versions respectively the *equivariant* and the *invariant* versions of the network. We denote  $\Theta_G(Z)$  as the output in the first case and  $\bar{\Theta}_G(Z)$  in the second case, where  $\bar{\Theta}_G$  use an additional pooling operation over the nodes,  $R : \mathbb{R}^{n \times d_L} \rightarrow \mathbb{R}^{d_L}$ , called the *readout* [Jegelka, 2022] function:

$$(3.2) \quad \Theta_G(Z) = Z^{(L)} \in \mathbb{R}^{n \times d_L}, \quad \bar{\Theta}_G(Z) = R \left( \left\{ z_1^{(L)}, \dots, z_n^{(L)} \right\} \right) \in \mathbb{R}^{d_L}$$

A fundamental property of GNNs is that they are consistent with graph isomorphism. More precisely, relabeling the nodes of the input graph signal must be the same as relabeling the nodes of the output in the *equivariant* case, and must leave the output unchanged in the *invariant* case. This exactly corresponds to the concepts of invariance and equivariance for group actions and follows naturally from the definition of MPGNNs, as stated in the following proposition.

**Proposition 3.1** (Invariance and equivariance of MPGNNs). *Let  $G \in \mathcal{G}(V)$  with  $|V| = n$ . Then,  $\Theta$  and  $\bar{\Theta}$  are respectively  $\mathfrak{S}_n$ -equivariant and  $\mathfrak{S}_n$ -invariant, in the sense that for all  $\sigma \in \mathfrak{S}_n$ , for all  $Z \in \mathbb{R}^{n \times d_0}$ , we have  $\Theta_{\sigma \cdot G}(\sigma \cdot Z) = \sigma \cdot \Theta_G(Z)$  and  $\bar{\Theta}_{\sigma \cdot G}(\sigma \cdot Z) = \bar{\Theta}_G(Z)$ .*

*Proof.* We prove the equivariant case. Let us introduce  $\Lambda_G^{(l)} : Z^{(l-1)} \mapsto Z^{(l)}$  the layer functions such that  $\Theta_G = \Lambda_G^{(L)} \circ \dots \circ \Lambda_G^{(1)}$  by construction. Let  $Z \in \mathbb{R}^{n \times d_{l-1}}$  be a signal on  $G$ .

On the one hand,  $\Lambda_{\sigma \cdot G}^{(l)}(\sigma \cdot Z) = Y$  is the signal on  $\sigma \cdot G$ , obtained from the message passing of  $\sigma \cdot Z$  with regard to the graph  $\sigma \cdot G$  and the weight function  $\sigma \cdot w$ . Locally, for all  $i$ ,  $y_i$  is the result of the message passing at the node labeled  $v_i$  in  $\sigma \cdot G$ . Recalling that the  $i$ th row of  $\sigma \cdot Z$  is  $z_{\sigma^{-1}(i)}$ , and that the  $(i, j)$ -entry of  $\sigma \cdot w$  is  $w_{\sigma^{-1}(i), \sigma^{-1}(j)}$ , we get that,



$$y_i = F^{(l)} \left( z_{\sigma^{-1}(i)}, \left\{ \left\{ (z_{\sigma^{-1}(j)}, w_{\sigma^{-1}(i), \sigma^{-1}(j)}) \right\}_{v_j \in \mathcal{N}_{\sigma \cdot G}(v_i)} \right\} \right).$$

Then, we do the change of variable  $j = \sigma(j')$  in the multiset indexing, we obtain

$$y_i = F^{(l)} \left( z_{\sigma^{-1}(i)}, \left\{ \left\{ (z_j, w_{\sigma^{-1}(i), j}) \right\}_{v_{\sigma(j)} \in \mathcal{N}_{\sigma \cdot G}(v_i)} \right\} \right).$$

Now, by definition of  $\sigma \cdot G$ , we have the equivalence  $v_{\sigma(j)} \in \mathcal{N}_{\sigma \cdot G}(v_i)$  if and only if  $v_j \in \mathcal{N}_G(v_{\sigma^{-1}(i)})$ . This implies that the multiset  $\left\{ \left\{ (z_j, w_{\sigma^{-1}(i), j}) \right\}_{v_{\sigma(j)} \in \mathcal{N}_{\sigma \cdot G}(v_i)} \right\}$  is the same as the multiset  $\left\{ \left\{ (z_j, w_{\sigma^{-1}(i), j}) \right\}_{v_j \in \mathcal{N}_G(v_{\sigma^{-1}(i)})} \right\}$ . Thus,

$$y_i = F^{(l)} \left( z_{\sigma^{-1}(i)}, \left\{ \left\{ (z_j, w_{\sigma^{-1}(i), j}) \right\}_{v_j \in \mathcal{N}_G(v_{\sigma^{-1}(i)})} \right\} \right).$$

On the other hand,  $\sigma \cdot \Lambda_G^{(l)}(Z) = Y'$  is the signal  $\Lambda_G^{(l)}(Z)$  to which the rows have been permuted a posteriori, so

$$y'_i = F^{(l)} \left( z_{\sigma^{-1}(i)}, \left\{ \left\{ (z_j, w_{\sigma^{-1}(i), j}) \right\}_{v_j \in \mathcal{N}_G(v_{\sigma^{-1}(i)})} \right\} \right).$$

Hence  $Y = Y'$ , which means that  $\Lambda_{\sigma \cdot G}^{(l)}(\sigma \cdot Z) = \sigma \cdot \Lambda_G^{(l)}(Z)$ , and that  $\Lambda^{(l)}$  is equivariant for all  $l$ . Thereby  $\Theta_{\sigma \cdot G}(\sigma \cdot Z) = \sigma \cdot \Theta_G(Z)$  by composition. For the invariant case,  $R$  is clearly  $\mathfrak{S}_n$ -invariant since it has a multiset as input. The fact that the composition of an equivariant map followed by an invariant map is invariant yields the result.  $\square$

The role of the functions  $F^{(l)}$  in (3.1) is crucial and there is a wide range of designs for them [Wu et al., 2021]. Nevertheless, they mostly take the following “message-then-combine” form. At layer  $l+1$ , the signals of the neighbors of a node are transformed by a learnable operation which is usually a classical multilayer perceptron (MLP) denoted as  $m^{(l+1)}$ . Then these *messages*  $m^{(l+1)}(z_j^{(l)})$  are *aggregated* along with some optional *weight coefficients*, whose expression are very general here:

$$(3.3) \quad c_{i,j}^{(l+1)} = c^{(l+1)} \left( z_i^{(l)}, z_j^{(l)}, w_{i,j} \right),$$

in a way that is invariant to node relabeling. It appears that a natural way of doing the aggregation step is to perform a *mean*, in a broad sense: an arithmetic mean, a weighted mean, a maximum, *etc.* Thus, we have a *mean* operator  $M^{(l+1)}$  such that (3.1) is expressed as

$$(3.4) \quad \begin{aligned} & F^{(l+1)} \left( z_i^{(l)}, \left\{ \left\{ (z_j^{(l)}, w_{i,j}) \right\}_{v_j \in \mathcal{N}(v_i)} \right\} \right) \\ &= M^{(l+1)} \left( \left\{ \left\{ (m^{(l+1)}(z_j^{(l)}), c_{i,j}^{(l+1)}) \right\}_{v_j \in \mathcal{N}(v_i)} \right\} \right) \end{aligned}$$

Up to our knowledge, (3.4) encompasses all existing popular MPGNN architectures of the literature. We note that it is essentially a more verbose reformulation of (3.1), the two different expressions mostly provide a different level of intuition on the message-passing process. In the sequel, we discuss five examples that follow (3.4).

For each example, we also give the corresponding readout function that will be used in our results, for the invariant case.

**Example 1** (Convolutional Message Passing). *The  $c_{i,j}$  are the graph weights  $w_{i,j}$  [Kipf and Welling, 2017, Defferrard et al., 2016, Gilmer et al., 2017]. Each neighbor representation is multiplied by its corresponding weight and we combine them with an arithmetic mean. Notice that this is equivalent to a Convolutional Graph Neural Network (GCN) with polynomial filters of degree one.*

$$z_i^{(l+1)} = \frac{1}{|\mathcal{N}(v_i)|} \sum_{v_j \in \mathcal{N}(v_i)} w_{i,j} m^{(l+1)}(z_j^{(l)}).$$

*In the invariant case, the readout function is an arithmetic mean:*

$$R\left(\left\{z_1^{(L)}, \dots, z_n^{(L)}\right\}\right) = \frac{1}{n} \sum_{i=1}^n z_i^{(L)}.$$

**Example 2** (Degree normalized convolution). *The  $c_{i,j}$  are still the graph weights  $w_{i,j}$  but a weighted mean is performed [Maskey et al., 2022].*

$$z_i^{(l+1)} = \sum_{j \in \mathcal{N}(v_i)} \frac{w_{i,j}}{\sum_{k \in \mathcal{N}(v_i)} w_{i,k}} m^{(l+1)}(z_j^{(l)}).$$

*In the invariant case, the readout function is again an arithmetic mean.*

**Example 3** (Attention based Message Passing). *Unlike the two examples above, the attention coefficients are learnable and depend on all the possible parameters mentioned in (3.3) [Veličković et al., 2017]. A weighted mean is then used.*

$$z_i^{(l+1)} = \sum_{j \in \mathcal{N}(v_i)} \frac{c^{(l+1)}(z_i^{(l)}, z_j^{(l)}, w_{i,j})}{\sum_{k \in \mathcal{N}(v_i)} c^{(l+1)}(z_i^{(l)}, z_k^{(l)}, w_{i,k})} m^{(l+1)}(z_j^{(l)}).$$

*In the invariant case, the readout function is again an arithmetic mean.*

**Example 4** (Generalized mean). *Similar to example 1, but with additional functions used to compute “generalized” or semi-arithmetic means [Kortvelesy et al., 2023, de Carvalho, 2016]:*

$$z_i^{(l+1)} = h \left( \frac{1}{|\mathcal{N}(v_i)|} \sum_{v_j \in \mathcal{N}(v_i)} h^{-1} \left( w_{i,j} m^{(l+1)}(z_j^{(l)}) \right) \right),$$

*for some invertible function  $h$  (possibly defined on a bounded domain). In this case, following the popular formalism from Kolmogorov and Castelnovo [1930], in order to legitimately be considered as a generalized mean, some regularity conditions are required on  $h$ , typically,  $h$  must be a strictly increasing continuous function. For instance, taking  $h^{-1} = \log(\cdot)$  (assuming positivity of the inputs) and  $h = \exp(\cdot)$  yields the geometric mean, while taking  $h^{-1} = (\cdot)^p$  and  $h = (\cdot)^{1/p}$  (again, assuming nonnegativity of the message if necessary) yields a power mean as employed in the moment-based aggregations from Corso et al. [2020] (up to centering, which we omit for simplicity).*

*In the invariant case, the readout function is again an arithmetic mean (for simplicity).*

**Example 5** (Max Convolutional Message Passing). *The aggregation maximum is often mentioned as a possibility in the literature [Hamilton et al., 2017], but we note that it is less common in practice. Here the  $c_{i,j}$  are also the graph weights  $w_{i,j}$  but a coordinate-wise maximum is used to combine the messages:*

$$z_i^{(l+1)} = \max_{v_j \in \mathcal{N}(v_i)} w_{i,j} m^{(l+1)} \left( z_j^{(l)} \right).$$

*In the invariant case, the readout function is a coordinate-wise maximum.*

$$R \left( \left\{ z_1^{(L)}, \dots, z_n^{(L)} \right\} \right) = \max_{i=1, \dots, n} z_i^{(L)}.$$

*Notice that, assuming positivity of the inputs, this aggregation is also obtained as the limit, for  $p \rightarrow \infty$  of the generalized power mean (Ex. 4) with  $h(x) = x^{1/p}$ .*

#### 4. Continuous MPGNNs (cMPGNNs) on random graph models

We define the continuous counterpart of MPGNNs, which we call continuous MPGNNs (cMPGNNs). A cMPGNN is defined to be  $L$  operators  $(\mathcal{F}^{(l)})_{1 \leq l \leq L}$  that propagate a function on  $\mathcal{X}$  relatively to a random graph model. Let  $(W, P)$  be a random graph model and  $f = f^{(0)} \in L_P^\infty(\mathcal{X}, \mathbb{R}^{d_0})$ ,  $f^{(l+1)}$  is recursively computed by:

$$(4.1) \quad \forall x \in \mathcal{X} \quad f^{(l+1)}(x) = \mathcal{F}_P^{(l+1)} \left( f^{(l)}(x), \left( f^{(l)}, W(x, \cdot) \right) \right) \in \mathbb{R}^{d_{l+1}}.$$

Notice that  $\mathcal{F}^{(l+1)}$  depends on the measure  $P$ . Considering the functions  $f^{(l)}$  as signals on the vertex set  $\mathcal{X}$ , the update  $f^{(l+1)}(x)$  of a node  $x \in \mathcal{X}$  is calculated from the knowledge of its current representation  $f^{(l)}(x)$  and all its “weighted neighborhood”  $(f^{(l)}, W(x, \cdot))$ . The latter is a short notation for the map  $y \mapsto (f^{(l)}(y), W(x, y))$  at  $x$  fixed, which is the continuum equivalent of the multiset of pairs of weighted neighbors  $\left\{ \left\{ z_j^{(l)}, w_{i,j} \right\} \right\}_{v_j \in \mathcal{N}(v_i)}$  from (3.1).

For conciseness, we will often overload (4.1) with the short notation:

$$(4.2) \quad f^{(l+1)} = \mathcal{F}_P^{(l+1)}(f^{(l)}, W).$$

We denote  $\Theta_{W,P}(f) = f^{(L)}$  the output in the equivariant case and  $\bar{\Theta}_{W,P}(f)$  in the invariant case.

$$(4.3) \quad \Theta_{W,P}(f) = f^{(L)} \in L_P^\infty(\mathcal{X}, \mathbb{R}^{d_L}), \quad \bar{\Theta}_{W,P}(f) = \mathcal{R}_P(\Theta_{W,P}(f)) \in \mathbb{R}^{d_L}$$

Where  $\bar{\Theta}_{W,P}$  involves an additional continuum readout operator  $\mathcal{R} : \mathcal{P}(\mathcal{X}) \times L_P^\infty(\mathcal{X}, \mathbb{R}^{d_L}) \rightarrow \mathbb{R}^{d_L}$ . Naturally, we also demand the equivariant and invariant versions of the cMPGNN to respectively be equivariant and invariant to random graph model isomorphism. To that extent, we impose the following assumption on the operators  $\mathcal{F}^{(l)}$  and on  $\mathcal{R}$ :

**Assumption 4.1.** *There is a subgroup  $H \subset \text{Aut}(\mathcal{X})$  such that  $\forall 1 \leq l \leq L$ ,  $\forall f \in L_P^\infty(\mathcal{X}, \mathbb{R}^{d_l})$ ,  $\forall \phi \in H$ :*

$$\mathcal{F}_{\phi \cdot P}^{(l)}(\phi \cdot f, \phi \cdot W) = \phi \cdot \mathcal{F}_P^{(l)}(f, W)$$

and

$$\mathcal{R}_{\phi \cdot P}(\phi \cdot f) = \mathcal{R}_P(f).$$

Assumption 4.1 is largely inspired by the classical change of variable formula by push forward measure in Lebesgue integration. This formula states that for any  $\phi \in \text{Aut}(\mathcal{X})$  and any measurable map  $f$ ,

$$(4.4) \quad \int f dP = \int \phi \cdot f d(\phi \cdot P).$$

It is easy to check that if, for example,  $\mathcal{F}_P(f, W) = \int f(y)W(x, y)dP(y)$  and  $\mathcal{R}_P(f) = \int f dP$ , then (4.4) implies Assumption 4.1 with  $H = \text{Aut}(\mathcal{X})$ .

Contrary to the discrete case, where the symmetry is valid for the full group  $\mathfrak{S}_n$ , we require here a symmetry for a subgroup of  $\text{Aut}(\mathcal{X})$  only. Ideally, one would like Assumption 4.1 to hold for  $H = \text{Aut}(\mathcal{X})$ . However, in the next section, we will interpret some cMPGNN as limits of discrete MPGNN, such that the graph isomorphism symmetry becomes a random graph model isomorphism symmetry as the number of nodes tends to infinity. In this context, the example of maximum aggregation (Example 5-e in the next section) will highlight the fact that, for a matter of *existence* of such a limit, one may have to impose some conditions on  $P$ , and thus restrict to a subgroup of  $\text{Aut}(\mathcal{X})$ .

**Proposition 4.2** (Invariance and equivariance of cMPGNNs). *Let  $(W, P)$  be a random graph model on  $\mathcal{X}$ . Then, under Assumption 4.1,  $\Theta$  and  $\bar{\Theta}$  are respectively  $H$ -equivariant and  $H$ -invariant. Meaning that for any  $f$ , for any  $\phi \in H$ ,  $\Theta_{\phi \cdot (W, P)}(\phi \cdot f) = \phi \cdot \Theta_{W, P}(f)$  and  $\bar{\Theta}_{\phi \cdot (W, P)}(\phi \cdot f) = \bar{\Theta}_{W, P}(f)$ .*

*Proof.* We start by the equivariant case and the invariant one follows directly by composition with  $\mathcal{R}$ . Let  $\Lambda_{W, P}^{(l)}$  be the layer operators such that  $\Theta_{W, P}^{(L)} = \Lambda_{W, P}^{(L)} \circ \dots \circ \Lambda_{W, P}^{(1)}$ . Let  $f \in L_P^\infty(\mathcal{X}, \mathbb{R}^{d_l-1})$ . Using Assumption 4.1 we obtain:

$$\phi \cdot \Lambda_{W, P}^{(l)}(f) = \phi \cdot \mathcal{F}_P^{(l)}(f, W) = \mathcal{F}_{\phi \cdot P}^{(l)}(\phi \cdot f, \phi \cdot W) = \Lambda_{\phi \cdot (W, P)}^{(L)}(\phi \cdot f)$$

So the Proposition is true on all the  $\Lambda_{W, P}^{(l)}$ , thus also true on  $\Theta_{W, P}^{(L)}$  by composition. For the invariant case, it is clear from Assumption 4.1 that  $\mathcal{R}$  is  $H$ -invariant. The fact that the composition of an equivariant map followed by an invariant map is invariant yields the result.  $\square$

In the following are some examples of cMPGNN. The reader will, of course, see the intuitive connection to the previous Examples 1, 2, 3 and 4. In the next section, we will precisely see in what sense Examples 1 to 4, when applied on random graphs and as  $n$  grows large, converge to the following cMPGNNs.

**Example a** (Convolutional Message Passing). *The arithmetic mean becomes an integral over the probability space:*

$$f^{(l+1)}(x) = \int_{y \in \mathcal{X}} W(x, y) m^{(l+1)}(f^{(l)}(y)) dP(y)$$

and, in the invariant case, the continuous readout is:

$$\mathcal{R}_P(f^{(L)}) = \int_{\mathcal{X}} f^{(L)} dP.$$

**Example b** (Degree Normalized Convolutional Message Passing). *The continuous counterpart is:*

$$f^{(l+1)}(x) = \int_{y \in \mathcal{X}} \frac{W(x, y)}{\int_{t \in \mathcal{X}} W(x, t) dP(t)} m^{(l+1)}(f^{(l)}(y)) dP(y).$$

*In the invariant case, the readout is again the integral relatively to  $P$ .*

**Example c** (Attention based Message Passing). *The continuous counterpart is:*

$$f^{(l+1)}(x) = \int_{y \in \mathcal{X}} \frac{c^{(l+1)}(f^{(l)}(x), f^{(l)}(y), W(x, y))}{\int_{t \in \mathcal{X}} c^{(l+1)}(f^{(l)}(x), f^{(l)}(t), W(x, t)) dP(t)} m^{(l+1)}(f^{(l)}(y)) dP(y).$$

*In the invariant case, the readout is again the integral relatively to  $P$ .*

**Example d** (Generalized mean). *We simply add the function  $h$  to the mean example:*

$$f^{(l+1)}(x) = h \left( \int_{y \in \mathcal{X}} h^{-1} \left( W(x, y) m^{(l+1)}(f^{(l)}(y)) \right) dP(y) \right)$$

*In the invariant case, the readout is again the integral relatively to  $P$ .*

**Example e** (Max Convolutional Message Passing). *The maximum becomes a coordinate-wise essential supremum according to the probability measure  $P$  (that is, a supremum  $P$ -almost everywhere):*

$$f^{(l+1)}(x) = \operatorname{ess\,sup}_{y \in \mathcal{X}, P} W(x, y) m^{(l+1)}(f^{(l)}(y))$$

*and, in the invariant case, the final readout is the coordinate-wise:*

$$\mathcal{R}_P(f^{(L)}) = \operatorname{ess\,sup}_{y \in \mathcal{X}, P} f^{(L)}(y).$$

*Remark that we use the  $P$ -essential supremum and not the classical supremum here, since this will represent the limit maximum of variables that are  $P$ -distributed.*

**Remark 4.3.** *It can be easily verified that for all these examples, the underlying  $\mathcal{F}^{(l)}$  functions satisfy Assumption 4.1 with  $H = \operatorname{Aut}(\mathcal{X})$ . For the integral, it is ensured by the classical change of variable formula (4.4).*

*As for the essential supremum, a similar formula holds. Indeed, recall that for any measurable  $g$ , for any measurable bijection  $\phi$ , one has*

$$\operatorname{ess\,sup}_P g \circ \phi = \inf\{M | P(g \circ \phi > M) = 0\}.$$

*However,  $(g \circ \phi > M) = \{x | g \circ \phi(x) > M\} = \{\phi^{-1}(y) | g(y) > M\} = \phi^{-1}(g > M)$ , such that one finally has:*

$$\inf\{M | P(g \circ \phi > M) = 0\} = \inf\{M | P(\phi^{-1}(g > M)) = 0\} = \operatorname{ess\,sup}_{\phi_{\#}P} g.$$

## 5. cMPGNNs as limits of MPGNNs on large random graphs

This section contains the core of our contributions. We focus on MPGNNs when applied on random graphs  $G_n$  drawn from  $\mathcal{G}_n(W, P)$ . Specifically, given such an MPGNN, we are interested in its limit as  $n$  tends to infinity. We show that under mild regularity conditions, such a limit exists and is a cMPGNN. Furthermore, we provide some non-asymptotic bounds to control the deviation between an MPGNN and its limit cMPGNN with high probability.

This section is divided in two parts. In the first part (Section 5.1), given an MPGNN, we define, *when it exists*, its associated canonical cMPGNN on  $(W, P)$  that we call **continuous counterpart**. The precise definition of this central concept is Definition 5.1: it states how that continuous counterpart is built out of the discrete network as a limit on random graphs  $G_n \sim \mathcal{G}_n(W, P)$  of growing sizes. Then, we show that under mild regularity conditions, Examples a, b, c and d are indeed the continuous counterparts of Examples 1, 2, 3, and 4 according to our definition.

In the second part of this section (Section 5.2), we study the convergence of MPGNNs towards their continuous counterpart, when it exists: we give sufficient conditions for this convergence to occur and provide convergence rates in the form of non-asymptotic bounds with high probability. Our first main result, Theorem 5.11 in Section 5.2.1, concerns a class of MPGNN that have a certain kind of Lipschitz continuity among other mild assumptions: in a few words, it states that such MPGNNs have a continuous counterpart to which they converge as  $n$  grows, with a controlled rate that we specify. As we will see, this applies to all examples *but* max aggregation. Our second result, Theorem 5.17 in Section 5.2.2, is specific to the case of maximum aggregation, as in this case the bounded difference property is not verified and Theorem 5.11 is not applicable. It is based on another concentration inequality and leads to a convergence rate with a dependence on the input dimension  $d$  (recall  $\mathcal{X} \subset \mathbb{R}^d$ ), contrary to the bounded differences method.

### 5.1. Definition of the limit cMPGNN

Let  $(W, P)$  be a random graph model and  $f \in L_P^\infty(\mathcal{X}, \mathbb{R}^d)$ . The main purpose of this subsection is to *define* the natural limit of discrete MPGNNs to cMPGNNs, before examining more precisely the rate of convergence from one to the other in the next subsection.

To this end, we consider a single-layer MPGNN applied on a random graph  $G_n \sim \mathcal{G}_n(W, P)$  and input node features  $Z = S_X f$  as a sampling of some function (recall the definition of the sampling operator in Eq. (2.1)). We define a corresponding cMPGNN layer on  $(W, P)$  with input map  $f$ . Since there is only one layer in this section, we drop the superscript indexation. To motivate the next definition – that may seem overly technical at first sight – let us consider the simplest example, namely Examples 1 and a. Let us examine how Example a can be recovered from Example 1 at the limit. The update of  $f(x)$  is given by

$$(5.1) \quad \mathcal{F}_P(f, W)(x) = \int_{y \in \mathcal{X}} W(x, y) m(f(y)) dP(y).$$

It is fairly clear that, by the law of large numbers, this integral equals the limit of

$$(5.2) \quad \frac{1}{n} \sum_{i=1}^n W(x, X_i) m(f(X_i))$$

for  $X_1, \dots, X_n \stackrel{iid}{\sim} P$ . Coincidentally, Eq. (5.2) is exactly the discrete message passing of Example 1 around node  $x$  of a random graph with node latent variables  $\{x, X_1, \dots, X_n\}$ , signal  $Z = \{f(x), f(X_1), \dots, f(X_n)\}$  and kernel  $W$ . We have thus naturally obtained the cMPGNN of Example (a) via a limit of the MPGNN of Example 1 on random graphs.

Back to the general case, given an abstract discrete (single-layer) MPGNN with aggregation  $F$ , we want to define a cMPGNN from its limit on random graphs. Following the path of the above example, we could look at the almost sure limit of the message passing equation:  $\lim_{n \rightarrow \infty} F\left(f(x), \left\{\!\!\left\{ (f(X_k), W(x, X_k)) \right\}_{1 \leq k \leq n}\right.\right)$ . However, the existence of this limit is far from obvious in the general case. As we will see in the next definition, we will rather relax it to the convergence of the expectation instead:

$$(5.3) \quad \mathbb{E}_{X_1, \dots, X_n} \left[ F\left(f(x), \left\{\!\!\left\{ (f(X_i), W(x, X_i)) \right\}_{1 \leq i \leq n}\right.\right)\right].$$

Up to some details related to isomorphism invariance, the existence of this limit is how we *define* the continuous counterpart of a MPGNN.

**Definition 5.1** (Continuous counterpart). *Let  $F$  be a MPGNN layer. For  $f \in L_P^\infty(\mathcal{X}, \mathbb{R}^d)$ ,  $W : \mathcal{X}^2 \rightarrow [0, 1]$  and  $P \in \mathcal{P}(\mathcal{X})$ , define the sequence of functions in  $L_P^\infty(\mathcal{X}, \mathbb{R}^d)$ :*

$$(5.4) \quad F_{P,n}(f, W) : x \mapsto \mathbb{E} \left[ F\left(f(x), \left\{\!\!\left\{ (g(X_i), W(x, X_i)) \right\}_{2 \leq i \leq n}\right.\right)\right]$$

where the expected value is taken over all the  $X_2, \dots, X_n \stackrel{iid}{\sim} P$ .

Let  $\mathcal{F}$  be an operator of the form (4.2) taking value in  $L_P^\infty(\mathcal{X}, \mathbb{R}^d)$  and suppose that there exists  $H$ , a non-trivial subgroup of  $\text{Aut}(\mathcal{X})$ , such that for any  $f \in L_P^\infty(\mathcal{X}, \mathbb{R}^d)$  and  $\phi \in H$ :

$$(5.5) \quad F_{\phi \cdot P, n}(\phi \cdot f, \phi \cdot W) \xrightarrow{L_{\phi \cdot P}^\infty(\mathcal{X}, \mathbb{R}^d)} \mathcal{F}_{\phi \cdot P}(\phi \cdot f, \phi \cdot W).$$

noting that the convergence is with respect to the norm  $L_{\phi \cdot P}^\infty(\mathcal{X}, \mathbb{R}^d)$ . Then we say that  $\mathcal{F}$  is the **continuous counterpart** of  $F$  for  $H$ . When  $H = \text{Aut}(\mathcal{X})$ , or when  $H$  is obvious from the context, we simply say that  $\mathcal{F}$  is the **continuous counterpart** of  $F$ .

Note that we consider only  $n - 1$  random variables for convenience with later definitions (in an  $n$ -sized graph, each node has potentially  $n - 1$  neighbors). In this definition of limit GNNs, we have *not* explicitly assumed that the  $\mathcal{F}$  defined above satisfies Assumption 4.1 related to continuous isomorphisms and cMPGNN. Fortunately, this assumption is in fact automatically verified, for the natural subgroup  $H$  involved in the definition. In other words, every continuous counterpart of MPGNNs as defined above are indeed valid cMPGNNs.

**Proposition 5.2.** *Let  $\mathcal{F}$  be the continuous counterpart of  $F$  for  $H$  as defined in Definition 5.1. Then it satisfies Assumption 4.1 for any  $\phi \in H$ .*

*Proof.* Let  $f \in L_P^\infty(\mathcal{X}, \mathbb{R}^d)$ ,  $\phi \in H$ , and  $X_2, \dots, X_n \stackrel{iid}{\sim} P$ , we have for  $P$ -almost all  $x$ :

$$\begin{aligned}
& \phi \cdot F_{P,n}(f, W)(x) \\
&= \mathbb{E}_{X_2, \dots, X_n} \left[ F \left( f(\phi^{-1}(x)), \left\{ \left\| (f(X_i), W(\phi^{-1}(x), X_i)) \right\|_{2 \leq i \leq n} \right\} \right) \right] \\
(5.6) \quad &= \mathbb{E}_{Y_2, \dots, Y_n} \left[ F \left( \phi \cdot f(x), \left\{ \left\| (\phi \cdot f(Y_i), \phi \cdot W(x, Y_i)) \right\|_{2 \leq i \leq n} \right\} \right) \right] \\
&= F_{\phi \cdot P, n}(\phi \cdot f, \phi \cdot W)(x).
\end{aligned}$$

Where in (5.6), we have set  $Y_i = \phi(X_i)$ ,  $\forall i$ , which have all law  $\phi \cdot P$ , and used the classical change of variable formula (4.4). Thus, by taking the limit, (5.5) implies:

$$\mathcal{F}_{\phi \cdot P}(\phi \cdot f, \phi \cdot W) = \phi \cdot \mathcal{F}_P(f, W)$$

□

The same definition and properties as above can also be given for a readout layer.

**Definition 5.3.** Let  $R$  be a MPGNN readout layer and  $P \in \mathcal{P}(\mathcal{X})$ . For  $f \in L_P^\infty(\mathcal{X}, \mathbb{R}^d)$ , we define the sequence of functions

$$R_{P,n}(f) = \mathbb{E}_{X_1, \dots, X_n} \left[ R \left( \left\{ f(X_1), \dots, f(X_n) \right\} \right) \right] \in \mathbb{R}^d,$$

where the expected value is taken over all the  $X_1, \dots, X_n \stackrel{iid}{\sim} P$ .

Let  $\mathcal{R}$  be a continuum readout operator of the form (4.3) taking values in  $\mathbb{R}^d$ .

Suppose we have  $H$  a non-trivial subgroup of  $\text{Aut}(\mathcal{X})$  such that for any  $f \in L_P^\infty(\mathcal{X}, \mathbb{R}^d)$ , for any  $\phi \in H$ ,  $R_{\phi \cdot P, n}(\phi \cdot f)$  converges to  $\mathcal{R}_{\phi \cdot P}(\phi \cdot f)$  in the  $\|\cdot\|_\infty$  norm of  $\mathbb{R}^d$ :

$$R_{\phi \cdot P, n}(\phi \cdot f) \rightarrow \mathcal{R}_{\phi \cdot P}(\phi \cdot f).$$

Then we say that  $\mathcal{R}$  is the **continuous counterpart** of  $R$  for  $H$ , unless  $H = \text{Aut}(\mathcal{X})$  or  $H$  is obvious from context, in which case we simply say that  $\mathcal{R}$  is the **continuous counterpart** of  $R$ .

Naturally, this also implies invariance with respect to the proper subgroup.

**Proposition 5.4.** Let  $\mathcal{R}$  be the continuous counterpart of  $R$  as in definition 5.3. Then it satisfies Assumption 4.1 for any  $\phi \in H$ .

Going back to our four examples of Sections 3 and 4, we now show that Examples a, b, c and d are the continuous counterparts of Examples 1, 2, 3 and 4 for the full  $\text{Aut}(\mathcal{X})$  under mild positivity conditions for the coefficients in the degree normalized and GAT examples, and regularity condition for the generalized mean. This is satisfied for most examples of kernel (e.g. Gaussian) or attention coefficients (e.g. the typical exponentials of LeakyReLUs), as the data live in a bounded domain  $\mathcal{X}$ . Example 5-e is however more involved, as one has to be careful with the shape of  $\mathcal{X}$  and the properties of  $P$  to avoid null set issues at the boundary  $\partial\mathcal{X}$ . We show that if  $\mathcal{X}$  contains no nonempty open null set, and if  $W, f$  are continuous, then Example e is the continuous counterpart of Example 5 for the subgroup  $H$  of  $\text{Aut}(\mathcal{X})$  consisting of all the *homeomorphisms* from  $\mathcal{X}$  into itself. The proof of the next proposition is given in Appendix 9.

**Proposition 5.5** (Continuous counterpart of Examples). *The following holds:*



- **Example 1-a.** *With no additional restriction on  $W$ ,  $f$ , nor  $P$ , Example a is the continuous counterpart of Example 1 for the full  $\text{Aut}(\mathcal{X})$ .*
- **Example 2-b.** *Suppose that  $m$  is bounded and that there is a strictly positive  $a$  such that  $0 < a \leq W$ . Then Example b is the continuous counterpart of Example 2 for the full  $\text{Aut}(\mathcal{X})$ .*
- **Example 3-c.** *Suppose that  $m$  is bounded and that there is two positive constants  $0 < a < b$  such that  $a \leq c(f(x), f(y), W(x, y)) \leq b$ . Then Example c is the continuous counterpart of Example 3 for the full  $\text{Aut}(\mathcal{X})$ .*
- **Example 4-d.** *Suppose that  $h^{-1}$  is bounded and that  $h$  is  $\alpha_h$ -Hölder on the range of  $h^{-1}$  with  $0 < \alpha_h \leq 1$ , that is,  $\|h(x) - h(y)\|_\infty \leq K_h \|x - y\|_\infty^{\alpha_h}$ . Then Example d is the continuous counterpart of Example 4 for the full  $\text{Aut}(\mathcal{X})$ .*
- **Example 5-e.** *Suppose that  $W$ ,  $m$ , and  $f$  are continuous and that the measure  $P$  is strictly positive on  $\mathcal{X}$  i.e., any nonempty relative open of  $\mathcal{X}$  has a strictly positive measure by  $P$ . Then e is the continuous counterpart of 5 for  $\text{Hom}(\mathcal{X})$ : the subgroup of  $\text{Aut}(\mathcal{X})$  made of the  $\phi \in \text{Aut}(\mathcal{X})$  that are homeomorphisms.*

## 5.2. Convergence of MPGNNs to their continuous counterpart

Let  $(W, P)$  be a random graph model, and  $(G_n)_{n \geq 1}$  be a sequence of random graphs drawn from  $\mathcal{G}_n(W, P)$ . We go back to the multi layer setup: consider a MPGNN  $(F^{(l)})_{1 \leq l \leq L}$ , a readout  $R$  and assume that their continuous counterparts  $(\mathcal{F}^{(l)})_{1 \leq l \leq L}$  and  $\mathcal{R}$  in the sense of Definitions 5.1 and 5.3 exist. For an  $f \in L^\infty_{\mathcal{P}}(\mathcal{X}, \mathbb{R}^{d_0})$ , does the MPGNN on  $G_n$  with input signal  $S_X f$  actually converge to the cMPGNN on  $(W, P)$  with input signal  $f$ ? If yes, at which speed? In this section we provide non-asymptotic bounds with high probability to quantify this convergence.

Our main theorems state that, under mild regularity conditions and with high probability,  $\Theta_{G_n}(S_X(f))$  is close to  $\Theta_{W,P}(f)$  in the equivariant case and that  $\bar{\Theta}_{G_n}(S_X(f))$  is close to  $\bar{\Theta}_{W,P}(f)$  in the invariant case. For the latter, we can compare both outputs directly since they belong to the same vector space. The comparison is however more involved in the equivariant case since  $\Theta_{G_n}(S_X(f))$  is a tensor and  $\Theta_{W,P}(f)$  is a function. In this case, we measure their deviation with the Maximum Absolute Error (MAE) defined by

$$\text{MAE}_X(Z, f) = \max_{1 \leq i \leq n} \|z_i - f(X_i)\|_\infty.$$

Our first theorem is based on bounded differences method and the McDiarmid inequality (Corollary 10.3 in Appendix 10). It encompasses numerous examples of MPGNNs that include Examples 1 to 4. For Example 5 however, we obtain a different bound based on other concentration inequalities similar to what has been done in the previous section.

### 5.2.1. Bounded differences method

Let us detail the assumptions that we make on the MPGNN. Our result is based on the so-called McDiarmid inequality [McDiarmid, 1989] (Corollary 10.3 in Appendix

10), which says that a multivariate function of independent random variable has a sub-Gaussian concentration around its mean if it satisfies the following notion of bounded differences.

**Definition 5.6** (Bounded Differences Property). *Let  $f : \mathcal{E}^n \rightarrow \mathbb{R}$  be a function of  $n$  variables. We say that  $f$  has the bounded differences property if there exist  $n$  nonnegative constants  $c_1, \dots, c_n$  such that for any  $1 \leq i \leq n$ :*

$$(5.7) \quad |f(x_1, \dots, x_{i-1}, x_i, x_{i+1}, \dots, x_n) - f(x_1, \dots, x_{i-1}, x'_i, x_{i+1}, \dots, x_n)| \leq c_i,$$

For any  $x_1, \dots, x_n, x'_i \in \mathcal{E}$ .

In plain terms, whenever one fixes all but one of the components of  $f$ , the variations should be bounded. For a fixed  $x_1 \in \mathcal{X}$ , we are then interested in the bounded differences of the layers of our MPGNN

$$(5.8) \quad (x_2, \dots, x_n) \mapsto F^{(l)}(f^{(l-1)}(x_1), \left\{ \left\{ f^{(l-1)}(x_i), W(x_1, x_i) \right\}_{i \geq 2} \right\})$$

as a map of the  $n - 1$  variables  $x_2, \dots, x_n$ . These bounded differences depend on  $x_1$ . Remark that, if we call them  $c_2(x_1), \dots, c_n(x_1)$ , since (5.8) is invariant to the permutations of  $x_2, \dots, x_n$ , they can be taken all equal  $c_2(x_1) = \dots = c_n(x_1)$ . To handle some examples, we allow to take a transform  $\psi$  of the layers before computing the bounded difference, which, as we will see, may influence the final rate of convergence. For instance, for Ex. 4 with  $h = (\cdot)^{1/p}$ , one should lift back to the power  $p$  before computing the bounded differences to get the proper rate (i.e., take  $\psi = h$  in the assumption below). The precise assumption that we make is the following.

**Assumption 5.7** (Bounded differences of layers). *For all layers  $l$ , there is an function  $\psi$  assumed invertible on the proper domain such that:*

- 1) We have the bounded difference inequality

$$\begin{aligned} \operatorname{ess\,sup}_{x_1 \in \mathcal{X}, P} \left\| \psi^{-1} \left( F^{(l)}(f^{(l-1)}(x_1), \left\{ \left\{ f^{(l-1)}(x_i), W(x_1, x_i) \right\}_{i \geq 2} \right\}) \right. \right. \\ \left. \left. - \psi^{-1} \left( F^{(l)}(f^{(l-1)}(x_1), \left\{ \left\{ f^{(l-1)}(x'_i), W(x_1, x'_i) \right\}_{i \geq 2} \right\}) \right) \right\|_{\infty} \leq D_n^{(l)} \end{aligned}$$

for all  $x_i, x'_i, i \geq 2$ , and  $x_i = x'_i$  except for  $i = 2$ , where  $D_n^{(l)}$  is some rate.

- 2) We have

$$\begin{aligned} \operatorname{ess\,sup}_{x_1 \in \mathcal{X}, P} \left\| \psi \left( \mathbb{E} \psi^{-1} \left( F^{(l)}(f^{(l-1)}(x_1), \left\{ \left\{ f^{(l-1)}(X_i), W(x_1, X_i) \right\}_{i \geq 2} \right\}) \right) \right. \right. \\ \left. \left. - \mathbb{E} F^{(l)}(f^{(l-1)}(x_1), \left\{ \left\{ f^{(l-1)}(X_i), W(x_1, X_i) \right\}_{i \geq 2} \right\}) \right\|_{\infty} \leq \bar{D}_n^{(l)} \end{aligned}$$

where the expectation is over  $X_2, \dots, X_n \sim P$  and  $\bar{D}_n^{(l)}$  is some rate.

- 3)  $\psi$  is  $\alpha_\psi$ -Holder on its domain with  $0 < \alpha_\psi \leq 1$ :

$$\|\psi(y) - \psi(y')\|_{\infty} \leq K_\psi \|y - y'\|_{\infty}^{\alpha_\psi}$$

In several examples, it will be enough to consider  $\psi = Id$ , such that the layers themselves satisfy the bounded difference property, the exponent is  $\alpha_\psi = 1$ , and items 2. and 3. in Assumption 5.7 above are automatically satisfied. However, we

allow for a transform  $\psi^{-1}$  before computing the bounded differences, to handle more general cases (namely, the generalized mean Example 4-d) through the modified McDiarmid's inequality Corollary 10.3 in Appendix 10. The next assumption relates to the existence of the continuous counterpart of the layers as defined by Definition 5.1. We recall that this is defined by the convergence of the expectation of the layers, here we just denote the rate of convergence by  $s_n$ .

**Assumption 5.8** (Continuous counterpart of layers). *For all layer  $l$ ,  $\mathcal{F}^{(l)}$  is the continuous counterpart of  $F^{(l)}$ , and using the notations of Definition 5.1, we let  $(s_n^{(l)})$  be a sequence of positive reals such that:*

$$(5.9) \quad \left\| F_{P,n}^{(l)}(f^{(l-1)}, W) - \mathcal{F}_P^{(l)}(f^{(l-1)}, W) \right\|_\infty \leq s_n^{(l)} \rightarrow 0.$$

for all  $n$ .

Finally, we state a final assumption on the Holder-stability of the layers, which is usually easy to verify.

**Assumption 5.9** (Holder property of layers). *For all  $1 \leq l \leq L$ , there exist a constant  $K_{F,n}^{(l)} > 0$  and an exponent  $0 < \alpha_F \leq 1$  such that the aggregations  $F^{(l)}$  satisfy:*

$$\left\| F^{(l)}(z_1, \{\!\!\{z_i, w_i\}\!\!\}_{i \geq 2}) - F^{(l)}(z'_1, \{\!\!\{z'_i, w_i\}\!\!\}_{i \geq 2}) \right\|_\infty \leq K_{F,n}^{(l)} \max_{1 \leq i \leq n} \|z_i - z'_i\|_\infty^{\alpha_F}$$

for all  $z_i, z'_i \in \mathbb{R}^{d_i-1}$  and  $w_i \in [0, 1]$ . Moreover, the  $K_{F,n}^{(l)}$  are bounded over  $n$ .

Note that the “for all” statement implies that the  $z'_i$  can be permuted, and the bound must stay valid. We finish by stating the same assumptions for the readout function in the invariant case.

**Assumption 5.10** (Readout function). *The readout function satisfies the following:*

- 1) *The readout function  $R$  has a continuous counterpart  $\mathcal{R}$ , and we let  $r_n$  be such that (recall the definitions of  $R_{P,n}$  and  $\mathcal{R}_P$  from Definition 5.3)*

$$(5.10) \quad \left\| R_{P,n}(f^{(L)}) - \mathcal{R}_P(f^{(L)}) \right\|_\infty \leq r_n$$

- 2) *The readout function has bounded differences (Def. 5.6). Since the  $n$  bounded differences can be taken all equal due to permutation invariance, we call  $C_n$  the bounded difference of*

$$(x_1, \dots, x_n) \mapsto R \left( \{\!\!\{f^{(L)}(x_1), \dots, f^{(L)}(x_n)\}\!\!\} \right).$$

- 3) *There exists  $K_{R,n} > 0$  such that*

$$\left\| R(\{\!\!\{z_i\}\!\!\}_{i \leq 1 \leq n}) - R(\{\!\!\{z'_i\}\!\!\}_{i \leq 1 \leq n}) \right\|_\infty \leq K_{R,n} \max_{1 \leq i \leq n} \|z_i - z'_i\|_\infty$$

for all  $z_i, z'_i \in \mathbb{R}^L$ . Moreover, the  $K_{R,n}$  are bounded over  $n$ .

Again, the “for all” statement implies that the bound remains under any permutation of the  $z'_i$ . Note that, for simplicity, we do not involve any “Holder” exponent in the readout function, as all our examples can be treated without. Our main result is then the following.

**Theorem 5.11** (MPGNN convergence towards cMPGNN). *Under Assumption 5.7, 5.8 and 5.9, for any  $0 < \rho \leq 1$ , with probability at least  $1 - \rho$ , the following assertions are verified:*

$$(5.11) \quad \begin{aligned} & \text{MAE}_X(\Theta_{G_n}(S_X(f)), \Theta_{W,P}(f)) \\ & \leq \sum_{l=1}^L A_n^{(l,L)} \left[ \left( \frac{1}{2} \left( D_n^{(l)} \right)^2 n \ln \left( \frac{2^{L+2-l} d_l n}{\rho} \right) \right)^{\alpha_{\psi/2}} + \bar{D}_n^{(l)} + s_n^{(l)} \right]^{\alpha_F^{L-l}} \end{aligned}$$

Where  $A_n^{(l,L)} = \prod_{k=l+1}^L (K_{F,n}^{(k)})^{\alpha_F^{L-k}}$  for  $1 \leq l \leq L$ , and with the convention  $\prod_{k=a}^b (\dots) = 1$  if  $a > b$ .

With additionally Assumption 5.10,

$$(5.12) \quad \begin{aligned} & \|\bar{\Theta}_{G_n}(S_X(f)) - \bar{\Theta}_{W,P}(f)\|_{\infty} \\ & \leq K_{R,n} \sum_{l=1}^L A_n^{(l,L)} \left[ \left( \frac{1}{2} \left( D_n^{(l)} \right)^2 n \ln \left( \frac{2^{L+3-l} d_l n}{\rho} \right) \right)^{\alpha_{\psi/2}} + \bar{D}_n^{(l)} + s_n^{(l)} \right]^{\alpha_F^{L-l}} \\ & \quad + C_n \sqrt{n \ln \left( \frac{4d_L}{\rho} \right)} + r_n. \end{aligned}$$

*Sketch of proof.* (See Appendix 7 for full proof) We prove the result by induction on the number of layers  $L$ . At each step, we bound  $\|z_i^{(L)} - f^{(L)}(X_i)\|$  for all  $i$ . This is done by conditioning over  $x_i$  and finding a bound of

$$\left\| F^{(L)} \left( f^{(L-1)}(x_i), \left\{ \left( f^{(L-1)}(X_k), W(x_i, X_k) \right) \right\}_{k \neq i} \right) - f^{(L-1)}(x_i) \right\|_{\infty}$$

that does not depend on  $x_i$ , using a succession of triangular inequalities, the Holder-type property of Assumption 5.9 and McDiarmid's inequality. We then turn it into a bound for  $\|z_i^{(L)} - f^{(L)}(X_i)\|_{\infty}$  via the law of total probability and conclude with a union bound over  $i$ .  $\square$

We can get a more explicit rate by hiding multiplicative constants, as in the following corollary.

**Corollary 5.12.** *Under the assumptions of Theorem 5.11, for  $n$  large enough, and for  $0 < \rho < 1$ , the following holds with probability at least  $1 - \rho$ .*

$$(5.13) \quad \text{MAE}_X(\Theta_{G_n}(S_X(f)), \Theta_{W,P}(f)) \lesssim \left( D_n^2 n \ln \left( \frac{n}{\rho} \right) \right)^{\alpha_F^{L-1} \alpha_{\psi/2}} + \bar{D}_n^{\alpha_F^{L-1}} + s_n^{\alpha_F^{L-1}},$$

Where  $D_n = \max_l D_n^{(l)}$ ,  $\bar{D}_n = \max_l \bar{D}_n^{(l)}$ ,  $d_{max} = \max_l d_l$ ,  $s_n = \max_l s_n^{(l)}$  and  $\lesssim$  hides some multiplicative constants which depend on  $K_{F,n}^{(1)}, \dots, K_{F,n}^{(L)}, K_{R,n}$  and are bounded over  $n$ .

*Proof.* Knowing  $(D_n)$  and  $(s_n)$  both tend to zero, there is an integer  $n_0$  such that, for any  $n \geq n_0$ , for each term of the sum in (5.11), the base under the exponent  $\alpha_{L-l}$  is smaller than 1. After, roughly majorizing each term of the sum, we disregard

the multiplicative constants that are bounded over  $n$  under the symbol  $\lesssim$ . Finally, we use the inequality  $(x + y)^a \leq x^a + y^a$  for  $a \leq 1$ . Recall that the  $K_{F,n}^{(l)}$  and  $K_{R,n}$  are assumed bounded from Assumption 5.9 and 5.10.  $\square$

The asymptotic behavior of (5.13) is generally determined by  $D_n$ . If the latter does not decrease fast enough, the inequality becomes meaningless. In particular, we have the following important corollary.

**Corollary 5.13.** *If  $D_n = o\left(\frac{1}{\sqrt{n \ln n}}\right)$  then  $\text{MAE}_X(\Theta_{G_n}(S_X(f)), \Theta_{W,P}(f))$  converges in probability towards 0. If  $D_n = n^{-q}$  with  $q > 1/2$ , then the convergence is almost sure.*

*Proof.* Call  $\text{MAE} = \text{MAE}_X(\Theta_{G_n}(S_X(f)), \Theta_{W,P}(f))$ . The first part is immediate.

For the second part, calling  $r_n = (D_n^2 n)^{\frac{\alpha_F^{L-1} \alpha_\psi}{4}}$  and  $R_n = C(r_n + \bar{D}_n^{\alpha_F^{L-1}} + s_n^{\alpha_F^{L-1}}) \rightarrow 0$  where  $C$  is the multiplicative constant appearing in (5.13), we have by (5.13) that

$$\mathbb{P}(\text{MAE} \geq R_n) \leq ne^{-\frac{1}{\sqrt{D_n^2 n}}} = O(ne^{-n^{q-1/2}})$$

Since this last term is summable over  $n$ , by Borel-Cantelli's lemma the convergence is almost sure.  $\square$

This corollary provides a sufficient condition for an MPGNN on a random graph to converge to its continuous counterpart on the random graph model: in words, its aggregation function needs to have sharp enough bounded differences. Below we investigate whether our examples have such sharp bounded differences. Under mild regularity conditions, this is the case for all examples but Example 5. The proof is in Appendix 9.

**Proposition 5.14.** *We present application of Theorem 5.11 on the Examples. In all cases the message functions  $m^{(l)}$  are supposed Lipschitz continuous and bounded. Additional regularity assumptions are needed for some examples.*

- **Example 1-a.**  $D_n = O(1/n)$ ,  $\bar{D}_n = 0$ ,  $s_n = r_n = 0$ ,  $\alpha_\psi = \alpha_F = 1$ . The final rate is therefore  $O(\sqrt{\ln n/n})$ .
- **Example 2-b.** Suppose there is  $a > 0$  such that  $W \geq a$ . Then  $D_n = O(1/n)$ ,  $\bar{D}_n = 0$ ,  $s_n = O(1/\sqrt{n})$ ,  $\alpha_\psi = \alpha_F = 1$ . The final rate is therefore  $O(\sqrt{\ln n/n})$ .
- **Example 3-c.** Suppose there is  $a, b > 0$  and  $K_c > 0$  such that  $a < c(x, y, t) < b$  and  $|c(x, y, t) - c(x', y', t)| \leq K_c(\|x - x'\|_\infty + \|y - y'\|_\infty)$ ,  $\forall x, x', y, y', t$ . Then  $D_n = O(1/n)$ ,  $\bar{D}_n = 0$ ,  $s_n = O(1/\sqrt{n})$ , and  $\alpha_\psi = \alpha_F = 1$ . The final rate is therefore  $O(\sqrt{\ln n/n})$ .
- **Example 4-d.** Suppose that  $h$  is  $\alpha_h$ -Holder and that  $h^{-1}$  is bounded, and that Assumption 5.9 is satisfied for some exponent  $0 < \alpha_F \leq 1$  (see examples below). Then  $D_n = O(1/n)$ ,  $\bar{D}_n = O(1/n^{\alpha_h/2})$ ,  $s_n = O(1/n^{\alpha_h/2})$ ,  $\alpha_\psi = \alpha_h$ . The final rate is therefore  $O((\ln n/n)^{\alpha_h \alpha_F^{L/2}})$ . For the exponents  $\alpha_h, \alpha_F$ , we can give several usual cases:

- If  $h = (\cdot)^{1/p}$  and  $h^{-1} = (\cdot)^p$  (moment-based aggregation), then  $\alpha_h = 1/p$  and  $\alpha_F = 1$ .
- If  $h^{-1}$  is Lipschitz w.r.t.  $x$  (and recall that  $h$  is  $\alpha_h$ -Holder), then  $\alpha_F = \alpha_h$ .
- If the data domain is bounded and  $h^{-1}$  and  $h$  are both Lipschitz (e.g. for geometric mean on a bounded domain), then  $\alpha_h = \alpha_F = 1$ .

- **Example 5-e.** The bounded differences do not satisfy Corollary 5.13.

*Proof.* Calculation and verification of the Theorem’s assumptions are done in Appendix 9.  $\square$

Example	$D_n$	$\bar{D}_n$	$s_n$	Convergence by Th. 5.11
1-a	$O(1/n)$	0	0	$O(\sqrt{\ln n/n})$
2-b	$O(1/n)$	0	$O(1/\sqrt{n})$	$O(\sqrt{\ln n/n})$
3-c	$O(1/n)$	0	$O(1/\sqrt{n})$	$O(\sqrt{\ln n/n})$
4-d	$O(1/n)$	$O(n^{-\alpha_h/2})$	$O(n^{-\alpha_h/2})$	$O((\ln n/n)^{\alpha_h \alpha_F^{1/2}})$
5-e	$\Omega(1)$	–	–	<b>X</b>

Table 1. Table summing up the convergence rates of this section. See Proposition 5.14 and Theorem 5.11 for details.

Table 1 sums up these results. For a network with max aggregation, the bounded differences are not sharp enough for theorem 5.11 to conclude. We thus treat this case separately in the next section.

### 5.2.2. Convergence of max aggregation MPGNNs

In this subsection, we specifically treat the example of max aggregation. We would like to follow the same line of proof used in the proof of Prop. 5.5, but when we reach Eq. (9.5), we need to be able to give an approximation of the measure of a ball in  $\mathcal{X}$ . To this end, we introduce the notion of *volume retaining property*. The purpose is to estimate from below the measure of a ball centered anywhere in  $\mathcal{X}$ .

**Definition 5.15** (Volume retaining property). *We say that the probability space  $(\mathcal{X}, P)$  has the  $(r_0, \kappa)$ -volume retaining property if for any  $r \leq r_0$  and for any  $x \in \mathcal{X}$ ,*

$$(5.14) \quad P(\mathcal{B}(x, r) \cap \mathcal{X}) \geq \kappa m(\mathcal{B}(x, r)).$$

Where  $\mathcal{B}(x, r)$  is the ball of center  $x$  and radius  $r$  and  $m$  is the classical  $d$ -dimensional Lebesgue measure in  $\mathbb{R}^d$ .

This condition prevents  $\mathcal{X}$  from having pathological shapes at the boundary, such as arbitrarily sharp peaks. When  $P$  itself is the Lebesgue measure on  $\mathcal{X}$ , it has a clear geometrical interpretation. For example, the complementary of the union of two tangent open balls does not satisfy volume retention, since the peak at the tangency point is too sharp. Whereas it is easy to see that the unit hypercube  $[0, 1]^d$  has the  $(1, 1/2^d)$ -volume retaining property. This hypothesis is standard in other related

problems where one needs to estimate the measure of balls in order to obtain some convergence rate, when it is also referred to as the space being *standard w.r.t. P*. In Set Estimation, the goal is to estimate the compact support of a probability distribution on a metric space. This is typically done by considering the union of balls centered at points drawn from that distribution [Cuevas and Fraiman, 1997, Cuevas and Rodríguez-Casal, 2004]. More contemporary, in Topological Data Analysis, it is used to measure the convergence rate of persistence diagrams, when the data is assumed to be drawn from a probability distribution supported on a compact metric space [Chazal et al., 2014]. For a volume retaining probability space, we prove the following concentration inequality.

**Lemma 5.16** (Concentration inequality for volume retaining space). *Let  $g : \mathcal{X}^2 \rightarrow \mathbb{R}^{d'}$  be  $K_g$ -Lipschitz and  $(\mathcal{X}, P)$  have the  $(r_0, \kappa)$ -volume retaining property for some  $r_0, \kappa > 0$ . Then for any  $\rho \geq e^{-n\kappa r_0^{d'} 2^{d'}}$ , for any random variables  $X_1, \dots, X_n \stackrel{iid}{\sim} P$ , with probability at least  $1 - \rho$ :*

$$\left\| \max_{1 \leq i \leq n} g(x, X_i) - \sup g(x, \cdot) \right\|_\infty \leq \frac{K_g}{2} \left( \frac{\ln(d'/\rho)}{n\kappa} \right)^{1/d'}.$$

*Proof.* We write the proof assuming  $d' = 1$ , the case  $d' \geq 1$  follows easily by a union bound. Clearly, volume-retention implies strict positiveness of the measure. The proof is exactly the same as Prop. 5.5, until (9.4) where we use Lipschitz continuity to get the bound

$$(5.15) \quad \left| \max_i g(x, X_i) - \sup g(x, \cdot) \right| \leq (1 - P(\mathcal{B}(x^*, \varepsilon/K_g) \cap \mathcal{X}))^n$$

By volume retention, for  $\varepsilon \leq r_0 K_g$ , (5.15) is bounded by

$$(5.16) \quad \left( 1 - \kappa \left( \frac{2\varepsilon}{K_g} \right)^{d'} \right)^n \leq e^{-n\kappa \frac{2^{d'} \varepsilon^{d'}}{K_g^{d'}}},$$

Which implies that for  $\rho \geq e^{-n\kappa r_0^{d'} 2^{d'}}$  with probability at least  $1 - \rho$ :

$$\left| \max_{1 \leq i \leq n} g(x, X_i) - \sup g(x, \cdot) \right| \leq \frac{K_g}{2} \left( \frac{\ln(1/\rho)}{n\kappa} \right)^{1/d'}.$$

□

Armed with this lemma, we are now ready to state the non-asymptotic bound for an MPGNN with max aggregation.

**Theorem 5.17** (Non-asymptotic convergence of max-MPGNN towards cMPGNN). *Suppose,  $(\mathcal{X}, P)$  has the  $(r_0, \kappa)$ -volume retaining property and that  $f, W$  and the  $m^{(l)}$  are Lipschitz continuous. Let  $\rho \geq 2^{L-1} n e^{-n\kappa r_0^{d'} 2^{d'}}$  and  $n$  large enough for  $0 < \rho < 1$  to hold. Then with probability at least  $1 - \rho$ :*

$$(5.17) \quad \text{MAE}_X(\Theta_{G_n}(S_X(f)), \Theta_{W,P}(f)) \lesssim \left( \frac{1}{n} \ln \left( \frac{2^{L-1} n d_{\max}}{\rho} \right) \right)^{1/d'}$$

and

$$(5.18) \quad \left\| \bar{\Theta}_{G_n}(S_X(f)) - \bar{\Theta}_{W,P}(f) \right\|_\infty$$

$$\lesssim \left( \frac{1}{n} \ln \left( \frac{2^L n d_{\max}}{\rho} \right) \right)^{1/d} + \left( \frac{1}{n} \ln \left( \frac{2d_L}{\rho} \right) \right)^{1/d},$$

where  $d_{\max} = \max_i d_i$ .

Since we made an assumption that involves the volume of a  $d$ -dimensional ball, the convergence rate for *max* convolution depends on the dimension of the latent space  $\mathcal{X} \subset \mathbb{R}^d$ , where it is roughly equal to  $O(n^{-1/d})$ , as opposed to the generally faster rate  $O(n^{-1/2})$  obtained with the McDiarmid’s method from Theorem 5.11. Intuitively, this is to be expected, as the fast rate is akin to the central limit theorem, while the rate for *max* convolution follows from the number of balls necessary to cover the latent space (covering numbers), which scales exponentially in its dimension.

### 5.3. Experimental illustrations

We illustrate the convergence rates from both Theorems 5.11 and 5.17 on toy examples. One difficulty in illustrating our convergence results is that the limit cGNN cannot be computed explicitly in most cases. Moreover, since our model of random graphs always produce dense (or even complete weighted) graphs, there are quite strong computational limits to testing very large  $n$  to approximate the cGNN. Nevertheless, we found that performing several rounds of Monte-Carlo simulation (50 is our experiments) yields a reasonable approximation of the limit for the mean example (Ex. 1). Additionally, there is a trick for the *max* example (Ex. 5): when all parameters are *nonnegative*, the non-linearity is increasing and nonnegative on  $\mathbb{R}_+$  (e.g. sigmoid), and, say, the input signal lives in  $[0, 1]^d$ , the cGNN can be computed explicitly: it is obtained when all points are  $x_i = [1, \dots, 1]$ . Hence we limit our experiments to Ex. 1 and 5, and our aim is to highlight the influence of the input dimension  $d$  on the convergence rate from Theorems 5.11 and 5.17: in theory,  $O(1/\sqrt{n})$  for Ex. 1 and  $O(1/n^{1/d})$  for Ex. 5. We leave other examples for future work (in particular the generalized mean Ex. 4, which we found difficult to observe in practice).

For both experiments, the MPGNN has four layers. Each layer uses a single layer MLP with sigmoid activation function, and random weights in  $[0, 1]$ . A *mean* and a *max* aggregation are respectively used on the left and the right sides of Figure 1. The input signal is a dot product with a random vector in  $[0, 1]^d$ , and the latent variables are uniformly distributed in  $[0, 1]^d$ . Each experiment is run for  $d = 2, 3, 5$  and 10. The MAE error is averaged over 50 experiments, and the standard deviation is also reported in Figure 1.

We indeed observe that the convergence rate is in  $O(1/\sqrt{n})$  for a *mean* aggregation, no matter the dimension of the latent space. Whereas for a *max* aggregation, the speed follows  $O(1/n^{1/d})$ , with  $d$  being the latent space’s dimension. The standard deviation evolves as the error (note that the scale is logarithmic), we do not observe additional concentration phenomenon.

## 6. Conclusion

In this work, we have defined continuous counterparts of MPGNNs with very generic aggregation functions on a probability space with respect to a transition



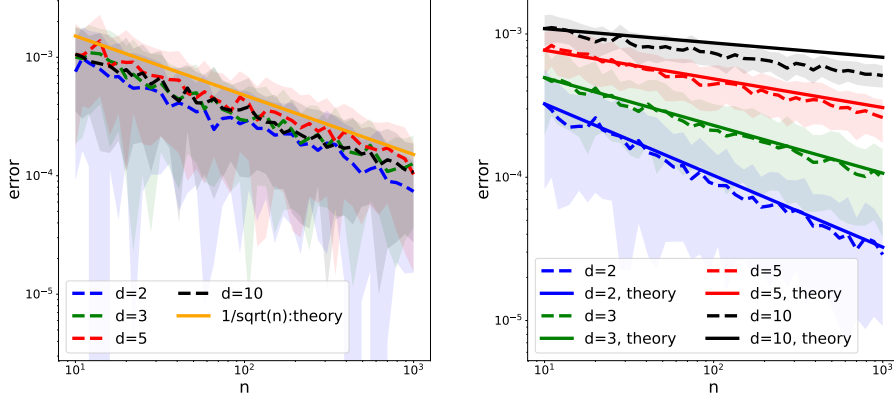


Figure 1. *Left: max aggregation. Right: mean aggregation. For both figures, the dashed lines represent the experimental error as the graph size increases, while the full lines represent the theoretical rates arising from Ths. 5.11 and 5.17. This experiment has been conducted for various values of the latent space dimension  $d$ . The theoretical rates are  $1/\sqrt{n}$  for a mean aggregation and  $1/n^{1/d}$  for a max aggregation.*

kernel. We then have shown that under certain conditions, cMPGNNs are limits of discrete MPGNNs on random graphs sampled from the corresponding random graph model. Until now, similar result were known for SGNs, which are more restricted architectures, or for MPGNNs with a degree normalized mean aggregation. Our main contribution is to extend this to abstract MPGNNs with generic aggregation functions. All along this paper, a focus is given on examples based on mean or weighted mean aggregation (Examples 1, 2 and 3) and max aggregation (Example 4), but our theorems are not limited to these examples and is in fact verified for mild assumptions on the underlying model.

Throughout this paper, we have emphasized the fact that *mean* and *max* aggregation behave differently. Albeit, a link between the two still exists: as mentioned before, the generalized mean (Ex. 4) with moment  $h = (\cdot)^{1/p}$  naturally converges to the maximum aggregation when  $p \rightarrow \infty$ . However the bounded difference proof gives a rate in  $n^{-1/2p}$ , while for the max aggregation, our specific proof based on covering numbers (Thm. 5.17) yields  $n^{-1/d}$ . This is intuitively the “worst” rate possible in dimension  $d$ , but is better when  $p > d/2$ . Hence future work could try to unify the two proofs, to obtain a smooth transition between the different rates.

## Appendices

### 7. Proof of Theorem 5.11

In all this section, we denote by  $H^{(L)}(\rho)$  the upper bound from the inequality (5.11),

$$H^{(L)}(\rho) = \sum_{l=1}^L A_n^{(l,L)} \left[ \left( \frac{1}{2} \left( D_n^{(l)} \right)^2 n \ln \left( \frac{2^{L+2-l} d_l n}{\rho} \right) \right)^{\alpha_{\psi}/2} + \bar{D}_n^{(l)} + s_n^{(l)} \right]^{\alpha_F^{L-l}}.$$

#### 7.1. Equivariant case

We start with the equivariant case. Calling  $z_i^{(l)}$  the layers of the GNN, we seek to bound:

$$\begin{aligned} \text{MAE}_X(\Theta_{G_n}(S_X f), \Theta_{W,P}(f)) &= \max_{1 \leq i \leq n} \left\| z_i^{(L)} - S_X(f^{(L)})_i \right\| \\ &= \max_{1 \leq i \leq n} \left\| z_i^{(L)} - f^{(L)}(X_i) \right\|. \end{aligned}$$

*Proof of inequality (5.11) of Theorem 5.11.* We prove the result by induction on  $L$ . Let  $\rho > 0$ . We recall some notations from Definition 5.1

$$\begin{aligned} &F_{P,n}^{(l+1)}(f^{(l)}, W)(x) \\ &= \mathbb{E}_{X_2, \dots, X_n} \left[ F^{(l+1)} \left( f^{(l)}(x), \left\{ \left( f^{(l)}(X_k), W(x, X_k) \right) \right\}_{2 \leq k \leq n} \right) \right], \end{aligned}$$

and,

$$\mathcal{F}_P^{(l+1)}(f^{(l)}, W)(x) = \mathcal{F}_P^{(l+1)} \left( f^{(l)}(x), \left( f^{(l)}, W(x, \cdot) \right) \right) = f^{(l+1)}(x).$$

Suppose  $L = 1$ , we shall find a quantity that bounds all the  $\left\| z_i^{(1)} - f^{(1)}(X_i) \right\|$  for  $i$  ranging from 1 to  $n$ , with probability at least  $1 - \rho/n$ . Thereby, by a union bound, this quantity will bound their maximum with probability at least  $1 - \rho$ . Choose  $i \in \{1, \dots, n\}$  and  $x_i \in \mathcal{X}$ , consider

$$\left\| F^{(1)} \left( f^{(0)}(x_i), \left\{ \left( f^{(0)}(X_k), W(x_i, X_k) \right) \right\}_{k \neq i} \right) - f^{(1)}(x_i) \right\|_{\infty}.$$

From a triangular inequality, and by definition of  $s_n$ .

$$\begin{aligned} &\left\| F^{(1)} \left( f^{(0)}(x_i), \left\{ \left( f^{(0)}(X_k), W(x_i, X_k) \right) \right\}_{k \neq i} \right) - f^{(1)}(x_i) \right\|_{\infty} \\ &\leq \left\| F^{(1)} \left( f^{(0)}(x_i), \left\{ \left( f^{(0)}(X_k), W(x_i, X_k) \right) \right\}_{k \neq i} \right) - F_{P,n}^{(1)}(f^{(0)}, W)(x_i) \right\|_{\infty} \\ &\quad + \left\| F_{P,n}^{(1)}(f^{(0)}, W)(x_i) - f^{(1)}(x_i) \right\|_{\infty} \\ (7.1) \quad &\leq \left\| F^{(1)} \left( f^{(0)}(x_i), \left\{ \left( f^{(0)}(X_k), W(x_i, X_k) \right) \right\}_{k \neq i} \right) - F_{P,n}^{(1)}(f^{(0)}, W)(x_i) \right\|_{\infty} + s_n^{(1)} \end{aligned}$$

Now let us bound (7.1) with high probability using the Hölder version of McDiarmid's inequality (Cor. 10.3) on

$$(x_1, \dots, x_{i-1}, x_{i+1}, \dots, x_n) \mapsto F^{(1)} \left( f^{(0)}(x_i), \left\{ \left( f^{(0)}(x_k), W(x_i, x_k) \right) \right\}_{k \neq i} \right),$$

as a multivariate function of the  $n - 1$  variables  $x_k$  for  $k \neq i$ . We obtain that for any  $x_i$ , with probability at least  $1 - \rho/n$ ,

$$(7.2) \quad \left\| F^{(1)} \left( f^{(0)}(x_i), \left\{ \left( f^{(0)}(X_k), W(x_i, X_k) \right) \right\}_{k \neq i} \right) - f^{(1)}(x_i) \right\|_{\infty} \\ \leq \left( \frac{1}{2} \left( D_n^{(1)} \right)^2 n \ln \left( \frac{2d_1 n}{\rho} \right) \right)^{\alpha_{\psi}/2} + \bar{D}_n^{(1)} + s_n^{(1)}.$$

Hence, by conditioning over  $X_i$  and applying the law of total probability, (7.2) yields with probability at least  $1 - \rho/n$

$$\left\| z_i^{(1)} - f^{(1)}(X_i) \right\|_{\infty} \leq \left( \frac{1}{2} \left( D_n^{(1)} \right)^2 n \ln \left( \frac{2d_1 n}{\rho} \right) \right)^{\alpha_{\psi}/2} + \bar{D}_n^{(1)} + s_n^{(1)}.$$

And, by a union bound, we can conclude that with probability at least  $1 - \rho$

$$\max_i \left\| z_i^{(1)} - f^{(1)}(X_i) \right\|_{\infty} \leq \left( \frac{1}{2} \left( D_n^{(1)} \right)^2 n \ln \left( \frac{2d_1 n}{\rho} \right) \right)^{\alpha_{\psi}/2} + \bar{D}_n^{(1)} + s_n^{(1)} \leq H^{(1)}(\rho),$$

which proves the case  $L = 1$ .

Now, suppose the theorem true for  $L \geq 1$ . For any node  $i$ ,

$$(7.3) \quad \left\| z_i^{(L+1)} - f^{(L+1)}(X_i) \right\|_{\infty} \\ \leq \left\| z_i^{(L+1)} - F_{P,n}^{(L+1)}(f^{(L)}, W)(X_i) \right\|_{\infty} \\ + \left\| F_{P,n}^{(L+1)}(f^{(L)}, W)(X_i) + f^{(L+1)}(X_i) \right\|_{\infty} \\ \leq \left\| z_i^{(L+1)} - F_{P,n}^{(L+1)}(f^{(L)}, W)(X_i) \right\|_{\infty} + s_n^{(L+1)} \\ \leq \left\| z_i^{(L+1)} - F^{(L+1)} \left( f^{(L)}(X_i), \left\{ \left( f^{(L)}(X_k), W(X_i, X_k) \right) \right\}_{k \neq i} \right) \right\|_{\infty} \\ + \left\| F^{(L+1)} \left( f^{(L)}(X_i), \left\{ \left( f^{(L)}(X_k), W(X_i, X_k) \right) \right\}_{k \neq i} \right) - F_{P,n}^{(L+1)}(f^{(L)}, W)(X_i) \right\|_{\infty} + s_n^{(L+1)} \\ \leq K_{F,n}^{(L+1)} \max_i \left\| z_i^{(L)} - f^{(L)}(X_i) \right\|_{\infty}^{\alpha_F} \\ + \left\| F^{(L+1)} \left( f^{(L)}(X_i), \left\{ \left( f^{(L)}(X_k), W(X_i, X_k) \right) \right\}_{k \neq i} \right) - F_{P,n}^{(L+1)}(f^{(L)}, W)(X_i) \right\|_{\infty} + s_n^{(L+1)},$$

where the last inequality comes from the Holder-like regularity Assumption 5.9 on  $F^{(L+1)}$ . Taking the maximum over the vertices, the inequality (7.3) yields

$$\begin{aligned}
& \max_i \left\| z_i^{(L+1)} - f^{(L+1)}(X_i) \right\|_\infty \\
& \leq K_{F,n}^{(L+1)} \max_i \left\| z_i^{(L)} - f^{(L)}(X_i) \right\|_\infty^{\alpha_F} \\
(7.4) \quad & + \max_i \left\| F^{(L+1)} \left( f(X_i), \left\{ (f(X_k), W(X_i, X_k)) \right\}_{k \neq i} \right) - F_{P,n}^{(L+1)}(f^{(L)}, W)(X_i) \right\|_\infty + s_n^{(L+1)}.
\end{aligned}$$

Finally, we bound (7.4) with high probability. The first term is handled by the induction hypothesis. For the second term, we employ the same technique as we did in the case  $L = 1$ . By conditioning over  $X_i$ , using the Hölder version McDiarmid's inequality, and a union bound, we obtain with probability at least  $1 - \rho$ ,

$$\begin{aligned}
& \max_i \left\| z_i^{(L+1)} - f^{(L+1)}(X_i) \right\|_\infty \\
& \leq K_{F,n}^{(L+1)} H^{(L)}(\rho/2)^{\alpha_F} + \left( \frac{1}{2} \left( D_n^{(L+1)} \right)^2 n \ln \left( \frac{4d_{L+1}n}{\rho} \right) \right)^{\alpha_\psi/2} + \bar{D}_n^{(L+1)} + s_n^{(L+1)} \\
& \leq K_{F,n}^{(L+1)} \left( \sum_{l=1}^L A_n^{(l,L)} \left[ \left( \frac{1}{2} \left( D_n^{(l)} \right)^2 n \ln \left( \frac{2^{L+3-l} d_l n}{\rho} \right) \right)^{\alpha_\psi/2} + \bar{D}_n^{(l)} + s_n^{(l)} \right]^{\alpha_F^{L-l}} \right)^{\alpha_F} \\
& \quad + \left( \frac{1}{2} \left( D_n^{(L+1)} \right)^2 n \ln \left( \frac{4d_{L+1}n}{\rho} \right) \right)^{\alpha_\psi/2} + \bar{D}_n^{(L+1)} + s_n^{(L+1)} \\
& \leq \sum_{l=1}^L K_{F,n}^{(L+1)} (A_n^{(l,L)})^{\alpha_F} \left[ \left( \frac{1}{2} \left( D_n^{(l)} \right)^2 n \ln \left( \frac{2^{L+3-l} d_l n}{\rho} \right) \right)^{\alpha_\psi/2} + \bar{D}_n^{(l)} + s_n^{(l)} \right]^{\alpha_F^{L+1-l}} \\
& \quad + \left( \frac{1}{2} \left( D_n^{(L+1)} \right)^2 n \ln \left( \frac{4d_{L+1}n}{\rho} \right) \right)^{\alpha_\psi/2} + \bar{D}_n^{(L+1)} + s_n^{(L+1)} \\
& = H^{(L+1)}(\rho).
\end{aligned}$$

where we have used that  $(x + y)^a \leq x^a + y^a$  for  $a \leq 1$ , as well as the recursive expression  $A^{(l,l)} = 1$  and  $A^{(l,L+1)} = K_{F,n}^{(L+1)} (A^{(l,L)})^{\alpha_F}$ , which yields the result.  $\square$

## 7.2. Invariant case

For the invariant case, it follows as a corollary of inequality (5.11). We use the bound of the equivariant case previously obtained, and we make additional use of McDiarmid's concentration bound.

*Proof of inequality (5.12) of Theorem 5.11.* Under Assumptions 5.7, 5.8, 5.9, and also 5.10, we the following inequality.

$$\left\| \bar{\Theta}_{G_n}(S_X(f)) - \bar{\Theta}_{W,P}(f) \right\|_\infty$$

$$\begin{aligned}
&\leq \left\| R \left( \left\{ z_1^{(L)}, \dots, z_n^{(L)} \right\} \right) - R \left( \left\{ f^{(L)}(X_1), \dots, f^{(L)}(X_n) \right\} \right) \right\|_\infty \\
&\quad + \left\| R \left( \left\{ f^{(L)}(X_1), \dots, f^{(L)}(X_n) \right\} \right) - R_{P,n}(f^{(L)}) \right\|_\infty \\
&\quad + \left\| R_{P,n}(f^{(L)}) - \mathcal{R}_P(f^{(L)}) \right\|_\infty \\
&\leq K_{R,n} \max_i \left\| z_i^{(L)} - f^{(L)}(X_i) \right\|_\infty \\
&\quad + \left\| R \left( \left\{ f^{(L)}(X_1), \dots, f^{(L)}(X_n) \right\} \right) - R_{P,n}(f^{(L)}) \right\|_\infty + r_n.
\end{aligned}$$

Using a union bound, inequality (5.11) and McDiarmid's inequality, we get that, with probability at least  $1 - \rho$ :

$$\left\| \bar{\Theta}_{G_n}(S_X(f)) - \bar{\Theta}_{W,P}(f) \right\|_\infty \leq K_{R,n} H^{(L)}(\rho/2) + C_n \sqrt{n \ln \left( \frac{4d_L}{\rho} \right)} + r_n,$$

which concludes the proof.  $\square$

## 8. Proof of Theorem 5.17

We will need the following property.

**Proposition 8.1.** *Under the hypothesis of Theorem 5.17, The functions  $f^{(0)}, \dots, f^{(L)}$  are Lipschitz continuous. We denote by  $K_f = K_{f^{(0)}}, \dots, K_{f^{(L)}}$  their Lipschitz constants.*

*Proof.* It is already assumed for  $l = 0$ . Suppose it is true for  $l \geq 1$ ,  $f^{(l+1)}(x) = \sup_y W(x, y) m^{(l+1)}(f^{(l)}(y)) = \sup_y g(x, y)$  where  $g$  is  $K_W \|m^{(l+1)} \circ f^{(l)}\|_\infty + K_{m^{(l)}} K_{f^{(l)}}$  Lipschitz. Then from Lemma 10.6  $f^{(l+1)}$  is also Lipschitz.  $\square$

### 8.1. Equivariant case

We will prove the following sharper version of Theorem 5.17.

**Theorem 8.2.** *Suppose,  $(\mathcal{X}, P)$  has the  $(r_0, \kappa)$ -volume retaining property and that  $f, W$  and the  $m^{(l)}$  are Lipschitz continuous. Let  $\rho \geq 2^{L-1} n e^{-n\kappa r_0^{d_0} 2^{d_0}}$  and  $n$  large enough for  $0 < \rho < 1$  to hold. Then with probability at least  $1 - \rho$ :*

$$\begin{aligned}
(8.1) \quad &\max_{1 \leq i \leq n} \left\| (S_X f)_i^{(L)} - f^{(L)}(X_i) \right\|_\infty \\
&\leq \sum_{l=1}^L B^{(l,L)} \frac{K_{f^{(l)}}}{2} \left( \frac{1}{n\kappa} \ln \left( \frac{2^{L+1-l} n d_l}{\rho} \right) \right)^{1/d}.
\end{aligned}$$

Where  $B^{(l,L)} = \prod_{k=l+1}^L K_{m^{(k)}}$  with the conventions  $\prod_{k=a}^b = 1$ .

**Corollary 8.3** (Theorem 5.17 in the main text). *Suppose,  $(\mathcal{X}, P)$  has the  $(r_0, \kappa)$ -volume retaining property and that  $f, W$  and the  $m^{(l)}$  are Lipschitz continuous. Let  $\rho \geq 2^{L-1} n e^{-n\kappa r_0^{d_0} 2^{d_0}}$  and  $n$  large enough for  $0 < \rho < 1$  to hold. Then with probability at least  $1 - \rho$ :*

$$\max_{1 \leq i \leq n} \left\| (S_X f)_i^{(L)} - f^{(L)}(X_i) \right\|_\infty \lesssim L \left( \frac{1}{n} \ln \left( \frac{2^{L-1} n d_{\max}}{\rho} \right) \right)^{1/d}.$$

*Proof of theorem 8.2.* Let  $\rho > 0$ . We will prove the theorem by induction on  $L$ . Until the end of the proof, we denote by  $H^{(L)}(\rho)$  the bound (8.1):

$$H^{(L)}(\rho) = \sum_{l=1}^L B^{(l,L)} \frac{K_{f^{(l)}}}{2} \left( \frac{1}{n\kappa} \ln \left( \frac{2^{L+1-l} n d_l}{\rho} \right) \right)^{1/d}.$$

For  $L = 1$ , let us note  $g(x, y) = W(x, y) m^{(1)}(f^{(0)}(y))$ . The map  $g$  is  $K_{f^{(1)}} = K_{m^{(1)}} K_{f^{(0)}} + \|m^{(1)} \circ f^{(0)}\|_{\infty} K_W$  Lipschitz continuous from Property 8.1. Fix  $i \in \{1, \dots, n\}$  and  $x_i \in \mathcal{X}$ , by lemma 5.16, for  $\rho \geq n e^{-n\kappa r_0^{d_0} 2^d}$ , with probability at least  $1 - \rho/n$ , we have

$$\left\| \max_{j \neq i} g(x, X_j) - \sup_{y \in \mathcal{X}} g(x, y) \right\|_{\infty} \leq \frac{K_{f^{(1)}}}{2} \left( \frac{1}{(n-1)\kappa} \ln \left( \frac{n d_0}{\rho} \right) \right)^{1/d}, \quad \forall x \in \mathcal{X}.$$

Thus, by the law of total probability, with probability at least  $1 - \rho/n$ ,

$$\left\| \max_{j \neq i} g(X_i, X_j) - \sup_{y \in \mathcal{X}} g(X_i, y) \right\|_{\infty} \leq \frac{K_{f^{(1)}}}{2} \left( \frac{1}{(n-1)\kappa} \ln \left( \frac{n d_0}{\rho} \right) \right)^{1/d}.$$

And by maximizing over  $i$  and doing a union bound, for  $\rho \geq n e^{-n\kappa r_0^{d_0} 2^d}$ , with probability at least  $1 - \rho$ :

$$\max_i \left\| (S_X f)_i^{(1)} - f^{(1)}(X_i) \right\|_{\infty} \leq \frac{K_{f^{(1)}}}{2} \left( \frac{1}{(n-1)\kappa} \ln \left( \frac{n d_0}{\rho} \right) \right)^{1/d} \leq H^{(1)}(\rho).$$

That concludes the case  $L = 1$ . Now let  $L \geq 1$ , fix  $i \in \{1, \dots, n\}$ :

$$\begin{aligned} (8.2) \quad & \left\| (S_X f)_i^{(L+1)} - f^{(L+1)}(X_i) \right\|_{\infty} \\ &= \left\| \max_{j \neq i} W(X_i, X_j) m^{(L+1)}((S_X f)_j^{(L)}) - f^{(L+1)}(X_j) \right\|_{\infty} \\ &\leq \left\| \max_{j \neq i} W(X_i, X_j) m^{(L+1)}((S_X f)_j^{(L)}) - \max_{j \neq i} W(X_i, X_j) m^{(L+1)}(f^{(L)}(X_j)) \right\|_{\infty} \\ &\quad + \left\| \max_{j \neq i} W(X_i, X_j) m^{(L+1)}(f^{(L)}(X_j)) - \sup_{y \in \mathcal{X}} W(X_i, y) m^{(L+1)}(f^{(L)}(y)) \right\|_{\infty} \\ &\leq K_{m^{(L+1)}} \max_{j \neq i} \left\| (S_X f)_j^{(L)} - f^{(L)}(X_j) \right\|_{\infty} \\ &\quad + \left\| \max_{j \neq i} W(X_i, X_j) m^{(L+1)}(f^{(L)}(X_j)) - \sup_{y \in \mathcal{X}} W(X_i, y) m^{(L+1)}(f^{(L)}(y)) \right\|_{\infty}. \end{aligned}$$

Where the last inequality uses Lemma 10.5,  $|W| \leq 1$ , and Lipschitz continuity of  $m^{(L+1)}$ . Thus taking the maximum over  $i$ :

$$\begin{aligned} (8.3) \quad & \max_i \left\| (S_X f)_i^{(L+1)} - f^{(L+1)}(X_i) \right\|_{\infty} \\ &\leq K_{m^{(L+1)}} \max_i \left\| (S_X f)_i^{(L)} - f^{(L)}(X_i) \right\|_{\infty} \\ &\quad + \max_i \left\| \max_{j \neq i} W(X_i, X_j) m^{(L+1)}(f^{(L)}(X_j)) - \sup_{y \in \mathcal{X}} W(X_i, y) m^{(L+1)}(f^{(L)}(y)) \right\|_{\infty}. \end{aligned}$$

Now we bound (8.3) with high probability. We use the induction hypothesis for the first term. For the second term, we set  $g(x, y) = W(x, y)m^{(L+1)}(f^{(L)}(y))$  and use lemma 5.16 on  $g$  which is  $K_{f^{(L+1)}} = K_{m^{(L+1)}}K_{f^{(L)}} + \|m^{(L+1)} \circ f^{(L)}\|_\infty K_W$  Lipschitz. The method is the same as in the case  $L = 1$  and by conditioning over  $X_i$  followed by a union bound. We obtain that for  $\rho \geq 2^L n e^{-n\kappa r_0^d 2^d}$ , with probability at least  $1 - \rho$ :

$$\begin{aligned}
& \max_i \left\| (S_X f)_i^{(L+1)} - f^{(L+1)}(X_i) \right\|_\infty \\
& \leq K_{m^{(L+1)}} H^{(L)}(\rho/2) + \frac{K_{f^{(L+1)}}}{2} \left( \frac{1}{(n-1)\kappa} \ln \left( \frac{2nd_L}{\rho} \right) \right)^{1/d} \\
& = \sum_{l=2}^L K_{m^{(L+1)}} B^{(l,L)} \frac{K_{f^{(l)}}}{2} \left( \frac{1}{(n-1)\kappa} \ln \left( \frac{2^{L+2-l}nd_l}{\rho} \right) \right)^{1/d} \\
& \quad + K_{m^{(L+1)}} B^{(1,L)} \frac{K_{f^{(1)}}}{2} \left( \frac{1}{(n-1)\kappa} \ln \left( \frac{2^L nd_0}{\rho} \right) \right)^{1/d} \\
& \quad + \frac{K_{f^{(L+1)}}}{2} \left( \frac{1}{(n-1)\kappa} \ln \left( \frac{2nd_L}{\rho} \right) \right)^{1/d} \\
& = \sum_{l=2}^L B^{(l,L+1)} \frac{K_{f^{(l)}}}{2} \left( \frac{1}{(n-1)\kappa} \ln \left( \frac{2^{L+2-l}nd_l}{\rho} \right) \right)^{1/d} \\
& \quad + B^{(1,L+1)} \frac{K_{f^{(1)}}}{2} \left( \frac{1}{(n-1)\kappa} \ln \left( \frac{2^L nd_0}{\rho} \right) \right)^{1/d} \\
& \quad + \frac{K_{f^{(L+1)}}}{2} \left( \frac{1}{(n-1)\kappa} \ln \left( \frac{2nd_L}{\rho} \right) \right)^{1/d} \\
& = \sum_{l=2}^{L+1} B^{(l,L+1)} \frac{K_{f^{(l)}}}{2} \left( \frac{1}{(n-1)\kappa} \ln \left( \frac{2^{L+2-l}nd_l}{\rho} \right) \right)^{1/d} \\
& \quad + B^{(1,L+1)} \frac{K_{f^{(1)}}}{2} \left( \frac{1}{(n-1)\kappa} \ln \left( \frac{2^L nd_0}{\rho} \right) \right)^{1/d} \\
& \leq H^{(L+1)}(\rho).
\end{aligned}$$

□

## 8.2. Invariant case

**Theorem 8.4.** *Suppose,  $(\mathcal{X}, P)$  has the  $(r_0, \kappa)$ -volume retaining property and that  $f, W$  and the  $m^{(l)}$  are Lipschitz continuous. Let  $\rho \geq 2^{L-1} n e^{-n\kappa r_0^d 2^d}$  and  $n$  large enough for  $0 < \rho < 1$  to hold. Then with probability at least  $1 - \rho$ :*

$$\| \bar{\Theta}_{G_n}(S_X(f)) - \bar{\Theta}_{W,P}(f) \|_\infty \lesssim L \left( \frac{1}{n-1} \ln \left( \frac{2^L nd_{\max}}{\rho} \right) \right)^{1/d} + \left( \frac{1}{n} \ln \left( \frac{2d_L}{\rho} \right) \right)^{1/d}.$$

*Proof.*

$$\begin{aligned}
& \left\| \bar{\Theta}_{G_n}(S_X(f)) - \bar{\Theta}_{W,P}(f) \right\|_\infty = \left\| \max_i (S_X f)_i^{(L)} - \sup f^{(L)} \right\|_\infty \\
& \leq \left\| \max_i (S_X f)_i^{(L)} - \max_i f^{(L)}(X_i) \right\|_\infty + \left\| \max_i f^{(L)}(X_i) - \sup f^{(L)} \right\|_\infty \\
& \leq \max_i \left\| (S_X f)_i^{(L)} - f^{(L)}(X_i) \right\|_\infty + \left\| \max_i f^{(L)}(X_i) - \sup f^{(L)} \right\|_\infty.
\end{aligned}$$

Using the bound for the equivariant case and Lemma 5.16 on  $f^{(L)}$ , we obtain the result.  $\square$

## 9. Examples

In this section, we put all computations related to the examples: we prove Prop. 5.5 and 5.14. For notational convenience, we drop any subscript or superscript ( $l$ ) referring to layers. Recall that  $m = m^{(l)}$  is supposed Lipschitz and bounded, we denote  $K_m$  its Lipschitz constant and  $\|m\|_\infty = \sup_x \|m(x)\|_\infty$  (on the respective domain of  $x$  at each layer). We divide this section in subsections for each example.

### 9.1. Examples 1-a: Convolutional message passing with mean aggregation

Prop. 5.5 for Example 1-a. By independence and identical distribution of the random variables and linearity of the expected value, the convergence in (5.5) is actually an equality for all integer  $n$ . For all  $x$ :

$$\mathbb{E} \left[ \frac{1}{n} \sum_i W(x, X_i) m(f(X_i)) \right] = \mathbb{E} [W(x, X_1) m(f(X_1))] = \int_{\mathcal{X}} W(x, y) m(y) dP(y).$$

Clearly this remains true replacing  $P$  by  $\phi \cdot P$ ,  $f$  by  $\phi \cdot f$  and  $W$  by  $\phi \cdot W$  for any  $\phi \in \text{Aut}(\mathcal{X})$ .

Assumption 5.8 for Example 1-a. The above calculation yields  $s_n = 0$ .

Assumption 5.7 for Example 1-a. We consider  $\psi = Id$ , such that  $\bar{D}_n = 0$  and  $K_\psi = 1$ .

Let  $x_1, \dots, x_n$  and  $x'_2, \dots, x'_n$  be such that  $x_i = x'_i$  except at  $k = 2$ .

$$\begin{aligned}
& \left\| F \left( f(x_1), \left\{ \left( f(x_i), W(x_1, x_i) \right) \right\}_{2 \leq i \leq n} \right) - F \left( f(x_1), \left\{ \left( f(x'_i), W(x_1, x'_i) \right) \right\}_{2 \leq i \leq n} \right) \right\|_\infty \\
& = \frac{1}{n-1} \left\| W(x_1, x_2) m(f(x_2)) - W(x_1, x'_2) m(f(x'_2)) \right\|_\infty \\
& = 2 \|m\|_\infty / (n-1) = O(1/n).
\end{aligned}$$

Since  $m$  is bounded. Hence,  $D_n = O(1/n)$ .

Assumption 5.9 for Example 1-a. We have

$$\begin{aligned}
& \left\| F(z_1, \left\{ (z_i, w_i) \right\}_{i \geq 2}) - F(z'_1, \left\{ (z'_i, w_i) \right\}_{i \geq 2}) \right\|_\infty \\
& \leq \left\| \frac{1}{n-1} \sum_{2 \leq i \leq n} w_i m(z_i) - \frac{1}{n-1} \sum_{2 \leq i \leq n} w_i m(z'_i) \right\|_\infty \\
& \leq K_m \max_i \|z_i - z'_i\|_\infty.
\end{aligned}$$

Hence Assumption 5.9 is satisfied with  $K_{F,n} = K_m$  and  $\alpha_F = 1$ .



## 9.2. Example 2 and b: Degree normalized message passing

Recall here that we assume that  $W(\cdot, \cdot) \geq a > 0$ .

Prop. 5.5 for Example 2-b. We have for all  $x$

$$\int_{\mathcal{X}} \frac{W(x, y)m(f(y))}{\int_{\mathcal{X}} W(x, t)dP(t)} dP(y) = \frac{\mathbb{E}[W(x, X)m(f(X))]}{\mathbb{E}[W(x, X)]},$$

where  $X \sim P$ . Let  $x \in \mathcal{X}$  be fixed. For simplicity, we compute  $s_{n+1}$  (i.e. we consider  $n$  random variables and not  $n-1$ ) Then

$$\begin{aligned} & \left\| \mathbb{E}_{X_i} \left[ \frac{\frac{1}{n} \sum_i W(x, X_i)m(f(X_i))}{\frac{1}{n} \sum_i W(x, X_i)} \right] - \frac{\mathbb{E}[W(x, X)m(f(X))]}{\mathbb{E}[W(x, X)]} \right\|_{\infty} \\ &= \left\| \mathbb{E}_{X_i} \left[ \frac{\frac{1}{n} \sum_i W(x, X_i)m(f(X_i))}{\frac{1}{n} \sum_i W(x, X_i)} - \frac{\mathbb{E}[W(x, X)m(f(X))]}{\mathbb{E}[W(x, X)]} \right] \right\|_{\infty} \\ &\leq \mathbb{E}_{X_i} \left[ \left\| \frac{\frac{1}{n} \sum_i W(x, X_i)m(f(X_i))}{\frac{1}{n} \sum_i W(x, X_i)} - \frac{\mathbb{E}[W(x, X)m(f(X))]}{\mathbb{E}[W(x, X)]} \right\|_{\infty} \right] \\ &\leq \mathbb{E} \left[ \left\| \frac{1}{n} \sum_i W(x, X_i)m(f(X_i)) \right\|_{\infty} \left| \frac{1}{\frac{1}{n} \sum_i W(x, X_i)} - \frac{1}{\mathbb{E}[W(x, X)]} \right| \right. \\ &\quad \left. + \left\| \frac{1}{n} \sum_i W(x, X_i)m(f(X_i)) - \mathbb{E}[W(x, X)m(f(X))] \right\|_{\infty} \left| \frac{1}{\mathbb{E}[W(x, X)]} \right| \right] \\ &\leq \frac{\|m\|_{\infty}}{a^2} \mathbb{E} \left[ \left\| \frac{1}{n} \sum_i W(x, X_i) - \mathbb{E}[W(x, X)] \right\| \right] \\ &\quad + \frac{1}{a} \mathbb{E} \left[ \left\| \frac{1}{n} \sum_i W(x, X_i)m(f(X_i)) - \mathbb{E}[W(x, X)m(f(X))] \right\|_{\infty} \right], \end{aligned}$$

since  $0 < a \leq W \leq 1$ . Consequently, using the formula  $\mathbb{E}(X) = \int_{t>0} \mathbb{P}(X > t)dt$  for  $X$  nonnegative, we get that this last quantity is equal to

$$(9.1) \quad \begin{aligned} & \frac{1}{a} \int_{t>0} \mathbb{P} \left( \left\| \frac{1}{n} \sum_i W(x, X_i)m(f(X_i)) - \mathbb{E}[W(x, X)m(f(X))] \right\|_{\infty} > t \right) dt \\ & + \frac{\|m\|_{\infty}}{a^2} \int_{t>0} \mathbb{P} \left( \left| \mathbb{E}[W(x, X)] - \frac{1}{n} \sum_i W(x, X_i) \right| > t \right) dt. \end{aligned}$$

Finally, we use McDiarmid inequality (which turns out to be the same as Hoeffding inequality for a sum of independent random variables). It is easy to check that the concerned multivariate maps have bounded differences of the form  $c_i = C/n$  for all  $i$ . Therefore, there are some positive constants  $C_1, C_2$  independent of  $x$  such that (9.1) is bounded by

$$C_1 \int_{t>0} e^{-nC_2 t^2} dt = O(1/\sqrt{n}) \rightarrow 0.$$

Since this is true for all  $x$  and this bound is independent of  $x$ , we obtain convergence in  $L_P^{\infty}$  norm. This remains true replacing  $P$  by  $\phi \cdot P$ ,  $f$  by  $\phi \cdot f$  and  $W$  by  $\phi \cdot W$  for any  $\phi \in \text{Aut}(\mathcal{X})$ . Hence we have shown Prop. 5.5.

Assumption 5.8 for Example 2-b. The above calculation yields  $s_n = O(1/\sqrt{n})$ .

Assumption 5.7 for Example 2-b. Let us first introduce some intermediate computations.

Let  $x_1, \dots, x_n$  and  $x'_2, \dots, x'_n$  be such that  $x_i = x'_i$  except at  $i = 2$ . Denote by  $z_i = f(x_i)$ ,  $z'_i = f(x'_i)$ ,  $w_i = W(x_1, x_i)$ , and  $w'_i = W(x'_1, x'_i)$  for short.

$$\begin{aligned}
& \left\| F \left( f(x_1), \left\{ \left( f(x_i), W(x_1, x_i) \right) \right\}_{2 \leq i \leq n} \right) - F \left( f(x_1), \left\{ \left( f(x'_i), W(x_1, x'_i) \right) \right\}_{2 \leq i \leq n} \right) \right\|_\infty \\
&= \left\| \frac{\sum_{2 \leq i \leq n} w_i m(z_i)}{\sum_i w_i} - \frac{\sum_{2 \leq i \leq n} w'_i m(z'_i)}{\sum_i w'_i} \right\|_\infty \\
&\leq \frac{1}{\sum_i w_i} \left\| \sum_i w_i m(z_i) - \sum_i w'_i m(z'_i) \right\|_\infty + \left\| \sum_i w'_i m(z'_i) \right\|_\infty \left| \frac{1}{\sum_i w_i} - \frac{1}{\sum_i w'_i} \right| \\
(9.2) \quad &\leq \frac{1}{(n-1)a} \left\| \sum_i w_i m(z_i) - \sum_i w'_i m(z'_i) \right\|_\infty + \frac{\|m\|_\infty}{(n-1)a^2} \left| \sum_i w_i - \sum_i w'_i \right|.
\end{aligned}$$

Then, again we consider  $\psi = Id$ , such that  $\bar{D}_n = 0$  and  $K_\psi = 1$ . Applying (9.2) with  $z_i = z'_i$  and  $w_i = w'_i$  except for  $i = 2$ , we prove Assumption 5.7 with

$$D_n = \frac{1}{(n-1)a} + \frac{\|m\|_\infty}{(n-1)a^2} = O(1/n).$$

Assumption 5.9 for Example 2-b. Again using (9.2) with  $w_i = w'_i$  and using the Lipschitz property of  $m$ ,

$$\begin{aligned}
& \left\| F \left( f(x_1), \left\{ \left( f(x_i), W(x_1, x_i) \right) \right\}_{2 \leq i \leq n} \right) - F \left( f(x_1), \left\{ \left( f(x'_i), W(x_1, x'_i) \right) \right\}_{2 \leq i \leq n} \right) \right\|_\infty \\
&\leq \frac{1}{(n-1)a} \left\| \sum_i w_i m(z_i) - \sum_i w_i m(z'_i) \right\|_\infty \\
&\leq \frac{K_m}{a} \max_i \|z_i - z'_i\|_\infty.
\end{aligned}$$

Hence we prove Assumption 5.9 with  $K_F = \frac{K_m}{a}$ .

### 9.3. Example 3-c: Attentional message passing

Call  $V(x, y) = c(f(x), f(y), W(x, y))$ . We are basically brought to the previous example with  $V$  instead of  $W$ .

Prop. 5.5 for Example 3-c. Using  $V$  instead of  $W$ , we have the previous example and therefore Prop. 5.5.

Assumption 5.8 for Example 3-c. By the same argument Assumption 5.8, is fulfilled with  $s_n = O(1/\sqrt{n})$ .

Assumption 5.7 for Example 3-c. From the previous Example, equation (9.2) stays valid with  $w_i = V(x_1, x_i)$ ,  $w'_i = V(x'_1, x'_i)$  instead of  $W$ . Hence Assumption 5.7 is proven with  $D_n = O(1/\sqrt{n})$ .

Assumption 5.9 for Example 3-c. Again  $\psi = Id$ . Using again eq. (9.2) but with  $t_i = c(z_1, z_i, w_i)$  and  $c(x, y, w) \leq b$  and  $|c(x, y, w) - c(x', y', w)| \leq K_c(\|x - x'\|_\infty + \|y - y'\|_\infty)$ , we get

$$\begin{aligned} & \left\| F\left(z_1, \mathbb{J}(z_i, w_i)\right)_{2 \leq k \leq n} - F\left(z'_1, \mathbb{J}(z'_i, w'_i)\right)_{2 \leq k \leq n} \right\|_\infty \\ & \leq \frac{b}{(n-1)a} \left\| \sum_i w_i m(z_i) - \sum_i w'_i m(z'_i) \right\|_\infty + \frac{b\|m\|_\infty}{(n-1)a^2} \left| \sum_i w_i - \sum_i w'_i \right| \\ & \leq \frac{b}{a} \max_i \|w_i m(z_i) - w'_i m(z'_i)\|_\infty + \frac{b\|m\|_\infty}{a^2} \max_i |w_i - w'_i| \\ & \leq \frac{b}{a} \left( \|m\|_\infty K_c \left( \|z_1 - z'_1\|_\infty + \max_i \|z_i - z'_i\|_\infty \right) + bK_m \max_i \|z_i - z'_i\|_\infty \right) \\ & \quad + \frac{b\|m\|_\infty}{a^2} K_c \left( \|z_1 - z'_1\|_\infty + \max_i \|z_i - z'_i\|_\infty \right). \end{aligned}$$

Hence we have shown Assumption 5.9 with  $\alpha_F = 1$ .

#### 9.4. Example 4-d: Generalized mean

Prop. 5.5 for Example 4-d. We call  $g(x, y) = h^{-1}(W(x, y)m(f(y)))$  and again consider  $n$  neighbors (instead of  $n-1$ ). For any fixed  $x \in \mathcal{X}$ , we have

$$\begin{aligned} & \left\| \mathbb{E}_{X_i} \left[ h\left(\frac{1}{n} \sum_i g(x, X_i)\right) \right] - h(\mathbb{E}_X [g(x, X)]) \right\|_\infty \\ & \leq \mathbb{E}_{X_i} \left[ \left\| h\left(\frac{1}{n} \sum_i g(x, X_i)\right) - h(\mathbb{E}_X [g(x, X)]) \right\|_\infty \right] \\ & \leq K_h \mathbb{E}_{X_i} \left[ \left\| \frac{1}{n} \sum_i g(x, X_i) - \mathbb{E}_X g(x, X) \right\|_\infty^{\alpha_h} \right]. \end{aligned}$$

Again, this is equal to

$$K_h \int_t \mathbb{P} \left( \left\| \frac{1}{n} \sum_i \bar{g}(x, X_i) - \mathbb{E} [\bar{g}(x, X)] \right\|_\infty^{\alpha_h} > t \right) dt,$$

and since  $h^{-1}$  is bounded we can use Hoeffding's inequality to show that this is bounded for some constant  $C_1, C_2$  by

$$C_1 \int_{t>0} e^{-nC_2 t^{2/\alpha_h}} dt = O(n^{-\frac{\alpha_h}{2}}) \rightarrow 0.$$

Since this is true for all  $x$  and this bound is independent of  $x$ , we obtain convergence in  $L_P^\infty$  norm. This remains true replacing  $P$  by  $\phi \cdot P$ ,  $f$  by  $\phi \cdot f$  and  $W$  by  $\phi \cdot W$  for any  $\phi \in \text{Aut}(\mathcal{X})$ . Hence we have shown Prop. 5.5.

Assumption 5.8 for Example 4-d. The above calculation yields  $s_n = O(n^{-\frac{\alpha_h}{2}})$ .

Assumption 5.7 for Example 4-d. Here we consider  $\psi = h$ . For item 1. of Assumption 5.7, we have

$$\psi^{-1} \left( F(f(x_1), \mathbb{J}(f(x_i), W(x_1, x_i)))_{i \geq 2} \right) = \frac{1}{n-1} \sum_{i \geq 2} h^{-1}(W(x_1, x_i)m(f(x_i))).$$

So we are brought back to Ex. 1 when  $h^{-1}$  is bounded, and therefore  $D_n = O(1/n)$ .

For item 2. of Assumption 5.7, calling again  $g(x, y) = h^{-1}(W(x, y), m(f(y)))$ , we have

$$\begin{aligned} & \left\| \psi \left( \mathbb{E} \psi^{-1} \left( F \left( f(x_1), \mathbb{1}_{\{(f(X_i), W(x_1, X_i))\}_{i \geq 2}} \right) \right) \right) - \mathbb{E} F \left( f(x_1), \mathbb{1}_{\{(f(X_i), W(x_1, X_i))\}_{i \geq 2}} \right) \right\|_{\infty} \\ &= \left\| h \left( \mathbb{E} \frac{1}{n-1} \sum_i g(x, X_i) \right) - \mathbb{E} \left[ h \left( \frac{1}{n-1} \sum_i g(x, X_i) \right) \right] \right\|_{\infty} \\ &= \left\| h(\mathbb{E}_X [g(x, X)]) - \mathbb{E}_{X_i} \left[ h \left( \frac{1}{n-1} \sum_i g(x, X_i) \right) \right] \right\|_{\infty} = O(n^{-\alpha_h/2}), \end{aligned}$$

as per the computation above for Prop. 5.5. Hence  $\bar{D}_n = O(n^{-\alpha_h/2})$ .

Finally,  $\psi = h$  is  $\alpha_h$ -Holder so item 3. from Assumption 5.7 is satisfied with  $\alpha_{\psi} = \alpha_h$ .

Assumption 5.9 for Example 4-d. This is to be treated on a case by case manner. For the examples mentioned in Prop. 5.14:

- **Power mean.** Consider  $h = (\cdot)^{1/p}$ , and  $m(x) \geq 0$  of dimension 1 (the reasoning can be done in each dimension). Define vectors  $S, S'$  of size  $n-1$  such that  $S_i = w_i m(f(x_i))$  and similarly for  $S'$ . Denoting by  $\|S\|_p = (\sum_i S_i^p)^{1/p}$  the  $p$ -norm, we get

$$\begin{aligned} & \left| F \left( f(x_1), \mathbb{1}_{\{(f(x_i), W(x_1, x_i))\}_{2 \leq i \leq n}} \right) - F \left( f(x_1), \mathbb{1}_{\{(f(x'_i), W(x_1, x'_i))\}_{2 \leq i \leq n}} \right) \right| \\ &= \frac{1}{(n-1)^{1/p}} \left| \|S\|_p - \|S'\|_p \right| \leq \frac{1}{(n-1)^{1/p}} \|S - S'\|_p \leq \|S - S'\|_{\infty} \\ &\leq K_m \max_i \|z_i - z'_i\|_{\infty}. \end{aligned}$$

Hence  $\alpha_F = 1$ .

- **Lipschitz  $h^{-1}$ .** We have

$$\begin{aligned} & \left\| F \left( f(x_1), \mathbb{1}_{\{(f(x_i), W(x_1, x_i))\}_{2 \leq i \leq n}} \right) - F \left( f(x_1), \mathbb{1}_{\{(f(x'_i), W(x_1, x'_i))\}_{2 \leq i \leq n}} \right) \right\|_{\infty} \\ &\leq K_h \left( \frac{1}{n-1} \left\| \sum_i h^{-1}(w_i m(z_i)) - h^{-1}(w_i m(z'_i)) \right\|_{\infty} \right)^{\alpha_h} \\ &\leq K_h (K_m \max_i \|z_i - z'_i\|_{\infty})^{\alpha_h}, \end{aligned}$$

since  $h^{-1}$  is Lipschitz.

- **Lipschitz  $h$  and  $h^{-1}$**  is the previous case with  $\alpha_h = 1$ .

## 9.5. Example 5-e: Convolutional Message Passing with max aggregation

Prop. 5.5 for Example 5-e. We call  $g(x, y) = W(x, y)m(f(y))$ . We start by the case when  $g$  is real valued, since  $g$  is continuous and  $P$  is strictly positive,  $\text{ess sup}_P g(x, \cdot) = \sup g(x, \cdot)$  for all  $x$  by Lemma 10.4 in the Appendix. Let  $\varepsilon > 0$  and  $x \in \mathcal{X}$ . By

definition of the supremum and by independence of the  $X_i$ , we have that

$$\begin{aligned}
(9.3) \quad & \mathbb{P}(|\max_i g(x, X_i) - \sup g(x, \cdot)| \geq \varepsilon) \\
&= \mathbb{P}(\max_i g(x, X_i) \leq \sup g(x, \cdot) - \varepsilon) \\
&= \mathbb{P}(g(x, X_1) \leq \sup g(x, \cdot) - \varepsilon)^n \\
&= \mathbb{P}(|g(x, X_1) - \sup g(x, \cdot)| \geq \varepsilon)^n.
\end{aligned}$$

By continuity and compactness, there is  $x^* \in \mathcal{X}$  such that  $\sup g(x, \cdot) = g(x, x^*)$ , so (9.3) is equal to

$$\begin{aligned}
(9.4) \quad & \mathbb{P}(|g(x, X_1) - g(x, x^*)| \geq \varepsilon)^n \\
&= (1 - \mathbb{P}(|g(x, X_1) - g(x, x^*)| < \varepsilon))^n.
\end{aligned}$$

By continuity and compactness again,  $g$  is uniformly continuous so there is  $\delta > 0$  such that  $\|(x, X_1) - (x, x^*)\| = \|X_1 - x^*\| < \delta$  implies  $|g(x, X_1) - g(x, x^*)| < \varepsilon$ . Thus (9.4) is bounded from above by

$$(9.5) \quad (1 - \mathbb{P}(\|X_1 - x^*\| < \delta))^n = (1 - P(\mathcal{B}(x^*, \delta) \cap \mathcal{X}))^n$$

where  $\mathcal{B}(x^*, \delta)$  is the open ball of center  $x^*$  and radius  $\delta$  in  $\mathbb{R}^d$ . To finish let us justify that the measure of the  $\mathcal{B}(x^*, \delta) \cap \mathcal{X}$  when  $x$  runs over  $\mathcal{X}$  is bounded from below. Suppose this would not be the case, i.e., that the measure of a ball of radius  $\delta$  centered in  $\mathcal{X}$  could be arbitrary small. By compactness, up to subsequence extraction, we can assume there is  $(x_k) \in \mathcal{X}^{\mathbb{N}}$  such that  $x_n \rightarrow x \in \mathcal{X}$  and  $P(\mathcal{B}(x_k, \delta) \cap \mathcal{X}) \leq 1/2^k$ . Call  $U = \mathcal{B}(x, \delta/2) \cap \mathcal{X}$ , there is rank  $k_0$  such that  $\forall k \geq k_0, x_k \in U$ . Thus  $U \subset \mathcal{B}(x_k, \delta) \cap \mathcal{X} \forall k \geq k_0$  yielding  $P(U) \leq 1/2^k \forall k \geq k_0$  i.e.,  $P(U) = 0$ . Impossible since  $U$  is nonempty relative open of  $\mathcal{X}$ .

So there is  $\eta > 0$  independent of  $x$  such that  $P(\mathcal{B}(x^*, \delta) \cap \mathcal{X}) > \eta$  and, coming back to (9.5):

$$(9.6) \quad \mathbb{P}(|\max_i g(x, X_i) - \sup g(x, \cdot)| \geq \varepsilon) \leq (1 - \eta)^n.$$

If  $g$  is vector valued, say in  $\mathbb{R}^{d'}$ , call  $g_1, \dots, g_{d'}$  its components and  $\eta_k$  such that  $g_k$  satisfies (9.6) with  $\eta = \eta_k$ . Then by a union bound we have

$$(9.7) \quad \mathbb{P}(\|\max_i g(x, X_i) - \sup g(x, \cdot)\|_\infty \geq \varepsilon) \leq \sum_{k=1}^{d'} (1 - \eta_k)^n.$$

At the end of the day, by letting  $Z = \|\max_i g(x, X_i) - \sup g(x, \cdot)\|_\infty$ , we have for any  $\varepsilon > 0$ :

$$\begin{aligned}
(9.8) \quad & \|\mathbb{E}(\max_i g(x, X_i)) - \sup g(x, \cdot)\|_\infty \leq \mathbb{E}(Z) \\
&= \mathbb{E}(Z \mathbf{1}_{Z \geq \varepsilon}) + \mathbb{E}(Z \mathbf{1}_{Z < \varepsilon}) \\
&\leq 2\|g\|_\infty \sum_{k=1}^{d'} (1 - \eta_k)^n + \varepsilon.
\end{aligned}$$

Again, since the right hand side does not depend on  $x$ , this concludes the uniform convergence. To conclude the proof, we are left to check that the strict positiveness of  $P$  as well as the continuity of  $f$  and  $W$  are preserved by the action of homeomorphisms. It is clear for maps' continuity. Let  $\phi \in \text{Hom}(\mathcal{X})$  and  $U \subset \mathcal{X}$  a relative nonempty open of  $\mathcal{X}$ ,

$$\phi \cdot P(U) = P(\phi^{-1}(U)) > 0$$

since  $\phi^{-1}(U)$  is a nonempty open of  $\mathcal{X}$  as  $\phi$  is continuous.

Bounded differences are not sharp. Here we check the bounded differences are not sharp. We show that the function mapping  $(x_1, \dots, x_n)$  to  $\max_i W(x, x_i)m(f(x_i))$  has no bounded differences in  $o(1/\sqrt{n \ln n})$ .

Call  $g(x, y) = W(x, y)f^{(l-1)}(y)$ , and  $(g_1, \dots, g_{d_l})$  its components which are real functions. We suppose  $g$  not constant, so there is  $k$  such that  $g_k$  is not constant, say  $k = 1$ . By compactness and continuity of  $g_1$  there is  $x^*$  such that  $g(x, x^*) = \sup_y g(x, y)$ . Since  $g_1$  is not constant, for any  $n$ , there exist  $x_1, \dots, x_n$  such that  $g(x, x_1), \dots, g(x, x_n)$  are all strictly smaller than  $g(x, x^*)$ . Up to reordering them we suppose  $g(x, x_1) = \max_{2 \leq i \leq n} g(x, x_i)$  and call  $a = |g_1(x, x^*) - g_1(x, x_1)| > 0$ .

$$\begin{aligned} & \left\| \max\{g(x, x^*), g(x, x_2), \dots, g(x, x_n)\} - \max\{g(x, x_1), g(x, x_2), \dots, g(x, x_n)\} \right\|_\infty \\ & \geq \left| \max\{g_1(x, x^*), g_1(x, x_2), \dots, g_1(x, x_n)\} - \max\{g_1(x, x_1), g_1(x, x_2), \dots, g_1(x, x_n)\} \right| \\ & = |g_1(x, x^*) - g_1(x, x_1)| \\ & > a. \end{aligned}$$

So for any  $n$

$$a < \sup \left\| \max\{g(x, x_1), \dots, g(x, x_n)\} - \max\{g(x, x'_1), \dots, g(x, x'_n)\} \right\|_\infty$$

where the supremum is taken over  $x, x_2, \dots, x_n, x'_2, \dots, x'_n \in \mathcal{X}$  such that  $(x_2, \dots, x_n)$  and  $(x'_2, \dots, x'_n)$  differ from only one component. That proves that the bounded differences are not  $o(1/\sqrt{n \ln n})$ .

## 10. Useful results

**Theorem 10.1** (McDiarmid inequality [Boucheron et al., 2013]). *Suppose  $\mathcal{E}$  is a probability space and let  $f : \mathcal{E}^n \rightarrow \mathbb{R}$  be a function of  $n$  variables. Suppose that  $f$  satisfies the bounded differences property with the  $n$  nonnegative constants  $c_1, \dots, c_n$ . Then for any independent random variables  $X_1, \dots, X_n$  in  $\mathcal{E}$ , for any  $\varepsilon > 0$ :*

$$\mathbb{P}(|f(X_1, \dots, X_n) - \mathbb{E}(f(X_1, \dots, X_n))| > \varepsilon) \leq 2e^{-\frac{2\varepsilon^2}{\sum_{i=1}^n c_i^2}}.$$

Notice that the  $X_i$  are not required to be identically distributed. By a union bound and reformulating Proposition 10.1 to a bound with high probability one can obtain the following result for function taking multidimensional values.

**Corollary 10.2** (Multi dimensional McDiarmid inequality). *Suppose that  $f : \mathcal{E}^n \rightarrow \mathbb{R}^d$  satisfies a vectorial version on the bounded difference:  $\|f(x) - f(x')\|_\infty \leq c_i$  whenever  $x$  and  $x'$  differ only from the  $i$ -th component. Then for any independent random variables  $X_1, \dots, X_n$  in  $\mathcal{E}$ , for any  $\rho > 0$ :*

$$\|f(X_1, \dots, X_n) - \mathbb{E}(f(X_1, \dots, X_n))\|_\infty \leq \sqrt{\frac{1}{2} \sum_{i=1}^n c_i^2 \ln \left( \frac{2d}{\rho} \right)}$$

holds with probability at least  $1 - \rho$ .

**Corollary 10.3** (McDiarmid inequality with Holder transform). *Let  $f : \mathcal{E}^n \rightarrow \mathcal{C} \subset \mathbb{R}^d$  and  $\psi : \mathcal{C} \rightarrow \mathcal{D}$  an invertible function such that:*

$$\|\psi^{-1}(f(x)) - \psi^{-1}(f(x'))\|_\infty \leq c_i$$

whenever  $x$  and  $x'$  differ only from the  $i$ -th component,  $\psi$  is  $\alpha$ -Holder with  $0 < \alpha \leq 1$ :

$$\|\psi(y) - \psi(y')\|_\infty \leq K_\psi \|y - y'\|_\infty^\alpha$$

and

$$\|\psi(\mathbb{E}\psi^{-1}(f(X_1, \dots, X_n))) - \mathbb{E}(f(X_1, \dots, X_n))\|_\infty = u_n \rightarrow 0$$

for independent random variables  $X_1, \dots, X_n$  in  $\mathcal{E}$ . Then, for any  $\rho > 0$ :

$$\|f(X_1, \dots, X_n) - \mathbb{E}(f(X_1, \dots, X_n))\|_\infty \leq K_\psi \left( \frac{1}{2} \sum_{i=1}^n c_i^2 \ln \left( \frac{2d}{\rho} \right) \right)^{\alpha/2} + u_n$$

holds with probability at least  $1 - \rho$ .

*Proof.* We write  $f(X_1, \dots, X_n) = f(X)$  and:

$$\begin{aligned} \|f(X) - \mathbb{E}(f(X))\|_\infty &\leq \|\psi(\psi^{-1}(f(X))) - \psi(\mathbb{E}\psi^{-1}(f(X)))\|_\infty \\ &\quad + \|\psi(\mathbb{E}\psi^{-1}(f(X))) - \psi(\psi^{-1}(\mathbb{E}f(X)))\|_\infty \\ &\leq K_\psi \|\psi^{-1}(f(X)) - \mathbb{E}\psi^{-1}(f(X))\|_\infty^\alpha + \|\psi(\mathbb{E}\psi^{-1}(f(X))) - \mathbb{E}f(X)\|_\infty \end{aligned}$$

We apply McDiarmid's inequality (Cor. 10.2) on the first term and bound the second by  $u_n$  to obtain the result.  $\square$

**Lemma 10.4.** *Suppose  $P$  is strictly positive i.e., : for all  $U \subset \mathbb{R}^d$ ,  $P(U \cap \mathcal{X}) > 0$  if and only if  $U \cup \mathcal{X}$  is nonempty. Then for any continuous map  $f : \mathcal{X} \rightarrow \mathbb{R}$ ,*

$$\operatorname{ess\,sup}_P f = \sup f < +\infty.$$

*Proof.* Clearly  $\operatorname{ess\,sup}_P f \leq \sup f$  and  $\sup f < +\infty$  by continuity and compactness. Suppose that  $\operatorname{ess\,sup}_P f < \sup f$  then there is  $M$  such that  $\operatorname{ess\,sup}_P f < M < \sup f$ . By definition of  $\sup f$ , the set  $(f > M) = f^{-1}(]M; +\infty[)$  is nonempty, it is also a relative open of  $\mathcal{X}$  since it is the inverse image of an open by a continuous map. Thus, this set has a strictly positive measure, which yields a contradiction with the fact that  $\operatorname{ess\,sup}_P f < M$ .  $\square$

**Lemma 10.5.** *Let  $(a_i)_{i \in I}$  and  $(b_i)_{i \in I}$  be two finite families of vectors in  $\mathbb{R}^m$ . We have the following properties:*

- (i)  $\|\max_i a_i\|_\infty \leq \max_i \|a_i\|_\infty$ .
- (ii)  $\|\max_i a_i - \max_i b_i\|_\infty \leq \max_i \|a_i - b_i\|_\infty$ .

*Proof.* (i) For  $m = 1$ ,  $a_i \leq |a_i| \implies \max_i a_i \leq \max_i |a_i| \implies |\max_i a_i| \leq \max_i |a_i| = \max_i |a_i|$ . For  $m \geq 1$ ,  $\|\max_i a_i\|_\infty = \max_k |\max_i a_i^{(k)}| \leq \max_k \max_i |a_i^{(k)}| = \max_i \max_k |a_i^{(k)}| = \max_i \|a_i\|_\infty$ .

(ii) For  $m = 1$ . Let  $i_a$  (resp.  $i_b$ ) be an index that realizes  $\max_i a_i$  (resp.  $\max_i b_i$ ). We have

$$\begin{aligned} \max_i a_i - \max_i b_i &= a_{i_a} - b_{i_b} = a_{i_a} - b_{i_a} + \underbrace{b_{i_a} - b_{i_b}}_{\leq 0} \\ &\leq a_{i_a} - b_{i_a} \leq \max_i a_i - b_i \leq |\max_i a_i - b_i| \leq \max_i |a_i - b_i|. \end{aligned}$$

Then analogously  $\max_i b_i - \max_i a_i \leq \max_i |b_i - a_i| = \max_i |a_i - b_i|$ .

For  $m \geq 1$ ,  $\|\max_i a_i - \max_i b_i\|_\infty = \max_k |\max_i a_i^{(k)} - \max_i b_i^{(k)}| \leq \max_k \max_i |a_i^{(k)} - b_i^{(k)}| = \max_i \|a_i - b_i\|_\infty$ .  $\square$

**Lemma 10.6.** *Let  $g : \mathcal{X} \times \mathcal{X} \rightarrow \mathbb{R}^m$  be  $K_g$ -Lipschitz continuous. Then  $f : x \mapsto \sup_{y \in \mathcal{X}} g(x, y)$  is also  $K_g$ -Lipschitz continuous.*

*Proof.* For  $m = 1$ . Let  $x, x' \in \mathcal{X}$ , by continuity on a compact,  $\exists x^*, x'^*$  such that  $f(x) = g(x, x^*)$  and  $f(x') = g(x', x'^*)$ . Then  $f(x) - f(x') = g(x, x^*) - g(x', x'^*) + \underbrace{g(x', x^*) - g(x', x'^*)}_{\leq 0} \leq K_g \|x - x'\|_\infty$ , and permuting  $x$  and  $x'$  we obtain

the Lipschitz condition.

For  $m \geq 1$ ,  $\|f(x) - f(x')\|_\infty = \max_i |\sup_y g_i(x, y) - \sup_y g_i(x', y)| = \max_i |g_i(x, x^*) - g_i(x', x'^*)| \leq \max_i K_g \|x - x'\|_\infty = K_g \|x - x'\|_\infty$ .  $\square$

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