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Stop! Border Ahead: Automatic detection of subthalamic exit during deep brain stimulation surgery

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3 **Stop! Border Ahead: Automatic detection of subthalamic exit during deep brain**
4 **stimulation surgery**
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For Peer Review

Abstract

Background: Microelectrode recordings along pre-planned trajectories are often used for accurate definition of the subthalamic nucleus (STN) borders during deep brain stimulation (DBS) surgery for Parkinson's disease. Usually, the demarcation of the STN borders is detected manually by a neurophysiologist. The exact detection of the borders is difficult and especially detecting the transition between the STN and the substantia nigra pars reticulata. Consequently, demarcation may be inaccurate, leading to sub-optimal location of the DBS lead and inadequate clinical outcomes.

Methods: We present machine learning classification procedures that utilize microelectrode recordings power spectra and allow for real time, high accuracy discrimination between STN and substantia nigra pars reticulata.

Results: A support vector machine procedure was tested on microelectrode recordings from 58 trajectories that included both STN and substantia nigra pars reticulata that achieved a 97.6% consistency with human expert classification (evaluated by 10-fold cross validation). We used the same dataset as a training set to find the optimal parameters for a hidden Markov model using both microelectrode recordings features and trajectory history to enable a real-time classification of the ventral STN border (STN exit). Seventy-three additional trajectories were used to test the reliability of the learned statistical model in identifying the exit from the STN. The hidden Markov model procedure identified the STN exit with an error of 0.04 ± 0.18 mm and detection reliability (error < 1 mm) of 94%.

Conclusion: The results indicate that robust, accurate and automatic real-time electrophysiological detection of the ventral STN border is feasible.

INTRODUCTION

Surgical treatment for advanced Parkinson's disease (PD) includes high-frequency deep brain stimulation (DBS) of the subthalamic nucleus (STN), which has proven to be surgically safe and beneficial over time.¹⁻⁴ In some patients, mood disorders such as depression⁵ or manic symptoms⁶⁻¹¹ may be observed after stimulation as a result of suboptimally placed DBS leads. By contrast, the combined stimulation of the substantia nigra pars reticulata (SNr) and STN may improve freezing of gait in patients with advanced PD.^{10,11} Therefore, accurate differentiation of the STN from the SNr is essential for achieving optimal therapeutic benefit while avoiding psychiatric complications.

Microelectrode recordings (MERs) along pre-planned trajectories are often used for improved delineation of the location of the STN during DBS surgery for Parkinson's disease. The detection of the *dorsolateral* region of the STN is based on clear-cut changes in electrical activity in the form of a sharp rise in the total power of the MER (as measured by the root mean square, RMS),¹² the tremor-frequency, and the β -oscillatory activity (13–30 Hz).¹³ In contrast, several factors can make electrophysiological determination of the *ventral* STN border more difficult, and in particular an uninterrupted STN-SNr transition because in this case there is no drop in activity (or RMS). In addition, the cells in the STN ventral domain have firing characteristics (reduced β band and tremor frequency oscillations) resembling SNr cells.¹⁴⁻¹⁸ Finally, electrophysiological determination of the STN exit can be challenging because white matter gaps in the STN may lead to erroneous early detection of STN exit.¹² Therefore, the

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3 electrophysiological determination of the STN ventral border can be ambiguous and occasionally
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5 difficult to define.
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10 Although recent imaging studies have been able to improve the differentiation between the STN
11 and the SNr,¹⁹ electrophysiology is still necessary to identify and verify the STN-SNr transition
12 intraoperatively. To facilitate detection of the transition, this article describes a new automatic,
13 reliable procedure for locating the STN exit. Earlier automatic methods that use RMS values^{12,20–}
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23 are successful in identifying STN-white matter (STN-WM) transitions, but are not as good for the direct STN-SNr transition. To improve the STN-SNr transition and STN lower border detection, we developed a computational analysis procedure that capitalizes on several features from the power spectra of the MER and allows for high accuracy discrimination between the STN and the SNr.

PATIENTS AND METHODS

Patients and Surgery

MERs were analyzed from 131 microelectrode trajectories that passed through both the STN and SNr of 81 Parkinson's disease patients undergoing bilateral STN DBS implantation. The patients' demography and clinical state were as follows: mean age (62.1 years), mean disease duration (10.3 years), 36% female, mean unified Parkinson's disease rating scale - part III (UPDRS III) score OFF/ON therapy before surgery (51.1/19.4), and mean levodopa equivalent dosage (LED) before surgery (849.6 mg/day). Patient demographic information appears in Supporting

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3 Information Table S4. This study was authorized and approved by the Institutional Review Board
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5 of Hadassah Hospital in accordance with the Helsinki Declaration (reference code: HMO-0064-
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7 12). All patients were awake during surgery. Further details on the surgical procedure and data
8
9 acquisition can be found in our previous reports.^{12,23}
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14 15 **Microelectrode recordings**

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17 For both the left and right hemispheres, one or two parallel microelectrodes were inserted and the
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19 recording started 10 mm above the calculated target. Our trajectories followed a double-oblique
20
21 approach towards the dorsolateral STN target. In most cases, two microelectrodes were used (Fig.
22
23 1A): a ‘central’ electrode was directed at the center of the dorsolateral STN target (as per
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25 imaging) and often traversed STN and entered SNr without passing through the white matter. An
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27 ‘anterior’ electrode was advanced 2 mm anterior to the central electrode (in the parasagittal
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29 plane) and therefore crossed STN-SNr area in a more ventral plane. In contrast to the central
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31 electrode, the anterior electrode often passed through the white matter before it entered the SNr.
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34 Analysis was not based on continuous recordings during the entire advance towards the
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36 dorsolateral STN target, but rather on segments of data recorded at specific points (without
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38 electrode movement; Fig. 1B). Segments of data were recorded for at least 4 seconds, after 0.5
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40 seconds of lowering the electrode. Further details on the microelectrode recordings and the
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42 intervals of the depths are presented as supporting information.
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50 51 **Neural Datasets**

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3 We divided our neuronal database into two parts. Training dataset was composed of 58
4 trajectories (obtained from 30 PD patients) containing 2678 stable MERs recorded in the white
5 matter before the STN, STN dorsolateral oscillatory region (DLOR), STN ventromedial non-
6 oscillatory region (VMNR), white matter after STN and SNr. A subset of this dataset, containing
7 1720 MERs from the dorsal and ventral STN as well as SNr, was used for the support vector
8 machine (SVM) procedure. Training dataset of 58 trajectories was also used to find the optimal
9 parameters for the hidden Markov model (HMM). Seventy-three additional trajectories recorded
10 from 51 other patients, and yielding 4526 stable MERs (test dataset) were used solely to test the
11 robustness of the HMM detection.
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27 **Root Mean Square (RMS)**

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29 The RMS estimate was calculated from the multi-unit activity recorded by the microelectrode at
30 each electrode depth. RMS values are susceptible to electrode properties (e.g., electrode
31 impedance);¹² hence, the RMS was normalized by the pre-STN (white matter) baseline RMS,^{12,23}
32 creating what we term the normalized RMS (NRMS).
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41 **Power spectral density (PSD)**

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43 Visual inspection of the average STN and SNr power spectra revealed significant differences in
44 the 5-300 Hz domain. To identify the frequency band that contained the largest difference
45 between the STN and the SNr we divided the 5-300 Hz range of the power spectra into 10
46 approximately logarithmically spaced bands. For each band we calculated the mean power for
47 each MER, and then evaluated the difference in the mean power between the STN and the SNr.
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3 Using this method we identified which frequency bands had the largest difference between the
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5 STN and the SNr. Additional details are presented in the supporting information.
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10 **Support vector machine (SVM) discrimination of STN and SNr MERs**

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12 In machine learning, SVMs are supervised learning models that are specifically designed to solve
13 a classification problem offline, after all the data have been collected. For our SVM analysis,
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15 measurements in both time and frequency domains (based on the NRMS and power spectra of the
16
17 MERs) were used as features for the SVM classification. The classification procedure used the
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19 NRMS and the "100-150 Hz / 5-25 Hz Power Ratio" features, as well as their class label (STN or
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21 SNr) for each of the 1720 MERs in the training dataset. The performance of the SVM classifier
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23 was evaluated by 10-fold cross validation. Additional details are presented in the supporting
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25 information.
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34 The SVM requires labeling the MERs of each region, which is not amenable to real time use.
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36 Here we used the SVM to identify which features had the most information in terms of
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38 discriminating regions. However, once the optimal features had been selected, the SVM was no
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40 longer needed or used.
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46 **The Hidden Markov Model**

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48 The HMM takes the set of features extracted from the raw data as input, and provides the output
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50 clustering in real time. In previous reports,^{23,24} the HMM procedure was used to discriminate the
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52 STN from the white matter. This study goes beyond these previous works by designing a HMM
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3 procedure with improved ability to detect the STN-exit by delineating the borders between the
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5 STN-SNr (even for cases without a WM gap between the STN and the SNr). Details on the
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7 HMM are provided in the supporting information.
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12 All statistical analyses were performed using custom-made MATLAB 7.5 routines (Mathworks,
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14 Natick, MA). The statistics presented in this report, if not specified otherwise, are the mean \pm
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16 standard error of the mean (SEM); the criterion for statistical significance was set at $P < 0.05$ for
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18 all statistical tests.
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22 23 24 **RESULTS**

25 26 27 **Power Spectra features help to discriminate STN from SNr recordings**

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29 The NRMS values calculated from the MERs were very effective in detecting the STN border
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31 with the white matter. As presented in the three examples in Figure 2A, top panels, the STN-
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33 entry and STN-exit borders appear as a sharp increase and decrease in the NRMS,
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35 respectively.^{23,12} In these “easy” cases the electrode traversed the STN and entered the SNr after
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37 passing through the white matter. The power spectra of these SNr (Fig 2A bottom panels) depict
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39 a unique signature: blue vertical lines indicating a reduction in relative power at lower
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41 frequencies. However, some trajectories lacked a clearly defined STN-exit (e.g., Fig. 2B). These
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43 are the “hard” cases in which there is no clear transient reduction in the NRMS (NRMS gap),
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45 most probably because the electrode traversed the STN and entered the SNr without passing
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47 through the white matter after the STN. Though the SNr cannot be identified by the NRMS in
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49 these cases, the SNr was identified by the electrophysiologist and can be seen in the power
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3 spectra (Fig. 2B bottom) as depicted by the vertical blue lines. These examples suggest that
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5 power spectra characteristics can be used to assist in detection of the STN exit, especially for
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7 cases without a STN-WM transition and NRMS gap.
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12 To evaluate the ability of the NRMS to distinguish the STN from the SNr, we calculated the
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14 distribution of their NRMS values. Figure 3A shows the overlap in the NRMS distribution of 660
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16 MERs in STN DLOR, 990 MERs in the STN VMNR, and 155 MERs in the SNr (training
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18 dataset). The significant overlap between the different distributions suggests that there is no clear
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20 separation between the STN and the SNr using NRMS. In contrast, Fig 3B, illustrating the mean
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22 PSD of the STN and SNr recordings, suggests that features from the PSD could be used to
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24 discriminate STN from SNr. In line with the characteristic signature of the STN and SNr in the
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26 spectrograms (Fig 2), the average PSDs of the two STN domains and the SNr revealed different
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28 non-overlapping features. The mean SNr PSD (Fig. 3B, green trace) presented decreased activity
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30 in the 5-25 Hz band as compared to the mean PSD of the STN DLOR, and VMNR (Fig. 3B, red
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32 and blue traces). In addition, the mean PSD in the SNr displayed increased activity in the 85-300
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34 Hz band (Fig. 3B, green trace).
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44 To determine quantitatively which part of the power spectra enables the best discrimination of the
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46 STN from the SNr, we examined 10 (approximately logarithmically distributed) bands along the
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48 frequency axis in the power spectra. The mean power in two different frequency bands - high
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50 frequency (100-150 Hz) and low frequency (5-25 Hz) - provided the greatest discrimination
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52 between STN and SNr (discrimination matrix of 10 bands presented in the Supporting
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3 Information Table S1). We therefore calculated the ratio of the power of these two frequency
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5 bands and termed this new feature the “100-150 Hz / 5-25 Hz Power Ratio”. Figure 3C shows
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7 very little overlap in the distributions of STN and SNr power ratio values.
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10 11 12 **Support vector machine (SVM) analysis confirms the utility of the power ratio for STN-SNr** 13 14 **discrimination**

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17 An SVM classifier was used to examine the ability of the “100-150 Hz / 5-25 Hz Power Ratio” to
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19 provide a robust discrimination between the SNr and STN. Figure 4 shows the result of an SVM
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21 classifier that was trained and tested on 155 randomly selected samples from the STN and all 155
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23 samples from the SNr. A linear-kernel decision boundary was used to classify the training set as
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25 SNr (hollow square; green) or STN (hollow triangle; blue); then new data points were classified
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27 as SNr (solid square; green) or STN (solid triangle; blue). Yellow circles represent the support
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29 vectors defining the decision boundary between the STN and SNr samples. Figure 4 further
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31 demonstrates the absence of correlation between NRMS and the “100-150 Hz / 5-25 Hz Power
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33 Ratio”. Both of these characteristics reinforce the utility of the power ratio feature as an
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35 additional attribute for classifying MERs. The discrimination performance of the SVM classifier
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37 for the entire training dataset using the two features, NRMS and “100-150 Hz / 5-25 Hz Power
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39 Ratio” was evaluated by 10-fold cross validation and is presented as an error matrix in the
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41 Supporting Information Table S2. The overall classification accuracy rate was 97.6%.
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50 **Hidden Markov model (HMM) analysis enables reliable detection of STN exit**

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3 The HMM procedure uses MER features and trajectory history to enable real time decisions as to
4 electrode placement. The use of trajectory history in addition to the MER features enable the
5 HMM procedure to "neglect" recording glitches that a classification method (e.g., SVM) would
6 classify incorrectly. Our previous HMM procedures²³ did not include the SNr as a possible state
7 and did not use the high frequencies (100-150 Hz) of the power spectrum. Here we extended the
8 HMM procedure to discriminate between the STN and SNr using the "100-150 Hz / 5-25 Hz
9 Power Ratio" and NRMS features, together with the depth of the trajectory (i.e., estimated
10 distance to the target). The distribution of STN-exit borders was evaluated, and revealed that 77
11 out of 131 trajectories (59%) had STN-WM transitions, and 54 out of 131 trajectories (41%) had
12 STN-SNr transitions.
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29 Figure 5 presents three examples of a typical trajectory's NRMS and PSD as well as the "100-
30 150 Hz / 5-25 Hz Power Ratio" feature. At each depth along the trajectory during the implant
31 process the NRMS and power spectra features of the MERs are continually calculated and
32 updated. Based on these calculations a new assessment by the HMM is made automatically in
33 real time. An expert physiologist lowers the electrode along the trajectory until the red line
34 appears (i.e., as determined by the real time HMM analysis). This indicates that the STN ventral
35 border has been reached, followed by either the SNr or white matter. The three example
36 trajectories illustrate the direct transition from the STN to SNr. The red line in the top panel
37 illustrates the direct STN-SNr transition defined by the real time HMM analysis. It takes 99 ms in
38 real time to process a new trajectory and determine whether it is STN or not, as illustrated by the
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3 HMM running time in Fig. 5. The time to analyze each subsequent MER is less than a ms per
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6 MER, making this a practical method for use during DBS surgery.
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10 For each of the 58 trajectories in the training dataset, the HMM parameters (transition and
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12 emission matrices) were estimated from the other 57 trajectories (leave-one-out cross-validation).
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14 The resulting mean (of all 58 trajectories) HMM transition and emission matrices are presented in
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16 the Supporting Information Table S3.
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22 The performance of the HMM was assessed with two measures. The first is the mean OUT
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24 location error. It is defined as the difference between the *location (Human Expert's*
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26 *Classification)*, which is the location of the transition defined by the neurophysiologist, and
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28 *location(HMM)*, which is the HMM inferred location of the transition, both measured in mm of
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30 estimated distance to the target. The second measure is the OUT transition error which is defined
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32 as an OUT location error greater than 1 mm. Hits were the number of correctly detected OUT
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34 transitions. Misses were the number of OUT transitions (according to the human expert's
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36 decision) that the HMM procedure did not detect.
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43 The OUT location error for both STN-SNr and STN-WM demonstrated better mean and standard
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45 deviation than that found by previous methods.^{12,23} The performance of the OUT location error
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47 on the training dataset had an error of 0.1 ± 0.34 mm (mean \pm standard deviation) with 2 misses
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49 out of 58 trajectories (97% Hits).
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3 The HMM procedure has to deal with a heterogeneous variation of trajectories, as some
4 transitions are from VMNR STN to SNr and others from white matter before STN to SNr.
5 Because an automatic detection algorithm that can be used in the operating room needs to
6 function on novel data without being continually adjusted, it is important to demonstrate that the
7 HMM procedure can work with completely novel data. Therefore, 73 other trajectories (from 51
8 patients, all trajectories included both STN and SNr) were evaluated by the HMM procedure. The
9 HMM procedure identified the STN-exit with error of 0.04 ± 0.18 mm. Using the 1 mm
10 threshold, the OUT transition error of the novel dataset committed 4 misses out of 73 trajectories
11 (94% Hits), which is better than that found when applying the previous HMM procedure²³ and
12 Bayesian method¹² (12 misses out of 73 trajectories, 83% hits, and error = 0.50 ± 0.59 mm,
13 respectively). The performance of the new HMM procedure was shown to be robust to the
14 specified threshold because threshold values of 0.5 mm and 0.15 mm produced similar
15 quantitative results (4 and 7 misses out of 73 trajectories, respectively).
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36 DISCUSSION

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38 We described a computational machine-learning procedure with a new feature; namely, the ratio
39 of high frequency (100-150 Hz) power to low frequency (5-25 Hz) power, which enables high
40 accuracy discrimination of the STN from SNr. We used a SVM procedure to verify that the “100-
41 150 Hz / 5-25 Hz Power Ratio” is a reliable feature for discriminating the STN and SNr
42 populations. Then, we utilized an HMM procedure using the MER features, together with the
43 trajectory history to detect the STN exit either to the white matter (WM) or SNr.
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6 The MERs along pre-planned trajectories are commonly used to confirm the STN territory during
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8 DBS surgery for Parkinson's disease; however, there is a lack of consensus on whether the MER
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10 allows for reliable separation between the STN exit point and the SNr entry point. Across the
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12 ventral region of the STN there are fewer kinesthetic neurons,²² and the STN VMNR neurons are
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14 characterized by consistently reduced β band and increased gamma (30-100 Hz) activity.¹³
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16 Similarly, the discharge pattern of the neurons in the SNr (below the STN target) lack the β band
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18 and tremor frequency oscillations, but have increased gamma activity.¹⁴⁻¹⁸ In addition, islands of
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20 cells have been observed with firing characteristics of both SNr and STN cells.²² Therefore, the
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22 electrophysiological determination of the transition from the STN to SNr is ambiguous and
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24 difficult to evaluate.
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32 Several studies have developed automatic detection and visualization not only for the STN, but
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34 also the SNr based on objective and quantitative MER features.^{12,20,22,25-27} Some of these studies
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36 have used features that require spike detection algorithms to identify the firing pattern.²⁵⁻²⁷ While
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38 these features may aid in detecting the STN ventral border near the SNr, it is still computationally
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40 challenging to calculate neuronal spike characteristics in a real-time intra-operative scenario.¹²
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42 Moreover, the ideal isolation of single units requires 5-10 microns steps of electrodes and is very
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44 time-consuming. In contrast, NRMS values that are based on unsorted multi-unit activity are easy
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46 to measure. The STN-entry and STN-exit often manifest as a sharp increase and decrease in the
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48 NRMS, respectively.^{23,12} Some studies have used NRMS together with spectral features of the
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50 analog signal, which are computationally efficient to calculate.^{20,22,27} However, these spectral
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3 features do not lead to reliable or robust identification of the transition between the STN and the
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5 SNr. Here, we divided the 5-300 Hz range power spectra into frequency bands. This division
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7 allowed us to determine which frequency bands contained the largest difference between the STN
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9 and the SNr, and to accurately detect the STN ventral border.
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15 When implementing the NRMS and features from the power spectra, there are several ways to
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17 differentiate the STN from the SNr using automatic detection methods. Some studies have
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19 proposed rule-based detection methods,^{22,27} however, they are unable to detect the direct STN-
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21 SNr transitions. For example, despite the fact that Cagnan et al.²⁷ used the power spectra of
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23 tremor, and the alpha band (3–12 Hz), beta band (13–30 Hz) and gamma band (31–100 Hz) as
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25 features, their algorithm still required a white matter gap in the trajectory between the STN and
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27 the SNr to detect the SNr. Furthermore, rule-based detection systems tend to be overly complex
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29 and may not generalize to other surgical centers. Other studies^{12,23,25} have used machine learning
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31 techniques to automatically extract the “rules” or decision boundaries to discriminate between
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33 the STN and the SNr. These machine learning procedures are either unsupervised, and involve
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35 extracting patterns using unlabeled training data (that still require labeling of the output),²⁵ or
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37 supervised, that require the labeling of the electrophysiological signals used for training.^{12,23} For
38
39 example, Wong et al.²⁵ used a clustering algorithm (unsupervised machine learning) that returns a
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41 pre-specified number of clusters, but then requires the human observer to label the clusters. The
42
43 main drawback of these techniques is that they do not take the previous location of the MERs
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45 into account when determining the electrode's current location. A supervised technique that uses
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47 the electrode's location is HMM. For example, Zaidel et al.²³ combined the power spectra of beta
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3 band features and NRMS to locate the STN and its sub-territories. The two advantages of the
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5 HMM procedure are the short recording time needed for location analysis and low computational
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7 cost. Our approach goes beyond this previous work by delineating the borders between the STN-
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9 SNr which thus enable intra-operative application with greater accuracy.
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15 Accurate discrimination between the STN and the SNr is of crucial importance for achieving
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17 optimal therapeutic benefits while avoiding psychiatric complications for PD DBS procedures.
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19 The beneficial effects of bilateral STN DBS on motor symptoms and quality of life have been
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21 repeatedly confirmed in patients with advanced PD;²⁸ however, psychiatric complications
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23 induced by STN DBS have also been reported.^{29,30} In some patients with PD with impulse control
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25 disorders, their abnormal behavior may be provoked by stimulation with a ventral contact of the
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27 DBS lead, and suppressed by switching off this contact.⁶⁻⁹ It also has been reported that
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29 manic^{31,32} and depressive⁵ symptoms are induced by stimulation of active contacts located in the
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31 SNr. On the other hand, the SNr is thought to be particularly involved in balance control during
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33 gait.³³ The combined stimulation of the SNr and the STN has been reported to improve axial
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35 symptoms (including freezing of gait, balance, and posture) compared to standard STN
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37 stimulation.^{10,11} In summary, automatic and reliable localization of the direct STN-SNr transition
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39 and STN lower border detection could lead to improved localization of DBS leads and better
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41 DBS clinical outcomes. It takes 99 ms in real time to process a new trajectory and decide whether
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43 it is STN or not, making this a practical method for use during DBS surgery. This analysis tool
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45 can be easily learned and employed in the DBS operating room. Future studies might incorporate
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3 MER data from multiple centers to test the applicability of these algorithms for automatic
4 navigation in DBS surgery.
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10 **Authors' role:** 1)Research project: A. Conception, B. Organization, C. Execution; 2)Statistical
11 Analysis: A. Design, B. Execution, C. Review and Critique; 3)Manuscript Preparation: A.
12 Writing of the first draft, B. Review and Critique;
13
14

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17 D.V.: 1A, 1B, 1C, 2A, 2B, 2C, 3A, 3B
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19 H.B.:1A, 1B, 2C, 3B
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21 O.M.: 2C, 3B
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24 R.E.: 1B, 3B
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26 M.D.: 3B
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28 K.B.: 1B, 2C, 3B
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31 Z.I.: 1A, 1B, 3B
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37

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Supporting Data

Additional Supporting Information may be found in the online version of this article on the publisher's website.

For Peer Review

SUPPORTING INFORMATION

Microelectrode recordings

The microelectrode recording data were acquired with the MicroGuide system (AlphaOmega Engineering, Nazareth, Israel). The signal was amplified by 10,000, band-passed filtered from 250 to 6,000 Hz using a hardware four-pole Butterworth filter, and sampled at 48 kHz by a 12-bit A/D converter (using ± 5 V input range).

A typical trajectory was $\sim 60^\circ$ from the axial anterior commissure-posterior commissure (AC-PC) plane and $\sim 15^\circ$ from the mid-sagittal plane. The trajectory was further adjusted for each patient to avoid the cortical sulci, the ventricles and major blood vessels.¹ The electrodes were advanced in small discrete steps toward the estimated target. Step size (ranging from 400 μm to 100 μm in our recordings) was controlled by the neurophysiologist to achieve optimal identification of the upper and lower borders of the STN. Typically, shorter steps (~ 100 μm) were used when the electrode was advanced closer to and inside the presumed location of the STN.

We did not attempt to isolate single units during the physiological mapping and our analysis below was conducted on the unsorted analog 250-6000Hz band-passed filtered data (multi-unit activity). Each segment along the trajectory (multi-unit traces) was recorded for at least 4 seconds, 0.5 seconds after electrode movement. A few segments were recorded for longer periods of time than others because responses to active and passive limb movement were tested (time ranged from 4 to 90 seconds). Each multi-unit signal was subjected to stability analysis using a custom-made algorithm.² Stability analysis divided each data trace into consecutive segments of 50 ms and computed the RMS for each segment. A section of the trace was considered stable when the RMS values of all corresponding segments lay within one standard deviation of the mean RMS. The longest stable section of the data trace was then selected for further analysis, and the rest of the trace was discarded. All stable sections included in the analysis were longer than 1.5 seconds.

Power spectral density (PSD)

The PSD was calculated from the mean-subtracted absolute value of the analog signal.^{3,4} This absolute procedure was needed to expose the frequency band of interest (below 250 Hz) since the original analog data were band-pass filtered at 250-6000 Hz (the 250 Hz cut off was used because of operating room constraints). The average power spectral density was calculated for each trace using Welch's method, with a 3 second Hamming window (50% overlap) and a spectral resolution of 1/3 Hz (sampling frequency 48 kHz, number of discrete Fourier transform points = 144,000). Values within 2 Hz of the 50 Hz power supply artifacts and their 100 and 150 Hz harmonics were removed and interpolated from the surrounding values. To normalize the PSD we divided the PSD by the total power of the signal from 0 to 24 KHz (excluding PSD values within 2 Hz of the 50 Hz power supply artifacts and their 100 and 150Hz harmonics) creating a relative PSD.² This normalization revealed the relative power across frequencies.

Discrimination matrix of the STN-SNr

Table S1: The frequency dependence of the STN-SNr discrimination matrix.

Discrimination matrix		Width of each band [Hz]			
		10 Hz	20 Hz	50 Hz	100 Hz
Starting Index [Hz]	5 Hz	4.28	5.30	1.71	0.04
	50 Hz	NA	2.62	2.02	2.41
	100 Hz	NA	NA	15.55	4.13
	200 Hz	NA	NA	NA	1.99

Values depict the discrimination between STN and SNr of 10 approximately logarithmically spaced bands along the 5-300 Hz range of the power spectra. The band starts at the starting index and has the specified width (e.g., top left box is the 5-15 Hz band). The starting index of the band width was simultaneously increased (e.g., for a starting index = 200 Hz, we only tested a width of 100 Hz, 200-300 Hz band). For each band the mean power (V^2/Hz) for each MER was calculated. Then, for each band the absolute value of the difference in the mean power between the STN and the SNr was obtained. Finally, the results were normalized by the square root of the sum of the variances of the STN and the SNr to yield the discrimination index (V^2/Hz). Maximal STN-SNr discrimination was obtained in two different

frequency bands: high frequency (100-150 Hz) with a value of 15.55, and low frequency (5-25 Hz) with a value of 5.3.

Support vector machine discrimination performance

An SVM is a classification method that finds the linear boundary that maximizes the separation between two classes. A linear SVM with a linear-kernel algorithm^{5,6} was used to provide high-performance discrimination between the STN and SNr populations. The SVM linear boundary is calculated solely from those MERs that lie close to the interface between the two groups of interest (the support vectors, see figure 4).

The performance of the SVM classifier was evaluated by 10-fold cross validation. First, the MERs from the entire training dataset were divided randomly into training (90% of the MERs) and test sub-sets (10% of the MERs). The model was trained by finding the optimal separating boundary based on the features from the training MERs. Then, the SVM was used to predict the class labels of the test sub-set and the predictions were compared with the known values to assess accuracy.⁷ This procedure was repeated 10 times, using different and non-overlapping 10% of the MERs for testing in each repetition, and the remaining 90% of the MERs for training on that repetition. The 10 results were averaged to produce the performance estimation.

Table S2: SVM discrimination performance

		Human Expert's Classification		Total
		STN	SNr	
SVM Output	STN	TP = 1528 88.83%	FP = 4 0.23%	1532
	SNr	FN = 37 2.15%	TN = 151 8.77%	188
Total		1565	155	n=1720

The discrimination performance of the SVM classifier for the training dataset. The NRMS and “100-150 Hz / 5-25 Hz Power Ratio” were evaluated by the 10-fold

cross validation method and are presented as an error matrix. TP, true positive; TN, true negative; FN, false negative; FP, false positive.

The Hidden Markov Model

An HMM procedure was used to estimate the state of the electrode at each depth along the trajectory. The input data to the HMM procedure were made up of a sequence of single values based on the features of the MER. The features that we used were NRMS, beta power (13–30 Hz) from the PSD,⁸ and the "100-150 Hz / 5-25 Hz Power Ratio" implemented in the SVM. To assess accuracy, the HMM predictions were compared to the electrophysiologist's determination of the location of the STN ventral border (STN exit).

For the HMM procedure, a trajectory is a sequence of states, and at any depth along the trajectory the electrode exists in one of a finite set of states (functionally discrete state model, presented in Figure 1C).

1. White matter before STN
2. Dorso lateral oscillatory region (DLOR) STN
3. Ventral medial non oscillatory region (VMNR) STN
4. STN exit
 - a. White matter between STN and SNr
 - b. or SNr

A typical trajectory state sequence proceeds through the first three states consecutively and then to the white matter between the STN and SNr (solid line in Figure 1C). However, not all trajectories have clearly defined STN-WM transitions; hence, a trajectory may enter the SNr immediately after the STN (dotted line). In addition, a trajectory can start in the white matter and enter the VMNR or go directly into the SNr (dashed lines) without passing through the STN.

In the HMM, transitions between states take place according to (1) a fixed probability (i.e., transition matrix and emission matrix) depending solely on the state of the electrode at the depth immediately preceding the current state and (2) a probability value calculated from the current MER. Note that we used a feed-

forward HMM procedure; i.e., as a sequence progresses, it is possible to remain in the same state, but it is not possible to return to a previous state (e.g., from the SNr to the STN state).

Table S3: The HMM transition and emission matrices.

A

Transition matrix		To			
		State-1	State-2	State-3	State-4
From	State-1	0.9510	0.0280	0.0103	0.0107
	State-2	0	0.9601	0.0397	0.0002
	State-3	0	0	0.9617	0.0383
	State-4	0	0	0	1.0000

B

Emission matrix		Observations						
		Low-NRMS	Intermediate-NRMS	high-NRMS				High to Low Power Ratio
				High mean beta		Low mean beta		
				High max beta	Low max beta	High max beta	Low max beta	
State	State-1	0.8685	0.0261	0.0348	0.0044	0.0039	0.0254	0.0365
	State-2	0.3056	0.0263	0.3786	0.0434	0.0336	0.1755	0.0367
	State-3	0.3167	0.0534	0.0769	0.0239	0.0780	0.3694	0.0814
	State-4	0.5382	0.1881	0.0130	0.0012	0.0207	0.1054	0.1330

(A) The HMM transition matrix. Values depict the probability of transition between states (or remaining in the current state) for each step in the sequence. The states are defined as follows: 1 – WM before the STN; 2 – in the dorsolateral oscillatory region (DLOR) of the STN; 3 – in the ventro medial non-oscillatory (VMNR) of the STN; 4 – STN exit (STN-SNr or STN-WM). (B) The HMM emission matrix. Values depict the probability of each observation given the state. The states are defined as in A. The seven columns correspond to the seven observations detailed in the table header as follows:

- All MERs with NRMS < 1.25 (threshold 1); i.e., below a 25% increase from the NRMS baseline (which is equal to 1 due to the normalization) were clustered together (Low-NRMS observation).

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- The mean deviation from threshold 1 (i.e. NRMS - 1.25) of the remaining MERs was calculated. Threshold 2 was defined as threshold 1 plus 25% of the calculated mean deviation. MERs with a NRMS between threshold 1 and threshold 2 were clustered together (Intermediate-NRMS observation), and MERs with NRMS > threshold 2 were further divided according to their (maximum and mean) beta (13–30 Hz) oscillatory activity (above or below the median), resulting in four more (high-NRMS) observations.
- A high to low power ratio observation was calculated for all the MERs and was independent of the NRMS observations.

Table S4: Patient characteristics

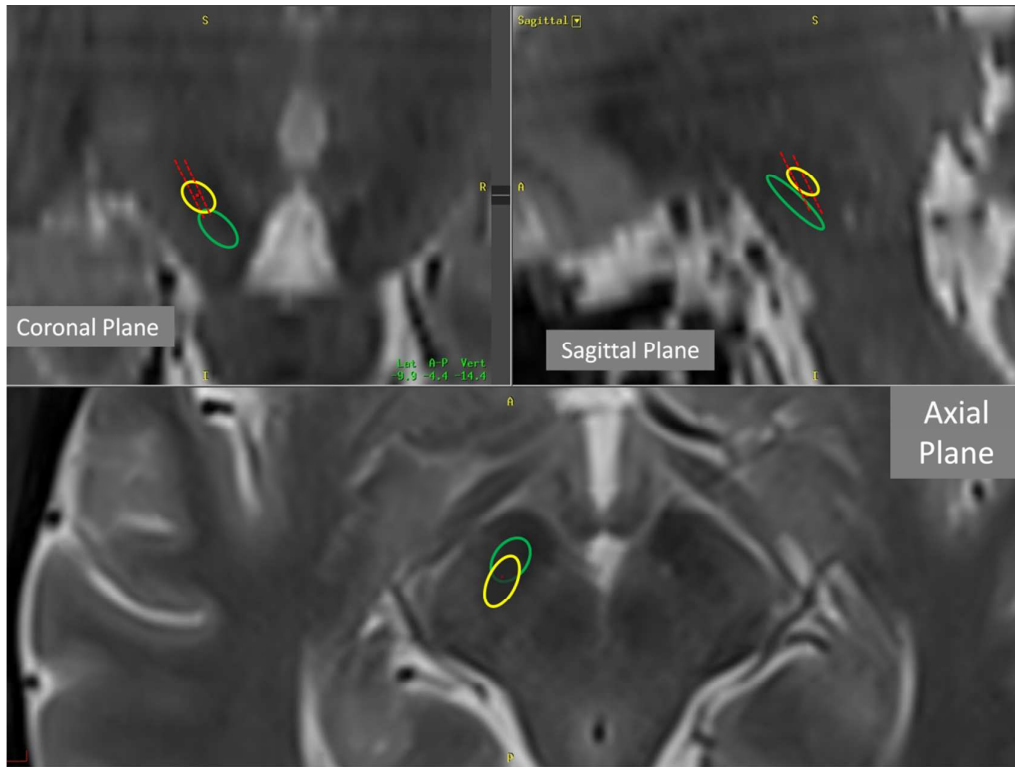
Patient No.	Sex	Age (years)	Disease duration (years)	Pre-operative		
				UPDRS 3 (OFF)	UPDRS 3 (On)	LED
1	m	69	8	55	13	1500
2	f	61	6	64	32	N/A
3	m	66	5	51	22	750
4	f	67	5	53	29	1000
5	m	67	26	55	24	550
6	m	59	8	48	13	570
7	m	52	7	38	12	540
8	m	64	8	41	6	825
9	m	60	5	39	15	1580
10	m	42	25	77	18	500
11	m	60	7	85	30	870
12	m	75	4	39	28	562.5
13	m	69	7	45	17	750
14	f	74	13	33	10	830
15	m	63	6	59	18	810
16	m	65	8	48	12	750
17	f	67	15	35	11	1147.5
18	m	59	8	36	10	900
19	f	57	8	48	19	680
20	m	53	3	49	6	200
21	m	64	4	56	34	850
22	m	74	16	57	31	750
23	f	71	22	51	35	2000
24	f	66	4	46	16	750
25	m	50	10	47	35	93.7
26	m	64	9	69	48	900
27	m	62	30	56	22	1120
28	m	66	10	63	11	600
29	m	61	7	32	7	750
30	f	59	13	75	19	1000
31	m	54	9	75	41	500
32	m	64	12	35	2	875
33	m	50	20	53	39	N/A
34	f	73	5	73	42	1250
35	m	57	7	78	37	1370
36	m	69	8	50	10	1140
37	m	66	9	34	14	1000
38	m	58	10	47	13	N/A
39	m	58	12	47	11	1120
40	f	62	14	37	9	1000
41	m	76	7	32	19	1120
42	f	62	13	32	6	925
43	m	70	10	N/A	N/A	950
44	f	59	10	50	14	455
45	f	61	10	N/A	N/A	1000
46	m	66	10	68	27	1250
47	m	73	20	60	16	1496
48	m	60	8	46	21	500
49	f	64	9	21	4	917.5
50	m	54	5	86	42	500
51	m	59	4	64	26	1000
52	f	60	8	44	12	975
53	m	78	10	N/A	N/A	2075
54	m	62	17	72	22	1550
55	f	70	13	41	13	400
56	f	69	9	33	6	1875
57	m	53	9	41	10	375
58	m	72	12	N/A	N/A	1125
59	f	50	8	N/A	N/A	550
60	f	45	9	82	55	700
61	m	59	9	42	14	150
62	m	62	12	55	19	1005
63	m	62	4	63	17	1080
64	m	52	8	27	3	510
65	f	52	10	35	9	770
66	f	66	15	48	13	1540
67	m	49	13	63	18	660
68	f	48	18	47	20	300
69	m	60	11	56	14	850
70	f	39	10	47	16	512.5
71	m	61	11	44	10	500
72	f	50	25	50	17	400
73	f	72	7	60	24	100
74	f	51	4	20	7	N/A
75	m	73	8	55	27	562.5
76	m	66	6	75	38	450
77	f	73	10	45	18	1750
78	f	62	20	56	9	517.5
79	m	74	6	61	31	750
80	f	67	8	48	3	250
81	m	72	6	42	33	640
sum/ mean ± SD	52 m 29 f	62.1 ± 8.3	10.3 ± 5.5	51.1 ± 14.8	19.4 ± 11.51	849.6 ± 425

N/A : Not Available

UPDRS 3 (OFF/ON medication) : clinician-scored motor evaluation (range 0–108)

LED : Levopoda Equivalent Dose

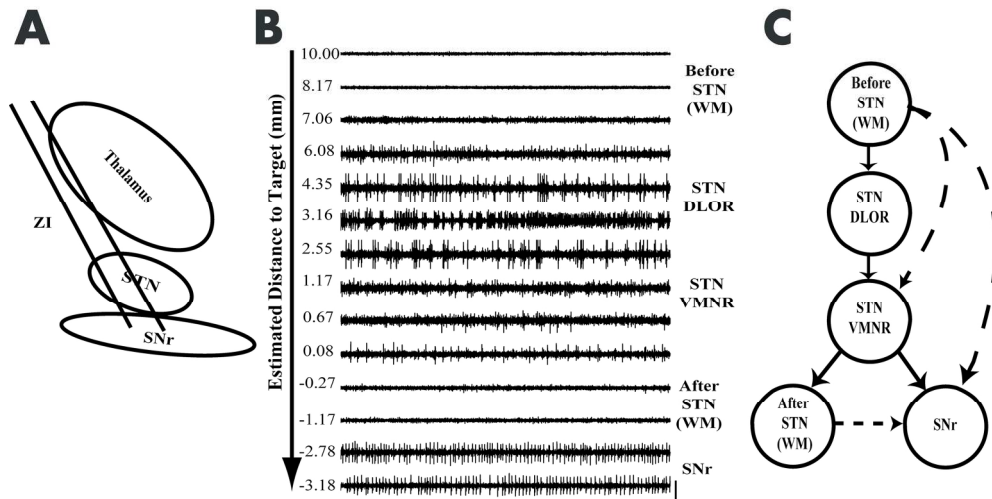
MRI image that shows typical anatomical targeting



T2 weighted Axial MR image 6mm below the ACPC plane with coronal and sagittal reconstructions. The STN is shown approximately outlined in yellow, the SNr is shown approximately outlined in green. The dotted red lines represent possible examples of MER tracks that traverse the STN and may enter the SNR. Although the target is the dorsolateral part of the STN, we aim to have as long a trajectory as possible traversing the STN through the target point.

References

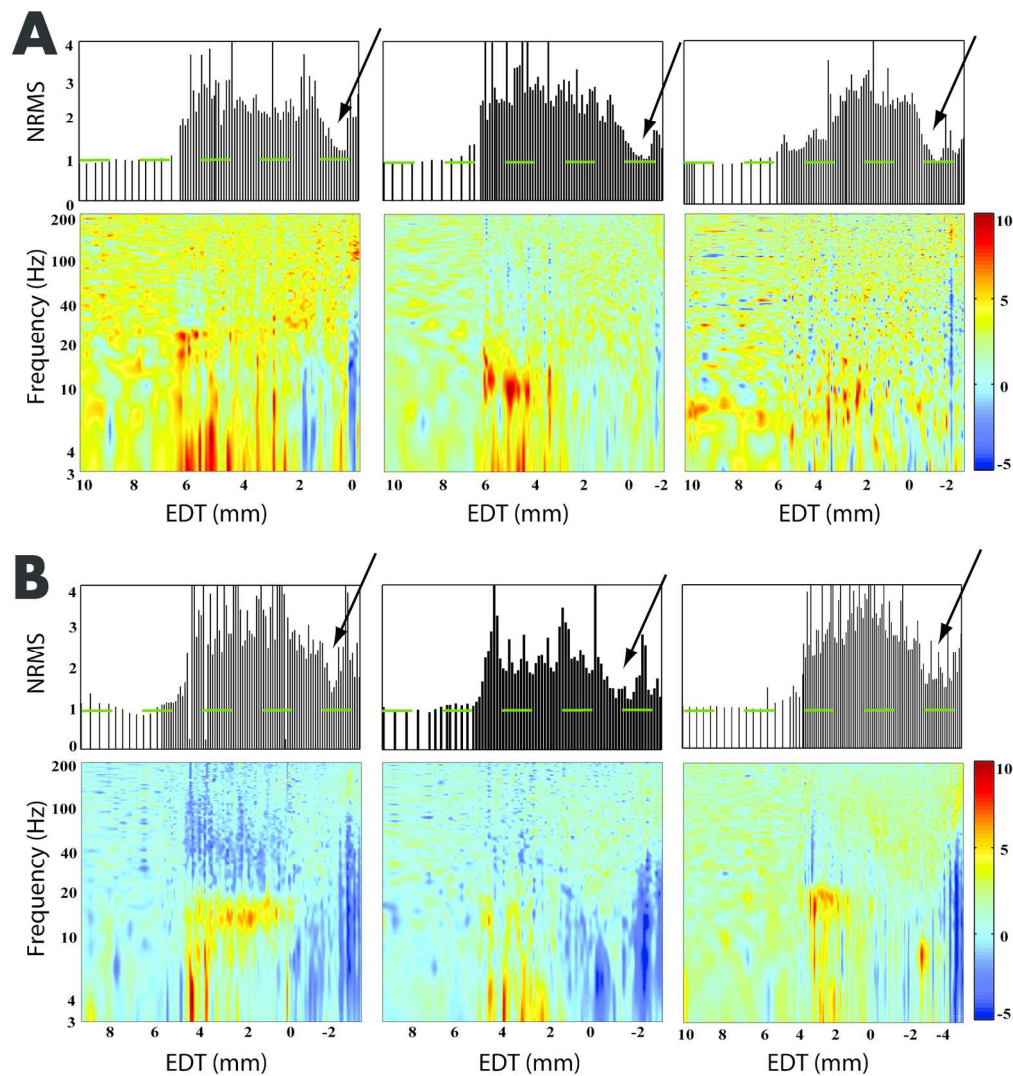
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Overview of STN targeting. (A) Schematic diagram of a typical trajectory of two parallel microelectrodes showing subcortical structures. STN-Subthalamic nucleus, SNr- Substantia nigra reticulata, ZI – zona incerta (B) One-second example of 14 representative raw signal traces (in descending order) out of the 82 recorded signal traces at various depths along the trajectory (a single DBS track) from a Parkinson's disease patient. The signal at each position was recorded for at least 4 seconds. The segment at 2.55 mm estimated distance to target (EDT) was recorded for a longer period of time than the others because responses to active and passive limb movements are tested. The traces indicate regions of internal capsule (white matter), dorsolateral oscillatory region (DLOR) STN, ventral medial non oscillatory region (VMNR) STN, white matter between STN and substantia nigra pars reticulata (SNr); vertical bar indicates 256 μ v, horizontal bar indicates 100 ms. (C) Functional state model represents the anatomy which is sequentially encountered during microelectrode recording of the STN detection. At all depths along the trajectory the electrode is in one of a finite set of states. Arrows between the states represent the possible state transitions. Solid lines depict a typical trajectory state sequence that proceeds through the first three states consecutively and then to the white matter between the STN and SNr. Dotted lines depict: 1) a trajectory that enters the SNr immediately after the STN, 2) a trajectory that starts in the white matter and enters the VMNR, 3) one that goes directly into the SNr without passing through the STN.

Figure 1

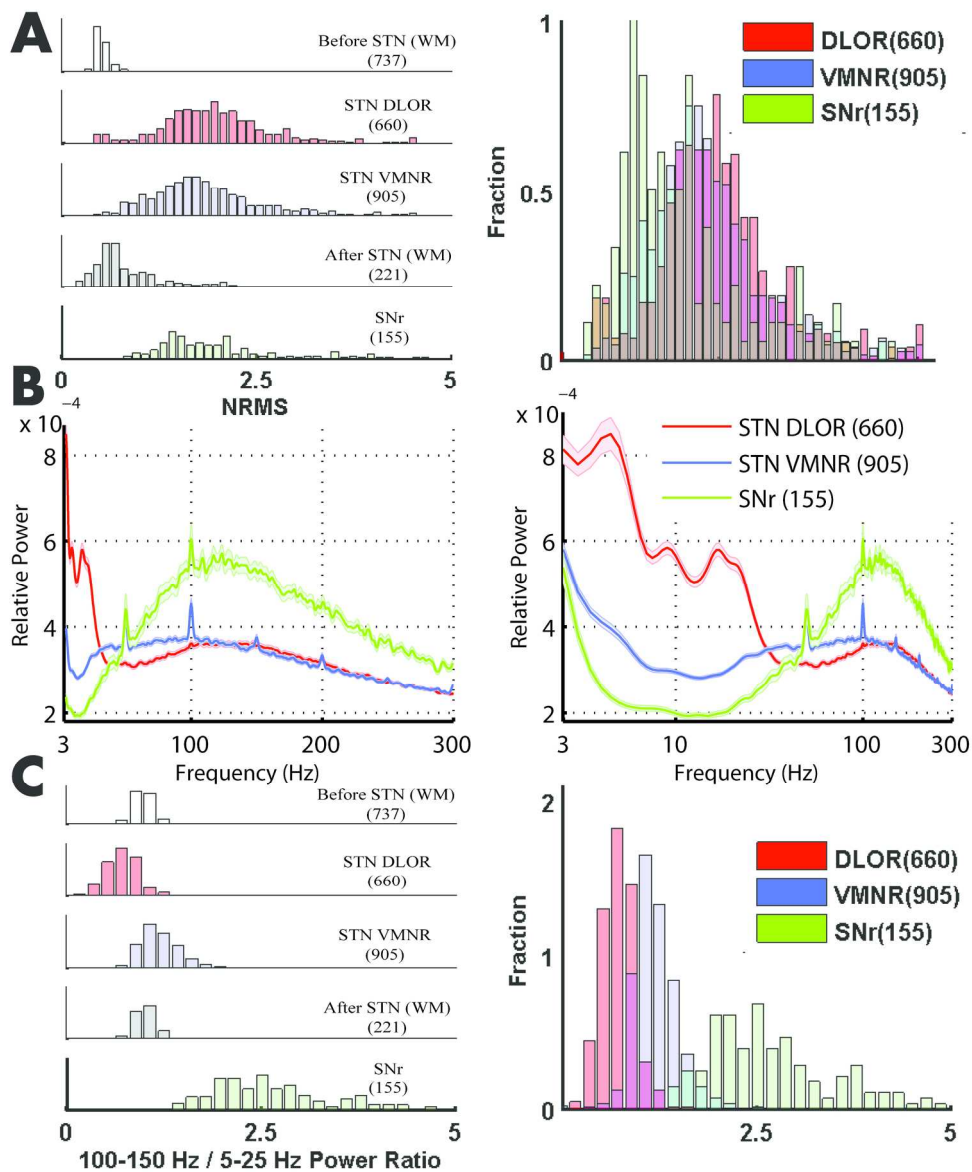
89x44mm (600 x 600 DPI)



STN-white matter transition versus STN-SNr transition. (A) Clearly defined STN-WM transition in three example trajectories (from three patients). The top three graphs represent the normalized root mean square (NRMS) analysis as a function of EDT. The bottom three graphs represent the power spectral distribution (PSD) spectrogram of the data, in relation to EDT on the x-axis. The arrow on each trajectory points to the transition between the STN and the WM (determined by an expert neurophysiologist). The green dashed lines represent the baseline of the NRMS (i.e., WM). (B) The same as in A, but for the STN-SNr transition. The power spectral density color-scale represents $10 \log_{10}(\text{power spectral density} / \text{average power spectral density})$. The arrow on each trajectory points to the transition between the STN and the SNr (determined by an expert neurophysiologist). EDT = estimated distance to target (defined as the dorsolateral STN target according to preoperative imaging).

Figure 2

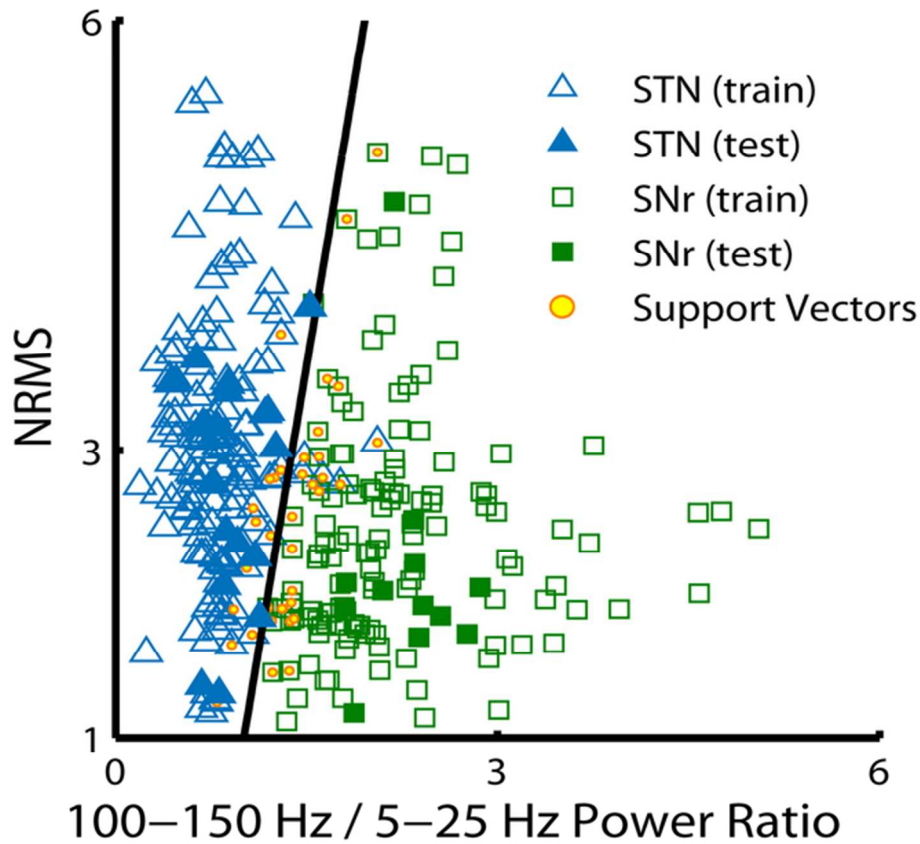
165x192mm (300 x 300 DPI)



“100-150 Hz / 5-25 Hz Power Ratio” separates STN from SNr better than NRMS. (A) The left hand figure illustrates the NRMS distribution for dorsal STN (red), ventral STN (blue), SNr (green), white matter before STN (white), white matter after STN (gray). Right hand figure same as left, but three subcortical structures are superimposed on the x-axis, and show the overlap in NRMS distribution of the STN and the SNr. (B) The left hand figure illustrates the power spectral density as a function of the frequency, with a linear scale plot in the DLOR STN (red), VMNR STN (blue), SNr (green). The right hand figure is the same as left, but with a logarithmic scale plot of the x-axis. The shaded regions mark SEMs. (C) The left hand figure illustrates “100-150 Hz / 5-25 Hz Power Ratio” distribution in five regions. Right figure same as left, but has the three subcortical structures superimposed on the x-axes.

Figure 3

181x215mm (300 x 300 DPI)

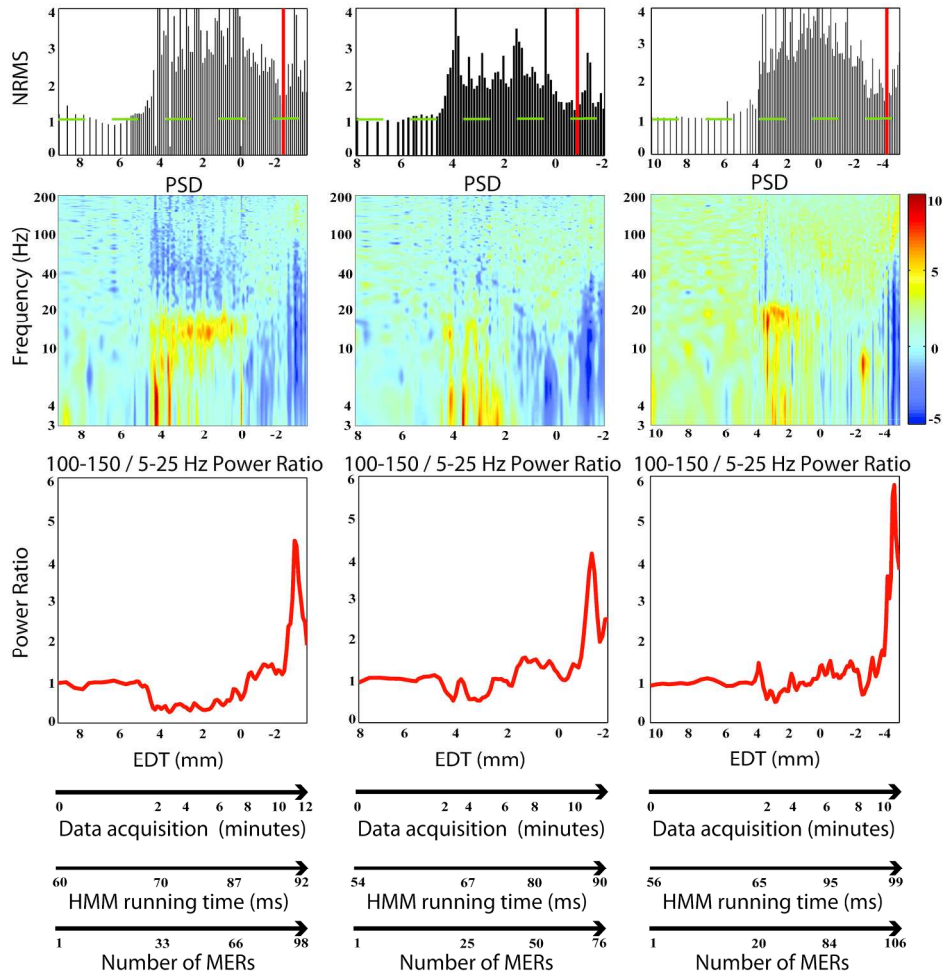


A linear support vector machine classifier provides high performance discrimination between the STN and SNr populations. A support vector machine (SVM) classifier was trained and tested on 155 randomly selected samples from the STN and all 155 samples from the SNr, using NRMS and the "100-150 Hz / 5-25 Hz Power Ratio" features. The linear-kernel decision boundary is used to classify the trained data for the SNr (hollow square; green) and the STN (hollow triangle; blue); then new data points are classified as SNr (solid square; green) or STN (solid triangle; blue). Yellow circles (within the hollow squares and triangles) represent the support vectors defining the decision boundary between the STN and SNr samples.

Figure 4

61x55mm (300 x 300 DPI)

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Robust detection of the STN-SNr transition by the “100-150 Hz / 5-25 Hz Power Ratio” feature. Top and middle panels illustrate a typical trajectory’s NRMS and PSD, respectively. Bottom panel represents the “100-150 Hz / 5-25 Hz Power Ratio” feature as a function of the estimated distance to target (EDT). The three sample trajectories illustrate the direct transition from the STN to SNr. The red line in the top panel illustrates the STN-SNr transition defined by the real time HMM analysis. The dashed green lines represent the baseline of the NRMS (i.e., WM). Each segment along the trajectory was recorded for at least 4 seconds, except for a few segments where responses to active and passive limb movements were tested. The data acquisition arrow marks the real duration of a single track of the example trajectories as a function of EDT.

The total recording time of a single DBS track of the example trajectories from the left to the right column: 992 seconds, 622 seconds and 608 seconds. The HMM running time arrow shows the duration of the HMM processing as a function of the number of MERs (lower arrow). MERs = micro-electrode recordings.

Figure 5
190x244mm (300 x 300 DPI)

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For Peer Review

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3 **Stop! Border Ahead: Automatic detection of subthalamic exit during deep brain**
4 **stimulation surgery**
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1
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5 microelectrode recording;
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For Peer Review

Abstract

Background: Microelectrode recordings along pre-planned trajectories are often used for accurate definition of the subthalamic nucleus (STN) borders during deep brain stimulation (DBS) surgery for Parkinson's disease. Usually, the demarcation of the STN borders is detected manually by a neurophysiologist. The exact detection of the borders is difficult and especially detecting the transition between the STN and the substantia nigra pars reticulata. Consequently, demarcation may be inaccurate, leading to sub-optimal location of the DBS lead and inadequate clinical outcomes.

Methods: We present machine learning classification procedures that utilize microelectrode recordings power spectra and allow for real time, high accuracy discrimination between STN and substantia nigra pars reticulata.

Results: A support vector machine procedure was tested on microelectrode recordings from 58 trajectories that included both STN and substantia nigra pars reticulata that achieved a 97.6% consistency with human expert classification (evaluated by 10-fold cross validation). We used the same dataset as a training set to find the optimal parameters for a hidden Markov model using both microelectrode recordings features and trajectory history to enable a real-time classification of the ventral STN border (STN exit). Seventy-three additional trajectories were used to test the reliability of the learned statistical model in identifying the exit from the STN. The hidden Markov model procedure identified the STN exit with an error of 0.04 ± 0.18 mm and detection reliability (error < 1 mm) of 94%.

Conclusion: The results indicate that robust, accurate and automatic real-time electrophysiological detection of the ventral STN border is feasible.

INTRODUCTION

Surgical treatment for advanced Parkinson's disease (PD) includes high-frequency deep brain stimulation (DBS) of the subthalamic nucleus (STN), which has proven to be surgically safe and beneficial over time.¹⁻⁴ In some patients, mood disorders such as depression⁵ or manic symptoms⁶⁻¹¹ may be observed after stimulation **as a result of** suboptimally placed DBS leads. **By contrast**, the combined stimulation of the substantia nigra pars reticulata (SNr) and STN may improve freezing of gait in patients with advanced PD.^{10,11} Therefore, accurate **differentiation of the STN from the** SNr is essential for achieving optimal therapeutic benefit while avoiding psychiatric complications.

Microelectrode recordings (MERs) along pre-planned trajectories are often used for improved delineation of the location **of the STN** during DBS surgery for Parkinson's disease. The detection of the *dorsolateral* region of the STN is **based on clear-cut changes** in electrical activity **in the form of** a sharp rise in the total power of the MER (as measured by the root mean square, RMS),¹² **the tremor-frequency, and the** β -oscillatory activity (13–30 Hz).¹³ In contrast, several factors can make electrophysiological determination of the *ventral* STN border more difficult, **and in particular** an uninterrupted STN-SNr transition **because in this case** there is no drop in activity (or RMS). **In addition**, the cells in the STN ventral domain have firing characteristics (reduced β band and tremor frequency oscillations) resembling SNr cells.¹⁴⁻¹⁸ Finally, electrophysiological determination of the STN exit can be challenging because white matter gaps in the STN may lead to **erroneous** early detection of STN exit.¹² Therefore, the

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3 electrophysiological determination of the STN ventral border can be ambiguous and occasionally
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5 difficult to define.
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10 Although recent imaging studies have been able to improve the **differentiation** between the STN
11 and the SNr,¹⁹ electrophysiology is still necessary to **identify** and verify the STN-SNr transition
12 intraoperatively. To facilitate detection of the transition, **this article describes a new** automatic,
13 reliable procedure for locating the STN exit. **Earlier** automatic methods **that use** RMS values^{12,20–}
14 ²³ are successful in **identifying** STN-white matter (STN-WM) transitions, but are not as good for
15 the **direct** STN-SNr transition. To improve the STN-SNr transition and STN lower border
16 detection, we **developed** a computational analysis procedure that **capitalizes on** several features
17 from the power spectra of the MER and allows for high accuracy discrimination between the
18 STN and the SNr.
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34 PATIENTS AND METHODS

37 Patients and Surgery

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40 MERs were analyzed from 131 microelectrode trajectories that passed through both the STN and
41 SNr of 81 Parkinson's disease patients undergoing bilateral STN DBS implantation. The patients'
42 demography and clinical state were as follows: mean age (62.1 years), mean disease duration
43 (10.3 years), 36% female, **mean unified Parkinson's disease rating scale - part III (UPDRS III)**
44 **score OFF/ON therapy before surgery (51.1/19.4)**, and mean levodopa equivalent dosage
45 (LED) before surgery (849.6 mg/day). **Patient demographic information appears in Supporting**
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3 **Information Table S4.** This study was authorized and approved by the Institutional Review Board
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5 of Hadassah Hospital in accordance with the Helsinki Declaration (reference code: HMO-0064-
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7 12). All patients were awake during surgery. Further details on the surgical procedure and data
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9 acquisition **can be found** in our previous reports.^{12,23}
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14 **Microelectrode recordings**

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17 For both the left and right hemispheres, one or two parallel microelectrodes were inserted and the
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19 recording started 10 mm above the calculated target. Our trajectories followed a double-oblique
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21 approach towards the **dorsolateral** STN target. In most cases, two microelectrodes were used (Fig.
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23 1A): a ‘central’ electrode was directed at the **center** of the dorsolateral STN target (as per
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25 imaging) and often traversed STN and entered SNr without passing through the white matter. An
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27 ‘anterior’ electrode was advanced 2 mm anterior to the central electrode (in the parasagittal
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29 plane) and therefore crossed STN-SNr area in a more ventral plane. In contrast to the central
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31 electrode, the anterior electrode often passed through the white matter before it entered the SNr.
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36 **Analysis was not based on continuous recordings during the entire advance towards the**
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38 **dorsolateral STN target, but rather on segments of data recorded at specific points (without**
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40 **electrode movement; Fig. 1B). Segments of data were recorded for at least 4 seconds, after 0.5**
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42 **seconds of lowering the electrode. Further details on the microelectrode recordings and the**
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44 **intervals of the depths** are presented as supporting information.
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50 **Neural Datasets**

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3 We divided our neuronal **database** into two parts. Training **dataset was composed of** 58
4 trajectories (obtained from 30 PD patients) containing 2678 stable MERs recorded in the white
5 matter before the STN, STN dorsolateral oscillatory region (DLOR), STN ventromedial non-
6 oscillatory region (VMNR), white matter after STN and SNr. A subset of this **dataset**, containing
7 1720 MERs from the dorsal and ventral STN as well as SNr, was used for the support vector
8 machine (SVM) procedure. Training **dataset** of 58 trajectories was also used to find the optimal
9 parameters for the hidden Markov model (HMM). Seventy-three additional trajectories recorded
10 from 51 other patients, and yielding 4526 stable MERs (test **dataset**) were used solely to test the
11 robustness of the HMM detection.
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27 **Root Mean Square (RMS)**

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29 The RMS estimate was calculated from the multi-unit activity recorded by the microelectrode at
30 each electrode depth. RMS values are susceptible to electrode properties (e.g., electrode
31 impedance);¹² hence, the RMS was normalized by the pre-STN (white matter) baseline RMS,^{12,23}
32 creating what we **term** the normalized RMS (NRMS).
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41 **Power spectral density (PSD)**

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43 Visual inspection of the average STN and SNr power spectra revealed significant differences in
44 the 5-300 Hz domain. To identify the frequency band that contained the largest difference
45 between the STN and the SNr we divided the 5-300 Hz range of the power spectra into 10
46 approximately logarithmically spaced bands. For each band we calculated the mean power for
47 each MER, and then evaluated the difference in the mean power between the STN and the SNr.
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3 Using this method we identified which frequency bands had the largest difference between the
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5 STN and the SNr. Additional details are presented in the [supporting information](#).
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10 **Support vector machine (SVM) discrimination of STN and SNr MERs**

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12 [In machine learning, SVMs are supervised learning models that are specifically designed to solve](#)
13 [a classification problem offline, after all the data have been collected.](#) For our SVM analysis,
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15 measurements in both time and frequency domains (based on the NRMS and power spectra of the
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17 MERs) were used as features for the SVM classification. The classification procedure used the
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19 NRMS and the "100-150 Hz / 5-25 Hz Power Ratio" features, as well as their class label (STN or
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21 SNr) for each of the 1720 MERs in the training dataset. [The performance of the SVM classifier](#)
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23 [was evaluated by 10-fold cross validation.](#) Additional details are presented in the [supporting](#)
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25 [information](#).
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34 [The SVM requires labeling the MERs of each region, which is not amenable to real time use.](#)
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36 [Here we used the SVM to identify which features had the most information in terms of](#)
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38 [discriminating regions. However, once the optimal features had been selected, the SVM was no](#)
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40 [longer needed or used.](#)
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45 **The Hidden Markov Model**

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48 [The HMM takes the set of features extracted from the raw data as input, and provides the output](#)
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50 [clustering in real time.](#) In previous reports,^{23,24} the HMM procedure was used to discriminate the
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52 STN from the white matter. This study goes beyond [these](#) previous [works](#) by designing a HMM
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3 procedure with improved ability to detect the STN-exit by delineating the borders between the
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5 STN-SNr (even for cases **without** a WM gap between the STN and the SNr). Details on the
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7 HMM are provided in the supporting information.
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12 All statistical analyses were performed using custom-made MATLAB 7.5 routines (Mathworks,
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14 Natick, MA). **The statistics** presented in this report, if not specified otherwise, **are** the mean \pm
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16 standard error of the mean (SEM); the criterion for statistical significance was set at $P < 0.05$ for
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18 all statistical tests.
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24 RESULTS

25 **Power Spectra features help to discriminate STN from SNr recordings**

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27 The NRMS values calculated from the MERs were very effective in detecting the STN border
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29 with the white matter. As presented in the three examples in Figure 2A, top panels, the STN-
30
31 entry and STN-exit borders **appear** as a sharp increase and decrease in the NRMS,
32
33 respectively.^{23,12} In these “easy” cases the electrode **traversed** the STN and **entered** the SNr after
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35 passing through the white matter. The power spectra of **these** SNr (Fig 2A bottom panels) depict
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37 a unique signature: blue vertical lines indicating a reduction in relative power at lower
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39 frequencies. However, some trajectories **lacked** a clearly defined STN-exit (e.g., Fig. 2B). These
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41 are the “hard” cases in which there is no clear transient reduction in the NRMS (NRMS gap),
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43 most probably because the electrode **traversed** the STN and **entered** the SNr without passing
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45 through the white matter after the STN. Though the SNr cannot be identified by the NRMS in
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47 these cases, the SNr was identified by the electrophysiologist and can be seen in the power
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3 spectra (Fig. 2B bottom) as depicted by the vertical blue lines. These examples suggest that
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5 power spectra characteristics can be used to assist in detection of the STN exit, especially for
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7 cases without a STN-WM transition and NRMS gap.
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12 To evaluate the ability of the NRMS to distinguish the STN from the SNr, we calculated the
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14 distribution of their NRMS values. Figure 3A shows the overlap in the NRMS distribution of 660
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16 MERs in STN DLOR, 990 MERs in the STN VMNR, and 155 MERs in the SNr (training
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18 dataset). The significant overlap between the different distributions suggests that there is no clear
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20 separation between the STN and the SNr using NRMS. In contrast, Fig 3B, illustrating the mean
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22 PSD of the STN and SNr recordings, suggests that features from the PSD could be used to
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24 discriminate STN from SNr. In line with the characteristic signature of the STN and SNr in the
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26 spectrograms (Fig 2), the average PSDs of the two STN domains and the SNr revealed different
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28 non-overlapping features. The mean SNr PSD (Fig. 3B, green trace) presented decreased activity
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30 in the 5-25 Hz band as compared to the mean PSD of the STN DLOR, and VMNR (Fig. 3B, red
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32 and blue traces). In addition, the mean PSD in the SNr displayed increased activity in the 85-300
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34 Hz band (Fig. 3B, green trace).
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44 To determine quantitatively which part of the power spectra enables the best discrimination of the
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46 STN from the SNr, we examined 10 (approximately logarithmically distributed) bands along the
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48 frequency axis in the power spectra. The mean power in two different frequency bands - high
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50 frequency (100-150 Hz) and low frequency (5-25 Hz) - provided the greatest discrimination
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52 between STN and SNr (discrimination matrix of 10 bands presented in the Supporting
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3 Information Table S1). We therefore calculated the ratio of the power of these two frequency
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5 bands and termed this new feature the “100-150 Hz / 5-25 Hz Power Ratio”. Figure 3C shows
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7 very little overlap in the distributions of STN and SNr power ratio values.
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10 11 12 **Support vector machine (SVM) analysis confirms the utility of the power ratio for STN-SNr** 13 14 **discrimination**

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17 An SVM classifier was used to examine the ability of the “100-150 Hz / 5-25 Hz Power Ratio” to
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19 provide a robust discrimination between the SNr and STN. Figure 4 shows the result of an SVM
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21 classifier that was trained and tested on 155 randomly selected samples from the STN and all 155
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23 samples from the SNr. A linear-kernel decision boundary was used to classify the training set as
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25 SNr (hollow square; green) or STN (hollow triangle; blue); then new data points were classified
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27 as SNr (solid square; green) or STN (solid triangle; blue). Yellow circles **represent** the support
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29 vectors defining the decision boundary between the STN and SNr samples. Figure 4 further
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31 demonstrates the **absence** of correlation between NRMS and the “100-150 Hz / 5-25 Hz Power
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33 Ratio”. Both of these characteristics reinforce the utility of the power ratio feature as an
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35 additional attribute for classifying MERs. The discrimination performance of the SVM classifier
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37 for the entire training dataset using the two features, NRMS and “100-150 Hz / 5-25 Hz Power
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39 Ratio” was **evaluated by 10-fold cross validation and** is presented as an error matrix in the
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41 Supporting Information Table S2. The overall classification accuracy rate was 97.6%.
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50 **Hidden Markov model (HMM) analysis enables reliable detection of STN exit**

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3 The HMM procedure uses MER features and trajectory history to enable real time decisions as to
4 electrode placement. The use of trajectory history in addition to the MER features enable the
5 HMM procedure to "neglect" recording glitches that a classification method (e.g., SVM) would
6 classify incorrectly. Our previous HMM procedures²³ did not include the SNr as a possible state
7 and did not use the high frequencies (100-150 Hz) of the power spectrum. Here we extended the
8 HMM procedure to discriminate between the STN and SNr using the "100-150 Hz / 5-25 Hz
9 Power Ratio" and NRMS features, together with the depth of the trajectory (i.e., estimated
10 distance to the target). The distribution of STN-exit borders was evaluated, and revealed that 77
11 out of 131 trajectories (59%) had STN-WM transitions, and 54 out of 131 trajectories (41%) had
12 STN-SNr transitions.
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29 Figure 5 presents three examples of a typical trajectory's NRMS and PSD as well as the "100-
30 150 Hz / 5-25 Hz Power Ratio" feature. At each depth along the trajectory during the implant
31 process the NRMS and power spectra features of the MERs are continually calculated and
32 updated. Based on these calculations a new assessment by the HMM is made automatically in
33 real time. An expert physiologist lowers the electrode along the trajectory until the red line
34 appears (i.e., as determined by the real time HMM analysis). This indicates that the STN ventral
35 border has been reached, followed by either the SNr or white matter. The three example
36 trajectories illustrate the direct transition from the STN to SNr. The red line in the top panel
37 illustrates the direct STN-SNr transition defined by the real time HMM analysis. It takes 99 ms in
38 real time to process a new trajectory and determine whether it is STN or not, as illustrated by the
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3 HMM running time in Fig. 5. The time to analyze each subsequent MER is less than a ms per
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6 MER, making this a practical method for use during DBS surgery.
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10 For each of the 58 trajectories in the training dataset, the HMM parameters (transition and
11 emission matrices) were estimated from the other 57 trajectories (leave-one-out cross-validation).
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13 The resulting mean (of all 58 trajectories) HMM transition and emission matrices are presented in
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15 the Supporting Information Table S3.
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22 The performance of the HMM was assessed with two measures. The first is the mean OUT
23 location error. It is defined as the difference between the *location (Human Expert's*
24 *Classification)*, which is the location of the transition defined by the neurophysiologist, and
25 *location(HMM)*, which is the HMM inferred location of the transition, both measured in mm of
26 estimated distance to the target. The second measure is the OUT transition error which is defined
27 as an OUT location error greater than 1 mm. Hits were the number of correctly detected OUT
28 transitions. Misses were the number of OUT transitions (according to the human expert's
29 decision) that the HMM procedure did not detect.
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43 The OUT location error for both STN-SNr and STN-WM demonstrated better mean and standard
44 deviation than that found by previous methods.^{12,23} The performance of the OUT location error
45 on the training dataset had an error of 0.1 ± 0.34 mm (mean \pm standard deviation) with 2 misses
46 out of 58 trajectories (97% Hits).
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3 The HMM procedure has to deal with a heterogeneous variation of trajectories, as some
4 transitions are from VMNR STN to SNr and others from white matter before STN to SNr.
5 Because an automatic detection algorithm that can be used in the operating room needs to
6 function on novel data without being continually adjusted, it is important to demonstrate that the
7 HMM procedure can work with completely novel data. Therefore, 73 other trajectories (from 51
8 patients, all trajectories included both STN and SNr) were evaluated by the HMM procedure. The
9 HMM procedure identified the STN-exit with error of 0.04 ± 0.18 mm. Using the 1 mm
10 threshold, the OUT transition error of the novel dataset committed 4 misses out of 73 trajectories
11 (94% Hits), which is better than that found when applying the previous HMM procedure²³ and
12 Bayesian method¹² (12 misses out of 73 trajectories, 83% hits, and error = 0.50 ± 0.59 mm,
13 respectively). The performance of the new HMM procedure was shown to be robust to the
14 specified threshold because threshold values of 0.5 mm and 0.15 mm produced similar
15 quantitative results (4 and 7 misses out of 73 trajectories, respectively).
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36 DISCUSSION

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38 We described a computational machine-learning procedure with a new feature; namely, the ratio
39 of high frequency (100-150 Hz) power to low frequency (5-25 Hz) power, which enables high
40 accuracy discrimination of the STN from SNr. We used a SVM procedure to verify that the “100-
41 150 Hz / 5-25 Hz Power Ratio” is a reliable feature for discriminating the STN and SNr
42 populations. Then, we utilized an HMM procedure using the MER features, together with the
43 trajectory history to detect the STN exit either to the white matter (WM) or SNr.
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6 The MERs along pre-planned trajectories are commonly used to confirm the STN territory during
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8 DBS surgery for Parkinson's disease; however, there is a lack of consensus on whether the MER
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10 allows for reliable separation between the STN exit point and the SNr entry point. Across the
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12 ventral region of the STN there are fewer kinesthetic neurons,²² and the STN VMNR neurons are
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14 characterized by consistently reduced β band and increased gamma (30-100 Hz) activity.¹³
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16 Similarly, the discharge pattern of the neurons in the SNr (below the STN target) lack the β band
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18 and tremor frequency oscillations, **but have** increased gamma activity.¹⁴⁻¹⁸ In addition, islands of
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20 cells have been observed with firing characteristics of both SNr and STN cells.²² Therefore, the
21
22 electrophysiological determination of the transition from the STN to SNr is ambiguous and
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24 difficult to evaluate.
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32 Several studies have developed automatic detection and visualization not only for the STN, but
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34 also the SNr based on objective and quantitative MER features.^{12,20,22,25-27} Some of these studies
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36 have used features that require spike detection algorithms to identify the firing pattern.²⁵⁻²⁷ While
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38 these features may aid in detecting the STN ventral border near the SNr, it is still computationally
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40 challenging to calculate neuronal spike characteristics in a real-time intra-operative scenario.¹²
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42 Moreover, the ideal isolation of single units requires 5-10 microns steps of electrodes and is very
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44 time-consuming. In contrast, NRMS values that are based on unsorted multi-unit activity are easy
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46 to measure. The STN-entry and STN-exit often **manifest** as a sharp increase and decrease in the
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48 NRMS, respectively.^{23,12} Some studies have used NRMS together with spectral features of the
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50 analog signal, which are computationally efficient to calculate.^{20,22,27} However, these spectral
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3 features do not lead to reliable or robust identification of the transition between the STN and the
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5 SNr. Here, we divided the 5-300 Hz range power spectra into frequency bands. This division
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7 allowed us to determine which frequency bands contained the largest difference between the STN
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9 and the SNr, and to accurately detect the STN ventral border.
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15 **When implementing the** NRMS and features from the power spectra, there are several ways to
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17 differentiate the STN from the SNr using automatic detection methods. Some studies have
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19 proposed rule-based detection methods,^{22,27} however, they are unable to detect the direct STN-
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21 SNr transitions. For example, despite the fact that Cagnan et al.²⁷ used the power spectra of
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23 tremor, and the alpha band (3–12 Hz), beta band (13–30 Hz) and gamma band (31–100 Hz) as
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25 features, their algorithm still required a white matter gap in the trajectory between the STN and
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27 the SNr to detect the SNr. Furthermore, rule-based detection systems tend to be overly complex
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29 and may not generalize to other surgical centers. Other studies^{12,23,25} have used machine learning
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31 techniques to automatically extract the “rules” or decision boundaries to discriminate between
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33 the STN and the SNr. These machine learning procedures are either unsupervised, **and involve**
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35 extracting patterns using unlabeled training data (that still require labeling of the output),²⁵ or
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37 supervised, that require the labeling of the electrophysiological signals used for training.^{12,23} For
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39 example, Wong et al.²⁵ used a clustering algorithm (unsupervised machine learning) that returns a
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41 pre-specified number of clusters, but then requires the human observer to label the clusters. The
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43 main drawback of these techniques is **that they do not take** the previous location of the MERs
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45 **into account when** determining the electrode's current location. A supervised technique that uses
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47 the electrode's location is HMM. For example, Zaidel et al.²³ combined the power spectra of beta
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3 band features and NRMS to locate the STN and its sub-territories. The two advantages of the
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5 HMM procedure are the short recording time needed for location analysis and low computational
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7 cost. Our **approach** goes beyond **this** previous work by delineating the borders between the STN-
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9 SNr **which thus enable intra-operative application with greater accuracy.**

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15 Accurate discrimination between the STN and the SNr is of **crucial** importance for achieving
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17 optimal therapeutic benefits while avoiding psychiatric complications for PD DBS procedures.
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19 The beneficial effects of bilateral STN DBS on motor symptoms and quality of life have been
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21 **repeatedly confirmed** in patients with advanced PD;²⁸ however, psychiatric complications
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23 induced by STN DBS have also been reported.^{29,30} In some patients with PD with impulse control
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25 disorders, their abnormal behavior may be provoked by stimulation with a ventral contact of the
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27 DBS lead, and suppressed by switching off this contact.⁶⁻⁹ It also has been reported that
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29 manic^{31,32} and depressive⁵ symptoms are induced by stimulation of active contacts located in the
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31 SNr. On the other hand, the SNr **is thought to be** particularly involved in balance control during
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33 gait.³³ The combined stimulation of the SNr and the STN has been reported to improve axial
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35 symptoms (including freezing of gait, balance, and posture) compared to standard STN
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37 stimulation.^{10,11} In summary, automatic and reliable localization of the **direct** STN-SNr transition
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39 and STN lower border detection could lead to improved localization of DBS leads and better
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41 DBS clinical outcomes. **It takes 99 ms in real time to process a new trajectory and decide whether**
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43 **it is STN or not, making this a practical method for use during DBS surgery. This analysis tool**
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45 **can be easily learned and employed in the DBS operating room.** Future studies might incorporate
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MER data from multiple centers to test the applicability of these algorithms for automatic navigation in DBS surgery.

Authors' role: 1)Research project: A. Conception, B. Organization, C. Execution; 2)Statistical Analysis: A. Design, B. Execution, C. Review and Critique; 3)Manuscript Preparation: A. Writing of the first draft, B. Review and Critique;

D.V.: 1A, 1B, 1C, 2A, 2B, 2C, 3A, 3B

H.B.:1A, 1B, 2C, 3B

O.M.: 2C, 3B

R.E.: 1B, 3B

M.D.: 3B

K.B.: 1B, 2C, 3B

Z.I.: 1A, 1B, 3B

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Supporting Data

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