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Handling model risk with XVAs*

Cyril Bénézet[†] Stéphane Crépey[‡]

August 26, 2024

Abstract

In this paper we revisit Burnett (2021) & Burnett and Williams (2021)'s notion of hedging valuation adjustment (HVA), originally intended to deal with dynamic hedging frictions such as transaction costs, in the direction of model risk. The corresponding HVA reconciles a global fair valuation model with the local models used by the different desks of the bank. Model risk and dynamic hedging frictions indeed deserve a reserve, but a risk-adjusted one, so not only an HVA, but also a contribution to the KVA of the bank. The orders of magnitude of the effects involved suggest that local models should not so much be managed via reserves, as excluded altogether.

Keywords: pricing models, model risk, calibration, transaction costs, cross valuation adjustments (XVAs).

Mathematics Subject Classification: 91B26, 91G20, 91G30, 91G40, 91G60, 91G70.

JEL Classification: D52, G13, G24, G28, G32, G33.

Introduction

Cross Valuation Adjustments (XVAs) The financial landscape has undergone significant transformation over the past few decades, particularly in the realm of counterparty risk management. Initially, the focus was on modeling and quantifying counterparty credit risk through credit valuation adjustment (CVA), which captures the market value of counterparty credit risk by considering potential future exposures and the likelihood of counterparty default (see e.g. Duffie and Singleton (1999)). However,

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the financial crisis of 2008 highlighted severe deficiencies in risk management frameworks, revealing the complexities of interconnected financial risks.

In the aftermath of the crisis, regulatory bodies implemented more stringent collateral and capital requirements to address these shortcomings. This led to the emergence of funding valuation adjustment (FVA, see e.g. Burgard and Kjaer (2011, 2013); Pallavicini, Perini, and Brigo (2011)) and capital valuation adjustment (KVA, see e.g. Green, Kenyon, and Dennis (2014), Albanese, Caenazzo, and Crépey (2016)). FVA accounts for the cost of funding uncollateralized trades, reflecting the funding spreads a financial institution incurs due to its own default risk. KVA represents the cost of holding capital against potential future losses, acknowledging the economic impact of regulatory capital requirements.

These valuation adjustments (XVAs) are complex and nonlinear, requiring aggregation at different levels. CVA can be calculated at the level of individual client relationships, considering the entire book of transactions with each counterparty. FVA and KVA can only be validly assessed at the portfolio level of the entire bank, encompassing all positions and the interplay of various risk factors across the institution.

Model Risk In the cost-of-capital XVA approach of Albanese, Crépey, Hoskinson, and Saadeddine (2021) and Crépey (2022), the market is assumed to be frictionless and no model risk is envisioned. In line with the Volcker rule that prevents proprietary trading by banks, the market risk is assumed perfectly hedged, the focus being on credit, funding, and capital risks. However, a perfect hedging strategy from a wrong model bears material market risk. In this work, we introduce model risk (paramount in recent structured products crises) and frictions (found particularly material for cross gamma CVA hedging in Burnett and Williams (2021)) within a comprehensive XVAs framework. In particular, the present paper provides an answer to Bichuch, Capponi, and Sturm (2020), who notes that the baseline cost-of-capital XVA approach “assumes that the counterparty-free payoffs of the contract are perfectly replicated, rather than designing the replication strategy from first principles (and ignoring potential interaction of risk factors)”.

Model risk is traditionally managed by reserving the price difference between outputs from low and high-quality models. This approach involves adjusting valuations to account for price discrepancies and ensuring that reserves are held against potential model inaccuracies. However, low-quality models are still used to compute hedging strategies, leading to incorrect hedging ratios relative to higher quality models.

For discussions on model risk and associated regulatory guidelines until 2014, we refer to Detering and Packham (2016) and references therein, including Karoui, Jeanblanc-piqué, and Shreve (1998), Cont (2006), Elices and Giménez (2013), and to Farkas, Fringuellotti, and Tunaru (2020), who propose a method to account for model risk in capital requirements related to market risk. Bartl, Drapeau, Obloj, and Wiesel (2021) address model risk by considering worst-case pricing and hedging with uncertainty in a Wasserstein ball around a reference probability measure. However, while the price is robust, the associated hedge remains imperfect. The model risk specific to XVA computations is also considered in the literature. Bichuch et al. (2020) and Silotto, Scaringi, and Bianchetti (2021) consider parameters uncertainty. Singh and

Zhang (2019b,a) consider uncertainty around a reference probability measure in the Wasserstein distance, in a discrete time setting and for a finitely supported reference measure.

But under none of the above references, reserve is held against the impact of model risk on hedging strategies. In the present work, we revisit Burnett (2021) & Burnett and Williams (2021)'s notion of hedging valuation adjustment (HVA), originally intended to deal with dynamic hedging frictions, in the direction of model risk. We argue and demonstrate numerically that the impact of model risk on hedging strategies can be very significant and deserves an adequate reserve, considered in addition to pricing adjustments. This reserve materializes as a contribution to the KVA of the bank. We also consider, similar to Burnett (2021) and Burnett and Williams (2021), a reserve against the market frictions induced by the practical implementation of dynamic hedging strategies. These two reserves — for market frictions and for the impact of model risk on hedging ratios — can only be computed at an aggregated level of deals, similarly to CVA, FVA and KVA computations as explained above, making an XVAs approach natural for this purpose.

Outline of the Paper We work in a continuous time probabilistic setup $(\Omega, \mathcal{A}, \mathfrak{F} = (\mathfrak{F}_t)_{t \in [0, \bar{T}]}, \mathbb{R})$ with a finite time horizon $\bar{T} > 0$, interpreted as the final maturity of a bank's portfolio, assessed on a runoff basis as standard in XVA computations. The risk-free asset is chosen as the numéraire. Until the concluding section of the paper, the bank and its counterparties are assumed to be default-free. We assume that all deals are European. For an integrable optional process $\mathcal{Y} = (\mathcal{Y}_t)_{t \in [0, \bar{T}]}$ starting at 0, interpreted as a cumulative cash-flow process associated with a deal, we define its value process $Y = va(\mathcal{Y})$ by:

$$Y_t = \mathbb{E}_t [\mathcal{Y}_{\bar{T}} - \mathcal{Y}_t], \quad t \in [0, \bar{T}], \quad (0.1)$$

where \mathbb{E}_t is the conditional expectation operator with respect to \mathfrak{F}_t under the probability distribution \mathbb{R} . Here \mathbb{R} is the hybrid of pricing and physical probability measures defined in (Artzner et al., 2024, Proposition 4.1), advocated in Albanese et al. (2021, Remark 2.3) for XVA computations. In particular, $Y + \mathcal{Y}$ is a martingale.

But our approach considers a dual-model environment: on one side, the global fair valuation model (or reference model as advocated for model risk assessment in Barrieu and Scandolo (2015)), in which prices are value processes as per (0.1); on the other side, local trade-specific models used by traders. Due to the use of local models, the raw profit-and-loss process pnl of the bank, defined as the sum of the profit-and-losses associated with each individual deal and of the friction costs associated with each hedging set, is not a martingale in the fair valuation model. From an XVA viewpoint, this deviation from a martingale necessitates a risk-adjusted reserve, so that the adjusted profit-and-loss process of the bank $pnl - (HVA - HVA_0) - (KVA - KVA_0)$ becomes a submartingale in line with a remuneration of the shareholders of the bank at some hurdle rate r (e.g. 10%). Here HVA is the value process of $-pnl$, so that $\mathcal{L} := -pnl + HVA - HVA_0$ is a martingale, while KVA is the cost of capital, sized on the fluctuations of \mathcal{L} .

Exploiting the linearity of the fair valuation operator, the HVA/KVA computation can be split at different aggregation levels. This leads to three layers of valuation

adjustments: the first layer, denoted HVA^{mtm} , is computed at the level of individual deals (i.e. no aggregation). The second layer, denoted HVA^f , is computed at the level of hedging sets (i.e. sets of deals that are hedged together), leading to $HVA = HVA^{mtm} + HVA^f$. The third layer, the KVA, can only be computed at the level of the bank's portfolio as a whole. More specifically, we introduce in this work:

1. **The first layer HVA (price adjustment, Section 1):** This layer compensates the loss process associated with a deal, ensuring it becomes a martingale under the global valuation model. This adjustment accounts for the model risk inherent in transitioning from local models to fair valuation. It corresponds to a model risk reserve as per current market practice, reserving the local model pricing gaps related to the asset and its static hedging component (see Proposition 1.1 and Remark 1.4).
2. **The second layer HVA (cost of market frictions, Section 2):** This layer addresses nonlinear market frictions induced by the dynamic hedging strategies associated with individual deals. Deals are hedged collectively to exploit netting benefits, reducing market frictions such as transaction costs, though these costs may still be significant. The valuation of these costs constitutes our second HVA layer, generalizing the original HVA defined by Burnett (2021) & Burnett and Williams (2021), also accounting for model risk. With these two HVA layers, the bank's loss process \mathcal{L} is a martingale.
3. **The third layer HVA (KVA risk adjustment, Section 3):** Despite the price adjustments from the first two HVA layers, hedging ratios remain computed within the local models, leading to material losses. The third HVA layer is defined as the KVA associated with \mathcal{L} . This layer accounts for the cost of holding capital against exceptional losses induced by the incorrect hedges.

So far this is all restricted to market risk. The last section of the paper introduces additional first layer HVA components related to credit and funding risks, thus incorporating the HVA into the global valuation framework of Albanese et al. (2021) and Crépey (2022), and concludes.

1 First Layer HVA: HVA for Individual Deals

1.1 Abstract Framework

This section introduces our dual-model setup.

For each deal contracted between the bank and a counterparty, the bank uses a local custom pricing model to price and hedge the deal. This holds up until a stopping time, at which the trader starts using the fair valuation model (for instance because the local model is no longer usable as it non longer calibrates to the market, represented in our setup by the fair valuation model). Under this model risk specification, the associated raw pnl of the trader is not a martingale, and we then introduce the first layer HVA as its martingale compensator.

Definition 1.1. We fix a generic European deal of the bank, denoted by “.”, with maturity T . The corresponding raw pnl is given, for all $t \geq 0$, by

$$pnl_t = \mathcal{Q}_t + q_t \mathbf{1}_{\{t < \tau_s\}} + Q_t \mathbf{1}_{\{t \geq \tau_s\}} - q_0 - (\mathcal{P}_t + p_t \mathbf{1}_{\{t < \tau_s\}} + P_t \mathbf{1}_{\{t \geq \tau_s\}} - p_0) - h_t, \quad (1.1)$$

where

- \mathcal{Q} denotes the cumulative cash flow process received by the bank from the client through the deal, while \mathcal{P} denotes the cumulative cash flow process paid by the bank to the hedging market through a static hedging component (with \mathcal{P} and \mathcal{Q} both assumed stopped at T),
- q (resp. p) is the price of the deal (resp. of its static hedging component), computed by the trader of the bank from a local pricing model used for pricing and hedging the deal until the stopping time τ_s , denoted model switch time,
- $Q = va(\mathcal{Q})$ (resp. $P = va(\mathcal{P})$) is the fair valuation price of the deal (resp. of its static hedging component), used by the trader of the bank from time τ_s onwards,
- h is the loss process associated to the dynamic hedging component of the deal, ignoring transaction costs.

Since h is a dynamic hedging loss, it should be thought about as a stochastic integral against the hedging instruments, all assumed European-style and without dividends, so that their prices are martingales in the global valuation model. A natural assumption regarding h is then:

Assumption 1.2. h is a zero-valued martingale, i.e. $va(h) = 0$.

Remark 1.1. We do not assume a frictionless market, but since numerous deals are hedged together inside “hedging sets” by the bank, market frictions such as transaction costs can only be addressed at the hedging set level, which will be the topic of Section 2.

Given a deal “.” the fair valuations Q and P , being value processes of cash flow processes stopped at T , vanish on $[T, \infty)$. Likewise, a natural assumption on the local prices is then:

Assumption 1.3. On $\{\tau_s > T\}$, the processes q and p vanish on $[T, +\infty)$.

The key observation here is that the raw pnl process pnl is not a martingale under the fair valuation model (unless $q = Q$ and $p = P$). We now define the contribution of a deal and its hedge to the first layer HVA and, eventually, the first layer HVA for all deals, by linearity.

Definition 1.4. For each deal “.”, its contribution to the first layer HVA is given by

$$\text{HVA} := -va(pnl), \quad (1.2)$$

i.e. $(-pnl + \text{HVA})$ is a martingale and $\text{HVA} = 0$ on $[T, +\infty)$. The first layer HVA is defined by

$$\text{HVA}^{mtm} := \sum \text{HVA} = -va(pnl^{mtm}), \quad (1.3)$$

where $pnl^{mtm} = \sum pnl$.

Remark 1.2. Without model risk, if the bank was only using the fair valuation model, then the pnl associated to the deal “.” would simply be the martingale $pnl^{,*}$ defined, for all $t \geq 0$, by

$$pnl_t^{,*} := \mathcal{Q}_t + Q_t - Q_0 - (\mathcal{P}_t^{,*} + P_t^{,*} - P_0^{,*}) - h_t^{,*}, \quad (1.4)$$

and the associated HVA would be zero. Note that the processes $\mathcal{P}^{,*}, P^{,*}, p^{,*}$ and $h^{,*}$ are *a priori* different from \mathcal{P}, P, p, h , as the former would be derived in the setup of the fair valuation model, while the latter rely on a local pricing model.

Remark 1.3. (i) If the trader is not willing or unable to use the fair valuation model, the bank may consider liquidating the deal at τ_s . To render this case, one just needs to stop the process pnl at τ_s .

(ii) One could consider products with knock-out features. In that case, one would need to introduce an additional stopping time (deactivation time) τ_e , and to stop pnl at τ_e .

(iii) We could also consider American or game claims with exercise times possibly $< T$ under the control of the bank and/or client, in which case τ_e as above should be understood as the corresponding exercise time. Further adjustments are then required to deal with possibly suboptimal stopping by the bank (suboptimal stopping by the client can be conservatively ignored in the modeling). These adjustments are the topic of Benezet, Crépey, and Essaket (2022). In the present paper we assume no early exercise features.

Regarding this first layer HVA, one can perform explicit computations, showing that it corresponds to the price difference between the two model prices.

Proposition 1.1. *Under Assumptions 1.2-1.3, for each deal “.”, we have, for all $t \geq 0$,*

$$\text{HVA}_t = (q_t - Q_t - (p_t - P_t)) \mathbb{1}_{\{t < \tau_s\}}. \quad (1.5)$$

Proof. From (1.1), one gets, for all $t \geq 0$,

$$pnl_t = \mathcal{Q}_t + Q_t + (q_t - Q_t) \mathbb{1}_{\{t < \tau_s\}} - (\mathcal{P}_t + P_t + (p_t - P_t) \mathbb{1}_{\{t < \tau_s\}}) - h_t.$$

By linearity of the $va(\cdot)$ operator, since (by definition) $\mathcal{Q} + Q, \mathcal{P} + P$ and (by Assumption 1.2) h are martingales, we obtain from (2.1)-(1.2), for all $t \geq 0$,

$$\begin{aligned} \text{HVA}_t &= -\mathbb{E}_t [(q_T - Q_T) \mathbb{1}_{\{T < \tau_s\}} - (p_T - P_T) \mathbb{1}_{\{T < \tau_s\}}] + \\ &\quad (q_t - Q_t) \mathbb{1}_{\{t < \tau_s\}} - (p_t - P_t) \mathbb{1}_{\{t < \tau_s\}}, \end{aligned}$$

which implies (1.5), as $Q_T = P_T = 0$ and $q_T = p_T = 0$ on $\{T < \tau_s\}$, by Assumption 1.3. \square

Remark 1.4. HVA corresponds to the current market practice for handling model risk in the form of a reserve put aside at initial time. In actual practice, rather than paying q_0 to the client (as implied by (1.1)) while the client would provide HVA_0 as reserve capital to the bank, the trader pays Q_0 to the client and puts by himself HVA_0 in the reserve capital account, which is equivalent (at least if $P = p$, as then $\text{HVA}_0 = q_0 - Q_0$).

1.2 The Vulnerable Put Example

1.2.1 Financial Model

We consider a financial derivative on a stock S , dubbed vulnerable put, whereby the bank is long the payoff $(K - S_T)^+ \mathbb{1}_{\{S_T > 0\}}$ at some maturity T , for some strike K (with $T, K, S \geq 0$). Using the notations introduced in Definition 1.1, we have here

$$T = T, \mathcal{Q}_t = (K - S_T)^+ \mathbb{1}_{\{S_T > 0\}} \mathbb{1}_{t \geq T}.$$

With dividend yields on S and interest rates in the economy set to 0, we assume the global valuation model defined as the jump-to-ruin (jr) model

$$dS_t = \lambda S_t dt + \sigma S_t dW_t - S_{t-} dN_t = \sigma S_t dW_t - S_{t-} dM_t, \quad t \geq 0, \quad (1.6)$$

for some standard Brownian motion W , a constant volatility parameter $\sigma > 0$, and $M = N - \lambda t$, where N is a Poisson process of intensity $\lambda > 0$. So the stock S jumps to 0 at the first jump time θ of the driving Poisson process N . Hence, for $t \geq 0$,

$$Q_t = va(\mathcal{Q})_t = Q_t^{jr} := \mathbb{E}_t [(K - S_T)^+ \mathbb{1}_{\{T < \theta\}}] \mathbb{1}_{\{t < T\}}. \quad (1.7)$$

The role of the local pricing model will be played by a Black-Scholes (bs) model with volatility parameter Σ continuously recalibrated to the jump-to-ruin price

$$P_t^{jr} := \mathbb{E}_t [(K - S_T)^+] \mathbb{1}_{\{t < T\}}, \quad t \geq 0 \quad (1.8)$$

of the “vanilla component” of the vulnerable put, with payoff $(K - S_T)^+$ at time T . The vulnerability of the vulnerable put is immaterial in this bs model, hence the local model price q_t of the vulnerable put coincides with the vanilla put price P_t^{jr} . We also define $\tau_s^* := \theta$. Indeed, an application of the formula (A.8) for $S = 0$ and $-d_{\pm} = +\infty$ shows that $P^{jr} = K$ on $[\theta, \theta \wedge T]$. As detailed in Remark A.1, at time θ (if $< T$), the implied volatility of the vanilla put ceases to be well-defined, hence the local pricing model cannot be used anymore.

Remark 1.5. In this example, which is devised for the sake of analytical tractability, the trader is short an extreme (default) event but pretends he does not see it, only hedging market risk. Hence the hedged position is still short the default event, which can be seen as an extreme case of “gamma negative” type position. The (Darwinian, as per Albanese, Crépey, and Iabichino (2021)) model risk mechanism here at hand is essentially the same as the one affecting huge amounts of structured derivative products, including range accruals in the fixed-income world, autocallables and cliquets on equities, or power-reversal dual currency options and target redemption forwards on foreign-exchange: cf. <https://www.risk.net/derivatives/6556166/remembering-the-range-accrual-bloodbath> (11 April 2019, last accessed on 19 June 2024). Risk.net thus reported that Q4 of 2019, a \$70bn notional of range accrual had to be unwound at very large losses by the industry.

1.2.2 First Layer HVA for a Static Hedging Scheme

We first consider a static hedging scheme. The trader uses at time $t = 0$ the local (bs) pricing model, in which the vulnerability of the put is immaterial: from the bs model viewpoint, shorting the vanilla put is a perfect hedge to the vulnerable put and no dynamic hedging is required. In the notation of Definition 1.1, this corresponds, for all $t \geq 0$, to $h_t \equiv 0$ and

$$\begin{aligned}\mathcal{P}_t &= (K - S_T)^+ \mathbb{1}_{t \geq T}, \\ p_t &= P_t = va(\mathcal{P})_t = P_t^{jr} \text{ as per (1.8)}.\end{aligned}\tag{1.9}$$

The equality $p = P$ implies that the local pricing model is continuously recalibrated (before the ruin time θ) to the vanilla put fair valuation P^{jr} , as explained after (1.8).

Applying (1.1) and (1.5), we compute, for all $t \geq 0$,

$$\begin{aligned}pnl_t &= -K \mathbb{1}_{\{\theta \leq t\}} \mathbb{1}_{\{\theta \leq T\}}, \\ HVA_t &= \mathbb{1}_{\{t < \theta\}} (P_t^{jr} - Q_t^{jr}) = J^\theta K (1 - e^{-\lambda(T-t)}),\end{aligned}\tag{1.10}$$

where, to compute pnl , we used that $Q_t - P_t = -K \mathbb{1}_{\{\theta \leq T \leq t\}}$, $p_t = q_t = P_t^{jr}$ on $\{t < \theta\}$, and $Q_t = 0, P_t = K$ on $\{\theta \leq t < T\}$. The raw pnl process in (1.10) and the corresponding compensated (by $HVA - HVA_0$) pnl satisfy, for $t \geq 0$,

$$\begin{aligned}dpnl_t &= -K \mathbb{1}_{\{t \leq T\}} \delta_\theta(dt) = \mathbb{1}_{\{t \leq \theta \wedge T\}} (-\lambda K dt - (K dN_t - \lambda K dt)) \\ dpnl_t - dHVA_t &= K \mathbb{1}_{\{t \leq \theta \wedge T\}} e^{-\lambda(T-t)} (\lambda dt - \delta_\theta(dt)),\end{aligned}\tag{1.11}$$

where δ_θ denotes the Dirac measure at time θ .

Remark 1.6. Consistently with the qualitative features of Darwinian model risk in Albanese et al. (2021), the seemingly positive drift $\mathbb{1}_{\{t \leq \theta \wedge T\}} \lambda K e^{-\lambda(T-t)} dt$ in the second line is only the compensator of the loss $-\mathbb{1}_{\{t \leq \theta \wedge T\}} K e^{-\lambda(T-t)} dN_t$ that hits the bank in case the jump-to-ruin event materializes. Hence the trader makes systematic profits in the short to medium term, followed by a large loss at the model switch time.

Numerical Application For $\lambda = 1\%$, $T = 10y$ and $K = 1$, (1.10) yields

$$HVA_0 = K(1 - e^{-0.1}) \approx 0.095.\tag{1.12}$$

1.2.3 First Layer HVA for a Dynamic Hedging Scheme

We now consider a dynamic delta hedging scheme. The trader delta hedges the vulnerable put with the stock S and the risk-free asset, in his local bs pricing model and until time θ , and there is no static hedging. In the notation of Definition 1.1, we have, for all $t \geq 0$,

$$\mathcal{P}_t = P_t = p_t \equiv 0 \text{ and } h_t = \int_0^{t \wedge \theta} \Delta_{s-}^{bs} dS_s,\tag{1.13}$$

where $\Delta_t^{bs} = \mathcal{N}(-d_-(t, S_t; 0, \Sigma_t))$, in which \mathcal{N} is the standard normal cumulative distribution function, is the delta of the vulnerable put computed in the local pricing

model: cf. the Black-Scholes formula for puts and (A.2). Note that, in this setting, dynamic hedging friction costs could be considered, namely transaction costs, which will be done in Section 2.5.

From (1.1) and (1.5), we compute, for $t \geq 0$,

$$\begin{aligned} pnl_t &= \mathbb{1}_{\{\theta > T\}} \mathbb{1}_{\{t \geq T\}} (K - S_T)^+ + \mathbb{1}_{\{t < \theta\}} P_t^{jr} - P_0^{jr} - h_t, \\ HVA_t &= \mathbb{1}_{\{t < \theta\}} (P_t^{jr} - Q_t^{jr}) = \mathbb{1}_{\{t < \theta\}} K(1 - e^{-\lambda(T-t)}). \end{aligned} \quad (1.14)$$

The raw pnl in (1.14), satisfies, for $0 \leq t < \theta$,

$$dpnl_t = \delta_T(dt)(K - S_T)^+ + dP_t^{jr} - \delta_t dS_t,$$

whereas at θ (if $\leq T$) the bank incurs a loss

$$\begin{aligned} pnl_\theta - pnl_{\theta-} &= -P_{\theta-}^{jr} + h_{\theta-} - h_\theta = -P_{\theta-}^{bs} + \Delta_{\theta-}^{bs}(S_{\theta-} - S_\theta) \\ &= -P_{\theta-}^{bs} + \Delta_{\theta-}^{bs} S_{\theta-} = -K\mathcal{N}(-d_-(\theta, S_{\theta-}; 0, \Sigma_{\theta-})) < 0. \end{aligned} \quad (1.15)$$

Numerical Application In the above example, while the static hedge is perfect before θ and the continuous-time delta hedge is not (due to the continuous recalibration of the local pricing model), one observes a smaller loss at $\theta < T$ in the delta hedging case:

$$P_{\theta-}^{jr} - \Delta_{\theta-}^{bs} S_{\theta-} = K\mathcal{N}(-d_-(\theta, S_{\theta-}; 0, \Sigma_{\theta-})) \leq K = P_{\theta-}^{bs},$$

cf. (1.15), the first identity in (1.11), and the left panel in Figure 2.1.

Remark 1.7. The statically hedged position is delta and vega neutral. Hence our vulnerable put example yields a case where delta-vega hedging the option actually increases model risk with respect to delta-hedging it only.

2 Second Layer HVA: HVA for Dynamic Hedging Frictions

2.1 Abstract Framework

As already hinted in Remark 1.1, the above processes h are meant for standard dynamic hedging cash flows ignoring frictions such as transaction costs. Indeed, as these are nonlinear, they can only be addressed at the level of a hedging set “ \star ”, i.e. a book of contracts that are hedged together. In this section we consider the cost associated with the dynamic hedging frictions, assessed at the level of each hedging set “ \star ”, leading to a corresponding contribution to the second layer HVA. We then define by linearity the second layer HVA considering all the hedging sets.

Definition 2.1. For each hedging set “ \star ”, we consider its associated dynamic hedging frictions process f^\star . The corresponding contribution to the second layer HVA is given by

$$\text{HVA}^\star = va(f^\star), \quad (2.1)$$

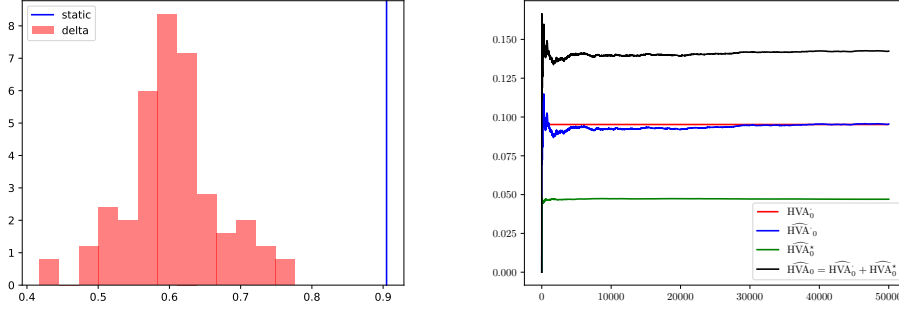


Figure 2.1: Vulnerable put example: **[left]** the red histogram is the density of $-pnl_1 + HVA_1 - HVA_0$ conditional on model switch occurring before time 1, i.e. on $\{0 < \theta \leq 1\}$, for delta hedging (without frictions at this stage). The vertical blue line corresponds to the deterministic loss $-pnl_1 + HVA_1 - HVA_0 = K + HVA_1 - HVA_0$ for static hedging, also conditional on $\{0 < \theta \leq 1\}$. The numerical parameters are as above (1.12). Note that, in both cases, $HVA_1 - HVA_0 = 0 - K(1 - e^{-\lambda T}) \simeq -0.095$ holds on $\{0 < \theta \leq 1\}$. **[right]** Monte-Carlo approximation of HVA_0 and HVA_0^* .

i.e. $(f^* + HVA^*)$ is a martingale and $HVA^* = 0$ on $[\bar{T}, +\infty)$.

The second layer HVA of the bank is defined by

$$HVA^f := \sum_{\star} HVA^{\star} = va(f), \quad (2.2)$$

where $f = \sum_{\star} f^*$.

A specification of the friction process f^* associated to the hedging set " \star " is necessary to compute the associated HVA^* for frictions. Hereafter we derive such a specification by passage to the continuous-time limit starting from a classical discrete-time specification. This sheds more rigor in the seminal contribution of Burnett (2021), who derives a PDE for the transaction costs at the limit, while only rebalancing when the delta of the underlying portfolio is shifted by a fixed and constant threshold $D > 0$ (so it seems that Burnett (2021)'s limiting HVA should increase at discrete rebalancing times only, rather than being given by a PDE). Our approach also allows computing HVA^* numerically in a model risk setup accounting for the impact of recalibration on transaction costs, which is not considered in Burnett (2021).

2.2 Fair Valuation Setup

In this section we work in the setup of the following fair valuation model $\mathcal{X} = (X, J)$ (stated under the probability measure \mathbb{R}):

$$\begin{aligned} dX_t &= \mu(t, \mathcal{X}_t)dt + \sigma(t, \mathcal{X}_t)dW_t, \\ dJ_t &= \sum_{j=1}^L (j - J_{t-})d\nu_t^j, \quad \lambda_t^j = \lambda_j(t, \mathcal{X}_{t-}), \end{aligned} \quad (2.3)$$

where W is a multivariate Brownian motion and ν_t^j is the number of transitions of the “Markov chain like” component J to the state j on $(0, t]$, with compensated martingale $d\nu_t^j - \lambda_t^j dt$ of ν^j . Jumps could also be introduced in X but we refrain from doing so for notational simplicity. This setup encompasses the jr fair valuation model in our vulnerable put example. It also includes XVA models, with room for client default indicator processes in the J components of \mathcal{X} , as required in view of our extension of the setup in the concluding section of the paper.

We assume that the function-coefficients μ, σ, λ are continuous maps such that the above-model is well-posed, referring to Crépey (2013, Proposition 12.3.7) for a set of explicit assumptions ensuring it. In particular:

- Assumption 2.2.** (i) The maps λ_j , $1 \leq j \leq L$, are bounded by a constant $\Lambda \geq 0$.
(ii) The map $(t, x, j) \mapsto (\mu, \sigma)(t, x, j)$ is Lipschitz in $x \in \mathbb{R}^d$, uniformly in (t, j) , and the map $(t, j) \mapsto (\mu, \sigma)(t, 0, j)$ is bounded.

Hence (see e.g. Élie (2006, (II.83) page 123)) there exists a constant $C_1 \geq 0$ such that

$$\mathbb{E} \left[|X_t - X_s|^2 \right]^{\frac{1}{2}} \leq C_1 (t - s)^{\frac{1}{2}}. \quad (2.4)$$

In addition, for all $1 \leq l \leq d$,

$$C^l := \sup_{t \in [0, T]} \mathbb{E} \left[(X_t^l)^2 \right]^{\frac{1}{2}} < +\infty. \quad (2.5)$$

2.3 Transaction Costs For Discrete Rebalancing

We assume that a trader values a hedging set “ \star ” as $q_t^\star = q^\star(t, \mathcal{X}_t)$, for some smooth map q^\star , and that the trader delta-hedges its position with respect to the d -dimensional risky asset X , discretely at the times of the uniform grid $(ih)_{0 \leq i \leq n}$ with $h = \frac{T^\star}{n}$ for some $n \geq 1$, where $T^\star \leq T$ is the final maturity of this hedging set.

Remark 2.1. More generally, one can consider delta-hedging only with respect to some components of X . It is actually what we will do in Section 2.5 while delta-hedging in Black-Scholes with respect to \tilde{S} only in $\mathcal{X} = (\tilde{S}, \Sigma; \mathbf{1}_{[0, \theta)})$ there (see (A.1) and (2.11)). The extension is straightforward, as it is (at least for our purpose) equivalent to considering no transaction costs for those non-delta-hedged assets, i.e. setting the corresponding diagonal entries of \mathbf{k} to 0 below.

We work in a setting similar to Kabanov and Safarian (2009, Chapter 1, Section 2), with proportional transaction costs scaled to the rebalancing time by a factor \sqrt{h} , where h is the time interval between two rebalancing dates.

Remark 2.2. In their case, scaling proportional transactions costs by h^α , with $\alpha \in (0, \frac{1}{2}]$, allows showing, in the Black and Scholes model, that perfect replication of a vanilla call can be achieved in the limit as the number of rebalancing dates goes to infinity, by delta-hedging the portfolio’s value computed with a modified volatility. In our case, scaling the transaction costs by \sqrt{h} allows passing to the continuous time limit and deriving the dynamics of the transaction costs and the PDE for the HVA * with trading indeed occurring continuously, and not only along a sequence of stopping times as in Burnett (2021).

Abbreviating ∂_{x_l} into ∂_l , let $a_t = (a_t^l)_{1 \leq l \leq d}$ with $a_t^l = \partial_l q^*(t, \mathcal{X}_t)$, $0 \leq t \leq T^*$, $1 \leq l \leq d$.

Assumption 2.3. The cost to rebalance the hedging portfolio from $a = (a^l)_{1 \leq l \leq d}$ at time t into $a + \delta a = (a^l + \delta a^l)_{1 \leq l \leq d}$ at time $t + h$ is $X_{t+h}^\top \delta a + \frac{1}{2} X_{t+h}^\top \mathbf{k} (\delta a)^{\text{abs}} \sqrt{h}$, where $(\delta a)^{\text{abs}} := (|\delta a_l|, 1 \leq l \leq d)$ and $\mathbf{k} := \text{diag}(k_l, 1 \leq l \leq d)$ for some constants $k_l \geq 0$, $1 \leq l \leq d$.

The transaction costs are thus proportional to the risky asset prices (measured in units of the risk-free numéraire asset). In the context of proportional transaction costs, Assumption 2.3 is classical (Kabanov and Safarian, 2009, page 8).

Remark 2.3. Unless there is no Markov-chain-like component J in \mathcal{X} , the replication hedging ratios in setups such as (2.3) also involve finite differences (as opposed to partial derivatives only in the above): see e.g. Proposition A.4. However practitioners typically only use partial derivatives as their hedging ratios, motivating the present framework, which encompasses in particular the use-case of Section 3.4.

The discrete-time hedging valuation adjustment for frictions (HVA^h) is then a process compensating the bank (on average) for these transaction costs.

Definition 2.4. The HVA for frictions associated to discrete hedging along the time-grid $(ih)_{0 \leq i \leq n}$ is defined as the (nonnegative) process HVA^h such that HVA^h_{nh} = 0 and, for $0 \leq i < n$,

$$\begin{aligned} \text{HVA}_{ih}^h &= \mathbb{E}_{ih} \left[f_{nh}^h - f_{ih}^h \right] = \\ & \mathbb{E}_{ih} \left[f_{(i+1)h}^h - f_{ih}^h + \text{HVA}_{(i+1)h}^h \right] = \mathbb{E}_{ih} \left[\varphi_{(i+1)h}^h + \text{HVA}_{(i+1)h}^h \right], \end{aligned} \quad (2.6)$$

where $f_{ih}^h = \sum_{u=0}^i \varphi_{uh}^h$, with

$$\begin{aligned} \varphi_{ih}^h &= \frac{\sqrt{h}}{2} X_{ih}^\top \mathbf{k} (\delta a_{ih})^{\text{abs}}, \quad 0 < i < n, \quad \varphi_0^h = \varphi_{nh}^h = 0, \\ \text{and } (\delta a_{ih})^{\text{abs}} &= (|a_{ih}^l - a_{(i-1)h}^l|, 1 \leq l \leq d). \end{aligned}$$

Remark 2.4. We neglect the transaction costs at time $t = 0$, given by (assuming $d = 1$ for simplicity) $\sqrt{h} \frac{k}{2} X_0 |a_0 - a_{0-}|$ (where a_{0-} is the initial quantity of risky asset possessed before entering the deal), and at time $t = T^* = nh$, given by $\sqrt{h} \frac{k}{2} X_{T^*} |a_{(n-1)h}|$ (to liquidate the hedging portfolio).

2.4 Transaction Costs in the Continuous-Time Rebalancing Limit

The results of this part specify the cumulative friction costs f^* and the ensuing HVA^{*} that arise in the above setup when the rebalancing frequency of the hedge goes to infinity, i.e. when $h \rightarrow 0$.

Definition 2.5. For all $t \in [0, T^*]$, let $\varphi_t := \varphi(t, \mathcal{X}_t)$ with, for all $(t, x, j) \in [0, T^*] \times \mathbb{R}^d \times \{1, \dots, L\}$,

$$\varphi(t, x, j) = \frac{1}{\sqrt{2\pi}} x^\top \mathbf{k} (\Gamma \sigma)^{\text{abs}}(t, x, j), \quad (2.7)$$

where $(\Gamma\sigma)^{\text{abs}} := (|\partial_x(\partial_l q^*)\sigma|, 1 \leq l \leq d)$. Let then $f_t^* = \int_0^t \varphi_s ds$ and

$$\text{HVA}_t^* = va(f^*)_t = \mathbb{E}_t \left[\int_t^{T^*} \varphi_s ds \right]. \quad (2.8)$$

Note that the map HVA^* defined by $\text{HVA}^*(t, x, j) := \mathbb{E}[\text{HVA}_t^* | \mathcal{X}_t = (x, k)]$ solves the PDE

$$\begin{aligned} \text{HVA}^*(T^*, \cdot) &= 0 \text{ on } \mathbb{R} \times \{1, \dots, L\}, \\ (\partial_t + \mathcal{G})\text{HVA}^* + \varphi &= 0 \text{ on } [0, T^*) \times \mathbb{R} \times \{1, \dots, L\}, \end{aligned} \quad (2.9)$$

where we denote, for any smooth map $u = u(t, x, j)$, $\mathcal{G}u = \mathcal{F}u + \sum_{j=1}^L (u(\cdot, j) - u) \lambda_k$, with $\mathcal{F}u := \partial_t u + \partial_x u \mu + \frac{1}{2} \text{tr} [\sigma \sigma^\top \partial_{x^2}^2 u]$, in which ∂_x is the row-gradient with respect to x , $\partial_{x^2}^2$ the Hessian matrix with respect to x , and tr is the trace operator.

We make the following technical hypotheses on the local valuation map q^* :

Assumption 2.6. (i) There exists $0 < \alpha < \frac{1}{2}$ such that, for all $1 \leq l \leq d$ and $1 \leq j \leq L$, the maps $(t, x) \mapsto \partial_l q^*(t, x, j)$ and $(t, x) \mapsto (\partial_x(\partial_l q^*))\sigma(t, x, j)$ are α -Hölder continuous in t and Lipschitz continuous in x ;

(ii) There exists $C_2 > 0$ such that, for any $u \in \{\partial_l q^*, \partial_x(\partial_l q^*)\sigma \mid 1 \leq l \leq d\}$,

$$\sup_{(t, x, j, j')} |u(t, x, j) - u(t, x, j')| \leq C_2 < \infty;$$

(iii) $\sup_{t \in [0, T^*]} \mathbb{E} \left[|(\partial_t + \mathcal{F})(\partial_l q^*)(t, \mathcal{X}_t)|^2 \right]^{\frac{1}{2}} \leq C_2 < \infty, 1 \leq l \leq d.$

Theorem 2.1. We set $\text{HVA}_t^h := \text{HVA}_{\lfloor \frac{t}{h} \rfloor h}^h, 0 \leq t \leq T^*$. Under Assumptions 2.2, 2.3 and 2.6, we have (almost surely)

$$\text{HVA}_t^h \xrightarrow{h \rightarrow 0} \text{HVA}_t^*, 0 \leq t \leq T^*.$$

Proof. see Section B.

Note that (2.8) would be virtually impossible to implement without the connection to HVA^h provided by the underlying discrete setup: transaction costs with model risk are a case where the approximation to a limiting problem in continuous time is problematic unless one knows where the limiting problem is coming from in the first (discrete) place. But Theorem 2.1 is interesting from a theoretical viewpoint and important in practice to guarantee the meaningfulness (stability for small h) of the numbers HVA_t^h to be computed numerically based on (2.6).

2.5 HVA^f for the Vulnerable Put Under the Delta Hedging Scheme

Continuing in the setup of Sections 1.2.1 and 1.2.3, regarding frictions, we assume (unrealistically but with some genericity as explained in Remark 1.5) the bank portfolio reduced to the vulnerable put and its dynamic delta-hedge in S (with $T^* = T$ in particular). We are thus in the setup of Sections 2.5–2.4 with $\mathcal{X} = (\tilde{S}, \Sigma; \mathbb{1}_{[0, \theta)})$, where \tilde{S} is the auxiliary Black-Scholes model (A.1), and $q^* = P^{bs}(t, S; \Sigma)$, the price of the vanilla put with strike K and maturity T in the Black and Scholes model with volatility Σ , with associated hedge ratio $\mathbb{1}_{\{t \leq \theta\}} \Delta_{t-}^{bs}$, where $\Delta_t^{bs} = \partial_S P^{bs}(t, S_t; \Sigma_t)$.

Corollary 2.2. *Assume that trading is permitted only at the discrete dates ih , $1 \leq i \leq n$, with $h = \frac{T}{n}$ (for any $n \geq 1$). Assume further that implementing the delta hedging strategy triggers a cumulative cost at time ih induced by proportional transaction costs, hence a discrete-time hedging valuation adjustment for frictions, respectively given by, for $0 \leq i \leq n$,*

$$f_{ih}^h := \sum_{j=1}^i k \frac{\sqrt{h}}{2} S_{jh} \left| \mathbb{1}_{\{jh \leq \theta\}} \Delta_{jh-}^{bs} - \mathbb{1}_{\{(j-1)h \leq \theta\}} \Delta_{(j-1)h-}^{bs} \right|, \quad (2.10)$$

$$\text{HVA}_{ih}^h := \mathbb{E}_{ih} \left[f_{nh}^h - f_{ih}^h \right].$$

Then, as h goes to 0, the discrete HVA for frictions $\text{HVA}_{\lfloor \frac{t}{h} \rfloor h}^h$ converges almost surely to $\text{HVA}^f = va(f)$ on $[0, T]$, for the process f such that

$$df_t = \mathbb{1}_{\{t \leq \theta\}} \frac{k}{\sqrt{2\pi}} S_t \left| \sigma \Gamma_{t-}^{bs} + \varsigma_t \partial_{\Sigma, S}^2 P^{bs}(t, S_{t-}; \Sigma_{t-}) \right| dt, \quad (2.11)$$

where $\Gamma_t^{bs} = \partial_{S^2}^2 P^{bs}(t, S_t; \Sigma_t) \geq 0$, while ς is the diffusion coefficient of the implied volatility process Σ .

Proof. By application of Theorem 2.1 (cf. (2.7)) with $\mathcal{X} = (\tilde{S}, \Sigma; \mathbb{1}_{[0, \theta)})$ and $k_1 = k \geq 0$, $k_2 = 0$ (as the position is not "delta-hedged" with respect to Σ in the jr model, see Remark 2.1). \square

Interestingly, the cost of delta-hedging in the bs model computed within the jr model also depends on the derivative of the delta with respect to the implicit volatility, or implied "vanna", $\partial_{\Sigma, S}^2 P^{bs}$. This comes from the continuous recalibration of the trader's model to the fair valuation of the vanilla put. Because of this impact of recalibration into transaction costs, (2.11) would be quite demanding to implement directly, whereas its discrete counterpart (2.10) is rather straightforward (the consistency between the two being insured by Corollary 2.2).

Numerical Application The numerical parameters are the same as above (1.12), along with $S_0 = K = 1$ and $\sigma = 0.3$, and with $k = 0.1$ in (2.11). We perform Monte-Carlo simulations with $M = 50,000$ paths to estimate $\text{HVA}_0^h = \mathbb{E} [f_{nh}^h]$ as per (2.6)-(2.10), for a monthly time-discretization, i.e. $n = 120$ and $h = \frac{T}{n} = \frac{1}{12}$. As a sanity check, we also price by Monte Carlo HVA_0 already known from (1.14) and (1.12). We can see from the right panel in Figure 2.1, where the horizontal red line corresponds to $\text{HVA}_0 = 1 - e^{-0.1}$, that HVA_0^h dominates HVA_0^f .

3 Third Layer HVA: Risk-adjustment

3.1 Abstract Framework

After compensation by the first layer HVA, the price is right (cf. Remark 1.4), but the hedge is still wrong (as, for each deal " \cdot ", before τ_s^i , the hedging ratios are computed

using the local pricing model and not the fair valuation one). Under a cost-of-capital valuation approach, the reserve for model risk and dynamic hedging frictions would not reduce to the first and second layers HVA, but this reserve should also be risk-adjusted. This leads to the third layer HVA that we introduce in this section.

Accounting for raw pnls, hedging frictions, and their associated HVA compensators (first and second layers HVA), we obtain the overall trading loss of the bank given as the martingale \mathcal{L} defined by, for all $t \geq 0$,

$$\begin{aligned}\mathcal{L}_t &= pnl_t + HVA_t - HVA_0 \\ &= -pnl_t^{mtm} + HVA_t^{mtm} - HVA_0^{mtm} + f_t + HVA_t^f - HVA_0^f,\end{aligned}\tag{3.1}$$

with $pnl := -pnl^{mtm} + f$ and $HVA := HVA^{mtm} + HVA^f$.

The reserves for model risk and dynamic hedging frictions will now be risk-adjusted. Namely, the volatile swings of \mathcal{L} due to model risk and transaction costs should be reflected in the economic capital and the cost of capital of the bank. The corresponding theory now proceeds as in Albanese et al. (2021) and Crépey (2022). The regulator expects that some capital, no less than a theoretical economic capital (EC) level, should be reserved to cover the exceptional (i.e. beyond average, which is in fact zero, thanks to the first two HVA layers) losses over the next year. Namely:

Definition 3.1. The economic capital (EC) of the bank is defined as the time- t conditional expected shortfall ($\mathbb{E}\mathcal{S}_t$) of the random variable $(\mathcal{L}_{t'} - \mathcal{L}_t)$ at some confidence level $\alpha \in (\frac{1}{2}, 1)$, where \mathcal{L} is the trading loss process of the bank and $t' = (t + 1) \wedge \bar{T}$, i.e.

$$\text{EC}_t = \mathbb{E}\mathcal{S}_t(\mathcal{L}_{t'} - \mathcal{L}_t) := \frac{\mathbb{E}_t((\mathcal{L}_{t'} - \mathcal{L}_t)\mathbb{1}_{\{\mathcal{L}_{t'} - \mathcal{L}_t \geq \text{VaR}_t(\mathcal{L}_{t'} - \mathcal{L}_t)\}})}{\mathbb{E}_t\mathbb{1}_{\{\mathcal{L}_{t'} - \mathcal{L}_t \geq \text{VaR}_t(\mathcal{L}_{t'} - \mathcal{L}_t)\}}},\tag{3.2}$$

in which VaR_t denotes the time- t conditional value-at-risk of level α .

The capital valuation adjustment (KVA) is then defined as the level of a risk margin required for remunerating the shareholders of the bank, dynamically at a constant and nonnegative hurdle rate $r \geq 0$ of their capital at risk. Since the KVA, which is paid by the clients of the bank, is also loss-absorbing (as a risk margin), hence part of capital at risk, the latter is given by $\max(\text{EC}, \text{KVA})$, while *shareholder* capital at risk only corresponds to $\text{SCR} = \max(\text{EC}, \text{KVA}) - \text{KVA} = (\text{EC} - \text{KVA})^+$, Accordingly:

Definition 3.2. The third layer HVA is defined as the capital valuation adjustment (KVA), itself defined by the inductive relation

$$\text{KVA}_t := r \mathbb{E}_t \int_t^{\bar{T}} (\text{EC}_s - \text{KVA}_s)^+ ds, \quad t \leq \bar{T}.\tag{3.3}$$

Equivalently, the KVA process vanishes at \bar{T} and turns the cumulative dividend process $-(\mathcal{L} + \text{KVA} - \text{KVA}_0)$ of the bank shareholders into a submartingale with drift coefficient $r \times \text{SCR}$. By standard Lipschitz BSDE results, assuming EC square integrable, (3.3) defines a unique square integrable KVA process Crépey (2022, Proposition B.1).

3.2 Additional Valuation Adjustment

We propose to compare the valuation adjustments (first, second and third layer HVAs summing up to $HVA^{mtm} + HVA^f + KVA$ as per (1.3)-(2.2)-(3.3)) to what would be obtained if the bank was only using the fair valuation model. The difference is what we call additional valuation adjustment (AVA, or model risk component thereof, cf. European Parliament (2013), European Parliament (2016) and see also <https://www.eba.europa.eu/regulation-and-policy/market-risk/draft-regulatory-technical-standards-on-prudent-valuation>).

As already noticed in Remark 1.2, if there was no model risk, i.e. if the bank was using the fair valuation model for all its purposes, then HVA^{mtm} would be identically zero. The first and second layer HVAs would thus reduce to a second layer HVA à la Burnett (2021) & Burnett and Williams (2021), the way detailed in Section 2 (but without model risk), still triggering a third layer HVA (KVA) as per Section 3.1. Moreover, using the fair valuation model for all purposes by the bank would also imply different and presumably much better hedges, triggering much less volatile swings of \mathcal{L} than the ones implied by local models, hence in turn much lower economic capital and KVA. One would then obtain a baseline (*) $HVA^{f,*} + KVA^*$ defined by equations (2.2)-(3.3), but for pnl^* defined by (1.4) instead of (1.1), and where $HVA^{f,*}$ is the second layer HVA associated to the dynamic hedging strategies leading to $h^{f,*}$ in (1.4). An additional valuation adjustment (AVA) could thus be defined as the difference

$$AVA = HVA^{mtm} + HVA^f + KVA - (HVA^{f,*} + KVA^*). \quad (3.4)$$

As a dealer bank should not do proprietary trading, the reference hedging case is when $pnl^{f,*} \equiv 0$ in (1.4). In that situation, the overall trading loss of the bank is the minimalistic (compare with (3.1))

$$\mathcal{L}^* = f^* + HVA^{f,*}, \quad (3.5)$$

which could be taken as a reference for defining EC^* and KVA^* via (3.2)-(3.3) and in turn the AVA via (3.4). After the introduction of the HVA and its risk adjustment in the KVA, the use of bad quality local models should imply a positive AVA in (3.4). Better models would imply a smaller AVA, hence an increased competitiveness for the bank. Our AVA thus provides a measure of the shortfall for a bank, in terms of additional KVA costs, by not using better models. Computing it could virtuously incite banks to use higher quality models. For that, however, there is no *economic* necessity for a bank of computing a baseline $HVA^{f,*} + KVA^*$, nor of identifying the corresponding AVA. All that matters economically is that the bank passes to its clients the total add-on $HVA^{mtm} + HVA^f + KVA = (HVA^{f,*} + KVA^*) + AVA$, by (3.4) (so $HVA^{mtm} + HVA^f + KVA$ encompasses $HVA^{f,*} + KVA^*$ and the AVA).

We now derive the KVA (3.3) associated with the two hedging schemes of the vulnerable put in Section 1.2, to come on top of HVA^f computed in Section 1.2.2 for the static hedging scheme and of HVA^f and HVA^* computed in Sections 1.2.3 and 2.5 for the delta hedging scheme. These computations are done under the assumption that the bank portfolio would solely consist of the vulnerable put and its hedge, but this

(even though unrealistic) situation has also some genericity as explained in Remark 1.5.

3.3 KVA for the Vulnerable Put Under the Static Hedging Scheme

Regarding the static hedging scheme of Section 1.2.2, one can derive explicit EC and KVA formulas:

Proposition 3.1. *Denoting $\Theta = (T + \frac{\ln(\alpha)}{\lambda})^+ \leq T$, where α is the confidence level at which economic capital is calculated, and by r the hurdle rate of the bank, we have, for all $t \geq 0$, $\widetilde{\text{EC}}_t = \mathbb{1}_{\{t < \theta\}} \widetilde{\text{EC}}_t$ and $\widetilde{\text{KVA}}_t = \mathbb{1}_{\{t < \theta\}} \widetilde{\text{KVA}}_t$, where*

$$\begin{aligned}\widetilde{\text{EC}}_t &= \mathbb{1}_{\lambda > -\ln(\alpha)} \mathbb{1}_{\{t < \Theta\}} K e^{-\lambda(T-t)}, \\ \widetilde{\text{KVA}}_t &= \mathbb{1}_{\lambda > -\ln(\alpha)} K e^{-\lambda(T-t)} \mathbb{1}_{\{t < \Theta\}} (1 - e^{-r(\Theta-t)}), \\ \text{KVA}_0 &= \mathbb{1}_{\lambda > -\ln(\alpha)} K e^{-\lambda T} \mathbb{1}_{\Theta > 0} (1 - e^{-r\Theta}).\end{aligned}\tag{3.6}$$

Proof. For $t < t' \leq T$, (3.1) and the last line in (1.10) yield

$$\begin{aligned}\mathcal{L}_{t'} - \mathcal{L}_t &= (-pnl' + \text{HVA}')_{t'} - (-pnl + \text{HVA})_t \\ &= \mathbb{1}_{\{t' \geq \theta > t\}} K + \mathbb{1}_{\{t' < \theta\}} K (1 - e^{-\lambda(T-t')}) - \mathbb{1}_{\{t < \theta\}} K (1 - e^{-\lambda(T-t)}) \\ &= \mathbb{1}_{\{t < \theta\}} \left(\mathbb{1}_{\{t' \geq \theta\}} (K - K(1 - e^{-\lambda(T-t')})) + K(1 - e^{-\lambda(T-t')}) - K(1 - e^{-\lambda(T-t)}) \right) \\ &= \mathbb{1}_{\{t < \theta\}} B_{t'}^t, \text{ where } B_{t'}^t = \mathbb{1}_{\{t' \geq \theta\}} K e^{-\lambda(T-t')} + K(e^{-\lambda(T-t)} - e^{-\lambda(T-t')}).\end{aligned}$$

On $\{t < \theta\}$, the Bernoulli random variable $\mathbb{1}_{\{t' \geq \theta\}}$ satisfies $\mathbb{E}_t [\mathbb{1}_{\{t' \geq \theta\}} = 0] = e^{-\lambda(t'-t)}$ and, for any confidence level $\alpha > e^{-\lambda(t'-t)}$, i.e. such that $t' - t > \frac{-\ln(\alpha)}{\lambda}$, $\mathbb{V}a\mathbb{R}_t(\mathcal{L}_{t'} - \mathcal{L}_t)$ is the largest of the two possible values of $(\mathcal{L}_{t'} - \mathcal{L}_t)$, so that the latter never exceeds $\mathbb{V}a\mathbb{R}_t(\mathcal{L}_{t'} - \mathcal{L}_t)$. As a consequence, for $t' - t > \frac{-\ln(\alpha)}{\lambda}$, we have by (3.2):

$$\begin{aligned}\mathbb{E}\mathbb{S}_t(\mathcal{L}_{t'} - \mathcal{L}_t) &= \mathbb{V}a\mathbb{R}_t(\mathcal{L}_{t'} - \mathcal{L}_t) = \\ &= \mathbb{1}_{\{t < \theta\}} (K e^{-\lambda(T-t')} + K(e^{\lambda(T-t)} - e^{-\lambda(T-t')})) = \mathbb{1}_{\{t < \theta\}} K e^{-\lambda(T-t)}.\end{aligned}$$

For $t' - t \leq \frac{-\ln(\alpha)}{\lambda}$, we have

$$(\mathcal{L}_{t'} - \mathcal{L}_t) \mathbb{1}_{\{\mathcal{L}_{t'} - \mathcal{L}_t \geq \mathbb{V}a\mathbb{R}_t(\mathcal{L}_{t'} - \mathcal{L}_t)\}} = \mathcal{L}_{t'} - \mathcal{L}_t,$$

which is a time- t conditionally centered random variable as the increment of the martingale \mathcal{L} . Hence

$$0 = \mathbb{E}_t(\mathcal{L}_{t'} - \mathcal{L}_t) = \mathbb{E}_t((\mathcal{L}_{t'} - \mathcal{L}_t) \mathbb{1}_{\{\mathcal{L}_{t'} - \mathcal{L}_t \geq \mathbb{V}a\mathbb{R}_t(\mathcal{L}_{t'} - \mathcal{L}_t)\}}) = \mathbb{E}\mathbb{S}_t(\mathcal{L}_{t'} - \mathcal{L}_t).$$

Setting $t' = (t+1) \wedge T$ as prescribed in (3.2) (for $\bar{T} = T$ here), so that $t' - t > \frac{-\ln(\alpha)}{\lambda} \Leftrightarrow t < \Theta$, we obtain by Definition 3.1:

$$\text{EC}_t = \mathbb{E}\mathbb{S}_t(\mathcal{L}_{t'} - \mathcal{L}_t) = \mathbb{1}_{\{t < \theta\}} \mathbb{1}_{\lambda > -\ln(\alpha)} \mathbb{1}_{t < \Theta} K e^{-\lambda(T-t)},$$

which is the first line in (3.6).

Assuming $\lambda > -\ln(\alpha)$ (otherwise $\text{EC} = \text{KVA} = 0$), let us define the process

$$\text{KVA}_t^\dagger := r \mathbb{E}_t \int_t^T e^{-r(u-t)} \text{EC}_u du = r \mathbb{E}_t \int_t^T (\text{EC}_s - \text{KVA}_s^\dagger) ds, \quad t \leq T. \quad (3.7)$$

We have

$$\begin{aligned} \text{KVA}_t^\dagger &= rK \mathbb{E}_t \mathbb{1}_{\{t < \Theta\}} \int_t^\Theta e^{-r(u-t)} \mathbb{1}_{\{u < \theta\}} e^{-\lambda(T-u)} du \\ &= rK e^{-\lambda(T-\Theta)} \mathbb{1}_{\{t < \Theta\}} \mathbb{1}_{\{t < \theta\}} \int_t^\Theta e^{-r(u-t)} e^{-\lambda(u-t)} e^{-\lambda(\Theta-u)} du \\ &= \mathbb{1}_{\{t < \theta\}} rK e^{-\lambda(T-\Theta)} e^{-\lambda(\Theta-t)} \mathbb{1}_{\{t < \Theta\}} \int_t^\Theta e^{-r(u-t)} du \\ &= \mathbb{1}_{\{t < \theta\}} K e^{-\lambda(T-t)} \mathbb{1}_{t < \Theta} (1 - e^{-r(\Theta-t)}) \leq \mathbb{1}_{\{t < \theta\}} K \mathbb{1}_{t < \Theta} e^{-\lambda(T-t)} = \text{EC}_t. \end{aligned} \quad (3.8)$$

Back to the right-hand side in (3.7), the process KVA^\dagger therefore satisfies

$$\text{KVA}_t^\dagger = r \mathbb{E}_t \int_t^T (\text{EC}_s - \text{KVA}_s^\dagger) ds = r \mathbb{E}_t \int_t^T (\text{EC}_s - \text{KVA}_s^\dagger)^+ ds, \quad t \leq T, \quad (3.9)$$

which is the KVA equation (3.3). As EC and KVA^\dagger are bounded processes, hence, by the result recalled after Definition 3.2, KVA^\dagger is the unique bounded (or even square integrable) solution to this equation, i.e. $\text{KVA}^\dagger = \text{KVA}$. The first identity in the last line of (3.8) then yields the second line in (3.6). \square

For a baseline (*) setup (cf. Section 3.2) corresponding to dynamic, assumed frictionless, replication of the vulnerable put by the stock and the vanilla put in the jr model as per Proposition A.4, we have $\text{HVA}^{f,*} + \text{KVA}^* = 0$, hence the AVA (3.4) reduces to $\text{HVA} + \text{KVA}$.

Numerical Application For $\lambda = 1\%$, $T = 10y$ and $r = 10\%$, (3.6) and (1.10) yield as $\alpha \downarrow e^{-0.01} \approx 99\%$:

$$\begin{aligned} \text{KVA}_0 \downarrow & K e^{-0.1} (1 - e^{-1+0.1}) \approx 0.54K \\ \frac{\text{KVA}_0}{\text{HVA}_0} \downarrow & \frac{(1 - e^{-0.9})}{(e^{0.1} - 1)} \approx 5.64. \end{aligned} \quad (3.10)$$

In the present case where $f = 0$ and a pure frictions HVA^f à la Burnett (2021) & Burnett and Williams (2021) vanishes, playing with the jump-to-ruin intensity λ in Figure 3.1, we see from the top panels that the first layer HVA alone can be extreme. As visible on the bottom panels of Figure 3.1, the corresponding KVA adjustment can be even several times larger. The latter holds for $\alpha > e^{-\lambda}$. For $\alpha \leq e^{-\lambda}$, instead, there is no tail risk at the envisioned confidence level, hence $\text{EC} = \text{KVA} = 0$.

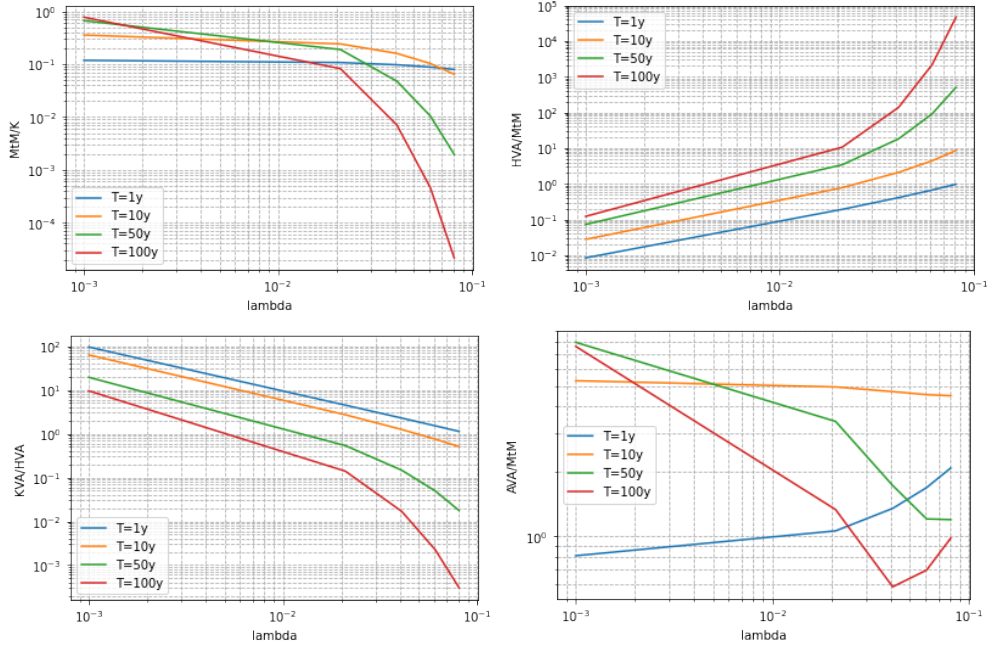


Figure 3.1: At-the-money $S_0 = K$, denoting $\text{MtM}_0 = Q_0^{jr}$ and assuming $\alpha \downarrow e^{-\lambda}$ everywhere in the bottom panels (where the limiting value of the confidence level α that underlies the KVA therefore depends of the abscissa λ): **[top left]** $\frac{\text{MtM}_0}{K}$; **[top right]** $\frac{\text{HVA}_0}{\text{MtM}_0}$; **[bottom left]** $\frac{\text{KVA}_0}{\text{HVA}_0}$; **[bottom right]** $\frac{\text{AVA}_0}{\text{MtM}_0}$.

3.4 KVA For the Vulnerable Put Under the Dynamic Hedging Scheme

In the dynamic hedging case of Section 1.2.3, we rely on numerical approximations to estimate the economic capital and the KVA of the bank at a quantile level α set in the numerics to 99%. In fact, in this Markovian framework, each process $Z = \text{HVA}^f, \text{EC}, \text{VaR}(\mathcal{L}' - \mathcal{L})$ and KVA satisfies, for all $t \geq 0$,

$$Z_t = \widetilde{Z}(t, S_t) = \mathbf{1}_{\{t < \theta\}} \widetilde{Z}(t, \widetilde{S}_t),$$

where \widetilde{S} is the auxiliary Black-Scholes model (A.1) and $\widetilde{\text{HVA}}^f(t, 0) = \widetilde{\text{VaR}}(t, 0) = \widetilde{\text{EC}}(t, 0) = \widetilde{\text{KVA}}(t, 0) = 0$, while, for all $(t, S) \in [0, T] \times (0, \infty)$, setting $t' = (t + 1) \wedge T$,

$$\begin{aligned} \widetilde{\text{HVA}}^f(t, S) &= \mathbb{E}[f_T - f_t | S_t = S], \\ \widetilde{\text{VaR}}(t, S) &= \text{VaR}[\mathcal{L}_{t'} - \mathcal{L}_t | S_t = S], \\ \widetilde{\text{EC}}(t, S) &= \mathbb{E}S[\mathcal{L}_{t'} - \mathcal{L}_t | S_t = S], \\ \widetilde{\text{KVA}}(t, S) &= r \mathbb{E} \left[\int_t^T (\text{EC}_u - \text{KVA}_u)^+ du \mid S_t = S \right]. \end{aligned} \tag{3.11}$$

On this basis, one can obtain approximations $\widehat{\text{HVA}}^f, \widehat{\text{EC}}$, and $\widehat{\text{KVA}}$ of the HVA^f, EC , and KVA processes at all nodes of a forward simulated grid $(S_{t_k}^m)_{0 \leq k \leq 10}^{1 \leq m \leq M}$ of S , by neural

net regressions and quantile regressions that are used backward in time for solving the above equations numerically, the way detailed in Section C.

Numerical application We plot on Figure 3.2 the processes $\widehat{EC}(\cdot, \tilde{S})$ and $\widehat{KVA}(\cdot, \tilde{S})$ represented by the term structures of their means (in green) and quantiles of levels 10%, 90% (in blue) and 2.5% and 97.5% (in red), both with and without frictions f , as well as in the (deterministic) static hedging case (3.6). In particular, we obtain in the dynamic hedging case for the same numerical parameters as the ones used in Section 2.5, a confidence level α for the EC computations set at 99%, and a hurdle rate r for the KVA computations set at 10%:

$$\begin{aligned} \widehat{HVA}_0 &\simeq 0.095 \text{ and } \widehat{HVA}_0^f \simeq 0.046, \text{ hence } \widehat{HVA}_0 = \widehat{HVA}_0 + \widehat{HVA}_0^f \simeq 0.141, \\ \widehat{KVA}_0 &\simeq 0.407, \frac{\widehat{KVA}_0}{\widehat{HVA}_0} \simeq 2.881. \end{aligned} \tag{3.12}$$

As could be expected from Remark 1.7, there is ultimately less risk (as assessed by economic capital and KVA, cf. (1.12) and Figure 3.2) with the delta hedge than with the static, aka delta-vega hedge.

In the frictionless case $f = 0$, we obtain by the same methodology

$$\begin{aligned} \widehat{HVA}_0 &= \widehat{HVA}_0 \simeq 0.095, \\ \widehat{KVA}_0 &\simeq 0.433, \frac{\widehat{KVA}_0}{\widehat{HVA}_0} \simeq 4.550. \end{aligned} \tag{3.13}$$

In view of (3.12) (see also Figure 3.2), the dynamic hedging frictions happen to be risk-reducing in this case, meaning that the components $-pnl^{mtm} + HVA^{mtm} - HVA_0^{mtm} = -pnl + HVA - HVA_0$ and $f + HVA^f - HVA_0^f$ of (3.1) are negatively correlated.

Conclusion

Executive Summary (Encompassing Credit): A Global Valuation Framework In the model-risk-free and frictionless XVA setup of Albanese et al. (2021) and Crépey (2022), pnl^{mtm} is a zero-valued martingale and $f = 0$, hence $HVA^{mtm} = HVA^f = 0$. In this paper, the loss process (3.14) also incorporates model risk (in pnl^{mtm}) and market frictions (in f), whence nontrivial first and second layers HVA. The process HVA^{mtm} can be seen as the bridge between a global fair valuation model and the local models used by the different desks of the bank. The reserve for model risk and transaction costs is then risk-adjusted by the Third HVA Layer, namely a KVA component, where the KVA is defined from (3.1) (or more generally (3.14) below) by (3.2)-(3.3).

Accounting methods are also models in the sense of SR-11-7 (cf. <https://www.federalreserve.gov/supervisionreg/srletters/sr1107.htm>) because they produce numbers, are based on assumptions, and have an impact on strategies. If they are misaligned with economics they cause a misalignment of interests between executives and shareholders. Hence, model risk is a concept that does not apply only to pricing models, but

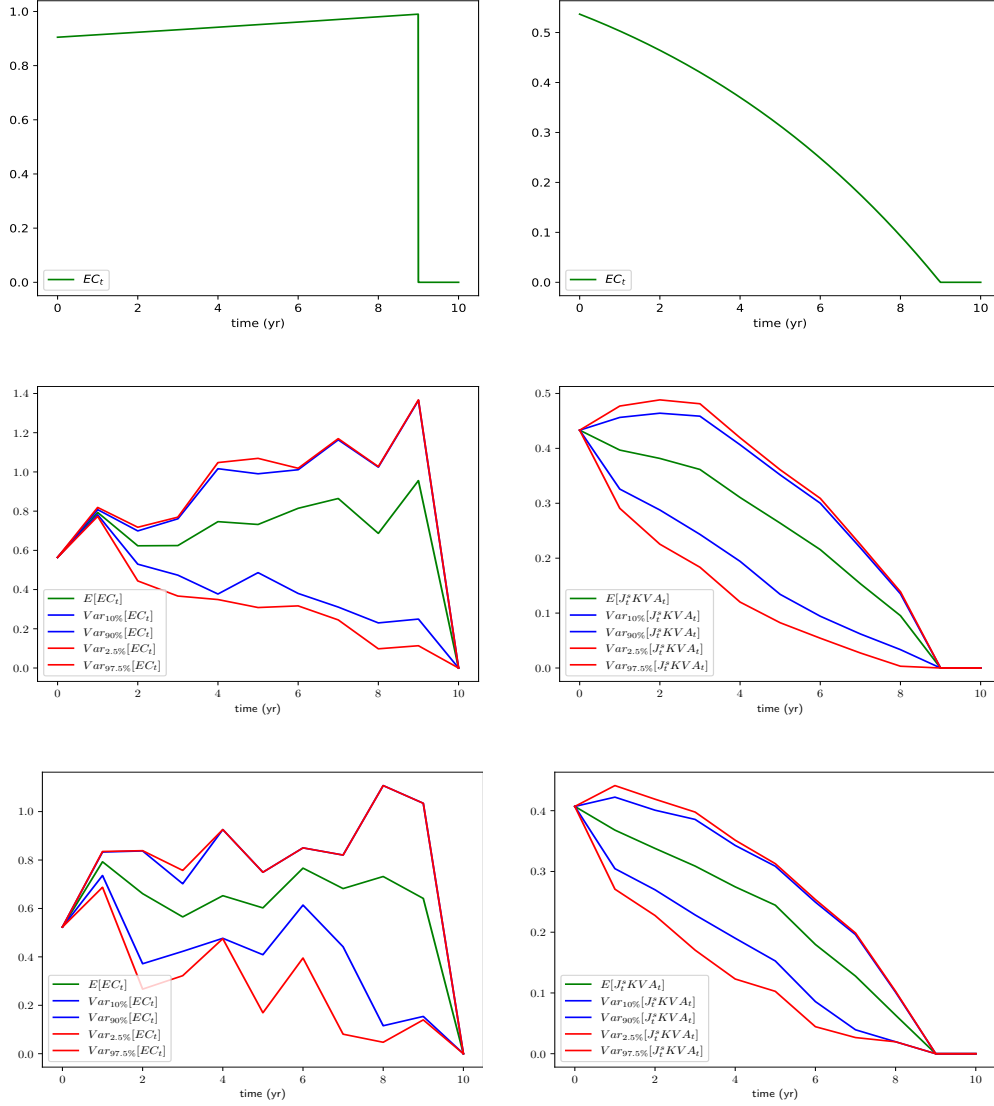


Figure 3.2: Plot of the deterministic maps $t \mapsto \widetilde{EC}(t)$ [top left] and $t \mapsto \widetilde{KVA}(t)$ [top right] corresponding to the static hedging case (3.6). Plots of mean (in green) and quantiles at levels 10% and 90% (in blue) and 2.5% and 97.5% (in red) of $\widehat{EC}(t, \tilde{S}_t)$ in the delta hedging case without friction [Middle left] and in the delta hedging case with frictions [bottom left]. Plots of mean (in green) and quantiles at levels 10% and 90% (in blue) and 2.5% and 97.5% (in red) of $\widehat{KVA}(t, \tilde{S}_t)$ in the delta hedging case without friction [Middle right] and in the delta hedging case with frictions [bottom right].

should be extended to accounting principles for dealer banks, including the specification of their CVA and FVA metrics (as these are liabilities to the bank, see Crépey (2022, Section 1) and Albanese et al. (2021, Figure 1)). From this model risk perspective, the CVA and FVA should be viewed as two additional “giant trades” of the bank with associated raw pnl^{cva} and pnl^{fva} , deserving first layer HVA contributions in the same way as individual deals “.” in the paper. Denoting these contributions by HVA^{cva} and HVA^{fva} , the first layer HVA becomes $HVA^{mtm} + HVA^{cva} + HVA^{fva}$. The overall loss trading process of the bank accounting for market, credit and funding risks is given by the martingale \mathcal{L} defined, for all $t \geq 0$, by (compare with (3.1))

$$\begin{aligned} \mathcal{L}_t = & -pnl_t^{mtm} + HVA_t^{mtm} - HVA_0^{mtm} - pnl_t^{cva} + HVA_t^{cva} - HVA_0^{cva} \\ & - pnl_t^{fva} + HVA_t^{fva} - HVA_0^{fva} + f_t + HVA_t^f - HVA_0^f. \end{aligned} \quad (3.14)$$

In this defaultable extension of the theory, the probability measure under which all equations are stated becomes the bank survival probability measure associated with \mathbb{R} in the sense of Albanese et al. (2021, Section 4) (see also Crépey (2022, Section B) for a practically equivalent reduction of filtration viewpoint). In addition, similarly to the extensions mentioned in the first two items of Remark 1.3, for each deal “.”, the associated raw pnl process pnl should be stopped at τ_d^i , the positive default time of the counterparty of the deal (the default of the bank itself being absorbed in the above-mentioned switch to its survival measure).

Regarding its KVA computations, a bank could also be subject to model risk: to enhance its competitiveness in the short term, a bank might be tempted to use a model understating the risk and economic capital of the bank. A sound practice in this regard is to combine different, equally valid (realistic and co-calibrated) models for simulating the set of trajectories underlying the economic capital and KVA computations (Albanese et al., 2023, Section 4.3). Such a Bayesian KVA approach typically fattens the tails of the simulated distributions and avoids under-stated risk estimates.

Take-Away Message: Bad Models Should Be Banned not Managed In this paper we revisit Burnett (2021) & Burnett and Williams (2021)’s notion of hedging valuation adjustment (HVA) in the direction of model risk. The fact evidenced by Example 1.7 that vega hedging may actually increase model risk illustrates well that model risk cannot be hedged. It can only be provisioned against or, preferably, compressed by improving the quality of the models used by traders. In any case, a provision for model risk should be risk-adjusted. But, as the paper illustrates, a risk-adjusted reserve would be much greater than the “HVA uptick” (price difference) currently used in banks, by a factor 3 to 5 in our experiments (cf. Remark 1.4 and (3.12)-(3.13)), and it could be even more if one accounted for the price impact of a liquidation in extreme market conditions (cf. <https://www.risk.net/derivatives/6556166/remembering-the-range-accrual-bloodbath> effects already mentioned in Remark 1.5). Risk-adjusted HVA computations are also very demanding. In particular, beyond analytical toy examples such as the one of Section 3.3 (and already in the case of Section 3.4), HVA risk-adjusted KVA computations require dynamic recalibration in a simulation setup, for assessing the hedging ratios used by the traders at future time points as well as the time of explosion of the trader’s strategy (time of model switch τ_s^i). Hence, from

the computational workload viewpoint too, the best practice would be that banks only rely on high-quality models, so that such computations are simply not needed.

In conclusion, the orders of magnitude of the corrections that would be required for duly compensating model risk (accounting not only for misvaluation but also for the associated mishedge), as well as the corresponding computational burden for a precise assessment of the latter, suggest that bad models should not so much be managed via reserves, as excluded altogether.

A Pricing Equations in the Jump-to-Ruin Model

In this section we provide pricing analytics in the jr model (1.6) for S , with jump-to-ruin time (first jump time of N) θ . We also consider the auxiliary Black-Scholes model

$$d\tilde{S}_t = \lambda\tilde{S}_t dt + \sigma\tilde{S}_t dW_t, \quad (\text{A.1})$$

starting from $\tilde{S}_0 = S_0$, where λ and σ (omitted in the notation for d_{\pm} below when clear from the context) were introduced after (1.6). Hence $S_t = \mathbb{1}_{\{N_t=0\}}\tilde{S}_t$, $t \geq 0$. Given the maturity $T > 0$ and strike $K > 0$ of an option, let, for every pricing time t and stock value S ,

$$d_{\pm}(t, S; \lambda, \sigma) = \frac{\ln(\frac{S}{K}) + \lambda(T-t)}{\sigma\sqrt{T-t}} \pm \frac{1}{2}\sigma\sqrt{T-t}. \quad (\text{A.2})$$

We first consider the pricing of a vanilla call option.

Proposition A.1. *The jr value process (0.1)-(1.8) of the call option with payoff $(S_T - K)^+$ at time T can be represented as*

$$C_t^{jr} = u(t, S_t)\mathbb{1}_{[0, T]}, \quad t \in [0, T],$$

where the pricing function $u = u(t, S) := \mathbb{E}((S_T - K)^+ | S_t = S)$ is the unique classical solution with linear growth in S to the PDE

$$\begin{cases} u(T, S) = (S - K)^+, \quad S \geq 0 \\ \partial_t u(t, S) + \lambda S \partial_S u(t, S) + \frac{\sigma^2 S^2}{2} \partial_{S^2}^2 u(t, S) - \lambda u(t, S) = 0, \quad t < T, \quad S \geq 0. \end{cases} \quad (\text{A.3})$$

For $t < T$,

$$C_t^{jr} = S_t \mathcal{N}(d_+(t, S_t)) - K e^{-\lambda(T-t)} \mathcal{N}(d_-(t, S_t)). \quad (\text{A.4})$$

Proof. We have $S_T = \mathbb{1}_{\{\theta > T\}}\tilde{S}_T = \mathbb{1}_{\{\theta > T\}}S_0 \exp\left(\sigma W_T + \left(\lambda - \frac{\sigma^2}{2}\right)T\right)$. Since $(S_T - K)^+ = 0$ on $\theta \leq T$ and $S_T = \tilde{S}_T$ on $\theta > T$, it follows that, on $\{t < \theta\}$,

$$\begin{aligned} \mathbb{E}_t [(S_T - K)^+] &= \mathbb{E}_t [\mathbb{1}_{\{\theta > T\}}(S_T - K)^+] = \\ &= \mathbb{E}_t [\mathbb{1}_{\{\theta > T\}}(\tilde{S}_T - K)^+] = \mathbb{E}_t [e^{-\lambda(T-t)}(\tilde{S}_T - K)^+], \end{aligned} \quad (\text{A.5})$$

by independence between W and N in (0.1). One recognizes the probabilistic expression for the time- t price of the vanilla call option in the auxiliary Black-Scholes model (A.1), hence the proposition follows from standard Black-Scholes results. \square

We now consider the pricing of a put option in the jr model, in two forms: either a vanilla put with payoff $(K - S_T)^+$, or a vulnerable put with payoff $\mathbb{1}_{\{\theta > T\}}(K - S_T)^+$.

Proposition A.2. *The jr value process (0.1) of the vanilla put can be represented as*

$$P_t^{jr} = v(t, S_t)\mathbb{1}_{[0, T]}, \quad t \in [0, T], \quad (\text{A.6})$$

where the vanilla put pricing function $v = v(t, S) := \mathbb{E}((K - S_T)^+ | S_t = S)$ is the unique bounded classical solution to the PDE

$$\begin{cases} v(T, S) = (K - S)^+, \quad S \geq 0 \\ \partial_t v(t, S) + \lambda S \partial_S v(t, S) + \frac{\sigma^2 S^2}{2} \partial_{S^2}^2 v(t, S) \\ \quad - \lambda v(t, S) + \lambda K = 0, \quad t < T, \quad S \geq 0. \end{cases} \quad (\text{A.7})$$

For $t < T$,

$$P_t^{jr} = K e^{-\lambda(T-t)} \mathcal{N}(-d_-(t, S_t)) - S_t \mathcal{N}(-d_+(t, S_t)) + K(1 - e^{-\lambda(T-t)}). \quad (\text{A.8})$$

Proof. Taking expectation in the decomposition $S_T - K = (S_T - K)^+ - (S_T - K)^-$ yields the (model-free) call-put parity relationship

$$S_t - K = u(t, S_t) - v(t, S_t), \quad t \leq T, \quad (\text{A.9})$$

hence $v = u - (S - K)$, from which the PDE characterization based on (A.7) for v results from the PDE characterization based on (A.3) for u . Moreover, we deduce from (A.4) that, for $t < T$,

$$\begin{aligned} P_t^{jr} &= C_t^{jr} - (S_t - K) = S_t (\mathcal{N}(d_+(t, S_t)) - 1) - K \left(e^{-\lambda(T-t)} \mathcal{N}(d_-(t, S_t)) - 1 \right) \\ &= K e^{-\lambda(T-t)} \mathcal{N}(-d_-(t, S_t)) - S_t \mathcal{N}(-d_+(t, S_t)) + K(1 - e^{-\lambda(T-t)}), \end{aligned}$$

which is (A.8). \square

In accordance with (A.8):

Definition A.1. For $t < \theta \wedge T$, given the observed spot price $S_t = S > 0$, the Black-Scholes implied volatility $\Sigma_t = \Sigma(t, S)$ of the vanilla put in the jr model is the unique solution Σ to

$$\begin{aligned} K e^{-\lambda(T-t)} \mathcal{N}(-d_-(t, S; \lambda, \sigma)) - S \mathcal{N}(-d_+(t, S; \lambda, \sigma)) + K(1 - e^{-\lambda(T-t)}) \\ = K \mathcal{N}(-d_-(t, S; 0, \Sigma_t)) - S \mathcal{N}(-d_+(t, S; 0, \Sigma_t)). \end{aligned} \quad (\text{A.10})$$

We also set $\Sigma(t, 0) = 0$.

Remark A.1. For $S = 0$, any $\Sigma \geq 0$ solves (A.10): for any Σ , $d_{\pm} = -\infty$ as $\ln(\frac{0}{K}) = -\infty$, so $K \mathcal{N}(-d_-) - S \mathcal{N}(-d_+) = K - S = K$ (for $S = 0$).

Proposition A.3. *The value process (0.1) of the vulnerable put is given by*

$$\begin{aligned} Q_t^{jr} &= \mathbb{1}_{t < \theta \wedge T} (P_t^{jr} - (1 - e^{-\lambda(T-t)})K) = \\ &\quad \mathbb{1}_{t < \theta \wedge T} \left(K e^{-\lambda(T-t)} \mathcal{N}(-d_-(t, S_t)) - S_t \mathcal{N}(-d_+(t, S_t)) \right). \end{aligned} \quad (\text{A.11})$$

For $t < T$,

$$P_t^{jr} - Q_t^{jr} = \mathbb{1}_{t < \theta} K (1 - e^{-\lambda(T-t)}) + \mathbb{1}_{t \geq \theta} K. \quad (\text{A.12})$$

Proof. We have

$$\mathbb{1}_{\{\theta > T\}} (S_T - K) = \mathbb{1}_{\{\theta > T\}} ((S_T - K)^+ - (S_T - K)^-),$$

which in jr reduces to

$$S_T - \mathbb{1}_{\{\theta > T\}} K = (S_T - K)^+ - \mathbb{1}_{\{\theta > T\}} (S_T - K)^-.$$

By taking time- t conditional expectations, we have, on $\{t < \theta \wedge T\}$, that $S_t - K e^{-\lambda(T-t)} = C_t^{jr} - Q_t^{jr}$, which yields

$$Q_t^{jr} = C_t^{jr} - S_t + K e^{-\lambda(T-t)},$$

out of which (still on $\{t < \theta \wedge T\}$) the first identity in (A.11) follows from (A.9) and the second identity in turn follows from (A.8). Besides, on $\{t \geq \theta\}$, we have $Q^{jr} = 0$ and $P^{jr} = K$, whereas on $\{t \geq T\}$ we have $Q^{jr} = 0$, which completes the proof of (A.11) and (A.12). \square

Proposition A.4. *Setting $w(t, S) = v(t, S) - K(1 - e^{-\lambda(T-t)})$ (see Proposition A.2 and (A.12)), the vulnerable put is replicable on $[0, \theta \wedge T]$ in the jr model (in the absence of model risk and hedging frictions), by the dynamic strategy ζ in S and η in the vanilla put given by*

$$\zeta_t = -\frac{\mathcal{N}(-d_+(t, S_t))}{1 - \mathcal{N}(-d_-(t, S_t))}, \quad \eta_t = -\frac{\mathcal{N}(-d_-(t, S_t))}{1 - \mathcal{N}(-d_-(t, S_t))}, \quad t < \tau_s \wedge T, \quad (\text{A.13})$$

and the number of constant riskless assets deduced from the budget condition $w(t, S_t)$ on the strategy.

Proof. The profit-and-loss associated with the hedging strategy ζ in S and η in the vanilla put, both assumed left-limits of càdlàg processes, evolves following (the position being assumed to be unwound at θ)

$$dpnl_t = \mathbb{1}_{\{t \leq \theta\}} (dQ_t^{jr} - \zeta_t dS_t - \eta_t dP_t^{jr})$$

(with $pnl_0 = 0$). Itô formulas with (elementary) jump exploiting the results of Propositions A.2 and A.3 yield (cf. (1.6))

$$dpnl_t = \mathbb{1}_{\{t \leq \theta\}} (\alpha_t dW_t + \beta_t dM_t),$$

where

$$\alpha_t = \sigma S_t \left(\partial_S w(t, S_{t-}) - \zeta_t - \eta_t \partial_S v(t, S_{t-}) \right), \beta_t = -w(t, S_{t-}) + \zeta_t S_{t-} + \eta_t (v(t, S_{t-}) - K).$$

Hence the replication condition $\alpha = \beta = 0$ reduces to the linear systems

$$\partial_S w(t, S_{t-}) - \zeta_t - \eta_t \partial_S v(t, S_{t-}) = -w(t, S_{t-}) + \zeta_t S_{t-} + \eta_t (v(t, S_{t-}) - K) = 0 \quad (\text{A.14})$$

in the (ζ_t, η_t) (one system for each $t < \tau_s \wedge T$). Using (A.8) for the first line and (A.11) and (A.12) for the second line, one verifies that (A.13) solves (A.14). \square

B Proof of Theorem 2.1

Lemma B.1. *Under Assumptions 2.2 and 2.6, there exists $C_3 > 0$ such that, for all $h > 0$ and $u \in \{\partial_l q^*, (\partial_x(\partial_l q^*))\sigma; 1 \leq l \leq d\}$,*

$$\sup_{0 < t-s < h} \mathbb{E} \left[|u(t, \mathcal{X}_t) - u(s, \mathcal{X}_s)|^2 \right]^{\frac{1}{2}} \leq C_3 h^\alpha.$$

Proof. Since $1 - \prod_{j=1}^L \mathbb{1}_{\{\nu_t^j = \nu_s^j\}} \leq \sum_{j=1}^L (\nu_t^j - \nu_s^j)$, we have, for some constant $C \geq 0$ varying from line to line,

$$\begin{aligned} & \mathbb{E} \left[|u(t, \mathcal{X}_t) - u(s, \mathcal{X}_s)|^2 \right]^{\frac{1}{2}} \\ & \leq \sqrt{2} \mathbb{E} \left[|u(t, X_t, J_t) - u(t, X_t, J_s)|^2 \right]^{\frac{1}{2}} + \sqrt{2} \mathbb{E} \left[|u(t, X_t, J_s) - u(s, X_s, J_s)|^2 \right]^{\frac{1}{2}} \\ & \leq C \left(\mathbb{E} \left[|u(t, X_t, J_t) - u(t, X_t, J_s)|^2 \sum_{j=1}^L (\nu_t^j - \nu_s^j) \right]^{\frac{1}{2}} + (t-s)^\alpha + (t-s)^{\frac{1}{2}} \right) \\ & \leq C \left(\sum_{j=1}^L \mathbb{E} \left[\int_s^t \lambda_r^j dr \right]^{\frac{1}{2}} + (t-s)^\alpha \right) \leq C \left(L \sqrt{\Lambda(t-s)} + (t-s)^\alpha \right) \leq C_3 h^\alpha, \end{aligned}$$

where we used equation (2.4) and the bound on the maps λ^j . \square

Coming to the proof of the theorem, we have, for $t = 0$ for notational simplicity,

$$\begin{aligned}
\left| \text{HVA}_0^h - \text{HVA}_0^f \right| &= \left| \mathbb{E} \left[\sum_{i=1}^n \varphi_{ih}^h \right] - \mathbb{E} \left[\int_0^{T^*} \varphi_t dt \right] \right| \\
&= \left| \frac{\sqrt{h}}{2} \mathbb{E} \left[\sum_{i=1}^n X_{ih}^\top \mathbf{k} (\delta a_{ih})^{\text{abs}} \right] - \frac{1}{\sqrt{2\pi}} \mathbb{E} \left[\sum_{i=1}^n \int_{(i-1)h}^{ih} X_t^\top \mathbf{k} (\Gamma \sigma)^{\text{abs}}(t, \mathcal{X}_t) dt \right] \right| \\
&\leq \sum_{l=1}^d k_l \left| \frac{\sqrt{h}}{2} \mathbb{E} \left[\sum_{i=1}^n X_{ih}^l |a_{ih}^l - a_{(i-1)h}^l| \right] - \frac{1}{\sqrt{2\pi}} \mathbb{E} \left[\sum_{i=1}^n \int_{(i-1)h}^{ih} X_t^l |\partial_x(\partial_l q^*) \sigma|(t, \mathcal{X}_t) dt \right] \right| \\
&= h \sum_{l=1}^d \sum_{i=1}^n k_l \left| \mathbb{E} \left[\frac{1}{2\sqrt{h}} X_{ih}^l |a_{ih}^l - a_{(i-1)h}^l| - \frac{1}{h\sqrt{2\pi}} \int_{(i-1)h}^{ih} X_t^l |\partial_x(\partial_l q^*) \sigma|(t, \mathcal{X}_t) dt \right] \right| \\
&\leq T^* \sum_{l=1}^d k_l \sup_{0 \leq s < t \leq T^*, t-s=h} \left| \mathbb{E} \left[\frac{1}{2\sqrt{h}} X_t^l |a_t^l - a_s^l| - \frac{1}{h\sqrt{2\pi}} \int_s^t X_u^l |\partial_x(\partial_l q^*) \sigma|(u, \mathcal{X}_u) du \right] \right|.
\end{aligned}$$

We fix $1 \leq l \leq d$ and we show that

$$\sup_{t-s=h} \left| \mathbb{E} \left[\frac{1}{2\sqrt{h}} X_t^l |a_t^l - a_s^l| - \frac{1}{h\sqrt{2\pi}} \int_s^t X_u^l |\partial_x(\partial_l q^*) \sigma|(u, \mathcal{X}_u) du \right] \right| \rightarrow_{h \rightarrow 0} 0. \quad (\text{B.1})$$

In fact, for all $0 \leq s < t \leq T^*$ such that $t - s = h$,

$$\begin{aligned}
&\left| \mathbb{E} \left[\frac{1}{2\sqrt{h}} X_t^l |a_t^l - a_s^l| - \frac{1}{h\sqrt{2\pi}} \int_s^t X_u^l |\partial_x(\partial_l q^*) \sigma|(u, \mathcal{X}_u) du \right] \right| \\
&\leq \frac{1}{2\sqrt{h}} \left| \mathbb{E} \left[(X_t^l - X_s^l) |a_t^l - a_s^l| \right] \right| \\
&+ \frac{1}{2\sqrt{h}} \left| \mathbb{E} \left[X_s^l \left(|a_t^l - a_s^l| - |\partial_x(\partial_l q^*) \sigma|(s, \mathcal{X}_s)(W_t - W_s)| \right) \right] \right| \\
&+ \left| \mathbb{E} \left[\frac{1}{2\sqrt{h}} X_s^l |\partial_x(\partial_l q^*) \sigma|(s, \mathcal{X}_s)(W_t - W_s)| - \frac{1}{h\sqrt{2\pi}} \int_s^t X_u^l |\partial_x(\partial_l q^*) \sigma|(u, \mathcal{X}_u) du \right] \right|
\end{aligned} \quad (\text{B.2})$$

Regarding the first term in the r.h.s. of (B.2), we have, by Assumption 2.2 and Lemma B.1,

$$\begin{aligned}
\frac{1}{2\sqrt{h}} \left| \mathbb{E} \left[(X_t^l - X_s^l) |a_t^l - a_s^l| \right] \right| &\leq \frac{1}{2\sqrt{h}} \mathbb{E} \left[|X_t^l - X_s^l|^2 \right]^{\frac{1}{2}} \mathbb{E} \left[|a_t^l - a_s^l|^2 \right]^{\frac{1}{2}} \\
&\leq \frac{C_1}{2} h^{-\frac{1}{2} + \frac{1}{2} + \alpha} = \frac{C_1}{2} h^\alpha.
\end{aligned} \quad (\text{B.3})$$

We now consider the second term in the r.h.s. of (B.2). With $\delta \partial_l q^*(t, x, j, k) := \partial_l q^*(t, x, j) - \partial_l q^*(t, x, k)$ and C^l defined in (2.5), recalling that $|\delta \partial_l q^*(t, x, j, k)| \leq C_2$

by Assumption 2.6, we compute by Itô's formula:

$$\begin{aligned}
& \frac{1}{2\sqrt{h}} \left| \mathbb{E} \left[X_s^l \left(|a_t^l - a_s^l| - |\partial_x(\partial_l q^*)\sigma(s, \mathcal{X}_s)(W_t - W_s)| \right) \right] \right| \\
& \leq \frac{1}{2\sqrt{h}} \mathbb{E} \left[X_s^l \int_s^t |(\partial_t + \mathcal{F})\partial_l q^*(u, \mathcal{X}_u)| du \right] + \sum_{j=1}^L \frac{1}{2\sqrt{h}} \mathbb{E} \left[X_s^l \left| \int_s^t \delta \partial_l q^*(u, \mathcal{X}_u, k) d\nu_u^k \right| \right] \\
& + \frac{1}{2\sqrt{h}} \mathbb{E} \left[X_s^l \left| \int_s^t (\partial_x(\partial_l q^*)\sigma(u, \mathcal{X}_u) - \partial_x(\partial_l q^*)\sigma(s, \mathcal{X}_s)) dW_u \right| \right] \\
& \leq \frac{C^l}{2} \mathbb{E} \left[\int_s^t |(\partial_t + \mathcal{F})\partial_l q^*(u, \mathcal{X}_u)|^2 du \right]^{\frac{1}{2}} + \frac{C_2}{2\sqrt{h}} \sum_{j=1}^L \mathbb{E} \left[X_s^l (\nu_t^j - \nu_s^j) \right] \\
& + \frac{C^l}{2\sqrt{h}} \mathbb{E} \left[\int_s^t |\partial_x(\partial_l q^*)\sigma(u, \mathcal{X}_u) - \partial_x(\partial_l q^*)\sigma(s, \mathcal{X}_s)|^2 du \right]^{\frac{1}{2}} \\
& \leq \frac{C^l C_2}{2} \sqrt{h} + \frac{C^l C_2 \Lambda L \sqrt{h}}{2} + \frac{C^l C_3}{2} h^\alpha \leq Ch^\alpha,
\end{aligned} \tag{B.4}$$

where we used

$$\begin{aligned}
\mathbb{E} \left[X_s^l (\nu_t^j - \nu_s^j) \right] &= \mathbb{E} \left[X_s^l \mathbb{E}_s [\nu_t^j - \nu_s^j] \right] = \mathbb{E} \left[X_s^l \int_s^t \lambda_u^j du \right] \\
&\leq \mathbb{E} \left[(X_s^l)^2 \right]^{\frac{1}{2}} \mathbb{E} \left[\left(\int_s^t \lambda_u^j du \right)^2 \right]^{\frac{1}{2}} \leq C^l \Lambda h, \\
\mathbb{E} \left[\int_s^t |(\partial_t + \mathcal{F})\partial_l q^*(u, \mathcal{X}_u)|^2 du \right]^{\frac{1}{2}} &= \left(\int_s^t \mathbb{E} \left[|(\partial_t + \mathcal{F})\partial_l q^*(u, \mathcal{X}_u)|^2 \right] du \right)^{\frac{1}{2}} \\
&\leq \sqrt{h} \sup_{u \in [0, T^*]} \mathbb{E} \left[|(\partial_t + \mathcal{F})\partial_l q^*(u, \mathcal{X}_u)|^2 \right]^{\frac{1}{2}} \leq C_2 \sqrt{h},
\end{aligned}$$

and Lemma B.1.

We finally deal with the last term in the r.h.s. of (B.2). As $\partial_x(\partial_l q^*)\sigma(s, \mathcal{X}_s)(W_t - W_s)$ has, conditionally on \mathfrak{F}_s , the law $\mathcal{N} \left(0, h |\partial_x(\partial_l q^*)\sigma(s, \mathcal{X}_s)|^2 \right)$, we have

$$\frac{1}{2\sqrt{h}} \mathbb{E} \left[X_s^l |\partial_x(\partial_l q^*)\sigma(s, \mathcal{X}_s)(W_t - W_s)| \right] = \frac{1}{\sqrt{2\pi}} \mathbb{E} \left[X_s^l |\partial_x(\partial_l q^*)\sigma(s, \mathcal{X}_s)| \right].$$

We then obtain for this last term:

$$\begin{aligned}
& \left| \mathbb{E} \left[\frac{1}{2\sqrt{h}} X_s^l |\partial_x(\partial_l q^*)\sigma(s, \mathcal{X}_s)| (W_t - W_s) - \frac{1}{h\sqrt{2\pi}} \int_s^t X_u^l |\partial_x(\partial_l q^*)\sigma|(u, \mathcal{X}_u) du \right] \right| \\
&= \frac{1}{\sqrt{2\pi}} \left| \mathbb{E} \left[X_s^l |\partial_x(\partial_l q^*)\sigma(s, \mathcal{X}_s)| - \frac{1}{h} \int_s^t X_u^l |\partial_x(\partial_l q^*)\sigma|(u, \mathcal{X}_u) du \right] \right| \\
&\leq \frac{1}{\sqrt{2\pi}} \left| \mathbb{E} \left[X_s^l |\partial_x(\partial_l q^*)\sigma(s, \mathcal{X}_s)| - \frac{1}{h} \int_s^t X_u^l |\partial_x(\partial_l q^*)\sigma|(u, X_u, J_s) du \right] \right| \\
&+ \frac{1}{h\sqrt{2\pi}} \left| \mathbb{E} \left[\int_s^t X_u^l (|\partial_x(\partial_l q^*)\sigma|(u, X_u, J_s) - |\partial_x(\partial_l q^*)\sigma|(u, X_u, J_u)) du \right] \right| \\
&\leq \frac{1}{\sqrt{2\pi}} \left| \mathbb{E} \left[X_s^l |\partial_x(\partial_l q^*)\sigma(s, \mathcal{X}_s)| - X_r^l |\partial_x(\partial_l q^*)\sigma(r, X_r, J_s)| \right] \right| \\
&+ \frac{C^l}{\sqrt{h}2\pi} \mathbb{E} \left[\int_s^t (\partial_x(\partial_l q^*)\sigma(u, X_u, J_s) - \partial_x(\partial_l q^*)\sigma(u, X_u, J_u))^2 du \sum_{j=1}^L (\nu_t^j - \nu_s^j) \right]^{\frac{1}{2}},
\end{aligned}$$

where the (random) $r \in (s, t)$ in the next-to-last line is obtained via the mean value theorem. We have, for a constant C changing from term to term,

$$\begin{aligned}
& \left| \mathbb{E} \left[X_s^l |\partial_x(\partial_l q^*)\sigma(s, \mathcal{X}_s)| - X_r^l |\partial_x(\partial_l q^*)\sigma(r, X_r, J_s)| \right] \right| \\
&\leq \mathbb{E} \left[|X_s^l - X_r^l| |\partial_x(\partial_l q^*)\sigma(s, \mathcal{X}_s)| \right] + \mathbb{E} \left[|X_r^l |\partial_x(\partial_l q^*)\sigma(s, \mathcal{X}_s)| - \partial_x(\partial_l q^*)\sigma(r, X_r, J_s)| \right] \tag{B.5} \\
&\leq C_1 h^{\frac{1}{2}} \sup_{t \in [0, T^*]} \mathbb{E} [|\partial_x(\partial_l q^*)\sigma(t, \mathcal{X}_t)|^2]^{\frac{1}{2}} + Ch^\alpha \mathbb{E} [X_r^l] + C \mathbb{E} [X_r^l |X_r - X_s|] \leq Ch^\alpha,
\end{aligned}$$

as

$$\sup_{t \in [0, T^*]} \mathbb{E} [|\partial_x(\partial_l q^*)\sigma(t, \mathcal{X}_t)|^2]^{\frac{1}{2}} \leq C(T^*)^\alpha + C^l + C \max_{1 \leq j \leq L} |\partial_x(\partial_l q^*)\sigma(0, 0, k)| < \infty.$$

Finally,

$$\begin{aligned}
& \frac{C^l}{\sqrt{h}2\pi} \mathbb{E} \left[\int_s^t (\partial_x(\partial_l q^*)\sigma(u, X_u, J_s) - \partial_x(\partial_l q^*)\sigma(u, X_u, J_u))^2 du \sum_{j=1}^L (\nu_t^j - \nu_s^j) \right]^{\frac{1}{2}} \\
& \frac{C^l C_2}{\sqrt{2\pi}} \mathbb{E} \left[\sum_{j=1}^L \int_s^t \lambda_u^j du \right]^{\frac{1}{2}} \leq \frac{C^l C_2}{\sqrt{2\pi}} \sqrt{L\Lambda h}.
\end{aligned} \tag{B.6}$$

Using (B.3)-(B.4)-(B.5)-(B.6), we obtain, for some constant $C \geq 0$,

$$\sup_{t-s=h} \left| \mathbb{E} \left[\frac{1}{2\sqrt{h}} X_t^l |a_t^l - a_s^l| - \frac{1}{h\sqrt{2\pi}} \int_s^t X_u^l |\partial_x(\partial_l q^*)\sigma|(u, \mathcal{X}_u) du \right] \right| \leq Ch^\alpha,$$

which proves (B.1) and therefore the theorem.

C Neural Nets Regression and Quantile Regressions for the Pathwise HVA^f, EC, and KVA of Section 3.4

The setup and notation are the ones of Section 3.4.

HVA^f Computations The function $\widehat{\text{HVA}}^f$ in (3.11) is such that $\widehat{\text{HVA}}^f(T, \cdot) = 0$, $\widehat{\text{HVA}}^f(t, 0) = 0$ for all t and, for $u < t$ and $S \in (0, \infty)$,

$$\begin{aligned} \widehat{\text{HVA}}^f(u, S) &= \mathbb{E} \left[(f_t - f_u) + \widehat{\text{HVA}}^f(t, S_t) \mid S_u = S \right] \\ &= \mathbb{E} \left[(f_t - f_u) + \widehat{\text{HVA}}^f(t, S_t) \mathbb{1}_{\{S_t > 0\}} \mid S_u = S \right], \end{aligned} \quad (\text{C.1})$$

for f as per (2.11). Accordingly, we approximate on $(0, \infty)$ the functions $\widehat{\text{HVA}}^f(t_i, \cdot)$ for $t_i := i \frac{T}{10}$, as follows. Set $\widehat{\text{HVA}}^f(t_{10}, \cdot) = 0$ and assume that we have already trained neural networks $\widehat{\text{HVA}}^f(t_k, \cdot)$, $i + 1 \leq k < 10$. Based on sampled data

$$(X, Y) = \left(\widetilde{S}_{t_i}^m, (f_{t_{i+1}} - f_{t_i})^m + \widehat{\text{HVA}}^f(t_{i+1}, S_{t_{i+1}}^m) \mathbb{1}_{\{S_{t_{i+1}}^m > 0\}} \right)_{1 \leq m \leq M},$$

where each $S_{t_{i+1}}^m$ is obtained from (1.6) with initial condition $S_{t_i}^m = \widetilde{S}_{t_i}^m > 0$ simulated from (A.1), in view of (C.1) and of the least-squares characterization of conditional expectation (in square integrable cases), we seek for $\widehat{\text{HVA}}^f(t_i, \cdot)$ in

$$\operatorname{argmin}_{u \in \mathcal{NN}} \sum_{m=1}^M \left(\widehat{\text{HVA}}^f(t_{i+1}, S_{t_{i+1}}^m) \mathbb{1}_{\{S_{t_{i+1}}^m > 0\}} + (f_{t_{i+1}} - f_{t_i})^m - u(\widetilde{S}_{t_i}^m) \right)^2, \quad (\text{C.2})$$

where \mathcal{NN} denotes the set of feedforward neural networks with three hidden layers of 10 neurons each and ReLU activation functions.

We then obtain $\widehat{\text{HVA}}^f(0, S_0) = 0.04613$ from $f_{t_1} + \widehat{\text{HVA}}^f(t_1, S_{t_1})$ as a sample mean. The corresponding standard deviation, 95% confidence interval and relative error at 95% are $\hat{\sigma}^f \simeq 6 \times 10^{-3}$, $[0.04601, 0.04624]$ and $\frac{1.96\hat{\sigma}^f}{\widehat{\text{HVA}}_0^f \sqrt{M}} \simeq 0.25\%$, where $\hat{\sigma}^f$ denotes the empirical standard deviation of $f_1 + \widehat{\text{HVA}}^f(t_1, S_{t_1})$.

EC Computations Next we approximate $\widetilde{\text{EC}}(t, \cdot)$ on $(0, \infty)$ by the two-stage scheme of Barrera et al. (2022, Section 4.3), for each $t = t_i$, $1 \leq i < 10$. Recall $t' = (t + 1) \wedge T$. We first train a neural network $\widetilde{\text{VaR}}(t, \cdot)$ approximating $\text{VaR}(t, \cdot)$ based on sampled data $(X, Y) = \left(\widetilde{S}_t^m, (\mathcal{L}_{t'} - \mathcal{L}_t)^m \right)_{1 \leq m \leq M}$ and on the pinball-type loss $(y - u(x))^+ + (1 - \alpha)u(x)$, i.e. we seek for $\widetilde{\text{VaR}}(t, \cdot)$ in

$$\operatorname{argmin}_{u \in \mathcal{NN}} \frac{1}{M} \sum_{m=1}^M \left((\mathcal{L}_{t'} - \mathcal{L}_t)^m - u(\widetilde{S}_t^m) \right)^+ + (1 - \alpha)u(\widetilde{S}_t^m).$$

Note from (3.1) that, for $t = t_i$, sampling $\mathcal{L}_{t'} - \mathcal{L}_t$ uses the already trained neural network $\widehat{\text{HVA}}^f(t_{i+1}, \cdot)$. For $t = \widehat{1yr}$ (where the approximation should be the worst due to error accumulated on $\widehat{\text{HVA}}^f$ from dynamic programming), the Monte Carlo estimate of Barrera et al. (2022, (4.10)) for the distance in p -values between the estimate $\widehat{\text{VaR}}(t, S_t)$ and the targeted (unknown) $\text{VaR}_t(\mathcal{L}_{t'} - \mathcal{L}_t)$ is less than $3.6 \times 10^{-3} \leq 1 - \alpha = 10^{-2}$ with 95% probability.

We then train neural networks $\widehat{\text{EC}}(t, \cdot)$ approximating $\widetilde{\text{EC}}(t, \cdot)$ on $(0, \infty)$ at times $t = t_i$ based on sampled data $(X, Y) = \left(\widetilde{S}_t^m, (\mathcal{L}_{t'} - \mathcal{L}_t)^m \right)_{1 \leq m \leq M}$ and on the loss

$$\left((1 - \alpha)^{-1} (y - \widehat{\text{VaR}}(t, x))^+ + \widehat{\text{VaR}}(t, x) - u(x) \right)^2,$$

i.e. we seek for $\widehat{\text{EC}}(t, \cdot)$ in

$$\operatorname{argmin}_{u \in \mathcal{NN}} \frac{1}{M} \sum_{m=1}^M \left((1 - \alpha)^{-1} \left((\mathcal{L}_{t'} - \mathcal{L}_t)^m - \widehat{\text{VaR}}(S_t^m) \right)^+ + \widehat{\text{VaR}}(S_t^m) - u(x) \right)^2.$$

For $t = 1yr$, the Monte Carlo estimate of Barrera et al. (2022, (4.8)) for the L_2 -norm of the difference between the estimate $\widehat{\text{EC}}(t, \widetilde{S}_t)$ and the targeted (unknown) $\widetilde{\text{EC}}(t, \widetilde{S}_t)$ is smaller than 0.067 (itself significantly less than the orders of magnitude of EC visible on the left panels of Figure 3.2) with probability 95%.

We also compute $\widehat{\text{VaR}}(0, S_0) = 0.0120$ (which is needed for $\widehat{\text{EC}}(0, S_0)$ below) as an empirical (unconditional) value-at-risk. The corresponding 95% confidence interval and relative error at 95% are $[0.0117, 0.0123]$ and $\frac{1.96}{\widehat{\text{VaR}}(0, S_0) \hat{d}(\widehat{\text{VaR}}(0, S_0))} \sqrt{\frac{\alpha(1-\alpha)}{M}} \simeq 2.3\%$, where \hat{d} denotes the empirical density of $\mathcal{L}_{t_1} - \mathcal{L}_{t_0}$. Finally we compute $\widehat{\text{EC}}(0, S_0) = 0.493$ using the recursive algorithm of Costa and Gadat (2021, Eqn (4)). Using the central limit theorem for expected shortfalls derived in Costa and Gadat (2021, Theorem 1.3), a 95% confidence interval is $[0.451, 0.534]$ and the relative error at 95% is $\sqrt{\frac{b_M}{2}} \frac{1.96 \hat{\sigma}^s}{(1-\alpha) \widehat{\text{EC}}(0, S_0)} \simeq 0.08$, where $\hat{\sigma}^s$ denotes the empirical standard deviation of $(\mathcal{L}_1 - \mathcal{L}_0) \mathbb{1}_{\{(\mathcal{L}_1 - \mathcal{L}_0) > \widehat{\text{VaR}}(0, S_0)\}}$ and b_M is defined in Costa and Gadat (2021, Assumption H_{a_n, b_n}).

KVA Computations Last, we approximate $\widehat{\text{KVA}}(t, \cdot)$ at times $t = t_i$ on $(0, \infty)$, for i decreasing from 10 to 1, by neural networks $\widehat{\text{KVA}}(t_i, \cdot)$, based on the following dynamic programming equation, for $0 \leq i < 10$:

$$\begin{aligned} \text{KVA}_{t_i} &= \mathbb{E}_{t_i} \left[\text{KVA}_{t_{i+1}} + h \int_{t_i}^{t_{i+1}} (\text{EC}_u - \text{KVA}_u)^+ du \right] \\ &\approx \mathbb{E}_{t_i} \left[\text{KVA}_{t_{i+1}} + h(t_{i+1} - t_i) (\text{EC}_{t_{i+1}} - \text{KVA}_{t_{i+1}})^+ \right]. \end{aligned}$$

Starting from $\widehat{\text{KVA}}(t_n, \cdot) = 0$ and having already trained the $\widehat{\text{KVA}}(t_j, \cdot), j > i > 0$, we train $\widehat{\text{KVA}}(t_i, \cdot)$ based on sampled data

$$(X, Y) = \left(\widetilde{S}_{t_i}^m, h(t_{i+1} - t_i) \left(\widehat{\text{EC}}(t_{i+1}, S_{t_{i+1}}^m) - \widehat{\text{KVA}}(t_{i+1}, S_{t_{i+1}}^m) \mathbb{1}_{\{S_{t_{i+1}}^m > 0\}} \right)^+ \right. \\ \left. + \widehat{\text{KVA}}(t_{i+1}, S_{t_{i+1}}^m) \mathbb{1}_{\{S_{t_{i+1}}^m > 0\}} \right)_{1 \leq m \leq M}$$

and on the quadratic loss $(y - u(x))^2$. We then compute $\widehat{\text{KVA}}(0, S_0) = 0.407$ from $r(t_1 - t_0)(\widehat{\text{EC}}(t_1, S_{t_1}) - \widehat{\text{KVA}}(t_1, S_{t_1}) \mathbb{1}_{\{S_{t_1} > 0\}}) + \widehat{\text{KVA}}(t_1, S_{t_1})$ as a sample mean. The corresponding standard deviation, 95% confidence interval and relative error at 95% are $\hat{\sigma}^{kva} \simeq 6 \times 10^{-2}$, $[0.4056, 0.4082]$ and $\frac{1.96\hat{\sigma}^{kva}}{\widehat{\text{KVA}}_{A_0}\sqrt{M}} \simeq 0.0028$, where $\hat{\sigma}^{kva}$ denotes the empirical standard deviation of $r(t_1 - t_0)(\widehat{\text{EC}}(t_1, S_{t_1}) - \widehat{\text{KVA}}(t_1, S_{t_1}) \mathbb{1}_{\{S_{t_1} > 0\}}) + \widehat{\text{KVA}}(t_1, S_{t_1})$.

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