## Predicting mechanical constitutive laws of elastomers with mesoscale simulations

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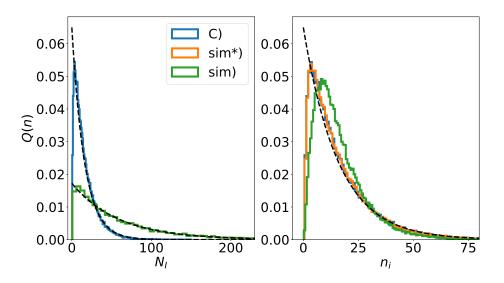


Figure 1: The effect of particle crossing on the shape of the chain/segment length probability density function Q(n). Dashed lines represent target distributions, C) not entangled network, sim<sup>\*</sup>) entangled network before mechanical relaxation, sim) entangled network after mechanical equilibration. Low *n* values are less likely to occur, because having over-extended chains is forbidden.

$\overline{a \times b \times c (\mathrm{nm})}$ $60 \times 60 \times 60$	Number of crosslinks 7776	Number of entanglements 20304
00 × 00 × 00	1110	20001
Connectivity	Number of segments	$\frac{a(t)-a(t_0)}{t-t_0} (\mathrm{cm}\mathrm{s}^{-1})$
4	15552	0.04

Table 1: Detailed simulation parameters

## Mooney-Rivlin representation of the stress

It is possible to find a simple expression for  $(\lambda - 1/\lambda^2)$ , resulting in the reduced stress found in the Mooney-Rivlin equation.<sup>1,2</sup> This derivation is well known, but since we make explicit use of it in Fig.3, it is included here for completeness.

Suppose we have a strain energy function W that is expressed as a function of the three strain tensor invariants  $I_1, I_2, I_3$ . These invariants are defined as:

$$I_{1} = \lambda_{1}^{2} + \lambda_{2}^{2} + \lambda_{3}^{2} ,$$

$$I_{2} = \lambda_{1}^{2} \lambda_{2}^{2} + \lambda_{2}^{2} \lambda_{3}^{2} + \lambda_{1}^{2} \lambda_{3}^{2} ,$$

$$I_{3} = \lambda_{1}^{2} \lambda_{2}^{2} \lambda_{3}^{2} ,$$
(1)

with  $\lambda_i$  the deformation ratio of the *i* axis. These three expressions are independent of the choice of reference frame. The case of an incompressible material corresponds to  $I_3 = 1$ .

If we choose to stretch our material along the i axis, we can express the stress as the partial derivative of energy with respect to the deformation along this axis:

$$\sigma_{ii} = \frac{\partial W}{\partial \lambda_i} \lambda_i \tag{2}$$

To calculate the nominal stress  $\sigma_0$  in the case of a uni-axial traction along axis 1, we have to evaluate  $(\sigma_{11} - \sigma_{22})/\lambda$ . This results in:

$$\sigma_{11} - \sigma_{22} = \frac{\partial W}{\partial \lambda_1} \lambda_1 - \frac{\partial W}{\partial \lambda_2} \lambda_2 \tag{3}$$

In order to change variables from  $\lambda_i$  to  $I_i$ , we need

$$\frac{\partial I_1}{\partial \lambda_1} = 2 \lambda_1 \quad ,$$

$$\frac{\partial I_2}{\partial \lambda_1} = 2 \lambda_1 \lambda_2^2 + 2 \lambda_1 \lambda_3^2$$
(4)

and by using the chain rule, we find

$$\sigma_{11} - \sigma_{22} = 2\left(\lambda_1^2 - \lambda_2^2\right)\frac{\partial W}{\partial I_1} + 2\left(\lambda_1^2 - \lambda_2^2\right)\lambda_3^2\frac{\partial W}{\partial I_2}$$
(5)

$$\sigma_{11} - \sigma_{22} = 2\left(\lambda_1^2 - \lambda_2^2\right) \left(\frac{\partial W}{\partial I_1} + \lambda_3^2 \frac{\partial W}{\partial I_2}\right) \tag{6}$$

In the case of uniaxial stress along axis 1 and by using the incompressibility approximation, we can write:

$$\lambda_{1} = \lambda \quad ,$$

$$\lambda_{1} \lambda_{2} \lambda_{3} = 1 \quad ,$$

$$\lambda_{2} = \lambda_{3} = \frac{1}{\sqrt{\lambda}}$$
(7)

and we find for the nominal stress:

$$\sigma_{0} = \frac{\sigma_{11} - \sigma_{22}}{\lambda} = 2\left(\lambda - \frac{1}{\lambda^{2}}\right)\left[\frac{\partial W}{\partial I_{1}} + \frac{1}{\lambda}\frac{\partial W}{\partial I_{2}}\right] ,$$

$$\frac{\sigma_{0}}{\lambda - 1/\lambda^{2}} = 2\left[\frac{\partial W}{\partial I_{1}} + \frac{1}{\lambda}\frac{\partial W}{\partial I_{2}}\right]$$
(8)

which is the expression of the reduced stress as defined by Mooney and Rivlin. If we assume a simple expression for W, such as  $\frac{\partial W}{\partial I_1}$  and  $\frac{\partial W}{\partial I_2}$  being constants, we obtain

$$\frac{\sigma_0}{\lambda - 1/\lambda^2} = 2C_1 + 2C_2\frac{1}{\lambda} \tag{9}$$

which is the reason for plotting  $\frac{\sigma_0}{\lambda - 1/\lambda^2}$  as a function of  $\frac{1}{\lambda}$ .

## References

- Mooney, M. A theory of large elastic deformation. Journal of applied physics 1940, 11, 582–592.
- (2) Rivlin, R. Large elastic deformations of isotropic materials IV. Further developments of the general theory. *Philosophical Transactions of the Royal Society of London. Series A*, *Mathematical and Physical Sciences* **1948**, *241*, 379–397.