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## A COMPOUND POLARIMETRIC-TEXTURAL APPROACH FOR UNSUPERVISED CHANGE DETECTION IN MULTI-TEMPORAL FULL-POL SAR IMAGERY

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### ABSTRACT

Change Detection represents a relevant topic for the analysis of multi-temporal analysis of Polarimetric SAR (PolSAR) data. However, most of the CD approaches for PolSAR imagery do not take into account textural information, which can be useful for have larger performance robustness. In this work, we propose a novel approach for unsupervised change detection considering polarimetric and textural information from multi-temporal PolSAR imagery. The approach is based on the joint use of features from coherency matrix and gradient tensor and the definition of a multi-temporal distance. A binary unsupervised thresholding is used for discriminating change and no-change classes. Experimental results obtained on a multi-temporal PolSAR dataset over Los Angeles area illustrate the effectiveness of the proposed approach.

*Index Terms*— Polarimetric SAR, change detection, gradient tensor, unsupervised detection

#### 1. INTRODUCTION

Multi-temporal environmental monitoring plays an important role in remote sensing, with different applications associated both to natural and urban scenes [1]. This makes Change Detection (CD) one of the hot topics for the remote sensing imagery. In particular, the large amount of data available from satellite and airborne sensors drives the research towards the development of automatic CD strategies.

Polarimetric SAR (PolSAR) represents one of the most interesting sensors for CD applications, as it is a microwave active system that guarantees acquisitions for all light and weather conditions with large scattering information. A large effort in the literature has been devoted to the development of classification techniques based on PolSAR imagery [2]. A smaller effort has been spent in the development of PolSARbased CD strategies, based on the scattering information of the single pixel. These are typically based on the definition of the log-likelihood ratio [3], statistical modeling [4] or polarimetric distance measures [5, 6]. However, texture represents an additional information source for target discrimination in SAR imagery. Some of state-of-the-art texturebased classification approaches considers the combination of the radiometric information with textures from Gray Level Co-occurrence Matrix (GLCM) [7], Gabor filters [8] or gradient tensors [9, 10]. To the best of our knowledge, a very small effort has been spent in combining radiometric and textural information for CD in PolSAR data. In this work, we present a novel CD approach from multi-temporal PolSAR images. The approach considers a weighted multi-looking of the coherency information in both pre- and post-event. Next, a feature vector for the two images is built by considering both the radiometric and the textural information The radiometric information is given by the multi-looked terms of the covariance matrix. The textural information is given by the gradient tensors of the covariance matrix, extracted based on the min-ratio operator along multiple directions [10]. A statistical distance between the two feature vectors is defined as a Change Index (CI) and thresholded.

The reminder of this paper is organized as follows. Section 2 describes the proposed methodology for the PolSAR based change detection. Section 3 provides some experimental results on a full-pol dataset from UAVSAR sensor. Section 4 presents the conclusions and possible future developments of the proposed work.

### 2. METHODOLOGY

Let us consider two images from PolSAR sensor acquired on two times  $t_1, t_2, t_1 < t_2$ , respectively. The proposed approach aims at identifying the set of changed and unchanged pixels, associated to classes  $\omega_c, \omega_u$ , respectively. Fig. 1 shows the block scheme for the proposed approach. Four main stages are composing the scheme, namely: i) generation of the multi-look Coherency matrix for single-time images; ii) generation of the texture descriptors for the single-time images, based on the De Zenzo gradient tensor [10]; iii) definition of the CI feature; iv) thresholding and generation of the CD map.

#### 2.1. Estimation of multi-look weighted coherency

Let us consider a PolSAR image acquired at time  $t_i$ , i = 1, 2. PolSAR measures complex scattering by transmitting and/or receiving radiation on multiple polarizations (e.g., H and V

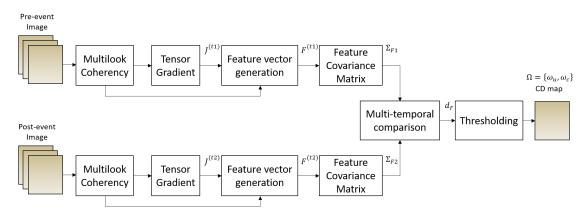


Fig. 1: Block scheme for the proposed approach.

linear polarizations). The complex information can be represented, under the Pauli basis, in form of a scattering vector  $k_p = [S_{hh}]$ , being the  $S_{pq}$  the complex scattering coefficient measured transmitting on polarization q and receiving on polarization q [11]. The scattering vector is a proper descriptor for coherent targets, but it fails in presence of distributed targets, where the scattering of each cell is composed by terms associated to multiple scatterers. In this case, the scattering information is described by a second-order statistics as the hermitian Coherency matrix T.

$$T = \frac{1}{L} \sum_{L} k_{P} k_{P}^{H} = \begin{bmatrix} T_{11} & T_{12} & T_{13} \\ T_{21} & T_{22} & T_{23} \\ T_{31} & T_{32} & T_{33} \end{bmatrix}$$
(1)

being  $k_P = \frac{1}{\sqrt{(2)}} [S_{HH} + S_{VV}; S_{HH} - S_{VV}; 2S_{HV}]$  the scattering vector in the Pauli basis and  $(\cdot)^H$  the hermitian operator.

#### 2.2. Texture description based on gradient tensor

Texture information can be often considered as a precious support for making image analysis more robust by taking into account neighborhood information. In the literature, several texture descriptors have been defined, in terms of transform domain [12], image statistics [13] or GLCM [7]. In this work, a gradient tensor measure is selected as texture descriptor for multi-channel data, thanks to its small computational cost and the possibility to extract inter-channel correlation information on the gradient coefficients. Let I be a data-cube containing the independent elements of the T hermitian matrix.

$$I = [|T_{11}|, |T_{12}|, |T_{13}|, |T_{22}|, |T_{23}|, |T_{33}|]$$
(2)

Let  $I_i$  be the *i*-th channel of *I*. For each position (x, y), spatial derivatives of *I* along x- and y-axis, namely  $I_{ix}$  and  $I_{iy}$ , are derived. From the derivatives, a gradient tensor *J* is obtained by summing the derivative information along the different im-

age channels.

$$J = \begin{bmatrix} \sum_{i=1}^{6} (I_{ix})^2 & \sum_{i=1}^{6} I_{ix}I_{iy} \\ \sum_{i=1}^{6} I_{ix}I_{iy} & \sum_{i=1}^{6} (I_{iy})^2 \end{bmatrix} = \begin{bmatrix} J_{11} & J_{12} \\ J_{21} & J_{22} \end{bmatrix}$$
(3)

Because of the SAR image statistics, a min-ratio operator is considered for computing the spatial derivatives with respect to pixel neighborhood.

$$I_{ix}(x,y) = 1 - \min\{\frac{I_i(x+1,y)}{I_i(x-1,y)}, \frac{I_i(x-1,y)}{I_i(x+1,y)}\}$$
(4)

$$I_{iy}(x,y) = 1 - \min\{\frac{I_i(x+1,y)}{I_i(x,y-1)}, \frac{I_i(x,y-1)}{I_i(x,y+1)}\}$$
(5)

#### 2.3. Generation of the combined change index

Based on the texture-based global information in J and polarimetric pixel-based information in T, a feature vector Fis constructed. In order to reduce the dimensionality of the vector, while keeping most of the information, just diagonal elements from T are considered.

$$F = \left[\sqrt{|T_{11}|}, \sqrt{|T_{22}|}, \sqrt{|T_{33}|}, |J_{11}|, |J_{12}|, |J_{22}|\right]$$
(6)

In order to consider the local dispersion of the vector F, covariance matrix  $C_F$  is considered. This is estimated on a moving square window around pixel (x, y), as follows:

$$\Sigma_F(x,y) = \frac{1}{K-1} \sum_{i \in N_i} (F_i - \mu_F)^T (F_i - \mu_F)$$
(7)

being  $\mu_F = \frac{1}{K-1} \sum_{i \in N_i} F_i$  the vector mean. Let  $\Sigma_{F1}, \Sigma_{F2}$  be feature covariance matrices obtained at times  $t_1, t_2$ , derived from vectors  $F^{(t1)}, F^{(t2)}$ , respectively. A multi-temporal compound change index  $d_F$  is defined as log-euclidean distance of the two single-time vectors.

$$d_F = \|\log(C_{F2}) - \log(C_{F1})\|_F$$
(8)

On one hand,  $d_F$  shows high values in presence of changes, because of the large distances between the two covariance matrices. On the other hand, it shows values close to zero for unchanged targets.

#### 2.4. CI thresholding and generation of the CD map

An unsupervised strategy for the detection of changed areas is applied on  $d_F$ , considering the binary problem with classes  $\omega_u, \omega_c$ . In particular, Otsu thresholding is considered as thresholding strategy. For binary Otsu thresholding, the probability density function of  $d_F$  can be modeled as a mixture of two components:

$$P(d_F) = P(\omega_u)p(d_F|\omega_u) + P(\omega_c)p(d_F|\omega_c)$$
(9)

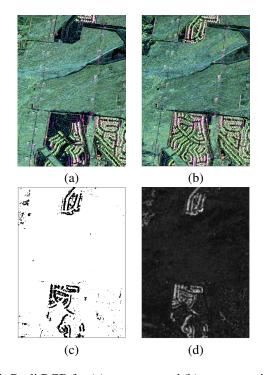
being  $P(\omega), p(d_F|\omega)$  the prior probability and the marginal distribution for the class  $\omega, \omega \in \{\omega_u, \omega_c\}$ . An optimal threshold  $d_{FT}$  is selected by minimizing the weighted sum of class variance for the two classes  $var(\omega_u), var(\omega_c)$ .

$$d_F = \arg\min_{d_F} \left[ P(\omega_u) var(\omega_u) + P(\omega_c) var(\omega_c) \right]$$
(10)

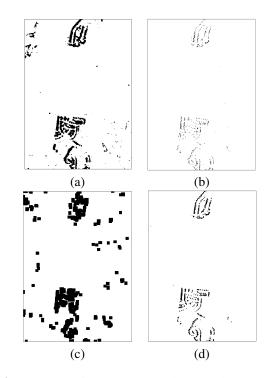
#### **3. EXPERIMENTAL RESULTS**

A validation campaign for the proposed approach has been conducted with a full-polarimetric multi-temporal dataset acquired by UAVSAR mission over Los Angeles, California (U.S.A.). The two images, acquired in 2009 (see Fig. 2a) and 2015 (see Fig. 2-b), have size  $559 \times 400$  pixels and show changes due to urbanization phenomenon, with the creation of new urban areas and the removal of vegetated areas for future built-up areas. The two images have been both acquired with a spatial resolution of  $0.4 \times 1.6$  meters and pre-processed with calibration and co-registration. Fig. 2-c shows the reference map obtained by photo-interpretation of the Pauli RGB of the single-time PolSAR images. The proposed approach has been compared with other state-of-the-art CD techniques based on full-polarimetric imagery. In particular, several techniques were considered, namely a Log-Likelihood Ratio (LLR) test [3], the Hotelling-Lawley trace (HLT) [14] and PCA-based K-means based of geodesic distance measure (GD-PCAK) [5]. For all the approaches, performance has been evaluated in terms of overall accuracy OA ad Cohen's coefficient Kappa.

For both single-time images, coherency matrix has been generated, resulting in a final multi-looking resolution of  $3 \times 3$  meters. Gradient tensor has been computed and diagonal components have been used to create the vectors  $F^{(t1)}$ ,  $F^{(t2)}$ . Feature covariance matrices  $\Sigma_{F1}$ ,  $\Sigma_{F2}$  have been derived by considering a local neighborhood of  $7 \times 7$  pixels. Fig. 3a shows the output CD map. Good detection performance can be inferred from its comparison with the reference map. In particular, a good tradeoff in terms of detail preservation and homogeneity for the changed regions is inferred. This resulted in numerical values OA = 0.9728 and Kappa =0.7133 (see Table 1). Table 2 illustrates the performance comparison of the proposed approach with respect to the literature. The proposed approach shows an increment of 0.5% for OA and 21% for Kappa with respect to LLR approach (see



**Fig. 2**: Pauli RGB for (a) pre-event and (b) post-event image; (c) reference map; (d) log-euclidean distance  $d_F$ .



**Fig. 3**: CD Map using: (a) proposed approach; (b) HLT; (c) GD-PCAK; (d) LLR.

Fig. 3-d). Larger improvements are registered with respect to the HLT (see Fig. 3-b) and the GD-PCAK (see Fig. 3-c).

 Table 1: Confusion Matrix for the proposed approach.

	$\hat{\omega}_u$	$\hat{\omega}_c$
$\omega_u$	209403	3082
$\omega_c$	2997	8118
	OA	0.9728
	Карра	0.7133

Table 2: Overview of Performance assessment.

Method	OA	Kappa
Proposed	0.9728	0.7133
HLT	0.9564	0.2112
LLR	0.9673	0.4989
GD-PCAK	0.9115	0.4067

#### 4. CONCLUSIONS

In this work, a novel CD approach for multi-temporal Pol-SAR images has been presented. The method considers the use of overall gradient tensor information from multiple polarimetric channels. A multi-temporal distance measure is based on compound textural-polarimetric features from the single-time matrices and thresholded for obtaining the final CD map. Preliminary experimental results show good detection capabilities, with performance larger than other literature techniques. Future developments aim at analyzing the distance measure based on the PolSAR image statistics and integrating advanced polarimetric features in the approach.

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