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An analytic and symbolic analysis of a coupled thermo-neutronic problem $\overset{\text{tr}}{\sim}$

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1. Introduction

In this note, we recall briefly the construction of an analytic solution of the low Mach number thermohydraulic model obtained by Dellacherie *et al.* detailed in [5]. The thermohydraulic-neutronics problem, stated in a 1d setting reads

$$\frac{d}{dz}(D(h(z))\frac{d\phi}{dz}) + \Sigma_a(h(z))\phi(z) = \frac{\nu\Sigma_f(h(z))}{k_{eff}}\phi(z), h'(z) = K\nu\Sigma_f(h)\phi(z), z \in [0, L],$$
(1)

where the unknowns are ϕ , the neutron density, *h*, the enthalpy (a measure of the temperature) and k_{eff} is called the multiplication factor of neutrons. The physical data are the functions Σ_a and $\nu \Sigma_f$ (respectively the absorption and fission cross section of the fissile material) and the constants *D* (diffusion coefficient) and *K* (heat transfer constant). This system is supplemented with the boundary conditions

$$\phi(0) = \phi(z) = 0, \phi \ge 0, h(0) = h_e, h(L) = h_s$$
(2)

Recall that in [5], we constructed an analytical solution of (1)(2) for any set of continuous positive functions $D, \Sigma_a, \nu \Sigma_f$, as a generalisation of Dellacherie and Lafitte [3]. Let X and Y be uniquely defined by: $-\frac{d}{d}(D(h)\nu \Sigma_f(h)\frac{dX}{dX}) - \frac{\Sigma_a(h)}{dX} - \frac{d}{d}(D(h)\nu \Sigma_f(h)\frac{dY}{dY}) - 1 X(h) - X(h) - X(h) - M(h) = 0$

$$-\frac{a}{dh}(D(h)\nu\Sigma_f(h)\frac{a\chi}{dh}) = \frac{2a(h)}{\nu\Sigma_f(h)}, -\frac{a}{dh}(D(h)\nu\Sigma_f(h)\frac{ag}{dh}) = 1, X(h_e) = X(h_s) = \mathcal{Y}(h_e) = \mathcal{Y}(h_s) = 0.$$

Denote by $\Psi(h, k_{eff}) = 2(\frac{\mathcal{Y}(h)}{k_{eff}} - \mathcal{X}(h))$. Let $z \to h(z, k_{eff})$ is the unique solution of: $h'(z, k_{eff}) = \sqrt{\Psi(h(z, k_{eff}), k_{eff})}, h(0) = h_e.$

Lemma 1.1. Equation $h(L, k_{eff}) = h_s$ has a unique solution $k_{eff}^* \in I := (0, (max_{[h_e,h_s]}\frac{y}{X})^{-1})$ which provides the unique solution of the system (1), (2).

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This result is the consequence of $k_{eff} \rightarrow h(L, k_{eff})$ decreasing from I to $(+\infty, 0)$ (see [3], [5]).

In this extended abstract, we shall, without losing the generality, simplify the problem (assuming that D and Σ_a are constant functions), we shall choose $h_e = 0, h_s = 1$, denote by $\lambda = \frac{1}{k_{eff}}$ and consider the totally adimensionnalized problem (L = 1 (unit of length), $\Sigma_a = 1, D = 1, K = 1$ (physical constants), $h_e = 0, h_s = 1$ (normalizing the temperature)):

$$-(D\phi')' + \Sigma_a \phi = \lambda \Sigma(h)\phi, h' = K\phi, z \in [0, 1]$$

supplemented by $\phi(0) = \phi(1) = 0$, $h(0) = h_e$, $h(1) = h_s$, where Σ is a given continuous function.

We assume throughout this paper

$$(H) \qquad \Sigma(h) \ge \Sigma_* > 0, 0 \le h \le 1.$$

and we define ψ_{λ} the unique solution of $\psi_{\lambda}''(h) = 2 - 2\lambda\Sigma(h)$ with $\psi_{\lambda}(0) = \psi_{\lambda}(1) = 0$. We intend to present a numerical method which solves the coupled problem without using the numerical methods traditionally used for solving each equation but rather concentrating on solving the equation h(1) = 1. This numerical method, as well as analytic and symbolic methods, are implemented when one knows only three values of Σ , and for simplicity again one assumes that one knows $\Sigma(0) = \sigma_0, \Sigma(\frac{1}{2}) = \sigma_{\frac{1}{2}}, \Sigma(1) = \sigma_1$. The analytic and symbolic methods are consequences of the finding of **exact** solutions using the incomplete Jacobi functions (which are its solutions) when Ψ is a polynomial of degree 3 or 4.

This numerical method is compared with an adapted numerical scheme, described in the first paragraph of Section **??**. This numerical scheme uses the Crank-Nicholson discretization of the ODE $h' = \phi$ in order to recover, from the numerical scheme, the property that the vector $(\phi_j)_j$ is a generalized eigenvector of the discretized version of $-\phi'' + \phi = \lambda \Sigma(h)\phi$, hence keeping what researchers working in the neutronics computations call the spectral problem for the neutronics.

We want to construct different relevant approximations of $\Sigma(h)$ (namely constant, affine, polynomial of order 2) in order to see what is the influence on the value of k_{eff} in order to be able to study the sensitivity of the value of k_{eff} for these different approximations, and furthermore to understand the number of significative figures in k_{eff} . Usually, the benchmarks in realistic cases are using sensitivity of 10^{-5} around $k_{eff} = 1$, which is a magnitude or two smaller than the results we obtain here, see Section 4.

2. Analytical approach

Following *e.g.* Abramowitz and Stegun [1], we define the incomplete elliptic integral of the first kind $K(m, \varphi)$ by the relation $K(m, \varphi) = \int_0^{\varphi} \frac{d\theta}{\sqrt{1-m\sin^2\theta}}$, $0 \le \varphi \le \frac{\pi}{2}$, m < 1. The complete elliptic integral of the first kind K(m) is defined by $K(m) \equiv K(m, \frac{\pi}{2})$.

Lemma 2.1. (i) Given two positive reals a and b such that
$$0 < a < b$$
, we have

$$\int_{-a}^{a} \frac{dT}{\sqrt{(a^2 - T^2)(b^2 - T^2)}} = \frac{2}{b} K(m), \ m = \frac{a^2}{b^2} \ and \ \int_{a}^{b} \frac{dT}{\sqrt{(T^2 - a^2)(b^2 - T^2)}} = \frac{1}{b} K(m), \ m = 1 - \frac{a^2}{b^2}.$$
(ii) Given two reals a and b with $a > 0$ and $b \neq 0$, we have $\int_{-a}^{a} \frac{dT}{\sqrt{(a^2 - T^2)(b^2 + T^2)}} = \frac{2}{|b|} K(m), \ m = -\frac{a^2}{b^2}.$

Recall that we are studying the model described by the following set of equations, where ϕ needs (physically) to be positive because it is a density flux of neutrons:

$$\begin{cases} -\frac{d^2\varphi}{dz^2} + \varphi(z) = \lambda \Sigma(h(z)) \,\varphi(z), \,\frac{dh}{dz} = \varphi(z), \, 0 < z < 1, \\ h(0) = 0, \,h(1) = 1, \,\varphi(0) = 0, \,\varphi(1) = 0, \,\lambda \ge 0, \,\varphi(z) > 0 \text{ if } 0 < z < 1. \end{cases}$$
(3)

Here Σ is defined by three positive real numbers σ_0 , $\sigma_{1/2}$ and σ_1 which represent the values of Σ at, respectively, $0, \frac{1}{2}, 1$. We describe in what follows five different modellings of the function Σ from these

values which lead to analytical approaches for determining the scalar parameter $\lambda > 0$ and deduce secondly the functions $z \mapsto \varphi(z)$ and $z \mapsto h(z)$.

Introduce

Definition 1. We define μ , α and δ through $\mu = \frac{1}{2}(\sigma_0 + \sigma_1)$, $\alpha = 1 - \frac{\sigma_0}{\mu}$ and $\delta = -\frac{\sigma_0 - 2\sigma_{1/2} + \sigma_1}{\sigma_0 + \sigma_1}$. They satisfy the inequalities $\mu > 0$, $|\alpha| < 1$ and $\delta > -1$. Furthermore $\gamma \equiv 1 - \frac{1}{3}|\alpha| + \frac{2}{3}\delta > 0$.

• Zero-th case: Σ is constant ($\alpha = \delta = 0$). Then the system modelized by the previous set of equations is totally decoupled and an exact solution can be provided with elementary arguments.

Proposition 2.1. If $\sigma_0 = \sigma_{1/2} = \sigma_1 \equiv \mu > 0$, the previous problem (3) admits a unique decoupled solution: we have $\lambda \mu = 1 + \pi^2$, $\varphi(z) = \frac{\pi}{2} \sin(\pi z)$ and $h(z) = \frac{1}{2} (1 - \cos(\pi z))$.

If the function Σ is no-more constant, it has been proven in [2, 3] that the unknown of the problem can be obtained with the following process. First integrate twice the function Σ and obtain a convex negative function V such that $\frac{d^2V}{dh^2} = \Sigma(h)$, V(0) = V(1) = 0. Second define $\psi_{\lambda}(h) \equiv h(h-1) - 2\lambda V(h)$. Then the equation for the function $z \mapsto h(z)$ becomes $\frac{dh}{dz} = \sqrt{\psi_{\lambda}(h)}$ and the condition h(1) = 1 gives a scalar equation for the unknown $\lambda > 0$: $\int_0^1 \frac{dh}{\sqrt{\psi_{\lambda}(h)}} = 1$.

A first difficulty is to compute the integral $I_{\lambda} \equiv \int_{0}^{1} \frac{dh}{\sqrt{\psi_{\lambda}(h)}}$. Then we can solve easily the equation $I_{\lambda} = 1$ with a Newton-like algorithm. Once λ is determined, the explicitation of the functions $z \mapsto \varphi(z)$ and $z \mapsto h(z)$ is not difficult. Thus the analytical method we propose is found on an analytical determination of the integral I_{λ} . We focus our attention to this question in the next sub-sections. • First case: $\Sigma \in P_1$.

In this case, the function Σ is a positive affine function on the interval (0, 1). Hence $\delta = 0$ and $\sigma_0 = \mu (1 - \alpha)$, $\sigma_{1/2} = \mu$ and $\sigma_1 = \mu (1 + \alpha)$ with $\mu > 0$ and $|\alpha| < 1$ to satisfy the constraint of positivity. We introduce the notation $\xi \equiv \lambda \mu$.

Proposition 2.2. With the notations introduced previously, the functions V and ψ_{λ} admit the algebraic expressions $V(h) = \mu h (h-1) \left(\frac{1}{2} - \frac{\alpha}{6} + \frac{\alpha}{3} h\right)$ and $\psi_{\lambda}(h) = h (h-1) \left(\xi \left(1 + \frac{\alpha}{3}\right) - 1 - \frac{2\alpha\xi}{3} h\right)$. Then we have $I_{\lambda} = \frac{2}{\sqrt{\xi \left(1 + \frac{|\alpha|}{3}\right) - 1}} K(m)$ with $m = \frac{2|\alpha|\xi}{3\xi + |\alpha|\xi - 3}$.

• Second case: $\Sigma \in P_2$.

In this case, the polynomial ψ_{λ} is a polynomial of degree 4 with real coefficients and ψ_{λ} is positive on the interval (0, 1). We have also $\psi_{\lambda}(0) = \psi_{\lambda}(1) = 0$. Recall that $\psi_{\lambda}(h) = h(h-1) - 2\lambda V(h)$ with $V'' \equiv \Sigma$ the Lagrange interpolate polynomial such that $\Sigma(0) = \sigma_0$, $\Sigma(\frac{1}{2}) = \sigma_{1/2}$ and $\Sigma(1) = \sigma_1$. All these coefficients are supposed positive: $\sigma_0 > 0$, $\sigma_{1/2} > 0$, $\sigma_1 > 0$. One has $\sigma_0 = \mu(1-\alpha)$, $\sigma_{1/2} = \mu(1+\delta)$ and $\sigma_1 = \mu(1+\alpha)$. In this sub-section, we exclude the case of a linear interpolation, *id est* $\delta \neq 0$, in coherence with the hypothesis that the degree of the polynomial ψ_{λ} is exactly equal to 4.

Lemma 2.2. With the above notations and properties, introduce the notation $\xi \equiv \lambda \mu$; then $\xi > 0$. Introduce also the two other roots p and g of the polynomial ψ_{λ} . We can write $\psi_{\lambda}(h) = a_0 h (h - 1) (h - p) (h - g)$. Then $a_0 = \frac{2}{3} \xi \delta$. Denote by $\sigma \equiv p + g$ the sum and $\pi \equiv p g$ the product and the two roots p and g. We have $a_0 \sigma = \frac{2}{3} \xi (\delta + \alpha)$ and $a_0 \pi = 1 - \xi + \frac{1}{3} \alpha \xi - \frac{2}{3} \delta \xi$.

The above relations have been computed with the help of the SageMath [6] formal calculus software. Observe that with the above notations and properties, if the integral I_{λ} is a positive real number, the roots p and g cannot be equal to 0 or 1.



Figure 1: Homographic transformation T for the computation of the integral I_{λ} ; case p < 0 < 1 < g. It is defined by the constraints T(p) = b, T(0) = -b, T(1) = -a and T(g) = a. The coefficients 0 < a < 1 < b are determined in Proposition 2.4.

Proposition 2.3. *We keep active the above notations.*

(i) If the discrete positive family $(\sigma_0, \sigma_{1/2}, \sigma_1)$ is the trace of a concave function, id est if $\sigma_{1/2} - \sigma_0 > \sigma_1 - \sigma_{1/2}$, we have $\delta > 0$, $a_0 > 0$ and $\gamma \xi > 1$. The two roots of the function ψ_{λ} are real with opposite signs. To fix the ideas, p < 0 < 1 < g. If we set $\Delta \equiv \sigma^2 - 4\pi = \frac{1}{a_0^2} \xi [(5\delta^2 + \alpha^2 + 6\delta)\xi - 6\delta]$, we have $p = \frac{1}{2}(\sigma - \sqrt{\Delta})$ and $g = \frac{1}{2}(\sigma + \sqrt{\Delta})$ with σ and π introduced in Lemma (2.2). (ii) Conversely, if the function ψ_{λ} are real zeros with opposite signs, then $\sigma_{1/2} - \sigma_0 > \sigma_1 - \sigma_{1/2}$.

Proposition 2.4. We suppose as in Proposition (2.3) that the function $\psi_{\lambda}(h)$ has two real zeros p and g that satisfy p < 0 < 1 < g. Then the integral $I_{\lambda} \equiv \int_{0}^{1} \frac{dh}{\sqrt{\psi_{\lambda}(h)}}$ can be computed with the help of the following

formulas:
$$A = -\sqrt{\frac{g(g-p)}{1-p}}$$
, $B = \sqrt{\frac{(1-p)(g-p)}{g}}$, $a = \frac{A+1}{A-1}$, $b = \frac{B+1}{B-1}$, $m = 1 - \frac{a^2}{b^2}$, $I_A = \frac{1}{\sqrt{a_0}} \left(1 - \frac{a}{b}\right) \frac{1}{\sqrt{g-p}} K(m)$. Moreover, we have $0 < a < 1 < b$ and $0 < m < 1$.

Proof. The general ideas of the proof are given in the book [1]. A detailed proof and a complete description of the other cases p < g < 0 < 1, 0 < 1 < p < g and p and g conjugate complex numbers can be founded in [4].

If the sequence σ_0 , $\sigma_{1/2}$, σ_1 is convex, *id est* if $\sigma_{1/2} - \sigma_0 < \sigma_1 - \sigma_{1/2}$, we have $\delta < 0$, $a_0 < 0$ and the discriminant Δ introduced in Proposition 2.3 can be negative or positive. In the case $\Delta < 0$ and we have two conjugate roots for the polynomial ψ_{λ} . In the case $\Delta > 0$, we have of course the case p < 0 < 1 < g studied at Proposition 2.4; this case must be completed by the two sub-cases p < g < 0 < 1 and 0 < 1 < p < g. All these cases are detailed in [4].

• Third case: Σ is a continuous positive function, affine in each interval $(0, \frac{1}{2})$ and $(\frac{1}{2}, 1)$.

The function Σ is defined by its values $\Sigma(0) = \sigma_0$, $\Sigma(\frac{1}{2}) = \sigma_{1/2}$ and $\tilde{\Sigma}(1) = \sigma_1^{-1}$. We introduce new parameters, still denoted by α and β to represent the data: $\sigma_0 = \sigma_{1/2}(1 - \alpha)$ and $\sigma_1 = \sigma_{1/2}(1 + \beta)$. Then the inequalities $\alpha < 1$ and $\beta > -1$ express the constraints $\sigma_0 > 0$ and $\sigma_1 > 0$. Moreover, $\sigma_{1/2}$ is positive.

Lemma 2.3. If the continuous function Σ defined on (0, 1) by its values $\Sigma(0) = \sigma_0$, $\Sigma(\frac{1}{2}) = \sigma_{1/2}$ and $\Sigma(1) = \sigma_1$ is affine in each interval $(0, \frac{1}{2})$ and $(\frac{1}{2}, 1)$, the function ψ_{λ} defined by the conditions

$$\frac{\mathrm{d}^2\psi_{\lambda}}{\mathrm{d}h^2} = 1 - 2\,\lambda\Sigma \quad and \quad \psi_{\lambda}(0) = \psi_{\lambda}(1) = 0$$

admits the following expressio

 $\psi_{\lambda}(h) = \begin{cases} \psi^{0}(h) = -\frac{2}{3} \,\alpha \,\xi \,h^{3} + (\alpha \,\xi - \xi + 1) \,h^{2} + (\frac{\beta - 5 \,\alpha}{12} \,\xi + \xi - 1) \,h & \text{if } h \leq \frac{1}{2} \\ \psi^{1}(h) = \frac{2}{3} \,\beta \,\xi \,(1 - h)^{3} + (-\beta \,\xi - \xi + 1) \,(1 - h)^{2} + (\frac{5\beta - \alpha}{12} \,\xi + \xi - 1) \,(1 - h) & \text{if } h \geq \frac{1}{2} \,, \end{cases}$ with $\xi \equiv \lambda \,\sigma_{1/2}$. We have in particular $\psi_{\lambda}(\frac{1}{2}) = \frac{\beta - \alpha}{24} \,\xi + \frac{1}{4} \,(\xi - 1)$. Moreover, if ψ_{λ} is positive on the interval $(0, 1), \ \frac{d\psi_{\lambda}}{dh}(0) = \frac{\beta - 5\alpha}{12} \,\xi + \xi - 1 > 0 \,and \ \frac{d\psi_{\lambda}}{dh}(1) = -(\frac{5\beta - \alpha}{12} \,\xi + \xi - 1) < 0.$

Remark 1. We observe that the expression of ψ^1 is obtained from the expression of ψ^0 by making the transformations $\alpha \longleftrightarrow (-\beta)$ and $h \longleftrightarrow (1-h)$.

Proof. The function Σ admits the algebraic expressions: $\Sigma(h) = (2 \alpha h - \alpha + 1) \sigma_{1/2}$ if $h \le \frac{1}{2}$ and $\Sigma(h) = (2\beta h - \beta + 1) \sigma_{1/2}$ if $h \ge \frac{1}{2}$. We integrate two times, enforce the conditions $\psi_{\lambda}(0) = \psi_{\lambda}(1) = 0$ and impose the continuity of ψ_{λ} and $\frac{d\psi_{\lambda}}{dh}$ at the specific value $h = \frac{1}{2}$. The result follows.

We have to compute the integral $I_{\lambda} \equiv \int_0^1 \frac{dh}{\sqrt{\psi_{\lambda}(h)}}$. We have the following calculus: $I_{\lambda} = \int_0^1 \frac{dh}{\sqrt{\psi^0(h)}} + \frac{dh}{\sqrt{\psi^0(h)}}$ $\int_{1/2}^{1} \frac{dh}{\sqrt{\psi^1(h)}} = \int_0^{1/2} \frac{dh}{\sqrt{\psi^0(h)}} + \int_0^{1/2} \frac{dh}{\sqrt{\psi^1(1-h)}}.$ Due to the Remark 1, the determination of the second term relative to ψ^1 is very analogous to the term associated to ψ^0 .

Proposition 2.5. Recall that $\psi^0(h) = -\frac{2}{3} \alpha \xi h^3 + (\alpha \xi - \xi + 1) h^2 + (\frac{\beta - 5\alpha}{12} \xi + \xi - 1) h$. (i) If the polynomial $\psi^0(h)$ has two complex roots, we write it under the form $\psi^0(h) \equiv a_0 h (h^2 + \mu h + \zeta^4)$ with $a_0 = \frac{2}{3} |\alpha| \xi > 0$ and we have the inequality $\mu^2 - 4\zeta^4 < 0$; we introduce $m = \frac{1}{2} - \frac{\mu}{4\zeta^2}$ that satisfies 0 < m < 1 and $\varphi_0 = 2 \arctan\left(\frac{1}{\zeta\sqrt{2}}\right)$. Then we have $I_0 = \frac{1}{\zeta\sqrt{a_0}} K(\varphi_0, m)$.

(ii) If the polynomial $\psi^0(h)$ has three real roots, we set $\psi^0(h) \equiv a_0 h (r_- - h) (r_+ - h)$ with $a_0 = \frac{2}{3} |\alpha| \xi > 0$ and $0 < r_- < r_+$; we consider $m = \frac{r_-}{r_+} \in (0, 1)$ and $\varphi_0 = \arcsin(\frac{1}{\sqrt{2r_-}})$. The integral I_0 is computed with the following expression: $I_0 = \frac{2}{\sqrt{a_0 r_+}} K(\varphi_0, m)$.

• Fourth case and fifth cases: Σ is a P2 polynomial or a continuous positive function, piecewise affine. The function $h \mapsto \frac{V(h)}{h(1-h)}$ is approximated by an affine function, as described in [3].

3. Numerical method

After adimensionalization, the problem can be formulated with the formulation (3). We introduce a nonregular meshing $0 = z_0 < z_1 < \dots < z_{N-1} < z_N = 1$ of the interval [0, 1] and we set $\Delta z_{j+1/2} \equiv z_{j+1} - z_j$ for j = 1, ..., N. We integrate the differential equation $\frac{dh}{dz} = \varphi(z)$ with the Crank-Nicolson scheme:

$$\frac{h_{j+1}-h_j}{\Delta z_{j+1/2}} = \frac{1}{2} \left(\varphi_j + \varphi_{j+1} \right)$$
 for $j = 0, \dots, N-1$.

Then after two integrations, the first equation can be written as $\varphi_j = \sqrt{\psi_{\lambda}(h_j)}$ and the Crank-Nicolson scheme takes the form $\frac{h_{j+1}-h_j}{\frac{1}{2}\left(\sqrt{\psi_{\lambda}(h_j)}+\sqrt{\psi_{\lambda}(h_{j+1})}\right)} = \Delta z_{j+1/2}(\lambda).$

We impose the values $h_j \equiv \sin^2(\frac{\pi j}{2N})$ in order to take into account the singularities and two boundary conditions of the problem at z = 0 and z = 1. The notation $\Delta z_{j+1/2}(\lambda)$ in the right hand side of the previous relation is justified by the fact that if the numbers h_i are given, the left hand side is a simple function of the



Figure 2: Function $h \mapsto \Sigma(h)$ on the left, $h \mapsto V(h)$ on the right.

scalar λ . The number λ is *a priori* not known, but we have the natural relation $\sum_{j=0}^{N-1} \Delta z_{j+1/2}(\lambda) = 1$ that takes the form

$$\sum_{j=0}^{N-1} \frac{h_{j+1} - h_j}{\frac{1}{2} \left(\sqrt{\psi_\lambda(h_j)} + \sqrt{\psi_\lambda(h_{j+1})} \right)} = 1.$$
(4)

Lemma 3.1. Recall that V is the unique solution of $V'' = \Sigma$, V(0) = V(1) = 0. We have observed previously that $\psi_{\lambda}(h) = h(h-1) - 2 \lambda V(h)$. Define $\lambda_* = \max_{[0,1]} \frac{h(h-1)}{V(h)}$. i) For $\lambda > \lambda_*, \psi_{\lambda}(h_i) > 0$

ii) Equation (4) has a unique solution
$$\lambda \in (\lambda_*, +\infty)$$
 when $\sum_{j=0}^{N-1} \frac{h_{j+1}-h_j}{\frac{1}{2}(\sqrt{\psi_{\lambda_*}(h_j)} + (\sqrt{\psi_{\lambda_*}(h_{j+1})}))} \in \mathbb{R}_+ > 1.$

For a fixed discretization with N intervals, a Newton algorithm can be implemented without difficulty. With this procedure, we recover on one hand an approximated value λ_N of the unknown λ and on the other hand the entire approximate solution of the problem $h_j \approx h(x_j)$ and $\varphi_j \approx \sqrt{\psi_\lambda(h_j)}$. Observe that at convergence of the Newton algorithm, the abscissas x_j are a function of the solution λ_N and the converged space mesh is a result of the problem. This coupled problem can be reduced to a single equation with only one real variable even after discretization!

4. Numerical results

They are presented in Figures 2 and 3. They correspond to the decrasing data $\sigma_0 = 8$, $\sigma_{1/2} = 6$ and $\sigma_1 = 3$. We obtain the following exact values for the scalar parameter: $\lambda = 1.89036$ in the decoupled case (case 0), $\lambda = 1.99533$ in the affine case (case 1), $\lambda = 1.86593$ in the parabolic case (case 2), $\lambda = 1.89454$ in the piecewise affine case (case 3), $\lambda = 1.85769$ in the parabolic case approached by an affine function (case 4) and $\lambda = 1.88614$ in the piecewise affine case projected on affine functions (case 5). For each of these six cases, our analytical-numerical approach gives converging results at second order accuracy for the parameter λ , hence showing the powerfulness and precision of the explicit calculations that one describes using the elliptic integrals.

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Figure 3: Functions $h \mapsto \psi^0(h)$ and $h \mapsto \psi^1(h)$ on the left, $z \mapsto \varphi(z)$ in the middle and $z \mapsto h(z)$ on the right.

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