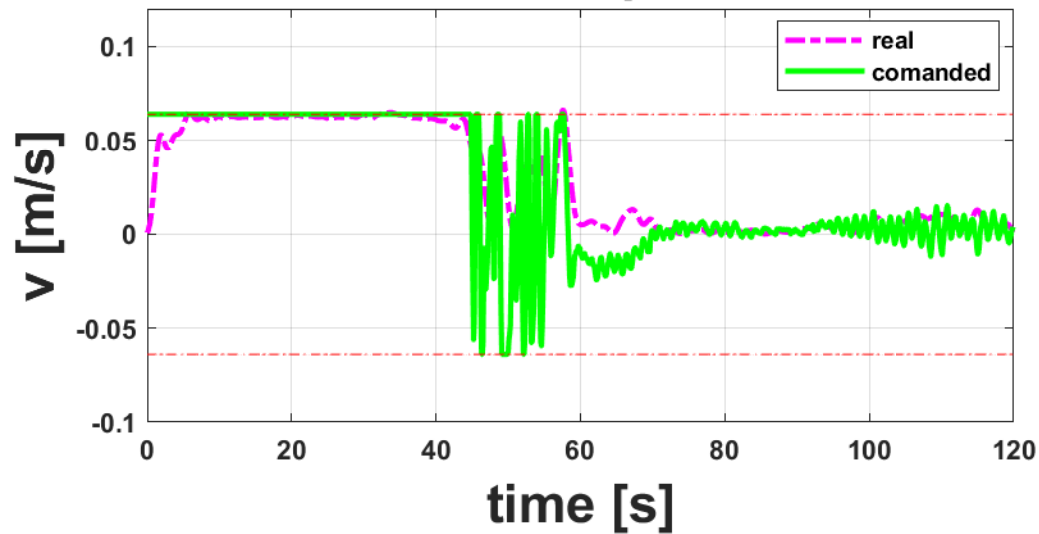


## Linear speed



## Angular speed

