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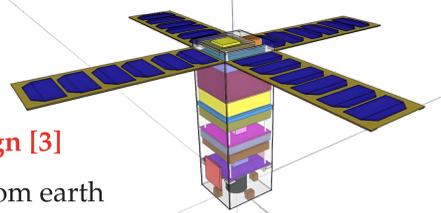
# Fast Meteor Detection Toolbox

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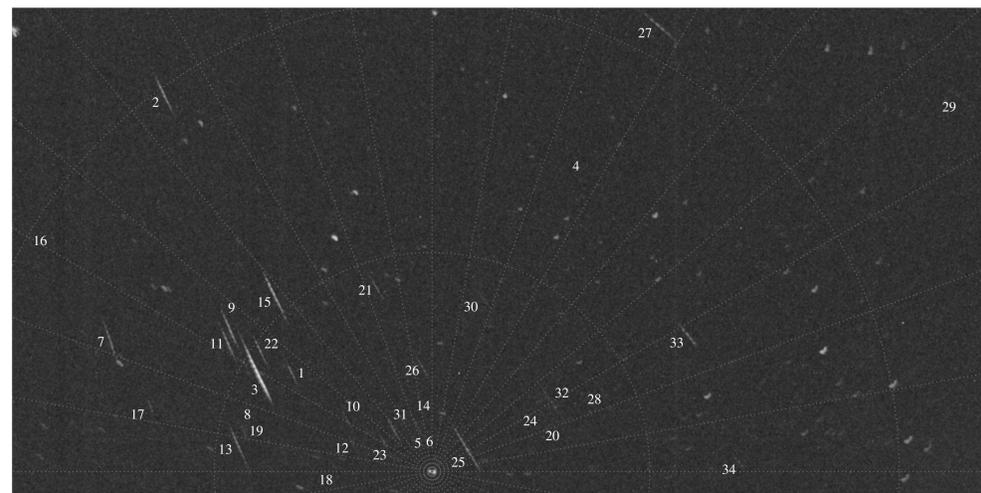


## CONTEXT

- **Detection and characterization of meteoroids** and space debris that enter into our atmosphere
  - From satellite (CubeSat) [1, 2]
  - From weather balloon
  - **From aircraft observation campaign [3]**
- Better observation conditions than from earth
- Greyscale input videos, output tracks (= positions of meteors)
- **Real-time constraints & Challenges**
  - Non-stabilized cameras, noisy video sequences
  - Limited computational power:  $\lesssim 10$  Watts
  - **Embedded systems** (RPI, Jetson, ...) & RISC architectures [4]
- LIP6/ALSOC & IMCCE joint-team: <https://www.imcce.fr/recherche/campagnes-observations/meteors/2022the>

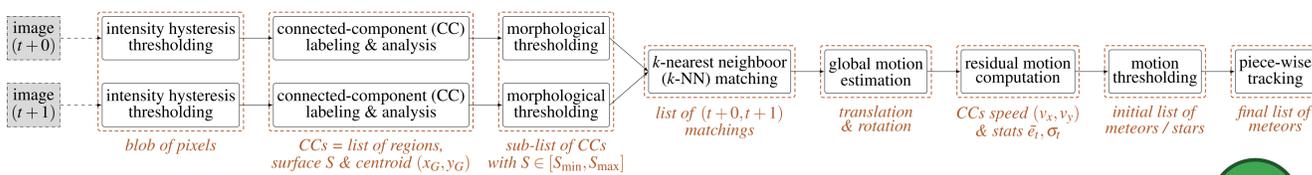


## 2022 $\tau$ -HERCULIDS METEOR CLUSTER



Composite closeup view of the 34  $\tau$ -Herculids meteor cluster (duration: 7.5 s) from an airborne observation campaign [3]. Center: *Ursa Minor* constellation.

## FMDT: COMPUTER-VISION DETECTION CHAIN

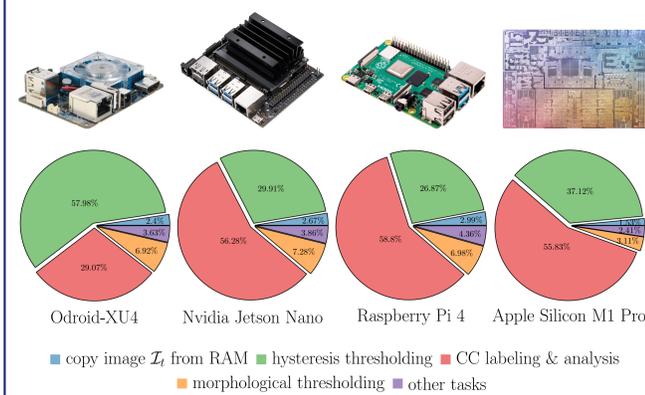


Computer-vision detection detailed chain.

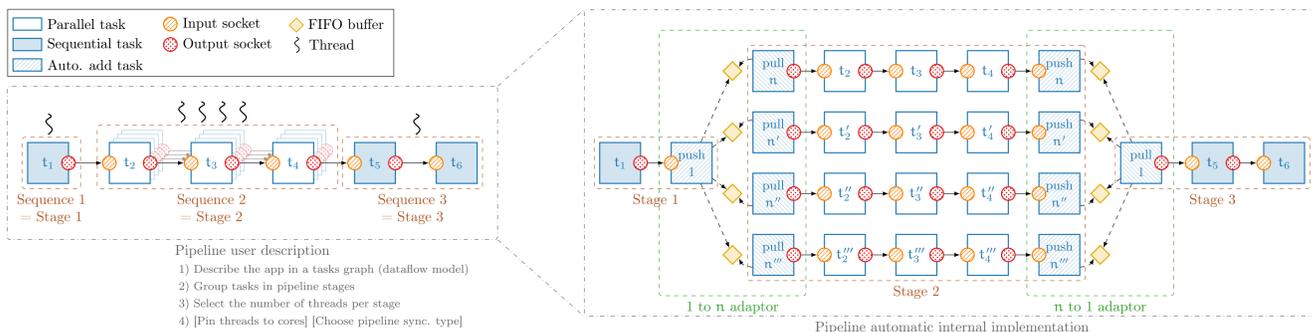
- Source code available on GitHub: <https://github.com/alsoc/fmdt>



## SEQUENTIAL TIME DISTRIBUTION



## TASKS GRAPH AND MULTI-THREADING WITH AFF3CT

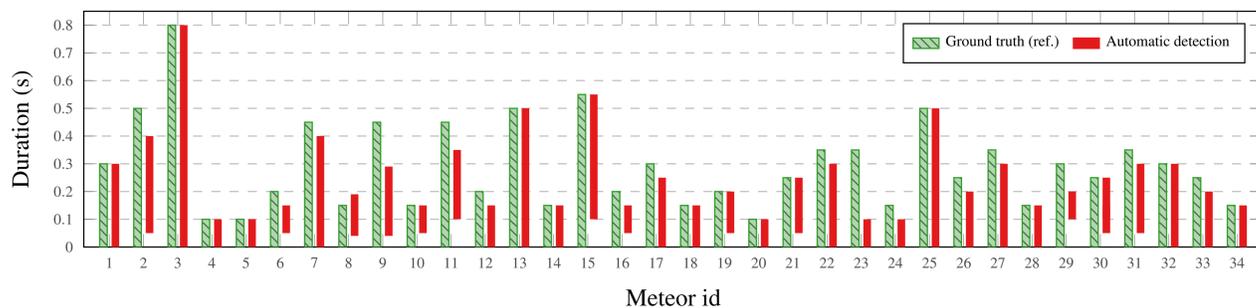


AFF3CT pipeline parallel construct.

A **3-stage pipeline** using the AFF3CT DSEL [5] has been implemented:

- 1) Copy image  $\mathcal{I}_t$  (sequential stage)
  - 2) Costly processing tasks from hysteresis to morphological thresholding (**parallel stage**)
  - 3) Lightweight processing tasks from  $k$ -NN to tracking (sequential stage)
- Design choice: most tasks of stage 3 are parallel but they are run on a single thread
    - Image processing results from  $\mathcal{I}_t$  are **memorized** for iteration  $t + 1$
    - **Dependency**: stage 3 tasks require memorized  $t - 1$  statistics
  - **Tracking is mainly a sequential task**, history management of statistics

## METEORS AUTOMATIC DETECTION EFFICIENCY



## REFERENCES

- [1] N. Rambaux et al. Meteorix: a CubeSat mission dedicated to the detection of meteors. In *COSPAR*, 2018.
- [2] M. Millet et al. Meteorix: High performance computer vision app. for Meteor detection from a CubeSat. In *COSPAR*, 2022.
- [3] J. Vaubaillon et al. A 2022  $\tau$ -herculid meteor cluster from airborne experiment: automated detection, characterization and consequences for meteoroids. *Astronomy & Astrophysics*, September 2022. (Submitted).
- [4] L. Lacassagne and B. Zavidovique. Light Speed Labeling for RISC architectures. In *ICIP*. IEEE, 2009.
- [5] A. Cassagne et al. A DSEL for high throughput and low latency software-defined radio on multicore CPUs. *Wiley Concurrency and Computation: Practice and Experience*, July 2022. (Submitted).

## EXPERIMENTATION RESULTS

- Video resolution: **1920x1200 (HD)**
- GNU compiler: `-O3 -march=native`
- **Odroid-XU4** – Feb. 2016 – 28 nm proc.
  - 4  $\times$  **LITTLE ARMv7 Cortex-A7** CPU @ 1.4 GHz
  - 4  $\times$  **Big ARMv7 Cortex-A15** CPU @ 1.5 GHz

	Conf. <sup>†</sup>	FPS	$\mathcal{L}$ (ms)	$\mathcal{E}$ (mJ)	$\mathcal{P}$ (W)
Seq.	<i>LITTLE</i>	7	142.6	403.7	2.82
Seq.	<i>Big</i>	14	70.4	274.6	3.88
Pip.	1L/4L/1L	26	361.8	153.1	4.04
Pip.	1B/4B/1B	42	216.1	159.9	6.74
Pip.	1/8/1	59	324.0	127.5	7.53

- Nvidia **Jetson Nano** – Mar. 2019 – 20 nm proc.
  - 4  $\times$  **ARMv8 Cortex-A57** CPU @ 1.479 GHz

	Conf. <sup>†</sup>	FPS	$\mathcal{L}$ (ms)	$\mathcal{E}$ (mJ)	$\mathcal{P}$ (W)
Seq.	–	34	29.0	114.9	3.93
Pip.	1/2/1	66	76.5	77.8	5.21
Pip.	1/4/1	91	98.5	68.1	6.25

- **RaspberryPi 4** model B – Jun. 2019 – 28 nm proc.
  - 4  $\times$  **ARMv8 Cortex-A72** CPU @ 1.5 GHz

	Conf. <sup>†</sup>	FPS	$\mathcal{L}$ (ms)	$\mathcal{E}$ (mJ)	$\mathcal{P}$ (W)
Seq.	–	20	48.7	156.5	3.19
Pip.	1/2/1	28	181.9	130.5	3.75
Pip.	1/4/1	30	310.8	123.4	3.79

- Apple Silicon **M1 Pro** – Oct. 2021 – 5 nm proc.
  - 2  $\times$  **E-core ARMv8 Icestorm** CPU @  $\approx 2.0$  GHz
  - 8  $\times$  **P-core ARMv8 Firestorm** CPU @  $\approx 3.0$  GHz

	Conf. <sup>†</sup>	FPS	$\mathcal{L}$ (ms)	$\mathcal{E}$ (mJ)	$\mathcal{P}$ (W)
Seq.	<i>E-core</i>	60	16.1	34.0	2.04
Seq.	<i>P-core</i>	206	4.8	30.4	6.27
Pip.	1E/2E/1E	118	42.0	19.7	2.33
Pip.	1P/2P/1P	409	12.4	25.8	10.55
Pip.	1/8/1	1280	14.6	21.8	27.98

<sup>†</sup> Pipeline config.: [stage 1, # of threads] / [stage 2, # of threads] / [stage 3, # of threads]  
FPS: frames per sec.,  $\mathcal{L}$ : latency per frame,  $\mathcal{E}$ : energy consumption per frame,  $\mathcal{P}$ : instant power