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INFECTION SPREADING IN CELL CULTURE AS A REACTION-DIFFUSION WAVE

LATIFA AIT MAHIOUT¹, NIKOLAI BESSONOV², BOGDAN KAZMIERCZAK³,
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Abstract. Infection spreading in cell culture occurs due to virus replication in infected cells and its random motion in the extracellular space. Multiplicity of infection experiments in cell cultures are conventionally used for the characterization of viral infection by the number of viral plaques and the rate of their growth. We describe this process with a delay reaction-diffusion system of equations for the concentrations of uninfected cells, infected cells, virus, and interferon. Time delay corresponds to the duration of viral replication inside infected cells. We show that infection propagates in cell culture as a reaction-diffusion wave, we determine the wave speed and prove its existence. Next, we carry out numerical simulations and identify three stages of infection progression: infection decay during time delay due to virus replication, explosive growth of viral load when infected cells begin to reproduce it, and finally, wave-like infection progression in cell culture characterized by a constant or slowly growing total viral load. The modelling results are in agreement with the experimental data for the coronavirus infection in a culture of epithelial cells and for some other experiments. The presence of interferon produced by infected cells decreases the viral load but does not change the speed of infection progression in cell culture. In the 2D modelling, the total viral load grows faster than in the 1D case due to the increase of plaque perimeter.

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1. INTRODUCTION

1.1. Infection progression in cell culture

Virus replication occurs inside host cells due to a complex multi-stage process resulting in production of new virions expelled from the infected cell into the extracellular space [3]. Each cell can produce hundreds or even thousands of new virus particles often dying after that, which depends on cell type and on specific properties of viral infection. Let us note that some viruses, including the coronavirus SARS-CoV-2, develop special mechanisms influencing cell cycle and provide a more efficient replication [17].

Experimental or clinical assessment of the progression of viral infection implies the evaluation of virus concentration in the infected tissue by means of conventional multiplicity of infection (MOI) assays (see, *e.g.*, [6, 7, 11, 14, 16] and the references therein). After several consecutive dilutions, the virus-containing solution is poured in a cell culture leading to the formation of virus plaques. The number of such plaques determines the virus concentration measured in plaque forming units (PFU). The plaques consist of dead or modified cells, and it forms due to virus replication inside the cells and its random motion (diffusion) between cells. The plaque growth rate characterizes the efficacy of virus penetration inside the cells, the intensity of its production and transmission between cells, thus, the virus virulence.

In spite of the importance and wide use of these experiments, there are relatively few modelling works devoted to the infection progression in cell culture taking into account spatial distributions of cells and virus particles. A reaction-diffusion model of plaque growth is considered in [22] in the case of reversible host infection. The plaque growth rate is determined by the method of linearization (*cf.* Sect. 3.1). Numerical simulations of viral plaque growth described by a reaction-diffusion model with time delay are presented in [10]. This model is different in comparison with the model (1.1)–(1.3) considered below, and these different approaches are complementary (see Discussion for more detail). Existence of solutions of an initial-boundary value problem for a reaction-diffusion model of viral infection is proved in [12]. Individual based models of viral infection spreading in cell cultures are developed in [1, 15].

In this work we continue to study viral plaque growth with a delay reaction-diffusion system of equation, in line with the previous investigations but with a different model, which seems to us more appropriate, and more complete results. The model is presented in the next section and the main results in Section 1.3.

1.2. Model formulation

We consider the system of equations

$$\frac{\partial U}{\partial t} = -aUV, \quad (1.1)$$

$$\frac{\partial I}{\partial t} = aUV - \beta I, \quad (1.2)$$

$$\frac{\partial V}{\partial t} = D \frac{\partial^2 V}{\partial x^2} + bI_\tau - \sigma V \quad (1.3)$$

describing virus spread in cell culture. Here U is the concentration of uninfected cells, I of infected cells, V of virus, $I_\tau(x) = I(x, t - \tau)$. Below in this work we will also consider a more complete model taking into account interferon production by infected cells, and a 2D formulation of this model.

If we neglect death of infected cells ($\beta = 0$), and we will see below that this assumption is appropriate for some experiments, then from equations (1.1), (1.2), we get $U + I = w_0$, where w_0 is some constant. In this case we can reduce system (1.1)–(1.3) to the following system of two equations:

$$\frac{\partial I}{\partial t} = a(w_0 - I)V, \quad (1.4)$$

$$\frac{\partial V}{\partial t} = D \frac{\partial^2 V}{\partial x^2} + bI_\tau - \sigma V. \quad (1.5)$$

In the study of travelling wave solution, we substitute

$$I(x, t) = w(x - ct), \quad V(x, t) = v(x - ct)$$

and obtain the following system of equations:

$$cw' + a(w_0 - w)v = 0, \tag{1.6}$$

$$Dv'' + cv' + bw(\xi + c\tau) - \sigma v = 0 \tag{1.7}$$

with respect to functions $w(\xi)$ and $v(\xi)$ having limits at infinity:

$$w(\infty) = v(\infty) = 0, \quad w(-\infty) = w_0, \quad v(-\infty) = \frac{bw_0}{\sigma}. \tag{1.8}$$

In the analytical part of the work we will study the existence of solutions of this problem, and the speed of wave propagation. Numerical simulations will be carried out for system (1.1)–(1.3) in a bounded interval, and for a more complete system containing also the interferon concentration.

1.3. The contents and main results

Viral infection can spread in cell culture as a reaction-diffusion wave. We will study in this work the properties of infection waves. One of their main characteristics is the speed of propagation. In order to determine it, we will use the linearization method applicable in the so-called monostable case where the waves exist for all speeds greater than or equal to the minimal speed. In general, this method allows the estimation of the minimal wave speed from below, that is, $c_* \leq c_0$, where c_* is the linearization speed and c_0 is the minimal speed (see [20] and the references therein). However, it is not known a priori whether it gives the exact value of the minimal wave speed. For example, for a single reaction-diffusion equation with the logistic nonlinearity, $c_0 = c_*$, but for some other nonlinearities, it is possible to have the exact inequality $c_0 > c_*$. We will prove that for system (1.6), (1.7) the waves exist for all speeds greater than or equal to the linearization speed c_* . Therefore, it gives indeed the minimal speed. In Section 2 we obtain this result for the model with cell diffusion, and in Section 3 without cell diffusion, passing to the limit as the diffusion coefficient tends to 0.

The wave existence is proved for the model without cell death ($\beta = 0$) where it can be reduced to a monotone system of two equations. Wave existence is known for monotone systems without time delay (see [20] and the references therein). Time delay in equation (1.5) enters in such a way that the system still satisfies the maximum principle and the comparison theorems allowing the proof of wave existence. Namely, we will use the method of upper and lower functions. However, the presence of time delay changes some spectral properties of the corresponding differential operators, and the wave existence is proved under the additional condition that τ is limited from above.

The analytical results on the wave existence and the speed of propagation are completed by numerical simulations of system (1.1)–(1.3) in Section 4. They allow us to identify three stages of infection progression. In the beginning, during time delay in virus replication, the total viral load decreases, while the viral particles introduced initially diffuse in the culture infecting the surrounding cells. At the second stage, infected cells begin to produce new virus particles, and there is an explosive growth of their concentration. The third stage of infection progression is characterized by wave propagation along the cell culture. If infected cells die, then the total viral load remains constant. In the case without cell death, the total viral load grows linearly in time proportionally to the wave speed. We compared these numerical results with the experimental data from the literature for coronavirus and poliovirus [11, 16]. In the 2D simulations, the total viral load increases faster than in the 1D case because the rate of cell infection increases proportionally to the plaque perimeter. We complete the numerical part of this work with a model including the interferon production by the infected cells. Interferon slows down virus replication and decreases the total viral load. However, the speed of infection wave in the cell culture remains the same.

2. EXISTENCE OF WAVES

Consider the problem

$$D_1 w'' + cw' + a(w_0 - w)v = 0, \quad (2.1)$$

$$D_2 v'' + cv' + bw(\xi + c\tau) - \sigma v = 0 \quad (2.2)$$

with respect to functions $w(\xi)$ and $v(\xi)$ having limits at infinity:

$$w(\infty) = v(\infty) = 0, \quad w(-\infty) = w_0, \quad v(-\infty) = \frac{bw_0}{\sigma}. \quad (2.3)$$

It differs from the previous one by the presence of the diffusion term in the first equation.

We will study the existence of solutions of problem (2.1)–(2.3) and the corresponding values of speed c . As usual in the monostable case, there is a minimal wave speed c_0 which will be determined from the linearized problem under the condition that its solution monotonically decreases at infinity. If the wave speed is less than c_0 , the solutions of the linear problem oscillate and change sign. Therefore, they do not have biological significance. The determination of the minimal wave speed c_0 is quite straightforward. However, the proof of wave existence for all $c \geq c_0$ is much more involved. We will use the method of upper and lower functions, and we will begin with an auxiliary problem (2.4)–(2.6) presented below, where the term $c\tau$ with an unknown speed c in equation (2.2) is replaced by a given constant h . First, we will prove the wave existence for $h = 0$, then for $h > 0$, and will conclude with $h = c\tau$. In Section 3, we will consider the limiting case $D_1 \rightarrow 0$ and obtain wave existence for problem (1.6)–(1.8).

Along with problem (2.1)–(2.3) consider the auxiliary problem

$$D_1 u_1'' + cu_1' + a(w_0 - u_1)u_2 = 0, \quad (2.4)$$

$$D_2 u_2'' + cu_2' + bu_1(\xi + h) - \sigma u_2 = 0 \quad (2.5)$$

with respect to functions $u_1(\xi)$ and $u_2(\xi)$ having limits at infinity:

$$u_1(\infty) = u_2(\infty) = 0, \quad u_1(-\infty) = w_0, \quad u_2(-\infty) = \frac{bw_0}{\sigma}. \quad (2.6)$$

Here h is a real constant.

We will use the method of upper and lower functions constructed as solutions of the corresponding linear problem:

$$D_1 v_1'' + cv_1' + aw_0 v_2 = 0, \quad (2.7)$$

$$D_2 v_2'' + cv_2' + bv_1(\xi + h) - \sigma v_2 = 0 \quad (2.8)$$

with respect to functions $v_1(\xi)$ and $v_2(\xi)$ having limits at infinity:

$$u_1(\infty) = u_2(\infty) = 0. \quad (2.9)$$

We look for its solution in the form

$$v_1(x) = pe^{-\lambda x}, \quad v_2(x) = qe^{-\lambda x} \quad (2.10)$$

assuming that $p, q, \lambda > 0$.

2.1. Minimal wave speed for $h = 0$

Consider, first, the case $h = 0$. Substituting (2.10) into equations (2.7), (2.8), we get

$$D_1\lambda^2p - c\lambda p + aw_0q = 0, \tag{2.11}$$

$$D_2\lambda^2q - c\lambda q + bp - \sigma q = 0. \tag{2.12}$$

Let us begin with the case $D_1 = D_2 = 1$ in order to get an explicit expression for the minimal wave speed. Multiplying the first equation by q , the second by p and subtracting, we get

$$aw_0q^2 + \sigma pq - bp^2 = 0.$$

Hence,

$$\frac{q}{p} = -\frac{\sigma}{2aw_0} \pm \sqrt{\left(\frac{\sigma}{2aw_0}\right)^2 + \frac{b}{aw_0}}. \tag{2.13}$$

Since p and q are positive, we take the sign plus in this equality. We obtain from (2.11):

$$\lambda_1 = \frac{c}{2} - \sqrt{\frac{c^2}{4} + \frac{\sigma}{2} - \sqrt{\frac{\sigma^2}{4} + abw_0}}, \quad \lambda_2 = \frac{c}{2} + \sqrt{\frac{c^2}{4} + \frac{\sigma}{2} - \sqrt{\frac{\sigma^2}{4} + abw_0}}.$$

Denote

$$c_{01} = 2\sqrt{\sqrt{\frac{\sigma^2}{4} + abw_0} - \frac{\sigma}{2}}.$$

Then $\lambda_2 \geq \lambda_1 > 0$ for $c \geq c_{01}$. Consider now the case $D_1 \neq D_2$. In what follows we will denote the minimal speed by c_0 . Notation c_{01} used here indicates that this value is obtained for $D_1 = D_2 = 1$.

Lemma 2.1. *There exists a value $c_0 > 0$ such that for $c > c_0$ the system of equations (2.11), (2.12) with respect to λ has exactly three real positive solutions $\lambda_1, \lambda_2, \lambda_3$, $\lambda_1 < \lambda_2 < \lambda_3$, and $\lambda_{1,2} \in (0, c/D_1)$.*

Proof. Equating the determinant of this system to 0, we get the equation

$$\lambda(D_1\lambda - c)(D_2\lambda^2 - c\lambda - \sigma) = abw_0. \tag{2.14}$$

Denote by $F(\lambda, c)$ the function in the left-hand side of this equation. Then $F(\lambda_i^*, c) = 0$, where

$$\lambda_1^* = \frac{c}{2D_2} - \sqrt{\frac{c^2}{4D_2^2} + \frac{\sigma}{D_2}} < 0, \quad \lambda_2^* = 0, \quad \lambda_3^* = \frac{c}{D_1}, \quad \lambda_4^* = \frac{c}{2D_2} + \sqrt{\frac{c^2}{4D_2^2} + \frac{\sigma}{D_2}}.$$

Let us note λ_3^* can be less, equal or larger than λ_4^* . Set $\lambda_m = \min(\lambda_3^*, \lambda_4^*)$. Then $F(\lambda, c) > 0$ and $\partial F(\lambda, c)/\partial c \geq \epsilon > 0$ for all $0 < \lambda < \lambda_m$, $c > 0$, and some ϵ , that can be checked by straightforward calculations. Since $F(0, c) = F(\lambda_m, c) = 0$, then the function $F(\lambda, c)$ has a maximum $F_m(c)$ in the interval $0 < \lambda < \lambda_m$. Since $F_m(c)$ is an increasing function, then there exists a value c_0 such that $F_m(c) > abw_0$ for $c > c_0$ and $F_m(c) < abw_0$ for $c < c_0$. The assertion of the lemma follows. \square

2.2. Wave existence for $h = 0$

Lemma 2.2. *Suppose that $c > c_0$. Then for any $k_1, k_2 > 0$, the function $z(x) = (z_1(x), z_2(x))$, where*

$$\begin{aligned} z_1(x) &= \min(v_1(x), w_0), & z_2(x) &= \min(v_2(x), bw_0/\sigma), \\ v_1(x) &= k_1e^{-\lambda_1x} + k_2e^{-\lambda_2x}, & v_2(x) &= q(k_1e^{-\lambda_1x} + k_2e^{-\lambda_2x}), \end{aligned}$$

$p = 1$, q is given by (2.13), provides the upper function (solution) for system (2.4), (2.5) for $h = 0$.

Proof. Consider functions $v_1(x), v_2(x)$ from the formulation of the theorem for some positive values k_1, k_2 , and q . They provide a positive solution of system (2.7), (2.8) converging to 0 at ∞ and unbounded as $x \rightarrow -\infty$. Substituting them in equations (2.4), (2.5), we get:

$$\begin{aligned} D_1 v_1'' + c v_1' + a(w_0 - v_1)v_2 &= -a v_1 v_2 < 0, \\ D_2 v_2'' + c v_2' + b v_1(\xi) - \sigma v_2 &= 0. \end{aligned}$$

Therefore, $(v_1(x), v_2(x))$ is an upper function for system (2.4), (2.5). Next, the function $u_1 = w_0, u_2 = b w_0 / \sigma$ is a solution of system (2.4), (2.5). Hence, the function $(z_1(x), z_2(x))$ defined in the formulation is an upper function for this system. \square

Lemma 2.3. *Solution $(u_1(x, t), u_2(x, t))$ of the system*

$$\frac{\partial u_1}{\partial t} = D_1 \frac{\partial^2 u_1}{\partial x^2} + c \frac{\partial u_1}{\partial x} + a(w_0 - u_1)u_2, \quad (2.15)$$

$$\frac{\partial u_2}{\partial t} = D_2 \frac{\partial^2 u_2}{\partial x^2} + c \frac{\partial u_2}{\partial x} + b u_1(x) - \sigma u_2 \quad (2.16)$$

considered on the whole axis $x \in \mathbb{R}$, with the initial condition $u_1(x, 0) = z_1(x), u_2(x, 0) = z_2(x)$, where $(z_1(x), z_2(x))$ is the upper function from Lemma 2.2, is positive for all $t \geq 0$ and monotonically decreases as a function of t (component-wise) for each x fixed.

Proof. It is sufficient to note that (2.15), (2.16) is a monotone system satisfying the comparison theorem. Therefore, the solution with an upper function as initial condition decreases in time. It remains positive since $u_1 = u_2 = 0$ is a stationary solution of this system and $z_i(x) > 0$ for $x \in \mathbb{R}, i = 1, 2$. \square

Lemma 2.4. *Suppose that $c > c_0$. Then there exists a solution $(\hat{v}_1(x), \hat{v}_2(x))$ of system (2.4), (2.5) such that $\hat{v}_i(x_0) < 0$ and $\hat{v}_i(x) > 0$ for all $x \geq x_1, i = 1, 2$ and some $x_0, x_1, x_1 > x_0$.*

Proof. We begin with the linearized system (2.7), (2.8). The function

$$v_1(x) = k_1 e^{-\lambda_1 x} + k_2 e^{-\lambda_2 x}, \quad v_2(x) = q(k_1 e^{-\lambda_1 x} + k_2 e^{-\lambda_2 x})$$

provides its solution converging to 0 as $x \rightarrow \infty$ for any k_1 and k_2 . Let us note that $\lambda_1 < \lambda_2$ since we suppose that $c > c_0$.

For any k_1 and k_2 such that

$$k_1 < 0, \quad k_2 > 0, \quad k_1 + k_2 < 0 \quad (2.17)$$

we have

$$v_1(0) < 0, \quad v_2(0) < 0, \quad v_1(x) > 0, \quad v_2(x) > 0 \text{ for } x \text{ sufficiently large.} \quad (2.18)$$

Set $k_i = \epsilon k_i^0, i = 1, 2$, where k_i^0 satisfy the conditions $k_1^0 < 0, k_2^0 > 0, k_1^0 + k_2^0 < 0$. Then (2.17) and (2.18) hold for any ϵ . If we decrease ϵ , then solution of the nonlinear system (2.4), (2.5) approaches the solution of the linear system (2.7), (2.8). Hence, there are solutions of system (2.4), (2.5) satisfying the assertion of the theorem.

In order to have a more explicit proof of the existence of such solutions, we will use the implicit function theorem. Let us write system (2.4), (2.5) as follows:

$$D_1 u_1'' + c u_1' + a w_0 u_2 - \gamma a u_1 u_2 = 0, \quad (2.19)$$

$$D_2 u_2'' + c u_2' + b u_1 - \sigma u_2 = 0 \quad (2.20)$$

($h = 0$). Then for $\gamma = 0$ we obtain the linear system (2.7), (2.8), and for $\gamma = 1$ the system (2.4), (2.5). We consider system (2.19), (2.20) on the half-axis $x \geq 0$ with the boundary condition

$$u_1(0) = u_1^0, \quad u_2(0) = u_2^0. \quad (2.21)$$

It follows from the implicit function theorem that problem (2.19)–(2.21) has a solution for γ sufficiently small (see below). Set $w_i(x) = \gamma u_i(x), i = 1, 2$. Then

$$D_1 w_1'' + c w_1' + a w_0 w_2 - a w_1 w_2 = 0, \tag{2.22}$$

$$D_2 w_2'' + c w_2' + b w_1 - \sigma w_2 = 0, \tag{2.23}$$

$$w_1(0) = \gamma u_1^0, \quad w_2(0) = \gamma u_2^0. \tag{2.24}$$

Thus, for all sufficiently small γ , we obtain a solution of system (2.4), (2.5) on the half-axis $x > 0$ satisfying the boundary condition (2.24).

It remains to verify that we can apply the implicit function theorem to problem (2.19)–(2.21). In what follows, we will consider the corresponding operator

$$L \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} = \begin{cases} D_1 u_1'' + c u_1' + a w_0 u_2 - \gamma a u_1 u_2 = 0 \\ D_2 u_2'' + c u_2' + b u_1 - \sigma u_2 = 0 \end{cases}$$

acting from the space $\dot{H}_\infty^2(\mathbb{R}_+) = \{u = (u_1, u_2) \in H_\infty^2(\mathbb{R}_+), u_1(0) = u_2(0) = 0\}$ into $L_\infty^2(\mathbb{R}_+)$ [19]. We recall that the norm in these spaces are defined by the equalities

$$\|u\|_{L_\infty^2(\mathbb{R}_+)} = \sup_{x \geq 0} \|u\|_{L^2[x, x+1]}, \quad \|u\|_{H_\infty^2(\mathbb{R}_+)} = \sup_{x \geq 0} \|u\|_{H^2[x, x+1]}.$$

First of all, we show that $\lambda = 0$ does not belong to the essential spectrum of the operator L , that is, this operator satisfies the Fredholm property. The essential spectrum is determined as the set of all complex λ for which the problem

$$D_1 v_1'' + c v_1' + a w_0 v_2 = \lambda v_1, \tag{2.25}$$

$$D_2 v_2'' + c v_2' + b v_1 - \sigma v_2 = \lambda v_2 \tag{2.26}$$

considered on the whole axis, has a nonzero bounded solution. Assuming that $\lambda = 0$ and applying the Fourier transform, we obtain the equalities

$$(-D_1 \xi^2 + ci\xi) \tilde{v}_1 + a w_0 \tilde{v}_2 = 0, \quad (-D_2 \xi^2 + ci\xi - \sigma) \tilde{v}_2 + b \tilde{v}_1 = 0,$$

where \tilde{v}_1 and \tilde{v}_2 are the Fourier transforms of the corresponding functions. Equating the determinant of the matrix of this system to 0, we get

$$(-D_1 \xi^2 + ci\xi)(-D_2 \xi^2 + ci\xi - \sigma) - a b w_0 = 0.$$

Hence

$$D_1 \xi^2 (D_2 \xi^2 + \sigma) - c^2 \xi^2 - a b w_0 = 0, \quad ci\xi (D_1 \xi^2 + D_2 \xi^2 + \sigma) = 0.$$

From the second equation we conclude that $\xi = 0$. Then the first equation leads to a contradiction since $a, b, w_0 > 0$. Thus, we conclude that the essential spectrum does not contain the origin.

Next, consider the eigenvalue problem for equations (2.25), (2.26) on the half-axis $x \geq 0$ with the boundary conditions $v_1(0) = v_2(0) = 0$. This problem has a unique (up to a constant factor) nonzero solution for $\lambda = 0$. Indeed, it is sufficient to set $k_1 = -k_2$ in order to satisfy the boundary conditions. Moreover, a similar solution can be constructed for all sufficiently small real λ .

Let us recall that the index κ of a Fredholm operator is defined as $\kappa = \alpha - \beta$, where α is the dimension of the kernel of the operator and β is the codimension of the image, that is, the number of solvability conditions of the non-homogeneous problem. Both numbers α and β are constant inside each connected component of the complex plane where the operator satisfies the Fredholm property, except possibly for some isolated points (eigenvalues). We will show in Lemma 2.5 below that $\beta = 0$, that is, the non-homogeneous problem is solvable for any right-hand side. In this case, we can apply the implicit function theorem ([20], Thm. 1.20, Chap. 4, p. 233). The lemma is proved. \square

Remark. In the construction of the lower function, it is sufficient that it is positive on some interval. However, it can be verified that it is positive on the half-axis $x \geq 0$. Indeed, its positiveness on bounded intervals follows from the fact that it is close to the solution of the linear problem. Its behavior at infinity is determined by the exponential with the minimal exponent λ_1 . For a more detailed analysis, we can consider weighted spaces with the exponential weight $\exp(\lambda_1 x)$ and apply the implicit function theorem in the weighted space.

Lemma 2.5. *The problem*

$$D_1 v_1'' + cv_1' + aw_0 v_2 = f_1, \quad (2.27)$$

$$D_2 v_2'' + cv_2' + bv_1 - \sigma v_2 = f_2, \quad (2.28)$$

$$v_1(0) = 0, \quad v_2(0) = 0 \quad (2.29)$$

is solvable in $H_\infty^2(\mathbb{R}_+)$ for any $f_1, f_2 \in L_\infty^2(\mathbb{R}_+)$.

Proof. It is sufficient to verify solvability of this problem for $f_1 = 0, f_2 \neq 0$ and for $f_1 \neq 0, f_2 = 0$. Let $f_1 = 0$. Then we can express v_2 from (2.27) and substitute into (2.28), (2.29). Assuming for brevity that $aw_0 = 1$, we obtain the following problem:

$$a_1 v_1'''' + a_2 v_1''' + a_3 v_1'' + a_4 v_1' + a_5 v_1 = f_2, \quad v_1(0) = 0, \quad D_1 v_1''(0) + cv_1'(0) = 0,$$

where

$$a_1 = -D_1 D_2, \quad a_2 = -c(D_1 + D_2), \quad a_3 = \sigma D_1, \quad a_4 = \sigma c, \quad a_5 = b.$$

This problem is solvable if and only if f_2 is orthogonal to all solutions in H^2 of the homogeneous formally adjoint problem ([19], Thm. 4.4, Chap. 6, p. 245 and [21]). The formally adjoint problem is obtained by the change of c to $-c$. Returning back to problem (2.27)–(2.29), we get a formally adjoint problem. Similar to Lemma 2.2 we find solutions of this problem. However, their solutions are growing at ∞ since $\lambda_1, \lambda_2 < 0$ if $c < 0$. Thus, the homogeneous formally adjoint problem has only zero solution, and problem (2.27)–(2.29) is solvable for any f_2 . Similarly, it can be proved in the case $f_1 \neq 0, f_2 = 0$. \square

Lemma 2.6. *Suppose that $c > c_0$. Then the function $\zeta(x) = (\zeta_1(x), \zeta_2(x))$, where*

$$\zeta_1(x) = \max(v_1(x), 0), \quad \zeta_2(x) = \max(v_2(x), 0),$$

and the function $(v_1(x), v_2(x))$ is a solution in Lemma 2.4, is a lower function (solution) for system (2.4), (2.5) ($h = 0$).

The proof of the lemma directly follows from Lemma 2.4 and the construction of the function $\zeta(x)$.

Theorem 2.7. *Suppose that $c > c_0$ and $h = 0$. Then problem (2.4)–(2.6) has a monotonically decreasing (component-wise) solution.*

Proof. We will use the method of upper and lower functions. The existence of an upper function $z(x)$ follows from Lemma 2.2, and the existence of a lower function $\zeta(x)$ from Lemma 2.6. Due to the asymptotic behavior of these functions at infinity (cf. Lem. 2.2), we can choose a real number x_0 such that

$$\zeta(x) < z(x + x_0), \quad x \in \mathbb{R},$$

where this inequality is understood component-wise. Consider the solution $\hat{u}(x, t) = (\hat{u}_1(x, t), \hat{u}_2(x, t))$ of system (2.15), (2.16) with the initial condition $\hat{u}(x, 0) = z(x + x_0)$. Then $\hat{u}(x, t)$ is a monotonically decreasing function with respect to t for each x (component-wise), and

$$\zeta(x) < \hat{u}(x, t), \quad x \in \mathbb{R}, \quad t \geq 0.$$

Therefore, there exists a limiting function

$$U(x) = \lim_{t \rightarrow \infty} u(x, t).$$

It satisfies problem (2.4)–(2.6), and it is monotonically decreasing with respect to x . □

Corollary 2.8. *Problem (2.4)–(2.6) has a monotonically decreasing (component-wise) solution for $c = c_0$.*

Proof. The existence of such solution can be proved passing to the limit as $c \rightarrow c_0$. □

2.3. The case $h \neq 0$

Substitute solution (2.10) into equations (2.7), (2.8):

$$D_1 \lambda^2 p - c \lambda p + a w_0 q = 0, \tag{2.30}$$

$$D_2 \lambda^2 q - c \lambda q + b p e^{-\lambda h} - \sigma q = 0. \tag{2.31}$$

Equating the determinant of this system to 0, we obtain the equation with respect to λ :

$$(D_1 \lambda^2 - c \lambda)(D_2 \lambda^2 - c \lambda - \sigma) = a b w_0 e^{-\lambda h}. \tag{2.32}$$

Equation (2.32) with respect to λ has from two to four solutions (Fig. 1, right). We are interested in its positive solutions in the interval $0 < \lambda < c/D_1$. The positivity of λ provides decay of functions (2.10) at infinity. From equation (2.30) we deduce that $q/p = \lambda(c - D_1 \lambda)/(a w_0)$. Therefore, p and q have the same sign if λ belongs to the indicated interval.

It can be easily verified that the function $F(\lambda, c) = (D_1 \lambda^2 - c \lambda)(D_2 \lambda^2 - c \lambda - \sigma)$ decreases with respect to c in the interval $0 < \lambda < c/D_1$. Therefore, there exists such value c_0 that equation (2.32) has a single solution λ_0 in the interval $0 < \lambda < c/D_1$ for $c = c_0$, there are no such solutions for $c < c_0$, and there are two solutions λ_1, λ_2 , $0 < \lambda_1 < \lambda_0 < \lambda_2$ for $c > c_0$. Hence, the following lemma holds.

Lemma 2.9. *There exists a value $c_0 > 0$ such that for $c > c_0$ the system of equations (2.30), (2.31) with respect to λ has exactly three real positive solutions $\lambda_1, \lambda_2, \lambda_3$, $\lambda_1 < \lambda_2 < \lambda_3$, and $\lambda_{1,2} \in (0, c/D_1)$.*

We can now proceed to the construction of upper and lower functions. Lemmas 2.2 and 2.3 remain applicable. Therefore, we can affirm the existence of an upper function. Some changes should be done in the proof of Lemma 2.5.

Lemma 2.10. *There exists $h_0(c) > 0$ such that for all $h \in (0, h_0(c)]$ the problem*

$$D_1 v_1'' + c v_1' + a w_0 v_2 = f_1, \tag{2.33}$$

$$D_2 v_2'' + c v_2' + b v_1(x + h) - \sigma v_2 = f_2, \tag{2.34}$$

$$v_1(0) = 0, \quad v_2(0) = 0 \tag{2.35}$$

is solvable in $H_\infty^2(\mathbb{R}_+)$ for any $f_1, f_2 \in L_\infty^2(\mathbb{R}_+)$.

Proof. Two properties should be verified: (1) the essential spectrum does not cross the origin if h decreases from the given value to 0. Then the index of the operator κ does no change, and $\kappa = 1$ as for $h = 0$. Moreover, its α and β characteristics can change only in isolated points, (2) $\alpha = 1$. Then $\beta = 0$.

The essential spectrum is determined as the set of all complex λ for which the problem

$$D_1 v_1'' + c v_1' + a w_0 v_2 = \lambda v_1, \tag{2.36}$$

$$D_2 v_2'' + c v_2' + b v_1(x + h) - \sigma v_2 = \lambda v_2 \tag{2.37}$$

considered on the whole axis, has a nonzero bounded solution. Assuming that $\lambda = 0$ and applying the Fourier transform, we obtain the equalities

$$(-D_1\xi^2 + ci\xi)\tilde{v}_1 + aw_0\tilde{v}_2 = 0, \quad (-D_2\xi^2 + ci\xi - \sigma)\tilde{v}_2 + b\tilde{v}_1e^{-i\xi h} = 0,$$

where \tilde{v}_1 and \tilde{v}_2 are the Fourier transforms of the corresponding functions. Equating the determinant of the matrix of this system to 0, we get

$$(-D_1\xi^2 + ci\xi)(-D_2\xi^2 + ci\xi - \sigma) - abw_0e^{-i\xi h} = 0$$

(cf. (2.32)). Hence,

$$D_1\xi^2(D_2\xi^2 + \sigma) - c^2\xi^2 - abw_0\cos(\xi h) = 0, \quad c\xi(D_1\xi^2 + D_2\xi^2 + \sigma) + abw_0\sin(\xi h) = 0. \quad (2.38)$$

There is such $h_0 > 0$ that this system does not have solutions for any $0 \leq h < h_0$. Indeed, if $abw_0h < c\sigma$, then the second equation has a unique solution $\xi = 0$. Then the first equation leads to a contradiction. Hence, $h_0 \geq c\sigma/(abw_0)$.

It remains to verify that the homogeneous problem (2.33)–(2.35) has a unique linearly independent solution. Since equation (2.32) has three positive solutions $\lambda_1 < \lambda_2 < \lambda_3$, general solution of system (2.33), (2.34) has the following form:

$$v(x) = k_1 \begin{pmatrix} p_1 \\ q_1 \end{pmatrix} e^{-\lambda_1 x} + k_2 \begin{pmatrix} p_2 \\ q_2 \end{pmatrix} e^{-\lambda_2 x} + k_3 \begin{pmatrix} p_3 \\ q_3 \end{pmatrix} e^{-\lambda_3 x},$$

where $q_i/p_i = (\lambda_i^2 - c\lambda_i)/(aw_0)$, $i = 1, 2, 3$. Since the right-hand sides of these equalities are different for different λ_i , then there are two linearly independent vectors (p_i, q_i) . From the boundary condition $v(0) = 0$, we express k_1 and k_2 through k_3 and obtain a unique linearly independent solution of the problem (2.33)–(2.35). Since $\lambda_1 < \lambda_2, \lambda_3$, then the sign of the solution at infinity is determined by the sign of p_1 (the same as q_1). The lemma is proved. \square

Remark. Let us note that for h sufficiently large, system of equations (2.38) can have a solution (Fig. 1, left) signifying that the essential spectrum passes through the origin. Moreover, equation (2.32) can have two positive solutions in the interval $0 < \lambda < c$ (Fig. 1, right). From equations (2.38) we get the equality

$$\xi^2(D_1\xi^2 + c^2)\left((D_2\xi^2 + \sigma)^2 + c^2\right) = (abw_0)^2.$$

It has a single solution ξ^2 depending on c . Having found this solution, we can determine a sequence of values of h for which equations (2.38) have solution. The minimal positive $h = h_0$ from this sequence satisfies the condition of the lemma.

Theorem 2.11. *Suppose that $c \geq c_0$ and $h \leq h_0(c)$, where c_0 is defined in Lemma 2.9 and $h_0(c)$ in Lemma 2.10. Then problem (2.4)–(2.6) has a monotonically decreasing (component-wise) solution.*

2.4. The case $h = c\tau$

In this case we get the equation

$$(D_1\lambda^2 - c\lambda)(D_2\lambda^2 - c\lambda - \sigma) = abw_0e^{-c\lambda\tau} \quad (2.39)$$

instead of equation (2.32). Since the function $F(\lambda, c)$ increases with respect to c in the interval $0 < \lambda < c$, and the exponential in the right-hand side decreases, then the conclusions above about the existence of the minimal speed c_0 remain valid.

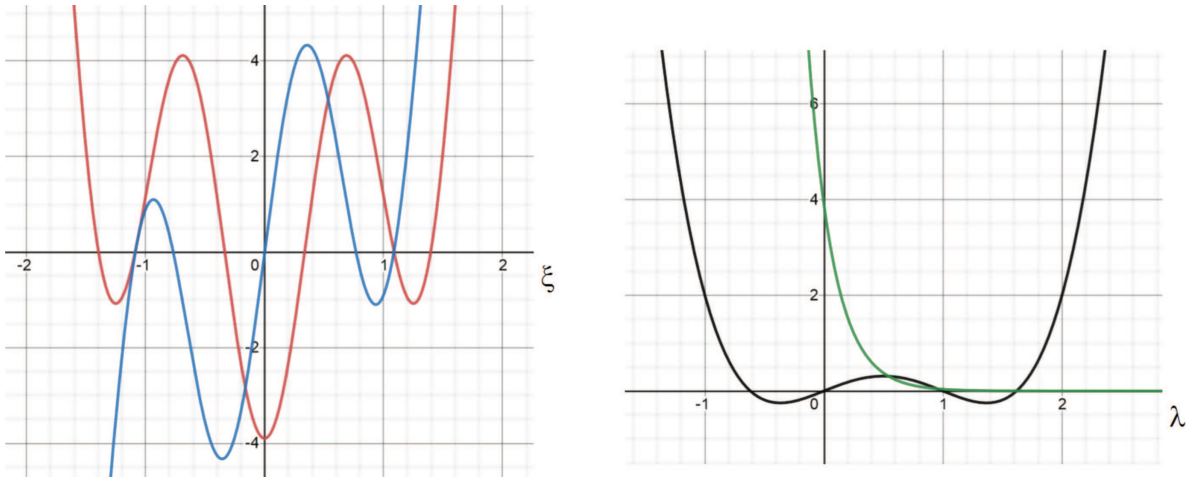


FIGURE 1. Graphical solution of equations (2.38) (left): both functions vanish for the same value of ξ . Graphical solution of equation (2.32) (right): there are two positive solutions in the interval $0 < \lambda < c$. The values of parameters are as follows: $c = 1, \sigma = 1, h = 4.67, abw_0 = 3.9, D_1 = D_2 = 1$.

Lemma 2.12. *There exists a value $c_0 > 0$ such that for $c > c_0$ the system of equations (2.39) with respect to λ has exactly three real positive solutions $\lambda_1, \lambda_2, \lambda_3$, $\lambda_1 < \lambda_2 < \lambda_3$, and $\lambda_{1,2} \in (0, c/D_1)$.*

We now obtain the following theorem as a corollary of Theorem 2.11.

Theorem 2.13. *Suppose that $c \geq c_0$ and $\tau \leq \tau_0(c)$, where c_0 is defined in Lemma 2.9, $\tau_0(c) = h_0(c)/c$, and $h_0(c)$ is defined in Lemma 2.10. Then problem (2.1)–(2.3) has a monotonically decreasing (component-wise) solution.*

3. LIMITING MODEL WITHOUT DIFFUSION

3.1. Analytical estimate of the wave speed

Linearizing system (1.6), (1.7) at ∞ , we obtain the system

$$cw' + aw_0v = 0, \tag{3.1}$$

$$Dv'' + cv' + bw(\xi + c\tau) - \sigma v = 0. \tag{3.2}$$

We look for the solution in the form

$$w(\xi) = pe^{-\lambda\xi}, \quad v(\xi) = qe^{-\lambda\xi}.$$

Then

$$-c\lambda + aw_0q = 0, \tag{3.3}$$

$$Dq\lambda^2 - cq\lambda + bpe^{-\lambda c\tau} - \sigma q = 0. \tag{3.4}$$

We express p from equation (3.3) and substitute in equation (3.4):

$$(D\lambda^2 - c\lambda - \sigma)c\lambda e^{\lambda c\tau} = -abw_0. \tag{3.5}$$

Set $\mu = c\lambda$. Then

$$\left(D\frac{\mu^2}{c^2} - \mu - \sigma\right)\mu e^{\mu\tau} = -abw_0$$

and, hence,

$$c^2 = \frac{D\mu^3 e^{\mu\tau}}{\mu(\mu + \sigma)e^{\mu\tau} - abw_0} \equiv F(\mu).$$

There exists $c_0 > 0$ such that this equation has two solutions μ for any $c > c_0$. The minimal wave speed c_0 is given by the equality

$$c_0^2 = \min_{\mu > 0} \frac{D\mu^3 e^{\mu\tau}}{\mu(\mu + \sigma)e^{\mu\tau} - abw_0}. \quad (3.6)$$

Example. We find the minima of these functions for different values of τ and determine the wave speed:

$$\tau = 0 : \mu = 4.57, F(\mu) = 0.00618, c = 0.077 \quad (\text{numerical value } 0.075),$$

$$\tau = 1 : \mu = 1.89, F(\mu) = 0.00171, c = 0.041 \quad (\text{numerical value } 0.039),$$

$$\tau = 2 : \mu = 1.29, F(\mu) = 0.00098, c = 0.031 \quad (\text{numerical value } 0.029).$$

The corresponding numerical values are obtained in numerical simulations of system (1.1)–(1.3) presented in the next section.

We note from formula (3.6) that the wave speed depends on \sqrt{D} , as usually for reaction-diffusion problems. It depends on the product ab , and this dependence is weak.

3.2. Existence of waves for $D_1 = 0$

We begin with some estimates of solutions of problem (2.1)–(2.3) in order to consider the limiting case $D_1 \rightarrow 0$. We need to estimate the second derivative w'' independently of D_1 . Consider this question in a more general setting.

Proposition 3.1. *Suppose that solution $w(x)$ of the system of equations*

$$Dw'' + cw' + F(w, w_h) = 0 \quad (3.7)$$

on the whole axis, where $w = (w_1, \dots, w_n)$, $F = (F_1, \dots, F_n)$, D is a diagonal matrix with positive diagonal elements d_i , $w_h(x) = w(x + h)$ satisfies the estimate $\sup_{x \in \mathbb{R}} |w(x)| \leq M$, where M is a positive constant independent of the values d_i . Moreover, assume that $|F|, |\partial F_i / \partial u_j| \leq K_1$ for $|w| \leq M$, $i, j = 1, \dots, n$ with some positive constant K_1 independent of d_i . Then the following estimate

$$\sup_{x \in \mathbb{R}} |w''(x)| \leq K_2 \quad (3.8)$$

holds for any fixed $c \geq \epsilon > 0$ with some constant K_2 independent of d_i and depending on ϵ .

Proof. Consider, for certainty, the first equation of system (3.7). Let x_0 be the point of maximum of the function $w_1'(x)$. Then $w_1''(x_0) = 0$, and $|w_1'(x_0)| \leq M/\epsilon$. Let us note that the solution is supposed to be bounded. Therefore, its derivative converges to 0 at infinity, at least along some sequence of x . The same estimate can be obtained at each maximum of the derivative providing the estimate for all $x \in \mathbb{R}$. Similar estimates can be obtained for other components of the vector $w'(x)$. Differentiating the first equation with respect to x and applying the same approach, we obtain the estimate of the second derivative. \square

Theorem 3.2. *Suppose that $c \geq c_0$, where c_0 is defined by equality (3.6), and $\tau \leq \tau_0(c)$, where $\tau_0(c)$, is defined in Theorem 2.13. Then problem (1.6)–(1.8) has a monotonically decreasing (component-wise) solution.*

Proof. Let us note that the minimal speed $c_0 = c_0(D_1)$ determined in Lemma 2.1 converges to the minimal speed $c_0 = c_0(0)$ in equality (3.6) as $D_1 \rightarrow 0$. Therefore, for any $c > c_0(0)$ and D_1 sufficiently small, $c > c_0(D_1)$. The existence of waves for such $D_1 > 0$ follows from Theorem 2.13. We will consider below the limit $D_1 \rightarrow 0$ for the fixed value of c and, consequently, prove the wave existence for $D_1 = 0$. Having proved the wave existence for any $c > c_0(0)$, we can conclude about the existence of waves for $c = c_0(0)$ passing to the limit. In order to prove the convergence of solutions as $D_1 \rightarrow 0$, we will begin with the convergence on compact subintervals of the form $[-K, K]$, and pass to the limit $K \rightarrow \infty$.

For $\varepsilon \in (0, 1]$, let $D_1 = \varepsilon$ and $(w_\varepsilon, v_\varepsilon)$ denote the family of solutions from Theorem 2.13. As the system does not depend explicitly on ξ , then we can for definiteness fix its position in the ξ -space by imposing the condition $w_\varepsilon(0) = \frac{1}{2}w_0$.

Consider a sequence $\{\varepsilon_l\}_{l=1}^{l=\infty}$ such that $\varepsilon_l > 0$ and $\lim_{l \rightarrow \infty} \varepsilon_l = 0$ and the corresponding sequence of solutions $(w_l, v_l) := (w_{\varepsilon_l}, v_{\varepsilon_l})$, $l = 1, 2, \dots$. From Proposition 3.1, it follows that these solutions are uniformly bounded in \mathbb{R} together with their third derivatives independently of D_1 .

Using the Arzela–Ascoli lemma we conclude that on every interval $I_K = [-K, K]$, $K > 0$, we can find a subsequence $\{k_l\}_{l=1}^{l=\infty}$ and the corresponding subsequence $\{\varepsilon_{k_l}\}_{l=1}^{l=\infty}$ such that the functions (w_{k_l}, v_{k_l}) converge to some limiting function (w^0, v^0) together with their second derivatives. Since all functions in the sequence $(w_{k_l}(\xi), v_{k_l}(\xi))$ tend to the same limits as $\xi \rightarrow \pm\infty$. This, together with the fact that their derivatives (up to the third order) are uniformly bounded implies the convergence to the limiting function in $C^2(\mathbb{R})$. This limiting function satisfies problem (1.6)–(1.8). The theorem is proved. \square

4. NUMERICAL SIMULATIONS OF INFECTION PROGRESSION

4.1. Three stages of infection progression

Numerical simulations of system (1.1)–(1.3) are carried out in a bounded interval $0 < x < L$ with the homogeneous Neumann boundary conditions for V : $x = 0, L$: $\frac{\partial V}{\partial x} = 0$, and the following initial conditions:

$$\begin{aligned} U(x, 0) &= U_0, \quad I(x, t) = 0, \quad -\tau < t \leq 0, \\ V(x, 0) &= V_0 \text{ for } 0 \leq x \leq x_0 \text{ and } V(x, 0) = 0 \text{ for } x_0 \leq x \leq L. \end{aligned}$$

These initial conditions mean that cell culture initially contains only uninfected cells, and some initial viral load is introduced at the left part of the computational interval. Numerical implementation of the problem is presented in the appendix.

Figure 2 shows an example of numerical simulations of system (1.1)–(1.3) with the spatial distributions of virus and infected cells in consecutive moments of time. The distance between the curves is not the same in the beginning of the simulation because of decaying oscillations due to time delay. Analysing the evolution of virus concentration distribution in space and in time, we can identify three stages of infection progression. At the first stage, virus does not yet reproduce due to the time delay in its replication. It diffuses in space while the total viral load decays because of its death. This first stage can be seen in Figure 4 as a linear decay of the function $\log V_T(t)$, where $V_T(t) = \int_0^L V(x, t) dx$ is the total viral load. This decay corresponds to exponential decrease of the function $V_T(t)$. At the next stage, initially infected cells begin to reproduce new virus particles leading to explosive growth of its total concentration. The last stage of infection progression corresponds to the propagation of infection front with a constant speed and linear growth of the total virus load. It can be seen as a logarithmic growth in Figure 4 (right).

If infected cells die after some time ($\beta > 0$), then their distribution has a spike-like shape, or a pulse moving along the cell culture (Fig. 3, upper left). Virus distribution has a similar form. In this case, the total virus concentration remains constant at the third stage of infection progression (Fig. 4, left).

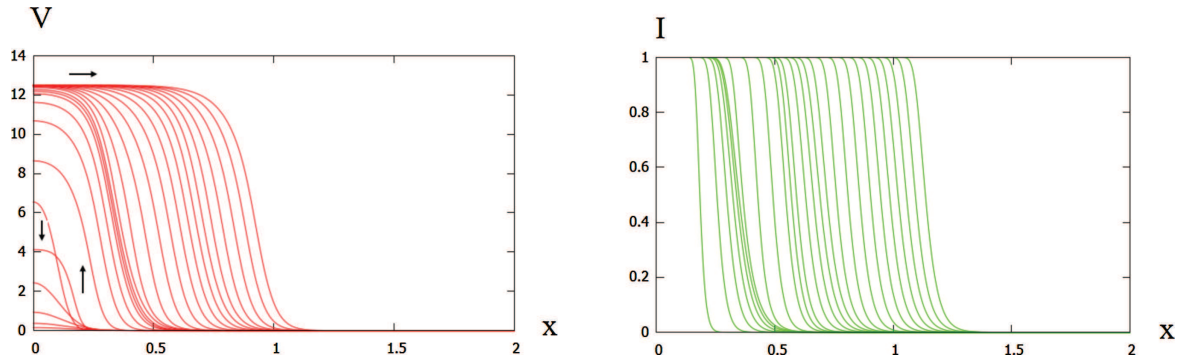


FIGURE 2. The distributions of virus concentration V (left) and of infected cells I (right) in numerical simulations of system (1.1)–(1.3). Different curves correspond to consecutive moments of time (every 2 time units). The values of parameters: $a = 10, b = 5, \beta = 0, \sigma = 0.4, D = 0.001, L = 2, \tau = 10, U_0 = 1, V_0 = 10, x_0 = 0.1$. The arrows in the left image show three stages of infection progression: virus concentration decay during time delay in its replication, explosive growth in its concentration when infected cells begin to reproduce new viral particles, propagation of infection wave along the cell culture.

4.2. Comparison with the experiments

Conventional multiplicity of infection (MOI) test is based on the experimental evaluation of virus spread in cell culture. We describe the experimental results on the spread of coronavirus in the culture of cilia cells [16] and of poliovirus [11]. Virus spread in the cilia cells occurs preferentially through the apical surface. The dependence of virus titer on time $V_T(t)$ has three stages: it decreases till time 10 h, then rapidly increases from 10 to 20 h, and finally its growth rate is slower after 20 h. The first stage corresponds to time delay of virus replication inside cells. New viruses are not yet produced, and the initial viral load decays due to virus death. Two other stages correspond to virus replication. During the second stage, the initial virus load (decreased in the first stage) converges to the wave. The last stage corresponds to the wave propagation.

The choice of the model and parameters. Let us note that there are two different wave propagation regimes from the point of view of virus production: with or without death of infected cells. If infected cells die ($\beta > 0$), then they form a spike of a constant size during the wave propagation. Therefore, the total virus production is also constant in this case, $V_T(t) = \int_0^L V(x, t) dx \rightarrow \text{const}$. This case corresponds to some experimental data (Fig. 4, left) but not to coronavirus in the culture of cilia cells (Fig. 4, right).

Suppose now that infected cells do not die ($\beta = 0$). Then their concentration remains constant behind the wave ($I = w_0$). Since the wave propagates with a constant speed, then the total number of infected cells grows linearly in time, $I(t) = ct$, where c is the wave speed. Integrating equation (1.5) with respect to x over the interval $[0, L]$, we obtain an approximate equation:

$$\frac{dV_T}{dt} = cbt - \sigma V_T, \quad V_T(0) = V_0. \tag{4.1}$$

Hence

$$V_T(t) = \left(V_0 + \frac{cb}{\sigma^2} \right) e^{-\sigma t} + \frac{cb}{\sigma} t - \frac{cb}{\sigma^2}. \tag{4.2}$$

Thus, $V_T(t)$ has asymptotically linear growth. This analysis shows that we should consider infection spreading without death of infected cells in order to describe the experimental results for coronavirus (Fig. 4, right) and with death of infected cell for poliovirus (Fig. 4, left).

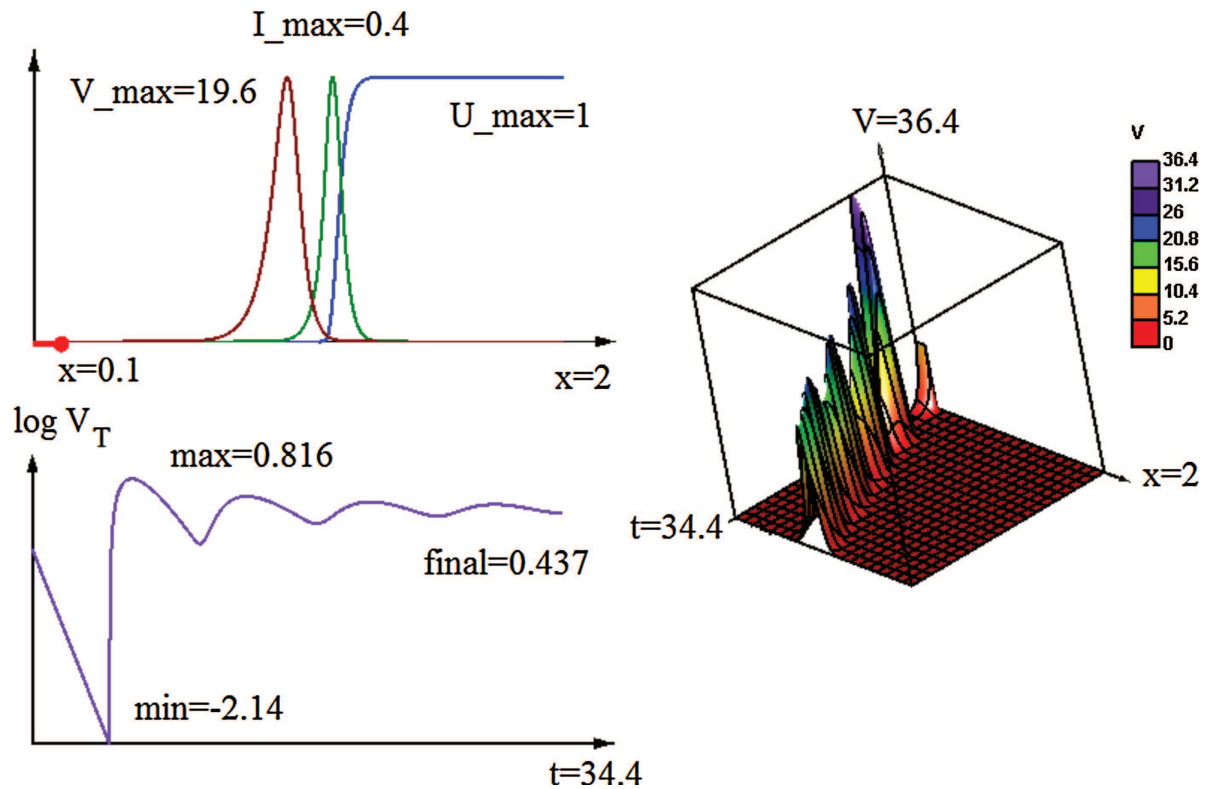


FIGURE 3. Numerical simulations of system (1.1)–(1.3) in the case where infected cells die with certain rate. Concentration distributions (*upper left*) are different in comparison with Figure 2: the virus distribution (brown curve) and the concentration of infected cells (green curve) have a specific pulse-like form. The same virus distribution as a function of x and t is shown in the *right figure*. We can notice decaying oscillations of the maximal concentration. The corresponding total viral load $\log V_T(t)$ also oscillates (*lower figure*). The values of parameters are as follows: $a = 10, b = 100, \beta = 1, \sigma = 1, D = 0.001, L = 2, \tau = 5, U_0 = 1, V_0 = 10, x_0 = 0.1$. A small red interval on the x -axis in the upper left figure shows the support of the initial viral load x_0 .

In the case of coronavirus, viral load decreases during first 10 h [16]. Hence, we set $\tau = 10$ h. Virus diffusion rate varies in the limit from 10^{-4} cm^2/h to 10^{-3} cm^2/h . We take the maximal value $D = 10^{-3}$ cm^2/h . We will discuss this choice below. The value of σ is determined by the decay rate of V_T during the first stage. We get $\sigma = 0.1 \div 0.2$ 1/h. There are two free parameters a and b . The rate of V_T growth during the second stage strongly depends on b . The wave speed at the third stage depends on the product ab but this dependence is weak. The initial viral load is taken from the experimental data.

Comparison of modelling and experiment. We describe this comparison in more detail in the case of coronavirus in the culture of cilia cells (Fig. 4, right). The function $\log V_T(t)$ in modelling shows the same three stages as in the experiment: exponential decay (linear in the log scale), exponential growth (linear in the log scale), linear growth (logarithmic in the log scale). The value $V_T(0)$ is chosen in such a way that it coincides with the experimental value. The value $V_T(t_1)$, $t_1 = 10$ h is controlled by the value of σ . We set $\sigma = 0.1$ in order to have the modelling value larger than the experimental one in order to minimize the difference between them for larger times. The growth rate at the second stage is determined by the parameter b . We choose it in such a way that $V_T(t_2)$, $t_2 = 20$ h is larger than the experimental value in order to minimize the difference later.

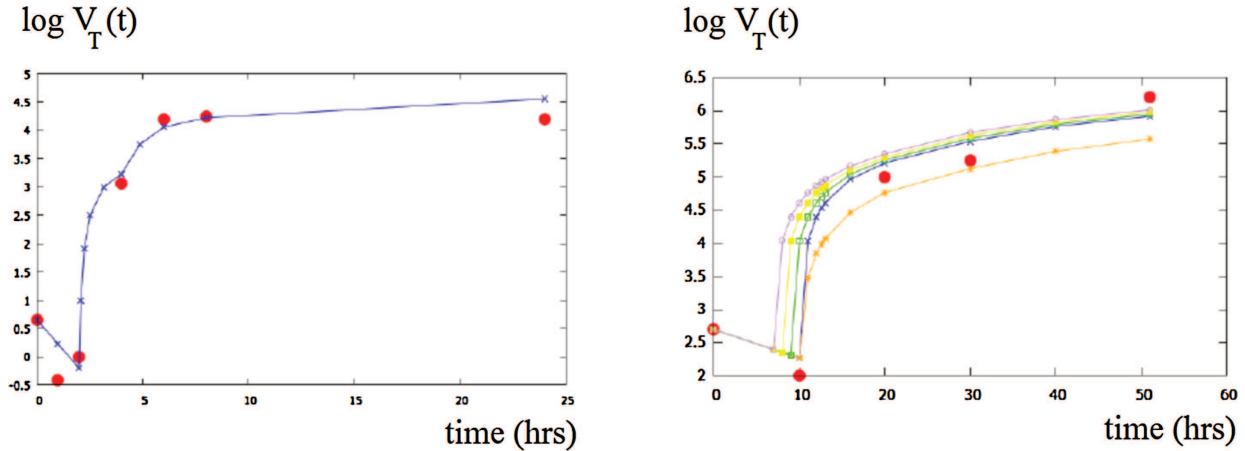


FIGURE 4. *Left:* comparison of the experimental data (red dots) for the poliovirus virus [11] with the function $\log V_T(t)$ obtained in numerical simulations of system (1.4), (1.5) (blue curve) with the values of parameters $a = 0.01, b = 80\,000, \beta = 0.1, \sigma = 1, D = 0.001, L = 2, \tau = 2, U_0 = 1, V_0 = 45, x_0 = 0.1$. *Right:* comparison of the experimental data (red points) for the SARS-CoV virus in the culture of epithelial cells [16] and $\log V_T(t)$ for the solution of problem (1.1)–(1.3) (blue curve), and for the problem with distributed delay where $h = 1$ (green curve), $h = 2$ (yellow curve), and $h = 3$ (purple curve) with the values of parameters $a = 0.01, b = 80\,000, \beta = 0, \sigma = 0.1, D = 0.001, L = 2, \tau = 10, U_0 = 1, V_0 = 5000, x_0 = 0.1$. The lower curve is obtained for the model with interferon (4.4)–(4.7) with the same values of parameters as in Figure 5.

At the last stage, the growth rate in modelling is less than in the experiment. Since the wave speed weakly depend on parameters a and b , their variation does not allow us to improve the accuracy. The wave speed is proportional to \sqrt{D} , but we take the maximal physically justified value of the diffusion coefficient. Therefore, we cannot use it to increase the wave speed. If we increase b , then we can decrease the difference at $t = 50$ h but this will increase the difference at $t = 20$ h and $t = 30$ h.

Thus, comparison of modelling and experiment show that growth rate in modelling at the last stage is less than in the experiment. Moreover, we can see from (4.2) that main term of $\log V_T(t)$ is $\log t$ in the 1D model. It is independent of the parameters of the model and cannot be increased for this model. We will see below that the growth rate is larger in the 2D model.

Distributed delay. In the case of distributed delay in the virus replication rate, equation (1.3) in system (1.1)–(1.3) is replaced by the equation

$$\frac{\partial V}{\partial t} = D \frac{\partial^2 V}{\partial x^2} + J_h(x, t) - \sigma V, \tag{4.3}$$

where

$$J_h(x, t) = \frac{b}{2h} \int_{t-\tau-h}^{t-\tau+h} I(x, s) ds.$$

This integral describes distributed delay with a uniform distribution in the interval $[t - \tau - h, t - \tau + h]$. We recover the model with a point-wise delay in the limit of small h . An example of numerical simulations of this model is shown in Figure 4 (right). The total viral load has qualitatively similar behavior as in the case of point-wise delay. However, virus reproduction begins earlier, and the total viral load becomes larger with the increase of h .

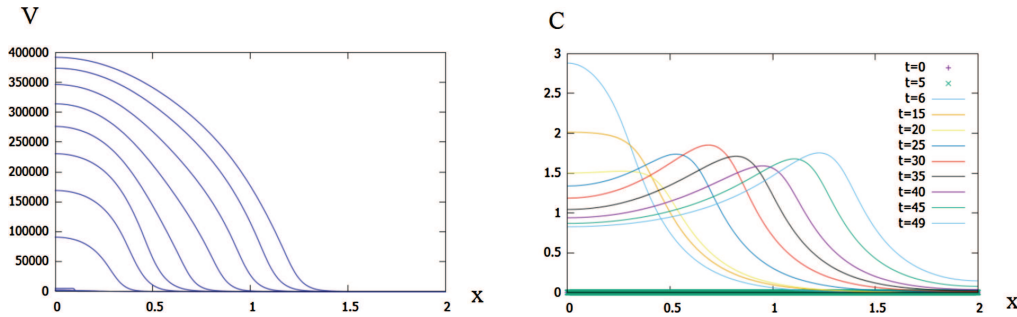


FIGURE 5. Numerical simulations of system (4.4)–(4.7) with the virus concentration distribution (left) and interferon distribution (right) in consecutive moments of time. The values parameters: $a = 0.01, b_1 = 80\,000, b_2 = 13.5, \beta = 0, \sigma_1 = 0.1, \sigma_2 = 3.5, D_1 = 0.001, D_2 = 0.16, V_0 = 5000, C_0 = 0, U_0 = 1, I_0 = 0, k_1 = 1, k_2 = 10^{-5}, \tau_1 = 10, \tau_2 = 5, x_0 = 0.1$. The bold green line in the right image corresponds to the initial concentration of interferon (equal 0).

4.3. Model with interferon

Infected cells produce interferon which downregulates virus replication. In this case, we complete system of equations (1.1)–(1.3) by the equation for the interferon concentration C :

$$\frac{\partial U}{\partial t} = -aUV, \tag{4.4}$$

$$\frac{\partial I}{\partial t} = aUV - \beta I, \tag{4.5}$$

$$\frac{\partial V}{\partial t} = D_1 \frac{\partial^2 V}{\partial x^2} + \frac{b_1}{1 + k_1 C} I_{\tau_1} - \sigma_1 V, \tag{4.6}$$

$$\frac{\partial C}{\partial t} = D_2 \frac{\partial^2 C}{\partial x^2} + \frac{b_2}{1 + k_2 V} I_{\tau_2} - \sigma_2 C. \tag{4.7}$$

The virus replication rate in equation (4.6) is inversely proportional to the interferon concentration C . On the other hand, virus can slow down the interferon production [8, 13]. We take this effect into account in the interferon production rate in equation (4.7). This term contain time delay τ_2 which is different, in general, from the time delay in virus replication.

Figure 5 shows an example of numerical simulations of system (4.4)–(4.7). Virus propagation is qualitatively similar to the case without interferon but the maximal virus concentration decreases. Interferon production follows the progression of infected cells. Its concentration strongly grows at the first stage of infection progression, then it propagates in space with damped oscillations. Let us note that the final value of virus concentration decreases due to the interferon production. However, the speed of infection progression, that is the speed of reaction-diffusion wave remains constant. Such behavior is specific for the monostable case for which the wave speed is determined by linearization at the virus free equilibrium (Sects. 2 and 3). The corresponding total virus load $V_T(t)$ is shown in Figure 4 (right).

4.4. 2D simulations

We present in this section the 2D modification of the system (1.1)–(1.3) by introducing the following equations for uninfected cells U , infected cells I and virus V :

$$\frac{\partial V}{\partial t} = D\Delta V + bI_{\tau} - \sigma V, \tag{4.8}$$

$$\frac{\partial U}{\partial t} = -aUV, \quad (4.9)$$

$$\frac{\partial I}{\partial t} = aUV - \beta I, \quad (4.10)$$

where

$$I_\tau(x, y, t) = \begin{cases} \begin{cases} 0 & t \leq \tau \\ I(x, y, t - \tau) & t > \tau \end{cases} & \text{if } \tau > 0 \\ I(x, y, t) & \text{if } \tau = 0 \end{cases}$$

and we consider Neumann boundary condition for the variable V : $\frac{\partial V}{\partial n} = 0$, where n denotes the normal derivative. We consider here a 2D domain $\Omega = \mathcal{C}(\mathcal{O}, \mathcal{R})$, which is a ball of center $\mathcal{O}(0, 0)$ and a radius $\mathcal{R} = L$, and we take the following initial condition: $U(x, y, 0) = U_0 = 1, I(x, y, 0) = 0$ and

$$V(x, y, 0) = \begin{cases} 0.5V_0(1 + \tanh(500(R - r(x, y)))) & , \quad r(x, y) \leq R \\ 0 & , \quad r(x, y) > R \end{cases}$$

where $r(x, y) = \sqrt{x^2 + y^2}$, and we set $R = \sqrt{x_0/\pi}$ in order to obtain the same initial viral load as in 1D.

Let us note that we consider a smooth function $V(x, y, 0)$ in order to avoid problems due to discontinuity of the solution on unstructured grid. Furthermore, we introduce a fine mesh near the radius R and a coarser mesh elsewhere (see (b) in Figs. 6, 8), and in order to not use a finer grid in all domain, we consider piecewise quadratic (P2) finite-elements instead of piecewise linear (P1) finite-elements. At the end, these simulations were done on a mesh with 79.468 triangles. We use the library PETSc⁸ (the Portable, Extensible Toolkit for Scientific Computation) which is a suite of data structures and routines for the scalable (parallel) solution of scientific applications modeled by partial differential equations. The computations were performed on a Macbook pro 2.2 GHz Intel Core i7, 16 GB of DDR4 2400 MHz RAM and took 00:24:16 over 6 threads.

We compute the viral load $V_T(t) = \int_\Omega V(x, y, t) dx dy$ and we compare the results with the 1D results obtained by FreeFEM code with the same parameters described above, for $\beta = 0$ (Figs. 6, 7) and $\beta = 0.2$ (Figs. 8, 9). In both cases, the total viral load is larger in the 2D case in comparison with the 1D case because the quantity of infected for the former grows in time due to the circular geometry. Though this difference does not seem essential in Figures 6c and 8c due to the log scale, the total viral load is about 3 times larger in the 2D case.

5. DISCUSSION

Experimental studies of viral infection progression in cell culture allow the assessment of the efficacy and the mechanisms of virus penetration the host cells and its replication inside the cells, both processes being important for the determination of virus virulence. The duration of time delay in virus replication, clearly seen in the experiments, can depend on virus and host cells. This time delay can be taken into account in the optimization of anti-viral treatment. Furthermore, interferon produced by infected cells downregulates virus replication while some viruses (including coronavirus) can decrease the rate on interferon production [8, 13]. Such experiments represent a necessary stage for further investigation of viral infection in the human organism where it interacts with the immune system essentially increasing the complexity of this process. Mathematical modelling of infection development in cell cultures allows a better understanding of these processes and their quantitative description.

Mathematical models of viral infection in cell culture. Viral plaque growth in cell culture can be described as a reaction-diffusion wave which converts uninfected cells into infected and eventually dead cells due to virus production and diffusion. Surprisingly, there are only few works where this process is modelled, some of them with continuous models [10, 22] and some other with individual based models [1, 15]. The advantage

⁸<https://www.mcs.anl.gov/petsc/>.

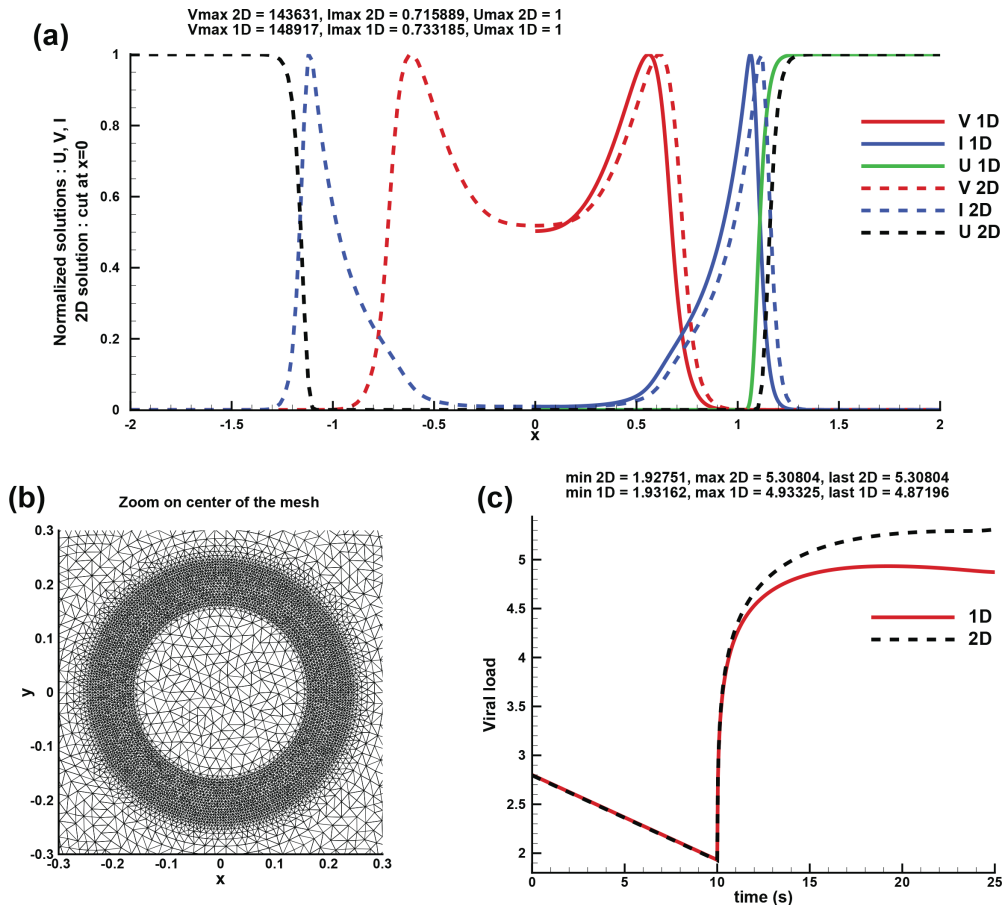


FIGURE 6. Comparison between the results obtained in 1D (solid lines) and in 2D (dashed lines) with FreeFEM (a) normalized solution V (log scale), I and U at $t = 25s$, (b) zoom on the center of the mesh used for the 2D case and (c) the total viral load $\log V_T(t)$ for $\beta = 0$.

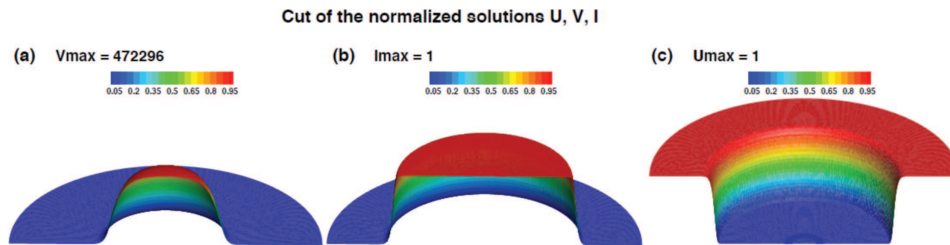


FIGURE 7. The cut of the normalized solutions of V (a), I (b) and U (c) at $t = 25s$ for $\beta = 0$.

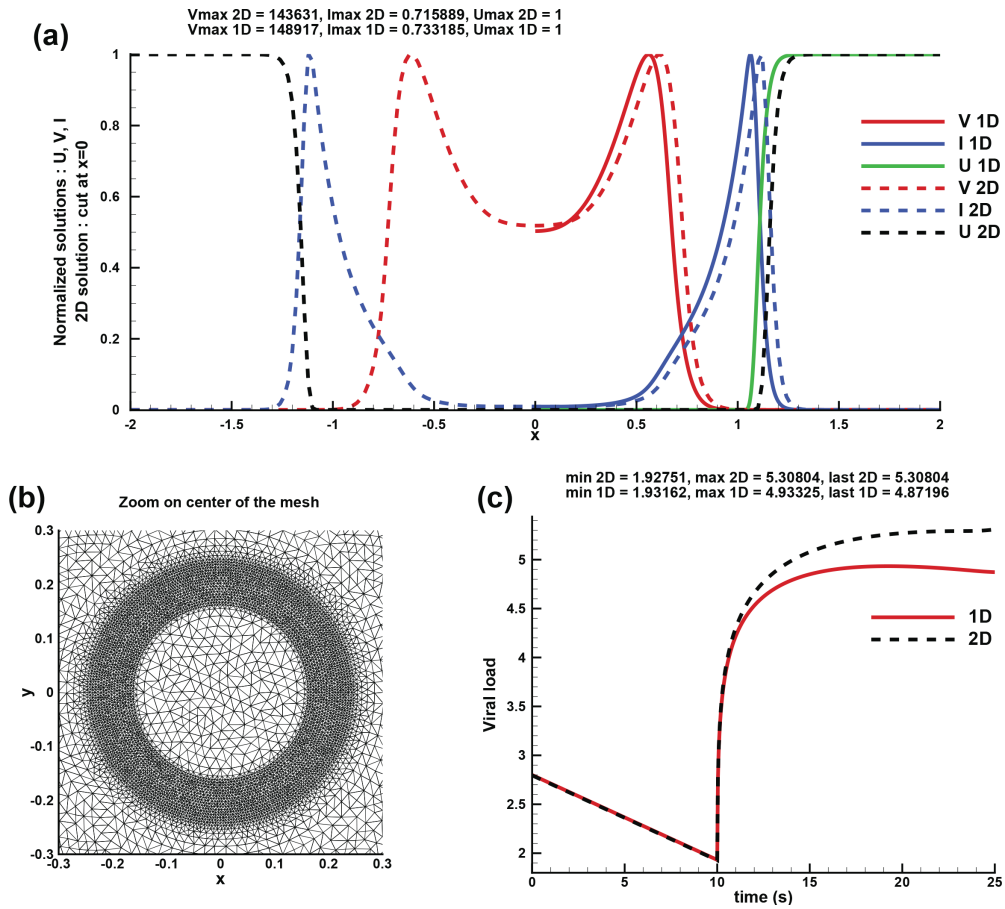


FIGURE 8. Comparison between the results obtained in 1D (solid lines) and in 2D (dashed lines) with FreeFEM (a) normalized solution V (log scale), I and U at $t = 25s$, (b) zoom on the center of the mesh used for the 2D case and (c) the total viral load $\log V_T(t)$ for $\beta = 0.2$.

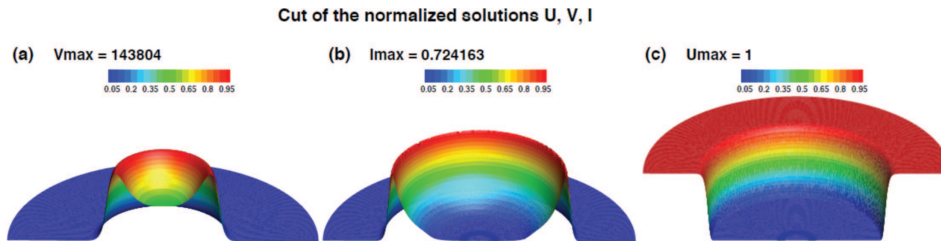


FIGURE 9. The cut of the normalized solutions of V (a), I (b) and U (c) at $t = 25s$ for $\beta = 0.2$.

of reaction-diffusion models is that they allow a theoretical investigation of infection waves, including their existence and the speed of propagation. The only delay reaction-diffusion model we are aware of differs from our model by the equation for infected cells [10]. It contains the first time delay taking into account latently infected cells before they become infectious and the second time delay for the death of infected cells. This second (negative) delay term needs to be controlled to avoid the negativity of solutions. Contrary to this previous work, we consider time delay in the virus replication term and, this term being positive, it preserves the positiveness of solutions and the applicability of powerful mathematical methods based on the maximum principle and comparison theorems. We use them to prove the existence of waves. Let us note that this question is not only of pure mathematical interest because it allows us to determine the minimal wave speed, which is particularly important for the description of behavior of solutions. We discuss this question in the next paragraph.

Individual based models allow a more detailed description of intracellular regulation of virus replication and interferon production. It is also possible to consider more complete continuous models and hybrid discrete-continuous models [5]. There is an increasing interest for all these modelling approaches in relation with the new coronavirus disease.

Existence and stability of waves. Existence of waves described by monotone reaction-diffusion systems is studied in the case without time delay (see [20] and the references therein). In general, the introduction of time delay essentially complicates the analysis of wave existence, as reviewed in [18]. In some cases, when the maximum principle remains applicable, the wave existence can be proved by conventional methods, though it may be more technically difficult and some additional conditions can be necessitated to be imposed. As such, we prove the wave existence in the monostable case under the additional assumption that time delay is limited from above. This condition is related to the location of the essential spectrum, and we do not know whether the waves exist if it not satisfied. It is possible that oscillating waves emerge instead of monotone waves as it is the case for some other models [18].

Let us recall that the wave existence is proved by the method of lower and upper functions. It implies also the wave stability understood in a certain sense. If the decreasing solution provided by the upper function and the increasing solution provided by the lower function have the same limit, then the limiting function is unique, and all solutions between the upper and lower functions converge to the same wave. However, the uniqueness of the limiting function is not proved, so we have only a partial (one-side) stability result. Furthermore, the existence of waves for the minimal speed is proved passing to the limit of the waves with a larger speed. This method does not provide the stability of the wave with the minimal speed. However, we know for the scalar equation without time delay that the wave with the minimal speed is mostly interesting because solutions with initial conditions with a finite support converge to it. We observe this convergence numerically for the problem studied in the present work but neither local stability of the wave with the minimal speed nor global convergence to it are not yet proved. Stability of waves for delay reaction-diffusion systems requires further investigations.

Infection spreading in the tissue. Infection spreading in cell culture is accompanied by the interferon production by the infected cells, which is a part of the innate immune response. In the case of infection development in tissues of the human organism, there are also cells of innate immune response, such as macrophages and dendritic cells, and also the adaptive immune response determined by T and B lymphocytes. Both components of the immune response also involve numerous cytokines and chemokines. Altogether, the process of infection spreading becomes much more complex than in cell cultures. Some simplified models are considered in [2] for a single equation for virus concentration and in [4] for two equations for virus and immune cells. These models allow the determination of some regimes of infection spreading. The model developed in the present work provides an appropriate background for a more detailed and biologically justified investigation of viral infection development in the tissue of the organisms. This question will be studied in the future works.

APPENDIX A. NUMERICAL IMPLEMENTATION

A.1. Spatial discretization

We let Ω be a convex, plane domain, and \mathcal{T}_h be a regular, quasi-uniform triangulation of Ω with triangles of maximum size $h < 1$. Setting $W_h = \{v_h \in C^0(\bar{\Omega}); v_h|_T \in \mathbb{P}_1(T), \forall T \in \mathcal{T}_h\}$ be a finite-dimensional, where \mathbb{P}_1 is the set of all polynomials of degree ≤ 1 with real coefficients and denoting by $\langle \cdot; \cdot \rangle$ the standard L^2 inner product on Ω , we consider the weak formulation of system (4.8)–(4.10): find $V_h, U_h, I_h \in W_h$ such that $\forall \phi_h^V, \phi_h^U, \phi_h^I \in W_h$, we have:

$$\begin{aligned} \langle \partial_t V_h - D \Delta V_h - b I_{\tau h} + \sigma V_h; \phi_h^V \rangle &= 0, \\ \langle \partial_t U_h + a U_h V_h; \phi_h^U \rangle &= 0, \\ \langle \partial_t I_h - a U_h V_h + \beta I_h; \phi_h^I \rangle &= 0, \end{aligned} \tag{A.1}$$

which gives after the integration by part:

$$\begin{aligned} \langle \partial_t V_h - b I_{\tau h} + \sigma V_h; \phi_h^V \rangle + \langle D \nabla V_h; \nabla \phi_h^V \rangle - \int_{\Gamma_n} D \frac{\partial V_h}{\partial n} \partial \gamma &= 0, \\ \langle \partial_t U_h + a U_h V_h; \phi_h^U \rangle &= 0, \\ \langle \partial_t I_h - a U_h V_h + \beta I_h; \phi_h^I \rangle &= 0, \end{aligned} \tag{A.2}$$

We note that $\int_{\Gamma_n} D \frac{\partial V_h}{\partial n} \partial \gamma = 0$ due to the Neumann boundary condition.

A.2. Time marching scheme

Our method is based on the explicit first order Euler scheme. For that, let us denote by $(V_h^{n+1}, U_h^{n+1}, I_h^{n+1})$ and (V_h^n, U_h^n, I_h^n) the approximate values at time $t = t^{n+1}$ and $t = t^n$, respectively and by δt the time step size. Then, owing to the system (A.2), the unknown fields at time $t = t^{n+1}$ are defined as the solution of the following system:

$$\langle V_h^{n+1} + \sigma \delta t V_h^{n+1}; \phi_h^V \rangle + \langle D \delta t \nabla V_h^{n+1}; \nabla \phi_h^V \rangle = \langle V_h^n - b \delta t I_{\tau h}^{n+1}; \phi_h^V \rangle, \tag{A.3}$$

$$\langle U_h^{n+1} + a \delta t U_h^{n+1} V_h^{n+1}; \phi_h^U \rangle = \langle U_h^n; \phi_h^U \rangle, \tag{A.4}$$

$$\langle I_h^{n+1} + \beta \delta t I_h^{n+1}; \phi_h^I \rangle = \langle I_h^n + a \delta t U_h^{n+1} V_h^{n+1}; \phi_h^I \rangle. \tag{A.5}$$

Remark. – We first solve the equation (A.3) in order to obtain V_h^{n+1} , then we solve the equation (A.4) in order to obtain U_h^{n+1} and at the end we solve the equation (A.5) in order to obtain I_h^{n+1} .

- All the solution of I_h^{n+1} are saved between the interval $[k \cdot \tau, (k+1) \cdot \tau]$, $k \in \mathbb{N}$ in order to be used for the term $I_{\tau h}^{n+1}$
- We use the free software **FreeFEM** [9] that offers a large variety of triangular finite elements (linear and quadratic Lagrangian elements, discontinuous P_1 , Raviart–Thomas elements, etc.) to solve partial differential equations. It is an integrated product with its own high level programming language and a syntax close to mathematical formulations, making the implementation of numerical algorithms very easy. Among the features making **FreeFEM** an easy-to-use and highly adaptive software we recall the advanced automatic mesh generator, mesh adaptation, problem description by its variational formulation, automatic interpolation of data, color display on line, postscript printouts, etc. The **FreeFEM** programming framework offers the advantage to hide all technical issues related to the implementation of the finite element method.

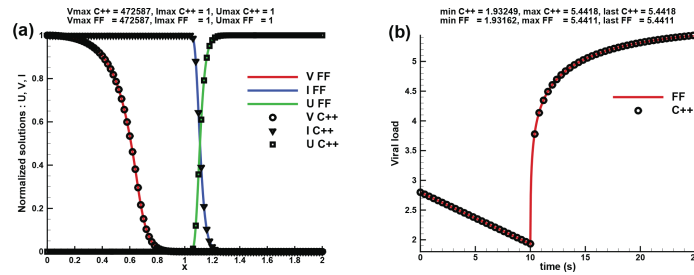


FIGURE A.1. Comparison of the normalized solutions of V , I and U at $t = 25s$ (a) in 1D and of the viral load evolution (b) between the results obtained using C++ code and FreeFEM code with $\beta = 0$

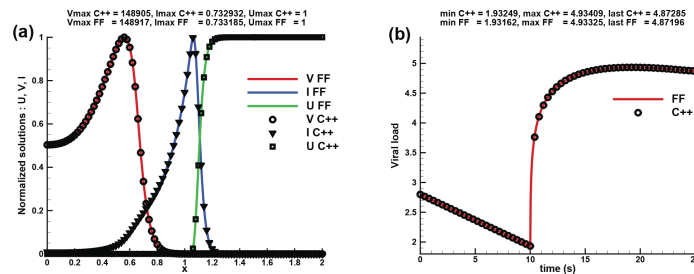


FIGURE A.2. Comparison of the normalized solutions of V , I and U at $t = 25s$ (a) in 1D and of the viral load evolution (b) between the results obtained using C++ code and FreeFEM code with $\beta = 0.2$

A.3. 1D examples

The FreeFEM code was validated in the 1D case by the comparison with the C++ code based on implicit finite difference method (Fig. 3). We start our simulation by considering the 1D domain $\Omega = [0, L]$ and we took the following initial condition: $U(x, 0) = U_0 = 1$, $I(x, 0) = 0$ and $V(x, 0) = V_0$ for $0 \leq x < x_0$ and 0 otherwise.

We compute the viral load $V_T(t) = \int_{\Omega} V(x, t) dx$ and we compare the results with the one obtained by the C++ code for two cases $\beta = 0$ (Fig. A.1) and $\beta = 0.2$ (Fig. A.2). The other parameters of this simulation are given as follows:

$$L = 2, x_0 = 0.1, D = 0.001, b = 10^5, \sigma = 0.2, V_0 = 6000, a = 1, \delta t = 0.01, \tau = 10s, T_f = 25s.$$

We note that we obtain similar between the two codes and a small difference for the CPU time: 11s with FreeFEM code *vs.* 18s with C++ code.

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