

A Dedicated Joint Unmixing and Demosaicing Method for Snapshot Spectral Images

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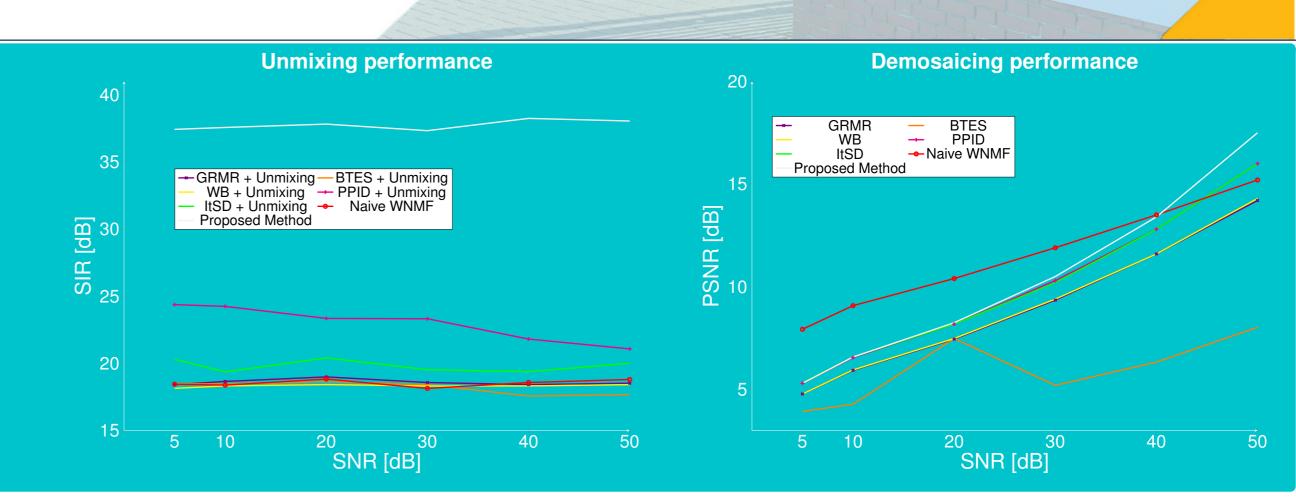
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Performing unmixing after demosaicing SSI images is not a good strategy. Instead, unmixing from the SSI data is far better!



A Dedicated Joint Unmixing and Demosaicing Method for Snapshot Spectral Images

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Snapshot Spectral Imaging (SSI)

Strategies for miniaturized HSI sensors (on the left for images,

Naive Method

Weighted Non-negative Matrix Factorization (WNMF) is used to solve the joint demosaicing and unmixing problem.

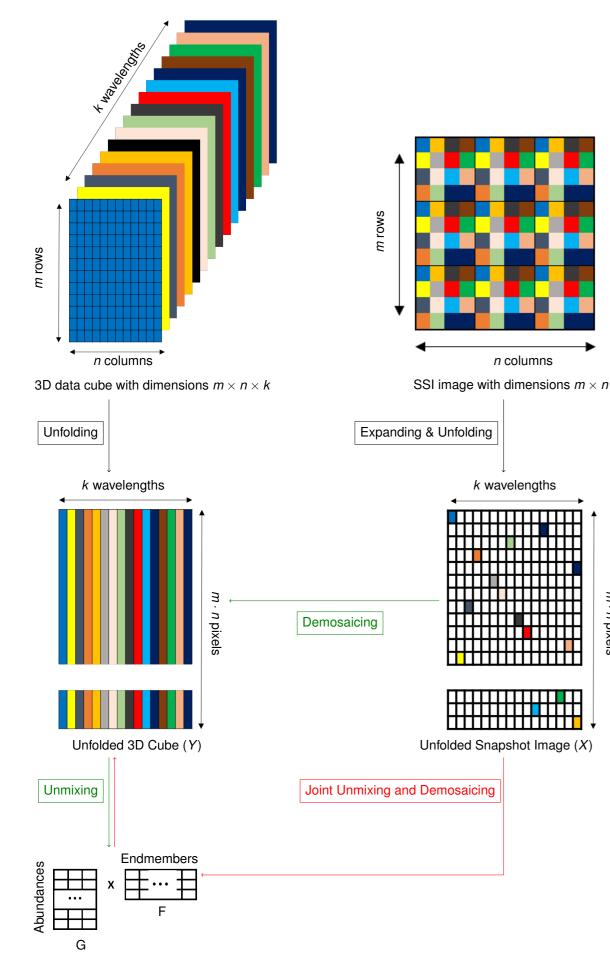
Real Filter Harmonics Problem

Fabry-Perot filters introduce additional harmonics around each

middle and right for videos - Source IMEC).



- Demosaicing = providing a datacube combining full spectral information & good spatial resolution
- Various approaches have been proposed:
- Weighted bilinear interpolation (WB)
- Iterative Spectral Difference (ItSD)
- Multispectral demosaicing approach using a pseudo-panchromatic image (PPID)
- Binary Tree-Based Generic Demosaicing (BTES)
- Graph and rank regularized method (GRMR)



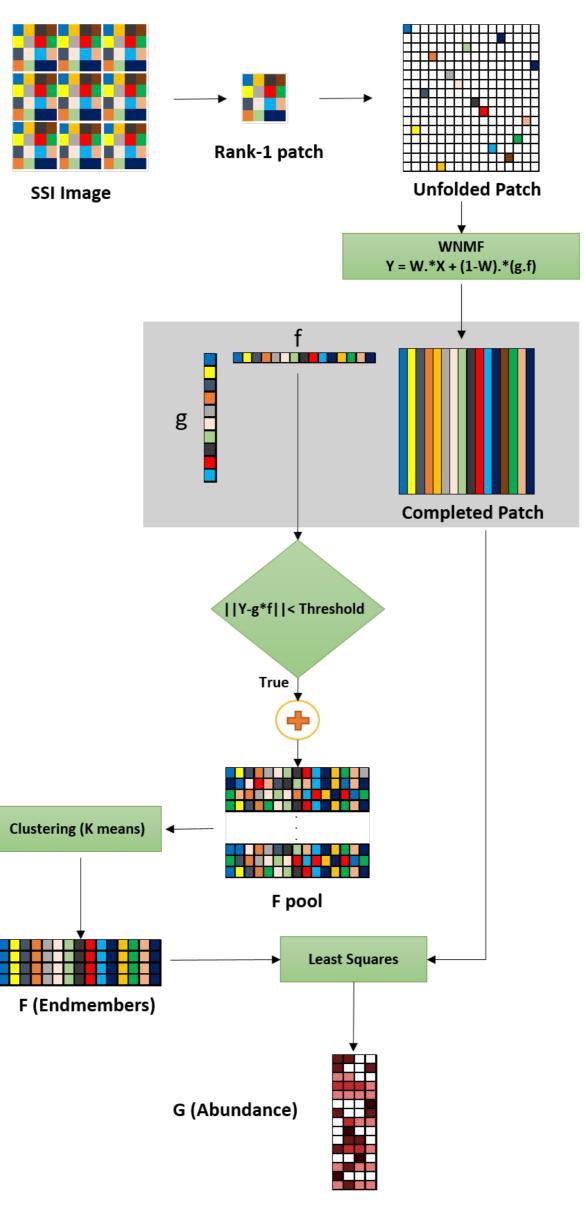
 $\hat{Y} = W \circ X + (\mathbb{1}_{(m \cdot n) \times k} - W) \circ (G \cdot F),$

(1)

- ► W denotes a binary weight matrix whose nonzero entries allow to select which wavelength is observed by the camera in the case of ideal filter.
- ► W denotes the contributions of each wavelength in the observed wavelength in the case of the real filter.
- Can be solved using Expectation Maximization WNMF framework [3].

Proposed Low-rank Completion-Based Method

- Patch-based rank-1 completion WNMF method (KPWNMF) [4]
 - Assumes some local abundance sparsity
 - Finds locally rank-1 patches which correspond to almost "pure patches" Assumption recently relaxed [5]



- wavelength of interest in real implementation.
- These filters are known and are provided by the camera manufacturers.
- Our proposed method takes these harmonics into consideration.

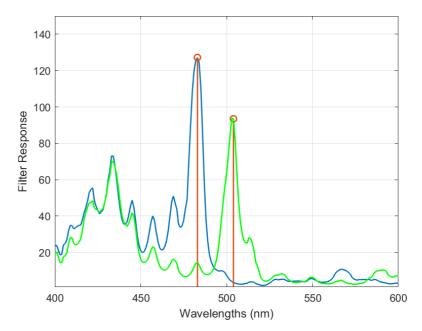


Figure: Ideal (in red) and real (in blue and green) spectral response of two Fabry-Perot filters of the 4×4 IMEC SSI camera.

Experiment and Results

- ► To validate the performance of the proposed approach, we conduct an experiment on Jasper Ridge image.
- ► We assume that the hyperspectral imagery is acquired using a SSI camera system, equipped with 5×5 and 4×4 spectral filter patterns.
- Simulations assuming an ideal and real snapshot mosaic filters.
- Reconstruction quality is measured in terms of Peak Signal-to-Noise Ratio (PSNR, in dB) while the unmixing enhancement is measured using Signal-to-Interference Ratio (SIR, in dB).
- Far better unmixing performance reached by our proposed approach than with 2-stage techniques and naive WNMF
- Still demosaicing similar or slightly better than SotA methods

Conclusion and Future Work

- The proposed method provides a slightly better demosaicing performance than state-of-the-art methods and a much higher unmixing enhancement.
- ► We aim to investigate the use of our proposed methods on real SSI data.

Figure: Principles of the two-step (in green) and joint (in red) strategies.

- \triangle Performing classification after demosaicing provides a poor classification performance [1]
- ▶ In [2], joint low-rank matrix completion and factorization far more accurate than a two-stage approach.
- Joint Demosaicing and Unmixing more efficient than a two-stage approach?

We also aim to extend them to the case when endmember spectral variability is met in the acquisition process.

Acknowledgements and References

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