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# 1

# Comparative accuracy and resolution assessment of two prototype proton computed tomography scanners

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#### 22

#### Abstract

Background: Improving the accuracy of relative stopping power (RSP) in proton
 therapy may allow reducing range margins. Proton computed tomography (pCT) has
 been shown to provide state-of-the-art RSP accuracy estimation, and various scanner
 prototypes have recently been built. The different approaches used in scanner design
 are expected to impact spatial resolution and RSP accuracy.

Purpose: The goal of this study was to perform the first direct comparison, in terms
 of spatial resolution and RSP accuracy, of two pCT prototype scanners installed at the
 same facility and by using the same image reconstruction algorithm.

Methods: A phantom containing cylindrical inserts of known RSP was scanned at the phase-II pCT prototype of the U.S. pCT collaboration and at the commercially oriented ProtonVDA scanner. Following distance-driven binning filtered backprojection reconstruction, the radial edge spread function of high-density inserts was used to estimate the spatial resolution. RSP accuracy was evaluated by the mean absolute percent error (MAPE) over the inserts. No direct imaging dose estimation was possible, which prevented a comparison of the two scanners in terms of RSP noise.

Results: In terms of RSP accuracy, both scanners achieved the same MAPE of 0.72%
when excluding the porous sinus insert from the evaluation. The ProtonVDA scanner
reached a better overall MAPE when all inserts and the body of the phantom were

accounted for (0.81%), compared to the phase-II scanner (1.14%). The spatial resolu-41 tion with the phase-II scanner was found to be 0.61 lp/mm, while for the ProtonVDA 42 scanner somewhat lower at 0.46 lp/mm. 43 **Conclusions:** The comparison between two prototype pCT scanners operated in the 44 same clinical facility showed that they both fulfill the requirement of an RSP accuracy 45 of about 1%. Their spatial resolution performance reflects the different design choices 46 of either a scanner with full tracking capabilities (phase-II) or of a more compact 47 tracker system which only provides the positions of protons but not their directions 48 (ProtonVDA). 49 50

51 Keywords: proton CT, image quality, design choices, RSP, spatial resolution

# <sup>52</sup> I. Introduction

Radiation therapy with external proton beams offers the potential for highly conformal 53 dose distributions with the possibility of healthy tissue sparing. The point where protons 54 stop in the patient is dependent on the stopping power of the tissue they traverse. This 55 is commonly expressed as relative to water and denoted as relative stopping power (RSP). 56 An accurate three dimensional (3D) patient RSP image in treatment position is needed for 57 accurate proton dose calculation. Errors in the 3D patient RSP image will cause proton range 58 prediction errors, thus introducing range uncertainties that entail the use of safety margins.<sup>1</sup> 59 Currently, RSP images are obtained by converting x-ray linear attenuation coefficients, 60 acquired with single energy x-ray computed tomography (CT) imaging. This is often based 61 on a stoichiometric calibration<sup>2</sup> which leads to institution–specific margin recipes, e.g., 3.5%62 plus 1 mm at the Massachusetts General Hospital or similar recipes at other proton centers.<sup>1,3</sup> 63

Besides CT imaging for treatment planning, the use of volumetric image guidance for 64 proton therapy is becoming well established.<sup>4</sup> Beyond patient positioning, there is a need 65 for adaptive re-planning based on accurate RSP estimation in 3D, when the patient is in 66 treatment position at isocenter, which allows reduced planning margins. The leading example 67 for improved RSP estimation is dual-energy x-ray CT (DECT), which after undergoing 68 extensive phantom  $5^{-14}$  and animal tissue validation,  $15^{-19}$  has seen clinical implementation 69 for treatment planning,<sup>20–22</sup> and which is now appearing in treatment rooms, but requires 70 the patient to be moved away from isocenter for verification.<sup>23</sup> 71

An alternative is to use the proton beam itself for imaging and to acquire a proton

CT (pCT) scan of the patient on the treatment table. While x-ray interactions are sparse, 73 multiple Coulomb scattering (MCS) of protons means that straight-path approximations in 74 the reconstruction algorithm lead to poor spatial resolution.<sup>24</sup> A curved path approximating 75 the true proton path can be estimated from measurements of the location of each proton 76 before and after the object, and can be refined with information about the direction of 77 the proton, inferred from two locations separated by air or materials with a low scattering 78 power. The RSP line integrals are evaluated along these curved paths,<sup>25</sup> and thus, a pCT 79 scanner equipped with tracking modules and an energy detector allows use of proton tracking 80 information in image reconstruction. pCT reconstruction algorithms account for curved 81 paths, either using iterative reconstruction  $^{26-28}$  or filtered-backprojection.  $^{29-31}$ 82

Several prototype pCT scanners have been presented in the literature,<sup>32–38</sup> and an early 83 simulation study suggested that pCT may provide competitive ideal RSP accuracy compared 84 to DECT.<sup>39</sup> Many of these scanners have been used to image phantoms, and experimental 85 RSP accuracy is reported better than 1.6%, <sup>37</sup> 1.4%, <sup>40</sup> or 0.74%, <sup>38</sup> and was shown to be 86 equivalent to state-of-the-art DECT in a comparison using known RSP tissue mimicking 87 phantoms<sup>41</sup> with a mean absolute percentage error (MAPE) of 0.6%. Since various proton 88 tracking pCT prototypes are in the early development stage, it is vet unclear what the 89 optimal system design is. Two of the most advanced scanners currently in operation are the 90 pCT collaboration's phase-II scanner<sup>35</sup> and the commercially-oriented ProtonVDA (pVDA) 91 scanner.<sup>42–44</sup> The phase-II scanner features silicon–strip tracking modules registering both 92 the location and direction of protons before and after the object, and a five-stage energy 93 detector. The pVDA scanner uses scintillating fibers tracking modules which register only 94 position with initial direction vectors derived from the beam geometry, and a single stage 95 energy detector requiring variation of the proton beam energy. Given the differences in 96 particle tracking and energy detection between the scanners, and since they are both available 97 at the Northwestern Medicine Chicago Proton Center, this study aimed at performing the 98 first comparison of two particle tracking pCT scanner prototypes. 99

# 100 II. Materials & methods

<sup>101</sup> To compare the performance of the new commercial pVDA system against the well-studied <sup>102</sup> phase-II scanner in terms of spatial resolution and RSP accuracy, we scanned a phantom of known RSP with both systems. In order to focus on the hardware differences between the two scanners, preconditioning of the data before image reconstruction and the reconstruction algorithm were the same for both scanners. Details about the scanners, the data processing, the reconstruction algorithm and the scanned object are given in the subsequent sections.

### <sup>107</sup> II.A. Phase-II prototype scanner

The phase-II scanner<sup>34</sup> is depicted in figure 1, left panel, and was designed by the pCT collaboration (at the Baylor University, Loma Linda University, and the University of California at Santa Cruz). The particle tracking system consists of two tracking modules,<sup>35</sup> one before and one after the object, measuring position and direction information, as well as a scintillating detector<sup>45</sup> measuring the residual energy.

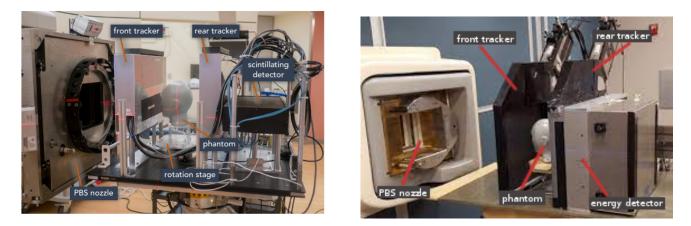


Figure 1: (Left) phase-II scanner with various parts of the system indicated (taken from <sup>46</sup> - © Institute of Physics and Engineering in Medicine. Reproduced by permission of IOP Publishing. All rights reserved). (Right) Photo of the pVDA scanner with its main parts labeled.

Each of the two tracking modules<sup>35</sup> consists of two tracking planes separated by 50 mm, each measuring the coordinates of every incoming proton. Using the two position measurements and the direction vector, the most likely path (MLP) can be estimated.<sup>25</sup> Coordinates are determined as hit locations of two adjacent planes of single–sided silicon strip detectors with lateral and vertical strip orientation, respectively, to provide two–dimensional coordinate measurements. Laterally, each tracking plane consists of four modules that are glued <sup>119</sup> together, resulting in an insensitive gap of 0.6 mm.

The energy detector<sup>45</sup> consists of five longitudinal segments of UPS-923A<sup>47</sup> (RSP = 1.038) which are individually wrapped in reflective material and coupled to a photo-multiplier. Each segment is referred to as a *stage* and their longitudinal depth is 51 mm. Each incident proton can produce up to five readings in the analog-digital converters (ADCs) of the photo-multipliers. The segmented design with five stages was chosen to minimize water-equivalent path length (WEPL) noise and to make it almost independent of the scanned object.

The scanner has been shown to produce a near 100 % detection efficiency for count rates up to 1 MHz with homogeneous proton fluence.<sup>35</sup> For operation of the scanner with scanned pencil beams, the local count rate increases and a pileup-free operation was demonstrated for count rates up to 400 kHz.<sup>46,48</sup> For the purpose of this study, a 200 MeV broad proton beam was utilized with the phase-II scanner. More details about the beam characteristics are given in section II.F.

#### <sup>133</sup> II.B. pVDA scanner

The second pCT scanner under investigation is the prototype<sup>43</sup> of ProtonVDA LLC (Naperville, Illinois, USA) depicted in figure 1, right panel. Its more compact design is intended for future clinical use. The system has two tracking modules, one upstream and one downstream the scanned object. Unlike the phase-II scanner, these tracking modules only consist of a single tracking plane and no direction information is acquired directly.

Tracking is realized through scintillating fibers. Each tracking module consists of two layers of fibers, one oriented horizontally and one vertically to provide two-dimensional coordinate measurements. The system can only be operated with scanned pencil beams due to the multiplexing of the tracking fibers: multiple non-adjacent fibers are connected to one of many photomultipliers and an exact and unambiguous location is determined using the approximate location of the pencil beam.

The energy detector is realized as a 130 mm thick monolithic scintillator block. The scintillation light is measured by 16 individual photomultipliers, which are distributed laterally across the surface of the detector. Due to the limited depth of the sensor, only thin <sup>148</sup> objects can be scanned with a single proton energy. To scan thicker objects, scans of several <sup>149</sup> incident proton energies are combined, rejecting protons that stopped in the object or com-<sup>150</sup> pletely penetrated the scintillator. The system is designed for count rates of up to 10 MHz;<sup>43</sup> <sup>151</sup> in this experiment, it was operated reliably at count rates of 1 - 2 MHz.

### <sup>152</sup> II.C. Data processing of the phase-II scanner

The data processing steps of the phase–II scanner, before data conditioning for reconstruction and image reconstruction itself, have been described Schultze et al.<sup>49</sup> The acquired data from the tracking detector and the energy detector are converted to coordinates in the reference system of the trackers and WEPL values for proton histories that are not rejected for various reasons, e.g., incomplete tracking data or suspected pileup events.

To generate WEPL measurements from the ADC readout, the phase-II scanner makes use of an elaborate calibration procedure based on data from a double-wedged polystyrene phantom (RSP= 1.03) complemented by one to four rectangular polystyrene blocks.<sup>50</sup> A detailed description of the calibration procedure is given in several previous publications, including Bashkirov et al.<sup>45</sup>, Piersimoni et al.<sup>50</sup>, Dedes et al.<sup>51</sup> and Schultze et al.<sup>49</sup>

The calibration runs cover the complete WEPL range of the detector. They are used to 163 establish two-dimensional histograms binned by WEPL and energy deposit to the stopping 164 stage. The stopping stage is defined as the furthest stage where the energy deposit ex-165 ceeded a certain threshold (usually 1 MeV) and the WEPL can be inferred from the tracking 166 information and the geometry of the calibration phantom. From this histogram, for each 167 energy deposit, the most frequent WEPL is found, which allows establishing an energy-to-168 WEPL calibration curve for each of the five stages of the energy detector. These calibration 169 curves are then applied to subsequent imaging runs to convert the ADC measurements of 170 an unknown object to WEPL values. Finally, the WEPL values are combined with the 171 four coordinate measurements in the tracker and yield the proton–by–proton WEPL, up-172 stream/downstream position, and upstream/downstream direction information used in the 173 reconstruction algorithm, as described by Schultze et al.<sup>49</sup>. 174

During this particular experiment, noise on the energy detector data was slightly elevated compared to past scans. This effect was manifested as increased RSP artifacts compared to what was previously observed<sup>41</sup> for the energy threshold of 1 MeV to select the stopping stage. To reduce the ring artifacts which intersect the inserts and affect the RSP accuracy, the stage threshold was varied from 1.5 MeV to 3 MeV in 0.25 MeV steps, in addition to the default threshold value. The optimal threshold value was found to be 1.5 MeV, yielding images with ring artifacts of comparable amplitude to what was previously reported in published literature.<sup>41</sup>

### $_{183}$ II.D. Data processing of the pVDA scanner

The pVDA scanner is calibrated without the use of a dedicated phantom and instead uti-184 lizes multiple acquisitions at different incident beam energies. The calibration procedure 185 converts the photomultiplier signals to residual proton range in WEPL. Protons are deliv-186 ered at 44 energies ranging from 100.8 to 164.7 MeV, with their range reduced by a 6.5 cm 187 water-equivalent material uniform absorber, covering proton ranges between 1.25 and 12 cm. 188 1.25 cm is roughly the minimum proton range needed to traverse the preceding detector mate-189 rial, enter the scintillator and produce a signal just above the noise threshold. Each incident 190 energy smaller than the maximum energy corresponds to a reduction in range and produces 191 energy deposits approximately proportional to the equivalent WEPL in the energy detector. 192 Via this calibration procedure, for each of the 44 proton beam energies, the corresponding 193 WEPL in the detector is mapped to the ADC number produced by the detector. The exact 194 procedure, including the correction of the spatial dependence of the signal with respect to 195 the locations of the energy deposit and the photomultiplier, is described in detail in DeJongh 196 et al.  $^{43}$ 197

Since the system's energy detector is too thin to cover the desired WEPL range directly, 198 data from multiple energies are merged. The calibration needs to be performed only once, 199 since calibrated WEPLs can be shifted by the difference in range of a lower incident energy. 200 For the imaging runs presented in this work, three incident energies (118 MeV, 160 MeV and 201 187 MeV) were acquired throughout the field of view, which resulted in an increased imaging 202 dose, but could be avoided in case prior knowledge of the scanned object is available.<sup>52</sup> Each 203 of the beam energies covered a specific WEPL range in the object scanned in this experiment, 204 with some overlapping WEPLs between them, as indicated in table 1. The first overlap 205 region extends from approximately  $50 \,\mathrm{mm}$  to about  $90 \,\mathrm{mm}$  and is covered by the  $118 \,\mathrm{MeV}$ 206

and the 160 MeV beams, respectively. The second overlap region spans 100 mm to 125 mm and was sampled by the 160 MeV and the 187 MeV beams. For that particular dataset, it was found that using protons from the 187 MeV beam together with protons from the other beams for sampling the same WEPL regions caused considerable ring-shaped image artifacts. Therefore, the use of the 187 MeV was reduced to the bare minimum, namely for WEPLs larger than 125 mm. With this filtration the number of protons available for reconstruction was reduced by 38% compared to the initial dataset.

The proton angle at the front tracker is determined from the location of the proton hit and the distance from the steering magnets in the beamline.<sup>43</sup> The rear tracker angle is determined by a MLP calculation. During that procedure, the most likely combination of exit position from the object and exit angle, given the upstream tracker position, upstream angle, and downstream tracker position, is estimated on a proton-by-proton basis.

Table 1: WEPL sampling for the pVDA scanner. The first column indicates the energies used. The second column lists the WEPL interval covered by each energy. The third column shows the WEPL range finally used for reconstruction, after removing the overlap between the two higher energies.

Energy (MeV)	WEPL (mm)	WEPL for reconstruction (mm)
118	0 - 90	0 - 90
160	50 - 125	50 - 125
187	100 - 200	125 - 200

#### <sup>219</sup> II.E. Phantom

The analyses performed in this work were based on scans of a custom-built phantom with known RSP and geometry shown in figure 2. The phantom's body consists of blue wax with an RSP of 0.980. It is 40 mm thick and has a diameter of 180 mm. It contains eight inserts made of tissue-equivalent plastic materials, each with a diameter of 18 mm and with thickness of 40 mm, listed in figure 2. The reference RSP (RSP<sub>ref</sub>) of each insert was determined in another study<sup>42</sup> using a multi-layer ionization chamber.

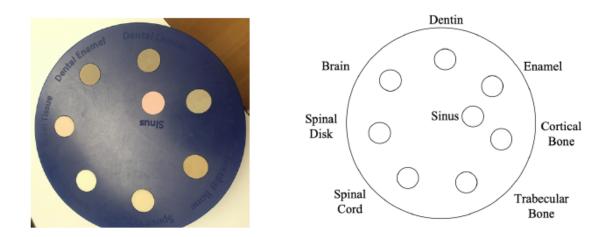


Figure 2: (Left) Photo of the cylindrical phantom made of plastic body and containing eight plastic tissue equivalent inserts. (Right) Drawing of the phantom with the inserts labeled. It should be noted that the labels of the enamel and dentin inserts as seen in the photograph have been mistakenly swapped in the manufacturing process. The correct positions are shown in the drawing.

### 226 II.F. Datasets

The phase-II scanner data of the cylindrical phantom were acquired at the Northwestern 227 Medicine Chicago Proton center using a 200 MeV wobbled beam of approximately 1.7 cm 228 size (1 $\sigma$  at isocenter). The acquisition was obtained in a continuous rotation mode, which 229 means that the phantom was rotating throughout the beam-on time and the data were later 230 on split into 360 projections, each one covering an arc of 1°, using the timestamp of each 231 proton and the known rotation speed (1 rpm) of the stage. The scan time was approximately 232 5 min, during which about  $3.6 \times 10^8$  protons were acquired at a 1 MHz rate. From the 360 233 projections, 90 projections at 4° steps were kept and used in the reconstruction. This choice 234 was made in order to have the same number of projections and at the same angular steps as in 235 the pVDA dataset, which was acquired in a step-and-shoot mode. The data were processed 236 with a calibration curve obtained on the same day with the same beam characteristics as the 237 imaging run. After cuts, in the processing of the raw data, the mean proton fluence in the 238 object was 30 protons/mm<sup>2</sup> per projection. As described in section II.C., the energy detector 239 stage threshold was optimized to suppress image artifacts. Prior to reconstruction, the data 240 were binned in  $2 \text{ mm} \times 2 \text{ mm}$  sized-pixels at the front tracker and  $3-\sigma$  cuts were applied on 241 the angle and WEPL distribution in each pixel. 242

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The pVDA scanner data of the same phantom were acquired in the same facility in a

step-and-shoot mode (90 projections at  $4^{\circ}$  angular steps), by scanning a  $0.4 - 0.8 \,\mathrm{cm}$  size 244 (energy dependent and quantified as  $1\sigma$  at isocenter) pencil beam over an area large enough to 245 cover the phantom. Three incident energies (118 MeV, 160 MeV and 187 MeV) were utilized 246 to sample the WEPL range of the phantom taking into account the limited thickness of the 247 energy detector. The beam-on time, considering all three energies, was approximately 90 sec, 248 during which about  $10^8$  protons were acquired at a rate between 1 and 2 MHz. This does not 249 account for the overhead time for rotating the phantom between two projections (phantom 250 rotation has been automated after that experiment). Additionally, about 10-20 sec were 251 needed for beam energy switching. The three incident energies combined covered a WEPL 252 range from 0 to approximately 200 mm (as shown in table 1). To avoid inadequate WEPL 253 sampling, the WEPL interval covered by each energy overlaps with that covered by another 254 energy. The extent of this overlap was tuned to provide the best possible image quality, 255 as previously described in section II.D.. After the initial processing and merging, a mean 256 fluence in the object of approximately  $20 \,\mathrm{protons/mm^2}$  per projection were forwarded to 257 the reconstruction. Similarly to the procedure followed for the phase-II scanner, prior to 258 reconstruction, the data were binned in  $2 \,\mathrm{mm} \times 2 \,\mathrm{mm}$  sized-pixels at the front tracker and 259  $3-\sigma$  cuts were applied on their angular and WEPL distribution in each pixel. 260

### <sup>261</sup> II.G. Reconstruction algorithm

Following the processing of the raw scanner data and the filtering on angle and WEPL, the 262 volumetric RSP images were reconstructed using a dedicated filtered backprojection algo-263 rithm. A detailed description of the concept of the algorithm is given in Rit et al.<sup>29</sup> To 264 account for the curved proton trajectories due to MCS, the path of every proton is esti-265 mated by an MLP formulation.<sup>25</sup> The MLP estimate is based on the position and direction 266 information from the tracker in the case of the phase-II scanner, and on the positions from 267 the tracker and the angles deduced in the processing of the data in the case of the pVDA 268 scanner. 269

The proton-by-proton data were binned in projection images with  $1 \text{ mm} \times 1 \text{ mm}$  pixels for use with the RSP accuracy analysis and with  $0.2 \text{ mm} \times 0.2 \text{ mm}$  pixels in the case of the spatial resolution determination. The projections were then filtered and backprojected. In the last step, the pCT images were reconstructed as RSP maps in a grid of  $1 \text{ mm} \times 1 \text{ mm} \times 1 \text{ mm}$ 

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for RSP analysis or  $0.2 \text{ mm} \times 0.2 \text{ mm} \times 1 \text{ mm}$  for spatial resolution. The reconstruction was applied to both scanner datasets without change of parameters.

### <sup>276</sup> II.H. RSP accuracy and spatial resolution

The RSP accuracy (percent RSP error) was quantified separately in each insert. A circular region-of-interest (ROI) with a radius of 7 mm (80% of the insert radius to avoid insert boundaries) was applied around the insert centers and the mean reconstructed RSP (RSP<sub>mean</sub>) in each ROI was calculated. The RSP accuracy (RSP<sub>acc</sub>) was then defined as:

$$RSP_{acc} = \frac{RSP_{mean} - RSP_{ref}}{RSP_{ref}} \cdot 100\%,$$
(1)

where  $RSP_{ref}$  denotes the reference RSP of each insert. The uncertainty of the  $RSP_{acc}$ per insert is derived from the uncertainty on the  $RSP_{ref}$  and from the uncertainty on the  $RSP_{mean}$ , making use of error propagation. The former was defined as the uncertainty from a 0.1 mm error in the sample thickness estimation during the multi-layer ionization chamber measurement. The latter was based on the standard error of the mean (SEM), calculated over the values of N voxels in the ROI:

$$SEM = \frac{\sigma_{\rm rec}}{\sqrt{N}},\tag{2}$$

where  $\sigma_{\rm rec}$  is the standard deviation of the reconstructed RSP values of the N voxels in the ROI.

In addition to the RSP for each insert, the MAPE achieved for each scanner for that particular phantom was also calculated as:

 $MAPE = \frac{\sum_{i=1}^{n} |RSP_{acc,i}|}{n},$ (3)

where n is the total number of inserts and  $RSP_{acc,i}$  is the percent error for every insert ias calculated from equation 1. The uncertainty on the MAPE was calculated via an error propagation based on the individual insert accuracy. <sup>297</sup> The spatial resolution was evaluated by calculating the modulation transfer function <sup>298</sup> (MTF) from the radial edge–spread function (ESF)<sup>53</sup> of the three inserts with the highest <sup>299</sup> RSP (enamel, cortical bone and dentin). After taking the average of 20 slices to reduce noise <sup>300</sup> in the images and determining the insert centers using a threshold followed by a center of <sup>301</sup> mass calculation, we followed the approach of Krah et al. <sup>54</sup> and Khellaf et al. <sup>31</sup> and modelled <sup>302</sup> the ESF as an error function with parameters A,  $\mu$ ,  $\sigma$  and C.

$$ESF = A \cdot \frac{1}{2} \left[ 1 + \operatorname{erf} \left( \frac{r - \mu}{\sqrt{2}\sigma} \right) \right] + C, \tag{4}$$

where r is the distance of the sampled points to the insert center. Using the parameters obtained by the fit of the ESF to the inserts, the frequency of the MTF at the 10% level, used here as the metric for spatial resolution, is then given by:

$$f_{\rm MTF_{10\%}} = \sqrt{\frac{\ln 10}{2}} \cdot \frac{1}{\pi\sigma}.$$
(5)

The uncertainty on the  $f_{MTF_{10\%}}$  is estimated by propagating the uncertainty on  $\sigma$  from the fit described in equation 4 to equation 5.

# 310 III. Results

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### <sup>311</sup> III.A. RSP accuracy and spatial resolution

For the comparison of the performance of the two scanners, the  $RSP_{acc}$  and spatial resolution 312 evaluations were applied on the pCT images (figure 3(a) for phase-II and figure 3(b) for 313 pVDA scanners, respectively). Ring-shaped artifacts are present in both images and to 314 some extent, affect the quantified  $RSP_{acc}$ . The difference image in figure 3(c) shows that 315 artifacts did not appear at the same location in both images. A slight residual misalignment 316 is the cause of large differences at the edges of some inserts. Undersampling streak artifacts 317 are also observed in images from both scanners, and are attributed to the limited number 318 of projections (90) used. We confirmed that for the phase-II scanner these vanish when 319 360 projections are used (not shown). The RSP<sub>acc</sub> results are listed in table 2–phase-II and 320 table 3–pVDA. 321



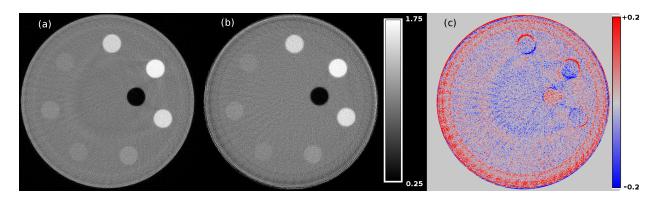


Figure 3: Reconstructed RSP images with  $0.2 \text{ mm} \times 0.2 \text{ mm}$  pixel size from (a) the phase-II and (b) the pVDA scanner. The average of 20 central slices was taken to reduce noise and the images are shown with an RSP level of 1.0 and window of 1.5. In (c) the difference (b)–(a) is shown with an RSP level of 0 and window of 0.4.

In the case of the phase-II scanner (table 2), the RSP<sub>acc</sub> varied from -0.29% for the brain insert up to -4.5% for the sinus. Except for the sinus, the enamel insert (-1.03%) and the phantom body (-1.33%), the RSP<sub>acc</sub> was better than 1%. The MAPE over all inserts and the phantom body for the phase-II scanner image was 1.14%. Excluding the phantom body, the MAPE marginally improved to 1.12%. Excluding the sinus, the MAPE reached 0.72%. Finally, excluding both the sinus and the body of the phantom from the RSP<sub>acc</sub> quantification, yielded a MAPE of 0.63%.

Table 2: Results of the RSP analysis for the phase-II scanner data. The table lists for each insert the  $\text{RSP}_{\text{ref}}$ , the  $\text{RSP}_{\text{mean}}$ , the  $\text{RSP}_{\text{acc}}$  and the size of the ROI in voxels. For different subsets of inserts, the MAPE is also listed. The uncertainty on each value was obtained as explained in section II.H..

Insert	$\mathrm{RSP}_{\mathrm{ref}}$	$\mathrm{RSP}_{\mathrm{mean}}$	$RSP_{acc} / \%$	ROI size / voxels
Cortical bone	$1.555 {\pm} 0.004$	$1.543 {\pm} 0.0006$	$-0.77 \pm 0.25$	3120
Trabecular bone	$1.100{\pm}0.003$	$1.095 {\pm} 0.0006$	$-0.45 \pm 0.25$	3060
Spinal disc	$1.070 {\pm} 0.003$	$1.066 {\pm} 0.0005$	$-0.37 \pm 0.25$	3080
Enamel	$1.755 {\pm} 0.004$	$1.737 {\pm} 0.0005$	$-1.03 \pm 0.25$	3060
Dentin	$1.495{\pm}0.004$	$1.481{\pm}0.0006$	$-0.94 \pm 0.25$	3020
Sinus	$0.200{\pm}0.005$	$0.191{\pm}0.0005$	$-4.50 \pm 0.35$	3040
Phantom body	$0.980{\pm}0.002$	$0.967{\pm}0.0001$	$-1.33 \pm 0.25$	46100
Spinal cord	$1.040{\pm}0.003$	$1.034{\pm}0.0005$	$-0.58 {\pm} 0.25$	3060
Brain	$1.040{\pm}0.003$	$1.037 {\pm} 0.0005$	$-0.29 \pm 0.25$	3100
MAPE (all values)			$1.14 \pm 0.09$	
MAPE (w/o body)			$1.12 {\pm} 0.09$	
MAPE $(w/o sinus)$			$0.72 {\pm} 0.09$	
MAPE (w/o body and sinus)			$0.63 {\pm} 0.10$	

III.A. RSP accuracy and spatial resolution

For the pVDA scanner (table 3), the RSP<sub>acc</sub> varied from 0.1% for the spinal cord and brain inserts up to -2.4% for the phantom body. Except for the body of the phantom, the only other insert for which the RSP<sub>acc</sub> was worse than 1% was the sinus with -1.5%. The MAPE over all inserts and the phantom body was 0.81%. When excluding the phantom body, the MAPE improved to 0.61%. Excluding the sinus, the MAPE reached 0.72%. When excluding both the sinus and the body of the phantom, the MAPE became 0.48%. The RSP<sub>acc</sub> per insert and the MAPE are displayed in figure 4 for both scanners.

Table 3: Results of the RSP analysis for the pVDA scanner data. The table lists for each insert the  $RSP_{ref}$ , the  $RSP_{mean}$ , the  $RSP_{acc}$  and the size of the ROI in voxels. For different subsets of inserts, the MAPE is also listed. The uncertainty on each value was obtained as explained in section II.H..

Insert	$RSP_{ref}$	$RSP_{mean}$	$RSP_{acc} / \%$	ROI size / voxels
			1	/
Cortical bone	$1.555 \pm 0.004$	$1.569 {\pm} 0.001$	$0.90 {\pm} 0.26$	3060
Trabecular bone	$1.100 {\pm} 0.003$	$1.103 {\pm} 0.001$	$0.27 {\pm} 0.27$	3100
Spinal disc	$1.070 {\pm} 0.003$	$1.073 {\pm} 0.001$	$0.28 {\pm} 0.28$	3100
Enamel	$1.755 {\pm} 0.004$	$1.771 {\pm} 0.001$	$0.91 {\pm} 0.26$	3120
Dentin	$1.495 {\pm} 0.004$	$1.507 {\pm} 0.001$	$0.80 {\pm} 0.27$	3120
Sinus	$0.200 {\pm} 0.005$	$0.197{\pm}0.001$	$-1.50 \pm 0.65$	3120
Phantom body	$0.980 {\pm} 0.002$	$0.957 {\pm} 0.001$	$-2.40 \pm 0.29$	448860
Spinal cord	$1.040 {\pm} 0.003$	$1.041{\pm}0.001$	$0.10 {\pm} 0.28$	3060
Brain	$1.040 {\pm} 0.003$	$1.041 {\pm} 0.001$	$0.10 {\pm} 0.28$	3080
MAPE (all values)			$0.81 {\pm} 0.11$	
MAPE $(w/o body)$			$0.61 {\pm} 0.12$	
MAPE $(w/o sinus)$			$0.72 {\pm} 0.10$	
MAPE (w/o body and sinus)			$0.48 {\pm} 0.10$	

336	The spatial resolution as estimated by the radial edge profile of the three higher RSP
337	inserts –enamel, cortical bone and dentin– for both scanners is reported in table 4. The
338	phase-II scanner yields a spatial resolution of $0.59 - 0.62 \mathrm{lp/mm}$ , while the analysis for the
339	pVDA scanner resulted in a slightly lower spatial resolution of $0.44 - 0.48 \mathrm{lp/mm}$ .

Table 4:  $f_{\text{MTF}_{10}}$  results for the three highest RSP inserts of the phase-II and pVDA scanners. The values and their uncertainties in brackets were obtained as described in section II.H.

insert	$f_{\rm MTF_{10}}^{\rm phase-II}$	$f_{\rm MTF_{10}}^{ m pVDA}$
	(lp/mm)	
Cortical bone	$0.61 \ (0.02)$	0.47(0.02)
Dentin	0.62(0.02)	0.44(0.02)
Enamel	0.59(0.01)	0.48(0.02)
Mean	0.61(0.01)	0.46(0.01)

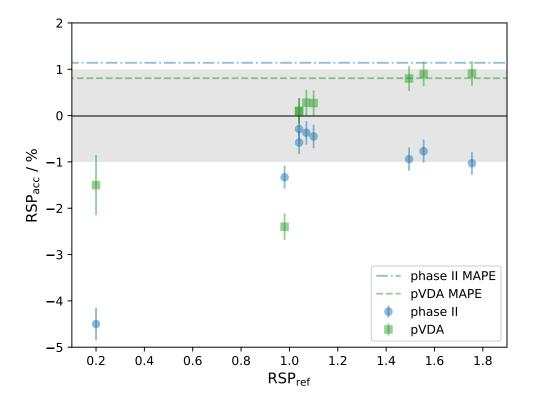


Figure 4: RSP accuracy comparison between the phase-II and the pVDA scanners. Each point represents a RSP<sub>acc</sub> value in % from table 2 and table 3, with the corresponding uncertainty depicted as the error bar. The shaded area signifies the  $\pm 1\%$  accuracy range. The dashed and the dotted–dashed lines indicate the MAPE for each scanner, when accounting for all inserts and the body of the phantom.

# <sup>340</sup> IV. Discussion

The scope of this study was to compare, in terms of RSP<sub>acc</sub> and spatial resolution, two pCT scanners of different design available for testing in the same clinical facility. The data were collected for the same object on different days, albeit using different proton beam delivery methods for the two scanners, namely a wobbled beam for the phase-II scanner and a pencil beam for the pVDA scanner.

No direct imaging dose estimation was possible, which prevented a comparison of the two scanners in terms of RSP noise. This limitation was due to lack of information on the total number of protons delivered by the beamline, which has to be operated in low-fluence mode for both scanners. The fluence is below the threshold where beam diagnostics function well. The number of protons registered by each scanner correlates to dose, but does not reflect lost protons due to nuclear interactions, pile up, or other detector inefficiencies.

As it may be noticed in figure 3, the pVDA image appears noisier. This is also confirmed 352 by the  $RSP_{mean}$  uncertainty per insert shown in table 2 and table 3 (a factor of 1.7–2 higher 353 for the pVDA scanner), and can be only partially explained by the higher mean proton 354 fluence in the case of the phase-II scanner. Nevertheless, several effects would have to be 355 considered before drawing conclusions about a fluence-based noise comparison. One is the 356 different detector design that could lead to different WEPL or detected energy resolution. 357 This implies that, even for the same mean fluence, different noise levels could be expected for 358 each scanner. Another important aspect is that the pVDA image is composed of scans with 359 three different energies (in general, the lower the energy the higher the energy straggling into 360 the object). This would have to be considered in any estimation of the noise, and the noise 361 in the pVDA three-energy image might even have a different spatial distribution compared 362 to a pVDA single–energy image. Thus, with the data at our disposal, a comparison based 363 only on the mean fluence would be inconclusive and the topic certainly deserves a separate 364 investigation. 365

By design, the pVDA scanner cannot use a single proton energy to cover the WEPL 366 dynamic range required for large objects. Therefore, three different scan energies (118 MeV, 367 160 MeV and 187 MeV) were used and assembled into a single dataset. It was observed 368 that the overlap of the two higher energies resulted in strong ring artifacts present in the 369 RSP image. The optimal RSP image from this dataset was obtained by removing the 370 overlap between the two highest energies and keeping only the WEPLs sampled from the 371  $160 \,\mathrm{MeV}$  beam in the region between  $100 - 160 \,\mathrm{mm}$ . The origin of the problematic overlap 372 between the two higher energies remains unclear, and the solution adopted in this manuscript 373 might be applicable and valid for this particular dataset only. In a recent work published 374 by DeJongh,<sup>55</sup> images of the same phantom reconstructed with an iterative reconstruction 375 algorithm show only very faint RSP artifacts, but a more conclusive investigation would 376 require comparison of the two algorithms and quantification of the RSP artifacts versus 377 spatial resolution, especially in the case of high values of the relaxation parameter  $\lambda$ . 378

For the phase-II scanner, the overall MAPE was slightly above 1% ( $1.14 \pm 0.09\%$ ), while for the pVDA scanner, it was  $0.81 \pm 0.11\%$ . The quantified RSP<sub>acc</sub> of the phase-II scanner

was strongly affected by the very large relative error of the sinus insert  $(-4.50 \pm 0.35\%)$ . 381 For the pVDA scanner, the RSP<sub>acc</sub> of that insert was also the worst among all inserts 382  $(-1.5 \pm 0.65\%)$ , but still closer to the desired  $\pm 1\%$ . When excluding the sinus insert from 383 the analysis, the MAPE for both scanners was 0.72%. It is worth noting that the absolute 384 RSP error  $|RSP_{mean} - RSP_{ref}|$  on the sinus insert is not generally higher than that of other 385 inserts. For the phase-II scanner, the sinus absolute RSP error is 0.009 while the average 386 absolute RSP error of all inserts is also 0.009 and ranging from 0.003 to 0.018. Similarly, for 387 the pVDA scanner, the sinus absolute RSP error is 0.003 while the average absolute RSP 388 error of all inserts is 0.008 and ranging from 0.001 to 0.023. Furthermore, protons traversing 389 the sinus insert do not have significantly different WEPL compared to protons crossing 390 other inserts, as the majority of the proton path is traveled across the body of the phantom. 391 Therefore, the WEPL measurement error of protons traversing the sinus insert and other 392 inserts is comparable. Thus, the very large relative error of the sinus insert is caused by 393 its small reference RSP, which is the mean value of the air and the trabecular material of 394 the sinus composite. It is conceivable that the systematically lower RSP values measured 395 by both scanners in the case of the sinus insert, are since the mean distance travelled in 396 the air component is larger than that travelled in the denser material due to preferentially 397 larger scattering out of the denser material. The next worse RSP<sub>acc</sub> for both scanners was 398 found to be that of the phantom body, with  $-1.33 \pm 0.25\%$  and  $-2.40 \pm 0.29\%$ , respectively. 390 This is to some extent expected as, unlike the small ROIs used for the inserts, the large 400 area in which the body of the phantom RSP<sub>acc</sub> was quantified contains most of the observed 401 ring artifacts. For example, quantifying the phantom body RSP in a ROI as large as for 402 the insert at the center of the phantom yielded an accuracy of -0.1% and 1.63% for the 403 phase-II and the pVDA scanners, respectively. When the same sized ROI was moved to a 404 radial distance similar to that of the other inserts, the  $RSP_{acc}$  was -0.92% and -0.1% for 405 the phase-II and the pVDA scanners, respectively. Removing the body of the phantom from 406 the MAPE analysis improves the phase-II scanner accuracy only marginally, from 1.14% to 407 1.12%, again because it is dominated by the difference in the sinus insert. On the other hand, 408 for the pVDA the MAPE without the phantom body improves from 0.81% to 0.61%. Finally, 409 a more selective RSP quantification which excludes both the phantom body and the sinus 410 yields for both scanners equivalent MAPE of  $0.63 \pm 0.10\%$  and  $0.48 \pm 0.10\%$ . That MAPE of 411 the phase-II scanner (without sinus and phantom body) agrees well with the result from<sup>41</sup> 412

<sup>413</sup> (0.55%), which was obtained from a set of inserts from a different phantom, but covering a <sup>414</sup> similar RSP range and making use of the same reconstruction algorithm.<sup>29</sup>

For both scanners, the spatial resolution obtained from this phantom was within the 415 range expected for pCT systems. For the phase-II scanner, it varied from 0.59 lp/mm to 416 0.62 lp/mm. This result is in good agreement with what was reported by Plautz et al.,<sup>56</sup>. In 417 that work, two quantities where the spatial resolution was quantified, were used to define the 418 location in a phantom. These were the circle's minimum chord intersecting the insert and 419 the smallest distance of the insert from the surface of the phantom. For the phantom used in 420 our study, these values were  $130-150 \,\mathrm{mm}$  in WEPL and about  $20-30 \,\mathrm{mm}$ , respectively. For 421 the pVDA scanner, the spatial resolution was found to be lower, ranging from  $0.44 \, \text{lp/mm}$  to 422 0.48 lp/mm. This can be explained by the fact that the phase-II scanner implements a full 423 tracking capability at the cost of a less compact detector scheme, while the pVDA scanner 424 comprises a more compact tracker design for future clinical use. Furthermore, the lower 425 energies used with the pVDA scanner also affect the scattering power of protons, which is 426 expected to impact spatial resolution. 427

To test this hypothesis, we made use of the formalism published in Krah et al.<sup>54</sup> to 428 estimate the relative loss of resolution expected from removing downstream position mea-429 surements for the phase-II scanner. This led to a decrease of resolution by a factor 1.5, 430 which is in reasonable agreement with the decrease by a factor 1.2 to 1.4 observed for the 431 inserts of table 4. It is thus likely that the use of position-only trackers downstream, where 432 directions cannot be approximated by the vector from the source to the position registered 433 by the tracker (as opposed to the upstream tracker), contributes chiefly to the lower spatial 434 resolution of the pVDA scanner. Approximating the pVDA scanner by the phase-II scan-435 ner without downstream directions should be valid since both scanners have a distance of 436 approximately 16 cm between trackers and the isocenter. 437

Whether the difference in spatial resolution affects dosimetric and range prediction accuracy when pCT is used for treatment planning remains to be investigated. Finally, the spatial resolution was evaluated at inserts located at relatively large radii. For more central inserts, where MCS has an increased role, the difference between the two scanners may be reduced and dominated by the accuracy of the MLP.

# 443 V. Conclusion

The comparison of the phase-II and pVDA particle tracking pCT scanners showed that they 444 provide similar  $RSP_{acc}$  (both a MAPE of 0.72%) when excluding the porous sinus insert; 44 when including it the phase-II scanner performed slightly worse than the pVDA (1.14% vs.)446 0.81% respectively). Spatial resolution estimated by three high density cylindrical inserts was 447 found to be 0.61 lp/mm for the phase-II scanner and slightly lower, at 0.46 lp/mm, for the 448 pVDA scanner. Their spatial resolution performance reflects the different hardware design 449 choices, with the more compact pVDA tracker, which does not provide directions, leading 450 to a slightly lower spatial resolution. The clinical significance of these findings remains to 451 be studied. 452

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# 459 Conflicts of interest

M. Pankuch and R. W. Schulte are members of the advisory board of ProtonVDA LLC. E.
DeJongh is employed by ProtonVDA LLC.

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