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Strongly contracting axes for fully irreducible automorphisms of Generalized Baumslag-Solitar groups

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Abstract

Similarly to the action of $Out(F_N)$ on Outer Space, the outer automorphism group of a Generalized Baumslag Solitar group acts on a *deformation space* endowed with the Lipschitz metric and the action of any fully irreducible automorphism with a train track representative is hyperbolic. Inspired by previous work by Algom-Kfir, we prove that the axis of such an automorphism is strongly contracting.

Introduction

Let G be a generalized Baumslag-Solitar (GBS) group, i.e. a group which is isomorphic to the fundamental group of a graph of groups where all vertex and edge groups are infinite cyclic. By Bass-Serre theory, G admits a minimal action by isometries on a simplicial tree T such that all vertex or edge stabilizers in T are infinite cyclic.

In general G admits infinitely many such actions. When G is not isomorphic to \mathbb{Z}, \mathbb{Z}^2 or the fundamental group of a Klein bottle $\langle a, b | a^2 = b^2 \rangle = \langle a, t | tat^{-1} = a^{-1} \rangle$, then the *cyclic deformation space* \mathcal{D} associated to G is defined as the projectivized set of minimal actions of G by isometries on metric simplicial trees with edge and vertex stabilizers isomorphic to \mathbb{Z} , where actions T, T' are identified if there exists a G-equivariant isometry $T \to T'$. The space \mathcal{D} is analogous to Culler and Vogtmann's Outer Space CV_N for the free group F_N . The study of Outer Space is crucial for understanding the outer automorphism group $Out(F_N)$. Just as $Out(F_N)$ acts on CV_N , the outer automorphism group Out(G) acts on \mathcal{D} by pre-composition of the action: if G acts on T, then define $T \cdot \phi$ as the action whose underlying space is T and where for $t \in T$, $g \cdot_{T \cdot \phi} t = \phi(g) \cdot_T t$.

There is an important analogy between the study of the outer automorphism group of free groups F_N and mapping class groups. In this analogy, Outer Space is the counterpart for Teichmüller space. Fully irreducible automorphisms of $\operatorname{Out}(F_N)$ are a special class of automorphisms which do not preserve the conjugacy class of any free factor. In some sense they act on Outer Space by translations along an axis whose points are actions which admit a *train track representative*. Their equivalent in the mapping class groups context is pseudo-Anosov automorphisms. Such automorphisms can also be defined for GBS groups: we say that an automorphism $\phi \in \operatorname{Out}(G)$ is *fully irreducible* if no conjugacy class of proper *cyclic factor* is ϕ -periodic. A *cyclic factor* is the analogue of a free factor for the free group: it is a non-cyclic subgroup G' < Gsuch that there exists a graph of groups Γ representing G, and a subgraph $\Gamma' \subset \Gamma$ such that the fundamental group $\pi_1(\Gamma')$ identifies to the subgroup G'. We say that G' is a proper cyclic factor if $G' \neq G$. One main property for a fully irreducible automorphism $\phi \in \text{Out}(F_N)$ is that its action on CV_N is hyperbolic and admits an axis \mathcal{L}_{ϕ} . In order for this to make sense, we endow CV_N with the non-symmetric *Lipschitz metric* d_{Lip} : it is defined by

$$d_{\rm Lip}(T,T') := {\rm Lip}(T,T') \frac{{\rm vol}(T)}{{\rm vol}(T')}$$

for $T, T' \in \mathrm{CV}_N$, where $\mathrm{Lip}(T, T') := \sup_{f:T \to T'} \mathrm{Lipschitz} \ \mathrm{Lip}(f)$.

One can define a closest point projection $\pi_f : \mathcal{D} \to \mathcal{L}_f$ such that for $T \in \mathcal{D}, d_{\text{Lip}}(T, \pi_f(T))$ is minimal. Define the *outward ball* $B_{\to}(Y, r) := \{T \in \mathcal{D}/d_{\text{Lip}}(Y, T) < r\}.$

In [Alg11] Algom-Kfir proves that the projections on axes have the strong contraction property: there exists B > 0 depending only on N and ϕ such that the diameter of the projection of any outward ball in \mathcal{D} disjoint from \mathcal{L}_{ϕ} is bounded by B.

Likewise we can define these objects for the deformation space \mathcal{D} of a GBS group. A few differences arise, for example because trees in \mathcal{D} have non-trivial edge stabilizers: one consequence is that in general there exist $T, T' \in \mathcal{D}$ such that $d_{\text{Lip}}(T, T') = 0$ and $d_{\text{Lip}}(T', T)$ is arbitrarily large.

In this paper we prove the analogue of this property for fully irreducible automorphisms of a GBS group:

Theorem A. Let G be a GBS group with $b_1(G) \geq 3$. Let ϕ be an atoroidal fully irreducible automorphism such that ϕ, ϕ^{-1} both admit train track representatives. Let \mathcal{L}_{ϕ} be an axis for ϕ in \mathcal{D} and let π_{ϕ} be a closest point projection to \mathcal{L}_{ϕ} . Then there exists D > 0 such that for any $Y \in \mathcal{D}$ and r > 0 such that $B_{\rightarrow}(Y, r) \cap \mathcal{L}_{\phi} = \emptyset$

$$\operatorname{diam}(\pi_{\phi}(B_{\to}(Y,r))) \le D$$

The proof for this result is similar to [Alg11].

We do not know whether train track representatives always exist for fully irreducible automorphism. Several cases are known:

- The procedure in [BH92] may be adapted to construct a train track map by hand on a specific example. See Example 1.11.
- If G has no non-trivial integer modulus then [For06] proves that \mathcal{D} has finite dimension. Then [Mei15] implies that all fully irreducible automorphisms admit train track representatives.
- If G := BS(p, pn) then Bouette proved in [Bou16] that all automorphisms of G are reducible and preserve the conjugacy class of a common cyclic factor H. She then introduces a new deformation space \mathcal{D}_H consisting in all G-trees with cyclic edge stabilizers, and vertex stabilizers either cyclic or conjugate to H. In this deformation space, there exist fully irreducible automorphisms and they admit train track representatives.

The second case is not relevant here since we need the trees in the deformation space to be locally finite.

For technical reasons, we ask that the automorphism ϕ in the theorem be pseudo-atoroidal, which means that for all $g \in G$, $(\|\phi^n(g)\|_T)_{n \in \mathbb{N}}$ is unbounded.

We also need the first Betti number $b_1(\Gamma)$ for any graph of cyclic groups Γ with $\pi_1(\Gamma) \simeq G$ to be at least 3. Actually $b_1(\Gamma)$ does not depend on the choice of Γ when G is not isomorphic to the fundamental group of a Klein bottle, which we exclude. An important result in [Alg11] is the fact that axes of automorphisms have bounded projection on each other. This fact is of great interest since it enables the definition of a projection complex on which the quasi-tree construction of [BBF15] could be applied. However we do not know yet if this still holds in the GBS context, due to the fact that the Lipschitz metric is even less symmetric. For example it is not true that the Lipschitz metric is quasi-symmetric on the θ -thick part of \mathcal{D} . Furthermore, there is no bound on the number of candidates in trees of \mathcal{D} .

In Section 1 we give some background about GBS groups and their automorphisms. We develop the topic of laminations in Section 2. In Section 3 we prove the analogue of results from [Alg11] which state that the axis of a simple element cannot follow both the stable and unstable lamination for a long distance; the method of the proof differs somehow from the original. Section 4 develops the behaviour of lines in T such as axes of elements of g when iterating a train track $f: T \to T$, and Section 5 relies on it to define a projection of \mathcal{D} on the axis of a fully irreducible element with a train track representative. The contents in this section are really close to [Alg11] and are there for completeness.

We prove negative curvature properties of the projection in Section 6, that is, inequalities about distances in \mathcal{D} . Although the former does not differ from the free group case, the latter needs some arguments which are specific to GBS groups. Finally we prove the strong contraction for balls of outward radius.

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1 Generalities

1.1 Graphs and trees

A graph Γ is defined by $(V(\Gamma), E(\Gamma), \overline{\cdot}, o, t)$ where

- $V(\Gamma)$ is a set of vertices
- $E(\Gamma)$ is a set of *edges*
- the map $\overline{\cdot}$ is an involution $E(\Gamma) \to E(\Gamma)$ without fixed point; for $e \in E(\Gamma)$ the edge \overline{e} is called the *opposite edge*
- the maps $o, t : E(\Gamma) \to V(\Gamma)$ are the *initial vertex* and *terminal vertex* maps, with the property that every $e \in E(\Gamma)$ satisfies $o(e) = t(\bar{e})$.

It is finite if $V(\Gamma)$, $E(\Gamma)$ are finite. See [Ser77] for more details on graphs.

An edge path in Γ is a sequence e_1, \ldots, e_k with $e_i \in E(\Gamma)$ for $i \in \{1, \ldots, k\}$ and $t(e_i) = o(e_{i+1})$ for $i \leq k-1$. It is non-backtracking if for all $i \in \{1, \ldots, k-1\}$, $\bar{e}_i \neq e_{i+1}$. It is a loop if $o(e_1) = t(e_k)$.

A tree is a graph without non-backtracking loops.

Let $E^+(\Gamma)$ be an orientation of the edges, i.e. a subset of $E(\Gamma)$ such that $E^+(\Gamma) \sqcup \overline{E^+(\Gamma)}$ is a partition of $E(\Gamma)$.

A metric on a graph Γ is a map $\operatorname{len}_{\Gamma} : E(\Gamma) \to \mathbb{R}_+$ such that for all $e \in E(\Gamma)$, $\operatorname{len}_{\Gamma}(\bar{e}) = \operatorname{len}_{\Gamma}(e)$.

The geometric realization of a graph Γ is the union of points $(x_v)_{v \in V(\Gamma)}$ and segments $(\sigma_e)_{e \in E^+(\Gamma)}$ where σ_e is isometric to $[0, \operatorname{len}_{\Gamma}(e)]$ for every $e \in E(\Gamma)$, where for every $e \in E^+(\Gamma)$

we identify the first point of σ_e with $x_{o(e)}$ and its last point with $x_{t(e)}$. It is endowed with the associated path metric. It does not depend on the choice of $E^+(\Gamma)$.

In the rest of the paper we will identify trees and other graphs with their geometric realizations. A path in a tree T is the image of a Lipschitz map from an interval to T. It is *non-backtracking* if the map is an immersion, and equivalently if it is a the image of a geodesic. In the context of geometric realizations an *edge path* is a path which is the image of an edge path in the graph. For two points $x, y \in T$, the segment [x, y] is the unique geodesic from x to y.

A graph of groups is a graph Γ together with collections of vertex groups $(G_v)_{v \in V(\Gamma)}$ and edge groups $(G_e)_{e \in E(\Gamma)}$ and monomorphisms $\iota_e : G_e \to G_{t(e)}$. Let τ be a maximal subtree in the graph Γ . The fundamental group $\pi_1(\Gamma, \tau)$ of the graph of groups Γ is defined as follows:

$$\pi_1(\Gamma,\tau) = \left\langle \bigcup_{v \in V(\Gamma)} G_v \cup (t_e)_{e \in E(\Gamma)} | \bigcup_{v \in V(\Gamma)} R_v, \bigcup_{e \in E(\Gamma)} R_e, R_\tau \right\rangle$$

where

- for $v \in V(\Gamma)$, R_v is the set of relations of G_v
- for $e \in E(\Gamma)$, $R_e = \{t_e \phi_e(h) t_{\bar{e}} \phi_{\bar{e}}(h)^{-1} / h \in G_e\}$
- $R_{\tau} := \{t_e, e \in \tau\}$

Note that for h = 1 we obtain the relation $t_{\bar{e}} = t_e^{-1}$. Up to isomorphism the fundamental group does not depend on the choice of τ . If the vertex groups and edge groups are finitely generated then $\pi_1(\Gamma)$ is finitely presented.

Let G be a group. A marked graph of groups for G is a graph of groups Γ together with a marking (i.e. an identification) $\Psi : G \to \pi_1(\Gamma)$. The automorphism group of G acts as follows on the set of marked graphs of groups: if $\phi \in \operatorname{Aut}(G)$ and (Γ, Ψ) is a marked graph of groups then $(\Gamma, \Psi) \cdot \phi := (\Gamma, \Psi \circ \phi)$.

A G-tree T is a metric simplicial tree with an action of G by isometries. The tree T is minimal if there is no proper G-invariant subtree.

The universal cover of a graph of groups Γ is a minimal $\pi_1(\Gamma)$ -tree T such that T/G is isomorphic to Γ as a graph and for every $v \in V(\Gamma)$ and every lift $\bar{v} \in T$, the stabilizer of \bar{v} is isomorphic to G_v . By Bass-Serre theory in [Ser77], universal covers exist and are unique up to $\pi_1(\Gamma)$ -equivariant isomorphism.

Moreover Bass-Serre theory gives a correspondance between marked graphs of groups for G and G-trees.

If Γ is a metric graph then the metric naturally lifts to its universal cover.

In a G-tree T we denote the pointwise stabilizer of a vertex v (resp. an edge e) by G_v (resp. G_e).

A generalized Baumslag-Solitar (GBS) group is a group which is isomorphic to the fundamental group of a finite graph of groups where all vertex and edge groups are infinite cyclic. If a generator is chosen for every vertex and edge group then the monomorphisms ϕ_e are defined by the multiplication by an integer $\lambda(\bar{e}) \in \mathbb{Z} \setminus \{0\}$.

Let G be a GBS group. In the general case there exist infinitely many marked graphs of cyclic groups for G. Making Aut(G) act on a marked graph of groups often yields infinitely many other markings, besides in general cases there are infinitely many possible underlying graphs of groups.

Let T be a G-tree. A subgroup H < G is *elliptic* in T if it fixes a point in T. Suppose all elliptic groups in T are also elliptic in S. Then there exists a G-equivariant map $T \to S$ (see by example [GL07]).

Let T, T' be *G*-trees. We say that they lie in the same *deformation space* if they have the same sets of elliptic subgroups. Equivalently they are in the same deformation space if there exist *G*-equivariant maps $T \to T'$ and $T' \to T$.

Now let us define the *cyclic deformation space* \mathcal{D} associated to a group G, as the set of minimal simplicial G-trees with cyclic vertex and edge stabilizers, where we identify T and T' if there is a G-equivariant isometry or homothety $T \to T'$.

Equivalently we could define \mathcal{D} with marked graphs of groups.

If G is not isomorphic to \mathbb{Z}^2 or the fundamental group of a Klein bottle $\langle a, b | a^2 = b^2 \rangle \simeq \langle a, t | tat^{-1} = a^{-1} \rangle$, then \mathcal{D} is a deformation space, i.e. all trees in \mathcal{D} have the same elliptic subgroups.

Let $T \in \mathcal{D}$ and let e be an edge in T. Define the equivalence relation \sim_e as the minimal G-invariant equivalence relation such that $x \sim_e y$ if $x, y \in e$. The *collapse* of the edge e is the quotient map $T \to T/\sim_e$. The edge e in T is *collapsible* if $T/\sim_e \in \mathcal{D}$. Equivalently an edge is collapsible if its image in the quotient is not a loop and one of its two labels is ± 1 .

A tree of \mathcal{D} is *reduced* if none of its edges is collapsible.

GBS trees in the same deformation space share some properties. Let Γ be a finite connected graph. Then the first Betti number $b_1(\Gamma)$ is defined by $b_1(\Gamma) = \#E(\Gamma) - \#V(\Gamma) + 1$. By [GL07, Section 4] the first Betti number is an invariant of the deformation space.

Let G be a GBS group with cyclic deformation space \mathcal{D} . We say that an elliptic subgroup H < G is *big* if there exists a tree $T \in \mathcal{D}$ such that H fixes no edge in T.

From [GL07] we deduce:

Lemma 1.1. Let $T \in \mathcal{D}$. The number of vertices $v \in T$ such that for all edge e with origin v, $G_e \neq G_v$ is bounded by the number of conjugacy classes of big subgroups of G. If T is reduced then these numbers are equal.

Remark 1.2. The notion of big subgroups is defined in [GL07], though it depends on a family \mathcal{A} of subgroups of G: a subgroup H < G is big if it is elliptic and is not conjugate into a subgroup of an element of \mathcal{A} . Here the corresponding choice for \mathcal{A} is the family of subgroups which fix an edge in a reduced tree of \mathcal{D} , or equivalently in every reduced tree of \mathcal{D} . Thus an elliptic subgroup is big if fixes a single point in some (equivalently any) tree in \mathcal{D} .

Solvable GBS groups are GBS groups isomorphic to \mathbb{Z} and BS(1, n) for $n \in \mathbb{N}$ (which include \mathbb{Z}^2 and the fundamental group of a Klein bottle).

1.2 Cyclic factors, irreducible automorphisms

From now on we assume G is a non-solvable GBS group. The automorphism group of G is $\operatorname{Aut}(G)$. The outer automorphism group is $\operatorname{Out}(G) := \operatorname{Aut}(G)/\operatorname{Inn}(G)$ where $\operatorname{Inn}(G)$ is the subgroup of inner automorphisms $\{c_g : x \mapsto gxg^{-1}, g \in G\}$.

Cyclic factors are the GBS analogue of free factors for free groups.

Definition 1.3. A cyclic factor of G is a subgroup H such that there exists a graph of cyclic groups Γ and an identification $G \simeq \pi_1(\Gamma)$, with a subgraph Γ_H such that H is conjugate to $\pi_1(\Gamma_H)$.

The family of cyclic factors of G is stable by conjugacy and by automorphisms.



Figure 1: Examples of cyclic factors

- *Examples* 1.4. 1. If $G := BS(2,4) = \langle a, t | ta^2t^{-1} = a^4 \rangle$, the first graph of groups of Figure 1 represents G. The red subgraph represents the subgroup $H := \langle a, t^{-1}a^2t \rangle$ which is a cyclic factor.
 - 2. The second and third graphs of Figure 1 represents $G := \langle u, r, s, t | tu^n t^{-1} = su^n s^{-1} = ru^n r^{-1} = u \rangle$. The subgroup $\langle u, r \rangle \simeq BS(1, n)$ is a cyclic factor, it can be seen in the graph on the left. The subgroup $\langle u, rur^{-1}, rsus^{-1}r^{-1}, rst \rangle \simeq BS(1, n^3)$ is a cyclic factor which can be seen in the graph on the right.

Definition 1.5. An automorphism $\phi \in \operatorname{Aut}(G)$ is *fully irreducible* if no power of ϕ preserves the conjugacy class of a cyclic factor. Since inner automorphisms preserve conjugacy classes, the full irreducibility can be defined for outer automorphisms.

A representative for ϕ is a map $f: T \to T$ with $T \in \mathcal{D}$ which is ϕ -equivariant, i.e. $\forall t \in T$, $\forall g \in G, f(gt) = \phi(g) \cdot f(t)$.

A representative for an outer automorphism class $\psi \in \text{Out}(G)$ is a representative for some automorphism in the class ψ .

Definition 1.6. Let $\phi \in \text{Out}(G)$. A *pseudo-periodic* conjugacy class for ϕ is the conjugacy class of an element $g \in G$ such that $\|\phi^n(g)\|_{n \in \mathbb{N}}$ is bounded.

An automorphism $\phi \in \text{Out}(G)$ is *pseudo-atoroidal* if ϕ has no pseudo-periodic conjugacy class.

Train track representatives for automorphisms of $Out(F_N)$ were introduced in [BH92]. They are a main tool for studying these automorphisms. One can define likewise train tracks for other families of groups acting on trees.

Definition 1.7. Let T be a G-tree. A gate structure on T is a G-invariant family of equivalence relations $(\sim_v)_{v \in V(T)}$ on the sets E_v of edges with origin v. Equivalence classes for these relations are called gates.

Let $\tau : T \to T'$ be a *G*-equivariant map sending edges to non-degenerate non-backtracking paths. The gate structure *induced by* τ is the minimal gate structure such that for $v \in V(T)$, $e, e' \in E_v$, if $\tau(e) \cap \tau(e')$ has non-zero length then $e \sim_v e'$.

Definition 1.8. Let T be a G-tree with a gate structure. A turn in T is a pair of edges with same origin. The turn $\{e, e'\}$ is *illegal* if e and e' belong to the same gate. Otherwise the turn is *legal*.

Definition 1.9. Let $\phi \in \text{Out}(G)$. Let $f : T \to T$ be a representative for ϕ sending vertex to vertex.. Then f is *train track* if for every $e \in E(T)$:

- $\operatorname{len}(f(e)) > 0$
- at every vertex $v \in V(T)$ there are at least two gates for the gate structure induced by f.
- for every $k \in \mathbb{N}$, $f^k(e)$ crosses only legal turns for the gate structure induced by f.

The train track structure is the gate structure such that $e \sim e'$ if there exists $k \in \mathbb{N}$ such that $f^k(e) \cap f^k(e')$ is not a single point.

Suppose $f : T \to T$ is a train track representative for a fully irreducible automorphism $\phi \in \text{Out}(G)$. Up to precomposing f with a map $T \to T$ whose restriction to edges is a homeomorphism, we may assume that f stretches the edges uniformly. Let e_1, \ldots, e_n be the edges of T/G. Let A(f) be the transition matrix for f where $A(f)_{ij}$ is the number of occurrences of edges in the orbit e_i in $f(e_j)$, for $1 \leq i, j \leq n$. Irreducibility of ϕ implies that up to collapsing edges in T the matrix A(f) is primitive, i.e. there exists $k \in \mathbb{N}$ such that $A(f)^k > 0$ (see [Pap22, Lemma 1.9]).

The theorem of Perron-Frobenius below then applies to A(f):

Theorem 1.10 (Perron-Frobenius). Let A be a non-negative primitive matrix with size $n \times n$. There exists a real eigenvalue $\lambda > 0$ (the Perron-Frobenius eigenvalue) such that for every other eigenvalue $\mu \neq \lambda$ we have $|\mu| < \lambda$. The eigenvectors for λ are unique up to scalar multiplication and there exists an eigenvector v for λ such that v > 0.

A proof of the theorem can be found in [Sen81, Theorem 1.1].

Let λ be the Perron-Frobenius eigenvalue and (l_1, \ldots, l_n) be the left Perron-Frobenius eigenvector. Define a metric on T by $\operatorname{len}(e_n) := l_n$. Then for every $e \in E(T)$ we have $\operatorname{len}(f(e)) = \lambda \operatorname{len}(e)$, and the Lipschitz constant $\operatorname{Lip}(f)$ is λ .

From now on we assume train track maps are linear on edges and have the same Lipschitz constant on all edges.

Recall that it is not known whether all fully irreducible automorphisms admit train track maps. However some do exist: Example 1.11 is an example of fully irreducible automorphism with a train track representative.

Examples 1.11. Let $G := \langle r, s, t | ru^n r^{-1} = su^n s^{-1} = atu^n t^{-1} = u \rangle$. Define $\phi \in Aut(G)$ by

$$\phi: \begin{cases} u \mapsto u \\ r \mapsto s \\ s \mapsto t \\ t \mapsto rsts^{-1}t^{-1} \end{cases}$$



Figure 2: The quotient T/G in Example 1.11

Define the tree T (whose quotient T/G is represented on Figure 2) by a fundamental domain with vertices v, x and edges

 $e_a = [v, rv]$ $e_b = [v, tx]$ $e_e = [v, x]$ $e_f = [v, s^{-1}x]$

Define f on T by

$$\begin{array}{l} f: v \mapsto v, x \mapsto tx \\ e_a \mapsto e_e - s \cdot \bar{e}_f \\ e_b \mapsto e_a - r \cdot e_e - rs \cdot \bar{e}_f - rs \cdot e_b - rst \cdot \bar{e}_e - rst \cdot e_f \\ e_e \mapsto e_b \\ e_f \mapsto e_e \end{array}$$

The map f is a train track representative for ϕ . To see this we can compute the successive images of the turns taken by f. Consider the turn $\{\bar{e}_a, re_e\}$ at vertex rv which is taken by $f(e_b)$:

$$r\{r^{-1}\bar{e}_{a}, e_{e}\} \xrightarrow{f} \phi(r)\{e_{f}, e_{b}\} \xrightarrow{f} \phi^{2}(r)\{e_{e}, e_{a}\} \xrightarrow{f} \phi^{3}(r)\{e_{b}, e_{e}\} \xrightarrow{f} \phi^{4}(r)\{e_{a}, e_{b}\}$$

When applying f to $\phi^4(r)\{e_a, e_b\}$ we find a turn in the orbit of $\phi^2(r)\{e_e, e_a\}$ which we had already found. Thus $\{\bar{e}_a, re_e\}$ is a legal turn. The proof for the other turns goes the same way.

The inverse of ϕ is

$$\phi^{-1}: \begin{cases} u \mapsto u \\ r \mapsto t s r s^{-1} r^{-1} \\ s \mapsto r \\ t \mapsto s \end{cases}$$

which is the same automorphism as ϕ , but with swapped roles for r and t. Thus it admits a train track map.

Let $f: T \to S$ be a *G*-equivariant map between trees of \mathcal{D} , sending vertex to vertex and edge to edge path. By [For02] it is a quasi-isometry, i.e. a map such that for all $x, y \in T$, $K^{-1}d_T(x, y) - C \leq d_{T'}(h(x), h(y)) \leq Kd_T(x, y) + C$. Thus the map has bounded backtracking property (see [GJLL98]) and there exists a constant BBT $(f) \leq K^2C + C$ such that for every $x, y \in T$ the image f([x, y]) lies in a BBT(f)-neighbourhood of [f(x), f(y)].

In [BFH97] and [Alg11], a similar constant BCC(f) is used. Let us clarify the link between these constants. Suppose $\alpha \cdot \beta$ is a geodesic concatenation of paths with α f-legal. When applying f to $\alpha \cdot \beta$, there is a subsegment $\tau \subset \alpha$ such that $f(\tau) \subset f(\beta)$. Let $\tau' \subset \beta$ be a minimal prefix such that $f(\tau) \subset f(\tau')$. The first point of τ and last point of τ' are mapped to the same point. Then because f is a quasi-isometry there is a constant K depending only on f such that the length of $\tau \cdot \tau'$ is bounded by K. This gives a bound BCC(f) (from bounded cancellation constant, introduced by Cooper in [Coo87]) on $f(\tau)$: the simplification which occurs at an illegal turn is bounded by BCC(f). By applying the previous paragraph to $\tau \cdot \tau'$ we have BCC(f) \leq BBT(f). In order to keep a reduced number of constants, we will use the BBT constant instead of BCC where it could be used.

For a path η in a tree T, we denote by $[\eta]$ the unique non-backtracking path which has the same endpoints as η . We can extend this notation to infinite paths which converge to a point in the boundary of T: for example, this is well-defined for a bi-infinite quasi-geodesic such as the image of a line by a quasi-isometry.

Definition 1.12. Let $\phi \in \text{Out}(G)$ be a fully irreducible automorphism with a train track representative $f: T \to T$. The *critical constant* is $C_f := \frac{2 \text{ BBT}(f)}{\lambda - 1}$.

The critical constant has the following property: for any geodesic concatenation $\alpha \cdot \beta \cdot \gamma \subset T$ such that β is legal and $\operatorname{len}(\beta) \geq C_f$ then let $\alpha' \subset \alpha, \beta' \subset \beta, \gamma' \subset \gamma$ such that the path $[f(\alpha \cdot \beta \cdot \gamma)]$ can be written as the concatenation $[f(\alpha')] \cdot [f(\beta')] \cdot [f(\gamma')]$. Then $\operatorname{len}(f(\beta')) \geq C_f$. More specifically we have:

Lemma 1.13. Let $\phi \in \text{Out}(G)$ be fully irreducible. Let $f: T \to T$ be a train track representative. Let α be any path in T. Let $\beta \subset \alpha$ be a legal subpath with length at least $2C_f$. Define β' as the legal subpath of β obtained by cutting out the $\frac{C_f}{2}$ -neighbourhood of the endpoints. Then β' satisfies the following condition: for all $n \in \mathbb{N}$

$$f^n(\alpha \setminus \beta') \cap f^n(\beta') = \emptyset \text{ and } f^n(\beta') \subset [f^n(\alpha)]$$

In particular $\operatorname{len}([f^n(\alpha)]) \ge \lambda^n \operatorname{len}(\beta').$

Proof. Let α, β be as above.

We actually prove a slightly stronger statement by induction on n. Define β'_n as the segment obtained by cutting out a $BBT(f) \sum_{k=1}^n \lambda^{-k}$ -neighbourhood from the endpoints of β . Observe that $\beta' = \bigcap_{n \in \mathbb{N}} \beta'_n$ since $BBT(f) \sum_{k=1}^\infty \lambda^{-k} = \frac{BBT(f)}{\lambda - 1} = \frac{C_f}{2}$.

We will prove that for all $n \in \mathbb{N}$ we have

$$f^n(\alpha \setminus \beta'_n) \cap f^n(\beta'_n) = \emptyset$$
 and $f^n(\beta'_n) \subset [f^n(\alpha)]$

and since $\beta' \subset \beta'_n$ is a subsegment of the legal segment β'_n , the same holds for β' .

The condition is true for n = 0 since $\beta'_0 = \beta$.

Suppose the lemma holds for some $n \in \mathbb{N}$. Since β'_n is legal we have $\operatorname{len}(f^n(\beta'_n)) = \lambda^n \operatorname{len}(\beta'_n)$. Besides $f^n(\beta'_n) \subset [f^n(\alpha)]$. Apply f to the path $f^n(\alpha)$. There may be cancellation at the endpoints of the legal segment $f^n(\beta'_n)$ but this cancellation does not exceed BBT(f) when measured in $f^{n+1}(\beta'_n)$, since β'_n is legal.

This neighbourhood in $f^{n+1}(\beta'_n)$ corresponds to a $\lambda^{-n-1} \operatorname{BBT}(f)$ -neighbourhood of the endpoints of β'_n : as a result $f^{n+1}(\beta'_{n+1})$ does not intersect $f(f^n(\alpha) \setminus f^n(\beta'_n))$ since it is contained in β'_n . It does not intersect $f(f^n(\beta'_n) \setminus f^n(\beta'_{n+1}))$ either. Finally note that $f(f^n(\alpha) \setminus f^n(\beta'_n)) \cap f^{n+1}(\beta'_n) = f^{n+1}(\alpha \setminus \beta'_n) \cap f^{n+1}(\beta'_n)$. Since $f^{n+1}(\beta'_{n+1})$ does not meet $f^{n+1}(\alpha \setminus \beta'_{n+1})$, is is contained in $[f^{n+1}(\alpha)]$.

A consequence of Lemma 1.13 is:

Lemma 1.14. Let $\phi \in \text{Out}(G)$ be fully irreducible. Let $f: T \to T$ be a train track representative. For any path α in T, for any legal subpath $\beta \subset \alpha$ such that $\operatorname{len}(\beta) > 2C_f$, we have for every $n \in \mathbb{N}$:

$$\operatorname{len}(f^{n}(\beta) \cap [f^{n}(\alpha)]) \geq \frac{1}{2}\lambda^{n}\operatorname{len}(\beta)$$

Proof. Suppose α contains a legal subsegment β of length greater than $2C_f$. Let β' be the subsegment of β at distance $\frac{C_f}{2}$ from the endpoints of β . By Lemma 1.13, for every $n \in \mathbb{N}$, $f^n(\beta') \subset [f^n(\alpha)]$ so we have:

$$\operatorname{len}(f^{n}(\beta')) = \lambda^{n} \operatorname{len}(\beta')$$
$$= \lambda^{n} \left(\operatorname{len}(\beta) - \frac{2 \operatorname{BBT}(f)}{\lambda - 1} \right)$$
$$\geq \lambda^{n} \operatorname{len}(\beta) \left(1 - \frac{1}{2} \right)$$

Therefore $\operatorname{len}(f^n(\beta) \cap [f^n(\alpha)]) \geq \frac{1}{2}\lambda^n \operatorname{len}(\beta).$

Definition 1.15. Let $f: T \to T$ be a train track representative for $\phi \in \text{Out}(G)$. A nonbacktracking segment $\eta \subset T$ is a *periodic Nielsen path* if there exists $g \in G$ and $n \geq 1$ such that $g[f^n(\eta)] = \eta$. We call it simply a Nielsen path if we can choose n = 1.

A periodic Nielsen path is *indivisible* if it cannot be written as the non-backtracking concatenation $\alpha \cdot \beta$ of two periodic Nielsen paths.

A result about periodic indivisible Nielsen paths (or pINPs) from [Pap22] is:

Proposition 1.16. Let $f: T \to T$ be a train track representative for an automorphism $\phi \in$ Out(G). There are only finitely many orbits of periodic indivisible Nielsen paths.

Periodic Nielsen paths give a characterization of pseudo-periodic conjugacy classes for $\phi \in$ Out(G), proved in [Pap22, Section 3]:

Lemma 1.17. Let $f: T \to T$ be a train track representative for $\phi \in Out(G)$. The conjugacy class of an element $g \in G$ is pseudo-periodic for ϕ if and only if the axis of g in T is a geodesic concatenation of periodic indivisible Nielsen paths.

Lemma 1.18. Suppose that ϕ is fully irreducible, pseudo-atoroidal and has a train track representative $f: T \to T$. Then there exists $m \in \mathbb{N}$ such that it is impossible to concatenate more than m periodic Nielsen paths for f together in T, and more than m periodic Nielsen paths for f_- in T_- .

Proof. There are finitely many orbits of periodic INPs; let l be the number of orbits of periodic INPs. By contradiction, suppose L is a path in T which contains a concatenation of more than 2l pINPs. Then there exists $\eta, g\eta \subset L$ with $g \in G$ loxodromic such that there is a fundamental domain for g which is a concatenation of pINPs. By Lemma 1.17, this implies that g is a loxodromic pseudo-periodic element for ϕ , which is impossible since ϕ is pseudo-atoroidal, so we can set m := 2l.

1.3 The Lipschitz metric on \mathcal{D}

The space \mathcal{D} can be endowed with a pseudo-metric called the *Lipschitz metric*. For $T, T' \in \mathcal{D}$ define

$$\operatorname{Lip}(T, T') = \inf_{f:T \to T'} \operatorname{Lip}(f)$$

where the infimum is taken over all G-equivariant Lipschitz functions $f: T \to T'$. In [Mei15] the following is proved:

Proposition 1.19. For $T, T' \in \mathcal{D}$ there exists a *G*-equivariant map $f: T \to T'$, sending vertex to vertex and edge to edge path, linear on the edges, such that $\operatorname{Lip}(f) = \operatorname{Lip}(T, T')$.

The Lipschitz metric is defined as follows: for $T, T' \in \mathcal{D}$

$$d_{\rm Lip}(T,T') = \log \left[{\rm Lip}(T,T') \frac{{\rm vol}(T/G)}{{\rm vol}(T'/G)} \right]$$

The distance $d_{\text{Lip}}(T,T')$ is unchanged by rescaling T or T': it only depends on their projective classes. If T, T' are normalized so that $\operatorname{vol}(T) = \operatorname{vol}(T') = 1$ then $d_{\text{Lip}}(T,T') = \log \operatorname{Lip}(T,T')$. Sometimes it is more practical to work with 1-Lipschitz maps, for example when $T \to T'$ is a collapse or a fold. When $\operatorname{Lip}(T,T') = 1$ then $d_{\operatorname{Lip}}(T,T') = \log \frac{\operatorname{vol}(T)}{\operatorname{vol}(T')}$.

The Lipschitz metric is not a metric in the actual sense.

Lemma 1.20. The Lipschitz metric has the following properties:

- (i) for $T, T' \in \mathcal{D}, d_{\text{Lip}}(T, T') \ge 0$
- (*ii*) for $T, T', T'' \in \mathcal{D}$, $d_{\text{Lip}}(T, T'') \le d_{\text{Lip}}(T, T') + d_{\text{Lip}}(T', T'')$

Proof. (i) Let $T, T' \in \mathcal{D}$ scaled such that $\operatorname{Lip}(T, T') = 1$. Then f induces a 1-Lipschitz map on the quotients. By minimality f is surjective so $\operatorname{vol}(T'/G) \leq \operatorname{vol}(T/G)$. Thus

$$\log \operatorname{Lip}(T, T') \frac{\operatorname{vol}(T/G)}{\operatorname{vol}(T'/G)} \ge 1$$

(ii) Let $T, T', T'' \in \mathcal{D}$. Let $f: T \to T', f': T' \to T''$ be Lipschitz maps. Then $\operatorname{Lip}(T, T'') \leq \operatorname{Lip}(f' \circ f) \leq \operatorname{Lip}(f) \operatorname{Lip}(f')$. By taking the lower bound we get $\operatorname{Lip}(T, T'') \leq \operatorname{Lip}(T, T') \operatorname{Lip}(T', T'')$. By taking the logarithm we obtain what we want.

Remark 1.21. The other properties of metrics fail for \mathcal{D} :

1. Classical example for F_2



2. Example in BS(2,4)



Figure 3: Counter examples for symmetry of the Lipschitz metric

- like in CV_N the Lipschitz metric is not symmetric. A common counter example is drawn on Figure 3: if T, T' are the same tree with a different metric on edges such that T'/G has a very short loop, $d_{\text{Lip}}(T', T)$ is very big.
- unlike in CV_N there exist T, T' in \mathcal{D} such that $d_{\text{Lip}}(T, T') = 0$ and $d_{\text{Lip}}(T', T) \neq 0$. More precisely, $d_{\text{Lip}}(T', T)$ can be chosen arbitrarily big. See Figure 3.
- If $\phi \in \text{Out}(G)$ and $T \in \mathcal{D}$ then $d_{\text{Lip}}(T, T \cdot \phi) = 0$ implies that $T = T \cdot \phi$. This is a consequence of the fact that the actions are minimal so maps are surjective. A 1-Lipschitz *G*-equivariant surjective map from *T* to itself is an isometry, unless *G* is solvable.

The Lipschitz metric and its computation have been explored before in [Bes11] for free groups, [FM15] for free products, and [Mei15] for more general deformation spaces. The facts presented below can be found in these papers.

Let $T, T' \in \mathcal{D}$. Let $f: T \to T'$ be a piecewise linear *G*-equivariant map. The *tension graph* $\Delta(f)$ is the subforest of *T* spanned by edges $e \in E(T)$ such that the stretch factor on *e* is Lip(f). The map *f* is *optimal* if it realizes the infimum of Lip(T, T') and if at every vertex $v \in \Delta(f)$, there are at least two gates at *v* for the gate structure induced by *f* which contain edges in $\Delta(f)$. In [Mei15] Meinert proves that optimal maps exist.

The distance between two points in \mathcal{D} can be effectively computed by comparing translation lengths of some elements of G in both trees. Suppose $f: T \to T'$ is a G-equivariant map between trees of \mathcal{D} . For every $g \in G$ we have, by applying f to a fundamental domain,

$$\frac{\|g\|_{T'}}{\|g\|_T} \le \operatorname{Lip}(f)$$

thus by taking the lower bound we have $\operatorname{Lip}(T, T') \geq \max_{g \in G} \frac{\|g\|_{T'}}{\|g\|_T}$. It is actually an equality, as this result from [Mei15] states:

Lemma 1.22. Let $T, T' \in \mathcal{D}$. Let $f : T \to T'$ be an optimal map. There exists $g \in G$ such that $\operatorname{Axe}_T(g)$ is f-legal and contained in the tension graph for f. In particular

$$\operatorname{Lip}(T, T') = \frac{\|g\|'_T}{\|g\|_T} = \max_{h \in G} \frac{\|h\|'_T}{\|h\|_T}$$

Let $T \in \mathcal{D}$. A candidate of T is an element $g \in G$ such that the map $\pi : \operatorname{Axe}_T(g)/\langle g \rangle \to T/G$ has one of the following forms (see Figure 4):

- a loop: the map π is an embedding
- a figure eight: there are two embedded circles u, v in T which intersect in exactly one point. The map π maps the circle $\operatorname{Axe}_T(g)/\langle g \rangle$ to the tight loop which crosses u and v successfully.
- a barbell: there are two disjoint embedded circles u, v in T/G, and a segment s which connects u to v; π maps the circle to the tight loop which crosses u, s, then v, and then s backwards.
- an embedded singly degenerate barbell : it is the degenerate case of the barbell where v is a single vertex. In that case, the vertex group at v must be greater than the edge group of the last edge of s.
- an embedded doubly degenerate barbell : degenerate case of the barbell where both circles are single vertices. The vertex group at *u* must also be greater than the edge group of the first edge of *g*.

In particular a candidate crosses each orbit of edge at most twice. In [FM15, Theorem 9.10] the following theorem is proved for the case of free products:

Theorem 1.23. Let $T \in \mathcal{D}$. For every $T' \in \mathcal{D}$, there exists a candidate g of T such that

$$Lip(T, T') = \frac{\|g\|'_T}{\|g\|_T}$$

For the proof we refer to [FM15]. Note that the context differs a little since the deformation space and the group are different. The relevant point is that contrary to elements of CV_N , trees in the outer space for a free product may have non-free vertex stabilizers, which account for the degenerate barbells. In the case of GBS products we also have vertices whose stabilizer is greater than the stabilizers of incident edges, hence the presence of degenerate barbell candidates.

1.4 The axis of an irreducible automorphism

Proposition 1.24. For an automorphism $\phi \in Out(G)$ with a primitive train track map $f: T \to T$, then

$$\operatorname{Lip}(f) = \operatorname{Lip}(T, T \cdot \phi) = \min_{S \in \mathcal{D}} \operatorname{Lip}(S, S \cdot \phi)$$



Figure 4: The five possible shapes for a candidate in the quotient graph

Proof. Since f is a train track map, at each vertex of T there are at least two gates. Consequently there exists $h \in G$ such that $\operatorname{Axe}_T(g)$ is legal. Let $n \in \mathbb{N}$. Since h is f^n -legal for all $n \in \mathbb{N}$ we have $\frac{\|\phi^n(h)\|_T}{\|h\|_T} = \operatorname{Lip}(f^n) = \operatorname{Lip}(f)^n$.

Then we have $\operatorname{Lip}(T, T \cdot \phi^n) = \sup_{g \in G} \frac{\|\phi^n(g)\|_T}{\|g\|_T} = \frac{\|\phi^n(h)\|_T}{\|h\|_T} = \operatorname{Lip}(f)^n$. Let $\lambda := \operatorname{Lip}(f)$. Let $S \in \mathcal{D}$. Let $f' : S \to S \cdot \phi$ be such that $\operatorname{Lip}(S, S \cdot \phi) = \operatorname{Lip}(f') =: \lambda'$. By triangular

Let $S \in D$. Let $f': S \to S \cdot \phi$ be such that $\operatorname{Lip}(S, S \cdot \phi) = \operatorname{Lip}(f') =: \lambda'$. By triangular inequality, for $n \in \mathbb{N}$ we have $\operatorname{Lip}(S, S \cdot \phi^n) \leq \lambda'^n$.

By triangular inequality we have

 $\lambda^n = \operatorname{Lip}(T, T \cdot \phi^n) \le \operatorname{Lip}(T, S) \operatorname{Lip}(S, S \cdot \phi^n) \operatorname{Lip}(S, T) \le \lambda'^n \operatorname{Lip}(T, S) \operatorname{Lip}(S, T)$

If $\lambda' < \lambda$ this inequality becomes false when n is big enough, hence the minimality of $\lambda = \text{Lip}(T, T \cdot \phi)$.

A map $\gamma : \mathbb{R} \to \mathcal{D}$ is a *geodesic* for the Lipschitz distance if for any $t, s \in \mathbb{R}, t < s \Rightarrow d_{\text{Lip}}(\gamma(t), \gamma(s)) = s - t$. Since the metric is not symmetric, the distance $d_{\text{Lip}}(\gamma(s), \gamma(t))$ needs not be |s - t|: in fact it can even be zero.

Proposition 1.25. Let $f: T \to T$ be a train track representative for ϕ . There exists a geodesic $\mathcal{L}_f: \mathbb{R} \to \mathcal{D}$ such that for every $n \in \mathbb{Z}, T \cdot \phi^n \in \mathcal{L}_f$, and such that the map \mathcal{L}_f is continuous for the axes topology.

For a construction see [Mei15, Section 4.4]. The *axes topology* on \mathcal{D} is the coarsest topology such that the functions $T \mapsto ||g||_T$ for $g \in G$ are continuous; for more information on the topologies of \mathcal{D} see [GL07].

If $f: T \to T$ is a train track representative we choose an arbitrary axis \mathcal{L}_f crossing T and denote by T_t the unique point of the axis such that $d_{\text{Lip}}(T, T_t) = t$ if $t \ge 0$ and $d_{\text{Lip}}(T_t, T) = -t$ if $t \le 0$.

Similarly there is an axis $\mathcal{L}_{f_{-}}$ for ϕ^{-1} defined from $f_{-}: T_{-} \to T_{-}$. Since d_{Lip} is Out(G)-invariant the axes stay within a bidirectional bounded neighbourhood of each other.

We already stated that between any two trees in \mathcal{D} , there exists a *G*-equivariant quasiisometry. The quasi-isometry constants can be chosen uniformly if the trees lie in a subsegment of \mathcal{L}_f :

Lemma 1.26. For any $T, S \in \mathcal{D}$ and $D \ge 1$ such that $\max\{\operatorname{Lip}(T, S), \operatorname{Lip}(S, T)\} \le D$, any optimal map $T \to S$ is an equivariant (D, 4D)-quasi-isometry.

Proof. Let $T, S \in \mathcal{D}$. Scale T, S such that $\operatorname{vol}(T/G) = \operatorname{vol}(S/G) = 1$. There exists $X \subset T$ such that $G \cdot X = T$ and $\operatorname{diam}(X) \leq 1$. For every oriented edges $\overrightarrow{e}, \overrightarrow{e'} \in E(T)$, there exists an edge path with length at most 2 with first edge \overrightarrow{e} and last edge $h \overrightarrow{e'}$ for some $h \in G$. This fails if G is solvable, but we assumed that it is not the case.

Let us prove this fact. First we will prove that for any edge e there exists a path $\overrightarrow{e} \dots \overleftarrow{he}$ for some $h \in G$.

Since G is not solvable, then the action of G on T is irreducible. Since T is not a line, there exist translates h_1e, h_2e such that for any line containing both edges, the orientations of the edges along the line differ.

There exists $h \in G$ such that $\operatorname{Axe}_T(h)$ crosses both h_1e and h_2e . Either h_1e and h_2e point towards each other, or they may point away from each other, but in that case there exists $k \in \mathbb{Z}$ such that $h^k h_1 e$ and $h_2 e$ point towards each other. Then we get a path $\overline{h_1e} \dots \overline{h_2e}$.

Now let e, e' be edges in the tree. There is a path which connects both edges, but the path may fail to contain a translate of $\overrightarrow{e} \dots \overrightarrow{he'}$ for some $h \in G$. By concatenating paths which reverse the orientation on one or both sides we obtain a path satisfying the condition.

As for the bound on the length of the path, observe that if an edge appears in the path twice with same orientation, then subpath can be deleted to obtain a shorter path.

Let $\tau: T \to S$ be an optimal map. Let $x, y \in T$. Let e be the first edge of [x, y]. Let e' be an edge with origin y and not in [x, y]: such an edge exists since T is minimal. By the fact above, there exists $g \in G$ and a path containing $\overrightarrow{e'}, g\overrightarrow{e'}$ with these orientations and length at most 2. Thus $d_T(gx, y) \leq 2$ and $[x, y] \subset \operatorname{Axe}_T(g)$. We have $d_T(x, y) + 2 \leq ||g||_T$.

Then by Lemma 1.27 we have $\operatorname{Lip}(S,T) \leq D, \operatorname{Lip}(T,S) \leq D$ so

$$d_S(\tau(x), \tau(y)) \le Dd_T(x, y)$$

and

$$d_{S}(\tau(x),\tau(y)) \geq d_{S}(\tau(x),\tau(gx)) - d_{S}(\tau(gx),\tau(y))$$

$$\geq \|g\|_{S} - 2\operatorname{Lip}(\tau)$$

$$\geq \frac{\|g\|_{T}}{D} - 2\operatorname{Lip}(\tau)$$

$$\geq \frac{d_{T}(x,y)}{D} - \frac{2}{D} - 2D$$

Then the optimal map $\tau: T \to T_{t'}$ is a (D, 4D)-quasi-isometry.

We have the following result about the axes \mathcal{L}_f and \mathcal{L}_{f-} :

Lemma 1.27. Let $\phi \in \text{Out}(G)$ be a fully irreducible automorphism. Let $f: T \to T$ be a train track representative for ϕ and $f_-: T_- \to T_-$ be a train track representative for ϕ^{-1} . Let $\mathcal{L}_f, \mathcal{L}_{f_-}$ be axes in \mathcal{D} for ϕ and ϕ^{-1} .

Let a < b, c, d be real numbers. There exists a constant $D_{a,b,c,d} > 1$ such that for every $X, Y \in \{T_t/a \le t \le b\} \cup \{(T_-)_t/c \le t \le d\}$, $\operatorname{Lip}(X, Y) \le D_{c,d}$.

Proof. Let $n, m \in \mathbb{N}$ be such that

$$a \log(\lambda) \le a, m \log(\lambda) \ge b, n \log(\lambda_{-}) \le c, m \log(\lambda_{-}) \ge d$$

There is a quadrilateron which crosses $T \cdot \phi^n, T \cdot \phi^m, T_- \cdot \phi^n, T_- \cdot \phi^n$, which contains $\{T_t/a \le t \le b\}$ and $\{(T_-)_t/c \le t \le d\}$. Its length is

$$d := d_{\operatorname{Lip}}(T \cdot \phi^n, T \cdot \phi^m) + d_{\operatorname{Lip}}(T, T_-) + d_{\operatorname{Lip}}(T_- \cdot \phi^m, T_- \cdot \phi^n) + d_{\operatorname{Lip}}(T_-, T)$$

Therefore, for every X, Y as above we have $L(X, Y) \leq D := e^d$.

Remark 1.28. Lemmas 1.26 and 1.27 imply that for every $S \in \mathcal{D}$, there exist (K, C) such that for every $t \in [0, \log(\lambda)]$, there exist equivariant (K, C)-quasi-isometries $T_t \to S$ and $S \to T_t$.

2 The stable and unstable laminations

Let $T, T' \in \mathcal{D}$. There exists a *G*-invariant quasi-isometry $T \to T'$. In fact all equivariant quasi-isometries $T \to T'$ are close:

Lemma 2.1. Let T, T' be metric G-trees such that T is co-compact. Let u, v be continuous G-equivariant maps $T \to T'$. There exists a constant C depending on u and v such that for every $x \in T$

$$d_{T'}(u(x), v(x)) \le C$$

Proof. Let $K \subset T$ be a compact subset such that $G \cdot K = T$. Let $C := \max_{x \in K} d_{T'}(u(x), v(x))$. For every $y \in T$ there exists $g \in G$ and $x \in K$ such that y = gx so by G-equivariance

$$d_{T'}(u(y), v(y)) = d_{T'}(gu(x), gv(x)) = d_{T'}(u(x), v(x)) \le C.$$

Recall that a *G*-invariant quasi-isometry f induces a *G*-equivariant homeomorphism $\partial T \rightarrow \partial T'$. Because of Lemma 2.1 the homeomorphism does not depend on f so there is a canonical *G*-invariant identification of the boundaries of all trees of \mathcal{D} .

A lamination Λ is a G-invariant, symmetric, closed subset of $\partial T \times \partial T \setminus \Delta$ where Δ is the diagonal, for some $T \in \mathcal{D}$. The discussion above implies that for any $S \in \mathcal{D}$, Λ can be canonically identified with a subset of $\partial S \times \partial S \setminus \Delta$ so we may drop the reference to T.

When we fix a tree T, Λ identifies with a G-invariant set of unoriented bi-infinite geodesics of T which we call the *realization* of Λ in T and which we denote by Λ_T . Its elements are called *leaves*. A *leaf segment* is a subsegment of a leaf of Λ_T . The assumption that Λ is a closed subset of $\partial T \times \partial T \setminus \Delta$ translates into the following fact: if $(\sigma_n)_{n \in \mathbb{N}}$ is an increasing sequence of leaf segments in T whose union is a bi-infinite geodesic $\ell \subset T$, then ℓ is a leaf of Λ_T .

If $T' \in \mathcal{D}$ is another tree, there exists a *G*-invariant quasi-isometry $h: T \to T'$. For any leaf $\lambda \in \Lambda_T$, the line of T' obtained by tightening $h(\lambda)$ is a leaf of $\Lambda_{T'}$, and conversely all leaves of $\Lambda_{T'}$ are tightened images of leaves of Λ_T .

Let $\phi \in \text{Out}(G)$ be a fully irreducible automorphism. Let $f: T \to T$ be an primitive train track representative for ϕ with Lipschitz constant $\lambda > 1$. Define the *stable lamination* Λ_f^+ by its realization in the train track tree T, as the set of bi-infinite geodesics whose subsegments belong to

$$\{\sigma \subset T/\exists e \in E(T), \exists n \in \mathbb{N}, \sigma \subset f^n(e)\}$$

We call $\Lambda_{f_{-}}^{+}$ the unstable lamination.

Remark 2.2. Since $\lambda > 1$, if e is an edge of T such that $e \subset f(e)$, then the limit of $f^n(e)$ when $n \to \infty$ is a leaf of the lamination. Since f is primitive, one can check that the set of leaves which can be obtained by this process by replacing f with gf for $g \in G$ is a G-invariant subset of the stable lamination and its closure is the stable lamination.

Lemma 2.3. For every l > 0 there exists $n_{\Lambda} > 0$ such that if $\alpha \subset T$ contains a legal subsegment with length at least $2C_f$, then $[f^n(\alpha)]$ contains a leaf segment of Λ_f^+ with length at least l for all $n \geq n_{\Lambda}$.

Proof. Let β be a legal subsegment of α with length at least $2C_f$. By Lemma 1.13 the subpath $\theta \subset \beta$ obtained by truncating the $C_f/2$ -neighbourhood of the endpoints has the following property: for any $n \in \mathbb{N}$, $f^n(\theta) \subset [f^n(\alpha)]$.

We have $\operatorname{len}(\theta) \geq C_f$. There exists $n_1 \in \mathbb{N}$ depending on T and λ such that $\lambda^{n_1}C_f \geq 2 \max_{e \in E(T)} \operatorname{len}(e)$ so $f^{n_1}(\theta)$ contains an edge.

There exists $n_2 \in \mathbb{N}$ depending on l such that $\lambda^{n_2} \min_{e \in E(T)} \operatorname{len}(e) \geq l$. For $n \geq n_2$, for any $e \in E(T)$, $f^n(e)$ contains a leaf segment of Λ_f^+ with length l.

Then for any $n \ge n_1 + n_2$, $[f^n(\alpha)]$ contains a leaf segment of Λ_f^+ with length l.

Definition 2.4. A lamination Λ is *minimal* in T if all leaves of Λ_T have the same leaf segments up to the action of G, i.e. for every leaf segment $\sigma \subset T$ of Λ_T , for every leaf ℓ in T, there exists $g \in G$ such that $g\sigma \subset \ell$.

Definition 2.5. Let Λ be a lamination. Let $T \in \mathcal{D}$. A leaf $\ell \in \Lambda_T$ is quasi-periodic if for every C > 0 there exists L > 0 such that for every subsegment $\sigma \subset \ell$ with $\operatorname{len}(\sigma) = C$, for every subsegment $\gamma \subset \ell$ with $\operatorname{len}(\gamma) > L$, there exists $g \in G$ such that $g\sigma \subset \gamma$.

Remark 2.6. If $T \to S$ is a quasi-isometry and Λ_T is minimal, then Λ is minimal in S. Similarly, if a leaf in T is quasi-periodic, then the realization of this leaf in another tree $S \in \mathcal{D}$ is also quasi-periodic. A proof is given in [Pap22, Remark 1.17].

The following is proved in [BFH97], although for a slightly different definition of the stable lamination.

Lemma 2.7. Let $f : T \to T$ be an irreducible train track representative for an automorphism $\phi \in \text{Out}(G)$ with Lipschitz constant λ . Then the stable lamination Λ_f^+ is minimal and its leaves in T are quasi-periodic.

Proof. First let us prove the minimality. There exists $N \in \mathbb{N}$ such that for all $e, e' \in E(T/G)$, $f^N(e)$ contains an edge in the orbit of e'.

Let $\ell \subset T$ be a leaf of Λ_f^+ . Let $k \in \mathbb{N}$. Let us prove that there exists a constant L_k such that every segment of ℓ longer than L_k contains a translate of $f^k(e_0)$ for every $e_0 \in E(T/G)$.

Let σ be a subsegment of ℓ with length at least $L_k := 2\lambda^k \max_{e \in E(T/G)} \operatorname{len}(f^N(e))$. By definition of the stable lamination, there exists $e \in E(T)$ such that $\sigma \subset f^{N+n}(e)$ with $n \geq k$. The segment σ is contained in the concatenation of segments $f^k(f^N(e'))$ for edges $e' \subset f^{n-k}(e)$. Each of these segments contains a translate of $f^k(e_0)$ and is shorter than $\operatorname{len}(\sigma)/2$ so one of them is contained in σ , hence in ℓ . This proves that ℓ contains a translate of every leaf segment of Λ_f^+ contained in $f^k(e_0)$ for any $e_0 \in E(T)$.

This also proves the quasi-periodicity: for all C > 0 there exists $k \in \mathbb{N}$ such that every segment I longer than C is contained in $f^k(e)$ for some edge e, and every leaf segment of the leaf ℓ longer than L_k contains a copy of $f^k(e)$ and thus a copy of I.

Lemma 2.8. Let Λ, Λ' be two distinct minimal closed G-invariant laminations with quasiperiodic leaves. Then for any G-tree T, there exists a bound C_T on the length of leaf segments which are common to both laminations.

Proof. Let $T \in \mathcal{D}$. By contraposition we prove that if the bound C_T does not exist then Λ and Λ' have the same sets of leaf segments in T. Since they are closed this implies $\Lambda = \Lambda'$.

Suppose that there exist leaf segments $(\eta_n)_{n\in\mathbb{N}}$ with $\eta_n \subset \Lambda_T \cap \Lambda'_T$ for all $n \in \mathbb{N}$, and $\operatorname{len}(\eta_n) \to \infty$. Then for any leaf segment $\sigma \subset \Lambda_T$, there exists $n \in \mathbb{N}$ and $g \in G$ such that $g\sigma \subset \eta_n \subset \Lambda'_T$ so σ is also a leaf segment of Λ'_T . By symmetry Λ_T and Λ'_T have the same leaf segments, so the laminations Λ and Λ' are equal.

We need the following:

Lemma 2.9. Let $h: T \to T'$ be a (K, C)-quasi-isometry where $K \ge 1, C \ge 0$.

For every l > 0 there exists L > 0 depending on l, K, C such that if η is a bi-infinite geodesic, if σ is a subsegment of η with length at least L, then $[h(\sigma)]$ contains a subsegment of $[h(\eta)]$ with length at least ℓ .

Proof. Let l > 0. Let η be a bi-infinite geodesic. Let σ be a subsegment of η . Then the length of $[h(\sigma)]$ is at least $K^{-1} \operatorname{len}(\sigma) - C$.

The image $h(\eta)$ lies in a BBT(h)-neighbourhood of $[h(\eta)]$, where BBT(h) $\leq K^2C + C$. The endpoints of $[h(\sigma)]$ are in this neighbourhood so the length of $[h(\sigma)] \cap [h(\eta)]$ is at least $K^{-1} \operatorname{len}(\sigma) - C - 2 \operatorname{BBT}(h)$. Thus by taking $L \geq K(l + C + 2 \operatorname{BBT}(h))$, if $\operatorname{len}(\sigma) \geq L$, then $[h(\sigma)]$ contains an *l*-segment of $[h(\eta)]$.

For a lamination Λ , $T \in \mathcal{D}$ and C > 0, a *C*-piece of Λ_T is a leaf segment of Λ_T with length C.

Lemma 2.10. Let $f : T \to T$ and $f' : T' \to T'$ be two train track representatives for a fully irreducible automorphism $\phi \in \text{Out}(G)$. Then the stable laminations Λ_f^+ and $\Lambda_{f'}^+$ are equal.

Proof. We will prove that every leaf segment of $(\Lambda_f^+)_{T'}$ is also a leaf segment of $(\Lambda_{f'}^+)_{T'}$: by symmetry we will get the result.

Let C > 0. By quasi-periodicity of the leaves of Λ_f^+ , there exists L > 0 such that every leaf segment of $(\Lambda_f^+)_{T'}$ longer than L contains every orbit of leaf segment of $(\Lambda_f^+)_{T'}$ with length at most C.

Let $h: T \to T'$ be a *G*-equivariant quasi-isometry.

By Lemma 2.9 there exists $L_0 > 0$ such that for every bi-infinite geodesic $\eta \subset T$, for every segment $\sigma \subset \eta$ with length at least L_0 , the segment $[h(\sigma)] \cap [h(\eta)]$ has length at least 2L + 2BBT(h). Without loss of generality, we may assume $L_0 \geq C_f$.

There exists $g \in G$ be such that $\operatorname{Axe}_{T'}(g)$ is legal for f'. The conjugacy class of g is not pseudo-periodic since $\|\phi^n(g)\|_{T'} \to \infty$ when $n \to \infty$.

The axis of g in T does not have to be legal, however the number of orbits of f-illegal turns under the action of $\langle \phi^n(g) \rangle$ cannot increase when $n \to \infty$: f sends f-legal subsegments to f-legal subsegments and $\operatorname{Axe}_T(\phi^n(g)) = [f^n(\operatorname{Axe}_T(g))]$. Since $\{\|\phi^n(g)\|_T, n \in \mathbb{N}\}$ is unbounded, this implies that there exists $n_0 \in \mathbb{N}$ such that $\operatorname{Axe}_T(\phi^{n_0}(g))$ contains an f-legal subsegment with length L_0 . Since $\operatorname{Axe}_{T'}(\phi^{n_0}(g))$ is also f'-legal, up to replacing $g \in \phi^{n_0}(g)$ we can assume $n_0 = 0$.

As in Lemma 2.3 there exists N > 0 such that for every $e \in E(T')$, $f'^N(e)$ is a leaf segment of $(\Lambda_{f'}^+)_{T'}$ with length at least 2L. The axis of $\phi^N(g)$ in T still contains a legal subsegment with length at least L_0 since $L_0 \ge C_f$. Once again, up to replacing g by $\phi^N(g)$, we may assume that the axis of g in T' can be cut into pieces of $(\Lambda_{f'}^+)_{T'}$ with length at least 2L.



Figure 5: When applying f^n and then f_{-}^n , the translation length of g increases if n is big enough

The map h maps $\operatorname{Axe}_T(g)$ to a BBT(h)-neighbourhood of $\operatorname{Axe}_{T'}(g)$. By Lemma 2.9 and by definition of L_0 , $h(\operatorname{Axe}_T(g)) \subset T'$ contains a leaf segment of $[h(\Lambda_f^+)_T)] = (\Lambda_f^+)_{T'}$ with length at least 2L + 2 BBT(h) and a subsegment with length at least 2L is contained in $Axe_{T'}(g)$.

Then there exists a segment $\gamma' \subset T'$ of length greater than L that is both a leaf segment $(\Lambda_f^+)_{T'}$ and $(\Lambda_{f'}^+)_T$. Thus every leaf segment of $(\Lambda_f)_{T'}$ of length C is a leaf segment of $(\Lambda_{f'})_{T'}$.

From now on, we can simply refer to the stable lamination as Λ_{ϕ}^+ or simply Λ^+ when the automorphism is obvious. The notation Λ_{ϕ}^{-} denotes the unstable lamination $\Lambda_{\phi^{-1}}^{+}$.

Lemma 2.11. For a fully irreducible automorphism $\phi \in \text{Out}(G)$, the stable lamination and unstable lamination are distinct.

Proof. Assume by contradiction that $\Lambda_{\phi}^{-} = \Lambda_{\phi}^{+}$. See Figure 5. Let $f : T \to T$ be a train track representative for ϕ and $f_{-} : T_{-} \to T_{-}$ be a train track representative for ϕ^{-1} . Let $\tau: T \to T_{-}$ be a *G*-equivariant quasi-isometry.

There exists $g \in G$ loxodromic whose axis in T is f-legal. By Lemma 2.9 there exists L > 0such that for every leaf segment σ of $(\Lambda^+)_T$ longer than L, $[\tau(\sigma)]$ contains a leaf segment of $(\Lambda^+)_{T_-}$ longer than $2C_{f_-}$.

Let $n_0 \in \mathbb{N}$ be such that for any edge $e \in T$, $\operatorname{len}(f^n(e)) \geq 2C_f$. Let $n \geq n_0$. Then every $e \in \mathbb{N}$ Axe_T($\phi^n(g)$) contributes a leaf segment of $(\Lambda^+)_{T_-} = (\Lambda^-)_{T_-}$ longer than $2C_f$ in Axe_T($\phi^n(g)$). By Lemma 1.13, the images $\beta_e := [\tau(f^n(e))]$ for different edges e contain subsegments β'_e obtained from β_e by cutting out the $\frac{C_{f_-}}{2}$ -neighbourhood of the endpoints. The subsegments β'_e satisfy the following: for any edge e, for any $m \in \mathbb{N}$, $f^m_-(\beta'_e) \subset \operatorname{Axe}_{T_-}(\phi^{n-m}(g))$ and for any other edge e', $f^m_-(\beta'_e) \cap f^m_-(\beta'_{e'}) = \emptyset.$

This implies that $[f_{-}^{n}(\operatorname{Axe}_{T_{-}}(\phi^{n}(g)))] = \operatorname{Axe}_{T_{-}}(g)$ contains two disjoint leaf segments $f_{-}^{n}(\beta_{e}')$, $gf_{-}^{n}(\beta_{e}') = f_{-}^{n}(\beta_{\phi^{n}(g)e}')$ longer than $\lambda^{n}C_{f}$.

Then we must have $||g||_{T_{-}} \geq \lambda^n C_f$, which is a contradiction for n sufficiently big.

Laminations and simple elements of G3

Simple elements, simple pairs and Whitehead graphs 3.1

Definition 3.1. A loxodromic element $g \in G$ is *simple* if it is contained in a proper cyclic factor of G.

A pair of elements $g, h \in G$ is simple if there exists cyclic factors H_g, H_h such that $g \in H_g, h \in H_h$ and a graph Γ of cyclic groups with $\pi_1(\Gamma) \simeq G$, with disjoint subgraphs Γ_g, Γ_h such that $\pi_1(\Gamma_g) \simeq H_g, \pi_1(\Gamma_h) \simeq H_h$.

In that case H_g , H_h belong to a proper system of cyclic factors, i.e. collection of conjugacy class of cyclic factors which can be simultaneously seen in some graph of groups as the fundamental groups of disjoint subgraphs.

Lemma 3.2. Suppose $b_1(G) \ge 3$. For any tree $T \in \mathcal{D}$, the candidates in T are simple.

Proof. If $b_1(G) \ge 3$ then every candidate g for T avoids at least an orbit of edges $G \cdot e$. Then $T \setminus G \cdot e$ is a proper subforest of G which contains the axis of g. It defines a cyclic factor containing g, so g is simple.

Lemma 3.3. Suppose $b_1(G) \ge 3$. Suppose $g, h \in G$ are candidates in $T \in \mathcal{D}$. There exists a candidate $k \in G$ such that $\{k, g\}$ and $\{k, h\}$ are both simple.

Proof. Since $b_1(\Gamma) \ge 3$ and g, h are candidates, neither of their axes crosses every orbit of edges in T.

Let e_g, e_h be edges in Γ such that $\pi(\operatorname{Axe}_T(g))$ avoids e_g and $\pi(\operatorname{Axe}_T(h))$ avoids e_h , where $\pi : T \to \Gamma$ is the quotient map. Since $b_1(g) \geq 3$ the graph $\Gamma' := \Gamma \setminus \{e_g, e_h\}$, which may be disconnected, has a connected component with first Betti number $b_1(\Gamma') \geq 1$. There exists an element $k \in G$ whose axis in T is in a lift of Γ' . Then $\operatorname{Axe}_T(k)$ crosses neither e_g nor e_h so:

- the axes of g, k are in $\Gamma \setminus e_q$, so $\{k, g\}$ is simple
- the axes of h, k are in $\Gamma \setminus e_h$, so $\{k, h\}$ is simple

Thus k is the element of G that we were looking for.

Definition 3.4. Let ℓ be a bi-infinite geodesic in $T \in \mathcal{D}$. A turn in ℓ is a pair $\{e, e'\} \subset E(T)$ of distinct edges such that o(e) = o(e') and $e \cup e' \subset \ell$.

Definition 3.5. Let \mathcal{G} be a collection of bi-infinite geodesics of some $T \in \mathcal{D}$. Let $v \in V(T)$. The Whitehead graph $W := Wh_T(\mathcal{G}, v)$ is the following graph:

- vertices of W are edges of T with origin v
- there is an edge e e' in W if there exists $\ell \in \mathcal{G}$ and $g \in G$ such that $g \cdot \ell$ contains both e and e', i.e. if $\{e, e'\}$ is a turn crossed by ℓ

Remark 3.6. For \mathcal{G}, T, v as in the definition, we have $\operatorname{Wh}_T(\mathcal{G}, v) = \operatorname{Wh}_T(G \cdot \mathcal{G}, v)$.

Examples 3.7. The two main examples, which we will both use in this paper, are the following.

- 1. $\mathcal{G} = \{\operatorname{Axe}_T(hgh^{-1}), h \in G\}$ is the collection of axes of all conjugates of some $g \in G$. In that case we write $\operatorname{Wh}_T(\mathcal{G}, v) = \operatorname{Wh}_T(g, v)$.
- 2. let $f: T \to T$ be a train track representative for a fully irreducible automorphism and let $S \in \mathcal{D}$, let $\mathcal{G} = (\Lambda^+)_S$. Since all leaves in Λ^+ have the same subsegments in S, for any leaf $\ell \in (\Lambda^+)_S$, for any $v \in V(S)$, $\operatorname{Wh}_S(\Lambda^+, v) = \operatorname{Wh}_S(\ell, v)$.

The interest of Whitehead graphs is that they help understanding cyclic factors. In [Pap21] we prove the following theorem (Theorem 2.14):

- **Theorem 3.8.** Let $g \in G$ be a loxodromic element. Then g is simple if and only if for every $T \in \mathcal{D}$ there exists $v \in T$ such that $Wh_T(g, v)$ is disconnected or has a cut vertex, i.e. a vertex $p \in Wh_T(g, v)$ such that $Wh_T(g, v) \setminus \{p\}$ is disconnected.
 - Let g, h ∈ G be loxodromic elements. Then {g, h} is simple if and only if for every T ∈ D there exists v ∈ T such that Wh_T({g, h}, v) is disconnected or has a cut vertex.

The stable lamination of an automorphism $\phi \in \text{Out}(G)$ is *carried* by a cyclic factor H if and only if there exists $T \in \mathcal{D}$ such that for every leaf $\ell \in (\Lambda^+)_T$ there exists a translate of the minimal subtree T_H which contains ℓ .

Minimality of these laminations imply that the stable lamination is carried by H if and only if there exists a leaf $\ell \in (\Lambda^+)_T$ such that ℓ is contained in T_H . For all $S \in T$, there exists a quasi-isometry $T \to S$ and it implies that the realization of ℓ in S is in the subtree S_H , so the fact that Λ^+ is carried by H can be seen in every $S \in \mathcal{D}$. These facts are proved in [Pap22].

Lemma 2.5 of [Pap22] implies:

Proposition 3.9. Suppose $\phi \in \text{Out}(G)$ is a fully irreducible automorphism with irreducible train track representative $f: T \to T$. Then no leaf of the stable lamination $(\Lambda_{\phi}^+)_T$ is carried by a cyclic factor.

3.2 Long segments of laminations in axes of elements of G

In this section, we assume that $\phi \in \operatorname{Aut}(G)$ is a fully irreducible automorphism such that both ϕ and ϕ^{-1} have train track representatives.

The following lemma is a transposition of Lemma 2.17 from [Pap21]. The original lemma gives a link between the Whitehead graph of the axis of a loxodromic element $g \in G$ in a tree S and the existence of a tree \hat{S} where $\hat{S} \to S$ is either a fold or a collapse which induces an isometry $\operatorname{Axe}_{\hat{S}}(g) \to \operatorname{Axe}_{S}(g)$. The proof of the lemma does not use the specific fact that $\operatorname{Axe}_{S}(g)$ is an axis of an element and could actually work with any bi-infinite geodesic. In particular, it can be transposed to laminations:

Lemma 3.10. Let $S \in \mathcal{D}$ such that no edge in S/G is a loop. Let ℓ^+ be a leaf of the stable lamination Λ^+ and ℓ^- be a leaf of the unstable lamination Λ^- . The following are equivalent:

- There exists a vertex $v \in V(S)$ such that $Wh_S(\{\ell^+, \ell^-\}, v)$ is disconnected or has a cut vertex
- There exists a tree Ŝ ∈ D and a non-injective map π := Ŝ → S such that if l̂⁺, l̂⁻ are the leaves in Ŝ corresponding to l⁺, l⁻ then π induces isometries l̂⁺ → l⁺ and l̂⁻ → l⁻.
- Remarks 3.11. 1. The assumption that S has no loop is not especially restrictive: in fact, up to subdividing all loops before applying the lemma, we may assume that S has no loop. The tree \hat{S} produced by the lemma does not have any loop either.
 - 2. A non-injective G map $\hat{S} \to S$ sending vertex to vertex and edge to edge is a composition of collapses and folds (see [BF91]). In particular we can assume that the map π given by the lemma is either a collapse or a fold.

Proposition 3.12. There exists $S \in \mathcal{D}$ such that for every $v \in V(S)$, the Whitehead graph $Wh_S(\Lambda^+ \cup \Lambda^-, v)$ is connected without cut vertex.

Proof. Let T be the initial train track representative for ϕ . We will change T gradually using Lemma 3.10.

By Proposition 3.9, the Whitehead graph $\operatorname{Wh}_T(\Lambda^+, v)$ is connected for every $v \in S$. The graph $\operatorname{Wh}_T(\Lambda^+ \cup \Lambda^-, v)$ has even more edges so it is also connected.

If an edge of T is a loop then subdivide it so that Lemma 3.10 applies. Endow T with the combinatorial metric, i.e. give each edge the length 1. This does not change the Whitehead graphs.

Suppose there exists a Whitehead graph in T which has a cut point. By applying Lemma 3.10 and Remark 3.11, we can construct a sequence

$$..T_n \to T_{n-1} \to \cdots \to T_0 = T$$

where each map $T_i \to T_{i-1}$ is either a collapse or a fold whose restriction to the leaves of both laminations are isometric. The construction of the sequence stops when we find n such that every Whitehead in T_n has no cut vertex.

The maps $T_i \to T_{i-1}$ are in fact not collapses, since a collapsed edge in T_i would not be crossed by any leaf of the lamination, contradicting Proposition 3.9. They are folds.

We want to prove that the sequence above cannot be infinite. By contradiction, assume it is infinite. In [Pap21, Lemma 1.25] we proved that the number of orbits of edges of the trees of the sequence built by iterating Lemma 3.10 has to go to infinity in that case.

The first Betti number $b_1(T_n)$ is constant. Recall that for a connected graph Γ with V vertices and A edges we have $b_1(\Gamma) = A - V + 1$.

Recall that a *big* vertex stabilizer is a vertex stabilizer which does not fix any edge in some (equivalently any) reduced tree. By Lemma 1.1 there is a bound on the number of vertices of valence 1 in T_n/G . In fact, the associated vertex groups are big since trees in \mathcal{D} are minimal. Since there exist finitely many conjugacy classes of big vertex stabilizers, this gives a bound on the number of vertices of valence 1 in T_n/G .

Let A_n, V_n be the number of edges and vertices in T_n/G . For every $v \in T_n$ denote by val(v) the valence of v. Then we have

$$2V_n + 2b_1(\Gamma) - 2 = 2A_n = \sum_{v \in T_n/G} \operatorname{val}(v)$$

Therefore

$$2b_1(\Gamma) - 2 = \sum_{v \in T_n/G} (\operatorname{val}(v) - 2)$$

The only negative terms in the sum correspond to valence 1 vertices so there is a lower bound on their sum. This implies that there is a bound on the number of vertices with valence ≥ 3 .

As a result, since the number of edges in T_n when n goes to infinity is unbounded, the number of vertices of valence 2 in T_n/G is unbounded.

Let $v \in T_n/G$ be a vertex of valence 2. Let l_1, l_2 be the labels at v. If $|l_1| > 1$ and $|l_2| > 1$ then the stabilizers of vertices in the orbit of v are big. Thus the number of vertices of valence 2 with both labels distinct from ± 1 is bounded by m(G). For every other vertex of valence 2, one of the labels is 1 or -1.

A topological edge in T_n/G is a connected component of

$$\Gamma \setminus \{v \in V(\Gamma) / \operatorname{val}(v) \neq 2 \text{ or no label at } v \text{ is } \pm 1\}$$



Figure 6: General form of a topological edge and monotonous subsegments

There is a bound B, independent of n, on the number of topological edges in T_n/G . Since $\operatorname{vol}(T_n/G)$ is unbounded there is no bound on the length of topological edges.

A subsegment $\sigma := e_0, \ldots, e_k$ of a topological edge is *increasing* if for any $i \in \{1, \ldots, k\}$, $G_{o(e_i)} = G_{e_i}$. It is *decreasing* if for any $i \in \{0, \ldots, k-1\}$, $G_{t(e_i)} = G_{e_i}$. A subsegment with a single edge is both increasing and decreasing. This can be understood efficiently with labels: σ is increasing (resp. decreasing) if $\lambda(e_i) = \pm 1$ (resp. $\lambda(\bar{e}_i) = \pm 1$) for all $i \in \{1, \ldots, k\}$.

We will now prove that any topological edge of T_n/G can be cut into at most 2m(G) + 1 subsegments which are either increasing or decreasing. See Figure 6 for an example.

Let $\sigma := e_0, \ldots, e_k$ be a topological edge. Cut it into subsegments by the following process. Let $\sigma_1 := e_0, \ldots, e_{i_1}$ be the maximal decreasing prefix of σ : it has at least one edge. Let σ_2 be the maximal increasing prefix of $\sigma \setminus \sigma_1$. The label $\lambda(\bar{e}_{i_1})$ must be nonzero unless $\sigma_1 = \sigma$, so since σ is a topological edge, $\lambda(e_{i_1+1}) = \pm 1$ so σ_2 also has at least one edge. Continue this procedure to construct an alternating sequence of disjoint decreasing and increasing subsegments.

Write σ as the concatenation $\sigma_1, \ldots, \sigma_N$ of subsegments. We claim that whenever an increasing subsegment is followed by a decreasing subsegment, the last edge of the former has a big stabilizer, and no edge in the latter does. Thus the number of increasing subsegments in σ is bounded by m(G) + 1.

Suppose σ_j is an increasing subsegment followed by a decreasing subsegment σ_{j+1} . Let e_i be the last edge of σ_j . Then by maximality of σ_j , $\lambda(e_{i+1}) \neq \pm 1$. Besides, σ_1 is a decreasing subsegment so there is a decreasing subsegment before σ_j . Let $e_{i'}$ be its last edge. We have i' < i and $\lambda(\bar{e}_{i'}) \neq \pm 1$. For all $p \in \{i'+1,i\}, \lambda(e_p) = \pm 1$ so σ_j is collapsible and collapses to a vertex v with labels $\lambda(e_{i+1})$ on the right, $\prod_{i' \leq p \leq i} \lambda(e_p)$ on the left. Both labels are not ± 1 so the vertex group associated to v is big. It is also the edge group associated to e_i .

For a topological edge of length k, at least one the maximal topological edges is longer than $\frac{k}{2m(G)+2}$. Thus there is no bound on the maximal length of half topological edges when n increases.

Suppose σ is an increasing subsegment of a topological edge with length k in T_n/G . Let us prove that there exists a leaf of Λ^+ and a leaf of Λ^- which overlap along a segment with length k. Let $\pi_n : T_n \to T_n/G$ be the quotient map.

Write σ as the concatenation e_0, \ldots, e_k with $\lambda(e_i) = \pm 1$ for all $i \in \{1, \ldots, k\}$ (see Figure 7). Let $w = t(e_k), v = o(e_0)$.

The subsegment σ lifts in T to a subforest Y_{σ} . Let $\tilde{\sigma}$ be a connected component of $Y_{\sigma} \setminus \pi_n^{-1}(v)$. It is a finite rooted tree with root \tilde{w} which is a lift of w. For every $i \in \{1, \ldots, k\}$, any lift of \tilde{e}_i is an edge of T which points towards \tilde{w} . The terminal vertices of $\tilde{\sigma}$, other than possibly \tilde{w} , are



Figure 7: Pre-image of an increasing subsegment

the lifts of v.

The vertex group $G_{\tilde{w}}$ acts transitively on the set of lifts of v.

Let ℓ be a leaf of Λ^+ . There is a translate of ℓ which crosses a lift of e_k . Thus it contains $[\tilde{v}, \tilde{w}]$ where \tilde{v} is a lift of v. By transitivity of the action of $G_{\tilde{w}}$, for every $\tilde{v}' \in \pi_n^{-1}(v)$, the segment $[\tilde{v}', \tilde{w}]$ is contained in a leaf of Λ^+ .

Similarly, if ℓ_{-} is a leaf of Λ^{-} , there exists a translate of ℓ_{-} crossing \tilde{e}_{k} and by translating further by an element of $G_{\tilde{w}}$ we can make sure that it crosses $[\tilde{v}', \tilde{w}]$ for any arbitrary $\tilde{v}' \in \pi_{n}^{-1}(v)$. Then the translates of ℓ and ℓ_{-} overlap on a length at least k.

The same proof can be transposed to the case of a decreasing subsegment.

Since there is no bound on the length of monotonous subsegments, for every L > 0 there exists $n \in \mathbb{N}$ such that T_n contains an increasing or decreasing subsegment σ longer than L. Let $\tilde{\sigma}$ be a lift for σ in T_n . There exist leaves ℓ^+, ℓ^- of the stable and unstable laminations which both cross $\tilde{\sigma}$. Therefore the leaves ℓ^+ and ℓ^- overlap on a length bigger than L.

The maps $T_n \to T$ for $n \in \mathbb{N}$ are isometric in restriction to the leaves of the laminations. Thus there is no bound on the length of common subsegments of both laminations in T, so by Lemma 2.8 the laminations are equal. This is a contradiction to Lemma 2.11.

Proposition 3.13. Let $\phi \in \text{Out}(G)$ be a train track automorphism. Let $f : T \to T$ be a train track representative for ϕ . Let \mathcal{L}_f be an axis for ϕ in \mathcal{D} passing through T. There exists L > 0 such that for any $T_t \in \mathcal{L}_f$:

- (i) If g is a simple loxodromic element in G, then $\operatorname{Axe}_{T_t}(g)$ cannot simultaneously contain an L-piece of Λ^+ and an L-piece of Λ^- .
- (ii) If g, h are simple loxodromic elements such that $\operatorname{Axe}_{T_t}(g)$ contains an L-piece of Λ^+ and $\operatorname{Axe}_{T_t}(h)$ contains an L-piece of Λ^- , then the pair $\{g,h\}$ is not simple.

Proof. Let S be a tree obtained with Proposition 3.12, i.e. such that for every $v \in V(S)$ the Whitehead graph $Wh_S(\Lambda^+ \cup \Lambda^-, v)$ is connected without cut vertex. Note that for any $n \in \mathbb{Z}$, $S \cdot \phi^n$ has the same property since Λ^+, Λ^- are ϕ -invariant.

By quasi-periodicity of leaves, there exists a constant $L_1 > 0$ such that any leaf segment of Λ^+ in S (resp. Λ^-) longer than L_1 contains all turns in Λ^+ (resp. Λ^-). Suppose $\operatorname{Axe}_S(g)$ contains an L_1 -piece of Λ^+ and an L_1 -piece of Λ^- , then $\operatorname{Wh}_S(g, v)$ is connected without cut vertex for all $v \in V(S)$. By theorem 3.8 g is not simple. This proves assertion (i) in the specific case where the tree is S: now we would like to prove it for T_t in the axis of ϕ .

By Remark 1.28 there exist constants K > 1, C > 0 such that for every $t \in [0, \log(\lambda)]$ there exists a *G*-equivariant (K, C)-quasi-isometry $h_t : T_t \to S$. There is an upper bound $B \ge 0$, depending only on (K, C), on BBT (h_t) .

Let L_0 be the constant of Lemma 2.9 for the quasi-isometry constants K, C and $\ell = L_1 + 2B$. If a fundamental domain γ of g in T_t contains a leaf segment σ with $\text{len}(\sigma) \geq L_0$ then $[h_t(\gamma)]$ contains a leaf segment with length at least $L_1 + 2B$, and a fundamental domain of g in S contains an L_1 -piece of the lamination. This works for both laminations.

Let $L > \max\{L_0, 2KL_1\}$. Suppose $\operatorname{Axe}_{T_l}(g)$ contains leaf segments σ_+, σ_- of the stable and unstable laminations, both longer than L. Up to replacing g with g^l for some $l \in \mathbb{N}$ we can suppose a fundamental domain for g contains both σ_+ and σ_- . Lemma 2.9 ensures that $\operatorname{Axe}_S(g)$ contains L_1 -pieces of both laminations, therefore implying that g^l hence g is not simple.

Finally suppose $t \notin [0, \log(\lambda)]$. There exists $n \in \mathbb{Z}$ such that $T_{t'} := T_t \cdot \phi^n$ with $t' = t + n \log(\lambda) \in [0, \log(\lambda)]$. Then $h_{t'} : T_{t'} \to S$ induces a *G*-equivariant (K, C)-quasi-isometry $T_t \to S \cdot \phi^{-n}$. With the same arguments as above we come to the same result, with the same constant *L*. This proves (i).

The proof of (ii) is analogous. We just proved that there exists L > 0, such that for $T_t \in \mathcal{L}_f$ there exists n such that for any $g \in G$, if $\operatorname{Axe}_{T_t}(g)$ contains an L-piece of any lamination then $\operatorname{Axe}_{S \cdot \phi^n}(g)$ contains an L_0 -piece of the same lamination. Applying this to g with the stable lamination and h with the unstable lamination, we get that $\operatorname{Wh}_{S \cdot \phi^n}(\{g, h\}, v)$ is connected without cut vertex for any $v \in V(S)$ and therefore $\{g, h\}$ is not simple. \Box

4 Legality

Let G be a GBS group with first Betti number $b_1(G) \ge 3$.

In this section we fix a pseudo-atoroidal fully irreducible automorphism $\phi \in \text{Out}(G)$ with a train track representative $f: T \to T$ and a train track representative $f_-: T_- \to T_-$ for ϕ^{-1} . The goal is to study the evolution of $\|\phi^n(g)\|_{T_-} \|\phi^n(g)\|_{T_-}$ when $n \to \pm \infty$ for $g \in G$.

The following three lemmas prove an analogue of Lemmas 2.9 and 2.10 in [BFH97]. The point of view differs a little since we state the results in the trees and not in the quotient graphs. A notable difference which is caused by non-trivial edge stabilizers is the fact that a concatenation of pINPs is not always a Nielsen path, since it might only be pre-periodic. The statements also differ a little for technical reasons.

Lemma 4.1. Let $\phi \in \operatorname{Aut}(G)$ be an automorphism with a train track representative $f: T \to T$. For every C > 0 there exists $M \in \mathbb{N}$ such that for any edge path $\sigma \subset T$, one of the following holds:

- (a) $[f^M(\sigma)]$ is legal
- (b) $[f^M(\sigma)]$ contains a legal segment of length $\geq C$ between two illegal turns

- (c) $[f^M(\sigma)]$ has fewer illegal turns than σ
- (d) σ is a concatenation $\eta_0 \cdot \eta_1 \cdots \eta_{k+1}$ for some $k \ge 1$ where η_0, η_{k+1} are legal subpaths, and for $1 \le i \le k$ the path $f^M(\eta_i)$ is a periodic indivisible Nielsen path, and turns at the concatenation points are legal.

Proof. Without loss of generality we may assume $C > C_f$. Then if $\sigma := [y, y']$ contains a legal path with length C then for any $n \in \mathbb{N}$, $[f^n(\sigma)]$ also does, by definition of the critical constant.

Let $M \in \mathbb{N}$ be a big enough integer, to be determined later. Suppose there exists a path $\sigma \subset T$ such that both (a), (b) and (c) fail. Since $[f^M(\sigma)]$ cannot have more illegal turns than σ , it has exactly the same number of illegal turns $k \geq 1$. There exist maximal legal subsegments $\gamma_0, \ldots, \gamma_k$ such that σ is the concatenation $\gamma_0 \cdots \gamma_k$. Since (a) fails we have $\operatorname{len}(\gamma_i) \leq C$ for every $i \in \{1, \ldots, k-1\}$.

The map f maps legal segments to legal segments and since the number of illegal turns is constant, for every $n \leq M$, there is a unique decomposition $[f^n(\sigma)] = \gamma_0^n \cdot \gamma_1^n \cdots \gamma_k^n$ into maximal legal subsegments. We have $\operatorname{len}(\gamma_i^n) \leq C_f$ for all $i \in \{1, \ldots, k-1\}$.

There are finitely many orbits of edge paths of T with length at most $2C_f$. Let N be the number of orbits of such subpaths.

Let
$$i \in \{2, \dots, k-1\}$$
. There exists $p_i \leq N$ and $g_i \in G$ such that $\gamma_{i-1}^N \cdot \gamma_i^N = g_i \left(\gamma_{i-1}^{N+p_i} \cdot \gamma_i^{N+p_i}\right)$.

There also exists $p_1 \leq N$ and $g_1 \in G$ such that the restrictions of $\gamma_0^N \cdot \gamma_1^N$ and $g_1\left(\gamma_0^{N+p_1} \cdot \gamma_1^{N+p_1}\right)$ to a $2C_f$ -neighbourhood of the illegal turn are equal. Similarly define $p_k \in \mathbb{N}, g_k \in G$ such that restrictions of $\gamma_{k-1}^N \cdot \gamma_k^N$ and $g_k\left(\gamma_{k-1}^{N+p_k} \cdot \gamma_k^{N+p_k}\right)$ coincide.

By taking the smallest common multiple of all p_i for $i \in \{1, ..., k\}$ we may replace p_i by some $P \in \mathbb{N}$ which does not depend on i.

Thus for every $i \in \{2, \ldots, k-1\}$, we have $\gamma_{i-1}^N \cdot \gamma_i^N \subset g_i[f^P(\gamma_{i-1}^N \cdot \gamma_i^N)]$. The same holds for restrictions to a $2C_f$ -neighbourhood of the illegal turn for $i \in \{1, k\}$. Note that this implies that there exists no $n \in \mathbb{N}$ such that γ_0^n or γ_k^n vanish.

there exists no $n \in \mathbb{N}$ such that γ_0^n or γ_k^n vanish. For any $i \in \{1, \ldots, k\}$ the path γ_i^n contains a unique point x_i such that $x_i = g_i f^P(x_i)$, and γ_0^N contains a unique point x_0 such that $x_0 = g_1 f^P(x_0)$. The point x_0 might be equal to y, x_k might be equal to y'. Note that $g_i \gamma_i^{N+P} = g_{i+1} \gamma_i^{N+P} = \gamma_i^N$ so for $i \in \{0, \ldots, k-1\}$ actually $g_{i+1} f^P(x_i) = g_i f^P(x_i) = x_i$. Then for any $i \in \{1, \ldots, k\}$ the path $[x_{i-1}, x_i]$ is a periodic indivisible Nielsen path.

For any $i \in \{0, ..., k\}$ there exists a unique point $y_i \in \sigma$ such that $f^N(y_i) = x_i$. The points $y_0, ..., y_k$ subdivide σ into k+2 subsegments. Define $\eta_i = [y_i, y_{i+1}]$ for $i \notin \{0, k+1\}, \eta_0 = [y, y_0]$ and $\eta_{k+1} = [y_k, y']$: we just proved that η_i is a pre-Nielsen path for $1 \leq i \leq k$. The other subpaths η_0 and η_{k+1} are legal, and the other subpaths are pre-Nielsen paths, so σ satisfies (d).

The integers N and P only depend on T. If $M \ge N + P$ we proved that for any path σ such that (a), (b) and (c) fail, (d) holds.

The following result, which is a key for Lemma 4.3, implies that when neither Case (a), Case (b) nor Case (d) of Lemma 4.1 occur, the decrease of the number of illegal turns is a definite proportion of the length of the segment.

Lemma 4.2. Let $\phi \in \operatorname{Aut}(G)$ with a train track representative $f: T \to T$. Let $C > C_f$. Let $M_0 \ge 1$ be the corresponding integer given by Lemma 4.1. There exists $p \in \mathbb{N}$ with the following property. Let $M := pM_0$. There exists K < 1 and $K' \ge 0$ such that for any loxodromic $g \in G$, for any $\sigma \subset \operatorname{Axe}_T(g)$, there exists segments α, β, σ' such that $[f^M(\sigma)] = \alpha \cdot \sigma' \cdot \beta$ with

• $\operatorname{len}(\alpha) \le K'/2, \operatorname{len}(\beta) \le K'/2$

- $\sigma' \subset \operatorname{Axe}_T(\phi^M(g))$ or $\operatorname{len}(\sigma') = 0$
- either σ' contains a legal subsegment with length greater than C, or

$$\operatorname{len}(\sigma') \le K \operatorname{len}(\sigma) + K$$

Moreover, if σ contains a legal subsegment longer than C, then so does σ' .

Proof. Let $C > C_f$. Let $g \in G$ and $\sigma \subset \operatorname{Axe}_T(g)$. Let M_0 be the constant of Lemma 4.1 for C.

Let $m \in \mathbb{N}$ be the maximal number of pINPs which may be concatenated in T or T_{-} , from Lemma 1.18.

If $\operatorname{len}([f^{M_0}(\sigma)]) \leq K'_0 := 2 \operatorname{BBT}(f^{M_0}) + 2mC$, then define $\alpha := [f^{M_0}(\sigma)]$, and σ' and β as single points such that $[f^{M_0}(\sigma)] = \alpha \cdot \sigma' \cdot \beta$. These subsegments satisfy the statement for any choice of p, with $\operatorname{len}(\sigma') = 0$.

Suppose $\operatorname{len}([f^{M_0}(\sigma)]) > K'_0$. Define $\sigma_0 := [f^{M_0}(\sigma)] \cap \operatorname{Axe}_T(g)$, which is not empty, and let α_0, β_0 be the remaining subsegments. Note that if σ contains a legal subsegment θ with length greater than $C > C_f$, then $[f^{iM_0}(\sigma) \cap \operatorname{Axe}_T(\phi^{iM_0}(g)) \cap f^{iM_0}(\theta)]$ is longer than C for all $i \ge 1$, hence the last statement.

Let $nbl(\theta)$ denote the number of maximal legal subsegments in a segment θ . We will now prove that if σ_0 contains no legal subsegment longer than C, then its number of maximal legal subsegments $nbl(\sigma)$ decreases.

Write $\sigma := \theta_0 \cdot \theta_1 \cdot \cdots \cdot \theta_n$ where each subsegment θ_i except θ_0 has m + 2 maximal legal subsegments. Let $i \in \{1, \ldots, n\}$. Apply Lemma 4.1 to θ_i . Case (d) cannot happen since θ_i has m + 1 illegal turns. If Case (a) happens then Case (c) also happens: $\operatorname{nbl}([f^{M_0}(\theta_i)]) < \operatorname{nbl}(\theta_i) = m + 1$. Suppose Case (b) happens: either $[f^{M_0}(\theta_i)] \cap \operatorname{Axe}_T(\phi^{M_0}(g))$ contains a legal subsegment with length C, or an illegal turn of θ_i is sent outside $\operatorname{Axe}_T(\phi^{M_0}(g))$, in which case $\operatorname{nbl}([f^{M_0}(\theta_i)] \cap \operatorname{Axe}_T(\phi^{M_0}(g))) < \operatorname{nbl}(\theta_i)$.

Thus if σ_0 does not contain any legal subsegment longer than C, then

$$\begin{aligned} \operatorname{nbl}(\sigma_0) &\leq \operatorname{nbl}(\theta_0) + \operatorname{nbl}([f^{M_0}(\theta_1)] \cap \operatorname{Axe}_T(\phi^{M_0}(g))) + \dots + \operatorname{nbl}([f^{M_0}(\theta_n)] \cap \operatorname{Axe}_T(\phi^{M_0}(g))) \\ &\leq \operatorname{nbl}(\theta_0) + (\operatorname{nbl}(\theta_1) - 1) + \dots + (\operatorname{nbl}(\theta_n) - 1) \\ &\leq \operatorname{nbl}(\sigma) - n \end{aligned}$$

where $n = \left\lfloor \frac{\operatorname{nbl}(\sigma)}{m+1} \right\rfloor$. Therefore, with $k := (1 - \frac{1}{m+1})$, we obtain

 $\operatorname{nbl}(\sigma_0) \le k \operatorname{nbl}(\sigma)$

This can be iterated as long as $[f^{iM_0}(\sigma)] \cap \operatorname{Axe}_T(\phi^{iM_0}(g))$ contains no legal subsegment of length C by applying the same argument to σ_1 instead of σ , creating a decreasing subsequence $\sigma_1, \sigma_2, \ldots$ of σ and increasing sequences $\alpha_1, \alpha_2, \ldots$ and β_1, β_2, \ldots Then for $p \geq 1$, $[f^{pM_0}(\sigma)]$ can be cut into subsegments $\alpha_p \cdot \sigma_p \cdot \beta_p$ with

- $\operatorname{len}(\alpha_p), \operatorname{len}(\beta_p) \le K'_0 \sum_{i=0}^{p-1} \lambda^i =: K'_p$
- $\sigma_p \subset \operatorname{Axe}_T(\phi^{pM_0}(g))$
- $\operatorname{nbl}(\sigma_p) \le k^p \operatorname{nbl}(\sigma)$

Now convert this result into lengths: we obtain

$$\operatorname{len}(\sigma_p) \le \frac{Ck^p}{l_{\min}} \operatorname{len}(\sigma)$$

where $l_{\min} := \min_{e \in E(t)} \operatorname{len}(e)$. Choose p such that $\frac{Ck^p}{l_{\min}} < 1$. Let $K := \frac{Ck^p}{l_{\min}}$ and $K' := K'_p$. Finally we get

$$\operatorname{len}(\sigma) \le K \operatorname{len}(\sigma) + K'$$

thus we obtain the lemma with $\alpha := \alpha_p, \beta := \beta_p, \sigma' := \sigma_p$.

Lemma 4.3. Recall that ϕ is pseudo-atoroidal. Let $h: T \to T_-$ be a Lipschitz G-equivariant map, sending vertex to vertex, and edge to edge path.

For every C > 0 there exists $N \in \mathbb{N}$ and L > 0 such that for any $g \in G$, for any geodesic $\sigma \subset \operatorname{Axe}_T(g)$ with length greater than L and possibly infinite, if $\sigma' := [h(\sigma)]$, then one of the followings holds:

(A) $[f^N(\sigma)] \cap \operatorname{Axe}_T(\phi^N(g))$ contains a legal segment of length > C

(B) $[f_{-}^{N}(\sigma')] \cap \operatorname{Axe}_{T}(\phi^{-N}(q))$ contains a legal segment of length > C.

Proof. Let M be the constant from Lemma 4.2. Assume

$$C \ge \max\left\{C_f, C_{f_-}\right\}$$

We will suppose by contradiction that the lemma fails for N := Mi with i sufficiently big. We will take a segment σ in T for which both (A) and (B) fail, and show that this assumption leads to a contradiction in the following sense. For $j \in \{0, \ldots, i\}$ the segment $[f^{Mj}(\sigma)]$ can be cut into three segments: one in the axis of ϕ^{Mj} and two "error" parts outside of the axis. Using the fact that (A) fails, we see that the part in the axis must not contain any long legal subsegment, thus its length can be estimated by counting the number of maximal legal subsegments in it. Lemma 4.2 controls the decrease of the number of maximal legal subsegments in σ up to error parts.

However the error parts may grow, for two reasons: they are stretched by f^M and the inner part produces small errors too, which add to the previous error. The aim of the proof is to take σ long enough to keep the growth of these error parts small in comparison with the decrease of the inner part, so that the overall effect of f^{Mi} on σ is a decrease. Then we apply the reverse: we look at the evolution of $f_{-}^{Mj} \circ h \circ f^{Mi}(\sigma)$ for $j \in \{0, \ldots, i\}$.

Now the argument for the absence of long legal subsegments in the inner part is the fact that (B) fails, and the conclusion is similar: the overall length of the segment decreases. As a result $[f_{-}^{Mi} \circ h \circ f^{Mi}(\sigma)]$ is a lot shorter than σ in proportion.

The contradiction comes from Lemma 2.1: the maps h and $f_{-}^{Mi} \circ h \circ f^{Mi}$ are equal up to a bounded error, so when σ is long enough, it cannot decrease much in proportion when applying $f_{-}^{Mi} \circ h \circ f^{Mi}.$

We now write a formal argument along these lines.

Let $i \in \mathbb{N}$; set N := Mi. Let σ be a segment in $\operatorname{Axe}_{\mathcal{T}}(q)$.

By Lemma 2.1, there exists a constant B_i such that for any $x \in T$, $d_T(h(x), f_{-}^{M_i} \circ h \circ$ $f^{Mi}(x) \leq B_i$. There exists a constant $L_{1,i}$ depending on B_i and h such that if $len(\sigma) > L_{1,i}$ then $\operatorname{len}([h(\sigma)]) > 4B_i$ so

$$\frac{\operatorname{len}([f_{-}^{Mj} \circ h \circ f^{Mi}(\sigma)])}{\operatorname{len}(\sigma)} > \frac{1}{2}$$

$$(1)$$

Moreover there exists $D_i \geq 0$ depending on f, f_-, h, i such that for any $\sigma \subset \operatorname{Axe}_T(g)$, for any segment $\theta \subset \sigma$ at distance greater than D_i from the endpoints of σ , $[f_-^{M_i} \circ h \circ f^{M_i}(\theta)] \cap \operatorname{Axe}_T(g) \subset [h(\sigma)] \cap \operatorname{Axe}_T(g)$. Let $\tilde{\sigma}$ be the subsegment of σ obtained by cutting out a D_i -neighbourhood of the endpoints.

Suppose that both (A) and (B) fail for σ and for N = Mi.

Since (A) fails for σ , no segment $[f^{M_j}(\sigma)] \cap \operatorname{Axe}_T(\phi^{M_j}(g))$ for $j \in \{0, \ldots, i\}$ can contain a legal subsegment longer than C. By Lemma 4.2 there exist constants $K < 1, K' \ge 0$ and a decomposition $[f^M(\sigma)] = \alpha_1 \cdot \sigma_1 \cdot \beta_1$ such that

$$\operatorname{len}(\sigma_1) \le K \operatorname{len}(\sigma) + K'$$

Define by induction $\alpha_j \cdot \sigma_j \cdot \beta_j = [f^M(\sigma_{j-1})]$ using Lemma 4.2. For all $j \in \{1, \ldots, i\}$ we have

$$\operatorname{len}(\sigma_j) \le K \operatorname{len}(\sigma_{j-1}) + K'$$

and $\operatorname{len}(\alpha_j), \operatorname{len}(\beta_j) \leq K'/2$ so

$$\operatorname{len}([f^M(\sigma_{j-1})]) \le K \operatorname{len}(\sigma_{j-1}) + K' + 2\lambda^M \frac{K'}{2}$$

where $\lambda := \operatorname{Lip}(f)$. Thus we have

$$\ln([f^{Mi}(\sigma)]) \le K^{i} \ln(\sigma) + K'(1+\lambda^{M}) \sum_{j=0}^{i-1} K^{j} \le K^{i} \ln(\sigma) + \frac{K'(1+\lambda^{M})}{1-K}$$

Remember that $\tilde{\sigma}$ be the subpath obtained from σ by cutting out the D_i -neighbourhood of the endpoints. Let $\sigma'_j := [f^{Mj}_{-} \circ h \circ f^{Mi}(\tilde{\sigma})] \cap \operatorname{Axe}_{T_-}(\phi^{M(i-j)}(g))$ for $j \in \{0, \ldots, i\}$: it cannot contain legal subsegments longer than C. Indeed $[f^{Mi}_{-} \circ h \circ f^{Mi}(\tilde{\sigma})] \cap \operatorname{Axe}_T(g) \subset [h(\sigma)] \cap \operatorname{Axe}_T(g)$ and by assumption that (B) fails, the latter does not contain any legal subsegments longer than C.

Applying the same argument as above using Lemma 4.2 with f_- , C, we obtain again K_-, K'_- such that

$$\operatorname{len}([f_-^{Mi} \circ h \circ f^{Mi}(\tilde{\sigma})]) \leq K_-^i \operatorname{len}([h \circ f^{Mi}(\tilde{\sigma})]) + \frac{K_-'(1 + \lambda_-^M)}{1 - K_-}$$

with $\lambda_{-} := \operatorname{Lip}(f_{-})$. By combining both inequalities, using the fact that h is Lipschitz:

$$\begin{aligned} &\ln([f_{-}^{Mi} \circ h \circ f^{Mi}(\tilde{\sigma})]) \leq \operatorname{Lip}(h) K_{-}^{i} \ln([f^{Mi}(\tilde{\sigma})]) + \frac{K_{-}^{\prime}(1+\lambda_{-}^{M})}{1-K_{-}} \\ &\leq \operatorname{Lip}(h) K_{-}^{i} \ln([f^{Mi}(\sigma)]) + 2\operatorname{Lip}(h) K_{-}^{i} D_{i} \operatorname{Lip}(f^{M})^{i} + \frac{K_{-}^{\prime}(1+\lambda_{-}^{M})}{1-K_{-}} \\ &\leq \operatorname{Lip}(h) (K_{-}K)^{i} \ln(\sigma) + \operatorname{Lip}(h) K_{-}^{i} \left(\frac{K^{\prime}(1+\lambda_{-}^{M})}{1-K_{-}} + 2D_{i} \operatorname{Lip}(f^{M})^{i}\right) \\ &+ \frac{K_{-}^{\prime}}{1-K_{-}} \end{aligned}$$

 \mathbf{so}

$$\operatorname{len}([f_{-}^{Mi} \circ h \circ f^{Mi}(\sigma)]) \leq \operatorname{Lip}(h)(K_{-}K)^{i}\operatorname{len}(\sigma) + S_{i}$$

where S_i is an additive constant depending on i.

Now assume that i is big enough so that $Lip(h)(K_K)^i < 1/4$. Note that the choice of i does not depend on σ but only on the maps f^M, f^M_-, h and on C. Then there exists a constant $L_{2,i} \geq 0$ such that if σ is longer than $L_{2,i}$ then

$$\frac{\operatorname{len}([f_{-}^{Mi} \circ h \circ f^{Mi}(\sigma)])}{\operatorname{len}(\sigma)} \le \frac{1}{2}$$

$$(2)$$

If σ is longer than $L := \max\{L_{1,i}, L_{2,i}\}$ then inequations 1 and 2 contradict each other. This achieves the proof.

Corollary 4.4. For every C > 0 there exists $N \in \mathbb{N}$ such that for every $q \in G$ one of the followings holds:

- (A) $\operatorname{Axe}_T(\phi^N(g))$ contains a legal segment of length > C
- (B) Axe_T ($\phi^{-N}(q)$) contains a legal segment of length > C.

Proof. It suffices to apply Lemma 4.3 to a long enough subsegment $\sigma \subset \operatorname{Axe}_T(g)$.

In the rest of the section, our aim will be to prove that if $g \in G$ then $\operatorname{Axe}_{T \cdot \phi^n(g)}(g)$ has increasingly long legal subsegments. This is a key step in the definition of the projection $\mathcal{D} \to \mathcal{L}_f$.

As in [Alg11] we define the legality threshold and the legality of a path in T:

Definition 4.5. Let $\kappa := \frac{4 \operatorname{BBT}(f)}{\lambda - 1} = 2C_f$ be the *legality threshold*. For every finite path $\alpha \subset T$ we define the *legality ratio* of α with respect to the train track structure as follows. Let $\alpha_1, \ldots, \alpha_k$ be the maximal legal subsegments of α . Then the legality of α is

$$\operatorname{Leg}_{f}(\alpha, T) := \frac{\sum_{\operatorname{len}(\alpha_{i}) \ge \kappa} \operatorname{len}(\alpha_{i})}{\operatorname{len}(\alpha)}$$

which is the proportion of α which belongs to a legal subpath longer than κ .

If g is a loxodromic element of G, then we distinguish two cases:

- g is legal and we define $\text{Leg}_f(g,T) = 1$
- there exists a fundamental domain α for g which starts and ends at an illegal turn of the axis. Then $\operatorname{Leg}_f(g,T) = \operatorname{Leg}_f(\alpha,T)$.
- Remarks 4.6. • If α is a fundamental domain of g which does not start and end at an illegal turn while $\operatorname{Axe}_T(g)$ contains one, then $\operatorname{Leg}_f(\alpha) \leq \operatorname{Leg}_f(g)$.
 - If $(\alpha_n)_{n \in \mathbb{N}}$ is a sequence of nested subsegments of $\operatorname{Axe}_T(g)$ whose length goes to infinity then $\operatorname{Leg}_f(g,T) = \lim_{n \to \infty} \operatorname{Leg}_f(\alpha,T).$
 - For $l \in \mathbb{Z} \setminus \{0\}$ we have $\operatorname{Leg}_f(g^l, T) = \operatorname{Leg}_f(g, T)$.
 - To define $\operatorname{Leg}_{f_-}(g, T_-)$ we use the threshold $\kappa_- := 2C_{f_-}$.

The following result states that if α contains sufficiently many long legal subsegments, then the length of $f^n(\alpha)$ grows exponentially, as though α were legal.

Lemma 4.7. Let $\varepsilon > 0$. There exists a constant $C(\varepsilon)$ such that for every finite path α in T such that $\operatorname{Leg}_f(\alpha, T) \geq \varepsilon$, for every $n \in \mathbb{N}$ we have $\operatorname{len}([f^n(\alpha)]) \geq C(\varepsilon)\lambda^n \operatorname{len}(\alpha)$.

Proof. Since $\text{Leg}_f(\alpha, T) \geq \varepsilon$, α contains at least one legal subsegment of length greater than κ . Let β_1, \ldots, β_k be the maximal legal subsegments of α longer than κ . For every $i \in \{1, \ldots, k\}$ let θ_i be the subsegment of β_i obtained by cutting out the $\frac{C_f}{2}$ -neighbourhood of the endpoints. By Lemma 1.13 the images of $\theta_1, \ldots, \theta_k$ by f^n are disjoint for any $n \in \mathbb{N}$ and contained in $[f^n(\alpha)]$. Moreover for every $i \in \{1, \ldots, k\}$, $\operatorname{len}(\theta_i) \geq \frac{1}{2} \operatorname{len}(\beta_i)$. Since $\kappa = 2C_f$ we have

$$\operatorname{len}([f^{n}(\alpha)]) \geq \sum_{i=1}^{k} \operatorname{len}(f^{n}(\theta_{i}))$$
$$\geq \lambda^{n} \sum_{i=1}^{k} \operatorname{len}(\theta_{i})$$
$$\geq \frac{1}{2} \lambda^{n} \sum_{i=1}^{k} \operatorname{len}(\beta_{i})$$
$$\geq \frac{1}{2} \lambda^{n} \varepsilon \operatorname{len}(\alpha)$$

Therefore we obtain the desired result, with $C(\varepsilon) = \varepsilon/2$.

Corollary 4.8. Let $\varepsilon > 0$. There exists a constant $C(\varepsilon)$ such that for every loxodromic $g \in G$ such that $\operatorname{Leg}_{f}(g,T) \geq \varepsilon$, for every $n \in \mathbb{N}$ we have $\|\phi^{n}(g)\|_{T} \geq C(\varepsilon)\lambda^{n}\|\phi^{n}(g)\|$.

Proof. Let $\varepsilon > 0$. Let $g \in G$. There exists $x \in \operatorname{Axe}_T(g)$ such that $\operatorname{Leg}_f([x, gx], T) = \operatorname{Leg}_f(g, T) \ge$ ε . By Lemma 4.7, for any $k \in \mathbb{N}$ we have $d_T(f^n(x), \phi^n(g^k)f^n(x)) \geq C(\varepsilon)\lambda^n d_T(x, g^k x)$.

Thus

$$\begin{split} \|\phi^{n}(g)\|_{T} &= \inf_{k \in \mathbb{N}} \frac{d_{T}(f^{n}(x), \phi^{n}(g^{k})f^{n}(x))}{k} \\ &\geq C(\varepsilon)\lambda^{n}\frac{d_{T}(x, g^{k}x)}{k} \\ &= C(\varepsilon)\lambda^{n}\|g\|_{T} \end{split}$$

Lemmas 4.9 and 4.11 aim to prove basic properties which can be deduced from Lemma 4.7. Together they prove that the legality function $n \mapsto \text{Leg}_f(\phi^n(g), T)$ cannot be greater than ε in a neighbourhood of $-\infty$. They are illustrated by Figure 8.

Lemma 4.9. For any $\varepsilon > 0$ there exists $M \in \mathbb{N}$ such that for any $g \in G$ such that $\text{Leg}_f(g) \geq \varepsilon$, for any $m \ge M$, $\|\phi^m(g)\|_T > \|g\|_T$.

Proof. By applying Lemma 4.7 to a fundamental domain for g starting at a legal turn, there exists $C(\varepsilon)$ such that for all $m \in \mathbb{N}$

$$\|\phi^m(g)\|_T \ge C(\varepsilon)\lambda^m \|g\|_T$$

so with $M \geq -\frac{\log C}{\log \lambda}$ we get the lemma.

Remark 4.10. Similarly there exists M_{-} such that if $\operatorname{Leg}_{f_{-}}(g) \geq \varepsilon$ then for any $m \geq M_{-}$, $\|\phi^{-m}(g)\|_{T_{-}} > \|g\|_{T_{-}}.$



Figure 8: If $\operatorname{Leg}_f(g,T) \ge \varepsilon_0$ then $\|\phi^n(g)\|_T$ is above the red graph. If $\operatorname{Leg}_f(\phi^{-m}(g),T) \ge \varepsilon_0$ then $\|g\|_T$ must be above the green graph, so if *m* is big then $\|\phi^{-m}(g)\|_T$ is small.

Lemma 4.11. For any loxodromic $g \in G$ there exists $m_g \in \mathbb{N}$ such that for any $m \geq m_g$, $\text{Leg}_f(\phi^{-m}(g)) < \varepsilon$.

Proof. Suppose $\operatorname{Leg}_f(\phi^{-m}(g)) \geq \varepsilon$ for some $m \in \mathbb{N}$ and $\varepsilon > 0$. By applying Corollary 4.8 to $\phi^{-m}(g)$, there exists $C(\varepsilon)$ such that $\|g\|_T \geq C(\varepsilon)\lambda^m \|\phi^{-m}(g)\|_T$. Let l_e be the length of the shortest edge in T, then $\|\phi^{-m}(g)\|_T \geq l_e$ so

$$m \le \frac{\log(\|g\|_T) - \log C - \log l_e}{\log \lambda}.$$

Corollary 4.4 proves that for any g in G, either $\phi^N(g)$ has a f-legal segment of length C, either $\phi^{-N}(g)$ has an f_- -legal segment of length C, where the integer N does not depend on gat all. A crucial point is Lemma 4.12, i.e. that such a result also works with the legality ratio, i.e. up to choosing a greater N, either the legality ratio of $\phi^N(g)$ in T or the legality ratio of $\phi^{-N}(g)$ in T_- is greater than a definite ε_0 . Combined with Lemma 4.7 we will then be able to prove that len(g) grows exponentially when $n \to \pm \infty$, and has a minimum in a bounded subset of \mathcal{L}_f .

The following lemma needs the fact that ϕ is pseudo-atoroidal since it relies on Lemma 1.18 through Corollary 4.4. It is proved for the free group case in [BFH97].

Lemma 4.12. There exists $\varepsilon_0 > 0$ and $N \in \mathbb{N}$ such that for every loxodromic element $g \in G$, one of the followings holds:

- $\operatorname{Leg}_f(\phi^N(g), T) > \varepsilon_0$
- Leg_f $(\phi^{-N}(g), T_{-}) > \varepsilon_0$

Proof. Fix a G-equivariant quasi-isometry $h: T \to T_-$. Recall that for a G-equivariant quasiisometry between G-trees $u: T_1 \to T_2$, such as h, f, f_- and their products, if a segment σ is



Figure 9: The axis of g in T is cut into subsegments θ_i separated by subsegments longer than K_N .

contained in the axis of an element g in T_1 , then $[u(\sigma)]$ is contained in the axis of g in T_2 apart from a BBT(u)-neighbourhood of its endpoints.

Let $C := \max\{2C_f, 2C_{f_-}\}$. Let L, N be the constants given by Lemma 4.3.

There exists a constant K_N depending on L and the quasi-isometry constants for f, f_- such that for any points $x, y \in T$, $f^N(x) = f^N(y) \Rightarrow d_T(x, y) \leq K_N$ and $f_-^N \circ h(x) = f_-^N \circ h(y) \Rightarrow d_T(x, y) \leq K_N$.

Observe that for any subsegment $\sigma \subset \operatorname{Axe}_T(g)$ of length at least K_N , there exists $x \in \sigma$ such that $f^N(x) \in \operatorname{Axe}_T(\phi^N(g))$ and $x_- \in \sigma$ such that $f^N_- \circ h(x_-) \in \operatorname{Axe}_T_-(\phi^{-N}(g))$.

The axis of g in T can be cut into subsegments $\theta_i, i \in \mathbb{Z}$ of length L separated by other subsegments of length K_N (see Figure 9).

By the choice of K_N , for any $i \in \mathbb{Z}$, $[f^N(\theta_i)] \cap [f^N(\theta_{i+1})] = \emptyset$ and $[f^N_- \circ h(\theta_i)] \cap [f^N_- \circ h(\theta_{i+1})] = \emptyset$.

There exists a power g^l such that $2L + 3K_N < ||g^l||_T$. Let $k := \lfloor \frac{||g^l||_T - K_N}{L + K_N} \rfloor$. There exists a fundamental domain α for g^l in Axe_T(g) which contains at least k consecutive $\theta_i, \theta_{i+1}, \ldots, \theta_{i+k-1}$ of the segments defined above, and at distance at least K_N from its endpoints.

Let $\alpha_N \subset T$ be a fundamental domain for $\phi^N(g^l)$ contained in $[f^N(\alpha)]$, and let $\alpha_{-N} \subset T_-$ be a fundamental domain for $\phi^{-N}(g^l)$ contained in $[f_-^N \circ h(\alpha)]$. Since there is a K_N -margin between θ_i, θ_{i+k-1} and the endpoints of α , for every $j \in \{i, \ldots, i+k-1\}$ we have $[f^N(\theta_j)] \cap \operatorname{Axe}_T(\phi^N(g)) \subset \alpha_N$ and $[f_-^N(\theta_j)] \cap \operatorname{Axe}_T(\phi^{-N}(g)) \subset \alpha_{-N}$.

By Lemma 4.3, for each $j \in \mathbb{Z}$, either $[f^N(\theta_j)] \cap \operatorname{Axe}_T(\phi^N(g))$ contains an f-legal segment with length C, or $[f^N_- \circ h(\theta_j)] \cap \operatorname{Axe}_{T_-}(\phi^{-N}(g))$ contains an f_- -legal segment with length C. Suppose the first case happens for at least half of the indices in $\{i, \ldots, i + k - 1\}$. Then since the images of the segments θ_j do not overlap, there are at least k/2 legal segments with length C in the fundamental domain α_N . Thus $\operatorname{Leg}_f(\phi^N(g)) \geq \frac{Ck}{2\operatorname{len}(\alpha_N)}$.

Since $k > \frac{\operatorname{len}(\alpha) - L - 2K_N}{L + K_N}$ and the fact that $\|g^l\|_T = \operatorname{len}(\alpha) \ge 2L + 3K_N$ we obtain

$$\begin{split} \operatorname{Leg}_{f}(\phi^{N}(g)) &\geq \frac{C}{2\operatorname{len}(\alpha_{N})} \frac{\operatorname{len}(\alpha) - L - 2K_{N}}{L + K_{N}} \\ &\geq \frac{C\operatorname{len}(\alpha)}{2\operatorname{len}(\alpha_{N})} \frac{1 - \frac{L - 2K_{N}}{2L + 3K_{N}}}{L + K_{N}} \\ &\geq \frac{C\operatorname{len}(\alpha)}{2\operatorname{len}(\alpha_{N})} \frac{L + 5K_{N}}{(L + K_{N})(2L + 3K_{N})} \\ &\geq \frac{C}{2\operatorname{Lip}(f^{N})} \frac{L + 5K_{N}}{(L + K_{N})(2L + 3K_{N})} > 0 \end{split}$$

The bound does not depend on g nor on α .

Similarly, if the second case happens, i.e. if there are more long legal segments in $\alpha_{-N} \subset \operatorname{Axe}_{T_{-}}(\phi^{-N}(g))$, then we get

$$\operatorname{Leg}_{f_{-}}(\phi^{-N}(g)) \geq \frac{C}{2\operatorname{Lip}(f_{-}^{N} \circ h)} \frac{1 - \frac{L - 2K_{N}}{2L + 3K_{N}}}{L + K_{N}}$$

Since at least one of these two cases occurs, we can define ε_0 as the smallest of both bounds and we obtain the lemma.

For a geodesic in T (resp. T_{-}) and a constant L > 0 we define the lamination ratio $LR(g,T,\Lambda^+,L)$ (resp. $LR(g,T_-,\Lambda^-,L)$ as the upper bound of the proportion of $Axe_T(g)$ (resp. $\operatorname{Axe}_{T_{-}}(g)$ which can be covered by pairwise disjoint leaf segments of Λ^{+} (resp. Λ^{-}) with length at least L.

Lemma 4.13. Let $\varepsilon_0 > 0$. For any L > 0, there exists $N_1 \ge 0$ such that for any $g \in G$, for any $n \geq N_1$, if $\operatorname{Leg}_f(g,T) > \varepsilon_0$ then

$$\operatorname{LR}(\phi^n(g), T, \Lambda^+, L) > \varepsilon_0/4.$$

Proof. Let $g \in G$ be such that $\operatorname{Leg}_f(g,T) > \varepsilon_0$. Let $\beta \subset \operatorname{Axe}_T(g)$ be a maximal legal subsegment with length at least κ . Let $\beta' \subset \beta$ be the subsegment obtained by cutting out the $\frac{C_f}{2} \leq \frac{\kappa}{4}$ -neighbourhood of the endpoints. Its length is at least $\operatorname{len}(\beta) - C_f$ and for all $n \in \mathbb{N}$, $f^n(\beta') \subset$ $\operatorname{Axe}_T(\phi^n(g)).$

There exists $n_1 \in \mathbb{N}$ such that $\lambda^{n_1} C_f \geq 4l_{\max}$ where $l_{\max} := \max_{e \in E(T)} \operatorname{len}(e)$. Thus $f^{n_1}(\beta')$ contains at least one edge of T. In fact, the number of edges of T contained in $f^{n_1}(\beta')$ is at least $k_{\beta'} := \left\lfloor \frac{\lambda^{n_1}(\operatorname{len}(\beta) - C_f)}{l_{\max}} \right\rfloor \text{ and their total length is at least } c_{\beta'} := \lambda^{n_1}(\operatorname{len}(\beta) - C_f) - 2l_{\max}.$ There exists $n_2 \in \mathbb{N}$ such that for every edge $e \in T$, $f^{n_2}(e)$ is a leaf segment with length

greater than L.

Thus $f^{n_1+n_2}(\beta')$ is contained in $\operatorname{Axe}_T(\phi^{n_1+n_2}(g))$ and contains at least $k_{\beta'}$ disjoint open leaf segment with length at least L whose total length is at least $\lambda^{n_2} c_{\beta'}$.

Let \mathcal{B} be the set of $\langle g \rangle$ -orbits of maximal legal subsegments of $\operatorname{Axe}_T(g)$. Let $n \in \mathbb{N}$. The proportion of $\operatorname{Axe}_T(\phi^{n_1+n_2+n_3}(q))$ covered by the leaf segments is at least

$$\frac{\lambda^{n_2+n} \sum_{\beta \in \mathcal{B}} \lambda^{n_1} (\operatorname{len}(\beta) - C_f) - 2l_{\max}}{\lambda^{n_1+n_2+n} \|g\|_T}$$

Thus

$$\begin{aligned} \operatorname{LR}(\phi^{n_1+n_2+n}(g),T,\Lambda^+,L) &\geq \frac{\displaystyle\sum_{\beta \in \mathcal{B}} \lambda^{n_1}(\operatorname{len}(\beta) - C_f) - 2l_{\max}}{\lambda^{n_1} \|g\|_T} \\ &\geq \frac{\displaystyle\sum_{\beta \in \mathcal{B}} \lambda^{n_1}(\operatorname{len}(\beta) - C_f) - \lambda^{n_1} \frac{C_f}{2}}{\lambda^{n_1} \|g\|_T} \\ &\geq \frac{\displaystyle\sum_{\beta \in \mathcal{B}} \frac{\operatorname{len}(\beta)}{4}}{\|g\|_T} \\ &\geq \frac{\displaystyle\varepsilon_0}{4} \end{aligned}$$

This proves the lemma with $N_1 = n_1 + n_2$.

Lemma 4.12 yields a constant ε_0 . For the rest of the paper we fix such an ε_0 . Define $k(g), k_{-}(g)$ as follows:

- $k(g) = \min\{k \in \mathbb{Z} / \operatorname{Leg}_f(\phi^k(g)) \ge \varepsilon_0\}$
- $k_{-}(g) = \max\{k \in \mathbb{Z} / \operatorname{Leg}_{f_{-}}(\phi^{k}(g)) \ge \varepsilon_{0}\}$

By Lemma 4.11 these integers are well-defined.

Lemma 4.14. There exists $N \in \mathbb{N}$ such that for any loxodromic $g \in G$, $|k(g) - k_{-}(g)| \leq N$.

Proof. Let $g \in G$ be a loxodromic element. Let N_0 be the constant given by Lemma 4.12. Lemma 4.12 implies that either $\text{Leg}_f(\phi^{N_0}(\phi^{k(g)-N_0-1}(g)))$ or $\text{Leg}_{f_-}(\phi^{-N_0} \circ \phi^{k(g)-N_0-1}(g))$ is greater than ε_0 . By definition of k(g), the former does not hold so $\text{Leg}_{f_-}(\phi^{-2N_0+k(g)-1}(g)) > \varepsilon_0$. Therefore we have

$$k(g) - k_{-}(g) \le 2N_0 + 1.$$

Lemma 4.9 gives M such that for all $m \ge M$ we have

$$\|\phi^m(\phi^{k(g)}(g))\|_T > \|\phi^{k(g)}(g)\|_T$$

It also gives a similar constant M_{-} for f_{-} . If we had $k_{-}(g) - k(g) \ge \max\{M, M_{-}\}$ then by applying Lemma 4.9 twice with $m = k_{-}(g) - k(g)$ we would get a contradiction:

$$\|\phi^{k}(g)\|_{T} = \|\phi^{-m} \circ \phi^{m} \circ \phi^{k}(g)\|_{T} > \|\phi^{m} \circ \phi^{k}(g)\|_{T} > \|\phi^{k}(g)\|_{T}$$

This gives an upper bound for $k_{-}(g) - k(g)$.

5 Defining the projection

Let $g \in G$ be a loxodromic element. Like in [Alg11] we define $t_0(g) := k(g) \log(\lambda_+)$. The following lemma is the same as [Alg11, Lemma XX]. The fact that G is a GBS group instead of F_N has no influence.

Lemma 5.1. There exists a constant C > 0 such that for every loxodromic element $g \in G$ we have for $t \ge t_0$:

$$C^{-1}\lambda^{\left\lfloor\frac{t-t_0}{\log(\lambda)}\right\rfloor}\|g\|_{T_0} \le \|g\|_{T_t} \le C\lambda^{\left\lfloor\frac{t-t_0}{\log(\lambda)}\right\rfloor}\|g\|_{T_0}$$

and for $t \leq t_0$:

$$C^{-1}\lambda_{-}^{\lfloor \frac{t_0-t}{\log(\lambda)}\rfloor} \|g\|_{T_0} \le \|g\|_{T_t} \le C\lambda_{-}^{\lfloor \frac{t_0-t}{\log(\lambda)}\rfloor} \|g\|_{T_0}$$

Proof. We will prove the inequalities in the case where t is a multiple of $\log(\lambda)$. The result for other values of t can be obtained by applying Lemma 1.27 to a translate of the subsegment $\{T_t/0 \leq t \leq \log(\lambda)\}$, and it will only result in increasing the multiplicative constants by a controlled amount.

Write $t_0 = t_0(g)$. First let us deal with the case $t \ge t_0$. Let $n \in \mathbb{N}$ and let $t_n = t_0 + n \log \lambda$. We have $T_{t_n} = T_{t_0} \cdot \phi^n$.

Since f is λ -Lipschitz we have

$$||g||_{T_{t_n}} \leq \lambda^n ||g||_{T_{t_0}}$$

Let us prove the other side of the inequality. Lemma 4.7 can be applied to a well-chosen fundamental domain for g and gives a constant $C(\varepsilon_0)$ independent of n and g such that

$$\|g\|_{T_{t_n}} \ge C(\varepsilon_0)\lambda^n \|g\|_{T_{t_0}}$$

which gives the first part of the Lemma.

Now let us deal with the case $t \leq t_0$. Let $n \in \mathbb{N}$. Let $t_n = t_0 - n \log(\lambda)$. In that case we have $n = \frac{t_0 - t}{\log(\lambda)}$.

We have

$$\operatorname{Lip}(T, T_{-})^{-1} \le \frac{\|g\|_{T}}{\|g\|_{T_{-}}} \le \operatorname{Lip}(T_{-}, T)$$

and by applying this to $\phi^n(g)$ instead of g for any $n \in \mathbb{Z}$, we have

$$\operatorname{Lip}(T, T_{-})^{-1} \le \frac{\|g\|_{T \cdot \phi^n}}{\|g\|_{T_{-} \cdot \phi^n}} \le \operatorname{Lip}(T_{-}, T_{-})$$

In particular, since $T_{t_0} = T \cdot \phi^{k(g)}$ this also works when replacing T, T_- with T_{t_0}, T_{-t_0} . We now have $T_{-t_n} = T_{-t_0} \cdot \phi^{-n}$ so $\|g\|_{T_{-t_n}} \leq \lambda_-^n \|g\|_{T_{-t_0}}$. We deduce the right inequality:

$$\begin{split} \|g\|_{T_{t_n}} &\leq \operatorname{Lip}(T_{-}, T) \|g\|_{T_{-t_n}} \\ &\leq \operatorname{Lip}(T_{-}, T) \lambda_{-}^n \|g\|_{T_{-t_0}} \\ &\leq \operatorname{Lip}(T_{-}, T) \operatorname{Lip}(T, T_{-}) \lambda_{-}^n \|g\|_{T_{t_n}} \end{split}$$

Now let us prove the left inequality. Lemma 4.12 gives an integer constant N such that $k_{-}(g) \geq k(g) - N$. Thus we have by the same arguments as above, and for $n \geq N$ and $T_{t_N} = T_{t_0} \cdot \phi^{-N}$ we obtain

$$||g||_{T_{-t_n}} \ge C(\varepsilon_0) \lambda_-^{n-N} ||g||_{T_{-t_N}}$$

Since $||g||_{T_{-t_N}} \ge \operatorname{Lip}(T_- \cdot \phi^{-N}, T_-)^{-1} ||g||_{T_{-t_0}}$ we have

$$\|g\|_{T_{-t_n}} \ge C(\varepsilon_0) \lambda_{-}^{-N} \operatorname{Lip}(T_{-} \cdot \phi^{-N}, T_{-})^{-1} \lambda_{-}^{n} \|g\|_{T_{-t_0}}$$

When $0 \le n < N$ then we have $\frac{\|g\|_{T_{-t_0}}}{\|g\|_{T_{-t_n}}} \le \operatorname{Lip}(T_-, T_- \cdot \phi^N)$ so in any case there is a constant C > 1 depending only on T, T_-, N such that

$$||g||_{T_{t_n}} \ge C^{-1}\lambda_{-}n(t)||g||_{T_{t_0}}$$

This proves the lemma.

Define $\Theta(g) := \{t \in \mathbb{R}/||g||_{T_t} \text{ minimal } \}.$

Lemma 5.2. There exists s > 0 such that for every loxodromic $g \in G$ and $t \in \Theta(g)$, then $|t - t_0(g)| < s$.

Proof. Let C be the constant from Lemma 5.1. Suppose $t > t_0(g)$. Then we have $||g||_{T_t} \ge C^{-1}\lambda^{\left\lfloor \frac{t-t_0(g)}{\log(\lambda)} \right\rfloor} ||g||_{T_{t_0}}$ so since $||g||_{T_t} \le ||g||_{T_{t_0}}$ this implies $t - t_0 \le \log(C\lambda)$. We get a similar inequality for $t < t_0$, hence the result.

Remark 5.3. The diameter of $\Theta(g)$ is bounded by 2s.

An important property of the projection is that projections of simple pairs are close:

Lemma 5.4. There exists s' > 0 with the following property. Let $\{g, h\}$ be a simple pair of loxodromic elements of G. Then $|t_0(g) - t_0(h)| < s'$.



Figure 10: If $t_0(g), t_0(h)$ are sufficiently far apart, then there exists t such that the axes of g and h in T_t contain long leaf segments of the opposite laminations

Proof. We prove this by contraposition: we will show that if $t_0(g)$ and $t_0(h)$ are too far apart then we can find t in between such that the axes of g and h in T_t contain long segments of the stable and unstable lamination (see Figure 10).

Let L_0 be the constant from Proposition 3.13 such that elements in a simple pair cannot contain leaf segments longer than L_0 of both lamination in their axes. Without loss of generality we may assume $L_0 > \kappa$.

By Lemma 2.9 there exists a constant L_1 such that if a path $\beta \subset T_-$ contains a leaf segment of Λ^- longer than L_1 , then $[h_-(\beta)]$ contains a leaf segment of Λ^- of length greater than L_0 . The choice of L_1 depends only on h_- , f_- , and L.

Without loss of generality suppose $t_0(g) < t_0(h)$.

Let $N_1 > 0$ be the integer given by Lemma 4.13 for f, ε_0 and L_0 . Similarly define $N_{1,-} > 0$ as the integer given for f_- , ε_0 , L_1 .

By definition of t_0 we have $\text{Leg}_f(g, T_{t_0(g)}) \geq \varepsilon_0$. Thus for all $n \geq N_1$ we have

 $\operatorname{LR}(g, T_{t_0(g)+n\log(\lambda)}, \Lambda^+, L_0) \ge \varepsilon_0/4.$

Similarly for all $n \ge N_{1,-}$ we have $\operatorname{Leg}_{f_-}(h, T_{t_0(h)-n\log(\lambda_-)}, \Lambda^-, L_1) \ge \varepsilon_0/4$.

Suppose $t_0(h) - t_0(g) > N_1 \log(\lambda) + N_{1,-} \log(\lambda_-)$. Then there exists $t_0(g) + N_1 \log(\lambda) < t < t_0(h) - N_{1,-} \log(\lambda_-)$. Consequently $\operatorname{Axe}_{T_t}(g)$ contains an L_0 -piece of Λ^+ and $[h(\operatorname{Axe}_{T_{-t}}(h))]$ contains an L_0 -piece of Λ^- . This contradicts the fact that the pair $\{g,h\}$ is simple.

Here is a direct corollary:

Corollary 5.5. Let s, s' be the constants from Lemmas 5.2 and 5.4. For a simple pair $\{g, h\}$, diam $(\Theta(g) \cup \Theta(h)) < s + s'$.

In order to evaluate the distance $d_{\text{Lip}}(X, \mathcal{L}_f)$ for some arbitrary $X \in \mathcal{D}$, we will use candidates of X. Lemma 5.4 applies in particular to candidates:

Corollary 5.6. Suppose $b_1(G) \ge 3$. There exists s'' > 0 such that for every $X \in \mathcal{D}$, if g, h are candidates in X, then for any $t_g \in \Theta(g)$ and $t_h \in \pi_f(h)$ we have $|t_g - t_h| < s''$.

Proof. By Lemma 3.3 there exists $k \in G$ such that the pairs $\{g, k\}$ and $\{h, k\}$ are simple. Applying the previous corollary gives $|t_g - t_h| < |t_g - t_k| + |t_k - t_h| < 2s' + 2s$.

For $X \in \mathcal{D}$, define $\Theta_X := \{t \in \mathbb{R}/d_{\text{Lip}}(X, T_t) \text{ minimal } \}.$

Lemma 5.7. For every $X \in \mathcal{D}$, the set Θ_X is non-empty.

Moreover there exists s > 0 such that for every $X \in \mathcal{D}$, diam $(\Theta_X) < s$.

Proof. Let $X \in \mathcal{D}$. By Theorem 1.23, for all $t \in \mathbb{R}$, there exists a candidate such that $d_{\text{Lip}}(X, T_t) = \log \frac{\|g\|_{T_t}}{\|g\|_X}.$ Therefore we have

$$d_{\rm Lip}(X, T_t) = \max_{g \text{ candidate }} \log \frac{\|g\|_{T_t}}{\|g\|_X}$$

Fix a candidate g. The function $t \mapsto \frac{\|g\|_{T_t}}{\|g\|_X}$ is minimal for $t \in \Theta_g$. We will prove that $d_{\text{Lip}}(X, T_t)$ reaches its minimum in a *D*-neighbourhood of Θ_g , where *D* does not depend on *X* nor on the number of candidates in X.

Let $t_0 := t_0(g)$. If h is another candidate we have $|t_0(h) - t_0| < s''$ where s'' is the constant from Corollary 5.6. By Lemma 5.1 we have

$$\|h\|_{T_{t_0}} \le \|h\|_{T_{t_0(h)}} C \lambda^{\frac{s''}{\log(\lambda)}}$$

Write $K = C\lambda^{\frac{s''}{\log(\lambda)}}$. For $t_* \ge \log(2CK) + \log(\lambda)$ and $t > t_0 + s'' + t_*$ we have $t > t_0(h) + t_*$ and still by Lemma 5.1 we get

$$h||_{T_t} \ge 2K||h||_{T_{t_0}(h)} \ge 2||h||_{T_t}$$

Dividing both sides by $||h||_X$ does not change the inequality.

Therefore we have for $t > t_0 + s'' + t_*$

$$\max_{h \text{ candidate}} \frac{\|h\|_{T_t}}{\|h\|_X} \ge 2 \frac{\|h\|_{T_{t_0}}}{\|h\|_X}$$

For $t < t_0$ we get a similar result. We deduce a constant Δt such that for $t \in \mathbb{R} \setminus [t_0 - \Delta t, t_0 + \Delta t]$ we have $d_{\text{Lip}}(X, T_t) > \log 2d_{\text{Lip}}(X, T_{t_0})$. Since $t \to T_t$ is continuous for the axes topology, $t \mapsto d_{\text{Lip}}(X, T_t)$ reaches its minimum in a Δt -neighbourhood of t_0 .

Remark 5.8. The previous proof differs slightly from the proof of [Alg11, XX] since there is no bound on the number of candidates in elements of \mathcal{D} , unlike in CV_N . This comes from the fact that \mathcal{D} is not finite dimensional so there is no bound on the number of orbits of edges in elements of \mathcal{D} .

For $X \in \mathcal{D}$ we choose t_X in Θ_X . Since Θ_X has bounded diameter and the bound does not depend on X this will be well enough defined.

6 Negative curvature properties of the projection

In this section we prove the analogues of Lemmas 5.7 and 5.8 of [Alg11] and deduce the strong contraction property.

The difference in the proof with [Alg11] is the proof of Lemma 6.4. The initial proof relies on special shapes of graphs such as roses (see [Alg11, Proposition 5.10]). Here reduced graphs will take the role of roses. The other proofs are actually quite similar to the free group case.

Lemma 6.1. There exist s, c > 0 such that for any $X \in \mathcal{D}$, if $|t - t_X| > s$ then $d_{\text{Lip}}(X, T_t) \ge d_{\text{Lip}}(X, \pi(X)) + d_{\text{Lip}}(\pi(X), T_t) - c$.

Proof. Suppose $t \leq t_X$. Let g be a candidate in X. The idea of the proof is that if s is big enough, then $\text{Leg}_f(g, T_{t_X+s})$ is also big and g almost realizes $d_{\text{Lip}}(T_{t_X+s}, T_t)$.

There is a candidate h of X such that $\operatorname{Lip}(X, \pi(X)) = \frac{\|h\|_{\pi(X)}}{\|h\|_X}$. Since $t_X \in \Theta(X)$ we have $t_X \in \Theta(h)$. By Lemmas 5.2 and 5.4 there exists a constant s such that for every candidate g of X we have $|t_X - t_0(g)| < s$. Thus for any candidate g of X, for any $t_1 > t_X + s$, we have $\operatorname{Leg}_f(g, T_1) > \varepsilon_0$.

Let $Z := T_{t_1}$. Let g be a candidate of X such that $d_{\text{Lip}}(X, Z) = \frac{\|g\|_Z}{\|g\|_X}$.

Applying twice Lemma 5.1 to g for t and t_1 we obtain a constant C such that

$$\frac{\|g\|_{T_t}}{\|g\|_Z} \ge C^{-2} \lambda^{\frac{t-t_0(g)}{\log(\lambda)} - \frac{t_1 - t_0(g)}{\log(\lambda)} - 1} = C^{-2} \lambda^{-1} e^{t-t_1}$$

Remarking that $e^{t-t_1} = \operatorname{Lip}(Z, T_t)$ we have

$$\operatorname{Lip}(Z, T_t) \le \frac{\|g\|_{T_t}}{\|g\|_Z} \frac{1}{C^2 \lambda}$$

with $C^2 \lambda > 1$.

Since $\operatorname{Lip}(X, Z) = \frac{\|g\|_Z}{\|g\|_X}$ we have

$$\begin{aligned} \operatorname{Lip}(X, T_t) &\geq \frac{\|g\|_{T_t}}{\|g\|_X} \\ &= \frac{\|g\|_{T_t}}{\|g\|_Z} \frac{\|g\|_Z}{\|g\|_X} \\ &\geq \frac{1}{C^2 \lambda} \operatorname{Lip}(Z, T_t) \operatorname{Lip}(X, Z) \end{aligned}$$

Applying the logarithm we get a constant K > 0 such that $d_{\text{Lip}}(X, T_t) \ge d_{\text{Lip}}(X, Z) + d_{\text{Lip}}(Z, T_t) - K$.

Finally by definition of the projection we have $d_{\text{Lip}}(X, Z) \ge d_{\text{Lip}}(X, \pi(X))$. If $t - t_X > s$ we have

$$d_{\text{Lip}}(X, T_t) \ge d_{\text{Lip}}(X, \pi(X) + d_{\text{Lip}}(Z, T_t) - K$$
$$\ge d_{\text{Lip}}(X, \pi(X)) + d_{\text{Lip}}(\pi(X), T_t) - s - K$$

Lemma 6.2. There exist s, c > 0 such that for any $X, Y \in \mathcal{D}$, if $|t_X - t_Y| > s$ then $d_{\text{Lip}}(Y, X) \ge d_{\text{Lip}}(Y, \pi(X)) - c$.

Before proving Lemma 6.2 we need some preliminary results.

Lemma 6.3. Let $X, T \in \mathcal{D}$ and $e_0 \in E(X)$. Suppose every edge orbit in $X \setminus G \cdot e_0$ is noncollapsible. There exists a G-equivariant map $\tau : X \to T$ such that every edge in $X \setminus G \cdot e_0$ is contained in a τ -legal bi-infinite geodesic in $X \setminus G \cdot e_0$.

Proof. We will prove this by constructing the map $\tau : X \to T$ such that at every vertex $v \in V(X)$, at least two gates at v for the gate structure induced by τ contain edges in $E(X) \setminus G \cdot e_0$. Then there exist bi-infinite τ -legal geodesics with the desired property.

There exists a G-equivariant map $\tau_0 : X \to T$. We may suppose that τ_0 sends vertex to vertex and is linear on edges.

Let v_1, \ldots, v_n be representatives of every vertex orbit of V(X). In order to define a new map τ , it suffices to choose the image of v_i for every $i \in \{1, \ldots, n\}$. The image of v_i can be any vertex $w_i \in V(T)$ such that $G_{v_i} \subset G_{w_i}$.

Suppose there exists $v \in X$ such that there is only one gate at v which contains edges in $E(X) \setminus G \cdot e_0$. We include the case where there is only one gate at v.

Let $w = \tau_0(v)$. There exists a vertex $w' \in T$ such that $\bigcap_{e \in E_v \setminus G \cdot e_0} \tau_0(e) = [w, w']$. Since no edges in τ_0 are collapsible except translates of e_0 , the images $\tau_0(e)$ have non-zero length. Since these edges are contained in a single gate, the intersection has non-zero length and we have $w \neq w'$.

Let us prove $G_v \subset G_{w'}$. Let $a \in G_v$. By contradiction suppose $aw' \neq w'$, then for any edge in $E_v \setminus G \cdot e_0$ we have $w' \notin \tau(ae)$ which contradicts the definition of w', thus $G_v \subset G_{w'}$. Define τ_1 by

$$\tau_1: x \in V(X) \longmapsto \begin{cases} \tau_0(x) & \text{if } x \notin G \cdot v \\ gw' & \text{if } x = gv \end{cases}$$

Note that if there exists $e \in E_v$ such that $\tau_0(e) = [w, w']$, then e cannot be a loop in the quotient. If e were a loop $[v, gv] \subset T$ then $g^{-1}\bar{e} = [v, g^{-1}v]$, which is also in E_v and has same length, would also be sent to $[w, w'] = [w, gw] = [w, g^{-1}w]$. This would imply that g^2 is elliptic, which is a contradiction. Thus the vertices of e are in distinct orbits, and since the image of e is a single point, τ_1 factors through the collapse of e.

Since no edge orbit is collapsible except e_0 , e can be collapsed only if e is a translate of e_0 . We do not care about the image of e_0 .

By construction of τ_1 , there are at least two gates for τ_1 at vertex v which contain edges in $E_v \setminus G \cdot e_0$. Let us prove that gates at other vertices have not changed.

Let $e \in E(T) \setminus G \cdot e_0$. Neither τ_0 nor τ_1 collapse e. If an endpoint x of e is in $G \cdot v$, then $\tau_1(x)$ is in the interior of $\tau_0(e)$. Otherwise $\tau_1(x) = \tau_0(x)$. Thus if $o(e) \notin G \cdot v$, the first edge of $\tau_1(e)$ and $\tau_0(e)$ are equal. Thus the gate structure at o(e) is unchanged.

Therefore the number of vertices with at most one gate containing edges not in $G \cdot e_0$ is smaller for τ_1 than for τ_0 .

We can iterate this procedure with τ_1 instead of τ_0 until we find a map τ such that all vertices in X have at least two gates containing edges not in $G \cdot e_0$.

Lemma 6.4. Let L be the constant from Proposition 3.13. Suppose $r \in \mathbb{R}$ is such that for every candidate $u \in G$ for X, the axis $\operatorname{Axe}_{T_r}(u)$ contains an L-piece of Λ^- . Let $g \in G$. Suppose that $\operatorname{Axe}_{T_r}(g)/\langle g \rangle$ contains k disjoint 2L-pieces of Λ^+ for some $k \in \mathbb{N}$. Then for every edge $e_0 \in E(X)$, $\operatorname{Axe}_X(g)/\langle g \rangle$ contains at least k/2 edges in the orbit of e_0 .



Figure 11: Axis of g in T_r ; the 2L-pieces are in thick red, the image of $\operatorname{Axe}_{X'}(g)$ in dotted line and the μ_j are highlighted in green. The line $\tau(\eta)$ is also represented. Due to minimality of μ_j , η contains σ_j .

Proof. Let e_0 be an orbit of edges in E(X). There exists a collapse $X \to X'$ such that e_0 is not sent to a single point, and every edge $e \neq e_0$ in X/G is not collapsible.

By Lemma 6.3 there exists a map $\tau: X' \to T_r$ such that:

- at every vertex $v \in V(X')$, there are at least two gates for the train track structure induced by τ
- at every vertex v, at least two gates contain edges which are not in $G \cdot e_0$.

Let $\sigma_1, \ldots, \sigma_k$ be the 2*L*-pieces of Λ^+ in $\operatorname{Axe}_{T_r}(g)$. Let $\mu_j := e_i \ldots e_l$ be a minimal edge path in $\operatorname{Axe}_{X'}(g)$ such that $[\tau(\mu_j)]$ contains σ_j (see Figure 11). We claim that for all $j \in \{1, \ldots, k\}$, the edge path μ_j contains one edge in $G \cdot e_0$. By contradiction, assume that for some $j \in \{1, \ldots, k\}$ no edge in μ_j is in $G \cdot e_0$.

The path μ_j can be completed into a bi-infinite line $\eta \subset X' \setminus G \cdot e_0$ such that every turn of η is τ -legal, apart from turns in the interior of $e_i \ldots e_l$. By minimality of μ_j , the image $\tau(e_i)$ (resp. $\tau(e_l)$) is not contained in $\tau(e_{i+1} \ldots e_l)$ (resp. $\tau(e_i \ldots e_{l-1})$). Therefore the legality property of η implies that the image $[\tau(\eta)]$ contains the segment $[\tau(\mu_j)]$.

Now we would like to find the axis of an element $h \in G$ such that $\operatorname{Axe}_{T_r}(h)$ contains $[\tau(\mu_j)]$ and $\operatorname{Axe}_{X'}(h) \cap G \cdot e_0 = \emptyset$. Suppose we find such an h. Then $\operatorname{Axe}_{T_r}(h)$ contains an L-piece of Λ^+ . However, in X', there exists a candidate $u \in G$, possibly equal to h, whose axis does not cross $G \cdot e_0$. The assumptions of the lemma imply that $\operatorname{Axe}_{T_r}(u)$ contains an L-piece of Λ^- . By Proposition 3.13 the pair $\{h, u\}$ is not simple. This contradicts the fact that their axes in X'both avoid $G \cdot e_0$. The conclusion is that e_0 must appear somewhere in μ_j . Let us explain how we construct h. In the special case where there exists an edge $e \in E(X')$ such that there are two translates e, he in η with same orientation, and one on each side of μ_j then [e, he] contains a fundamental domain for the axis of h and again by minimality of μ_j , $\operatorname{Axe}_{T_r}(h)$ contains $[\tau(\mu_j)]$.

In the general case, since no edge in $X' \setminus G \cdot e_0$ is collapsible, the connected component of $X' \setminus G \cdot e_0$ containing η has no valence 1 vertex. Its stabilizer is a cyclic factor H and this connected component is the minimal subtree X'_H . For every $g \in G$, $gX'_H \cap X'_H \neq \emptyset \Rightarrow g \in H$. The subtree X'_H has infinite diameter because it contains η . As X'/G is finite, there exists a vertex with unbounded H-orbit so H is not elliptic. Thus it is not cyclic.

If H is not solvable, then the action of H on X'_H is irreducible: for every segment $I \subset X'_H$, there exists $h \in H$ whose axis contains I.

Let $I \subset \eta$ be a segment containing a $2 \operatorname{BBT}(\tau)/m$ -neighbourhood of μ_j , where $m = \min_{e \notin G \cdot e_0} \frac{\operatorname{len}(\tau(e))}{\operatorname{len}(e)}$. Let $h \in H$ be a loxodromic element whose axis contains I.

The cancellation in $\tau(\operatorname{Axe}_{X'}(h))$ does not reach μ_j so $\operatorname{Axe}_{T_r}(h)$ contains $[\tau(\mu_j)]$.

Finally we must deal with the case where H is isomorphic to BS(1, n). The subtree X'_H is reduced, so X'_H/H consists in a single edge. If $n = \pm 1$ then X'_H is a line. If $h \in H$ is a loxodromic element then its axis contains η . Moreover since X_H has only valence 2 vertices, they have to belong to different gates so all turns are τ -legal. Therefore $\operatorname{Axe}_{T_r}(h)$ contains $[\tau(\mu_j)]$.

If |n| > 1 then X_H is not a line but there is a fixed point ξ in ∂X_H for the action of H. If the line η has both endpoints different from ξ then it might be impossible to find h containing μ_j as a whole. However η contains only one orbit of edge e. Up to reversing the orientation of e we may assume $G_e = G_{t(e)}$, so every turn of the form $\{e, a\bar{e}\}$ with $a \in G_{t(e)}$ is degenerate. Therefore η maps to $\ldots \bar{e}\bar{e}\bar{e}\ldots \bar{e}e\ldots eee\ldots$ in X'_H/H . Since $e_i \ldots e_l$ has length > 2L there exists a subsegment η_0 with length > L of the form $eee\ldots$ or $\bar{e}\bar{e}\bar{e}\ldots$ Once again such a segment is τ -legal otherwise there would only be one gate at the vertices of X_H . There exists a loxodromic element $h \in H$ such that $\operatorname{Axe}_{X'}(h)$ contains η_0 . Therefore $\operatorname{Axe}_{X'}(h)$ contains a L-piece of Λ^+ so once again we can apply the discussion above.

We proved that for any $j \in \{1, ..., k\}$, there exists a translate of e_0 in X' such that the minimal edge subpath μ_j contains a translate of e_0 .

If the segments μ_j , $j \in \{1, \ldots, k\}$ are disjoint, then we are done. This may fail though. We will see that $\mu_j \cap \mu_{j'} = \emptyset$ if $|j - j'| \ge 2$ and may be a single edge if |j - j'| = 1. Thus when counting the translates of e_0 in the μ_j , $j \in \{1, \ldots, k\}$, a translate may be counted more than once, but it can be counted for at most twice (see Figure 12). Therefore $\operatorname{Axe}_{X'}(g)/g$ contains at least k/2 translates of e_0 . Since this lifts to X we get the lemma.

Let us prove the fact about the intersection of the segments μ_i .

First we prove that a 2L-piece of Λ^+ cannot be contained in the τ -image of a single edge e. By contradiction, suppose otherwise: again we will construct a simple pair of elements containing long pieces of opposite laminations. The edge e must be in the orbit of e_0 . As above, one can find τ -legal turns $\{e, e_1\}$ and $\{\bar{e}, e_2\}$ with $e_1, e_2 \notin G \cdot e_0$. Let e' be an edge of $X' \setminus G \cdot e_0$. Since e' is not collapsible, there exists a translate $he' \neq e'$ such that $\{e', he'\}$ (if e' is not a loop in the quotient) or $\{e', h\bar{e'}\}$ (if e' is a loop) is a non-degenerate turn. Define

$$\rho_i := e_i \cdot h_i \bar{e}_i \cdot h_i h'_i e_i \cdot h_i h'_i h_i \bar{e}_1 \dots$$

if e_i is not a loop, where h_i, h'_i are such that $\{e_i, he_i\}$ and $\{\bar{e}_i, h'\bar{e}_i\}$ are non-degenerate. If e_i is a loop define

$$\rho_i := e_i \cdot h_i e_i \cdot h_i^2 e_i \dots$$



Figure 12: The subsegments of $\operatorname{Axe}_X(g)$ whose image contain a 2L-piece of Λ^+ may overlap

Suppose e_i is not a loop. Then e_i cannot be identified with $h_i e_i$ by τ , because the vertex groups at $t(e_i)$ and $h_i t(e_i)$ are not nested: it would imply that T_r has an elliptic element which is not elliptic in X'. There exists a subdivision of X' such that $e_i = a_i \cdot e'_i \cdot b_i$, with $\tau(b_i) = \tau(h_i b_i)$ and $\tau(a_i) = \tau(h'_i a_i)$. Then

$$[\tau(\rho_i)] := \tau(a_i) \cdot \tau(e'_i) \cdot h_i \tau(\bar{e}'_i) \cdot h_i h'_i \tau(e'_i) \dots$$

and since the turns between e and e_i are legal, there is no simplification between $\tau(a_i)$ and $\tau(e)$.

If e_i is a loop, then we already proved in Lemma 6.3 that e_i and $h_i \bar{e}_i$ cannot have the same image by τ , or we would obtain new elliptic elements. Once again there exists a subdivision $e_i = a_i \cdot e'_i \cdot b_i$ with $\tau(\bar{b}_i) = h_i \tau(a_i)$. Thus

$$[\tau(\rho_i)] := \tau(a_i) \cdot \tau(e'_i) \cdot h_i \tau(e'_i) \cdot h_i^2 \tau(e'_i) \dots$$

and once again there is no cancellation between $\tau(a_i)$ and $\tau(e)$.

Consequently we can construct a bi-infinite geodesic $\bar{\rho}_1 \cdot e \cdot \rho_2$ such that ρ_1, ρ_2 are rays which cross only one orbit of edges, and $\tau(e) \subset [\tau(\bar{\rho}_1 \cdot e \cdot \rho_2)]$. We proved above that the rays need not be legal, the point is that the cancellation which may occur at turns remains controlled.

Let l be such that the image of any segment of longer than l by τ is longer than $2 \operatorname{Lip}(\tau)$. Let ρ_1^0, ρ_2^0 be prefixes of the rays longer than l. The path $\bar{\rho}_1^0 \cdot e \cdot \rho_2^0$ can be closed into a loop in the quotient, representing an element $h \in G$ such that $\operatorname{Axe}_{T_r}(h) = [\tau(\operatorname{Axe}_X(h))]$ contains $\tau(e)$, hence a 2L-piece of Λ^+ . The point is that this loop may be constructed such that it crosses only three orbits of edges in X'. Since $b_1(X'/G) \geq 3$, $\operatorname{Axe}_{X'}(h)$ must avoid one orbit of edges.

There exists a candidate u of X' whose axis avoids the same orbit of edge as h, thus $\{u, h\}$ is a simple pair. By assumption $\operatorname{Axe}_{T_r}(u)$ contains an L-piece of Λ^- , which is a contradiction to Proposition 3.13: thus $\tau(e)$ cannot contain a whole 2L-piece of the lamination.

The second point is that the intersection of segments μ_i, μ_j cannot be more than one edge: by minimality of μ_j , the last endpoint of σ_j lies in the image of the last edge of μ_j but not in the image of any other edge. Similarly for j' > j, the first point of $\sigma_{j'}$ lies in the image of the first edge of $\mu_{j'}$ and not in any other edge. Thus the intersection $\mu_i \cap \mu_j$ is at most one single edge.

Besides, if $|j' - j| \ge 2$, then σ_{j+1} must be contained between the last point of σ_j and first point of $\sigma_{j'}$. This is not possible if both belong to the same edge, hence the fact.

Now we have sufficient tools to prove Lemma 6.2.

Proof of Lemma 6.2. Let X, Y be as in the statement of the lemma. Assume $t_Y < t_X$ in \mathcal{L}_f . The other case works similarly by exchanging the roles of ϕ and ϕ^{-1} and will give other constants s, c: we will take the greater constants.

There exists s_1 such that for any $s > s_1$, for any $t \in \mathbb{R}$, for any candidate g of T_t , Leg_f $(g, T_{t+s}) > \varepsilon_0$. This is a consequence of the following facts: T_t has an f-legal candidate u(Lemma 1.22) so $t_0(u) \le t$, and there exists s > 0 such that for any other candidate v we have $t_0(v) \le t_0(u) + s$ (Lemma 5.4).

Let L be the constant from Proposition 3.13. By Lemma 4.13 there exists $N_1 \in \mathbb{N}$ such that for every candidate g of X, $LR(\phi^{N_1}(g), T, \Lambda^+, 2L) > \varepsilon_0/4$.

There exists $s_2 > 0$ such that for any $t \in \mathbb{R}$, the image of any candidate of T_t in T_{t-s_3} contains an *L*-piece of Λ^- .

Define $d = s_1 + N_1 \log(\lambda) + s_2$. Suppose $t_X - t_Y > d$. Let $r = t_X - s_2$. Let $g \in G$ be a candidate of Y which realizes $\operatorname{Lip}(Y, \pi(X))$. Then the axis of g in T_r contains long leaf segments of Λ^+ . Actually $\operatorname{LR}(g, T_r, \Lambda^+, 2L) \geq \varepsilon_0/4$. A given leaf segment of length longer than 2L can be at least half covered with disjoint 2L-pieces of Λ^+ . Thus a proportion of at least $\varepsilon_0/8$ of $\operatorname{Axe}_{T_r}(g)$ can be covered by disjoint 2L-pieces of Λ^+ .

Let k(r) be the number of disjoint 2L-pieces of Λ^+ which tile $\operatorname{Axe}_{T_r}(g)/\langle g \rangle$. We have

$$2Lk(r) > \frac{\varepsilon_0}{8} \|g\|_{T_r}$$

Now $\operatorname{Axe}_{T_r}(g)/\langle g \rangle$ contains k(r) 2*L*-pieces of Λ^+ . By Lemma 6.4 $\operatorname{Axe}_X(g)/\langle g \rangle$ contains at least k(r)/2 edges in each orbit of E(X). Since $\operatorname{vol}(X/G) = 1$ we have

$$\operatorname{vol}(\operatorname{Axe}_X(g)/\langle g \rangle) = \|g\|_X \ge k(r)/2.$$

Thus

$$||g||_X \ge k(r)/2 \ge ||g||_{T_r} \frac{\varepsilon_0}{16L}$$

Then

$$\operatorname{Lip}(Y, X) = \frac{\|g\|_X}{\|g\|_Y}$$

$$\geq \frac{\|g\|_{T_r}}{\|g\|_Y} \frac{\varepsilon_0}{16L}$$

$$\geq \frac{\varepsilon_0}{16L} \operatorname{Lip}(Y, T_r)$$

By triangular inequality $d_{\text{Lip}}(Y, T_r) \ge d_{\text{Lip}}(Y, \pi(X)) - r$ so

$$d_{\mathrm{Lip}}(Y,X) \ge d_{\mathrm{Lip}}(Y,\pi(X)) - s_2 - \log(\frac{16L}{\varepsilon_0})$$

Definition 6.5. The ball of outward radius r > 0 centered at $Y \in \mathcal{D}$ is

$$B_{\to}(Y,r) := \{ X \in \mathcal{D}/d_{\mathrm{Lip}}(Y,X) < r \}$$

A closest point projection to \mathcal{L}_f is a map $p_f : \mathcal{D} \to \mathcal{L}_f$ such that for all $X \in \mathcal{D}$, the distance $d_{\text{Lip}}(X, p_f(X))$ is minimal. The map π_f constructed in Section 5 is a closest point projection to \mathcal{L}_f .

Now we can state and prove the strong contraction property.

Theorem 6.6. Let ϕ be a fully irreducible automorphism such that ϕ , ϕ^{-1} both admit train track representatives.

Let \mathcal{L}_f be an axis for ϕ in \mathcal{D} and let p_f be a closest point projection to \mathcal{L}_f . Then there exists D > 0 such that for any $Y \in \mathcal{D}$ and r > 0 such that $B_{\rightarrow}(Y, r) \cap \mathcal{L}_f = \emptyset$

$$\operatorname{diam}(p_f(B_{\to}(Y,r))) \le D$$

Proof. Let $Y \in \mathcal{D}$, $r = d_{\text{Lip}}(Y, p_f(Y))$. Let $B := B_{\rightarrow}(Y, r)$. A ball centred at Y intersects the axis if and only if its radius it greater than r. Balls with smaller radius are contained in B so it suffices to bound diam $(p_f(B))$ independently of Y. Let $X \in B$. Let s, c be the constants from Lemma 6.2 and s', c' be the constants from Lemma 6.1. Suppose $d_{\text{Lip}}(p_f(Y), p_f(X)) > \max\{s, s'\}$. Then Lemma 6.2 yields

$$d_{\operatorname{Lip}}(Y, X) \ge d_{\operatorname{Lip}}(Y, p_f(X)) - c$$

and using Lemma 6.1:

$$d_{\mathrm{Lip}}(Y,X) \ge d_{\mathrm{Lip}}(Y,p_f(Y)) + d_{\mathrm{Lip}}(p_f(Y),p_f(X)) - c - c'$$

Since $d_{\text{Lip}}(Y, X) < r = d_{\text{Lip}}(Y, p_f(Y))$ we have

$$d_{\operatorname{Lip}}(p_f(Y), p_f(X)) \le c + c'$$

Therefore diam $(p_f(B)) \le 2 \max\{s, s', c+c'\}$. This bound is independent of Y.

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