

# Qualitative results for parabolic equations involving the p-Laplacian under dynamical boundary conditions

Joachim von Below, Mabel Cuesta, Gaëlle Pincet Mailly

#### ▶ To cite this version:

Joachim von Below, Mabel Cuesta, Gaëlle Pincet Mailly. Qualitative results for parabolic equations involving the p-Laplacian under dynamical boundary conditions. North-Western European Journal of Mathematics, 2018, 4, pp.59-97. hal-03715299

HAL Id: hal-03715299

https://hal.science/hal-03715299

Submitted on 6 Jul 2022

**HAL** is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers. L'archive ouverte pluridisciplinaire **HAL**, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d'enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.

# Qualitative results for parabolic equations involving the p-Laplacian under dynamical boundary conditions

Joachim von Below Mabel Cuesta Gaëlle Pincet Mailly

#### **Abstract**

We discuss comparison principles, the asymptotic behaviour, and the occurrence of blow up phenomena for nonlinear parabolic problems involving the p-Laplacian operator of the form

$$\left\{ \begin{array}{ll} \partial_t u = \Delta_p u + f(t,x,u) & \text{in } \Omega \ \text{ for } \ t>0, \\ \sigma \partial_t u + |\nabla u|^{p-2} \partial_\nu u = 0 & \text{on } \partial\Omega \ \text{ for } \ t>0, \\ u(0,\cdot) = u_0 & \text{in } \overline{\Omega}, \end{array} \right.$$

where  $\Omega$  is a bounded domain of  $\mathbb{R}^N$  with Lipschitz boundary, and where

$$\Delta_p u := \operatorname{div} \left( |\nabla u|^{p-2} \nabla u \right)$$

is the p-Laplacian operator for p>1. As for the dynamical time lateral boundary condition  $\sigma \partial_t u + |\nabla u|^{p-2} \partial_\nu u = 0$  the coefficient  $\sigma$  is assumed to be a nonnegative constant. In particular, the asymptotic behaviour in the large for the parameter dependent nonlinearity  $f(\cdot,\cdot,u)=\lambda |u|^{q-2}u$  will be investigated by means of the evolution of associated norms.

**Keywords**: nonlinear degenerate parabolic problems, p-Laplacian, dynamical boundary conditions, blow up, comparison principles.

#### 1 Introduction

This paper deals with the behaviour of solutions of nonlinear parabolic problems of the form

$$(P_{\sigma,f}) \qquad \begin{cases} \partial_t u = \Delta_p u + f(t,x,u) & \text{in } \Omega \text{ for } t > 0, \\ \sigma \partial_t u + |\nabla u|^{p-2} \partial_\nu u = 0 & \text{on } \partial \Omega \text{ for } t > 0, \end{cases}$$

LMPA Joseph Liouville ULCO, FR CNRS Math. 2956, Universités Lille Nord de France, 50, rue F. Buisson, CS 80699, F-62228 Calais, France; e-mail: below@univ-littoral.fr; cuesta@univ-littoral.fr; mailly@univ-littoral.fr

Mathematics Subject Classification (2010): Primary 35K92,35B40,35K10; Secondary 35B44, 35K57, 35K65, 35R45.

where  $\Omega$  is a bounded domain of  $\mathbb{R}^N$ ,  $N \geq 1$ , with Lipschitz boundary, and where

$$\Delta_p u := \operatorname{div} \left( |\nabla u|^{p-2} \nabla u \right)$$

is the well known p-Laplacian operator defined in  $W^{1,p}(\Omega)$  in a weak setting in the usual way for any real number p>1. Another distinctive feature in the present context is the dynamical boundary condition imposed on the time lateral boundary relating the outer normal derivative to the time derivative. For the sake of simplicity, the dynamical coefficient  $\sigma$  is assumed to be a nonnegative constant.

Of particular interest will be the Cauchy problem

$$(P_{\sigma,f_{\lambda,q},u_0}) \qquad \begin{cases} \partial_t u = \Delta_p u + \lambda |u|^{q-2} u & \text{in } \Omega \text{ for } t > 0, \\ \sigma \partial_t u + |\nabla u|^{p-2} \partial_\nu u = 0 & \text{on } \partial \Omega \text{ for } t > 0, \\ u(0,\cdot) = u_0 & \text{in } \overline{\Omega}, \end{cases}$$

where  $\lambda$  is a real parameter and q > 1.

The classical heat equation, i.e. p=2, and reaction–diffusion equations under dynamical boundary conditions have been intensively studied on  $L^q$ -spaces or spaces of continuous functions, see e.g. [BBR, BD, BP, H, P, VV] and the references therein. We refer also to [E], where Escher proves that the heat equation generates a strongly continuous analytic semigroup on  $L^q(\Omega) \times W^{1-1/q,q}(\partial\Omega)$  for q>N for more general quasilinear equations.

Some special cases of  $(P_{\sigma,f})$  for p>1 have been considered recently by Gal [G], Gal and Warma [GW] and Showalter [Sw], where the generation of the corresponding  $C^0$ -semigroups is shown. In fact, generation of  $C^0$ -semigroups in  $L^2(\Omega)$  of the p-Laplacian heat equation under Dirichlet, Neumann and Robin boundary conditions was already studied by J.L.Lions [Ls]. Boundedness and higher Hölder–regularity have been extensively treated by DiBenedetto [Di] in the homogeneous case, i.e.  $f \equiv 0$ . Recently, Cipriani and Grillo [CG] have shown generation of  $C^0$ –semigroups for the p–Laplacian under Dirichlet boundary conditions on  $L^q$ –spaces and have obtained some ultracontractivity properties of the associated semigroups.

Beyond the approaches to local existence and higher regularity of weak solutions, the existence or exclusion of global solutions, as well as the occurrence of blow up phenomena for problem  $(P_{\sigma,f})$  are of particular interest. In the works [BBR, BP, P] the authors dealt with the linear principal part, i.e. p=2, and with different nonlinearities f. A main aim in the present paper is to generalize some of the results from these references to the p-Laplacian heat equation under dynamical boundary conditions. We also prove some ultra conductivity bounds of the solutions for problem  $(P_{\sigma,0})$  that seem not to be available in the literature yet. Moreover, the absence of general boundedness result for weak solutions of  $(P_{\sigma,f})$  is one of the major difficulties in establishing the qualitative properties that we present in this work. Unfortunately, the existing results as e.g. the aforementioned ones [E, G, GW] do not apply to the equations considered here. More recent existence results by Li and You, see [LY] and the references therein, can be applied to some of the problems  $(P_{\sigma,f})$ . However, as it stands, the aim of the present paper is not to deal with

existence results, but to detail qualitative properties of solutions.

The present paper is organized as follows. In Section 2 the notion of weak solutions and of upper and lower weak solutions is made precise. Moreover, weak comparison principles are shown under a generalized one–sided Lipschitz condition imposed to f given in Definition 2.4 and involving a Lipschitz constant that can depend on the solutions. In particular, it will be shown in Theorem 2.9 that a weak lower solution  $u_1$  of  $(P_{\sigma,f,u_0^1})$  and a weak upper solution  $u_2$  of  $(P_{\sigma,f,u_0^2})$  whose initial data satisfy  $u_0^1 \leq u_0^2$  a.e. in  $\Omega$  and on  $\partial\Omega$ , maintain the same inequality for t>0. We also compare solutions under different boundary conditions, namely homogeneous Dirichlet boundary conditions vs. dynamical ones, see e.g. Theorem 2.12.

Sections 3 and 4 are devoted to the evolution of associated norms and energy functionals. For time independent nonlinearities f under a specific Lipschitz condition (3.3), the energy of weak solutions u of  $(P_{\sigma,f,u_0})$ ,  $E_F(u) = \frac{1}{p} \|\nabla u\|_p^p - \int_{\Omega} \int_0^u f(\cdot,z) \, dz \, dx$  will be shown to fulfill an identity of the form

$$-\frac{d}{dt}E_F(u(t,\cdot)) = \|\partial_t u(t,\cdot)\|_2^2 + \sigma \|\partial_t u_{|\partial\Omega}(t,\cdot)\|_{2,\partial\Omega}^2.$$
(3.4)

For the special case  $f=f_{\lambda,q}=\lambda|u|^{q-2}u$  with  $\lambda<0$ , the evolution of the  $L^2$ -norms in  $\Omega$  and on  $\partial\Omega$ , can be completely controlled leading to  $\lim_{t\to\infty}\|u(t,\cdot)\|_{\mathcal{X}^2}=0$ . In particular, for p<2, the solutions vanish to 0 in finite time, see Theorem 4.1.

In Section 5 the behaviour in the large of weak solutions u of  $(P_{\sigma,f_{\lambda,q},u_0})$  with  $\lambda \leq 0$  is investigated. For  $\lambda < 0$  and p > 2, it turns out that an analogue to Berryman and Holland's asymptotic result for the porous media equation [BH] holds, i.e. there is a sequence of time steps  $(t_n)_{n \in \mathbb{N}}$  tending to  $\infty$  such that

$$\lim_{n \to \infty} \|(1 + (p-2)t_n)^{\frac{2}{p-2}} u(t_n, \cdot) - w\|_{\mathcal{X}^2} = 0,$$
 (Theorem 5.1)

where  $w \in W^{1,p}(\Omega)$  is the solution of the elliptic equation  $-\Delta_p w - \lambda |w|^{p-2} w = w$  under the Robin–Steklov boundary condition stemming from the dynamical one. Another distinctive asymptotic result in this section deals with the solutions for the homogeneous problem  $(P_{\sigma,0,u_0})$  and says that

$$\lim_{t \to \infty} u(t, \cdot) = \frac{\int_{\Omega} u_0 \, dx + \sigma \oint_{\partial \Omega} u_0 \, d\rho}{|\Omega| + \sigma |\partial \Omega|}$$
 (Theorem 5.2)

in  $W^{1,p}(\Omega)$ . Note that this asymptotic formula is exactly the same as for the classical Laplacian [BBR], i.e. p=2, established via Fourier expansion of the initial data, that, however, does not apply for  $p\neq 2$ . For initial data belonging to  $W^{1,p}(\Omega)$  this holds also with respect to the  $L^{\infty}$ -norm, see Theorem 5.3, and will be very useful in order to guarantee strict positivity a.e. in finite time, e.g. when showing the exclusion of global existence, see Theorem 6.1 without using a strong parabolic minimum principle. It turns out that  $\lambda=0$  plays the same role under dynamical boundary conditions as the first eigenvalue  $\lambda_1$  does for homogeneous Dirichlet boundary conditions as it has been shown in [LX]. For short, for  $\lambda\leq 0$  the weak solutions are bounded for each t>0, while for

 $\lambda > 0$  blow up occurs for q = p > 2 and for  $q > \max\{2, p\}$ . Closing this section, we deduce global existence close to an equilibrium fulfilling f'(B) < 0 in the general autonomous case  $\partial_t u = \Delta_p u + f(u)$ , see Theorem 5.5.

Section 6 deals with the occurrence of blow up phenomena with respect to the  $L^{\infty}$ -norm. First, we generalize the result on the non existence of global solutions from [BBR] to the p-Laplacian with nonlinearities f(t,x,u)=m(t,x)g(u) under the same assumptions as in [BBR], see Theorem 6.1. As for Problem  $(P_{\sigma,f_{\lambda,q},u_0})$  with  $\lambda>0$  and q>2, it remains to determine the behaviour in the large. In fact, for p=q and for initial energy  $\frac{1}{p}\int_{\Omega}(|\nabla u_0|^p-|u_0|^p)\,dx<0$  it will be shown that solutions blow up in finite time, see Theorem 6.4. For  $q>\max\{2,p\}$  we first adopt a technique developed in [Ba, BP] in order to establish an upper bound for the blow up time under homogeneous Dirichlet boundary conditions for initial data  $0\neq u_0\in W_0^{1,p}(\Omega)\cap L^{\infty}(\Omega)$  with energy  $\frac{1}{p}\int_{\Omega}|\nabla u_0|^p\,dx-\frac{\lambda}{q}\int_{\Omega}|u_0|^q\,dx\leq 0$ , see Theorem 6.5. Then the comparison techniques from Section 2 apply in order to establish the occurrence of blow up under dynamical boundary conditions too, see Theorems 6.6 and Corollary 6.7 for nonlinearities satisfying  $f(\cdot,\cdot,z)\geq \lambda|z|^{q-2}z$ . In the latter one it will be shown that for initial data  $u_0\in W_0^{1,p}(\Omega)\cap L^{\infty}(\Omega;[0,\infty))$  with nonpositive energy the  $L^2$ -norm of the weak solution of  $(P_{\sigma,f,u_0})$  blows up at the latest at time T with

$$T_{\max}(u) \le T \le \frac{q}{\lambda(q-2)(q-p)} |\Omega|^{\frac{q-2}{2}} \left( \int_{\Omega} |u_0|^2 dx \right)^{\frac{2-q}{2}},$$
 (Corollary 6.7)

where  $T_{\max}(u)$  is the maximal existence time with respect to the  $L^{\infty}$ -norm. Finally, we present an optimal upper bound for the blow up time under the Neumann boundary condition based on the evolution of the  $L^{1}$ -norm.

We close this introduction with some notations and the abstract formulation of the evolution problem. We shall denote by  $d\rho$  the restriction to  $\partial\Omega$  of the (N-1)-dimensional Hausdorff measure, which coincides with the usual Lebesgue hypersurface measure, since  $\partial\Omega$  is supposed to be Lipschitz. Moreover, we shall denote by  $\nu=\nu(x)$  its outer normal vector field at  $x\in\partial\Omega$  defined  $\rho$ -a.e. in  $\partial\Omega$ .

The Lebesgue norm of  $L^q(\Omega)$  will be denoted by  $\|\cdot\|_q$ , and the Lebesgue norm of  $L^q(\partial\Omega,\rho)$  by  $\|\cdot\|_{q,\partial\Omega}$ , for  $q\in[1,\infty]$ . The scalar product of  $L^2(\Omega)$  will be denoted by  $\langle\cdot,\cdot\rangle$  and the scalar product of  $L^2(\partial\Omega,\rho)$  will be denoted by  $\langle\cdot,\cdot\rangle_0$ :

$$\langle u, v \rangle = \int_{\Omega} uv \, dx, \quad \langle u, v \rangle_0 = \oint_{\partial \Omega} uv \, d\rho.$$

The conjugate of any  $r \in [1,\infty]$  will be denoted by r'. The critical Sobolev exponent for the embedding  $W^{1,p}(\Omega) \hookrightarrow L^q(\Omega)$  will be denoted by  $p^* := \frac{pN}{N-p}$  if  $1 , and by <math>p^* = \infty$  otherwise. It is worth noting that

$$W^{1,p}(\Omega) \hookrightarrow L^2(\Omega) \iff p \ge p_0 := \frac{2N}{N+2}.$$

The trace  $u_{|_{\partial\Omega}}$  of any function  $u\in W^{1,p}(\Omega)$  is well defined since  $\partial\Omega$  is regular enough. We recall that, if  $\gamma$  denotes the trace operator, then  $\gamma(W^{1,p}(\Omega))=W^{1-1/p,p}(\partial\Omega,\rho)$ .

Moreover, the trace operator  $W^{1,p}(\Omega) \to L^q(\partial\Omega,\rho)$  is continuous if and only if  $1 \le q \le p_*$  if  $p \ne N$  and for  $1 \le q < \infty$  if p = N. Recall that  $p_* := \frac{p(N-1)}{N-p}$  if  $1 , and that <math>p_* = \infty$  if  $p \ge N$ . Note that for q = 2, the trace operator is well-defined and continuous under the following condition:

$$W^{1,p}(\Omega) \to L^2(\partial\Omega, \rho) \iff p \ge p_1 := \frac{2N}{N+1}.$$

Finally, for a reflexive Banach space  $(V, \|\cdot\|_V)$  and  $r \in [1, \infty)$ , the classical Bochner space  $L^r((0, T); V)$  will be endowed with the norm

$$||u||_{L^r((0,T);V)} := \left(\int_0^T ||u||_V^r dt\right)^{1/r}.$$

# 2 Weak solutions, comparison principles and uniqueness results

Throughout this paper, unless otherwise stated, we shall assume that  $p>p_1$  and  $p\neq 2$ . The case  $1< p< p_1$  is a bit more involved, as one has to work with functions belonging to  $W^{1,p}(\Omega)\cap L^2(\Omega)$  having  $L^2(\partial\Omega,\rho)$ -trace instead of  $W^{1,p}(\Omega)$ . The case  $p=p_1$  should also be treated separately, as the Sobolev embedding  $W^{1,p}(\Omega)\to L^{p_*}(\partial\Omega,\rho)$  is not compact bearing in mind that here  $p_*=2$ .

Set 
$$\mathcal{X}^q = L^q(\Omega) \times L^q(\partial\Omega, \rho)$$
, for  $1 \leq q \leq \infty$ , and

$$U = (u, \varphi) \in \mathcal{X}^q, \qquad ||U||_{\mathcal{X}^q} := (||u||_q^q + \sigma ||\varphi||_{q,\partial\Omega}^q)^{1/q},$$

and for q=2 and  $U=(u,\varphi), V=(v,\psi)\in\mathcal{X}^2$ 

$$\langle U, V \rangle_{\mathcal{X}^2} := \langle u, v \rangle + \sigma \langle \varphi, \psi \rangle_0.$$

Identifying each element  $u \in W^{1,p}(\Omega)$  with the vector  $U = (u,u_{|\partial\Omega})$ , the space  $W^{1,p}(\Omega)$  can be regarded as a subspace of  $\mathcal{X}^s$  for any  $1 \leq s < p_*$ . Moreover,  $\mathcal{X}^s$  and  $L^s(\overline{\Omega},d\tau)$  can be identified in a natural way for  $s \geq 1$ , where the measure  $d\tau = dx_{|\Omega} \oplus d\rho_{|\partial\Omega}$  is defined for any measurable set  $A \subset \overline{\Omega}$  by  $\tau(A) = |A| + \rho(A \cap \partial\Omega)$ . We will agree that A is *measurable* if  $A \cap \Omega$  is Lebesgue measurable and  $A \cap \partial\Omega$  is measurable with respect to the (N-1)-Hausdorff measure  $\rho$ .

For any T > 0, let us denote  $\Omega_T = (0, T) \times \Omega$ . Let us recall the definition of a local weak solution of the evolution problem  $(P_{\sigma,f})$ . Let  $f : \Omega_T \times \mathbb{R} \to \mathbb{R}$  be a Carathéodory function.

**Definition 2.1.** A function  $u: \overline{\Omega}_T \to \mathbb{R}$  is called a weak solution of problem  $(P_{\sigma,f})$  if

(i) 
$$u \in L^p((0,T); W^{1,p}(\Omega)) \cap C([0,T]; \mathcal{X}^2)$$
,

(ii) 
$$\partial_t u \in L^2((0,T); L^2(\Omega)); \ \partial_t u|_{\partial\Omega} \in L^2((0,T); L^2(\partial\Omega,\rho)),$$

(iii) 
$$\tilde{f} := f(\cdot, \cdot, u(\cdot, \cdot)) \in L^2((0, T); L^2(\Omega)),$$

(iv) for any  $\varphi \in W^{1,p}(\Omega)$  and for almost all  $t \in [0,T]$  it holds

$$\langle \partial_t u, \varphi \rangle + \langle |\nabla u|^{p-2} \nabla u, \nabla \varphi \rangle - \langle f(t, x, u), \varphi \rangle + \sigma \langle \partial_t u_{|\partial\Omega}, \varphi \rangle_0 = 0.$$

Clearly, in (ii) the notation  $\partial_t u$  (resp.  $\partial_t u_{|\partial\Omega}$ ) stands for the weak temporal derivative of u(resp. of  $u_{|\partial\Omega}$ ).

By writing  $u \in \mathcal{X}^q$  we mean that  $u : \overline{\Omega} \to \mathbb{R}$  is such that  $u_{|_{\Omega}} \in L^q(\Omega)$  and also  $u_{|_{\partial\Omega}} \in L^q(\partial\Omega, \rho)$ .

**Definition 2.2.** For given  $u_0 \in \mathcal{X}^2$  a function  $u : \overline{\Omega}_T \to \mathbb{R}$  is called a weak solution of the Cauchy problem  $(P_{\sigma,f,u_0})$ 

$$(P_{\sigma,f,u_0}) \qquad \begin{cases} \partial_t u = \Delta_p u + f(t,x,u) & \text{in } \Omega \text{ for } t > 0, \\ \sigma \partial_t u + |\nabla u|^{p-2} \partial_\nu u = 0 & \text{on } \partial\Omega \text{ for } t > 0, \\ u(0,\cdot) = u_0 & \text{in } \overline{\Omega}, \end{cases}$$

if u is a weak solution of  $(P_{\sigma,f})$  in the sense of Definition 2.1 and if, in addition,

$$u(0,\cdot) = u_0 \quad \tau$$
-a.e. in  $\overline{\Omega}$ .

Let us also recall the definition of upper and lower solution for our evolution problem. Writing  $(u,\varphi) \leq (v,\psi)$  for functions belonging to  $\mathcal{X}^s$  means that  $u \leq v$  a.e. in  $\Omega$  and that  $\varphi \leq \psi$   $\rho$ -a.e. on  $\partial\Omega$ .

**Definition 2.3.** For given  $u_0 \in \mathcal{X}^2$ , a function  $u: \Omega_T \to \mathbb{R}$  satisfying (i)-(iii) from Definition 2.1 is called a weak lower solution of  $(P_{\sigma,f,u_0})$  if for all  $\varphi \in W^{1,p}(\Omega)$  with  $\varphi \geq 0$ , and for almost all  $t \in [0,T]$ 

$$\begin{cases} \langle \partial_t u, \varphi \rangle + \langle |\nabla u|^{p-2} \nabla u, \nabla \varphi \rangle - \langle f(t, x, u), \varphi \rangle + \sigma \langle \partial_t u, \varphi \rangle_0 \leq 0, \\ u(0, \cdot) \leq u_0 \quad \tau \text{-a.e. in } \overline{\Omega}, \end{cases}$$

in its interval of existence. Similarly, a weak upper solution is defined by reversing the last two inequalities.

In order to compare two different solutions of the evolution equations, it is necessary to require some Lipschitz condition on f with respect to the variable u and with respect to the pair  $(u_1, u_2) \in L^2(\Omega_T)^2$ . This is the motivation of the following definition.

**Definition 2.4.** A function f is said to satisfy the following one-sided Lipschitz condition for the pair  $(u_1, u_2) \in L^2(\Omega_T)^2$  if

$$\exists l \in L^{1}((0,T);[0,\infty)) \text{ such that for a.a. } (t,x) \in \Omega_{T},$$

$$[f(t,x,u_{1}(t,x)) - f(t,x,u_{2}(t,x)) - l(t)(u_{1}(t,x) - u_{2}(t,x))] (u_{1}(t,x) - u_{2}(t,x))^{+} \leq 0.$$
(2.1)

Observe that no ordered between  $u_1$  and  $u_2$  is assumed here and that (2.1) is in fact a condition for the set of  $(t,x) \in \Omega_T$  for which  $u_1(t,x) \ge u_2(t,x)$ . At the end of this section, we shall give some special cases where (2.1) is satisfied, c.f. Remark 2.15. Let us prove the following comparison result.

**Theorem 2.5.** Let  $u_0^1$ ,  $u_0^2 \in \mathcal{X}^2$  be given, let  $u_1$  be a weak lower solution of  $(P_{\sigma,f,u_0^1})$  and let  $u_2$  be a weak upper solution of  $(P_{\sigma,f,u_0^2})$ . Assume that the pair  $(u_1,u_2)$  satisfies (2.1) and let us denote  $v := u_1 - u_2$ ,  $v_0 := u_0^1 - u_0^2$ . Then

- (i)  $||v^+(t,\cdot)||_{\mathcal{X}^2}^2 \le e^{2L(t)} ||v_0^+||_{\mathcal{X}^2}^2$  for all  $t \in [0,T]$ , with  $L(t) := \int_0^t l(s) \, ds$ .
- (ii) Moreover, there exists a constant  $C = C(p, N, T, ||l||_1) > 0$  such that

$$\|\nabla v^{+}\|_{L^{p}(\Omega_{T})}^{p} \leq \begin{cases} C\|v_{0}^{+}\|_{\mathcal{X}^{2}}^{2} & \text{if } p \geq 2, \\ C\|v_{0}^{+}\|_{\mathcal{X}^{2}}^{p} (\|\nabla u_{1}\|_{L^{p}(\Omega_{T})} + \|\nabla u_{2}\|_{L^{p}(\Omega_{T})})^{p(1-\frac{p}{2})} & \text{if } p < 2. \end{cases}$$

$$(2.2)$$

*Proof.* (i) Fixing  $t \in [0,T]$  and taking  $\varphi = v^+(t,\cdot)$  as a test function in the differential inequalities satisfied by  $u_1$  and  $u_2$ , subtracting them and integrating over  $\Omega$  yield

$$\langle \partial_t v, v^+ \rangle + \sigma \langle \partial_t v, v^+ \rangle_0 \le - \langle |\nabla u_1|^{p-2} \nabla u_1 - |\nabla u_2|^{p-2} \nabla u_2, \nabla (u_1 - u_2)^+ \rangle + \langle f(t, x, u_1) - f(t, x, u_2), v^+ \rangle.$$
 (2.3)

Here Conditions (i)-(iv) from Definition 2.1 assure that all the above integrals are finite. By convexity of the function  $z\mapsto |z|^p$  in  $\mathbb{R}^N$  the first term of the r.h.s. is negative, while the second term is bounded from above by  $l(t)\langle v(t,\cdot),v^+(t,\cdot)\rangle$  using (2.1). Moreover, we deduce for almost all t that

$$\langle \partial_t v, v^+ \rangle = \frac{1}{2} \frac{d}{dt} \|v^+\|_2^2,$$
$$\langle \partial_t v, v^+ \rangle_0 = \frac{1}{2} \frac{d}{dt} \|v^+\|_{2,\partial\Omega}^2.$$

These identities and the existence of the derivatives on the r.h.s. are justified, see e.g. [Sw, Chapter III, Proposition 1.2]. It follows that

$$\frac{d}{dt} \|v^+\|_2^2 + \sigma \frac{d}{dt} \|v^+\|_{2,\partial\Omega}^2 \le 2l(t) \|v^+\|_2^2,$$

and therefore, by the Bellman–Gronwall Inequality [Bel]

$$||v^+(t,\cdot)||_{\mathcal{X}^2}^2 \le e^{2L(t)}||v_0^+||_{\mathcal{X}^2}^2$$

for all  $t \in [0, T]$ .

(ii) We apply the following inequality from [Si]:  $\exists C = C(p, N) > 0 \, \forall z_1, z_2 \in \mathbb{R}^N$ :

$$\begin{cases} \langle |z_{1}|^{p-2}z_{1} - |z_{2}|^{p-2}z_{2}, z_{1} - z_{2}\rangle_{\mathbb{R}^{N}} \geq C|z_{1} - z_{2}|_{\mathbb{R}^{N}}^{p}, & \text{if } p \geq 2, \\ \langle |z_{1}|^{p-2}z_{1} - |z_{2}|^{p-2}z_{2}, z_{1} - z_{2}\rangle_{\mathbb{R}^{N}} \geq C(|z_{1}|_{\mathbb{R}^{N}} + |z_{2}|_{\mathbb{R}^{N}})^{p-2}|z_{1} - z_{2}|_{\mathbb{R}^{N}}^{2}, & \text{if } 1$$

In order to bound from above the first term of the r.h.s. of (2.3) by  $C\|\nabla v^+(t,\cdot)\|_p^p$  if  $p \geq 2$  or by  $C\int_{\Omega}(|\nabla u_1(t,x)|+|\nabla u_2(t,x)|)^{p-2}|\nabla v^+(t,x)|^2\,dx$  if p < 2. Therefore we deduce for almost all t that

$$\frac{1}{2}\frac{d}{dt}\|v^{+}(t,\cdot)\|_{\mathcal{X}^{2}}^{2} + Ca(t) \le l(t)\|v^{+}(t,\cdot)\|_{\mathcal{X}^{2}}^{2},$$

where we abbreviate

$$a(t) = \begin{cases} \|\nabla v^{+}(t, \cdot)\|_{p}^{p}, & \text{if } p \geq 2, \\ \int_{\Omega} (|\nabla u_{1}(t, \cdot)| + |\nabla u_{2}(t, \cdot)|)^{p-2} |\nabla v^{+}(t, \cdot)|^{2} dx, & \text{if } 1$$

Integrating over [0, T] and using the estimate (i) we obtain

$$\frac{1}{2}(\|v^{+}(T,\cdot)\|_{\mathcal{X}^{2}}^{2} - \|v^{+}(0,\cdot)\|_{\mathcal{X}^{2}}^{2}) + C \int_{0}^{T} a(t) dt \leq \|l\|_{1} e^{2L(T)} \|v_{0}^{+}\|_{\mathcal{X}^{2}}^{2}$$

i.e.

$$\int_0^T a(t) dt \le \frac{1}{C} \left( \|l\|_1 e^{2L(T)} + \frac{1}{2} \right) \|v_0^+\|_{\mathcal{X}^2}^2.$$

If  $p \ge 2$ , then the statement (ii) is clear. Consider p < 2. First, Hölder's inequality leads to

$$\|\nabla v^{+}\|_{p}^{p} \leq a(t)^{\frac{p}{2}} \left( \int_{\Omega} (|\nabla u_{1}| + |\nabla u_{2}|)^{p} dx \right)^{1 - \frac{p}{2}}$$

$$\leq 2^{(p-1)(1 - \frac{p}{2})} a(t)^{p/2} \left( \|\nabla u_{1}\|_{p}^{p} + \|\nabla u_{2}\|_{p}^{p} \right)^{1 - \frac{p}{2}},$$

since 1 . Then, we use Hölder's inequality with respect to the dependence on <math>t and obtain

$$\begin{split} \|\nabla v^+\|_{L^p(\Omega_T)}^p &\leq 2^{(p-1)(1-\frac{p}{2})} \left( \int_0^T a(t) \, dt \right)^{p/2} \left( \|\nabla u_1\|_{L^p(\Omega_T)}^p + \|\nabla u_2\|_{L^p(\Omega_T)}^p \right)^{1-\frac{p}{2}} \\ &\leq 2^{(p-1)(1-\frac{p}{2})} \left( \int_0^T a(t) \, dt \right)^{p/2} \left( \|\nabla u_1\|_{L^p(\Omega_T)} + \|\nabla u_2\|_{L^p(\Omega_T)} \right)^{p(1-\frac{p}{2})}. \end{split}$$

Immediate consequences of the previous theorem are given by the following corollaries.

**Corollary 2.6.** Let  $f_1, f_2 : \Omega_T \to \mathbb{R}$  be two measurable functions such that  $f_1 \leq f_2$  a.a.  $(t,x) \in \Omega_T$ . Let  $u_0^1, u_0^2 \in \mathcal{X}^2$  be given, let  $u_1$  be a weak lower solution of  $(P_{\sigma,f_1,u_0^1})$  and let  $u_2$  be a weak upper solution of  $(P_{\sigma,f_2,u_0^2})$ . Then the conclusions (i) and (ii) hold with  $l \equiv 0$ .

**Corollary 2.7.** Let  $u_0 \in \mathcal{X}^2$  be given. Let  $u_1$  and  $u_2$  be two weak solutions of  $(P_{\sigma,f,u_0})$ . Assume that the pair  $(u_1, u_2)$  satisfies the Lipschitz condition:

$$\exists l \in L^{1}(0,T), \ l \geq 0, \ \text{such that for a.a.} \ (t,x) \in \Omega_{T},$$

$$[f(t,x,u_{1}(t,x)) - f(t,x,u_{2}(t,x)) - l(t)(u_{1}(t,x) - u_{2}(t,x))] \left(u_{1}(t,x) - u_{2}(t,x)\right) \leq 0.$$
(2.5)

Then for all  $t \in [0,T]$ ,  $u_1(t,\cdot) = u_2(t,\cdot)$  a.e. in  $\Omega$ .

Note that (2.5) implies (2.1) for both  $(u_1 - u_2)^+$  and  $(u_1 - u_2)^-$ , which means that uniqueness is plain. For the Lipschitz case we can state the following

**Corollary 2.8.** Assume that f satisfies the following Lipschitz condition (2.6) with respect to the variable u:

$$\exists l \in L^{1}(0,T), \ l \geq 0, \ \text{such that for a.a.} \ (t,x) \in \Omega_{T}, \ \text{for all} \ (u_{1},u_{2}) \in \mathbb{R}^{2},$$
$$\left[f(t,x,u_{1}) - f(t,x,u_{2}) - l(t)(u_{1} - u_{2})\right] \left(u_{1} - u_{2}\right) \leq 0. \tag{2.6}$$

Let  $u_0 \in \mathcal{X}^2$ . Let  $(u_n^0)_{n \in \mathbb{N}}$  be a sequence in  $\mathcal{X}^2$  such that  $\lim_{n \to \infty} \|u_n^0 - u_0\|_{\mathcal{X}^2} = 0$ . Let  $u_n$  be a weak solution of  $(P_{\sigma,f,u_0})$  and u a weak solution of  $(P_{\sigma,f,u_0})$ . Then  $u_n(t,\cdot) \to u(t,\cdot)$  in  $\mathcal{X}^2$  and  $u_n \to u$  in  $L^p((0,T);W^{1,p}(\Omega))$ .

*Proof.* The convergence in  $\mathcal{X}^2$  follows readily from (i) of Theorem 2.5. From (ii), if p > 2, we have directly that there exists a constant  $C = C(p, N, T, ||l||_1) > 0$  such that

$$\|\nabla u_n - \nabla u\|_{L^p(\Omega_T)}^p \le C\|u_n^0 - u_0\|_{\mathcal{X}^2}^2.$$

If p < 2 we have

$$\|\nabla u_n - \nabla u\|_{L^p(\Omega_T)}^p \le C\|u_n^0 - u_0\|_{\mathcal{X}^2}^p (\|\nabla u_n\|_{L^p(\Omega_T)} + \|\nabla u\|_{L^p((\Omega_T)})^{p(1-\frac{p}{2})}.$$

Since  $\|u_n^0 - u_0\|_{\mathcal{X}^2} \to 0$ , the latter inequality yields that the sequence  $\|\nabla u_n\|_{L^p(\Omega_T)}$  is bounded and therefore  $\|\nabla u_n - \nabla u\|_{L^p(\Omega_T)}^p \to 0$ .

Another consequence of Theorem 2.5 is the following standard comparison principle.

**Theorem 2.9** (Weak comparison principle with dynamical boundary condition). Let  $u_0^1, u_0^2 \in \mathcal{X}^2$  satisfy  $u_0^1 \leq u_0^2 \tau$ -a.e. in  $\overline{\Omega}$ . Let  $u_1$  be a weak lower solution of  $(P_{\sigma,f,u_0^1})$  and let  $u_2$  be a weak upper solution of  $(P_{\sigma,f,u_0^2})$ . Assume that the pair  $(u_1,u_2)$  satisfies (2.1). Then

$$u_1(t,\cdot) \leq u_2(t,\cdot) \quad \tau$$
-a.e. in  $\overline{\Omega}$ .

*Proof.* By hypothesis

$$\|(u_1(0,\cdot)-u_2(0,\cdot))^+\|_2 = \|(u_0^1-u_0^2)^+\|_2 = 0$$

and

$$\|(u_1(0,\cdot)-u_2(0,\cdot))^+\|_{2,\partial\Omega}^2 = \|(u_0^1-u_0^2)^+\|_{2,\partial\Omega} = 0.$$

Hence, from Theorem 2.5 (i) it follows that  $(u_1(t,\cdot)-u_2(t,\cdot))^+=0$  a.e. in  $\Omega$ , which permits to conclude.

In Section 5 we need to compare a weak solution of a parabolic problem with dynamical boundary condition with a solution of the analogous parabolic problem under homogeneous Dirichlet boundary condition for the forcing term

$$f(t, x, u) = f_{\lambda, q}(u) := \lambda |u|^{q-2} u$$

with  $\lambda > 0$  and  $q > \max\{2, p\}$ . Let us consider here a more general parabolic problem for the p-Laplacian under Dirichlet boundary condition

$$\begin{cases}
\partial_t v = \Delta_p v + f(t, x, v) & \text{in } \Omega \text{ for } t > 0, \\
v = 0 & \text{on } \partial\Omega \text{ for } t > 0, \\
v(0, \cdot) = v_0 & \text{in } \Omega,
\end{cases}$$
(2.7)

for an initial value  $v_0 \in L^2(\Omega)$ . A function  $v:[0,T]\times\Omega\to\mathbb{R}$  is called a weak solution of (2.7) if  $v\in L^p((0,T);W^{1,p}_0(\Omega))\cap C([0,T];L^2(\Omega)),$   $\partial_t v\in L^2(\Omega_T),$   $v(0,\cdot)=v_0$  a.e. in  $\Omega$  and for any test function  $\varphi\in W^{1,p}_0(\Omega)$  we have

$$\langle \partial_t v, \varphi \rangle + \langle |\nabla v|^{p-2} \nabla v, \nabla \varphi \rangle - \langle f(t, x, v), \varphi \rangle = 0$$

for a.a.  $t \in (0,T)$ . Correspondingly, we define upper and lower solutions for Problem (2.7). For the sake of completeness let us state the following Weak Comparison Principle for Problem (2.7), though the result is partially known, namely for the special case  $f \equiv 0$ , c.f. [Di].

**Theorem 2.10** (Weak Comparison Principle with Dirichlet boundary condition). Let  $v_1$  be a lower weak solution of (2.7) with initial data  $v_0^1 \in L^2(\Omega)$  and let  $v_2$  be an upper weak solution of (2.7) with initial data  $v_0^2 \in L^2(\Omega)$ , satisfying  $v_0^1 \leq v_0^2$  a.e. in  $\Omega$ . Assume further that the pair  $(v_1, v_2)$  satisfies the one-sided Lipschitz condition (2.1). Then  $v_1(t, \cdot) \leq v_2(t, \cdot)$  a.e. in  $\Omega$ , for all  $t \in [0, T]$ .

*Proof.* Fix  $t \in [0, T]$ . The choice of  $\varphi \equiv (v_1(t, \cdot) - v_2(t, \cdot))^+$  leads to

$$\langle \partial_t (v_1 - v_2), (v_1 - v_2)^+ \rangle = -\int_{\Omega} (|\nabla v_1|^{p-2} \nabla v_1 - |\nabla v_2|^{p-2} \nabla v_2) \cdot \nabla (v_1 - v_2)^+ dx + \int_{\Omega} (f(t, x, v_1) - f(t, x, v_2))(v_1 - v_2)^+ dx.$$

Thus, by convexity of the function  $z \in \mathbb{R}^N \mapsto |z|^p$  and by Condition (2.1),

$$\langle \partial_t (v_1 - v_2), (v_1 - v_2)^+ \rangle \le l(t) \| (v_1 - v_2)^+ \|_2^2$$

As in the proof of the Theorem 2.9 we can conclude

$$2\int_0^s l(t)\|(v_1(t,\cdot)-v_2(t,\cdot))^+\|_2^2 dt \ge \int_0^s \frac{d}{dt}\|(v_1(t,\cdot)-v_2(t,\cdot))^+\|_2^2 dt = \|(v_1(s,\cdot)-v_2(s,\cdot))^+\|_2^2 - \|(v_1(0,\cdot)-v_2(0,\cdot))^+\|_2^2.$$

By the Bellman–Gronwall Inequality and that  $(v_1(0,\cdot)-v_2(0,\cdot))^+=(v_0^1-v_0^2)^+=0$  a.e. in  $\Omega$ , it follows that  $\|(v_1(s,\cdot)-v_2(s,\cdot))^+\|_2^2 \leq e^{2L(s)}\|(v_1(0,\cdot)-v_2(0,\cdot))^+\|_2^2=0$  for all  $s\in[0,T]$ , which permits to conclude.

As a consequence of the previous theorem we have

**Proposition 2.11** (Weak Maximum Principle with Dirichlet boundary condition). Let v be a weak upper solution of (2.7) with initial data  $v_0 \in L^2(\Omega)$  satisfying  $v_0 \ge 0$  a.e. in  $\Omega$ . Assume further that  $f(\cdot, \cdot, 0) \ge 0$  and that the pair (0, v) satisfies the one-sided Lipschitz condition (2.1). Then v satisfies  $v(t, \cdot) \ge 0$  a.e. in  $\Omega$ , for all  $t \in [0, T]$ .

Finally, we compare solutions of parabolic problems under dynamical boundary conditions and nonnegative solutions of parabolic problems under Dirichlet boundary conditions. For that purpose, the solution v of (2.7) is required to fulfill  $v(t,\cdot) \in C^1(\overline{\Omega})$ , since we shall need some estimates of the gradient of the solution  $v(t,\cdot)$  on  $\partial\Omega$ . See also the Remark 2.13 below about the regularity of weak solutions of Problem (2.7).

**Theorem 2.12.** Assume that  $\partial\Omega$  is of class  $C^2$ . Let u be a weak lower solution of Problem  $(P_{\sigma,f,u_0})$  with initial data  $u_0 \in \mathcal{X}^2$ . Let v be the weak solution of Problem (2.7) with initial data  $v_0 \in L^2(\Omega)$ , satisfying  $v_0 \geq 0$  a.e. in  $\Omega$ . Assume that

- (i)  $f(\cdot, \cdot, 0) > 0$ ,
- (ii) the pair (0, v) satisfies the one-sided Lipschitz condition (2.1),
- (iii) the pair (v, u) satisfies the one-sided Lipschitz condition (2.1),
- (iv) for all  $t \in (0,T)$ ,  $v(t,\cdot) \in C^1(\overline{\Omega})$ .

If, in addition,

$$u_0 \ge v_0 \ge 0$$
 a.e. in  $\Omega$ ,  $u_0 \ge 0$   $\rho$ -a.e. in  $\partial \Omega$ , (2.8)

then  $u(t,\cdot) \geq v(t,\cdot)$  a.e. in  $\Omega$ , for all  $t \in [0,T]$ .

*Proof.* By Theorem 2.10 and hypotheses (i) and (ii), the solution v is nonnegative in  $[0,T]\times\Omega$ . Since  $v(t,\cdot)\in W^{1,p}_0(\Omega)\cap C(\overline{\Omega})$ , and since  $\partial\Omega$  is of class  $C^1$ , the solution v has to vanish on  $\partial\Omega$  for all  $t\in(0,T)$ . Thus,  $\partial_{\nu}v(t,\cdot)\leq 0$  on  $\partial\Omega$  for all  $t\in(0,T)$ , and multiplying the differential equation of Problem (2.7) by any nonnegative function  $\varphi\in W^{1,p}(\Omega)$  and integrating over  $\Omega$  yield

$$\langle \partial_t v, \varphi \rangle = -\langle |\nabla v|^{p-2} \nabla v, \nabla \varphi \rangle + \langle |\nabla v|^{p-2} \partial_\nu v, \varphi \rangle_0 + \langle f(t, x, v), \varphi \rangle$$

$$\leq -\langle |\nabla v|^{p-2} \nabla v, \nabla \varphi \rangle + \langle f(t, x, v), \varphi \rangle. \quad (2.9)$$

Although the test function  $\varphi$  used in the weak formulation of Problem (2.7) must belong to  $W_0^{1,p}(\Omega)$ , the above integration by parts is justified e.g. by Lemma A.1 from [CT]. Hence,  $\partial_t v(t,\cdot) \equiv 0$  on  $\partial\Omega$ , (2.9), and the weak formulation of Problem  $(P_{\sigma,f,u_0})$  with the test function  $w(t,\cdot) = (v(t,\cdot) - u(t,\cdot))^+$  yield that

$$\int_{\epsilon}^{s} (\langle \partial_{t} w, w \rangle + \sigma \langle \partial_{t} w, w \rangle_{0}) dt \leq \int_{\epsilon}^{s} \langle |\nabla v|^{p-2} \nabla v - |\nabla u|^{p-2} \nabla u, \nabla w \rangle dt + \int_{\epsilon}^{s} \langle f(t, x, v) - f(t, x, u), w \rangle dt.$$

for any  $0 < \epsilon < s < T$ . By convexity of the function  $z \mapsto |z|^p$  in  $\mathbb{R}^N$ , the first integral on the r.h.s. is seen to be positive, which implies in turn that

$$\frac{1}{2} \int_{\epsilon}^{s} \frac{d}{dt} \|w(t, \cdot)\|_{\mathcal{X}^{2}}^{2} dt \le \int_{\epsilon}^{s} \langle f(t, x, v) - f(t, x, u), w \rangle dt$$

and

$$||w(s,\cdot)||_{\mathcal{X}^{2}}^{2} - ||w(\epsilon,\cdot)||_{\mathcal{X}^{2}}^{2} \leq 2 \int_{\epsilon}^{s} \left( \int_{\Omega} |f(t,x,v) - f(t,x,u)| \, w \, dx \right) \, dt$$

$$\leq 2 \int_{\epsilon}^{s} |l(t)||w(t,\cdot)||_{2}^{2} \, dt. \quad (2.10)$$

As  $w(\epsilon, \cdot) = u^{-}(\epsilon, \cdot) \rho$ -a.e. in  $\partial \Omega$ ,

$$\lim_{\epsilon \to 0} \|w(\epsilon, \cdot)\|_{\mathcal{X}^2}^2 = \|w(0, \cdot)\|_2^2 + \sigma \|u_0^-\|_{2, \partial \Omega}^2 = 0$$

by (2.8). Thus (2.10) reduces to

$$||w(s,\cdot)||_2^2 \le 2 \int_0^s l(t) ||w(t,\cdot)||_2^2 dt.$$

As the function l(t) is integrable and nonnegative, the Bellman–Gronwall Inequality yields

$$\forall s \in [0, T] : ||w(s, \cdot)||_2^2 = 0.$$

Thus, we can conclude that  $v(s,\cdot) \leq u(s,\cdot)$  a.e. in  $\Omega$  for all  $s \in [0,T]$ .

**Remark 2.13.** Standard regularity results (c.f. [Li, Theorem 01]) imply that a weak solution v of Problem (2.7) satisfies  $v \in C^1((0,T] \times \overline{\Omega})$  provided that  $v \in L^{\infty}((\epsilon,T) \times \Omega)$  for all  $\epsilon \in (0,T)$  and that  $\partial \Omega$  is of class  $C^{1,\alpha}$  for some  $0 < \alpha < 1$ .

**Remark 2.14.** In order to assure the global boundedness in the large of any weak solution v of Problem (2.7), that is,  $v \in L^{\infty}((\epsilon, T) \times \Omega)$ , one should impose to f a growth condition with respect to the u-variable, say e.g.

$$|f(t, x, v)| \le A|v|^{q-1}$$
 for  $a.a.(t, x) \in (\epsilon, T) \times \Omega, \forall v \in \mathbb{R}$ ,

with q (c.f [Di, Theorem 3.2 Chapter V]).

**Remark 2.15.** In the special case  $f(t, x, u) = f_{\lambda,q}(u)$ , with q > 1

- (i) Conditions (2.1) and (2.5) are trivially satisfied for any pair of functions  $(u_1, u_2)$  if  $\lambda \leq 0$ .
- (ii) If  $\lambda > 0$  and q > 2, the one-sided Lipschitz condition (2.1) is satisfied for any pair and  $(u_1, u_2) \in L^1((0, T); L^{\infty}(\Omega))^2$  because

$$|f_{\lambda,q}(u_1(t,\cdot)) - f_{\lambda,q}(u_2(t,\cdot))| \le l(t)|u_1(t,\cdot) - u_2(t,\cdot)|$$

with 
$$l(t) := (q-1)\lambda \max\{\|u_1(t,\cdot)\|_{\infty}, \|u_2(t,\cdot)\|_{\infty}\}^{q-2}$$
.

(iii) Clearly, for q < 2 Condition (2.1) does not hold, and Theorem 2.9 does not apply. In general, the solutions of  $(P_{\sigma,f_{\lambda,q},u_0})$  are even not unique. Take e.g.  $\sigma = 0$  and  $q = \frac{3}{2}$ , then the continuum of nonnegative solutions of  $\dot{z} = \lambda z^{\frac{1}{2}}$  under z(0) = 0 furnishes also non unique solutions of  $(P_{0,f_{\lambda,3},0})$ .

# 3 An energy identity

In this section we show an energy estimate for solutions of Problem  $(P_{\sigma,f,u_0})$  for time independent nonlinearities:

$$\forall (t, x, u) \in \Omega_T \times \mathbb{R} : f(t, x, u) = f(x, u). \tag{3.1}$$

For any weak solution u of Problem  $(P_{\sigma,f,u_0})$  we introduce the energy  $E_F$  by

$$E_F(u(t,\cdot)) = \frac{1}{p} \|\nabla u(t,\cdot)\|_p^p - \int_{\Omega} F(x, u(t,x)) \, dx$$
 (3.2)

with

$$F(x,s) := \int_0^s f(x,z) \, dz.$$

The following *energy identity* for weak solutions of  $(P_{\sigma,f,u_0})$  will be shown as in the case  $f \equiv 0$ , where the classical theory of maximal monotone operators [Br, Theorem 3.2] has been applied.

**Theorem 3.1.** Let  $u: \overline{\Omega}_T \to \mathbb{R}$  be a weak solution of Problem  $(P_{\sigma,f,u_0})$  with  $u_0 \in \mathcal{X}^2$ . Assume that f satisfies (3.1) and that there exists a constant  $l \geq 0$  such that

$$[f(x, u(t, x)) - f(x, u(s, x)) - l(u(t, x) - u(s, x))] (u(t, x) - u(s, x)) \le 0$$
 (3.3)

for a.a.  $t, s \in (0, T]$  and for a.a.  $x \in \Omega$ . Then for a.a.  $t \in (0, T]$ , the time derivative of  $E_F(u(t, \cdot))$  exists and satisfies the identity

$$-\frac{d}{dt}E_F(u(t,\cdot)) = \|\partial_t u(t,\cdot)\|_2^2 + \sigma \|\partial_t u_{|_{\partial\Omega}}(t,\cdot)\|_{2,\partial\Omega}^2.$$
(3.4)

For simplicity we shall abbreviate

$$\langle \partial_t u(t,\cdot), \varphi \rangle_{\mathcal{X}^2} := \langle \partial_t u(t,\cdot), \varphi \rangle + \sigma \langle \partial_t u_{|\partial\Omega}(t,\cdot), \varphi \rangle_0,$$

for any  $\varphi \in W^{1,p}(\Omega)$ , and

$$\|\partial_t u\|_{\mathcal{X}^2}^2 := \|\partial_t u(t,\cdot)\|_2^2 + \sigma \|\partial_t u\|_{\partial\Omega}(t,\cdot)\|_{2,\partial\Omega}^2.$$

Note that we do not state here that  $\partial_t u_{|\partial\Omega}(t,\cdot)$  is the trace of  $\partial_t u(t,\cdot)$ , since this function is assumed only to belong to  $L^2(\Omega)$ !

*Proof.* Recall the following basic convexity inequality, valid for any p > 1 and any  $x, y \in \mathbb{R}^N$ :

$$p|x|^{p-2}x \cdot (y-x) \le |y|^p - |x|^p. \tag{3.5}$$

Fix  $t \in (0,T)$  and h > 0 small and choose  $\varphi = u(t+h,\cdot) - u(t,\cdot)$  in the weak formulation of  $(P_{\sigma,f,u_0})$  at time t. Then, using (3.5)

$$\langle \partial_t u(t,\cdot), u(t+h,\cdot) - u(t,\cdot) \rangle_{\mathcal{X}^2}$$

$$= -\langle |\nabla u(t,\cdot)|^{p-2} \nabla u(t,\cdot), \nabla u(t+h,\cdot) - \nabla u(t,\cdot) \rangle + \langle f(\cdot, u(t,\cdot)), u(t+h,\cdot) - u(t,\cdot) \rangle$$

$$\geq -\frac{1}{p} (\|\nabla u(t+h,\cdot)\|_p^p - \|\nabla u(t,\cdot)\|_p^p) + \langle f(\cdot, u(t,\cdot)), u(t+h,\cdot) - u(t,\cdot) \rangle. \quad (3.6)$$

Now take the test function  $\varphi$  again in the weak formulation of  $(P_{\sigma,f,u_0})$  at t+h and get

$$\langle \partial_{t} u(t+h,\cdot), u(t+h,\cdot) - u(t,\cdot) \rangle_{\mathcal{X}^{2}}$$

$$= -\langle |\nabla u(t+h,\cdot)|^{p-2} \nabla u(t+h,\cdot), \nabla u(t+h,\cdot) - \nabla u(t,\cdot) \rangle$$

$$+ \langle f(\cdot, u(t+h,\cdot)), u(t+h,\cdot) - u(t,\cdot) \rangle$$

$$\leq \frac{1}{p} (\|\nabla u(t,\cdot)\|_{p}^{p} - \|\nabla u(t+h,\cdot)\|_{p}^{p}) + \langle f(\cdot, u(t+h,\cdot)), u(t+h,\cdot) - u(t,\cdot) \rangle. \quad (3.7)$$

For s > 0, let us denote for the sake of simplicity

$$g(s) = \langle \partial_t u(t, \cdot), u(t+s, \cdot) - u(t, \cdot) \rangle_{\mathcal{X}^2},$$

$$e(s) = \frac{1}{p} (\|\nabla u(t+s, \cdot)\|_p^p - \|\nabla u(t, \cdot)\|_p^p),$$

$$k(s) = \langle f(\cdot, u(t, \cdot)), u(t+s, \cdot) - u(t, \cdot) \rangle,$$

$$d(s) = \langle \partial_t u(t+s,\cdot) - \partial_t u(t,\cdot), u(t+s,\cdot) - u(t,\cdot) \rangle_{\mathcal{X}^2} - \langle f(\cdot, u(t+s,\cdot)) - f(\cdot, u(t,\cdot)), u(t+s,\cdot) - u(t,\cdot) \rangle.$$

Combining (3.6) and (3.7) yields

$$-g(h) + k(h) \le e(h) \le -g(h) + k(h) - d(h). \tag{3.8}$$

The assertion of the proposition will follow from dividing (3.8) by h and passing to the limit as  $h \to 0$ . Let us study the existence of those limits. Inequality (3.8) implies in particular that  $d(h) \le 0$ , which in turn in combination with (3.3) leads to

$$\frac{1}{2}\frac{d}{dt}\left(\|u(t+h,\cdot)-u(t,\cdot)\|_{\mathcal{X}^2}^2\right) - l\|u(t+h,\cdot)-u(t,\cdot)\|_2^2 \le d(h) \le 0,$$

and, after integrating over any interval  $[s_1, s_2] \subset (0, T]$ ,

$$e^{-2ls_2} \|u(s_2+h,\cdot)-u(s_2,\cdot)\|_{\mathcal{X}^2}^2 - e^{-2ls_1} \|u(s_1+h,\cdot)-u(s_1,\cdot)\|_{\mathcal{X}^2}^2 \le 0.$$

Dividing by  $h^2$  and letting  $h \to 0$  we have then

$$e^{-2ls_2} \|\partial_t u(s_2, \cdot)\|_{\mathcal{X}^2}^2 - e^{-2ls_1} \|\partial_t u(s_1, \cdot)\|_{\mathcal{X}^2}^2 \le 0.$$
(3.9)

Thus, we can conclude that there exists a constant M>0 depending on u and t such that

$$\beta_n := \|\partial_t u(t + h_n, \cdot)\|_{\mathcal{X}^2}^2 \le M,$$

where  $(h_n)_{n\in\mathbb{N}}$  is any sequence of real numbers tending to 0. Since  $(\beta_n)_{n\in\mathbb{N}}$  is bounded, there exists some  $(\xi_1,\xi_2)\in\mathcal{X}^2$  such that, up to a subsequence,  $(\partial_t u(t+h_n,\cdot),\partial_t u_{|\partial\Omega}(t+h_n,\cdot)) \rightharpoonup (\xi_1,\xi_2)$  in  $\mathcal{X}^2$ . Hence, by (3.8) and by  $u\in C([0,T];\mathcal{X}^2)$ , g(s) and the r.h.s. of (3.8) are bounded, as well as  $(u(t+h_n,\cdot))_{n\in\mathbb{N}}$  in  $W^{1,p}(\Omega)$ . Therefore there exists some  $z\in W^{1,p}(\Omega)$  such that, up to a subsequence,  $u(t+h_n,\cdot) \rightharpoonup z$  in  $W^{1,p}(\Omega)$ , strongly in  $\mathcal{X}^2$  and simply a.e. in  $\Omega$ . By continuity of  $t\mapsto u(t,\cdot)$  in  $\mathcal{X}^2$  we must have  $z=u(t,\cdot)$ .

Finally, we conclude that  $(\xi_1, \xi_2) = (\partial_t u(t, \cdot), \partial_t u_{|\partial\Omega}(t, \cdot))$  by the following argument. In the weak formulation of  $(P_{\sigma,f,u_0})$  at time  $t+h_n$  we find, passing to the limit

$$\langle \xi_1, \varphi \rangle + \sigma \langle \xi_2, \varphi \rangle_0 = -\langle |\nabla u(t, \cdot)|^{p-2} \nabla u(t, \cdot), \nabla \varphi \rangle + \langle f(\cdot, u(t, \cdot)), \varphi \rangle = \langle \partial_t u(t, \cdot), \varphi \rangle_{\mathcal{X}^2}$$

for any  $\varphi \in W^{1,p}(\Omega)$ . The special choice of  $\varphi \in W^{1,p}_0(\Omega)$  implies that  $\xi_1 = \partial_t u(t,\cdot)$  and consequently  $\xi_2 = \partial_t u_{|\partial\Omega}(t,\cdot)$ . Hence,  $\lim_{h\to 0} \frac{g(h)}{h} = \|\partial_t u(t,\cdot)\|_{\mathcal{X}^2}^2$  and  $\lim_{h\to 0} \frac{k(h)}{h} = \langle f(\cdot,u(t,\cdot)),\partial_t u(t,\cdot)\rangle$ . This completes the proof.

**Remark 3.2.** One can readily see that the same arguments apply for the evolution equation under Dirichlet boundary conditions, i.e. for Problem (2.7) with f satisfying (3.3), obtaining similarly for a.a.  $t \in (0,T]$ 

$$-\frac{d}{dt}E_F(u(t,\cdot)) = \|\partial_t u(t,\cdot)\|_2^2.$$
 (3.10)

Now, let us consider the particular case  $f = f_{\lambda,p}$ , i.e.

$$\begin{cases} \partial_t u = \Delta_p u + \lambda |u|^{p-2} u & \text{in } \Omega \text{ for } t > 0, \\ \sigma \partial_t u + |\nabla u|^{p-2} \partial_\nu u = 0 & \text{on } \partial \Omega \text{ for } t > 0, \\ u(0, \cdot) = u_0 & \text{in } \overline{\Omega}. \end{cases}$$
(3.11)

Throughout we shall denote

$$E_{\lambda}(u) = \frac{1}{p} \int_{\Omega} (|\nabla u|^p - \lambda |u|^p) dx.$$
 (3.12)

We can use the energy identity to prove the following result on the Rayleigh quotient

$$\mathcal{E}_{\lambda}[u](t) := \frac{\int_{\Omega} (|\nabla u(t,\cdot)|^p - \lambda |u(t,\cdot)|^p) \, dx}{\|u\|_{\mathcal{X}^2}^p}.$$
(3.13)

Here, we followed [SV] where a similar result was proved under Dirichlet boundary conditions.

**Lemma 3.3.** Let  $\lambda \in \mathbb{R}$  and  $u \not\equiv 0$  be a solution of  $(P_{\sigma, f_{\lambda, p}, u_0})$  with  $u_0 \in \mathcal{X}^2$ . In the case  $\lambda > 0$  assume further that  $u \in L^{\infty}(\Omega_T)$ . Then

- (i) the function  $\mathcal{E}_{\lambda}[u](t)$  defined in (3.13) is non increasing with respect to  $t \in (0,T]$ ,
- (ii) and the mapping  $t \to ||u(t,\cdot)||_{\mathcal{V}^2}^{2-p}$  is concave if p > 2 and convex if p < 2.

**Remark 3.4.** Since  $\mathcal{E}_{\lambda}[u](t)$  is only defined a.e. in (0,T), one should understand the result of (i) as follows: "there is an integrable function g with g=0 a.e. such that  $\mathcal{E}_{\lambda}[u]+g$  is non increasing with respect to t".

*Proof.* (i) We apply the energy identity 3.4 to f. Note that Condition (3.3) is always satisfied for any function u if  $\lambda \leq 0$ , whereas for  $\lambda > 0$  it holds for  $u \in L^{\infty}(\Omega_T)$ .

On the one hand, multiplying the differential equation of  $(P_{\sigma,f_{\lambda,p},u_0})$  by u and integrating over  $\Omega$  yield

$$pE_{\lambda}(u(t,\cdot)) = -\int_{\Omega} u\partial_t u \, dx - \sigma \oint_{\partial\Omega} u\partial_t u_{|\partial\Omega} \, d\rho = -\frac{1}{2} \frac{d}{dt} \|u(t,\cdot)\|_{\mathcal{X}^2}^2$$
 (3.14)

and using Hölder's inequality in (3.14),

$$p^{2}E_{\lambda}(u(t,\cdot))^{2} \leq \|\partial_{t}u(t,\cdot)\|_{\mathcal{X}^{2}}^{2}\|u(t,\cdot)\|_{\mathcal{X}^{2}}^{2}.$$
(3.15)

On the other hand, by Theorem 3.1

$$\frac{d}{dt}E_{\lambda}(u(t,\cdot)) = -\|\partial_t u(t,\cdot)\|_{\mathcal{X}^2}^2 \le 0$$
(3.16)

a.e. in (0,T). Combining (3.15) et (3.16) we have

$$\frac{d}{dt}E_{\lambda}(u(t,\cdot)) \leq -p^{2} \frac{E_{\lambda}(u(t,\cdot))^{2}}{\|u(t,\cdot)\|_{\mathcal{X}^{2}}^{2}} = \frac{p}{2} E_{\lambda}(u(t,\cdot)) \frac{\frac{d}{dt} \|u(t,\cdot)\|_{\mathcal{X}^{2}}^{2}}{\|u(t,\cdot)\|_{\mathcal{X}^{2}}^{2}},$$

Hence, if  $E_{\lambda}(u) > 0$ ,

$$\frac{d}{dt} \left( \ln(E_{\lambda}(u(t,\cdot)) - \ln \|u(t,\cdot)\|_{\mathcal{X}^2}^p \right) \le 0$$

and  $t\mapsto \ln E_\lambda(u(t,\cdot))-\ln \|u(t,\cdot)\|_{\mathcal{X}^2}^p$  is a non increasing function of t>0 and the conclusion follows. If  $E_\lambda(u)<0$ ,  $t\mapsto \ln |E_\lambda(u(t,\cdot))|-\ln \|u(t,\cdot)\|_{\mathcal{X}^2}^p$  is a non decreasing function, which leads to the same conclusion. If  $E_\lambda(u(t,\cdot))=0$ , then, by (3.16),  $E_\lambda(u(s,\cdot))\leq 0$  for s>t and therefore,  $\mathcal{E}_\lambda[u](s)\leq 0=\mathcal{E}_\lambda[u](t)$ .

 $E_{\lambda}(u(s,\cdot)) \leq 0$  for s>t and therefore,  $\mathcal{E}_{\lambda}[u](s) \leq 0 = \mathcal{E}_{\lambda}[u](t)$ . (ii) Note that by (3.14),  $\mathcal{E}_{\lambda}[u] = -\frac{1}{2}\frac{dH}{dt}H^{-\frac{p}{2}}$ , where we have set  $H(t) = \|u(t,\cdot)\|_{\mathcal{X}^2}^2$  for simplicity. It readily follows that

$$\frac{d\mathcal{E}_{\lambda}[u]}{dt} \leq 0 \Leftrightarrow \left(\frac{dH}{dt}\right)^2 \leq \frac{2}{p}H\frac{d^2H}{dt^2} \Leftrightarrow \mathrm{sign}\left(1-\frac{p}{2}\right) \cdot \frac{d^2H^{1-\frac{p}{2}}}{dt^2} \geq 0,$$

which shows (ii).  $\Box$ 

## 4 Estimates of the $\chi^2$ -norm

In this section we present some estimates of the  $\mathcal{X}^2$ -norm of the solutions of Problem  $(P_{\sigma,f_{\lambda,q},u_0})$  for various cases of q and  $\lambda$ .

**Proposition 4.1.** Assume  $\lambda < 0$  and let u be a weak solution of Problem  $(P_{\sigma,f_{\lambda,p},u_0})$  with initial data  $u_0 \in \mathcal{X}^2$ .

(i) Assume p > 2. Then there exists a positive constant K depending only on  $p, \Omega, \lambda$ , and  $\sigma$  such that for all  $t \geq 0$ ,

$$||u(t,\cdot)||_{\mathcal{X}^2} \le (||u_0||_{\mathcal{X}^2}^{2-p} + K(p-2)t)^{\frac{1}{2-p}}.$$
 (4.1)

In particular,  $\lim_{t\to\infty} ||u(t,\cdot)||_{\mathcal{X}^2} = 0$ .

(ii) In the case p < 2, the estimate (4.1) holds for  $0 \le t \le T^* := \frac{\|u_0\|_{\mathcal{X}^2}^{2-p}}{K(2-p)}$  and  $\|u(t,\cdot)\|_{\mathcal{X}^2} = 0$  for all  $t \ge T^*$ .

*Proof.* Consider any  $t \ge 0$  in the maximal interval of existence containing 0. Multiplying the differential equation by u yields

$$\frac{1}{2n}\frac{d}{dt}\|u(t,\cdot)\|_{\mathcal{X}^2}^2 = -E_{\lambda}(u(t,\cdot)).$$

By Sobolev's classical embedding theorem there exists a constant K > 0 depending only on  $p, \Omega, \lambda$ , and  $\sigma$  such that for any  $u \in W^{1,p}(\Omega)$ ,

$$E_{\lambda}(u) \ge K \|u\|_{\mathcal{X}^2}^p.$$

Combining these two results leads to

$$\frac{d}{dt} \|u(t,\cdot)\|_{\mathcal{X}^2}^2 \le -K \|u(t,\cdot)\|_{\mathcal{X}^2}^p$$

and therefore,

$$\frac{1}{2-p}(\|u(t,\cdot)\|_{\mathcal{X}^2}^{2-p} - \|u_0\|_{\mathcal{X}^2}^{2-p}) \le -Kt. \tag{4.2}$$

For p > 2 it follows that the solution exists for all  $t \ge 0$  and

$$||u(t,\cdot)||_{\mathcal{X}^2}^{2-p} \ge -K(2-p)t + ||u_0||_{\mathcal{X}^2}^{2-p}$$

and

$$||u(t,\cdot)||_{\mathcal{X}^2}^2 \le \left(K(p-2)t + ||u_0||_{\mathcal{X}^2}^{2-p}\right)^{\frac{2}{2-p}}.$$
 (4.3)

In the case p < 2, the inequalities (4.2) and (4.3) hold only for  $0 \le t \le T^*$ . But, as the r.h.s. in (4.3) vanishes at  $T^*$ , we conclude that  $||u(t,\cdot)||_{\mathcal{X}^2} = 0$  for  $t = T^*$ , and, thereby,  $||u(t,\cdot)||_{\mathcal{X}^2} = 0$  for all  $t \ge T^*$ .

**Remark 4.2.** For Problem (2.7) with  $f_{\lambda,q} \equiv 0$ , DiBenedetto [Di, Chapter VII, Proposition 2.1] proved that positive solutions extinct in finite time, i.e. there exists  $T_* > 0$  such that  $u(t,\cdot) = 0$  for  $t \geq T_*$  for  $1 . Here we proved that the same result holds for the solutions of Problem <math>(P_{\sigma,f_{\lambda,v},u_0})$  if  $\lambda < 0$  and  $p_1 .$ 

Next, we give a point–wise one–sided estimate of the solution  $u(t,\cdot)$  in the case of a bounded initial data with definite sign:

**Proposition 4.3.** Suppose  $\lambda < 0$  and  $u_0 \in \mathcal{X}^{\infty} \cap W^{1,p}(\Omega)$ . Then the unique solution u of  $(P_{\sigma,f_{\lambda,p},u_0})$  is globally bounded. Moreover, if p > 2 and  $\sup_{\overline{\Omega}} u_0 < 0$ , then

$$u(t,x) \le \eta(t) := -\left(\left(-\sup_{\overline{\Omega}} u_0\right)^{2-p} + (2-p)\lambda t\right)^{\frac{1}{2-p}}.$$

Correspondingly, if p > 2 and  $\inf_{\overline{\Omega}} u_0 > 0$ , then

$$u(t,x) \ge \tilde{\eta}(t) = \left(\inf_{\overline{\Omega}} u_0^{2-p} + (2-p)\lambda t\right)^{\frac{1}{2-p}}$$

for all  $t \geq 0$  and a.e. in  $\Omega$ .

*Proof.* The boundedness follows straightforwardly from Remark 2.15 and Theorem 2.9 applied to u and the constant  $\pm \|u_0\|_{\mathcal{X}}^{\infty}$ . Now suppose that  $u_0 \leq 0$   $\tau-$  a.e. in  $\overline{\Omega}$ . As  $\lambda < 0$  and 2 < p,  $\eta(t) < 0$  for  $t \geq 0$ , and  $\eta$  clearly satisfies the ODE

$$\eta' = \lambda |\eta|^{p-2} \eta.$$

Moreover, observe that  $u_0(x) \leq \eta(0)$   $\tau$ -a.e. in  $\overline{\Omega}$ , and  $\sigma \eta'(t) \geq 0$  on  $\partial \Omega$ , since  $\sigma \geq 0$ . Then, again, Theorem 2.9 permits to conclude that  $u(t,\cdot) \leq \eta(t)$  a.e. in  $\Omega$ . Thus, we are led to

$$-\|u_0\|_{\mathcal{X}}^{\infty} = \inf_{\overline{\Omega}} u_0 \le u(t, x) \le \eta(t)$$

for all  $t \ge 0$  and a.e. in  $\Omega$ . The case  $u_0 \ge 0$  is shown similarly.

For 1 < q < 2 and  $\lambda \ge 0$  the  $\mathcal{X}^2$ -norm of a solution remains bounded on bounded time intervals. This is part of the following result bearing in mind that for the present case, the solutions of  $(P_{\sigma,f_{\lambda,q},u_0})$  are not unique in general, see Remark 2.15 (iii).

**Proposition 4.4.** Suppose  $1 < q \le 2$  and  $\lambda \ge 0$ . Let  $u_0 \in \mathcal{X}^2$  be given. Then for any weak solution of Problem  $(P_{\sigma,f_{\lambda,q},u_0})$ , the following estimate holds for all  $t \in [0,T]$ :

$$||u(t,\cdot)||_{\mathcal{X}^2} \le \begin{cases} ||u_0||_{\mathcal{X}^2} e^{\lambda t} & \text{for } q = 2, \\ \left(||u_0||_{\mathcal{X}^2}^{2-q} + (2-q)\lambda |\Omega|^{\frac{2-q}{2}} t\right)^{\frac{1}{2-q}} & \text{for } 1 < q < 2. \end{cases}$$
(4.4)

*Proof.* Set  $H(t) = ||u(t, \cdot)||_{\mathcal{X}^2}^2$ . Multiplying the differential equation by u yields

$$\frac{dH}{dt} = -2 \int_{\Omega} |\nabla u|^p \, dx + 2\lambda \int_{\Omega} |u|^q \, dx.$$

In the case q=2, it follows readily that  $\frac{dH}{dt} \leq 2\lambda H$ . In the case 1 < q < 2, the inequality

$$\frac{dH}{dt} \le 2\lambda |\Omega|^{\frac{2-q}{2}} \left( \int_{\Omega} u^2 dt \right)^{\frac{q}{2}} \le 2\lambda |\Omega|^{\frac{2-q}{2}} H^{\frac{q}{2}}$$

leads to the desired estimate.

#### 5 Behaviour at infinity

In this section we investigate the behaviour and growth order estimates at infinity of solutions of  $(P_{\sigma,f_{\lambda,p},u_0})$  in the case  $\lambda \leq 0$ . The uniqueness of solutions of Problem  $(P_{\sigma,f_{\lambda,p},u_0})$  stems from Theorem 2.9 and Remark 2.15. Our aim is to prove first some behaviour at infinity in the spaces  $\mathcal{X}^2$  and  $W^{1,p}(\Omega)$ , c.f. Proposition 5.2. Secondly we shall give a more precise rate of convergence at  $\infty$  of the  $\mathcal{X}^{\infty}$  norms, c.f. Proposition 5.3. Finally, we give more precise informations about the behaviour of the solution of Problem (3.11) as  $t \to \infty$ .

**Theorem 5.1.** Let  $\lambda < 0$  and p > 2 and let u be a solution of Problem  $(P_{\sigma,f_{\lambda,p},u_0})$  with initial data  $u_0 \in \mathcal{X}^2$ . Then there exists a sequence  $(t_n)_{n \in \mathbb{N}}$  in  $\mathbb{R}^+$  tending to  $\infty$  and a solution  $w \in W^{1,p}(\Omega)$  of the elliptic problem with Robin–Steklov boundary condition

$$\begin{cases}
-\Delta_p w - \lambda |w|^{p-2} w = w & \text{in } \Omega, \\
|\nabla w|^{p-2} \partial_\nu w = \sigma w & \text{on } \partial\Omega,
\end{cases}$$
(5.1)

such that

$$\lim_{n \to \infty} \|(1 + (p-2)t_n)^{\frac{2}{p-2}} u(t_n, \cdot) - w\|_{\mathcal{X}^2} = 0.$$

*Proof.* We can follow the proof of [BH]. Set  $z(t,x)=(1+(p-2)t)^{\frac{1}{p-2}}u(t,x)$  for  $t\geq 0, x\in \overline{\Omega}$ . A simple calculation shows that z solves

$$\begin{cases}
(1+(p-2)t)\partial_t z = z + \Delta_p z + \lambda |z|^{p-2}z & \text{in } \Omega \text{ for } t > 0, \\
\sigma(1+(p-2)t)\partial_t z = -|\nabla z|^{p-2}\partial_\nu z + \sigma z & \text{on } \partial\Omega \text{ for } t > 0, \\
z(0,\cdot) = u_0 & \text{in } \overline{\Omega},
\end{cases}$$
(5.2)

Consider the energy functional J associated to (5.2)

$$J(v) = \frac{1}{p} \int_{\Omega} (|\nabla v|^p - \lambda |v|^p) \, dx - \frac{1}{2} \left( \int_{\Omega} |v|^2 \, dx + \sigma \oint_{\partial \Omega} |v|^2 \, d\rho \right)$$

By Proposition 4.1,  $||z(t,\cdot)||_{\mathcal{X}^2}$  is uniformly bounded for t>0 and thereby, using Lemma 3.3,  $||z(t,\cdot)||_{W^{1,p}}$  is uniformly bounded for  $t\geq t_0>0$  for any  $t_0$  as well. A similar reasoning as in the proof of Lemma 3.3, shows that

$$\frac{d}{dt}J(z(t,\cdot)) = -(1 + (p-2)t)\|\partial_t z(t,\cdot)\|_{\mathcal{X}^2}^2 < 0$$

for a.a. t > 0. Thus,  $t \mapsto J(z(t, \cdot))$  is bounded from below and decreasing, and therefore there exists a sequence  $(t_n)_{n \in \mathbb{N}}$  with  $t_n \to \infty$  such that

$$\lim_{n \to \infty} \frac{d}{dt} J(z(t_n, \cdot)) = 0.$$

Set  $w_n=z(t_n,\cdot)$ . By Lemma 3.3 the sequence  $(\|w_n\|_{W^{1,p}})_{n\in\mathbb{N}}$  is bounded as well, thus there exists a subsequence still denoted by  $(w_n)_{n\in\mathbb{N}}$ , and a function  $w\in W^{1,p}(\Omega)$  such that  $w_n\rightharpoonup w$  weakly in  $W^{1,p}(\Omega)$ , strongly in  $\mathcal{X}^2$  and simply  $\tau-$  a.e. in  $\overline{\Omega}$ . Then the l.h.s. of the equations in (5.2) tend weakly to 0 in  $\mathcal{X}^2$  as  $n\to\infty$ , while the r.h.s. tend weakly in  $W^{1,p}(\Omega)$  to  $\Delta_p w+\lambda |w|^{p-2}w+w$  in  $\Omega$  and to  $-|\nabla w|^{p-2}\partial_\nu w+\sigma w$  on  $\partial\Omega$ .

In the case  $\lambda=0$  an asymptotic result holds that is analogous to Proposition 4.1 and Theorem 5.1. Note that the asymptotic constant  $c_0$  defined in (5.3) is exactly the same one as for the classical Laplacian, i.e. p=2, see [BBR].

**Theorem 5.2.** Assume  $\lambda = 0$  and let  $u_0 \in \mathcal{X}^2$  be given. Let u be the weak solution of the Cauchy problem  $(P_{\sigma,0,u_0})$  with initial data  $u_0$ . Then

$$\lim_{t \to \infty} u(t, \cdot) = c_0 \quad \text{in } W^{1,p}(\Omega)$$

with

$$c_0 := \frac{\int_{\Omega} u_0 \, dx + \sigma \oint_{\partial \Omega} u_0 \, d\rho}{|\Omega| + \sigma |\partial \Omega|}.$$
 (5.3)

Moreover, for p < 2 there exists  $t_* \ge 0$  such that  $u(t,x) = c_0$  for all  $(t,x) \in [t_*, \infty[ \times \overline{\Omega}.$  Furthermore

$$t_* = \frac{\|u_0 - c_0\|_{\mathcal{X}^2}^{2-p}}{K(2-p)} > 0$$
 (5.4)

with some constant K > 0 depending only on  $N, p, \sigma$  and  $\Omega$ .

*Proof.* Integrating the differential equation leads to

$$0 = \int_{\Omega} \partial_t u \, dx - \oint_{\partial \Omega} |\nabla u|^{p-2} \partial_{\nu} u \, d\rho = \int_{\Omega} \partial_t u \, dx + \sigma \oint_{\partial \Omega} \partial_t u \, d\rho;$$

that is  $\frac{d}{dt} \left( \int_{\Omega} u \, dx + \sigma \oint_{\partial \Omega} u \, d\rho \right) = 0$  for any  $t \geq 0$ . Writing  $\alpha := |\Omega| + \sigma |\partial \Omega|$ , we have

$$\int_{\Omega} u \, dx + \sigma \oint_{\partial \Omega} u \, d\rho = \int_{\Omega} u_0 \, dx + \sigma \oint_{\partial \Omega} u_0 \, d\rho = c_0 \alpha.$$

Again, integrating the differential equation multiplied by u leads to

$$E(u(t,\cdot)) = -\frac{1}{2p} \frac{d}{dt} ||u(t,\cdot)||_{\mathcal{X}^2}^2, \tag{5.5}$$

where  $E(u) := E_0(u) = \frac{1}{p} \int_{\Omega} |\nabla u|^p dx$ . Set  $v = u - c_0$  and  $v_0 = u_0 - c_0$  and observe that  $\int_{\Omega} v_0 dx + \sigma \oint_{\partial \Omega} v_0 d\rho = 0$  and that v is a weak solution of Problem  $(P_{\sigma,0,u_0})$  for the

initial data  $v_0$ . Since  $v \mapsto \|\nabla v\|_p$  defines an equivalent norm to the usual  $W^{1,p}(\Omega)$ -norm on the subspace  $H_0$  defined by

$$H_0 = \left\{ v \in W^{1,p}(\Omega) \mid \int_{\Omega} v \, dx + \sigma \oint_{\partial \Omega} v \, d\rho = 0 \right\}, \tag{5.6}$$

we infer from Sobolev's embedding  $W^{1,p}(\Omega) \hookrightarrow \mathcal{X}^2$  that

$$E(v) \ge K \|v\|_{\mathcal{X}^2}^p$$

with some constant  $0 < K = K(p,N,\sigma,\Omega)$ . Then we proceed as in the proof of Proposition 4.1 in order to get the bound (4.1) for the function v. Thus,  $\|v\|_{\mathcal{X}^2} = 0$  for all  $t \geq t_* := \frac{\|v_0\|_{\mathcal{X}^2}^{2-p}}{K(2-p)}$  if 2 < p. If p > 2, then  $\lim_{t \to \infty} \|v(t,\cdot)\|_{\mathcal{X}^2} = 0$ . Finally, Lemma 3.3 implies that the Rayleigh quotient  $\mathcal{E}_0[v](t) := \frac{\int_{\Omega}(|\nabla v(t,\cdot)|^p}{\|v\|_{\mathcal{X}^2}^p}$  is non increasing with respect to t for t > 0, that is

$$\|\nabla v(t,\cdot)\|_p \le \frac{\|\nabla v(t_0,\cdot)\|_p}{\|v(t_0,\cdot)\|_{\mathcal{X}^2}} \|v(t,\cdot)\|_{\mathcal{X}^2} \quad \text{for } t > t_0 > 0.$$

Then if  $p \neq 2$ ,  $\lim_{t \to \infty} \|\nabla v(t,\cdot)\|_p = 0$  and  $\lim_{t \to \infty} \|v(t,\cdot)\|_{W^{1,p}(\Omega)} = 0$  since  $v \in H_0$ , which permits to conclude that  $u(t,\cdot) \to c_0$  in  $W^{1,p}(\Omega)$  as  $t \to \infty$ .

Next, we want to establish the  $L^{\infty}$ -convergence for the previous limit result  $c_0 = \lim_{t \to \infty} u(t,\cdot)$ . The problem of the global boundedness of positive weak solutions for the parabolic equation in  $(P_{\sigma,f_{\lambda,p},u_0})$  with Dirichlet or Neumann boundary conditions and bounded initial data has been completely treated e.g. in [Di, Chapter V]. Later F. Cipriani and G. Grillo [CG] gave the so called "ultraconductivity bounds" of the solutions of the parabolic equation of  $(P_{\sigma,f_{\lambda,p},u_0})$  in the case  $2 under Dirichlet boundary conditions and initial data <math>u_0 \in L^q(\Omega)$  with q sufficiently large. In the case  $\lambda = 0$  under dynamical boundary conditions such results seem to be unavailable yet in the literature. Therefore we present the following one here.

**Theorem 5.3.** Let us assume  $\lambda = 0$  and  $u_0 \in W^{1,p}(\Omega)$ . Let u be a solution of  $(P_{\sigma,0,u_0})$  with initial data  $u_0$  and let  $c_0$  be defined as in (5.3). Then the following estimates hold.

(i) If p < N and  $u_0 \in \mathcal{X}^{p_*}$ , then there exists  $0 < d = d(p_*, \Omega, \sigma)$  such that, for all t > 0,

$$||u(t,\cdot) - c_0||_{\mathcal{X}^{\infty}} \le d t^{-\frac{1}{p_* - 2}} ||u_0 - c_0||_{\mathcal{X}^{p_*}}^{\frac{p_* - p}{p_* - 2}}.$$
 (5.7)

(ii) If  $p \ge N$  and  $u_0 \in \mathcal{X}^q$  then for some  $q > \max\{p, 2\}$ , there exists  $0 < d = d(q, \Omega, \sigma)$  such that, for all t > 0,

$$||u(t,\cdot) - c_0||_{\mathcal{X}^{\infty}} \le dt^{-\frac{1}{q-2}} ||u_0 - c_0||_{\mathcal{X}^q}^{\frac{q-p}{q-2}}.$$
 (5.8)

In particular

$$\lim_{t \to \infty} \|u(t, \cdot) - c_0\|_{\mathcal{X}^{\infty}} = 0.$$

*Proof.* We shall give only the proof in the case (i), as the proof of case (ii) is the same provided  $p^*$  is replaced by q. Let us assume first that  $u_0 \in \mathcal{X}^{\infty} \cap W^{1,p}(\Omega)$ , we shall get rid of this assumption at the end of the proof. As in the proof of Proposition 5.2, we shall use  $v = u - c_0$  and  $v_0 = u_0 - c_0$ . Since  $v_0 \in \mathcal{X}^{\infty}$ , Theorem 2.9 gives readily the estimates

$$||v||_{\infty,\mathbb{R}^+\times\Omega} \le ||v_0||_{\infty,\Omega}, \quad ||v||_{\infty,\mathbb{R}^+\times\partial\Omega} \le ||v_0||_{\infty,\partial\Omega},$$

in particular for all  $t \geq 0$ ,  $v(t,\cdot) \in \mathcal{X}^{\infty}$ . We can consider for any  $m \geq 2$  the test function  $\varphi = |v|^{m-2}v$ , yielding

$$\frac{d}{dt}\|v(t,\cdot)\|_{\mathcal{X}^m}^m = -m(m-1)\left(\frac{p}{p+m-2}\right)^p \int_{\Omega} \left|\nabla|v(t,\cdot)|^{\frac{m-2+p}{p}}\right|^p dx. \tag{5.9}$$

Note that for any  $m \geq 2$ ,  $|v|^{\frac{m-2}{p}}v \in H$ , where H is defined in Lemma 5.4 below. Hence, by combining (5.4) and trace embeddings we infer the existence of a constant C depending only on  $p_*$ ,  $\Omega$ , and  $\sigma$  such that

$$\int_{\Omega} \left| \nabla |v(t,\cdot)|^{\frac{m-2+p}{p}} \right|^p dx \ge C \left\| |v(t,\cdot)|^{\frac{m-2+p}{p}} \right\|_{\mathcal{X}^{p_*}}^p.$$

Then it follows from (5.9) that

$$\frac{d}{dt} \|v(t,\cdot)\|_{\mathcal{X}^m}^m \le -Cm(m-1) \left(\frac{p}{p+m-2}\right)^p \|v(t,\cdot)\|_{\mathcal{X}^{\frac{p*}{p}(p+m-2)}}^{p+m-2}.$$

Set  $r_0 = \frac{p_*}{p}$ ,  $m_0 = p_*$  and for  $k \in \mathbb{N}^*$ 

$$m_k = r_0(p + m_{k-1} - 2) = r_0^{k+1} \frac{p_* - 2}{r_0 - 1} - \frac{r_0(p - 2)}{r_0 - 1}.$$

Now the previous inequality for  $m = m_k$  reads

$$\frac{d}{dt} \|v(t,\cdot)\|_{\mathcal{X}^{m_k}}^{m_k} \le -C\theta_k \|v(t,\cdot)\|_{\mathcal{X}^{m_{k+1}}}^{\frac{m_{k+1}}{r_0}},\tag{5.10}$$

where  $\theta_k := m_k(m_k - 1) \left(\frac{p}{p + m_k - 2}\right)^p$ . Denote for simplicity  $Y_k = \|v\|_{\mathcal{X}^{m_k}}^{m_k}$  and fix t > 0 and  $k \in \mathbb{N}^*$ . Define, for  $0 \le j \le k$ ,

$$s_0 = t$$
,  $s_j - s_{j+1} = \frac{\mu}{\theta_{k-j} r_0^{(p-1)(k-j)}}$ 

for some  $\mu > 0$  to be chosen later. By integrating (5.10) between  $s_1$  and  $s_0$  we have, using that  $t \mapsto Y_j(t)$  is a positive decreasing function,

$$Y_k(s_0) - Y_k(s_1) \le -C\theta_k(s_0 - s_1)Y_{k+1}^{\frac{1}{r_0}}(t)$$

and

$$Y_{k+1}(t) \le \left[C\mu r_0^{-(p-1)k}\right]^{-r_0} Y_k(s_1)^{r_0}. \tag{5.11}$$

Iterating k + 1 times leads to

$$Y_{k+1}(t) \le \alpha_k \beta_k Y_0(s_{k+1})^{r_0^{k+1}}$$

with

$$\alpha_k := (\mu C)^{-\sum_{j=0}^k r_0^{j+1}} = (\mu C)^{\frac{r_0}{r_0 - 1}(1 - r_0^{k+1})},$$

$$\beta_k := \prod_{j=0}^k r_0^{(p-1)(k-j)r_0^{j+1}} = r_0^{(p-1)[-k\frac{r_0}{r_0 - 1} + \frac{r_0^2}{(r_0 - 1)^2}(r_0^k - 1)]}.$$

Thus,

$$Y_{k+1}^{\frac{1}{m_{k+1}}}(t) \le \alpha_k^{\frac{1}{m_{k+1}}} \beta_k^{\frac{1}{m_{k+1}}} Y_0(s_{k+1})^{\frac{r_0^{k+1}}{m_{k+1}}}.$$
(5.12)

Now choose  $\mu$  in such a way that  $\lim_{k\to\infty} s_k = 0$ , i.e.  $\mu = \frac{t}{\sum_{j=0}^\infty r_0^{j(1-p)}\theta_j^{-1}}$ . Note that the series in the denominator converges, since  $\theta_j$  scales with  $(m_j)^{2-p}$  and  $r_0^{(2-p)j}$ . Moreover, a simple calculation gives  $\lim_{k\to\infty} \frac{r_0^{k+1}}{m_{k+1}} = \frac{(r_0-1)}{(p_*-2)r_0}$ ,  $\lim_{k\to\infty} \alpha_k^{\frac{1}{m_{k+1}}} = (\mu C)^{-\frac{1}{p_*-2}}$ ,

 $\lim_{k\to\infty} \beta_k^{\frac{1}{m_{k+1}}} = r_0^{\frac{p-1}{(p_*-2)(r_0-1)}}$ . Now, the estimate (5.7) follows by passing to the limit in (5.12). Note that the convergence of  $Y_0(s_{k+1}) = \|v(s_{k+1},\cdot)\|_{p_*}^{p_*}$  to  $Y_0(0) = \|v_0\|_{p_*}^{p_*}$  follows from the fact that  $v\in C([0,T];L^2(\Omega))$  by Definition 2.1 and by the boundedness of v.

Finally assume that  $u_0 \in \mathcal{X}^{p_*}$  and take a sequence  $(u_n^0)_{n \in \mathbb{N}}$  in  $\mathcal{X}^{\infty} \cap W^{1,p}(\Omega)$  converging to  $u_0$  in  $\mathcal{X}^{p_*}$ . In particular  $c_n^0 := c_0 \, (u_n^0) \to c_0$ . Let  $u_n$  be the unique solution of  $(P_{\sigma,f_{\lambda,p},u_0})$  for  $\lambda=0$  and initial data  $u_n^0$ . Thus, (5.7) holds for each  $u_n$ . By Corollary 2.8, for any  $t \in \mathbb{R}$ ,  $u_n(t,\cdot) \to u(t,\cdot)$  in  $\mathcal{X}^2$  and therefore, for a.a.  $x \in \Omega$ ,  $u_n(t,x) \to u(t,x)$ , which permits to conclude.

#### **Lemma 5.4.** Let $0 < q < p_*$ be fixed and set

$$H := \left\{ u \in W^{1,p}(\Omega) \ \middle| \ \exists s \in (0,q] : \int_{\Omega} |u|^{s-1} u \, dx + \sigma \oint_{\partial \Omega} |u|^{s-1} u \, d\rho = 0 \right\}.$$

Then there exists a constant C = C(q) > 0 such that for all  $u \in H$ ,

$$\int_{\Omega} |\nabla u|^p \, dx \ge C \int_{\Omega} |u|^p \, dx.$$

*Proof.* Assume by contradiction that there exists a sequence  $(u_n)_{n\in\mathbb{N}}$  in  $W^{1,p}(\Omega)$  and a sequence  $(s_n)_{n\in\mathbb{N}}$  in (0,q] such that

$$\int_{\Omega} |u_n|^{s_n - 1} u_n \, dx + \sigma \oint_{\partial \Omega} |u_n|^{s_n - 1} u_n \, d\rho = 0, \tag{5.13}$$

 $\int_{\Omega} |u_n|^p dx = 1$  and  $\int_{\Omega} |\nabla u_n|^p dx \leq \frac{1}{n}$ . Choose a subsequence of  $(s_n)_{n \in \mathbb{N}}$  denoted again by  $(s_n)_{n \in \mathbb{N}}$ , that is converging to some  $s_0 \in [0,q]$ . As the sequence  $(u_n)_{n \in \mathbb{N}}$  is bounded in  $W^{1,p}(\Omega)$ , there exists a subsequence of  $(u_n)_{n \in \mathbb{N}}$ , still denoted by  $(u_n)_{n \in \mathbb{N}}$ , converging

weakly to some  $v_0 \in W^{1,p}(\Omega)$ , strongly in  $L^p(\Omega) \cap \mathcal{X}^{s_0}$  and simply a.e. in  $\Omega$ . Then  $v_0$  has to be constant, say c since

$$\int_{\Omega} |\nabla v_0|^p \, dx \le \lim_{n \to \infty} \int_{\Omega} |\nabla u_n|^p \, dx = 0.$$

But  $v_0 = c \neq 0$  a.e. in  $\Omega$  by the strong convergence in  $L^p(\Omega)$ . On the other hand, by letting n tend to  $\infty$  in (5.13) and by the strong convergence in  $\mathcal{X}^{s_0}$ , we are led to the contradiction

$$0 = \int_{\Omega} |c|^{s_0 - 1} c \, dx + \sigma \oint_{\partial \Omega} |c|^{s_0 - 1} c \, d\rho.$$

**Remark 5.1.** The existence of a solution of  $(P_{\sigma,f_{\lambda,p},u_0})$  in the case  $\lambda \leq 0$  in the sense of distributions has been proved for instance in [Sw, p. 141] and in [Ls] in the case  $\lambda = 0$ , that is readily extended to the case  $\lambda < 0$ . Note that our notion of a weak solution in Definition 2.1 requires more regularity, since we impose  $\partial_t u(t,\cdot) \in L^2(\Omega)$  and  $\partial_t u_{|\partial\Omega}(t,\cdot) \in L^2(\partial\Omega,\rho)$  for a.a.  $t \in [0,T)$ . This higher regularity is not a restriction since distributional solutions of  $(P_{\sigma,f_{\lambda,p},u_0})$  with initial data  $u_0 \in W^{1,p}(\Omega)$  bear this property, see e.g. [Sw, p.124] or [Br, Theorem 3.1]). Furthermore, following [Br, Theorem 3.2],  $\partial_t u \in L^\infty(\mathbb{R}^+,\mathcal{X}^2)$ .

Closing this section we present the occurrence of global solution existence in the presence of a hyperbolic equilibrium for a reaction term  $f \in \mathcal{C}^1(\mathbb{R})$ . Thus, the Cauchy problem in question reads

$$\begin{cases}
\partial_t u = \Delta_p u + f(u) & \text{in } \Omega \text{ for } t > 0, \\
\sigma \partial_t u + |\nabla u|^{p-2} \partial_\nu u = 0 & \text{on } \partial\Omega \text{ for } t > 0, \\
u(0, \cdot) = u_0 \in \mathcal{C}(\overline{\Omega}).
\end{cases} (5.14)$$

We suppose that

(5.14) defines a local flow in 
$$\mathcal{X}^{\infty} \cap W^{1,p}(\Omega)$$
 (5.15)

and that there are real numbers  $-\infty < A < B < C < \infty$  such that

$$f(A) = f(B) = f(C) = 0, \quad f'(B) < 0, \quad f > 0 \text{ in } (A, B), \quad f < 0 \text{ in } (B, C).$$

$$(5.16)$$

Introduce  $F(s) = \int_A^s f(\eta) d\eta$ , and recall that the energy functional  $E_F: W^{1,p}(\Omega) \to \mathbb{R}$  is defined formally by  $E_F(u) = \frac{1}{p} \int_{\Omega} |\nabla u|^p dx - \int_{\Omega} F(u) dx$ . Now we can state the following.

**Theorem 5.5.** Under the conditions (5.15), (5.16), and  $u_0 \in \mathcal{X}^{\infty} \cap W^{1,p}(\Omega)$ , any weak solution of Problem (5.14) with initial condition fulfilling  $A \leq u_0 \leq C \tau$ -a.e. in  $\overline{\Omega}$  exists globally in  $[0,\infty)$  and satisfies  $A \leq u \leq C \tau$ -a.e. in  $\overline{\Omega}$  for all  $t \geq 0$ . Moreover, the equilibrium B is stable in the class of functions from  $W^{1,p}(\Omega)$  taking their values in [A,C]  $\tau$ -a.e. in  $\overline{\Omega}$ .

*Proof.* If  $u_0$  takes its values in [A,B] or [B,C]  $\tau$ -a.e. in  $\overline{\Omega}$ , then Theorem 2.9 for the given  $\sigma$  permits to conclude that  $A \leq u(t,\cdot) \leq B$  or  $B \leq u(t,\cdot) \leq C$  respectively  $\tau$ -a.e. in  $\overline{\Omega}$  for all  $t \geq 0$ . For an initial condition  $u_0$  satisfying  $A \leq u_0 \leq C$   $\tau$ -a.e. in  $\overline{\Omega}$  Theorem 2.9 again applies to the solutions  $u_0$ ,  $u_0$ , and  $\overline{u}$  with respective initial data

$$\underline{u}_0 := \min \{u_0, B\} \le u_0 \le \max \{u_0, B\} =: \overline{u}_0$$

and yields

$$\forall t \geq 0: A \leq \underline{u}(t, \cdot) \leq u(t, \cdot) \leq \overline{u}(t, \cdot) \leq C \quad \tau$$
-a.e. in  $\overline{\Omega}$ .

As for the last assertion, note that  $E_F(u)$  defines a generalized Lyapunov function for the equilibrium B in the class of functions from  $W^{1,p}(\Omega)$  taking their values in [A,C]  $\tau$ -a.e. As above, the orbital derivative along solutions of (5.14) is nonpositive, since

$$\frac{d}{dt}E_F(u(t,\cdot)) = -\int_{\Omega} (\partial_t u(t,\cdot))^2 dx - \sigma \oint_{\partial\Omega} (\partial_t u_{|\partial\Omega}(t,\cdot))^2 ds \le 0.$$

Moreover, for functions belonging to the mentioned class the potential energy term is bounded from below by  $-|\Omega|F(B)$ . Thus, the equilibrium B is stable, see e.g. [A, Section 18].

We note in passing that by Lasalle's Principle [A, Section 18], the trajectories of the flow belonging to (5.14) have their  $\omega$ -limits in the set of functions satisfying  $\frac{d}{dt}E_F(u)=0$ . This yields another global existence proof. Moreover, attractivity properties of the equilibrium B might be obtained by using similar arguments as in [Be, Theorem 17.31]. We omit the details here and mention only the following result under the Neumann boundary condition.

**Corollary 5.6.** Under the hypotheses of Theorem 5.5 in the case  $\sigma = 0$ , any weak solution of

$$\begin{cases}
\partial_t u = \Delta_p u + f(u) & \text{in } \Omega \text{ for } t > 0, \\
\partial_\nu u = 0 & \text{on } \partial\Omega \text{ for } t > 0, \\
u(0, \cdot) = u_0 \in \mathcal{C}(\overline{\Omega}) \setminus \{A, C\},
\end{cases} (5.17)$$

satisfies

$$\lim_{t \to \infty} \|u(t, \cdot) - B\|_{\mathcal{X}^{\infty}} = 0.$$

*Proof.* Recall  $c_0 := \frac{\int_{\Omega} u_0 \; dx + \sigma \oint_{\partial\Omega} u_0 \; d\rho}{|\Omega| + \sigma |\partial\Omega|}$  and get by assumption that  $A < c_0 < C$ . Using the notations of Theorem 5.5, by Theorems 5.3 and 2.9 there exists  $t_c \ge 0$  such that

$$\forall t \geq t_c: \ \frac{A+c_0}{2} \leq \underline{v}(t,\cdot) \leq \underline{u}(t,\cdot) \leq \overline{u}(t,\cdot) \leq \overline{u}(t,\cdot) \leq \overline{v}(t,\cdot) \leq \frac{C+c_0}{2} \quad \text{$\tau$-a.e. in $\overline{\Omega}$},$$

where  $\underline{v}$  and  $\overline{v}$  denote the solutions for f=0 with initial conditions  $\underline{u}_0$  and  $\overline{u}_0$ , respectively. But the solutions  $z_1$  and  $z_2$  of

$$\begin{cases} \dot{z}_1 = f(z_1) & \text{for } t \ge t_c, \\ z_1(t_c) = \frac{A+c_0}{2}, \end{cases} \quad \text{for } t \ge t_c, \quad \begin{cases} \dot{z}_2 = f(z_2) \\ z_2(t_c) = \frac{C+c_0}{2}, \end{cases}$$

tend both uniformly to B, while  $z_1(t) \leq u(t,\cdot) \leq z_2(t)$   $\tau$ -a.e. in  $\overline{\Omega}$  for all  $t \geq t_c$  by Theorem 2.9.

### 6 Blow up phenomena

This section is devoted to the occurrence of blow up for the solutions of Problem  $(P_{\sigma,f,u_0})$ . We note in passing, that among others, the recent rather general blow up results by Vulkov [Vul] complement nicely the ones presented here, but do not include the latter ones. First, we consider a rather general case of nonnegative source terms f(t,x,u) of the form (6.1). Then we shall study a source term with a sign change of the form  $f=f_{\lambda,q}$ , with  $q\geq p$  and  $\lambda>0$ . For the first case, assume that f is of the form

$$f(t,x,u) = m(t,x)g(u), \tag{6.1}$$

where g and m satisfy

$$g \in \mathcal{C}^1(\mathbb{R}), \ g(s) > 0 \text{ for all } s > 0,$$
 (6.2)

$$g(s) \ge 0 \text{ for all } s \in \mathbb{R}, g'(s) \ge 0 \text{ for all } s > 0$$
 (6.3)

$$\int_{s_0}^{\infty} \frac{d\eta}{g(\eta)} < \infty \text{ for some } s_0 > 0, \tag{6.4}$$

$$m \in L^1_{loc}(\mathbb{R}^+; L^1(\Omega)), \ m \ge 0,$$
 (6.5)

and

$$\int_0^\tau \left( \int_\Omega m(t,x) \, dx \right) \, dt \to \infty \text{ as } \tau \to \infty$$
 (6.6)

We follow a technique developed in [BBR] to exclude the existence of global weak solution of Problem  $(P_{\sigma,f,u_0})$  for positive sources in the case p=2. Unlike in that reference, it is impossible to establish an expansion formula for the solution of the homogeneous linear problem corresponding to  $(P_{\sigma,f,u_0})$  for  $p \neq 2$ . However, as a consequence of the asymptotic result Theorem 5.3 obtained for the homogeneous Problem  $(P_{\sigma,0,u_0})$ , u is bounded from below after a certain finite time. A main result of this section is the following.

**Theorem 6.1.** Assume (6.1)-(6.6) and let  $u_0 \in \mathcal{X}^{p_*}$  if p < N or  $u_0 \in \mathcal{X}^q$  for some q > p if  $p \ge N$ . Assume that  $u_0$  fulfills

$$\int_{\Omega} u_0 \, dx + \sigma \oint_{\partial \Omega} u_0 \, d\rho > 0. \tag{6.7}$$

Then there is no weak solution u of  $(P_{\sigma,f,u_0})$  existing for all times.

*Proof.* Suppose that u is a global weak solution of  $(P_{\sigma,f,u_0})$ . First, we claim that there exists  $t_0>0$  such that  $u(t,\cdot)\geq \frac{c_0}{2}$  a.e. in  $\Omega$  and for  $t\geq t_0$ , with  $c_0$  defined in (5.3). Let v be the unique solution of the homogeneous problem  $(P_{\sigma,0,u_0})$  with initial data  $u_0$ . Theorem 5.3 implies that there exists a  $t_0\geq 0$  such that for all  $t\geq t_0, \frac{c_0}{2}\leq v(t,\cdot)$  a.e. in  $\Omega$ . As v is a solution of  $(P_{\sigma,0,u_0})$  for  $t\geq t_0$ , Corollary 2.6 applies to  $f_1:=0\leq m(t,x)g(u)=:f_2$  by (6.3) and yields  $u(t,\cdot)\geq v(t,\cdot)$  a.e. in  $\Omega$  for all  $t\geq t_0$ . Trivially, by (6.3), we also have  $g(u(t,x))\geq g(\frac{c_0}{2})$  a.e. in  $\Omega$  for all  $t\geq t_0$ .

Fix any  $t > t_0$  and any  $M > \frac{c_0}{2}$  and consider the test function defined by

$$\varphi_M(x) = \begin{cases} \frac{1}{g(u(t,x))} & \text{if } u(t,x) \leq M; \\ \frac{1}{g(M)} & \text{if } u(t,x) > M. \end{cases}$$

Then  $\varphi_M$  is admissible in the formulation of a weak solution of  $(P_{\sigma,f,u_0})$ , i.e.  $\varphi_M \in W^{1,p}(\Omega)$ . Thus,

$$\int_{\Omega} \partial_t u \varphi_M(u) \, dx + \sigma \oint_{\partial \Omega} \partial_t u \varphi_M(u) \, d\rho \\
- \underbrace{\int_{\{x \in \Omega \mid u(t,x) < M\}} |\nabla u|^p \frac{g'(u)}{g(u)^2} \, dx}_{\geq 0} - \int_{\Omega} m(x,t) g(u) \varphi_M(u) \, dx = 0,$$

so that

$$\int_{\Omega} \partial_t u \varphi_M(u) \, dx + \sigma \oint_{\partial \Omega} \partial_t u \varphi_M(u) \, d\rho \ge \int_{\Omega} m(x, t) g(u) \varphi_M(u) \, dx \ge \int_{\Omega} m(x, t) \, dx.$$

Letting M tend to  $\infty$  implies

$$\int_{\Omega} \frac{\partial_t u}{g(u)} dx + \sigma \oint_{\partial \Omega} \frac{\partial_t u}{g(u)} d\rho \ge \int_{\Omega} m(x, t) dx.$$

Setting  $h(s) = \int_{s_0}^s \frac{d\eta}{g(\eta)}$  and integrating between  $t_0$  and  $\tau$  lead to

$$\begin{split} \int_{\Omega} \left( h(u(\tau, x)) - h(u(t_0, x)) \right) dx + \sigma \left( \oint_{\partial \Omega} \left( h(u(\tau, r)) - h(u(t_0, r)) \right) d\rho(r) \right) \\ & \geq \int_{t_0}^{\tau} \int_{\Omega} m(x, t) \, dx \, dt. \end{split}$$

By (6.6), the r.h.s. tends to infinity as  $\tau \to \infty$ , whereas the l.h.s. remains bounded by Hypothesis (6.4). This contradiction permits to conclude.

**Remark 6.2.** The result in Theorem 6.1 applies especially to reaction terms of the form  $f = \lambda |u|^{q-1}$  with  $\lambda > 0$  and q > 2 or of the form  $f(u) = e^u$ .

In the sequel,  $T_{\max}(u)$  will denote the maximal existence time of the weak solution of  $(P_{\sigma,f})$  with respect to the  $L^{\infty}(\Omega)$ -norm, i.e.

$$T_{\max}(u) \stackrel{\text{def}}{=} \inf \left\{ s > 0 \mid \limsup_{t \nearrow s} \|u(t, \cdot)\|_{\infty} = \infty \right\}.$$
 (6.8)

In the case  $m \equiv 1$  a lower bound for the maximal existence time can be obtained by comparison with the solution of the ODE under an appropriate initial condition.

**Proposition 6.3.** Let  $u_0 \in \mathcal{X}^{\infty}$ . Under (6.2) and (6.4), suppose that z is the solution of the ordinary IVP

$$\begin{cases} \dot{z} = g(z), & \text{for } 0 < t < t_0 := \int_{\|u_0\|_{\mathcal{X}_{\infty}}}^{\infty} \frac{d\eta}{g(\eta)} \\ z(0) = \|u_0\|_{\mathcal{X}_{\infty}}, \end{cases}$$

Then any weak solution u of  $(P_{\sigma,g,u_0})$  satisfies either  $T_{\max}(u) = 0$  or  $T_{\max}(u) \geq t_0$  and  $u(t,\cdot) \leq z(t)$  for all  $t \in [0,T_{\max}(u))$ , a.e. in  $\Omega$ .

*Proof.* Since g is of class  $C^1$ , g and the pair (u,z) satisfy the one-sided Lipschitz condition (2.1) for  $0 < t < T_{\max}(u)$ , with  $l(t) = \max\{|g'(s)| \mid s \in [0, \max\{z(t), \|u(t,\cdot)\|_{\infty}\}]\}$  (c.f. Remark 2.15). Thus, by Theorem 2.9, for all  $t \in [0, T_{\max}(u))$ ,  $u(t,\cdot) \leq z(t)$  a.e. in  $\Omega$ . Note that by (6.4), the maximal existence time  $t_0$  of z satisfies  $\infty > t_0 = \int_{\|u_0\|_{\mathcal{X}_{\infty}}}^{\infty} \frac{d\eta}{g(\eta)}$ , since by separation of variables,  $t = \int_0^t \frac{\dot{z}(s)}{g(z(s))} \, ds = \int_{z(0)}^{z(t)} \frac{d\eta}{g(\eta)}$ .

Let us prove now three different blow up results for nonlinearities of the form  $f=f_{\lambda,q}$ , always assuming that  $\lambda>0$ . We start with the particular case q=p>2, i.e. with Problem  $(P_{\sigma,f_{\lambda,p},u_0})$ . We recall the definition of  $E_{\lambda}(u):=\frac{1}{p}\int_{\Omega}(|\nabla u|^p-|u|^p)\,dx$ . Note that according to Proposition 4.4, blow up in finite time cannot occur for  $1< q\leq 2$ .

**Theorem 6.4.** Suppose  $u_0 \in W^{1,p}(\Omega) \cap L^{\infty}(\Omega)$  satisfies  $E_{\lambda}(u_0) < 0$ . Let u be a weak solution of Problem  $(P_{\sigma,f_{\lambda,p},u_0})$  with  $\lambda > 0, p > 2$  and initial data  $u_0$ . Then  $T_{\max}(u) < \infty$ .

*Proof.* Assume by contradiction that  $T_{\max}(u)=\infty$ . Then, for any s>0 there exist  $M_s, \delta_s>0$  such that  $\|u(t,\cdot)\|_\infty < M_s$  for all  $t\in [s-\delta_s,s]$ . Put  $\delta_0=0, M_0=\|u_0\|_\infty$ . Hence, by a compactness argument,  $u\in L^\infty(\Omega_T)$  for any T>0, and the condition (3.3) of Theorem 3.1 will be satisfied in [0,T]. Using the results and notations of Lemma 3.3, and the fact that  $E_\lambda(u_0)<0$  and  $H(t)\geq 0$ , it follows that  $E_\lambda(u(t,\cdot))<0$  a.e. and thereby, that  $H^{1-\frac{p}{2}}$  is decreasing. The continuity of H and the concavity of  $H^{1-\frac{p}{2}}$  will imply that  $H^{1-\frac{p}{2}}$  vanishes in finite time, which leads to the desired contradiction.

Next, we shall prove that there is also blow up for solutions of Problem  $(P_{\sigma,f_{\lambda,q},u_0})$  for  $q > \max\{2,p\}$  and for (sufficiently regular) *positive* initial data  $u_0$ . We shall use in this case the following parabolic equation under Dirichlet boundary conditions

$$\begin{cases}
\partial_t u = \Delta_p u + \lambda |u|^{q-2} u & \text{in } \Omega \text{ for } t > 0, \\
u(t, \cdot) = 0 & \text{on } \partial \Omega \text{ for } t > 0.
\end{cases}$$
(6.9)

The corresponding energy functional  $E_F$  defined in (3.2) related to Problem (6.9) and to  $(P_{\sigma,f_{\lambda,q},u_0})$  will be denoted by  $E_{\lambda,q}$ :

$$E_{\lambda,q}(u) = \frac{1}{p} \int_{\Omega} |\nabla u|^p dx - \frac{\lambda}{q} \int_{\Omega} |u|^q dx.$$

For any solution u of Problem (6.9) we will define  $T_{\rm max}(u)$  identically as in (6.8). We have

**Theorem 6.5.** Suppose that  $\lambda > 0$  and  $q > \max\{2, p\}$ . Let  $u_0 \in W_0^{1,p}(\Omega) \cap L^{\infty}(\Omega)$  with  $E_{\lambda,q}(u_0) \leq 0$ . Then any weak solution v of the Cauchy problem (6.9) with initial data  $u_0$  blows up in finite time with respect to  $\|\cdot\|_2$  at the latest at time  $T^*$  satisfying satisfying

$$T_{\max}(v) \le T^* \le \frac{q}{\lambda(q-2)(q-p)} |\Omega|^{\frac{q-2}{2}} \left( \int_{\Omega} |u_0|^2 dx \right)^{\frac{2-q}{2}} =: T_2.$$
 (6.10)

*Proof.* According to the results of [J, Theorem 2.1], there exists a local solution of (6.9) which is bounded. Thus,  $T_{\text{max}}(v) > 0$ . Introduce

$$N(t) = ||v(t, \cdot)||_2^2 = \int_{\Omega} |v(t, x)|^2 dx.$$

Multiplying the differential equation by v leads to

$$\int_{\Omega} v \partial_t v \, dx = -\int_{\Omega} |\nabla v|^p \, dx + \lambda \int_{\Omega} |v|^q \, dx = -p E_{\lambda,q}(v) + \lambda \frac{q-p}{q} \int_{\Omega} |v|^q \, dx.$$

Since by hypothesis q>2, the function  $f_{\lambda,q}$  satisfies the Lipschitz condition (3.3) in  $t\in[0,T]$ , with any  $T< T_{\max}(v)$ . Hence (3.10) implies that  $E_{\lambda,q}(v(t,\cdot))$  is decreasing in time and, since  $E_{\lambda,q}(u_0)\leq 0$ , we have  $E_{\lambda,q}(v(t,\cdot))\leq 0$  for all  $t\in[0,T]$ . Hence

$$\frac{dN(t)}{dt} = 2 \int_{\Omega} v \partial_t v \, dx \ge \frac{2\lambda(q-p)}{q} \int_{\Omega} |v|^q \, dx$$

and by Hölder's inequality

$$\int_{\Omega} |v|^2 dx \le |\Omega|^{\frac{q-2}{q}} \left( \int_{\Omega} |v|^q dx \right)^{\frac{2}{q}},$$

we obtain

$$\frac{dN(t)}{dt} \ge \frac{2\lambda(q-p)}{q} |\Omega|^{\frac{2-q}{2}} N(t)^{\frac{q}{2}} =: \alpha N(t)^{\frac{q}{2}}.$$

Integration between 0 and t > 0 leads to

$$N(t) \ge \left(N(0)^{\frac{2-q}{2}} - \frac{q-2}{2}\alpha t\right)^{\frac{2}{2-q}}.$$

Since q > 2, N(t) becomes infinite at  $t = T_2$ , with  $T_2$  as defined in the assertion. As  $L^{\infty}(\Omega) \subset L^2(\Omega)$ , the inequality in (6.10) is plain.

By comparing positive solutions of parabolic problem with Dirichlet boundary conditions with those of parabolic problem with dynamical boundary boundary conditions we have the following result:

**Theorem 6.6.** Assume that  $\partial\Omega$  is of class  $C^2$ . Suppose that  $q > \max\{2, p\}$  and  $\lambda > 0$ . Let  $u_0 \in W_0^{1,p}(\Omega) \cap L^{\infty}(\Omega)$ ,  $u_0 \geq 0$  in  $\Omega$  and  $E_{\lambda,q}(u_0) \leq 0$ . Then any weak solution of the Problem  $(P_{\sigma,f_{\lambda,q},u_0})$  u blows up at the latest for  $t = T_2$ .

Proof. Let us assume by contradiction that  $T_{\max}(u) > T_2$ . Let v be the unique weak solution of Problem (6.9) with initial data  $u_0$  (c.f. [J, Theorem 2.1]). As  $u_0 \geq 0$ ,  $v \geq 0$  as well in [0,T] with  $T < T_{\max}(v) \leq T_2 < T_{\max}(u)$ . In particular, both solutions u and v belong to  $L^{\infty}(\Omega_T)$ . Consequently, c.f. Remark 2.15, the hypotheses (ii) and (iii) of the comparison result Theorem 2.12 are satisfied. Moreover, the regularity results already cited in Remark 2.13 imply that  $v \in C^1((0,T]\times\Omega)$ . Thus, the hypothesis (iv) is satisfied too, and thereby,  $u(t,\cdot) \geq v(t,\cdot)$  a.e. in  $\Omega$  for all  $t \in [0,T]$  and  $T_2 < T_{\max}(u) \leq T_{\max}(v)$ . This contradicts (6.10) and permits to conclude.

As for more general nonlinearities, we deduce the following result

**Corollary 6.7.** Under the hypothesis of Theorem 6.6, let u be a weak solution of  $(P_{\sigma,f,u_0})$  with f satisfying

$$f(\cdot, \cdot, z) \ge \lambda |z|^{q-2}z$$
 for all  $z \ge 0$ .

Then u blows up at the latest at  $T_2$ :

$$T_{\max}(u) \leq T_2$$
.

*Proof.* Let  $\tilde{u}$  be a solution of Problem  $(P_{\sigma,f_{\lambda,q},u_0})$  with initial data  $u_0$ . As  $\tilde{u}$  is a weak lower solution of Problem  $(P_{\sigma,f,u_0})$  and  $u(t,\cdot)$  is bounded for any  $t\in[0,T_{\max}(u))$ , then the Lipschitz condition (2.1) applies to the pair  $(\tilde{u},u)$  and Theorem 2.9 permits to conclude.

Finally, dealing with nonnegative solutions, we can derive another upper bound for the blow up time under the Neumann boundary condition ( $\sigma = 0$ ) for arbitrary  $p > p_1$  and arbitrary q > 2. Note that the upper bound  $T_1$  will be optimal, as readily follows by choosing constant positive initial data.

**Theorem 6.8.** Suppose that q > 2 and  $\lambda > 0$ . Let  $u_0 \in \mathcal{X}^2$  and  $u_0 \ge 0$  a.e. in  $\Omega$ ,  $u_0 \not\equiv 0$ . Then a weak solution u of  $(P_{0,f_{\lambda,q},u_0})$  blows up in finite time with respect the  $L^1$ -norm at the latest at time  $T^{**}$  satisfying

$$T_{\max}(u) \le T^{**} \le \frac{\left(\int_{\Omega} |u_0| \, dx\right)^{2-q}}{(q-2)\lambda |\Omega|^{2-q}} =: T_1.$$

*Proof.* Assume by contradiction that  $T_{\max}(u) = \infty$ . First, note that by the aforementioned hypothesis on  $\lambda$  and  $u_0$ , Theorem 2.9 implies that  $u \geq 0$  for all  $t \geq 0$  and a.e. in  $\Omega$ . Integrating the partial differential equation and using Hölder's inequality yield

$$\int_{\Omega} \partial_t u \, dx = \lambda \int_{\Omega} u^{q-1} \, dx \ge \lambda |\Omega|^{2-q} \left( \int_{\Omega} u \, dx \right)^{q-1}.$$

Set  $N(t) = ||u(t, \cdot)||_{1,\Omega}$  for t > 0, we are led to

$$\frac{dN(t)}{dt} \ge \lambda |\Omega|^{2-q} N(t)^{q-1} \tag{6.11}$$

and, integrating between 0 and t > 0, we obtain

$$N(t)^{2-q} \le (N(0)^{2-q} - (q-2)\lambda |\Omega|^{2-q}t),$$

which implies that N becomes infinite at  $T_1$ .

### Acknowledgments

The authors gratefully acknowledge valuable remarks by both referees.

#### References

- [A] Amman, H.: Ordinary differential equations. De Gruyter Berlin (1990)
- [Ba] Ball, J.M.: Remarks on blow-up and nonexistence theorems for nonlinear evolution equations. Quart. J. Math. Oxford **28**, 473–486 (1977)
- [BBR] Bandle, C., Below, J. von, Reichel, W.: Parabolic problems with dynamical boundary conditions: eigenvalue expansions and blow up. Rend. Lincei Math. Appl. 17,35–67 (2006).
- [Bel] Bellman, R.: Stability Theory of Differential Equations. McGraw Hill, New York, 1953.
- [Be] Below, J. von: Parabolic network equations. 2nd ed. Tübinger Universitätsverlag, Tübingen (1994)
- [BD] Below, J. von, De Coster, C.: A qualitative theory for parabolic problems under dynamical boundary conditions. J. Inequalities and Applications 5, 467–486 (2000)
- [BP] Below, J. von, Pincet Mailly, G.: Blow up for reaction diffusion equations under dynamical boundary conditions. Comm. Partial Differential Equat. **28**, 223–247 (2003)
- [BH] Berryman, J.G., Holland, C.J.: Stability of the separable solution for fast diffusion equations. Arch. Rat. Mech. Anal. **74**, 279–288 (1980)
- [Br] Brézis, B.: Opérateurs maximaux monotones. North–Holland Mathematics Studies 5 (1973)
- [CG] Cipriani, F., Grillo, G.: Uniform Bounds for Solutions to Quasilinear Parabolic Equations. J. Differential Equat. **177**, 209–234 (2001)
- [CT] Cuesta, M., Takáč, P.: A Strong comparison principle for positive solutions of degenerate elliptic equations. J. Differential and Integral Equat. 13, 741–746 (2000)
- [Di] DiBenedetto, E.: Degenerate Parabolic equations. Universitext, Springer-Verlag (1991)
- [E] Escher, J.: Quasilinear parabolic systems with dynamical boundary conditions. Comm. Partial Differential Equat. **18**, 1309–1364 (1993)
- [G] Gal, C. G.: On a class of degenerate parabolic equations with dynamical boundary conditions. J. Differential Equat. **253**, 126–166 (2012)

- [GW] Gal, C. G., Warma, M.: Well posedness and the global attractor of some quasilinear parabolic equations with nonlinear dynamical boundary conditions. Differential and Integral Equat. **33**, 327–358 (2010)
- [H] Hintermann, T.: Evolution equations with dynamic boundary conditions. Proc. Royal Soc. Edinburgh **113A**, 43–60 (1989)
- [J] Junning, Z.: Existence and nonexistence of solutions for  $u_t = \text{div}(|\nabla u|^{p-2}\nabla u) + f(\nabla u, u, x, t)$ . J. Math. Anal. Appl. 172, 130–146 (1993)
- [LX] Li, Y., Xie, C.: Blow-up for p-Laplacian parabolic equations. Electronic J. Differential Equat. **20**, 1–12 (2003)
- [LY] Li, K., You, B.: Uniform attractors for the non-autonomous *p*–Laplacian equations with dynamic flux boundary conditions. Boundary Value Prob. **128**, 24 pp. (2013)
- [Li] Lieberman, G. M.: Boundary and initial regularity for solutions of degenerate parabolic equations. Nonlinear Analysis TMA **20**, 551–569 (1993)
- [Ls] Lions, J. L.: Quelques Méthodes de Résolution des Probèmes aux Limites non Linéaires. Dunod, Paris (1969)
- [P] Pincet Mailly, G.: Explosion des solutions de problèmes paraboliques sous conditions au bord dynamiques. PhD thesis, Université du Littoral Côte d'Opale (2001)
- [SV] G. Savaré, G., Vespri, V.: The asymptotic profile of solutions of a class of doubly nonlinear equations. Nonlinear Analysis TMA **12**, 1553-1565 (1994)
- [Si] Simon, J.: Régularité de la solution d'une équation non linéaire. In: Journées d'Analyse Non Linéaire, P. Benilan and J. Robert eds., Lecture Notes in Math. 665, Springer, Berlin, 205-227 (1978)
- [Sw] Showalter, R. E.: Monotone Operators in Banach Space and Nonlinear Partial Differential Equations. Mathematical Surveys and Monographs 49, AMS (1997)
- [Vul] Vulkov, L. G.: Blow up for some quasilinear equations with dynamical boundary conditions of parabolic type. Applied Mathematics and Computation **191**, 89–99 (2007)
- [VV] Vazquez, J. L., Vitillaro, E.: On the Laplace equation with dynamical boundary conditions of reactive-diffusive type. J. Math. Anal. Appl. **354**, 674–688 (2009)