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► **To cite this version:**

Michaël Allouche, Emmanuel Gobet, Clara Lage, Edwin Mangin. Structured Dictionary Learning of Rating Migration Matrices for Credit Risk Modeling. Computational Statistics, 2024, 10.1007/s00180-023-01449-y . hal-03715954v2

**HAL Id: hal-03715954**

**<https://hal.science/hal-03715954v2>**

Submitted on 9 Dec 2023

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# Structured Dictionary Learning of Rating Migration Matrices for Credit Risk Modeling

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## Abstract

Rating Migration Matrix is a crux to assess credit risks. Modeling and predicting these matrices are then an issue of great importance for risk managers in any financial institution. As a challenger to usual parametric modeling approaches, we propose a new structured dictionary learning model with auto-regressive regularization that is able to meet key expectations and constraints: small amount of data, fast evolution in time of these matrices, economic interpretability of the calibrated model. To show the model applicability, we present a numerical test with both synthetic and real data and a comparison study with the widely used parametric Gaussian Copula model: it turns out that our new approach based on dictionary learning significantly outperforms the Gaussian Copula model. The source code and the data are available at <https://github.com/michael-allouche/dictionary-learning-RMM.git> for the sake of reproducibility of our research.

**Keywords:** Rating Migration Matrix, Dictionary Learning, Auto-regressive modeling, Interpretability, Gaussian Copula model

# 1 Introduction

## 1.1 Banking context

Credit risk refers to the risk of incurring losses due to unexpected changes in the credit quality of the counterparty. Such a risk is summarized in a structured rating migration matrix which captures all possible transition probabilities that an obligor will migrate from a credit state to another over a given time period (see Figure 1). According to the financial regulation guidelines (Basel II and III), banks can use internal ratings and risk exposure estimations in order to assess regulatory capital requirement and credit risk measures (VaR, ES, ...). See [1, 2, 7, 21] for extensive references on risk measures and credit risk. Rating migration matrices (RMM) are key indicators to assess credit risk portfolio through the estimation of the credit quality of the obligors. Rating allocation process includes models and expert systems taking into account obligors idiosyncratic features evolving over time given the economic situation. Observed migration frequencies are displayed into RMM that are the cornerstone of rating migration models upon which credit risk portfolio simulation relies. The most widely used method for modeling RMM is the one-factor Gaussian Copula (GC) model [13] which assumes that a single factor represents the underlying systemic credit quality in the economy and defines a stationary economic cycle. See [3] among others for estimating risk measures on the loss distribution of a large credit risk portfolio under this model. The popularity of the GC model is due to the ease of use but it also suffers from too simple underlying hypothesis. These weak assumptions lead to miscapture the dependence structure in tails. However, and despite post subprime crisis criticisms [14], the one-factor GC model remains very popular in the banking industry because of its parsimony and of its ability to generate intuitive and interpretable results. The aim of this work is to derive from the data a non parametric representation of RMM, as an alternative and a challenger to the parametric GC model. This work is devoted to the design of a new methodology with thorough tests and a comparison with the GC model.

## 1.2 Matrix Factorization for RMM

Let us start from the data. In practice, we observe at time  $t$  a one-year rating migration matrix  $\mathbf{P}^t \in \mathbb{R}^{R-1} \otimes \mathbb{R}^R$ , which encodes the probability of migrating from rating  $i = 1, \dots, R-1$  to rating  $j = 1, \dots, R$  within one year period starting at time  $t-1$ ; in Figure 1 we have  $R = 11$ . The reconstruction of this matrix is made empirically by evaluating the frequencies of obligors going from the rating  $i$  to rating  $j$  between times  $t-1$  and  $t$ . It is important for risk management purposes to model the evolution of  $\mathbf{P}^t$ , by finding a representation of the type

$$\mathbf{P}^t \approx \sum_{k=1}^K \alpha_k^t \mathbf{d}_k, \quad \forall t \geq 1, \quad (1)$$

	1	2	3	4	5	6	7	8	9	10	11
1	71.48	17.87	5.36	2.38	1.25	0.71	0.43	0.26	0.15	0.08	0.03
2	16.01	57.62	14.41	5.69	2.80	1.54	0.89	0.52	0.30	0.16	0.06
3	5.05	15.14	53.85	13.46	5.89	3.03	1.68	0.96	0.54	0.28	0.11
4	2.45	6.52	14.67	51.35	12.84	5.87	3.06	1.68	0.92	0.47	0.18
5	1.45	3.61	7.23	14.46	49.57	12.39	5.74	2.95	1.55	0.76	0.30
6	0.96	2.31	4.34	7.71	14.46	48.19	12.05	5.51	2.71	1.29	0.48
7	0.70	1.63	2.94	4.90	8.16	14.69	47.00	11.75	5.14	2.28	0.82
8	0.54	1.24	2.18	3.48	5.44	8.71	15.24	45.71	11.43	4.51	1.52
9	0.45	1.02	1.75	2.73	4.09	6.14	9.55	16.38	43.67	10.92	3.28
10	0.43	0.95	1.60	2.43	3.55	5.11	7.46	11.36	19.17	38.35	9.59

**Fig. 1:** Representation of an idealized rating migration matrix of size  $10 \times 11$ . All values are in percentage. The credit quality goes from the highest (rating 1) to the lowest (rating 10), the default is 11.

for some so-called (deterministic) basis vectors  $\mathbf{d}_k$  and for some scalar random coefficients  $\alpha_k^t$  which we should model the evolution. In a matrix form (using the  $\text{vec}()$  operator to simplify, see Section 1.5), we say that the collection of vectorized matrices  $\mathbf{P} = \{\text{vec}(\mathbf{P}^t) \in \mathbb{R}^d\}_{t=1}^T \in \mathbb{R}^d \otimes \mathbb{R}^T$ , with

$$d := (R - 1)R$$

for all  $t = 1, \dots, T$ , admits a matrix factorization over a dictionary  $\mathbf{D} \in \mathbb{R}^d \otimes \mathbb{R}^K$  composed by  $K$  elements (called atoms), if there exists a linear combination of atoms weighted by coefficients (called codings)  $\mathbf{A} = \{\alpha^t \in \mathbb{R}^K\}_{t=1}^T \in \mathbb{R}^K \otimes \mathbb{R}^T$  such that

$$\mathbf{P} \approx \mathbf{D}\mathbf{A}. \quad (2)$$

### 1.3 Objective

In this work, the objective is to achieve (2) while requiring

- $\mathbf{D}$  to satisfy some linear constraints (see Section 1.5) in order to represent economically interpretable RMM,
- the time series of elements  $\alpha^t$  of  $\mathbf{A}$  to be smooth enough in order to get stability in the representation and to perform simulations/predictions through a time series modeling,
- consider a dimensionality reduction framework  $K \ll d$  in order to work in a lower dimensional space with extracted meaningful information.

However, the RMM evolution may vary quickly over time and a limited data history is available (usually 10-20 years  $\approx 200$  observations) which is close to

the dimension of the problem (usually  $R = 11$  and  $d = 110$ ). Thus, modeling constrained RMM in a data-based non-parametric way presents an important challenge, which has not been addressed so far to the best of our knowledge.

## 1.4 State of the art

Over the last years, a new paradigm of data-based models have emerged in the Machine Learning (ML) community in order to extract structured information from high-dimensional objects. A classical approach in ML is to use Matrix Factorization techniques in order to project the data in some relevant basis. It is well known that the optimal basis that minimizes the linear approximation error is the Karhunen-Loève basis [20, Theorem 9.8], also known as the principal components in the principal component analysis (PCA).

Introduced in [24], dictionary learning (DL), see [9] for an overview and [12] for theoretical results, is another matrix representation technique where the basis, called dictionary, is learned from the observations. Unlike in the PCA decomposition, neither the orthogonality nor the representation constraints of the basis vectors (atoms) are imposed, allowing more flexibility to adapt the desired representation to the data. Moreover, compared with a predefined dictionary like Gabor functions, wavelets or local cosine vectors [20], learning a dictionary adapted to the observations has shown better results in practice [10, 17].

In DL, the linear approximation (2) is usually coupled with a regularization criterion  $\mathcal{R}(\mathbf{A})$  applied to the codings and yields to the general optimization problem

$$\min_{\mathbf{D}, \mathbf{A}} \|\mathbf{P} - \mathbf{D}\mathbf{A}\|_F^2 + \lambda \mathcal{R}(\mathbf{A}), \quad \lambda \geq 0, \quad (3)$$

where the regularization term shall reflect the expected codings representation, see [9, Chapter 4]. The most widely studied regularization is  $\mathcal{R}(\mathbf{A}) = \|\mathbf{A}\|_1$  referring to the so-called sparse coding (see [15] for an overview), where the optimization with respect to  $A$  is known as basis pursuit [6] or the Lasso [29]. DL with sparse representation was notably studied in image and video processing [16, 18, 19], in graph learning [30] and in clustering [28]. In the case of spatial data, and more precisely in image processing, Total Variation (TV) plays an important role. In one dimension we have  $\mathcal{R}_{TV}(\mathbf{A}) = \sum_{t=1}^{T-1} \sum_{k=1}^K |\alpha_k^{t+1} - \alpha_k^t|$ , which is the integral of the absolute value of the gradient [26]. The intuition of this type of regularization in images is to allow a smooth transition between close codings and can be understood as a prior in a Bayesian model, see [5].

Here, we rather focus on DL with a temporal structure. This application has been mainly studied in video denoising [19, 25] where the temporal structure is exploited through an operator extracting patches of a fixed size in the objective function representing an energy minimization procedure. Another approach is to deal with an auto-regressive (AR) representation modeled either in the dictionary [8] or in the codings [32]. In the former, a mixed audio

signal is decomposed into its constituent temporal sources (atoms of the dictionary) in order to detect the presence of a specific sound. In the latter, the authors present a framework which supports data-driven temporal learning and forecasting through an AR modelization of the codings represented as a regularization term. Our model described in Section 2 is inspired from this problem formulation.

Our main and original contributions are to

- propose a new RMM modelization technique using DL approach
- derive a DL solution with linear constraints and a temporal regularization term for both interpretable clustering and prediction of RMM
- retrieve an economic health indicator on real data
- confirm the nice reconstruction performance against the one-factor Gaussian Copula model on both real and synthetic data.

The paper is organized as follows. We introduce our proposed model and the associated optimization procedure in Section 2. Then we provide a numerical study on real data in Section 3 with two applications: prediction/simulation and clustering of RMM with economic interpretations. Finally, we challenge in Section 4 the one-factor Gaussian Copula model on both real and synthetic data.

## 1.5 Notations and data constraints

### Notations

Let  $\mathbf{M} \in \mathbb{R}^{d_1} \otimes \mathbb{R}^{d_2}$  be a matrix with  $d_1$  rows and  $d_2$  columns. We use the notation for the  $i$ -th row  $\mathbf{M}_{i,:}$ , for the  $j$ -th column  $\mathbf{M}_{:,j} := \mathbf{m}_j$  and for the sum column-wise

$$M_{i,\geq j} := M_{i,j} + \dots + M_{i,d_2}.$$

The vectorization operator  $\text{vec}(\cdot)$  and its inverse  $\text{vec}^{-1}(\cdot)$  are defined as column-major order, *i.e.*

$$\text{vec}^{-1}\text{vec}(\mathbf{M}) := \text{vec}^{-1}([M_{1,1}, M_{2,1}, \dots, M_{d_1,d_2}]^\top \in \mathbb{R}^{d_1 d_2}) = \mathbf{M}.$$

The Frobenius norm is defined by:

$$\|\mathbf{M}\|_F = \sqrt{\text{Tr}(\mathbf{M}\mathbf{M}^\top)} = \sqrt{\sum_{i \in [d_1], j \in [d_2]} M_{i,j}^2},$$

where  $[d_i] := \{1, \dots, d_i\}$  for  $i \in \{1, 2\}$ . The orthogonal linear projection of a vector  $\mathbf{u} \in \mathbb{R}^u$  onto the space generated by the columns of a matrix  $\mathbf{V} \in \mathbb{R}^{v_1} \otimes \mathbb{R}^{v_2}$ , with  $u = v_1$ , is denoted by  $\text{Proj}_{\mathbf{V}}(\mathbf{u})$ . For a matrix  $\mathbf{U} \in \mathbb{R}^{u_1} \otimes \mathbb{R}^{u_2}$ , ( $u_1 = v_1$ ) with columns  $\{\mathbf{U}_{:,1}, \dots, \mathbf{U}_{:,u_2}\}$ , the projection is defined by

$$\text{Proj}_{\mathbf{V}}(\mathbf{U}) \in \mathbb{R}^{v_2} \otimes \mathbb{R}^{u_2},$$

with columns  $\{\text{Proj}_{\mathbf{V}}(\mathbf{U}_{:,1}), \dots, \text{Proj}_{\mathbf{V}}(\mathbf{U}_{:,u_2})\}$ .

### Data constraints

A rating migration matrix  $\mathbf{M}$  must satisfy some constraints for both mathematical and economical reasons.

*Mathematical constraints.* Each row of  $\mathbf{M}$  is a discrete probability, hence  $\mathbf{M}$  is a stochastic matrix. The set of Stochastic Matrices is denoted by

$$\mathcal{M}^S := \left\{ \mathbf{M} \in \mathbb{R}^{(R-1)} \otimes \mathbb{R}^R : \sum_{j \in [R]} M_{i,j} = 1, \forall i \in [R-1], \right. \\ \left. M_{i,j} \geq 0, \forall (i,j) \in [R-1] \times [R] \right\}.$$

*Economic constraints.* Depending on their expertise, some risk managers may consider important to put additional constraints that are meaningful from economic point-of-view. For instance, the likelihood of default for higher-rated counterparties is lower than for the lower-quality ones. Then, the collection of rating matrices satisfying so-called economic constraints is denoted by

$$\mathcal{M}^E := \left\{ \mathbf{M} \in \mathbb{R}^{(R-1)} \otimes \mathbb{R}^R : M_{i,\geq j} \leq M_{i',\geq j}, \right. \\ \left. \forall j \in [R], \quad 1 \leq i < i' \leq R-1 \right\}.$$

A matrix satisfying such constraints is called an idealized matrix and is illustrated in Figure 1.

## 2 Dictionary learning: modeling and solving

### 2.1 Defining the regularization term

In the case of time-series DL, the expected time dependency can be encoded in the regularization part. We propose a regularization term with an extra parameter  $\mathbf{w}$  that will be used to infer the behavior of the codings as a time-series.

Defining

$$\bar{\alpha}_k := \frac{1}{T} \sum_{t=1}^T \alpha_k^t,$$

the proposed DL problem is:

$$\min_{\mathbf{D} \in \Omega, \alpha_k^t \geq 0, t \in [T], k \in [K]} \|\mathbf{P} - \mathbf{D}\mathbf{A}\|_F^2 + \lambda \mathcal{R}_{AR}(\mathbf{A}, \mathbf{w}) \quad (4)$$

where  $\mathbf{w} = (w_1, \dots, w_K)$ , with regularization:

$$\mathcal{R}_{AR}(\mathbf{A}, \mathbf{w}) := \sum_{k=1}^K \sum_{t=1}^{T-1} \left( \alpha_k^{t+1} - \bar{\alpha}_k - w_k(\alpha_k^t - \bar{\alpha}_k) \right)^2, \quad (5)$$

where the extra parameter  $\mathbf{w}$  allows us to estimate the AR parameters of the time-series  $\alpha_k$  for each  $k \in [K]$ , as it will be detailed below. The available set  $\Omega$  is the convex set of dictionaries verifying the idealized constraints (see Section 1.5):

$$\Omega := \{ \mathbf{D} \in \mathbb{R}^d \otimes \mathbb{R}^K : \text{vec}^{-1}(\mathbf{d}_k) \in \mathcal{M}^E \cap \mathcal{M}^S, \forall k \in [K] \}.$$

### *Heuristics for the regularization strategy*

The AR model is an important time-series structure, largely applied in finance and other contexts (see [22]). For a fixed  $k \in [K]$ , we say that the time-series  $\alpha_k$  is auto-regressive of order 1, if

$$\alpha_k^{t+1} = \mu_k + w_k \alpha_k^t + \epsilon_k^t, \quad \text{for all } t > 1, \quad (6)$$

where  $\mu_k$  is a constant called drift,  $w_k$  is the AR coefficient and  $(\epsilon_k^t)_{t=1}^T$  are independent centered Gaussian variables with some variance parameter  $\sigma_k^2$ .

Starting from the DL model (3), we encourage the codings  $\mathbf{A}$  to have an AR structure (6) through the regularization term. Thus, assuming an AR structure of  $\alpha_k$  for each  $k \in [K]$ , the log-likelihood with respect to parameters  $\mu_k$ ,  $w_k$ , and  $\sigma_k$ , up to a constant term, is:

$$\ell(\alpha_k, \mu_k, w_k, \sigma_k) := -\frac{1}{2\sigma_k^2} \sum_{t=1}^{T-1} \left( \alpha_k^{t+1} - \mu_k - w_k \alpha_k^t \right)^2 - (T-1) \log(\sigma_k)$$

(see [27, Chapter 3.6]), with solutions:

$$\tilde{\mu}_k, \tilde{w}_k, \tilde{\sigma}_k = \arg \max_{\mu_k, w_k, \sigma_k} \ell(\alpha_k, \mu_k, w_k, \sigma_k).$$

It readily follows that the optimal parameter  $\mu_k$  is

$$\tilde{\mu}_k = \frac{1}{T-1} \sum_{t=1}^{T-1} (\alpha_k^{t+1} - \tilde{w}_k \alpha_k^t) \approx (1 - \tilde{w}_k) \bar{\alpha}_k =: \hat{\mu}_k$$

where the approximation holds for large values of  $T$ . Thus, the optimization of  $w_k$  boils down to (up to a small error)

$$\hat{w}_k = \arg \min_{w_k} \sum_{t=1}^{T-1} \left( \alpha_k^{t+1} - \bar{\alpha}_k - w_k(\alpha_k^t - \bar{\alpha}_k) \right)^2. \quad (7)$$



Doing so, we obtain the regularization term of (5). Note that this regularization makes problem (3) convex with respect to  $\mathbf{A}$  which will be useful to the optimization strategy (Section 2.2). Observe that we would have lost convexity in  $\mathbf{A}$  if we had replaced the explicit minimizer  $\widehat{w}_k$  into (5).

Later (in the hyper-parameter selection step in Section 3.1), we will need also to retrieve all AR coefficients from observations. Obtaining the optimal  $w_k$  is straightforward from (7):

$$\widehat{w}_k = \frac{\sum_{t=1}^{T-1} (\alpha_k^{t+1} - \bar{\alpha}_k)(\alpha_k^t - \bar{\alpha}_k)}{\sum_{t=1}^{T-1} (\alpha_k^t - \bar{\alpha}_k)^2}. \quad (8)$$

*Remark 1* Note that  $\widehat{w}_k$  in (8) is not necessarily between  $-1$  and  $1$ , so for better adequacy with the expected mean-reversion property of the alphas we prefer to implement

$$\widehat{w}_k = \frac{\sum_{t=1}^{T-1} (\alpha_k^{t+1} - \bar{\alpha}_k)(\alpha_k^t - \bar{\alpha}_k)}{\sqrt{\sum_{t=1}^{T-1} (\alpha_k^{t+1} - \bar{\alpha}_k)^2} \sqrt{\sum_{t=1}^{T-1} (\alpha_k^t - \bar{\alpha}_k)^2}}.$$

Regarding  $\sigma_k$ , we proceed similarly and we get that  $\tilde{\sigma}_k$  is close to

$$\widehat{\sigma}_k^2 = \frac{\sum_{t=1}^{T-1} \left( \alpha_k^{t+1} - \widehat{\mu}_k - \widehat{w}_k \alpha_k^t \right)^2}{T-1}.$$

We observe that, replacing  $\widehat{w}_k$  in (7) (and then in (4)) would result in a non-convex function in terms of  $\alpha_k$ , which would increase the difficulty of the optimization problem (4). Therefore, optimize this parameter  $w_k$  as an extra variable is the best choice regarding convexity purposes.

*Remark 2* The model presented in this work can be easily generalized to an AR model of order  $p \in \mathbf{N}$ . The choice to introduce it in order 1 simplifies our notation and is adequate to our case of application, see Section 3.1.1. The DL optimization strategy, Section 2.2, applies likewise to an AR model of order  $p \in \mathbf{N}$ .

### ***The importance of the parameter $\mu_k$***

A similar AR regularization, inspired in graph theory, is proposed in [32]. The difference between the latter and our model is that their  $\mu_k$  is considered to be zero. We discuss in this paragraph why in our case of application this choice would not work.

Indeed, because of Equation (1) and the fact that  $\Omega$  is a convex set, we expect  $\{\alpha_k^t\}_{k=1}^K$  to be coefficients of a linear combination of  $\{\mathbf{d}_k\}_{k=1}^K$  that

approximates  $\mathbf{P}^t \in \mathcal{M}^S$  for each  $t$  fixed, as explained in Equation (1). Then:

$$\sum_{k=1}^K \alpha_k^t \approx 1, \quad \text{for all } t \in [T]. \quad (9)$$

On the other hand, if  $\mu_k = 0$ , and  $\alpha_k$  are AR time-series of order 1 with coefficients  $\mu_k$  and  $w_k$ , the estimator  $\hat{\mu}_k$  gives that:

$$0 \approx \hat{\mu}_k = (1 - w_k)\bar{\alpha}_k.$$

Either  $w_k = 1$ , which restricts a lot the possible time-modeling of  $\alpha_k$ . Or, if  $w_k \neq 1$  for all  $k \in [K]$ , then  $\frac{1}{T} \sum_{t=1}^T \alpha_k^t \approx 0$  and summing in  $k$ , we get  $\sum_{k=1}^K \sum_{t=1}^T \alpha_k^t \approx 0$ , which contradicts (9). This contradiction shows the difficulty of fitting an AR model with drift 0 in the case where dictionaries lie in a convex set and where the codings are expected to be a convex combination.

## 2.2 Dictionary learning optimization strategy

Problem (4) is not a convex optimization problem, as it is usually the case in DL problems. Nevertheless, the problem is convex in variables  $\mathbf{D}$ ,  $\mathbf{A}$  and  $\mathbf{w}$ , as we can observe in (4). This property encourages the use of a policy that consists in alternating the minimization in  $\mathbf{A}$ ,  $\mathbf{D}$  and  $\mathbf{w}$ . This largely applied strategy does not ensure a global solution of problem (4), but it is a straightforward way of finding a local minima of problem.

The quadratic problems presented in this section are solved by a Interior Point Method, see ([23, Section 16.8],[31]). Interior point methods (IPMs) are very well-suited to solving quadratic optimization problems, particularly when sizes of problems grow large, see [11].

### 2.2.1 Dictionary update

We opt for a sequential update of each atom of the dictionary:  $\mathbf{d}_k$  for  $k \in [K]$ . This choice is guided by two advantages: 1. The problem is strictly convex for each atom  $\mathbf{d}_k$  (as stated in Proposition 1 below) which is not necessarily true for the whole matrix  $\mathbf{D}$ . 2. This strategy breaks the problem in smaller problems making the resolution less dependent on the amount of atoms  $K$ . Updating atoms separately is also the strategy of the widely used K-SVD (see [9, Section 3.5]), however, the purpose in that case is to find a closed form for the optimization problem, which is not true in our case of study because of the form of constraints.

**Proposition 1** *Assume that  $\{\alpha_k^t\}_{t=1}^T$  is non zero. The minimization of (4) over  $\mathbf{d}_k \in \text{vec}(\mathcal{M}^E \cap \mathcal{M}^S)$  is equivalent to minimizing a strictly convex quadratic problem with linear constraints*

$$\min_{\mathbf{d}_k} \left\| \text{vec} \left( \tilde{\mathbf{P}}_k \right) - \tilde{\mathbf{A}}_k \mathbf{d}_k \right\|_F^2, \quad \text{s.t. } \text{vec}^{-1}(\mathbf{d}_k) \in \mathcal{M}^E \cap \mathcal{M}^S, \quad (10)$$

where  $\tilde{\mathbf{P}}_k$  and  $\tilde{\mathbf{A}}_k$  are explicitly defined in (12).

Observe that the condition on  $\alpha_k$  is expected to be systematically satisfied since each element  $\alpha_k^t$  is non-negative and sums up (in  $k$ ) approximately to 1 (see (9)).

*Proof* Start from the reconstruction error in (4) and write

$$\|\mathbf{P} - \mathbf{DA}\|_F^2 = \left\| \mathbf{P} - \sum_{j \neq k}^K \mathbf{d}_j \mathbf{A}_{j,:} - \mathbf{d}_k \mathbf{A}_{k,:} \right\|_F^2. \quad (11)$$

From this, it is obvious that the function  $\mathbf{d}_k \mapsto \|\mathbf{P} - \mathbf{DA}\|_F^2$  to minimize is quadratic and convex. However, under this form, it is not yet clear it is strictly convex. To establish this property, define

$$\tilde{\mathbf{P}}_k := \mathbf{P} - \sum_{j \neq k}^K \mathbf{d}_j \mathbf{A}_{j,:},$$

$$\tilde{\mathbf{A}}_k := \begin{bmatrix} A_{k,1} & 0 & \dots & 0 \\ 0 & A_{k,1} & \dots & 0 \\ \vdots & \vdots & \ddots & 0 \\ 0 & 0 & \dots & A_{k,1} \\ \vdots & \vdots & \vdots & \vdots \\ A_{k,T} & 0 & \dots & 0 \\ 0 & A_{k,T} & \dots & 0 \\ \vdots & \vdots & \ddots & 0 \\ 0 & 0 & \dots & A_{k,T} \end{bmatrix} \in \mathbb{R}^{dT} \otimes \mathbb{R}^d. \quad (12)$$

The quantity in (11) is thus equal to

$$\left\| \text{vec}(\tilde{\mathbf{P}}_k) - \tilde{\mathbf{A}}_k \mathbf{d}_k \right\|_F^2.$$

Note that  $\tilde{\mathbf{A}}_k^\top \tilde{\mathbf{A}}_k$  is diagonal matrix equal to  $\sum_{t=1}^T (\alpha_k^t)^2 \mathcal{I}_{\mathbb{R}^d}$ , where  $\mathcal{I}_{\mathbb{R}^d}$  is the identity matrix in  $\mathbb{R}^d$ .  $\square$

## 2.2.2 Codings update

Similarly to the dictionary update, we adopt a strategy based on the update of each  $\mathbf{A}_{k,:}$  for  $k \in [K]$ . The reasons are the same: it is preferable to solve a smaller and strictly convex optimization problem. The fact that the optimization for each  $k$  is a strongly convex problem is not straightforward and is argued in the proposition below.

**Proposition 2** *Let  $k \in [K]$  be fixed. Consider the minimization of (4)-(5) over one coding  $\mathbf{A}_{k,:}$ , i.e.*

$$\min_{\mathbf{A}_{k,:}, A_{k,t} \geq 0} \|\mathbf{P} - \mathbf{DA}\|_F^2 + \lambda \sum_{k=1}^K \sum_{t=1}^{T-1} \left( A_{k,t+1} - \bar{\mathbf{A}}_{k,:} - w_k (A_{k,t} - \bar{\mathbf{A}}_{k,:}) \right)^2. \quad (13)$$

For any  $\lambda \geq 0$ , the above problem is a strongly convex quadratic optimization problem with linear constraints.

*Proof* First, there is a symmetric non-negative matrix  $\mathbf{H}^{w_k} \in \mathbb{R}^T \otimes \mathbb{R}^T$  such that

$$\begin{aligned} \mathcal{R}_{AR}^k(A_{k,:}, w_k) &= \sum_{t=1}^{T-1} \left( A_{k,t+1} - \bar{\mathbf{A}}_{k,:} - w_k(A_{k,t} - \bar{\mathbf{A}}_{k,:}) \right)^2 \\ &= \langle \mathbf{A}_{k,:}^\top, \mathbf{H}^{w_k} \mathbf{A}_{k,:} \rangle \end{aligned}$$

since for  $w_k$  fixed,  $\mathcal{R}_{AR}^k(\cdot, w_k)$  is a quadratic problem without linear term that can be represented by a symmetric matrix. Obviously, it is non-negative.

Similarly to the proof for the dictionary update, we define a matrix  $\tilde{\mathbf{D}}_k$  :

$$\tilde{\mathbf{D}}_k := \begin{bmatrix} \mathbf{D}_{1,k} & 0 & \dots & \dots & 0 \\ \vdots & \vdots & \ddots & \ddots & \vdots \\ \mathbf{D}_{d,k} & 0 & \dots & \dots & 0 \\ 0 & \mathbf{D}_{1,k} & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & 0 \\ 0 & \mathbf{D}_{d,k} & 0 & \dots & 0 \\ \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots \\ 0 & \dots & \dots & 0 & \mathbf{D}_{1,k} \\ \vdots & \ddots & \ddots & \vdots & \vdots \\ 0 & \dots & \dots & 0 & \mathbf{D}_{d,k} \end{bmatrix} \in \mathbb{R}^{dT} \otimes \mathbb{R}^T;$$

note that the minimization problem (13) is equivalent to

$$\min_{\mathbf{A}_{k,:}, A_{k,t} \geq 0} \left\| \text{vec} \left( \tilde{\mathbf{P}}_k \right) - \tilde{\mathbf{D}}_k \mathbf{A}_{k,:}^\top \right\|_F^2 + \lambda \langle \mathbf{A}_{k,:}^\top, \mathbf{H}^{w_k} \mathbf{A}_{k,:} \rangle, \quad (14)$$

which is a quadratic constrained optimization problem with quadratic term given by the matrix:

$$\mathbf{C}_k := \tilde{\mathbf{D}}_k^\top \tilde{\mathbf{D}}_k + \lambda \mathbf{H}^{w_k}.$$

Since  $\tilde{\mathbf{D}}_k^\top \tilde{\mathbf{D}}_k = \|\mathbf{d}_k\|_2^2 \mathcal{I}_{\mathbb{R}^T}$  and that  $\|\mathbf{d}_k\|_2$  is uniformly bounded from below on  $\text{vec}(\mathcal{M}^E \cap \mathcal{M}^S)$ , and since  $\mathbf{H}^{w_k}$  is symmetric non-negative, the matrix  $\mathbf{C}_k$  is symmetric positive definite with a uniform lower bound for its eigenvalues. The announced statement is proved.  $\square$

### 2.3 Coefficient update

We note that, for each  $k \in [K]$ , the optimization problem with respect to  $\mathbf{w}_k$  in equation (4) is a 1-dimensional quadratic problem with explicit solution given by Equation (8).

*Remark 3* For each  $k \in [K]$ , the solution of problem (10) and (13) decreases the objective value of the respective optimization problems. However, it is an open question to justify that this strategy provides a solution to problems (4) with respect to  $\mathbf{D}$ ,  $\mathbf{A}$  and  $\mathbf{w}$ .

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**Algorithm 1: Dictionary Learning (DL)**


---

**Input:** *matrix of vectorized RMM:*  $\mathbf{P} \in \mathbb{R}^d \otimes \mathbb{R}^T$ ,  
*number of atoms:*  $K \in \{1, 2, \dots\}$ ,  
*regularization parameter:*  $\lambda > 0$ ,  
*number of iterations:*  $N \in \{1, 2, \dots\}$   
**Output:** *optimized dictionary, codings and drift:*  $\mathbf{D}, \mathbf{A}, \mathbf{w}$

- 1 initialize  $\mathbf{D} \in \mathbb{R}^d \otimes \mathbb{R}^K$  and  $\mathbf{A} \in \mathbb{R}^K \otimes \mathbb{R}^T$
- 2 **for**  $i = 1 : N$  **do**
- 3     # Dictionary update
- 4     **for**  $k = 1 : K$  **do**  
        | update  $\mathbf{d}_k$  with QP s.t.  $\text{vec}^{-1}(\mathbf{d}_k) \in \mathcal{M}^E \cap \mathcal{M}^S$
- 5     # Codings update
- 6     **for**  $k = 1 : K$  **do**  
        | update  $\alpha_k$  with QP s.t.  $\alpha_k^t \geq 0$ ,  $t \in [T]$
- 7     # Coefficient update
- 8     **for**  $k = 1 : K$  **do**  
        | update  $w_k$  with Equation (8)

---

### 3 Experiments

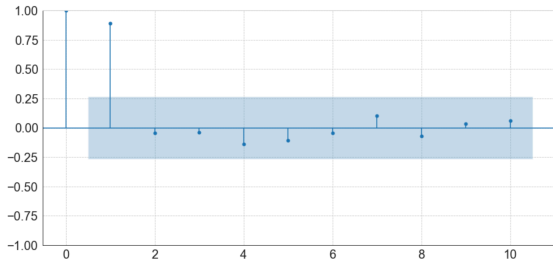
Our proposed DL method with temporal AR regularization will be evaluated on real RMM provided by BNP Paribas. The dataset contains  $T = 192$  one-year observed transition frequency matrices with shape  $R = 11$  issued monthly from 52 sectors composed by large European capitalization companies between January 2004 and December 2019. This period contains in particular the subprime crisis but not the COVID-19 pandemic.

#### 3.1 Experimental design

Ideally, we should apply our DL method on each sector. However given the dataset, the observed matrices are very sparse which refers to another problem formulation (missing data). To overcome this issue we computed a (confidential) weighted sum among the 52 sectors to form a shareable (on git) set of matrices  $\mathbf{P} = \{\text{vec}(\mathbf{P}^t) \in \mathbb{R}^d\}_{t=1}^T$  with  $d = 110$  and  $T = 192$ . Those matrices are still noisy and so they might not respect the economic constraints, *i.e.*  $\mathbf{P}^t \in \mathcal{M}^S, \forall t \in [192]$ . Based on this dataset, we performed a classical 80/20 non-random train-test split in time, stored respectively in  $\mathbf{P}^{\text{Train}} \in \mathbb{R}^d \otimes \mathbb{R}^{T^{\text{Train}}}$  and  $\mathbf{P}^{\text{Test}} \in \mathbb{R}^d \otimes \mathbb{R}^{T^{\text{Test}}}$ . In all the following experiments in Section 3 we use  $K = 3$  for ease of interpretation since we want to represent the RMM as a combination of three regimes, assuming that each one represents an economic state. Larger values of  $K$  perform similar results but lead to a more sophisticated economic analysis. See Section 3.1.2 for an automatic selection of the hyperparameters.

### 3.1.1 AR lag estimation

First let us check the relevance of the AR(1) model in (5). Starting from the optimization problem (4) with  $\lambda = 0$ , we trained the DL model on  $\mathbf{P}^{\text{Train}}$  and applied the well-known partial autocorrelation function (PACF) [4, Section 3.2.5] on the codings  $\mathbf{A}_{k,:}^{\text{Train}}$ , for all  $k \in [3]$ . For each series, we identified just one statistically significant lag, suggesting a possible AR(1) model adapted to the data. See Figure 2 for  $k = 1$ , while the others behave similarly.



**Fig. 2:** PACF of  $\mathbf{A}_{1,:}^{\text{Train}}$  for the first 10 lags. The shaded region represents the 95% confidence interval.

### 3.1.2 Hyper-parameter selection

The best hyper-parameters  $\lambda$  and  $K$  can be chosen automatically through the procedure described in Algorithm 2. The latter allows to evaluate both the prediction and the reconstruction capacity of the model through an AR log-likelihood estimation component-wise (see Lines 3 and 4 in Algorithm 2). We applied Algorithm 2 for  $\lambda \in \{0.01, 0.1, 1, 3, 5, 10\}$ ,  $K \in \{2, 3, 4, 5, 6, 7, 8, 9, 10\}$  and stored the results in Table 1 which highlights the benefit of our proposed regularization in the RMM predictions. The parameters associated with the smallest selection criteria is  $K = 9$  and  $\lambda = 0.1$ . However, since we consider  $K = 3$  for ease of interpretation, we select the best associated lambda which is  $\lambda = 0.1$ .

In the next section we illustrate the results of our DL model and propose two ML applications. First a time-series simulation of the RMM and second their unsupervised clustering in order to infer an estimation of the global economic sentiment.

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**Algorithm 2: Hyper-parameter selection**


---

**Input:** *data train:*  $\mathbf{P}^{\text{Train}} \in \mathbb{R}^d \otimes \mathbb{R}^{T^{\text{Train}}}$ ,  
*data test:*  $\mathbf{P}^{\text{Test}} \in \mathbb{R}^d \otimes \mathbb{R}^{T^{\text{Test}}}$ ,  
*number of atoms:*  $K \in \{1, 2, \dots\}$ ,  
*lambda:*  $\lambda > 0$

**Output:** *criteria:*  $\mathcal{L}$

- 1  $\mathbf{D}^{\text{Train}}, \mathbf{A}^{\text{Train}}, \mathbf{w}^{\text{Train}} \leftarrow \text{DL}(\mathbf{P}^{\text{Train}}, K, \lambda, N = 500)$ , where the function DL refers to Algorithm 1
  - 2  $\mathbf{A}^{\text{Test}} \leftarrow \text{Proj}_{\mathbf{D}^{\text{Train}}}(\mathbf{P}^{\text{Test}})$
  - 3  $\ell_k \leftarrow -\frac{1}{2\hat{\sigma}_k^2} \sum_{t=1}^{T^{\text{Test}}-1} \left( A_{k,t+1}^{\text{Test}} - \hat{\mu}_k - w_k^{\text{Train}} A_{k,t}^{\text{Test}} \right)^2 - (T^{\text{Test}} - 1) \log(\hat{\sigma}_k)$ ,  

$$\hat{\mu}_k = \bar{\alpha}_k^{\text{Train}} (1 - w_k^{\text{Train}}),$$

$$\hat{\sigma}_k^2 \leftarrow \widehat{\text{Var}}[\boldsymbol{\alpha}_k^{\text{Train}}] (1 - (w_k^{\text{Train}})^2),$$
  - 4  $\mathcal{L} \leftarrow \frac{1}{K} \sum_{k=1}^K \ell_k$
- 

$K \backslash \lambda$	0.01	0.1	0.5	1	3	5	10
2	73.9	68.3	2.8	—	—	—	—
3	90.2	<u>98.7</u>	96.1	85.4	35.3	—	—
4	92.7	101.7	100.9	93.2	62.9	28.1	—
5	92.7	101.2	100.3	92.3	64.4	44.8	14.2
6	96.7	104.8	106.1	99.2	68.3	40.6	22.8
7	100.5	106.0	106.0	100.7	73.4	56.1	37.6
8	103.8	106.0	100.7	93.0	72.6	48.3	20.7
9	106.9	<b>109.4</b>	105.5	104.6	70.9	40.8	24.4
10	106.9	108.1	106.6	97.3	67.1	71.1	7.8

**Table 1:** Selection criteria  $\mathcal{L}$  from Algorithm 2 associated with various  $\lambda$  and  $K$ . Negative values are not reported. The best overall result is emphasized in bold and the best one for  $K = 3$  is underlined.

## 3.2 Results

### *Computational aspects*

The numerical experiments have been conducted on a Macbook Pro (13-inch, M1, 2020), 512 Go SSD, 16 Go RAM. All the code was implemented in Python 3.10. It takes less than a minute to train the model with  $K = 3$  during 500 iterations. Clearly from Algorithm 1 the training time is linear with respect to  $K$ . The calibration of GC model takes about 70ms: although quite different from one model to the other, the computational time is not an issue in practice since RMM are assessed on a low frequency basis (every month).

### 3.2.1 Dictionary representation

Once learned, it appears that the dictionary managed to extract three candidates (atoms) to be good representatives for all RMM included in our dataset. In Figure 3 are represented these atoms in a matrix form generating a stable (strong diagonal, see Figure 3a), an upgrade (strong lower diagonal, see Figure 3b) and a downgrade (strong upper diagonal, see Figure 3c) risk configuration. Although automatically obtained by our algorithm, observe that these representatives make fully sense in terms of economic interpretation, and should reveal the underlying characteristics of RMM in our data set.

	1	2	3	4	5	6	7	8	9	10	11
1	92.89	4.42	0.00	1.52	0.00	0.51	0.31	0.17	0.07	0.00	0.12
2	2.30	88.04	6.73	1.25	0.51	0.51	0.31	0.17	0.04	0.03	0.12
3	0.65	7.13	77.99	10.05	2.52	0.99	0.30	0.17	0.04	0.03	0.12
4	0.18	0.96	9.93	79.25	5.84	3.03	0.44	0.17	0.04	0.03	0.12
5	0.17	0.19	1.60	10.04	75.61	9.42	2.03	0.62	0.15	0.07	0.12
6	0.04	0.13	0.42	1.35	10.36	79.34	6.50	1.16	0.18	0.32	0.19
7	0.04	0.13	0.10	0.30	1.20	10.10	78.70	7.70	1.17	0.18	0.39
8	0.04	0.10	0.08	0.04	0.43	2.01	10.64	84.14	1.95	0.18	0.39
9	0.00	0.00	0.00	0.00	0.15	0.47	4.92	6.24	87.65	0.18	0.39
10	0.00	0.00	0.00	0.00	0.15	0.37	3.48	0.00	5.59	84.80	5.61

(a)  $\text{vec}^{-1}(\mathbf{d}_1)$ 

	1	2	3	4	5	6	7	8	9	10	11
1	91.43	8.57	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
2	0.27	91.29	8.44	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
3	0.27	7.85	87.30	0.19	3.14	1.22	0.00	0.03	0.00	0.00	0.00
4	0.26	2.95	10.37	82.02	3.05	1.30	0.01	0.04	0.00	0.00	0.00
5	0.26	0.88	0.78	14.52	75.80	7.71	0.00	0.04	0.00	0.00	0.00
6	0.26	0.30	1.23	1.34	13.87	75.00	5.84	2.16	0.00	0.00	0.00
7	0.26	0.30	0.46	0.79	2.47	13.39	80.16	2.17	0.00	0.00	0.00
8	0.26	0.30	0.45	0.80	1.57	1.64	13.14	81.84	0.00	0.00	0.00
9	0.00	0.00	0.00	0.00	0.09	3.81	14.27	61.27	17.86	2.71	0.00
10	0.00	0.00	0.00	0.00	0.08	0.00	3.41	75.94	17.86	0.17	2.54

(b)  $\text{vec}^{-1}(\mathbf{d}_2)$ 

	1	2	3	4	5	6	7	8	9	10	11
1	73.18	17.63	3.60	2.54	0.73	1.82	0.00	0.00	0.00	0.00	0.50
2	0.00	82.99	9.86	4.10	0.73	0.83	0.35	0.17	0.25	0.22	0.50
3	0.00	0.00	88.51	8.43	0.74	0.83	0.35	0.17	0.25	0.22	0.50
4	0.00	0.00	0.13	81.89	14.96	1.36	0.51	0.17	0.24	0.23	0.50
5	0.00	0.00	0.13	3.57	82.87	8.15	2.52	1.03	0.45	0.77	0.51
6	0.00	0.00	0.13	1.19	5.32	74.59	12.98	1.46	1.30	0.88	2.14
7	0.00	0.00	0.13	0.55	1.43	5.83	77.09	9.22	2.45	0.78	2.51
8	0.00	0.00	0.13	0.28	0.63	0.66	17.34	61.66	8.67	4.30	6.32
9	0.00	0.00	0.13	0.28	0.61	0.68	0.00	15.24	13.98	26.55	42.52
10	0.00	0.00	0.00	0.00	0.00	0.00	1.71	0.00	1.03	53.85	43.42

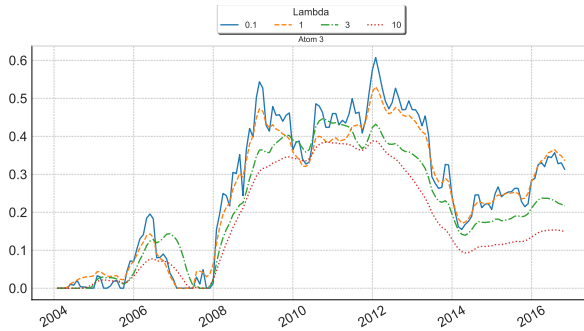
(c)  $\text{vec}^{-1}(\mathbf{d}_3)$ 

**Fig. 3:** Matrix representation of the atoms in a trained dictionary with  $K = 3, \lambda = 0.1$ .



### 3.2.2 Codings

The AR regularization (5) enforces an AR behavior of the codings making them more regular. The choice of the best prediction and analysis will then be a trade-off between the reconstruction and the regularity of the time evolution of the codings. Figure 4 depicts this evolution.



**Fig. 4:** Time evolution of  $\mathbf{A}_{3,:}^{\text{Train}}$  for  $\lambda \in \{0.1, 1, 3, 10\}$ .

Note that for larger values of  $\lambda$  the evolution in time of the coding is smoother. This property tends to advantage the prediction of future matrices.

### 3.2.3 Simulation-base example

Let us briefly exemplify the use of the fitted model in a credit risk use-case, using simulations. Consider a portfolio of obligors owned by a bank, described according to the losses given default  $\text{LGD}_i$  given the initial rating  $i$  at time  $T$ : due to the definition of RMM, the average loss in one-year (estimated at the current time  $T$ ) is given by

$$\text{Loss}_T = \sum_{i=1}^{10} \text{LGD}_i \mathbf{P}_{i,11}^T.$$

This average potential loss is then converted into capital requirements. In addition, banks are invited to develop forward-looking tools, for financial planning and steering. This means, for example, understanding what the average loss distribution will be in the future, in 12 months' time for example, i.e. what the distribution of  $\text{Loss}_{T+12}$  is. Our fitted model allows to sample the above loss by the simulation of  $(\mathbf{P}^t : t = T + 1, \dots, T + 12)$  for getting RMM trajectories. This simulation can be easily performed through the reconstruction

matrix and the sampling of codings:

$$\begin{aligned} \mathbf{P}^t &\approx \sum_{k=1}^K \alpha_k^t \mathbf{d}_k^{\text{Train}}, \\ \alpha_k^{t+1, \text{Sim}} &= \hat{\mu}_k + \alpha_k^{t, \text{Sim}} w_k^{\text{Train}} + \varepsilon_k^t, \quad t \geq T, \\ \alpha_k^{T, \text{Sim}} &= \alpha_k^{T, \text{Train}}, \end{aligned}$$

where  $(\varepsilon_k^t : k \in [K])$  is a centered Gaussian random variable, which  $k$ -th coordinate has variance  $\hat{\sigma}_k^2$ , and where the correlation between components are estimated empirically from the codings  $\boldsymbol{\alpha}^{\text{Train}}$ . These Gaussian variables are taken independent in time.

### 3.2.4 Clustering

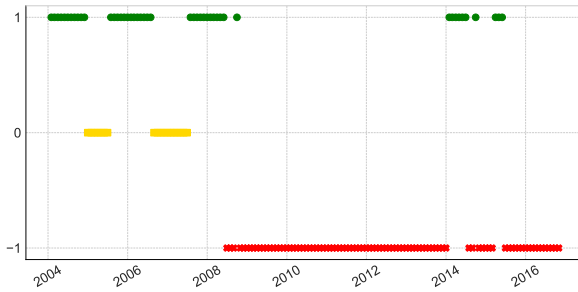
Let study now the benefit of our proposed regularized DL model in order to obtain an interpretable classification of the RMM. We fit a k-means algorithm on the standardized  $\mathbf{A}^{\text{Train}}$  in 3 clusters and predict the classes of the standardized  $\mathbf{A}^{\text{Train}}$ . Assuming that the atoms and the clusters represent different economic states, we obtain in Figure 5 a classification in time of the observed RMM. Additionally to the historical financial context, we present how to infer an economic sentiment indicator based on both the codings' classification and the dictionary. To do so, we store in Table 2 the weights of the atoms assigned to each cluster. Thus, combining with Figure 3, we can easily deduce that the labels associated to the clusters green, yellow, red are respectively a good, a stable and a bad economic sentiment indicator. Such an allocation can be confirmed graphically in Figure 5 which captures effectively the financial bubble between 2006-2008, as well as the subprime crisis.

cluster \ k	1	2	3
green	83.2	6.6	10.2
yellow	64.9	32.9	2.2
red	50.9	10.2	38.9

**Table 2:** Centroid of  $\mathbf{A}^{\text{Train}}$  in each cluster: green, yellow, red. The values are adjusted in percentage.

## 4 Challenging the one-factor Gaussian Copula model

Let us compare our proposed non-parametric DL approach with the parametric one-factor GC model based on the same real RMMs as tested in the previous section.



**Fig. 5:** Unsupervised classification of the codings  $\mathbf{A}^{\text{Train}}$  in 3 clusters:  $\{-1$  (red cross),  $0$  (yellow square),  $1$  (green dot) $\}$ .

#### 4.1 One-factor Gaussian Copula model

For an initial rating  $i$  at time  $t$ , the one-factor Copula model assumes that the event "migration to the rating greater than  $j$  at time  $t + 1$ " is given by

$$\{X_i^t \geq c_{i,j}\},$$

where the parameters  $\{c_{i,j}\}_{i \in [R-1], j \in [R]}$  are thresholds triggering the rating migration and with a stochastic factor

$$X_i^t = \rho Z^t + \sqrt{1 - \rho^2} \epsilon_i^t, \quad (15)$$

composed by a systemic risk factor  $Z^t$  (common to all obligors), an idiosyncratic risk factor  $\epsilon_i^t \stackrel{d}{=} \mathcal{N}(0, 1)$  (specific to every obligor), independent from  $Z^t$ , and a correlation parameter  $\rho \in (-1, 1)$  between the two sources of risk. The systemic factor  $Z$  evolves through time and has a stationary distribution given by a standard Gaussian distribution. Thus, conditionally to  $Z^t$ , this event "migration to the rating greater than  $j$  at time  $t + 1$ " has the probability

$$\Phi\left(\frac{\rho Z^t - c_{i,j}}{\sqrt{1 - \rho^2}}\right) =: P_{i,\geq j}^t, \quad (16)$$

and the unconditional probability is

$$\Phi(-c_{i,j}) =: P_{i,\geq j}^{\text{TTC}}, \quad (17)$$

where  $\Phi$  is the c.d.f. of a standard Gaussian distribution. The matrix  $\mathbf{P}^{\text{TTC}}$  represents the probability of default 'Through the Cycle' which is a long-run average over a cycle and focuses mainly on permanent components of default risk, whereas the matrix  $\mathbf{P}^t$  represents the probability of default 'Point-In-Time' which takes into account both cyclical and permanent effect. Inverting

$c_{i,j}$  in (17) and replacing in (16) gives

$$P_{i,\geq j}^t = \Phi \left( \frac{\rho Z^t + \Phi^{-1}(P_{i,\geq j}^{\text{TTC}})}{\sqrt{1-\rho^2}} \right), \quad (18)$$

$$P_{i,j}^t := \Phi \left( \frac{\rho Z^t + \Phi^{-1}(P_{i,\geq j}^{\text{TTC}})}{\sqrt{1-\rho^2}} \right) - \Phi \left( \frac{\rho Z^t + \Phi^{-1}(P_{i,\geq j+1}^{\text{TTC}})}{\sqrt{1-\rho^2}} \right), \quad (19)$$

with the convention  $P_{i,\geq R+1}^{\text{TTC}} = 0$ .

## 4.2 Parameter estimation

Starting from (18), under the GC model one should have for all  $i \in [R-1]$  and  $j \in [R]$

$$\Phi^{-1}(P_{i,\geq j}^t) = \frac{\rho Z^t + \Phi^{-1}(P_{i,\geq j}^{\text{TTC}})}{\sqrt{1-\rho^2}},$$

where  $\rho$  is the unknown parameter. Since the matrix  $\mathbf{P}^{\text{TTC}}$  interprets, in the GC model, as the migration matrix in the stationary systemic regime, each  $P_{i,\geq j}^{\text{TTC}}$  can be estimated as a long-run time average, i.e.

$$\widehat{P_{i,\geq j}^{\text{TTC}}} := \frac{1}{T} \sum_{t=1}^T P_{i,\geq j}^t.$$

Then, denoting for all  $t \in [T]$ ,  $P_{i,\geq j}^{\Phi,t} := \Phi^{-1}(P_{i,\geq j}^t)$  and  $P_{i,\geq j}^{\Phi,\text{TTC}} := \Phi^{-1}(\widehat{P_{i,\geq j}^{\text{TTC}}})$ , we should get

$$P_{i,\geq j}^{\Phi,t} \approx a_1^t + a_2 P_{i,\geq j}^{\Phi,\text{TTC}},$$

where (in the stationary regime)

$$a_1^t \stackrel{d}{\approx} \mathcal{N} \left( 0, \frac{\rho^2}{1-\rho^2} \right), \quad a_2 \approx \frac{1}{\sqrt{1-\rho^2}}.$$

Therefore, solving the least square regression problem

$$\min_{a_2} \frac{1}{T} \sum_{t=1}^T \sum_{j=1}^R \sum_{i=1}^{R-1} \left( \bar{P}_{i,\geq j}^{\Phi,t} - a_2 \bar{P}_{i,\geq j}^{\Phi,\text{TTC}} \right)^2,$$

with

$$\begin{aligned}\bar{P}_{i,\geq j}^{\Phi,t} &:= P_{i,\geq j}^{\Phi,t} - \frac{1}{R(R-1)} \sum_{j=1}^R \sum_{i=1}^{R-1} P_{i,\geq j}^{\Phi,t}, \\ \bar{P}_{i,\geq j}^{\Phi,\text{TTC}} &:= P_{i,\geq j}^{\Phi,\text{TTC}} - \frac{1}{R(R-1)} \sum_{j=1}^R \sum_{i=1}^{R-1} P_{i,\geq j}^{\Phi,\text{TTC}},\end{aligned}$$

entails

$$\hat{a}_2 = \frac{\sum_{t=1}^T \sum_{j=1}^R \sum_{i=1}^{R-1} \bar{P}_{i,\geq j}^{\Phi,t} \bar{P}_{i,\geq j}^{\Phi,\text{TTC}}}{T \sum_{j=1}^R \sum_{i=1}^{R-1} (\bar{P}_{i,\geq j}^{\Phi,\text{TTC}})^2},$$

and the parameter estimation

$$\hat{\rho} = \pm \sqrt{1 - \left(\frac{1}{\hat{a}_2}\right)^2}. \quad (20)$$

We pick the plus sign, for the sake of interpretation of  $Z$  as a systematic risk factor (the higher  $Z$ , the larger the default probabilities). Then, computing the mean residuals for all  $t \in [T]$ ,

$$\hat{a}_1^t = \frac{1}{R(R-1)} \sum_{j=1}^R \sum_{i=1}^{R-1} \left( P_{i,\geq j}^{\Phi,t} - \hat{a}_2 P_{i,\geq j}^{\Phi,\text{TTC}} \right),$$

we obtain an estimate

$$\hat{Z}^t = \frac{\sqrt{1 - \hat{\rho}^2}}{\hat{\rho}} \hat{a}_1^t. \quad (21)$$

Finally, we obtain the reconstructed RMM  $\mathbf{P}^{\text{GC}}$  similarly to (19), i.e.

$$P_{i,j}^{\text{GC},t} = \Phi\left(\hat{P}_{i,\geq j}^{\Phi,t}\right) - \Phi\left(\hat{P}_{i,\geq j+1}^{\Phi,t}\right),$$

with

$$\hat{P}_{i,\geq j}^{\Phi,t} := \hat{a}_1^t + \hat{a}_2 P_{i,\geq j}^{\Phi,\text{TTC}},$$

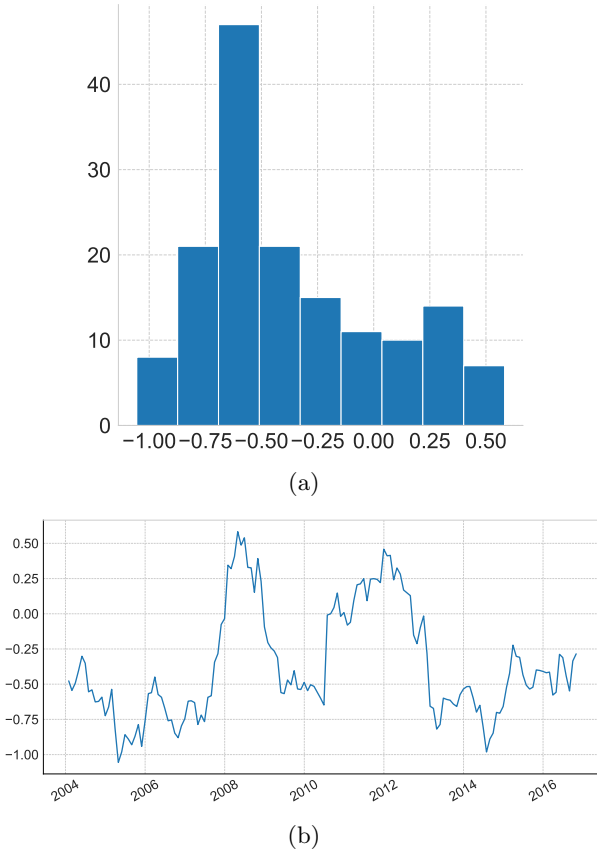
and where by convention  $\hat{P}_{i,R+1}^{\Phi,t} = -\infty$ .

### 4.3 Results

The GC model will be evaluated on  $\mathbf{P}^{\text{Train}}$  in order 1) to check if the underlying assumptions of the model are verified, and 2) to compare the reconstruction error with our proposed DL model.

**Validation.**

On the first hand, Figure 6a displays the empirical distribution of the estimated (21) on  $\mathbf{P}^{\text{Train}}$  with associated  $\hat{\rho} = 0.66$  (given by (20)). If the data were coherent with a GC model, this histogram would be close to the stationary distribution of  $Z$ , i.e. a standard Gaussian distribution, which is far to be the case. On the other hand, Figure 6b illustrates that the model captures in this term (which should represent the business cycle) the market's volatility during the 2007-2013 period. In addition, note that since the real data may not satisfy the economic constraints, neither will the reconstructed GC RMM.



**Fig. 6:** Histogram (6a) and series (6b) of  $\{\hat{Z}^t, t \in [T]\}$  estimated on  $\mathbf{P}^{\text{Train}}$ .

### Reconstruction

Table 3 reports the Root Mean Square Error (RMSE)  $\mathbf{P}^{\text{Reco}} \mapsto \sqrt{\|\mathbf{P}^{\text{Train}} - \mathbf{P}^{\text{Reco}}\|_F^2 / T^{\text{Train}}}$  of the reconstructed RMM using the GC and the DL models. It appears that even with only  $K = 2$  atoms, the reconstruction error with the DL approach is about twice lower than with the GC one. This gap is accentuated as we increase the number of atoms.

model	GC	DL(0)	DL(0.1)	DL(0.5)	DL(1)
error	0.527	<b>0.304</b>	0.304	0.306	0.307

**Table 3:** Reconstruction RMSE of  $\mathbf{P}^{\text{Train}}$  using the GC model, and the DL ( $\lambda$ ) model with  $K = 2$  atoms and  $\lambda \in \{0, 0.1, 0.5, 1\}$ . The best result is emphasized in bold.

## 4.4 Validation on simulated data

The reconstruction performance between the GC and the DL model is compared on simulated data using the One-factor Gaussian Copula model. Assume that the economy factor in (15) evolves as an AR(1) process

$$Z^t = \kappa Z^{t-1} + \epsilon_t^z,$$

where the innovation noise  $\epsilon_t^z$  is independent in  $t$  and distributed as  $\mathcal{N}(0, 1 - \kappa^2)$ . Here  $\kappa \in (-1, 1)$  and one can easily show that the stationary distribution of  $Z$  is  $\mathcal{N}(0, 1)$  with  $\mathbb{E}[Z^0] = 0$ .

### 4.4.1 Choice of $\kappa$

The half-life concept can be defined as how long the horizon should be for the mean of the process to be half-way between its current value and its long term mean. The half-life of the AR(1) process is defined as

$$H = -\frac{\ln 2}{\ln |\kappa|}.$$

In our context, the simulated matrices  $(\mathbf{P}^t)_{t \in [T]}$  are supposed to be issued quarterly with an economic cycle estimated around 5 years (20 quarters) leading to  $\kappa = \exp(-\ln 2/10) = 0.93$ .

### 4.4.2 Synthetic RMM generation

We define the synthetic matrix  $\mathbf{P}^{\text{TTC}} \in \mathbb{R}^{(R-1)} \otimes \mathbb{R}^R$  such that  $\mathbf{P}^{\text{TTC}}$  is an idealized matrix through

$$\mathbf{P}^{\text{TTC}} = \varphi \left( \begin{bmatrix} 2(R-i) & \frac{(R-j)}{(1+j-i)} \binom{i}{j} & \dots \\ \frac{(R-i)}{(1+i-j)} \binom{j}{i} & \ddots & \vdots \\ \vdots & \dots & \ddots \end{bmatrix} \right), \quad (22)$$

with  $i \in \{0, \dots, R-2\}$ ,  $j \in \{0, \dots, R-1\}$ ,  $R = 11$  and

$$\varphi(\mathbf{X}) := \left[ \begin{array}{c} \mathbf{X}_{i,:} \\ X_{i,\geq 1} \end{array} \right]_{i \in \{1, \dots, R-1\}},$$

the normalization operator by rows. Once the  $\mathbf{P}^{\text{TTC}}$  is defined, one can use (19) to generate idealized RMM from a GC model  $P_{i,j}^t$  and add some multiplicative noise such that the synthetic RMM are defined as

$$\mathbf{P}^t := \varphi \left( [P_{i,j}^t (1 + \zeta_{i,j}^t)]_{i \in \{0, \dots, R-2\}, j \in \{0, \dots, R-1\}} \right),$$

with independent  $\zeta_{i,j}^t \sim \mathcal{U}([-0.01, 0.01])$ . See Figure 8 for an illustration of the synthetic data with  $R = 11$  and  $T = 100$  (25 years).

### 4.4.3 Results

Table 4 reports the RMSE of the reconstructed synthetic RMM using the GC and the DL models. While the better results with the GC model were expected, those with the DL are very similar and confirm the good performance of our model even when the data come from a Gaussian model.

model	GC	DL (0)	DL(0.1)	DL(0.5)	DL(1)
error	<b>0.116</b>	0.117	0.118	0.122	0.125

**Table 4:** Reconstruction RMSE of synthetic  $\mathbf{P}$  using the GC model, and the DL ( $\lambda$ ) model with  $K = 2$  atoms and  $\lambda \in \{0, 0.1, 0.5, 1\}$ . The best result is emphasized in bold.

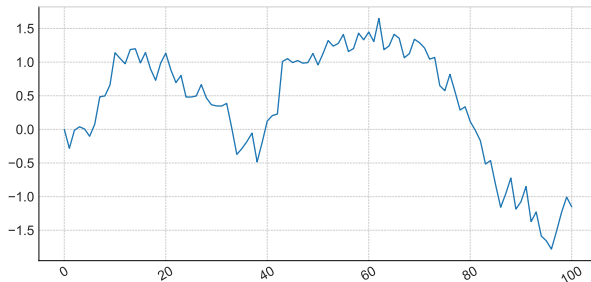
## 5 Conclusion

Modeling RMM is a challenging problem because it is necessary to find an interpretable representation, satisfying economic constraints, while the data are involving in time, not numerous and in a dimension close to the number of observations. We propose a new data-based method using a dictionary learning approach, which implementation boils down to solve small-dimension



	1	2	3	4	5	6	7	8	9	10	11
1	71.48	17.87	5.36	2.38	1.25	0.71	0.43	0.26	0.15	0.08	0.03
2	16.01	57.62	14.41	5.69	2.80	1.54	0.89	0.52	0.30	0.16	0.06
3	5.05	15.14	53.85	13.46	5.89	3.03	1.68	0.96	0.54	0.28	0.11
4	2.45	6.52	14.67	51.35	12.84	5.87	3.06	1.68	0.92	0.47	0.18
5	1.45	3.61	7.23	14.46	49.57	12.39	5.74	2.95	1.55	0.76	0.30
6	0.96	2.31	4.34	7.71	14.46	48.19	12.05	5.51	2.71	1.29	0.48
7	0.70	1.63	2.94	4.90	8.16	14.69	47.00	11.75	5.14	2.28	0.82
8	0.54	1.24	2.18	3.48	5.44	8.71	15.24	45.71	11.43	4.51	1.52
9	0.45	1.02	1.75	2.73	4.09	6.14	9.55	16.38	43.67	10.92	3.28
10	0.43	0.95	1.60	2.43	3.55	5.11	7.46	11.36	19.17	38.35	9.59

(a)



(b)

**Fig. 7**

**Fig. 8:** Synthetic  $\mathbf{P}^{\text{TC}}$  matrix (7a) and series of synthetic  $\{Z^t, t \in [T]\}$  (7b) with  $R = 11, T = 100$  and  $\kappa = 0.93$ .

quadratic optimization problems with linear constraints, leading to a fast algorithm. On the modeling size, we overcome the challenge of a constrained dictionary learning problem and progress in temporal comprehension of the data through the AR regularization. When tested on a real data-set, the method enjoys good accuracy for reconstruction and includes the interpretable classification with respect to economic sentiment indicator. Compared to the popular Gaussian Copula model, it appears that the latter is not appropriate to fit well the real data based on 1) model assumptions not satisfied, 2) twice bigger reconstruction error. Therefore our DL model appears to be an efficient alternative to the widely used Gaussian Copula model.

As perspectives for further works, beyond the better reconstruction ability of our DL approach compared to the GC modeling, it is worthy mentioning that the new model can be used for simulation purposes (to generate scenarios of evolution of RMMs) and forward-looking financial steering tools, with some

applications to risk analysis of credit portfolio; this will be considered in more details in further research. In addition, in terms of financial interpretation, the clustering analysis suggests that it is possible to connect the temporal evolution of the codings with important macro-economical variables such as GDP or financial indices. The integration of these real indicators in the DL model, is one of the possible extension of the model to be considered in future works.

**Acknowledgments.** The authors gratefully acknowledge the support of the Chair Stress Test, Risk Management and Financial Steering, led by the French Ecole Polytechnique and its Foundation and sponsored by BNP Paribas.

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