# Length orthospectrum of convex bodies on flat tori 

Nguyen Viet Dang, Matthieu Léautaud, Gabriel Rivière

## To cite this version:

Nguyen Viet Dang, Matthieu Léautaud, Gabriel Rivière. Length orthospectrum of convex bodies on flat tori. 2022. hal-03719958v1

## HAL Id: hal-03719958 <br> https://hal.science/hal-03719958v1

Preprint submitted on 11 Jul 2022 (v1), last revised 5 Nov 2023 (v2)

HAL is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers.

L'archive ouverte pluridisciplinaire HAL, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d'enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.

# LENGTH ORTHOSPECTRUM OF CONVEX BODIES ON FLAT TORI 

NGUYEN VIET DANG, MATTHIEU LÉAUTAUD, AND GABRIEL RIVIÈRE


#### Abstract

In analogy with the study of Pollicott-Ruelle resonances on negatively curved manifolds, we define anisotropic Sobolev spaces that are well-adapted to the analysis of the geodesic vector field on the flat torus $\mathbb{T}^{d}$. Among several applications of this functional point of view, we study properties of geodesics that are orthogonal to two convex subsets of $\mathbb{T}^{d}$ (i.e. projection of the boundaries of strictly convex bodies of $\mathbb{R}^{d}$ ). Associated to the set of lengths of such orthogeodesics, we define a geometric Epstein function and prove its meromorphic continuation. We compute its residues in terms of intrinsic volumes of the convex sets. We also prove Poisson-type summation formulas relating the set of lengths of orthogeodesics and the spectrum of magnetic Laplacians.


## Contents

1. Introduction ..... 2
1.1. Epstein zeta functions in convex geometry ..... 3
1.2. Poincaré series in convex geometry ..... 5
1.3. Application to Poisson type formulas ..... 6
1.4. Related results ..... 7
2. Analytical results: a functional setup for the geodesic vector field ..... 10
2.1. Lifting the problem to the unit tangent bundle ..... 10
2.2. Defining a proper functional framework for the geodesic flow ..... 11
2.3. Anisotropic Sobolev spaces ..... 12
2.4. Emergence of quantum dynamics ..... 14
2.5. Organization of the article ..... 15
2.6. Comments on generalizations ..... 15
3. Background on differential forms and currents ..... 16
3.1. Differential forms ..... 16
3.2. Currents ..... 17
3.3. Orientation conventions ..... 17
3.4. Decomposition of currents in Fourier series ..... 18
3.5. Fundamental examples of currents of integration ..... 19
3.6. Action by pullback ..... 20
3.7. Transport equations on differential forms ..... 21
3.8. Correlation function for differential forms ..... 22
4. Asymptotics of oscillatory integrals ..... 24
4.1. Splitting the oscillatory integral ..... 24
4.2. Nonstationary points ..... 25
4.3. Stationary points ..... 27
5. Asymptotics of twisted dynamical correlations ..... 29
5.1. Anisotropic Sobolev spaces of distributions, splitting the correlation function ..... 30
5.2. Asymptotics of the correlation function ..... 31
5.3. Geometry of the anisotropic Sobolev norms ..... 33
6. Anisotropic spaces of currents ..... 35
6.1. Anisotropic Sobolev spaces ..... 35
6.2. Mapping properties ..... 36
7. Mellin and Laplace transforms ..... 39
7.1. Mellin transform ..... 39
7.2. Laplace transform ..... 44
7.3. Terms near zero in the Mellin and Laplace transforms ..... 53
8. Counting orthogeodesics ..... 54
8.1. Normal bundles to convex sets ..... 54
8.2. Admissible submanifolds ..... 55
8.3. Epstein zeta functions and Poincaré series for admissible submanifolds ..... 55
8.4. Currents of integration on admissible subsets ..... 58
8.5. Asymptotic of the counting function ..... 60
8.6. Continuation of generalized Epstein zeta functions ..... 61
8.7. Continuation of generalized Poincaré series ..... 64
8.8. A summation formula in the spirit of Guinand-Meyer ..... 66
8.9. The case when $K_{1}, K_{2}$ are points ..... 67
9. Geometric interpretation of the residues ..... 70
9.1. Some simple cases ..... 70
9.2. Volumes in convex geometry ..... 71
10. Equidistribution of the boundary of convex bodies ..... 73
10.1. Lifting the problem to the unit tangent bundle ..... 75
10.2. Equidistribution properties ..... 75
Appendix A. Another formula for zeta functions ..... 79
Acknowledgements ..... 80
References ..... 80

## 1. Introduction

Motivated by recent developments on analytical and spectral properties of geodesic flows on negatively curved manifolds, we study in this article related questions in the opposite setting of a completely integrable system. Such an analysis is now known to have several types of applications ranging from the study of correlation functions to counting problems and equidistribution properties. Before discussing analytical and spectral properties of the geodesic flow on the torus (see Section 2), we thus start by presenting one of their applications in the context of convex geometry.

Let $K_{1}$ and $K_{2}$ be two strictly convex and compact subsets of $\mathbb{R}^{d}(d \geq 2)$ with smooth boundaries $\partial K_{1}$ and $\partial K_{2}$. All along this article, by strictly convex, we mean that the boundary of the convex set $K_{i}$ has all its sectional curvatures positive and we adopt the convention that, if $K$ is reduced to a point, then it is strictly convex with smooth boundary. By a classical Theorem of Hadamard [Had97] and Sacksteder [Sac60], if $S$ is a smooth, compact, connected, orientable hypersurface embedded in $\mathbb{R}^{d}$ and if $S$ has all its sectional curvatures nonnegative, then it is the boundary of a convex body - see also [dCL69].

Through the canonical projection $\mathfrak{p}: \mathbb{R}^{d} \rightarrow \mathbb{T}^{d}:=\mathbb{R}^{d} / 2 \pi \mathbb{Z}^{d}$, the boundaries of $K_{1}$ and $K_{2}$ can be identified with immersed submanifolds of the flat torus that may have selfintersection points. We fix an orientation on each submanifold $\partial K_{i}$ either by the outgoing normal vector to $K_{i}$ or by the ingoing one. This orientation induces an orientation on $\Sigma_{i}:=\mathfrak{p}\left(\partial K_{i}\right)$. The choice of orientation is not necessarily the same on each $\partial K_{i}$ (hence on each $\Sigma_{i}$ ) and, once each orientation is fixed, we denote by $\mathcal{P}_{K_{1}, K_{2}}$ the set of geodesic arcs (parametrized by arc length) on $\mathbb{T}^{d}$ that are directly orthogonal ${ }^{1}$ to $\Sigma_{1}$ and $\Sigma_{2}$. The orientation of the sets $K_{1}, K_{2}$ is implicit in our notation (in the introduction); the results however depend on this choice. Using the strict convexity of $K_{1}$ and $K_{2}$, one can first verify the following statement.
Lemma 1.1. There is $T_{0}>0$ large enough, such for any $T>0$ the subset

$$
\left\{\gamma \in \mathcal{P}_{K_{1}, K_{2}}: T_{0}<\ell(\gamma) \leq T\right\}
$$

of $\mathcal{P}_{K_{1}, K_{2}}$ is finite.

[^0]Note that the complementary set in $\mathcal{P}_{K_{1}, K_{2}}$ might be uncountable, depending on the choice of orientations of $\Sigma_{i}$. We will be interested on the asymptotic properties of the lengths of these orthogeodesics. We shall for instance verify in Theorem 8.12 below that, for $T_{0}>0$ as in Lemma 1.1,

$$
\begin{equation*}
\sharp\left\{\gamma \in \mathcal{P}_{K_{1}, K_{2}}: T_{0}<\ell(\gamma) \leq T\right\}=\frac{\pi^{\frac{d}{2}} T^{d}}{(2 \pi)^{d} \Gamma\left(\frac{d}{2}+1\right)}+\mathcal{O}\left(T^{d-1}\right) \tag{1.1}
\end{equation*}
$$

In the case where $K_{1}=K_{2}=\{0\}$, this exactly amounts to count the number of lattice points in $2 \pi \mathbb{Z}^{d}$ of length less than $T$ and understanding the optimal size of the remainder is a deep problem in number theory. Here, we consider the setting of orthogeodesics for much more general convex sets. Thus, in some sense less arithmetical tools are available and we do not necessarily expect as strong properties on the size of the remainder. In fact, rather than refining these asymptotic formulas, our main purpose is to study various zeta functions associated to these length orthospectra and some of their analytical properties. We also aim at determining the geometric quantities encoded by these functions. Recall that counting orthogeodesics to convex subsets in the setup of hyperbolic geometry was much studied (see e.g. [PP16, BAPP19] and the references therein) and similar questions arise even if the asymptotic formulas are of different nature.
1.1. Epstein zeta functions in convex geometry. The most natural way to form a zeta function starting from $\mathcal{P}_{K_{1}, K_{2}}$ is to define, for $T_{0}>0$ as in Lemma 1.1, a generalized Epstein zeta function:

$$
\begin{equation*}
\zeta_{\beta}\left(K_{1}, K_{2}, s\right):=\sum_{\gamma \in \mathcal{P}_{K_{1}, K_{2}}: \ell(\gamma)>T_{0}} \frac{e^{i \int_{\gamma} \beta}}{\ell(\gamma)^{s}} \tag{1.2}
\end{equation*}
$$

where $\beta$ is a closed and real-valued one form on $\mathbb{T}^{d}$. Recall that any such form writes $\beta=$ $\sum_{i=1}^{d} \beta_{i} d x_{i}+d f$ where $\beta_{i} \in \mathbb{R}$ and $f \in \mathcal{C}^{\infty}\left(\mathbb{T}^{d} ; \mathbb{R}\right)$. The one-form $[\beta]=\sum_{i=1}^{d} \beta_{i} d x_{i}$ is identified with the de Rham cohomology class of $\beta$. The first de Rham cohomology group will be denoted by $H^{1}\left(\mathbb{T}^{d}, \mathbb{R}\right)=H_{\mathrm{dR}}^{1}\left(\mathbb{T}^{d}\right)$ : it corresponds to the kernel of the Laplacian acting on smooth realvalued one-forms and it can be identified with the first singular cohomology group. See [Lee13, Chapter 17 and 18] or [Lee09, Chapter 10]. We shall say that the cohomology class $[\beta]$ of $\beta$ is in $H^{1}\left(\mathbb{T}^{d}, \mathbb{Z}\right)$ if, in the above decomposition, $\beta_{i} \in \mathbb{Z}$ for all $i \in\{1, \ldots, d\}$.

Thanks to (1.1), $s \mapsto \zeta_{\beta}\left(K_{1}, K_{2}, s\right)$ defines a holomorphic function on $\{\operatorname{Re}(s)>d\}$ and our first main result describes its meromorphic continuation to $\mathbb{C}$ :

Theorem 1.2. Let $K_{1}$ and $K_{2}$ be two strictly convex and compact subsets of $\mathbb{R}^{d}(d \geq 2)$ with smooth boundary and let $\beta$ be a closed and real-valued one form on $\mathbb{T}^{d}$. The following holds:
(1) if the cohomology class $[\beta]$ of $\beta$ is in $H^{1}\left(\mathbb{T}^{d}, \mathbb{Z}\right)$, then

$$
s \in\{\operatorname{Re}(s)>d\} \mapsto \zeta_{\beta}\left(K_{1}, K_{2}, s\right)
$$

extends meromorphically to $\mathbb{C}$, its poles are located at $s=1, \ldots, d$ and are simple;
(2) otherwise, $\zeta_{\beta}\left(K_{1}, K_{2}, s\right)$ extends holomorphically to $\mathbb{C}$.

In the case where both $K_{1}$ and $K_{2}$ are reduced to points, this theorem recovers a classical property of Epstein zeta functions [Eps03]. See $\S 1.4 .1$ below for a brief reminder on such arithmetic functions. Yet, to the best of our knowledge, this result seems to be new in the case of general strictly convex subsets.

As for classical zeta functions in number theory, it is natural to compute the explicit values of the residues and, due to the geometric nature of the problem, one would like to express them in terms of natural geometric quantities attached to the convex sets $K_{1}$ and $K_{2}$. In order to be more explicit on the residues when $\beta=0$, recall Steiner's formula for a compact and convex subset $K$ of $\mathbb{R}^{d}[S \operatorname{ch} 14, \S 4]$ :

$$
\begin{equation*}
\text { for all } t>0, \quad \operatorname{Vol}_{\mathbb{R}^{d}}\left(K+t B_{d}\right)=\sum_{\ell=0}^{d} V_{d-\ell}(K) \frac{\pi^{\frac{\ell}{2}}}{\Gamma\left(\frac{\ell}{2}+1\right)} t^{\ell} \tag{1.3}
\end{equation*}
$$

where $V_{\ell}(K) \geq 0$ is the $\ell$-intrinsic volume of the convex set $K$, and (1.3) may be taken as a definition of the numbers $V_{\ell}(K)$. Note that $V_{0}(K)=1, V_{d}(K)=\operatorname{Vol}_{\mathbb{R}^{d}}(K)$. Moreover, if $\partial K$ has smooth boundary, one finds by the Minkowski-Steiner formula [Sch14, 4.2] [Tei16, p. 86]:

$$
V_{d-1}(K)=\frac{1}{2} \operatorname{Vol}(\partial K)
$$

where Vol is the $(d-1)$-volume measure on $\partial K$ induced by the Euclidean structure on $\mathbb{R}^{d}$. Observe that $V_{d-\ell}(K)=0$ for any $0 \leq \ell \leq d-1$ when $K$ is reduced to a point. Other properties of these intrinsic volumes are their invariance under Euclidean isometries (i.e. any composition of a rotation with a translation), their continuity with respect to the Hausdorff metric and their additivity ${ }^{2}$ on convex subsets of $\mathbb{R}^{d}$, i.e.

$$
\forall 0 \leq \ell \leq d, \quad V_{\ell}(K)+V_{\ell}(L)=V_{\ell}(K \cup L)+V_{\ell}(K \cap L)
$$

whenever $K, L, K \cup L, K \cap L$ are convex subsets of $\mathbb{R}^{d}$. In fact, a classical Theorem of Hadwiger states that any functional on the convex subsets of $\mathbb{R}^{d}$ enjoying these three properties is a linear combination of these intrinsic volumes [Sch14, Th. 6.4.14].

Our second main theorem expresses the residues of $\zeta_{0}\left(K_{1}, K_{2}, s\right)$ (stated for $\beta=0$ to improve readability) in terms of these intrinsic volumes:
Theorem 1.3. Let $K_{1}$ and $K_{2}$ be two strictly convex and compact subsets of $\mathbb{R}^{d}(d \geq 2)$ with smooth boundary. Suppose in addition that $\Sigma_{1}=\mathfrak{p}\left(\partial K_{1}\right)$ (resp. $\left.\Sigma_{2}=\mathfrak{p}\left(\partial K_{2}\right)\right)$ is oriented by the outgoing (resp. ingoing) normal vector to $K_{1}$ (resp. $K_{2}$ ).

Then, the function

$$
s \mapsto \zeta_{0}\left(K_{1}, K_{2}, s\right)-\frac{1}{(2 \pi)^{d}} \sum_{\ell=1}^{d} \frac{\pi^{\frac{\ell}{2}} \ell}{\Gamma\left(\frac{\ell}{2}+1\right)} \frac{V_{d-\ell}\left(K_{1}-K_{2}\right)}{s-\ell}
$$

extends holomorphically from $\{\operatorname{Re}(s)>d\}$ to $\mathbb{C}$.
Note that $-K_{2}$ is a convex set and thus so is $K_{1}-K_{2}$. Here we only describe the case where $\beta=0$ and geodesics are pointing outward $K_{1}$ and inward $K_{2}$. Yet our proof yields an explicit expression for any $\beta$ and for more general orientation conditions on the $\Sigma_{i}$. See formula (8.23) and $\S 9$ for more details. For the sake of simplicity, we restricted ourselves to this case here as it has a transparent expression in terms of intrinsic volumes while formulas are more involved in the general case. When $K_{2}$ is reduced to a point, this theorem in particular solves the following geometric inverse problem: recover all $\ell$-intrinsic volumes of $K_{1}$ for $0 \leq \ell \leq d-1$ from the lengths of the geodesics of $\mathbb{R}^{d}$ orthogonal to $K_{1}$ and joining $K_{1}$ to an element of $2 \pi \mathbb{Z}^{d}$ (see Figure 1).


Figure 1. Lift of the orthogeodesic arcs when $K_{2}=\{0\}$.

[^1]1.2. Poincaré series in convex geometry. In analogy with the case of negatively curved manifolds [PP16, BAPP19, DR21], one can also define generalized Poincaré series for the length orthospectrum:
\[

$$
\begin{equation*}
\mathcal{Z}_{\beta}\left(K_{1}, K_{2}, s\right):=\sum_{\gamma \in \mathcal{P}_{K_{1}, K_{2}}: \ell(\gamma)>T_{0}} e^{i \int_{\gamma} \beta-s \ell(\gamma)} \tag{1.4}
\end{equation*}
$$

\]

which, as a consequence of (1.1), is holomorphic on $\{\operatorname{Re}(s)>0\}$. As above, $\beta$ is a closed and real-valued one form on $\mathbb{T}^{d}$. For such functions, we are able to describe the continuation up to $\operatorname{Re}(s)=0$ in the following sense:

Theorem 1.4 (Continuous continuation of Poincaré series). Let $K_{1}$ and $K_{2}$ be two strictly convex and compact subsets of $\mathbb{R}^{d}(d \geq 2)$ with smooth boundary and let $\beta$ be a closed and real-valued one form on $\mathbb{T}^{d}$.

Then, the function

$$
s \in\{\operatorname{Re}(s)>0\} \mapsto \mathcal{Z}_{\beta}\left(K_{1}, K_{2}, s\right)
$$

extends continuously to

$$
\{\operatorname{Re}(s) \geq 0\} \backslash\left\{ \pm i|\xi-[\beta]|: \xi \in \mathbb{Z}^{d}\right\}
$$

Moreover, given $\xi_{0} \in \mathbb{Z}^{d}$, one has
(1) if $\xi_{0}-[\beta]=0$, then there exist $a_{\beta}^{(1)}\left(K_{1}, K_{2}\right), \ldots, a_{\beta}^{(d)}\left(K_{1}, K_{2}\right)$ in $\mathbb{C}$ such that

$$
\mathcal{Z}_{\beta}\left(K_{1}, K_{2}, s\right)-\sum_{\ell=1}^{d} \frac{a_{\beta}^{(\ell)}\left(K_{1}, K_{2}\right)}{s^{\ell}}
$$

converges as $s \rightarrow 0$ (with $\operatorname{Re}(s)>0)$;
(2) if $\xi_{0}-[\beta] \neq 0$ and $d$ is odd, then there exist $a_{\xi_{0}, \beta}^{(0)}\left(K_{1}, K_{2}\right), \ldots, a_{\xi_{0}, \beta}^{\left(\frac{d-1}{2}\right)}\left(K_{1}, K_{2}\right)$ and $b_{\xi_{0}, \beta}\left(K_{1}, K_{2}\right)$ in $\mathbb{C}$ such that

$$
\mathcal{Z}_{\beta}\left(K_{1}, K_{2}, s\right)-\sum_{\ell=0}^{\frac{d-1}{2}} \frac{a_{\xi_{0}, \beta}^{(\ell)}\left(K_{1}, K_{2}\right)}{\left(s \mp i\left|\xi_{0}-[\beta]\right|\right)^{\frac{d+1}{2}-\ell}}-b_{\xi_{0}, \beta}\left(K_{1}, K_{2}\right) \ln \left(s \mp i\left|\xi_{0}-[\beta]\right|\right)
$$

converges as $s \rightarrow \pm i\left|\xi_{0}-[\beta]\right|$ (with $\left.\operatorname{Re}(s)>0\right)$;
(3) if $\xi_{0}-[\beta] \neq 0$ and $d$ is even, then there exist $a_{\xi_{0}, \beta}^{(0)}\left(K_{1}, K_{2}\right), \ldots, a_{\xi_{0}, \beta}^{(d / 2)}\left(K_{1}, K_{2}\right)$ such that

$$
\mathcal{Z}_{\beta}\left(K_{1}, K_{2}, s\right)-\sum_{\ell=0}^{\frac{d}{2}} \frac{a_{\xi_{0} \beta}^{(\ell)}\left(K_{1}, K_{2}\right)}{\left(s \mp i\left|\xi_{0}-[\beta]\right|\right)^{\frac{d+1}{2}-\ell}} .
$$

converges as $s \rightarrow \pm i\left|\xi_{0}-[\beta]\right|$ (with $\left.\operatorname{Re}(s)>0\right)$.
This Theorem is a weakened version of Theorem 8.17 where the $\mathcal{C}^{k}$ regularity of the continuation of $\mathcal{Z}_{\beta}$ will also be discussed. Note that the set of singular points $\left\{ \pm i|\xi-[\beta]|: \xi \in \mathbb{Z}^{d}\right\}$ is linked to the spectrum of a natural magnetic Laplacian on $\mathbb{T}^{d}$, namely ${ }^{3} \Delta_{-[\beta]}=\left(\partial_{x}-i[\beta]\right)^{2}-$ see the discussion in Sections 2.4 and 5.2.2. For $\beta=0$ and for the orientation conventions of Theorem 1.3, the "residues" at $s=0$ can be explicitly expressed as

$$
\forall 1 \leq \ell \leq d, \quad a_{0}^{(\ell)}:=\frac{(-1)^{d-1} \ell!\pi^{\frac{d}{2}}}{(2 \pi)^{d} \Gamma\left(\frac{\ell}{2}+1\right)} V_{d-\ell}\left(K_{1}-K_{2}\right)
$$

[^2]1.3. Application to Poisson type formulas. According to (1.1), and for $T_{0}>0$ as in Lemma 1.1 above, we emphasize that, on the imaginary axis, the Poincaré series
\[

$$
\begin{equation*}
\mathcal{Z}_{\beta}\left(K_{1}, K_{2}, i t\right)=\sum_{\gamma \in \mathcal{P}_{K_{1}, K_{2}}: \ell(\gamma)>T_{0}} e^{i \int_{\gamma} \beta} e^{-i t \ell(\gamma)} \tag{1.5}
\end{equation*}
$$

\]

is the Fourier transform of the counting measure

$$
\begin{equation*}
\mathrm{T}_{\beta, K_{1}, K_{2}}(t):=\sum_{\gamma \in \mathcal{P}_{K_{1}, K_{2}}: \ell(\gamma)>T_{0}} e^{i \int_{\gamma} \beta} \delta(t-\ell(\gamma)) \quad \in \mathcal{S}^{\prime}(\mathbb{R}) \tag{1.6}
\end{equation*}
$$

which is a tempered distribution supported in the cone $(0,+\infty)$. Therefore, thanks to [RS75, Thm IX. 16 p. 23] (see also Proposition 7.5 below), $\widehat{\top}_{\beta, K_{1}, K_{2}}(t)$ can be obtained as the boundary value of a holomorphic function as follows:

$$
\begin{equation*}
\mathcal{Z}_{\beta}\left(K_{1}, K_{2}, i t+\alpha\right) \rightharpoonup \widehat{\mathrm{T}}_{\beta, K_{1}, K_{2}}(t) \quad \text { in } \mathcal{S}^{\prime}(\mathbb{R}), \quad \text { as } \alpha \rightarrow 0^{+} \tag{1.7}
\end{equation*}
$$

The holomorphic function is nothing but the analytic extension of the Fourier transform to the upper half-plane. Hence, the reader can think of Theorem 1.4 as a loose version of the Paley-Wiener-Schwartz Theorem, stating that the Fourier transform of a distribution supported on the half-line $(0,+\infty)$ is the boundary value on $\mathbb{R}$ of a holomorphic function on the lower halfplane (sometimes called its Fourier-Laplace transform). Note that, as a consequence of (1.7), the Poincaré series completely determines the distribution of the twisted length orthospectrum.

Remark 1.5. In case $\beta=0, \mathrm{~T}_{0, K_{1}, K_{2}}$ gives precisely the distribution of length of orthogeodesics: namely if $\mathcal{L}\left(K_{1}, K_{2}\right)=\left\{\ell(\gamma), \gamma \in \mathcal{P}_{K_{1}, K_{2}}\right\}$ denotes the set of length of orthogeodesics, then we simply have

$$
\begin{equation*}
\mathrm{T}_{0, K_{1}, K_{2}}(t):=\sum_{\ell>T_{0}, \ell \in \mathcal{L}\left(K_{1}, K_{2}\right)} \mathrm{m}_{\ell} \delta(t-\ell), \quad \text { where } \mathrm{m}_{\ell}=\sharp\left\{\gamma \in \mathcal{P}_{K_{1}, K_{2}}, \ell(\gamma)=\ell\right\} \tag{1.8}
\end{equation*}
$$

denotes the multiplicity of the length $\ell \in \mathcal{L}\left(K_{1}, K_{2}\right)$.
As a direct application of a refined version of Theorem 1.4 (namely Theorem 8.17 below) together with (1.7), we also obtain a new Poisson-type summation formulas, describing the distributional singularities of $\widehat{T}$.

Theorem 1.6 (Poisson type formula). Let $K_{1}$ and $K_{2}$ be two strictly convex and compact subsets of $\mathbb{R}^{d}(d \geq 2)$ with smooth boundary and let $\beta$ be a closed and real-valued one form on $\mathbb{T}^{d}$. Then, with $\mathrm{T}_{\beta, K_{1}, K_{2}}(\tau)$ defined in (1.6), the singular support of

$$
\widehat{\mathbf{T}}_{\beta, K_{1}, K_{2}}(\tau)=\sum_{\gamma \in \mathcal{P}_{K_{1}, K_{2}}: \ell(\gamma)>T_{0}} e^{i \int_{\gamma} \beta} e^{-i \tau \ell(\gamma)}
$$

is included in $\mathrm{Sp}\left( \pm \sqrt{-\Delta_{[\beta]}}\right)$ and the singularities are explicitly described by Theorem 8.17.
Here, we recall that the complementary of the singular support of a distribution $T$ is the open set where the distribution is smooth. In particular, the singular support of the geometric distribution $\widehat{\mathrm{T}}_{\beta, K_{1}, K_{2}}$ is given by the eigenvalues of the magnetic Laplacian and it does not depend on the convex sets $K_{1}, K_{2}$. We would like to remark that Theorem 1.6 looks like a trace formula and we refer to paragraph 1.4.2 for a more detailed comparison. The precise form of the singularity depends on the geometry of the convex sets $K_{1}$ and $K_{2}$ - see Theorem 8.17 for precise expressions of the leading term at each singularity. We emphasize that the singularities are obtained as the boundary values of simple holomorphic functions as in [Hör03, Th.3.1.11].

In view of having simpler singularities and motivated by the recent developments on crystalline measures [Mey22], one can symmetrize (and renormalize) the distribution $\mathrm{T}_{\beta, K_{1}, K_{2}}(t)$. This is the content of our last main result which extends in our geometric setup the Guinand-Meyer summation formula [Mey16, Th. 5].

Theorem 1.7 (Guinand-Meyer type formula). Let $K_{1}$ and $K_{2}$ be two strictly convex and compact subsets of $\mathbb{R}^{d}(d \geq 2)$ with smooth boundary and let $\beta$ be a closed and real-valued one form on $\mathbb{T}^{d}$ such that $[\beta] \notin H^{1}\left(\mathbb{T}^{d}, \mathbb{Z}\right)$. Let $\mu$ be the signed measure defined as

$$
\mu(t)=\sum_{\gamma \in \mathcal{P}_{K_{1}, K_{2}}: \ell(\gamma)>T_{0}} \frac{e^{i \int_{\gamma} \beta}}{\ell(\gamma)^{\frac{d-1}{2}}} \delta(t-\ell(\gamma))+(-i)^{d-1} \sum_{\gamma \in \mathcal{P}_{K_{2}, K_{1}}: \ell(\gamma)>T_{0}} \frac{e^{-i \int_{\gamma} \beta}}{\ell(\gamma)^{\frac{d-1}{2}}} \delta(t+\ell(\gamma)),
$$

where we take the same orientation conventions for ${ }^{4} \mathcal{P}_{K_{2}, K_{1}}$ and $\mathcal{P}_{K_{1}, K_{2}}$.
Then, there exist complex numbers $\left(c_{\lambda}\right)_{\lambda \in \operatorname{Sp}\left( \pm \sqrt{-\Delta_{[\beta]}}\right)}$ and $r$ belonging to $L_{\mathrm{loc}}^{p}(\mathbb{R})$ for every $1 \leq p<\infty$ such that

$$
\widehat{\mu}(\tau)=\sum_{\lambda \in \operatorname{Sp}\left( \pm \sqrt{-\Delta_{[\beta]}}\right)} c_{\lambda} \delta(\tau-\lambda)+r
$$

In the case where $\beta \in H^{1}\left(\mathbb{T}^{d}, \mathbb{Z}\right)$, the result would be similar except for an extra singularity of the Fourier transform at $\tau=0$ that may be more singular than the Dirac distribution. Following our proof, one could in fact describe explicitly this singularity at $\tau=0$ even if we do not carry out the calculation explicitly. In the case where $K_{1}$ and $K_{2}$ are distinct points and where $d=3$, it was in fact proved that $r \equiv 0$ in [Mey16, Th. 5]. The proof of this last fact is briefly recalled in §8.9.2 using our formalism. We also explain how it can be extended to higher dimensions (when $d$ is odd) to give rise to crystalline distributions, as first shown in [LR21, §2]. We finally deduce from this discussion that $r$ is not identically 0 as soon as $d \geq 5$, even in the case where $K_{1}, K_{2}$ are points. See also [Gui59, LO16, RV19] for earlier related results and [Mey22] for a review on recent developments in that direction.
1.4. Related results. Before discussing the relation of these results to the analytical properties of geodesic flows, let us comment how these applications to zeta functions and Poisson formulas in convex geometry compare with similar properties and objects appearing in different contexts, most notably in arithmetic, spectral geometry and hyperbolic geometry.
1.4.1. Comparison with zeta functions from analytic number theory. The zeta functions appearing in Theorem 1.2 are natural generalizations in the setup of convex geometry of the Hurwitz zeta function [Apo98, Ch. 12]:

$$
\zeta_{\mathrm{Hur}}(q, s):=\sum_{\xi \in \mathbb{Z}: \xi \neq-q} \frac{1}{|\xi+q|^{s}},
$$

where $q$ is some fixed element in $[0,1)$. In the case $q=0$, this is nothing else than twice the Riemann zeta function $\zeta_{R}(s)$. It is well known that these functions extend meromorphically from $\{\operatorname{Re}(s)>1\}$ to $\mathbb{C}$ with a simple pole at $s=1$ whose residue is equal to 2 . The relation with our zeta functions is as follows. Assume that both $K_{1}$ and $K_{2}$ are points in $\mathbb{T}^{1}=\mathbb{R} / 2 \pi \mathbb{Z}$ that are at a distance $\ell=2 \pi \min \{q, 1-q\}$ of each other. Then, one can verify that $\zeta_{0}\left(K_{1}, K_{2}, s\right)=$ $(2 \pi)^{-s} \zeta_{\text {Hur }}(q, s)$. The fact that we are in higher dimensions is responsible for the presence of extra poles at $s=1, \ldots d$ and Theorem 1.3 gives us an explicit expression of their residues in terms of geometric quantities. Due to our use of stationary phase arguments, we note that our proof does not work (strictly speaking) for $d=1$ even if the functions are of the same nature from the perspective of convex geometry.

Here we choose to call our functions generalized Epstein zeta functions in analogy with the zeta functions defined by Epstein [Eps03, Eq. (2)] as higher-dimensional analogues of the Riemann zeta function:

$$
\zeta_{\mathrm{Eps}}(q, \beta, s):=\sum_{\xi \in \mathbb{Z}^{d} \backslash\{-q\}} \frac{e^{2 i \pi \xi \cdot \beta}}{|\xi+q|^{s}}
$$

[^3]where $q$ and $\beta$ are two fixed elements in $\mathbb{R}^{d}$ and |.| is the Euclidean norm. When $K_{1}$ and $K_{2}$ are reduced to two points $x_{1}$ and $x_{2}$, one has
$$
\zeta_{\mathrm{Eps}}\left(\frac{x_{2}-x_{1}}{2 \pi}, \beta, s\right)=(2 \pi)^{s} e^{i\left(x_{1}-x_{2}\right) \cdot \beta} \zeta_{\beta}\left(K_{1}, K_{2}, s\right),
$$
where $\beta \in \mathbb{R}^{d}$ is identified with a closed one form, and $\zeta_{\beta}$ is defined in (1.2). Hence, up to a multiplicative factors, our zeta functions $\zeta_{\beta}\left(K_{1}, K_{2}, s\right)$ are the natural extension of Epstein zeta functions when one considers general convex subsets of $\mathbb{R}^{d}$ instead of points. It is well-known that the "classical" Epstein zeta functions extend meromorphically to the whole complex plane with at most a simple pole at $s=d$. Theorems 1.2 and 1.3 show that, for more general convex sets, one may also have poles at $s=1, \ldots, d-1$. Note that we recover the continuation of the "classical" Epstein case since, if $K_{1}, K_{2}$ are both points, $V_{\ell}\left(K_{1}-K_{2}\right)=0$ for all $1 \leq \ell \leq d-1$.

In Theorem 1.2, we saw that if we weight our series with some unitary twist involving a closed and real-valued one form $\beta$, then our zeta functions have in fact a holomorphic extension as soon as $[\beta] \notin H^{1}\left(\mathbb{T}^{d}, \mathbb{Z}\right)$. These unitary twists can be thought of as geometric analogues of the (arithmetic) twisting factors used when one extends the Riemann zeta function to more general Dirichlet series [Apo98, Ch. 12]. Recall that these are defined in the following manner. Fix a positive integer $D$ and a morphism $\chi:(\mathbb{Z} / D \mathbb{Z})^{*} \rightarrow \mathbb{S}^{1}:=\{z \in \mathbb{Z}:|z|=1\}$ (the Dirichlet character). Such a morphism can be extended into a $D$-periodic function $\chi: \mathbb{Z} \rightarrow \mathbb{S}^{1}$ by letting $\chi(\xi)=0$ for every $\xi$ such that $\xi$ and $D$ are not coprime. Dirichlet series (or $L$-functions of weight $\chi)$ are then defined as

$$
L(\chi, s):=\sum_{\xi \in \mathbb{Z}^{*}} \frac{\chi(\xi)}{|\xi|^{s}}=\sum_{r=1}^{D} \sum_{q \in \mathbb{Z} \backslash\{-r / D\}} \frac{\chi(q D+r)}{|q D+r|^{s}}=\frac{1}{D^{s}} \sum_{r=1}^{D} \chi(r) \zeta_{\mathrm{Hur}}\left(s, \frac{r}{D}\right)
$$

and they have a holomorphic extension to $\mathbb{C}$ except for the trivial character $\chi=1$ where one has a simple pole at $s=1$. Understanding the holomorphic continuation of more general $L$ functions [Art24] on algebraic number fields (for arbitrary irreducible representations) is in fact a classical topic in analytic number theory: this is for instance at the heart of Artin's conjecture. Here, we emphasize that our unitary twists do not have any particular arithmetic meaning and our (strictly) convex sets are a priori arbitrary. Despite that and thus for seemingly different reasons, these twisting factors have the same effect as Dirichlet characters for the Riemann zeta function in the sense that, under some natural "non-rationality" assumption on $\beta$, our zeta functions extend holomorphically to $\mathbb{C}$.
1.4.2. Relation with trace formulas. Our main result on the singular support of the oscillatory series $\widehat{\mathrm{T}}_{0, K_{1}, K_{2}}(t)=\sum_{\gamma} e^{-i t \ell(\gamma)}$ is very reminiscent to the celebrated wave trace formula proved by Chazarain [Cha74] and Duistermaat-Guillemin [DG75] extending previous results by Selberg [Sel56] and Colin de Verdière [CdV73]. These formulas may be seen as generalizations in spectral geometry of the Poisson summation formula, letting $\operatorname{Sp}\left(\sqrt{-\Delta_{g}}\right)$ denote the spectrum of the square root of the Laplace-Beltrami operator $\Delta_{g}$, one considers the series

$$
\widehat{\mathrm{T}}(t)=\sum_{\lambda \in \operatorname{Sp}\left(\sqrt{-\Delta_{g}}\right)} e^{-i t \lambda} \in \mathcal{S}^{\prime}(\mathbb{R})
$$

which converges in tempered distributions thanks to the Weyl law. The wave trace formula states that the singular support of the distribution $\widehat{T}$ is exactly the set of lengths of periodic geodesic curves for the metric $g$. Furthermore, when the geodesic flow is nondegenerate, they described the singularity of $\widehat{T}$ at each period in terms of geometric data attached to the periodic orbits and of distributions of the form $(t \pm \ell+i 0)^{-1}$. In other words, the quantum spectrum determines the classical length spectrum and these wave trace formulas are often referred as generalized Poisson formulas. Recall from [Hör03, p.72] that the singularities in this formula can also be rewritten as follows

$$
\begin{equation*}
\lim _{y \rightarrow 0^{+}} \frac{1}{t \pm \ell+i y}=(t \pm \ell+i 0)^{-1}=\mathrm{FP}\left(\frac{1}{t \pm \ell}\right)-i \pi \delta(t \pm \ell) \tag{1.9}
\end{equation*}
$$

where $\mathrm{FP}($.$) is the finite part of the (non-integrable) function (t \pm \ell)^{-1}$.
Theorem 1.6 has a similar flavour except that the correspondence is in the other sense and that it involves orthogeodesics of two given convex sets. More precisely, we start from the length orthospectrum between two convex sets, we then form the series $\widehat{\mathrm{T}}_{\beta, K_{1}, K_{2}}(t)=\sum_{\gamma} e^{i \int_{\gamma} \beta} e^{-i t \ell(\gamma)}$, and its singular support coincides with the quantum spectrum $\operatorname{Sp}\left( \pm i \sqrt{-\Delta_{[\beta]}}\right)$ where $\Delta_{[\beta]}$ is the magnetic Laplacian. Another notable difference is that the singularities are more complicated in the sense that they involve distributions of the form $(t \pm \lambda-i 0)^{-k}$ with $k \geq 1$ that may not even be an integer if $d$ is even. We emphasize from (1.9) that, as in the Chazarain-DuistermaatGuillemin formula, the singularities of $\widehat{T}_{\beta, K_{1}, K_{2}}$ are not purely Dirac type distributions (and their derivatives). This is due to the fact that the counting measure $T_{\beta, K_{1}, K_{2}}$ is supported on the half-line, hence its Fourier transform $\mathcal{Z}_{\beta, K_{1}, K_{2}}(i t)$ must have its ( $C^{\infty}$ and analytic) wave front set contained in the half cotangent cone $\{(t ; \tau) ; \tau<0\} \subset T^{*} \mathbb{R}$. This prevents the presence of purely $\delta^{(k)}(t)$-like singularities whose contribution to the wave front set would contain both positive and negative frequencies $\tau$.

As alluded above, the formulation in Theorem 1.7 is itself motivated by recent developments on crystalline measures [Mey22], i.e. measures on $\mathbb{R}$ carried by a discrete locally finite set, belonging to $\mathcal{S}^{\prime}(\mathbb{R})$, whose Fourier transform is still a measure carried by a discrete locally finite set. Here, we started from a complex valued measure carried by a discrete locally finite set on $\mathbb{R}$ (defined from our convex orthospectrum) and we ended up with a Radon measure carried by the spectrum of the magnetic Laplacian (which is a discrete locally finite set) modulo some (absolutely continuous) remainder lying in $L_{\mathrm{loc}}^{p}$. Hence, in general, it does not fall into the category of crystalline measures due to this a priori nonvanishing remainder.
1.4.3. Poincaré series on negatively curved manifolds. Poincaré series appear naturally when one studies counting problems on a negatively curved manifold $(M, g)$ [PP16, BAPP19]. In that context, one aims for instance at couting the number of common perpendicular geodesic curves of two convex subsets of the universal cover $(\tilde{M}, \tilde{g})$. Due to the exponential growth of the number of such orthogeodesics, it is natural to consider $e^{-s \ell(\gamma)}$ rather than $\ell(\gamma)^{-s}$ in order to ensure the convergence of the sums. The study of the meromorphic continuation of Poincaré series on compact manifolds of constant negative curvature goes back to the works of Huber in the late fifties [Hub56, Satz A], [Hub59, Satz 2]. In that setting, one can obtain the meromorphic continuation through the relation between Poincaré series and the spectral decomposition of the Laplacian. In the case of variable negative curvature, the relation with the Laplacian is less explicit and one rather needs to exploit the ergodic properties of the geodesic flow directly. This approach was initiated by Margulis in [Mar69, Mar04]. Using this dynamical approach and the theory of Pollicott-Ruelle resonances, two of the authors recently proved the meromorphic continuation of Poincaré series on manifolds of variable negative curvature [DR21]. Here, as in the works of Huber, we will use the tools from harmonic analysis that are available on the torus to study the continuation of Poincaré series. Yet, rather than making the connection with the Laplacian ${ }^{5}$, we will directly study the analytical properties of the geodesic flow on the torus when acting on spaces of distributions with anisotropic regularity as it was the case for negatively curved manifolds. See $\S 2.2$ for more details. In the negatively curved setting, it is shown in [DR21] that one has meromorphic continuation beyond the threshold $\operatorname{Re}(s)=h_{\text {top }}$. In the case of the flat torus, Theorem 1.4 shows that there is barrier at $\operatorname{Re}(s)=h_{\text {top }}=0$ where logarithmic or square root singularities may occur at certain points that correspond to the eigenvalues of the (magnetic) Laplacian. Outside these singularities, we are however able to continuously/smoothly extend the function up to $\operatorname{Re}(s)=0$. As already alluded, our study is intimately related to the analytic properties of the geodesic vector field

$$
\begin{equation*}
V:=\theta \cdot \partial_{x} \tag{1.10}
\end{equation*}
$$

on the unit tangent bundle

$$
S \mathbb{T}^{d}:=\left\{(x, \theta) \in \mathbb{T}^{d} \times \mathbb{S}^{d-1}\right\}
$$

[^4]When studying the resolvent of this operator, we will verify that there is a barrier at $\operatorname{Re}(s)=0$ when trying to make some analytic continuation. This phenomenon is retated to observations made by Dyatlov and Zworski at the end of the introduction of [DZ15], where stochastic perturbations of geodesic vector fields on Anosov manifolds are studied. In that reference, the authors studied stochastic perturbations of geodesic vector fields on Anosov manifolds. In the opposite setup of the flat 2-torus, they described the spectrum of $P_{\epsilon}:=V+\epsilon \Delta_{S \mathbb{T}^{2}}$ (with $V$ given by (1.10)) and they observed that, in the limit $\epsilon \rightarrow 0^{+}$, the spectrum of $P_{\epsilon}$ fills $Y$-shaped lines in the halfplane $\{\operatorname{Re}(s) \leq 0\}$ that are based at the same singularities as our Poincaré series. See e.g. Figure 3 in that reference and the companion article [DGBLR22] for more details on this issue.
1.4.4. Orthospectrum identities in hyperbolic geometry. Finally, let us mention the following related problem in hyperbolic geometry. Consider some hyperbolic manifold $X$ with nonempty totally geodesic smooth boundary. In that framework, an orthogeodesic $\gamma$ is a geodesic arc which is properly immersed in $X$ and which is perpendicular to $\partial X$ at its endpoints. The lengths of these orthogeodesics verify certain identities connecting them to the volume of the boundary of $X$ (Basmajian's identity) [Bas93]:

$$
\operatorname{Vol}(\partial X)=\sum_{\gamma} V_{d-1}\left(\ln \left(\operatorname{coth} \frac{\ell(\gamma)}{2}\right)\right)
$$

where $V_{d-1}(r)$ is the volume of a ball of radius $r$ on the hyperbolic space $\mathbb{H}^{d-1}$ (with the convention that $\left.V_{1}(r)=2 r\right)$. Similar equalities also relate this length orthospectrum with the volume of the unit tangent bundle $S X$ (Bridgeman-Kahn's identity [BK10]) and the analogues of these results on manifolds with cusps are due to McShane [McS91, McS98]. We refer to [BT16] for a recent review on this topic. In some sense, this formula has the same flavour as Theorem 1.3 as it relates some length orthospectrum with some volumes associated with our convex. However, while the righthand side of Basmajian's identity converges in a standard sense, our zeta functions are defined by analytic continuation and the volumes appear as the residues of these functions.

## 2. Analytical Results: a functional setup for the geodesic vector field

Let us now discuss the relation of these problems from convex geometry with the analytical properties of geodesic flows on flat tori and come to the statement of our main analytical results. For simplicity, we now restrict ourselves to the case where $\beta=0$ and where we look at geodesic arcs pointing outside $K_{1}$ and inside $K_{2}$ (as in Theorem 1.3).
2.1. Lifting the problem to the unit tangent bundle. In order to prove Theorems 1.2, 1.3 and 1.4 , one way is to rewrite the series we are interested in under an integral form as follows:

$$
\begin{equation*}
\sum_{\gamma \in \mathcal{P}_{K_{1}, K_{2}}} \chi(\ell(\gamma))=\int_{\mathbb{R}^{d}} \delta_{[0]}(x)\left(\int_{0}^{+\infty} \chi(t) \delta_{\partial\left(K_{1}-K_{2}+t B_{d}\right)}(x,|d x|)|d t|\right) \tag{2.1}
\end{equation*}
$$

where $\chi$ is a nice enough function on $\mathbb{R}_{+}^{*}$ (in the applications we have in mind, $\chi \in \mathcal{C}_{c}^{\infty}\left(\mathbb{R}_{+}^{*}\right)$ or $\chi(t)=t^{-s}$ or $\left.\chi(t)=e^{-s t}\right)$, where $\delta_{\partial\left(K_{1}-K_{2}+t B_{d}\right)}(x,|d x|)$ is the volume measure on $\partial\left(K_{1}-K_{2}+t B_{d}\right)$ induced by the Euclidean structure on $\mathbb{R}^{d}$ and where

$$
\begin{equation*}
\delta_{[0]}(x)=\frac{1}{(2 \pi)^{d}} \sum_{\xi \in \mathbb{Z}^{d}} e^{i \xi \cdot x} \tag{2.2}
\end{equation*}
$$

A precise signification of the right hand-side of (2.1) together with a proof of this formula are given in Appendix A. With that expression at hand, proving our main results on convex geometry amounts to discuss the allowed functions $\chi$ in (2.1), to decompose $\delta_{[0]}$ according to (2.2) and to analyze the oscillatory integrals that come out. Yet, as explained in the beginning of the article, rather than doing that directly, we will obtain these results as a by-product of a more general analysis ${ }^{6}$ of the geodesic vector field on $S \mathbb{T}^{d}$. In fact, since the seminal work of Margulis [Mar69, Mar04], it is well understood that on negatively curved manifolds, it is convenient to lift this kind

[^5]of geometric problems to the unit cotangent bundle of the manifold. For instance, properties of Poincaré series are related to the asymptotic properties of the geodesic flow, and more specifically to its mixing properties. In a recent work [DR21], two of the authors formulated this relation using the theory of De Rham currents and we will see that this still makes sense in the case of flat tori where the curvature vanishes everywhere. See Section 8 for details. Let us explain this connection without being very precise on the sense of the various integrals. We denote by $N\left(K_{i}\right)$ the outward unit normal to $K_{i}$ inside $S \mathbb{T}^{d}$ :
$$
N\left(K_{i}\right):=\left\{(\mathfrak{p}(x), d \mathfrak{p}(x) \theta), x \in \partial K_{i}, \theta \text { directly orthogonal to } \partial K_{i} \text { at } x\right\}
$$

Then, given any nice enough function $\chi(t)$ (say again in $\mathcal{C}_{c}^{\infty}\left(\mathbb{R}_{+}^{*}\right), t^{-s}$ or $e^{-s t}$ ), we shall prove that

$$
\begin{equation*}
\sum_{\gamma \in \mathcal{P}_{K_{1}, K_{2}}} \chi(\ell(\gamma))=(-1)^{d-1} \int_{S \mathbb{T}^{d}}\left[N\left(K_{1}\right)\right] \wedge \int_{\mathbb{R}} \chi(t) \iota_{V} e^{-t V *}\left[N\left(K_{2}\right)\right]|d t| . \tag{2.3}
\end{equation*}
$$

where $\left[N\left(K_{i}\right)\right]$ is the current of integration on $N\left(K_{i}\right)$ and where

$$
e^{t V}:(x, \theta) \in S \mathbb{T}^{d} \rightarrow(x+t \theta, \theta) \in S \mathbb{T}^{d}
$$

is the geodesic flow. Compared with (2.1), this new formula has the advantage to explicitly involve the geodesic vector field. This current theoretic approach also allows to deal directly with the exponential weights appearing in our zeta functions together with the more general orientation conventions considered in the introduction. On the contrary, the approach using (2.1) (performed in Appendix A) seems to only apply (at least directly) to the outgoing/ingoing convention of Theorem 1.3.

Remark 2.1. Formula (2.3) derives from the observation that elements in $\mathcal{P}_{K_{1}, K_{2}}$ are in one-to-one correspondance with the geodesic orbits in $S \mathbb{T}^{d}$ joining the two Legendrian submanifolds $N\left(K_{1}\right)$ and $N\left(K_{2}\right)$. In the framework of symplectic topology, such orbits are referred as the Reeb chords of these two Legendrian submanifolds.
2.2. Defining a proper functional framework for the geodesic flow. Hence, rather than proceeding directly to the calculation of zeta functions from (2.1), we choose to view this as a consequence of analytical properties of geodesic vector fields. More precisely, we will define appropriate functional frameworks to study the operators appearing in (2.3):

$$
\widehat{\chi}(-i V):=\int_{\mathbb{R}} \chi(t) e^{-t V *}|d t|
$$

where $\chi$ is a nice enough function (say $e^{-s t}$ or $t^{-s}$ ). In the end, our main geometrical theorems on length orthospectra for convex bodies will be simple corollaries of this analysis - see Section 8. Even if slightly longer, we believe that this sharp analysis, which is the content of Sections 4 to 7, is interesting on its own and that it allows to capture the dynamical mechanism at work when proving this kind of results. Along the way, it also has the advantage to apply directly to other questions such as equidistribution properties of the geodesic flow. See Theorems 2.5, 5.5 or 10.1 for instance.

On top of these applications, this analysis is motivated by the study of similar questions arising on negatively curved manifolds where one defines appropriate spaces of anisotropic Sobolev distributions in order to make sense of the spectrum of the geodesic vector field: the so-called Pollicott-Ruelle spectrum [Rue76, Pol85]. More precisely, given any $N>0$, one aims at defining a Banach space $\mathcal{B}_{N}$ such that the geodesic vector field (viewed as an unbounded order 1 differential operator) has discrete spectrum on $\{\operatorname{Re}(s)>-N\}$. One of the difficulties when analyzing such an operator on the unit tangent bundle $S X$ of some manifold $(X, g)$ is that its symbol $H(x, \theta ; \xi)=\xi(V(x, \theta))$ is not elliptic and that it vanishes on the noncompact set:

$$
\mathcal{C}:=\left\{(x, \theta ; \xi) \in T^{*} S X: \xi(V(x, \theta))=0\right\}
$$

In the case of a negatively curved manifold, this characteristic region is generated by two subbundles: the unstable direction and the stable one. Using this duality, one is able to construct Banach (or Hilbert) spaces adapted to the operator $V$ by requiring some negative (resp. positive) Sobolev regularity along the unstable (resp. stable) direction and by exploiting the contraction
properties along these directions. The construction of such functional spaces was made explicit through different methods in various geometric contexts: Anosov flows [Liv04, BL07, Tsu10, FS11, Tsu12, GLP13, DZ16, FT17b], Axiom A flows [DG16, Med21], billiard dynamics [BDL18, BD20], Morse-Smale flows [DR20], manifolds with cusps [GBW17], analytic Anosov flows [Jéz21, GBJ20], etc. We also refer the reader to [Bal18] for a detailed account of the (related) case of hyperbolic diffeomorphisms.

In our framework, the geodesic flow does not belong to any of these classes of flows as it is an integrable dynamical system without any hyperbolic property. Despite that and using the fact that the curvature is 0 (and thus nonpositive), there is a notion of stable and unstable bundles [Rug07, Ch. 3]. Yet, as opposed to the negatively curved setting, both bundles are equal and they do not generate the whole characteristic region. They correspond in fact to the tangent space to $\mathbb{T}^{d}$ intersected with $\mathcal{C}$. See $\S 5.3 .1$ for details. As we shall recall in $\S 5.3 .1$, this bundle is in some sense attractive/repulsive for the lifted dynamics on the cotangent bundle to $S X$. This observation is somehow enough to implement the same ideas (with of course also some major differences) as for geodesic flows on negatively curved manifolds and in order to define spaces with anisotropic regularity adapted to the geodesic flow on $S \mathbb{T}^{d}$. On $S \mathbb{T}^{d}$, the "mixing" properties of the geodesic flow are much weaker than for geodesic flows on negatively curved manifolds, but they turn out to be sufficient in view of proving our main results using formula (2.3). To that aim, we will use tools from harmonic analysis that are available on the torus in order to construct the spaces adapted to $V$. In this respect, our approach is in some sense reminiscent of the one used by Ratner [Rat87] to study the decay of correlations on hyperbolic surfaces. Even though anisotropic Sobolev spaces are not explicitly mentioned in her analysis, the Fourier type reduction made in [Rat87, §2] and the way it is handled there is close to the strategy we will follow in Sections 3 and 4 of the present work.
2.3. Anisotropic Sobolev spaces. Let us now describe more precisely the analytical properties we are aiming at in the simplified setting where we consider functions rather than currents of integrations as in (2.3). We define anisotropic Sobolev spaces of distributions on $S \mathbb{T}^{d}$ as follows

$$
\mathcal{H}^{M, N}\left(S \mathbb{T}^{d}\right):=\left\{u \in \mathcal{D}^{\prime}\left(S \mathbb{T}^{d}\right): \sum_{\xi \in \mathbb{Z}^{d}}\langle\xi\rangle^{2 N}\left\|\widehat{u}_{\xi}\right\|_{H^{M}\left(\mathbb{S}^{d-1}\right)}^{2}<+\infty\right\}, \quad\langle\xi\rangle=\left(1+|\xi|^{2}\right)^{\frac{1}{2}}
$$

where $(M, N) \in \mathbb{R}^{2}$ and

$$
u(x, \theta)=\sum_{\xi \in \mathbb{Z}^{d}} \widehat{u}_{\xi}(\theta) \frac{e^{i \xi \cdot x}}{(2 \pi)^{\frac{d}{2}}},
$$

with $\widehat{u}_{\xi} \in \mathcal{D}^{\prime}\left(\mathbb{S}^{d-1}\right)$, and where $\|\cdot\|_{H^{M}}$ denotes the standard Sobolev norm on $\mathbb{S}^{d-1}$. Roughly speaking, $u=u(x, \theta) \in \mathcal{H}^{M, N}\left(S \mathbb{T}^{d}\right)$ if $u$ has $H^{N}$ regularity in the variable $x \in \mathbb{T}^{d}$ and $H^{M}$ regularity in the variable $\theta \in \mathbb{S}^{d-1}$. With this convention at hand, we will prove the following type of results:

Theorem 2.2 (Mellin transform, function case). Let $\chi \in \mathcal{C}_{c}^{\infty}([1,+\infty))$ such that $\chi=1$ in a neighborhood of 1 and let $N \in \mathbb{Z}_{+}$. Then, the operator

$$
\mathcal{M}(s):=\int_{1}^{\infty} t^{-s} e^{-t V *}|d t|: \mathcal{C}^{\infty}\left(S \mathbb{T}^{d}\right) \rightarrow \mathcal{D}^{\prime}\left(S \mathbb{T}^{d}\right)
$$

splits as

$$
\mathcal{M}(s)=\mathcal{M}_{0}(s)+\mathcal{M}_{\infty}(s)
$$

where

$$
\mathcal{M}_{0}(s):=\int_{1}^{\infty} \chi(t) t^{-s} e^{-t V *}|d t|: \mathcal{H}^{N,-N / 2}\left(S \mathbb{T}^{d}\right) \rightarrow \mathcal{H}^{N,-N / 2}\left(S \mathbb{T}^{d}\right)
$$

is a holomorphic family of bounded operators on $\mathbb{C}$ and where

$$
\mathcal{M}_{\infty}(s):=\int_{1}^{\infty}(1-\chi(t)) t^{-s} e^{-t V *}|d t|: \mathcal{H}^{N,-N / 2}\left(S \mathbb{T}^{d}\right) \rightarrow \mathcal{H}^{-N, N / 2}\left(S \mathbb{T}^{d}\right)
$$

extends as a meromorphic family of bounded operators from $\{\operatorname{Re}(s)>1\}$ to $\{\operatorname{Re}(s)>1-N\}$ with only a simple pole at $s=1$ whose residue is given by

$$
\forall \psi \in \mathcal{C}^{\infty}\left(S \mathbb{T}^{d}\right), \quad \operatorname{Res}_{s=1}\left(\mathcal{M}_{\infty}(s)\right)(\psi)(x, \theta)=\frac{1}{(2 \pi)^{d}} \int_{\mathbb{T}^{d}} \psi(y, \theta) d y
$$

In particular, this Theorem tells us that the operator

$$
\mathcal{M}(s):=\int_{1}^{\infty} t^{-s} e^{-t V *}|d t|: \mathcal{C}^{\infty}\left(S \mathbb{T}^{d}\right) \rightarrow \mathcal{D}^{\prime}\left(S \mathbb{T}^{d}\right)
$$

extends meromorphically from $\{\operatorname{Re}(s)>1\}$ to the whole complex plane with only a simple pole at $s=1$. Yet, the statement is more precise as it allows us to describe the allowed regularity for this meromorphic continuation. We emphasize that the mapping properties of $\mathcal{M}_{0}(s)$ are rather immediate from the definition of our anisotropic norms and the main difficulty in this statement is about the "regularizing" properties of $\mathcal{M}_{\infty}(s)$. This Theorem is a direct consequence of the much more general Theorem 7.4 (together with Proposition 7.9), and it is one of the main results of this article. In other words, our meromorphic continuations are valid on spaces of distributions that are regular along the vertical bundle to $S \mathbb{T}^{d}$ (i.e. the tangent space to $\mathbb{S}^{d-1}$ ) and that may have negative Sobolev regularity along the horizontal bundle (i.e. the tangent space to $\mathbb{T}^{d}$ ). In particular, the anisotropic Sobolev spaces $\mathcal{H}^{N,-N / 2}$ contain the Dirac distribution $\delta_{[0]}(x)$ for $N>d$, and this is typically the kind of distributions that we will pick as test functions in order to derive our main applications on convex geometry using (2.3). In order to prove Theorems 1.2 and 1.3 , we will in fact need to prove more general statements for the action of $\mathcal{M}(s)$ on differential forms or more precisely on certain anisotropic Sobolev spaces of currents. Among other things, the action on differential forms will be responsible for the presence of the extra poles at $s=2, \ldots, d$ but this simplified statement already illustrates the kind of properties we are aiming at.

The same spaces will also allow us to prove the following statement:
Theorem 2.3 (Laplace transform, function case, continuous continuation). Let $\chi \in \mathcal{C}_{c}^{\infty}([0,+\infty))$ such that $\chi=1$ in a neighborhood of 0 and let $N \in 2 \mathbb{Z}_{+}^{*}+d$. Then, the operator

$$
\mathcal{L}(s):=(V+s)^{-1}=\int_{0}^{\infty} e^{-s t} e^{-t V *}|d t|: \mathcal{C}^{\infty}\left(S \mathbb{T}^{d}\right) \rightarrow \mathcal{D}^{\prime}\left(S \mathbb{T}^{d}\right)
$$

splits as

$$
\mathcal{L}(s)=\mathcal{L}_{0}(s)+\mathcal{L}_{\infty}(s)
$$

where

$$
\mathcal{L}_{0}(s):=\int_{0}^{\infty} \chi(t) e^{-s t} e^{-t V *}|d t|: \mathcal{H}^{N,-N}\left(S \mathbb{T}^{d}\right) \rightarrow \mathcal{H}^{N,-N}\left(S \mathbb{T}^{d}\right)
$$

is a holomorphic family of bounded operators on $\mathbb{C}$ and where

$$
\mathcal{L}_{\infty}(s):=\int_{0}^{\infty}(1-\chi(t)) e^{-s t} e^{-t V *}|d t|: \mathcal{H}^{N,-N / 2}\left(S \mathbb{T}^{d}\right) \rightarrow \mathcal{H}^{-N, N / 2}\left(S \mathbb{T}^{d}\right)
$$

extends continuously from $\{\operatorname{Re}(s)>0\}$ to
(1) $\{\operatorname{Re}(s) \geq 0\} \backslash\{0\}$ if $d \geq 4$,
(2) $\{\operatorname{Re}(s) \geq 0\} \backslash\left\{ \pm i|\xi|: \xi \in \mathbb{Z}^{d}\right\}$ if $d=2,3$.

Moreover, in any dimension, one has, as $s \rightarrow 0^{+}$,

$$
(V+s)^{-1}(\psi)(x, \theta)=\frac{1}{(2 \pi)^{d} s} \int_{\mathbb{T}^{d}} \psi(y, \theta) d y+\mathcal{O}_{\mathcal{D}^{\prime}}(1)
$$

and, when $d=2,3$, one has, as $s \rightarrow \pm i\left|\xi_{0}\right|$ (with $\left|\xi_{0}\right| \neq 0$ ),

$$
\begin{aligned}
& (V+s)^{-1}(\psi)(x, \theta) \\
& \quad=\frac{e^{\mp i \pi \frac{d-1}{4}} g_{d}\left(s \mp i\left|\xi_{0}\right|\right)}{(2 \pi)^{\frac{d+1}{2}}\left|\xi_{0}\right|^{\frac{d-1}{2}}} \sum_{\xi:|\xi|=\left|\xi_{0}\right|} e^{i \xi \cdot x} \delta_{0}\left(\theta \mp \frac{\xi}{|\xi|}\right) \int_{\mathbb{T}^{d}} \psi\left(y, \pm \frac{\xi}{|\xi|}\right) e^{-i \xi \cdot y} d y+\mathcal{O}_{\mathcal{D}^{\prime}}(1)
\end{aligned}
$$

where

$$
g_{2}(z):=\frac{\sqrt{2 \pi}}{\sqrt{z}}, \quad \text { and } \quad g_{3}(z):=-\ln (z)
$$

Again, this result is the consequence of the much more precise Theorem 7.8 (together with Proposition 7.9) which is valid on certain anisotropic Sobolev spaces of currents and which will also lead us to the proof of Theorem 1.4. In Theorem 7.8, the $\mathcal{C}^{k}$ continuation of $\mathcal{L}(s)$ is also discussed, and shows that the Laplace transform actually exhibits $\mathcal{C}^{k}$-singularities at the points $\left\{ \pm i|\xi|: \xi \in \mathbb{Z}^{d}\right\}$ in any dimension (but for larger values of $k$ in higher dimension). In the companion article [DGBLR22], we show that this result can be "improved" if we replace the Sobolev norm on $\mathbb{S}^{d-1}$ by some appropriate analytic norm built from the norms used in [GZ19] for the study of analytic pseudodifferential operators of order 0. In fact, after Fourier decomposition, studying the resolvent of $V$ acting on functions amounts to study a family of resolvents of multiplication operators (i.e. of pseudodifferential operators of order 0 ) on $\mathbb{S}^{d-1}$. In Sobolev regularity (as we are dealing here), one could apply the results from [ABdMG96, §7.6] (e.g. Th. 7.6.2) based on Mourre's commutator method. See also [CdVSR20, DZ19b] for recent developments for more general pseudodifferential operators of order 0 in dimension 2. Modulo some extra work to sum over all Fourier modes, this would yield in principle that

$$
\forall \epsilon>0, \forall N \in \mathbb{R}, \quad(V+s)^{-1}: \mathcal{H}^{\frac{1}{2}+\epsilon, N}\left(S \mathbb{T}^{d}\right) \rightarrow \mathcal{H}^{-\frac{1}{2}-\epsilon,-N}\left(S \mathbb{T}^{d}\right)
$$

extends continuously from $\{\operatorname{Re}(s)>0\}$ to $\{\operatorname{Re}(s) \geq 0\} \backslash\left\{ \pm i|\xi|: \xi \in \mathbb{Z}^{d}\right\}$. In view of our geometric applications to convex geometry, this analysis does not suffice since we aim at considering distributions having the same regularity as $\delta_{[0]}$, which does not belong to such spaces.

Remark 2.4. The operator $\mathcal{L}(s) \psi$ is the Laplace transform of the solution $u(t, \cdot)=e^{-t V *} \psi$ to the transport equation

$$
\partial_{\tau} u+\theta \cdot \partial_{x} u=0, \quad u(\tau=0, x, \theta)=\psi(x, \theta)
$$

while

$$
\mathcal{M}(s+1) \psi=\int_{0}^{+\infty} e^{-s \tau} e^{-e^{\tau} V *} \psi|d \tau|
$$

is the Laplace transform of the map $\tau \mapsto v(\tau, \cdot)=e^{-e^{\tau} V *}(\psi)$ which solves the (reparametrized) transport equation

$$
\partial_{\tau} v+e^{\tau} \theta \cdot \partial_{x} v=0, \quad v(\tau=0, x, \theta)=\psi(x, \theta)
$$

2.4. Emergence of quantum dynamics. Theorems 2.2 and 2.3 (as well as their analogues in the case of differential forms) are consequences of the fact that, through standard stationary phase asymptotics, we can give a full expansion of the Schwartz kernel of the geodesic flow. For instance, the first term in the asymptotic expansion reads

Theorem 2.5 (Time asymptotics of the geodesic flow, function case, leading term). For every smooth function $\psi \in \mathcal{C}^{\infty}\left(S \mathbb{T}^{d}\right)$, one has

$$
\begin{aligned}
t^{\frac{d-1}{2}}\left(\psi \circ e^{-t V}(x, \theta)-\frac{1}{(2 \pi)^{d}} \int_{\mathbb{T}^{d}} \psi(y, \theta) d y\right) & =(2 \pi)^{\frac{d-1}{2}} \sum_{\varepsilon \in\{ \pm\}} \mathbf{P}_{\varepsilon}^{\dagger} \frac{e^{i \varepsilon\left(t \sqrt{-\Delta}-\frac{\pi}{4}(d-1)\right)}}{(-\Delta)^{\frac{d-1}{4}}} \mathbf{P}_{\varepsilon} \\
& +\mathcal{O}_{\mathcal{D}^{\prime}\left(S \mathbb{T}^{d}\right)}\left(t^{-1}\right)
\end{aligned}
$$

where $\Delta=\sum_{j=1}^{d} \partial_{x_{j}}^{2}$ is the Euclidean Laplacian on $\mathbb{T}^{d}$,

$$
\mathbf{P}_{ \pm}: \psi \in \mathcal{C}^{\infty}\left(S \mathbb{T}^{d}\right) \mapsto \sum_{\xi \neq 0} \frac{1}{(2 \pi)^{d}} \int_{\mathbb{T}^{d}} \psi\left(y, \pm \frac{\xi}{|\xi|}\right) e^{i(y-x) \cdot \xi} d y \in \mathcal{C}^{\infty}\left(\mathbb{T}^{d}\right)
$$

and

$$
\mathbf{P}_{ \pm}^{\dagger}: f \in \mathcal{C}^{\infty}\left(\mathbb{T}^{d}\right) \mapsto \sum_{\xi \neq 0} \frac{1}{(2 \pi)^{d}}\left(\int_{\mathbb{T}^{d}} f(y) e^{i(y-x) \cdot \xi} d y\right) \delta_{0}\left(\theta \mp \frac{\xi}{|\xi|}\right) \in \mathcal{D}^{\prime}\left(S \mathbb{T}^{d}\right)
$$

This Theorem is a corollary of the much more precise statement given in Theorem 5.5 which provides a full asymptotic expansion with a precise description of the remainder terms at each step. Once again, this result could (and will) be expressed in terms of anisotropic Sobolev norms. Yet, due to the absence of integration over time, this requires a refined version of the spaces $\mathcal{H}^{N,-N / 2}\left(S \mathbb{T}^{d}\right)$ with an additional regularity imposed in the direction of the vector field $\theta \cdot \partial_{x}$.

In order to keep track of the comparison with negatively curved manifolds, such a result can be viewed as a simple occurence of the emergence of quantum dynamics (through the half-wave group $\left(e^{ \pm i t \sqrt{-\Delta}}\right)_{t \in \mathbb{R}}$ on the torus) in the long time dynamics of geodesic flows (i.e. $\left(e^{t V}\right)_{t \in \mathbb{R}}$ on $\left.S \mathbb{T}^{d}\right)$. This phenomenon was recently exhibited by Faure and Tsujii in the general context of contact Anosov flows [FT15, FT17b, FT17a, FT21]. See also [DFG15] for related results of Dyatlov, Faure and Guillarmou in the particular case of geodesic flows on hyperbolic manifolds. Compared with the results of Faure and Tsujii, we emphasize that our analysis heavily relies on the algebraic structure of our flows as in the hyperbolic settings treated in [Rat87, DFG15]. Moreover, we are dealing with completely integrable systems which have in some sense opposite behaviours compared with the dynamical situations considered in all these references. In particular, due to the integrable nature of our system, the asymptotic expansion in terms of the quantum propagator is polynomial rather than exponential as in [FT21, Th. 1.2]. This is reminiscent to the much weaker mixing properties of the geodesic flow in this situation.
2.5. Organization of the article. In Section 3, we review the necessary background on de Rham currents and we fix some conventions that will be used all along this work. Among other things, we reduce our analysis of $e^{-t V}$ to the study of certain oscillatory integrals. The reader only interested in dynamical properties (correlations of functions), and not on the geometrical questions (e.g. in relation with convex sets) may skip this section and consult directly Sections 4 and 5.

The analysis of these oscillatory integrals is a standard topic in harmonic analysis [Her62a, Hör03, Ste93, DZ19a] and in Section 4, we rediscuss some of their properties and pay some attention on the control of certain estimates in terms of the frequency parameter.

Then, in Section 5, we apply this analysis to define spaces with anisotropic Sobolev regularity, in which we describe the asymptotic expansion of the operator $e^{-t V *}$ as $t \rightarrow+\infty$ acting on functions, as in Theorem 2.5.

In Sections 6.1 and 7 , we come back to the general forms/currents setting of the article, and show how to define norms for which the operator $\widehat{\chi}(-i V)$ is well defined and can be continued when $\chi$ depends on some complex parameter $s \in \mathbb{C}$ as in Theorems 2.2 and 2.3.

In Section 8, we apply these results to particular currents to make the connection between these kinds of operators and geometric zeta functions/Poincaré series, using the strategy initiated in [DR21]. Along the way, we prove slightly more general versions of Theorems 1.2, 1.4, 1.6 and 1.7.

We conclude the proof of Theorem 1.3 in Section 9 by identifying the values of certain residues using tools from convex geometry [Sch14].

Finally, in Section 10, we apply our approach to prove some equidistribution properties of convex subsets under the action of the geodesic flow. The associated statements, that are variants of earlier results due to Randol [Ran84], are not presented in the introduction and we refer the reader directly to this section.
2.6. Comments on generalizations. The choice of the lattice $2 \pi \mathbb{Z}^{d}$ is somewhat arbitrary and it makes the presentation slightly simpler. However, our analysis could be adapted to handle more general flat tori of the form $\mathbb{R}^{d} / \Gamma$ where $\Gamma$ is a lattice in $\mathbb{R}^{d}$ of maximal rank.

All along this work, we consider the case of the geodesic flow on $S \mathbb{T}^{d}$. Yet our analysis could handle more general flows of the form:

$$
(x, \theta) \in S \mathbb{T}^{d} \mapsto(x+t \tilde{x}(\theta), \theta) \in S \mathbb{T}^{d}
$$

where $\theta \in \mathbb{S}^{d-1} \mapsto \tilde{x}(\theta) \in \mathbb{R}^{d}$ is the parametrization of the boundary of a strictly convex compact subset $K$ by its outward normal, i.e. the inverse of the Gauss map. The key observation to extend our analysis to these flows is that, for every $\xi \neq 0$ in $\mathbb{R}^{d}$, the map $\theta \in \mathbb{S}^{d-1} \mapsto \xi \cdot \tilde{x}(\theta)$ has only two critical points at $\theta= \pm \xi /|\xi|$. Moreover, these two points are nondegenerate thanks to the strict convexity assumption, which allows to perform the stationary phase asymptotics of $\S 4$.

From the geometric perspective of the introduction, this would correspond to the more general setup where one considers dilations $K \mapsto T K, T>0$, of the arbitrary strictly convex subset $K$ [vdC20, Hla50, Her62b, Ran66, CdV77]. In fact, as it will be clear in our proof, our geometric problem is related to the description of the lattice points in $K_{1}-K_{2}+T B_{d}$ (at least for a proper choice of orientation), where $B_{d}$ is the Euclidean unit ball of $\mathbb{R}^{d}$ centered at 0 . The choice of $B_{d}$ (and thus of the geodesic flow) makes the presentation slightly easier.

## 3. Background on differential forms and currents

In view of defining our functional setup for the vector field $V$, we need to describe as precisely as possible the long time behaviour of the geodesic flow $e^{t V}$ acting on differential forms of $S \mathbb{T}^{d}$. More precisely, given $(\varphi, \psi) \in \Omega^{2 d-1-k}\left(S \mathbb{T}^{d}\right) \times \Omega^{k}\left(S \mathbb{T}^{d}\right)$ (see $\S 3.1$ for a reminder of the definition), we aim at describing the correlation function

$$
\begin{equation*}
\mathcal{C}_{\varphi, \psi}(t):=\int_{S \mathbb{T}^{d}} \varphi \wedge e^{-t V *}(\psi), \quad \text { as } \quad t \rightarrow+\infty \tag{3.1}
\end{equation*}
$$

In this preliminary section, we review the notion of current [Sch66, Ch.IX] which plays the role of distributions for differential forms. Among other things, we define their Fourier transform in the setting of $S \mathbb{T}^{d}$ following [Sch66, Ch.IX, $\left.\S 6\right]$. In particular, we fix some conventions that will be used all along this work and we describe a few concrete examples that will be useful in view of our applications to convex geometry. This preliminary analysis is then used to rewrite the correlation function (3.1) using the Fourier decomposition of $\varphi$ and $\psi$. This is the content of Lemma 3.15 which allows to reduce the problem to estimating some classical oscillatory integrals.

Remark 3.1. We note that we implicitely fix an orientation on $\mathbb{T}^{d}$ by fixing the volume form $d x_{1} \wedge \ldots \wedge d x_{d}$ which can be identified with the Lebesgue measure on $\mathbb{T}^{d}$. When we want to insist on the fact that we view it as the Lebesgue measure, we will use the convention $|d x|$ and we will use the same convention to distinguish volume forms and measures on $\mathbb{R}^{d}, \mathbb{S}^{d-1}$ or $\mathbb{R}$.
3.1. Differential forms. We begin with [Lee09, Ch. 8]:

Definition 3.2. A differential form on $S \mathbb{T}^{d}$ of degree $0 \leq k \leq 2 d-1$ is a map which associates to each point $(x, \theta) \in S \mathbb{T}^{d}$ a $k$-linear form on $T_{x, \theta} S \mathbb{T}^{d}$ which is alternating. We denote by $\Lambda^{k} T^{*} S \mathbb{T}^{d}$ the set of alternating $k$-linear form on $T S \mathbb{T}^{d}$.

Let us be slightly more concrete. Given a subset $I=\left\{i_{1}<i_{2}<\ldots<i_{l}\right\}$ of $\{1, \ldots, d\}$, recall that $d x^{I}=d x_{i_{1}} \wedge d x_{i_{2}} \ldots \wedge d x_{i_{l}}$ denotes a differential form of degree $|I|$ on $\mathbb{T}^{d}$ (and thus on $S \mathbb{T}^{d}$ by pullback). Similarly, we can define differential forms on $\mathbb{S}^{d-1}$ as follows. For every $\theta \in \mathbb{S}^{d-1}$, we can fix a direct orthonormal basis $\left(e_{0}(\theta)=\theta, e_{1}(\theta), \ldots, e_{d-1}(\theta)\right)$ of $\mathbb{R}^{d}$, depending smoothly on $\theta$ in a small open set.

Remark 3.3. For instance, in the case $d=2$, we can identify $S_{x_{0}} \mathbb{T}^{2}=\mathbb{S}^{1}$ with $\mathbb{R} / 2 \pi \mathbb{Z}$ via the map $\tilde{\theta} \mapsto \cos \tilde{\theta} \partial_{x}+\sin \tilde{\theta} \partial_{y}$. Then, we complete the vector $e_{0}(\tilde{\theta})=\tilde{\theta}$ by the vector $e_{1}(\tilde{\theta})=$ $-\sin \tilde{\theta} \partial_{x}+\cos \tilde{\theta} \partial_{y}$.

To each $0 \leq j \leq d-1$, we can associate the 1-form

$$
e_{j}^{*}(\theta, d \theta): v \in \mathbb{R}^{d} \mapsto v \cdot e_{j}(\theta)
$$

where $\cdot$ denotes the standard Euclidean inner product on $\mathbb{R}^{d}$. For every subset $J=\left\{j_{1}<j_{2}<\right.$ $\left.\ldots<j_{l}\right\}$ of $\{1, \ldots, d-1\}$, we define the $|J|$-form

$$
e_{J}^{*}(\theta, d \theta)=e_{j_{1}}^{*}(\theta, d \theta) \wedge e_{j_{2}}^{*}(\theta, d \theta) \wedge \ldots \wedge e_{j_{l}}^{*}(\theta, d \theta)
$$

Since $T_{\theta} \mathbb{S}^{d-1} \simeq \theta^{\perp}=e_{0}(\theta)^{\perp}$, this differential form of degree $|J| \leq d-1$ on $\mathbb{R}^{d}$ restricts to a differential form on $T_{\theta} \mathbb{S}^{d-1}$. We keep the same notation for the restriction to $T_{\theta} \mathbb{S}^{d-1}$.

Let $U$ be a small open set of $\mathbb{S}^{d-1}$ so that we can pick the above orthonormal family $\left(e_{1}(\theta), \ldots, e_{d-1}(\theta)\right)$ depending in a smooth way on $\theta \in U$. For every $0 \leq m<\infty$ and $0 \leq k \leq 2 d-1$, we then define
the set $\Omega_{m}^{k}\left(\mathbb{T}^{d} \times U\right)$ of (complex valued) differential forms of degree $k$ and of class $\mathcal{C}^{m}$ as the set of elements of the form

$$
\psi(x, \theta, d x, d \theta)=\sum_{I \subset\{1, \ldots, d\}} \sum_{J \subset\{1, \ldots, d-1\}} \sum_{|I|+|J|=k} \psi^{I, J}(x, \theta) d x^{I} \wedge e_{J}^{*}(\theta, d \theta)
$$

where $\psi^{I, J}(x, \theta) \in \mathcal{C}^{m}\left(\mathbb{T}^{d} \times U, \mathbb{C}\right)$.
Definition 3.4. An element in $\Omega_{m}^{k}\left(S \mathbb{T}^{d}\right)=\Omega_{m}^{k}\left(\mathbb{T}^{d} \times \mathbb{S}^{d-1}\right)$ is a section $\psi: S \mathbb{T}^{d} \rightarrow \Lambda^{k} T^{*} S \mathbb{T}^{d}$, whose restriction to $\mathbb{T}^{d} \times U$ belongs to $\Omega_{m}^{k}\left(\mathbb{T}^{d} \times U\right)$ for any open set $U \subset \mathbb{S}^{d-1}$ (and it suffices of course to check this property for $U$ belonging to a finite atlas of $\mathbb{S}^{d-1}$ ).

In particular, elements in $\Omega_{m}^{k}\left(S \mathbb{T}^{d}\right)$ can be written under the following form

$$
\psi(x, \theta, d x, d \theta)=\sum_{I \subset\{1, \ldots, d\},|I| \leq k} d x^{I} \wedge \psi^{I}(x, \theta, d \theta)
$$

where, given any (local) smooth orthonormal family $\theta \mapsto\left(e_{1}(\theta), \ldots, e_{d-1}(\theta)\right)$ as above, $\psi^{I}$ can be written as

$$
\sum_{J \subset\{1, \ldots, d-1\}} \sum_{|J|=k-|I|} \psi^{I, J}(x, \theta) e_{J}^{*}(\theta, d \theta),
$$

with $\psi^{I, J}(x, \theta) \in \mathcal{C}^{m}\left(\mathbb{T}^{d} \times U, \mathbb{C}\right)$. In the following and for smooth forms, we will use the convention

$$
\Omega^{k}\left(\mathbb{T}^{d} \times U\right)=\bigcap_{m \geq 0} \Omega_{m}^{k}\left(\mathbb{T}^{d} \times U\right), \quad \Omega^{k}\left(S \mathbb{T}^{d}\right)=\bigcap_{m \geq 0} \Omega_{m}^{k}\left(S \mathbb{T}^{d}\right)
$$

Remark 3.5. The convention $d x$ and $d \theta$ in the arguments of $\psi \in \Omega_{m}^{k}\left(S \mathbb{T}^{d}\right)$ will always indicate that we are considering differential forms in the $x$ and $\theta$ variables.
3.2. Currents. For any $k \in\{0, \ldots, 2 d-1\}$, recall that $\Omega^{k}\left(S \mathbb{T}^{d}\right)$ has a natural structure of Fréchet space since $S \mathbb{T}^{d}$ is compact. We now define the set of currents as the topological dual to differential forms [Sch66, Ch.IX, §2].
Definition 3.6. The set of currents of degree $0 \leq k \leq 2 d-1$ on $S \mathbb{T}^{d}$ is the topological dual of $\Omega^{2 d-1-k}\left(S \mathbb{T}^{d}\right)$ with respect to bilinear pairing

$$
\left(\psi_{1}, \psi_{2}\right) \in \Omega^{k}\left(S \mathbb{T}^{d}\right) \times \Omega^{2 d-1-k}\left(S \mathbb{T}^{d}\right) \mapsto\left\langle\psi_{1}, \psi_{2}\right\rangle:=\int_{S \mathbb{T}^{d}} \psi_{1} \wedge \psi_{2} \in \mathbb{C}
$$

and the Fréchet topology of $\Omega^{2 d-1-k}\left(S \mathbb{T}^{d}\right)$. We denote this set by $\mathcal{D}^{\prime k}\left(S \mathbb{T}^{d}\right)$.
More concretely, given any (small enough) open subset $U$ of $\mathbb{S}^{d-1}$ and given any smooth orthonormal family $\theta \in U \mapsto\left(e_{1}(\theta), \ldots, e_{d-1}(\theta)\right)$ as above, an element $u$ in $\mathcal{D}^{\prime k}\left(S \mathbb{T}^{d}\right)$ can be written inside $\mathbb{T}^{d} \times U$ as

$$
u(x, \theta, d x, d \theta)=\sum_{I \subset\{1, \ldots, d\}} \sum_{J \subset\{1, \ldots, d-1\}} \sum_{|I|+|J|=k} u^{I, J}(x, \theta) d x^{I} \wedge e_{J}^{*}(\theta, d \theta)
$$

where $u^{I, J}(x, \theta)$ is a distribution on $\mathbb{T}^{d} \times U$, i.e. an element in $\mathcal{D}^{\prime}\left(\mathbb{T}^{d} \times U, \mathbb{C}\right)=\mathcal{D}^{\prime 0}\left(\mathbb{T}^{d} \times U, \mathbb{C}\right)$.
Remark 3.7. Note that in the extremal cases $k=0,2 d-1$, the restriction to an open subset $U$ is not necessary in this discussion as there is a canonical volume form on $S \mathbb{T}^{d}-$ see $\S 3.3$.
3.3. Orientation conventions. In the following, we choose to orient $\mathbb{S}^{d-1}$ with the $d-1$ form

$$
e_{1}^{*}(\theta, d \theta) \wedge e_{2}^{*}(\theta, d \theta) \wedge \ldots \wedge e_{d-1}^{*}(\theta, d \theta)
$$

and $S \mathbb{T}^{d}$ with the $2 d$ - 1 -form

$$
d x_{1} \wedge \ldots \wedge d x_{d} \wedge e_{1}^{*}(\theta, d \theta) \wedge \ldots \wedge e_{d-1}^{*}(\theta, d \theta)
$$

Note that $e_{1}^{*}(\theta, d \theta) \wedge e_{2}^{*}(\theta, d \theta) \wedge \ldots \wedge e_{d-1}^{*}(\theta, d \theta)$ is independent of the choice of the orthonormal family $\left(e_{1}(\theta), \ldots, e_{d-1}(\theta)\right)$ and that it can be identified with the canonical volume form $\operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta, d \theta)$ on $\mathbb{S}^{d-1}$ :

$$
\operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta, d \theta)=\sum_{p=1}^{d}(-1)^{p+1} \theta_{p} \bigwedge_{q=1, q \neq p}^{d} d \theta_{q}, \quad \theta \in \mathbb{S}^{d-1}
$$

When we want to emphasize that we view it as a measure, we will write $\operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta,|d \theta|)$.
Remark 3.8 (Orientation conventions for the sphere). If we denote by $\mathbb{B}_{d}:=\left\{\theta \in \mathbb{R}^{d}:|\theta| \leq 1\right\}$, the natural orientation on $\mathbb{B}_{d}$ is given by that on $\mathbb{R}^{d}$. In spherical coordinates $(r, \theta)$, the current of integration on $\mathbb{B}_{d}$ reads $\left[\mathbb{B}_{d}\right](r, \theta, d r, d \theta)=\mathbb{1}_{[0,1]}(r) d r$ so that

$$
\left[\mathbb{S}^{d-1}\right](r, \theta, d r, d \theta)=\partial\left[\mathbb{B}_{d}\right](r, \theta, d r, d \theta):=-d\left[\mathbb{B}_{d}\right](r, \theta, d r, d \theta)=\delta_{0}(r-1) d r
$$

In particular, $\operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta, d \theta)$ is the orientation on $\mathbb{S}^{d-1}=\partial \mathbb{B}_{d}$ induced by the one on $\mathbb{R}^{d}$ as

$$
\left\langle\left[\mathbb{S}^{d-1}\right], \operatorname{Vol}_{\mathbb{S}^{d-1}}\right\rangle=\int_{\mathbb{R}^{d}}\left[\mathbb{S}^{d-1}\right] \wedge \operatorname{Vol}_{\mathbb{S}^{d-1}}>0
$$

(where $\operatorname{Vol}_{\mathbb{S}^{d-1}}$ has been extended smoothly in a small neighborhood of $\mathbb{S}^{d-1}$ ).
In the standard spherical coordinates $\left(\tilde{\theta}_{1}, \ldots, \tilde{\theta}_{d-1}\right) \in(0, \pi)^{d-2} \times \mathbb{R} / 2 \pi \mathbb{Z}$, this volume form reads

$$
\operatorname{Vol}_{\mathbb{S}^{d-1}}(\tilde{\theta}, d \tilde{\theta})=\sin ^{d-2}\left(\tilde{\theta}_{1}\right) \ldots \sin \left(\tilde{\theta}_{d-2}\right) d \tilde{\theta}_{1} \wedge \ldots \wedge d \tilde{\theta}_{d-1}
$$

The volume form $\operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta, d \theta)$ can also be viewed as a volume form on $S \mathbb{T}^{d}$ via the pullback map $(x, \theta) \mapsto \theta$. For the sake of simplicity, we use the same convention for the volume form on $\mathbb{S}^{d-1}$ or for its pullback on $S \mathbb{T}^{d}$.
3.4. Decomposition of currents in Fourier series. We now explain how to decompose currents in Fourier series in the first variable, and fix some conventions. Let $u \in \mathcal{D}^{\prime k}\left(S \mathbb{T}^{d}\right)$ and $U \subset \mathbb{S}^{d-1}$ an open set. One can decompose locally $u$ in $\mathbb{T}^{d} \times U$ as

$$
u(x, \theta, d x, d \theta)=\sum_{I \subset\{1, \ldots, d\}} \sum_{J \subset\{1, \ldots, d-1\}} \sum_{|I|+|J|=k} u^{I, J}(x, \theta) d x^{I} \wedge e_{J}^{*}(\theta, d \theta)
$$

where $u^{I, J}(x, \theta) \in \mathcal{D}^{\prime}\left(\mathbb{T}^{d} \times U\right)$. Given $\xi \in \mathbb{Z}^{d}$, we can define the Fourier coefficient $\widehat{u}_{\xi}^{I, J} \in \mathcal{D}^{\prime}(U)$ as follows

$$
\widehat{u}_{\xi}^{I, J}: \psi \in \mathcal{C}_{c}^{\infty}(U) \mapsto\left\langle u^{I, J}, \mathfrak{e}_{-\xi} \psi\right\rangle=\int_{S \mathbb{T}^{d}} u^{I, J}(x, \theta) \mathfrak{e}_{-\xi}(x) \psi(\theta)|d x| \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta,|d \theta|)
$$

with

$$
\mathfrak{e}_{\xi}(x):=\frac{e^{i \xi \cdot x}}{(2 \pi)^{\frac{d}{2}}}
$$

This yields the following decomposition in Fourier series of $u \in \mathcal{D}^{\prime k}\left(S \mathbb{T}^{d}\right)$ :

$$
\begin{aligned}
u(x, \theta, d x, d \theta) & =\sum_{\xi \in \mathbb{Z}^{d}} \sum_{I \subset\{1, \ldots, d\}} \sum_{J \subset\{1, \ldots, d-1\}} \sum_{|I|+|J|=k} \widehat{u}_{\xi}^{I, J}(\theta) \mathfrak{e}_{\xi}(x) d x^{I} \wedge e_{J}^{*}(\theta, d \theta) \\
& =\sum_{\xi \in \mathbb{Z}^{d}} \sum_{I \subset\{1, \ldots, d\}} \mathfrak{e}_{\xi}(x) d x^{I} \wedge\left(\sum_{J \subset\{1, \ldots, d-1\}} \sum_{|I|+|J|=k} \widehat{u}_{\xi}^{I, J}(\theta) e_{J}^{*}(\theta, d \theta)\right)
\end{aligned}
$$

In summary, we can decompose any current $u$ in $\mathcal{D}^{\prime k}\left(S \mathbb{T}^{d}\right)$ as

$$
\begin{equation*}
u(x, \theta, d x, d \theta)=\sum_{\xi \in \mathbb{Z}^{d}} \sum_{I \subset\{1, \ldots, d\}} \mathfrak{e}_{\xi}(x) d x^{I} \wedge \widehat{u}_{\xi}^{I}(\theta, d \theta) \tag{3.2}
\end{equation*}
$$

where each $\widehat{u}_{\xi}^{I}$ is a current of degree $k-|I|$ on $\mathbb{S}^{d-1}$ and $\widehat{u}_{\xi}^{I}=0$ if $|I|>k$. For the sake of compactness, we also set

$$
\pi_{\xi}^{(k)}(u)(\theta, d x, d \theta):=\sum_{I \subset\{1, \ldots, d\}} d x^{I} \wedge \widehat{u}_{\xi}^{I}(\theta, d \theta),
$$

and

$$
\Pi_{\xi}^{(k)}(u)(x, \theta, d x, d \theta):=\sum_{I \subset\{1, \ldots, d\}} \mathfrak{e}_{\xi}(x) d x^{I} \wedge \widehat{u}_{\xi}^{I}(\theta, d \theta)=\mathfrak{e}_{\xi}(x) \pi_{\xi}^{(k)}(u)(\theta, d x, d \theta)
$$

These operators are projectors in the sense that

$$
\begin{equation*}
\forall \xi, \xi^{\prime} \in \mathbb{Z}^{d}, \quad \Pi_{\xi}^{(k)} \Pi_{\xi^{\prime}}^{(k)}=\delta_{\xi, \xi^{\prime}} \Pi_{\xi}^{(k)} \tag{3.3}
\end{equation*}
$$

where $\delta_{\xi, \xi^{\prime}}$ is the Kronecker symbol. These conventions allow to decompose any element $u \in$ $\mathcal{D}^{\prime k}\left(S \mathbb{T}^{d}\right)$ as follows

$$
u=\sum_{\xi \in \mathbb{Z}^{d}} \Pi_{\xi}^{(k)}(u)=\sum_{\xi \in \mathbb{Z}^{d}} \pi_{\xi}^{(k)}(u) \mathfrak{e}_{\xi} .
$$

Definition 3.9. Suppose that we are given a Sobolev or Hölder type norm $\|\cdot\|_{\mathcal{B}\left(\mathbb{S}^{d}\right)}$ on some Banach space $\mathcal{B}\left(\mathbb{S}^{d}\right)$ continuously included in

$$
\bigoplus_{l=0}^{d-1} \mathcal{D}^{l l}\left(\mathbb{S}^{d-1}\right)
$$

If we identify $\pi_{\xi}^{(k)}(u)$ with some vector valued distribution $\left(\widehat{u}_{\xi}^{I}\right)_{I \subset\{1, \ldots, k\}}$ on $\mathbb{S}^{d-1}$, we then define

$$
\left\|\pi_{\xi}^{(k)}(u)\right\|_{\mathcal{B}\left(\mathbb{S}^{d-1}\right)}:=\sup \left\{\left\|\widehat{u}_{\xi}^{I}\right\|_{\mathcal{B}\left(\mathbb{S}^{d-1}\right)}: I \subset\{1, \ldots, d\},|I| \leq k\right\} .
$$

Similarly, for some open set $U$ of $\mathbb{S}^{d-1}$, we set

$$
\left\|\pi_{\xi}^{(k)}(u)\right\|_{\mathcal{B}(U)}:=\sup \left\{\left\|\widehat{u}_{\xi}^{I}\right\|_{\mathcal{B}(U)}: I \subset\{1, \ldots, d\},|I| \leq k\right\} .
$$

3.5. Fundamental examples of currents of integration. We now discuss an important example of current in view of our analysis. In the sequel, $[0]$ denotes the equivalence class of $0 \bmod 2 \pi \mathbb{Z}^{d}$. We introduce the following current of degree $d$ on $\mathbb{T}^{d}$ :

$$
\delta_{2 \pi \mathbb{Z}^{d}}(x, d x):=\frac{1}{(2 \pi)^{\frac{d}{2}}} \sum_{\xi \in \mathbb{Z}^{d}} \mathfrak{e}_{\xi}(x) d x_{1} \wedge \ldots \wedge d x_{d}
$$

acting on functions $f \in \mathcal{C}^{\infty}\left(\mathbb{T}^{d}\right)$ by $\left\langle\delta_{2 \pi \mathbb{Z}^{d}}(x, d x), f\right\rangle=f([0])$. We will also use the notation

$$
\begin{equation*}
\delta_{[0]}(x)=\frac{1}{(2 \pi)^{\frac{d}{2}}} \sum_{\xi \in \mathbb{Z}^{d}} \mathfrak{e}_{\xi}(x), \tag{3.4}
\end{equation*}
$$

so that we can write

$$
\begin{equation*}
\delta_{2 \pi \mathbb{Z}^{d}}(x, d x)=\delta_{[0]}(x) d x_{1} \wedge \ldots \wedge d x_{d} \tag{3.5}
\end{equation*}
$$

If we view this current as a current ${ }^{7}$ on $S \mathbb{T}^{d}$ via the pullback by the map $(x, \theta) \in S \mathbb{T}^{d} \mapsto x \in \mathbb{T}^{d}$, then it is in fact the current of integration on the fiber $S_{[0]} \mathbb{T}^{d}$ viewed as a submanifold of dimension $d-1$. We can now slightly modify this example by fixing a smooth map $\tilde{x}: \mathbb{S}^{d-1} \rightarrow \mathbb{R}^{d}$ so that we can set

$$
\begin{equation*}
[\mathcal{N}]:=\delta_{[0]}(x-\tilde{x}(\theta)) \bigwedge_{i=1}^{d} d\left(x_{i}-\tilde{x}_{i}(\theta)\right) \in \mathcal{D}^{\prime d}\left(S \mathbb{T}^{d}\right) \tag{3.6}
\end{equation*}
$$

Note that this is the current of integration on the $d-1$ dimensional submanifold

$$
\mathcal{N}:=\left\{(\tilde{x}(\theta), \theta): \theta \in \mathbb{S}^{d-1}\right\} \subset \mathbb{T}^{d} \times \mathbb{S}^{d-1}
$$

that we have oriented with $\operatorname{Vol}_{S^{d-1}}(\theta, d \theta)$ [DR18, Cor. D.4]. This is typically the kind of currents to which we will apply $e^{-t V *}$ in Section 8 . See (8.10) and Lemma 8.9 for instance.

Thanks to (3.4), we have the following Fourier decomposition

$$
\begin{aligned}
{[\mathcal{N}](x, \theta, d x, d \theta) } & =\delta_{0}(x-\tilde{x}(\theta)) \bigwedge_{i=1}^{d} d\left(x_{i}-\tilde{x}_{i}(\theta)\right) \in \mathcal{D}^{\prime d}\left(S \mathbb{T}^{d}\right) \\
& =\frac{1}{(2 \pi)^{\frac{d}{2}}} \sum_{\xi \in \mathbb{Z}^{d}} \mathfrak{e}_{\xi}(x) e^{-i \xi \cdot \tilde{x}(\theta)} \bigwedge_{i=1}^{d} d\left(x_{i}-\tilde{x}_{i}(\theta)\right) \in \mathcal{D}^{\prime d}\left(S \mathbb{T}^{d}\right) .
\end{aligned}
$$

[^6]Thus, for every $\xi \in \mathbb{Z}^{d}$, one finds using the conventions of $\S 3.4$ :

$$
\begin{equation*}
\pi_{\xi}^{(d)}([\mathcal{N}])(\theta, d x, d \theta)=\mathfrak{e}_{\xi}(-\tilde{x}(\theta)) \bigwedge_{i=1}^{d} d\left(x_{i}-\tilde{x}_{i}(\theta)\right) \in \Omega^{d}\left(S \mathbb{T}^{d}\right) \tag{3.7}
\end{equation*}
$$

3.6. Action by pullback. If we fix a smooth map $\tilde{x}: \mathbb{S}^{d-1} \rightarrow \mathbb{R}^{d}$, then we can define a translation map on $S \mathbb{T}^{d}$ :

$$
\begin{equation*}
\mathbf{T}_{\tilde{x}}:(x, \theta) \in S \mathbb{T}^{d} \mapsto(x+\tilde{x}(\theta), \theta) \in S \mathbb{T}^{d} \tag{3.8}
\end{equation*}
$$

We can think of the above transport map as generated by the flow $\mathbf{T}_{t \tilde{x}}=e^{t \tilde{x}(\theta) \cdot \partial_{x}}: S \mathbb{T}^{d} \mapsto S \mathbb{T}^{d}, t \in$ $\mathbb{R}$ of the vector field $\tilde{x}(\theta) . \partial_{x}$. In section 9 , we will make a crucial use of the above map to transport the cotangent fiber $S_{[0]} \mathbb{T}^{d}$ into the normal bundle $\mathcal{N}:=\left\{(\tilde{x}(\theta), \theta): \theta \in \mathbb{S}^{d-1}\right\} \subset \mathbb{T}^{d} \times \mathbb{S}^{d-1}$ when $\tilde{x}$ is the parametrization by the normal.

Remark 3.10. An important example for our analysis will be of course given by the action of the geodesic flow, that is to say $e^{t V}=\mathbf{T}_{t \mathrm{Id}}$ where $\operatorname{Id}=\operatorname{Id}_{\mathbb{S}^{d-1}}$ (or equivalently $\tilde{x}(\theta)=\theta$ ). Yet, we will also need to consider more general translation maps when dealing with example (3.6).

Such a diffeomorphism acts on currents by pullback in the following way. Write locally

$$
u(x, \theta, d x, d \theta)=\sum_{I \subset\{1, \ldots, d\}} \sum_{J \subset\{1, \ldots, d-1\}} \sum_{|I|+|J|=k} u^{I, J}(x, \theta) d x^{I} \wedge e_{J}^{*}(\theta, d \theta)
$$

for some $u \in \mathcal{D}^{\prime k}\left(S \mathbb{T}^{d}\right)$. The action by pullback on $u$ is defined as

$$
\left(\mathbf{T}_{\tilde{x}}^{*} u\right)(x, \theta, d x, d \theta)
$$

$$
=\sum_{I \subset\{1, \ldots, d\}} \sum_{J \subset\{1, \ldots, d-1\}} \sum_{|I|+|J|=k} u^{I, J}(x+\tilde{x}(\theta), \theta)\left(\bigwedge_{l=1}^{|I|} d\left(x_{i_{l}}+\tilde{x}_{i_{l}}(\theta)\right)\right) \wedge e_{J}^{*}(\theta, d \theta) .
$$

For instance, this allows to rewrite example (3.6) as

$$
\begin{equation*}
\delta_{0}(x-\tilde{x}(\theta)) \bigwedge_{i=1}^{d} d\left(x_{i}-\tilde{x}_{i}(\theta)\right)=\mathbf{T}_{-\tilde{x}}^{*}\left(\delta_{2 \pi \mathbb{Z}^{d}}\right)(x, \theta, d x, d \theta)=\mathbf{T}_{-\tilde{x}}^{*}\left[S_{[0]} \mathbb{T}^{d}\right]=\left[\mathbf{T}_{\tilde{x}}\left(S_{[0]} \mathbb{T}^{d}\right)\right] \tag{3.9}
\end{equation*}
$$

This can be explained visually as follows, we start from the cotangent fiber $S_{[0]} \mathbb{T}^{d}$ and transporting this fiber by the flow $\tilde{x} . \partial_{\theta}$ yields the integration current $[\mathcal{N}]$ on the submanifold $\mathcal{N}$. We also record the following useful property regarding the projectors $\Pi_{\xi}$ :

$$
\begin{equation*}
\mathbf{T}_{\tilde{x}}^{*} \Pi_{\xi}^{(k)}(u)(x, \theta, d x, d \theta)=\mathfrak{e}_{\xi}(x) e^{i \xi \cdot \tilde{x}(\theta)} \pi_{\xi}^{(k)}(u)(\theta, d x+d \tilde{x}(\theta), d \theta) \tag{3.10}
\end{equation*}
$$

Finally, we close this preliminary section with two useful lemmas. We let $\mathbf{V}$ be the operator acting as the Lie derivative along $V$ on differential forms. The first lemma concerns the expansion rate of the geodesic flow on the torus, and will be useful when computing geometric quantities appearing in our analysis (like mixed volumes).
Lemma 3.11. Setting $\omega:=\iota_{V}\left(d x_{1} \wedge \cdots \wedge d x_{d}\right) \in \Omega^{d-1}\left(S \mathbb{T}^{d}\right)$, then the form $e^{-t \mathbf{V}} \omega$ is a polynomial of degree $d-1$ in $t$ with coefficients in $\Omega^{d-1}\left(S \mathbb{T}^{d}\right)$, with leading coefficient

$$
\frac{1}{(d-1)!} \mathbf{V}^{d-1} \omega=\operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta, d \theta)
$$

Proof. We start from

$$
\omega=\sum_{j=1}^{d} \theta_{j}\left(d x_{1} \wedge \cdots \wedge d x_{d}\right)\left(\partial_{x_{j}}\right)=\sum_{j=1}^{d}(-1)^{j+1} \theta_{j} d x_{1} \wedge \cdots \wedge \widehat{d x_{j}} \wedge \cdots \wedge d x_{d}
$$

from which we deduce that

$$
e^{-t \mathbf{V}} \omega=\sum_{j=1}^{d}(-1)^{j+1} \theta_{j} d\left(x_{1}-t \theta_{1}\right) \wedge \cdots \wedge d\left(\widehat{x_{j}-t} \theta_{j}\right) \wedge \cdots \wedge d\left(x_{d}-t \theta_{d}\right)
$$

is a polynomial of degree $d-1$ in $t$, whence the first statement. As a consequence, we have

$$
e^{-t \mathbf{V}} \omega=\sum_{k=0}^{d-1} \frac{1}{k!}(-t \mathbf{V})^{k} \omega
$$

where the leading order coefficient in $t$ is thus $\frac{(-1)^{d-1}}{(d-1)!} \mathbf{V}^{d-1} \omega$. Identifying with the leading order in the previous computation yields

$$
\frac{\mathbf{V}^{d-1} \omega}{(d-1)!}=\sum_{j=1}^{d}(-1)^{j+1} \theta_{j} d \theta_{1} \wedge \cdots \wedge \widehat{d \theta}_{j} \wedge \cdots \wedge d \theta_{d}=\iota_{\theta \cdot \partial_{\theta}}\left(d \theta_{1} \wedge \cdots \wedge d \theta_{d}\right)=\operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta, d \theta)
$$

which concludes the proof of the lemma.
The second lemma concerns commutation properties.
Lemma 3.12. Let $\tilde{x}: \mathbb{S}^{d-1} \rightarrow \mathbb{R}^{d}$ be a smooth map and $\mathbf{T}_{\tilde{x}}$ defined by (3.8), then one has

$$
\begin{align*}
\mathbf{T}_{\tilde{x}}^{*} \mathbf{V} & =\mathbf{V} \mathbf{T}_{\tilde{x}}^{*}  \tag{3.11}\\
\iota_{V} \mathbf{T}_{\tilde{x}}^{*} & =\mathbf{T}_{\tilde{x}}^{*} \iota_{V} \tag{3.12}
\end{align*}
$$

Proof. First notice that $e^{t V} \mathbf{T}_{\tilde{x}}(x, \theta)=(x+\tilde{x}(\theta)+t \theta, \theta)=\mathbf{T}_{\tilde{x}} e^{t V}(x, \theta)$, from which (3.11) follows.
Next, due to the specific forms of the operators $\mathbf{T}_{\tilde{x}}^{*}$, it is sufficient to verify (3.12) on the smooth forms $d x^{I}$ with $I \subset\{1, \ldots, d\}$. To that aim, we write

$$
\begin{aligned}
\iota_{V} \mathbf{T}_{\tilde{x}}^{*}\left(d x^{I}\right) & =\iota_{V}\left(\bigwedge_{m=1}^{l} d\left(x_{i_{m}}+\tilde{x}_{i_{m}}(\theta)\right)\right) \\
& =\sum_{m=1}^{l}(-1)^{l+1} \theta_{i_{m}} \bigwedge_{m^{\prime}=1, m^{\prime} \neq m}^{l} d\left(x_{i_{m^{\prime}}}+\tilde{x}_{i_{m^{\prime}}}(\theta)\right) \\
& =\mathbf{T}_{\tilde{x}}^{*}\left(\sum_{m=1}^{l}(-1)^{l+1} \theta_{i_{m}} \bigwedge_{m^{\prime}=1, m^{\prime} \neq m}^{l} d x_{i_{m^{\prime}}}\right) \\
& =\mathbf{T}_{\tilde{x}}^{*} \iota_{V}\left(d x^{I}\right)
\end{aligned}
$$

3.7. Transport equations on differential forms. We set

$$
H^{1}\left(\mathbb{T}^{d}, \mathbb{R}\right):=\left\{\beta:=\sum_{j=1}^{d} \beta_{j} d x_{j}:\left(\beta_{1}, \ldots, \beta_{d}\right) \in \mathbb{R}^{d}\right\}
$$

Given $u_{0} \in \mathcal{D}^{\prime k}\left(S \mathbb{T}^{d}\right)$, we can verify that

$$
u(t):=e^{-i t \beta_{0}(V)} e^{-t V *}\left(u_{0}\right)
$$

solves the transfort equation

$$
\partial_{t} u=-\mathbf{V} u-i \beta_{0}(V) u, \quad u(t=0)=u_{0}
$$

where we recall that $\mathbf{V}=d \iota_{V}+\iota_{V} d$ is the Lie derivative along the geodesic vector field. Equivalently, the transport equation can be written as

$$
\begin{equation*}
\partial_{t} u=-\mathbf{V}_{\beta_{0}} u, \quad \mathbf{V}_{\beta_{0}}:=\left(d+i \beta_{0} \wedge\right) \iota_{V}+\iota_{V}\left(d+i \beta_{0} \wedge\right) \tag{3.13}
\end{equation*}
$$

More generally, we can fix ${ }^{8} \beta \in \Omega_{\mathbb{R}}^{1}\left(\mathbb{T}^{d}\right)$ such that $d \beta=0$. Recall that any such 1 -form can be written as $\beta_{0}+d f$ where $f \in \mathcal{C}^{\infty}\left(\mathbb{T}^{d}, \mathbb{R}\right)$. Hence, we also define the twisted Lie derivative for such a general closed 1-form $\beta$,

$$
\mathbf{V}_{\beta}:=(d+i \beta \wedge) \iota_{V}+\iota_{V}(d+i \beta \wedge)
$$

[^7]and consider the corresponding transport equation (3.13). Yet, we note that it is "conjugated" to the transport equation induced by $\beta_{0} \in H^{1}\left(\mathbb{T}^{d}, \mathbb{R}\right)$ as
\[

$$
\begin{equation*}
\mathbf{V}_{\beta}=e^{-i f} \mathbf{V}_{\beta_{0}} e^{i f} \tag{3.14}
\end{equation*}
$$

\]

Intuitively, the reader should think that we are doing weighted transport. We transport some differential form by the flow and simultaneously, we multiply the the differential form by the integral of $\beta_{0}$ along the transport path.

Finally, we also record the following a priori estimate:
Lemma 3.13. Let $\beta \in \Omega_{\mathbb{R}}^{1}\left(\mathbb{T}^{d}\right)$ such that $d \beta=0$. Let $\chi \in \mathcal{C}^{\infty}(\mathbb{R})$ such that $t^{d-1} \chi(t) \in L^{1}(\mathbb{R})$. Then, for every $0 \leq k \leq 2 d-1$,

$$
\widehat{\chi}\left(-i \mathbf{V}_{\beta}\right): \psi \in \Omega_{0}^{k}\left(S \mathbb{T}^{d}\right) \mapsto \int_{\mathbb{R}} \chi(t) e^{-t \mathbf{V}_{\beta}}(\psi)|d t| \in \Omega_{0}^{k}\left(S \mathbb{T}^{d}\right)
$$

is a bounded operator.
Proof. This follows from the fact that for any $k$-form $\psi \in \Omega^{k}\left(S \mathbb{T}^{d}\right)$, we have the polynomial bound $\left\|e^{-t V_{\beta}} \psi\right\|_{L^{\infty}}=\mathcal{O}\left(t^{d-1}\right)$ which comes from the definition of the flow exactly like in the proof of Lemma 3.11.
Remark 3.14. Note that there is a slight abuse of notations when writing $\widehat{\chi}\left(-i \mathbf{V}_{\beta}\right)$ as the operator $-i \mathbf{V}_{\beta}$ is not selfadjoint even on $L^{2}$-spaces (except if $k=0$ or $2 d-1$ ). Yet, this convention from functional calculus is convenient and we will use it in the following except when it may create some confusions with the standard spectral Theorem [Ste09, § 12.7].
3.8. Correlation function for differential forms. We can now describe the correlation function $\mathcal{C}_{\varphi, \psi}(t)$ defined in (3.1) using our Fourier decomposition. In fact, slightly more generally than (3.1), we want to fix a smooth map $\tilde{x}: \mathbb{S}^{d-1} \rightarrow \mathbb{R}^{d}$ and some element $\beta_{0} \in H^{1}\left(\mathbb{T}^{d}, \mathbb{R}\right)$ and to describe

$$
\begin{equation*}
\mathcal{C}_{\varphi, \mathbf{T}_{-\tilde{x}}^{*}(\psi)}\left(t, \beta_{0}\right):=\int_{S \mathbb{T}^{d}} \varphi \wedge e^{-t \mathbf{V}_{\beta_{0}}} \mathbf{T}_{-\tilde{x}}^{*}(\psi) \tag{3.15}
\end{equation*}
$$

as $t \rightarrow+\infty$ in terms of $\varphi, \psi$ and the map $\tilde{x}$ which will be needed later in our applications to convex geometry. The element $\beta_{0}$ plays the role of magnetic potential. Here, $\varphi$ and $\psi$ are two differential forms on $S \mathbb{T}^{d}$ of respective degree $k_{1}$ and $k_{2}$ such that $k_{1}+k_{2}=2 d-1$, and $\mathbf{T}_{\tilde{x}}$ is defined in (3.8). We shall also use at some points that, for every smooth map $\tilde{x}: \mathbb{S}^{d-1} \rightarrow \mathbb{R}^{d}$,

$$
\begin{equation*}
\int_{S \mathbb{T}^{d}} \varphi \wedge e^{-t \mathbf{V}_{\beta_{0}}} \mathbf{T}_{-\tilde{x}}^{*}(\psi)=\int_{S \mathbb{T}^{d}} e^{t \mathbf{V}_{-\beta_{0}}} \mathbf{T}_{\tilde{x}}^{*}(\varphi) \wedge \psi \tag{3.16}
\end{equation*}
$$

as a consequence of the change of variable formula and of the commutation of $e^{t \mathbf{V}_{-\beta_{0}}}$ and $\mathbf{T}_{\tilde{x}}$. With the above conventions, we can make things slightly more concrete using Fourier series. Following $\S 3.4$, we write

$$
\begin{equation*}
\varphi(x, \theta, d x, d \theta)=\sum_{\xi \in \mathbb{Z}^{d}} \mathfrak{e}_{\xi}(x) \pi_{\xi}^{\left(k_{1}\right)}(\varphi)(\theta, d x, d \theta) \tag{3.17}
\end{equation*}
$$

We collect in the following lemma several useful properties of $\mathcal{C}_{\varphi, \mathbf{T}_{-\tilde{x}}^{*}(\psi)}\left(t, \beta_{0}\right)$.
Lemma 3.15. Using the above conventions, one has, for every $(\varphi, \psi) \in \Omega^{k_{1}}\left(S \mathbb{T}^{d}\right) \times \Omega^{k_{2}}\left(S \mathbb{T}^{d}\right)$, and $t \in \mathbb{R}$,

$$
\begin{align*}
& \mathcal{C}_{\varphi, \mathbf{T}_{-\tilde{x}}^{*}(\psi)}\left(t, \beta_{0}\right)=\sum_{l=0}^{\min \left\{k_{1}, k_{2}\right\}} \mathcal{C}_{\varphi, \mathbf{T}_{-\tilde{x}}^{*}(\psi)}^{l}\left(t, \beta_{0}\right) \quad \text { with }  \tag{3.18}\\
& \mathcal{C}_{\varphi, \mathbf{T}_{-\tilde{x}}^{*}(\psi)}^{l}\left(t, \beta_{0}\right)=\frac{t^{l}}{l!} \sum_{\xi \in \mathbb{Z}^{d}} \int_{\mathbb{S}^{d-1}} e^{i t\left(\xi-\beta_{0}\right) \cdot \theta} e^{i \xi \cdot \tilde{x}(\theta)} B_{\tilde{x}, \xi}^{\left(k_{2}, l\right)}(\varphi, \psi)(\theta) \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta, d \theta) \tag{3.19}
\end{align*}
$$

and

$$
\begin{equation*}
B_{\tilde{x}, \xi}^{\left(k_{2}, l\right)}(\varphi, \psi)(\theta) \operatorname{Vol}_{S \mathbb{T}^{d}}(\theta, d x, d \theta):=(-1)^{l} \pi_{\xi}^{\left(k_{1}\right)}(\varphi)(\theta, d x, d \theta) \wedge \mathbf{V}^{l} \mathbf{T}_{-\tilde{x}}^{*} \pi_{-\xi}^{\left(k_{2}\right)}(\psi)(\theta, d x, d \theta) \tag{3.20}
\end{equation*}
$$

Moreover, for every $m \in \mathbb{Z}_{+}$(resp. $s \in \mathbb{R}$ ), one can find some constant $C_{m}>0$ (resp. $C_{s}>0$ ) (depending also on $d, \tilde{x}$ ) such that, for every open set $U \subset \mathbb{S}^{d-1}$, for every $\xi \in \mathbb{Z}^{d}$, for every $k_{1}+k_{2}=2 d-1$, for every $0 \leq l \leq \min \left\{k_{2}, k_{1}\right\}$ and for every $(\varphi, \psi) \in \Omega^{k_{1}}\left(S \mathbb{T}^{d}\right) \times \Omega^{k_{2}}\left(S \mathbb{T}^{d}\right)$,

$$
\begin{equation*}
\left\|B_{\tilde{x}, \xi}^{\left(k_{2}, l\right)}(\varphi, \psi)\right\|_{W^{m, 1}(U)} \leq C_{m}\left\|\pi_{\xi}^{\left(k_{1}\right)}(\varphi)\right\|_{H^{m}(U)}\left\|\pi_{-\xi}^{\left(k_{2}\right)}(\psi)\right\|_{H^{m}(U)} \tag{3.21}
\end{equation*}
$$

resp.

$$
\begin{equation*}
\left\|B_{\tilde{x}, \xi}^{\left(k_{2}, l\right)}(\varphi, \psi)\right\|_{L^{1}\left(\mathbb{S}^{d-1}\right)} \leq C_{s}\left\|\pi_{\xi}^{\left(k_{1}\right)}(\varphi)\right\|_{H^{s}\left(\mathbb{S}^{d-1}\right)}\left\|\pi_{-\xi}^{\left(k_{2}\right)}(\psi)\right\|_{H^{-s}\left(\mathbb{S}^{d-1}\right)} \tag{3.22}
\end{equation*}
$$

where $W^{m, 1}(U)$ is the Sobolev norm of order $m$ and exponent $p=1$ and where $H^{m}(U)=W^{m, 2}(U)$ is the Sobolev norm of order $m$ (and exponent $p=2$ ) on differential forms on the set $U$.

The decomposition of the dynamical correlator $\mathcal{C}$ in terms of Fourier series and in powers of $t$ introduced in the above Lemma will play a crucial role in the sequel, especially for our applications for convex geometry.

Proof. According to (3.17) applied to $\psi$ and to (3.10), we may first expand

$$
\begin{align*}
\left(e^{-t \mathbf{V}_{\beta_{0}}} \mathbf{T}_{-\tilde{x}}^{*} \psi\right)(x, \theta, d x, d \theta)=\sum_{l=0}^{\min \left\{k_{2}, d-1\right\}} \frac{(-1)^{l} t^{l}}{l!} \sum_{\xi \in \mathbb{Z}^{d}} & \mathfrak{e}_{\xi}(x) e^{-i t\left(\xi+\beta_{0}\right) \cdot \theta} e^{-i \xi \cdot \tilde{x}(\theta)}  \tag{3.23}\\
& \times \mathbf{V}^{l} \circ \mathbf{T}_{-\tilde{x}}^{*} \circ \pi_{\xi}^{\left(k_{2}\right)}(\psi)(\theta, d x, d \theta)
\end{align*}
$$

Hence, using (3.17) applied to $\varphi$, (3.11), (3.23) and (3.16), one has

$$
\mathcal{C}_{\varphi, \mathbf{T}_{-\tilde{x}}^{*}(\psi)}\left(t, \beta_{0}\right)=\sum_{l=0}^{\min \left\{k_{1}, k_{2}\right\}} \frac{t^{l}}{l!} \sum_{\xi \in \mathbb{Z}^{d}} \int_{\mathbb{S}^{d-1}} e^{i \xi \cdot \tilde{x}(\theta)} e^{i t\left(\xi-\beta_{0}\right) \cdot \theta} B_{\tilde{x}, \xi}^{\left(k_{2}, l\right)}(\varphi, \psi)(\theta) \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta, d \theta)
$$

where $B_{\tilde{x}, \xi}^{\left(k_{2}, l\right)}(\varphi, \psi)(\theta) \operatorname{Vol}_{S \mathbb{T}^{d}}(\theta, d x, d \theta)$ is given by (3.20). This readily yields (3.18)-(3.19).
Finally, estimate (3.21) and (3.22) follow from the fact that the coefficients $B_{\tilde{x}, \xi}^{\left(k_{2}, l\right)}(\varphi, \psi)$ depend in a bilinear way on $\left(\pi_{\xi}^{\left(k_{1}\right)}(\varphi), \pi_{-\xi}^{\left(k_{2}\right)}(\psi)\right)$, together with the Cauchy-Schwarz inequality.

According to Lemma 3.15, understanding the properties of the correlation function as $t \rightarrow+\infty$ amounts to describe the behaviour of the integrals

$$
\begin{equation*}
I_{F}\left(\xi-\beta_{0}, t\right):=\int_{\mathbb{S}^{d-1}} e^{i\left(\xi-\beta_{0}\right) \cdot(t \theta+\tilde{x}(\theta))} e^{i \beta_{0} \cdot \tilde{x}(\theta)} F(\theta) \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta,|d \theta|), \tag{3.24}
\end{equation*}
$$

as $t \rightarrow+\infty$, where $\xi \in \mathbb{Z}^{d} \backslash\{0\}$, where $\beta_{0}$ plays the role of the magnetic potential and where $F$ is a smooth function. In view of applications, one needs to make this asymptotic description with a uniform control in terms of the $W^{m, 1}$-norm of $F$ and of $\xi \in \mathbb{Z}^{d}$.
Remark 3.16. The extra oscillating term $e^{i \xi \cdot \tilde{x}(\theta)}$ makes things slightly more involved than when one treats the case of dilating convex sets as for instance in [Hla50, Her62b, Ran66]. Indeed, in that setup, the parameter $t$ is also in factor of $\xi \cdot \tilde{x}(\theta)$ which allows to deal with $t|\xi|$ as a large parameter. Despite this technical issue, the strategy to analyze these integrals remains the same. See Section 4 below.
Remark 3.17. In the case where $k_{1}=2 d-1$ and $k_{2}=0$, one has

$$
\varphi(x, \theta, d x, d \theta)=\sum_{\xi \in \mathbb{Z}^{d}} \widehat{\varphi}_{\xi}(\theta) \mathfrak{e}_{\xi}(x) d x_{1} \wedge \ldots d x_{d} \wedge \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta, d \theta)
$$

and

$$
\psi(x, \theta, d x, d \theta)=\sum_{\xi \in \mathbb{Z}^{d}} \widehat{\psi}_{\xi}(\theta) \mathfrak{e}_{\xi}(x)
$$

Hence, one gets the simpler expression

$$
\mathcal{C}_{\varphi, \mathbf{T}_{-\tilde{x}}^{*}(\psi)}\left(t, \beta_{0}\right)=\sum_{\xi \in \mathbb{Z}^{d}} \int_{\mathbb{S}^{d-1}} e^{i t\left(\xi-\beta_{0}\right) \cdot \theta} e^{i \xi \cdot \tilde{x}(\theta)} \widehat{\varphi}_{\xi}(\theta) \widehat{\psi}_{-\xi}(\theta) \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta,|d \theta|)
$$

## 4. Asymptotics of oscillatory integrals

In view of describing the long time asymptotics of the correlation function (or integrated versions of it), we need to describe with some accuracy the oscillatory integrals appearing in Lemma 3.15. More precisely, we want to study the behaviour as $t \rightarrow+\infty$ (and for $\xi-\beta_{0} \neq 0$ ) of the oscillatory integral $I_{F}\left(\xi-\beta_{0}, t\right)(3.24)$, where $\beta_{0} \in \mathbb{R}^{d}, F \in \mathcal{C}^{\infty}\left(\mathbb{S}^{d-1}, \mathbb{C}\right)$ and $\tilde{x} \in \mathcal{C}^{\infty}\left(\mathbb{S}^{d-1}, \mathbb{R}\right)$. Estimating these kind of integrals as $t \rightarrow+\infty$ is a classical topic in harmonic analysis. See [Her62a, Lit63] for a rough estimate, and [Hör03, Th. 7.7.14], [Ste93, Section VIII-3, p347] and [DZ19a, Th. 3.38, p140] for fine asymptotic expansions. The only additional difficulty compared with these references is that we need to have a good control in terms of $|\xi|$. Thus, we need to pay a little attention to the extra term $e^{i \xi \cdot \tilde{x}(\theta)}$ when revisiting the classical stationary phase arguments used to describe these integrals: this is the content of the present section. There is a subtle competition between the large times $t$ and the large momenta $|\xi|$ which is what we deal with in the next Lemmas. As usual, we split these oscillatory integrals in two parts: one corresponding to nonstationary points and one corresponding to stationary ones.
4.1. Splitting the oscillatory integral. We first define cutoff functions that will be used all along the paper and that we will fix once and for all in Lemma 4.4.

Definition 4.1. We let $\left(\chi_{j}\right)_{j \in\{-1,0,1\}}$ be any smooth partition of unity of the closed interval $[-1,1]$ such that $\chi_{1}$ is equal to one in a neighborhood of $1, \operatorname{supp}\left(\chi_{1}\right) \subset(0,1], \chi_{-1}(s)=\chi_{1}(-s)$, and $\operatorname{supp}\left(\chi_{0}\right) \subset(-1,1)$.

We shall make a $\xi$-dependent partition of unity of the sphere $\theta \in \mathbb{S}^{d-1}$ by letting

$$
\chi_{j}\left(\theta \cdot \frac{\xi-\beta_{0}}{\left|\xi-\beta_{0}\right|}\right), \quad j \in\{-1,0,1\}, \quad \xi \neq \beta_{0}
$$

that is to say, for $j= \pm 1$, localization near the poles $\pm \frac{\xi-\beta_{0}}{\left|\xi-\beta_{0}\right|}$, and for $j=0$, localization near the equator $\left(\frac{\xi-\beta_{0}}{\left|\xi-\beta_{0}\right|}\right)^{\perp}$.

We split the integral $I_{F}$ defined in (3.24) accordingly as

$$
\begin{align*}
I_{F}\left(\xi-\beta_{0}, t\right) & =I_{F}^{(-1)}\left(\xi-\beta_{0}, t\right)+I_{F}^{(0)}\left(\xi-\beta_{0}, t\right)+I_{F}^{(1)}\left(\xi-\beta_{0}, t\right), \quad \text { with }  \tag{4.1}\\
I_{F}^{(j)}\left(\xi-\beta_{0}, t\right) & :=\int_{\mathbb{S}^{d-1}} \chi_{j}\left(\theta \cdot \frac{\xi-\beta_{0}}{\left|\xi-\beta_{0}\right|}\right) e^{i\left(\xi-\beta_{0}\right) \cdot(t \theta+\tilde{x}(\theta))} e^{i \beta_{0} \cdot \tilde{x}(\theta)} F(\theta) \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta,|d \theta|) \tag{4.2}
\end{align*}
$$

We denote by $\left(e_{1}, \ldots, e_{d}\right)$ the canonical basis of $\mathbb{R}^{d}$. We first rewrite $\xi-\beta_{0}$ as $\xi-\beta_{0}=\lambda \omega$ with $\lambda=\left|\xi-\beta_{0}\right| \neq 0$ and $\omega=\frac{\xi-\beta_{0}}{\left|\xi-\beta_{0}\right|} \in \mathbb{S}^{d-1}$, and let

$$
R: \omega \ni \mathbb{S}^{d-1} \rightarrow R(\omega)=R_{\omega} \in S O(d)
$$

be so that $\omega=R_{\omega} e_{d}$. We then make a change of variable in the integral, setting $\theta^{\prime}=R_{\omega}^{-1} \theta=R_{\omega}^{T} \theta$, and obtain

$$
\begin{aligned}
I_{F}(\lambda \omega, t) & =\int_{\mathbb{S}^{d-1}} e^{i \lambda R(\omega) e_{d} \cdot(t \theta+\tilde{x}(\theta))} e^{i \beta_{0} \cdot \tilde{x}(\theta)} F(\theta) \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta,|d \theta|) \\
& =\int_{\mathbb{S}^{d-1}} e^{i \lambda e_{d} \cdot\left(t \theta^{\prime}+R_{\omega}^{-1} \tilde{x}\left(R_{\omega} \theta^{\prime}\right)\right)} e^{i \beta_{0} \cdot \tilde{x}\left(R_{\omega} \theta^{\prime}\right)} F\left(R_{\omega} \theta^{\prime}\right) \operatorname{Vol}_{\mathbb{S}^{d-1}}\left(\theta^{\prime},\left|d \theta^{\prime}\right|\right)
\end{aligned}
$$

where we used the invariance of $\mathrm{Vol}_{\mathbb{S}^{d-1}}$ under $\mathrm{SO}(d)$. The above splitting (4.1) of $I_{F}$ into three pieces now reads

$$
\begin{align*}
I_{F}(\lambda \omega, t) & =I_{F}^{(-1)}(\lambda \omega, t)+I_{F}^{(0)}(\lambda \omega, t)+I_{F}^{(1)}(\lambda \omega, t), \quad \text { with }  \tag{4.3}\\
I_{F}^{(j)}(\lambda \omega, t) & =\int_{\mathbb{S}^{d}-1} \chi_{j}\left(\theta^{\prime} \cdot e_{d}\right) e^{i \lambda e_{d} \cdot\left(t \theta^{\prime}+R_{\omega}^{-1} \tilde{x}\left(R_{\omega} \theta^{\prime}\right)\right)} e^{i \beta_{0} \cdot \tilde{x}\left(R_{\omega} \theta^{\prime}\right)} F\left(R_{\omega} \theta^{\prime}\right) \operatorname{Vol}_{\mathbb{S}^{d-1}}\left(\theta^{\prime},\left|d \theta^{\prime}\right|\right) \tag{4.4}
\end{align*}
$$

and we study each piece separately. To state our results, we also define, for $\eta \in \mathbb{R}^{d} \backslash\{0\}$,

$$
\begin{equation*}
\mathbf{C}_{j}(\eta):=\left\{\theta \in \mathbb{S}^{d-1} \text { such that } \theta \cdot \frac{\eta}{|\eta|} \in \operatorname{supp}\left(\chi_{j}\right)\right\}, \quad \text { for } j=-1,0,1 \tag{4.5}
\end{equation*}
$$

These are three closed subsets of the sphere. According to the above properties of the cutoff functions $\chi_{j}$, we have, for all $\eta \in \mathbb{R}^{d} \backslash\{0\}$,

$$
\mathbf{C}_{-1}(\eta) \cup \mathbf{C}_{0}(\eta) \cup \mathbf{C}_{1}(\eta)=\mathbb{S}^{d-1}
$$

$\mathbf{C}_{ \pm 1}(\eta)$ is a neighborhood of $\pm \frac{\eta}{|\eta|}$ in $\mathbb{S}^{d-1}$, and $\mathbf{C}_{0}(\eta)$ is a neighborhood of $\left(\frac{\eta}{|\eta|}\right)^{\perp}$ in $\mathbb{S}^{d-1}$. We also notice that these three sets only depend on $\frac{\eta}{|\eta|}=\omega$, whence $\mathbf{C}_{j}(\eta)=\mathbf{C}_{j}\left(\frac{\eta}{|\eta|}\right)=\mathbf{C}_{j}(\omega)$.
4.2. Nonstationary points. We start with the integral $I_{F}^{(0)}$ for which we will use the following lemma.

Lemma 4.2 (Non-stationary points). We set

$$
\mathcal{I}_{0}[X, f](\lambda, t):=\int_{\mathbb{S}^{d-1}} \chi_{0}\left(\theta \cdot e_{d}\right) e^{i \lambda e_{d} \cdot(t \theta+X(\theta))} f(\theta) \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta,|d \theta|)
$$

For all $\chi_{0} \in \mathcal{C}_{c}^{\infty}(-1,1)$, there exists $C\left(\chi_{0}\right)>0$ such that for all $N \in \mathbb{N}$, there is a nondecreasing function $r \mapsto C_{N}(r)>0$ such that for all $X \in \mathcal{C}^{N+1}\left(\mathbb{S}^{d-1}\right), t>C\left(\chi_{0}\right)\|d X\|_{L^{\infty}\left(\mathbf{C}_{0}\left(e_{d}\right)\right)}, \lambda>0$, $f \in \mathcal{C}^{N}\left(\mathbb{S}^{d-1}\right)$, we have

$$
\begin{equation*}
\mathcal{I}_{0}[X, f](\lambda, t):=(i \lambda t)^{-N} \int_{\mathbb{S}^{d-1}} e^{i \lambda e_{d} \cdot(t \theta+X(\theta))} \mathcal{L}_{N, t}\left(\chi_{0}\left(\theta \cdot e_{d}\right) f(\theta)\right) \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta,|d \theta|) \tag{4.6}
\end{equation*}
$$

where $\mathcal{L}_{N, t}$ is a differential operator of order $N$ on $\mathbb{S}^{d-1}$ with smooth coefficients depending only on $X$ and $t$ and such that for all $\psi \in \mathcal{C}^{N}\left(\mathbb{S}^{d-1}\right)$, for all $\theta \in \mathbf{C}_{0}\left(e_{d}\right)$, and all $t \geq C\left(\chi_{0}\right)\|d X\|_{L^{\infty}\left(\mathbf{C}_{0}\left(e_{d}\right)\right)}$ we have

$$
\begin{equation*}
\left|\left(\mathcal{L}_{N, t} \psi\right)(\theta)\right| \leq C_{N}\left(\frac{\|X\|_{W^{N+1, \infty}\left(\mathbf{C}_{0}\left(e_{d}\right)\right)}}{t}\right)\left(\sum_{|\alpha| \leq N}\left|\nabla_{\theta}^{\alpha} \psi(\theta)\right|\right) \tag{4.7}
\end{equation*}
$$

In particular,

$$
\left|\mathcal{I}_{0}[X, f](\lambda, t)\right| \leq C_{N}\left(\frac{\left.\|X\|_{W^{N+1, \infty}\left(\mathbf{C}_{0}\left(e_{d}\right)\right)}^{t}\right)(\lambda t)^{-N}\|f\|_{W^{N, 1}\left(\mathbf{C}_{0}\left(e_{d}\right)\right)} . . . . ~}{}\right.
$$

Recall that $\theta \in \mathbf{C}_{0}\left(e_{d}\right)$ iff $\theta \cdot e_{d} \in \operatorname{supp}\left(\chi_{0}\right)$. Again, this kind of estimates is classical and the only novelty here is the explicit control in terms of the various parameters involved which will be obtained by a careful inspection of the usual arguments.

We now apply this lemma to

$$
X\left(\theta^{\prime}\right)=R_{\omega}^{-1} \tilde{x}\left(R_{\omega} \theta^{\prime}\right) \quad \text { and } \quad f\left(\theta^{\prime}\right)=e^{i \beta_{0} \cdot \tilde{x}\left(R_{\omega} \theta^{\prime}\right)} F\left(R_{\omega} \theta^{\prime}\right)
$$

remarking that

$$
\begin{aligned}
\|X\|_{W^{N+1, \infty}\left(\mathbf{C}_{0}\left(e_{d}\right)\right)} & \leq C_{N}\|\tilde{x}\|_{W^{N+1, \infty}\left(\mathbf{C}_{0}(\omega)\right)}, \\
\sum_{|\alpha| \leq N}\left|\nabla_{\theta}^{\alpha} f\left(\theta^{\prime}\right)\right| & \leq C_{N}\|\tilde{x}\|_{W^{N, \infty}\left(\mathbf{C}_{0}(\omega)\right)}\left(\sum_{|\gamma| \leq N}\left|\nabla_{\theta}^{\gamma} F\right|\left(R_{\omega} \theta^{\prime}\right)\right), \quad \text { for all } \theta \in \mathbf{C}_{0}\left(e_{d}\right), \\
\|f\|_{W^{N, 1}\left(\mathbf{C}_{0}\left(e_{d}\right)\right)} & \leq C_{N}\|\tilde{x}\|_{W^{N, \infty}\left(\mathbf{C}_{0}(\omega)\right)}\|F\|_{W^{N, 1}\left(\mathbf{C}_{0}(\omega)\right)},
\end{aligned}
$$

uniformly in the variable $\omega \in \mathbb{S}^{d-1}$. Denoting $\mathcal{L}_{N, t}^{\omega}=R_{\omega}^{-1 *} \circ \mathcal{L}_{N, t} \circ R_{\omega}^{*}$, we thus obtain the following corollary.
Corollary 4.3 (Nonstationary points). For all $\chi_{0} \in \mathcal{C}_{c}^{\infty}(-1,1)$, there exists $C\left(\chi_{0}\right)>0$ such that for all $N \in \mathbb{N}$, there is a nondecreasing function $r \mapsto C_{N}(r)>0$ such that for all $\tilde{x} \in \mathcal{C}^{N+1}\left(\mathbb{S}^{d-1}\right)$, $t>C\left(\chi_{0}\right)\|d \tilde{x}\|_{L^{\infty}\left(\mathbb{S}^{d-1}\right)}, \omega \in \mathbb{S}^{d-1}, \lambda>0$ and $F \in \mathcal{C}^{N}\left(\mathbb{S}^{d-1}\right)$, we have

$$
I_{F}^{(0)}(\lambda \omega, t)=(i \lambda t)^{-N} \int_{\mathbb{S}^{d-1}} e^{i \lambda \omega \cdot(t \theta+\tilde{x}(\theta))} \mathcal{L}_{N, t}^{\omega}\left(\chi_{0}(\theta \cdot \omega) e^{i \beta_{0} \cdot \tilde{x}(\theta)} F(\theta)\right) \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta,|d \theta|)
$$

or equivalently for $\xi \in \mathbb{R}^{d} \backslash\left\{\beta_{0}\right\}$,

$$
\begin{align*}
& \left(i\left|\xi-\beta_{0}\right| t\right)^{N} I_{F}^{(0)}\left(\xi-\beta_{0}, t\right)  \tag{4.8}\\
& \quad=\int_{\mathbb{S}^{d-1}} e^{i\left(\xi-\beta_{0}\right) \cdot(t \theta+\tilde{x}(\theta))} \mathcal{L}_{N, t}^{\frac{\xi-\beta_{0}}{\left|\xi-\beta_{0}\right|}}\left(\chi_{0}\left(\theta \cdot \frac{\xi-\beta_{0}}{\left|\xi-\beta_{0}\right|}\right) e^{i \beta_{0} \cdot \tilde{x}(\theta)} F(\theta)\right) \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta,|d \theta|)
\end{align*}
$$

where $\mathcal{L}_{N, t}^{\omega}$ is a differential operator of order $N$ on $\mathbb{S}^{d-1}$ with smooth coefficients only depending on $X, \omega$ and $t$ and such that for all $\psi \in \mathcal{C}^{N}\left(\mathbb{S}^{d-1}\right)$, for all $\omega \in \mathbb{S}^{d-1}$, for all $\theta \in \mathbf{C}_{0}(\omega)$, and all $t \geq C\left(\chi_{0}\right)\|d \tilde{x}\|_{L^{\infty}\left(\mathbb{S}^{d-1}\right)}$ we have

$$
\left|\left(\mathcal{L}_{N, t}^{\omega} \psi\right)(\theta)\right| \leq C_{N}\left(\frac{\|\tilde{x}\|_{W^{N+1, \infty}\left(\mathbf{C}_{0}(\omega)\right)}}{t}\right)\left(\sum_{|\alpha| \leq N}\left|\nabla_{\theta}^{\alpha} \psi(\theta)\right|\right)
$$

In particular,

$$
\left|I_{F}^{(0)}(\lambda \omega, t)\right| \leq C_{N}\left(\frac{\|\tilde{x}\|_{W^{N+1, \infty}\left(\mathbf{C}_{0}(\omega)\right)}}{t}\right)(\lambda t)^{-N}\|F\|_{W^{N, 1}\left(\mathbf{C}_{0}(\omega)\right)}
$$

or equivalently, for $\xi \in \mathbb{R}^{d} \backslash\left\{\beta_{0}\right\}$

Proof of Lemma 4.2. We denote by $P_{ \pm}:= \pm e_{d}=(0, \ldots, 0, \pm 1)$ the north/south poles and, near the support of $\theta \mapsto \chi_{0}\left(\theta \cdot e_{d}\right)$, we parametrize the sphere by the height $x_{d}=\theta \cdot e_{d}$, yielding the diffeomorphism

$$
\begin{aligned}
(-1,1) \times \mathbb{S}^{d-2} & \rightarrow \mathbb{S}^{d-1} \backslash\left\{P_{+}, P_{-}\right\} \subset \mathbb{R}^{d} \\
\left(x_{d}, \theta^{\prime}\right) & \mapsto\left(\sqrt{1-x_{d}^{2}} \theta^{\prime}, x_{d}\right)
\end{aligned}
$$

The spherical volume measure in these coordinates is given by

$$
\operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta,|d \theta|)=\left(1-x_{d}^{2}\right)^{\frac{d-3}{2}} \operatorname{Vol}_{\mathbb{S}^{d-2}}\left(\theta^{\prime},\left|d \theta^{\prime}\right|\right)\left|d x_{d}\right|
$$

Writing $z=x_{d}$ for short, and recalling that $\operatorname{supp}\left(\chi_{0}\right) \subset(-1,1)$, we have

$$
\begin{aligned}
& \mathcal{I}_{0}[X, f](\lambda, t) \\
:= & \int_{\mathbb{S}^{d-2}} \int_{-1}^{1} \chi_{0}(z) \exp (i \lambda(\underbrace{t z+e_{d} \cdot X\left(\sqrt{1-z^{2}} \theta^{\prime}, z\right)}_{=\varphi\left(z, \theta^{\prime}, t\right)})) f\left(\sqrt{1-z^{2}} \theta^{\prime}, z\right)\left(1-z^{2}\right)^{\frac{d-3}{2}}|d z| \operatorname{Vol}_{\mathbb{S}^{d-2}}\left(\theta^{\prime},\left|d \theta^{\prime}\right|\right)
\end{aligned}
$$

We write $\varphi\left(z, \theta^{\prime}, t\right)=z+t^{-1} e_{d} \cdot X\left(\sqrt{1-z^{2}} \theta^{\prime}, z\right)$ and notice that

$$
\partial_{z} \varphi\left(z, \theta^{\prime}, t\right)=1+t^{-1} e_{d} \cdot d X\left(\sqrt{1-z^{2}} \theta^{\prime}, z\right) \cdot\left(-\frac{z \theta^{\prime}}{\sqrt{1-z^{2}}}, 1\right)
$$

As a consequence, observing that $\left|\left(-\frac{z \theta^{\prime}}{\sqrt{1-z^{2}}}, 1\right)\right|=\sqrt{\frac{z^{2}\left|\theta^{\prime}\right|^{2}}{1-z^{2}}+1}=\frac{1}{\sqrt{1-z^{2}}}$, we have

$$
\partial_{z} \varphi\left(z, \theta^{\prime}, t\right) \geq 1-\frac{t^{-1}}{\sqrt{1-z^{2}}}\left|d X\left(\sqrt{1-z^{2}} \theta^{\prime}, z\right)\right|
$$

where $|d X(\theta)|$ is the norm of linear maps $T_{\theta} \mathbb{S}^{d-1} \rightarrow \mathbb{R}^{d}$ (endowed with their respective Euclidean structures).

Setting

$$
\begin{equation*}
K:=\frac{1}{2} \sup \left\{\frac{1}{\sqrt{1-z^{2}}}\left|d X\left(\sqrt{1-z^{2}} \theta^{\prime}, z\right)\right|, \theta^{\prime} \in \mathbb{S}^{d-2}, z \in \operatorname{supp}\left(\chi_{0}\right)\right\} \tag{4.9}
\end{equation*}
$$

we have $K \leq C\left(\chi_{0}\right)\|d X\|_{L^{\infty}\left(\operatorname{supp}\left(\chi_{0}\right)\right)}<\infty \operatorname{since} \operatorname{supp}\left(\chi_{0}\right) \subset(-1,1)$. We deduce that

$$
\begin{equation*}
\partial_{z} \varphi\left(z, \theta^{\prime}, t\right) \geq 1 / 2 \quad \text { for all } t \geq K, \theta^{\prime} \in \mathbb{S}^{d-2}, z \in \operatorname{supp}\left(\chi_{0}\right) \tag{4.10}
\end{equation*}
$$

Next, we use that $\partial_{z}\left(e^{i \lambda t \varphi\left(z, \theta^{\prime}, t\right)}\right)=i \lambda t \partial_{z} \varphi\left(z, \theta^{\prime}, t\right) e^{i \lambda t \varphi\left(z, \theta^{\prime}, t\right)}$. Setting $L=\frac{1}{\partial_{z} \varphi\left(z, \theta^{\prime}, t\right)} \partial_{z}$ and integrating $N$ times by parts in the variable $z$, we deduce that, for all $N \in \mathbb{N}$,

$$
\begin{equation*}
(i \lambda t)^{-N} \int_{\mathbb{S}^{d-2}} \int_{-1}^{1} e^{i \lambda t \varphi\left(z, \theta^{\prime}, t\right)}\left(L^{T}\right)^{N}\left(\chi_{0}(z) f\left(\sqrt{1-z^{2}} \theta^{\prime}, z\right)\left(1-z^{2}\right)^{\frac{d-3}{2}}\right)|d z| \operatorname{Vol}_{\mathbb{S}^{d-2}}\left(\theta^{\prime},\left|d \theta^{\prime}\right|\right) \tag{4.11}
\end{equation*}
$$

where $L^{T} \psi\left(z, \theta^{\prime}, t\right)=-\partial_{z}\left(\frac{1}{\partial_{z} \varphi\left(z, \theta^{\prime}, t\right)} \psi\left(z, \theta^{\prime}\right)\right)$. We now set, in these coordinates

$$
\mathcal{L}_{N, t} \psi\left(z, \theta^{\prime}\right):=\left(L^{T}\right)^{N}\left(\tilde{\chi}_{0}(z) \psi\left(\sqrt{1-z^{2}} \theta^{\prime}, z\right)\left(1-z^{2}\right)^{\frac{d-3}{2}}\right)\left(1-z^{2}\right)^{-\frac{d-3}{2}}
$$

where $\tilde{\chi}_{0} \operatorname{has} \operatorname{supp}\left(\tilde{\chi}_{0}\right) \subset(-1,1)$ and $\tilde{\chi}_{0}=1$ in a neighborhood of $\operatorname{supp}\left(\chi_{0}\right)$ has the same support properties as $\chi_{0}$ (see Definition 4.1). With this definition, pulling (4.11) back to the sphere yields (4.6).

Next, using (4.10), we thus obtain by induction that there exists some nondecreasing function $r \mapsto C_{N}(r)>0$ (depending only on $\left.N\right)$ such that for all $t \geq K, \theta^{\prime} \in \mathbb{S}^{d-2}$ and $z \in \operatorname{supp}\left(\chi_{0}\right)$,

$$
\left|\left(L^{T}\right)^{N} \psi\left(z, \theta^{\prime}, t\right)\right| \leq C_{N}\left(\|\varphi\|_{W^{N+1, \infty}}\right)\left(\sum_{j=0}^{N}\left|\partial_{z}^{j} \psi\left(z, \theta^{\prime}, t\right)\right|\right)
$$

Pulling this formula back to the sphere implies the existence of a nondecreasing function $r \mapsto$ $C_{N}(r)>0$ such that for all $X \in \mathcal{C}^{N+1}\left(\mathbb{S}^{d-1}\right), t \geq K$ with $K=K\left(\chi_{0}, d X\right)$ defined by (4.9), $\lambda \geq 1$ and $f \in \mathcal{C}^{N}\left(\mathbb{S}^{d-1}\right)$, the pointwise bound (4.7) holds.

Finally, applying this in (4.11) yields

$$
\left|\mathcal{I}_{0}[X, f](\lambda, t)\right| \leq C_{N}\left(\frac{\|X\|_{W^{N+1, \infty}\left(\operatorname{supp}\left(\chi_{0}\right)\right)}}{t}\right)(\lambda t)^{-N}\|f\|_{W^{N, 1}\left(\operatorname{supp}\left(\chi_{0}\right)\right)}
$$

which concludes the proof of the lemma.
4.3. Stationary points. We now turn to the terms $I_{F}^{( \pm 1)}$ and need the following lemma, which is again more or less classical (asymptotics of the Fourier transform of the surface measure on the sphere).

Lemma 4.4 (Stationary points). We set

$$
\mathcal{I}_{ \pm 1}[u](\mu):=\int_{\mathbb{S}^{d}-1} \chi_{ \pm 1}\left(\theta \cdot e_{d}\right) e^{i \mu e_{d} \cdot \theta} u(\theta) d \operatorname{Vol}_{\mathbb{S}^{d}-1}(\theta)
$$

For all $\chi_{1} \in \mathcal{C}^{\infty}([-1,1])$ which is compactly supported in a small enough neighborhood ${ }^{9}$ of 1 and equal to one on a slightly smaller neighborhood of 1 , with $\chi_{-1}(s)=\chi_{1}(-s)$, and for all $N \in \mathbb{N}^{*}$, there exists $C_{N}>0$ such that we have, for all $\mu>0$ and all $u \in W^{2 N+d, 1}\left(\mathbb{S}^{d-1}\right) \subset \mathcal{C}^{2 N+1}\left(\mathbb{S}^{d-1}\right)$

$$
\begin{array}{r}
\left|\mathcal{I}_{ \pm 1}[u](\mu)-e^{ \pm i \mu} e^{\mp i \frac{\pi}{4}(d-1)}\left(\frac{2 \pi}{\mu}\right)^{\frac{d-1}{2}} \sum_{j=0}^{N-1} \mu^{-j}\left(L_{j}^{ \pm} u\right)\left( \pm e_{d}\right)\right| \\
\leq C_{N} \mu^{-\left(N+\frac{d-1}{2}\right)}\|u\|_{W^{2 N+d, 1}\left(\operatorname{supp}\left(\chi_{ \pm 1}\right)\right)}
\end{array}
$$

where $\operatorname{supp}\left(\chi_{ \pm 1}\right)$ means $\theta$ is such that $\theta \cdot e_{d} \in \operatorname{supp}\left(\chi_{ \pm 1}\right)$ and where $L_{j}^{ \pm}$is a differential operator of order $2 j$ on $\mathbb{S}^{d-1}$ (depending only on the geometry of $\mathbb{S}^{d-1}$ ), with $L_{0}^{ \pm}=1$.

Remark 4.5. For the sake of simplicity, we do not write the explicit expression of the operators $L_{j}^{ \pm}$but the proof provides such an expression.

[^8]Recalling the definitions of $I_{F}^{( \pm 1)}$ in (4.4), we want to apply this Lemma with $\mu=\lambda t=\left|\xi-\beta_{0}\right| t>$ 0 and

$$
u(\theta)=e^{i \lambda e_{d} \cdot R_{\omega}^{-1} \tilde{x}\left(R_{\omega} \theta\right)} e^{i \beta_{0} \cdot \tilde{x}\left(R_{\omega} \theta\right)} F\left(R_{\omega} \theta\right)=e^{i \xi \cdot \tilde{x}\left(R_{\omega} \theta\right)} F\left(R_{\omega} \theta\right)
$$

The remainder term can be roughly estimated, for all $\xi \in \mathbb{R}^{d} \backslash\left\{\beta_{0}\right\}$, as

$$
\begin{aligned}
\|u\|_{W^{k, 1}\left(\operatorname{supp}\left(\chi_{ \pm 1}\right)\right)} & =\left\|e^{i \xi \cdot \tilde{x}\left(R_{\omega} \theta\right)} F\left(R_{\omega} \theta\right)\right\|_{W^{k, 1}\left(\operatorname{supp}\left(\chi_{ \pm 1}\right)\right)} \\
& \leq\left\|e^{i \xi \cdot \tilde{x}(\cdot)} F\right\|_{W^{k, 1}\left(\mathbf{C}_{ \pm 1}\left(\xi-\beta_{0}\right)\right)} \\
& \leq C_{k}\left\|e^{i \xi \cdot \tilde{x}(\cdot)}\right\|_{W^{k, \infty}\left(\mathbf{C}_{ \pm 1}\left(\xi-\beta_{0}\right)\right)}\|F\|_{W^{k, 1}\left(\mathbf{C}_{ \pm 1}\left(\xi-\beta_{0}\right)\right)} \\
& \leq C_{k, \beta_{0}} \max \left\{1,\left|\xi-\beta_{0}\right|^{k}\|\tilde{x}\|_{W^{k, \infty}\left(\mathbf{C}_{ \pm 1}\left(\xi-\beta_{0}\right)\right)}^{k}\right\} F \|_{W^{k, 1}\left(\mathbf{C}_{ \pm 1}\left(\xi-\beta_{0}\right)\right)}
\end{aligned}
$$

Concerning the terms in the sum, we have

$$
L_{j}^{ \pm} u(\theta)\left( \pm e_{d}\right)=L_{j}^{ \pm}\left(e^{i \xi \cdot \tilde{x}\left(R_{\omega} \theta\right)} F\left(R_{\omega} \theta\right)\right)\left( \pm e_{d}\right)=L_{j, \frac{\xi}{|\xi|}}^{ \pm}\left(e^{i \xi \cdot \tilde{x}(\cdot)} F\right)\left( \pm \frac{\xi}{|\xi|}\right)
$$

where $L_{j, \omega}^{ \pm}=R_{\omega}^{-1 *} \circ L_{j}^{ \pm} \circ R_{\omega}^{*}$ and $L_{0}^{ \pm}=1$. Hence, we deduce the following corollary:
Corollary 4.6. For all $\chi_{1} \in \mathcal{C}^{\infty}([-1,1])$ compactly supported in a small enough neighborhood of 1 and equal to one on a slightly smaller neighborhood of 1 , with $\chi_{-1}(s)=\chi_{1}(-s)$, and for all $N \in \mathbb{N}^{*}$, we have, for all $t>0, \xi \in \mathbb{R}^{d} \backslash\left\{\beta_{0}\right\}$, $\tilde{x} \in \mathcal{C}^{2 N+d}\left(\mathbb{S}^{d-1}\right)$ and all $F \in \mathcal{C}^{2 N+d}\left(\mathbf{C}_{ \pm 1}\left(\xi-\beta_{0}\right)\right)$,

$$
\begin{aligned}
& I_{F}^{( \pm 1)}\left(\xi-\beta_{0}, t\right) \\
& \quad=e^{ \pm i t\left|\xi-\beta_{0}\right|} e^{\mp i \frac{\pi}{4}(d-1)}\left(\frac{2 \pi}{t\left|\xi-\beta_{0}\right|}\right)^{\frac{d-1}{2}} \sum_{j=0}^{N-1} \frac{1}{\left(t\left|\xi-\beta_{0}\right|\right)^{j}} L_{j, \frac{\xi-\beta_{0}}{\xi-\beta_{0} \mid}}^{ \pm}\left(e^{i \xi \cdot \tilde{x}(\cdot)} F\right)\left( \pm \frac{\xi-\beta_{0}}{\left|\xi-\beta_{0}\right|}\right) \\
& \quad+\mathcal{O}_{N, \beta_{0}}(1) \frac{\max \left\{1,\|\tilde{x}\|_{W^{2 N+d, \infty}\left(\mathbf{C}_{ \pm 1}\left(\xi-\beta_{0}\right)\right)}^{2 N+d}\left|\xi-\beta_{0}\right|^{2 N+d}\right\}}{\left(t\left|\xi-\beta_{0}\right|\right)^{N+\frac{d-1}{2}}}\|F\|_{W^{2 N+d, 1}\left(\mathbf{C}_{ \pm 1}(\xi)\right)},
\end{aligned}
$$

where the constant in the remainder $\mathcal{O}_{N, \beta_{0}}(1)$ depends only on $N$ and the cutoff functions and where $L_{j, \omega}^{ \pm}=R_{\omega}^{-1 *} \circ L_{j}^{ \pm} \circ R_{\omega}^{*}$ with $L_{j}^{ \pm}$the differential operator from Lemma 4.4.

Remark 4.7. We note that the growth in $|\xi|$ is a priori quite bad (except if $\tilde{x}=0$, which is e.g. the case when studying dynamical correlations for functions, see Section 5 below) and we will have to pay attention to this problem in the upcoming sections. For instance, this reads, for $N=1$ and for a constant $C$ depending on $\tilde{x}$,

$$
\begin{aligned}
\left\lvert\, I_{F}^{( \pm 1)}\left(\xi-\beta_{0}, t\right)-e^{i t\left|\xi-\beta_{0}\right|} e^{-i \frac{\pi}{4}(d-1)}\right. & \left.\left(\frac{2 \pi}{t|\xi|}\right)^{\frac{d-1}{2}} e^{i \xi \cdot \tilde{x}\left(\frac{\xi-\beta_{0}}{\left|\xi-\beta_{0}\right|}\right)} F\left(\frac{\xi-\beta_{0}}{\left|\xi-\beta_{0}\right|}\right) \right\rvert\, \\
& \leq C \frac{\left|\xi-\beta_{0}\right|^{2+d}}{\left(t\left|\xi-\beta_{0}\right|\right)^{1+\frac{d-1}{2}}}\|F\|_{W^{2+d, 1}\left(\mathbf{C}_{1}(\xi)\right)}
\end{aligned}
$$

Again, the proof of Lemma 4.4 is classical. As it is rather short, we recall it in order to keep track of the constant in the remainder terms and also to record the explicit expressions for the operators $L_{j}^{ \pm}$.

Proof of Lemma 4.4. We denote by $x^{\prime}=\left(x_{1}, \ldots, x_{d-1}\right)$, with $x_{j}=\theta \cdot e_{j}$ the coordinates along $\left(e_{1}, \ldots, e_{d-1}\right)$, and $x_{d}=\theta \cdot e_{d}$ the coordinate along $e_{d}$.

Near the support of $\theta \mapsto \chi_{ \pm 1}\left(\theta \cdot e_{d}\right)$, we may parametrize the upper/lower half-sphere by the coordinate $x^{\prime}$ :

$$
\begin{aligned}
B_{\mathbb{R}^{d-1}}(0,1) & \rightarrow\left\{x \in \mathbb{S}^{d-1}, \pm x_{d}>0\right\} \\
x^{\prime} & \mapsto\left(x^{\prime}, \pm \sqrt{1-\left|x^{\prime}\right|^{2}}\right) .
\end{aligned}
$$

Setting $\varphi\left(x^{\prime}\right)=\sqrt{1-\left|x^{\prime}\right|^{2}}$, we have on $\operatorname{supp}\left(\chi_{ \pm 1}\right), x_{d}= \pm \varphi\left(x^{\prime}\right)$. Moreover, we have

$$
\nabla \varphi\left(x^{\prime}\right)=\frac{-x^{\prime}}{\sqrt{1-\left|x^{\prime}\right|^{2}}}
$$

from which we infer that the surface measure reads

$$
\operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta,|d \theta|)=\sqrt{1+\left|\nabla \varphi\left(x^{\prime}\right)\right|^{2}}\left|d x^{\prime}\right|=\frac{\left|d x^{\prime}\right|}{\varphi\left(x^{\prime}\right)}
$$

Moreover, given the properties of $\chi_{ \pm 1}$, in these parametrizations, the function

$$
\tilde{\chi}: x^{\prime} \mapsto \chi_{ \pm 1}\left(\theta \cdot e_{d}\right)=\chi_{ \pm 1}\left( \pm \sqrt{1-\left|x^{\prime}\right|^{2}}\right)
$$

does not depend on $\pm$, it is equal to 1 in a neighborhood of 0 and its support verifies

$$
\operatorname{supp}(\tilde{\chi}) \subset B_{\mathbb{R}^{d-1}}(0,1)=\left\{x^{\prime} \in \mathbb{R}^{d-1},\left|x^{\prime}\right|<1\right\} \subset \mathbb{R}^{d-1}
$$

As a consequence, we deduce that

$$
\mathcal{I}_{ \pm 1}[u](\mu)=\int_{\mathbb{R}^{d-1}} e^{ \pm i \mu \varphi\left(x^{\prime}\right)} \tilde{\chi}\left(x^{\prime}\right) u\left(x^{\prime}, \pm \varphi\left(x^{\prime}\right)\right) \frac{\left|d x^{\prime}\right|}{\varphi\left(x^{\prime}\right)}
$$

The phase function $\varphi\left(x^{\prime}\right)$ admits 0 as a unique stationary point with $\varphi(0)=1$ and

$$
\partial_{i} \partial_{j} \varphi(x)=-\delta_{i j}\left(1-\left|x^{\prime}\right|^{2}\right)^{-1 / 2}-x_{i} x_{j}\left(1-\left|x^{\prime}\right|^{2}\right)^{-3 / 2} \quad \Longrightarrow \quad \operatorname{Hess} \varphi(0)=-\operatorname{Id}_{\mathbb{R}^{d-1}}
$$

with determinant $\operatorname{det}(\operatorname{Hess} \varphi(0))=(-1)^{d-1}$ and signature $\operatorname{sgn}(\operatorname{Hess} \varphi(0))=-(d-1)$. Following [Zwo12, p.42], we write

$$
\varphi\left(x^{\prime}\right)=1-\frac{\left|x^{\prime}\right|^{2}}{2} \psi\left(x^{\prime}\right), \quad \text { with } \quad \psi\left(x^{\prime}\right):=2 \int_{0}^{1} \frac{(1-\tau)\left(1+2 \tau^{2}\left|x^{\prime}\right|^{2}\right)}{\left(1-\tau^{2}\left|x^{\prime}\right|^{2}\right)^{\frac{3}{2}}} d \tau
$$

Noting that $\psi\left(x^{\prime}\right)>0$ on the support of $\tilde{\chi}^{\prime}$ and up to taking $\tilde{\chi}$ supported ${ }^{10}$ close enough to 0 , we can make the change of variables $y=\varphi_{1}\left(x^{\prime}\right):=\sqrt{\psi\left(x^{\prime}\right)} x^{\prime}$ in our integral:

$$
\mathcal{I}_{ \pm 1}[u](\mu)=e^{i \pm \mu} \int_{\mathbb{R}^{d-1}} e^{\mp i \mu|y|^{2}} \tilde{\chi} \circ \varphi_{1}^{-1}(y) u\left(\varphi_{1}^{-1}(y), \pm \varphi\left(\varphi_{1}^{-1}(y)\right)\right) \frac{\left|\operatorname{Jac}\left(\varphi_{1}^{-1}\right)(y)\right||d y|}{\varphi\left(\varphi_{1}^{-1}(y)\right)}
$$

Setting

$$
L_{j}(v):=\frac{1}{(2)^{j} j!} \Delta_{y}^{j}\left(\frac{\left|\operatorname{Jac}\left(\varphi_{1}^{-1}\right)(y)\right|}{\varphi\left(\varphi_{1}^{-1}(y)\right)} v\left(\varphi_{1}^{-1}(y)\right)\right)
$$

the standard stationary phase estimate (see ${ }^{11}$ e.g. [Zwo12, Th.3.13-16, p.46-49]) then reads

$$
\begin{array}{r}
\left|\mathcal{I}_{ \pm 1}[u](\mu)-e^{ \pm i \mu} e^{\mp i \frac{\pi}{4}(d-1)}\left(\frac{2 \pi}{\mu}\right)^{\frac{d-1}{2}} \sum_{j=0}^{N-1} e^{\mp \frac{i j \pi}{2}} \mu^{-j}\left(L_{j} u(\cdot, \pm \varphi(\cdot))\right)(0)\right| \\
\leq C_{N} \mu^{-\left(N+\frac{d-1}{2}\right)}\|u\|_{W^{2 N+d, 1}(\operatorname{supp}(\tilde{\chi}))}
\end{array}
$$

Recalling that $u(\cdot, \pm \varphi(\cdot))(0)=u\left( \pm e_{d}\right)$ and pulling this back to the sphere yields the sought result (up to changing the name of the operators $L_{j}$ ).

## 5. Asymptotics of twisted dynamical correlations

In this section, as a first application of these fine stationary phase asymptotics, we give an accurate description of the correlation function as $t \rightarrow+\infty$. See Theorem 5.5 for a precise statement. As a byproduct, this shows how anisotropic Sobolev norms naturally appear when studying analytical properties of geodesic flows and it also proves Theorem 2.5 from the introduction.

[^9]For the sake of simplicity, we restrict ourselves to the case where $k_{1}=2 d-1, k_{2}=0$ and $\tilde{x}(\theta)=0$. Namely, we fix two smooth functions $\varphi$ and $\psi$ in $\mathcal{C}^{\infty}\left(S \mathbb{T}^{d}\right)$ and we want to analyze the behaviour as $t \rightarrow+\infty$ of

$$
\begin{aligned}
\tilde{\mathfrak{C}}_{\varphi, \psi}\left(t, \beta_{0}\right) & :=\int_{S \mathbb{T}^{d}} \varphi(x, \theta) e^{-t \mathbf{V}_{\beta_{0}}}(\psi)(x, \theta)|d x| \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta,|d \theta|) \\
& =\int_{S \mathbb{T}^{d}} e^{-i t \theta \cdot \beta_{0}} \varphi(x, \theta) \psi(x-t \theta, \theta)|d x| \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta,|d \theta|)
\end{aligned}
$$

where $\beta_{0} \in H^{1}\left(\mathbb{T}^{d}, \mathbb{R}\right) \simeq \mathbb{R}^{d}$. According to Remark 3.17, this can be rewritten as

$$
\tilde{\mathcal{C}}_{\varphi, \psi}\left(t, \beta_{0}\right)=\sum_{\xi \in \mathbb{Z}^{d}} \int_{\mathbb{S}^{d-1}} \widehat{\varphi}_{\xi}(\theta) \widehat{\psi}_{-\xi}(\theta) e^{i t\left(\xi-\beta_{0}\right) \cdot \theta} \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta,|d \theta|)
$$

where

$$
\varphi(x, \theta)=\sum_{\xi \in \mathbb{Z}^{d}} \widehat{\varphi}_{\xi}(\theta) \mathfrak{e}_{\xi}(x), \quad \text { and } \quad \psi(x, \theta)=\sum_{\xi \in \mathbb{Z}^{d}} \widehat{\psi}_{\xi}(\theta) \mathfrak{e}_{\xi}(x) .
$$

We will now implement the decomposition (4.1)-(4.2) together with Corollaries 4.3 and 4.6 in order to analyze the asymptotic expansion of $\tilde{\mathcal{C}}_{\varphi, \psi}\left(t, \beta_{0}\right)$ as $t \rightarrow+\infty$.

Remark 5.1. Modulo some tedious work, the analysis could be extended to the more general framework of Lemma 3.15 except that the terms in the asymptotic expansion will be slightly less explicit.

First, we write

$$
\tilde{\mathcal{C}}_{\varphi, \psi}\left(t, \beta_{0}\right)=E_{\beta_{0}}(\varphi, \psi)+\sum_{\xi \in \mathbb{Z}^{d} \backslash\left\{\beta_{0}\right\}} \int_{\mathbb{S}^{d-1}} \widehat{\varphi}_{\xi}(\theta) \widehat{\psi}_{-\xi}(\theta) e^{i t\left(\xi-\beta_{0}\right) \cdot \theta} \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta,|d \theta|),
$$

where

$$
\begin{equation*}
E_{\beta_{0}}(\varphi, \psi):=\int_{\mathbb{S}^{d-1}} \widehat{\varphi}_{\beta_{0}}(\theta) \widehat{\psi}_{-\beta_{0}}(\theta) \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta,|d \theta|), \text { if } \beta_{0} \in \mathbb{Z}^{d} \tag{5.1}
\end{equation*}
$$

and $E_{\beta_{0}}(\varphi, \psi)=0$ otherwise.
5.1. Anisotropic Sobolev spaces of distributions, splitting the correlation function. We decompose these correlations further by writing

$$
\begin{align*}
\tilde{\mathcal{C}}_{\varphi, \psi}\left(t, \beta_{0}\right) & =E_{\beta_{0}}(\varphi, \psi)+\tilde{\mathcal{C}}_{\varphi, \psi}^{-1}(t)+\tilde{\mathcal{C}}_{\varphi, \psi}^{0}(t)+\tilde{\mathcal{C}}_{\varphi, \psi}^{1}(t), \quad \text { with, for } j \in\{-1,0,1\}  \tag{5.2}\\
\tilde{\mathcal{C}}_{\varphi, \psi}^{j}(t) & :=\sum_{\xi \in \mathbb{Z}^{d} \backslash\left\{\beta_{0}\right\}} \int_{\mathbb{S}^{d-1}} \chi_{j}\left(\theta \cdot \frac{\xi-\beta_{0}}{\left|\xi-\beta_{0}\right|}\right) \widehat{\varphi}_{\xi}(\theta) \widehat{\psi}_{-\xi}(\theta) e^{i t\left(\xi-\beta_{0}\right) \cdot \theta} \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta,|d \theta|),
\end{align*}
$$

where the $\chi_{j}$ are the cutoff functions defined in $\S 4.1$ and $E_{\beta_{0}}(\varphi, \psi)$ is defined in (5.1).
We first consider the term $\tilde{\mathcal{C}}^{0}(t)$. Applying Corollary 4.3 to $\tilde{x}=0$ and $F=\widehat{\varphi}_{\xi} \widehat{\psi}_{-\xi}$ combined with the Cauchy-Schwarz inequality $\left\|\widehat{\varphi}_{\xi} \widehat{\psi}_{-\xi}\right\|_{\left.W^{N, 1}\left(\mathbf{C}_{0}\left(\xi-\beta_{0}\right)\right)\right)} \leqslant\left\|\widehat{\varphi}_{\xi}\right\|_{H^{N}\left(\mathbf{C}_{0}\left(\xi-\beta_{0}\right)\right)}\left\|\widehat{\psi}_{-\xi}\right\|_{H^{N}\left(\mathbf{C}_{0}\left(\xi-\beta_{0}\right)\right)}$, we have the following statement:

Lemma 5.2. For all $\chi_{0} \in \mathcal{C}_{c}^{\infty}(-1,1)$ and for all $N \in \mathbb{N}$, there is $C_{N}>0$ such that for every $t>0$, every $\beta_{0} \in \mathbb{R}^{d}$, and every $\varphi, \psi \in \mathcal{C}^{\infty}\left(S \mathbb{T}^{d}\right)$, we have

$$
\left|\tilde{\mathcal{C}}^{0}(t)\right| \leq C_{N} t^{-N} \sum_{\xi \in \mathbb{Z}^{d} \backslash\left\{\beta_{0}\right\}} \frac{\left\|\widehat{\varphi}_{\xi}\right\|_{H^{N}\left(\mathbf{C}_{0}\left(\xi-\beta_{0}\right)\right)}\left\|\widehat{\psi}_{-\xi}\right\|_{H^{N}\left(\mathbf{C}_{0}\left(\xi-\beta_{0}\right)\right)}}{\left|\xi-\beta_{0}\right|^{N}}
$$

We now consider the terms $\mathcal{C}^{ \pm 1}(t)$. Applying similarly Corollary 4.6 to $\tilde{x}(\theta)=0$ and $F=\widehat{\varphi}_{\xi} \widehat{\psi}_{-\xi}$, we have the following statement:

Lemma 5.3. For all $\chi_{1} \in \mathcal{C}^{\infty}([-1,1])$ compactly supported in a small enough neighborhood of 1 and equal to one on a slightly smaller neighborhood of 1 , with $\chi_{-1}(s)=\chi_{1}(-s)$, and for all $N \in \mathbb{N}^{*}$, we have for every $\beta_{0} \in \mathbb{R}^{d}$,

$$
\begin{aligned}
& \tilde{\mathcal{C}}^{ \pm 1}(t)=\sum_{\xi \in \mathbb{Z}^{d} \backslash\left\{\beta_{0}\right\}} e^{ \pm i t\left|\xi-\beta_{0}\right|} e^{\mp i \frac{\pi}{4}(d-1)}\left(\frac{2 \pi}{t\left|\xi-\beta_{0}\right|}\right)^{\frac{d-1}{2}} \\
& \times \sum_{j=0}^{N-1} \frac{1}{\left(t\left|\xi-\beta_{0}\right|\right)^{j}} L_{j, \frac{\xi-\beta_{0}}{\mid--\beta_{0}}}^{ \pm}\left(\widehat{\varphi}_{\xi} \widehat{\psi}_{-\xi}\right)\left( \pm \frac{\xi-\beta_{0}}{\left|\xi-\beta_{0}\right|}\right) \\
&+\mathcal{O}_{N}\left(t^{-N-\frac{d-1}{2}}\right) \sum_{\xi \in \mathbb{Z}^{d} \backslash\left\{\beta_{0}\right\}} \frac{\left\|\widehat{\varphi}_{\xi}\right\|_{H^{2 N+d}\left(\mathbf{C}_{ \pm 1}\left(\xi-\beta_{0}\right)\right)}\left\|\widehat{\psi}_{-\xi}\right\|_{H^{2 N+d}\left(\mathbf{C}_{ \pm 1}\left(\xi-\beta_{0}\right)\right)}}{\left|\xi-\beta_{0}\right|^{N+\frac{d-1}{2}}},
\end{aligned}
$$

as $t \rightarrow+\infty$, where the constant in the remainder $\mathcal{O}_{N}\left(t^{-N-\frac{d-1}{2}}\right)$ depends also on $\beta_{0} \in \mathbb{R}^{d}$.
The above decomposition motivates the following definition of anisotropic Sobolev norms.
Definition 5.4 (Anisotropic Sobolev spaces). Let $\gamma \in \mathbb{R}^{d}$ and let ( $s_{0}, s_{1}, N_{0}, N_{1}$ ) be an element in $\mathbb{Z}_{+}^{2} \times \mathbb{R}^{2}$. For every $\varphi(x, \theta)=\sum_{\xi} \widehat{\varphi}_{\xi}(\theta) \mathfrak{c}_{\xi}(x) \in \mathcal{C}^{\infty}\left(S \mathbb{T}^{d}\right)$, we define the following anisotropic Sobolev norms:

$$
\|\varphi\|_{\mathcal{H}_{\gamma}^{s_{0}, N_{0}, s_{1}, N_{1}}}^{2}:=\sum_{\xi \in \mathbb{Z}^{d}}\langle\xi\rangle^{2 N_{0}}\left\|\widehat{\varphi} \xi^{\xi}\right\|_{H^{s_{0}}\left(\mathbf{C}_{0}(\xi-\gamma)\right)}^{2}+\sum_{\xi \in \mathbb{Z}^{d}, \pm}\langle\xi\rangle^{2 N_{1}}\left\|\widehat{\varphi}_{\xi}\right\|_{H^{s_{1}}\left(\mathbf{C}_{ \pm 1}(\xi-\gamma)\right)}^{2} .
$$

In our applications, these norms are used for $\gamma= \pm \beta_{0}$. The geometric content of these anisotropic norms is discussed in Section 5.3 below.
5.2. Asymptotics of the correlation function. Now, combining this definition with the reduction made in $\S 5.1$, we find

Theorem 5.5 (Asymptotics of twisted correlations). Let $\beta_{0} \in H^{1}\left(\mathbb{T}^{d}, \mathbb{R}\right)$ and let $N \in \mathbb{Z}_{+}^{*}$. For every $\varphi(x, \theta)=\sum_{\xi \in \mathbb{Z}^{d}} \widehat{\varphi}_{\xi}(\theta) \mathfrak{e}_{\xi}(x)$ and $\psi(x, \theta)=\sum_{\xi \in \mathbb{Z}^{d}} \widehat{\psi}_{\xi}(\theta) \mathfrak{e}_{\xi}(x)$ in $\mathcal{C}^{\infty}\left(S \mathbb{T}^{d}\right)$, one has

$$
\begin{aligned}
\tilde{\mathfrak{C}}_{\varphi, \psi}\left(t, \beta_{0}\right): & \int_{S \mathbb{T}^{d}} e^{-i t \beta_{0} \cdot \theta} \varphi(x, \theta) \psi \circ e^{-t V}(x, \theta)|d x| \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta,|d \theta|)-E_{\beta_{0}}(\varphi, \psi) \\
= & (2 \pi)^{\frac{d-1}{2}} \sum_{j=0}^{N-1} \sum_{\xi \in \mathbb{Z}^{d} \backslash\left\{\beta_{0}\right\}, \pm} \frac{e^{ \pm i\left(t\left|\xi-\beta_{0}\right|-\frac{\pi}{4}(d-1)\right)}}{\left(t\left|\xi-\beta_{0}\right|\right)^{j+\frac{d-1}{2}}} L_{j, \left.\frac{\xi-\beta_{0}}{ \pm} \right\rvert\,}\left(\widehat{\varphi}_{\xi} \widehat{\psi}_{-\xi}\right)\left( \pm \frac{\xi-\beta_{0}}{\left|\xi-\beta_{0}\right|}\right) \\
& +\mathcal{O}_{N, \varphi, \psi}\left(\frac{1}{t^{N+\frac{d-1}{2}}}\right),
\end{aligned}
$$

where $E_{\beta_{0}}(\varphi, \psi)$ was defined in (5.1), $L_{j, \omega}^{ \pm}$is the differential operator of degree $2 j$ appearing in Corollary 4.6 and, for every integer $s_{0} \geq N+d$ the constant in the remainder is controlled by
with $C_{N}>0$ depending only on d, $N, s_{0}, \beta_{0}$ and the cutoff functions $\left(\chi_{j}\right)_{j \in\{0,1\}}$ used in $\S 4$.
Theorem 2.5 from the introduction is a direct consequence of this result by taking $\beta_{0}=0$ and $N=1$. See also below for a more detailed connection with the Laplacian. Recalling from the proof of Lemma 4.4 that the operators $L_{j}^{ \pm}$can be computed explicitly (up to some tedious work), this theorem provides an explicit asymptotic of the twisted correlation function for smooth observables. Besides that, another interesting feature of this theorem is that it illustrates how anisotropic Sobolev norms naturally appears when studying the asymptotic behaviour of the geodesic flow on the torus. This is particularly clear in the case of the remainder while for the term in the asymptotic
expansion, one can remark that, using the standard Sobolev inequalities [Eva10, §5.6.3],

$$
\begin{aligned}
\left|L_{j, \frac{\xi-\beta_{0}}{\left|\xi-\beta_{0}\right|}}^{ \pm}\left(\widehat{\varphi}_{\xi} \widehat{\psi}_{-\xi}\right)\left( \pm \frac{\xi-\beta_{0}}{\left|\xi-\beta_{0}\right|}\right)\right| & \leq C_{j}\left\|\widehat{\varphi}_{\xi}\right\|_{\mathcal{C}^{2 j}\left(\mathbf{C}_{ \pm 1}\left(\xi-\beta_{0}\right)\right)}\left\|\widehat{\psi}_{-\xi}\right\|_{\mathcal{C}^{2 j}\left(\mathbf{C}_{ \pm 1}\left(\xi_{-\beta_{0}}\right)\right)} \\
& \leq \tilde{C}_{j}\left\|\widehat{\varphi}_{\xi}\right\|_{H^{2 j+d}\left(\mathbf{C}_{ \pm 1}\left(\xi-\beta_{0}\right)\right)}\left\|\widehat{\psi}_{-\xi}\right\|_{H^{2 j+d}\left(\mathbf{C}_{ \pm 1}\left(\xi-\beta_{0}\right)\right)}
\end{aligned}
$$

Hence, each term in the sum over $j$ is controlled by some anisotropic Sobolev semi-norm (that depends on $j$ ). In summary, test functions can have a priori arbitrarily large polynomial growth in $|\xi|$ away from the direction of $\xi-\beta_{0}$. Close to $\xi-\beta_{0}$, the situations is not as good and one needs to have moderate growth in $|\xi|$ to ensure the convergence of the sums.
5.2.1. Further comments. Let us now comment a little bit more Theorem 5.5. First, we emphasize that our strategy can be viewed as an analogue on flat tori of the strategy used by Ratner [Rat87] to describe the asymptotic behaviour of the correlation function for the geodesic flow on hyperbolic manifolds. Like in this reference, we use tools from harmonic analysis to describe accurately the correlations and we end up naturally with anisotropic Sobolev norms (see e.g. [Rat87, Th.1] for the use of spaces with anisotropic Hölder regularity). As in [Rat87, Cor.1], it is interesting to look at the case where $\varphi$ and $\psi$ do not depend on $\theta$. In that case, the asymptotic expansion of Theorem 5.5 reads as follows

$$
\begin{aligned}
\tilde{\mathcal{C}}_{\varphi, \psi}\left(t, \beta_{0}\right) & :=\int_{S^{d}} e^{-i t \beta_{0}(\theta)} \varphi(x) \psi(x-t \theta)|d x| \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta,|d \theta|) \\
& =\frac{2 \pi^{\frac{d-1}{2}} \delta_{\mathbb{Z}^{d}, \beta_{0}}}{\Gamma\left(\frac{d-1}{2}\right)}\left(\int_{\mathbb{T}^{d}} \varphi(x) \mathfrak{e}_{-\beta_{0}}(x)|d x|\right)\left(\int_{\mathbb{T}^{d}} \psi(x) \mathfrak{e}_{\beta_{0}}(x)|d x|\right) \\
& +(2 \pi)^{\frac{d-1}{2}} \sum_{j=0}^{N-1} \sum_{\xi \in \mathbb{Z} \backslash\left\{\beta_{0}\right\}, \pm} c_{j}^{ \pm}\left(\xi-\beta_{0}\right) \frac{e^{ \pm i\left(t\left|\xi-\beta_{0}\right|-\frac{\pi}{4}(d-1)\right)}}{\left(t\left|\xi-\beta_{0}\right|\right)^{j+\frac{d-1}{2}}} \widehat{\varphi}_{\xi} \widehat{\psi}_{-\xi} \\
& +\mathcal{O}_{N, \varphi, \psi}\left(\frac{1}{t^{N+\frac{d-1}{2}}}\right),
\end{aligned}
$$

where $\delta_{\mathbb{Z}^{d}, \beta_{0}}=1$ if $\beta_{0} \in \mathbb{Z}^{d}$ and $\delta_{\mathbb{Z}^{d}, \beta_{0}}=0$ otherwise and where the coefficients $c_{j}^{ \pm}\left(\xi-\beta_{0}\right)$ depend only on the geometry of $\mathbb{S}^{d-1}$ and are uniformly bounded in terms of $\xi$. In particular, we can verify that the term of degree $j$ is controlled by the following quantity (up to some constant depending only on $j$ and $d$ )

$$
\left(\sum_{\xi \in \mathbb{Z}^{d} \backslash\left\{\beta_{0}\right\}}\left|\xi-\beta_{0}\right|^{-j-\frac{d-1}{2}}\left|\widehat{\varphi}_{\xi}\right|^{2}\right)^{\frac{1}{2}}\left(\sum_{\xi \in \mathbb{Z}^{d} \backslash\left\{\beta_{0}\right\}}\left|\xi+\beta_{0}\right|^{-j-\frac{d-1}{2}}\left|\widehat{\psi}_{\xi}\right|^{2}\right)^{\frac{1}{2}} \leq C_{\beta_{0}}\|\varphi\|_{L^{2}}\|\psi\|_{L^{2}}
$$

The same bound would hold on the remainder term. Hence, $L^{2}$ is the natural space to consider when considering observables depending only on $x$ as in the case of hyperbolic manifolds [Rat87, Cor.1]. See also [HR17, Prop. 2.1] for related results on Birkhoff averages in the case of flat tori.
5.2.2. Relation with the magnetic Laplacian. When the observables $\varphi, \psi$ depend only on $x$ and not on $\theta$, the above discussion can also be understood differently if we make the connection with the magnetic Laplacian

$$
\Delta_{\beta_{0}}:=\sum_{j=1}^{d}\left(\partial_{x_{j}}+i \beta_{0, j}\right)^{2}
$$

Indeed, if we rewrite according to [Ste93, Eq.(25),p.347]

$$
\begin{aligned}
\tilde{\mathcal{C}}_{\varphi, \psi}\left(t, \beta_{0}\right) & :=\int_{S \mathbb{T}^{d}} e^{-i t \beta_{0} \cdot \theta} \varphi(x) \psi(x-t \theta)|d x| \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta,|d \theta|) \\
& =\sum_{\xi \in \mathbb{Z}^{d}} \widehat{\varphi}_{\xi} \widehat{\psi}_{-\xi} \int_{\mathbb{S}^{d-1}} e^{i t\left(\xi-\beta_{0}\right) \cdot \theta} \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta,|d \theta|) \\
& =2 \pi \sum_{\xi \in \mathbb{Z}^{d}} \widehat{\varphi}_{-\xi} \widehat{\psi}_{\xi}\left(t\left|\xi+\beta_{0}\right|\right)^{\frac{2-d}{2}} J_{\frac{d-2}{2}}\left(2 \pi t\left|\xi+\beta_{0}\right|\right) \\
& =2 \pi \int_{\mathbb{T}^{d}} \varphi(x)\left(t \sqrt{-\Delta_{\beta_{0}}}\right)^{\frac{2-d}{2}} J_{\frac{d-2}{2}}\left(2 \pi t \sqrt{-\Delta_{\beta_{0}}}\right) \psi(x)|d x|
\end{aligned}
$$

where $J_{\nu}$ is the standard Bessel function of the first kind. In particular, if we denote by $\Pi$ : $(x, \theta) \in S \mathbb{T}^{d} \mapsto x \in \mathbb{T}^{d}$ the canonical projection, we obtain the following relation between the twisted geodesic flow and the magnetic Laplacian

$$
\begin{equation*}
\Pi_{*} e^{i t\left(i V-\beta_{0}(V)\right)} \Pi^{*}=2 \pi\left(t \sqrt{-\Delta_{\beta_{0}}}\right)^{\frac{2-d}{2}} J_{\frac{d-2}{2}}\left(2 \pi t \sqrt{-\Delta_{\beta_{0}}}\right) \tag{5.3}
\end{equation*}
$$

For observables depending also on the $\theta$ variable, the expressions are slightly less explicit. Yet, as in Theorem 2.5, we can for instance consider the first term in the asymptotic expansion of Theorem 5.5, which is given by

$$
\begin{aligned}
& (2 \pi)^{\frac{d-1}{2}} \sum_{\xi \in \mathbb{Z}^{d} \backslash\left\{\beta_{0}\right\}, \pm} \frac{e^{ \pm i\left(t\left|\xi-\beta_{0}\right|-\frac{\pi}{4}(d-1)\right)}}{\left(t\left|\xi-\beta_{0}\right|\right)^{\frac{d-1}{2}}}\left(\widehat{\varphi}_{\xi} \widehat{\psi}_{-\xi}\right)\left( \pm \frac{\xi-\beta_{0}}{\left|\xi-\beta_{0}\right|}\right) \\
& =(2 \pi)^{\frac{d-1}{2}} \sum_{\xi \in \mathbb{Z}^{d} \backslash\left\{\beta_{0}\right\}, \pm} \frac{e^{ \pm i\left(t\left|\xi+\beta_{0}\right|-\frac{\pi}{4}(d-1)\right)}}{\left(t\left|\xi+\beta_{0}\right|\right)^{\frac{d-1}{2}}}\left(\widehat{\varphi}_{-\xi} \widehat{\psi}_{\xi}\right)\left(\mp \frac{\xi+\beta_{0}}{\left|\xi+\beta_{0}\right|}\right)
\end{aligned}
$$

If we introduce the following map

$$
\Pi_{\beta_{0}}^{ \pm}(\varphi):=\sum_{\xi \in \mathbb{Z}^{d} \backslash\left\{-\beta_{0}\right\}} \widehat{\varphi}_{\xi}\left( \pm \frac{\xi+\beta_{0}}{\left|\xi+\beta_{0}\right|}\right) \mathfrak{e}_{\xi}
$$

then the (first term) asymptotic expansion of $\tilde{\mathcal{C}}_{\varphi, \psi}\left(t, \beta_{0}\right)$ in Theorem 5.5 can be rewritten, modulo $\mathcal{O}_{\varphi, \psi}\left(\frac{1}{t^{1+\frac{d-1}{2}}}\right)$, as

$$
\begin{align*}
\tilde{\mathcal{C}}_{\varphi, \psi}\left(t, \beta_{0}\right) & =\left(\frac{2 \pi}{t}\right)^{\frac{d-1}{2}} \sum_{ \pm} e^{\mp \frac{i \pi(d-1)}{4}} \int_{\mathbb{T}^{d}}\left(\frac{e^{ \pm i t \sqrt{-\Delta_{-\beta_{0}}}}}{\left(-\Delta_{-\beta_{0}}\right)^{\frac{d-1}{4}}} \circ \Pi_{-\beta_{0}}^{ \pm}(\varphi)\right)(x) \Pi_{\beta_{0}}^{\mp}(\psi)(x)|d x| \\
& =\left(\frac{2 \pi}{t}\right)^{\frac{d-1}{2}} \sum_{ \pm} e^{\mp \frac{i \pi(d-1)}{4}} \int_{\mathbb{T}^{d}} \Pi_{-\beta_{0}}^{ \pm}(\varphi)(x)\left(\frac{e^{ \pm i t \sqrt{-\Delta_{\beta_{0}}}}}{\left(-\Delta_{\beta_{0}}\right)^{\frac{d-1}{4}}} \circ \Pi_{\beta_{0}}^{\mp}(\psi)\right)(x)|d x|, \tag{5.4}
\end{align*}
$$

after having used the Plancherel Theorem. Similarly, all the terms in the asymptotic expansion can be written in the same fashion except that the expression will be slightly more involved.
5.3. Geometry of the anisotropic Sobolev norms. In this section, we review a few facts from Riemannian geometry [Rug07] that are useful to understand the geometric picture behind these norms.
5.3.1. Decomposition of the tangent space of $S \mathbb{T}^{d}$. The tangent space to a point $(x, \theta) \in S \mathbb{T}^{d}$ decomposes in a way which is adapted to the dynamical features of our problem. First, we write

$$
T_{x, \theta} S \mathbb{T}^{d} \simeq T_{x} \mathbb{T}^{d} \times T_{\theta} \mathbb{S}^{d-1}
$$

Given $\theta \in \mathbb{S}^{d-1}$, we consider as in Section 3.1 an orthonormal family $\left(e_{1}(\theta), \ldots, e_{d-1}(\theta)\right)$ such that

$$
\operatorname{det}\left(\theta, e_{1}(\theta), \ldots, e_{d-1}(\theta)\right)>0
$$

At a given point $(x, \theta) \in S \mathbb{T}^{d}$, we define the horizontal space as

$$
\mathcal{H}_{x, \theta}:=\operatorname{Span}_{T_{x} \mathbb{T}^{d}}\left(e_{1}(\theta), \ldots, e_{d-1}(\theta)\right) \times\{0\} \subset T_{x} \mathbb{T}^{d} \times\{0\} \subset T_{x, \theta}\left(S \mathbb{T}^{d}\right)
$$

Similarly, we introduce the vertical space

$$
\mathcal{V}_{x, \theta}:=\{0\} \times \operatorname{Span}_{T_{\theta} \mathbb{S}^{d-1}}\left(e_{1}(\theta), \ldots, e_{d-1}(\theta)\right)=\{0\} \times T_{\theta} \mathbb{S}^{d-1} \subset T_{x, \theta}\left(S \mathbb{T}^{d}\right)
$$

Note that $\mathcal{V}(x, \theta)$ is the tangent space to the submanifold $S_{x} \mathbb{T}^{d}$, or equivalently the kernel of the tangent map of $\Pi:(x, \theta) \in S \mathbb{T}^{d} \mapsto x \in \mathbb{T}^{d}$. Letting $V(x, \theta)=\theta \cdot \partial_{x} \simeq \theta \in T_{x} \mathbb{T}^{d} \times\{0\}$, one has then

$$
T_{x, \theta} S \mathbb{T}^{d}=\mathbb{R} V(x, \theta) \oplus \mathcal{H}_{x, \theta} \oplus \mathcal{V}_{x, \theta}
$$

In the terminology of symplectic geometry, $\mathcal{H}_{x, \theta} \oplus \mathcal{V}_{x, \theta}$ is the kernel of the Liouville (contact) form $\alpha(x, \theta, d x, d \theta):=\theta \cdot d x$. This decomposition of the tangent space allows to write the following nice expression of the tangent map $D\left(e^{t V}\right)$ at a point $(x, \theta)$ :

$$
\left[D\left(e^{t V}\right)(x, \theta)\right]_{\mathbb{R} V(x, \theta) \oplus \mathcal{H}_{x, \theta} \oplus \mathcal{V}_{x, \theta}}=\left(\begin{array}{ccc}
1 & 0 & 0  \tag{5.5}\\
0 & \text { Id } & \text { tId } \\
0 & 0 & \text { Id }
\end{array}\right) .
$$

Remark 5.6. Every vector in $\mathcal{H}_{x, \theta} \oplus \mathcal{V}_{x, \theta}$ tends to the horizontal bundle under the tangent map as $t \rightarrow \pm \infty$. In fact, in the case of flat tori, the stable and unstable bundles ${ }^{12}$ coincide and are equal to the horizontal bundle [Rug07, Ch. 3, §1.3]. See Figure 2.


Figure 2. Action of the tangent map on the kernel of the contact form.

Remark 5.7. We will denote by $E_{0}^{*}=\mathbb{R} \alpha \subset T^{*} S \mathbb{T}^{d}$ the annihilator of $\mathcal{H} \oplus \mathcal{V}$, by $\mathcal{H}^{*} \subset T^{*} S \mathbb{T}^{d}$ the annihilator of $\mathbb{R} V \oplus \mathcal{V}$ and by $\mathcal{V}^{*} \subset T^{*} S \mathbb{T}^{d}$ the annihilator of $\mathbb{R} V \oplus \mathcal{H}$. The action of the tangent map on $T^{*} S \mathbb{T}^{d}$ reads

$$
\left[D\left(e^{t V}\right)(x, \theta)^{T}\right]_{\mathbb{R} \alpha(x, \theta) \oplus \mathcal{H}_{x, \theta}^{*} \oplus \mathcal{V}_{x, \theta}^{*}}^{-1}=\left(\begin{array}{ccc}
1 & 0 & 0  \tag{5.6}\\
0 & \mathrm{Id} & 0 \\
0 & -t \mathrm{Id} & \mathrm{Id}
\end{array}\right)
$$

[^10]5.3.2. Geometric interpretation of the anisotropic seminorms. With that geometric description at hand, we can give a rough geometric interpretation of our anisotropic spaces using the notion of pseudodifferential operators [Hör85]. Usually, Sobolev spaces are designed using the quantization of a symbol of the form $\left(1+|(\xi, \Theta)|_{x, \theta}^{2}\right)^{\frac{s}{2}}$ where $(x, \theta, \xi, \Theta)$ is an element in $T^{*} S \mathbb{T}^{d}$ and $s$ is the Sobolev regularity. Here, due to the explicit structure of the problem, we did not write exactly things in that fashion. Yet, our spaces would in principle correspond to replace $s$ by a function $s(x, \theta, \xi, \Theta)$ whose values depend on the directions in $T^{*} S \mathbb{T}^{d}$ and thus to work with anisotropic symbols. More precisely, taking $\gamma=0$ for simplicity, we would in fact require using this pseudodifferential approach that

- near $E_{0}^{*}$, the symbol is given by $\left(1+|\xi|^{2}\right)^{\frac{N_{1}}{2}}\left(1+|\Theta|_{\theta}^{2}\right)^{\frac{s_{1}}{2}}$. Thus, we are roughly requiring a Sobolev regularity $N_{1}$ along $E_{0}^{*}$.
- near $\mathcal{H}^{*} \oplus \mathcal{V}^{*}$, the symbol is given by $\left(1+|\xi|^{2}\right)^{\frac{N_{0}}{2}}\left(1+|\Theta|_{\theta}^{2}\right)^{\frac{s_{0}}{2}}$. In particular, on $\mathcal{V}^{*}$, this correspond to a Sobolev regularity of order $s_{0}$ while on $\mathcal{H}^{*}$, the Sobolev regularity is $N_{0}$.
See Figure 3.


Figure 3. Sobolev regularity in the cotangent picture.

## 6. Anisotropic spaces of currents

In Lemma 3.13, we saw that, for $\beta_{0} \in H^{1}\left(\mathbb{T}^{d}, \mathbb{R}\right)$ and for a smooth function $\chi: \mathbb{R} \rightarrow \mathbb{R}$ with enough decay at infinity, the operator

$$
\widehat{\chi}\left(-i \mathbf{V}_{\beta_{0}}\right):=\int_{\mathbb{R}} \chi(t) e^{-t \mathbf{V}_{\beta_{0}}}|d t|
$$

is bounded when acting on the space of continuous differential forms. Now we aim at describing anisotropic Sobolev spaces adapted to the dynamics of the geodesic flow on which $\widehat{\chi}\left(-i \mathbf{V}_{\beta_{0}}\right)$ will still extend continuously.
6.1. Anisotropic Sobolev spaces. Motivated by the norms of Definition 5.4 appearing in the description of the correlation function, we introduce the following spaces of currents.
Definition 6.1 (Anisotropic Sobolev spaces of currents). Let $\beta_{0} \in H^{1}\left(\mathbb{T}^{d}, \mathbb{R}\right)$, let $0 \leq k \leq 2 d-1$ and let $\left(s_{0}, s_{1}, N_{0}, N_{1}\right)$ in $\mathbb{Z}_{+}^{2} \times \mathbb{R}^{2}$. We define the following anisotropic Sobolev norm:

$$
\|\varphi\|_{\mathcal{H}_{k, \beta_{0}}^{s_{0}, N_{0}, s_{1}, N_{1}}}^{2}:=\sum_{\xi \in \mathbb{Z}^{d}}\langle\xi\rangle^{2 N_{0}}\left\|\pi_{\xi}^{(k)}(\varphi)\right\|_{H^{s_{0}}\left(\mathbf{C}_{0}\left(\xi-\beta_{0}\right)\right)}^{2}+\sum_{\xi \in \mathbb{Z}^{d}, \pm}\langle\xi\rangle^{2 N_{1}}\left\|\pi_{\xi}^{(k)}(\varphi)\right\|_{H^{s_{1}}\left(\mathbf{C}_{ \pm 1}\left(\xi-\beta_{0}\right)\right)}^{2}
$$

where $\langle\eta\rangle:=\left(1+|\eta|^{2}\right)^{\frac{1}{2}}$ and where the Sobolev norms $H^{s}$ on forms are understood in the sense of Remark 3.9. We define the space $\mathcal{H}_{k, \beta_{0}}^{s_{0}, N_{0}, s_{1}, N_{1}}$ to be the completion of $\Omega^{k}\left(S \mathbb{T}^{d}\right)$ for this norm.

As above, we note that these norms depend implicitely on the cutoff functions used in §4.1. In particular, the conic neighborhood $\mathbf{C}_{ \pm 1}(\omega)$ can be chosen arbitrarily close to $\omega \in \mathbb{S}^{d-1}$ but it cannot be too large in order to apply Lemma 4.4. Using these spaces, one gets

Theorem 6.2. Let $0 \leq k \leq 2 d-1, M, N$ be elements in $\mathbb{Z}_{+}, \beta_{0} \in H^{1}\left(\mathbb{T}^{d}, \mathbb{R}\right)$ and $\chi \in \mathcal{C}_{c}^{\infty}\left(\mathbb{R}_{+}^{*}\right)$. Then,

$$
\widehat{\chi}\left(-i \mathbf{V}_{\beta_{0}}\right): \mathcal{H}_{k,-\beta_{0}}^{M,-M / 2,0,-N / 2} \rightarrow\left(\mathcal{H}_{2 d+1-k, \beta_{0}}^{M,-M / 2,0,-N / 2}\right)^{\prime}
$$

defines a continuous linear map, where $\left(\mathcal{H}_{2 d+1-k, \beta_{0}}^{M,-M / 2,0, N / 2}\right)^{\prime} \subset \mathcal{D}^{\prime k}\left(S \mathbb{T}^{d}\right)$ is the topological dual of $\mathcal{H}_{2 d+1-k, \beta_{0}}^{M,-M / 2,0, N / 2}$.

Compared with the spaces appearing when describing the asymptotics of the correlation function, we now require that test currents are regular enough along the vertical space $\mathcal{V}$ while they can be singular along the horizontal space $\mathbb{R} V \oplus \mathcal{H}$. See Figure 3 with $s_{0}=M, N_{0}=-M / 2$ and $N_{1}=-N / 2$.
6.2. Mapping properties. For later applications to counting orthogeodesics, we also fix a smooth map

$$
\tilde{x}: \mathbb{S}^{d-1} \rightarrow \mathbb{R}^{d}
$$

and our goal is to study more generally the analytical properties of the operator:

$$
\widehat{\chi}\left(-i \mathbf{V}_{\beta_{0}}\right) \mathbf{T}_{-\tilde{x}}^{*}:=\int_{\mathbb{R}} \chi(t) e^{-t \mathbf{V}_{\beta_{0}}} \mathbf{T}_{-\tilde{x}}^{*}|d t|
$$

under appropriate assumptions on $\chi$. To that aim, we fix $0 \leq k_{1}, k_{2} \leq 2 d-1$ and two smooth forms $(\varphi, \psi) \in \Omega^{k_{1}}\left(S \mathbb{T}^{d}\right) \times \Omega^{k_{2}}\left(S \mathbb{T}^{d}\right)$ (with $k_{1}+k_{2}=2 d-1$ ). Hence, for $\chi$ with enough regularity, we want to study the properties of

$$
\begin{equation*}
\int_{S \mathbb{T}^{d}} \varphi \wedge \widehat{\chi}\left(-i \mathbf{V}_{\beta_{0}}\right) \mathbf{T}_{-\tilde{x}}^{*}(\psi)=\int_{\mathbb{R}} \chi(t) \mathcal{C}_{\varphi, \mathbf{T}_{-\tilde{x}}^{*}(\psi)}\left(t, \beta_{0}\right)|d t| \tag{6.1}
\end{equation*}
$$

in terms of the anisotropic Sobolev norms we have just introduced. In order to state the main technical result of this section, let us introduce the following definition:
Definition 6.3. Let $p \in \mathbb{R}$ and let $N \in \mathbb{Z}_{+}$. We say that $\chi$ is $(N, p)$-admissible if $\chi \in \mathcal{C}^{\infty}\left(\mathbb{R}_{+}\right)$ and if it satisfies the following properties:

- the support of $\chi$ does not contain 0 ,
- for every $0 \leq m \leq N$,

$$
\lim _{t \rightarrow+\infty} \frac{d^{m}}{d t^{m}}\left(t^{p} \chi(t)\right)=0
$$

- $t \mapsto t^{p} \chi(t) \in L^{1}\left(\mathbb{R}_{+}\right)$.

This definition obviously includes the case of smooth compactly supported functions on $\mathbb{R}_{+}^{*}$ and Theorem 6.2 is actually a corollary of the much more precise statement:

Theorem 6.4. Let $k_{1}+k_{2}=2 d-1$, let $\beta_{0} \in H^{1}\left(\mathbb{T}^{d}, \mathbb{R}\right)$ and let $M, N$ be elements in $\mathbb{Z}_{+}$. There exists a constant $C_{M, N}>0$ such that for all $(\varphi, \psi) \in \Omega^{k_{1}}\left(S \mathbb{T}^{d}\right) \times \Omega^{k_{2}}\left(S \mathbb{T}^{d}\right)$ and for all $\chi$ which is $(N, p)$-admissible (for every $0 \leq p \leq \min \left\{k_{1}, k_{2}\right\}$ ) and which satisfies ${ }^{13} \operatorname{supp} \chi \subset$ $\left(C\left(\chi_{0}\right)\|d \tilde{x}\|_{L^{\infty}\left(\mathbb{S}^{d-1}\right)}, \infty\right)$, one has

$$
\begin{equation*}
\int_{\mathbb{R}} \chi(t) \mathcal{C}_{\varphi, \mathbf{T}_{-\tilde{x}}^{*}(\psi)}\left(t, \beta_{0}\right)|d t|=\sum_{l=0}^{\min \left\{k_{1}, k_{2}\right\}} \mathcal{J}_{\chi}^{(l)}(\varphi, \psi) \tag{6.2}
\end{equation*}
$$

[^11]where, for all $0 \leq l \leq \min \left\{k_{1}, k_{2}\right\}$,
\[

$$
\begin{aligned}
& \left|\mathcal{J}_{\chi}^{(l)}(\varphi, \psi)-\frac{E_{\beta_{0}}^{(l)}}{l!} \int_{\mathbb{R}} \chi(t) t^{l}\right| d t|\mid \\
& \leq C_{M, N} \max \left\{\left\|\chi(t) t^{l-M}\right\|_{L^{1}\left(\mathbb{R}_{+}\right)},\left\|\frac{d^{N}}{d t^{N}}\left(t^{l} \chi\right)\right\|_{L^{1}\left(\mathbb{R}_{+}\right)}\right\}\|\varphi\|_{\mathcal{H}_{1}}\|\psi\|_{\mathcal{H}_{2}}
\end{aligned}
$$
\]

with $\mathcal{H}_{1}:=\mathcal{H}_{k_{1}, \beta_{0}}^{M,-M / 2,0,-N / 2}$ and $\mathcal{H}_{2}:=\mathcal{H}_{k_{2},-\beta_{0}}^{M,-M / 2,0,-N / 2}$ defined by Definition 6.1 and with

$$
\begin{equation*}
E_{\beta_{0}}^{(l)}=\int_{\mathbb{S}^{d-1}} e^{i \beta_{0} \cdot \tilde{x}(\theta)} B_{\tilde{x}, \beta_{0}}^{\left(k_{2}, l\right)}(\varphi, \psi)(\theta) \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta, d \theta) \text { if } \beta_{0} \in H^{1}\left(\mathbb{T}^{d}, \mathbb{Z}\right), \quad E_{\beta_{0}}^{(l)}=0 \text { otherwise } \tag{6.3}
\end{equation*}
$$

where the explicit expression for $B_{\tilde{x}, \beta_{0}}^{\left(k_{2}, l\right)}$ is given by (3.20).
The function $\chi_{0}$ appearing in this Theorem is the one from Definition 4.1 and we recall that each function $\chi_{j}$ implicitely appears in the definition of the anisotropic spaces. Before entering the details of the proof, we start with the following observation which follows from a direct integration by parts argument:

Lemma 6.5. Suppose that $\chi$ is ( $N, p$ )-admissible. Then, for every $\lambda \neq 0$, one has

$$
\left|\int_{\mathbb{R}_{+}} t^{p} \chi(t) e^{-i t \lambda}\right| d t\left|\left|\leq|\lambda|^{-N}\left\|\frac{d^{N}}{d t^{N}}\left(t^{p} \chi(t)\right)\right\|_{L^{1}\left(\mathbb{R}_{+}\right)} .\right.\right.
$$

This lemma will allow us to gain a decay in $|\xi|$ that is lacking in the region where the phase is stationary. In other words, it will allow us to take observables that may be singular along the direction of $V$ while for the correlation function we required to have some regularity along $V$; that is to say, we can now choose $N_{1} \ll-1$ in Figure 3. Henceforth, in the proof of Theorem 6.4, we only make use of the non-stationary phase estimate of Corollary 4.3 and do not rely on stationary phase estimates of Corollary 4.6.

Proof of Theorem 6.4. According to Lemma 3.15, we start from the decomposition (3.18)-(3.19) of the dynamical correlator $\mathcal{C}$ according to the various homogeneity in the variable $t$. Integrating the expression of $\mathcal{C}_{\varphi, \mathbf{T}_{-\tilde{x}}^{*}(\psi)}^{l}\left(t, \beta_{0}\right)$ in (3.18) against $\chi(t)$ will then yield (6.2) with

$$
\begin{equation*}
\mathcal{J}_{\chi}^{(l)}(\varphi, \psi)=\int_{\mathbb{R}} \chi(t) \mathcal{C}_{\varphi, \mathbf{T}_{-\tilde{x}}^{*}(\psi)}^{l}\left(t, \beta_{0}\right)|d t| . \tag{6.4}
\end{equation*}
$$

We decompose $\mathcal{C}_{\varphi, \mathbf{T}_{-\tilde{x}}^{*}(\psi)}^{l}\left(t, \beta_{0}\right)$ further by writing

$$
\begin{align*}
\mathcal{C}_{\varphi, \mathbf{T}_{-\tilde{x}}^{*}(\psi)}^{l}\left(t, \beta_{0}\right) & =\frac{t^{l}}{l!} E_{\beta_{0}}^{(l)}+\frac{t^{l}}{l!} \mathrm{C}^{(l,-1)}(t)+\frac{t^{l}}{l!} \mathrm{C}^{(l, 0)}(t)+\frac{t^{l}}{l!} \mathcal{C}^{(l, 1)}(t), \quad \text { with, for } j \in\{-1,0,1\}  \tag{6.5}\\
E_{\beta_{0}}^{(l)} & =\int_{\mathbb{S}^{d-1}} e^{i \beta_{0} \cdot \tilde{x}(\theta)} B_{\tilde{x}, \beta_{0}}^{\left(k_{2}, l\right)}(\varphi, \psi)(\theta) \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta, d \theta) \quad \text { if } \beta_{0} \in H^{1}\left(\mathbb{T}^{d}, \mathbb{Z}\right) \simeq \mathbb{Z}^{d} \\
E_{\beta_{0}}^{(l)} & =0 \quad \text { otherwise },
\end{align*}
$$

and

$$
\mathfrak{C}^{(l, j)}(t)=\sum_{\xi \in \mathbb{Z}^{d} \backslash\left\{\beta_{0}\right\}} \int_{\mathbb{S}^{d-1}} \chi_{j}\left(\theta \cdot \frac{\xi-\beta_{0}}{\left|\xi-\beta_{0}\right|}\right) e^{i t\left(\xi-\beta_{0}\right) \cdot \theta} e^{i \xi \cdot \tilde{x}(\theta)} B_{\tilde{x}, \xi}^{\left(k_{2}, l\right)}(\varphi, \psi)(\theta) \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta, d \theta),
$$

where the functions $\chi_{j}$ were introduced in Definition 4.1. Note that $E_{\beta_{0}}^{(l)}$ concerns the Fourier coefficient $\xi=\beta_{0}$ (in the case $\beta_{0} \in \mathbb{Z}^{d}$ and it vanishes otherwise). The above decomposition indexed by $j=-1,0,1$ corresponds to the different integration regions of $\mathbb{S}^{d-1}$ on which we study the oscillatory integral. Moreover, it is a time invariant quantity.

We now compute each term in (6.5). The first term is nothing but

$$
\begin{equation*}
\int_{\mathbb{R}} \chi(t) \frac{t^{l}}{l!} E_{\beta_{0}}^{(l)}|d t|=\frac{E_{\beta_{0}}^{(l)}}{l!} \int_{\mathbb{R}} \chi(t) t^{l}|d t| \tag{6.6}
\end{equation*}
$$

We next consider the term involving $\mathcal{C}^{(l, 0)}(t)$. Applying Corollary 4.3 to the function $F(\theta)=$ $B_{\tilde{x}, \xi}^{\left(k_{2}, l\right)}(\varphi, \psi)(\theta)$, we have the following statement: there exists $C\left(\chi_{0}\right)>0$ (independent of $\left.\tilde{x}\right)$ such that for all $M \in \mathbb{Z}_{+}$, there is $C_{M}>0$ (depending on the map $\tilde{x}: \mathbb{S}^{d-1} \mapsto \mathbb{R}^{d}$ ) such that for all $t>C\left(\chi_{0}\right)\|d \tilde{x}\|_{L^{\infty}\left(\mathbb{S}^{d-1}\right)},|\xi| \geq 1,(\varphi, \psi) \in \Omega^{k_{1}}\left(S \mathbb{T}^{d}\right) \times \Omega^{k_{2}}\left(S \mathbb{T}^{d}\right)$, we have

$$
\left|\mathcal{C}^{(l, 0)}(t)\right| \leq \sum_{\xi \in \mathbb{Z}^{d} \backslash\left\{\beta_{0}\right\}} C_{M} \frac{1}{\left(\left|\xi-\beta_{0}\right| t\right)^{M}}\left\|B_{\tilde{x}, \xi}^{\left(k_{2}, l\right)}(\varphi, \psi)(\cdot)\right\|_{W^{M, 1}\left(\mathbf{C}_{0}\left(\xi-\beta_{0}\right)\right)}
$$

According to (3.21), this implies for every $k_{1}+k_{2}=2 d-1$, for every $0 \leq l \leq \min \left\{k_{1}, k_{2}\right\}$ and for every $(\varphi, \psi) \in \Omega^{k_{1}}\left(S \mathbb{T}^{d}\right) \times \Omega^{k_{2}}\left(S \mathbb{T}^{d}\right)$,

$$
\left|\mathcal{C}^{(l, 0)}(t)\right| \leq \frac{C_{M}}{t^{M}} \sum_{\xi \in \mathbb{Z}^{d} \backslash\left\{\beta_{0}\right\}} \frac{1}{\left|\xi-\beta_{0}\right|^{M}}\left\|\pi_{\xi}^{\left(k_{1}\right)}(\varphi)\right\|_{H^{M}\left(\mathbf{C}_{0}\left(\xi-\beta_{0}\right)\right)}\left\|\pi_{-\xi}^{\left(k_{2}\right)}(\psi)\right\|_{H^{M}\left(\mathbf{C}_{0}\left(\xi-\beta_{0}\right)\right)}
$$

We thus obtain, if $\operatorname{supp} \chi \subset\left(C\left(\chi_{0}\right)\|d \tilde{x}\|_{L^{\infty}\left(\mathbb{S}^{d-1}\right)}, \infty\right)$, that

$$
\left|\int_{\mathbb{R}} \chi(t) \frac{t^{l}}{l!} \mathfrak{C}^{(l, 0)}(t)\right| d t|\mid
$$

$$
\begin{equation*}
\leq C_{M}\left\|\chi(t) t^{l-M}\right\|_{L^{1}\left(\mathbb{R}_{+}\right)} \sum_{\xi \in \mathbb{Z}^{d} \backslash\left\{\beta_{0}\right\}} \frac{1}{\left|\xi-\beta_{0}\right|^{M}}\left\|\pi_{\xi}^{\left(k_{1}\right)}(\varphi)\right\|_{H^{M}\left(\mathbf{C}_{0}\left(\xi-\beta_{0}\right)\right)}\left\|\pi_{-\xi}^{\left(k_{2}\right)}(\psi)\right\|_{H^{M}\left(\mathbf{C}_{0}\left(\xi-\beta_{0}\right)\right)} \tag{6.7}
\end{equation*}
$$

For the remaining two terms, we write

$$
\begin{aligned}
\int_{\mathbb{R}} \chi(t) \frac{t^{l}}{l!} \mathcal{C}^{(l, \pm 1)}(t)|d t|=\sum_{\xi \in \mathbb{Z}^{d} \backslash\left\{\beta_{0}\right\}} & \int_{\mathbb{S}^{d-1}}\left(\int_{\mathbb{R}} \chi(t) \frac{t^{l}}{l!} e^{i t\left(\xi-\beta_{0}\right) \cdot \theta}|d t|\right) \\
& \times \chi_{ \pm 1}\left(\theta \cdot \frac{\xi-\beta_{0}}{\left|\xi-\beta_{0}\right|}\right) e^{i \xi \cdot \tilde{x}(\theta)} B_{\tilde{x}, \xi}^{\left(k_{2}, l\right)}(\varphi, \psi)(\theta) \operatorname{Vol}_{\mathbb{S}^{d}-1}(\theta, d \theta)
\end{aligned}
$$

We then remark from the properties of $\chi_{ \pm 1}$ in Definition 4.1 that $s \in \operatorname{supp}\left(\chi_{ \pm 1}\right) \Longrightarrow|s| \geq \epsilon_{0}>0$. Lemma 6.5 then implies that for $(\theta, \xi)$ in $\operatorname{supp} \chi_{ \pm 1}\left(\theta \cdot \frac{\xi-\beta_{0}}{\left|\xi-\beta_{0}\right|}\right)$ :

$$
\begin{aligned}
&\left|\int_{\mathbb{R}} \chi(t) t^{l} e^{i t\left(\xi-\beta_{0}\right) \cdot \theta}\right| d t\left|\left\lvert\, \leq \frac{1}{\left|\left(\xi-\beta_{0}\right) \cdot \theta\right|^{N}}\left\|\frac{d^{N}}{d t^{N}}\left(t^{l} \chi\right)\right\|_{L^{1}\left(\mathbb{R}_{+}\right)}\right.\right. \\
& \leq \frac{1}{\left|\epsilon_{0}\left(\xi-\beta_{0}\right)\right|^{N}}\left\|\frac{d^{N}}{d t^{N}}\left(t^{l} \chi\right)\right\|_{L^{1}\left(\mathbb{R}_{+}\right)}
\end{aligned}
$$

Coming back to our problem, we can derive the estimate

$$
\begin{aligned}
& \left|\int_{\mathbb{R}} \chi(t) \frac{t^{l}}{l!} \mathfrak{e}^{(l, \pm 1)}(t)\right| d t|\mid \\
& \leq C_{N}\left\|\frac{d^{N}}{d t^{N}}\left(t^{l} \chi\right)\right\|_{L^{1}\left(\mathbb{R}_{+}\right)} \sum_{\xi \in \mathbb{Z}^{d} \backslash\left\{\beta_{0}\right\}} \frac{1}{\left|\left(\xi-\beta_{0}\right)\right|^{N}}\left\|B_{\tilde{x}, \xi}^{\left(k_{2}, l\right)}(\varphi, \psi)(\theta)\right\|_{L^{1}\left(\mathbf{C}_{ \pm 1}\left(\xi-\beta_{0}\right)\right)} \\
& \leq C_{N}\left\|\frac{d^{N}}{d t^{N}}\left(t^{l} \chi\right)\right\|_{L^{1}\left(\mathbb{R}_{+}\right)} \sum_{\xi \in \mathbb{Z}^{d} \backslash\left\{\beta_{0}\right\}} \frac{\left\|\pi_{\xi}^{\left(k_{1}\right)}(\varphi)\right\|_{L^{2}\left(\mathbf{C}_{ \pm 1}\left(\xi-\beta_{0}\right)\right)}\left\|\pi_{-\xi}^{\left(k_{2}\right)}(\psi)\right\|_{L^{2}\left(\mathbf{C}_{ \pm 1}\left(\xi-\beta_{0}\right)\right)}}{\left|\left(\xi-\beta_{0}\right)\right|^{N}}
\end{aligned}
$$

Combining this together with (6.6) and (6.7) in (6.4)-(6.5), and recalling the definition of the norm $\mathcal{H}:=\mathcal{H}_{k, \beta_{0}}^{M,-M / 2,0,-N / 2}$ in Definition 6.1, we have obtained the expected bound.

## 7. Mellin and Laplace transforms

We will now apply the results of Section 4 to two examples which, besides their own interest, will be instrumental in our description of zeta functions associated to the length orthospectrum. All along this section, we will take $\chi_{\infty}$ to be a smooth function on $\mathbb{R}$ satisfying the following properties

$$
\begin{equation*}
\exists T_{0} \geq 1, \exists t_{0}>0, \quad \text { such that } \quad \operatorname{supp}\left(\chi_{\infty}\right) \subset\left[T_{0}, \infty\right) \quad \text { and } \quad \chi_{\infty}(t)=1 \quad \text { for } \quad t \geq T_{0}+t_{0} \tag{7.1}
\end{equation*}
$$

Typically, for our applications, we will in fact work with nondecreasing functions of this type. We now aim at refining the results of Section 6.1 when the function $\chi$ depends on some extra complex parameter, e.g.

$$
\chi_{s}^{L}(t):=\chi_{\infty}(t) e^{-s t} \quad \text { and } \quad \chi_{s}^{M}(t):=\chi_{\infty}(t) t^{-s}
$$

where $s \in \mathbb{C}$ has large enough real part. Equivalently, this amounts to study the Laplace and the Mellin transforms of $\chi_{\infty}(t) e^{-t \mathbf{V}_{\beta_{0}}}$ :

$$
\begin{equation*}
\widehat{\chi_{s}^{L}}\left(-i \mathbf{V}_{\beta_{0}}\right):=\int_{0}^{\infty} e^{-s t} \chi_{\infty}(t) e^{-t \mathbf{V}_{\beta_{0}}}|d t| \quad \text { and } \quad \widehat{\chi_{s}^{M}}\left(-i \mathbf{V}_{\beta_{0}}\right):=\int_{1}^{\infty} t^{-s} \chi_{\infty}(t) e^{-t \mathbf{V}_{\beta_{0}}}|d t| \tag{7.2}
\end{equation*}
$$

Note that, for $\operatorname{Re}(s)$ large enough, we are in the setting of application of Theorem 6.4. Hence, for such $s$, these operators are well defined on the anisotropic Sobolev spaces we have introduced in Section 6.1. Our goal is to show that these operators in fact extend to appropriate subsets of the complex plane when considered on these spaces. See Theorems 7.4 and 7.8 for precise statements. This section is divided in two main parts corresponding respectively to the analysis of $\widehat{\chi_{s}^{M}}\left(-i \mathbf{V}_{\beta_{0}}\right)$ (§7.1) and to the one of $\widehat{\chi_{s}^{L}}\left(-i \mathbf{V}_{\beta_{0}}\right)(\S 7.2)$.

Remark 7.1. Besides applications to Poincaré series, note that the Laplace transform appears naturally when studying the resolvent of $\mathbf{V}_{\beta_{0}}$. In fact, one has

$$
\left(s+\mathbf{V}_{\beta_{0}}\right)^{-1}:=\int_{0}^{+\infty} e^{-s t} e^{-t \mathbf{V}_{\beta_{0}}}|d t|=\int_{0}^{+\infty}\left(1-\chi_{\infty}(t)\right) e^{-s t} e^{-t \mathbf{V}_{\beta_{0}}}|d t|+\widehat{\chi_{s}^{L}}\left(-i \mathbf{V}_{\beta_{0}}\right)
$$

which defines a bounded operator from $\Omega^{k}\left(S \mathbb{T}^{d}\right)$ to $\mathcal{D}^{\prime k}\left(S \mathbb{T}^{d}\right)$ for $\operatorname{Re}(s)$ large enough. Note that the first integral on the right hand side is over a compact interval. Hence, this part extends holomorphically to the whole complex plane as an operator from $\Omega^{k}\left(S \mathbb{T}^{d}\right)$ to $\Omega^{k}\left(S \mathbb{T}^{d}\right)$. Equivalently, understanding the extension of the resolvent amounts to understand the continuation of $\widehat{\chi}_{s}^{L}(-i V)$. The same remarks hold for the integral

$$
\int_{1}^{+\infty} t^{-s} e^{-t \mathbf{V}_{\beta_{0}}}|d t|
$$

We refer to Section 7.3 below for precise statements. A refined analysis of the resolvent when $k=0$ and in the case of analytic regularity will be discussed in [DGBLR22].
7.1. Mellin transform. We begin with the case of the Mellin transform which is slightly easier to handle as it only requires nonstationary phase estimates.
7.1.1. A preliminary lemma. In that case, the analysis relies on the following elementary lemma:

Lemma 7.2. Let $T_{0} \geq 1$ and $\phi \in \mathcal{C}^{\infty}(\mathbb{R})$ be such that $\operatorname{supp}(\phi) \subset\left[T_{0},+\infty\right)$ and $\phi$ is constant near infinity. Then, the following hold:
(1) For any $\lambda \in \mathbb{R}$, the function

$$
f_{\phi, \lambda}(s):=\int_{\mathbb{R}} \phi(t) t^{-s} e^{i \lambda t}|d t|
$$

is a well-defined holomorphic function for $\operatorname{Re}(s)>1$ satisfying

$$
\left|f_{\phi, \lambda}(s)\right| \leq\|\phi\|_{L^{\infty}(\mathbb{R})} \frac{T_{0}^{-(\operatorname{Re}(s)-1)}}{\operatorname{Re}(s)-1}, \quad \text { for } s \in \mathbb{C}, \operatorname{Re}(s)>1
$$

(2) If $\phi$ is compactly supported, $f_{\phi, \lambda}$ is actually defined on the whole complex plane and defines an entire function on $\mathbb{C}$ such that

$$
\left|f_{\phi, \lambda}(s)\right| \leq C_{\phi} \frac{T_{0}^{-\operatorname{Re}(s)}}{\langle\operatorname{Re}(s)\rangle}, \quad \text { for } s \in \mathbb{C}
$$

(3) If $\lambda=0$ and $\phi=1$ in a neighborhood of $+\infty$, then $f_{\phi, 0}$ extends to $\mathbb{C}$ as a meromorphic function with a single simple pole at $s=1$ whose residue is equal to 1. Moreover,

$$
\begin{equation*}
f_{\phi, 0}(s)=\frac{f_{\phi^{\prime}, 0}(s-1)}{s-1}, \quad \text { for all } s \in \mathbb{C} \backslash\{1\} \tag{7.3}
\end{equation*}
$$

(4) If $\lambda \neq 0$ and $\phi=1$ in a neighborhood of $+\infty$, then $f_{\phi, \lambda}$ extends to $\mathbb{C}$ as an entire function. Moreover, this extended function satisfies, for all $m \in \mathbb{N}^{*}$ and all $s \in \mathbb{C}$,

$$
\begin{equation*}
f_{\phi, \lambda}(s)=\frac{1}{(i \lambda)^{m}} \sum_{j=0}^{m-1}\binom{m}{j}(-1)^{m-j} P_{j}(s) f_{\phi^{(m-j)}, \lambda}(s+j)+\frac{P_{m}(s)}{(i \lambda)^{m}} f_{\phi, \lambda}(s+m) \tag{7.4}
\end{equation*}
$$

where

$$
\begin{equation*}
P_{j}(s)=\prod_{k=0}^{j-1}(s+k), \quad \text { for } \quad j \in \mathbb{Z}_{+}^{*}, \quad \text { and } \quad P_{0}(s)=1 \tag{7.5}
\end{equation*}
$$

and, for all $m \in \mathbb{Z}_{+}$, there is a constant $C_{\phi, m}>0$ such that for all $\lambda \neq 0$,

$$
\begin{equation*}
\left|f_{\phi, \lambda}(s)\right| \leq C_{\phi, m} \frac{\langle | s| \rangle^{m}}{|\lambda|^{m}} \frac{T_{0}^{-\operatorname{Re}(s)+1}}{\operatorname{Re}(s)+m-1}, \quad \text { for } \operatorname{Re}(s)>-(m-1) \tag{7.6}
\end{equation*}
$$

Proof. Item 1 follows from the rough estimate $\left|\phi(t) t^{-s} e^{i \lambda t}\right| \leq\|\phi\|_{L^{\infty}} t^{-\operatorname{Re}(s)}$. In case supp $\phi \subset$ [ $T_{0}, T_{1}$ ], this yields in particular the estimate

$$
\begin{equation*}
\left|f_{\phi, \lambda}(s)\right| \leq\|\phi\|_{L^{\infty}} \int_{T_{0}}^{T_{1}} t^{-\operatorname{Re}(s)}|d t|=\frac{T_{0}^{-\operatorname{Re}(s)+1}-T_{1}^{-\operatorname{Re}(s)+1}}{\operatorname{Re}(s)-1} \tag{7.7}
\end{equation*}
$$

which, combined with holomorphy under the integral, provides a proof of Item 2. Item 3 consists in proving (7.3) for $\operatorname{Re}(s)>1$ by an integration by parts, and then observing that $f_{\phi^{\prime}, 0}$ is an entire function, whence the right hand-side of (7.3) has the sought properties. The result for all $s \in \mathbb{C}$ follows from analytic continuation and the residue is $f_{\phi^{\prime}, 0}(0)=\int_{\mathbb{R}} \phi^{\prime}(t) d t=\phi(+\infty)-\phi(0)=1$.

The proof of Item 4 (in case $\lambda \neq 0$ ) also consists in proving first (7.4) for $\operatorname{Re}(s)>1$ by integration by parts. After $m$ integrations by parts, one finds for $\operatorname{Re}(s)>1$

$$
f_{\phi, \lambda}(s)=\left(\frac{-1}{i \lambda}\right)^{m} \int_{\mathbb{R}} \partial_{t}^{m}\left(\phi(t) t^{-s}\right) e^{i \lambda t}|d t|
$$

The Leibniz formula together with the fact that $\left(t^{-s}\right)^{(j)}=(-1)^{j} P_{j}(s) t^{-s-j}$ then implies (7.4) for $\operatorname{Re}(s)>1$.

Next, we observe that the first term on the right hand-side of (7.4) is an entire function (as $\phi^{(m-j)}$ is compactly supported for $\left.j \leq m-1\right)$ and the second term is holomorphic on the half space $\operatorname{Re}(s)>-m+1$. Hence, for all $m \in \mathbb{N}^{*}$, the right hand-side of (7.4) is a holomorphic function on $\operatorname{Re}(s)>-m+1$, and all these functions coincide with $f_{\phi, \lambda}(s)$ on $\operatorname{Re}(s)>-m+1$. As a consequence of analytic continuation, for any $m \in \mathbb{N}, f_{\phi, \lambda}$ can be extended uniquely to a holomorphic function on $\operatorname{Re}(s)>-m+1$ (still denoted $f_{\phi, \lambda}$ ), which satisfies $(7.4)$ on $\operatorname{Re}(s)>-m+1$.

To prove the estimate, we use (7.4) and write

$$
|\lambda|^{m}\left|f_{\phi, \lambda}(s)\right| \leq \sum_{j=0}^{m-1}\binom{m}{j}\left|P_{j}(s)\right|\left|f_{\phi^{(m-j)}, \lambda}(s+j)\right|+\left|P_{m}(s)\right|\left|f_{\phi, \lambda}(s+m)\right|
$$

Taking $1 \leq T_{0}<T_{1}$ such that $\operatorname{supp}\left(\phi^{\prime}\right) \subset\left[T_{0}, T_{1}\right]$ and using item 1 together with (7.7), we deduce

$$
\begin{aligned}
&|\lambda|^{m}\left|f_{\phi, \lambda}(s)\right| \leq C_{m} \sum_{j=0}^{m-1}\langle | s| \rangle^{j}\left\|\phi^{(m-j)}\right\|_{L^{\infty}} \int_{T_{0}}^{T_{1}} t^{-\operatorname{Re}(s)-j}|d t| \\
&+C_{m}\langle | s| \rangle^{m}\|\phi\|_{L^{\infty}(\mathbb{R})} \frac{T_{0}^{-(\operatorname{Re}(s)+m-1)}}{\operatorname{Re}(s)+m-1}
\end{aligned}
$$

from which the statement follows.
7.1.2. Meromorphic continuation of $\widehat{\chi_{s}^{M}}\left(-i \mathbf{V}_{\beta_{0}}\right)$. Before discussing the meromorphic continuation, let us first clarify its holomorphic properties on $\operatorname{Re}(s)>d$ :

Proposition 7.3. Let $\chi_{\infty}$ be a function verifying assumption (7.1), let $\beta_{0} \in H^{1}\left(\mathbb{T}^{d}, \mathbb{R}\right)$ and let $\tilde{x}: \mathbb{S}^{d-1} \rightarrow \mathbb{R}^{d}$ be a smooth function.

Then, for all $(\varphi, \psi) \in \Omega^{k_{1}}\left(S \mathbb{T}^{d}\right) \times \Omega^{k_{2}}\left(S \mathbb{T}^{d}\right)$ with $k_{1}+k_{2}=2 d-1$, the function

$$
\begin{equation*}
s \mapsto \mathcal{M}_{(\varphi, \psi)}(s):=\int_{S \mathbb{T}^{d}} \varphi \wedge \widehat{\chi_{s}^{M}}\left(-i \mathbf{V}_{\beta_{0}}\right) \mathbf{T}_{-\tilde{x}}^{*}(\psi) \tag{7.8}
\end{equation*}
$$

is holomorphic on $\operatorname{Re}(s)>\min \left\{k_{1}, k_{2}\right\}+1$ and it satisfies

$$
\begin{equation*}
\left|\mathcal{M}_{(\varphi, \psi)}(s)\right| \leq C \frac{T_{0}^{-\left(\operatorname{Re}(s)-\min \left\{k_{1}, k_{2}\right\}-1\right)}}{\operatorname{Re}(s)-\min \left\{k_{1}, k_{2}\right\}-1}\|\varphi\|_{L^{2}\left(S \mathbb{T}^{d}\right)}\|\psi\|_{L^{2}\left(S \mathbb{T}^{d}\right)} \tag{7.9}
\end{equation*}
$$

Note that in this expression, $\min \left\{k_{1}, k_{2}\right\}+1$ can be always be replaced by $d$ (but it downgrades the statement).

Proof. Recalling (6.1), we use again Lemma 3.15 and the decomposition (3.18)-(3.19). Integrating (3.18)-(3.19) against $\chi_{\infty}(t) t^{-s}$ then yields

$$
\begin{equation*}
\mathcal{M}_{(\varphi, \psi)}(s)=\int_{S \mathbb{T}^{d}} \varphi \wedge \widehat{\chi_{s}^{M}}\left(-i \mathbf{V}_{\beta_{0}}\right) \mathbf{T}_{-\tilde{x}}^{*}(\psi)=\sum_{l=0}^{\min \left\{k_{1}, k_{2}\right\}} \mathcal{M}_{(\varphi, \psi)}^{(l)}(s) \tag{7.10}
\end{equation*}
$$

with

$$
\begin{equation*}
\mathcal{M}_{(\varphi, \psi)}^{(l)}(s)=\int_{1}^{\infty} \chi_{\infty}(t) t^{-s} \mathcal{C}_{\varphi, \mathbf{T}_{-\tilde{x}}^{*}(\psi)}^{l}\left(t, \beta_{0}\right)|d t| \tag{7.11}
\end{equation*}
$$

We then notice that the index $l$ is bounded by $l \leq \min \left\{k_{1}, k_{2}\right\} \leq d-1$, and that

$$
\begin{align*}
\left|\mathcal{C}_{\varphi, \mathbf{T}_{-\tilde{x}}^{*}(\psi)}^{l}\left(t, \beta_{0}\right)\right| & =\left|\frac{t^{l}}{l!} \sum_{\xi \in \mathbb{Z}^{d}} \int_{\mathbb{S}^{d-1}} e^{i t\left(\xi-\beta_{0}\right) \cdot \theta} e^{i \xi \cdot \tilde{x}(\theta)} B_{\tilde{x}, \xi}^{\left(k_{2}, l\right)}(\varphi, \psi)(\theta) \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta,|d \theta|)\right| \\
& \leq \frac{t^{l}}{l!} \sum_{\xi \in \mathbb{Z}^{d}} \int_{\mathbb{S}^{d-1}}\left|B_{\tilde{x}, \xi}^{\left(k_{2}, l\right)}(\varphi, \psi)(\theta)\right| \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta,|d \theta|) \\
& \leq C t^{l}\|\varphi\|_{L^{2}\left(S \mathbb{T}^{d}\right)}\|\psi\|_{L^{2}\left(S \mathbb{T}^{d}\right)} \tag{7.12}
\end{align*}
$$

according to (3.21). We deduce that

$$
\left|\chi_{\infty}(t) t^{-s} \mathcal{C}_{\varphi, \mathbf{T}_{-\tilde{x}}^{*}(\psi)}^{l}\left(t, \beta_{0}\right)\right| \leq C \chi_{\infty}(t) t^{l-s}\|\varphi\|_{L^{2}\left(S \mathbb{T}^{d}\right)}\|\psi\|_{L^{2}\left(S \mathbb{T}^{d}\right)}
$$

Recalling that $l \leq \min \left\{k_{1}, k_{2}\right\},(7.11)$ then implies holomorphy of $\mathcal{M}_{(\varphi, \psi)}^{(l)}$ in $\operatorname{Re}(s)>l+1$ (and in particular in $\left.\operatorname{Re}(s)>\min \left\{k_{1}, k_{2}\right\}+1\right)$. Item 1 in Lemma 7.2 finally yields

$$
\left|\mathcal{M}_{(\varphi, \psi)}^{(l)}(s)\right| \leq \frac{T_{0}^{-\left(\operatorname{Re}(s)-\min \left\{k_{1}, k_{2}\right\}-1\right)}}{\operatorname{Re}(s)-\min \left\{k_{1}, k_{2}\right\}-1} C\|\varphi\|_{L^{2}\left(S \mathbb{T}^{d}\right)}\|\psi\|_{L^{2}\left(S \mathbb{T}^{d}\right)}
$$

from which we infer (7.9) thanks to (7.10).
We now turn to our main statement on these regularized Mellin transforms.

Theorem 7.4. Let $\chi_{\infty}$ be a function verifying assumption (7.1), let $\beta_{0} \in H^{1}\left(\mathbb{T}^{d}, \mathbb{R}\right)$ and let $\tilde{x}: \mathbb{S}^{d-1} \rightarrow \mathbb{R}^{d}$ be a smooth function. Suppose in addition that $T_{0} \geq C\left(\chi_{0}\right)\|d \tilde{x}\|_{L^{\infty}\left(\mathbb{S}^{d-1}\right)}$ where $T_{0} \geq 1$ is the constant appearing in (7.1) and $C\left(\chi_{0}\right)>0$ the one from Corollary 4.3. Set

$$
E_{\beta_{0}}^{(l)}:=\int_{\mathbb{S}^{d-1}} e^{i \beta_{0} \cdot \tilde{x}(\theta)} B_{\tilde{x}, \beta_{0}}^{\left(k_{2}, l\right)}(\varphi, \psi)(\theta) \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta,|d \theta|), \quad \text { if } \beta_{0} \in H^{1}\left(\mathbb{T}^{d}, \mathbb{Z}\right)
$$

and $E_{\beta_{0}}^{(l)}=0$ otherwise. Then, using the conventions of Proposition 7.3, for any $N \in \mathbb{Z}_{+}^{*}$, there exists $C_{N}>0$ such that, for every couple $(\varphi, \psi)$ in $\mathcal{H}_{k_{1}, \beta_{0}}^{N,-N / 2,0,-N / 2} \times \mathcal{H}_{k_{2},-\beta_{0}}^{N,-N / 2,0,-N / 2}$ with $k_{1}+k_{2}=2 d-1$, the function

$$
\mathcal{M}_{(\varphi, \psi)}(s)-\sum_{l=0}^{\min \left\{k_{1}, k_{2}\right\}} \frac{1}{l!} \frac{E_{\beta_{0}}^{(l)}}{s-l-1},
$$

originally defined on $\operatorname{Re}(s)>\min \left\{k_{1}, k_{2}\right\}+1$ extends holomorphically to the half-plane $\operatorname{Re}(s)>$ $-N+\min \left\{k_{1}, k_{2}\right\}+1$ with

$$
\begin{aligned}
\left\lvert\, \mathcal{M}_{(\varphi, \psi)}(s)-\sum_{l=0}^{\min \left\{k_{1}, k_{2}\right\}} \frac{1}{l!}\right. & \left.\frac{E_{\beta_{0}}^{(l)}}{s-l-1} \right\rvert\, \\
& \leq \frac{C_{N}\langle | s| \rangle^{N}}{\operatorname{Re}(s)-\min \left\{k_{1}, k_{2}\right\}-1+N}\|\varphi\|_{\mathcal{H}_{k_{1}, \beta_{0}}^{N,-N / 2,0,-N / 2}}\|\psi\|_{\mathcal{H}_{k_{2},-\beta_{0}}^{N,-N / 2,0,-N / 2}}
\end{aligned}
$$

The proof is very close to that of Theorem 6.4 and we just need to pay attention to the dependence on the parameter $s \in \mathbb{C}$. Combined with Proposition 7.9, this proves Theorem 2.2 from the introduction by picking $\beta_{0}=0, k_{1}=2 d-1$ and $k_{2}=0$.

Proof. By bilinearity of the considered mappings with respect to $(\varphi, \psi)$ and by density, it is sufficient to prove these analytical estimates when $(\varphi, \psi) \in \Omega^{k_{1}}\left(S \mathbb{T}^{d}\right) \times \Omega^{k_{2}}\left(S \mathbb{T}^{d}\right)$. As in the proof of Proposition 7.3, we can decompose $\mathcal{C}_{\varphi, \mathbf{T}_{-\tilde{x}}(\psi)}^{l}\left(t, \beta_{0}\right)$ using (6.5). Then, we are left with describing the terms $\mathcal{M}_{(\varphi, \psi)}^{(l)}(s)$ in (7.11) that can be decomposed accordingly as

$$
\begin{equation*}
\mathcal{M}_{(\varphi, \psi)}^{(l)}(s)=\mathcal{M}_{(\varphi, \psi)}^{(l, E)}(s)+\mathcal{M}_{(\varphi, \psi)}^{(l,-1)}(s)+\mathcal{M}_{(\varphi, \psi)}^{(l, 0)}(s)+\mathcal{M}_{(\varphi, \psi)}^{(l, 1)}(s), \tag{7.13}
\end{equation*}
$$

with

$$
\begin{aligned}
& \mathcal{M}_{(\varphi, \psi)}^{(l, E)}(s)=\int_{\mathbb{R}} \chi_{\infty}(t) t^{-s} \frac{t^{l}}{l!} E_{\beta_{0}}^{(l)}|d t|, \quad \text { and } \\
& \mathcal{M}_{(\varphi, \psi)}^{(l, j)}(s)=\int_{\mathbb{R}} \chi_{\infty}(t) t^{-s} \frac{t^{l}}{l!} \mathrm{e}^{(l, j)}(t)|d t|, \quad \text { for } j \in\{-1,0,1\} .
\end{aligned}
$$

We now study each of these terms separately.
Firstly, as $\operatorname{supp}\left(\chi_{\infty}\right) \subset[1, \infty)$, we have

$$
\begin{equation*}
\mathcal{M}_{(\varphi, \psi)}^{(l, E)}(s)=E_{\beta_{0}}^{(l)} \frac{1}{l!} \int_{1}^{\infty} \chi_{\infty}(t) t^{-s+l}|d t|=\frac{1}{l!} \frac{E_{\beta_{0}}^{(l)}}{s-l-1}+\frac{E_{\beta_{0}}^{(l)}}{l!} \int_{1}^{\infty}\left(1-\chi_{\infty}(t)\right) t^{-s+l}|d t| \tag{7.14}
\end{equation*}
$$

where the second term on the right-hand side of the equation is an entire function. Hence, this term has the claimed properties.

Secondly, we consider the term with $\mathcal{M}_{(\varphi, \psi)}^{(l, 0)}(s)$ and proceed as in the proof of Theorem 6.4. According to Corollary 4.3, we have, for $t>C\left(\chi_{0}\right)\|d \tilde{x}\|_{L^{\infty}\left(\mathbb{S}^{d-1}\right)}$

$$
\begin{aligned}
\mathcal{C}^{(l, 0)}(t) & =\sum_{\xi \in \mathbb{Z}^{d} \backslash\left\{\beta_{0}\right\}} \int_{\mathbb{S}^{d-1}} \chi_{0}\left(\theta \cdot \frac{\xi-\beta_{0}}{\left|\xi-\beta_{0}\right|}\right) e^{i t\left(\xi-\beta_{0}\right) \cdot \theta} e^{i \xi \cdot \tilde{x}(\theta)} B_{\tilde{x}, \xi}^{\left(k_{2}, l\right)}(\varphi, \psi)(\theta) \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta,|d \theta|) \\
& =\sum_{\xi \in \mathbb{Z}^{d} \backslash\left\{\beta_{0}\right\}}\left(i\left|\xi-\beta_{0}\right| t\right)^{-N} \int_{\mathbb{S}^{d-1}} F(t, \xi, \theta) \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta,|d \theta|)
\end{aligned}
$$

with

$$
F(t, \xi, \theta)=e^{i\left(\xi-\beta_{0}\right) \cdot(t \theta+\tilde{x}(\theta))} \mathcal{L}_{N, t}^{\frac{\xi-\beta_{0}}{\xi-\beta_{0}}}\left(\chi_{0}\left(\theta \cdot \frac{\xi-\beta_{0}}{\left|\xi-\beta_{0}\right|}\right) e^{i \beta_{0} \cdot \tilde{x}(\theta)} B_{\tilde{x}, \xi}^{\left(k_{2}, l\right)}(\varphi, \psi)(\theta)\right)
$$

and, for all $\omega \in \mathbb{S}^{d-1}$, for all $\theta \in \mathbf{C}_{0}(\omega)$, and all $t>C\left(\chi_{0}\right)\|d \tilde{x}\|_{L^{\infty}\left(\mathbb{S}^{d-1}\right)}$,

$$
\left|\left(\mathcal{L}_{N, t}^{\omega} \psi\right)(\theta)\right| \leq C_{N}\left(\frac{\|\tilde{x}\|_{W^{N+1, \infty}\left(\mathbf{C}_{0}(\omega)\right)}}{t}\right)\left(\sum_{|\alpha| \leq N}\left|\nabla_{\theta}^{\alpha} \psi(\theta)\right|\right)
$$

Coming back to $\mathcal{M}_{(\varphi, \psi)}^{(l, 0)}(s)$, we have

$$
\begin{aligned}
\mathcal{M}_{(\varphi, \psi)}^{(l, 0)}(s) & =\int_{\mathbb{R}} \chi_{\infty}(t) t^{-s} \frac{t^{l}}{l!} \mathcal{C}^{(l, 0)}(t)|d t| \\
& =\int_{\mathbb{R}^{2}} \sum_{\xi \in \mathbb{Z}^{d} \backslash\left\{\beta_{0}\right\}} \int_{\mathbb{S}^{d-1}} \chi_{\infty}(t) t^{-s} \frac{t^{l}}{l!}\left(i\left|\xi-\beta_{0}\right| t\right)^{-N} F(t, \xi, \theta) \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta,|d \theta|)|d t|
\end{aligned}
$$

where, as $\operatorname{supp}\left(\chi_{\infty}\right) \subset\left[T_{0},+\infty\right)$ with $T_{0} \geq \max \left\{1, C\left(\chi_{0}\right)\|d \tilde{x}\|_{L^{\infty}\left(\mathbb{S}^{d-1}\right)}\right\}$, one has

$$
\begin{aligned}
& \left|\chi_{\infty}(t) t^{-s} \frac{t^{l}}{l!}\left(i\left|\xi-\beta_{0}\right| t\right)^{-N} F(t, \xi, \theta)\right| \\
& \leq \chi_{\infty}(t) t^{-\operatorname{Re}(s)+l-N}\left|\xi-\beta_{0}\right|^{-N} C_{N}\left(\frac{\left.\|\tilde{x}\|_{W^{N+1, \infty}\left(\mathbf{C}_{0}(\omega)\right)}^{t}\right)\left(\sum_{|\alpha| \leq N}\left|\nabla_{\theta}^{\alpha} B_{\tilde{x}, \xi}^{\left(k_{2}, l\right)}(\varphi, \psi)(\theta)\right|\right)}{} .\left\{\begin{array}{l}
\end{array}\right)\right.
\end{aligned}
$$

uniformly for $t \geq \max \left\{1, C\left(\chi_{0}\right)\|d \tilde{x}\|_{L^{\infty}\left(\mathbb{S}^{d-1}\right)}\right\}, \xi \in \mathbb{R}^{d} \backslash\left\{\beta_{0}\right\}$ and $\theta \in \mathbf{C}_{0}\left(\xi-\beta_{0}\right)$. We deduce from that bound and from (3.21) the holomorphy of the term $\mathcal{N}_{(\varphi, \psi)}^{(l, 0)}(s)$ in $\operatorname{Re}(s)>-N+l+1$ together with the estimate

$$
\begin{align*}
& \left|\mathcal{M}_{(\varphi, \psi)}^{(l, 0)}(s)\right| \\
& \leq C_{N}\left\|\chi_{\infty}(t) t^{l-\operatorname{Re}(s)-N}\right\|_{L^{1}\left(\mathbb{R}_{+}\right)} \sum_{\xi \in \mathbb{Z}^{d} \backslash\left\{\beta_{0}\right\}} \frac{1}{\left|\xi-\beta_{0}\right|^{N}}\left\|B_{\tilde{x}, \xi}^{\left(k_{2}, l\right)}(\varphi, \psi)\right\|_{W^{1, N}\left(\mathbf{C}_{0}\left(\xi-\beta_{0}\right)\right)} \\
& \leq C_{N}\left\|\chi_{\infty}(t) t^{l-\operatorname{Re}(s)-N}\right\|_{L^{1}\left(\mathbb{R}_{+}\right)} \sum_{\xi \in \mathbb{Z}^{d} \backslash\left\{\beta_{0}\right\}} \frac{\left\|\pi_{\xi}^{\left(k_{1}\right)}(\varphi)\right\|_{H^{N}\left(\mathbf{C}_{0}\left(\xi-\beta_{0}\right)\right)}\left\|\pi_{-\xi}^{\left(k_{2}\right)}(\psi)\right\|_{H^{N}\left(\mathbf{C}_{0}\left(\xi-\beta_{0}\right)\right)}}{\left|\xi-\beta_{0}\right|^{N}} \\
& \leq C_{N} \frac{T_{0}^{-(\operatorname{Re}(s)+N-l-1)}}{\operatorname{Re}(s)+N-l-1} \sum_{\xi \in \mathbb{Z}^{d} \backslash\left\{\beta_{0}\right\}} \frac{\left\|\pi_{\xi}^{\left(k_{1}\right)}(\varphi)\right\|_{H^{N}\left(\mathbf{C}_{0}\left(\xi-\beta_{0}\right)\right)}\left\|\pi_{-\xi}^{\left(k_{2}\right)}(\psi)\right\|_{H^{N}\left(\mathbf{C}_{0}\left(\xi-\beta_{0}\right)\right)}}{\left|\xi-\beta_{0}\right|^{N}} . \tag{7.15}
\end{align*}
$$

Thirdly, we consider the two terms $\mathcal{M}_{(\varphi, \psi)}^{(l, \pm 1)}(s)$ and proceed as in the proof of Theorem 6.4 (i.e. take advantage of the integration over time). We write

$$
\begin{aligned}
\mathcal{M}_{(\varphi, \psi)}^{(l, \pm 1)}(s)= & \sum_{\xi \in \mathbb{Z}^{d} \backslash\left\{\beta_{0}\right\}} \int_{\mathbb{S}^{d-1}}\left(\int_{\mathbb{R}} \chi_{\infty}(t) t^{-s} \frac{t^{l}}{l!} e^{i t\left(\xi-\beta_{0}\right) \cdot \theta}|d t|\right) \\
& \times \chi_{ \pm 1}\left(\theta \cdot \frac{\xi-\beta_{0}}{\left|\xi-\beta_{0}\right|}\right) e^{i \xi \cdot \tilde{x}(\theta)} B_{\tilde{x}, \xi}^{\left(k_{2}, l\right)}(\varphi, \psi)(\theta) \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta,|d \theta|)
\end{aligned}
$$

We then remark from the properties of $\chi_{ \pm 1}$ in Definition 4.1 that $\sigma \in \operatorname{supp}\left(\chi_{ \pm 1}\right) \Longrightarrow|\sigma| \geq \epsilon_{0}>0$ from which we infer that $\left|\theta \cdot\left(\xi-\beta_{0}\right)\right| \geq \epsilon_{0}\left|\xi-\beta_{0}\right|$ for $(\theta, \xi)$ in the support of $\chi_{ \pm 1}\left(\theta \cdot \frac{\xi-\beta_{0}}{\left|\xi-\beta_{0}\right|}\right)$. Item 4 in Lemma 7.2 then implies that the integral

$$
\int_{\mathbb{R}} \chi_{\infty}(t) t^{-s} \frac{t^{l}}{l!} e^{i t\left(\xi-\beta_{0}\right) \cdot \theta}|d t|=\frac{1}{l!} f_{\chi_{\infty},\left(\xi-\beta_{0}\right) \cdot \theta}(s-l)
$$

extends as an entire function in $s$ for any given $(\theta, \xi)$ in the support of $\chi_{ \pm 1}\left(\theta \cdot \frac{\xi-\beta_{0}}{\left|\xi-\beta_{0}\right|}\right)$. According to (7.6), it satisfies in addition, for any $m \in \mathbb{Z}_{+}^{*}$,

$$
\left|f_{\chi_{\infty},\left(\xi-\beta_{0}\right) \cdot \theta}(s-l)\right| \leq C_{\chi_{\infty}, m} \frac{\langle | s| \rangle^{m}}{\epsilon_{0}^{m}\left|\xi-\beta_{0}\right|^{m}} \frac{T_{0}^{-\operatorname{Re}(s)+l+1}}{\operatorname{Re}(s)-l+m-1}, \quad \text { for } \operatorname{Re}(s)>-m+l+1
$$

Coming back to $\mathcal{M}_{(\varphi, \psi)}^{(l, \pm 1)}(s)$, we find that it is holomorphic in $\operatorname{Re}(s)>-m+l+1$ together with the estimate

$$
\begin{aligned}
\left|\mathcal{M}_{(\varphi, \psi)}^{(l, \pm 1)}(s)\right| & \lesssim m \frac{\langle | s\left\rangle^{m} T_{0}^{-\operatorname{Re}(s)+l+1}\right.}{\operatorname{Re}(s)-l+m-1} \sum_{\xi \in \mathbb{Z}^{d} \backslash\left\{\beta_{0}\right\}} \frac{1}{\left|\xi-\beta_{0}\right|^{m}}\left\|B_{\tilde{x}, \xi}^{\left(k_{2}, l\right)}(\varphi, \psi)(\theta)\right\|_{L^{1}\left(\mathbf{C}_{ \pm 1}\left(\xi-\beta_{0}\right)\right)} \\
& \lesssim m \frac{\langle | s\left\rangle^{m} T_{0}^{-\operatorname{Re}(s)+l+1}\right.}{\operatorname{Re}(s)-l+m-1} \sum_{\xi \in \mathbb{Z}^{d} \backslash\left\{\beta_{0}\right\}} \frac{\left\|\pi_{\xi}^{\left(k_{1}\right)}(\varphi)\right\|_{L^{2}\left(\mathbf{C}_{ \pm 1}\left(\xi-\beta_{0}\right)\right)}\| \|_{-\xi}^{\left(k_{2}\right)}(\psi) \|_{L^{2}\left(\mathbf{C}_{ \pm 1}\left(\xi-\beta_{0}\right)\right)}}{\left|\xi-\beta_{0}\right|^{m}} .
\end{aligned}
$$

Finally, combining this together with (7.15) (and the statement preceding this estimate), and choosing $m=N$, we have obtained in the decomposition (7.13) that the function

$$
\mathcal{M}_{(\varphi, \psi)}^{(l)}(s)-\mathcal{M}_{(\varphi, \psi)}^{(l, E)}(s)=\mathcal{M}_{(\varphi, \psi)}^{(l,-1)}(s)+\mathcal{M}_{(\varphi, \psi)}^{(l, 0)}(s)+\mathcal{M}_{(\varphi, \psi)}^{(l, 1)}(s)
$$

is a holomorphic function in $\operatorname{Re}(s)>-N+l+1$. As long as $T_{0} \geq \max \left\{1, C\left(\chi_{0}\right)\|d \tilde{x}\|_{L^{\infty}\left(\mathbb{S}^{d-1}\right)}\right\}$ and recalling the definition of the norm $\mathcal{H}_{k, \pm \beta_{0}}^{N,-N / 2,0,-N / 2}$ in Definition 6.1, we end up with the estimate

$$
\left|\mathcal{M}_{(\varphi, \psi)}^{(l)}(s)-\mathcal{M}_{(\varphi, \psi)}^{(l, E)}(s)\right| \leq C_{N} \frac{\langle | s| \rangle^{N} T_{0}^{-\operatorname{Re}(s)+l+1}}{\operatorname{Re}(s)-l+N-1}\|\varphi\|_{\mathcal{H}_{k_{1}, \beta_{0}}^{N,-N / 2,0,-N / 2}}\|\psi\|_{\mathcal{H}_{k_{2},-\beta_{0}}^{N,-N / 2,0,-N / 2}}
$$

Coming back to the decomposition (7.10), recalling that $l \leq \min \left\{k_{1}, k_{2}\right\}$, and implementing the value of $\mathcal{M}_{(\varphi, \psi)}^{(l, E)}(s)$ in (7.14) concludes the proof of the theorem.
7.2. Laplace transform. Here and in the whole section, we write

$$
\overline{\mathbb{C}}_{+}:=\{z \in \mathbb{C}, \operatorname{Re}(z) \geq 0\}
$$

and we say that a function is in $\mathcal{C}^{k}\left(\overline{\mathbb{C}}_{+}\right)$if it is the restriction in $\overline{\mathbb{C}}_{+}$of a function in $\mathcal{C}^{k}(\mathbb{C})$. In this part, we are going to use the notion of distributions obtained as boundary values of holomorphic functions [Hör03, Th. 3.1.11] in the most elementary way. We state a proposition which characterizes those distributions which arise as boundary values from the upper or lower half-plane of holomorphic functions:

Proposition 7.5. Let $T \in \mathcal{S}^{\prime}(\mathbb{R})$ be a tempered distribution supported in $\mathbb{R}_{ \pm}^{*}$. Then, there exists a holomorphic function $F(z)$ on the half plane $\mathbb{H}_{\mp}=\{(x \mp i y): y>0\}$ such that

$$
\widehat{T}=\lim _{\varepsilon \rightarrow 0^{+}} F(. \mp i \varepsilon) \text { in } \mathcal{S}^{\prime}(\mathbb{R})
$$

and we shall write $\widehat{T}=F(. \mp i 0)$. Furthermore, $F(x \mp i y)$ is the Fourier transform of $T(x) e^{\mp y x}$. Conversely, if we are given a holomorphic function $F$ on $\mathbb{H}_{\mp}$, such that there exists $C, N$ and some polynomial $P$ such that $\forall y>0$ :

$$
|F(x \mp i y)| \leqslant C|P(x \mp i y)|\left(1+y^{-N}\right)
$$

then the following limit

$$
\widehat{T}=\lim _{y \rightarrow 0^{+}} F(. \mp i y)
$$

exists in $\mathcal{S}^{\prime}(\mathbb{R})$ and it is the Fourier transform of a distribution $T$ carried on $\mathbb{R}_{ \pm}^{*}$.

This is a particular case of a more general result valid on $\mathbb{R}^{d}$ and described in [RS75, Thm IX. 16 p. 23]. Given $\lambda<0$, we can now give the fundamental example of such boundary values together with their Fourier transform. Namely, if we consider

$$
T(x):=\frac{2 \pi e^{\mp i \lambda \frac{\pi}{2}}}{\Gamma(-\lambda)} \mathbb{1}_{\mathbb{R}_{+}^{*}}( \pm x)|x|^{-1-\lambda},
$$

where $\mathbb{1}_{\mathbb{R}_{+}^{*}}$ is the indicator of the positive reals, then the Fourier transform $\widehat{T}(\xi)$ is given by $(\xi \mp i 0)^{\lambda}$ [GS, p. 360]. The function $\mathbb{1}_{\mathbb{R}_{+}^{*}}( \pm x)|x|^{-1-\lambda}$ is in $L_{\text {loc }}^{1}(\mathbb{R})$ and bounded polynomially. Hence it defines a tempered distribution for all $\lambda<0$. In the litterature, one can also find the notation $\xi_{\mp}^{-1-\lambda}=\left(1_{[0,+\infty)}(\mp \xi)|\xi|^{-1-\lambda}\right)$ [GS, $\S 3.2$, p. 48$]$. We shall use the above proposition to describe the singularities of our Poincaré series.

The useful analogue to Lemma 7.2 is the following elementary result:
Lemma 7.6. Let $T_{1}>T_{0}>0$ and $\phi \in \mathcal{C}^{\infty}(\mathbb{R})$ be such that $\operatorname{supp}(\phi) \subset\left[T_{0},+\infty\right)$ and $\phi=1$ on $\left[T_{1}+\infty\right)$. Then, the following hold:
(1) For any $\alpha \in \mathbb{R}$, the function

$$
F_{\phi, \alpha}(z):=\int_{\mathbb{R}_{+}} \phi(t) t^{-\alpha} e^{-z t}|d t|, \quad \text { for } \operatorname{Re}(z)>0
$$

defines a holomorphic function in $\operatorname{Re}(z)>0$ which satisfies

$$
\begin{aligned}
& \left|F_{\phi, \alpha}(z)\right| \leq C_{\phi, \alpha}, \quad \text { for } z \in \overline{\mathbb{C}}_{+} \text {and extends continuously to this set, } \quad \text { if } \alpha>1 \\
& \left|F_{\phi, \alpha}(z)\right| \leq \frac{C_{\phi, \alpha}}{\operatorname{Re}(z)^{1-\alpha}}, \quad \text { for } z \in \mathbb{C}, \operatorname{Re}(z)>0, \quad \text { if } \alpha<1, \\
& \left|F_{\phi, 1}(z)\right| \leq C_{\phi, 1}(|\ln \operatorname{Re}(z)|+1), \quad \text { for } z \in \mathbb{C}, \operatorname{Re}(z)>0, \quad \text { if } \alpha=1
\end{aligned}
$$

(2) $\partial_{z}^{k} F_{\phi, \alpha}(z)=(-1)^{k} F_{\phi, \alpha-k}(z)$ for all $k \in \mathbb{Z}_{+}, z \in \mathbb{C}, \operatorname{Re}(z)>0$, and $F_{\phi, \alpha} \in \mathcal{C}^{k}\left(\overline{\mathbb{C}}_{+}\right)$for all $k \in \mathbb{Z}_{+}$such that $\alpha-k>1$.
(3) If $\alpha<1$, the function $F_{\phi, \alpha}$ can be extended to $\mathbb{C} \backslash \mathbb{R}_{-}$(and even to $\mathbb{C} \backslash\{0\}$ if $\alpha \in \mathbb{Z}_{-}$) as a holomorphic function satisfying $F_{\phi, \alpha}(z)=\frac{\Gamma(1-\alpha)}{z^{1-\alpha}}+H_{\alpha}(z)$ where $H_{\alpha}$ is an entire function such that, for all $k \geq 0$, $\left|\partial_{z}^{k} H_{\alpha}(z)\right| \leq C_{\phi, \alpha, k}\left(e^{-T_{1} \operatorname{Re}(z)}+1\right)$ on $\mathbb{C}$, for some $C_{\phi, \alpha, k}>0$. Moreover, we have the following identity which holds in $\mathcal{S}^{\prime}(\mathbb{R})$ :

$$
\begin{equation*}
\lim _{x \rightarrow 0^{+}} F_{\phi, \alpha}(x+i y)=\frac{\Gamma(1-\alpha) e^{i \frac{\pi}{2}(\alpha-1)}}{(y-i 0)^{1-\alpha}}+H_{\alpha}(i y) \tag{7.16}
\end{equation*}
$$

(4) If $\alpha=1$, the function $F_{\phi, 1}$ can be extended to the cut plane $\mathbb{C} \backslash \mathbb{R}^{-}$as a holomorphic function satisfying $F_{\phi, 1}(z)=-\log (z)+H_{1}(z)$ where $\log$ is the principal determination of the logarithm and $H_{1}$ is an entire function such that, for all $k \geq 0$, $\left|\partial_{z}^{k} H_{1}(z)\right| \leq$ $C_{\phi, k}\left(e^{-T_{1} \operatorname{Re}(z)}+1\right)$ on $\mathbb{C}$, for some $C_{\phi, \alpha, k}>0$. Moreover, we have the following identity which holds in $\mathcal{S}^{\prime}(\mathbb{R})$ :

$$
\begin{equation*}
\lim _{x \rightarrow 0^{+}} F_{\phi, \alpha}(x+i y)=-\log (y-i 0)-\frac{\pi}{2}+H_{1}(i y) \tag{7.17}
\end{equation*}
$$

(5) For all $\beta \in \mathbb{R}, m \in \mathbb{Z}_{+}^{*}$,

$$
\begin{equation*}
F_{\phi, \beta}(z)=\frac{1}{z^{m}} E_{\beta, m}(z)+(-1)^{m} \frac{P_{m}(\beta)}{z^{m}} F_{\phi, \beta+m}(z) \tag{7.18}
\end{equation*}
$$

where $P_{j}(\beta)$ is defined in (7.5) and $E_{\beta, m}(z)$ is an entire function such that

$$
\begin{equation*}
\left|E_{\beta, m}(z)\right| \leq C_{\phi, \beta, m}\left(e^{-T_{1} \operatorname{Re}(z)}+1\right), \quad z \in \mathbb{C} \tag{7.19}
\end{equation*}
$$

(6) if $\alpha>1, \alpha \notin \mathbb{Z}_{+}$, the function $F_{\phi, \alpha}$ can be extended to the cut plane $\mathbb{C} \backslash \mathbb{R}_{-}$as a holomorphic function satisfying $F_{\phi, \alpha}(z)=\frac{\pi}{\sin (\pi \alpha) \Gamma(\alpha)} z^{\alpha-1}+H_{\alpha}(z)$ where $H_{\alpha}$ is an entire function such that, for all $k \geq 0,\left|\partial_{z}^{k} H_{\alpha}(z)\right| \leq C_{\phi, \alpha, k}\langle | z| \rangle^{\lfloor\alpha\rfloor}\left(e^{-T_{1} \operatorname{Re}(z)}+1\right)$ on $\mathbb{C}$, for some $C_{\phi, \alpha, k}>0$. Moreover, extended by the value zero at zero, we have $F_{\phi, \alpha} \in \mathcal{C}^{\lfloor\alpha\rfloor-1}\left(\overline{\mathbb{C}}_{+}\right)$.
(7) if $\alpha=n \in \mathbb{Z}_{+}^{*}, n \geqslant 2$, the function $F_{\phi, n}$ can be extended to the cut plane $\mathbb{C} \backslash \mathbb{R}_{-}$as a holomorphic function satisfying $F_{\phi, n}(z)=\frac{(-1)^{n}}{n!} z^{n-1} \log (z)+H_{n}(z)$ where $H_{n}$ is an entire function such that, for all $k \geq 0,\left|\partial_{z}^{k} H_{n}(z)\right| \leq C_{\phi, n, k}\langle | z| \rangle^{n-1}\left(e^{-T_{1} \operatorname{Re}(z)}+1\right)$ on $\mathbb{C}$, for some $C_{\phi, n, k} \geq 0$. Moreover, extended by the value zero at zero and for $n \geq 2$, we have $F_{\phi, n} \in \mathcal{C}^{n-2}\left(\overline{\mathbb{C}}_{+}\right)$.
Proof. Let us first prove Item 1. The statement for $\alpha>1$ follows from a crude bound and continuity under the integral. For $\alpha<1$, we have

$$
\begin{aligned}
\left|F_{\phi, \alpha}(z)\right| & \leq\|\phi\|_{\infty} \int_{T_{0}}^{\infty} t^{-\alpha} e^{-\operatorname{Re}(z) t}|d t|=\|\phi\|_{\infty} \operatorname{Re}(z)^{1-\alpha} \int_{T_{0} \operatorname{Re}(z)}^{\infty} \sigma^{-\alpha} e^{-\sigma}|d \sigma| \\
& \leq\|\phi\|_{\infty} \operatorname{Re}(z)^{1-\alpha} \int_{0}^{\infty} \sigma^{-\alpha} e^{-\sigma}|d \sigma|
\end{aligned}
$$

which is the sought estimate. In the case $\alpha=1$, we have

$$
\begin{aligned}
\left|F_{\phi, 1}(z)\right| & \leq\|\phi\|_{\infty} \int_{T_{0}}^{\infty} t^{-1} e^{-\operatorname{Re}(z) t}|d t|=\|\phi\|_{\infty} \int_{T_{0} \operatorname{Re}(z)}^{\infty} \sigma^{-1} e^{-\sigma}|d \sigma| \\
& \leq\|\phi\|_{\infty} \int_{T_{0} \operatorname{Re}(z)}^{1} \sigma^{-1}|d \sigma|+\|\phi\|_{\infty} \int_{1}^{\infty} e^{-\sigma}|d \sigma|=-\|\phi\|_{\infty} \ln \left(T_{0} \operatorname{Re}(z)\right)+\|\phi\|_{\infty} e^{-1}
\end{aligned}
$$

Item 2 is a straightforward consequence of Item 1 and differentiation under the integral.
For Item 3, we first notice that for $\gamma:=-\alpha>-1$ and $z \in \mathbb{R}_{+}^{*}$, we have

$$
\begin{aligned}
& F_{\phi,-\gamma}=\int_{0}^{\infty} t^{\gamma} e^{-z t}|d t|+\int_{0}^{\infty}(\phi(t)-1) t^{\gamma} e^{-z t}|d t| \\
&=\frac{1}{z^{\gamma+1}} \int_{0}^{\infty} \sigma^{\gamma} e^{-\sigma}|d \sigma|+\int_{0}^{\infty}(\phi(t)-1) t^{\gamma} e^{-z t}|d t|
\end{aligned}
$$

The last integral is an entire function satisfying the sought bound and the result follows from analytic continuation, where the cut plane $\mathbb{C} \backslash \mathbb{R}_{-}$is chosen arbitrarily. These bounds give exactly the necessary moderate growth assumption so that the distributional limit $F_{\phi, \alpha}(i y+0)$ exists by Proposition 7.5.

To prove Item 4, we differentiate $F_{\phi, 1}$ in $\operatorname{Re}(z)>0$ to obtain

$$
\begin{aligned}
\partial_{z} F_{\phi, 1}(z)=-\int_{0}^{\infty} \phi(t) e^{-z t} d t=-\int_{0}^{\infty} e^{-z t} d t+\int_{0}^{\infty}(1-\phi(t)) e^{-z t} d t & \\
& =-\frac{1}{z}+\int_{0}^{\infty}(1-\phi(t)) e^{-z t} d t
\end{aligned}
$$

Integrating this equation on the segment $[1, z]$ for $\operatorname{Re}(z)>0$ implies

$$
F_{\phi, 1}(z)-F_{\phi, 1}(1)=-\log (z)+\int_{0}^{\infty}(1-\phi(t)) \int_{1}^{z} e^{-s t} d s d t
$$

whence, for $\operatorname{Re}(z)>0$,

$$
F_{\phi, 1}(z)=-\log (z)+\int_{0}^{\infty} \phi(t) t^{-1} e^{-t} d t+\int_{0}^{\infty}(1-\phi(t)) e^{-\frac{1+z}{2} t} \frac{\sinh \left(\frac{z-1}{2} t\right)}{t} d t
$$

The right hand side continues holomorphically to $\mathbb{C} \backslash \mathbb{R}_{-}$, the last integral being on the compact set $\left[0, T_{1}\right]$. Using now that $\sinh (a+i b)=\sinh a \cos b+i \cosh a \sin b$, we have $\left|\frac{\sinh (t(a+i b))}{t}\right| \leq$ $\left|\frac{\sinh (t a)}{t}\right|+\cosh (t a) \leq 2 \cosh (t a) \leq e^{|t a|}$, whence

$$
\begin{aligned}
\left\lvert\, \int_{0}^{\infty}(1-\phi(t)) e^{-\frac{1+z}{2}}\right. & \left.t \frac{\sinh \left(\frac{z-1}{2} t\right)}{t} d t \right\rvert\, \\
& \leq C_{\phi} \int_{0}^{T_{1}} e^{-\frac{1+\operatorname{Re}(z)}{2} t} e^{\frac{|\operatorname{Re}(z)-1|}{2} t} d t=\left.C_{\phi}\left(\frac{e^{T_{1} A}-1}{A}\right)\right|_{A=\frac{|\operatorname{Re}(z)-1|-(\operatorname{Re}(z)+1)}{2}}
\end{aligned}
$$

which implies the sought estimate. The distributional limit again follows from Proposition 7.5 and the bound from item 1.

Item 5 is proved as in Lemma 7.2 and consists in integrating by parts $m$ times to obtain, for $\operatorname{Re}(z)>0$,

$$
F_{\phi, \alpha}(z)=\int_{0}^{\infty}\left(\frac{1}{z} \frac{d}{d t}\right)^{m}\left(\phi(t) t^{-\alpha}\right) e^{-z t}|d t|
$$

and then expanding with the Leibniz formula. We obtain the formula (7.18) with

$$
E_{\alpha, m}(z)=\sum_{j=0}^{m-1}(-1)^{j}\binom{m}{j} P_{j}(\alpha) F_{\phi^{(m-j)}, \alpha+j}(z)
$$

and the estimate (7.19) follows from the fact that $\left|F_{\phi^{(m-j)}, \alpha}(z)\right| \leq C_{\phi, \alpha}\left(e^{-T_{1} \operatorname{Re}(z)}+1\right)$ for $z \in \mathbb{C}$ if $m-j>0$ since $\phi^{(m-j)}$ is compactly supported in $\mathbb{R}_{+}^{*}$.

Item 6 is a consequence of Items 3 and 5 for $m=\lfloor\alpha\rfloor \in \mathbb{Z}_{+}$and $\beta=\alpha-\lfloor\alpha\rfloor \in(0,1)$. From (7.18), we obtain

$$
\begin{aligned}
F_{\phi, \alpha}(z) & =F_{\phi, \beta+m}(z)=(-1)^{m} \frac{z^{m}}{P_{m}(\beta)} F_{\phi, \beta}(z)-\frac{(-1)^{m}}{P_{m}(\beta)} E_{\beta, m}(z) \\
& =(-1)^{m} \frac{z^{m}}{P_{m}(\beta)}\left(\frac{\Gamma(1-\beta)}{z^{1-\beta}}+H_{\beta}(z)\right)-\frac{(-1)^{m}}{P_{m}(\beta)} E_{\beta, m}(z)
\end{aligned}
$$

where we have used Item 3 in the second line. We further notice from $\Gamma(z+1)=z \Gamma(z)$ that $P_{m}(\beta)=\frac{\Gamma(\beta+m)}{\Gamma(\beta)}($ see $(7.5))$ whence

$$
F_{\phi, \alpha}(z)=(-1)^{m} z^{m+\beta-1} \frac{\Gamma(1-\beta) \Gamma(\beta)}{\Gamma(\beta+m)}+\frac{(-1)^{m} z^{m}}{P_{m}(\beta)} H_{\beta}(z)-\frac{(-1)^{m}}{P_{m}(\beta)} E_{\beta, m}(z)
$$

and hence the sought formula recalling $\Gamma(1-\beta) \Gamma(\beta)=\frac{\pi}{\sin (\pi \beta)}=(-1)^{m} \frac{\pi}{\sin (\pi(m+\beta))}$.
Item 7 is a consequence of Items 4 and 5 taken for $\beta=1$ and $m=n-1$, and the fact that $P_{n-1}(1)=n!$.
7.2.1. Meromorphic continuation of $\widehat{\chi_{s}^{L}}\left(-i \mathbf{V}_{\beta_{0}}\right)$. Before discussing the meromorphic continuation, let us first clarify its holomorphic properties on $\operatorname{Re}(s)>0$ :
Proposition 7.7. Let $\chi_{\infty}$ be a function verifying assumption (7.1), let $\beta_{0} \in H^{1}\left(\mathbb{T}^{d}, \mathbb{R}\right)$ and let $\tilde{x}: \mathbb{S}^{d-1} \rightarrow \mathbb{R}^{d}$ be a smooth function. Then, for all $(\varphi, \psi) \in \Omega^{k_{1}}\left(S \mathbb{T}^{d}\right) \times \Omega^{k_{2}}\left(S \mathbb{T}^{d}\right)$ with $k_{1}+k_{2}=2 d-1$, the function

$$
\begin{equation*}
s \mapsto \mathcal{L}_{(\varphi, \psi)}(s):=\int_{S \mathbb{T}^{d}} \varphi \wedge \widehat{\chi_{s}^{L}}\left(-i \mathbf{V}_{\beta_{0}}\right) \mathbf{T}_{-\tilde{x}}^{*}(\psi) \tag{7.20}
\end{equation*}
$$

is holomorphic on $\operatorname{Re}(s)>0$ and it satisfies

$$
\begin{equation*}
\left|\mathcal{L}_{(\varphi, \psi)}(s)\right| \leq \frac{C}{\operatorname{Re}(s)^{\min \left\{k_{1}, k_{2}\right\}+1}}\|\varphi\|_{L^{2}\left(S \mathbb{T}^{d}\right)}\|\psi\|_{L^{2}\left(S \mathbb{T}^{d}\right)} \tag{7.21}
\end{equation*}
$$

Recall that $\min \left\{k_{1}, k_{2}\right\} \leq d-1$ so that the latter estimate can always be roughly bounded by $\frac{C}{\operatorname{Re}(s)^{d}}$.
Proof. We start with (6.1) and we use again Lemma 3.15 to write

$$
\mathcal{C}_{\varphi, \mathbf{T}_{-\tilde{x}}^{*}(\psi)}\left(t, \beta_{0}\right)=\sum_{l=0}^{\min \left\{k_{1}, k_{2}\right\}} \mathcal{C}_{\varphi, \mathbf{T}_{-\tilde{x}}^{*}(\psi)}^{l}\left(t, \beta_{0}\right)
$$

with

$$
\mathcal{C}_{\varphi, \mathbf{T}_{-\tilde{x}}^{*}(\psi)}^{l}\left(t, \beta_{0}\right)=\frac{t^{l}}{l!} \sum_{\xi \in \mathbb{Z}^{d}} \int_{\mathbb{S}^{d-1}} e^{i t\left(\xi-\beta_{0}\right) \cdot \theta} e^{i \xi \cdot \tilde{x}(\theta)} B_{\tilde{x}, \xi}^{\left(k_{2}, l\right)}(\varphi, \psi)(\theta) \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta,|d \theta|)
$$

Integrating against $\chi_{\infty}(t) e^{-s t}$ then yields

$$
\begin{equation*}
\mathcal{L}_{(\varphi, \psi)}(s)=\int_{S \mathbb{T}^{d}} \varphi \wedge \widehat{\chi_{s}^{M}}\left(-i \mathbf{V}_{\beta_{0}}\right) \mathbf{T}_{-\tilde{x}}^{*}(\psi)=\sum_{l=0}^{\min \left\{k_{1}, k_{2}\right\}} \mathcal{L}_{(\varphi, \psi)}^{(l)}(s) \tag{7.22}
\end{equation*}
$$

with

$$
\begin{equation*}
\mathcal{L}_{(\varphi, \psi)}^{(l)}(s)=\int_{\mathbb{R}} \chi_{\infty}(t) e^{-s t} \mathcal{C}_{\varphi, \mathbf{T}_{-\tilde{x}}^{*}(\psi)}^{l}\left(t, \beta_{0}\right)|d t| \tag{7.23}
\end{equation*}
$$

According to (7.12), we have

$$
\left|\mathcal{C}_{\varphi, \mathbf{T}_{-\tilde{x}}^{*}(\psi)}^{l}\left(t, \beta_{0}\right)\right| \leq C t^{l}\|\varphi\|_{L^{2}\left(S \mathbb{T}^{d}\right)}\|\psi\|_{L^{2}\left(S \mathbb{T}^{d}\right)},
$$

which according to (7.23) implies holomorphy of $\mathcal{L}_{(\varphi, \psi)}^{(l)}$ in $\operatorname{Re}(s)>0$. We further deduce that

$$
\begin{aligned}
\left|\mathcal{L}_{(\varphi, \psi)}^{(l)}(s)\right| \leq \int_{\mathbb{R}}\left|\chi_{\infty}(t) e^{-s t} \mathcal{C}_{\varphi, \mathbf{T}_{-\tilde{x}}^{*}(\psi)}^{l}\left(t, \beta_{0}\right)\right| & |d t| \\
& \leq C \int_{\mathbb{R}}\left|\chi_{\infty}(t) t^{l} e^{-s t}\right||d t|\|\varphi\|_{L^{2}\left(S \mathbb{T}^{d}\right)}\|\psi\|_{L^{2}\left(S \mathbb{T}^{d}\right)}
\end{aligned}
$$

Recalling that $l \leq \min \left\{k_{1}, k_{2}\right\}$, Item 1 in Lemma 7.6 then yields, as $\operatorname{Re}(s) \rightarrow 0^{+}$,

$$
\left|\mathcal{L}_{(\varphi, \psi)}^{(l)}(s)\right| \leq \frac{C}{\operatorname{Re}(s)^{1+\min \left\{k_{1}, k_{2}\right\}}}\|\varphi\|_{L^{2}\left(S \mathbb{T}^{d}\right)}\|\psi\|_{L^{2}\left(S \mathbb{T}^{d}\right)}
$$

from which we infer (7.21) thanks to (7.22).
We now turn to our main statement on these regularized Laplace transforms. Lemma 7.6 leads us to introduce the functions

$$
\mathrm{F}_{\alpha}(z):= \begin{cases}\frac{\Gamma(1-\alpha)}{z^{1-\alpha}}, & \text { if } \quad \alpha<1  \tag{7.24}\\ \frac{(-1)^{n}}{n!} z^{n-1} \log (z), & \text { if } \quad \alpha=n \in \mathbb{Z}_{+} \\ \frac{\pi}{\sin (\pi \alpha) \Gamma(\alpha)} z^{\alpha-1}, & \text { if } \quad \alpha>1, \alpha \notin \mathbb{Z}_{+}\end{cases}
$$

these functions are considered as holomorphic functions on the plane $\mathbb{C} \backslash \mathbb{R}_{-}$(except if $\alpha \in \mathbb{Z}_{-}^{*}$ in which case $F_{\alpha}$ is holomorphic in $\mathbb{C}^{*}$ ). We also associate the corresponding distributions obtained as boundary values that is still denoted by $\mathrm{F}_{\alpha}$ :

$$
\mathrm{F}_{\alpha}(i y+0):= \begin{cases}\frac{\Gamma(1-\alpha) e^{i \frac{\pi}{2}(\alpha-1)}}{(y-i 0)^{1-\alpha}}, & \text { if } \quad \alpha<1  \tag{7.25}\\ \frac{(-1)^{n} e^{i \frac{\pi}{2}(n-1)}}{n!} y^{n-1}\left(\log (y-i 0)+\frac{\pi}{2}\right), & \text { if } \quad \alpha=n \in \mathbb{Z}_{+} \\ \frac{\pi^{n}}{\sin (\pi \alpha) \Gamma(\alpha)} e^{i \frac{\pi}{2}(\alpha-1)} y^{\alpha-1}, & \text { if } \quad \alpha>1, \alpha \notin \mathbb{Z}_{+},\end{cases}
$$

Both will describe the singularities of the Laplace transform of correlators up to the imaginary axis. For a given $\alpha \in \mathbb{R}, \mathrm{F}_{\alpha}$ is essentially the Laplace transform of $t^{-\alpha}$ (near $t=+\infty$ ).

We also denote

$$
\overline{\mathbb{C}}_{+}^{\Lambda}:=\left\{s \in \overline{\mathbb{C}}_{+},|\operatorname{Im}(s)| \leq \Lambda\right\}=\{s \in \mathbb{C}, \operatorname{Re}(z) \geq 0,|\operatorname{Im}(s)| \leq \Lambda\}
$$

and explain how the Laplace transform extends to this set.
Theorem 7.8. Suppose that the assumptions of Theorem 7.4 on $\tilde{x}, \chi_{\infty}$ and $T_{0}$ are satisfied. Given $N, N_{0} \in \mathbb{Z}_{+}^{2}, m \geq 0, \Lambda \geq 1$, and $(\varphi, \psi) \in \Omega^{k_{1}}\left(S \mathbb{T}^{d}\right) \times \Omega^{k_{2}}\left(S \mathbb{T}^{d}\right)$ with $k_{1}+k_{2}=2 d-1$, we
define, for all $s \in \mathbb{C}$ with $\operatorname{Re}(s)>0$,

$$
\begin{align*}
& \mathcal{R}_{(\varphi, \psi)}^{(N, \Lambda)}(s):=\mathcal{L}_{(\varphi, \psi)}(s)-\sum_{l=0}^{\min \left\{k_{1}, k_{2}\right\}} \frac{E_{\beta_{0}}^{(l)}}{s^{l+1}} \\
& 26) \quad-\sum_{l=0}^{\min \left\{k_{1}, k_{2}\right\}} \sum_{ \pm} \sum_{j=0}^{N-1} \sum_{0<\left|\xi-\beta_{0}\right| \leq 2 \Lambda} \frac{\mathrm{~F}_{\frac{d-1}{2}+j-l}\left(s \mp i\left|\xi-\beta_{0}\right|\right)}{l!\left|\xi-\beta_{0}\right|^{\frac{d-1}{2}+j}} P_{j, l, \xi}^{ \pm}[\varphi, \psi]\left( \pm \frac{\xi-\beta_{0}}{\left|\xi-\beta_{0}\right|}\right), \tag{7.26}
\end{align*}
$$

where $E_{\beta_{0}}^{(l)}$ is defined in (6.3), $\mathrm{F}_{\alpha}$ in (7.24), and, letting $L_{j, \omega}^{ \pm}$being that of Corollary 4.6, with

$$
\begin{equation*}
P_{j, l, \xi}^{ \pm}[\varphi, \psi](\omega)=e^{\mp i \frac{\pi}{4}(d-1)}(2 \pi)^{\frac{d-1}{2}} L_{j, \omega}^{ \pm}\left(e^{i \xi \cdot \tilde{x}(\cdot)} B_{\tilde{x}, \xi}^{\left(k_{2}, l\right)}(\varphi, \psi)\right)(\omega), \quad \omega \in \mathbb{S}^{d-1} \tag{7.27}
\end{equation*}
$$

Both sides of the equation 7.26 extend for $s=x+i y$ when $x \rightarrow 0^{+}$as tempered distributions of the variable $y$ where $\mathrm{F}_{\alpha}$ is defined in (7.25).

For any $N, N_{0} \in \mathbb{Z}_{+}^{2}$ such that

$$
\mathrm{k}:=\mathrm{k}\left(N_{0}, N\right)=\min \left\{N_{0}, N+\left\lceil\frac{d-1}{2}\right\rceil\right\}-\min \left\{k_{1}, k_{2}\right\}-2>0
$$

and for any $m \geq 0$, there exists $C=C_{N_{0}, N, m}>0$ such that for any $\Lambda \geq 1$ and for every $(\varphi, \psi) \in \mathcal{H}_{k_{1}, \beta_{0}}^{N_{0},-N_{0} / 2,2 N+d,-m} \times \mathcal{H}_{k_{2}, \beta_{0}}^{N_{0},-N_{0} / 2,2 N+d,-m}$ with $k_{1}+k_{2}=2 d-1$ the function $\mathcal{R}_{(\varphi, \psi)}^{(N, \Lambda)}$ originally defined for $\operatorname{Re}(s)>0$, extends as a function $\mathcal{R}_{(\varphi, \psi)}^{(N, \Lambda)} \in \mathcal{C}^{\mathrm{k}}\left(\overline{\mathbb{C}}_{+}^{\Lambda}\right)$ for $\mathrm{k}=\mathrm{k}\left(N_{0}, N\right)$ with

$$
\begin{equation*}
\left\|\mathcal{R}_{(\varphi, \psi)}^{(N, \Lambda)}\right\|_{\mathcal{C}^{k}\left(\overline{\mathbb{C}}_{+}^{\Lambda}\right)} \leq C \Lambda^{2 m+N+\frac{d+1}{2}}\|\varphi\|_{\mathcal{H}_{k_{1}, \beta_{0}}^{N_{0},-N_{0} / 2,2 N+d,-m}}\|\varphi\|_{\mathcal{H}_{k_{2},-\beta_{0}}^{N_{0}, N_{0} / 2,2 N+d,-m},} \tag{7.28}
\end{equation*}
$$

using the notation of Definition 6.1.
In particular, this theorem states that for $(\varphi, \psi) \in \Omega^{k_{1}}\left(S \mathbb{T}^{d}\right) \times \Omega^{k_{2}}\left(S \mathbb{T}^{d}\right)$, the Laplace transform $\mathcal{L}_{(\varphi, \psi)}(s)$ extends as a $\mathcal{C}^{\infty}$ function in a neighborhood in $\overline{\mathbb{C}}_{+}$of any point $z_{0} \in i \mathbb{R} \backslash$ $\left( \pm i \sqrt{\operatorname{Sp}\left(-\Delta_{-\beta_{0}}\right)}\right)^{14}$, where $\Delta_{-\beta_{0}}=\left(\partial_{x}-i \beta_{0}\right)^{2}$ is the magnetic Laplacian acting on functions on $\mathbb{T}^{d}$. This follows from the fact that bookkeeping the regularities in the proof below, we may choose the regularity exponent $k=\inf \left(N_{0}-2-\inf \left(k_{1}, k_{2}\right), N-2-\inf \left(k_{1}, k_{2}\right)+\frac{d-1}{2}\right)$ and we see that $k \rightarrow+\infty$ when $N, N_{0} \rightarrow+\infty$. Moreover, when $\operatorname{Re}(s)>0$ goes to zero, then $y \mapsto \mathcal{L}_{(\varphi, \psi)}(i y+0)$ makes sense as a tempered distribution obtained as boundary value of holomorphic function and our Theorem describes its singularity near any point in $\pm \sqrt{\operatorname{Sp}\left(-\Delta_{\beta_{0}}\right)}$ explicitly in terms of the distributions $\mathrm{F}_{\alpha}$ in (7.25). In particular, if $d$ is odd, (7.26) gives an expansion of the limit Laplace transform $\lim _{x \rightarrow 0^{+}} \mathcal{L}_{(\varphi, \psi)}(x+i y)$ in terms of the distributions $\frac{1}{\left(y-i 0-z_{j}\right)^{m}}$ and $\left(y-z_{j}\right)^{n} \log \left(y-i 0-z_{j}\right)$, for $z_{j} \in \pm \sqrt{\operatorname{Sp}\left(-\Delta_{\beta_{0}}\right)}$ and $m, n \in \mathbb{Z}_{+}, m \leq \min \left\{k_{1}, k_{2}\right\}-\frac{d-1}{2}$. If $d$ is even, (7.26) is an expansion of the limit Laplace transform in terms of the distributions $\frac{1}{\left(y-i 0-z_{j}\right)^{m / 2}}$ for $z_{j} \in \pm \sqrt{\operatorname{Sp}\left(-\Delta_{\beta_{0}}\right)}$ and $m \in \mathbb{Z}, m \leq 2 \min \left\{k_{1}, k_{2}\right\}-d+1$. The coefficients in this expansion are explicit; recall for instance that $L_{0, \omega}^{ \pm}=1$. Note also that in (7.28) the regularity of the resolvent up to the imaginary axis, given by the index $\mathrm{k}\left(N_{0}, N\right)$, depends explicitly on the anisotropic Sobolev regularity $\mathcal{H}^{N_{0},-N_{0} / 2,2 N+d,-m / 2}$ of the currents $(\varphi, \psi)$. The bigger $N_{0}, N$ are, the better the regularity of this background remainder term is.

Note finally that in case $\tilde{x}=0$ (and when computing the resolvent acting on functions), the proof simplifies slightly and the estimate (7.28) of the remainder is better behaved in terms of spaces and powers of $\Lambda$. As far as the proof is concerned, it is worth noticing that, as opposed to the proofs of Theorems 6.4 and 7.4 , we do actually make use of both non-stationary and stationary phase estimates of Corollaries 4.3 and 4.6.

Proof of Theorem 7.8. As in the proof of Proposition 7.7, we consider $(\varphi, \psi) \in \Omega^{k_{1}}\left(S \mathbb{T}^{d}\right) \times$ $\Omega^{k_{2}}\left(S \mathbb{T}^{d}\right)$ and decompose $\mathcal{C}_{\varphi, \mathbf{T}_{-\tilde{x}}^{*}(\psi)}\left(t, \beta_{0}\right)$ as a sum of $\mathfrak{C}_{\varphi, \mathbf{T}_{-\tilde{x}}^{*}(\psi)}^{l}\left(t, \beta_{0}\right)$ according to (3.18)-(3.19).

[^12]Then decomposing $\mathcal{C}_{\varphi, \mathbf{T}_{-\tilde{x}}^{*}(\psi)}^{l}\left(t, \beta_{0}\right)$ according to (6.5), we are left with describing the terms $\mathcal{L}_{(\varphi, \psi)}^{(l)}(s)$ in (7.22)-(7.23), which we again decompose accordingly as

$$
\begin{equation*}
\mathcal{L}_{(\varphi, \psi)}^{(l)}(s)=\mathcal{L}_{(\varphi, \psi)}^{(l, E)}(s)+\mathcal{L}_{(\varphi, \psi)}^{(l,-1)}(s)+\mathcal{L}_{(\varphi, \psi)}^{(l, 0)}(s)+\mathcal{L}_{(\varphi, \psi)}^{(l, 1)}(s) \tag{7.29}
\end{equation*}
$$

with

$$
\begin{align*}
& \mathcal{L}_{(\varphi, \psi)}^{(l, E)}(s)=\int_{0}^{\infty} \chi_{\infty}(t) e^{-s t} \frac{t^{l}}{l!} E_{\beta_{0}}^{(l)}|d t|, \quad \text { and } \\
& \mathcal{L}_{(\varphi, \psi)}^{(l, j)}(s)=\int_{0}^{\infty} \chi_{\infty}(t) e^{-s t} \frac{t^{l}}{l!} \mathrm{C}^{(l, j)}(t)|d t|, \quad \text { for } j \in\{-1,0,1\} . \tag{7.30}
\end{align*}
$$

We now study each of these terms separately.
Firstly, we have using Item 3 of Lemma 7.6

$$
\begin{equation*}
\mathcal{L}_{(\varphi, \psi)}^{(l, E)}(s)=E_{\beta_{0}}^{(l)} \frac{1}{l!} \int_{0}^{\infty} \chi_{\infty}(t) t^{l} e^{-s t}|d t|=\frac{E_{\beta_{0}}^{(l)}}{l!} F_{\chi_{\infty},-l}(s)=\frac{E_{\beta_{0}}^{(l)}}{s^{l+1}}+\frac{E_{\beta_{0}}^{(l)}}{l!} H_{-l}(s) \tag{7.31}
\end{equation*}
$$

where $H_{-l}$ is an entire function such that $\left|\partial_{s}^{k} H_{-l}(s)\right| \leq C_{\chi_{\infty},-l, k}\left(e^{-T_{1} \operatorname{Re}(s)}+1\right)$ on $\mathbb{C}$.
Secondly, we consider the term with $\mathcal{L}_{(\varphi, \psi)}^{(l, 0)}(s)$ and proceed as in the proof of Theorem 6.4. The index $j=0$ means that we consider a good term in the nonstationary phase region. According to Corollary 4.3, we have, for $t \geq C\left(\chi_{0}\right)\|d \tilde{x}\|_{L^{\infty}\left(\mathbb{S}^{d-1}\right)}$, all $N \in \mathbb{Z}_{+}$,

$$
\left|\mathcal{C}^{(l, 0)}(t)\right| \leq C_{N} \sum_{\xi \in \mathbb{Z}^{d} \backslash\left\{\beta_{0}\right\}}\left(\left|\xi-\beta_{0}\right| t\right)^{-N}\left\|B_{\tilde{x}, \xi}^{\left(k_{2}, l\right)}(\varphi, \psi)\right\|_{W^{N, 1}\left(\mathbf{C}_{0}\left(\xi-\beta_{0}\right)\right)}
$$

We now use that $\operatorname{supp}\left(\chi_{\infty}\right) \subset\left[T_{0},+\infty\right)$ with $T_{0} \geq \max \left\{1, C\left(\chi_{0}\right)\|d \tilde{x}\|_{L^{\infty}\left(\mathbb{S}^{d-1}\right)}\right\}$. Integrating in (7.30), using Item 1 in Lemma 7.6, we deduce that $\mathcal{L}_{(\varphi, \psi)}^{(l, 0)}(s)$ extends as a function in $\mathcal{C}^{\infty}\left(\overline{\mathbb{C}}_{+}\right)$ with

$$
\begin{align*}
\left|\partial_{s}^{k} \mathcal{L}_{(\varphi, \psi)}^{(l, 0)}(s)\right| \leq & \leq C_{N_{0}} \int_{0}^{\infty} \chi_{\infty}(t) t^{l+k} t^{-N_{0}} e^{-\operatorname{Re}(s) t}|d t| \sum_{\xi \in \mathbb{Z}^{d} \backslash\left\{\beta_{0}\right\}} \frac{\left\|B_{\tilde{x}, \xi}^{\left(k_{2}, l\right)}(\varphi, \psi)\right\|_{W^{N_{0}, 1}\left(\mathbf{C}_{0}\left(\xi-\beta_{0}\right)\right)}}{\left|\xi-\beta_{0}\right|^{N_{0}}} \\
& \leq C_{N_{0}, k} \sum_{\xi \in \mathbb{Z}^{d} \backslash\left\{\beta_{0}\right\}} \frac{\left\|\pi_{\xi}^{\left(k_{1}\right)}(\varphi)\right\|_{H^{N_{0}}\left(\mathbf{C}_{0}\left(\xi-\beta_{0}\right)\right)}\left\|\pi_{-\xi}^{\left(k_{2}\right)}(\psi)\right\|_{H^{N_{0}}\left(\mathbf{C}_{0}\left(\xi-\beta_{0}\right)\right)}}{\left|\xi-\beta_{0}\right|^{N_{0}}} \tag{7.32}
\end{align*}
$$

uniformly on $\operatorname{Re}(s) \geq 0$, as soon as $N_{0}-k-l>1$. Recalling that $l \leq \min \left\{k_{1}, k_{2}\right\}$, this holds for all $N_{0}, k$ such that $N_{0}>k+\min \left\{k_{1}, k_{2}\right\}+1$.

Thirdly, we consider the term with $\mathcal{L}_{(\varphi, \psi)}^{(l, \pm 1)}(s)$. According to (7.30) and the expression of $\mathcal{C}^{(l, \pm 1)}(t)$ in (6.5), we have

$$
\begin{aligned}
\mathcal{L}_{(\varphi, \psi)}^{(l, \pm 1)}(s)= & \sum_{\xi \in \mathbb{Z}^{d} \backslash\left\{\beta_{0}\right\}} \int_{\mathbb{S}^{d-1}}\left(\int_{\mathbb{R}} \chi_{\infty}(t) \frac{t^{l}}{l!} e^{-s t} e^{i t\left(\xi-\beta_{0}\right) \cdot \theta}|d t|\right) \\
& \times \chi_{ \pm 1}\left(\theta \cdot \frac{\xi-\beta_{0}}{\left|\xi-\beta_{0}\right|}\right) e^{i \xi \cdot \tilde{x}(\theta)} B_{\tilde{x}, \xi}^{\left(k_{2}, l\right)}(\varphi, \psi)(\theta) \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta,|d \theta|)
\end{aligned}
$$

## An extra decomposition in large and small Fourier modes.

Given $\Lambda>0$, we recall that we always assume $|\operatorname{Im}(s)| \leq \Lambda$, and we split (further) this expression according to

$$
\begin{aligned}
\mathcal{L}_{(\varphi, \psi)}^{(l, \pm 1)}(s) & =\mathcal{L}_{\leq}^{(l, \pm 1)}(s)+\mathcal{L}_{>}^{(l, \pm 1)}(s), \quad \text { with } \\
\mathcal{L}_{\leq}^{(l, \pm 1)}(s) & :=\sum_{\xi \in \mathbb{Z}^{d}, 0<\left|\xi-\beta_{0}\right| \leq 2 \Lambda} \cdots, \quad \text { and } \quad \mathcal{L}_{>}^{(l, \pm 1)}(s):=\sum_{\xi \in \mathbb{Z}^{d},\left|\xi-\beta_{0}\right|>2 \Lambda} \cdots
\end{aligned}
$$

In other words, we decomposed the sum $\sum_{\xi}$ into an infinite sum over large Fourier modes (i.e. $|\xi|$ far from $|s|$ ) and into a finite sum over small Fourier modes. We will apply stationary phase estimates only to the finite sum and use integration by parts with the infinite sum to get decay in $\xi$. Let us first consider the good term $\mathcal{L}_{>}^{(l, \pm 1)}(s)$. Recalling the properties of $\chi_{ \pm 1}$ in Definition 4.1, we have $\sigma \in \operatorname{supp}\left(\chi_{ \pm 1}\right) \Longrightarrow|\sigma| \geq \epsilon_{0}>0$ with $\epsilon_{0}<1 / 2$, from which we infer that $\left|\theta \cdot\left(\xi-\beta_{0}\right)\right| \geq$ $\epsilon_{0}\left|\xi-\beta_{0}\right|$ for $(\theta, \xi)$ in the support of $\chi_{ \pm 1}\left(\theta \cdot \frac{\xi-\beta_{0}}{\left|\xi-\beta_{0}\right|}\right)$. For $|\operatorname{Im}(s)| \leq \Lambda$, and $(\theta, \xi)$ in the support of $\chi_{ \pm 1}\left(\theta \cdot \frac{\xi-\beta_{0}}{\left|\xi-\beta_{0}\right|}\right)$ and such that $\left|\xi-\beta_{0}\right|>2 \Lambda$, we thus have a lower bound on the phase factor:

$$
\left|s-i\left(\xi-\beta_{0}\right) \cdot \theta\right| \geq\left|\operatorname{Im}(s)-\left(\xi-\beta_{0}\right) \cdot \theta\right| \geq\left(1-\epsilon_{0}\right)\left|\xi-\beta_{0}\right|-|\operatorname{Im}(s)| \geq\left(1 / 2-\epsilon_{0}\right)\left|\xi-\beta_{0}\right| .
$$

According to Items 1, 2 and 5 of Lemma 7.6 applied with $z=s-i\left(\xi-\beta_{0}\right) \cdot \theta, \alpha=-l$ and $\beta=-(l+k)$, we deduce that for any $m, k \in \mathbb{Z}_{+}$,

$$
\left|\partial_{s}^{k} \int_{\mathbb{R}} \chi_{\infty}(t) \frac{t^{l}}{l!} e^{-s t} e^{i t\left(\xi-\beta_{0}\right) \cdot \theta}\right| d t\left|\left\lvert\, \leq \frac{C_{m, k}}{\left|s-i\left(\xi-\beta_{0}\right)\right|^{m}} \leq \frac{C_{m, k}}{\left|\xi-\beta_{0}\right|^{m}}\right.\right.
$$

uniformly in $\Lambda>0, \operatorname{Re}(s) \geq 0,|\operatorname{Im}(s)| \leq \Lambda,\left|\xi-\beta_{0}\right|>2 \Lambda,(\theta, \xi)$ in the support of $\chi_{ \pm 1}\left(\theta \cdot \frac{\xi-\beta_{0}}{\left|\xi-\beta_{0}\right|}\right)$. Moreover, this integral extends as a function in $\mathcal{C}^{\infty}\left(\overline{\mathbb{C}}_{+}^{\Lambda}\right)$. As a consequence, $\mathcal{L}_{>}^{(l, \pm 1)}$ also extends as a function in $\mathcal{C}^{\infty}\left(\overline{\mathbb{C}}_{+}^{\Lambda}\right)$ with, for $s \in \overline{\mathbb{C}}_{+}^{\Lambda}$,

$$
\begin{aligned}
\left|\partial_{s}^{k} \mathcal{L}_{>}^{(l, \pm 1)}(s)\right| & \leq C_{m, k} \sum_{\xi \in \mathbb{Z}^{d},\left|\xi-\beta_{0}\right|>2 \Lambda} \frac{1}{\left|\xi-\beta_{0}\right|^{m}}\left\|B_{\tilde{x}, \xi}^{\left(k_{2}, l\right)}(\varphi, \psi)\right\|_{L^{1}\left(\mathbf{C}_{ \pm 1}\left(\xi-\beta_{0}\right)\right)} \\
& \leq C_{m, k} \sum_{\xi \in \mathbb{Z}^{d},\left|\xi-\beta_{0}\right|>2 \Lambda} \frac{1}{\left|\xi-\beta_{0}\right|^{m}}\left\|\pi_{\xi}^{\left(k_{1}\right)}(\varphi)\right\|_{L^{2}\left(\mathbf{C}_{ \pm 1}\left(\xi-\beta_{0}\right)\right)}\left\|\pi_{-\xi}^{\left(k_{2}\right)}(\psi)\right\|_{L^{2}\left(\mathbf{C}_{ \pm 1}\left(\xi-\beta_{0}\right)\right)}
\end{aligned}
$$

We next consider the term $\mathcal{L}_{\leq}^{(l, \pm 1)}(s)$, which we rewrite as

$$
\begin{equation*}
\mathcal{L}_{\leq}^{(l, \pm 1)}(s):=\sum_{\xi \in \mathbb{Z}^{d}, 0<\left|\xi-\beta_{0}\right| \leq 2 \Lambda} \int_{\mathbb{R}} \chi_{\infty}(t) \frac{t^{l}}{l!} e^{-s t} I_{B_{\tilde{x}, \xi, \xi}^{\left(k_{2}, l\right)}(\varphi, \psi)}^{( \pm 1)}\left(\xi-\beta_{0}, t\right)|d t| \tag{7.34}
\end{equation*}
$$

where $I_{F}^{( \pm 1)}\left(\xi-\beta_{0}, t\right)$ is defined in (4.2). We then use the asymptotic expansion in Corollary 4.6 which yields, with $P_{j, l, \xi}^{ \pm}[\varphi, \psi]$ defined in (7.27),

$$
I_{B_{\tilde{x}, \xi}^{(k, t)}(\varphi, \psi)}^{( \pm 1)}\left(\xi-\beta_{0}, t\right)=\sum_{j=0}^{N-1} \frac{e^{ \pm i t\left|\xi-\beta_{0}\right|}}{\left(t\left|\xi-\beta_{0}\right|\right)^{\frac{d-1}{2}+j}} P_{j, l, \xi}^{ \pm}[\varphi, \psi]\left( \pm \frac{\xi-\beta_{0}}{\left|\xi-\beta_{0}\right|}\right)+\frac{R_{N}^{ \pm}[\varphi, \psi](\xi, t)}{t^{N+\frac{d-1}{2}}}
$$

where

$$
\begin{equation*}
\left|R_{N}^{ \pm}[\varphi, \psi](\xi, t)\right| \leq C_{N}\left|\xi-\beta_{0}\right|^{N+\frac{d+1}{2}}\left\|B_{\tilde{x}, \xi}^{\left(k_{2}, l\right)}(\varphi, \psi)\right\|_{W^{2 N+d, 1}\left(\mathbf{C}_{ \pm 1}\left(\xi-\beta_{0}\right)\right)} \tag{7.35}
\end{equation*}
$$

(except if $\tilde{x}=0$, in which case this remainder is much better behaved in terms of $\xi$ and it is not necessary to split this again). Note that when $\tilde{x}$ is non zero, the remainder in the stationary phase estimates has good decay properties in the $t$ variable but not in $\xi$, but this is not of our concern since the extra decomposition involves only a finite sum $\sum_{\left|\xi-\beta_{0}\right| \leqslant 2 \Lambda}$. Coming back to (7.34), we have obtained

$$
\begin{equation*}
\mathcal{L}_{\leq}^{(l, \pm 1)}(s)=\frac{\mathrm{c}_{d}^{ \pm}}{l!} \sum_{j=0}^{N-1} \mathrm{~T}_{j}(s)+\mathrm{R}_{N}(s), \tag{7.36}
\end{equation*}
$$

where

$$
\begin{aligned}
\mathrm{T}_{j}^{ \pm}(s) & =\sum_{\xi \in \mathbb{Z}^{d}, 0<\left|\xi-\beta_{0}\right| \leq 2 \Lambda}\left(\int_{\mathbb{R}_{+}} \chi_{\infty}(t) \frac{e^{-s t \pm i t\left|\xi-\beta_{0}\right|}}{t^{\frac{d-1}{2}+j-l}}|d t|\right) \frac{1}{\left|\xi-\beta_{0}\right|^{\frac{d-1}{2}+j}} P_{j, l, \xi}^{ \pm}[\varphi, \psi]\left( \pm \frac{\xi-\beta_{0}}{\left|\xi-\beta_{0}\right|}\right) \\
\mathrm{R}_{N}^{ \pm}(s) & =\sum_{\xi \in \mathbb{Z}^{d}, 0<\left|\xi-\beta_{0}\right| \leq 2 \Lambda} \int_{\mathbb{R}_{+}} \chi_{\infty}(t) \frac{R_{N}^{ \pm}[\varphi, \psi](\xi, t)}{t^{N+\frac{d-1}{2}-l}} e^{-s t}|d t|
\end{aligned}
$$

According to Items 1 and 2 of Lemma 7.6 and the uniform in $t$ estimate in (7.35), $\mathrm{R}_{N}^{ \pm}$extends as a function in $\mathcal{C}^{k}\left(\overline{\mathbb{C}}_{+}^{\Lambda}\right)$ as soon as $N+\frac{d-1}{2}-l-k>1$ (which, recalling $l \leq \min \left\{k_{1}, k_{2}\right\}$, holds for all $l$ if $N, k$ are such that $\left.N>k+\min \left\{k_{1}, k_{2}\right\}+1-\frac{d-1}{2}\right)$, with the estimate for $m \geq 0$

$$
\begin{align*}
& \left|\partial_{s}^{k} \mathrm{R}_{N}^{ \pm}(s)\right| \leq C_{N, k} \sum_{\xi \in \mathbb{Z}^{d}, 0<\left|\xi-\beta_{0}\right| \leq 2 \Lambda}\left|\xi-\beta_{0}\right|^{N+\frac{d+1}{2}}\left\|B_{\tilde{x}, \xi}^{\left(k_{2}, l\right)}(\varphi, \psi)\right\|_{W^{2 N+d, 1}\left(\mathbf{C}_{ \pm 1}(\xi)\right)}  \tag{7.37}\\
& \leq C_{N, m, k} \Lambda^{2 m+N+\frac{d+1}{2}} \sum_{\xi \in \mathbb{Z}^{d} \backslash\left\{\beta_{0}\right\}} \frac{\left\|\pi_{\xi}^{\left(k_{1}\right)}(\varphi)\right\|_{H^{2 N+d}\left(\mathbf{C}_{ \pm 1}\left(\xi-\beta_{0}\right)\right)}\left\|\pi_{-\xi}^{\left(k_{2}\right)}(\psi)\right\|_{H^{2 N+d}\left(\mathbf{C}_{ \pm 1}\left(\xi-\beta_{0}\right)\right)}}{\left|\xi-\beta_{0}\right|^{2 m}} .
\end{align*}
$$

Then, we have

$$
\mathrm{T}_{j}^{ \pm}(s)=\sum_{\xi \in \mathbb{Z}^{d}, 0<\left|\xi-\beta_{0}\right| \leq 2 \Lambda} F_{\chi \infty, \frac{d-1}{2}+j-l}\left(s \mp i\left|\xi-\beta_{0}\right|\right) \frac{1}{\left|\xi-\beta_{0}\right|^{\frac{d-1}{2}+j}} P_{j, l, \xi}^{ \pm}[\varphi, \psi]\left( \pm \frac{\xi-\beta_{0}}{\left|\xi-\beta_{0}\right|}\right)
$$

where the singularity of $s \mapsto F_{\chi \infty, \frac{d-1}{2}+j-l}\left(s \mp i\left|\xi-\beta_{0}\right|\right)$ near $s= \pm i\left|\xi-\beta_{0}\right|$ is described in Items 3-4-6-7 of Lemma 7.6, namely:

$$
F_{\chi \infty, \frac{d-1}{2}+j-l}(z)=\mathrm{F}_{\frac{d-1}{2}+j-l}(z)+H_{\frac{d-1}{2}+j-l}(z)
$$

with $\mathrm{F}_{\alpha}$ defined in (7.24), and $H_{\alpha}$ are entire functions whose derivatives are uniformly bounded by a constant times $\langle z\rangle^{\frac{d-1}{2}}$ on $\operatorname{Re}(s) \geq-1$. Moreover, the terms $\mathrm{T}_{j}^{ \pm}(s)$ have a limit $\lim _{x \rightarrow 0^{+}} \mathrm{T}_{j}^{ \pm}(x+i y)$ in $\mathcal{S}^{\prime}$ since the terms $\mathrm{F}_{\alpha}$ have boundary value distributions by Lemma 7.6 defined by (7.25). This allows us to rewrite $\mathrm{T}_{j}(s)$ as

$$
\begin{array}{r}
\mathrm{T}_{j}^{ \pm}(s)=\sum_{\xi \in \mathbb{Z}^{d}, 0<\left|\xi-\beta_{0}\right| \leq 2 \Lambda} \mathrm{~F}_{\frac{d-1}{2}+j-l}\left(s \mp i\left|\xi-\beta_{0}\right|\right) \frac{1}{\left|\xi-\beta_{0}\right|^{\frac{d-1}{2}+j}} P_{j, l, \xi}^{ \pm}[\varphi, \psi]\left( \pm \frac{\xi-\beta_{0}}{\left|\xi-\beta_{0}\right|}\right) \\
+\tilde{R}_{j}^{ \pm}[\varphi, \psi](s)
\end{array}
$$

where

$$
\tilde{R}_{j}^{ \pm}[\varphi, \psi](s)=\sum_{\xi \in \mathbb{Z}^{d}, 0<\left|\xi-\beta_{0}\right| \leq 2 \Lambda} H_{\frac{d-1}{2}+j-l}\left(s \mp i\left|\xi-\beta_{0}\right|\right) \frac{1}{\left|\xi-\beta_{0}\right|^{\frac{d-1}{2}+j}} P_{j, l, \xi}^{ \pm}[\varphi, \psi]\left( \pm \frac{\xi-\beta_{0}}{\left|\xi-\beta_{0}\right|}\right)
$$

The function $\tilde{R}_{j}^{ \pm}$is holomorphic on $\operatorname{Re}(s)>-1$. Moreover, recalling (7.27), the fact that the operators $L_{j, \frac{\xi-\beta_{0}}{\left|\xi-\beta_{0}\right|}}^{ \pm}$are of order $2 j$, and using a Sobolev embedding, this can be estimated as follows, for $s \in \overline{\mathbb{C}}_{+}^{\Lambda} \cap\{|\operatorname{Re}(s)| \leq 1\}$,

$$
\begin{aligned}
\left|\partial_{s}^{k} \tilde{R}_{j}^{ \pm}[\varphi, \psi](s)\right| & \lesssim_{k}\langle\Lambda\rangle^{\frac{d-1}{2}} \sum_{\xi \in \mathbb{Z}^{d}, 0<\left|\xi-\beta_{0}\right| \leq 2 \Lambda} \frac{\left|L_{j, \frac{\xi-\beta_{0}}{\left|\xi-\beta_{0}\right|}}\left(e^{i \xi \cdot \tilde{x}(\cdot)} B_{\tilde{x}, \xi}^{\left(k_{2}, l\right)}(\varphi, \psi)\right)\left( \pm \frac{\xi-\beta_{0}}{\left|\xi-\beta_{0}\right|}\right)\right|}{\left|\xi-\beta_{0}\right|^{\frac{d-1}{2}+j}} \\
& \lesssim_{k}\langle\Lambda\rangle^{\frac{d-1}{2}} \sum_{\xi \in \mathbb{Z}^{d}, 0<\left|\xi-\beta_{0}\right| \leq 2 \Lambda} \frac{\left\|e^{i \xi \cdot \tilde{x}(\cdot)} B_{\tilde{x}, \xi}^{\left(k_{2}, l\right)}(\varphi, \psi)\right\|_{W^{2 j, \infty}\left(\mathbf{C}_{ \pm 1}\left(\xi-\beta_{0}\right)\right)}}{\left|\xi-\beta_{0}\right|^{\frac{d-1}{2}+j}} \\
& \lesssim_{k}\langle\Lambda\rangle^{\frac{d-1}{2}} \sum_{\xi \in \mathbb{Z}^{d}, 0<\left|\xi-\beta_{0}\right| \leq 2 \Lambda} \frac{\langle\xi\rangle^{2 j}}{\left|\xi-\beta_{0}\right|^{\frac{d-1}{2}+j}\left\|B_{\tilde{x}, \xi}^{\left(k_{2}, l\right)}(\varphi, \psi)\right\|_{W^{2 j+d, 1}\left(\mathbf{C}_{ \pm 1}\left(\xi-\beta_{0}\right)\right)}} .
\end{aligned}
$$

which can be bounded one more time using the Cauchy-Schwarz inequality in terms of the norms of $\varphi$ and $\psi$. This yields actually a better bound than the estimate (7.37) we already have on $\mathrm{R}_{N}^{ \pm}$.

Coming back to the definition of $\mathcal{L}_{(\varphi, \psi)}^{(l)}$ in (7.29) and collecting (7.31), (7.32), (7.33), (7.36), (7.37) together with the last three lines, we obtain that if $N+\frac{d-1}{2}-l-k>1, N_{0}-k-l>1$,
and $m \geq 0$, then the function

$$
\begin{aligned}
\mathcal{R}_{(\varphi, \psi)}^{(l, N)}(s) & :=\mathcal{L}_{(\varphi, \psi)}^{(l)}(s)-\frac{E_{\beta_{0}}^{(l)}}{s^{l+1}} \\
& -\sum_{ \pm} \sum_{j=0}^{N-1} \sum_{\xi \in \mathbb{Z}^{d}, 0<\left|\xi-\beta_{0}\right| \leq 2 \Lambda} \frac{1}{l!} \frac{\mathrm{F}_{\frac{d-1}{2}+j-l}\left(s \mp i\left|\xi-\beta_{0}\right|\right)}{\left|\xi-\beta_{0}\right|^{\frac{d-1}{2}+j}} P_{j, l, \xi}^{ \pm}[\varphi, \psi]\left( \pm \frac{\xi-\beta_{0}}{\left|\xi-\beta_{0}\right|}\right)
\end{aligned}
$$

extends as $\mathcal{R}_{(\varphi, \psi)}^{(l, N)} \in \mathcal{C}^{k}\left(\overline{\mathbb{C}}_{+}^{\Lambda}\right)$ with, for $s \in \overline{\mathbb{C}}_{+}^{\Lambda}$ with $\operatorname{Re}(s) \leq 1$,

$$
\begin{aligned}
& \left|\partial_{s}^{k} \mathcal{R}_{(\varphi, \psi)}^{(l, N)}(s)\right| \leq C_{N_{0}, k} \sum_{\xi \in \mathbb{Z}^{d} \backslash\left\{\beta_{0}\right\}} \frac{\left\|\pi_{\xi}^{\left(k_{1}\right)}(\varphi)\right\|_{H^{N_{0}}\left(\mathbf{C}_{0}\left(\xi-\beta_{0}\right)\right)}\left\|\pi_{-\xi}^{\left(k_{2}\right)}(\psi)\right\|_{H^{N_{0}}\left(\mathbf{C}_{0}\left(\xi+\beta_{0}\right)\right)}}{\left|\xi-\beta_{0}\right|^{N_{0}}} \\
& +C_{N, m, k} \Lambda^{2 m+N+\frac{d+1}{2}} \sum_{\xi \in \mathbb{Z}^{d} \backslash\left\{\beta_{0}\right\}} \frac{\left\|\pi_{\xi}^{\left(k_{1}\right)}(\varphi)\right\|_{H^{2 N+d}\left(\mathbf{C}_{ \pm 1}\left(\xi-\beta_{0}\right)\right)}\left\|\pi_{-\xi}^{\left(k_{2}\right)}(\psi)\right\|_{H^{2 N+d}\left(\mathbf{C}_{ \pm 1}\left(\xi+\beta_{0}\right)\right)}}{\left|\xi-\beta_{0}\right|^{2 m}} \\
& \leq C_{N_{0}, N, m, k} \Lambda^{2 m+N+\frac{d+1}{2}}\|\varphi\|_{\mathcal{H}_{k_{1}, \beta_{0}}^{N_{0},-N_{0} / 2,2 N+d,-m}}\|\varphi\|_{\mathcal{H}_{k_{2},-\beta_{0}}^{N_{0},-N_{0} / 2,2 N+d,-m}},
\end{aligned}
$$

where we have used the notation of Definition 6.1. When collecting all terms in (7.22)-(7.23) this includes the statement of the theorem as $\mathcal{R}_{(\varphi, \psi)}^{(N, \Lambda)}(s)=\sum_{l=0}^{\min \left\{k_{1}, k_{2}\right\}} \mathcal{R}_{(\varphi, \psi)}^{(l, N)}(s)$.
7.3. Terms near zero in the Mellin and Laplace transforms. To conclude the proofs of Theorems 2.2 and 2.3 (together with their generalization to the case of forms/currents) it remains to describe the properties of the part of the integrals involving $\chi_{0}=1-\chi_{\infty}$ :

Proposition 7.9. Let $T_{1} \geq 1$, assume that $\chi_{0} \in \mathcal{C}_{c}^{\infty}(\mathbb{R})$ has $\operatorname{supp}\left(\chi_{0}\right) \subset\left[-T_{1}, T_{1}\right]$, and let $\sigma, N \in \mathbb{R}$. Consider the operator functions

$$
A_{\mathcal{M}}: s \mapsto \int_{1}^{\infty} t^{-s} \chi_{0}(t) e^{-t \mathbf{V}_{\beta_{0}}}|d t| \quad \text { and } \quad A_{\mathcal{L}}: s \mapsto \int_{0}^{\infty} e^{-s t} \chi_{0}(t) e^{-t \mathbf{V}_{\beta_{0}}}|d t|
$$

Then, there exists $C>0$ such that for all $\left(k_{1}, k_{2}\right)$ with $k_{1}+k_{2}=2 d-1$, for every $(\varphi, \psi) \in$ $\mathcal{H}_{k_{1}, \beta_{0}}^{\sigma, N, \sigma, N} \times \mathcal{H}_{k_{2},-\beta_{0}}^{-\sigma,-N,-\sigma,-N}$,

$$
A_{\mathcal{M}, \varphi, \psi}: s \mapsto \int_{S \mathbb{T}^{d}} \varphi \wedge A_{\mathcal{M}}(s) \mathbf{T}_{-\tilde{x}}^{*}(\psi), \quad A_{\mathcal{L}, \varphi, \psi}: s \mapsto \int_{S \mathbb{T}^{d}} \varphi \wedge A_{\mathcal{L}}(s) \mathbf{T}_{-\tilde{x}}^{*}(\psi)
$$

are entire functions satisfying for all $s \in \mathbb{C}$,

$$
\begin{aligned}
\left|A_{\mathcal{M}, \varphi, \psi}(s)\right| \leq C \frac{T_{1}^{-\operatorname{Re}(s)+d}+1}{\langle\operatorname{Re}(s)\rangle}\|\varphi\|_{\mathcal{H}_{k_{1}, \beta_{0}}^{\sigma, N, \sigma, N}}\|\psi\|_{\mathcal{H}_{k_{2},-\beta_{0}}^{-\sigma,-N,-\sigma,-N}}, \\
\left|A_{\mathcal{L}, \varphi, \psi}(s)\right| \leq C \frac{e^{-T_{1} \operatorname{Re}(s)}+1}{\langle\operatorname{Re}(s)\rangle}\|\varphi\|_{\mathcal{H}_{k_{1}, \beta_{0}}^{\sigma, N, \sigma, N}}\|\psi\|_{\mathcal{H}_{k_{2},-\beta_{0}}^{-\sigma,-N,-\sigma,-N}} .
\end{aligned}
$$

Proof. We prove the result for $A_{\mathcal{M}, \varphi, \psi}(s)$; the proof for $A_{\mathcal{L}, \varphi, \psi}(s)$ being the same. We start with the same decomposition as in (7.10)-(7.11), namely

$$
\begin{aligned}
A_{\mathcal{M}, \varphi, \psi}(s) & =\sum_{l=0}^{\min \left\{k_{1}, k_{2}\right\}} A_{\mathcal{M}, \varphi, \psi}^{(l)}(s), \quad \text { with } \\
A_{\mathcal{M}, \varphi, \psi}^{(l)}(s) & =\int_{1}^{\infty} \chi_{0}(t) t^{-s} \mathcal{C}_{\varphi, \mathbf{T}_{-\tilde{x}}^{*}(\psi)}^{l}\left(t, \beta_{0}\right)|d t| \\
& =\int_{1}^{\infty} \chi_{0}(t) t^{-s} \frac{t^{l}}{l!} \sum_{\xi \in \mathbb{Z}^{d}} \int_{\mathbb{S}^{d-1}} e^{i t\left(\xi-\beta_{0}\right) \cdot \theta} e^{i \xi \cdot \tilde{x}(\theta)} B_{\tilde{x}, \xi}^{\left(k_{2}, l\right)}(\varphi, \psi)(\theta) \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta,|d \theta|)|d t|,
\end{aligned}
$$

which is an entire function as $\chi_{0}$ is compactly supported in $\mathbb{R}$. We also have the rough bound

$$
\left|A_{\mathcal{M}, \varphi, \psi}^{(l)}(s)\right| \leq C_{l} \int_{1}^{\infty}\left|\chi_{0}(t)\right| t^{-\operatorname{Re}(s)+l} \sum_{\xi \in \mathbb{Z}^{d}} \int_{\mathbb{S}^{d-1}}\left|B_{\tilde{x}, \xi}^{\left(k_{2}, l\right)}(\varphi, \psi)(\theta)\right| \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta,|d \theta|)|d t|
$$

The conclusion of the proposition follows

$$
\left|A_{\mathcal{M}, \varphi, \psi}^{(l)}(s)\right| \leq C \frac{T_{1}^{-\operatorname{Re}(s)+l+1}+1}{\langle\operatorname{Re}(s)\rangle} \sum_{\xi \in \mathbb{Z}^{d}}\langle\xi\rangle^{N}\left\|\pi_{\xi}^{\left(k_{1}\right)}(\varphi)\right\|_{H^{\sigma}\left(\mathbb{S}^{d-1}\right)}\langle\xi\rangle^{-N}\left\|\pi_{-\xi}^{\left(k_{2}\right)}(\psi)\right\|_{H^{-\sigma}\left(\mathbb{S}^{d-1}\right)}
$$

where we have used (3.22), and the Cauchy-Schwarz inequality.

## 8. Counting orthogeodesics

Now that we have given a precise description of the analytical properties of the geodesic vector field, we are in position to derive, essentially as corollaries of this sharp analysis, the expected properties of generalized Epstein zeta functions and Poincaré series, as well as some asymptotics of counting functions. We follow the strategy of [DR21, §4]. Before that, we begin by introducing a few conventions on convex sets of $\mathbb{R}^{d}$ in $\S 8.1$. Then, we introduce the notion of admissible manifolds of $\mathbb{T}^{d}$ and describe their geometric properties and their corresponding zeta functions in $\S 8.2$ and $\S 8.3$. In $\S 8.4$, following [DR21, $\S 4$ ], we define current of integration on their normal bundles and we establish the connection between our zeta type functions and the analytical quantities appearing in the previous sections. Finally, in $\S 8.5$ to $\S 8.8$, we prove Theorems 1.2, 1.4, 1.6 and 1.7 from the introduction as well as the asymptotic formula (1.1).
8.1. Normal bundles to convex sets. Let $K$ be a compact and convex subset of $\mathbb{R}^{d}$ with smooth boundary $\partial K$. As for the case of $\mathbb{S}^{d-1}$ discussed in $\S 3.3$, the boundary $\partial K$ of a smooth convex body $K$ is naturally oriented by the outward normal. We define the unit normal bundle to $\partial K$ as

$$
N(\partial K):=\left\{(x, \theta) \in \partial K \times \mathbb{S}^{d-1}: \forall v \in T_{x} \partial K, \theta \cdot v=0\right\}
$$

Except when $K$ is reduced to a point, this submanifold of $\mathbb{R}^{d} \times \mathbb{S}^{d-1}$ has two connected components and, in that case, we introduce the direct normal bundle to $K$ as

$$
N_{+}(K):=\{(x, \theta) \in N(\partial K): \theta \text { is pointing outward } K\}
$$

and the indirect normal bundle to $K$ as $N_{-}(K):=N(\partial K) \backslash N_{+}(K)$. In the case where $K$ is reduced to a point, we set $N_{+}(K)=N(\partial K)=N_{-}(K)$.

Remark 8.1. Recall that the shape operator of the smooth hypersurface $\partial K$ is the map

$$
S(x): v \in T_{x} \partial K \mapsto \nabla_{v} \theta \in T_{x} \partial K
$$

where $x \in \partial K \mapsto \theta(x) \in N_{+, x}(\partial K) \subset \mathbb{S}^{d-1}$ and where $\nabla$ is the (standard) covariant derivative in $\mathbb{R}^{d}$ [Lee09, §4.2]. In particular, $S(x)$ is the selfadjoint map associated with the second fundamental form of $\Sigma$ and it is invertible if and only if $\partial K$ has nonvanishing Gauss curvature [Lee09, Def. 4.24]. If $K$ is a stricly convex body (not reduced to a point), then $\partial K$ has all its sectional curvatures [Lee09, p.557] positive by definition (and thus nonvanishing Gaussian curvature). This is equivalent to saying that all the eigenvalues of the shape operator are non zero and have the same sign thanks to the Gauss curvature equation [Lee09, Eq. 4.10, p. 172].

If we suppose that $K$ is strictly convex, then the Gauss map

$$
\begin{equation*}
G:(x, \theta) \in N_{+}(K) \mapsto \theta \in \mathbb{S}^{d-1} \tag{8.1}
\end{equation*}
$$

is a diffeomorphism and there exists a smooth map $x_{K}: \mathbb{S}^{d-1} \rightarrow \mathbb{R}^{d}$ such that $G^{-1}(\theta)=\left(x_{K}(\theta), \theta\right)$. The map $x_{K}$ is the inverse Gauss map. Note that this remains true when $K=\left\{x_{0}\right\}$ by letting $x_{K}(\theta)=x_{0}$. In both cases, it is natural to say that we can parametrize the convex set by the normal.
8.2. Admissible submanifolds. Recall that we denote by $\mathfrak{p}: \mathbb{R}^{d} \rightarrow \mathbb{T}^{d}$ the map that associates to a point $x \in \mathbb{R}^{d}$ its equivalence class $[x] \in \mathbb{T}^{d}$. In the following, we will need the following admissibility property:

Definition 8.2. We say that $\Sigma \subset \mathbb{T}^{d}$ is admissible if there exists a strictly convex and compact subset $K \subset \mathbb{R}^{d}$ with smooth boundary such that

$$
\mathfrak{p}(\partial K)=\Sigma
$$

where $\partial K=K \backslash \stackrel{\circ}{K}$.
This definition includes the case where $\Sigma$ is reduced to a point. We also observe that the map $\mathfrak{p}: \partial K \rightarrow \mathbb{T}^{d}$ is a smooth immersion but it is not necessarily injective, i.e. $\Sigma$ may have selfintersection points. Using the inverse of the Gauss map (8.1), one can then define the unit normal bundle to $\Sigma$ as

$$
N(\Sigma):=\left\{\left(\tilde{x}(\theta):=\mathfrak{p} \circ x_{K}(\theta), \pm \theta\right): \theta \in \mathbb{S}^{d-1}\right\}
$$

As above, one can also introduce the direct normal bundle to $\Sigma$ :

$$
\begin{equation*}
N_{+}(\Sigma):=\left\{\left(\tilde{x}(\theta):=\mathfrak{p} \circ x_{K}(\theta), \theta\right): \theta \in \mathbb{S}^{d-1}\right\} \tag{8.2}
\end{equation*}
$$

and the indirect normal bundle

$$
N_{-}(\Sigma):=\left\{\left(\tilde{x}(\theta):=\mathfrak{p} \circ x_{K}(\theta),-\theta\right): \theta \in \mathbb{S}^{d-1}\right\}
$$

Even if $\Sigma$ is not a proper submanifold (as it may have selfintersection points), $N(\Sigma)$ and $N_{ \pm}(\Sigma)$ are smooth, compact and embedded submanifolds of $\mathbb{T}^{d} \times \mathbb{S}^{d-1}$. Using the conventions of $\S 5.3 .1$, one has

Lemma 8.3. Let $\Sigma \subset \mathbb{T}^{d}$ be admissible. Then, for every $(x, \theta)=(\tilde{x}(\theta), \theta) \in N_{ \pm}(\Sigma)$,

$$
\begin{align*}
& T_{\tilde{x}(\theta), \theta} N_{+}(\Sigma)=\left\{(D \tilde{x}(\theta) v, v): v \in \mathcal{V}_{\tilde{x}(\theta), \theta}\right\} \subset \mathbb{R} V(\tilde{x}(\theta), \theta) \oplus \mathcal{H}_{\tilde{x}(\theta), \theta} \oplus \mathcal{V}_{\tilde{x}(\theta), \theta}  \tag{8.3}\\
& T_{x, \theta} N_{ \pm}(\Sigma) \subset \mathcal{H}_{x, \theta} \oplus \mathcal{V}_{x, \theta}  \tag{8.4}\\
& T_{x, \theta} S \mathbb{T}^{d}=\mathbb{R} V(x, \theta) \oplus \mathcal{H}_{x, \theta} \oplus T_{x, \theta} N_{ \pm}(\Sigma) \tag{8.5}
\end{align*}
$$

In the terminology of symplectic geometry, (8.4) says that $N_{ \pm}(\Sigma)$ is a Legendrian submanifold as its tangent space lies in the kernel of the Liouville contact form. Property (8.5) is a transversality property, see Figure 4. It says that our unit normal bundle is never tangent to the horizontal bundle inside $S \mathbb{T}^{d}$. Recalling Remark 5.6 , the horizontal bundle coincides with the stable and unstable bundles in the case of flat tori. Hence, Property (8.5) agrees with the transversality assumption appearing in Margulis' works on Anosov flows [Mar04, Ch. 7].

Proof of Lemma 8.3. We start proving (8.4) and only discuss the case of $N_{+}(\Sigma)$ (the other case can be handled similarly). We recall that $N_{+}(\Sigma)$ is defined in (8.2). In particular, the tangent set to a point $(\tilde{x}(\theta), \theta)$ is given by (8.3). Thus, in order to prove (8.4), we need to check that $D \tilde{x}(\theta) v \perp V(\tilde{x}(\theta), \theta)$ for every $v \in \mathcal{V}_{\tilde{x}(\theta), \theta}$. To see this, we only need to discuss the case where $D \tilde{x}(\theta) v \neq 0$. By construction, this means that $D x_{K}(\theta) v \neq 0$. By definition, such a vector is an element in $T_{x_{K}(\theta)} \partial K$ and thus orthogonal to $\theta \cdot \partial_{x}$ which is the outward normal to $\partial K$ at $x_{K}(\theta)$. This implies that $D \tilde{x}(\theta) v$ is orthogonal to $V(\tilde{x}(\theta), \theta)$, hence the conclusion (8.4).

Finally, using the decomposition of the tangent space (8.3) one more time, these Legendrian submanifolds verify the transversality property (8.5).
8.3. Epstein zeta functions and Poincaré series for admissible submanifolds. Let now $\Sigma_{1}$ and $\Sigma_{2}$ be two admissible subsets of $\mathbb{T}^{d}$ and let $\sigma_{1}$ and $\sigma_{2}$ be two elements in $\{ \pm\}$. Our goal in the present section is to describe the set of times $t \in \mathbb{R}_{+}$such that $N_{\sigma_{1}}\left(\Sigma_{1}\right) \cap e^{t V}\left(N_{\sigma_{2}}\left(\Sigma_{2}\right)\right) \neq \emptyset$. To this aim, we define, for $t>0$,

$$
\begin{equation*}
\mathcal{E}_{t}\left(\Sigma_{1}, \Sigma_{2}\right):=N_{\sigma_{1}}\left(\Sigma_{1}\right) \cap e^{t V}\left(N_{\sigma_{2}}\left(\Sigma_{2}\right)\right) \subset S \mathbb{T}^{d} \tag{8.6}
\end{equation*}
$$

Note that the orientations $\sigma_{i}$ are implicit in this notation.


Figure 4. Tangent space to $N(\Sigma)$.
8.3.1. A priori bounds on the number of intersection points. The first basic statement concerns finiteness of $\mathcal{E}_{t}\left(\Sigma_{1}, \Sigma_{2}\right)$ together with the set of times $t$ for which $\mathcal{E}_{t}\left(\Sigma_{1}, \Sigma_{2}\right)$ is nonempty.
Lemma 8.4. There exists some $T_{0}>0$ such that, for every $t \geq T_{0}, \mathcal{E}_{t}\left(\Sigma_{1}, \Sigma_{2}\right)$ is a (possibly empty) finite set. Moreover, setting

$$
m_{\Sigma_{1}, \Sigma_{2}}(t):=\sharp \mathcal{E}_{t}\left(\Sigma_{1}, \Sigma_{2}\right)<\infty, \quad t \geq T_{0},
$$

for any $[a, b] \subset\left[T_{0},+\infty\right)$,

$$
\left\{t \in[a, b]: \mathcal{E}_{t}\left(\Sigma_{1}, \Sigma_{2}\right) \neq \emptyset\right\}=\left\{t \in[a, b]: m_{\Sigma_{1}, \Sigma_{2}}(t) \neq 0\right\}
$$

is as well a finite set.
Note that Lemma 1.1 is then a reformulation of Lemma 8.4. The above Lemma means that after some time $T_{0}$, all possible intersections are transverse and thus our counting problem is well-posed. We can easily visualize this property as follows. When pushing a convex hypersurface $\partial K_{1}$ by the geodesic flow, the reader has to imagine that, after some time $T_{0}$, it will have all its sectional curvatures (in the cover $\mathbb{R}^{d}$ it behaves more and more like a flat hypersurface) strictly less than the sectional curvatures of $\partial K_{2}$. This implies that the intersections occuring in $S \mathbb{T}^{d}$ of the corresponding normal bundles will become transverse right after $T_{0}$.

Proof of Lemma 8.4. Given $t_{0} \in \mathbb{R}_{+}$, one can always find some $\epsilon>0$ such that

$$
\bigcup_{t \in\left(t_{0}-\epsilon, t_{0}+\epsilon\right)} e^{t V}\left(N_{\sigma_{2}}\left(\Sigma_{2}\right)\right)
$$

is a smooth submanifold (with boundary) of dimension $d$ inside $S \mathbb{T}^{d}$. Moreover, thanks to (8.5) and to (5.5), we know that, for $t_{0}$ large enough, one can find $\epsilon>0$ such that, for every $(x, \theta) \in$ $N_{\sigma_{1}}\left(\Sigma_{1}\right) \cap \cup_{t \in\left(t_{0}-\epsilon, t_{0}+\epsilon\right)} e^{t V}\left(N_{\sigma_{2}}\left(\Sigma_{2}\right)\right)$,

$$
\begin{equation*}
T_{x, \theta} S \mathbb{T}^{d}=T_{x, \theta} N_{\sigma_{1}}\left(\Sigma_{1}\right) \oplus T_{x, \theta}\left(\cup_{t \in\left(t_{0}-\epsilon, t_{0}+\epsilon\right)} e^{t V}\left(N_{\sigma_{2}}\left(\Sigma_{2}\right)\right)\right) \tag{8.7}
\end{equation*}
$$

In other words, the two submanifolds are transversal and, by compactness, they intersect at only finitely many points. Note that the transversal intersection implies that the boundary of $\cup_{t \in\left(t_{0}-\epsilon, t_{0}+\epsilon\right)} e^{t V}\left(N_{\sigma_{2}}\left(\Sigma_{2}\right)\right)$ does not meet $N_{\sigma_{1}}\left(\Sigma_{1}\right)$.

We now provide with an a priori polynomial upper bound on $m_{\Sigma_{1}, \Sigma_{2}}(t)$. This is essential to ensure our Epstein functions and Poincaré series have non empty convergence domains.

Lemma 8.5. Let $\Sigma_{1}$ and $\Sigma_{2}$ be two admissible subsets of $\mathbb{T}^{d}$. Then, for $T_{0}$ as in Lemma 8.4, there is $C_{0}>0$ such that, for every $T \geq T_{0}$,

$$
\sum_{T \leq t \leq T+1} m_{\Sigma_{1}, \Sigma_{2}}(t) \leq C_{0} T^{d-1}
$$

In particular, as $T \rightarrow+\infty$,

$$
\sum_{T_{0} \leq t \leq T} m_{\Sigma_{1}, \Sigma_{2}}(t)=\mathcal{O}\left(T^{d}\right)
$$

Proof. In order to obtain such an upper bound, it is more convenient to lift the problem to $\mathbb{R}^{d}$ and to recall that the lift of $\Sigma_{j}$ is by definition the smooth boundary of a compact and strictly convex set. As a consequence, we have for any $t>0$

$$
m_{\Sigma_{1}, \Sigma_{2}}(t)=\sharp \mathcal{E}_{t}\left(\Sigma_{1}, \Sigma_{2}\right)=\sharp \mathcal{E}_{t}\left(\partial K_{1}, \partial K_{2}\right),
$$

where

$$
\mathcal{E}_{t}\left(\partial K_{1}, \partial K_{2}\right):=\left\{(x, \theta) \in N_{\sigma_{1}}\left(\partial K_{1}+2 \pi \mathbb{Z}^{d}\right):(x-t \theta, \theta) \in N_{\sigma_{2}}\left(\partial K_{2}\right)\right\} \subset S \mathbb{R}^{d}
$$

Recalling that, when lifting the problem to $\mathbb{R}^{d}$,

$$
N_{ \pm}\left(\partial K_{j}\right):=\left\{\left(\tilde{x}_{j}(\theta), \sigma_{j} \theta\right): \theta \in \mathbb{S}^{d-1}\right\}=\left\{\left(\tilde{x}_{j}\left(\sigma_{j} \theta\right), \theta\right): \theta \in \mathbb{S}^{d-1}\right\}
$$

we notice that

$$
(x, \theta) \in \mathcal{E}_{t}\left(\partial K_{1}, \partial K_{2}\right) \Longrightarrow t \theta+\tilde{x}_{1}\left(\sigma_{1} \theta\right)-\tilde{x}_{2}\left(\sigma_{2} \theta\right) \in 2 \pi \mathbb{Z}^{d}
$$

whence

$$
\sharp \mathcal{E}_{t}\left(\partial K_{1}, \partial K_{2}\right)=\sharp\left\{\theta \in \mathbb{S}^{d-1}: t\left(\theta+\frac{\tilde{x}_{1}\left(\sigma_{1} \theta\right)-\tilde{x}_{2}\left(\sigma_{2} \theta\right)}{t}\right) \in 2 \pi \mathbb{Z}^{d}\right\} .
$$

For $t \geq 1$, we have $\left|\frac{\tilde{x}_{1}\left(\sigma_{1} \theta\right)-\tilde{x}_{2}\left(\sigma_{2} \theta\right)}{t}\right| \leq C_{0}$ so that
$\sum_{T \leq t \leq T+1} \sharp \mathcal{E}_{t}\left(\partial K_{1}, \partial K_{2}\right) \leq \sharp\left(2 \pi \mathbb{Z}^{d} \cap \mathcal{C}_{T}\right) \leq C \operatorname{Vol}_{\mathbb{R}^{d}}\left(\mathcal{C}_{T}\right), \quad$ with $\quad \mathcal{C}_{T}=\bar{B}\left(0, T+1+C_{0}\right) \backslash B\left(0, T-C_{0}\right)$.
We finally deduce that, for $T_{0}>0$ as in Lemma 8.4,

$$
\sum_{T \leq t \leq T+1} m_{\Sigma_{1}, \Sigma_{2}}(t)=\sum_{T \leq t \leq T+1} \sharp \mathcal{E}_{t}\left(\partial K_{1}, \partial K_{2}\right) \leq C T^{d-1}, \quad T \geq T_{0},
$$

which concludes the proof of the lemma.
8.3.2. Generalized Epstein zeta functions and Poincaré series. We fix $T_{0}>0$ large enough to ensure that Lemma 8.4 (and thus 8.5) apply. We also fix $\beta=\beta_{0}+d f$ with $\beta_{0} \in H^{1}\left(\mathbb{T}^{d}, \mathbb{R}\right)$. In particular, for such a $T_{0}$ and such a $\beta$, we can define, for $\operatorname{Re}(s)>d$, the generalized Epstein zeta function as

$$
\begin{equation*}
\zeta_{\beta}\left(K_{2}, K_{1}, s\right):=\sum_{t>T_{0}: \mathcal{E}_{t}\left(\Sigma_{1}, \Sigma_{2}\right) \neq \emptyset} t^{-s}\left(\sum_{(x, \theta) \in \mathcal{E}_{t}\left(\Sigma_{1}, \Sigma_{2}\right)} e^{-i \int_{-t}^{0} \beta(V)(x+s \theta, \theta)|d s|}\right) \tag{8.8}
\end{equation*}
$$

where $\mathcal{E}_{t}\left(\Sigma_{1}, \Sigma_{2}\right)$ is defined in (8.6) and is a finite set according to Lemma 8.4. Lemma 8.5 ensures that this defines a holomorphic function in $\{\operatorname{Re}(s)>d\}$.

Similarly, for $\operatorname{Re}(s)>0$, we define the generalized Poincaré series as

$$
\begin{equation*}
\mathcal{Z}_{\beta}\left(K_{2}, K_{1}, s\right):=\sum_{t>T_{0}: \mathcal{E}_{t}\left(\Sigma_{1}, \Sigma_{2}\right) \neq \emptyset} e^{-s t}\left(\sum_{(x, \theta) \in \mathcal{E}_{t}\left(\Sigma_{1}, \Sigma_{2}\right)} e^{-i \int_{-t}^{0} \beta(V)(x+s \theta, \theta)|d s|}\right) \tag{8.9}
\end{equation*}
$$

Again Lemma 8.5 shows that this defines a holomorphic function in $\{\operatorname{Re}(s)>0\}$.
Remark 8.6. Except for the role of $K_{1}$ and $K_{2}$ that are reversed compared with the introduction, these two functions are exactly the two series defined in (1.2) and (1.4) in the introduction.
8.4. Currents of integration on admissible subsets. From this point on, we shall always suppose that $\Sigma$ is admissible in the sense of Definition 8.2. We can choose to orient the submanifold $N_{ \pm}(\Sigma)$ with the volume form $\operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta, d \theta)$. Once we have fixed an orientation on $N_{ \pm}(\Sigma)$, we can define the current of integration $\left[N_{ \pm}(\Sigma)\right.$ ] on this $(d-1)$-submanifold [Sch66, p.326-327], i.e.

$$
\forall \psi \in \Omega^{d-1}\left(S \mathbb{T}^{d}\right), \quad\left\langle\left[N_{ \pm}(\Sigma)\right], \psi\right\rangle:=\int_{N_{ \pm}(\Sigma)} \psi
$$

This is the de Rham current of integration on the normal bundle associated to our convex set. Its expression in the Gauss coordinates (8.2) is given by (3.6) thanks to our choice of orientation of $N_{ \pm}(\Sigma)$. More precisely, one has

$$
\left[N_{+}(\Sigma)\right](x, \theta, d x, d \theta)=\delta_{0}(x-\tilde{x}(\theta)) \bigwedge_{i=1}^{d} d\left(x_{i}-\tilde{x}_{i}(\theta)\right)
$$

and

$$
\left[N_{-}(\Sigma)\right](x, \theta, d x, d \theta)=\delta_{0}(x-\tilde{x}(-\theta)) \bigwedge_{i=1}^{d} d\left(x_{i}-\tilde{x}_{i}(-\theta)\right)
$$

In any case, this is a current of degree $d$, i.e. an element of $\mathcal{D}^{\prime d}\left(S \mathbb{T}^{d}\right)$. Finally, we recall from (3.5) that, in Fourier series, one has the following representation:

$$
\begin{equation*}
\left[N_{ \pm}(\Sigma)\right](x, d x, \theta, d \theta)=\frac{1}{(2 \pi)^{\frac{d}{2}}} \sum_{\xi \in \mathbb{Z}^{d}} \mathfrak{e}_{\xi}(x-\tilde{x}( \pm \theta)) \bigwedge_{i=1}^{d} d\left(x_{i}-\tilde{x}_{i}( \pm \theta)\right) \tag{8.10}
\end{equation*}
$$

Remark 8.7. In the case where $\Sigma$ is reduced to a point $x_{0}$, one has in fact the simple expression:

$$
\left[S_{x_{0}} \mathbb{T}^{d}\right]=\left[N_{ \pm}\left(x_{0}\right)\right]=\delta_{0}\left(x-x_{0}\right) d x_{1} \wedge \ldots \wedge d x_{d}=\delta_{2 \pi \mathbb{Z}^{d}}\left(x-x_{0}, d x\right)
$$

8.4.1. Wavefront sets of the currents of integration. The following lemma studies the wavefront set of this current in view of pairing two such objects.

Lemma 8.8. For any admissible subset $\Sigma$ of $\mathbb{T}^{d}$, we have
(8.11)
$\mathrm{WF}\left(\left[N_{ \pm}(\Sigma)\right]\right) \cap T_{(x, \theta)}^{*} S \mathbb{T}^{d}=E_{0}^{*}(\tilde{x}( \pm \theta), \theta) \oplus\left\{\left(0, \xi, \mp(d \tilde{x}( \pm \theta))^{T} \xi\right): \xi \in \mathcal{H}^{*}\right\} \subset\left(E_{0}^{*} \oplus \mathcal{H}^{*} \oplus \mathcal{V}^{*}\right)(\tilde{x}( \pm \theta), \theta)$.
Moreover, for any conical neighborhood $\Gamma$ of $E_{0}^{*} \oplus \mathcal{V}^{*}$, there exists $T_{0}>0$ such that, for every $T \geq T_{0}$, the wavefront set of $e^{-T V *}\left[N_{ \pm}(\Sigma)\right]=\left[e^{T V}\left(N_{ \pm}(\Sigma)\right)\right]$ satisfies

$$
\begin{equation*}
\mathrm{WF}\left(e^{-T V *}\left[N_{ \pm}(\Sigma)\right]\right) \subset\left\{(x, \theta ; \xi) \in T^{*} S \mathbb{T}^{d}: e^{-T V}(x, \theta) \in N_{ \pm}(\Sigma), \xi \in \Gamma(x, \theta)\right\} \tag{8.12}
\end{equation*}
$$

In particular, if $\Sigma_{1}$ and $\Sigma_{2}$ are two admissible subsets and if $\sigma_{1}, \sigma_{2} \in\{ \pm\}$, then one can find $T_{0}>0$ such that, for every $T \geq T_{0}$,

$$
\begin{equation*}
\mathrm{WF}\left(\left[N_{\sigma_{1}}\left(\Sigma_{1}\right)\right]\right) \cap \mathrm{WF}\left(e^{-T V *}\left[N_{\sigma_{2}}\left(\Sigma_{2}\right)\right]\right) \subset E_{0}^{*} \tag{8.13}
\end{equation*}
$$

Proof. The wavefront set of the current $\left[N_{ \pm}(\Sigma)\right]$ is given according to [Hör03, Th. 8.1.5] ${ }^{15}$ by the conormal bundle to $N_{ \pm}(\Sigma)$, namely

$$
\mathcal{N}^{*}\left(N_{ \pm}(\Sigma)\right):=\left\{(x, \theta ; \xi) \in T^{*} S \mathbb{T}^{d} \backslash \underline{0}:(x, \theta) \in N_{ \pm}(\Sigma), \forall v \in T_{x, \theta} N_{ \pm}(\Sigma), \xi(v)=0\right\}
$$

In particular, thanks to (8.4), the fiber $\mathcal{N}_{(x, \theta)}^{*}\left(N_{ \pm}(\Sigma)\right) \subset T_{(x, \theta)}^{*} S \mathbb{T}^{d}$ over $(x ; \theta)$ always contains the annihilator $E_{0}^{*}(x, \theta)$ of $\mathcal{H} \oplus \mathcal{V}(x, \theta)$. Using the description of $T_{x, \theta} N_{+}(\Sigma)$ in (8.3) in the coordinates (8.2), this wavefront set can in fact be identified as

$$
\mathcal{N}_{(x, \theta)}^{*}\left(N_{ \pm}(\Sigma)\right)=E_{0}^{*}(\tilde{x}( \pm \theta), \theta) \oplus\left\{\left(0, \xi, \mp(d \tilde{x}( \pm \theta))^{T} \xi\right): \xi \in \mathcal{H}^{*}\right\} \subset\left(E_{0}^{*} \oplus \mathcal{H}^{*} \oplus \mathcal{V}^{*}\right)(\tilde{x}( \pm \theta), \theta)
$$

whence the first statement (8.11). Hence, thanks to (5.6) and to [Hör03, Th. 8.2.4] (see also [BDH16, Prop. 5.1]), we deduce the second statement (8.12). The last statement (8.13) follows from the first by choosing $\Gamma$ some sufficiently small conical neighborhood of $E_{0}^{*} \oplus \mathcal{V}^{*}$ so that $\left(\mathrm{WF}\left(\left[N_{\sigma_{1}}\left(\Sigma_{1}\right)\right]\right) \cap \Gamma\right) \subset$ $E_{0}^{*}$.

[^13]8.4.2. Representation of truncated series using currents. Our goal is to use our fine analysis of the geodesic vector field to study the continuation of these series beyond their natural halfplane of definition. As in [DR21, Prop. 4.10], one starts with the following result, relating the above discrete sums on intersection points between two submanifolds with the geodesic flow acting on currents.

Lemma 8.9. Let $\Sigma_{1}$ and $\Sigma_{2}$ be two admissible subsets of $\mathbb{T}^{d}$ and let $\sigma_{1}$ and $\sigma_{2}$ be elements in $\{ \pm\}$. Let $\beta=\beta_{0}+d f$ be a closed one-form with $\beta_{0} \in H^{1}\left(\mathbb{T}^{d}, \mathbb{R}\right)$ and $f \in \mathcal{C}^{\infty}\left(\mathbb{T}^{d}, \mathbb{R}\right)$. There exists $T_{0}>0$ large enough such that, for every $T \geq T_{0}$, one can find $t_{0}>0$ such that, for every $\chi \in \mathcal{C}_{c}^{\infty}\left(\left(T-t_{0},+\infty\right)\right)$,

$$
I_{T}(\chi):=(-1)^{d-1} \int_{S \mathbb{T}^{d}}\left[N_{\sigma_{1}}\left(\Sigma_{1}\right)\right] \wedge \int_{\mathbb{R}} \chi(t) e^{-t \mathbf{V}_{\beta}} \iota_{V}\left(\left[N_{\sigma_{2}}\left(\Sigma_{2}\right)\right]\right)|d t|
$$

is well defined and is equal to

$$
\sum_{t>T-t_{0}: \mathcal{E}_{t}\left(\Sigma_{1}, \Sigma_{2}\right) \neq \emptyset} \chi(t)\left(\sum_{(x, \theta) \in \mathcal{E}_{t}\left(\Sigma_{1}, \Sigma_{2}\right)} \epsilon_{t}(x) e^{-i \int_{-t}^{0} \beta(V)(x+\tau \theta, \theta)|d \tau|}\right)
$$

where $\epsilon_{t}(x)=1$ if

$$
T_{(x, \theta)} N_{\sigma_{1}}\left(\Sigma_{1}\right) \oplus \mathbb{R} V(x, \theta) \oplus D\left(e^{t V}\right)\left(e^{-t V}(x, \theta)\right)\left(T_{e^{-t V}(x, \theta)} N_{\sigma_{2}}\left(\Sigma_{2}\right)\right),
$$

has the same orientation as $S \mathbb{T}^{d}$ and $\epsilon_{t}(x)=-1$ otherwise.
This result follows from [DR21, Lemma 4.11] together with Lemma 8.8. Here, $\left[N_{ \pm}\left(\Sigma_{1}\right)\right]$ is an element in $\mathcal{D}^{\prime d}\left(S \mathbb{T}^{d}\right)$ and $\int_{\mathbb{R}} \chi(t) e^{-t V} \iota_{V}\left(\left[N_{+}\left(\Sigma_{2}\right)\right]\right)|d t|$ is an element in $\mathcal{D}^{\prime d-1}\left(S \mathbb{T}^{d}\right)$. The key point in the argument of [DR21] is that the wavefront sets of these two currents are disjoint so that we can take their wedge product. Here, the wavefront set of $\left[N_{\sigma_{1}}\left(\Sigma_{1}\right)\right]$ is given by (8.11) while the wavefront set of $\int_{\mathbb{R}} \chi(t) e^{-t V} \iota_{V}\left(\left[N_{\sigma_{2}}\left(\Sigma_{2}\right)\right]\right)|d t|$ is contained in a small conical neighborhood of $\mathcal{V}^{*}$ thanks to Lemma 8.8 and to the integration over time. See [DR21, Lemma 4.11] for more details. We would like to emphasize that the fact that this lemma states that the dynamical correlator

$$
I_{T}: t \mapsto(-1)^{d-1} \int_{S \mathbb{T}^{d}}\left[N_{\sigma_{1}}\left(\Sigma_{1}\right)\right] \wedge e^{-t \mathbf{V}_{\beta}} \iota_{V}\left(\left[N_{\sigma_{2}}\left(\Sigma_{2}\right)\right]\right)
$$

is in fact a distribution of the variable $t$ which writes as a weighted sum of $\delta$. The reader should think of the distribution $I_{T}$ as some kind of weighted counting measure and the Laplace transform of $I_{T}$ is nothing but the Poincaré series.

In order to make the connection with the above series, we need to clarify the values of $\epsilon_{t}(x)$ in our case:

Lemma 8.10. There exists $T_{0}>0$ such that, for every $t \geq T_{0}, \epsilon_{t}(x)=1$.
Proof. Recall that we oriented $N_{ \pm}\left(\Sigma_{1}\right)$ with the $d-1$-form $\operatorname{Vol}_{\mathbb{S}^{d}-1}(\theta, d \theta)$, or equivalently with the polyvector $\left(e_{1}(\theta) \cdot \partial_{\theta}\right) \wedge \ldots \wedge\left(e_{d}(\theta) \cdot \partial_{\theta}\right)$ where $\left(\theta, e_{1}(\theta), \ldots, e_{d}(\theta)\right)$ is a direct orthonormal basis of $\mathbb{R}^{d}$. The same holds true for $\Sigma_{2}$ but we need to take into account the action of the tangent map as given by (5.5) which transforms this polyvector into

$$
\left(e_{1}(\theta) \cdot \partial_{\theta}+t e_{1}(\theta) \cdot \partial_{x}\right) \wedge \ldots \wedge\left(e_{d}(\theta) \cdot \partial_{\theta}+t e_{d}(\theta) \cdot \partial_{x}\right)
$$

Finally, $\mathbb{R} V(x)$ is oriented through the vector $\theta \cdot \partial_{x}$ and it yields the following orientation

$$
t^{d-1}\left(e_{1}(\theta) \cdot \partial_{\theta}\right) \wedge \ldots \wedge\left(e_{d}(\theta) \cdot \partial_{\theta}\right) \wedge \theta \cdot \partial_{x} \wedge\left(e_{1}(\theta) \cdot \partial_{x}\right) \wedge \ldots \wedge\left(e_{d}(\theta) \cdot \partial_{x}\right)
$$

which is the same as the orientation on $S \mathbb{T}^{d}$ up to the factor $(-1)^{d(d-1)}=1$.
Letting $\tilde{x}_{j}^{ \pm}(\theta)=\tilde{x}_{j}( \pm \theta)$, we derive the following corollary.

Corollary 8.11. There is $T_{0}>0$ and $t_{0} \in\left(0, T_{0}\right)$ such that for every $\chi \in \mathcal{C}_{c}^{\infty}\left(\left(T_{0}-t_{0},+\infty\right)\right)$ with $\chi=1$ on $\left[T_{0},+\infty\right)$, we have

$$
\begin{align*}
& \sum_{t>T_{0}-t_{0}} \chi(t)\left(\sum_{(x, \theta) \in \mathcal{E}_{t}\left(\Sigma_{1}, \Sigma_{2}\right)} e^{-i \int_{-t}^{0} \beta(V)(x+\tau \theta, \theta)|d \tau|}\right)  \tag{8.14}\\
& =(-1)^{d-1} \int_{S \mathbb{T}^{d}} e^{i\left(f\left(\tilde{x}_{2}^{\sigma_{2}}\right)-f\left(\tilde{x}_{1}^{\sigma_{1}}\right)\right)} \delta_{2 \pi \mathbb{Z}^{d}} \wedge \int_{\mathbb{R}} \chi(t)\left(e^{-t \mathbf{V}_{\beta_{0}}} \mathbf{T}_{\tilde{x}_{1}^{\sigma_{1}}-\tilde{x}_{2}^{\sigma_{2}}}^{*}\right) \iota_{V}\left(\delta_{2 \pi \mathbb{Z}^{d}}\right)|d t|,
\end{align*}
$$

where we recall that the notation $\left(\delta_{2 \pi \mathbb{Z}^{d}}\right)$ stands for a current of degree $d$.
We now recognize in the right hand-side the quantities that we studied in Sections 4 to 7 .
Proof. According to Lemma 8.10, for $T_{0}>0$ large enough and recalling (3.14), one deduces from Lemma 8.9 that, for every $\chi \in \mathcal{C}_{c}^{\infty}\left(\left(T_{0}-t_{0},+\infty\right)\right)$,

$$
\begin{align*}
& \sum_{t>T_{0}-t_{0}} \chi(t)\left(\sum_{(x, \theta) \in \mathcal{E}_{t}\left(\Sigma_{1}, \Sigma_{2}\right)} e^{-i \int_{-t}^{0} \beta(V)(x+\tau \theta, \theta)|d \tau|}\right)  \tag{8.15}\\
&=(-1)^{d-1} \int_{S \mathbb{T}^{d}} e^{-i f}\left[N_{\sigma_{1}}\left(\Sigma_{1}\right)\right]
\end{align*} \wedge \int_{\mathbb{R}} \chi(t) e^{-t \mathbf{V}_{\beta_{0}}} \iota_{V}\left(e^{i f}\left[N_{\sigma_{2}}\left(\Sigma_{2}\right)\right]\right)|d t| .
$$

Thanks to (8.10), we can write, for $j=1,2$,

$$
e^{ \pm i f}\left[N_{\sigma_{j}}\left(\Sigma_{j}\right)\right]=e^{ \pm i f(x)} \mathbf{T}_{-\tilde{x}_{j}^{\sigma_{j}}}^{*}\left(\delta_{2 \pi \mathbb{Z}^{d}}\right)=e^{ \pm i f\left(\tilde{x}_{j}^{\sigma_{j}}\right)} \mathbf{T}_{-\tilde{x}_{j}^{*}}^{*}\left(\delta_{2 \pi \mathbb{Z}^{d}}\right)
$$

Combined with (3.11) and (3.12) in Lemma 3.12, this allows to rewrite (8.15) as (8.14).
8.5. Asymptotic of the counting function. As a first application of this construction, we will refine the a priori bounds obtained in Lemma 8.5 and prove formula (1.1) from the introduction. Namely, we fix two admissible submanifolds $\Sigma_{1}, \Sigma_{2} \subset \mathbb{T}^{d}$ and $\sigma_{1}, \sigma_{2} \in\{ \pm\}$. We want to compute a precise asymptotic formula for

$$
\sum_{T_{0} \leq t \leq T} m_{\Sigma_{1}, \Sigma_{2}}(t)=\sum_{T_{0} \leq t \leq T} \sharp\left(N_{\sigma_{1}}\left(\Sigma_{1}\right) \cap e^{t V}\left(N_{\sigma_{2}}\left(\Sigma_{2}\right)\right)\right) .
$$

Theorem 8.12. Let $\Sigma_{1}, \Sigma_{2} \subset \mathbb{T}^{d}$ be two admissible submanifolds, let $\sigma_{1}, \sigma_{2} \in\{ \pm\}$. Then, there exists $T_{0}>0$ such that, as $T \rightarrow+\infty$

$$
\sum_{T_{0} \leq t \leq T} \sharp \mathcal{E}_{t}\left(\Sigma_{1}, \Sigma_{2}\right)=\frac{\pi^{\frac{d}{2}} T^{d}}{(2 \pi)^{d} \Gamma\left(\frac{d}{2}+1\right)}+\mathcal{O}\left(T^{d-1}\right) .
$$

Even if it may not be the simplest manner to prove such a result, this discussion illustrates how our current-theoretical approach to this problem can be implemented. An interesting question would be to understand how the remainder term depends on $\Sigma_{1}$ and $\Sigma_{2}$. See [vdC20, Hla50, Her62b, Ran66, CdV77] for such results in the context of dilations of convex subsets. We do not pursue this here and we rather focus on the application of this approach to zeta functions associated with our families of orthogeodesics.

Proof. First fix $T_{0}>0$ large enough so that all the above lemmas apply. In order to study this quantity, we take $\beta=0$ in (8.14) and we choose appropriate cutoff functions $\chi$ approximating the characteristic function of the interval $\left[T_{0}, T\right]$. More precisely, we fix $T>0$ (large enough) and $t_{0}>0$ (small enough). We define two smooth cutoffs functions $\chi_{T}^{ \pm} \in \mathcal{C}_{c}^{\infty}(\mathbb{R},[0,1])$ with the following properties:

- $\chi_{T}^{+}$is equal to 1 on $\left[T_{0}, T\right]$, it is compactly supported on $\left(T_{0}-t_{0}, T+t_{0}\right)$, it is nonincreasing on $\left[T, T+t_{0}\right]$.
- $\chi_{T}^{-}$is equal to 1 on $\left[T_{0}+t_{0}, T-t_{0}\right]$, it is compactly supported on $\left(T_{0}, T\right)$, it is nonincreasing on $\left[T-t_{0}, T\right]$.

With such functions at hand, one has

$$
\begin{equation*}
\sum_{t>T_{0}-t_{0}} \chi_{T}^{-}(t) m_{\Sigma_{1}, \Sigma_{2}}(t) \leq \sum_{T_{0} \leq t \leq T} m_{\Sigma_{1}, \Sigma_{2}}(t) \leq \sum_{t>T_{0}-t_{0}} \chi_{T}^{+}(t) m_{\Sigma_{1}, \Sigma_{2}}(t) \tag{8.16}
\end{equation*}
$$

Hence, thanks to (8.14), we have to study

$$
\sum_{t>T_{0}-t_{0}} \chi_{T}^{ \pm}(t) m_{\Sigma_{1}, \Sigma_{2}}(t)=(-1)^{d-1} \int_{S \mathbb{T}^{d}} \delta_{2 \pi \mathbb{Z}^{d}} \wedge \int_{\mathbb{R}} \chi_{T}^{ \pm}(t)\left(e^{\left.-t \mathbf{V}_{\mathbf{T}_{\tilde{x}_{1}^{\sigma_{1}}-\tilde{x}_{2}^{\sigma_{2}}}^{*}}\right) \iota_{V}\left(\delta_{2 \pi \mathbb{Z}^{d}}\right)|d t|, ~, ~, ~}\right.
$$

which can be analyzed using Theorem 6.4. Indeed, the cutoff functions $\chi_{T}^{ \pm}$are compactly supported which implies that they satisfy the assumption of this Theorem. We just have to pay some attention to their dependence in $T$ as $T \rightarrow+\infty$. More precisely, we need to apply this Theorem with $k_{1}=d$, $k_{2}=d-1$ and

$$
\varphi=\delta_{2 \pi \mathbb{Z}^{d}}, \quad \psi=\iota_{V}\left(\delta_{2 \pi \mathbb{Z}^{d}}\right) .
$$

We have

$$
\begin{equation*}
\varphi \in \mathcal{H}_{d, 0}^{+\infty,-\frac{d}{2}-,+\infty,-\frac{d}{2}-}:=\bigcap_{\epsilon \in(0,1]} \mathcal{H}_{d, 0}^{\frac{1}{\epsilon},-\frac{d}{2}-\epsilon, \frac{1}{\epsilon},-\frac{d}{2}-\epsilon}, \quad \text { and } \quad \psi \in \mathcal{H}_{d-1,0}^{+\infty,-\frac{d}{2}-,+\infty,-\frac{d}{2}-} \tag{8.17}
\end{equation*}
$$

Thus, we are left with analyzing the size of the different integrals involving $\chi_{T}^{ \pm}$. First, for $0 \leq l \leq$ $d-1$, one has

$$
\frac{T^{l+1}}{l+1}+\mathcal{O}(1) \leq \int_{\mathbb{R}} \chi_{T}^{+}(t) t^{l}|d t| \leq \frac{\left(T+t_{0}\right)^{l+1}}{l+1}+\mathcal{O}(1)
$$

and

$$
\frac{\left(T-t_{0}\right)^{l+1}}{l+1}+\mathcal{O}(1) \leq \int_{\mathbb{R}} \chi_{T}^{-}(t) t^{l}|d t| \leq \frac{T^{l+1}}{l+1}+\mathcal{O}(1)
$$

where the constants in the remainders are independent of $T$. Similarly, we can treat the remainder terms involving terms of the type $\left\|\left(\chi_{T, \delta}^{ \pm} t^{l}\right)^{(2 d+1)}\right\|_{L^{1}\left(\mathbb{R}_{+}\right)}=\mathcal{O}\left(T^{d-1}\right)$. Finally, the term $\left\|\chi_{T, \delta}^{ \pm} t^{l-(2 d+1)}\right\|_{L^{1}\left(\mathbb{R}_{+}\right)}$is bounded uniformly in terms of $T$. Gathering these bounds, we find that

$$
\begin{aligned}
& \int_{S \mathbb{T}^{d}} \delta_{2 \pi \mathbb{Z}^{d}} \wedge \int_{\mathbb{R}} \chi_{T}^{ \pm}(t)\left(e^{-t \mathbf{V}} \mathbf{T}_{\tilde{x}_{1}^{\sigma_{1}}-\tilde{x}_{2}^{\sigma_{2}}}^{\sigma_{2}}\right) \iota_{V}\left(\delta_{2 \pi \mathbb{Z}^{d}}\right)|d t| \\
&=\frac{T^{d}}{d!} \int_{\mathbb{S}^{d-1}} B_{\tilde{x}_{2}^{\sigma_{2}}-\tilde{x}_{1}^{\sigma_{1}}, 0}^{(d-1)}\left(\delta_{2 \pi \mathbb{Z}^{d}}, \iota_{V}\left(\delta_{2 \pi \mathbb{Z}^{d}}\right)\right) \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta, d \theta)+\mathcal{O}\left(T^{d-1}\right)
\end{aligned}
$$

Recall now that $B_{\tilde{x}_{2}^{\sigma_{2}}-\tilde{x}_{1}^{\sigma_{1}}, 0}^{(d-1, d-1)}\left(\delta_{2 \pi \mathbb{Z}^{d}}, \iota_{V}\left(\delta_{2 \pi \mathbb{Z}^{d}}\right)\right)$ is defined in (3.20) as

$$
\begin{aligned}
& B_{\tilde{x}_{2}^{\sigma_{2}}-\tilde{x}_{1}^{\sigma_{1}}, 0}^{(d-1)}\left(\delta_{2 \pi \mathbb{Z}^{d}}, \iota_{V}\left(\delta_{2 \pi \mathbb{Z}^{d}}\right)\right) \operatorname{Vol}_{S \mathbb{T}^{d}}(\theta, d x, d \theta) \\
&=(-1)^{d-1} \pi_{0}^{(d)}\left(\delta_{2 \pi \mathbb{Z}^{d}}\right) \wedge \mathbf{T}_{\tilde{x}_{1}^{\sigma_{1}}-\tilde{x}_{2}^{\sigma_{2}}} \mathbf{V}^{d-1} \pi_{0}^{(d-1)}\left(\iota_{V}\left(\delta_{2 \pi \mathbb{Z}^{d}}\right)\right) \\
&=(-1)^{d-1}(2 \pi)^{-d}(d-1)!\operatorname{Vol}_{S \mathbb{T}^{d}}(\theta, d x, d \theta)
\end{aligned}
$$

after having used (3.4)-(3.5) together with Lemma 3.11. Inserting this expression in the above calculation and recalling that $\operatorname{Vol}\left(\mathbb{S}^{d-1}\right)=\frac{2 \pi^{d / 2}}{\Gamma(d / 2)}=\frac{d \pi^{d / 2}}{\Gamma(d / 2+1)}$ concludes the proof of the theorem.
8.6. Continuation of generalized Epstein zeta functions. We now aim at proving Theorem 1.2. Using the conventions of this paragraph, this amounts to studying the meromorphic properties of the generalized Epstein zeta function defined in (8.8). As an application of Lemma 8.5, it defines a holomorphic function on $\{\operatorname{Re}(s)>d\}$ and we want to understand its possible extension beyond the threshold $\operatorname{Re}(s)>d$. To that aim, the first step is to use Lemma 8.9 to interpret $\zeta_{\Sigma_{1}, \Sigma_{2}, T_{0}}(s)$ as the Mellin transform of a correlation function of appropriate currents, and then make use of Theorem 7.4.

Lemma 8.13. There is $T_{0}^{*}>0$ such that for all $T_{0}>T_{0}^{*}$, one can find $\chi_{\infty}$ verifying assumption (7.1) with $t_{0}>0$ small enough such that
where $\widehat{\chi_{s}^{M}}\left(-i \mathbf{V}_{\beta_{0}}\right)$ was defined in (7.2).
In a more compact manner and using the conventions of Theorem 7.4 with $\tilde{x}=\tilde{x}_{2}^{\sigma_{2}}-\tilde{x}_{1}^{\sigma_{1}}$, the right hand-side of (8.18) can be rewritten as

$$
\begin{aligned}
& \mathcal{M}_{\left(e^{i\left(f\left(\tilde{x}_{2}^{\sigma_{2}}\right)-f\left(\tilde{x}_{1}^{\sigma_{1}}\right)\right)} \delta_{\left.2 \pi \mathbb{Z}^{d}, \iota_{V}\left(\delta_{2 \pi \mathbb{Z}^{d}}\right)\right)}\right.} \\
&=\int_{S \mathbb{T}^{d}} e^{i\left(f\left(\tilde{x}_{2}^{\sigma_{2}}\right)-f\left(\tilde{x}_{1}^{\sigma_{1}}\right)\right)} \delta_{2 \pi \mathbb{Z}^{d}} \wedge \widehat{\chi_{s}^{M}}\left(-i \mathbf{V}_{\beta_{0}}\right) \mathbf{T}_{\tilde{x}_{1}^{\sigma_{1}}-\tilde{x}_{2}^{\sigma_{2}} \iota_{V}\left(\delta_{2 \pi \mathbb{Z}^{d}}\right)|d t|}
\end{aligned}
$$

Proof. First, we fix a smooth nondecreasing function $\chi_{\infty}$ which is equal to 1 on $\left[T_{0}+t_{0}, \infty\right)$ and to 0 on $\left(-\infty, T_{0}\right]$ for some small enough $t_{0}>0$ to ensure that $m_{\Sigma_{1}, \Sigma_{2}}(t)=0$ for all $t \in\left(T_{0}, T_{0}+t_{0}\right]$. We also fix a smooth function $\chi \in \mathcal{C}_{c}^{\infty}((-2,2),[0,1])$ such that

$$
\forall t \in \mathbb{R}, \quad \sum_{j \in \mathbb{Z}} \chi(t+j)=1
$$

We let $\chi_{\infty, j}(t):=\chi_{\infty}(t) \chi(t+j)$. Using (8.14), this leads to the following decomposition

$$
\begin{align*}
& \quad \zeta_{\beta}\left(K_{2}, K_{1}, s\right)=\sum_{j \in \mathbb{Z}} \sum_{t>T_{0}} \chi_{\infty, j}(t) t^{-s}\left(\sum_{(x, \theta) \in \mathcal{E}_{t}\left(\Sigma_{1}, \Sigma_{2}\right)} e^{-i \int_{-t}^{0} \beta(V)(x+\tau \theta, \theta)|d \tau|}\right)  \tag{8.19}\\
& =(-1)^{d-1} \sum_{j \in \mathbb{Z}} \int_{S \mathbb{T}^{d}} e^{i\left(f\left(\tilde{x}_{2}^{\sigma_{2}}\right)-f\left(\tilde{x}_{1}^{\sigma_{1}}\right)\right)} \delta_{2 \pi \mathbb{Z}^{d}} \wedge \int_{\mathbb{R}} \chi_{\infty, j}(t) t^{-s}\left(e^{\left.-t \mathbf{V}_{\beta_{0}} \mathbf{T}_{\tilde{x}_{1}^{\sigma_{1}}-\tilde{x}_{2}^{\sigma_{2}}}\right) \iota_{V}\left(\delta_{2 \pi \mathbb{Z}^{d}}\right)|d t| .} .\right.
\end{align*}
$$

We now fix some $N$ large enough in order to apply Theorem 6.4 (with $N=M$ ) to $\tilde{x}=\tilde{x}_{2}-\tilde{x}_{1}$, to $k_{1}=d, k_{2}=d-1$, and to the currents

$$
\varphi=e^{i\left(f\left(\tilde{x}_{2}^{\sigma_{2}}\right)-f\left(\tilde{x}_{1}^{\sigma_{1}}\right)\right)} \delta_{2 \pi \mathbb{Z}^{d}} \in \mathcal{D}^{\prime d}\left(S \mathbb{T}^{d}\right), \quad \text { and } \quad \psi=\iota_{V}\left(\delta_{2 \pi \mathbb{Z}^{d}}\right) \in \mathcal{D}^{\prime d-1}\left(S \mathbb{T}^{d}\right)
$$

In order to apply this theorem, we have (in practice) to split the sum over $j$ into a finite sum and an infinite one corresponding to the cutoff functions $\chi_{\infty}(t) \chi(t+j)$ in the range of application of this statement. We also have to control the growth of several integrals, namely for $0 \leq l \leq d-1$ and for $\operatorname{Re}(s)$ large enough,

$$
\int_{\mathbb{R}} \chi_{\infty}(t) \chi(t+j) t^{-s+l}|d t|=\mathcal{O}\left(j^{-s+l}\right), \int_{\mathbb{R}} \chi_{\infty}(t) \chi(t+j) t^{-s+l-N}|d t|=\mathcal{O}\left(j^{-s+l-N}\right)
$$

and

$$
\int_{\mathbb{R}}\left|\frac{d^{N}}{d t^{N}}\left(\chi_{\infty}(t) \chi(t+j) t^{-s+l}\right)\right||d t|=\mathcal{O}\left(j^{-s+l}\right)
$$

These bounds allow to apply Theorem 6.4 for $\operatorname{Re}(s)$ large enough and thus the sums under consideration converge in the anisotropic Sobolev spaces of Section 6.1 as long as $N$ is large enough to have $\varphi$ and $\psi$ in that space.

The next step is to make use of Theorem 7.4 to deduce the meromorphic continuation.
Theorem 8.14. If $\beta_{0} \notin \mathbb{Z}^{d}$, the function $\zeta_{\beta}\left(K_{2}, K_{1}, s\right)$ extends holomorphically to the whole complex plane. If $\beta_{0} \in \mathbb{Z}^{d}$, the function extends meromorphically to the whole complex plane with (at most) simple poles at $s=1, \ldots, d$ whose residues are given by

$$
\begin{equation*}
\operatorname{Res}_{s=\ell}\left(\zeta_{\beta}\left(K_{2}, K_{1}, s\right)\right)=\frac{(-1)^{d-1}}{(\ell-1)!} E_{\beta_{0}}^{(\ell-1)}, \quad \text { for } \quad \ell \in\{1, \ldots, d\} \tag{8.20}
\end{equation*}
$$

with

$$
\begin{equation*}
E_{\beta_{0}}^{(\ell-1)}=\frac{(-1)^{d+\ell}}{(2 \pi)^{2 d}} \int_{S \mathbb{T}^{d}} e^{i \int_{\tilde{x}_{1}^{\sigma_{1}}(\theta) \rightarrow \tilde{x}_{2}^{\sigma_{2}}(\theta)} \beta} d x_{1} \wedge \ldots \wedge d x_{d} \wedge \iota_{V} \mathbf{V}^{\ell-1} \mathbf{T}_{\tilde{x}_{1}^{\sigma_{1}}-\tilde{x}_{2}^{\sigma_{2}}}^{*}\left(d x_{1} \wedge \ldots \wedge d x_{d}\right) \tag{8.21}
\end{equation*}
$$

Recall that, for $\beta_{0}=0$, we used the convention that $E_{0}^{(\ell)}=0$ for every $1 \leq \ell \leq d$. This lemma proves in particular Theorem 1.2 as a particular case (see Remark 8.6). In order to prove Theorem 1.3, we are left with giving an expression of these residues in terms of geometric quantities associated with our convex subsets. This will be the topic of Section 9.

Remark 8.15. Before getting to this, let us already observe that the residue at $s=d$ can be written explicitly as

$$
\frac{1}{(2 \pi)^{d}} \int_{\mathbb{S}^{d-1}} e^{i \int_{\tilde{x}_{1}^{\sigma_{1}}(\theta) \rightarrow \vec{x}_{2}^{\sigma_{2}}(\theta)} \beta} \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta,|d \theta|)
$$

Moreover, if $\tilde{x}_{1}^{\sigma_{1}}=\tilde{x}_{2}^{\sigma_{2}}$ or if $\Sigma_{1}$ and $\Sigma_{2}$ are both points, all these residues vanish except for the one at $s=d$ which is equal to

$$
\frac{d e^{i \int_{\tilde{x}_{1}^{\sigma_{1}} \rightarrow \tilde{x}_{2}^{\sigma_{2}} \beta}}}{2^{d} \pi^{\frac{d}{2}} \Gamma\left(\frac{d}{2}+1\right)}
$$

In that case, we recall that the lengths of the geodesic arcs joining $\Sigma_{1}$ to $\Sigma_{2}$ are given explicitly by $\left(\left|2 \pi \xi+\tilde{x}_{2}^{\sigma_{2}}-\tilde{x}_{1}^{\sigma_{1}}\right|\right)_{\xi \in \mathbb{Z}^{d}}$ so that we end up with the classical Epstein zeta function [Eps03].

Proof of Theorem 8.14. Given (8.18), we are now in position to apply Theorem 7.4 to

$$
\begin{equation*}
\varphi=e^{i\left(f\left(\tilde{x}_{2}^{\sigma_{2}}\right)-f\left(\tilde{x}_{1}^{\sigma_{1}}\right)\right)} \delta_{2 \pi \mathbb{Z}^{d}} \in \mathcal{H}_{d, \beta_{0}}^{+\infty,-\frac{d}{2}-,+\infty,-\frac{d}{2}-}, \quad \text { and } \quad \psi=\iota_{V}\left(\delta_{2 \pi \mathbb{Z}^{d}}\right) \in \mathcal{H}_{d-1,-\beta_{0}}^{+\infty,-\frac{d}{2}-,+\infty,-\frac{d}{2}-} \tag{8.22}
\end{equation*}
$$

where the notation is taken from (8.17). Up to increasing slightly the value of $T_{0}$ to be in the setup of Theorem 7.4, this result applies for all $N>d / 2$. This theorem implies that for $\beta_{0} \notin \mathbb{Z}^{d}$, the function $\zeta_{\Sigma_{1}, \Sigma_{2}, T_{0}}(s)$ extends holomorphically to the whole complex plane (as $E_{\beta_{0}}^{(l)}=0$ in that case). When $\beta_{0} \in \mathbb{Z}^{d}$, Theorem 7.4 implies that the function extends meromorphically to the whole complex plane with possibly some simple poles at $s=1, \ldots, d$. Moreover, together with (8.18), we deduce that if $\beta_{0} \in \mathbb{Z}^{d}$, then

$$
\operatorname{Res}_{s=l+1}\left(\zeta_{\beta}\left(K_{2}, K_{1}, s\right)\right)=\frac{(-1)^{d-1}}{l!} E_{\beta_{0}}^{(l)}, \text { for } \quad l \in\{0, \ldots, d-1\}
$$

with

$$
E_{\beta_{0}}^{(l)}=\int_{\mathbb{S}^{d-1}} e^{i \beta_{0} \cdot\left(\tilde{x}_{2}^{\sigma_{2}}(\theta)-\tilde{x}_{1}^{\sigma_{1}}(\theta)\right)} B_{\tilde{x}_{2}^{\sigma_{2}}-\tilde{x}_{1}^{\sigma_{1}}, \beta_{0}}^{(d-1, l)}\left(e^{i\left(f\left(\tilde{x}_{2}^{\sigma_{2}}\right)-f\left(\tilde{x}_{1}^{\sigma_{1}}\right)\right)} \delta_{2 \pi \mathbb{Z}^{d}}, \iota_{V}\left(\delta_{2 \pi \mathbb{Z}^{d}}\right)\right)(\theta) \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta,|d \theta|)
$$

where the bilinear operator $B$ is defined in (3.20). From the expression of $B$, one can verify that $e^{i\left(f\left(\tilde{x}_{2}^{\sigma_{2}}\right)-f\left(\tilde{x}_{1}^{\sigma_{1}}\right)\right)}$ can be put in factor so that, in the resulting exponential, we obtain a term

$$
\beta_{0} \cdot\left(\tilde{x}_{2}^{\sigma_{2}}(\theta)-\tilde{x}_{1}^{\sigma_{1}}(\theta)\right)+f\left(\tilde{x}_{2}^{\sigma_{2}}\right)-f\left(\tilde{x}_{1}^{\sigma_{1}}\right)=\int_{\tilde{x}_{1}^{\sigma_{1}}(\theta) \rightarrow \tilde{x}_{2}^{\sigma_{2}}(\theta)} \beta
$$

which is independent of the choice of the path between $\tilde{x}_{1}^{\sigma_{1}}(\theta)$ and $\tilde{x}_{2}^{\sigma_{2}}(\theta)$ modulo $2 \pi \mathbb{Z}$. Therefore, the residue at $s=\ell:=l+1 \in\{1, \ldots, d\}$ is given by

$$
E_{\beta_{0}}^{(\ell-1)}=\int_{\mathbb{S}^{d-1}} e^{i \int_{\tilde{x}_{1}^{\sigma_{1}}(\theta) \rightarrow \tilde{x}_{2}^{\sigma_{2}}(\theta)} \beta} B_{\tilde{x}_{2}^{\sigma_{2}}-\tilde{x}_{1}^{\sigma_{1}}, \beta_{0}}^{(d-1, \ell-1)}\left(\delta_{2 \pi \mathbb{Z}^{d}}, \iota_{V}\left(\delta_{2 \pi \mathbb{Z}^{d}}\right)\right)(\theta) \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta,|d \theta|)
$$

Using expression (3.20) together with (3.12) in Lemma 3.12, we finally obtain

$$
\begin{equation*}
E_{\beta_{0}}^{(\ell-1)}=\frac{(-1)^{\ell-1}}{(2 \pi)^{d}} \int_{S \mathbb{T}^{d}} e^{i \int_{\tilde{x}_{1}^{\sigma_{1}}(\theta) \rightarrow \tilde{x}_{2}^{\sigma_{2}}(\theta)} \beta} d x_{1} \wedge \ldots \wedge d x_{d} \wedge \iota_{V} \mathbf{V}^{\ell-1} \mathbf{T}_{\tilde{x}_{1}^{\sigma_{1}}-\tilde{x}_{2}^{\sigma_{2}}}^{*}\left(\delta_{2 \pi \mathbb{Z}^{d}}\right) \tag{8.23}
\end{equation*}
$$

for $1 \leq \ell \leq d$. The latter can be rewriten as (8.21) when recalling (3.4)-(3.5).
8.7. Continuation of generalized Poincaré series. We now turn to the proof of Theorem 1.4 which amounts to study the properties of the generalized Poincaré series defined in (8.9). Arguing as in Lemma 8.13 with $e^{-s t}$ instead of $t^{-s}$, we can make use of Theorem 6.4 and Lemma 8.9 to interpret $\mathcal{Z}_{\beta}\left(K_{2}, K_{1}, s\right)$ as the Laplace transform of a correlation function of appropriate currents.

Lemma 8.16. There is $T_{0}^{*}>0$ such that for all $T_{0}>T_{0}^{*}$, one can find $\chi_{\infty}$ verifying assumption (7.1) with $t_{0}>0$ small enough such that

$$
\begin{equation*}
\mathcal{Z}_{\beta}\left(K_{2}, K_{1}, s\right)=(-1)^{d-1} \int_{S \mathbb{T}^{d}} e^{i\left(f\left(\tilde{x}_{2}^{\sigma_{2}}\right)-f\left(\tilde{x}_{1}^{\sigma_{1}}\right)\right)} \delta_{2 \pi \mathbb{Z}^{d}} \wedge \widehat{\chi_{s}^{L}}\left(-i \mathbf{V}_{\beta_{0}}\right) \mathbf{T}_{\tilde{x}_{1}^{\sigma_{1}}-\tilde{x}_{2}^{\sigma_{2}} \iota_{V}\left(\delta_{2 \pi \mathbb{Z}^{d}}\right) . . . . ~}^{\text {. }} \tag{8.24}
\end{equation*}
$$

Again, using the conventions of Theorem 7.8 with $\tilde{x}=\tilde{x}_{2}^{\sigma_{2}}-\tilde{x}_{1}^{\sigma_{1}}$, the right-hand side can be rewritten as

$$
\begin{aligned}
& \mathcal{L}_{\left(e^{i\left(f\left(\tilde{x}_{2}^{\sigma_{2}}\right)-f\left(\tilde{x}_{1}^{\sigma_{1}}\right)\right)} \delta_{\left.2 \pi \mathbb{Z}^{d}, \iota_{V}\left(\delta_{2 \pi \mathbb{Z}^{d}}\right)\right)}\right.}(s) \\
&=\int_{S \mathbb{T}^{d}} e^{i\left(f\left(\tilde{x}_{2}^{\sigma_{2}}\right)-f\left(\tilde{x}_{1}^{\sigma_{1}}\right)\right)} \delta_{2 \pi \mathbb{Z}^{d}} \wedge \widehat{\chi_{s}^{L}}\left(-i \mathbf{V}_{\beta_{0}}\right) \mathbf{T}_{\tilde{x}_{1}^{\sigma_{1}}-\tilde{x}_{2}^{\sigma_{2}} \iota_{V}\left(\delta_{2 \pi \mathbb{Z}^{d}}\right)}
\end{aligned}
$$

We are thus in position to apply Theorem 7.8.
Theorem 8.17. Setting

$$
\begin{equation*}
S_{\beta_{0}}=\left\{ \pm i\left|\xi-\beta_{0}\right|, \quad \xi \in \mathbb{Z}^{d}\right\} \tag{8.25}
\end{equation*}
$$

the following statements hold:
(1) $\mathcal{Z}_{\beta}\left(K_{2}, K_{1}\right.$, s) extends as a function in $\mathcal{C}^{\infty}\left(\overline{\mathbb{C}}_{+} \backslash S_{\beta_{0}}\right)$ and the limit $\lim _{x \rightarrow 0^{+}} \mathcal{Z}_{\beta}\left(K_{2}, K_{1}, x+\right.$ iy) exists in $\mathcal{S}^{\prime}(\mathbb{R})$ as boundary value of holomorphic function,
(2) if $\beta_{0} \in \mathbb{Z}^{\text {d }}$ (i.e. $0 \in S_{\beta_{0}}$ ), then

$$
\mathcal{Z}_{\beta}\left(K_{2}, K_{1}, s\right)-\sum_{\ell=1}^{d} \frac{E_{\beta_{0}}^{(\ell-1)}}{s^{\ell}}
$$

is a $\mathcal{C}^{\infty}$ function in a neighborhood of zero in $\overline{\mathbb{C}}_{+}$where $E_{\beta_{0}}^{(\ell-1)}$ is given by (8.23). The limit $\lim _{x \rightarrow 0^{+}} \mathcal{Z}_{\beta}\left(K_{2}, K_{1}, x+i y\right)-\sum_{\ell=1}^{d} \frac{E_{\beta_{0}}^{(\ell-1)}}{(x+i y)^{\ell}}$ exists as a smooth function near $y=0$. In case $\beta_{0} \notin \mathbb{Z}^{d}$, then $\mathcal{Z}_{\beta}\left(K_{2}, K_{1}, s\right)$ is itself a $\mathcal{C}^{\infty}$ function in a neighborhood of zero in $\overline{\mathbb{C}}_{+}$.
(3) There exist constants $C_{j, \ell-1}\left(\xi, \beta_{0}\right)$ for every $\ell \in\{1, \ldots, d\}$ and $j \in \mathbb{Z}_{+}$, such that for any $i r_{0}^{ \pm}= \pm i\left|\xi_{0}-\beta_{0}\right| \in S_{\beta_{0}} \backslash\{0\}$, the function

$$
\begin{equation*}
\mathcal{Z}_{\beta}\left(K_{2}, K_{1}, s\right)-\sum_{\ell=1}^{d} \sum_{j=0}^{N-1}\left(\sum_{\xi \in \mathbb{Z}^{d},\left|\xi-\beta_{0}\right|=\left|r_{0}^{ \pm}\right|} \frac{1}{(\ell-1)!} C_{j, \ell-1}^{ \pm}\left(\xi, \beta_{0}\right)\right) \mathrm{F}_{\frac{d-1}{2}+j+1-\ell}\left(s-i r_{0}^{ \pm}\right) \tag{8.26}
\end{equation*}
$$

extends as a $\mathcal{C}^{N-1-\left\lceil\frac{d+1}{2}\right\rceil}$ function in a neighborhood of $i r_{0}^{ \pm}$in $\overline{\mathbb{C}}_{+}$.
Moreover, the most singular term in this expansion near $i r_{0}^{ \pm}$is given by ( $j=0$ and $\ell=d$ )

$$
\begin{aligned}
& \frac{(-1)^{d-1} e^{\mp i \frac{\pi}{4}(d-1)} \mathrm{F}_{-\frac{d-1}{2}}\left(s-i r_{0}^{ \pm}\right)}{(2 \pi)^{\frac{d+1}{2}}\left|r_{0}^{ \pm}\right|^{\frac{d-1}{2}}} \\
& \times\left(\sum_{\xi \in \mathbb{Z}^{d},\left|\xi-\beta_{0}\right|=\left|r_{0}^{ \pm}\right|} e^{i \xi \cdot\left(\tilde{x}_{2}^{\sigma_{2}}-\tilde{x}_{1}^{\sigma_{1}}\right)\left( \pm \frac{\xi-\beta_{0}}{\left|\xi-\beta_{0}\right|}\right)} e^{i\left(f\left(\tilde{x}_{2}^{\sigma_{2}}\right)-f\left(\tilde{x}_{1}^{\sigma_{1}}\right)\right)\left( \pm \frac{\xi-\beta_{0}}{\left|\xi-\beta_{0}\right|}\right)}\right)
\end{aligned}
$$

Recall that for $\alpha \in \mathbb{R}$, the distribution $\mathrm{F}_{\alpha}$ is defined in (7.25) and it is essentially the Laplace transform of $t^{-\alpha}$ (near $t=+\infty$ ).

Note the important fact that the difference
$\lim _{x \rightarrow 0^{+}} \mathcal{Z}_{\beta}\left(K_{2}, K_{1}, x+i y\right)-\sum_{\ell=1}^{d} \sum_{j=0}^{N-1}\left(\sum_{\xi \in \mathbb{Z}^{d},\left|\xi-\beta_{0}\right|=\left|r_{0}^{ \pm}\right|} \frac{1}{(\ell-1)!} \mathrm{C}_{j, \ell-1}^{ \pm}\left(\xi, \beta_{0}\right)\right) \mathrm{F}_{\frac{d-1}{2}+j+1-\ell}\left(x+i y-i r_{0}^{ \pm}\right)$,
viewed as tempered distributions in $\mathcal{S}^{\prime}(\mathbb{R})$ of the variable $y$ is an element in $\mathcal{C}^{N-1-\left\lceil\frac{d+1}{2}\right\rceil}$ near $y=r_{0}^{ \pm}$. Here we view the difference as a distribution obtained as boundary values of holomorphic functions.

Proof. We apply Theorem 7.8 to $\tilde{x}=\tilde{x}_{2}^{\sigma_{2}}-\tilde{x}_{1}^{\sigma_{1}}$ and to the currents $\varphi, \psi$ in (8.22). Theorem 7.8 thus applies to all $N_{0}>d, N>0, m>d / 2$ and Item 1 readily follows. As for Item 2, Theorem 7.8 implies the expected result after recalling the definition of $E_{\beta_{0}}^{(l)}$.

We next prove Item 3. We fix a point $r_{0}^{ \pm}:= \pm\left|\xi_{0}-\beta_{0}\right|$ such that $i r_{0}^{ \pm}= \pm i\left|\xi_{0}-\beta_{0}\right| \in S_{\beta_{0}} \backslash\{0\}$, and describe $\mathcal{Z}_{\beta}\left(K_{2}, K_{1}, s\right)$ near $i r_{0}^{ \pm}$. Theorem 7.8, taken for $N_{0}>d$ large enough (compared to $N$ ), implies that

$$
\mathcal{Z}_{\beta}\left(K_{2}, K_{1}, s\right)-\sum_{l=0}^{d-1} \sum_{j=0}^{N-1}\left(\sum_{\xi \in \mathbb{Z}^{d},\left|\xi-\beta_{0}\right|=\left|r_{0}^{ \pm}\right|} \frac{1}{l!} \mathrm{C}_{j, l}^{ \pm}\left(\xi, \beta_{0}\right)\right) \mathrm{F}_{\frac{d-1}{2}+j-l}\left(s-i r_{0}^{ \pm}\right)
$$

extends as a $\mathcal{C}^{\mathbf{k}}$ function in a neighborhood of $i r_{0}^{ \pm}$in $\overline{\mathbb{C}}_{+}$, where

$$
\mathrm{k}=N+\left\lceil\frac{d-1}{2}\right\rceil-\min \left\{k_{1}, k_{2}\right\}-2=N-1-\left\lceil\frac{d+1}{2}\right\rceil
$$

(recall that $\min \left\{k_{1}, k_{2}\right\}=d-1$ here) and

$$
\begin{equation*}
\mathrm{C}_{j, l}^{ \pm}\left(\xi, \beta_{0}\right)=\frac{1}{\left|\xi_{0}-\beta_{0}\right|^{\frac{d-1}{2}+j}} P_{j, l, \xi}^{ \pm}\left[e^{i\left(f\left(\tilde{x}_{2}^{\sigma_{2}}\right)-f\left(\tilde{x}_{1}^{\sigma_{1}}\right)\right)} \delta_{2 \pi \mathbb{Z}^{d}, \iota_{V}\left(\delta_{2 \pi \mathbb{Z}^{d}}\right)}\right]\left( \pm \frac{\xi-\beta_{0}}{\left|\xi-\beta_{0}\right|}\right) \tag{8.28}
\end{equation*}
$$

Now, recalling the definition of $\mathrm{F}_{\alpha}$ in (7.24), we notice that the most singular term in the expansion (8.26) is for $l=d-1$ and $j=0$, and is given by

$$
\begin{equation*}
\left(\sum_{\xi \in \mathbb{Z}^{d},\left|\xi-\beta_{0}\right|=\left|r_{0}^{ \pm}\right|} \frac{1}{(d-1)!} \mathrm{C}_{0, d-1}^{ \pm}\left(\xi, \beta_{0}\right)\right) \mathrm{F}_{-\frac{d-1}{2}}\left(s-i r_{0}^{ \pm}\right) \tag{8.29}
\end{equation*}
$$

We now compute it explicitly. We first compute $C_{0, l}^{ \pm}(\omega)$ according to the definition of $P_{j, l, \xi}^{ \pm}$ in (7.27), recalling from Lemma 4.4 and Corollary 4.6 that $L_{0, \mp \omega}^{ \pm}=1$, as

$$
\begin{align*}
& P_{0, l, \xi}^{ \pm}\left[e^{i\left(f\left(\tilde{x}_{2}^{\sigma_{2}}\right)-f\left(\tilde{x}_{1}^{\sigma_{1}}\right)\right)} \delta_{2 \pi \mathbb{Z}^{d}}, \iota_{V}\left(\delta_{2 \pi \mathbb{Z}^{d}}\right)\right]( \pm \omega)  \tag{8.30}\\
& =e^{\mp i \frac{\pi}{4}(d-1)}(2 \pi)^{\frac{d-1}{2}} e^{i \xi \cdot \tilde{x}(\omega)} B_{\tilde{x}, \xi}^{(d-1, l)}\left(e^{i\left(f\left(\tilde{x}_{2}^{\sigma_{2}}\right)-f\left(\tilde{x}_{1}^{\sigma_{1}}\right)\right)} \delta_{\left.2 \pi \mathbb{Z}^{d}, \iota_{V}\left(\delta_{2 \pi \mathbb{Z}^{d}}\right)\right)( \pm \omega) .} .\right.
\end{align*}
$$

Finally, the expression of $B_{\tilde{x}, \xi}^{(d-1, l)}$ is given in (3.20) and writes for $l=d-1$,

$$
\begin{aligned}
& B_{\tilde{x}, \xi}^{(d-1, d-1)}\left(e^{i\left(f\left(\tilde{x}_{2}^{\sigma_{2}}\right)-f\left(\tilde{x}_{1}^{\sigma_{1}}\right)\right)} \delta_{2 \pi \mathbb{Z}^{d}}, \iota_{V}\left(\delta_{2 \pi \mathbb{Z}^{d}}\right)\right)(\theta) \operatorname{Vol}_{S \mathbb{T}^{d}}(\theta, d x, d \theta) \\
& \quad=(-1)^{d-1} e^{i\left(f\left(\tilde{x}_{2}^{\sigma_{2}}\right)-f\left(\tilde{x}_{1}^{\sigma_{1}}\right)\right)} \pi_{\xi}^{(d)}\left(\delta_{2 \pi \mathbb{Z}^{d}}\right)(\theta, d x, d \theta) \wedge \mathbf{V}^{d-1} \mathbf{T}_{-\tilde{x}}^{*} \pi_{-\xi}^{(d-1)}\left(\iota_{V}\left(\delta_{2 \pi \mathbb{Z}^{d}}\right)\right)(\theta, d x, d \theta)
\end{aligned}
$$

According to (3.4)-(3.5), we have $\pi_{\xi}^{(d)}\left(\delta_{2 \pi \mathbb{Z}^{d}}\right)=\frac{1}{(2 \pi)^{d / 2}} d x_{1} \wedge \cdots \wedge d x_{d}$ together with

$$
\pi_{-\xi}^{(d-1)}\left(\iota_{V}\left(\delta_{2 \pi \mathbb{Z}^{d}}\right)\right)=\frac{1}{(2 \pi)^{d / 2}} \iota_{V}\left(d x_{1} \wedge \cdots \wedge d x_{d}\right)
$$

Thanks to Lemmas 3.12 and 3.11, we then deduce

$$
\begin{aligned}
\mathbf{V}^{d-1} \mathbf{T}_{-\tilde{x}}^{*} \pi_{-\xi}^{(d-1)}\left(\iota_{V}\left(\delta_{2 \pi \mathbb{Z}^{d}}\right)\right)(\theta, d x, d \theta) & =\frac{1}{(2 \pi)^{d / 2}} \mathbf{T}_{-\tilde{x}}^{*} \mathbf{V}^{d-1}\left(\iota_{V}\left(d x_{1} \wedge \cdots \wedge d x_{d}\right)\right) \\
& =\frac{(d-1)!}{(2 \pi)^{d / 2}} \mathbf{T}_{-\tilde{x}}^{*} \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta, d \theta) \\
& =\frac{(d-1)!}{(2 \pi)^{d / 2}} \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta, d \theta)
\end{aligned}
$$

Combining the above three lines, we have obtained that

$$
B_{\tilde{x}, \xi}^{(d-1, d-1)}\left(e^{i\left(f\left(\tilde{x}_{2}^{\sigma_{2}}\right)-f\left(\tilde{x}_{1}^{\sigma_{1}}\right)\right)} \delta_{2 \pi \mathbb{Z}^{d}}, \iota_{V}\left(\delta_{2 \pi \mathbb{Z}^{d}}\right)\right)(\theta)=\frac{(-1)^{d-1}(d-1)!}{(2 \pi)^{d}} e^{i\left(f\left(\tilde{x}_{2}^{\sigma_{2}}\right)-f\left(\tilde{x}_{1}^{\sigma_{1}}\right)\right)(\theta)}
$$

Coming back to (8.28)-(8.29)-(8.30), this concludes the proof of the statement in Item 3.
8.8. A summation formula in the spirit of Guinand-Meyer. We now turn to the proof of Theorem 1.7. Repeating the above arguments for certain variations of Poincaré series, we can in fact deduce a summation formula in the spirit of the recent results on crystalline measures by Meyer [Mey16]. More precisely, we set

$$
\begin{equation*}
\tilde{\mathcal{Z}}_{\beta}\left(K_{2}, K_{1}, s\right):=\sum_{t>T_{0}: \mathcal{E}_{t}\left(\Sigma_{1}, \Sigma_{2}\right) \neq \emptyset} \frac{e^{-s t}}{t^{\frac{d-1}{2}}}\left(\sum_{(x, \theta) \in \mathcal{E}_{t}\left(\Sigma_{1}, \Sigma_{2}\right)} e^{-i \int_{-t}^{0} \beta(V)(x+\tau \theta, \theta)|d \tau|}\right), \tag{8.31}
\end{equation*}
$$

and we emphasize that this function depends on the choice of orientation $\left(\sigma_{1}, \sigma_{2}\right)$ even if we drop this dependence for the moment. As for Poincaré series, the limit as $x \rightarrow 0^{+}$of $y \mapsto$ $\tilde{\mathcal{Z}}_{\beta}\left(K_{2}, K_{1}, x+i y\right)$ exists as a tempered distribution on $\mathbb{R}$ thanks to Lemma 8.5. Arguing as in the proof of Theorem 8.17, one can verify that the singular support of this distribution is the same as for $\lim _{x \rightarrow 0^{+}} \mathcal{Z}_{\beta}\left(K_{2}, K_{1}, x+i y\right)$ but the singularity are slightly simpler due to the renormalization factor $t^{-\frac{d-1}{2}}$. More precisely, using the conventions of this Theorem, one finds that, near $y=r_{0}^{+}$, $\lim _{x \rightarrow 0^{+}} \tilde{\mathcal{Z}}_{\beta}\left(K_{2}, K_{1}, x+i y\right)$ is equal to

$$
\lim _{x \rightarrow 0^{+}} \frac{(-1)^{d-1} e^{-i \frac{\pi}{4}(d-1)}}{(2 \pi)^{\frac{d+1}{2}}\left|r_{0}^{+}\right|^{\frac{d-1}{2}}\left(x+i y-i r_{0}^{+}\right)} \times\left(\sum_{\xi \in \mathbb{Z}^{d},\left|\xi-\beta_{0}\right|=\left|r_{0}^{+}\right|} e^{i \xi \cdot\left(\tilde{x}_{2}^{\sigma_{2}}-\tilde{x}_{1}^{\sigma_{1}}\right)\left(\frac{\xi-\beta_{0}}{\left|\xi-\beta_{0}\right|}\right)} e^{i\left(f\left(\tilde{x}_{2}^{\sigma_{2}}\right)-f\left(\tilde{x}_{1}^{\sigma_{1}}\right)\right)\left(\frac{\xi-\beta_{0}}{\left|\xi-\beta_{0}\right|}\right)}\right)
$$

modulo some remainder belonging to $L^{p}\left(\left(r_{0}^{+}-\delta, r_{0}^{+}+\delta\right)\right)$ for some positive $\delta$ and for every $1 \leq p<\infty$. Similarly, one has, near $y=r_{0}^{+}, \lim _{x \rightarrow 0^{+}} \tilde{\mathcal{Z}}_{\beta}\left(K_{2}, K_{1}, x-i y\right)$ is equal to

$$
\lim _{x \rightarrow 0^{+}} \frac{(-1)^{d-1} e^{i \frac{\pi}{4}(d-1)}}{(2 \pi)^{\frac{d+1}{2}}\left|r_{0}^{+}\right|^{\frac{d-1}{2}}\left(x-i y+i r_{0}^{+}\right)} \times\left(\sum_{\xi \in \mathbb{Z}^{d},\left|\xi-\beta_{0}\right|=\left|r_{0}^{+}\right|} e^{i \xi \cdot\left(\tilde{x}_{2}^{\sigma_{2}}-\tilde{x}_{1}^{\sigma_{1}}\right)\left(-\frac{\xi-\beta_{0}}{\left|\xi-\beta_{0}\right|}\right)} e^{i\left(f\left(\tilde{x}_{2}^{\sigma_{2}}\right)-f\left(\tilde{x}_{1}^{\sigma_{1}}\right)\right)\left(-\frac{\xi-\beta_{0}}{\left|\xi-\beta_{0}\right|}\right)}\right),
$$

modulo some remainder belonging to $L^{p}\left(\left(r_{0}^{+}-\delta, r_{0}^{+}+\delta\right)\right)$ for every $1 \leq p<\infty$. Recalling from [Hör03, Eq. (3.2.11), p.72] that

$$
\lim _{x \rightarrow 0^{+}}\left(\frac{1}{y+i x}-\frac{1}{y-i x}\right)=-2 i \pi \delta_{0}(y)
$$

we finally find that, near $y=r_{0}^{+}$, the tempered distribution ${ }^{16}$

$$
\lim _{x \rightarrow 0^{+}}\left(e^{i \frac{\pi}{4}(d-1)} \tilde{\mathcal{Z}}_{\beta}^{\sigma_{2}, \sigma_{1}}\left(K_{2}, K_{1}, x+i y\right)+e^{-i \frac{\pi}{4}(d-1)} \tilde{\mathcal{Z}}_{\beta}^{-\sigma_{2},-\sigma_{1}}\left(K_{2}, K_{1}, x-i y\right)\right)
$$

is equal to

$$
\frac{(-1)^{d-1} \delta_{0}\left(y-r_{0}^{+}\right)}{(2 \pi)^{\frac{d-1}{2}}\left|r_{0}^{+}\right|^{\frac{d-1}{2}}} \times\left(\sum_{\xi \in \mathbb{Z}^{d},\left|\xi-\beta_{0}\right|=\left|r_{0}^{+}\right|} e^{i \xi \cdot\left(\tilde{x}_{2}^{\sigma_{2}}-\tilde{x}_{1}^{\sigma_{1}}\right)\left(\frac{\xi-\beta_{0}}{\left|\xi-\beta_{0}\right|}\right)} e^{i\left(f\left(\tilde{x}_{2}^{\sigma_{2}}\right)-f\left(\tilde{x}_{1}^{\sigma_{1}}\right)\right)\left(\frac{\xi-\beta_{0}}{\left|\xi-\beta_{0}\right|}\right)}\right)+\mathcal{O}_{L^{p}}(1)
$$

[^14]The same discussion of course holds near $y=r_{0}^{-}$. Hence, if $\beta_{0} \notin H^{1}\left(\mathbb{T}^{d}, \mathbb{Z}\right)$, one finds that the distribution

$$
e^{i \frac{\pi}{4}(d-1)} \tilde{\mathcal{Z}}_{\beta}^{\sigma_{2}, \sigma_{1}}\left(K_{2}, K_{1}, i y\right)+e^{-i \frac{\pi}{4}(d-1)} \tilde{\mathcal{Z}}_{\beta}^{-\sigma_{2},-\sigma_{1}}\left(K_{2}, K_{1},-i y\right)
$$

is a combination of Dirac masses modulo some $L_{\mathrm{loc}}^{p}$ remainder which proves Theorem 1.7.
8.9. The case when $K_{1}, K_{2}$ are points. In this section we finally discuss the particular case where the convex sets are reduced to points (or to balls). In that case, the proofs are simpler and lead to very explicit formulas with connection to the magnetic Laplacian.
8.9.1. Meromorphic continuation of Poincaré series.

Proposition 8.18. Assume $K_{1}:=\{x\}$ and $K_{2}:=\{y\}$ where $x, y \in \mathbb{R}^{d}$ are two points and $\beta=\beta_{0}+d f$ is a closed real valued one-form such that $[\beta]=\beta_{0} \in H^{1}\left(\mathbb{T}^{d}, \mathbb{R}\right) \simeq \mathbb{R}^{d}$. Then we have

$$
\begin{equation*}
\sum_{\gamma \in \mathcal{P}_{x, y}} e^{i \int_{\gamma} \beta} \delta(t-\ell(\gamma))=2 \pi t^{\frac{d}{2}} e^{i(f(y)-f(x))} \frac{J_{\frac{d-2}{}}^{2}\left(2 \pi t \sqrt{-\Delta_{\beta_{0}}}\right)}{\left(\sqrt{-\Delta_{\beta_{0}}}\right)^{\frac{d-2}{2}}}(x, y) \text { in } \mathcal{D}^{\prime}\left(\mathbb{R}_{+}^{*}\right) \tag{8.32}
\end{equation*}
$$

If moreover $x \neq y$, then (8.32) also holds in $\mathcal{D}^{\prime}\left(\left(-t_{0}, \infty\right)\right)$ for some small enough $t_{0}>0$, and we have

$$
\begin{equation*}
\mathcal{Z}_{\beta}(x, y, s)=2^{d} \pi^{\frac{d-1}{2}} \Gamma\left(\frac{d+1}{2}\right) e^{i(f(y)-f(x))} s\left(s^{2}-4 \pi^{2} \Delta_{\beta_{0}}\right)^{-\frac{d+1}{2}}(x, y), \quad \operatorname{Re}(s)>0 \tag{8.33}
\end{equation*}
$$

Recall that in the right hand-side of (8.33), $\left(s^{2}-4 \pi^{2} \Delta_{\beta_{0}}\right)^{-\frac{d+1}{2}}(x, y)$ denotes the Schwartz kernel of the operator $\left(s^{2}-4 \pi^{2} \Delta_{\beta_{0}}\right)^{-\frac{d+1}{2}}$ taken at the point $(x, y)$. The proof relies on the fact that the twisted counting measure $\sum_{\gamma} e^{i \int_{\gamma} \beta} \delta(t-\ell(\gamma))$ has an explicit relation with the Schwartz kernel of $\Pi_{*} e^{-t\left(V+i \beta_{0}(V)\right)} \Pi^{*}$ (acting on functions) at ( $x, y$ ).

Proof. On the one hand, by a direct calculation, one has

$$
\Pi_{*} e^{-t\left(V+i \beta_{0}(V)\right)} \Pi^{*}(x, y)=\frac{1}{(2 \pi)^{d}} \sum_{\xi \in \mathbb{Z}^{d}} e^{i \xi \cdot(y-x)} \int_{\mathbb{S}^{d-1}} e^{i t\left(\xi-\beta_{0}\right) \cdot \theta} \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta, d \theta)
$$

On the other hand, one can make use of Lemma 8.9 (applied either for $x \neq y$ or for $t>0$ ) to write the twisted counting measure when $K_{2}=\{x\}$ and $K_{1}=\{y\}$. This yields that this is equal to the previous quantity up to a normalization factor:

$$
\sum_{\gamma \in \mathcal{P}_{x, y}} e^{i \int_{\gamma} \beta} \delta(t-\ell(\gamma))=e^{i(f(y)-f(x))} t^{d-1} \Pi_{*} e^{-t\left(V+i \beta_{0}(V)\right)} \Pi^{*}(x, y) \text { in } \mathcal{D}^{\prime}\left(\mathbb{R}_{+}^{*}\right)
$$

In particular, according to (5.3), one has (8.32). Note that, as soon as $x \neq y$, the formula (8.32) still makes sense in $\mathcal{D}^{\prime}\left(\left(-t_{0}, \infty\right)\right)$ for some small enough $t_{0}>0$. For $x \neq y$, we can then make the Laplace transform of this equality:

$$
\sum_{\gamma \in \mathcal{P}_{x, y}} e^{i \int_{\gamma} \beta} e^{-s \ell(\gamma)}=2 \pi e^{i(f(y)-f(x))} \int_{0}^{\infty} t^{\frac{d}{2}} \frac{J_{\frac{d-2}{2}}\left(2 \pi t \sqrt{-\Delta_{\beta_{0}}}\right)}{\left(\sqrt{-\Delta_{\beta_{0}}}\right)^{\frac{d-2}{2}}}(x, y) e^{-s t}|d t|
$$

We now recall that, for every $\nu>-1$ and for every $a \in \mathbb{R}$,

$$
\int_{0}^{\infty} e^{-s t} t^{\nu+1} J_{\nu}(a t)|d t|=2^{\nu+1} \pi^{-\frac{1}{2}} \Gamma\left(\nu+\frac{3}{2}\right) a^{\nu} s\left(s^{2}+a^{2}\right)^{-\nu-\frac{3}{2}}, \quad \operatorname{Re}(s)>0
$$

see e.g. [EMOT54, Table 8, line (8) p 182]. Combining the last two lines, we obtain

$$
\sum_{\gamma \in \mathcal{P}_{x, y}} e^{i \int_{\gamma} \beta} e^{-s \ell(\gamma)}=2^{d} \pi^{\frac{d-1}{2}} \Gamma\left(\frac{d+1}{2}\right) e^{i(f(y)-f(x))} s\left(s^{2}-4 \pi^{2} \Delta_{\beta_{0}}\right)^{-\frac{d+1}{2}}(x, y)
$$

which is the sought result.

In particular, using the spectral properties of the operator $\Delta_{\beta_{0}}$, we can directly recover Theorem 1.4 from the introduction in that case. Precisely, one has, for $x \neq y$,

$$
\begin{equation*}
\mathcal{Z}_{\beta}(x, y, s)=\pi^{-\frac{d+1}{2}} \Gamma\left(\frac{d+1}{2}\right) e^{i(f(y)-f(x))} s \sum_{\xi \in \mathbb{Z}^{d}} \frac{e^{i \xi \cdot(x-y)}}{\left(s^{2}+4 \pi^{2}\left|\xi+\beta_{0}\right|^{2}\right)^{\frac{d+1}{2}}} \tag{8.34}
\end{equation*}
$$

We can even be slightly more precise as we can verify that

- if $d$ is odd, this expression has a meromorphic extension to $\mathbb{C}$ with poles located at $\operatorname{Sp}\left( \pm i \sqrt{-\Delta_{\beta_{0}}}\right)$;
- if $d$ is even, this expression has a meromorphic extension for instance to

$$
\begin{equation*}
\mathbb{C} \backslash\left\{i \lambda+\mathbb{R}_{-}, \lambda \in \pm \operatorname{Sp}\left(\sqrt{-\Delta_{\beta_{0}}}\right) \backslash\{0\}\right\} \tag{8.35}
\end{equation*}
$$

due to the presence, in this case, of squareroot singularities at the points of $\mathrm{Sp}\left( \pm i \sqrt{-\Delta_{\beta_{0}}}\right)$ \} $\{0\}$. Note that the only possible pole in the region described in (8.35) is then at 0 and that it only occurs if $\beta_{0} \in \mathbb{Z}^{d}$.
Finally, when the convex sets $K_{1}$ and $K_{2}$ are two round balls, i.e. $K_{1}=\bar{B}\left(x, r_{1}\right)$ and $K_{1}=$ $\bar{B}\left(y, r_{2}\right)$, with $x \neq y$ and small enough radii $r_{1}$ and $r_{2}$, the Poincaré series is slightly modified by a factor $e^{-s\left(r_{1}+r_{2}\right)}$ and the above formula yields

$$
\begin{equation*}
\mathcal{Z}_{\beta}\left(K_{1}, K_{2}, s\right)=\pi^{-\frac{d+1}{2}} \Gamma\left(\frac{d+1}{2}\right) e^{i(f(y)-f(x))} s e^{-s\left(r_{2}+r_{1}\right)} \sum_{\xi \in \mathbb{Z}^{d}} \frac{e^{i \xi \cdot(x-y)}}{\left(s^{2}+4 \pi^{2}\left|\xi+\beta_{0}\right|^{2}\right)^{\frac{d+1}{2}}}, \tag{8.36}
\end{equation*}
$$

where we have taken $\left(\sigma_{1}, \sigma_{2}\right)=(+,-)$ for the (implicit) choice of orientations of the two balls.
8.9.2. A Guinand-Meyer formula when $d$ is odd. Let us now discuss a variant of Theorem 1.7 when $K_{1}:=\{x\}$ and $K_{2}:=\{y\}$ are reduced to points that are distinct. Following [Mey16, Th. 5], we define, for $x \neq y$,

$$
\begin{equation*}
\mu_{G M}(t):=\sum_{\gamma \in \mathcal{P}_{x, y}} \frac{e^{i \int_{\gamma} \beta}}{\ell(\gamma)}(\delta(t-\ell(\gamma))-\delta(t+\ell(\gamma))) \tag{8.37}
\end{equation*}
$$

which is a Radon measure in $\mathcal{S}^{\prime}(\mathbb{R})$ carried by a discrete and locally finite set of $\mathbb{R}$. Note that compared to the twisted counting measure in (8.32), $\mu_{G M}$ is symmetrized and renormalized by $t^{-1}$. In particular, this is not the same renormalization as in Theorem 1.7 except if $d=3$.
Proposition 8.19. Assume that $d$ is odd, that $x \neq y$ and that $\beta_{0} \notin H^{1}\left(\mathbb{T}^{d}, \mathbb{Z}\right) \simeq \mathbb{Z}^{d}$. Then, the Fourier transform of $\mu_{G M}$ in (8.37) is given by

$$
\begin{aligned}
\widehat{\mu}_{G M}(\tau)= & i(-1)^{\frac{d-3}{2}} 2^{d} \pi^{\frac{d+1}{2}} e^{i(f(y)-f(x))} \\
& \times \sum_{\xi \in \mathbb{Z}^{d}}\left(\frac{\delta^{\left(\frac{d-3}{2}\right)}\left(\tau-2 \pi\left|\xi+\beta_{0}\right|\right)}{\left(\tau+2 \pi\left|\xi+\beta_{0}\right|\right)^{\frac{d-1}{2}}}+\frac{\delta^{\left(\frac{d-3}{2}\right)}\left(\tau+2 \pi\left|\xi+\beta_{0}\right|\right)}{\left(\tau-2 \pi\left|\xi+\beta_{0}\right|\right)^{\frac{d-1}{2}}}\right)
\end{aligned}
$$

The assumption $\beta_{0} \notin H^{1}\left(\mathbb{T}^{d}, \mathbb{Z}\right) \simeq \mathbb{Z}^{d}$ implies that the continuation of the Laplace transform of $\mu_{G M}$ has no pole at $s=0$ while the assumption $d$ odd ensures that the Poincaré series extends meromorphically to $\mathbb{C}$ with poles located on the imaginary axis. When $d=3$, this proposition recovers [Mey16, Th. 5] and, for $d \geq 5$, it corresponds to the more general statement from [LR21, Corollary 2.4]. In particular, if $d=3, \mu_{G M}$ is a crystalline measure: a measure in $\mathcal{S}^{\prime}(\mathbb{R})$ carried by a discrete and locally finite set of $\mathbb{R}$ with Fourier transform having the same properties. In odd dimension $d \neq 3, \widehat{\mu}_{G M}$ is no longer a crystalline measure since its Fourier transform is not a measure (but a distribution of order $\frac{d-3}{2}$ ). Following [LR21], one says that the measure $\mu_{G M}$ is a crystalline distribution, i.e. a distribution in $\mathcal{S}^{\prime}(\mathbb{R})$ carried by a discrete and locally finite set of $\mathbb{R}$ with Fourier transform having the same properties. Compared to the measure in Theorem 1.7, $\widehat{\mu}_{G M}$ has the drawback of not being a measure here. However, it has the advantage to be carried by a discrete and locally finite set of $\mathbb{R}$ (i.e. there is no absolutely continuous remainder $r$ as in Theorem 1.7).

Proof. Dividing (8.32) by $t$ (which we may since $x \neq y$ ), we obtain

$$
\sum_{\gamma \in \mathcal{P}_{x, y}} \frac{e^{i \int_{\gamma} \beta}}{\ell(\gamma)} \delta(t-\ell(\gamma))=2 \pi t^{\frac{d-2}{2}} e^{i(f(y)-f(x))} \frac{J_{\frac{d-2}{2}}^{2}\left(2 \pi t \sqrt{-\Delta_{\beta_{0}}}\right)}{\left(\sqrt{-\Delta_{\beta_{0}}}\right)^{\frac{d-2}{2}}}(x, y)
$$

Taking the Laplace transform, one finds that, for $\operatorname{Re}(s)>0$,

$$
\sum_{\gamma \in \mathcal{P}_{x, y}} \frac{e^{i \int_{\gamma} \beta}}{\ell(\gamma)} e^{-s \ell(\gamma)}=2 \pi e^{i(f(y)-f(x))} \int_{0}^{\infty} e^{-s t} t^{\frac{d-2}{2}} \frac{J_{\frac{d-2}{2}}^{2}\left(2 \pi t \sqrt{-\Delta_{\beta_{0}}}\right)}{\left(\sqrt{-\Delta_{\beta_{0}}}\right)^{\frac{d-2}{2}}}(x, y)|d t|
$$

Recalling that, for every $\nu>-1 / 2$ and for every $a \in \mathbb{R}$,

$$
\int_{0}^{\infty} e^{-s t} t^{\nu} J_{\nu}(a t)|d t|=2^{\nu} \pi^{-\frac{1}{2}} \Gamma\left(\nu+\frac{1}{2}\right) a^{\nu}\left(s^{2}+a^{2}\right)^{-\nu-\frac{1}{2}}, \quad \operatorname{Re}(s)>0
$$

see e.g. [EMOT54, Table 8, line (7) p 182], we deduce that

$$
\begin{equation*}
\sum_{\gamma \in \mathcal{P}_{x, y}} \frac{e^{i \int_{\gamma} \beta}}{\ell(\gamma)} e^{-s \ell(\gamma)}=2^{d-1} \pi^{\frac{d-1}{2}} \Gamma\left(\frac{d-1}{2}\right) e^{i(f(y)-f(x))}\left(s^{2}-4 \pi^{4} \Delta_{\beta_{0}}\right)^{-\frac{d-1}{2}}(x, y) \tag{8.38}
\end{equation*}
$$

Recalling the definition of $\mu_{G M}$ in (8.37), its Fourier transform is given by

$$
\widehat{\mu}_{G M}(\tau)=\sum_{\gamma \in \mathcal{P}_{x, y}} \frac{e^{i \int_{\gamma} \beta}}{\ell(\gamma)}\left(e^{-i \tau \ell(\gamma)}-e^{i \tau \ell(\gamma)}\right)=\lim _{\alpha \rightarrow 0^{+}} \sum_{\gamma \in \mathcal{P}_{x, y}} \frac{e^{i \int_{\gamma} \beta}}{\ell(\gamma)}\left(e^{-(i \tau+\alpha) \ell(\gamma)}-e^{-(-i \tau+\alpha) \ell(\gamma)}\right)
$$

This is an odd distribution and, according to (8.38), it is smooth near $\tau=0$ since $\beta_{0} \notin \mathbb{Z}^{d}$.
Next, from (8.38), one knows that

$$
\begin{aligned}
\widehat{\mu}_{G M}(\tau)=2^{d-1} \pi^{\frac{d-1}{2}} & \Gamma\left(\frac{d-1}{2}\right) e^{i(f(y)-f(x))} \\
& \times \lim _{\alpha \rightarrow 0^{+}}\left(\left((i \tau+\alpha)^{2}-4 \pi^{4} \Delta_{\beta_{0}}\right)^{-\frac{d-1}{2}}-\left((-i \tau+\alpha)^{2}-4 \pi^{4} \Delta_{\beta_{0}}\right)^{-\frac{d-1}{2}}\right)(x, y)
\end{aligned}
$$

As $\widehat{\mu}_{G M}$ is odd and smooth near 0 , we just need to understand this distribution for $\tau>0$. To do that, we write that, for $\lambda>0$ and $\tau>0$,

$$
\begin{aligned}
\lim _{\alpha \rightarrow 0^{+}}\left(\left((i \tau+\alpha)^{2}+\lambda^{2}\right)^{-\frac{d-1}{2}}-\right. & \left.\left((-i \tau+\alpha)^{2}+\lambda^{2}\right)^{-\frac{d-1}{2}}\right) \\
& =\frac{1}{(\tau+\lambda)^{\frac{d-1}{2}}} \lim _{\alpha \rightarrow 0^{+}}\left((\tau-\lambda-i \alpha)^{-\frac{d-1}{2}}-(\tau-\lambda+i \alpha)^{-\frac{d-1}{2}}\right)
\end{aligned}
$$

Implementing [Hör03, Eq. (3.2.11), p.72] one more time, one finds

$$
\lim _{\alpha \rightarrow 0^{+}}\left(\left((i \tau+\alpha)^{2}+\lambda^{2}\right)^{-\frac{d-1}{2}}-\left((-i \tau+\alpha)^{2}+\lambda^{2}\right)^{-\frac{d-1}{2}}\right)=\frac{(-1)^{\frac{d-3}{2}} 2 i \pi}{\Gamma\left(\frac{d-1}{2}\right)(\tau+\lambda)^{\frac{d-1}{2}}} \delta^{\left(\frac{d-3}{2}\right)}(\tau-\lambda)
$$

We can now rewrite $\widehat{\mu}_{G M}(\tau)$ using this formula. It yields, for $\tau>0$,

$$
\widehat{\mu}_{G M}(\tau)=i(-1)^{\frac{d-3}{2}} 2^{d} \pi^{\frac{d+1}{2}} e^{i(f(y)-f(x))} \sum_{\xi \in \mathbb{Z}^{d}} \frac{1}{\left(\tau+2 \pi\left|\xi+\beta_{0}\right|\right)^{\frac{d-1}{2}}} \delta^{\left(\frac{d-3}{2}\right)}\left(\tau-2 \pi\left|\xi+\beta_{0}\right|\right)
$$

Recalling that $\widehat{\mu}_{G M}$ is smooth near 0 and odd, this completely determines the Fourier transform and concludes the proof of the propotition.

Remark 8.20. Recall that in Theorem 1.7, we are rather interested (in the more general setting of two convex sets) by a renormalized version of (8.37), namely

$$
\tilde{\mu}_{G M}(t):=e^{\frac{i \pi}{4}(d-1)} \sum_{\gamma \in \mathcal{P}_{x, y}} \frac{e^{i \int_{\gamma} \beta}}{\ell(\gamma)^{\frac{d-1}{2}}} \delta(t-\ell(\gamma))+e^{-\frac{i \pi}{4}(d-1)} \sum_{\gamma \in \mathcal{P}_{x, y}} \frac{e^{i \int_{\gamma} \beta}}{\ell(\gamma)^{\frac{d-1}{2}}} \delta(t+\ell(\gamma))
$$

In particular, when $d=5$, one has

$$
\widehat{\tilde{\mu}}_{G M}(\tau)=-\sum_{\gamma \in \mathcal{P}_{x, y}} \frac{e^{i \int_{\gamma} \beta}}{\ell(\gamma)^{2}}\left(e^{i \tau \ell(\gamma)}+e^{-i \tau \ell(\gamma)}\right), \quad \widehat{\tilde{\mu}}_{G M}^{\prime}(\tau)=\widehat{\mu}_{G M}(\tau)
$$

and, thanks to Proposition 8.19, the remainder $r$ in Theorem 1.7 is not identically 0 (as $r^{\prime}(\tau)$ is a combination of Dirac distributions). A similar remark holds for $d \geq 5$.

## 9. Geometric interpretation of the residues

In this Section, we aim at computing somehow explicitly the residues appearing in (8.23) in terms of geometric quantities. We will always suppose in the following that $\beta=0$ which will make the content of this residue more geometric. Along the way, we will prove Theorem 1.3 from the introduction.

Before giving a geometric interpretation of these residues, recall that the admissible manifolds $\Sigma_{1}$ and $\Sigma_{2}$ used to define our generalized Epstein zeta functions are constructed from two compact and strictly convex subsets $K_{1}$ and $K_{2}$ of $\mathbb{R}^{d}$ with smooth boundaries $\partial K_{1}$ and $\partial K_{2}$ (possibly reduced to a point). The submanifolds $\Sigma_{i}$ are parametrized through the inverse Gauss map $\tilde{x}_{i}: \mathbb{S}^{d-1} \rightarrow \mathbb{T}^{d}$ (using the convention that $\partial K_{i}$ is oriented using the outward normal vector to $K_{i}$ ). In order to take the various possibilities for our orthospectrum (outward or inward pointing geodesics), we introduced orientation parameters $\sigma_{i} \in\{ \pm\}$ and we have set

$$
\tilde{x}_{i}^{\sigma_{i}}(\theta)=\tilde{x}_{i}\left(\sigma_{i} \theta\right)
$$

When $\sigma_{i}=+$ (resp. $\sigma_{i}=-$ ), it means that $\Sigma_{i}=\mathfrak{p}\left(\partial K_{i}\right)$ is oriented using the outward (resp. inward) normal vector to $K_{i}$.
9.1. Some simple cases. In Remark 8.15, we saw that the residue at $s=d$ for the Epstein zeta function has an explicit expression. Let us now discuss a couple of other simple cases that do not require to introduce definitions from convex geometry.
9.1.1. The case $d=2$. When $d=2$, the residue at $s=1$ reads

$$
\begin{aligned}
\operatorname{Res}_{s=1}\left(\zeta_{0}\left(K_{2}, K_{1}, s\right)\right) & =-\frac{1}{(2 \pi)^{4}} \int_{\mathbb{T}^{2} \times \mathbb{S}^{1}} d x_{1} \wedge d x_{2} \wedge \mathbf{T}_{\tilde{x}_{1}^{\sigma_{1}}-\tilde{x}_{2}^{\sigma_{2}} \iota}^{*}\left(d x_{1} \wedge d x_{2}\right) \\
& =-\frac{1}{(2 \pi)^{4}} \int_{\mathbb{T}^{2} \times \mathbb{S}^{1}} d x_{1} \wedge d x_{2} \wedge \mathbf{T}_{\tilde{x}_{1}^{\sigma_{1}}-\tilde{x}_{2}^{\sigma_{2}}}^{*}\left(\theta_{1} d x_{2}-\theta_{2} d x_{1}\right) \\
& =-\frac{1}{(2 \pi)^{4}} \int_{\mathbb{T}^{2} \times \mathbb{S}^{1}} d x_{1} \wedge d x_{2} \wedge\left(\theta_{1} d \tilde{x}_{1,2}^{\sigma_{1}}-\theta_{2} d \tilde{x}_{1,1}^{\sigma_{1}}\right) \\
& +\frac{1}{(2 \pi)^{4}} \int_{\mathbb{T}^{2} \times \mathbb{S}^{1}} d x_{1} \wedge d x_{2} \wedge\left(\theta_{1} d \tilde{x}_{2,2}^{\sigma_{2}}-\theta_{2} d \tilde{x}_{2,1}^{\sigma_{2}}\right) \\
& =-\frac{1}{(2 \pi)^{2}} \int_{\mathbb{S}^{1}}\left(\theta_{1} d \tilde{x}_{1,2}^{\sigma_{1}}-\theta_{2} d \tilde{x}_{1,1}^{\sigma_{1}}\right)+\frac{1}{(2 \pi)^{2}} \int_{\mathbb{S}^{1}}\left(\theta_{1} d \tilde{x}_{2,2}^{\sigma_{2}}-\theta_{2} d \tilde{x}_{2,1}^{\sigma_{2}}\right)
\end{aligned}
$$

where we wrote $\tilde{x}_{i}^{\sigma_{i}}(\theta)=\left(\tilde{x}_{i, 1}^{\sigma_{i}}(\theta), \tilde{x}_{i, 2}^{\sigma_{i}}(\theta)\right) \in \mathbb{T}^{2}$. Recalling that $\tilde{x}_{i}(\theta)=\mathfrak{p}\left(x_{i}(\theta)\right)$ is the projection on $\mathbb{T}^{2}$ of the boundary curve for $K_{i}$, this can equivalently be rewritten as

$$
\operatorname{Res}_{s=1}\left(\zeta_{0}\left(K_{2}, K_{1}, s\right)\right)=-\frac{1}{(2 \pi)^{2}} \int_{\mathbb{S}^{1}}\left(\theta_{1} d x_{1,2}^{\sigma_{1}}-\theta_{2} d x_{1,1}^{\sigma_{1}}\right)+\frac{1}{(2 \pi)^{2}} \int_{\mathbb{S}^{1}}\left(\theta_{1} d x_{2,2}^{\sigma_{2}}-\theta_{2} d x_{2,1}^{\sigma_{2}}\right)
$$

Hence, we recognize the volume forms of $\partial K_{1}$ and $\partial K_{2}$ which are either oriented with the outward $\left(\sigma_{i}=+\right)$ or inward $\left(\sigma_{i}=-\right)$ normal vector to the convex set. Hence,

$$
\begin{equation*}
\operatorname{Res}_{s=1}\left(\zeta_{0}\left(K_{2}, K_{1}, s\right)\right)=\frac{1}{(2 \pi)^{2}}\left(\sigma_{2} \operatorname{Vol}\left(\partial K_{2}\right)-\sigma_{1} \operatorname{Vol}\left(\partial K_{1}\right)\right) \tag{9.1}
\end{equation*}
$$

9.1.2. The case where $\Sigma_{2}$ is reduced to a point. We now discuss the residue at $s=1$ when $\Sigma_{2}$ is reduced to a point and when $d \geq 2$. In that case, following the same lines as for $d=2$, the residue can be written as

$$
\begin{aligned}
\operatorname{Res}_{s=1}\left(\zeta_{0}\left(K_{2}, K_{1}, s\right)\right) & =\frac{(-1)^{d-1}}{(2 \pi)^{2 d}} \int_{S^{d}} d x_{1} \wedge \ldots \wedge d x_{d} \wedge \iota_{V} \mathbf{T}_{\tilde{x}_{1}^{\sigma_{1}}}^{*}\left(d x_{1} \wedge \ldots \wedge d x_{d}\right) \\
& =\frac{(-1)^{d-1}}{(2 \pi)^{d}} \int_{\mathbb{S}^{d-1}} \sum_{l=1}^{d}(-1)^{l+1} \theta_{l} d x_{1,1}^{\sigma_{1}} \wedge \ldots \wedge \widehat{d x_{1, l}^{\sigma_{1}}} \wedge \ldots \wedge d x_{1, d}^{\sigma_{1}}
\end{aligned}
$$

One more time, as $\theta$ is the normal to $\partial K_{1}$ at $x_{1}(\theta)$, we recognize the volume form on $\partial K_{1}$ endowed with orientation induced by $\sigma_{1}$. Therefore, when $\sigma_{1}=+$ and up to the factor $(2 \pi)^{d}$, we find that this is equal to $(-1)^{d-1} \operatorname{Vol}\left(\partial K_{1}\right)$. When $\sigma_{1}=-$, we find $\operatorname{Vol}\left(\partial K_{1}\right)$. In a more compact way, we write

$$
\begin{equation*}
\operatorname{Res}_{s=1}\left(\zeta_{0}\left(K_{2}, K_{1}, s\right)\right)=\frac{(-1)^{\frac{\left(1 \sigma_{1} 1\right)(d-1)}{2}}}{(2 \pi)^{d}} \operatorname{Vol}\left(\partial K_{1}\right) \tag{9.2}
\end{equation*}
$$

9.2. Volumes in convex geometry. In this paragraph, we suppose that $\sigma_{1}=-$ and that $\sigma_{2}=+$. Equivalently, it means that we consider geodesic arcs that go from $\Sigma_{2}$ to $\Sigma_{1}$ and that point outside $K_{2}$ and inward $K_{1}$ (when lifted to $\mathbb{R}^{d}$ ). Let $1 \leq \ell \leq d$. Thanks to (8.20)-(8.21), we now compute the coefficients $E_{0}^{(\ell-1)}$ or equivalently the residues

$$
\operatorname{Res}_{s=\ell}\left(\zeta_{0}\left(K_{2}, K_{1}, s\right)\right)=\frac{(-1)^{\ell+d}}{(2 \pi)^{2 d}(\ell-1)!} \int_{S \mathbb{T}^{d}} d x_{1} \wedge \ldots \wedge d x_{d} \wedge \mathbf{T}_{\tilde{x}_{1}^{-}-\tilde{x}_{2}^{+} \iota_{V}}^{*} \mathbf{V}^{\ell-1}\left(d x_{1} \wedge \ldots \wedge d x_{d}\right)
$$

It will be more convenient to lift this expression as an integral on $\mathbb{R}^{d} \times \mathbb{S}^{d-1}$. To do that, we introduce the following vector fields on $\mathbb{R}^{d} \times \mathbb{S}^{d-1}$ :

$$
V_{K_{i}}^{+}:=x_{i}(\theta) \cdot \partial_{x}, \quad V_{K_{i}}^{-}:=x_{i}(-\theta) \cdot \partial_{x} \quad \text { and } \quad V:=\theta \cdot \partial_{x}
$$

where we recall that $\theta \in \mathbb{S}^{d-1} \mapsto x_{i}(\theta) \in \mathbb{R}^{d}$ is the inverse Gauss map associated with the convex $K_{i}$ (used to define $\Sigma_{i}$ ). We denote by $e^{t V_{K}^{ \pm}}$the corresponding flows on $S \mathbb{R}^{d}$. We also observe that $V$ is just the geodesic vector field on $S \mathbb{R}^{d}$ and that it could be written as $V_{B_{d}}^{+}$with these conventions (where $B_{d}$ is the unit ball of $\mathbb{R}^{d}$ ). Finally, one has

$$
V_{-K_{i}}^{+}=-V_{K_{i}}^{-},
$$

and thus we will drop the exponents $\pm$ and just write $V_{K}=V_{K}^{+}$.
With these notations at hand, the residue at $s=\ell$ can be rewritten as

$$
\begin{aligned}
\operatorname{Res}_{s=\ell} & \left(\zeta_{0}\left(K_{2}, K_{1}, s\right)\right) \\
& =\frac{(-1)^{\ell+d}}{(2 \pi)^{d}(\ell-1)!} \int_{S \mathbb{R}^{d}} \delta_{0}^{\mathbb{R}^{d}}(x) d x_{1} \wedge \ldots \wedge d x_{d} \wedge e^{-V_{-K_{1}} *} e^{-V_{K_{2}}{ }^{*} \iota_{V}} \mathbf{V}^{\ell-1}\left(d x_{1} \wedge \ldots \wedge d x_{d}\right)
\end{aligned}
$$

Observe now that

$$
\begin{aligned}
& \int_{S \mathbb{R}^{d}}\left[S_{0} \mathbb{R}^{d}\right] \wedge e^{-V_{-K_{1}} *} e^{-V_{K_{2}} *} \iota_{V} e^{-t V *}\left(d x_{1} \wedge \ldots \wedge d x_{d}\right) \\
&=\sum_{\ell=1}^{d} \frac{(-t)^{\ell-1}}{(\ell-1)!} \int_{S \mathbb{R}^{d}}\left[S_{0} \mathbb{R}^{d}\right] \wedge e^{-V_{-K_{1}} *} e^{-V_{K_{2}} *} \iota_{V} \mathbf{V}^{\ell-1}\left(d x_{1} \wedge \ldots \wedge d x_{d}\right)
\end{aligned}
$$

where $\left[S_{0} \mathbb{R}^{d}\right]=\delta_{0}^{\mathbb{R}^{d}}(x) d x_{1} \wedge \ldots \wedge d x_{d}$ is the current of integration on $S_{0} \mathbb{R}^{d}:=\{0\} \times \mathbb{S}^{d-1}$. In particular, one has

$$
\begin{equation*}
\frac{(-1)^{d-1}}{(2 \pi)^{d}} \int_{S \mathbb{R}^{d}}\left[S_{0} \mathbb{R}^{d}\right] \wedge e^{-\left(V_{-K_{1}}+V_{K_{2}}+V_{t B_{d}}\right) *} \iota_{V}\left(d x_{1} \wedge \ldots \wedge d x_{d}\right)=\sum_{\ell=1}^{d} t^{\ell-1} \operatorname{Res}_{s=\ell}\left(\zeta_{0}\left(K_{2}, K_{1}, s\right)\right) \tag{9.3}
\end{equation*}
$$

We now aim at expressing the left hand side of (9.3) in terms of the intrinsic volumes appearing in Steiner's formula (1.3).
9.2.1. A reminder on convex geometry. Let $K$ be a compact and convex subset of $\mathbb{R}^{d}$ (not necessarily strictly convex or with a smooth boundary). Following [Sch14, §1.7], we define the supporting hyperplane to $K$ with exterior normal $v \in \mathbb{R}^{d} \backslash\{0\}$ as

$$
H(K, v):=\left\{w \in \mathbb{R}^{d}: v \cdot w=\max _{x \in K} v \cdot x\right\}
$$

Note that the maximum in this definition is necessarily attained at a point $x_{0} \in \partial K$. In particular, if a point $x$ lies in $H(K, v) \cap K$, then it belongs to $\partial K$. For such a point, $v$ is called an outward normal vector of $K$ at $x$. Then, the normal bundle $N_{x}(K)$ to $K$ at the point $x$ consists into the collection of all the outward normal vectors of $K$ at $x$ together with the zero vector [Sch14, §2.2].

Remark 9.1. Note that for strictly convex smooth domains, as considered in the present article, $N_{x}(K)$ is a one-dimensional cone. This is not necessarily the case for general convex sets, see for instance $K:=\left\{(x, y) \in \mathbb{R}_{+}^{2}: x+y \leq 1\right\}$ where the reader can convince himself that, at the vertices of the square, the normal bundle contains subcones of the tangent fiber.

In that manner, we can extend the definition given in $\S 8.1$ to any compact and convex subset of $\mathbb{R}^{d}$ :

$$
N_{+}(K):=\bigcup_{x \in K}\left\{(x, v): v \in N_{x}(K)\right\} \cap \mathbb{S}^{d-1}
$$

Given two compact and convex subsets $K$ and $L$ of $\mathbb{R}^{d}$, one has according to [Sch14, Th. 2.2.1]

$$
\begin{equation*}
\forall(x, y) \in K \times L, \quad N_{x+y}(K+L)=N_{x}(K) \cap N_{y}(L) \tag{9.4}
\end{equation*}
$$

In particular, if $K$ and $L$ are two strictly convex bodies with smooth boundaries $N_{x+y}(K+L)$ is not reduced to 0 if and only if the outward unit normal vectors at $x \in \partial K$ and $y \in \partial L$ coincide. We may summarize the formula for the normal bundle of the sum of two strictly convex subsets as

$$
\begin{equation*}
N(K+L)=\{(x+y ; \xi) ;(x ; \xi) \in N(K),(y ; \xi) \in N(L)\} \tag{9.5}
\end{equation*}
$$

where we only take the outgoing normals.
9.2.2. Back to computing residues. Thanks to (9.4), we deduce the following fact of independent interest

Lemma 9.2. Let $K_{1}, K_{2}$ be two smooth strictly convex subsets of $\mathbb{R}^{d}$ whose boundaries $\partial K_{1}, \partial K_{2}$ are parametrized by their outward normals through the maps $\tilde{x}_{1}, \tilde{x}_{2}: \mathbb{S}^{d-1} \mapsto \mathbb{R}^{d}$. Then, the Minkowski sum $K_{1}+K_{2}$ is such that its boundary $\partial\left(K_{1}+K_{2}\right)$ is parametrized by the sum:

$$
\tilde{x}_{1}+\tilde{x}_{2}: \mathbb{S}^{d-1} \mapsto \mathbb{R}^{d}
$$

In particular, the boundary of the compact convex set $K_{2}-K_{1}+t B_{d}$ is parametrized by the map $\theta \in \mathbb{S}^{d-1} \mapsto x_{2}(\theta)-x_{1}(-\theta)+t \theta \in \mathbb{R}^{d}$. Therefore, we can rewrite (9.3) as

$$
\frac{1}{(2 \pi)^{d}} \int_{S \mathbb{R}^{d}}\left[S_{0} \mathbb{R}^{d}\right] \wedge e^{-V_{K_{2}-K_{1}+t B_{d} *} \iota_{V}}\left(d x_{1} \wedge \ldots \wedge d x_{d}\right)=(-1)^{d-1} \sum_{\ell=1}^{d} t^{\ell-1} \operatorname{Res}_{s=\ell}\left(\zeta_{0}\left(K_{2}, K_{1}, s\right)\right)
$$

or equivalently,

$$
\frac{1}{(2 \pi)^{d}} \int_{S \mathbb{R}^{d}} e^{V_{K_{2}-K_{1}+t B_{d}} *}\left[S_{0} \mathbb{R}^{d}\right] \wedge \iota_{V}\left(d x_{1} \wedge \ldots \wedge d x_{d}\right)=(-1)^{d-1} \sum_{\ell=1}^{d} t^{\ell-1} \operatorname{Res}_{s=\ell}\left(\zeta_{0}\left(K_{2}, K_{1}, s\right)\right)
$$

Intertwining the place of $\iota_{V}$ in the integral, we find

$$
\sum_{\ell=1}^{d} t^{\ell-1} \operatorname{Res}_{s=\ell}\left(\zeta_{0}\left(K_{2}, K_{1}, s\right)\right)=\frac{1}{(2 \pi)^{d}} \int_{S \mathbb{R}^{d}} \iota_{V}\left(e^{V_{K_{2}-K_{1}+t B_{d} *}}\left[S_{0} \mathbb{R}^{d}\right]\right) \wedge d x_{1} \wedge \ldots \wedge d x_{d}
$$

Write now that

$$
e^{V_{K_{2}-K_{1}+t B_{d}} *}\left[S_{0} \mathbb{R}^{d}\right]=\delta_{0}\left(x+x_{2}(\theta)-x_{1}(-\theta)+t \theta\right) \bigwedge_{j=1}^{d} d\left(x_{j}+x_{2, j}(\theta)-x_{1, j}(-\theta)+t \theta_{j}\right)
$$

where $\theta$ is the normal to $K_{2}-K_{1}+t B_{d}$ at the point $x_{2}(\theta)-x_{1}(-\theta)+t \theta$. Hence, as in the preliminary examples, we can recognize the volume form of $\partial\left(K_{2}-K_{1}+t B_{d}\right)$ and we obtain

$$
\begin{aligned}
& \sum_{\ell=1}^{d} t^{\ell-1} \operatorname{Res}_{s}=\ell\left(\zeta_{0}\left(K_{2}, K_{1}, s\right)\right) \\
& \\
& =\frac{1}{(2 \pi)^{d}} \int_{\mathbb{R}^{d} \times \partial\left(K_{2}-K_{1}+t B_{d}\right)} \delta_{0}^{\mathbb{R}^{d}}(x-y) d \operatorname{Vol}_{\partial\left(K_{2}-K_{1}+t B_{d}\right)}(y, d y) \wedge d x_{1} \wedge \ldots \wedge d x_{d}
\end{aligned}
$$

which implies

$$
\sum_{\ell=1}^{d} t^{\ell-1} \operatorname{Res}_{s=\ell}\left(\zeta_{0}\left(K_{2}, K_{1}, s\right)\right)=\frac{1}{(2 \pi)^{d}} \operatorname{Vol}\left(\partial\left(K_{2}-K_{1}+t B_{d}\right)\right)
$$

In particular, by the Minkowski-Steiner formula, one finds

$$
\sum_{\ell=1}^{d} t^{\ell-1} \operatorname{Res}_{s=\ell+1}\left(\zeta_{0}\left(K_{2}, K_{1}, s\right)\right)=\frac{1}{(2 \pi)^{d}} \frac{d}{d t} \operatorname{Vol}_{\mathbb{R}^{d}}\left(K_{2}-K_{1}+t B_{d}\right)
$$

Remark 9.3. Observe that we implicitely proved through this calculation that the volume $K_{2}-$ $K_{1}+t B_{d}$ is a polynomial in $t$, or equivalently Steiner's formula (1.3) for such (strictly) convex subsets.

According to (1.3), this last quantity can be expressed in terms of the intrinsic volumes of the convex sets under consideration and we end up with:

Proposition 9.4. Let $K_{1}$ and $K_{2}$ be two stricly convex subsets ${ }^{17}$ of $\mathbb{R}^{d}$, let $\sigma_{1}=+$ and $\sigma_{2}=-$ and let $T_{0}>0$ be large enough to have the meromorphic extension of $\zeta_{0}\left(K_{2}, K_{1}, s\right)$. Then, one has, for every $1 \leq \ell \leq d$,

$$
\operatorname{Res}_{s=\ell}\left(\zeta_{0}\left(K_{2}, K_{1}, s\right)\right)=\frac{\ell}{(2 \pi)^{d}} \frac{\pi^{\frac{\ell}{2}}}{\Gamma\left(\frac{\ell}{2}+1\right)} V_{d-\ell}\left(K_{2}-K_{1}\right)
$$

This concludes the proof of Theorem 1.3.
Remark 9.5. Recall that $2 V_{d-1}\left(K_{2}-K_{1}\right)=\operatorname{Vol}\left(\partial\left(K_{2}-K_{1}\right)\right)$.

## 10. Equidistribution of the boundary of convex bodies

In this final section, we revisit the equidistribution results of Section 5 when convex subsets are involved as in Section 8. More precisely, in all this section, we fix a strictly convex subset $K$ of $\mathbb{R}^{d}$ which has a smooth boundary $\partial K$. Recall that we implicitely allow $K$ to be reduced to a point $x_{0}$. Following $\S 8.1$, the smooth map $x_{K}: \theta \in \mathbb{S}^{d-1} \rightarrow \mathbb{R}^{d}$ parametrizes the boundary $\partial K$ by its ouward normal vector $\theta \in \mathbb{S}^{d-1}$. We then define the strictly convex subset

$$
\forall t \geq 0, \quad K_{t}:=K+t B_{d}
$$

whose boundary $\partial K_{t}$ is parametrized as follows

$$
\partial K_{t}:=\left\{x_{K}(\theta)+t \theta: \theta \in \mathbb{S}^{d-1}\right\}
$$

thanks to $\S 9.2 .1$. Our goal is to decribe the distribution of this submanifold modulo $2 \pi \mathbb{Z}^{d}$, i.e. the distribution as $t \rightarrow+\infty$ of

$$
\begin{equation*}
\Sigma_{t}:=\mathfrak{p}\left(\partial K_{t}\right) \tag{10.1}
\end{equation*}
$$

where we recall that $\mathfrak{p}: \mathbb{R}^{d} \rightarrow \mathbb{T}^{d}$ is the canonical projection. Our main result in that direction reads:

[^15]Theorem 10.1. Let $K$ be a strictly convex subset of $\mathbb{R}^{d}$ which has a smooth boundary $\partial K$. Then, for every $f \in \mathcal{C}^{\infty}\left(\mathbb{T}^{d}\right)$, one has

$$
\frac{1}{\operatorname{Vol}\left(\Sigma_{t}\right)} \int_{\Sigma_{t}} f(x) \operatorname{Vol}_{\Sigma_{t}}(x, d x)=\int_{\mathbb{T}^{d}} f(x) \frac{|d x|}{(2 \pi)^{d}}+\mathcal{O}\left(\|f\|_{H^{2 d+1}\left(\mathbb{T}^{d}\right)} t^{-\frac{d-1}{2}}\right), \quad \text { as } \quad t \rightarrow+\infty
$$

where $\Sigma_{t}$ is the image of $\partial K_{t}$ on $\mathbb{T}^{d}$ as defined in (10.1), $\operatorname{Vol}_{\Sigma_{t}}$ is the volume measure ${ }^{18}$ on $\Sigma_{t}$ induced by the Euclidean structure on $\mathbb{T}^{d}$ and the constant in the remainder only depends on $d$ and $K$.

This Theorem is a variant of a classical result due to Randol [Ran84] who considered the equidistribution of $\partial(t K)$ instead of $\partial\left(K+t B_{d}\right)$. See also [Str89] for further generalizations in the Euclidean setting and [EM93] in the context of Lie groups. The proof of Theorem 10.1 is given in Section 10.2.1 below. In the case where $K$ is reduced to a point, we can get a slightly better remainder - see (10.8) below. See also Remark 10.4 below for more details on the remainder.

As stated in Theorem 10.1, the explicit dependence in $f$ of the remainder also allows us to consider the case where the test function $f$ is a characteristic function. Indeed, let $U$ be some open set of $\mathbb{T}^{d}$ with smooth boundary. Given $\delta>0$, one can fix two smooth functions $f_{\delta, \pm}$ on $\mathbb{T}^{d}$ such that

- $0 \leq f_{\delta, \pm} \leq 1$,
- $f_{\delta,-} \leq \mathbb{1}_{U} \leq f_{\delta,+}$,
- $\left\|f_{\delta, \pm}\right\|_{\mathcal{C}^{k}}=\mathcal{O}\left(\delta^{-k}\right)$ for every $k \geq 0$,
- $\int_{\mathbb{T}^{d}} f_{\delta, \pm}(x)|d x|=\operatorname{Vol}_{\mathbb{T}^{d}}(U)+\mathcal{O}(\delta)$.

One has then

$$
\frac{1}{\operatorname{Vol}\left(\Sigma_{t}\right)} \int_{\Sigma_{t}} f_{\delta,-}(x) \operatorname{Vol}_{\Sigma_{t}}(x, d x) \leq \frac{\operatorname{Vol}\left(\Sigma_{t} \cap U\right)}{\operatorname{Vol}\left(\Sigma_{t}\right)} \leq \frac{1}{\operatorname{Vol}\left(\Sigma_{t}\right)} \int_{\Sigma_{t}} f_{\delta,+}(x) \operatorname{Vol}_{\Sigma_{t}}(x, d x)
$$

Using Theorem 10.1, it yields

$$
\frac{\operatorname{Vol}\left(\Sigma_{t} \cap U\right)}{\operatorname{Vol}\left(\Sigma_{t}\right)}=\frac{\operatorname{Vol}_{\mathbb{T}^{d}}(U)}{(2 \pi)^{d}}+\mathcal{O}(\delta)+\mathcal{O}\left(t^{-\frac{d-1}{2}} \delta^{-(2 d+1)}\right)
$$

from which we infer by taking $\delta=t^{-\frac{d-1}{4(d+1)}}$ that

$$
\frac{\operatorname{Vol}\left(\Sigma_{t} \cap U\right)}{\operatorname{Vol}\left(\Sigma_{t}\right)}=\frac{\operatorname{Vol}_{\mathbb{T}^{d}}(U)}{(2 \pi)^{d}}+\mathcal{O}\left(t^{-\frac{d-1}{4(d+1)}}\right)
$$

For a nice enough subset $U$ satisfying some convexity assumption, and in the case where $K$ is a point (i.e. $\Sigma_{t}$ is the projection on $\mathbb{T}^{d}$ of a sphere of $\mathbb{R}^{d}$ radius $t$ ), then one can be even more precise:

Theorem 10.2. Suppose that the assumption of Theorem 10.1 are satisfied and that $K$ is reduced to a point $x_{0}$. Then, for any open set $U$ of $\mathbb{T}^{d}$ whose boundary $\partial U$ is a smooth, connected, compact and embedded submanifold all of whose sectional curvatures are positive, the function

$$
R(t):=t^{\frac{d-1}{2}}\left(\frac{\operatorname{Vol}\left(\Sigma_{t} \cap U\right)}{\operatorname{Vol}\left(\Sigma_{t}\right)}-\frac{\operatorname{Vol}_{\mathbb{T}^{d}}(U)}{(2 \pi)^{d}}\right)
$$

satisfies the following properties

- its singular support is contained in the set of times $t$ such that $\Sigma_{t}$ is tangent to $\partial U$;
- for every $s>0,\left\|\left(1-\partial_{t}^{2}\right)^{-s} R\right\|_{L^{\infty}\left(\mathbb{R}_{+}\right)} \leqslant C_{U, s}<+\infty$.

This result provides with an accurate analysis of the remainder in our equidistribution statement when one considers projections of large spheres on $\mathbb{T}^{d}$ and when measured with particular test functions (namely characteristic functions of convex open sets). The proof of Theorem 10.2 is given in Section 10.2.2 below. Together with the proof of Theorem 10.1 (and actually with all results presented in this article), it relies on lifting the problem to $S \mathbb{T}^{d}$. The end of Section 10 is devoted to the proofs of Theorems 10.1 and 10.2.

[^16]10.1. Lifting the problem to the unit tangent bundle. As before, this problem takes naturally place in the unit normal bundle of the torus. Hence, we reformulate things in terms of the normal bundle $N_{+}\left(\Sigma_{0}\right)$ of the admissible subset $\Sigma_{0} \subset \mathbb{T}^{d}$ :

Lemma 10.3. Under the assumptions of Theorem 10.1 and for any smooth function $f$, one has

$$
\int_{S \mathbb{T}^{d}} \iota_{V} e^{-t \mathbf{V}}\left[N_{+}\left(\Sigma_{0}\right)\right] \wedge f(x) d x_{1} \wedge \ldots \wedge d x_{d}=(-1)^{d-1} \int_{\Sigma_{t}} f(x) \operatorname{Vol}_{\Sigma_{t}}(x, d x)
$$

where $N_{+}\left(\Sigma_{0}\right)$ was defined in §8.2.
The volume form

$$
\begin{equation*}
P_{K}(t, \theta) \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta, d \theta):=\sum_{\ell=1}^{d}(-1)^{\ell+1} \theta_{\ell} \bigwedge_{j \neq \ell} d\left(\tilde{x}_{j}(\theta)+t \theta_{j}\right) \tag{10.2}
\end{equation*}
$$

will appear at several stages of our proof. Remark that, as $\theta$ is the outward unit normal to $\partial K_{t}$ at $x_{K}(\theta)+t \theta, P_{K}(t, \theta) \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta, d \theta)$ is the volume form on $\partial K_{t}$ induced by the Euclidean structure on $\mathbb{R}^{d}$. We also note that

$$
\begin{equation*}
P_{K}(t, \theta)=t^{d-1}+a_{d-2}(\theta) t^{d-2}+\ldots+a_{0}(\theta) \tag{10.3}
\end{equation*}
$$

is a polynomial whose coefficients depend implicitely on $K$. For simplicity of the expressions in the upcoming proof, we set $a_{d-1}=1$. When $K$ is reduced to a point, $a_{j}(\theta)$ vanishes for every $0 \leq j \leq d-2$. More generally, when $K$ is a Euclidean ball of radius $r \geq 0$ centered at a point of $\mathbb{R}^{d}$, one has $a_{\ell}=\frac{r^{d-1-\ell}(d-1)!}{\ell!(d-1-\ell)!}$ for every $0 \leq \ell \leq d-2$.

Proof. In order to prove this Lemma, we proceed as in Section 9 and recognize the natural volume form on $\Sigma_{0}$. We first note that

$$
e^{-t \mathbf{V}}\left[N_{+}\left(\Sigma_{0}\right)\right]=\delta_{0}(x-\tilde{x}(\theta)-t \theta) \bigwedge_{j=1}^{d} d\left(x_{j}-\tilde{x}_{j}(\theta)-t \theta_{j}\right)=\left[N_{+}\left(\Sigma_{t}\right)\right]
$$

where $\tilde{x}(\theta)=\mathfrak{p}\left(x_{K}(\theta)\right)$ is the boundary map of $\Sigma_{0}$ as in $\S 8.2$. After letting $y=x_{K}(\theta)+t \theta$ and recalling (10.2) one has

$$
\begin{aligned}
\int_{S \mathbb{T}^{d}} \iota_{V} e^{-t \mathbf{V}}\left[N_{+}\left(\Sigma_{0}\right)\right] \wedge & f(x) d x_{1} \wedge \ldots \wedge d x_{d} \\
& =(-1)^{d-1} \int_{\mathbb{T}^{d} \times \partial K_{t}} f(x) \delta_{2 \pi \mathbb{Z}^{d}}(x-y) \operatorname{Vol}_{\partial K_{t}}(y, d y) \wedge d x_{1} \wedge \ldots \wedge d x_{d}
\end{aligned}
$$

from which the Lemma follows
10.2. Equidistribution properties. This paragraph is devoted to the proofs of Theorems 10.1 and 10.2.
10.2.1. Proof of Theorem 10.1. In order to prove this theorem, we shall start from

$$
\int_{S \mathbb{T}^{d}} \iota_{V} e^{-t \mathbf{V}}\left[N_{+}\left(\Sigma_{0}\right)\right] \wedge f(x) d x_{1} \wedge \ldots \wedge d x_{d}
$$

and reexpress it in terms of the oscillatory integrals of Section 4 following the analysis of Section 3. Then, we will be able to implement the arguments of Section 5 up to some (minor) modifications needed to handle the lack of regularity of $\left[N_{+}\left(\Sigma_{0}\right)\right]$ (and possibly of $f$ ). For the moment, we make
the assumption that $f$ is smooth so that

$$
\begin{aligned}
\int_{S \mathbb{T}^{d}} \iota_{V} e^{-t \mathbf{V}}\left[N_{+}\left(\Sigma_{0}\right)\right] & \wedge f(x) d x_{1} \wedge \ldots \wedge d x_{d} \\
& =\sum_{\xi \in \mathbb{Z}^{d}} \widehat{f}_{\xi} \int_{S \mathbb{T}^{d}} \frac{e^{i x \cdot \xi}}{(2 \pi)^{\frac{d}{2}}} \iota_{V} e^{-t \mathbf{V}^{2}}\left[N_{+}\left(\Sigma_{0}\right)\right] \wedge d x_{1} \wedge \ldots \wedge d x_{d} \\
& =\frac{(-1)^{d-1} \operatorname{Vol}\left(\Sigma_{t}\right)}{(2 \pi)^{d}} \int_{\mathbb{T}^{d}} f(x)|d x|+\sum_{\xi \neq 0} \widehat{f}_{\xi} \int_{S \mathbb{T}^{d}} \frac{e^{i x \cdot \xi}}{(2 \pi)^{\frac{d}{2}}} \iota_{V} e^{-t \mathbf{V}^{2}}\left[N_{+}\left(\Sigma_{0}\right)\right] \wedge d x_{1} \wedge \ldots \wedge d x_{d}
\end{aligned}
$$

where we used Lemma 10.3 to rewrite the Fourier coefficient $\xi=0$. Recalling (3.6) and (10.3), this can be rewritten as

$$
\begin{aligned}
& \int_{S \mathbb{T}^{d}} \iota_{V} e^{-t \mathbf{V}}\left[N_{+}\left(\Sigma_{0}\right)\right] \wedge f(x) d x_{1} \wedge \ldots \wedge d x_{d}=\frac{(-1)^{d-1} \operatorname{Vol}\left(\Sigma_{t}\right)}{(2 \pi)^{d}} \int_{\mathbb{T}^{d}} f(x)|d x| \\
&+\frac{(-1)^{d-1}}{(2 \pi)^{\frac{d}{2}}} \sum_{\xi \neq 0} \widehat{f}_{\xi} \int_{\mathbb{S}^{d-1}} e^{i \xi \cdot\left(x_{K}(\theta)+t \theta\right)} P_{K}(t, \theta) \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta, d \theta)
\end{aligned}
$$

Hence, according to Lemma 10.3, one has

$$
\begin{align*}
& \frac{1}{\operatorname{Vol}\left(\Sigma_{t}\right)} \int_{\Sigma_{t}} f(x) \operatorname{Vol}_{\Sigma_{t}}(x, d x)-\int_{\mathbb{T}^{d}} f(x) \frac{|d x|}{(2 \pi)^{d}}  \tag{10.4}\\
&=\frac{1}{(2 \pi)^{\frac{d}{2}} \operatorname{Vol}\left(\Sigma_{t}\right)} \sum_{\ell=0}^{d-1} t^{\ell} \sum_{\xi \neq 0} \widehat{f}_{\xi} \int_{\mathbb{S}^{d-1}} e^{i \xi \cdot\left(x_{K}(\theta)+t \theta\right)} a_{\ell}(\theta) \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta, d \theta)
\end{align*}
$$

We recognize the oscillatory integrals studied in Section 4. In particular, given $f \in \mathcal{C}^{\infty}\left(\mathbb{T}^{d}\right)$, one can make use of Corollaries 4.3 and 4.6 to derive

$$
\frac{1}{\operatorname{Vol}\left(\Sigma_{t}\right)} \int_{\Sigma_{t}} f(x) \operatorname{Vol}_{\Sigma_{t}}(x, d x)=\int_{\mathbb{T}^{d}} f(x) \frac{|d x|}{(2 \pi)^{d}}+\mathcal{O}_{f}\left(t^{-\frac{d-1}{2}}\right)
$$

We can in fact be rather precise about the dependence in $f$. Applying Corollary 4.3 with $N=d$ and Corollary 4.6 with $N=1$, one finds that, for every $0 \leq \ell \leq d-1$, one has

$$
\left|\int_{\mathbb{S}^{d-1}} e^{i \xi \cdot\left(x_{K}(\theta)+t \theta\right)} a_{\ell}(\theta) \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta, d \theta)\right| \leq C_{\ell}|\xi|^{\frac{3 d+1}{2}} t^{-\frac{d-1}{2}}
$$

Hence, one finds

$$
\left|\frac{1}{\operatorname{Vol}\left(\Sigma_{t}\right)} \int_{\Sigma_{t}} f(x) \operatorname{Vol}_{\Sigma_{t}}(x, d x)-\int_{\mathbb{T}^{d}} f(x) \frac{|d x|}{(2 \pi)^{d}}\right| \leq C\|f\|_{H^{2 d+1}\left(\mathbb{T}^{d}\right)} t^{-\frac{d-1}{2}} .
$$

This proves Theorem 10.1.
Remark 10.4. As in Section 5 and for any $f \in \mathcal{C}^{\infty}\left(\mathbb{T}^{d}\right)$, we could in fact get an asymptotic expansion at any order in $t$ by using the full asymptotic expansion given in Corollary 4.6 in order to describe the asymptotics of the integral

$$
\int_{\mathbb{S}^{d-1}} e^{i \xi \cdot\left(x_{K}(\theta)+t \theta\right)} a_{\ell}(\theta) \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta, d \theta)
$$

Finally, revisiting the above argument, one can in fact prove the following result, which considers the asymptotic distribution of the normal cycle $\left[N_{+}\left(\Sigma_{0}\right)\right]$ subject to the geodesic flow on the torus.
Proposition 10.5 (Asymptotic distribution of the normal cycle). Suppose that $\Sigma_{0}$ is admissible in the sense of §8.2. Then, as $t \rightarrow+\infty$, one has

$$
t^{-d+1} e^{-t \mathbf{V}}\left[N_{+}\left(\Sigma_{0}\right)\right]=\frac{(-1)^{d-1}}{(2 \pi)^{\frac{d}{2}}} \sum_{\ell=1}^{d} d \theta_{1} \wedge \ldots \wedge d \theta_{\ell-1} \wedge d x_{\ell} \wedge d \theta_{\ell+1} \wedge \ldots \wedge d \theta_{d}+\mathcal{O}_{\mathcal{D}^{\prime} d\left(S \mathbb{T}^{d}\right)}\left(t^{-1}\right)
$$

Again, we could in fact write the full asymptotic expansion in powers of $t^{-\frac{1}{2}}$ using the full strength of Corollaries 4.3 and 4.6. We do not write this asymptotics for concision and readability.
10.2.2. The case $K=\left\{x_{0}\right\}$ : proof of Theorem 10.2. Let us now be slightly more precise in the case where $K$ is reduced to a point $x_{0}$. In that case, equality (10.4) reads

$$
\begin{align*}
& \frac{1}{\operatorname{Vol}\left(\Sigma_{t}\right)} \int_{\Sigma_{t}} f(x) \operatorname{Vol}_{\Sigma_{t}}(x, d x)=\int_{\mathbb{T}^{d}} f(x) \frac{|d x|}{(2 \pi)^{d}}  \tag{10.5}\\
&+\frac{\Gamma\left(\frac{d}{2}\right)}{2(2 \pi)^{d} \pi^{\frac{d}{2}}} \sum_{\xi \neq 0} \widehat{f}_{\xi} e^{i \xi \cdot x_{0}} \int_{\mathbb{S}^{d-1}} e^{i t \xi \cdot \theta} \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta, d \theta)
\end{align*}
$$

According to Corollaries 4.3 and 4.6, one has

$$
\begin{equation*}
\int_{\mathbb{S}^{d-1}} e^{i t \xi \cdot \theta} \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta, d \theta)=2\left(\frac{2 \pi}{t|\xi|}\right)^{\frac{d-1}{2}} \cos \left(t|\xi|-\frac{\pi}{4}(d-1)\right)+\mathcal{O}\left((t|\xi|)^{-\frac{d+1}{2}}\right) \tag{10.6}
\end{equation*}
$$

from which we infer, for every $s>0$,

$$
\begin{align*}
& \frac{1}{\operatorname{Vol}\left(\Sigma_{t}\right)} \int_{\Sigma_{t}} f(x) \operatorname{Vol}_{\Sigma_{t}}(x, d x)=\int_{\mathbb{T}^{d}} f(x) \frac{|d x|}{(2 \pi)^{d}}  \tag{10.7}\\
& +\frac{\Gamma\left(\frac{d}{2}\right)}{t^{\frac{d-1}{2}}(2 \pi)^{\frac{d+1}{2}} \pi^{\frac{d}{2}}} \sum_{\xi \neq 0}|\xi|^{-\frac{d-1}{2}} \cos \left(t|\xi|-\frac{\pi}{4}(d-1)\right) \widehat{f}_{\xi} e^{i \xi \cdot x_{0}}+\mathcal{O}_{s}\left(\|f\|_{H^{-\frac{1}{2}+s}\left(\mathbb{T}^{d}\right)} t^{-\frac{d+1}{2}}\right)
\end{align*}
$$

We note that the sum is absolutely convergent for $f \in H^{\frac{1}{2}+s}\left(\mathbb{T}^{d}\right)$ as soon as $s>0$ so that when $K=\left\{x_{0}\right\}$, one finds, for every $s>0$,

$$
\begin{equation*}
\frac{1}{\operatorname{Vol}\left(\Sigma_{t}\right)} \int_{\Sigma_{t}} f(x) \operatorname{Vol}_{\Sigma_{t}}(x, d x)=\int_{\mathbb{T}^{d}} f(x) \frac{|d x|}{(2 \pi)^{d}}+\mathcal{O}_{s}\left(\|f\|_{H^{\frac{1}{2}+s}\left(\mathbb{T}^{d}\right)} t^{-\frac{d-1}{2}}\right) \tag{10.8}
\end{equation*}
$$

We can also record from (10.5) and from Plancherel formula the following result on average over $x_{0} \in \mathbb{T}^{d}$ :

Proposition 10.6. There exists a constant $C_{d}>0$, such that, for every $f \in \mathcal{C}^{\infty}\left(\mathbb{T}^{d}\right)$ and for every $t \geq 1$, one has

$$
\int_{\mathbb{T}^{d}}\left|\frac{1}{\operatorname{Vol}\left(\Sigma_{t}\left(x_{0}\right)\right)} \int_{\Sigma_{t}\left(x_{0}\right)} f(x) \operatorname{Vol}_{\Sigma_{t}\left(x_{0}\right)}(x, d x)-\int_{\mathbb{T}^{d}} f(x) \frac{|d x|}{(2 \pi)^{d}}\right|^{2} d x_{0} \leq \frac{C_{d}}{t^{d-1}} \sum_{\xi \neq 0}|\xi|^{-d+1}\left|\widehat{f}_{\xi}\right|^{2}
$$

where $\Sigma_{t}\left(x_{0}\right)$ is the projection on $\mathbb{T}^{d}$ of the Euclidean sphere of radius $t$ centered at $x_{0}$.
Hence, averaging in $x_{0}$ allows to decrease the regularity needed on $f$ to ensure convergence by replacing the $H^{1 / 2+s}$ norm in (10.8) by the $H^{-\frac{d-1}{2}}$-norm. In particular, if $f$ is the characteristic function of some (small) open set $U$, then $f \in L^{2}\left(\mathbb{T}^{d}\right)$ and the righthand side of the above inequality is convergent, i.e.

$$
\int_{\mathbb{T}^{d}}\left|\frac{\operatorname{Vol}\left(\Sigma_{t}\left(x_{0}\right) \cap U\right)}{\operatorname{Vol}\left(\Sigma_{t}\left(x_{0}\right)\right)}-\frac{\operatorname{Vol}_{\mathbb{T}^{d}}(U)}{(2 \pi)^{d}}\right|^{2} d x_{0}=\mathcal{O}\left(t^{-d+1}\right)
$$

One can be even more precise on the regularity of the map

$$
\Phi_{U}:\left(t, x_{0}\right) \in[1, \infty) \times \mathbb{T}^{d} \mapsto t^{\frac{d-1}{2}}\left(\frac{\operatorname{Vol}\left(\Sigma_{t}\left(x_{0}\right) \cap U\right)}{\operatorname{Vol}\left(\Sigma_{t}\left(x_{0}\right)\right)}-\frac{\operatorname{Vol}_{\mathbb{T}^{d}}(U)}{(2 \pi)^{d}}\right)
$$

if one makes extra assumptions on the regularity of $\partial U$. For instance, recall the following consequence of Herz asymptotic formula:

Lemma 10.7. If $U$ is some open set whose boundary $\partial U$ is a smooth, compact and embedded submanifold of $\mathbb{T}^{d}$ and such that the sectional curvatures of $\partial U$ are positive everywhere (so that $U$, viewed as a subset of $\mathbb{R}^{d}$, is a strictly convex set), then the characteristic function $f:=\mathbb{1}_{U}$ verifies

$$
\begin{equation*}
\left|\widehat{f_{\xi}}\right|=\mathcal{O}\left(|\xi|^{-\frac{d+1}{2}}\right) \tag{10.9}
\end{equation*}
$$

Proof. The proof uses the Stokes Theorem combined with Littman's Theorem ${ }^{19}$ [Lit63]. More precisely, the Gauss-Green formula, one writes, for every $1 \leq j \leq d$,

$$
-i \xi_{j} \int_{U} e^{-i x \cdot \xi}|d x|=\int_{\partial U} e^{-i y \cdot \xi} n_{j}(y) \operatorname{Vol}_{\partial U}(y,|d y|)
$$

where $n_{j}(y)$ is the $j$-th component of the outward normal vector $n(y)$ at $y \in \partial U$. Multiplying this equality by $\xi_{j}$ and summing over $j$, one finds

$$
-i|\xi|^{2} \int_{U} e^{-i x \cdot \xi}|d x|=\int_{\partial U} e^{-i y \cdot \xi} \xi \cdot n(y) \operatorname{Vol}_{\partial U}(y|d y|)
$$

Thus, using the strict convexity of $\partial U$, one can apply Littman's formula [Ste93, §VIII.3.1] on the decay of the Fourier transform of surface measures and it yields the expected result.

Hence, equation (10.5) together with the Fourier decay bound (10.9) imply the existence for every $s>0$ of a constant $C_{s, U}>0$ such that

$$
\left\|\left(1-\Delta_{x}\right)^{-s} \Phi_{U}\right\|_{L^{\infty}\left([1, \infty) \times \mathbb{T}^{d}\right)} \leq C_{s, U}
$$

It now remains to discuss the regularity of $\Phi_{U}\left(t, x_{0}\right)$ in $t$ with $x_{0}$ being fixed: this amounts to study the remainder term $R(t)$ in Theorem 10.2. Using equation (10.5) one more time, the Fourier decay bound (10.9) together with (10.6) to control the remainder term in equation (10.5) and the fact that $\left(1-\partial_{t}^{2}\right)^{-s} \cos \left(t|\xi|-\frac{\pi}{4}(d-1)\right)=\mathcal{O}\left(\langle\xi\rangle^{-2 s}\right)$ for every $s>0$, one finds the existence of a constant $\tilde{C}_{s, U}>0$ such that

$$
\forall x_{0} \in \mathbb{T}^{d}, \quad\left\|\left(1-\partial_{t}^{2}\right)^{-s} \Phi_{U}\left(., x_{0}\right)\right\|_{L^{\infty}([1, \infty))} \leq \tilde{C}_{s, U}
$$

which proves the third item of Theorem 10.2. It remains to discuss the local regularity of the remainder term $R=\Phi_{U}\left(., x_{0}\right)$ defined in Theorem 10.2. To that aim, we can apply Lemma 10.3 to $f=\mathbb{1}_{U}$ by density and we find

$$
\begin{aligned}
\operatorname{Vol}\left(\Sigma_{t}\left(x_{0}\right) \cap U\right) & =(-1)^{d-1} \int_{S \mathbb{T}^{d}} \iota_{V} e^{-t \mathbf{V}}\left[S_{x_{0}} \mathbb{T}^{d}\right] \wedge \mathbb{1}_{U}(x) d x_{1} \wedge \ldots \wedge d x_{d} \\
& =t^{d-1} \int_{S \mathbb{T}^{d}} \mathbb{1}_{U}(x) \delta_{0}\left(x-x_{0}-t \theta\right) \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta, d \theta) \wedge d x_{1} \wedge \ldots \wedge d x_{d} \\
& =t^{d-1} \int_{\mathbb{S}^{d-1}} \sum_{\xi \in \mathbb{Z}^{d}} \mathbb{1}_{U}\left(x_{0}+2 \pi \xi+t \theta\right) \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta, d \theta)
\end{aligned}
$$

where, in the last equality, we identify $U$ with a strictly convex subset of $\mathbb{R}^{d}$ and $x_{0}$ with one of its representative in $\mathbb{R}^{d}$. Hence, one has

$$
\frac{\operatorname{Vol}\left(\Sigma_{t}\left(x_{0}\right) \cap U\right)}{\operatorname{Vol}\left(\Sigma_{t}\left(x_{0}\right)\right)}=\frac{\Gamma\left(\frac{d}{2}\right)}{2 \pi^{\frac{d}{2}}} \int_{\mathbb{S}^{d-1}} \sum_{\xi \in \mathbb{Z}^{d}} \mathbb{1}_{U}\left(x_{0}+t \theta+2 \pi \xi\right) \operatorname{Vol}_{d-1}(\theta, d \theta)
$$

Note that, as in $\S 8.4$, the wavefront set of the function $\tilde{f}(y)=\sum_{\xi \in \mathbb{Z}^{d}} \mathbb{1}_{U}\left(y+x_{0}+2 \pi \xi\right)$ is contained in

$$
\bigcup_{\xi \in \mathbb{Z}^{d}}\left\{(y, \eta) \in\left(\partial U-x_{0}-2 \pi \xi\right) \times\left(\left(\mathbb{R}^{d}\right)^{*} \backslash\{0\}\right): \forall v \in T_{y} \partial U, \eta(v)=0\right\}
$$

Now we pullback the function $\tilde{f}$ through the map $\kappa:(t, \theta) \in \mathbb{R}_{>0} \times \mathbb{S}^{d-1} \mapsto t \theta \in \mathbb{R}^{d}$. By the pullback Theorem of Hörmander [Hör03, Th. 8.2.4], $\tilde{f} \circ \kappa$ has wavefront set inside

$$
\left\{\left(t, \theta ;\left(\sum_{j=1}^{d} \eta_{j} \theta_{j}\right) d t, \sum_{j=1}^{d} t \eta_{j} d \theta_{j}\right) \text { s.t. }(t \theta, \eta) \in \mathrm{WF}(\tilde{f})\right\}
$$

[^17]Since

$$
\frac{\operatorname{Vol}\left(\Sigma_{t}\left(x_{0}\right) \cap U\right)}{\operatorname{Vol}\left(\Sigma_{t}\left(x_{0}\right)\right)}=\int_{\mathbb{S}^{d-1}} \sum_{\xi \in \mathbb{Z}^{d}} \mathbb{1}_{U}\left(t \theta+x_{0}+2 \pi \xi\right) \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta, d \theta)=\int_{\mathbb{S}^{d-1}} \tilde{f} \circ \kappa(t, \theta) \operatorname{Vol}_{\mathbb{S}^{d-1}}(\theta, d \theta)
$$

and thanks to the pushforward Theorem [Hör03, Th. 8.2.12], the map $t \mapsto \frac{\operatorname{Vol}\left(\Sigma_{t}\left(x_{0}\right) \cap U\right)}{\operatorname{Vol}\left(\Sigma_{t}\left(x_{0}\right)\right)}$ has its wavefront set inside

$$
\begin{aligned}
\left\{(t, \tau) \in \mathbb{R}_{+} \times \mathbb{R}^{*}:\right. & (t, \theta ; \tau, 0) \in \mathrm{WF}(\tilde{f} \circ \kappa)\} \\
& =\left\{(t, \tau) \in \mathbb{R}_{+} \times \mathbb{R}^{*}: \exists \theta \in \mathbb{S}^{d-1} \text { such that } t \theta \in \tilde{\Sigma}\left(x_{0}\right), \tau \theta \perp T_{t \theta} \tilde{\Sigma}\left(x_{0}\right)\right\}
\end{aligned}
$$

where

$$
\tilde{\Sigma}\left(x_{0}\right):=\bigcup_{\xi \in \mathbb{Z}^{d}}\left(\partial U-x_{0}-2 \pi \xi\right)
$$

In particular, this allows to bound the singular support of both functions $\frac{\operatorname{Vol}\left(\Sigma_{t}\left(x_{0}\right) \cap U\right)}{\operatorname{Vol}\left(\Sigma_{t}\left(x_{0}\right)\right)}$ and $R(t)$ appearing in Theorem 10.2. Geometrically speaking, we are saying that $R$ is smooth outside the set of times where the sphere $t \mathbb{S}^{d-1}$ is tangent to $\cup_{\xi \in \mathbb{Z}^{d}}\left(\partial U-x_{0}-2 \pi \xi\right)$. Arguing as at the beginning of $\S 8.3$, one can verify that these singularities form a discrete subset for $t$ large enough:
Lemma 10.8. There exists $T_{0}>0$ such that, for every $t \geqslant T_{0}$, the set of times $t$ when the scaled sphere $t \mathbb{S}^{d-1}$ is tangent to $\cup_{\xi \in \mathbb{Z}^{d}}\left(\partial U-x_{0}-2 \pi \xi\right)$ is locally finite and the tangency occurs at a finite number of points of $t \mathbb{S}^{d-1}$.

## Appendix A. Another formula for zeta functions

We now briefly explain how to prove (2.1) without appealing the theory of De Rham currents and how it may slightly simplify the exposition of the proofs of Theorems 1.2, 1.3 and 1.4. Yet, this would be at the expense of loosing the dynamical pictures behind these results and thus the relation of these results with our other (more clearly dynamical) applications. Recall also that this formula only holds a priori for a specific choice of orientations for $K_{1}$ and $K_{2}$ while our current theoretic approach allows to handle any orientation convention and to easily implement exponential weights in our zeta functions.

First, from $\S 8.1, \partial K_{1}$ and $\partial K_{2}$ can be parametrized by their outward normal vector $\theta \in \mathbb{S}^{d-1}$ through the maps $x_{K_{j}}: \mathbb{S}^{d-1} \rightarrow \mathbb{R}^{d}, j \in\{1,2\}$. Moreover, according to $\S 9.2 .1$, the maps

$$
\theta \mapsto x_{K_{1}}(\theta)-x_{K_{2}}(-\theta)+t \theta
$$

parametrize the boundary of the convex set $K_{1}-K_{2}+t B_{d}$ for every $0 \leq t \leq T$. Let us now remark that $\gamma$ belongs to $\mathcal{P}_{K_{1}, K_{2}}$ with $0<\ell(\gamma)=t \leq T$ if and only if there exist $\theta \in \mathbb{S}^{d-1}$ and $\xi \in \mathbb{Z}^{d}$ such that

$$
x_{K_{2}}(-\theta)=x_{K_{1}}(\theta)+t \theta-2 \pi \xi
$$

Equivalently, it means that there exists $\xi \in \mathbb{Z}^{d}$ such that $2 \pi \xi$ belongs to $\partial\left(K_{1}-K_{2}+t \theta\right)$. Hence, elements $\gamma$ in $\mathcal{P}_{K_{1}, K_{2}}$ are in one-to-one correspondance with the set

$$
2 \pi \mathbb{Z}^{d} \cap\left(K_{1}-K_{2}+T B_{d}\right) \backslash\left(K_{1}-K_{2}\right)
$$

Now observe that the restriction of the Lebesgue measure to the set $\left(K_{1}-K_{2}+T B_{d}\right) \backslash\left(K_{2}-K_{1}\right)$ can be disintegrated as follows

$$
\int_{0}^{T} \delta_{\partial\left(K_{1}-K_{2}+t B_{d}\right)}(x,|d x|)|d t|
$$

so that

$$
\sharp\left\{\gamma \in \mathcal{P}_{K_{1}, K_{2}}: 0 \leq \ell(\gamma) \leq T\right\}=\int_{\mathbb{R}^{d}} \delta_{[0]}(x) \int_{0}^{T} \delta_{\partial\left(K_{1}-K_{2}+t B_{d}\right)}(x,|d x|)|d t|,
$$

with $\delta_{[0]}$ defined in (2.2). Similarly, if we weight the Lebesgue measure with $\chi(t)$ on each sublevel $\partial\left(K_{1}-K_{2}+t \theta\right)$, we derive formula (2.1) from the introduction. Now, in order to prove our theorems on convex geometry from this formula, one would need to decompose $\delta_{[0]}(x)$ according to (2.2) and to make sense of the right side after this decomposition for the functions $t^{-s}$ and $e^{-s t}$.

For $\operatorname{Re}(s)$ large enough, this is not a problem through a direct calculation. Then, one would need to make the meromorphic continuation of the right hand side through the natural threshold. This could be achieved by reducing to the oscillatory integrals of Section 4 (through the parametrization of $K_{1}-K_{2}+t B_{d}$ by $\theta$ as in Sections 8 and 9 ) and by arguing as in Section 7 with the simplifications that we only deal with $\delta$ functions rather than general test functions (as in $\S 8.6$ and 8.7). Thus, the analytical difficulties would remain exactly the same through this approach. The main advantage would be that the fact that the residues involve the intrinsic volume would be more direct (from the analysis of the Fourier mode 0).

## Acknowledgements

We warmly thank B. Chantraine, N.B. Dang, F. Faure, Y. Guedes-Bonthonneau, D. Han-Kwan and J. Viola for interesting discussions related to this work. ML and GR are partially supported by the Agence Nationale de la Recherche through the PRC grant ADYCT (ANR-20-CE40-0017). GR also acknowledges the support of the Institut Universitaire de France and of the PRC grant ODA from the Agence Nationale de la Recherche (ANR-18-CE40-0020).

## References

[ABdMG96] W.O. Amrein, A. Boutet de Monvel, and V. Georgescu. C0-groups, commutator methods and spectral theory of $N$-body Hamiltonians. Modern Birkhäuser Classics. Birkhäuser/Springer, Basel, 1996. [2013] reprint of the 1996 edition.
[Apo98] T.M. Apostol. Introduction to analytic number theory. Springer Science and Business Media, 1998.
[Art24] E. Artin. Über eine neue art vonL-Reihen. Abh. Math. Sem. Univ. Hamburg, 3(1):89-108, 1924.
[Bal18] V. Baladi. Dynamical zeta functions and dynamical determinants for hyperbolic maps, volume 68 of Ergebnisse der Mathematik und ihrer Grenzgebiete. 3. Folge. A Series of Modern Surveys in Mathematics. Springer, Cham, 2018. A functional approach.
[BAPP19] A. Broise-Alamichel, J. Parkkonen, and F. Paulin. Equidistribution and counting under equilibrium states in negative curvature and trees, volume 329 of Progress in Mathematics. Birkhäuser/Springer, Cham, 2019.
[Bas93] A. Basmajian. The orthogonal spectrum of a hyperbolic manifold. Amer. J. Math., 115(5):1139-1159, 1993.
[BD20] V. Baladi and M.F. Demers. On the measure of maximal entropy for finite horizon Sinai billiard maps. J. Amer. Math. Soc., 33(2):381-449, 2020.
[BDH16] C. Brouder, N.V. Dang, and F. Hélein. Continuity of the fundamental operations on distributions having a specified wave front set (with a counterexample by Semyon Alesker). Studia Math., 232(3):201226, 2016.
[BDL18] V. Baladi, M.F. Demers, and C. Liverani. Exponential decay of correlations for finite horizon Sinai billiard flows. Invent. Math., 211(1):39-177, 2018.
[BK10] M. Bridgeman and J. Kahn. Hyperbolic volume of manifolds with geodesic boundary and orthospectra. Geom. Funct. Anal., 20(5):1210-1230, 2010.
[BL07] O. Butterley and C. Liverani. Smooth Anosov flows: correlation spectra and stability. J. Mod. Dyn., 1(2):301-322, 2007.
[BT16] M. Bridgeman and S.P. Tan. Identities on hyperbolic manifolds. In Handbook of Teichmüller theory. Vol. V, volume 26 of IRMA Lect. Math. Theor. Phys., pages 19-53. Eur. Math. Soc., Zürich, 2016.
[CdV73] Y. Colin de Verdière. Spectre du laplacien et longueurs des géodésiques périodiques. I, II. Compositio Math., 27:83-106; ibid. 27 (1973), 159-184, 1973.
[CdV77] Y. Colin de Verdière. Nombre de points entiers dans une famille homothétique de domains de $\mathbb{R}^{n}$. Ann. Sci. École Norm. Sup. (4), 10(4):559-575, 1977.
[CdVSR20] Y. Colin de Verdière and L. Saint-Raymond. Attractors for two-dimensional waves with homogeneous Hamiltonians of degree 0. Comm. Pure Appl. Math., 73(2):421-462, 2020.
[Cha74] J. Chazarain. Formule de Poisson pour les variétés riemanniennes. Inventiones mathematicae, 24(1):65-82, 1974.
[dCL69] M.P. do Carmo and E. Lima. Isometric immersions with semi-definite second quadratic forms. Arch. Math. (Basel), 20:173-175, 1969.
[DFG15] S. Dyatlov, F. Faure, and C. Guillarmou. Power spectrum of the geodesic flow on hyperbolic manifolds. Anal. PDE, 8(4):923-1000, 2015.
[DG75] J. J. Duistermaat and V. W. Guillemin. The spectrum of positive elliptic operators and periodic bicharacteristics. Invent. Math., 29(1):39-79, 1975.
[DG16] S. Dyatlov and C. Guillarmou. Pollicott-Ruelle resonances for open systems. Ann. Henri Poincaré, 17(11):3089-3146, 2016.
[DGBLR22] N.V. Dang, Y Guedes Bonthonneau, M. Léautaud, and G. Rivière. Analytic correlations on flat tori. 2022. to appear.
[DR18] N.V. Dang and G. Rivière. Equidistribution of the conormal cycle of random nodal sets. J. Eur. Math. Soc. (JEMS), 20(12):3017-3071, 2018.
[DR20] N. V. Dang and G. Rivière. Spectral analysis of Morse-Smale flows I: Construction of the anisotropic spaces. J. Inst. Math. Jussieu, 19(5):1409-1465, 2020.
[DR21] N.V. Dang and G. Rivière. Poincaré series and linking of Legendrian knots. 2021. Preprint arxiv 2005.13235.
[DZ15] S. Dyatlov and M. Zworski. Stochastic stability of Pollicott-Ruelle resonances. Nonlinearity, 28(10):3511-3533, 2015.
[DZ16] S. Dyatlov and M. Zworski. Dynamical zeta functions for Anosov flows via microlocal analysis. Ann. Sci. Éc. Norm. Supér. (4), 49(3):543-577, 2016.
[DZ19a] S. Dyatlov and M. Zworski. Mathematical theory of scattering resonances, volume 200 of Graduate Studies in Mathematics. American Mathematical Society, Providence, RI, 2019.
[DZ19b] S. Dyatlov and M. Zworski. Microlocal analysis of forced waves. Pure Appl. Anal., 1(3):359-384, 2019.
[EM93] A. Eskin and C. McMullen. Mixing, counting, and equidistribution in Lie groups. Duke Math. J., 71(1):181-209, 1993.
[EMOT54] A. Erdélyi, W. Magnus, F. Oberhettinger, and F. G. Tricomi. Tables of integral transforms. Vol. I. McGraw-Hill Book Co., Inc., New York-Toronto-London, 1954. Based, in part, on notes left by Harry Bateman.
[Eps03] P. Epstein. Zur Theorie allgemeiner Zetafunctionen. Math. Ann., 56(4):615-644, 1903.
[Eva10] L.C. Evans. Partial differential equations, volume 19 of Graduate Studies in Mathematics. American Mathematical Society, Providence, RI, second edition, 2010.
[FS11] F. Faure and J. Sjöstrand. Upper bound on the density of Ruelle resonances for Anosov flows. Comm. Math. Phys., 308(2):325-364, 2011.
[FT15] F. Faure and M. Tsujii. Prequantum transfer operator for symplectic Anosov diffeomorphism. Astérisque, (375):ix+222, 2015.
[FT17a] F. Faure and M. Tsujii. Fractal Weyl law for the Ruelle spectrum of Anosov flows. 2017. Preprint arXiv:1706.09307.
[FT17b] F. Faure and M. Tsujii. The semiclassical zeta function for geodesic flows on negatively curved manifolds. Invent. Math., 208(3):851-998, 2017.
[FT21] F. Faure and M. Tsujii. Microlocal analysis of contact Anosov flows and band structure of the Ruelle spectrum. 2021. Preprint arXiv:2102.11196.
[GBJ20] Y. Guedes Bonthonneau and M. Jézequel. FBI transform in Gevrey classes and Anosov flows. 2020. Preprint arXiv:2001.03610.
[GBW17] Y. Guedes Bonthonneau and T. Weich. Ruelle-Pollicott resonances for manifolds with hyperbolic cusps. 2017. Preprint arXiv:1712.07832, to appear JEMS.
[GLP13] P. Giulietti, C. Liverani, and M. Pollicott. Anosov flows and dynamical zeta functions. Ann. of Math. (2), 178(2):687-773, 2013.
[GS] I.M. Gel'fand and G.E. Shilov. Generalized functions i (properties and operations)(1958, english translation 1963).
[Gui59] A. P. Guinand. Concordance and the harmonic analysis of sequences. Acta Math., 101:235-271, 1959.
[GZ19] J. Galkowski and M. Zworski. Viscosity limits for 0th order pseudodifferential operators. 2019. Preprint arXiv:1912.09840, to appear CPAM.
[Had97] J. Hadamard. Sur certaines propriétés des trajectoires en dynamique. J. Math. Pures Appl., 3:331-387, 1897.
[Her62a] C. S. Herz. Fourier transforms related to convex sets. Ann. of Math. (2), 75:81-92, 1962.
[Her62b] C. S. Herz. On the number of lattice points in a convex set. Amer. J. Math., 84:126-133, 1962.
[Hla50] E. Hlawka. Über Integrale auf konvexen Körpern. I. Monatsh. Math., 54:1-36, 1950.
[Hör85] L. Hörmander. The analysis of linear partial differential operators. III, volume 274. Springer-Verlag, Berlin, 1985. Pseudodifferential operators.
[Hör03] L. Hörmander. The analysis of linear partial differential operators. I. Classics in Mathematics. Springer-Verlag, Berlin, 2003. Distribution theory and Fourier analysis, Reprint of the second (1990) edition.
[HR17] H. Hezari and G. Rivière. Quantitative equidistribution properties of toral eigenfunctions. J. Spectr. Theory, 7(2):471-485, 2017.
[Hub56] H. Huber. Über eine neue Klasse automorpher Funktionen und ein Gitterpunktproblem in der hyperbolischen Ebene. I. Comment. Math. Helv., 30:20-62 (1955), 1956.
[Hub59] H. Huber. Zur analytischen Theorie hyperbolischen Raumformen und Bewegungsgruppen. Math. Ann., 138:1-26, 1959.
[Jéz21] M. Jézéquel. Global trace formula for ultra-differentiable Anosov flows. Comm. Math. Phys., 385(3):1771-1834, 2021.
[Lee09] J.M. Lee. Manifolds and differential geometry, volume 107 of Graduate Studies in Mathematics. American Mathematical Society, Providence, RI, 2009.
[Lee13] J.M. Lee. Introduction to smooth manifolds, volume 218 of Graduate Texts in Mathematics. Springer, New York, second edition, 2013.
[Lit63] W. Littman. Fourier transforms of surface-carried measures and differentiability of surface averages. Bull. Amer. Math. Soc., 69:766-770, 1963.
[Liv04] C. Liverani. On contact Anosov flows. Ann. of Math. (2), 159(3):1275-1312, 2004.
[LO16] N. Lev and A. Olevskii. Quasicrystals with discrete support and spectrum. Rev. Mat. Iberoam., 32(4):1341-1352, 2016.
[LR21] N. Lev and G. Reti. Poisson summation formulas involving the sum-of-squares function. Israel J. Math., 246(1):403-421, 2021.
[Mar69] G. A. Margulis. Certain applications of ergodic theory to the investigation of manifolds of negative curvature. Funkcional. Anal. i Priložen., 3(4):89-90, 1969.
[Mar04] G.A. Margulis. On some aspects of the theory of Anosov systems. Springer Monographs in Mathematics. Springer-Verlag, Berlin, 2004. With a survey by Richard Sharp: Periodic orbits of hyperbolic flows, Translated from the Russian by Valentina Vladimirovna Szulikowska.
[McS91] G. McShane. A remarkable identity for lengths of curves. ProQuest LLC, Ann Arbor, MI, 1991. Thesis (Ph.D.)-University of Warwick (United Kingdom).
[McS98] G. McShane. Simple geodesics and a series constant over Teichmuller space. Invent. Math., 132(3):607632, 1998.
[Med21] A. Meddane. A Morse complex for axiom A flows. 2021. Preprint arXiv:2107.08875.
[Mey16] Y. Meyer. Measures with locally finite support and spectrum. Proc. Natl. Acad. Sci. USA, 113(12):3152-3158, 2016.
[Mey22] Y. Meyer. Mesures cristallines et applications, d'après p. kurasov, a. olevskii, p. sarnak et m. viazovska. Astérisque, page Exp. No. 1194, 2022. Séminaire Bourbaki, Vol. 2021/2022.
[Pol85] M. Pollicott. On the rate of mixing of Axiom A flows. Invent. Math., 81(3):413-426, 1985.
[PP16] J. Parkkonen and F. Paulin. Counting arcs in negative curvature. In Geometry, topology, and dynamics in negative curvature, volume 425 of London Math. Soc. Lecture Note Ser., pages 289-344. Cambridge Univ. Press, Cambridge, 2016.
[Ran66] B. Randol. A lattice-point problem. Trans. Amer. Math. Soc., 121:257-268, 1966.
[Ran84] B. Randol. The behavior under projection of dilating sets in a covering space. Trans. Amer. Math. Soc., 285(2):855-859, 1984.
[Rat87] M. Ratner. The rate of mixing for geodesic and horocycle flows. Ergodic Theory Dynam. Systems, 7(2):267-288, 1987.
[RS75] Michael Reed and Barry Simon. II: Fourier Analysis, Self-Adjointness, volume 2. Elsevier, 1975.
[Rue76] D. Ruelle. Zeta-functions for expanding maps and Anosov flows. Invent. Math., 34(3):231-242, 1976.
[Rug07] R.O. Ruggiero. Dynamics and global geometry of manifolds without conjugate points, volume 12 of Ensaios Matemáticos [Mathematical Surveys]. Sociedade Brasileira de Matemática, Rio de Janeiro, 2007.
[RV19] D. Radchenko and M. Viazovska. Fourier interpolation on the real line. Publ. Math. Inst. Hautes Études Sci., 129:51-81, 2019.
[Sac60] R. Sacksteder. On hypersurfaces with no negative sectional curvatures. Amer. J. Math., 82:609-630, 1960.
[Sch66] L. Schwartz. Théorie des distributions. Publications de l'Institut de Mathématique de l'Université de Strasbourg, No. IX-X. Hermann, Paris, 1966.
[Sch14] R. Schneider. Convex bodies: the Brunn-Minkowski theory, volume 151 of Encyclopedia of Mathematics and its Applications. Cambridge University Press, Cambridge, expanded edition, 2014.
[Sel56] A. Selberg. Harmonic analysis and discontinuous groups in weakly symmetric Riemannian spaces with applications to Dirichlet series. J. Indian Math. Soc. (N.S.), 20:47-87, 1956.
[Ste93] E. M. Stein. Harmonic analysis: real-variable methods, orthogonality, and oscillatory integrals, volume 43 of Princeton Mathematical Series. Princeton University Press, Princeton, NJ, 1993. With the assistance of Timothy S. Murphy, Monographs in Harmonic Analysis, III.
[Ste09] S. Sternberg. Theory of functions of a real variable. University Press of Florida, 2009.
[Str89] R. S. Strichartz. Magnified curves on a flat torus, determination of almost periodic functions, and the Riemann-Lebesgue lemma. Proc. Amer. Math. Soc., 107(3):755-759, 1989.
[Tei16] B. Teissier. Bonnesen-type inequalities in algebraic geometry, i: Introduction to the problem. In Seminar on Differential Geometry.(AM-102), Volume 102, pages 85-106. Princeton university press, 2016.
[Tsu10] M. Tsujii. Quasi-compactness of transfer operators for contact Anosov flows. Nonlinearity, 23(7):14951545, 2010.
[Tsu12] M. Tsujii. Contact Anosov flows and the Fourier-Bros-Iagolnitzer transform. Ergodic Theory Dynam. Systems, 32(6):2083-2118, 2012.
[vdC20] J. G. van der Corput. Über Gitterpunkte in der Ebene. Math. Ann., 81(1):1-20, 1920.
[Zwo12] M. Zworski. Semiclassical analysis, volume 138 of Graduate Studies in Mathematics. American Mathematical Society, Providence, RI, 2012.

Sorbonne Université, IMJ-PRG, 75252 Paris Cedex 05, France
E-mail address: dang@imj-prg.fr
Laboratoire de Mathématiques d'Orsay, UMR 8628, Université Paris-Saclay, CNRS, Bâtiment 307, 91405 Orsay Cedex France

E-mail address: mathieu.leautaud@universite-paris-saclay.fr
Laboratoire de Mathématiques Jean Leray, Nantes Université, umR CNRS 6629, 2 rue de la Houssinière, 44322 Nantes Cedex 03, France

Institut Universitaire de France, Paris, France
E-mail address: gabriel.riviere@univ-nantes.fr


[^0]:    ${ }^{1}$ In the case where $K_{i}$ is reduced to a point, every geodesic passing through $K_{i}$ is said to be orthogonal to it and we fix the natural orientation using the Euclidean volume on $\mathbb{R}^{d}$.

[^1]:    ${ }^{2} \mathrm{~A}$ functional satisfying such an additive property is referred as a valuation $[$ Sch14, $\S 6.1]$.

[^2]:    ${ }^{3}$ The eigenvalues of $\Delta_{-[\beta]}$ and $\Delta_{[\beta]}$ coincide.

[^3]:    ${ }^{4}$ In particular, both sets are a priori distinct.

[^4]:    ${ }^{5}$ The fact that we aim at dealing with general convex sets (and not only points) seems to prevent us from working with the Laplacian on $\mathbb{T}^{d}$.

[^5]:    ${ }^{6}$ Similar oscillatory integrals will of course appear in our analysis.

[^6]:    ${ }^{7}$ Again, we use the same notation for the current on the base and its pullback on $S \mathbb{T}^{d}$. We keep this convention for simplicity and we will in fact mostly consider the pullback in the following.

[^7]:    ${ }^{8}$ The index $\mathbb{R}$ means that the coefficients of the form are real valued.

[^8]:    ${ }^{9}$ As we shall in the proof, the size of the neighborhood depends only on the geometry of the sphere.

[^9]:    ${ }^{10}$ Thus, $\chi_{1}$ is supported close enough to 1 .
    ${ }^{11}$ Strictly speaking the statement of Th. 3.16 in that reference involves the $\mathcal{C}^{2 N+d}$-norm. Yet, inspecting the proof (namely, step 3 in the proof of p. 43 together with the proof of Lemma 3.5(ii)), one finds a control by the $W^{2 N+d, 1}$-norm.

[^10]:    ${ }^{12}$ Such bundles are well defined on manifolds without conjugate points, e.g. non positively curved manifolds.

[^11]:    ${ }^{13}$ The constant is the one from Lemma 4.2.

[^12]:    ${ }^{14}$ Again this can be equivalently rephrased in terms of the spectrum of $\Delta_{\beta_{0}}$ instead of that of $\Delta_{-\beta_{0}}$ if we change variables $\xi \rightarrow-\xi$ as in (5.4).

[^13]:    ${ }^{15}$ The proof in that reference is given for a linear space and it can be transfered to submanifolds through a local chart thanks to [Hör03, Th. 8.2.4]. See Example 8.2.5 in that reference.

[^14]:    ${ }^{16}$ We restablish the dependence in the orientation to get the expected cancellation.

[^15]:    ${ }^{17}$ Recall that we denote by $\Sigma_{i}$ the corresponding admissible submanifolds on $\mathbb{T}^{d}$.

[^16]:    ${ }^{18}$ In particular, $\operatorname{Vol}\left(\Sigma_{t}\right)=\int_{\Sigma_{t}} \operatorname{Vol}_{\Sigma_{t}}(x, d x)$.

[^17]:    ${ }^{19}$ In the case we are interested in (strictly convex subsets), the result can also be found in the works of Hlawka [Hla50] and Herz [Her62a].

