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A TRULY TWO-DIMENSIONAL, ASYMPTOTIC-PRESERVING SCHEME FOR A DISCRETE MODEL OF RADIATIVE TRANSFER

LAURENT GOSSE*∗* AND NICOLAS VAUCHELET*†*

Abstract. For a four-stream approximation of the kinetic model of radiative transfer wih isotropic scattering, a numerical scheme endowed with both truly-2D well-balanced and diffusive asymptotic-preserving properties is derived, in the same spirit as what was done in [14] in the 1D case. Building on former results of Birkhoff and Abu-Shumays, [4], it is possible to express 2D kinetic steady-states by means of harmonic polynomials, and this allows to build a scattering *S*matrix yielding a time-marching scheme. Such a *S*-matrix can be decomposed, as in [15], so as to deduce another scheme, well-suited for a diffusive approximation of the kinetic model, for which rigorous convergence can be proved. Challenging benchmarks are also displayed on coarse grids.

Key words. Diffusive scaling; Four-stream approximation; Grey radiative transfer; *S*-matrix.

AMS subject classifications. 31A05, 65M06, 76R50, 82B40, 85A25.

1. Introduction and preliminaries.

1.1. Kinetic modeling in 2D. We are interested in a "truly two-dimensional" numerical simulation of the simple kinetic model, where $\mathbf{x} = (x, y)$ and $\mathbf{v} = (\xi, \eta)$,

$$
\partial_t f(t, \mathbf{x}, \mathbf{v}) + \mathbf{v} \cdot \nabla_{\mathbf{x}} f = \sigma(\mathbf{x}) \left(\int_{\mathbb{S}^1} f(t, \mathbf{x}, \mathbf{v}') \frac{d\mathbf{v}'}{2\pi} - f \right), \qquad |\mathbf{v}| = 1.
$$

in particular, of its "four-stream approximation", evoked in *e.g.* [17, §5] or [9],

$$
\partial_t f^{\pm} \pm \partial_x f^{\pm} = \sigma(x, y)(\rho/4 - f^{\pm}), \qquad \partial_t g^{\pm} \pm \partial_y g^{\pm} = \sigma(x, y)(\rho/4 - g^{\pm}), \qquad (1.1)
$$

where the "opacity" $\sigma(x, y) \geq 0$ and the macroscopic density simplifies into,

$$
\forall t, \mathbf{x} \in \mathbb{R}^+ \times \mathbb{R}^2, \qquad \rho(t, \mathbf{x}) = f^+(t, \mathbf{x}) + f^-(t, \mathbf{x}) + g^+(t, \mathbf{x}) + g^-(t, \mathbf{x}).
$$

In order to take full advantage of a 9-points, so–called *Moore*, stencil, microscopic velocities are rotated so as to be aligned with the diagonals of a Cartesian grid,

$$
\mathbf{v} = \left(\frac{\pm 1}{\sqrt{2}}(1,1), \frac{\pm 1}{\sqrt{2}}(-1,1)\right),\tag{1.2}
$$

like, for instance, in [5, §2.1]. This choice leads to the following 2D system,

$$
\begin{cases}\n\partial_t f^{\pm} \pm \frac{1}{\sqrt{2}} \left(\partial_x f^{\pm} + \partial_y g^{\pm} \right) = \sigma(x, y) \left(\frac{\rho}{4} - f^{\pm} \right), \\
\partial_t g^{\pm} \mp \frac{1}{\sqrt{2}} \left(\partial_x f^{\pm} - \partial_y g^{\pm} \right) = \sigma(x, y) \left(\frac{\rho}{4} - g^{\pm} \right),\n\end{cases} (1.3)
$$

for which we propose a numerical scheme endowed with similar properties as the one in [14], in a two-dimensional context, without domain decomposition, like [2, 16, 19].

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1.2. Diffusive approximation to (|1.1). To study diffusive limits of (1.1), one rescales $(t, \mathbf{x}) \rightarrow (\varepsilon^2 t, \varepsilon \mathbf{x})$ in order to produce,

$$
\varepsilon \partial_t f^{\pm} \pm \partial_x f^{\pm} = \frac{\sigma(\mathbf{x})}{\varepsilon} (\frac{\rho}{4} - f^{\pm}), \qquad \varepsilon \partial_t g^{\pm} \pm \partial_y g^{\pm} = \frac{\sigma(\mathbf{x})}{\varepsilon} (\frac{\rho}{4} - g^{\pm}),
$$

and introduces macroscopic quantities, mass and flux,

$$
\rho = f^+ + f^- + g^+ + g^-, \qquad \mathbf{J} = \frac{1}{\varepsilon} \begin{pmatrix} f^+ - f^- \\ g^+ - g^- \end{pmatrix} \in \mathbb{R}^2
$$

By summing the four balance laws, the continuity equation emerges,

$$
\partial_t \rho + \text{div } \mathbf{J} = 0.
$$

However, as noted in [17, page 504], the equation on **J** isn't closed,

$$
\varepsilon^2 \partial_t \mathbf{J} + \nabla \begin{pmatrix} f^+ + f^- \\ g^+ + g^- \end{pmatrix} = -\sigma(\mathbf{x}) \mathbf{J}, \qquad (1.4)
$$

.

.

so that, formally, the asymptotic behavior appears to be given by,

$$
\partial_t \rho = \partial_x \left(\frac{\partial_x (f^+ + f^-)}{\sigma(\mathbf{x})} \right) + \partial_y \left(\frac{\partial_y (g^+ + g^-)}{\sigma(\mathbf{x})} \right)
$$

However, by subtracting the first (second) and the third (fourth) balance laws,

$$
\varepsilon \partial_t (f^{\pm} - g^{\pm}) \pm (\partial_x f^{\pm} - \partial_y g^{\pm}) = -\frac{\sigma}{\varepsilon} (f^{\pm} - g^{\pm}),
$$

we get that $|f^{\pm} - g^{\pm}| = O(\varepsilon)$, so former calculations can be improved into,

$$
\varepsilon^2 \partial_t \mathbf{J} + \nabla \left(\frac{\rho}{2} \right) = -\sigma \mathbf{J} - \frac{1}{2} \nabla \left(\begin{pmatrix} f^+ - g^+ \\ (g^+ - f^+) + (f^- - g^-) \end{pmatrix} \right) = -\sigma \mathbf{J} - O(\varepsilon),
$$

which leads to the expected diffusion equation (see also (4.8),

$$
\partial_t \rho(t, \mathbf{x}) = \text{div}\left(\frac{\nabla \rho}{2\sigma(\mathbf{x})}\right), \qquad \text{or } \partial_t \rho = \frac{\Delta \rho}{2\sigma} \text{ if } \sigma \text{ is a constant.}
$$
\n(1.5)

These formal arguments were made fully rigorous in [17] when σ is a constant.

1.3. Plan of the paper. This text follows a similar roadmap as the original article [14], with the supplementary difficulty that every derivation must now be made on two-dimensional kinetic models. To proceed, we recall in §2 the pioneering results of [4], thanks to which one can deduce, by means of Laplace transforms, kinetic steady-states from harmonic functions. Following ideas of [12, 13], a *S*-matrix is derived, in §3, from the data of such polynomial kinetic steady-states, yielding a time-marching scheme (3.5), which is able to preserve non-trivial 2D equilibria (see Theorem 3.2). Moreover, the *S*-matrix being doubly-stochastic, it is straightforward to show that (3.5) preserves positivity as well as L^1/L^{∞} bounds, like its continuous counterpart. Drawing on our paper [15], after a parabolic rescaling of variables, the *S*-matrix decomposes nicely so as to yield an IMEX scheme (4.1) which relaxes, as $\varepsilon \to 0$, towards (4.8), which is a consistent discretization of (1.5). Rigorous proofs are produced in §5, in particular in Theorem 5.6, where we can see that the multidimensional feature (1.4), raised in [17], has consequences at the numerical level. These bounds are visualized in §6 where several challenging benchmarks for both (3.5) and (4.3) are tested on a coarse 32×32 Cartesian grid. Finally, §7 paves the way for tackling more complex kinetic models, like (7.1), and some early results of [14] are rephrased in the context of *S*-matrices in Appendix A.

2. Harmonic stationary distributions.

2.1. Harmonic functions and isotropic scattering. In [4], the authors present a tricky procedure which allows to derive an infinity of (explicit) exact steady-states of the following multi-dimensional kinetic model,

$$
\partial_t f(t, \mathbf{x}, \mathbf{v}) + \mathbf{v} \cdot \nabla_{\mathbf{x}} f = \int_{\mathbb{S}^1} f(t, \mathbf{x}, \mathbf{v}') \frac{d\mathbf{v}'}{2\pi} - f, \quad \mathbf{x} = (x, y), \quad \mathbf{v} = (\xi, \eta).
$$

In virtue of the method of characteristics, long-time asymptotics $t \rightarrow +\infty$ satisfy,

$$
f(\mathbf{x}, \mathbf{v}) = \int_0^\infty \exp(-r) \, \rho(\mathbf{x} - r\mathbf{v}) \, dr, \qquad \rho(\mathbf{x}) = \int_{\mathbb{S}^1} f(\mathbf{x}, \mathbf{v}) \frac{d\mathbf{v}}{2\pi}, \tag{2.1}
$$

which is the Laplace transform of the (oriented) one-dimensional trace of ρ , [18],

$$
\tilde{\rho}_{\mathbf{x},\mathbf{v}} : \mathbb{R}^+ \ni r \mapsto \rho(\mathbf{x} - r\mathbf{v}), \qquad f(\mathbf{x}, \mathbf{v}) = \mathcal{L}_r(\tilde{\rho}_{\mathbf{x},\mathbf{v}})[p = 1]. \tag{2.2}
$$

A Fredholm equation (of the second kind) follows by integrating again in $\mathbf{v} \in \mathbb{S}^1$,

$$
\forall \mathbf{x} \in \mathbb{R}^2, \qquad \rho(\mathbf{x}) = \int_0^\infty \exp(-r) \left(\int_{\mathbb{S}^1} \rho(\mathbf{x} - r\mathbf{v}) \, \frac{d\mathbf{v}}{2\pi} \right) dr. \tag{2.3}
$$

At this point, the authors of [4] claim that, as the long-time behavior of the kinetic model is pure diffusion and *ρ* is a macroscopic quantity, *harmonic functions may induce mesoscopic steady-states by means of* (2.1) *.* Hence, if ρ is a steady-state of diffusion, $\Delta \rho = 0$, and its mean-value property [6, 10, 20] yields,

$$
\forall r \in \mathbb{R}^+, \qquad \rho(\mathbf{x}) = \int_{\mathbb{S}^1} \rho(\mathbf{x} - r\mathbf{v}) \frac{d\mathbf{v}}{2\pi},
$$

so that, by multiplying by $\exp(-r)$ and integrating in $r \in \mathbb{R}^+$,

$$
\int_0^\infty \rho(\mathbf{x}) \exp(-r) dr = \rho(\mathbf{x}) = \int_0^\infty \exp(-r) \left(\int_{\mathbb{S}^1} \rho(\mathbf{x} - r\mathbf{v}) \frac{d\mathbf{v}}{2\pi} \right) dr,
$$

holds for any $\mathbf{x} \in \mathbb{R}^2$, so that (2.3) is satisfied, and a class of stationary kinetic densities $f(\mathbf{x}, \mathbf{v})$ can be deduced from (2.1). For instance, harmonic polynomials furnish an infinity of 2D mesoscopic steady-states, which generalize the only two $1, x - v$ (see *e.g.* [11, Chap. 9]), which follow from $\rho''(x) = 0$ in one dimension.

2.2. Kinetic steady-states and harmonic polynomials. A major result in [4] is that *kinetic stationary solutions* $f(\mathbf{x}, \mathbf{v})$ *can be deduced from macroscopic (i.e. diffusive, or harmonic) ones* $\rho(\mathbf{x})$, by means of a Laplace transform of $r \mapsto \rho(\mathbf{x}-r\mathbf{v})$,

$$
f(\mathbf{x}, \mathbf{v}) = \int_0^\infty \rho(\mathbf{x} - r \mathbf{v}) \exp(-r) dr, \qquad \Delta \rho = 0,
$$
 (2.4)

as soon as certain integrability conditions are met (see [4, Theorem A]). Accordingly, in the special case where $\mathbf{x} = x \in \mathbb{R}$ (one space dimension), harmonic solutions of $d^2\rho/dx^2 = 0$ reduce to $\{1, x\}$ and it comes that, for $v \in \mathbb{R}$,

$$
f(x,v) = \int_0^\infty \exp(-r) dr = 1, \qquad f(x,v) = \int_0^\infty (x - rv) \exp(-r) dr = x - v,
$$

which are well-known "separated variables Case's solutions", see [11, eqn (9.8)]. In more space dimensions, harmonic functions are abundant (any holomorphic function of $z = x + iy \in \mathbb{C}$ furnishes two harmonic ones: its real and imaginary parts), so that (2.4) yields an infinite set of polynomial solutions, being

$$
f(\mathbf{x}, \mathbf{v}) = \left\{ 1, \, \mathbf{x} - \mathbf{v} \in \mathbb{R}^2, \, (2.5) \right\}
$$
\n
$$
xy - (x\eta + y\xi) + 2\xi\eta, \, \frac{x^2 - y^2}{2} - (x\xi - y\eta) + (\xi^2 - \eta^2), \dots \text{ etc.} \right\},
$$
\n(2.5)

see [4, eqn (2.6)]. The first ones correspond to "dimensional splitting", whereas last two ones are truly 2D and "conjugate" in a certain sense (as seen below). These stationary distributions $f(\mathbf{x}, \mathbf{v})$ can be easily retrieved from (2.4) by taking advantage of the expression of harmonic functions in polar coordinates,

$$
\rho(x = r\cos\theta, y = r\sin\theta) = a_0 + \sum_{n \in \mathbb{N}_*} (a_n\cos n\theta + b_n\sin n\theta)r^n, \qquad (2.6)
$$

in which the first basis components are

$$
\{1, x = r\cos\theta, y = r\sin\theta, x^2 - y^2 = r^2\cos 2\theta, xy = r^2\sin 2\theta, ...\}.
$$

These "harmonic steady-states" $f(\mathbf{x}, \mathbf{v})$ follow from Euler's Gamma function,

$$
\Gamma(x) = \int_0^\infty \exp(-t) t^{x-1} dt, \qquad \Gamma(n) = (n-1)!\text{ if } n \in \mathbb{N},
$$

because, according to (2.1) , the polynomial solutions given in (2.6) rewrite,

$$
f(\mathbf{x}, \mathbf{v}) = \left\{ \Gamma(1), \ \Gamma(1)\mathbf{x} - \Gamma(2)\mathbf{v}, \ \Gamma(1)xy - \Gamma(2)(x\eta + y\xi) + \Gamma(3)\xi\eta, \ \dots \right\}.
$$

3. A "truly 2D" approximation of $f(t, \mathbf{x}, \mathbf{v})$. Working on a uniform Cartesian grid for which $\Delta x = \Delta y$, we mimic the notation already used in [3], see Fig. 3.1.

3.1. Derivation of the *S***-matrix.** In order to simulate (1.3) on a 9-points stencil, we only need the first four stationary solutions: the choice between the two "truly 2D" quadratic ones depends on the velocity vectors. A simple case, where one of the conjugate solutions is always null, consists in working in diagonal coordinates,

$$
\mathbf{x} = (\mp R, 0)
$$
 and $(0, \mp R)$, $\mathbf{v} = (\pm 1, 0)$ and $(0, \pm 1)$,

where $R = \Delta x / \sqrt{2}$ is the radius of the disc centered in $x_{i-\frac{1}{2}}, y_{j+\frac{1}{2}}$. The *S*-matrix acts on four incoming states and produces four outgoing ones, so

$$
\left(\begin{array}{c} f_{*}^{+} \\ f_{*}^{-} \\ g_{*}^{+} \\ g_{*}^{-} \end{array}\right)=S_{i-\frac{1}{2},j+\frac{1}{2}}\left(\begin{array}{c} f_{i-1,j}^{+} \\ f_{i,j+1}^{-} \\ g_{i,j}^{+} \\ g_{i-1,j+1}^{-} \end{array}\right).
$$

By linearity, and following ideas from [11, Chap. 9], a C^{∞} stationary solution reads,

$$
f(\mathbf{x}, \mathbf{v}) = \alpha + \beta(x - \xi) + \gamma(y - \eta) + \nu \left(\frac{x^2 - y^2}{2} - (x\xi - y\eta) + (\xi^2 - \eta^2) \right), \quad (3.1)
$$

FIGURE 3.1. *The S*-matrix $S_{i-\frac{1}{2},j+\frac{1}{2}}$ and an incoming state, $f_{i-1,j}^+$.

so that aforementioned "incoming" and "outgoing" states are, respectively,

$$
\left\{\begin{array}{l} f_{i-1,j}^+ = f(\mathbf{x} = (-R,0), \mathbf{v} = (1,0)), \quad f_{i,j+1}^- = f(\mathbf{x} = (R,0), \mathbf{v} = (-1,0)),\\ g_{i,j}^+ = f(\mathbf{x} = (0,-R), \mathbf{v} = (0,1)), \quad g_{i-1,j+1}^- = f(\mathbf{x} = (0,R), \mathbf{v} = (0,-1)),\end{array}\right.
$$

which is a linear system for $(\alpha, \beta, \gamma, \nu)$, and

$$
\begin{cases}\nf^+_*=f(\mathbf{x}=(R,0),\mathbf{v}=(1,0)), & f^-=f(\mathbf{x}=(-R,0),\mathbf{v}=(-1,0)),\\
g^+_*=f(f\mathbf{x}=(0,R),\mathbf{v}=(0,1)), & g^-_*=f(\mathbf{x}=(0,-R),\mathbf{v}=(0,-1)),\n\end{cases}
$$

involving again the "spectral coefficients" $(\alpha, \beta, \gamma, \nu) \in \mathbb{R}^4$ which values are fixed by the four incoming states. Accordingly, the *S*-matrix decomposes again like,

$$
\forall (i,j) \in \mathbb{Z}^2, \qquad S_{i-\frac{1}{2},j+\frac{1}{2}} = S(\sigma_{i-\frac{1}{2},j+\frac{1}{2}}), \qquad S(\sigma) = \tilde{M} M^{-1}, \tag{3.2}
$$

where *M* has mutually orthogonal columns,

$$
M = \begin{pmatrix} 1 & -(1+\sigma R) & 0 & 1 + (1+\sigma R)^2 \\ 1 & (1+\sigma R) & 0 & 1 + (1+\sigma R)^2 \\ 1 & 0 & -(1+\sigma R) & -(1+(1+\sigma R)^2) \\ 1 & 0 & (1+\sigma R) & -(1+(1+\sigma R)^2) \end{pmatrix},
$$
(3.3)

along with its companion \tilde{M} ,

$$
\tilde{M} = \begin{pmatrix}\n1 & -(1 - \sigma R) & 0 & 1 + (1 - \sigma R)^2 \\
1 & 1 - \sigma R & 0 & 1 + (1 - \sigma R)^2 \\
1 & 0 & -(1 - \sigma R) & -(1 + (1 - \sigma R)^2) \\
1 & 0 & (1 - \sigma R) & -(1 + (1 - \sigma R)^2)\n\end{pmatrix},
$$

in which a rescaling of **x** was made in order to cope with variable opacity $\sigma(\mathbf{x})$. One recognizes the matrices of 1D Goldstein-Taylor model, see §A and [11, Remark 9.3],

$$
\left(\begin{array}{cc} 1 & -(1+\sigma R) \\ 1 & (1+\sigma R) \end{array}\right), \qquad \left(\begin{array}{cc} 1 & -(1-\sigma R) \\ 1 & (1-\sigma R) \end{array}\right),
$$

but now, 1D solutions σ **x** − **v** are coupled by the constant and quadratic ones.

3.2. Resulting 2D time-marching scheme. For $\sigma R \geq 0$, the determinant *|M|* is positive, so *M* is invertible and its inverse reads:

$$
|M| = 8(1 + \sigma R)^2 (1 + (1 + \sigma R)^2), \quad M^{-1} = \begin{pmatrix} \frac{1}{4} & \frac{1}{4} & \frac{1}{4} & \frac{1}{4} \\ -A & A & 0 & 0 \\ 0 & 0 & -A & A \\ B & B & -B & -B \end{pmatrix},
$$

so that α is always the average of the four incoming states, and where

$$
A = \frac{1}{2(1 + \sigma R)}, \qquad B = \frac{1}{4(1 + (1 + \sigma R)^2)}.
$$

Accordingly, the *S*-matrix is given by the product,

$$
S(\sigma) = \tilde{M} M^{-1}
$$
\n
$$
= \begin{pmatrix}\n\frac{1}{4} + C + D & \frac{1}{4} - C + D & \frac{1}{4} - D & \frac{1}{4} - D \\
\frac{1}{4} - C + D & \frac{1}{4} + C + D & \frac{1}{4} - D & \frac{1}{4} - D \\
\frac{1}{4} - D & \frac{1}{4} - D & \frac{1}{4} + C + D & \frac{1}{4} - C + D \\
\frac{1}{4} - D & \frac{1}{4} - D & \frac{1}{4} - C + D & \frac{1}{4} + C + D\n\end{pmatrix},
$$
\n(3.4)

which both lines and columns clearly add to unity, because

$$
C = \frac{1 - \sigma R}{2(1 + \sigma R)} = \frac{1}{2} - \frac{\sigma R}{1 + \sigma R}, \quad D = \frac{(1 - \sigma R)^2 + 1}{4((1 + \sigma R)^2 + 1)} = \frac{1}{4} - \frac{\sigma R}{1 + (1 + \sigma R)^2}.
$$

The *S*-matrix rewrites as a $O(\sigma R)$ -perturbation of the identity of \mathbb{R}^4 ,

$$
S(\sigma) = \mathrm{Id}_{\mathbb{R}^4} + \sigma R \left\{ \frac{1}{1 + \sigma R} \begin{pmatrix} -1 & 1 & 0 & 0 \\ 1 & -1 & 0 & 0 \\ 0 & 0 & -1 & 1 \\ 0 & 0 & 1 & -1 \end{pmatrix} + \frac{1}{1 + (1 + \sigma R)^2} \begin{pmatrix} -1 & -1 & 1 & 1 \\ -1 & -1 & 1 & 1 \\ 1 & 1 & -1 & -1 \\ 1 & 1 & -1 & -1 \end{pmatrix} \right\},\,
$$

so that, similarly to *e.g.* [15, Prop. 3.2],

$$
S(\sigma) \to \mathrm{Id}_{\mathbb{R}^4} \text{ if } \sigma \to 0, \qquad S(\sigma) \to S^0 = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{pmatrix} \text{ if } \sigma \to +\infty.
$$

Having at hand the 4×4 matrix (3.2) allows to deduce a time-marching scheme for the 2D system (1.3) on a uniform Cartesian grid (see Fig. 3.1, $\Delta x = \Delta y$),

$$
\begin{pmatrix} f_{i,j+1}^{+,n+1} \\ f_{i-1,j}^{-,n+1} \\ g_{i-1,j+1}^{-,n+1} \\ g_{i,j}^{-,n+1} \end{pmatrix} = \left(1 - \frac{\Delta t}{2R}\right) \begin{pmatrix} f_{i,j+1}^{+,n} \\ f_{i-1,j}^{-,n} \\ f_{i-1,j}^{-,n} \\ g_{i,j}^{-,n} \end{pmatrix} + \frac{\Delta t}{2R} S(\sigma_{i-\frac{1}{2},j+\frac{1}{2}}) \begin{pmatrix} f_{i-1,j}^{+,n} \\ f_{i-1,j}^{-,n} \\ f_{i,j+1}^{-,n} \\ g_{i,j}^{+,n} \\ g_{i-1,j+1}^{-,n} \end{pmatrix} . (3.5)
$$

Lemma 3.1. *Under the CFL restriction* ∆*t ≤* 2*R, the scheme (3.5) is consistent with* (1.3) and preserves positivity. Moreover, it is conservative and L^∞ -bounded.

Proof. Under the aforementioned CFL restriction, (3.5) is a convex combination (as advocated in $[12, \text{ eqn } (2.2)]$), hence it preserves positivity because all the entries of $S(\sigma)$ are nonnegative. Besides, doubly-stochastic matrices are such that,

$$
\forall \vec{v} \in \mathbb{R}^4, \qquad \|S(\sigma)\vec{v}\|_{\infty} \le \|\vec{v}\|_{\infty}, \ \|S(\sigma)\vec{v}\|_{1} \le \|\vec{v}\|_{1},
$$

which implies that (3.5) is bounded in L^1 and L^∞ . Consistency is shown for $0 \leq$ *σR ≪* 1 (fine grid); at first order, the expression of the *S*-matrix reduces to,

$$
\frac{1}{1 + (1 + \sigma R)^2} \simeq \frac{1}{2(1 + \sigma R)}, \quad S(\sigma) = \text{Id}_{\mathbb{R}^4} + \frac{\sigma R}{2(1 + \sigma R)} \begin{pmatrix} -3 & 1 & 1 & 1 \\ 1 & -3 & 1 & 1 \\ 1 & 1 & -3 & 1 \\ 1 & 1 & 1 & -3 \end{pmatrix},
$$

and inserting this expression in (3.5) yields a consistent approximation of (1.3) . \Box

The scheme (3.5) is able to preserve some non-trivial 2D equilibria, see *e.g.* [1].

THEOREM 3.2 (2D well-balanced). Let $\sigma(\mathbf{x}) \equiv \bar{\sigma} > 0$ *a constant, then any linear combination (3.1) induces a numerical steady-state for the scheme (3.5), given by*

$$
f^{\pm}\left(\frac{x-y}{\sqrt{2}}, \frac{x+y}{\sqrt{2}}\right) = f(\bar{\sigma}\mathbf{x}; (\pm 1, 0)), \quad g^{\pm}\left(\frac{x-y}{\sqrt{2}}, \frac{x+y}{\sqrt{2}}\right) = f(\bar{\sigma}\mathbf{x}; (0, \pm 1)).
$$

Proof. Pick $(\alpha, \beta, \gamma, \nu) \in \mathbb{R}^4$ in (3.1) and consider a steady-state $f(\bar{\sigma} \mathbf{x}, \mathbf{v})$: since $|M| > 0$, its restriction to $\mathbf{v} = \{(\pm 1, 0), (0, \pm 1)\}\$ on a uniform Cartesian grid satisfies,

$$
\begin{pmatrix} \alpha \\ \beta \\ \gamma \\ \nu \end{pmatrix} = M^{-1} \begin{pmatrix} f_{i-1,j}^{+,n} \\ f_{i,j+1}^{-,n} \\ g_{i,j}^{+,n} \\ g_{i-1,j+1}^{-,n} \end{pmatrix} \quad \Rightarrow \quad S(\bar{\sigma}) \begin{pmatrix} f_{i-1,j}^{+,n} \\ f_{i,j+1}^{-,n} \\ g_{i,j}^{+,n} \\ g_{i-1,j+1}^{-,n} \end{pmatrix} = \begin{pmatrix} f_{i,j+1}^{+,n} \\ f_{i,j+1}^{-,n} \\ g_{i-1,j}^{+,n} \\ g_{i-1,j+1}^{-,n} \end{pmatrix},
$$

so they are invariant by the time-marching scheme (3.5). By a $-\frac{\pi}{4}$ rotation we pass from diagonal coordinates with $\mathbf{v} = \{(\pm 1, 0), (0, \pm 1)\}\)$ to axial ones with (1.2). \Box

4. Diffusive behavior of the *S***-matrix.** In order to study asymptotic limits so as to check a possible consistency with the estimates stated in [17, Theorem 5.1], we rescale $\sigma(\mathbf{x}) \to \sigma(\mathbf{x})/\varepsilon$, $\varepsilon \ll 1$. Accordingly, the *S*-matrix decomposes into $S^0 + \varepsilon S^{1,\varepsilon}$, like in [15, §1.2], where, as $\varepsilon \to 0$, Following again [15], an IMEX scheme may read

$$
\begin{pmatrix}\nf_{i,j+1}^{+,n+1} \\
f_{i-1,j}^{-,n+1} \\
g_{i-1,j+1}^{-,n+1} \\
g_{i,j}^{-,n+1}\n\end{pmatrix} + \frac{\Delta t}{2\varepsilon R} \left\{ \begin{pmatrix}\nf_{i,j+1}^{+,n+1} \\
f_{i-1,j}^{-,n+1} \\
g_{i-1,j+1}^{-,n+1} \\
g_{i,j}^{-,n+1}\n\end{pmatrix} - S^0 \begin{pmatrix}\nf_{i-1}^{+,n+1} \\
f_{i-1,j}^{-,n+1} \\
g_{i,j}^{+,n+1} \\
g_{i,j}^{-,n+1}\n\end{pmatrix} \right\}
$$
\n
$$
= \begin{pmatrix}\nf_{i,j+1}^{+,n} \\
f_{i,j+1}^{-,n} \\
f_{i-1,j}^{-,n}\n\end{pmatrix} + \frac{\Delta t}{2R} S^{1,\varepsilon} \begin{pmatrix}\nf_{i-1,j}^{+,n} \\
f_{i-1,j}^{-,n} \\
g_{i,j}^{-,n}\n\end{pmatrix},
$$
\n(4.1)

and we expect the (implicit, but not costly) left-hand side to yield "Maxwellian estimates" of the type [17, eqn (5.15)], and the (explicit) right-hand side to produce accurate and consistent diffusive numerical fluxes.

4.1. Decomposition of the *S***-matrix.** By defining the positive coefficients,

$$
\alpha_{i-\frac{1}{2},j+\frac{1}{2}}^{\varepsilon} = \frac{1}{\varepsilon + \sigma_{i-\frac{1}{2},j+\frac{1}{2}}R}; \qquad \beta_{i-\frac{1}{2},j+\frac{1}{2}}^{\varepsilon} = \frac{\sigma_{i-\frac{1}{2},j+\frac{1}{2}}R}{\varepsilon^2 + (\varepsilon + \sigma_{i-\frac{1}{2},j+\frac{1}{2}}R)^2}, \qquad (4.2)
$$

the aforementioned decomposition reads, at each location $i - \frac{1}{2}, j + \frac{1}{2}$,

$$
S^{\varepsilon} = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{pmatrix} + \varepsilon \begin{pmatrix} \alpha - \beta & -(\alpha + \beta) & \beta & \beta \\ -(\alpha + \beta) & \alpha - \beta & \beta & \beta \\ \beta & \beta & \alpha - \beta & -(\alpha + \beta) \\ \beta & \beta & -(\alpha + \beta) & \alpha - \beta \end{pmatrix},
$$

hence, the IMEX scheme (4.1) rewrites as,

$$
f_{i,j+1}^{+,n+1} + \frac{\Delta t}{2\varepsilon R} \Big(f_{i,j+1}^{+,n+1} - f_{i,j+1}^{-,n+1} \Big) = f_{i,j+1}^{+,n} +
$$
\n
$$
\frac{\Delta t}{2R} \Big[\alpha_{i-\frac{1}{2},j+\frac{1}{2}}^{\varepsilon} \Big(f_{i-1,j}^{+,n} - f_{i,j+1}^{-,n} \Big) + \beta_{i-\frac{1}{2},j+\frac{1}{2}}^{\varepsilon} \Big(- f_{i-1,j}^{+,n} - f_{i,j+1}^{-,n} + g_{i,j}^{+,n} + g_{i-1,j+1}^{-,n} \Big) \Big]
$$
\n
$$
f_{i-1,j}^{-,n+1} + \frac{\Delta t}{2\varepsilon R} \Big(f_{i-1,j}^{-,n+1} - f_{i-1,j}^{+,n+1} \Big) = f_{i-1,j}^{-,n} +
$$
\n
$$
\frac{\Delta t}{2R} \Big[\alpha_{i-\frac{1}{2},j+\frac{1}{2}}^{\varepsilon} \Big(f_{i,j+1}^{-,n} - f_{i-1,j}^{+,n} \Big) + \beta_{i-\frac{1}{2},j+\frac{1}{2}}^{\varepsilon} \Big(- f_{i-1,j}^{+,n} - f_{i,j+1}^{-,n} + g_{i,j}^{+,n} + g_{i-1,j+1}^{-,n} \Big) \Big]
$$
\n
$$
g_{i-1,j+1}^{+,n+1} + \frac{\Delta t}{2\varepsilon R} \Big(g_{i-1,j+1}^{+,n} - g_{i-1,j+1}^{-,n} \Big) = g_{i-1,j+1}^{+,n} +
$$
\n
$$
\frac{\Delta t}{2R} \Big[\alpha_{i-\frac{1}{2},j+\frac{1}{2}}^{\varepsilon} \Big(g_{i,j}^{+,n} - g_{i-1,j+1}^{-,n} \Big) + \beta_{i-\frac{1}{2},j+\frac{1}{2}}^{\varepsilon} \Big(f_{i-1,j}^{+,n} + f_{i,j+1}^{-,n} - g_{i,j}^{+,n} - g_{i-1,j+1}^{-,n} \Big) \Big]
$$
\n
$$
g_{i,j}^{-,n+1} + \frac{\Delta t}{2\varepsilon R} \Big(g_{i,j}^{-,n+1} -
$$

An index-shift yields:

$$
\begin{pmatrix}\n1 + \frac{\Delta t}{2\varepsilon R} & -\frac{\Delta t}{2\varepsilon R} & 0 & 0 \\
-\frac{\Delta t}{2\varepsilon R} & 1 + \frac{\Delta t}{2\varepsilon R} & 0 & 0 \\
0 & 0 & 1 + \frac{\Delta t}{2\varepsilon R} & -\frac{\Delta t}{2\varepsilon R} \\
0 & 0 & -\frac{\Delta t}{2\varepsilon R} & 1 + \frac{\Delta t}{2\varepsilon R}\n\end{pmatrix}\n\begin{pmatrix}\nf_{i,j}^{+,n+1} \\
f_{i,j}^{-,n+1} \\
g_{i,j}^{+,n+1} \\
g_{i,j}^{-,n}\n\end{pmatrix} = \n\begin{pmatrix}\nf_{i,j}^{+,n} \\
f_{i,j}^{-,n} \\
g_{i,j}^{-,n}\n\end{pmatrix} + (4.3)
$$
\n
$$
\Delta t \begin{pmatrix}\n\alpha_{i-1}^{\varepsilon} & 0 & 0 \\
0 & -\frac{\Delta t}{2\varepsilon R} & 1 + \frac{\Delta t}{2\varepsilon R}\n\end{pmatrix}\n\begin{pmatrix}\nf_{i,j}^{+,n+1} \\
g_{i,j}^{+,n+1} \\
g_{i,j}^{-,n}\n\end{pmatrix} = \n\begin{pmatrix}\nf_{i,j}^{+,n} \\
g_{i,j}^{-,n}\n\end{pmatrix} + (4.3)
$$
\n
$$
\Delta t \begin{pmatrix}\n\alpha_{i-1}^{\varepsilon} & 0 & -\alpha_{i-1}^{\varepsilon} \\
0 & 0 & 0\n\end{pmatrix} + \n\begin{pmatrix}\
$$

The implicit part relies on a block-diagonal matrix, for which,

$$
\begin{pmatrix} 1+b & -b \\ -b & 1+b \end{pmatrix}^{-1} = \frac{1}{a+b} \begin{pmatrix} a & b \\ b & a \end{pmatrix}, \quad b = \frac{\Delta t}{2\varepsilon R}, \quad a = 1 + \frac{\Delta t}{2\varepsilon R},
$$

so that (4.3) rewrites as an explicit time-marching scheme. The matrix in the left hand side of (4.3) may be written as

$$
\mathrm{Id}_{\mathbb{R}^4} + \frac{\Delta t}{2\varepsilon R} H_0, \quad \text{with} \quad H_0 = \begin{pmatrix} 1 & -1 & 0 & 0 \\ -1 & 1 & 0 & 0 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & -1 & 1 \end{pmatrix} . \tag{4.4}
$$

Denoting $f_{i,j}^n = f_{i,j}^{+,n} + f_{i,j}^{-,n}$ and $\mathfrak{g}_{i,j}^n = g_{i,j}^{+,n} + g_{i,j}^{-,n}$, their time evolution follows from adding the first two and the last two equations in (4.3):

$$
f_{i,j}^{n+1} = f_{i,j}^{n} + \frac{\Delta t}{2R} \Big(\alpha_{i-\frac{1}{2},j-\frac{1}{2}}^{e} (f_{i-1,j-1}^{+,n} - f_{i,j}^{-,n}) + \alpha_{i+\frac{1}{2},j+\frac{1}{2}}^{e} (f_{i+1,j+1}^{-,n} - f_{i,j}^{+,n}) \Big) - \frac{\Delta t}{2R} \Big(\beta_{i-\frac{1}{2},j-\frac{1}{2}}^{e} (f_{i-1,j-1}^{+,n} + f_{i,j}^{-,n} - g_{i,j-1}^{+,n} - g_{i-1,j}^{-,n}) \Big) + \beta_{i+\frac{1}{2},j+\frac{1}{2}}^{e} (f_{i,j}^{+,n} + f_{i+1,j+1}^{-,n} - g_{i+1,j}^{+,n} - g_{i,j+1}^{-,n}) \Big)
$$

$$
\mathfrak{g}_{i,j}^{n+1} = \mathfrak{g}_{i,j}^{n} + \frac{\Delta t}{2R} \Big(\alpha_{i+\frac{1}{2},j-\frac{1}{2}}^{e} (g_{i+1,j-1}^{+,n} - g_{i,j}^{-,n}) + \alpha_{i-\frac{1}{2},j+\frac{1}{2}}^{e} (g_{i-1,j+1}^{-,n} - g_{i,j}^{+,n}) \Big) + \frac{\Delta t}{2R} \Big(\beta_{i+\frac{1}{2},j-\frac{1}{2}}^{e} (f_{i,j-1}^{+,n} + f_{i+1,j}^{-,n} - g_{i+1,j-1}^{+,n} - g_{i,j}^{-,n}) \Big) + \beta_{i-\frac{1}{2},j+\frac{1}{2}}^{e} (f_{i-1,j}^{+,n} + f_{i,j+1}^{-,n} - g_{i,j}^{+,n} - g_{i-1,j+1}^{-,n}) \Big).
$$
\n(4.6)

4.2. Formal diffusive limit. When $\varepsilon \to 0$, we deduce from (4.3) that,

$$
\begin{pmatrix} f_{i,j}^{+,n+1} \\ f_{i,j}^{-,n+1} \\ g_{i,j}^{+,n+1} \\ g_{i,j}^{-,n+1} \end{pmatrix} \in \text{Ker}(H_0) = \text{Span}\left\{ \begin{pmatrix} 1 \\ 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \\ 1 \end{pmatrix} \right\}.
$$
 (4.7)

Then, in the limit $\varepsilon \to 0$, we expect, at least formally, that

$$
f_{i,j}^{+,n+1} = f_{i,j}^{-,n+1} = \frac{1}{2} f_{i,j}^{n+1}, \qquad g_{i,j}^{+,n+1} = g_{i,j}^{-,n+1} = \frac{1}{2} \mathfrak{g}_{i,j}^{n+1},
$$

along with, from (4.2),

$$
\alpha_{i-\frac{1}{2},j+\frac{1}{2}}^{\varepsilon},\beta_{i-\frac{1}{2},j+\frac{1}{2}}^{\varepsilon}\to\frac{1}{\sigma_{i-\frac{1}{2},j+\frac{1}{2}}R},\qquad \varepsilon\to 0,
$$

so that, former equations (4.5) and (4.6) become

$$
f_{i,j}^{n+1} = f_{i,j}^{n} + \frac{\Delta t}{4R^2} \left(\frac{1}{\sigma_{i-\frac{1}{2},j-\frac{1}{2}}} \left((\mathfrak{g}_{i-1,j}^{n} - \mathfrak{f}_{i,j}^{n}) + (\mathfrak{g}_{i,j-1}^{n} - \mathfrak{f}_{i,j}^{n}) \right) + \frac{1}{\sigma_{i+\frac{1}{2},j+\frac{1}{2}}} \left((\mathfrak{g}_{i+1,j}^{n} - \mathfrak{f}_{i,j}^{n}) + (\mathfrak{g}_{i,j+1}^{n} - \mathfrak{f}_{i,j}^{n}) \right) \right) + \mathfrak{g}_{i,j}^{n+1} = \mathfrak{g}_{i,j}^{n} + \frac{\Delta t}{4R^2} \left(\frac{1}{\sigma_{i-\frac{1}{2},j+\frac{1}{2}}} \left((\mathfrak{f}_{i,j+1}^{n} - \mathfrak{g}_{i,j}^{n}) + (\mathfrak{f}_{i-1,j}^{n} - \mathfrak{g}_{i,j}^{n}) \right) + \frac{1}{\sigma_{i+\frac{1}{2},j-\frac{1}{2}}} \left((\mathfrak{f}_{i+1,j}^{n} - \mathfrak{g}_{i,j}^{n}) + (\mathfrak{f}_{i,j-1}^{n} - \mathfrak{g}_{i,j}^{n}) \right) \right).
$$

Accordingly, f and g satisfy similar diffusion equations, if the opacity σ is smooth. Consequently, if initially they are close enough (so–called "*well-prepared initial data*"), they can be expected to stay so because their difference $f_{i,j}^n - \mathfrak{g}_{i,j}^n$ satisfies a parabolic equation. The decay of $f - g$ will be rigorously proved when σ is a constant, see

Theorem 5.6. Adding, assuming $f - g \rightarrow 0$, and denoting $\rho_{i,j}^n = f_{i,j}^n + g_{i,j}^n$, it comes

$$
\rho_{i,j}^{n+1} = \rho_{i,j}^{n} + \frac{\Delta t}{2\sigma R^2} \left(\left(\frac{1}{2\sigma_{i+\frac{1}{2},j+\frac{1}{2}}} + \frac{1}{2\sigma_{i+\frac{1}{2},j-\frac{1}{2}}} \right) (\rho_{i+1,j}^{n} - \rho_{i,j}^{n}) + \left(\frac{1}{2\sigma_{i+\frac{1}{2},j+\frac{1}{2}}} + \frac{1}{2\sigma_{i-\frac{1}{2},j+\frac{1}{2}}} \right) (\rho_{i,j+1}^{n} - \rho_{i,j}^{n}) - \left(\frac{1}{2\sigma_{i-\frac{1}{2},j+\frac{1}{2}}} + \frac{1}{2\sigma_{i-\frac{1}{2},j-\frac{1}{2}}} \right) (\rho_{i,j}^{n} - \rho_{i-1,j}^{n}) - \left(\frac{1}{2\sigma_{i+\frac{1}{2},j-\frac{1}{2}}} + \frac{1}{2\sigma_{i-\frac{1}{2},j-\frac{1}{2}}} \right) (\rho_{i,j}^{n} - \rho_{i,j-1}^{n}) \right).
$$
\n(4.8)

which is a second-order, finite-differences, monotone (under the CFL restriction (5.6)) discretization of the macroscopic diffusion equation (1.5).

5. Rigorous uniform estimates for constant opacity. Let $(u_{i,j})$ stand for any real sequence, we introduce the following notations,

$$
\delta u_{i+\frac{1}{2},j} = u_{i+1,j} - u_{i,j}, \quad \delta u_{i,j+\frac{1}{2}} = u_{i,j+1} - u_{i,j},
$$

\n
$$
||u||_1 = \sum_{i,j} \Delta x^2 |u_{i,j}|, \qquad TV(u) = \sum_{i,j} \Delta x (|\delta u_{i+\frac{1}{2},j}| + |\delta u_{i,j+\frac{1}{2}}|),
$$

\n
$$
||\Delta u||_1 = \sum_{i,j} |u_{i+1,j} + u_{i,j+1} + u_{i-1,j} + u_{i,j-1} - 4u_{i,j}|.
$$
\n
$$
(5.1)
$$

5.1. General properties of the scheme. The first stepping stone is the definition of a convenient CFL restriction:

LEMMA 5.1. *Assume that there exists* $\sigma_{min} > 0$ *such that the opacity is such that* $0 < \sigma_{min} \leq \sigma_{i-\frac{1}{2},j+\frac{1}{2}}$ for all *i*, *j*. Then, under the CFL condition

$$
\Delta t \le \min\left\{\frac{2}{3}\sigma_{min}R^2, \frac{R(\varepsilon + \sigma_{min}R)}{2}\left(1 + \sqrt{1 + \frac{8\varepsilon}{\varepsilon + \sigma_{min}R}}\right)\right\},\qquad(5.2)
$$

the IMEX scheme (4.3) *preserves positivity.*

Proof. Inverting the block-diagonal matrix in (4.3) brings the expressions,

$$
f_{i,j}^{+,n+1} = \frac{1}{2\varepsilon R + 2\Delta t} \Big(\big(2\varepsilon R + \Delta t - \frac{\Delta t^2}{2R} \big(\alpha_{i + \frac{1}{2}, j + \frac{1}{2}}^{\varepsilon} + \beta_{i + \frac{1}{2}, j + \frac{1}{2}}^{\varepsilon} \big) \Big) f_{i,j}^{+,n} + \big(\Delta t - \frac{\Delta t}{2R} \big(2\varepsilon R + \Delta t \big) \big(\alpha_{i - \frac{1}{2}, j - \frac{1}{2}}^{\varepsilon} + \beta_{i - \frac{1}{2}, j - \frac{1}{2}}^{\varepsilon} \big) \big) f_{i,j}^{-,n} + \big(2\varepsilon R + \Delta t \big) \frac{\Delta t}{2R} \big(\alpha_{i - \frac{1}{2}, j - \frac{1}{2}}^{\varepsilon} - \beta_{i - \frac{1}{2}, j - \frac{1}{2}}^{\varepsilon} \big) f_{i-1,j-1}^{+,n} + \frac{\Delta t^2}{2R} \big(\alpha_{i + \frac{1}{2}, j + \frac{1}{2}}^{\varepsilon} - \beta_{i + \frac{1}{2}, j + \frac{1}{2}}^{\varepsilon} \big) f_{i+1,j+1}^{-,n} + \big(2\varepsilon R + \Delta t \big) \frac{\Delta t}{2R} \beta_{i - \frac{1}{2}, j - \frac{1}{2}}^{\varepsilon} \big(g_{i,j-1}^{+,n} + g_{i-1,j}^{-,n} \big) + \frac{\Delta t^2}{2R} \beta_{i + \frac{1}{2}, j + \frac{1}{2}}^{\varepsilon} \big(g_{i+1,j}^{+,n} + g_{i,j+1}^{-,n} \big) \Big),
$$
(5.3)

and

$$
f_{i,j}^{-,n+1} = \frac{1}{2\varepsilon R + 2\Delta t} \Big(\Big(\Delta t - (2\varepsilon R + \Delta t) \frac{\Delta t}{2R} (\alpha_{i+\frac{1}{2},j+\frac{1}{2}}^{\varepsilon} + \beta_{i+\frac{1}{2},j+\frac{1}{2}}^{\varepsilon}) \Big) f_{i,j}^{+,n} + (2\varepsilon R + \Delta t - \frac{\Delta t^2}{2R} (\alpha_{i-\frac{1}{2},j-\frac{1}{2}}^{\varepsilon} + \beta_{i-\frac{1}{2},j-\frac{1}{2}}^{\varepsilon}) \Big) f_{i,j}^{-,n} + \frac{\Delta t^2}{2R} (\alpha_{i-\frac{1}{2},j-\frac{1}{2}}^{\varepsilon} - \beta_{i-\frac{1}{2},j-\frac{1}{2}}^{\varepsilon}) f_{i-1,j-1}^{+,n} + (2\varepsilon R + \Delta t) \frac{\Delta t}{2R} (\alpha_{i+\frac{1}{2},j+\frac{1}{2}}^{\varepsilon} - \beta_{i+\frac{1}{2},j+\frac{1}{2}}^{\varepsilon}) f_{i+1,j+1}^{-,n} + \frac{\Delta t^2}{2R} \beta_{i-\frac{1}{2},j-\frac{1}{2}} (g_{i,j-1}^{+,n} + g_{i-1,j}^{-,n}) + (2\varepsilon R + \Delta t) \frac{\Delta t}{2R} \beta_{i+\frac{1}{2},j+\frac{1}{2}}^{\varepsilon} (g_{i+1,j}^{+,n} + g_{i,j+1}^{-,n}) \Big),
$$

along with similar ones for $g_{i,j}^{\pm,n+1}$, too. From (4.2), it comes

$$
\alpha_{i-\frac{1}{2},j+\frac{1}{2}}^{\varepsilon}-\beta_{i-\frac{1}{2},j+\frac{1}{2}}^{\varepsilon}=\frac{\varepsilon^2+\varepsilon(\varepsilon+\sigma_{i-\frac{1}{2},j+\frac{1}{2}}R)}{(\varepsilon+\sigma_{i-\frac{1}{2},j+\frac{1}{2}}R)(\varepsilon^2+(\varepsilon+\sigma_{i-\frac{1}{2},j+\frac{1}{2}}R)^2)}\geq 0.
$$

Define a (decreasing) function $\psi : \mathbb{R}^+ \to \mathbb{R}^+,$

$$
\psi(x) \stackrel{def}{=} \frac{1}{\varepsilon + x} + \frac{x}{\varepsilon^2 + (\varepsilon + x)^2}, \qquad \psi'(x) \le 0 \text{ on } (0, +\infty),
$$

then, since

$$
\alpha_{i-\frac{1}{2},j+\frac{1}{2}}^{\varepsilon}+\beta_{i-\frac{1}{2},j+\frac{1}{2}}^{\varepsilon}=\psi(\sigma_{i-\frac{1}{2},j+\frac{1}{2}}R),
$$

we get the following bound:

$$
\alpha_{i-\frac{1}{2},j+\frac{1}{2}}^{\varepsilon} + \beta_{i-\frac{1}{2},j+\frac{1}{2}}^{\varepsilon} \le \frac{1}{\varepsilon + \sigma_{min}R} + \frac{\sigma_{min}R}{\varepsilon^2 + (\varepsilon + \sigma_{min}R)^2}.
$$

Hence $f_{i,j}^{\pm,n+1}, g_{i,j}^{\pm,n+1}$ are nonnegative combinations of previous iterates if,

$$
\left(\varepsilon + \frac{\Delta t}{2R}\right) \left(\frac{1}{\varepsilon + \sigma_{min}R} + \frac{\sigma_{min}R}{\varepsilon^2 + (\varepsilon + \sigma_{min}R)^2}\right) \le 1,\tag{5.4}
$$

$$
\frac{\Delta t^2}{2R} \left(\frac{1}{\varepsilon + \sigma_{min} R} + \frac{\sigma_{min} R}{\varepsilon^2 + (\varepsilon + \sigma_{min} R)^2} \right) \le 2\varepsilon R + \Delta t. \tag{5.5}
$$

Conditions (5.4) and (5.5) are met if and only if,

$$
\frac{\Delta t}{2R} \le \sigma_{min} R \frac{\varepsilon^2 + \varepsilon \sigma_{min} R + (\sigma_{min} R)^2}{2\varepsilon^2 + 3\varepsilon \sigma_{min} R + 2(\sigma_{min} R)^2}, \qquad \frac{\Delta t^2}{R(\varepsilon + \sigma_{min} R)} \le 2\varepsilon R + \Delta t
$$

and these hold as soon as (5.2) does. \Box

Remark 1. *A sufficient condition for* (5.2) *is the heat equation's restriction:*

$$
2\Delta t \le \sigma_{min} R^2 \tag{5.6}
$$

Lemma 5.2 (Conservation). *Let us assume that the initial data are nonnegative and that* (5.2) *holds. Then, the scheme* (4.3) *is bounded in L* ¹ *and conservative :*

$$
||f^{+,n}||_1 + ||f^{-,n}||_1 + ||g^{+,n}||_1 + ||g^{-,n}||_1 = ||f^{+,0}||_1 + ||f^{-,0}||_1 + ||g^{+,0}||_1 + ||g^{-,0}||_1.
$$

Proof. It suffices to add the lines of (4.3) and to sum over *i* and *j*. \Box LEMMA 5.3 (L^∞ bound). Let initial data satisfy

$$
0 \le f_{i,j}^{\pm,0} \le M, \qquad 0 \le g_{i,j}^{\pm,0} \le M.
$$

Then, under the CFL (5.2)*,*

$$
\forall n \in \mathbb{N}, \qquad 0 \le f_{i,j}^{\pm,n} \le M, \qquad 0 \le g_{i,j}^{\pm,n} \le M.
$$

Proof. The proof of Lemma 5.1 yields that, under (5.2), $f_{i,j}^{\pm,n+1}$ and $g_{i,j}^{\pm,n+1}$ are convex combination of previous iterates, giving the announced \tilde{L}^{∞} bound.

REMARK 2. *These bounds hold even if the opacity* σ *isn't* a (*positive*) constant.

5.2. Uniform estimates in the case σ constant. We study rigorously the diffusive limit of (4.3) in order to prove that it is "asymptotic-preserving" (AP). Recall from (4.2) the coefficients,

$$
\alpha^{\varepsilon} = \frac{1}{\varepsilon + \sigma R}; \qquad \beta^{\varepsilon} = \frac{\sigma R}{\varepsilon^2 + (\varepsilon + \sigma R)^2}, \qquad \text{for } \sigma \equiv \bar{\sigma} \in \mathbb{R}^+.
$$
 (5.7)

As σ is constant, (4.3) simplifies into,

$$
\begin{pmatrix}\n1 + \frac{\Delta t}{2\varepsilon R} & -\frac{\Delta t}{2\varepsilon R} & 0 & 0 \\
-\frac{\Delta t}{2\varepsilon R} & 1 + \frac{\Delta t}{2\varepsilon R} & 0 & 0 \\
0 & 0 & 1 + \frac{\Delta t}{2\varepsilon R} & -\frac{\Delta t}{2\varepsilon R} \\
0 & 0 & -\frac{\Delta t}{2\varepsilon R} & 1 + \frac{\Delta t}{2\varepsilon R}\n\end{pmatrix}\n\begin{pmatrix}\nf_{i,j}^{+,n+1} \\
f_{i,j}^{-,n+1} \\
g_{i,j}^{+,n+1} \\
g_{i,j}^{-,n+1}\n\end{pmatrix} = \begin{pmatrix}\nf_{i,j}^{+,n} \\
f_{i,j}^{-,n} \\
g_{i,j}^{+,n}\n\end{pmatrix}
$$
\n
$$
(5.8)
$$
\n
$$
+\frac{\Delta t}{2\varepsilon R} \begin{pmatrix}\n\alpha^{\varepsilon}(f_{i-1,j-1}^{+,n} - f_{i,j}^{-,n}) - \beta^{\varepsilon}(f_{i-1,j-1}^{+,n} + f_{i,j}^{-,n} - g_{i,j-1}^{+,n} - g_{i-1,j}^{-,n}) \\
\alpha^{\varepsilon}(f_{i-1,j+1}^{-,n} - f_{i,j}^{-,n}) - \beta^{\varepsilon}(f_{i,j}^{+,n} + f_{i-1,j-1}^{-,n} - g_{i,j-1}^{-,n} - g_{i,j+1}^{-,n}) \\
\alpha^{\varepsilon}(g_{i+1,j-1}^{+,n} - g_{i,j}^{-,n}) + \beta^{\varepsilon}(f_{i,j-1}^{+,n} + f_{i+1,j}^{-,n} - g_{i+1,j-1}^{-,n} - g_{i,j}^{-,n}) \\
\alpha^{\varepsilon}(g_{i-1,j+1}^{-,n} - g_{i,j}^{+,n}) + \beta^{\varepsilon}(f_{i-1,j}^{+,n} + f_{i,j+1}^{-,n} - g_{i,j}^{+,n} - g_{i-1,j+1}^{-,n})\n\end{pmatrix}
$$
\n(5.8)

Lemma 5.4. *Let σ be a positive constant: under the parabolic CFL restriction,*

$$
2\,\Delta t < \sigma_{min} R^2,\tag{5.9}
$$

the scheme (5.8) *is TVD (total variation diminishing),*

$$
TV(f^{+,n+1}) + TV(f^{-,n+1}) + TV(g^{+,n+1}) + TV(g^{-,n+1})
$$

\n
$$
\leq TV(f^{+,n}) + TV(f^{-,n}) + TV(g^{+,n}) + TV(g^{-,n}).
$$

Proof. By linearity, the expression of $f_{i,j}^{+,n+1}$ in (5.3) in the proof of Lemma 5.1 is similar to the ones of $\delta f_{i+\frac{1}{2},j}^{+,n}$. Since (5.9) ensures that coefficients are nonnegative, a triangle inequality brings,

$$
|\delta f_{i+\frac{1}{2},j}^{+,n+1}| \leq \frac{1}{2\varepsilon R + 2\Delta t} \Big(\big(2\varepsilon R + \Delta t - \frac{\Delta t^2}{2R} (\alpha^{\varepsilon} + \beta^{\varepsilon})\big) |\delta f_{i+\frac{1}{2},j}^{+,n}| + \big(\Delta t - \frac{\Delta t}{2R} (2\varepsilon R + \Delta t)(\alpha^{\varepsilon} + \beta^{\varepsilon})\big) |\delta f_{i+\frac{1}{2},j}^{-,n}| + (2\varepsilon R + \Delta t) \frac{\Delta t}{2R} (\alpha^{\varepsilon} - \beta^{\varepsilon}) |\delta f_{i-\frac{1}{2},j-1}^{+,n}| + \frac{\Delta t^2}{2R} (\alpha^{\varepsilon} - \beta^{\varepsilon}) |\delta f_{i+\frac{3}{2},j+1}^{-,n}| + (2\varepsilon R + \Delta t) \frac{\Delta t}{2R} \beta^{\varepsilon} (|\delta g_{i+\frac{1}{2},j-1}^{+,n}| + |\delta g_{i-\frac{1}{2},j}^{-,n}|) + \frac{\Delta t^2}{2R} \beta^{\varepsilon} (|\delta g_{i+\frac{1}{2},j}^{+,n}| + |\delta g_{i+\frac{1}{2},j+1}^{-,n}|) \Big),
$$

with similar expressions for $|\delta f_{i+\frac{1}{2},\vert}^{-,n},$ $|\delta g_{i\frac{1}{2},j}^{+,n+1}|$ and $|\delta g_{i+\frac{1}{2},j}^{-,n+1}|$. Adding,

$$
\begin{split} &|\delta f_{i+\frac{1}{2},j}^{+,n+1}|+|\delta f_{i+\frac{1}{2},j}^{-,n+1}|+|\delta g_{i+\frac{1}{2},j}^{-,n+1}|\leq\\ &\qquad \qquad \left(1-\frac{\Delta t}{2R}(\alpha^{\varepsilon}+\beta^{\varepsilon})\right)\left(|\delta f_{i+\frac{1}{2},j}^{+,n}|+|\delta f_{i+\frac{1}{2},j}^{-,n}|+|\delta g_{i+\frac{1}{2},j}^{+,n}|+|\delta g_{i+\frac{1}{2},j}^{-,n}|\right)\\ &+\frac{\Delta t}{2R}(\alpha^{\varepsilon}-\beta^{\varepsilon})\left(|\delta f_{i-\frac{1}{2},j-1}^{+,n}|+|\delta f_{i+\frac{3}{2},j+1}^{-,n}|+|\delta g_{i+\frac{3}{2},j-1}^{+,n}|+|\delta g_{i-\frac{1}{2},j+1}^{-,n}|\right)\\ &+\frac{\Delta t}{2R}\beta^{\varepsilon}\left(|\delta f_{i+\frac{1}{2},j-1}^{+,n}|+|\delta f_{i+\frac{3}{2},j}^{-,n}|+|\delta f_{i-\frac{1}{2},j}^{+,n}|+|\delta f_{i+\frac{1}{2},j+1}^{-,n}| \right)\\ &+\frac{\Delta t}{2R}\beta^{\varepsilon}\left(|\delta g_{i+\frac{1}{2},j-1}^{+,n}|+|\delta_{i-\frac{1}{2},j}^{-,n}|+|\delta g_{i+\frac{3}{2},j}^{+,n}|+|\delta g_{i+\frac{1}{2},j+1}^{-,n}| \right), \end{split}
$$

and summing over i and j , we get, after shifting the indexes,

$$
\begin{aligned} \sum_{i,j}\Big(|\delta f^{+,n+1}_{i+\frac{1}{2},j}|+|\delta f^{-,n+1}_{i+\frac{1}{2},j}|+|\delta g^{+,n+1}_{i+\frac{1}{2},j}|+|\delta g^{-,n+1}_{i+\frac{1}{2},j}|\Big)\\ &\leq \sum_{i,j}\Big(|\delta f^{+,n}_{i+\frac{1}{2},j}|+|\delta f^{-,n}_{i+\frac{1}{2},j}|+|\delta g^{+,n}_{i+\frac{1}{2},j}|+|\delta g^{-,n}_{i+\frac{1}{2},j}|\Big). \end{aligned}
$$

By the same token with variations in j instead of i , we get the claimed result. \square

Define $f_{\Delta x}^{\pm}$, $g_{\Delta x}^{\pm}$ the piecewise constant functions such that,

$$
f^{\pm}(t, \mathbf{x}) = f^{\pm, n}_{i, j}, \qquad g^{\pm}(t, \mathbf{x}) = g^{\pm, n}_{i, j}, \tag{5.10}
$$

for $t \in [n\Delta t, (n+1)\Delta t)$, $\mathbf{x} \in ((i-\frac{1}{2})\Delta x, (i+\frac{1}{2})\Delta x) \times ((j-\frac{1}{2})\Delta x, (j+\frac{1}{2})\Delta x)$.

Corollary 5.5. *Under* (5.9)*, and for bounded integrable nonnegative data, the approximate solutions* (5.10) are uniformly bounded in $L^1 \cap L^\infty \cap BV([0,T] \times \mathbb{R}^2)$.

5.3. Rigorous diffusive limit. We are now in position to state the main result of this section:

Theorem 5.6 (Asymptotic-Preserving property). *Assume* (5.9) *holds and that initial data are independent of ε and smooth enough such that*

$$
\exists C \in \mathbb{R}^+, \qquad \|\Delta f^{+,0}\|_1 + \|\Delta f^{-,0}\|_1 + \|\Delta g^{+,0}\|_1 + \|\Delta g^{-,0}\|_1 \le C,
$$

then the sequences $(f^{\epsilon} \dot{x}, \eta)$ *and* $(g^{\epsilon} \dot{x}, \eta)$ *are of uniformly bounded total variation and converge towards limits, denoted respectively* $(f_{i,j}^{\pm,n})$ *and* $(g_{i,j}^{\pm,n})$ *which satisfy:*

$$
f_{i,j}^{+,n} = f_{i,j}^{-,n} = \frac{1}{2} f_{i,j}^n
$$
, $g_{i,j}^{+,n} = g_{i,j}^{-,n} = \frac{1}{2} \mathfrak{g}_{i,j}^n$,

where

$$
f_{i,j}^{n+1} = f_{i,j}^n + \frac{\Delta t}{4\sigma R^2} (\mathfrak{g}_{i,j-1}^n + \mathfrak{g}_{i-1,j}^n + \mathfrak{g}_{i+1,j}^n + \mathfrak{g}_{i,j+1}^n - 4f_{i,j}^n)
$$
(5.11)

$$
\mathfrak{g}_{i,j}^{n+1} = \mathfrak{g}_{i,j}^n + \frac{\Delta t}{4\sigma R^2} (\mathfrak{f}_{i,j-1}^n + \mathfrak{f}_{i+1,j}^n + \mathfrak{f}_{i-1,j}^n + \mathfrak{f}_{i,j+1}^n - 4\mathfrak{g}_{i,j}^n). \tag{5.12}
$$

Moreover, the "Maxwellian gap" decreases in time according to,

$$
\forall n \in \mathbb{N}_*, \qquad \|\mathbf{f}^n - \mathbf{g}^n\|_1 \le \|\mathbf{f}^0 - \mathbf{g}^0\|_1 \exp\left(-\frac{2n\Delta t}{\sigma R^2}\right) + C R^2. \tag{5.13}
$$

Adding both equations (5.11)-(5.12), we deduce the following result:

Corollary 5.7. *Under the same assumptions as Theorem 5.6, we have*

$$
\rho_{i,j}^{n+1} = \rho_{i,j}^n + \frac{\Delta t}{4\sigma R^2} (\rho_{i,j-1}^n + \rho_{i,j+1}^n + \rho_{i-1,j}^n + \rho_{i+1,j}^n - 4\rho_{i,j}^n), \quad \rho^n = \mathfrak{f}^n + \mathfrak{g}^n.
$$

along with $f^{\pm,n} = \rho^n/4 + O(R^2), g^{\pm,n} = \rho^n/4 + O(R^2).$

Proof. By the computations in the proof of Lemma 5.4, the sequences $(f^{\varepsilon} \dot{x}, n)$, and $(g^{\varepsilon} \dot{t}^n)$ are Cauchy sequences with respect to ε in ℓ^1 . Thus, when $\varepsilon \to 0$, they converge to some limits denoted respectively $(f_{i,j}^{\pm,n})$, and $(g_{i,j}^{\pm,n})$ and we can pass to the limit in (5.8). Hence as $\varepsilon \to 0$, by (4.4) and (4.7), we get that

$$
\forall (i, j, n) \in \mathbb{Z}^2 \times \mathbb{N}, \qquad f_{i,j}^{+,n+1} = f_{i,j}^{-,n+1}, \quad g_{i,j}^{+,n+1} = g_{i,j}^{-,n+1}.
$$

Denoting $\mathfrak{f}_{i,j}^{\varepsilon n} = f^{\varepsilon +,n}_{i,j} + f^{\varepsilon^{-,n}}_{i,j}$ and $\mathfrak{g}_{i,j}^{\varepsilon n} = g^{\varepsilon +,n}_{i,j} + g^{\varepsilon^{-,n}}_{i,j}$, we obtain their equations by adding the first two and the last two lines in (5.8):

$$
f^{\varepsilon n+1} = f^{\varepsilon n}_{i,j} + \frac{\Delta t}{2R} \Big(\alpha^{\varepsilon} (f^{\varepsilon+n}_{i-1,j-1} - f^{\varepsilon-n}_{i,j}) + \alpha^{\varepsilon} (f^{\varepsilon-n}_{i+1,j+1} - f^{\varepsilon+n}_{i,j}) \Big) - \frac{\Delta t}{2R} \Big(\beta^{\varepsilon} (f^{\varepsilon+n}_{i-1,j-1} + f^{\varepsilon-n}_{i,j} - g^{\varepsilon+n}_{i,j-1} - g^{\varepsilon-n}_{i-1,j}) + \beta^{\varepsilon} (f^{\varepsilon+n}_{i,j} + f^{\varepsilon-n}_{i+1,j+1} - g^{\varepsilon+n}_{i+1,j} - g^{\varepsilon-n}_{i,j+1}) \Big);
$$

$$
\mathfrak{g}^{\varepsilon n+1} = \mathfrak{g}^{\varepsilon n}_{i,j} + \frac{\Delta t}{2R} \Big(\alpha^{\varepsilon} (g^{\varepsilon+n}_{i+1,j-1} - g^{\varepsilon-n}_{i,j}) + \alpha^{\varepsilon} (g^{\varepsilon-n}_{i-1,j+1} - g^{\varepsilon+n}_{i,j}) \Big) + \frac{\Delta t}{2R} \Big(\beta^{\varepsilon} (f^{\varepsilon+n}_{i,j-1} + f^{\varepsilon-n}_{i+1,j} - g^{\varepsilon+n}_{i+1,j-1} - g^{\varepsilon-n}_{i,j}) \Big) + (5.15)
$$

$$
\qquad\quad+\beta^{\varepsilon}(f^{\varepsilon+,\boldsymbol{n}}_{i-1,j}+f^{\varepsilon-,\boldsymbol{n}}_{i,j+1}-g^{\varepsilon+,\boldsymbol{n}}_{i,j}-g^{\varepsilon-,\boldsymbol{n}}_{i-1,j+1})\Big).
$$

From the expressions (5.7),

$$
\alpha^{\varepsilon}, \ \beta^{\varepsilon} \to \frac{1}{\sigma R}, \text{ when } \varepsilon \to 0.
$$

Yet, passing into the limit we obtain both (5.11) and (5.12) . If initially f and g are identical, they stay so. More precisely, let $D_{i,j}^n = \mathfrak{f}_{i,j}^n - \mathfrak{g}_{i,j}^n$ be the Maxwellian gap,

$$
D_{i,j}^{n+1} = D_{i,j}^n (1 - \frac{2\Delta t}{\sigma R^2}) + \frac{\Delta t}{4\sigma R^2} (4D_{i,j}^n - D_{i,j-1}^n - D_{i-1,j}^n - D_{i+1,j}^n - D_{i,j+1}^n). \tag{5.16}
$$

Hypotheses on initial data in Theorem 5.6 ensure that

$$
\|\Delta \mathfrak{f}^0\|_1 + \|\Delta \mathfrak{g}^0\|_1 \leq C.
$$

Moreover, from (5.11) – (5.12) and (5.9) , we have

$$
\|\Delta \mathbf{\hat{y}}^{n+1}\|_1 \le \|\Delta \mathbf{\hat{y}}^n\|_1 (1 - \frac{\Delta t}{\sigma R^2}) + \frac{\Delta t}{\sigma R^2} \|\Delta \mathbf{\hat{y}}^n\|_1
$$

$$
\|\Delta \mathbf{\hat{y}}^{n+1}\|_1 \le \|\Delta \mathbf{\hat{y}}^n\|_1 (1 - \frac{\Delta t}{\sigma R^2}) + \frac{\Delta t}{\sigma R^2} \|\Delta \mathbf{\hat{y}}^n\|_1.
$$

As a consequence, for all $n \in \mathbb{N}$, we have $||\Delta \mathfrak{f}^n||_1 + ||\Delta \mathfrak{g}^n||_1 \leq C$, so that

$$
\sum_{i,j} |4D_{i,j}^n - D_{i,j-1}^n - D_{i-1,j}^n - D_{i+1,j}^n - D_{i,j+1}^n| \le C.
$$

By inserting this latter inequality into (5.16), taking modulus and summing,

$$
||D^{n+1}||_1 = \sum_{i,j} \Delta x^2 |D^{n+1}_{i,j}| \le ||D^n||_1 (1 - \frac{2\Delta t}{\sigma R^2}) + C\frac{\Delta t}{\sigma},
$$

holds for some constant $C \geq 0$. Applying a discrete Gronwall inequality,

$$
||D^n||_1 \le ||D^0||_1 e^{-2n\Delta t/(\sigma R^2)} + C \frac{\Delta t}{\sigma} \sum_{k=0}^{n-1} \left(1 - \frac{2\Delta t}{\sigma R^2}\right)^k
$$

\$\leq ||D^0||_1 e^{-2n\Delta t/(\sigma R^2)} + \frac{C}{2}R^2\$.

Remark 3. *The bound (5.13) relates to (1.4) and means that, for constant opacity,* $||\mathfrak{f} - \mathfrak{g}||_1$ *is roughly of order* Δx^2 *when nonnegative initial data belong to* $W^{2,1}(\mathbb{R}^2)$. Conversely, both $||f^+ - f^-||_1$ and $||g^+ - g^-||_1$ are of order ε , as in the 1D *case, see* [11, Lemma 8.4] and [14]. All in all, these will be similar when $\varepsilon \simeq O(R^2)$.

6. Numerical assessments. Hereafter, some benchmarks for both (3.5) and (4.3) are presented, on a coarse 32×32 uniform Cartesian grid. The computational domain is the unit square $\Omega = (0, 1)^2$ with various boundary conditions.

6.1. Hyperbolic/kinetic scaling. Following [8, §5.1], the long-time stabilization of (1.3) can be considered in presence of a stiff, discontinuous opacity,

$$
\sigma(\mathbf{x})=5+995\cdot\chi\left(\max(|x-\frac{1}{2}|,|y-\frac{1}{2}|)<\frac{1}{4}\right),
$$

with $\chi(A)$ the indicator function of a set A. A null initial data and an inflow boundary condition is prescribed on the left side by means of,

$$
f^+(x = 0, \cdot) = g^-(x = 0, \cdot) = 1,
$$

along with specular reflection on horizontal walls $y = 0$, $y = 1$, and outflow at $x = 1$. The macroscopic velocity field $\vec{v}(t, \mathbf{x})$ is defined as the following ratio,

$$
\forall \mathbf{x} \in \Omega, \qquad \vec{v}(t, \mathbf{x}) = \left(\frac{f^+(t, \mathbf{x}) - f^-(t, \mathbf{x})}{\rho(t, \mathbf{x}) - g^-(t, \mathbf{x}) \over \rho(t, \mathbf{x})} \right), \qquad \text{where } \rho \neq 0.
$$

The scheme (3.5) was set with $\Delta t = 0.975\sqrt{2} \Delta x$, and iterated up to $T = 35$: see Fig. 6.1. Another benchmark consists in considering smooth, but quickly varying opacity,

Figure 6.1. *Steady-state of (3.5) in presence of a square opaque zone.*

$$
\sigma(\mathbf{x}) = 5 + 195 \exp\left(-\gamma((x - \frac{1}{4})^2 + (x - \frac{1}{2})^2 + (x - \frac{3}{4})^2)\right)
$$

$$
\times \exp\left(-\gamma((y - \frac{1}{4})^2 + (y - \frac{1}{2})^2 + (y - \frac{3}{4})^2)\right), \qquad \gamma = 400,
$$

with identical initial and boundary conditions. Results are displayed on Fig. 6.2. In particular, on both Figs. 6.1 and 6.2, a (second-order) centered approximation of the divergence of the macroscopic flux, div $J(t, x)$ was displayed, so as to shed light on the ability of (3.5) to stabilize on a correct discretization of stationary regimes.

6.2. Diffusive/parabolic scaling. In order to validate the scheme (4.3), the same array of opaque Gaussian bumps was set, along with the parameter $\varepsilon = 10^{-5}$, outflow boundary conditions on each side, and Maxwellian (well-prepared) initial data,

$$
\rho(t = 0, \mathbf{x}) = \exp(-\nu((x - 0.375)^2 + (x - 0.625)^2))
$$

× $\exp(-\nu((y - 0.375)^2 + (y - 0.635)^2))$, $\nu = 250$.

Figure 6.2. *Steady-state of (3.5) in a periodic array of obstacles.*

The scheme was iterated until $T = 15$ with the CFL condition (5.6): see Fig. 6.3. The macroscopic density is correctly confined inside the array of obstacles, showing how tiny the artificial dissipation of the IMEX scheme really is. The Maxwellian gap $|f - g|$ is locally of 10^{-3} , a value compatible with (5.13) because $\Delta x^2 \simeq 10^{-3}$, even in the vicinity of areas of strong variations of $\sigma(\mathbf{x})$; it smoothly decays with time. Beside, Δx^2 is also the order of accuracy for the centered discretization of the diffusion equation (4.8). The macroscopic velocity field \vec{v} is now rescaled,

$$
\forall \mathbf{x} \in \Omega, \qquad \vec{v}(t, \mathbf{x}) = \frac{1}{\varepsilon} \left(\frac{\frac{f^+(t, \mathbf{x}) - f^-(t, \mathbf{x})}{\rho(t, \mathbf{x})}}{\frac{g^+(t, \mathbf{x}) - g^-(t, \mathbf{x})}{\rho(t, \mathbf{x})}} \right), \qquad \rho \neq 0.
$$

A simpler benchmark consists in iterating (4.3) with a Gaussian opacity,

$$
\forall \mathbf{x} \in \Omega, \qquad \sigma(\mathbf{x}) = 5 + 15 \exp\left(-25(|x - \frac{1}{2}|^2 + |y - \frac{1}{2}|^2)\right),
$$

with identical initial and outflow boundary conditions, up to $T = 0.1$: see Fig. 6.4.

7. Conclusion and outlook. The present paper showed that a high-quality, genuinely two-dimensional, numerical scheme (3.5), (4.3) can be deduced from the computations achieved in [4]. Such a strategy is by no means limited to isotropic scattering. Following [11, §10.3], an elementary model of chemotaxis dynamics is,

$$
\partial_t f + \mathbf{v} \cdot \nabla f = \chi(\mathbf{v} \cdot \nabla S) \rho(t, \mathbf{x}) - f(\mathbf{x}, \mathbf{v}), \qquad \mathbf{a} := \nabla S(\bar{\mathbf{x}}) \in \mathbb{R}^2, \tag{7.1}
$$

FIGURE 6.3. *Diffusive approximation* (4.3) at $T = 15$, $\varepsilon = 10^{-5}$ in a periodic array of obstacles.

where ∇S is "frozen" locally at a point $\bar{\mathbf{x}}$ and the biasing function $\chi \geq 0$ is normalized so as to get the standard 2D continuity equation:

$$
\int_{\mathbb{S}^1} \chi(\mathbf{v}) \frac{\mathrm{d}\mathbf{v}}{2\pi} = 1, \qquad \partial_t \rho(t, \mathbf{x}) + \text{div } \mathbf{J} = 0.
$$

The analogue of the Laplace transform in (2.1) for steady-states $f(\mathbf{x}, \mathbf{v})$ reads,

$$
f(\mathbf{x}, \mathbf{v}) = \chi(\mathbf{v}) \int_0^\infty \exp(-r)\rho(\mathbf{x} - r\mathbf{v}) dr = \chi(\mathbf{v})\mathcal{L}_r(\tilde{\rho}_{\mathbf{x}, \mathbf{v}})[p = 1], \tag{7.2}
$$

from which follows a new Fredholm equation, now involving the biasing function χ ,

$$
\rho(\mathbf{x}) = \int_0^\infty \exp(-r) \left(\int_{\mathbb{S}^1} \chi(\mathbf{v}) \, \rho(\mathbf{x} - r\mathbf{v}) \frac{d\mathbf{v}}{2\pi} \right) dr. \tag{7.3}
$$

To mimic some computations of [4], macroscopic steady-states should verify,

$$
\forall r \in \mathbb{R}^+, \qquad \rho(\mathbf{x}) = \int_{\mathbb{S}^1} \chi(\mathbf{v}) \rho(\mathbf{x} - r\mathbf{v}) \frac{d\mathbf{v}}{2\pi},
$$

which means that *our "biasing function" χ should also be the "Poisson kernel" of a certain elliptic differential operator that* $\rho(\mathbf{x})$ *solves*. Indeed, $\rho(\mathbf{x} - r\mathbf{v})$ is "boundary data" on \mathbb{S}^1 , so $\rho(\mathbf{x})$ is the "solution value". Accordingly, from [3, eqn (2.24)],

$$
\rho(\mathbf{x}) = \int_0^{2\pi} \rho\left(\mathbf{x} + r e^{i\theta}\right) \frac{\exp(-\omega r \cos(\theta - \mu))}{\mathcal{I}_0(\omega r)} \frac{d\theta}{2\pi},
$$

FIGURE 6.4. *Diffusive approximation* (*4.3*) at $T = 15$, $\varepsilon = 10^{-5}$ *with a Gaussian opacity.*

so that, by changing $\theta \to \theta - \pi$, one gets (see also [6, 10, 20])

$$
\rho(\mathbf{x}) = \int_{-\pi}^{\pi} \rho\left(\mathbf{x} - r e^{i\theta}\right) \frac{\exp(\omega r \cos(\theta - \mu))}{\mathcal{I}_0(\omega r)} \frac{d\theta}{2\pi},
$$

Pick, as the biasing function, (\mathcal{I}_0) , the modified Bessel function of index zero)

$$
\chi(\mathbf{v} = e^{i\theta}) = \frac{\exp(\omega \, r \cos(\theta - \mu))}{\mathcal{I}_0(\omega \, r)} \ge 0, \qquad \int_0^{2\pi} \frac{\exp(\omega \, r \cos \theta)}{\mathcal{I}_0(\omega \, r)} \frac{d\theta}{2\pi} = 1,
$$

the normalization being a consequence of the "integral representation of Bessel functions", see *e.g.* [3, eqn (3.1)], then such a kernel corresponds to drift-diffusion equation,

$$
-\Delta \rho + \mathbf{a} \cdot \nabla \rho = 0, \qquad \text{in the disk of radius } r > 0,
$$
\n
$$
(7.4)
$$

where (see again [3, eqns (2.1–3) and (2.12)]), for $\mu \in (0, 2\pi)$,

$$
0 \leq \omega := \frac{\|\mathbf{a}\|}{2}, \qquad \frac{\mathbf{a}}{2} = \omega(\cos \mu, \sin \mu) \in \mathbb{R}^2,
$$

is the polar representation of the drift velocity $\mathbf{a} \in \mathbb{R}^2$ in (7.4). Accordingly, one can relate mesoscopic to macroscopic steady-states thanks to (7.2), and similar derivations as the ones performed in this article may lead to a "truly two-dimensional", asymptotic-preserving (in diffusive scaling) discretization of (7.1), like (3.5) and (4.3).

Appendix A. *S***-matrix for Goldstein-Taylor model in 1D.**

It might be interesting to recall some properties of "two-stream" one-dimensional (position-dependent) radiative transfer, already studied in [14], [11, §8.2] and [7, 9],

$$
\partial_t f^{\pm} \pm \partial_x f^{\pm} = \sigma(x)(\rho/2 - f^{\pm}), \qquad \rho = f^+ + f^-.
$$

Macroscopic (diffusive) stationary regimes in 1D reduce to $\rho''(x) = 0$, *i.e.* constant or linear functions, and yield Case's polynomial solutions, 1 and $x - v$. Accordingly, for $R = \Delta x/2$ and $f(x, v) = \alpha + \beta(x - v)$,

$$
M = \begin{pmatrix} 1 & -(1 + \sigma R) \\ 1 & (1 + \sigma R) \end{pmatrix}, \qquad \tilde{M} = \begin{pmatrix} 1 & -(1 - \sigma R) \\ 1 & (1 - \sigma R) \end{pmatrix},
$$

so that,

$$
|M| = 2(1 + \sigma R), \qquad M^{-1} = \frac{1}{2} \begin{pmatrix} 1 & 1 \\ -\frac{1}{1 + \sigma R} & \frac{1}{1 + \sigma R} \end{pmatrix},
$$

meaning that α is the average of incoming states, and

$$
S(\sigma) = \tilde{M} M^{-1} = \frac{1}{1 + \sigma R} \begin{pmatrix} 1 & \sigma R \\ \sigma R & 1 \end{pmatrix}.
$$

Such a *S*-matrix is "doubly-stochastic" because both its rows and columns add to unity and all its entries are positive when $\sigma R \geq 0$. Asymptotic limits are

$$
S(\sigma) \to \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \text{ if } \sigma \to 0, \qquad S(\sigma) \to \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \text{ if } \sigma \to +\infty.
$$

The resulting well-balanced 1D time-marching scheme reads,

$$
\begin{pmatrix} f_j^{+,n+1} \\ f_{j-1}^{-,n+1} \end{pmatrix} = (1 - \frac{\Delta t}{2R}) \begin{pmatrix} f_j^{+,n} \\ f_{j-1}^{-,n} \end{pmatrix} + \frac{\Delta t}{2R} S(\sigma_{j-\frac{1}{2}}) \begin{pmatrix} f_{j-1}^{+,n} \\ f_j^{-,n} \end{pmatrix}.
$$

In parabolic scaling, the following decomposition holds,

$$
S(\sigma) = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} + \frac{\varepsilon}{\varepsilon + \sigma R} \begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix},
$$

and brings back the well-known IMEX scheme originally written in [14],

$$
\begin{split} \begin{pmatrix} f_j^{+,n+1} \\ f_{j-1}^{-,n+1} \end{pmatrix} + \frac{\Delta t}{2\varepsilon R} \left(\begin{array}{cc} 0 & 1 \\ 1 & 0 \end{array} \right) \begin{pmatrix} f_j^{+,n+1} \\ f_{j-1}^{-,n+1} \end{pmatrix} \\ &= \begin{pmatrix} f_j^{+,n} \\ f_{j-1}^{-,n} \end{pmatrix} + \frac{\Delta t}{2R(\varepsilon + \sigma R)} \begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix} \begin{pmatrix} f_j^{+,n} \\ f_j^{-,n} \end{pmatrix}. \end{split}
$$

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