



Modelling high-T_c superconducting dynamos

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Presentation Outline

- The high-*T*_c superconducting (HTS) dynamo
- Numerical modelling of the HTS dynamo
 - Benchmark problem
 - Efficient 3D models
 - Modelling dynamic coil charging behaviour
 - Future view



High-T_c Superconducting (HTS) Dynamo



Inject large DC supercurrents into a

closed superconducting circuit

Mataira et al. APL 114 (2019) 112601





HTS Dynamo

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- Inject large DC supercurrents into a closed superconducting circuit
- Energise HTS coils in NMR/MRI magnets, superconducting rotating machines without need for current leads









HTS Dynamo



• Energise HTS coils in NMR/MRI magnets, superconducting rotating machines without need for current leads







HTS Dynamo – Device Characterisation



HTS Dynamo – Current Injection Without Leads

Can be used to drive large DC current into a superconducting coil, without current leads



Jiang et al. APL 105 (2014) 112601





Benchmark Problem Definition

- Several numerical models have been developed recently to model the HTS dynamo
- Benchmark problem:
 - A specific simplified geometry with well-defined inputs (i.e. assumptions)
 - An expected set of outputs (i.e. the solution)
 - Allows any modelling technique to be validated & its performance critically compared





Benchmark Problem Definition

Based on experimental setup in Badcock et al. *IEEE TAS* 27 (2017) 5200905

HTS dynamo benchmark parameters

Permanent magnet (PM)	Width, a Height, b Active length (depth), L Remanent flux density, B_r	6 mm 12 mm 12.7 mm 1.25 T
HTS stator wire	Width, <i>e</i> Thickness, <i>f</i> Critical current, <i>I_c</i> [self-field, 77 K] <i>n</i> value	12 mm 1 μm 283 A 20
Rotor external radius, <i>R_{rotor}</i> Distance between PM face and HTS surface, <i>airgap</i> Frequency of rotation Number of cycles		35 mm 3.7 mm 4.25 Hz 10

General definitions

E-J power law: $\mathbf{E} = \frac{E_0}{J_c} \left| \frac{J}{J_c} \right|^{n-1} \mathbf{J}$

DC component:

$$V_{DC} = -\frac{L}{T} \int_{t}^{t+T} E_{ave}(t') dt'$$

Equivalent instantaneous voltage:

$$V_{eq}(t) = -LE_{ave}(t)$$

Cumulative time-averaged voltage:

$$V_{cumul}(t) = \frac{1}{t} \int_0^t V_{eq}(t) dt$$
$$I(t) = \iint_S J_z(x, y, t) dS = 0$$





Numerical Modelling Frameworks

- H-formulation methods
 - Coupled H-A
 - H-formulation + shell current
 - Segregated H-formulation
- Coupled T-A formulation
 - 1D (line) or 2D (finite thickness) object
 - 'Pure' T-A (vector potential only)
 - Mixed scalar-vector potential

• MEMEP

- Variational method
- Solves J by minimising a functional containing all variables of problem: A, J, φ

Integral equation (IE)

- Current distribution along 1D superconducting layer obtained from IE
- Volume integral equation (VIE)

• Solves
$$\mathbf{E} = -\frac{\partial \mathbf{A}^{int}}{\partial t} - \mathbf{v} \times \mathbf{B}^{PM} - \nabla \varphi$$



Comparison of Key Results – $V_{eq}(t)$

Open-circuit equivalent instantaneous voltage

 $V_{eq}(t) = -LE_{ave}(t)$

2nd transit of PM past HTS wire, ignoring any initial transient effects in 1st cycle

Qualitatively, four distinct peaks with left-to-right asymmetry, as observed in experiments

Excellent quantitative agreement (see cumulative voltage next)





Comparison of Key Results – $V_{cumul}(t)$

Cumulative time-averaged equivalent voltage

$$V_{cumul}(t) = \frac{1}{t} \int_0^t V_{eq}(t) dt$$

 $V_{\rm cumul}$ over 10 cycles

Converges to non-zero asymptotic value $\rightarrow V_{DC}$

Excellent quantitative agreement: -9.41 µV average with 0.34 µV standard deviation





Comparison of Key Results – J/J_{c0} , E



Comparison of Modelling Frameworks

Methods emphasising reduction of mesh elements / DOFs performed best

Key metrics assessed for each benchmark model								
Model	Mesh (SC)	Mesh (total)	DOFs	Rel./abs. tolerance	Approx. time/cycle (min/cycle)	Software implementation		
MEMEP	$120(120 \times 1)$	120	120	$1e-4^{1}$	<0.25 ^a	C++		
SEG-H	$120(120 \times 1)$	2653	4071	1e-4/0.1	1.1 ^b 2.6 ^b	COMSOL 5.4 COMSOL 5.5		
VIE	$120(120 \times 1)$	120	120	$1e-3^{2}/1e-6^{2}$	1.6 ^b	MATLAB		
H-A	$120(120 \times 1)$	4176	3061	1e - 4/0.1	2.1 ^b	COMSOL 5.5		
T-A (2D) SP	$240~(60 \times 4)$	3800	2863	1e - 5/1e - 4	3.9 ^b	COMSOL 5.5		
IE	$120(120 \times 1)$	5932	12 451	5e-3/0.1	5.1 ^b	COMSOL 5.5		
T-A (1D) SP	$120(120 \times 1)$	4876	2779	1e - 5/1e - 4	6.5 ^b	COMSOL 5.5		
H+SC	120(120 imes 1)	11 272	16 988	1e-5/1e-3	7.9 ^b > 120	COMSOL 5.4 COMSOL 5.5		
T-A (1D) VP	$120(120 \times 1)$	6064	12715	1e - 4/0.1	21.6 ^b	COMSOL 5.5		
T-A (2D) VP	$240(60 \times 4)$	5286	13 696	1e-4/0.1	64.6 ^b	COMSOL 5.5		

PC specifications:^aIntel[®] Core[™] i7-8700 CPU @ 3.20 GHz, 31.1 GB RAM (10% memory used for MEMEP model), Ubuntu 16.04 LTS, 64-bit^bIntel[®] Core[™] i9-7900X CPU @ 3.30 GHz, 63.7 GB RAM, Microsoft Windows 10 Pro, 64-bitOther notes:¹Tolerance for the mutual interaction matrix²Default settings for MATLAB/*ode23b* solver

H-A, T-A = rotating machine-like frameworks; stability issues with 'pure' T-A → use of mixed scalar-vector potential performed significantly better



Prigozhin Method

- Benchmark problem also implemented by Prigozhin & Sokolovsky in 2021
 - Uses expansions in Chebyshev polynomials for approximation in space, method of lines for integration in time
 - Offers a potentially even faster method to model the HTS dynamo
 - See Supercond. Sci. Technol. 34 (2021) 065006 for more details
 - Also talk today PM (OS-M1-PM)





Efficient 3D Models

3D models can consider the return of the current within the wire & more complex geometries, e.g., magnet shape





Efficient 3D Models

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Mixed FEM, fast Fourier transform methods

Prigozhin & Sokolovsky IEEE TAS 31 (2021) 5201107





Modelling Dynamic Coil Charging Behaviour



HTS 2022 – 14-16 June 2022 – Nancy, France

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Modelling Dynamic Coil Charging Behaviour



Total flux pump output voltage V(t)& its constituent components: $V_{eq}(t)$ from $E_{av} + A_{J,av} + A_{M,av}$ **Dynamic charging current curve** Freq. = 25 Hz Analytical equation vs MEMEP, SEG-H



Modelling Dynamic Coil Charging Behaviour



Total flux pump output voltage V(t)& its constituent components: $V_{eq}(t)$ from $E_{av} + A_{J,av} + A_{M,av}$

1st five cycles: 135.4 mW, 135.7 mW 5001st cycle: 135.7 mW, 135.9 mW



Future View

- More complicated models
 → kA-class dynamo design
- Coupling of FEM models
 - e.g. dynamo <-> coil

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- See Pengbo Zhou talk tomorrow AM (Applications)
- Use of machine learning to accelerate dynamo design optimisation
 - Proposed in Wen et al. *SUST* 34 (2021) 125019 to obtain V_{oc} for various key parameters (freq, airgap, B_r of PM etc.)



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