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A fuzzy classification of the hydrodynamic forcings of the
 Rhone River plume: an application in case of accidental
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16 Abstract

Assessing and modelling the coastal plume dispersion of nuclearized rivers is strategic in case of accidental releases for the protection of vulnerable areas, but taking into account all the possible hydrodynamical conditions is challenging. River plumes are mostly affected by wind and river discharge, but the variability of these two forcings suggest that data mining methods may be particularly effective to define their major trends and influences on the plume behavior.

This study uses fuzzy c-mean clustering on Rhone River (France) discharge and wind speed at its estuary for two objectives: explaining the variability of the riverplume by defining scenarios of hydrodynamic forcings, and relating these scenarios with the

spatial extension of the plume . The application to the Rhone River, the most 26 27 nuclearized European river, highlighted the ability of this method to classify a 10 years 28 serie of wind and discharge into 6 scenarios with remarkable characteristics. These 29 scenarios correspond to different surface currents and plume behaviors, and they were 30 used to simulate the extension and dilution of a radioactive release. These simulations 31 can be used as a quick decision tool, and a decisional tree is also proposed to identify in 32 real time which climatological scenario occurs at the river mouth and the potential plume pattern. 33

34 Keywords:

Coastal plume, Fuzzy c-mean clustering, modelling scenarios, Rhone River, radioprotection, coastalmanagement

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38 1.Introduction :

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40 The Rhone River catchment extends over 98000 km² and covers one fifth of the French 41 metropolitan territory. It is the main source of particles and freshwater for the Gulf of 42 Lion in the North Western Mediterranean sea (Durrieu De Madron et al., 2000), and all together one of the most important input to the Mediterranean sea (Ludwig et al., 2009). 43 The Rhone valley also hosts the largest concentration of nuclear power plants in Europe 44 45 with 4 nuclear power plants in process and a spent fuel reprocessing center, under 46 dismantlement since 1997. Evrolle et al. (2020) recently synthesized the studies showing 47 that this river carries artificial radionuclides from decades, resulting from authorized releases of low level radioactive liquid wastes and from the export of atmospheric 48 49 deposits on watersheds consequently to nuclear weapons testing and Chernobyl accident.

50 France is presently ranked second in the world for the production of nuclear energy, and

- 51 the total electricity production in the combined regions of Northern, Western and
- 52 Southern Europe is projected to increase by 2050 (IAEA 2019). Also, the risk of incident

53 on any kind of nuclear installations is still of concern in France and must be taken into account. As for any river, the transport of artificial radionuclides in case of accidental 54 55 release will occur both in dissolved and particulate form, depending on the amount of 56 suspended particulate matter and on the chemical properties of the radionuclides, and 57 particularly their distribution coefficient (Tomczak et al., 2019). For the Rhone River, the 58 prediction of dissolved vs particulate fluxes and the associated time scale for transit can 59 be evaluated through numerical modeling (Launay et al., 2019), but the behavior of radionuclides once at sea is clearly less constrained, because it will primarily depend on 60 the forcings governing the shape of the Rhone River plume. 61

The area of the Rhone river mouth is characterized by a very small tidal amplitude 62 63 about 30 cm inducing the formation of a sedimentary delta. As usual in this case, the freshwater input forms a thin stratified plume of low salinity water (and higher 64 turbidity) overlying the seawater and extending between 4 and 1000 km² (Estournel et 65 al., 1997; Gangloff et al., 2017) with a thickness decreasing seaward (Pairaud et al., 66 67 2011; Gangloff et al., 2017). It is preferentially deflected westward in a clockwise 68 orientation running East to West (Reffray et al., 2004) due to the general circulation 69 induced by the Northern Current along the continental slope. Under north-northwest winds, the plume extends offshore towards the southwest, whereas it is pushed to the 70 71 coast west of the river inlet in case of southeastern winds. Satellite and modelling 72 results have also shown that the plume size increases with river discharge (Fraysse et 73 al., 2014; Gangloff et al., 2017). More episodic processes impact the plume pattern such 74 as dense water formation and cascading (Ulses et al., 2008), upwelling cells and marine 75 storms (Millot, 1990; Millot, 1999). As a result, this plume extends far beyond the coastal 76 areas and may covers a large area in the GoL extending from the vicinity of the mouth 77 up to the Cap de Creus at the french-spanish border (Sanchez-Cabeza et al., 1992). It can also reach the Gulf of Fos (Gontier et al., 1992; Charmasson et al., 1999) or the Bay of 78

Marseille (Pairaud et al., 2011; Fraysse et al., 2014) on the eastern side of river mouth. 79 The Gulf of Fos is an important economic area with one of the biggest commercial port in 80 81 Europe and a large shellfish area, and Marseille is one of the biggest Mediterranean 82 coastal city with one million inhabitants. Due to the oligotrophic nature of the 83 Mediterranean Sea, the region of freshwater influence (ROFI) of the Rhone river has a major influence on the distribution of plankton groups (Diaz et al., 2019) and thus 84 85 pelagic catches on the GoL. Obviously, the inputs of chemical contaminants from the 86 Rhone River can greatly affect the fishery activity.

87 The combination of meteorological and hydrodynamic forcings with the dynamics of the 88 Rhone River discharge results in a large spatio-temporal variability in freshwater and associated pollutants delivery to the GoL (Martin et al., 2019). If an accidental release 89 occurs in the Rhone River, the dissolved radionuclides may reach the estuary within 48h 90 91 hours to few days depending on the source location and water discharge [unpublished 92 results]. Once at sea, the different shapes that the plume may present will depend on 93 hydrodynamic and weather conditions and will lead to contaminate different areas. 94 Since one goal of radioprotection is to predict the transfer of radionuclides in the 95 environment, there is a need to anticipate their dispersion at any time and in any kind of 96 meteorological and hydrodynamical conditions.

97 Different numerical hydrodynamic models have been set up in the GoL, including the 98 river mouth (Pairaud et al., 2011 ;Duffa et al., 2016), and they could be used actually in 99 case of accidental release in order to predict the behavior of the freshwater input. 100 However, the delay necessary for their implementation will range from few hours to few days, whereas very quick and concise information should be provided to experts and 101 decision-makers as a first picture of the local issues. Also he potentially impacted zones 102 will be better defined by performing afine spatial scale simulation adequately centered, 103 104 compared to a large-scale simulation

As a result, a preliminary study embraces all possible plume patterns is necessary, and a first step is to target the general behavior of the estuarine-plume system. Bárcena et al., (2015) explained that two approaches may be conducted for that: simulating several scenarios using constant conditions of hydrodynamic forcings or simulating few scenarios using the most frequent or extreme real hydrodynamic forcings during short-medium term periods (month to year).

111 These authors demonstrated that the first approach is not complete because real forcings cannot be deduced from the combination of simple idealized scenarios. The second 112 113 approach relies on a subjective selection of scenarios by an expert and it will have an 114 expensive computational cost for simulations if the need is to get on overview of the 115 different kind of realistic responses of the estuarine-plume mean behavior. In this case, and to minimize subjectivity, a methodology based on data mining should be able to 116 117 select the most relevant condensed hydrodynamic scenarios, taking into account the time evolution and the occurrence probability of the forcings. 118

119 Plume classifications based on satellite observations or hydrodynamic model output have 120 been defined in several river-sea systems using Empirical Orthogonal Function or Self-121 Organizing-Map (Falcieri et al., 2014; Xu et al., 2019). Such classification method deals 122 with large spatial scale but implies a heavy data pretreatment like « masking » to treat the satellite data or for the computation of the model. In addition, the need of long-term 123 124 environmental databases (e.g., 10-20 years) to assess probabilities implies significant 125 computational costs as well as long and multiple series of data to be used as boundary 126 conditions and climatic forcings. Another approach is to classify the main hydrodynamics drivers by looking for example at the catchment discharge and the winds intensities and 127 directions (Kaufmann & Whiteman 1999; Zhang et al., 2011). Since the plume response 128 to these forcings can be longer than 24h (Demarcq & Wald, 1984; Estournel et al., 1997), 129 the classification should work observation by observationbut must also keep consistency 130

over longer temporal scales of few days in order to be accurate. Clustering performed on
temporal series helps to assess the consistency of a trend over time, and a fuzzy
clustering algorithm provides a continuous cluster membership function allowing to spot
significant trend changes.

135 In this context, this paper presents a methodology based on statistical analysis and 136 numerical modelling that was developed to address the limitations of the previously 137 mentioned approaches. Firstly, we used a fuzzy c-mean algorithm to identify and classify combinations of winds and discharge at the mouth of the Rhone river in order to define 138 "model scenarios" of realistic forcings. Secondly, the consequences for sea surface 139 currents will be assessed and the resulting plume pattern will be modeled for each 140 scenario, as well as the distribution of dissolved radionuclides due to a hypothetical and 141 episodic release on the Rhone River. These plumes scenario can be used as a support for 142 operational tools improvement and decision. 143

144

145 2.Matérial and Methods

146 2.1 Field study and data

147

The Rhone River hourly discharges have been provided by the C.N.R (Compagnie 148 Nationale du Rhône) thanks to the Rhone Sediment Observatory (OSR program). They 149 were measured at the SORA station, in the city of Arles located 47 km upstream of 150 151 Rhone River mouth (Fig 1). It must be noted that the Rhone River splits in two branches upstream of this station: the Grand Rhone and Petit Rhone. The station reports the 152 153 discharge for the Grand Rhone River only, which represents about 90 % of the total Rhone River discharge (Boudet et al., 2017). In our case we focus only on the river plume 154 at the Grand Rhone outlet. 155

156 Weather data and subsurface marine currents data are issued from the MesuRho station (Pairaud et al., 2016), operational since June 2009 and located at the Buoy Float 157 Immersed (BFI) maritime buoyage Roustan East (43 ° 19.2 N, 4 ° 52 E) on the Rhone 158 159 prodelta (20 m water depth). It is about 1 mile southeast of the mouth and was 160 configured to collect physico-chemical data in near real time and at high frequency 161 (about 30 min) in the fresh/marine waters transition zone. It is equipped with a weather 162 station at 10 m height and an Acoustic Current Doppler Profiler (ADCP). The 163 instrumentation is connected by a cable to a controller located above the sea surface and 164 powered by solar panels. The measurements are transmitted to the Coriolis data center via GPRS (about 1 transmission every 12h since 2015, 4h before). 165

Weather variables used are the average wind speed over 30 min and the gust wind speed. Gust wind speed is the maximal mean wind speed over 0.5 second observed during a period of 30 min.

The observations used were registered between 2009 and 2019 and result in a total of 128262 data. The subsurface currents (maximum depth of 1.5 m) from 2010 to 2019 were also used, when available and after quality control validation, leading to a total of 31826 observations.

In order to perform multivariate analysis and regression, wind and currents variables
(expressed in terms of velocities u and directions θ) are described by an Eastward and a
Northward component X and Y and calculated as follow :

176
$$\begin{cases} X = u. \cos(\theta) \\ Y = u. \sin(\theta) \end{cases}$$
(1)

The corresponding hourly discharges in Arles (64131 obs.) were shifted with a 24 h
delay, which corresponds to the transit time between Arles and the river mouth for a
mean liquid discharge.

181 2.2 Principal Component Analysis182

Principal Component Analysis (PCA) has been widely used in environmental sciences including hydrologic and hydrodynamics (e.g. Hannah et al., 2000; Pairaud et al., 2008). The common goal to all principal component methods is to describe a data set (X with *i* individuals or observations and w variables) using a small number (p<w) of uncorrelated variables, while retaining as much information (variance) as possible. The reduction is achieved by transforming the data into a new set of continuous variables named the principal components.

190 The reduction of dimensionality provides a framework to visualize data which is 191 especially important for large datasets (Husson et al., 2010). This facilitates the analyses 192 based on geometrical criteria such as separate observations into k distinct sub-groups 193 (clustering) or determination of extreme points (Renner, 1993; Napoleon & Pavalakodi, 194 2011)).

Using PCA as a pre-processing tool in order to cluster presents two additional advantages. The reduction of dimensionality speeds up the convergence of classification algorithms, which usually depends on the square of p and i (Ben-Dor et al., 2004), and it reduces the noise, the essential of the information being on the first components whereas the noise is on the lasting ones (Husson et al., 2010). PCA has been performed using the R package "FactoMineR" (Lê et al., 2008).

201 2.3 Fuzzy c-mean algorithm

202 Clustering is a usual method for data mining when it comes to identify groups and 203 classify individuals, but many algorithms exist and present different results and 204 convergence speeds (Jain et al., 1999). The first goal is to find an algorithm based on 205 geometrical criteria as simple as possible for a more realistic interpretability, and the second one is to find a fast convergence algorithm in order to treat the importantdataset.

208 The most usual method is the c-mean or k-mean (MacQueen, 1965 ;Yadav & Sharma, 2013) and its fuzzy alternative (Bezdek, 1981; Fu Lai & Tong, 1994). C-means are 209 210 iterative algorithms that classify individuals of a dataset into C groups. The algorithm 211 allows to randomly define C centroids in the same coordinate systems as the individuals. 212 Each individual x (total of K) is then assigned to the closest centroid center c_i. The barycenter of each subgroup is then calculated and becomes the new centroid. Again, 213 214 individuals are reassigned to the closest centroid. This iterative procedure minimizes the objective function (J) and the procedure ends when J reaches an inferior threshold in Eq 215 (2).216

218
$$J = \sum_{i=1}^{C} \sum_{X_k \in C_i} ||x_k - c_i||^2$$
(2)

This method is defined as "crisp", which means that each observation is set to belong to its closest centroid cluster. Consequences are that observations with different distances from the nearest cluster are classified into this cluster without degree of uncertainty and the ambiguity of the data is eliminated.

Cluster boundaries are usually not sharp in environmental sciences (Zadeh et al., 1965), especially when ambiguous data exist, and membership degrees are more realistic than crisp assignments (Klawonn & Höppner, 2003). A priori we do not expect a crisp classification and it is important to have feedback on the confidence of classification for each individual. As a result, the ambiguity of the data can be preserved and his probability can be used later for post treatments (Kim et al., 2011).

The fuzzy alternative introduces two new parameters. The first one is the membership
coefficient μ_{ik}, the coefficient of the *kth* observation to the *ith* cluster. This membership

represents how closely the *kth* data object (x_k) is located from the *ith* cluster center. It varies from 0 to 1 depending on the distance ($||x_k - c_i||^2$), and a higher membership coefficient indicates stronger association between the *kth* data object to the *ith* cluster.

234
$$\mu_{ik} = \left[\sum_{j=1}^{C} \left(\frac{\|x_k - c_i\|^2}{\|x_k - c_j\|^2}\right)^{\frac{2}{m-1}}\right]^{-1}$$
(3)

The second parameter *m* is the fuzziness coefficient. It is greater than 1 and usually dependent on the dataset structure because it represents the degree of overlap of the clusters (Klawonn & Höppner, 2003). If we set *m* to a smaller value, more (less) weight is given to the objects that are located closer to (farther from) a cluster center. As *m* is close to 1, μ_{ik} converges to 0 for the objects that are far from a cluster center, or 1 for those close to a cluster center, which implies less fuzziness (i.e. clearer cut).

The symbol || || denotes any vector norm that represents the distance between the data
object and the cluster center. Here we use the 2-norm (Euclidean norm) which is widely
used in the FCM.

244 The new c-mean function to minimize becomes:

245
$$J = \sum_{i=1}^{C} \sum_{k=1}^{K} (\mu_{ik})^m ||x_k - c_i||^2$$
(4)

The robustness brought by the fuzzy approach over the crisp classification is a significant improvement in term of efficiency and convergence. Because each individual (observations) has a probability to belong to each center, centers are adjusted faster and the algorithm converges faster (Fu Lai & Tong, 1994;Ferraro & Giordani, 2015).

Also, without any prior information on the cluster structure (sphericity of clusters,
possible overlap) the fuzzy c-mean provides better results than its crisp counterpart
(Selim & Kamel, 1992). As a result, hydrologic and climatologic combinations can be
identified by fuzzy-cmean (Kim et al., 2011; Zhang et al., 2011; Bárcena et al., 2015).

In this study the fuzzy-cmean algorithm is performed using the "e1071" package from R
software (Hornik et al., 2019).

256

257 2.4 Choice of the number of clusters C and the coefficient of fuzziness m

Fuzzy c-mean algorithm needs to be initialized with the number of clusters C and the coefficient of fuzziness *m*. The best combination of these parameters is not determined by the algorithm. One approach is to run different simulations with different {C, m} pairs and to check the efficiency of clustering with a quality criteria (Ramze Rezaee et al., 1998; Setnes & Babuška, 1999)

263 Many criteria and their efficiency are available in Wang & Zhang (2007) and Liu et al. 264 (2010). Some have fast calculation like partition coefficient (PC) or partition entropy 265 (PE), but they monotonously decrease with the number of clusters and the lack of direct 266 connection to the geometry of the dataset. Others are more complete but computationally expensive, such as the Dunn index (Dunn, 1974) or the fuzzy silhouette (Campello & 267 Hruschka, 2006), and they could not be calculated with this dataset. The Xie and Beni 268 index (Xie & Beni, 1991) could be calculated based on Eq (5). XB has a direct connection 269 270 to the geometrical property of dataset because it takes into account both compacity and separation of the clusters. It deals correctly with noisy datasets, size or density 271 272 variations (Liu et al., 2010).

273
$$XB = \frac{\sum_{i=1}^{C} \sum_{k=1}^{K} \mu_{ik}^{m} \|x_{k} - c_{i}\|^{2}}{K \min_{i,j} \|c_{j} - c_{i}\|^{2}}$$
(5)

274 Calculation of XB is also fast for our dataset: from 4 to 10 seconds depending on {C,m}
275 pair.

C could be any integer number between 2 and 358, the last one being theorically the
square root of the dataset length (Chaimontree et al., 2010). The fuzzifier *m* can be in

theory any real number between 1 and ∞. In our case, the interval of {C, m} simulations
has been restrained based on the following:

Depending on the river-sea system involved, a different number of plume patterns exist. In literature, we found that a river plume can present up to 8 patterns (Xu et al. 2019). As a result, we do not expect our number of cluster to exceed 8 and the number of clusters C was set between 2 and 8.

Previous studies report that values of m can range from 1 to 4. Most of them use $m \in [1.5, 2.5]$ and as result m is usually set to 2 by default (Hathaway and Bezdek 2001; Klawonn & Höppner, 2003). Overall m is lower for large datasets (Klawonn & Höppner, 2003), and the lower limit will be fix in our case to 1. Using the empirical threshold equation based on the length and dimensions of the dataset proposed by Schwämmle & Jensen (2010), we found that the superior threshold value of m for our dataset is around 2.5. By safety, this threshold value is increased by +0.25.

As a result, parameter m will be tested in the interval [1;2.75] and C in the interval [2;8].

292

293

294 3. Results and discussion

295 3.1 Principal Component Analysis

PCA successfully reduced the five original variables (Wind speed toward North and East, Gust wind speed toward North and East and Rhone discharge) into three components and gave a summed variance of 96.4% (Fig1 supplementary material). This is not surprising since the gust wind speed and mean wind speed are correlated due to same direction (Fig 2 supplementary material. The first axis contains 51% of variability with the information on wind direction. The second axis with 25 % of variability contains the information on wind speed, and the last one (20% variability) corresponds to the Rhone discharge. The "elbow criteria", the "Kaiser rule" and the interpretation of the components confirm without ambiguity these three components (Fig 1 supplementary material). The lasting 3.6% carried by the two remaining components concern really specific and scarce interactions like the anticorrelation between mean wind speed and gust wind speed.

As a result, 80 and 20% of the variability are due to the variations of winds and liquiddischarge respectively.

310 3.2 Clustering results and performances

Fuzzy-c-mean clustering was performed on the 128262 observations and the three main 311 312 dimensions resulting from PCA. A summary on classification performances based on XB index is shown Fig 2. All configurations performs reasonably well except the one with 3 313 clusters. An interesting result is that the 2 clusters configuration performed reasonably 314 well, which confirms that the plume dynamics can be described as a first approach by 315 316 considering only the wind direction that is South East against North West winds. This is in agreement with the 50% of variability held by the wind direction discussed hereunder. 317 However, the configuration selected is the one giving the better result for XB, with 6 318 319 clusters optimized at m=2.45 (XB=0.19).

320

321 3.3 Characterization of the scenarios

A cluster gathers observations having close values for one or more variables. These
properties on variables are specific to each cluster and are then interpreted hereunder as
a scenario.

In order to interpret the clustering and to characterize the resulting scenarios we present the distribution of winds and discharges in Fig 3 and 4, whereas Fig 5 shows the percentage of occurrence of these scenarios for each month. The discharge distribution in each cluster was significantly different from the global distribution of Rhone discharge in Arles based on the Kolmogorov-Smirnov test (see Fig 4).

In the description below, a flood event for the Rhone River refers to a discharge above a threshold set at 3900m³/s in Arles (Boudet et al., 2017). A storm criteria is usually the significant wave height, but this parameter showed too many breaks in the time series transmitted in near real time by the buoy over the 2009-2019 period. Also, we defined sea storm here by using as a threshold the quantile 98 of our offshore gust wind speed dataset (50.3% of total dataset) which is27.8 m/s (100 km/h) (Klawa & Ulbrich, 2003).

336

Cluster 1 gathers South-East winds (paragon 126°) with 9.2 m/s mean wind-speed and m/s mean gust. It contains 86% of all observed sea storm events (with the highest intensity) and 19% of the flood events. The distribution of the hourly water discharge does not characterize this cluster. Observations belonging to this cluster have less than 6% occurrence in July-September, rising up to 23% in October and November. This cluster can be interpreted as moderate to high waves scenario resulting from fresh breeze to violent storm South-East marine winds.

Observations in cluster 2 are winds with velocities around 4.5m/s, and 9.2 m/s gust fully coming from the South (171°). It contains 12% of all observed sea storm events. It gathers discharges values under 2500 m³/s, with a median at 960 m³/s. The observations mainly occur in August-September with 23% occurrence. This cluster can be interpreted as a Rhone River low flow scenario mainly associated with South-East marine breeze or sometimes a Sirocco wind coming from the South (Reiter, 1975). 350 Wind observations in cluster 3 show an important variability and are superimposed with clusters 4 and 5. Most representative winds present a mean speed of 8.5 m/s, and gust 351 352 speed of 13.1 m/s. The Rhone discharge distribution for cluster 3 is very different from 353 the reference distribution (highest Kolmogorov's D statistic). It gathers discharges 354 higher than 2000 m³/s and contains most of the flood events (79% of them). This is also the cluster showing the highest contrast in seasonality, with an occurrence up to 33% 355 356 from November to February, decreasing to 0-2% during the July-October period. Cluster 3 can be interpreted as the "high river flow" scenario with a combination of different 357 winds coming from the North West. 358

359

In cluster 4, observations are usually winds with 7.2m/s mean wind-speed and 9.1 m/s 360 mean gust coming from the West (272°). It contains 2% of all observed sea storm events. 361 Discharges are below 2500 m³/s with a median around 1070 m³/s. These observations 362 mainly occur in July-August-September with 33% of occurrence. A specific point is that 363 their occurrence increases during the afternoon with a peak around 1h AM (Fig 3 364 365 supplementary material). Interpretation of this cluster is a Rhone River low flow 366 scenario gathering moderate sea-breeze coming from the South-West (Cros et al., 2004), 367 with sometimes a strong onshore gale from West.

368

Cluster 5_corresponds to winds with 12.3 m/s average speed and 18.6 m/s gust coming from a restricted area in the North (325°). The corresponding water discharge distribution is on the lower part of the global distribution (median of 1140 m³/s) and discharges are always below 3000 m³/s. The monthly occurrence is stable (15%) with a peak in February at 25%. The strong average wind intensities and gust speeds (highest at 340 °) combined with the restricted wind direction parallel to the Rhone valley stand for the characteristics of the Mistral wind (Reiter, 1975). This last author also found that the highest peak of occurrence for Mistral is in February. As a result, cluster 5 can be interpreted as a Mistral wind scenario (dry and strong breeze to strong gale) associated with low to moderate discharges.

379 Cluster 6 usually gathers winds with 5.7 m/s average speed, and gusts of 12.5 m/s coming from the North East (11°). However, winds coming from 340-360° (North/North-380 381 West) are also observed. The related hourly water discharges distribution is in the lower part of the global one (median of 1230 m³/s) and few discharges higher than 3000 m³/s 382 383 are observed. Occurrence of cluster 6 observations is very stable all along the year, ranging between 14 and 18 %. This cluster presents the largest gap between the wind 384 speed average and the gust wind speed, and shows an increasing occurrence in the early 385 386 morning. The highest gusts reach 50 m/s and occur episodically in winter with an origin 387 from 10 to 60° (North-West). These are the strongest gusts observed among all scenarios. We interpret cluster 6 as a scenario gathering land breeze or valley flow during summer 388 and winds channeled by Pre Alps moutains (Cros et al., 2004; Duine et al., 2017)which 389 become stronger in winter ("orsure" according Reiter, 1975)). 390

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392 393

3.4 Consequences for surface currents

Six clear wind/discharge patterns have been identified, but did they correspond or induce different hydrodynamics responses of the surface currents in the vicinity of the Rhone River mouth? Consequences for subsurface currents observations issued from the ADCP on the MesuRho station are investigated through a least squares multiple regression. Observation membership to clusters C_i are the explanatory variables and currents in Eastward and Northward directions are the response variables. 400 Estimators X_i and Y_i are then used to calculate current orientation θ (rad) and speed u 401 (m/s) observed on each cluster with equation (1).

402 Confidence intervals are calculated with the robust White standard errors with "Imtest" 403 package (White, 1980; Hothorn et al., 2019) to avoid heteroscedasticity and 404 underestimation of confidence intervals. The main current direction for each cluster 405 obtained by least square regression on memberships is presented on figure 6 (right) 406 along with the global current rose (left).

407 Currents oriented at 280° correspond to scenario 1 and are in agreement with the more 408 general modelling and satellite observations during similar south easterlies wind 409 conditions showing the plume tackled to the Camargue coast (Marsaleix et al., 1998; 410 Gangloff et al., 2017). Scenario 2 presents small currents not related to the wind 411 direction. In this case, winds are probably too low and currents are driven by the general 412 circulation, which has a current speed similar to those of this scenario: 10 cm/s.

In scenario 3 the current direction correspond to those at the Rhone River mouth, meaning that during high water events (discharges superior to 2500 m³/s) the river influence becomes significant.

416 Scenario 4, 5 and 6 seem to follow the surface Ekman transport, with a deflection to the 417 left relative to the wind direction. Scenario 5 is the one presenting the largest interval of confidence despite having the straightest wind distribution. A closer look at the data 418 shows that, in this scenario, the currents deeper than 1.2 m present an important 419 heterogeneity in their direction. However, for wind average speeds superior to 15 m/s 420 421 and gust wind speeds over 25 m/s this heterogeneity does no longer exist and all currents are oriented in a 150° direction. For comparison, scenario 5 paragon is an average wind 422 423 speed of 12.3 m/s and gust wind speed of 18.6 m/s, values which areinferior to the two thresholds and may explain the currents discrepancies associated with this scenario. 424

425 To conclude, each scenario has its own current direction and intensity, statistically426 different and significant.

427

428 3.5 Application

429

The main objective of this work is to define the general trends of dispersal in the GoL that can be expected in the case of artificial radionuclides release within the river. Since releases may occur at any time in a year, we modeled the dispersion of a radioactive plume in the GoL for each of the previous hydrodynamic scenario, in order to get an overview of the potential impacts, whatever the hydrodynamic and climatological conditions.

The simulation code used at IRSN for the marine area is STERNE ("Simulation du Transport et du transfert d'Eléments Radioactifs dans l'environNEment marin", or "Simulation of radionuclide transport and transfer in marine environments"). It was designed to assess the radiological impact of accidental releases affecting the marine environment. Eulerian radionuclide dispersion is calculated using a tracer advection diffusion equation. More details on the code can be found in Duffa et al. (2016).

442 We use the 2010 hydrodynamic outputs provided by IFREMER with its MARS3D model 443 implemented on the North-western Mediterranean Sea (Nicolle et al., 2009). The simulations assumed a release of 1 TBq of ¹³⁷Cs dissolved activity in the river, over a 444 445 temporal window of 48 h. ¹³⁷Cs was chosen because this radionuclide is released at each 446 nuclear accident and is also found in authorized releases from nuclear powerplants. This radionuclide presents a high radiotoxicity (Garnier-Laplace et al., 2011) and is relatively 447 448 soluble in seawater with a Kd ranging from 450 to 2000 L/kg (Delaval et al., 2020). For comparison, the estimated average direct discharge of 137Cs to the ocean during the 449 450 Fukushima Daiichi nuclear power plants was around 5000 TBq (Buesseler et al., 2017).

The simulations were done for each hydro-meteorological scenario defined on the basis of the 2009-2019 dataset and the plume extension in the GoL was modelled for each scenario. Since the hydrodynamic inputs are only available for the year 2010, we selected in this input the most representative temporal window for each scenario simulation by integrating observations memberships over a sliding window of 48h. The temporal window presenting the highest summed membership values were selected for each cluster.

The results of the 6 simulations are very different in terms of plume shape and thus affected areas (Fig 7). Mean winds and discharges conditions over 48 h hours are indicated in the figure. It must be noted that these values are specific to the chosen temporal windows, and thus can be different from the parangons presented in the previous chapter.

In scenario 1 (strong marine wind with moderate discharge conditions), the plume is constrained to the coast and extends west in agreement with the currents at the buoy. This scenario has already been highlighted by Demarcq & Wald, (1984) and Many et al., (2018) or modelled by Estournel et al., (1997). A part of the activity remains blocked in the estuary due to winds in opposition with its flowing path and an increase in sea level at the mouth limiting the power of the jet.

The lowest expansion of the plume is observed with scenario 2 (weak wind with discharge slightly under the annual mean). The plume has the lowest surface spatial expansion among the 6 plumes and is nearly stagnant and remains with a high activity. This is in agreement with the currents observed at the buoy showing really low speeds. This scenario appears mostly during summer (Fig 4), and satellite images confirmed that the turbid plume present effectively its smallest area at this period (Gangloff et al. (2017). 476 Scenario 3 corresponds to a high Rhone River discharge and northwest winds conditions.
477 The plume presents a large area but the northwesterly wind is powerful enough to carry
478 the plume offshore. For different wind stress simulations, Marsaleix et al., (1998)
479 showed that winds around 30 km/h were sufficient to detach the plume from the coast.
480 According to this author this threshold is independent of Rhone River discharge.

In scenario 4 (strong westerly wind and low discharge conditions), the plume extends over a large area favored by the presence of a summer stratification at low discharge. A part of the plume at the latitude of the buoy can be deflected eastwards in the Gulf of Fos, in agreement with current data at the buoy. According to Fraysse et al., (2014) this plume shape is the first step toward an intrusion in the Bay of Marseille if this scenario is followed by south east winds conditions. To note, such intrusions occurred in summer (Fraysse et al, 2014) when the probability of occurrence of this scenario are the highest.

In scenario 5, with a strong northwest wind (Mistral) and low discharge conditions the plume stands out from the coast as shown by Demarcq & Wald, (1984) and Gangloff et al., (2017) and modelled by Estournel et al., (1997). This case is favorable to an export of the plume far away from the coast, even at low discharge conditions and moderate Mistral (but the wind speed are however above the 30 km/h threshold proposed by Marsaleix et al., (1998)).

Finally, the northeast wind and moderate discharge conditions of scenario 6 maintain the plume towards the coast, similarly to scenario 1. It is here again in agreement with the currents measured at the buoy. This is confirmed by Gangloff et al., (2017) who showed that for the most northern winds (higher than 340 °) the plume tends to be tacked to the coast .The part of the plume going East towards the gulf of Fos is quite unexpected. A closer look at the dataset shows that this temporal window of 48 h, despite being classified as scenario 6, presented 16 consecutives observations (8 hours period)corresponding to scenario 2. This explains why the plume extends toward the gulfof Fos in a similar fashion as in scenario 2.

503

All these simulations shown that the activity plume may be maintained along the western coast of the Rhone river outlet (Scenarios 1 and 6), its eastern side (Scenario 4) or can extend far away from the coast (Scenario 5). Plume of different extents can also remain nearly stable (Scenarios 2 and 3) until a change of hydrodynamic, conditions and thus scenario (most likely shifts from 2 to 4, 5, 6 and from 3 to 5, 6, 1).

509

510

Each cluster of hydrodynamic forcings has thus its own patterns for Rhone River plume 511 spreading in the GoL. Their hydrodynamic variables and resulting trends were 512 presented in the previous chapters, and these results now allow to better evaluate the 513 risk of propagation of ¹³⁷Cs activity. However, it is also interesting to define thresholds 514 values for these variables, in order to be able to select the most appropriate scenario to 515 516 apply in case of alert on accidental release of radionuclides (or any kind of chemical 517 contaminants). To summarize the differences obtained between the scenarios, a 518 simplified decision tree has been constructed (Fig 8). From top to bottom it allows to outline practical separation criteria (Fig 8). 519

The classification of these 6 scenarios is based on the wind (and gust) direction, wind speed and water discharge. These *in situ* conditions can thus be associated with a scenario in near real-time, as they are available at this time scale from the websites of Coriolis Cotier (wind) and Vigicrues (river flow). The tree reproduces the classification using 80% of the hydrodynamic raw data (without PCA treatment) as training, and 20% as a validation set. It allows a fast crisp classification into one of the 6 established scenario with 83% of accuracy on both trained and tested data. As an example, in case of wind direction of 270° and a river discharge of 2500 m3/s, the shape of the plume will
correspond to scenario 3. Currents directions at the buoy (Coriolis Cotier) can also be
used as an additional verification.

530 Conclusion

531

In this paper, a 10-year period was considered in order to identify the main combinations of hydrodynamic forcings (wind and Rhone River discharge) using a fuzzy c-mean clustering. These combinations, called scenario summarized mean shelf behavior providing a very important information to estimate and understand the Rhone plume patterns in case of accidental release. In addition, existence of observations memberships allowed to spot the best temporal windows to run simulations covering all possible patterns.

539 6 scenarios have been identified and simulations showed that the plume behavior was different for each of them. These plume patterns are more or less critical in terms of 540 radiologic risks regarding the areas affected and the dilution of the activity. 541 If 542 necessary, wind speed measured on one point are sufficient to extrapolate plume shape 543 for 48 hours on this zone, and the surface currents measured at the Roustan buoy will give a first idea of plume orientation. This study provided a first global picture of main 544 Rhone River plume patterns and consequences for radionuclides accidental releases, but 545 546 the methodology may be applied to other estuaries.

547

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555	Mesurho station is part of the COAST-HF network and associates IFREMER, IRSN,
556	CNRS, CETMEF, and CEREMA

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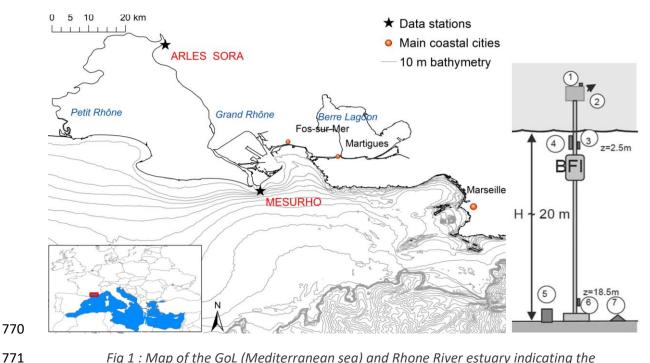


Fig 1 : Map of the GoL (Mediterranean sea) and Rhone River estuary indicating the locations of discharge and weather stations used in the fuzzy-clustering algorithm. Scheme of MesuRho buoy devices Weather station + PAR (1), solar panels and control and transmission automat ABIN (2), Multiparameters sonds (3 and 6) nitrates captor ISUS (4), benthic station (5), ADCP (7).

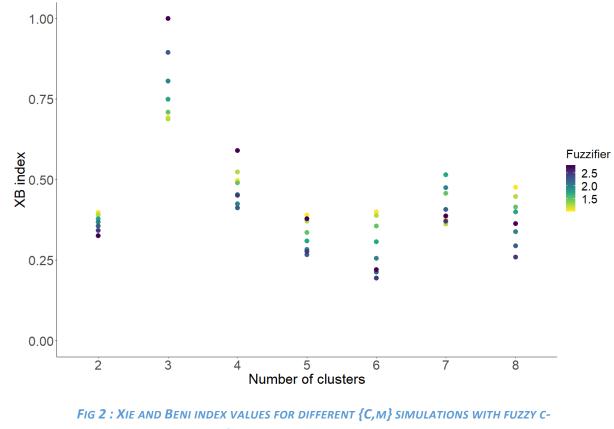
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MEAN ALGORITHM. A LOWER INDEX INDICATES A BETTER CLASSIFICATION.

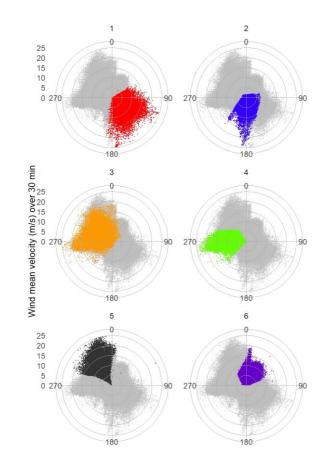
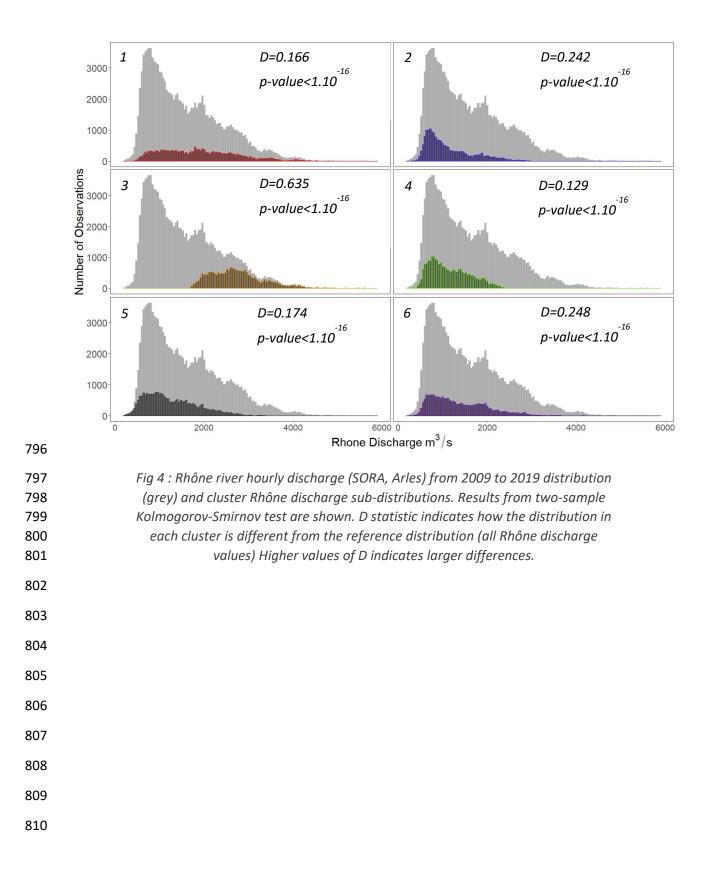
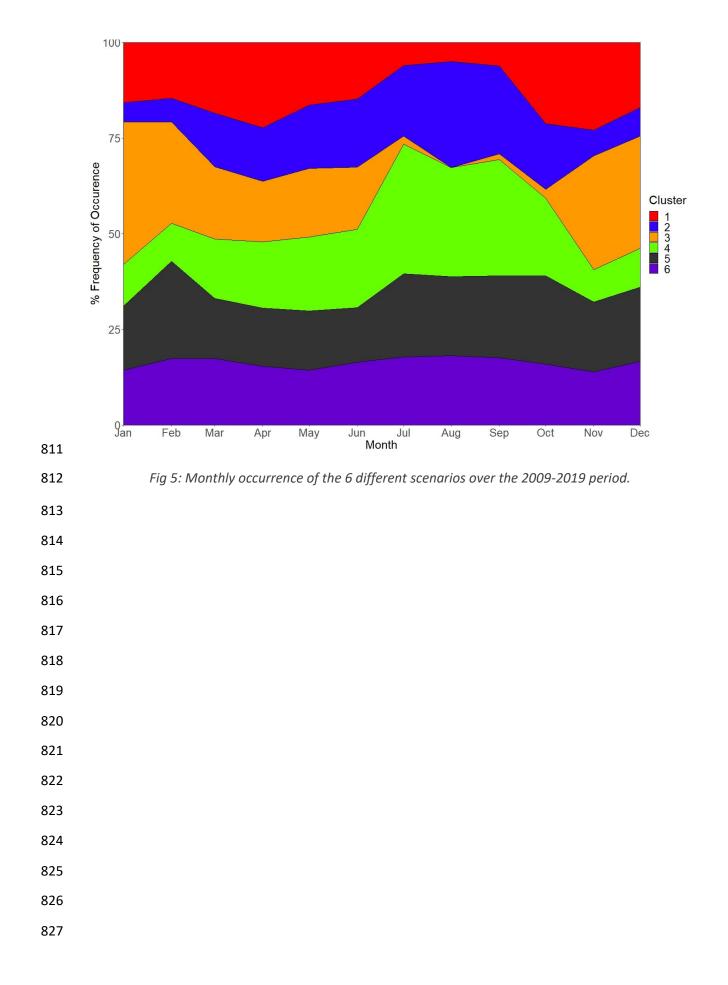
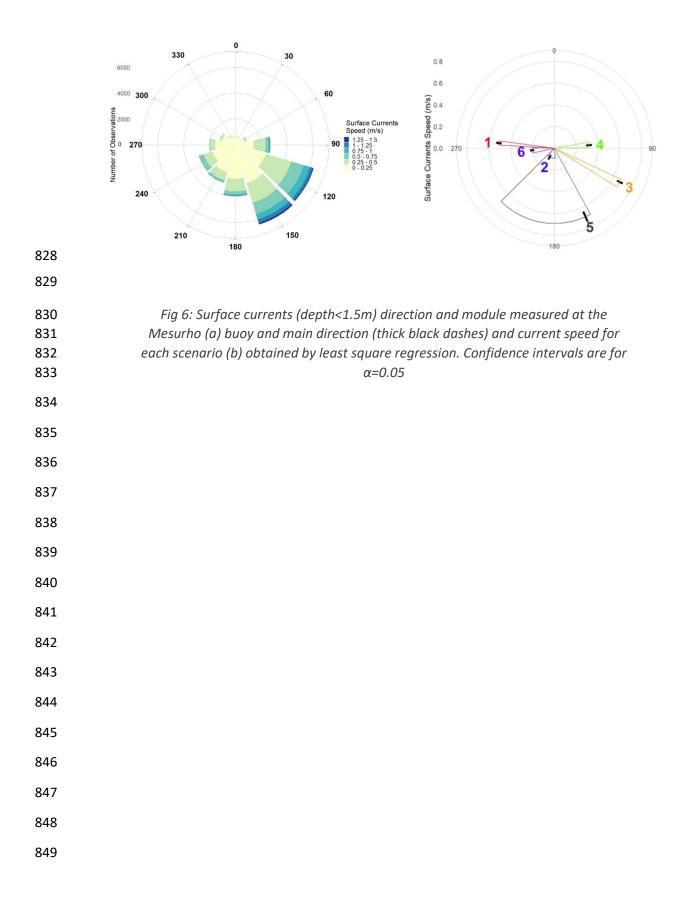
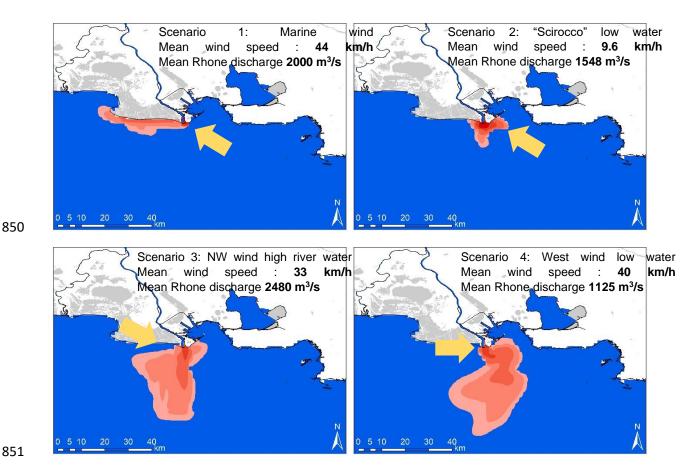


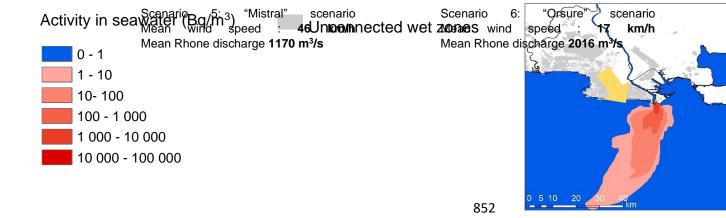
Fig 3: Grey dots: mean wind origin and speed (m/s) over 30 min from 2009 to 2019 measured at the Mesurho buoy, in front of the Rhone river. Color dots: cluster mean wind and speed sub-distributions.

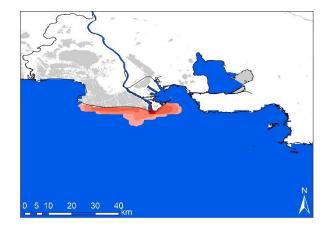


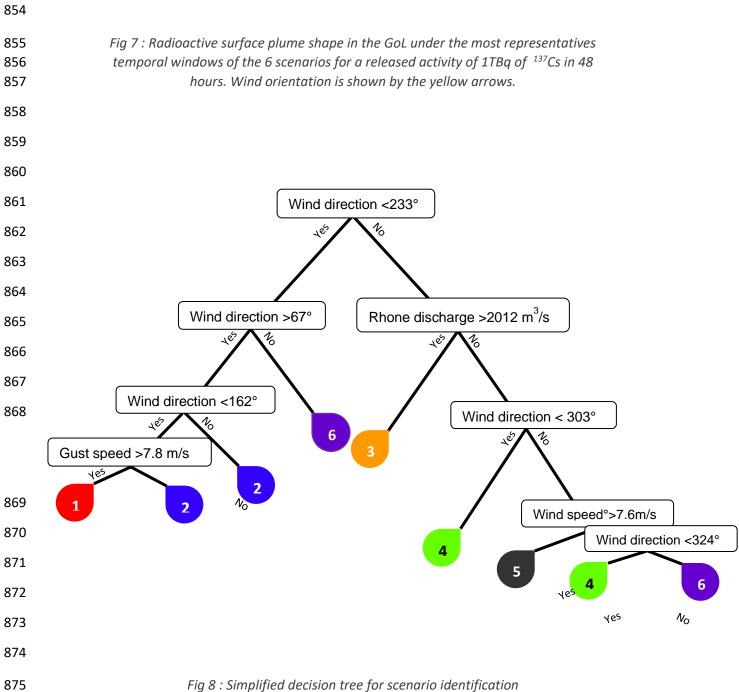












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