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► **To cite this version:**

Giovanni Brigati, Jean Dolbeault, Nikita Simonov. Stability for the logarithmic Sobolev inequality. 2023. hal-04042046v1

HAL Id: hal-04042046

<https://hal.science/hal-04042046v1>

Preprint submitted on 22 Mar 2023 (v1), last revised 29 Mar 2024 (v2)

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Stability for the logarithmic Sobolev inequality

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Abstract

This paper is devoted to stability results for the Gaussian logarithmic Sobolev inequality. Our approach covers several cases involving the strongest possible norm with the optimal exponent, under constraints. Explicit constants are obtained. The strategy of proof relies on entropy methods and the Ornstein-Uhlenbeck flow.

Keywords: logarithmic Sobolev inequality, stability, log-concavity, heat flow, entropy, carré du champ.

2020 MSC: Primary: [39B62](#); Secondary: [47J20](#), [49J40](#), [35A23](#), [35K85](#).

1. Introduction and main results

Let us consider the *Gaussian logarithmic Sobolev inequality*

$$\|\nabla u\|_{L^2(\mathbb{R}^d, d\gamma)}^2 \geq \frac{1}{2} \int_{\mathbb{R}^d} |u|^2 \log \left(\frac{|u|^2}{\|u\|_{L^2(\mathbb{R}^d)}^2} \right) d\gamma \quad \forall u \in H^1(\mathbb{R}^d, d\gamma) \quad (1)$$

where $d\gamma = \gamma(x) dx$ is the normalized Gaussian probability measure with density

$$\gamma(x) = (2\pi)^{-\frac{d}{2}} e^{-\frac{1}{2}|x|^2} \quad \forall x \in \mathbb{R}^d.$$

In this paper we are interested in stability results, that is, in estimating the difference of the two terms in (1) from below, by a distance to the set of optimal functions. According to [20, 4], equality in (1) is achieved by functions in the manifold

$$\mathcal{M} := \{w_{a,c} : (a, c) \in \mathbb{R}^d \times \mathbb{R}\}$$

where

$$w_{a,c}(x) = c e^{-a \cdot x} \quad \forall x \in \mathbb{R}^d$$

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and only by these functions. The ultimate goal of *stability estimates* is to find a notion of distance d , an explicit constant $\beta > 0$ and an explicit exponent $\alpha > 0$, which may depend on d , such that

$$\|\nabla u\|_{L^2(\mathbb{R}^d, d\gamma)}^2 - \frac{1}{2} \int_{\mathbb{R}^d} |u|^2 \log \left(\frac{|u|^2}{\|u\|_{L^2(\mathbb{R}^d)}^2} \right) d\gamma \geq \beta \inf_{w \in \mathcal{M}} d(u, w)^\alpha \quad (\mathcal{S})$$

for any given $u \in H^1(\mathbb{R}^d, d\gamma)$. In this paper we consider the slightly simpler question of finding a specific $w_u \in \mathcal{M}$ such that

$$\|\nabla u\|_{L^2(\mathbb{R}^d, d\gamma)}^2 - \frac{1}{2} \int_{\mathbb{R}^d} |u|^2 \log \left(\frac{|u|^2}{\|u\|_{L^2(\mathbb{R}^d)}^2} \right) d\gamma \geq \beta d(u, w_u)^\alpha, \quad (*)$$

which provides us with no more than an estimate for (\mathcal{S}) : any estimate of α and β for $(*)$ is also an estimate for (\mathcal{S}) . In order to illustrate the difference between the two questions, let us consider the following elementary example. Assume that $d = 1$ and consider the functions $u_\varepsilon(x) = 1 + \varepsilon x$ in the limit as $\varepsilon \rightarrow 0$. With $d(u, w) = \|u' - w'\|_{L^2(\mathbb{R}, d\gamma)}$, which is the strongest possible notion of distance that we can expect to control in $(*)$, elementary computations show that the *deficit* of the logarithmic Sobolev inequality, *i.e.*, the left hand-side in $(*)$, is

$$\|\nabla u_\varepsilon\|_{L^2(\mathbb{R}, d\gamma)}^2 - \frac{1}{2} \int_{\mathbb{R}} |u_\varepsilon|^2 \log \left(\frac{|u_\varepsilon|^2}{\|u_\varepsilon\|_{L^2(\mathbb{R})}^2} \right) d\gamma = \frac{1}{2} \varepsilon^4 + O(\varepsilon^6),$$

while, using the test function $w_{a_\varepsilon, c_\varepsilon} \in \mathcal{M}$ where $a_\varepsilon = 2\varepsilon$ and $c_\varepsilon = e^{-a_\varepsilon^2/4}$, we obtain

$$d(u_\varepsilon, 1)^2 = \|u'_\varepsilon\|_{L^2(\mathbb{R}, d\gamma)}^2 = \varepsilon^2 \quad \text{and} \quad \inf_{w \in \mathcal{M}} d(u_\varepsilon, w)^\alpha \leq d(u_\varepsilon, w_{a_\varepsilon, c_\varepsilon})^2 = \frac{1}{2} \varepsilon^4 + O(\varepsilon^6).$$

In practice we will consider only the case

$$w_u = 1$$

in $(*)$ and the above example shows that the best we can hope for without additional restriction is $\alpha \geq 4$. Similar examples in higher dimensions can be obtained by considering for an arbitrary given $v \in \mathbb{S}^{d-1}$ the functions $u_\varepsilon(x) = 1 + \varepsilon x \cdot v$ in the limit as $\varepsilon \rightarrow 0$. This is not a surprise in view of [33, 30, 39], and also of the detailed Taylor expansions of [36, 17, 18]. Still with $w_u = 1$, we can expect to have $\alpha = 2$ in $(*)$ *under additional conditions*, including for $d(u, w) = \|\nabla u - \nabla w\|_{L^2(\mathbb{R}^d, d\gamma)}$, while it is otherwise banned as shown for instance from [39, Theorem 1.2 (2)], or simply from considering the above example. Before entering the details, let us mention a recent stability result for (\mathcal{S}) with $\alpha = 2$ involving a constructive although very delicate expression for $\beta > 0$ and $d(u, w) = \|u - w\|_{L^2(\mathbb{R}^d, d\gamma)}$ that appeared in [27]. Here we aim at stronger estimates under additional constraints, with $w_u = 1$, which is a different point of view. Let us start by a first stability result.

Proposition 1. For all $u \in H^1(\mathbb{R}^d, d\gamma)$ such that $\|u\|_{L^2(\mathbb{R}^d)} = 1$ and $\|xu\|_{L^2(\mathbb{R}^d)}^2 \leq d$, we have

$$\|\nabla u\|_{L^2(\mathbb{R}^d, d\gamma)}^2 - \frac{1}{2} \int_{\mathbb{R}^d} |u|^2 \log |u|^2 d\gamma \geq \frac{1}{2d} \left(\int_{\mathbb{R}^d} |u|^2 \log |u|^2 d\gamma \right)^2 \quad (2)$$

and, with $\psi(s) := s - \frac{d}{4} \log(1 + \frac{4}{d}s)$, we also have the stronger estimate

$$\|\nabla u\|_{L^2(\mathbb{R}^d, d\gamma)}^2 - \frac{1}{2} \int_{\mathbb{R}^d} |u|^2 \log |u|^2 d\gamma \geq \psi \left(\|\nabla u\|_{L^2(\mathbb{R}^d, d\gamma)}^2 \right). \quad (3)$$

Similar results are already known in the literature (see for instance [14, 33, 30, 39]) and we claim no originality for the the results. Also see references to earlier proofs at the end of the introduction. Our method is based on the *carré du champ* method. Even if some ideas go back to [2], it is elementary, new as far as we know, and of some use for our other results.

Coming back to (\star) , we may notice that there is no loss of generality in imposing the condition $\|u\|_{L^2(\mathbb{R}^d)} = 1$, as we can always replace u by $u/\|u\|_{L^2(\mathbb{R}^d)}$. Because of the Csiszár-Kullback-Pinsker inequality

$$\int_{\mathbb{R}^d} |u|^2 \log |u|^2 d\gamma \geq \frac{1}{4} \left\| |u|^2 - 1 \right\|_{L^1(\mathbb{R}^d, d\gamma)}^2 \quad (4)$$

and $\left| |u| - 1 \right| = \left| |u|^2 - 1 \right| / \left| |u| + 1 \right| \leq \left| |u|^2 - 1 \right|$, we find that (2) implies (\star) type with $d(u, w) = \|u - w\|_{L^1(\mathbb{R}^d, d\gamma)}$ for nonnegative functions u , $\alpha = 4$, and $\beta = 1/(32d)$. For functions far away from the optimal functions, say such that $\|\nabla u\|_{L^2(\mathbb{R}^d, d\gamma)} \geq A$ under the conditions of Proposition 1, Inequality (3) provides us with an even stronger stability result of (\star) type with $\alpha = 2$ and $d(u, w) = \|\nabla u - \nabla w\|_{L^2(\mathbb{R}^d, d\gamma)}$, but with a positive constant β which depends on $A > 0$. Again, notice that (\star) with such a distance cannot hold without constraints.

Next we aim at explicit results with $\alpha = 2$, under other constraints. Let

$$\mathcal{C}_\star = 1 + \frac{1}{1728} \approx 1.0005787.$$

Theorem 2. For all $u \in H^1(\mathbb{R}^d, d\gamma)$ such that $u^2 \gamma$ is log-concave and such that

$$\int_{\mathbb{R}^d} (1, x) |u|^2 d\gamma = (1, 0) \quad \text{and} \quad \int_{\mathbb{R}^d} |x|^2 |u|^2 d\gamma \leq d, \quad (5)$$

we have

$$\|\nabla u\|_{L^2(\mathbb{R}^d, d\gamma)}^2 - \frac{\mathcal{C}_\star}{2} \int_{\mathbb{R}^d} |u|^2 \log |u|^2 d\gamma \geq 0. \quad (6)$$

The condition $\int_{\mathbb{R}^d} |x|^2 |u|^2 d\gamma \leq d$ in (5) is a simplifying assumption. A result like (6) also holds if $\int_{\mathbb{R}^d} |x|^2 |u|^2 d\gamma > d$, but with a constant that differs from \mathcal{C}_\star and actually depends on $\int_{\mathbb{R}^d} |x|^2 |u|^2 d\gamma$. We refer to Section 3.5: see Proposition 7 for an extension of Theorem 2, and also for further comments on the extension of Proposition 1. The constant \mathcal{C}_\star in (8) relies on an estimate of [12].

Inequality (6) with improved constant $\mathcal{C}_\star > 1$ compared to (1) can be recast in

the form of a stability inequality of type (\star) around the normalised Gaussian as

$$\|\nabla u\|_{L^2(\mathbb{R}^d, d\gamma)}^2 - \frac{1}{2} \int_{\mathbb{R}^d} |u|^2 \log |u|^2 d\gamma \geq \frac{1}{2} (\mathcal{C}_\star - 1) \int_{\mathbb{R}^d} |u|^2 \log |u|^2 d\gamma$$

for all functions $u \in H^1(\mathbb{R}^d, d\gamma)$ such that $\|u\|_{L^2(\mathbb{R}^d)} = 1$, which covers the case $\alpha = 2$, $\beta = (\mathcal{C}_\star - 1)/8$ and $d(u, w) = \|u - w\|_{L^1(\mathbb{R}^d, d\gamma)}$ in (\star) for nonnegative functions by (4), or even in the stronger $\dot{H}^1(\mathbb{R}^d, d\gamma)$ semi-norm, as

$$\|\nabla u\|_{L^2(\mathbb{R}^d, d\gamma)}^2 - \frac{1}{2} \int_{\mathbb{R}^d} |u|^2 \log |u|^2 d\gamma \geq \frac{\mathcal{C}_\star - 1}{\mathcal{C}_\star} \|\nabla u\|_{L^2(\mathbb{R}^d, d\gamma)}^2$$

for all functions $u \in H^1(\mathbb{R}^d, d\gamma)$ such that $\|u\|_{L^2(\mathbb{R}^d)} = 1$, which corresponds to $\alpha = 2$, $\beta = (\mathcal{C}_\star - 1)/\mathcal{C}_\star$ and $d(u, w) = \|\nabla(u - w)\|_{L^2(\mathbb{R}^d, d\gamma)}$ in (\star) . By the Gaussian Poincaré inequality, notice that the case of (\star) with $\alpha = 2$, $\beta = (\mathcal{C}_\star - 1)/\mathcal{C}_\star$ and the standard distance $d(u, w) = \|u - w\|_{L^2(\mathbb{R}^d, d\gamma)}$ is also covered.

Log-concavity might appear as a rather restrictive assumption, but this is useful because a function which is compactly supported at time $t = 0$ evolves through the diffusion flow into a logarithmically concave function after some finite time that can be estimated by the heat flow estimates of [48]. This is enough to produce a stability result with an explicit constant. Compact support is in fact a too restrictive condition and we have the following result.

Theorem 3. *Let $d \geq 1$. For any $\varepsilon > 0$, there is some explicit $\mathcal{C} > 1$ depending only on ε such that, for any $u \in H^1(\mathbb{R}^d, d\gamma)$ satisfying (5) and*

$$\int_{\mathbb{R}^d} |u|^2 e^{\varepsilon|x|^2} d\gamma < \infty, \quad (7)$$

then we have

$$\|\nabla u\|_{L^2(\mathbb{R}^d, d\gamma)}^2 \geq \frac{\mathcal{C}}{2} \int_{\mathbb{R}^d} |u|^2 \log |u|^2 d\gamma. \quad (8)$$

Additionally, if u is compactly supported in a ball of radius $R > 0$, then (8) holds with

$$\mathcal{C} = 1 + \frac{\mathcal{C}_\star - 1}{1 + \mathcal{C}_\star R^2}.$$

This expression of the constant \mathcal{C} in (8) is given in the proof, in Section 3.4. The simpler estimate in terms of R relies on Theorem 2.

Let us conclude this introduction with a review of the literature. The *logarithmic Sobolev inequality* historically appeared in [54, 11], in a form that was later rediscovered as an equivalent scale-invariant form of the Euclidean version of the inequality in [56]. We refer to [37] for the Gaussian version (1) of the inequality, and also to [34] for an equivalent result. The optimality case in the inequality has been characterized in [20] but can also be deduced from [4]. Also see [55] for a short introductory review with an emphasis on *information theoretical* aspects. The logarithmic Sobolev inequality can be viewed as a limit case of a family of the Gagliardo-Nirenberg-Sobolev

(GNS) as observed in [25], in the Euclidean setting, or as a large dimension limit of the Sobolev inequality according to [9]. See [27, 18] for recent developments and further references. We refer to [1, 38, 52, 5] to reference books on the topic. In a classical result on stability in functional inequalities, Bianchi and Egnell proved in [10] that the deficit in the Sobolev inequality measures the $\dot{H}^1(\mathbb{R}^d, dx)$ distance to the manifold of the Aubin-Talenti functions. The estimate has been made constructive in [27] where a new $L^2(\mathbb{R}^d, dx)$ stability result for the logarithmic Sobolev inequality is also established (also see [39] for further results in strong norms). Still in the Euclidean setting a first stability result in strong norms for the logarithmic Sobolev inequality appears in [33], where the authors give deficit estimates in various distances for functions inducing a Poincaré inequality. Under the condition $\|xu\|_{L^2(\mathbb{R}^d, d\gamma)} = \sqrt{d}$, a stability result measured by an entropy is given in [30]. For sequential stability results in strong norms, we refer to [40] when assuming a bound on u in $L^4(\mathbb{R}^d, d\gamma)$ and to [39] when assuming a bound on $|x|^2 u$ in $L^2(\mathbb{R}^d, d\gamma)$. Stability according to other notions of distance has been studied in [47, 46, 35].

To our knowledge, the first result of stability for the logarithmic Sobolev inequality is a reinforcement of the inequality due to E. Carlen in [20] where he introduces an additional term involving the Wiener transform. Stability in logarithmic Sobolev inequality is related to deficit in Gaussian isoperimetry and we refer to [14] for an introduction to early results in this direction, [7] for a sharp, dimension-free quantitative Gaussian isoperimetric inequality, and [31] for recent results and further references. Results of Proposition 1 are known from [14, Theorem 1.1] where it is deduced from the HWI inequality due to F. Otto and C. Villani [51]. Such estimates have even been refined in [31]. There are several other proofs. In [33], M. Fathi, E. Indrei and M. Ledoux use a Mehler formula for the Ornstein-Uhlenbeck semigroup and Poincaré inequalities. The proof in [30] is based on simple scaling properties of the Euclidean form of the logarithmic Sobolev inequality, which also apply to Gagliardo-Nirenberg inequalities. Various stability results have been proved in Wasserstein's distance: we refer to [41, 14, 33, 40, 43, 15, 31, 39]. A key argument for Theorem 2 is the fact that the heat flow preserves log-concavity according, e.g., [53], which is a pretty natural property in this framework: see for instance [24].

In this paper, we carefully distinguish stability results of type (\mathcal{S}) where stability is measured w.r.t. \mathcal{M} , and of type (\star) where the distance to a given function is estimated. Even if this function is normalized and centered, this is not enough as shown in [39]. Many counter-examples to stability are known, involving Wasserstein's distance for instance in [41, 14, 33, 40, 43], weaker distances like p -Wasserstein, or stronger norms like L^p or H^1 : see for instance [40, 39]. The main counter-examples which we might try to apply to our setting are [43, Theorem 1.3] and [31, Theorem 4] but, as already noted in [40], they are based on the fact that the second moment diverges along a sequence of test functions, which is forbidden in our assumptions.

This paper is organized as follows. Section 2 is devoted to the standard *carré du champ* method and a proof of Proposition 1. Theorem 2 is proved in Section 3.3, under a log-concavity assumption. Using properties of the heat flow, the method is extended to the larger class of functions of Theorem 3 in Section 3.4.

2. Entropy methods and entropy – entropy production stability estimates

This section is devoted to the proof of Proposition 1.

2.1. Definitions and preliminary results

Consider the *Ornstein-Uhlenbeck equation* on \mathbb{R}^d

$$\frac{\partial h}{\partial t} = \mathcal{L}h, \quad h(t=0, \cdot) = h_0, \quad (t, x) \in \mathbb{R}^+ \times \mathbb{R}^d, \quad (9)$$

where $\mathcal{L}h := \Delta h - x \cdot \nabla h$ denotes the *Ornstein-Uhlenbeck operator*.

Let us recall some classical results. If $h_0 \in L^1(\mathbb{R}^d, d\gamma)$ is nonnegative, then there exists a unique nonnegative weak solution to (9) (see for instance [32]). The two key properties of the Ornstein-Uhlenbeck operator are

$$\int_{\mathbb{R}^d} v_1 (\mathcal{L}v_2) d\gamma = - \int_{\mathbb{R}^d} \nabla v_1 \cdot \nabla v_2 d\gamma \quad \text{and} \quad [\nabla, \mathcal{L}]v = -\nabla v.$$

As a consequence, we obtain the two identities

$$\int_{\mathbb{R}^d} (\mathcal{L}v)^2 d\gamma = \int_{\mathbb{R}^d} \|\text{Hess } v\|^2 d\gamma + \int_{\mathbb{R}^d} |\nabla v|^2 d\gamma \quad (10)$$

and

$$\int_{\mathbb{R}^d} \mathcal{L}v \frac{|\nabla v|^2}{v} d\gamma = -2 \int_{\mathbb{R}^d} \text{Hess } v : \frac{\nabla v \otimes \nabla v}{v} d\gamma + \int_{\mathbb{R}^d} \frac{|\nabla v|^4}{v^2} d\gamma, \quad (11)$$

where $\text{Hess } v = \nabla \otimes \nabla v$ is the *Hessian matrix* of v . Here we use the following notations. If a and b take values in \mathbb{R}^d , $a \otimes b$ denotes the matrix $(a_i b_j)_{1 \leq i, j \leq d}$. With matrix valued m and n , we define $m : n = \sum_{i, j=1}^d m_{i, j} n_{i, j}$ and $\|m\|^2 = m : m$. If h is a nonnegative solution of (9), notice that $v = \sqrt{h}$ solves

$$\frac{\partial v}{\partial t} = \mathcal{L}v + \frac{|\nabla v|^2}{v}. \quad (12)$$

Let us fix $\|v\|_{L^2(\mathbb{R}^d)} = 1$, then the *entropy* and the *Fisher information*, respectively defined by

$$\mathcal{E}[v] := \int_{\mathbb{R}^d} |v|^2 \log |v|^2 d\gamma \quad \text{and} \quad \mathcal{I}[v] := \int_{\mathbb{R}^d} |\nabla v|^2 d\gamma,$$

evolve along the flow according to

$$\frac{d}{dt} \mathcal{E}[v] = -4 \mathcal{I}[v] \quad \text{and} \quad \frac{d}{dt} \mathcal{I}[v] = -2 \int_{\mathbb{R}^d} \left((\mathcal{L}v)^2 + \mathcal{L}v \frac{|\nabla v|^2}{v} \right) d\gamma$$

if v solves (12). Using (10) and (11), we obtain the classical expression of the *carré du champ* method

$$\frac{d}{dt} \mathcal{I}[v] + 2 \mathcal{I}[v] = -2 \int_{\mathbb{R}^d} \left\| \text{Hess } v - \frac{\nabla v \otimes \nabla v}{v} \right\|^2 d\gamma \quad (13)$$

as for instance in [3, 28, 5]. By writing that

$$\frac{d}{dt} \left(\mathcal{I}[v] - \frac{1}{2} \mathcal{E}[v] \right) \leq 0 \quad \text{and} \quad \lim_{t \rightarrow +\infty} \left(\mathcal{I}[v(t, \cdot)] - \frac{1}{2} \mathcal{E}[v(t, \cdot)] \right) = 0,$$

we recover the standard proof of the *entropy – entropy production* inequality

$$\mathcal{I}[v] - \frac{1}{2} \mathcal{E}[v] \geq 0, \quad (14)$$

i.e., of (1) by the method of [4].

Several of the above expression can be rephrased in terms of the *pressure variable*

$$P := -\log h = -2 \log v$$

using the following elementary identities

$$\begin{aligned} \nabla v &= -\frac{1}{2} e^{-P/2} \nabla P, & \frac{\nabla v \otimes \nabla v}{v} &= \frac{1}{4} e^{-P/2} \nabla P \otimes \nabla P, \\ \text{Hess } v &= -\frac{1}{2} e^{-P/2} \text{Hess } P + \frac{1}{4} e^{-P/2} \nabla P \otimes \nabla P, \end{aligned}$$

so that, by taking into account $v \nabla P = -2 \nabla v$ and $h = v^2$, we have

$$\mathcal{I}[v] = \frac{1}{4} \int_{\mathbb{R}^d} |\nabla P|^2 h d\gamma \quad \text{and} \quad \int_{\mathbb{R}^d} \left\| \text{Hess } v - \frac{\nabla v \otimes \nabla v}{v} \right\|^2 d\gamma = \frac{1}{4} \int_{\mathbb{R}^d} \|\text{Hess } P\|^2 h d\gamma.$$

2.2. Improvements under moment constraints

In standard computations based on the *carré du champ* method, one usually drops the right-hand side in (13) which results in the standard exponential decay of $\mathcal{I}[v(t, \cdot)]$ if v solves (12) and, after integration on $t \in \mathbb{R}^+$, proves (1). Keeping track of the right-hand side in (13) provides us with improvements as shown in [2, 26, 29] in various interpolation inequalities but generically fails in the case of the logarithmic Sobolev inequality. We remedy to this issue by introducing moment constraints. This is not a very difficult result but, as far as we know, it is new in the framework of the *carré du champ* method.

Lemma 4. *With the notations of Section 2.1, if $v \in H^2(\mathbb{R}^d, d\gamma)$ is a positive function such that $\int_{\mathbb{R}^d} |x|^2 |v|^2 d\gamma \leq d$, then*

$$4 \mathcal{I}[v] \leq \int_{\mathbb{R}^d} (\Delta P) h d\gamma \leq \sqrt{d} \int_{\mathbb{R}^d} \|\text{Hess } P\|^2 h d\gamma.$$

Proof. Using $h \nabla P = -\nabla h$, we obtain

$$4 \mathcal{I}[v] = \int_{\mathbb{R}^d} |\nabla P|^2 h d\gamma = - \int_{\mathbb{R}^d} \nabla P \cdot \nabla h d\gamma = \int_{\mathbb{R}^d} h (\mathcal{L}P) d\gamma.$$

After recalling that $\mathcal{L}P = \Delta P - x \cdot \nabla P$, using an integration by parts we deduce that

$$-\int_{\mathbb{R}^d} h x \cdot \nabla P d\gamma = \int_{\mathbb{R}^d} x \cdot \nabla h d\gamma = \int_{\mathbb{R}^d} h(|x|^2 - d) d\gamma = \int_{\mathbb{R}^d} |v|^2 (|x|^2 - d) d\gamma \leq 0$$

which proves the first inequality. The second inequality follows from a Cauchy-Schwarz inequality and the arithmetic-geometric inequality

$$(\Delta P)^2 \leq d \|\text{Hess } P\|^2.$$

□

Proof of Proposition 1. Let $h = v^2$ be the solution of (9) with initial datum $h_0 = u^2$. Since $x \mapsto (|x|^2 - d)$ is an eigenfunction of \mathcal{L} with corresponding eigenvalue -2 and \mathcal{L} is self-adjoint on $L^2(\mathbb{R}^d, d\gamma)$, we have

$$\begin{aligned} \frac{d}{dt} \int_{\mathbb{R}^d} (|x|^2 - d) h d\gamma &= \int_{\mathbb{R}^d} (|x|^2 - d) (\mathcal{L}h) d\gamma \\ &= \int_{\mathbb{R}^d} h \mathcal{L}(|x|^2 - d) d\gamma = -2 \int_{\mathbb{R}^d} (|x|^2 - d) h d\gamma. \end{aligned} \quad (15)$$

The sign of $t \mapsto \int_{\mathbb{R}^d} (|x|^2 - d) h(t, x) d\gamma$ is conserved and in particular we have that $\int_{\mathbb{R}^d} |x|^2 |v|^2 d\gamma \leq d$ for any $t \geq 0$. For any $i = 1, 2, \dots, d$, we also notice that $x \mapsto x_i$ is also an eigenfunction of \mathcal{L} with corresponding eigenvalue -1 so that

$$\frac{d}{dt} \int_{\mathbb{R}^d} x h d\gamma = - \int_{\mathbb{R}^d} x h d\gamma$$

and, as a consequence $\int_{\mathbb{R}^d} x h(t, \cdot) d\gamma = 0$ for all $t \geq 0$ because $\int_{\mathbb{R}^d} x h_0 d\gamma = 0$.

For smooth enough solutions, we deduce from Lemma 4, (13) and (14) that

$$\frac{d}{dt} \mathcal{J}[v] + 2 \mathcal{J}[v] \leq -\frac{8}{d} \mathcal{J}^2[v] \leq \frac{1}{2d} \frac{d}{dt} (\mathcal{E}[v])^2$$

and obtain by considering the limit as $t \rightarrow +\infty$ that

$$\mathcal{J}[v] \geq \frac{1}{2} \mathcal{E}[v] + \frac{1}{2d} (\mathcal{E}[v])^2.$$

This provides us with (2). In the general case, one can get rid of the $H^2(\mathbb{R}^d, d\gamma)$ regularity of Lemma 4 by a standard approximation scheme, which is classical and will not be detailed here.

As in [17], a better estimate is achieved as follows. Let

$$\phi(s) := \frac{d}{4} \left(e^{\frac{2}{d}s} - 1 \right) \quad \forall s \geq 0.$$

Using $\frac{d}{dt} \mathcal{E}[v] = -4 \mathcal{I}[v]$, we notice that

$$\frac{d}{dt} \left(\mathcal{I}[v] - \phi(\mathcal{E}[v]) \right) = -\frac{8}{d} \left(\mathcal{I}[v] - \phi(\mathcal{E}[v]) \right).$$

Since $\lim_{t \rightarrow +\infty} \mathcal{I}[v(t, \cdot)] = 0$ as can be deduced from a Gronwall estimate relying on $\frac{d}{dt} \mathcal{I}[v] \leq -2 \mathcal{I}[v]$ and $\lim_{t \rightarrow +\infty} \mathcal{E}[v(t, \cdot)] = 0$ as a consequence of (1), one knows that

$$\lim_{t \rightarrow +\infty} \left(\mathcal{I}[v(t, \cdot)] - \phi(\mathcal{E}[v(t, \cdot)]) \right) = 0.$$

Moreover, Gronwall estimates show that $\mathcal{I}[v(t, \cdot)] - \phi(\mathcal{E}[v(t, \cdot)])$ cannot change sign and an asymptotic expansion as $t \rightarrow +\infty$ as in [17, Appendix B.4] is enough to obtain that $\mathcal{I}[v(t, \cdot)] - \phi(\mathcal{E}[v(t, \cdot)])$ takes nonnegative values for $t > 0$ large enough. Altogether, we conclude that

$$\mathcal{I}[v(t, \cdot)] - \phi(\mathcal{E}[v(t, \cdot)]) \geq 0$$

for any $t \geq 0$ and, as a particular case, at $t = 0$ for $v(0, \cdot) = u$. The function ϕ is convex increasing and, as such, invertible, so that we can also write

$$\varphi(\mathcal{I}[u])^{-1} - \phi(\mathcal{E}[u]) \geq 0.$$

his completes the proof of (3) with the convex monotone increasing function

$$\psi(s) := s - \frac{1}{2} \phi^{-1}(s).$$

□

3. Stability results

3.1. Log-concave measures and Poincaré inequality

According to [6], given a Borel probability measure μ on \mathbb{R}^d , its *isoperimetric constant* is defined as

$$h(\mu) := \inf_A \frac{P_\mu(A)}{\min\{\mu(A), 1 - \mu(A)\}}$$

where the infimum is taken on the set of arbitrary Borel subset \mathbb{R}^d with μ -perimeter or surface measure $P_\mu(A) := \lim_{\varepsilon \rightarrow 0^+} (\mu(A_\varepsilon) - \mu(A))/\varepsilon$ and $A_\varepsilon := \{x \in \mathbb{R}^d : |x - a| < \varepsilon \text{ for some } a \in A\}$. Here and in what follows, we shall say that a measure μ with density $e^{-\psi}$ with respect to Lebesgue's measure is a *log-concave probability measure* if ψ is a convex function, and denote by $\lambda_1(\mu)$ the first positive eigenvalue of $-\mathcal{L}_\psi$ where \mathcal{L}_ψ is the *Ornstein-Uhlenbeck operator* $\mathcal{L}_\psi := \Delta - \nabla \psi \cdot \nabla$. In that case, we learn from [45, Ineq. (5.8)] that

$$\frac{1}{4} h(\mu)^2 \leq \lambda_1(\mu) \leq 36 h(\mu)^2$$

where the lower bound is J. Cheeger's inequality that goes back to [22] for Riemannian manifolds and also to earlier works by V.G. Maz'ya [49, 50]. This bound was later improved in [19, 44]. The characterization of $h(\mu)$ has been actively studied, but it is out of the scope of the present paper. We learn from [12, Theorem 1.2] and [12, Ineq. (3.4)] that

$$h(\mu) \geq \frac{1}{6\sqrt{3} \int_{\mathbb{R}^d} |x - x_\mu|^2 d\mu} \quad \text{where} \quad x_\mu = \int_{\mathbb{R}^d} x d\mu$$

for any log-concave probability measure μ . This estimate is closely related with the results by R. Kannan, L. Lovász and M. Simonovits in [42] and their conjecture, which again lies out of the scope of the present paper (see for instance [13] for a recent work on the topic).

Altogether, if μ is a log-concave probability measure with $d\mu = e^{-\psi} dx$ such that $\int_{\mathbb{R}^d} |x|^2 d\mu \leq d$, then we have the *Poincaré inequality*

$$\int_{\mathbb{R}^d} |\nabla f|^2 d\mu \geq \frac{1}{432} \int_{\mathbb{R}^d} |f|^2 d\mu \quad \forall f \in H^1(\mathbb{R}^d, d\mu) \text{ such that } \int_{\mathbb{R}^d} f d\mu = 0. \quad (16)$$

We refer to [21] and references therein for further estimates on $\lambda_1(\mu)$.

3.2. Time evolution, log-concave densities and Poincaré inequality

Lemma 5. *Let us consider a solution h of (9) with initial datum $h_0 = v^2$ and assume that $\mu_0 := h_0 \gamma$ is log-concave. Then $\mu_t := h(t, \cdot) \gamma$ is log-concave for all $t \geq 0$.*

Proof. The function $g := h \gamma$ solves the Fokker-Planck equation

$$\frac{\partial g}{\partial t} = \Delta g + \nabla \cdot (x g).$$

The function f such that

$$f(t, x) := g\left(\frac{1}{2} \log(1 + 2t), \frac{x}{\sqrt{1 + 2t}}\right) \quad \forall (t, x) \in \mathbb{R}^+ \times \mathbb{R}^d$$

solves the heat equation and can be represented using the heat kernel. According for instance to [53, 8], log-concavity is preserved under convolution, which completes the proof. \square

The log-concavity property becomes true under the action of the flow of (9) after some delay t_\star for large classes of initial data. With the notation of Lemma 5, for any $R > 0$, we read from [48, Theorem 5.1] by K. Lee and J-L. Vázquez that μ_t is log-concave for any

$$t \geq t_\star(R) := \log\left(\sqrt{R^2 + 1}\right), \quad (17)$$

if v is compactly supported in a ball of radius $R > 0$, by reducing the problem to the heat flow as in the above proof. As a consequence, we know that (16) holds for any $t \geq t_\star(R)$.

Alternatively, under Assumption (7), we learn from a recent paper [23, Theorem 2] by H.-B. Chen, S. Chewi, and J. Niles-Weed that the *Poincaré inequality*

$$\int_{\mathbb{R}^d} |\nabla f|^2 d\mu_t \geq \lambda_1(\mu_t) \int_{\mathbb{R}^d} |f|^2 d\mu_t \quad \forall f \in H^1(\mathbb{R}^d, d\mu_t) \text{ such that } \int_{\mathbb{R}^d} f d\mu_t = 0 \quad (18)$$

holds for all $t \geq t_*^\varepsilon$ with

$$t_*^\varepsilon := \log(\sqrt{1 + \varepsilon^{-1}}), \quad \frac{1}{\lambda_1(\mu_t)} \leq \tau \left(\frac{\varepsilon \tau}{\varepsilon \tau - 1} + A \varepsilon^{\frac{1}{\tau-1}} \right) \quad \text{and} \quad \tau = \frac{1}{2} (e^{2t} - 1).$$

3.3. Explicit stability results for log-concave densities

Let us start by an elementary observation.

Lemma 6. *If $h \in H^1(\mathbb{R}^d, d\gamma)$ is such that $\int_{\mathbb{R}^d} x h d\gamma = 0$ and $P = -\log h$ is the pressure variable, then*

$$\int_{\mathbb{R}^d} \nabla P h d\gamma = 0.$$

Proof. The result follows from $\int_{\mathbb{R}^d} \nabla P h d\gamma = -\int_{\mathbb{R}^d} \nabla h d\gamma = \int_{\mathbb{R}^d} x h d\gamma = 0$. \square

With this result in hand, we can now prove our first main result.

Proof of Theorem 2. The function $h = v^2$ is such that $\int_{\mathbb{R}^d} x h d\gamma = 0$ and Lemma 6 applies. Since $h\gamma$ is log-concave, we can apply (16) with $f = \partial P / \partial x_i$ for any $i = 1, 2, \dots, d$ and obtain

$$\int_{\mathbb{R}^d} \|\text{Hess } P\|^2 h d\gamma \geq \frac{1}{432} \int_{\mathbb{R}^d} |\nabla P|^2 h d\gamma.$$

It follows from (13) that

$$\frac{d}{dt} \int_{\mathbb{R}^d} |\nabla v|^2 d\gamma + 2 \int_{\mathbb{R}^d} |\nabla v|^2 d\gamma \leq -\frac{1}{864} \int_{\mathbb{R}^d} |\nabla v|^2 d\gamma,$$

and the stability result is obtained as in the proof of Proposition 1. \square

3.4. Extension by entropy methods and flows

This section is devoted to the proof of Theorem 3. The key idea is to evolve the function by the Ornstein-Uhlenbeck equation, so that the solution after an *initial time layer* has the log-concavity property of Theorem 2, at least if the initial datum has compact support. To some extent, the strategy is similar to the one used in [16]. During the initial time layer, we use an improved version of the entropy – entropy production inequality which arises as a consequence of the *carré du champ* method.

Proof of Theorem 3. Let h be the solution to (9) with initial datum $h_0 = u^2$ and define

$$\mathcal{Q}(t) := \frac{\mathcal{J}[\sqrt{h(t, \cdot)}]}{\mathcal{E}[\sqrt{h(t, \cdot)}]} \quad \forall t \geq 0.$$

Let us assume first that v has compact support. With no loss of generality, we can assume that v is supported in $B(0, R)$ for some $R > 0$. With $t_* = t_*(R)$ given by (17), we know from [48, Theorem 5.1] that μ_t is log-concave at $t = t_*$ and Theorem 2 applies:

$$\mathcal{Q}(t_*) \geq \frac{\mathcal{C}_*}{2}.$$

With an estimate similar to [16, Lemma 2.9], we learn from Section 2 that

$$\frac{d\mathcal{Q}}{dt} \leq 2\mathcal{Q}(2\mathcal{Q} - 1). \quad (19)$$

An integration on $(0, t_*)$ shows that

$$\mathcal{Q}(0) \geq \frac{1}{2} \left(1 + \frac{2\mathcal{Q}(t_*) - 1}{1 + 2\mathcal{Q}(t_*)(e^{2t_*} - 1)} \right) \geq \frac{1}{2} \left(1 + \frac{\mathcal{C}_* - 1}{1 + \mathcal{C}_* R^2} \right) = \frac{\mathcal{C}}{2}.$$

Under the more general assumption (7), we rely on (18) and obtain with same notations as above and $t_* = t_*^\varepsilon$ that

$$\int_{\mathbb{R}^d} \|\text{Hess } P\|^2 h(t, \cdot) d\gamma \geq \lambda_1(\mu_t) \int_{\mathbb{R}^d} |\nabla P|^2 h(t, \cdot) d\gamma \quad \forall t \geq t_*.$$

Moreover, for some explicit $t_0 = t_0(\varepsilon) > t_*$, we notice that $t \mapsto \lambda_1(\mu_t)$ is nonincreasing on $(t_0, +\infty)$. Hence we deduce from

$$\mathcal{I}[v(t_0, \cdot)] - \frac{1}{8} \int_{t_0}^{+\infty} (4 + \lambda_1(\mu_s)) \mathcal{E}'[v(s, \cdot)] ds \geq 0$$

after an integration by parts that

$$\mathcal{Q}(t_0) \geq \frac{1}{2} \left(1 + \frac{1}{4} \lambda_1(\mu_{t_0}) \right) =: \mathcal{C}_0.$$

Using (19), we obtain

$$\mathcal{C} = 1 + \frac{\mathcal{C}_0 - 1}{1 + \mathcal{C}_0(e^{2t_0} - 1)}.$$

This concludes the proof. \square

3.5. Normalization issues

If we do not assume that $\|u\|_{L^2(\mathbb{R}^d, d\gamma)} = 1$ and $\|xu\|_{L^2(\mathbb{R}^d, d\gamma)} \leq d$, it is still possible to state the analogue of Theorem 2, but the price to be paid is a dependence on

$$\kappa[u] := \frac{\|u\|_{L^2(\mathbb{R}^d, d\gamma)}}{\max\{\sqrt{d}, \|(x - x_0)u\|_{L^2(\mathbb{R}^d, d\gamma)}\}} \quad \text{where} \quad x_0 = \int_{\mathbb{R}^d} x h_0 d\gamma,$$

which goes as follows.

Proposition 7. For all $u \in H^1(\mathbb{R}^d, (1 + |x|^2) d\gamma)$ such that $\int_{\mathbb{R}^d} x u^2 d\gamma = 0$, and $u^2 \gamma$ is log-concave, we have

$$\|\nabla u\|_{L^2(\mathbb{R}^d, d\gamma)}^2 - \frac{1}{2} (1 + (\mathcal{C}_* - 1) \kappa[u]) \int_{\mathbb{R}^d} |u|^2 \log\left(\frac{|u|^2}{\|u\|_{L^2(\mathbb{R}^d, d\gamma)}^2}\right) d\gamma \geq 0.$$

Proof. We learn from (15) that

$$\int_{\mathbb{R}^d} |x|^2 h(t, x) d\gamma = d \|u\|_{L^2(\mathbb{R}^d, d\gamma)}^2 + e^{-2t} \int_{\mathbb{R}^d} (|x|^2 - d) h_0 d\gamma \quad \forall t \geq 0.$$

Hence [12, Theorem 1.2] and [12, Ineq. (3.4)] apply with

$$h(\mu) \geq \frac{\kappa[u]}{6\sqrt{3}}.$$

and the remainder of the proof of Theorem 2 is unchanged. \square

A similar extension of Theorem 3 can be done on the same basis. Details are left to the reader. As for Proposition 1, we can make the following observations. The case $\int_{\mathbb{R}^d} |x|^2 |v|^2 d\gamma \leq d$ is already covered in Lemma 4. If

$$A := \int_{\mathbb{R}^d} |u|^2 (|x|^2 - d) d\gamma$$

is positive, let us consider the solution h of (9) with initial datum $h_0 = u^2$. We know from (15) that

$$\int_{\mathbb{R}^d} h(t, x) (|x|^2 - d) d\gamma = A e^{-2t}$$

and deduce as in the proof of Lemma 4 that

$$4 \mathcal{S}[v] = \int_{\mathbb{R}^d} |\nabla P|^2 h d\gamma = \int_{\mathbb{R}^d} h(\mathcal{L}P) d\gamma + A e^{-2t} \leq \sqrt{d \int_{\mathbb{R}^d} \|\text{Hess} P\|^2 h d\gamma} + A e^{-2t}$$

with $P = -\log h$. Hence by (13), we learn that

$$\frac{d}{dt} \mathcal{S}[v] + 2 \mathcal{S}[v] = -\frac{1}{2} \int_{\mathbb{R}^d} \|\text{Hess} P\|^2 h d\gamma \leq -\frac{1}{2d} (4 \mathcal{S}[v] - A e^{-2t})^2$$

and this estimate can be rephrased with $z(t) := e^{2t} \mathcal{S}[v(t, \cdot)]$ as

$$z' \leq -\frac{e^{-2t}}{2d} (4z - A)^2.$$

Knowing that $z' < 0$ is an improvement on the decay rate $\mathcal{S}[v(t, \cdot)] \leq \mathcal{S}[u] e^{-2t}$ can be rephrased as an improved entropy – entropy production inequality for $A > 0$.

Acknowledgements

The authors thank Max Fathi and Pierre Cardaliaguet for fruitful discussions and Emanuel Indrei for stimulating interactions. G.B. has been funded by the European Union's Horizon 2020 research and innovation program under the Marie Skłodowska-Curie grant agreement No 754362.

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