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DECREASED MECHANICAL WORK DEMAND IN THE CHOPART JOINT AFTER TOTAL ANKLE REPLACEMENT

| Journal: Foot & Ankle International Manuscript ID FAI-22-0143.R1 Manuscript Type: (Original) Clinical Research Article Keywords: Biomechanics, Gait Studies, Arthritis Background: The success of total ankl based on restoring reasonable mechanic structures that can produce mechanic tendons, fascia) or viscoelastic (e.g., I muscle contractions. Yet, quantifying affected joint and the neighbouring fo Therefore, the objective of this study change in the joint work distribution a and Metatarso-phalangeal joints durin patients undergo TAR. Methods: Fifteen patients with end-sta for primary TAR for pain relief were references. | nical balance with anatomical |
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| STRUCTURED ABSTRACT (Limit 300 words) Background, Methods, Results & Conclusion: Background, Methods, Results Background, Methods, R | heel pad) mechanisms, or by active the work distribution across the ot joints after TAR is lacking. was to investigate if there is a across the Ankle, Chopart, Lisfranc ig level walking before and after age ankle osteoarthritis scheduled ecruited and peer-matched with a ents underwent a 3D gait analysis in a kinetic multisegment foot model joint work. joint (P = .007) to the total foot inificantly after TAR. In contrast, a in to the total foot and ankle joint at the Chopart joint after TAR. The ficant increase in a net mechanical to + 0.05 J/kg after TAR (P = y corroborate the theoretical y the compensatory strategy in the in end-stage ankle osteoarthritis showed that the contribution of the e total foot and ankle joint positive |

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DECREASED MECHANICAL WORK DEMAND IN THE CHOPART JOINT

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AFTER TOTAL ANKLE REPLACEMENT

3 ABSTRACT

Background: The success of total ankle replacement (TAR) must be based on restoring 4 5 reasonable mechanical balance with anatomical structures that can produce mechanical joint work through elastic (e.g., tendons, fascia) or viscoelastic (e.g., heel pad) 6 mechanisms, or by active muscle contractions. Yet, quantifying the work distribution 7 8 across the affected joint and the neighbouring foot joints after TAR is lacking. 9 Therefore, the objective of this study was to investigate if there is a change in the joint 10 work distribution across the Ankle, Chopart, Lisfranc and Metatarso-phalangeal joints 11 during level walking before and after patients undergo TAR.

Methods: Fifteen patients with end-stage ankle osteoarthritis scheduled for primary TAR for pain relief were recruited and peer-matched with a sample of 15 control subjects. All patients underwent a 3D gait analysis before and after surgery, during which a kinetic multisegment foot model was used to quantify inter-segmental joint work.

Results: The contribution of the ankle joint (P = .007) to the total foot and ankle positive work increased significantly after TAR. In contrast, a significant decrease in the contribution to the total foot and ankle joint positive work (P < .001) were found at the Chopart joint after TAR. The foot joints combined produced a significant increase in a net mechanical work from + 0.01 J/kg before surgery to + 0.05 J/kg after TAR (P= .006).

Conclusions: The findings of this study corroborate the theoretical rationale that TAR reduces significantly the compensatory strategy in the Chopart joint in patients suffering from end-stage ankle osteoarthritis after TAR. However, the findings also showed that the contribution of the ankle joint of patients after TAR to the total foot and ankle joint positive work remained impaired compared to the control group.

28 Level of evidence: Level III

29 Keywords : Total Ankle Replacement; Ankle Osteoarthritis; Mechanical Work
30 Demand

31

32 INTRODUCTION

End-stage ankle osteoarthritis is a chronic debilitating disease characterized by 33 cartilage breakdown, significant pain and disability.^{1,30} It is estimated that 34 35 approximately 1% of the world's adult population is living with symptomatic ankle osteoarthritis.^{1,30} Once the pain associated with end-stage ankle osteoarthritis is no 36 37 longer manageable through conservative treatment, current surgical treatment options 38 include total ankle replacement (TAR) and ankle arthrodesis, with TAR becoming increasingly popular.^{3,26,27,32} While ankle arthrodesis (fusion of tibio-talar joint) is 39 considered to be the "gold standard" operative treatment strategy, TAR has been 40 41 encouraged during the last decade as it has the potential to maintain the existing preoperative ankle range of motion and to protect the more distally located joints of the 42 foot.^{2,18} However, the latter has not yet been investigated from a mechanical joint work 43 perspective. 44

Recently developed 3D multi-segmental kinetic foot models were created 45 46 to provide estimations of joint mechanics and energetics across various subsections of 47 the foot and ankle to provide deeper insight into the complex behaviour of the foot and ankle during walking.^{4,13,31} Although still explorative in nature, the importance of these 48 49 models should not be underestimated, and use of such models has indicated altered 50 inter-segmental power at the more distally located foot joints in patients suffering from ankle osteoarthritis.^{11,13,28} Recently, a first insight into the kinetics of the midfoot 51 52 following TAR was provided by DiLiberto et al. (2021) with findings suggesting that no changes in midfoot region peak power generation and absorption occurred between 53 preoperative and 6 months postoperative conditions.¹¹ A drawback of the latter study, 54

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however, is the oversimplification of foot mechanics neglecting the complex interaction
between forefoot, midfoot and hindfoot.³⁹

The success of a surgical intervention must be based on restoring reasonable 57 balance of joint mechanics and energetics across the affected joint and the neighbouring 58 joints. Biomechanical work measured at the level of specific joints is critical for 59 60 understanding the work produced by all the anatomical structures crossing the joint center such as fascia, muscles, tendons and other structures at each joint.³³ For example, 61 62 one of the major contributors of positive work production (i.e. energy generation) 63 within the foot and ankle is the plantarflexor muscle-tendon structures during pushoff.^{10,33} In contrast, the metatarso-phalangeal joints tend to produce more negative work 64 65 (i.e. energy absorption) than the joints distal to the ankle joint during propulsion as they stabilize the toes against the ground to counteract the ground reaction forces.³³ 66 Understanding where in the foot this work is performed and how it is distributed among 67 the foot joints is useful for discerning fundamental mechanisms of how TAR benefits 68 or degrades biomechanical performance in the affected ankle joint as well as in the 69 70 neighouring foot joints. This is of clinical relevance as progression of osteoarthritis of the neighbouring foot joints after TAR was observed in 15% to 19.6% of the cases.^{19,37} 71 72 Increased tissue trauma caused by functional compensatory mechanism in the ipsilateral joints adjacent to the affected ankle is thought to contribute to the progression 73 74 of these secondary postoperative arthritic changes. Despite the fact that gait mechanics 75 after TAR is an active area of research, yet to our knowledge, no study so far has 76 actually investigated the work distribution in the affected ankle joint and the neighbouring joints of the foot after TAR by making use of a four-segmented kinetic 77 foot model.^{3,26} Therefore, the purpose of this study was to explore the changes 78 79 occurring in the work distribution of the affected ankle joint as well as the neighbouring joints of the foot during level walking before and after patients undergo a TAR, using 80 a four-segmented foot model. 81

Therefore, we asked, (1) Is there a change in the joint work distribution across 82 83 the Ankle, Chopart, Lisfranc and Metatarso-phalangeal joints during level walking before and after patients undergo TAR? Our hypothesis was that the ankle joint will 84 increase its contribution to the total foot and ankle positive work after surgery. We 85 further hypothesized that the adjacent Chopart joint of the affected ankle will 86 significantly decrease its contribution to the total foot and ankle positive and negative 87 work after surgery. This hypothesis is underpinned by the findings of previous studies 88 89 that found compensatory strategies in the distal foot joints triggered to compensate for 90 the altered ankle joint biomechanics in patients suffering from ankle osteoarthritis compared to healthy reference data during walking.^{5,20} (2) Following TAR surgery, 91 92 does the joint work distribution across the intrinsic joints of the foot approach the values of the control group of asymptomatic subjects? We hypothesized that the mechanical 93 contribution of the ankle joint after surgery would remain impaired compared with 94 control subjects and that it would be partially compensated by the distal joints of the 95 PRIC foot. 96

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98 **PATIENTS AND METHODS**

99 Patients

100 Between March 2017 and June 2020, 102 eligible patients suffering from end-stage ankle osteoarthritis, Takakura stage 3 - 4 (4 being complete obliteration of the joint 101 102 space) scheduled for primary TAR for pain relief, were invited to participate in 103 prospective data collection in the gait analysis laboratory. Of those, 46% (46) of patients were enrolled. From this database, a convenience sample of 15 symptomatic 104 patients were peer-matched with 15 asymptomatic control subjects according to their 105 demographics and their postoperative walking speed and stride length to participate in 106 107 this retrospective study (Table 1). This sample size provides 80% power and a p-value at 0.05 to detect a higher contribution of the ankle joint to the total foot and ankle 108

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positive and negative work after surgery and a lower contribution of the adjacent 109 Chopart joint of the affected ankle to the total foot and ankle positive and negative work 110 111 after surgery. The hypothetical effect size for this analysis was estimated based on pilot results reported by Deleu et al. (2021).⁷ which can be found in Supplementary material. 112 113 The inclusion criteria were (1) diagnosis of posttraumatic end-stage ankle osteoarthritis with an indication for TAR established by two senior orthopaedic surgeons, (2) 114 scheduled to undergo TAR (CADENCE® fixed-bearing prosthesis, Smith & Nephew, 115 London, UK) within 4 weeks of preoperative gait testing and to be tested again 1 year 116 after surgery. (3) being older than 18 years of age. (4) absence of systemic or 117 neurological diseases, (5) capable of walking at least 100 meters without an assistive 118 device and without rest. Exclusion criteria were (1) major lower limb orthopedic 119 pathologies or surgeries, (2) pain in more than one lower-extremity joint in either limb, 120 and (3) any medical problem other than posttraumatic end-stage ankle osteoarthritis 121 122 that could possibly affect gait. Exclusion criteria of the control group comprised of any 123 medical condition possibly affecting normal gait. Participant's demographic data are reported in Table 1. The local ethical committee approved the study and all participants 124 ien signed an informed consent form. 125

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Fixed-bearing prosthesis 127

The Cadence prosthesis (Smith & Nephew, London, UK) is a new generation two-128 component, fixed-bearing, semi-constrained TAR system. The prosthesis is 129 characterized by an anatomic shaped bone-anchored talar component (cobalt chrome 130 alloy) and a polyethylene meniscal insert attached to a bone-anchored tibial component 131 (titanium alloy).^{21,29} The articular surface pattern of talar dome is characterized by two 132 condylar surfaces.³⁴ The lateral condyle of the talar dome has a larger radius of 133 curvature compared to the medial condyle of the talar dome.³⁴ The articular bearing 134

surface of polyethylene meniscal insert is shaped similarly to the surface pattern of the

talar dome in order to achieve a congruent fit between the two prosthesis components.³⁴

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138 Data Capture and Analysis

139 A ten-camera optoelectronic motion analysis system sampling at 200Hz, was used to track the trajectories of markers (Migus, Qualysis, Göteborg Sweden) used in 140 conjunction with a Footscan® pressure plate (0.5m x 0.4m, 4.096 sensors, 2.8 sensors 141 per cm²; RSscan International, Paal, Belgium) mounted on the top of a AMTI-force 142 143 plate (0.5 x 0.4m; Advanced Mechanical Technology, Inc., Watertown, MA, USA). 144 Both plates were embedded in a 10-m walkway in a gait laboratory, enabling the 145 collection of data regarding joint mechanics and ground reaction forces. The force plate was custom-made to fit the surface dimensions of the pressure plate and both plates 146 were sampled at 200Hz. This set-up provided continuous calibration of the pressure 147 plate with respect to the force plate, using an RsScan® 3D box (RSscan International, 148 Paal, Belgium). 149

150 A marker set of sixteen retro-reflective skin markers ($\emptyset = 8 \text{ mm}$) was placed on the foot and shank of each patient in accordance with the marker placement protocol of the 151 Rizzoli four segment foot model (Figure 1).²² This multi-segment foot model has 152 revealed the kinematic and kinetic alterations occuring in the joints of the foot other 153 than the affected ankle in patients suffering from end-stage ankle osteoarthritis.^{5,6,13,14} 154 Patients were instructed to walk at a self-selected, comfortable speed barefoot across 155 156 the walkway. A minimum of five representative trials were collected per patient, a trial 157 being considered representative when the foot of interest made clear contact with the pressure plate without visual adjustments in walking behavior. 158

Inter-segmental angle calculations were performed between the shank (Sha),
calcaneus (Cal), midfoot (Mid), metatarsus (Met) and hallux (Hx) segments according
to the modified Rizzoli multi-segment foot model (IOR-4Segment-model 1).^{4,9} The

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term joint is used in this manuscript to represent the modelled biomechanical interaction 162 between two adjacent foot segments.³⁹ The following inter-segmental center (joint) 163 definitions of the four segment foot model were applied in accordance with previously 164 investigated kinetic Rizzoli multi-segment foot model^{5,6,9,14} : 1) ankle joint (Sha-Cal) 165 center defined as the midpoint between the malleoli skin markers, and motion at this 166 joint was considered between the calcaneus and the shank segments, 2) Chopart joint 167 (Cal-Mid) center defined as the midpoint between the cuboid and the navicular bone, 168 169 and motion at this joints was considered between the calcaneus and the midfoot 170 segments, 3) Lisfranc joint (Mid-Met) center defined as being on the base of the second metatarsal, and motion at this joint was considered between the midfoot and the 171 metatarsus segments, 4) first metatarso-phalangeal joint center (Met-Hx) defined as 172 being at intersection of the projection of the first metatarsal head skin marker vertically 173 at mid distance and the floor, and motion at this joint was considered between the 174 metatarsus and the hallux segments.⁹ 175

Inter-segmental forces (F) and moments (M) were calculated in the Joint 176 Coordinate System using a bottom-up inverse dynamic method.^{8,23} Kinematic and force 177 data were filtered using a low-pass zero-lag, 4th order, Butterworth filter, with a cut-off 178 179 frequency of 10 Hz. Inertia and mass parameters of each foot segment were not accounted for considering that the inertia effects were negligible during stance in 180 comparison to the external forces.^{16,28} The force plate data were distributed over the 181 segments of the Rizzoli foot model using a proportionality scheme (i.e. if 20% of the 182 183 total vertical force acted on the midfoot, it was assumed that 20% of the total horizontal force and vertical moment also acted on the midfoot), which was validated in a similar 184 population study.¹⁵ For every sample, the estimation of the ground contact area of each 185 foot segment was achieved by projecting the markers' position vertically onto the 186 sensor matrix of the pressure platform. The resulting center of pressure (CoP) of each 187 estimated ground contact area was then used as the CoP for the corresponding foot 188

189 segment in the inverse dynamics calculations. Inter-segmental kinetic data were

190 calculated using an in-house written Matlab© program (Mathworks Inc., Natick, US).

191 Internal inter-segmental moments, power and work were normalized by subject-mass,

- and all variables were time-normalized to 100% of the stance phase.
- 193

194 Study endpoints and statistical analysis

195 The primary outcome measure was mechanical work (calculated respectively, as the 196 negative and positive time-integral of power) of the Ankle (Sha-Cal), Chopart (Cal-197 Mid). Lisfranc (Mid-Met) and MTP1 (Met-Hx) joints during the stance phase of the gait cycle (Absolute values). In this study, the term work is referred to the mechanical 198 action produced by all the anatomical structures crossing the joint center such as skin, 199 200 fat, fascia, muscles, ligaments, together with friction and contact between the articular surfaces.⁸ Positive work was normalized by the summed positive work of all joints of 201 202 the foot and ankle to account for potential increases in the total foot and ankle positive 203 work after TAR, given the expected increase in walking speed and allowing for the 204 expression of individual foot joint contributions to the total foot and ankle joint positive work as a percentage (Relative values). The same approach was used for the 205 206 normalization of negative work. In addition, the total positive and negative work as well as the net work performed by the entire foot and ankle joints during the stance 207 phase were also calculated across conditions and timepoints. Therefore, these outcome 208 209 measures can be compared between assessment dates (preoperatively and 1 year 210 postoperatively). Comparisons were performed within patients (preoperative versus 211 postoperative variables) and between groups (postoperative versus control). Normality and hetereoskedasticity of continuous data were assessed with Shapiro-Wilk and 212 213 Levene's test respectively. When the data was normally distributed, paired T-tests 214 (within patients) and independent sample T-tests (post-op patient group vs control 215 subject group were performed. When the data was not normally distributed, Wilcoxon

signed rank (within patients) and Mann-Whitney test (post-op vs control) were used. 216 An adjusted *P*-value (0.05/4=0.013 for each individual joint comparison; 0.05/2=0.025217 for the absolute total positive and negative work as well as for the net mechanical work) 218 was used to control the type 1 error rate when performing multiple comparisons. All 219 220 statistical tests used R software, version 3.4.3. (https://www.r-project.org/; The R 221 Foundation for Statistical Computing, Vienna, Austria). 222 223 **RESULTS** 224 Demographic and spatio-temporal data No significant differences between the two groups were found for age (P =225 .717), weight (P = .781), height (P = .504) and BMI (P = .428). The spatiotemporal 226

parameters showed a statistically significant increase after surgery in walking speed (P228 = .001) and stride length (P < .001) being comparable with that of the controls (Table 229 1 & 2).

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231 Pre- versus postoperative condition

The Ankle (Sha-Cal; 0.09 J/kg), Chopart (Cal-Mid; 0.03 J/kg), Lisfranc (Mid-232 233 Met; 0.04 J/kg) and MTP1 (Met-Hx; 0.002 J/kg) joints combined produced a total preoperative positive work of 0.16 J/kg during the stance phase of gait. After TAR, the 234 positive work of each foot joint increased significantly except for the Chopart joint 235 236 (Table 3 & Figure 2). The total postoperative positive work produced in the foot and 237 ankle increased significantly to 0.25 J/kg (P < .001) (Ankle (Sha-Cal; 0.15 J/kg); 238 Chopart (Cal-Mid; 0.03 J/kg); Lisfranc (Mid-Met; 0.07 J/kg); MTP1 (Met-Hx; 0.004 J/kg)). As for the negative mechanical work, 0.15 J/kg was absorbed in the foot and 239 ankle before surgery during the stance phase of gait (Ankle (Sha-Cal; -0.07 J/kg); 240 Chopart (Cal-Mid; -0.05 J/kg); Lisfranc (Mid-Met; -0.01 J/kg); MTP1 (Met-Hx; -0.02 241 J/kg)). The latter increased significantly after surgery to 0.20 J/kg (P = .001). Only the 242

243 Ankle joint produced a significantly increased negative mechanical work after surgery

244 (Sha-Cal = -0.1 J/kg; P = .003). This resulted in a net mechanical work of + 0.01 J/kg

before surgery and of + 0.05 J/kg after TAR, embodying a significant increase of 0.04

246 J/kg (P = .006).

The relative distribution of the mechanical work across the intrinsic joints of the 247 foot changed significantly after TAR (Figures 3 & 4, Table 4). The contribution of the 248 Ankle (Sha-Cal) (mean (\pm SD) preoperative 52.4% \pm 9.8, mean (\pm SD) postoperative 249 $57.2\% \pm 7.4$, P = .007) to the total foot and ankle positive work increased significantly 250 after surgery. In contrast, a significant decrease in the contribution to the total foot and 251 ankle joint positive work (mean (\pm SD) preoperative 21.6% \pm 7.6, mean (\pm SD) 252 postoperative $13.2\% \pm 5.5$, P < .001) was found at the Chopart (Cal-Mid) joint after 253 TAR (Table 4). 254

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256 Control subjects versus patients after TAR

Patients after TAR had a significantly lower mechanical positive work of Ankle 257 (Sha-Cal = 0.15 J/kg) compared to the control group (Sha-Cal = 0.22 J/kg; P < .001) 258 259 (Table 3 & Figure 2). The total postoperative positive work produced in the foot and ankle (0.25 J/kg) was significantly lower compared to the control group (0.35 J/kg) (P 260 <.001). As for the total negative mechanical work, no significant difference was found 261 between the two groups. The net mechanical work was significantly lower in the patient 262 group after TAR (+ 0.05 J/Kg) compared to the control group (0.10 J/kg) (P = .017). 263 264 Patients after TAR had no significant differences in terms of the contribution of each individual joint to the total foot and ankle positive and negative work after surgery 265

compared to the control group (Figures 3 & 4, Table 4).

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270 **DISCUSSION**

This prospective exploratory study was designed to compare pre- and postoperative 271 contribution of the affected ankle joint as well as the neighbouring joints of the foot to 272 the total foot and ankle mechanical work during gait of patients with end-stage ankle 273 osteoarthritis treated with a TAR. The outcome of this study confirmed our first 274 275 hypothesis and showed that TAR increased the contribution of the ankle joint (Sha-Cal) to the total foot and ankle positive work after surgery, as well as decreased the 276 277 contribution of the Chopart (Cal-Mid) joint after surgery. Furthermore, there exists a 278 trend toward decrease in the contribution of Chopart (Cal-Mid) joint to the total foot and ankle joint negative work after TAR. These results corroborate the suggestion that 279 280 TAR improves the mechanical contribution of the ankle (Sha-Cal) and has the potential to protect the adjacent joints of the foot after surgery.^{2,18} These findings are in contrast 281 to that of DiLiberto et al. (2021) who found no differences in midfoot function between 282 the preoperative and 6-month postoperative conditions in their TAR group. While our 283 absolute Chopart (Cal-Mid) joint work values would corroborate the findings of 284 DiLiberto et al. (2021), the individual contribution of each joint as percentages of the 285 total foot and ankle work contradicts their findings, and shows as a significant 286 287 postoperative decrease of 8.1 percent in the contribution of the Chopart (Cal-Mid) joint to the total foot and ankle joint positive work. This combination of findings provides 288 some support for a more holistic and functional approach towards foot and ankle 289 dynamics rather than an analytical, traditional single foot segment approach. 290

The ankle joint is one of the body's major sources of positive work produced mainly by the plantarflexor muscle-tendon structures during walking.¹⁰ The increased positive ankle (Sha-Cal) work values found after TAR are therefore a good indicator of an improvement in the ability to use the ankle to propel forward and an increase in strength of the calf muscles.¹⁸ These findings are indirectly corroborated by a recent metaanalysis that found moderate evidence of an increase in ankle power generation after

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TAR compared to pre-operative levels.³ Although the mechanical behavior of the affected ankle joint (Sha-Cal) appears to have improved postoperatively, the extent to which these changes in the contribution of the ankle joint (Sha-Cal) to the total foot and ankle positive work after surgery are attributable to pain relief and production of a more mechanically 'functional' ankle, cannot be determined.

302 The second hypothesis, that after surgery the ankle joint remained impaired compared with control subjects, was partially confirmed by the absolute Ankle (Sha-303 304 Cal) joint work values. Since the plantarflexor muscle-tendon structures are the main 305 contributor of the foot and ankle positive work, the impaired postoperative work 306 production observed at the Ankle (Sha-Cal) joint also seems to affect the total 307 postoperative positive work as well as the net total mechanical work produced in the foot and ankle which are significantly lower compared to control subjects. A possible 308 explanation for these results may be related to the findings of Valderrabano et al. (2007) 309 who reported that the torque produced by the arthritic ankles at one year after TAR 310 recovered partially to 83% for dorsiflexion and to 86% for plantarflexion compared to 311 the contralateral healthy ankle joint.³⁵ They further found that the preoperative calf 312 muscle atrophy did not change over the 1-year rehabilitation period after TAR. This 313 314 combination of findings provides some support to the theory that patients with TAR 315 may retain their muscle strength deficits due to a selective muscle fiber type loss or to a sustained preoperative disuse.³⁵ 316

The findings of this study further revealed an interesting biomechanical phenomenon, in which TAR seems successfully to increase the mechanical contribution of the ankle joint (Sha-Cal) and to reduce the need for compensatory mechanical work in the Chopart (Cal-Mid) joint. This is of clinical interest, as the results corroborate the theoretical rationale of choosing TAR over ankle arthrodesis. It is hypothesized that TAR preserves the preoperative ankle range of motion, and protects the more distally located joints of the foot.^{2,18} Based on the results, it is therefore plausible to suggest that

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the compensatory strategy in the distal joints of the foot in patients suffering from end-324 stage ankle osteoarthritis after TAR are reduced, especially in the Chopart (Cal-Mid) 325 joint, but remain present in the neighboring joints of the foot to compensate for the 326 residual mechanical deficit of the affected ankle joint. These residual compensatory 327 adaptations, and their impact on structures of neighboring joints during activities of 328 329 daily living, may result in tissue trauma and the development of adjacent hindfoot and midfoot osteoarthritis.¹⁷ Previous studies have reported progressive osteoarthritis in the 330 more distally located joints of the foot in 15 to 19.6% of the cases after TAR.^{19,38} Since 331 332 progressive osteoarthritis in distal joints of the foot has been reported after TAR, as well as after ankle arthrodesis, during the postoperative follow-up, future 333 334 biomechanical studies should compare the compensatory adaptations in the neighboring joints of both cohorts of subjects and their relationship with the 335 development and/or progression of adjacent foot joint osteoarthritis. 336

The findings of this study should be considered in the context of several 337 limitations. A first limitation is the observed increase in walking speed after TAR. Since 338 walking speed affects foot power and joint work, caution should be exercised when 339 interpreting the differences in joint power and joint work between pre- and 340 postoperative conditions.¹² A recent study suggested that power variables significantly 341 differ when walking speed increases by 37.5% (0.48 m/s). However, the results of the 342 study reported in this paper show an increase of only 15.6% (0.16 m/s) between pre-343 344 and postoperative measurements. Furthermore, Eerdekens et al. (2019) showed that an 345 increase in walking speed did not change the positive work distribution across the foot 346 and ankle joints. A second limitation is the estimation of motion of foot bones using skin markers, especially in complex joints such as the Subtalar, Chopart and Lisfranc 347 joints. The complexity resides in capturing relatively small motions occuring at these 348 joints composed by a group of relatively small foot bones. Over the last decade, multi-349 350 segment foot models using skin markers have been proposed to estimate the mechanical

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351 behaviour of foot joints by grouping foot bones into segments (e.g. hindfoot, midfoot, forefoot), the clinical value of which has been shown through the detection of intrinsic 352 foot mobility impairments.^{5–7,11} However, because these foot models do not account for 353 individual bone-to-bone motion, they may therefore violate rigid-body assumptions and 354 lead to inaccuracies in foot joint kinematic and kinetic estimations.^{25,36} To overcome 355 356 these challenges, methods using biplanar videoradiography have been used to provide more accurate measures of foot joint motion, which can be difficult to discern with skin 357 mounted markers.^{25,36} Recently, Lenz et al. (2022) used biplanar videoradiography to 358 359 capture postoperatively the kinematics at the prosthetic ankle joint as well as the adjacent subtalar joint.²⁴ They found symmetrical ankle and subtalar kinematics 360 361 between operated and nonoperated limbs after TAR during walking and double heelrise tasks. However, the invasive/ionising nature of these alternative methods precludes 362 their use in routine clinical analysis. A third limitation was the relatively small patient 363 population. To avoid clinical misinterpretations of the results due to differences in 364 spatio-temporal variables as well as demographic variables between the patient and the 365 366 control groups, strict inclusion criteria had to be met. By doing so, our study population was limited to 15 patients from a prospectively collected database consisting of 46 367 368 patients. Future studies could perhaps broaden the inclusion criteria to provide more generalizable clinical significance for this quite heterogeneous patient population in 369 terms of etiology and its associated osteo-articular deformity. 370

In conclusion, the results from this study seem to corroborate the theoretical rationale that TAR significantly reduces the compensatory strategy in the Chopart (Cal-Mid) joint in patients suffering from end-stage ankle osteoarthritis. The residual mechanical deficit of the affected ankle (Sha-Cal) joint observed in patients after TAR should be addressed with intensive physiotherapeutic rehabilitation program and patients should be encouraged to perform regular strengthening exercices of the ankle joint plantarflexor muscle-tendon structures even 1 year after TAR.

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DECLARATION OF CONFLICTING INTERESTS

The authors declare that they have no known competing financial interests or personal

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- relationships that could have appeared to influence the work reported in this paper.

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540 LEGENDS

541 **Table 1**: Participant's demographic data.

542 **Table 2**: Participant's spatio-temporal data.

543 Table 3: Absolute joint work (J/kg) across the intrinsic joints of the foot during level

544 walking preoperatively, 1 year postoperatively and compared to a control group.

545 (Abbreviations: Ankle OA, Ankle Osteoarthritis; CTRL, control group; SD, standard

546 deviation; J, joule; preop, preoperative; postop, postoperative).

547 **Table 4:** Normalized joint work across the intrinsic joints of the foot during level

548 walking preoperatively, 1 year postoperatively and compared to a control group.

549 (Abbreviations: Ankle OA, Ankle Osteoarthritis; CTRL, control group; SD, standard

550 deviation; J, joule ; preop, preoperative; postop, postoperative)

Figure 1: A) Inter-segment center definitions were defined according to an adapted

version of Rizzoli foot model (Leardini et al. 2007) developed by Deschamps et al.

553 (2017) (IOR-4Segment-model 1). Markers name: upper ridge of the posterior surface

of the calcaneus (FC); peroneal tubercle (FPT); sustentaculum tali (FST); virtual cuboid

555 marker (FCub), tuberosity of the navicular bone (FNT); first, second and fifth

556 metatarsal base (FMB, SMB, FMT); first, second and fifth metatarsal head (FM1, FM2,

557 FM5); PD6: distal dorso-medial aspect of the head of the proximal phalanx of the

558 hallux; hallux-metatarsus joint center (FM1; midfoot-metatarsus center (SMB);

calcaneus-midfoot center (ID); B) Experimental apparatus with the instrumented footover the platforms.

Figure 2: A) Positive and negative mechanical work contributions from subareas
within the foot and ankle Preop : Pre-operative data (blue), postop : postoperative data
(green), ctrl : control data (grey); B) The total foot and ankle positive and negative
mechanical work contributions from subareas within the foot and ankle : Preop : Preoperative data (blue), postop : postoperative data (green), ctrl : control data (grey); C)

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566 The total net mechanical work from the total foot and ankle structures : Preop : Pre-

567 operative data (blue), postop : postoperative data (green), ctrl : control data (grey);

Figure 3: Relative contribution of each foot and ankle joint (Ankle (Sha-Cal) joint = 568 blue. Chopart (Cal-Mid) joint = orange. Lisfranc (Mid-Met) joint = grev. MTP1 (Met-569 Hx) = yellow) to the total foot and ankle joint positive work during level walking 570 preoperatively, 1 year postoperatively and compared to a control group. To show the 571 percentage of mechanical work that each joint contributed to the total work of the foot 572 573 and ankle, the work of individual joints has been divided by the total positive work of 574 the foot and ankle. The contribution of the foot and ankle totals 1.0, and a comparison 575 between pre- and postoperatively indicates which joint changes the most after TAR, 576 and if the joint work distribution across the intrinsic joints of the foot are similar to the values of the control group of asymptomatic subjects. The height of each bar represents 577 578 the mean for the total sample.

Figure 4: Relative contribution of each foot and ankle joint (Ankle (Sha-Cal) joint = 579 blue, Chopart (Cal-Mid) joint = orange, Lisfranc (Mid-Met) joint = grey, MTP1 (Met-580 581 Hx) = yellow) to the total foot and ankle joint negative work during level walking preoperatively, 1 year postoperatively and compared to a control group. To show the 582 583 percentage of mechanical work that each joint contributed to the total work of the foot 584 and ankle, the work of individual joints has been divided by the total positive work of the foot and ankle. The contribution of the foot and ankle totals 1.0, and a comparison 585 between pre- and postoperatively indicates which joint changes the most after TAR, 586 587 and if the joint work distribution across the intrinsic joints of the foot are similar to the 588 values of the control group of asymptomatic subjects. The height of each bar represents the mean for the total sample. 589

590 Supplementary material 1: A priori power analysis

591 Supplementary material 2: Joint angles, moments and power waveforms

592 representation with +/- 1 standard deviation cloud for the intrinsic foot joints between

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the groups (pre- and postoperative patient and control groups) during the stance phase
of gait: Sha-Cal: shank-calcaneus; Cal-Mid: calcaneus-midfoot; Midt-Met: midfootmetatarsus; Met-Hx: hallux-metatarsus: Pre-operative condition in green and postoperative condition in blue; control group in red; DF: dorsiflexion ; PF: plantarflexion;

Add: Adduction ; Abd : Abduction ; Inv: Inversion ; Ev: Eversion.

for per peries

| Table 1: Participant's demographic data (Abbreviations: Ankle OA, | , Ankle Osteoarthritis; CTRL, | Control; SD, Standard Deviation) |
|---|-------------------------------|----------------------------------|
| | | |

| Damagnankias | Ankle | OA | СТ | RL | Ankle OA vs CTRL | | | | | |
|-----------------|-------|-------|-------|-------|------------------|--|--|--|--|--|
| Demographics | Mean | SD | Mean | SD | (P value) | | | | | |
| Age (years) | 59.07 | 9.78 | 57.80 | 9.17 | 0.717 | | | | | |
| Height (meters) | 1.71 | 0.08 | 1.73 | 0.08 | 0.504 | | | | | |
| Weight (kg) | 78.00 | 14.57 | 76.40 | 16.60 | 0.781 | | | | | |
| BMI | 26.63 | 4.41 | 25.36 | 4.26 | 0.428 | | | | | |
| Gender (M/F) | 10 : | 5 | 7 | 8 | Not applicable | | | | | |
| | | | | | | | | | | |

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Table 2: Participant's spatiotemporal data (Abbreviations: Ankle OA, Ankle Osteoarthritis; CTRL, Control; SD, Standard Deviation; m, meters; preop, preoperative; postop, post-operative)

| Spatio-temporal factors | | Ankle OA | | CTR | L | Preop versus Postop | | | |
|-------------------------|--------|----------|------|-----------|------|---------------------|--|--|--|
| | | Mean | SD | Mean | SD | (P value) | | | |
| Walking speed | Preop | 1.02 | 0.13 | 1.22 0.12 | | .001 | | | |
| (m/s) | Postop | 1.20 | 0.11 | 1.22 | 0.12 | .001 | | | |
| Cycle Length (m) | Preop | 1.14 | 0.15 | 1.32 | 0.11 | < .001 | | | |
| | Postop | 1.29 | 0.13 | 1.52 | 0.11 | <.001 | | | |
| | | | | | | | | | |

Table 3: Absolute joint work (J/kg) across the intrinsic joints of the foot during level walking preoperatively, 1 year postoperatively and compared to a control group. (Abbreviations: Ankle OA, Ankle Osteoarthritis; CTRL. Control; SD, Standard Deviation; J, Joule; preop, pre-operative; postop, post-operative)

| Positive Work (J/kg) | PREOP | SD | POSTOP | SD | CTRL | SD | Pre-op vs Post-op (P value) | Post-op vs CTRL (P value) |
|----------------------------------|-------|-------|--------|-------|-------|-------|--------------------------------|------------------------------|
| Ankle (Shank-Calcaneus) | 0.09 | 0.05 | 0.15 | 0.05 | 0.22 | 0.04 | < .001 | < .001 |
| Chopart (Calcaneus-Midfoot) | 0.03 | 0.01 | 0.03 | 0.01 | 0.04 | 0.02 | .730 | .076 |
| Lisfranc (Midfoot-Metatarsus) | 0.04 | 0.02 | 0.07 | 0.02 | 0.09 | 0.03 | < .001 | .037 |
| MTP1 (Metatarsus-Hallux) | 0.002 | 0.002 | 0.004 | 0.003 | 0.003 | 0.002 | .007 | .320 |
| Total Positive Work (J/kg) | 0.16 | 0.06 | 0.25 | 0.06 | 0.35 | 0.06 | < .001 | < .001 |
| Negative Work (J/kg) | PREOP | SD | POSTOP | SD | CTRL | SD | Pre-op vs Post-op (P value) | Post-op vs CTRL (P value) |
| Ankle (Shank-Calcaneus) | -0.07 | 0.04 | -0.1 | 0.04 | -0.12 | 0.04 | .003 | .062 |
| Chopart (Calcaneus-Midfoot) | -0.05 | 0.02 | -0.05 | 0.02 | -0.06 | 0.02 | .587 | .312 |
| Lisfranc (Midfoot-Metatarsus) | -0.01 | 0.005 | -0.01 | 0.01 | -0.01 | 0.01 | .106 | .457 |
| MTP1 (Metatarsus-Hallux) | -0.02 | 0.03 | -0.04 | 0.03 | -0.06 | 0.04 | .022 | .100 |
| Total Negative Work (J/kg) | -0.15 | 0.06 | -0.20 | 0.05 | -0.25 | 0.07 | .001 | .035 |
| Total Net Work (J/kg) | 0.01 | 0.05 | 0.05 | 0.05 | 0.10 | 0.06 | .006 | .017 |

Table 4: Normalized joint work across the intrinsic joints of the foot during level walking preoperatively, 1 year postoperatively and compared to a control group. (Abbreviations: Ankle OA, Ankle Osteoarthritis; CTRL. Control; SD, Standard Deviation; J, Joule; preop, pre-operative; postop, post-operative)

| Positive Work | PREOP | SD | POSTOP | SD | CTRL | SD | Pre-op vs Post-op (P value) | Post-op vs CTRL (P value) |
|----------------------------------|-------|------|--------|------|-------|------|--------------------------------|------------------------------|
| Ankle (Shank-Calcaneus) | 52.4% | 9.8% | 57.2% | 7.4% | 61.7% | 4.6% | .007 | .026 |
| Chopart (Calcaneus-Midfoot) | 21.6% | 7.6% | 13.5% | 5.5% | 12.2% | 5.4% | < .001 | .531 |
| Lisfranc (Midfoot-Metatarsus) | 24.3% | 7.4% | 28.6% | 6.6% | 25.3% | 4.5% | .014 | .142 |
| MTP1 (Metatarsus-Hallux) | 1.8% | 1.4% | 1.1% | 1.1% | 0.6% | 0.7% | .599 | .056 |

| Negative Work | PREOP | SD | POSTOP | SD | CTRL | SD | Pre-op vs Post-op (P value) | Post-op vs CTRL (P value) |
|----------------------------------|-------|-------|--------|-------|-------|-------|--------------------------------|------------------------------|
| Ankle (Shank-Calcaneus) | 43.9% | 16.2% | 48.6% | 13.7% | 48.1% | 11.1% | .200 | .456 |
| Chopart (Calcaneus-Midfoot) | 35.5% | 17.8% | 27.4% | 15.5% | 24.6% | 3.0% | .018 | .999 |
| Lisfranc (Midfoot-Metatarsus) | 6.4% | 2.8% | 6.9% | 4.4% | 4.9% | 6.8% | .599 | .229 |
| MTP1 (Metatarsus-Hallux) | 14.1% | 13.2% | 17.2% | 13.4% | 22.4% | 11.2% | .151 | .256 |

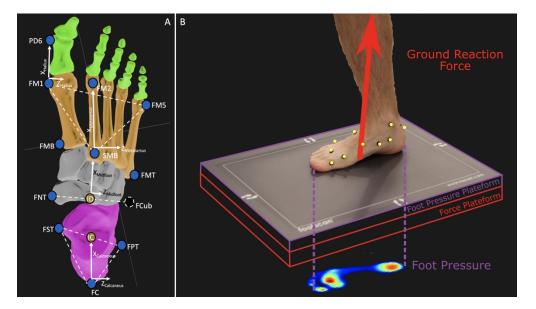


Figure 1: A) Inter-segment center definitions were defined according to an adapted version of Rizzoli foot model (Leardini et al. 2007) developed by Deschamps et al. (2017) (IOR-4Segment-model 1). Markers name: upper ridge of the posterior surface of the calcaneus (FC); peroneal tubercle (FPT); sustentaculum tali (FST); virtual cuboid marker (FCub), tuberosity of the navicular bone (FNT); first, second and fifth metatarsal base (FMB, SMB, FMT); first, second and fifth metatarsal head (FM1,FM2, FM5); PD6: distal dorso-medial aspect of the head of the proximal phalanx of the hallux; hallux-metatarsus joint center (FM1; midfoot-metatarsus center (SMB); calcaneus-midfoot center (ID); B) Experimental apparatus with the instrumented foot over the platforms.

624x353mm (144 x 144 DPI)

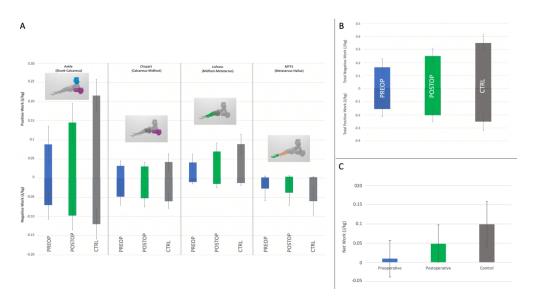


Figure 2: A) Positive and negative mechanical work contributions from subareas within the foot and ankle Preop : Pre-operative data (blue), postop : postoperative data (green), ctrl : control data (grey); B) The total foot and ankle positive and negative mechanical work contributions from subareas within the foot and ankle : Preop : Pre-operative data (blue), postop : postoperative data (green), ctrl : control data (grey); C) The total net mechanical work from the total foot and ankle structures : Preop : Pre-operative data (blue), postop : postoperative data (green), ctrl : control data (grey);

451x244mm (144 x 144 DPI)

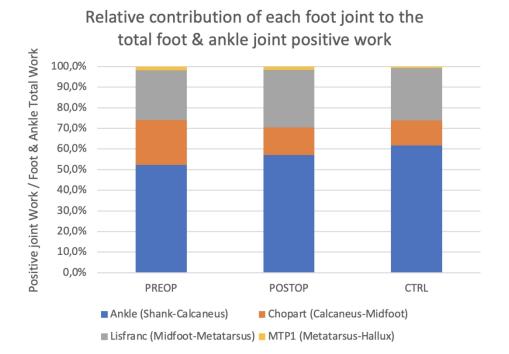


Figure 3: Relative contribution of each foot and ankle joint (Ankle (Sha-Cal) joint = blue, Chopart (Cal-Mid) joint = orange, Lisfranc (Mid-Met) joint =grey, MTP1 (Met-Hx) = yellow) to the total foot and ankle joint positive work during level walking preoperatively, 1 year postoperatively and compared to a control group. To show the percentage of mechanical work that each joint contributed to the total work of the foot and ankle, the work of individual joints has been divided by the total positive work of the foot and ankle. The contribution of the foot and ankle totals 1.0, and a comparison between pre- and postoperatively indicates which joint changes the most after TAR, and if the joint work distribution across the intrinsic joints of the foot are similar to the values of the control group of asymptomatic subjects. The height of each bar represents the mean for the total sample.

249x183mm (144 x 144 DPI)

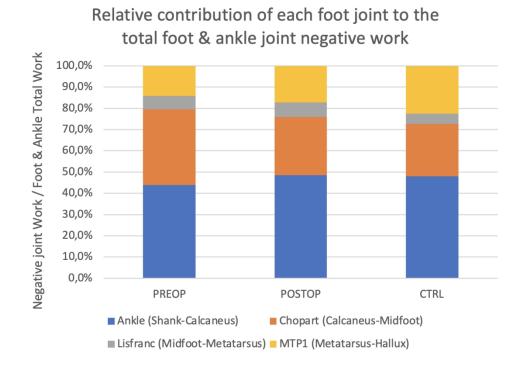


Figure 4: Relative contribution of each foot and ankle joint (Ankle (Sha-Cal) joint = blue, Chopart (Cal-Mid) joint = orange, Lisfranc (Mid-Met) joint =grey, MTP1 (Met-Hx) = yellow) to the total foot and ankle joint negative work during level walking preoperatively, 1 year postoperatively and compared to a control group. To show the percentage of mechanical work that each joint contributed to the total work of the foot and ankle, the work of individual joints has been divided by the total positive work of the foot and ankle. The contribution of the foot and ankle totals 1.0, and a comparison between pre- and postoperatively indicates which joint changes the most after TAR, and if the joint work distribution across the intrinsic joints of the foot are similar to the values of the control group of asymptomatic subjects. The height of each bar represents the mean for the total sample.

242x176mm (144 x 144 DPI)

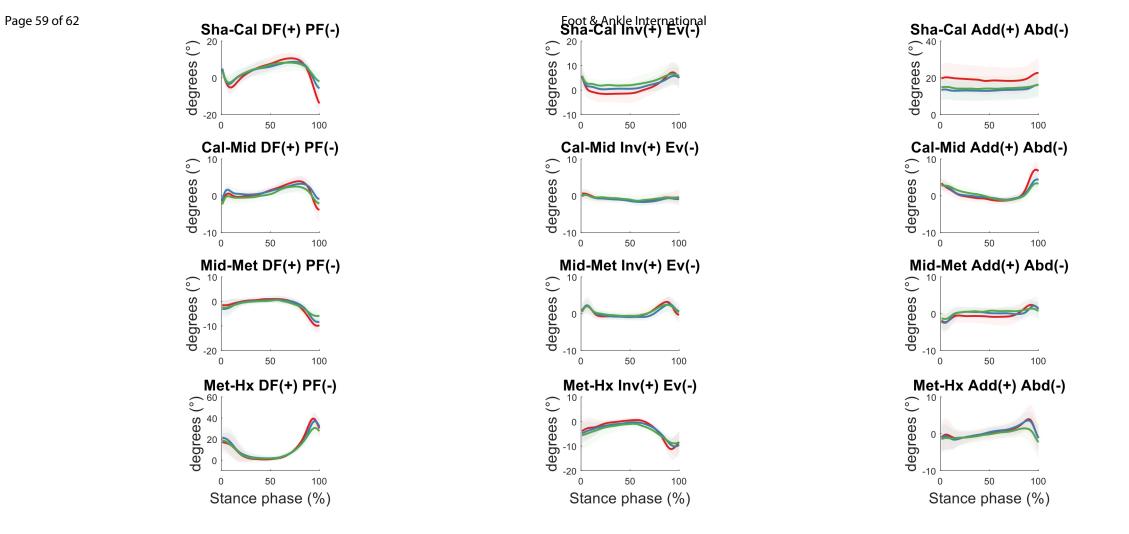
Supplementary material 1

G*Power (Version 3.1.9.6) was used to perform an a priori power analysis for a dependent groups t test comparing pre- and post-operative conditions in patients suffering from end-stage ankle osteoarthritis. This sample size provides 80% power and a p-value at 0.05 to detect a higher contribution of the ankle joint to the total foot and ankle positive and negative work after surgery and a lower contribution of the adjacent Chopart joint of the affected ankle to the total foot and ankle positive and negative work after surgery. The hypothetical effect size for this analysis was estimated based on pilot results reported by Deleu et al. (2021).

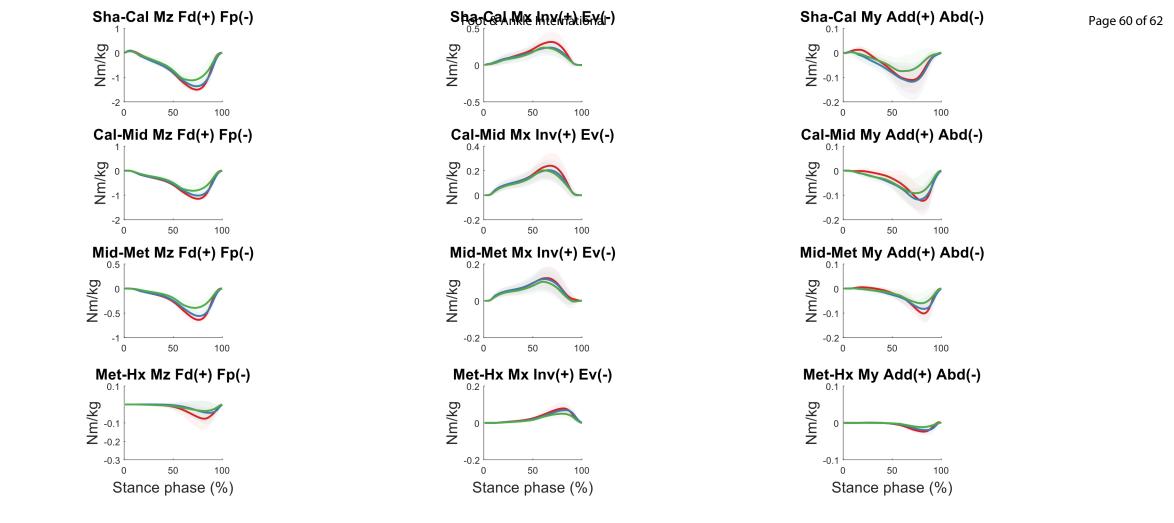
| Sagittal ankle joint range of motion variables | Mean Pre- op to Post- op difference | Pooled Standard Deviation | Effect size (δ) | Power | Alpha | Tails | N |
|---|--|---------------------------------|--------------------|-------|-------|------------|----|
| Shank-Calcaneus Relative Positive Work Contribution | 5% | 7% | 0.714 | 0.800 | 0.05 | One-tailed | 14 |
| Shank-Calcaneus Relative NegativeWork Contribution | 9.5% | 13.8% | 0.687 | 0.800 | 0.05 | One-tailed | 15 |
| Calcaneus-Midfoot Relative Positive Work Contribution | 7% | 6.3% | -0.707 | 0.800 | 0.05 | One-tailed | 14 |
| Calcaneus-Midfoot Relative NegativeWork Contribution | 13.8% | 12.5% | -1.10 | 0.800 | 0.05 | One-tailed | 8 |

References

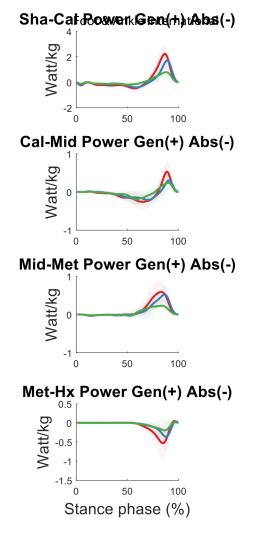
Deleu PA, Naaim A, Leemrijse T, et al. Impact of foot modeling on the quantification of the effect of total ankle replacement: A pilot study. *Gait Posture*. 2021;84(December 2020):308-314. doi:10.1016/j.gaitpost.2020.12.027.



Joint angle waveforms representation with +/- 1 standard deviation cloud for the intrinsic foot joints between the groups (pre- and postoperative patient and control groups) during the stance phase of gait: Sha-Cal: shank-calcaneus; Cal-Mid: calcaneus-midfoot; Mid-Met: midfoot-metatarsus; Met-Hx: hallux-metatarsus: Pre-operative condition in green and post-operative condition in blue; control group in red; DF: dorsiflexion ; PF: http://mc.manuscriptcentral.com/fai
plantarflexion; Add: Adduction ; Abd :Abduction ; Inv: Inversion ; Ev: Eversion.



Joint moments waveforms representation with +/- 1 standard deviation cloud for the intrinsic foot joints between the groups (pre- and postoperative patient and control groups) during the stance phase of gait: Sha-Cal: shank-calcaneus; Cal-Mid: calcaneus-midfoot; Mid-Met: midfoot-metatarsus; Met-Hx: hallux-metatarsus: Pre-operative condition in green and post-operative condition in blue; control group in red; DF: dorsiflexion ; PF: http://mc.manuscriptcentral.com/fai
plantarflexion; Add: Adduction ; Abd :Abduction ; Inv: Inversion ; Ev: Eversion. Page 61 of 62



Joint power waveforms representation with +/- 1 standard deviation cloud for the intrinsic foot joints between the groups (pre- and postoperative

patient and control groups) during the stance phase of gait: Sha-Cal: shank-calcaneus; Cal-Mid: calcaneus-midfoot; Mid-Met: midfoot-metatarsus;

Met-Hx: hallux-metatarsus: Pre-operative condition in green and post-operative condition in blue; control group in red; DF: dorsiflexion; PF:

http://mc.manuscriptcentral.com/fai plantarflexion; Add: Adduction ; Abd :Abduction ; Inv: Inversion ; Ev: Eversion.