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# A multiscale Time-Laplace method to extract relaxation times from non-stationary Dynamic Light Scattering signals

F. Liénard, E. Freyssingeas, and P. Borgnat ENS de Lyon, CNRS, Laboratoire de Physique, 69342 Lyon

(\*Electronic mail: francois.lienard@ens-lyon.fr, eric.freyssingeas@ens-lyon.fr, pierre.borgnat@ens-lyon.fr)

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Dynamic Light Scattering (DLS) is a well-known technique to study the relaxation times of systems at equilibrium. In many soft matter systems, we actually have to consider non-equilibrium or non-stationary situations. We discuss here the principles, the signal processing techniques we developed, based on regularized inverse Laplace transform, sliding with time, as well as the light scattering signal acquisition, that enable us to use DLS experiments in this general situation. In this article we show how to obtain such a Time-Laplace analysis. We claim that this method can be adapted to numerous DLS experiments dealing with non-equilibrium systems so as to extract the non-stationary distribution of relaxation times. To prove that, we test this Time-Laplace method on three different non-equilibrium processes or systems investigated by means of DLS technique: the cooling kinetics of a colloidal particle solution; the sol-gel transition; and the internal dynamics of a living cell nucleus.

#### I. INTRODUCTION

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Dynamic light scattering (DLS), also known as Quasi-<sup>56</sup> Elastic Light Scattering (QELS) or Photon Counting Spec-<sup>57</sup> troscopy (PCS), is a non-invasive spectroscopic analysis technique. Its fields of applications are diverse and range from chemistry, through biophysics, to physics. DLS principle is <sup>60</sup> based upon analysis of the temporal fluctuations in the light <sup>61</sup> intensity scattered by the sample under investigation,  $I_{scat}(t)$ . <sup>62</sup>

One of the main applications of DLS is likely to be the size measurement of nano- and micro-scale particles in solutions, *e.g.* colloidal particles, micelles, polymers, proteins; all objects with radii smaller than ~ 300 nm<sup>1-3</sup>. In this case, experiments are carried out with dilute solutions in stationary conditions so as to probe the Brownian motion of these objects. Nevertheless, particle sizing is not the only application of DLS. Several phenomena in statistical and soft condensed matter physics can be investigated thanks to DLS measurements: dynamics of liquid crystal phases<sup>4-8</sup>, dispersions of colloids<sup>9-11</sup>, micelles<sup>12-14</sup>, polymers<sup>15-18</sup>. DLS measurements then are performed with more concentrated solutions and provide information on the collective relaxation processes, therefore, on the sample thermodynamics.

For all these reasons, DLS has been extensively used to  $_{78}$  probe the dynamics of "soft matter systems" in thermodynamic equilibrium for more than fifty years. To characterize  $^{79}$  the dynamics of the sample, commercial DLS devices return  $^{80}$  the autocorrelation function of the scattered light intensity,  $^{81}$  namely  $g_2(\tau) = \langle I_{\rm scat}(t)I_{\rm scat}(t+\tau)\rangle$ . The decay of  $g_2(\tau)$  as  $^{82}$  a function of the delay  $\tau$  is related to the relaxation times  $\zeta_i$  (possibly several of them, hence the index i) of the sample. This technique allows to probe relaxation times of the system  $_{85}$  over a broad range, typically from microsecond to minute. In  $_{86}$  usual DLS applications, the investigated samples are in thermodynamic equilibrium, or at least stationary over the duration of the measurement.

Of course non-equilibrium or non-stationary systems scat-90 ter light as well, and therefore it is tempting to use DLS ex-91 periments to probe their dynamics. This has already been 92

done for the study of continuous phase transitions <sup>19,20</sup>, spinodal decomposition<sup>21–23</sup>, as well as the dynamics of gels<sup>24–28</sup>, glassy systems<sup>29–32</sup>, or nucleus of a living cell<sup>33–35</sup>. However, in these cases, usual analyses of  $I_{\text{scat}}(t)$  data no longer hold; particularly the autocorrelation function  $g_2(\tau)$  of the scattered intensity only makes sense if the dynamics of the investigated system is stationary over the duration of its measurement. Theoretical models linking measurements of  $g_2(\tau)$ to  $\zeta_i$  assume, indeed, that the system is stationary. Here, as this is not the case, the computed autocorrelation function should depend on the time t at which it is estimated; that is:  $g_2(\tau,t)$  instead of  $g_2(\tau)$ . The relaxation times of the sample,  $\zeta_i$ , as well as the mean scattered intensity, evolve throughout the measurement. The signal measured in non-stationary DLS is thereby complex, and the analysis of its autocorrelation function is intrinsically complicated. The non-stationarity of  $I_{\text{scat}}(t)$  may also appear as a long relaxation time (possibly longer than the typical duration  $T_0$  on which autocorrelation is estimated). And mostly, an issue is how to deal with change in  $\zeta_i$  with time during the acquisition. Consequently, to take full advantage of DLS technique to investigate the dynamics of non-equilibrium, non-ergodic or non-stationary systems, it is necessary to develop new signal processing methods able to reliably extract the time-dependent dynamics of these systems. The following properties are required:

- The analysis must be possible under non-stationary conditions. This means that the analysis has to be made time-dependent so that it evolves with t, the time at which it is carried out. Hence, formally, we have to work with a non-stationary autocorrelation function,  $g_2(\tau,t)$ .
- The duration of the data acquisition  $\Delta T$  has to be taken into account, as well as  $T_0$  the duration over which the autocorrelation function is estimated. Indeed, if  $\Delta T$  is large compared to the time evolution of the  $\zeta_i$ 's, autocorrelation function will tend to provide time-average values, which poorly reflects the evolution of the system (especially for the short  $\zeta$ ). Conversely, if it is chosen a too short  $\Delta T$ , it will no longer be possible to probe the

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long relaxation time, even if they are stationary. More-147 over, the measured  $g_2(\tau,t)$  might be very noisy which 48 will prevent good estimation even of the short  $\zeta_i$ . So, it 49 is required to adapt the estimation and choose a suitable 50  $T_0$  which may vary and be different from  $\Delta T$ .

• In out-of-equilibrium systems, there are often several characteristic relaxation times, denoted  $\zeta_i$ , for i=1,...,M, which occur at the same moment and that may be distributed over a broad time range. M is unknown, so is the time range, yet it is needed to find out all these times

All that calls for developing a new methodology for the  $_{56}$  analysis of DLS data recorded on non-equilibrium, non $_{157}$  ergodic or non-stationary systems. This is the first objective  $_{58}$  of the present article. For this purpose, we will revisite  $_{59}$  S.W. Provencher's regularized Inverse Laplace Transform  $_{60}$  method  $_{36,37}$ , and from there develop an original Inverse  $_{61}$  Laplace Transform method that can be used as a multiscale  $_{262}$  non-stationary method for DLS analysis. Thereby, the nov- $_{163}$  elty of this work is to develop a comprehensive method for  $_{664}$  estimating a non-stationary inverse (and regularized) Laplace  $_{65}$  Tranform, which can cope the three issues mentioned above  $_{466}$  Thus, the originality of the present work is to carefully study. $_{67}$  sampling, resolution, duration of the estimation window  $_{70,268}$  then to validate the method on various systems of soft matter. $_{369}$ 

Section II recalls in A the basics of DLS experiments, in B<sub>171</sub> the classical analysis of DLS signals on systems in thermo-172 dynamic equilibrium, in C the attempts done to analyse DLS<sub>173</sub> signals on non-stationary systems, finally in D we explain the 74 aim of the present work and how we adapt the current analysis 175 of DLS signals to non-stationary signals. Then, Section III de-176 scribes the inverse Laplace transform procedure, based on the 77 CONTIN method<sup>36,37</sup>, which we develop to extract valuable 78 information from non-stationary DLS signals. In the second 179 part of this section it is discussed a numerical experiment val-180 idating this method. Next, in Section IV, it is first explained 181 the proposed Time-Laplace approach that aims at following.82 the time evolution of the relaxation times for non-equilibrium to 1833 systems thanks to DLS experiments. Then it is described the 84 experimental setting for data acquisition of the scattering signate nal required to allows this approach. Finally, in Section V186 in order to validate this method it is shown its application, 87 to the investigation of the dynamics of three different non-188 equilibrium processes or systems: the cooling kinetics of asso colloidal particle solution; the sol-gel transition; and the inter<sub>300</sub> nal dynamics of a living cell nucleus.

### II. PRINCIPLES OF DYNAMIC LIGHT SCATTERING EXPERIMENTS AND THEIR ANALYSIS

Here, it is important to state that although the methods de<sup>497</sup> veloped in this article can most likely be applied to hetero<sup>498</sup> dyne light scattering, cross-correlation light scattering, scat<sup>499</sup> tering wave spectroscopy (DWS) and X-ray photon correla<sup>200</sup> tion spectroscopy (XPCS), since the scattered intensity can be<sub>01</sub>

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recorded continuously and an autocorrelation function (ACF) of the scattered intensity can be computed, in this article we only focus on the case of a single scattering process in a homodyne light scattering experiment.

#### A. DLS principles

Light scattering originates in the spatio-temporal fluctuations of the medium refractive index<sup>38</sup>. It therefore arises from the local optical properties of the sample, which are themselves linked to both the structure and the internal dynamics of the investigated sample. Fluctuations of the medium refractive index imprints information about particle motion in the scattering signal. We restrict the present study to light scattering in the Rayleigh-Gans-Debye regime (RGD). This theory is an approximate solution to light scattering by optically "soft" particles dispersed in a medium. Optical softness means that the size of particles is smaller or of the order of the light wavelength  $\lambda$ , and their refractive index  $n_1$  is close to that of the surrounding medium  $n_0$ . The approximation holds for particles of arbitrary shape that are relatively small but may be larger than Rayleigh scattering limits; the RGD approximation implies:  $a|n_0 - n_1|2\pi/\lambda \ll 1$ , a being the size of the particles. In this framework, the refractive index of the medium can be written as a function of space  $\vec{r}$  and time t, as:  $n(\vec{r},t) = \langle n \rangle + \delta n(\vec{r},t)$ , where  $\delta n(\vec{r},t)$  represents both spatial and time fluctuations in the refractive index of the sample around its mean value  $\langle n \rangle$ ; in most cases  $\langle n \rangle \approx n_0$ . The scattered electromagnetic field,  $E_{\rm scat}$ , is proportional to the spatial Fourier transform of the fluctuations of  $n(\vec{r},t)$ , i.e.  $\delta \hat{n}(\vec{q},t)$ , where  $\vec{q}$  is the scattering wave vector. Thereby, the scattered light intensity,  $I_{\text{scat}}(q,t) = |E_{\text{scat}}(q,t)|^2 = E_{\text{scat}}^*(q,t)E_{\text{scat}}(q,t)$ , is the "diffraction pattern" of the scattering volume (the sample's volume where the scattered light comes from). The size of the scattering volume is defined both by the optics and by the size of the hole placed in front of the detector.

For systems in thermodynamic equilibrium, the measured light scattering signal shows random fluctuations around a mean value:  $I_{\text{scat}}(t) = I_0 + \delta I(t)$ , with  $\langle \delta I(t) \rangle = 0$ . According to the RGD theory, these fluctuations are related to the dynamics of the processes involved in the temporal fluctuations of the refractive index n. For dispersions, these fluctuations  $\delta I(t)$  come from the particle motion and reflect the randomly changing relative position of the particles as a result of thermal agitation. Thus analysis of  $\delta I(t)$  yields information about the dynamics of the system. In the case of non-interacting particles (i.e. in practice for dilute samples) this provides information on the Brownian motion of the particles; henceforth DLS measurements give access to the diffusion coefficient of the objects:  $D_0 = k_B T / 6\pi \eta R_h$ , where  $\eta$  is the solvent viscosity and  $R_h$  the hydrodynamic radius of the objects. In the case of interacting particles, then DLS measurements yield information on the thermodynamics of the system as well as on hydrodynamic interactions<sup>39</sup>.

The principle of DLS experiment is therefore simple, as sketched on Fig. 1. It consists in passing a light beam (usually a laser beam of wavelength  $\lambda$  in its fundamental mode)

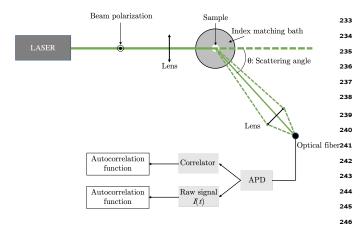


FIG. 1. Schematic representation of DLS set-up.

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through the sample, and to study the light intensity scattered by the sample in a given direction. The scattered light inten-251 sity,  $I_{\rm scat}(\vec{q},t)$  coming from the scattering volume, is detected by means of a photodetector placed at an angle  $\theta$  with re-253 spect to the incident laser beam direction. This angle selects the scattering wave vector  $\vec{q}$ , the module of which is given as a function of the mean refractive index  $\langle n \rangle$  of the dispersion-256 and the incident light wavelength  $\lambda$ :

$$q = (4\pi \langle n \rangle \sin(\theta/2)) / \lambda. \tag{1}^{25}$$

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This scattering wave vector sets the length scale l over which light scattering probes the fluctuations of the refractive index<sup>261</sup> n:  $l \approx 2\pi/q$ . By varying the scattering angle  $\theta$ , q is varied<sub>2</sub>62 thus allowing for probing the sample dynamics over spatial<sup>263</sup> scales ranging from hundreds of nanometers ( $\sim \lambda/2\langle n \rangle$ ) to 264 few micrometers.

#### B. Classical methods for analyses of stationary DLS signals 268

The starting point for analyzing temporal fluctuations of the roscattered light intensity is the estimation of its ACF  $g_2(\tau)$ . In general, the incoming data are processed in real time using a digital signal processing device known as a correlator that outputs an estimate of the ACF of the scattered intensity as a function of the delay time  $\tau$ . This ACF,  $g_2(q,\tau)$  is written:

$$g_2(q,\tau) = \langle I_{\text{scat}}(-q,t)I_{\text{scat}}(q,t+\tau)\rangle$$
 (2)<sup>276</sup>

Note that here, the explicit dependence on q has been taken into account in order to relate the measured ACF to  $I_{\text{scat}}$  and  $E_{\text{scat}}$ . This latter equation can also be expressed as

$$g_2(q,\tau) = \langle I_{\text{scat}}(q,t) \rangle^2 \left( 1 + \beta |g_1(q,\tau)|^2 \right) \tag{3}^{\text{psi}}$$

This equation is known as the Siegert relation  $^{38}$  283  $\langle I_{\text{Scat}}(q,t) \rangle = I_{\text{Scat}}(q)$ , is the static scattering intensity at wave vector  $\vec{q}$ ;  $g_1(q,\tau)$  is the first-order ACF, de-285 fined as:  $g_1(q,\tau) = \langle E_{\text{scat}}^*(q,t)E_{\text{scat}}(q,t+\tau) \rangle$ , hence  $g_1(q,\tau) \propto \langle \delta \hat{n}(-q,t)\delta \hat{n}(q,t+\tau) \rangle$ . The factor  $\beta$  is the inverse of the number of coherence area on the photodetector surface 288 i.e. the number of speckle spots;  $0 \leq \beta \leq 1$ .

Note that in the rest of this article, we get rid of the dependence on q; both for reasons of simplicity, and also because in the following it is only considered experiments with fixed q; hence we write:  $g_2(\tau) = \langle I_{\text{scat}}(t) \rangle^2 \left(1 + \beta |g_1(\tau)|^2\right)$ , with  $g_1(\tau) \propto \langle \delta \hat{n}(t) \delta \hat{n}(t+\tau) \rangle$ .

The first step of a DLS experiment is to obtain an ACF  $g_2(\tau)$  that can be readily analyzed. To obtain such a function care must be taken. If  $T_0$  is the duration over which the ACF of the scattered intensity is computed, the scattering signal has to be stationary over  $T_0$ , i.e.  $\langle I_{\text{scat}}(q,u) \rangle = \text{cste}, \forall u \in [0,T_0].$ The largest value of the probed  $\tau$  has to be larger than the slowest relaxation time of the system; and  $T_0$  must be, at least, 10 times larger than the last value of the probed  $\tau$ . If all that is satisfied, then  $g_2(\tau)$  could be correctly estimated. Moreover, noise may be reduced by iterating the computation of  $g_2(\tau)$  to average them. In such cases, it provides accurate information on the dynamics of systems in thermodynamic equilibrium, or at least in a stationary state throughout the experiment duration. (Note that using a correlator,  $T_0$  and the signal duration acquisition  $\Delta T$  are always identical. However, if the ACF is computed from the measurement of  $I_{\text{scat}}(t)$ ,  $T_0$  can be different from  $\Delta T$ ). If it is used a correlator that typically probes  $\tau$  between  $10^{-8}$  s and 1000 s, (their optimal operating range, in practice, is rather  $10^{-6}$  s - 10 s), this first step works well for systems the relaxation times of which are included within this latter range that corresponds to most of "soft matter" systems in thermodynamic equilibrium.

The second step of a DLS experiment is to extract the relaxation times  $\zeta_i$  of the investigated sample from the measured ACF  $g_2(\tau)$ . The objective is, on the basis of physically relevant characteristics of the probed system, to relate  $|g_1(\tau)|^2$  to the relaxation times. For example, in the canonical case of a dilute solution of monodisperse nanospheres, there is only a single relaxation time  $\zeta$  related to the Brownian diffusion of the particles. Thereby  $|g_1(\tau)|^2 = e^{-2\tau/\zeta}$ , where:  $1/\zeta = D_0 q^2$ ,  $D_0$  being the diffusion coefficient of the spheres, i.e.  $D_0 = k_B T/6\pi \eta R_h$  as recalled above. Using a parametric fit  $(g_2(\tau) = A + Be^{-2\tau/\zeta})$ , it is easy to obtain  $\zeta$ , and then the hydrodynamic radius of the particles. Actually, particles are often polydisperse and then  $|g_1(\tau)|^2$ is no longer a simple decaying exponential function. For slightly polydisperse spheres, the ACF can then be fitted to a cumulant expansion around some mean relaxation time  $\zeta$ :  $|g_1(\tau)|^2 \simeq e^{-2\tau/\zeta} \left(1 + \mu_2 \tau^2/2 + ...\right)^2$ , where  $\mu_2$  is the 2<sup>nd</sup> order moment of the particle size distribution; and this parametric expansion can be continued to higher orders 40-42. However, this method is only adapted to systems that exhibit a single polydisperse relaxation time.

Unfortunately, not all the systems are as simple as slightly polydisperse nanospheres in dilute solution. Still, many methods have been proposed to fit (either linearly or non-linearly)  $|g_1(\tau)|^2$  in terms of the cumulants (or moments) of the relaxation times distribution<sup>41–44</sup>. However many systems are actually much more complex. They can, indeed, exhibit several relaxation times that can be broadly distributed over many

decades, with in some cases very long relaxation times, largeB41 than a few seconds<sup>4–18</sup>. Under these conditions, one approach<sub>842</sub> is to fit  $|g_1(\tau)|^2$  to a model that is the square of a sum of ex-343 ponential decays. Thus:

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$$|g_1(\tau)|^2 = \left| \sum_{i=1}^M a_i e^{-\tau/\zeta_i} \right|^2 \tag{4}_{\mathbf{347}}^{\mathbf{346}}$$

with M > 2 the number of modes, and  $\zeta_i$  the mean relaxation time of the ith process. It can even be used a more complicated model, where it is assumed a time relaxation polydis-349 persity around each  $\zeta_i$  (as in the previous model). Nonetheless, these approaches fail quickly due to the large number of fitting parameters required. Often, in complex cases, to take into account several relaxation times,  $|g_1(\tau)|^2$  is modeled by  $g_{352}$ the empirical Kohlrausch-William-Watts (KWW) form<sup>6,43,45</sup>.  $|g_1(\tau)|^2 = e^{-2(\tau/\zeta)^{\alpha}}$ , where  $\alpha$  is a parameter, which in the  $g_{554}$ case of systems in equilibrium is in the range [0,1]. Then 355  $g_1(\tau)$  is a stretched exponential function, which means that it decays slower than a single exponential relaxation. This is, assumed to reflect the existence of a broad distribution of re-358 laxation times. However, even if this kind of functions fits to 359  $|g_1(\tau)|^2$  properly, physical interpretation of both  $\zeta$  and  $\alpha$  may<sub>360</sub> Andrews et al. 43,44, KWW models do not always capture the whole relaxation processes present in the ACF.

Henceforth, in the general setting, and especially for sys<sub>364</sub> tems with a broad distribution of relaxation times, a good ap<sub>365</sub> proach to interpret DLS measurements is to move to a non-<sub>366</sub> parametric method and to consider that  $g_1(\tau)$  provides the<sub>367</sub> Laplace transform (LT) of a density distribution of relaxation<sub>368</sub> times, G(s):

$$g_1(\tau) = \int_0^{+\infty} G(s) e^{-\tau/s} ds$$
 (5)

Eq. (5) is the Laplace transform of G, except that here there Laplace variable s has the same dimension as  $\tau$ . Note that in this article, we use s for the Laplace variable and keep at distinct notation  $\zeta$  for the relaxation times.

Hence, as already advocated by S. Provencher<sup>36,37</sup>, and also 377 more recently by Andrews et al. 43,44, rather than a parametric 78 fit, to get all the relaxation times  $\zeta_i$ , it is more powerful to esti-379 mate the inverse Laplace transform (ILT) of  $g_1(\tau)$ . Therefore 380 to obtain a non-parametric estimation of G(s), one has simply 381 to invert eq. (5). The difficulty is that the ILT process is nu-382 merically an ill-conditioned problem, prone to be very sensi-383 tive to any experimental or numerical noise. In references 36,37 it is developed a method for regularized inverse Laplace trans-385 form, called CONTIN that is particularly used in the analysis 86 of DLS and X-ray photon correlation spectroscopy (XPCS)887 autocorrelation functions (its applications, however, are much see broader than just these fields). The major contribution of S. Provencher<sup>36,37</sup> was to develop and validate, both mathe 390 matically and numerically, an algorithm to compute the ILT<sub>391</sub> of the ACF in a stable manner thanks to a regularization of so2 this ill-conditioned problem. Many different solutions for ILT have been developed with other approaches including 94 maximum entropy<sup>47</sup>, maximum likelihood<sup>48</sup> or non-negative<sub>395</sub> SVD<sup>49</sup>. Compared to parametric fits or other methods, the CONTIN method requires little prior knowledge about the relaxation times of the investigated system. Note that this approach works for both ACFs built using a correlator and ACFs computed from  $I_{\text{scat}}(t)$ . (For particle sizing, the CONTIN method is now a routine analysis used in commercial DLS softwares.)

#### C. Current approaches for non-stationary DLS signals.

In principle, for experiments on non-equilibrium or non-stationary systems, the approaches described in the former section should not be employed. Nonetheless, because of the interest of DLS or XPCS techniques to probe the dynamics of Soft Matter, works have used these techniques to investigate non-equilibrium systems. Therefore, many attempts were made to follow the temporal evolution of non-stationary scattered signals. Time-resolved-correlation measurements were proposed to quantify statistically dynamical heterogeneities <sup>50,51</sup>. Two-time correlation functions were used to represent the temporal evolution of ACFs in two dimensions <sup>46,52–54</sup>. All these works are very interesting and in these cases, the authors overcame to extract relevant information on the dynamics of the investigated systems.

Fluerasu et al. 52, Madsen et al. 46,55 and Cipilletti et al. 56 investigated dynamics of gels or glassy-like systems by analysing the ACFs of the scattered intensity using KWW models. Mostly, they followed the temporal evolution of the coefficient  $\alpha$  of the KWW model. In these cases, and contrary to what is observed for systems at thermodynamic equilibrium, it can be found  $\alpha < 1$ , or  $\alpha > 1$ . Sometimes, as for equilibrium systems, the ACF is a stretched exponential, and then  $\alpha$  is likely the signature of a broad distribution of relaxation times. But at other times, it is found  $1 < \alpha$ ; when  $1 < \alpha$ ,  $g_1(\tau)$  is a compressed exponential function, which means the ACF decays faster than a single exponential relaxation. The physical meaning of such a relaxation is not yet well understood. Nevertheless, such approaches allow to characterise the investigated dynamics through the degree of stretching or compression of its exponential relaxation. For aging systems slow dynamics can be investigated thanks to such methods, yet assumptions on the dynamics are required and faster relaxations are overlooked, or not investigated, as mentioned<sup>43,46</sup>. All these analyses manage to provide temporal evolution of an average behavior of the dynamics as well as of its heterogeneities. These analyses, however, do not attempt to measure the relaxation spectrum, i.e. the different characteristic times that compose the dynamics of the investigated systems, nor their evolution as a function of time.

It is still lacking an accurate signal processing tool able to quantify, from DLS measurements (or XPCS), the whole dynamics of a non-stationary system as a function of time (at least over a broad range of relaxation times). Indeed, from our knowledge, there is no systematic, multiscale and free-of-a-priori method available yet to analyse non-stationary signals of DLS in order to obtain the full spectrum of relaxation

times of an out-of-equilibrium system and follows its evolu-450 tion. This is the goal of our article.

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### D. Adaptation of "CONTIN" based methods to non-stationary signals.

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In this article, we intend to bring about a general, system<sup>456</sup> atic and accurate method allowing to extract temporal evo-457 lution of the relaxation times of non-stationary signals. As458 we aim to investigate samples having, a priori, a dynamic<sup>459</sup> with many relaxation times, polydispersed and spread overa broad time range, we believe that the best approach is to 161 assume that the ACF of the scattered intensity is the Laplace 62 transform of a density distribution of relaxation times. In this 463 case, however, the ACF is a non-stationary function of the464 time t and, consequently, one should deal with a more general 65 non-stationary ACF, which is  $g_2(\tau, t, T_0)$ , and the correspond. ing  $|g_1(\tau,t,T_0)|^2$ . There, indeed, the ensemble average is re-467 placed by a local temporal average computed between t and to a local temporal average computed between t and the same temporal average computed between t and the local temporal average computed between the local temporal ave  $t + T_0$ , where  $T_0$  is the duration over which the ACF is built. In this notation, we highlight the dependence of  $g_2(\tau)$  with  $t_4$ 70 which is the starting time of the ACF measurement. Further-471 more, we make explicit that the estimation of  $g_2(\tau, t, T_0)$  (i.e.472  $g_1(\tau,t,T_0)$ ), also depends on the duration over which  $g_2(\tau,t)$  $(g_1(\tau,t))$  is computed. Therefore,  $g_1(\tau,t,T_0)$  can be written 474 as the Laplace transform of a density distribution of relaxation<sub>875</sub> times,  $G(s,t,T_0)$ : 476

$$g_1(\tau, t, T_0) = \int_0^{+\infty} G(s, t, T_0) e^{-\tau/s} ds$$
 (6)<sup>478</sup>

Let us explain the ideas behind our approach. First of all, it 480 is chosen a first starting time  $t_1$ , and  $g_1(\tau, t_1, T_0)$  is computed<sup>481</sup> between  $t_1$  and  $t_1 + T_0$ . Then, it is chosen a second starting<sup>482</sup> time  $t_2$ , and a new ACF  $g_1(\tau, t_2, T_0)$  is computed between  $t_2$  and  $t_2 + T_0$ . This process is iterated in order to achieve a series of ACFs whose starting times are all different. Thanks<sup>484</sup> to eq (6), each of these  $g_1(\tau, t_i, T_0)$  is related to a density distribution of relaxation times  $G(s,t_i,T_0)$ . As in the classical CONTIN used on systems in equilibrium, here also one has to invert eq. (6) to obtain a non-parametric estimation of the 485 distribution of relaxation times  $G(s,t_i,T_0)$ . Such a procedure should provide the relaxation times of the studied system as a function of time; i.e.  $\zeta_i(t_i)$ . This use of a sliding window<sup>487</sup> connects the method to a non-stationary setting.  $T_0$  reminds<sup>488</sup> us that  $G(s,t_i,T_0)$  (and thus the relaxation times  $\zeta_i$ ), cannot be well estimated when they are not small enough compared. to  $T_0$ . Hence, by playing with  $T_0$ , it is possible to change the so investigated s range, allowing thus a multiscale approach of page 1 the scattering signal analysis.

In order to follow such a strategy to investigate the dy-494 namics, as well as its time evolution, for non-equilibrium and 955 non-stationary systems, care has to be taken when measuring 92  $(\tau, t, T_0)$ . It is obvious that building the ACF of the scattered 977 intensity thanks to a correlator will not bring about worthwhile 988 results, since the correlator returns  $g_2(\tau, t, \Delta T)$ , where t can-499 not be tuned. A direct measurement of the scattered intensity 500

 $I_{\text{scat}}(t)$ , with a high acquisition rate and over a long period of time  $\Delta t$ , is indeed necessary to apply our signal processing. Once  $I_{\text{scat}}(t)$  recorded, the different  $g_2(\tau, t_i, T_0)$   $(g_1(\tau, t, T_0))$ can be computed, where it will be possible to play with both parameters  $t_i$  and  $T_0$  in order to be able to finely follow the time evolution of the dynamics (multi scale approach). As written previously, to analyze these functions properly, the first step of this work is, therefore, to rewrite a new version of CONTIN that takes into account a logarithmic distribution of the delay times  $\tau$ , over at least 6-7 decades, with appropriate regularization that makes it resilient to experimental noise and statistical limits in the estimates of ACFs over these broad time ranges. We will then demonstrate that this modified version of CONTIN is still a suitable non-parametric method to allow, from DLS measurements, the extraction of characteristic relaxation times of systems with multiple relaxation processes and high polydispersity. This modified algorithm, indeed, is a new ILT algorithm.

That is by combining computation of  $g_1(\tau, t, T_0)$  functions, from  $I_{\text{scat}}(t)$  measurements, with the new ILT algorithm, that the time evolution of the dynamics of non-equilibrium and non-stationary systems can be accessed. This will be proved on experimental situations.

The objectives and novel contributions of the present article are the following:

- Revisit the classical CONTIN method in a modern and practical way, so as to put forward its advantages when processing non-stationary DLS experiments.
- Provide a "Time-Laplace method" that brings a systematic way to analyze the temporal evolution of relaxation times for systems exhibiting multiple relaxations and strong polydispersities.
- Provide a multiscale approach allowing to monitor the resolution of the relaxation times and of their evolution.

### III. NON-STATIONARY DLS SIGNAL PROCESSING BASED ON INVERSE LAPLACE TRANSFORM

### A. Log spaced and weighted Inverse Laplace Transform algorithm.

Let's assume that we have a measure of the scattered light intensity as a function of time,  $I_{\text{scat}}(t)$  (we will describe the procedure for acquiring  $I_{\text{scat}}(t)$  in section IV B). The starting point of the procedure we develop here is the estimation of the ACFs of the scattering intensity (**ACF**) from  $I_{\text{scat}}(t)$ . Hereafter these estimated ACF are noted  $\hat{g}_2(\tau,t,T_0)$ . As discussed, these ACF are computed over a time window of length  $T_0$ , between time t and  $t+T_0$ . In practice, to probe a broad range of relaxation times,  $\hat{g}_2(\tau,t,T_0)$  is calculated as a logarithmic downsampled version of the standard, biased and normalized, autocorrelation estimator, expressed with the centered intensity  $I^c(u) = I_{\text{scat}}(u) - \sum_{t=1}^{t+T_0} I(v)$ . Therefore  $\hat{g}_2(\tau,t,T_0)$  writes

as:

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$$\hat{g}_2(\tau,t,T_0) = \frac{\sum_{u=t}^{t+T_0-\tau} I^c(u) I^c(u+\tau)}{\sum_{u=t}^{t+T_0} I^c(u)^2}. \tag{7}$$

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Here  $\hat{g}_2$  is normalized (on contrary to  $g_2$  in eq. (3)). One can<sub>622</sub> notice that this expression of  $\hat{g}_2(\tau, t, T_0)$  is as writing that:

$$\hat{g}_2(\tau, t, T_0) = \frac{\langle I_{\text{scat}}(t)I_{\text{scat}}(t+\tau)\rangle_{T_0} - \langle I_{\text{scat}}(t)\rangle_{T_0}^2}{\langle I_{\text{scat}}(t)\rangle_{T_0}^2} \qquad (8)_{\text{52}}^{\text{52}}$$

Which according to Siegert's equation (eq. (3)) is equivalents to

$$\begin{split} \hat{g}_2(\tau, t, T_0) &= \frac{1}{\beta} \left( \frac{\langle I_{\text{scat}}(t) I_{\text{scat}}(t+\tau) \rangle_{T_0}}{\langle I_{\text{scat}}(t) \rangle_{T_0}^2} - 1 \right) \\ &= |g_1((\tau, t, T_0)|^2 \quad (9)^{\text{p3o}} \end{split}$$

The estimated ACF,  $\hat{g}_2$ , is thus equal to  $|g_1|^2$ . Hence, by nor-532 malizing and centering the ACF, the experimental aspects of the measurement are eliminated (the baseline and  $\beta$ ) to give rise to a quantity directly related to  $g_1$ . Moreover, if one would assume a model as in eq. 4:

$$|g_1(\tau)|^2 = \left| \sum_{i=1}^{M} a_i e^{-\tau/\zeta_i} \right|^2$$

$$= \sum_{i=1}^{M} |a_i|^2 e^{-2\tau/\zeta_i} + \sum_{i \neq j} a_i a_j^* e^{-\tau/\zeta_i - \tau/\zeta_j}, \quad (10)_{539}^{538}$$

then the cross terms are in fact negligible, or more precisely, incorporated in the broadening of the distributions as if there were some polydispersity. For example, if  $\zeta_i$  and  $\zeta_j$  are very different, then the cross term is dominated by the smaller one<sup>540</sup> and it is inside the peak associated to it. On the other hand, if<sup>641</sup> they are close to each other,  $1/\zeta_i + 1/\zeta_j \simeq 2/\zeta_i$ , and thus they<sup>542</sup> are not distinguishable from polydispersity. Therefore

$$|g_1(\tau)|^2 \simeq \sum_i |b_i|^2 \mathrm{e}^{-2\tau/\zeta_i}$$
 (11)<sup>F45</sup>

where the amplitudes  $b_i$  reflect the influence of the  $cross_{\texttt{b48}}$  terms. Thereby

$$\hat{g}_2(\tau, t, T_0) \simeq \sum_i |b_i(t, T_0)|^2 e^{-2\tau/\zeta_i(t, T_0)}$$
 (12)

Hence one expect the characteristic (local) relaxation times of  $\hat{g_2}(\tau)$  to be equal to the half of the  $\zeta_i$ , and therefore the ILT of  $\hat{g_2}(\tau)$ , should provide relaxation times that are the half of the real relaxation times.

ILT algorithms, such as CONTIN, aim at performing the inverse Laplace transform of  $\hat{g}_2(\tau)$ , by numerically solving an inverse problem to provide an estimate  $\hat{G}$  written as follows:

$$\hat{G}(s,t,T_0) = \arg\min_{G \in \mathscr{G}} (\|LT(G) - \hat{g}_2(\tau,t,T_0)\|_w^2 + \gamma^2 R(G))$$

$$(13)_{ES}^{552}$$

where R(G) is the regularization term,  $\gamma$  a parameter,  $\mathcal{G}$  is the set of constraints defining the admissible G, and  $w(\tau)$  leaves the possibility to have a weight in the norm with respect to the delay  $\tau$ . The discretization of the Laplace transform has to be specified, as well as the choice for the regularizations and weights. To take advantage of the acquisition of the scattered light intensity over a long duration, we use a logarithmic sampling both in the delays  $\tau_j$  and in the Laplace variable  $s_k$ . This sampling goes from the smallest measured delay  $\tau_1$  (equal to the sampling interval) up to  $\tau_N = T_0$ , as it is the maximum value that makes sense. A similar sampling is done for the  $s_k$ , using  $N_s$  points. LT(G) is computed as the discretized expression of the integral in eq. (6):

$$LT(G)(\tau_j) = \sum_{k=1}^{N_s} G(s_k) e^{-\tau_j/s_k}$$
 (14)

The set of constraints  $\mathscr{G}$  is that  $\forall s, G(s) \geq 0$ . The regularization term R(G) is taken to promote regularity and smoothness, with a minimum number of peaks; an adequate choice is  $R(G) = \left\|D^{(2)}(G)\right\|^2$ , where  $D^{(2)}$  is the second order discrete difference operator, which writes:

$$D^{(2)}(G(s_k)) = G(s_{k+1}) - 2G(s_k) + G(s_{k-1})$$
 (15)

The weight function  $w(\tau)$  is introduced in the first term of eq. (13) because it is expected, by letting the  $\tau_j$ 's increase up to  $T_0$ , to have higher statistical fluctuations at large delays than at small delays. This constrains  $LT(\hat{G})$  to follow more closely  $\hat{G}_2$  at short delays than for the large delays. This weight is:

$$w_j = w(\tau_j) = \sqrt{\frac{T_0}{\tau_j}} \tag{16}$$

Indeed, it can be expected that the variance of the fluctuations of the autocorrelation estimators<sup>57</sup> roughly evolves as  $\tau/T_0$ . In other words, the number of decorrelated measures at delay  $\tau$  over a duration  $T_0$  evolves as  $T_0/\tau$  and this leads to the following choice of weighting.

Altogether, and introducing both the logarithmic increments  $\Delta sk$  and  $\Delta \tau_j$ , as well as the matrix notation  $(\mathbf{A})_{jk} = \exp(-\tau_j/s_k)$  for the exponential term in the LT, it is obtained the discrete form of the eq. (13):

$$\hat{G}(s,t,T_0) = \arg\min_{G \ge 0} \sum_{j=1}^{N} w_j \left[ (\mathbf{A}G)_j - \hat{g}_2(\tau_j, t, T_0) \right]^2 \Delta \tau_j$$

$$+ \gamma^2 \sum_{k=1}^{N_s} \left[ D^{(2)} \left( G(s_k) \right) \right]^2 \Delta s_k$$
 (17)

where N is the size of the downsampled vector  $\hat{g}_2$ .

The minimization of eq. (17) is implemented in Matlab, based on the CONTIN algorithm<sup>36,37</sup> and adapted from the implementation of Marino<sup>58</sup>. It alternates between finding the minimum of the unconstrained problem with the simplex algorithm (using fminsearch in Matlab), and projecting over the constraint.

In the next section, we verify that the choices of ACF normalization, discretization, and weighting work properly in our implementation.

#### B. Numerical validation in stationary condition.

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The first step is to prove that this method of analyzing ACFs<sup>914</sup> works. There are several requirements to check its proper<sup>615</sup> functioning. Obviously, this strategy has to be able to mea<sup>916</sup> sure reasonable values for each of the relaxation times present<sup>617</sup> in the ACF. Secondly, the ratio between two densities of re<sup>918</sup> laxation times needs to be approximately preserved through<sup>619</sup> the analysis. Thirdly, the regularization must work uniformly<sup>620</sup> for the all ranges of relaxation times.

To test these three points, this method is first applied to<sup>622</sup> modeled ACFs. For this purpose, ACFs described by a sun<sup>623</sup> of decreasing exponential functions were modelled in which<sup>624</sup> some polydispersity was incorporated as in the cumulant ex.<sup>625</sup> pansion model (here with order 2 in the cumulants only).<sup>626</sup> These ACFs follow the model:

$$g_{2,\text{mod}}(\tau) = \frac{\sum_{i=1}^{M} A_i e^{-\tau/\zeta_i} \left(1 + \frac{1}{2} \left(\sigma_i \tau/\zeta_i\right)^2\right)}{\sum_{i=1}^{M} A_i}$$
(18)30

where M is the number of relaxation modes;  $A_i$  is the amplitude of mode i,  $\zeta_i$  its mean relaxation time, and  $\sigma_i$  the relative standard deviation associated to  $\zeta_i$  (so that  $\sigma_i^2 = \mu_{2i}\zeta_i^2$ ). Fig. 1 rally, it is added noise to these ACFs. As in the experiments, the noise is higher at long times than short ones. Then, the ILT algorithm we developed is applied to these ACFs to compute the density function of the relaxation times  $\hat{G}(s)$ . It is always observed a very good agreement between the modelled ACFs and  $\hat{G}(s)$  calculated by means of the ILT algorithm that has been developed.

This numerical validation is illustrated with the follow-<sup>642</sup> ing example. An ACF is modelled with 5 different relax-<sup>643</sup> ation times (*i.e.* M=5), distributed over 8 decades in time, <sup>644</sup> with for each relaxation time a polydispersity of 20% ( $\forall i$ , <sup>645</sup>  $\sigma_i = 0.2$ ). The five relaxation times  $\zeta_i$  are:  $10^{-5}$  s,  $10^{-4}$  s, <sup>646</sup>  $10^{-3}$  s,  $10^{-2}$  s,  $10^{-1}$  s, respectively, with the following mode <sup>647</sup> amplitudes:  $A_i = 1, 0.2, 0.5, 1, 0.2$ . This ACF is displayed in <sup>648</sup> Fig. 2 (a); it is the orange dashed curve. Then, a random noise <sup>649</sup> increasing with  $\tau$  is added to this ACF to form a noisy ACF, <sup>650</sup> which is also shown in Fig. 2 (a); that is the blue curve.

Then  $\hat{G}(s)$  are calculated for both the noisy and the noise <sup>552</sup> free ACFs thanks to the ITL algorithm that was developed. The parameters that control the ILT algorithm are N, the num ber of points in  $\tau$  used to sample the ACF, and  $N_s$ , the num ber of points in s used to sample  $\hat{G}$ . For this test, it is set ber of points in s used to sample  $\hat{G}$ . For this test, it is set  $s = N_s = 100$ , so as to cover well the time range from  $s = 10^{-8} s = 10^{-8} s$ , with logarithmic spacing; there are about 12 points per decade. The parameter  $s = 10^{-8} s = 10^{-8} s$  decade. The

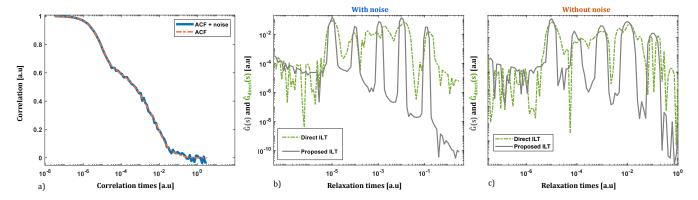
The calculated  $\hat{G}(s)$  are displayed in Fig. 2 (b) and Fig. 2<sub>665</sub> (c), for the noisy and the noise-free ACFs, respectively (both<sub>666</sub> gray solid lines). In both cases, five distinct peaks, well de<sub>-667</sub> fined, are observed. The analysis of the noise-free ACF almost<sub>668</sub> exactly returns the properties of this ACF. Let's now focus or<sub>669</sub>

the analysis of the noisy ACF. The peaks of relaxation times are obtained for:  $\zeta_i \simeq 10^{-5}$  s,  $9.410^{-5}$  s,  $1.110^{-3}$  s,  $9.910^{-3}$  s,  $1.110^{-1}$  s, respectively. These values correspond to the inputs  $\zeta_i$ 's nearly perfectly. It is likely that this small difference lies in the grid discretization; checking closely, when the input value is comprised between two points of the logscale sampling, the measured value is always one of these two points. The measured amplitudes for the different modes are:  $A_i \simeq$ 0.15, 0.034, 0.072, 0.13, 0.030, respectively. One can note that ratios between amplitudes are almost preserved, even if the amplitudes are not. It can be noted, qualitatively, that the relative widths of the peaks are similar (i.e., with respect to the relaxation times). For each peak, the standard deviation to relaxation time ratio is computed and it is found:  $\hat{\sigma}_i = 17$ , 14, 17, 18, 15 %. It remains some discrepancies with the set value, likely due to noise and numerical resolution, yet the result is satisfactory, demonstrating the uniformity of the regularization across s. Therefore, the used ILT algorithm perfectly captures the ACF features for the noisy ACF as for the noise-free ACF; this result demonstrates the robustness of our algorithm to noise.

In Fig. 2 (b) and Fig. 2 (c), it is also displayed  $\hat{G}_{direct}(s)(s)$ estimated using a classical CONTIN algorithm, for the noisy and the noise-free ACFs, respectively (green dotted lines). This algorithm does not take into account the logarithmic scale specifically, nor the weight w. CONTIN algorithm allows to recover, roughly, the characteristics of the ACF. The result, however, is obviously not as good as that obtained by means of the ILT algorithm developed in this work. It is clearly seen that using CONTIN algorithm, the regularization is not uniform along the s-axis: one observes several peaks for long relaxation times whereas broad peaks are observed at short relaxation times. It is also noticed that the CONTIN algorithm does not correctly preserve homogeneity of the peaks width; in this case, it depends on the considered time range. These observations emphasize the necessity to take into account the logscale, as well as used a weight function to reduce the effect of noise on ILT process.

It is worth noticed that if one wishes to analyze this ACF using a parametric fit, then this would require a very large number of parameters. Indeed, if trying to fit a cumulant model to such an ACF, 15 different parameters are necessary. Moreover, this would require having prior knowledge on the number *M* of relaxation times. It is, therefore, unrealistic to expect that such a fit can correctly evaluate such ACFs.

As mentioned before, for the implementation of the ITL algorithm developed in this work, it remains the question of the choice of the parameter  $\gamma$ . In fact, as for the classical CONTIN algorithm. The precise estimation of this parameter is a challenge. A too low value of  $\gamma$  can lead to artifacts, as a single relaxation time with a slight polydispersity can be detected as multiple relaxation times. On the other hand, a high value of  $\gamma$  may excessively smooth the solution, resulting in non-discrimination between two close relaxation times, or overestimation of the polydispersity of the sample. To determine  $\gamma$  in a heuristic way, multimodal ACFs are simulated from eq. (18) in order to estimate the resolution of the method. Here we do not detail the protocol used, but



**FIG. 2.** Left panel (a): modeled ACF from eq. 18; M = 5, with  $\zeta_i = 10^{-5}$  s,  $10^{-4}$  s,  $10^{-3}$  s,  $10^{-2}$  s,  $10^{-1}$  s, respectively, and  $A_i = 1$ , 0.2, 0.5, 1, 0.2. The polydispersity around each relaxation time is the same:  $(\forall i, \sigma_i = 0.2)$ . The orange dashed line is the noise-free ACF; the blue solid line is the noisy ACF (a random noise increasing with  $\tau$  was added to this ACF). Middle panel (b): density distributions of the relaxation times computed for the noisy ACF; using the ILT algorithm we developed  $(\hat{G}(s); \text{ gray solid line})$ , and a classical implementation of CONTIN<sup>58</sup>  $(\hat{G}_{direct}(s)(s); \text{ green dashed line})$ , this latter algorithm does not take into account weighting w nor a logarithmic scale,  $\gamma = 0.1$  in both cases. Right panels (c): density distributions of the relaxation times computed for the noise-free ACF; using the ILT algorithm we developed  $(\hat{G}(s); \text{ gray solid line})$ , and a classical implementation of CONTIN<sup>58</sup>  $(\hat{G}_{direct}(s)(s); \text{ green dashed line})$ 

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the idea behind this study is to set  $\gamma$  so that relaxation timesoo separated by at least one decade are always discriminated  $_{701}$  and that each peak with a polydispersity of the order of  $25\%_{702}$  is not split into several peaks. With such an idea, it foundoos out that a good compromise is obtained when  $\gamma$  belongsoot the interval [0.1-10]. Usually, under these conditions, theos relaxation times can be separated if there is at least a ratio of 3 between these times. These values of  $\gamma$  also imply that one or cannot estimate a polydispersity lower than 10%; below thisos value, such a polydispersity will lead to a broadening of theo peaks similar to the smoothing imposed by the regularization  $_{710}$ 

### IV. TIME-LAPLACE APPROACH FOR OUT-OF-EQUILIBRIUM SYSTEMS

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There is now a ILT algorithm for extracting a large number of relaxation times, spread over a broad time range, from any measured  $g_2(\tau,t,T_0)$  ( $g_1(\tau,t,T_0)$ ). In Sections II and III  $we^{T^0}$  have thought of an approach, based on this algorithm where of the evolution of the Laplace variables s is studied as a function of time. By analogy with time-frequency analysis, hereafter, this approach will be call Time- Laplace analysis. However, at this point there is still a problem: in practice, how can this method be applied to analyze DLS experiments carried out on this had been applied to an ergodic or non-stationary systems? In this section, we summarize what has already been written in this article and explain how this method is implemented.

#### A. Concepts of Time-Laplace analysis.

To illustrate our approach and demonstrate that usual DLS<sub>731</sub> approaches cannot work properly for non-stationary systems<sub>732</sub> we will use a toy example. Let us consider a non-stationary<sub>733</sub>

signal measured over 100s, with an instantaneous relaxation time,  $\zeta(t)$ , evolving linearly as a function of time from 0.35 s to 1s throughout its measurement (Fig. 3, left panel). First of all, let us carry out a classical DLS experiment where the ACF is built thanks to a correlator upon an estimation window  $T_0$ (which, in this case, is also the measurement duration  $\Delta T$ ). If  $T_0 = 100$  s, then the ACF appeared to be a single decaying exponential function (there is barely a factor 3 in  $\zeta$  between the starting and ending times), and it returns an average relaxation time (Figure 3, central panel). If  $T_0 = 10$  s, it is computed 10 ACFs over 100s and each ACF returns a relaxation time that depends on t (see right panel of Figure 3); this provides a more realistic view of the real instantaneous relaxation time as this one evolves less on a small window. This simple example clearly shows the importance of  $T_0$  choice to properly analyze a signal, the relaxation times of which evolve as a function of time. However, if nothing is known about the temporal evolution of the relaxation times, which is often the case when performing an experiment, it is very difficult to choose the right estimation window for the correlator. Moreover, additional difficulties arise when several relaxation times are involved. In this example, if a second relaxation time  $\zeta_2 = 10 \, \mathrm{s}$  is added, it is not possible to measure it using 10 windows. Two issues, indeed, raise from the non-stationarity of the scattering signal:

- Using a correlator, the signal acquisition and its process only allow to take "snapshots" of the dynamics of the system which average the relaxation times. For systems undergoing temporal evolution, it may lead to inaccurate information.
- Furthermore, it is no longer possible to iterate the computation of the ACFs to average them in order to reduce
  the experimental noise; in other words it is not possible to increase the signal/noise ratio using several data
  acquisitions.

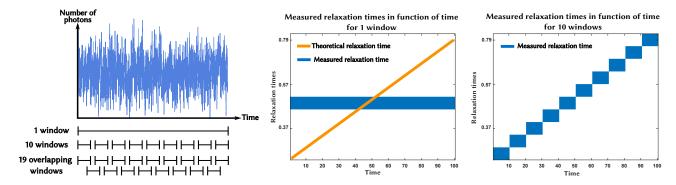


FIG. 3. Scheme illustrating our method: We compare the relaxation time(s) extracted when they are computed i) from only one large temporal window (middle panel) ii) from several shorter windows (right panel).

Therefore, in order to obtain a correct measurement of the 76 temporal evolution of all the relaxation times existing in the 77 system using a correlator, it would be necessary to measure 78 several ACFs with different delays and acquisition durations. Each  $g_2(\tau,t,T_0)$  would have to be measured on a different sample which must have the same evolution as the others. This is experimentally complicated and time consuming. It is therefore necessary to find out an alternative.

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Consequently, the Time-Laplace method we propose con-783 sists in decoupling the data acquisition and their analyzes. In-784 stead of building the scattered intensity ACF using a correla-785 tor, we simply record the raw scattered intensity as a function786 of time, i.e.  $I_{\text{scat}}(t)$ , over a duration  $\Delta T$ , by means of an ac-787 quisition card. In other words, I<sub>scat</sub> is sampled at a frequency<sup>788</sup>  $f_0 = 1/\delta t$  Hz over  $\Delta T$  seconds. Thanks to this, non-stationary, ACFs,  $\hat{g}_2(\tau, t, T_0)$ , can be estimated according to eq (7); there  $T_0$  and the starting times t at which the ACFs are computed are taken as tunable parameters in post-processing. This avoids<sup>791</sup> preliminary experiments to figure out the relevant relaxation time range to probe. More importantly, it gives the possibility to zoom in or out to focus on specific relaxation time ranges,793 providing thus a more dynamic view of the time evolution of 194 processes under investigation. This is achieved simply by using short or long  $T_0$ ; small  $T_0$  to better follow the time evolution of short relaxation times, larger  $T_0$  if the focus is on studying slower relaxation times (note that for a chosen  $T_0$ , respectively) only the relaxation times s less than about  $T_0/10$  are physically relevant, as the larger relaxation times are dominated by 799 estimation problems). The measurement of  $I_{\text{scat}}$  is performed  $^{800}$ over a long  $\Delta T$ , that takes into account the complete dynam<sub>-801</sub> ics of the studied system. In this way, on a sole experiment 802 and even for out-of-equilibrium systems, it is possible to process the scattering data at different scales of resolution  $T_0$ , for all relevant  $\tau$  and s. The starting times t of ACF computing can be sampled every  $T_0$ , yet there is advantage to use oversampling. This later point allows partial overlap between two consecutive windows. If we return to the example, we can sketch 19 windows of  $T_0 = 10$  s, where the starting time of the *n*-th window is  $t_n = 5(n-1)$  s as sketched on the left panel of Figure 3 (hence overlap between two consecutive windows of b10) 5 s). This provides a more continuous estimation of  $G(s,t,T_0)$  111 as a function of t, leading to obtain a "smoother" evolution of t

the dynamics, without decreasing  $T_0$  (*i.e.* the size of the window over which the ACF is computed). It will even allow us to track abrupt time variations.

Let us summarize the method for the proposed Time-Laplace approach:

#### • Time-Laplace parameters:

- **Signal acquisition:** Sampling rate of  $I_{\text{scat}}(t)$ :  $\delta t$ , it is the inverse of the acquisition frequency  $(f_0 = 1/\delta t)$ . Measurement duration:  $\Delta T$ .
- ACF computing: Window duration:  $T_0$ . Number of windows:  $N_w$ . Starting times of n-th window:  $t_n$  with n between 1 and  $N_w$ . Number of points in delays  $\tau_i$ : N.
- ACF analysis: Number of points in Laplace variable  $s_k$ :  $N_s$ . Parameter of regularization  $\gamma$ .
- **Input:**  $I_{\text{scat}}(t)$  recorded over the duration  $\Delta T$ .

#### Signal processing:

- Split  $I_{\text{scat}}(t)$  into  $N_w$  sub-signals covering window  $[t_n, t_n + T_0]$ .
- For each sub-signal:
  - \* Compute the ACF of the centered and normalized intensity, eq. (7), and keep the downsampled version at the N points  $\tau_i$ .
  - \* Apply ILT algorithm, minimizing eq. (17); it returns:  $\hat{G}(s_k, t_n, T_0)$ .
- **Output:** 2D-map  $\hat{G}(s,t,T_0)$ , characterizing temporal evolution of the dynamics of the system.

In the following,  $\hat{G}(s_j,t_n,T_0)$  is displayed as a 2D-map in the time-Laplace domain  $(t_n,s_k)$  (like in well-known Time-Frequency methods). The y-axis is the relaxation times s (Laplace domain) and the x-axis the window starting time t at which the ACF is computed;  $\hat{G}$  is displayed color-coded with a suitable colormap.

We use the method as described above, with a logarithmic spacing in  $\tau_j$  and  $s_k$ , with overlapping windows of duration  $T_0$  at times  $t_n$  so as to follow in a smoother way the temporal evolution of the relaxation times.

#### B. Light scattering signal acquisition

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Let us now describe what is the second key to our approach: the acquisition of the light scattering signal. In practice, the scattered photons are detected by means of an avalanche photodiode (Perkin Elmer) that is a photon counting system capable of detecting single photons of light over visible to near infrared wavelength range (400 nm to 1060 nm). This module is supplied by a triple output stabilized DC Power Supply (BK Precision-BK9130). The maximum number of photons that can be detected is of the order of 10<sup>7</sup> photons/s. Over the visible range the APD module detects about 60 - 70%of the received photons and its "dark noise" is in the range of 150 – 200 counts/s, so much lower than the number of photons detected in our experiments (typically of the order of, or larger than 10<sup>5</sup> photons/s). Each photon detected by the photodiodes gives rise to a transistor-transistor logic pulse (TTL). These pulses are sent to a "counting" channel of a data-acquisition card, which allows for counting each detected photon (DAQ NI USB-6361 - National Instrument; resolution 32-bits and maximum acquisition rate 10 MHz). To measure the scattered intensity as a function of time,  $I_{\text{scat}}(t)$ , the number of photons detected by the APD,  $N_p$ , is counted during time intervals  $\delta t$ over a duration  $\Delta T$  that is much larger than  $\delta t$  ( $\delta t$  is the sample time;  $\Delta = v \delta t$ , where v is the number of times the photon<sup>864</sup> counting process is repeated). Thus,  $I_{\text{scat}}(t_i) = N_p([t_i, t_i + \delta t_i])$ . The acquisition card is computer-controlled by means of 2866 LabVIEW program we developed that provides the number of 667 detected photons as a function of time,  $N_p(t)$ . Both values of 668 parameters  $\delta t$  and  $\Delta T$  can be monitored. The choice of both<sup>869</sup> parameters is essential to ensure that the measurements of the 870 scattering intensity upon time provide reliable information on<sub>871</sub> the dynamic properties of the considered sample. Basically, 872  $\delta t$  has to be short enough to allow access to the entire "fast"<sub>873</sub> dynamics of the system, while  $\Delta T$  has to be long enough so it<sub>674</sub> can provide access to the full "slow" dynamics of the system875 Moreover, to ensure good photon statistics, the incident laser, and laser, an power as to be set so there are at least ten photons in each  $\delta t_{877}$ interval are required, with the constraint that the number of 878 photons detected per second is less than 10<sup>7</sup> photons. 879

### V. DLS EXPERIMENTS WITH OUT-OF-EQUILIBRIUM SYSTEMS: EXPERIMENTAL VALIDATION

To experimentally validate the proposed Time-Laplacesss method, we investigate the time-evolution of the dynamicsso of three different non-equilibrium processes or systems: these cooling kinetics of a colloidal particle solution; the sol-gebse transition; and the internal dynamics of a living cell nucleus.

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## A. Temporal evolution of particle Brownian motion upon cooling

First of all, we apply the Time-Laplace method to the in-<sup>995</sup> vestigation of the Brownian relaxation of colloidal latex par-<sup>896</sup> ticles in a solution whose temperature evolves spontaneously<sup>897</sup>

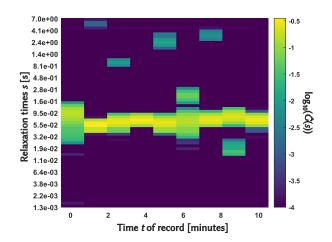


FIG. 4. Density map of the extracted relaxation times from a colloidal solution at constant temperature (paragraph V A 0 a). The x-axis corresponds to the beginning time when the ACF was computed. The y-axis corresponds to the measured relaxation times. The colorbar displays the density of the relaxation times distribution.  $T_0 = 1$  min, overlap = 0%,  $\gamma = 1$ , signal was recorded for 10 minutes.

from  $\sim 59^{\rm o}$ C to  $\sim 19^{\rm o}$ C. The temperature relaxation as a function of time induces changes in the particle diffusion coefficient  $D_0$  through the evolution of temperature and viscosity  $(D_0 = k_B T/6\pi \eta R_h)$ . This therefore creates a simple out-of-equilibrium process based on a solution of latex particles and we try to measure  $D_0(t)$  throughout the cooling process.

The investigated system is made up of 9 g of glycerol, 1 g of water, and 0.1 g of an aqueous solution of spherical latex particles with 1 wt% of solid. This colloidal solution is provided by the Duke Scientific Corporation and used without further purification (indicated particle radius:  $100 \pm 3$  nm). The 0.1 g of this solution is mixed with 1 g of milliO ultrapure water  $(\rho = 18 \pm 0.1 \text{ M}\Omega \text{ cm}; \text{ from an in house ELGA system})$ . The obtained mixture is filtered through a porous Nylon membrane with pores of  $0.45 \,\mu m$  diameter (Millex-HA syringe filter), to remove dusts and aggregates. It is then mixed with 9 g of glycerol. The obtained solution is allowed to equilibrate at room temperature over  $\sim 24$  hours. About 1.5 g of this final solution is placed in a cylindrical glass tube of 8 mm diameter that is set at the center of a vat containing an index-matching liquid (decahydronaphthalene). A thermocouple is inserted into the tube to allow in situ measurement of the sample temperature (accuracy  $\pm 0.1^{\circ}$  C). The internal temperature of the vat is monitored thanks to a thermal bath (Lauda); this sets the sample temperature. The sample is irradiated with a laser (Laser Quantum GEM, vertically polarized;  $\lambda = 532$  nm), the detector is placed at an angle  $\theta$  with respect to the direction of the incident beam. For  $\lambda = 532$  nm, the refractive index of the sample is  $\sim 1.45$  and its temperature variation is assumed to be negligible. The sample viscosity as a function of temperature is measured using a Kinexus Ultra+ rheometer, with a cone-plane geometry (cone characteristics: 2° - 60 mm).

a. Colloidal system at constant temperature. DLS experiments are used to measure the latex particle radius at dif-

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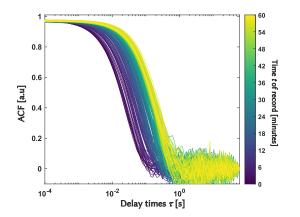


FIG. 5. ACFs computed along the experiment of the relaxation in temperature (paragraph V A 0 b) with  $T_0 = 60$  s, each color corresponds to a computed time indicated by the colorbar.

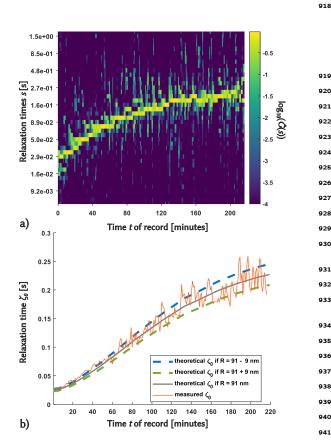


FIG. 6. Visualization of the relaxation times for the temperature re $_{\bf \bar{9}42}$  laxation experiment (paragraph V A 0 b). (a) Top panel: Density map $_{\bf 943}$  of the extracted relaxation times from a colloidal solution when temperature is relaxing.  $T_0 = 120$  s,  $\gamma = 1$ , overlap = 50%. (b) Bottom panel: Main relaxation time extracted  $\zeta_0(t)$  (see eq.20) for each time t (orange curve), expected relaxation time if  $R_{\rm mean} = 91$  nm (dot.947 (gray curve), expected relaxation times if  $R_{\rm mean} = 91 \pm 9$  nm (dot.947 ted lines).

ferent temperatures between 19°C and 59°C (i.e. 19.6°C, 32.0°C, 41.3°C, 51.2°C, and 58.3°C, respectively). Measurements are performed both by direct estimation of the ACF of the light scattering signal thanks to a TurboCorr Digital Correlator (Brookhaven Instruments), as well as acquiring the scattering intensity  $I_{\text{scat}}$  as a function of time according to the Time-Laplace procedure described in Sec. IV B (here:  $\delta t = 10^{-4} \,\mathrm{s}$  and  $\Delta T = 600 \,\mathrm{s}$ ). Fig. 4 shows the output of a scattering signal recorded over 10 minutes at T=41.3°C and analyzed with our Time-Laplace approach. Here, ACFs are computed over 1 minute sliding windows with no overlap between two consecutive slots. One notices that for most of the windows the analysis does not return a single relaxation time; very likely, because despite our efforts the sample is not simply a dispersion of monodisperse latex beads. However, one of the observed relaxation processes is always seen, its characteristic time does not evolve, and its amplitude is always much higher than that of the others. Moreover, this relaxation time corresponds to that obtained by fitting the ACF with the cumulant model. It is thus assumed that it corresponds to  $\zeta_0$ the relaxation time of the Brownian motion of the particles:

$$\zeta_0 = \frac{1}{2D_0 q^2} = \frac{3\pi \eta R_h}{k_B T q^2} \tag{19}$$

Both methods lead to the same result: it is found a particle radius  $R_h = 91 \pm 9 \,\mathrm{nm}$ , which seems to be rather constant as a function of temperature in the studied range. We use this measured size in the following. These experiments prove that the Time-Laplace method works well when the system under investigation is in thermodynamic equilibrium and so the scattering signal is stationary.

b. Cooling kinetics of a colloidal system. The initial temperature of the sample,  $T_i$ , is set to  $58.6 \pm 0.1$ °C. We wait for half an hour to make sure that the sample has reached its thermodynamic equilibrium prior to starting the measurement.

- To start with, light scattered by the sample at  $T_i$  is recorded for 2 minutes (acquisition with a sample time  $\delta t = 10^{-4}$  s).
- Then the thermal bath is turned off. This sets the beginning of the experiment, t=0 s; the system (vat + sample) is let to cool down to room temperature;  $T_f=19\pm 1^{\circ}\text{C}$ .  $I_{\text{scat}}(t)$  is recorded during the cooling process until 23.2°C. Parameters of the signal acquisition are:  $\delta t=10^{-4}$  s and  $\Delta T=13200$ s (220 minutes). During the whole experiment, temperature inside the sample is read every 30 s.

For this experiment, ACFs are computed from  $I_{\text{scat}}(t)$  over 2 minutes sliding windows with an overlap between two consecutive slots of 50% (i.e. one minute). Figure 5 shows the evolution of the ACFs with time. It is noticed that the decay rate of these ACFs shifts towards large relaxation times as the system cools. The  $\hat{G}(s,t)$  distribution is extracted for each ACF; an example of fit is displayed in Fig. 7. The agreement between the experimental ACF and that which can be calculated from the found  $\hat{G}(s,t)$  distribution is always very good.

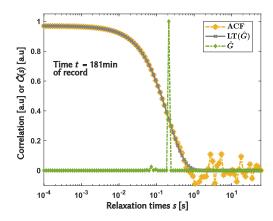


FIG. 7. Visualization of the data adjustment with the proposed ILT algorithm for the temperature cooling experiment. The yellow curve (stars) shows the ACF computed from the data. The ACF was computed 181 min after the beginning of the experiment with  $T_0 = 60_{983}$  s. The green curve (diamonds) exhibits the distribution of relaxation times  $\hat{G}(s)$  computed with the proposed method with  $\gamma = 1$ . The gray curve (crosses) is the ACF fit calculated from the result  $\hat{G}(s)$  using eq. (14).

As expected, it is clearly seen that the sample dynamics slows down with time (see Fig 6 (a)). One notices that in almost all cases, the relaxation is not a single exponential; several  $re_{989}$  laxation times can be observed. Nevertheless, one relaxation always dominates strongly; its amplitude being much higher than that of the others. The temporal evolution of this relax-991 ation time is assumed to be the evolution of the relaxation time of the Brownian motion of the particles  $\zeta_0(t)$  as the system cools down.

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The radius of the latex particles is known, as well as  $T(t)_{995}^{996}$  the temperature in the sample as a function time from t=0 s. The sample viscosity as a function of T has been measured. The temporal evolution of the particle diffusion coefficient  $D_0(t)$  can therefore be calculated during the cooling process, allowing modeling of  $\zeta_0(t)$ .

$$\zeta_0(t) = \frac{1}{2D_0(t)q^2} = \frac{3\pi\eta(T(t))R_h}{k_BT(t)q^2}$$
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Fig. 6 (b) displays both measured and calculated values of  $s_0(t)$  throughout the sample cooling (with scattering angleoss  $\theta=45^{\circ}$ ). The agreement between the model and the experiment is good. We conclude that these experiments demonsors strate that the Time-Laplace method is suitable to probe theose dynamics of systems that are not in thermodynamic equilibroos rium and when the scattering signal is non-stationary.

Our goal here is to validate the Time-Laplace method and not to investigate what happens in the sample as it  $cools_{012}$ . Therefore, we will not discuss these results further. Howevis ever, it is worth noticed that the  $\hat{G}(s,t)$  distributions exhibited more relaxation times than those obtained when the sample is in thermodynamic equilibrium. Fluctuations in the meanis sured values of  $\zeta_0(t)$  are also observed. We believe these observations come from the non-equilibrium aspect of the pherois nomenon; cooling induces convection in the sample and assis

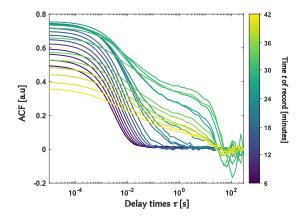


FIG. 8. ACFs computed along the experiment of the transition solgel with  $T_0 = 300$  s (paragraph V B).

a consequence temperature within the scattering volume may fluctuate significantly in time and space; because of convection, dust or objects larger than the latex beads may pass inside the scattering volume. Therefore, the analysis of the temporal behavior of  $\hat{G}(s,t)$  can also provide valuable information on the evolution of the studied system.

#### B. Sol-gel transition

The second process investigated to test the Time-Laplace method is the sol-gel transition in colloidal solutions. This transition occurs when the repulsive interactions between colloids, which prevent their aggregation, are screened. As a result, colloidal particles can approach close to each other and stick together due to van der Waals forces. It is then observed growth of fractal objects formed by their aggregation<sup>59,60</sup>. Once these structures percolate the gel phase is formed.

Here, the used system is an aqueous solution of silica nanobeads of  $\sim 12$  nm diameter. This colloidal suspension is stabilised due to electrostatic interactions between the particles. In that case, addition of ions to the solution changes the ionic strength and leads to screening of these interactions and induces the transition. Concentration in silica particles, as well as the kind of ions added to the solution and their concentration monitor this transition and its kinetic  $^{61}$ .

For these experiments, we used two different DLS setups; the setup used for the colloid solution cooling experiment as in Sec. V A, and a setup we developed to investigate the dynamics of a living cell nucleus. Here, it is only displayed experiments performed with the latter device. 0.3g of the final mixture is introduced into a special chamber of  $10 \times 10 \times 3$  mm<sup>3</sup>, that is made by sandwiching a stainless frame  $(65 \times 35 \times 3 \text{ mm}^3)$  between 2 microscope slides. This provides a container of low thickness and small volume whose both sides of entry and exit of light are transparent. The solution is introduced into this chamber thanks to two channels of 1 mm diameter drilled in the section. The chamber is set in a vice, the glass surfaces perpendicular to a laser beam (He-Ne laser, vertically polarized;  $\lambda = 632, 8$  nm). Temperature

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is  $\sim 20^{\rm o} \pm 0.5^{\rm o}$ C. Once the sample is placed, recording of the scattering signal is started with the following parameters  $\delta t = 10^{-5}$  s and  $\Delta T = 2400$  s (40 minutes). These measurements were made at  $\theta = 12^{\rm o}$ ; 25° and 30°.

Here, it is shown the result of an experiment performed us<sup>2079</sup> ing the second DLS setup, with  $\theta = 25^{\circ}$ . The recording of the scattering signal starts 6 minutes after the mixing of the solo80 lutions. The colloidal solution is prepared by simply mixing<sup>081</sup> 4.54g of LUDOX® HS-40 (suspension of colloidal silica itp82 H<sub>2</sub>O with 40 wt % of solid; from Sigma Aldrich) with 13.39 g,083 of milliQ ultrapure water ( $\rho = 18 \pm 0.1 \text{ M}\Omega$  cm; from an if  $\rho^{84}$ house ELGA system). In order to remove dusts and big ag1085 gregates, the obtained solution is first filtered through a glastose fiber membrane (GF/A) with pores of 1.6  $\mu$ m diameter (What experience) man® Puradisc 13 syringe filters). At the same time, 3.93 8088 of a NaCl solution with a NaCl concentration of 17.55 wt 9689 are prepared. At t = 0 s, 0.33 g of the NaCl solution artegor added to 1.5g of the colloidal mixture. This gives rise to 2091 final solution with a colloidal silica concentration of 8.3 wt 9092 and a NaCl concentration of 3.15 wt %. Dissociation of NaClp93 molecules into Na<sup>+</sup> and Cl<sup>-</sup> ions make the electrostatic inter<sup>1,094</sup> actions between particles vanish (the negative charges of the objection) silica nanobeads are screened by Na<sup>+</sup> ions) and the gelatioth of process starts. According to rheology studies<sup>62</sup>, in these ex<sup>1097</sup> perimental conditions, it takes about 27 minutes after mixin №98 the two solutions to form the gel phase.

Figure 8 shows the evolution of the computed ACFs as a 2000 function of time throughout the gelation process (in this case, 101 ACFs are computed from  $I_{\text{scat}}(t)$  over  $T_0 = 300 \,\text{s}$  with an over  $\frac{1.102}{1.000}$ lap between two consecutive slots of 70%). The observation<sup>103</sup> are coherent with previous works<sup>59</sup>: First, the value of the value of the ACFs plateau that is seen at short delay times increases (this is 15105 related to the increase in scattered intensity), then, in a second 106 part, the plateau position starts to decrease with time (due to to decrease) the decrease of the scattered intensity). This change of behav<sup>1108</sup> ior in the scattering intensity is assumed to indicate the full of gelation of the sample; the drop of the plateau of the ACF8110 indicating a reduced mobility due to the formation of a longrange network. According to this result, the full gelation process takes about 26-27 minutes after the mixing, in agreement 11 with rheology measurements. It is also noticed that the shape of these ACFs evolves strongly as gelation process progresses, At the beginning of the process, the ACFs are close to a single exponential decay with a short relaxation time, then the ACF5114 take on a more and more pronounced stretched exponential 115 shape, with an increasing relaxation time.

Figure 9 shows an instance of the ACF fitted by the  $pro_{\bar{1}17}$  posed method. One sees that (here before full gelation) the distribution of relaxation times is largely spread over two decades. Figure 10 displays four different Time-Laplace anal  $_{\bar{1}120}$  yses of the recorded signal along the full experiment.

• ACFs are computed from  $I_{\text{scat}}(t)$  over  $T_0 = 5 \, \text{s}$  sliding<sub>123</sub> windows with no overlap between two consecutive slots<sub>124</sub>

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• ACFs are computed from  $I_{\text{scat}}(t)$  over  $T_0 = 60 \,\text{s}$  sliding 26 windows with an overlap between two consecutive slots 27 of 70%.

- ACFs are computed from  $I_{\text{scat}}(t)$  over  $T_0 = 120 \,\text{s}$  sliding windows with an overlap of 70%.
- ACFs are computed from  $I_{\text{scat}}(t)$  over  $T_0 = 300 \,\text{s}$  sliding windows with an overlap of 70%.

This figure clearly shows the influence, on the distribution of relaxation times, of the duration  $T_0$  of the window over which the ACFs are computed. However, some characteristics are preserved. In particular the change in dynamics between the gelation phase and the gel phase. During the whole gelation phase, the dynamics evolves as a function of time. Regardless the time at which the scattered signal is analyzed, or the window over which the ACFs are computed, we always observe several relaxation times that are more and more widely distributed as the gelation process progresses. The overall dynamics slows down; the relaxation time with the largest amplitude increases exponentially with time. Once the system has turned into a gel phase, its dynamics changes. The system is non ergodic but does not seem to evolve much with time (at least not over 25 minutes); it is observed several relaxation processes between  $10^{-4}$ s and  $10^{-1}$ s, as well as a very long relaxation time ( $\sim 15 \, \mathrm{s}$ ), which is caught correctly only if the ACFs are computed over a large window ( $T_0 = 300 \,\mathrm{s}$ ). The fact that, in the sample, there are several relaxation times of non-negligible amplitudes, distributed over 2 to 3 decades in time, at the same observation window, most likely explains the observed stretched exponential shape of the ACFs.

Our results are consistent with the results of other groups on similar systems<sup>59,61</sup>. Nevertheless, we believe that the method we have developed and are using (both signal acquisition and Time-Laplace analysis) provides more information on the dynamics of the system during gelation and in the gel phase. Again, the purpose of these experiments is not to precisely study the dynamics of the processes associated with gelation, or that of the gel phase, and therefore, we will not go further in the discussion of our results.

#### C. Dynamics of a living cell nucleus

In this third example, we use the method to investigate the dynamics inside a living cell nucleus. This experiment is the reason why the method was originally developed (the combination of acquisition and signal processing). The first attempts to study the internal dynamics of a living cell nucleus using dynamic light scattering experiments date back about 10 years ago<sup>33–35</sup>. These first experiments showed that DLS could be useful to study these dynamics. Nonetheless for this approach to be truly effective, an effort was to be done to dispose of a signal processing of the scattering signal that takes into account the fact that a cell nucleus is an out-of-equilibrium system, with a very broad relaxation time distribution.

To perform these experiments, we use the experimental device that has been developed by Suissa *et al.*<sup>33–35</sup> to carry out these first attempts to investigate the internal dynamics of the nucleus of a living cell by means of DLS. The details of this setup are presented in the references<sup>33–35</sup>. A He-Ne laser

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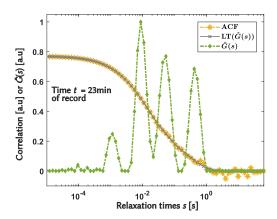


FIG. 9. Visualization of the data adjustment with the developed  $IL_{1179}^{7}$  algorithm for transition sol-gel experiment. The yellow curve (stars) shows the ACF computed from the data. The ACF was computed 23min24 after the beginning of the experiment with  $T_0 = 60$  s. The green curve (diamonds) exhibits the distribution of relaxation times  $\hat{G}(s)$  computed with the proposed method with  $\gamma = 1$ . The gray curve (crosses) is the ACF fit calculated from the result  $\hat{G}(s)$  using eq. (14).

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beam is focused with a microscope objective (Nikon, mag-1187 nification 20×, N.A. 0.45) onto a glass surface to which the 1188 cells have adhered. Before passing through the microscope 1189 objective, the laser beam is enlarged using a beam expander a beam expander  $(3\times)$  to obtain a beam waist smaller than the nucleus diameter. The laser beam waist diameter on the surface is then the then the surface is then the then the surface is then the surface is then the surface is the of the order of 3-4  $\mu$ m, hence less than the nucleus diame<sup>1193</sup> ter of the investigated cells. In order to enable us to visual 1-194 ize the adherent cells, the objective lens that focuses the laser 1195 beam is used to make a bright field transmission microscope. 1966 The sample is illuminated with a white light that propagates 1197 in the direction opposite the laser beam propagation. The image of the observed field is formed on a CCD camera (JAI199 CB-080 GE- Stemmer Imaging), thanks to a homemade ocular that provides additional magnification of the order of 1.6 ×200 -  $1.7\times$ , thus the final magnification of this homemade microscope (objective + "ocular") is of about 34×. By means of this system the adherent cells as well as the reflection spot of the laser beam on the surface can be observed and using translation stages to move the glass surface, the nucleus of 203 one cell can easily be brought into the beam waist. The lighton scattered by the nucleus is collected at an angle  $\theta$  which is scattered by the nucleus is collected at an angle  $\theta$ either 12°; 25° or 30°. For each angle, the image of the scat<sub>1206</sub> tering volume (i.e. the nucleus volume illuminated by the laser,  $\frac{1}{2}$ beam) is formed on the entrance face of a single mode optigon cal fiber (core diameter:  $5 \mu m$ , N.A.: 0.6) using a focusing a lens of focal length 7.5 cm. This system of collection of the 10 scattered light selects only a part of the nucleus volume that is 1211 illuminated; the magnification of the scattered light collection, optics is of the order of 1, thus the scattering volume is esti<sub>1213</sub> mated to be of about  $50 \,\mu\text{m}^3$ . An interferential filter (central<sub>214</sub> wavelength 630nm, 10nm bandpass) is placed right before 1515 the optical fiber to avoid polluting the detection of the scat\_[216] tered light with parasitic light.

The experiments were carried out on nuclei of HeLa line18

living cells<sup>63</sup>, in the G1 phase *i.e.* the first stage of the cell cycle). In order to keep the cells alive throughout the experiment duration and avoid any kind of contamination by bacteria and/or yeast, the cells immersed in their culture medium are introduced into the chamber described in the previous section. Prior to the experiment the stainless frame used to make the culture chamber is placed in a surfactant solution for two hours (4% of Decon 90) then brushed before being rinsed with both ultra-purified water (USF Elga) and ethanol. Finally this frame is dried with nitrogen and autoclaved. The 2 microscope slides are cleaned and autoclaved before being stuck on the stainless frame using silicon seals. Once the seals are dry, the cells and their culture medium are introduced into the chamber through the channels drilled in the section of the frame, which are then hermetically sealed so that the chamber inside does not have any contact with the external medium. The chamber is left horizontally in an incubator, at 37°C, for three hours, to let the cells adhere to the bottom glass surface. Then, the chamber is set vertically in a vice, with the glass surfaces perpendicular to the laser beam, the "bottom surface" set further from the objective lens. By means of a heating resistor set in the vise, we assure a temperature control within the culture chamber at  $\sim 37^{\circ}$  C. The culture medium is made of DMEM (Dubbelco Modified Eagle Medium), supplemented with 10% of foetal calf serum, 1% of L-Glutamine 1M and 2.5% of a 1M Hepes buffer to maintain physiological pH. These culture conditions (culture medium and temperature of about 37°C) allow us to cultivate the cells in these chambers under conditions approaching those of an incubator.

Figure 11 shows a scattering signal recorded as a function of time for the nucleus of a HELA cell in G1 phase ( $\delta t = 10^{-5} \, \text{s}$ ,  $\Delta T = 600 \, \text{s}$ ). This signal fluctuates a lot, with large and rapid variations of the scattered intensity. Figure 12 displays four different Time-Laplace analyses of this recording signal with:

- $T_0 = 10$  s sliding windows with no overlap;
- $T_0 = 60$  s sliding windows with an overlap of 70%;
- $T_0 = 120$  s sliding windows with an overlap of 70%;
- $T_0 = 300$  s sliding windows with an overlap of 70%.

As in the case of the sol-gel transition, being able to compute ACFs on temporal windows of variable size with an overlap between two consecutive windows that can be changed, allows us to probe the nucleus dynamics between  $\sim 10^{-5}\,\mathrm{s}$  and  $\sim 30\,\mathrm{s}$ . It can be seen three different dynamics that are clearly distinct: dynamics with relaxation times between  $\sim 10^{-2}\,\mathrm{s}$  and  $\sim 4\times 10^{-2}\,\mathrm{s}$ ; dynamics with relaxation times between  $\sim 5\times 10^{-1}\,\mathrm{s}$  and  $\sim 1.5\,\mathrm{s}$  and finally dynamics with relaxation times between  $\sim 10\,\mathrm{s}$  and  $\sim 30\,\mathrm{s}$ . These dynamics do not seem to change much over 10 minutes, however, if the same measurement is repeated one hour later, the two fastest dynamics appear to be different, likely due to a different biological activity within the nucleus.

Our results are consistent with the results of Suissa *et al.*  $^{33-35}$ . Again, our purpose in this article is not to study the dynamics of a living cell nucleus, and therefore, we will not

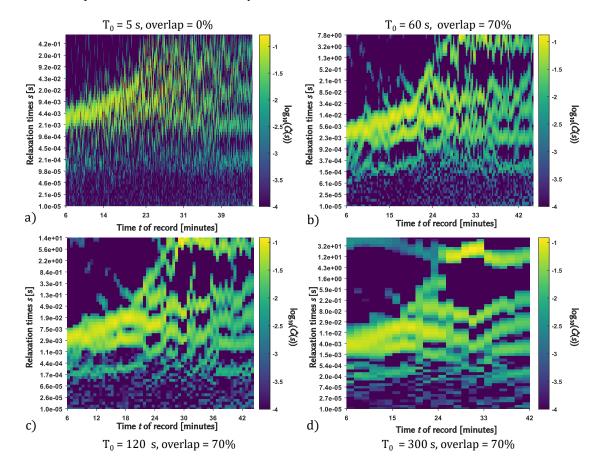


FIG. 10. Density maps of the relaxation times computed with different parameters for the transition sol-gel experiment: a)  $T_0 = 5$  s, overlapping rate = 0%, b)  $T_0 = 60$  s, overlapping rate = 70%, c)  $T_0 = 120$  s, overlapping rate = 70%, d)  $T_0 = 300$  s, overlapping rate = 70%. On the x-axis: Time t when the ACF has been computed (in minutes), the scale is logarithmic. On the y-axis: Relaxation times s, in seconds, estimated using the developed ILT algorithm, eq. (13); the scale in s is logarithmic. The color represents the density of the relaxation time, the scale is logarithmic.  $T_0 = 1$  for the four figures. Signal duration is 40 minutes.

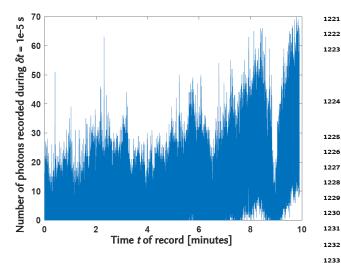


FIG. 11. Light scattering signal from a HeLa cell nucleus in  $G_{1234}^{1}$  phase. Signal recorded over 10 minutes at  $f_0 = 10^5$  Hz.

go further in the discussion of our results. Still, these results prove that we have got the tools (both signal acquisition and acquisition acquisition acquisition acquisition and acquisition acquis

Time-Laplace analysis) to investigate the evolution of the dynamics of a living cell nucleus as a function of its biological activity.

#### VI. CONCLUSION

In this article, we present a new method to analyze DLS signals from out-of-equilibrium systems. This method, we call Time-Laplace analysis, is based on a regularized ILT of sliding ACFs of the scattered signal, computed upon estimation windows that can be modulated. This approach is then multiscale, systematic and more robust than the classical CONTIN algorithm.

Here, we discuss the principles of the method, and we describe the signal processing techniques, as well as the experimental set-up, that we develop in order to use dynamic light scattering in general situations. On different out-of-equilibrium systems, we prove that this method enables us to extract the non-stationary distribution of relaxation times from DLS experiments. The main limitation of this multiscale approach is the necessity to compute the ILT over windows with

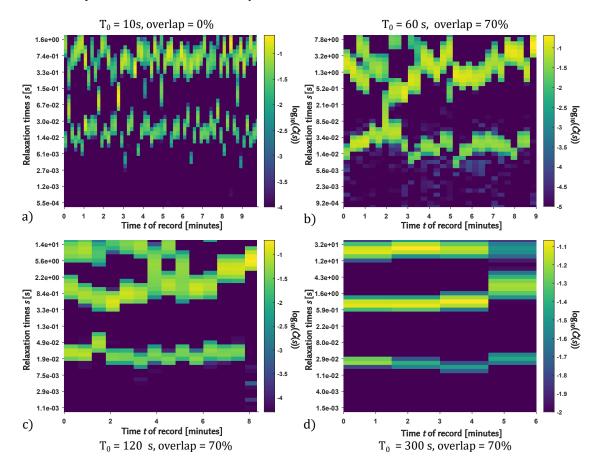


FIG. 12. Density maps of the relaxation times computed with different parameters for the DLS experiment on living Hela cells: a)  $T_0 = 10$  s, overlapping rate = 0%, b)  $T_0 = 60$  s, overlapping rate = 70%, c)  $T_0 = 120$  s, overlapping rate = 70%, d)  $T_0 = 300$  s, overlapping rate = 70%. On the x-axis: Time t when the ACF has been computed (in minutes), the scale is logarithmic. On the y-axis: Relaxation times s in seconds computed with the developed ILT, eq. (13), the scale is logarithmic. The color represents the density of the relaxation time, the scale is logarithmic.  $\gamma = 1$  for the four figures. Signal duration is 10 minutes.

different time length  $T_0$ , even if we think that an all-in-one computation is possible. A minor limitation is the difficulty tensa treat ACF decays faster than a simple exponential. Neverther less, a possibility is to use Gaussian transforms as mentioned in the article of Andrew *et al.* 43

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Therefore, we would like to stress out that the obtained re<sup>1.267</sup> sults clearly show that DLS experiments capture all the rich<sup>1.268</sup> ness and complexity of the dynamics of various processes and systems, and that the Time-Laplace method we have developed allows to extract them. Henceforth, the proposed approach can prove to be very useful for the study of the dy<sub>1.270</sub> namics of many out-of-equilibrium "soft matter" systems. We claim, indeed, that this signal treatment can be adapted to numerous DLS experiments dealing with non-equilibrium of non-ergodic systems. In our case we aim at applying this method to investigate the internal dynamics of living cell nucleus. Moreover, this Time-Laplace method could be applied as well in XPCS, but also to all ACFs that could reasonably be decomposed as a weighted sum of exponential decays.

Regarding the signal processing aspect, the next step is to to use more efficient algorithms to reduce the numerical expensive cost raised by resolution of inverse problems. Further 1276

more, S. Provencher (more recently Andrew *et al.*<sup>43</sup>) brought the idea<sup>64</sup> in 1996 to find the distribution of relaxation times for stationary systems by solving an inverse problem regarding the decay times and the wave vectors *i.e.* in a 2D-space. In the same spirit, we could imagine figuring out the distribution of relaxation times according to the decay times but also to the times of recording. This 2D-problem would bring a smoother solution that would reduce noise in our distributions.

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#### DATA AVAILABILITY STATEMENT

Data are available upon request to the corresponding author.

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