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# A TRULY TWO-DIMENSIONAL, ASYMPTOTIC-PRESERVING SCHEME FOR A DISCRETE MODEL OF RADIATIVE TRANSFER 

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#### Abstract

For a four-stream approximation of the kinetic model of radiative transfer wih isotropic scattering, a numerical scheme endowed with both truly-2D well-balanced and diffusive asymptotic-preserving properties is derived, in the same spirit as what was done in [14] in the 1D case. Building on former results of Birkhoff and Abu-Shumays, [4], it is possible to express 2D kinetic steady-states by means of harmonic polynomials, and this allows to build a scattering $S$ matrix yielding a time-marching scheme. Such a $S$-matrix can be decomposed, as in $\|15\|$, so as to deduce another scheme, well-suited for a diffusive approximation of the kinetic model, for which rigorous convergence can be proved. Challenging benchmarks are also displayed on coarse grids.


Key words. Diffusive scaling; Four-stream approximation; Grey radiative transfer; $S$-matrix.
AMS subject classifications. 31A05, 65M06, 76R50, 82B40, 85A25.

## 1. Introduction and preliminaries.

1.1. Kinetic modeling in 2D. We are interested in a "truly two-dimensional" numerical simulation of the simple kinetic model, where $\mathbf{x}=(x, y)$ and $\mathbf{v}=(\xi, \eta)$,

$$
\partial_{t} f(t, \mathbf{x}, \mathbf{v})+\mathbf{v} \cdot \nabla_{\mathbf{x}} f=\sigma(\mathbf{x})\left(\int_{\mathbb{S}^{1}} f\left(t, \mathbf{x}, \mathbf{v}^{\prime}\right) \frac{\mathrm{d} \mathbf{v}^{\prime}}{2 \pi}-f\right), \quad|\mathbf{v}|=1
$$

in particular, of its "four-stream approximation", evoked in e.g. [17, §5] or [9],

$$
\begin{equation*}
\partial_{t} f^{ \pm} \pm \partial_{x} f^{ \pm}=\sigma(x, y)\left(\rho / 4-f^{ \pm}\right), \quad \partial_{t} g^{ \pm} \pm \partial_{y} g^{ \pm}=\sigma(x, y)\left(\rho / 4-g^{ \pm}\right), \tag{1.1}
\end{equation*}
$$

where the "opacity" $\sigma(x, y) \geq 0$ and the macroscopic density simplifies into,

$$
\forall t, \mathbf{x} \in \mathbb{R}^{+} \times \mathbb{R}^{2}, \quad \rho(t, \mathbf{x})=f^{+}(t, \mathbf{x})+f^{-}(t, \mathbf{x})+g^{+}(t, \mathbf{x})+g^{-}(t, \mathbf{x})
$$

In order to take full advantage of a 9 -points, so-called Moore, stencil, microscopic velocities are rotated so as to be aligned with the diagonals of a Cartesian grid,

$$
\begin{equation*}
\mathbf{v}=\left(\frac{ \pm 1}{\sqrt{2}}(1,1), \frac{ \pm 1}{\sqrt{2}}(-1,1)\right) \tag{1.2}
\end{equation*}
$$

like, for instance, in [5, §2.1]. This choice leads to the following 2D system,

$$
\left\{\begin{array}{l}
\partial_{t} f^{ \pm} \pm \frac{1}{\sqrt{2}}\left(\partial_{x} f^{ \pm}+\partial_{y} g^{ \pm}\right)=\sigma(x, y)\left(\frac{\rho}{4}-f^{ \pm}\right),  \tag{1.3}\\
\partial_{t} g^{ \pm} \mp \frac{1}{\sqrt{2}}\left(\partial_{x} f^{ \pm}-\partial_{y} g^{ \pm}\right)=\sigma(x, y)\left(\frac{\rho}{4}-g^{ \pm}\right),
\end{array}\right.
$$

for which we propose a numerical scheme endowed with similar properties as the one in [14], in a two-dimensional context, without domain decomposition, like [2, 16, 19].

[^0]1.2. Diffusive approximation to (1.1). To study diffusive limits of (1.1), one rescales $(t, \mathbf{x}) \rightarrow\left(\varepsilon^{2} t, \varepsilon \mathbf{x}\right)$ in order to produce,
$$
\varepsilon \partial_{t} f^{ \pm} \pm \partial_{x} f^{ \pm}=\frac{\sigma(\mathbf{x})}{\varepsilon}\left(\frac{\rho}{4}-f^{ \pm}\right), \quad \varepsilon \partial_{t} g^{ \pm} \pm \partial_{y} g^{ \pm}=\frac{\sigma(\mathbf{x})}{\varepsilon}\left(\frac{\rho}{4}-g^{ \pm}\right)
$$
and introduces macroscopic quantities, mass and flux,
$$
\rho=f^{+}+f^{-}+g^{+}+g^{-}, \quad \mathbf{J}=\frac{1}{\varepsilon}\binom{f^{+}-f^{-}}{g^{+}-g^{-}} \in \mathbb{R}^{2} .
$$

By summing the four balance laws, the continuity equation emerges,

$$
\partial_{t} \rho+\operatorname{div} \mathbf{J}=0
$$

However, as noted in [17, page 504], the equation on $\mathbf{J}$ isn't closed,

$$
\begin{equation*}
\varepsilon^{2} \partial_{t} \mathbf{J}+\nabla\binom{f^{+}+f^{-}}{g^{+}+g^{-}}=-\sigma(\mathbf{x}) \mathbf{J} \tag{1.4}
\end{equation*}
$$

so that, formally, the asymptotic behavior appears to be given by,

$$
\partial_{t} \rho=\partial_{x}\left(\frac{\partial_{x}\left(f^{+}+f^{-}\right)}{\sigma(\mathbf{x})}\right)+\partial_{y}\left(\frac{\partial_{y}\left(g^{+}+g^{-}\right)}{\sigma(\mathbf{x})}\right)
$$

However, by subtracting the first (second) and the third (fourth) balance laws,

$$
\varepsilon \partial_{t}\left(f^{ \pm}-g^{ \pm}\right) \pm\left(\partial_{x} f^{ \pm}-\partial_{y} g^{ \pm}\right)=-\frac{\sigma}{\varepsilon}\left(f^{ \pm}-g^{ \pm}\right)
$$

we get that $\left|f^{ \pm}-g^{ \pm}\right|=O(\varepsilon)$, so former calculations can be improved into,

$$
\varepsilon^{2} \partial_{t} \mathbf{J}+\nabla\left(\frac{\rho}{2}\right)=-\sigma \mathbf{J}-\frac{1}{2} \nabla\binom{\left(f^{+}-g^{+}\right)+\left(f^{-}-g^{-}\right)}{\left(g^{+}-f^{+}\right)+\left(g^{-}-f^{-}\right)}=-\sigma \mathbf{J}-O(\varepsilon)
$$

which leads to the expected diffusion equation (see also (4.8),

$$
\begin{equation*}
\partial_{t} \rho(t, \mathbf{x})=\operatorname{div}\left(\frac{\nabla \rho}{2 \sigma(\mathbf{x})}\right), \quad \text { or } \partial_{t} \rho=\frac{\Delta \rho}{2 \sigma} \text { if } \sigma \text { is a constant. } \tag{1.5}
\end{equation*}
$$

These formal arguments were made fully rigorous in 17] when $\sigma$ is a constant.
1.3. Plan of the paper. This text follows a similar roadmap as the original article [14], with the supplementary difficulty that every derivation must now be made on two-dimensional kinetic models. To proceed, we recall in $\S 2$ the pioneering results of [4], thanks to which one can deduce, by means of Laplace transforms, kinetic steady-states from harmonic functions. Following ideas of [12, 13], a $S$-matrix is derived, in $\$ 3$, from the data of such polynomial kinetic steady-states, yielding a time-marching scheme (3.5), which is able to preserve non-trivial 2D equilibria (see Theorem 3.2). Moreover, the $S$-matrix being doubly-stochastic, it is straightforward to show that (3.5) preserves positivity as well as $L^{1} / L^{\infty}$ bounds, like its continuous counterpart. Drawing on our paper [15], after a parabolic rescaling of variables, the $S$-matrix decomposes nicely so as to yield an IMEX scheme (4.1) which relaxes, as $\varepsilon \rightarrow 0$, towards (4.8), which is a consistent discretization of (1.5). Rigorous proofs are produced in $\$ 5$, in particular in Theorem 5.6, where we can see that the multidimensional feature (1.4), raised in 17], has consequences at the numerical level. These bounds are visualized in $\S 6$ where several challenging benchmarks for both (3.5) and (4.3) are tested on a coarse $32 \times 32$ Cartesian grid. Finally, $\S 7$ paves the way for tackling more complex kinetic models, like (7.1), and some early results of [14] are rephrased in the context of $S$-matrices in Appendix A.

## 2. Harmonic stationary distributions.

2.1. Harmonic functions and isotropic scattering. In [4] , the authors present a tricky procedure which allows to derive an infinity of (explicit) exact steady-states of the following multi-dimensional kinetic model,

$$
\partial_{t} f(t, \mathbf{x}, \mathbf{v})+\mathbf{v} \cdot \nabla_{\mathbf{x}} f=\int_{\mathbb{S}^{1}} f\left(t, \mathbf{x}, \mathbf{v}^{\prime}\right) \frac{\mathrm{d} \mathbf{v}^{\prime}}{2 \pi}-f, \quad \mathbf{x}=(x, y), \quad \mathbf{v}=(\xi, \eta)
$$

In virtue of the method of characteristics, long-time asymptotics $t \rightarrow+\infty$ satisfy,

$$
\begin{equation*}
f(\mathbf{x}, \mathbf{v})=\int_{0}^{\infty} \exp (-r) \rho(\mathbf{x}-r \mathbf{v}) \mathrm{d} r, \quad \rho(\mathbf{x})=\int_{\mathbb{S}^{1}} f(\mathbf{x}, \mathbf{v}) \frac{\mathrm{d} \mathbf{v}}{2 \pi} \tag{2.1}
\end{equation*}
$$

which is the Laplace transform of the (oriented) one-dimensional trace of $\rho$, [18],

$$
\begin{equation*}
\tilde{\rho}_{\mathbf{x}, \mathbf{v}}: \mathbb{R}^{+} \ni r \mapsto \rho(\mathbf{x}-r \mathbf{v}), \quad f(\mathbf{x}, \mathbf{v})=\mathcal{L}_{r}\left(\tilde{\rho}_{\mathbf{x}, \mathbf{v}}\right)[p=1] \tag{2.2}
\end{equation*}
$$

A Fredholm equation (of the second kind) follows by integrating again in $\mathbf{v} \in \mathbb{S}^{1}$,

$$
\begin{equation*}
\forall \mathbf{x} \in \mathbb{R}^{2}, \quad \rho(\mathbf{x})=\int_{0}^{\infty} \exp (-r)\left(\int_{\mathbb{S}^{1}} \rho(\mathbf{x}-r \mathbf{v}) \frac{\mathrm{d} \mathbf{v}}{2 \pi}\right) \mathrm{d} r \tag{2.3}
\end{equation*}
$$

At this point, the authors of [4] claim that, as the long-time behavior of the kinetic model is pure diffusion and $\rho$ is a macroscopic quantity, harmonic functions may induce mesoscopic steady-states by means of (2.1). Hence, if $\rho$ is a steady-state of diffusion, $\Delta \rho=0$, and its mean-value property [6, 10, 20] yields,

$$
\forall r \in \mathbb{R}^{+}, \quad \rho(\mathbf{x})=\int_{\mathbb{S}^{1}} \rho(\mathbf{x}-r \mathbf{v}) \frac{\mathrm{d} \mathbf{v}}{2 \pi}
$$

so that, by multiplying by $\exp (-r)$ and integrating in $r \in \mathbb{R}^{+}$,

$$
\int_{0}^{\infty} \rho(\mathbf{x}) \exp (-r) \mathrm{d} r=\rho(\mathbf{x})=\int_{0}^{\infty} \exp (-r)\left(\int_{\mathbb{S}^{1}} \rho(\mathbf{x}-r \mathbf{v}) \frac{\mathrm{d} \mathbf{v}}{2 \pi}\right) \mathrm{d} r
$$

holds for any $\mathbf{x} \in \mathbb{R}^{2}$, so that (2.3) is satisfied, and a class of stationary kinetic densities $f(\mathbf{x}, \mathbf{v})$ can be deduced from (2.1). For instance, harmonic polynomials furnish an infinity of 2D mesoscopic steady-states, which generalize the only two $1, x-v$ (see e.g. 11, Chap. 9]), which follow from $\rho^{\prime \prime}(x)=0$ in one dimension.
2.2. Kinetic steady-states and harmonic polynomials. A major result in [4] is that kinetic stationary solutions $f(\mathbf{x}, \mathbf{v})$ can be deduced from macroscopic (i.e. diffusive, or harmonic) ones $\rho(\mathbf{x})$, by means of a Laplace transform of $r \mapsto \rho(\mathbf{x}-r \mathbf{v})$,

$$
\begin{equation*}
f(\mathbf{x}, \mathbf{v})=\int_{0}^{\infty} \rho(\mathbf{x}-r \mathbf{v}) \exp (-r) \mathrm{d} r, \quad \Delta \rho=0 \tag{2.4}
\end{equation*}
$$

as soon as certain integrability conditions are met (see [4, Theorem A]). Accordingly, in the special case where $\mathbf{x}=x \in \mathbb{R}$ (one space dimension), harmonic solutions of $\mathrm{d}^{2} \rho / \mathrm{d} x^{2}=0$ reduce to $\{1, x\}$ and it comes that, for $v \in \mathbb{R}$,

$$
f(x, v)=\int_{0}^{\infty} \exp (-r) \mathrm{d} r=1, \quad f(x, v)=\int_{0}^{\infty}(x-r v) \exp (-r) \mathrm{d} r=x-v
$$

which are well-known "separated variables Case's solutions", see [11, eqn (9.8)]. In more space dimensions, harmonic functions are abundant (any holomorphic function of $z=x+i y \in \mathbb{C}$ furnishes two harmonic ones: its real and imaginary parts), so that (2.4) yields an infinite set of polynomial solutions, being

$$
\begin{align*}
& f(\mathbf{x}, \mathbf{v})=\left\{1, \mathbf{x}-\mathbf{v} \in \mathbb{R}^{2}\right.  \tag{2.5}\\
&\left.x y-(x \eta+y \xi)+2 \xi \eta, \frac{x^{2}-y^{2}}{2}-(x \xi-y \eta)+\left(\xi^{2}-\eta^{2}\right), \ldots \text { etc }\right\}
\end{align*}
$$

see [4, eqn (2.6)]. The first ones correspond to "dimensional splitting", whereas last two ones are truly 2D and "conjugate" in a certain sense (as seen below). These stationary distributions $f(\mathbf{x}, \mathbf{v})$ can be easily retrieved from (2.4) by taking advantage of the expression of harmonic functions in polar coordinates,

$$
\begin{equation*}
\rho(x=r \cos \theta, y=r \sin \theta)=a_{0}+\sum_{n \in \mathbb{N}_{*}}\left(a_{n} \cos n \theta+b_{n} \sin n \theta\right) r^{n} \tag{2.6}
\end{equation*}
$$

in which the first basis components are

$$
\left\{1, x=r \cos \theta, y=r \sin \theta, x^{2}-y^{2}=r^{2} \cos 2 \theta, x y=r^{2} \sin 2 \theta, \ldots\right\}
$$

These "harmonic steady-states" $f(\mathbf{x}, \mathbf{v})$ follow from Euler's Gamma function,

$$
\Gamma(x)=\int_{0}^{\infty} \exp (-t) t^{x-1} \mathrm{~d} t, \quad \Gamma(n)=(n-1)!\text { if } n \in \mathbb{N}
$$

because, according to (2.1), the polynomial solutions given in (2.6) rewrite,

$$
f(\mathbf{x}, \mathbf{v})=\{\Gamma(1), \Gamma(1) \mathbf{x}-\Gamma(2) \mathbf{v}, \Gamma(1) x y-\Gamma(2)(x \eta+y \xi)+\Gamma(3) \xi \eta, \ldots\}
$$

3. A "truly $2 \mathbf{D}$ " approximation of $f(t, \mathbf{x}, \mathbf{v})$. Working on a uniform Cartesian grid for which $\Delta x=\Delta y$, we mimic the notation already used in [3], see Fig. 3.1.
3.1. Derivation of the $S$-matrix. In order to simulate (1.3) on a 9-points stencil, we only need the first four stationary solutions: the choice between the two "truly 2D" quadratic ones depends on the velocity vectors. A simple case, where one of the conjugate solutions is always null, consists in working in diagonal coordinates,

$$
\mathbf{x}=(\mp R, 0) \text { and }(0, \mp R), \quad \mathbf{v}=( \pm 1,0) \text { and }(0, \pm 1)
$$

where $R=\Delta x / \sqrt{2}$ is the radius of the disc centered in $x_{i-\frac{1}{2}}, y_{j+\frac{1}{2}}$. The $S$-matrix acts on four incoming states and produces four outgoing ones, so

$$
\left(\begin{array}{c}
f_{*}^{+} \\
f_{*}^{-} \\
g_{*}^{+} \\
g_{*}^{-}
\end{array}\right)=S_{i-\frac{1}{2}, j+\frac{1}{2}}\left(\begin{array}{c}
f_{i-1, j}^{+} \\
f_{i, j+1}^{-} \\
g_{i, j}^{+} \\
g_{i-1, j+1}^{-}
\end{array}\right)
$$

By linearity, and following ideas from [11, Chap. 9], a $C^{\infty}$ stationary solution reads,

$$
\begin{equation*}
f(\mathbf{x}, \mathbf{v})=\alpha+\beta(x-\xi)+\gamma(y-\eta)+\nu\left(\frac{x^{2}-y^{2}}{2}-(x \xi-y \eta)+\left(\xi^{2}-\eta^{2}\right)\right) \tag{3.1}
\end{equation*}
$$



Figure 3.1. The $S$-matrix $S_{i-\frac{1}{2}, j+\frac{1}{2}}$ and an incoming state, $f_{i-1, j}^{+}$.
so that aforementioned "incoming" and "outgoing" states are, respectively,

$$
\left\{\begin{array}{l}
f_{i-1, j}^{+}=f(\mathbf{x}=(-R, 0), \mathbf{v}=(1,0)), \quad f_{i, j+1}^{-}=f(\mathbf{x}=(R, 0), \mathbf{v}=(-1,0)), \\
g_{i, j}^{+}=f(\mathbf{x}=(0,-R), \mathbf{v}=(0,1)), \quad g_{i-1, j+1}^{-}=f(\mathbf{x}=(0, R), \mathbf{v}=(0,-1))
\end{array}\right.
$$

which is a linear system for $(\alpha, \beta, \gamma, \nu)$, and

$$
\left\{\begin{array}{l}
f_{*}^{+}=f(\mathbf{x}=(R, 0), \mathbf{v}=(1,0)), \quad f_{*}^{-}=f(\mathbf{x}=(-R, 0), \mathbf{v}=(-1,0)), \\
g_{*}^{+}=f(f \mathbf{x}=(0, R), \mathbf{v}=(0,1)), \quad g_{*}^{-}=f(\mathbf{x}=(0,-R), \mathbf{v}=(0,-1))
\end{array}\right.
$$

involving again the "spectral coefficients" $(\alpha, \beta, \gamma, \nu) \in \mathbb{R}^{4}$ which values are fixed by the four incoming states. Accordingly, the $S$-matrix decomposes again like,

$$
\begin{equation*}
\forall(i, j) \in \mathbb{Z}^{2}, \quad S_{i-\frac{1}{2}, j+\frac{1}{2}}=S\left(\sigma_{i-\frac{1}{2}, j+\frac{1}{2}}\right), \quad S(\sigma)=\tilde{M} M^{-1} \tag{3.2}
\end{equation*}
$$

where $M$ has mutually orthogonal columns,

$$
M=\left(\begin{array}{cccc}
1 & -(1+\sigma R) & 0 & 1+(1+\sigma R)^{2}  \tag{3.3}\\
1 & (1+\sigma R) & 0 & 1+(1+\sigma R)^{2} \\
1 & 0 & -(1+\sigma R) & -\left(1+(1+\sigma R)^{2}\right) \\
1 & 0 & (1+\sigma R) & -\left(1+(1+\sigma R)^{2}\right)
\end{array}\right)
$$

along with its companion $\tilde{M}$,

$$
\tilde{M}=\left(\begin{array}{cccc}
1 & -(1-\sigma R) & 0 & 1+(1-\sigma R)^{2} \\
1 & 1-\sigma R & 0 & 1+(1-\sigma R)^{2} \\
1 & 0 & -(1-\sigma R) & -\left(1+(1-\sigma R)^{2}\right) \\
1 & 0 & (1-\sigma R) & -\left(1+(1-\sigma R)^{2}\right)
\end{array}\right)
$$

in which a rescaling of $\mathbf{x}$ was made in order to cope with variable opacity $\sigma(\mathbf{x})$. One recognizes the matrices of 1D Goldstein-Taylor model, see $\S A$ and [11, Remark 9.3],

$$
\left(\begin{array}{cc}
1 & -(1+\sigma R) \\
1 & (1+\sigma R)
\end{array}\right), \quad\left(\begin{array}{cc}
1 & -(1-\sigma R) \\
1 & (1-\sigma R)
\end{array}\right)
$$

but now, 1D solutions $\sigma \mathbf{x}-\mathbf{v}$ are coupled by the constant and quadratic ones.
3.2. Resulting 2D time-marching scheme. For $\sigma R \geq 0$, the determinant $|M|$ is positive, so $M$ is invertible and its inverse reads:

$$
|M|=8(1+\sigma R)^{2}\left(1+(1+\sigma R)^{2}\right), \quad M^{-1}=\left(\begin{array}{cccc}
\frac{1}{4} & \frac{1}{4} & \frac{1}{4} & \frac{1}{4} \\
-A & A & 0 & 0 \\
0 & 0 & -A & A \\
B & B & -B & -B
\end{array}\right)
$$

so that $\alpha$ is always the average of the four incoming states, and where

$$
A=\frac{1}{2(1+\sigma R)}, \quad B=\frac{1}{4\left(1+(1+\sigma R)^{2}\right)}
$$

Accordingly, the $S$-matrix is given by the product,

$$
\begin{align*}
S(\sigma) & =\tilde{M} M^{-1}  \tag{3.4}\\
& =\left(\begin{array}{cccc}
\frac{1}{4}+C+D & \frac{1}{4}-C+D & \frac{1}{4}-D & \frac{1}{4}-D \\
\frac{1}{4}-C+D & \frac{1}{4}+C+D & \frac{1}{4}-D & \frac{1}{4}-D \\
\frac{1}{4}-D & \frac{1}{4}-D & \frac{1}{4}+C+D & \frac{1}{4}-C+D \\
\frac{1}{4}-D & \frac{1}{4}-D & \frac{1}{4}-C+D & \frac{1}{4}+C+D
\end{array}\right)
\end{align*}
$$

which both lines and columns clearly add to unity, because

$$
C=\frac{1-\sigma R}{2(1+\sigma R)}=\frac{1}{2}-\frac{\sigma R}{1+\sigma R}, \quad D=\frac{(1-\sigma R)^{2}+1}{4\left((1+\sigma R)^{2}+1\right)}=\frac{1}{4}-\frac{\sigma R}{1+(1+\sigma R)^{2}}
$$

The $S$-matrix rewrites as a $O(\sigma R)$-perturbation of the identity of $\mathbb{R}^{4}$,

$$
\begin{aligned}
S(\sigma)=\operatorname{Id}_{\mathbb{R}^{4}}+\sigma R\left\{\frac{1}{1+\sigma R}\right. & \left(\begin{array}{cccc}
-1 & 1 & 0 & 0 \\
1 & -1 & 0 & 0 \\
0 & 0 & -1 & 1 \\
0 & 0 & 1 & -1
\end{array}\right) \\
& \left.+\frac{1}{1+(1+\sigma R)^{2}}\left(\begin{array}{cccc}
-1 & -1 & 1 & 1 \\
-1 & -1 & 1 & 1 \\
1 & 1 & -1 & -1 \\
1 & 1 & -1 & -1
\end{array}\right)\right\}
\end{aligned}
$$

so that, similarly to e.g. 15, Prop. 3.2],

$$
S(\sigma) \rightarrow \mathrm{Id}_{\mathbb{R}^{4}} \text { if } \sigma \rightarrow 0, \quad S(\sigma) \rightarrow S^{0}=\left(\begin{array}{cccc}
0 & 1 & 0 & 0 \\
1 & 0 & 0 & 0 \\
0 & 0 & 0 & 1 \\
0 & 0 & 1 & 0
\end{array}\right) \text { if } \sigma \rightarrow+\infty
$$

Having at hand the $4 \times 4$ matrix (3.2) allows to deduce a time-marching scheme for the 2D system (1.3) on a uniform Cartesian grid (see Fig. 3.1, $\Delta x=\Delta y$ ),

$$
\left(\begin{array}{c}
f_{i, j+1}^{+, n+1}  \tag{3.5}\\
f_{i-1, j}^{-,+n+1} \\
g_{i-1, j+1}^{+,+1+1} \\
g_{i, j}^{-, n+1}
\end{array}\right)=\left(1-\frac{\Delta t}{2 R}\right)\left(\begin{array}{c}
f_{i, n}^{+, n} \\
f_{i-1, n}^{-}, n \\
g_{i-1, j}^{+,-1, j+1} \\
g_{i, j}^{-, n}
\end{array}\right)+\frac{\Delta t}{2 R} S\left(\sigma_{i-\frac{1}{2}, j+\frac{1}{2}}\right)\left(\begin{array}{c}
f_{i-1, j}^{+, n} \\
f_{i, n}^{-, n+1} \\
g_{i, n}^{+,, n} \\
g_{i-1, j+1}^{-, n}
\end{array}\right)
$$

Lemma 3.1. Under the $C F L$ restriction $\Delta t \leq 2 R$, the scheme (3.5) is consistent with (1.3) and preserves positivity. Moreover, it is conservative and $L^{\infty}$-bounded.

Proof. Under the aforementioned CFL restriction, (3.5) is a convex combination (as advocated in [12, eqn (2.2)]), hence it preserves positivity because all the entries of $S(\sigma)$ are nonnegative. Besides, doubly-stochastic matrices are such that,

$$
\forall \vec{v} \in \mathbb{R}^{4}, \quad\|S(\sigma) \vec{v}\|_{\infty} \leq\|\vec{v}\|_{\infty},\|S(\sigma) \vec{v}\|_{1} \leq\|\vec{v}\|_{1}
$$

which implies that (3.5) is bounded in $L^{1}$ and $L^{\infty}$. Consistency is shown for $0 \leq$ $\sigma R \ll 1$ (fine grid); at first order, the expression of the $S$-matrix reduces to,

$$
\frac{1}{1+(1+\sigma R)^{2}} \simeq \frac{1}{2(1+\sigma R)}, \quad S(\sigma)=\operatorname{Id}_{\mathbb{R}^{4}}+\frac{\sigma R}{2(1+\sigma R)}\left(\begin{array}{cccc}
-3 & 1 & 1 & 1 \\
1 & -3 & 1 & 1 \\
1 & 1 & -3 & 1 \\
1 & 1 & 1 & -3
\end{array}\right)
$$

and inserting this expression in (3.5) yields a consistent approximation of (1.3). $\square$
The scheme (3.5) is able to preserve some non-trivial 2D equilibria, see e.g. [1].
THEOREM 3.2 (2D well-balanced). Let $\sigma(\mathbf{x}) \equiv \bar{\sigma}>0$ a constant, then any linear combination (3.1) induces a numerical steady-state for the scheme (3.5), given by

$$
f^{ \pm}\left(\frac{x-y}{\sqrt{2}}, \frac{x+y}{\sqrt{2}}\right)=f(\bar{\sigma} \mathbf{x} ;( \pm 1,0)), \quad g^{ \pm}\left(\frac{x-y}{\sqrt{2}}, \frac{x+y}{\sqrt{2}}\right)=f(\bar{\sigma} \mathbf{x} ;(0, \pm 1))
$$

Proof. Pick $(\alpha, \beta, \gamma, \nu) \in \mathbb{R}^{4}$ in (3.1) and consider a steady-state $f(\bar{\sigma} \mathbf{x}, \mathbf{v})$ : since $|M|>0$, its restriction to $\mathbf{v}=\{( \pm 1,0),(0, \pm 1)\}$ on a uniform Cartesian grid satisfies,

$$
\left(\begin{array}{c}
\alpha \\
\beta \\
\gamma \\
\nu
\end{array}\right)=M^{-1}\left(\begin{array}{c}
f_{i-1, j}^{+, n} \\
f_{i, n}^{-,+1} \\
g_{i, n}^{+, n} \\
g_{i-1, j+1}^{-, n}
\end{array}\right) \Rightarrow S(\bar{\sigma})\left(\begin{array}{c}
f_{i-1, j}^{+, n} \\
f_{i, n}^{-, n+1} \\
g_{i, j}^{+, n} \\
g_{i-1, j+1}^{-, n}
\end{array}\right)=\left(\begin{array}{c}
f_{i, j+1}^{+, n} \\
f_{i, n}^{,, n} \\
g_{i-n, j}^{+,-1, j+1} \\
g_{i, j}^{-, n}
\end{array}\right)
$$

so they are invariant by the time-marching scheme (3.5). By a $-\frac{\pi}{4}$ rotation we pass from diagonal coordinates with $\mathbf{v}=\{( \pm 1,0),(0, \pm 1)\}$ to axial ones with (1.2).
4. Diffusive behavior of the $S$-matrix. In order to study asymptotic limits so as to check a possible consistency with the estimates stated in [17, Theorem 5.1], we rescale $\sigma(\mathbf{x}) \rightarrow \sigma(\mathbf{x}) / \varepsilon, \varepsilon \ll 1$. Accordingly, the $S$-matrix decomposes into $S^{0}+\varepsilon S^{1, \varepsilon}$, like in [15, §1.2], where, as $\varepsilon \rightarrow 0$, Following again [15], an IMEX scheme may read

$$
\begin{align*}
& \left(\begin{array}{c}
f_{i, j+1}^{+, n+1} \\
f_{i-n+1}^{-, n+1} \\
g_{i-1, j+1}^{+, n+1} \\
g_{i, j}^{-, n+1}
\end{array}\right)+\frac{\Delta t}{2 \varepsilon R}\left\{\left(\begin{array}{c}
f_{i, j}^{+, n+1} \\
f_{i-1, j}^{--n+1} \\
g_{i-1, j+1}^{+, n+1} \\
g_{i, j}^{-, n+1}
\end{array}\right)-S^{0}\left(\begin{array}{c}
f_{i-1, j}^{+, n+1} \\
f_{i, j+1}^{-, n+1} \\
g_{i, j}^{+, n+1} \\
g_{i-1, j+1}^{--, n+1}
\end{array}\right)\right\}  \tag{4.1}\\
& =\left(\begin{array}{c}
f_{i, j+1}^{+, n} \\
f_{i-1, j}^{-, n} \\
g_{i-1, j, j+1}^{+,-1, j+1} \\
g_{i, j}^{-, n}
\end{array}\right)+\frac{\Delta t}{2 R} S^{1, \varepsilon}\left(\begin{array}{c}
f_{i-1, j}^{+, n} \\
f_{i, j}^{-, n+1} \\
g_{i, n}^{+, n} \\
g_{i-1, j+1}^{-, n}
\end{array}\right),
\end{align*}
$$

and we expect the (implicit, but not costly) left-hand side to yield "Maxwellian estimates" of the type [17, eqn (5.15)], and the (explicit) right-hand side to produce accurate and consistent diffusive numerical fluxes.
4.1. Decomposition of the $S$-matrix. By defining the positive coefficients,

$$
\begin{equation*}
\alpha_{i-\frac{1}{2}, j+\frac{1}{2}}^{\varepsilon}=\frac{1}{\varepsilon+\sigma_{i-\frac{1}{2}, j+\frac{1}{2}} R} ; \quad \beta_{i-\frac{1}{2}, j+\frac{1}{2}}^{\varepsilon}=\frac{\sigma_{i-\frac{1}{2}, j+\frac{1}{2}} R}{\varepsilon^{2}+\left(\varepsilon+\sigma_{i-\frac{1}{2}, j+\frac{1}{2}} R\right)^{2}} \tag{4.2}
\end{equation*}
$$

the aforementioned decomposition reads, at each location $i-\frac{1}{2}, j+\frac{1}{2}$,

$$
S^{\varepsilon}=\left(\begin{array}{llll}
0 & 1 & 0 & 0 \\
1 & 0 & 0 & 0 \\
0 & 0 & 0 & 1 \\
0 & 0 & 1 & 0
\end{array}\right)+\varepsilon\left(\begin{array}{cccc}
\alpha-\beta & -(\alpha+\beta) & \beta & \beta \\
-(\alpha+\beta) & \alpha-\beta & \beta & \beta \\
\beta & \beta & \alpha-\beta & -(\alpha+\beta) \\
\beta & \beta & -(\alpha+\beta) & \alpha-\beta
\end{array}\right),
$$

hence, the IMEX scheme (4.1) rewrites as,

$$
\begin{aligned}
f_{i, j+1}^{+, n+1}+ & \frac{\Delta t}{2 \varepsilon R}\left(f_{i, j+1}^{+, n+1}-f_{i, j+1}^{-, n+1}\right)=f_{i, j+1}^{+, n}+ \\
& \frac{\Delta t}{2 R}\left[\alpha_{i-\frac{1}{2}, j+\frac{1}{2}}^{\varepsilon}\left(f_{i-1, j}^{+, n}-f_{i, j+1}^{-, n}\right)+\beta_{i-\frac{1}{2}, j+\frac{1}{2}}^{\varepsilon}\left(-f_{i-1, j}^{+, n}-f_{i, j+1}^{-, n}+g_{i, j}^{+, n}+g_{i-1, j+1}^{-, n}\right)\right] \\
f_{i-1, j}^{-, n+1}+ & \frac{\Delta t}{2 \varepsilon R}\left(f_{i-1, j}^{-, n+1}-f_{i-1, j}^{+, n+1}\right)=f_{i-1, j}^{-, n}+ \\
& \frac{\Delta t}{2 R}\left[\alpha_{i-\frac{1}{2}, j+\frac{1}{2}}^{\varepsilon}\left(f_{i, j+1}^{-, n}-f_{i-1, j}^{+, n}\right)+\beta_{i-\frac{1}{2}, j+\frac{1}{2}}^{\varepsilon}\left(-f_{i-1, j}^{+, n}-f_{i, j+1}^{-, n}+g_{i, j}^{+, n}+g_{i-1, j+1}^{-, n}\right)\right] \\
g_{i-1, j+1}^{+, n+1}+ & \frac{\Delta t}{2 \varepsilon R}\left(g_{i-1, j+1}^{+, n+1}-g_{i-1, j+1}^{-, n+1}\right)=g_{i-1, j+1}^{+, n}+ \\
& \frac{\Delta t}{2 R}\left[\alpha_{i-\frac{1}{2}, j+\frac{1}{2}}^{\varepsilon}\left(g_{i, j}^{+, n}-g_{i-1, j+1}^{-, n}\right)+\beta_{i-\frac{1}{2}, j+\frac{1}{2}}^{\varepsilon}\left(f_{i-1, j}^{+, n}+f_{i, j+1}^{-, n}-g_{i, j}^{+, n}-g_{i-1, j+1}^{-, n}\right)\right] \\
g_{i, j}^{-, n+1} & +\frac{\Delta t}{2 \varepsilon R}\left(g_{i, j}^{-, n+1}-g_{i, j}^{+, n+1}\right)=g_{i, j}^{-, n}+ \\
& \frac{\Delta t}{2 R}\left[\alpha_{i-\frac{1}{2}, j+\frac{1}{2}}^{\varepsilon}\left(g_{i-1, j+1}^{-, n}-g_{i, j}^{+, n}\right)+\beta_{i-\frac{1}{2}, j+\frac{1}{2}}^{\varepsilon}\left(f_{i-1, j}^{+, n}+f_{i, j+1}^{-, n}-g_{i, j}^{+, n}-g_{i-1, j+1}^{-, n}\right)\right] .
\end{aligned}
$$

An index-shift yields:

$$
\begin{align*}
& \left(\begin{array}{cccc}
1+\frac{\Delta t}{2 \varepsilon R} & -\frac{\Delta t}{2 \varepsilon R} & 0 & 0 \\
-\frac{\Delta t}{2 \varepsilon R} & 1+\frac{\Delta t}{2 \varepsilon R} & 0 & 0 \\
0 & 0 & 1+\frac{\Delta t}{2 \varepsilon R} & -\frac{\Delta t}{2 \varepsilon R} \\
0 & 0 & -\frac{2 t}{2 \varepsilon R} & 1+\frac{\Delta t}{2 \varepsilon R}
\end{array}\right)\left(\begin{array}{c}
f_{i, j}^{+, n+1} \\
f_{i, j}^{-, n+1} \\
g_{i, j}^{+, n+1} \\
g_{i, j}^{-, n+1}
\end{array}\right)=\left(\begin{array}{c}
f_{i, j}^{+, n} \\
f_{i, j}^{-, n} \\
g_{i, j}^{+, n} \\
g_{i, j}^{-, n}
\end{array}\right)+ \tag{4.3}
\end{align*}
$$

The implicit part relies on a block-diagonal matrix, for which,

$$
\left(\begin{array}{cc}
1+b & -b \\
-b & 1+b
\end{array}\right)^{-1}=\frac{1}{a+b}\left(\begin{array}{cc}
a & b \\
b & a
\end{array}\right), \quad b=\frac{\Delta t}{2 \varepsilon R}, \quad a=1+\frac{\Delta t}{2 \varepsilon R}
$$

so that (4.3) rewrites as an explicit time-marching scheme. The matrix in the left hand side of (4.3) may be written as

$$
\operatorname{Id}_{\mathbb{R}^{4}}+\frac{\Delta t}{2 \varepsilon R} H_{0}, \quad \text { with } \quad H_{0}=\left(\begin{array}{cccc}
1 & -1 & 0 & 0  \tag{4.4}\\
-1 & 1 & 0 & 0 \\
0 & 0 & 1 & -1 \\
0 & 0 & -1 & 1
\end{array}\right)
$$

Denoting $\mathfrak{f}_{i, j}^{n}=f_{i, j}^{+, n}+f_{i, j}^{-, n}$ and $\mathfrak{g}_{i, j}^{n}=g_{i, j}^{+, n}+g_{i, j}^{-, n}$, their time evolution follows from adding the first two and the last two equations in (4.3):

$$
\begin{gather*}
\mathfrak{f}_{i, j}^{n+1}=\mathfrak{f}_{i, j}^{n}+\frac{\Delta t}{2 R}\left(\alpha_{i-\frac{1}{2}, j-\frac{1}{2}}^{\varepsilon}\left(f_{i-1, j-1}^{+, n}-f_{i, j}^{-, n}\right)+\alpha_{i+\frac{1}{2}, j+\frac{1}{2}}^{\varepsilon}\left(f_{i+1, j+1}^{-, n}-f_{i, j}^{+, n}\right)\right) \\
-\frac{\Delta t}{2 R}\left(\beta_{i-\frac{1}{2}, j-\frac{1}{2}}^{\varepsilon}\left(f_{i-1, j-1}^{+, n}+f_{i, j}^{-, n}-g_{i, j-1}^{+, n}-g_{i-1, j}^{-, n}\right)\right.  \tag{4.5}\\
\left.+\beta_{i+\frac{1}{2}, j+\frac{1}{2}}^{\varepsilon}\left(f_{i, j}^{+, n}+f_{i+1, j+1}^{-, n}-g_{i+1, j}^{+, n}-g_{i, j+1}^{-, n}\right)\right) \\
\mathfrak{g}_{i, j}^{n+1}=\mathfrak{g}_{i, j}^{n}+\frac{\Delta t}{2 R}\left(\alpha_{i+\frac{1}{2}, j-\frac{1}{2}}^{\varepsilon}\left(g_{i+1, j-1}^{+, n}-g_{i, j}^{-, n}\right)+\alpha_{i-\frac{1}{2}, j+\frac{1}{2}}^{\varepsilon}\left(g_{i-1, j+1}^{-, n}-g_{i, j}^{+, n}\right)\right) \\
+\frac{\Delta t}{2 R}\left(\beta_{i+\frac{1}{2}, j-\frac{1}{2}}^{\varepsilon}\left(f_{i, j-1}^{+, n}+f_{i+1, j}^{-, n}-g_{i+1, j-1}^{+, n}-g_{i, j}^{-, n}\right)\right.  \tag{4.6}\\
\\
\left.+\beta_{i-\frac{1}{2}, j+\frac{1}{2}}^{\varepsilon}\left(f_{i-1, j}^{+, n}+f_{i, j+1}^{-, n}-g_{i, j}^{+, n}-g_{i-1, j+1}^{-, n}\right)\right)
\end{gather*}
$$

4.2. Formal diffusive limit. When $\varepsilon \rightarrow 0$, we deduce from (4.3) that,

$$
\left(\begin{array}{l}
f_{i, j}^{+, n+1}  \tag{4.7}\\
f_{i, j}^{-, n+1} \\
g_{i, j}^{+, n+1} \\
g_{i, j}^{-, n+1}
\end{array}\right) \in \operatorname{Ker}\left(H_{0}\right)=\operatorname{Span}\left\{\left(\begin{array}{l}
1 \\
1 \\
0 \\
0
\end{array}\right),\left(\begin{array}{l}
0 \\
0 \\
1 \\
1
\end{array}\right)\right\}
$$

Then, in the limit $\varepsilon \rightarrow 0$, we expect, at least formally, that

$$
f_{i, j}^{+, n+1}=f_{i, j}^{-, n+1}=\frac{1}{2} \mathfrak{f}_{i, j}^{n+1}, \quad g_{i, j}^{+, n+1}=g_{i, j}^{-, n+1}=\frac{1}{2} \mathfrak{g}_{i, j}^{n+1}
$$

along with, from (4.2),

$$
\alpha_{i-\frac{1}{2}, j+\frac{1}{2}}^{\varepsilon}, \beta_{i-\frac{1}{2}, j+\frac{1}{2}}^{\varepsilon} \rightarrow \frac{1}{\sigma_{i-\frac{1}{2}, j+\frac{1}{2}} R}, \quad \varepsilon \rightarrow 0
$$

so that, former equations (4.5) and (4.6) become

$$
\begin{aligned}
\mathfrak{f}_{i, j}^{n+1}=\mathfrak{f}_{i, j}^{n}+\frac{\Delta t}{4 R^{2}}( & \frac{1}{\sigma_{i-\frac{1}{2}, j-\frac{1}{2}}}\left(\left(\mathfrak{g}_{i-1, j}^{n}-\mathfrak{f}_{i, j}^{n}\right)+\left(\mathfrak{g}_{i, j-1}^{n}-\mathfrak{f}_{i, j}^{n}\right)\right) \\
& \left.+\frac{1}{\sigma_{i+\frac{1}{2}, j+\frac{1}{2}}}\left(\left(\mathfrak{g}_{i+1, j}^{n}-\mathfrak{f}_{i, j}^{n}\right)+\left(\mathfrak{g}_{i, j+1}^{n}-\mathfrak{f}_{i, j}^{n}\right)\right)\right) \\
\mathfrak{g}_{i, j}^{n+1}=\mathfrak{g}_{i, j}^{n}+\frac{\Delta t}{4 R^{2}}( & \frac{1}{\sigma_{i-\frac{1}{2}, j+\frac{1}{2}}}\left(\left(\mathfrak{f}_{i, j+1}^{n}-\mathfrak{g}_{i, j}^{n}\right)+\left(\mathfrak{f}_{i-1, j}^{n}-\mathfrak{g}_{i, j}^{n}\right)\right) \\
& \left.+\frac{1}{\sigma_{i+\frac{1}{2}, j-\frac{1}{2}}}\left(\left(\mathfrak{f}_{i+1, j}^{n}-\mathfrak{g}_{i, j}^{n}\right)+\left(\mathfrak{f}_{i, j-1}^{n}-\mathfrak{g}_{i, j}^{n}\right)\right)\right) .
\end{aligned}
$$

Accordingly, $\mathfrak{f}$ and $\mathfrak{g}$ satisfy similar diffusion equations, if the opacity $\sigma$ is smooth. Consequently, if initially they are close enough (so-called "well-prepared initial data"), they can be expected to stay so because their difference $\mathfrak{f}_{i, j}^{n}-\mathfrak{g}_{i, j}^{n}$ satisfies a parabolic equation. The decay of $\mathfrak{f}-\mathfrak{g}$ will be rigorously proved when $\sigma$ is a constant, see

Theorem 5.6. Adding, assuming $\mathfrak{f}-\mathfrak{g} \rightarrow 0$, and denoting $\rho_{i, j}^{n}=\mathfrak{f}_{i, j}^{n}+\mathfrak{g}_{i, j}^{n}$, it comes

$$
\begin{align*}
\rho_{i, j}^{n+1}=\rho_{i, j}^{n}+\frac{\Delta t}{2 \sigma R^{2}}( & \left(\frac{1}{2 \sigma_{i+\frac{1}{2}, j+\frac{1}{2}}}+\frac{1}{2 \sigma_{i+\frac{1}{2}, j-\frac{1}{2}}}\right)\left(\rho_{i+1, j}^{n}-\rho_{i, j}^{n}\right)  \tag{4.8}\\
+ & \left(\frac{1}{2 \sigma_{i+\frac{1}{2}, j+\frac{1}{2}}}+\frac{1}{2 \sigma_{i-\frac{1}{2}, j+\frac{1}{2}}}\right)\left(\rho_{i, j+1}^{n}-\rho_{i, j}^{n}\right) \\
& -\left(\frac{1}{2 \sigma_{i-\frac{1}{2}, j+\frac{1}{2}}}+\frac{1}{2 \sigma_{i-\frac{1}{2}, j-\frac{1}{2}}}\right)\left(\rho_{i, j}^{n}-\rho_{i-1, j}^{n}\right) \\
& \left.\quad-\left(\frac{1}{2 \sigma_{i+\frac{1}{2}, j-\frac{1}{2}}}+\frac{1}{2 \sigma_{i-\frac{1}{2}, j-\frac{1}{2}}}\right)\left(\rho_{i, j}^{n}-\rho_{i, j-1}^{n}\right)\right) .
\end{align*}
$$

which is a second-order, finite-differences, monotone (under the CFL restriction (5.6)) discretization of the macroscopic diffusion equation (1.5).
5. Rigorous uniform estimates for constant opacity. Let $\left(u_{i, j}\right)$ stand for any real sequence, we introduce the following notations,

$$
\begin{align*}
\delta u_{i+\frac{1}{2}, j} & =u_{i+1, j}-u_{i, j}, \quad \delta u_{i, j+\frac{1}{2}}=u_{i, j+1}-u_{i, j} \\
\|u\|_{1} & =\sum_{i, j} \Delta x^{2}\left|u_{i, j}\right|, \quad T V(u)=\sum_{i, j} \Delta x\left(\left|\delta u_{i+\frac{1}{2}, j}\right|+\left|\delta u_{i, j+\frac{1}{2}}\right|\right)  \tag{5.1}\\
\|\Delta u\|_{1} & =\sum_{i, j}\left|u_{i+1, j}+u_{i, j+1}+u_{i-1, j}+u_{i, j-1}-4 u_{i, j}\right|
\end{align*}
$$

5.1. General properties of the scheme. The first stepping stone is the definition of a convenient CFL restriction:

Lemma 5.1. Assume that there exists $\sigma_{\min }>0$ such that the opacity is such that $0<\sigma_{\min } \leq \sigma_{i-\frac{1}{2}, j+\frac{1}{2}}$ for all $i, j$. Then, under the CFL condition

$$
\begin{equation*}
\Delta t \leq \min \left\{\frac{2}{3} \sigma_{\min } R^{2}, \frac{R\left(\varepsilon+\sigma_{\min } R\right)}{2}\left(1+\sqrt{1+\frac{8 \varepsilon}{\varepsilon+\sigma_{\min } R}}\right)\right\} \tag{5.2}
\end{equation*}
$$

the IMEX scheme (4.3) preserves positivity.
Proof. Inverting the block-diagonal matrix in (4.3) brings the expressions,

$$
\begin{align*}
f_{i, j}^{+, n+1} & =\frac{1}{2 \varepsilon R+2 \Delta t}\left(\left(2 \varepsilon R+\Delta t-\frac{\Delta t^{2}}{2 R}\left(\alpha_{i+\frac{1}{2}, j+\frac{1}{2}}^{\varepsilon}+\beta_{i+\frac{1}{2}, j+\frac{1}{2}}^{\varepsilon}\right)\right) f_{i, j}^{+, n}\right. \\
& +\left(\Delta t-\frac{\Delta t}{2 R}(2 \varepsilon R+\Delta t)\left(\alpha_{i-\frac{1}{2}, j-\frac{1}{2}}^{\varepsilon}+\beta_{i-\frac{1}{2}, j-\frac{1}{2}}^{\varepsilon}\right)\right) f_{i, j}^{-, n} \\
& +(2 \varepsilon R+\Delta t) \frac{\Delta t}{2 R}\left(\alpha_{i-\frac{1}{2}, j-\frac{1}{2}}^{\varepsilon}-\beta_{i-\frac{1}{2}, j-\frac{1}{2}}^{\varepsilon}\right) f_{i-1, j-1}^{+, n}  \tag{5.3}\\
& +\frac{\Delta t^{2}}{2 R}\left(\alpha_{i+\frac{1}{2}, j+\frac{1}{2}}^{\varepsilon}-\beta_{i+\frac{1}{2}, j+\frac{1}{2}}^{\varepsilon}\right) f_{i+1, j+1}^{-, n} \\
& +(2 \varepsilon R+\Delta t) \frac{\Delta t}{2 R} \beta_{i-\frac{1}{2}, j-\frac{1}{2}}^{\varepsilon}\left(g_{i, j-1}^{+, n}+g_{i-1, j}^{-, n}\right) \\
& \left.+\frac{\Delta t^{2}}{2 R} \beta_{i+\frac{1}{2}, j+\frac{1}{2}}^{\varepsilon}\left(g_{i+1, j}^{+, n}+g_{i, j+1}^{-, n}\right)\right)
\end{align*}
$$

and

$$
\begin{aligned}
f_{i, j}^{-, n+1} & =\frac{1}{2 \varepsilon R+2 \Delta t}\left(\left(\Delta t-(2 \varepsilon R+\Delta t) \frac{\Delta t}{2 R}\left(\alpha_{i+\frac{1}{2}, j+\frac{1}{2}}^{\varepsilon}+\beta_{i+\frac{1}{2}, j+\frac{1}{2}}^{\varepsilon}\right)\right) f_{i, j}^{+, n}\right. \\
& +\left(2 \varepsilon R+\Delta t-\frac{\Delta t^{2}}{2 R}\left(\alpha_{i-\frac{1}{2}, j-\frac{1}{2}}^{\varepsilon}+\beta_{i-\frac{1}{2}, j-\frac{1}{2}}^{\varepsilon}\right)\right) f_{i, j}^{-, n} \\
& +\frac{\Delta t^{2}}{2 R}\left(\alpha_{i-\frac{1}{2}, j-\frac{1}{2}}^{\varepsilon}-\beta_{i-\frac{1}{2}, j-\frac{1}{2}}^{\varepsilon}\right) f_{i-1, j-1}^{+, n} \\
& +(2 \varepsilon R+\Delta t) \frac{\Delta t}{2 R}\left(\alpha_{i+\frac{1}{2}, j+\frac{1}{2}}^{\varepsilon}-\beta_{i+\frac{1}{2}, j+\frac{1}{2}}^{\varepsilon}\right) f_{i+1, j+1}^{-, n} \\
& +\frac{\Delta t^{2}}{2 R} \beta_{i-\frac{1}{2}, j-\frac{1}{2}}\left(g_{i, j-1}^{+, n}+g_{i-1, j}^{-, n}\right) \\
& \left.+(2 \varepsilon R+\Delta t) \frac{\Delta t}{2 R} \beta_{i+\frac{1}{2}, j+\frac{1}{2}}^{\varepsilon}\left(g_{i+1, j}^{+, n}+g_{i, j+1}^{-, n}\right)\right)
\end{aligned}
$$

along with similar ones for $g_{i, j}^{ \pm, n+1}$, too. From (4.2), it comes

$$
\alpha_{i-\frac{1}{2}, j+\frac{1}{2}}^{\varepsilon}-\beta_{i-\frac{1}{2}, j+\frac{1}{2}}^{\varepsilon}=\frac{\varepsilon^{2}+\varepsilon\left(\varepsilon+\sigma_{i-\frac{1}{2}, j+\frac{1}{2}} R\right)}{\left(\varepsilon+\sigma_{i-\frac{1}{2}, j+\frac{1}{2}} R\right)\left(\varepsilon^{2}+\left(\varepsilon+\sigma_{i-\frac{1}{2}, j+\frac{1}{2}} R\right)^{2}\right)} \geq 0
$$

Define a (decreasing) function $\psi: \mathbb{R}^{+} \rightarrow \mathbb{R}^{+}$,

$$
\psi(x) \stackrel{\text { def }}{=} \frac{1}{\varepsilon+x}+\frac{x}{\varepsilon^{2}+(\varepsilon+x)^{2}}, \quad \psi^{\prime}(x) \leq 0 \text { on }(0,+\infty)
$$

then, since

$$
\alpha_{i-\frac{1}{2}, j+\frac{1}{2}}^{\varepsilon}+\beta_{i-\frac{1}{2}, j+\frac{1}{2}}^{\varepsilon}=\psi\left(\sigma_{i-\frac{1}{2}, j+\frac{1}{2}} R\right)
$$

we get the following bound:

$$
\alpha_{i-\frac{1}{2}, j+\frac{1}{2}}^{\varepsilon}+\beta_{i-\frac{1}{2}, j+\frac{1}{2}}^{\varepsilon} \leq \frac{1}{\varepsilon+\sigma_{\min } R}+\frac{\sigma_{\min } R}{\varepsilon^{2}+\left(\varepsilon+\sigma_{\min } R\right)^{2}}
$$

Hence $f_{i, j}^{ \pm, n+1}, g_{i, j}^{ \pm, n+1}$ ) are nonnegative combinations of previous iterates if,

$$
\begin{align*}
& \left(\varepsilon+\frac{\Delta t}{2 R}\right)\left(\frac{1}{\varepsilon+\sigma_{\min } R}+\frac{\sigma_{\min } R}{\varepsilon^{2}+\left(\varepsilon+\sigma_{\min } R\right)^{2}}\right) \leq 1  \tag{5.4}\\
& \frac{\Delta t^{2}}{2 R}\left(\frac{1}{\varepsilon+\sigma_{\min } R}+\frac{\sigma_{\min } R}{\varepsilon^{2}+\left(\varepsilon+\sigma_{\min } R\right)^{2}}\right) \leq 2 \varepsilon R+\Delta t \tag{5.5}
\end{align*}
$$

Conditions (5.4) and (5.5) are met if and only if,

$$
\frac{\Delta t}{2 R} \leq \sigma_{\min } R \frac{\varepsilon^{2}+\varepsilon \sigma_{\min } R+\left(\sigma_{\min } R\right)^{2}}{2 \varepsilon^{2}+3 \varepsilon \sigma_{\min } R+2\left(\sigma_{\min } R\right)^{2}}, \quad \frac{\Delta t^{2}}{R\left(\varepsilon+\sigma_{\min } R\right)} \leq 2 \varepsilon R+\Delta t
$$

and these hold as soon as (5.2) does.
REMARK 1. A sufficient condition for (5.2) is the heat equation's restriction:

$$
\begin{equation*}
2 \Delta t \leq \sigma_{\min } R^{2} \tag{5.6}
\end{equation*}
$$

Lemma 5.2 (Conservation). Let us assume that the initial data are nonnegative and that (5.2) holds. Then, the scheme (4.3) is bounded in $L^{1}$ and conservative :

$$
\left\|f^{+, n}\right\|_{1}+\left\|f^{-, n}\right\|_{1}+\left\|g^{+, n}\right\|_{1}+\left\|g^{-, n}\right\|_{1}=\left\|f^{+, 0}\right\|_{1}+\left\|f^{-, 0}\right\|_{1}+\left\|g^{+, 0}\right\|_{1}+\left\|g^{-, 0}\right\|_{1}
$$

Proof. It suffices to add the lines of (4.3) and to sum over $i$ and $j$.
Lemma 5.3 ( $L^{\infty}$ bound). Let initial data satisfy

$$
0 \leq f_{i, j}^{ \pm, 0} \leq M, \quad 0 \leq g_{i, j}^{ \pm, 0} \leq M
$$

Then, under the CFL (5.2),

$$
\forall n \in \mathbb{N}, \quad 0 \leq f_{i, j}^{ \pm, n} \leq M, \quad 0 \leq g_{i, j}^{ \pm, n} \leq M
$$

Proof. The proof of Lemma 5.1 yields that, under (5.2), $f_{i, j}^{ \pm, n+1}$ and $g_{i, j}^{ \pm, n+1}$ are convex combination of previous iterates, giving the announced $L^{\infty}$ bound. $\square$

REMARK 2. These bounds hold even if the opacity $\sigma$ isn't a (positive) constant.
5.2. Uniform estimates in the case $\sigma$ constant. We study rigorously the diffusive limit of (4.3) in order to prove that it is "asymptotic-preserving" (AP). Recall from (4.2) the coefficients,

$$
\begin{equation*}
\alpha^{\varepsilon}=\frac{1}{\varepsilon+\sigma R} ; \quad \beta^{\varepsilon}=\frac{\sigma R}{\varepsilon^{2}+(\varepsilon+\sigma R)^{2}}, \quad \text { for } \sigma \equiv \bar{\sigma} \in \mathbb{R}^{+} \tag{5.7}
\end{equation*}
$$

As $\sigma$ is constant, (4.3) simplifies into,

$$
\begin{align*}
& \left(\begin{array}{cccc}
1+\frac{\Delta t}{2 \varepsilon R} & -\frac{\Delta t}{2 \varepsilon R} & 0 & 0 \\
-\frac{\Delta t}{2 \varepsilon R} & 1+\frac{\Delta t}{2 \varepsilon R} & 0 & 0 \\
0 & 0 & 1+\frac{\Delta t}{2 \varepsilon R} & -\frac{\Delta t}{2 \varepsilon R} \\
0 & 0 & -\frac{\Delta t}{2 \varepsilon R} & 1+\frac{\Delta t}{2 \varepsilon R}
\end{array}\right)\left(\begin{array}{l}
f_{i, j}^{+, n+1} \\
f_{i, j}^{-}, n+1 \\
g_{i, j}^{+, n+1} \\
g_{i, j}^{-, n+1}
\end{array}\right)=\left(\begin{array}{l}
f_{i, j}^{+, n} \\
f_{i, j}^{-},{ }_{j} \\
g_{i, j}^{+, n} \\
g_{i, j}^{-, n}
\end{array}\right)  \tag{5.8}\\
& +\frac{\Delta t}{2 R}\left(\begin{array}{c}
\alpha^{\varepsilon}\left(f_{i-1, j-1}^{+, n}-f_{i, n}^{-, n}\right)-\beta^{\varepsilon}\left(f_{i-1, j-1}^{+, n}+f_{i, j}^{-, n}-g_{i, j-1}^{+, n}-g_{i-1, j}^{--, n}\right) \\
\alpha^{\varepsilon}\left(f_{i+n}^{-, n, 1, j+1}-f_{i, j}^{+, n}\right)-\beta^{\varepsilon}\left(f_{i, n}^{+, n}+f_{i+n}^{-,+1, j+1}-g_{i+n}^{+, n}-g_{i, j}^{-, n+1}\right) \\
\alpha^{\varepsilon}\left(g_{i+1, j}^{+,+1, j-1}-g_{i, j}^{-}, n\right. \\
\alpha^{\varepsilon}\left(g_{i-1, j+1}^{-, n}-\beta_{i, j}^{+,, n}\left(f_{i, n}^{+, n-1}+f_{i+n}^{-, n, j}-g_{i+1, n-1}^{+,+1, j-1}-g_{i, j}^{-, n}\right)\right. \\
\beta^{\varepsilon}\left(f_{i-1, j}^{+, n}+f_{i, n+1}^{-, n}-g_{i, j}^{+, n}-g_{i-1, j+1}^{-, n}\right)
\end{array}\right)
\end{align*}
$$

Lemma 5.4. Let $\sigma$ be a positive constant: under the parabolic CFL restriction,

$$
\begin{equation*}
2 \Delta t<\sigma_{\min } R^{2} \tag{5.9}
\end{equation*}
$$

the scheme (5.8) is TVD (total variation diminishing),

$$
\begin{aligned}
T V\left(f^{+, n+1}\right) & +T V\left(f^{-, n+1}\right)+T V\left(g^{+, n+1}\right)+T V\left(g^{-, n+1}\right) \\
& \leq T V\left(f^{+, n}\right)+T V\left(f^{-, n}\right)+T V\left(g^{+, n}\right)+T V\left(g^{-, n}\right)
\end{aligned}
$$

Proof. By linearity, the expression of $f_{i, j}^{+, n+1}$ in (5.3) in the proof of Lemma 5.1 is similar to the ones of $\delta f_{i+\frac{1}{2}, j}^{+, n}$. Since (5.9) ensures that coefficients are nonnegative,
a triangle inequality brings,

$$
\begin{aligned}
\left|\delta f_{i+\frac{1}{2}, j}^{+, n+1}\right| & \leq \frac{1}{2 \varepsilon R+2 \Delta t}\left(\left(2 \varepsilon R+\Delta t-\frac{\Delta t^{2}}{2 R}\left(\alpha^{\varepsilon}+\beta^{\varepsilon}\right)\right)\left|\delta f_{i+\frac{1}{2}, j}^{+, n}\right|\right. \\
& +\left(\Delta t-\frac{\Delta t}{2 R}(2 \varepsilon R+\Delta t)\left(\alpha^{\varepsilon}+\beta^{\varepsilon}\right)\right)\left|\delta f_{i+\frac{1}{2}, j}^{-, n}\right| \\
& +(2 \varepsilon R+\Delta t) \frac{\Delta t}{2 R}\left(\alpha^{\varepsilon}-\beta^{\varepsilon}\right)\left|\delta f_{i-\frac{1}{2}, j-1}^{+, n}\right| \\
& +\frac{\Delta t^{2}}{2 R}\left(\alpha^{\varepsilon}-\beta^{\varepsilon}\right)\left|\delta f_{i+\frac{3}{2}, j+1}^{-, n}\right| \\
& +(2 \varepsilon R+\Delta t) \frac{\Delta t}{2 R} \beta^{\varepsilon}\left(\left|\delta g_{i+\frac{1}{2}, j-1}^{+, n}\right|+\left|\delta g_{i-\frac{1}{2}, j}^{-, n}\right|\right) \\
& \left.+\frac{\Delta t^{2}}{2 R} \beta^{\varepsilon}\left(\left|\delta g_{i+\frac{1}{2}, j}^{+, n}\right|+\left|\delta g_{i+\frac{1}{2}, j+1}^{-, n}\right|\right)\right)
\end{aligned}
$$

with similar expressions for $\left|\delta f_{i+\frac{1}{2}}^{-, n}\right|,\left|\delta g_{i \frac{1}{2}, j}^{+, n+1}\right|$ and $\left|\delta g_{i+\frac{1}{2}, j}^{-, n+1}\right|$. Adding,

$$
\begin{aligned}
& \left|\delta f_{i+\frac{1}{2}, j}^{+, n+1}\right|+\left|\delta f_{i+\frac{1}{2}, j}^{-,,+1}\right|+\left|\delta g_{i+\frac{1}{2}, j}^{+, n+1}\right|+\left|\delta g_{i+\frac{1}{2}, j}^{-, n+1}\right| \leq \\
& \quad\left(1-\frac{\Delta t}{2 R}\left(\alpha^{\varepsilon}+\beta^{\varepsilon}\right)\right)\left(\left|\delta f_{i+\frac{1}{2}, j}^{+, n}\right|+\left|\delta f_{i+\frac{1}{2}, j}^{-, n}\right|+\left|\delta g_{i+\frac{1}{2}, j}^{+, n}\right|+\left|\delta g_{i+\frac{1}{2}, j}^{-, n}\right|\right) \\
& \quad+\frac{\Delta t}{2 R}\left(\alpha^{\varepsilon}-\beta^{\varepsilon}\right)\left(\left|\delta f_{i-\frac{1}{2}, j-1}^{+, n}\right|+\left|\delta f_{i+\frac{3}{2}, j+1}^{-, n}\right|+\left|\delta g_{i+\frac{3}{2}, j-1}^{+, n}\right|+\left|\delta g_{i-\frac{1}{2}, j+1}^{-, n}\right|\right) \\
& \quad+\frac{\Delta t}{2 R} \beta^{\varepsilon}\left(\left|\delta f_{i+\frac{1}{2}, j-1}^{+,, n}\right|+\left|\delta f_{i+\frac{3}{2}, j}^{-, n}\right|+\left|\delta f_{i-\frac{1}{2}, j}^{+, n}\right|+\left|\delta f_{i+\frac{1}{2}, j+1}^{-, n}\right|\right) \\
& \quad+\frac{\Delta t}{2 R} \beta^{\varepsilon}\left(\left|\delta g_{i+\frac{1}{2}, j-1}^{+, n}\right|+\left|\delta_{i-\frac{1}{2}, j}^{-, n}\right|+\left|\delta g_{i+\frac{3}{2}, j}^{+, n}\right|+\left|\delta g_{i+\frac{1}{2}, j+1}^{-, n}\right|\right)
\end{aligned}
$$

and summing over $i$ and $j$, we get, after shifting the indexes,

$$
\begin{aligned}
\sum_{i, j}\left(\left|\delta f_{i+\frac{1}{2}, j}^{+, n+1}\right|\right. & \left.+\left|\delta f_{i+\frac{1}{2}, j}^{-, n+1}\right|+\left|\delta g_{i+\frac{1}{2}, j}^{+, n+1}\right|+\left|\delta g_{i+\frac{1}{2}, j}^{-, n+1}\right|\right) \\
& \leq \sum_{i, j}\left(\left|\delta f_{i+\frac{1}{2}, j}^{+, n}\right|+\left|\delta f_{i+\frac{1}{2}, j}^{-, n}\right|+\left|\delta g_{i+\frac{1}{2}, j}^{+, n}\right|+\left|\delta g_{i+\frac{1}{2}, j}^{-, n}\right|\right)
\end{aligned}
$$

By the same token with variations in $j$ instead of $i$, we get the claimed result.
Define $f_{\Delta x}^{ \pm}, g_{\Delta x}^{ \pm}$the piecewise constant functions such that,

$$
\begin{equation*}
f^{ \pm}(t, \mathbf{x})=f_{i, j}^{ \pm, n}, \quad g^{ \pm}(t, \mathbf{x})=g_{i, j}^{ \pm, n} \tag{5.10}
\end{equation*}
$$

for $t \in[n \Delta t,(n+1) \Delta t), \mathbf{x} \in\left(\left(i-\frac{1}{2}\right) \Delta x,\left(i+\frac{1}{2}\right) \Delta x\right) \times\left(\left(j-\frac{1}{2}\right) \Delta x,\left(j+\frac{1}{2}\right) \Delta x\right)$.
Corollary 5.5. Under (5.9), and for bounded integrable nonnegative data, the approximate solutions (5.10) are uniformly bounded in $L^{1} \cap L^{\infty} \cap B V\left([0, T] \times \mathbb{R}^{2}\right)$.
5.3. Rigorous diffusive limit. We are now in position to state the main result of this section:

Theorem 5.6 (Asymptotic-Preserving property). Assume (5.9) holds and that initial data are independent of $\varepsilon$ and smooth enough such that

$$
\exists C \in \mathbb{R}^{+}, \quad\left\|\Delta f^{+, 0}\right\|_{1}+\left\|\Delta f^{-, 0}\right\|_{1}+\left\|\Delta g^{+, 0}\right\|_{1}+\left\|\Delta g^{-, 0}\right\|_{1} \leq C
$$

then the sequences $\left(f_{i, j}^{\varepsilon \pm, n}\right)$ and $\left(g_{i, j}^{\varepsilon \pm, n}\right)$ are of uniformly bounded total variation and converge towards limits, denoted respectively $\left(f_{i, j}^{ \pm, n}\right)$ and $\left(g_{i, j}^{ \pm, n}\right)$ which satisfy:

$$
f_{i, j}^{+, n}=f_{i, j}^{-, n}=\frac{1}{2} \mathfrak{f}_{i, j}^{n}, \quad g_{i, j}^{+, n}=g_{i, j}^{-, n}=\frac{1}{2} \mathfrak{g}_{i, j}^{n},
$$

where

$$
\begin{align*}
\mathfrak{f}_{i, j}^{n+1} & =\mathfrak{f}_{i, j}^{n}+\frac{\Delta t}{4 \sigma R^{2}}\left(\mathfrak{g}_{i, j-1}^{n}+\mathfrak{g}_{i-1, j}^{n}+\mathfrak{g}_{i+1, j}^{n}+\mathfrak{g}_{i, j+1}^{n}-4 \mathfrak{f}_{i, j}^{n}\right)  \tag{5.11}\\
\mathfrak{g}_{i, j}^{n+1} & =\mathfrak{g}_{i, j}^{n}+\frac{\Delta t}{4 \sigma R^{2}}\left(\mathfrak{f}_{i, j-1}^{n}+\mathfrak{f}_{i+1, j}^{n}+\mathfrak{f}_{i-1, j}^{n}+\mathfrak{f}_{i, j+1}^{n}-4 \mathfrak{g}_{i, j}^{n}\right) \tag{5.12}
\end{align*}
$$

Moreover, the "Maxwellian gap" decreases in time according to,

$$
\begin{equation*}
\forall n \in \mathbb{N}_{*}, \quad\left\|\mathfrak{f}^{n}-\mathfrak{g}^{n}\right\|_{1} \leq\left\|\mathfrak{f}^{0}-\mathfrak{g}^{0}\right\|_{1} \exp \left(-\frac{2 n \Delta t}{\sigma R^{2}}\right)+C R^{2} \tag{5.13}
\end{equation*}
$$

Adding both equations (5.11)-(5.12), we deduce the following result:
Corollary 5.7. Under the same assumptions as Theorem 5.6, we have

$$
\rho_{i, j}^{n+1}=\rho_{i, j}^{n}+\frac{\Delta t}{4 \sigma R^{2}}\left(\rho_{i, j-1}^{n}+\rho_{i, j+1}^{n}+\rho_{i-1, j}^{n}+\rho_{i+1, j}^{n}-4 \rho_{i, j}^{n}\right), \quad \rho^{n}=\mathfrak{f}^{n}+\mathfrak{g}^{n} .
$$

along with $f^{ \pm, n}=\rho^{n} / 4+O\left(R^{2}\right), g^{ \pm, n}=\rho^{n} / 4+O\left(R^{2}\right)$.
Proof. By the computations in the proof of Lemma 5.4, the sequences $\left(f_{i, j}^{\varepsilon \pm, n}\right)$, and $\left(g_{i, j}^{\varepsilon \pm, n}\right)$ are Cauchy sequences with respect to $\varepsilon$ in $\ell^{1}$. Thus, when $\varepsilon \rightarrow 0$, they converge to some limits denoted respectively $\left(f_{i, i}^{ \pm, n}\right)$, and $\left(g_{i, j}^{ \pm, n}\right)$ and we can pass to the limit in (5.8). Hence as $\varepsilon \rightarrow 0$, by (4.4) and (4.7), we get that

$$
\forall(i, j, n) \in \mathbb{Z}^{2} \times \mathbb{N}, \quad f_{i, j}^{+, n+1}=f_{i, j}^{-, n+1}, \quad g_{i, j}^{+, n+1}=g_{i, j}^{-, n+1}
$$

Denoting $\mathfrak{f}_{i, j}^{\varepsilon n}=f_{i, j}^{\varepsilon+, n}+f_{i, j}^{\varepsilon-, n}$ and $\mathfrak{g}_{i, j}^{\varepsilon n}=g^{\varepsilon+, n}+g_{i, j}^{\varepsilon-, n}$, we obtain their equations by adding the first two and the last two lines in (5.8):

$$
\begin{align*}
f_{i, j}^{\varepsilon n+1}=f_{i, j}^{\varepsilon n}+ & \frac{\Delta t}{2 R}\left(\alpha^{\varepsilon}\left(f_{i-1, j-1}^{\varepsilon+, n}-f_{i, j}^{\varepsilon-, n}\right)+\alpha^{\varepsilon}\left(f_{i+1, j+1}^{\varepsilon-, n}-f_{i, j}^{\varepsilon+, n}\right)\right) \\
- & \frac{\Delta t}{2 R}\left(\beta^{\varepsilon}\left(f_{i-1, j-1}^{\varepsilon+, n}+f_{i, j}^{\varepsilon-, n}-g_{i, j-1}^{\varepsilon+, n}-g_{i-1, j}^{\varepsilon-, n}\right)\right.  \tag{5.14}\\
& \left.\quad \beta^{\varepsilon}\left(f_{i, j}^{\varepsilon+, n}+f_{i+1, j+1}^{\varepsilon-, n}-g_{i+1, j}^{\varepsilon+, n}-g_{i, j+1}^{\varepsilon-, n}\right)\right) ; \\
\mathfrak{g}_{i, j}^{\varepsilon n+1}=\mathfrak{g}_{i, j}^{\varepsilon n}+ & \frac{\Delta t}{2 R}\left(\alpha^{\varepsilon}\left(g_{i+1, j-1}^{\varepsilon+, n}-g_{i, j}^{\varepsilon-, n}\right)+\alpha^{\varepsilon}\left(g_{i-1, j+1}^{\varepsilon--, n}-g_{i, j}^{\varepsilon+, n}\right)\right) \\
+ & \frac{\Delta t}{2 R}\left(\beta^{\varepsilon}\left(f_{i, j-1}^{\varepsilon+, n}+f_{i+1, j}^{\varepsilon-, n}-g_{i+1, j-1}^{\varepsilon+, n}-g_{i, j}^{\varepsilon-, n}\right)\right.  \tag{5.15}\\
& \left.+\beta^{\varepsilon}\left(f_{i-1, j}^{\varepsilon+, n}+f_{i, j+1}^{\varepsilon-, n}-g_{i, j}^{\varepsilon+, n}-g_{i-1, j+1}^{\varepsilon-, n}\right)\right) .
\end{align*}
$$

From the expressions (5.7),

$$
\alpha^{\varepsilon}, \beta^{\varepsilon} \rightarrow \frac{1}{\sigma R}, \quad \text { when } \varepsilon \rightarrow 0
$$

Yet, passing into the limit we obtain both (5.11) and (5.12). If initially $\mathfrak{f}$ and $\mathfrak{g}$ are identical, they stay so. More precisely, let $D_{i, j}^{n}=\mathfrak{f}_{i, j}^{n}-\mathfrak{g}_{i, j}^{n}$ be the Maxwellian gap,

$$
\begin{equation*}
D_{i, j}^{n+1}=D_{i, j}^{n}\left(1-\frac{2 \Delta t}{\sigma R^{2}}\right)+\frac{\Delta t}{4 \sigma R^{2}}\left(4 D_{i, j}^{n}-D_{i, j-1}^{n}-D_{i-1, j}^{n}-D_{i+1, j}^{n}-D_{i, j+1}^{n}\right) . \tag{5.16}
\end{equation*}
$$

Hypotheses on initial data in Theorem 5.6 ensure that

$$
\left\|\Delta \mathfrak{f}^{0}\right\|_{1}+\left\|\Delta \mathfrak{g}^{0}\right\|_{1} \leq C
$$

Moreover, from (5.11) (5.12) and (5.9), we have

$$
\begin{aligned}
\left\|\Delta \mathfrak{f}^{n+1}\right\|_{1} & \leq\left\|\Delta \mathfrak{f}^{n}\right\|_{1}\left(1-\frac{\Delta t}{\sigma R^{2}}\right)+\frac{\Delta t}{\sigma R^{2}}\left\|\Delta \mathfrak{g}^{n}\right\|_{1} \\
\left\|\Delta \mathfrak{g}^{n+1}\right\|_{1} & \leq\left\|\Delta \mathfrak{g}^{n}\right\|_{1}\left(1-\frac{\Delta t}{\sigma R^{2}}\right)+\frac{\Delta t}{\sigma R^{2}}\left\|\Delta \mathfrak{f}^{n}\right\|_{1}
\end{aligned}
$$

As a consequence, for all $n \in \mathbb{N}$, we have $\left\|\Delta \mathfrak{f}^{n}\right\|_{1}+\left\|\Delta \mathfrak{g}^{n}\right\|_{1} \leq C$, so that

$$
\sum_{i, j}\left|4 D_{i, j}^{n}-D_{i, j-1}^{n}-D_{i-1, j}^{n}-D_{i+1, j}^{n}-D_{i, j+1}^{n}\right| \leq C
$$

By inserting this latter inequality into (5.16), taking modulus and summing,

$$
\left\|D^{n+1}\right\|_{1}=\sum_{i, j} \Delta x^{2}\left|D_{i, j}^{n+1}\right| \leq\left\|D^{n}\right\|_{1}\left(1-\frac{2 \Delta t}{\sigma R^{2}}\right)+C \frac{\Delta t}{\sigma}
$$

holds for some constant $C \geq 0$. Applying a discrete Gronwall inequality,

$$
\begin{aligned}
\left\|D^{n}\right\|_{1} & \leq\left\|D^{0}\right\|_{1} e^{-2 n \Delta t /\left(\sigma R^{2}\right)}+C \frac{\Delta t}{\sigma} \sum_{k=0}^{n-1}\left(1-\frac{2 \Delta t}{\sigma R^{2}}\right)^{k} \\
& \leq\left\|D^{0}\right\|_{1} e^{-2 n \Delta t /\left(\sigma R^{2}\right)}+\frac{C}{2} R^{2}
\end{aligned}
$$

Remark 3. The bound (5.13) relates to (1.4) and means that, for constant opacity, $\|\mathfrak{f}-\mathfrak{g}\|_{1}$ is roughly of order $\Delta x^{2}$ when nonnegative initial data belong to $W^{2,1}\left(\mathbb{R}^{2}\right)$. Conversely, both $\left\|f^{+}-f^{-}\right\|_{1}$ and $\left\|g^{+}-g^{-}\right\|_{1}$ are of order $\varepsilon$, as in the $1 D$ case, see [11, Lemma 8.4] and [14]. All in all, these will be similar when $\varepsilon \simeq O\left(R^{2}\right)$.
6. Numerical assessments. Hereafter, some benchmarks for both (3.5) and (4.3) are presented, on a coarse $32 \times 32$ uniform Cartesian grid. The computational domain is the unit square $\Omega=(0,1)^{2}$ with various boundary conditions.
6.1. Hyperbolic/kinetic scaling. Following [8, §5.1], the long-time stabilization of (1.3) can be considered in presence of a stiff, discontinuous opacity,

$$
\sigma(\mathbf{x})=5+995 \cdot \chi\left(\max \left(\left|x-\frac{1}{2}\right|,\left|y-\frac{1}{2}\right|\right)<\frac{1}{4}\right)
$$

with $\chi(A)$ the indicator function of a set $A$. A null initial data and an inflow boundary condition is prescribed on the left side by means of,

$$
f^{+}(x=0, \cdot)=g^{-}(x=0, \cdot)=1
$$

along with specular reflection on horizontal walls $y=0, y=1$, and outflow at $x=1$. The macroscopic velocity field $\vec{v}(t, \mathbf{x})$ is defined as the following ratio,

$$
\forall \mathbf{x} \in \Omega, \quad \vec{v}(t, \mathbf{x})=\binom{\frac{f^{+}(t, \mathbf{x})-f^{-}(t, \mathbf{x})}{\rho(t, \mathbf{x})}}{\frac{g^{+}(t, \mathbf{x})-g^{-}(t, \mathbf{x})}{\rho(t, \mathbf{x})}}, \quad \text { where } \rho \neq 0 .
$$

The scheme (3.5) was set with $\Delta t=0.975 \sqrt{2} \Delta x$, and iterated up to $T=35$ : see Fig. 6.1. Another benchmark consists in considering smooth, but quickly varying opacity,


Figure 6.1. Steady-state of (3.5) in presence of a square opaque zone.

$$
\begin{aligned}
\sigma(\mathbf{x})=5+195 \exp & \left(-\gamma\left(\left(x-\frac{1}{4}\right)^{2}+\left(x-\frac{1}{2}\right)^{2}+\left(x-\frac{3}{4}\right)^{2}\right)\right) \\
& \times \exp \left(-\gamma\left(\left(y-\frac{1}{4}\right)^{2}+\left(y-\frac{1}{2}\right)^{2}+\left(y-\frac{3}{4}\right)^{2}\right)\right), \quad \gamma=400
\end{aligned}
$$

with identical initial and boundary conditions. Results are displayed on Fig. 6.2. In particular, on both Figs. 6.1 and 6.2, a (second-order) centered approximation of the divergence of the macroscopic flux, $\operatorname{div} \mathbf{J}(t, \mathbf{x})$ was displayed, so as to shed light on the ability of (3.5) to stabilize on a correct discretization of stationary regimes.
6.2. Diffusive/parabolic scaling. In order to validate the scheme (4.3), the same array of opaque Gaussian bumps was set, along with the parameter $\varepsilon=10^{-5}$, outflow boundary conditions on each side, and Maxwellian (well-prepared) initial data,

$$
\begin{aligned}
\rho(t=0, \mathbf{x})=\exp & \left(-\nu\left((x-0.375)^{2}+(x-0.625)^{2}\right)\right) \\
& \times \exp \left(-\nu\left((y-0.375)^{2}+(y-0.635)^{2}\right)\right), \quad \nu=250 .
\end{aligned}
$$



Figure 6.2. Steady-state of (3.5) in a periodic array of obstacles.

The scheme was iterated until $T=15$ with the CFL condition (5.6): see Fig. 6.3. The macroscopic density is correctly confined inside the array of obstacles, showing how tiny the artificial dissipation of the IMEX scheme really is. The Maxwellian gap $|\mathfrak{f}-\mathfrak{g}|$ is locally of $10^{-3}$, a value compatible with (5.13) because $\Delta x^{2} \simeq 10^{-3}$, even in the vicinity of areas of strong variations of $\sigma(\mathbf{x})$; it smoothly decays with time. Beside, $\Delta x^{2}$ is also the order of accuracy for the centered discretization of the diffusion equation (4.8). The macroscopic velocity field $\vec{v}$ is now rescaled,

$$
\forall \mathbf{x} \in \Omega, \quad \vec{v}(t, \mathbf{x})=\frac{1}{\varepsilon}\binom{\frac{f^{+}(t, \mathbf{x})-f^{-}(t, \mathbf{x})}{\rho(t, \mathbf{x})}}{\frac{g^{+}(t, \mathbf{x})-g^{-}(t, \mathbf{x})}{\rho(t, \mathbf{x})}}, \quad \rho \neq 0 .
$$

A simpler benchmark consists in iterating (4.3) with a Gaussian opacity,

$$
\forall \mathbf{x} \in \Omega, \quad \sigma(\mathbf{x})=5+15 \exp \left(-25\left(\left|x-\frac{1}{2}\right|^{2}+\left|y-\frac{1}{2}\right|^{2}\right)\right)
$$

with identical initial and outflow boundary conditions, up to $T=0.1$ : see Fig. 6.4.
7. Conclusion and outlook. The present paper showed that a high-quality, genuinely two-dimensional, numerical scheme (3.5), (4.3) can be deduced from the computations achieved in [4]. Such a strategy is by no means limited to isotropic scattering. Following [11, §10.3], an elementary model of chemotaxis dynamics is,

$$
\begin{equation*}
\partial_{t} f+\mathbf{v} \cdot \nabla f=\chi(\mathbf{v} \cdot \nabla S) \rho(t, \mathbf{x})-f(\mathbf{x}, \mathbf{v}), \quad \mathbf{a}:=\nabla S(\overline{\mathbf{x}}) \in \mathbb{R}^{2} \tag{7.1}
\end{equation*}
$$



Figure 6.3. Diffusive approximation (4.3) at $T=15, \varepsilon=10^{-5}$ in a periodic array of obstacles.
where $\nabla S$ is "frozen" locally at a point $\overline{\mathbf{x}}$ and the biasing function $\chi \geq 0$ is normalized so as to get the standard 2 D continuity equation:

$$
\int_{\mathbb{S}^{1}} \chi(\mathbf{v}) \frac{\mathrm{d} \mathbf{v}}{2 \pi}=1, \quad \partial_{t} \rho(t, \mathbf{x})+\operatorname{div} \mathbf{J}=0
$$

The analogue of the Laplace transform in (2.1) for steady-states $f(\mathbf{x}, \mathbf{v})$ reads,

$$
\begin{equation*}
f(\mathbf{x}, \mathbf{v})=\chi(\mathbf{v}) \int_{0}^{\infty} \exp (-r) \rho(\mathbf{x}-r \mathbf{v}) \mathrm{d} r=\chi(\mathbf{v}) \mathcal{L}_{r}\left(\tilde{\rho}_{\mathbf{x}, \mathbf{v}}\right)[p=1] \tag{7.2}
\end{equation*}
$$

from which follows a new Fredholm equation, now involving the biasing function $\chi$,

$$
\begin{equation*}
\rho(\mathbf{x})=\int_{0}^{\infty} \exp (-r)\left(\int_{\mathbb{S}^{1}} \chi(\mathbf{v}) \rho(\mathbf{x}-r \mathbf{v}) \frac{\mathrm{d} \mathbf{v}}{2 \pi}\right) \mathrm{d} r . \tag{7.3}
\end{equation*}
$$

To mimic some computations of [4], macroscopic steady-states should verify,

$$
\forall r \in \mathbb{R}^{+}, \quad \rho(\mathbf{x})=\int_{\mathbb{S}^{1}} \chi(\mathbf{v}) \rho(\mathbf{x}-r \mathbf{v}) \frac{\mathrm{d} \mathbf{v}}{2 \pi},
$$

which means that our "biasing function" $\chi$ should also be the "Poisson kernel" of a certain elliptic differential operator that $\rho(\mathbf{x})$ solves. Indeed, $\rho(\mathbf{x}-r \mathbf{v})$ is "boundary data" on $\mathbb{S}^{1}$, so $\rho(\mathbf{x})$ is the "solution value". Accordingly, from [3, eqn (2.24)],

$$
\rho(\mathbf{x})=\int_{0}^{2 \pi} \rho\left(\mathbf{x}+r e^{i \theta}\right) \frac{\exp (-\omega r \cos (\theta-\mu))}{\mathcal{I}_{0}(\omega r)} \frac{\mathrm{d} \theta}{2 \pi}
$$



Figure 6.4. Diffusive approximation (4.3) at $T=15, \varepsilon=10^{-5}$ with a Gaussian opacity.
so that, by changing $\theta \rightarrow \theta-\pi$, one gets (see also [6, 10, 20])

$$
\rho(\mathbf{x})=\int_{-\pi}^{\pi} \rho\left(\mathbf{x}-r e^{i \theta}\right) \frac{\exp (\omega r \cos (\theta-\mu))}{\mathcal{I}_{0}(\omega r)} \frac{\mathrm{d} \theta}{2 \pi}
$$

Pick, as the biasing function, $\left(\mathcal{I}_{0}\right.$, the modified Bessel function of index zero)

$$
\chi\left(\mathbf{v}=e^{i \theta}\right)=\frac{\exp (\omega r \cos (\theta-\mu))}{\mathcal{I}_{0}(\omega r)} \geq 0, \quad \int_{0}^{2 \pi} \frac{\exp (\omega r \cos \theta)}{\mathcal{I}_{0}(\omega r)} \frac{\mathrm{d} \theta}{2 \pi}=1
$$

the normalization being a consequence of the "integral representation of Bessel functions", see e.g. [3, eqn (3.1)], then such a kernel corresponds to drift-diffusion equation,

$$
\begin{equation*}
-\Delta \rho+\mathbf{a} \cdot \nabla \rho=0, \quad \text { in the disk of radius } r>0 \tag{7.4}
\end{equation*}
$$

where (see again $[3$, eqns $(2.1-3)$ and $(2.12)]$ ), for $\mu \in(0,2 \pi)$,

$$
0 \leq \omega:=\frac{\|\mathbf{a}\|}{2}, \quad \frac{\mathbf{a}}{2}=\omega(\cos \mu, \sin \mu) \in \mathbb{R}^{2}
$$

is the polar representation of the drift velocity $\mathbf{a} \in \mathbb{R}^{2}$ in (7.4. Accordingly, one can relate mesoscopic to macroscopic steady-states thanks to (7.2), and similar derivations as the ones performed in this article may lead to a "truly two-dimensional", asymptotic-preserving (in diffusive scaling) discretization of (7.1), like (3.5) and (4.3).

## Appendix A. $S$-matrix for Goldstein-Taylor model in 1D.

It might be interesting to recall some properties of "two-stream" one-dimensional (position-dependent) radiative transfer, already studied in [14], [11, §8.2] and [7, 9],

$$
\partial_{t} f^{ \pm} \pm \partial_{x} f^{ \pm}=\sigma(x)\left(\rho / 2-f^{ \pm}\right), \quad \rho=f^{+}+f^{-}
$$

Macroscopic (diffusive) stationary regimes in 1D reduce to $\rho^{\prime \prime}(x)=0$, i.e. constant or linear functions, and yield Case's polynomial solutions, 1 and $x-v$. Accordingly, for $R=\Delta x / 2$ and $f(x, v)=\alpha+\beta(x-v)$,

$$
M=\left(\begin{array}{cc}
1 & -(1+\sigma R) \\
1 & (1+\sigma R)
\end{array}\right), \quad \tilde{M}=\left(\begin{array}{cc}
1 & -(1-\sigma R) \\
1 & (1-\sigma R)
\end{array}\right)
$$

so that,

$$
|M|=2(1+\sigma R), \quad M^{-1}=\frac{1}{2}\left(\begin{array}{cc}
1 & 1 \\
-\frac{1}{1+\sigma R} & \frac{1}{1+\sigma R}
\end{array}\right)
$$

meaning that $\alpha$ is the average of incoming states, and

$$
S(\sigma)=\tilde{M} M^{-1}=\frac{1}{1+\sigma R}\left(\begin{array}{cc}
1 & \sigma R \\
\sigma R & 1
\end{array}\right)
$$

Such a $S$-matrix is "doubly-stochastic" because both its rows and columns add to unity and all its entries are positive when $\sigma R \geq 0$. Asymptotic limits are

$$
S(\sigma) \rightarrow\left(\begin{array}{ll}
1 & 0 \\
0 & 1
\end{array}\right) \text { if } \sigma \rightarrow 0, \quad S(\sigma) \rightarrow\left(\begin{array}{ll}
0 & 1 \\
1 & 0
\end{array}\right) \text { if } \sigma \rightarrow+\infty
$$

The resulting well-balanced 1D time-marching scheme reads,

$$
\binom{f_{j}^{+, n+1}}{f_{j-1}^{-, n+1}}=\left(1-\frac{\Delta t}{2 R}\right)\binom{f_{j}^{+, n}}{f_{j-1}^{-, n}}+\frac{\Delta t}{2 R} S\left(\sigma_{j-\frac{1}{2}}\right)\binom{f_{j-1}^{+, n}}{f_{j}^{-, n}}
$$

In parabolic scaling, the following decomposition holds,

$$
S(\sigma)=\left(\begin{array}{ll}
0 & 1 \\
1 & 0
\end{array}\right)+\frac{\varepsilon}{\varepsilon+\sigma R}\left(\begin{array}{cc}
1 & -1 \\
-1 & 1
\end{array}\right)
$$

and brings back the well-known IMEX scheme originally written in 14],

$$
\begin{gathered}
\binom{f_{j}^{+, n+1}}{f_{j-1}^{-, n+1}}+\frac{\Delta t}{2 \varepsilon R}\left(\begin{array}{cc}
0 & 1 \\
1 & 0
\end{array}\right)\binom{f_{j}^{+, n+1}}{f_{j-1}^{-, n+1}} \\
=\binom{f_{j}^{+, n}}{f_{j-1}^{-,-n}}+\frac{\Delta t}{2 R(\varepsilon+\sigma R)}\left(\begin{array}{cc}
1 & -1 \\
-1 & 1
\end{array}\right)\binom{f_{j-1}^{+, n}}{f_{j}^{-, n}} \\
\text { REFERENCES }
\end{gathered}
$$

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