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# Kernel-based quadrature applied to offshore wind turbine damage estimation

(1)

(3)

Python

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# **Industrial context & Problem statement**

- EDF Renewables operates  $\sim$  10 000 MW of wind turbine (WT) worldwide
- New technologies (e.g., offshore floating WT), wind farms reaching end-of-life
- $\hookrightarrow$  Need probabilistic tools to optimize safety margins and asset management **Chained simulation model**

Expensive-to-evaluate deterministic computer model [3] (distributed on a cluster):

 $g: \mathbb{R}^p \times \mathbb{R}^q \to \mathbb{R}, (\mathbf{x}, \mathbf{z}) \mapsto g(\mathbf{x}, \mathbf{z})$ 

TurbSim	TAT:	DIEGO	Von Mises stress	
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# **Kernel-based probabilistic integration**

**1. Select integration nodes**  $\Rightarrow \mathbb{E}[g(\mathbf{X})] \approx \frac{1}{n} \sum_{i=1}^{n} g(\mathbf{x}^{(i)})$ 

**Candidate set:** S is a fairly dense finite subset of  $\mathbb{R}^d$  with size  $N \gg n$  that emulates the target distribution (e.g., a large Sobol' sequence, available data as in Fig.2) **Kernel herding criterion [4, 6]:** at iteration n + 1, for a given design of experiments (DoE)  $\mathbf{X}_n = {\mathbf{x}^{(1)}, \dots, \mathbf{x}^{(n)}}$ , and a given kernel k

$$\mathbf{x}^{(n+1)} \in \arg\min\left(\frac{1}{N}\sum_{i=1}^{n}k(\mathbf{x},\mathbf{x}^{(i)}) - \frac{1}{N}\sum_{i=1}^{N}k(\mathbf{x},\mathbf{x}^{(j)})\right)$$
(4)



• The random vectors are considered mutually independent

#### **Uncertainty propagation**

#### Two nested quantities of interest to estimate (see [5])

**Damage Equivalent Load (DEL):** expected value of the damage over the environmental conditions (conditionally to a sample of system variables Z = z)  $\mathbb{E}[Y|\mathbf{Z} = \mathbf{z}] = \mathbb{E}[g(\mathbf{X}, \mathbf{Z})|\mathbf{Z} = \mathbf{z}] = \int_{\mathcal{D}_{\mathbf{Y}}} g(\mathbf{x}, \mathbf{z}) f_{\mathbf{X}}(\mathbf{x}) \, \mathrm{d}\mathbf{x} = \boldsymbol{\phi}(\mathbf{z})$ (2)

**Probability of threshold exceedance:** for a given threshold  $y_{th} \in \mathbb{R}$  $p_{\mathrm{f}} = \mathbb{P}\left(\boldsymbol{\phi}(\mathbf{Z}) > y_{\mathrm{th}}\right) = \int_{\mathcal{D}_{\mathbf{Z}}} \mathbb{1}_{\{\boldsymbol{\phi}(\mathbf{z}) > y_{\mathrm{th}}\}} f_{\mathbf{Z}}(\mathbf{z}) \, \mathrm{d}\mathbf{z}$ 

 $\hookrightarrow$  How to efficiently estimate the DEL?

#### **Environmental measured data**



2. Compute optimal weights for integration  $\Rightarrow \mathbb{E}[g(\mathbf{X})] \approx \sum_{i=1}^{n} \mathbf{w}_{i}^{*} g(\mathbf{x}^{(i)})$ 

**Optimal weights for quadrature [2]:** for a given DoE  $X_n$  and a given kernel k  $\mathbf{w}^* = P(\mathbf{X}_n)\mathbf{K}_n^{-1}$ (5) with potentials  $P(\mathbf{X}_n) = \left[\int k(\mathbf{x}, \mathbf{x}^{(1)}) f_{\mathbf{X}}(\mathbf{x}) d\mathbf{x}, \dots, \int k(\mathbf{x}, \mathbf{x}^{(n)}) f_{\mathbf{X}}(\mathbf{x}) d\mathbf{x}\right]$ and variance-covariance matrix  $\{\mathbf{K}_n\}_{i,i} = k(\mathbf{x}^{(i)}, \mathbf{x}^{(j)})$ 



Fig. 3: Kernel-based sampling on a bivariate random mixture (markers' sizes indexed to the optimal weights)

 $\hookrightarrow$  E. Fekhari et al. "Model predictivity assessment: incremental test-set selection" and accuracy evaluation". In: Preprint (2021).





 $\rightarrow$  New Python package on pypi: otkerneldesign (using OpenTURNS[1])

## **Conclusions & Perspectives**

- Combining kernel herding with optimal weights is an efficient integration method
- This method is sensitive to the chosen kernel and its hyper-parameters
- This method allows direct sampling from available empirical distribution
- Active learning methods might be more efficient but are harder to distribute (HPC)
- $\hookrightarrow$  Determine influential system variables using advanced sensitivity analysis methods  $\hookrightarrow$  Adapt kernel-based sampling methods to reliability analysis problems

### References

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### Numerical results: DEL estimation by kernel herding

