

# A Global-Scale Analysis of Hydrologic Extremes using Hidden Climate Indices

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### ▶ To cite this version:

Benjamin Renard, David M<br/>cinerney, Seth Westra, Michael Leonard, Dmitri Kavetski, et al.: A Global-Scale Analysis of Hydrologic Extremes using Hidden Climate Indices. EGU General Assembly 2022, May 2022, Vienna, Austria. 10.5194/egu<br/>sphere-egu22-7122 . hal-03710318

# HAL Id: hal-03710318 https://hal.science/hal-03710318

Submitted on 30 Jun2022

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## Hydrologic Extremes at the Global Scale 100-year Analysis and 180-year Reconstruction

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EGU General Assembly, 27 May 2022











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Climate Change 2021 The Physical Science Basis



"The frequency and intensity of heavy precipitation events have increased since the 1950s over most land area for which observational data are sufficient [...]"

ipcc climate change

Climate Change 2021 The Physical Science Basis Summary for Policymakers



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" Confidence about peak flow trends over past decades on the global scale is low [...]"

#### ipcc

Climate Change 2021 The Physical Science Basis Surmary for Policymakers



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#### ipcc

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" changes may be more complex than simple trends"



EGU May 2022

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HEGS

Better understand the temporal variability of heavy precipitation (P) and flood (Q) at the global scale by means of an innovative probabilistic model

#### 100-year analysis

- Identify common (P+Q) vs. specific (P-only or Q-only) signals behind global extremes
- Look for trends and low-frequency variability in those signals

#### 180-year reconstruction

Using 20CRv3, reconstruct probabilities of extreme P/Q since 1836

P: a selection from Hadex 2+3 Donat et al. (2013); Dunn et al. (2020)



#### **Q**: a selection from <u>GSIM</u> <u>Do et al.</u> (2018); <u>Gudmundsson et al.</u> (2018)

Available series length at 1884 sites



P: a selection from Hadex 2+3 Donat et al. (2013); Dunn et al. (2020)

#### **Q**: a selection from <u>GSIM</u> <u>Do et al.</u> (2018); <u>Gudmundsson et al.</u> (2018)



• Extract seasonal maxima at each site (SON, DJF, MAM, JJA)

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- The rectangle dilemma...

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- Extract seasonal maxima at each site (SON, DJF, MAM, JJA)
- The rectangle dilemma...
- In this work, we'll use all data available during 1916-2015

After suitable data transformation...

```
\begin{cases} \mathbb{E}[P(s,t)] = \\ \mathbb{E}[Q(s,t)] = \end{cases}
```

Legend: varies in space and time

After suitable data transformation...

$$\begin{cases} \mathbb{E}[P(s,t)] = c_{P}(s) \\ \mathbb{E}[Q(s,t)] = c_{Q}(s) \\ \text{constant (intercept)} \end{cases}$$

Legend: varies in space and time ; varies in space

After suitable data transformation...

```
\begin{cases} \mathbb{E}[P(s,t)] = c_P(s) + \lambda_P(s)\tau(t) \\ \mathbb{E}[Q(s,t)] = c_Q(s) + \lambda_Q(s)\tau(t) \end{cases}
```

.

After suitable data transformation...

$$\mathbb{E}[P(s,t)] = c_P(s) + \lambda_P(s)\tau(t)$$
$$\mathbb{E}[Q(s,t)] = c_Q(s) + \underbrace{\lambda_Q(s)\tau(t)}_{\text{the SAME covariate  $\tau$  affects both P and Q$$

After suitable data transformation...

$$\mathbb{E}[P(s,t)] = c_P(s) + \lambda_P(s)\tau(t) + \pi(s)\delta(t)$$
$$\mathbb{E}[Q(s,t)] = c_Q(s) + \lambda_Q(s)\tau(t) + \theta(s)\omega(t)$$

After suitable data transformation...

$$\mathbb{E}[P(s,t)] = c_P(s) + \lambda_P(s)\tau(t) + \overline{\pi(s)\delta(t)}$$

$$\mathbb{E}[Q(s,t)] = c_Q(s) + \lambda_Q(s)\tau(t) + \theta(s)\omega(t)$$
Q-specific covariate and its effects

After suitable data transformation...

$$\mathbb{E}[P(s,t)] = c_P(s) + \lambda_P(s)\tau(t) + \pi(s)\delta(t)$$
$$\mathbb{E}[Q(s,t)] = c_Q(s) + \lambda_Q(s)\tau(t) + \theta(s)\omega(t)$$

Legend: varies in space and time ; varies in space ; varies in time

 All covariates are considered unknown and are estimated → Hidden Climate Indices (HCI)

After suitable data transformation...

$$\mathbb{E}[P(s,t)] = c_P(s) + \lambda_P(s)\tau(t) + \pi(s)\delta(t)$$
$$\mathbb{E}[Q(s,t)] = c_Q(s) + \lambda_Q(s)\tau(t) + \theta(s)\omega(t)$$

Legend: varies in space and time ; varies in space ; varies in time

All covariates are considered unknown and are estimated
 → Hidden Climate Indices (HCI)
 τ(t) ~ AR(1) + trend.

After suitable data transformation...

$$\mathbb{E}[P(s,t)] = c_P(s) + \lambda_P(s)\tau(t) + \pi(s)\delta(t)$$
$$\mathbb{E}[Q(s,t)] = c_Q(s) + \lambda_Q(s)\tau(t) + \theta(s)\omega(t)$$

- All covariates are considered unknown and are estimated
   → Hidden Climate Indices (HCI)
- $au(t) \sim \mathsf{AR}(1) + \mathsf{trend.}$  Same for  $\delta(t)$  and  $\omega(t)$

After suitable data transformation...

$$\mathbb{E}[P(s,t)] = c_P(s) + \lambda_P(s)\tau(t) + \pi(s)\delta(t)$$
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- All covariates are considered unknown and are estimated → Hidden Climate Indices (HCI)
- $au(t) \sim \mathsf{AR}(1) + \mathsf{trend.}$  Same for  $\delta(t)$  and  $\omega(t)$
- $\lambda(s) \sim$  Spatial Gaussian Process. Same for others

After suitable data transformation...

$$\mathbb{E}[P(s,t)] = c_P(s) + \lambda_P(s)\tau(t) + \pi(s)\delta(t) + more \ components...$$
$$\mathbb{E}[Q(s,t)] = c_Q(s) + \lambda_Q(s)\tau(t) + \theta(s)\omega(t) + more \ components...$$
one component

- All covariates are considered unknown and are estimated → Hidden Climate Indices (HCI)
- $au(t) \sim \mathsf{AR}(1) + \mathsf{trend.}$  Same for  $\delta(t)$  and  $\omega(t)$
- $\lambda(s) \sim$  Spatial Gaussian Process. Same for others
- $\bullet\,$  One component not enough at the global scale  $\rightarrow\,5$  used here

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After suitable data transformation...

$$\mathbb{E}[P(s,t)] = c_P(s) + \lambda_P(s)\tau(t) + \pi(s)\delta(t) + more \ components...$$
$$\mathbb{E}[Q(s,t)] = c_Q(s) + \lambda_Q(s)\tau(t) + \theta(s)\omega(t) + more \ components...$$

Legend: varies in space and time ; varies in space ; varies in time

- All covariates are considered unknown and are estimated → Hidden Climate Indices (HCI)
- $au(t) \sim \mathsf{AR}(1) + \mathsf{trend.}$  Same for  $\delta(t)$  and  $\omega(t)$
- $\lambda(s) \sim$  Spatial Gaussian Process. Same for others
- $\bullet\,$  One component not enough at the global scale  $\rightarrow\,5$  used here
- (Bayesian + MCMC) estimation



Effect on P











Effect on P













Effect on P





















component 📫 1 🛱 2 🛱 3 🛱 4 📫 5



#### 180-year reconstruction









 $\rightarrow$  Using 20CRv3, reconstruction of HCls from 1836  $\rightarrow$  Hydro-extreme probability maps from 1836



- $\rightarrow$  Using 20CRv3, reconstruction of HCIs from 1836
- $\rightarrow$  Hydro-extreme probability maps from 1836

## Thank you!

Renard & Thyer (2019). Revealing Hidden Climate Indices from the Occurrence of Hydrologic Extremes. *Water Resources Research*.

Renard et al. (2021). A Hidden Climate Indices Modeling Framework for Multi-Variable Space-Time Data. *Water Resources Research.* 



https://globxblog.inrae.fr/

https://github.com/STooDs-tools



This project has received funding from the European Union's Horizon 2020 research and innovation programme under the Marie Sklodowska-Curie grant agreement <u>No 835496</u> Non-exceedance probability ( $\Leftrightarrow$  return period) of the largest event of the season

# **Example**: Maximum streamflow in December-January-February for 2 Australian stations





Clarke Brooke at Hillview Farm (WA)

Beta distribution reparameterized in terms of mean  $\mu$  and precision  $\gamma$ 

$$\begin{cases} P(s,t) \sim Beta\left(\mu_{P}(s,t), \gamma_{P}(s)\right); Q(s,t) \sim Beta\left(\mu_{Q}(s,t), \gamma_{Q}(s)\right)\\ logit\left(\mu_{P}(s,t)\right) = \lambda_{P,0}(s) + \sum_{k=1}^{K} \lambda_{P,k}(s)\tau_{k}(t) + \sum_{k=1}^{K} \pi_{k}(s)\delta_{k}(t)\\ logit\left(\mu_{Q}(s,t)\right) = \lambda_{Q,0}(s) + \sum_{k=1}^{K} \lambda_{Q,k}(s)\tau_{k}(t) + \sum_{k=1}^{K} \theta_{k}(s)\omega_{k}(t) \end{cases}$$



### P-specific HCIs with large trends



### HCIs with notable autocorrelation





#### Method: inverted regression

Step 1: w(s,t): climate field at time t and location s  $\hat{\tau}_k(t)$ : estimated HCI's (from previous analysis) Goal: estimate  $\psi_k(s)$ 's in:  $w(s,t) = \psi_0(s) + \psi_1(s)\hat{\tau}_1(t) + \ldots + \psi_K(s)\hat{\tau}_K(t) + \varepsilon(s,t)$ 

Step 2:  $w(s, t^*)$ : climate field at time  $t^*$  and location s $\widehat{\psi}_k(s)$ : estimated from previous step Goal: estimate  $\tau_k(t^*)$ 's in:  $w(s, t^*) = \psi_0(s) + \widehat{\psi}_1(s)\tau_1(t^*) + \ldots + \widehat{\psi}_K(s)\tau_K(t^*) + \varepsilon(s, t^*)$ 

Alternatives: LASSO, RIDGE and other form of penalised regression, but first attempts inconclusive





SON 1840



#### Probability of a 10-year flood occurring

1			
0.0	0.2	0.4	0.6



SON 1840



#### Probability of a 10-year flood occurring

1			
1			
0.0	0.2	0.4	0.6

SON 1840





SON 1840



#### SON 1840







#### Probability of a 10-year flood occurring





SON 1840



#### Probability of a 10-year flood occurring

		and the second	
0.0	0.2	0.4	0.6







Probability of a 10-year flood occurring

0.0 0.1 0.2 0.3 0.4 0.5







SON 1840



#### Probability of a 10-year flood occurring

0.0	0.2	0.4	0.6

SON 1840 Probability of a 10-year flood occurring SON 1867 Probability of a 10-year flood occurring Probability of a 10-year flood occurring



 $\rightarrow$  Reliability: good (cross-validation); Sharpness: poor (P) to good (Q)

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Renard

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