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# Deciding contextual equivalence of $v$-calculus with effectful contexts 

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#### Abstract

We prove decidability for contextual equivalence of the $\lambda \mu \nu$ calculus, that is the simply-typed call-by-value $\lambda \mu$-calculus equipped with booleans and fresh name creation, with contexts taken in $\lambda \mu_{\text {ref }}$, that is $\lambda \mu \nu$-calculus extended with higher-order references. The proof exploits a labelled transition system capturing the interactions between $\lambda \mu \nu$ programs and $\lambda \mu_{\text {ref }}$ contexts. The induced bisimulation equivalence is characterized as equality of certain trees, inspired by the work of Lassen. Since these trees are computable and finite, decidability follows. Bisimulation coincides also with trace equivalence, which in turn coincides with contextual equivalence.


## 1 Introduction

Dynamic allocation is central to many of programming constructions. Many languages provide built-in support for dynamically-allocated resources, for example, objects in Java or references in ML. The creation of these resources is local, meaning that they can be accessed only within their scope. They can also be passed around via function applications, meaning that their scope is not static but evolves dynamically. While building semantics for such languages, one represents dynamic allocation as the creation of fresh locations, that can be seen as atoms or names.

In this paper, we study a paradigmatic language with dynamic allocation, namely the $v$-calculus, a simply-typed call-by-value $\lambda$-calculus with fresh atom creation and equality test of atoms, as introduced by Pitts and Stark in [27]. For instance, the $v$-calculus program new $n$ in $\lambda x \cdot(x=n)$ allocates a new atom $n$, receives an atom $x$ and returns the result of the comparison between $x$ and $n$.

A central question while studying this language is to determine when two programs can be considered to be equivalent. The most studied approach to express behavioral equivalence between programs is contextual equivalence. Intuitively, two programs are deemed equivalent if and only if whenever they are run as part of an enclosing program called the context, it is not possible to distinguish one from the other. For instance, because the context has no way to guess the atom $n$, we expect the program above to be equivalent to $\lambda x$.false.

Reasoning on contextual equivalence for the $v$-calculus has shown to be challenging, due to the interplay between the higher-order control flow and the scope
extrusion of atoms. A variety of frameworks has been introduced to do so, based on logical relations [27], environmental bisimulations [6], and game semantics [1].

However, the question of whether this equivalence is decidable remains open since the introduction of this language 30 years ago.

In this paper, we address this question by working in an asymmetric setting, giving contexts more discriminating power than just the mere creation of atoms. Indeed, contextual equivalence depends on two languages: the language for programs, and the language for contexts interacting with these programs. We take contexts in the $\lambda \mu_{\text {ref }}$-calculus, an extension of the $v$-calculus with both higherorder references and continuations. In this setting, atoms are simply references where only the unit value can be stored. Contextual equivalence is then coarser than for the symmetric setting when the contexts are also taken in the $v$-calculus. For example, one of the standard examples of equivalence of the literature,

$$
\text { new } n \text { in new } n^{\prime} \text { in } \lambda f .\left(f n=f n^{\prime}\right) \simeq_{c t x} \lambda f . \text { true }
$$

is not an equivalence anymore, since a $\lambda \mu_{\text {ref }}$ context can provide a function that stores its argument in a reference and use it to discriminate these programs.

The main result we establish in this paper is the decidability of contextual equivalence for terms of $v$-calculus with contexts in the $\lambda \mu_{\text {ref }}$-calculus. More generally, we establish this result for terms of the $\lambda \mu \nu$-calculus, which corresponds to terms of the $\lambda \mu_{\text {ref }}$-calculus that only uses references storing the unit value.

To establish this result, we provide a Böhm-like tree representation [7, 4] for the terms of the $\lambda \mu \nu$-calculus. Being in call-by-value, equality of such trees coincides with Lassen's eager normal form bisimulations [17]. Moreover, since programs in the $\lambda \mu \nu$-calculus are terminating, these trees, which we call Lassen trees, are finite. It is thus straightforward to check their equality. Then, we prove that Lassen trees equality is fully-abstract, that is it coincides with contextual equivalence with contexts in the $\lambda \mu_{\text {ref }}$-calculus.

Proving this full-abstraction result is done through the introduction of an operational game semantics (OGS) for $\lambda \mu_{\text {ref }}$ by defining an Labelled Transition System (LTS) that distinguishes between internal operations, Proponent moves (originating in the program) and Opponent moves (originating in the context). Trace equivalence based on these labelled transitions is shown to coincide with the contextual equivalence of $\lambda \mu_{\text {ref }}$.

The OGS also gives rise to a notion of bipartite bisimulation, describing a game between Proponent (the program in $\lambda \mu_{\text {ref }}$ ) and Opponent (a context in $\left.\lambda \mu_{\text {ref }}\right)$. Proponent reduces the program until it reaches a normal form, that triggers an interaction with the context. Along the game, knowledge is accumulated in configurations. When it is Opponent's turn to play, it chooses between answering a previous function call from Proponent, or generating a new function call, to which Proponent shall answer. Among this knowledge, we accumulate the atoms that have been disclosed by the two players, so that Opponent cannot use an atom private to Proponent.

The OGS LTS generates infinite trees since Opponent can interrogate an arbitrary number of times each value provided by Proponent. The Lassen trees
used to decide contextual equivalence are generated using a linearized variant of the OGS LTS, called the Prime Operational Game Semantics (POGS) LTS. This LTS enforces that Opponent interrogates only once each value provided by Proponent. For this linearization to be sound, one has to guess the disclosed status of atoms as soon as they are created. Indeed, looking at the following example of inequivalence

$$
\text { new } n \text { in } \lambda x . n \not \not_{c t x} \lambda x \text {. new } n \text { in } n
$$

Opponent must be able to interrogate at least twice each of these two programs to discriminate them. The first program would then return the same atom at each call, while the second program would return two different atoms. The Lassen tree of the first program would declare $n$ to be disclosed when giving back the control to Opponent by providing the $\lambda$-abstraction, but this could not be matched by the second program, since $n$ would not exist yet at that point of the interaction.

The main technical challenge at this point is to prove that this forecasting of the disclosure process is sound and complete. This is done by proving that the bipartite bisimilarities defined over the OGS LTS and the POGS LTS coincide. One direction is proven by lifting POGS bisimulations into OGS bisimulation via an up-to technique. The other direction is done by introducing a new limit construction of the disclosed set of atoms appearing in the OGS bisimulations, to transform it into a POGS bisimulation.

Paper outline. After introducing the $\lambda \mu_{\text {ref }}$-calculus and the $\lambda \mu \nu$-calculus in Section 2, we define the LTS for the OGS in Section 3. The induced trace equivalence coincides with contextual equivalence. We then move to Lassen trees in Section 4, and show that they yield an equivalence that coincides with bipartite bisimilarity in the OGS in Section 5. We present concluding remarks in Section 7. For lack of space, several technical developments are given in Appendix.

## 2 The $\lambda \mu_{\text {ref }}$-calculus and the $\lambda \mu \nu$-calculus

The syntax of the $\lambda \mu_{\text {ref }}$-calculus is given by the following grammar:

$$
\begin{array}{ll}
\text { Values } & \mathrm{V}, \mathrm{~W} \triangleq x|()| \lambda x . \mathrm{M} \mid \text { true } \mid \text { false } \mid \ell \\
\text { Terms } & \mathrm{M}, \mathrm{~N} \triangleq \mathrm{~V} \mid \text { let } x=\mathrm{M} \text { in } \mathrm{N}|\mathrm{VW}| \text { if } \mathrm{V} \text { then } \mathrm{N}_{1} \text { else } \mathrm{N}_{2} \\
& |\mathrm{~V}=\mathrm{W}| \text { new } x=\mathrm{V} \text { in } \mathrm{M}|\mathrm{~V}:=\mathrm{W}|!\mathrm{V}|\mu \mathrm{c} . \mathrm{M}|[\mathrm{c}] \mathrm{M} \\
\text { Eval. Contexts } \mathrm{E}, \mathrm{E}^{\prime} \triangleq[\mathrm{c}] \bullet \mid \mathrm{E}[\text { let } x=\bullet \text { in } \mathrm{M}] \\
\text { Contexts } & \mathrm{C}, \mathrm{C}^{\prime} \triangleq \bullet|[\mathrm{c}] \mathrm{C}| \text { let } x=\mathrm{C} \text { in } \mathrm{M} \mid \text { let } x=\mathrm{M} \text { in } \mathrm{C}|\lambda x . \mathrm{C}| \mu \mathrm{c} . \mathrm{C} \\
& \quad \mid \text { if } \mathrm{V} \text { then } \mathrm{C} \text { else } \mathrm{M} \mid \text { if } \mathrm{V} \text { then } \mathrm{M} \text { else } \mathrm{C} \mid \text { new } x=\mathrm{V} \text { in } \mathrm{C} \\
\text { Types } & \sigma, \tau \triangleq \text { Unit } \mid \text { Bool }|\sigma \rightarrow \tau| \operatorname{ref}_{\sigma} \mid \perp
\end{array}
$$

with $x \in$ Vars (variables), $c \in$ Covars (continution variables), $\ell \in$ Locs (locations). We write $\operatorname{supp}(M)$ for the set of locations appearing in M, and $\mathbf{F V}(M)$ for the free variables of M. This language has two binders, the standard $\lambda$-abstraction, and the $\mu$ binder for continuation variables c, $d$ [25].


Fig. 1. $\lambda \mu_{\text {ref }}$ : typing rules for terms and evaluation contexts

A store, ranged over by $S, T$, is a finite mapping from locations to values. $S(\ell)$ stands for the value associated to $\ell$ in S . We use notation $\mathrm{S} \cdot[\ell \mapsto \mathrm{V}]$ for the extension of S with a mapping for $\ell$, which is only defined if $\ell$ is not defined in $\mathrm{S} . \mathrm{S}[\ell \mapsto \mathrm{V}]$ denotes the store S in which the value associated to $\ell$ is updated.

The operational semantics $\mapsto_{\mathrm{op}}$ of the $\lambda \mu_{\text {ref }}$-calculus is defined over configurations, which are pairs ( $\mathrm{M}, \mathrm{S}$ ) formed by a term and a store. It is given by the following rules:

| (E[( $\lambda x . \mathrm{M}) \mathrm{V}], \mathrm{S})$ | $\mapsto_{\text {op }}(\mathrm{E}[\mathrm{M}\{x:=\mathrm{V}\}], \mathrm{S})$ |
| :---: | :---: |
| (E[let $x=\mathrm{V}$ in M], S) | $\mapsto_{\mathrm{op}}(\mathrm{E}[\mathrm{M}\{x:=\mathrm{V}\}], \mathrm{S})$ |
| (E[if true then $\mathrm{N}_{1}$ else $\mathrm{N}_{2}$ ], S) | $\mapsto_{\mathrm{op}}\left(\mathrm{E}\left[\mathrm{N}_{1}\right], \mathrm{S}\right)$ |
| (E[if false then $\mathrm{N}_{1}$ else $\mathrm{N}_{2}$ ], S) | $\mapsto_{\text {op }}\left(\mathrm{E}\left[\mathrm{N}_{2}\right], \mathrm{S}\right)$ |
| (E[new $x=\mathrm{V}$ in M$], \mathrm{S}$ ) | $\mapsto_{\mathrm{op}}(\mathrm{E}[\mathrm{M}\{x:=\ell\}], \mathrm{S} \cdot[\ell \mapsto \mathrm{V}])$ |
| ( $\mathrm{E}[\ell:=\mathrm{V}], \mathrm{S}$ ) | $\mapsto_{\mathrm{op}}(\mathrm{E}[()], \mathrm{S}[\ell \mapsto \mathrm{V}])$ |
| (E[! $\ell, \mathrm{S}$ ) | $\mapsto_{\mathrm{op}}(\mathrm{E}[\mathrm{S}(\ell)], \mathrm{S})$ |
| (E[ $\ell=\ell], S$ ) | $\mapsto_{\text {op }}(\mathrm{E}[$ true $], \mathrm{S})$ |
| ( $\left.\mathrm{E}\left[\ell=\ell^{\prime}\right], \mathrm{S}\right)$ | $\mapsto_{\text {op }}(\mathrm{E}[\mathrm{false}$ ], S$)$ |
| (E[ $\mu \mathrm{c} . \mathrm{M}], \mathrm{S})$ | $\mapsto_{\text {op }}(\mathrm{M}\{\mathrm{c}:=\mathrm{E}\})$ |

The typing system for terms is given by the rules in Figure 1. We chose here a typing judgement with a single typing context $\Gamma$, so that continuation variables are given types of the shape $\neg \sigma$. Such negated types are also used to type evaluation contexts, as given by the two last rules in Figure 1. While we cannot store continuation variable c in a reference, we can always store its
associated function $\lambda x$.[c] $x$. Typing rules force terms of type $\perp$ to be of the shape [d]M, following Parigot's original presentation of the $\lambda \mu$-calculus [25].

We also consider a typing judgement of the shape $\Sigma \vdash \mathrm{C}:(\Gamma ; \sigma) \leadsto(\Delta ; \tau)$, for contexts C that take terms M of type $\Sigma ; \Gamma \vdash \mathrm{M}: \sigma$ and produce terms of type $\Sigma ; \Delta \vdash \mathrm{C}[\mathrm{M}]: \tau$. The typing rules defining this judgement are standard and not recalled here.

In the following, we consider the $\lambda \mu \nu$-calculus, the fragment of the $\lambda \mu_{\mathrm{ref}}-$ calculus that only handles references of type $\mathbf{r e f}_{\text {Unit }}$. That is, for all the reference type $\operatorname{ref}_{\sigma}$ appearing in the typing derivation, we have $\sigma=$ Unit.

We use $\mathrm{a}, \mathrm{b}, \ldots$ to range over locations of type $\mathbf{r e f}_{\text {Unit }}$, also called atoms, and introduce the slightly shorter notation new $n$ in M to stand for new $n=()$ in M in $\lambda \mu \nu$. The syntax for values and terms of the $\lambda \mu \nu$-calculus is thus:

```
Values V,W\triangleq 
Terms M, N \triangleq V | let x= M in N|VW| if V then N N else N N | V = W | new n in M
    | |c.M
```

In this setting, we see stores $S$ directly as sets of atoms, all mapping to the unit value (). For L a set of atoms. we write $\widehat{\mathrm{L}}$ for the store that maps atoms in L to the unit value ().

We consider the following extension of the typing judgement respectively to stores S , value-mapping substitutions $\gamma$, and evaluation contexts:

$$
\begin{array}{ll}
\frac{\forall \ell \in \operatorname{dom}(\mathrm{S}), \Sigma ; \varnothing \vdash \mathrm{S}(\ell): \Sigma(\ell)}{} & \operatorname{dom}(\mathrm{S})=\operatorname{dom}(\Sigma) \\
\vdash \mathrm{S}: \Sigma & \\
\frac{\forall x \in \operatorname{dom}(\Gamma), \Sigma ; \Delta \vdash \gamma(x): \Gamma(x)}{} & \operatorname{dom}(\gamma)=\operatorname{dom}(\Gamma) \\
\Sigma ; \Delta \vdash \gamma: \Gamma
\end{array}
$$

Definition 1. A normal form ( $\mathrm{M}, \mathrm{S}$ ) is a configuration that is irreducible for the reduction relation $\mapsto_{\mathrm{op}}$. We write $(\mathrm{M}, \mathrm{S}) \Downarrow \mathrm{N}$ when there exists a store T such that $(\mathrm{M} ; \mathrm{S}) \mapsto_{\mathrm{op}}^{*}(\mathrm{~N} ; \mathrm{T})$ and that $(\mathrm{N} ; \mathrm{T})$ is a normal form.

We call the types Bool, Unit and ref $_{\sigma}$ positive types, while $\sigma \rightarrow \tau$ and $\neg \sigma$ are called negative types. By only allowing free variables of negative types, we provide a sharp characterization of normal forms.
Theorem 2. Taking a term M such that $\Sigma ; \Gamma \vdash \mathrm{M}: \perp$ with $\Gamma$ a typing context mapping variables to negative types, if $(\mathrm{M}, \mathrm{S})$ is in normal form with respect to $\mapsto_{\mathrm{op}}$, then M is either a named value $[\mathrm{c}] \mathrm{V}$ or a neutral term $\mathrm{E}[x \mathrm{~V}]$.

Moreover, for any configuration ( $\mathrm{M}, \mathrm{S}$ ) such that M is in $\lambda \mu \nu, \Sigma ; \Gamma \vdash \mathrm{M}: \perp$ and $\vdash \mathrm{S}: \Sigma$, there exists N such that $(\mathrm{M}, \mathrm{S}) \Downarrow \mathrm{N}$.

Definition 3. Taking two terms $\mathrm{M}, \mathrm{N}$ such that $\Sigma ; \Gamma \vdash \mathrm{M}: \sigma$ and $\Sigma ; \Gamma \vdash \mathrm{N}: \sigma$, we say that they are contextually equivalent, written $\Sigma ; \Gamma \vdash \mathrm{M} \simeq_{c t x} \mathrm{~N}: \sigma$, when for all continuation variable c and context C such that $\Sigma \vdash \mathrm{C}:(\Gamma ; \sigma) \leadsto(\mathrm{c}: \neg$ Unit $; \perp$ ), and for all store S such that $\stackrel{\mathrm{S}}{ }: \Sigma^{\prime}$, we have $(\mathrm{C}[\mathrm{M}], \mathrm{S}) \Downarrow[\mathrm{c}]()$ if and only if $(\mathrm{C}[\mathrm{N}], \mathrm{S}) \Downarrow[\mathrm{c}]()$.

In the definition above, we use $\lambda \mu_{\text {ref }}$ contexts to observe $\lambda \mu \nu$ terms. Such contexts can use higher-order references, and lead to divergent computations. For this reason, testing for convergence to () is enough when defining $\simeq_{c t x}$.

## 3 Operational Game Semantics

We now introduce a fully-abstract trace semantics for $\lambda \mu_{\text {ref }}$ programs. We follow a modular presentation, inspired by the one provided by Laird in [16], where the semantics is built from a synchronization product of three LTS:

- the Interactive $\operatorname{LTS} \mathcal{L}_{1}$, that represents the raw interactions of programs with their environment.
- the Typing LTS $\mathcal{L}_{\mathrm{Ty}}$, that keeps track of the polarization and types of names exchanged, to preserve well-typedness.
- the Disclosing LTS $\mathcal{L}_{\mathrm{Di}}$, that prevents the environment to use private resources that have not been disclosed by Proponent.


### 3.1 Abstract values

To represent the interaction between the program and its environment, we distinguish between values that we can observe and values that we can interact with. The two players only exchange observable values, called abstract values in this paper. They are defined by the following grammar:

$$
\mathrm{A}, \mathrm{~B} \triangleq \mathrm{f}|\mathrm{a}| \text { true } \mid \text { false } \mid()
$$

with f a function name, that is a variables used to represent functions exchanged between the two players. They correspond to the positive part of values, and are also called ultimate patterns in [18]. Like for terms, supp(A) stands for the set of atoms occurring in A . We consider the typing judgement $\Delta \Vdash \mathrm{A}: \sigma$ for abstract values, with $\sigma$ a positive type, that is defined similarly than for terms, with the extra condition that all variables appearing in A are distinct.

Then we introduce the abstraction relation $\mathbb{Z}$ that transforms a value V into a pair $(\mathrm{A}, \gamma)$ formed by an abstract value and a substitution, such that $\mathrm{A}\{\gamma\}=\mathrm{V}$ :

$$
\frac{\mathrm{f}, \mathrm{~g} \text { function names }}{\mathrm{f} \not \mathbb{Z}(\mathrm{~g},[\mathrm{~g} \mapsto \mathrm{f}])} \quad \frac{\mathrm{b} \in\{\text { true, false }\}}{() \not \mathbb{Z}((), \varepsilon)} \quad \frac{\mathrm{a} \text { an atom }}{\mathrm{b} \not / \mathbb{}(\mathrm{b}, \varepsilon)} \quad \mathrm{a}(\mathrm{a}, \varepsilon)
$$

$$
\lambda x . \mathrm{M} \not /(\mathrm{f},[\mathrm{f} \mapsto \lambda x . \mathrm{M}])
$$

### 3.2 Labelled Transition Systems

The two players, Opponent and Proponent, exchange moves, which are in one of six forms:

| P-question | P-answer | O-question | O-answer | P-init question | O-init question |
| :--- | :--- | :--- | :--- | :--- | :--- |
| $\overline{\mathrm{f}}(\mathrm{A}, \mathrm{c})$ | $\overline{\mathrm{c}}(\mathrm{A})$ | $\mathrm{f}(\mathrm{A}, \mathrm{c})$ | $\mathrm{c}(\mathrm{A})$ | $\vec{?}\left(\overrightarrow{\mathrm{~A}_{i}}\right)$ | $?\left(\overrightarrow{\mathrm{~A}_{i}}\right)$ |

We use $\mathbf{m}$ to range over moves, and $\mathbf{p}$ (resp. o) to range over Proponent (resp. Opponent) moves. Initial questions are the introductory moves. Compared to other moves, they can introduce multiple abstract values in a row, which is used to instantiate all the variables of a typing context $\Gamma$. They use a distinguished function name?

Traces $\mathbf{t}$ are sequences of moves. We write $\overline{\mathbf{m}}$ for the corresponding move with reversed polarity (input switched to output, and vice-versa). We extend this definition to switch traces, written $\overline{\mathbf{t}}$.

The three labelled transition systems we define are instances of the following definition:

Definition 4. A labelled transition system (LTS) $\mathcal{L}$ is a triple (Confs, Actions, $\rightarrow$ ) with Confs a set of configurations $\mathbb{C}, \mathbb{D}$, Actions a set of actions a, formed by the moves $\mathbf{m}$, together with a silent action op, corresponding to internal computations, and $\rightarrow \subseteq$ Confs $\times$ Actions $\times$ Confs the labelled transition relation. We write $\mathbb{C} \xrightarrow{\mathbf{a}} \mathbb{D}$ for $(\mathbb{C}, \mathbf{a}, \mathbb{D}) \in \rightarrow$.

Taking $\mathbb{C}$ a configuration of an LTS $\mathcal{L}$, we write $\operatorname{Tr}_{\mathcal{L}}(\mathbb{C})$ for the set of traces, as sequences of moves generated by this LTS over $\mathbb{C}$ (so with op actions removed). We write $\mathbb{C} \simeq_{\operatorname{tr}} \mathbb{D}$ for the trace equivalence relation, which equates configurations $\mathbb{C}, \mathbb{D}$ when both have the same set of traces.

### 3.3 Interactive LTS

We consider interactive configurations $\mathbb{I} ; \mathbb{J} \in$ IConfs which are either passive of the shape $\langle\mathrm{S} ; \gamma\rangle$, or active of the shape $\langle\mathrm{M} ; \mathrm{S} ; \gamma\rangle$ with M a term, S a store, and $\gamma$ a substitution. The Interactive LTS $\mathcal{L}_{1}$ is then defined as the triple (IConfs, Actions, $\rightarrow_{\mathrm{I}}$ ) with $\rightarrow_{\mathrm{I}}$ defined in Figure 2.

The two rules for Proponent moves describe transitions performed by normal forms and make use of the abstraction relation. In the two rules for Opponent, the notation $S \odot[\overline{\operatorname{supp}(A)}]$ stands for $S$ extended with a binding a $\mapsto()$ in the case when $A=a$ and $a$ is fresh for Proponent, and simply $S$ otherwise: Proponent extends its store when a new atom is received.

### 3.4 Typing LTS

We consider type-context configurations $\mathbb{S}, \mathbb{T} \in \operatorname{Confs}_{T y}$ which are either active of the shape $\left\langle\Delta_{\mathrm{O}} \mid \perp_{;} \Delta_{\mathrm{P}}\right\rangle$ or passive of the shape $\left\langle\Delta_{\mathrm{O}} \mid \Delta_{\mathrm{P}}\right\rangle$ with $\Delta_{\mathrm{O}}, \Delta_{\mathrm{P}}$ two disjoint typing contexts that map variables to negative types.

The Interactive LTS $\mathcal{L}_{1}$ is then defined as the triple ( Confs $_{T y}$, Actions, $\rightarrow_{\mathrm{Ty}}$ ) with $\rightarrow_{\text {Ty }}$ defined in Figure 3. Notice that the type of the active term is $\perp$ since the reduction relation $\mapsto_{\mathrm{op}}$ is well defined only on terms of this type.

Typing configurations can be used to specify interactive configurations, via the following validity judgement.

Definition 5. An interactive configuration $\mathbb{I}$ is said to be validated by a typing configuration $\mathbb{S}$, written $\mathbb{I} \triangleright \mathbb{S}$, when:


Fig. 2. Definition of $\mathcal{L}_{1}$, the Interactive LTS: transitions of interactive configurations

$$
\begin{array}{cc}
\mathrm{PQ} \xrightarrow{\Delta_{\mathrm{O}}(\mathrm{f})=\sigma \rightarrow \tau} \begin{array}{cc}
\Delta \Delta_{\mathrm{O}}\left|\perp ; \Delta_{\mathrm{P}}\right\rangle \xrightarrow{\overline{\mathrm{f}}(\mathrm{~A}, \mathrm{c})} \mathrm{T}_{\mathrm{y}}\left\langle\Delta_{\mathrm{O}} \mid \Delta_{\mathrm{P}}, \Delta, \mathrm{c}: \neg \tau\right\rangle
\end{array} & \begin{array}{c}
\Delta_{\mathrm{O}}(\mathrm{c})=\neg \sigma \\
\left\langle\Delta_{\mathrm{O}} \mid \perp ; \Delta_{\mathrm{P}}\right\rangle \xrightarrow{\bar{c}(\mathrm{~A})} \mathrm{T}_{\mathrm{y}}\left\langle\Delta_{\mathrm{O}} \mid \Delta_{\mathrm{P}}, \Delta\right\rangle \\
\mathrm{OQ} \xrightarrow{\left\langle\Delta_{\mathrm{O}} \mid \Delta_{\mathrm{P}}\right\rangle \xrightarrow{f(\mathrm{~A}, \mathrm{c})} \mathrm{T}_{\mathrm{y}}\left\langle\Delta_{\mathrm{O}}, \Delta, \mathrm{c}: \neg \tau \mid \perp ; \Delta_{\mathrm{P}}\right\rangle} \mathrm{PA} \\
\end{array}
\end{array}
$$

Fig. 3. Definition of $\mathcal{L}_{\text {Ty }}$, the typing LTS: transitions of type-context configurations

- either $\mathbb{I}=\langle\mathrm{S} ; \gamma\rangle, \mathbb{S}=\left\langle\Delta_{\mathrm{O}} \mid \Delta_{\mathrm{P}}\right\rangle$, and there exists a store typing context $\Sigma$ such that $\Sigma ; \Delta_{\mathrm{O}} \vdash \gamma: \Delta_{\mathrm{P}}$ and $\vdash \mathrm{S}: \Sigma$.
- or $\mathbb{I}=\langle\mathrm{M} ; \mathrm{S} ; \gamma\rangle, \mathbb{S}=\left\langle\Delta_{\mathrm{O}} \mid \perp ; \Delta_{\mathrm{P}}\right\rangle$, and there exists a store typing context $\Sigma$ such that $\Sigma ; \Delta_{\mathrm{O}} \vdash \mathrm{M}: \perp, \Sigma ; \Delta_{\mathrm{O}} \vdash \gamma: \Delta_{\mathrm{P}}$ and $\vdash \mathrm{S}: \Sigma$.


### 3.5 Disclosing LTS

In order to enforce a non-omniscient condition on the Opponent transitions, we introduce a Disclosing LTS $\mathcal{L}_{\mathrm{Di}} \triangleq\left(\right.$ DConfs, Actions, $\left.\rightarrow_{\mathrm{Di}}\right)$ whose configurations DConfs are pairs of sets of locations $\langle\mathrm{L} ; \mathrm{D}\rangle$ with D a set of atoms contained in L , and the transition function $\rightarrow_{\mathrm{Di}}$ is defined in Figure 4. The condition L $\cap \operatorname{supp}(\mathbf{o}) \subseteq$ D corresponds to the fact that Opponent cannot play Proponent atoms that have not been disclosed yet, i.e. not in D.

Definition 6. An interactive configuration $\mathbb{I}$ is said to be validated by a disclosing configuration $\mathbb{D}=\langle\mathrm{L} ; \mathrm{D}\rangle$, written $\mathbb{I} \triangleright \mathbb{D}$, when writing S for the store component of $\mathbb{I}$, we have $\operatorname{dom}(\mathrm{S})=\mathrm{L}$.

### 3.6 Operational Game Semantics: LTS and Trace Equivalence

The Operational Game Semantics (OGS) LTS $\mathcal{L}_{\mathrm{OGS}} \triangleq\left(\right.$ Confs $_{\text {ogs }}$, Actions, $\left.\xrightarrow{\mathrm{a}}{ }_{\mathrm{ogs}}\right)$ is defined over configurations $\mathbb{G}, \mathbb{H} \in$ Confs $_{\text {ogs }}$ of the shape $(\mathbb{I}, \mathbb{S}, \mathbb{D})$, such that

$$
\begin{aligned}
& \mathrm{op} \overline{\langle\mathrm{~L} ; \mathrm{D}\rangle \xrightarrow{\text { op }} \mathrm{Di}\left\langle\mathrm{~L} \cup \mathrm{~L}^{\prime} ; \mathrm{D}\right\rangle} \\
& \left.\mathrm{PQ} / \mathrm{PA} \xlongequal\left[{\langle\mathrm{~L} ; \mathrm{D}\rangle \xrightarrow{\mathrm{p}}_{\mathrm{Di}}\langle\mathrm{~L} ; \mathrm{D} \cup \operatorname{supp}(\mathbf{p})}\right\rangle\right]{ } \frac{\mathrm{L} \cap \operatorname{supp}(\mathbf{o}) \subseteq \mathrm{D}}{\langle\mathrm{~L} ; \mathrm{D}\rangle \stackrel{\mathbf{o}}{\mathrm{Di}}^{\mathrm{Di}}\langle\mathrm{~L} \cup \operatorname{supp}(\mathbf{o}) ; \mathrm{D} \cup \operatorname{supp}(\mathbf{o})\rangle} \mathrm{OQ} / \mathrm{OA}
\end{aligned}
$$

Fig. 4. Definition of $\mathcal{L}_{\mathrm{Di}}$, the Disclosing LTS
$\mathbb{I} \triangleright \mathbb{S}$ and $\mathbb{I} \triangleright \mathbb{D}$, or of initial configurations $\langle\Sigma ; \Gamma \vdash \mathrm{M}: \sigma\rangle$ for Proponent and $\langle\mathrm{c}: \neg$ Unit $\vdash(\mathrm{S} ; \delta):(\Sigma ; \Gamma)\rangle$ for Opponent. Its transition relation is defined by the following rules:

$$
\begin{aligned}
& \frac{\Gamma=\overrightarrow{\left(x_{i}: \sigma_{i}\right)} \quad \overrightarrow{\Delta_{i} \Vdash \mathrm{~A}_{i}: \sigma_{i}} \quad \mathrm{~L}=\left(\cup_{i} \operatorname{supp}\left(\mathrm{~A}_{i}\right)\right) \cup \operatorname{dom}(\Sigma)}{\langle\Sigma ; \Gamma \vdash \mathrm{M}: \perp\rangle{\xrightarrow{?\left(\overrightarrow{\mathrm{~A}_{i}}\right)}}_{\mathrm{ogs}}\left(\left\langle\mathrm{M}\left\{\overrightarrow{\left.x_{i}:=\mathrm{A}_{i}\right\}} ; \widehat{\mathrm{L}} ; \varepsilon\right\rangle,\left\langle\overrightarrow{\Delta_{i}} \mid \perp ; \varnothing\right\rangle,\langle\mathrm{L} ; \mathrm{L}\rangle\right)\right.} \\
& \frac{\Gamma=\overrightarrow{\left(x_{i}: \sigma_{i}\right)}}{\overrightarrow{\delta\left(x_{i}\right) \not / 7\left(\mathrm{~A}_{i} ; \gamma_{i}\right)}} \begin{array}{ll}
\overrightarrow{\Delta_{i} \Vdash \mathrm{~A}: \sigma_{i}} & \mathrm{~L}=\Sigma^{-1}\left(\mathrm{ref}_{\text {Unit }}\right)
\end{array}
\end{aligned}
$$

The initial question generated by $\langle\Sigma ; \Gamma \vdash \mathrm{M}: \sigma\rangle$ provides a way for Opponent to instantiate variables of $\Gamma$ with abstract values. In this setting $\Sigma$ only contains atoms since M is a term of $\lambda \mu \nu$. The transition for $\langle\mathrm{c}: \neg$ Unit $\vdash(\mathrm{S} ; \delta):(\Sigma ; \Gamma)\rangle$ represents this behavior from the point of view of Opponent. Since contexts are written in $\lambda \mu_{\text {ref }}$, these initial configurations come equipped with an initial store S of type $\Sigma$, but only the locations of type $\mathbf{r e f}_{\text {Unit }}$ are considered to be disclosed, since the other ones cannot be used by Proponent. The continuation name c is used for Opponent to perform its final answer, which is of type Unit, following the notion of observation used to define contextual equivalence.

We use notation $\stackrel{\mathbf{p}}{\Rightarrow}$ ogs to denote a $\mathbf{p}$ transition preceded by a possibly empty sequence of op transitions. Trace equivalence according to $\mathcal{L}_{\text {OGS }}$ and contextual equivalence coincide.

Theorem 7. Taking two terms $\mathrm{M}, \mathrm{N}$ such that $\Sigma ; \Gamma \vdash \mathrm{M}, \mathrm{N}: \sigma$, then $\langle\Sigma ; \Gamma \vdash \mathrm{M}$ : $\sigma\rangle \simeq_{\mathrm{tr}}\langle\Sigma ; \Gamma \vdash \mathrm{N}: \sigma\rangle$ if and only if $\Sigma ; \Gamma \vdash \mathrm{M} \simeq_{c t x} \mathrm{~N}: \sigma$.

Such a full-abstraction theorem was proven in [14] for RefML, that is the intuitionistic fragment of $\lambda \mu_{\text {ref }}$-calculus, without control operators. It was also proven in [11] for $H O S C$, a variant of the $\lambda \mu_{\text {ref }}$-calculus, with the call/cc operator, but without atom disclosure. Such a full-abstraction result being rather standard, we have chosen to present its proof in Appendix A.

$$
\begin{aligned}
& \mathrm{OQ} \overline{\langle\mathrm{~L} ; \gamma\rangle \xrightarrow{\mathrm{f}(\mathrm{~A}, \mathrm{c})}{ }_{\mathrm{PI}}\langle[\mathrm{c}] \gamma(\mathrm{f}) \mathrm{A} ; \mathrm{L} \cup \operatorname{supp}(\mathrm{~A})\rangle} \quad \overline{\langle\mathrm{L} ; \gamma\rangle \xrightarrow{\mathrm{c}(\mathrm{~A})}{ }_{\mathrm{PI}}\langle\gamma(\mathrm{c})[\mathrm{A}] ; \mathrm{L} \cup \operatorname{supp}(\mathrm{~A})\rangle} \mathrm{OA}
\end{aligned}
$$

Fig. 5. Definition of $\mathcal{L}_{\text {PI }}$ : transitions of prime interactive configurations

$$
\begin{aligned}
& \mathrm{PQ} \frac{\Delta_{\mathrm{O}}(\mathrm{f})=\sigma \rightarrow \tau \quad \Delta \Vdash \mathrm{A}: \sigma}{\left\langle\Delta_{\mathrm{O}} \mid \perp\right\rangle \xrightarrow{\overline{\mathrm{f}}(\mathrm{~A}, \mathrm{c})} \mathrm{P} T_{\mathrm{y}}\left\langle\Delta_{\mathrm{O}} \mid \Delta, \mathrm{c}: \neg \tau\right\rangle} \\
& \frac{\Delta_{\mathrm{O}}(\mathrm{c})=\neg \sigma \quad \Delta \Vdash{ }^{\bar{c}} \mathrm{~A}: \sigma}{\left\langle\Delta_{\mathrm{O}} \mid \perp\right\rangle \xrightarrow{\bar{c}(\mathrm{~A})} \mathrm{PA} \mathrm{PTy}_{\mathrm{y}}\left\langle\Delta_{\mathrm{O}} \mid \Delta\right\rangle} \mathrm{PA} \\
& \mathrm{OQ} \frac{\Delta_{\mathrm{P}}(\mathrm{f})=\sigma \rightarrow \tau \quad \Delta \Vdash \mathrm{A}: \sigma}{\left\langle\Delta_{\mathrm{O}} \mid \Delta_{\mathrm{P}}\right\rangle \xrightarrow{f(\mathrm{~A}, \mathrm{c})} \mathrm{P} T_{\mathrm{y}}\left\langle\Delta_{\mathrm{O}}, \Delta, \mathrm{c}: \neg \tau \mid \perp\right\rangle} \\
& \frac{\Delta_{\mathrm{P}}(\mathrm{c})=\neg \sigma \quad \Delta \Vdash \mathrm{A}: \sigma}{\left\langle\Delta_{\mathrm{O}} \mid \Delta_{\mathrm{P}}\right\rangle \xrightarrow{\mathrm{c}(\mathrm{~A})} \mathrm{PTy}\left\langle\Delta_{\mathrm{O}}, \Delta \mid \perp\right\rangle} \mathrm{OA}
\end{aligned}
$$

Fig. 6. Definition of $\mathcal{L}_{\text {PTy }}$ : transitions of prime type-context configurations

In the remainder of the paper, we focus on the $\lambda \mu \nu$-calculus. In particular, we only consider OGS configurations corresponding to $\lambda \mu \nu$ from now on.

## 4 Lassen Trees for the $\lambda \mu \nu$-calculus

### 4.1 POGS and POGS bipartite bisimulation

We introduce Lassen trees for terms of the $\lambda \mu \nu$-calculus, as a form of linearized version of $\mathcal{L}_{\text {OGS }}$, where Opponent can interrogate a name provided by Proponent only once, immediately after it has been introduced. So we consider prime interactive configurations which are either passive of the shape $\langle\mathrm{L} ; \gamma\rangle$, or active of the shape $\langle\mathrm{M} ; \mathrm{L}\rangle$ with M a term, L a set of atoms, and $\gamma$ a substitution. Compared to interactive configurations, the active configurations do not carry an environment $\gamma$. Furthermore, we have a set of atoms rather than a full store, since this LTS is defined only for the $\lambda \mu \nu$-calculus and not for the whole $\lambda \mu_{\text {ref }}$-calculus.

The Prime Interactive LTS, $\mathcal{L}_{\mathrm{PI}}$, is then defined as (ConfsPI, Actions, $\rightarrow_{\mathrm{PI}}$ ), with $\rightarrow_{\mathrm{PI}}$ defined in Figure 5.

The corresponding Typing LTS is defined using the transitions given in Figure 6 , which are very close in spirit to the transitions in Figure 3.

The transitions for the Disclosing LTS for POGS are presented on Figure 7. We compare these with the Disclosing LTS for OGS (Figure 4) below.

The Prime Operational Game Semantics LTS is introduced as a synchronization product, together with initial transitions, like for OGS. More precisely, the synchronization between the interactive and typing LTSs requires that active configurations $\langle\mathrm{M} ; \mathrm{L}\rangle$ correspond to type-contexts of the shape $\left\langle\Delta_{\mathrm{O}} \mid \perp\right\rangle$, with

$$
\begin{gathered}
\text { op } \frac{\mathrm{D}^{\prime} \subseteq \mathrm{L}^{\prime}}{\langle\mathrm{L} ; \mathrm{D}\rangle \xrightarrow{\mathrm{op}}{ }_{\mathrm{pd}}\left\langle\mathrm{~L} \uplus \mathrm{~L}^{\prime} ; \mathrm{D} \uplus \mathrm{D}^{\prime}\right\rangle} \\
\mathrm{PQ} / \mathrm{PA} \frac{\operatorname{supp}(\mathbf{p}) \subseteq \mathrm{D}}{\langle\mathrm{~L} ; \mathrm{D}\rangle \xrightarrow{p}_{\mathrm{pd}}\langle\mathrm{~L} ; \mathrm{D}\rangle} \quad \frac{\mathrm{L} \cap \operatorname{supp}(\mathbf{o}) \subseteq \mathrm{D}}{\langle\mathrm{~L} ; \mathrm{D}\rangle{\xrightarrow{\mathbf{o}}{ }_{\mathrm{pd}}\langle\mathrm{~L} \cup \operatorname{supp}(\mathbf{o}) ; \mathrm{D} \cup \operatorname{supp}(\mathbf{o})\rangle} \mathrm{OQ} / \mathrm{OA}}
\end{gathered}
$$

Fig. 7. Definition of $\mathcal{L}_{\text {PDi }}$ : Disclosing LTS for POGS
$\Sigma ; \Delta_{O} \vdash \mathrm{M}: \perp$ and $\vdash \widehat{\mathrm{L}}: \Sigma$, for some store typing context $\Sigma$. Accordingly, for passive configurations $\langle\mathrm{L} ; \gamma\rangle$, we synchronize with $\left\langle\Delta_{\mathrm{O}} \mid \Delta_{\mathrm{P}}\right\rangle$, and check that $\Sigma ; \Delta_{O}+\gamma: \Delta_{P}$ and $\vdash \widehat{\mathrm{L}}: \Sigma$, for some store typing context $\Sigma$.

To synchronize with the Disclosing LTS, whose states are of the form $\langle\mathrm{L} ; \mathrm{D}\rangle$, we simply impose that the L component is the same in the state of $\mathcal{L}_{\mathrm{Pl}}$, both for active and passive configurations.

We call $\mathcal{L}_{\text {POGS }}$ the LTS obtained by synchronizing $\mathcal{L}_{\text {PI }}, \mathcal{L}_{\text {PTy }}$ and $\mathcal{L}_{\text {PDi }}$. We write $\mathbb{P}, \mathbb{Q} \in$ Confspogs the configurations of $\mathcal{L}_{\text {Pogs }}$. The Lassen tree of a term is then defined as the unfolding of the $\mathcal{L}_{\text {POGS }}$ on the initial active configuration associated to this term.

Example 8. The Lassen trees (omitting the typing configurations) for [c]new $n$ in $\lambda_{\text {_. }} n$ and [c] $\lambda$ _new $n$ in $n$ are given by:


Due to the condition $\operatorname{supp}(\mathbf{p}) \subseteq \mathrm{D}$ in $\stackrel{\mathrm{p}}{\mathrm{pd}}$, some configurations with terms in normal form do not have a corresponding Proponent transition. The dashed arrows correspond to op transitions that lead to such stuck configurations.

### 4.2 Bipartite Bisimulations for OGS and POGS

We consider typed relations on passive and active configurations, that is, we require related configurations to have the same type. This means in particular that the environment components $\gamma$ of the two configurations have the same domain. In addition to the typing, we also enforce that both sets of disclosed atoms are identical.

Definition 9. A bipartite bisimulation is a pair of relations ( $\mathcal{R}_{\text {Act }}, \mathcal{R}_{\text {Pas }}$ ) respectively on active and passive configurations, such that:

- If $\left(\mathbb{G}_{1}, \mathbb{G}_{2}\right) \in \mathcal{R}_{\text {Pas }}$ then for all Opponent moves $\mathbf{o}$ and $\mathbb{H}_{1}, \mathbb{H}_{2}$ such that $\mathbb{G}_{1} \xrightarrow{\mathbf{o}} \mathbb{H}_{1}$ and $\mathbb{G}_{2} \xrightarrow{\mathbf{o}} \mathbb{H}_{2}$, we have $\left(\mathbb{H}_{1}, \mathbb{H}_{2}\right) \in \mathcal{R}_{\text {Act }}$.
- If $\left(\mathbb{G}_{1}, \mathbb{G}_{2}\right) \in \mathcal{R}_{\text {Act }}$ then there exists a Proponent move $\mathbf{p}$ and $\left(\mathbb{H}_{1}, \mathbb{H}_{2}\right) \in \mathcal{R}_{\text {Pas }}$ such that $\mathbb{G}_{1} \stackrel{\mathrm{p}}{\Rightarrow} \mathbb{H}_{1}$ and $\mathbb{G}_{2} \stackrel{\mathrm{p}}{\Rightarrow} \mathbb{H}_{2}$.

An OGS-bipartite bisimulation is a bipartite bisimulation defined over $\mathcal{L}_{\mathrm{ogs}}$, and a POGS-bipartite bisimulation is a bipartite bisimulation defined over $\mathcal{L}_{\text {POGS }}$. We write $\simeq_{\text {ogs }}$ and $\simeq_{\text {pogs }}$ respectively for the greatest bipartite bisimulation respectively over $\mathcal{L}_{\text {ogs }}$ and $\mathcal{L}_{\text {POGS }}$.

The following property follows from the fact that the transition relation is deterministic (up to the choice of fresh names).
Lemma 10. $\simeq_{\text {ogs }}$ coincides with trace equivalence on OGS configurations.
For op transitions, the difference between OGS and POGS shows up in the disclosing LTS: in $\xrightarrow{\text { op }}$ pd , a $D^{\prime}$ component can be chosen non-deterministically. This observation is related to the existential quantification in the second clause of Definition 13 . Both in $\mathcal{L}_{\text {OGS }}$ and $\mathcal{L}_{\text {POGS }}$, there is only one possible next visible (Proponent) move. However, in $\simeq_{\text {pogs }}$, the game involves choosing an appropriate set of atoms to be disclosed along ${ }^{\mathrm{op}}{ }_{\mathrm{pd}}$ transitions. For instance, when constructing a POGS bipartite bisimulation between terms new $n$ in $\lambda_{\text {_. }} n$ and $\lambda_{\text {_.new }} n$ in $n$ from Example 8, we have two choices for the second step:

$$
\begin{aligned}
& \left(\left(\left\langle\{\mathrm{a}\} ;\left[\mathrm{f} \mapsto \lambda_{\mathrm{I}} \mathrm{a}\right]\right\rangle,\langle\{\mathrm{a}\}, \emptyset\rangle\right), \quad\left(\left\langle\emptyset ;\left[\mathrm{f} \mapsto \lambda_{\text {_.new }} n \text { in } n\right]\right\rangle,\langle\emptyset, \emptyset\rangle\right)\right) \\
& \left(\left(\left\langle\{\mathrm{a}\} ;\left[\mathrm{f} \mapsto \lambda_{\mathrm{I}} . \mathrm{a}\right]\right\rangle,\langle\{\mathrm{a}\},\{\mathrm{a}\}\rangle\right), \quad\left(\left\langle\emptyset ;\left[\mathrm{f} \mapsto \lambda_{\text {_.new }} n \text { in } n\right]\right\rangle,\langle\emptyset, \emptyset\rangle\right)\right)
\end{aligned}
$$

The latter does not satisfy the constraint on the disclosed set, since the sets are not the same in the two configurations. The former leads to a stuck configuration: $\left(\left\langle\left[c^{\prime}\right]\left(\lambda_{-} . a\right)(),\{a\}\right\rangle,\langle\{a\}, \emptyset\rangle\right)$ cannot perform any Proponent move. Thus the two programs are not equivalent.

### 4.3 Deciding $\simeq_{\text {pogs }}$

We now study how to decide when two POGS configurations are bisimilar. First, trees generated by $\mathcal{L}_{\text {POGS }}$ are of finite depth.

Lemma 11. Taking a POGS configuration $\mathbb{G}$, any trace in $\operatorname{Tr}_{\text {Pogs }}(\mathbb{G})$ is finite.
This lemma is proven using a biorthogonal logical predicate, following the use of biorthogonality to prove strong normalization of $\lambda \mu$-calculus [26], the computational metalanguage [19], and cut elimination for linear logic [10]. The proof can be found in Appendix D.

Due to the non-determinism of atom generation in $\mapsto_{\mathrm{op}}$, of function name generation in $\not \mathscr{}$, and of name picking in Opponent transitions, the trees generated by $\mathcal{L}_{\text {POGS }}$ are infinitely branching. To tame this infinite branching, we see the set of moves Moves and the set of configurations Confspogs of $\mathcal{L}_{\text {POGS }}$ as nominal sets [9] over atoms, function and continuation variables. So taking $\pi$ a
finite permutation over these sets, we write $\pi * X$ for the action of permutation $\pi$ over elements of nominal set $X$. The transition relation $\rightarrow_{\text {pogs }}$ of $\mathcal{L}_{\text {POGS }}$ preserves this action of permutation, i.e., it is equivariant: if $\mathbb{P} \xrightarrow{m}{ }_{\text {pogs }} \mathbb{Q}$ then for all finite permutation $\pi$, we have $\pi * \mathbb{P} \xrightarrow{\pi * \mathrm{~m}}$ pogs $\pi * \mathbb{Q}$.

One can then consider a variant $\mathcal{L}_{\text {DPOGS }}$ of the POGS LTS which uses the same set of configurations as $\mathcal{L}_{\text {POGS }}$, but whose transition relation $\rightarrow_{\text {dpogs }}$ chooses fresh atoms and names deterministically. So $\rightarrow_{\text {dpogs }}$ is then deterministic on op and Proponent actions, and finitely branching on Opponent actions.

We remark at this point that the notion of bipartite bisimulation $\simeq_{\text {pogs }}$ introduced in Definition 13 is not suited for $\mathcal{L}_{\text {DPOGS }}$. Indeed, it requires equality of actions in the bisimulation game, and also that configurations related by bisimulation have the same type. So we relax the definition of $\simeq_{\text {pogs }}$ and work with ternary relations, adding a finite permutation of names and atoms in order to match the actions, rather than enforcing syntactic equality.

Definition 12. A relation $\mathcal{R} \subseteq$ Confspogs $\times$ Confspogs $\times$ Perm is said to be valid when, for all $\left(\left(\mathbb{I}, \mathbb{S},\left\langle_{\_}, \mathrm{D}\right\rangle\right),\left(\mathbb{J}, \mathbb{T},\left\langle \_, \mathrm{D}^{\prime}\right\rangle\right), \pi\right) \in \mathcal{R}$, we have $\mathbb{T}=\pi * \mathbb{S}$ and $\mathrm{D}^{\prime}=\pi * \mathrm{D}$.

Definition 13. A relaxed bipartite bisimulation is a pair of valid relations $\left(\mathcal{R}_{\text {Act }}, \mathcal{R}_{\text {Pas }}\right)$ respectively on active and passive configurations such that:

- If $\left(\mathbb{P}_{1}, \mathbb{P}_{2}, \pi\right) \in \mathcal{R}_{\text {Pas }}$ then for all Opponent moves $\mathbf{o}_{1}, \mathbf{o}_{2}$, for all permutation $\pi^{\prime}$ extending $\pi$, and active POGS configurations $\mathbb{Q}_{1}, \mathbb{Q}_{2}$ satisfying $\mathbf{o}_{2}=\pi^{\prime} * \mathbf{o}_{1}$, $\mathbb{P}_{1} \xrightarrow{\mathbf{o}_{1}} \mathbb{Q}_{1}$ and $\mathbb{P}_{2} \xrightarrow{\mathbf{o}_{2}} \mathbb{Q}_{2}$, we have $\left(\mathbb{Q}_{1}, \mathbb{Q}_{2}, \pi^{\prime}\right) \in \mathcal{R}_{\text {Act }}$.
- If $\left(\mathbb{P}_{1}, \mathbb{P}_{2}, \pi\right) \in \mathcal{R}_{\text {Act }}$ then there exists a permutation $\pi^{\prime}$ extending $\pi$, two Proponent moves $\mathbf{p}_{2}=\pi^{\prime} * \mathbf{p}_{1}$, and two passive POGS configurations $\mathbb{Q}_{1}, \mathbb{Q}_{2}$ such that $\left(\mathbb{Q}_{1}, \mathbb{Q}_{2}, \pi^{\prime}\right) \in \mathcal{R}_{\text {Pas }}, \mathbb{P}_{1} \stackrel{\mathbf{p}_{1}}{\Longrightarrow} \mathbb{Q}_{1}$ and $\mathbb{P}_{2} \xlongequal{\mathbf{p}_{2}} \mathbb{Q}_{2}$.

We write $\simeq_{\text {pogs }}^{r}$ for the greatest relaxed bipartite bisimulation over $\mathcal{L}_{\text {POGS }}$. From the fact that $\rightarrow_{\text {pogs }}$ is equivariant, we deduce that $\simeq_{\text {pogs }}^{r}$ and $\simeq_{\text {ogs }}$ coincide. Since $\mathcal{L}_{\text {DPOGS }}$ generates finite Lassen trees, we deduce that the bisimulation game can be decided.

Theorem 14. Taking two POGS configurations $\mathbb{P}, \mathbb{Q}$, we can decide if $\mathbb{P} \simeq_{\text {pogs }} \mathbb{Q}$.

### 4.4 Relating the Transitions in OGS and POGS

To relate the transitions in the OGS and in the POGS, we need to introduce some relations and operations on OGS configurations.

Definition 15. Let $\mathbb{G}=(\mathbb{I}, \mathbb{S},\langle\mathrm{L} ; \mathrm{D}\rangle)$ and $\mathbb{H}=\left(\mathbb{I}, \mathbb{S},\left\langle\mathrm{L} ; \mathrm{D}^{\prime}\right\rangle\right)$ be two OGS configurations. We write $\mathbb{G} \subseteq_{\mathrm{Di}} \mathbb{H}$ for when $\mathrm{D} \subseteq \mathrm{D}^{\prime}$.

When $\mathbb{G} \subseteq_{D i} \mathbb{H}$, the configurations only differ by their set of disclosed atoms.
Lemma 16. If $\mathbb{G} \subseteq_{\mathrm{Di}} \mathbb{H}$ and $\mathbb{G} \xrightarrow{\mathrm{a}} \mathrm{ogs} \mathbb{G}^{\prime}$ then $\mathbb{H} \xrightarrow{\mathrm{a}} \mathrm{ogs}^{H^{\prime}}$ and $\mathbb{G}^{\prime} \subseteq_{\mathrm{Di}} \mathbb{H}^{\prime}$.
Lemma 17. Let $\mathbb{P}$ be an active prime configuration. We have the following:

- if $\mathbb{P} \xrightarrow{\text { op }}{ }_{\text {ogs }} \mathbb{P}^{\prime}$, then $\mathbb{P} \xrightarrow{\text { op }}{ }_{\text {pogs }} \mathbb{P}^{\prime}$,
- if $\mathbb{P} \xrightarrow{\text { op }}_{\text {pogs }} \mathbb{P}^{\prime}$, then $\mathbb{P} \xrightarrow{\text { op }}{ }_{\text {ogs }} \subseteq_{\text {Di }} \mathbb{P}^{\prime}$.

In POGS, the disclosed set increases in op transitions as seen above, but not in $\mathbf{p}$. In a sense, disclosing in OGS is done only when needed, whereas in POGS, disclosing must be declared as soon as the atom is created. This is ensured by the additional condition $\operatorname{supp}(\mathbf{p}) \subseteq \mathrm{D}$ in the rule for $\xrightarrow{\mathbf{p}}_{\mathrm{pd}}$.

Lemma 18. When $\mathbb{P} \xrightarrow{\mathrm{p}}_{\text {pogs }} \mathbb{P}^{\prime}$ with $\mathbb{P}$ active, we also have $\mathbb{P} \xrightarrow{\mathrm{p}} \mathrm{ogss}^{\mathbb{P}^{\prime}}$.
However, the converse does not always hold, specifically if an atom has been declared non-disclosed but still appears in the action $\mathbf{p}$. Indeed, the transition $(\langle[\mathrm{c}] \mathrm{a} ; \widehat{\mathrm{L}} ; \emptyset\rangle, \mathbb{S},\langle\mathrm{L} ; \emptyset\rangle) \xrightarrow{\overline{\mathrm{c}}(\mathrm{a})}$ ogs $(\langle\widehat{\mathrm{L}} ; \emptyset\rangle, \mathbb{S},\langle\mathrm{L} ;\{\mathrm{a}\}\rangle)$ is valid for OGS, but has no counterpart in POGS, since $\langle L ; \emptyset\rangle$ cannot make the transition $\xrightarrow{\bar{c}(a)}$ pd .

Using the following notion of limit (on OGS configurations), we can intuitively replace $D$ by its minimal extension, preventing this from happening.

Definition 19. Given a configuration $\mathbb{G}=(\mathbb{I}, \mathbb{S},\langle\mathrm{L} ; \mathrm{D}\rangle)$, we define its limit as:

$$
\lim (\mathbb{G}) \triangleq\left(\mathbb{I}, \mathbb{S},\left\langle\mathrm{L} ; \bigcup_{\mathrm{t} \in \text { Traces }}\left(\mathrm{L} \cap \mathrm{D}^{\prime}\right)\right\rangle\right) \text { with } \mathbb{G} \xrightarrow{\mathrm{t}} \mathrm{ogs}\left(-,-,\left\langle-, \mathrm{D}^{\prime}\right\rangle\right)
$$

We have that $\mathbb{G} \subseteq_{\text {Di }} \lim (\mathbb{G})$ and $\lim$ is idempotent. We call limit configurations those configurations that are a limit (or alternatively, that are their own limit). Being a limit configuration is preserved by moves but not necessarily by op.
Lemma 20. Let $\mathbb{P}$ be a limit configuration. If $\mathbb{P} \xrightarrow{\mathbf{p}}{ }_{\text {ogs }} \mathbb{P}^{\prime}$, then $\mathbb{P} \xrightarrow{\mathbf{p}}$ pogs $\mathbb{P}^{\prime}$.
For Opponent transitions, the situation is less simple since not all active OGS configurations are active POGS configurations. To circumvent that issue, we reuse the tensor product from [13]. For two OGS configurations where at least one is passive, we define the tensor product, written $\otimes$, as follows:

$$
\begin{gathered}
(\mathbb{I}, \mathbb{S}, \mathbb{D}) \otimes(\mathbb{J}, \mathbb{T}, \mathbb{E})=(\mathbb{I} \otimes \mathbb{J}, \mathbb{S} \otimes \mathbb{T}, \mathbb{D} \otimes \mathbb{E}) \\
\langle\mathrm{S} ; \gamma\rangle \otimes\left\langle\mathrm{S}^{\prime} ; \gamma^{\prime}\right\rangle=\left\langle\mathrm{S} \cup \mathrm{~S}^{\prime} ; \gamma \cdot \gamma^{\prime}\right\rangle \quad\langle\mathrm{M} ; \mathrm{S} ; \gamma\rangle \otimes\left\langle\mathrm{S}^{\prime} ; \gamma^{\prime}\right\rangle=\left\langle\mathrm{M} ; \mathrm{S} \cup \mathrm{~S}^{\prime} ; \gamma \cdot \gamma^{\prime}\right\rangle \\
\langle\mathrm{L} ; \mathrm{D}\rangle \otimes\left\langle\mathrm{L}^{\prime} ; \mathrm{D}^{\prime}\right\rangle=\left\langle\mathrm{L} \cup \mathrm{~L}^{\prime} ; \mathrm{D} \cup \mathrm{D}^{\prime}\right\rangle \text { when } \begin{array}{l}
\mathrm{D}^{\prime} \cap \mathrm{L} \subseteq \mathrm{D} \\
\mathrm{D} \cap \mathrm{~L}^{\prime} \subseteq \mathrm{D}^{\prime}
\end{array}
\end{gathered}
$$

The side conditions for the L and D components ensure that no shared atom is disclosed on one configuration but not the other.

We can then describe an active OGS configuration as the tensor of two POGS configurations (where $S=\widehat{\mathrm{L}}$ ):
$\left(\langle\mathrm{M} ; \mathrm{S} ; \gamma\rangle,\left\langle\Delta_{O} \vdash \perp ; \Delta_{P}\right\rangle,\langle\mathrm{L}, \mathrm{D}\rangle\right)=\left(\langle\mathrm{M} ; \mathrm{L}\rangle,\left\langle\Delta_{O} \vdash \perp\right\rangle,\langle\mathrm{L}, \mathrm{D}\rangle\right) \otimes\left(\langle\mathrm{L} ; \gamma\rangle,\left\langle\Delta_{O} \vdash \Delta_{P}\right\rangle,\langle\mathrm{L}, \mathrm{D}\rangle\right)$
Finally, we have the following for opponent transitions:

When $\mathbb{P} \xrightarrow{\mathbf{o}}$ ogs $^{G}$, we have $\mathbb{P} \xrightarrow{\mathbf{o}}$ pogs $_{\mathbb{Q}}$ with $\mathbb{G}=\mathbb{Q} \otimes \mathbb{P}$.

## 5 Relating Bisimilarities in OGS and POGS

In this section, we show that $\simeq_{\text {pogs }}$ can be used to characterize $\simeq_{\text {ogs }}$ for the limit configurations introduced above. We rely for that on up-to techniques for bipartite bisimulation in OGS, which we introduce first.

### 5.1 Up-to techniques for $\simeq_{\text {ogs }}$

The proofs in this section use the theory of compatible functions [30, 28]. More details can be found in Appendix B.

Definition 22 (Bipartite bisimulation up-to). Given a function f, a bipartite bisimulation up to $f$ is a pair $\left(\mathcal{R}_{\text {Act }}, \mathcal{R}_{\text {Pas }}\right)$ such that:

- If $\left(\mathbb{G}_{1}, \mathbb{G}_{2}\right) \in \mathcal{R}_{\text {Pas }}$ then for all Opponent moves $\mathbf{o}$ and $\mathbb{H}_{1}, \mathbb{H}_{2}$ such that $\mathbb{G}_{1} \xrightarrow{\mathbf{o}}{ }_{\mathrm{ogs}} \mathbb{H}_{1}$ and $\mathbb{G}_{2} \xrightarrow{\mathbf{o}} \mathrm{ogs}^{\mathbb{H}_{2}}$, we have $\left(\mathbb{H}_{1}, \mathbb{H}_{2}\right) \in f\left(\mathcal{R}_{\text {Act }}\right)$.
- If $\left(\mathbb{G}_{1}, \mathbb{G}_{2}\right) \in \mathcal{R}_{\text {Act }}$ then there exists a Proponent move $\mathbf{p}$ and $\left(\mathbb{H}_{1}, \mathbb{H}_{2}\right) \in$ $f\left(\mathcal{R}_{\text {Pas }}\right)$ such that $\mathbb{G}_{1} \xrightarrow[\text { ogs }]{\Rightarrow} \mathbb{H}_{1}$ and $\mathbb{G}_{2} \xlongequal[\text { ogs }]{\boldsymbol{p}} \mathbb{H}_{2}$.

We then define hide $\left(\mathcal{R}_{A c t}, \mathcal{R}_{\text {Pas }}\right) \triangleq\left(\subseteq_{\mathrm{Di}} \mathcal{R}_{A c t} \supseteq_{\mathrm{Di}}, \subseteq_{\mathrm{Di}} \mathcal{R}_{\text {Pas }} \supseteq_{\mathrm{Di}}\right)$. Recall that we still require that hide $\left(\mathcal{R}_{\text {Act }}, \mathcal{R}_{\text {Pas }}\right)$ only contains pairs of configurations with the same disclosed set. The soundness of hide can be proved using Lemma 16.

Lemma 23. hide is a sound up-to technique, i.e. if $\left(\mathcal{R}_{A c t}, \mathcal{R}_{\text {Pas }}\right)$ is a bisimulation up to hide, then $\left(\mathcal{R}_{\text {Act }}, \mathcal{R}_{\text {Pas }}\right) \subseteq \simeq_{\text {ogs }}$.

Given a pair of relations $\left(\mathcal{R}_{\text {Act }}, \mathcal{R}_{\text {Pas }}\right)$ on active and passive OGS configurations respectively, we define the following functions:

```
tensor \(\left(\mathcal{R}_{\text {Act }}, \mathcal{R}_{\text {Pas }}\right) \triangleq\left(\left\{\left(\mathbb{G}_{1} \otimes \mathbb{G}_{2}, \mathbb{H}_{1} \otimes \mathbb{H}_{2}\right)\right.\right.\) s.t. \(\left.\left(\mathbb{G}_{1}, \mathbb{H}_{1}\right) \in \mathcal{R}_{A c t},\left(\mathbb{G}_{2}, \mathbb{H}_{2}\right) \in \mathcal{R}_{\text {Pas }}\right\}\),
    \(\left\{\left(\mathbb{G}_{1} \otimes \mathbb{G}_{2}, \mathbb{H}_{1} \otimes \mathbb{H}_{2}\right)\right.\) s.t. \(\left.\left.\left(\mathbb{G}_{1}, \mathbb{H}_{1}\right),\left(\mathbb{G}_{2}, \mathbb{H}_{2}\right) \in \mathcal{R}_{\text {Pas }}\right\}\right)\)
\(\operatorname{split}\left(\mathcal{R}_{A c t}, \mathcal{R}_{\text {Pas }}\right) \triangleq\left(\left\{\left(\mathbb{G}_{1}, \mathbb{H}_{1}\right) \quad\right.\right.\) s.t. \(\left.\left(\mathbb{G}_{1} \otimes \mathbb{G}_{2}, \mathbb{H}_{1} \otimes \mathbb{H}_{2}\right) \in \mathcal{R}_{\text {Act }}\right\}\),
    \(\left\{\left(\mathbb{G}_{1}, \mathbb{H}_{1}\right) \quad\right.\) s.t. \(\left.\left(\mathbb{G}_{1} \otimes \mathbb{G}_{2}, \mathbb{H}_{1} \otimes \mathbb{H}_{2}\right) \in \mathcal{R}_{\text {Pas }}\right\}\)
```

Lemma 24. split $\left(\simeq_{\text {ogs }}\right) \subseteq \simeq_{\text {ogs }}$.
tensor is not a sound up-to technique. It is nevertheless useful to reason about POGS bipartite bisimilar configurations; see Theorem 30 below.

### 5.2 Properties of the Limit (in OGS)

Lemma 25 (Monotonicity). If $\mathbb{G}$ is passive and $\mathbb{G} \xrightarrow{\mathbf{t}} \mathrm{ogs} \mathbb{H}$, then there exists $\mathbb{G}^{\prime}$ such that $\mathbb{G} \otimes \mathbb{G}^{\prime} \subseteq_{\mathrm{Di}} \mathbb{H}$.

Lemma 25 shows that transitions can only increase the substitution and the store (corresponding to the $\mathbb{G}^{\prime}$ component), and the set of disclosed atoms (represented by the use of $\subseteq_{\text {Di }}$ ). More precisely, $\subseteq_{\text {Di }}$ is required if some atoms from $\mathbb{G}$ are disclosed along the trace $\mathbf{t}$, in which case new ones can appear in $\mathbb{G}^{\prime}$.

Lemma 25 is language specific. It does not hold when the language allows the content of the store to be modified (like, e.g. in $\lambda \mu_{\text {ref }}$ ). Additionally, LTSs enforcing some local restriction on the usage of function or continuation names usually have extra components that are modified along the transitions; we return to this point in Section 7.

In a limit configuration (Definition 19), all atoms that may be disclosed at some point are disclosed. By Lemma 25, these atoms can be disclosed using a single trace.

Lemma 26. Given a passive configuration $\mathbb{G}$, there exists a trace $\mathbf{t}$ and a configuration $\mathbb{H}$ such that $\mathbb{G} \xrightarrow{\mathbf{t}}{ }_{\mathrm{ogs}} \lim (\mathbb{G}) \otimes \mathbb{H}$.

The limit is also useful to relate transitions in OGS and in POGS as follows.
Lemma 27. Take a POGS configuration $\mathbb{P}$.
If $\mathbb{P}$ is active and $\mathbb{P} \xrightarrow{\text { a }}$ ogs $\mathbb{Q}$, then $\lim (\mathbb{P}) \xrightarrow{\mathrm{a}}$ pogs $\lim (\mathbb{Q})$.

All in all, we obtain that $\simeq_{\text {ogs }}$ is a congruence for $\lim$. For $\mathcal{R}$ a relation over configurations, we write $\lim (\mathcal{R})$ for the set $\{(\lim (\mathbb{G}), \lim (\mathbb{H})) \mid(\mathbb{G}, \mathbb{H}) \in \mathcal{R}\}$.

Lemma 28. $\simeq_{\text {ogs }}$ is closed by computing the limit: $\lim \left(\simeq_{\text {ogs }}\right) \subseteq \simeq_{\text {ogss }}$.
The case for passive configurations follows immediately from Lemmas 26 and 24.
The property of the limit might make us think that the disclosure process of an atom could be decided statically, by annotating new syntactically. The following example shows that it is not the case:

$$
\lambda b \text {.new } n, m \text { in } \lambda \text {.if } b \text { then } n \text { else } m
$$

Either $n$ or $m$ will be disclosed depending on the boolean $b$ given by Opponent, but never both. So this term is indeed contextually equivalent to $\lambda b$.new $n$ in $\lambda_{\text {_. }}$.

### 5.3 Correspondence Between $\simeq_{\text {ogs }}$ and $\simeq_{\text {pogs }}$

Theorem 29 (From $\simeq_{\text {ogs }}$ to $\simeq_{\text {pogs }}$ ). Consider two POGS configurations $\mathbb{P}$ and $\mathbb{Q}$. If $\mathbb{P} \simeq_{\text {ogs }} \mathbb{Q}$ are both limit configurations, then $\mathbb{P} \simeq_{\text {pogs }} \mathbb{Q}$.

To reason about bisimilar POGS configurations, we use the closure of tensor, written tensor. Intuitively, $\overline{\text { tensor }}\left(\mathcal{R}_{A c t}\right)$ contains the pairs $\left(\mathbb{G}_{1} \otimes \mathbb{G}_{2}, \mathbb{H}_{1} \otimes \mathbb{H}_{2}\right)$ with $\left(\mathbb{G}_{1}, \mathbb{H}_{1}\right) \in \mathcal{R}_{\text {Act }},\left(\mathbb{G}_{2}, \mathbb{H}_{2}\right) \in \overline{\text { tensor }}\left(\mathcal{R}_{\text {Pas }}\right)$, and tensor $\left(\mathcal{R}_{\text {Pas }}\right)$ contains the pairs $\left(\mathbb{G}_{1} \otimes \mathbb{G}_{2}, \mathbb{H}_{1} \otimes \mathbb{H}_{2}\right)$ with $\left(\mathbb{G}_{1}, \mathbb{H}_{1}\right) \in \mathcal{R}_{\text {Pas }},\left(\mathbb{G}_{2}, \mathbb{H}_{2}\right) \in \operatorname{tensor}\left(\mathcal{R}_{\text {Pas }}\right)$.

Theorem 30 (From $\simeq_{\text {pogs }}$ to $\simeq_{\text {ogs }}$ ). Suppose $\mathcal{R}$ is a POGS bipartite bisimulation. Then tensor $(\mathcal{R})$ is a OGS bipartite bisimulation up-to hiding.

By Lemma 23 , Theorem 30 means that if $\mathbb{P} \simeq_{\text {pogs }} \mathbb{Q}$, then $\mathbb{P} \simeq_{\text {ogs }} \mathbb{Q}$.
The correspondence between $\simeq_{\text {ogs }}$ and $\simeq_{\text {pogs }}$ is restricted to prime configurations as $\simeq_{\text {pogs }}$ can only relate those. Having the additional conditions of configurations being limits is enough for our decidability result.

## 6 Related Work

The $v$-calculus was introduced in [27], together with logical relations to reason over contextual equivalence for this language. These logical relations use a Kripke-style definition, worlds being defined as spans of atoms to keep track of the disclosed atoms, similar to the permutation we use in our relaxed bipartite bisimulations. They capture contextual equivalence for programs of first order type, but are an incomplete technique for higher-order programs. This entails a decidability result for the first-order fragment of the $v$-calculus, since logical relations only quantify over finite objects at first-order types.

Categorical models of the $v$-calculus were provided in [32, 33], using a representation of name creation via a strong monad. Two examples of such models were given: (i) the functor category $S_{e t} I^{\text {w }}$ with $I$ the category of finite sets and injection; (ii) the category $\mathbf{B} G$ of continuous $G$-sets, with $G$ the topological group of automorphisms over $\mathbb{N}$. None of these models are fully-abstract, since they distinguish new $n$ in $\lambda x \cdot x=n$ from $\lambda x$.false.

These models were later refined using nominal sets [9], so that types are interpreted via Fraenkel-Mostowski sets [31] or domains [15]. Both of these works are continuation models; they might be used to provide a semantics for the $\lambda \mu \nu$ calculus studied in this paper, a direction we wish to explore in future work. Such use of continuations was justified in [31] to provide a model for an extension of the $v$-calculus with recursion. More recently, proof-relevant logical relations were introduced to deal with recursion in the presence of name generation [5].

In [29], a model of the $v$-calculus is given in quasi-Borel spaces, showing a correspondence between random sampling and fresh name generation. This model is shown to be fully-abstract for terms of first-order types.

In [6], environmental bisimulations for the $v$-calculus are defined and shown to be fully abstract. Nevertheless, it does not seem possible to extract a decision procedure from that result, since environmental bisimulations are played over a higher-order LTS, that is, an LTS whose actions contain $\lambda$-terms. So this LTS is infinitely branching at higher-order types.

Eager normal-form bisimulations have been introduced by Lassen for the call-by-value $\lambda$-calculus [17] and $\lambda \mu$-calculus. In [34], a notion of bisimulation similar to $\simeq_{\text {ogs }}$ is introduced and shown to be fully abstract for an untyped version of $\lambda \mu_{\text {ref }}$. Compared to the standard notion of eager normal form bisimulations, the configurations in the bisimulations in [34] contain an environment similar to the environment component $\gamma$ of the OGS LTS in Section 3.

In [1], a fully-abstract game model is provided for the $v$-calculus. However, this model requires an extensional collapse, that is not directly computable at higher-order type. So that model could only be used to prove the decidability of contextual equivalence for terms of first-order types. Enforcing a well-bracketed and visible behavior for Opponent in the OGS model, we believe that our trace model would coincide with the intentional game model of [1]. Nominal game semantics was developed for languages with nominal references and exceptions in [36]. In that setting, algorithmic presentations of game semantics make it possible to provide a classification of decidability of call-by-value languages with
(bounded) integer references [22], and ground references [24]. In this setting, the undecidability of contextual equivalence originates from the use of integer references by Proponent. A detailed survey on the literature on contextual equivalence for the $v$-calculus is available in [37].

## 7 Conclusion

To decide the contextual equivalence between two $\lambda \mu \nu$ typed terms M and N with contexts in the $\lambda \mu_{\text {ref }}$-calculus, we first construct the corresponding initial configurations, and we can decide by Thm. 14 if they are POGS-bisimilar. This decidability result comes from the fact that the POGS LTS generates finite trees.

Then, we prove in Thm. 29 and Thm. 30 that two initial active configurations are POGS-bisimilar iff they are OGS-bisimilar. This is possible because initial configurations are prime (they are active and $\gamma$ is empty) and are also limit configurations (their disclosed sets contain all the atoms of the store). In Thm. 7 and Lemma 10, we prove that M and N are contextually equivalent iff the corresponding initial configurations are OGS-bisimilar, which yields decidability.

We now examine the obstacles that remain to prove the decidability of contextual equivalence with contexts in the $v$-calculus.

First of all, in that setting, trace equivalence would not be fully-abstract anymore (Thm. 7). Indeed, without integer references, one cannot observe the sequentiality of calls and returns. So an extensional collapse would be necessary.

Another obstacle is that in the absence of higher-order references, Opponent must satisfy a condition of O-visibility [2], that corresponds to a local well-scoping discipline, for the function names it is allowed to call. Working in an intuitionistic type system, corresponding to the standard $\lambda$-calculus without control operators, the call-and-return discipline of the interaction between Proponent and Opponent has to be well-bracketed. These two conditions, namely O-visibility and well-bracketing, can be enforced operationally [14] in the LTS, by keeping track of part of the history of the interaction. However the reduction of $\simeq_{\text {ogs }}$ to $\simeq_{\text {pogs }}$ is not possible anymore in that setting. Indeed, the limit over-approximates the set of atoms that can be tested. This can be seen when comparing the programs
new $n$ in let ${ }_{-}=y(\lambda z . z=a)$ in $n$ and new $n$ in let $=y(\lambda z . f a l$ se $)$ in $n$
Assuming $n$ is immediately disclosed makes it possible to distinguish the two programs. Because the local conditions of well-bracketing or visibility would prevent Opponent from playing some actions, Opponent could perform irreversible changes that would invalidate Lemma 25 . This would make $\simeq_{\text {pogs }}$ incomplete.

To handle this difficulty, we could try and use Kripke eager normal-form bisimulation [12], using a structure for worlds richer than just a set of atoms.

Finally, in absence of full ground references, that can store locations, atoms played by Opponent would also follow a local well-scoping discipline, but the discriminatory power over Player atoms would also be restricted [23]. In such a setting, the same difficulties as with well-bracketing and O-visibility would arise, and a more complex extensional collapse would be needed.

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## A Full Abstraction of the OGS LTS

We prove in this appendix that trace-equivalence $\simeq_{\operatorname{tr}}$ and contextual equivalence $\simeq_{c t x}$ coincide. The proof uses the notion of "closed instantiation of all use" (CIU) equivalence, as introduced in [20].

The proof goes through the introduction of a notion of "parallel composition with hiding" of OGS configurations, which is defined as a reduction relation $\mapsto_{\text {so }}$. This composition is used to define an observational equivalence $\simeq_{\text {barb }}$ for the OGS LTS as a barbed equivalence. We then prove that

- $\simeq_{\text {ciu }}$ and $\simeq_{\text {barb }}$ coincide on initial configurations, by using the fact that:
- the observation over Unit type used in the definition of $\simeq_{c t x}$ coincides with the observation used to define $\simeq_{\text {barb }}$;
- the reduction relation used to define the composition and the operational semantics are bisimilar.
$-\simeq_{\operatorname{tr}}$ is included in $\simeq_{\text {barb }}$, since the notion of observation used to define $\simeq_{\text {barb }}$ corresponds to an answer c(());
$-\simeq_{\text {barb }}$ is included in $\simeq_{\text {tr }}$, by proving a definability result to build an OGS configuration that generates exactly a given trace.


## A. 1 CIU equivalence

Definition 31. Two terms $\mathrm{M}, \mathrm{N}$ are said to be ciu equivalent, written $\Sigma ; \Gamma \vdash$ $\mathrm{M} \simeq_{\text {ciu }} \mathrm{N}: \sigma$, when for all store typing context $\Sigma^{\prime} \supseteq \Sigma$ for all covariable c, for all substitution $\gamma$ such that $\Sigma^{\prime} ; \mathrm{c}: \neg$ Unit $\vdash \gamma: \Gamma$, for all store S such that $\vdash \mathrm{S}: \Sigma^{\prime}$, and for all continuation variable c we have $(\mathrm{M}\{\gamma\}, \mathrm{S}) \Downarrow[\mathrm{c}]()$ if and only if $(\mathrm{N}\{\gamma\}, \mathrm{S}) \Downarrow[\mathrm{c}]()$.

Following the general framework developed in [35], we can prove the correspondence between $\simeq_{c i u}$ and $\simeq_{c t x}$.

Theorem 32. $\Sigma ; \Gamma \vdash \mathrm{M} \simeq_{c i u} \mathrm{~N}: \sigma$ if and only if $\Sigma ; \Gamma \vdash \mathrm{M} \simeq_{c t x} \mathrm{~N}: \sigma$.

## A. 2 Composition and Barbed Equivalence

We introduce the composition of two OGS configurations, one representing Proponent and the other Opponent. To do so, we first define when such a composition is possible, via a compatibility predicate. The latter is defined as a reduction relation between pairs of OGS configurations, following [16, 13].

Definition 33. Taking a Ty configuration $\mathbb{S}$, we define its c -dual configuration, written $\mathbb{S}^{* c}$, as:

$$
\begin{aligned}
& \left\langle\Delta_{O} \mid \Delta_{P}\right\rangle^{*_{c}} \triangleq\left\langle\Delta_{P}, \mathrm{c}: \neg \text { Unit } \mid \perp ; \Delta_{O}\right\rangle \\
& \left\langle\Delta_{O} \mid \perp ; \Delta_{P}\right\rangle^{* c} \triangleq\left\langle\Delta_{P}, \mathrm{c}: \neg \text { Unit } \mid \Delta_{O}\right\rangle
\end{aligned}
$$

Definition 34. We say that two OGS configurations $\mathbb{G}=(\mathbb{I} ; \mathbb{S} ; \mathbb{D})$ and $\mathbb{H}=$ $(\mathbb{J} ; \mathbb{T} ; \mathbb{E})$ are c-compatible, written compat $_{\mathrm{c}}(\mathbb{G}, \mathbb{H})$ when:

- the two are initial, with $\mathbb{G}$ of the shape $\langle\Sigma ; \Gamma \vdash \mathrm{M}: \perp\rangle$ and $\mathbb{H}$ of the shape $\langle\mathrm{c}: \neg$ Unit $\vdash(\mathrm{S} ; \gamma):(\Sigma ; \Gamma)\rangle$ with $\Sigma \subseteq \Sigma^{\prime}$.
- or $\mathbb{G}=(\mathbb{I} ; \mathbb{S} ; \mathbb{D})$ and $\mathbb{H}=(\mathbb{J} ; \mathbb{T} ; \mathbb{E})$ one is active and the other passive, and:
- writing S and T for the store component of $\mathbb{I}$ and $\mathbb{J}$ respectively, for all $\ell \in \operatorname{dom}(\mathrm{S}) \cap \operatorname{dom}(\mathrm{T}), \mathrm{S}(\ell)=\mathrm{T}(\ell)=()$.
- $\mathbb{T}=\mathbb{S}^{* c}$;
- writing $\mathbb{D}$ as $\langle\mathrm{L}, \mathrm{D}\rangle$ and $\mathbb{E}$ as $\left\langle\mathrm{L}^{\prime}, \mathrm{D}^{\prime}\right\rangle$, we have $\mathrm{D}=\mathrm{D}^{\prime}=\mathrm{L} \cap \mathrm{L}^{\prime}$.

We write compat $(\mathbb{G}, \mathbb{H})$ when there exists a continuation variable c such that $\operatorname{compat}_{c}(\mathbb{G}, \mathbb{H})$.

The composition is then defined as a reduction relation over pairs of compatible OGS configurations.

Definition 35 (Synchronization). We define the Synchronizing/Operational transition system $\mathcal{L}_{\text {so }}$ as the transition system whoses configurations are pairs of OGS compatible configurations, written $\left(\mathbb{G}_{1} \| \mathbb{G}_{2}\right)$, and whose reduction relation $\mapsto_{\mathrm{so}}$ is defined as $\mapsto_{\mathrm{so}}^{\mathrm{op}} \cup \mapsto_{\mathrm{so}}^{\text {sync }}$, where:

$$
\begin{aligned}
& \frac{\mathbb{G}_{1} \xrightarrow{\text { op }}_{\text {ogs }} \mathbb{H}_{1} \quad \operatorname{compat}\left(\mathbb{H}_{1}, \mathbb{G}_{2}\right)}{\left(\mathbb{G}_{1} \| \mathbb{G}_{2}\right) \mapsto_{\mathrm{so}}^{\mathrm{op}}\left(\mathbb{H}_{1} \| \mathbb{G}_{2}\right)} \quad \frac{\mathbb{G}_{2} \xrightarrow{\text { op }}_{\mathrm{ogs}} \mathbb{H}_{2} \quad \operatorname{compat}\left(\mathbb{G}_{1}, \mathbb{H}_{2}\right)}{\left(\mathbb{G}_{1} \| \mathbb{G}_{2}\right) \mapsto_{\mathrm{so}}^{\mathrm{op}}\left(\mathbb{G}_{1} \| \mathbb{H}_{2}\right)} \\
& \frac{\mathbb{G}_{1} \xrightarrow{\mathrm{~m}}{ }_{\mathrm{ogs}} \mathbb{H}_{1} \quad \mathbb{G}_{2} \xrightarrow{\overline{\mathrm{~m}}}{ }_{\mathrm{ogs}} \mathbb{H}_{2}}{\left(\mathbb{G}_{1} \| \mathbb{G}_{2}\right) \mapsto_{\mathrm{so}}^{\text {sync }}\left(\mathbb{H}_{1} \| \mathbb{H}_{2}\right)}
\end{aligned}
$$

While compatibility is preserved by $\mapsto_{\mathrm{so}}^{\mathrm{sync}}$, it is not necessarily by $\mapsto_{\mathrm{so}}^{\mathrm{op}}$. Indeed, taking $\mathbb{G}_{1}, \mathbb{H}_{1}$ two compatible OGS configurations, if $\mathbb{G}_{1} \xrightarrow{\text { op }}$ ogs $\mathbb{H}_{1}$, then this operational reduction could have allocated fresh locations that already exist in $\mathbb{G}_{2}$. This explains why we have to restrict to compatible configurations in the rules defining $\mapsto_{\mathrm{so}}^{\mathrm{op}}$. However, in such a case there exists always a configuration $\mathbb{H}_{1}^{\prime}$, equal to $\mathbb{H}_{1}$ up-to renaming of the fresh locations, and such that $\mathbb{G}_{1} \xrightarrow{\text { op }}$ ogs $\mathbb{H}_{1}^{\prime}$ and compat $\left(\mathbb{H}_{1}^{\prime}, \mathbb{G}_{2}\right)$.

Using the SO reduction relation we define a notion of observation as a barb [21].

Definition 36. We write $(\mathbb{I}|\mid \mathbb{J}) \Downarrow$ c when there exist two interactive configurations $\mathbb{I}, \mathbb{I}^{\prime}$ such that $\left(\mathbb{I}|\mid \mathbb{J}) \mapsto_{\mathrm{so}}^{*}\left(\mathbb{I}^{\prime}| | \mathbb{J}^{\prime}\right)\right.$ with $\mathbb{I}^{\prime}$ is a passive configuration of the shape $\left\langle\mathrm{S}_{\mathrm{P}} ; \gamma_{\mathrm{P}}\right\rangle$ and $\mathbb{J}^{\prime}$ of the shape $\left\langle[\mathrm{c}]() ; \mathrm{S}_{\mathrm{O}} ; \gamma_{\mathrm{O}}\right\rangle$. This definition can be directly lifted to OGS configurations.

This is used to define the following equivalence for OGS configurations.
Definition 37. Two configurations $\mathbb{G}_{1}, \mathbb{G}_{2}$ are said to be barbed equivalent, written $\mathbb{G}_{1} \simeq_{\text {barb }} \mathbb{G}_{2}$, when for all configuration $\mathbb{H}$ such that $\operatorname{compat}_{\mathrm{c}}\left(\mathbb{G}_{1}, \mathbb{H}\right)$ and $\operatorname{compat}_{\mathrm{c}}\left(\mathbb{G}_{2}, \mathbb{H}\right)$, we have $\left(\mathbb{G}_{1} \| \mathbb{H}\right) \Downarrow \mathrm{c}$ if and only if $\left(\mathbb{G}_{2} \| \mathbb{H}\right) \Downarrow \mathrm{c}$.

## A. 3 Adequacy

To prove that $\simeq_{\text {barb }}$ and $\simeq_{c t x}$ coincide, we introduce an intermediate transition system $\mathcal{L}_{\text {bop }}$, and we show that $\mathcal{L}_{\text {bop }}$ and $\mathcal{L}_{\text {SO }}\left(\mathcal{L}_{1}\right)$ are bisimilar, and that $\mathcal{L}_{\text {bop }}$ and the operational reduction relation are weakly bisimilar, ignoring the sync actions.
$\mathcal{L}_{\text {bop }}$ can be seen as an abstract machine to compute the interaction represented by $\mathcal{L}_{\mathrm{SO}}\left(\mathcal{L}_{1}\right)$. It relies on a notion of telescoped substitution, to avoid cycles in the concatenation of mappings coming from the composition of two interactive configurations. This enforces the absence of livelocks in the interaction.

Definition 38. $A$ telescoped substitution $\delta$ is a substitution seen as a list of mappings [ $n_{1} \mapsto \mathrm{~V}_{1}, \ldots, n_{k} \mapsto \mathrm{~V}_{k}$ ] such that for all $i \in\{1, \ldots, k\}$, we have $\operatorname{supp}\left(\mathrm{V}_{i}\right) \cap\left\{n_{i}, \ldots, n_{k}\right\}=\varnothing$.

A telescoped substitution $\delta$ can be transformed into a substitution $\delta^{*}$ that maps names to closed values.

Definition 39. Taking a telescoped substitution $\delta$ and $k \in \mathbb{N}^{*}$, we define the iterated telescoped substitution $\delta^{i}$ as:

$$
\delta^{1} \triangleq \delta \quad \delta^{i+1} \triangleq \Pi_{\mathrm{n} \in \operatorname{dom}(\delta)}\left[\mathrm{n} \mapsto \delta(\mathrm{n})\left\{\delta^{i}(\mathrm{n})\right\}\right]
$$

We then define $\delta^{*}$ as $\delta^{k}$ with $k$ the size of the domain of $\delta$. Then if $\Gamma \cdot \Delta \vdash \delta: \Gamma$, we have $\Delta \vdash \delta^{*}: \Gamma$.

Lemma 40. Taking $\delta$ a telescoped substitution and $\mathrm{n} \in \operatorname{dom}(\delta)$, then there exists a name $\mathrm{n} \in \operatorname{dom}(\delta)$ and a natural number $k \in \mathbb{N}^{*}$ such that $\delta^{k}(\mathrm{n})=\mathrm{m}$ and $\delta(\mathrm{m})$ is a value that is not a name in $\operatorname{dom}(\delta)$.

Definition 41. We introduce the boxed operational (bop) transition system $\mathcal{L}_{\text {bop }} \triangleq\left(\operatorname{Confs}_{\text {bop }}, \mapsto_{\text {bop }}\right)$ with configurations $\mathbb{A}, \mathbb{B} \in \operatorname{Confs}_{\text {bop }}$ of the shape $(\mathrm{M} ; \mathrm{S} ; \delta)$ with $\delta$ a telescoped substitution such that there exists a typing context $\Gamma$ and a store context $\Sigma$ with $\Sigma ; \Gamma \vdash \mathrm{M}: \perp, \Gamma \vdash \mathrm{S}: \Sigma$ and $\Sigma \vdash \delta: \Gamma$.

Its reduction relation $\mapsto_{\text {bop }}$ is given by the two reduction relations $\mapsto_{\text {bop }}^{\mathrm{op}}$ and $\mapsto \begin{gathered}\text { bync } \\ \text { bop }\end{gathered}$ defined in Figure 8.

$$
\begin{aligned}
& \text { op } \frac{(\mathrm{M} ; \mathrm{S}) \mapsto_{\mathrm{op}}(\mathrm{~N} ; \mathrm{T})}{\langle\mathrm{M} ; \mathrm{S} ; \delta\rangle \mapsto_{\mathrm{bop}}^{\mathrm{op}}\langle\mathrm{~N} ; \mathrm{T} ; \delta\rangle} \\
& \mathrm{PQ} \frac{\mathrm{~V} \not /(\mathrm{A} ; \gamma)}{\langle\mathrm{E}[\mathrm{fV}] ; \mathrm{S} ; \delta\rangle \mapsto_{\text {bop }}^{\text {sync }}\langle[\mathrm{c}] \delta(\mathrm{f}) \mathrm{A} ; \mathrm{S} ; \delta \cdot \gamma \cdot[\mathrm{c} \mapsto \mathrm{E}]\rangle} \quad \frac{\mathrm{V} \not /(\mathrm{A} ; \gamma)}{\langle[\mathrm{c}] \mathrm{V} ; \mathrm{S} ; \delta\rangle \mapsto_{\text {bop }}^{\text {sync }}\langle\delta(\mathrm{c})[\mathrm{A}] ; \mathrm{S} ; \delta \cdot \gamma\rangle} \mathrm{PA}
\end{aligned}
$$

Fig. 8. Definition of $\mathcal{L}_{\text {bop }}$

This transition system can be seen as an abstract machine, that performs a variant of the linear head reduction, which is known to be the way interaction in game semantics computes [8]. Having a global environment $\gamma$, it is similar to the Milner Abstract Machine [3].

We define a bisimulation between $\mapsto_{\text {bop }}$ and $\mapsto_{\text {op }}$ by collapsing $\mathcal{L}_{\text {bop }}$ configurations into operational ones.
Definition 42. We define the function $\Phi_{\mathrm{op}}^{\mathrm{bop}}: \mathrm{Confs}_{\mathrm{bop}} \rightarrow$ Terms $\times$ Stores as the function:

$$
(\mathrm{M} ; \mathrm{S} ; \delta) \mapsto\left(\mathrm{M}\left\{\delta^{*}\right\} ; \mathrm{S}\left\{\delta^{*}\right\}\right)
$$

It is direct to prove that $\Phi_{\mathrm{op}}^{\text {bop }}$ is invariant by $\mapsto_{\text {bop }}^{\text {sync }}$.
Lemma 43. If $\mathbb{A} \mapsto \mapsto_{\text {bop }}^{\text {sync }} \mathbb{B}$ then $\Phi_{\mathrm{op}}^{\text {bop }}(\mathbb{A})=\Phi_{\mathrm{op}}^{\text {bop }}(\mathbb{B})$.

Proof. Taking a value V such that V // $(\mathrm{A} ; \gamma)$ then:

$$
\begin{aligned}
(\delta(\mathrm{c})[\mathrm{A}])\left\{(\delta \cdot \gamma)^{*}\right\} & =(\delta(\mathrm{c})[\mathrm{A}\{\gamma\}])\left\{\delta^{*}\right\} \\
& =([\mathrm{c}] \mathrm{V})\left\{\delta^{*}\right\} \\
([\mathrm{c}] \delta(\mathrm{f}) \mathrm{A})\left\{(\delta \cdot \gamma \cdot[\mathrm{c} \mapsto \mathrm{E}])^{*}\right\} & =(\mathrm{E}[\delta(\mathrm{f})(\mathrm{A}\{\gamma\})])\left\{\delta^{*}\right\} \\
& =(\mathrm{E}[\mathrm{fV}])\{\delta\}
\end{aligned}
$$

Using the fact that the environment of bop configurations are telescoped, we deduce that such configurations can only perform a finite number of sync reduction steps, after which they have to perform an op reduction.

Lemma 44. Taking $\mathbb{A}$ a bop configuration, then there exists a configuration $\mathbb{B}$ such that $\mathbb{A}\left(\mapsto_{\text {bop }}^{\text {sync }}\right) * \mathbb{B}$ and $\mathbb{B} \notin \operatorname{dom}\left(\mapsto_{\text {bop }}^{\text {sync }}\right)$.

Proof. Suppose that $\mathbb{A} \in \operatorname{dom}\left(\mapsto_{\text {bop }}^{\text {sync }}\right)$. We write $\mathbb{A}$ as $\langle M ; S ; \gamma\rangle$, so that:

- either M is of the shape $\mathrm{E}[\mathrm{fV}]$ with $\mathrm{f} \in \operatorname{dom}(\gamma)$. Then from Lemma 40, there exists a natural number $k$ and a function name g such that $\gamma^{k}(\mathrm{f})=\mathrm{g}$ and $\gamma(\mathrm{g})$ is a value that is not a name in $\operatorname{dom}(\gamma)$. So $\gamma(\mathrm{g})$ must be a $\lambda$-abstraction. Then there exists a configuration $\mathbb{B}$ that can be written as $\left\langle\gamma(\mathrm{g}) \mathrm{A} ; \mathrm{T} ; \gamma \cdot \gamma^{\prime}\right\rangle$ such that $\mathbb{A}\left(\mapsto_{\text {bop }}^{\text {sync }}\right)^{*} \mathbb{B}$. Since $\gamma(\mathrm{g}) \mathrm{A}$ is not a normal form, we deduce that $\mathbb{B} \notin \operatorname{dom}\left(\mapsto_{\text {bop }}^{\text {syn }}\right)$.
- or M is of the shape [c]V with $c \in \operatorname{dom}(\gamma)$. Then a similar reasoning applies.

Lemma 45. Taking a bop configuration $\mathbb{A}=(M ; S ; \delta)$ such that $(M ; S) \mapsto_{o p}(N ; T)$, then $\Phi_{\text {op }}^{\text {bop }}(\mathbb{A}) \mapsto_{\text {op }} \Phi_{\text {op }}^{\text {bop }}(\langle\mathrm{N} ; \mathrm{T} ; \delta\rangle)$.

From Theorem 2, we deduce the following theorem.
Lemma 46. Taking M a term, S a store and $\gamma$ a substitution such that $\Sigma ; \Gamma \vdash \mathrm{M}$ : $\perp, \Gamma \vdash \mathrm{S}: \Sigma$ and $\Sigma ; \varnothing \vdash \gamma: \Gamma$, if $(\mathrm{M}\{\gamma\} ; \mathrm{S}\{\gamma\}) \mapsto_{\mathrm{op}}(\mathrm{N} ; \mathrm{T})$ then:

- either there exists $\tilde{\mathrm{N}}, \tilde{\mathrm{T}}$ such that $(\mathrm{M} ; \mathrm{S}) \mapsto_{\mathrm{op}}(\tilde{\mathrm{N}} ; \tilde{\mathrm{T}})$ with $\tilde{\mathrm{N}}\{\gamma\}=\mathrm{N}$ and $\tilde{\mathrm{T}}\{\gamma\}=\mathrm{T}$,
- or M is of the shape $\mathrm{E}[\mathrm{fV}]$ with $\mathrm{f} \in \operatorname{dom}(\gamma)$,
- or M is of the shape [c]V with $\mathrm{c} \in \operatorname{dom}(\gamma)$.

Lemma 47. Taking $\mathbb{A} a$ bop configuration such that $\Phi_{\mathrm{op}}^{\mathrm{bop}}(\mathbb{A}) \mapsto_{\mathrm{op}}(\mathrm{N} ; \mathrm{T})$ and $\mathbb{A} \notin \operatorname{dom}\left(\mapsto_{\text {bop }}^{\text {sync }}\right)$, then there exists a bop configuration $\mathbb{B}$ such that $\mathbb{A} \mapsto_{\text {bop }}^{\mathrm{op}} \mathbb{B}$ and $\Phi_{\mathrm{op}}^{\mathrm{bop}}(\mathbb{B})=(\mathrm{N} ; \mathrm{T})$.

Proof. We write $\mathbb{A}$ as $\langle\mathrm{M} ; \mathrm{S} ; \delta\rangle$. Since $\mathbb{A} \notin \operatorname{dom}\left(\mapsto_{\text {bop }}^{\text {sync }}\right)$, we get that $M$ cannot be of the shape $\mathrm{E}[\mathrm{fV}]$ with $\mathrm{f} \in \operatorname{dom}(\delta)$, or of the shape $[\mathrm{c}] \mathrm{V}$ with $\mathrm{c} \in \operatorname{dom}(\delta)$. We conclude using Lemma 46.

From this, we deduce that $\Phi_{\mathrm{op}}^{\mathrm{bop}}$ is a functional bisimulation, that is a bisimulation relation that is functional.

Lemma 48. Writing $\mapsto_{\text {bop }}^{\mathrm{op}}$ for $\left(\mapsto_{\text {bop }}^{\text {sync }}\right)^{*} \mapsto_{\text {bop }}^{\mathrm{op}}$, then $\Phi_{\mathrm{op}}^{\mathrm{bop}}$ is a functional bisimulation between $\left(\right.$ Confs $_{\text {bop }},{ }_{\text {bop }}^{\mathrm{op}}$ ) and (Terms $\times$ Stores, $\mapsto_{\mathrm{op}}$ ).

Proof. Taking $\mathbb{A}$ a bop configuration, suppose that there exists ( $\mathrm{N} ; \mathrm{T}$ ) such that $\Phi_{\mathrm{op}}^{\text {bop }}(\mathbb{A}) \mapsto_{\mathrm{op}}(\mathrm{N} ; \mathrm{T})$. From Lemma 44, there exists a bop configuration $\mathbb{B}$ such that $\mathbb{A}\left(\mapsto_{\text {bop }}^{\text {sync }}\right)^{*} \mathbb{B}$ and $\mathbb{B} \notin \operatorname{dom}\left(\mapsto_{\text {bop }}^{\text {sync }}\right)$. From Lemma 43 , we get that $\Phi_{\text {op }}^{\text {bop }}(\mathbb{A})=$ $\Phi_{\text {op }}^{\text {bop }}(\mathbb{B})$. Then from Lemma 47 , we get that there exists a bop configuration $\mathbb{B}^{\prime}$ such that $\mathbb{B} \mapsto_{\text {bop }}^{\mathrm{op}} \mathbb{B}^{\prime}$ and $\Phi_{\mathrm{op}}^{\mathrm{bop}}\left(\mathbb{B}^{\prime}\right)=(\mathrm{N} ; \mathrm{T})$.

Suppose now that $\mathbb{A} \mapsto_{\text {bop }}^{\text {op }}\left(\mathrm{N} ; \mathrm{T} ; \delta^{\prime}\right)$. Writing $\mathbb{A}$ as $(\mathrm{M} ; \mathrm{S} ; \delta)$, we have $(\mathrm{M} ; \mathrm{S}) \mapsto_{\mathrm{op}}$ $(\mathrm{N} ; \mathrm{T})$ with and $\delta^{\prime}=\delta$. Then from Lemma 45 we have $\Phi_{\mathrm{op}}^{\mathrm{bop}}(\mathbb{A}) \mapsto_{\mathrm{op}} \Phi_{\mathrm{op}}^{\mathrm{bop}}\left(\mathrm{N} ; \mathrm{T} ; \delta^{\prime}\right)$.

We now establish a bisimulation between $\mathcal{L}_{\text {SO }}$ and $\mathcal{L}_{\text {bop }}$.
Definition 49. We define the function $\mathcal{R}_{\text {bop }}^{\text {so }}: \operatorname{Confs}_{\text {so }} \rightarrow \operatorname{Confs}_{\text {bop }}$ as
$\left\{\left(((\mathbb{I} ; \mathbb{S} ; \mathbb{D}) \|(\mathbb{J} ; \mathbb{T} ; \mathbb{E})),\left(\mathrm{M} ; \mathrm{S}_{\mathrm{P}} \cup \mathrm{S}_{\mathrm{O}} ; \delta\right)\right) \mid \delta\right.$ a telescoped substitution of $\left.\gamma_{\mathrm{P}} \cdot \gamma_{\mathrm{O}}\right\}$
with $\mathbb{I}=\left\langle\mathrm{M} ; \mathrm{S}_{\mathrm{P}} ; \gamma_{\mathrm{P}}\right\rangle$ and $\mathbb{J}=\left\langle\mathrm{S}_{\mathrm{O}} ; \gamma_{\mathrm{O}}\right\rangle$, or $\mathbb{I}=\left\langle\mathrm{S}_{\mathrm{P}} ; \gamma_{\mathrm{P}}\right\rangle$ and $\mathbb{J}=\left\langle\mathrm{M} ; \mathrm{S}_{\mathrm{O}} ; \gamma_{\mathrm{O}}\right\rangle$.
Notice that $S_{P} \cup S_{O}$ is well-formed in this definition thanks to the fact that $\mathbb{I}$ and $\mathbb{J}$ are compatible, being part of a SO configuration.

In order to prove that $\mathcal{R}_{\text {bop }}^{\text {so }}$ is a bisimulation, we prove in the following lemma that an Opponent configuration can always perform an action as soon as a compatible Player configuration can perform the dual action.

Lemma 50. Taking $\mathbb{G}, \mathbb{H}$ two OGS configurations such that compat $(\mathbb{G}, \mathbb{H})$, for all Proponent action $\mathbf{p}$, if $\mathbb{G} \xrightarrow{\mathbf{p}}{ }_{\mathrm{ogs}} \mathbb{G}^{\prime}$, then there exists a configuration $\mathbb{H}^{\prime}$ s.t. $\mathbb{H} \xrightarrow{\overline{\mathrm{p}}}{ }_{\text {ogs }} \mathbb{H}^{\prime}$ and compat $\left(\mathbb{G}^{\prime}, \mathbb{H}^{\prime}\right)$.

Proof. From the fact that there exists c such that compat $_{c}(\mathbb{G}, \mathbb{H})$, we can write:

- $\mathbb{G}$ as $\left(\left\langle\mathrm{M} ; \mathrm{SP}_{\mathrm{P}} ; \gamma_{\mathrm{P}}\right\rangle ;\left\langle\Delta_{\mathrm{O}} \mid \perp ; \Delta_{\mathrm{P}}\right\rangle ;\langle\mathrm{L} ; \mathrm{D}\rangle\right) ;$
$-\mathbb{H}$ as $\left(\left\langle\mathrm{S}_{\mathrm{O}} ; \gamma_{\mathrm{O}}\right\rangle ;\left\langle\Delta_{\mathrm{P}}, \mathrm{c}: \neg\right.\right.$ Unit $\left.\left.\mid \Delta_{\mathrm{O}}\right\rangle ;\left\langle\mathrm{L}^{\prime} ; \mathrm{D}\right\rangle\right)$.
Then either $\mathbf{p}$ is a question of the shape $\overline{\mathrm{f}}(\mathrm{A})$ with $\Delta_{\mathrm{O}}(\mathrm{f})=\sigma \rightarrow \tau$, or an answer of the shape $\overline{\mathrm{c}}(\mathrm{A})$ with $\Delta_{\mathrm{O}}(\mathrm{c})=\neg \sigma$.

There exists a typing context $\Delta$ disjoint from $\Delta_{\mathrm{P}}$ and $\Delta_{\mathrm{O}}$ such that $\Delta \Vdash \mathrm{A}: \sigma$
 $\left\langle\Delta, \Delta_{\mathrm{P}}, \mathrm{c}: \neg\right.$ Unit $\left.\mid \Delta_{\mathrm{O}}\right\rangle$.

From the fact that $\mathbb{G}$ is valid, we get that there exists a store typing context $\Sigma_{P}$ such that $\operatorname{dom}\left(\Sigma_{P}\right)=L$ and $\Sigma_{P} ; \Delta_{\mathrm{O}} \vdash \mathrm{M}: \perp$. By analysis of the action $\mathbf{p}$ generated by $M$, we then have $\operatorname{supp}(\mathbf{p}) \subseteq L$. Since $D=L \cap L^{\prime}$ and $\operatorname{supp}(\mathbf{p})=\operatorname{supp}(\overline{\mathbf{p}})$, we get that $\mathrm{L}^{\prime} \cap \operatorname{supp}(\overline{\mathbf{p}}) \subseteq \mathrm{L}^{\prime} \cap \mathrm{L}=\mathrm{D}$. We then have $\left\langle\mathrm{L}^{\prime} ; \mathrm{D}\right\rangle \xrightarrow{\overline{\mathbf{p}}} \mathrm{Di}\left\langle\mathrm{L}^{\prime} \cup \operatorname{supp}(\overline{\mathbf{p}}) ; \operatorname{D} \cup \operatorname{supp}(\overline{\mathbf{p}})\right\rangle$ and $\langle\mathrm{L} ; \mathrm{D}\rangle \xrightarrow[\mathrm{p}]{\mathrm{Di}}_{\mathbf{p}}\langle\mathrm{L} ; \operatorname{D} \cup \operatorname{supp}(\mathbf{p})\rangle$. And indeed, $\mathrm{L} \cap\left(\mathrm{L}^{\prime} \cup \operatorname{supp}(\overline{\mathbf{p}})\right)=\left(\mathrm{L} \cap \mathrm{L}^{\prime}\right) \cup \operatorname{supp}(\overline{\mathbf{p}})=$ $\mathrm{D} \cup \operatorname{supp}(\mathbf{p})$.

Lemma 51. $\mathcal{R}_{\text {bop }}^{\text {so }}$ is a bisimulation between $\mathcal{L}_{\text {so }}$ and $\mathcal{L}_{\text {bop }}$.
Proof. We take $((\mathbb{G} \| \mathbb{H}), \mathbb{A}) \in \mathcal{R}_{\text {bop }}^{\text {so }}$. Without loss of generality, suppose that $\mathbb{G}$ is the active configuration. So we write:

- $\mathbb{G}$ as $(\mathbb{I} ; \mathbb{S} ; \mathbb{D})$,
$-\mathbb{H}$ as $(\mathbb{J} ; \mathbb{T} ; \mathbb{E})$,
$-\mathbb{I}$ as $\left\langle M ; S_{P} ; \gamma_{P}\right\rangle$
$-\mathbb{J}$ as $\left\langle\mathrm{S}_{\mathrm{O}} ; \gamma_{\mathrm{O}}\right\rangle$,
- $\mathbb{A}$ as $\left(\mathrm{M} ; \mathrm{SP}_{\mathrm{P}} \cup \mathrm{S}_{\mathrm{O}} ; \delta\right)$, with $\delta$ a telescoped substitution of $\gamma_{\mathrm{P}} \cdot \gamma_{\mathrm{O}}$.

First, suppose $(\mathbb{G} \| \mathbb{H}) \mapsto_{\text {so }} \mathbf{a}\left(\mathbb{G}^{\prime}| | \mathbb{H}^{\prime}\right)$. There are two possible cases:

- either $\mathbf{a}=o p$ and $\mathbb{G} \xrightarrow{\text { op }}{ }_{o g s}\left\langle M^{\prime} ; S_{P}^{\prime}, \gamma_{P}\right\rangle$ and $\mathbb{H}=\mathbb{H}^{\prime}$. Since $\mathbb{G}^{\prime}$ is compatible with $\mathbb{H}$, we deduce that new locations allocated in $S_{p}^{\prime}$ cannot be in $S_{O}$, so that $\mathrm{S}_{\mathrm{P}}^{\prime} \cup \mathrm{S}_{\mathrm{O}}$ is well-defined. Then writing $\mathbb{B}$ as $\left(\mathrm{M}^{\prime} ; \mathrm{S}_{\mathrm{P}}^{\prime} \cup \mathrm{S}_{\mathrm{O}} ; \delta\right)$, we have $\mathbb{A} \mapsto_{\text {bop }}^{\mathrm{op}} \mathbb{B}$ and $\left(\left(\mathbb{G}^{\prime}| | \mathbb{H}\right), \mathbb{B}\right) \in \mathcal{R}_{\text {bop }}^{\text {so }}$.
- or $\mathbf{a}=$ sync so there exists a Proponent move $\mathbf{m}$ such that $\mathbb{G} \xrightarrow{\mathbf{m}}$ ogs $\mathbb{G}^{\prime}$ and $\mathbb{H} \xrightarrow{\overline{\mathrm{m}}}{ }_{\text {ogs }} \mathbb{H}^{\prime}$. We then have $\mathbb{G}^{\prime}=\left(\left\langle\mathrm{S}_{\mathrm{P}} ; \gamma_{\mathrm{P}} \cdot \gamma^{\prime}\right\rangle ; \_;-\right)$and $\mathbb{H}^{\prime}=\left(\left\langle\mathrm{M}^{\prime} ; \mathrm{S}_{\mathrm{O}} ; \gamma_{\mathrm{O}}\right\rangle ;-;{ }_{-}\right)$. $\gamma^{\prime} \cdot \delta$ is a telescoped substitution, so that, defining $\mathbb{B}$ as $\left\langle\mathrm{M}^{\prime} ; \mathrm{S}_{\mathrm{P}} \cup \mathrm{S}_{\mathrm{O}} ; \gamma^{\prime} \cdot \delta\right\rangle$, we have $\mathbb{A} \mapsto_{\text {bop }}^{\text {op }} \mathbb{B}$ and $\left(\left(\mathbb{G}^{\prime}| | \mathbb{H}\right), \mathbb{B}\right) \in \mathcal{R}_{\text {bop }}^{\text {so }}$.
Now suppose that $\mathbb{A} \mapsto_{\text {bop }} \mathbb{B}$, and we write $\mathbb{A}$ as $(M ; S ; \delta)$. There are three possible cases:
- either $\mathbf{a}=$ sync and M is of the shape $\mathrm{E}[f \mathrm{~V}]$, and there exists a reduction $\mathrm{V} \not{/}(\mathrm{A} ; \gamma)$ such that $\mathrm{N}=\delta(f) \mathrm{A}$ and $\delta^{\prime}=\gamma \cdot \delta$. Then writing $\mathbf{m}$ for $\bar{f}(\mathrm{~A})$, we have the existence of $\mathbb{G}^{\prime}$ such that $\mathbb{G} \xrightarrow{\mathbf{m}}$ ogs $\mathbb{G}^{\prime}$. From Lemma 50, we get that there exists $\mathbb{H}^{\prime}$ such that $\mathbb{H} \xrightarrow{\bar{m}}$ ogs $\mathbb{H}^{\prime}$ and $\left(\left(\mathbb{G}^{\prime}| | \mathbb{H}^{\prime}\right), \mathbb{B}\right) \in \mathcal{R}_{\text {bop }}^{\text {so }}$.
- or $\mathbf{a}=$ sync and $M$ is a named value $[\mathrm{c}] \mathrm{V}$, and there exists a reduction $\mathrm{V} \mathbb{\nabla}(\mathrm{A} ; \gamma)$ such that $\mathrm{N}=\gamma_{\mathrm{O}}(\mathrm{C})[\mathrm{A}]$, and $\delta^{\prime}=\gamma \cdot \delta$. Then writing $\mathbf{m}$ for $\overline{\mathrm{C}}(\mathrm{A})$, we have the
 get that there exists $\mathbb{H}^{\prime}$ such that $\mathbb{H} \xrightarrow{\bar{m}}{ }_{\text {ogs }} \mathbb{H}^{\prime}$ and $\left(\left(\mathbb{G}^{\prime} \| \mathbb{H}^{\prime}\right), \mathbb{B}\right) \in \mathcal{R}_{\text {bop }}^{\text {so }}$.
- or $\mathbf{a}=\mathrm{op},(\mathrm{M}, \mathrm{S}) \mapsto_{\mathrm{op}}(\mathrm{N}, \mathrm{T})$ and $\delta^{\prime}=\delta$. From the fact that $\mathbb{I}$ is validated by $\mathbb{S}$, we get that there exists a store $\Sigma_{P}$ such that $\vdash S_{P}: \Sigma_{P}$ and $\Sigma_{P} ; \Delta_{O} \vdash M: \perp$. We deduce that there exists a store $\mathrm{T}^{\prime}$ such that $\left(\mathrm{M}, \mathrm{Sp}_{\mathrm{p}}\right) \mapsto_{\mathrm{op}}(\mathrm{N}, \mathrm{T})$ and $\mathrm{T}=\mathrm{T}^{\prime} \cup \mathrm{S}_{\mathrm{o}}$. We define $\mathbb{I}^{\prime}$ as $\left\langle N ; T^{\prime} ; \gamma_{P}\right\rangle$, and $\mathbb{G}^{\prime}$ as $\left(\mathbb{I}^{\prime} ; \mathbb{S} ; \mathbb{D}\right)$. Then $\mathbb{G} \xrightarrow{\text { op }}$ ogs $\mathbb{G}^{\prime}$ and $\mathbb{G}^{\prime}$ is compatible with $\mathbb{H}$. So $(\mathbb{G} \| \mathbb{H}) \mapsto_{\text {so }}^{\text {op }}\left(\mathbb{G}^{\prime}| | \mathbb{H}\right)$ and $\left(\left(\mathbb{G}^{\prime}| | \mathbb{H}\right), \mathbb{B}\right) \in \mathcal{R}_{\text {bop }}^{\text {so }}$.
Combining Lemma 48 and 51, we deduce that the collapse

$$
\begin{aligned}
\Phi_{\mathrm{op}}^{\text {so }}: \mathrm{Confs}_{\text {so }} & \rightarrow \text { Terms } \times \text { Stores } \\
((\mathbb{I} ; \mathbb{S} ; \mathbb{D}) \|(\mathbb{J} ; \mathbb{T} ; \mathbb{E})) & \mapsto\left(\mathrm{M}\left\{\delta^{*}\right\} ; \mathrm{S}\left\{\delta^{*}\right\}\right)
\end{aligned}
$$

with $\mathbb{I}=\left\langle\mathrm{M} ; \mathrm{S}_{\mathrm{P}} ; \gamma_{\mathrm{P}}\right\rangle$ and $\mathbb{J}=\left\langle\mathrm{S}_{\mathrm{O}} ; \gamma_{\mathrm{O}}\right\rangle$, or $\mathbb{I}=\left\langle\mathrm{S}_{\mathrm{P}} ; \gamma_{\mathrm{P}}\right\rangle$ and $\mathbb{J}=\left\langle\mathrm{M} ; \mathrm{S}_{\mathrm{O}} ; \gamma_{\mathrm{O}}\right\rangle$, and $\delta$ a telescoped substitution of $\gamma_{\mathrm{P}} \cdot \gamma_{\mathrm{O}}$, is a functional bisimulation

This provides us the following adequacy result between the observation used to define $\simeq_{\text {barb }}$ and the one to define $\simeq_{c i u}$.

Theorem 52. Taking $\mathbb{G}, \mathbb{H}$ two compatible configurations, then $(\mathbb{G} \mid \mathbb{H}) \Downarrow$ c if and only if $\Phi_{\mathrm{op}}^{\mathrm{so}}\left(\left(\mathbb{G}_{i} \| \mathbb{H}\right)\right) \Downarrow[\mathrm{c}]()$.

Theorem 53. $\left\langle\Sigma ; \Gamma \vdash \mathrm{M}_{1}: \sigma\right\rangle \simeq_{\text {barb }}\left\langle\Sigma ; \Gamma \vdash \mathrm{M}_{2}: \sigma\right\rangle$ iff $\Sigma ; \Gamma \vdash \mathrm{M}_{1} \simeq_{c i u} \mathrm{M}_{2}: \sigma$.
Proof. Let us write $\mathbb{G}_{i}$ for $\left\langle\Sigma ; \Gamma \vdash \mathrm{M}_{i}: \sigma\right\rangle$, with $i \in\{1,2\}$.

From barb to ciu We first suppose that $\mathbb{G}_{1} \simeq_{\text {barb }} \mathbb{G}_{2}$. We consider:

- a store typing context $\Sigma^{\prime} \supseteq \Sigma$;
- a substitution $\gamma$ such that $\Sigma^{\prime} ; d: \neg \mathrm{b} \vdash \gamma: \Gamma$;
- a store S such that $\vdash \mathrm{S}: \Sigma^{\prime}$.

We write $\mathbb{H}$ for $\left\langle\Sigma^{\prime} ; d: \neg\right.$ Unit $\left.\vdash(\mathrm{S} ; \gamma): \Gamma\right\rangle$. Then for $i \in\{1,2\}$ we have $\Phi_{\mathrm{op}}^{\mathrm{so}}\left(\left(\mathbb{G}_{i} \| \mathbb{H}\right)\right)=\left(\mathrm{M}_{i}\{\gamma\}, \mathrm{S}\right)$.

Taking $i \in\{1,2\}$ Suppose that $\left(M_{i}\{\gamma\}, S\right) \Downarrow[d]()$. Then from Theorem 52 , we get that $\left(\mathbb{G}_{i} \| \mathbb{H}\right) \Downarrow d$. From $\mathbb{G}_{1} \simeq_{\text {barb }} \mathbb{G}_{2}$, taking $j \triangleq\left\{\begin{array}{l}1 \text { if } i=2 \\ 2 \text { if } i=1\end{array}\right.$, we get that $\left(\mathbb{G}_{j} \| \mathbb{H}\right) \Downarrow d$. So from Theorem 52 , we get that $\left(\mathrm{M}_{j}\{\gamma\}, \mathrm{S}\right) \Downarrow[d]()$, i.e. $\Sigma ; \Gamma \vdash$ $\mathrm{M}_{1} \simeq{ }_{c i u} \mathrm{M}_{2}: \sigma$.

From ciu to barb Suppose now that $\Sigma ; \Gamma \vdash \mathrm{M}_{1} \simeq_{\text {ciu }} \mathrm{M}_{2}: \sigma$. We take an OGS configuration $\mathbb{H}=(\mathbb{I} ; \mathbb{S} ; \mathbb{D})$ such that for all $i \in\{1,2\}$, $\boldsymbol{c o m p a t}_{\mathrm{c}}\left(\mathbb{G}_{i}, \mathbb{H}\right)$. Then by definition $\mathbb{H}=\left\langle c: \neg\right.$ Unit $\left.\vdash(\mathrm{S} ; \gamma):\left(\Sigma^{\prime} ; \Gamma\right)\right\rangle$.

Then for $i \in\{1,2\}$ we have $\Phi_{\mathrm{op}}^{\text {so }}\left(\left(\mathbb{G}_{i} \| \mathbb{H}\right)\right)=\left(\mathrm{M}_{i}\{\gamma\}, \mathrm{S}\right)$. We conclude from $\Sigma ; \Gamma \vdash \mathrm{M}_{1} \simeq_{c i u} \mathrm{M}_{2}: \sigma$, using again Theorem 52 in both directions.

## A. 4 Relating barbed equivalence and traces equivalence

We now prove that trace equivalence and barbed equivalence coincide. To do so, we express the barb observation $(\mathbb{G} \| \mathbb{H}) \Downarrow$ c of $\mathcal{L}_{\text {SO }}$ as the existence of traces ending with $\overline{\mathrm{c}}(())$.

Definition 54. We write $(\mathbb{G}, \mathbb{H}) \in \Perp_{c}$ when there exists a trace $\mathbf{t}$ such that $\mathbf{t} \in \operatorname{Tr}_{\mathcal{L}_{\text {OGS }}}(\mathbb{G})$ and $\overline{\mathbf{t}} \overline{\mathrm{c}}(()) \in \operatorname{Tr}_{\mathcal{L}_{\text {OGS }}}(\mathbb{H})$.

By definition, this notion of observation is preserved by trace equivalence:
Lemma 55. If $(\mathbb{G}, \mathbb{H}) \in \Perp_{c}$ and $\mathbb{G} \simeq_{\operatorname{tr}} \mathbb{G}^{\prime}$ then $\left(\mathbb{G}^{\prime}, \mathbb{H}\right) \in \Perp_{c}$.
It is also closed by antireduction.
Lemma 56. Taking $(\mathbb{G} \| \mathbb{H})$ and $\left(\mathbb{G}^{\prime}| | \mathbb{H}^{\prime}\right)$ two SO configurations such that $(\mathbb{G} \| \mathbb{H}) \mapsto_{\text {so }}$ $\left(\mathbb{G}|\mid \mathbb{H})\right.$ and $\left(\mathbb{G}^{\prime}| | \mathbb{H}^{\prime}\right) \in \Perp_{c}$, then $\left(\mathbb{G}|\mid \mathbb{H}) \in \Perp_{c}\right.$.

This trace predicate coincides with termination:
Lemma 57. $(\mathbb{G}, \mathbb{H}) \in \Perp_{c}$ if and only if $(\mathbb{G}|\mid \mathbb{H}) \Downarrow c$.

Proof. First suppose that $(\mathbb{G}, \mathbb{H}) \in \Perp_{c}$, that is there exists a trace $\mathbf{t}$ such that $\mathbf{t} \in \operatorname{Tr}_{\mathcal{L}_{\text {OGS }}}(\mathbb{G})$ and $\overline{\mathbf{t}} \overline{\mathrm{c}}(()) \in \operatorname{Tr}_{\mathcal{L}_{\text {OGS }}}(\mathbb{H})$. We reason by induction on the length of t to prove that $(\mathbb{G}|\mid \mathbb{H}) \Downarrow c$, using the fact that $\Downarrow$ is closed by anti-reduction of $\mapsto_{\mathrm{so}}$. When this trace is empty, we have $\mathbb{G}=\left\langle\mathrm{S}_{\mathrm{P}}, \gamma_{\mathrm{P}}\right\rangle$ and $\mathbb{H}=\left\langle[\mathrm{c}]() ; \mathrm{S}_{\mathrm{O}} ; \gamma_{\mathrm{O}}\right\rangle$. So $(\mathbb{G}|\mid \mathbb{H}) \Downarrow c$.

Next, we suppose the following reduction:

$$
(\mathbb{G} \| \mathbb{H}) \mapsto_{\mathrm{so}}^{*}\left(\left\langle\mathrm{~S}_{\mathrm{P}} ; \gamma_{\mathrm{P}}\right\rangle \|\left\langle() ; \mathrm{S}_{\mathrm{O}} ; \gamma_{\mathrm{O}}\right\rangle\right)
$$

We reason by induction over the length of this reduction, using the fact that $\Perp_{c}$ is closed by anti-reduction of $\mapsto_{\text {so }}$ (Lemma 56). When this reduction is empty, we conclude using the fact that $\left\langle[\mathrm{c}]() ; \mathrm{S}_{\mathrm{O}} ; \gamma_{\mathrm{O}}\right\rangle \xrightarrow{\overline{\mathrm{c}}(())}{ }_{\mathrm{ogs}}\left\langle\mathrm{S}_{\mathrm{O}} ; \gamma_{\mathrm{O}}\right\rangle$.

Combining Lemma 57 and 55, we prove the soundness of trace equivalence.
Theorem 58. Taking $\mathbb{G}, \mathbb{H}$ two $O G S$ configurations, if $\mathbb{G} \simeq_{\operatorname{tr}} \mathbb{H}$ then $\mathbb{G} \simeq_{\text {barb }} \mathbb{H}$.
In order to prove full abstraction, the opposite direction, we rely on a definability result over traces.

Definition 59. We say that an OGS LTS is O-definable when taking a trace $\mathbf{t} \in \operatorname{Tr}_{\mathrm{ogs}}(\mathbb{G})$ with $\mathbb{G}$ prime, there exists a configuration $\mathbb{H}$ and a continuation name c such that compat ${ }_{\mathrm{c}}(\mathbb{G}, \mathbb{H})$ and $\operatorname{Tr}_{\mathrm{OGS}}(\mathbb{H})=\left\{\mathbf{t}^{\prime} \mid \mathbf{t}^{\prime} \sim \overline{\mathbf{t}} \overline{\mathrm{c}}(())\right\}$.

Theorem 60. Considering an OGS LTS satisfying the O-definable condition, and taking $\mathbb{G}, \mathbb{H}$ two OGS configurations, if $\mathbb{G} \simeq_{\text {barb }} \mathbb{H}$ then $\mathbb{G} \simeq_{\mathrm{tr}} \mathbb{H}$.

In the next section, we will prove that $\mathcal{L}_{\text {OGS }}$ is $O$-definable. Combining this result with Theorems $32,53,58$ and 60 , we deduce Theorem 7 stating the correspondence between trace equivalence and contextual equivalence.

## A. 5 Definability

To prove full abstraction of trace equivalence, we need to be able to define a program that generates a given trace.

Given such a trace $\mathbf{t}$, we suppose given a function that maps all the function names f , continuations names c , and atoms appearing in $\mathbf{t}$ to locations $\ell_{\mathrm{f}}, \ell_{\mathrm{c}}$ and $\ell_{\mathrm{a}}$. These locations are then used to store all these names. To enforce that the moves appear in the right order, we use a clock implemented via a reference clock.

To build code from a given trace, we reason inductively on the tree structure inherited from the justification structure over the trace.

Definition 61. Taking a trace of the shape $\mathbf{t} \mathbf{m} \mathbf{t}_{1} \mathbf{n} \mathbf{t}_{2}$ we say that $\mathbf{m}$ is justified by $\mathbf{n}$ when $\mathbf{m}$ is a question over a function name f or an answer of a continuation name $\mathbf{c}$, that is bound in $\mathbf{n}$.

This tree structure corresponds to the Lassen trees generated by the POGS LTS.

Definition 62. Taking an execution trace

$$
\mathbf{t}=\left(\mathbb{G}_{1}, \mathbb{S}_{1},\left\langle_{-}, \mathrm{D}_{1}\right\rangle\right) \xrightarrow{\mathbf{m}_{1}} \mathrm{ogs}^{\mathrm{og}}\left(\mathbb{G}_{2}, \mathbb{S}_{2},\left\langle_{-}, \mathrm{D}_{2}\right\rangle\right) \ldots{\xrightarrow{\mathbf{m}_{k}}}_{\mathrm{ogs}}\left(\mathbb{G}_{k+1}, \mathbb{S}_{k+1},\left\langle_{-}, \mathrm{D}_{k+1}\right\rangle\right)
$$

we associate the view-tree viewtree $(\mathbf{t})$ whose nodes are triples $\left(i, \mathbb{S}_{i}, \mathrm{D}_{i}\right)_{i \in\{1, \ldots, k\}}$, and such that $\left(i, \mathbb{S}_{i}, \mathrm{D}_{i}\right) \xrightarrow{\mathbf{m}}\left(k, \mathbb{S}_{k}, \mathrm{D}_{k}\right)$ when $\mathbf{m}=\mathbf{m}_{k}$ and:

- either $\mathbf{m}_{k}$ is an Opponent move justified by $\mathbf{m}_{j}$;
- or $\mathbf{m}_{k}$ is a Proponent move and $k=j+1$.

To a configuration $\left(i,\left\langle\left.\Delta_{\mathrm{O}}\right|_{-}\right\rangle, \mathrm{D}\right)$ of a view tree, we associate the store $\mathrm{S}_{i}$ defined as:

$$
[\mathrm{clock} \mapsto i] \cdot \odot_{\mathrm{f} \in \operatorname{dom}\left(\Delta_{\mathrm{o}}\right)}\left[\ell_{\mathrm{f}} \mapsto \mathrm{f}\right] \cdot \odot_{\mathrm{c} \in \operatorname{dom}\left(\Delta_{\mathrm{o}}\right)}\left[\ell_{\mathrm{c}} \mapsto \mathrm{c}\right] \cdot \odot_{\mathrm{a} \in \mathrm{D}}\left[\ell_{\mathrm{a}} \mapsto \mathrm{a}\right]
$$

To a variable $x$ and an abstract value A, we associate the following terms set $_{x, \mathrm{~A}}$ and get $_{\mathrm{A}}$, defined by case analysis over A:

$$
\begin{array}{lll}
\operatorname{set}_{x, \mathrm{f}} \triangleq \ell_{\mathrm{f}}:=x & \operatorname{get}_{\mathrm{f}} \triangleq() \\
\operatorname{set}_{x, v \mathrm{a}} \triangleq \ell_{\mathrm{a}}:=x & \operatorname{get}_{v \mathrm{a}} \triangleq() \\
\operatorname{set}_{x, \mathrm{a}} \triangleq x & \operatorname{get}_{\mathrm{a}} \triangleq!\ell_{\mathrm{a}} \\
\operatorname{set}_{x,()} \triangleq x & \operatorname{get}_{()} \triangleq() \\
\operatorname{set}_{x, \text { true }} \triangleq x & \operatorname{get}_{\text {true }} \triangleq \mathrm{true} & \operatorname{get}_{\text {false }} \triangleq \mathrm{false}
\end{array}
$$

Proving definability means building a prime Interactive configuration $\mathbb{P}$ such that the only "successful" interaction of $\mathbb{P}$ is represented by $\mathcal{T}$ (up-to renaming).

Theorem 63. Taking $\mathbb{S}$ an active prime Ty configuration, с a continuation name, and $\mathcal{T} \in \mathbf{V T}(\mathbb{S})$ a view-tree, there exists a Prime Interactive configuration $\mathbb{P}$ such that $\mathbb{P} \triangleright \mathbb{S}^{*}{ }^{c}$ and $\mathbf{V T}\left(\mathbb{P} ; \mathbb{S}^{*}{ }^{*}\right)=\left\{\mathcal{T}^{\prime} \mid \mathcal{T}^{\prime}=\pi * \mathcal{T}, \pi\right.$ a finite permutation $\}$.

Proof. By induction on the tree structure of $\mathcal{T}$.
For the induction step, we consider the tree generated by the LTS from the configuration $\mathbb{P}_{\mathrm{P}}$, represented by the following paths: $\mathbb{P}_{\mathrm{P}} \xrightarrow{(\mathbf{p} ; h)} \mathrm{PI} \mathbb{P}_{\mathrm{O}} \xrightarrow{\left(\boldsymbol{o}_{i} ; j_{i}\right)} \mathrm{PI}$ $\mathbb{P}_{i} \Downarrow_{\mathrm{op}} \mathbb{P}_{\mathrm{P}, i}$ for $i \in\{1, \ldots, k\}$. We write $\mathbb{P}_{\mathrm{P}, i}$ as $\left\langle\mathrm{M}_{i}, \mathrm{~S}_{j_{i}}\right\rangle$.

Taking the function name f introduced in $\mathbf{p}$, we consider all the occurrences $\mathbf{o}_{i_{1}}, \ldots, \mathbf{o}_{i_{l}}$ of actions of $\left(\mathbf{o}_{i}\right)_{i \in\{1, \ldots, k\}}$ of the shape $f\left(\mathrm{~A}_{i_{j}} ; \mathrm{c}_{i_{j}}\right)$. We then define $\gamma(f)$ as

$$
\begin{aligned}
& \lambda x . \mu \mathrm{c} \text {.[c]let } i=\text { !clock in clock :=!clock }+1 \text {; } \\
& \text { if }\left(i=j_{i_{1}} \text { and } \operatorname{set}_{x, \mathrm{~A}_{i_{1}}}=\operatorname{get}_{\mathrm{A}_{i_{1}}}\right) \text { then } \ell_{{c_{i_{1}}}}:=\lambda y \text {. [c] } y ; \mathrm{M}_{i_{1}} \\
& \text { else if }\left(i=j_{i_{2}} \text { and } \operatorname{set}_{x, \mathrm{~A}_{i_{2}}}=\operatorname{get}_{\mathrm{A}_{i_{2}}}\right) \text { then } \ell_{\mathrm{c}_{i_{2}}}:=\lambda y \text {.[c]y; } \mathrm{M}_{i_{2}} \\
& \text { ! } \\
& \text { else if }\left(i=j_{i_{l}} \text { and } \operatorname{set} x_{x, \mathrm{~A}_{i_{l}}}=\operatorname{get}_{\mathrm{A}_{i_{l}}}\right) \text { then } \ell_{\mathrm{c}_{i_{l}}}:=\lambda y \text {.[c]y; } \mathrm{M}_{i_{l}} \\
& \text { else } \Omega
\end{aligned}
$$

Then $\mathbb{P}_{i_{j}}=\left\langle\gamma(\mathrm{f}) \mathrm{A}_{i_{j}}, \mathrm{~S}_{h}\right\rangle$.

The other actions, if they exist, are of the shape $\mathrm{c}\left(\mathrm{A}_{i_{j}}\right)$, with c a continuation name c introduced in $\mathbf{p}$. In such a case we define $\gamma(\mathrm{c})$ by replacing the first line of the term above by

```
let }x=\bullet\mathrm{ in let }i=!clock in clock :=!clock + 1; 
    if ( }i=\mp@subsup{j}{1}{}\mathrm{ and set 
```



```
    \vdots
    else if (i=j}\mp@subsup{j}{k}{}\mathrm{ and set }\mp@subsup{\operatorname{se,A}}{x,\mp@subsup{i}{l}{}}{}=\mp@subsup{\operatorname{get}}{\mp@subsup{\textrm{A}}{\mp@subsup{i}{l}{}}{}}{})\mathrm{ then M}\mp@subsup{\textrm{M}}{\mp@subsup{i}{l}{}}{
    else \Omega
```

Then $\mathbb{P}_{i_{j}}=\left\langle\gamma(\mathrm{c})\left[\mathrm{A}_{i_{j}}\right], \mathrm{S}_{h}\right\rangle$.
If $\mathbf{p}$ is of the shape $\overline{\mathrm{g}}(\mathrm{f}, \mathrm{c})$, then we define $\mathbb{P}_{\mathrm{P}}$ as $\left\langle\gamma(\mathrm{c})\right.$ [let $x=!\ell_{\mathrm{g}}$ in $\left.\left.x \gamma(\mathrm{f})\right], \mathrm{S}_{m}\right\rangle$. If $\mathbf{p}$ is of the shape $\bar{d}(\mathrm{f})$, then we define $\mathbb{P}_{\mathrm{P}}$ as $\left\langle\right.$ let $x=!\ell_{d}$ in $\left.x \gamma(\mathrm{f}), \mathrm{S}_{m}\right\rangle$.

So by construction, we have $\{\mathcal{T}\} \subseteq \mathbf{V T}(\mathbb{P} ; \mathbb{S})$. The reverse inclusion is proven using the fact that $\mathbb{P}_{\mathrm{O}}$ reduces to a diverging configuration top-level term for all moves different from $\left(\mathbf{o}_{i} ; j_{i}\right)$.

We relate the notion of dual Ty configuration with this notion of dual for a set of traces.

Lemma 64. Taking $\mathbf{t} \in \operatorname{Tr}_{\mathrm{Ty}}(\mathbb{S})$, we have $\overline{\mathbf{t}} \overline{\mathrm{c}}(()) \in \operatorname{Tr}_{\mathrm{Ty}}\left(\mathbb{S}^{*} \mathrm{c}\right)$.
Combining these statements, we deduce the following definability theorem for the OGS LTS.

Theorem 65. Taking a trace $\mathbf{t} \in \operatorname{Tr}_{\mathrm{OGs}}(\mathbb{G})$ with $\mathbb{G}$ prime, then there exists a configuration $\mathbb{H}$ compatible with $\mathbb{G}$ such that $\operatorname{compat}_{c}(\mathbb{G}, \mathbb{H})$ and $\operatorname{Tr}_{\mathrm{OGS}}(\mathbb{H})=\left\{\mathbf{t}^{\prime} \mid\right.$ $\left.\mathbf{t}^{\prime} \sim \overline{\mathbf{t}} \overline{\mathrm{c}}(())\right\}$.

## B Proofs for Up-to Techniques

## B. 1 Progression and Compatible Functions

Definition 66 (Progress). A pair of relations $\left(\mathcal{R}_{\text {Act }}, \mathcal{R}_{\text {Pas }}\right)$ on active and passive configurations respectively progresses to the pair $\left(\mathcal{R}_{\text {Act }}^{\prime}, \mathcal{R}_{\text {Pas }}^{\prime}\right)$, written $\left(\mathcal{R}_{\text {Act }}, \mathcal{R}_{\text {Pas }}\right) \mapsto$ ( $\mathcal{R}_{A c t}^{\prime}, \mathcal{R}_{\text {Pas }}^{\prime}$ ) when:
$-\left(\mathcal{R}_{A c t}, \mathcal{R}_{\text {Pas }}\right) \subseteq\left(\mathcal{R}_{A c t}^{\prime}, \mathcal{R}_{\text {Pas }}^{\prime}\right)$

- Whenever $\left(\mathbb{G}_{1}, \mathbb{G}_{2}\right) \in \mathcal{R}_{\text {Pas }}$, for all Opponent moves $\mathbf{o}$ and $\mathbb{H}_{1}, \mathbb{H}_{2}$ such that

- Whenever $\left(\mathbb{G}_{1}, \mathbb{G}_{2}\right) \in \mathcal{R}_{\text {Act }}$, there exists a Proponent move $\mathbf{p}$ and $\left(\mathbb{H}_{1}, \mathbb{H}_{2}\right) \in$ $\mathcal{R}_{\text {Pas }}^{\prime}$ such that $\mathbb{G}_{1} \stackrel{\mathrm{p}}{\Rightarrow} \mathbb{H}_{\text {ogs }}$ and $\mathbb{G}_{2} \xlongequal[\text { ogs }]{\mathrm{p}} \mathbb{H}_{2}$.

Using the notion of progress, a bipartite bisimulation is a pair $\left(\mathcal{R}_{A c t}, \mathcal{R}_{\text {Pas }}\right)$ that progresses to itself, i.e. $\left(\mathcal{R}_{A c t}, \mathcal{R}_{\text {Pas }}\right) \mapsto\left(\mathcal{R}_{\text {Act }}, \mathcal{R}_{\text {Pas }}\right)$. Similarly, a bisimulation up to $f$ is a pair $\left(\mathcal{R}_{A c t}, \mathcal{R}_{\text {Pas }}\right)$ such that $\left(\mathcal{R}_{A c t}, \mathcal{R}_{\text {Pas }}\right) \mapsto f\left(\mathcal{R}_{\text {Act }}, \mathcal{R}_{\text {Pas }}\right)$.

Definition 67 (Compatibility). A monotone function from pairs of relations to pairs of relations is compatible if for all pairs $\left(\mathcal{R}_{\text {Act }}, \mathcal{R}_{\text {Pas }}\right),\left(\mathcal{R}_{\text {Act }}^{\prime}, \mathcal{R}_{\text {Pas }}^{\prime}\right)$ such that $\left(\mathcal{R}_{\text {Act }}, \mathcal{R}_{\text {Pas }}\right) \mapsto\left(\mathcal{R}_{A c t}^{\prime}, \mathcal{R}_{\text {Pas }}^{\prime}\right)$, we have $f\left(\mathcal{R}_{\text {Act }}, \mathcal{R}_{\text {Pas }}\right) \mapsto f\left(\mathcal{R}_{A c t}^{\prime}, \mathcal{R}_{\text {Pas }}^{\prime}\right)$.

Additionally, we require $f$ to be expansive, i.e. id $\subseteq f$ and idempotent, i.e. $f \circ f \subseteq f$.

These results hold without these additional constraints but simplify the proofs.

Lemma 68. The composition of compatible functions is compatible.
Compatible functions are useful for defining up-to techniques.
Lemma 69. Compatible functions are sound up-to techniques, i.e. if $f$ is compatible and $\left(\mathcal{R}_{A c t}, \mathcal{R}_{\text {Pas }}\right)$ is a bisimulation up to $f$, then $\left(\mathcal{R}_{A c t}, \mathcal{R}_{\text {Pas }}\right) \subseteq \simeq_{\text {ogs }}$.

Proof. Suppose we have a compatible function $f$ and a bisimulation up to $f$ : $\left(\mathcal{R}_{A c t}, \mathcal{R}_{\text {Pas }}\right)$. Then $f\left(\mathcal{R}_{A c t}, \mathcal{R}_{\text {Pas }}\right)$ is a bisimulation.

By definition, $\left(\mathcal{R}_{A c t}, \mathcal{R}_{\text {Pas }}\right) \mapsto f\left(\mathcal{R}_{\text {Act }}, \mathcal{R}_{\text {Pas }}\right)$. As $f$ is compatible, this means $f\left(\mathcal{R}_{A c t}, \mathcal{R}_{\text {Pas }}\right) \mapsto f\left(f\left(\mathcal{R}_{A c t}, \mathcal{R}_{\text {Pas }}\right)\right)$. We conclude by using the idempotence of $f$.

Lemma 70. Bisimilarity is a congruence w.r.t to compatible functions.
Proof. Take a compatible function $f$. As $f$ is expansive, bisimilarity is a bisimulation up to $f$. By the proof above, we know that $f\left(\simeq_{\text {ogs }}\right)$ is a bisimulation, so $f\left(\simeq_{\text {ogs }}\right) \subseteq \simeq_{\text {ogs }}$.

A function can satisfy the properties in Lemmas 69 and 70 while not being compatible. This is trivially the case for any function $f$ with $f \subseteq g$ for a compatible function $g$. One way of showing that a function $f$ falls in that case is to prove that $f$ is compatible up-to.

Definition 71 (Compatible up-to). A monotone, expansive and idempotent function $f$ from pairs of relations to pairs of relations is compatible up-to $g$ if for all pairs $\left(\mathcal{R}_{\text {Act }}, \mathcal{R}_{\text {Pas }}\right),\left(\mathcal{R}_{\text {Act }}^{\prime}, \mathcal{R}_{\text {Pas }}^{\prime}\right)$ such that $\left(\mathcal{R}_{\text {Act }}, \mathcal{R}_{\text {Pas }}\right) \mapsto\left(\mathcal{R}_{\text {Act }}^{\prime}, \mathcal{R}_{\text {Pas }}^{\prime}\right)$, we have $f\left(\mathcal{R}_{A c t}, \mathcal{R}_{\text {Pas }}\right) \mapsto(g \circ f \circ g)\left(\mathcal{R}_{A c t}^{\prime}, \mathcal{R}_{\text {Pas }}^{\prime}\right)$.

When $g$ is compatible, thus expansive, compatibility up-to $g$ is weaker than compatibility.

Lemma 72. For any compatible function $g$, if $f$ is compatible up-to $g$, then $g \circ f \circ g$ is compatible.

Proof. For any $\left(\mathcal{R}_{\text {Act }}, \mathcal{R}_{\text {Pas }}\right) \mapsto\left(\mathcal{R}_{\text {Act }}^{\prime}, \mathcal{R}_{\text {Pas }}^{\prime}\right)$, we have $g\left(\mathcal{R}_{\text {Act }}, \mathcal{R}_{\text {Pas }}\right) \mapsto g\left(\mathcal{R}_{\text {Act }}^{\prime}, \mathcal{R}_{\text {Pas }}^{\prime}\right)$, by compatibility of $g$. Then, by definition, we have $f\left(g\left(\mathcal{R}_{A c t}, \mathcal{R}_{\text {Pas }}\right)\right) \mapsto(g \circ$ $f \circ g)\left(g\left(\mathcal{R}_{A c t}^{\prime}, \mathcal{R}_{\text {Pas }}^{\prime}\right)\right)$. As $g$ is compatible, this means $g\left(f\left(g\left(\mathcal{R}_{A c t}, \mathcal{R}_{\text {Pas }}\right)\right)\right) \mapsto$ $g\left((g \circ f \circ g)\left(g\left(\mathcal{R}_{A c t}^{\prime}, \mathcal{R}_{\text {Pas }}^{\prime}\right)\right)\right)$. By idempotence of $g$, we can conclude as $(g \circ f \circ$ $g)\left(\mathcal{R}_{\text {Act }}, \mathcal{R}_{\text {Pas }}\right) \mapsto(g \circ f \circ g)\left(\mathcal{R}_{A c t}^{\prime}, \mathcal{R}_{\text {Pas }}^{\prime}\right)$.

## B. 2 Compatible Functions for $\simeq_{\text {ogs }}$

The compatibility of hide follows from Lemma 16.
Lemma 73. hide is compatible.
split is not directly compatible as it requires substitutions over atoms. Thus, we introduce an extra function. We use $\sigma$ to range over substitutions over atoms. Given a pair of relations $\left(\mathcal{R}_{\text {Act }}, \mathcal{R}_{\text {Pas }}\right)$ on active and passive OGS configurations respectively, we define the following function:

$$
\left.\begin{array}{rl}
\operatorname{isub}\left(\mathcal{R}_{A c t}, \mathcal{R}_{\text {Pas }}\right) \triangleq( & \left\{(\mathbb{G} \sigma, \mathbb{H} \sigma) \text { s.t. }(\mathbb{G}, \mathbb{H}) \in \mathcal{R}_{\text {Act }}, \sigma \text { is injective }\right\}, \\
& \left\{(\mathbb{G} \sigma, \mathbb{H} \sigma) \text { s.t. }(\mathbb{G}, \mathbb{H}) \in \mathcal{R}_{\text {Pas }}, \sigma \text { is injective }\right\}
\end{array}\right)
$$

Lemma 74. Take an injective substitution $\sigma$.
Whenever $\mathbb{G} \sigma \xrightarrow{\text { a }}_{\text {ogs }} \mathbb{H}$, there exists $\mathbb{G}^{\prime}, \sigma^{\prime}, \mathbf{a}^{\prime}, \mathbb{H}^{\prime}$ such that $\mathbb{G} \sigma=\mathbb{G} \sigma^{\prime}, \mathbf{a}^{\prime} \sigma^{\prime}=\mathbf{a}$, $\mathbb{H}^{\prime} \sigma^{\prime}=\mathbb{H}$ and $\mathbb{G}^{\prime} \xrightarrow{\mathrm{a}^{\prime}}{ }_{\mathrm{ogs}} \mathbb{H}^{\prime}$.

Whenever $\mathbb{G} \xrightarrow{\mathrm{a}} \mathrm{ogs} \mathbb{H}, \mathbb{G} \sigma \xrightarrow{\mathrm{a} \sigma}{ }_{\mathrm{ogs}} \mathbb{H} \sigma$.
The compatibility of isub follows from Lemma 74.
Lemma 75. isub is compatible.
Finally, we can study the tensor and prove that split is compatible.
Lemma 76. Whenever $\mathbb{G} \otimes \mathbb{H} \xrightarrow{\mathrm{a}} \mathrm{ogs}^{\mathbb{G}_{1}}$, then

- either $\mathbb{G} \xrightarrow{\text { a }}$ ogs $\mathbb{G}^{\prime}$ and $\mathbb{G}_{1}=\mathbb{G}^{\prime} \otimes \mathbb{H}^{\prime}$ with $\mathbb{H} \subseteq_{\text {Di }} \mathbb{H}^{\prime}$,
- or $\mathbb{H} \xrightarrow{\text { a }}$ ogs $\mathbb{H}^{\prime}$ and $\mathbb{G}_{1}=\mathbb{G}^{\prime} \otimes \mathbb{H}^{\prime}$ with $\mathbb{G} \subseteq_{\mathrm{Di}} \mathbb{G}^{\prime}$.

In both cases, the configuration that does not perform a transition is passive.
Whenever $\mathbb{G} \xrightarrow{\text { a }}$ ogs $\mathbb{G}^{\prime}$, then for all passive configuration $\mathbb{H}$ with $\mathbb{G} \otimes \mathbb{H}$ defined and $\left(\mathrm{L}_{\mathbb{G}^{\prime}} \backslash \mathrm{L}_{\mathbb{G}}\right) \cap \mathrm{L}_{\mathbb{H}}=\emptyset$, we have $\mathbb{G} \otimes \mathbb{H} \xrightarrow{\text { a }}$ ogs $\mathbb{G}^{\prime} \otimes \mathbb{H}^{\prime}$ with $\mathbb{H} \subseteq_{\mathrm{Di}} \mathbb{H}^{\prime}$.

The need for $\subseteq_{\text {Di }}$ occurs when $\mathbf{a}$ is a Proponent move that disclosed an atom shared by both $\mathbb{G}$ and $\mathbb{H}$. This does not happen if they are limit configurations. The condition $\left(L_{\mathbb{G}^{\prime}} \backslash \mathrm{L}_{\mathbb{G}}\right) \cap \mathrm{L}_{\mathbb{H}}=\emptyset$ ensures that the fresh names created via $\mathbf{a}$ - via allocation or given by the environment - do not appear in $\mathbb{H}$. Up to renaming, this condition always holds:

Remark 77. For any $\mathbb{G} \xrightarrow{\text { a }}$ ogs $\mathbb{G}^{\prime}$ and passive configuration $\mathbb{H}$ with $\mathbb{G} \otimes \mathbb{H}$ welldefined, there always exists an injective substitution $\sigma$, with $\mathbb{G} \sigma=\mathbb{G}$ such that we can apply Lemma 76 on $\mathbb{G} \xrightarrow{\mathrm{a} \sigma} \mathrm{ogs}^{\mathbb{G}^{\prime}} \sigma$.

Lemma 78. split is compatible up to isub.
Proof. We consider two pairs of relations such that $\left(\mathcal{R}_{\text {Act }}, \mathcal{R}_{\text {Pas }}\right) \mapsto\left(\mathcal{R}_{A c t}^{\prime}, \mathcal{R}_{\text {Pas }}^{\prime}\right)$.
$-\operatorname{Take}\left(\mathbb{A}, \mathbb{A}^{\prime}\right) \in \operatorname{split}\left(\mathcal{R}_{A c t}\right)$, meaning $\left(\mathbb{A} \otimes \mathbb{P}, \mathbb{A}^{\prime} \otimes \mathbb{P}^{\prime}\right) \in \mathcal{R}_{A c t}$. By hypothesis, there exists p and $\left(\mathbb{G}, \mathbb{G}^{\prime}\right) \in \mathcal{R}_{\text {Pas }}^{\prime}$ such that $\mathbb{A} \otimes \mathbb{P} \stackrel{\mathbf{p}}{\Rightarrow} \mathbb{O}, \mathbb{A}^{\prime} \otimes \mathbb{P}^{\prime} \stackrel{\mathbf{p}}{\Rightarrow} \mathbb{G}_{\text {ogs }}$. By lemma 76 , we must have that $\mathbb{A} \stackrel{\mathrm{p}}{\Rightarrow}{ }_{\text {ogs }}, \mathbb{P}_{2}, \mathbb{A}^{\prime} \stackrel{\mathrm{p}}{\Rightarrow}{ }_{\text {ogs }} \mathbb{P}_{2}^{\prime}$ with $\mathbb{G}=\mathbb{P}_{2} \otimes \mathbb{P}_{3}$ and $\mathbb{G}^{\prime}=\mathbb{P}_{2}^{\prime} \otimes \mathbb{P}_{3}^{\prime}$. Thus, we can conclude as $\left(\mathbb{P}_{2}, \mathbb{P}_{2}^{\prime}\right) \in \operatorname{split}\left(\mathcal{R}_{\text {Pas }}^{\prime}\right) \subseteq$ (isub $\circ$ split。isub) $\left(\mathcal{R}_{\text {Pas }}^{\prime}\right)$.

- Take $\left(\mathbb{P}_{1}, \mathbb{P}_{1}^{\prime}\right) \in \operatorname{split}\left(\mathcal{R}_{\text {Pas }}\right)$, meaning $\left(\mathbb{P}_{1} \otimes \mathbb{P}_{2}, \mathbb{P}_{1}^{\prime} \otimes \mathbb{P}_{2}^{\prime}\right) \in \mathcal{R}_{\text {Pas }}$, an Opponent move $\mathbf{o}$, and configurations $\mathbb{G}, \mathbb{G}^{\prime}$ such that $\mathbb{P}_{1} \xrightarrow{\mathbf{o}}$ ogs $\mathbb{G}$ and $\mathbb{P}_{1}^{\prime} \xrightarrow{\mathbf{0}}{ }_{\text {ogs }} \mathbb{G}^{\prime}$.
We can construct $\sigma$ injective such that we can use Lemma 76 for $\mathbb{P}_{1} \otimes$ $\mathbb{P}_{2} \xrightarrow{\boldsymbol{\sigma} \sigma}{ }_{\text {ogs }} \mathbb{G} \sigma \otimes \mathbb{P}_{2}$, and $\mathbb{P}_{1}^{\prime} \otimes \mathbb{P}_{2}^{\prime} \xrightarrow{\boldsymbol{o} \sigma}$ ogs $\mathbb{G}^{\prime} \sigma \otimes \mathbb{P}_{2}^{\prime}$. So $\left(\mathbb{G} \sigma \otimes \mathbb{P}_{2}, \mathbb{G}^{\prime} \sigma \otimes \mathbb{P}_{2}^{\prime}\right) \in \mathcal{R}_{\text {Act }}^{\prime}$. Thus, we have $\left(\mathbb{G}, \mathbb{G}^{\prime}\right) \in($ isubosplit $)\left(\mathcal{R}_{A c t}^{\prime}\right) \subseteq($ isubosplitoisub $)\left(\mathcal{R}_{A c t}^{\prime}\right)$.


## C Proofs for the Comparison of $\simeq_{\text {ogs }}$ and $\simeq_{\text {pogs }}$

We write $\mathbb{G} \leq \mathbb{H}$ where there exists $\mathbb{G}^{\prime}$ such that $\mathbb{G} \otimes \mathbb{G}^{\prime} \subseteq_{D i} \mathbb{H}$.
When $\mathbb{G} \leq \mathbb{H}$, if we write $\langle\mathrm{L} ; \mathrm{D}\rangle$ (resp. $\left\langle\mathrm{L}^{\prime} ; \mathrm{D}^{\prime}\right\rangle$ ) for the disclosing components of $\mathbb{G}($ resp. $\mathbb{H})$, we can decompose $\mathrm{L}^{\prime}$ as $\mathrm{L} \uplus \mathrm{L}_{f}$ and $\mathrm{D}^{\prime}$ as $\mathrm{D} \uplus \mathrm{D}_{e} \uplus \mathrm{D}_{f}$ with $\mathrm{D}_{e} \subseteq \mathrm{~L}$ and $\mathrm{D}_{f} \subseteq \mathrm{~L}_{f}$. This means $\langle\mathrm{L} ; \mathrm{D}\rangle \otimes\left\langle\mathrm{L}_{f} ; \mathrm{D}_{f}\right\rangle \subseteq_{\mathrm{Di}}\left\langle\mathrm{L} \uplus \mathrm{L}_{f} ;\left(\mathrm{D} \uplus \mathrm{D}_{e}\right) \uplus \mathrm{D}_{f}\right\rangle$.

Note that we can have $(\mathbb{I}, \mathbb{S}, \mathbb{D}) \leq(\mathbb{J}, \mathbb{T}, \mathbb{E})$ when one configuration is Opponent and the other is Proponent, although we will focus on situations where this is not the case.

Lemma 79. Suppose $\mathbb{G} \leq \mathbb{H}$ where $\mathbb{G}$ and $\mathbb{H}$ are either both passive or both active. Then $\mathbb{G} \xrightarrow{\mathrm{a}}$ ogs $\mathbb{G}^{\prime}$ implies that $\mathbb{H} \xrightarrow{\mathrm{a} \sigma}$ ogs $\mathbb{H}^{\prime}$ and $\mathbb{G}^{\prime} \sigma \leq \mathbb{H}^{\prime}$ for some $\mathbb{H}^{\prime}$ and injective $\sigma$ such that $\mathbb{H} \sigma=\mathbb{H}$.

Proof. This is a direct application of Remark 77 and Lemma 16.
The property above can be extended to traces, by a simple induction.
Lemma 80 (Asynchrony of atom disclosure). Consider a configuration $\mathbb{G}$ and two passive configurations $\mathbb{H}, \mathbb{G}^{\prime}$ such that $\mathbb{G} \xrightarrow{\mathbf{t}}$ ogs $\mathbb{H}$ and $\mathbb{G} \xrightarrow{\mathbf{t}^{\prime}}{ }_{\mathrm{ogs}} \mathbb{G}^{\prime}$, for some $\mathbf{t}, \mathbf{t}^{\prime}$. Then there exist $\mathbf{t}^{\prime \prime}, \mathbb{H}^{\prime}$ such that $\mathbb{G}^{\prime} \xrightarrow{\mathbf{t}^{\prime \prime}} \mathrm{ogs}^{\mathbb{H}^{\prime}}$ and $\mathbb{H} \leq \mathbb{H}^{\prime}$.

Among other, this lemma states that if some existing names in $\mathrm{D}_{e}$ can be disclosed (using a trace $\mathbf{t}$ ), then they can always be disclosed after an arbitrary trace $\mathbf{t}^{\prime}$.

Proof. If $\mathbf{t}^{\prime}$ is empty, the result is trivial.
If $\mathbf{t}$ is empty, then the result follows immediately from Lemma 25.
Otherwise if $\mathbb{G}$ is an active configuration, then $\mathbf{t}$ and $\mathbf{t}^{\prime}$ start with the same transition so we can conclude by induction.

If $\mathbb{G}$ is a passive configuration, by Lemma $25, \mathbb{G} \leq \mathbb{G}^{\prime}$. We show the expected result by an induction on the trace $\mathbf{t}$ using Lemmas 79 and 74 .

For $\mathcal{L}_{O G S}$, there exists a reachable state in which every name in the limit is disclosed:

Proof (Lemma 26). Write $\mathbb{G}=\left(\_, \_,\langle\mathrm{L}, \mathrm{D}\rangle\right)$ and $\lim (\mathbb{G})=\left(\_, \_,\left\langle\mathrm{L}, \mathrm{D}_{l}\right\rangle\right)$. We have $\mathrm{D}_{l} \backslash \mathrm{D}=\left\{a_{1}, \ldots, a_{n}\right\}$.

We reason by induction on $n$ to show that there exists a reachable configuration $\mathbb{G}_{i}$ such that the disclosed set contains $\mathrm{D} \uplus\left\{a_{1}, \ldots, a_{i}\right\}$.

The induction case is a direct consequence of Lemma 80.
Then by definition of the limit, we know that the result configuration cannot have a disclosed set $D^{\prime}$ bigger than $D_{l}$ when restricting to existing names $\left(D^{\prime} \cap L=\right.$ $\left.\mathrm{D}_{l} \cap \mathrm{~L}\right)$. Thus, the use of $\subseteq_{\mathrm{Di}}$ in the definition of $\leq$ is not required.

Proof (Lemma 27). We note L for the set of atoms of $\mathbb{P}, \mathrm{D}$ (resp. $\mathrm{D}^{\prime}$ ) for the disclosed set of $\mathbb{P}($ resp. $\mathbb{Q})$, and $\mathrm{D}_{l}\left(\right.$ resp. $\left.\mathrm{D}_{l}^{\prime}\right)$ for the one for the limit configuration. We have the following inequalities: $\mathrm{D}_{l}^{\prime} \cap \mathrm{L} \subseteq \mathrm{D}_{l} \subseteq \mathrm{D}_{l}^{\prime}$. This means that the disclosed set for $\lim (\mathbb{Q})$ may only change from the one of $\lim (\mathbb{P})$ in the new atoms that are created by the transition.

By Lemma 16 , we know that $\lim (\mathbb{P}) \xrightarrow{\text { a }}_{\text {ogs }} \mathbb{G}$ for some $\mathbb{G} \supseteq_{\text {Di }} \mathbb{Q}$ (resp. $\mathbb{G} \supseteq_{\text {Di }}$ $\mathbb{Q} \otimes \mathbb{P})$.

- for $\mathbf{a}=\mathbf{p}$, by Lemma 20 , this means $\lim (\mathbb{P}) \xrightarrow{\mathbf{p}}_{\text {pogs }} \mathbb{G}$. We can verify that $\lim (\mathbb{Q})=\mathbb{G}$ by looking at the LTS using the inequalities above.
- for $\mathbf{a}=\mathbf{o}$, we have that $\mathbb{G}=\mathbb{P}^{\prime} \otimes \lim (\mathbb{P})$ with $\mathbb{P}^{\prime} \supseteq_{\mathrm{Di}} \mathbb{Q}$. Then, by Lemma 21,
 the inequalities above.
- for $\mathbf{a}=\mathrm{op}$, the inequalities correspond to the conditions for the transition $\xrightarrow{\mathrm{op}}$ pd. Thus, there always is a transition in POGS for which the resulting configuration is $\lim (\mathbb{Q})$.
Proof (Theorem 29). We examine transitions in the target:

 This means $\mathbb{P}^{\prime} \operatorname{split}\left(\simeq_{\text {ogs }}\right) \mathbb{Q}^{\prime}$ which is included in $\simeq_{\text {ogs }}$ by Lemma 24 . Both are limits by Lemma 27 so we can conclude.
- for a Proponent transition, we have $\mathbb{P} \stackrel{\mathbf{p}}{\Rightarrow} \underset{\text { ogs }}{ } \mathbb{P}^{\prime}$ and $\mathbb{Q} \stackrel{\mathbf{p}}{\Rightarrow} \mathbb{o g s}^{\prime}$. By Lemma 28, $\lim \left(\mathbb{P}^{\prime}\right) \simeq_{\text {ogs }} \lim \left(\mathbb{Q}^{\prime}\right)$ and we conclude by Lemma 27.
Proof (Theorem 30). Take $\mathbb{G} \overline{\operatorname{tensor}}(\mathcal{R}) \mathbb{H}$. We write $\mathbb{G} \triangleq \mathbb{P} \otimes \mathbb{G}^{\prime}$ and $\mathbb{H} \triangleq \mathbb{Q} \otimes \mathbb{H}^{\prime}$.
- for a Proponent transition, we have $\mathbb{P} \stackrel{\mathrm{p}}{\Rightarrow} \underset{\text { pogs }}{ } \mathbb{P}^{\prime}$ and $\mathbb{Q} \stackrel{\mathrm{p}}{\Rightarrow}{ }_{\text {pogs }} \mathbb{Q}^{\prime}$ and $\mathbb{P}^{\prime} \mathcal{R} \mathbb{Q}^{\prime}$. Thus, by Lemmas 17,18 and $76, \mathbb{G} \stackrel{\mathbf{p}}{\Rightarrow} \subseteq_{\text {ogs }} \subseteq_{\text {Di }} \mathbb{P}^{\prime} \otimes \mathbb{G}^{\prime}$ and $\mathbb{H} \stackrel{\mathbf{p}}{\Rightarrow} \subseteq_{\text {ogs }} \subseteq_{\text {Di }} \mathbb{Q}^{\prime} \otimes \mathbb{H}^{\prime}$. We can conclude as $\mathbb{P}^{\prime} \otimes \mathbb{G}^{\prime} \overline{\text { tensor }}(\mathcal{R}) \mathbb{Q}^{\prime} \otimes \mathbb{H}^{\prime}$.
- for an Opponent transition, if $\mathbb{G} \xrightarrow{\mathbf{o}}{ }_{\text {ogs }} \mathbb{P}^{\prime} \otimes \mathbb{G}$ and $\mathbb{H} \xrightarrow{\mathbf{o}} \mathrm{ogs}^{\mathbb{Q}^{\prime}} \otimes \mathbb{H}$, then by Lemma 21, $\mathbb{P} \xrightarrow{\mathbf{o}}$ pogs $^{\mathbb{P}^{\prime}}$ and $\mathbb{Q} \stackrel{\mathrm{o}}{\text { pogs }}^{\mathbb{Q}^{\prime}}$. Thus, $\mathbb{P}^{\prime} \mathcal{R} \mathbb{Q}^{\prime}$ and $\mathbb{P}^{\prime} \otimes \mathbb{G} \overline{\text { tensor }}(\mathcal{R})$ $\mathbb{Q}^{\prime} \otimes \mathbb{H}$.


## D Finiteness of POGS Traces

We prove Lemma 11. We write $\boldsymbol{O}$ for the set of prime OGS configurations $\mathbb{G}$ such that any trace in $\operatorname{Tr}_{\text {Pogs }}(\mathbb{G})$ is finite.

We introduce Kripke biorthogonal logical predicates $\mathcal{V} \llbracket \sigma \rrbracket, \mathcal{K} \llbracket \neg \sigma \rrbracket$ and $\mathcal{E} \llbracket \sigma \rrbracket$ respectively over quadruple formed by either a value V , an evaluation context E or a term M, together with two sets of atoms L, D and a typing context for continuation and function names $\Delta$. They are defined in Figure 9, by recursion over the type $\sigma$. Notice that $\mathcal{K} \llbracket \neg \sigma \rrbracket$ is defined by orthogonality wrt $\mathcal{V} \llbracket \sigma \rrbracket$, and $\mathcal{E} \llbracket \sigma \rrbracket$ by orthogonality wrt $\mathcal{K} \llbracket \neg \sigma \rrbracket$, the pole being $\mathcal{O}$.

We extend their definition to terms with free variables, using a logical predicate $\mathcal{G} \llbracket \Gamma \rrbracket$ on substitution from variable to values. From it, we define the logical predicate

$$
\mathrm{L} ; \Gamma \models \mathrm{M}: \sigma
$$

on terms of type $\sigma$ with free variables in $\Gamma$, locations in $L$ and function names in $\Delta$.

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\mathcal { V } \llbracket \text { Bool】 } \triangleq \{ ( \mathrm { b } ; \mathrm { L } ; \mathrm { D } ; \Delta ) \| \mathrm { b } \in \{ \text { true, false } \} , \mathrm { D } \subseteq \mathrm { L } \subseteq \text { Locs, } \Delta \in \text { TCtxs } \}
\mathcal { V } \llbracket \mathrm { ref } _ { \text { Unit } } ^ { \| } \triangleq \{ ( \mathrm { a } ; \mathrm { L } ; \mathrm { D } ; \Delta ) \| \mathrm { a } \in \mathrm { L } \}
\mathcal { V } \llbracket \sigma \rightarrow \tau \rrbracket ~ \{ ( \mathrm { V } ; \mathrm { L } ; \mathrm { D } ; \Delta ) \| \forall \Theta \supseteq \Delta . \forall ( \mathrm { L } ^ { \prime } , \mathrm { D } ^ { \prime } ) \supseteq ( \mathrm { L } , \mathrm { D } ) . \forall \mathrm { W } . ( \mathrm { W } ; \mathrm { L } ^ { \prime } ; \mathrm { D } ^ { \prime } ; \Theta ) \in \mathcal { V } \llbracket \sigma \rrbracket
    =>(VW; L'; D';\Theta) \in\mathcal{E}\llbracket\tau\rrbracket}
\mathcal { K } \llbracket \neg \sigma \rrbracket \quad \triangleq \{ ( \mathrm { E } ; \mathrm { L } ; \mathrm { D } ; \Delta ) \| \forall \Theta \supseteq \Delta . \forall ( \mathrm { L } ^ { \prime } , \mathrm { D } ^ { \prime } ) \supseteq ( \mathrm { L } , \mathrm { D } ) . \forall \mathrm { V } .
                            (V;\mp@subsup{L}{}{\prime};\mp@subsup{\textrm{D}}{}{\prime};\Theta)\in\mathcal{V}\llbracket\sigma\rrbracket=>(\langle\textrm{E}[\textrm{V}];\mp@subsup{\textrm{L}}{}{\prime}\rangle,\langle\Theta|\perp\rangle,\langle\mp@subsup{\textrm{L}}{}{\prime};\mp@subsup{\textrm{D}}{}{\prime}\rangle)\inO}
\mathcal{E}|\sigma\rrbracket \triangleq{(M;L;D;\Delta)|\Delta;L\vdashM:\sigma^\forallE.(E;L;D;\Delta)\in\mathcal{K}\llbracket\neg\sigma\rrbracket=>(\langleE[M];L\rangle,\langle\Delta|\perp\rangle,\langleL;D\rangle)\inO}
\mathcal{E}|\perp\rrbracket \triangleq = (M;L;D;\Delta)|\Delta;L\vdashM: &^(\langleM;L\rangle,\langle\Delta|\perp\rangle,\langleL; D \) \inO}
G|\varnothing\rrbracket \triangleq & (\varepsilon;L;D;\Delta)|D\subseteqL\subseteqLocs,\Delta\inTCtxs }
G}\llbracket\Gamma,x:\sigma\rrbracket\triangleq{(\delta\cdot[x\mapsto\textrm{V}];\textrm{L};\textrm{D};\Delta)|(\delta;\textrm{L};\textrm{D};\Delta)\in\mathcal{G}\llbracket\Gamma\rrbracket\wedge(\textrm{V};\textrm{L};\textrm{D};\Delta)\in\mathcal{V}\llbracket\sigma\rrbracket
G\llbracket\Gamma,c:\neg\sigma\rrbracket\triangleq{(\delta\cdot[c\mapstoE];L;D;\Delta)|(\delta;L;D;\Delta)\in\mathcal{G}|\Gamma\rrbracket^(E;L;D;\Delta)\in\mathcal{K}|\neg\sigma\rrbracket}
L;\Gamma = M:\sigma \triangleq \forall(L'; D) \supseteq(L;L).\forall\Theta.\forall\delta.( }\delta;\mp@subsup{\textrm{L}}{}{\prime};\textrm{D};\Theta)\in\mathcal{G}\llbracket\Gamma\rrbracket=>(M{\delta};\mp@subsup{\textrm{L}}{}{\prime};\textrm{D};\Theta)\in\mathcal{E}\llbracket\sigma
L;\Gamma = E: \neg\sigma \triangleq \forall(L'; D) \supseteq (L;L).\forall\Theta.\forall\delta.(\delta;\mp@subsup{\textrm{L}}{}{\prime};\textrm{D};\Theta)\in\mathcal{G}\llbracket\Gamma\rrbracket=>(\textrm{E}{\delta};\mp@subsup{\textrm{L}}{}{\prime};\textrm{D};\Theta)\in\mathcal{K}\llbracket\neg\sigma\rrbracket
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Fig. 9. Definition of the logical predicates

## D. 1 Basic Lemmas

$O$ is closed by antireduction.
Lemma 81. If $\mathbb{G} \in O$ and $\mathbb{H} \xrightarrow{\text { op }}$ pogs $\mathbb{G}$ then $\mathbb{H} \in O$
Logical predicates are monotone over both the typing context of locations and function names.

Lemma 82. Taking $\mathrm{D}, \mathrm{D}^{\prime}, \mathrm{L}, \mathrm{L}^{\prime} \subseteq$ Locs such that $\mathrm{D} \subseteq \mathrm{L}$ and $\mathrm{D}^{\prime} \subseteq \mathrm{L}^{\prime}$, and $\Delta, \Theta \in$ TCtxs, if $\left(\mathrm{L}^{\prime} ; \mathrm{D}^{\prime}\right) \supseteq(\mathrm{L} ; \mathrm{D})$ and $\Theta \supseteq \Delta$, then:

- if $(\mathrm{V} ; \mathrm{L} ; \mathrm{D} ; \Delta) \in \mathcal{V} \llbracket \sigma \rrbracket$, then $\left(\mathrm{V} ; \mathrm{L}^{\prime} ; \mathrm{D}^{\prime} ; \Theta\right) \in \mathcal{V} \llbracket \sigma \rrbracket ;$
- if $(\mathrm{E} ; \mathrm{L} ; \mathrm{D} ; \Delta) \in \mathcal{K} \llbracket \neg \sigma \rrbracket$, then $\left(\mathrm{E} ; \mathrm{L}^{\prime} ; \mathrm{D}^{\prime} ; \Theta\right) \in \mathcal{K} \llbracket \neg \sigma \rrbracket$;
- if $(\delta ; \mathrm{L} ; \mathrm{D} ; \Delta) \in \mathcal{G} \llbracket \Gamma \rrbracket$, then $\left(\delta ; \mathrm{L}^{\prime} ; \mathrm{D}^{\prime} ; \Theta\right) \in \mathcal{G} \llbracket \Gamma \rrbracket ;$

The logical predicates $\mathcal{V} \llbracket \sigma \rrbracket$ is included in $\mathcal{E} \llbracket \sigma \rrbracket$.
Lemma 83. Taking V a value such that $(\mathrm{V} ; \mathrm{L} ; \mathrm{D} ; \Delta) \in \mathcal{V} \llbracket \sigma \rrbracket$, then $(\mathrm{V} ; \mathrm{L} ; \mathrm{D} ; \Delta) \in$ $\mathcal{E} \llbracket \sigma \rrbracket$.

Lemma 84. Taking $\sigma$ a type, then:

1. if $\Delta \Vdash \mathrm{A}: \sigma$ and $\operatorname{supp}(\mathrm{A}) \subseteq \mathrm{D}$, then $(\mathrm{A} ; \mathrm{L} ; \mathrm{D} ; \Delta) \in \mathcal{V} \llbracket \sigma \rrbracket$;
2. if $(\mathrm{V} ; \mathrm{L} ; \mathrm{D} ; \Delta) \in \mathcal{V} \llbracket \sigma \rightarrow \tau \rrbracket$ then $(\langle[\mathrm{f} \mapsto \mathrm{V}] ; \mathrm{L}\rangle,\langle\Delta \mid \mathrm{f}: \sigma \rightarrow \tau\rangle,\langle\mathrm{L} ; \mathrm{D}\rangle) \in \mathcal{O}$;
3. $([\mathrm{c}] \bullet ; \mathrm{L} ; \mathrm{D} ; \mathrm{c}: \neg \sigma) \in \mathcal{K} \llbracket \neg \sigma \rrbracket$;
4. if $(\mathrm{E} ; \mathrm{L} ; \mathrm{D} ; \Delta) \in \mathcal{K} \llbracket \neg \sigma \rrbracket$ then $(\langle[\mathrm{c} \mapsto \mathrm{E}] ; \mathrm{L}\rangle,\langle\Delta \mid \mathrm{c}: \neg \sigma\rangle,\langle\mathrm{L} ; \mathrm{D}\rangle) \in O$;

Proof. The four points are proven by a mutual induction over $\sigma$.

1. Suppose that $\Delta \Vdash \mathrm{A}: \sigma$.

- If $\sigma$ is a ground type this is straightforward;
- Otherwise, if $\sigma=\sigma_{1} \rightarrow \sigma_{2}$, we have A equal to a function name f. Taking $\left(\mathrm{L}^{\prime} ; \mathrm{D}^{\prime}\right) \supseteq(\mathrm{L} ; \mathrm{D})$ and $\Theta \supseteq \Delta$, we have to prove that ( $\left.\mathrm{fV} ; \mathrm{L}^{\prime} ; \mathrm{D}^{\prime} ; \Theta\right) \in \mathcal{E} \llbracket \sigma_{2} \rrbracket$ for all V such that $\left(\mathrm{V} ; \mathrm{L}^{\prime} ; \mathrm{D}^{\prime} ; \Theta\right) \in \mathcal{V} \llbracket \sigma_{1} \rrbracket$. To do so, taking E such that $\left(\mathrm{E} ; \mathrm{L}^{\prime} ; \mathrm{D}^{\prime} ; \boldsymbol{\Theta}\right) \in \mathcal{K} \llbracket \neg \sigma_{2} \rrbracket$, we then have to prove that $\left(\left\langle\mathrm{E}[\mathrm{fV}] ; \mathrm{L}^{\prime}\right\rangle,\langle\Delta|\right.$ $\left.\perp\rangle,\left\langle\mathrm{L}^{\prime} ; \mathrm{D}^{\prime}\right\rangle\right) \in O$. Depending on $\tau_{1}$, there are then three possible cases:
- if $\tau_{1}=$ Bool, then $\left(\langle E[f V] ; L\rangle,\langle\Theta \vdash \perp\rangle,\left\langle\mathrm{L}^{\prime} ; \mathrm{D}^{\prime}\right\rangle\right) \xrightarrow{\overline{\mathrm{f}}(\mathrm{V}, \mathrm{c})}$ pogs $(\langle[\mathrm{c} \mapsto$ $\left.\mathrm{E}]\rangle,\left\langle\Theta \vdash \mathrm{c}: \neg \sigma_{2}\right\rangle,\left\langle\mathrm{L}^{\prime} ; \mathrm{D}^{\prime}\right\rangle\right)$
- if $\sigma_{1}$ is functional, then $\left(\langle\mathrm{E}[\mathrm{fV}] ; \mathrm{L}\rangle,\langle\Theta \vdash \perp\rangle,\left\langle\mathrm{L}^{\prime} ; \mathrm{D}^{\prime}\right\rangle\right) \xrightarrow{\overline{\mathrm{f}}(\mathrm{g}, \mathrm{c})} \mathrm{pogs}(\langle[\mathrm{g} \mapsto$ $\left.\mathrm{V}] \cdot[\mathrm{c} \mapsto \mathrm{E}]\rangle,\left\langle\Theta \vdash \mathrm{g}: \sigma_{1}, \mathrm{c}: \neg \sigma_{2}\right\rangle,\left\langle\mathrm{L}^{\prime} ; \mathrm{D}^{\prime}\right\rangle\right)$
- if $\tau_{1}=\operatorname{ref}_{\text {Unit }}$, then $\left(\langle E[f V] ; L\rangle,\langle\Theta \vdash \perp\rangle,\left\langle L^{\prime} ; D^{\prime}\right\rangle\right) \xrightarrow{\overline{\mathrm{f}}(\mathrm{V}, \mathrm{c})}{ }_{\text {pogs }}(\langle[\mathrm{c} \mapsto$ $\left.\mathrm{E}]\rangle,\left\langle\Theta \vdash \mathrm{c}: \neg \sigma_{2}\right\rangle,\left\langle\mathrm{L}^{\prime} ; \mathrm{D}^{\prime}\right\rangle\right)$.
From induction on (2) at type $\sigma_{1}$, we deduce that ( $\langle[\mathrm{g} \mapsto \mathrm{V}]\rangle,\langle\Theta \vdash$ $\left.\left.\mathrm{g}: \sigma_{1}\right\rangle,\left\langle\mathrm{L}^{\prime} ; \mathrm{D}^{\prime}\right\rangle\right) \in \mathcal{O}$. From induction on (4) at type $\sigma_{2}$, we deduce that $\left(\langle[\mathrm{c} \mapsto \mathrm{E}]\rangle,\left\langle\Theta \vdash \mathrm{c}: \neg \sigma_{2}\right\rangle,\left\langle\mathrm{L}^{\prime} ; \mathrm{D}^{\prime}\right\rangle\right) \in O$. So we deduce that $(\langle\mathrm{E}[\mathrm{fV}] ; \mathrm{L}\rangle,\langle\Theta \vdash$ $\left.\perp\rangle,\left\langle\mathrm{L}^{\prime} ; \mathrm{D}^{\prime}\right\rangle\right) \in O$.

2. Suppose that $(\mathrm{V} ; \mathrm{L} ; \mathrm{D} ; \Delta) \in \mathcal{V} \llbracket \sigma \rightarrow \tau \rrbracket$. We have
$(\langle[\mathrm{f} \mapsto \mathrm{V}] ; \mathrm{L}\rangle,\langle\Delta \mid \mathrm{f}: \sigma \rightarrow \tau\rangle,\langle\mathrm{L} ; \mathrm{D}\rangle) \xrightarrow{\mathrm{f}(\mathrm{A} ; \mathrm{c})} \mathrm{pogs}\left(\left\langle[\mathrm{c}] \mathrm{VA} ; \mathrm{L}^{\prime}\right\rangle,\langle\Theta, \Delta, \mathrm{c}: \neg \tau \vdash \perp\rangle,\left\langle\mathrm{L}^{\prime} ; \mathrm{D}^{\prime}\right\rangle\right)$
for all A such that $\Theta \Vdash A: \sigma$ and $\left\langle L^{\prime} ; D^{\prime}\right\rangle$ such that $\langle L ; D\rangle \xrightarrow{f(A)} D_{i}\left\langle L^{\prime} ; D^{\prime}\right\rangle$. From induction on (1) at type $\sigma$, we deduce that $\left(\mathrm{A} ; \mathrm{L}^{\prime} ; \mathrm{D}^{\prime} ; \Theta\right) \in \mathcal{V} \llbracket \sigma \rrbracket$, so that $\left(\mathrm{VA} ; \mathrm{L}^{\prime} ; \mathrm{D}^{\prime} ; \Theta\right) \in \mathcal{E} \llbracket \tau \rrbracket$. From induction on (3) at type $\tau$, we deduce that $\left([\mathrm{c}] \bullet ; \mathrm{L}^{\prime} ; \mathrm{D}^{\prime} ; \Delta\right) \in \mathcal{K} \llbracket \neg \tau \rrbracket$, so that $\left(\left\langle[\mathrm{c}] \mathrm{VA} ; \mathrm{L}^{\prime}\right\rangle,\langle\Theta, \Delta, \mathrm{c}: \neg \tau \vdash \perp\rangle,\left\langle\mathrm{L}^{\prime} ; \mathrm{D}^{\prime}\right\rangle\right) \in O$. Thus, $(\langle[\mathrm{f} \mapsto \mathrm{V}] ; \mathrm{L}\rangle,\langle\Delta \mid \mathrm{f}: \sigma \rightarrow \tau\rangle,\langle\mathrm{L} ; \mathrm{D}\rangle) \in O$.
3. Taking ( $\left.\mathrm{L}^{\prime} ; \mathrm{D}^{\prime}\right) \supseteq(\mathrm{L} ; \mathrm{D})$ and $\Delta$ such that $\mathrm{c} \notin \operatorname{dom}(\Delta)$, for all V such that $\left(\mathrm{V} ; \mathrm{L}^{\prime} ; \mathrm{D}^{\prime} ; \Delta, \mathrm{c}: \neg \sigma\right) \in \mathcal{V} \llbracket \sigma \rrbracket$, depending on $\sigma$ there are three cases:

- If $\sigma=$ Bool, then $\left(\left\langle[\mathrm{c}] \mathrm{V} ; \mathrm{L}^{\prime}\right\rangle,\langle\Delta, \mathrm{c}: \neg \sigma \mid \perp\rangle,\left\langle\mathrm{L}^{\prime} ; \mathrm{D}^{\prime}\right\rangle\right) \xrightarrow{\overline{\mathrm{c}}(\mathrm{V})}{ }_{\mathrm{pogs}}\left(\left\langle\varepsilon ; \mathrm{L}^{\prime}\right\rangle,\langle\Delta, \mathrm{c}:\right.$ $\left.\neg \sigma|\varepsilon\rangle,\left\langle\mathrm{L}^{\prime} ; \mathrm{D}^{\prime}\right\rangle\right)$ which is a normal form for $\mathcal{L}_{\mathrm{POGS}}$ so that it is in $\boldsymbol{O}$.
- If $\sigma=\operatorname{ref}_{\text {Unit }}$, then $\left(\left\langle[\mathrm{c}] \mathrm{V} ; \mathrm{L}^{\prime}\right\rangle,\langle\Delta, \mathrm{c}: \neg \sigma \mid \perp\rangle,\left\langle\mathrm{L}^{\prime} ; \mathrm{D}^{\prime}\right\rangle\right) \xrightarrow{\overline{\mathrm{c}}(\mathrm{V})}{ }_{\text {pogs }}\left(\left\langle\varepsilon ; \mathrm{L}^{\prime}\right\rangle,\langle\Delta, \mathrm{c}:\right.$ $\left.\neg \sigma|\varepsilon\rangle,\left\langle\mathrm{L}^{\prime} ; \mathrm{D}^{\prime}\right\rangle\right)$ whenever $\mathrm{V} \in \mathrm{D}^{\prime}$ (in the other case, no transition can happen so we are done). And again, this configuration is a normal form for $\mathcal{L}_{\text {POGS }}$ so that it is in $\boldsymbol{O}$.
- If $\sigma$ is a function type, then $\left(\left\langle[\mathrm{c}] \mathrm{V} ; \mathrm{L}^{\prime}\right\rangle,\langle\Delta, \mathrm{c}: \neg \sigma \mid \perp\rangle,\left\langle\mathrm{L}^{\prime} ; \mathrm{D}^{\prime}\right\rangle\right) \xrightarrow{\overline{\mathrm{c}(\mathrm{f})}} \mathrm{p}_{\mathrm{pogs}}$ ( $\left.\left\langle[\mathrm{f} \mapsto \mathrm{V}] ; \mathrm{L}^{\prime}\right\rangle,\langle\Delta, \mathrm{c}: \neg \sigma \mid \mathrm{f}: \sigma\rangle,\left\langle\mathrm{L}^{\prime} ; \mathrm{D}^{\prime}\right\rangle\right)$. Then we deduce from (2) that $\left(\left\langle[\mathrm{f} \mapsto \mathrm{V}] ; \mathrm{L}^{\prime}\right\rangle,\langle\Delta, \mathrm{c}: \neg \sigma \mid \mathrm{f}: \sigma\rangle,\langle\mathrm{L} ; \mathrm{D}\rangle\right) \in O$.
So we indeed get in all three cases that $\left(\left\langle[\mathrm{c}] \mathrm{V} ; \mathrm{L}^{\prime}\right\rangle,\langle\Delta, \mathrm{c}: \neg \sigma \mid \perp\rangle,\left\langle\mathrm{L}^{\prime} ; \mathrm{D}^{\prime}\right\rangle\right) \in O$. 4. Suppose that $(\mathrm{E} ; \mathrm{L} ; \mathrm{D} ; \Delta) \in \mathcal{K} \llbracket \neg \sigma \rrbracket$. Then

$$
(\langle[\mathrm{c} \mapsto \mathrm{E}] ; \mathrm{L}\rangle,\langle\Delta, \mathrm{c}: \neg \sigma\rangle,\langle\mathrm{L} ; \mathrm{D}\rangle) \xrightarrow{\mathrm{c}(\mathrm{~A})}_{\mathrm{pogs}}\left(\left\langle\mathrm{E}[\mathrm{~A}] ; \mathrm{L}^{\prime}\right\rangle,\langle\Theta, \Delta \vdash \perp\rangle,\left\langle\mathrm{L}^{\prime} ; \mathrm{D}^{\prime}\right\rangle\right)
$$

for all A such that $\Theta \Vdash A: \sigma$ and $\left\langle L^{\prime} ; D^{\prime}\right\rangle$ such that $\langle L ; D\rangle \xrightarrow{c(A)}{ }_{D i}\left\langle L^{\prime} ; D^{\prime}\right\rangle$. From induction on (1) at type $\sigma$, we deduce that $(\mathrm{A} ; \mathrm{L} ; \mathrm{D} ; \Theta) \in \mathcal{V} \llbracket \sigma \rrbracket$, so that $\left(\left\langle\mathrm{E}[\mathrm{A}] ; \mathrm{L}^{\prime}\right\rangle,\langle\Theta, \Delta \vdash \perp\rangle,\left\langle\mathrm{L}^{\prime} ; \mathrm{D}^{\prime}\right\rangle\right) \in O$. So $(\langle[\mathrm{c} \mapsto \mathrm{E}] ; \mathrm{L}\rangle,\langle\Delta, \mathrm{c}: \neg \sigma\rangle,\langle\mathrm{L} ; \mathrm{D}\rangle) \in O$.

## D. 2 Fundamental Property

We now prove the standard compatibility lemmas needed to prove the fundamental theorem of the logical predicates.

Lemma 85. $\mathrm{L} ; \Gamma \vDash x: \Gamma(x)$
Proof. Let us take $\Theta,\left(\mathrm{L}^{\prime} ; \mathrm{D}\right) \supseteq(\mathrm{L} ; \mathrm{L})$, and $\delta \operatorname{such}$ that $\left(\delta ; \mathrm{L}^{\prime} ; \mathrm{D} ; \Theta\right) \in \mathcal{G} \llbracket \Gamma \rrbracket$. Then by definition of $\mathcal{G} \llbracket \Gamma \rrbracket,\left(\delta(x) ; \mathrm{L}^{\prime} ; \mathrm{D} ; \Theta\right) \in \mathcal{V} \llbracket \Gamma(x) \rrbracket$ so that from Lemma 83 $\left(\delta(x) ; \mathrm{L}^{\prime} ; \mathrm{D} ; \Theta\right) \in \mathcal{E} \llbracket \Gamma(x) \rrbracket$.

Lemma 86. If $\mathrm{L} ; \Gamma \vDash \mathrm{V}: \sigma \rightarrow \tau$ and $\mathrm{L} ; \Gamma \vDash \mathrm{W}: \sigma$, then $\mathrm{L} ; \Gamma \vDash \mathrm{VW}: \tau$.
Proof. Let us take ( $\left.\mathrm{L}^{\prime} ; \mathrm{D}\right) \supseteq(\mathrm{L} ; \mathrm{L})$, and $\delta$ such that $\left(\delta ; \mathrm{L}^{\prime} ; \mathrm{D} ; \Delta\right) \in \mathcal{G} \llbracket \Gamma \rrbracket$. We write $\tilde{\mathrm{V}}$ for $\mathrm{V}\{\delta\}$ and $\tilde{\mathrm{W}}$ for $\mathrm{W}\{\delta\}$. Taking E such that $\left(\mathrm{E} ; \mathrm{L}^{\prime} ; \mathrm{D} ; \Delta\right) \in \mathcal{K} \llbracket \neg \tau \rrbracket$, we have to prove that $\left(\left\langle\mathrm{E}[\tilde{\mathrm{V}} \tilde{W}] ; \mathrm{L}^{\prime} ; \mathrm{D}\right\rangle,\langle\Delta \mid \perp\rangle,\left\langle\mathrm{L}^{\prime} ; \mathrm{D}\right\rangle\right) \in O$. To do so, we prove that $(\mathrm{E}[$ let $x=$ $\bullet$ in $\left.x \tilde{\mathrm{~W}}] ; \mathrm{L}^{\prime} ; \mathrm{D} ; \Delta\right) \in \mathcal{K} \llbracket \neg(\sigma \rightarrow \tau) \rrbracket$. Taking $\left(\mathrm{L}^{\prime \prime} ; \mathrm{D}^{\prime}\right) \supseteq\left(\mathrm{L}^{\prime} ; \mathrm{D}\right), \Theta \supseteq \Delta$ and $\mathrm{V}^{\prime}$ such that $\left(\mathrm{V}^{\prime} ; \mathrm{L}^{\prime \prime} ; \mathrm{D}^{\prime} ; \Theta\right) \in \mathcal{V} \llbracket \sigma \rightarrow \tau \rrbracket$, we want to prove that $\left(\left\langle\mathrm{E}\left[\mathrm{V}^{\prime} \tilde{\mathrm{W}}\right] ; \mathrm{L}^{\prime \prime} ; \mathrm{D}^{\prime}\right\rangle,\langle\Theta|\right.$ $\left.\perp\rangle,\left\langle\mathrm{L}^{\prime \prime} ; \mathrm{D}^{\prime}\right\rangle\right) \in \mathcal{O}$. Since $\mathrm{L} ; \Gamma \models \mathrm{W}: \sigma$, and from Lemma $82\left(\delta ; \mathrm{L}^{\prime \prime} ; \mathrm{D}^{\prime} ; \Theta\right) \in \mathcal{G} \llbracket \Gamma \rrbracket$, we get that $\left(\tilde{W} ; \mathrm{L}^{\prime \prime} ; \mathrm{D}^{\prime} ; \Theta\right) \in \mathcal{E} \llbracket \sigma \rrbracket$. So we simply have to prove that $(\mathrm{E}[$ let $y=$ $\bullet$ in $\left.\left.\mathrm{V}^{\prime} y\right] ; \mathrm{L}^{\prime \prime} ; \mathrm{D}^{\prime} ; \Theta\right) \in \mathcal{K} \llbracket \neg \sigma \rrbracket$, which is straightforward.

Lemma 87. If $\mathrm{L} ; \Gamma, x: \sigma \vDash \mathrm{M}: \tau$, then $\mathrm{L} ; \Gamma \vDash \lambda x . \mathrm{M}: \sigma \rightarrow \tau$.
Proof. Let us take ( $\left.\mathrm{L}^{\prime} ; \mathrm{D}\right) \supseteq(\mathrm{L} ; \mathrm{L})$, and $\delta$ such that $\left(\delta ; \mathrm{L}^{\prime} ; \mathrm{D} ; \Delta\right) \in \mathcal{G} \llbracket \Gamma \rrbracket$, from Lemma 83 we have to prove that $\left((\lambda x . \mathrm{M})\{\delta\} ; \mathrm{L}^{\prime} ; \mathrm{D} ; \Delta\right) \in \mathcal{V} \llbracket \sigma \rightarrow \tau \rrbracket$. So taking $\Theta \supseteq \Delta,\left(\mathrm{L}^{\prime \prime} ; \mathrm{D}^{\prime}\right) \supseteq\left(\mathrm{L}^{\prime} ; \mathrm{D}\right), \mathrm{V}$ such that $\left(\mathrm{V} ; \mathrm{L}^{\prime \prime} ; \mathrm{D}^{\prime} ; \Theta\right) \in \mathcal{V} \llbracket \sigma \rrbracket$, and E such that
$\left(\mathrm{E} ; \mathrm{L}^{\prime \prime} ; \mathrm{D}^{\prime} ; \Theta\right) \in \mathcal{K} \llbracket \neg \tau \rrbracket$ we have to prove that $\underbrace{\left(\left\langle\mathrm{E}[(\lambda x . \mathrm{M}\{\delta\}) \mathrm{V}] ; \mathrm{L}^{\prime \prime}\right\rangle,\langle\Theta \mid \perp\rangle,\left\langle\mathrm{L}^{\prime \prime} ; \mathrm{D}^{\prime}\right\rangle\right)}_{\mathbb{G}} \in$
O. We conclude using Lemma 81 since
$\left(\left\langle\mathrm{E}[(\lambda x . \mathrm{M}\{\delta\}) \mathrm{V}] ; \mathrm{L}^{\prime \prime}\right\rangle,\langle\Theta \mid \perp\rangle,\left\langle\mathrm{L}^{\prime \prime} ; \mathrm{D}^{\prime}\right\rangle\right) \xrightarrow{\mathrm{op}}_{\mathrm{pogs}}(\underbrace{\left(\left\langle\mathrm{E}[(\mathrm{M}\{\delta \cdot[x \mapsto \mathrm{~V}]\}) \mathrm{V}] ; \mathrm{L}^{\prime \prime}\right\rangle,\langle\Theta \mid \perp\rangle,\left\langle\mathrm{L}^{\prime \prime} ; \mathrm{D}^{\prime}\right\rangle\right)}_{\mathbb{H}}$
. Indeed, by hypothesis, we get that $\mathrm{E}\left[\left(\mathrm{M}\{\delta \cdot[x \mapsto \mathrm{~V}]\} ; \mathrm{L}^{\prime \prime} ; \mathrm{D}^{\prime} ; \Theta\right)\right] \in \mathcal{O}$. .
Lemma 88. If $\mathrm{L} ; \Gamma, x: \sigma \vDash \mathrm{M}: \tau$ and $\mathrm{L} ; \Gamma \vDash \mathrm{E}: \neg \tau$ then $\mathrm{L} ; \Gamma \vDash \mathrm{E}[$ let $x=\bullet$ in M$]$ : $\neg \sigma$.

Proof. Let us take ( $\left.\mathrm{L}^{\prime} ; \mathrm{D}\right) ~ \supseteq(\mathrm{~L} ; \mathrm{L})$, and $\delta$ such that $\left(\delta ; \mathrm{L}^{\prime} ; \mathrm{D} ; \Delta\right) \in \mathcal{G} \llbracket \Gamma \rrbracket$. We write $\tilde{\mathrm{M}}$ for $\mathrm{M}\{\delta\}$ and $\tilde{\mathrm{E}}$ for $\mathrm{E}\{\delta\}$.. Taking V such that $\left(\mathrm{V} ; \mathrm{L}^{\prime} ; \mathrm{D} ; \Delta\right) \in \mathcal{V} \llbracket \sigma \rrbracket$, we prove that $\left(\left\langle\tilde{E}[\right.\right.$ let $x=\mathrm{V}$ in $\left.\left.\tilde{\mathrm{M}}] ; \mathrm{L}^{\prime}\right\rangle,\langle\Delta \mid \perp\rangle,\left\langle\mathrm{L}^{\prime} ; \mathrm{D}\right\rangle\right) \in O$. Indeed, we have

$$
\mathbb{G} \stackrel{\text { op }}{ }_{\mathrm{pogs}} \underbrace{\left(\left\langle\tilde{\mathrm{E}}[\tilde{\mathrm{M}}\{x:=\mathrm{V}\}] ; \mathrm{L}^{\prime}\right\rangle,\langle\Delta \mid \perp\rangle,\left\langle\mathrm{L}^{\prime} ; \mathrm{D}\right\rangle\right)}_{\mathbb{H}}
$$

From $\mathrm{L} ; \Gamma, x: \sigma \vDash \mathrm{M}: \tau$, we get $\left(\tilde{\mathrm{M}}\{x:=\mathrm{V}\} ; \mathrm{L}^{\prime} ; \mathrm{D} ; \Delta\right) \in \mathcal{E} \llbracket \sigma \rrbracket$, which is enough to conclude that $\mathbb{H} \in O$. So from Lemma 81 we get that $\mathbb{G} \in O$.

Lemma 89. If $\mathrm{L} ; \Gamma \vDash \mathrm{M}: \sigma$ and $\mathrm{L} ; \Gamma, x: \sigma \vDash \mathrm{N}: \tau$ then $\mathrm{L} ; \Gamma \vDash \operatorname{let} x=\mathrm{M}$ in $\mathrm{N}: \tau$.
Proof. Let us take (L'; D) $\supseteq(\mathrm{L} ; \mathrm{L})$, and $\delta$ such that $\left(\delta ; \mathrm{L}^{\prime} ; \mathrm{D} ; \Delta\right) \in \mathcal{G} \llbracket \Gamma \rrbracket$. We write $\tilde{M}$ for $M\{\delta\}$ and $\tilde{N}$ for $N\{\delta\}$. We want to prove that (let $x=\tilde{M}$ in $\left.\tilde{N} ; \mathrm{L}^{\prime} ; \mathrm{D} ; \Delta\right) \in \mathcal{E} \llbracket \tau \rrbracket$. So taking E such that $\left(\mathrm{E} ; \mathrm{L}^{\prime} ; \mathrm{D} ; \Delta\right) \in \mathcal{K} \llbracket \neg \tau \rrbracket$, we have to prove that $(\langle\mathrm{E}[$ let $x=$ $\tilde{M}$ in $\left.\left.\tilde{\mathrm{N}}] ; \mathrm{L}^{\prime}\right\rangle,\langle\Delta \mid \perp\rangle,\left\langle\mathrm{L}^{\prime} ; \mathrm{D}\right\rangle\right) \in O$.

By hypothesis, $\left(\tilde{M} ; \mathrm{L}^{\prime} ; \mathrm{D} ; \Delta\right) \in \mathcal{E} \llbracket \sigma \rrbracket$, so we prove the fact that ( $\mathrm{E}[$ let $x=$ $\bullet$ in $\left.\tilde{\mathrm{N}}] ; \mathrm{L}^{\prime} ; \mathrm{D} ; \Delta\right) \in \mathcal{K} \llbracket \neg \sigma \rrbracket$. Taking $\left(\mathrm{L}^{\prime \prime} ; \mathrm{D}^{\prime}\right) \supseteq\left(\mathrm{L}^{\prime} ; \mathrm{D}\right)$ and V such that $\left(\mathrm{W} ; \mathrm{L}^{\prime \prime} ; \mathrm{D}^{\prime} ; \Theta\right)$, we prove that $\left(\left\langle\mathrm{E}[\right.\right.$ let $x=\mathrm{V}$ in $\left.\left.\tilde{\mathrm{N}}] ; \mathrm{L}^{\prime}\right\rangle,\langle\Delta \vdash \perp\rangle,\left\langle\mathrm{L}^{\prime \prime} ; \mathrm{D}^{\prime}\right\rangle\right) \in O$ using Lemma 81. In-

deed,

$$
\mathbb{G} \xrightarrow{\mathrm{op}}_{\mathrm{pogs}} \underbrace{\left(\left\langle\tilde{\mathrm{E}}[\tilde{\mathrm{M}}\{x:=\mathrm{V}\}] ; \mathrm{L}^{\prime}\right\rangle,\langle\Delta \mid \perp\rangle,\left\langle\mathrm{L}^{\prime} ; \mathrm{D}\right\rangle\right)}_{\mathbb{H}}
$$

and from $\mathrm{L} ; \Gamma, x: \sigma \vDash \mathrm{M}: \tau$, we get $\left(\tilde{\mathrm{M}}\{x:=\mathrm{V}\} ; \mathrm{L}^{\prime} ; \mathrm{D} ; \Delta\right) \in \mathcal{E} \llbracket \sigma \rrbracket$, which is enough to conclude that $\mathbb{H} \in O$.

Lemma 90. If $\mathrm{L} ; \Gamma, x: \boldsymbol{r e f}_{\text {Unit }} \vDash \mathrm{M}: \sigma$ then $\mathrm{L} ; \Gamma \vDash$ new $x$ in $\mathrm{M}: \sigma$
Proof. For all ( $\left.\mathrm{L}^{\prime} ; \mathrm{D}\right) \supseteq(\mathrm{L} ; \mathrm{L})$, taking $\delta$ such that $\left(\delta ; \mathrm{L}^{\prime} ; \mathrm{D} ; \Delta\right) \in \mathcal{G} \llbracket \Gamma \rrbracket$, we have to prove that (new $x$ in $\left.M\{\delta\} ; \mathrm{L}^{\prime} ; \mathrm{D}^{\prime} ; \Delta\right) \in \mathcal{E} \llbracket \sigma \rrbracket$. Taking E such that $\left(\mathrm{E} ; \mathrm{L} ; \mathrm{D}^{\prime} ; \Delta\right) \in$ $\mathcal{K} \llbracket \neg \sigma \rrbracket$, we have
$\underbrace{\left(\left\langle\mathrm{E}[\text { new } x \text { in } \mathrm{M}\{\delta\}] ; \mathrm{L}^{\prime}\right\rangle,\langle\Delta \mid \perp\rangle,\left\langle\mathrm{L}^{\prime} ; \mathrm{D}^{\prime}\right\rangle\right)}_{\mathbb{G}} \xrightarrow{\text { op }}_{\mathrm{pogs}} \underbrace{\left(\left\langle\mathrm{E}[\mathrm{M}\{\delta \cdot[x \mapsto \mathrm{a}]\}] ; \mathrm{L}^{\prime} \cup\{\mathrm{a}\}\right\rangle,\langle\Delta \mid \perp\rangle,\left\langle\mathrm{L}^{\prime} \cup\{\mathrm{a}\} ; \mathrm{D}^{\prime \prime}\right\rangle\right)}_{\mathbb{H}}$
for all a $\notin \mathrm{L}^{\prime}$, with $\mathrm{D}^{\prime \prime}$ either equal to $\mathrm{D}^{\prime}$ or to $\mathrm{D}^{\prime} \cup\{\mathrm{a}\}$. From $\mathrm{L} ; \Gamma, x: \operatorname{ref}_{\text {Unit }} \vDash \mathrm{M}$ : $\sigma$ we get that $\left(\mathrm{M}\{\delta \cdot[x \mapsto \mathrm{a}]\} ; \mathrm{L}^{\prime} \cup\{\mathrm{a}\} ; \mathrm{D}^{\prime \prime} ; \Delta\right) \in \mathcal{E} \llbracket \tau \rrbracket$, since $\left(\mathrm{L}^{\prime} \cup\{\mathrm{a}\} ; \mathrm{D}^{\prime \prime}\right) \supseteq(\mathrm{L}, \mathrm{L})$. This is enough to conclude that $\mathbb{H} \in O$ and so from Lemma 81 that $\mathbb{G} \in \mathcal{O}$.

Lemma 91. If $\mathrm{L} ; \Gamma, \mathrm{c}: \neg \sigma \vDash \mathrm{M}: \perp$ then $\mathrm{L} ; \Gamma \vDash \mu \mathrm{c} \cdot \mathrm{M}: \sigma$
Proof. For all (L' D$) \supseteq(\mathrm{L} ; \mathrm{L})$, taking $\delta$ such that $\left(\delta ; \mathrm{L}^{\prime} ; \mathrm{D} ; \Delta\right) \in \mathcal{G} \llbracket \Gamma \rrbracket$, and E such that $\left(\mathrm{E} ; \mathrm{L}^{\prime} ; \mathrm{D} ; \Delta\right) \in \mathcal{K} \llbracket \neg \sigma \rrbracket$, writing $\mathbb{G}$ for $\left(\langle\mathrm{E}[\mu \mathrm{c} . \mathrm{M}] ; \mathrm{L}\rangle,\langle\Delta \mid \perp\rangle,\left\langle\mathrm{L}^{\prime} ; \mathrm{D}\right\rangle\right)$, we
 hypothesis, we have that $\left(\mathrm{M}\{\delta \cdot[\mathrm{c} \mapsto \mathrm{E}]\} ; \mathrm{L}^{\prime} ; \mathrm{D} ; \Delta\right) \in \mathcal{E} \llbracket \perp \rrbracket$, so that indeed $\mathbb{H} \in O$, which is enough to conclude.

Lemma 92. If $\mathrm{L} ; \Gamma \vDash \mathrm{M}: \sigma$ and $\Delta(\mathrm{c})=\neg \sigma$ then $\mathrm{L} ; \Gamma \vDash[\mathrm{c}] \mathrm{M}: \perp$
Proof. For all (L' $; \mathrm{D}) \supseteq(\mathrm{L} ; \mathrm{L})$, taking $\delta$ such that $\left(\delta ; \mathrm{L}^{\prime} ; \mathrm{D} ; \Delta\right) \in \mathcal{G} \llbracket \Gamma \rrbracket$, we have to prove that $\left(\langle\delta(\mathrm{c})[(\mathrm{M}\{\delta\})]\rangle,\langle\Delta \mid \perp\rangle,\left\langle\mathrm{L}^{\prime} ; \mathrm{D}\right\rangle\right) \in \mathcal{O}$. From $\mathrm{L} ; \Gamma \vDash \mathrm{M}: \sigma$, we get that $\left(\mathrm{M} ; \mathrm{L}^{\prime} ; \mathrm{D} ; \Delta\right) \in \mathcal{E} \llbracket \sigma \rrbracket$, and from $\left(\delta ; \mathrm{L}^{\prime} ; \mathrm{D} ; \Delta\right) \in \mathcal{G} \llbracket \Gamma \rrbracket$ we get that $(\delta(\mathrm{c}) ; \mathrm{L} ; \mathrm{D} ; \mathrm{c}$ : $\neg \sigma) \in \mathcal{K} \llbracket \neg \sigma \rrbracket$, which is enough to conclude.

Lemma 93. L; $\Gamma \neq[\mathrm{c}] \bullet: \Gamma(\mathrm{c})$
Proof. Let us take $\Theta,\left(\mathrm{L}^{\prime} ; \mathrm{D}\right) \supseteq(\mathrm{L} ; \mathrm{L})$, and $\delta$ such that $\left(\delta ; \mathrm{L}^{\prime} ; \mathrm{D} ; \Theta\right) \in \mathcal{G} \llbracket \Gamma \rrbracket$. Then by definition of $\mathcal{G} \llbracket \Gamma \rrbracket,\left(\delta(\mathrm{c}) ; \mathrm{L}^{\prime} ; \mathrm{D} ; \Theta\right) \in \mathcal{K} \llbracket \Gamma(x) \rrbracket$.

Theorem 94 (Fundamental property). If $\Sigma ; \Gamma \vdash \mathrm{M}: \sigma$ then $\operatorname{dom}(\Sigma) ; \Gamma \vDash \mathrm{M}$ : $\sigma$. If $\Sigma ; \Gamma \vdash \mathrm{E}: \neg \sigma$ then $\operatorname{dom}(\Sigma) ; \Gamma \vDash \mathrm{E}: \sigma$.

Proof. By induction over the derivation $\Sigma ; \Gamma \vdash \mathrm{M}: \sigma$ or $\Sigma ; \Gamma \vdash \mathrm{E}: \neg \sigma$, each rule having a corresponding compatibility lemma proven above.

From it, we deduce a proof of Lemma 11. Indeed, taking an active POGS configuration $\mathbb{G}=(\langle M\rangle,\langle\Delta \mid \perp\rangle\langle L ; D\rangle)$, then $\widehat{\mathrm{L}} ; \Delta \vdash \mathrm{M}: \perp$. So from Theorem 94, we get that $\mathrm{L} ; \Delta \vDash \mathrm{M}: \perp$. Writing $\delta$ that the identity substitution $\Delta \vdash \delta: \Delta$ that maps any function or continuation name in $\operatorname{dom}(\Delta)$ to itself, we get from Lemma 84, that $(\delta ; \mathrm{L} ; \mathrm{D} ; \Delta) \in \mathcal{G} \llbracket \Delta \rrbracket$. So we conclude that $(\mathrm{M} ; \mathrm{L} ; \mathrm{D} ; \Delta) \in \mathcal{E} \llbracket \perp \rrbracket$. Thus, $\mathbb{G} \in \mathcal{O}$. A similar reasoning applies to passive POGS configurations.

