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Design of an intelligent multi-sensor medical device for the detection of low mobility.

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Context and Objectives

In the context of chronic pain management, there is a need for a secure, autonomous, non-invasive wearable device able to collect sedentary data and monitor patients daily.

- 1. Detect and quantify sedentary and physical activity levels for patients with chronic pain.
- 2. Patient surveillance and evaluation of medical intervention efficiency.
- 3. Detailed result interpretation based on quantitative data.
- 4. Provide a learning tool that can be used to detect similar physiological patterns, characteristic behaviour or bio-markers from different subjects.

Methods and Materials

- Physical activity detection and data collection:
- ▶ Activity detection using an Inertial Measurement Unit (IMU)
- ▶ Data processing and analysis:
 - An ARM-based (Cortex-M family) Micro-controller processes data and runs them through an embedded deep learning model for activity classification.

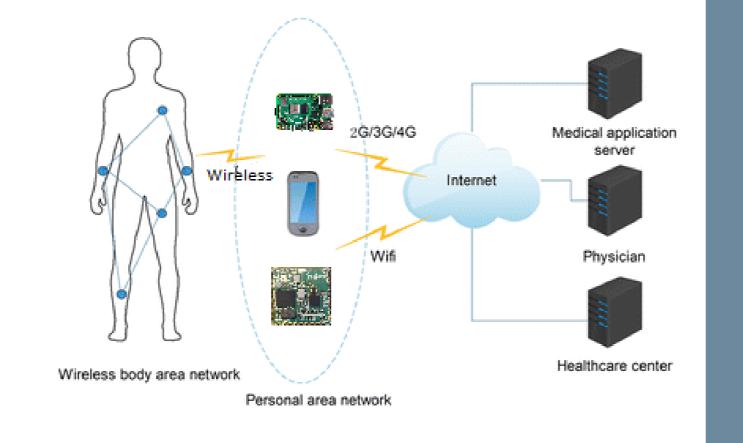


Figure 1:Body Area Network

- ► Data transmission:
- ▶ The model output is transmitted to a sink using a low energy module.
 i.e Bluetooth Low Energy (BLE), LoRa

Deep learning

The first model was built using a public dataset of data collected on smartphone with different subjects [1]

- ► Characteristics:
 - ▶ Multiple sensor data (Accelerometer, Gyroscope and Magnetometer)
 - ▶ Multiple positions (pockets, belt, upper-arm and wrist)
 - Collected at a frequency of 50Hz
- ► Feature Engineering and Extraction:
 - Data preparation and train-test split (80% 20 % respectively)
 - ▶ Model training and accuracy evaluation using a DCNN Model (Deeep Convolutional Neural Network).[2]
- Deployment:
- \triangleright Model conversion to a C++ library using TensflowLite [3]
- ▶ Inference run directly on Micro-controller

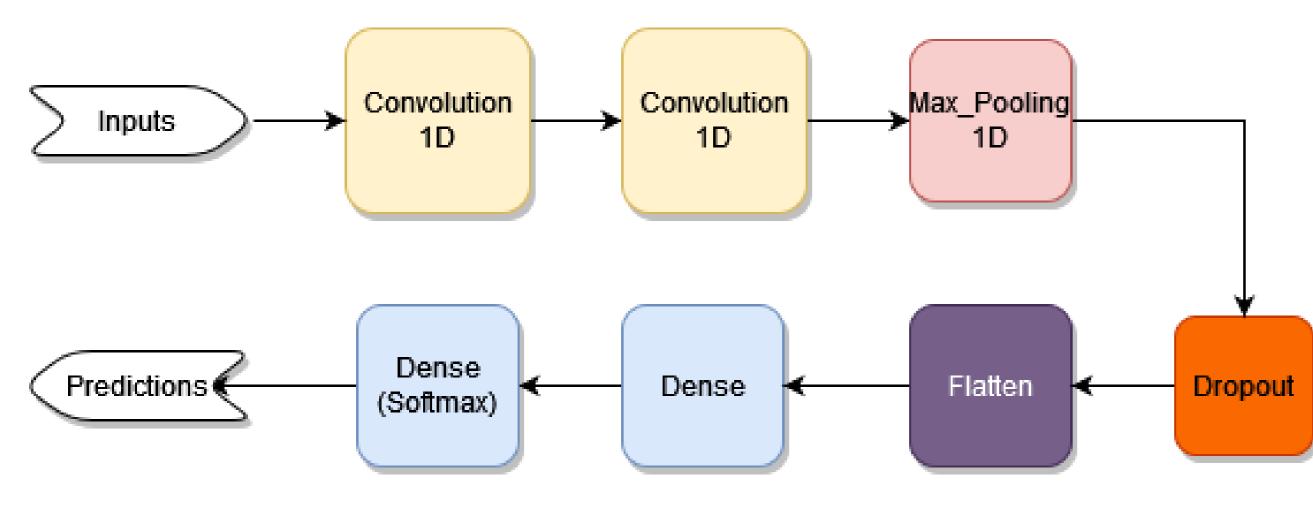


Figure 2: Model structure

Results: Model Features

► Feature selection:

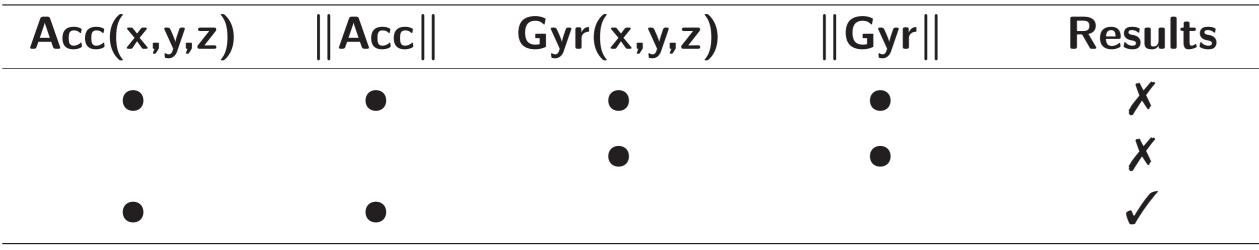


Table 1:Feature selection

- *The use of magnetometer data in combination with accelerometer based data does not necessarily improve classification accuracy.
- ► Model performance on a single position:

Position	Pockets	Belt	Upper-arm	Wrist
Accuracy	98.8%	95.7%	90.3%	94.6%

Table 2: Model accuracy on different positions

Results: Model Evaluation

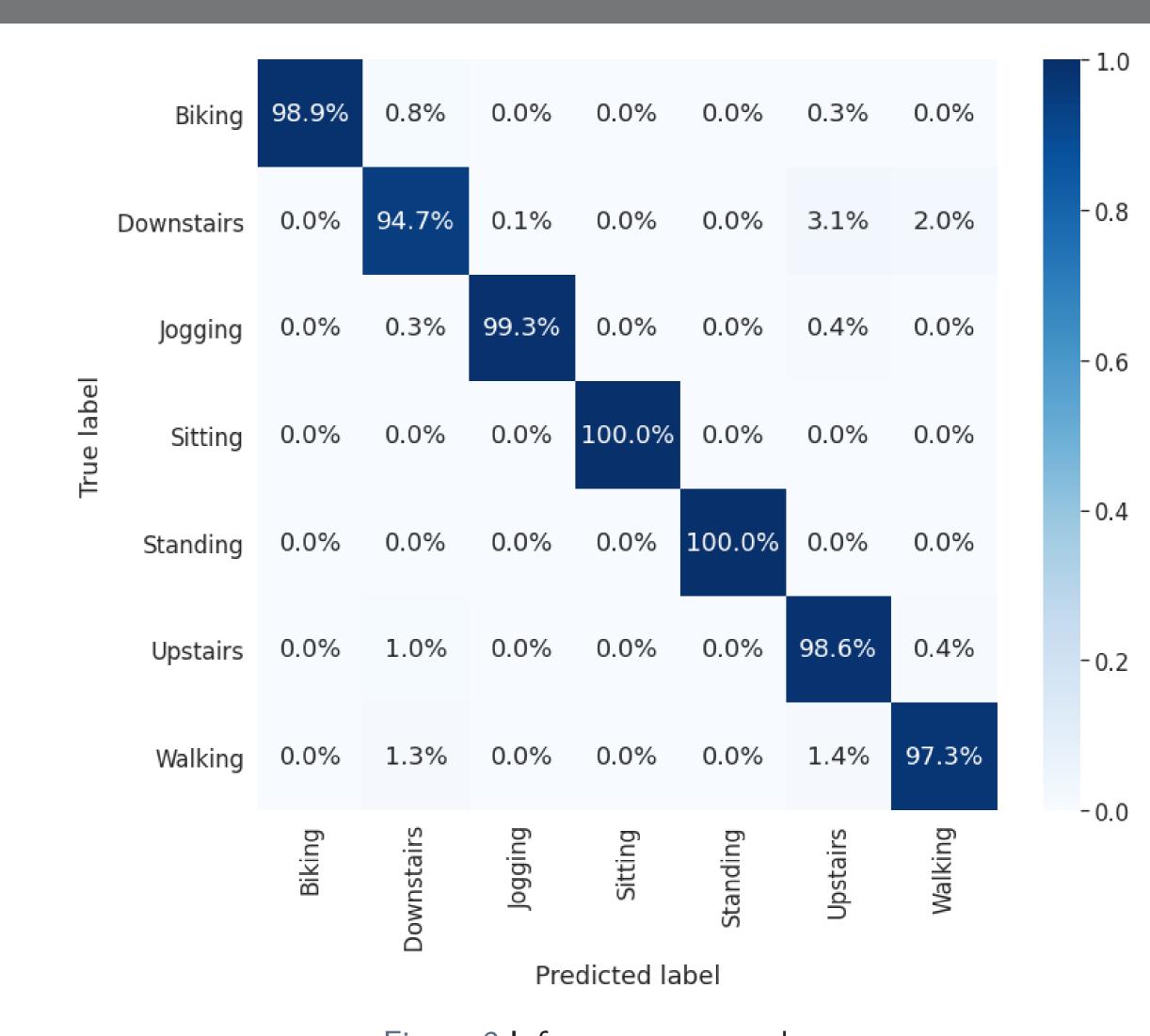


Figure 3:Inferences on test data

Data Collection

After a successful inference run using the model generated from public dataset, we conducted multiple data acquisition sessions on different participants performing complex daily activities.

- ► Data Collected:
 - ▶ Accelerometer data on 3 positions (Belt, Wrist and ankle)
 - ▶ High-Resolution video, Optical Motion data (Qualisys Track Manager)

Conclusion

- ► We proved that deep-learning algorithms can be used for human activity recognition even on resource constrained embedded systems whith good accuracy.
- ▶ Power consumption reduction by 10% using Embedded-Al versus Remote Al
- ► Creation of a custom dataset with complex gestures and multiple nodes, this dataset will be used in future studies.
- ► Future Work:
 - Defining an energy consumption model.
 - ▶ Generating a deep learning model with our data.
 - ▶ Use of distributed DCNN model on multiple sensors forming a BAN (Body Area Network)
 - Designing and building a custom device with optimized memory and enrgy consumption

References

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