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ON A DISCRETE FRAMEWORK OF HYPOCOERCIVITY FOR KINETIC EQUATIONS

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ABSTRACT. We propose and study a fully discrete finite volume scheme for the Vlasov-Fokker-Planck equation written as an hyperbolic system using Hermite polynomials in velocity. This approach naturally preserves the stationary solution and the weighted L^2 relative entropy. Then, we adapt the arguments developed in [12] based the hypocoercivity method to get quantitative estimates on the convergence to equilibrium of the discrete solution. Finally, we prove that in the diffusive limit, the scheme is asymptotic preserving with respect to both the time variable and the scaling parameter at play.

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1. INTRODUCTION

The Vlasov-Fokker-Planck equation is the kinetic description of the Brownian motion of a large system of charged particles under the effect of an electric field. For example, in electrostatic plasma, where the Coulomb force are taken into account, the time evolution of the electron distribution function f solves the

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Vlasov-Poisson-Fokker-Planck system, under the action of a self-consistent potential Φ :

$$\begin{cases} \frac{\partial f}{\partial t} + \mathbf{v} \cdot \nabla_{\mathbf{x}} f + \frac{q_e}{m_e} \mathbf{E} \cdot \nabla_{\mathbf{v}} f = \frac{1}{\tau_e} \operatorname{div}_{\mathbf{v}} (\mathbf{v} f + T_0 \nabla_{\mathbf{v}} f) , \\ -\varepsilon_0 \Delta \Phi = q_e \int_{\mathbb{R}^3} f d\mathbf{v} , \end{cases}$$

where ε_0 is the vacuum permittivity, q_e and m_e are elementary charge and mass of the electrons, whereas τ_e is the relaxation time due to the collisions of the particles with the surrounding bath.

Considering $\varepsilon > 0$ as the ratio between the mean free path of particles and the length scale of observation, it allows to identify different regimes and the Vlasov equation may be written in a adimensional form

$$(1.1) \quad \varepsilon \frac{\partial f}{\partial t} + \mathbf{v} \cdot \nabla_{\mathbf{x}} f + \mathbf{E} \cdot \nabla_{\mathbf{v}} f = \frac{\varepsilon}{\tau(\varepsilon)} \operatorname{div}_{\mathbf{v}} (\mathbf{v} f + T_0 \nabla_{\mathbf{v}} f) ,$$

Our main purpose here is to build and analyse a numerical scheme able to capture two regimes of interest for equation (1.1), in a linear framework: the long time behavior $t \rightarrow \infty$ and the diffusive regime $\varepsilon \rightarrow 0$. In various situations, the scaling parameters at play may be non homogeneous across the system leading to intricate situations, where both processes may coexist. Thus, we aim at designing a scheme robust enough to capture simultaneously these different behaviors.

More precisely, we consider the one dimensional Vlasov-Fokker-Planck equation with periodic boundary conditions in space, which reads

$$(1.2) \quad \partial_t f + \frac{1}{\varepsilon} (v \partial_x f + E \partial_v f) = \frac{1}{\tau(\varepsilon)} \partial_v (v f + T_0 \partial_v f) ,$$

with $t \geq 0$, position $x \in \mathbb{T}$ and velocity $v \in \mathbb{R}$, whereas the electric field derives from a potential Φ such that $E = -\partial_x \Phi$, with the following regularity assumption

$$(1.3) \quad \Phi \in W^{2,\infty}(\mathbb{T}) .$$

We also define the density ρ by integrating the distribution function in velocity,

$$(1.4) \quad \rho(t, x) = \int_{\mathbb{R}} f(t, x, v) dv .$$

It is worth to mention that there are already several works on preserving large-time behaviors of solutions to the Fokker-Planck equation or related kinetic models. On the one hand, a fully discrete finite difference scheme for the homogeneous Fokker-Planck equation has been proposed in the pioneering work of Chang and Cooper [9]. This scheme preserves the stationary solution and the entropy decay of the numerical solution. On the other hand, finite volume schemes preserving the exponential trend to equilibrium have been studied for non-linear convection-diffusion equations (see for example [2, 6, 7, 19]). More recently, in [27], the authors investigate the question of describing correctly the equilibrium state of non-linear diffusion and kinetic models for high order schemes. Let us also mention some works on boundary value problems [14, 8] where non-homogeneous Dirichlet boundary conditions are dealt with.

In the case of space non homogeneous kinetic equations, the convergence to equilibrium becomes tricky because of the lack of coercivity since dissipation occurs only in the velocity variable whereas transport acts in the space variable. Therefore, only few results are available and a better understanding of hypocoercive structures at the discrete level is challenging. Let us mention a first rigorous work in this direction on the Kolmogorov equation [28, 17, 18]. In [17], a time-splitting scheme is applied and it is shown that solutions decay polynomially in time. In [28, 18], a different approach has been used, based on the work of Hérau [20] and Villani [31], for finite difference and a finite element schemes. Later, Dujardin, Hérau and Lafitte [13] studied a finite difference scheme for the kinetic Fokker-Planck equation. Finally, in a more recent work [5], the authors established a discrete hypocoercivity framework based on the continuous approach provided in [12]. It is based on a modified discrete entropy, equivalent to a weighted L^2 norm involving macroscopic quantities and the authors show quantitative estimates on the numerical solution for large time and in the limit $\varepsilon \rightarrow 0$.

The present contribution can be considered as a continuation of this latter work in order to discretize the kinetic Fokker-Planck equation with an applied force field. On the one hand, we consider the case where the interactions associated to collisions and electrostatic effects have the same magnitude, that is, $\tau(\varepsilon) \sim \varepsilon$, hence the limit $t/\varepsilon \rightarrow +\infty$ corresponds to the long time behavior of equation (1.2). In this

regime, the distribution function f relaxes towards the stationary solution to the Vlasov-Fokker-Planck equation $\rho_\infty \mathcal{M}$, where the Maxwellian \mathcal{M} is given by

$$\mathcal{M}(v) = \frac{1}{\sqrt{2\pi T_0}} \exp\left(-\frac{|v|^2}{2T_0}\right),$$

whereas the density ρ_∞ is determined by

$$(1.5) \quad \rho_\infty = c_0 \exp\left(-\frac{\Phi}{T_0}\right),$$

where the constant c_0 is fixed by the conservation of mass, that is,

$$\int_{\mathbb{T}} \rho_\infty dx = \iint_{\mathbb{T} \times \mathbb{R}} f_0(x, v) dv dx.$$

Thus, we set f_∞ the stationary state of (1.2), defined as

$$f_\infty(x, v) = \rho_\infty(x) \mathcal{M}(v)$$

and we expect that $f \rightarrow f_\infty$ as $t/\varepsilon \rightarrow +\infty$.

On the other hand, the diffusive regime corresponds to a frontier where collisions dominate but still not enough to cancel completely the electrostatic effects. This situation occurs as $\varepsilon \rightarrow 0$ in the case where $\tau(\varepsilon) \sim \tau_0 \varepsilon^2$, for some $\tau_0 > 0$. Due to collisions, the distribution of velocities also relaxes towards a Maxwellian equilibrium. However, in this case, the spatial distribution converges to a time dependent distribution ρ whose dynamics are driven by a drift-diffusion equation depending on the force field E . Indeed, performing the change of variable $x \rightarrow x + \tau_0 \varepsilon v$ in (1.2) and integrating with respect to v , we deduce that the quantity

$$\pi(t, x) = \int_{\mathbb{R}} f(t, x - \tau_0 \varepsilon v, v) dv,$$

solves the following equation

$$\partial_t \pi + \tau_0 \partial_x \left(\int_{\mathbb{R}} E f(t, x - \tau_0 \varepsilon v, v) dv - T_0 \partial_x \pi \right) = 0.$$

According to its definition, π verifies: $\rho \sim \pi$ in the limit $\varepsilon \rightarrow 0$. Therefore, we may formally replace π with ρ and ε with 0 in the latter equation. This yields

$$f(t, x, v) \xrightarrow{\varepsilon \rightarrow 0} \rho_{\tau_0}(t, x) \mathcal{M}(v),$$

where ρ_{τ_0} solves

$$(1.6) \quad \partial_t \rho_{\tau_0} + \tau_0 \partial_x (E \rho_{\tau_0} - T_0 \partial_x \rho_{\tau_0}) = 0.$$

To be noted that this regime is an intermediate situation which contains more information than the long time asymptotic since we have $\rho \rightarrow \rho_\infty$ by taking either $t \rightarrow +\infty$ or $\tau_0 \rightarrow +\infty$.

At the discrete level, Asymptotic-Preserving schemes have been developed to capture in a discrete setting the diffusion limit, so that in the limit $\varepsilon \rightarrow 0$, the numerical discretization converges to the macroscopic model (see for instance [23, 26, 22, 25] on finite difference and finite volume schemes and [11, 10] on particle methods).

In the present article, our aim is to design a numerical scheme which is able to capture these two regimes but also all the intermediate situations where $\varepsilon^2 \lesssim \tau(\varepsilon) \lesssim \varepsilon$. More precisely, we suppose that

$$(1.7) \quad \sup_{\varepsilon > 0} \frac{\tau(\varepsilon)}{\varepsilon} \leq \bar{\tau}_0 \in (0, +\infty).$$

and distinguish two cases on $\tau(\varepsilon)$:

(i) either the diffusive regime assumption

$$(1.8) \quad \frac{\tau(\varepsilon)}{\varepsilon^2} \xrightarrow{\varepsilon \rightarrow 0} \tau_0 < +\infty,$$

where collisional effects strongly dominate;

(ii) or the intermediate regime assumption

$$(1.9) \quad \frac{\tau(\varepsilon)}{\varepsilon^2} \xrightarrow{\varepsilon \rightarrow 0} +\infty,$$

which may for instance correspond to $\tau(\varepsilon) = \varepsilon^\beta$, with $1 \leq \beta < 2$. It describes all the intermediate situations between long time and diffusive regime.

The starting point of our analysis is the following estimate, obtained multiplying equation (1.2) by f/f_∞ , and balancing the transport term with the source term corresponding to the electric field thanks to the weight f_∞^{-1}

$$(1.10) \quad \frac{1}{2} \frac{d}{dt} \int_{\mathbb{T}^d \times \mathbb{R}^d} |f - f_\infty|^2 f_\infty^{-1} dv dx + \frac{T_0}{\tau(\varepsilon)} \int_{\mathbb{T} \times \mathbb{R}} \left| \partial_v \left(\frac{f}{f_\infty} \right) \right|^2 f_\infty dv dx = 0.$$

This estimate is important since it yields a L^2 stability result on the solution to the Vlasov-Fokker-Planck equation (1.2).

Our purpose is to design a numerical scheme for which such estimate occurs. To this aim, we split our approach in two steps: we apply a spectral decomposition in velocity of f based on Hermite decomposition and we apply a structure preserving finite volume scheme for the space discretization. In the next section (Section 2), we provide explicit convergence rates for the continuous model written in the Hermite basis (see Theorems 2.1 and 2.2). This first step allows us to present the general strategy and to highlight the main properties of the transport operator in order to design suitable numerical scheme. Therefore, in Section 3 we adapt these latter results without any loss to the fully discrete setting using a structure preserving finite volume scheme and an implicit Euler scheme for the time discretization (see Theorems 3.1 and 3.2). The variety of situations that we aim to cover may lead to various and intricate behaviors. Therefore, we successfully put great efforts into providing results which are uniform with respect to all parameters at play: time t , scaling parameters (ε, τ_0) and eventually the numerical discretization. The result is worth the pain, since we propose in the Section 4 various simulations, in which we are able to capture, at low computational cost, a rich variety of situations.

2. HERMITE'S DECOMPOSITION FOR THE VELOCITY VARIABLE

The purpose of this section is to present a formulation of the Vlasov-Fokker-Planck equation (1.2) based on Hermite polynomial and to provide quantitative results on f when $\varepsilon \rightarrow 0$ and $t \rightarrow +\infty$. These results are identical to the ones obtained in the continuous case except that there are formulated on the corresponding Hermite's coefficients solution to a linear hyperbolic system. This formulation is well adapted to prepare the fully discrete setting in Section 3.

We first use Hermite polynomials in the velocity variable and write the Vlasov-Fokker-Planck equation (1.2) as an infinite hyperbolic system for the Hermite coefficients depending only on time and space. The idea is to apply a Galerkin method only keeping a small finite set of orthogonal polynomials rather than discretizing the distribution function in velocity [1, 24]. The merit to use orthogonal basis like the so-called scaled Hermite basis has been shown in [21, 30, 29] or more recently [16, 4] for the Vlasov-Poisson system. In this context the family of Hermite's functions $(\Psi_k)_{k \in \mathbb{N}}$ defined as

$$\Psi_k(v) = H_k \left(\frac{v}{\sqrt{T_0}} \right) \mathcal{M}(v),$$

constitutes an orthonormal system for the inverse Gaussian weight, that is,

$$\int_{\mathbb{R}} \Psi_k(v) \Psi_l(v) \mathcal{M}^{-1}(v) dv = \delta_{k,l}.$$

In the latter definition, $(H_k)_{k \in \mathbb{N}}$ stands for the family of Hermite polynomials defined recursively as follows $H_{-1} = 0$, $H_0 = 1$ and

$$\xi H_k(\xi) = \sqrt{k} H_{k-1}(\xi) + \sqrt{k+1} H_{k+1}(\xi), \quad \forall k \geq 0.$$

Let us also point out that Hermite's polynomials verify the following relation

$$H'_k(\xi) = \sqrt{k} H_{k-1}(\xi), \quad \forall k \geq 0.$$

Taking advantage of the latter relations, one can see why Hermite's functions arise naturally when studying the Vlasov-Poisson-Fokker-Planck model, especially in the diffusive regime, as they constitute an orthonormal basis which diagonalizes the Fokker-Planck operator:

$$\partial_v [v \Psi_k + T_0 \partial_v \Psi_k] = -k \Psi_k.$$

Therefore, we consider the decomposition of f into its components $C = (C_k)_{k \in \mathbb{N}}$ in the Hermite basis

$$(2.1) \quad f(t, x, v) = \sum_{k \in \mathbb{N}} C_k(t, x) \Psi_k(v).$$

It's worth to mention that we also may consider a truncated series neglecting high order coefficient in order to construct a spectrally accurate approximation of f in the velocity variable.

As we have shown before, Hermite's decomposition with respect to the velocity variable is a suitable choice in our setting. When it comes to the space variable, we see from estimate (1.10) that the natural functional framework here is the L^2 space with weight ρ_∞^{-1} . Unfortunately, it is not very well adapted to the space discretization since it may generate additional spurious terms difficult to control when dealing with discrete integration by part. We bypass this difficulty by integrating the weight in the quantity of interest: instead of working directly with f , we consider the quantity $f / \sqrt{\rho_\infty}$ in order to get a well-balanced scheme in the same spirit to what has been already done in [8, 14] for well-balanced finite volume schemes. More precisely, we set

$$D_k := \frac{C_k}{\sqrt{\rho_\infty}}$$

in (2.1), and inject this ansatz in (1.2). Using that $\rho_\infty E = T_0 \partial_x \rho_\infty$, we get that $D = (D_k)_{k \in \mathbb{N}}$ satisfies the following system

$$(2.2) \quad \begin{cases} \partial_t D_k + \frac{1}{\varepsilon} \left(\sqrt{k} \mathcal{A} D_{k-1} - \sqrt{k+1} \mathcal{A}^* D_{k+1} \right) = -\frac{k}{\tau(\varepsilon)} D_k, \\ D_k(t=0) = D_k^{0,\varepsilon}, \end{cases}$$

where operators \mathcal{A} and \mathcal{A}^* are given by

$$\begin{cases} \mathcal{A} u = +\sqrt{T_0} \partial_x u - \frac{E}{2\sqrt{T_0}} u, \\ \mathcal{A}^* u = -\sqrt{T_0} \partial_x u - \frac{E}{2\sqrt{T_0}} u. \end{cases}$$

In this framework, the equilibrium D_∞ to (2.2) is given by

$$(2.3) \quad D_{\infty,k} = \begin{cases} \sqrt{\rho_\infty}, & \text{if } k = 0, \\ 0, & \text{else,} \end{cases}$$

and estimate (1.10) simply rewrites

$$(2.4) \quad \frac{1}{2} \frac{d}{dt} \|D(t) - D_\infty\|_{L^2}^2 + \frac{1}{\tau(\varepsilon)} \sum_{k \in \mathbb{N}^*} k \|D_k(t)\|_{L^2(\mathbb{T})}^2 = 0,$$

where $\|\cdot\|_{L^2}$ stands for the overall L^2 -norm **with no weight**

$$\|D\|_{L^2}^2 = \sum_{k \in \mathbb{N}} \|D_k\|_{L^2(\mathbb{T})}^2.$$

On top of that, the limit of the diffusive regime is given by $D_{\tau_0} = (D_{\tau_0,k})_{k \in \mathbb{N}}$ defined as follows

$$(2.5) \quad D_{\tau_0,k} = \begin{cases} D_{\tau_0,0}, & \text{if } k = 0, \\ 0, & \text{else,} \end{cases}$$

where the first Hermite coefficient $D_{\tau_0,0}$ solves the following drift-diffusion equation

$$(2.6) \quad \partial_t D_{\tau_0,0} + \tau_0 \mathcal{A}^* \mathcal{A} D_{\tau_0,0} = 0,$$

which is obtained substituting ρ_{τ_0} with $D_{\tau_0,0} \sqrt{\rho_\infty}$ in equation (1.6).

To conclude this section, we introduce some additional norms which arise naturally along our analysis. In Section 2.3, we consider the following H^{-1} norm defined on the L^2 subspace orthogonal to $\sqrt{\rho_\infty}$: for all $g \in L^2(\mathbb{T})$ which meets the condition

$$(2.7) \quad \int_{\mathbb{T}} g \sqrt{\rho_\infty} \, dx = 0,$$

we set

$$\|g\|_{H^{-1}} = \|\mathcal{A}u\|_{L^2(\mathbb{T})},$$

where u solves the following elliptic equation

$$(2.8) \quad \begin{cases} \mathcal{A}^* \mathcal{A} u = g, \\ \int_{\mathbb{T}} u \sqrt{\rho_\infty} \, dx = 0. \end{cases}$$

The latter equation admits a unique solution in $H^2(\mathbb{T})$ for any data $g \in L^2(\mathbb{T})$ that meets the compatibility condition (2.7). This well-posedness result crucially relies on the Poincaré inequality (2.18).

In Section 2.3, we use the following H^1 norm, defined for all $D = (D_k)_{k \in \mathbb{N}}$ as follows

$$\|\mathcal{B}D\|_{L^2}^2 = \sum_{k \in \mathbb{N}} \|\mathcal{B}_k D_k\|_{L^2(\mathbb{T})}^2,$$

where the family of differential operator $\mathcal{B} = (\mathcal{B}_k)_{k \geq 0}$ is defined as follows

$$(2.9) \quad \mathcal{B}_k = \begin{cases} \mathcal{A}, & \text{if } k = 0, \\ \mathcal{A}^*, & \text{else.} \end{cases}$$

To end with, we introduce the notation $D_\perp = (D_{\perp,k})_{k \in \mathbb{N}}$, which corresponds to the Hermite coefficients of $f - \rho \mathcal{M}$, that is

$$(2.10) \quad D_{\perp,k} = \begin{cases} 0, & \text{if } k = 0, \\ D_k, & \text{else,} \end{cases}$$

so that

$$\|D_\perp\|_{L^2} = \|f - \rho \mathcal{M}\|_{L^2(f_\infty^{-1})}.$$

2.1. Main results. In this section, we present two results which aim at describing the dynamics of (1.2) in various regimes ranging from long time behavior to diffusive limit. We aim for result which capture simultaneously the limits $t \rightarrow +\infty$ and $\varepsilon \rightarrow 0$, in order to lay the groundworks for our upcoming numerical analysis, in which we will build a scheme robust enough so that it captures all these situations.

Our first main result tackles the long time behavior of the solution $D = (D_k)_{k \in \mathbb{N}}$ to (1.2). It is uniform with respect ε and covers all the regimes of interests since we only impose assumption (1.7) on the scaling parameter $\tau(\varepsilon)$. This result is the first step towards its discrete analog, Theorem 3.1

Theorem 2.1. *Suppose that condition (1.7) on $\tau(\varepsilon)$ is satisfied and let $D = (D_k)_{k \in \mathbb{N}}$ be the solution to (2.2) with an initial datum $D^{0,\varepsilon}$. There exists some positive constant C depending only on Φ and T_0 such that*

(i) *under the condition $\|D(0)\|_{L^2} < +\infty$, it holds for all times $t \geq 0$*

$$\|D(t) - D_\infty\|_{L^2} \leq \sqrt{3} \|D(0) - D_\infty\|_{L^2} \exp\left(-\frac{\tau(\varepsilon)}{\varepsilon^2} \kappa t\right);$$

(ii) *under the condition $\|\mathcal{B}D(0)\|_{L^2} + \|D(0)\|_{L^2} < +\infty$, it holds for all times $t \geq 0$*

$$\|\mathcal{B}D(t)\|_{L^2} \leq \sqrt{3} (C(\bar{\tau}_0 + 1) \|D(0) - D_\infty\|_{L^2} + \|\mathcal{B}D(0)\|_{L^2}) \exp\left(-\frac{\tau(\varepsilon)}{\varepsilon^2} \kappa t\right);$$

where $\kappa > 0$ is given by

$$\kappa = \frac{1}{C(\bar{\tau}_0^2 + 1)}.$$

The proof of this result is provided in Section 2.3. The main difficulty here consists in proving the convergence of the first coefficient D_0 in the Hermite decomposition of f towards the equilibrium $\sqrt{\bar{\rho}_\infty}$. We adapt hypocoercivity methods developed in [31, 12] to the framework of Hermite decomposition. Instead of estimating directly the quantities of interest, we introduce modified entropy functionals (see (2.20) and (2.27)), in order to recover dissipation and thus a convergence rate on D_0 . Then, the second item tackles the convergence in a H^1 setting. Though a bit more technical, this second convergence result contains no main additional difficulty in comparison to the L^2 convergence result. Actually this latter result is essentially motivated by the analysis of the regime $\varepsilon \rightarrow 0$ presented below.

This leads us to our second main result, which describes the behavior of the system as ε vanishes. We distinguish the diffusive regime, which corresponds to the case where $\tau(\varepsilon)$ satisfies (1.8) and the intermediate situations between long time and diffusive regime where $\tau(\varepsilon)$ satisfies (1.9). We will adapt this result into the fully discrete setting in Theorem 3.2

Theorem 2.2. *Suppose that $\tau(\varepsilon)$ meets assumption (1.7). For all positive ε , consider $D = (D_k)_{k \in \mathbb{N}}$ the solution to (2.2) with an initial datum $D(0)$ such that*

$$\|D(0)\|_{H^1}^2 := \|\mathcal{B}D(0)\|_{L^2}^2 + \|D(0)\|_{L^2}^2 < +\infty.$$

The following statements hold true uniformly with respect to ε

(i) *suppose that $\tau(\varepsilon)$ satisfies (1.8), that is $\tau(\varepsilon) \sim \tau_0 \varepsilon^2$ and for simplicity, suppose*

$$(2.11) \quad \left| \frac{\tau(\varepsilon)}{\tau_0 \varepsilon^2} - 1 \right| \leq \frac{1}{2}, \quad \forall \varepsilon > 0$$

and consider $D_{\tau_0} = (D_{\tau_0, k})_{k \in \mathbb{N}}$ given by (2.5). On the one hand, it holds for all time $t \in \mathbb{R}^+$

$$\|D_\perp(t)\|_{L^2} \leq \|D_\perp(0)\|_{L^2} e^{-t/(4\tau_0 \varepsilon^2)} + \tau_0 \varepsilon C(\bar{\tau}_0 + 1) \|D(0) - D_\infty\|_{H^1} e^{-\tau_0 \kappa t},$$

where D_\perp is given in (2.10); on the other hand, it holds

$$\begin{aligned} \|D_0(t) - D_{\tau_0, 0}(t)\|_{H^{-1}} &\leq C (\|D_0(0) - D_{\tau_0, 0}(0)\|_{H^{-1}} + \varepsilon \tau_0 (\bar{\tau}_0^3 + 1) \|D(0) - D_\infty\|_{H^1}) e^{-\tau_0 \kappa t} \\ &\quad + C \left| \frac{\tau_0 \varepsilon^2}{\tau(\varepsilon)} - 1 \right| \|D_{\tau_0}(0) - D_\infty\|_{L^2} e^{-\tau_0 \kappa t}; \end{aligned}$$

(ii) *suppose that $\tau(\varepsilon)$ satisfies (1.9), that is $\tau(\varepsilon)/\varepsilon^2 \rightarrow +\infty$ as ε vanishes. Then it holds for all time $t \in \mathbb{R}^+$*

$$\|D_\perp(t)\|_{L^2} \leq \|D_\perp(0)\|_{L^2} e^{-t/(2\tau(\varepsilon))} + \frac{\tau(\varepsilon)}{\varepsilon} C(\bar{\tau}_0 + 1) \|D(0) - D_\infty\|_{H^1} e^{-\frac{\tau(\varepsilon)}{\varepsilon^2} \kappa t},$$

as well as

$$\|D_0(t) - D_{\infty, 0}\|_{H^{-1}} \leq C \left(\|D_0(0) - D_{\infty, 0}\|_{H^{-1}} + \frac{\tau(\varepsilon)}{\varepsilon} (\bar{\tau}_0^3 + 1) \|D(0) - D_\infty\|_{H^1} \right) e^{-\frac{\tau(\varepsilon)}{\varepsilon^2} \kappa t}.$$

In the latter estimate, constant C only depends on Φ and T_0 and exponent κ is given by

$$\kappa = \frac{1}{C(\bar{\tau}_0^2 + 1)}.$$

The proof of this result is provided in Section 2.4, it showcases two major difficulties. The first one is similar to the one encountered in Theorem 2.1; instead of estimating directly the H^{-1} norm between the first Hermite coefficient D_0 and its limit, we find the right intermediate quantity in order to recover dissipation (see (2.29)). However, unlike in the case of Theorem 2.1, we crucially need to incorporate derivatives of the solution D to (1.2) in this quantity in order to obtain some convergence rates. This leads us to the second difficulty, which is that we propagate some regularity. Furthermore, since Theorem 2.2 describes simultaneously the large time behavior and the asymptotic $\varepsilon \rightarrow 0$, it is not sufficient to propagate derivative globally nor uniformly with respect to time, we need instead to prove a convergence result in regular norms. This motivates item (ii) in Theorem 2.1, which will play a key role in our proof. This regularity issue explains why we prove H^{-1} convergence with respect to the first Hermite coefficient whereas we achieve strong L^2 convergence with respect to other coefficients. To be noted that strong L^2 convergence for the first coefficient may be achieved with our method at the price of losing pointwise estimate with respect to time and thus considering integrated norms with respect to the time variable.

Theorems 2.1 and 2.2 fully answer their purpose, which is to describe the dynamics of (1.2) in the regime of interests, uniformly with respect to all parameters at play here.

2.2. Preliminary results. Let us first emphasize the important properties satisfied by \mathcal{A} , which we will need to recover later on, in the discrete setting. First, \mathcal{A}^* is its dual operator in $L^2(\mathbb{T})$, indeed for all $u, v \in H^1(\mathbb{T})$ it holds

$$(2.12) \quad \langle \mathcal{A}^* u, v \rangle = \langle \mathcal{A} v, u \rangle,$$

where $\langle \cdot, \cdot \rangle$ denotes the classical scalar product in $L^2(\mathbb{T})$. Furthermore, we have $D_{\infty,0}$ lies in the kernel of \mathcal{A} , indeed

$$(2.13) \quad \mathcal{A} D_{\infty,0} = 0;$$

in this setting, conservation of mass is ensured by the following property

$$(2.14) \quad \int_{\mathbb{T}} \mathcal{A}^* u \sqrt{\rho_{\infty}} dx = 0,$$

indeed, considering equation (2.2) with index $k = 0$ integrated over \mathbb{T} and applying the latter relation with $u = D_1$, we obtain

$$\frac{d}{dt} \int_{\mathbb{T}} D_0(t) \sqrt{\rho_{\infty}} dx = 0,$$

and therefore

$$(2.15) \quad \int_{\mathbb{T}} D_0(t) \sqrt{\rho_{\infty}} dx = \int_{\mathbb{T}} D_{\infty,0} \sqrt{\rho_{\infty}} dx;$$

we also point out that since

$$\sqrt{T_0} (\mathcal{A} + \mathcal{A}^*) = \partial_x \Phi,$$

it holds

$$(2.16) \quad \| (\mathcal{A} + \mathcal{A}^*) u \|_{L^2} \leq \frac{1}{\sqrt{T_0}} \|\Phi\|_{W^{1,\infty}} \|u\|_{L^2},$$

on top of that, operators \mathcal{A} and \mathcal{A}^* do not commute and we have

$$[\mathcal{A}, \mathcal{A}^*] = \mathcal{A} \mathcal{A}^* - \mathcal{A}^* \mathcal{A} = \partial_{xx} \Phi,$$

which yields

$$(2.17) \quad \| [\mathcal{A}, \mathcal{A}^*] u \|_{L^2} \leq \|\Phi\|_{W^{2,\infty}} \|u\|_{L^2};$$

the last key property verified by operator \mathcal{A} is the following Poincaré-Wirtinger inequality: under the compatibility condition (2.7) on $u \in H^1(\mathbb{T})$ it holds

$$(2.18) \quad \|u\|_{L^2} \leq C_P \sqrt{T_0} \left(\int_{\mathbb{T}} \left| \partial_x \left(\frac{u}{\sqrt{\rho_{\infty}}} \right) \right|^2 \rho_{\infty} dx \right)^{1/2} = C_P \| \mathcal{A} u \|_{L^2},$$

for some positive constant C_P depending only on the potential Φ and T_0 . A proof of this result will be given in the discrete setting (see Lemma 3.3), we do not detail it in the continuous case since it is not our main interest here.

2.3. Proof of Theorem 2.1. It is worth to mention that estimate (2.4) itself is not sufficient to conclude on the rate of convergence of D to the equilibrium D_{∞} , since there is no dissipation with respect to the zero-th Hermite coefficient D_0 . Therefore, it does not provide quantitative estimates when it comes to its convergence towards $D_{\infty,0}$. Recovering this dissipation is the key feature of hypocoercivity [31, 12]. In our setting it is done by combining the equations on D_0 and D_1 , to remove stiff terms

$$(2.19) \quad \partial_t \left(D_0 + \frac{\tau(\varepsilon)}{\varepsilon} \mathcal{A}^* D_1 \right) + \frac{\tau(\varepsilon)}{\varepsilon^2} \left(\mathcal{A}^* \mathcal{A} D_0 - \sqrt{2} (\mathcal{A}^*)^2 D_2 \right) = 0.$$

To prove quantitative estimates on the solution to (2.2), we therefore introduce the "modified entropy functional" [12, 31]: for any $\alpha_0 > 0$, which will be specified later, we define \mathcal{H}_0 as

$$(2.20) \quad \mathcal{H}_0[D|D_{\infty}] = \frac{1}{2} \|D(t) - D_{\infty}\|_{L^2}^2 + \alpha_0 \left\langle \frac{\tau(\varepsilon)}{\varepsilon} \mathcal{A}^* D_1, u^{\varepsilon} \right\rangle,$$

where u^ε is the particular solution to equation (2.8) with source term is $g = D_0 - D_{\infty,0}$. To be noted that $g = D_0 - D_{\infty,0}$ fullfils the compatibility condition (2.7), thanks to the conservation of mass property (2.14).

The first step consists in proving some intermediate results on the solutions u^ε to (2.8)

Lemma 2.3. *Consider any $g \in L^2(\mathbb{T})$ which meets condition (2.7) and u the corresponding solution to (2.8). Then, u satisfies the following estimate*

$$(2.21) \quad \|\mathcal{A}u\|_{L^2} \leq C_P \|g\|_{L^2},$$

and

$$(2.22) \quad \|\mathcal{A}^2 u\|_{L^2} \leq \left(1 + \frac{C_P}{\sqrt{T_0}} \|\Phi\|_{W^{1,\infty}}\right) \|g\|_{L^2},$$

where C_P is the Poincaré constant in (2.18).

Moreover, considering now the solution D to (2.2) and u^ε the solution to (2.8) with source term $g = D_0 - D_{\infty,0}$, it holds for all time $t \geq 0$

$$(2.23) \quad \varepsilon \|\mathcal{A} \partial_t u^\varepsilon(t)\|_{L^2} \leq \|D_1(t)\|_{L^2}.$$

Proof. The first estimate is obtained by testing the elliptic equation (2.8) against u and applying (2.12)

$$\|\mathcal{A}u\|_{L^2}^2 \leq \|g\|_{L^2} \|u\|_{L^2},$$

hence the Wirtinger-Poincaré inequality (2.18) yields,

$$\|\mathcal{A}u\|_{L^2} \leq C_P \|g\|_{L^2}.$$

For the second estimate, we rewrite $\mathcal{A}^2 u$ as follows

$$\mathcal{A}^2 u = -\mathcal{A}^* \mathcal{A} u + (\mathcal{A} + \mathcal{A}^*) \mathcal{A} u,$$

then we replace $\mathcal{A}^* \mathcal{A} u$ according to equation (2.8), take the L^2 norm on both sides of the relation and apply in turn (2.16) to estimate operator $\mathcal{A} + \mathcal{A}^*$ and item (2.21) to estimate the norm of $\mathcal{A} u$, it yields

$$\|\mathcal{A}^2 u\|_{L^2} \leq \left(1 + \frac{C_P}{\sqrt{T_0}} \|\Phi\|_{W^{1,\infty}}\right) \|g\|_{L^2}.$$

For the third estimate we consider now that D is solution to (2.2) and first take the time derivative of the elliptic equation (2.8) and use the equation (2.2) on D_0 to get

$$\varepsilon \partial_t (\mathcal{A}^* \mathcal{A} u^\varepsilon) = \varepsilon \partial_t (D_0 - D_{\infty,0}) = -\mathcal{A}^* D_1.$$

Then multiply by $\partial_t u^\varepsilon$ and use (2.12) to get

$$\|\partial_t \mathcal{A} u^\varepsilon\|_{L^2}^2 = -\frac{1}{\varepsilon} \langle D_1, \partial_t \mathcal{A} u^\varepsilon \rangle \leq \frac{1}{\varepsilon} \|D_1\|_{L^2} \|\partial_t \mathcal{A} u^\varepsilon\|_{L^2}.$$

□

Thanks to the latter result we now prove that for small enough $\alpha_0 > 0$, the square root of the modified entropy is equivalent to the L^2 norm of $D - D_\infty$

Lemma 2.4. *Suppose that condition (1.7) on $\tau(\varepsilon)$ is satisfied. Then for all $\alpha_0 \in (0, \bar{\alpha}_0)$, with $\bar{\alpha}_0 = 1/(4\bar{\tau}_0 C_P)$ and $D \in L^2(\mathbb{T})$ such that $D_0 - D_\infty$ satisfies the compatibility condition (2.7), one has*

$$(2.24) \quad \|D - D_\infty\|_{L^2}^2 \leq 4 \mathcal{H}_0[D|D_\infty] \leq 3 \|D - D_\infty\|_{L^2}^2.$$

Proof. We estimate the additional term in the expression of \mathcal{H}_0 by applying the duality formula (2.12) and then Cauchy-Schwarz inequality

$$|\langle \mathcal{A}^* D_1, u^\varepsilon \rangle| = |\langle D_1, \mathcal{A} u^\varepsilon \rangle_{L^2}| \leq \|D_1\|_{L^2} \|\mathcal{A} u^\varepsilon\|_{L^2}.$$

Then, we apply item (2.21) of Lemma 2.3 with u^ε and $g = D_0 - D_{\infty,0}$ and upper bound the norm of $\mathcal{A} u^\varepsilon$ accordingly

$$\|D_1\|_{L^2} \|\mathcal{A} u^\varepsilon\|_{L^2} \leq C_P \|D - D_\infty\|_{L^2}^2,$$

hence, applying assumption (1.7), we deduce

$$\alpha_0 \frac{\tau(\varepsilon)}{\varepsilon} |\langle \mathcal{A}^* D_1, u^\varepsilon \rangle| \leq \alpha_0 \bar{\tau}_0 C_P \|D - D_\infty\|_{L^2}^2.$$

Choosing $\bar{\alpha}_0 = 1/(4\bar{\tau}_0 C_P)$, the result follows for $\alpha_0 \in (0, \bar{\alpha}_0)$. \square

Relying on the previous lemmas, we are now able to carry out the proof of the first item (i) of Theorem 2.1. We compute the time derivative of the modified relative entropy and split into three terms

$$\frac{d}{dt} \mathcal{H}_0[D(t)|D_\infty] = \mathcal{I}_1(t) + \alpha_0 \mathcal{I}_2(t) + \alpha_0 \mathcal{I}_3(t),$$

where the first one corresponds to the dissipation of the L^2 norm (2.4),

$$\mathcal{I}_1 = -\frac{1}{\tau(\varepsilon)} \sum_{k \in \mathbb{N}} k \|D_k\|_{L^2}^2,$$

whereas the other ones correspond to the additional term of the modified relative entropy,

$$\begin{cases} \mathcal{I}_2 := -\frac{\tau(\varepsilon)}{\varepsilon^2} \langle \mathcal{A}^* \mathcal{A} (D_0 - D_{\infty,0}) - \sqrt{2} (\mathcal{A}^*)^2 D_2, u^\varepsilon \rangle - \frac{1}{\varepsilon} \langle \mathcal{A}^* D_1, u^\varepsilon \rangle, \\ \mathcal{I}_3 := +\frac{\tau(\varepsilon)}{\varepsilon} \langle \mathcal{A}^* D_1, \partial_t u^\varepsilon \rangle. \end{cases}$$

On the one hand, the term \mathcal{I}_2 gives the expected dissipation on $(D_0 - D_{\infty,0})$ since u^ε solves (2.8) with source term $(D_0 - D_{\infty,0})$. On the other hand we get some additional terms which can be estimated thanks to (2.21) and (2.22) in Lemma 2.3, it yields,

$$\begin{aligned} \mathcal{I}_2 &\leq -\frac{\tau(\varepsilon)}{\varepsilon^2} \|D_0 - D_{\infty,0}\|_{L^2}^2 + \frac{\tau(\varepsilon)}{\varepsilon^2} \sqrt{2} \left(1 + \frac{C_P}{\sqrt{T_0}} \|\Phi\|_{W^{1,\infty}} \right) \|D_0 - D_{\infty,0}\|_{L^2} \|D_2\|_{L^2} \\ &\quad + \frac{C_P}{\varepsilon} \|D_0 - D_{\infty,0}\|_{L^2} \|D_1\|_{L^2}, \\ &\leq -\frac{\tau(\varepsilon)}{\varepsilon^2} (1 - C\eta) \|D_0 - D_{\infty,0}\|_{L^2}^2 + \frac{C}{2\eta} \left(\frac{\tau(\varepsilon)}{\varepsilon^2} \|D_2\|_{L^2}^2 + \frac{1}{\tau(\varepsilon)} \|D_1\|_{L^2}^2 \right), \end{aligned}$$

for any positive η and for some positive constant C depending only on T_0 and Φ . The term \mathcal{I}_3 is estimated directly by applying (2.23) of Lemma 2.3,

$$\mathcal{I}_3 \leq \frac{\tau(\varepsilon)}{\varepsilon^2} \|D_1\|_{L^2}^2.$$

From these latter estimates and taking $\eta = 1/(2C)$, we get the following inequality

$$\begin{aligned} &\frac{d}{dt} \mathcal{H}_0[D|D_\infty] \\ &\leq -\frac{\tau(\varepsilon)}{\varepsilon^2} \left(\frac{\alpha_0}{2} \|D_0 - D_{\infty,0}\|_{L^2}^2 + \left(\frac{\varepsilon^2}{\tau(\varepsilon)^2} - C^2 \left(1 + \frac{\varepsilon^2}{\tau(\varepsilon)^2} \right) \alpha_0 \right) \sum_{k \in \mathbb{N}} k \|D_k\|_{L^2}^2 \right). \end{aligned}$$

Under the following condition

$$\alpha_0 \leq \operatorname{argmax}_{\alpha > 0} \min \left(\frac{\alpha}{2}, \frac{\varepsilon^2}{\tau(\varepsilon)^2} - C^2 \left(1 + \frac{\varepsilon^2}{\tau(\varepsilon)^2} \right) \alpha \right),$$

which, according to assumption (1.7) on $\tau(\varepsilon)$, is fulfilled as long as

$$\alpha_0 \leq \frac{1}{C(\bar{\tau}_0^2 + 1)},$$

for some constant C depending only on Φ and T_0 , and taking κ_0 such that $3\kappa_0/4 = \alpha_0/2$, we derive the following estimate

$$\frac{d}{dt} \mathcal{H}_0[D|D_\infty] + \frac{\tau(\varepsilon)}{\varepsilon^2} \frac{3\kappa_0}{4} \|D - D_\infty\|_{L^2}^2 \leq 0.$$

Then applying Lemma 2.4 and taking $\alpha_0 \leq \bar{\alpha}_0$, we deduce

$$\frac{d}{dt} \mathcal{H}_0[D|D_\infty] + \frac{\tau(\varepsilon)}{\varepsilon^2} \kappa_0 \mathcal{H}_0[D|D_\infty] \leq 0,$$

which yields after applying Gronwall's lemma, for any $t \geq 0$,

$$\mathcal{H}_0[D(t)|D_\infty] \leq \mathcal{H}_0[D(0)|D_\infty] \exp \left(-\frac{\tau(\varepsilon)}{\varepsilon^2} \kappa_0 t \right).$$

We conclude this proof by applying Lemma 2.4 in order to substitute \mathcal{H}_0 with the L^2 norm of $D - D_\infty$ in the latter estimate.

We now turn to the proof of the second item (ii) of Theorem 2.1. To estimate the norm of $\mathcal{B}D$, we apply the operator \mathcal{B}_k to (2.2) and next multiply by $\mathcal{B}_k D_k$, integrate with respect to $x \in \mathbb{T}$ and sum over $k \in \mathbb{N}$, it yields

$$\frac{1}{2} \frac{d}{dt} \|\mathcal{B}D(t)\|_{L^2}^2 = \mathcal{J}_1(t),$$

where \mathcal{J}_1 is defined as follows

$$\mathcal{J}_1 = \sum_{k \in \mathbb{N}^*} -\frac{k}{\tau(\varepsilon)} \|\mathcal{B}_k D_k\|_{L^2}^2 + \frac{\sqrt{k}}{\varepsilon} (\langle \mathcal{B}_{k-1} \mathcal{A}^* D_k, \mathcal{B}_{k-1} D_{k-1} \rangle - \langle \mathcal{B}_k \mathcal{A} D_{k-1}, \mathcal{B}_k D_k \rangle),$$

where we use that $\mathcal{A}D_{\infty,0} = 0$ and $D_{\infty,k} = 0$ for $k > 0$. Hence applying an integration by part and from the specific choice (2.9) of \mathcal{B} , we have

$$(2.25) \quad \mathcal{J}_1 = -\frac{1}{\tau(\varepsilon)} \sum_{k \in \mathbb{N}^*} k \|\mathcal{B}_k D_k\|_{L^2}^2 - \frac{1}{\varepsilon} \sum_{k \geq 2} \sqrt{k} \langle [\mathcal{A}^*, \mathcal{A}] D_{k-1}, \mathcal{A}^* D_k \rangle.$$

Applying Young inequality and property (2.17) on the commutator $[\mathcal{A}^*, \mathcal{A}]$, we get that

$$\mathcal{J}_1 \leq \frac{1}{\tau(\varepsilon)} \left(\frac{\eta}{2} \|\Phi\|_{W^{2,\infty}}^2 - 1 \right) \sum_{k \in \mathbb{N}^*} k \|\mathcal{B}_k D_k\|_{L^2}^2 + \frac{1}{2\eta} \frac{\tau(\varepsilon)}{\varepsilon^2} \sum_{k \geq 1} \|D_k\|_{L^2}^2.$$

Therefore, choosing $\eta \leq 1/\|\Phi\|_{W^{2,\infty}}^2$, it yields

$$(2.26) \quad \frac{1}{2} \frac{d}{dt} \|\mathcal{B}D\|_{L^2}^2 + \frac{1}{2\tau(\varepsilon)} \sum_{k \in \mathbb{N}^*} k \|\mathcal{B}_k D_k\|_{L^2}^2 \leq C \frac{\tau(\varepsilon)}{\varepsilon^2} \sum_{k \geq 1} \|D_k\|_{L^2}^2.$$

Again since there is no dissipation on the zero-th Hermite coefficient of $\mathcal{B}_0 D_0$, we proceed as for the L^2 estimate and introduce a correction \mathcal{H}_1 given by

$$(2.27) \quad \mathcal{H}_1[D|D_\infty] = \frac{1}{2} \|\mathcal{B}D\|_{L^2}^2 + \alpha_1 \left\langle \frac{\tau(\varepsilon)}{\varepsilon} \mathcal{A} D_0, D_1 \right\rangle,$$

where α_1 has to be determined. First, we point out that for small enough $\alpha_1 > 0$, the modified entropy \mathcal{H}_1 is controlled by the squares of the L^2 norms of $D - D_\infty$ and $\mathcal{B}D$.

Lemma 2.5. *Suppose that condition (1.7) on $\tau(\varepsilon)$ is satisfied. Then for all $\alpha_1 \in (0, \bar{\alpha}_1)$, with $\bar{\alpha}_1 = 1/(2\bar{\tau}_0)$ and $D \in L^2(\mathbb{T})$, one has*

$$(2.28) \quad \|\mathcal{B}D\|_{L^2}^2 - \|D - D_\infty\|_{L^2}^2 \leq 4\mathcal{H}_1[D|D_\infty] \leq 3\|\mathcal{B}D\|_{L^2}^2 + \|D - D_\infty\|_{L^2}^2.$$

Proof. The result is obtained applying the Young inequality to the additional term in the definition (2.27) of \mathcal{H}_1 \square

To complete the proof of the second item (ii) in Theorem 2.1, we compute the time derivative of the modified relative entropy and split into two terms

$$\frac{d}{dt} \mathcal{H}_1[D|D_\infty] = \mathcal{J}_1 + \alpha_1 \mathcal{J}_2,$$

where the first one corresponds to the dissipation of the L^2 norm of $\mathcal{B}(D - D_\infty)$ for which we already have an estimate (2.26), that is,

$$\mathcal{J}_1 \leq -\frac{1}{2\tau(\varepsilon)} \sum_{k \in \mathbb{N}^*} k \|\mathcal{B}_k D_k\|_{L^2}^2 + C \frac{\tau(\varepsilon)}{\varepsilon^2} \sum_{k \geq 1} \|D_k\|_{L^2}^2,$$

whereas the other ones correspond to the additional term of the modified relative entropy,

$$\mathcal{J}_2 := \frac{\tau(\varepsilon)}{\varepsilon^2} \left(\langle \mathcal{A} \mathcal{A}^* D_1, D_1 \rangle - \|\mathcal{A} D_0\|_{L^2}^2 + \sqrt{2} \langle \mathcal{A} D_0, \mathcal{A}^* D_2 \rangle \right) - \frac{1}{\varepsilon} \langle D_1, \mathcal{A} D_0 \rangle.$$

From (2.12) and (2.13) on the operators $(\mathcal{A}, \mathcal{A}^*)$, we have

$$\frac{1}{\varepsilon} \langle D_1, \mathcal{A} D_0 \rangle = \left\langle \frac{1}{\tau(\varepsilon)^{1/2}} \mathcal{A}^* D_1, \frac{\tau(\varepsilon)^{1/2}}{\varepsilon} (D_0 - D_{\infty,0}) \right\rangle,$$

hence applying twice the Young inequality on the third term of the right hand side and on the latter term, it yields

$$\mathcal{J}_2 \leq -\frac{\tau(\varepsilon)}{\varepsilon^2} \left[\frac{1}{2} \|\mathcal{A} D_0\|_{L^2}^2 - \left(1 + \frac{\varepsilon^2}{\tau(\varepsilon)^2}\right) \sum_{k \in \mathbb{N}^*} k \|\mathcal{B}_k D_k\|_{L^2}^2 - \|D_0 - D_{\infty,0}\|_{L^2}^2 \right].$$

Therefore, from these estimates, we get the following inequality

$$\begin{aligned} \frac{d}{dt} \mathcal{H}_1[D|D_\infty] &\leq (C + \alpha_1) \frac{\tau(\varepsilon)}{\varepsilon^2} \|D_0 - D_{\infty,0}\|_{L^2}^2 \\ &\quad - \frac{\tau(\varepsilon)}{2\varepsilon^2} \left[\alpha_1 \|\mathcal{A} D_0\|_{L^2}^2 + \left(\frac{\varepsilon^2}{\tau(\varepsilon)^2} - 2\alpha_1 \left(1 + \frac{\varepsilon^2}{\tau(\varepsilon)^2}\right) \right) \sum_{k \in \mathbb{N}^*} k \|\mathcal{B}_k D_k\|_{L^2}^2 \right], \end{aligned}$$

hence choosing α_1

$$\alpha_1 \leq \operatorname{argmax}_{\alpha > 0} \min \left(\alpha, \frac{\varepsilon^2}{\tau(\varepsilon)^2} - 2\alpha \left(1 + \frac{\varepsilon^2}{\tau(\varepsilon)^2}\right) \right) = \frac{1}{2 + 3 \frac{\tau(\varepsilon)^2}{\varepsilon^2}},$$

which is verified under the following condition

$$\alpha_1 \leq \frac{1}{2 + 3 \bar{\tau}_0^2},$$

we get that

$$\frac{d}{dt} \mathcal{H}_1[D|D_\infty] + \frac{\tau(\varepsilon)}{\varepsilon^2} \frac{\alpha_1}{2} \|\mathcal{B} D\|_{L^2}^2 \leq C \frac{\tau(\varepsilon)}{\varepsilon^2} \|D - D_\infty\|_{L^2}^2.$$

Furthermore, taking $\alpha_1 \leq 1/(2\bar{\tau}_0)$ and applying Lemma 2.5, we obtain

$$\frac{d}{dt} \mathcal{H}_1[D|D_\infty] + \frac{\tau(\varepsilon)}{\varepsilon^2} \frac{2\alpha_1}{3} \mathcal{H}_1[D|D_\infty] \leq C \frac{\tau(\varepsilon)}{\varepsilon^2} \|D - D_\infty\|_{L^2}^2.$$

Then we set

$$\kappa_1 = \min \left(\frac{2\alpha_1}{3}, \kappa_0 \right)$$

and multiply the latter inequality by $\exp\left(\frac{\tau(\varepsilon)}{\varepsilon^2} \frac{2\alpha_1}{3} t\right)$, integrate in time and apply the first item (i) of Theorem 2.1 to estimate the right hand side, this yields

$$\mathcal{H}_1[D(t)|D_\infty] \leq \left(C (\bar{\tau}_0^2 + 1) \|D(0) - D_\infty\|_{L^2}^2 + \mathcal{H}_1[D(0)|D_\infty] \right) \exp\left(-\frac{\tau(\varepsilon)}{\varepsilon^2} \kappa_1 t\right).$$

We conclude this proof by substituting \mathcal{H}_1 with the norm of $\mathcal{B}D$ in the latter estimate according to Lemma 2.5.

2.4. Proof of Theorem 2.2. Once again, instead of estimating directly the H^{-1} norm of $D_0 - D_{\tau_0}$, we introduce the following quantity, meant to recover dissipation on the zero-th Hermite coefficient

$$(2.29) \quad \mathcal{E}(t) = \frac{1}{2} \|\mathcal{A} v^\varepsilon(t)\|_{L^2}^2,$$

where $v^\varepsilon(t)$ solves the elliptic equation (2.8) with source term given by

$$g(t) = D_0(t) + \frac{\tau(\varepsilon)}{\varepsilon} \mathcal{A}^* D_1(t) - D_{\tau_0,0}(t),$$

where $D_0(t)$ and $D_1(t)$ are the first two components of the solution $D(t)$ of (2.2) and $D_{\tau_0,0}(t)$ is either the unique solution to the convection-diffusion equation (2.6) when τ_0 is finite or the stationary solution $D_{\infty,0}$ given by (2.3) when $\tau_0 = \infty$. The latter right hand side is motivated by equation (2.19) since it is given by the difference between $D_0 + \frac{\tau(\varepsilon)}{\varepsilon} \mathcal{A}^* D_1$ and $D_{\tau_0,0}$. We point out that the latter source term meets the compatibility condition (2.7) thanks to property (2.14), which ensures that $\mathcal{A}^* D_1(t)$ is orthogonal to $\sqrt{\rho_\infty}$ in $L^2(\mathbb{T})$.

Before proving the first item of Theorem 2.2, let us present some preliminary results. On the one hand, the following Lemma ensures that $\mathcal{E}(t)$ is controlled by the squares of the L^2 norm of $\mathcal{B}D(t)$ and the H^{-1} norm of $D_0(t) - D_{\tau_0,0}(t)$

Lemma 2.6. *We consider $\mathcal{E}(t)$ defined by (2.29). It holds uniformly with respect to ε*

$$(2.30) \quad \mathcal{E}(t) \leq \|D_0(t) - D_{\tau_0,0}(t)\|_{H^{-1}}^2 + C_P^2 \frac{\tau(\varepsilon)^2}{\varepsilon^2} \|\mathcal{B}D(t)\|_{L^2}^2,$$

and

$$(2.31) \quad \frac{1}{4} \|D_0(t) - D_{\tau_0,0}(t)\|_{H^{-1}}^2 - C_P^2 \frac{\tau(\varepsilon)^2}{2\varepsilon^2} \|\mathcal{B}D(t)\|_{L^2}^2 \leq \mathcal{E}(t).$$

Proof. Defining w^ε and u_{τ_0} as the respective solutions to (2.8) with source term $g = \mathcal{A}^*D_1$ and $D_{\tau_0,0} - D_{\infty,0}$, it holds

$$v^\varepsilon = u^\varepsilon - u_{\tau_0} + \frac{\tau(\varepsilon)}{\varepsilon} w^\varepsilon.$$

We apply operator \mathcal{A} to the latter relation, take the L^2 norm, and apply the triangular inequality, it yields

$$\sqrt{2\mathcal{E}} \leq \|\mathcal{A}(u^\varepsilon - u_{\tau_0})\|_{L^2} + \frac{\tau(\varepsilon)}{\varepsilon} \|\mathcal{A}w^\varepsilon\|_{L^2},$$

and

$$\|\mathcal{A}(u^\varepsilon - u_{\tau_0})\|_{L^2} - \frac{\tau(\varepsilon)}{\varepsilon} \|\mathcal{A}w^\varepsilon\|_{L^2} \leq \sqrt{2\mathcal{E}}.$$

We estimate $\|\mathcal{A}w^\varepsilon\|_{L^2}$ applying (2.21) in Lemma 2.3 with source term $g = \mathcal{A}^*D_1$, this yields

$$\sqrt{2\mathcal{E}} \leq \|D_0 - D_{\tau_0,0}\|_{H^{-1}} + \frac{\tau(\varepsilon)}{\varepsilon} C_P \|\mathcal{B}D\|_{L^2},$$

and

$$\|D_0 - D_{\tau_0,0}\|_{H^{-1}} - \frac{\tau(\varepsilon)}{\varepsilon} C_P \|\mathcal{B}D\|_{L^2} \leq \sqrt{2\mathcal{E}}.$$

We obtain the result taking the square of the latter inequalities and applying Young's inequality. \square

On the other hand, when τ_0 is finite, we observe that the long time behavior of $D_{\tau_0,0}$ may be easily investigated. Indeed, since $\mathcal{A}D_{\infty,0} = 0$, we have that $D_{\tau_0,0} - D_{\infty,0}$ also solves (2.6). Therefore, multiplying (2.6) by $D_{\tau_0,0} - D_{\infty,0}$, integrating over \mathbb{T} and applying the Poincaré inequality (2.18), we obtain the following estimate after applying Gronwall lemma

$$(2.32) \quad \|D_{\tau_0}(t) - D_{\infty}\|_{L^2} \leq \|D_{\tau_0}(t) - D_{\infty}\|_{L^2} \exp\left(-\frac{\tau_0}{C_P^2} t\right), \quad \forall t \in \mathbb{R}^+.$$

We are now able to prove the first item (i) of Theorem 2.2, which treats the case where $\tau(\varepsilon) \sim \tau_0 \varepsilon^2$, when $\varepsilon \rightarrow 0$ where $\tau_0 \in \mathbb{R}_*^+$. To derive the first estimate in item (i) of Theorem 2.2, our starting point is the L^2 estimate (2.4) which ensures

$$\begin{aligned} \frac{1}{2} \frac{d}{dt} \|D_\perp(t)\|_{L^2}^2 + \frac{1}{\tau(\varepsilon)} \|D_\perp(t)\|_{L^2}^2 &\leq -\frac{1}{2} \frac{d}{dt} \|D_0(t) - D_{\infty,0}\|_{L^2}^2 \\ &\leq -\frac{1}{\varepsilon} \langle \mathcal{A}^*D_1(t), D_0(t) - D_{\infty,0} \rangle \\ &= -\frac{1}{\varepsilon} \langle D_1(t), \mathcal{A}(D_0(t) - D_{\infty,0}) \rangle, \end{aligned}$$

hence it gives from the Young inequality

$$\frac{d}{dt} \|D_\perp(t)\|_{L^2}^2 + \frac{1}{\tau(\varepsilon)} \|D_\perp(t)\|_{L^2}^2 \leq \frac{\tau(\varepsilon)}{\varepsilon^2} \|\mathcal{B}D(t)\|_{L^2}^2.$$

We bound $\|\mathcal{B}D(t)\|_{L^2}^2$ applying item (ii) of Theorem 2.1. After multiplying the latter estimate by $e^{t/\tau(\varepsilon)}$ and integrating with respect to time, it yields

$$\begin{aligned} \|D_\perp(t)\|_{L^2}^2 &\leq \|D_\perp(0)\|_{L^2}^2 \exp\left(-\frac{t}{\tau(\varepsilon)}\right) \\ &+ \left(C(\bar{\tau}_0^2 + 1) \|D(0) - D_\infty\|_{L^2}^2 + \|\mathcal{B}D(0)\|_{L^2}^2\right) \frac{3\tau(\varepsilon)^2}{\varepsilon^2 - \kappa\tau(\varepsilon)^2} \exp\left(-\frac{\tau(\varepsilon)}{\varepsilon^2} \kappa t\right), \end{aligned}$$

where C is a positive constant depending only on Φ and T_0 and $\kappa = (C(\bar{\tau}_0^2 + 1))^{-1}$. Then we apply condition (1.7) on $\tau(\varepsilon)$, which ensures that taking C greater than 2 in the definition of κ , it holds $1/2 \leq 1 - \kappa\tau(\varepsilon)^2/\varepsilon^2$ uniformly with respect to ε . Therefore, we deduce the following estimate, which yields the first result in (i) of Theorem (2.1), after taking its square root and applying assumption (2.11) in order to substitute $\tau(\varepsilon)$ with $\tau_0\varepsilon^2$

$$\|D_\perp(t)\|_{L^2}^2 \leq \|D_\perp(0)\|_{L^2}^2 e^{-\frac{t}{\tau(\varepsilon)}} + 6 \left(C(\bar{\tau}_0^2 + 1) \|D(0) - D_\infty\|_{L^2}^2 + \|\mathcal{B}D(0)\|_{L^2}^2\right) \frac{\tau(\varepsilon)^2}{\varepsilon^2} e^{-\frac{\tau(\varepsilon)}{\varepsilon^2} \kappa t}.$$

We now prove the second result in item (i) of Theorem 2.2. To do so, we evaluate \mathcal{E} observing that

$$\frac{d\mathcal{E}}{dt} = \left\langle \partial_t \left(D_0 + \frac{\tau(\varepsilon)}{\varepsilon} \mathcal{A}^* D_1 - D_{\tau_0,0} \right), v^\varepsilon \right\rangle.$$

Therefore, relying on equations (2.19) and (2.6) we deduce

$$\frac{d\mathcal{E}}{dt} = -\frac{\tau(\varepsilon)}{\varepsilon^2} \|D_0 + \frac{\tau(\varepsilon)}{\varepsilon} \mathcal{A}^* D_1 - D_{\tau_0,0}\|_{L^2}^2 + \mathcal{E}_1 + \mathcal{E}_2 + \mathcal{E}_3,$$

where

$$\begin{cases} \mathcal{E}_1 = \left(\tau_0 - \frac{\tau(\varepsilon)}{\varepsilon^2} \right) \langle \mathcal{A}^* \mathcal{A} D_{\tau_0,0}, v^\varepsilon \rangle, \\ \mathcal{E}_2 = \frac{\tau(\varepsilon)^2}{\varepsilon^3} \langle \mathcal{A}^* \mathcal{A} D_1, v^\varepsilon \rangle, \\ \mathcal{E}_3 = \sqrt{2} \frac{\tau(\varepsilon)}{\varepsilon^2} \langle (\mathcal{A}^*)^2 D_2, v^\varepsilon \rangle. \end{cases}$$

We rewrite \mathcal{E}_1 , \mathcal{E}_2 and \mathcal{E}_3 according to the following considerations: first, we notice that $D_{\infty,0}$ solves (2.13) and therefore add $D_{\infty,0}$ to the left hand side of the bracket in \mathcal{E}_1 , second we apply the duality formula (2.12) in \mathcal{E}_1 , \mathcal{E}_2 and \mathcal{E}_3 and then replace v^ε in \mathcal{E}_1 and \mathcal{E}_2 according to the relation

$$\mathcal{A}^* \mathcal{A} v^\varepsilon = D_0 + \frac{\tau(\varepsilon)}{\varepsilon} \mathcal{A}^* D_1 - D_{\tau_0,0}.$$

Hence, we obtain

$$\begin{cases} \mathcal{E}_1 = \left(\tau_0 - \frac{\tau(\varepsilon)}{\varepsilon^2} \right) \left\langle D_{\tau_0,0} - D_{\infty,0}, D_0 + \frac{\tau(\varepsilon)}{\varepsilon} \mathcal{A}^* D_1 - D_{\tau_0,0} \right\rangle, \\ \mathcal{E}_2 = \frac{\tau(\varepsilon)^2}{\varepsilon^3} \left\langle D_1, D_0 + \frac{\tau(\varepsilon)}{\varepsilon} \mathcal{A}^* D_1 - D_{\tau_0,0} \right\rangle, \\ \mathcal{E}_3 = \sqrt{2} \frac{\tau(\varepsilon)}{\varepsilon^2} \langle D_2, \mathcal{A}^2 v^\varepsilon \rangle. \end{cases}$$

To estimate \mathcal{E}_1 , we apply Young's inequality, which yields

$$\mathcal{E}_1 \leq \frac{\eta\tau(\varepsilon)}{2\varepsilon^2} \|D_0 + \frac{\tau(\varepsilon)}{\varepsilon} \mathcal{A}^* D_1 - D_{\tau_0,0}\|_{L^2}^2 + \frac{1}{2\eta} \frac{\varepsilon^2}{\tau(\varepsilon)} \left| \tau_0 - \frac{\tau(\varepsilon)}{\varepsilon^2} \right|^2 \|D_{\tau_0,0} - D_{\infty,0}\|_{L^2}^2,$$

for all positive η . To estimate \mathcal{E}_2 , we apply Young's inequality and then assumption (1.7) which ensures that $\tau(\varepsilon)^3/\varepsilon^4 \leq (\bar{\tau}_0^2 \tau(\varepsilon))/\varepsilon^2$, this gives

$$\mathcal{E}_2 \leq \frac{\eta\tau(\varepsilon)}{2\varepsilon^2} \|D_0 + \frac{\tau(\varepsilon)}{\varepsilon} \mathcal{A}^* D_1 - D_{\tau_0,0}\|_{L^2}^2 + \frac{1}{\eta} \frac{\tau(\varepsilon)}{\varepsilon^2} \bar{\tau}_0^2 \|D_\perp\|_{L^2}^2,$$

for all positive η . To estimate \mathcal{E}_3 , we apply Young's inequality and then bound the norm of $\mathcal{A}^2 v^\varepsilon$ by applying item (2.22) in Lemma 2.3 with source term

$$g = D_0 + \frac{\tau(\varepsilon)}{\varepsilon} \mathcal{A}^* D_1 - D_{\tau_0,0},$$

it yields

$$\mathcal{E}_3 \leq \eta \frac{\tau(\varepsilon)}{\varepsilon^2} \|D_0 + \frac{\tau(\varepsilon)}{\varepsilon} \mathcal{A}^* D_1 - D_{\tau_0,0}\|_{L^2}^2 + \frac{C}{\eta} \frac{\tau(\varepsilon)}{\varepsilon^2} \|D_\perp\|_{L^2}^2,$$

for some constant C depending only on Φ and T_0 . We gather the latter estimates, take $\eta = 1/4$ and apply item (2.21) in Lemma 2.3, which ensures that

$$\mathcal{E} \leq \frac{C_P^2}{2} \|D_0 + \frac{\tau(\varepsilon)}{\varepsilon} \mathcal{A}^* D_1 - D_{\tau_0,0}\|_{L^2}^2.$$

Therefore, we obtain

$$\frac{d\mathcal{E}}{dt} + \frac{\tau(\varepsilon)}{C_P^2 \varepsilon^2} \mathcal{E} \leq C \frac{\tau(\varepsilon)}{\varepsilon^2} (1 + \bar{\tau}_0^2) \|D_\perp\|_{L^2}^2 + C \frac{\varepsilon^2}{\tau(\varepsilon)} \left| \tau_0 - \frac{\tau(\varepsilon)}{\varepsilon^2} \right|^2 \|D_{\tau_0} - D_\infty\|_{L^2}^2,$$

for some constant C depending only on Φ and T_0 . Then we multiply the latter estimate by $\exp\left(\frac{\tau(\varepsilon)}{C_P^2 \varepsilon^2} t\right)$ and integrate with respect to time. After applying (2.32) to estimate $\|D_{\tau_0} - D_\infty\|_{L^2}$ and the first result in item (i) of Theorem 2.2 to estimate the norm of D_\perp , it yields

$$\begin{aligned} \mathcal{E}(t) &\leq \left(\mathcal{E}(0) + C \frac{\tau(\varepsilon)^2}{\varepsilon^2} (\bar{\tau}_0^6 + 1) \|D(0) - D_\infty\|_{H^1}^2 \right) \exp\left(-\frac{\tau(\varepsilon)}{\varepsilon^2} \kappa t\right) \\ &\quad + C \left| \frac{\tau_0 \varepsilon^2}{\tau(\varepsilon)} - 1 \right|^2 \|D_{\tau_0}(0) - D_\infty\|_{L^2}^2 \left(\frac{2\tau_0 \varepsilon^2}{\tau(\varepsilon)} - 1 \right)^{-1} \exp\left(-\frac{\tau(\varepsilon)}{\varepsilon^2} \kappa t\right). \end{aligned}$$

To conclude, we substitute $\mathcal{E}(t)$ (resp. $\mathcal{E}(0)$) in the latter estimate according to (2.31) (resp. (2.30)) in Lemma 2.6 and then apply assumption (2.11) on $\tau(\varepsilon)$, which ensures $\left(\frac{2\tau_0 \varepsilon^2}{\tau(\varepsilon)} - 1\right)^{-1} \leq 3$, this yields

$$\begin{aligned} \|D_0(t) - D_{\tau_0,0}(t)\|_{H^{-1}}^2 &\leq \\ &C \left(\|D_0(0) - D_{\tau_0,0}(0)\|_{H^{-1}}^2 + \frac{\tau(\varepsilon)^2}{\varepsilon^2} (\bar{\tau}_0^6 + 1) \|D(0) - D_\infty\|_{H^1}^2 \right) e^{-\frac{\tau(\varepsilon)}{\varepsilon^2} \kappa t} + \\ &C \left| \frac{\tau_0 \varepsilon^2}{\tau(\varepsilon)} - 1 \right|^2 \|D_{\tau_0}(0) - D_\infty\|_{L^2}^2 e^{-\frac{\tau(\varepsilon)}{\varepsilon^2} \kappa t}. \end{aligned}$$

We obtain the second estimate provided in (i) of Theorem 2.2 taking the square root in the latter estimate and applying assumption (2.11) in order to substitute $\tau(\varepsilon)$ with $\tau_0 \varepsilon^2$.

To prove the second item (ii) of Theorem 2.2, we follow the same lines as the ones for item (i) replacing D_{τ_0} by D_∞ and observing that D_∞ also solves the equation (2.6) since it is a stationary solution. Therefore, computations are even simpler since the term \mathcal{E}_1 vanishes in this case. As a consequence the estimate provided in item (ii) follows.

3. FINITE VOLUME DISCRETIZATION FOR THE SPACE VARIABLE

In this section we present a finite volume scheme for (2.2). Then we prove discrete hypocoercive estimates on the discrete solution to investigate the long time behavior and the speed of convergence to the steady state. Finally, we prove an asymptotic preserving property for the diffusive limit taking $\tau(\varepsilon) \sim \tau_0 \varepsilon^2$ with error estimates with respect to ε . Thanks to the groundworks laid in the previous Section, we are able to propose a scheme which describes all the variety of regimes that we aim to capture in this article.

3.1. Numerical scheme. For simplicity purposes, we consider the problem in one space dimension. It will be straightforward to generalize this construction for Cartesian meshes in multidimensional case. In a one-dimensional setting, we consider an interval (a, b) of \mathbb{R} and for $N_x \in \mathbb{N}^*$, we introduce the set $\mathcal{J} = \{1, \dots, N_x\}$ and a family of control volumes $(K_j)_{j \in \mathcal{J}}$ such that $K_j =]x_{j-1/2}, x_{j+1/2}[$ with x_j the middle of the interval K_j and

$$a = x_{1/2} < x_1 < x_{3/2} < \dots < x_{j-1/2} < x_j < x_{j+1/2} < \dots < x_{N_x} < x_{N_x+1/2} = b.$$

Let us set

$$\begin{cases} \Delta x_j = x_{j+1/2} - x_{j-1/2}, & \text{for } j \in \mathcal{J}, \\ \Delta x_{i+1/2} = x_{j+1} - x_j, & \text{for } 1 \leq j \leq N_x - 1. \end{cases}$$

We also introduce the parameter h such that

$$h = \max_{j \in \mathcal{J}} \Delta x_j.$$

Let Δt be the time step. We set $t^n = n\Delta t$ with $n \in \mathbb{N}$. A time discretization of \mathbb{R}^+ is then given by the increasing sequence of $(t^n)_{n \in \mathbb{N}}$. In the sequel, we will denote by D_k^n the approximation of $D_k(t^n)$, where the index k represents the k -th mode of the Hermite decomposition, whereas $\mathcal{D}_{k,j}^n$ is an approximation of the mean value of D_k over the cell K_j at time t^n .

First of all, the initial condition is discretized on each cell K_j by:

$$\mathcal{D}_{k,j}^0 = \frac{1}{\Delta x_j} \int_{K_j} D_k(t=0, x) dx, \quad j \in \mathcal{J}.$$

The finite volume scheme is obtained by integrating the equation (2.2) over each control volume K_j and over each time step. Concerning the time discretization, we can choose any implicit method (backward Euler, Implicit Runge-Kutta,...). Since in this paper we are interested in the spatial discretization, we will only consider a backward Euler method afterwards. Let us now focus on the spatial discretization.

By integrating equation (2.2) on K_j for $j \in \mathcal{J}$, we obtain the numerical scheme: for $D_k^n = (\mathcal{D}_{k,j}^n)_{j \in \mathcal{J}}$

$$(3.1) \quad \frac{D_k^{n+1} - D_k^n}{\Delta t} + \frac{1}{\varepsilon} \left(\sqrt{k} \mathcal{A}_h D_{k-1}^{n+1} - \sqrt{k+1} \mathcal{A}_h^* D_{k+1}^{n+1} \right) = -\frac{k}{\tau(\varepsilon)} D_k^{n+1},$$

where \mathcal{A}_h (resp. \mathcal{A}_h^*) is an approximation of the operator \mathcal{A} (resp. \mathcal{A}^*) given by

$$(3.2) \quad \mathcal{A}_h = (\mathcal{A}_j)_{j \in \mathcal{J}} \quad \text{and} \quad \mathcal{A}_h^* = (\mathcal{A}_j^*)_{j \in \mathcal{J}}.$$

and where for $D = (\mathcal{D}_j)_{j \in \mathcal{J}}$ it holds

$$(3.3) \quad \begin{cases} \mathcal{A}_j D = +\sqrt{T_0} \left(\frac{\mathcal{D}_{j+1} - \mathcal{D}_{j-1}}{2\Delta x_j} - \frac{E_j}{2T_0} \mathcal{D}_j \right), & j \in \mathcal{J}, \\ \mathcal{A}_j^* D = -\sqrt{T_0} \left(\frac{\mathcal{D}_{j+1} - \mathcal{D}_{j-1}}{2\Delta x_j} + \frac{E_j}{2T_0} \mathcal{D}_j \right), & j \in \mathcal{J}, \end{cases}$$

whereas the discrete electric field E_j is given by

$$(3.4) \quad E_j = -\frac{\Phi_{j+1} - \Phi_{j-1}}{2\Delta x_j} = \frac{2T_0}{\sqrt{\rho_{\infty,j}}} \frac{\sqrt{\rho_{\infty,j+1}} - \sqrt{\rho_{\infty,j-1}}}{2\Delta x_j},$$

where $\rho_{\infty,j}$ is an approximation of the stationary density ρ_{∞} on the cell K_j . This latter formula is consistent with the definition of $\sqrt{\rho_{\infty}} = c_0 e^{-\Phi/(2T_0)}$ and the fact that

$$\frac{1}{2T_0} \partial_x \Phi = -\frac{1}{\sqrt{\rho_{\infty}}} \partial_x \sqrt{\rho_{\infty}}.$$

This choice of discretization is motivated by preserving at the discrete level the key properties (2.12)-(2.18). In the end, we propose the following approximation of the continuous solution f to (1.2)

$$f^n(x, v) = \sum_{k \in \mathbb{N}} \sqrt{\rho_{\infty}}(x) D_k^n(x) \Psi_k(v),$$

where for each $k \geq 0$ and $n \geq 0$, we define a piecewise constant function D_k^n from the numerical values $(\mathcal{D}_{k,j}^n)_{j \in \mathcal{J}}$ as

$$D_k^n(x) = \mathcal{D}_{k,j}^n, \quad x \in K_j.$$

In this context the equilibrium D_{∞} is given by

$$(3.5) \quad D_{\infty,k} = \begin{cases} \sqrt{\rho_{\infty}}, & \text{if } k = 0, \\ 0, & \text{else;} \end{cases}$$

as for the limit in the diffusive regime $D_{\tau_0}^n = (D_{\tau_0,k}^n)_{k \in \mathbb{N}}$, it is given by

$$(3.6) \quad D_{\tau_0,k}^n = \begin{cases} D_{\tau_0,0}^n, & \text{if } k = 0, \\ 0, & \text{else,} \end{cases}$$

where $D_{\tau_0,0}^n$ solves the following discrete version of equation (2.6)

$$(3.7) \quad \frac{D_{\tau_0,0}^{n+1} - D_{\tau_0,0}^n}{\Delta t} + \tau_0 \mathcal{A}_h^* \mathcal{A}_h D_{\tau_0,0}^{n+1} = 0.$$

We now introduce the norms we will work with in this section. We denote by $\langle \cdot, \cdot \rangle$ the L^2 scalar product for any $u = (u_j)_{j \in \mathcal{J}}$ and $v = (v_j)_{j \in \mathcal{J}}$,

$$\langle u, v \rangle = \sum_{j \in \mathcal{J}} \Delta x_j u_j v_j$$

and

$$\|u\|_{L^2} = \left(\sum_{j \in \mathcal{J}} \Delta x_j u_j^2 \right)^{1/2}.$$

As in the (2.7), we consider the following H^{-1} norm defined on the L^2 subspace orthogonal to $\sqrt{\bar{\rho}}_\infty$: for all $g_h = (g_j)_{j \in \mathcal{J}}$ which meets the condition

$$(3.8) \quad \sum_{j \in \mathcal{J}} \Delta x_j g_j \sqrt{\bar{\rho}_{\infty,j}} = 0,$$

we set

$$\|g_h\|_{H^{-1}} = \|\mathcal{A} u_h\|_{L^2(\mathbb{T})},$$

where $u_h = (u_j)_{j \in \mathcal{J}}$ is the solution to the discrete equivalent of equation (2.8)

$$(3.9) \quad \begin{cases} (\mathcal{A}_h^* \mathcal{A}_h) u_h = g, \\ \sum_{j \in \mathcal{J}} \Delta x_j u_j \sqrt{\bar{\rho}_{\infty,j}} = 0. \end{cases}$$

We also use the H^1 norm, analog to the one given in (2.9), defined for all $D = (D_k)_{k \in \mathbb{N}}$ as follows

$$\|\mathcal{B}_h D\|_{L^2}^2 = \sum_{k \in \mathbb{N}} \|\mathcal{B}_k D_k\|_{L^2}^2,$$

where the family of discrete operator $\mathcal{B}_h = (\mathcal{B}_{h,k})_{k \geq 0}$ is given as follows

$$(3.10) \quad \mathcal{B}_{h,k} = \begin{cases} \mathcal{A}_h, & \text{if } k = 0, \\ \mathcal{A}_h^*, & \text{else.} \end{cases}$$

To conclude with this section, we take the same definition of D_\perp as in the continuous setting.

3.2. Main results. We can now release the two results that constitute the core of this article. Thanks to our choice of discretization, they are an exact translation of their continuous analogs, Theorems 2.1 and 2.2, into the discrete setting, without any loss of accuracy nor uniformity with respect to the parameters at play in our analysis. On top of that, the results are also uniform with respect to the discretization parameters.

This first result is the continuous analog of Theorem 2.1, it ensures that our scheme has the same long time behavior as the continuous model

Theorem 3.1. *Suppose that condition (1.7) on $\tau(\varepsilon)$ is satisfied and Let $D^n = (D_k^n)_{k \in \mathbb{N}}$ be the solution to (3.1). The following statements hold true*

- (i) *there exists some positive constant C_0 depending only on Φ and T_0 such that for all $\varepsilon > 0$ and all $n \geq 0$, we have*

$$\|D^n - D_\infty\|_{L^2} \leq \sqrt{3} \|D^0 - D_\infty\|_{L^2} \left(1 + \frac{\tau(\varepsilon)}{\varepsilon^2} \kappa_0 \Delta t \right)^{-n/2};$$

(ii) suppose in addition that the mesh is regular enough so that the quantity

$$(3.11) \quad R_h = \sup_{(i,j) \in \mathcal{J}^2} |\Delta x_j \Delta x_i^{-1} - 1|$$

stays uniformly bounded with respect to the discretization parameter h . Then there exists a positive constant C_1 (depending only on Φ , T_0 and R_h) such that for all $\varepsilon > 0$ and all $n \geq 0$, we have

$$\|\mathcal{B}_h D^n\|_{L^2} \leq \sqrt{3} (C_1 (\bar{\tau}_0 + 1) \|\mathcal{B}_h D^0\|_{L^2} + \|D^0 - D_\infty\|_{L^2}) \left(1 + \frac{\tau(\varepsilon)}{\varepsilon^2} \kappa_1 \Delta t\right)^{-\frac{n}{2}},$$

In the previous estimates $\kappa_i > 0$ is given by

$$\kappa_i = \frac{1}{C_i (\bar{\tau}_0^2 + 1)}.$$

Our second result deals with the asymptotic $\varepsilon \rightarrow 0$, it is the discrete analog of Theorem 2.2

Theorem 3.2. *Suppose that $\tau(\varepsilon)$ meets assumption (1.7) and that the mesh meets assumption (3.11). Consider the solution $D^n = (D_k^n)_{k \in \mathbb{N}}$ to (3.1). The following statements hold true uniformly with respect to ε*

(i) *suppose that $\tau(\varepsilon)$ satisfies (1.8) and (2.11) and consider $D_{\tau_0}^n = (D_{\tau_0,k}^n)_{k \in \mathbb{N}}$ given by (3.6). Then it holds for all $n \geq 0$,*

$$\|D_{\perp}^n\|_{L^2} \leq \|D_{\perp}^0\|_{L^2} \left(1 + \frac{\Delta t}{2\tau_0 \varepsilon^2}\right)^{-\frac{n}{2}} + \tau_0 \varepsilon C(\bar{\tau}_0 + 1) \|D^0 - D_\infty\|_{H^1} (1 + \tau_0 \kappa \Delta t)^{-\frac{n}{2}},$$

and

$$\begin{aligned} \|D_0^n - D_{\tau_0,0}^n\|_{H^{-1}} &\leq C \left(\|D_0^0 - D_{\tau_0,0}^0\|_{H^{-1}} + \varepsilon \tau_0 (\bar{\tau}_0^3 + 1) \|D^0 - D_\infty\|_{H^1} \right) (1 + \tau_0 \kappa \Delta t)^{-\frac{n}{2}}, \\ C \left| \frac{\tau_0 \varepsilon^2}{\tau(\varepsilon)} - 1 \right| &\|D_{\tau_0}^0 - D_\infty\|_{L^2} (1 + \tau_0 \kappa \Delta t)^{-\frac{n}{2}}; \end{aligned}$$

(ii) *suppose that $\tau(\varepsilon)$ satisfies (1.9). Then it holds for any $n \geq 0$*

$$\|D_{\perp}\|_{L^2}^2 \leq \|D_{\perp}\|_{L^2}^2 \left(1 + \frac{\Delta t}{\tau(\varepsilon)}\right)^{-\frac{n}{2}} + \frac{\tau(\varepsilon)}{\varepsilon} C(\bar{\tau}_0 + 1) \|D^0 - D_\infty\|_{H^1} \left(1 + \frac{\tau(\varepsilon)}{\varepsilon^2} \kappa \Delta t\right)^{-\frac{n}{2}},$$

and

$$\|D_0^n - D_{\infty,0}^n\|_{H^{-1}} \leq C \left(\|D_0^0 - D_{\infty,0}^0\|_{H^{-1}} + \frac{\tau(\varepsilon)}{\varepsilon} (\bar{\tau}_0^3 + 1) \|D^0 - D_\infty\|_{H^1} \right) \left(1 + \frac{\tau(\varepsilon)}{\varepsilon^2} \kappa \Delta t\right)^{-\frac{n}{2}}.$$

In the latter estimate, constant C only depends on Φ , T_0 and R_h and exponent κ is given by

$$\kappa = \frac{1}{C (\bar{\tau}_0^2 + 1)}.$$

Furthermore the shorthand notation $\|\cdot\|_{H^1}$ stands for

$$\|D\|_{H^1}^2 := \|\mathcal{B}D\|_{L^2}^2 + \|D\|_{L^2}^2.$$

The proof of these results follows almost exactly the same lines as the proof of Theorems 2.1 and 2.2 thanks to the Lemma 3.3, which constitutes the keystone of our analysis and which ensures that our discretization \mathcal{A}_h of operator \mathcal{A} shares all the important properties (2.12)-(2.18) of its continuous analog. The only difference comes down to some numerical remainder terms that we easily control applying methods already developed in the continuous section.

3.3. Preliminary properties. This section is dedicated to the following fundamental Lemma, which ensures that the key properties (2.12)-(2.18) of the continuous operator \mathcal{A} are preserved by its discrete analog \mathcal{A}_h . Thanks to this Lemma, all the computations carried in Section 2 directly translate into the discrete framework.

Lemma 3.3. *Consider the discrete operators \mathcal{A}_h and \mathcal{A}_h^* given in (3.2). Then we have for any $u = (u_j)_{j \in \mathcal{J}}$ and $v = (v_j)_{j \in \mathcal{J}}$*

(1) *preservation of the duality formula*

$$\langle \mathcal{A}_h u, v \rangle = \langle u, \mathcal{A}_h^* v \rangle;$$

(2) preservation of the kernel of operator \mathcal{A}_h

$$\mathcal{A}_h D_{\infty,0} = 0,$$

where the equilibrium D_{∞} is given by (3.5);

(3) preservation of the mass conservation properties

$$(3.12) \quad \sum_{j \in \mathcal{J}} \Delta x_j \mathcal{A}_j^* u \sqrt{\rho_{\infty,j}} = 0,$$

and for all $n \geq 0$, the solution $D_0^n = (\mathcal{D}_{0,j}^n)_{j \in \mathcal{J}}$ to (3.1) with index $k = 0$ verifies

$$(3.13) \quad \sum_{j \in \mathcal{J}} \Delta x_j \mathcal{D}_{0,j}^n \sqrt{\rho_{\infty,j}} = \sum_{j \in \mathcal{J}} \Delta x_j \rho_{\infty,j};$$

(4) preservation of the sum property

$$\|(\mathcal{A}_h + \mathcal{A}_h^*) u\|_{L^2} \leq \frac{1}{\sqrt{T_0}} \|\Phi\|_{W^{1,\infty}} \|u\|_{L^2};$$

(5) preservation with the commutator property

$$\|[\mathcal{A}_h, \mathcal{A}_h^*] u\|_{L^2} \leq C \|\Phi\|_{W^{2,\infty}} \|u\|_{L^2},$$

where constant C depends only on R_h (see (3.11)), it is explicitly given by

$$C = 2 + R_h;$$

(6) conservation of the Poincaré-Wirtinger inequality: under condition (3.8) on u there exists a constant $C_d > 0$ depending only on Φ and T_0 such that

$$(3.14) \quad \|u\|_{L^2} \leq C_d \|\mathcal{A}_h u\|_{L^2}.$$

Remark 3.4. When the mesh is regular, item (5) in Lemma 3.3 may be improved into a consistent estimate compared to its continuous analog (2.17), indeed we easily obtain

$$\|[\mathcal{A}_h, \mathcal{A}_h^*] u\|_{L^2} \leq \left(\|\Phi\|_{W^{2,\infty}} + \frac{h}{2} \|\Phi\|_{W^{3,\infty}} \right) \|u\|_{L^2},$$

for any $u = (u_j)_{j \in \mathcal{J}}$, following the same method as in the proof.

Proof. To prove item (1), we consider any $(u_j)_{j \in \mathcal{J}}$ and $(v_j)_{j \in \mathcal{J}}$, we have after a discrete integration by part and using periodic boundary conditions

$$\begin{aligned} \langle \mathcal{A}_h u, v \rangle &= \sum_{j \in \mathcal{J}} \Delta x_j \mathcal{A}_j u v_j \\ &= \sum_{j \in \mathcal{J}} \sqrt{T_0} \left(\frac{u_{j+1} - u_{j-1}}{2} v_j - \Delta x_j \frac{E_j}{2T_0} u_j v_j \right) \\ &= \sum_{j \in \mathcal{J}} -\sqrt{T_0} \left(\frac{v_{j+1} - v_{j-1}}{2} u_j + \Delta x_j \frac{E_j}{2T_0} v_j u_j \right) = \langle u, \mathcal{A}_h^* v \rangle. \end{aligned}$$

To prove item (2), we look for $D = (D_k)_{k \in \mathbb{N}}$ such that $\mathcal{A}_h D_0 = 0$, that is,

$$0 = \mathcal{A}_i D_0 = \frac{\sqrt{T_0}}{2 \Delta x_j} \left(\mathcal{D}_{0,j+1} - \mathcal{D}_{0,j-1} + \frac{\Phi_{j+1} - \Phi_{j-1}}{2T_0} \mathcal{D}_{0,j} \right).$$

Hence, from the particular choice of the discrete electric field (3.4), we have that

$$\frac{\mathcal{D}_{0,j+1} - \mathcal{D}_{0,j-1}}{\mathcal{D}_{0,j}} - \frac{\sqrt{\rho_{\infty,j+1}} - \sqrt{\rho_{\infty,j-1}}}{\sqrt{\rho_{\infty,j}}} = 0,$$

which yields to definition (3.5).

We turn to the mass conservation property (3). According to the definition (3.3) of \mathcal{A}_h^* , it holds

$$\mathcal{A}_j^* u \sqrt{\rho_{\infty,j}} \Delta x_j = -\sqrt{T_0} \left(\sqrt{\rho_{\infty,j}} \frac{u_{j+1} - u_{j-1}}{2} + \frac{\sqrt{\rho_{\infty,j+1}} - \sqrt{\rho_{\infty,j-1}}}{2} u_j \right).$$

Therefore, relation (3.12) is obtained summing the latter over $j \in \mathcal{J}$ and performing a discrete integration by part. Relation (3.13) is obtained evaluating equation (3.1) with index $k = 0$ and $j \in \mathcal{J}$, multiplying by $\sqrt{\rho_{\infty,j}} \Delta x_j$, then summing over $j \in \mathcal{J}$ and applying relation (3.12) with $u = D_1^{n+1}$.

We prove item (4) taking the L^2 norm in the following relation

$$\sqrt{T_0} (\mathcal{A}_j + \mathcal{A}_j^*) u = - \frac{2T_0}{\sqrt{\rho_{\infty,j}}} \frac{\sqrt{\rho_{\infty,j+1}} - \sqrt{\rho_{\infty,j-1}}}{2\Delta x_j} u_j,$$

which holds for any $u = (u_j)_{j \in \mathcal{J}}$.

We turn to item (5) and compute the commutator for the discrete operator $[\mathcal{A}_h, \mathcal{A}_h^*]$ as

$$\begin{aligned} [\mathcal{A}_h, \mathcal{A}_h^*]_j u &= (\mathcal{A}_h \mathcal{A}_h^* - \mathcal{A}_h^* \mathcal{A}_h)_j u \\ &= - \frac{E_{j+1} - E_{j-1}}{4\Delta x_j} (u_{j+1} + u_{j-1}) - \frac{E_{j+1} - 2E_j + E_{j-1}}{4\Delta x_j} (u_{j+1} - u_{j-1}), \end{aligned}$$

and therefore, we deduce item (5) taking the L^2 norm in the latter result.

Finally, we prove the Poincaré inequality (3.14). Consider $u = (u_j)_{j \in \mathcal{J}}$ which meets condition (3.8) and let us denote by $\bar{\rho}_{\infty}$ the mean of ρ_{∞}

$$\bar{\rho}_{\infty} = \sum_{j \in \mathcal{J}} \Delta x_j \rho_{\infty,j}.$$

First using the zero weighted average assumption (3.8) on u , we remark that the cross term vanishes and

$$\begin{aligned} \|u\|_{L^2}^2 &= \sum_{j \in \mathcal{J}} \Delta x_j \left(\frac{u_j}{\sqrt{\rho_{\infty,j}}} \right)^2 \rho_{\infty,j}, \\ &= \frac{1}{2\bar{\rho}_{\infty}} \sum_{j \in \mathcal{J}} \sum_{k \in \mathcal{J}} \Delta x_j \Delta x_k \left(\frac{u_k}{\sqrt{\rho_{\infty,k}}} - \frac{u_j}{\sqrt{\rho_{\infty,j}}} \right)^2 \rho_{\infty,j} \rho_{\infty,k}, \\ &= \frac{1}{\bar{\rho}_{\infty}} \sum_{k \in \mathcal{J}} \sum_{j < k} \Delta x_j \Delta x_k \left(\frac{u_k}{\sqrt{\rho_{\infty,k}}} - \frac{u_j}{\sqrt{\rho_{\infty,j}}} \right)^2 \rho_{\infty,j} \rho_{\infty,k}. \end{aligned}$$

For $j < k$, we have

$$\frac{u_k}{\sqrt{\rho_{\infty,k}}} - \frac{u_j}{\sqrt{\rho_{\infty,j}}} = \sum_{l=j}^{k-1} \frac{u_{l+1}}{\sqrt{\rho_{\infty,l+1}}} - \frac{u_l}{\sqrt{\rho_{\infty,l}}},$$

which yields

$$(3.15) \quad \|u\|_{L^2}^2 \leq \bar{\rho}_{\infty} \left(\sum_{l \in \mathcal{J}} \frac{u_{l+1}}{\sqrt{\rho_{\infty,l+1}}} - \frac{u_l}{\sqrt{\rho_{\infty,l}}} \right)^2.$$

On the other hand, we set for any $j \in \mathcal{J}$

$$\sqrt{\bar{\rho}_{\infty,j}} = \frac{\sqrt{\rho_{\infty,j-1}} + \sqrt{\rho_{\infty,j+1}}}{2}, \quad \text{and} \quad \eta_j = \frac{\sqrt{\rho_{\infty,j+1}} - \sqrt{\rho_{\infty,j-1}}}{2\sqrt{\bar{\rho}_{\infty,j}}},$$

and observe that the discrete operator $\mathcal{A}_h u$ may be written as

$$\frac{\Delta x_j}{\sqrt{\bar{\rho}_{\infty,j}}} \mathcal{A}_j u = \frac{\sqrt{T_0}}{2} \left[\left(\frac{u_{j+1}}{\sqrt{\rho_{\infty,j+1}}} - \frac{u_j}{\sqrt{\rho_{\infty,j}}} \right) (1 + \eta_j) + \left(\frac{u_j}{\sqrt{\rho_{\infty,j}}} - \frac{u_{j-1}}{\sqrt{\rho_{\infty,j-1}}} \right) (1 - \eta_j) \right].$$

Then we have using periodic boundary conditions

$$\begin{aligned} \sqrt{T_0} \sum_{j \in \mathcal{J}} \left(\frac{u_{j+1}}{\sqrt{\rho_{\infty,j+1}}} - \frac{u_j}{\sqrt{\rho_{\infty,j}}} \right) &= \frac{\sqrt{T_0}}{2} \sum_{j \in \mathcal{J}} \left(\frac{u_{j+1}}{\sqrt{\rho_{\infty,j+1}}} - \frac{u_j}{\sqrt{\rho_{\infty,j}}} \right) + \left(\frac{u_j}{\sqrt{\rho_{\infty,j}}} - \frac{u_{j-1}}{\sqrt{\rho_{\infty,j-1}}} \right) \\ &= \sum_{j \in \mathcal{J}} \frac{\Delta x_j}{\sqrt{\bar{\rho}_{\infty,j}}} \mathcal{A}_j u - \sqrt{T_0} \left(\frac{u_{j+1}}{\sqrt{\rho_{\infty,j+1}}} - \frac{u_j}{\sqrt{\rho_{\infty,j}}} \right) \frac{\eta_j - \eta_{j+1}}{2} \end{aligned}$$

Hence using that Φ is Lipschitzian, we have

$$|\eta_{j+1} - \eta_j| \leq C_\Phi h,$$

which yields that

$$\sqrt{T_0} \sum_{j \in \mathcal{J}} \left| \frac{u_{j+1}}{\sqrt{\rho_{\infty,j+1}}} - \frac{u_j}{\sqrt{\rho_{\infty,j}}} \right| \leq \sum_{j \in \mathcal{J}} \frac{\Delta x_j}{\sqrt{\bar{\rho}_{\infty,j}}} |\mathcal{A}_j u| + C_\Phi h \sqrt{T_0} \sum_{j \in \mathcal{J}} \left| \frac{u_{j+1}}{\sqrt{\rho_{\infty,j+1}}} - \frac{u_j}{\sqrt{\rho_{\infty,j}}} \right|.$$

On the one hand, we consider the case when h is small enough such that $1 - C_\Phi h \geq 1/2$, we get that

$$\sum_{j \in \mathcal{J}} \left| \frac{u_{j+1}}{\sqrt{\rho_{\infty,j+1}}} - \frac{u_j}{\sqrt{\rho_{\infty,j}}} \right| \leq \frac{2}{\sqrt{T_0}} \sum_{j \in \mathcal{J}} \frac{\Delta x_j}{\sqrt{\bar{\rho}_{\infty,j}}} |\mathcal{A}_j u|$$

On the other hand, when $1 - C_\Phi h \leq 1/2$ (the space step h is large), we use the fact that in finite dimension, both semi-norms are equivalent. Thus, there exists a constant $C'_\Phi > 0$, independent of h , such that

$$\sum_{j \in \mathcal{J}} \left| \frac{u_{j+1}}{\sqrt{\rho_{\infty,j+1}}} - \frac{u_j}{\sqrt{\rho_{\infty,j}}} \right| \leq \frac{C'_\Phi}{\sqrt{T_0}} \sum_{j \in \mathcal{J}} \frac{\Delta x_j}{\sqrt{\bar{\rho}_{\infty,j}}} |\mathcal{A}_j u|.$$

Gathering the latter result with (3.15), it yields

$$\|u\|_{L^2}^2 \leq \frac{(C'_\Phi)^2 \bar{\rho}_\infty}{T_0} \left(\sum_{j \in \mathcal{J}} \frac{\Delta x_j}{\sqrt{\bar{\rho}_{\infty,j}}} |\mathcal{A}_j u| \right)^2.$$

Using the Cauchy-Schwarz inequality, we obtain the result

$$\|u\|_{L^2}^2 \leq C_d^2 \|\mathcal{A}_h u\|_{L^2}^2,$$

where C_d^2 is given by

$$C_d^2 = \frac{(C'_\Phi)^2 \bar{\rho}_\infty}{T_0} \sum_{j \in \mathcal{J}} \frac{\Delta x_j}{|\sqrt{\bar{\rho}_{\infty,j}}|^2}.$$

□

From the latter results, we may now get estimates on the solution u_h to (3.9) as in Lemma 2.3 in the continuous setting.

Lemma 3.5. *Let us consider the solution u_h to (3.9) with source term $g = (g_j)_{j \in \mathcal{J}}$ satisfying the compatibility assumption (3.8). Then, u_h satisfies the following estimate*

$$(3.16) \quad \|\mathcal{A}_h u_h\|_{L^2} \leq C_d \|g\|_{L^2},$$

and

$$(3.17) \quad \|\mathcal{A}_h^2 u_h\|_{l^2} \leq \left(1 + \frac{C_d}{\sqrt{T_0}} \|\partial_x \Phi\|_{L^\infty} \right) \|g\|_{L^2}.$$

Moreover, consider now $(D_k^n)_{k \in \mathbb{N}}$ solution to (3.1) and $u_h^n = (u_j^n)_{j \in \mathcal{J}}$ the corresponding solution to (3.9) with the source term $D_0^n - \sqrt{\rho}_\infty$. Then we define $d_t u_h^{n+1}$ as

$$(3.18) \quad d_t u_h^{n+1} = \frac{u_h^{n+1} - u_h^n}{\Delta t},$$

which satisfies

$$(3.19) \quad \varepsilon \|\mathcal{A}_h d_t u_h^{n+1}\|_{L^2} \leq \|D_1^{n+1}\|_{L^2}.$$

Proof. We follow the proof of Lemma 2.3, we multiply (3.9) by $\Delta x_i u_i$, sum over $i \in \mathcal{J}$ and apply item (1) of Lemma 3.3, it yields

$$\|\mathcal{A}_h u_h\|_{L^2}^2 \leq \|D - \sqrt{\rho}_\infty\|_{L^2} \|u_h\|_{L^2},$$

hence the discrete Wirtinger-Poincaré inequality, obtained in Lemma 3.5, gives,

$$\|\mathcal{A}_h u_h\|_{L^2} \leq C_d \|D - \sqrt{\rho}_\infty\|_{L^2}.$$

For the second estimate, we observe that

$$(\mathcal{A}_h + \mathcal{A}_h^*)_j u_h = \frac{\sqrt{\rho_{\infty,j+1}} - \sqrt{\rho_{\infty,j-1}}}{2 \Delta x_j \sqrt{\rho_{\infty,j}}} u_j$$

hence we obtain

$$\begin{aligned} (\mathcal{A}_h^2)_j u_h &= -(\mathcal{A}_h^* \mathcal{A}_h)_j u_h + \frac{\sqrt{\rho_{\infty,j+1}} - \sqrt{\rho_{\infty,j-1}}}{2 \Delta x_j \sqrt{\rho_{\infty,j}}} \mathcal{A}_j u_h \\ &= -\left(D_{0,j} - \sqrt{\rho_{\infty,j}}\right) + \frac{\sqrt{\rho_{\infty,j+1}} - \sqrt{\rho_{\infty,j-1}}}{2 \Delta x_j \sqrt{\rho_{\infty,j}}} \mathcal{A}_j u_h. \end{aligned}$$

Since Φ is Lipschitzian and applying (3.16), we obtain the result

$$\|\mathcal{A}_h^2 u_h\|_{L^2} \leq C \|D(t) - \sqrt{\rho_\infty}\|_{L^2}.$$

For the third estimate we consider now the solution $D^n = (D_k^n)_{k \in \mathbb{N}}$ to (3.1) and u_h^n the solution to (3.9) with source term $D_0^n - \sqrt{\rho_\infty}$. We get for any $j \in \mathcal{J}$,

$$(\mathcal{A}_h^* \mathcal{A}_h)_j d_t u_h^{n+1} = \frac{\mathcal{D}_{0,j}^{n+1} - \mathcal{D}_{0,j}^n}{\Delta t} = -\frac{1}{\varepsilon} \mathcal{A}_j^* D_1^{n+1}.$$

Then we multiply by $\Delta x_j d_t u_h^{n+1}$, sum over $j \in \mathcal{J}$ and use (2.12) to get

$$\|\mathcal{A}_h d_t u_h^{n+1}\|_{L^2}^2 = -\frac{1}{\varepsilon} \langle D_1^{n+1}, \mathcal{A}_h d_t u_h^{n+1} \rangle \leq \frac{1}{\varepsilon} \|D_1^{n+1}\|_{L^2} \|\mathcal{A}_h d_t u_h^{n+1}\|_{L^2}.$$

□

3.4. Proof of Theorem 3.1. We split the proof of Theorem 3.1 into two steps corresponding to the L^2 and H^1 convergence result. Thanks to Lemma 3.5, the method followed in Section 2 to prove the continuous analog to this result (Theorem 2.1) directly applies here, excepted for some additional numerical remainders for which we give a detailed method in order to get control over.

We define \mathcal{H}_0^n as

$$(3.20) \quad \mathcal{H}_0^n = \frac{1}{2} \|D^n - D_\infty\|_{L^2}^2 + \alpha_0 \left\langle \frac{\tau(\varepsilon)}{\varepsilon} \mathcal{A}_h^* D_1^n, u_h^n \right\rangle,$$

where u^n is solution to (3.9) with $D_0^n - \sqrt{\rho_\infty}$ as a source term. First let us point out that \mathcal{H}_0^n shares the same properties as its continuous analog, indeed it holds

Lemma 3.6. *Suppose that condition (1.7) on $\tau(\varepsilon)$ is satisfied. Then for all $\alpha_0 \in (0, \bar{\alpha}_0)$, with $\bar{\alpha}_0 = 1/(4\bar{\tau}_0 C_d)$ and $D^n = (\mathcal{D}_{k,j}^n)_{j \in \mathcal{J}, k \in \mathbb{N}}$, one has*

$$(3.21) \quad \frac{1}{4} \|D^n - D_\infty\|_{L^2}^2 \leq \mathcal{H}_0^n \leq \frac{3}{4} \|D^n - D_\infty\|_{L^2}^2.$$

Proof. The proof follows the same lines as the one of Lemma 2.4. □

We are now able to proceed to the proof of the first item (i) of Theorem 3.1. On the one hand, proceeding as the proof of item (i) in Theorem 2.1, it yields from Lemma 3.3

$$(3.22) \quad \frac{\mathcal{H}_0^{n+1} - \mathcal{H}_0^n}{\Delta t} = \mathcal{I}_1^{n+1} + \alpha_0 \mathcal{I}_2^{n+1} + \alpha_0 \mathcal{I}_3^{n+1} - \mathcal{R}_0^{n+1},$$

where

$$\mathcal{I}_1^{n+1} = -\frac{1}{\tau(\varepsilon)} \sum_{k \in \mathbb{N}^*} k \|D_k^{n+1}\|_{L^2}^2$$

whereas the other terms correspond to the additional term of the modified relative entropy,

$$\begin{cases} \mathcal{I}_2^{n+1} := -\frac{\tau(\varepsilon)}{\varepsilon^2} \left\langle \mathcal{A}_h^* \mathcal{A}_h (D_0^{n+1} - \sqrt{\rho_\infty}) - \sqrt{2} (\mathcal{A}_h^*)^2 D_2^{n+1}, u_h^{n+1} \right\rangle - \frac{1}{\varepsilon} \left\langle \mathcal{A}_h^* D_1^{n+1}, u_h^{n+1} \right\rangle, \\ \mathcal{I}_3^{n+1} := +\frac{\tau(\varepsilon)}{\varepsilon} \left\langle \mathcal{A}_h^* D_1^{n+1}, d_t u_h^{n+1} \right\rangle, \end{cases}$$

where $d_t u_h^{n+1}$ is given in (3.18) and \mathcal{R}_0 is a purely numerical remainder given by

$$(3.23) \quad \mathcal{R}_0^{n+1} = \frac{1}{2\Delta t} \|D^{n+1} - D^n\|_{L^2}^2 + \alpha_0 \frac{\tau(\varepsilon)}{\varepsilon} \langle \mathcal{A}_h^* (D_1^{n+1} - D_1^n), d_t u_h^{n+1} \rangle.$$

Both terms \mathcal{I}_2^{n+1} and \mathcal{I}_3^{n+1} can be estimated as in the proof of item (i) in Theorem 2.1, which yields

$$\mathcal{I}_2^{n+1} \leq -\frac{\tau(\varepsilon)}{\varepsilon^2} (1 - C\eta) \|D_0^{n+1} - D_{\infty,0}\|_{L^2}^2 + \frac{C}{2\eta} \left(\frac{\tau(\varepsilon)}{\varepsilon^2} \|D_2^{n+1}\|_{L^2}^2 + \frac{1}{\tau(\varepsilon)} \|D_1^{n+1}\|_{L^2}^2 \right),$$

for any positive η and for some positive constant C depending only on T_0 and Φ and

$$\mathcal{I}_3^{n+1} \leq \frac{\tau(\varepsilon)}{\varepsilon^2} \|D_1^{n+1}\|_{L^2}^2.$$

From these latter estimates and taking $\eta = 1/(2C)$ and as long as

$$\alpha_0 < \frac{1}{C(\bar{\tau}_0^2 + 1)},$$

for C great enough and taking κ_0 such that $3\kappa_0/4 = \alpha_0/2$, we get that

$$\frac{\mathcal{H}_0^{n+1} - \mathcal{H}_0^n}{\Delta t} + \frac{\tau(\varepsilon)}{\varepsilon^2} \kappa_0 \mathcal{H}_0^{n+1} \leq -\mathcal{R}_0^{n+1}.$$

Now we treat the remainder term \mathcal{R}_0^{n+1} , observing that

$$|\langle \mathcal{A}_h^* (D_1^{n+1} - D_1^n), d_t u_h^{n+1} \rangle| \leq \frac{1}{2\Delta t} (\|D_1^{n+1} - D_1^n\|_{L^2}^2 + \|\mathcal{A}_h (u_h^{n+1} - u_h^n)\|_{L^2}^2).$$

Therefore, applying (3.16) in Lemma 3.5 with source term $D_0^{n+1} - D_0^n$, we obtain

$$|\langle \mathcal{A}_h^* (D_1^{n+1} - D_1^n), d_t u_h^{n+1} \rangle| \leq \frac{1 + C_d^2}{2\Delta t} \|D^{n+1} - D^n\|_{L^2}^2.$$

Since $\tau(\varepsilon)$ meets assumption (1.7), the latter estimate ensures that, as long as $\alpha_0 \leq (\bar{\tau}_0(1 + C_d^2))^{-1}$, it holds

$$0 \leq \mathcal{R}_0^{n+1},$$

which yields

$$\frac{\mathcal{H}_0^{n+1} - \mathcal{H}_0^n}{\Delta t} + \frac{\tau(\varepsilon)}{\varepsilon^2} \kappa_0 \mathcal{H}_0^{n+1} \leq 0.$$

The result follows by applying a discrete Gronwall's lemma and then applying Lemma 3.6 in order to substitute \mathcal{H}_0^n with the L^2 norm of $D^n - D_\infty$ in the latter estimate.

Now we turn to the proof of the second item (ii) of Theorem 3.1. Following Section 2.3, we introduce \mathcal{H}_1^n given by

$$(3.24) \quad \mathcal{H}_1^n = \frac{1}{2} \|\mathcal{B}_h D^n\|_{L^2}^2 + \alpha_1 \left\langle \frac{\tau(\varepsilon)}{\varepsilon} \mathcal{A}_h D_0^n, D_1^n \right\rangle,$$

where α_1 has to be determined. Once again, \mathcal{H}_1^n shares the same properties as its continuous analog

Lemma 3.7. *Suppose that condition (1.7) on $\tau(\varepsilon)$ is satisfied. Then for all $\alpha_1 \in (0, \bar{\alpha}_1)$, with $\bar{\alpha}_1 = 1/(2\bar{\tau}_0)$ and $D^n = (D_k^n)_{k \in \mathbb{N}}$, one has*

$$\|\mathcal{B}_h D^n\|_{L^2}^2 - \|D^n - D_\infty\|_{L^2}^2 \leq 4\mathcal{H}_1^n \leq 3\|\mathcal{B}_h D^n\|_{L^2}^2 + \|D^n - D_\infty\|_{L^2}^2.$$

Proof. The result is obtained applying the same method as in the proof of Lemma 2.5. \square

We now compute the variation of the modified relative entropy between one time step from t^n to t^{n+1} and split it into three terms

$$\frac{\mathcal{H}_1^{n+1} - \mathcal{H}_1^n}{\Delta t} = \mathcal{J}_1^{n+1} + \alpha_1 \mathcal{J}_2^{n+1} - \mathcal{R}_1^{n+1},$$

where \mathcal{J}_1^{n+1} is given by

$$\mathcal{J}_1^{n+1} := -\frac{1}{\varepsilon} \sum_{k \geq 2} \sqrt{k} \langle [\mathcal{A}_h^*, \mathcal{A}_h] D_{k-1}^{n+1}, \mathcal{A}_h^* D_k^{n+1} \rangle - \frac{1}{\tau(\varepsilon)} \sum_{k \in \mathbb{N}^*} k \|\mathcal{B}_{h,k} D_k^{n+1}\|_{L^2}^2$$

and

$$\begin{aligned} \mathcal{J}_2^{n+1} &:= \frac{\tau(\varepsilon)}{\varepsilon^2} \left(\langle \mathcal{A}_h \mathcal{A}_h^* D_1^{n+1}, D_1^{n+1} \rangle - \|\mathcal{A}_h D_0^{n+1}\|_{L^2}^2 + \sqrt{2} \langle \mathcal{A}_h D_0^{n+1}, \mathcal{A}_h^* D_2^{n+1} \rangle \right) \\ &\quad - \frac{1}{\varepsilon} \langle D_1^{n+1}, \mathcal{A}_h D_0^{n+1} \rangle \end{aligned}$$

whereas \mathcal{R}_1^n is given by

$$(3.25) \quad \mathcal{R}_1^{n+1} = \frac{1}{\Delta t} \left(\frac{1}{2} \|\mathcal{B}_h (D^{n+1} - D^n)\|_{L^2}^2 + \alpha_1 \frac{\tau(\varepsilon)}{\varepsilon} \langle \mathcal{A}_h (D_0^{n+1} - D_0^n), D_1^{n+1} - D_1^n \rangle \right).$$

On the one hand we estimate the terms \mathcal{J}_1^{n+1} and \mathcal{J}_2^{n+1} following the same method as the one presented to estimate their continuous analogs $\mathcal{J}_1(t)$ and $\mathcal{J}_2(t)$ (see the proof item (ii) in Theorem 2.1). On the other hand, the remainder term \mathcal{R}_1^{n+1} can be treated as \mathcal{R}_0^{n+1} in the proof of (i) of Theorem 3.1. Indeed,

$$|\langle \mathcal{A}_h (D_0^{n+1} - D_0^n), D_1^{n+1} - D_1^n \rangle| \leq \frac{1}{2} (\|D_0^{n+1} - D_0^n\|_{L^2}^2 + \|\mathcal{A}^* (D_1^{n+1} - D_1^n)\|_{L^2}^2).$$

According to the mass conservation property (3.13), $D_0^{n+1} - D_0^n$ meets condition (3.8). Therefore we may apply the discrete Poincaré inequality (3.14) to bound $\|D_0^{n+1} - D_0^n\|_{L^2}^2$ in the latter estimate, this yields

$$|\langle \mathcal{A}_h (D_0^{n+1} - D_0^n), D_1^{n+1} - D_1^n \rangle| \leq \frac{1 + C_d^2}{2} \|\mathcal{B}_h (D^{n+1} - D^n)\|_{L^2}^2.$$

As in the case of \mathcal{R}_0^{n+1} in the former section, the latter estimate ensures that, as long as $\alpha_0 \leq (\bar{\tau}_0 (1 + C_d^2))^{-1}$, it holds

$$0 \leq \mathcal{R}_1^{n+1}.$$

Hence, we obtain the result by adapting at the discrete level the proof of item (ii) in Theorem 2.1 to bound \mathcal{J}_1^{n+1} and \mathcal{J}_2^{n+1} and applying a discrete Gronwall lemma.

3.5. Proof of Theorem 3.2. As in the continuous setting, we prove that the solution $D^n = (D_k^n)_{k \in \mathbb{N}}$ to (3.1) converges to $D_{\tau_0}^n = (D_{\tau_0, k}^n)_{k \in \mathbb{N}}$ given by (3.6)-(3.7), whose long time behavior is easily obtained relying on the discrete Poincaré inequality (3.14)

$$(3.26) \quad \|D_{\tau_0}^n - D_{\infty}\|_{L^2} \leq \|D_{\tau_0}^0 - D_{\infty}\|_{L^2} \left(1 + \frac{2\tau_0}{C_d^2} \Delta t \right)^{-\frac{n}{2}}, \quad \forall t \in \mathbb{R}^+.$$

We estimate $\|D_0^n - D_{\tau_0, 0}^n\|_{H^{-1}}$ by introducing the intermediate quantity \mathcal{E} , meant to recover coercivity with respect to the first coefficient D_0^n

$$(3.27) \quad \mathcal{E}^n = \frac{1}{2} \|\mathcal{A}_h v_h^n\|_{L^2}^2,$$

where v_h^n solves (3.9) with source term

$$g = D_0^n + \frac{\tau(\varepsilon)}{\varepsilon} \mathcal{A}_h^* D_1^n - D_{\tau_0, 0}^n.$$

The following lemma ensures that the quantity \mathcal{E}^n shares the same properties as its continuous analog. Indeed it holds

Lemma 3.8. *We consider \mathcal{E}^n defined by (3.27). It holds uniformly with respect to ε*

$$(3.28) \quad \mathcal{E}^n \leq \|D^n - D_{\tau_0}^n\|_{H^{-1}}^2 + C_d^2 \frac{\tau(\varepsilon)^2}{\varepsilon^2} \|\mathcal{B}_h D^n\|_{L^2}^2,$$

and

$$(3.29) \quad \frac{1}{4} \|D^n - D_{\tau_0}^n\|_{H^{-1}}^2 - C_d^2 \frac{\tau(\varepsilon)^2}{2\varepsilon^2} \|\mathcal{B}_h D^n\|_{L^2}^2 \leq \mathcal{E}^n.$$

Proof. Defining w_h^n and u_{τ_0} as the respective solutions to (3.9) with source term $g = \mathcal{A}_h^* D_1^n$ and $D_{\tau_0, 0}^n - D_{\infty, 0}$, it holds

$$v_h^n = u_h^n - u_{\tau_0}^n + \frac{\tau(\varepsilon)}{\varepsilon} w_h^n.$$

Applying operator \mathcal{A}_h to the latter relation, taking the L^2 norm, and applying the triangular inequality, it yields

$$\sqrt{2\mathcal{E}^n} \leq \|\mathcal{A}_h(u_h^n - u_{\tau_0}^n)\|_{L^2} + \frac{\tau(\varepsilon)}{\varepsilon} \|\mathcal{A}_h w_h^n\|_{L^2},$$

and

$$\|\mathcal{A}_h(u_h^n - u_{\tau_0}^n)\|_{L^2} - \frac{\tau(\varepsilon)}{\varepsilon} \|\mathcal{A}_h w_h^n\|_{L^2} \leq \sqrt{2\mathcal{E}^n}.$$

We estimate $\|\mathcal{A}_h w_h^n\|_{L^2}$ applying (3.16) in Lemma 3.5, this yields

$$\sqrt{2\mathcal{E}^n} \leq \|D^n - D_{\tau_0}^n\|_{H^{-1}} + \frac{\tau(\varepsilon)}{\varepsilon} C_d \|\mathcal{B}_h D^n\|_{L^2},$$

and

$$\|D^n - D_{\tau_0}^n\|_{H^{-1}} - \frac{\tau(\varepsilon)}{\varepsilon} C_d \|\mathcal{B}_h D^n\|_{L^2} \leq \sqrt{2\mathcal{E}^n}.$$

We obtain the result taking the square of the latter inequalities and applying Young's inequality. \square

We now treat the asymptotic limit $\varepsilon \rightarrow 0$ corresponding to the case of (i) in Theorem 3.2 and therefore suppose that $\tau(\varepsilon)$ fulfills the assumptions (1.7), (1.8) and (2.11). As in the continuous setting, we start by deriving the first result in (i) of Theorem 3.2. We already know from the L^2 estimate (3.22) that

$$\begin{aligned} \frac{\|D_{\perp}^{n+1}\|_{L^2}^2 - \|D_{\perp}^n\|_{L^2}^2}{2\Delta t} &+ \frac{1}{\tau(\varepsilon)} \|D_{\perp}^{n+1}\|_{L^2}^2 \\ &\leq - \left\langle \frac{D_0^{n+1} - D_0^n}{\Delta t}, D_0^{n+1} - D_0^n \right\rangle - \frac{1}{2\Delta t} \sum_{k \in \mathbb{N}^*} \|D_k^{n+1} - D_k^n\|_{L^2}^2 \\ &\leq - \left\langle \frac{D_0^{n+1} - D_0^n}{\Delta t}, D_0^{n+1} - D_{\infty,0} \right\rangle. \end{aligned}$$

Therefore, we replace $D_0^{n+1} - D_0^n$ according to equation (3.1), and after applying the duality formula of Lemma 3.3-(1), we obtain

$$\frac{\|D_{\perp}^{n+1}\|_{L^2}^2 - \|D_{\perp}^n\|_{L^2}^2}{\Delta t} + \frac{1}{\tau(\varepsilon)} \|D_{\perp}^{n+1}\|_{L^2}^2 \leq -\frac{1}{\varepsilon} \langle D_1^{n+1}, \mathcal{A}_h D_0^{n+1} \rangle,$$

Hence, after multiplying by Δt and applying the Young inequality to bound the right hand side of the latter inequality, it yields

$$\left(1 + \frac{\Delta t}{\tau(\varepsilon)}\right) \|D_{\perp}^{n+1}\|_{L^2}^2 \leq \|D_{\perp}^n\|_{L^2}^2 + \Delta t \frac{\tau(\varepsilon)}{\varepsilon^2} \|\mathcal{B}_h D^{n+1}\|_{L^2}^2.$$

To achieve the proof, it remains to bound $\|\mathcal{B}_h D^{n+1}\|_{L^2}^2$ by applying Theorem 3.1-(ii) and again following the line of the proof of Theorem 2.2, we deduce

$$\begin{aligned} \|D_{\perp}^n\|_{L^2}^2 &\leq \\ \|D_{\perp}^0\|_{L^2}^2 &\left(1 + \frac{\Delta t}{\tau(\varepsilon)}\right)^{-n} + 6 (C(\bar{\tau}_0^2 + 1) \|D^0 - D_{\infty}\|_{L^2}^2 + \|\mathcal{B}_h D^0\|_{L^2}^2) \frac{\tau(\varepsilon)^2}{\varepsilon^2} \left(1 + \frac{\tau(\varepsilon)}{\varepsilon^2} \kappa \Delta t\right)^{-n}. \end{aligned}$$

Therefore we obtain the result taking the square root in the latter estimate and substituting $\tau(\varepsilon)$ with $\tau_0 \varepsilon^2$ according to assumption (2.11).

To prove the second result of (i) in Theorem 3.2 we evaluate \mathcal{E}^n as in the proof of Theorem 2.2 observing that

$$\|\mathcal{A}_h v_h^n\|_{L^2}^2 = \left\langle D_0^n + \frac{\tau(\varepsilon)}{\varepsilon} \mathcal{A}_h^* D_1^n - D_{\tau_0,0}^n, v_h^n \right\rangle$$

hence, relying on equations (3.1) and (3.7) we deduce

$$\frac{\mathcal{E}^{n+1} - \mathcal{E}^n}{\Delta t} = -\frac{\tau(\varepsilon)}{\varepsilon^2} \|D_0^n + \frac{\tau(\varepsilon)}{\varepsilon} \mathcal{A}_h^* D_1^n - D_{\tau_0}^n\|_{L^2}^2 + \mathcal{E}_1^{n+1} + \mathcal{E}_2^{n+1} + \mathcal{E}_3^{n+1} - \mathcal{R}_3^{n+1},$$

where \mathcal{E}_1^{n+1} , \mathcal{E}_2^{n+1} and \mathcal{E}_3^{n+1} are the numerical equivalents of the terms $\mathcal{E}_1(t)$, $\mathcal{E}_2(t)$ and $\mathcal{E}_3(t)$ in the proof of Theorem 2.2

$$\begin{cases} \mathcal{E}_1^{n+1} = \left(\tau_0 - \frac{\tau(\varepsilon)}{\varepsilon^2} \right) \langle \mathcal{A}_h^* \mathcal{A}_h D_{\tau_0,0}^{n+1}, v_h^{n+1} \rangle, \\ \mathcal{E}_2^{n+1} = \frac{\tau(\varepsilon)^2}{\varepsilon^3} \langle \mathcal{A}_h^* \mathcal{A}_h D_1^{n+1}, v_h^{n+1} \rangle, \\ \mathcal{E}_3^{n+1} = \sqrt{2} \frac{\tau(\varepsilon)}{\varepsilon^2} \langle (\mathcal{A}_h^*)^2 D_2^{n+1}, v_h^{n+1} \rangle, \end{cases}$$

and \mathcal{R}_3^{n+1} is a numerical dissipation term

$$\mathcal{R}_3^{n+1} = \frac{1}{2\Delta t} \|\mathcal{A}_h (v_h^{n+1} - v_h^n)\|_{L^2}^2.$$

Since \mathcal{R}_3^{n+1} is positive, we apply the same method as the one presented in the proof of Theorem 2.2 and therefore we obtain the following estimate for \mathcal{E}^n

$$\begin{aligned} \left(1 + \frac{\tau(\varepsilon)\Delta t}{C_d^2 \varepsilon^2} \right) \mathcal{E}^{n+1} &\leq \mathcal{E}^n + C \Delta t \frac{\tau(\varepsilon)}{\varepsilon^2} (1 + \bar{\tau}_0^2) \|D_{\perp}^{n+1}\|_{L^2}^2 \\ &\quad + C \Delta t \frac{\varepsilon^2}{\tau(\varepsilon)} \left| \tau_0 - \frac{\tau(\varepsilon)}{\varepsilon^2} \right|^2 \|D_{\tau_0}^{n+1} - D_{\infty}\|_{L^2}^2, \end{aligned}$$

for some constant C depending only on Φ and T_0 . In the latter inequality, we bound $\|D_{\tau_0}^{n+1} - D_{\infty}\|_{L^2}^2$ according to (3.26) and the norm of D_{\perp} according to the first estimate of (i) in Theorem 3.2. Then we multiply the inequality by $\left(1 + \frac{\tau(\varepsilon)\Delta t}{C_d^2 \varepsilon^2} \right)^n$ and sum for k ranging from 0 to $n-1$, it yields

$$\begin{aligned} \mathcal{E}^n &\leq \left(\mathcal{E}^0 + C \frac{\tau(\varepsilon)^2}{\varepsilon^2} (\bar{\tau}_0^6 + 1) \|D^0 - D_{\infty}\|_{H^1}^2 \right) \left(1 + \frac{\tau(\varepsilon)}{\varepsilon^2} \kappa \Delta t \right)^{-n} \\ &\quad + C \left| \frac{\tau_0 \varepsilon^2}{\tau(\varepsilon)} - 1 \right|^2 \|D_{\tau_0}^0 - D_{\infty}\|_{L^2}^2 \left(\frac{2\tau_0 \varepsilon^2}{\tau(\varepsilon)} - 1 \right)^{-1} \left(1 + \frac{\tau(\varepsilon)}{\varepsilon^2} \kappa \Delta t \right)^{-n}. \end{aligned}$$

To conclude, we substitute \mathcal{E}^n (resp. \mathcal{E}^0) in the latter estimate according to (3.29) (resp. (3.28)) in Lemma 2.6 and then apply assumption (2.11) on $\tau(\varepsilon)$, which ensures $\left(\frac{2\tau_0 \varepsilon^2}{\tau(\varepsilon)} - 1 \right)^{-1} \leq 3$, this yields

$$\begin{aligned} \|D_0^n - D_{\tau_0,0}^n\|_{H^{-1}}^2 &\leq C \left(\|D_0^0 - D_{\tau_0,0}^0\|_{H^{-1}}^2 + \frac{\tau(\varepsilon)^2}{\varepsilon^2} (\bar{\tau}_0^6 + 1) \|D^0 - D_{\infty}\|_{H^1}^2 \right) \left(1 + \frac{\tau(\varepsilon)}{\varepsilon^2} \kappa \Delta t \right)^{-n} \\ &\quad + C \left| \frac{\tau_0 \varepsilon^2}{\tau(\varepsilon)} - 1 \right|^2 \|D_{\tau_0}^0 - D_{\infty}\|_{L^2}^2 \left(1 + \frac{\tau(\varepsilon)}{\varepsilon^2} \kappa \Delta t \right)^{-n}. \end{aligned}$$

We obtain the result taking the square root in the latter estimate and substituting $\tau(\varepsilon)$ with $\tau_0 \varepsilon^2$ according to assumption (2.11).

Finally the proof of the second item follows the same lines replacing $D_{\tau_0}^n$ by D_{∞} in the discrete functional \mathcal{E}^n .

4. NUMERICAL SIMULATIONS

We performed several numerical simulations which confirm the accuracy of the scheme (3.1). We do not detail this process here and rather focus on the physical interpretation and the quantitative results obtained in our experiments. We refer to [3] for a precise discussion on that matter.

In this section, we want to illustrate the quantitative estimates of the solution obtained using the Hermite Spectral method in velocity and finite volume scheme in space for the one-dimensional Vlasov-Fokker-Planck equation. We choose $\tau(\varepsilon) = \tau_0 \varepsilon^2$ with $\tau_0 = 5$ and consider the Vlasov-Fokker-Planck equation (1.1) with $E = -\partial_x \Phi$ and

$$\Phi(x) = 0.1 \cos\left(\frac{2\pi x}{L}\right) + 0.9 \cos\left(\frac{4\pi x}{L}\right),$$

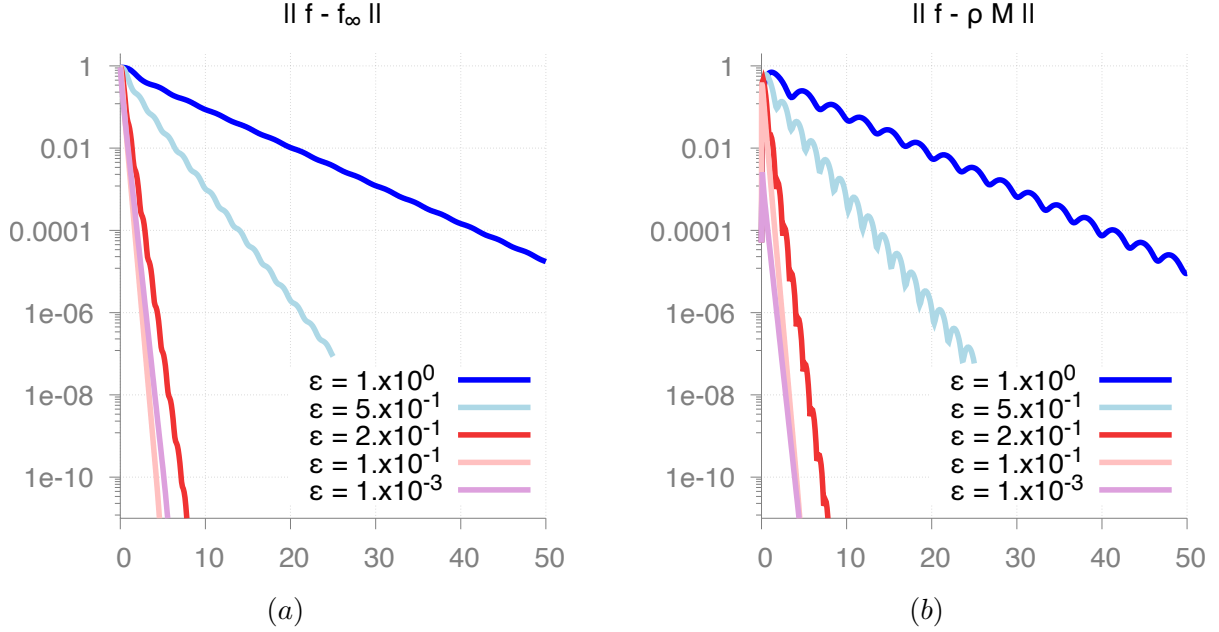


FIGURE 1. **Test 1 : centred Maxwellian.** time evolution in log scale of (a) $\|f - f_\infty\|_{L^2(f_\infty^{-1})}$, (b) $\|f - \rho \mathcal{M}\|_{L^2(f_\infty^{-1})}$.

The stationary state is given by the Maxwell-Boltzmann distribution

$$f_\infty(x, v) = \frac{c_0}{\sqrt{2\pi}} \exp\left(-\left(\Phi + \frac{|v|^2}{2}\right)\right),$$

where c_0 is given by mass conservation

$$\int_{\mathbb{T} \times \mathbb{R}} f_\infty dv dx = \int_{\mathbb{T} \times \mathbb{R}} f_0 dv dx,$$

where f_0 is the initial datum.

In our simulation, we take a time step $\Delta t = 10^{-3}$, a number of modes $N_H = 200$ and $N_x = 64$. It is worth to mention that all the numerical simulations presented in this section are not affected by the numerical parameters, which allows us to focus our discussion on the quantitative results on the diffusive limit $\varepsilon \rightarrow 0$ and large time behavior.

4.1. Test 1 : centred Maxwellian. For the first test, we choose the following initial condition

$$f_0(x, v) = \frac{1}{\sqrt{2\pi}} \left(1 + \delta \cos\left(\frac{2\pi x}{L}\right)\right) \exp\left(-\frac{|v|^2}{2}\right),$$

with $\delta = 0.5$ and $L = 10$.

On the one hand, we present in Figure 1 the time evolution of $\|f - f_\infty\|_{L^2(f_\infty^{-1})}$ and the relative entropy on f ,

$$\|f - \rho \mathcal{M}\|_{L^2(f_\infty^{-1})} = \|D_\perp(t)\|_{L^2}.$$

The most striking feature in this test consists in the oscillatory behavior of the relative entropy which unfolds in the relaxation of f towards its equilibrium. These oscillations may be observed in Figure 1-(b) and occur for various values of ε ranging from 1 represented by blue curves to $2 \cdot 10^{-1}$ represented by red curves.

We also present in Figure 2 the relaxation to equilibrium of macroscopic quantities

$$\|D_0 - D_{\infty,0}\|_{L^2} = \|\rho - \rho_\infty\|_{L^2(f_\infty^{-1})}$$

and the norm of the first moment D_1 . Time oscillations, observed on the distribution function, seem to affect macroscopic quantities associated to the solution as moments D_0 and D_1 .

On the other hand, we provide In Figure 3, a detailed description in the case $\varepsilon = 1$, where we see that the oscillations of the spatial density and the ones of the higher modes in velocity are asynchronous, this may be interpreted as a transfer of information between these two quantities. This phenomenon has

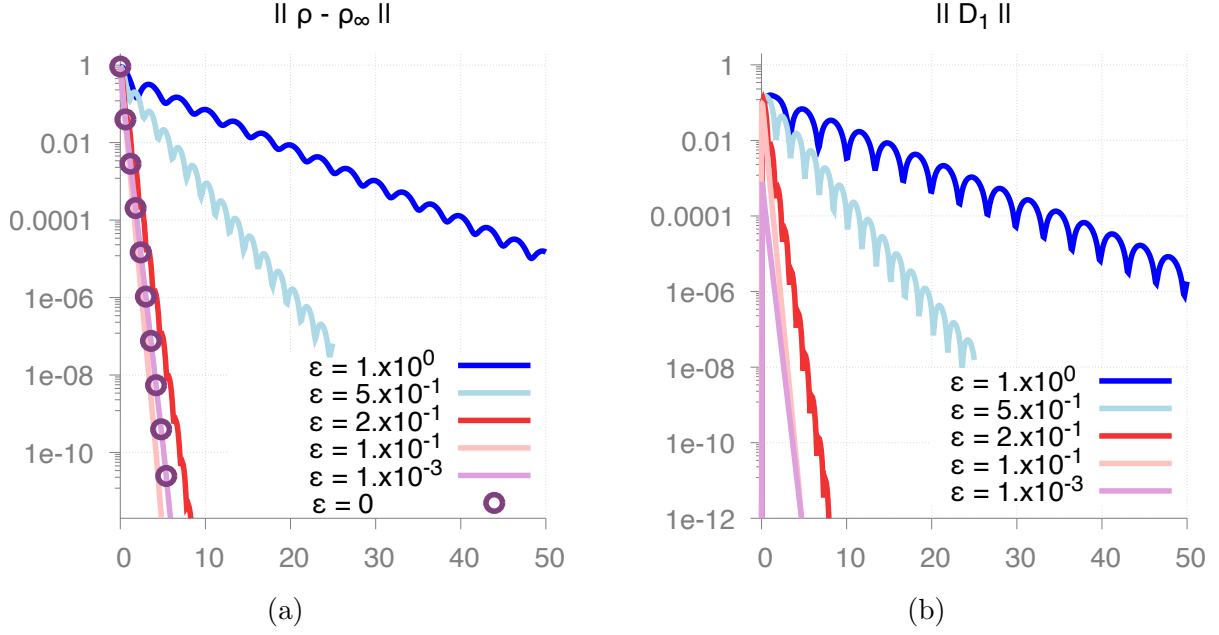


FIGURE 2. **Test 1 : centred Maxwellian.** time evolution in log scale of (a) $\|\rho - \rho_\infty\|_{L^2(\rho_\infty^{-1})}$ and (b) $\|D_1\|_{L^2}$.

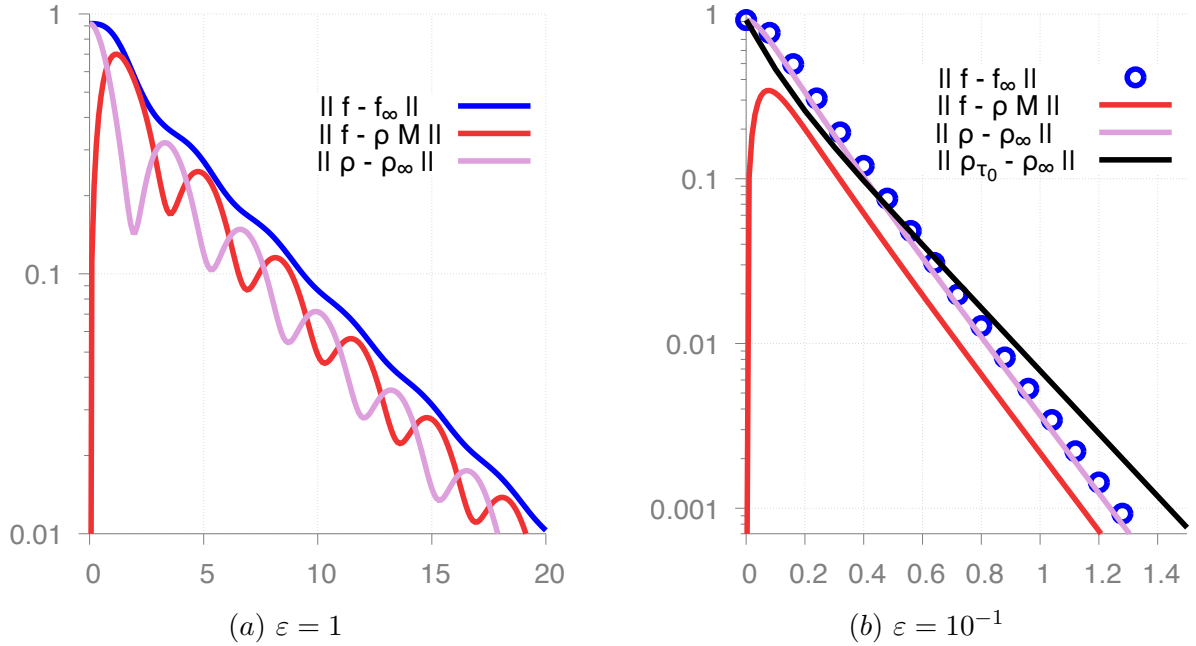


FIGURE 3. **Test 1 : centred Maxwellian.** time evolution in log scale of $\|f - f_\infty\|_{L^2(f_\infty^{-1})}$ (blue), $\|f - \rho_M\|_{L^2(f_\infty^{-1})}$ (red), $\|\rho - \rho_\infty\|_{L^2(\rho_\infty^{-1})}$ (pink) and $\|\rho_{\tau_0} - \rho_\infty\|_{L^2(\rho_\infty^{-1})}$ (black) for (a) $\varepsilon = 1$ and (b) $\varepsilon = 10^{-1}$.

already been investigated for non-linear kinetic models (see [15]) but we show through these experiments that even the simple model at play here captures this phenomena.

These oscillations stay visible for surprisingly small values of ε , up to 10^{-1} . It showcases the robustness of our scheme, which is still able to capture them at low computational cost. To be noted that our numerical experiments indicate that a non zero external force field seems to be mandatory to observe this oscillatory behavior. We also emphasize that these oscillations seem to be quite sensitive to the choice of the initial data and the external field (see the second numerical test with a different initial data, where such oscillations disappear for large time).

This leads us to the second feature of this test, which is the asymptotic preserving property of the scheme for various values of ε . The method is accurate on large time intervals in the situation where $\varepsilon = 1$ (see Figure 3-(a)), which corresponds to the long time behavior of the model but it is also accurate when $\varepsilon \ll 1$.

Indeed, as it is shown in Figure 2-(a), the purple error curve of the density ρ corresponds exactly to the circled error curve of the macroscopic model ρ_{τ_0} when $\varepsilon = 10^{-3}$ and even smaller (not shown since the curves coincide).

Finally we focus on the intermediate value $\varepsilon = 10^{-1}$, for which we observe in Figures 1-(a), 2-(a) and 3-(b), a somehow surprising phenomenon: the kinetic model relaxes faster towards equilibrium than the macroscopic one. This appears to be a consequence of our choice of initial data which is already at local equilibrium at time $t = 0$. This aspect of the experiment justifies our efforts to cover a wide range of values for the scaling parameter ε : it enables to capture intermediate regimes which may display peculiar phenomena. As we will see in the next section, the reverse situation is possible as well, when the initial condition is far from equilibrium.

We conclude this section by drawing the readers attention towards Figure 4, which features the graph of the solution f at different times, in the case $\varepsilon = 1$ and on which we witness its intricate relaxation towards equilibrium.

4.2. Test 2 : shifted Maxwellian. We now choose the same parameter as before excepted that the initial condition is a shifted Maxwellian

$$f_0(x, v) = \frac{1}{\sqrt{2\pi}} \left(1 + \delta \cos \left(\frac{2\pi x}{L} \right) \right) \exp \left(-\frac{|v - u_0|^2}{2} \right),$$

with $u_0 = 1$, which is far from equilibrium.

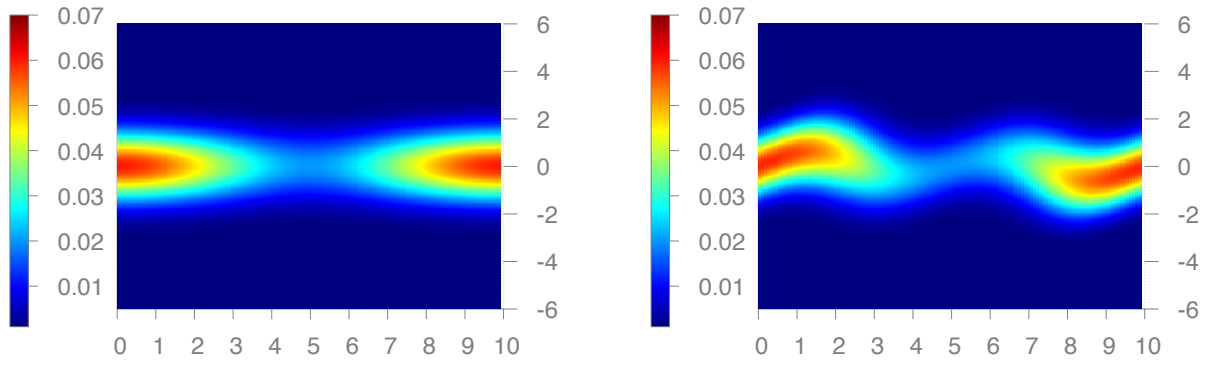
First, we focus on the case $\varepsilon = 1$ displayed in Figure 5, where we observe that unlike in the previous test, the oscillatory relaxation stops after a short time and is replaced by a slower but straight relaxation towards equilibrium. Another interesting comment on Figure 5 is that all the curves associated to value of ε below $5 \cdot 10^{-2}$ (red, beige, pink and purple) are parallel. These two features might be explained by a fine spectral analysis of the model at play.

We now zoom in to focus on smaller time intervals and propose a detailed description of these dynamics in Figure 6, where we distinguish three phases constituting a great illustration for the result presented in item (i) of Theorem 3.2:

- (1) the first phase is the initial time layer, it occurs on negligible time intervals compared to the time scale chosen in Figure 6 but it is still visible if we focus on the red curves, representing the norm of D_{\perp} , in plots (a) to (d). As predicted by the first result in (i) of Theorem 3.2, higher Hermite modes gathered in the quantity D_{\perp} undergo a steep exponential descent with theoretical rate of order $(\varepsilon^2 \tau_0)^{-1}$, until they reach a critical level of order ε ;
- (2) the second phase corresponds to the diffusive regime where f is close to $\rho_{\tau_0} \mathcal{M}$. Indeed we see that for times ranging from ~ 0 up to $t = 1$ in the case $\varepsilon = 10^{-2}$ and increasing up to $t = 3$ in the case $\varepsilon = 10^{-5}$, the red curve, which represents the norm of D_{\perp} , is parallel to the pink line corresponding to the norm of $\rho - \rho_{\tau_0}$ which itself coincides with the black curve representing the norm of $\rho_{\tau_0} - \rho_{\infty}$. It indicates that, for a finite amount of time which increases as ε goes to zero, the kinetic model behaves like the macroscopic one;
- (3) the last phase is the long time behavior, it starts as the error between ρ_{τ_0} and ρ is of the same order as the error between ρ and ρ_{∞} . In Figure 6 (a)-(d), it corresponds to the intersection between circled blue and black lines. As predicted by the second result in (i) of Theorem 3.2, this circled curve, representing the error $\|\rho - \rho_{\tau_0}\|$, starts with an ordinate of order ε at time $t = 0$, then it decays with a rate proportional to τ_0 but smaller than the relaxation rate of the macroscopic model. This constitutes a striking illustration of "hypocoercivity" phenomenon induced by the transport term proper to kinetic equations. During this final phase, the solution f to (1.2) slowly relaxes towards equilibrium. A surprising and unexpected fact is that the transition from diffusive regime to long time behavior occurs synchronisingly for the spatial density and higher modes in velocity. Indeed, as it can be observed in plots (a) to (c) of Figure 6, the inflexions points of the red and the pink curves are almost aligned.

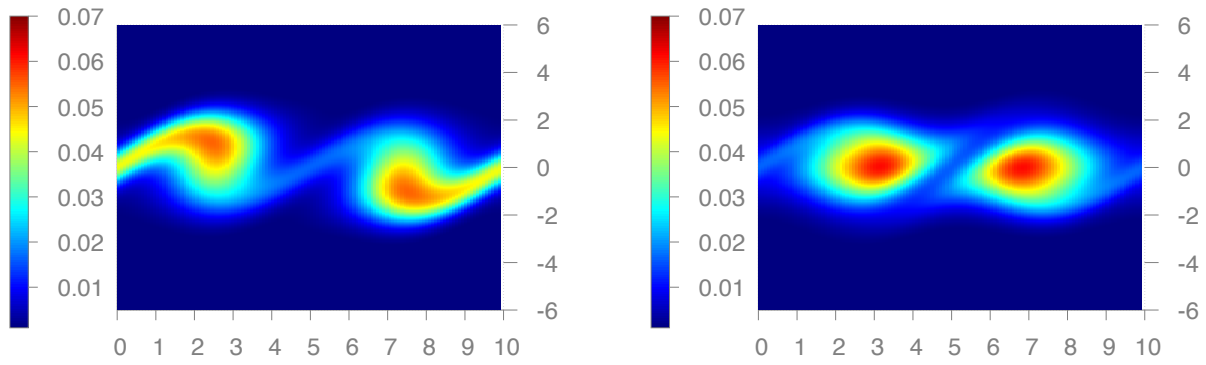
5. CONCLUSION AND PERSPECTIVES

In the present article, we design a numerical method capable to capture a rich variety of regimes for a Vlasov-Fokker-Planck equation with external force field. We prove quantitative estimates for all the regimes of interest, and do this uniformly with respect to all parameter at play. We illustrate the robustness of our scheme by proposing several numerical tests in which we capture a wide variety of situations (exponential



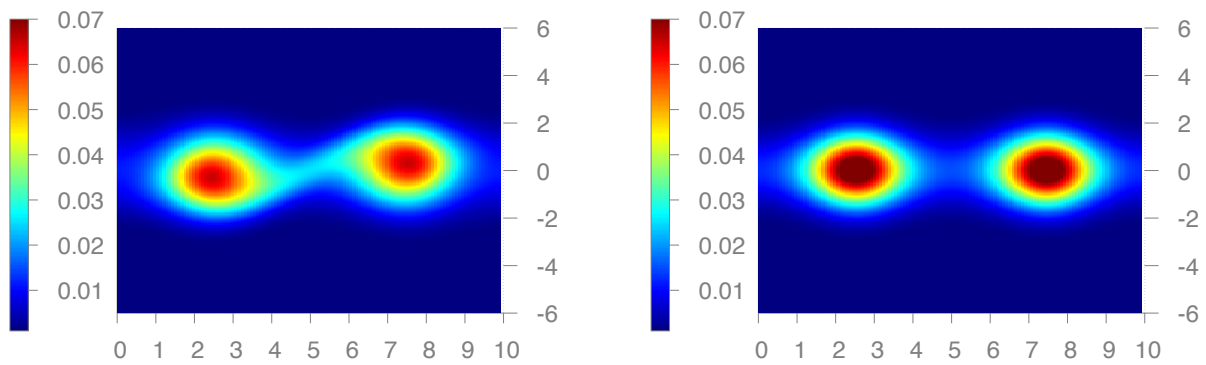
(a) $t = 0$

(b) $t = 0.5$



(c) $t = 1.5$

(d) $t = 3$



(e) $t = 5$

(f) $t = 20$

FIGURE 4. **Test 1 : centred Maxwellian.** snapshots of the distribution function for $\varepsilon = 1$ at time $t = 0, 0.5, 1.5, 3, 5$ and 20 .

decay with oscillations, transition phase between diffusive regime and long time behavior, initial time layer, etc ...). Furthermore, we built the method such that it should be easily adaptable in any dimension, at least for cartesian mesh.

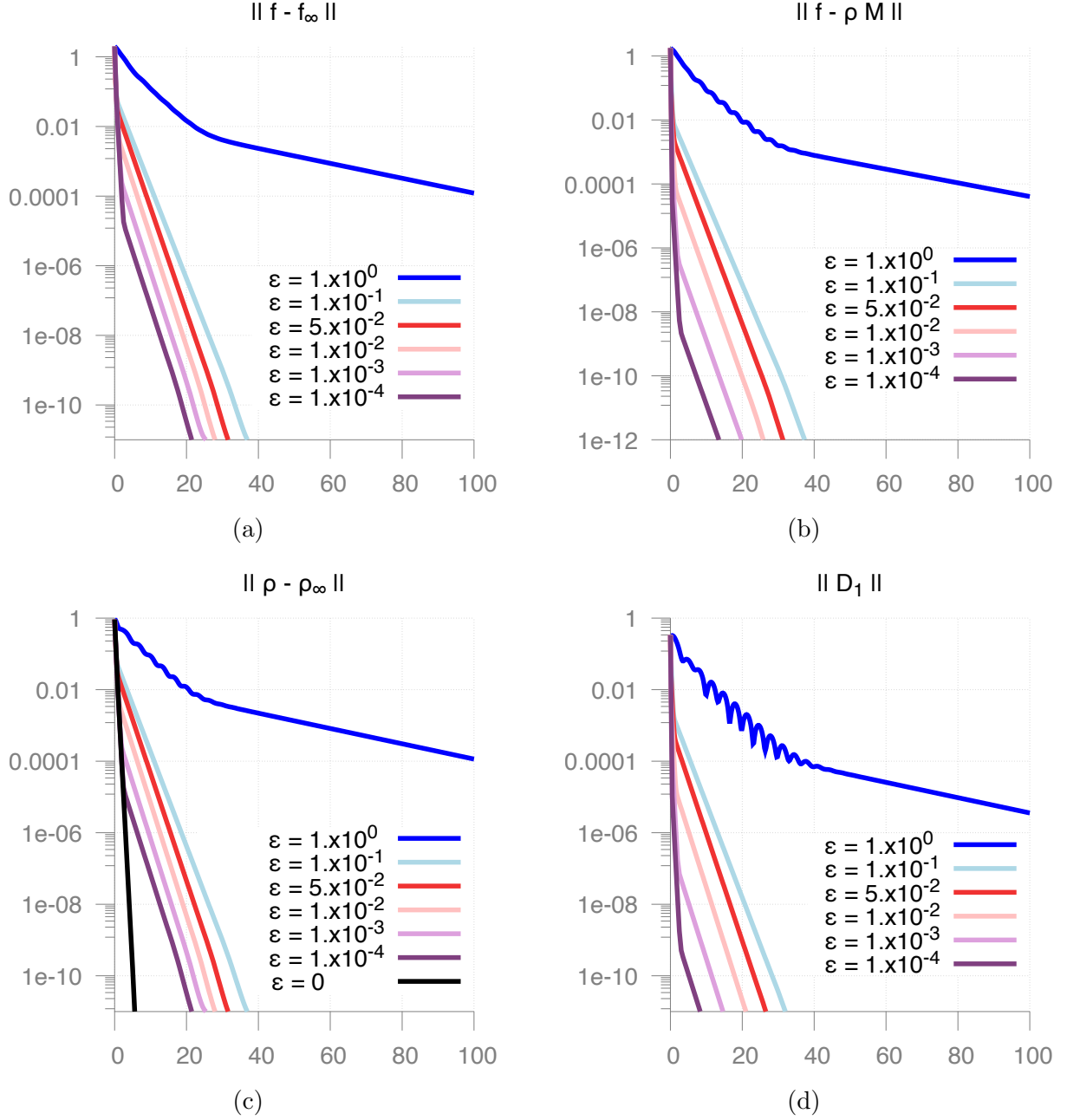


FIGURE 5. **Test 2 : shifted Maxwellian.** time evolution in log scale of (a) $\|f - f_\infty\|_{L^2(f_\infty^{-1})}$, (b) $\|f - \rho \mathcal{M}\|_{L^2(f_\infty^{-1})}$, (c) $\|\rho - \rho_\infty\|_{L^2(\rho_\infty^{-1})}$ and (d) $\|D_1\|_{L^2}$.

Two questions arise naturally from this work. The first one is to build on the groundworks layed in this article in order to design a scheme which takes into account non-linear coupling with Poisson for the electric force field. This challenging perspective would be a great improvement since even for the continuous model, there exists to our knowledge very few results which treat the longtime behavior and the diffusive regime with the accuracy proposed in this article. Up to our knowledge, all the works on this subject have restrictions on the dimension of the phase-space and therefore, it would naturally be interesting to propose a method which applies in the physical case $d = 3$.

Another interesting question arose from our numerical tests, in which we witnessed oscillating behaviors in the solution's relaxation towards equilibrium as well as transition phase between diffusive regime and longtime behavior. It would be of great interest to carry out a fine spectral analysis of the model both at the continuous and the discrete level in order to provide a quantitative description of these phenomena: we may hope for precise and enlightening results due to the simplicity of our model.

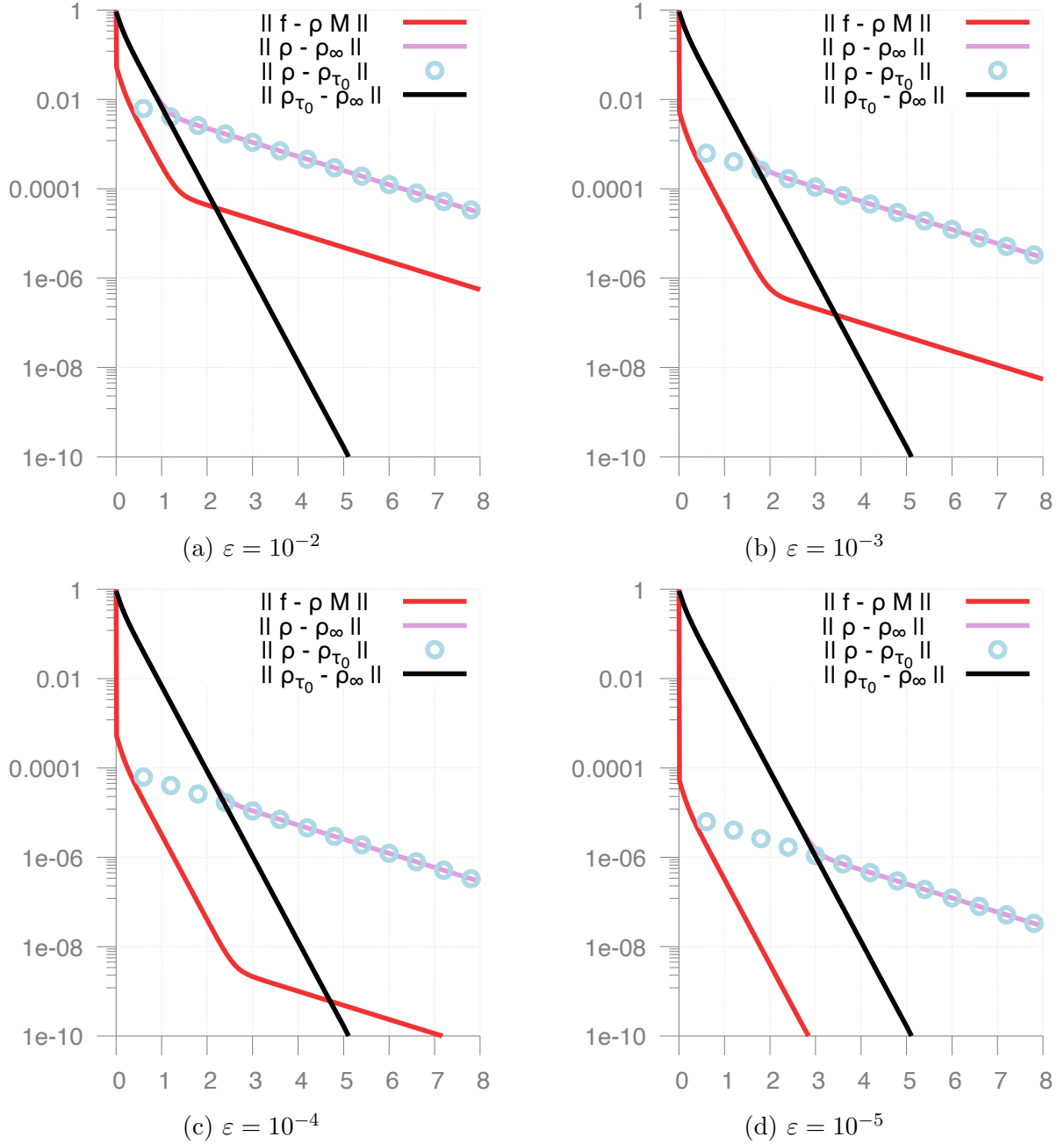


FIGURE 6. **Test 2 : shifted Maxwellian.** time evolution in log scale of $\|f - \rho \mathcal{M}\|_{L^2(f_\infty^{-1})}$ (red), $\|\rho - \rho_\infty\|_{L^2(\rho_\infty^{-1})}$ (pink), $\|\rho - \rho_{\tau_0}\|_{L^2(\rho_\infty^{-1})}$ (blue points) and $\|\rho_{\tau_0} - \rho_\infty\|_{L^2(\rho_\infty^{-1})}$ (black) for $\varepsilon = 10^{-2}, 10^{-3}, 10^{-4}$ and 10^{-5} .

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