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Contribution of Sentinel-2 satellite images for habitat mapping

2 of the Natura 2000 site 'Estuaire de la Loire' (France)

spread evenly over a year and performed a multi-date classification of 9 images. We obtained high overall accuracy between 76.47% and 87.28% for the single-date image classifications and 98.7% for multi-date image classification. Our results demonstrate that Sentinel-2 images are appropriate for accurate habitat mapping and constitute a relevant tool to identify and conserve habitats of community interest.

1. Introduction

Preserving habitats is a major challenge for European nature conservation policies (Bijlsma et al., 2019). The implementation of the Habitats Directive 92/43/CEE (HabDir) especially permitted to target the most threatened habitats for which the European Union (EU) is committed to ensuring the maintain or the restoration to a favorable state of conservation (Art. 2 of HabDir) (Evans & Arvela 2011; Schaminée et al., 2016). Moreover, the Directive imposes applying measures of conservation and assessing the state of these habitats regularly. More specifically, naming protected areas led to the creation of the Natura 2000 network for which it is necessary to gather information on

41 the habitats' distribution and surface areas (Evans, 2012).

To meet this goal, the EU member states need precise, simple and reproducible methods. Mapping represents an excellent tool to evaluate the habitat distribution and surface areas (Bunce et al., 2013). Currently, mapping methodologies are mainly based on field surveys and photo-interpretation (Ichter et al., 2014). These methods require roaming all the study areas to gather data on the vegetation and environmental factors characterizing the habitats. However, this type of mapping becomes quickly very time-consuming, costly and therefore difficult to implement in large and difficult-to-access territories (Kopeć et al., 2016; Moran et al., 2017). This is especially the case when mapping wetlands, which tend to be inaccessible because of numerous canals and flooded areas. (Harris et al., 2015; Zlinszky et al., 2014). Furthermore, this type of work is often subjective, which is why the cartographic productions can greatly vary from one operator to the other (Cherrill, 2014; Raab et al., 2018; Ullerud et al., 2018).

Approaches based on remote sensing currently offer many opportunities for cost-effective, rapid and reproducible mapping (Corbane et al., 2015; Vanden Borre et al., 2011). More and more studies show that remote sensing is increasingly used for mapping natural environments (Lang et al., 2015). For example, this is the case for studies on the mapping of alkaline peatland habitats in Poland using Rapid-Eye satellite images (Stenzel et al., 2014) or on mapping Belgian heathland habitats using hyperspectral airborne imagery (Haest et al., 2017). The quality of the remote sensing-based image classification depends on the characteristics of the images used, like the number of available spectral bands, the spatial resolution or the sensor's acquisition frequency. The Sentinel-2 satellite constellation produces 13-band multispectral images in the visible and infrared frequency range with a minimum spatial resolution of 100 m² and a high revisit frequency (several images per month). These characteristics are a good compromise for mapping wetland vegetation, in particular through multi-date classifications (Rapinel et al., 2019; Vrieling et al., 2018). To overcome these obstacles, remote sensing is a pertinent tool for identifying and locating habitats and, more broadly, areas with conservation issues. In this context, this study aims to assess the contribution of Sentinel-2 satellite images to mapping habitats in the Loire estuary by (1) developing an exhaustive typology of habitats from ground reference data and by (2) testing the accuracy of single-date and multi-date Sentinel-2 image classification using the Random Forest algorithm.

2. Materials and Methods

2.1 Study area

73 The Natura 2000 site 'Estuaire de la Loire', located in western France (47° 15′N, 1° 54′O) (Fig. 1), is an estuary formed by the Loire's alluvial plain which covers an area of 26,000 ha. It is a tidal wetland site of major ecological importance, hence its designation in 2004 as a Natura 2000 site (FR5200621 – Estuaire de la Loire). The site is recognized for the diversity of its ecosystems, from coastal habitats of dunes and salt marshes to agropastoral habitats of freshwater marshes and woodland habitats. The

- large variety of habitats is mostly linked to flood frequency and duration, variations in exposure to
- salinity, as well as agricultural management (mainly mowing and grazing).

Fig. 1. Location of the Natura 2000 site 'Estuaire de la Loire' and available ground data.

2.2 Typology of habitat types

We used two habitat classification systems to establish the typology: EUNIS

(European Union Nature Information System), which represents the most complete habitat repository

in Europe, covering both marine and terrestrial environments (Chytrý et al., 2020; Evans, 2012) and

the Interpretation Manual of European Union Habitats-EUR28 (European Commission, 2013), which

- includes definitions of the habitats of community interest in annex 1 of HabDir.
- The typological units of these habitat repositories are mostly defined by vegetation classifications
- derived from sigmatist phytosociology (Gayet et al., 2018; Rodwell et al., 2018). We established the
- study site's habitat typology by identifying field vegetation plots which were collected using the
- sigmatist phytosociological method. A vegetation plot corresponds to the list of plant species
- inventoried inside areas with a floristically homogeneous composition (Dengler et al. 2008). The cover

of each species is visually estimated and quantified according to the Braun-Blanquet's scale (Braun-Blanquet, 1932).

We used 1,248 phytosociological vegetation plots to obtain a representative sampling of the diversity of habitat types present in the study site (Fig. 1). A total of 989 phytosociological vegetation plots were collected from the bibliography (scientific publications, PhD theses, impact studies, vegetation maps…) and we collected in the field 259 phytosociological vegetation plots for this study. This dataset is constituted of vegetation plots that were collected from 2010 to 2019. Older vegetation plots were not selected because of a too long-time gap between field and satellite data. Most bibliographical vegetation plots were located precisely (horizontal accuracy <5 m) and those collected during this study were georeferenced using a differential GPS (GPS GeoXH™ from Trimble Geo-Explorer®, horizontal accuracy <1 m).

Firstly, we assigned vegetation plots to a phytosociological unit based on the descriptions contained in the Prodrome of French Vegetation (Bioret et al., 2013). Secondly, phytosociological units were related to EUNIS and EUR28 habitat types. This step (hereafter call "crosswalks") has been carried out using the French repository of habitats and vegetation typologies HABREF (Clair et al., 2019).

2.3 Acquisition of Sentinel-2 images

Covering the entire site requires using two Sentinel-2 image tiles (tiles' identification numbers:

T30TWT and T30TXT). We looked for images without cloud cover and regularly distributed along an

annual cycle of vegetation. Overall, we used 22 Sentinel-2 images (Level-2A – product-Bottom of

Atmosphere (BOA) reflectance), corresponding to 11 acquisition dates from autumn 2018 to summer

2019 (Fig. 2).

117 **Fig. 2.** Acquisition dates of Sentinel-2 images during an annual cycle of vegetation.

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119 *2.4 Image preparation and vegetation indices calculations*

Sentinel-2 images are distributed with three spectral bands at 60m spatial resolution (B1, B9 and B10), six bands at 20m spatial resolution (B5, B6, B7, B8A, B11 and B12) and four bands at 10m spatial resolution (B2, B3, B4 and B8) (Table 1). For each date, we only selected the bands with a spatial resolution of 10m and 20m (the 60m bands were mostly intended for the atmospheric corrections). We stacked the bands with the same spatial resolution and the 20m bands were interpolated on a 10m grid using the bilinear approach. Finally, all bands were stacked to form an image of 10 spectral bands with a 10-meter spatial resolution.

127 **Table 1** Sentinel-2 band characteristics

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128

130 **Calculating vegetation indices**

131 Remote sensing spectral indices are based on the combination of spectral bands to highlight

132 biophysical characteristics of land surfaces. They are particularly useful for multi-date classifications

133 as they are good indicators of seasonal changes of vegetation cover (Schuster et al., 2015). In this

134 study, we have selected a set of 12 spectral indices (Table 2) covering the full spectral domain of

147 **Table 2** List of vegetation indices calculated using Sentinel-2 spectral bands.

B, G, R, RE1, RE2, NIR, SWIR1, represent blue, green, red, red-edge 1, red-edge 2, near-infrared and and shortwave-infrared 1 spectral bands.

1.NDI45: Normalized difference index 4 and 5 *NDVI: Normalised Difference Vegetation Index EVI: Enhanced Vegetation Index NDWI: Normalized Difference Water Index SAVI: Soil Adjusted Vegetation Index IReCI: Inverted Red-Edge Chlorophyll Index CRE: Chlorophyll Red-Edge index PSSRa: Pigment Specific Simple Ratio S2REP: Sentinel-2 red-edge position*

GNDVI: Green Normalised Difference Vegetation Index MCARI: Modified chlorophyll absorption in reflectance index MTCI: MERIS Terrestrial Chlorophyll Index

149 Finally, we cropped the images according to the study area's limits and we excluded artificial areas

150 using auxiliary thematic layers integrating roads, built-up and cultivated areas as suggested by Inglada

151 et al. (2017) and Rapinel et al. (2015).

2.5 Selection of training data

We vectorized a Sentinel-2 image to build a vector grid consisting of 100m2 polygons (10*10m) used as support to select training areas. We superimposed this grid on a very high spatial resolution image from spring 2018 (Google Earth: Images CNES ©/Airbus, Maxar Technologies©). Based on the location of the phytosociological vegetation plots, we individually and manually selected polygons covering visually homogenous vegetation units ('pure' pixels) (Fig. 3). The training areas had to respect a criterion of physiognomic and colorimetric homogeneity so as not to select mixed habitats (mosaic) or pixels overlapping several typological units.

Fig. 3. Methodological process to select training data. (a) very high spatial resolution image of the study area (the red marked pixels indicate the training data's location). (b) Zoom on a part of the study

area with the vector grid displayed and the polygons selected for three EUNIS habitats (red:

EUNIS A2.551; pink: EUNIS F9.3131; sea green: EUNIS A2.511). The yellow dots correspond to the

phytosociological vegetation plot locations. (c) A phytosociological vegetation plot and photograph of

- habitat EUNIS A2.551 acquired during fieldwork.
- We used a study of the spatio-temporal dynamics of vegetation in the Loire estuary (Le Dez et al.,
- 2017) to determine the level of stability of plant communities in the study area. For plant communities
- with a high degree of stability (e.g. woodlands, forests and some types of meadows), we selected
- training areas using data up to the year 2010. On the other hand, for highly dynamic plant
- communities, we have only kept the plots collected during the year of acquisition of satellite images
- (e.g. annual salt marshes vegetation (A2.551 '*Salicornia*, *Suaeda* and *Salsola* pioneer salt marshes')
- or reedbeds on regularly submerged banks (C3.27 'Halophile *Scirpus*, *Bolboschoenus* and
- *Schoenoplectus* beds'). In addition, during the pixel selection phase by photo-interpretation, we
- checked that the pixels viewed and the habitat categories identified in the typology were consistent so
- as not to take training samples in locations where the vegetation might have changed.
- Finally, we selected additional pixels for some habitat categories that were easily recognizable by
- photo-interpretation and for which we had little field data (e.g. C3.21 '*Phragmites australis* beds' or
- G1.1111 'Western European white willow forests').
- We made sure to select a number of training data that was proportional to the area covered by each habitat on the study site (Colditz 2015; Raab et al., 2018).
-
- *2.6 Classification method*
- *2.6.1 Choosing the classification algorithm*

We used the Random Forest (RF) algorithm (Breiman 2001) to classify the habitats. RF is a machine

learning classifier commonly used in remote sensing and many studies showed that it could produce

accurate maps of vegetation and habitats types, including from Sentinel-2 (Marzialetti et al., 2019;

Rapinel et al., 2020; Wittke et al., 2019). RF is especially known to be fast (requiring little calculation effort) and able to process asymmetric data with many predictive variables (Millard and Richardson, 2015; Sławik et al., 2019). In RF model, the original training data are randomly sampled-with-replacement generating bootstrap samples. Each decision tree in RF is trained on an 'in bag' sample of the original training data. The remaining sample ('out of bag' sample) is used to be predicted by all the decision trees that allowed to evaluate the outcome (known as OOB score). For our analyses, we set the number of trees to 2,000 and the number of randomly sampled variables as candidates for each 196 split to six.

We used the overall accuracy index (OA) and the Kappa coefficient to evaluate the overall quality of classification models (Smits et al., 1999; Stehman, 1997). We produced confusion matrices representing errors by class after each modeling and we calculated the producer's, as well as the user's accuracy (respectively PA and UA), for each habitat (Congalton, 1991). These accuracy assessment metrics are commonly used in remote sensing (Belgiu and Csillik, 2018; Calleja et al., 2019; Rana and Venkata Suryanarayana, 2020). After processing each image, we applied the model produced from the training areas to the entire image to create a predictive habitat classification of the entire study area.

2.6.2 Selection of the most important variables for multi-date image classification

From the 11 Sentinel-2 image acquisition dates, we identified the most important variables (acquisition dates, spectral bands and vegetation indices) to classify habitats of the Natura 2000 site. It is possible to select the best variables using automatized methods as suggested by the Recursive Feature Elimination algorithm (Radecka et al., 2019; Rapinel et al., 2019). However, we chose to develop our supervised methodology by first assessing which of the 11 image acquisitions were relevant for separating habitat classes. The general objective is to first integrate seasonal phenological variations for all the habitats in the study site. Vegetation growth stages differ among plant communities which is an important characteristic to be used for classification. Thus, the images must

include vegetation changes starting with the development of the earliest plant communities until those appearing the latest (mainly from early spring to autumn for this site).

First, we performed an RF classification for each of the 11 dates and we assessed the overall quality of

the classification models using OA. We wanted to only keep the acquisition dates of the images with

the highest performance, so we set an accuracy threshold at 80% (OA=0.8). Above this percentage, we

considered the classification result as satisfying, as suggested by Rapinel et al. (2014) and Zlinszky et

al. (2014). All images over this threshold (OA>0.8) were retained while those below (OA<0.8) were

excluded because we considered their performance as too low.

Secondly, we tested the importance of the spectral variables (spectral bands and vegetation indices)

using the measures of mean decrease Gini (MDG) obtained from the RF algorithm classification

(Hubert-Moy et al., 2020; Li et al., 2019). For each selected date (OA>80%), we selected the five best

performing variables (spectral bands, vegetation indices) based on MDG (Grabska et al., 2019).

Finally, we stacked all these variables (five best performing bands and/or indices of the dates with

OA>80%) to build the multi-date feature dataset.

2.7 Software:

We used the R software (version 3.6.2) (R Development Core Team, 2019) for our analyses, with the

packages 'randomForest' (version 4.6-14) (Liaw & Wiener, 2002), 'rgdal' (version 1.4-8) (Bivand et

al., 2015) and 'raster' (version 3.0-7) (Hijmans, 2015). The results were visualized in QGIS 3.4.8

(QGIS Development Team, 2019).

3. Results

3.1. Typology of habitats

3.1.1. Complete typology of habitats in the Natura 2000 site

The complete typology brings together all the habitats identified on the study site. They are presented in Appendix A. Overall, we characterized 74 phytosociological units based on phytosociological plots' identification.

The crosswalk of phytosociological units with EUNIS habitat types led us to identify 62 habitats. Waterbodies and reed bed habitats and grassland habitats were the most diversified with 19 and 15 244 habitats respectively. Two grassland habitats are made of a mosaic of EUNIS habitats (E2.1xE2.5 $\&$ E3.44xA2.5) linked to vegetation plots with an intermediate floristic composition between several vegetation communities (transitional vegetation). Marine habitats are also diversified with 14 EUNIS habitats inventoried. Woodland and forest habitats, as well as shrubs and thicket habitats are more unified with respectively 7 and 6 EUNIS habitats. Finally, cultivated plots constitute the last EUNIS habitat in our typology.

The crosswalk with EUR28 habitat types led us to determine 15 habitats of community interest (HCI) including 3 that are considered as a priority. All the marine habitats are HCIs and represent half of the total number of HCIs with 7 EUR28 habitats, including 1 priority. The other HCIs include waterbodies and reed bed habitats (4 HCIs, of which 1 is a priority), grassland habitats (2 HCIs), woodland and forest habitats (2 HCIs, of which 1 is a priority) and shrub and thicket habitats (1 HCI).

3.1.2. Typology retained for the classifications after selection of the training data

The typology retained to classify the images is presented in Table 3. It includes all phytosociological units for which training areas could be selected. The other phytosociological units did not cover enough surface area to compose 'pure' pixels; therefore, they could not be integrated into this typology.

Ultimately, only 44 of the 74 phytosociological units identified could be included in the final

typology. This result corresponds to 39 EUNIS habitats out of the 62 identified and 9 EUR28 habitats

- out of the 15 identified in the Natura 2000 site.
- **Table 3** Habitat typology used for image classification (habitats for which pixels could be selected).
- 'Nb pixels' corresponds to the number of pixels selected as training area for the image classification.
- The EUR28 habitats marked in bold correspond to priority habitats of community interest in HabDir.
- Fields marked with an asterisk correspond to non-vegetated or artificialized areas. They were assigned
- to habitat typologies based on the biotope using the criteria of the French EUNIS habitat determination
- guide (Gayet et al., 2018) and the 'Cahiers d'habitats' (Bensettiti et al., 2001–2005).

272 The number of training pixels per typological unit varies from 15 (mud bottoms of waterbodies) to 777

273 (*Alopecurion utriculati* Zeidler 1954). Overall, 5,564 training pixels were selected for all the data.

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275 *3.2 Analyses of single date images*

- 276 Overall accuracy indices of the single classification of the Sentinel-2 images for the 11 selected dates
- 277 are presented in Fig. 4. Images acquired during spring and summer gave the best results (OA>85%).

The highest accuracy was obtained with the image of July 6, 2019 (OA=87.28%). The classifications of the images taken at the end of winter and in autumn present slightly lower results (80 %< OA <85%). The less accurate classifications are from the late autumn and winter images (OA <80%).

Fig. 4. Overall accuracy indices of the single date classifications of Sentinel-2 images for the 11 dates. The dotted line shows the 80% threshold used to select the best-performing dates.

3.3 Selected variables to build the multi-date feature dataset

Based on the results of the single-image classifications, we selected images of nine dates that had an overall accuracy higher than 80% (Fig. 4). For each of these dates, we kept the five variables (spectral bands and vegetation indices) that contribute most to the classification result according to MDG (Table 4, Appendix B). In total, six different spectral bands and four vegetation indices were included in the multi-date feature dataset. The spectral bands B11 and B12 (SWIR) were systematically present for the nine dates, while the bands B5 (red-edge), B3 (green) and B2 (blue) are only present for six, four and two dates respectively and the band B8A (near-infrared narrow) only for one date. Regarding vegetation indices, GNDVI and MTCI are present for seven and four dates respectively, whereas NDWI and EVI both appear for two dates. In total, 45 variables were retained and stacked to build the multi-date feature dataset.

Table 4 List of the five variables that contributed most to the single-date image classification (spectral bands and vegetation indices) according to MDG for each date. The number indicates the variable's order of importance according to MDG for each date (the most contributing variables are indicated by the lowest numbers - for more details, see Appendix B).

Fig. 5 shows the seasonal variations of the main variables (Table 4) for habitat discrimination. The GNDVI index and B2 (blue) and B3 (green) spectral bands allow good discrimination of habitats A2.2 'Littoral sand and muddy sand' and A2.3 – 'Littoral mud' all year long. On the contrary, the phenological profiles of the other habitats cannot be easily distinguished over the period studied. Overall, temporal profiles have more similar values during wintertime. The main reflectance and intensity variations of the indices are observed in spring and summer. More precisely, it is the temporal shifts in spectral responses that allow the distinction of habitats. For example, habitats A2.523 – 'Mediterranean short *Juncus, Carex, Hordeum* and *Trifolium* salt meadows' and A2.511 – 'Atlantic salt marsh and drift rough grass communities' show similar profiles on some bands (B11 and B12) and some indices (NDWI and EVI). However, they peak at different dates (June 26, 2019, for A2.523 and August 25, 2019, for A2.51) because of mowing taking place at different times.

 \rightarrow A2.511 \rightarrow G1.211 \rightarrow E3.512 \rightarrow A2.553 \rightarrow A2.542 \rightarrow G1.1111 $-A2.2$ \div F9.3131 \div G1.22 \div A2.3 \div A2.551 \div E5.412 \div A2.531 \div A2.523

Fig. 5. Seasonal variations of the most important variables (Table 4) for habitat discrimination in the study site. Only the spectral profiles of EUNIS habitats characterizing habitats of community interest are represented. The curves are plotted from the average for all training pixels for each habitat.

3.4 Multi-date classification

The confusion matrix showing the results of the RF classification of the multi-date feature dataset is presented in Table 5. The predictive habitat map obtained after running the RF model on all pixels of the investigation area is shown in Fig. 6. The results are presented at the EUNIS habitats level after merging the phytosociological units corresponding to the same habitat category, following the crosswalks in Table 3.

The overall evaluation of the model shows highly satisfying results with an overall accuracy of 98.7% and a kappa coefficient of 0.99. The producer's accuracy is 100% for 19 habitats out of the 39 in the EUNIS habitat typology. The other habitats present moderate errors leading us to obtain a producer's 329 accuracy higher than 90%, except for EUNIS habitats D5.21, E3.512 and F9.2 with a PA of 87.5%, 75% and 89.7% respectively. These results indicate that these habitats tend to be underrepresented in the predicted habitat map (Fig. 6).

In the same way, the user's accuracy is highly satisfying with 21 habitats with 100% UA whereas other habitats still present an accuracy higher than 90% UA. These slight confusions lead to an overrepresentation of habitats in the predicted map (Fig. 6).

Figure 7 shows that habitats with a high number of training areas obtain a very high estimated

producer's accuracy (PA). This is the case for habitat A2.523 – 'Mediterranean short *Juncus, Carex,*

Hordeum and *Trifolium* salt meadows' with 874 training pixels and a 99.4% PA or habitat E3.41 –

- 'Atlantic and sub-Atlantic humid meadows' with 706 pixels and a 99.6% PA. Conversely, habitats
- with a lower PA have fewer training areas, such as habitat E3.512 'Acidocline purple moor grass
- meadows' with 20 training and a 75% PA or habitat D5.21 'Beds of large *Carex spp.*' with 48

- 341 training pixels and an 87.5% PA. However, some habitats with few training areas are very well 342 modeled due to their specific spectral signatures, which are very different from those of other habitats. 343 This is the case for habitats A2.531 – 'Atlantic upper shore communities' (21 pixels and a 100% PA) 344 or E5.412 – 'Western nemoral river bank tall-herb communities dominated by *Filipendula*' (19 pixels 345 and a 100% PA).
- 346 **Table 5** Confusion matrix between the reference data (line) and the classified data by RF (columns)
- 347 for the 39 EUNIS habitats.

- **Fig. 6.** Predicted map of the 39 EUNIS habitats in the Natura 2000 site 'Estuaire de la Loire'. The
- codes correspond to EUNIS habitat identifiers and crosswalks with EUR28 habitats are indicated in
- brackets. For details of the full habitat headings, see Table 3.

Fig. 7. Correspondence between the number of training data and the producers' accuracy (PA) for the 39 EUNIS habitats. Note that x-axis is in a log-scale.

3.5 Map description

Visually examining the final predictive map led us to evaluate qualitatively the consistency level with

the reality in the field. Overall, the mapped units' distribution is consistent with the general

organization of known habitats in the Loire estuary.

- Marine habitats are distributed along both sides of the river downstream of the Natura 2000 site, which
- are most subject to oceanic influences. In these areas, Mediterranean salt meadows
- (EUNIS A2.523/EUR28 1410) cover vast areas homogeneously. Upstream, these salt meadows also
- develop in numerous areas as patches that mix with other habitats. Thus, these meadows represent the
- most extensive habitat with 5,047 ha mapped, corresponding to 19% of the study site's total surface.

Reed beds are frequently near the river, in areas that are regularly flooded by the tides. Among reed bed habitats, habitat C3.21 – '*Phragmites australis* beds' is dominating (977 ha) and regularly distributed in tidal marshes throughout the site. Habitat C3.27 – 'Halophile *Scirpus*, *Bolboschoenus* and *Schoenoplectus beds*' colonizes the downstream areas (510 ha) while habitat C3.251 – 'sweetgrass beds', intolerant to salt, succeeds it when going upstream (747 ha).

Grassland habitats also cover large areas (10,400 ha) and are distributed mostly upstream and on the

margins of the site, i.e., in areas that are less subjected to saltwater intrusions. Thickets and forests are

rarer and cover smaller areas with 1,471 ha and 1,027 ha respectively. These habitats usually do not

- tolerate salt, hence their location on the most upstream areas of the Natura 2000 site.
-

4. Discussion

4.1 The Importance of field data

Using a large amount of field data is paramount to ensure high accuracy in the classification of remotely sensed images (Calleja et al., 2019; Yeo et al., 2020). Several authors insist on using a wide range of vegetation plots to establish a complete typology of habitats (Chytrý et al., 2016; Rodwell et al., 2018). In this study, we relied on a large phytosociological plots dataset which led us to develop a complete and accurate typology of the study site. Beyond confirming the diversity of the habitats present at the Natura 2000 site, we used these field plots to calibrate the RF algorithm for image classification. Indeed, these field data are essential to locate and precisely sample the training areas to optimize image classification (Millard and Richardson, 2015). We conducted this step pixel by pixel by selecting only visually homogenous areas. The number of training pixels per habitat varies and depends on the number of field plots and habitat homogeneity. In general, the most widespread habitats are characterized by more training pixels to assess their variability at the scale of the study site (Colditz, 2015; Raab et al., 2018).

Most of the plots we used are derived from bibliographical data and were collected through an important work of synthesis of the studies previously conducted on site (impact studies, vegetation maps…). Accessing preexisting data is essential to develop a robust typology and to calibrate classification algorithms. Thus, it is essential to centralize and share field plots, and especially to implement common databases (Gautreau and Noucher, 2013), such as the European Vegetation Archive which gathers thousands of vegetation plots across Europe (Chytrý et al., 2016).

However, despite compiling numerous phytosociological vegetation plots, we could only use a part to calibrate the classifier. Indeed, several habitats could not be selected inside Sentinel-2 pixels because the images' spatial resolution was insufficient to integrate habitats of small surface areas. This led us to only use a partial typology of habitats compared to the initial typology established from all the plots. For example, aquatic vegetation (i.e. *Lemnetalia minoris* or *Hydrocharition morsus-ranae*), which are uncommon and occupy small areas, could not be represented in the final map. To overcome this problem, other remote sensing images could be tested, such as high spatial resolution data (Gavish et al., 2018; Strasser and Lang, 2015). For example, Espel et al. (2020) used very fine-scale resolution Pléiades satellite imagery (50cm) to map aquatic vegetation in France.

4.2 Single-date image classification

4.2.1 Determining the most favorable image acquisition dates

Analysis of mono-temporal Sentinel-2 imagery showed that it is possible to obtain a satisfying level of classification when using only one acquisition date. This is particularly the case for the image of July 6, 2019, for which we obtained an overall accuracy of 87.74%. Analysis of the overall accuracy (OA) obtained for each date led us to determine the most favorable times of the year to get good discrimination of the habitats. Even if the overall accuracy differences are small between dates 414 ($\Delta = 11\%$), images acquired in spring and summer noticeably give the best results. This time of year is especially marked by rapid phenological variations in vegetation (appearance of leaves, flowering). Those variations are linked to the increase in day length and temperatures (Meier, 1997), as well as to

the receding water from winter flooding due in particular to evapotranspiration and the hydraulic management of marshes (Reed, 1993). During this period of maximum vegetation growth, the plants' expression of pigment content is most pronounced, favoring habitat discrimination (Addabbo et al., 420 2016). These observations are consistent with the results of recent studies for vegetation mapping from series of remote sensing images on floodplain meadows (Rapinel et al., 2019) or salt marsh vegetation (Vrieling et al., 2018).

4.2.2 Determination of the most favorable spectral bands and indices

In this study, most habitats are characterized by vegetation whose spectral response is determined by plants' biochemical and biophysical properties (Peñuelas and Filella, 1998). Over time, variations of reflectance values and indices reflect plants' phytosociological changes (pigment composition, plants' internal tissue structure) allow us to differentiate habitats according to their floristic composition (Cole et al., 2014). MDG led us to highlight the most contributing variables for habitat mapping of the study site.

B11 and B12 spectral bands appear as the best performing bands for all dates. These shortwave-infrared (SWIR) spectral bands are especially characterized by their sensitivity to water on the earth's surface (Middleton et al., 2012; Psomas et al., 2011) and to biochemical contents such as lignin and cellulose in plant cover (Fourty et al., 1996). SWIR bands can be particularly useful for mapping 435 wetlands where plant communities are marked by flooding gradients (Rapinel et al., 2019). The B5 band is located at the beginning of the red-edge curve (704.1 nm), and it also represents an important variable to discriminate the study site's habitats. Several studies have shown that different meadow vegetation types can be effectively discriminated using red-edge wavelengths (Pinar and Curran, 1996; Shoko and Mutanga, 2017) due to its sensitivity to variations in chlorophyll concentration (Curran et al., 1990; Sims and Gamon, 2002). SWIR and red-edge spectrum regions are interesting for mapping wetland vegetation as demonstrated by several previous studies (Dronova, 2015; Dronova et al., 2012; Franke et al., 2012). GNDVI (based on NIR (B8) and green (B3) bands) is the most important

The other retained variables contribute to a lesser extent: MTCI (analysis of the red-edge curve with B4, B6 and B5), B3 (leaf green intensity), NDWI (leaf water content with B8 and B11), B2 (leaf blue-green intensity), EVI (leaf pigment content with B2, B4 and B8) and B8A (leaf structure). Overall, we notice that most available spectral bands contributed to the classifications' success. Thus, our results confirm the relevance of the different spectral regions covered by Sentinel-2 satellites for vegetation mapping (Fauvel et al., 2020; Grabska et al., 2019).

4.3 Multi-date classification

While individual image analyses achieved satisfactory levels of accuracy, the multi-date classification considerably improved habitats modeling accuracy with a 98.8% OA and a 0.99 Kappa. PA and UA are at 100% for numerous habitats showing a perfect match between reference and modeled data. For the other habitats, PA and UA are still very close to 100%, thus indicating respectively low over-or under-representation in the final map.

Numerous authors demonstrated the accuracy improvement brought by multi-date classifications

compared to single-date classifications (Belgiu and Csillik, 2018; Feret et al., 2015; Raab et al., 2018).

Rapinel et al. (2019) especially highlighted the benefits of a Sentinel-2 multi-date classification to

differentiate marsh plant communities according to the flood duration and management measures

(mowing, grazing). In the same way, the evolution of these parameters during our study period

contributed to the success of the habitat classification of the Loire estuary.

4.4 Habitat mapping by remote sensing: contributions for nature conservation

Our work led us to elaborate a map of EUNIS habitats from which it is possible to highlight conservation issues, specifically those linked to the European Habitat Directive (HabDir). Even if we could not map all the habitats of community interests due to their small surface areas, we mapped 9 HCIs from typological crosswalks, representing a total of 7,080 ha, i.e. 26% of the total surface area of the site. Among all the habitats, HCI 1410 'Mediterranean salt meadows (*Juncetalia maritimi*)' covers the largest area (5,047 ha, 19% of the total surface area). Thus, the use of Sentinel-2 images contributes to locate and quantify the occupied areas for these habitats of the Natura 2000 site: distribution and range being two parameters retained to assess the conservation status according to Art.17 of HabDir (European Commission, 1992; DG Environment, 2017). These data are essential for managers to define conservation measures to maintain the HICs. Thus, the habitat map produced during this study meets the needs of the manager of the Natura 2000 site 'Estuaire de la Loire' and will be essential to preserve this natural site.

Overall, our results show that it is possible to obtain habitat maps quickly and at a low cost compared with conventional fieldwork (Ichter et al., 2014). This method can be transposed to other natural sites, in or outside the Natura 2000 network, which has the advantage of promoting a common and standardized methodological approach to habitat mapping. In addition, the approach we offer completely meets the European requirements as part of the reporting required by Europe for each member state. Indeed, this method could be adopted to evaluate the distribution and areas of habitats at the European scale, two parameters defined by the HabDir to assess the conservation status of HICs (Bijlsma et al., 2019; Gigante et al., 2016). Furthermore, this method can be used for long-term monitoring of habitats based on regularly produced maps (every three or four years depending on the habitat type). The approach we developed meets the need for a monitoring method which could be proposed as part of Art. 11 of HabDir on surveillance of the conservation status of HICs (Delbosc et al. 2021).

5. Conclusion

Our results demonstrated that Sentinel-2 images allow for accurately mapping habitats and that their spectral resolution is particularly adapted to the study of wetlands. The high revisit frequency of Sentinel-2 satellites ensures the regular acquisition of images throughout the year, allowing multi-date image classification. This method led us to obtain a highly accurate habitat map, which considerably improves the accuracy level compared to single-date image classification. However, the spatial resolution of Sentinel-2 remains insufficient to include numerous habitats that are only locally and occasionally present. In this study, only 23 out of the 62 EUNIS habitats could be mapped. Consequently, using these images can only be considered to map habitats with a surface area higher than 100 m². Our results generally show that Sentinel-2 data are adapted to create habitat maps at a 1:25 000 scale. For finer-scale mapping, Sentinel-2 could be complemented by high spatial resolution remote sensing data such as those provided by other satellites, UAV or airborne acquisitions.

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Appendix B. MDG measures obtained after RF classification for the nine analyzed dates. The five most contributing variables, which have been retained to integrate the temporal series, are marked in bold.

