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Differential equations properties and ψ function

W. Oukil

Laboratory of Dynamical Systems, Faculty of Mathematics. University of Science and Technology Houari Boumediene, BP 32 EL ALIA 16111 Bab Ezzouar, Algiers, Algeria.

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Abstract

Using the differential equations properties, we study the function ψ which is a function defined by an integral. The particular case of this function coincide with the function $s\mapsto \zeta(s)/s$, where ζ is the Riemann Zeta function. In the end of the paper, we find that $\frac{\zeta(s)}{s}\neq -\frac{\zeta(1-s)}{1-s}$ for every $\Re(s)\in(0,\frac{1}{2})$ and $\Im(s)\in\mathbb{R}^*$. Thanks to the Riemann functional equation, we deduce that any *non-trivial zero* of ζ is of real part equal to $\frac{1}{2}$.

Keywords: Linear differential equation, Zeta function, Riemann hypothesis.

1 Main result

Let be $\eta: \mathbb{R}_+ \to \mathbb{R}$ be a bounded function. We study the function $\psi[\eta]: (0,1) \times \mathbb{R}^* \to \mathbb{C}$ defined as

$$\forall x \in (0,1), \ \forall \tau \in \mathbb{R}^*: \quad \psi[\eta](x,\tau) := \int_0^{+\infty} \frac{\eta(t)}{t^{1+x+i\tau}} dt, \tag{1}$$

We focus about the function $\eta: \mathbb{R}_+ \to \mathbb{R}$ satisfying the following hypotheses

 $H_1: \exists \omega > 0: 0 \le \eta(t) < \omega \text{ for all } t \ge 0,$

 H_2 : there exists an at most countable set $A \subset \mathbb{R}_+$ such that η is C^1 on \mathbb{R}_+/A .

We prove in this paper the following Main result

W. Oukil

Main Result. Consider the function ψ defined by Equation (1). Then, for every function $\eta: \mathbb{R}_+ \to \mathbb{R}$ that satisfies the hypotheses H_1 and H_2 we have

$$\forall \tau \in \mathbb{R}^*, \ \forall x \in (0, \frac{1}{2}): \quad \|\psi[\eta](x, \tau) - \psi[\eta](1 - x, \tau)\| \neq 0.$$

2 Main proposition

In this Section we study the function ψ , defined in Equation (1), by transforming the problem to some non-homogeneous linear differential equation.

Proposition 1. Let $\eta : \mathbb{R}_+ \to \mathbb{R}$ be a function that satisfies H_1 and H_2 . For every $r \in (0, \frac{1}{2})$ and $\tau > 0$ define the $h_{\tau,r} : \mathbb{R}_+ \to \mathbb{R}_+$ as

$$h_{\tau,r}(t) := \tau \exp(-\frac{1}{2}t)[\eta(\exp(t)) + 1]\sinh(rt), \quad \forall t \ge 0.$$

Then for every $r \in (0, \frac{1}{2})$ and every $\tau > 0$, the unique continuous solution $t \mapsto \delta_{\tau,r}(t)$ of the following linear differential equation

$$\frac{d}{dt}\delta_{\tau,r}(t) = \begin{pmatrix} 0 & 1 \\ -\tau^2 & 0 \end{pmatrix} \delta_{\tau,r}(t) + \begin{pmatrix} 0 \\ h_{\tau,r}(t) \end{pmatrix}, \ t \in \mathbb{R}/\ln(A), \ \delta_{\tau,r}(0) = \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \tag{2}$$

satisfies

$$\lim_{t \to +\infty} \|\delta_{\tau,r}(t)\| \neq 0.$$

Lemma 2. For every $t \ge 0$ we have

$$\exp\left(\begin{pmatrix}0&1\\-\tau^2&0\end{pmatrix}t\right) = \begin{pmatrix}\cos(\tau t)&\frac{1}{\tau}\sin(\tau t)\\-\tau\sin(\tau t)&\cos(\tau t)\end{pmatrix}.$$

Proof. We have

$$\begin{pmatrix} 0 & 1 \\ -\tau^2 & 0 \end{pmatrix}^2 = -\tau^2 \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}.$$

Then

$$\exp\left(\begin{pmatrix} 0 & 1 \\ -\tau^2 & 0 \end{pmatrix} t\right) = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \sum_{k=0}^{+\infty} (-1)^k \frac{(\tau t)^{2k}}{(2k)!} + \begin{pmatrix} 0 & 1 \\ -\tau^2 & 0 \end{pmatrix} \sum_{k=0}^{+\infty} (-1)^k (\tau)^{2k} \frac{t^{2k+1}}{(2k+1)!}.$$

Implies

$$\exp\left(\begin{pmatrix} 0 & 1 \\ -\tau^2 & 0 \end{pmatrix} t\right) = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \cos(\tau t) + \begin{pmatrix} 0 & 1 \\ -\tau^2 & 0 \end{pmatrix} \frac{1}{\tau} \sin(\tau t)$$
$$= \begin{pmatrix} \cos(\tau t) & \frac{1}{\tau} \sin(\tau t) \\ -\tau \sin(\tau t) & \cos(\tau t) \end{pmatrix}.$$

Proof of the Proposition 1. By contradiction, suppose that there exist $r \in (0, \frac{1}{2})$ and $\tau > 0$ such that

$$\lim_{t \to +\infty} \|\delta_{\tau,r}(t)\| = 0. \tag{3}$$

By the hypotheses H_1 , integrate Equation (2) using the fact $\delta_{\tau,r}$ is the continuous solution and the fact $\delta_{\tau,r}(0) = 0$, we get

$$\delta_{\tau,r}(t) = \begin{pmatrix} 0 & 1 \\ -\tau^2 & 0 \end{pmatrix} \int_0^t \delta_{\tau,r}(u) du + \begin{pmatrix} 0 \\ \int_0^t h_{\tau,r}(u) du \end{pmatrix}, \quad \forall t \ge 0.$$
 (4)

Since

$$\begin{pmatrix} 0 & 1 \\ -\tau^2 & 0 \end{pmatrix}^2 = -\tau^2 \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix},$$

then

$$\int_0^t \delta_{\tau,r}(u)du = \frac{-1}{\tau^2} \begin{pmatrix} 0 & 1\\ -\tau^2 & 0 \end{pmatrix} \left[\delta_{\tau,r}(t) - \begin{pmatrix} 0\\ \int_0^t h_{\tau,r}(u)du \end{pmatrix} \right], \quad \forall t \ge 0. \quad (5)$$

By hypothesis H_1 the function η is bounded and positive. Since $r \in (0, \frac{1}{2})$ then there exists $\alpha_r > 0$ such that

$$\lim_{t \to +\infty} \int_0^t h_{\tau,r}(u) du = \tau \alpha_r.$$

By Equation (5) and the hypothesis (3), we get

$$\lim_{t \to +\infty} \int_0^t \delta_{\tau,r}(u) du = \frac{1}{\tau^2} \begin{pmatrix} 0 & 1 \\ -\tau^2 & 0 \end{pmatrix} \begin{pmatrix} 0 \\ \tau \alpha_r \end{pmatrix} = \begin{pmatrix} \frac{1}{\tau} \alpha_r \\ 0 \end{pmatrix}$$
 (6)

Equation (4), can be written as

$$\delta_{\tau,r}(t) = \begin{pmatrix} 0 & 1 \\ -\tau^2 & 0 \end{pmatrix} \begin{bmatrix} \int_0^t \delta_{\tau,r}(u) du - \begin{pmatrix} \frac{1}{\tau} \alpha_r \\ 0 \end{pmatrix} \end{bmatrix} + \begin{pmatrix} 0 \\ -\int_t^{+\infty} h_{\tau,r}(u) du \end{pmatrix}, \quad \forall t \ge 0.$$

4 W. Oukil

Integrate,

$$\int_{0}^{t} \delta_{\tau,r}(u) du = \begin{pmatrix} 1 - \cos(\tau t) & \frac{1}{\tau} - \sin(\tau t) \\ \tau \sin(\tau t) & 1 - \cos(\tau t) \end{pmatrix} \begin{pmatrix} \frac{1}{\tau} \alpha_{r} \\ 0 \end{pmatrix} + \begin{pmatrix} \cos(\tau t) & \frac{1}{\tau} \sin(\tau t) \\ -\tau \sin(\tau t) & \cos(\tau t) \end{pmatrix} \begin{pmatrix} \int_{0}^{t} \frac{1}{\tau} \sin(\tau u) \int_{u}^{+\infty} h_{\tau,r}(v) dv du \\ -\int_{0}^{t} \cos(\tau u) \int_{u}^{+\infty} h_{\tau,r}(v) dv du \end{pmatrix}. \tag{8}$$

By definition of the function $h_{\tau,r}$ and by the hypothesis H_1 , the function $u \mapsto \int_u^{+\infty} h_{\tau,r}(v) dv$ is positive and increasing. Using the symmetry of the function $\sin(\tau u)$ on $[0, \frac{2\pi}{\tau}]$ about the point $\frac{\pi}{2\tau}$ we get,

$$\int_0^t \sin(\tau u) \int_u^{+\infty} h_{\tau,r}(v) dv du > 0, \quad \forall t > 0.$$

In particular,

$$\int_0^t \sin(\tau u) \int_u^{+\infty} h_{\tau,r}(v) dv du > \int_0^t \sin(\tau u) \int_u^{+\infty} h_{\tau,r}(v) dv du, \ \forall t > \frac{2\pi}{\tau}.$$
(9)

Then the function

$$t \mapsto = \frac{\int_0^t \cos(\tau u) \int_u^{+\infty} h_{\tau,r}(v) dv du}{\int_0^t \sin(\tau u) \int_u^{+\infty} h_{\tau,r}(v) dv du}$$

is continuous and uniformly bounded on $(\frac{2\pi}{\tau}, +\infty)$. In addition, the limit

$$\lim_{t \to +\infty} \frac{\int_0^t \cos(\tau u) \int_u^{+\infty} h_{\tau,r}(v) dv du}{\int_0^t \sin(\tau u) \int_u^{+\infty} h_{\tau,r}(v) dv du}$$

exists. Then there exists sequence $t_n \to +\infty$ such that

$$\frac{\cos(\tau t_n)}{\sin(\tau t_n)} := \frac{\int_0^{t_n} \cos(\tau u) \int_u^{+\infty} h_{\tau,r}(v) dv du}{\int_0^{t_n} \sin(\tau u) \int_u^{+\infty} h_{\tau,r}(v) dv du},$$

and such that

$$\lim_{n \to +\infty} \left[t_n - \left(\frac{n\pi}{\tau} + \frac{\pi}{2\tau} \right) \right] \neq 0, \tag{10}$$

Implies that, there exists a sub-sequence $(t_{n_k})_k \subset (t_n)_n$ such that $\lim_{k\to+\infty}\cos(\tau t_{n_k}):=\alpha\neq 0$. By Equation (7), we get

$$\lim_{k \to +\infty} \int_0^{t_{n_k}} \delta_{2,\tau,r}(u) du = \lim_{k \to +\infty} \frac{1}{\tau} \alpha_r \Big(1 - \cos(\tau t_{n_k}) \Big) \neq \frac{1}{\tau} \alpha_r,$$

where $(\delta_{1,\tau,r}, \delta_{2,\tau,r}) := \delta_{\tau,r}$. Contradiction with Equation (6).

3 Proof of the Main results

Proof of the Main result. Integrate Equation (2) using the fact $\delta_{\tau,r}$ is the continuous solution and the fact $\delta_{\tau,r}(0) = 0$, we get

$$\delta_{\tau,r}(t) = \int_0^t \exp\left(\begin{pmatrix} 0 & 1 \\ -\tau^2 & 0 \end{pmatrix} (t-u)\right) \begin{pmatrix} 0 \\ h_{\tau,r}(u) \end{pmatrix} du.$$

By Lemma 2, we obtain,

$$\delta_{\tau,r}(t) = \begin{pmatrix} \cos(\tau t) & \frac{1}{\tau}\sin(\tau t) \\ -\tau\sin(\tau t) & \cos(\tau t) \end{pmatrix} \begin{pmatrix} -\int_0^t \frac{1}{\tau}\sin(\tau u)h_{\tau,r}(t)du \\ \int_0^t \cos(\tau u)h_{\tau,r}(u)du. \end{pmatrix}.$$

Use the change of variable, $t \to \exp(u)$, in Equation (1), we obtain

$$\begin{pmatrix} \frac{1}{\tau} \Im[\psi(\frac{1}{2} - r, \tau) - \psi(\frac{1}{2} + r, \tau)] \\ \Re[\psi(\frac{1}{2} - r, \tau) - \psi(\frac{1}{2} + r, \tau)] \end{pmatrix} = \lim_{t \to +\infty} \begin{pmatrix} \cos(\tau t) & \frac{1}{\tau} \sin(\tau t) \\ -\tau \sin(\tau t) & \cos(\tau t) \end{pmatrix}^{-1} \delta_{\tau, r}(t).$$

By the Main Proposition 1 we have $\|\psi(\frac{1}{2}-r,\tau)-\psi(\frac{1}{2}+r,\tau)\|\neq 0$ for every $r\in(0,\frac{1}{2})$ and $\tau\in\mathbb{R}^*$.

4 Discussion about the Riemann hypothesis

Consider the representation of the Riemann Zeta function ζ defined by the Abel summation formula [[1], page 14 Equation 2.1.5] as

$$\zeta(s) := -s \int_0^{+\infty} \frac{\{t\}}{t^{1+s}} dt, \quad \Re(s) \in (0,1), \quad \Im(s) \in \mathbb{R}^*, \tag{11}$$

and where $\{t\}$ is the fractional part of the real t. Define the non-trivial zeros of the function ζ in the following sense

Definition 3. Let be $s \in \mathbb{C}$. We say that s is a non-trivial zero of the function ζ if

$$\zeta(s) = 0$$
 and $\Re(s) \in (0,1)$, $\Im(s) \in \mathbb{R}^*$.

Denote $\eta_*(t) := \{t\}$. For every $\tau \in \mathbb{R}^*$ and every $x \in (0,1)$ we have

$$\psi[\eta_*](x,\tau) = \frac{\zeta(s)}{s}$$
 and $\psi[\eta_*](1-x,\tau) = -\frac{\zeta(1-s)}{1-s}$, $s := x + i\tau$.

Since

$$0 \le \eta_*(t) \le 1, \quad \forall t \ge 0,$$

6 W. Oukil

Then η_* satisfies the hypotheses H_1 . The function η_* is C^1 on \mathbb{R}_+/\mathbb{N} . Then η_* satisfies the hypotheses H_2 . By the Riemann functional equation [[1], page 13 Theorem 2.1], the non-trivial zeros of the function ζ are symmetric about the line $\Re(z) = \frac{1}{2}$. By the Main result, the non-trivial zeros $s \in \mathbb{C}$ symmetric about the line $\Re(z) = \frac{1}{2}$ satisfies $\Re(s) = \frac{1}{2}$.

References

[1] E.C. Titchmarsh, The Theory of the Riemann Zeta-Function (revised by D.R. Heath-Brown), Clarendon Press, Oxford. (1986).