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## Transformations for Energy Efficient Accelerated Chain Matrix Multiplication (TEE-ACM 2)

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### ► To cite this version:

Maxim Moraru, Mina Warnet, Julien Loiseau, Vinay Ramakrishnaiah, Nirmal Prajapati, et al.. Transformations for Energy Efficient Accelerated Chain Matrix Multiplication (TEE-ACM 2). Supercomputing, Nov 2022, Dallas, United States. hal-03872897

**HAL Id: hal-03872897**

**<https://hal.science/hal-03872897>**

Submitted on 25 Nov 2022

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## Introduction

**Matrix Chain Multiplication** plays a key role in the training of deep learning models. They also appear in physics, computer graphics, image processing, etc. Matrix Multiplications often cause a bottleneck in terms of performance and energy because of the heavy costs in computations and memory operations. While the runtime performance has been studied for years, significantly less effort has been expended into optimizing energy efficiency.

Most processors weren't built with energy in mind [3], only performance. For a supercomputer, the cost of power is the most significant expense, and even with the most affordable energy, the cost of a MW ends up at \$1M. Moreover, the Exascale Computing Project [4] defines a 'capable' exascale system as one that operates in a power envelope of 20-30 MW. Thus, reducing the energy cost of these types of computations is a major challenge.

### Matrix Chain Multiplication

**Problem:** Given a sequence of matrices  $\{A_1, A_2, \dots, A_n\}$  with sizes  $\{P_0, P_1, \dots, P_n\}$ , compute  $\prod_{k=1}^n A_k$

$$\text{Sizes } 10 \times 30, 30 \times 5, 5 \times 60 \\ R = A_1 A_2 A_3$$

$$(A_1 A_2) A_3 = 10 \times 30 \times 5 + 10 \times 5 \times 60 \\ = 4,500 \text{ multiplications}$$

$$A_1 (A_2 A_3) = 30 \times 5 \times 60 + 10 \times 30 \times 60 \\ = 27,000 \text{ multiplications}$$

- Multiplication order can significantly impact the performance of the algorithm
- The Optimal Parenthesization (OP\_Count) algorithm in "Cormen et al. Introduction to Algorithms." outputs an order of matrix multiplications that minimizes the total number of operations.

### Energy Efficient GPU implementation

- Energy consumption of a GPU can be broken down into 2 major parts:
  - Energy of the operations executing on the GPU
  - Energy of the GPU itself
- Memory operations dominate the executed operations

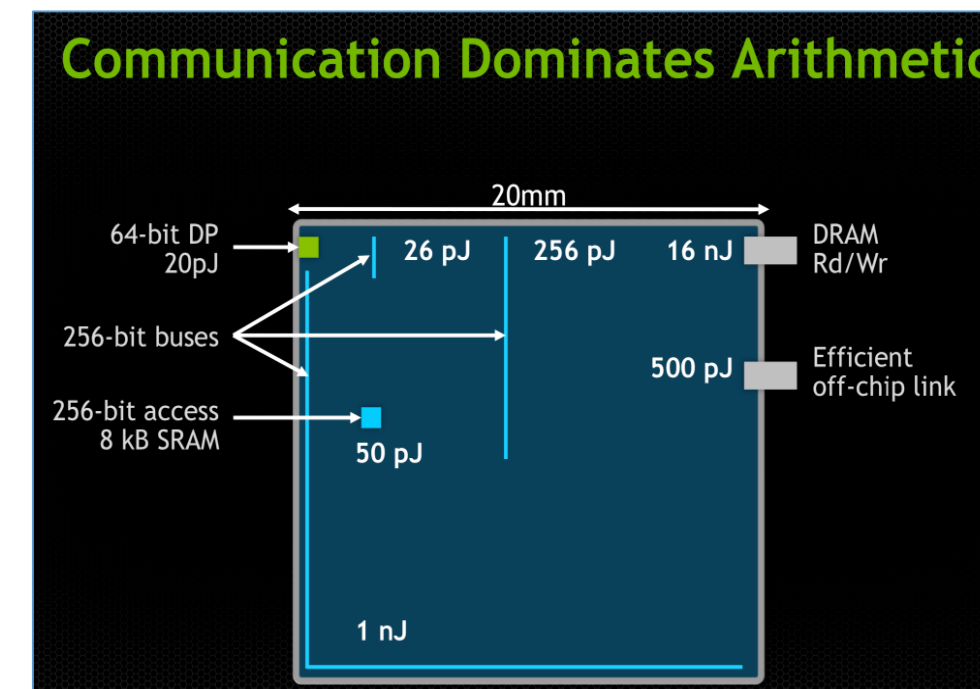


Figure 1: Data transfers vs arithmetic operations (Bill Dally, Challenges of Future Computing Systems, HiPEAC 2015)

**Our goal:** optimize the total energy consumption for Matrix Chain Multiplications

## Single Matrix Multiplication

### Single Matrix Multiplication : Blocking Strategy

Total number of global data transfers (reads + writes) : **Minimize !**

$$P_1 P_2 + P_0 P_1 P_2 \left( \frac{x+y}{xy} \right)$$

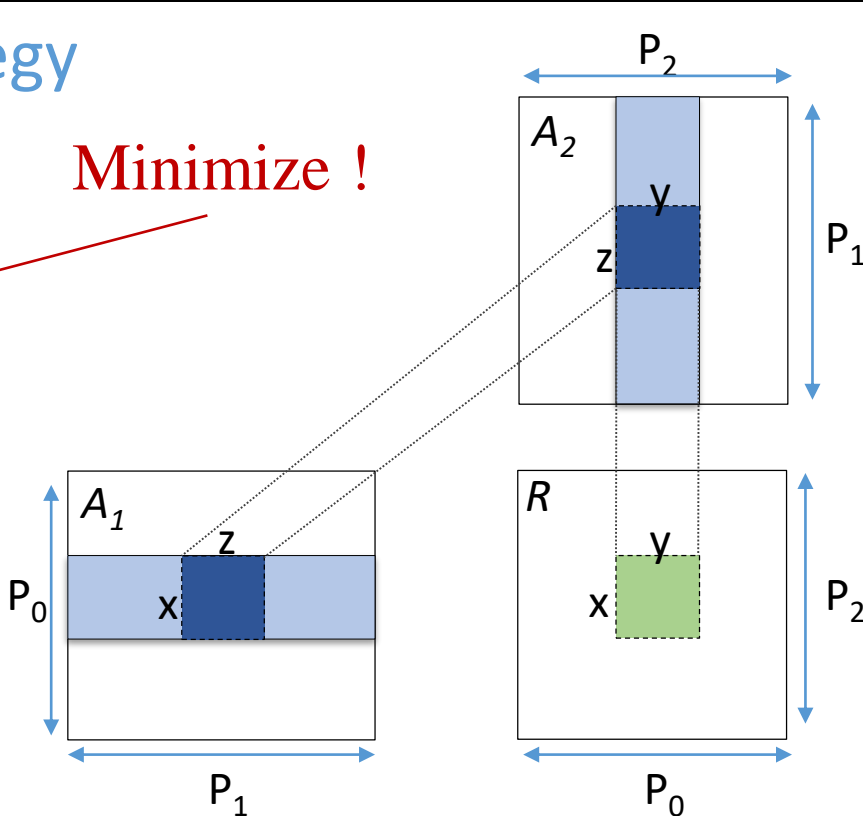


Figure 2: Blocking strategy for single matrix multiplication

$$\frac{2 \cdot P_0 \cdot P_1 \cdot P_2}{\sqrt{M}} + P_0 \cdot P_2$$

Achieved when  $x = y = \sqrt{M}$ , and  $z = [1, P1]$  (Figure 3)

### Low level TEE-ACM<sup>2</sup> optimizations

- Double level buffering : use of registers
- Loop unrolling
- Large shared memory tiles

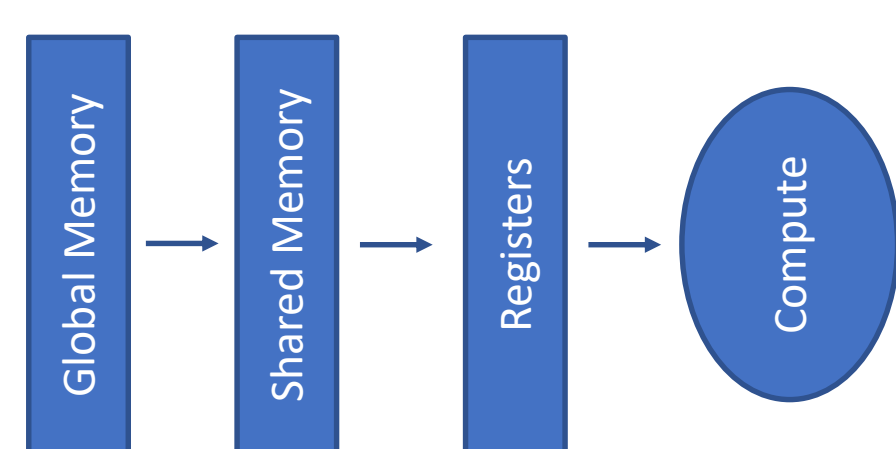


Figure 4 : Double level buffering

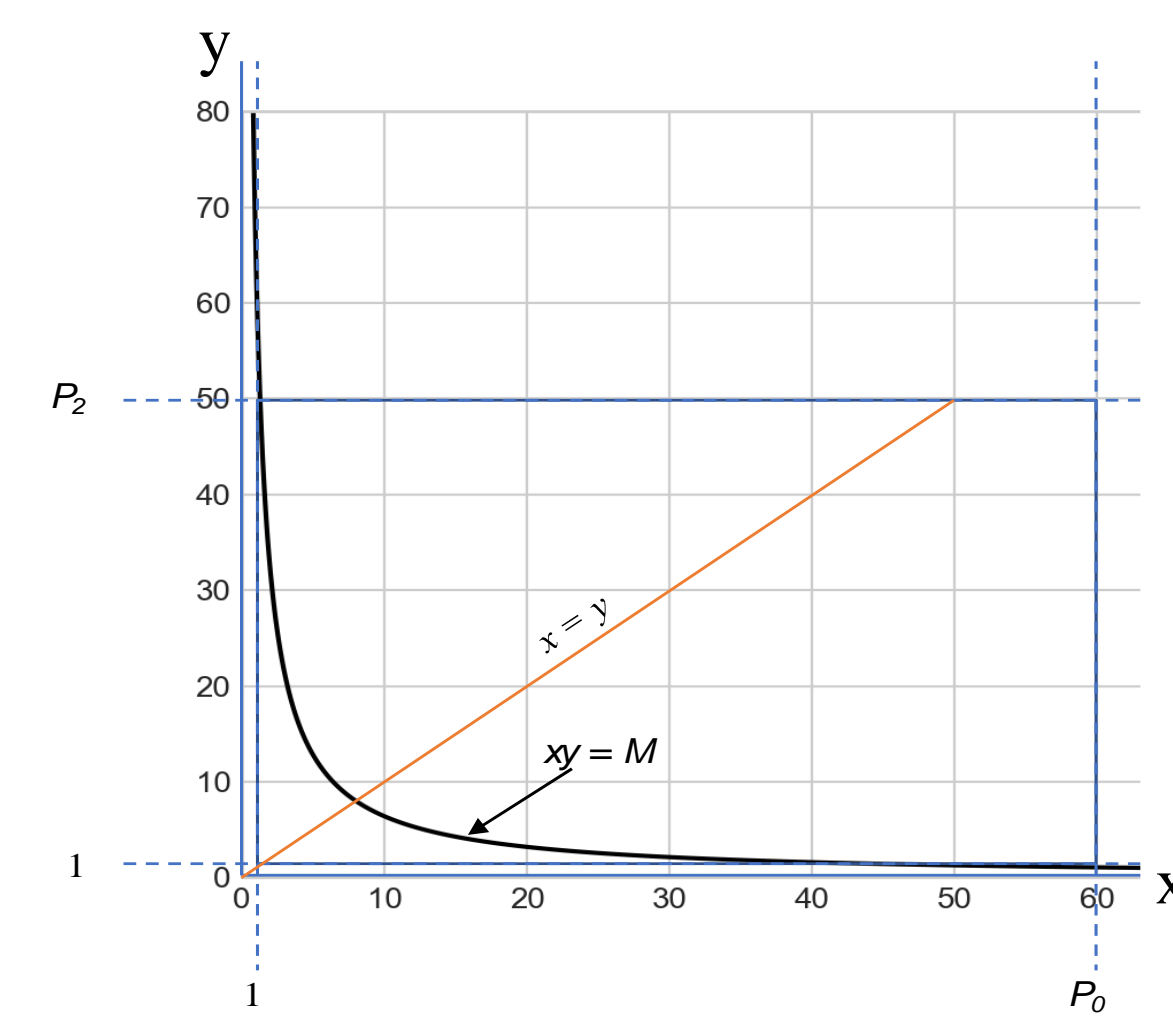


Figure 3 : Minimum number of global loads achieved when  $x=y$

## Fused Matrix Multiplication [1]

### Extending the approach to three matrices

To compute  $(A_1 A_2) A_3$ , the intermediate result produced,  $T = A_1 A_2$  is consumed directly from the on-chip memory to produce values of the final matrix,  $R = T A_3$ . This avoids writing of the intermediate matrix,  $T$  to off-chip memory.

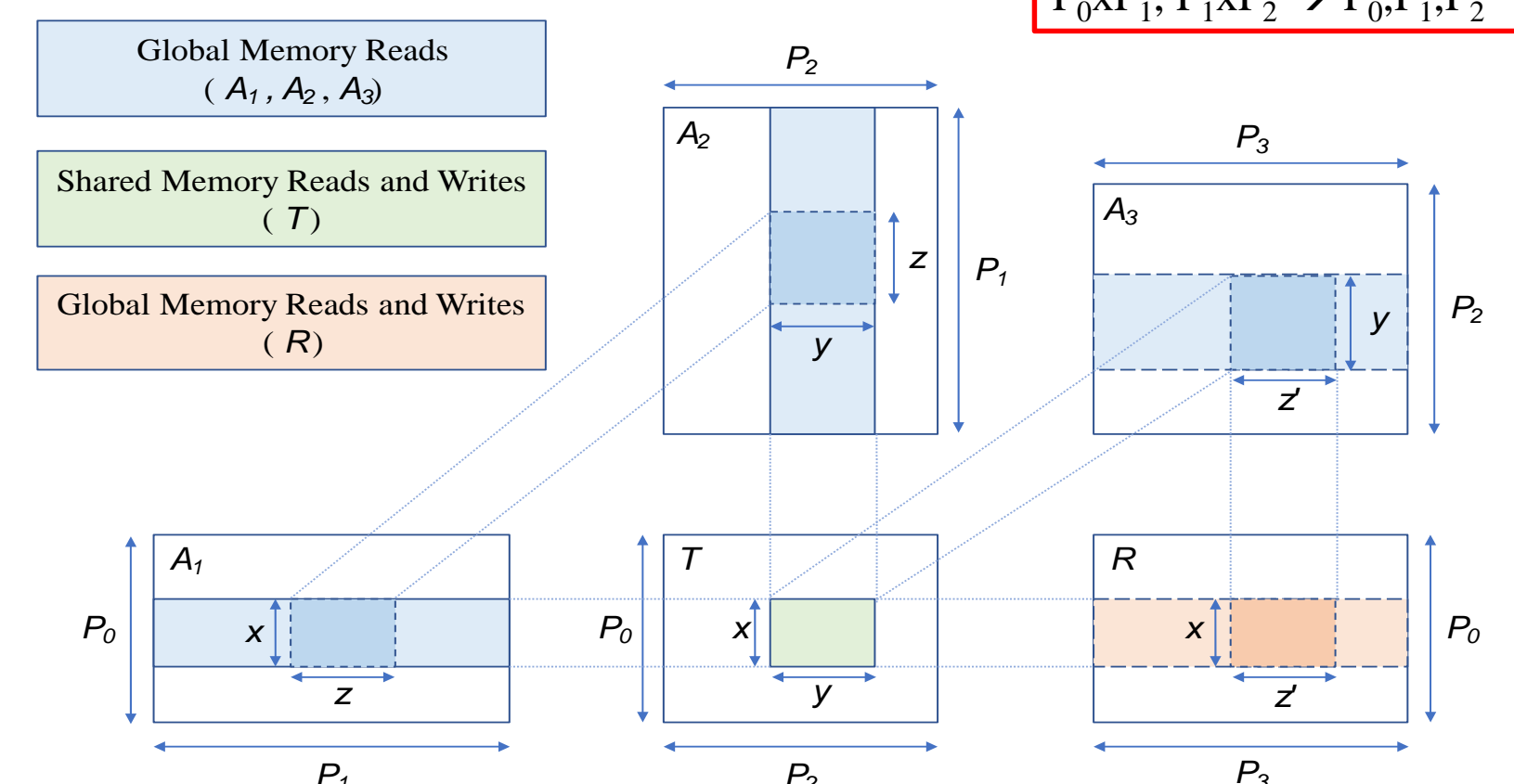
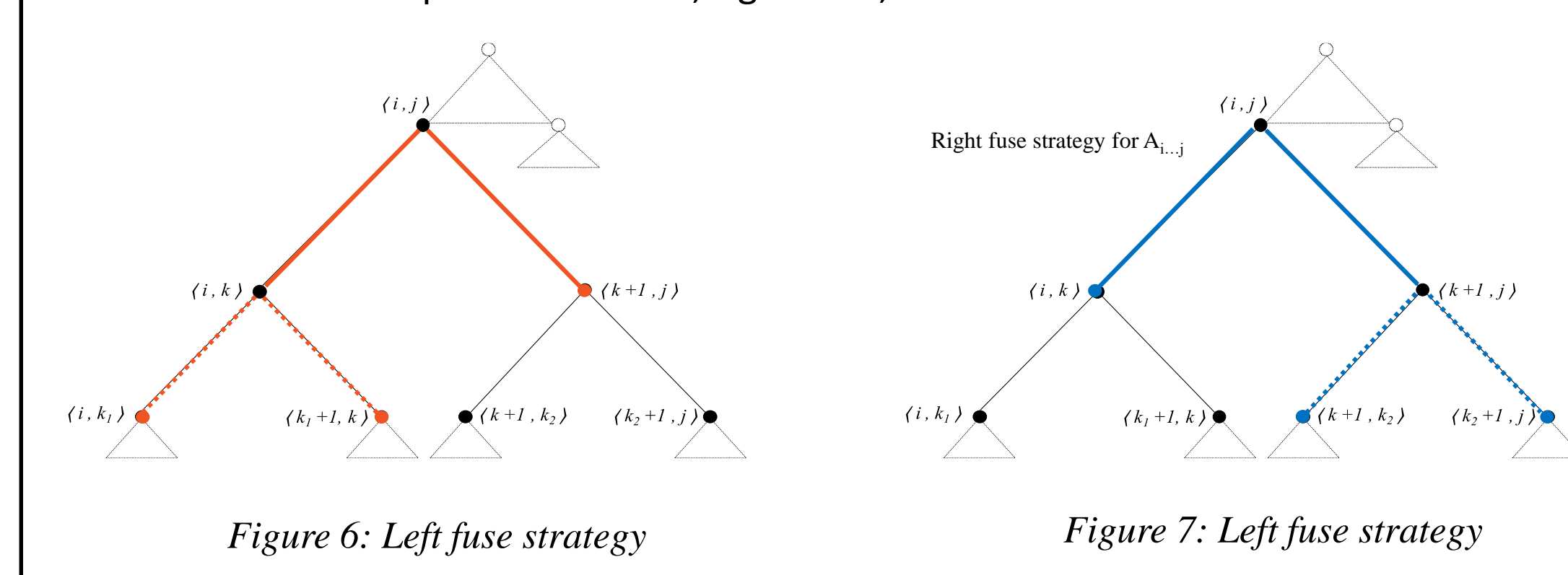


Figure 5: Fused matrix multiplication approach, where three matrices are multiplied in a single GPU kernel.

### Optimal Algorithm for Matrix Chain Multiplication

- The OP\_Count algorithm produces a tree decomposing a matrix chain, which indicates the order of matrix products to minimize operations
- OP\_DM\_Fuse is created from OP\_Count, which reduces the number of operations and then minimizes the off-chip data transfers by using fusion
- Minimize over the options: left-fuse, right-fuse, and no-fusion

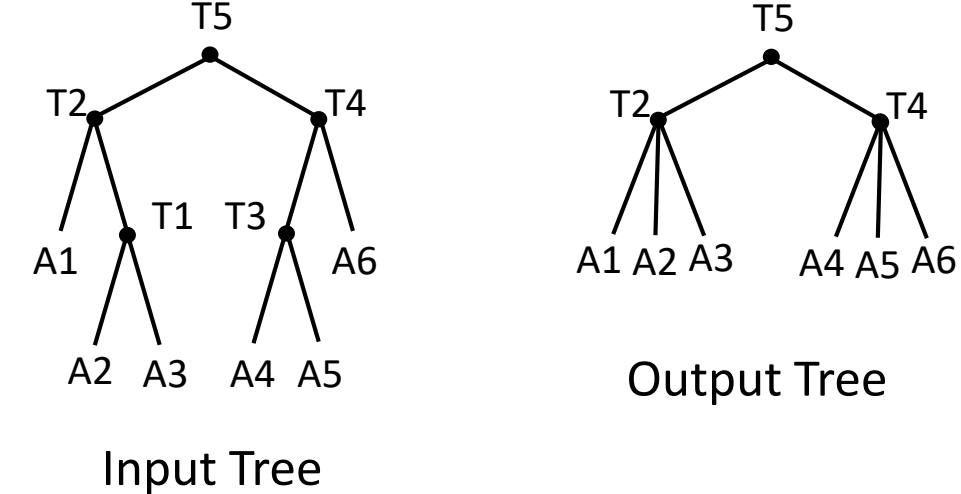


### Example for fusion decision algorithm

Input: 5 matrices with sizes 936, 1008, 552, 368, 1016, 616, 544 and  $M = 65,536$

T-matrix	No Fuse (data transfers)	Fuse left (data transfers)	Fuse right (data transfers)	Final Data Transfers	Fusion decision	Tile sizes (x, y)
T1 : (2,3)	1599696	-	-	1599696	No fuse (A2,A3)	(256,256)
T2 : (1,3)	4683168	-	3072693	3072693	Right fuse (A1 (A2,A3))	(304,208)
T3 : (4,5)	1799336	-	-	1799336	No fuse (A4,A5)	(256,256)
T4 : (4,6)	3116960	2942313	-	2942313	Left fuse ((A4,A5), A6)	(216,296)
T5 : (1,6)	8243798	9364761	9136171	8243798	No fuse (T2,T4)	(256,256)

- Visit each node of the OP\_Count tree
- Consider options: no fuse, left fuse, right fuse
- Calculate the minimum number of data transfers for each node
- Use the optimal over all possible options



- The output tree consists of the minimum number of computations and data transfers for multiplying the given matrix chain

## Energy Measurement Accuracy

### Tools used for power measurements

- Software
- Nvidia Management Library (NVML)
- Hardware
- Power Capture Analysis Tool (PCAT)

### Hardware vs software power measurements

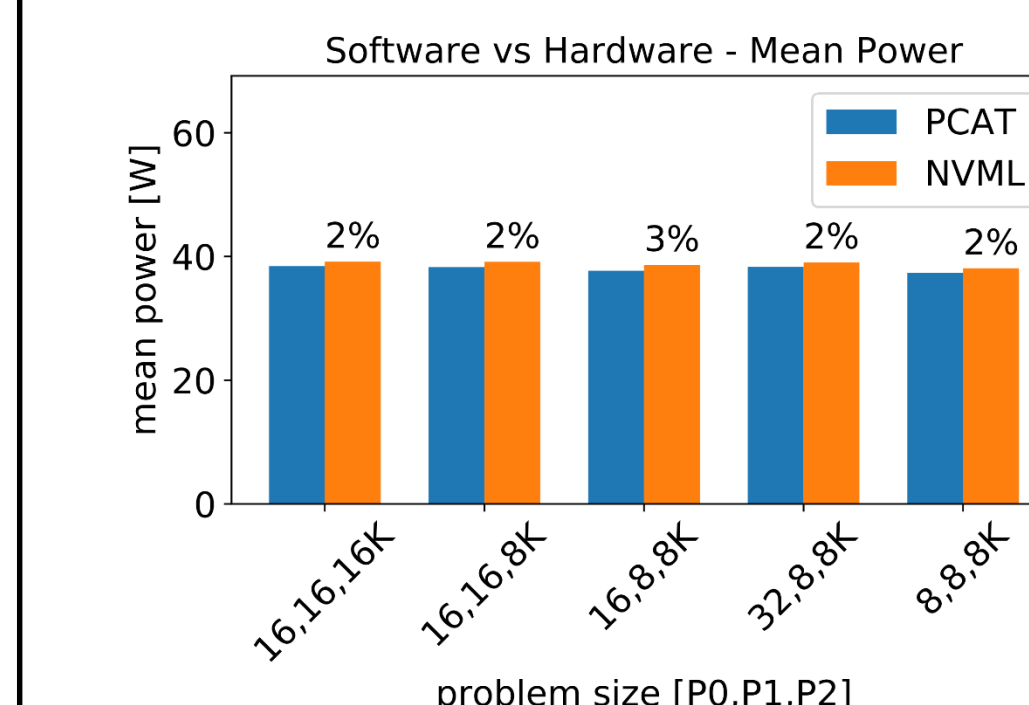


Figure 9 : NVML power precision on an entire run

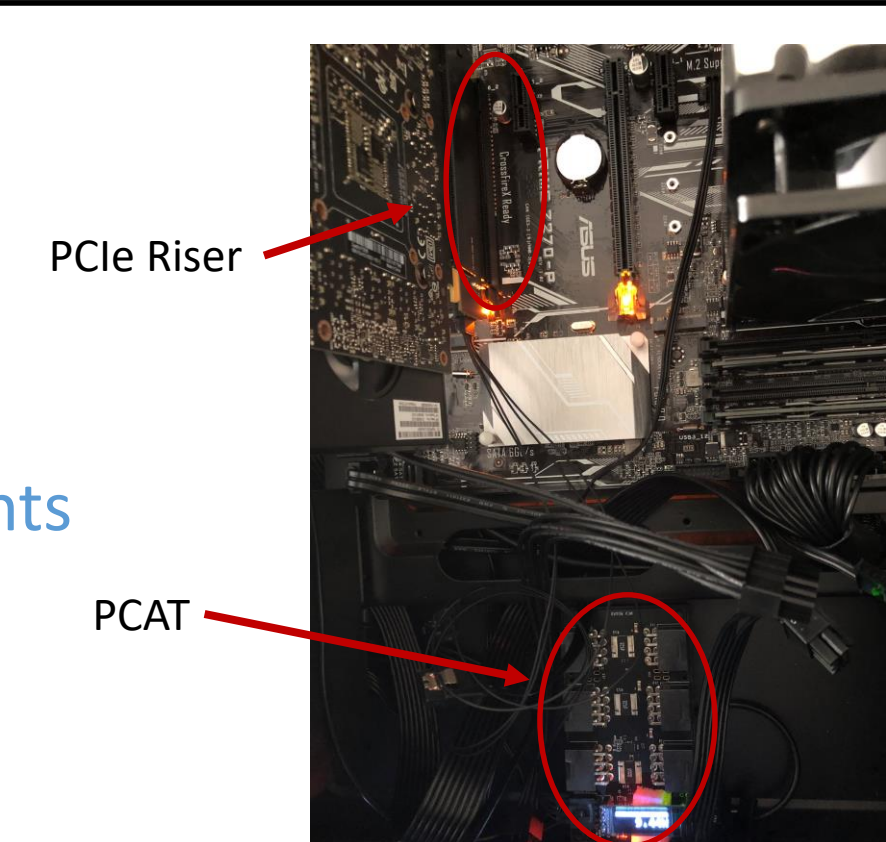


Figure 8 : Installation of PCAT device on GPU for hardware power measurement

- We observed less than 3% difference in power between PCAT and NVML measurements on average

## Single Matrix Multiplication Results

### Energy efficiency

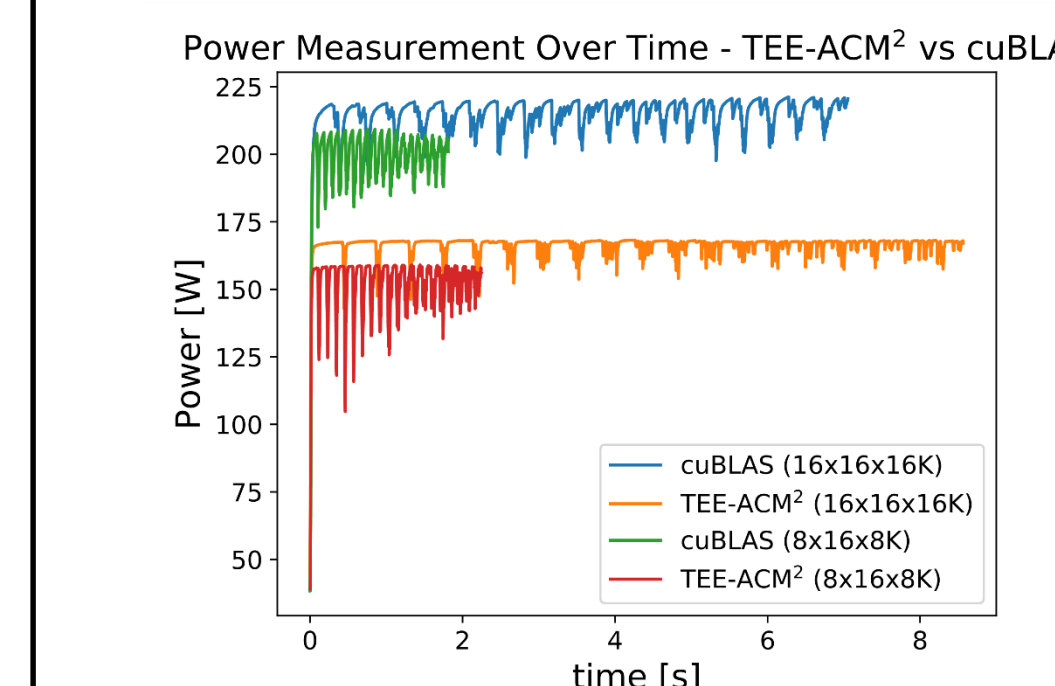


Figure 10 : Power savings of TEE-ACM<sup>2</sup> over cuBLAS (lower is better)

- The number of global loads are reduced by 66% compared to cuBLAS. This results in 30% power saving and 8% energy saving on average, and up to 21% savings
- The average execution time overhead of TEE-ACM<sup>2</sup> is 20%

### GPU resources usage

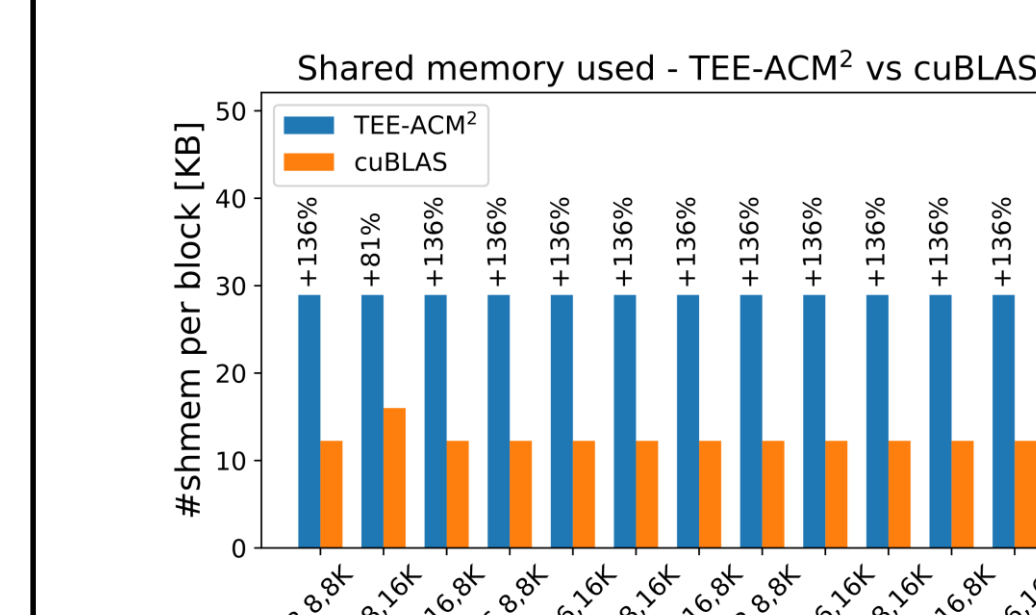


Figure 12 : The amount of shared memory used by TEE-ACM<sup>2</sup> compared to cuBLAS

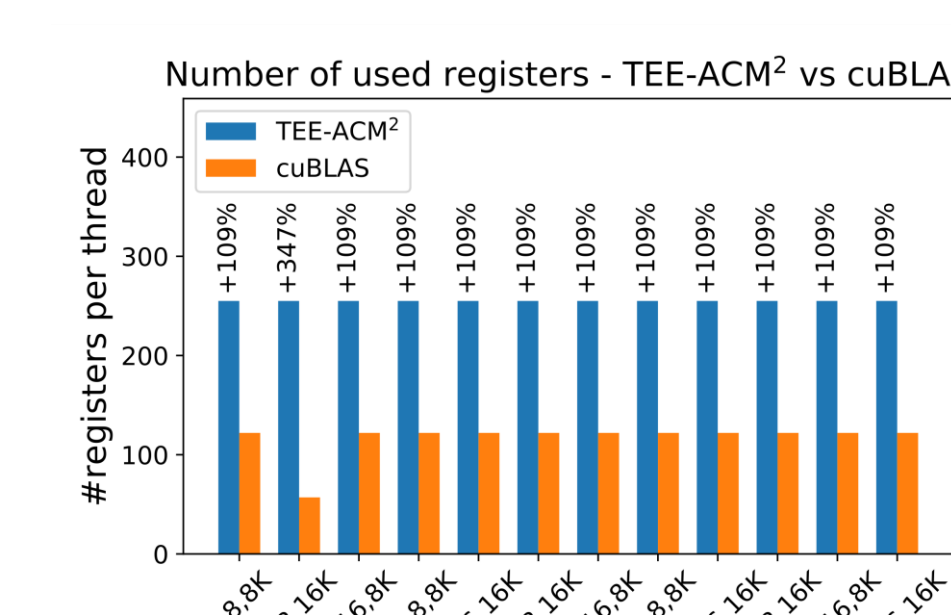


Figure 13 : The number of registers used by TEE-ACM<sup>2</sup> compared to cuBLAS

- TEE-ACM<sup>2</sup> uses more than two times on-chip memory than cuBLAS

### The impact of varying the tile size

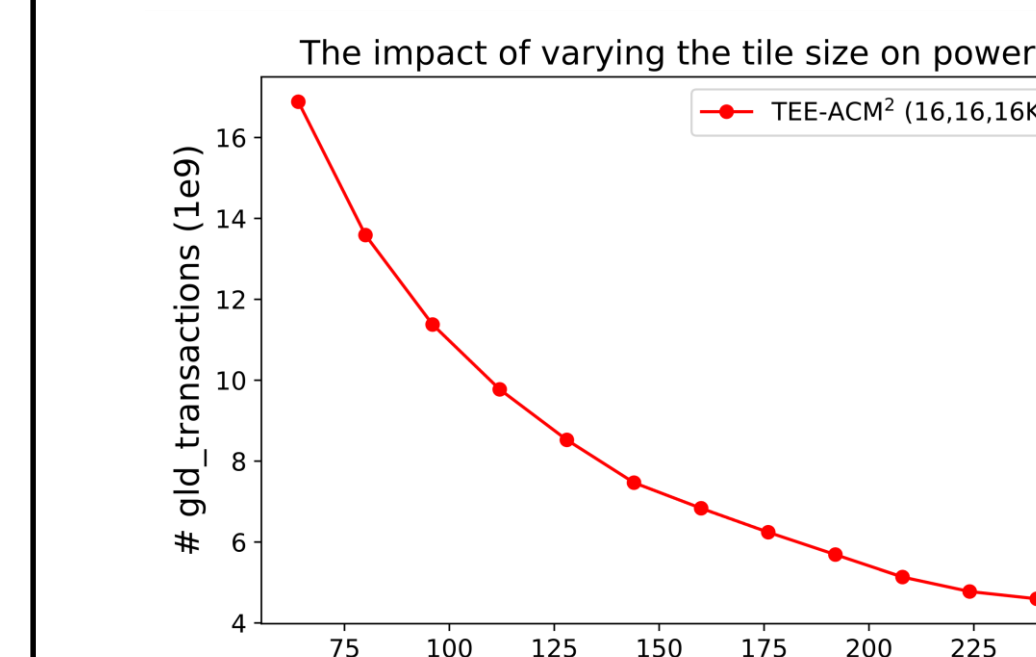


Figure 14 : The number of global loads decreases when the tile size increases

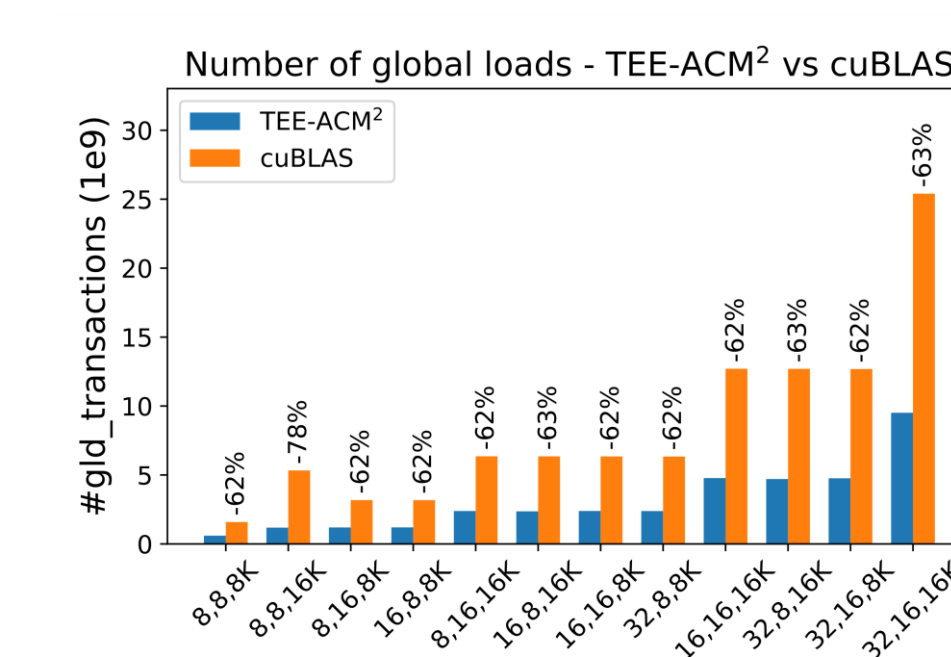


Figure 15 : The number of global loads performed by TEE-ACM<sup>2</sup> compared to cuBLAS

- By using larger tile sizes, the number of global loads decrease significantly
- cuBLAS performs 3 times more global loads on average than TEE-ACM<sup>2</sup>

\*Present results were obtained on a Darwin node equipped with v100 GPUs and Cascade Lake CPUs (averaged over 10 samples of 10 runs each)

## Matrix Chain Multiplication Results

### OP\_Count Tree effect on MCM execution time

Best case : the matrix sizes are increasing → in order computation is most efficient  
 Worst case : the matrix sizes are decreasing → in order computation is least efficient  
 Random : the matrix sizes are generated at random between 8k and 24 k

Problem sizes for best and worst: 8,10,12,14,16,18,20k  
 Problem sizes for random: 10,20,15,9,9,22,21k  
 Problem sizes for best and worst: 8,9,10,11,12,13,14,15,16,17,18,19,20k  
 Problem sizes for random: 20,16,17,10,16,19,9,24,16,12,8,10k

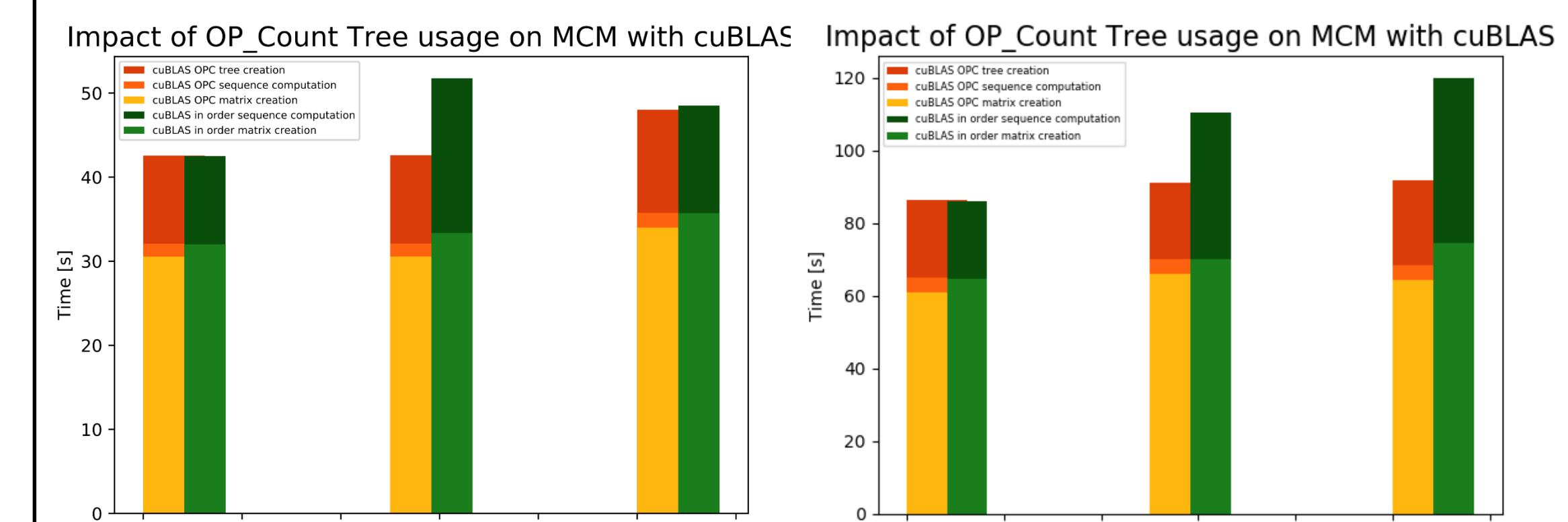


Figure 18 : Execution time of creation and computation for a sequence of 6 matrices  
 Figure 19 : Execution time of creation and computation for a sequence of 12 matrices

- When computing with the best case, cuBLAS without the tree is 2% faster because of the overhead of building and traversing the tree
- In the worst case, the creation of the matrices is longer without the tree because the parenthesizing isn't optimal, the temporary matrices are bigger, thus the longer execution time

### Impact of tree usage on Energy for best vs worst case

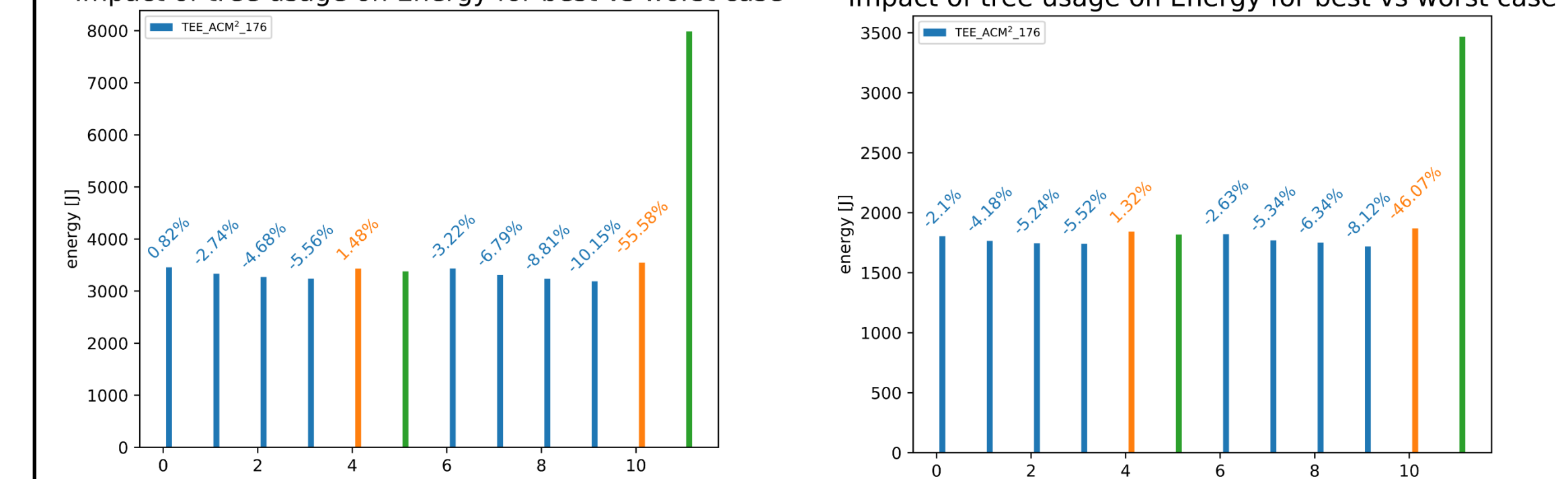


Figure 20 : Energy consumption of computation for a sequence of 6 matrices  
 Figure 21 : Energy consumption of computation for a sequence of 12 matrices

- The blue percentages indicate the energy consumption ratio between TEE-ACM<sup>2</sup> and cuBLAS using OP\_Count. By using our optimized kernel, we end up with 5 to 10% energy savings with the optimal tile sizes of 224
- The orange percentages indicate the energy consumption ratio between cuBLAS with and without the tree. In the best case, we consume 1.5% more energy with the tree, but in the worst case, using the tree allows us to save up to 50% energy on average

\*Present results were obtained on a Darwin's node equipped with v100 GPUs and Cascade Lake CPUs. The plots shows the results from 3 kernels usage per matrix multiplication

## Conclusions and Future Work

- Less power consumption may be preferred over shorter execution times for applications such as edge computing. This work focuses on such use cases
- For our fused kernel implementation, the energy consumption was primarily dictated by the execution time (static power)
- Performing fewer global loads and stores significantly decreases the GPU power consumption at the cost of increased execution time
- By using the OP\_Count tree we optimize the computation order in a sequence of matrices.
  - Using cuBLAS decreases execution time by a factor of two
  - Using TEE-ACM<sup>2</sup>, we save up to 10% energy
- The hardware counters and APIs supplied by Nvidia provide accurate results with precision comparable to the measurements made using the hardware power capture analysis tool (PCAT)

- Future work: we plan to optimize the fused kernels by removing atomic operations, thus reducing computation time. Once the fused kernels are implemented, we will generate the fusion tree and compare the time and energy between TEE-ACM<sup>2</sup> with and without fusion

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