

# Experimental investigation of the alternate recurrence of quasi-static and dynamic crack propagation in PMMA

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## Experimental investigation of the alternate recurrence of

- <sup>2</sup> quasi-static and dynamic crack propagation in PMMA.
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Abstract The alternate (stick-slip) cracking phenomenon in Poly(methyl methacry-7 late) (PMMA) was investigated using high-speed imaging and digital image correla-8 tion (DIC). PMMA is known to show a great variety of fracture behaviors by even small a changes in loading conditions. With TDCB-shaped samples and under a range of con-10 stant extension rates, the phenomenon of alternate cracking is observed. Here, loops of 11 successive quasi-static and dynamic crack propagation are found within a single frac-12 ture experiment suggesting a 'forbidden' velocity regime. For the first time, such ma-13 terial/structural cyclic fracture behavior is examined through the lens of linear elastic 14 fracture mechanics (LEFM) by using in-situ High-Speed (HS) DIC. Energy release rates 15 and crack velocities during fracture experiments are derived from full-field measure-16 ments using Williams' series expansion. Fracture surfaces of post-mortem samples have 17 been systematically analyzed using optical microscopy. The investigation of the actual 18 limits of the 'forbidden' velocity regime in terms of critical velocity and energy release 19 rate in relation to post-mortem crack length features is achieved by holistic experimen-20

- tal data on alternate cracking. This work provides key experimental data regarding the
- <sup>22</sup> improved understanding of a unified theoretical framework of crack instabilities.

23 Keywords Polymers · Fracture Mechanics · High Speed DIC · Stick-Slip · 'Forbidden'
 24 Velocity

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## 25 1 Introduction

Even the failure of the smallest structural component can be the source of the global col-26 lapse of an entire engineering structure with severe consequences. Thus, understand-27 ing the mechanisms of failure by studying the formation and propagation of cracks is 28 of utter importance in preventing such damaging events. A crucial parameter in frac-29 ture mechanics for experimental investigations of crack propagation is the crack veloc-30 ity, as they are strongly related to underlying fracture mechanisms. In brittle materi-31 als, a wide range of velocities can already be explored by relatively minor variations in 32 loading conditions. Within this span of observable velocities, two independent groups 33 of interest—slow (quasi-static) and fast (dynamic) cracking—are covered in literature. 34 Without considering impact tests, at very large constant extension rates, cracks typically 35 propagate at very high velocities (about 0.5 times the Rayleigh wave speed) (Dally et al., 36 1985; Miller et al., 1999; Scheibert et al., 2010). In that case, cracks are considered unsta-37 ble, which means that no additional load is required to significantly propagate the crack, 38 eventually resulting in total failure of the sample. On the contrary, with a sufficiently 39 slow loading rate, the crack propagates continuously stable with velocities at least two 40 order of magnitude slower (Marshall et al., 1974; Beaumont and Young, 1975; Vasude-41 van et al., 2021). Between these two regimes, the phenomenon of alternate cracking 42 (Ravi-Chandar and Balzano, 1988; Hattali et al., 2012) is observed for some materials. 43 Even though the crack is driven by a constant extension rate, the two unique cracking 44 behaviors can be found within one fracture experiment. Between these two propaga-45 tion types, a range of velocities is suggested that can not be exploited by the crack. This 46 causes a gap between the two well-defined phases of quasi-static and dynamic propa-47 gation that is commonly described as 'forbidden' velocity regime. Due to experimental 48 (crack velocity mismatch of about two orders of magnitude) and theoretical consider-49 ations (apparent theoretical mismatch regarding the mechanisms), these two regimes 50 have been investigated individually up to now. As a consequence, the 'forbidden' veloc-51 ity regime has only been approached from both sides without clearly quantifying en-52 ergies and velocities involved during transitions. The experimental design in this work 53 however allows the investigation of the reoccurring appearance of the two particular 54 crack propagation types during one fracture process in PMMA. Better estimations of the 55 'forbidden' velocity regime, considering in-process viscous effects (history-dependent), 56 can be accomplished. Thus, to achieve improved velocity measurements through high 57 temporal and moderate spatial resolution, up to date high-speed imaging has been 58 employed. Energy release rate estimations benefit from direct measurements of crack 59 60 tip positions and linear elastic fracture mechanic (LEFM) parameters through full-field 61 measurements using digital image correlation (DIC) and Williams' series expansion.

The presented work is introduced with a brief description of the theoretical background and existing literature mainly regarding the experimental exploration of alternate cracking. In the following, relevant information related to the experimental program including short technical explanations of DIC and Williams' series expansion is presented. The work is then concluded by discussing the results of multiple TDCB experiments and a summary of the presented study.

### 68 2 Alternate (stick-slip) cracking

<sup>69</sup> Beforehand, different terminologies are found in literature discussing this fracture phe-

- 70 nomenon. The most commonly used expression is stick-slip, due to the theoretical
- 71 proximity with observations during the frictional phenomenon of sliding (Feeny et al.,
- 1998). In this study, however, alternate cracking is used to additionally specify and sep arate between sliding and fracture related observations.

#### 74 2.1 Basic theoretical background

- 75 The specific behavior for materials showing alternate cracking is classically described by
- **76** the kinematic law of brittle fracture in the space of energy release rate (G) as a function of the areal value sity (u) in the log code (Figure 1)
- of the crack velocity (v) in the log-scale (Figure 1).



Fig. 1: Kinetic law ( $G_c$ -log  $\nu$  curve) for materials showing alternate cracking (stick-slip) behavior.

This kinematic law can be subdivided into three regions. Region I depicts a quasistatic propagation phase in which the Griffith criterion (Griffith, 1921) should apply.

80 However, when varying the crack velocity over decades, it has been observed exper-

imentally that the critical energy release rate actually depends on the crack veloc-

<sup>82</sup> ity. Consequently, in this region, the crack speed is driven by its relationship with the

critical energy release rate that varies between  $G_c$  for infinitely low crack speeds and

avalanche threshold  $G_a$  at the transition with region II (A  $\rightarrow$  B). Extreme crack tip accel-

erations take place during the following region II with a supposedly "softening" branch

- causing the jump from the region I to the dynamic region III (B  $\rightarrow$  C). Hereinafter,
- <sup>87</sup> the crack finds itself in the dynamic region where the generic Kanninen's relationship  $(K = K = (1 + 1)^m)$  is the last of K = 1 + 1.
- <sup>88</sup>  $(K_{ID} = K_{IC}/(1 (v/c_R)^m)$  with the dynamic SIF  $K_{ID}$ , static SIF  $K_{IC}$ , crack tip velocity v, <sup>89</sup> Rayleigh wave speed  $c_R$  and material constant m) of dynamic fracture (Kanninen and

Popelar, 1985) can be applied, and crack tip speeds are restricted by the dynamic limiting speed of Rayleigh wave speed ( $c_R$ ). However, during the high-velocity branch (region

<sup>92</sup> III), crack tip speeds in alternate cracking slow down after a certain propagation length

to a point of arrest. This arrest marks the beginning of the second jump back to the slow

velocity branch. For this, authors in existing literature generally propose the crack to fol low along the reference points D to A. All this, due to the reiterating behavior, explains

the appearance of a hysteresis implying a 'forbidden' velocity zone (between  $v^B$  and  $v^D$ ).

A typical example of a fracture surface linked to such cracking is shown in Figure 2.
 Here, the two particular surface markings related to quasi-static and dynamic propa gating cracks can be observed.



Fig. 2: Crack surface recorded with an inclined high resolution camera through the bulk of a transparent PMMA specimen visualizing the two phases of alternate cracking.

#### 101 2.2 Existing literature

While regions I and III are being well defined and investigated independently, insufficient experimental data and few modeling attempts are provided in the literature to fuse
the two regions with a proper description of the 'forbidden' region II. In the following, by
focusing on the most recent modeling attempt and presented experimental methods,
existing literature on alternate cracking will be presented briefly.

Most recently, (Vincent-Dospital et al., 2020) provided a predictive model of the frac-107 turing behavior in PMMA based on the theoretical concept of thermal softening. In this 108 model, the failure process is thermally activated and combined with the dissipation and 109 diffusion of heat in the process zone surrounding the crack tip. Covering the vast range 110 of different crack tip speeds found in PMMA fracturing, their thermodynamic approach 111 showed good compliance with the experimental data of quasi-static and dynamic frac-112 turing experiments. Furthermore, the two well-defined 'stable' regimes were connected 113 by the model through a continuous description of the 'softening' branch. Noteworthily, 114 no experimental data of alternate cracking was considered. Notice, for terminology pur-115 pose, that this unified model introduces the concept of sub-critical failure. Indeed, con-116 trary to the discussion made around Figure 1, where velocity domains where classified 117 through a discontinuous transition from classical Griffith theory to Kanninen's type rate 118 dependent relationship, the authors propose that the actual critical energy released rate 119 is reached at high velocity (~165 m.s<sup>-1</sup>), while initiation and propagation at lower speed 120 is supposedly sub-critical. 121

To this day, different methods have been used to experimentally investigate the phenomenon of alternate cracking. In the work of (Ravi-Chandar and Balzano, 1988), PMMA and Homalite-100 fracturing of single-edge-notched (SEN) and compact tension (CT) specimens were investigated by focusing on the temporal evolution of the

4

stress intensity factor. Stress intensity factor (SIF) data has been obtained through the method of caustics (Beinert and Kalthoff, 1981) using a camera system at 12 kfps over a duration of one minute. Crack length and  $K_I$  measurements were retrieved during quasi-static propagation phases of alternate cracking experiments, while the experimental setup did not support dynamic phase measurements.

(Hattali et al., 2012) investigated the phenomenon in PMMA, by focusing on crack 131 tip speeds and fracture surfaces, using a high-resolution camera (maximal temporal and 132 spatial resolution of 396 fps and 21 Mpix, respectively) and an in-house image process-133 ing tool. The system setup only allowed for the investigation of quasi-static crack prop-134 agation phases. Thus, only the lower limit of the 'forbidden' velocity regime, i.e.  $v_a$ , was 135 investigated and found to be 3.5 cm.s<sup>-1</sup> and 4.0 cm.s<sup>-1</sup> for the two observed dynamic 136 bursts, respectively. However, with an interframe of approx. 2.5 ms, it has to be expected 137 that phase transitional velocities were not captured accurately. 138

(Vasudevan, 2018) contributed an in-depth investigation of cracking in PMMA, ded-139 icating a chapter of his PhD manuscript to the transition phase from dynamic to quasi-140 static propagations. During the experiments, load cell and clip gauge have been used 141 to obtain force and displacement data, respectively. Crack tip positions have been ob-142 tained by using a high-speed camera system (temporal and spatial resolution of 48 kfps 143 and  $\sim 175$  kpix, respectively) and a home-made algorithm. By combining these re-144 sults, SIF and thereby fracture energies have been derived through a numerical (FE) 145 based compliance chart relying on load and displacement data. However, difficulties in 146 this setup arise in the high-velocity regime, where the accuracy for load and displace-147 ment measurements can not be assured. Furthermore, the chosen sample geometry 148 had the unique purpose of studying dynamic to quasi-static crack propagation transi-149 tions. TDCB specimens with the notch being blunted by a circular hole allow for the 150 initiation of a dynamically propagating crack while using low tensile extension rates 151  $(\sim 2.5 \,\mu m.s^{-1})$ . Here, with respect to the theoretical concept of fracture in PMMA (Figure 152 1), the crack finds its way back to the master curve far below the value of  $v_a$  by following 153 the path  $D \rightarrow A$ , which can be explained by the relatively low extension rate. After the 154 arrival of the initiated dynamic crack, by assuming an infinite sample length, the crack 155 would have propagated entirely quasi-static in the wake. Hence, the presented experi-156 ments are a matter of quasi-static experiments introduced by dynamic crack propaga-157 tion. 158

Under the scope of providing a model of the fracturing behavior in PMMA, (Vincent-Dospital et al., 2020) performed wedge-splitting fracture experiments on PMMA sam-160 ples over a wide range of quasi-static driving speeds (1.6  $\mu$ m.s<sup>-1</sup> to 1.2 mm.s<sup>-1</sup>). Force 161 data were monitored in real-time by the load cell, while the propagating crack was fol-162 lowed by a high-resolution camera. In this case, for quasi-static propagation measure-163 ments, the temporal resolution of 10 fps provided crack length and subsequently ve-164 locity measurements by post-treating the images with the in-house crack tip detection 165 algorithm. On the other hand, fast crack propagations were detected, through an os-166 cilloscope, by the successive rupture of parallel 500  $\mu$ m large chromium or gold lines 167 on the surface. Numerical charts based on FE analysis supported the determination of 168 mode I related stress intensity factor  $K_I$ . Energy release rates then were retrieved under 169 plane stress assumption. 170

In summary, literature shows that the investigation of region II has been conducted by experimental procedures only suitable for either of the two other enclosing regions. Crack-speeds are usually obtained from camera systems (either high-speed or high-resolution) and tracking algorithms. *K*<sub>I</sub> and subsequently energy release rates are

mostly obtained from numerical compliance methods or analytical charts, which are 175 limited due to low accuracies in high loading rate cases. Note that region II is classically 176 referred to as 'forbidden' velocity regime, but the model proposed in (Vincent-Dospital 177 et al., 2020) suggest that it could be reached if the simulation or the experiment can 178 be conducted by controlling the crack speeds. However, this is impossible to achieve 179 neither numerically nor experimentally, with the energy release rate being governed by 180 the applied load as the controlled parameter. Beyond the methodological contribution 181 of investigating alternate cracking through high-speed DIC, we address in the follow-182 ing the experimental investigation of alternate cracking by focusing systematically on 183 crack velocities, SIFs and their relation to the fracture surface. Like this, transitions from 184 dynamic to quasi-static and quasi-static to dynamic can be studied. Hence, we pro-185 pose a compromised experimental configuration, based on high-speed fullfield mea-186 surements (DIC), and on asymptotic solutions of kinematic fields to get not only FE 187 independent and chart-free estimations of the SIFs, but also sub-pixel estimations of 188 crack tip positions. Additionally, the contribution of this study can be summed by the attempt of providing experimental data for an improved estimation of the hysteretic 190 fracturing behavior described by the loop following path B, C, D and A' in Figure 1. 191

#### 192 3 Experimental program

193 Experiments have been performed during two independent experimental campaigns,

called M1 and M2. Setup, material and loading conditions have been kept consistent,

while using different sample thicknesses. 5 mm and 8 mm thick plates have been used

196 for the specimen preparation of the M1 and M2 campaign, respectively.

#### 197 3.1 Material and geometry of the specimen

In this study, alternate cracking, specific to Poly(methyl methacrylate) (PMMA) (Ravi-198 Chandar and Yang, 1997), as well as polyesters (Leevers, 1986), epoxy resins (Yamini and 199 Young, 1977), rubber (Isherwood and Williams, 1978) and polymeric adhesives (Maugis 200 and Barquins, 1988), is investigated. Due to its ideal brittle behavior and the presence 201 of different cracking behaviors at varying loading conditions, PMMA is a material of 202 great interest in fracture mechanics research and an ideal model material for this in-203 vestigation. Here, molded PMMA (Perspex® and Plexiglas® for M1 and M2 campaign, 204 respectively) was the material of choice. For details on material properties and its me-205 chanical behavior, the authors refer to (Ali et al., 2015). The tapered double-cantilever 206 beam (TDCB) shape was chosen to have a constant specimen compliance w.r.t. the 207 crack length and ensure stable crack propagation. The samples were obtained by using a 208 class 4 laser cutting machine (130 W). Notice that pin holes have been manually drilled 209 to avoid laser beam (conical shape) related clearance angles ( $\sim 1.5^{\circ}$ ), which would in-210 duce transverse load, i.e. potential sample bending. The detailed sample geometry can 211 be found in Figure 3. 212

Notice that caution is required regarding sample preparation for achieving good repeatability. Indeed, PMMA fracture behavior is very sensitive to temperature (Atkins
et al., 1975a,b), but also to any significant interaction with organic solvents (Wang et al.,
1994). In that context, ethanol (eventually used for surface cleaning) should be avoided,
and solvent free paints should be preferred for DIC patterning of the sample surface.



Fig. 3: Sample geometry [mm].

Table 1: Second loading stage extension rates applied during the experiments.

Extension rate [mm.s <sup>-1</sup> ]	Test
1.0	M1-T2, M2-T15, M2-T19
0.5	M1-T3, M1-T6

218 3.2 Loading and test configuration

All experiments were performed using an Instron all electric dynamic and fatigue test-219 ing system (ElectroPuls E10000) with a load cell of 1 kN maximum loading capacity in a 220 temperature controlled (21 °C) room. Beforehand, preliminary experiments were con-221 ducted to identify the alternate cracking domain within the experimental environment. 222 With respect to the used material and geometry, solely quasi-static propagation has 223 consistently been found below extension rates of 0.1 mm.s<sup>-1</sup>. First dynamic bursts have 224 been observed between 0.1 mm.s<sup>-1</sup> and 0.5 mm.s<sup>-1</sup> with strong variability from one test 225 to another. Following this domain of inconsistency, alternate cracking was systemati-226 cally determined in a repeatable manner (Figure 2). Entirely dynamic cracks have been 227 found for extension rates above 20 mm.s<sup>-1</sup>. Extension rates close to the lower end of 228 the identified alternate cracking domain have been used to provoke higher repetition of 229 crack arrests while maintaining reasonable quasi-static lengths. Additionally, to achieve 230 an experimental consistency of the crack line by avoiding influences of the notch tip on 231 the subsequent cracking and the point of initiation for different cracking experiments, 232 a two stages loading procedure was established: 233

1. Controlled quasi-static crack propagation. During this stage a relatively slow exten-234 sion rate of 0.01 mm.s<sup>-1</sup> was imposed. Stage change has been executed by the help 235 of the Static Break Detector option within the Instron WaveMatrix software (Figure 236 4). The tool is designed to trigger a user-selected action when the monitored signal 237 falls below or rises above a pre-defined value (event value). 25 N was selected for the 238 event value, which generally led to slow propagating cracks of about 5-10 mm. 239 2. Alternate crack propagation. A second loading stage was introduced to release the 240 alternate crack propagation from this fresh pre-crack. During this stage, the exten-241 sion rates being used during the different experiments are shown in Table 1. 242



Fig. 4: Example of stage change method (Static Crack Detection).



Fig. 5: Experimental setup: (a) sketch, (b) picture.

### 243 3.3 Experimental setup

Alternate cracking is a phenomenon, where two entirely different cracking behaviors 244 are to be found during solely one fracturing process. Hence, for relevant data acqui-245 sition during the dynamic crack propagation phases, the experiments are in need of 246 high speed imaging. Here, images of the cracking sample were captured using a Photron 247 FASTCAM Mini AX camera system with an acquisition speed of 40 kfps. Sufficient light-248 ing of the sample was ensured by LED projectors (EFFI-Sharp PWR FF by Effilux). Master 249 device for camera triggering has been the tensile machine, which sent a 5 V TTL trigger 250 signal to an oscilloscope once the second loading stage has been activated. A thresh-251 old in the oscilloscope was then used to trigger the camera system. Hence, only second 252 loading stage results have been recorded. Picture and sketch of the experimental setup 253 can be seen in Figure 5. Camera specifications related to the experiments are presented 254 255 in Table 2.

#### 256 3.4 Fracture parameters by DIC

- <sup>257</sup> The foundation for retrieving the sought-after fracture mechanics variables is found in
- DIC by providing full-field displacement measurements from sequential images. By fol-
- lowing the principle of conservation of brightness between a reference (f) and a deformed image (g), i.e. the equation of optical flow, DIC presents an ill-posed non-linear

Campaign	M1	M2
Camera	Photron FASTCAM Mini AX	
Image resolution	896×160 pix	
Acquisition rate	40,000 fps	
Exposure time	25 µs	
Lens	TOKINA 100 mm	
Aperture	f/2.8	
Field of view	74×13 mm	64.5×11.5 mm
Image scale	$1 \text{ pix} = 83 \mu\text{m}$	$1 \text{ pix} = 72 \mu\text{m}$
Patterning technique	Spray paint	

Table 2: DIC hardware parameters

261 inverse problem:

$$f(\underline{X}) = g(\underline{X} + \underline{u}(\underline{X})) \tag{1}$$

with u(X) being the sought displacement field. To bypass this ill-posed problem, the 262 pixel displacement has to be parameterized using shape functions. Here, FE discretiza-263 tion has been used (Besnard et al., 2006). Eventually, the problem can be linearized and 264 solved iteratively in a least-squares sense. A median regularization is used to mitigate 265 detrimental impact of noise and smaller elements. By post-treating the displacement 266 field, variables relevant for fracture mechanics analysis (e.g. SIFs and crack tip posi-267 tions) were derived through Williams' series expansion. Traditionally, in the case of a 268 semi infinite linear elastic isotropic media, stress and displacement fields around the 269 crack tip depend on SIF, the distance to the crack tip (r) and the angle ( $\theta$ ) in a polar 270 reference system attached to the crack tip (Williams, 1957). Thus, by knowing the dis-271 placement field through DIC and projecting it onto the analytical solution, different 272 fracture mechanics parameters can be derived through a non-linear inverse problem 273 (Roux and Hild, 2006; Réthoré, 2015; Roux-Langlois et al., 2015). The displacement field 274 around the crack tip is written as following: 275

$$u(r,\theta) = \sum_{i=I,II} \sum_{n=-\infty}^{\infty} A_i^n r^{n/2} g_i^n(\theta)$$
<sup>(2)</sup>

with the distance to the crack tip r, the angle  $\theta$  in a polar reference system attached to the crack tip, Williams' coefficients A and base function g. The base function  $g_i^n(\theta)$  has the following form:

$$g_{I}^{n}(\theta) = \frac{1}{2\mu} \begin{bmatrix} (\kappa + n/2 + (-1)^{n}) \cos[(n/2)\theta] - (n/2)\cos[(n/2 - 2)\theta] \\ (\kappa - n/2 - (-1)^{n})\sin[(n/2)\theta] + (n/2)\sin[(n/2 - 2)\theta] \end{bmatrix}_{(e_{t}, e_{n})}$$
(3)

$$g_{II}^{n}(\theta) = \frac{1}{2\mu} \begin{bmatrix} -(\kappa + n/2 - (-1)^{n}) \sin[(n/2)\theta] + (n/2)\sin[(n/2 - 2)\theta] \\ (\kappa - n/2 - (-1)^{n}) \cos[(n/2)\theta] + (n/2)\cos[(n/2 - 2)\theta] \end{bmatrix}_{(e_{1}, e_{2})}$$
(4)

with  $\mu$  and  $\kappa$  being the shear modulus and the Kolossov's constant, respectively. Kolossov's constant under plane stress is  $\kappa = (3 - \nu)/(1 + \nu)$  with  $\nu$  being the Poisson's ratio.

Equation 2 states, that displacements can be computed for an infinite sum of modes. However, limiting the solution to  $n_{min} = -3$  and  $n_{max} = 7$  is sufficient to retain the relevant crack features. For quasi-brittle medium, good agreement of the mechanical fields can be established outside the process zone of the crack for the following Williams' series coefficient  $(A_i^n)$  solutions:

Campaign	M1	M2		
Test	2, 3, 6	15, 19		
DIC				
Software	UFreckles (Réthoré, 2018)			
Discretization	FE-based global DIC			
Shape function	Bi-linear quadrilateral			
	Lagrange element (Q4P1)			
Element (subset) size	0.581 mm (7 pix)	0.576 mm (8 pix)		
Post-filtering	Median filter using			
	1 <sup>st</sup> neighbours applied to U			
Williams' series projection				
Е	3.5 GPa			
ν	0.32			
R <sub>min</sub>	1.16 mm	1.15 mm		
R <sub>max</sub>	6.39 mm	6.34 mm		

Table 3: DIC & Williams' series parameters

- n = 0, in-plane rigid body translations
- n = 1, asymptotic terms  $K_I$  and  $K_{II}$

n = 2, T-stress and in-plane body rotations

Notice that the projection zone is defined by  $R_{min}$  and  $R_{max}$ . On the one hand, the 290 asymptotic behaviour near the crack tip of the fields computed by the super-singular terms (n < 0) do not provide any physical meaning and are therefore classically ne-292 glected. However, when the crack tip position is sought, these super-singular functions 293 appear in the required basis (n=-1 being, up to a scaling factor, the derivative of n=1 294 with respect to the assumed crack tip position). To not induce biases due to truncation, 295 terms for n down to -3 are considered. Hence, data at a distance to the crack tip smaller 296 than  $R_{min}$  are discarded to maintain reasonable conditioning of the least-squares prob-297 lem. On the other hand,  $R_{max}$  – defining the projection zone size externally – has to be 298 small enough to avoid influences of the free boundary, but large enough to still include 299 a sufficient amount of mesh points in the domain. The right size of projection zone, i.e. 300 defining  $R_{min}$  and  $R_{max}$  (see Table 3), has been identified through a parametric study. 301 Furthermore, by using a pre-defined crack path, the super-singular term n = -1 is used 302 to estimate the position to the equivalent elastic crack tip along this path (Réthoré et al., 303 2011). In the context of the study, relevant coefficients of the solution imply n = -1 and 304 n = 1, i.e. crack tip detection and SIFs. It is worthwhile mentioning, that the quasi-static 305 form (not in function of the velocity) of the displacement field around the crack tip is 306 used in line with previous works showing that marginal errors can be assumed for ve-307 locities below  $0.5c_R$  (Lee et al., 2010). Eventually, the outcome is used to derive crack 308 velocities and energy release rates. The second, under the assumption of plane stress, 309 has been computed through Equation 5. 310

$$G = K_1^2 / E \tag{5}$$

with  $K_1$  and E being the SIF related to mode I and Young's Modulus, respectively. DIC and Williams' series projection results have been obtained entirely by accessing the library of the open-source software UFreckles (Réthoré, 2018). All relevant parameters for the two procedures are listed in Table 3.

#### 315 3.5 Post-processing and method synchronization

To get derivatives such as the crack velocity, raw crack tip measurements had to be 316 filtered accordingly. The need for high speed imaging to obtain sufficient amount of 317 data points during dynamic crack propagation led to comparable huge sets of data for 318 the quasi-static propagation phases. With a difference of tens (dynamic) to thousands 319 (quasi-static) of data points between the two regimes, the data set had to be separated 320 and post-filtered by different kernel sizes. The post-filtering has been performed by us-321 ing a Savitzky Golay filter with a second order polynomial. Depending on the regime af-322 filiation, a filtering window size of 7.275 ms (291 frames) or 75  $\mu$ s (3 frames) has been ap-323 plied for quasi-static and dynamic regimes, respectively. The relatively strong and rather 324 insignificant kernel size for, respectively, the quasi-static and dynamic phases deemed 325 to be fitting to not drastically influence crack speed evolution in the quasi-static parts 326 or decrease the accuracy of the dynamic phase measurements. 327

To investigate crack kinetics, not only high-speed recordings but also post-mortem 328 high resolution microscopy was performed. Therefore, the comparison of data obtained 329 by techniques with different spatial resolutions are in need of harmonization. Here, as 330 the notch tip can easily be identified in DIC and microscopic images, it served as com-331 mon point of reference. By doing so, DIC obtained crack tip positions were tied to post-332 mortem microscopic images. The most dominant error sources related to the process of 333 spatial matching are the manual selection of the notch position ( $\sigma_{natch}$ ) and the pixel to 334 meter conversion ('pix2m') uncertainty ( $\sigma_{pix2m}$ ). Due to camera resolution, used lens 335 and clearance angle of the sample cut, the uncertainty on the notch tip localization has 336 been evaluated to be about  $\sigma_{notch} = 1.5$  pix. Pixel to meter conversion values have been 337 identified by analysing ruler images taken before each test, with the help of the Fast 338 Fourier transform (FFT) approach. The uncertainty of the 'pix2m' value has been eval-339 uated to be about  $\sigma_{pix2m} = 1.12 \times 10^{-3}$  pix as the FFT sampling was chosen to be the 340 horizontal pixel size of the image (896 pix). First approximation of the crack tip local-341 ization uncertainty ( $\sigma_T(a)$ ) can be evaluated through the following equation: 342

$$\sigma_T(a) = (a \times \sigma_{nix2m} + \sigma_{notch}) \times pix2m \tag{6}$$

with *a* being the crack length at any position of interest. A maximal error of approx. 160  $\mu$ m and 140  $\mu$ m have to be expected for the considered field of view (FOV) for ex-

periments related to campaign M1 and M2, respectively.

#### 346 4 Results

PMMA samples were subjected to the above described loading condition (see Chapter 347 3.2) and followed by a high-speed camera system. About 40,000 successive images over 348 a duration of one second were obtained for each experiment. The images were used 349 for DIC analysis and subsequently for the retrieving of fracture mechanic parameters. 350 Five tests have been taken into consideration coming from two different experimen-351 tal campaigns (M1 and M2). Representative for all experiments, full-field displacement 352 measurements (in y-direction) for the first and last recorded frame superimposed on 353 the appropriate image of experiment M2-T15 are presented in Figure 6(a) and Figure 354 6(b), respectively. In the same configuration, corresponding Williams' series projection 355 areas are presented in Figure 6(c) and Figure 6(d). Crack length data, retrieved through 356 the process of Williams' series expansion, are then presented in Figure 7 in the form 357



Fig. 6: Entire displacement field in y-direction [mm] and its corresponding Williams' series projection [mm] on the process zone surrounding the crack-tip (defined by  $R_{min}$  and  $R_{max}$ ) of the first ((a) and (c)) and last recorded image ((b) and (d)) for experiment M2-T15. The used Williams' series parameters are listed in Table 3.

of the temporal evolution of the normalized crack length. This is defined by the crack
length relative to the length of the samples (63mm from notch tip to sample boundary).
Furthermore, stable first stage crack propagations have been taken into consideration
for the presentation of the normalized crack length. This causes each experiment to
start from its own individual pre-crack length.

Each crack length evolution is showing a similar global behavior. After the pre-crack, 363 almost horizontal lines describe the first quasi-static propagation of the crack. Following vertical jumps indicate the dynamic cracking. The combination of the two regimes 365 is what is referred to as alternate cracking of the sample. This is depicted by the repeat-366 ing occurrence of vertical jumps surrounded by quasi-static phases. 4, 3, 2, 2 and 2 ver-367 tical lines, i.e. dynamically propagating cracks, are observed for tests M1-T2, M1-T3, 368 M1-T6, M2-T15 and M2-T19, respectively. The frame rate chosen for this investigation 369 leads to dynamic crack propagation phases being sampled by 4 to 7 images depending 370 on their propagation length. It will allow to have good estimations of the mean veloc-371 ity, while not being sufficient to accurately probe potential speed variations. Oscilla-372 tions in the crack length of the quasi-static rest phases appear always closely following 373 the dynamic bursts. These fluctuations can be explained by system vibrations due to 374 history-dependent effects induced by brutal, instantaneous dynamic bursts. It leads to 375 oscillations of the crack lips (opening and closing) causing the crack tip detection to 376 record backwards moving cracks. Furthermore, as they become more prominent when 377 the crack approaches the free end of the sample, the vanishing resistivity of the entire 378 sample seems to have an enhancing effect on the phenomenon. 379

For sake of clarity, two experiments will be prioritized for the continuation of the discussion. For this, M1-T2 and M2-T15 have been selected as representatives of the two experimental campaigns as the tests with the most quasi-static rest repetitions within their experimental campaign.

#### 384 4.1 Velocities

- To further differentiate among the crack propagation types observed during alternate
- cracking, crack speeds have been derived from the crack length. Figure 8 is showing
- the spatial evolution (as a function of crack length) of the crack speed for experiments
- M1-T2 and M2-T15. Only effective crack tip positions, i.e. always keeping the most ad-



Fig. 7: Normalized crack length (1.0 = 63 mm) as a function of recording time [s] for all five experiments.

vanced position as real position of the crack tip, have been taken into consideration to 389 avoid the influences of crack length oscillations discussed before. Two strongly different 390 crack speeds are observed in the experiments. Variations in dynamic crack speeds are 301 rather small, while crack speeds associated to quasi-static propagation show significant 392 oscillatory behavior. By taking both experiment M1-T2 and M2-T15 into consideration 393 (Figure 8), average crack tip speeds up to  $10.5 \text{ cm.s}^{-1}$  and between  $14 \text{ m.s}^{-1}$  to  $107 \text{ m.s}^{-1}$ 394 are observed during quasi-static and dynamic crack propagations, respectively. Average 395 dynamic crack speeds around ~14 m.s<sup>-1</sup> would portray a divergent observation from 396 the literature (Hattali et al., 2012; Vasudevan, 2018) documented dynamic crack speed 397 measurements during similar experiments. However, by taking the fracture surface into 398 consideration, one can see tiny rest bands (see Figure 9) appearing within the flat parts 399 of some dynamic bursts. The specific surface pattern is regularly found during transi-400 tion from dynamic to quasi-static phases (see Detail 2 and Detail 3 in Figure 9). Thus, the 401 rest bands suggest small pauses of the crack, too short to be visible in the recordings (in-402 terframe of 25  $\mu$ s) but long enough to significantly influence the crack speed measure-403 ments during these dynamic phases considering the frame rate of 40 kfps. The appear-404 ance of rest bands can be interpreted as intermittent behavior of dynamic cracks. The 405 amount of rest band appearances during the different dynamic bursts for all considered 406 experiments are listed in Table 4. Associated to this Table, Figure 10 provides a rela-407 tion between crack speeds and their corresponding propagating length. Here, cracking 408 phases with biased velocity measurements are marked in red. Globally, two groups of 409 propagation phases can be observed in the figure. Cracks with rest bands fall all within 410 the lower velocity range, while the others are found above. It appears that the limit av-411 erage velocity separating these two can be allocated at approx. 60 m.s<sup>-1</sup>. Indeed, with 412 sufficient temporal resolution to capture velocity variations during dynamic propaga-413 tion, rest band deceleration's could have been singled out. This would most certainly 414 cause the upwards shift in average velocity during these phases with the option of ex-415 cluding rest bands. However, by taking all bursts into consideration, a relation of in-416 creasing average velocity with increasing burst length can be assumed. A specific case 417 is found during the first dynamic burst of M2-T15. The particular surface roughening is 418 observed, even though no rest band is entirely formed. Nevertheless, crack deceleration 419 influencing the velocity measurement have to be expected. Thus, this burst will be con-420 sidered as biased and included to the rest band effected bursts. With an average velocity 421 of  $\sim 60 \text{ m.s}^{-1}$ , the dynamic burst seems to be at the velocity threshold for the formation 422



Fig. 8: Crack tip speed (v)  $[m.s^{-1}]$  as a function of the normalized crack length (a) [mm]. Black bars present the phase-dependent mean velocity  $[m.s^{-1}]$ , while their value is presented as numbers next to the bar with its standard deviation (std).

of rest bands. Hence, if dynamic bursts affected by rest bands (biased velocity measurements) are neglected, a 'forbidden' velocity regime of ~36 cm.s<sup>-1</sup> to ~36 m.s<sup>-1</sup> can be implied taking all conducted experiments into consideration. This is expressed in Figure 11, showing velocities with respect to the normalized crack length for all conducted experiments excluding dynamic phases that are considered to be biased. Notice, with average velocities above the identified threshold value (~60 m.s<sup>-1</sup>) for the formation of rest bands, instantaneous velocity measurements at the beginning and the end of rest

band free dynamic burst can fall below the threshold and thereby present the upper

431 bound of the 'forbidden' velocity regime.

#### 432 4.2 Connections to the fracture surface

In the following, more attention is given to the relation of experimental data and frac-433 ture surfaces. Microscopic images have been obtained by an optical microscope (Nikon) 434 with a resolution of 0.67  $\mu$ m.pix<sup>-1</sup>.  $K_I$  and velocity data as a function of the crack length 435 are presented in face with their corresponding fracture surface in Figure 12. Here, only 436 the propagation parts between notch tip and the beginning of the second dynamic 437 phase are presented. Like this, two quasi-static to dynamic and one dynamic to quasi-438 static transition can be seen. Crack propagation is from left to right and marked in 439 the left bottom corner of the figures. DIC ( $K_I$ , v) and microscopic observations (frac-440 ture surface) have been spatially matched with respect to the notch tip. Fracture sur-441 faces were recreated by manually stitching microscopic images with a field of view of 442  $1.715 \times 1.286$  mm. Hence, minor light differences can be seen between the sub-frames. 443



Fig. 9: Example fracture surface showing different particular surface observations. Detail 1, 2 and 3 are showing nucleation phase, rest band and the dynamic to quasi-static deceleration phase with the appearance of Wallner lines, respectively.



DYN-burst Test 2 1 3 M1-T2 0 0 2 2 M1-T3 0 3 1 M1-T6 2 0 M2-T15 1\* 0 M2-T19 0 0

Fig. 10: Mean velocity  $[m.s^{-1}]$  as a function of the burst length [mm] for the dynamic phases of all conducted experiments. The chronological order of the different dynamic burst for each individual test is given by the numbers next to the data points. Red colored numbers indicate the appearance of at least one rest-band during this particular dynamic burst, while the error bars give the variation (std) of the velocities for each dynamic phase.

Table 4: Amount of rest band appearances during the dynamic bursts. (\*) means specific roughening of the surface observed, which implies the early formation of a rest band that is yet not fully evolved. However, biased velocity measurements still have to be expected.



Fig. 11: Velocity [m.s<sup>-1</sup>] as a function of the normalized crack length [mm] for all conducted experiments.

The most striking observation is the regime and phenomenon-dependent fracture 444 surface pattern: quasi-static and dynamic fracture processes produce wave-like and flat 445 surface patterns, respectively. Macroscopically, the two entirely different mechanisms 446 therefore produce different fracture surfaces. Differences in fracture surface with re-447 spect to the experiments coming from the two campaigns are found in height of the 448 wave-like ligaments and the curvature of the crack fronts. Crack front curvatures arise 449 by focusing on the transitions between the two phases. Furthermore, the particular 450 roughening of the fracture surface between 8 to 10 mm in M2-T15 (12(b)) is indicating 451 the partial formation of a rest band, which has been discussed before. Other particular 452 observations are the specific rough pattern appearing during transition from dynamic 453 to quasi-static with Wallner lines (Wallner, H., 1939; Bonamy and Ravi-Chandar, 2003) 454 (Detail 3 in Figure 9) and the occurrence of conical marks related to micro-crack for-455 mations ahead of the main crack during the quasi-static to dynamic transition phases 456 (Detail 1 in Figure 9) (Ravi-Chandar and Balzano, 1988). These conical surface marks 457 are only found in the really beginning of the dynamic bursts suggesting, from (Guerra 458 et al., 2012), crack speeds above ~165 m.s<sup>-1</sup>. Highest velocities can thereby be expected 459 in the beginning of dynamic bursts.  $K_I$  and velocity measurements underline this de-460 pendency. With severe differences (around two orders of magnitude) in velocities sep-461 arating the two types of crack propagation,  $K_I$  is globally showing a decrease as the 462 crack propagates dynamically and a recovering increase as it rests during the quasi-463 static phases. As longer lasting quasi-static propagations are present (see Figure 12(b)), 464  $K_I$  and v find itself oscillating around a constant value. 465

Special interest is given in the following to the transition phase dynamic to quasi-466 static propagation related to the first quasi-static rest of the two experiments. During 467 the quasi-static rest of the M1-T2 experiment (Figure 12 (a)),  $K_I$  consists out of two 468 phases: Increasing from ~ 0.9 MPa $\sqrt{m}$  to ~ 1.2 MPa $\sqrt{m}$  (~ 27 mm to ~ 27.6 mm), while 469 stabilizing around ~ 1.2 MPa $\sqrt{m}$  (~ 27.6 mm to ~ 28.4 mm) before the occurrence of 470 the following dynamic burst. By relating these observations to the measured velocities, 471 one can notice a drop in crack tip speed when  $K_I$  has a sudden change and an over-472 all decrease of crack speed during this first phase. During the second stable  $K_I$  phase, 473 the velocity increasingly converges towards a stable crack tip speed before the sudden 474 jump into the dynamic region. Linking the observations to the fracture surface, the for-475 mation of triangular surface patterns (see Detail 3 in Figure 9 for zoomed view on an 476

example surface) seems to be related to the first phase, while the stable second phase 477 can be linked to the continuation of the newly formed wavy fracture pattern. Overall, 478 similar trends are found in the quasi-static rest obtained from the M2-T15 experiments 479 (Figure 12 (b)).  $K_I$  increases with decreasing crack speeds during the formation of the 480 triangular crack pattern, while both stabilize in the continuation of the wavy pattern. 481 In detail,  $K_I$  values increase during the first phase from ~ 1.1 MPa $\sqrt{m}$  to ~ 1.4 MPa $\sqrt{m}$ 482 (~16 mm to ~15 mm), while decreasing again until 22 mm to around ~1.3 MPa $\sqrt{m}$  with 483 stronger oscillations. However, until ~ 22.5 mm, a sudden increase back to 1.4 MPa $\sqrt{m}$ 484 is observed, followed by a phase of continuity before the crack starts to propagate dy-485 namically again at  $\sim 23.7$  mm. 486

When focusing on the fracture surface at the beginning of the quasi-static phase, 487 both specimens show the particular roughening and the appearance of Wallner lines. 488 According to velocity measurements, this area seems to be the result of an intense decel-489 eration zone. Here, a variable e is used to depict the distance of the end of this particular 490 rough pattern and the first appearance of a Wallner line. A relationship of this distance 491 e (Figure 13(b)) with the mean crack tip speed of the preceding dynamic phase is estab-492 lished in Figure 13(a) for the quasi-static rests of all conducted experiments. Red color 493 numbers again indicate the presence of rest bands falsifying the velocity measurement 494 of this particular dynamic burst. Hence, if dynamic bursts with rest band occurrences 495 are neglected, a trend with a growing relationship of dynamic velocity and distance e 496 can be suggested. While first Wallner lines seem to appear after  $193\pm78 \ \mu m$  for mean 497 dynamic crack speeds of  $85\pm5$  m.s<sup>-1</sup>, they first appear after  $490\pm125$   $\mu$ m for mean crack 498 tip speeds above 100 m.s<sup>-1</sup>. It seems to show that depending on the velocity, a critical 499 distance is required (with almost linear trend) to reach quasi-static propagations. 500

#### 501 4.3 Energy release rate

Energy release rates have been computed from  $K_I$  to reproduce the kinetic law of ma-502 terials showing alternate cracking (Section 2.1). Again, a detailed presentation of the 503 hysteresis will only be presented for two tests (here, M1-T2 and M2-T19). For clearer 504 visualization, only the crack propagation phases directly associated with the alternate 505 cracking are presented. This means, only the phases surrounded by dynamic bursts are 506 taken into consideration with the hysteresis always starting with the first dynamic burst. In each of the two sub figures, presented in Figure 14, two related graphs are found: the 508 temporal evolution of the crack length (a(t)) and the energy release rate as a function of 509 the crack tip speed (G(v)). Each individual phase of cracking is colored concordant over 510 the two plots. Also, triangular and square markers indicate the beginning or the end of 511 a phase, respectively. 512

Let us first look at test M1-T2 (Figure 14(a)). The hysteretic behavior of the frac-513 turing is here introduced by a first dynamic burst (light blue) following the theoretical 514 corner points C to D. During this propagation phase, the energy release rate drops from 515  $\sim$ 520 J.m<sup>-2</sup> to  $\sim$ 195 J.m<sup>-2</sup>, while the crack speed undergoes an increasing, stabilizing 516 and decreasing phase with velocities around 85 m.s<sup>-1</sup>, 120 m.s<sup>-1</sup> and 70 m.s<sup>-1</sup>, respec-517 tively. Subsequently, no data points are acquired until the first points in the quasi-static 518 region, indicating the first jump between the two accessible regions. By arriving at the 519 first quasi-static propagation phase (dark blue), G rises from  $\sim 240 \text{ J.m}^{-2}$  to  $\sim 375 \text{ J.m}^{-2}$ , 520 while the crack speed continues to decrease from 5 cm.s<sup>-1</sup> to 3 cm.s<sup>-1</sup>. After this, while 521 G continues to grow (~375 J.m<sup>-2</sup> to ~420 J.m<sup>-2</sup>), v finds itself increasing from the low 522



Fig. 12: Velocity  $[m.s^{-1}]$  and  $K_I$  [MPa $\sqrt{m}$ ] as a function of crack length [mm] in face with the microscopic image of the fracture surface for the experiments: (a) M1-T2 and (b) M2-T15. A spatial matching error between DIC and microscope measurements of ~160  $\mu$ m and ~140  $\mu$ m has to be considered for M1-T2 and M2-T15, respectively.



Fig. 13: (a) Mean velocity during dynamic crack propagation  $[m.s^{-1}]$  as a function of e-length (i.e. distance from dynamic micro roughening to Wallner lines)  $[\mu m]$  of the subsequent DYN to QS transition phase for all experiments. Error bars present the measurements on the two free edges of the fracture surface over the sample thickness. The chronological order of the different dynamic burst for each individual test is given by the numbers next to the data. Red colored numbers indicate the appearance of at least one rest-band during this particular dynamic burst. (b) Example of the measured distance e on the fracture surface.

point to around 15 cm.s<sup>-1</sup>. With G decreasing after reaching its peak value (~420 J.m<sup>-2</sup>), 523 the crack continues to accelerate to 23 cm.s<sup>-1</sup> before jumping back to the dynamic re-524 gion. Globally, this repeats itself until full crack arrest. However, the last two dynamic 525 branches (orange and light red) have to be taken with caution since the measurements 526 are influenced by the presence of rest bands. Furthermore, the seemingly separation 527 of the last quasi-static phase (dark red) into two arms can be explained by the post-528 treatment done on the crack length to remove post-dynamic oscillation leading to zero 529 velocities for a short duration. Additionally, it is worthwhile mentioning that the value of 530 critical fracture energy (G), introducing the 'forbidden' region II, is  $430\pm30$  J.m<sup>-2</sup> for all 531 quasi-static phases. Test M2-T19 (Figure 14(b)) generally follows this description with 532 the difference of a long quasi-static rest resulting in more data points and stronger ve-533 locity oscillations during this phase. 534

To conclude the results of this study, all experimental data (excluding phases with 535 biased velocity measurements) is presented in the same (v,G) space (Figure 15). Ad-536 ditionally, an entirely quasi-static experiment, that has been subjected to an extension 537 rate (0.07 mm.s<sup>-1</sup>) close to the threshold of the observed appearance of alternate crack-538 ing, was added. To place the experimental results into the context of the literature, ex-539 perimental data points from (Vincent-Dospital et al., 2020) and (Scheibert et al., 2010) 540 (quantitatively extracted using online software (Rohatgi, 2022)) were furthermore in-541 cluded. While our entirely quasi-static experiment seems to align well with the quasi-542 static experiments conducted in (Vincent-Dospital et al., 2020), alternate cracking re-543 sults do seem to add the missing experimental data to adequately cover the transition 544 between quasi-static and dynamic crack propagation in the full spectrum of PMMA 545 fracturing. Starting with the dynamic branch, experimental data points found in this 546 study fit well the trend of existing literature. However, the last value of G (before jump-547 ing to the quasi-static phase) is systematically found below any G value of the quasi-548

static regime, and therefore below the expected value of  $G_c$ . In detail, velocity mea-549 surements and energy release rates introducing the jump from dynamic to quasi-static 550 propagation are found to be 236±40 J.m<sup>-2</sup> and 67±31 m.s<sup>-1</sup>, respectively. During quasi-551 static phases, with velocities reaching a function of the macroscopic loading rate after 552 the decelerating phase, the crack grows at almost constant speed. Observed variations 553 during quasi-static propagation can be explained partly by physical and partly by post-554 dynamic effects. Avalanche values for energy release rate and velocity marking the be-555 ginning of the 'forbidden' region II are found to be 497±92 J.m<sup>-2</sup> and 0.19±0.15 m.s<sup>-1</sup>, 556 respectively. Taking both sides into consideration, region II, i.e. 'forbidden' velocity 557 regime, is thereby found to be more narrow than presented in literature. Nevertheless, a 558 brutal switch is seen from the rate dependent dynamic branch to the quasi-static regime 550 with only, as transition, the deceleration distance e. 560

General variations in the energy release rate are found to be in line with the liter-561 ature. In the quasi-static regime, the material strength increases with increasing strain rates due to the viscosity of PMMA. The resulting increase of G in the quasi-static regime is supported by the experimental data of Vincent-Dospital et al. (Vincent-Dospital et al., 56 2020). The increase in the energy release rate in the dynamic regime can be explained 565 by the increase of the process zone around the crack tip, which is in line with Kanni-566 nen's theory (Kanninen and Popelar, 1985). However, differing energy release rates for 567 dynamic crack initiation and arrest – where the SIF at dynamic crack initiation  $K1D_{ini}$ 568 has been found to be higher than at dynamic crack arrest  $K 1 D_a$  – have also been dis-569 cussed in Grégoire et al. (Grégoire et al., 2009). Furthermore, influences on the fracture 570 surface of the variations of the dynamic crack propagation and the increase of surface 571 roughness due to the appearance of micro-cracking have also been discussed in the lit-572 erature (Ravi-Chandar and Balzano, 1988; Grégoire, 2008; Dalmas et al., 2013). This is 573 in line with the presented observations, where conical shapes on the fracture surface 574 (micro-cracking) are found at the beginning of the dynamic propagation (Figure 9, de-575 tail 1) with high levels of G. At the same time, they vanish as G decreases to the point of 576 dynamic crack propagation arrest. 577

#### 578 5 Conclusions and perspectives

For this study, alternate cracking in PMMA has been observed by high-speed imaging 579 and investigated with the help of DIC and post-mortem analysis. Quasi-static and dy-580 namic crack propagations linked to this specific fracture phenomenon have been in-581 vestigated by a compromised experimental setup. The setup however allowed for the 582 investigation of the two cracking types within one fracture process. Velocity and SIF 583 measurements obtained through DIC and Williams' series expansion have been tied 584 to microscopic images to highlight the regime-dependent behavior of alternate crack-585 ing. By doing so, it was possible to find relationships through the synchronization of 586 experimental devices. Main observations with potential perspectives can be summed 587 as following: 588

*Forbidden' velocity regime*. The in literature described 'forbidden' velocity regime was not approached from two sides, but studied through holistic alternate cracking experiments with high-speed imaging. Here, the 'forbidden' regime has been identified by quasi-static and dynamic velocity threshold measurements of ~36 cm.s<sup>-1</sup> and ~ 36 m.s<sup>-1</sup>, respectively. Notice that the limit values stem from the lowest/highest measured velocity of all observed phases.



Fig. 14: Energy release rate (*G*)  $[J.m^{-2}]$  as a function of velocity (v)  $[m.s^{-1}]$  for the alternate cracking phases with its corresponding temporal evolution of the crack for: (a) M1-T2 and (b) M2-T19. Reference to the phases of the theoretical kinematic law (see Figure 1) are added for better comprehension.



Fig. 15: Energy release rate (*G*)  $[J.m^{-2}]$  as a function of velocity (v)  $[m.s^{-1}]$  for the alternate cracking and one entirely quasi-static experiment.

*Relationship of mean dynamic velocity with burst length.* Dynamic crack speeds and
 their burst lengths have been registered and used to establish a relationship. By do-

ing so, it was shown that higher velocities result in longer dynamic bursts.

Observation of rest bands. In line with the previous point, probably for dynamic propagation phases containing lower levels of energy, dynamic bursts show an intermittent behavior with extremely small rest bands. An average velocity threshold for the potential occurrence of rest bands has been identified at ~60 m.s<sup>-1</sup>.

Perspective: Higher temporal sampling would allow for the identification of rest
 band decelerations influencing the average dynamic velocity measurements and

thereby the exploration of the intermittent behavior of dynamic bursts itself.

- Deceleration phase occurring during transition of dynamic to quasi-static propagation. The influence of dynamically propagating cracks arriving at quasi-static phase on the fracture surface led to the definition of a critical deceleration distance between the two phases. Here, an almost linear trend is found between mean crack tip speeds of the dynamic burst and the specific deceleration distance. It is found between 115 and 615  $\mu$ m for mean velocities ranging from 78 to 106 m.s<sup>-1</sup>. It points to the fact that the crack tip undergoes a deceleration of about 10<sup>7</sup> m.s<sup>-2</sup>.

Perspective: The observed extreme accelerations/decelerations potentially induce elastic waves that could be measured with Acoustic Emission (AE) devices. In that context, recent developments in Ultra High Speed (UHS) imaging techniques (temporal resolutions in the order of Mfps (Vinel et al., 2021)) would allow for a detailed investigation of the acceleration/deceleration phases and help visualizing crack induced waves propagation.

Particular surface markings. Two particular PMMA-related fracture surface patterns, Wallner lines and nucleation phases, have been observed. The second one, only appearing at the beginning of the dynamic bursts, suggests crack speed phases beyond the velocities measured during the experiments. This can be explained by the limits of the chosen interframe.

Perspective: Again, by stretching the limits of the interframe and reaching higher
 samplings during dynamic propagation, velocity variations could be explored. Sur face markings of the nucleation phase, suggesting highest crack tip speeds in the
 beginning of dynamic bursts, could thereby be confirmed.

Improved sampling of the kinematic law of PMMA fracturing in vicinity of instabil-627 ity. Kinematic law for fracturing in PMMA was established by supplementing the 628 results of this work with experimental data from existing literature. Here, experi-629 mental data of the interaction of reoccurring dynamic and quasi-static phases dur-630 ing alternate cracking experiments was provided. For the first time, direct velocity 631 and SIF measurements have been experimentally identified for both phases dur-632 ing the same alternate cracking experiments. Results led to a proposed adjustment 633 of the classical description of alternate cracking regarding the transition from dy-634 namic to quasi-static propagation (path along reference points B-C-D-A' in Figure 635 2.1). On one hand, in view of the chosen extension rates to induce alternate recur-636 rence of the transitions, different mechanisms could have been activated. On the 637 other hand, the transition of dynamic to quasi-static propagation with extreme de-638 celerations (potentially being outside of the framework of (Vincent-Dospital et al., 639 2020)) is not smooth after all. In addition, the path that the crack follows to revert to 640 the master curve in the quasi-static regime differs from the observations in (Vasude-641 van, 2018). However, in his work, very slow extension rates have been used resulting 642 in quasi-static experiments initiated by a dynamic crack. No alternate recurrence of the two propagation types was observed. Regarding quasi-static to dynamic transitions, even with a temporal resolution of 40 kfps, it was not possible to experimen-645 tally explore the smooth transition during the 'softening' branch predicted by the 646 thermodynamic model of (Vincent-Dospital et al., 2020). This, however, could po-647 tentially be explained by a lack of temporal resolution or the feasibility to explore 648 this regime due to the way the experiments were conducted. To do so, an experi-649 mental configuration enabling decreasing  $K_I$  values with increasing crack velocities 650 is needed. 651

*Perspective:* An experimental configuration containing UHS imaging techniques would allow for the investigation of separate dynamic propagation phases during

- alternate cracking. Consequently, better descriptions of the transition phases could 654
- be reached, potentially leading to an exploration of the predicted smooth transition, 655
- i.e. the 'softening' regime. 656

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#### **Declarations** 660

- Conflict of interest: 661
- The authors declare that they have no conflict of interest. 662

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