

Influence of sea-ice-related features and anthropogenic subsidies on the foraging behaviour of a high-Arctic seabird, the ivory gull (Pagophila eburnea)

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Influence of sea-ice-related features and anthropogenic subsidies on the foraging behaviour of a 1 high-Arctic seabird, the ivory gull (*Pagophila eburnea*) 2 3 Keyvan Dumas^{1, 3}*, Olivier Gilg^{2, 3}, Nicolas Courbin¹, Alejandro Corregidor-Castro^{4a}. Guillaume 4 Evanno^{3, 5}, Hallvard Strøm⁶, Anders Mosbech⁴, Morten Frederiksen⁴, and Glenn Yannic^{1, 3} 5 6 7 ¹Univ. Grenoble Alpes, Univ. Savoie Mont Blanc, CNRS, LECA, 38000 Grenoble, France ²Université de Bourgogne Franche Comté, UMR 6249 Chrono-environnement, 25000 Besançon, 8 France 9 ³Groupe de Recherche en Ecologie Arctique, 21440 Francheville, France 10 ⁴Department of Ecoscience, Aarhus University, 4000, Roskilde, Denmark 11 ⁵DECOD (Ecosystem Dynamics and Sustainability), INRAE, Institut Agro, IFREMER, Rennes, 12 France 13 ⁶Norwegian Polar Institute, Fram Centre, 9296 Tromsø, Norway 14

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ABSTRACT

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The Arctic region is currently experiencing major modifications in sea ice extent and phenology due 22 to global climate and anthropogenic changes. As Arctic marine ecosystems rely greatly on the 23 presence of sea ice and its seasonal dynamics, these changes could have major impacts on Arctic 24 biota. The ivory gull (*Pagophila eburnea*) is an endemic Arctic seabird whose populations are 25 declining in Canada and Svalbard. Its affinity for sea ice makes it a good sentinel species of current 26 changes in the high Arctic. We explored the influence of sea-ice-related features and anthropogenic 27 subsidies on the foraging behaviour of ivory gulls during the breeding season. To this end, we 28 29 analysed the movement of adult ivory gulls in north-east Greenland. We confirmed that ivory gulls use a dual foraging strategy, with birds faithful to their foraging areas at short distances from the 30 colony, but used individual-specific areas during long-distance foraging trips. We highlight that 31 ivory gulls are spatially specialised individuals within a generalist species. We demonstrated that 32 human settlements attracted foraging birds, which shows that human presence in such a remote 33 34 place may influence seabird behaviour. Finally, by combining hidden Markov models and resourceselection functions, we showed that ivory gulls selected highly concentrated sea ice for foraging 35 during the breeding season. Our study provides key information on the use of space and foraging 36 37 strategies of ivory gulls during the breeding season, and more broadly, how Arctic seabirds use ice features. 38

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40 KEYWORDS: Seabirds \cdot Arctic ice fauna \cdot GPS tracking \cdot Dual foraging \cdot Site fidelity \cdot Greenland

1. INTRODUCTION

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Global climate and anthropogenic changes have profound impacts on the Arctic, where warming is 42 occurring at least twice as rapidly as elsewhere on Earth (Miller et al. 2010; Box et al. 2019). The 43 increase in temperature is pressuring the cryosphere by melting sea ice and glaciers. The Arctic 44 region is expected to be free of sea ice in summer by the mid-21st century (IPCC, 2021). The 45 thinning and retreat of sea ice profoundly change trophic interactions at high latitudes by changing 46 47 landscapes (Post et al. 2013), animal interactions (Eamer et al. 2013; Macias-Fauria and Post 2018; Clairbaux et al. 2019), and resource availability (Søreide et al. 2010). Sea ice can be divided into 48 two large-scale components: pack ice (sea ice concentration (SIC) > 80%) and the marginal ice 49 zone (MIZ), which is the area of sea ice between the ice edge (SIC = 15%) and the edge of the pack 50 ice (Strong and Rigor 2013). The high density of fractured sea ice in the MIZ supports development 51 of ice algae and phytoplankton, which are key primary producers whose blooms are triggered by the 52 breakup of sea ice in spring and summer (Søreide et al. 2010). Primary producer blooms structure 53 the entire trophic network, from zooplankton community growth (Kohlbach et al. 2016) to the 54 timing of seabird reproduction (Ramírez et al. 2017). However, thinning of sea ice causes it to break 55 up early in the season, which can result in a phenological mismatch between bloom production and 56 predator requirements, especially for reproduction (Søreide et al. 2010; Arrigo and van Dijken 57 58 2015; Ramírez et al. 2017). Seabirds are widely recognised as good indicators of marine ecosystem health (Furness and 59 Camphuysen 1997; Dunphy et al. 2020; Grémillet et al. 2020; Wojczulanis-Jakubas et al. 2021). 60 Due to their high mobility and high trophic position, seabirds rely on large ocean areas for feeding. 61 They thus aggregate effects from multiple marine ecosystems phenomenons (Durant et al. 2009). 62 63 The rapid response of their population fitness enables monitoring of environmental changes related to ecosystem dynamics, prey availability, or the climate (Furness and Camphuysen 1997; Durant et 64 al. 2009; Grémillet and Charmantier 2010). In rapidly changing sea-ice landscapes, seabirds thus 65 seem to be excellent sentinel species to investigate the influence of changes in sea ice on marine 66

- 67 trophic networks. The global retreat of sea ice and a longer ice-free period each year could disrupt
- 68 prey availability around seabird breeding grounds, as shown, for example, for the Adelie penguin
- 69 (Pygoscelis adeliae; Michelot et al. 2020). Changes in sea ice could also provide new resources for
- seabirds (Korczak-Abshire et al. 2021). For example, in the absence of sea ice, little auks (*Alle alle*)
- can switch to foraging at nearby glacier meltwater fronts or at the shelf break (Grémillet et al. 2015;
- Amélineau et al. 2016), at the cost of relying on lower-quality prey (Steen et al. 2007).
- 73 Additionally, climate-induced behavioural changes explain most of the decrease in fitness reported
- 74 for several Arctic specialists, including little auks (Amélineau et al. 2019).
- 75 The ivory gull (*Pagophila eburnea*) is an endemic Arctic seabird that is closely associated with sea
- ice throughout the year (Spencer et al. 2014; Gilg et al. 2016). Ivory gulls breed on the ground or on
- 77 cliffs, in colonies of a few to hundreds of individuals in Greenland, Svalbard, Russia, and Canada.
- 78 Considered a generalist predator or opportunistic scavenger, ivory gulls concentrate on prey related
- 79 to sea ice (Divoky 1976; Mehlum and Gabrielsen 1993; Karnovsky et al. 2009), leftovers from
- 80 humans and large predators such as polar bears (*Ursus maritimus*) (Renaud and McLaren 1982),
- and occasionally small mammals (Karnovsky et al. 2009). The ivory gull is classified as "Near
- 82 Threatened" on the IUCN Red List (BirdLife International, 2020). Reports suggest that its
- populations have declined by 70% since the 1980s in Canada (Gilchrist and Mallory 2005) and by
- 40% in Svalbard (Norway) from 2009 to 2019 (Strøm et al. 2020), while trends are unclear in other
- breeding regions (Gilg et al. 2009; Gavrilo and Martynova 2017; Boertmann et al. 2020). These
- major declines highlight the fragile situation of these populations. The main threats identified for
- 87 ivory gulls are related to (i) a decrease in sea ice (i.e. ivory gulls' main habitat) due to global
- warming (Gilg et al. 2016; Spencer et al. 2016), (ii) contamination from persistent organic
- 89 pollutants and heavy metals through environmental exposure and bio-magnification (Braune et al.
- 2006; Miljeteig et al. 2009, 2012; Gaston et al. 2012; Bond et al. 2015; Lucia et al. 2015), (iii)
- 91 extensive development of human activities and associated pollution (e.g. oil or pollution spills from
- 92 resource extraction (oil, gas, mineral) and shipping routes in the Arctic) (Gilg et al. 2012;

93 Yurkowski et al. 2019), and (iv) extreme climatic events that decrease chick survival (Yannic et al.

94 2014).

The availability of miniaturised GPS trackers has helped understand the behaviour of seabirds (Wilmers et al. 2015; Brisson-Curadeau et al. 2017). Methodological frameworks that combine GPS data and advanced statistical methods to distinguish behavioural phases (e.g. resting, foraging, transiting) provide detailed information on the movement behaviour of seabirds. During the breeding season, the movement of breeding seabirds is strongly limited because they need to move back and forth to the nest continually (i.e. "central place foraging"; Orians and Pearson 1979). Consequently, however, colonial seabirds are thus restricted to forage in the same locations. This concentration of individuals results in sub-optimal foraging opportunities near the colony. In response to this increased competition, and to meet the food requirements of their chicks, individuals can adopt a dual foraging strategy (Weimerskirch et al. 1994; Steen et al. 2007). In this strategy, seabirds make frequent short trips to provide a steady supply of food to their chicks, but they feed themselves on longer trips by exploring areas far from the colonies, with more resources (Jakubas et al. 2012; Tyson et al. 2017). Trip characteristics thus show a bimodal distribution. To improve foraging efficiency, seabirds may also select areas where the availability of resources is spatially and temporally predictable (Patrick and Weimerskirch 2017; Courbin et al. 2018).

In environments with highly variable resources, seabirds often adopt a win-stay/lose-shift strategy to optimise their energy gain when foraging (Kamil 1983; Davoren et al. 2003; Weimerskirch 2007), whereas in areas with predictable resources, seabirds appear to know the productive locations and tend to feed preferentially in them to optimise their energy budget (Weimerskirch 2007). In the latter case, seabirds return regularly to the same foraging areas and therefore appear site-faithful to them (Wakefield et al. 2015). Colonial seabirds must also compete for access to resources. In a high-Arctic environment, snow and ice cover may hinder seabirds' access to marine resources, which makes them likely to develop site fidelity to the few favourable foraging areas.

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In the present study, we sought to understand the foraging strategies of Arctic seabirds in relation to ice features and human settlement, using ivory gulls as an example. To this end, we used highfrequency GPS transmitters to track the movements of ivory gulls in north-east Greenland. Because foraging opportunities in the Arctic are influenced by the availability of open water, distance to sea ice, and the potential presence of anthropogenic food, we made three hypotheses. First, we investigated the spatial strategies of ivory gulls by combining behavioural segmentation based on hidden Markov models (HMMs) with site-fidelity analysis. We hypothesised that during short trips, individual ivory gulls repeatedly forage in the same areas due to limited resource availability and predictability around the colonies. Thus, we expected high site fidelity and overlap among birds during short trips. Conversely, we hypothesised that longer trips have low site fidelity and overlap (H1). Following previous fieldwork by members of our team, we hypothesised that the Station Nord human settlement might affect ivory gulls- foraging behaviour. Due to the very predictable nature of this food source, it should be regularly visited by ivory gulls (H2). Finally, we analysed habitat selection to assess in more detail the foraging grounds used by ivory gulls. Based on previous studies and expert knowledge, we hypothesised that ivory gulls select habitat within the MIZ and near the sea ice edge when foraging (H3).

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2. MATERIALS AND METHODS

139 2.1. FIELD SITE AND DATA COLLECTION

Adult ivory gulls were caught at Station Nord (STN, 81.60° N, 16.66° W), a Danish military and research base in north-east Greenland, and at a nearby colony (81.60°N, 15.57°W; a complex of three sub-colonies located 18-25 km east of STN) in July 2018 (n=22 birds) and July 2019 (n=5 birds) (Fig. 1). In 2018, 15 of the birds were caught near the STN kitchen building, while the other 7 were caught at the colony. In 2019, all five birds were captured near the STN kitchen building. All birds were captured using baited traps or flap nets. Capture and handling procedures are fully described by Frederiksen et al. (2019, 2021). In brief, each captured bird was weighed using a

Pesola spring scale (to the nearest 5 g), measured (the head, and for some birds, also the gonys, tarsus, and wing, to the nearest mm; Yannic et al. 2016), and fitted with a metal ring (Zoological Museum, Copenhagen, Denmark) and an engraved Darvic colour ring (white or yellow, with a two-letter code in black). The combined mass of the two rings was 2.86 g. For birds caught at the colony, the breeding status was inferred from the presence of a chick in the nest. For birds caught at STN, the breeding status was unknown because all ivory gulls have a brood patch during the breeding season. Feathers were sampled for molecular sexing (Table S1). All 27 ivory gulls were tagged with RadioTag-14 solar GPS transmitters (Milsar Technologies SRL, Romania). They were attached with a leg-loop harness made from Teflon ribbon (Bally Ribbon Mills, USA) that was designed to fall off by itself after approximately one year. The combined mass of the GPS (10.4 g) and harness was 12.2 g, which represented $2.2 \pm 0.1\%$ (mean ± 1 standard deviation) of the mean body mass of tagged individuals. GPS data were remotely downloaded by a VHF base station when birds were within a ca. 5 km radius around the device. Of the 27 ivory gulls tagged with a GPS transmitter, only those whose GPS fixes were recorded at 5-min intervals were kept for analysis.

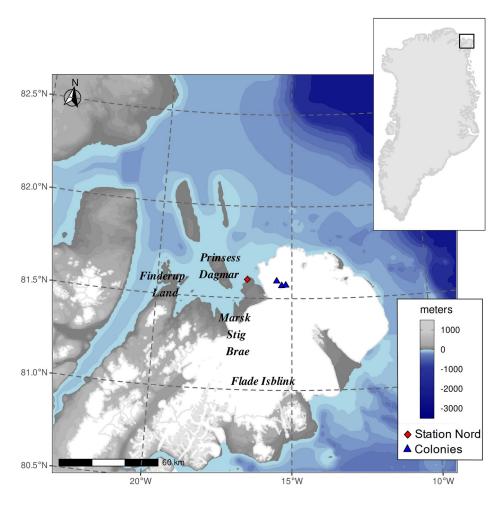


Figure 1. Map of the study site and the surrounding region. Blue and grey shading refers to bathymetry and altitude, respectively (Jakobsson et al. 2012). White areas are glaciers and icecaps (Raup et al. 2007).

2.2. DATA PROCESSING

GPS fixes collected within 24 h of capture were removed to exclude altered movement behaviours (Gupte et al. 2021). All GPS tracks were checked for missing data, which never exceeded 1% of a track. All locations collected after 15 August were also removed, as we considered that birds started displaying post-breeding dispersal behaviour around this date (Gilg et al. 2010). As the interval between GPS fixes can sometimes vary by a few dozen sec, which can influence subsequent analyses, each GPS tracks were divided into 300 sec (5 min) intervals (Table S1). For each bird tagged at STN, its breeding sub-colony was inferred from its GPS track, whereas the sub-colony was known for birds tagged at the colony. One bird (ID 931013) transmitted data for two

consecutive years, but in the second year, it showed no attachment to any sub-colony and was thus removed from all analyses except for habitat selection analysis. As only two of the seven birds captured at the colony and equipped with a transmitter returned data, we could not investigate differences between capture sites (i.e. STN vs. sub-colonies) (Fig. 1), which may represent a bias of our study. The small sample size also precluded testing the influence of sex on foraging behaviours and strategies.

2.3. FORAGING TRIPS

We defined trips as round trips of at least 1 h during which a bird flies further than 500 m from its sub-colony. For each trip, we calculated the duration, Euclidean distance between the sub-colony and the furthest point of the trip, and the total distance travelled during the entire trip. We used piecewise linear regression (i.e. breakpoint analysis) to assess whether ivory gulls performed dual foraging (i.e. the duration of short and long trips differs significantly). To this end, we used the segmented package (Muggeo 2020) of R software (R Core Team 2019) to solve the following equation: $furthest distance = \alpha \times \log(trip duration)$, with α a constant whose value differed on either side of the breakpoint. The duration threshold (D_{thresh}), at which α changed, was used in the analysis as the threshold between short and long trips.

To investigate the potential influence of breeding phenology on trip duration, we modelled the relationship between the duration of foraging trips and the day of year. We used a generalised additive model to detect non-linear changes in trip duration, which likely happen when birds change from incubation to chick rearing. Using the *gamm4* package (Wood and Scheipl 2020) of R, we fit trip duration as a function of the day of year, with the individual as a random effect on the intercept and slope to capture the influence of individual differences in phenology.

2.4. Behavioural segmentation

We defined individuals' behavioural states by fitting HMMs of the step length and the change in angle between steps (Morales et al. 2004) to the tracking data with the moveHMM package (Michelot et al, 2016) of R. Based on studies of seabird behaviour (Zhang et al. 2019; Harris et al. 2020; Dunphy et al. 2020), we developed a three-state model. Firstly, we defined a low-movement state that had a very short step length and, due to GPS error, a large change in angle between steps; because it likely corresponded to rest or feeding, we defined it as "rest". This state corresponded to birds remaining at the same location for a given amount of time. Because these two behavioural states have a similar movement signature, and the Arctic summer lacks a day/night cycle which could help distinguish these states (rest at night vs feeding during the day), we grouped both of them in the same state. Secondly, we defined a moderate-movement state with a moderate step length and large change in angle between steps, which likely corresponded to an "area-restricted search" (ARS) state, in which individuals were foraging. Finally, we defined a high-movement state with a long step length and small change in angle between steps, in which individuals were moving rapidly from one area to another (i.e. "transit"). We assumed gamma and von Mises distributions for the step length and angle between steps, respectively (Michelot et al. 2016). Twenty sets of random initial parameters were tested from a range of biologically plausible values (Table S2), following the procedure described by Michelot et al. (2016). The best segmentation, based on the maximum log-likelihood value, was selected for further analysis, and states were attributed using the Viterbi algorithm.

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2.5. INDIVIDUAL SITE FIDELITY AND INTER-INDIVIDUAL OVERLAP IN FORAGING AREAS During the breeding season, colonial seabirds exist in a competitive space. To understand how they share space and resources, we investigated individual site fidelity and the overlap among individuals' foraging areas. These two metrics were calculated separately for short and long trips to assess how dual foraging influenced the use of space. We included all GPS fixes of complete trips in the analysis. Foraging areas were defined as zones in which birds displayed ARS. Individual site

fidelity is the tendency for an individual to forage in the same location repeatedly (Switzer 1993; Piper 2011; Patrick and Weimerskirch 2017), whereas overlap among individuals' foraging areas indicates how birds aggregate or segregate in favourable foraging grounds (Masello et al. 2010; Sánchez et al. 2018). GPS fixes within a 2 km radius of each sub-colony were removed, as we assumed that gulls were not likely to forage there (GY, pers. obs.). Only GPS fixes defined as ARS by the HMM were kept in the analysis. We calculated the kernel utilisation distribution (UD) at a 1000 m resolution for (i) ARS locations of a single trip and (ii) all ARS locations visited by an individual across trips. We used Bhattacharyya's affinity (BA) index (Fieberg and Kochanny 2005) to assess UD overlap and site fidelity (Wakefield et al. 2015; Courbin et al. 2018). BA ranges from 0 (no overlap among UDs) to 1 (identical UDs). Based on Clapp and Beck (2015), BA indices were calculated for both 95% and 50% isopleths to quantify site fidelity at different scales. To compare overlap between the 95% and 50% UDs, their BA index values were rescaled to the [0, 1] interval by dividing them by the highest possible value (0.95 and 0.50, respectively). Individual site fidelity was the mean of the BA indices calculated for each pair of trips for the same individual. Overlap was calculated as the BA index between each individual's foraging areas. In both cases, short and long trips were compared separately. To rigorously interpret BA index values for site fidelity and inter-individual foraging overlap, we calculated BA index values under a null hypothesis (BA_{null}). We randomly reattributed foraging trips to 15 individual tracks and calculated individual site fidelity and inter-individual foraging overlap using the method described previously. This procedure was repeated 500 times. Site fidelity and inter-individual overlap values were then compared to their BA_{null} values using a Wilcoxon signed-rank test. The null hypothesis values and observed values were compared to assess whether the birds' site fidelity and inter-individual overlap differed from that expected by chance.

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2.6. INFLUENCE OF HUMAN SETTLEMENT ON THE USE OF SPACE

Ivory gulls are frequently observed at the STN settlement, either foraging or feeding on waste from

human activities. To better understand this behaviour, we estimated UDs of ivory gulls based on all GPS fixes using the biased random bridges (BRB) method (Benhamou 2011) implemented in the adehabitatHR package (Calenge, 2006) of R. BRB is based on sequential spatio-temporal correlation of animal tracks, which provides mechanistic understanding of UDs. It can be separated into an intensity distribution (i.e. the mean amount of time spent in a given area) and a recursion distribution (i.e. the proportion of total visits to a given area) (Benhamou and Riotte-Lambert 2012). The *maxt* parameter (i.e. the maximum amount of time a bird could spend outside a patch before considering re-entry into the patch as a separate event) was set to 30 min. As we were interested in foraging events, we wanted to avoid considering erratic movement around an area as multiple visits. The *hmin* parameter (i.e. minimum smoothing) was set to 300 m. Intensity and recursion distributions were calculated for each individual at a 1000 m resolution. The proportion of time spent at STN per individual was determined using the intensity distribution. The proportion of revisits within 500 m of STN was estimated using the recursion distribution. We determined intensity and recursion distributions for each individual in a 500 m radius around STN. We considered that potential attraction of ivory gulls to STN would be indicated by a large percentage of the time budget spent at STN (intensity distribution) and many revisits (recursion distribution). To investigate this, we used the recurse package (Bracis et al., 2018) of R to calculate revisits to STN to forage and the time between them. Ivory gulls were assumed to forage at STN when they were within 500 m of STN and in an ARS behavioural state.

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Based on our hypothesis that STN is a focal point for foraging ivory gulls, we expected to find a large percentage of rest and ARS behavioural states near STN. We calculated these percentages in a 500 m radius around STN and used a randomisation procedure to estimate the percentages of states expected by chance in the population. For each GPS fix of the tracked gulls, we calculated the percentage of states within 500 m of the fix. We then used the mean percentage of each step as the sample mean and compared these means to those observed near STN.

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2.7. MARINE HABITAT SELECTION

We used resource selection functions (RSF) to explore the marine habitat selection of ivory gulls at sea (Manly et al. 2002, Muff et al. 2020). All GPS fixes on land (AMSR2 land mask, 10 km × 10 km grid) were excluded. Due to a lack of variables for land-based resource availability, we inferred habitat selection at sea using the 44,875 GPS fixes obtained in 2018 and 2019. RSF compares the environmental attributes of observed GPS fixes ("used") to those of locations randomly sampled within likely reachable areas ("available"). To obtain a comprehensive sample of available habitats, we used a 1:10 ratio for used:available locations for each individual. According to this ratio, for each observed location, 10 available locations were created with the same attributes as the observed one (behavioural states, date, individual ID). We considered the non-random distribution of available area due to the central place foraging behaviour of ivory gulls by applying a circular bivariate exponential distribution centred on the centroid of the sub-colonies each year, with a radius equal to the furthest GPS fix observed within the 95% UD isopleth (628.6 km) (Monsarrat et al. 2013; Grémillet et al. 2020). Because ivory gulls ignored areas south-west of the sub-colonies, the availability distribution was truncated to the 1st-99th percentiles for a circular distribution, using the *circular* package (Agostinelli and Lund, 2022) of R. Three continuous environmental variables were used to fit the RSF: (i) bathymetry (m) at a 500 m resolution based on the International Bathymetric Chart of the Arctic Ocean (Jakobsson et al, 2012); (ii) SIC (percentage per cell) at a 10 km resolution from the AMSR2 daily SIC product of the EUMETSAT Ocean and Sea Ice Satellite Application Facility (http://www.osi-saf.org); and (iii) distance to the edge of sea ice (km, dist2edge) (i.e. nearest cell with 15% SIC), also from the AMSR2 SIC product (Pang et al. 2018). The dist2edge was positive when gulls were on ice and negative when they were on open water (Gilg et al. 2016). To avoid having missing data when exploiting the high temporal frequency of SIC maps, SIC and dist2edge were averaged over a 3-day

sliding window centred on the GPS fix date. All three variables were mean centred and divided by their standard deviation to facilitate model convergence. RSFs were fitted with a generalised linear mixed model with binomial errors using the *qlmmTMB* package (Brooks et al, 2017) of R. The use-availability likelihood of RSF was maximized fitting a logistic regression (McDonald, 2013). Within a species, many characteristics are likely to vary among individuals. To represent individual differences and bias in habitat selection, we used random intercepts for individuals and random slopes for predictors, following statistical recommendations of Muff et al. (2020). To represent non-linear responses, we used a spline with four degrees of freedom for all environmental predictors. The variables for which we estimated a non-linear response were selected using the Akaike information criterion. To represent behaviour-specific habitat selection, we considered the behavioural states defined by the HMM as a factor that interacted with all environmental variables. During the ca. 2-month study period each year, the day of year may have influenced habitat selection through factors such as breeding stage or weather. To consider temporal changes during the study period, the day of year was thus considered a random effect nested within each year.

$$\omega(x_{ij}) = exp(\beta_0 + (\beta_{bathy}bathy_{ij} + \beta_{dist2edge}dist2edge_{ij} + \beta_{SIC}xSIC_{ij})\beta_s stateHMM_{ij} + \gamma_{0j} + \gamma_{0yd} + \gamma_{bathy,j} + \gamma_{dist2edge,j} + \gamma_{SIC,j})$$
Eq. (1)

The RSF model estimated the relative probability of selection ($\omega(x_{ij})$), expressed as a binary vector for the i^{th} location and j^{th} gull tracked (Eq. 1), where β_0 is the mean intercept; β_{bathy} , $\beta_{dist2edge}$, and β_{SIC} are fixed-effect coefficients for bathymetry, dist2edge, and SIC, respectively; β_s is the coefficient for stateHMM in state s; γ_{0j} and γ_{0yd} are random intercepts for individual j and day of year yd, respectively; and $\gamma_{bathy,j}$, $\gamma_{dist2edge,j}$, and $\gamma_{SIC,j}$ are random slope coefficients for the corresponding predictors for gull j.

Model robustness was assessed using 30 runs of k-fold cross-validation. For each run, the complete

dataset was randomly split into a training set (80% of the individuals) and a testing set (the remaining 20%). We calculated RSF probabilities for the training dataset and split them into ten bins (area-adjusted frequency). We then calculated the Spearman rank correlation between the rank of the bins and the frequency of the RSF probabilities calculated for the testing set in each bin. A mean Spearman rank correlation close to 1 indicated high capacity to predict ivory gull distribution (Boyce et al. 2002).

All analyses were performed using R software 3.5.3 (R Core Team 2019). All results are presented as mean \pm standard deviation, unless stated otherwise.

342 3. RESULTS

3.1. FORAGING TRIP DESCRIPTION

We tracked a total of 15 birds (13 only in 2018 and 2 only in 2019). One bird tagged in 2018 was tracked in both 2018 and 2019, but the second year of tracking was used only for RSF analysis. This yielded a total of 16 summer tracks. See Table S1 for information on the individuals tagged. Ivory gulls made a total of 356 trips (23.7 \pm 18.9 trips per bird) (306 in 2018 and 50 in 2019). The piecewise linear regression yielded a D_{thresh} of 18.2 h (Fig. 2a). By rounding, we thus considered trips shorter than 18 h as "short" and those longer than 18 h as "long", regardless of the distance travelled. The slope between trip duration and distance was five times as high for long trips as for short trips (Fig. 2a), which showed that long trips had a longer maximum distance per unit of time. See Table S3 for basic summary metrics, such as the duration, furthest distance reached, and total distance of ivory gull trips. Of the 16 birds studied, 3 never took short trips (mean = 20.3 \pm 18.0, min = 0, and max = 50 short trips per individual), whereas all 16 took at least one long trip (mean = 3.4 \pm 2.2, min = 1, and max = 8 long trips per individual). The proportion of short and long trips varied among individuals (Fig. S1), but the mean proportion of short or long trips for the 16 birds was 0.85 and 0.15, respectively. Day of year influenced trip duration (p < 0.05), but explained only a small part of it (R² = 0.05), with high variability among individuals. Thus, it is unlikely that

breeding stage had a significant effect.

We identified two main foraging areas that ivory gulls used during short trips: (i) the coasts of the mainland (around STN) and islands and (ii) the Marsk Stig Bræ tidewater glacier front (Fig. 3a). A large lead to the north-east between the fjord system and the open sea was also used for foraging, but less intensively. During long trips, ivory gulls used multiple areas on the pack ice or in the MIZ near the North-East Water Polynya (Fig. 3b).

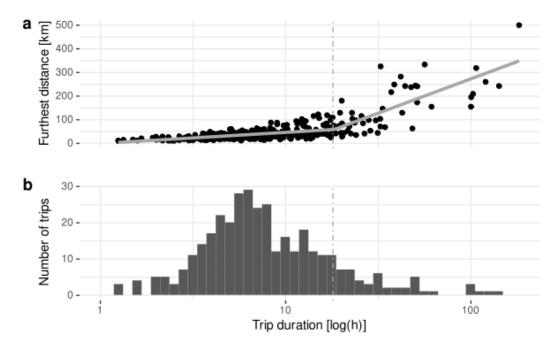


Figure 2. Characteristics of ivory gull trips as a function of trip duration. (a) Piecewise linear regression of the furthest distance reached during a trip as a function of trip duration, for short trips (left of the threshold of 18 h, vertical grey line) and long trips (right of the threshold). (b) Number of trips as a function of trip duration.

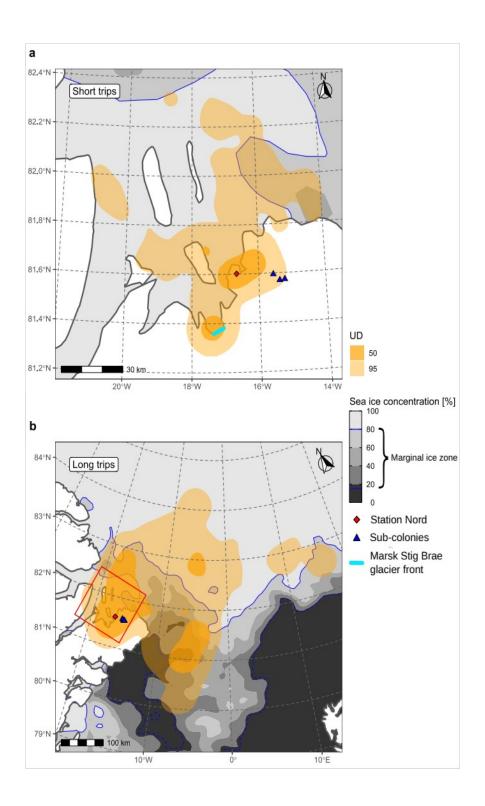


Figure 3. Areas that ivory gulls used for foraging in north-east Greenland during (a) short (< 18 h) and (b) long (>18 h) foraging trips. Short trips were concentrated at glacier fronts, coastal leads, or nearby pack ice in areas of high sea ice concentration (SIC), whereas long trips were concentrated on areas with variable SIC along the ice edge in the North-East Water Polynya, and over pack ice.

Dark and light yellow shading represents 50% and 95% UD of foraging areas, respectively. The map shows sea ice concentration for 31 July 2018. The red rectangle in (b) shows the extent of (a).

3.2. Individual site fidelity

Ivory gulls showed site fidelity during short trips, with BA indices higher than those expected by chance (50% UD BA index = 0.28 ± 0.17 , N_{obs} = 15, P < 0.001, Fig. 4; 95% UD BA index = 0.44 ± 0.24 , N_{obs} = 15, P < 0.001, Fig. ESM1).Conversely, ivory gulls did not show site fidelity during long trips (Fig. 4). This pattern was consistent for both the 50% and 95% UD.

3.3. Inter-individual overlap in foraging areas

Suitable foraging areas around STN were rare and limited mainly by coastal ice, which restricted access to marine prey. During short trips, BA_{null} indices were high (50% UD BA_{null} index = 0.79 \pm 0.04, Fig. 4; 95% UD BA_{null} index = 0.82 \pm 0.03, Fig. ESM1), indicating that under the null model, individuals were expected to share most of their foraging areas with each other. However, individual ivory gulls tended to use different foraging areas, as shown by lower observed BA indices (50% UD $BA_{observed}$ index = 0.36 \pm 0.26, N_{obs} = 12, P < 0.001, Fig. 4; 95% UD $BA_{observed}$ index = 0.56 \pm 0.22, N_{obs} = 12, P < 0.001; Fig. ESM1) than under the null hypothesis, which indicated spatial segregation between individuals during foraging (Fig. 4).

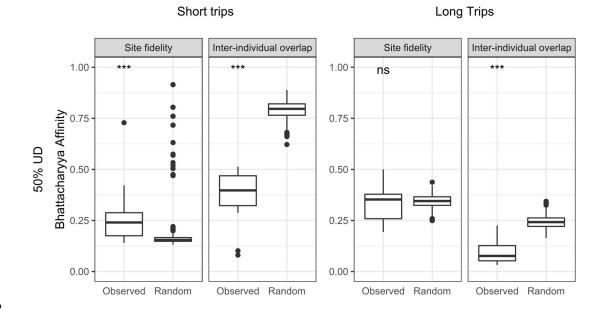


Figure 4. Bhattacharyya's Affinity (BA) index for individual site fidelity and utilisation distribution

(UD) overlap among individuals' foraging areas during (left) short (< 18 h) and (right) long (> 18 h)

trips into core foraging areas (50% UD). "Observed" refers to the BA index observed for individual

ivory gulls, whereas "Random" refers to the BA index based on random trips (BA_{null}). Observed and

random BA indices were compared using the Wilcoxon-signed-rank test (significance levels: ns =

non-significant, *** < 0.001). Whiskers equal 1.5 times the interquartile range.

The larger areas explored by ivory gulls during long trips, mainly the ice edge north of the North-East Water Polynya and the pack ice east of STN (Fig. 2b), led to a smaller spatial segregation of individuals. A significant difference was observed during long trips between BA_{null} indices (50% UD BA_{null} = 0.24 ± 0.03 , Fig. 4; 95% UD BA_{null} = 0.41 ± 0.04 , Fig. ESM1) and observed BA indices (50% UD BA_{observed} = 0.09 ± 0.13 , min = 0, max = 0.53, N_{obs} = 15, P < 0.001, Fig. 4; 95% UD BA_{observed} = 0.34 ± 0.24 , N_{obs} = 15, P < 0.001; Fig. ESM1). Thus, ivory gulls also showed spatial segregation during long trips.

3.4. INFLUENCE OF HUMAN SETTLEMENT ON THE USE OF SPACE

Among the 16 tracked birds, 3 (including the 2 tagged at the colony) never came close enough to STN (i.e. within 500 m) to be considered as visiting it. For the 13 birds tagged at STN, all but 1 spent time there. The gulls visited STN in 43% of the short trips and 45% of the long trips. A total of 160 trips (45% of the total) were visits to STN. Ivory gulls spent $16.1\% \pm 24.4\%$ of their time at STN (min = 3.2%, max = 100.0%) and frequently revisited it $(13.02\% \pm 26.90\%$ (min = 0.12%, max = 100.00%) of revisits were to STN). Based on the recursion distribution of the population (Fig. 5a), ivory gulls made 271 revisits to forage at STN (mean 18.1 ± 13.2 visits per individual), which yielded a mean of 5.4 ± 3.4 visits per week of tracking per individual. Gulls remained at STN a mean of 0.9 ± 1.1 h (min = 0.02 h, max = 6.2 h). In total, ivory gulls spent 192.9 h at STN. At STN, the percentage of rest, ARS, and transit was 44.8%, 53.4%, and 1.8%, respectively. For rest

and ARS, these percentages at STN were much higher than those for all tracked gulls (31.0% and 39.4%, respectively). Conversely, the transit state occurred only for 1.7% of the tracked gulls at STN, compared to 29.5% of the all tracked gulls (Fig. 5b). Thus, the birds displayed behavioural states related to feeding or foraging during most of their time at STN. Thus, compared to other areas, STN was more a location that ivory gulls visited to forage than to transit.

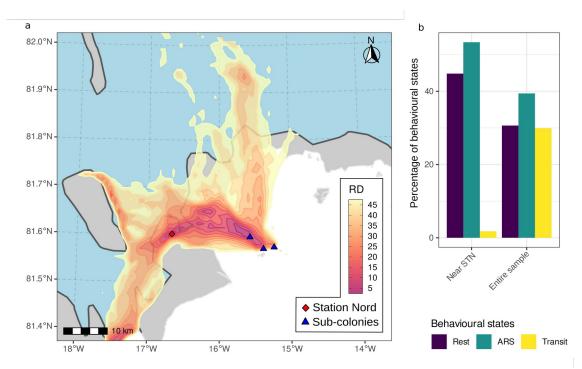


Figure 5. Use of space around Station Nord (STN) and its influence on ivory gull behaviour. (a) The 0-50% recursion distribution (RD) interval for all foraging trips, which illustrates areas that ivory gulls frequently visited. White areas are glaciers (Raup et al. 2007). (b) The percentage of time that ivory gulls spent within 500 m of STN per behavioural state. ARS: area-restricted search

3.5 BEHAVIOUR-SPECIFIC MARINE HABITAT SELECTION

The RSF showed that bathymetry, distance to the sea ice edge, and SIC significantly influenced the marine habitat selection of ivory gulls. The distance to the sea ice edge was the only explanatory variable for which a non-linear effect was retained. The influence of behaviours on habitat selection was significant but often weak for all variables, except for SIC, for which no difference in selection was observed between the rest and transit states (p = 0.09). The influence of the ARS and transit

states on habitat selection was also weak, with almost no difference in selection between them, whereas "rest" had a positive influence on bathymetry and SIC selection (Fig. 7). The model was robust to cross-validation (mean Spearman rank correlation: 0.60 ± 0.07). Ivory gulls strongly selected high SIC from the upper edge of the MIZ (SIC = 70-80%) to pack ice (> 80%), but they did not select areas with SIC less than 60% (Fig. 6a). The gulls strongly selected areas over sea ice rather than over the open sea, with a peak in the relative probability of selection over ice 50-60 km from the ice edge (Fig. 6b). Conversely, the relative probability of selection decreased sharply over the open sea, falling to zero 50 km from the ice edge. Ivory gulls selected coastal areas, with increased relative probability of selection for areas with depths of 0-500 m (Fig. 6c). Gulls showed no affinity for the deep sea and rarely selected areas deeper than 1000 m (Fig. 6c). Core foraging areas for individuals during short trips were located mainly in coastal areas or over the Greenland ice shelf, with high SIC and far from the ice edge (Fig. 3). Conversely, long trips focused on deeper areas with a variety of SIC located in the Fram Strait and North-East Water Polynya, within the MIZ and pack ice (Fig. 3).

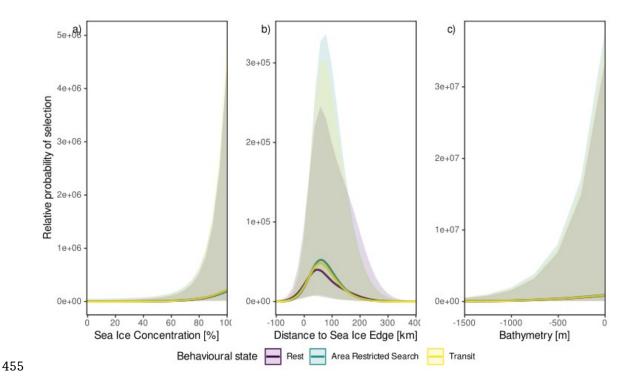


Figure 6. Relative probability of habitat selection as predicted by the resource selection function model for (a) sea ice concentration (percentage of ice at a 10 km resolution), (b) distance to the sea ice edge (negative = over open sea, positive = over sea ice), and (c) bathymetry. Colours indicate different behavioural states defined by a three-state hidden Markov model (rest, area-restricted search, and transit). Shaded area represent the 95% confidence interval.

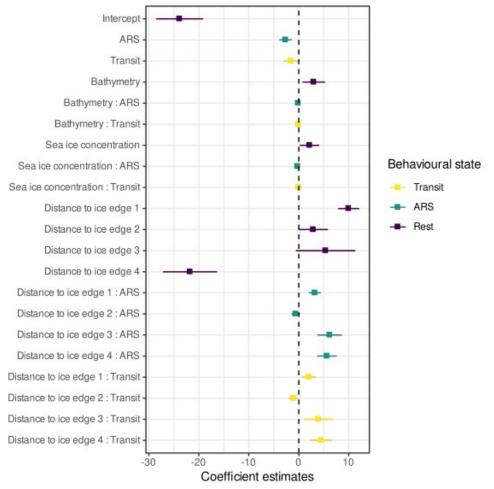


Figure 7. Mean and 95% confidence intervals of coefficients associated with the resource selection function. Colours indicate different behavioural states. ARS = area-restricted search

4. DISCUSSION

The present study provided rare insight into the foraging behaviour of seabirds at high latitudes. We confirmed that ivory gulls use a dual foraging strategy and highlighted their differing spatial strategies during short and long trips. When making short trips, ivory gulls appeared to be site faithful but segregated in space, with individual-specific foraging areas. This finding strengthens the hypothesis that dual foraging is also a strategy for decreasing competition among colonial seabirds. Furthermore, most birds in the study visited and regularly returned to STN to forage, which confirms that human settlement in the Arctic can provide food sources for seabirds. Finally, we provide additional details about habitat selection by ivory gulls while at sea that confirm their affinity for high-concentration patches in the pack ice.

4.1. IMPLICATION OF DUAL FORAGING FOR ARCTIC SEABIRDS

Many seabird populations use a dual foraging strategy, alternating short and long foraging trips in response to the energetic cost of rearing chicks (Welcker et al. 2009; Wojczulanis-Jakubas et al. 2010). In the present study, we did not observe a clear bimodal distribution of trip duration, as observed for little auks (Welcker et al. 2009) or Manx shearwaters (*Puffinus puffinus*; Shoji et al. 2015). However, ivory gulls did make short and long foraging trips during the breeding season. The long trips were notable for their duration and destinations, which focused mainly on distant areas in the pack ice and the MIZ, where overlap among individuals, and thus intra-colony competition, was low.

For little auks, dual foraging enables individuals to gain mass during the breeding season, whereas short trips focus mainly on delivering food to chicks (Welcker et al. 2012; Jakubas et al. 2014).

Little auks forage in distant areas regardless of local foraging conditions, which suggests that dual foraging is unrelated to the local environment, but is likely related to local competition, resource availability, and physiological constraints (Wojczulanis-Jakubas et al. 2010). In the harsh environment around ivory gull colonies in north-east Greenland, favourable foraging areas are rare and located mainly at the land-sea interface (coast and glacier fronts) and in the MIZ. The availability of favourable foraging grounds is therefore limited, which increases competition among individuals. Spatial segregation of individuals in different foraging areas is likely a response to the limited access to resources that enables individuals to decrease competition. Ivory gulls were sitefaithful to the foraging grounds used during short trips. Competition for resources is not likely the only explanation for site fidelity, however, because the latter is driven by several factors, including previous foraging success, personality, and shared social information on the location of resources (Carroll et al. 2018; Harris et al. 2020). Site fidelity of ivory gulls in north-east Greenland is probably reinforced by the predictability and higher productivity of annual coastal cracks or

tidewater glacier fronts than of the offshore pack ice, which has thicker ice that makes accessing marine resources more difficult (Lee et al. 2010). Coastal cracks and glacier fronts are major features of the landscape in the Arctic and are spatially stable over several years. Conversely, ivory gulls did not show site fidelity to foraging areas during long trips, for which ice features are more likely less predictable, with locations that change each year or during the breeding season. Over pack ice, ivory gulls are known to feed on polar bear kills, whose spatial and temporal distribution is likely highly unpredictable. Foraging for unpredictable prey could explain why ivory gulls explored larger areas during long foraging trips, as covering large area increases the chances of finding resources. Thus, these long trips could be more exploratory than short trips, which agrees with findings of Paiva et al. (2010).

4.2. FORAGING AREAS AND THE SPATIAL STRATEGY OF IVORY GULLS IN NORTH-EAST

Greenland

Using a null-model framework, we simulated which strategies ivory gulls would implement if they behaved randomly. Surprisingly, under this framework, ivory gulls should have low site fidelity and high overlap during short trips, and medium site fidelity and low overlap during long trips.

However, we observed that the gulls used different strategies. The gulls used mainly two foraging areas during short trips. Although most foraged at least partially in one of the areas (*i.e.* the strait between STN and Princess Dagmar Island), spatial segregation occurred within our sample, as indicated by the lower foraging overlap observed than that of the null model. Individuals were spatially specialised and used different areas than their conspecifics (*e.g.* individuals foraging almost exclusively on a glacier front or along a large lead in the ice to the north-east of STN).

Moreover, individuals appeared to be site-faithful during short foraging trips, which reinforced their spatial specialisation. These results partially support our second hypothesis. Although ivory gulls did not aggregate during short trips, as was expected due to the local nature of the resources, but tended to be spatially segregated, they did disperse during longer foraging trips (H2). Furthermore,

site fidelity was observed only during short trips, for which resources are likely more predictable than during long trips. Whether these strategies are only a spatial phenomenon or are related to individual diet specialisation remains unclear, as the ivory gull is usually considered a generalist species, even though hypotheses about individual specialisation have emerged (Karnovsky et al. 2009). However, specialised individuals within a generalist population have been observed for other seabirds, such as Antarctic petrels (*Thalassoica antarctica*; Tarroux et al. 2020) and Scopoli's shearwaters (*Calonectris diomedea*; Courbin et al. 2018). Combining isotopic niche analysis and spatial analysis of foraging strategies at population and individual levels could help distinguish whether ivory gull site fidelity is related to prey specialisation and individual trophic niche specialisation within a generalist species (Bonnet-Lebrun et al. 2018; Courbin et al. 2018).

4.3. INFLUENCE OF ANTHROPOGENIC SUBSIDIES ON ARCTIC SEABIRDS

Anthropogenic food resources modify the behaviour and foraging strategies of opportunistic scavengers (Cama et al. 2012; Patrick et al. 2015), which may influence a population's long-term survival (Fluhr et al. 2017). The few human settlements in the high Arctic could provide an important source of anthropogenic food for some seabirds compared to the surrounding natural habitats. This has been observed for ivory gulls in Canada (Thomas and MacDonald 1987; Mallory et al. 2003). We found that STN is an attractive location for ivory gulls in north-east Greenland, as they frequently return there to forage. Due to their high spatial and temporal predictability, anthropogenic subsidies attract mammals and seabirds worldwide (Plaza and Lambertucci 2017), especially gulls (Lenzi et al. 2019), and can represent a large part of an animal's diet in an environment with low resource availability (Savory et al. 2014). However, the food available for opportunistic birds at STN – garbage and sewage from the kitchen, as well as leftover dog food – has decreased in the past few decades. A new sewer system and waste incinerator, as well as changes in the management of dog food, reduced leftovers, which has reduced the amount of anthropogenic subsidies in recent years (OG and GY, pers. obs.). Nevertheless, foraging birds

frequently visit STN, indicating that it remains an attractive place to forage, although the ivory gull colony has moved a few km further from STN over the past decade (Gilg et al. 2009; Frederiksen et al. 2019). We may have overestimated the influence of STN on ivory gulls, however, as birds observed at STN tended to return regularly, whereas many birds from the colonies have likely never visited STN. The few birds observed daily at STN during the breeding season (n << 10, with a high proportion of resightings; authors, pers. obs) contrasts with the 120-130 ivory gull pairs that bred in the sub-colonies in 2018 (Frederiksen et al., 2019) and 2019 (Boertmann et al., 2019). When considering all of the birds tagged with GPS transmitters in 2018 and 2019, data from 16 of the 20 birds tagged at STN (80%) were retrieved, although we included only 14 of them in the study. For gulls tagged in the colonies, only 30% of their transmitters (2 out of 7) transmitted data for more than 24 h. Because the main base station used to collect GPS data was located mainly at STN, it is likely that most birds tagged at the colony did not visit STN, or did so briefly.

4.4. RESOURCE SELECTION BY IVORY GULLS AT SEA

A high-frequency GPS dataset of ivory gull tracks and a robust validated RSF assessed in a dynamic temporal framework provided strong evidence that ivory gulls select highly concentrated sea ice (>60%) when foraging at sea during the breeding season. This was partially expected based on the first hypothesis (H1); however, ivory gulls used a wider range of SIC than that hypothesised, as they used areas with SIC that included the upper limit of MIZ (60-80%) to pack ice (>80%). These results are consistent with those of Gilg et al (2016), which were similar for year-round ARGOS tracking of ivory gulls from different colonies in the Arctic. However, we highlight that birds in the present study selected marine habitats with a small but significant influence of certain behavioural states (i.e. rest, ARS, and transit) during the time at sea. We also observed that ivory gulls selected relatively shallow areas, which are common around STN.

4.5. SEABIRD USE OF TIDEWATER GLACIER FRONTS IN THE ARCTIC

Our study also highlighted that ivory gulls forage at tidewater glacier fronts, which agrees with previous studies of ivory gulls (Renaud and McLaren 1982; Lydersen et al. 2014), black-legged kittiwakes (Rissa tridactyla) (McLaren and Renaud 1982; Lydersen et al. 2014; Bertrand et al. 2021), or northern fulmars (Fulmarus glacialis) (McLaren and Renaud 1982; Nishizawa et al. 2020). High concentrations of surface-feeding seabirds foraging at glacier fronts have been observed in the Arctic (Hartley and Fisher 1936; Irons 1998), including large flocks of ivory gulls (Renaud and McLaren 1982). Tidewater glacier fronts usually provide more stable foraging habitats for surface feeders than certain climate-induced ephemeral habitats (Grémillet et al. 2015). Foraging in these areas is facilitated by the discharge of nutrient-rich freshwater from the bottom of the glacier, which causes upwelling and forces zooplankton upward in the water column, which increases productivity (Apollonio 1973; Arimitsu et al. 2016; Arrigo et al. 2017) and kills plankton via osmotic shock (Hartley and Fisher 1936). Climate-induced continental glacier melt is likely to maintain the attraction of tidewater glacier fronts for seabirds and even increase the discharge of freshwater into the ocean (Mu et al. 2020; Nishizawa et al. 2020). However, climate change is a long-term threat to this habitat, as continental glaciers are currently losing mass, and this loss is amplified by the decrease in sea ice (Liu et al. 2016; Pedersen and Christensen 2019). Foraging at tidewater glacier fronts is likely to remain stable in the short-to-medium term, and might allow seabird populations to temporarily buffer the impact of climate change on sea ice, as Grémillet et al. (2015) observed for little auks.

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4.6. IMPORTANCE OF SEA ICE AND IMPACT OF CHANGES IN SEA ICE FOR SEABIRDS

Along with changes in glacier runoff, and despite rapid changes in the extent and thickness of
glaciers, sea ice remains the most attractive foraging area for most ivory gulls, which forage over
high-concentration patches of sea ice. The opening of cracks in previously dense, multiyear sea ice
provides new foraging opportunities for breeding birds, especially in coastal areas around colonies.

As mentioned, this is likely to temporarily delay the impact of climate change on Arctic marine ecosystems. The main threats to breeding seabird populations in the Arctic will be changes in the timing of the planktonic bloom and the continuous northward retreat of the MIZ (Rolph et al. 2020). Due to climate change, sea ice breaks up earlier in many parts of the Arctic (Johnson and Eicken 2016; Kowal et al. 2017). This could result in a mismatch between breeding phenology (e.g. egg laying, chick rearing) and the peak of the planktonic bloom, making it difficult for adults to feed themselves and their chicks, which could a decrease survival. The mismatch between the supply of resources and the demand of breeding adults is a major threat of climate change, as it decreases adult survival and influences population demographics (Thomas et al. 2001; Durant et al. 2007; Gilg et al. 2012). Seabirds are already responding to changes in ice phenology, but earlier laying dates are strongly influenced by individual experience and thus vary within a population (Descamps et al. 2019; Sauve et al. 2019). Even if seabirds adapt their breeding phenology, stochastic changes in climatic conditions in the Arctic, such as a switch from snowfall to rainfall in summer during the breeding season, can have a dramatic influence on recruitment (e.g., Yannic et al. 2014). Ivory gulls forage over high-concentration patches of sea ice, even around their colonies. In the context of climate change, these areas may move northward, forcing the birds to switch to other foraging areas (Grémillet et al. 2015) or to make longer trips, which increases the time, distance, and energetic cost of travel between foraging grounds and colonies, whereas seabirds already struggle to balance an increase in the duration of foraging trips without reducing the rate of feeding chicks (Welcker et al. 2009). An unbalanced energy budget may decrease adult fitness and chick survival (Kidawa et al. 2015; Kitaysky and Hunt 2018; Duffy-Anderson et al. 2019). This has likely contributed to the decline observed in ivory gull colonies in south-east Greenland, Canada, and Svalbard (Strøm et al. 2019). Despite our study of ivory gull habitat selection during foraging trips and previous studies of their feeding habits (Karnovsky et al. 2009), there is a lack of precise knowledge about the pagophilic organisms that ivory gulls prey upon and the importance of scavenging in their diet. Further

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investigation using alternative approaches (e.g. isotopic analyses, meta-barcoding of the diet) is thus required to better understand the role of sea ice habitats on ivory gulls' diet.

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5. CONCLUSION

Using fine-scale spatial and temporal tracking of ivory gulls, we analysed the foraging strategies and habitat selection of high-Arctic seabirds in relation to sea ice. Although our study was limited to the breeding season of the ivory gull in north-east Greenland, we could not confirm whether the tracked birds were actively breeding or the phenological influence of breeding on their behaviour. This is a major caveat of our study, as breeding is most likely to influence seabirds' foraging strategies due to the energy that it requires. We performed robust analysis of spatial strategies (site fidelity and foraging area overlap) and habitat selection to provide relevant insight into Arctic seabirds' foraging behaviour during the breeding season, which is a vital period for all species. Our results highlight that human settlements and glacier fronts are attractive foraging grounds for this Arctic seabird species. Opportunities for new temporary food subsidies will most likely increase in the near future for opportunistic species such as the ivory gull, while its main natural habitat – sea ice – will continue to shrink. Nonetheless, the relative contribution of anthropogenic and natural subsidies in the ivory gull diet should be investigated to accurately assess the short- and long-term influence of anthropogenic subsidies on bird fitness. We focused on ivory gulls from north-east Greenland during the breeding season, and such studies should be extended to encompass the entire Arctic breeding range of the species.

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661 COMPLIANCE WITH ETHICAL STANDARDS

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- 665 1210"].
- 666 CONFLICTS OF INTEREST
- All authors declare that they have no conflict of interest.
- 668 AVAILABILITY OF DATA
- Part of the dataset analysed in the present study is available in the MOVEBANK repository
- 670 (Movebank ID: 1123149708). The rest of the dataset is available on request, and will be made
- available on MOVEBANK upon publication.
- 672 AUTHORS' CONTRIBUTIONS
- KD and GY designed the study, with input from OG and MF. GE, MF, and GY performed
- 674 fieldwork and collected data. KD analysed the data with help from NC and input from ACC. KD
- led the writing of the manuscript. All authors commented on previous drafts and approved the final
- 676 manuscript.
- 677 ETHICS APPROVAL
- This project was approved by the Government of Greenland (Permits Nanoq ID No. 7708144
- 679 (2018), Nanoq ID No. 8246959 (2018), and Nanoq ID No. 10615955 (2019)).

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