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Parikh Automata over Infinite Words

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Abstract

Parikh automata extend finite automata by counters that can be tested for membership in a semilinear set, but only at the end of a run, thereby preserving many of the desirable algorithmic properties of finite automata. Here, we study the extension of the classical framework onto infinite inputs: We introduce reachability, safety, Büchi, and co-Büchi Parikh automata on infinite words and study expressiveness, closure properties, and the complexity of verification problems.

We show that almost all classes of automata have pairwise incomparable expressiveness, both in the deterministic and the nondeterministic case; a result that sharply contrasts with the well-known hierarchy in the ω -regular setting. Furthermore, emptiness is shown decidable for Parikh automata with reachability or Büchi acceptance, but undecidable for safety and co-Büchi acceptance. Most importantly, we show decidability of model checking with specifications given by deterministic Parikh automata with safety or co-Büchi acceptance, but also undecidability for all other types of automata. Finally, solving games is undecidable for all types.

1 Introduction

While finite-state automata are the keystone of automata-theoretic verification, they are not expressive enough to deal with the many non-regular aspects of realistic verification problems. Various extensions of finite automata have emerged over the years, to allow for the specification of context-free properties and beyond, as well as the modelling of timed and quantitative aspects of systems. Among these extensions, Parikh automata, introduced by Klaedtke and Rueß [18], consist of finite automata, augmented with counters that can only be incremented. A Parikh automaton only accepts a word if the final counter-configuration is within a semilinear set specified by the automaton. As the counters do not interfere with the control flow of the automaton, that is, counter values do not affect whether transitions are enabled, they allow for mild quantitative computations without the full power of vector addition systems or other more powerful models.

For example, the nonregular language L of words that have more a 's than b 's is accepted by a Parikh automaton obtained from the one-state DFA accepting $\{a, b\}^*$ by equipping it with two counters, one counting the a 's in the input, the other counting the b 's, and a semilinear set ensuring that the first counter is

larger than the second one. With a similar approach, one can construct a Parikh automaton accepting the noncontextfree language of words that have more a 's than b 's and more a 's than c 's.

Klaedtke and Rueß [18] showed Parikh automata to be expressively equivalent to a quantitative version of existential WMSO that allows for reasoning about set cardinalities. Their expressiveness also coincides with that of reversal-bounded counter machines [18], in which counters can go from decrementing to incrementing only a bounded number of times, but in which counters affect control flow [17]. The (weakly) unambiguous restriction of Parikh automata, that is, those that have at most one accepting run, on the other hand, coincide with unambiguous reversal-bounded counter machines [2]. Parikh automata are also expressively equivalent to weighted finite automata over the groups $(\mathbb{Z}^k, +, 0)$ [9, 20] for $k \geq 1$. This shows that Parikh automata accept a natural class of quantitative specifications.

Despite their expressiveness, Parikh automata retain some decidability: nonemptiness, in particular, is NP-complete [12]. For weakly unambiguous Parikh automata, inclusion [5] and regular separability [6] are decidable as well. Figuera and Libkin [12] also argued that this model is well-suited for querying graph databases, while mitigating some of the complexity issues related with more expressive query languages. Further, they have been used in the model checking of transducer properties [14].

As Parikh automata have been established as a robust and useful model, many variants thereof exist: pushdown (visibly [8] and otherwise [22]), two-way with [8] and without stack [13], unambiguous [4], and weakly unambiguous [2] Parikh automata, to name a few. Despite this attention, so far, some more elementary questions have remained unanswered. For instance, despite Klaedtke and Rueß's suggestion in [18] that the model could be extended to infinite words, we are not aware of previous work on ω -Parikh automata.

Yet, specifications over infinite words are a crucial part of the modern verification landscape. Indeed, programs, especially safety-critical ones, are often expected to run continuously, possibly in interaction with an environment. Then, executions are better described by infinite words, and accordingly, automata over infinite, rather than finite, words are appropriate for capturing specifications.

This is the starting point of our contribution: we extend Parikh automata to infinite inputs, and consider reachability, safety, Büchi, and co-Büchi acceptance conditions. We observe that when it comes to reachability and Büchi, there are two possible definitions: an asynchronous one, that just requires both an accepting state and the semilinear set to be reached (once or infinitely often) by the run, but not necessarily at the same time, and a synchronous one, which requires both to be reached (once or infinitely often) simultaneously.

Parikh automata on infinite words accept, for example, the language of infinite words with some prefix in L (reachability acceptance), the language of infinite words with all nonempty prefixes in L (safety acceptance), the language of infinite words with infinitely many prefixes in L (Büchi acceptance), and the language of infinite words with and almost all prefixes in L (co-Büchi acceptance).

We establish that, both for reachability and Büchi acceptance, both the synchronous and the asynchronous variant are linearly equivalent in the presence of nondeterminism, but not for deterministic automata. Hence, by considering all acceptance conditions and (non)determinism, we end up with ten different classes of automata. We show that almost all of these classes have pairwise incomparable expressiveness, which is in sharp contrast to the well-known hierarchies in the ω -regular case. Furthermore, we establish an almost complete picture of the Boolean closure properties of these ten classes of automata. Most notably, they lack closure under negation, even for nondeterministic Büchi Parikh automata. Again, this result should be contrasted with the ω -regular case, where nondeterministic Büchi automata are closed under negation [21].

We then study the complexity of the most important verification problems, e.g., nonemptiness, universality, model checking, and solving games. We show that nonemptiness is undecidable for deterministic safety and co-Büchi Parikh automata. However, perhaps surprisingly, we also show that nonemptiness is decidable, in fact NP-complete, for reachability, and Büchi Parikh automata, both for the synchronous and asynchronous versions. Strikingly, for Parikh automata, the Büchi acceptance condition is algorithmically simpler than the safety one (recall that their expressiveness is pairwise incomparable).

Next, we consider model checking, arguably the most successful application of automata theory in the field of automated verification. Model checking asks whether a given finite-state system satisfies a given specification. Here, we consider quantitative specifications given by Parikh automata. Model checking is decidable for specifications given by deterministic Parikh automata with safety or co-Büchi acceptance. On

the other hand, the problem is undecidable for all other classes of automata.

The positive results imply that one can model-check an arbiter serving requests from two clients against specifications like “the accumulated waiting time between requests and responses of client 1 is always at most twice the accumulated waiting time for client 2 and vice versa” and “the difference between the number of responses for client 1 and the number of responses for client 2 is from some point onward bounded by 100”. Note that both properties are not ω -regular.

Finally, we consider solving games with winning conditions expressed by Parikh automata. Zero-sum two-player games are a key formalism used to model the interaction of programs with an uncontrollable environment. In particular, they are at the heart of solving synthesis problems, in which, rather than verifying the correctness of an existing program, we are interested in generating a program that is correct by construction, from its specifications. In these games, the specification corresponds to the winning condition: one player tries to build a word (i.e., behaviour) that is in the specification, while the other tries to prevent this. As with model checking, using Parikh automata to capture the specification would enable these well-understood game-based techniques to be extended to mildly quantitative specifications. However, we show that games with winning conditions specified by Parikh automata are undecidable for all acceptance conditions we consider.

All proofs omitted due to space restrictions can be found in the appendix.

2 Definitions

An alphabet is a finite nonempty set Σ of letters. As usual, ε denotes the empty word, Σ^* denotes the set of finite words over Σ , Σ^+ denotes the set of finite nonempty words over Σ , and Σ^ω denotes the set of infinite words over Σ . The length of a finite word w is denoted by $|w|$ and, for notational convenience, we define $|w| = \infty$ for infinite words w .

Finally, $|w|_a$ denotes the number of occurrences of the letter a in a finite word w . Let $a, b \in \Sigma$. A word $w \in \Sigma^*$ is (a, b) -balanced, if $|w|_a = |w|_b$, otherwise it is (a, b) -unbalanced. Note that the empty word is (a, b) -balanced.

Semilinear Sets We denote the set of nonnegative integers by \mathbb{N} . Given vectors $\vec{v} = (v_0, \dots, v_{d-1}) \in \mathbb{N}^d$ and $\vec{v}' = (v'_0, \dots, v'_{d'-1}) \in \mathbb{N}^{d'}$, we define $\vec{v} \cdot \vec{v}' = (v_0, \dots, v_{d-1}, v'_0, \dots, v'_{d'-1}) \in \mathbb{N}^{d+d'}$. We lift the concatenation of vectors to sets $D \subseteq \mathbb{N}^d$ and $D' \subseteq \mathbb{N}^{d'}$ via $D \cdot D' = \{\vec{v} \cdot \vec{v}' \mid \vec{v} \in D \text{ and } \vec{v}' \in D'\}$.

Let $d \geq 1$. A set $C \subseteq \mathbb{N}^d$ is *linear*, if there are vectors $\vec{v}_0, \dots, \vec{v}_k \in \mathbb{N}^d$ such that

$$C = \left\{ \vec{v}_0 + \sum_{i=1}^k c_i \vec{v}_i \mid c_i \in \mathbb{N} \text{ for } i = 1, \dots, k \right\}.$$

Furthermore, a subset of \mathbb{N}^d is *semilinear*, if it is a finite union of linear sets.

Proposition 1 ([16]). *If $C, C' \subseteq \mathbb{N}^d$ are semilinear, then so are $C \cup C'$, $C \cap C'$, $\mathbb{N}^d \setminus C$, as well as $\mathbb{N}^{d'} \cdot C$ and $C \cdot \mathbb{N}^{d'}$ for every $d' \geq 1$.*

Finite Automata A (nondeterministic) finite automaton (NFA) $\mathcal{A} = (Q, \Sigma, q_I, \Delta, F)$ over Σ consists of a finite set Q of states containing the initial state q_I , an alphabet Σ , a transition relation $\Delta \subseteq Q \times \Sigma \times Q$, and a set $F \subseteq Q$ of accepting states. The NFA is deterministic (i.e., a DFA) if for every state $q \in Q$ and every letter $a \in \Sigma$, there is at most one $q' \in Q$ such that (q, a, q') is a transition of \mathcal{A} . A run of \mathcal{A} is a (possibly empty) sequence $(q_0, w_0, q_1)(q_1, w_1, q_2) \cdots (q_{n-1}, w_{n-1}, q_n)$ of transitions with $q_0 = q_I$. It processes the word $w_0 w_1 \cdots w_{n-1} \in \Sigma^*$. The run is *accepting* if it is either empty and the initial state is accepting or if it is nonempty and q_n is accepting. The language $L(\mathcal{A})$ of \mathcal{A} contains all finite words $w \in \Sigma^*$ such that \mathcal{A} has an accepting run processing w .

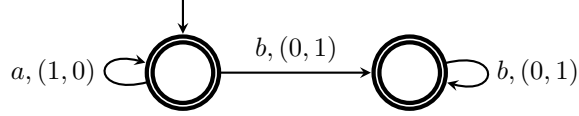


Figure 1: The automaton for Example 1.

Parikh Automata Let Σ be an alphabet, $d \geq 1$, and D a finite subset of \mathbb{N}^d . Furthermore, let $w = (a_0, \vec{v}_0) \cdots (a_{n-1}, \vec{v}_{n-1})$ be a word over $\Sigma \times D$. The Σ -projection of w is $p_\Sigma(w) = a_0 \cdots a_{n-1} \in \Sigma^*$ and its *extended Parikh image* is $\Phi_e(w) = \sum_{j=0}^{n-1} \vec{v}_j \in \mathbb{N}^d$ with the convention $\Phi_e(\varepsilon) = \vec{0}$, where $\vec{0}$ is the d -dimensional zero vector.

A *Parikh automaton* (PA) is a pair (\mathcal{A}, C) such that \mathcal{A} is an NFA over $\Sigma \times D$ for some input alphabet Σ and some finite $D \subseteq \mathbb{N}^d$ for some $d \geq 1$, and $C \subseteq \mathbb{N}^d$ is semilinear. The language of (\mathcal{A}, C) consists of the Σ -projections of words $w \in L(\mathcal{A})$ whose extended Parikh image is in C , i.e.,

$$L(\mathcal{A}, C) = \{p_\Sigma(w) \mid w \in L(\mathcal{A}) \text{ with } \Phi_e(w) \in C\}.$$

The automaton (\mathcal{A}, C) is deterministic, if for every state q of \mathcal{A} and every $a \in \Sigma$, there is at most one pair $(q', \vec{v}) \in Q \times D$ such that $(q, (a, \vec{v}), q')$ is a transition of \mathcal{A} . Note that this definition does *not* coincide with \mathcal{A} being deterministic: As mentioned above, \mathcal{A} accepts words over $\Sigma \times D$ while (\mathcal{A}, C) accepts words over Σ . Therefore, determinism is defined with respect to Σ only.

Note that the above definition of $L(\mathcal{A}, C)$ coincides with the following alternative definition via accepting runs: A run ρ of (\mathcal{A}, C) is a run

$$\rho = (q_0, (a_0, \vec{v}_0), q_1)(q_1, (a_1, \vec{v}_1), q_2) \cdots (q_{n-1}, (a_{n-1}, \vec{v}_{n-1}), q_n)$$

of \mathcal{A} . We say that ρ *processes* the word $a_0 a_1 \cdots a_{n-1} \in \Sigma^*$, i.e., the \vec{v}_j are ignored, and that ρ 's extended Parikh image is $\sum_{j=0}^{n-1} \vec{v}_j$. The run is accepting, if it is either empty and both the initial state of \mathcal{A} is accepting and the zero vector (the extended Parikh image of the empty run) is in C , or if it is nonempty, q_n is accepting, and ρ 's extended Parikh image is in C . Finally, (\mathcal{A}, C) accepts $w \in \Sigma^*$ if it has an accepting run processing w .

Example 1. Consider the deterministic PA (\mathcal{A}, C) with \mathcal{A} in Figure 1 and $C = \{(n, n) \mid n \in \mathbb{N}\} \cup \{(n, 2n) \mid n \in \mathbb{N}\}$. It accepts the language $\{a^n b^n \mid n \in \mathbb{N}\} \cup \{a^n b^{2n} \mid n \in \mathbb{N}\}$.

A cycle is a nonempty finite run infix

$$(q_0, w_0, q_1)(q_1, w_1, q_2) \cdots (q_{n-1}, w_{n-1}, q_n)(q_n, w_n, q_0)$$

starting and ending in the same state and such that the q_j are pairwise different. Note that every run infix containing at least n transitions contains a cycle, where n is the number of states of the automaton. Many of our proofs rely on the following shifting argument, which has been used before to establish inexpressibility results for Parikh automata [3].

Remark 1. Let $\rho_0 \rho_1 \rho_2 \rho_3$ be a run of a PA such that ρ_1 and ρ_3 are cycles starting in the same state. Then, $\Phi_e(\rho_0 \rho_1 \rho_2 \rho_3) = \Phi_e(\rho_0 \rho_2 \rho_1 \rho_3) = \Phi_e(\rho_0 \rho_1 \rho_3 \rho_2)$. Furthermore, all three runs end in the same state and visit the same set of states (but maybe in different orders).

3 Parikh Automata over Infinite Words

In this section, we introduce Parikh automata over infinite words by lifting safety, reachability, Büchi, and co-Büchi acceptance from finite automata to Parikh automata. Recall that a Parikh automaton on finite words accepts if the last state of the run is accepting and the extended Parikh image of the run is in the

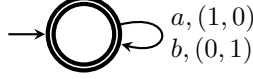


Figure 2: The automaton for Example 2.

semilinear set, i.e., both events are synchronized. For reachability and Büchi acceptance it is natural to both consider a synchronous and an asynchronous variant while for safety and co-Büchi there is only a synchronous variant.

All these automata have the same format as Parikh automata on finite words, but are now processing infinite words. Formally, consider (\mathcal{A}, C) with $\mathcal{A} = (Q, \Sigma \times D, q_I, \Delta, F)$. Fix an infinite run $(q_0, w_0, q_1)(q_1, w_1, q_2)(q_2, w_2, q_3) \cdots$ of \mathcal{A} with $q_0 = q_I$ (recall that each w_j is in $\Sigma \times D$), which we say processes $p_\Sigma(w_0 w_1 w_2 \cdots)$.

- The run is *safety accepting* if $q_n \in F$ and $\Phi_e(w_0 \cdots w_{n-1}) \in C$ for all $n \geq 0$.
- The run is *synchronous reachability accepting* if $q_n \in F$ and $\Phi_e(w_0 \cdots w_{n-1}) \in C$ for some $n \geq 0$.
- The run is *asynchronous reachability accepting* if $q_n \in F$ for some $n \geq 0$ and $\Phi_e(w_0 \cdots w_{n'-1}) \in C$ for some $n' \geq 0$.
- The run is *synchronous Büchi accepting* if $q_n \in F$ and $\Phi_e(w_0 \cdots w_{n-1}) \in C$ for infinitely many $n \geq 0$.
- The run is *asynchronous Büchi accepting* if $q_n \in F$ for infinitely many $n \geq 0$ and $\Phi_e(w_0 \cdots w_{n'-1}) \in C$ for infinitely many $n' \geq 0$.
- The run is *co-Büchi accepting* if there is an n_0 such that $q_n \in F$ and $\Phi_e(w_0 \cdots w_{n-1}) \in C$ for every $n \geq n_0$.

Note that we do not distinguish between synchronous and asynchronous co-Büchi acceptance, as these definitions are equivalent. Also, note that all our definitions are conjunctive in the sense that acceptance requires visits to accepting states *and* extended Parikh images in C . Thus, e.g., reachability and safety are not dual on a syntactic level. Nevertheless, we later prove dualities on a semantic level.

Similarly, one can easily show that a disjunctive definition is equivalent to our conjunctive one: One can reflect in the extended Parikh image of a run prefix whether it ends in an accepting state (see the proof of Theorem 1). So, any given Parikh automaton (\mathcal{A}, C) (with disjunctive or conjunctive acceptance) can be turned into another one (\mathcal{A}', C') capturing acceptance in (\mathcal{A}, C) by Parikh images only. So, with empty (full) set of accepting states and C' mimicking disjunction (conjunction), it is equivalent to the original automaton with disjunctive (conjunctive) acceptance.

Now, the language $L_S(\mathcal{A}, C)$ of a safety Parikh automaton (SPA) (\mathcal{A}, C) contains those words $w \in \Sigma^\omega$ such that (\mathcal{A}, C) has a safety accepting run processing w . The languages $L_R^s(\mathcal{A}, C)$ and $L_R^a(\mathcal{A}, C)$ of synchronous reachability Parikh automata (sRPA) and asynchronous reachability Parikh automata (aRPA), $L_B^s(\mathcal{A}, C)$ and $L_B^a(\mathcal{A}, C)$ of synchronous Büchi Parikh automata (sBPA) and asynchronous Büchi Parikh automata (aBPA), and $L_C(\mathcal{A}, C)$ of co-Büchi Parikh automata (CPA) are defined similarly. Determinism for all types of automata is defined as for Parikh automata on finite words. Unless explicitly stated otherwise, every automaton is assumed to be nondeterministic.

Example 2. Let \mathcal{A} be the DFA shown in Figure 2 and let $C = \{(n, n) \mid n \in \mathbb{N}\}$ and $\overline{C} = \{(n, n') \mid n \neq n'\}$.

Recall that a finite word w is (a, b) -balanced if $|w|_a = |w|_b$, i.e., the number of a 's and b 's in w is equal. The empty word is (a, b) -balanced and every odd-length word over $\{a, b\}$ is (a, b) -unbalanced.

1. When interpreting (\mathcal{A}, C) as a PA, it accepts the language of (a, b) -balanced words, when interpreting $(\mathcal{A}, \overline{C})$ as a PA, it accepts the language of (a, b) -unbalanced words.
2. When interpreting (\mathcal{A}, C) as an aRPA or sRPA, it accepts the language of infinite words that have an (a, b) -balanced prefix, when interpreting $(\mathcal{A}, \overline{C})$ as an aRPA or sRPA, it accepts the language of infinite

words that have an (a, b) -unbalanced prefix. Note that both languages are universal, as the empty prefix is always (a, b) -balanced and every odd-length prefix is (a, b) -unbalanced.

3. When interpreting (\mathcal{A}, C) as an SPA, it accepts the language of infinite words that have only (a, b) -balanced prefixes, when interpreting $(\mathcal{A}, \overline{C})$ as an SPA, it accepts the language of infinite words that have only (a, b) -unbalanced prefixes. Here, both languages are empty, which follows from the same arguments as universality in the previous case.
4. When interpreting (\mathcal{A}, C) as an aBPA or sBPA, it accepts the language of infinite words with infinitely many (a, b) -balanced prefixes, when interpreting $(\mathcal{A}, \overline{C})$ as an aBPA or sBPA, it accepts the language of infinite words with infinitely many (a, b) -unbalanced prefixes. The latter language is universal, as every odd-length prefix is unbalanced.
5. When interpreting (\mathcal{A}, C) as a CPA, it accepts the language of infinite words such that almost all prefixes are (a, b) -balanced, when interpreting $(\mathcal{A}, \overline{C})$ as a CPA, it accepts the language of infinite words such that almost all prefixes are (a, b) -unbalanced. Again, the former language is empty.

Let (\mathcal{A}, C) be a Parikh automaton. To simplify our language, we say that a run prefix is an F -prefix if it ends in an accepting state of \mathcal{A} , a C -prefix if its extended Parikh image is in C , and an FC -prefix if it is both an F -prefix and a C -prefix. Note that both asynchronous acceptance conditions are defined in terms of the existence of F -prefixes and C -prefixes and all other acceptance conditions in terms of the existence of FC -prefixes.

Remark 2. *RPA (SPA, BPA, CPA) are strictly more expressive than ω -regular reachability (safety, Büchi, co-Büchi) automata. Inclusion follows by definition while strictness is witnessed by the languages presented in Example 2.*

4 Expressiveness

In this section, we study the expressiveness of the various types of Parikh automata on infinite words introduced above, by comparing synchronous and asynchronous variants, deterministic and nondeterministic variants, and the different acceptance conditions.

Remark 3. *In this, and only this, section, we consider only reachability Parikh automata that are complete in the following sense: For every state q and every letter a there is a vector \vec{v} and a state q' such that $(q, (a, \vec{v}), q')$ is a transition of \mathcal{A} , i.e., every letter can be processed from every state. Without this requirement, one can express safety conditions by incompleteness, while we want to study the expressiveness of “pure” reachability automata.*

Safety, Büchi, and co-Büchi automata can be assumed, without loss of generality, to be complete, as one can always add a nonaccepting sink to complete such an automaton without modifying the accepted language.

We begin our study by comparing the synchronous and asynchronous variants of reachability and Büchi automata. All transformations proving the following inclusions are effective and lead to a linear increase in the number of states and a constant increase in the dimension of the semilinear sets.

Theorem 1.

1. *aRPA and sRPA are equally expressive.*
2. *Deterministic aRPA are strictly more expressive than deterministic sRPA.*
3. *aBPA and sBPA are equally expressive.*
4. *Deterministic aBPA are strictly more expressive than deterministic sBPA.*

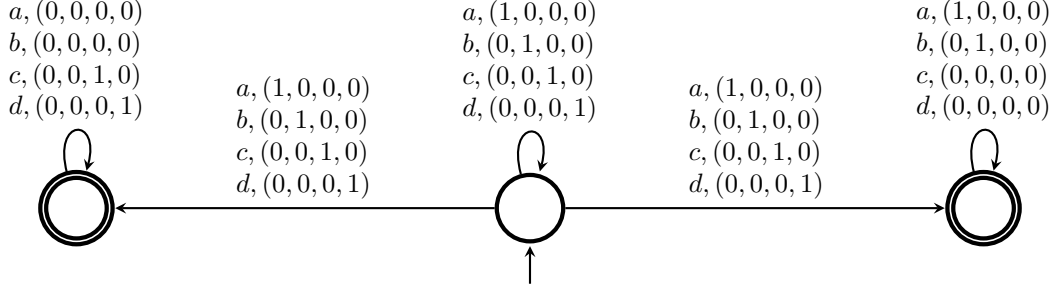


Figure 3: The automaton for Lemma 2.1.

Due to the equivalence of synchronous and asynchronous (nondeterministic) reachability Parikh automata, we will drop the qualifiers whenever possible and just speak of reachability Parikh automata (RPA). We do the same for (nondeterministic) Büchi Parikh automata (BPA).

Next, we compare the deterministic and nondeterministic variant for each acceptance condition. Note that all separations are as strong as possible, i.e., for reachability and Büchi we consider deterministic asynchronous automata, which are more expressive than their asynchronous counterpart (see Theorem 1).

Theorem 2.

1. *Nondeterministic RPA are strictly more expressive than deterministic aRPA.*
2. *Nondeterministic SPA are strictly more expressive than deterministic SPA.*
3. *Nondeterministic BPA are strictly more expressive than deterministic aBPA.*
4. *Nondeterministic CPA are strictly more expressive than deterministic CPA.*

Proof. 1.) Consider the language D of infinite words over $\{a, b, c, d\}$ that have prefixes w_1 and w_2 such that $|w_1|_a = |w_1|_b > 0$ and $|w_2|_c = |w_2|_d > 0$. Note that $|w_1|_a = |w_1|_b > 0$ is a stronger requirement than w_1 being nonempty and (a, b) -balanced: the word c is nonempty and (a, b) -balanced, but $|c|_a = |c|_b = 0$. It is accepted by the nondeterministic sRPA (\mathcal{A}, C) with \mathcal{A} shown in Figure 3 and $C = \{(n_0, n_1, n_2, n_3) \mid n_0 = n_1 > 0 \text{ and } n_2 = n_3 > 0\}$. Note that \mathcal{A} uses nondeterminism to freeze one pair of counters (thereby picking w_1 or w_2).

Now, towards a contradiction, assume that D is accepted by some deterministic aRPA (\mathcal{A}, C) , say with n states. Now, consider $w = a(a^n b^n)^{n+1} (c^n d^n)^\omega \notin L$. Due to completeness, \mathcal{A} has a run ρ processing w . Every infix of ρ processing b^n contains a cycle. Hence, there are two such cycles that start in the same state. Let ρ_s be the run obtained by shifting the second cycle to the end of the first cycle, and let w_s be the word processed by ρ_s . Shifting the nonempty cycle creates a prefix w_1 with $|w_1|_a = |w_1|_b > 0$. Furthermore, as the shifting is restricted to the prefix containing the a 's and b 's, w_s also has a prefix w_2 with $|w_2|_c = |w_2|_d > 0$, e.g., the one ending with processing the first $c^n d^n$ infix. Hence, $w_s \in D$ and ρ_s is accepting due to determinism.

We show that the run ρ is rejecting, yielding the desired contradiction. First, let us remark that exactly the same states occur in ρ and ρ_s . Hence, as ρ_s contains an accepting state, so does ρ . Also, there is a C -prefix ρ' of ρ_s .

First, we consider the case where the prefix ρ' has length at most $(n + 1)2n + 1$, i.e., it processes a word containing only a 's and b 's. Each run infix of ρ_s that processes c^n contains a cycle. We pump this cycle once in the first such infix. This yields an accepting run, as the C -prefix ρ' is preserved (it appears before the pumping position) and the set of states occurring is unchanged by the pumping. However, the word processed by the resulting run does not even have a (c, d) -balanced prefix, as the first c -block now has more than n c 's. So, we have derived the desired contradiction in this case.

Now, consider the case where the C -prefix ρ' of ρ_s has length greater than $(n + 1)2n + 1$, i.e., it processes at least one c . Then, as the shifting used to obtain ρ_s from ρ is confined to the prefix of length $(n + 1)2n + 1$,

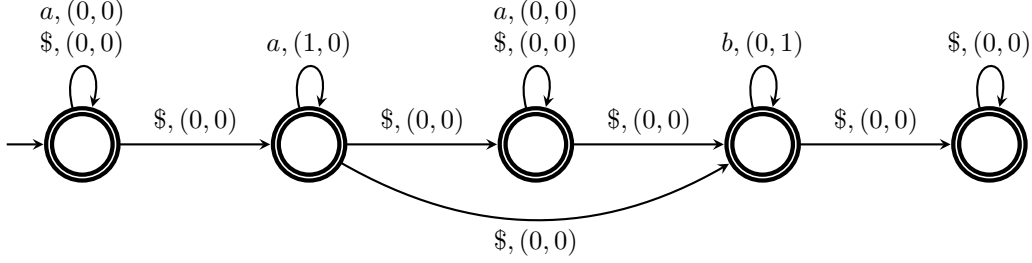


Figure 4: The automaton for Lemma 2.2.

we conclude that the prefix of ρ of length $|\rho'|$ has the same extended Parikh image as ρ' . Hence, ρ is also accepting, yielding again the desired contradiction.

2.) Next, we consider safety acceptance. Let $L = L' \cup \{a, \$\}^\omega$ with

$$L' = \{a^{n_0} \$ a^{n_1} \$ \dots \$ a^{n_k} \$ b^n \$^\omega \mid k > 0 \text{ and } n < n_i \text{ for some } 0 \leq i \leq k\},$$

which is accepted by the SPA (\mathcal{A}, C) with \mathcal{A} in Figure 4 and $C = \{(n, n') \mid n > n'\} \cup \{(0, 0)\}$. Note that adding $\{a, \$\}^\omega$ ensures that L can be accepted by a safety automaton. The language L' itself cannot be accepted by a safety automaton, as it requires the occurrence of a $\$$ after an unbounded number of a 's (stated differently, it is not a closed set in the Cantor topology).

Towards a contradiction, assume that L is accepted by a deterministic SPA (\mathcal{A}, C) , say with n states. Due to Remark 3, we can assume the automaton to be complete. Now, consider the word $w = (a^n \$)^{n+1} b^n \$^\omega \notin L$. Due to completeness, the automaton has a (unique) run ρ processing w , which is rejecting. Hence, there is a prefix ρ' of ρ that either ends in a nonaccepting state or whose extended Parikh image is not in C .

First, we show that ρ' has at least length $(n+1)^2 + 1$. If not, then ρ' does not process a single b , which means we can extend it with a suffix processing a^ω (recall that \mathcal{A} is complete). The resulting run is rejecting, due to the prefix ρ' , but processes a word in $(a^* \$)^* a^\omega \subseteq L$, a contradiction.

Every infix of ρ processing an infix of the form a^n contains a cycle. Hence, there are two such cycles starting in the same state. By shifting the first of these cycles in front of the second one we obtain a new run ρ_s processing a word of the form $(a^n \$)^{n_0} a^{n-k} \$ (a^n \$)^{n_1} a^{n+k} \$ (a^n \$)^{n_2} b^n \$^\omega$, where $k > 0$ is the length of the first cycle. This word is in L , but the unique run ρ_s of (\mathcal{A}, C) processing it is rejecting: its prefix of length $|\rho'|$ ends in the same state as ρ' and has the same extended Parikh image as ρ' , as the shifting is restricted to this prefix. This again yields a contradiction.

3. and 4.) To conclude, we simultaneously consider Büchi and co-Büchi acceptance. Let B be the language of infinite words that have a nonempty (a, b) -balanced prefix. The deterministic sRPA (\mathcal{A}, C) with \mathcal{A} as in Figure 2 and $C = \{(n, n) \mid n > 0\}$ accepts B . In Theorem 3, we show that every RPA can be turned into an equivalent BPA and into an equivalent CPA. Thus, it remains to show that B is not accepted by the deterministic variants.

Towards a contradiction, assume that B is accepted by a deterministic BPA or by a deterministic CPA, say with n states. Due to Remark 3, we can assume the automaton to be complete.

Consider $w = a(a^n b^n)^\omega \notin L$, i.e., (\mathcal{A}, C) has a nonaccepting run ρ processing w . Here, we consider cycles in ρ that process the b^n -infixes, starting in the same state. We shift one of them forward, and obtain a run ρ_s processing a word with a nonempty (a, b) -balanced prefix, i.e., the word processed by ρ_s is in B . However, its (unique due to determinism) run ρ_s is not accepting, as both asynchronous and synchronous Büchi nonacceptance as well as co-Büchi nonacceptance are preserved under shifting a single cycle. \square

After having separated deterministic and nondeterministic automata for all acceptance conditions, we now consider inclusions and separations between the different acceptance conditions. Here, the picture is notably different than in the classical ω -regular setting, as almost all classes can be separated.

Theorem 3. *Every RPA can be turned into an equivalent BPA and into an equivalent CPA. Open Problem 1 is open. All other automata types are pairwise incomparable.*

Our separations between the different acceptance conditions are as strong as possible, e.g., when we show that not every RPA has an equivalent SPA, we exhibit a *deterministic* sRPA (the weakest class of RPA) whose language is not accepted by any nondeterministic SPA (the strongest class of SPA). The same is true for all other separations.

We leave one (potential) separation for further work.

Open Problem 1. *Does every BPA have an equivalent CPA?*

Let us just mention that, while the general problem is left open, a stronger question can be shown to be false using results obtained in the next section: there is an (even deterministic) sBPA that does not have an equivalent *deterministic* CPA (but might have an equivalent nondeterministic CPA). In the proof of Theorem 6, we show that the language of words having infinitely many (a, b) -balanced prefixes is accepted by a deterministic sBPA. Assuming that the language is accepted by a deterministic CPA yields a contradiction due to its complement not being accepted by any BPA (see the proof of Theorem 3) and due to Theorem 4.6.

5 Closure Properties

In this section, we study the closure properties of Parikh automata on infinite words. We begin by showing that, for deterministic synchronous automata, reachability and safety acceptance as well as Büchi and co-Büchi acceptance are dual, although they are not syntactically dual. On the other hand, deterministic asynchronous automata can still be complemented, however only into nondeterministic automata.

Theorem 4.

1. *Let (\mathcal{A}, C) be a deterministic sRPA. The complement of $L_R^s(\mathcal{A}, C)$ is accepted by a deterministic SPA.*
2. *Let (\mathcal{A}, C) be a deterministic aRPA. The complement of $L_R^a(\mathcal{A}, C)$ is accepted by an SPA, but not necessarily by a deterministic SPA.*
3. *Let (\mathcal{A}, C) be a deterministic SPA. The complement of $L_S(\mathcal{A}, C)$ is accepted by a deterministic sRPA.*
4. *Let (\mathcal{A}, C) be a deterministic sBPA. The complement of $L_B^s(\mathcal{A}, C)$ is accepted by a deterministic CPA.*
5. *Let (\mathcal{A}, C) be a deterministic aBPA. The complement of $L_B^a(\mathcal{A}, C)$ is accepted by a CPA, but not necessarily by a deterministic CPA.*
6. *Let (\mathcal{A}, C) be a deterministic CPA. The complement of $L_C(\mathcal{A}, C)$ is accepted by a deterministic sBPA.*

The positive results above are for deterministic automata. For nondeterministic automata, the analogous statements fail.

Theorem 5.

1. *There is an sRPA (\mathcal{A}, C) such that the complement $\overline{L_R^s(\mathcal{A}, C)}$ is not accepted by any SPA.*
2. *There is an SPA (\mathcal{A}, C) such that the complement $\overline{L_S(\mathcal{A}, C)}$ is not accepted by any RPA.*
3. *There is an sBPA (\mathcal{A}, C) such that the complement $\overline{L_B^s(\mathcal{A}, C)}$ is not accepted by any CPA.*
4. *There is a CPA (\mathcal{A}, C) such that the complement $\overline{L_C(\mathcal{A}, C)}$ is not accepted by any BPA.*

Next, we consider closure under union, intersection, and complementation of the various classes of Parikh automata on infinite words. Notably, all nondeterministic (and some deterministic) classes are closed under union, the picture for intersection is more scattered, and we prove failure of complement closure for almost all classes. Again, this is in sharp contrast to the setting of classical Büchi automata, which are closed under all three Boolean operations.

	Closure			Decision Problems			
	\cup	\cap	$-$	Emptiness	Universality	Model Check.	Games
RPA	✓	✓	✗	NP-compl.	undec.	undec.	undec.
det. aRPA	✗	✗	✗	NP-compl.	undec.	undec.	undec.
det. sRPA	✓	✗	✗	NP-compl.	undec.	undec.	undec.
SPA	✓	✓	✗	undec.	undec.	undec.	undec.
det. SPA	✗	✓	✗	undec.	coNP-compl.	coNP-compl.	undec.
BPA	✓	✗	✗	NP-compl.	undec.	undec.	undec.
det. aBPA	?	✗	✗	NP-compl.	undec.	undec.	undec.
det. sBPA	✓	✗	✗	NP-compl.	undec.	undec.	undec.
CPA	✓	✓	✗	undec.	undec.	undec.	undec.
det. CPA	✗	✓	?	undec.	coNP-compl.	coNP-compl.	undec.

Table 1: Closure properties and decidability of decision problems for Parikh automata on infinite words.

Theorem 6. *The closure properties depicted in Table 1 hold.*

Note that there are two question marks in the closure properties columns in Table 1, which we leave for further research.

Open Problem 2.

- Are deterministic aBPA closed under union?
- Are deterministic CPA closed under intersection?

6 Decision Problems

In this section, we study the complexity of the emptiness and universality problem, model checking, and solving games for Parikh automata on infinite words.

Before we can do so, we need to specify how a Parikh automata (\mathcal{A}, C) is represented as input for algorithms: The vectors labeling the transitions of \mathcal{A} are represented in binary and a linear set

$$\left\{ \vec{v}_0 + \sum_{i=1}^k c_i \vec{v}_i \mid c_i \in \mathbb{N} \text{ for } i = 1, \dots, k \right\}$$

is represented by the list $(\vec{v}_0, \dots, \vec{v}_k)$ of vectors, again encoded in binary. A semilinear set is then represented by a set of such lists.

6.1 Emptiness and Universality

Emptiness and universality are the most basic decision problems for automata. The results we obtain will be later used to study verification problems.

We begin by settling the complexity of the nonemptiness problem. The positive results are obtained by reductions to the emptiness of Parikh automata over finite words while the undecidability results are reductions from the termination problem for two-counter machines.

Theorem 7.

1. The following problem is NP-complete: Given an RPA, is its language nonempty?
2. The following problem is undecidable: Given a deterministic SPA, is its language nonempty?

3. *The following problem is NP-complete: Given a BPA, is its language nonempty?*
4. *The following problem is undecidable: Given a deterministic CPA, is its language nonempty?*

Recall that ω -regular languages are exactly the languages of the form $\bigcup_{j=1}^n L_j \cdot (L'_j)^\omega$, where each L_j, L'_j is regular. Analogously, ω -context-free languages can be characterized by context-free languages [7]. For Büchi Parikh automata, one direction of the above characterization holds, which follows from the decomposition underlying in the emptiness algorithm for Büchi Parikh automata.

Lemma 1. *If a language L is accepted by a BPA then $L = \bigcup_{j=1}^n L_j \cdot (L'_j)^\omega$, where each L_j, L'_j is accepted by some PA.*

Recall that a word is ultimately periodic if it is of the form xy^ω . Every nonempty ω -regular and every nonempty ω -contextfree language contains an ultimately periodic word, which is a simple consequence of them being of the form $\bigcup_{j=1}^n L_j \cdot (L'_j)^\omega$. The same is true for languages of Büchi Parikh automata.

Corollary 1. *Every nonempty language accepted by a BPA contains an ultimately periodic word.*

Let us briefly comment on the other direction, i.e., is every language of the form $\bigcup_{j=1}^n L_j \cdot (L'_j)^\omega$, where each L_j, L'_j is accepted by some PA, also accepted by some BPA? The answer is no: Consider the language $L = \{a^n b^n \mid n > 1\}$, which is accepted by a deterministic PA. However, using the shifting technique one can show that L^ω is not accepted by any BPA: In every accepting run of an n -state BPA processing $(a^n b^n)^\omega$ can be turned into an accepting run on a word of the form $(a^n b^n)^* a^{n+k} b^n (a^n b^n)^* a^{n-k} b^n (a^n b^n)^\omega$ by shifting some cycle to the front while preserving Büchi acceptance.

Due to Theorem 3, the characterization question is nontrivial for the other acceptance conditions as well. For reachability, this is straightforward, but not for safety and co-Büchi as for these acceptance conditions all (almost all) run prefixes have to be *FC*-prefixes. We leave this problem for future work.

Now, we consider the universality problem.

Theorem 8.

1. *The following problem is undecidable: Given a deterministic sRPA, is its language universal?*
2. *The following problem is coNP-complete: Given a deterministic SPA, is its language universal?*
3. *The following problem is undecidable: Given an SPA, is its language universal?*
4. *The following problem is undecidable: Given a deterministic sBPA, is its language universal?*
5. *The following problem is coNP-complete: Given a deterministic CPA, is its language universal?*
6. *The following problem is undecidable: Given a CPA, is its language universal?*

All decidability results for deterministic automata follow from decidability of emptiness for their dual automaton model and Theorem 4. A similar reasoning yields the undecidability results for deterministic automata, while the ones for nondeterministic automata are reductions from universality of Parikh automata on finite words (co-Büchi) or termination of two-counter machines (safety).

6.2 Model Checking

Model checking is arguably the most successful applications of automata theory to automated verification. The problem asks whether a given system satisfies a specification, often given by an automaton.

More formally, and for the sake of notational convenience, we say that a transition system \mathcal{T} is a (possibly incomplete) SPA (\mathcal{A}, C) so that every state of \mathcal{A} is accepting and $C = \mathbb{N}^d$, i.e., every run is accepting. Now, the model checking problem for a class \mathcal{L} of languages of infinite words asks, given a transition system \mathcal{T} and a language $L \in \mathcal{L}$, whether $L_S(\mathcal{T}) \subseteq L$, i.e., whether every word in the transition system satisfies the specification L . Note that our definition here is equivalent to the standard definition of model checking of finite-state transition systems.

Here, we study the model checking problem for different types of Parikh automata.

Theorem 9.

1. *The following problem is undecidable: Given a transition system \mathcal{T} and a deterministic sRPA (\mathcal{A}, C) , is $L_S(\mathcal{T}) \subseteq L_R^s(\mathcal{A}, C)$?*
2. *The following problem is coNP-complete: Given a transition system \mathcal{T} and a deterministic SPA (\mathcal{A}, C) , is $L_S(\mathcal{T}) \subseteq L_S(\mathcal{A}, C)$?*
3. *The following problem is undecidable: Given a transition system \mathcal{T} and an SPA (\mathcal{A}, C) , is $L_S(\mathcal{T}) \subseteq L_S(\mathcal{A}, C)$?*
4. *The following problem is undecidable: Given a transition system \mathcal{T} and a deterministic sBPA (\mathcal{A}, C) , is $L_S(\mathcal{T}) \subseteq L_B^s(\mathcal{A}, C)$?*
5. *The following problem is coNP-complete: Given a transition system \mathcal{T} and a deterministic CPA (\mathcal{A}, C) , is $L_S(\mathcal{T}) \subseteq L_C(\mathcal{A}, C)$?*
6. *The following problem is undecidable: Given a transition system \mathcal{T} and a CPA (\mathcal{A}, C) , is $L_S(\mathcal{T}) \subseteq L_C(\mathcal{A}, C)$?*

The positive results follow from the classical automata-theoretic approach to model checking: complement the specification automaton, take the intersection with the transition system, and check it for emptiness. For deterministic SPA and deterministic CPA, complementation and intersection with the transition system yields an automaton with decidable emptiness problem. The undecidability results on the other hand all follow from undecidability of universality, which is a special case of model checking.

6.3 Infinite Games

In this section, we study infinite games with winning conditions specified by Parikh automata. Such games are the technical core of the synthesis problem, the problem of determining whether there is a reactive system satisfying a given specification on its input-output behavior. Our main result is that solving infinite games is undecidable for all acceptance conditions we consider here.

Here, we consider Gale-Stewart games [15], abstract games induced by a language L of infinite words, in which two players alternately pick letters, thereby constructing an infinite word w . One player aims to ensure that w is in L while the other aims to ensure that it is not in L .

Formally, given a language $L \subseteq (\Sigma_1 \times \Sigma_2)^\omega$, the game $G(L)$ is played between Player 1 and Player 2 in rounds $i = 0, 1, 2, \dots$ as follows: At each round i , first Player 1 plays a letter $a_i \in \Sigma_1$ and then Player 2 answers with a letter $b_i \in \Sigma_2$. A play of $G(L)$ is an infinite outcome $w = \binom{a_0}{b_0} \binom{a_1}{b_1} \dots$ and Player 2 wins it if and only if $w \in L$.

A strategy for Player 2 in $G(L)$ is a mapping from Σ_1^+ to Σ_2 that gives for each prefix played by Player 1 the next letter to play. An outcome $\binom{a_0}{b_0} \binom{a_1}{b_1} \dots$ agrees with a strategy σ if for each i , we have that $b_i = \sigma(a_0 a_1 \dots a_i)$. Player 2 wins $G(L)$ if she has a strategy that only agrees with outcomes that are winning for Player 2.

The following result follows immediately from the fact that emptiness and universality can be reduced to solving Gale-Stewart games, and that for all deterministic classes of automata one of these problems is undecidable.

Theorem 10. *The problem “Given an automaton (\mathcal{A}, C) , does Player 2 win $G(L(\mathcal{A}, C))$?” is undecidable for the following classes of automata: (deterministic) sRPA, (deterministic) SPA, (deterministic) sBPA, and (deterministic) CPA.*

7 Conclusion

In this work, we have extended Parikh automata to infinite words and studied expressiveness, closure properties, and decision problems. Unlike their ω -regular counterparts, Parikh automata on infinite words do not form a nice hierarchy induced by their acceptance conditions. This is ultimately due to the fact that transitions cannot be disabled by the counters running passively along a run. Therefore, a safety condition on the counters cannot be turned into a, say, Büchi condition on the counters, something that is trivial for state conditions. Furthermore, we have shown that emptiness, universality, and model checking are decidable for some of the models we introduced, but undecidable for others. Most importantly, we prove coNP-completeness of model checking with specifications given by deterministic Parikh automata with safety and co-Büchi acceptance. This allows for the automated verification of quantitative safety and persistence properties. Finally, solving infinite games is undecidable for all models.

Note that we have “only” introduced reachability, safety, Büchi, and co-Büchi Parikh automata. There are many more acceptance conditions in the ω -regular setting, e.g., parity, Rabin, Streett, and Muller. We have refrained from generalizing these, as any natural definition of these acceptance conditions will subsume co-Büchi acceptance, and therefore have an undecidable emptiness problem.

Throughout the paper, we have mentioned some open problems on expressiveness and closure properties. We aim to close these problems in future work. Also, we leave open the complexity of the decision problems in case the semilinear sets are not given by their generators, but by a Presburger formula.

One of the appeals of Parikh automata over finite words is their robustness: they can equivalently be defined via a quantitative variant of WMSO, via weighted automata, and other models (see the introduction for a more complete picture). In future work, we aim to provide similar alternative definitions for Parikh automata on infinite words, in particular comparing our automata to blind multi-counter automata [11] and reversal-bounded counter machines [17]. However, let us mention that the lack of closure properties severely limits to chances for a natural fragment of MSO being equivalent to Parikh automata on infinite words.

Let us conclude with the following problem for further research: If a Parikh automaton with, say safety acceptance, accepts an ω -regular language, is there then an equivalent safety automaton? Stated differently, does Parikhness allow to accept more ω -regular languages? The same question can obviously be asked for other acceptance conditions as well.

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Appendix

This appendix contains all proofs omitted due to space restrictions.

A Parikh Automata and Two-counter Machines

Many of our undecidability proofs are reductions from nontermination problems for two-counter machines. Such a machine \mathcal{M} is a sequence

$$(0 : \mathbf{I}_0)(1 : \mathbf{I}_1) \cdots (k-2 : \mathbf{I}_{k-2})(k-1 : \mathbf{STOP}),$$

where the first element of a pair $(\ell : \mathbf{I}_\ell)$ is the line number and \mathbf{I}_ℓ for $0 \leq \ell < k-1$ is an instruction of the form

- $\mathbf{INC}(X_i)$ with $i \in \{0, 1\}$,
- $\mathbf{DEC}(X_i)$ with $i \in \{0, 1\}$, or
- $\mathbf{IF } X_i=0 \mathbf{ GOTO } \ell' \mathbf{ ELSE GOTO } \ell''$ with $i \in \{0, 1\}$ and $\ell', \ell'' \in \{0, \dots, k-1\}$.

A configuration of \mathcal{M} is of the form (ℓ, c_0, c_1) with $\ell \in \{0, \dots, k-1\}$ (the current line number) and $c_0, c_1 \in \mathbb{N}$ (the current contents of the counters). The initial configuration is $(0, 0, 0)$ and the unique successor configuration of a configuration (ℓ, c_0, c_1) is defined as follows:

- If $\mathbf{I}_\ell = \mathbf{INC}(X_i)$, then the successor configuration is $(\ell + 1, c'_0, c'_1)$ with $c'_i = c_i + 1$ and $c'_{1-i} = c_{1-i}$.
- If $\mathbf{I}_\ell = \mathbf{DEC}(X_i)$, then the successor configuration is $(\ell + 1, c'_0, c'_1)$ with $c'_i = \max\{c_i - 1, 0\}$ and $c'_{1-i} = c_{1-i}$.
- If $\mathbf{I}_\ell = \mathbf{IF } X_i=0 \mathbf{ GOTO } \ell' \mathbf{ ELSE GOTO } \ell''$ and $c_i = 0$, then the successor configuration is (ℓ', c_0, c_1) .
- If $\mathbf{I}_\ell = \mathbf{IF } X_i=0 \mathbf{ GOTO } \ell' \mathbf{ ELSE GOTO } \ell''$ and $c_i > 0$, then the successor configuration is (ℓ'', c_0, c_1) .
- If $\mathbf{I}_\ell = \mathbf{STOP}$, then (ℓ, c_0, c_1) has no successor configuration.

The unique run of \mathcal{M} (starting in the initial configuration) is defined as expected. It is either finite (line $k-1$ is reached) or infinite (line $k-1$ is never reached). In the former case, we say that \mathcal{M} terminates.

Proposition 2 ([19]). *The following problem is undecidable: Given a two-counter machine \mathcal{M} , does \mathcal{M} terminate?*

In the following, we assume without loss of generality that each two-counter machine satisfies the *guarded-decrement property*: Every decrement instruction $(\ell : \mathbf{DEC}(X_i))$ is preceded by $(\ell - 1 : \mathbf{IF } X_i=0 \mathbf{ GOTO } \ell + 1 \mathbf{ ELSE GOTO } \ell)$ and decrements are never the target of a goto instruction. As the decrement of a zero counter has no effect, one can modify each two-counter machine \mathcal{M} into an \mathcal{M}' satisfying the guarded-decrement property such that \mathcal{M} terminates if and only if \mathcal{M}' terminates: One just adds the the required guard before every decrement instruction and changes each target of a goto instruction that is a decrement instruction to the preceding guard.

The guarded-decrement property implies that decrements are only executed if the corresponding counter is nonzero. Thus, the value of counter i after a finite sequence of executed instructions (starting with value zero in the counters) is equal to the number of executed increments of counter i minus the number of executed decrements of counter i . Note that the number of executed increments and decrements can be tracked by a Parikh automaton.

Consider a finite or infinite word $w = w_0 w_1 w_2 \cdots$ over the set $\{0, 1, \dots, k-1\}$ of line numbers. We now describe how to characterize whether w is (a prefix of) the projection to the line numbers of the unique run of \mathcal{M} starting in the initial configuration. This characterization is designed to be checkable by a Parikh

automaton. Note that w only contains line numbers, but does not encode values of the counters. These will be kept track of by the Parikh automaton by counting the number of increment and decrement instructions in the input, as explained above (this explains the need for the guard-decrement property). Formally, we say that w contains an *error* at position $n < |w| - 1$ if either $w_n = k - 1$ (the instruction in line w_n is **STOP**), or if one of the following two conditions is satisfied:

1. The instruction \mathbf{I}_{w_n} in line w_n of \mathcal{M} is an increment or a decrement and $w_{n+1} \neq w_n + 1$, i.e., the letter w_{n+1} after w_n is not equal to the line number $w_n + 1$, which it should be after an increment or decrement.
2. \mathbf{I}_{w_n} has the form **IF** $\mathbf{X}_i=0$ **GOTO** ℓ **ELSE** **GOTO** ℓ' , and one of the following cases holds: Either, we have

$$\sum_{j: \mathbf{I}_j=\mathbf{INC}(X_i)} |w_0 \cdots w_n|_j = \sum_{j: \mathbf{I}_j=\mathbf{DEC}(X_i)} |w_0 \cdots w_n|_j$$

and $w_{n+1} \neq \ell$, i.e., the number of increments of counter i is equal to the number of decrements of counter i in $w_0 \cdots w_n$ (i.e., the counter is zero) but the next line number in w is not the target of the if-branch. Or, we have

$$\sum_{j: \mathbf{I}_j=\mathbf{INC}(X_i)} |w_0 \cdots w_n|_j \neq \sum_{j: \mathbf{I}_j=\mathbf{DEC}(X_i)} |w_0 \cdots w_n|_j,$$

and $w_{n+1} \neq \ell'$, i.e., the number of increments of counter i is not equal to the number of decrements of counter i in $w_0 \cdots w_n$ (i.e., the counter is nonzero) but the next line number in w is not the target of the else-branch.

Note that the definition of error (at position n) refers to the number of increments and decrements in the prefix $w_0 \cdots w_n$, which does not need to be error-free itself. However, if a sequence of line numbers does not have an error, then the guarded-decrement property yields the following result.

Lemma 2. *Let $w \in \{0, 1, \dots, k-1\}^+$ with $w_0 = 0$. Then, w has no errors at positions $\{0, 1, \dots, |w| - 2\}$ if and only if w is a prefix of the projection to the line numbers of the run of \mathcal{M} .*

Proof. If w has no errors at positions $\{0, 1, \dots, |w| - 2\}$, then an induction shows that (w_n, c_0^n, c_1^n) with

$$c_i^n = \sum_{j: \mathbf{I}_j=\mathbf{INC}(X_i)} |w_0 \cdots w_{n-1}|_j - \sum_{j: \mathbf{I}_j=\mathbf{DEC}(X_i)} |w_0 \cdots w_{n-1}|_j$$

is the n -th configuration of the run of \mathcal{M} .

On the other hand, projecting a prefix of the run of \mathcal{M} to the line numbers yields a word w without errors at positions $\{0, 1, \dots, |w| - 2\}$. \square

The existence of an error can be captured by a Parikh automaton, leading to the undecidability of the safe word problem for Parikh automata, which we now prove. Let (\mathcal{A}, C) be a PA accepting finite words over Σ . A *safe* word of (\mathcal{A}, C) is an infinite word in Σ^ω such that each of its prefixes is in $L(\mathcal{A}, C)$.

Lemma 3. *The following problem is undecidable: Given a deterministic PA, does it have a safe word?*

Proof. Our proof proceeds by a reduction from the nontermination problem for decrement-guarded two-counter machines. Given such a machine $\mathcal{M} = (0 : \mathbf{I}_0) \cdots (k-2 : \mathbf{I}_{k-2})(k-1 : \mathbf{STOP})$ let $\Sigma = \{0, \dots, k-1\}$ be the set of its line numbers. We construct a deterministic PA $(\mathcal{A}_{\mathcal{M}}, C_{\mathcal{M}})$ that accepts a word $w \in \Sigma^*$ if and only if $w = \varepsilon$, $w = 0$, or if $|w| \geq 2$ and w does not contain an error at position $|w| - 2$ (but might contain errors at earlier positions). Intuitively, the automaton checks whether the second-to-last instruction is executed properly. The following is then a direct consequence of Lemma 2: $(\mathcal{A}_{\mathcal{M}}, C_{\mathcal{M}})$ has a safe word if and only if \mathcal{M} does not terminate.

The deterministic PA $(\mathcal{A}_{\mathcal{M}}, C_{\mathcal{M}})$ keeps track of the occurrence of line numbers with increment and decrement instructions of each counter (using four dimensions) and two auxiliary dimensions to ensure that the two cases in Condition 2 of the error definition on Page 16 are only checked when the second-to-last letter corresponds to a goto instruction. More formally, we construct $\mathcal{A}_{\mathcal{M}}$ such the unique run processing some input $w = w_0 \dots w_{n-1}$ has the extended Parikh image $(v_{\text{inc}}^0, v_{\text{dec}}^0, v_{\text{goto}}^0, v_{\text{inc}}^1, v_{\text{dec}}^1, v_{\text{goto}}^1)$ where

- v_{inc}^i is equal to $\sum_{j: \mathbf{I}_j = \text{INC}(x_i)} |w_0 \cdots w_{n-2}|_j$, i.e., the number of increment instructions read so far (ignoring the last letter),
- v_{dec}^i is equal to $\sum_{j: \mathbf{I}_j = \text{DEC}(x_i)} |w_0 \cdots w_{n-2}|_j$, i.e., the number of decrement instructions read so far (ignoring the last letter), and
- $v_{\text{goto}}^i \bmod 4 = 0$, if the second-to-last instruction $\mathbf{I}_{w_{n-2}}$ is not a goto testing counter i ,
- $v_{\text{goto}}^i \bmod 4 = 1$, if the second-to-last instruction $\mathbf{I}_{w_{n-2}}$ is a goto testing counter i and the last letter w_{n-1} is equal to the target of the if-branch of this instruction, and
- $v_{\text{goto}}^i \bmod 4 = 2$, if the second-to-last instruction $\mathbf{I}_{w_{n-2}}$ is a goto testing counter i and the last letter w_{n-1} is equal to the target of the else-branch of this instruction.
- $v_{\text{goto}}^i \bmod 4 = 3$, if the second-to-last instruction $\mathbf{I}_{w_{n-2}}$ is a goto testing counter i and the last letter w_{n-1} is neither equal to the target of the if-branch nor equal to the target of the else-branch of this instruction. Note that this constitutes an error at position $n - 2$.

Note that $v_{\text{goto}}^i \bmod 4 \neq 0$ can be true for at most one of the i at any time (as a goto instruction $\mathbf{I}_{w_{n-2}}$ only refers to one counter) and that the v_{inc}^i and v_{dec}^i are updated with a delay of one transition (as the last letter of w is ignored). This requires to store the previously processed letter in the state space of $\mathcal{A}_{\mathcal{M}}$.

Further, $C_{\mathcal{M}}$ is defined such that $(v_{\text{inc}}^0, v_{\text{dec}}^0, v_{\text{goto}}^0, v_{\text{inc}}^1, v_{\text{dec}}^1, v_{\text{goto}}^1)$ is in $C_{\mathcal{M}}$ if and only if

- $v_{\text{goto}}^i \bmod 4 = 0$ for both i , or if
- $v_{\text{goto}}^i \bmod 4 = 1$ for some i (recall that i is unique then) and $v_{\text{inc}}^i = v_{\text{dec}}^i$, or if
- $v_{\text{goto}}^i \bmod 4 = 2$ for some i (again, i is unique) and $v_{\text{inc}}^i \neq v_{\text{dec}}^i$.

All other requirements, e.g., Condition 1 of the error definition on Page 16, the second-to-last letter not being $k - 1$, and the input being in $\{\varepsilon, 0\}$, can be checked using the state space of $\mathcal{A}_{\mathcal{M}}$. \square

B Proofs omitted in Section 4

B.1 Proof of Theorem 1

Proof. 1.) First, let us show that every aRPA can be turned into an equivalent sRPA, i.e., we need to synchronize an F -prefix and a C -prefix. To this end, we add two Boolean flags f_{acc} and f_{frz} to the state space of \mathcal{A} to obtain \mathcal{A}' . The flag f_{acc} is raised once an accepting state has been visited while the flag f_{frz} can be nondeterministically raised at any time during a run, with the effect that the extended Parikh image is frozen, i.e., all subsequent transitions are labeled with a zero vector. Thus, if (\mathcal{A}, C) has an asynchronous reachability accepting run, then (\mathcal{A}', C) will have a (synchronous) reachability-accepting run which is obtained by freezing the extended Parikh image, if the extended Parikh image is in C before an accepting state is visited for the first time. On the other hand, if an accepting state is visited before the extended Parikh image is in C , then we do not have to freeze, as a state in \mathcal{A}' is accepting as long as the flag f_{acc} is equal to one.

Formally, let $\mathcal{A} = (Q, \Sigma \times D, q_I, \Delta, F)$ and let $I_F: Q \rightarrow \{0, 1\}$ be the indicator function for F . We define $\mathcal{A}' = (Q \times \{0, 1\} \times \{0, 1\}, \Sigma \times (D \cup \{\vec{0}\}), (q_I, I_F(q_I), 0), \Delta', Q \times \{1\} \times \{0, 1\})$ with

$$\begin{aligned} \Delta' = & \{((q, f_{\text{acc}}, 0), (a, \vec{v}), (q', \max\{I_F(q'), f_{\text{acc}}\}, 0) \mid (q, (a, \vec{v}), q') \in \Delta\} \cup \\ & \{((q, f_{\text{acc}}, f_{\text{frz}}), (a, \vec{0}), (q', \max\{I_F(q'), f_{\text{acc}}\}, 1) \mid (q, (a, \vec{v}), q') \in \Delta \text{ and } f_{\text{frz}} \in \{0, 1\}\}, \end{aligned}$$

where $\vec{0}$ is the zero vector of appropriate dimension. Then, we have $L_{\mathbb{R}}^s(\mathcal{A}', C) = L_{\mathbb{R}}^a(\mathcal{A}, C)$.

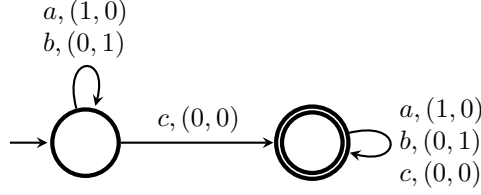


Figure 5: The automaton for Theorem 1.2.

Now, consider the other inclusion, i.e., we want to turn an sRPA into an equivalent aRPA. Here, we reflect whether the last state of a run prefix is accepting or not in the extended Parikh image of the run prefix. As we consider synchronous reachability acceptance, the visit of an accepting state and the Parikh image being in the semilinear set happen at the same time, i.e., they can be captured just by a semilinear set using the additional information in the extended Parikh image. As now both requirements are captured by the semilinear set, we can just make every state accepting to obtain an equivalent aRPA.

Formally, let (\mathcal{A}, C) be an sRPA with $\mathcal{A} = (Q, \Sigma \times D, q_I, \Delta, F)$. If q_I is in F and the zero vector is in C , then $L_R^s(\mathcal{A}, C) = \Sigma^\omega$ due to completeness and we have $L_R^s(\mathcal{A}, C) = L_R^a(\mathcal{A}, C)$, i.e., the transformation is trivial. So, in the following we assume that $q_I \notin F$ or that the zero vector is not in C . This implies that if a run is accepting, then this is witnessed by a *nonempty* FC -prefix. Hence, if q_I is in F , then we can add a new nonaccepting initial state to \mathcal{A} without any incoming transitions, with the same outgoing transitions as the original initial state. The resulting automaton is equivalent to (\mathcal{A}, C) and has a nonaccepting initial state.

Now, define $\mathcal{A}' = (Q, \Sigma \times D', q_I, \Delta', Q)$ where

$$D' = \{(v_0, \dots, v_{d-1}, b) \mid (v_0, \dots, v_{d-1}) \in D \text{ and } b \in \{0, 1\}\}$$

and Δ' contains the transition

$$(q, (a, (v_0, \dots, v_{d-1}, b)), q')$$

for every transition $(q, (a, (v_0, \dots, v_{d-1})), q') \in \Delta$. Here, $b = 0$ if both q and q' are accepting or both are nonaccepting, otherwise $b = 1$.

Note that there is a bijection between run prefixes in \mathcal{A} and run prefixes in \mathcal{A}' , as we only added a new component to the vector labelling each transition. Now, an induction shows that a nonempty run prefix in \mathcal{A}' has an extended Parikh image whose last (new) component is odd if and only if the run prefix ends in a state in F . Thus, consider the semilinear set

$$C' = \{(v_0, \dots, v_d) \mid (v_0, \dots, v_{d-1}) \in C \wedge v_d \text{ is odd}\}.$$

Then, we have $L_R^a(\mathcal{A}', C) = L_R^s(\mathcal{A}, C)$, as every state of \mathcal{A}' is accepting.

2.) The transformation of an sRPA into an equivalent aRPA presented in Item 1 preserves determinism, so every deterministic sRPA can be turned into a deterministic aRPA.

Now, we show the strictness of the inclusion. Consider the language L of infinite words over $\{a, b\}$ that have a nonempty (a, b) -balanced prefix and contain at least one c , which is accepted by the deterministic aRPA (\mathcal{A}, C) with \mathcal{A} depicted in Figure 5 and $C = \{(n, n) \mid n > 0\}$.

Now, assume there is a deterministic sRPA (\mathcal{A}, C) accepting L , say with n states. Consider the word $w = a(a^n b^n)^{n+1} c^\omega$, which is not in L as it has no (a, b) -balanced prefix. Due to completeness¹, (\mathcal{A}, C) has a run ρ processing w , which is not synchronously reachability accepting.

¹Note that L is a liveness property, i.e., every finite word is a prefix of some word in L . Hence, any automaton accepting L must be complete. Thus, our separation argument here can even be generalized to incomplete automata. In fact, most, but not all, of our separations the invocation of completeness as an assumption is just for convenience and could be replaced by arguing that the language witnessing the separation is a liveness property.

The run ρ processing w contains $n + 1$ cycles in the infixes processing the a^n -infixes. Hence, two such cycles start (and thus end) in the same state. Let $\rho = \rho_0\rho_1\rho_2\rho_3\rho'$ be the decomposition of ρ such that ρ_1 and ρ_3 are these two cycles. As the cycles start and end in the same state, $\rho_s = \rho_0\rho_2\rho_1\rho_3\rho'$ is also a run of (\mathcal{A}, C) , i.e., we shift the first cycle further back.

The first cycle processes a word in a^+ , say a^k with $0 < k \leq n$. Thus, the word processed by ρ_s has the form

$$w_s = a(a^n b^n)^{n_0} (a^{n-k} b^n) (a^n b^n)^{n_1} (a^{n+k} b^n) (a^n b^n)^{n_2} c^\omega$$

for some $n_0, n_1, n_2 \geq 0$ with $n_0 + n_1 + n_2 + 2 = n + 1$. Hence, w_s contains a nonempty (a, b) -balanced prefix w' (ending in the $(n_0 + 1)$ -th block of b 's). Hence, $w_s \in L$.

We now show that the run ρ_s is not synchronously reachability accepting. As \mathcal{A} is deterministic, this implies that w_s is not accepted by (\mathcal{A}, C) , which yields the desired contradiction to $L_{\text{R}}^s(\mathcal{A}, C) = L$.

So, consider the run ρ_s . Its prefix of length $(n + 1)2n + 1$ processing

$$a(a^n b^n)^{n_0} (a^{n-k} b^n) (a^n b^n)^{n_1} (a^{n+k} b^n) (a^n b^n)^{n_2}$$

(which does not contain a c) cannot contain an FC -prefix. Every such prefix could, due to completeness, be completed to an accepting run processing a word without a c , resulting in a contradiction.

So, consider a prefix of ρ_s of length greater than $(n + 1)2n + 1$ and the prefix of ρ of the same length. Both end in the same state (as the shifting is confined to the prefix of length $(n + 1)2n + 1$) and have the same extended Parikh image, as it only depends on the number of occurrences of transitions, not their order. As ρ is synchronously reachability rejecting, we conclude that the prefix of ρ_s is not an FC -prefix.

So, ρ_s is not synchronously reachability accepting, as it has no FC -prefix. This yields the desired contradiction.

3.) We describe how to turn a given aBPA (\mathcal{A}, C) into an sBPA (\mathcal{A}', C') by synchronizing F -prefixes and C -prefixes (not necessarily all, infinitely many suffice). We do so by adding a flag f_{acc} to the state space that is deterministically raised when an accepting state is visited. If this flag is high, it can nondeterministically be lowered. In the sBPA we construct, only states reached by lowering the flag are accepting. So, the flag should be lowered when the extended Parikh image of the current run prefix is in C , thereby synchronizing both events. Altogether, the flag we use can assume three distinct values: “low” (value 0), “high” (value 1), and “low, but high in the last step” (value 2), i.e., lowered during the last transition.

Formally, consider an aBPA (\mathcal{A}, C) with $\mathcal{A} = (Q, \Sigma \times D, q_I, \Delta, F)$. We define $\mathcal{A}' = (Q \times \{0, 1, 2\}, \Sigma \times D, (q_I, 0), \Delta', Q \times \{2\})$ where Δ' contains the following transitions for every $(q, (a, \vec{v}), q') \in \Delta$:

- $((q, 0), (a, \vec{v}), (q', I_F(q')))$ where $I_F: Q \rightarrow \{0, 1\}$ is the indicator function for F : If the flag is low, it is raised if and only if an accepting state is reached by the transition.
- $((q, 1), (a, \vec{v}), (q', 1))$: The flag stays high.
- $((q, 1), (a, \vec{v}), (q', 2))$: The flag is (nondeterministically) lowered. Note that we move to state $(q', 2)$ with the 2 signifying that the flag was lowered during the last transition.
- $((q, 2), (a, \vec{v}), (q', I_F(q')))$: The flag has just been lowered and is raised again, if an accepting state reached by the transition.

Then, we have $L_{\text{B}}^a(\mathcal{A}, C) = L_{\text{B}}^s(\mathcal{A}', C)$.

For the other direction, we show how to turn an sBPA (\mathcal{A}, C) into an equivalent aBPA. Note that we can assume without loss of generality that the initial state of \mathcal{A} is not accepting. If it is, we just duplicate it as described in Item 1 above to obtain an NFA equivalent to \mathcal{A} .

With this assumption, the construction turning an sRPA into an equivalent aRPA also works for the Büchi acceptance condition: we have $L_{\text{B}}^a(\mathcal{A}', C') = L_{\text{B}}^s(\mathcal{A}, C)$ where (\mathcal{A}', C') is obtained from (\mathcal{A}, C) by reflecting whether a run ends in an accepting state in the prefix's extended Parikh image.

4.) Again, the transformation turning an sBPA into an equivalent aBPA presented in Item 3 preserves determinism, which yields the inclusion.

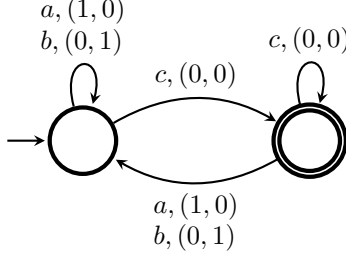


Figure 6: The automaton for Theorem 1.4.

Now, we show the strictness of the inclusion. Consider the language L of infinite words over $\{a, b, c\}$ that contain infinitely many (a, b) -balanced prefixes and infinitely many c 's. It is recognised by the deterministic aBPA (\mathcal{A}, C) where \mathcal{A} is depicted in Figure 6 and $C = \{(n, n) \mid n \in \mathbb{N}\}$.

Now, towards a contradiction, assume there is a deterministic (w.l.o.g. complete) sBPA (\mathcal{A}, C) accepting L , say with n states. We need to introduce some language to simplify our arguments. Let ρ and ρ' be two infinite runs or two run prefixes of the same length. We say that ρ covers ρ' if the following holds: for every FC -prefix of ρ' , the prefix of ρ of the same length is also an FC -prefix. If ρ' is an infinite accepting run and ρ covers ρ' , then ρ is accepting as well.

We construct two infinite words w^- , which is *not* in L , and w^+ , which is in L , such that the (unique) run of \mathcal{A} processing w^- covers the (unique) run processing w^+ . This contradicts the fact that \mathcal{A} accepts L .

The idea behind our construction is as follows: we pick the word w^- in the language $a((a^n b^n)^* c)^\omega$, which guarantees $w^- \notin L$ since it has no (a, b) -balanced prefix. Then, we create the word w^+ by shifting cycles in the run of (\mathcal{A}, C) processing w^- , in a way that creates infinitely many (a, b) -balanced prefixes. The challenging part of the proof is that we need to guarantee that shifting the cycles does not create new FC -prefixes. By doing so, we ensure that the run processing w^- covers the one processing w^+ .

Formally, we define two sequences of run prefixes $(\rho_i^-)_{i \in \mathbb{N}}$ and $(\rho_i^+)_{i \in \mathbb{N}}$, processing finite words $(w_i^-)_{i \in \mathbb{N}}$ and $(w_i^+)_{i \in \mathbb{N}}$ respectively, such that for all $i \geq 0$:

1. ρ_i^- is a strict prefix of ρ_{i+1}^- and ρ_i^+ is a strict prefix of ρ_{i+1}^+ .
2. ρ_i^- and ρ_i^+ have the same length, end in the same state, and have the same extended Parikh image.
3. ρ_i^- covers ρ_i^+ .
4. $|w_i^-|_a = |w_i^-|_b + 1$, $|w_i^-|_c = i$, and w_i^- contains no (a, b) -balanced prefix.
5. $|w_i^+|_a = |w_i^+|_b + 1$, $|w_i^+|_c = i$, and w_i^+ contains at least i (a, b) -balanced prefixes.

Then, we define $w^- = \lim_{i \rightarrow \infty} w_i^-$ and $w^+ = \lim_{i \rightarrow \infty} w_i^+$, which is well-defined due to Property 1. These words then satisfy the desired requirements: $w^- \notin L$ (due to Property 4), $w^+ \in L$ (due to Property 5), and the run processing w^- covers the run processing w^+ (due to determinism and Property 3). Note that Property 2 is used in the construction below.

We define the sequences $(\rho_i^-)_{i \in \mathbb{N}}$ and $(\rho_i^+)_{i \in \mathbb{N}}$ inductively: First, we set $\rho_0^- = \rho_0^+$ to be the unique run prefix processing a , which satisfies all five conditions. We now show how to build ρ_{i+1}^- and ρ_{i+1}^+ based on ρ_i^- and ρ_i^+ while preserving the desired properties. Let χ^- denote the (unique) run of (\mathcal{A}, C) processing the infinite word $w_i^- (a^n b^n)^\omega$. Since \mathcal{A} has n states, the run χ^- visits a cycle while processing each a^n -infix occurring in $(a^n b^n)^\omega$. Therefore, one of these cycles, that we denote by π , is visited infinitely often (recall that cycles are simple).

Hence, we can decompose χ^- into $\rho_i^- \chi_0 \pi \chi_1 \pi \chi_2 \pi \dots$, where we assume each χ_j to process at least one b^n block (note that this can be achieved by adding some π to the χ_j if necessary). Now, consider the run χ^+ of \mathcal{A} obtained by concatenating the run prefix ρ_i^+ with the infinite suffix $\chi_0 \pi \chi_1 \pi \chi_2 \pi \dots$, and then swapping each occurrence of π in the decomposition of the suffix with the run infix ρ_j immediately following it:

$$\begin{array}{l}
\chi^- = \rho_i^- \chi_0 \pi \chi_1 \pi \chi_2 \pi \chi_3 \pi \chi_4 \pi \chi_5 \pi \chi_6 \cdots \\
\chi^+ = \rho_i^+ \chi_0 \chi_1 \pi \chi_2 \pi \chi_3 \pi \chi_4 \pi \chi_5 \pi \chi_6 \pi \cdots
\end{array}$$

The word processed by χ^+ is not in L as it contains finitely many c 's (only the finite prefix processed by ρ_i^+ can contain c 's). Therefore, it is not accepting. As a consequence, there exists some integer $j \geq 0$ such that no FC -prefix ends in the infix $\chi_j \pi$ of χ^+ .

We are now ready to define ρ_{i+1}^- and ρ_{i+1}^+ . Recall that ρ_{j+1} processes a word of the form $ub^n v$. Now, let χ'_{j+1} be the unique run prefix starting in the same state as χ_{j+1} processing $ub^n c$.

We define ρ_{i+1}^- and ρ_{i+1}^+ as follows:

$$\begin{array}{l}
\rho_{i+1}^- = \rho_i^- \chi_0 \pi \chi_1 \pi \chi_2 \cdots \pi \chi_{j-1} \pi \chi_j \pi \chi'_{j+1} \\
\rho_{i+1}^+ = \rho_i^+ \chi_0 \pi \chi_1 \pi \chi_2 \cdots \pi \chi_{j-1} \chi_j \pi \chi'_{j+1}
\end{array}$$

Note that the suffix of ρ_{i+1}^+ after ρ_i^+ differs from the suffix of ρ_{i+1}^- after ρ_i^- by the swap of ρ_j with the cycle π preceding it. Also, note that this is one of the swaps used to obtain the suffix of χ^+ from the suffix of χ^- , and it does not create a new FC -prefix in $\chi_j \pi$, by the choice of j .

Note that $\chi_0 \pi \chi_1 \cdots \chi_j \pi \chi'_{j+1}$ processes a word in $(a^n b^n)^+ c$. Thus, Properties 1 and 4 follow immediately from the definition of ρ_{i+1}^- and ρ_{i+1}^+ and the induction hypothesis. Furthermore, Property 2 follows from Remark 1 and the induction hypothesis.

Now, consider Property 5: To see that w_{i+1}^+ contains (at least) one more (a, b) -balanced prefix than w_i^+ , note that, in the run ρ_{i+1}^- , after each b^n block the difference between the number of a 's and b 's processed so far is equal to 1. Therefore, since in the run ρ_{i+1}^+ we swapped one of the cycles π (processing a nonzero number of a 's) with χ_j (processing at least one b^n block), we created a new (a, b) -balanced prefix. All other requirements of Property 5 follow from the induction hypothesis and arguments similar to those for Property 4.

Finally, consider Property 3, i.e., we need to show that for every FC -prefix of ρ_{i+1}^+ , the prefix of ρ_{i+1}^- of the same length is also an FC -prefix. We proceed by case distinction. So, consider a prefix of ρ_{i+1}^+ .

- If it is even a prefix of ρ_i^+ , then we can apply the induction hypothesis.
- If it ends in the part $\chi_0 \pi \chi_1 \pi \cdots \pi \chi_{j-1}$, then the corresponding prefix of ρ_{i+1}^- ends in the same state and has the same extended Parikh image by induction hypothesis (Property 2).
- If it ends in the part $\chi_j \pi$ then it is not an FC -prefix by the choice of j .
- If it ends in the part $\pi \chi'_{j+1}$, then the corresponding prefix of ρ_{i+1}^- ends in the same state and has the same extended Parikh image due to Remark 1 and the induction hypothesis. \square

B.2 Proof of Theorem 3

Proof. RPA \subseteq BPA and RPA \subseteq CPA Let (\mathcal{A}, C) be an RPA and recall that \mathcal{A} is complete by assumption. Without loss of generality, we assume that (\mathcal{A}, C) is an sRPA (recall Theorem 1). Hence, a word w is in $L_{\mathbb{R}}^s(\mathcal{A}, C)$ if and only if there is an FC -prefix processing a prefix of w . Due to completeness, we can always extend such a run prefix into an infinite accepting run.

By “freezing” (see the proof of Theorem 1.2) the extended Parikh image after such a prefix, we ensure that almost all run prefixes are C -prefixes. To implement the freezing, we add a sink state q_s equipped with a self-loop labeled with a zero vector and add transitions leading from every accepting state to the sink, again labeled with a zero vector. Formally, given $\mathcal{A} = (Q, \Sigma \times D, q_I, \Delta, F)$, we define $\mathcal{A}' = (Q \cup \{q_s\}, \Sigma \times (D \cup \{\vec{0}\}), q_I, \Delta \cup \Delta', \{q_s\})$ where $\vec{0}$ is the zero vector of appropriate dimension and

$$\Delta' = \{(q, (a, \vec{0}), q_s) \mid q \in F \text{ and } a \in \Sigma\} \cup \{(q_s, (a, \vec{0}), q_s) \mid a \in \Sigma\}.$$

So, from every state in F , we can nondeterministically transition to the sink state (which should only be done if the extended Parikh image is in C). Then, we have $L_R^s(\mathcal{A}, C) = L_B^a(\mathcal{A}', C) = L_B^s(\mathcal{A}', C) = L_C(\mathcal{A}', C)$.

Now, we show that all other automata types are pairwise incomparable, save for the inclusion $\text{BPA} \subseteq \text{CPA}$ (see Open Problem 1). Due to the sheer number of cases, and the fact that most proofs rely on the shifting property introduced in Remark 1 and are similar to the arguments described in detail in the proofs of Theorem 1 and Theorem 2, we only sketch them here.

We begin by showing that the two inclusions proved above are as tight as possible, e.g., an RPA can be turned into a nondeterministic BPA and into a nondeterministic CPA, but in general not into a deterministic BPA and not into a deterministic CPA. Then, we prove the remaining non-inclusions.

RPA $\not\subseteq$ deterministic aBPA) We have shown in the proof of Theorem 2 that the language B of infinite words containing a nonempty (a, b) -balanced prefix is accepted by a deterministic sRPA. Here, we show that it is not accepted by any deterministic aBPA.

Assume B is accepted by a deterministic aBPA (\mathcal{A}, C) , say with n states. Due to Remark 3 we assume that \mathcal{A} is complete. The word $w = a(a^n b^n)^\omega$ is not in B , i.e., the unique run ρ of (\mathcal{A}, C) processing w is not accepting. However, the run infixes processing the infixes b^n each contain a cycle. So, we can find two cycles starting in the same state and shift the second one forward while preserving asynchronous Büchi acceptance of the run since the shift does not affect Büchi acceptance. But the resulting run processes a word w_s with a nonempty (a, b) -balanced prefix, yielding the desired contradiction, as the unique run of (\mathcal{A}, C) processing w_s has to be accepting.

RPA $\not\subseteq$ deterministic CPA) The argument just presented showing that B is not accepted by any deterministic BPA also applies to deterministic CPA, as co-Büchi acceptance is also preserved by shifting one cycle.

SPA $\not\subseteq$ BPA and SPA $\not\subseteq$ CPA) We show that the language

$$U = \{w \in \{a, b\}^\omega \mid \text{all nonempty prefixes of } w \text{ are } (a, b)\text{-unbalanced}\}$$

is accepted by a deterministic SPA, but not by any BPA nor by any CPA. The SPA accepting the language is (\mathcal{A}, C) where \mathcal{A} is depicted in Figure 2 and $C = \{(n, n') \mid n \neq n'\} \cup \{(0, 0)\}$.

Now, assume the language is accepted by some BPA or CPA, say with n states. We consider the word $w = a(a^n b^n)^\omega \in U$, which has an accepting run ρ . For every infix b^n there is a cycle in the corresponding transitions of ρ . Hence, we can find two such cycles starting in the same state. Shifting the second cycle to the front preserves both Büchi and co-Büchi acceptance, but the resulting run processes a word with a nonempty (a, b) -balanced prefix, yielding the desired contradiction.

BPA $\not\subseteq$ SPA) We show that the language $A_{=\omega}$ of infinite words over $\{a, b\}$ containing infinitely many a 's is accepted by a deterministic sBPA, but not by any SPA. Constructing a deterministic sBPA is trivial (the usual deterministic Büchi automaton with a universal semilinear set suffices), so we focus on the second part of the claim.

Assume $A_{=\omega}$ is accepted by an SPA (\mathcal{A}, C) . As $b^n a^\omega$ is in $A_{=\omega}$ for every n , there is an accepting run ρ_n of (\mathcal{A}, C) for every word of this form. Hence, every prefix of each ρ_n is an FC -prefix. We arrange the prefixes of the ρ_n processing the prefixes b^n in a finitely branching infinite tree. Thus, König's Lemma yields an infinite path through the tree. By construction, this path is an accepting run of (\mathcal{A}, C) processing $b^\omega \notin A_{=\omega}$, yielding the desired contradiction.

CPA $\not\subseteq$ SPA) We show that the language $A_{<\omega}$ of infinite words over $\{a, b\}$ containing finitely many a 's is accepted by a deterministic CPA, but not by any SPA. Constructing a deterministic CPA is trivial (the usual deterministic co-Büchi automaton with a universal semilinear set suffices), so we focus on the second part of the claim.

Assume $A_{<\omega}$ is accepted by an SPA (\mathcal{A}, C) . Analogously to the previous case, for every $a^n b^\omega \in A_{<\omega}$ there is an accepting run ρ_n of (\mathcal{A}, C) . The run prefixes processing the prefixes a^n can be arranged in a tree and König's Lemma yields an accepting run of (\mathcal{A}, C) processing $a^\omega \notin A_{<\omega}$.

BPA $\not\subseteq$ RPA) We have shown above that the language $A_{=\omega}$ of infinite words with infinitely many a 's is accepted by a deterministic sBPA. Here, we show that it is not accepted by any RPA.

Towards a contradiction, assume w.l.o.g. (see Theorem 1) it is accepted by an sRPA (\mathcal{A}, C) . By definition, \mathcal{A} is complete. Now, consider an accepting run ρ processing a^ω . There is an FC -prefix of ρ . Due to completeness, we can extend this prefix to an accepting run of (\mathcal{A}, C) processing a word of the form $a^n b^\omega$, yielding the desired contradiction.

CPA $\not\subseteq$ RPA) We have shown above that the language $A_{<\omega}$ of infinite words with finitely many a 's is accepted by a deterministic sBPA. Here, we show that it is not accepted by any RPA.

Towards a contradiction, assume w.l.o.g. (see Theorem 1) it is accepted by an sRPA (\mathcal{A}, C) . Analogously to the previous case, relying on completeness, we can extend a prefix of an accepting run processing b^ω into an accepting run of (\mathcal{A}, C) processing a word of the form $b^n a^\omega$, yielding the desired contradiction.

RPA $\not\subseteq$ SPA) The language $A_{>0}$ of infinite words over $\{a, b\}$ having at least one a is accepted by a deterministic sRPA (the usual deterministic reachability automaton with a universal semilinear set suffices). Now, we show that $A_{>0}$ is not accepted by any SPA.

So, towards a contradiction, assume that $A_{>0}$ is accepted by an SPA. The word $b^n a^\omega$ is in $A_{>0}$ for every $n \geq 0$, i.e., there is an accepting run processing each such word. As before, we arrange the run prefixes processing the prefixes b^n in a finitely-branching infinite tree. Then, König's Lemma yields an accepting run processing b^ω , yielding the desired contradiction.

SPA $\not\subseteq$ RPA) We have shown above that the language U is accepted by a deterministic SPA, but not by any BPA. Thus, the fact that every RPA can be effectively be turned into an equivalent BPA implies that U is not accepted by any RPA.

CPA $\not\subseteq$ BPA) Here, we consider the language $U' \subseteq \{a, b\}^\omega$ of infinite words such that almost all prefixes are (a, b) -unbalanced. It is recognized by the deterministic CPA (\mathcal{A}, C) where \mathcal{A} is depicted in Figure 2 and $C = \{(n, n') \mid n \neq n'\}$.

Now, towards a contradiction, assume that U' is accepted by a nondeterministic sBPA (\mathcal{A}, C) , say with n states. We consider the word $a(a^n b^n)^\omega$, which is processed by some accepting run ρ . As we consider synchronous acceptance, the set of FC -prefixes of ρ is infinite.

We inductively define a sequence of runs ρ_j maintaining the following invariant: each ρ_j is accepting and processes a word of the form $w_j(a^n b^n)^\omega$ where w_j has at least j nonempty (a, b) -balanced prefixes and $|w_j|_a = |w_j|_b + 1$.

We start with $\rho_0 = \rho$, which satisfies the invariant with $w_0 = a$. Now, consider ρ_j for some $j \geq 0$ which processes $w_j(a^n b^n)^\omega$. Due to the invariant, there is some proper extension w'_j of w_j such that the prefix of ρ_j processing w'_j is an FC -prefix. After that prefix, we can find two cycles processing only a 's starting in the same state. Let ρ_{j+1} be the run obtained by shifting the first one to the second one. It processes a word of the form $w_j w(a^n b^n)^\omega$ for some w that contains the shifted infixes. We define $w_{j+1} = w_j w$.

The run ρ_{j+1} is still accepting, as the shift only changes the extended Parikh image of finitely many prefixes. Furthermore, the requirement on the word w_{j+1} processed by ρ_{j+1} is also satisfied, as we have introduced another (a, b) -balanced prefix by the shift, but the balance of almost all suffixes is left unchanged.

To conclude, notice that for every $j < j'$, w_j is a strict prefix of $w_{j'}$ and the prefix of ρ_j processing w_j is also a prefix of $\rho_{j'}$, and contains at least j FC -prefixes. Hence, taking the limit of these prefixes yields an accepting run on a word with infinitely many (a, b) -balanced prefixes. Hence, we have derived the desired contradiction. \square

C Proofs omitted in Section 5

C.1 Proof of Theorem 4

Proof. 1.) Let (\mathcal{A}, C) be a deterministic sRPA accepting $L_{\text{R}}^s(\mathcal{A}, C) \subseteq \Sigma^\omega$. We have described in the proof of Theorem 1.1 how to reflect in the extended Parikh image of a run prefix whether this prefix ends in an accepting state or not. To this end, one adds a new component that is odd if and only if the prefix does end in an accepting state. Now, we have $\Sigma^\omega \setminus L_{\text{R}}^s(\mathcal{A}, C) = L_{\text{S}}(\mathcal{A}', C')$ where \mathcal{A}' is obtained from \mathcal{A} by making every state accepting and where

$$C' = \{(v_0, \dots, v_{d-1}, f) \mid (v_0, \dots, v_{d-1}) \notin C \text{ or } f \text{ even}\},$$

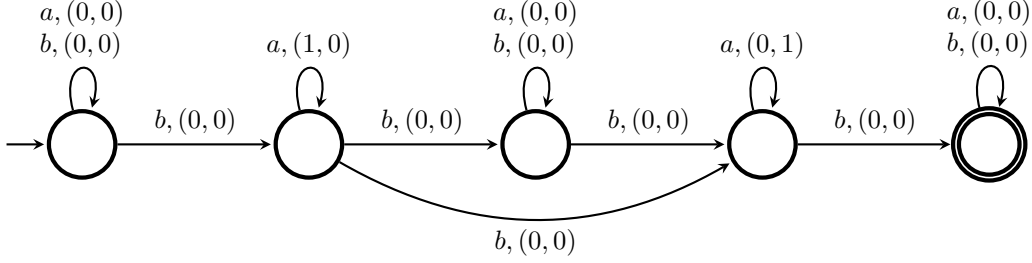


Figure 7: The automaton for Theorem 5.1.

i.e., the safety automaton checks whether every prefix does not end in an accepting state (the last component of the extended Parikh image, reflecting that information, is even) or the original extended Parikh image is not in C .

2.) Let (\mathcal{A}, C) be a deterministic aRPA accepting $L_{\mathbb{R}}^a(\mathcal{A}, C) \subseteq \Sigma^\omega$. As before, we reflect whether a run ends in an accepting state in its extended Parikh image. Now, we construct two SPA from (\mathcal{A}, C) . Given an input w , the first one checks whether every prefix of the unique run ρ of \mathcal{A} processing w ends in a rejecting state and the second one checks that the extended Parikh image of every run prefix of ρ is not in C . Thus, the union of the languages accepted by these two SPA is equal to the complement of $L(\mathcal{A}, C)$. As SPA are closed under union (see Theorem 6), we obtain the desired complement automaton.

Finally, the fact that deterministic aRPA are strictly more expressive than deterministic sRPA implies that not every deterministic aRPA can be complemented into a deterministic SPA: Otherwise, every deterministic aRPA (\mathcal{A}, C) could be turned into a deterministic SPA for the complement, which can be turned into a deterministic sRPA for the original language of (\mathcal{A}, C) (see the next item), which contradicts Theorem 1.2.

3.) Let (\mathcal{A}, C) be a deterministic SPA accepting $L_S(\mathcal{A}, C) \subseteq \Sigma^\omega$. Again, we reflect whether a run prefix ends in an accepting state in its extended Parikh image and then turn (\mathcal{A}, C) into a deterministic sRPA that accepts if and only if there is a run prefix that does not end in an accepting state *or* whose original extended Parikh image is not in C .

4.) The construction presented in Item 1 for deterministic sRPA also turns a deterministic sBPA into a deterministic CPA accepting its complement.

5.) The construction presented in Item 2 for deterministic aRPA also turns a deterministic aBPA into a CPA accepting its complement. The proof that nondeterminism might be required is also analogous.

6.) The construction presented in Item 3 for deterministic SPA also turns a deterministic CPA into a deterministic sBPA accepting its complement. \square

C.2 Proof of Theorem 5

Proof. 1.) Consider the language

$$L = \{w \in \{a, b\}^\omega \mid \text{there exists } n \geq 1 \text{ such that } w \text{ contains the infix } ba^n b \text{ twice}\}.$$

It is accepted by the nondeterministic sRPA (\mathcal{A}, C) where \mathcal{A} is depicted in Figure 7 and $C = \{(n, n) \mid n \in \mathbb{N}\}$.

Now, towards a contradiction, assume that the complement of L is accepted by a nondeterministic SPA (\mathcal{A}, C) , say with n states and d counters. Furthermore, let m be the maximal entry of a vector labeling the transitions of \mathcal{A} .

Then, every entry of the extended Parikh image of a run prefix of length ℓ is bounded by $m \cdot \ell$. Hence, the number of extended Parikh images reachable by run prefixes of length at most ℓ is bounded by $(m \cdot \ell + 1)^d$.

Given $x \geq 1$, define $[x] = \{1, \dots, x\}$. Given a subset S of $[x]$, we define the word $w_S = ba^{s_1}ba^{s_2}b \dots a^{s_{|S|}}$, where $s_1 < s_2 < \dots < s_{|S|}$ is an enumeration of the elements of S . Note that $|w_S| \leq (x + 1)^2$ for $S \subseteq [x]$. Also, $w_S w_S b^\omega$ is in the complement of L if and only if $S \cap S' = \emptyset$.

For $x \geq 1$ and $S \subseteq [x]$, there is an accepting run ρ_S of (\mathcal{A}, C) processing the word $w_S w_{\overline{S}} b^\omega$, where $\overline{S} = [x] \setminus S$. We decompose ρ_S into $\rho_S^1 \rho_S^2 \rho_S^3$ such that ρ_S^1 processes w_S , ρ_S^2 processes $w_{\overline{S}}$, and ρ_S^3 processes b^ω .

Let $S \neq S'$ be two subsets of $[x]$, i.e., there is (w.l.o.g.) some $s \in S$ that is not in S' . We claim that ρ_S^1 and $\rho_{S'}^1$, either end in different states or have distinct extended Parikh images. If this is not the case, then $\rho_S^1 \rho_{S'}^2 \rho_{S'}^3$ is an accepting run of (\mathcal{A}, C) processing $w_S w_{\overline{S'}} b^\omega$ which is not in the complement of L , as $S \cap \overline{S'}$ contains s .

So, to accept the complement of L , the automaton (\mathcal{A}, C) has to reach at least 2^x combinations of extended Parikh image and state for inputs of length at most $(x+1)^2$. For large enough x , the quantity 2^x exceeds the number of such combinations reachable by runs of length $(x+1)^2$, which is at most $n \cdot (m \cdot (x+1)^2 + 1)^d$.

Note that this proof also applies to Büchi and co-Büchi acceptance conditions, i.e., the complement of L is accepted by none of the automata types we have introduced (the case of reachability being even simpler).

2.) In the proof of Theorem 2.2, we have shown that $L = L' \cup (a^* \$)^\omega \cup (a^* \$)^* a^\omega$ with

$$L' = \{ a^{n_0} \$ a^{n_1} \$ \dots \$ a^{n_k} \$ b^n \$^\omega \mid k > 0 \text{ and } n < n_i \text{ for some } 0 \leq i \leq k \}$$

is accepted by an SPA. Towards a contradiction, assume that its complement is accepted by an RPA, say with n states and, without loss of generality, with synchronous reachability acceptance. Note that the set

$$\{ a^{n_0} \$ a^{n_1} \$ \dots \$ a^{n_k} \$ b^n \$^\omega \mid k > 0 \text{ and } n \geq n_i \text{ for all } 0 \leq i \leq k \}$$

is a subset of L 's complement. In particular, it contains the word $(a^n \$)^{n+1} b^n \$^\omega$. So, consider an accepting run ρ of (\mathcal{A}, C) processing w , i.e., the run has an FC -prefix. This prefix has to be longer than $(n+1)^2$ as we can otherwise extend this FC -prefix into an accepting run processing the word $(a^n \$)^\omega$, which is in L and therefore is not accepted by (\mathcal{A}, C) .

Hence, the FC -prefix is longer than $(n+1)^2$. However, this allows us to shift some nonempty a -block around, thereby producing a run that is still accepting, but processing a word with an a -block of length $n+k$ for some $k > 0$, but only n b 's. This word is again in L and not in the complement, i.e., we have again derived a contradiction.

3. and 4.) In the proof of Theorem 3, we show that the language B of infinite words over $\{a, b\}$ that have a nonempty (a, b) -balanced prefix is accepted both by a BPA and by a CPA, as it is accepted by an RPA. However, in the same proof, we show that the complement of B , the set of words such that all nonempty prefixes are (a, b) -unbalanced is not accepted by any BPA nor by any CPA. \square

C.3 Proof of Theorem 6

Proof. Throughout this proof, we fix two automata (\mathcal{A}_i, C_i) for $i \in \{1, 2\}$ with $\mathcal{A}_i = (Q_i, \Sigma \times D_i, q_I^i, \Delta_i, F_i)$, where we assume without loss of generality $Q_1 \cap Q_2 = \emptyset$. Furthermore, we assume without loss of generality that C_1 and C_2 have the same dimension, say d (if this is not the case, we can apply Proposition 1). Finally, note that we also assume that both automata have the same alphabet. This is not a restriction, as we allow incomplete automata, even reachability ones, here.

Due to inclusions and techniques that work for several types of automata, we group the cases.

Union for RPA, SPA, BPA, CPA) For all nondeterministic classes of automata, we prove closure under union by taking the disjoint union of two automata with a fresh initial state. We add a new dimension to the vectors labeling the transitions to ensure that the union of the two semilinear constraints is also disjoint.

Let q_I be a fresh state not in $Q_1 \cup Q_2$. Then, we define (\mathcal{A}, C) where $\mathcal{A} = (Q_1 \cup Q_2 \cup \{q_I\}, \Sigma \times D, q_I, \Delta, F_1 \cup F_2)$ where $D = D_1 \cdot \{(0), (1)\} \cup D_2 \cdot \{(0), (2)\}$, and Δ is the union of the following sets of transitions.

- $\{(q, (a, \vec{v} \cdot (0)), q') \mid (q, (a, \vec{v}), q') \in \Delta_1 \cup \Delta_2\}$: we keep all transitions of both automata, adding a zero in the last component.
- $\{(q_I, (a, \vec{v} \cdot (i)), q') \mid (q_i^i, (a, \vec{v}), q') \in \Delta_i \text{ for some } i\}$: The new initial state has all transitions the initial states of the original automata have, adding an i in the last component if the transition is copied from \mathcal{A}_i .

So, after the first transition, the value in the last dimension is in $\{1, 2\}$, is never updated, and reflects in which of the two automata the run proceeds. Thus, we define $C = C_1 \cdot \{(1)\} \cup C_2 \cdot \{(2)\}$ to take the disjoint union of the two semilinear sets.

Then, we have $L_{\mathbb{R}}^a(\mathcal{A}, C) = L_{\mathbb{R}}^a(\mathcal{A}_1, C_1) \cup L_{\mathbb{R}}^a(\mathcal{A}_2, C_2)$ as well as the corresponding statements for all other acceptance conditions (synchronous and asynchronous). Let us remark that this construction introduces nondeterminism, i.e., the initial choice in which automaton to proceed. We will later see that this is in some cases unavoidable.

Union for deterministic sRPA, deterministic sBPA) For deterministic synchronous automata, we show that their union can be accepted by their product automaton, after reflecting whether a run prefix is an F -prefix in its extended Parikh image.

Recall the construction from the proof of Theorem 1.1 which reflects whether a nonempty run prefix ends in an accepting state in its extended Parikh image, i.e., there is a bijection between FC -prefixes in the original automaton and C' -prefixes in the new automaton. Thus, we assume the (\mathcal{A}_i, C_i) to be of this form. In particular, every state is accepting.

Now, we define the product automaton as follows: (\mathcal{A}, C) where $\mathcal{A} = (Q, \Sigma \times (D_1 \cdot D_2), (q_I^1, q_I^2), \Delta, Q_1 \times Q_2)$ where

$$((q_1, q_2), (a, v_1 \cdot v_2), (q'_1, q'_2)) \in \Delta \text{ if and only if } (q_i, (a, \vec{v}_i), q'_i) \in \Delta_i \text{ for } i \in \{1, 2\},$$

and $C = C_1 \cdot \mathbb{N}^d \cup \mathbb{N}^d \cdot C_2$. Then, we have $L_{\mathbb{R}}^s(\mathcal{A}, C) = L_{\mathbb{R}}^s(\mathcal{A}_1, C_1) \cup L_{\mathbb{R}}^s(\mathcal{A}_2, C_2)$ and $L_{\mathbb{B}}^s(\mathcal{A}, C) = L_{\mathbb{B}}^s(\mathcal{A}_1, C_1) \cup L_{\mathbb{B}}^s(\mathcal{A}_2, C_2)$ (for the Büchi case note that if a run of the product automaton has infinitely many C -prefixes, then one of the simulated runs has infinitely many C_i -prefixes and vice versa).

Union for deterministic aRPA) Let L be the language of infinite words over $\{a, b, c, d, e, f\}$ containing a nonempty prefix w with $|w|_a = |w|_b$ and at least one c . Similarly, let L' be the language of infinite words over $\{a, b, c, d, e, f\}$ containing a nonempty prefix w with $|w|_d = |w|_e$ and at least one f . Both languages are accepted by a deterministic aRPA (cp. the proof of Theorem 1.2), but we show that their union is not accepted by any deterministic aRPA.

Towards a contradiction, assume the union is accepted by a deterministic aRPA (\mathcal{A}, C) , say with n states. Consider the finite word $w = ad(a^n b^n)^{n+1} (d^n e^n)^{n+1}$ and the unique run ρ of \mathcal{A} processing this prefix (which has to exist as w can be extended to a word in the union).

As usual, we find a cycle in each run infix processing an infix a^n (d^n). Thus, we also find two cycles starting in the same state processing a word in a^+ (d^+). Now, let ρ_a (ρ_d) be the run obtained from ρ by shifting the first of the a -cycles (d -cycles) to the back. Note that ρ_a (ρ_d) processes a word w_a (w_d) that has a nonempty prefix with the same number of a 's and b 's (the same number of d 's and e 's). Also, ρ , ρ_a and ρ_d visit the same set of states, as we have just shifted cycles around. In particular, if one of these runs has an F -prefix, then all have one.

Now consider the unique run $\rho_a \rho_c$ of \mathcal{A} processing $w_a c^\omega$ (note that ρ_c processes the whole c^ω suffix). This is an extension of ρ_a due to determinism of \mathcal{A} . Furthermore, it is accepting as $w_a c^\omega$ is in L , i.e., it has an F -prefix and a C -prefix. Note that not both of these prefixes can be prefixes of ρ_a , as we could otherwise construct an accepting run on a word without c 's and without f 's. Similarly, it cannot be the case that the prefix ρ_a does contain neither an F -prefix nor a C -prefix: Otherwise, as both ρ_a and ρ end in the same state and have the same extended Parikh image, the run $\rho \rho_c$ is an accepting run on the word $w c^\omega$ that is not in $L \cup L'$. So, ρ_a has either an F -prefix or a C -prefix, but not both.

An analogous argument shows that ρ_d contains either an F -prefix or a C -prefix, but not both. Now, recall that ρ_a and ρ_d contain the same states. Hence, either both ρ_a and ρ_d contain an F -prefix but no C -prefix, or both contain a C -prefix but no F -prefix.

First, assume that they both contain an F -prefix. Then, the accepting run $\rho_a \rho_c$ contains a C -prefix that is longer than ρ_a . As ρ and ρ_a visit the same states, end in the same state, and have the same extended Parikh image, the run $\rho \rho_c$ is also accepting, but it processes the word $w c^\omega$, which is not in $L \cup L'$, a contradiction.

Finally, assume that both ρ_a and ρ_d contain a C -prefix. Then, the accepting run $\rho_a \rho_c$ contains an F -prefix that is longer than ρ_a , i.e., ρ_c contains an accepting state. Then, $\rho_d \rho_c$ is also accepting, but it processes the word $w_d c^\omega$ that is not in $L \cup L'$, a contradiction.

Union for deterministic SPA) Let L be the language of infinite words over $\{a, b, c, d\}$ such that all prefixes w of length at least two satisfy $|w|_a \neq |w|_b$. Similarly, let L' be the language of infinite words over $\{a, b, c, d\}$ such that all prefixes w of length at least two satisfy $|w|_c \neq |w|_d$. Both are accepted by a deterministic SPA (cp. the proof of Theorem 3). We show that their union is not accepted by any deterministic SPA.

Towards a contradiction, assume it is accepted by some deterministic SPA (\mathcal{A}, C) , say with n states. Consider the word $ac(a^n b^n)^{n+1}(c^n d^n)^{n+1}a^\omega \in L \cap L'$ and its unique accepting run ρ of \mathcal{A} . Hence, every prefix of ρ is an FC -prefix.

In each infix of ρ processing an infix a^n there is a cycle. So, there are two starting with the same state. Moving the first of those to the back yields a run ρ_a on a word in $L' \setminus L$ (as it has a prefix of length at least two with the same number of a 's and b 's, but the c 's and d 's are not touched). So, ρ_a must still be accepting, i.e., every prefix of ρ_a is an FC -prefix.

Dually, by shifting a cycle processing some c 's to the back, we obtain a run ρ_c on a word in $L \setminus L'$, so it must still be accepting, i.e., every prefix of ρ_c is an FC -prefix.

However, due to determinism and the fact that both of these shifts are independent, we conclude that the run obtained by shifting both cycles is also accepting, as each its prefixes is a prefix of ρ_a or ρ_c . However, it processes a word that is neither in L (as there is a prefix of length at least two with the same number of a 's and b 's obtained by shifting the a 's to the back) nor in L' (as there is a prefix of length at least two with the same number of c 's and d 's obtained by shifting the c 's to the back). This yields the desired contradiction.

Union for deterministic CPA) The proof is a generalization of the previous one for deterministic SPA. Consider the language L of infinite words over $\{a, b, c, d\}$ such that almost all prefixes w satisfy $|w|_a \neq |w|_b$. Similarly, let L' be the language of infinite words over $\{a, b, c, d\}$ such that almost all prefixes w satisfy $|w|_c \neq |w|_d$. Both are accepted by a deterministic CPA (cp. the proof of Theorem 3). We show that their union is not accepted by any deterministic CPA.

Here, we start with the word $ac((a^n b^n)^{n+1}(c^n d^n)^{n+1})^\omega \in L \cap L'$. Now, we can shift infinitely many cycles processing only a 's, thereby obtaining an accepting run ρ_a processing a word in $L' \setminus L$. Dually, we can shift infinitely many cycles processing only c 's, thereby obtaining an accepting run ρ_c processing a word in $L \setminus L'$. Now, doing both types of shifting infinitely often yields an accepting run, as due to determinism every prefix of the resulting run is a prefix of either ρ_a or of ρ_c . However, the resulting run processes a word with infinitely many prefixes that have the same number of a 's and b 's and with infinitely many prefixes that have the same number of c 's and d 's, which yields the desired contradiction.

Intersection for RPA) Here, we assume the automata without loss of generality to be synchronous. We again take the Cartesian product \mathcal{A} of the two automata (taking the concatenation of the vectors), but allow the product automaton to nondeterministically freeze the counters of one of the automata during a transition leaving an accepting state of that automaton (see the proof of Theorem 1.2). Then, using the constraint $C = C_1 \cdot C_2$, we obtain $L_R^a(\mathcal{A}, C) = L_R^s(\mathcal{A}_1, C_1) \cap L_R^s(\mathcal{A}_2, C_2)$.

Intersection for SPA, deterministic SPA, CPA, deterministic CPA) Again, let \mathcal{A} be the Cartesian product of the two automata (without reflecting or freezing) and let $C = C_1 \cdot C_2$. Note that this construction preserves determinism. We have $L_S(\mathcal{A}, C) = L_S(\mathcal{A}_1, C_1) \cap L_S(\mathcal{A}_2, C_2)$ and $L_C(\mathcal{A}, C) = L_C(\mathcal{A}_1, C_1) \cap L_C(\mathcal{A}_2, C_2)$.

Intersection for deterministic aRPA) We have shown in the proof of Theorem 2.3 that the language B of infinite words over $\{a, b\}$ having a nonempty prefix w with $|w|_a = |w|_b$ is accepted by a deterministic sRPA, and thus also by a deterministic aRPA (Theorem 1.2). Similarly, in the proof of Theorem 2.1 we have shown that the language of infinite words over $\{a, b, c, d\}$ that have prefixes w_1, w_2 with $|w_1|_a = |w_1|_b$ and $|w_2|_c = |w_2|_d$ is not accepted by any deterministic aRPA. This yields the desired counterexample.

Intersection for deterministic sRPA) Recall that we have shown in Theorem 1.2 that the language of infinite words over $\{a, b, c\}$ that have a nonempty (a, b) -balanced prefix and contain at least one c is not accepted by any deterministic sRPA. However both the language of infinite words containing an (a, b) -balanced prefix and the language of infinite words containing a c are accepted by deterministic sRPA. This yields the desired counterexample.

Intersection for BPA, deterministic sBPA, deterministic aBPA) In order to show that BPA,

deterministic sBPA and deterministic aBPA are not closed under intersection, we proceed as follows. We know that both the language $L_{a,b} \subseteq \{a,b,c,d\}^\omega$ of words containing infinitely many (a,b) -balanced prefixes and the language $L_{c,d} \subseteq \{a,b,c,d\}^\omega$ of words containing infinitely many (c,d) -balanced prefixes are accepted by deterministic sBPA (thus also by deterministic aBPA and BPA). We show that the intersection $L_{a,b} \cap L_{c,d}$ is not accepted by a BPA (thus neither by a deterministic aBPA or sBPA).

Towards a contradiction, assume there is a (non-deterministic) BPA (\mathcal{A}, C) accepting $L_{a,b} \cap L_{c,d}$, say with n states. We show that, while the infinite word $w = a^n(c^n a^n b^{2n} a^n d^n)^\omega$ is in $L_{a,b} \cap L_{c,d}$, by swapping well chosen parts of some accepting run of (\mathcal{A}, C) processing w we can build an accepting run of (\mathcal{A}, C) that processes a word that is not in $L_{a,b} \cap L_{c,d}$.

Let us consider an accepting run ρ processing w . Then either infinitely many FC -prefixes of ρ end in the $a^n b^{2n} a^n$ blocks of w , or infinitely many FC -prefixes of ρ end in the $d^n c^n$ blocks of w . We show how to reach a contradiction in the former case, and at the end of the proof we will explain how the latter case can be treated similarly.

So, let us suppose that infinitely many FC -prefixes of ρ end in the $a^n b^{2n} a^n$ blocks of the word $w = a^n(c^n a^n b^{2n} a^n d^n)^\omega$. Since \mathcal{A} has n states, this means that we can decompose ρ into $\rho_0 \pi_c \chi \pi_d \rho_1 \pi_c \chi \pi_d \rho_2 \pi_c \chi \pi_d \cdots$, where the run infix $\pi_c \chi \pi_d$ occurring infinitely often satisfies:

- π_c is a cycle processing a word in c^+ .
- χ processes a word in $c^* a^n b^{2n} a^n d^*$, and there is an FC -prefix ending in each copy of χ in the decomposition above.
- π_d is a cycle processing a word in d^+ .

Note that the ρ_j may contain copies of $\pi_c \chi \pi_d$ where no FC -prefix ends.

We denote by ρ' the run obtained by moving all the odd copies of π_c (except the first) one step backward in this decomposition of ρ , and all the odd copies of π_d one step forward:

$$\begin{array}{l} \rho = \underline{\rho_0 \pi_c \chi} \pi_d \rho_1 \pi_c \chi \pi_d \rho_2 \pi_c \chi \pi_d \rho_3 \pi_c \chi \pi_d \rho_4 \pi_c \chi \pi_d \rho_5 \pi_c \chi \pi_d \rho_6 \pi_c \chi \cdots \\ \rho' = \underline{\rho_0 \pi_c \chi} \rho_1 \pi_c \pi_c \chi \pi_d \pi_d \rho_2 \underline{\chi} \rho_3 \pi_c \pi_c \chi \pi_d \pi_d \rho_4 \underline{\chi} \rho_5 \pi_c \pi_c \chi \pi_d \pi_d \rho_6 \underline{\chi} \cdots \end{array}$$

Let $\text{diff}(n)$ denote the difference between the number of c 's and the number of d 's occurring in the prefix of ρ of length n , and define $\text{diff}'(n)$ similarly for prefixes of ρ' . We now compare $\text{diff}(n)$ and $\text{diff}'(n)$ to argue that ρ' processes a word that is not in $L_{c,d}$.

The underlined elements of ρ and ρ' denote the only parts containing positions n such that $\text{diff}(n) = \text{diff}'(n)$. All the other positions n satisfy $\text{diff}'(n) > \text{diff}(n)$ since the length- n prefix of ρ' has either processed more c 's than the corresponding prefix of ρ (as a c -cycle π_c has been moved backward) or has processed less d 's (as a d -cycle π_d has been moved forward). Thus, the word processed by ρ' only has finitely many (c,d) -balanced prefixes. This follows from the fact that along the run ρ the difference $\text{diff}(n)$ between the number of c 's and d 's processed so far never falls below 0, and is always strictly greater than 0 along the run infixes χ . Therefore, moving c -cycles backward and d -cycles forward in ρ' ensures that, past the run prefix ρ_0 , the difference between the number of c 's and d 's processed so far is always strictly greater than 0. Thus, there is no (c,d) -balanced prefix.

Moreover, note that along the underlined parts both runs visit the same states and have the same extended Parikh images (see Remark 1). Hence, the run ρ' is accepting since there is an FC -prefix ending in each run infix χ of ρ .

This gives us the desired contradiction: the run ρ' of \mathcal{A} is accepting, yet it processes a word that is not in $L_{a,b} \cap L_{c,d}$.

To conclude, if infinitely many FC -prefixes of ρ end in the $d^n c^n$ blocks of w (instead of the $a^n b^{2n} a^n$ blocks), we again decompose ρ into $\rho_0 \pi_a \chi \pi_b \rho_1 \pi_a \chi \pi_b \rho_2 \pi_a \chi \pi_b \cdots$, where this time:

- π_a is a cycle processing a word in a^+ ;

- χ processes a word in $a^*d^nc^na^nb^*$, and there is an FC -prefix ending in each copy of χ ;
- π_b is a cycle processing a word in b^+ .

We then complete the proof as in the previous case.

Complement for RPA, deterministic sRPA, deterministic aRPA) The language of infinite words over $\{a, b\}$ containing at least one a is accepted by a deterministic sRPA. However, its complement, the language of infinite words having no a , is not accepted by any (even nondeterministic) RPA: Assume it is and consider an accepting run ρ processing b^ω : it has a F -prefix and a C -prefix. Due to our completeness assumption, after these prefixes the run can be continued in any way, e.g., by processing a word containing an a , while staying accepting, a contradiction. This yields the desired counterexample for all three types of automata.

Complement for SPA, deterministic SPA) The language of infinite words over $\{a, b\}$ containing no a is accepted by a deterministic SPA. However, its complement, the language of infinite words having at least one a , is not accepted by any (even nondeterministic) SPA, as shown in the proof of Theorem 3. This yields the desired counterexample for both types of automata.

Complement for BPA, deterministic sBPA, deterministic aBPA) The language of infinite words over $\{a, b\}$ containing infinitely many (a, b) -balanced prefixes is accepted by the deterministic sBPA (\mathcal{A}, C) where \mathcal{A} is depicted in Figure 2 and $C = \{(n, n) \mid n \geq 0\}$. However, we showed in the proof of Theorem 3 that its complement, the language U' of infinite words such that almost all prefixes are (a, b) -unbalanced, is not accepted by any (even nondeterministic) BPA. This yields the desired counterexample for all three types of automata.

Complement for CPA) The language of infinite words over $\{a, b\}$ containing a nonempty (a, b) -balanced prefix is accepted by a nondeterministic CPA, as shown in the proof of Theorem 2.3. However, we showed in the proof of Theorem 3 that its complement, the language U of infinite words that have only (a, b) -unbalanced nonempty prefixes, is not accepted by any nondeterministic CPA. This yields the desired counterexample. \square

D Proofs omitted in Section 6

D.1 Proof of Theorem 7

Proof. 1.) Due to Theorem 1.1, we only consider the case of sRPA for the NP upper bound. Given such an automaton (\mathcal{A}, C) with $\mathcal{A} = (Q, \Sigma \times D, q_I, \Delta, F)$ let $F' \subseteq F$ be the set of accepting states from which a cycle is reachable. Now, define $\mathcal{A}' = (Q, \Sigma \times D, q_I, \Delta, F')$. Then, we have $L_R^s(\mathcal{A}, C) \neq \emptyset$ if and only if $L(\mathcal{A}', C) \neq \emptyset$ (i.e., we treat (\mathcal{A}', C) as a PA), with the latter problem being in NP [12].

The matching NP lower bound is, again due to Theorem 1.1, only shown for sRPA. We proceed by a reduction from the NP-complete [12] nonemptiness problem for Parikh automata. Given a Parikh automaton (\mathcal{A}, C) , let \mathcal{A}' be obtained from \mathcal{A} by adding a fresh state q with a self-loop labeled by $(\#, \vec{0})$ as well as transitions labeled by $(\#, \vec{0})$ leading from the accepting states of \mathcal{A} to q . Here, $\#$ is a fresh letter and $\vec{0}$ is the zero vector of the correct dimension. By declaring q to be the only accepting state in \mathcal{A}' , we have that $L_R^s(\mathcal{A}', C)$ is nonempty if and only if $L(\mathcal{A}, C)$ is nonempty.

Note that hardness holds already for deterministic automata, as one can always rename letters to make a nondeterministic PA deterministic without changing the answer to the emptiness problem.

2.) Now, consider safety: A PA (\mathcal{A}, C) has a safe word if and only if $L_S(\mathcal{A}, C) \neq \emptyset$. As existence of a safe word is undecidable (see Lemma 3), we obtain the result.

3.) Due to Theorem 1.3, it is enough to consider synchronous Büchi acceptance for the upper bound. So, fix some sBPA (\mathcal{A}, C) with $\mathcal{A} = (Q, \Sigma \times D, q_I, \Delta, F)$. Let $C = \bigcup_i L_i$ where the L_i are linear sets. The language $L_B^s(\mathcal{A}, C)$ is nonempty if and only if $L_B^s(\mathcal{A}, L_i)$ is nonempty for some i . Hence, we show how to solve emptiness for automata with linear C , say $C = \left\{ \vec{v}_0 + \sum_{i=1}^k c_i \vec{v}_i \mid c_i \in \mathbb{N} \text{ for } i = 1, \dots, k \right\}$. We define $P = \left\{ \sum_{i=1}^k c_i \vec{v}_i \mid c_i \in \mathbb{N} \text{ for } i = 1, \dots, k \right\}$ and, for a given state $q \in Q$, the NFA

- \mathcal{A}_q obtained from \mathcal{A} by replacing the set of accepting states by $\{q\}$, and

- $\mathcal{A}_{q,q}$ obtained from \mathcal{A} by replacing the initial state by q , by replacing the set of accepting states by $\{q\}$, and by modifying the resulting NFA such that it does not accept the empty word (but leaving its language unchanged otherwise).

We claim that $L_B^s(\mathcal{A}, C)$ is nonempty if and only if there is a $q \in F$ such that both $L(\mathcal{A}_q, C)$ and $L(\mathcal{A}_{q,q}, P)$ are nonempty. As emptiness of Parikh automata is in NP, this yields the desired upper bound.

So, assume there is such a q . Then, there is a finite run ρ_1 of \mathcal{A} that starts in q_I , ends in q , and processes some $w_1 \in \Sigma^*$ with extended Parikh image in C . Also, there is a finite run ρ_2 of \mathcal{A} that starts and ends in q and processes some nonempty $w_2 \in \Sigma^*$ with extended Parikh image in P . For every $n \geq 1$, $\rho_1(\rho_2)^n$ is a finite run of (\mathcal{A}, C) ending in the accepting state q that processes $w_1(w_2)^n$ and whose extended Parikh image is in C . So, $\rho_1(\rho_2)^\omega$ is a synchronous Büchi accepting run of (\mathcal{A}, C) .

For the converse, assume there is some synchronous Büchi accepting run $(q_0, w_0, q_1)(q_1, w_1, q_2)(q_2, w_2, q_3) \cdots$ of (\mathcal{A}, C) . Then, there is also an accepting state $q \in F$ and an infinite set of positions $S \subseteq \mathbb{N}$ such that $q_s = q$ and $\Phi_e(w_0 \cdots w_{s-1}) \in C$ for all $s \in S$. Hence, for every $s \in S$ there is a vector $(c_1^s, \dots, c_k^s) \in \mathbb{N}^k$ such that $\Phi_e(w_0 \cdots w_{s-1}) = \vec{v}_0 + \sum_{i=1}^k c_i^s \vec{v}_i$. By Dickson's Lemma [10], there are $s_1 < s_2$ such that $c_j^{s_1} \leq c_j^{s_2}$ for every $1 \leq j \leq k$. Then, $\Phi_e(w_{s_1} \cdots w_{s_2-1}) = \sum_{i=1}^k (c_i^{s_2} - c_i^{s_1}) \vec{v}_i$, which implies $\Phi_e(w_{s_1} \cdots w_{s_2-1}) \in P$. Thus, the prefix of ρ of length s_1 is an accepting run of the PA (\mathcal{A}_q, C) and the next $(s_2 - s_1)$ transitions of ρ form a nonempty accepting run of the PA $(\mathcal{A}_{q,q}, P)$.

The NP lower bound follows from the proof of Theorem 7.1 by noticing that we also have that $L_B^s(\mathcal{A}', C)$ is nonempty if and only if $L(\mathcal{A}, C)$ is nonempty.

4.) Now, consider co-Büchi acceptance. We present a reduction from the undecidable universal termination problem for decrement-guarded two-counter machines [1]², which asks whether a given machine terminates from every configuration. If this is the case, we say that \mathcal{M} is universally terminating.

Now, consider a decrement-guarded two-counter machine \mathcal{M} that contains, without loss of generality, an increment instruction for each counter, say in lines ℓ_0^+ and ℓ_1^+ . Recall that the deterministic automaton $(\mathcal{A}_\mathcal{M}, C_\mathcal{M})$ constructed in the proof of Lemma 3 accepts w over the line numbers of \mathcal{M} if and only if $w = \varepsilon$, $w = 0$, or if $|w| \geq 2$ and w does not contain an error at position $|w| - 2$. We claim that $L_C(\mathcal{A}_\mathcal{M}, C_\mathcal{M})$ is nonempty if and only if \mathcal{M} is not universally terminating.

So, first assume there is some $w \in L_C(\mathcal{A}_\mathcal{M}, C_\mathcal{M})$. Hence, there is a run of $(\mathcal{A}_\mathcal{M}, C_\mathcal{M})$ processing w satisfying the co-Büchi acceptance condition: From some point n_0 onward, the run only visits states in F and the extended Parikh image is in $C_\mathcal{M}$. This means that there is no error in w after position n_0 . So, \mathcal{M} does not terminate from the configuration (w_{n_0}, c_0, c_1) with

$$c_i = \sum_{j: I_j = \text{INC}(x_i)} |w_0 \cdots w_{n_0-1}|_j - \sum_{j: I_j = \text{DEC}(x_i)} |w_0 \cdots w_{n_0-1}|_j,$$

i.e., \mathcal{M} is not universally terminating.

Now, assume \mathcal{M} does not universally terminate, say it does not terminate from configuration (ℓ, c_0, c_1) . Recall that the instruction in line ℓ_i^+ is an increment of counter i . We define $w = (\ell_0^+)^{c_0} (\ell_1^+)^{c_1} w'$ where w' is the projection to the line numbers of the (nonterminating) run of \mathcal{M} starting in (ℓ, c_0, c_1) . This word does not have an error after position ℓ (but may have some before that position). Hence there is a co-Büchi accepting run of $(\mathcal{A}_\mathcal{M}, C_\mathcal{M})$ processing w , i.e., $L_C(\mathcal{A}_\mathcal{M}, C_\mathcal{M})$ is nonempty. \square

D.2 Proof of Lemma 1

Proof. Let L be accepted by an sBPA (\mathcal{A}, C) with $C = \bigcup_{j \in J} C_j$ for some finite set J , where each C_j is a linear set. In the proof of Theorem 7.3, we have defined the NFA \mathcal{A}_q and $\mathcal{A}_{q,q}$ for every state q of \mathcal{A} .

Now, consider some $w \in L$ and an accepting run $\rho = (q_0, w_0, q_1)(q_1, w_1, q_2)(q_2, w_2, q_3) \cdots$ of (\mathcal{A}, C) processing w . Then, there is an accepting state q of \mathcal{A} , some C_j , and an infinite set $S \subseteq \mathbb{N}$ of positions such

²The authors use a slightly different definition of two-counter machine than we do here. Nevertheless, the universal termination problem for their machines can be reduced to the universal termination problem for decrement-guarded two-counter machines as defined here.

that $q_s = q$ and $\Phi_e(w_0 \cdots w_{s-1}) \in C_j$ for all $s \in S$. Let $C_j = \left\{ \vec{v}_0 + \sum_{i=1}^k c_i \vec{v}_i \mid c_i \in \mathbb{N} \text{ for } i = 1, \dots, k \right\}$ and let $P_j = \left\{ \sum_{i=1}^k c_i \vec{v}_i \mid c_i \in \mathbb{N} \text{ for } i = 1, \dots, k \right\}$. As before, for every $s \in S$, there is a vector $(c_1^s, \dots, c_k^s) \in \mathbb{N}^k$ such that $\Phi_e(w_0 \cdots w_{s-1}) = \vec{v}_0 + \sum_{i=1}^k c_i^s \vec{v}_i$.

Now, we apply an equivalent formulation of Dickson's Lemma [10], which yields an infinite subset $S' \subseteq S$ with $c_j^s \leq c_j^{s'}$ for all $1 \leq j \leq k$ and all $s, s' \in S'$ with $s < s'$, i.e., we have an increasing chain in S . Let $s_0 < s_1 < s_2 < \dots$ be an enumeration of S' .

As above, we have $\Phi_e(w_{s_n} \cdots w_{s_{n+1}-1}) \in P_j$ for all n . Thus, $(q_0, w_0, q_1) \cdots (q_{s_0-1}, w_{s_0-1}, q_{s_0})$ is an accepting run of the PA (\mathcal{A}_q, C) and each $(q_{s_n}, w_{s_n}, q_{s_{n+1}}) \cdots (q_{s_{n+1}-1}, w_{s_{n+1}-1}, q_{s_{n+1}})$ is an accepting run of the PA $(\mathcal{A}_{q,q}, P)$. So, $w \in \bigcup_{j \in J} \bigcup_{q \in Q} L(\mathcal{A}_q, C_j) \cdot (L(\mathcal{A}_{q,q}, P_j))^\omega$. \square

D.3 Proof of Theorem 8

Proof. The proofs of the results for deterministic automata follow immediately from the fact that a language is universal if and only if its complement is empty, Theorem 4, and Theorem 7. So, let us consider universality of SPA and CPA.

3.) We present a reduction from the termination problem for (decrement-guarded) two-counter machines to universality of SPA. So, fix such a machine \mathcal{M} with line numbers $0, 1, \dots, k-1$ where $k-1$ is the line number of the stopping instruction, fix $\Sigma = \{0, 1, \dots, k-1\}$, and consider $L_{\mathcal{M}} = L_{\mathcal{M}}^0 \cup L_{\mathcal{M}}^1$ with

$$L_{\mathcal{M}}^0 = \{w \in \Sigma^\omega \mid w_0 \neq 0\} \text{ and}$$

$$L_{\mathcal{M}}^1 = \{w \in \Sigma^\omega \mid \text{if } |w|_{k-1} > 0 \text{ then } w \text{ contains an error strictly before the first occurrence of } k-1\}.$$

Here, errors are defined as in Section A. We first prove that $L_{\mathcal{M}}$ is not universal if and only if \mathcal{M} terminates, then that $L_{\mathcal{M}}$ is accepted by some SPA.

So, assume that \mathcal{M} terminates and let $w \in \Sigma^*$ be the projection of the unique finite run of \mathcal{M} to the line numbers. Then, w starts with 0, contains a $k-1$, and no error before the $k-1$. Thus, $w0^\omega$ is not in $L_{\mathcal{M}}$, i.e., $L_{\mathcal{M}}$ is not universal.

Conversely, assume that $L_{\mathcal{M}}$ is not universal. Then, there is an infinite word w that is neither in $L_{\mathcal{M}}^0$ nor in $L_{\mathcal{M}}^1$. So, w must start with 0, contain a $k-1$, but no error before the first $k-1$. Thus, Lemma 2 implies that the prefix of w up to and including the first $k-1$ is the projection to the line numbers of the run of \mathcal{M} . This run is terminating, as the prefix ends in $k-1$. Thus, \mathcal{M} terminates.

It remains to argue that $L_{\mathcal{M}} = L_{\mathcal{M}}^0 \cup L_{\mathcal{M}}^1$ is accepted by an SPA. Due to closure of SPA under union and the fact that every ω -regular safety property is also accepted by an SPA, we only need to consider $L_{\mathcal{M}}^1$. Recall that we have constructed a deterministic PA (\mathcal{A}, C) (on finite words) accepting a word if it is empty, 0, or contains an error at the second-to-last position. We modify this PA into an SPA (\mathcal{A}', C') that accepts $L_{\mathcal{M}}^1$.

To this end, we add a fresh accepting state q_a and a fresh rejecting state q_r to \mathcal{A} while making all states of \mathcal{A} accepting in \mathcal{A}' . Both fresh states are sinks equipped with self-loops that are labeled with $(\ell, \vec{0})$ for every line number ℓ . Here, $\vec{0}$ is the appropriate zero vector, i.e., the counters are frozen when reaching the fresh states.

Intuitively, moving to q_a signifies that an error at the current position is guessed. Consequently, if a $k-1$ is processed from a state of \mathcal{A} , the rejecting sink q_r is reached. We reflect in a fresh component of the extended Parikh image whether q_a has been reached. Due to this, we can define C' so that the extended Parikh image of every run prefix ending in a state of \mathcal{A} is in C' and that the extended Parikh image of a run prefix ending in q_a is in C' if removing the last entry (the reflecting one) yields a vector in C , i.e., an error has indeed occurred. Then, we have $L_S(\mathcal{A}', C') = L_{\mathcal{M}}^1$ as required.

6 Universality of Parikh automata over finite words is undecidable [18]. Now, given a PA (\mathcal{A}, C) over Σ , one can construct a CPA (\mathcal{A}', C') for the language $L(\mathcal{A}, C) \cdot \# \cdot (\Sigma \cup \{\#\})^\omega \cup \Sigma^\omega$, where $\# \notin \Sigma$ is a fresh letter. This construction relies on freezing the counters (cp. the proof of Theorem 3) and closure of CPA under union. Now, $L(\mathcal{A}, C)$ is universal if and only if $L_C(\mathcal{A}', C')$ is universal. \square

D.4 Proof of Theorem 9

Proof. Let \mathcal{T} be a transition system with $L_S(\mathcal{T}) = \Sigma^\omega$, e.g., a one-state transition system with a self-loop labeled with all letters in Σ . Then, $L \subseteq \Sigma^\omega$ is universal if and only if $L \cap L_S(\mathcal{T}) \subseteq L$. Thus, all six lower bounds (coNP-hardness and undecidability) immediately follow from the analogous lower bounds for universality (see Theorem 8). So, it remains to consider the two coNP upper bounds.

So, fix a deterministic SPA (\mathcal{A}, C) and a transition system \mathcal{T} . We apply the usual approach to automata-theoretic model checking: We have $L_S(\mathcal{T}) \subseteq L_S(\mathcal{A}, C)$ if and only if $L_S(\mathcal{T}) \cap \overline{L_S(\mathcal{A}, C)} = \emptyset$.

Due to Theorem 4.3 there is a deterministic sRPA (\mathcal{A}', C') accepting $\overline{L_S(\mathcal{A}, C)}$. Furthermore, using a product construction, one can construct an RPA (\mathcal{A}'', C'') accepting $L_S(\mathcal{T}) \cap \overline{L_S(\mathcal{A}, C)}$, which can then be tested for emptiness, which is in coNP (see Theorem 7).

Note that the product construction depends on the fact that every run of \mathcal{T} is accepting, i.e., the acceptance condition of the product automaton only has to check one acceptance condition.

The proof for deterministic co-Büchi Parikh automata is analogous, but using Büchi automata (\mathcal{A}', C') and (\mathcal{A}'', C'') . \square

D.5 Proof of Theorem 10

Proof. The results follow immediately from the following two facts and the undecidability of emptiness or universality for the corresponding automata types:

- A language L is nonempty if and only if Player 2 wins $G(\binom{\#}{L})$ with $\binom{\#}{L} = \{(\binom{\#}{w_0})(\binom{\#}{w_1})(\binom{\#}{w_2}) \cdots \mid w_0 w_1 w_2 \cdots \in L\}$.
- A language L is universal if and only if Player 2 wins $G(\binom{L}{\#})$ with $\binom{L}{\#} = \{(\binom{w_0}{\#})(\binom{w_1}{\#})(\binom{w_2}{\#}) \cdots \mid w_0 w_1 w_2 \cdots \in L\}$.

Note that a Parikh automaton for L can be turned into an equivalent one for $\binom{\#}{L}$ and $\binom{L}{\#}$ while preserving determinism and the acceptance type, by just replacing each transition label a by $\binom{\#}{a}$ and $\binom{a}{\#}$, respectively. \square