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▶ To cite this version:

Qin Liu, Sylvie Janicot, Patrick Georges, Gaëlle Lucas-Leclin. Coherent combination of micropulse semiconductor amplifiers for water vapor differential absorption lidars. Optics Letters, 2023, 48 (2), pp.489-492. 10.1364/OL.481895 . hal-03922039

HAL Id: hal-03922039 https://hal.science/hal-03922039v1

Submitted on 12 Jan2023

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Coherent combination of micropulse tapered amplifiers at 828 nm for direct-detection lidar applications

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Compiled December 19, 2022

We report on the design of a compact master oscillator power amplifier (MOPA) diode laser architecture at 828 nm suitable for direct-detection lidars, specifically applied to water vapor differential absorption lidars. Coherent beam combination of two pulsed high-brightness tapered amplifiers (1 µs, 10 kHz), seeded by a DBR laser diode, is demonstrated. The phase dynamics during the pulses have been thoroughly investigated. The main limitation to the CBC efficiency is quantified. The maximum combined pulse energy reaches 10.3 µJ with combining efficiency above $82\% \pm 5\%$. © 2022 Optica Publishing Group

2 http://dx.doi.org/10.1364/ao.XX.XXXXXX

1. INTRODUCTION

Continuous monitoring of atmospheric parameters and compo-5 nents is highly demanded in the atmospheric science community. 6 Lidar is one of the key atmospheric remote-sensing techniques due to its ability to deliver high-resolution measurements[1]. Differential absorption lidars (DIAL) can provide a self-calibrated, range-resolved atmospheric components mapping with a rel-10 atively low-power laser source[2]. It requires a pulsed laser 11 source with high spectral purity, which operates at two wave-12 lengths - one at the absorption line and the other away from 13 it[2]. In recent years, diode-laser-based DIAL architectures for 14 water-vapor measurements have been constructed[3, 4], which 15 have demonstrated long-term autonomous operations under a 16 wide range of atmospheric conditions [4, 5]. They utilize two 17 DBR diode lasers operating at 828.187 nm and 828.287 nm to 18 inject one tapered semiconductor optical amplifier (TSOA) al-19 ternatively. The transmitted pulse energy reaches 5 µJ, which is 20 limited by the maximum peak power that can be extracted from 21 a TSOA. Though this is adequate in ground-based platforms, a 22 higher pulse energy would be required for an airborne system 23 to achieve a high-resolution measurement along the airplane 24 traveling axis. The pulse energy can be further increased by 25 combining beams from multiple emitters. Among the different 26 beam-combining techniques that have been investigated[6], co-27 herent beam combination (CBC), which is based on the construc-28 tive interference of coherent beams, is the only approach that 29 preserves the spectral purity as well as the beam quality of the 30

initial emitters[7, 8]. With careful phase control and superposition of the beams, the combined output would increase in power. Coherent combination of diode lasers has been demonstrated in continuous-wave (CW) operation with up to 47 edge-emitting ridge-waveguide amplifiers resulting in a combined power of 40 W at 1064 nm[9]. CBC of TSOAs has also been achieved in CW operation, and in pulsed regime with millisecond-long pulses[10]. A maximum CW power of 17 W was demonstrated with only 4 coherently combined TSOAs seeded by a DFB laser diode at 976 nm. In pulsed operation (2 ms - 50 Hz), the peak power could be increased up to 23 W. It is noteworthy that under pulsed operation, diode laser devices experience temperature and carrier dynamics. Therefore, the beam properties and the accumulated phase are not steady during the pulse. It makes the phase-locking and coherent superposition of the beams more challenging.

In this paper, we demonstrate for the first time the coherent beam combination under a µs-pulse regime of two TSOAs operating at 828 nm. The phase dynamics through the TSOAs during the optical pulse are investigated. The phase difference between the amplified beams is actively locked to maximize the combined pulse energy. The experimental combining efficiency is evaluated and compared to theoretical estimations to understand its limitation. Eventually, the mid-term average power stability is measured. The CBC architecture is shown as an innovative approach for the future development of high peak-power diode-laser-based pulsed sources as those required in direct-detection lidars.

2. DESCRIPTION OF EXPERIMENTAL SETUP

The MOPA architecture applied in this work is shown in figure 1. The seed laser source (MO) is a DBR laser diode (Photodigm, Inc., PH828DBR180T8) operated in CW mode with a maximal operation power of 235 mW. It has a narrow spectral linewidth (\leq 5 MHz), as measured from the frequency noise spectral density in an integration time of 1 ms. The central wavelength is 828 nm and can reach the online and offline wavelengths of water absorption features by temperature tuning. The seed beam is collimated and optically isolated (>60 dB) to prevent power and spectral instabilities induced by optical feedback. The beam is coupled into a polarization-maintaining (PM) single-mode fiber connected to a 90:10 PM fiber coupler. The 10% output is utilized for seed power and wavelength monitoring. The 90% output is connected to a 50:50 PM fiber coupler to inject the two

power amplifiers (A_1 and A_2). The power amplifiers are com- 118 74 mercial tapered semiconductor optical amplifier devices (TSOA, 75 119 Eagleyard Photonics, EYP-TPA-0830) centered at 830 nm. They 76 120 consist of a single-mode ridge-waveguide section followed by a 77 121 flared section. Their output electric fields are linearly polarized, 78 122 and parallel to their junction plane. Under CW operation, the 79 123 maximum output power is 1.1 W at 3 A. The fiber-coupled seed 80 beams are collimated by fiber collimators (Thorlabs, F280APC-¹²⁴ 81 850, L₃: $f_3 = 18.45$ mm) and coupled into the ridge section of the 125 82 two TSOAs by aspheric lenses (L₄: $f_4 = 8$ mm). Each TSOA is ¹²⁶ 83 electronically driven by a commercial current driver (PicoLAS, 127 84 LDP-V 50-100) with 1 µs pulse duration, 10 kHz repetition rate, ¹²⁸ 85 and pulse rise time of 40 ns (see figure 2). Due to the low opera-¹²⁹ 86 tion duty cycle (1%), TSOAs can be overdriven to high currents ¹³⁰ 87 131 beyond their specifications without thermal rollover effects. 88 132

The amplifier peak output power P_{out} follows closely the 89 133 relationship $P_{out} = G_0(I) \times P_{in}/(1 + P_{in}/P_{sat})$ where $G_0(I)$ is 90 134 the small-signal gain at the driving current I, P_{in} is the injection 91 135 power and P_{sat} is the saturation power. P_{sat} is below 4 mW 92 136 under our typical operating conditions. The input power P_{in} is 93 137 chosen at about 24 mW for each TSOA in order to saturate the 94 amplifier and maximize the output power. The maximal peak 95 139 power reaches 6.7 W (corresponding to a pulse energy of 6.7 96 140 μ J) at a current of 8.1 A. The slope efficiency of the individual ₁₄₁ 97 amplified beams remains constant at about 1.1 W/A throughout 142 98 our range of driving currents. The astigmatic amplified beams 99 143 are collimated in the fast axis (FA) by aspheric lenses (L_5 : $f_5 =$ 100 144 2.75 mm) and in the slow axis (SA) by cylindrical lenses (L_6 : f_6 = 101 145 12.7 mm). The lens positions are carefully aligned to maximize 102 146 the overlap of the amplified beams of the two TSOAs at 5.3 A. A 103 6-axis high-precision mounting stage is used for the alignment 104 of all lenses before they are glued into place to obtain long-term 105 operation stability of the laser source. The collimated beams are 106 slightly multimode with $M^2_{4\sigma}$ factors $\leq 3.2 \times 1.6$ at 5.3 A. 107

147 The amplified beams are recombined using a Mach–Zehnder 108 148 interferometer architecture and superposed on a non-polarizing 109 149 50:50 beamsplitter in free space. The piston phase difference 110 varies with time due to thermal and acoustic noises both in the 150 111 TSOAs and in the environment. It can be corrected by actively 151 112 controlling the path difference between the two interferometer 152 113 arms. The TSOAs and the CBC sections including fiber collima- 153 114 tors, and coupling optics are mounted on a 22 cm imes 18 cm imes154 115 0.6 cm aluminium breadboard which is thermally controlled by 116 Peltier elements. 117



Fig. 1. Diode-laser-based source with coherent beam combination of two high brightness tapered amplifiers (A_1 and A_2).

3. EVALUATION OF SYSTEM PERFORMANCE

A. Phase dynamics during the pulse

The phase dynamics during the pulses were measured by interfering each amplified beam independently with the 10% output of the coherent seed beam. The CW seed beam was circularly polarized by a quarter wave plate, and superposed with the amplified beam on a polarizing beamsplitter. Then the in-phase signal (I) and quadrature signal (Q) are measured separately and the phase evolution $\phi(t)$ is deduced from $\arctan(Q(t)/I(t))$ [11]. Figure 2 shows the resulted phase drifts experienced by the amplified beams at 2.2 A, 5.3 A, 6.9 A, and 8.1 A. The phase drift evolves almost linearly after the first 50 ns of pulse, which is attributed to the temperature evolution of the device[12]. The positive phase drift measured within the first 50 ns of the pulse could be contributed to the high-frequency current modulation at the beginning of the pulse and measurement errors due to the rapid change of pulse power. The consistency of our phase evolution measurement is validated by overlapping 20 consecutive measurements at 8.1 A. The relative phase difference, or the envelope magnitude of the overlapped data points, is in the range of 0.11 π on average. Hence, the phase drift during the pulse is repeatable from pulse to pulse. At 8.1 A, the amplitude of the phase change reaches 4.6 π .

Although the phase drift during the pulse is large in magnitude, its evolution is similar between the two TSOAs. The maximal phase drift difference is 0.17 π at ~5.3 A as shown in figure 2. To evaluate the effect of this piston phase mismatch during the pulse, the temporal power profile of coherently combined pulses $P_{CBC}(t)$, defined as

$$P_{CBC}(t) = \frac{1}{2}(P_1(t) + P_2(t) + 2\sqrt{P_1(t) \times P_2(t)} \times \cos(\phi_1(t) - \phi_2(t)))$$
(1)

is calculated from the individual amplified pulse profiles $P_1(t)$ and $P_2(t)$ and the phase evolutions $\phi_1(t)$ and $\phi_2(t)$ in figure 2. The CBC efficiency $\eta_{CBC} = E_{CBC}/(E_1 + E_2)$, based on the pulse energy $E_n = \int_0^{1\mu s} P_n(t) dt$, remains high during the pulse with an average efficiency of 98% at 5.3 A. It confirms that the phase mismatches between the two TSOAs during the 1 µs-pulses are small enough and will not deteriorate significantly the overall combining efficiency.



Fig. 2. a) The phase evolution during the pulse experienced by the amplified beams at 2.2 A, 5.3 A, 6.9 A, and 8.1 A with a magnitude of 0.7 π , 2.3 π , 3.5 π , and 4.6 π respectively. The pulse shape (red) is plotted for reference. b) Phase drifts experienced by the amplified pulses of A₁ and A₂ at ~5.3 A. The resulting combined pulse profile (brown) is calculated using eq.(1) from the pulse temporal profiles and phases.

155 B. Analysis of beam profiles

The spatial overlap of the two amplified beams on the combining
element - both in intensity and phase - is the most impacting
parameter on the coherent combining efficiency of two beams in
Club beams in the coherent combining efficiency of two beams in

¹⁵⁹ a filled-aperture architecture. The local CBC efficiency $\eta_{local}(x, y)$ ¹⁶⁰ is given by

$$\eta_{local}(x,y) = \frac{1}{2} \frac{|\sqrt{I_1(x,y)}e^{i\phi_1(x,y)} + \sqrt{I_2(x,y)}e^{i\phi_2(x,y)}|^2}{|\sqrt{I_1(x,y)}e^{i\phi_1(x,y)}|^2 + |\sqrt{I_2(x,y)}e^{i\phi_2(x,y)}|^2}$$
(2)

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and the overall combining efficiency η_{CBC} is computed by an intensity-weighted average of the local CBC efficiency over the whole intensity profile[8]:

$$\eta_{CBC}^{spatial} = \frac{\int \int \left[(I_1(x,y) + I_2(x,y)) \times \eta_{local}(x,y) \right] dxdy}{\int \int \left[I_1(x,y) + I_2(x,y) \right] dxdy}$$
(3)

The far-field intensity profiles $I_n(x, y)$ of the two amplified 208 164 beams A_1 and A_2 were captured with a CMOS camera at 40 209 165 cm after the beamsplitter for an integration time of 40 ms (fig- 210 166 ure 3). These images are thus the time average measurements 211 167 of a few hundred pulses. On the other hand, because of the 212 168 existence of side lobes in the slow-axis profile intrinsically in- 213 169 duced by the tapered sections, the phase distribution of the full 214 170 beams $\phi_n(x, y)$ cannot be correctly deduced with a wavefront 215 171 sensor. We assumed here a perfect overlap of the phase profiles 216 172 $(\phi_1(x,y) = \phi_2(x,y))$. The local CBC efficiency $\eta_{local}(x,y)$ com- ²¹⁷ 173 puted at the driving current of 8.1 A is shown in figure 3.c. The 218 174 output powers of the two TSOAs differ by 10% since the driving 219 175 current of A_2 is slightly adjusted (± 5%) to maximize the phase 220 176 drift matching at high driving currents (see section 3.A). How- 221 177 ever, the power mismatch does not affect significantly the CBC 222 178 efficiency $\eta_{CBC}^{spatial}$. This value is estimated to be 94.0% which is ²²³ 179 an averaged combining efficiency rather than an instantaneous ²²⁴ 180 value during the pulse. The efficiency remains constant for all ²²⁵ 181 226 182 driving currents.

Considering both the temporal phase mismatch during pulses (see section 3.A) and the intensity overlap calculated here, we expect the experimental combining efficiency to be below 92%, as the spatial phase profile overlap was assumed perfect in our evaluation.



Fig. 3. Beam intensity profile of A_1 (a) and A_2 (b) and theoretical evaluation of CBC efficiency profile $\eta_{local}(x, y)$ (c) at 8.1 A.

C. Analysis of the phase stabilization operation

189 The synchronization of the two TSOA outputs is achieved by 251

externally triggering the currents through the two amplifiers, 252

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with a delay below 10 ns. Since the piston phase drifts during the pulses only slightly reduce the constructive interference efficiency (figure 2), correction of the phase during pulses is not needed. However, the phase matching can not be maintained from pulse to pulse due to low-frequency phase drifts of the whole interferometer, which lead to an unstable combined average power at a time scale > 1 s. Those slow phase fluctuations are corrected with a servo-loop which actively controls the interferometer arm length of A_1 . A small proportion of the combined beam is collected by the photodiode PhD₁ as an error signal and integrated by an RC circuit (cut-off frequency = 19 Hz). A hill-climbing algorithm is coded into a microcontroller whose voltage output controls the deformation of the piezoelectric transducer (PZT) attached to the folding mirror M₁ (figure The servo loop takes a local measurement of the combined power and calculates the slope of the combined power change after applying a small voltage perturbation every 65 ms. Therefore, the phase mismatch is corrected by searching for the combined power maximum, which corresponds to a zero slope. The servo loop correction frequency is 5 Hz. To reduce the voltage perturbation on the combined power, we applied a latency time of 260 ms when the power maximum is reached. Since the lowfrequency phase noise is dominated by thermal and acoustic noises (figure 4.c), the algorithm is sufficient to maintain phase matching and maximize the averaged combined pulse power.

The effect of phase stabilization at 6.9 A is demonstrated in figure 4 with the signals from the two photodiodes PhD_1 and PhD₂. PhD₁ measures the average combined power P_{CBC} = $E_{CBC} \times F_{rep}$, proportional to the mean energy per pulse E_{CBC} , whereas PhD₂ provides a time-resolved measurement of pulses. The combined pulse energy evolution over more than 1000 s with and without the stability control are shown in figure 4.a. The free-running system already exhibits good stability ($\sigma_{off} = 5.0\%$) due to the compactness and robustness of our architecture. The active phase stabilization further reduces the fluctuations to 0.4% for all operation currents, limited by the perturbation amplitude applied by the hill-climbing servo-loop. About 500 sets of combined pulses at 6.9 A recorded with PhD₂ are overlapped in the density plot (figure 4.b). The mean fluctuation between the measurements is 1.2% (control off 5.0%). The effect of the stabilization is further illustrated in the frequency domain with the relative intensity noise (RIN) power spectral density (PSD) of the average combined power with and without the servo-loop at 6.9 A (figure 4.c). The servo loop successfully corrects the low-frequency phase noise (< 0.5 Hz) with more than 20 dB of correction at f < 0.01 Hz. Extra perturbations at frequencies above 2 Hz are directly related to the stabilization algorithm with a peak at the correction frequency 5 Hz. However, the amplitude of the additional noises is much smaller than the environmental noises so the hill-climbing algorithm improves the system stability overall.

D. Coherent combining efficiency and pulse energy

The mean pulse energies of individual TSOAs, the mean combined pulse energies, and the corresponding combining efficiencies are measured from 2.2 A to 8.1 A (figure 5). The phase evolution during the pulses was matched by slight adjustments (\pm 5%) of the drive current of A₂. The maximum peak power in the combined beam reaches 10.3 W (energy per pulse = 10.3 µJ) at 8.1 A with individual amplifiers contributing 6.7 W. The combined peak power, compared with the micropulse DIAL with one TSOA[4], increases by almost a factor of two at the same operating current. The beam quality of the combined beam is



Fig. 4. a) Combined pulse energy evolution with (red) and without (black) active phase control during 1000 s of operation at 6.9 A measured by PhD₁. b) Density plot of \sim 500 sets of combined pulses during 1000 s measured by PhD₂. c) Relative intensity noise PSD of the stabilized (red) and free-running (black) power measurements (PhD₁).

²⁵³ comparable to the one of the individual beams [10].

300 The combining efficiency was evaluated by different methods, 254 301 such as the combined average power P_{CBC} and the pulse profiles 255 302 of the combined beam $P_{CBC}(t)$. The combining efficiency de-256 creases from $88\% \pm 4\%$ at 2.2 A to $82\% \pm 5\%$ at 8.1 A where the 257 303 uncertainties considered the discrepancies between the different 258 methods of efficiency evaluation. Those experimental values are 304 259 lower than the estimated CBC efficiency based on the intensity 305 260 profiles and residual temporal phase mismatches during pulses 306 261 (92% - see section B). It could be due to slight differences in beam 307 262 308 collimation and astigmatism correction which would impact the 263 309 spatial phases $\phi_n(x, y)$ and have not been considered earlier, 264 or a slight polarization misalignment. Therefore, although the 265 311 amplifiers may not have reached their optical power limit, we 266 312 did not over-drive them above 8.1 A to avoid further reduction 267 313 of the system efficiency and remain within a safe range of cur-268 314 rents below catastrophic optical damage threshold for long-term 315 269 robust operation. Still, the combining efficiency is comparable 316 270 to previous results with tapered devices even under different 317 271 318 temporal regimes[7, 10]. 272



4. CONCLUSION

In this paper, we demonstrate a compact diode-laser-based source in microsecond-pulsed operation using coherent combination of two pulsed-driven tapered amplifiers seeded by a single-frequency DBR laser diode. The phase dynamics and its impact on the combining efficiency are analyzed. The laser source reaches a peak power of 10.3 W (10.3 µJ energy per pulse) and can operate with high power stability (<0.4%) maintained by an active phase control loop. The spectral purity of the combined beam is assumed to be similar to the seed laser one, as it should not be deteriorated by the amplifiers[4] or the combining process. This laser architecture is thus fully compatible with integration in a micropulse DIAL instrument for atmospheric water vapor profiling. The performance obtained here already demonstrates the interest of coherent combining to increase the energy per pulse and improve the spatial resolution of a lidar. The CBC architecture can be adapted to different wavelengths for other direct-detection lidars. Further advancement in pulse energy can be achieved by the coherent combination of more amplifiers[10].

Funding. This project has received financial support from the CNRS through the MITI interdisciplinary programs.

Acknowledgments. We are grateful to J. Totems and P. Chazette (LSCE-UMR 1572/CEA-CNRS-UVSQ), and N. Amarouche (DT-INSU/CNRS) for fruitful discussions on the design of the DIAL system.

Disclosures. The authors declare no conflicts of interest.

Data availability. Data underlying the results presented in this paper are not publicly available at this time but may be obtained from the authors upon reasonable request.

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