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# A TRULY TWO-DIMENSIONAL, ASYMPTOTIC-PRESERVING SCHEME FOR A DISCRETE MODEL OF RADIATIVE TRANSFER

LAURENT GOSSE\* AND NICOLAS VAUCHELET<sup>†</sup>

**Abstract.** For a four-stream approximation of the kinetic model of radiative transfer wih isotropic scattering, a numerical scheme endowed with both truly-2D well-balanced and diffusive asymptotic-preserving properties is derived, in the same spirit as what was done in [14] in the 1D case. Building on former results of Birkhoff and Abu-Shumays, [4], it is possible to express 2D kinetic steady-states by means of harmonic polynomials, and this allows to build a scattering S-matrix yielding a time-marching scheme. Such a S-matrix can be decomposed, as in [15], so as to deduce another scheme, well-suited for a diffusive approximation of the kinetic model, for which rigorous convergence can be proved. Challenging benchmarks are also displayed on coarse grids.

Key words. Diffusive scaling; Four-stream approximation; Grey radiative transfer; S-matrix.

AMS subject classifications. 31A05, 65M06, 76R50, 82B40, 85A25.

#### 1. Introduction and preliminaries.

1.1. Kinetic modeling in 2D. We are interested in a "truly two-dimensional" numerical simulation of the simple kinetic model, where  $\mathbf{x} = (x, y)$  and  $\mathbf{v} = (\xi, \eta)$ ,

$$\partial_t f(t, \mathbf{x}, \mathbf{v}) + \mathbf{v} \cdot \nabla_{\mathbf{x}} f = \sigma(\mathbf{x}) \left( \int_{\mathbb{S}^1} f(t, \mathbf{x}, \mathbf{v}') \frac{\mathrm{d} \mathbf{v}'}{2\pi} - f \right), \qquad |\mathbf{v}| = 1.$$

in particular, of its "four-stream approximation", evoked in e.g. [17, §5] or [9],

$$\partial_t f^{\pm} \pm \partial_x f^{\pm} = \sigma(x, y)(\rho/4 - f^{\pm}), \qquad \partial_t g^{\pm} \pm \partial_y g^{\pm} = \sigma(x, y)(\rho/4 - g^{\pm}),$$
 (1.1)

where the "opacity"  $\sigma(x,y) \ge 0$  and the macroscopic density simplifies into,

$$\forall t, \mathbf{x} \in \mathbb{R}^+ \times \mathbb{R}^2, \qquad \rho(t, \mathbf{x}) = f^+(t, \mathbf{x}) + f^-(t, \mathbf{x}) + g^+(t, \mathbf{x}) + g^-(t, \mathbf{x}).$$

In order to take full advantage of a 9-points, so-called *Moore*, stencil, microscopic velocities are rotated so as to be aligned with the diagonals of a Cartesian grid,

$$\mathbf{v} = \left(\frac{\pm 1}{\sqrt{2}}(1,1), \frac{\pm 1}{\sqrt{2}}(-1,1)\right),\tag{1.2}$$

like, for instance, in [5, §2.1]. This choice leads to the following 2D system,

$$\begin{cases}
\partial_t f^{\pm} \pm \frac{1}{\sqrt{2}} \left( \partial_x f^{\pm} + \partial_y g^{\pm} \right) = \sigma(x, y) \left( \frac{\rho}{4} - f^{\pm} \right), \\
\partial_t g^{\pm} \mp \frac{1}{\sqrt{2}} \left( \partial_x f^{\pm} - \partial_y g^{\pm} \right) = \sigma(x, y) \left( \frac{\rho}{4} - g^{\pm} \right),
\end{cases} (1.3)$$

for which we propose a numerical scheme endowed with similar properties as the one in [14], in a two-dimensional context, without domain decomposition, like [2, 16, 19].

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1.2. Diffusive approximation to (|1.1). To study diffusive limits of (1.1), one rescales  $(t, \mathbf{x}) \to (\varepsilon^2 t, \varepsilon \mathbf{x})$  in order to produce,

$$\varepsilon \partial_t f^{\pm} \pm \partial_x f^{\pm} = \frac{\sigma(\mathbf{x})}{\varepsilon} (\frac{\rho}{4} - f^{\pm}), \qquad \varepsilon \partial_t g^{\pm} \pm \partial_y g^{\pm} = \frac{\sigma(\mathbf{x})}{\varepsilon} (\frac{\rho}{4} - g^{\pm}),$$

and introduces macroscopic quantities, mass and flux,

$$\rho = f^+ + f^- + g^+ + g^-, \quad \mathbf{J} = \frac{1}{\varepsilon} \begin{pmatrix} f^+ - f^- \\ g^+ - g^- \end{pmatrix} \in \mathbb{R}^2.$$

By summing the four balance laws, the continuity equation emerges,

$$\partial_t \rho + \operatorname{div} \mathbf{J} = 0.$$

However, as noted in [17, page 504], the equation on **J** isn't closed,

$$\varepsilon^{2} \partial_{t} \mathbf{J} + \nabla \begin{pmatrix} f^{+} + f^{-} \\ g^{+} + g^{-} \end{pmatrix} = -\sigma(\mathbf{x}) \mathbf{J}, \tag{1.4}$$

so that, formally, the asymptotic behavior appears to be given by,

$$\partial_t \rho = \partial_x \left( \frac{\partial_x (f^+ + f^-)}{\sigma(\mathbf{x})} \right) + \partial_y \left( \frac{\partial_y (g^+ + g^-)}{\sigma(\mathbf{x})} \right).$$

However, by subtracting the first (second) and the third (fourth) balance laws,

$$\varepsilon \partial_t (f^{\pm} - g^{\pm}) \pm (\partial_x f^{\pm} - \partial_y g^{\pm}) = -\frac{\sigma}{\varepsilon} (f^{\pm} - g^{\pm}),$$

we get that  $|f^{\pm} - g^{\pm}| = O(\varepsilon)$ , so former calculations can be improved into,

$$\varepsilon^{2} \partial_{t} \mathbf{J} + \nabla(\frac{\rho}{2}) = -\sigma \mathbf{J} - \frac{1}{2} \nabla \begin{pmatrix} (f^{+} - g^{+}) + (f^{-} - g^{-}) \\ (g^{+} - f^{+}) + (g^{-} - f^{-}) \end{pmatrix} = -\sigma \mathbf{J} - O(\varepsilon),$$

which leads to the expected diffusion equation (see also (4.8),

$$\partial_t \rho(t, \mathbf{x}) = \text{div } \left( \frac{\nabla \rho}{2\sigma(\mathbf{x})} \right), \quad \text{or } \partial_t \rho = \frac{\Delta \rho}{2\sigma} \text{ if } \sigma \text{ is a constant.}$$
 (1.5)

These formal arguments were made fully rigorous in [17] when  $\sigma$  is a constant.

1.3. Plan of the paper. This text follows a similar roadmap as the original article [14], with the supplementary difficulty that every derivation must now be made on two-dimensional kinetic models. To proceed, we recall in §2 the pioneering results of [4], thanks to which one can deduce, by means of Laplace transforms, kinetic steady-states from harmonic functions. Following ideas of [12, 13], a S-matrix is derived, in §3, from the data of such polynomial kinetic steady-states, yielding a time-marching scheme (3.5), which is able to preserve non-trivial 2D equilibria (see Theorem 3.2). Moreover, the S-matrix being doubly-stochastic, it is straightforward to show that (3.5) preserves positivity as well as  $L^1/L^{\infty}$  bounds, like its continuous counterpart. Drawing on our paper [15], after a parabolic rescaling of variables, the S-matrix decomposes nicely so as to yield an IMEX scheme (4.1) which relaxes, as  $\varepsilon \to 0$ , towards (4.8), which is a consistent discretization of (1.5). Rigorous proofs are produced in §5, in particular in Theorem 5.6, where we can see that the multidimensional feature (1.4), raised in [17], has consequences at the numerical level. These bounds are visualized in §6 where several challenging benchmarks for both (3.5) and (4.3) are tested on a coarse  $32 \times 32$  Cartesian grid. Finally, §7 paves the way for tackling more complex kinetic models, like (7.1), and some early results of [14] are rephrased in the context of S-matrices in Appendix A.

#### 2. Harmonic stationary distributions.

**2.1.** Harmonic functions and isotropic scattering. In [4], the authors present a tricky procedure which allows to derive an infinity of (explicit) exact steady-states of the following multi-dimensional kinetic model,

$$\partial_t f(t, \mathbf{x}, \mathbf{v}) + \mathbf{v} \cdot \nabla_{\mathbf{x}} f = \int_{\mathbb{S}^1} f(t, \mathbf{x}, \mathbf{v}') \frac{\mathrm{d} \mathbf{v}'}{2\pi} - f, \quad \mathbf{x} = (x, y), \quad \mathbf{v} = (\xi, \eta).$$

In virtue of the method of characteristics, long-time asymptotics  $t \to +\infty$  satisfy,

$$f(\mathbf{x}, \mathbf{v}) = \int_0^\infty \exp(-r) \, \rho(\mathbf{x} - r\mathbf{v}) \, dr, \qquad \rho(\mathbf{x}) = \int_{\mathbb{S}^1} f(\mathbf{x}, \mathbf{v}) \frac{d\mathbf{v}}{2\pi}, \tag{2.1}$$

which is the Laplace transform of the (oriented) one-dimensional trace of  $\rho$ , [18],

$$\tilde{\rho}_{\mathbf{x},\mathbf{v}}: \mathbb{R}^+ \ni r \mapsto \rho(\mathbf{x} - r\mathbf{v}), \qquad f(\mathbf{x}, \mathbf{v}) = \mathcal{L}_r(\tilde{\rho}_{\mathbf{x},\mathbf{v}})[p=1].$$
 (2.2)

A Fredholm equation (of the second kind) follows by integrating again in  $\mathbf{v} \in \mathbb{S}^1$ ,

$$\forall \mathbf{x} \in \mathbb{R}^2, \qquad \rho(\mathbf{x}) = \int_0^\infty \exp(-r) \left( \int_{\mathbb{S}^1} \rho(\mathbf{x} - r\mathbf{v}) \, \frac{\mathrm{d}\mathbf{v}}{2\pi} \right) \mathrm{d}r. \tag{2.3}$$

At this point, the authors of [4] claim that, as the long-time behavior of the kinetic model is pure diffusion and  $\rho$  is a macroscopic quantity, harmonic functions may induce mesoscopic steady-states by means of (2.1). Hence, if  $\rho$  is a steady-state of diffusion,  $\Delta \rho = 0$ , and its mean-value property [6, 10, 20] yields,

$$\forall r \in \mathbb{R}^+, \qquad \rho(\mathbf{x}) = \int_{\mathbb{S}^1} \rho(\mathbf{x} - r\mathbf{v}) \frac{\mathrm{d}\mathbf{v}}{2\pi},$$

so that, by multiplying by  $\exp(-r)$  and integrating in  $r \in \mathbb{R}^+$ ,

$$\int_0^\infty \rho(\mathbf{x}) \exp(-r) dr = \rho(\mathbf{x}) = \int_0^\infty \exp(-r) \left( \int_{\mathbb{S}^1} \rho(\mathbf{x} - r\mathbf{v}) \frac{d\mathbf{v}}{2\pi} \right) dr,$$

holds for any  $\mathbf{x} \in \mathbb{R}^2$ , so that (2.3) is satisfied, and a class of stationary kinetic densities  $f(\mathbf{x}, \mathbf{v})$  can be deduced from (2.1). For instance, harmonic polynomials furnish an infinity of 2D mesoscopic steady-states, which generalize the only two 1, x - v (see e.g. [11, Chap. 9]), which follow from  $\rho''(x) = 0$  in one dimension.

**2.2. Kinetic steady-states and harmonic polynomials.** A major result in [4] is that kinetic stationary solutions  $f(\mathbf{x}, \mathbf{v})$  can be deduced from macroscopic (i.e. diffusive, or harmonic) ones  $\rho(\mathbf{x})$ , by means of a Laplace transform of  $r \mapsto \rho(\mathbf{x} - r \mathbf{v})$ ,

$$f(\mathbf{x}, \mathbf{v}) = \int_0^\infty \rho(\mathbf{x} - r \mathbf{v}) \exp(-r) dr, \qquad \Delta \rho = 0,$$
 (2.4)

as soon as certain integrability conditions are met (see [4, Theorem A]). Accordingly, in the special case where  $\mathbf{x} = x \in \mathbb{R}$  (one space dimension), harmonic solutions of  $\mathrm{d}^2 \rho / \mathrm{d} x^2 = 0$  reduce to  $\{1, x\}$  and it comes that, for  $v \in \mathbb{R}$ ,

$$f(x,v) = \int_0^\infty \exp(-r) dr = 1, \qquad f(x,v) = \int_0^\infty (x - rv) \exp(-r) dr = x - v,$$

which are well-known "separated variables Case's solutions", see [11, eqn (9.8)]. In more space dimensions, harmonic functions are abundant (any holomorphic function of  $z = x + iy \in \mathbb{C}$  furnishes two harmonic ones: its real and imaginary parts), so that (2.4) yields an infinite set of polynomial solutions, being

see [4, eqn (2.6)]. The first ones correspond to "dimensional splitting", whereas last two ones are truly 2D and "conjugate" in a certain sense (as seen below). These stationary distributions  $f(\mathbf{x}, \mathbf{v})$  can be easily retrieved from (2.4) by taking advantage of the expression of harmonic functions in polar coordinates,

$$\rho(x = r\cos\theta, y = r\sin\theta) = a_0 + \sum_{n \in \mathbb{N}_*} (a_n\cos n\theta + b_n\sin n\theta)r^n, \tag{2.6}$$

in which the first basis components are

$$\{1, x = r\cos\theta, y = r\sin\theta, x^2 - y^2 = r^2\cos 2\theta, xy = r^2\sin 2\theta, ...\}$$

These "harmonic steady-states"  $f(\mathbf{x}, \mathbf{v})$  follow from Euler's Gamma function,

$$\Gamma(x) = \int_0^\infty \exp(-t) t^{x-1} dt, \qquad \Gamma(n) = (n-1)! \text{ if } n \in \mathbb{N},$$

because, according to (2.1), the polynomial solutions given in (2.6) rewrite,

$$f(\mathbf{x}, \mathbf{v}) = \left\{ \Gamma(1), \ \Gamma(1)\mathbf{x} - \Gamma(2)\mathbf{v}, \ \Gamma(1)xy - \Gamma(2)(x\eta + y\xi) + \Gamma(3)\xi\eta, \ \dots \right\}.$$

- **3.** A "truly 2D" approximation of  $f(t, \mathbf{x}, \mathbf{v})$ . Working on a uniform Cartesian grid for which  $\Delta x = \Delta y$ , we mimic the notation already used in [3], see Fig. 3.1.
- **3.1. Derivation of the** S-matrix. In order to simulate (1.3) on a 9-points stencil, we only need the first four stationary solutions: the choice between the two "truly 2D" quadratic ones depends on the velocity vectors. A simple case, where one of the conjugate solutions is always null, consists in working in diagonal coordinates,

$$\mathbf{x} = (\mp R, 0) \text{ and } (0, \mp R), \quad \mathbf{v} = (\pm 1, 0) \text{ and } (0, \pm 1),$$

where  $R=\Delta x/\sqrt{2}$  is the radius of the disc centered in  $x_{i-\frac{1}{2}},y_{j+\frac{1}{2}}$ . The S-matrix acts on four incoming states and produces four outgoing ones, so

$$\begin{pmatrix} f_*^+ \\ f_-^- \\ g_*^+ \\ g_*^- \end{pmatrix} = S_{i-\frac{1}{2},j+\frac{1}{2}} \begin{pmatrix} f_{i-1,j}^+ \\ f_{i,j+1}^- \\ g_{i,j}^+ \\ g_{i-1,j+1}^- \end{pmatrix}.$$

By linearity, and following ideas from [11, Chap. 9], a  $C^{\infty}$  stationary solution reads,

$$f(\mathbf{x}, \mathbf{v}) = \alpha + \beta(x - \xi) + \gamma(y - \eta) + \nu \left( \frac{x^2 - y^2}{2} - (x\xi - y\eta) + (\xi^2 - \eta^2) \right), \quad (3.1)$$

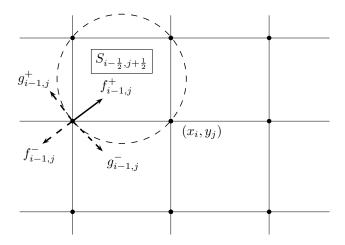


FIGURE 3.1. The S-matrix  $S_{i-\frac{1}{2},j+\frac{1}{2}}$  and an incoming state,  $f_{i-1,j}^+$ .

so that aforementioned "incoming" and "outgoing" states are, respectively,

$$\begin{cases} f_{i-1,j}^+ = f(\mathbf{x} = (-R,0), \mathbf{v} = (1,0)), & f_{i,j+1}^- = f(\mathbf{x} = (R,0), \mathbf{v} = (-1,0)), \\ g_{i,j}^+ = f(\mathbf{x} = (0,-R), \mathbf{v} = (0,1)), & g_{i-1,j+1}^- = f(\mathbf{x} = (0,R), \mathbf{v} = (0,-1)), \end{cases}$$

which is a linear system for  $(\alpha, \beta, \gamma, \nu)$ , and

$$\left\{ \begin{array}{l} f_*^+ = f(\mathbf{x} = (R,0), \mathbf{v} = (1,0)), \quad f_*^- = f(\mathbf{x} = (-R,0), \mathbf{v} = (-1,0)), \\ g_*^+ = f(f\mathbf{x} = (0,R), \mathbf{v} = (0,1)), \quad g_*^- = f(\mathbf{x} = (0,-R), \mathbf{v} = (0,-1)), \end{array} \right.$$

involving again the "spectral coefficients"  $(\alpha, \beta, \gamma, \nu) \in \mathbb{R}^4$  which values are fixed by the four incoming states. Accordingly, the S-matrix decomposes again like,

$$\forall (i,j) \in \mathbb{Z}^2, \qquad S_{i-\frac{1}{2},j+\frac{1}{2}} = S(\sigma_{i-\frac{1}{2},j+\frac{1}{2}}), \qquad S(\sigma) = \tilde{M} M^{-1},$$
 (3.2)

where M has mutually orthogonal columns,

$$M = \begin{pmatrix} 1 & -(1+\sigma R) & 0 & 1+(1+\sigma R)^2 \\ 1 & (1+\sigma R) & 0 & 1+(1+\sigma R)^2 \\ 1 & 0 & -(1+\sigma R) & -(1+(1+\sigma R)^2) \\ 1 & 0 & (1+\sigma R) & -(1+(1+\sigma R)^2) \end{pmatrix},$$
(3.3)

along with its companion  $\tilde{M}$ .

$$\tilde{M} = \begin{pmatrix} 1 & -(1 - \sigma R) & 0 & 1 + (1 - \sigma R)^2 \\ 1 & 1 - \sigma R & 0 & 1 + (1 - \sigma R)^2 \\ 1 & 0 & -(1 - \sigma R) & -(1 + (1 - \sigma R)^2) \\ 1 & 0 & (1 - \sigma R) & -(1 + (1 - \sigma R)^2) \end{pmatrix},$$

in which a rescaling of  $\mathbf{x}$  was made in order to cope with variable opacity  $\sigma(\mathbf{x})$ . One recognizes the matrices of 1D Goldstein-Taylor model, see §A and [11, Remark 9.3],

$$\left(\begin{array}{cc} 1 & -(1+\sigma R) \\ 1 & (1+\sigma R) \end{array}\right), \qquad \left(\begin{array}{cc} 1 & -(1-\sigma R) \\ 1 & (1-\sigma R) \end{array}\right),$$

but now, 1D solutions  $\sigma \mathbf{x} - \mathbf{v}$  are coupled by the constant and quadratic ones.

**3.2. Resulting 2D time-marching scheme.** For  $\sigma R \geq 0$ , the determinant |M| is positive, so M is invertible and its inverse reads:

$$|M| = 8(1 + \sigma R)^2 \left( 1 + (1 + \sigma R)^2 \right), \quad M^{-1} = \begin{pmatrix} \frac{1}{4} & \frac{1}{4} & \frac{1}{4} & \frac{1}{4} \\ -A & A & 0 & 0 \\ 0 & 0 & -A & A \\ B & B & -B & -B \end{pmatrix},$$

so that  $\alpha$  is always the average of the four incoming states, and where

$$A = \frac{1}{2(1+\sigma R)},$$
  $B = \frac{1}{4(1+(1+\sigma R)^2)}.$ 

Accordingly, the S-matrix is given by the product,

$$S(\sigma) = \tilde{M} M^{-1}$$

$$= \begin{pmatrix} \frac{1}{4} + C + D & \frac{1}{4} - C + D & \frac{1}{4} - D & \frac{1}{4} - D \\ \frac{1}{4} - C + D & \frac{1}{4} + C + D & \frac{1}{4} - D & \frac{1}{4} - D \\ \frac{1}{4} - D & \frac{1}{4} - D & \frac{1}{4} + C + D & \frac{1}{4} - C + D \\ \frac{1}{4} - D & \frac{1}{4} - D & \frac{1}{4} - C + D & \frac{1}{4} + C + D \end{pmatrix},$$
(3.4)

which both lines and columns clearly add to unity, because

$$C = \frac{1 - \sigma R}{2(1 + \sigma R)} = \frac{1}{2} - \frac{\sigma R}{1 + \sigma R}, \quad D = \frac{(1 - \sigma R)^2 + 1}{4((1 + \sigma R)^2 + 1)} = \frac{1}{4} - \frac{\sigma R}{1 + (1 + \sigma R)^2}.$$

The S-matrix rewrites as a  $O(\sigma R)$ -perturbation of the identity of  $\mathbb{R}^4$ ,

so that, similarly to e.g. [15, Prop. 3.2],

$$S(\sigma) \to \mathrm{Id}_{\mathbb{R}^4} \text{ if } \sigma \to 0, \qquad S(\sigma) \to S^0 = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{pmatrix} \text{ if } \sigma \to +\infty.$$

Having at hand the  $4 \times 4$  matrix (3.2) allows to deduce a time-marching scheme for the 2D system (1.3) on a uniform Cartesian grid (see Fig. 3.1,  $\Delta x = \Delta y$ ),

$$\begin{pmatrix} f_{i,j+1}^{+,n+1} \\ f_{i-1,j}^{-,n+1} \\ g_{i-1}^{+,n+1} \\ g_{i,j}^{+,n+1} \end{pmatrix} = \left(1 - \frac{\Delta t}{2R}\right) \begin{pmatrix} f_{i,j+1}^{+,n} \\ f_{i,j+1}^{-,n} \\ f_{i-1,j}^{+,n} \\ g_{i-1,j+1}^{+,n} \\ g_{i,j}^{-,n} \end{pmatrix} + \frac{\Delta t}{2R} S(\sigma_{i-\frac{1}{2},j+\frac{1}{2}}) \begin{pmatrix} f_{i-1,j}^{+,n} \\ f_{i-1,j}^{-,n} \\ f_{i,j+1}^{-,n} \\ g_{i,j}^{+,n} \\ g_{i,j}^{-,n} \\ g_{i-1,j+1}^{-,n} \end{pmatrix}. (3.5)$$

LEMMA 3.1. Under the CFL restriction  $\Delta t \leq 2R$ , the scheme (3.5) is consistent with (1.3) and preserves positivity. Moreover, it is conservative and  $L^{\infty}$ -bounded.

*Proof.* Under the aforementioned CFL restriction, (3.5) is a convex combination (as advocated in [12, eqn (2.2)]), hence it preserves positivity because all the entries of  $S(\sigma)$  are nonnegative. Besides, doubly-stochastic matrices are such that,

$$\forall \vec{v} \in \mathbb{R}^4, \qquad \|S(\sigma)\vec{v}\|_{\infty} \le \|\vec{v}\|_{\infty}, \ \|S(\sigma)\vec{v}\|_1 \le \|\vec{v}\|_1,$$

which implies that (3.5) is bounded in  $L^1$  and  $L^{\infty}$ . Consistency is shown for  $0 \le \sigma R \ll 1$  (fine grid); at first order, the expression of the S-matrix reduces to,

$$\frac{1}{1 + (1 + \sigma R)^2} \simeq \frac{1}{2(1 + \sigma R)}, \quad S(\sigma) = \operatorname{Id}_{\mathbb{R}^4} + \frac{\sigma R}{2(1 + \sigma R)} \begin{pmatrix} -3 & 1 & 1 & 1\\ 1 & -3 & 1 & 1\\ 1 & 1 & -3 & 1\\ 1 & 1 & 1 & -3 \end{pmatrix},$$

and inserting this expression in (3.5) yields a consistent approximation of (1.3).  $\square$ 

The scheme (3.5) is able to preserve some non-trivial 2D equilibria, see e.g. [1].

THEOREM 3.2 (2D well-balanced). Let  $\sigma(\mathbf{x}) \equiv \bar{\sigma} > 0$  a constant, then any linear combination (3.1) induces a numerical steady-state for the scheme (3.5), given by

$$f^{\pm}\left(\frac{x-y}{\sqrt{2}}, \frac{x+y}{\sqrt{2}}\right) = f(\bar{\sigma}\mathbf{x}; (\pm 1, 0)), \quad g^{\pm}\left(\frac{x-y}{\sqrt{2}}, \frac{x+y}{\sqrt{2}}\right) = f(\bar{\sigma}\mathbf{x}; (0, \pm 1)).$$

*Proof.* Pick  $(\alpha, \beta, \gamma, \nu) \in \mathbb{R}^4$  in (3.1) and consider a steady-state  $f(\bar{\sigma}\mathbf{x}, \mathbf{v})$ : since |M| > 0, its restriction to  $\mathbf{v} = \{(\pm 1, 0), (0, \pm 1)\}$  on a uniform Cartesian grid satisfies,

$$\begin{pmatrix} \alpha \\ \beta \\ \gamma \\ \nu \end{pmatrix} = M^{-1} \begin{pmatrix} f_{i-1,j}^{+,n} \\ f_{i,j+1}^{-,n} \\ f_{i,j}^{+,n} \\ g_{i,j}^{+,n} \\ g_{i-1,j+1}^{-,n} \end{pmatrix} \quad \Rightarrow \quad S(\bar{\sigma}) \begin{pmatrix} f_{i-1,j}^{+,n} \\ f_{i-1,j}^{-,n} \\ f_{i,j}^{+,n} \\ g_{i,j}^{+,n} \\ g_{i-1,j+1}^{+,n} \end{pmatrix} = \begin{pmatrix} f_{i,j+1}^{+,n} \\ f_{i-1,j}^{-,n} \\ f_{i-1,j}^{-,n} \\ g_{i,j}^{+,n} \end{pmatrix},$$

so they are invariant by the time-marching scheme (3.5). By a  $-\frac{\pi}{4}$  rotation we pass from diagonal coordinates with  $\mathbf{v} = \{(\pm 1, 0), (0, \pm 1)\}$  to axial ones with (1.2).  $\square$ 

**4. Diffusive behavior of the** S-matrix. In order to study asymptotic limits so as to check a possible consistency with the estimates stated in [17, Theorem 5.1], we rescale  $\sigma(\mathbf{x}) \to \sigma(\mathbf{x})/\varepsilon$ ,  $\varepsilon \ll 1$ . Accordingly, the S-matrix decomposes into  $S^0 + \varepsilon S^{1,\varepsilon}$ , like in [15, §1.2], where, as  $\varepsilon \to 0$ , Following again [15], an IMEX scheme may read

$$\begin{pmatrix}
f_{i,j+1}^{+,n+1} \\
f_{i-1,j}^{-,n+1} \\
g_{i-1,j+1}^{+,n+1} \\
g_{i,j}^{-,n+1}
\end{pmatrix} + \frac{\Delta t}{2\varepsilon R} \left\{ \begin{pmatrix}
f_{i,j+1}^{+,n+1} \\
f_{i-1,j}^{-,n+1} \\
g_{i,n+1}^{-,n+1} \\
g_{i,j}^{-,n+1}
\end{pmatrix} - S^{0} \begin{pmatrix}
f_{i-1,j}^{+,n+1} \\
f_{i-1,j}^{-,n+1} \\
f_{i,j+1}^{-,n+1} \\
g_{i,j}^{-,n+1}
\end{pmatrix} \right\}$$

$$= \begin{pmatrix}
f_{i,j+1}^{+,n} \\
f_{i-1,j}^{-,n} \\
f_{i-1,j}^{-,n} \\
g_{i-1,j+1}^{+,n}
\end{pmatrix} + \frac{\Delta t}{2R} S^{1,\varepsilon} \begin{pmatrix}
f_{i-1,j}^{+,n} \\
f_{i,j+1}^{-,n} \\
g_{i,j}^{-,n} \\
g_{i,j}^{-,n}
\end{pmatrix} ,$$

$$(4.1)$$

and we expect the (implicit, but not costly) left-hand side to yield "Maxwellian estimates" of the type [17, eqn (5.15)], and the (explicit) right-hand side to produce accurate and consistent diffusive numerical fluxes.

**4.1.** Decomposition of the S-matrix. By defining the positive coefficients,

$$\alpha_{i-\frac{1}{2},j+\frac{1}{2}}^{\varepsilon} = \frac{1}{\varepsilon + \sigma_{i-\frac{1}{2},j+\frac{1}{2}}R}; \qquad \beta_{i-\frac{1}{2},j+\frac{1}{2}}^{\varepsilon} = \frac{\sigma_{i-\frac{1}{2},j+\frac{1}{2}}R}{\varepsilon^2 + (\varepsilon + \sigma_{i-\frac{1}{2},j+\frac{1}{2}}R)^2}, \tag{4.2}$$

the aforementioned decomposition reads, at each location  $i - \frac{1}{2}, j + \frac{1}{2}$ ,

$$S^{\varepsilon} = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{pmatrix} + \varepsilon \begin{pmatrix} \alpha - \beta & -(\alpha + \beta) & \beta & \beta \\ -(\alpha + \beta) & \alpha - \beta & \beta & \beta \\ \beta & \beta & \alpha - \beta & -(\alpha + \beta) \\ \beta & \beta & -(\alpha + \beta) & \alpha - \beta \end{pmatrix},$$

hence, the IMEX scheme (4.1) rewrites as,

$$\begin{split} f_{i,j+1}^{+,n+1} + \frac{\Delta t}{2\varepsilon R} \Big( f_{i,j+1}^{+,n+1} - f_{i,j+1}^{-,n+1} \Big) &= f_{i,j+1}^{+,n} + \\ \frac{\Delta t}{2R} \left[ \alpha_{i-\frac{1}{2},j+\frac{1}{2}}^{\varepsilon} \Big( f_{i-1,j}^{+,n} - f_{i,j+1}^{-,n} \Big) + \beta_{i-\frac{1}{2},j+\frac{1}{2}}^{\varepsilon} \Big( - f_{i-1,j}^{+,n} - f_{i,j+1}^{-,n} + g_{i,j}^{+,n} + g_{i-1,j+1}^{-,n} \Big) \right] \\ f_{i-1,j}^{-,n+1} + \frac{\Delta t}{2\varepsilon R} \Big( f_{i-1,j}^{-,n+1} - f_{i-1,j}^{+,n+1} \Big) &= f_{i-1,j}^{-,n} + \\ \frac{\Delta t}{2R} \left[ \alpha_{i-\frac{1}{2},j+\frac{1}{2}}^{\varepsilon} \Big( f_{i,j+1}^{-,n} - f_{i-1,j}^{+,n} \Big) + \beta_{i-\frac{1}{2},j+\frac{1}{2}}^{\varepsilon} \Big( - f_{i-1,j}^{+,n} - f_{i,j+1}^{-,n} + g_{i,j}^{+,n} + g_{i-1,j+1}^{-,n} \Big) \right] \\ g_{i-1,j+1}^{+,n+1} + \frac{\Delta t}{2\varepsilon R} \Big( g_{i-1,j+1}^{+,n+1} - g_{i-1,j+1}^{-,n+1} \Big) &= g_{i-1,j+1}^{+,n} + \\ \frac{\Delta t}{2R} \left[ \alpha_{i-\frac{1}{2},j+\frac{1}{2}}^{\varepsilon} \Big( g_{i,j}^{+,n} - g_{i-1,j+1}^{-,n} \Big) + \beta_{i-\frac{1}{2},j+\frac{1}{2}}^{\varepsilon} \Big( f_{i-1,j}^{+,n} + f_{i,j+1}^{-,n} - g_{i,j}^{+,n} - g_{i-1,j+1}^{-,n} \Big) \right] \\ g_{i,j}^{-,n+1} + \frac{\Delta t}{2\varepsilon R} \Big( g_{i,j}^{-,n+1} - g_{i,j}^{+,n+1} \Big) &= g_{i,j}^{-,n} + \\ \frac{\Delta t}{2R} \left[ \alpha_{i-\frac{1}{2},j+\frac{1}{2}}^{\varepsilon} \Big( g_{i,j}^{-,n} - g_{i,j}^{+,n+1} \Big) + \beta_{i-\frac{1}{2},j+\frac{1}{2}}^{\varepsilon} \Big( f_{i-1,j}^{+,n} + f_{i,j+1}^{-,n} - g_{i,j}^{+,n} - g_{i-1,j+1}^{-,n} \Big) \right]. \end{split}$$

An index-shift yields:

$$\begin{pmatrix}
1 + \frac{\Delta t}{2\varepsilon R} & -\frac{\Delta t}{2\varepsilon R} & 0 & 0 \\
-\frac{\Delta t}{2\varepsilon R} & 1 + \frac{\Delta t}{2\varepsilon R} & 0 & 0 \\
0 & 0 & 1 + \frac{\Delta t}{2\varepsilon R} & -\frac{\Delta t}{2\varepsilon R} \\
0 & 0 & -\frac{\Delta t}{2\varepsilon R} & 1 + \frac{\Delta t}{2\varepsilon R}
\end{pmatrix}
\begin{pmatrix}
f_{i,j}^{+,n+1} \\
f_{i,j}^{-,n+1} \\
g_{i,j}^{+,n+1} \\
g_{i,j}^{-,n+1}
\end{pmatrix} = \begin{pmatrix}
f_{i,j}^{+,n} \\
f_{i,j}^{-,n} \\
f_{i,j}^{-,n} \\
g_{i,j}^{-,n}
\end{pmatrix} + (4.3)$$

$$\frac{\Delta t}{2R} \begin{pmatrix}
\alpha_{i-\frac{1}{2},j-\frac{1}{2}}^{\varepsilon} (f_{i-1,j-1}^{+,n} - f_{i,j}^{-,n}) - \beta_{i-\frac{1}{2},j-\frac{1}{2}}^{\varepsilon} (f_{i-1,j-1}^{+,n} + f_{i,j}^{-,n} - g_{i,j-1}^{+,n} - g_{i-1,j}^{-,n}) \\
\alpha_{i+\frac{1}{2},j+\frac{1}{2}}^{\varepsilon} (f_{i+1,j+1}^{+,n} - f_{i,j}^{+,n}) - \beta_{i+\frac{1}{2},j+\frac{1}{2}}^{\varepsilon} (f_{i,j}^{+,n} + f_{i+1,j+1}^{-,n} - g_{i+1,j}^{+,n} - g_{i,j+1}^{-,n}) \\
\alpha_{i+\frac{1}{2},j-\frac{1}{2}}^{\varepsilon} (g_{i+1,j-1}^{+,n} - g_{i,j}^{-,n}) + \beta_{i+\frac{1}{2},j-\frac{1}{2}}^{\varepsilon} (f_{i+,n}^{+,n} + f_{i+1,j}^{-,n} - g_{i+1,j-1}^{+,n} - g_{i,j}^{-,n}) \\
\alpha_{i-\frac{1}{2},j+\frac{1}{2}}^{\varepsilon} (g_{i-1,j+1}^{-,n} - g_{i,j}^{+,n}) + \beta_{i-\frac{1}{2},j+\frac{1}{2}}^{\varepsilon} (f_{i-1,j}^{+,n} + f_{i+1,j}^{-,n} - g_{i+1,j-1}^{+,n} - g_{i-1,j+1}^{-,n})
\end{pmatrix}.$$

The implicit part relies on a block-diagonal matrix, for which,

$$\begin{pmatrix} 1+b & -b \\ -b & 1+b \end{pmatrix}^{-1} = \frac{1}{a+b} \begin{pmatrix} a & b \\ b & a \end{pmatrix}, \quad b = \frac{\Delta t}{2\varepsilon R}, \quad a = 1 + \frac{\Delta t}{2\varepsilon R},$$

so that (4.3) rewrites as an explicit time-marching scheme. The matrix in the left hand side of (4.3) may be written as

$$\operatorname{Id}_{\mathbb{R}^4} + \frac{\Delta t}{2\varepsilon R} H_0, \quad \text{with} \quad H_0 = \begin{pmatrix} 1 & -1 & 0 & 0 \\ -1 & 1 & 0 & 0 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & -1 & 1 \end{pmatrix}. \tag{4.4}$$

Denoting  $\mathfrak{f}_{i,j}^n=f_{i,j}^{+,n}+f_{i,j}^{-,n}$  and  $\mathfrak{g}_{i,j}^n=g_{i,j}^{+,n}+g_{i,j}^{-,n}$ , their time evolution follows from adding the first two and the last two equations in (4.3):

$$\mathfrak{f}_{i,j}^{n+1} = \mathfrak{f}_{i,j}^{n} + \frac{\Delta t}{2R} \left( \alpha_{i-\frac{1}{2},j-\frac{1}{2}}^{\varepsilon} (f_{i-1,j-1}^{+,n} - f_{i,j}^{-,n}) + \alpha_{i+\frac{1}{2},j+\frac{1}{2}}^{\varepsilon} (f_{i+1,j+1}^{-,n} - f_{i,j}^{+,n}) \right) \\
- \frac{\Delta t}{2R} \left( \beta_{i-\frac{1}{2},j-\frac{1}{2}}^{\varepsilon} (f_{i-1,j-1}^{+,n} + f_{i,j}^{-,n} - g_{i,j-1}^{+,n} - g_{i-1,j}^{-,n}) \right) \\
+ \beta_{i+\frac{1}{2},j+\frac{1}{2}}^{\varepsilon} (f_{i,j}^{+,n} + f_{i+1,j+1}^{-,n} - g_{i+1,j}^{+,n} - g_{i,j+1}^{-,n}) \right) \\
\mathfrak{g}_{i,j}^{n+1} = \mathfrak{g}_{i,j}^{n} + \frac{\Delta t}{2R} \left( \alpha_{i+\frac{1}{2},j-\frac{1}{2}}^{\varepsilon} (g_{i+1,j-1}^{+,n} - g_{i,j}^{-,n}) + \alpha_{i-\frac{1}{2},j+\frac{1}{2}}^{\varepsilon} (g_{i-1,j+1}^{-,n} - g_{i,j}^{+,n}) \right) \\
+ \frac{\Delta t}{2R} \left( \beta_{i+\frac{1}{2},j-\frac{1}{2}}^{\varepsilon} (f_{i,j-1}^{+,n} + f_{i+1,j}^{-,n} - g_{i+1,j-1}^{+,n} - g_{i,j}^{-,n}) \right) \\
+ \beta_{i-\frac{1}{2},j+\frac{1}{2}}^{\varepsilon} (f_{i-1,j}^{+,n} + f_{i,j+1}^{-,n} - g_{i,j}^{+,n} - g_{i-1,j+1}^{-,n}) \right). \tag{4.6}$$

#### **4.2. Formal diffusive limit.** When $\varepsilon \to 0$ , we deduce from (4.3) that,

$$\begin{pmatrix}
f_{i,j}^{+,n+1} \\
f_{i,j}^{-,n+1} \\
g_{i,j}^{+,n+1} \\
g_{i,j}^{-,n+1}
\end{pmatrix} \in \operatorname{Ker}(H_0) = \operatorname{Span} \left\{ \begin{pmatrix} 1 \\ 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \\ 1 \end{pmatrix} \right\}.$$
(4.7)

Then, in the limit  $\varepsilon \to 0$ , we expect, at least formally, that

$$f_{i,j}^{+,n+1} = f_{i,j}^{-,n+1} = \frac{1}{2} \mathfrak{f}_{i,j}^{n+1}, \qquad g_{i,j}^{+,n+1} = g_{i,j}^{-,n+1} = \frac{1}{2} \mathfrak{g}_{i,j}^{n+1},$$

along with, from (4.2),

$$\alpha_{i-\frac{1}{2},j+\frac{1}{2}}^{\varepsilon},\beta_{i-\frac{1}{2},j+\frac{1}{2}}^{\varepsilon}\to\frac{1}{\sigma_{i-\frac{1}{2},j+\frac{1}{2}}R},\qquad\varepsilon\to0,$$

so that, former equations (4.5) and (4.6) become

$$\begin{split} \mathfrak{f}_{i,j}^{n+1} &= \mathfrak{f}_{i,j}^{n} + \frac{\Delta t}{4R^{2}} \left( \frac{1}{\sigma_{i-\frac{1}{2},j-\frac{1}{2}}} \Big( (\mathfrak{g}_{i-1,j}^{n} - \mathfrak{f}_{i,j}^{n}) + (\mathfrak{g}_{i,j-1}^{n} - \mathfrak{f}_{i,j}^{n}) \Big) \right. \\ &\quad + \frac{1}{\sigma_{i+\frac{1}{2},j+\frac{1}{2}}} \Big( (\mathfrak{g}_{i+1,j}^{n} - \mathfrak{f}_{i,j}^{n}) + (\mathfrak{g}_{i,j+1}^{n} - \mathfrak{f}_{i,j}^{n}) \Big) \Big) \\ \\ \mathfrak{g}_{i,j}^{n+1} &= \mathfrak{g}_{i,j}^{n} + \frac{\Delta t}{4R^{2}} \left( \frac{1}{\sigma_{i-\frac{1}{2},j+\frac{1}{2}}} \Big( (\mathfrak{f}_{i,j+1}^{n} - \mathfrak{g}_{i,j}^{n}) + (\mathfrak{f}_{i-1,j}^{n} - \mathfrak{g}_{i,j}^{n}) \Big) \\ &\quad + \frac{1}{\sigma_{i+\frac{1}{2},j-\frac{1}{2}}} \Big( (\mathfrak{f}_{i+1,j}^{n} - \mathfrak{g}_{i,j}^{n}) + (\mathfrak{f}_{i,j-1}^{n} - \mathfrak{g}_{i,j}^{n}) \Big) \right). \end{split}$$

Accordingly,  $\mathfrak{f}$  and  $\mathfrak{g}$  satisfy similar diffusion equations, if the opacity  $\sigma$  is smooth. Consequently, if initially they are close enough (so–called "well-prepared initial data"), they can be expected to stay so because their difference  $\mathfrak{f}_{i,j}^n - \mathfrak{g}_{i,j}^n$  satisfies a parabolic equation. The decay of  $\mathfrak{f} - \mathfrak{g}$  will be rigorously proved when  $\sigma$  is a constant, see

Theorem 5.6. Adding, assuming  $\mathfrak{f} - \mathfrak{g} \to 0$ , and denoting  $\rho_{i,j}^n = \mathfrak{f}_{i,j}^n + \mathfrak{g}_{i,j}^n$ , it comes

$$\begin{split} \rho_{i,j}^{n+1} &= \rho_{i,j}^{n} + \frac{\Delta t}{2\sigma R^{2}} \left( \left( \frac{1}{2\sigma_{i+\frac{1}{2},j+\frac{1}{2}}} + \frac{1}{2\sigma_{i+\frac{1}{2},j-\frac{1}{2}}} \right) (\rho_{i+1,j}^{n} - \rho_{i,j}^{n}) \right. \\ &\quad + \left( \frac{1}{2\sigma_{i+\frac{1}{2},j+\frac{1}{2}}} + \frac{1}{2\sigma_{i-\frac{1}{2},j+\frac{1}{2}}} \right) (\rho_{i,j+1}^{n} - \rho_{i,j}^{n}) \\ &\quad - \left( \frac{1}{2\sigma_{i-\frac{1}{2},j+\frac{1}{2}}} + \frac{1}{2\sigma_{i-\frac{1}{2},j-\frac{1}{2}}} \right) (\rho_{i,j}^{n} - \rho_{i-1,j}^{n}) \\ &\quad - \left( \frac{1}{2\sigma_{i+\frac{1}{2},j-\frac{1}{2}}} + \frac{1}{2\sigma_{i-\frac{1}{2},j-\frac{1}{2}}} \right) (\rho_{i,j}^{n} - \rho_{i,j-1}^{n}) \right). \end{split}$$

which is a second-order, finite-differences, monotone (under the CFL restriction (5.6)) discretization of the macroscopic diffusion equation (1.5).

5. Rigorous uniform estimates for constant opacity. Let  $(u_{i,j})$  stand for any real sequence, we introduce the following notations,

$$\delta u_{i+\frac{1}{2},j} = u_{i+1,j} - u_{i,j}, \quad \delta u_{i,j+\frac{1}{2}} = u_{i,j+1} - u_{i,j},$$

$$\|u\|_1 = \sum_{i,j} \Delta x^2 |u_{i,j}|, \qquad TV(u) = \sum_{i,j} \Delta x \left( |\delta u_{i+\frac{1}{2},j}| + |\delta u_{i,j+\frac{1}{2}}| \right), \tag{5.1}$$

$$\|\Delta u\|_1 = \sum_{i,j} |u_{i+1,j} + u_{i,j+1} + u_{i-1,j} + u_{i,j-1} - 4u_{i,j}|.$$

**5.1. General properties of the scheme.** The first stepping stone is the definition of a convenient CFL restriction:

LEMMA 5.1. Assume that there exists  $\sigma_{min} > 0$  such that the opacity is such that  $0 < \sigma_{min} \le \sigma_{i-\frac{1}{2},j+\frac{1}{2}}$  for all i,j. Then, under the CFL condition

$$\Delta t \le \min \left\{ \frac{2}{3} \sigma_{min} R^2, \frac{R(\varepsilon + \sigma_{min} R)}{2} \left( 1 + \sqrt{1 + \frac{8\varepsilon}{\varepsilon + \sigma_{min} R}} \right) \right\}, \tag{5.2}$$

the IMEX scheme (4.3) preserves positivity.

*Proof.* Inverting the block-diagonal matrix in (4.3) brings the expressions,

$$\begin{split} f_{i,j}^{+,n+1} &= \frac{1}{2\varepsilon R + 2\Delta t} \Big( \Big( 2\varepsilon R + \Delta t - \frac{\Delta t^2}{2R} \big( \alpha_{i+\frac{1}{2},j+\frac{1}{2}}^{\varepsilon} + \beta_{i+\frac{1}{2},j+\frac{1}{2}}^{\varepsilon} \big) \Big) f_{i,j}^{+,n} \\ &+ \Big( \Delta t - \frac{\Delta t}{2R} \big( 2\varepsilon R + \Delta t \big) \big( \alpha_{i-\frac{1}{2},j-\frac{1}{2}}^{\varepsilon} + \beta_{i-\frac{1}{2},j-\frac{1}{2}}^{\varepsilon} \big) \Big) f_{i,j}^{-,n} \\ &+ \big( 2\varepsilon R + \Delta t \big) \frac{\Delta t}{2R} \Big( \alpha_{i-\frac{1}{2},j-\frac{1}{2}}^{\varepsilon} - \beta_{i-\frac{1}{2},j-\frac{1}{2}}^{\varepsilon} \big) f_{i-1,j-1}^{+,n} \\ &+ \frac{\Delta t^2}{2R} \big( \alpha_{i+\frac{1}{2},j+\frac{1}{2}}^{\varepsilon} - \beta_{i+\frac{1}{2},j+\frac{1}{2}}^{\varepsilon} \big) f_{i+1,j+1}^{-,n} \\ &+ \big( 2\varepsilon R + \Delta t \big) \frac{\Delta t}{2R} \beta_{i-\frac{1}{2},j-\frac{1}{2}}^{\varepsilon} \big( g_{i,j-1}^{+,n} + g_{i-1,j}^{-,n} \big) \\ &+ \frac{\Delta t^2}{2R} \beta_{i+\frac{1}{2},j+\frac{1}{2}}^{\varepsilon} \big( g_{i+1,j}^{+,n} + g_{i,j+1}^{-,n} \big) \Big), \end{split}$$
 (5.3)

and

$$\begin{split} f_{i,j}^{-,n+1} &= \frac{1}{2\varepsilon R + 2\Delta t} \Big( \Big( \Delta t - (2\varepsilon R + \Delta t) \frac{\Delta t}{2R} \big( \alpha_{i+\frac{1}{2},j+\frac{1}{2}}^{\varepsilon} + \beta_{i+\frac{1}{2},j+\frac{1}{2}}^{\varepsilon} \big) \Big) f_{i,j}^{+,n} \\ &+ \big( 2\varepsilon R + \Delta t - \frac{\Delta t^2}{2R} \big( \alpha_{i-\frac{1}{2},j-\frac{1}{2}}^{\varepsilon} + \beta_{i-\frac{1}{2},j-\frac{1}{2}}^{\varepsilon} \big) \Big) f_{i,j}^{-,n} \\ &+ \frac{\Delta t^2}{2R} \big( \alpha_{i-\frac{1}{2},j-\frac{1}{2}}^{\varepsilon} - \beta_{i-\frac{1}{2},j-\frac{1}{2}}^{\varepsilon} \big) f_{i-1,j-1}^{+,n} \\ &+ \big( 2\varepsilon R + \Delta t \big) \frac{\Delta t}{2R} \big( \alpha_{i+\frac{1}{2},j+\frac{1}{2}}^{\varepsilon} - \beta_{i+\frac{1}{2},j+\frac{1}{2}}^{\varepsilon} \big) f_{i+1,j+1}^{-,n} \\ &+ \frac{\Delta t^2}{2R} \beta_{i-\frac{1}{2},j-\frac{1}{2}} \big( g_{i,j-1}^{+,n} + g_{i-1,j}^{-,n} \big) \\ &+ \big( 2\varepsilon R + \Delta t \big) \frac{\Delta t}{2R} \beta_{i+\frac{1}{2},j+\frac{1}{2}}^{\varepsilon} \big( g_{i+1,j}^{+,n} + g_{i,j+1}^{-,n} \big) \Big), \end{split}$$

along with similar ones for  $g_{i,j}^{\pm,n+1}$ , too. From (4.2), it comes

$$\alpha_{i-\frac{1}{2},j+\frac{1}{2}}^{\varepsilon} - \beta_{i-\frac{1}{2},j+\frac{1}{2}}^{\varepsilon} = \frac{\varepsilon^2 + \varepsilon(\varepsilon + \sigma_{i-\frac{1}{2},j+\frac{1}{2}}R)}{(\varepsilon + \sigma_{i-\frac{1}{2},j+\frac{1}{2}}R)(\varepsilon^2 + (\varepsilon + \sigma_{i-\frac{1}{2},j+\frac{1}{2}}R)^2)} \ge 0.$$

Define a (decreasing) function  $\psi : \mathbb{R}^+ \to \mathbb{R}^+$ ,

$$\psi(x) \stackrel{def}{=} \frac{1}{\varepsilon + x} + \frac{x}{\varepsilon^2 + (\varepsilon + x)^2}, \qquad \psi'(x) \le 0 \text{ on } (0, +\infty),$$

then, since

$$\alpha_{i-\frac{1}{2},j+\frac{1}{2}}^{\varepsilon} + \beta_{i-\frac{1}{2},j+\frac{1}{2}}^{\varepsilon} = \psi(\sigma_{i-\frac{1}{2},j+\frac{1}{2}}R),$$

we get the following bound:

$$\alpha_{i-\frac{1}{2},j+\frac{1}{2}}^{\varepsilon} + \beta_{i-\frac{1}{2},j+\frac{1}{2}}^{\varepsilon} \le \frac{1}{\varepsilon + \sigma_{min}R} + \frac{\sigma_{min}R}{\varepsilon^2 + (\varepsilon + \sigma_{min}R)^2}.$$

Hence  $f_{i,j}^{\pm,n+1},g_{i,j}^{\pm,n+1})$  are nonnegative combinations of previous iterates if,

$$\left(\varepsilon + \frac{\Delta t}{2R}\right) \left(\frac{1}{\varepsilon + \sigma_{min}R} + \frac{\sigma_{min}R}{\varepsilon^2 + (\varepsilon + \sigma_{min}R)^2}\right) \le 1, \tag{5.4}$$

$$\frac{\Delta t^2}{2R} \left( \frac{1}{\varepsilon + \sigma_{min}R} + \frac{\sigma_{min}R}{\varepsilon^2 + (\varepsilon + \sigma_{min}R)^2} \right) \le 2\varepsilon R + \Delta t. \tag{5.5}$$

Conditions (5.4) and (5.5) are met if and only if,

$$\frac{\Delta t}{2R} \leq \sigma_{min} R \frac{\varepsilon^2 + \varepsilon \sigma_{min} R + (\sigma_{min} R)^2}{2\varepsilon^2 + 3\varepsilon \sigma_{min} R + 2(\sigma_{min} R)^2}, \qquad \frac{\Delta t^2}{R(\varepsilon + \sigma_{min} R)} \leq 2\varepsilon R + \Delta t$$

and these hold as soon as (5.2) does.  $\square$ 

Remark 1. A sufficient condition for (5.2) is the heat equation's restriction:

$$2\Delta t \le \sigma_{min} R^2 \tag{5.6}$$

LEMMA 5.2 (Conservation). Let us assume that the initial data are nonnegative and that (5.2) holds. Then, the scheme (4.3) is bounded in  $L^1$  and conservative:

$$||f^{+,n}||_1 + ||f^{-,n}||_1 + ||g^{+,n}||_1 + ||g^{-,n}||_1 = ||f^{+,0}||_1 + ||f^{-,0}||_1 + ||g^{+,0}||_1 + ||g^{-,0}||_1.$$

*Proof.* It suffices to add the lines of (4.3) and to sum over i and j.  $\square$  LEMMA 5.3 ( $L^{\infty}$  bound). Let initial data satisfy

$$0 \le f_{i,j}^{\pm,0} \le M, \qquad 0 \le g_{i,j}^{\pm,0} \le M.$$

Then, under the CFL (5.2),

$$\forall n \in \mathbb{N}, \qquad 0 \le f_{i,j}^{\pm,n} \le M, \qquad 0 \le g_{i,j}^{\pm,n} \le M.$$

*Proof.* The proof of Lemma 5.1 yields that, under (5.2),  $f_{i,j}^{\pm,n+1}$  and  $g_{i,j}^{\pm,n+1}$  are convex combination of previous iterates, giving the announced  $L^{\infty}$  bound.  $\square$ 

Remark 2. These bounds hold even if the opacity  $\sigma$  isn't a (positive) constant.

5.2. Uniform estimates in the case  $\sigma$  constant. We study rigorously the diffusive limit of (4.3) in order to prove that it is "asymptotic-preserving" (AP). Recall from (4.2) the coefficients,

$$\alpha^{\varepsilon} = \frac{1}{\varepsilon + \sigma R}; \qquad \beta^{\varepsilon} = \frac{\sigma R}{\varepsilon^2 + (\varepsilon + \sigma R)^2}, \qquad \text{for } \sigma \equiv \bar{\sigma} \in \mathbb{R}^+.$$
 (5.7)

As  $\sigma$  is constant, (4.3) simplifies into,

$$\begin{pmatrix}
1 + \frac{\Delta t}{2\varepsilon R} & -\frac{\Delta t}{2\varepsilon R} & 0 & 0 \\
-\frac{\Delta t}{2\varepsilon R} & 1 + \frac{\Delta t}{2\varepsilon R} & 0 & 0 \\
0 & 0 & 1 + \frac{\Delta t}{2\varepsilon R} & -\frac{\Delta t}{2\varepsilon R} \\
0 & 0 & -\frac{\Delta t}{2\varepsilon R} & 1 + \frac{\Delta t}{2\varepsilon R}
\end{pmatrix} = \begin{pmatrix}
f_{i,j}^{+,n+1} \\
f_{i,j}^{-,n+1} \\
g_{i,j}^{+,n+1} \\
g_{i,j}^{-,n}
\end{pmatrix} = \begin{pmatrix}
f_{i,j}^{+,n} \\
f_{i,j}^{-,n} \\
g_{i,j}^{-,n}
\end{pmatrix} + \frac{\Delta t}{2R} \begin{pmatrix}
\alpha^{\varepsilon} (f_{i-1,j-1}^{+,n} - f_{i,j}^{-,n}) - \beta^{\varepsilon} (f_{i-1,j-1}^{+,n} + f_{i,j}^{-,n} - g_{i,j-1}^{+,n} - g_{i-1,j}^{-,n}) \\
\alpha^{\varepsilon} (f_{i+1,j+1}^{-,n} - f_{i,j}^{+,n}) - \beta^{\varepsilon} (f_{i,j}^{+,n} + f_{i+1,j+1}^{-,n} - g_{i+1,j}^{+,n} - g_{i,j+1}^{-,n}) \\
\alpha^{\varepsilon} (g_{i+1,j-1}^{+,n} - g_{i,j}^{-,n}) + \beta^{\varepsilon} (f_{i,j-1}^{+,n} + f_{i+1,j-1}^{-,n} - g_{i+1,j-1}^{+,n} - g_{i,j}^{-,n}) \\
\alpha^{\varepsilon} (g_{i-1,j+1}^{-,n} - g_{i,j}^{+,n}) + \beta^{\varepsilon} (f_{i-1,j}^{+,n} + f_{i+1,j-1}^{-,n} - g_{i,j}^{+,n} - g_{i-1,j+1}^{-,n})
\end{pmatrix} (5.8)$$

LEMMA 5.4. Let  $\sigma$  be a positive constant: under the parabolic CFL restriction,

$$2\Delta t < \sigma_{min}R^2,\tag{5.9}$$

the scheme (5.8) is TVD (total variation diminishing),

$$TV(f^{+,n+1}) + TV(f^{-,n+1}) + TV(g^{+,n+1}) + TV(g^{-,n+1})$$

$$< TV(f^{+,n}) + TV(f^{-,n}) + TV(g^{+,n}) + TV(g^{-,n}).$$

*Proof.* By linearity, the expression of  $f_{i,j}^{+,n+1}$  in (5.3) in the proof of Lemma 5.1 is similar to the ones of  $\delta f_{i+\frac{1}{2},j}^{+,n}$ . Since (5.9) ensures that coefficients are nonnegative,

a triangle inequality brings,

$$\begin{split} |\delta f_{i+\frac{1}{2},j}^{+,n+1}| &\leq \frac{1}{2\varepsilon R + 2\Delta t} \Big( \big(2\varepsilon R + \Delta t - \frac{\Delta t^2}{2R} (\alpha^\varepsilon + \beta^\varepsilon) \big) |\delta f_{i+\frac{1}{2},j}^{+,n}| \\ &\quad + \big(\Delta t - \frac{\Delta t}{2R} (2\varepsilon R + \Delta t) (\alpha^\varepsilon + \beta^\varepsilon) \big) |\delta f_{i+\frac{1}{2},j}^{-,n}| \\ &\quad + \big(2\varepsilon R + \Delta t\big) \frac{\Delta t}{2R} (\alpha^\varepsilon - \beta^\varepsilon) |\delta f_{i-\frac{1}{2},j-1}^{+,n}| \\ &\quad + \frac{\Delta t^2}{2R} (\alpha^\varepsilon - \beta^\varepsilon) |\delta f_{i+\frac{3}{2},j+1}^{-,n}| \\ &\quad + \big(2\varepsilon R + \Delta t\big) \frac{\Delta t}{2R} \beta^\varepsilon (|\delta g_{i+\frac{1}{2},j-1}^{+,n}| + |\delta g_{i-\frac{1}{2},j}^{-,n}|) \\ &\quad + \frac{\Delta t^2}{2R} \beta^\varepsilon (|\delta g_{i+\frac{1}{2},j}^{+,n}| + |\delta g_{i+\frac{1}{2},j+1}^{-,n}|) \Big), \end{split}$$

with similar expressions for  $|\delta f_{i+\frac{1}{2},}^{-,n}|$ ,  $|\delta g_{i+\frac{1}{2},j}^{+,n+1}|$  and  $|\delta g_{i+\frac{1}{2},j}^{-,n+1}|$ . Adding,

$$\begin{split} |\delta f_{i+\frac{1}{2},j}^{+,n+1}| + |\delta f_{i+\frac{1}{2},j}^{-,n+1}| + |\delta g_{i+\frac{1}{2},j}^{+,n+1}| + |\delta g_{i+\frac{1}{2},j}^{-,n+1}| \leq \\ & \left(1 - \frac{\Delta t}{2R} (\alpha^{\varepsilon} + \beta^{\varepsilon})\right) \left(|\delta f_{i+\frac{1}{2},j}^{+,n}| + |\delta f_{i+\frac{1}{2},j}^{-,n}| + |\delta g_{i+\frac{1}{2},j}^{+,n}| + |\delta g_{i+\frac{1}{2},j}^{-,n}|\right) \\ & + \frac{\Delta t}{2R} (\alpha^{\varepsilon} - \beta^{\varepsilon}) \left(|\delta f_{i-\frac{1}{2},j-1}^{+,n}| + |\delta f_{i+\frac{3}{2},j+1}^{-,n}| + |\delta g_{i+\frac{3}{2},j-1}^{+,n}| + |\delta g_{i-\frac{1}{2},j+1}^{-,n}|\right) \\ & + \frac{\Delta t}{2R} \beta^{\varepsilon} \left(|\delta f_{i+\frac{1}{2},j-1}^{+,n}| + |\delta f_{i+\frac{3}{2},j}^{-,n}| + |\delta f_{i-\frac{1}{2},j}^{+,n}| + |\delta f_{i+\frac{1}{2},j+1}^{-,n}|\right) \\ & + \frac{\Delta t}{2R} \beta^{\varepsilon} \left(|\delta g_{i+\frac{1}{2},j-1}^{+,n}| + |\delta_{i-\frac{1}{2},j}^{-,n}| + |\delta g_{i+\frac{3}{2},j}^{+,n}| + |\delta g_{i+\frac{1}{2},j+1}^{-,n}|\right), \end{split}$$

and summing over i and j, we get, after shifting the indexes,

$$\begin{split} \sum_{i,j} \left( |\delta f_{i+\frac{1}{2},j}^{+,n+1}| + |\delta f_{i+\frac{1}{2},j}^{-,n+1}| + |\delta g_{i+\frac{1}{2},j}^{+,n+1}| + |\delta g_{i+\frac{1}{2},j}^{-,n+1}| \right) \\ & \leq \sum_{i,j} \left( |\delta f_{i+\frac{1}{2},j}^{+,n}| + |\delta f_{i+\frac{1}{2},j}^{-,n}| + |\delta g_{i+\frac{1}{2},j}^{+,n}| + |\delta g_{i+\frac{1}{2},j}^{-,n}| \right). \end{split}$$

By the same token with variations in j instead of i, we get the claimed result.  $\square$  Define  $f_{\Delta x}^{\pm}, g_{\Delta x}^{\pm}$  the piecewise constant functions such that,

$$f^{\pm}(t, \mathbf{x}) = f_{i,j}^{\pm,n}, \qquad g^{\pm}(t, \mathbf{x}) = g_{i,j}^{\pm,n},$$
 (5.10)

for  $t \in [n\Delta t, (n+1)\Delta t)$ ,  $\mathbf{x} \in ((i-\frac{1}{2})\Delta x, (i+\frac{1}{2})\Delta x) \times ((j-\frac{1}{2})\Delta x, (j+\frac{1}{2})\Delta x)$ .

COROLLARY 5.5. Under (5.9), and for bounded integrable nonnegative data, the approximate solutions (5.10) are uniformly bounded in  $L^1 \cap L^\infty \cap BV([0,T] \times \mathbb{R}^2)$ .

**5.3. Rigorous diffusive limit.** We are now in position to state the main result of this section:

Theorem 5.6 (Asymptotic-Preserving property). Assume (5.9) holds and that initial data are independent of  $\varepsilon$  and smooth enough such that

$$\exists C \in \mathbb{R}^+, \qquad \|\Delta f^{+,0}\|_1 + \|\Delta f^{-,0}\|_1 + \|\Delta g^{+,0}\|_1 + \|\Delta g^{-,0}\|_1 \le C,$$

then the sequences  $(f_{i,j}^{\varepsilon\pm,n})$  and  $(g_{i,j}^{\varepsilon\pm,n})$  are of uniformly bounded total variation and converge towards limits, denoted respectively  $(f_{i,j}^{\pm,n})$  and  $(g_{i,j}^{\pm,n})$  which satisfy:

$$f_{i,j}^{+,n} = f_{i,j}^{-,n} = \frac{1}{2} \mathfrak{f}_{i,j}^n, \qquad g_{i,j}^{+,n} = g_{i,j}^{-,n} = \frac{1}{2} \mathfrak{g}_{i,j}^n,$$

where

$$\mathfrak{f}_{i,j}^{n+1} = \mathfrak{f}_{i,j}^{n} + \frac{\Delta t}{4\sigma R^2} (\mathfrak{g}_{i,j-1}^{n} + \mathfrak{g}_{i-1,j}^{n} + \mathfrak{g}_{i+1,j}^{n} + \mathfrak{g}_{i,j+1}^{n} - 4\mathfrak{f}_{i,j}^{n})$$
 (5.11)

$$\mathfrak{g}_{i,j}^{n+1} = \mathfrak{g}_{i,j}^{n} + \frac{\Delta t}{4\sigma R^{2}} (\mathfrak{f}_{i,j-1}^{n} + \mathfrak{f}_{i+1,j}^{n} + \mathfrak{f}_{i-1,j}^{n} + \mathfrak{f}_{i,j+1}^{n} - 4\mathfrak{g}_{i,j}^{n}). \tag{5.12}$$

Moreover, the "Maxwellian gap" decreases in time according to,

$$\forall n \in \mathbb{N}_*, \qquad \|\mathfrak{f}^n - \mathfrak{g}^n\|_1 \le \|\mathfrak{f}^0 - \mathfrak{g}^0\|_1 \exp\left(-\frac{2n\Delta t}{\sigma R^2}\right) + CR^2. \tag{5.13}$$

Adding both equations (5.11)-(5.12), we deduce the following result:

COROLLARY 5.7. Under the same assumptions as Theorem 5.6, we have

$$\rho_{i,j}^{n+1} = \rho_{i,j}^{n} + \frac{\Delta t}{4\sigma R^{2}} (\rho_{i,j-1}^{n} + \rho_{i,j+1}^{n} + \rho_{i-1,j}^{n} + \rho_{i+1,j}^{n} - 4\rho_{i,j}^{n}), \quad \rho^{n} = \mathfrak{f}^{n} + \mathfrak{g}^{n}.$$

along with  $f^{\pm,n} = \rho^n/4 + O(R^2)$ ,  $g^{\pm,n} = \rho^n/4 + O(R^2)$ .

*Proof.* By the computations in the proof of Lemma 5.4, the sequences  $(f^{\varepsilon_{i,j}^{\pm,n}})$ , and  $(g^{\varepsilon_{i,j}^{\pm,n}})$  are Cauchy sequences with respect to  $\varepsilon$  in  $\ell^1$ . Thus, when  $\varepsilon \to 0$ , they converge to some limits denoted respectively  $(f^{\pm,n}_{i,j})$ , and  $(g^{\pm,n}_{i,j})$  and we can pass to the limit in (5.8). Hence as  $\varepsilon \to 0$ , by (4.4) and (4.7), we get that

$$\forall (i,j,n) \in \mathbb{Z}^2 \times \mathbb{N}, \qquad f_{i,j}^{+,n+1} = f_{i,j}^{-,n+1}, \quad g_{i,j}^{+,n+1} = g_{i,j}^{-,n+1}.$$

Denoting  $\mathfrak{f}^{\varepsilon n}_{i,j}=f^{\varepsilon^+,n}_{i,j}+f^{\varepsilon^-,n}_{i,j}$  and  $\mathfrak{g}^{\varepsilon n}_{i,j}=g^{\varepsilon^+,n}_{i,j}+g^{\varepsilon^-,n}_{i,j}$ , we obtain their equations by adding the first two and the last two lines in (5.8):

$$\mathfrak{f}^{\varepsilon n+1}_{i,j} = \mathfrak{f}^{\varepsilon n}_{i,j} + \frac{\Delta t}{2R} \left( \alpha^{\varepsilon} (f^{\varepsilon+,n}_{i-1,j-1} - f^{\varepsilon-,n}_{i,j}) + \alpha^{\varepsilon} (f^{\varepsilon-,n}_{i+1,j+1} - f^{\varepsilon+,n}_{i,j}) \right) \\
- \frac{\Delta t}{2R} \left( \beta^{\varepsilon} (f^{\varepsilon+,n}_{i-1,j-1} + \mathfrak{f}^{\varepsilon}_{i,j}^{-,n} - g^{\varepsilon+,n}_{i,j-1} - g^{\varepsilon-,n}_{i-1,j}) \right) \\
+ \beta^{\varepsilon} (f^{\varepsilon+,n}_{i,j} + f^{\varepsilon-,n}_{i+1,j+1} - g^{\varepsilon+,n}_{i+1,j} - g^{\varepsilon-,n}_{i,j+1}) \right);$$
(5.14)

$$\mathfrak{g}^{\varepsilon n+1}_{i,j} = \mathfrak{g}^{\varepsilon n}_{i,j} + \frac{\Delta t}{2R} \left( \alpha^{\varepsilon} (g^{\varepsilon +,n}_{i+1,j-1} - g^{\varepsilon -,n}_{i,j}) + \alpha^{\varepsilon} (g^{\varepsilon -,n}_{i-1,j+1} - g^{\varepsilon +,n}_{i,j}) \right) \\
+ \frac{\Delta t}{2R} \left( \beta^{\varepsilon} (f^{\varepsilon +,n}_{i,j-1} + f^{\varepsilon -,n}_{i+1,j} - g^{\varepsilon +,n}_{i+1,j-1} - g^{\varepsilon -,n}_{i,j}) \right) \\
+ \beta^{\varepsilon} (f^{\varepsilon +,n}_{i-1,j} + f^{\varepsilon -,n}_{i,j+1} - g^{\varepsilon +,n}_{i,j} - g^{\varepsilon -,n}_{i-1,j+1}) \right).$$
(5.15)

From the expressions (5.7),

$$\alpha^{\varepsilon}, \ \beta^{\varepsilon} \to \frac{1}{\sigma R}, \ \text{when } \varepsilon \to 0.$$

Yet, passing into the limit we obtain both (5.11) and (5.12). If initially  $\mathfrak{f}$  and  $\mathfrak{g}$  are identical, they stay so. More precisely, let  $D_{i,j}^n = \mathfrak{f}_{i,j}^n - \mathfrak{g}_{i,j}^n$  be the Maxwellian gap,

$$D_{i,j}^{n+1} = D_{i,j}^{n} \left(1 - \frac{2\Delta t}{\sigma R^2}\right) + \frac{\Delta t}{4\sigma R^2} \left(4D_{i,j}^{n} - D_{i,j-1}^{n} - D_{i-1,j}^{n} - D_{i+1,j}^{n} - D_{i,j+1}^{n}\right). \tag{5.16}$$

Hypotheses on initial data in Theorem 5.6 ensure that

$$\|\Delta \mathfrak{f}^0\|_1 + \|\Delta \mathfrak{g}^0\|_1 \le C.$$

Moreover, from (5.11)–(5.12) and (5.9), we have

$$\|\Delta \mathfrak{f}^{n+1}\|_{1} \leq \|\Delta \mathfrak{f}^{n}\|_{1} (1 - \frac{\Delta t}{\sigma R^{2}}) + \frac{\Delta t}{\sigma R^{2}} \|\Delta \mathfrak{g}^{n}\|_{1}$$
$$\|\Delta \mathfrak{g}^{n+1}\|_{1} \leq \|\Delta \mathfrak{g}^{n}\|_{1} (1 - \frac{\Delta t}{\sigma R^{2}}) + \frac{\Delta t}{\sigma R^{2}} \|\Delta \mathfrak{f}^{n}\|_{1}.$$

As a consequence, for all  $n \in \mathbb{N}$ , we have  $\|\Delta \mathfrak{f}^n\|_1 + \|\Delta \mathfrak{g}^n\|_1 \leq C$ , so that

$$\sum_{i,j} |4D_{i,j}^n - D_{i,j-1}^n - D_{i-1,j}^n - D_{i+1,j}^n - D_{i,j+1}^n| \le C.$$

By inserting this latter inequality into (5.16), taking modulus and summing.

$$||D^{n+1}||_1 = \sum_{i,j} \Delta x^2 |D_{i,j}^{n+1}| \le ||D^n||_1 (1 - \frac{2\Delta t}{\sigma R^2}) + C\frac{\Delta t}{\sigma},$$

holds for some constant  $C \geq 0$ . Applying a discrete Gronwall inequality,

$$||D^{n}||_{1} \leq ||D^{0}||_{1}e^{-2n\Delta t/(\sigma R^{2})} + C\frac{\Delta t}{\sigma} \sum_{k=0}^{n-1} \left(1 - \frac{2\Delta t}{\sigma R^{2}}\right)^{k}$$
$$\leq ||D^{0}||_{1}e^{-2n\Delta t/(\sigma R^{2})} + \frac{C}{2}R^{2}.$$

П

REMARK 3. The bound (5.13) relates to (1.4) and means that, for constant opacity,  $\|\mathfrak{f} - \mathfrak{g}\|_1$  is roughly of order  $\Delta x^2$  when nonnegative initial data belong to  $W^{2,1}(\mathbb{R}^2)$ . Conversely, both  $\|f^+ - f^-\|_1$  and  $\|g^+ - g^-\|_1$  are of order  $\varepsilon$ , as in the 1D case, see [11, Lemma 8.4] and [14]. All in all, these will be similar when  $\varepsilon \simeq O(R^2)$ .

- **6. Numerical assessments.** Hereafter, some benchmarks for both (3.5) and (4.3) are presented, on a coarse  $32 \times 32$  uniform Cartesian grid. The computational domain is the unit square  $\Omega = (0,1)^2$  with various boundary conditions.
- **6.1.** Hyperbolic/kinetic scaling. Following [8, §5.1], the long-time stabilization of (1.3) can be considered in presence of a stiff, discontinuous opacity,

$$\sigma(\mathbf{x}) = 5 + 995 \cdot \chi \left( \max(|x - \frac{1}{2}|, |y - \frac{1}{2}|) < \frac{1}{4} \right),$$

with  $\chi(A)$  the indicator function of a set A. A null initial data and an inflow boundary condition is prescribed on the left side by means of,

$$f^+(x=0,\cdot) = g^-(x=0,\cdot) = 1,$$

along with specular reflection on horizontal walls y = 0, y = 1, and outflow at x = 1. The macroscopic velocity field  $\vec{v}(t, \mathbf{x})$  is defined as the following ratio,

$$\forall \mathbf{x} \in \Omega, \qquad \vec{v}(t, \mathbf{x}) = \begin{pmatrix} \frac{f^+(t, \mathbf{x}) - f^-(t, \mathbf{x})}{\rho(t, \mathbf{x})} \\ \frac{g^+(t, \mathbf{x}) - g^-(t, \mathbf{x})}{\rho(t, \mathbf{x})} \end{pmatrix}, \qquad \text{where } \rho \neq 0.$$

The scheme (3.5) was set with  $\Delta t = 0.975\sqrt{2}\,\Delta x$ , and iterated up to T = 35: see Fig. 6.1. Another benchmark consists in considering smooth, but quickly varying opacity,

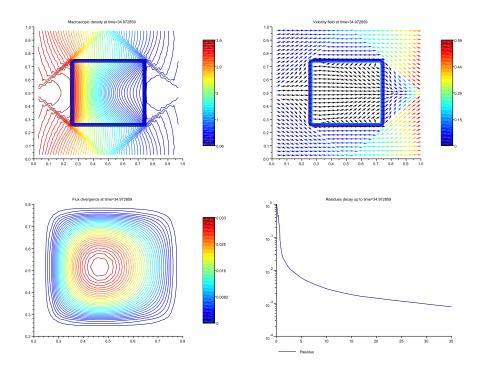


Figure 6.1. Steady-state of (3.5) in presence of a square opaque zone.

$$\begin{split} \sigma(\mathbf{x}) &= 5 + 195 \exp\left(-\gamma((x - \frac{1}{4})^2 + (x - \frac{1}{2})^2 + (x - \frac{3}{4})^2)\right) \\ &\times \exp\left(-\gamma((y - \frac{1}{4})^2 + (y - \frac{1}{2})^2 + (y - \frac{3}{4})^2)\right), \qquad \gamma = 400, \end{split}$$

with identical initial and boundary conditions. Results are displayed on Fig. 6.2. In particular, on both Figs. 6.1 and 6.2, a (second-order) centered approximation of the divergence of the macroscopic flux, div  $\mathbf{J}(t, \mathbf{x})$  was displayed, so as to shed light on the ability of (3.5) to stabilize on a correct discretization of stationary regimes.

**6.2. Diffusive/parabolic scaling.** In order to validate the scheme (4.3), the same array of opaque Gaussian bumps was set, along with the parameter  $\varepsilon = 10^{-5}$ , outflow boundary conditions on each side, and Maxwellian (well-prepared) initial data,

$$\rho(t=0,\mathbf{x}) = \exp\left(-\nu((x-0.375)^2 + (x-0.625)^2)\right) \times \exp\left(-\nu((y-0.375)^2 + (y-0.635)^2)\right), \qquad \nu = 250.$$

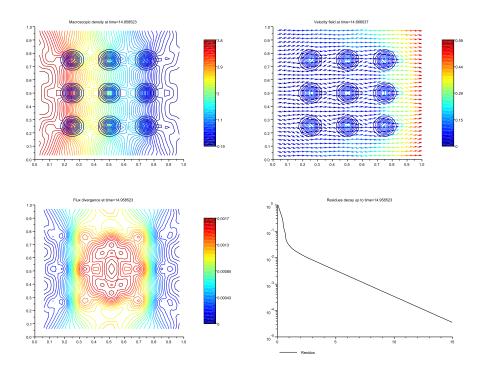


Figure 6.2. Steady-state of (3.5) in a periodic array of obstacles.

The scheme was iterated until T=15 with the CFL condition (5.6): see Fig. 6.3. The macroscopic density is correctly confined inside the array of obstacles, showing how tiny the artificial dissipation of the IMEX scheme really is. The Maxwellian gap  $|\mathfrak{f}-\mathfrak{g}|$  is locally of  $10^{-3}$ , a value compatible with (5.13) because  $\Delta x^2 \simeq 10^{-3}$ , even in the vicinity of areas of strong variations of  $\sigma(\mathbf{x})$ ; it smoothly decays with time. Beside,  $\Delta x^2$  is also the order of accuracy for the centered discretization of the diffusion equation (4.8). The macroscopic velocity field  $\vec{v}$  is now rescaled,

$$\forall \mathbf{x} \in \Omega, \qquad \vec{v}(t, \mathbf{x}) = \frac{1}{\varepsilon} \begin{pmatrix} \frac{f^+(t, \mathbf{x}) - f^-(t, \mathbf{x})}{\rho(t, \mathbf{x})} \\ \frac{g^+(t, \mathbf{x}) - g^-(t, \mathbf{x})}{\rho(t, \mathbf{x})} \end{pmatrix}, \qquad \rho \neq 0.$$

A simpler benchmark consists in iterating (4.3) with a Gaussian opacity,

$$\forall \mathbf{x} \in \Omega, \qquad \sigma(\mathbf{x}) = 5 + 15 \exp\left(-25(|x - \frac{1}{2}|^2 + |y - \frac{1}{2}|^2)\right),$$

with identical initial and outflow boundary conditions, up to T = 0.1: see Fig. 6.4.

7. Conclusion and outlook. The present paper showed that a high-quality, genuinely two-dimensional, numerical scheme (3.5), (4.3) can be deduced from the computations achieved in [4]. Such a strategy is by no means limited to isotropic scattering. Following [11, §10.3], an elementary model of chemotaxis dynamics is,

$$\partial_t f + \mathbf{v} \cdot \nabla f = \chi(\mathbf{v} \cdot \nabla S)\rho(t, \mathbf{x}) - f(\mathbf{x}, \mathbf{v}), \quad \mathbf{a} := \nabla S(\bar{\mathbf{x}}) \in \mathbb{R}^2,$$
 (7.1)

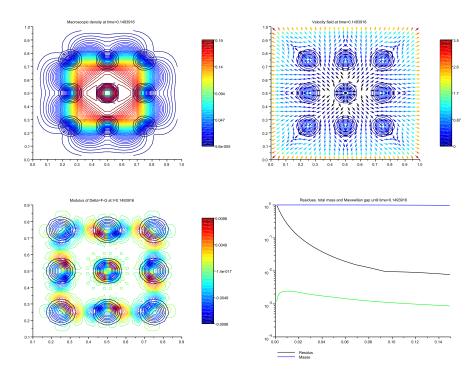


Figure 6.3. Diffusive approximation (4.3) at T = 15,  $\varepsilon = 10^{-5}$  in a periodic array of obstacles.

where  $\nabla S$  is "frozen" locally at a point  $\bar{\mathbf{x}}$  and the biasing function  $\chi \geq 0$  is normalized so as to get the standard 2D continuity equation:

$$\int_{\mathbb{S}^1} \chi(\mathbf{v}) \frac{\mathrm{d}\mathbf{v}}{2\pi} = 1, \qquad \partial_t \rho(t, \mathbf{x}) + \text{div } \mathbf{J} = 0.$$

The analogue of the Laplace transform in (2.1) for steady-states  $f(\mathbf{x}, \mathbf{v})$  reads,

$$f(\mathbf{x}, \mathbf{v}) = \chi(\mathbf{v}) \int_0^\infty \exp(-r)\rho(\mathbf{x} - r\mathbf{v}) dr = \chi(\mathbf{v}) \mathcal{L}_r(\tilde{\rho}_{\mathbf{x}, \mathbf{v}})[p = 1], \quad (7.2)$$

from which follows a new Fredholm equation, now involving the biasing function  $\chi$ ,

$$\rho(\mathbf{x}) = \int_0^\infty \exp(-r) \left( \int_{\mathbb{S}^1} \chi(\mathbf{v}) \, \rho(\mathbf{x} - r\mathbf{v}) \frac{\mathrm{d}\mathbf{v}}{2\pi} \right) \mathrm{d}r.$$
 (7.3)

To mimic some computations of [4], macroscopic steady-states should verify,

$$\forall r \in \mathbb{R}^+, \qquad \rho(\mathbf{x}) = \int_{\mathbb{S}^1} \chi(\mathbf{v}) \rho(\mathbf{x} - r\mathbf{v}) \frac{\mathrm{d}\mathbf{v}}{2\pi},$$

which means that our "biasing function"  $\chi$  should also be the "Poisson kernel" of a certain elliptic differential operator that  $\rho(\mathbf{x})$  solves. Indeed,  $\rho(\mathbf{x} - r\mathbf{v})$  is "boundary data" on  $\mathbb{S}^1$ , so  $\rho(\mathbf{x})$  is the "solution value". Accordingly, from [3, eqn (2.24)],

$$\rho(\mathbf{x}) = \int_0^{2\pi} \rho\left(\mathbf{x} + r e^{i\theta}\right) \frac{\exp(-\omega r \cos(\theta - \mu))}{\mathcal{I}_0(\omega r)} \frac{d\theta}{2\pi},$$

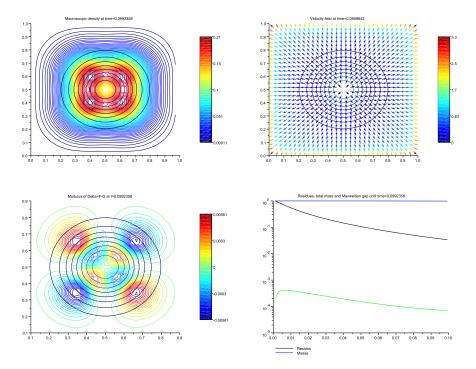


Figure 6.4. Diffusive approximation (4.3) at T = 15,  $\varepsilon = 10^{-5}$  with a Gaussian opacity.

so that, by changing  $\theta \to \theta - \pi$ , one gets (see also [6, 10, 20])

$$\rho(\mathbf{x}) = \int_{-\pi}^{\pi} \rho\left(\mathbf{x} - r e^{i\theta}\right) \frac{\exp(\omega r \cos(\theta - \mu))}{\mathcal{I}_0(\omega r)} \frac{\mathrm{d}\theta}{2\pi},$$

Pick, as the biasing function,  $(\mathcal{I}_0$ , the modified Bessel function of index zero)

$$\chi(\mathbf{v} = e^{i\theta}) = \frac{\exp(\omega r \cos(\theta - \mu))}{\mathcal{I}_0(\omega r)} \ge 0, \qquad \int_0^{2\pi} \frac{\exp(\omega r \cos \theta)}{\mathcal{I}_0(\omega r)} \frac{d\theta}{2\pi} = 1,$$

the normalization being a consequence of the "integral representation of Bessel functions", see e.g. [3, eqn (3.1)], then such a kernel corresponds to drift-diffusion equation,

$$-\Delta \rho + \mathbf{a} \cdot \nabla \rho = 0, \quad \text{in the disk of radius } r > 0, \tag{7.4}$$

where (see again [3, eqns (2.1–3) and (2.12)]), for  $\mu \in (0, 2\pi)$ ,

$$0 \le \omega := \frac{\|\mathbf{a}\|}{2}, \qquad \frac{\mathbf{a}}{2} = \omega(\cos \mu, \sin \mu) \in \mathbb{R}^2,$$

is the polar representation of the drift velocity  $\mathbf{a} \in \mathbb{R}^2$  in (7.4). Accordingly, one can relate mesoscopic to macroscopic steady-states thanks to (7.2), and similar derivations as the ones performed in this article may lead to a "truly two-dimensional", asymptotic-preserving (in diffusive scaling) discretization of (7.1), like (3.5) and (4.3).

### Appendix A. S-matrix for Goldstein-Taylor model in 1D.

It might be interesting to recall some properties of "two-stream" one-dimensional (position-dependent) radiative transfer, already studied in [14], [11, §8.2] and [7, 9],

$$\partial_t f^{\pm} \pm \partial_x f^{\pm} = \sigma(x)(\rho/2 - f^{\pm}), \qquad \rho = f^+ + f^-.$$

Macroscopic (diffusive) stationary regimes in 1D reduce to  $\rho''(x) = 0$ , *i.e.* constant or linear functions, and yield Case's polynomial solutions, 1 and x - v. Accordingly, for  $R = \Delta x/2$  and  $f(x, v) = \alpha + \beta(x - v)$ ,

$$M = \begin{pmatrix} 1 & -(1+\sigma R) \\ 1 & (1+\sigma R) \end{pmatrix}, \qquad \tilde{M} = \begin{pmatrix} 1 & -(1-\sigma R) \\ 1 & (1-\sigma R) \end{pmatrix},$$

so that,

$$|M| = 2(1 + \sigma R), \qquad M^{-1} = \frac{1}{2} \begin{pmatrix} 1 & 1 \\ -\frac{1}{1 + \sigma R} & \frac{1}{1 + \sigma R} \end{pmatrix},$$

meaning that  $\alpha$  is the average of incoming states, and

$$S(\sigma) = \tilde{M} M^{-1} = \frac{1}{1 + \sigma R} \begin{pmatrix} 1 & \sigma R \\ \sigma R & 1 \end{pmatrix}.$$

Such a S-matrix is "doubly-stochastic" because both its rows and columns add to unity and all its entries are positive when  $\sigma R \geq 0$ . Asymptotic limits are

$$S(\sigma) \to \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$
 if  $\sigma \to 0$ ,  $S(\sigma) \to \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$  if  $\sigma \to +\infty$ .

The resulting well-balanced 1D time-marching scheme reads,

$$\begin{pmatrix} f_j^{+,n+1} \\ f_{j-1}^{-,n+1} \end{pmatrix} = (1 - \frac{\Delta t}{2R}) \begin{pmatrix} f_j^{+,n} \\ f_{j-1}^{-,n} \end{pmatrix} + \frac{\Delta t}{2R} S(\sigma_{j-\frac{1}{2}}) \begin{pmatrix} f_{j-1}^{+,n} \\ f_{j}^{-,n} \end{pmatrix}.$$

In parabolic scaling, the following decomposition holds,

$$S(\sigma) = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} + \frac{\varepsilon}{\varepsilon + \sigma R} \begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix},$$

and brings back the well-known IMEX scheme originally written in [14],

$$\begin{pmatrix} f_{j}^{+,n+1} \\ f_{j-1}^{-,n+1} \end{pmatrix} + \frac{\Delta t}{2\varepsilon R} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} f_{j}^{+,n+1} \\ f_{j-1}^{-,n+1} \end{pmatrix}$$

$$= \begin{pmatrix} f_{j}^{+,n} \\ f_{j-1}^{-,n} \end{pmatrix} + \frac{\Delta t}{2R(\varepsilon + \sigma R)} \begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix} \begin{pmatrix} f_{j-1}^{+,n} \\ f_{j}^{-,n} \end{pmatrix}.$$

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