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# Mean field approximation of an optimal control problem for the continuity equation arising in smart charging

Adrien Seguret \*

## Abstract

We consider the optimal control of a finite population of hybrid processes (namely agents state is composed of a discrete and a continuous variable), modeling the optimal charging of a large population of identical plug-in electric vehicles (PEVs). We prove the convergence of the solution and that of the value of a sequence of finite population problems respectively to a solution and the value of a mean field optimal control problem.

**Keywords:** Optimal control, hybrid state space, mean-field limit.

## 1 Introduction

This work is motivated by the optimal charging of a very large population of plug-in electric vehicles (PEVs) controlled by a central planner. Each PEV is characterised by two variables: a continuous one representing the state of charge (SoC) of the battery, and a discrete one denoting the mode of charging of the PEV (e.g. idling, charging, discharging, etc...). The central planner determines when and to which mode of charging of each PEV switches. In addition to the charging cost, the objective function also contain a term penalizing the switches, in order to avoid both excessive jumps per PEV and synchronization effects, i.e., simultaneous switches of a large proportion of PEVs. An optimization problem is considered, where the distribution of the population is subject to a congestion constraint to avoid large proportion of PEVs having the same regime. Such a control problem typically arises in parking lots powered by solar energy that can be found in malls, airports, stadiums, hospitals and other facilities with large parking areas [21]. Since the number  $n$  of PEVs is very large, both combinatorial techniques and optimal control tools may fail to solve the problems, due to the curse of dimensionality [5]. To overcome these difficulties, one can approximate the problem of  $n$  PEVs by considering a continuum of PEVs, leading to the techniques of optimal control of PDEs and those of convex optimization. The resulting limit mean field control problem was studied in [48] and numerically solved in [49]. Note that several articles have already dealt with smart charging problems within a mean field limit framework [16, 44, 46]. Our paper aims to justify the mean field approximation by proving the convergence of the finite population optimization problem to the mean field problem, when  $n$  tends to infinity.

We point out three important features in our modelling of the PEV charging. First, only a finite number of charging rates are allowed, because charging is mostly done at discrete rates [45]. This feature was also adopted for example in [17, 27, 50]. However, these papers did not systematically take into account the switching cost and congestion constraints, which are the second and third features of our modelling. Indeed, penalizing switches is crucial because, on the one hand, multiple changes in charging regime causes more intensive battery aging and degradation [20, 42] whereas, on the other hand, the synchronization of switches of PEVs can disrupt energy balance on the electrical network [52] and increase instability of distribution transformers [53]. Finally, congestion constraints enable to avoid voltage drops and overloading of transformers [33] caused by uncoordinated large fleets of PEVs.

The main contribution of this work is the convergence, as  $n$  tends to infinity, of the value of the finite population problem to the value of the mean field control problem (Theorem 2.1). We also prove the convergence (up to a subsequence) of optimal solutions of the finite population problem to a solution of the mean field control problem (Theorem 2.2).

Let us make some remarks on the method of proof. The finite population problem is first defined in a Lagrangian point of view, namely that the evolution of the population is described by the trajectory of each process (PEV).

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\*PSL Research University, Université Paris-Dauphine, CEREMADE, Place de Lattre de Tassigny, F- 75016 Paris, France, OSIRIS department, EDF Lab, Bd Gaspard Monge, 91120 Palaiseau, France, seguret@ceremade.dauphine.fr

Then, an Eulerian formulation of the problem, which characterizes the evolution of the population by its state distribution, velocity field and the distribution of the switches of its discrete state, is introduced and proved to be equivalent to the Lagrangian formulation (Corollary 3.1). This result is obtained thanks to a superposition principle (Theorem 3.1), that is a direct adaptation of the one in [12]. The superposition principle states that any curve of probability measure, solution of the continuity equation, can be represented as the transport of the initial distribution along an ODE flow. This result was first introduced in [1] in the Euclidean setting and extended to general metric spaces in [41].

The convergence of the solution and that of the value of the finite population problem in the Eulerian formulation are achieved in two steps. First, we prove that the lower limit, as  $n$  tends to infinity, of the value of the finite population problem is larger than the value of the mean field control problem, due to the compactness and lower semi-continuity arguments (Theorem 4.1). Second, we show that the value of the finite population problem is bounded above by the value of the mean field control problem up to a term of order  $\mathcal{O}(n^{-1/3})$  (Theorem 4.2). To obtain this bound, a mean field optimal control is implemented to a finite population of processes and an estimate of the Wasserstein distance between the empirical distribution of the finite population and the optimal mean field distribution is derived (Theorem 4.3). This estimate strongly relies on the regularity of the optimal control of the mean field control problem. The Lipschitz continuity w.r.t. the space variable, uniformly in time, of the optimal control has been established in a companion paper [48]. Similar results of Lipschitz regularity of the optimal controls have been studied in the context of mean field control problem [6, 19].

The *mean field limit* of a system of  $n$  interacting agents is defined as the asymptotic behaviour of the system when  $n$  tends to infinity. The empirical distribution of the system of  $n$  agents can be approximated by a distribution that is a solution of a Vlasov type equation. In the stochastic setting, one often refers this asymptotic behavior to the notion of propagation of chaos [51]. In the context of optimal control with deterministic dynamics, the convergence of the solutions of the finite population problem to a solution of the mean field control problem, was first proved in [26]. The authors applied  $\Gamma$ -convergence techniques [18] and restricted the result to the particular case of feedback control functions that are locally Lipschitz continuous in space. The convergence of the value of the optimal control of a finite population of interacting McKean-Vlasov dynamics to the value of a mean field optimal control problem was proved in [36] in fairly general settings (the results hold for degenerate diffusion). The convergence results in [26] were obtained without the restrictions on the control in [25]. In [12], the Eulerian, Lagrangian and Kantorovich formulation of the finite population and the mean field problems are introduced, and the convergence of the value functions of the finite population Lagrangian and Eulerian problems were established. More convergence properties in various deterministic settings can be found in [7, 30] and in the references therein. In a stochastic setting, the results of [36] were extended to the case with common noise in [23] and with interaction of the agents with joint distribution of the state and control in [22]. More recently, in a setting with idiosyncratic and common noise in the dynamic of the agents, a convergence rate of the value function of the finite population problem to the value function of the mean field limit problem was derived in [8]. In a finite state space setting, this rate was proved to be of order  $1/\sqrt{n}$  in [13]. Similar results on the value function were obtained in [3] in the case of mean field control problem with regime switching in the state dynamics. The  $\Gamma$ -convergence of a control problem of hybrid processes was proved in [29] in the very specific framework of multi-line traffic. Several convergence properties of the finite population model to the mean field one are given in [43] for the discrete time setting with common noise.

Mean field control problems are strongly connected with the mean field game (MFG) problems. This class of games, introduced by Lasry and Lions [38, 39, 40] and Huang, Malhamé and Caines [31, 32], describes the interaction among a large population of identical and rational agents in competition. It was first proved that one can construct  $\varepsilon$ -Nash equilibrium in the  $n$ -player game from mean field models [10, 11, 14, 31]. The convergence of the Nash equilibrium system to the MFG system is closely related to the well-posedness of the so-called “master equation”. Such a property was proved in general settings, with common noise, in the breakthrough of [9]. The convergence was studied in [24, 35] in the open-loop control framework and extended in [37] for closed-loop Nash equilibrium, expanding results obtained in [9]. Finally, convergence results in the finite state settings were obtained in [4, 14, 28, 34]

While problems in the literature deal with either continuous or discrete state variables, this work addresses the analysis of the mean field limit of hybrid processes. Also, a congestion constraint is considered in the optimization problem, which is unusual among the existing literature studying mean field limit of control problems (see however [15] for a  $\Gamma$ -convergence result of an  $n$ -agent system to a mean field control problem with  $L^\infty$  upper bound on the density of the population). Finally, a particularity of the model in this paper is that the nature of the dynamics in the finite population problem is different from that in the mean field problem. While the switches are controlled and deterministic in the finite population setting, the jumps of the discrete variable of each process are stochastic and the control is on the transition rate in the mean field problem .

The paper is organized as follows. In Section 2, we present our assumptions, the  $n$ -agent optimal control problem, the mean field control problem and the main results. The equivalence between the finite population problem and its Eulerian formulation is established in Section 3, as well as the superposition principle. Finally, the convergence of the solution and that of the value of the finite population problem to the solution and the value of the mean field problem are proved in Section 4.

## 2 Main results

**Notations** The space of Borel, positive and bounded measures on a space  $A$  is denoted by  $\mathcal{M}^+(A)$  and the space of Borel probability measures on a space  $A$  is denoted by  $\mathcal{P}(A)$ . For any measure  $\mu \in \mathcal{M}([0, T])$  and  $0 \leq t_1 < t_2 \leq T$ , we set  $\int_{t_1}^{t_2} \mu(dt) := \mu([t_1, t_2])$ . Given a set  $\mathcal{S}$ , for any function  $f$  defined on  $\mathcal{S} \times I$  and any measure  $\mu \in \mathcal{M}(\mathcal{S} \times \mathcal{S} \times I)$ , we use the notations  $f_i(x) := f(x, i)$  for any  $(x, i) \in \mathcal{S} \times I$  and  $\mu_i(\mathcal{S}) := \mu(\mathcal{S} \times i)$  for any  $(\mathcal{S}, i) \in \mathcal{B}(\mathcal{S}) \times I$ , where  $\mathcal{B}(\mathcal{S})$  denotes the Borel algebra. Similarly, for any function  $g$  defined on  $\mathcal{S} \times I \times I$  and any measure  $\nu \in \mathcal{M}(\mathcal{S} \times \mathcal{S}' \times I \times I)$ , where  $\mathcal{S}'$  is a set, we use the notations  $g_{i,j}(x) := g(x, i, j)$  for any  $(x, i, j) \in \mathcal{S} \times I^2$  and  $\nu_{i,j}(\mathcal{S}, \mathcal{S}') := \nu(\mathcal{S} \times \mathcal{S}' \times \{i\} \times \{j\})$  for any  $(\mathcal{S}, \mathcal{S}', i, j) \in \mathcal{B}(\mathcal{S}) \times \mathcal{B}(\mathcal{S}') \times I^2$ . If  $\mathcal{S}$  is a metric space, let  $\text{Lip}(\mathcal{S})$  denote the vector space of bounded and Lipschitz continuous maps  $f : \mathcal{S} \rightarrow \mathbb{R}$ . For any  $\mu \in C^0([0, T], \mathcal{P}([0, 1]))$ , let  $L_\mu^2([0, T] \times [0, 1]) := \{f : [0, T] \times [0, 1] \mapsto \mathbb{R}, \int_0^T \int_0^1 f(t, s)^2 \mu(t, ds) dt < +\infty\}$ . We denote by  $\mathcal{W}$  the Wasserstein distance on  $\mathcal{P}([0, 1] \times I)$ , defined by  $\mathcal{W}(\mu, \rho) := \sup \{\sum_{i \in I} \int_0^1 \varphi(\mu - \rho) \mid \varphi \text{ is } 1 - \text{Lipschitz from } [0, 1] \times I \text{ to } \mathbb{R}\}$ . We recall that if a function  $\varphi$  is 1-Lipschitz continuous from  $[0, 1] \times I$  to  $\mathbb{R}$ , then  $|\varphi(x, i) - \varphi(x, j)| \leq 1$  for any  $i, j \in I$ . For any metric space  $(X, d)$ , we denote by  $D([0, T], X)$  the set of cadlag functions from  $[0, T]$  to  $X$  and by  $AC([0, T], X)$  the set of absolutely continuous functions. For any  $x \in \mathbb{R}$ ,  $\lfloor x \rfloor$  denotes the integer truncation of  $x$ . For any  $n \in \mathbb{N}$ , we introduce  $\mathcal{P}^n([0, 1] \times I)$ , the set of empirical probability measures on the space  $[0, 1] \times I$  defined by

$$\mathcal{P}^n([0, 1] \times I) := \{\mu = \frac{1}{n} \sum_{\ell=1}^n \delta_{(x^\ell, i^\ell)} \text{ for some } (x^\ell, i^\ell) \in [0, 1] \times I\},$$

and similarly we introduce  $\mathcal{M}^n([0, 1])$  defined by:

$$\mathcal{M}^n([0, 1]) := \{\mu = \frac{1}{n} \sum_{\ell=1}^{\bar{n}} \delta_{x^\ell} \text{ for some } x^\ell \in [0, 1] \text{ and } \bar{n} \leq n\}. \quad (2.1)$$

### 2.1 The $n$ PEVs control problem

We consider a population of  $n$  PEVs ( $n \in \mathbb{N}^*$ ), a state space  $[0, 1] \times I$ , where  $I$  is a finite set, and a time interval  $[0, T]$ . We consider a time and space discretization depending on  $n$ , with time step  $\Delta t^n$  and space step  $\Delta s^n$  (indexed by the superscript  $n$ ), such that  $N_T^n := T/\Delta t^n$  and  $N_s^n := 1/\Delta s^n$  are integers. The time mesh is  $\{0, t_1^n, \dots, t_{k+1}^n, \dots, T\}$  with  $t_k^n := k\Delta t^n$ , for any  $k \in \{0, \dots, N_T^n\}$ . The space mesh is  $\{0, y_1^n, \dots, y_p^n, \dots, 1\}$  with  $y_p^n := p\Delta s^n$ , for any  $p \in \{0, \dots, N_s^n\}$ . For the sake of simplicity, we write  $t_k$  and  $y_p$  instead of  $t_k^n$  and  $y_p^n$ , and  $\Delta s$  and  $\Delta t$  instead of  $\Delta s^n$  and  $\Delta t^n$ .

For any  $\ell \in \{1, \dots, n\}$  and  $t \in [0, T]$ , the vehicle  $\ell$  is described by its state variable  $x_t^\ell := (i_t^\ell, s_t^\ell) \in I \times [0, 1]$ , with a given initial datum  $x_0^\ell = (i_0^\ell, s_0^\ell)$ . The discrete variable  $i^\ell$ , denoting the mode of charging, can switch deterministically and only at fixed times in  $\{t_1, \dots, t_{N_T^n-1}\}$ , while the continuous variable  $s^\ell$ , representing the SoC, is governed by an ODE depending on the mode of charging. Between two jumps of the variable  $i^\ell$ , i.e. within each interval  $[t_k, t_{k+1})$ , the dynamics of  $x^\ell$  is deterministic and is given by:

$$i_t^\ell = i_{t_k}^\ell, \quad \frac{ds_t^\ell}{dt} = b(i_t^\ell, s_t^\ell) \text{ for any } t \in [t_k, t_{k+1}) \text{ and with } s_{t_k}^\ell = \lim_{\tau \uparrow t_k} s_\tau^\ell, \quad (2.2)$$

where the initial state  $(i_0^\ell, s_0^\ell)$  is given. Note that there are no switches of  $i^\ell$  at times  $t = 0$  and  $t = T$ . We further assume that  $b$  belongs to  $C^1(I \times \mathbb{R})$  and vanishes at the boundary of  $[0, 1]$ , so that the ODE satisfied by  $s^\ell$  has a unique solution and  $s^\ell$  lies in  $[0, 1]$ . By (2.2), the map  $t \mapsto (i_t^\ell, s_t^\ell)$  is cadlag. Given  $\bar{m} \in \mathcal{P}^n([0, 1] \times I)$ , we introduce the set of processes:

$$\begin{aligned} \mathcal{X}^n(\bar{m}) := & \left\{ \{(i^\ell, s^\ell)\}_{\ell \in \{1, \dots, n\}} \in (D([0, T], I) \times C^0([0, T], [0, 1]))^n \mid \text{the empirical distribution} \right. \\ & \left. \text{of } \{(i_0^\ell, s_0^\ell)\}_\ell \text{ is equal to } \bar{m} \text{ and } (i^\ell, s^\ell) \text{ satisfies (2.2)} \right\}. \end{aligned} \quad (2.3)$$

We denote by  $(\mathbf{i}, \mathbf{s})$  a generic element of  $\mathcal{X}^n(\bar{m})$ . The population of  $n$  processes is subject to the following congestion constraints:

$$\frac{1}{n} \sum_{\ell=1}^n 1_i(i_t^\ell) \leq D_i(t) \quad \forall (i, t) \in I \times [0, T], \quad (2.4)$$

where  $D : [0, T] \rightarrow \mathbb{R}_+^*$  is given. The admissible set  $\mathcal{T}^n(\bar{m}, D)$  is defined by:

$$\mathcal{T}^n(\bar{m}, D) := \{(\mathbf{i}, \mathbf{s}) \in \mathcal{X}^n(\bar{m}) \mid (\mathbf{i}, \mathbf{s}) \text{ satisfies (2.4)}\}. \quad (2.5)$$

Let  $\mathcal{J}^n$  be the objective function, defined by:

$$\mathcal{J}^n(\mathbf{i}, \mathbf{s}) := \frac{1}{n} \sum_{\ell=1}^n \int_0^T c(t, i_t^\ell, s_t^\ell) dt + g(i_T^\ell, s_T^\ell) + \sum_{i, j \in I, j \neq i} \sum_{k=1}^{N_T^n - 1} \sum_{p=0}^{N_s^n - 1} L \left( \frac{Q_{i,j}^{k,p}(\mathbf{i}, \mathbf{s})}{\Delta t} \right) \Delta t Q_i^{k,p}(\mathbf{i}, \mathbf{s}), \quad (2.6)$$

where  $Q_{i,j}^{k,p}(\mathbf{i}, \mathbf{s})$  is the proportion of PEVs among the processes with a state in  $[y_p, y_{p+1}) \times \{i\}$  that switch their discrete state  $i$  to  $j$  at time  $t_k$ , and  $Q_i^{k,p}(\mathbf{i}, \mathbf{s})$  is the proportion of PEVs among the overall population of processes that has a state in  $[y_p, y_{p+1}) \times \{i\}$  at time  $t_k^-$  (just before the jumps). More precisely,  $Q_i^{k,p}(\mathbf{i}, \mathbf{s})$  and  $Q_{i,j}^{k,p}(\mathbf{i}, \mathbf{s})$  are defined by:

$$Q_i^{k,p}(\mathbf{i}, \mathbf{s}) := \frac{1}{n} \sum_{\ell=1}^n 1_i(i_{t_k^-}^\ell) 1_{[y_p, y_{p+1})}(s_{t_k}^\ell),$$

$$Q_{i,j}^{k,p}(\mathbf{i}, \mathbf{s}) := \begin{cases} 0 & \text{if } Q_i^{k,p}(\mathbf{i}, \mathbf{s}) = 0, \\ \frac{1}{n Q_i^{k,p}(\mathbf{i}, \mathbf{s})} \sum_{\ell=1}^n 1_i(i_{t_k^-}^\ell) 1_j(i_{t_k}^\ell) 1_{[y_p, y_{p+1})}(s_{t_k}^\ell) & \text{otherwise.} \end{cases}$$

Our purpose is to study the mean field limit of the following finite population optimal control problem:

$$\inf_{(\mathbf{i}, \mathbf{s}) \in \mathcal{T}^n(\bar{m}, D)} \mathcal{J}^n(\mathbf{i}, \mathbf{s}). \quad (2.7)$$

We recall that this work is initially motivated by the optimal charging of a population of plug-in electrical vehicles (PEVs) controlled by a central planner. The given velocity field  $b(i, s)$  denotes the power of charge or discharge of a PEV in mode  $i$  and with battery level  $s$ . The congestion constraint (2.4) aims at avoiding high demand of energy at each moment over the period. The value  $c(t, i, s)$  in (2.6) corresponds to the running cost of a PEV at state  $(s, i)$  and at time  $t \in [0, T]$ ;  $g(i, s)$  is the final cost per PEV at state  $(s, i)$ . The switching cost  $L \left( \frac{Q_{i,j}^{k,p}(\mathbf{i}, \mathbf{s})}{\Delta t} \right) \Delta t Q_i^{k,p}(\mathbf{i}, \mathbf{s})$  penalizes large values of  $Q_{i,j}^{k,p}(\mathbf{i}, \mathbf{s})$ , i.e., large proportion of PEVs switching from a state in  $[y_p, y_{p+1}) \times \{i\}$  to a state in  $[y_p, y_{p+1}) \times \{j\}$  at time  $t_k$ . The normalization by  $\Delta t$  avoids frequent jumps. Finally, the multiplication of  $L(\cdot)$  by  $\Delta t Q_i^{k,p}(\mathbf{i}, \mathbf{s})$  normalizes the transition cost and avoids its explosion when  $n$  tends to infinity. The switching costs in (2.7) showed good numerical results in [49].

**Remark 2.1.** *The definition of  $\mathcal{J}^n$  in (2.6) does not take into account the jumps of PEVs with SoC equal to 1. However, by Assumptions 1 and 2 (specified in Section 2.3) it is not possible for a PEV to have a SoC equal to 1, which justifies our choice.*

**Remark 2.2.** *Since the number of admissible trajectories is finite and by Assumption 3 (given in Section 2.3) non empty, the infimum is always attained in (2.7). Actually, Assumption 3 ensures that the  $n$  processes with no switches for the discrete variable is admissible. We deduce that, for any  $n \in \mathbb{N}$ ,*

$$\inf_{(\mathbf{i}, \mathbf{s}) \in \mathcal{T}^n(\bar{m}, D)} \mathcal{J}^n(\mathbf{i}, \mathbf{s}) \leq T \|c\|_\infty + \|g\|_\infty. \quad (2.8)$$

## 2.2 The mean field control problem

This section defines the limit model when  $n$  tends to infinity. Let  $(\bar{m}, D) \in \mathcal{P}([0, 1] \times I) \times C^0([0, T] \times I, \mathbb{R}_+^*)$  satisfy  $\text{supp}(\bar{m}_i) \subset (0, 1)$ , for any  $i \in I$ , and

$$\sup_{t \in [0, T], i \in I} D_i(t) - \bar{m}_i([0, 1]) \leq \varepsilon^0,$$

where the constant  $\varepsilon^0 > 0$  is defined further in Assumption 3. We consider the continuity equation on the pair  $(m, E)$ , defined on the domain  $(0, T) \times (0, 1) \times I$ :

$$\begin{aligned} \partial_t m_i(t, s) + \partial_s(m_i(t, s)b_i(s)) &= - \sum_{i, j \in I, j \neq i} (E_{i, j}(t, s) - E_{j, i}(t, s)) \quad (i, t, s) \in I \times (0, T) \times (0, 1) \\ m_i(0, s) &= \bar{m}_i(s) \quad (i, s) \in I \times (0, 1). \end{aligned} \quad (2.9)$$

We introduce the density constraint:

$$m_i(t, [0, 1]) \leq D_i(t) \quad \forall (i, t) \in I \times [0, T], \quad (2.10)$$

and the admissible set

$$\mathcal{S}(\bar{m}, D) := \left\{ (m, E) \mid m \in C^0([0, T], \mathcal{P}([0, 1] \times I)), E \in \mathcal{M}^+([0, T] \times [0, 1] \times I^2), E_{i, j} \ll m_i \text{ and } \frac{dE_{i, j}}{dm_i} \in L^2_{m_i}(0, T) \forall i, j \in I, (m, E) \text{ is a weak solution of (2.9) and satisfies (2.10)} \right\}. \quad (2.11)$$

The definition of weak solution of (2.9) is given by Definition 3.1 in Section 3. The objective function  $J$  is defined for any  $(m, E) \in \mathcal{S}(\bar{m}, D)$  by:

$$J(E, m) := \sum_{i \in I} \int_0^T \int_0^1 \left( c_i(t, s) + \sum_{j \in I, j \neq i} L\left(\frac{dE_{i, j}}{dm_i}(t, s)\right) \right) m_i(t, ds) dt + \sum_{i \in I} \int_0^1 g_i(s) m_i(T, ds). \quad (2.12)$$

The mean field control problem is:

$$\inf_{(m, E) \in \mathcal{S}(\bar{m}, D)} J(m, E). \quad (2.13)$$

This problem has been studied in [48], where optimality conditions and regularity results on the solutions are established. The main result of the paper, giving the convergence of Problem (2.7) to Problem (2.13), is described in the next section.

## 2.3 Convergence result

Throughout the paper, we assume the following:

### General assumptions

1. For any  $i \in I$ ,  $b_i \in C^1(\mathbb{R})$  with  $b_i(s) = 0$  for any  $s \notin (0, 1)$ .
2. For any  $n \in \mathbb{N}$  and  $i \in I$ , we assume that  $\bar{m}^n \in \mathcal{P}^n([0, 1] \times I)$  and  $\text{supp}(\bar{m}_i^n) \subset (0, 1)$ .
3. There exists  $\varepsilon^0 > 0$  such that, for any  $n \in \mathbb{N}$ ,  $\varepsilon^0 \leq \inf_{(i, t) \in I \times [0, T]} D_i(t) - \bar{m}_i^n([0, 1])$ .
4. For any  $i \in I$ ,  $c_i \in C^1([0, T] \times [0, 1])$  and  $g_i \in C^1([0, 1])$ .
5.  $L : \mathbb{R} \rightarrow \bar{\mathbb{R}}$  is a convex function, defined by:

$$L(x) := \begin{cases} l(x) & \text{if } x > 0 \\ 0 & \text{if } x = 0 \\ +\infty & \text{otherwise,} \end{cases}$$

where  $l \in C^1(\mathbb{R}_+, \mathbb{R}_+)$  is an increasing strongly convex function, bounded from above by a quadratic function, i.e. there exist  $C > 0$  such that for any  $x \in \mathbb{R}_+$ :

$$\frac{x^2}{C} - C \leq l(x) \leq C(x^2 + 1),$$

where the first inequality is due to the strong convexity of  $l$ . By convention:  $L\left(\frac{0}{0}\right) \cdot 0 := 0$ .

**Remark 2.3.** The main role of Assumptions 1 and 2 is to ensure that the solution of the ODE in (2.2) takes values in  $[0, 1]$ . In addition, the superposition principle formulated in Section 3 relies on the regularity of  $b$  stated in Assumption 1. Assumption 3 ensures that the  $n$  trajectories with no switch of discrete variable  $i$  are admissible trajectories. Correspondingly, the feasible set  $\mathcal{T}^n(\bar{m}, D)$  of Problem (2.7) is not empty. This assumption also enables to build in Section 4.2 admissible trajectories based on a solution of the mean field control problem. It is possible to replace Assumption 3 by less restrictive conditions. However, for the sake of clarity, we restrict the analysis to the case with Assumption 3. Regularity results of the solution of the mean field control problem (2.13) are derived from the properties of  $c$ ,  $g$  and  $L$  given in Assumptions 4 and 5. Assumption 5 enables to obtain the compactness of the solutions of the finite population problem and to apply  $\Gamma$ -convergence techniques in Section 4.1.

In the following theorem, we state the convergence of the value of Problem (2.7) to the value of Problem (2.13) as  $n$  tends to infinity.

**Theorem 2.1.** *There exist constants  $\tilde{C}_1, \tilde{C}_2 > 1$  such that, if*

$$\frac{1}{\tilde{C}_1 n^{\frac{1}{3}}} \leq \Delta t, \Delta s \leq \frac{\tilde{C}_1}{n^{\frac{1}{3}}}, \quad (2.14)$$

and

$$\Delta t < \frac{1}{\tilde{C}_2 |I|}, \quad (2.15)$$

hold for any  $n \in \mathbb{N}^*$ , then,

1. *If  $\{\bar{m}^n\}_n$  weakly converges to  $\bar{m} \in \mathcal{P}([0, 1] \times I)$ , then*

$$\inf_{(m, E) \in \mathcal{S}(\bar{m}, D)} J(m, E) \leq \liminf_{n \rightarrow \infty} \inf_{(i, s) \in \mathcal{T}^n(\bar{m}^n, D)} \mathcal{J}^n(i, s). \quad (2.16)$$

2. *There exists  $C > 0$  such that for any  $n \in \mathbb{N}$ :*

$$\inf_{(i, s) \in \mathcal{T}^n(\bar{m}^n, D)} \mathcal{J}^n(i, s) - \frac{C}{n^{\frac{1}{3}}} \leq \inf_{(m, E) \in \mathcal{S}(\bar{m}^n, D)} J(m, E), \quad (2.17)$$

where  $C$  depends on the data.

The proof of Theorem 2.1 is given in Section 4.3. To obtain this result, an Eulerian formulation of Problem 2.7 is introduced and proved to be equivalent to Problem 2.7 (Corollary 3.1) thanks to a superposition principle (Theorem 3.1). Then, the first part of Theorem 2.1 is obtained in Section 4 by applying compactness arguments on the sequences of solutions of the Eulerian problem, while the second part directly derives from Theorem 4.2. Inequality (2.17) relies on regularity results of the solution of Problem (2.13), that are used to build an admissible control for the Eulerian version of Problem 2.7.

**Remark 2.4.** *Improving the qualitative inequality (2.16) into a quantitative one, as in (2.17), seems a difficult task. The main difficulties come from the constraint (2.4) and the lack of regularity of the objective function  $\mathcal{J}^n$  w.r.t. to the set of trajectories  $(s, i)$ .*

**Remark 2.5.** *To obtain the inequality in Theorem 2.1.1, one needs that  $\lim_{n \rightarrow \infty} \Delta t = \lim_{n \rightarrow \infty} \Delta s = 0$ . This condition is ensured by inequality (2.14). Inequality (2.17), on the other hand, requires (2.14) and (2.15).*

For any  $n \in \mathbb{N}$ , let  $(\mathbf{i}^n, \mathbf{s}^n) \in \mathcal{T}^n(\bar{m}^n, D)$  be a solution of Problem (2.7). We define the empirical distribution of the processes  $m^n$  and the empirical measure of the switches  $E^n$  by:

$$m^n(t) := \frac{1}{n} \sum_{\ell=1}^n \delta_{(i_t^{n, \ell}, s_t^{n, \ell})}, \quad (2.18)$$

and

$$E_{i,j}^n := \frac{1}{n} \sum_{\ell=1}^n \sum_{k=1}^{N_T^n - 1} 1_i(i_{t_k}^{n, \ell}) 1_j(i_{t_k}^{n, \ell}) \delta_{t_k} \otimes \delta_{s_{t_k}^{n, \ell}}. \quad (2.19)$$

The next result states the weak convergence of  $\{(m^n, E^n)\}$  to a solution of Problem (2.13).

**Theorem 2.2.** *Under the assumptions of Theorem 2.1, if  $\{\bar{m}^n\}_n$  weakly converges to  $\bar{m} \in \mathcal{P}([0, 1] \times I)$ , there exists a subsequence of  $\{(m^n, E^n)\}_n$  and a solution  $(m^*, E^*)$  of Problem (2.13) such that,  $\{E^n\}_n$  weakly converges to  $E^*$  and  $\{m^n(t)\}_n$  converges in Wasserstein distance uniformly in  $t \in [0, T]$  to  $m^*(t)$ .*

The proof of Theorem 2.2 is given in Section 4.3.

### 3 Equivalence between Eulerian and Lagrangian finite population control problems

In this section, an Eulerian formulation of Problem (2.7) is introduced. The equivalence between the Lagrangian and the Eulerian formulation relies on a superposition principle, adapted to the problem and stated in Theorem 3.1.

**Definition 3.1.** *We say that a pair  $(m, E) \in D([0, T], \mathcal{P}([0, 1] \times I)) \times \mathcal{M}^+([0, T] \times [0, 1] \times I \times I)$  satisfies (2.9) in the weak sense if, for any test function  $\phi \in C^1([0, T] \times [0, 1] \times I)$ , we have:*

$$\begin{aligned} & \sum_{i \in I} \int_0^1 \phi_i(T, s) m_i(T, ds) - \phi_i(0, s) \bar{m}_i(ds) \\ &= \int_0^T \int_0^1 \sum_{i \in I} (\partial_t \phi_i(t, s) + b_i(s) \partial_s \phi_i(t, s)) m_i(t, ds) + \sum_{j \in I, j \neq i} \phi_i(t, s) (E_{j,i} - E_{i,j})(dt, ds). \end{aligned}$$

Let  $n \in \mathbb{N}$ ,  $(m, E) \in D([0, T], \mathcal{P}^n([0, 1] \times I)) \times \mathcal{M}^+([0, T] \times [0, 1] \times I^2)$ , we consider the following:

$$\text{supp}(E_{i,j}) \subset \{t_q\}_{1 \leq q \leq N_T^n - 1} \times [0, 1], \quad \forall i, j \in I, \quad (3.1)$$

and

$$\sum_{j \in I, j \neq i} E_{i,j}(\{t_k\}, B) \leq m_i(t_k, B), \quad \forall t_k \in \{t_q\}_{0 \leq q \leq N_T^n} \text{ and } \forall B \in \mathcal{B}([0, 1]). \quad (3.2)$$

The two constraints above are used to characterize the empirical distribution  $m$  of the set of processes  $\{(i^\ell, s^\ell)\}_{1 \leq \ell \leq n}$  and to characterize the distribution of the jumps  $E$  associated to  $\{i^\ell\}_{1 \leq \ell \leq n}$ . Constraint (3.1) implies that the support of  $E$  is concentrated on the nodes of the time mesh. Thus, the jumps only occur at times in the set  $\{t_1, \dots, t_{N_T^n - 1}\}$ . Constraint (3.2) ensures that the number of switches does not exceed the number of vehicles at each time and position.

Finally, for any  $n \in \mathbb{N}$  and  $\bar{m} \in \mathcal{P}^n([0, 1] \times I)$ , we define the set  $\mathcal{Q}^n(\bar{m})$  by:

$$\begin{aligned} \mathcal{Q}^n(\bar{m}) := & \{(m, E) \in D([0, T], \mathcal{P}^n([0, 1] \times I)) \times \mathcal{M}^+([0, T] \times [0, 1] \times I^2) \text{ such that } (m, E) \text{ is a weak solution of (2.9)} \\ & \text{with initial distribution } \bar{m}, (m, E) \text{ satisfies (3.1) and (3.2), and } E_{i,j}(\{t_k\}, \cdot) \in \mathcal{M}^n([0, 1]) \forall k \in \{0, \dots, N_T^n\}\}. \end{aligned} \quad (3.3)$$

The theorem below is the main result of this section. It highlights the equivalence between the Lagrangian and the Eulerian points of view, when describing the evolution of the system of  $n$  PEVs. It is a reminiscent of the superposition principle [2].

**Theorem 3.1** (Superposition principle).

1. *For any  $n \in \mathbb{N}$ ,  $\bar{m} \in \mathcal{P}^n([0, 1] \times I)$  and  $(\mathbf{i}, \mathbf{s}) \in \mathcal{X}^n(\bar{m})$ , there exists a pair  $(m^n, E^n) \in \mathcal{Q}^n(\bar{m})$  such that  $m^n$  is the empirical distribution of the processes  $(\mathbf{i}, \mathbf{s})$  and  $E^n$  is that of the jumps over the period  $[0, T]$ , i.e.  $m^n$  satisfies (2.18) and  $E^n$  satisfies (2.19).*
2. *For any  $n \in \mathbb{N}$ ,  $\bar{m} \in \mathcal{P}^n([0, 1] \times I)$ , and  $(m, E) \in \mathcal{Q}^n(\bar{m})$ , there exists  $(\mathbf{i}, \mathbf{s}) \in \mathcal{X}^n(\bar{m})$ , such that  $m$  satisfies (2.18) and  $E$  satisfies (2.19).*

We stress that the processes  $(\mathbf{i}, \mathbf{s})$  in 2 is not necessary unique. The proof of the theorem is given in section 3.2.

#### 3.1 Eulerian problem formulation

In this subsection, we describe the Eulerian formulation of the optimal control problem and show that it is equivalent to the Lagrangian Problem (2.7).

We define, for any  $\bar{m} \in \mathcal{P}^n([0, 1] \times I)$  and  $D \in C^0([0, T] \times I, \mathbb{R}_+^*)$ , the set  $\mathcal{S}^n(\bar{m}, D)$  by:

$$\mathcal{S}^n(\bar{m}, D) := \{(m, E) \in \mathcal{Q}^n(\bar{m}) \mid (m, E) \text{ satisfies (2.10)}\}. \quad (3.4)$$



**Remark 3.1.** For all  $\bar{m} \in \mathcal{P}^n([0, 1] \times I)$  and  $D \in C^0([0, T] \times I, \mathbb{R}_+^*)$  satisfying Assumption 3, the sets  $\mathcal{S}^n(\bar{m}, D)$  and  $\mathcal{S}(\bar{m}, D)$  are different. On the one hand, if  $(m, E)$  belongs to  $\mathcal{S}(\bar{m}, D)$ , then  $E_{i,j} \ll m_i$  for any  $i, j \in I$  and we show below that  $m$  is continuous in time. On the other hand, if  $(m, E)$  belongs to  $\mathcal{S}^n(\bar{m}, D)$  and  $E \neq 0$ , then by (3.1)  $E_{i,j}$  is supported by a set of discrete times (and therefore  $E_{i,j} \ll m_i$  cannot hold); moreover  $m$  is discontinuous w.r.t. the time variable.

For any  $n \in \mathbb{N}$ , we define the cost function  $J^n$ , for any  $(m, E) \in \mathcal{S}^n(\bar{m}, D)$  by:

$$J^n(m, E) := \sum_{i \in I} \int_0^T \int_0^1 c_i(t, s) m_i(t, ds) dt + \sum_{i, j \in I, i \neq j} \sum_{k=1}^{N_T^n - 1} \sum_{p=0}^{N_s^n - 1} L \left( \frac{E_{i,j}(\{t_k\}, [y_p, y_{p+1}])}{\Delta t m_i(t_k^-, [y_p, y_{p+1}])} \right) \Delta t m_i(t_k^-, [y_p, y_{p+1}]) + \sum_{i \in I} \int_0^1 g_i(s) m_i(T, ds). \quad (3.5)$$

For any  $n \in \mathbb{N}$ , we consider the optimization problem:

$$\inf_{(m, E) \in \mathcal{S}^n(\bar{m}, D)} J^n(m, E). \quad (3.6)$$

The following corollary is a direct consequence of Theorem 3.1.

**Corollary 3.1.** One has:

$$\inf_{(\mathbf{i}, \mathbf{s}) \in \mathcal{T}^n(\bar{m}, D)} \mathcal{J}^n(\mathbf{i}, \mathbf{s}) = \inf_{(m, E) \in \mathcal{S}^n(\bar{m}, D)} J^n(m, E).$$

*Proof.* Let  $(\mathbf{i}, \mathbf{s}) \in \mathcal{T}^n(\bar{m}, D)$ , then from Theorem 3.1.1, there exists  $(m, E) \in \mathcal{Q}^n(\bar{m})$  such that  $m$  is the empirical distribution of  $(\mathbf{i}, \mathbf{s})$  satisfying (2.18) and  $E$  is the empirical distribution of the jumps satisfying (2.19). Since  $(\mathbf{i}, \mathbf{s}) \in \mathcal{T}^n(\bar{m}, D)$ , we have for any  $i \in I$  and  $t \in [0, T]$

$$m_i(t, [0, 1]) = \frac{1}{n} \sum_{\ell=1}^n 1_i(i_t^\ell) \leq D_i(t) \quad \forall (i, t) \in I \times [0, T],$$

and thus,  $(m, E) \in \mathcal{S}^n(\bar{m}, D)$ . For any  $j \in I$  with  $i \neq j$ ,  $k \in \{1, \dots, N_T^n - 1\}$  and  $p \in \{0, \dots, N_s^n - 1\}$ , one has:

$$m_i(t_k^-, [y_p, y_{p+1}]) = \frac{1}{n} \sum_{\ell=1}^n \delta_{(i_{t_k}^\ell, s_{t_k}^\ell)}(\{i\} \times [y_p, y_{p+1}]) = Q_i^{k,p}(\mathbf{i}, \mathbf{s}),$$

and

$$E_{i,j}(\{t_k\}, [y_p, y_{p+1}]) = \frac{1}{n} \sum_{\ell=1}^n \sum_{k=1}^{N_T^n} 1_i(i_{t_k}^\ell) 1_j(i_{t_k}^\ell) \delta_{s_{t_k}^\ell}([y_p, y_{p+1}]) = Q_{i,j}^{k,p}(\mathbf{i}, \mathbf{s}) Q_i^{k,p}(\mathbf{i}, \mathbf{s}).$$

From the two previous equalities, one has for any  $k \in \{1, \dots, N_T^n - 1\}$  and  $p \in \{0, \dots, N_s^n - 1\}$ :

$$L \left( \frac{E_{i,j}(\{t_k\}, [y_p, y_{p+1}])}{\Delta t m_i(t_k^-, [y_p, y_{p+1}])} \right) \Delta t m_i(t_k^-, [y_p, y_{p+1}]) = L \left( \frac{Q_{i,j}^{k,p}(\mathbf{i}, \mathbf{s})}{\Delta t} \right) \Delta t Q_i^{k,p}(\mathbf{i}, \mathbf{s}).$$

By (2.18) and (2.19), we have:

$$\frac{1}{n} \sum_{\ell=1}^n \int_0^T c(t, i_t^\ell, s_t^\ell) dt = \sum_{i \in I} \int_0^T \int_0^1 c_i(t, s) m_i(t, ds) dt \quad \text{and} \quad \frac{1}{n} \sum_{\ell=1}^n g(i_T^\ell, s_T^\ell) = \sum_{i \in I} \int_0^1 g_i(s) m_i(T, ds).$$

Therefore, it holds:

$$\mathcal{J}^n(\mathbf{i}, \mathbf{s}) = J^n(m, E), \quad (3.7)$$

and

$$\inf_{(\mathbf{i}, \mathbf{s}) \in \mathcal{T}^n(\bar{m}, D)} \mathcal{J}^n(\mathbf{i}, \mathbf{s}) \geq \inf_{(m, E) \in \mathcal{S}^n(\bar{m}, D)} J^n(m, E).$$

Using Theorem 3.1.2 and similar computations as in the first part of this proof, one can obtain the reverse inequality:

$$\inf_{(\mathbf{i}, \mathbf{s}) \in \mathcal{T}^n(\bar{m}, D)} \mathcal{J}^n(\mathbf{i}, \mathbf{s}) \leq \inf_{(m, E) \in \mathcal{S}^n(\bar{m}, D)} J^n(m, E),$$

and the conclusion follows.  $\square$

**Remark 3.2.** By Remark 2.2, there exists a solution to Problem (2.7). Thus, by Theorem 3.1 and Corollary 3.1, there exists a solution to Problem (3.6).

## 3.2 Proof of the superposition principale

### 3.2.1 Construction of the empirical distribution and of the jump measure from $n$ PEVs trajectories

In this section, we fix  $n \in \mathbb{N}^*$ ,  $\bar{m} \in \mathcal{P}^n([0, 1] \times I)$  and  $(\mathbf{i}, \mathbf{s}) \in \mathcal{X}^n(\bar{m})$ , where  $\mathcal{X}^n(\bar{m})$  is defined in (2.3).

**Lemma 3.1.** *The pair  $(m^n, E^n)$  defined in (2.18) and (2.19) from  $(\mathbf{i}, \mathbf{s})$  is a weak solution of (2.9) and satisfies (3.1) and (3.2).*

*Proof.* Using the definition of  $E^n$  in (2.19) and  $m^n$  in (2.18), (3.1) and (3.2) hold. We now show that  $(m^n, E^n)$  is a weak solution of (2.9). Since, for any  $\ell \in \{1, \dots, n\}$ , the function  $t \mapsto (i^\ell, s^\ell)$  is cadlag, one has  $m^n \in D([0, T], \mathcal{P}^n([0, 1] \times I))$ . Let  $\varphi \in C^1([0, T] \times [0, 1] \times I)$ . One deduces:

$$\begin{aligned}
& \sum_{i \in I} \int_0^T \int_0^1 (\partial_t \varphi_i(t, s) + b_j(s) \partial_s \varphi_i(t, s)) m_i^n(t, ds) dt \\
&= \frac{1}{n} \sum_{i \in I} \sum_{\ell=1}^n \sum_{k=0}^{N_T^n - 1} \int_{t_k}^{t_{k+1}} (\partial_t \varphi_i(t, s_i^\ell) + b_i(s_i^\ell) \partial_s \varphi_i(t, s_i^\ell)) \mathbb{1}_i(i_{t_k}^\ell) dt \\
&= \frac{1}{n} \sum_{i \in I} \sum_{\ell=1}^n \sum_{k=0}^{N_T^n - 1} (\varphi_i(t_{k+1}, s_{t_{k+1}}^\ell) - \varphi_i(t_k, s_{t_k}^\ell)) \mathbb{1}_i(i_{t_k}^\ell) \\
&= \frac{1}{n} \sum_{i \in I} \sum_{\ell=1}^n \varphi_i(T, s_T^\ell) \mathbb{1}_i(i_0^\ell) - \varphi_i(0, s_0^\ell) \mathbb{1}_i(i_0^\ell) + \frac{1}{n} \sum_{i, j \in I, j \neq i} \sum_{\ell=1}^n \sum_{k=1}^{N_T^n - 1} (\varphi_i(t_k, s_{t_k}^\ell) - \varphi_j(t_k, s_{t_k}^\ell)) \mathbb{1}_i(i_{t_k}^\ell) \mathbb{1}_j(i_{t_k}^\ell) \\
&= \sum_{i \in I} \int_0^1 (\varphi_i(T, s) m_i^n(T, ds) - \varphi_i(0, s) \bar{m}_i^n(ds)) + \int_0^T \int_0^1 \sum_{i, j \in I} (\varphi_i(t, s) - \varphi_j(t, s)) E_{i, j}^n(ds, dt),
\end{aligned}$$

and the conclusion follows.  $\square$

### 3.2.2 Construction of $n$ PEVs trajectories from a couple of measure $(m, E)$

In this subsection, we prove the converse result of Section 3.2.1. Given  $n \in \mathbb{N}$ ,  $\bar{m} \in \mathcal{P}^n(I \times [0, 1])$  and  $(m, E) \in \mathcal{Q}^n(\bar{m})$ , where  $\mathcal{Q}^n(\bar{m})$  is defined in (3.3), we show that there exists  $(\mathbf{i}, \mathbf{s}) \in \mathcal{X}^n(\bar{m})$  such that  $m$ , the empirical distribution of  $(\mathbf{i}, \mathbf{s})$ , satisfies (2.18) and  $E$ , the empirical distribution of the jumps, satisfies (2.19).

First, a relation between  $E_{i, j}$  and  $m_i$  at any time  $t_k$  is stated in the following lemma.

**Lemma 3.2.** *The measure  $E$  satisfies for any  $i \in I$  and any  $k \in \{1, \dots, N_T^n - 1\}$ :*

$$\sum_{j \in I, j \neq i} (E_{i, j}(\{t_k\}, ds) - E_{j, i}(\{t_k\}, ds)) = m_i(t_k^-, ds) - m_i(t_k, ds). \quad (3.8)$$

*Proof.* Let  $\varphi \in C^1([0, 1])$ ,  $\varepsilon > 0$ ,  $k \in \{1, \dots, N_T^n - 1\}$  and  $\xi^{k, \varepsilon} \in \text{Lip}([0, T])$  be such that  $\xi^{k, \varepsilon}(t) = 0$  outside  $[t_k - \varepsilon, t_k + \varepsilon]$  and:

$$\xi^{k, \varepsilon}(t) = 1 + \frac{t - t_k}{\varepsilon} \quad \forall t \in [t_k - \varepsilon, t_k) \quad \text{and} \quad \xi^{k, \varepsilon}(t) = 1 - \frac{t - t_k}{\varepsilon} \quad \forall t \in [t_k, t_k + \varepsilon].$$

For any  $i \in I$ , even though  $(t, s, j) \mapsto \xi^{k, \varepsilon}(t) \varphi(s) \mathbb{1}_i(j)$  is not in  $C^1([0, T] \times [0, 1] \times I)$ , it can be considered as a test function for the equation (2.9) because  $(t, s) \mapsto \xi^{k, \varepsilon}(t) \partial_s \varphi(s)$  is in  $C^0([0, T] \times [0, 1])$  and  $(t, s) \mapsto \partial_t \xi^{k, \varepsilon}(t) \varphi(s)$  in  $L^\infty([0, T] \times [0, 1])$ . Thus,

$$\int_{t_k - \varepsilon}^{t_k + \varepsilon} \int_0^1 (\varphi(s) \partial_t \xi^{k, \varepsilon}(t) + b_i(s) \xi^{k, \varepsilon}(t) \partial_s \varphi(s)) m_i(t, ds) dt = \sum_{j \in I, j \neq i} \int_0^1 \varphi(s) (E_{i, j}(\{t_k\}, ds) - E_{j, i}(\{t_k\}, ds)). \quad (3.9)$$

On the one hand, using the dominated convergence theorem one has:

$$\lim_{\varepsilon \rightarrow 0} \int_{t_k - \varepsilon}^{t_k + \varepsilon} \int_0^1 b_i(s) \xi^{k, \varepsilon}(t) \partial_s \varphi(s) m_i(t, ds) dt = 0. \quad (3.10)$$

On the other hand, one gets:

$$\int_{t_k-\varepsilon}^{t_k+\varepsilon} \int_0^1 \varphi(s) \partial_t \xi^{k,\varepsilon}(t) m_i(t, ds) dt = \frac{1}{\varepsilon} \left( \int_{t_k-\varepsilon}^{t_k} \int_0^1 \varphi(s) m_i(t, ds) dt - \int_{t_k}^{t_k+\varepsilon} \int_0^1 \varphi(s) m_i(t, ds) dt \right).$$

Since  $m$  is cadlag, one obtains by considering the limit  $\varepsilon \rightarrow 0$  in the previous equality:

$$\lim_{\varepsilon \rightarrow 0} \int_{t_k-\varepsilon}^{t_k+\varepsilon} \int_0^1 \varphi(s) \partial_t \xi^{k,\varepsilon}(t) m_i(t, ds) = \int_0^1 \varphi(s) m_i(t_k^-, ds) - \int_0^1 \varphi(s) m_i(t_k, ds).$$

Therefore

$$\sum_{j \in I, j \neq i} \int_0^1 \varphi(s) (E_{i,j}(\{t_k\}, ds) - E_{j,i}(\{t_k\}, ds)) = \int_0^1 \varphi(s) (m_i(t_k^-, ds) - m_i(t_k, ds)).$$

Since  $\varphi$  is arbitrary, equality (3.8) is satisfied.  $\square$

We define  $\hat{m} : [0, T] \mapsto \mathcal{P}([0, 1])$  by:  $\hat{m}(t) := \sum_i m_i(t)$ . The next lemma states a superposition principle for  $\hat{m}$ .

**Lemma 3.3.** *There exists  $\{z^\ell\}_{1 \leq \ell \leq n}$  such that, for any  $\ell \in \{1, \dots, n\}$ ,  $z^\ell \in AC([0, T], [0, 1])$  is solution of:*

$$\frac{dz^\ell}{dt} = v(t, z_t^\ell) \quad \text{for a.e. } t \in [0, T], \quad (3.11)$$

where  $v : [0, T] \times [0, 1] \rightarrow [0, 1]$  is a Borel vector field and  $\hat{m}$  satisfies:

$$\hat{m}(t) = \frac{1}{n} \sum_{\ell=1}^n \delta_{z^\ell(t)} \quad \forall t \in [0, T].$$

*Proof.* We first show that  $\hat{m}$  is in  $\text{Lip}([0, T], \mathcal{P}^n([0, 1]))$ . Since  $m(t) \in \mathcal{P}^n([0, 1] \times I)$ , for any  $t \in [0, T]$ , one has  $\hat{m}(t) \in \mathcal{P}^n([0, 1])$ . Since  $(m, E)$  is a weak solution (2.9), taking a test function  $\varphi \in C^1(0, 1)$  that is 1-Lipschitz continuous, one has:

$$\frac{d}{dt} \int_0^1 \varphi(s) \hat{m}(t, ds) = \int_0^1 (\partial_s \varphi(s)) \sum_{i \in I} b_i(s) m_i(t, ds).$$

Since  $\varphi$  is 1-Lipschitz continuous, one deduces:

$$\left| \frac{d}{dt} \int_0^1 \varphi(s) \hat{m}(t, ds) \right| \leq \|b\|_\infty,$$

and therefore, for any  $t, \tau \in [0, T]$ :

$$\mathcal{W}(\hat{m}(t), \hat{m}(\tau)) \leq |t - \tau| \|b\|_\infty.$$

Thus,  $\hat{m} \in \text{Lip}([0, T], \mathcal{P}^n([0, 1]))$  and the conclusion follows from [12, Theorem C.1].  $\square$

The following lemma gives for each time interval  $(t_k, t_{k+1})$  a superposition principle for  $m$ .

**Lemma 3.4.** *For any  $k \in \{0, \dots, N_T^n - 1\}$ , there exists  $\{(i^{k,\ell}, s^{k,\ell})\}_{\ell \in \{1, \dots, n\}}$  such that for any  $\ell \in \{1, \dots, n\}$   $(i^{k,\ell}, s^{k,\ell}) \in C^0([t_k, t_{k+1}], I) \times C^1([t_k, t_{k+1}], [0, 1])$  and any  $t \in (t_k, t_{k+1})$ :*

$$m(t) = \frac{1}{n} \sum_{\ell=1}^n \delta_{(i_t^{k,\ell}, s_t^{k,\ell})}. \quad (3.12)$$

In addition, for any  $\ell \in \{1, \dots, n\}$   $(i^{k,\ell}, s^{k,\ell})$  satisfies for any  $t \in [t_k, t_{k+1}]$ :

$$i_t^{k,\ell} = i_{t_k}^{k,\ell} \quad \text{and} \quad \frac{ds_t^{k,\ell}}{dt} = b(i_t^{k,\ell}, s_t^{k,\ell}), \quad (3.13)$$

where the distribution of  $\{(i_{t_k}^{k,\ell}, s_{t_k}^{k,\ell})\}_{\ell \in \{1, \dots, n\}}$  is  $m(t_k)$ .

*Proof.* For any  $k \in \{1, \dots, N_T^n - 1\}$  and test function  $\varphi \in C_c^1((t_k, t_{k+1}) \times [0, 1] \times I)$ , by (2.9) and using that  $\text{supp}(E)$  satisfies (3.1), one has:

$$\sum_{i \in I} \int_{t_k}^{t_{k+1}} \int_0^1 (\partial_t \varphi_i(t, s) + b_i(s) \partial_s \varphi_i(t, s)) m_i(ds, t) = 0.$$

The existence of  $\{(i^{k,\ell}, s^{k,\ell})\}_{\ell \in \{1, \dots, n\}}$ , which satisfies the dynamics (3.13) and equality (3.12), follows from [12, Theorem C.1].  $\square$

Since  $m \in D([0, T], \mathcal{P}([0, 1] \times I))$  and, for any  $\ell \in \{1, \dots, n\}$ ,  $(i^{k,\ell}, s^{k,\ell}) \in C^0([t_k, t_{k+1}], I) \times C^1([t_k, t_{k+1}], [0, 1])$ , one deduces from the previous lemma that, for any  $k \in \{0, \dots, N_T^n - 1\}$ ,

$$m(t_k) = \frac{1}{n} \sum_{\ell=1}^n \delta_{(i_{t_k}^{k,\ell}, s_{t_k}^{k,\ell})}. \quad (3.14)$$

The next lemma shows that, for any  $k \in \{1, \dots, N_T^n - 1\}$ , the number of indices  $\ell \in \{1, \dots, n\}$  satisfying  $s_{t_k}^{k,\ell} = s$  is equal to the number of indices  $\ell \in \{1, \dots, n\}$  satisfying  $s_{t_k}^{k+1,\ell} = s$ .

**Lemma 3.5.** *For any  $k \in \{0, \dots, N_T^n - 1\}$ , one has:*

$$\frac{1}{n} \sum_{\ell=1}^n \delta_{s_{t_{k+1}}^{k,\ell}} = \frac{1}{n} \sum_{\ell=1}^n \delta_{s_{t_{k+1}}^{k+1,\ell}},$$

where  $s^{k,\ell}$  and  $s^{k+1,\ell}$  are defined in Lemma 3.4.

*Proof.* By Lemmas 3.3 and 3.4, summing (3.12) over  $I$  one deduces that, for any  $t \in (t_k, t_{k+1})$ ,

$$\frac{1}{n} \sum_{\ell=1}^n \delta_{s_t^{k,\ell}} = \sum_{i \in I} m_i(t) = \hat{m}(t) = \frac{1}{n} \sum_{\ell=1}^n \delta_{z_t^\ell},$$

where  $z_t^\ell$  is defined in Lemma 3.3. Since  $z_t^\ell$  is continuous at  $t_{k+1}$  and,  $s^{k,\ell}$  and  $s^{k+1,\ell}$  are respectively cadlag on  $[t_k, t_{k+1}]$  and  $[t_{k+1}, t_{k+2}]$ , the previous equality holds for  $t = t_{k+1}$  and gives the result.  $\square$

**Lemma 3.6.** *For any  $k \in \{1, \dots, N_T^n - 1\}$ , there exist two collections  $\{T_{i,j}^{k,+}(s)\}_{i,j \in I, s \in [0,1]}$  and  $\{T_{i,j}^{k,-}(s)\}_{i,j \in I, s \in [0,1]}$  of subsets of  $\{1, \dots, n\}$  satisfying:*

1.  $\text{card}(T_{i,j}^{k,+}(s)) = \text{card}(T_{i,j}^{k,-}(s)) = nE_{i,j}(t_k, \{s\})$ , for any  $i, j \in I$  with  $i \neq j$  and for any  $s \in [0, 1]$ .
2.  $\{T_{i,j}^{k,+}(s)\}_{i,j \in I, s \in [0,1]}$  and  $\{T_{i,j}^{k,-}(s)\}_{i,j \in I, s \in [0,1]}$  are partitions of  $\{1, \dots, n\}$ .

**Remark 3.3.** *For some  $s \in [0, 1]$  and  $i, j \in I$ , the sets  $T_{i,j}^{k,+}(s)$  or  $T_{i,j}^{k,-}(s)$  can be empty. We maintain the terminology of "partition" in this case for the sake of simplicity.*

*Proof.* Let  $k \in \{1, \dots, N_T^n - 1\}$ ,  $i \in I$  and  $s \in [0, 1]$ . Let us set:

$$R_i^{k,-}(s) := \left\{ \ell \in \{1, \dots, n\} \mid (i_{t_k}^{k-1,\ell}, s_{t_k}^{k-1,\ell}) = (i, s) \right\},$$

and

$$R_i^{k,+}(s) := \left\{ \ell \in \{1, \dots, n\} \mid (i_{t_k}^{k,\ell}, s_{t_k}^{k,\ell}) = (i, s) \right\}.$$

The set  $R_i^{k,-}(s)$  represents the set of indices of processes defined in Lemma 3.4 that have a state equal to  $(i, s)$  at time  $t_k^-$ , just before a possible jump, while  $R_i^{k,+}(s)$  represents the set of indices of processes with a state equal to  $(i, s)$  at time  $t_k$ . By the definition of  $R_i^{k,-}(s)$  and  $R_i^{k,+}(s)$ , and by Lemma 3.5, we have, for any  $k \in \{1, \dots, N_T^n - 1\}$ ,

$$R_i^{k,-}(s) \cap R_j^{k,-}(s) = \emptyset \quad \text{and} \quad R_i^{k,+}(s) \cap R_j^{k,+}(s) = \emptyset \quad \text{for any } i, j \in I \text{ with } i \neq j, \quad (3.15)$$

$$\text{card}(R_i^{k,-}(s)) = nm_i(t_k^-, \{s\}) \quad \text{and} \quad \text{card}(R_i^{k,+}(s)) = nm_i(t_k, \{s\}), \quad (3.16)$$

$$\bigcup_{s \in [0,1]} \bigcup_{i \in I} R_i^{k,-}(s) = \bigcup_{s \in [0,1]} \bigcup_{i \in I} R_i^{k,+}(s) = \{1, \dots, n\}. \quad (3.17)$$

Hence,  $\{R_i^{k,-}(s)\}_{i \in I, s \in [0,1]}$  and  $\{R_i^{k,+}(s)\}_{i \in I, s \in [0,1]}$  are partitions of  $\{1, \dots, n\}$ . The rest of the proof consists in constructing the sets  $\{T_{i,j}^{k,-}(s)\}_{j \in I}$  and  $\{T_{i,j}^{k,+}(s)\}_{j \in I}$  that are respectively a partition of  $R_i^{k,-}(s)$  and  $R_i^{k,+}(s)$ . We define, for any  $s \in [0, 1]$ ,  $i, j \in I$  with  $j \neq i$ ,

$$c_{i,j}^k(s) := nE_{i,j}(t_k, \{s\}). \quad (3.18)$$

We define, for any  $i \in I$ ,  $c_{i,i}^k(s) := nm_i(t_k, \{s\}) - \sum_{j \in I, j \neq i} c_{j,i}^k(s)$ . By Lemma 3.2, one has:

$$c_{i,i}^k(s) = nm_i(t_k^-, \{s\}) - \sum_{j \in I, j \neq i} c_{i,j}^k(s) \geq 0, \quad (3.19)$$

where the inequality is obtained by (3.2). Since  $m(t_k) \in \mathcal{P}^n([0, 1] \times I)$  and  $E_{i,j}(t_k, \cdot) \in \mathcal{M}^n([0, 1])$ , one has  $c_{i,j}^k(s) \in \mathbb{N}$  for any  $i, j \in I$ . By (3.16) and (3.19), one has, for any  $i \in I$  and  $s \in [0, 1]$  such that  $m_i(t_k^-, \{s\}) > 0$ ,

$$\sum_{j \in I} c_{i,j}^k(s) = \text{card}(R_i^{k,-}(s)) \text{ and } \sum_{j \in I} c_{j,i}^k(s) = \text{card}(R_i^{k,+}(s)). \quad (3.20)$$

Sorting the elements of  $R_i^{k,-}(s)$  and  $R_i^{k,+}(s)$  in ascending order, we can now define the collections of subsets  $\{T_{i,j}^{k,+}(s)\}_{i,j \in I, s \in [0,1]}$  and  $\{T_{i,j}^{k,-}(s)\}_{i,j \in I, s \in [0,1]}$ . For any  $i \in I$  and  $s \in [0, 1]$ ,  $T_{i,j}^{k,-}(s)$  and  $T_{i,j}^{k,+}(s)$  are defined iteratively for  $j = 1, \dots, |I|$ :

- if  $c_{i,j}^k(s) = 0$ , then  $T_{i,j}^{k,-}(s) = T_{i,j}^{k,+}(s) = \emptyset$ ;
- otherwise,  $T_{i,j}^{k,-}(s)$  is the set of the  $c_{i,j}^k(s)$  with smallest indices of  $R_i^{k,-}(s) \setminus \bigcup_{1 \leq q < j} T_{i,q}^{k,-}(s)$  and  $T_{i,j}^{k,+}(s)$  is equal to the set of the  $c_{i,j}^k(s)$  with smallest indices of  $R_i^{k,+}(s) \setminus \bigcup_{1 \leq q < j} T_{i,q}^{k,+}(s)$ ,

we used the convention  $\bigcup_{1 \leq q < 1} T_{i,q}^{k,-}(s) = \bigcup_{1 \leq q < 1} T_{i,q}^{k,+}(s) = \emptyset$ . By (3.20) and their construction, the sets  $\{T_{i,j}^{k,+}(s)\}_{j \in I}$  and  $\{T_{i,j}^{k,-}(s)\}_{j \in I}$  are well defined and are respectively a partition of  $R_i^{k,-}(s)$  and  $R_i^{k,+}(s)$ . Since  $\{R_i^{k,-}(s)\}_{i \in I, s \in [0,1]}$  and  $\{R_i^{k,+}(s)\}_{s \in [0,1]}$  are both partitions of  $\{1, \dots, n\}$ , the conclusion follows.  $\square$

We denote by  $\mathfrak{S}(n)$  the set of permutation in  $\{1, \dots, n\}$ . The next lemma enables to express  $E_{i,j}(t^k, \cdot)$  in terms of the processes  $\{(i^{k,\ell}, s^{k,\ell})\}_{\ell \in \{1, \dots, n\}}$ .

**Lemma 3.7.** *For any  $k \in \{1, \dots, N_T^n - 1\}$ , there exists  $\sigma^k \in \mathfrak{S}(n)$  such that the measure  $E$  satisfies, for any  $i, j \in I$  and  $s \in [0, 1]$ :*

$$E_{i,j}(t^k, \{s\}) = \frac{1}{n} \text{card} \left( \left\{ \ell \in \{1, \dots, n\} \mid (i_{t_k^-}^{k-1,\ell}, s_{t_k^-}^{k-1,\ell}) = (i, s) \text{ and } (i_{t_k}^{k,\sigma^k(\ell)}, s_{t_k}^{k,\sigma^k(\ell)}) = (j, s) \right\} \right),$$

where the processes  $\{(i^{k,\ell}, s^{k,\ell})\}_{\ell \in \{1, \dots, n\}}$  are defined in Lemma 3.4,

*Proof.* Let  $\sigma^k \in \mathfrak{S}(n)$  be such that, for any  $s \in [0, 1]$  and  $i, j \in I$ , if  $c_{i,j}^k(s) > 0$ , the restriction of  $\sigma^k$  to  $T_{i,j}^{k,-}(s)$  is a bijective map from  $T_{i,j}^{k,-}(s)$  to  $T_{i,j}^{k,+}(s)$ , where  $T_{i,j}^{k,-}(s)$  and  $T_{i,j}^{k,+}(s)$  are defined in Lemma 3.6. The existence of such a permutation is guaranteed by the properties of  $\{T_{i,j}^{k,+}(s)\}_{i,j \in I, s \in [0,1]}$  and  $\{T_{i,j}^{k,-}(s)\}_{i,j \in I, s \in [0,1]}$  established in Lemma 3.6. By the construction of  $\sigma^k$ , one deduces that, for any non empty set  $T_{i,j}^{k,-}(s)$ ,

$$T_{i,j}^{k,-}(s) = \{\ell \in R_i^{k,-}(s) \mid \sigma^k(\ell) \in R_j^{k,+}(s)\},$$

where  $R_j^{k,+}(s)$  and  $R_i^{k,-}(s)$  are defined in the proof of Lemma 3.6. Finally, one has, for any  $s \in [0, 1]$  and  $i, j \in I$ ,

$$\begin{aligned} E_{i,j}(t_k, \{s\}) &= \frac{c_{i,j}^k(s)}{n} = \frac{1}{n} \text{card}(T_{i,j}^k(s)) \\ &= \frac{1}{n} \text{card} \left( \{\ell \in R_i^{k,-}(s) \mid \sigma^k(\ell) \in R_j^{k,+}(s)\} \right) \\ &= \frac{1}{n} \text{card} \left( \{\ell \in \{1, \dots, n\} \mid (i_{t_k^-}^{k-1,\ell}, s_{t_k^-}^{k-1,\ell}) = (i, s) \text{ and } (i_{t_k}^{k,\sigma^k(\ell)}, s_{t_k}^{k,\sigma^k(\ell)}) = (j, s)\} \right). \end{aligned}$$

$\square$

The next lemma shows the existence of  $n$  processes, such that  $m$  is the empirical measure of these processes and  $E$  is the empirical measure of the jumps of the processes.

**Lemma 3.8.** *There exists  $(\mathbf{i}, \mathbf{s}) \in \mathcal{X}^n(\bar{m})$ , such that  $m$  satisfies (2.18) and  $E$  satisfies (2.19).*

*Proof.* For any  $k \in \{1, \dots, N_T^n - 1\}$ , we consider the permutation  $\hat{\sigma}^k \in \mathfrak{S}(n)$ , defined by:

$$\hat{\sigma}^k := \sigma^k \circ \sigma^{k-1} \circ \dots \circ \sigma^1, \quad (3.21)$$

where  $\sigma^k$  is defined for any  $k \in \{1, \dots, N_T^n - 1\}$  in Lemma 3.7. For  $k = 0$ , we define  $\hat{\sigma}^0$  by  $\hat{\sigma}^0(\ell) = \ell$ , for any  $\ell \in \{1, \dots, n\}$ . For any  $\ell \in \{1, \dots, n\}$ , we consider the processes  $(i^\ell, s^\ell)$  defined on  $[0, T]$  by:

$$i_t^\ell := i_t^{k, \hat{\sigma}^k(\ell)} \text{ and } s_t^\ell := s_t^{k, \hat{\sigma}^k(\ell)} \text{ for any } t \in [t_k, t_{k+1}), \text{ and } i_T^\ell := \lim_{t \rightarrow T} i_t^\ell, \quad (3.22)$$

where  $\{(i^{k, \ell}, s^{k, \ell})\}_{\ell \in \{1, \dots, n\}}$  is defined in Lemma 3.4. Thus, one has for any  $k \in \{0, \dots, N_T^n - 1\}$  and  $t \in [t_k, t_{k+1})$ :

$$\frac{ds_t^\ell}{dt} = \frac{ds_t^{k, \hat{\sigma}^k(\ell)}}{dt} = b(i_t^{k, \hat{\sigma}^k(\ell)}, s_t^{k, \hat{\sigma}^k(\ell)}) = b(i_t^\ell, s_t^\ell),$$

and

$$i_t^\ell = i_t^{k, \hat{\sigma}^k(\ell)} = i_{t_k}^{k, \hat{\sigma}^k(\ell)} = i_{t_k}^\ell.$$

By the definitions  $\hat{\sigma}^k$  and  $\sigma^k$  in Lemma 3.7, one gets for any  $\ell \in \{1, \dots, n\}$ :

$$s_{t_{k+1}}^{k, \ell} = s_{t_{k+1}}^{k+1, \sigma^k(\ell)},$$

and therefore:

$$s_{t_{k+1}}^\ell = \lim_{\tau \uparrow t_{k+1}} s_\tau^\ell.$$

Thus, one has for any  $t \in [0, T)$ :

$$m^n(t) := \frac{1}{n} \sum_{\ell=1}^n \delta_{(i_t^\ell, s_t^\ell)}.$$

Since there is no jump at time  $t = T$  and since  $i^\ell$  and  $s^\ell$  are continuous at  $T$ , equality also holds for  $t = T$ . Finally, by Lemma 3.7, one has:

$$E_{i,j} = \frac{1}{n} \sum_{\ell=1}^n \sum_{k=1}^{N_T^n - 1} 1_i(i_{t_k}^{k-1, \ell}) 1_j(i_{t_k}^{k, \sigma^k(\ell)}) \delta_{t_k} \otimes \delta_{s_{t_k}^{k-1, \ell}} = \frac{1}{n} \sum_{\ell=1}^n \sum_{k=1}^{N_T^n - 1} 1_i(i_{t_k}^\ell) 1_j(i_{t_k}^\ell) \delta_{t_k} \otimes \delta_{s_{t_k}^\ell}.$$

Taking  $(\mathbf{i}, \mathbf{s}) := \{(i^\ell, s^\ell)\}_{\ell \in \{1, \dots, n\}}$ , one has  $(\mathbf{i}, \mathbf{s}) \in \mathcal{X}^n(\bar{m})$  and the conclusion follows.  $\square$

We are now able to prove Theorem 3.1.

*Proof of Theorem 3.1.* This is a direct consequence of Lemmas 3.1 and 3.8.  $\square$

## 4 The convergence result

This section is devoted to the proofs of Theorem 2.1.1, reformulated in Theorem 4.1 and proved in Section 4.1, Theorem 2.1.2 reformulated in Theorem 4.2 and proved in Section 4.2, and Theorem 2.2 proved in Section 4.3. We assume in this section that the time and space parameters  $\Delta t$  and  $\Delta s$  are such that (2.14) and (2.15) are satisfied.

## 4.1 $\Gamma$ -lower limit result

We reformulate the first result of the paper, Theorem 2.1.1 in Theorem 4.1.

**Theorem 4.1.** *For any sequence  $\{\bar{m}^n\}_n$  weakly converging to a measure  $\bar{m} \in \mathcal{P}([0, 1] \times I)$  and satisfying Assumptions 2 and 3, we have:*

$$\inf_{(m,E) \in \mathcal{S}(\bar{m}, D)} J(m, E) \leq \liminf_{n \rightarrow \infty} \inf_{(i,s) \in \mathcal{T}^n(\bar{m}^n, D)} \mathcal{J}^n(i, s). \quad (4.1)$$

The rest of this subsection is dedicated to the proof of Theorem 4.1. The proof is based on Lemmas 4.1 and 4.2, for which we need the following preliminary results.

By Corollary 3.1 and Remark 3.2 we know that there exists a sequence  $\{(m^n, E^n)\}_n$  such that, for any  $n \in \mathbb{N}$ ,  $(m^n, E^n) \in \mathcal{S}^n(\bar{m}^n, D)$  and

$$J^n(m^n, E^n) = \inf_{(i,s) \in \mathcal{T}^n(\bar{m}^n, D)} \mathcal{J}^n(i, s).$$

The proof of Theorem 4.1 relies on the existence of a limit point  $(m^*, E^*)$  of the sequence  $\{(m^n, E^n)\}_n$  that belongs to the set  $\mathcal{S}(\bar{m}, D)$ . By inequality (2.8), we have

$$\sum_{i,j \in I} \sum_{k=1}^{N_T^n - 1} \sum_{p=0}^{N_s^n - 1} L \left( \frac{E_{i,j}(\{t_k\}, [y_p, y_{p+1}])}{\Delta t m_i(t_k^-, [y_p, y_{p+1}])} \right) \Delta t m_i(t_k^-, [y_p, y_{p+1}]) \leq C_0, \quad (4.2)$$

where the constant  $C_0 > 0$  only depends on  $T$ ,  $\|c\|_\infty$  and  $\|g\|_\infty$ . Inequality (4.2) implies that  $\{E_{i,j}^n([0, T] \times [0, 1])\}_n$  is uniformly bounded. Indeed, let  $t, \bar{t} \in [0, T]$ , with  $t \leq \bar{t}$ . If there is no  $t_q \in \{0, \dots, k\Delta t, \dots, T\}$  satisfying  $t \leq t_q \leq \bar{t}$ , then by (3.1)  $\sum_{i,j \in I} E_{i,j}^n([t, \bar{t}], [0, 1]) = 0$ . Otherwise, let  $k_1, k_2 \in \{0, \dots, N_T^n\}$  be such that  $t_{k_1} - \Delta t < t \leq t_{k_1} \leq t_{k_2} \leq \bar{t} < t_{k_2} + \Delta t$ . By (3.1) and Cauchy-Schwartz inequality, one has:

$$\begin{aligned} \left( \sum_{i,j \in I} E_{i,j}^n([t, \bar{t}], [0, 1]) \right)^2 &= \left( \sum_{i,j \in I} \sum_{k=k_1}^{k_2} \sum_{p=0}^{N_s^n - 1} E_{i,j}^n(\{t_k\}, [y_p, y_{p+1}]) \right)^2 \\ &\leq \left( \sum_{i,j \in I} \sum_{k=k_1}^{k_2} \sum_{p=0}^{N_s^n - 1} \Delta t m_i^n(t_k^-, [y_p, y_{p+1}]) \right) \left( \sum_{i,j \in I} \sum_{k=k_1}^{k_2} \sum_{p=0}^{N_s^n - 1} \frac{(E_{i,j}^n(\{t_k\}, [y_p, y_{p+1}]))^2}{\Delta t m_i^n(t_k^-, [y_p, y_{p+1}])} \right) \\ &\leq |I| \Delta t (k_2 - k_1 + 1) \sum_{i,j \in I} \sum_{k=k_1}^{k_2} \sum_{p=0}^{N_s^n - 1} C \left( L \left( \frac{E_{i,j}^n(\{t_k\}, [y_p, y_{p+1}])}{\Delta t m_i^n(t_k^-, [y_p, y_{p+1}])} \right) + C \right) \Delta t m_i^n(t_k^-, [y_p, y_{p+1}]) \\ &\leq C |I| (\bar{t} - t + \Delta t) (C_0 + C), \end{aligned} \quad (4.3)$$

where the two last inequalities are obtained by Assumption 5 and inequality (4.2). Taking  $t = 0$  and  $\bar{t} = T$ , one obtains:

$$\sum_{i,j \in I} E_{i,j}^n([0, T], [0, 1]) \leq \sqrt{CT|I|}, \quad (4.4)$$

$C >$  is a constant that depends on Assumption 5 and on  $C_0$ . By (4.4), there exists a limit point  $E^* \in \mathcal{M}^+([0, T] \times [0, 1] \times I^2)$  of the sequence  $\{E^n\}_n$ , w.r.t. the weak topology induced by  $\mathcal{M}^+([0, T] \times [0, 1] \times I^2)$ .

Now we are ready to prove the two lemmas needed for the proof of Theorem 4.1. First Lemma states that  $\{m^n\}_n$  admits a limit point  $m^* \in C^0([0, T], \mathcal{P}([0, 1] \times I))$ .

**Lemma 4.1.** *There exists  $m^* \in C^0([0, T], \mathcal{P}([0, 1] \times I))$  such that, up to a subsequence,  $\{m^n\}_n$  uniformly converges in time to  $m^*$  w.r.t. the Wasserstein distance  $\mathcal{W}$ . In addition,  $(m^*, E^*)$  is a weak solution of (2.9) with initial data  $\bar{m}$ , and it satisfies (2.10).*

*Proof.* By (4.3) and the continuity equation (2.9) satisfied by  $(m^n, E^n)$ , one has, for any  $t, \bar{t} \in [0, T]$  and  $n \in \mathbb{N}$ ,

$$\mathcal{W}(m^n(t), m^n(\bar{t})) \leq \sqrt{|t - \bar{t}| + \Delta t} (\sqrt{T} \|b\|_\infty + \sqrt{C|I|}).$$

By adapting the Ascoli-Arzelà Theorem, one can deduce the existence of  $m^* : [0, T] \rightarrow \mathcal{P}([0, 1] \times I)$ , that is 1/2-Hölder continuous in time w.r.t. the distance  $\mathcal{W}$  and, such that, up to a subsequence,  $\{m^n\}_n$  uniformly converges in time to  $m^*$  w.r.t. to  $\mathcal{W}$ . Finally, since (2.9) and (2.10) are linear w.r.t. the couple  $(m, E)$  and that, for any  $n \in \mathbb{N}$ ,  $(m^n, E^n)$  is a weak solution of (2.9) and satisfies (2.10), one can deduce, by the respective weak convergence of  $(m^n, E^n)$  and  $\{\bar{m}^n\}_n$  to  $(m^*, E^*)$  and  $\bar{m}$ , that  $(m^*, E^*)$  is also a weak solution of (2.9) with initial distribution  $\bar{m}$ , and satisfies (2.10).  $\square$

The next lemma states the absolute continuity of  $E^*$  w.r.t. the measure  $m^*$ .

**Lemma 4.2.** *For any  $i, j \in I$ ,  $E_{i,j}^*$  is absolutely continuous w.r.t. the measure  $m_i^*$ . Denoting by  $\alpha_{i,j}^*$  the Radon-Nikodym derivative of  $E_{i,j}^*$  w.r.t. the measure  $m_i^*$ , we have  $\alpha_{i,j}^* \in L_{m_i^*}^2([0, T] \times [0, 1])$ .*

*Proof.* We define for any  $n \in \mathbb{N}$  and  $i, j \in I$ , the curve of measure  $\tilde{m}^n : [0, T] \rightarrow \mathcal{P}([0, 1] \times I)$  by:

$$\tilde{m}_i^n(t, ds) := \sum_{k=0}^{N_T^n-1} \sum_{p=0}^{N_s^n-1} 1_{[t_k, t_{k+1})}(t) 1_{[y_p, y_{p+1})}(s) \frac{m_i^n(t_k^-, [y_p, y_{p+1}))}{\Delta s} ds. \quad (4.5)$$

By the uniform weak convergence of  $\{m^n\}_n$  to  $m^*$  in Lemma 4.1 and the definition of  $\tilde{m}^n$ , one can show that for any  $t \in [0, T]$ ,  $\{\tilde{m}^n(t)\}_n$  weakly converges to  $m^*(t)$  in  $\mathcal{P}([0, 1] \times I)$ . For any  $n \in \mathbb{N}$  and  $i, j \in I$ , we introduce  $\alpha_{i,j}^n : [0, T] \times [0, 1] \rightarrow \mathbb{R}_+$ :

$$\alpha_{i,j}^n(t, s) := \frac{E_{i,j}^n(\{t_k\}, [y_p, y_{p+1}))}{\Delta t m_i^n(t_k^-, [y_p, y_{p+1}))} \quad \text{where } t \in [t_k, t_{k+1}) \quad \text{and } s \in [y_p, y_{p+1}), \quad (4.6)$$

and we define the measure  $\tilde{E}_{i,j}^n$  on  $[0, T] \times [0, 1]$  by:  $\tilde{E}_{i,j}^n(dt, ds) := \alpha_{i,j}^n \tilde{m}_i^n(t, ds) dt$ . One can observe that:

$$\begin{aligned} \sum_{i,j \in I, i \neq j} \tilde{E}_{i,j}^n([0, T] \times [0, 1]) &= \sum_{i,j \in I, i \neq j} \sum_{k=0}^{N_T^n-1} \sum_{p=0}^{N_s^n-1} \int_{t_k}^{t_{k+1}} \int_{y_p}^{y_{p+1}} \frac{E_{i,j}^n(\{t_k\}, [y_p, y_{p+1}))}{\Delta s \Delta t} dt ds \\ &= \sum_{i,j \in I, i \neq j} E_{i,j}^n([0, T] \times [0, 1]). \end{aligned} \quad (4.7)$$

Using the previous equality and (4.4),  $\{\tilde{E}_{i,j}^n\}_n$  is tight. Thus, there exists a measure  $\tilde{E}_{i,j}$  such that a subsequence of  $\{\tilde{E}_{i,j}^n\}_n$  weakly converges to  $\tilde{E}_{i,j}$ . We define the function  $\Theta : \mathcal{M}^+([0, T] \times [0, 1] \times I) \times \mathcal{M}^+([0, T] \times [0, 1] \times I \times I) \rightarrow \mathbb{R} \cup \{+\infty\}$  by:

$$\Theta(m, E) : \begin{cases} \sum_{i,j \in I, i \neq j} \int_0^T \int_0^1 L(\alpha_{i,j}(t, s)) m_i(dt, ds) & \text{if } E_{i,j} \ll m_i \text{ and } \alpha_{i,j} := \frac{dE_{i,j}}{dm_i} \text{ with } \alpha_{i,j} \geq 0, \\ +\infty & \text{otherwise.} \end{cases}$$

The function  $\Theta$  is convex and l.s.c. w.r.t. the weak topology in  $\mathcal{M}^+([0, T] \times [0, 1] \times I) \times \mathcal{M}^+([0, T] \times [0, 1] \times I^2)$  (see e.g. [47, Proposition 5.18]). From the definition of  $\tilde{E}^n$ , it turns out that  $\tilde{E}_{i,j}^n \ll \tilde{m}_i^n$  with  $\frac{d\tilde{E}_{i,j}^n}{d\tilde{m}_i^n} = \alpha_{i,j}^n$ . We have:

$$\begin{aligned} \Theta(\tilde{m}^n, \tilde{E}^n) &= \sum_{i,j \in I} \int_0^T \int_0^1 L(\alpha_{i,j}^n(t, s)) \tilde{m}_i^n(t, s) dt ds \\ &= \sum_{i,j \in I} \sum_{k=0}^{N_T^n-1} \sum_{p=0}^{N_s^n-1} L\left(\frac{E_{i,j}^n(\{t_k\}, [y_p, y_{p+1}))}{\Delta t m_i^n(t_k^-, [y_p, y_{p+1}))}\right) m_i^n(t_k^-, [y_p, y_{p+1})) \Delta t \\ &\leq C_0. \end{aligned}$$

where the constant  $C_0 > 0$  is defined in (4.2). Using that  $(m_i^n, \tilde{E}_{i,j}^n)$  weakly converges to  $(m_i^*, \tilde{E}_{i,j})$  and by the previous inequality, one deduces that  $\Theta(m^*, \tilde{E}) \leq C_0$  and thus, for any  $i, j \in I$ :  $\tilde{E}_{i,j} \ll m_i^*$ . We now prove that  $\tilde{E}_{i,j} = E_{i,j}^*$  by showing that  $\tilde{E}_{i,j}^n - E_{i,j}^n$  weakly converges to 0 in  $\mathcal{M}^+([0, T] \times [0, 1] \times I^2)$ . By the definition of  $\tilde{E}^n$  and (4.4) one has  $\tilde{E}_{i,j}^n([0, T] \times [0, 1] \times I^2) = E_{i,j}^n([0, T] \times [0, 1] \times I^2) \leq \sqrt{CT|I|}$  for any  $n \in \mathbb{N}$ . Let  $\varphi : [0, T] \times [0, 1] \rightarrow \mathbb{R}$  be a 1-Lipschitz continuous function. Using (4.4), we have:

$$\begin{aligned} &\int_0^T \int_0^1 \varphi(t, s) (\alpha_{i,j}^n(t, s) \tilde{m}_i^n(t, ds) dt - E_{i,j}^n(dt, ds)) \\ &= \sum_{k=0}^{N_T^n-1} \sum_{p=0}^{N_s^n-1} \int_{t_k}^{t_{k+1}} \int_{y_p}^{y_{p+1}} \varphi(t, s) \left( \frac{E_{i,j}^n(\{t_k\}, [y_p, y_{p+1}))}{\Delta s \Delta t} ds dt - E_{i,j}^n(dt, ds) \right) \\ &\leq \sum_{k=0}^{N_T^n-1} \sum_{p=0}^{N_s^n-1} \int_{t_k}^{t_{k+1}} \int_{y_p}^{y_{p+1}} \frac{\Delta s + \Delta t}{\Delta s \Delta t} E_{i,j}^n(\{t_k\}, [y_p, y_{p+1})) ds dt \\ &\leq (\Delta s + \Delta t) E_{i,j}^n([0, T] \times [0, 1]) \\ &\leq \sqrt{CT|I|} (\Delta s + \Delta t), \end{aligned} \quad (4.8)$$



and therefore  $\mathcal{W}(\tilde{E}_{i,j}^n, E_{i,j}^n) \rightarrow 0$ . We deduce that  $E_{i,j}^* = \tilde{E}_{i,j}$  and we can define the Radon-Nikodym derivative  $\alpha_{i,j}^* := \frac{dE_{i,j}^*}{dm_i^*}$ . Since  $\Theta(m_i^*, E_{i,j}^*) < \infty$ , we deduce for any  $i, j \in I$  that  $\alpha_{i,j}^* \in L_{m_i^*}^2([0, T] \times [0, 1])$  from Assumption 5.  $\square$

We can now prove Theorem 4.1.

*Proof of Theorem 4.1.* By Lemmas 4.1 and 4.2, one has that  $(m^*, E^*) \in \mathcal{S}(\bar{m}, D)$ . Since  $c \in C^1([0, T] \times [0, 1] \times I)$  and  $g \in C^1([0, 1] \times I)$ , by the w.l.s.c. of  $\Theta$  defined in Lemma 4.2, we have:

$$\inf_{(m,E) \in \mathcal{S}(\bar{m}, D)} J(m, E) \leq J(m^*, E^*) \leq \liminf_{n \rightarrow \infty} J^n(m^n, E^n) = \liminf_{n \rightarrow \infty} \inf_{(\mathbf{i}, \mathbf{s}) \in \mathcal{T}^n(\bar{m}^n, D)} \mathcal{J}^n(\mathbf{i}, \mathbf{s}),$$

and the conclusion follows.  $\square$

## 4.2 Upper bound of the value of the finite population problem

We reformulate the second main result of this paper, Theorem 2.1.2, in Theorem 4.2 and gives a proof.

**Theorem 4.2.** *There exist  $C > 0$  such that, for any sequence  $\{\bar{m}^n\}_n$  in  $\mathcal{P}^n([0, 1] \times I)$  satisfying Assumptions 2 and 3, one has, for any  $n \in \mathbb{N}^*$ ,*

$$\inf_{(\mathbf{i}, \mathbf{s}) \in \mathcal{T}^n(\bar{m}^n, D)} \mathcal{J}^n(\mathbf{i}, \mathbf{s}) - \frac{C}{n^{\frac{1}{3}}} \leq \inf_{(m,E) \in \mathcal{S}(\bar{m}^n, D)} J(m, E). \quad (4.9)$$

Theorem 4.2 provides an upper bound on the value of Problem (2.7). Note that the constants in this theorem depend on  $\varepsilon^0$  (defined in Assumption 3) and not on the choice of the sequence  $\{\bar{m}^n\}_n$ . To prove this theorem, we first show in Section 4.2.1 how to implement an optimal control of the mean field control problem to a finite population of PEVs, such that the constraint (2.4) is satisfied (Corollary 4.1). Then, in Section 4.2.2 we give an estimate of the Wasserstein distance between the resulting empirical distribution of the finite population of processes and the mean field distribution. Finally, we finish the proof of Theorem 4.2 in Section 4.2.3.

### 4.2.1 Transfer procedure for a finite number of PEVs using a mean field control

The goal of this subsection is to present how a bounded mean field control  $\alpha$  can be implemented for a finite population of PEVs. We provide a convergence rate of the empirical distribution to the mean field distribution. Let us fix a sequence  $\{\bar{m}^n\}_n$  of initial distribution in (2.9) satisfying Assumptions 2 and 3. We highlight that, all the constants in this section depend on  $\varepsilon^0$  and not on the choice of the sequence  $\{\bar{m}^n\}_n$ . Let  $N \in \mathbb{N}$  be such that,

$$N > \left( \frac{2C^*}{\varepsilon^0} \right)^3, \quad (4.10)$$

where  $C^* > 0$  is introduced later in (4.17). For any  $n \in \mathbb{N}$ , we consider  $(m^{*,n}, E^{*,n})$ , a minimizer of  $J$  over the set  $\mathcal{S}(\bar{m}^n, D - C^*/n^{\frac{1}{3}})$ . We define  $\alpha^n$  by  $\alpha_{i,j}^n := \frac{dm_{i,j}^{*,n}}{dE_{i,j}^{*,n}}$ , for any  $i, j \in I$ . By Assumption 3 and the definition of  $N$  in (4.10), one has for any  $n \geq N$ , and  $(i, t) \in I \times [0, T]$ ,

$$\left( D_i(t) - \frac{C^*}{n^{\frac{1}{3}}} \right) - m_i^n(0, [0, 1]) \leq \frac{\varepsilon^0}{2}. \quad (4.11)$$

By the previous inequality and [48, Theorem 2.1], we have  $\alpha^n \in L^\infty([0, T] \times [0, 1] \times I^2)$  and, for any  $(i, j, t, s) \in I^2 \times [0, T] \times [0, 1]$ ,

$$\alpha_{i,j}^n(t, s) = H' \left( \beta_{i,j}^n(t, s) + \int_t^T (\lambda_i^n - \lambda_j^n)(d\tau) \right), \quad (4.12)$$

where  $\beta^n \in \text{Lip}([0, T] \times [0, 1] \times I^2)$  and  $\lambda^n \in \mathcal{M}^+([0, T] \times I)$ . By Assumption 5,  $H'$  is Lipschitz continuous on  $\mathbb{R}$  and thus,  $\alpha^n$  is Lipschitz continuous in space uniformly in time. By [48, Lemma 5.3], the upper bound of  $\lambda^n([0, T] \times I)$  only depends on  $\varepsilon^0$  in (4.11) and on the data of the problem. In addition, by [48, Theorem 2.1], for any  $n \in \mathbb{N}^*$ , there exists  $\varphi^n(\text{Lip}([0, T] \times [0, 1] \times I) + BV([0, T] \times I))$  such that  $\alpha_{i,j}^n = H'(\varphi_i^n - \varphi_j^n)$ , where by [48, Remark 4.5],

upper bounds on  $\|\varphi^n\|_\infty$  and  $\|\partial_s \varphi^n\|_\infty$  depend on the data of the problem and on  $\lambda^n([0, T] \times I)$ . Since (4.11) is satisfied for any  $n > N$ , there exists  $\bar{C} > 0$  that depends on  $\varepsilon^0$ , such that, for any  $n > N$ ,

$$\max(\|\alpha^n\|_\infty, \|\partial_s \alpha^n\|_\infty, \lambda^n([0, T] \times I)) \leq \bar{C}. \quad (4.13)$$

**Transfer procedure** We consider  $n > N$  PEVs with an initial state distribution  $\bar{m}^n$ . At each time step  $t_k \in \{\Delta t, \dots, \Delta t(N_T^n - 1)\}$  and for any  $p \in \{0, \dots, N_s^n - 1\}$ , we apply the following steps:

- We define  $V_i^{k,p}$ , the set of indices of PEVs in the mode of charging  $i \in I$  with a SoC in the range  $[y_p, y_{p+1})$  at time  $t_k$ , and set  $N_i^{k,p} := \text{card}(V_i^{k,p})$ .
- The number of PEVs in  $V_i^{k,p}$  transferred from the mode of charging  $i \in I$  to the mode  $j \in I$  at time  $t_k$  is denoted by  $a_{i,j}^n(k,p)$  and is defined by:  $a_{i,j}^n(k,p) := \lfloor \Delta t \alpha_{i,j}^n(t_k, y_p) N_i^{k,p} \rfloor$ . The transferred vehicles are the ones with the lowest indices. We denote by  $T_{i,j}^{k,p}$  the set of indices of the transferred vehicles. We have:  $T_{i,j}^{k,p} \subset V_i^{k,p}$ .

**Remark 4.1.** By inequalities (2.15) and (4.13), one has, for any  $n \in \mathbb{N}$ ,  $\Delta t \leq \frac{1}{|I| \|\alpha^n\|_\infty}$ . It implies that, for any

$i, k, \ell$ ,  $\sum_{j=1, j \neq i}^n a_{i,j}^n(k,p) \leq N_i^{k,p}$ . Thus, the maximal amount of PEVs with a state in  $\{i\} \times [y_p, y_{p+1})$  that can be transferred is bounded by the total number of PEVs with a state in  $i \times [y_p, y_{p+1})$ .

**Remark 4.2.** One can observe that PEVs with a SoC equal to 1 are not taken into account in the transfer procedure given above. This is without consequence because, following Remark 2.1 and Assumption 2, there is never a PEV with a SoC equal to 1.

Recall that  $\bar{m}^n \in \mathcal{P}^n([0, 1] \times I)$  is the initial distribution of the states of the population of PEVs. The procedure defined above enables to construct a unique set of  $n$  processes  $\{(i^\ell, s^\ell)\}_{\ell \in \{1, \dots, n\}} \in \mathcal{X}^n(\bar{m}^n)$ . For any  $\ell \in \{1, \dots, n\}$  and  $t \in [0, T]$ ,  $i_t^\ell$  and  $s_t^\ell$  denote respectively the mode of charging and the SoC of the  $\ell^{\text{th}}$  PEV at time  $t$ . By Theorem 3.1, the pair  $(m^n, E^n)$  defined by (2.18) and (2.19) belongs to  $\mathcal{Q}^n(\bar{m}^n)$ .

There exists a pair  $(m^n, E^n) \in \mathcal{Q}^n(\bar{m}^n)$  that is the empirical distribution of the states of the population of PEVs and of the jumps and that satisfies (2.18) and (2.19). In addition, the following equalities hold, for any  $k \in \{0, \dots, N_T^n - 1\}$ ,  $p \in \{0, \dots, N_s^n - 1\}$  and  $i, j \in I$ ,

$$m_i^n(t_k^-, [y_p, y_{p+1})) = \frac{N_i^{k,p}}{n}, \quad (4.14)$$

$$E_i^n([t_k, t_{k+1}), [y_p, y_{p+1})) = \frac{a_{i,j}^n(k,p)}{n}. \quad (4.15)$$

The theorem below gives an estimate of the Wasserstein distance between  $m^{*,n}$  and  $m^n$ .

**Theorem 4.3.** *There exists  $C > 0$ , such that for any  $n > N$  and  $t \in [0, T]$ ,*

$$\mathcal{W}(m^{*,n}(t), m^n(t)) \leq \frac{C}{n^{\frac{1}{3}}}. \quad (4.16)$$

We postpone the proof to Section 4.2.2. As we show below, the rate  $n^{-\frac{1}{3}}$  in the right hand-side of (4.16) comes from inequality (2.14).

Next result shows that the previous theorem enables to find strategies, based on a mean field optimal control, satisfying the constraint (2.4). We now set:

$$C^* = C + 1, \quad (4.17)$$

where  $C > 0$  is the constant defined in Theorem 4.3.

**Corollary 4.1.** *One has, for any  $n \geq N$ ,*

$$\frac{1}{n^{\frac{1}{3}}} \leq D_i(t) - m_i^n(t, [0, 1]) \quad \forall (i, t) \in I \times [0, T]. \quad (4.18)$$

*Proof.* Observing that

$$D_i(t) - m_i^{*,n}(t, [0, 1]) - \mathcal{W}(m^{*,n}(t), m^n(t)) \leq D_i(t) - m_i^n(t, [0, 1]),$$

by Theorem 4.3 and since  $(m^{*,n}, E^{*,n}) \in \mathcal{S}(\bar{m}^n, D - \frac{C^*}{n^{\frac{1}{3}}})$ , one deduces, for any  $(i, t) \in I \times [0, T]$ ,

$$\frac{C^* - C}{n^{\frac{1}{3}}} \leq D_i(t) - m_i^n(t, [0, 1]).$$

The conclusion follows from the previous inequality and inequality (4.17).  $\square$

#### 4.2.2 Proof of Theorem 4.3

We start by stating some preliminary results.

**Lemma 4.3.** *For any function  $\varphi \in C^1([0, T] \times [0, 1] \times I)$ , we have, for any  $i \in I$ ,*

$$\begin{aligned} \int_0^T \int_0^1 (\partial_t \varphi_i(t, s) + b_i(t) \partial_s \varphi_i(t, s)) m_i^n(t, ds) dt &= \int_0^1 \varphi_i(T, s) m_i^n(T, ds) - \varphi_i(0, s) \bar{m}_i^n(ds) \\ &+ \frac{1}{n} \sum_{k=1}^{N_T^n - 1} \sum_{p=0}^{N_s^n - 1} \sum_{j \in I, j \neq i} \left( \sum_{\ell \in T_{i,j}^{k,p}} \varphi_i(t_k, s_{t_k}^\ell) - \sum_{\ell \in T_{j,i}^{k,p}} \varphi_i(t_k, s_{t_k}^\ell) \right). \end{aligned}$$

*Proof.* This lemma is a direct consequence of the proof of Lemma 3.1.  $\square$

We introduce  $\check{m}^n \in L^1([0, T] \times [0, 1] \times I)$  and  $\check{\alpha}^n \in L^\infty([0, T] \times [0, 1] \times I)$  defined, for any  $i, j \in I$ ,  $t \in [t_k, t_{k+1})$  and  $s \in [y_p, y_{p+1})$ , by:

$$\check{m}_i^n(t, s) := \frac{1}{\Delta s} m_i^n(t_k, [y_p, y_{p+1})) \text{ and } \check{\alpha}_{i,j}^n(t, s) := \alpha_{i,j}^n(t_k, y_p). \quad (4.19)$$

We observe that:  $\check{m}_i^n(t, s) = N_i^{k,p} / (\Delta s n)$  for any  $t \in [t_k, t_{k+1})$  and  $s \in [y_p, y_{p+1})$ .

**Lemma 4.4.** *There exists  $C > 0$  such that for any  $n \geq N$  and any function  $\varphi \in C^0([0, T] \times [0, 1] \times I)$  and  $i \in I$ , we have:*

$$\left| \int_0^T \int_0^1 \varphi_i(t, s) (\alpha_{i,j}^n(t, s) m_i^n(t, ds) - \check{\alpha}_{i,j}^n(t, s) \check{m}_i^n(t, s) ds) dt \right| \leq C \|\varphi\|_\infty (\Delta s + \Delta t). \quad (4.20)$$

*Proof.* We observe for any  $i, j \in I$ :

$$\begin{aligned} & \left| \int_0^T \int_0^1 \varphi_i(t, s) (\alpha_{i,j}^n(t, s) m_i^n(t, ds) - \check{\alpha}_{i,j}^n(t, s) \check{m}_i^n(t, s) ds) dt \right| \\ &= \left| \sum_{p=0}^{N_s^n - 1} \sum_{k=0}^{N_T^n - 1} \int_{t_k}^{t_{k+1}} \left( \int_{y_p}^{y_{p+1}} \varphi_i(t, s) \alpha_{i,j}^n(t, s) m_i^n(t, ds) - \int_{y_p}^{y_{p+1}} \varphi_i(t, s) \alpha_{i,j}^n(t_k, y_p) \frac{N_i^{k,p}}{n \Delta s} ds \right) dt \right| \\ &\leq \|\varphi\|_\infty \sum_{p=0}^{N_s^n - 1} \sum_{k=0}^{N_T^n - 1} \int_{t_k}^{t_{k+1}} \left| \left( \sum_{\ell \in V_i^{k,p}} \frac{\alpha_{i,j}^n(t, s_t^\ell)}{n} \right) - \alpha_{i,j}^n(t_k, y_p) \frac{N_i^{k,p}}{n} \right| dt \\ &= \|\varphi\|_\infty \sum_{p=0}^{N_s^n - 1} \sum_{k=0}^{N_T^n - 1} \int_{t_k}^{t_{k+1}} \left| \sum_{\ell \in V_i^{k,p}} \left( \frac{\alpha_{i,j}^n(t, s_t^\ell)}{n} - \frac{\alpha_{i,j}^n(t_k, y_p)}{n} \right) \right| dt. \end{aligned} \quad (4.21)$$

By equality (4.12), and the uniform Lipschitz continuity property of  $H'$  and  $\beta$ , one has, for any  $\ell \in V_i^{k,p}$  and  $t \in [t_k, t_{k+1})$ :

$$\begin{aligned} |\alpha_{i,j}^n(t, s_t^\ell) - \alpha_{i,j}^n(t_k, y_p)| &\leq C \left( |\beta_{i,j}^n(t, s_t^\ell) - \beta_{i,j}^n(t_k, y_p)| + \int_{t_k}^t (\lambda_i^n + \lambda_j^n)(d\tau) \right) \\ &\leq C \left( \Delta s + \Delta t + \int_{t_k}^t (\lambda_i^n + \lambda_j^n)(d\tau) \right), \end{aligned} \quad (4.22)$$

where the second inequality is deduced by the fact that, if  $s_{t_k}^\ell \in [y_p, y_{p+1})$ , then  $|s_t^\ell - y_p| \leq (\Delta s + \Delta t \|b\|_\infty)$  for any  $t \in [t_k, t_{k+1})$ . Summing the previous inequality over  $\ell \in V_i^{k,p}$ , one has, for any  $t \in [t_k, t_{k+1})$ ,

$$\left| \sum_{\ell \in V_i^{k,p}} \left( \frac{\alpha_{i,j}^n(t, s_{t_k}^\ell)}{n} - \frac{\alpha_{i,j}^n(t_k, y_p)}{n} \right) \right| \leq \frac{N_i^{k,p}}{n} C \left( \Delta s + \Delta t + \int_{t_k}^t (\lambda_i^n + \lambda_j^n)(d\tau) \right). \quad (4.23)$$

By (4.23) and (4.13), inequality (4.21) becomes:

$$\begin{aligned} & \left| \int_0^T \int_0^1 \varphi_i(t, s) (\alpha_{i,j}^n(t, s) m_i^n(t, ds) - \check{\alpha}_{i,j}^n(t, s) \check{m}^n i(t, s) ds) dt \right| \\ & \leq \|\varphi\|_\infty \sum_{p=0}^{N_s^n-1} \sum_{k=0}^{N_T^n-1} \int_{t_k}^{t_{k+1}} \frac{N_i^{k,p}}{n} C \left( \Delta s + \Delta t + \int_{t_k}^t (\lambda_i^n + \lambda_j^n)(d\tau) \right) dt \\ & \leq \|\varphi\|_\infty \sum_{k=0}^{N_T^n-1} \sum_{p=0}^{N_s^n-1} \frac{N_i^{k,p}}{n} C \left( \Delta s + \Delta t + \int_{t_k}^{t_{k+1}} (\lambda_i^n + \lambda_j^n)(d\tau) \right) \Delta t \\ & \leq \|\varphi\|_\infty C(\Delta s + \Delta t). \end{aligned}$$

□

**Lemma 4.5.** For any  $i \in I$ ,  $n \geq N$  and any function  $\varphi \in C^1([0, T] \times [0, 1] \times I)$ , with Lipschitz constant denoted by  $\gamma_\varphi > 0$ , we have:

$$\begin{aligned} & \left| \int_0^T \int_0^1 (\partial_t \varphi_i(t, s) + b_i(s) \partial_s \varphi_i(t, s)) m_i^n(t, ds) dt - \int_0^1 \varphi_i(T, s) m_i^n(T, ds) - \varphi_i(0, s) \bar{m}_i^n(ds) \right. \\ & \quad \left. - \int_0^T \int_0^1 \varphi_i(t, s) (\check{\alpha}_{i,j}^n(t, s) \check{m}_i^n(t, s) - \check{\alpha}_{j,i}^n(t, s) \check{m}_j^n(t, s)) dt ds \right| \\ & \leq C(\gamma_\varphi + \|\varphi\|_\infty) \left( \Delta s + \Delta t + \frac{1}{n \Delta s \Delta t} \right). \end{aligned} \quad (4.24)$$

*Proof.* Let  $\varphi \in C^1([0, T] \times [0, 1] \times I)$ . We observe, for any  $i, j \in I$ ,

$$\begin{aligned} & \int_0^T \int_0^1 \varphi_i(t, s) (\check{\alpha}_{i,j}^n(t, s) \check{m}_i^n(t, s) - \check{\alpha}_{j,i}^n(t, s) \check{m}_j^n(t, s)) dt ds \\ & = \sum_{k=0}^{N_T^n-1} \sum_{p=0}^{N_s^n-1} \int_{t_k}^{t_{k+1}} \int_{y_p}^{y_{p+1}} \varphi_i(t, s) \left( \alpha_{i,j}^n(t_k, y_p) \frac{N_i^{k,p}}{n \Delta s} - \alpha_{j,i}^n(t_k, y_p) \frac{N_j^{k,p}}{n \Delta s} \right) dt ds \\ & = \sum_{p=0}^{N_s^n-1} \sum_{k=0}^{N_T^n-1} \left( \Delta t \alpha_{i,j}^n(t_k, y_p) \frac{N_i^{k,p}}{n \Delta s} - \Delta t \alpha_{j,i}^n(t_k, y_p) \frac{N_j^{k,p}}{n \Delta s} \right) \frac{1}{\Delta t} \int_{y_p}^{y_{p+1}} \int_{t_k}^{t_{k+1}} \varphi_i(t, s) dt ds. \end{aligned} \quad (4.25)$$

Combining Lemma 4.3 and the previous equality, we get:

$$\begin{aligned} & \int_0^T \int_0^1 (\partial_t \varphi_i(t, s) + b_i(s) \partial_s \varphi_i(t, s)) m_i^n(t, ds) dt - \int_0^1 \varphi_i(T, s) m_i^n(T, ds) - \varphi_i(0, s) \bar{m}_i^n(ds) \\ & \quad - \int_0^T \int_0^1 \varphi_i(t, s) (\check{\alpha}_{i,j}^n(t, s) \check{m}_i^n(t, s) - \check{\alpha}_{j,i}^n(t, s) \check{m}_j^n(t, s)) dt ds \\ & = \frac{1}{n} \sum_{k=0}^{N_T^n-1} \sum_{p=0}^{N_s^n-1} \sum_{j \in I, j \neq i} \left( \sum_{\ell \in T_{i,j}^{k,p}} \varphi_i(t_k, s_{t_k}^\ell) - \sum_{\ell \in T_{j,i}^{k,p}} \varphi_i(t_k, s_{t_k}^\ell) \right) \\ & \quad - \sum_{p=0}^{N_s^n-1} \sum_{k=0}^{N_T^n-1} \sum_{j \in I, j \neq i} \left( \Delta t \alpha_{i,j}^n(t_k, y_p) \frac{N_i^{k,p}}{n \Delta s} - \Delta t \alpha_{j,i}^n(t_k, y_p) \frac{N_j^{k,p}}{n \Delta s} \right) \frac{1}{\Delta t} \int_{y_p}^{y_{p+1}} \int_{t_k}^{t_{k+1}} \varphi_i(t, s) dt ds. \end{aligned} \quad (4.26)$$

We recall that there is no transfer at time  $t_0 = 0$  in the transfer procedure described in Section 4.2.1. Thus, to find an upper bound of (4.26), two cases are considered below:  $k = 0$  and  $k \in \{1, \dots, N_T^n - 1\}$ .

- If  $k = 0$ , we have, for any  $i, j \in I$  and  $p \in \{0, \dots, N_s^n - 1\}$ , that  $T_{i,j}^{k,p} = \emptyset$ . Thus,  $\sum_{\ell \in T_{i,j}^{k,p}} \frac{1}{n} \varphi_i(t_k, s_{t_k}^\ell) = 0$  and

$$\begin{aligned}
& \sum_{p=0}^{N_s^n-1} \sum_{j \in I, j \neq i} \left| \sum_{\ell \in T_{i,j}^{k,p}} \frac{1}{n} \varphi_i(t_k, s_{t_k}^\ell) - \Delta t \alpha_{i,j}^n(t_k, y_p) \frac{N_i^{k,p}}{n} \frac{1}{\Delta s \Delta t} \int_{y_p}^{y_{p+1}} \int_{t_k}^{t_{k+1}} \varphi_i(t, s) dt ds \right| \\
&= \sum_{p=0}^{N_s^n-1} \sum_{j \in I, j \neq i} \left| \Delta t \alpha_{i,j}^n(t_k, y_p) \frac{N_i^{k,p}}{n} \frac{1}{\Delta s \Delta t} \int_{y_p}^{y_{p+1}} \int_{t_k}^{t_{k+1}} \varphi_i(t, s) dt ds \right| \\
&\leq \bar{C} \|\varphi\|_\infty \Delta t,
\end{aligned} \tag{4.27}$$

where the constant  $\bar{C} > 0$  is defined in (4.13).

- For  $k \in \{1, \dots, N_T^n - 1\}$ , recalling the definition  $a^n$  in Section 4.2.1, we have, for any  $i, j, k, p$ ,

$$|a_{i,j}^n(k, p) - \Delta t \alpha_{i,j}^n(t_k, y_p) N_i^{k,p}| \leq 1,$$

and thus, one obtains, for any  $k \in \{0, \dots, N_T^n - 1\}$  and  $p \in \{0, \dots, N_s^n - 1\}$ ,

$$\left| \left( a_{i,j}^n(k, p) - \Delta t \alpha_{i,j}^n(t_k, y_p) N_i^{k,p} \right) \frac{1}{n \Delta s \Delta t} \int_{y_p}^{y_{p+1}} \int_{t_k}^{t_{k+1}} \varphi_i(t, s) dt ds \right| \leq \frac{\|\varphi\|_\infty}{n}.$$

Since, for any  $i, j, p$ ,  $\text{card}(T_{i,j}^{k,p}) = a_{i,j}^n(k, p)$ , one has from the previous inequality, for any  $p \in \{0, \dots, N_s^n - 1\}$ ,

$$\begin{aligned}
& \left| \sum_{\ell \in T_{i,j}^{k,p}} \frac{1}{n} \varphi_i(t_k, s_{t_k}^\ell) - \Delta t \alpha_{i,j}^n(t_k, y_p) \frac{N_i^{k,p}}{n} \frac{1}{\Delta s \Delta t} \int_{y_p}^{y_{p+1}} \int_{t_k}^{t_{k+1}} \varphi_i(t, s) dt ds \right| \\
&\leq \left| \sum_{\ell \in T_{i,j}^{k,p}} \frac{1}{n \Delta s \Delta t} \int_{y_p}^{y_{p+1}} \int_{t_k}^{t_{k+1}} \varphi_i(t_k, s_{t_k}^\ell) dt ds - \frac{a_{i,j}^n(k, p)}{n \Delta s \Delta t} \int_{y_p}^{y_{p+1}} \int_{t_k}^{t_{k+1}} \varphi_i(t, s) dt ds \right| + \frac{\|\varphi\|_\infty}{n} \\
&\leq \left| \sum_{\ell \in T_{i,j}^{k,p}} \left( \frac{1}{n \Delta s \Delta t} \int_{y_p}^{y_{p+1}} \int_{t_k}^{t_{k+1}} (\varphi_i(t_k, s_{t_k}^\ell) - \varphi_i(t, s)) dt ds \right) \right| + \frac{\|\varphi\|_\infty}{n}.
\end{aligned} \tag{4.28}$$

By the Lipschitz continuity of  $\varphi$ , the definition of  $a_{i,j}^n(k, p)$  and inequality (4.13), one gets:

$$\begin{aligned}
& \left| \sum_{\ell \in T_{i,j}^{k,p}} \left( \frac{1}{n \Delta s \Delta t} \int_{y_p}^{y_{p+1}} \int_{t_k}^{t_{k+1}} (\varphi_i(t_k, s_{t_k}^\ell) - \varphi_i(t, s)) dt ds \right) \right| \leq \frac{a_{i,j}^n(k, p) \gamma_\varphi (\Delta t + \Delta s)}{n} \\
&\leq \frac{(\bar{C} N_i^{k,p} \Delta t + 1) \gamma_\varphi (\Delta t + \Delta s)}{n}.
\end{aligned}$$

Inequality (4.28) becomes:

$$\begin{aligned}
& \left| \sum_{\ell \in T_{i,j}^{k,p}} \frac{1}{n} \varphi_i(t_k, s_{t_k}^\ell) - \Delta t \alpha_{i,j}^n(t_k, y_p) \frac{N_i^{k,p}}{n} \frac{1}{\Delta s \Delta t} \int_{y_p}^{y_{p+1}} \int_{t_k}^{t_{k+1}} \varphi_i(t, s) dt ds \right| \\
&\leq \frac{(\bar{C} N_i^{k,p} \Delta t + 1) \gamma_\varphi (\Delta t + \Delta s) + \|\varphi\|_\infty}{n}.
\end{aligned} \tag{4.29}$$

By a similar computation, one can show that:

$$\begin{aligned}
& \left| \sum_{\ell \in T_{j,i}^{k,p}} \frac{1}{n} \varphi_i(t_k, s_{t_k}^\ell) - \Delta t \alpha_{j,i}^n(t_k, y_p) \frac{N_j^{k,p}}{n} \frac{1}{\Delta s \Delta t} \int_{y_p}^{y_{p+1}} \int_{t_k}^{t_{k+1}} \varphi_i(t, s) dt ds \right| \\
&\leq \frac{(\bar{C} N_j^{k,p} \Delta t + 1) \gamma_\varphi (\Delta t + \Delta s) + \|\varphi\|_\infty}{n}.
\end{aligned} \tag{4.30}$$

Finally, by inequality (4.27) and summing (4.29) and (4.30) over  $k, p$  and  $j$ , equality (4.26) becomes:

$$\begin{aligned}
& \left| \int_0^T \int_0^1 (\partial_t \varphi_i(t, s) + b_i(s) \partial_s \varphi_i(t, s)) m_i^n(t, ds) dt - \int_0^1 \varphi_i(T, s) m_i^n(T, ds) - \varphi_i(0, s) \bar{m}_i^n(ds) \right. \\
& \quad \left. - \sum_{j \in I, j \neq i} \int_0^T \int_0^1 \varphi_i(t, s) (\check{\alpha}_{i,j}^n(t, s) \check{m}_i^n(t, s) - \check{\alpha}_{j,i}^n(t, s) \check{m}_j^n(t, s)) ds dt \right| \\
& \leq \bar{C} \|\varphi\|_\infty \Delta t + \sum_{j \in I, j \neq i} \sum_{k=1}^{N_T^n - 1} \sum_{p=1}^{N_s^n - 1} \frac{(\bar{C}(N_i^{k,p} + N_j^{k,p}) \Delta t + 2) \gamma_\varphi (\Delta t + \Delta s) + 2 \|\varphi\|_\infty}{n} \\
& \leq C(\gamma_\varphi + \|\varphi\|_\infty) (\Delta s + \Delta t + \frac{1}{n \Delta s \Delta t}),
\end{aligned} \tag{4.31}$$

where the constant  $C$  depends on  $\bar{C}, T$  and  $|I|$ .  $\square$

**Lemma 4.6.** *There exists  $C > 0$  such that, for any  $i \in I$ ,  $n \geq N$  and any function  $\varphi \in C^1([0, T] \times [0, 1] \times I)$ , with Lipschitz constant denoted by  $\gamma_\varphi > 0$ , we have:*

$$\begin{aligned}
& \left| \int_0^T \int_0^1 (\partial_t \varphi_i(t, s) + b_i(s) \partial_s \varphi_i(t, s)) m_i^n(t, ds) dt - \sum_{j \in I, j \neq i} \int_0^T \int_0^1 \varphi_i(t, s) (\alpha_{i,j}^n(t, s) m_i^n(t, s) - \alpha_{j,i}^n(t, s) m_j^n(t, s)) dt \right. \\
& \quad \left. - \int_0^1 \varphi_i(T, s) m_i^n(T, ds) - \varphi_i(0, s) m_i^n(0, ds) \right| \\
& \leq C(\|\varphi\|_\infty + \gamma_\varphi) (\Delta t + \Delta s + \frac{1}{n \Delta s \Delta t}).
\end{aligned} \tag{4.32}$$

*Proof.* This results is a direct consequence of Lemmas 4.4 and 4.5.  $\square$

**Remark 4.3.** *Lemma 4.6 also holds when  $T$  is replaced by any  $t \in (0, T]$ .*

**Remark 4.4.** *The term  $\frac{T}{n \Delta s \Delta t}$  on the r.h.s. of the inequality in Lemma 4.6, implies to choose carefully the time and space steps, depending on the number of agents  $n$ . To this end, inequality (2.14) is crucial.*

We can now prove Theorem 4.3.

*Proof of Theorem 4.3.* Let  $\psi \in C^1([0, 1] \times I)$  and  $\varphi \in C^1([0, T] \times [0, 1] \times I)$  be the classical solution of the PDE:

$$\begin{aligned}
& \partial_\tau \varphi_i(\tau, s) + b_i(s) \partial_s \varphi_i(\tau, s) = 0 \quad (\tau, s, i) \in [0, t] \times [0, 1] \times I \\
& \varphi_i(t, s) = \psi_i(s) \quad (s, i) \in \times [0, 1] \times I.
\end{aligned} \tag{4.33}$$

One has  $\|\varphi\|_\infty = \|\psi\|_\infty$ , and denoting by  $\gamma_\psi$  the Lipschitz constant of  $\psi$ , for any  $t \in [0, T]$   $\varphi_i(t, \cdot)$  is Lipschitz continuous with Lipschitz constant  $\gamma_\psi e^{T \|b'\|_\infty}$ . Since  $(m^{*,n}, E^{*,n})$  is a weak solution of the continuity equation (2.9) with initial distribution  $\bar{m}^n$ , and  $\varphi$  a classical solution of (4.33), using that  $\alpha_{i,j}^n = \frac{dE_{i,j}^{*,n}}{dm_i^{*,n}}$ , we have:

$$\int_0^1 \psi_i(s) m_i^{*,n}(t, ds) = \int_0^1 \varphi_i(0, s) m_i^n(0, s) ds - \int_0^t \int_0^1 \sum_{j \in I, j \neq i} \varphi_i(\tau, s) (\alpha_{i,j}^n(\tau, s) m_i^{*,n}(\tau, ds) - \alpha_{j,i}^n(\tau, s) m_j^{*,n}(\tau, ds)) d\tau. \tag{4.34}$$

From Lemma 4.6 and Remark 4.3, we have, for any  $t \in (0, T]$ :

$$\begin{aligned}
\int_0^1 \psi_i(s) m_i^n(t, ds) & \leq \int_0^1 \varphi_i(0, s) m_i^n(0, ds) - \sum_{j \in I, j \neq i} \int_0^t \int_0^1 \varphi_i(t, s) (\alpha_{i,j}^n(t, s) m_i^n(t, s) - \alpha_{j,i}^n(t, s) m_j^n(t, s)) dt \\
& \quad + C(\|\psi\|_\infty + \gamma_\psi e^{T \|b'\|_\infty}) (\Delta t + \Delta s + \frac{1}{n \Delta s \Delta t}).
\end{aligned} \tag{4.35}$$

From the previous equality and inequality, one deduces:

$$\begin{aligned}
\sum_{i \in I} \int_0^1 \psi_i(s) (m_i^{*,n}(t, ds) - m_i^n(t, ds)) &\leq - \sum_{i \in I} \int_0^t \int_0^1 \sum_{j \in I, j \neq i} \varphi_i(\tau, s) \alpha_{i,j}^n(\tau, s) (m_i^{*,n}(\tau, ds) - m_i^n(\tau, ds)) d\tau \\
&+ \sum_{i \in I} \int_0^t \int_0^1 \sum_{j \in I, j \neq i} \varphi_i(\tau, s) \alpha_{j,i}^n(\tau, s) (m_j^{*,n}(\tau, ds) - m_j^n(\tau, ds)) d\tau \\
&+ C(\|\psi\|_\infty + \gamma_\psi)(\Delta t + \Delta s + \frac{1}{n\Delta s\Delta t}).
\end{aligned} \tag{4.36}$$

By inequality (4.13),  $\{\alpha^n(t, \cdot)\}_{n > N, t \in [0, T]}$  is uniformly Lipschitz continuous with constant  $\bar{C}$ . Thus, for any  $t \in [0, T]$ ,  $(s, i, j) \mapsto \varphi_i(t, s) \alpha_{i,j}^n(t, s)$  is Lipschitz on  $[0, 1] \times I \times I$  with Lipschitz constant  $\bar{C}(\|\psi\|_\infty + \gamma_\psi e^{T\|b'\|_\infty})$ . We deduce that, for any  $\tau \in [0, T]$ :

$$\sum_{i \in I} \int_0^1 \sum_{j \in I, j \neq i} \varphi_i(\tau, s) \alpha_{i,j}^n(\tau, s) (m_i^{*,n}(\tau, ds) - m_i^n(\tau, ds)) d\tau \leq \bar{C}|I|(\|\psi\|_\infty + \gamma_\psi e^{T\|b'\|_\infty}) \mathcal{W}(m^{*,n}(\tau), m^n(\tau)).$$

Using the previous inequality, equality (4.36) becomes:

$$\begin{aligned}
\sum_{i \in I} \int_0^1 \psi_i(s) (m_i^{*,n}(t, ds) - m_i^n(t, ds)) &\leq 2\bar{C}|I|(\|\psi\|_\infty + \gamma_\psi e^{T\|b'\|_\infty}) \int_0^t \mathcal{W}(m^{*,n}(\tau), m^n(\tau)) d\tau \\
&+ C(\|\psi\|_\infty + \gamma_\psi e^{T\|b'\|_\infty})(\Delta t + \Delta s + \frac{1}{n\Delta s\Delta t}).
\end{aligned}$$

Consider  $\eta \in \text{Lip}([0, 1] \times I)$  with a Lipschitz constant equal to 1 and satisfying  $\eta_i(0) = 0$  for a certain  $i \in I$  (to bound  $\|\eta\|_\infty$ ). Let  $\{\psi^m\}_m$  be a sequence in  $C^1([0, 1] \times I)$  that is uniformly bounded w.r.t. the Lipschitz norm and that approximates  $\eta$  w.r.t. the norm  $\|\cdot\|_\infty$ . Since the previous inequality holds for any function  $\psi$  in  $C^1([0, 1] \times I)$ , one deduces that:

$$\sum_{i \in I} \int_0^1 \eta_i(s) (m_i^{*,n}(t, ds) - m_i^n(t, ds)) \leq C \left( \int_0^t \mathcal{W}(m^{*,n}(\tau), m^n(\tau)) d\tau + \Delta t + \Delta s + \frac{1}{n\Delta s\Delta t} \right),$$

where  $C > 0$  depends on  $\bar{C}$  and  $|I|$ . Since  $\eta$  is arbitrary, one has:

$$\mathcal{W}(m^{*,n}(t), m^n(t)) \leq C \left( \int_0^t \mathcal{W}(m^{*,n}(\tau), m^n(\tau)) d\tau + \Delta t + \Delta s + \frac{1}{n\Delta s\Delta t} \right).$$

Applying the Grownwall Lemma and usig inequality (2.14), there exists  $C > 0$  such that one gets, for any  $t \in (0, T]$ ,

$$\mathcal{W}(m^{*,n}(t), m^n(t)) \leq \frac{C}{n^{\frac{1}{3}}}.$$

□

### 4.2.3 Proof of Theorem 4.2

We need the following preliminary results.

**Lemma 4.7.** *There exists  $C > 0$  such that, for any  $n \in \mathbb{N}$ , the function defined on  $[0, T]$ , by*

$$t \mapsto \sum_{i, j \in I, j \neq i} \int_0^1 L(\alpha_{i,j}^n(t, s)) m_i^{*,n}(t, ds) \tag{4.37}$$

has a total variation on  $[0, T]$  lower than  $C$ .

*Proof.* For any  $i, j \in I$  and  $t_1, t_2 \in [0, T]$  with  $t_2 > t_1$ , we have:

$$\begin{aligned}
&\left| \int_0^1 L(\alpha_{i,j}^n(t_2, s)) m_i^{*,n}(t_2, ds) - \int_0^1 L(\alpha_{i,j}^n(t_1, s)) m_i^{*,n}(t_1, ds) \right| \\
&\leq \left| \int_0^1 L(\alpha_{i,j}^n(t_2, s)) (m_i^{*,n}(t_2, ds) - m_i^{*,n}(t_1, ds)) \right| + \left| \int_0^1 (L(\alpha_{i,j}^n(t_1, s)) - L(\alpha_{i,j}^n(t_2, s))) m_i^{*,n}(t_1, ds) \right|.
\end{aligned}$$

By (4.13) one has that  $\{\alpha_{i,j}^n\}_i$  and  $\{\partial_s \alpha_{i,j}^n\}_n$  are uniformly bounded. By Assumption 5, one gets that  $L$  is locally Lipschitz continuous and by [48, Theorem 2.1] that  $m_i^{*,n} \in \text{Lip}([0, T], \mathcal{P}([0, 1] \times I))$ , with a Lipschitz constant that only depends on  $\|b\|_\infty, T$  and  $\|\alpha^n\|_\infty$ . Thus, there exists a constant  $C > 0$  independent of  $n$  such that:

$$\sum_{i \in I} \left| \int_0^1 L(\alpha_{i,j}^n(t_2, s))(m_i^{*,n}(t_2, ds) - m_i^{*,n}(t_1, ds)) \right| \leq C|t_2 - t_1|. \quad (4.38)$$

By (4.12), inequality 4.13 and the locally Lipschitz continuity of  $L$ , one gets

$$\begin{aligned} \left| \int_0^1 (L(\alpha_{i,j}^n(t_1, s)) - L(\alpha_{i,j}^n(t_2, s))) m_i^{*,n}(t_1, ds) \right| &\leq C \int_0^1 |\alpha_{i,j}^n(t_1, s) - \alpha_{i,j}^n(t_2, s)| m_i^{*,n}(t_1, ds) \\ &\leq C \left( |t_1 - t_2| + \int_{t_1}^{t_2} (\lambda_i^n + \lambda_j^n)(d\tau) \right). \end{aligned} \quad (4.39)$$

By inequalities 4.13, (4.38) and (4.39), we deduce that the total variation of the function defined in (4.37) on  $[0, T]$  is bounded by a constant.  $\square$

**Lemma 4.8.** *There exists  $C > 0$  such that, for any  $n \geq N$ ,*

$$J^n(m^n, E^n) \leq J(m^{*,n}, E^{*,n}) + \frac{C}{n^{\frac{1}{3}}}. \quad (4.40)$$

*Proof of Lemma 4.8.* By equality (4.15), one deduces, for any  $k \in \{1, \dots, N_T^n - 1\}, i \in I$  and  $p \in \{1, \dots, N_s^n - 1\}$  satisfying  $m_i^n(t_k^-, [y_p, y_{p+1})) > 0$ ,

$$\left| \frac{E^n([t_k, t_{k+1}), [y_p, y_{p+1}))}{\Delta t m_i^n(t_k^-, [y_p, y_{p+1}))} - \alpha_{i,j}^n(t_k, y_p) \right| \leq \frac{1}{n \Delta t m_i^n(t_k^-, [y_p, y_{p+1}))}. \quad (4.41)$$

The function  $L$  being locally Lipschitz continuous, one has:

$$\begin{aligned} &\sum_{i,j} \sum_{k=1}^{N_T^n-1} \sum_{p=0}^{N_s^n-1} L\left(\frac{E_{i,j}^n([t_k, t_{k+1}), [y_p, y_{p+1}))}{\Delta t m_i^n(t_k^-, [y_p, y_{p+1}))}\right) m_i^n(t_k^-, [y_p, y_{p+1})) \Delta t \\ &\leq \sum_{i,j} \sum_{k=0}^{N_T^n-1} \sum_{p=0}^{N_s^n-1} L(\alpha_{i,j}^n(t_k, x_\ell)) m_i^n(t_k^-, [y_p, y_{p+1})) \Delta t + \frac{C}{n \Delta s \Delta t}, \end{aligned} \quad (4.42)$$

Now we compare  $\sum_{i,j} \sum_{k=0}^{N_T^n-1} \sum_{p=0}^{N_s^n-1} L(\alpha_{i,j}^n(t_k, y_p)) m_i^n(t_k^-, [y_p, y_{p+1})) \Delta t$  and  $\sum_{i,j} \int_0^T \int_0^1 L(\alpha_{i,j}^n(t, s)) m_i^{*,n}(t, ds) dt$ . Recall that, for any  $i, j \in I$ ,  $s \mapsto L(\alpha_{i,j}^n(t, s))$  is Lipschitz continuous on  $[0, 1]$  uniformly in time. We have:

$$\begin{aligned} \sum_{i,j} \sum_{k=0}^{N_T^n-1} \sum_{p=0}^{N_s^n-1} L(\alpha_{i,j}^n(t_k, y_p)) m_i^n(t_k^-, [y_p, y_{p+1})) \Delta t &\leq \sum_{i,j} \sum_{k=0}^{N_T^n-1} \int_0^1 L(\alpha_{i,j}^n(t_k, s)) m_i^n(t_k^-, ds) \Delta t + C \Delta s \\ &\leq \sum_{i,j} \sum_{k=0}^{N_T^n-1} \int_0^1 L(\alpha_{i,j}^n(t_k, s)) m_i^{*,n}(t_k^-, ds) \Delta t + \frac{C}{n^{\frac{1}{3}}}, \end{aligned} \quad (4.43)$$

where the last inequality is obtained by Theorem 4.3 and the fact that  $\Delta s = \mathcal{O}(n^{-\frac{1}{3}})$ . From Lemma 4.7, there exists  $C > 0$  such that  $t \mapsto \int_0^1 L(\alpha_{i,j}^n(t, s)) m_i^{*,n}(t, ds)$  has a total variation on  $[0, T]$  lower than  $C$ . Applying classical results on approximation of Riemann sum of bounded total variation functions, we have, for any  $i, j \in I$ :

$$\sum_{k=0}^{N_T^n-1} \int_0^1 L(\alpha_{i,j}^n(t_k, s)) m_i^{*,n}(t_k, ds) \Delta t \leq \int_0^T \int_0^1 L(\alpha_{i,j}^n(t, s)) m_i^{*,n}(t, ds) dt + \frac{C}{n^{\frac{1}{3}}}, \quad (4.44)$$



where we used that  $\Delta t = \mathcal{O}(\frac{1}{n^{\frac{1}{3}}})$ . By inequalities (4.42), (4.43) and (4.44), and by the definition of  $\alpha$ ,

$$\begin{aligned} \sum_{i,j} \sum_{k=1}^{N_T^n-1} \sum_{p=0}^{N_s^n-1} L\left(\frac{E_{i,j}^n([t_k, t_{k+1}), [y_p, y_{p+1})]}{\Delta t m_i^n(t_k^-, [y_p, y_{p+1}))}\right) m_i^n(t_k^-, [y_p, y_{p+1})) \Delta t &\leq \int_0^T \int_0^1 L(\alpha_{i,j}^n(t, s)) m_i^{*,n}(t, ds) dt + \frac{C}{n^{\frac{1}{3}}} \\ &= \int_0^T \int_0^1 L\left(\frac{dE_{i,j}^{*,n}}{dm_i^{*,n}}(t, s)\right) m_i^{*,n}(t, ds) dt + \frac{C}{n^{\frac{1}{3}}}. \end{aligned}$$

From the previous inequality and Theorem 4.3, using that  $g \in C^1([0, 1] \times I)$ ,  $c \in C^1([0, T] \times [0, 1] \times I)$  and the definition of  $J^n$  and  $J$ , one has:

$$J^n(m^n, E^n) \leq J(m^{*,n}, E^{*,n}) + \frac{C}{n^{\frac{1}{3}}}.$$

□

We now turn to the proof of Theorem 4.2.

*Proof of Theorem 4.2.* By [48, Proposition 7.1], the value of Problem (2.13) is Lipschitz continuous, with Lipschitz constant  $C_L$ , w.r.t. the initial distribution  $\bar{m}$  and the congestion constraint  $D$ . Then, since  $(m^{*,n}, E^{*,n})$  is a minimizer of  $J$  over the set  $\mathcal{S}(\bar{m}^n, D - C^*/n^{\frac{1}{3}})$ , one has:

$$J(m^{*,n}, E^{*,n}) \leq \inf_{(m,E) \in \mathcal{S}(\bar{m}^n, D)} J(m, E) + \frac{C_L C^*}{n^{\frac{1}{3}}}.$$

By the previous inequality and Lemma 4.8:

$$J^n(m^n, E^n) \leq \inf_{(m,E) \in \mathcal{S}(\bar{m}^n, D)} J(m, E) + \frac{C + C_L C^*}{n^{\frac{1}{3}}}. \quad (4.45)$$

By Corollary 4.1, one has for any  $i \in I$ ,  $t \in [0, T]$  and  $n \geq N$ , that:

$$0 \leq D_i(t) - m_i^n(t, [0, 1]),$$

yielding that  $(m^n, E^n) \in \mathcal{S}^n(\bar{m}^n, D)$ . It follows from Corollary 3.1 and inequality (4.45) that there exist  $N, C > 0$  such that, for any sequence  $\{\bar{m}^n\}_n$  in  $\mathcal{P}^n([0, 1] \times I)$  satisfying Assumptions 2 and 3, one has, for any  $n > N$ ,

$$\inf_{(\mathbf{i}, \mathbf{s}) \in \mathcal{T}^n(\bar{m}^n, D)} \mathcal{J}^n(\mathbf{i}, \mathbf{s}) - \frac{C}{n^{\frac{1}{3}}} \leq \inf_{(m,E) \in \mathcal{S}(\bar{m}^n, D)} J(m, E). \quad (4.46)$$

One can consider a constant  $C > 0$  large enough such that previous inequality holds for any  $n \in \mathbb{N}^*$ . □

### 4.3 Proof of Theorem 2.2

In this section we provide a proof of Theorem 2.2, based on the results obtained above in Section 4.

*Proof of Theorem 2.2.* The convergence of a subsequence of  $\{(m^n, E^n)\}$  to  $(m^*, E^*)$  is given by Lemma 4.1. One obtains that  $(m^*, E^*)$  is optimal for Problem (2.13) by Theorem 2.1 and the proof of Theorem 4.1. □

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