



HAL
open science

Approximation of a degenerate semilinear PDEs with a nonlinear Neumann boundary condition

Khaled Bahlali, Brahim Boufoussi, Soufiane Mouchtabih

► **To cite this version:**

Khaled Bahlali, Brahim Boufoussi, Soufiane Mouchtabih. Approximation of a degenerate semilinear PDEs with a nonlinear Neumann boundary condition. 2022. hal-03523538

HAL Id: hal-03523538

<https://hal.science/hal-03523538v1>

Preprint submitted on 12 Jan 2022

HAL is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers.

L'archive ouverte pluridisciplinaire **HAL**, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d'enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.

Approximation of a degenerate semilinear PDEs with a nonlinear Neumann boundary condition

Khaled Bahlali* Brahim Boufoussi † Soufiane Mouchtabih *†

Abstract: We consider a system of semilinear partial differential equations (PDEs) with a nonlinearity depending on both the solution and its gradient. The Neumann boundary condition depends on the solution in a nonlinear manner. The uniform ellipticity is not required to the diffusion coefficient. We show that this problem admits a viscosity solution which can be approximated by a penalization. The Lipschitz condition is required to the coefficients of the diffusion part. The nonlinear part as well as the Neumann condition are Lipschitz. Moreover, the nonlinear part is assumed monotone in the solution variable. Note that the existence of a viscosity solution to this problem has been established in [13] then completed in [15]. In the present paper, We construct a sequence of penalized system of decoupled forward backward stochastic differential equations (FBSDEs) then we directly show its strong convergence. This allows us to deal with the case where the nonlinearity depends on both the solution and its gradient. Our work extends, in particular, the result of [4] and, in some sense, those of [1, 3]. In contrast to works [1, 3, 4], we do not pass by the weak compactness of the laws of the stochastic system associated to our problem.

Keywords: Reflecting stochastic differential equation; Penalization method; Backward stochastic differential equations; Viscosity solution.

AMS Subject Classification 2010: 60H99; 60H30; 35K61.

1 Introduction

Let D be a regular convex, open and bounded subset of \mathbb{R}^d . We introduce the function $\rho \in C_b^1(\mathbb{R}^d)$ such that $\rho = 0$ in \bar{D} , $\rho > 0$ in $\mathbb{R}^d \setminus \bar{D}$ and $\rho(x) = (d(x, \bar{D}))^2$ in a neighborhood of \bar{D} . On the other hand, since the domain D is smooth (say C^3), it is possible to consider

*Université de Toulon, IMATH, EA 2134, 83957 La Garde cedex, France.

†Department of Mathematics, Faculty of Sciences Semlalia, Cadi Ayyad University, 2390 Marrakesh, Morocco

an extension $l \in \mathcal{C}_b^2(\mathbb{R}^d)$ of the function $d(\cdot, \partial D)$ such that D and ∂D are characterized by

$$D = \{x \in \mathbb{R}^d : l(x) > 0\} \quad \text{and} \quad \partial D = \{x \in \mathbb{R}^d : l(x) = 0\},$$

and for every $x \in \partial D$, $\nabla l(x)$ coincides with the unit normal pointing toward the interior of D (see for example [9, Remark 3.1]). In particular we may and do choose ρ and l such that

$$\langle \nabla l(x), \delta(x) \rangle \leq 0, \quad \text{for all } x \in \mathbb{R}^d, \quad (1)$$

where $\delta(x) := \nabla \rho(x)$ and is called the penalization term. We have

$$\frac{1}{2}\delta(x) = x - \pi_{\bar{D}}(x), \quad \forall x \in \mathbb{R}^d$$

where $\pi_{\bar{D}}$ is the projection operator on \bar{D} . Consider the second-order differential operator

$$\mathcal{L} = \frac{1}{2} \sum_{i,j} (\sigma \sigma^*(\cdot))_{ij} \frac{\partial^2}{\partial x_i \partial x_j} + \sum_i b_i(\cdot) \frac{\partial}{\partial x_i}$$

where $b : \mathbb{R}^d \rightarrow \mathbb{R}^d$ and $\sigma : \mathbb{R}^d \rightarrow \mathbb{R}^{d \times d'}$ are given functions satisfying suitable assumptions.

Our first aim is to establish the existence of a viscosity solution via penalization to the following system of partial differential equations with nonlinear Neumann boundary condition, defined for $1 \leq i \leq m$, $0 \leq t \leq T$, $x \in D$.

$$\begin{cases} \frac{\partial u_i}{\partial t}(t, x) + \mathcal{L}u_i(t, x) + f_i(t, x, u(t, x), (\nabla u \sigma)(t, x)) = 0 \\ u(T, x) = g(x), \quad x \in D \\ \frac{\partial u}{\partial n}(t, x) + h(t, x, u(t, x)) = 0, \quad (t, x) \in [0, T] \times \partial D. \end{cases} \quad (2)$$

To this end, we consider a sequence (u^n) of viscosity solutions of the following semi-linear partial differential equations ($1 \leq i \leq m$, $0 \leq t \leq T$, $x \in \mathbb{R}^d$, $n \in \mathbb{N}$).

$$\left\{ \begin{array}{l} \frac{\partial u_i^n}{\partial t}(t, x) + \mathcal{L}u_i^n(t, x) + f_i(t, x, u^n(t, x), (\nabla u^n \sigma)(t, x)) \\ \quad - n \langle \delta(x), \nabla u_i^n(t, x) + \nabla l(x) \rangle > h_i(t, x, u^n(t, x)) = 0; \\ u^n(T, x) = g(x). \end{array} \right\} \quad (3)$$

then we show that for each n , equation (3) has a viscosity solution u_n which converges to a function u , and u is a viscosity solution to (2). Our method is probabilistic.

The authors of [1, 3, 4] considered the case where f does not depends on ∇u . Using the connection between backward stochastic differential equations (BSDEs) and partial differential equations (PDEs), the convergence of u^n to u has been established in [4] for

bounded and uniformly Lipschitz coefficients b and σ . The authors of [1] extended the result of [4] to the case where b and σ are bounded continuous. The case where b , σ and f are bounded measurable is considered in [3] in the framework of L^p -viscosity solution. The techniques developed in the previous works rely on tightness properties of the associated sequence of BSDEs in the Jakubowski S -topology. The main drawback of this method is that it does not allow to deal with the nonlinearity f depending on ∇u . Here, our method is direct and does not pass by weak compactness properties. Usually, when the nonlinearity f depends in the gradient of the solution, PDEs techniques are used to control the gradient ∇u in order to get the convergence of the associated BSDE. And generally, a uniform ellipticity of the diffusion is required to get a good control of the gradient ∇u , see for instance [2, 5, 6] where this method is used in homogenization of nonlinear PDEs. Our approach is completely different: We use a purely probabilistic method, which allows us to deal with (possibly) degenerate PDEs. The convergence of the penalized BSDE is provided only by the convergence of the penalized forward SDE. Our proof essentially use [14, Proposition 6.80, Annex C]. The latter has been already used by the authors of [15] in order to prove the continuity of the solution of a system of SDE-BSDE in its initial data (t, x) . By bringing essential modifications in the idea developed in [15], we prove the convergence of our sequence of penalized BSDEs.

The paper is organized as follows: Section 2 contains some facts about reflected stochastic differential equations (SDEs) and generalized BSDEs. This mainly consists in approximation, existence, uniqueness results and a priori estimates of the solutions. Section 3 is devoted to the penalization of the nonlinear Neumann PDE.

2 Preliminaries and formulation of the problem

Throughout the paper, for a fixed $T > 0$, $(W_t; t \in [0, T])$ is a d -dimensional Brownian motion defined on a complete probability space $(\Omega, \mathcal{F}, \mathbb{P})$ and for every $t \in [0, T]$, \mathcal{F}_s^t is the σ -algebra $\sigma(W_r; t \leq r \leq s) \vee \mathcal{N}$ if $s \geq t$ and $\mathcal{F}_s^t = \mathcal{N}$ if $s \leq t$, where \mathcal{N} is the \mathbb{P} -zero sets of \mathcal{F} . For $q \geq 0$, we denote by $\mathcal{S}_d^q[0, T]$ the space of continuous progressively measurable stochastic processes $X : \Omega \times [0, T] \rightarrow \mathbb{R}^d$, such that for $q > 0$ we have

$$\mathbb{E} \sup_{t \in [0, T]} |X_t|^q < +\infty.$$

For $q \geq 0$, we denote by $\mathcal{M}_d^q(0, T)$ the space of progressively measurable stochastic processes $X : \Omega \times [0, T] \rightarrow \mathbb{R}^d$ such that:

$$\mathbb{E} \left[\left(\int_0^T |X_t|^2 dt \right)^{\frac{q}{2}} \right] < +\infty \quad \text{if } q > 0; \quad \text{and} \quad \int_0^T |X_t|^2 dt < +\infty \quad \mathbb{P} - a.s. \quad \text{if } q = 0.$$

2.1 Penalization for reflected stochastic differential equation

Let $(t, x) \in [0, T] \times \bar{D}$. The reflected SDE under consideration is

$$\begin{cases} X_s^{t,x} = x + \int_t^s b(X_r^{t,x}) dr + \int_t^s \sigma(X_r^{t,x}) dW_r + K_s^{t,x}, \\ K_s^{t,x} = \int_t^s \nabla l(X_r^{t,x}) d|K^{t,x}|_{[t,r]}, \\ |K^{t,x}|_{[t,s]} = \int_t^s 1_{\{X_r^{t,x} \in \partial D\}} d|K^{t,x}|_{[t,r]}, \quad s \in [t, T], \end{cases} \quad (4)$$

where the notation $|K^{t,x}|_{[t,s]}$ stands for the total variation of $K^{t,x}$ on the interval $[t, s]$, we denote this continuous increasing process by $k_s^{t,x}$. In particular we have

$$k_s^{t,x} = \int_t^s \langle \nabla l(X_r^{t,x}), dK_r^{t,x} \rangle. \quad (5)$$

Several authors have studied the problem of the existence of solutions of the reflected diffusion and its approximation by solutions of equations with penalization terms, we refer for example to [9, 7, 18, 19, 20]. We consider the following sequence of penalized SDEs associated with our reflected diffusion $X^{t,x}$

$$X_s^{t,x,n} = x + \int_t^s [b(X_r^{t,x,n}) - n\delta(X_r^{t,x,n})] dr + \int_t^s \sigma(X_r^{t,x,n}) dW_r, \quad s \in [t, T]. \quad (6)$$

For $s \in [t, T]$, we put

$$K_s^{t,x,n} := \int_t^s -n\delta(X_r^{t,x,n}) dr \quad \text{and} \quad k_s^{t,x,n} := \int_t^s \langle \nabla l(X_r^{t,x,n}), dK_r^{t,x,n} \rangle. \quad (7)$$

We introduce the following assumption

(A.1) : There exist positive constants C and μ such that for every $(x, y) \in \mathbb{R}^d$:

- (i) $\|b(x) + \sigma(x)\| \leq C(1 + |x|)$,
- (ii) $\|b(x) - b(y) + \sigma(x) - \sigma(y)\| \leq \mu|x - y|$.

It is known that under assumption (A.1) equation (6) admits, for any fixed $n \in \mathbb{N}$, a unique strong solution, and we have for every $q \geq 1$:

$$\sup_{n \geq 0} \mathbb{E} \sup_{s \in [t, T]} |X_s^{t,x,n}|^{2q} + \sup_{n \geq 0} \mathbb{E} \sup_{s \in [t, T]} |K_s^{t,x,n}|^{2q} + \sup_{n \geq 0} \mathbb{E} |K^{t,x,n}|_{[t, T]}^q < +\infty. \quad (8)$$

The proof of the previous estimates can be found e.g. in [1, Lemma 3.1].

The first assertion of the following theorem is proved in [20], while the second one follows from [18].

Theorem 1 *Under assumption (A.1), we have*

- (i) the system (4) admits a unique solution,
- (ii) for every $1 \leq q < \infty$ and $0 < T < \infty$,

$$\mathbb{E} \left[\sup_{t \leq s \leq T} |X_s^{t,x,n} - X_s^{t,x}|^q \right] \longrightarrow 0, \quad \text{as } n \rightarrow \infty,$$

the limit is uniform in $(t, x) \in [0, T] \times \bar{D}$.

We extend the processes $(X^{t,x}, K^{t,x})$ and $(X^{t,x,n}, K^{t,x,n})$ to $[0, t)$ by putting

$$X_s^{t,x} = X_s^{t,x,n} := x, \quad K_s^{t,x} = K_s^{t,x,n} := 0, \quad \text{for } s \in [0, t).$$

As a consequence of Theorem 1, we have the following convergence, which is established in [4, Lemma 2.2].

Lemma 2 ([4]) *Under assumptions of Theorem 1, we have, for any $q \geq 1$:*

- (i) $\lim_{n \rightarrow \infty} \mathbb{E} \left[\sup_{0 \leq s \leq T} |K_s^{t,x,n} - K_s^{t,x}|^q \right] = 0;$
- (ii) $\lim_{n \rightarrow \infty} \mathbb{E} \left[\sup_{0 \leq s \leq T} \left| \int_0^s \varphi(X_r^n) dK_r^{t,x,n} - \int_0^s \varphi(X_r) dK_r^{t,x} \right|^q \right] = 0$ for every $\varphi \in \mathcal{C}_b^1(\mathbb{R}^d)$.

Remark 3 (i) *Using Lemma 2 and the representations (5), (7), it holds that for any $q \geq 1$ and any $(t, x) \in [0, T] \times \bar{D}$*

$$\lim_{n \rightarrow +\infty} \mathbb{E} \sup_{s \in [0, T]} |k_s^{t,x,n} - k_s^{t,x}|^q = 0. \quad (9)$$

(ii) *From [17, Corollary 2.5], it follows that for each $q \geq 1$ and each $(t, x) \in [0, T] \times \bar{D}$*

$$\mathbb{E} \sup_{s \in [0, T]} |X_s^{t,x}|^{2q} + \mathbb{E} \sup_{s \in [0, T]} |K_s^{t,x}|^{2q} + \mathbb{E} |K^{t,x}|_{[0, T]}^q < +\infty. \quad (10)$$

2.2 Backward inequality

We state a lemma which is a version of [14, Proposition 6.80, Annex C]. This lemma is essential in our proofs. We give its proof for the convenience.

Lemma 4 Let $(Y, Z) \in \mathcal{S}_m^0 \times \mathcal{M}_{m \times d}^0$, satisfying

$$Y_t = Y_T + \int_t^T d\mathcal{K}_r - \int_t^T Z_r dW_r, \quad 0 \leq t \leq T, \quad \mathbb{P} - a.s.,$$

where $\mathcal{K} \in \mathcal{S}_m^0$ and $\mathcal{K}(\omega) \in BV([0, T]; \mathbb{R}^m)$ (the space of bounded variation processes).

Assume be given

- a non-decreasing stochastic process L with $L_0 = 0$,
- a stochastic process $R(\omega) \in BV([0, T], \mathbb{R})$, with $R_0 = 0$,
- a continuous stochastic process $V(\omega) \in BV([0, T], \mathbb{R})$, such that $V_0 = 0$,

$$\mathbb{E} \left(\sup_{s \in [0, T]} \int_s^T e^{2V_r} dR_r \right) < \infty,$$

and

$$(i) \quad \langle Y_r, d\mathcal{K}_r \rangle \leq \frac{\alpha}{2} \|Z_r\|^2 dr + |Y_r|^2 dV_r + |Y_r| dL_r + dR_r \text{ as measures on } [0, T],$$

$$(ii) \quad \mathbb{E} \sup_{r \in [0, T]} e^{2V_r} |Y_r|^2 < +\infty.$$

We have the following conclusion : if $\alpha < 1$, then there exist positive constants C_1, C_2 and C_3 , depending only on α , such that

$$\begin{aligned} & \mathbb{E} \left(\sup_{r \in [0, T]} |e^{V_r} Y_r|^2 \right) + \mathbb{E} \left(\int_0^T e^{2V_r} \|Z_r\|^2 dr \right) \\ & \leq C_1 \mathbb{E} |e^{V_T} Y_T|^2 + C_2 \mathbb{E} \left(\int_0^T e^{V_r} dL_r \right)^2 + C_3 \mathbb{E} \sup_{s \in [0, T]} \int_s^T e^{2V_r} dR_r. \end{aligned}$$

Proof. By Itô's formula, we have

$$\begin{aligned} |e^{V_t} Y_t|^2 &= |e^{V_T} Y_T|^2 - 2 \int_t^T e^{2V_s} |Y_s|^2 dV_s + 2 \int_t^T e^{2V_s} \langle Y_s, d\mathcal{K}_s \rangle \\ &\quad - \int_t^T e^{2V_s} \|Z_s\|^2 ds - 2 \int_t^T \langle e^{V_s} Y_s, e^{V_s} Z_s dW_s \rangle \\ &= |e^{V_T} Y_T|^2 + 2 \int_t^T e^{2V_s} (\langle Y_s, d\mathcal{K}_s \rangle - |Y_s|^2 dV_s) - \int_t^T e^{2V_s} \|Z_s\|^2 ds \\ &\quad - 2 \int_t^T \langle e^{V_s} Y_s, e^{V_s} Z_s dW_s \rangle. \end{aligned}$$

Using (i) of Lemma 4, we get

$$\begin{aligned} |e^{V_t} Y_t|^2 + (1 - \alpha) \int_t^T e^{2V_s} \|Z_s\|^2 ds &\leq \\ |e^{V_T} Y_T|^2 + 2 \int_t^T e^{2V_s} (dR_s + |Y_s| dL_s) - 2 \int_t^T \langle e^{V_s} Y_s, e^{V_s} Z_s dW_s \rangle. & \end{aligned}$$

We consider the following sequence of stopping time

$$T_n := T \wedge \inf\{s \geq t : \sup_{r \in [t, s]} |e^{V_r} Y_r - e^{V_t} Y_t| + \int_t^s e^{2V_r} \|Z_r\|^2 dr + \int_t^s e^{V_r} dL_r \geq n\}.$$

For $s \in [t, T]$, we put $N_s := 2 \int_0^s 1_{[t, T_n]}(r) < e^{V_r} Y_r, e^{V_r} Z_r dW_r >$.

Since

$$\begin{aligned} \mathbb{E}(\langle N \rangle_T)^{\frac{1}{2}} &\leq C \mathbb{E} \left(\int_t^{T_n} e^{4V_r} |Y_r|^2 \|Z_r\|^2 dr \right)^{\frac{1}{2}} \\ &\leq \sqrt{2} C \mathbb{E} \left(\left[\sup_{r \in [t, T_n]} |e^{V_r} Y_r - e^{V_t} Y_t|^2 + |e^{V_t} Y_t|^2 \right] \int_t^{T_n} e^{2V_r} |Z_r|^2 dr \right)^{\frac{1}{2}} \\ &\leq \sqrt{2} C \mathbb{E} (|e^{V_t} Y_t| + n) \sqrt{n} < +\infty. \end{aligned}$$

Then, the process $\{N_s : s \in [0, T]\}$ is a martingale.

By the foregoing, we have

$$|e^{V_t} Y_t|^2 + (1 - \alpha) \int_t^{T_n} e^{2V_s} \|Z_s\|^2 ds \leq |e^{V_{T_n}} Y_{T_n}|^2 + 2 \int_t^{T_n} e^{2V_s} (dR_s + |Y_s| dL_s) - (N_{T_n} - N_t).$$

Taking expectation, it follows that

$$\begin{aligned} \mathbb{E} \left(|e^{V_t} Y_t|^2 + (1 - \alpha) \int_t^{T_n} e^{2V_s} \|Z_s\|^2 ds \right) &\leq \\ &\mathbb{E} \left(|e^{V_{T_n}} Y_{T_n}|^2 + 2 \int_t^{T_n} e^{2V_s} (dR_s + |Y_s| dL_s) \right). \end{aligned} \quad (11)$$

On the other hand, we have

$$\mathbb{E} \sup_{r \in [0, T_n]} |e^{V_r} Y_r|^2 \leq \mathbb{E} \left(|e^{V_{T_n}} Y_{T_n}|^2 + 2 \sup_{s \in [0, T_n]} \int_s^{T_n} e^{2V_r} dR_r + 2 \int_0^{T_n} e^{2V_s} |Y_s| dL_s + 2 \sup_{r \in [0, T_n]} |N_r| \right).$$

The Burkholder-Davis-Gundy inequality shows that

$$\begin{aligned}
\mathbb{E} \sup_{r \in [0, T_n]} |e^{V_r} Y_r|^2 &\leq \mathbb{E} \left(|e^{V_{T_n}} Y_{T_n}|^2 + 2 \sup_{s \in [0, T_n]} \int_s^{T_n} e^{2V_r} dR_r + 2 \int_0^{T_n} e^{2V_s} |Y_s| dL_s \right) \\
&\quad + 2C_{BDG} \mathbb{E} \left(\int_0^{T_n} e^{4V_r} |Y_r|^2 \|Z_r\|^2 dr \right)^{\frac{1}{2}} \\
&\leq \mathbb{E} \left(|e^{V_{T_n}} Y_{T_n}|^2 + 2 \sup_{s \in [0, T_n]} \int_s^{T_n} e^{2V_r} dR_r + 2 \int_0^{T_n} e^{2V_s} |Y_s| dL_s \right) \\
&\quad + 2C_{BDG} \mathbb{E} \left(\sup_{r \in [0, T_n]} e^{2V_r} |Y_r|^2 \int_0^{T_n} e^{2V_r} \|Z_r\|^2 dr \right)^{\frac{1}{2}} \\
&\leq \mathbb{E} \left(|e^{V_{T_n}} Y_{T_n}|^2 + 2 \sup_{s \in [0, T_n]} \int_s^{T_n} e^{2V_r} dR_r + 2 \int_0^{T_n} e^{2V_s} |Y_s| dL_s \right) \\
&\quad + \mathbb{E} \left(\frac{1}{2} \sup_{r \in [0, T_n]} e^{2V_r} |Y_r|^2 + 2C_{BDG}^2 \int_0^{T_n} e^{2V_r} \|Z_r\|^2 dr \right) \\
&\leq 2\mathbb{E} \left(|e^{V_{T_n}} Y_{T_n}|^2 + 2 \sup_{s \in [0, T_n]} \int_s^{T_n} e^{2V_r} dR_r + 2 \int_0^{T_n} e^{2V_s} |Y_s| dL_s \right) \\
&\quad + 4C_{BDG}^2 \mathbb{E} \left(\int_0^{T_n} e^{2V_r} \|Z_r\|^2 dr \right),
\end{aligned}$$

where C_{BDG} denotes the Burkholder-Davis-Gundy constant.

From inequality (11), we get

$$\begin{aligned}
\mathbb{E} \sup_{r \in [0, T_n]} |e^{V_r} Y_r|^2 + \frac{1}{2} \mathbb{E} \int_0^{T_n} e^{2V_r} \|Z_r\|^2 dr &\leq \mu \mathbb{E} (|e^{V_{T_n}} Y_{T_n}|^2) \\
+ 2\mu \mathbb{E} \left(\sup_{s \in [0, T_n]} \int_s^{T_n} e^{2V_r} dR_r \right) + 2\mu \mathbb{E} \left(\int_0^{T_n} e^{2V_s} |Y_s| dL_s \right),
\end{aligned}$$

where

$$\mu = 2 + \frac{2C_{BDG}^2}{1 - \alpha} + \frac{1}{2(1 - \alpha)}.$$

It follows that

$$\begin{aligned}
& \mathbb{E} \sup_{r \in [0, T_n]} |e^{V_r} Y_r|^2 + \frac{1}{2} \mathbb{E} \int_0^{T_n} e^{2V_r} \|Z_r\|^2 dr \leq \mathbb{E} \left(\mu |e^{V_{T_n}} Y_{T_n}|^2 + 2\mu \sup_{s \in [0, T_n]} \int_s^{T_n} e^{2V_r} dR_r \right) \\
& \quad + 2\mu \mathbb{E} \left(\sup_{r \in [0, T_n]} e^{V_r} |Y_r| \int_0^{T_n} e^{V_r} dL_r \right) \\
& \mathbb{E} \sup_{r \in [0, T_n]} |e^{V_r} Y_r|^2 + \frac{1}{2} \mathbb{E} \int_0^{T_n} e^{2V_r} \|Z_r\|^2 dr \leq \mathbb{E} \left(\mu |e^{V_{T_n}} Y_{T_n}|^2 + 2\mu \sup_{s \in [0, T_n]} \int_s^{T_n} e^{2V_r} dR_r \right) \\
& \quad + \frac{1}{2} \mathbb{E} \sup_{r \in [0, T_n]} e^{2V_r} |Y_r|^2 + 2\mu^2 \mathbb{E} \left(\int_0^{T_n} e^{V_r} dL_r \right)^2 \\
& \mathbb{E} \sup_{r \in [0, T_n]} |e^{V_r} Y_r|^2 + \mathbb{E} \int_0^{T_n} e^{2V_r} \|Z_r\|^2 dr \leq \mathbb{E} \left(2\mu |e^{V_{T_n}} Y_{T_n}|^2 + 4\mu \sup_{s \in [0, T_n]} \int_s^{T_n} e^{2V_r} dR_r \right) \\
& \quad + 4\mu^2 \mathbb{E} \left(\int_0^{T_n} e^{V_r} dL_r \right)^2.
\end{aligned}$$

Put

$$C_1 := 2\mu, \quad C_2 := 4\mu \quad \text{and} \quad C_3 := 4\mu^2.$$

We then have,

$$\begin{aligned}
\mathbb{E} \left(\sup_{r \in [0, T_n]} |e^{V_r} Y_r|^2 + \int_0^{T_n} e^{2V_r} \|Z_r\|^2 dr \right) & \leq C_1 \mathbb{E} |e^{V_{T_n}} Y_{T_n}|^2 + C_2 \mathbb{E} \sup_{s \in [0, T_n]} \int_s^{T_n} e^{2V_r} dR_r \\
& \quad + C_3 \mathbb{E} \left(\int_0^T e^{V_r} dL_r \right)^2.
\end{aligned}$$

Letting n tends to $+\infty$, we conclude by using the Beppo-Levi theorem for the left-hand side term of the previous inequality, and the Lebesgue dominated convergence theorem for the right-hand side term. ■

2.3 The BSDEs associated to the nonlinear Neumann problem

We introduce the generalized BSDEs which we have to use. Let $f : [0, T] \times \mathbb{R}^d \times \mathbb{R}^m \times \mathbb{R}^{m \times d} \rightarrow \mathbb{R}^m$, $h : [0, T] \times \mathbb{R}^d \times \mathbb{R}^m \rightarrow \mathbb{R}^m$ and $g : \mathbb{R}^d \rightarrow \mathbb{R}^m$ be continuous functions, satisfying the following assumptions:

(A.4) There exist C, l_f positive constants and $\beta < 0, \mu_f \in \mathbb{R}$ such that for every $t \in [0, T]$ and every $(x, x', y, y', z, z') \in (\mathbb{R}^d)^2 \times (\mathbb{R}^m)^2 \times (\mathbb{R}^{m \times d})^2$ we have:

- (i) $\langle y - y', f(t, x, y, z) - f(t, x, y', z) \rangle \leq \mu_f |y - y'|^2$,
- (ii) $|f(t, x, y, z) - f(t, x, y, z')| \leq l_f \|z - z'\|$,

- (iii) $|f(t, x, y, 0)| \leq C(1 + |y|)$,
- (iv) $\langle y - y', h(t, x, y) - h(t, x, y') \rangle \leq \beta|y - y'|^2$,
- (v) $|h(t, x, y)| \leq C(1 + |y|)$,
- (vi) $|g(x)| \leq C(1 + |x|)$.

For every $t \in [0, T]$ and $s \in [t, T]$, consider the following generalized BSDEs

$$Y_s^{t,x,n} = g(X_T^{t,x,n}) + \int_s^T f(r, X_r^{t,x,n}, Y_r^{t,x,n}, Z_r^{t,x,n}) dr + \int_s^T h(r, X_r^{t,x,n}, Y_r^{t,x,n}) dk_r^{t,x,n} - \int_s^T Z_r^{t,x,n} dW_r, \quad (12)$$

and

$$Y_s^{t,x} = g(X_T^{t,x}) + \int_s^T f(r, X_r^{t,x}, Y_r^{t,x}, Z_r^{t,x}) dr + \int_s^T h(r, X_r^{t,x}, Y_r^{t,x}) dk_r^{t,x} - \int_s^T Z_r^{t,x} dW_r. \quad (13)$$

According to [12, 13], assumption (A.4) ensures the existence of unique solutions to equations (12) and (13). The solutions of equations (12) and (13) will be respectively denoted by $(Y_s^{t,x,n}, Z_s^{t,x,n})_{s \in [t, T]}$ and $(Y_s^{t,x}, Z_s^{t,x})_{s \in [t, T]}$.

Lemma 5 *Under assumptions (A.1)(i) and (A.4), it holds that for any $t \in [0, T]$,*

$$\sup_{n \geq 1} \mathbb{E} \left(\sup_{r \in [t, T]} |Y_r^{t,x,n}|^2 + \int_t^T |Y_r^{t,x,n}|^2 dk_r^{t,x,n} + \int_t^T \|Z_r^{t,x,n}\|^2 dr \right) < +\infty \quad (14)$$

and

$$\mathbb{E} \left(\sup_{r \in [t, T]} |Y_r^{t,x}|^q + \mathbb{E} \left(\int_t^T \|Z_r^{t,x}\|^2 dr \right)^{\frac{q}{2}} \right) < +\infty, \quad \forall q > 1. \quad (15)$$

Proof. We prove the first assertion. Itô's formula gives

$$\begin{aligned} |Y_s^{t,x,n}|^2 + \int_s^T \|Z_r^{t,x,n}\|^2 dr &= |g(X_T^{t,x,n})|^2 \\ &+ 2 \int_t^T \langle Y_r^{t,x,n}, f(r, X_r^{t,x,n}, Y_r^{t,x,n}, Z_r^{t,x,n}) \rangle dr \\ &+ 2 \int_t^T \langle Y_r^{t,x,n}, h(r, X_r^{t,x,n}, Y_r^{t,x,n}) \rangle dk_r^{t,x,n} - 2 \int_t^T \langle Y_r^{t,x,n}, Z_r^{t,x,n} dW_r \rangle. \end{aligned}$$

Using assumption (A.4), we find

$$\begin{aligned} |Y_s^{t,x,n}|^2 + \int_s^T \|Z_r^{t,x,n}\|^2 dr &\leq C^2 T + 2C^2 + 2C^2 |X_T^{t,x,n}|^2 \\ &+ (1 + 2\mu_f + 2l_f^2) \int_s^T |Y_r^{t,x,n}|^2 dr + 2 \int_s^T (\beta |Y_r^{t,x,n}|^2 + C |Y_r^{t,x,n}|) dk_r^{t,x,n} \\ &- 2 \int_s^T \langle Y_r^{t,x,n}, Z_r^{t,x,n} dW_r \rangle. \end{aligned}$$

Since $-\beta > 0$, we use the inequality $2ab \leq (-\beta)a^2 + \frac{b^2}{(-\beta)}$, to get

$$\begin{aligned} |Y_s^{t,x,n}|^2 + \int_s^T \|Z_r^{t,x,n}\|^2 dr &\leq C^2 T + C^2 + C^2 |X_T^{t,x,n}|^2 \\ &\quad + (1 + 2\mu_f + 2l_f^2) \int_s^T |Y_r^{t,x,n}|^2 dr - \frac{C^2}{\beta} k_T^{t,x,n} + \beta \int_s^T |Y_r^{t,x,n}|^2 dk_r^{t,x,n} \\ &\quad - 2 \int_s^T \langle Y_r^{t,x,n}, Z_r^{t,x,n} dW_r \rangle. \end{aligned}$$

Since the process $(\int_0^\cdot \langle Y_r^{t,x,n}, Z_r^{t,x,n} \rangle dW_r)$ is a uniformly integrable martingale, we take expectation in the previous inequality to show that

$$\begin{aligned} \mathbb{E} \left(|Y_s^{t,x,n}|^2 + |\beta| \int_s^T |Y_r^{t,x,n}|^2 dk_r^{t,x,n} + \int_s^T \|Z_r^{t,x,n}\|^2 dr \right) &\leq C^2 T + C^2 + C^2 \mathbb{E} |X_T^{t,x,n}|^2 \\ &\quad + \frac{C^2}{|\beta|} \mathbb{E} k_T^{t,x,n} + (1 + 2\mu_f + 2l_f^2) \mathbb{E} \int_s^T |Y_r^{t,x,n}|^2 dr. \end{aligned}$$

Using estimate (8) and Gronwall's inequality, we obtain

$$\sup_{n \geq 1} \sup_{s \in [t, T]} \mathbb{E} \left(|Y_s^{t,x,n}|^2 + \int_s^T |Y_r^{t,x,n}|^2 dk_r^{t,x,n} + \int_s^T \|Z_r^{t,x,n}\|^2 dr \right) < +\infty.$$

Burkholder-Davis-Gundy inequality shows that

$$\sup_{n \geq 1} \mathbb{E} \left(\sup_{s \in [t, T]} |Y_s^{t,x,n}|^2 + \int_t^T |Y_r^{t,x,n}|^2 dk_r^{t,x,n} + \int_t^T \|Z_r^{t,x,n}\|^2 dr \right) < +\infty.$$

Inequality (14) is proved. Using [10, Proposition A.2], we prove inequality (15). \blacksquare

We extend the processes $(Y^{t,x,n}, Z^{t,x,n})$ and $(Y^{t,x}, Z^{t,x})$ to $[0, t)$ as follows

$$Y_s^{t,x,n} := Y_t^{t,x,n}, \quad Y_s^{t,x} := Y_t^{t,x} \quad \text{and} \quad Z_s^{t,x,n} = Z_s^{t,x} := 0, \quad s \in [0, t). \quad (16)$$

3 Penalization of the nonlinear Neumann PDE

We divide this section into two parts. The first one concerns the convergence of the solution of the BSDE (12). The second one is an application of our convergence to the nonlinear Neumann boundary problem.

3.1 Convergence of the penalized BSDE

For $(t, x) \in [0, T] \times \bar{D}$, let $(Y_s^{t,x,n}, Z_s^{t,x,n})_{s \in [0, T]}$ and $(Y_s^{t,x}, Z_s^{t,x})_{s \in [0, T]}$ be respectively, the solutions of BSDEs (12) and (13). Our first main result is

Theorem 6 *Let assumptions (A.1) and (A.4) hold. Then, we have the following convergence*

$$\mathbb{E} \left(\sup_{r \in [0, T]} |Y_r^{t,x,n} - Y_r^{t,x}|^2 + \int_0^T \|Z_r^{t,x,n} - Z_r^{t,x}\|^2 dr \right) \rightarrow 0, \quad \text{as } n \rightarrow +\infty.$$

Proof. We adapt the proof of [15, Theorem 3.1] to our situation by bringing some modifications. From now on, we suppress the superscripts (t, x) , and C will denote a nonnegative constant, which may vary from one line to another, but does not depend on n . We shall apply Lemma 4 to the following BSDE

$$Y_s^n - Y_s = g(X_T^n) - g(X_T) + \int_s^T d\mathcal{K}_r^n - \int_s^T (Z_r^n - Z_r) dW_r$$

where

$$d\mathcal{K}_r^n := [f(r, X_r^n, Y_r^n, Z_r^n) - f(r, X_r, Y_r, Z_r)] dr + h(r, X_r^n, Y_r^n) dk_r^n - h(r, X_r, Y_r) dk_r.$$

Using (A.4)(i)-(A.4)(ii), we get for every $0 \leq t \leq s \leq T$,

$$\begin{aligned} & \int_s^T \langle Y_r^n - Y_r, f(r, X_r^n, Y_r^n, Z_r^n) - f(r, X_r, Y_r, Z_r) \rangle dr \\ &= \int_s^T \langle Y_r^n - Y_r, f(r, X_r^n, Y_r^n, Z_r^n) - f(r, X_r^n, Y_r, Z_r^n) \rangle dr \\ & \quad + \int_s^T \langle Y_r^n - Y_r, f(r, X_r^n, Y_r, Z_r^n) - f(r, X_r^n, Y_r, Z_r) \rangle dr \\ & \quad + \int_s^T \langle Y_r^n - Y_r, f(r, X_r^n, Y_r, Z_r) - f(r, X_r, Y_r, Z_r) \rangle dr \\ &\leq \int_s^T \mu_f |Y_r^n - Y_r|^2 dr + l_f |Y_r^n - Y_r| \|Z_r^n - Z_r\| dr \\ & \quad + \int_s^T |Y_r^n - Y_r| |f(r, X_r^n, Y_r, Z_r) - f(r, X_r, Y_r, Z_r)| dr \\ &\leq \int_s^T (l_f^2 + \mu_f) |Y_r^n - Y_r|^2 dr + \frac{1}{4} \|Z_r^n - Z_r\|^2 dr \\ & \quad + \int_s^T |Y_r^n - Y_r| |f(r, X_r^n, Y_r, Z_r) - f(r, X_r, Y_r, Z_r)| dr. \end{aligned}$$

On the other hand, thanks to assumption (A.4)(iv), we obtain

$$\begin{aligned}
& \int_s^T \langle Y_r^n - Y_r, h(r, X_r^n, Y_r^n) dk_r^n - h(r, X_r, Y_r) dk_r \rangle \\
&= \int_s^T \langle Y_r^n - Y_r, h(r, X_r^n, Y_r^n) - h(r, X_r^n, Y_r) \rangle dk_r^n \\
&\quad + \int_s^T \langle Y_r^n - Y_r, h(r, X_r^n, Y_r) - h(r, X_r, Y_r) \rangle dk_r^n \\
&\quad + \int_s^T \langle Y_r^n - Y_r, h(r, X_r, Y_r) \rangle (dk_r^n - dk_r) \\
&\leq \beta \int_s^T |Y_r^n - Y_r|^2 dk_r^n + \int_s^T |Y_r^n - Y_r| |h(r, X_r^n, Y_r) - h(r, X_r, Y_r)| dk_r^n \\
&\quad + \int_s^T \langle Y_r^n - Y_r, h(r, X_r, Y_r) \rangle (dk_r^n - dk_r) \\
&\leq \int_s^T |Y_r^n - Y_r| |h(r, X_r^n, Y_r) - h(r, X_r, Y_r)| dk_r^n + \int_s^T \langle Y_r^n - Y_r, h(r, X_r, Y_r) \rangle (dk_r^n - dk_r).
\end{aligned}$$

By the foregoing, it holds that, for $\lambda = (l_f^2 + \mu_f) \vee l_f^2$,

$$\begin{aligned}
\langle Y_r^n - Y_r, d\mathcal{K}_r^n \rangle &\leq \frac{1}{4} \|Z_r^n - Z_r\|^2 dr + \lambda |Y_r^n - Y_r|^2 dr \\
&\quad + |Y_r^n - Y_r| |h(r, X_r^n, Y_r) - h(r, X_r, Y_r)| dk_r^n \\
&\quad + |Y_r^n - Y_r| |f(r, X_r^n, Y_r, Z_r) - f(r, X_r, Y_r, Z_r)| dr \\
&\quad + \langle Y_r^n - Y_r, h(r, X_r, Y_r) \rangle (dk_r^n - dk_r) \\
&= \frac{1}{4} \|Z_r^n - Z_r\|^2 dr + \lambda |Y_r^n - Y_r|^2 dr + |Y_r^n - Y_r| dL_r^n + dR_r^n,
\end{aligned}$$

where L^n and R^n are defined by

$$dL_r^n := |f(r, X_r^n, Y_r, Z_r) - f(r, X_r, Y_r, Z_r)| dr + |h(r, X_r^n, Y_r) - h(r, X_r, Y_r)| dk_r^n \quad (17)$$

$$dR_r^n := \langle Y_r^n - Y_r, h(r, X_r, Y_r) \rangle (dk_r^n - dk_r). \quad (18)$$

Therefore, by Lemma 4, there exist positive constants C_1, C_2 and C_3 such that

$$\begin{aligned}
& \mathbb{E} \left(\sup_{r \in [0, T]} e^{2\lambda r} |Y_r^n - Y_r|^2 \right) + \mathbb{E} \left(\int_0^T e^{2\lambda r} \|Z_r^n - Z_r\|^2 dr \right) \\
&\leq C_1 \mathbb{E} e^{2\lambda T} |g(X_T^n) - g(X_T)|^2 + C_2 \mathbb{E} \left(\int_0^T e^{\lambda r} dL_r^n \right)^2 + C_3 \mathbb{E} \sup_{s \in [0, T]} \int_s^T e^{2\lambda r} dR_r^n.
\end{aligned} \quad (19)$$

We shall give several auxiliary assertions ensuring that the right-hand side term of the previous inequality converges to zero as n goes to $+\infty$.

Lemma 7 Under assumptions (A.1) and (A.4)(vi), the following convergence holds

$$\lim_{n \rightarrow \infty} \mathbb{E} \left(e^{2\lambda T} |g(X_T^n) - g(X_T)|^2 \right) = 0.$$

Proof. Taking into account the convergence of X_T^n to X_T , the continuity of g , assumption (A.4)(vi) and estimates (8) and (10), the result follows by using the Lebesgue dominated convergence theorem. ■

Lemma 8 Let L^n be the processes given by equation (17). Assume that (A.1) and (A.4) are satisfied. Then,

$$\lim_{n \rightarrow \infty} \mathbb{E} \left(\int_0^T e^{\lambda r} dL_r^n \right)^2 = 0.$$

Proof. Using the triangular inequality, we obtain

$$\begin{aligned} \mathbb{E} \left(\int_0^T e^{\lambda r} dL_r^n \right)^2 &\leq 2\mathbb{E} \left(\int_0^T e^{\lambda r} |f(r, X_r^n, Y_r, Z_r) - f(r, X_r, Y_r, Z_r)| dr \right)^2 \\ &\quad + 2\mathbb{E} \left(\int_0^T e^{\lambda r} |h(r, X_r^n, Y_r) - h(r, X_r, Y_r)| dk_r^n \right)^2 \\ &:= I_1^n + I_2^n. \end{aligned}$$

We shall show that I_1^n and I_2^n tend to zero as n tends to ∞ . Hölder's inequality leads to

$$\begin{aligned} I_1^n &= \mathbb{E} \left(\int_0^T e^{\lambda r} |f(r, X_r^n, Y_r, Z_r) - f(r, X_r, Y_r, Z_r)| dr \right)^2 \\ &\leq 2Te^{2\lambda T} \mathbb{E} \left(\int_0^T |f(r, X_r^n, Y_r, Z_r) - f(r, X_r, Y_r, Z_r)|^2 dr \right). \end{aligned} \quad (20)$$

Again by the convergence of X^n to X in each L^q with respect to the uniform norm and the continuity of f we deduce that the sequence $|f(r, X_r^n, Y_r, Z_r) - f(r, X_r, Y_r, Z_r)|^2$ converges to zero in probability, *a.e.* $r \in [0, T]$. Since by assumptions (A.4)(ii) and (A.4)(iii) on f we have

$$|f(r, X_r^n, Y_r, Z_r) - f(r, X_r, Y_r, Z_r)|^2 \leq C(1 + |Y_r|^2 + \|Z_r\|^2), \quad \textit{a.e. } r \in [0, T],$$

it follows that

$$\mathbb{E}|f(r, X_r^n, Y_r, Z_r) - f(r, X_r, Y_r, Z_r)|^2 \rightarrow 0, \quad \textit{as } n \rightarrow +\infty, \quad \textit{a.e. } r \in [0, T].$$

Using the Lebesgue dominated convergence theorem, we get $\lim_{n \rightarrow +\infty} I_1^n = 0$. Concerning I_2^n , Hölder's inequality yields

$$\begin{aligned} I_2^n &= 2\mathbb{E} \left(\int_0^T e^{\lambda r} |h(r, X_r^n, Y_r) - h(r, X_r, Y_r)| dk_r^n \right)^2 \\ &\leq 2e^{2\lambda T} \left(\mathbb{E} \sup_{r \in [0, T]} |h(r, X_r^n, Y_r) - h(r, X_r, Y_r)|^4 \right)^{\frac{1}{2}} \left(\sup_{n \geq 1} \mathbb{E} (k_T^n)^4 \right)^{\frac{1}{2}}. \end{aligned} \quad (21)$$

On the other hand, by the linear growth assumption on h , we have for each $q > 1$

$$\mathbb{E} \sup_{r \in [0, T]} |h(r, X_r^n, Y_r) - h(r, X_r, Y_r)|^{4q} \leq C(1 + \mathbb{E} \sup_{r \in [0, T]} |Y_r|^{4q}).$$

It follows from estimates (15) that the sequence of random variables $\sup_{r \in [0, T]} |h(r, X_r^n, Y_r) - h(r, X_r, Y_r)|^4$ is uniformly integrable. Since X^n converges to X in each L^q for the uniform norm, we deduce that the sequence $\sup_{r \in [0, T]} |h(r, X_r^n, Y_r) - h(r, X_r, Y_r)|^4$ converges to zero in probability as n goes to $+\infty$. This combined with estimate (8) ensure that $\lim_{n \rightarrow +\infty} I_2^n = 0$. Lemma 8 is proved. ■

We will show an estimate for the solution Y^n that will be used to control the term $\mathbb{E} \sup_{s \in [0, T]} \int_s^T e^{2\lambda r} dR_r^n$. To this end, let $N \in \mathbb{N}$, $N > T$ and the partition of $[0, T]$, $r_i = \frac{iT}{N}$ $i = 0, \dots, N$. We put $r/N := \max\{r_i; r_i \leq r\}$. Given a continuous stochastic process $(H_r)_{r \in [0, T]}$, we define

$$H_r^N := \sum_{i=0}^{N-1} H_{r_i} 1_{[r_i, r_{i+1})}(r) + H_T 1_{\{T\}}(r) = H_{r/N}.$$

Lemma 9 *Assume (A.1) and (A.4) hold. Then, for any $q \in]1, 2[$, there exists a positive constant C depending on T , q and independent on N , such that:*

$$\limsup_{n \rightarrow \infty} \mathbb{E} \left(\int_0^T |Y_r^n - Y_r^{n, N}|^q (dk_r^n + dk_r) \right) \leq \frac{C}{N^{q/2}} + C \left[\mathbb{E} \max_{i=1, \dots, N} (k_{r_i} - k_{r_{i-1}})^{\frac{2q}{2-q}} \right]^{\frac{2-q}{4}}.$$

Proof. We write BSDE (12) between s/N and s

$$\begin{aligned} Y_s^{n, N} &= Y_s^n + \int_{s/N}^s f(r, X_r^n, Y_r^n, Z_r^n) dr \\ &\quad + \int_{s/N}^s h(r, X_r^n, Y_r^n) dk_r^n - \int_{s/N}^s Z_r^n dW_r. \end{aligned}$$

Hölder's inequality gives

$$\begin{aligned} |Y_s^{n, N} - Y_s^n|^q &\leq \frac{C}{N^{q/2}} \left[\int_{s/N}^s |f(r, X_r^n, Y_r^n, Z_r^n)|^2 dr \right]^{q/2} \\ &\quad + C (k_s^n - k_{s/N}^n)^{q/2} \left[\int_{s/N}^s |h(r, X_r^n, Y_r^n)|^2 dk_r^n \right]^{q/2} + C \left| \int_{s/N}^s Z_r^n dW_r \right|^q. \end{aligned}$$

It follows that

$$\mathbb{E} \left(\int_0^T |Y_r^n - Y_r^{n, N}|^q (dk_r^n + dk_r) \right) \leq J_1^{n, N} + J_2^{n, N} + J_3^{n, N}$$

where

$$J_1^{n,N} := \frac{C}{N^{q/2}} \mathbb{E} \int_0^T \left[\int_{s/N}^s |f(r, X_r^n, Y_r^n, Z_r^n)|^2 dr \right]^{q/2} (dk_s^n + dk_s),$$

$$J_2^{n,N} := C \mathbb{E} \int_0^T (k_s^n - k_{s/N}^n)^{q/2} \left(\int_{s/N}^s |h(r, X_r^n, Y_r^n)|^2 dk_r^n \right)^{q/2} (dk_s^n + dk_s),$$

$$J_3^{n,N} := C \mathbb{E} \int_0^T \left| \int_{s/N}^s Z_r^n dW_r \right|^q (dk_s^n + dk_s).$$

We shall estimate $J_1^{n,N}$, $J_2^{n,N}$ and $J_3^{n,N}$. We use Hölder's inequality to obtain

$$\begin{aligned} J_1^{n,N} &= \frac{C}{N^{q/2}} \mathbb{E} \int_0^T \left[\int_{s/N}^s |f(r, X_r^n, Y_r^n, Z_r^n)|^2 dr \right]^{q/2} (dk_s^n + dk_s) \\ &\leq \frac{C}{N^{q/2}} \mathbb{E} \left((k_T^n + k_T) \left[\int_0^T |f(r, X_r^n, Y_r^n, Z_r^n)|^2 dr \right]^{q/2} \right) \\ &\leq \frac{C}{N^{q/2}} \left(\mathbb{E}(k_T^n + k_T)^{\frac{2}{2-q}} \right)^{\frac{2-q}{2}} \left(\mathbb{E} \int_0^T |f(r, X_r^n, Y_r^n, Z_r^n)|^2 dr \right)^{q/2}. \end{aligned}$$

By the linear growth of f in its third variable and Lipschitz continuity with respect to the fourth argument, we get

$$\begin{aligned} J_1^{n,N} &\leq \frac{C}{N^{q/2}} \left(\mathbb{E}(k_T^n + k_T)^{\frac{2}{2-q}} \right)^{\frac{2-q}{2}} \left(1 + \mathbb{E} \sup_{r \in [0, T]} |Y_r^n|^2 + \mathbb{E} \int_0^T \|Z_r^n\|^2 dr \right)^{q/2} \\ &\leq \frac{C}{N^{q/2}} \end{aligned}$$

where in the last line we have used inequalities (8), (10) and (14).

Concerning $J_2^{n,N}$, we use Hölder's inequality, the monotony of k^n and the linear growth

condition on h , to obtain

$$\begin{aligned}
J_2^{n,N} &= C \mathbb{E} \int_0^T (k_s^n - k_{s/N}^n)^{q/2} \left(\int_{s/N}^s |h(r, X_r^n, Y_r^n)|^2 dk_r^n \right)^{q/2} (dk_s^n + dk_s) \\
&\leq C \mathbb{E} \left(\int_0^T |h(r, X_r^n, Y_r^n)|^2 dk_r^n \right)^{q/2} \sum_{i=1}^N \int_{r_{i-1}}^{r_i} (k_s^n - k_{s/N}^n)^{q/2} (dk_s^n + dk_s) \\
&\leq C \left(\mathbb{E} \int_0^T |h(r, X_r^n, Y_r^n)|^2 dk_r^n \right)^{q/2} \left[\mathbb{E} \left(\sum_{i=1}^N \int_{r_{i-1}}^{r_i} (k_s^n - k_{s/N}^n)^{q/2} (dk_s^n + dk_s) \right)^{\frac{2}{2-q}} \right]^{\frac{2-q}{2}} \\
&\leq C \left(\mathbb{E} \int_0^T |h(r, X_r^n, Y_r^n)|^2 dk_r^n \right)^{q/2} \left[\mathbb{E} \left(\sum_{i=1}^N (k_{r_i}^n - k_{r_{i-1}}^n)^{q/2} (k_{r_i}^n + k_{r_i} - k_{r_{i-1}}^n - k_{r_{i-1}}) \right)^{\frac{2}{2-q}} \right]^{\frac{2-q}{2}} \\
&\leq C \left(\mathbb{E} \int_0^T 1 + |Y_r^n|^2 dk_r^n \right)^{q/2} \left[\mathbb{E} \left(\sum_{i=1}^N (k_{r_i}^n - k_{r_{i-1}}^n)^{q/2} (k_{r_i}^n + k_{r_i} - k_{r_{i-1}}^n - k_{r_{i-1}}) \right)^{\frac{2}{2-q}} \right]^{\frac{2-q}{2}} \\
&\leq C \left(\mathbb{E} k_T^n + \mathbb{E} \int_0^T |Y_r^n|^2 dk_r^n \right)^{q/2} \left[\mathbb{E} \left(\sum_{i=1}^N (k_{r_i}^n - k_{r_{i-1}}^n)^{q/2} (k_{r_i}^n + k_{r_i} - k_{r_{i-1}}^n - k_{r_{i-1}}) \right)^{\frac{2}{2-q}} \right]^{\frac{2-q}{2}}.
\end{aligned}$$

Hence, by inequalities (8) and (14), we see that

$$J_2^{n,N} \leq C \left[\mathbb{E} \left(\sum_{i=1}^N (k_{r_i}^n - k_{r_{i-1}}^n)^{q/2} (k_{r_i}^n + k_{r_i} - k_{r_{i-1}}^n - k_{r_{i-1}}) \right)^{\frac{2}{2-q}} \right]^{\frac{2-q}{2}}.$$

Taking into account the convergence of k^n to k (Remark 3 (i)), estimates (8) and (10), we pass to the limit as n goes $+\infty$ then we use the Lebesgue dominated convergence theorem to get

$$\begin{aligned}
\limsup_{n \rightarrow \infty} J_2^{n,N} &\leq C \left[\mathbb{E} \left(\sum_{i=1}^N (k_{r_i} - k_{r_{i-1}})^{q/2} (k_{r_i} - k_{r_{i-1}}) \right)^{\frac{2}{2-q}} \right]^{\frac{2-q}{2}} \\
&\leq C \left[\mathbb{E} \left(\max_{i=1, \dots, N} (k_{r_i} - k_{r_{i-1}})^{q/2} k_T \right)^{\frac{2}{2-q}} \right]^{\frac{2-q}{2}} \\
&\leq C \left[\mathbb{E} \max_{i=1, \dots, N} (k_{r_i} - k_{r_{i-1}})^{\frac{q}{2-q}} k_T^{\frac{2}{2-q}} \right]^{\frac{2-q}{2}} \\
&\leq C \left[\mathbb{E} \max_{i=1, \dots, N} (k_{r_i} - k_{r_{i-1}})^{\frac{2q}{2-q}} \right]^{\frac{2-q}{4}} \left[\mathbb{E} k_T^{\frac{4}{2-q}} \right]^{\frac{2-q}{4}}.
\end{aligned}$$

For $J_3^{n,N}$, we have

$$\begin{aligned}
J_3^{n,N} &= C \mathbb{E} \int_0^T \left| \int_{s/N}^s Z_r^n dW_r \right|^q (dk_s^n + dk_s) \\
&= C \mathbb{E} \sum_{i=1}^N \int_{r_{i-1}}^{r_i} \left| \int_{s/N}^s Z_r^n dW_r \right|^q (dk_s^n + dk_s) \\
&\leq C \sum_{i=1}^N \mathbb{E} \sup_{s \in [r_{i-1}, r_i]} \left| \int_{s/N}^s Z_r^n dW_r \right|^q (k_{r_i}^n - k_{r_{i-1}}^n + k_{r_i} - k_{r_{i-1}}) \\
&\leq C \sum_{i=1}^N \left(\mathbb{E} \sup_{s \in [r_{i-1}, r_i]} \left| \int_{r_{i-1}}^s Z_r^n dW_r \right|^2 \right)^{\frac{q}{2}} \left(\mathbb{E} (k_{r_i}^n - k_{r_{i-1}}^n + k_{r_i} - k_{r_{i-1}})^{\frac{2}{2-q}} \right)^{\frac{2-q}{2}}.
\end{aligned}$$

Using the Burkholder-Davis-Gundy inequality, we obtain

$$J_3^{n,N} \leq C \sum_{i=1}^N \left(\mathbb{E} \int_{r_{i-1}}^{r_i} \|Z_r^n\|^2 dr \right)^{\frac{q}{2}} \left(\mathbb{E} (k_{r_i}^n - k_{r_{i-1}}^n + k_{r_i} - k_{r_{i-1}})^{\frac{2}{2-q}} \right)^{\frac{2-q}{2}}.$$

Again by Hölder's inequality, we find

$$\begin{aligned}
J_3^{n,N} &\leq C \left(\sum_{i=1}^N \mathbb{E} \int_{r_{i-1}}^{r_i} \|Z_r^n\|^2 dr \right)^{\frac{q}{2}} \left(\sum_{i=1}^N \mathbb{E} (k_{r_i}^n - k_{r_{i-1}}^n + k_{r_i} - k_{r_{i-1}})^{\frac{2}{2-q}} \right)^{\frac{2-q}{2}} \\
&\leq C \left(\mathbb{E} \int_0^T \|Z_r^n\|^2 dr \right)^{\frac{q}{2}} \left(\sum_{i=1}^N \mathbb{E} (k_{r_i}^n - k_{r_{i-1}}^n + k_{r_i} - k_{r_{i-1}})^{\frac{2}{2-q}} \right)^{\frac{2-q}{2}}.
\end{aligned}$$

Keeping in mind inequality (14) and the convergence of k^n to k , we pass to the limit as $n \rightarrow +\infty$, to obtain

$$\begin{aligned}
\lim_{n \rightarrow \infty} J_3^{n,N} &\leq C \left(\sum_{i=1}^N \mathbb{E} (k_{r_i} - k_{r_{i-1}})^{\frac{2}{2-q}} \right)^{\frac{2-q}{2}} \\
&\leq C \left(\mathbb{E} \max_{i=1,N} (k_{r_i} - k_{r_{i-1}})^{\frac{q}{2-q}} \sum_{i=1}^N (k_{r_i} - k_{r_{i-1}}) \right)^{\frac{2-q}{2}} \\
&\leq C \left(\mathbb{E} \max_{i=1,N} (k_{r_i} - k_{r_{i-1}})^{\frac{q}{2-q}} k_T \right)^{\frac{2-q}{2}} \\
&\leq C (\mathbb{E} k_T^2)^{\frac{2-q}{4}} \left(\mathbb{E} \max_{i=1,N} (k_{r_i} - k_{r_{i-1}})^{\frac{2q}{2-q}} \right)^{\frac{2-q}{4}} \\
&\leq C \left(\mathbb{E} \max_{i=1,N} (k_{r_i} - k_{r_{i-1}})^{\frac{2q}{2-q}} \right)^{\frac{2-q}{4}}.
\end{aligned}$$

This completes the proof of Lemma 9. \blacksquare

Lemma 10 *Let R^n be the process defined by (18). Under assumptions (A.1) and (A.4), the following inequality holds*

$$\limsup_{n \rightarrow \infty} \mathbb{E} \sup_{s \in [0, T]} \int_s^T e^{2\lambda r} dR_r^n \leq 0.$$

Proof. Set $h_r = h(r, X_r, Y_r)$ and $|h|_\infty = \sup_{r \in [0, T]} |h_r|$, we have

$$\begin{aligned} \langle Y_r^n - Y_r, h_r \rangle &= \langle Y_r^{n, N} - Y_r^N, h_r - h_r^N \rangle + \langle Y_r^N - Y_r, h_r \rangle \\ &\quad + \langle Y_r^{n, N} - Y_r^N, h_r^N \rangle + \langle Y_r^n - Y_r^{n, N}, h_r \rangle. \end{aligned}$$

$$\begin{aligned} \mathbb{E} \left(\sup_{s \in [0, T]} \int_s^T e^{2\lambda r} dR_r^n \right) &= \mathbb{E} \left(\sup_{s \in [0, T]} \int_s^T e^{2\lambda r} \langle Y_r^n - Y_r, h(r, X_r, Y_r) \rangle (dk_r^n - dk_r) \right) \\ &\leq \mathbb{E} \left[(|Y^n|_\infty + |Y|_\infty) |h - h^N|_\infty + |Y^N - Y|_\infty |h|_\infty \right] e^{2\lambda T} (k_T^n + k_T) \\ &\quad + \mathbb{E} \left(\sup_{s \in [0, T]} \sum_{i=1}^N \langle Y_{r_{i-1}}^n - Y_{r_{i-1}}, h_{r_{i-1}} \rangle \int_{s \wedge r_{i-1}}^{r_i} e^{2\lambda r} d(k_r^n - k_r) \right) \\ &\quad + \mathbb{E} \left(e^{2\lambda T} |h|_\infty \int_0^T |Y_r^{n, N} - Y_r^n| (dk_r^n + dk_r) \right). \end{aligned}$$

Let $1 < q < 2$. Using Hölder's inequality repeatedly to obtain

$$\begin{aligned} \mathbb{E} \left(\sup_{s \in [0, T]} \int_s^T e^{2\lambda r} dR_r^n \right) &\leq \left[\mathbb{E} \left[e^{2\lambda T} (|Y^n|_\infty + |Y|_\infty)^2 \right] \right]^{\frac{1}{2}} \left[\mathbb{E} (k_T^n + k_T)^4 \right]^{\frac{1}{4}} \left[\mathbb{E} |h - h^N|_\infty^4 \right]^{\frac{1}{4}} \\ &\quad + \left[\mathbb{E} \left[e^{2\lambda T} (k_T^n + k_T) |h|_\infty \right]^2 \right]^{\frac{1}{2}} \left[\mathbb{E} |Y^N - Y|_\infty^2 \right]^{\frac{1}{2}} \\ &\quad + 2N e^{2\lambda T} (1 + \lambda T) \left[\mathbb{E} \left[e^{2\lambda T} (|Y^n|_\infty + |Y|_\infty)^2 \right] \right]^{\frac{1}{2}} \left[\mathbb{E} |h|_\infty^4 \right]^{\frac{1}{4}} \left(\mathbb{E} \left[\sup_{s \in [0, T]} |k_s^n - k_s|^4 \right] \right)^{\frac{1}{4}} \\ &\quad + e^{2\lambda T} \left[\mathbb{E} |h|_\infty^{\frac{2q}{q-1}} \right]^{\frac{q-1}{2q}} \left[\mathbb{E} (k_T^n + k_T)^2 \right]^{\frac{q-1}{2q}} \left[\mathbb{E} \int_0^T |Y_r^{n, N} - Y_r^n|^q (dk_r^n + dk_r) \right]^{\frac{1}{q}}. \end{aligned} \quad (22)$$

The linear growth hypothesis on h combined with estimate (15) show that for every $p \geq 1$,

$$\mathbb{E} |h|_\infty^p = \mathbb{E} \sup_{r \in [0, T]} |h(r, X_r, Y_r)|^p \leq C(1 + \mathbb{E} \sup_{r \in [0, T]} |Y_r|^p) < +\infty.$$

On the other hand, we use inequalities (8), (10), (14) and (15) along with Lemma 9 then we pass to the limit as n goes to $+\infty$ in inequality (22) to get, for all $N \in \mathbb{N}^*$,

$$\begin{aligned} \limsup_{n \rightarrow +\infty} \mathbb{E} \left(\sup_{s \in [0, T]} \int_s^T e^{2\lambda r} dR_r^n \right) &\leq C (\mathbb{E} |h - h^N|_\infty^4)^{1/4} + C (\mathbb{E} |Y^N - Y|_\infty^2)^{1/2} \\ &\quad + \left[\frac{C}{N^{q/2}} + C \left[\mathbb{E} \max_{i=1, N} (k_{r_i} - k_{r_{i-1}})^{\frac{2q}{2-q}} \right]^{\frac{2-q}{4}} \right]^{1/q}. \end{aligned}$$

Since the integrands are uniformly integrable, then passing to the limit as $N \rightarrow +\infty$, we get the result. Lemma 10 is proved. ■

Now, combining inequality (19) with Lemmas 7, 8 and 10, we complete the proof of Theorem 6. ■

3.2 Convergence of the penalized PDE

This subsection is devoted to an application of our convergence of the BSDE. Namely, we will establish the convergence of a viscosity solution of the following systems

$$\begin{cases} \frac{\partial u_i^n}{\partial t}(t, x) + \mathcal{L} u_i^n(t, x) + f_i(t, x, u^n(t, x), (\nabla u^n \sigma)(t, x)) \\ \quad - n < \delta(x), \nabla u_i^n(t, x) + \nabla l(x) > h_i(t, x, u^n(t, x)) = 0, \\ u^n(T, x) = g(x), 1 \leq i \leq m, 0 \leq t \leq T, x \in \mathbb{R}^d, n \in \mathbb{N} \end{cases} \quad (23)$$

to a viscosity solution of a system of the form

$$\begin{cases} \frac{\partial u_i}{\partial t}(t, x) + \mathcal{L} u_i(t, x) + f_i(t, x, u(t, x), (\nabla u \sigma)(t, x)) = 0, 1 \leq i \leq m, (t, x) \in [0, T] \times D, \\ u(T, x) = g(x), x \in D, \\ \frac{\partial u}{\partial n}(t, x) + h(t, x, u(t, x)) = 0, \forall (t, x) \in [0, T] \times \partial D. \end{cases} \quad (24)$$

Since, we consider viscosity solutions, we introduce the following condition

(A.5) f_i , the i -th coordinate of f , depends only on the i -th row of the matrix z .

For the self-contained, we recall the definition of the viscosity solution of system (24).

Definition 11 (i) $u \in \mathcal{C}([0, T] \times \bar{D}, \mathbb{R}^m)$ is called a viscosity sub solution of system (24) if $u_i(T, x) \leq g_i(x)$, $x \in \bar{D}$, $1 \leq i \leq m$ and, for any $1 \leq i \leq m$, $\varphi \in \mathcal{C}^{1,2}([0, T] \times \mathbb{R}^d)$, and $(t, x) \in (0, T] \times \bar{D}$ at which $u_i - \varphi$ has a local maximum, one has

$$-\frac{\partial \varphi}{\partial t}(t, x) - \mathcal{L} \varphi(t, x) - f_i(t, x, u(t, x), (\nabla \varphi \sigma)(t, x)) \leq 0, \quad \text{if } x \in D,$$

$$\begin{aligned} & \min \left(-\frac{\partial \varphi}{\partial t}(t, x) - \mathcal{L} \varphi(t, x) - f_i(t, x, u(t, x), (\nabla \varphi \sigma)(t, x)), \right. \\ & \left. -\frac{\partial \varphi}{\partial n}(t, x) - h_i(t, x, u(t, x)) \right) \leq 0, \quad \text{if } x \in \partial D. \end{aligned}$$

(ii) $u \in \mathcal{C}([0, T] \times \bar{D}, \mathbb{R}^d)$ is called a viscosity super-solution of (24) if $u_i(T, x) \geq g_i(x)$, $x \in \bar{D}$, $1 \leq i \leq m$ and, for any $1 \leq i \leq m$, $\varphi \in \mathcal{C}^{1,2}([0, T] \times \mathbb{R}^d)$, and $(t, x) \in (0, T] \times \bar{D}$

at which $u_i - \varphi$ has a local minimum, one has

$$-\frac{\partial \varphi}{\partial t}(t, x) - \mathcal{L}\varphi(t, x) - f_i(t, x, u(t, x), (\nabla \varphi \sigma)(t, x)) \geq 0, \quad \text{if } x \in D,$$

$$\max \left(-\frac{\partial \varphi}{\partial t}(t, x) - \mathcal{L}\varphi(t, x) - f_i(t, x, u(t, x), (\nabla \varphi \sigma)(t, x)), \right. \\ \left. -\frac{\partial \varphi}{\partial n}(t, x) - h_i(t, x, u(t, x)) \right) \geq 0, \quad \text{if } x \in \partial D.$$

(iii) $u \in \mathcal{C}([0, T] \times \bar{D}, \mathbb{R}^m)$ is called a viscosity solution of system (24) if it is both a viscosity sub and super-solution.

We recall a continuity of the map $(t, x) \mapsto Y_t^{t,x}$ where $Y^{t,x}$ is the solution of BSDE (13). This continuity has been proved in [15].

Proposition 12 ([15]) Under assumptions (A.1) and (A.4), the mapping $(t, x) \rightarrow Y_t^{t,x}$ is continuous.

Our second main result is

Theorem 13 Assume (A.1), (A.4) and (A.5). There exist a sequence of continuous functions $u^n : [0, T] \times \mathbb{R}^d \rightarrow \mathbb{R}^m$ and a function $u : [0, T] \times \bar{D} \rightarrow \mathbb{R}^m$ such that: u^n is a viscosity solution to system (23), u is a viscosity solution to system (24) and the following convergence holds for every $(t, x) \in [0, T] \times \bar{D}$

$$\lim_{n \rightarrow +\infty} u^n(t, x) = u(t, x).$$

Proof. We set,

$$u^n(t, x) := Y_t^{t,x,n} \quad \text{and} \quad u(t, x) := Y_t^{t,x}. \quad (25)$$

It follows from Theorem 3.2 of [12] that u^n is a viscosity solution of PDEs (23). Thanks to [15, 13], u is a viscosity solution of PDEs (24). Further, we have for each $(t, x) \in [0, T] \times \bar{D}$

$$|u^n(t, x) - u(t, x)|^2 = |Y_t^{t,x,n} - Y_t^{t,x}|^2 \leq \mathbb{E} \sup_{s \in [0, T]} |Y_s^{t,x,n} - Y_s^{t,x}|^2.$$

Thanks to Theorem 6, we have $\lim_{n \rightarrow \infty} \mathbb{E} \sup_{s \in [0, T]} |Y_s^{t,x,n} - Y_s^{t,x}|^2 = 0$. It follows that,

$$\lim_{n \rightarrow +\infty} u^n(t, x) = u(t, x).$$

The theorem is proved. ■

Remark 14 When u is the unique viscosity solution of system (24), then it is constructible by penalization. This is the case when $d = d'$, since by [14, Theorem 5.43, p 423] or [15, Theorem 5.1] the viscosity solution of system (24) is unique.

References

- [1] K. Bahlali, L. Maticiuc and A. Zalinescu, Penalization method for a nonlinear Neumann PDE via weak solution of reflected SDEs, *Electron. J. Probab.* 18(2013), no. 102, 1-19
- [2] Bahlali, Khaled; Elouaffin, Abouo; Pardoux, Etienne Averaging for BSDEs with null recurrent fast component. Application to homogenization in a non periodic media. *Stochastic Process. Appl.* 127 (2017), no. 4, 1321-1353.
- [3] K. Bahlali, B. Boufoussi and S. Mouchtabih, Penalization for a PDE with a nonlinear Neumann boundary condition and measurable coefficients. *Stochastics and Dynamics*, 2021. <https://doi.org/10.1142/S0219493721500532>
- [4] B. Boufoussi, J. van Casteren, An approximation result for a nonlinear Neumann boundary value problem via BSDEs, *Stochastic Process. Appl.* 114 (2004), 331-350.
- [5] Delarue, F. Equations différentielles stochastiques progressives-rétrogrades. Application à l'homogénéisation des EDP quasi-linéaires. *Thèse de Doctorat*, (2002), Aix Marseille Université. Formerly Université de Provence, Aix-Marseille I.
- [6] Delarue, F. Auxiliary SDEs for homogenization of quasilinear PDEs with periodic coefficients. *Ann. Probab.* 32 (2004), no. 3B, 2305-2361.
- [7] W. Laukajtys, L. Slominski, Penalization methods for reflecting stochastic differential equations with jumps, *Stoch. Stoch. Rep.* 75 no. 5 (2003), 275-293
- [8] P.L. Lions, J.L. Menaldi and A.S. Sznitman, Construction de processus de diffusion réfléchis par pénalisation du domaine, *C. R. Acad. Sc. Paris, t. 229, Série I (1981)* 459-462.
- [9] P.L. Lions, A.S. Sznitman, Stochastic differential equations with reflecting boundary conditions, *Comm. Pure Appl. Math.* XXXVII (1984) 511-537.
- [10] L. Maticiuc and A. Rascanu, Backward stochastic variational inequalities on random interval, *Bernoulli* 21(2) (2015), pp. 1166-1199.
- [11] J.L. Menaldi, Stochastic Variational Inequality for Reflected Diffusion, *Indiana University Mathematical Journal*, Vol.32, No 5 (1983).
- [12] E. Pardoux, BSDEs, weak convergence and homogenization of semilinear PDEs, *Non-linear Analysis, Differential Equations and Control (Montreal, QC, 1998)*, Kluwer Academic Publishers, Dordrecht (1999), 503-549.

- [13] É. Pardoux and S. Zhang, Generalized BSDEs and nonlinear Neumann boundary value problems, *Prob. Theory and Rel. Fields*, 110 (1998) 535-558.
- [14] E. Pardoux and A. Rascanu, Stochastic differential equations, Backward SDEs, Partial differential equations, *Stoch. Model. Appl. Probab.* 69 (2014). Springer
- [15] E. Pardoux and A. Rascanu (2017): Continuity of the Feynman-Kac formula for a generalized parabolic equation, *Stochastics* (89) 5, 726-752. <http://dx.doi.org/10.1080/17442508.2016.1276911>
- [16] A. Rozkosz and L. Slominski, On stability and existence of solutions of SDEs with reflection at the boundary, *Stoc. Proc. Appl.* 68, (1997), 285-302.
- [17] L. Slominski, Eulers approximations of solutions of SDEs with reflecting boundary, *Stochastic Process. Appl.* 94(2001) 317-337.
- [18] L. Slominski, Weak and strong approximations of reflected diffusions via penalization methods, *Stochastic Process. Appl.* 123(2013)752-763.
- [19] D.W. Stroock, S.R.S. Varadhan, Diffusion Processes with boundary conditions, *Comm. Pure Appl. Math.* 24 (1971), 147-225.
- [20] H. Tanaka, Stochastic differential equations with reflecting boundary condition in convex regions, *Hiroshima Math. J.* 9 (1979) 163-177.