# Dealing with missing data in model-based clustering through a MNAR model 

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## Dealing with missing data in model-based clustering through a MNAR model

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## Take home message

1 The missing data pattern may convey some information on clustering
2 Embed the missingness mechanism directly within the clustering modeling step

## Outline

1 Introduction

2 A model-based MNAR clustering approach

3 Identifiability

4 Inference procedures

5 Medical study illustration

6 Concluding remarks

## Missing data: an inevitable event

The larger the datasets, the more missing data may appear. . .

Two traditional solutions (for obtaining a filled dataset)

- Discard individuals with missing data: more variance or a biased subset
- Impute missing data: possible bias and underestimation of the variability


## General guidelines

- Obtaining a complete dataset is not the final goal
- Missing data management should take into account the initial analysis target

Our analysis target: model-based clustering
Embed missing data management into this paradigm...

## Missing data: notations

■ $Y=\left\{y_{1}|\ldots| y_{n}\right\}^{T}$ : full dataset with $n$ individuals
$\square y_{i}=\left(y_{i 1}, \ldots, y_{i d}\right) \in \mathcal{Y}$, depending on the data type: individual $i \in\{1, \ldots, n\}$

- continuous data: $\mathcal{Y}=\mathbb{R}^{d}$
- categorical data: $\mathcal{Y}=\{0,1\}^{\ell_{1}} \times \ldots \times\{0,1\}^{\ell_{d}}$ where $\ell_{j}$ is the number of levels for $y_{i j}=\left(y_{i j}^{1}, \ldots, y_{i j}^{\ell j}\right)$, where $y_{i j}^{\ell}=1$ if $y_{i j}$ takes the level $\ell, 0$ otherwise.
- mixed data: combination of continuous and categorical data.
- $C=\left\{c_{1}|\ldots| c_{n}\right\}^{T} \in\{0,1\}^{n \times d}$ : pattern of missing data for the full dataset
- $c_{i}=\left(c_{i 1}, \ldots, c_{i d}\right) \in\{0,1\}^{d}$ : pattern of missing data for individual $i \in\{1, \ldots, n\}$

$$
c_{i j}=1 \Leftrightarrow y_{i j} \text { is missing }
$$

- $y_{i}^{\text {obs: }}$ the observed variables values for individual $i$
- $y_{i}^{\text {mis }}$ : the missing variables values for individual $i$

Missing data: typology of the missing mechanisms

- Missing completely at random (MCAR):

$$
\mathbb{P}(c \mid y ; \psi)=\mathbb{P}(c ; \psi) \quad \forall y
$$

- Missing at random (MAR):

$$
\mathbb{P}(c \mid y ; \psi)=\mathbb{P}\left(c \mid y^{\mathrm{obs}} ; \psi\right) \quad \forall y^{\mathrm{mis}}
$$

■ Missing not at random (MNAR): the mechanism is not MCAR nor MAR

## Example of MNAR data

The probability to have a missing value on income depends on the value of income (rich people less inclined to reveal their income).

## Ignorable vs. non ignorable model

A missing mechanism is ignorable if likelihoods can be decomposed as

$$
L(\theta, \psi ; \underbrace{y^{\text {obs }}, c}_{\text {observed data }})=L\left(\psi ; c \mid y^{\text {obs }}\right) \times L\left(\theta ; y^{\text {obs }}\right)
$$

Some simple algebra show that this occurs when missing mechanism is not MNAR

## Inference of $\theta$

"If the missing mechanism is ignorable then likelihood-based inferences for $\theta$ from $L\left(\theta ; y^{\text {obs }}\right)$ will be the same as likelihood based inference for $\theta$ from $L\left(\theta, \psi ; y^{\text {obs }}, c\right)$. ." ([Little and Rubin, 2002] Section 6.2)

- M(C)AR is ignorable
- MNAR is not ignorable


## Clustering: model-based approach

- Partition with $K$ clusters: $Z=\left(z_{1}|\ldots| z_{n}\right)^{T} \in\{0,1\}^{n \times K}$ where
- $z_{i}=\left(z_{i 1}, \ldots, z_{i k}\right) \in\{0,1\}^{K}$
- $z_{i k}=1$ if $y_{i}$ belongs to cluster $k, z_{i k}=0$ otherwise

■ Mixture model: $y_{1}, \ldots, y_{n}$ are i.i.d. from the mixture

$$
f\left(y_{i} ; \pi, \theta\right)=\sum_{k=1}^{K} \pi_{k} f_{k}\left(y_{i} ; \theta_{k}\right)
$$

- $\pi_{k}=P\left(z_{i k}=1\right), \pi=\left(\pi_{1}, \ldots, \pi_{K}\right)$
- $f_{k}\left(. ; \theta_{k}\right)$ : pdf of the $k$-th component parametrized by $\theta_{k}, \theta=\left(\theta_{1}, \ldots, \theta_{K}\right)$
- continuous data: $f_{k}\left(. ; \theta_{k}\right)=\phi\left(. ; \mu_{k}, \Sigma_{k}\right)$ is the d-variate Gaussian distribution with mean vector $\mu_{k}$ and covariance matrix $\Sigma_{k}$
- categorical data: the features are independent conditionally to the group membership i.e.
$f_{k}\left(. ; \theta_{k}\right)=\prod_{j=1}^{d} f_{k j}\left(. ; \theta_{k j}\right)$, where $f_{k j}=\prod_{\ell=1}^{\ell_{j}}\left(\theta_{k j}^{\ell}\right)^{y_{i j}^{\ell}}$ is the multinomial distribution with $\theta_{k j}=\left(\theta_{k j}^{\ell}=\mathbb{P}\left(y_{i j}^{\ell}=1 \mid z_{i k}=1\right)\right)_{\ell=1, \ldots, \ell_{j}}$
- mixed data: the features are independent conditionally to the group membership, $f_{k}\left(. ; \theta_{k}\right)$ is the product of univariate Gaussian and multinomial distributions
- Can also be extended to other cases (count data with Poisson distributions for instance)


## Question we address in this work

Which distribution $\mathbb{P}(c \mid y, z ; \psi)$ to propose in this clustering context?

## Outline

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2 A model-based MNAR clustering approach

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## Proposed zoology of MNAR models in clustering

$$
\mathbb{P}\left(c_{i} \mid y_{i}, z_{i k}=1 ; \psi\right)=\prod_{j=1}^{d} \mathbb{P}\left(c_{i j} \mid y_{i}, z_{i k}=1 ; \psi\right)
$$

- MNARy ${ }^{k} z^{j}$, with $\psi=(\alpha, \beta)$ where $\alpha=\left(\alpha_{11}, \ldots, \alpha_{1 d}, \ldots, \alpha_{K 1}, \ldots, \alpha_{K d}\right)^{T} \in \mathbb{R}^{K d}$ and

$$
\begin{aligned}
\beta=\left(\beta_{11}, \ldots,\right. & \beta_{1 d}, \ldots, \\
& \left.\beta_{K 1}, \ldots, \beta_{K d}\right)^{T} \in \mathbb{R}^{K d} \\
& \mathbb{P}\left(c_{i j}=1 \mid y_{i}, z_{i k}=1 ; \psi\right)=\rho\left(\alpha_{k j}+\beta_{k j} y_{i j}\right),
\end{aligned}
$$

with $\rho$ the cdf of any continuous distribution (logit, probit)

- MNARyz , MNARy ${ }^{k} z$, MNARyz $^{j}$
- MNARy, MNARy ${ }^{k}$

$$
\begin{aligned}
& \psi=\left(\beta_{11}, \ldots, \beta_{1 d}, \ldots, \beta_{K 1}, \ldots, \beta_{K d}\right)^{T} \\
& \quad \mathbb{P}\left(c_{i j}=1 \mid y_{i}, z_{i k}=1 ; \psi\right)=\rho\left(\beta_{k j} y_{i j}\right)
\end{aligned}
$$

- MNARz, MNARz ${ }^{j}$

$$
\begin{aligned}
\psi=\left(\alpha_{11}\right. & \left.\ldots, \alpha_{1 d}, \ldots, \alpha_{K 1}, \ldots, \alpha_{K d}\right)^{T} \\
& \mathbb{P}\left(c_{i j}=1 \mid y_{i}, z_{i k}=1 ; \psi\right)=\rho\left(\alpha_{k j}\right)
\end{aligned}
$$



## Overview of the proposed MNAR models

|  | Effect on the <br> variable $j$ |  | Effect on the class <br> membership $k$ |  | Nb parameters |  |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Depends <br> on $j$ | Depends <br> on $k$ | Depends <br> on $j$ | Depends <br> on $k$ | Continuous | Categorical |
| MNARz $^{j} y^{k}$ | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ | $2 K d$ | $K\left(d+\sum_{j=1}^{d}\left(\ell_{j}-1\right)\right)$ |
| MNARyz $^{j}$ | $\checkmark$ | $x$ | $\checkmark$ | $\checkmark$ | $(K+1) d$ | $K d+\sum_{j=1}^{d}\left(\ell_{j}-1\right)$ |
| MNARy $z$ | $\checkmark$ | $\checkmark$ | $x$ | $\checkmark$ | $K(d+1)$ | $K\left(1+\sum_{j=1}^{d}\left(\ell_{j}-1\right)\right)$ |
| MNARyz | $\checkmark$ | $x$ | $x$ | $\checkmark$ | $(K+d)$ | $K+\sum_{j=1}^{d}\left(\ell_{j}-1\right)$ |
| MNARy | $\checkmark$ | $x$ | $x$ | $x$ | $d$ | $\sum_{j=1}^{d}\left(\ell_{j}-1\right)$ |
| MNARy $^{k}$ | $\checkmark$ | $\checkmark$ | $x$ | $x$ | $K$ | $K \sum_{j=1}^{d}\left(\ell_{j}-1\right)$ |
| MNARz $^{j}$ | $x$ | $x$ | $x$ | $\checkmark$ | $\checkmark$ | $\checkmark$ |

Terminology in the sequel:
■ MNARz, MNARz ${ }^{j}$ : the only effect of missingness is on the class membership

- MNARy*: all the other models which considers the effect of the missingness depending on the variable
- MNAR*: all the models

MNARz analysis: it depends on $y$ through $z$ !

$$
P\left(c_{i j}=1 \mid y_{i} ; \theta, \psi\right)=\sum_{k=1}^{K} P\left(c_{i j}=1 \mid y_{i}, z_{i k}=1 ; \psi\right) P\left(z_{i k}=1 \mid y_{i} ; \theta\right)
$$

Example of a univariate Gaussian model with the three components

$$
0.2 N(\cdot ; 0,1)+0.3 N(\cdot ; 1,2)+0.5 N(\cdot ; 2,3)
$$

and with parameters of the logit expression: $\alpha_{0}=1, \beta_{1}=1, \beta_{2}=-1, \beta_{3}=1$


## MNARz analysis: pattern c gives information on partition z!

Draw Bayes error of a MNARz model with two components and $20 \%$ of missing data

$$
\pi_{k}=0.5,\left\|\mu_{2}-\mu_{1}\right\| \text { varies, } \Sigma_{1}=\boldsymbol{\Sigma}_{2}=\mathbf{I},\left|\beta_{2}-\beta_{1}\right| \text { varies }
$$



Both $\mu_{k}$ and $\beta_{k}$ act on the Bayes error

## Reinterpretation of the MNARz and MNARz ${ }^{j}$ models as MAR

Commonly used in Machine Learning
[Jones, 1996, Little and Rubin, 2002, Josse et al., 2019]

Mixture model for $Y^{\text {obs }}$ and Bernoulli distribution for $C$
$\Leftrightarrow$ MAR mixture model for $\tilde{Y}^{\text {obs }}=\left(Y^{\text {obs }} \mid C\right)$

For example,

$$
Y^{\text {obs }}=\left(\begin{array}{ccc}
? & 2.6 & 5 \\
\text { blue } & 1.9 & 4 \\
\text { red } & 2.3 & ?
\end{array}\right), \quad C=\left(\begin{array}{lll}
1 & 0 & 0 \\
0 & 0 & 0 \\
0 & 0 & 1
\end{array}\right)
$$

then $\tilde{Y}^{\text {obs }}$ is expressed as

$$
\tilde{Y}^{\mathrm{obs}}=\left(\begin{array}{cccccc}
? & 2.6 & 5 & 1 & 0 & 0 \\
\text { blue } & 1.9 & 4 & 0 & 0 & 0 \\
\text { red } & 2.3 & ? & 0 & 0 & 1
\end{array}\right)
$$

## Proposition 1: in terms of maximum likelihood

The maximum likelihood estimate associated to the dataset $\tilde{Y}^{\text {obs }}$ under MAR model is the one associated to the dataset $Y^{\text {obs }}$ under MNARz or MNARz ${ }^{j}$ models. $\Rightarrow$ can be extended to other estimation strategies

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## Continuous and count data (1)

Previous works: [Teicher, 1963] (without NA), [Miao et al., 2016] (for MNAR data)

Identifiability for a mixture model with MNAR data
$\Leftrightarrow$ Mixture/MNAR parameters are uniquely determined from available information

## Proposition 2: identifiability for continuous and count data

Assume that
1 The marginal mixture $\sum_{k=1}^{K} \pi_{k} f_{k}\left(y_{i} ; \theta_{k}\right)$ is identifiable
■ There exists a total ordering $\preceq$ of $\mathcal{F}_{j} \times \mathcal{R}$, for $j \in\{1, \ldots, d\}$ fixed, where $\mathcal{F}_{j}=\left\{f_{1 j}, \ldots, f_{K j}\right\}$ and $\mathcal{R}=\left\{\rho_{1}, \ldots, \rho_{K}\right\}=\left\{\rho\left(. ; \psi_{1}\right), \ldots, \rho\left(. ; \psi_{K}\right)\right\}$. The total ordering is s.t. $\forall k<\ell, F_{k}=\rho_{k} f_{k j} \preceq F_{\ell}=\rho_{\ell} f_{\ell j}$ implies

$$
\lim _{u \rightarrow+\infty} \frac{\rho_{\ell}(u) f_{\ell j}(u)}{\rho_{k}(u) f_{k j}(u)}=0
$$

Then the mixture model with one of the MNAR* mechanisms is identifiable up to label swapping

## Continuous and cound data (2)

Is the total ordering checked for classical distributions ?

| $f_{k}$ | Gaussian |  | Poisson |  |
| :---: | :---: | :---: | :---: | :---: |
| $\rho_{k}$ | Probit | Logit | Probit | Logit |
| MNARz $^{j} y^{k}$ |  | generic idenfiability | $\checkmark$ | generic idenfiability |
| MNARy $^{k} z$ | $\checkmark$ |  |  |  |
| MNARy |  |  |  |  |

Generic identifiability: all not-identifiable parameter choices lie within a proper subvariety, and thus form a set of Lebesgue zero measure

## Categorical data

Previous work: [Allman et al., 2009] (without NA)
Recall that for categorical data: conditional independence of the features given the group membership holds i.e. $f_{k}\left(\cdot ; \theta_{k}\right)=\prod_{j=1}^{d} f_{k j}\left(\cdot ; \theta_{k j}\right)$

Proposition 3: identifiability for categorical data
Assume that $d \geq 2\left\lceil\log _{2} K\right\rceil+1$ and $f_{k}\left(\cdot ; \theta_{k}\right)=\prod_{j=1}^{d} f_{k j}\left(\cdot ; \theta_{k j}\right)$
$\checkmark$ Then the mixture model with MNARz or MNARz ${ }^{j}$ mechanism is identifiable up
to label swapping
$x$ The mixture model with one of the MNARy* mechanisms is not identifiable

## Mixed data

$f_{k}\left(\cdot ; \theta_{k}\right)=\prod_{j=1}^{d} f_{k j}\left(\cdot ; \theta_{k j}\right)$, thus identifiability of mixed data directly follows from Proposition 2 for continuous variables and from Proposition 3 for categorical variables

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EM algorithm: looks simple

The expected complete log-likelihood knowing the observed data and a current value of the parameters can be decomposed into two parts

$$
\begin{aligned}
Q\left(\theta, \psi, \pi ; \theta^{r}, \psi^{r}, \pi^{r}\right) & =\mathbb{E}\left[\ell_{\text {comp }}(\theta, \psi, \pi ; y, z, c) \mid y_{i}^{\text {obs }}, c_{i} ; \theta^{r}, \psi^{r}, \pi^{r}\right] \\
& =Q_{y}\left(\theta, \pi ; \theta^{r}, \psi^{r}, \pi^{r}\right)+Q_{c}\left(\psi ; \theta^{r}, \psi^{r}, \pi^{r}\right) \\
Q_{y}\left(\theta, \pi ; \theta^{r}, \psi^{r}, \pi^{r}\right)= & \sum_{i=1}^{n} \sum_{k=1}^{K}\left(\tau_{i k}\right)^{r} \log \left(\pi_{k}\right)+\sum_{i=1}^{n} \sum_{k=1}^{K}\left(\tau_{i k}\right)^{r} E_{i y}^{r}(\theta) \\
Q_{c}\left(\psi ; \theta^{r}, \psi^{r}, \pi^{r}\right) & =\sum_{i=1}^{n} \sum_{k=1}^{K}\left(\tau_{i k}\right)^{r} E_{i c}^{r}(\psi)
\end{aligned}
$$

where for $i=1, \ldots, n$ and $k=1, \ldots, K$,

$$
\begin{aligned}
E_{i y}^{r}(\theta) & =\mathbb{E}\left[\log \left(f_{k}\left(y_{i} ; \theta_{k}\right)\right) \mid y_{i}^{\text {obs }}, z_{i k}=1, c_{i} ; \theta^{r}, \psi^{r}\right] \\
E_{i c}^{r}(\psi) & =\mathbb{E}\left[\log \left(\mathbb{P}\left(c_{i} \mid y_{i}, z_{i k}=1 ; \psi\right)\right) \mid y_{i}^{\text {obs }}, z_{i k}=1, c_{i} ; \theta^{r}, \psi^{r}\right] \\
\left(\tau_{i k}\right)^{r} & =\mathbb{P}\left(z_{i k}=1 \mid y_{i}^{\text {obs }}, c_{i} ; \theta^{r}, \psi^{r}, \pi^{r}\right) \propto \pi_{k}^{r} f_{k}\left(y_{i}^{\text {obs }} ; \theta_{k}^{r}\right) \mathbb{P}\left(c_{i} \mid y_{i}^{\text {obs }}, z_{i k}=1 ; \psi^{r}\right)
\end{aligned}
$$

## EM algorithm for MNARz and MNARz ${ }^{j}$

MNARz, MNARzj : needs some computations but still simple.

$$
\mathbb{P}\left(c_{i j}=1 \mid y_{i}, z_{i k}=1 ; \psi\right)=\rho\left(\alpha_{k j}\right) \quad \text { (independent of } y \text { ) }
$$

- Gaussian data: $\left(y_{i} \mid z_{i k}=1 ; \theta^{r}\right) \sim \mathcal{N}\left(\mu_{k}, \Sigma_{k}\right)$
- $\mathbb{P}\left(y_{i}^{\text {mis }} \mid y_{i}^{\text {obs }}, z_{i k}=1, c_{i} ; \theta^{r}, \psi^{r}\right)=\mathbb{P}\left(y_{i}^{\text {mis }} \mid y_{i}^{\text {obs }}, z_{i k}=1 ; \theta^{r}\right)$ using $(\Delta)$ and

$$
\left(y_{i}^{\text {mis }} \mid y_{i}^{\text {obs }}, z_{i k}=1 ; \theta^{r}\right) \sim \mathcal{N}\left(\left(\tilde{\mu}_{i k}^{\mathrm{mis}}\right)^{r},\left(\tilde{\Sigma}_{i k}^{\mathrm{mis}}\right)^{r}\right)
$$

where $\left(\tilde{\mu}_{i k}^{\text {mis }}\right)^{r}$ and $\left(\tilde{\Sigma}_{i k}^{\text {mis }}\right)^{r}$ only depend on $\mu_{k}^{r}, \Sigma^{r}$ and $y_{i}^{\text {obs }}$
$\Rightarrow E_{i y}^{r}(\theta)=\mathbb{E}\left[\log \left(f_{k}\left(y_{i} ; \theta_{k}\right)\right) \mid y_{i}^{\text {obs }}, z_{i k}=1, ; \theta^{r}\right]$ easy to compute (classical formulae)

- Using ( $\Delta$ )

$$
E_{i c}^{r}(\psi)=\log \left(\mathbb{P}\left(c_{i} \mid z_{i k}=1 ; \psi\right)\right)=\sum_{j=1}^{d} c_{i j} \log \rho\left(\alpha_{k j}\right)+\left(1-c_{i j}\right) \log \left(1-\rho\left(\alpha_{k j}\right)\right)
$$

- Using ( $\Delta$ )

$$
\left(\tau_{i k}\right)^{r} \propto \pi_{k}^{r} \phi\left(y_{i}^{\mathrm{obs}} ;\left(\mu_{i k}^{\mathrm{obs}}\right)^{r},\left(\sum_{i k}^{\mathrm{obs}, \mathrm{obs}}\right)^{r}\right) \prod_{j=1}^{d} \rho\left(\alpha_{k j}^{r}\right)^{c_{i j}}\left(1-\rho\left(\alpha_{k j}^{r}\right)\right)^{1-c_{i j}}
$$

## EM algorithm for MNARz and MNARz ${ }^{j}$

Recall that: $\left(y_{i}^{\mathrm{mis}} \mid y_{i}^{\text {obs }}, z_{i k}=1 ; \theta^{r}\right) \sim \mathcal{N}\left(\left(\tilde{\mu}_{i k}^{\mathrm{mis}}\right)^{r},\left(\tilde{\Sigma}_{i k}^{\mathrm{mis}}\right)^{r}\right)$.

- E-step: for $k=1, \ldots, K$ and $i=1, \ldots, n$, compute $\left(\tilde{\mu}_{i k}^{\text {mis }}\right)^{r},\left(\tilde{\Sigma}_{i k}^{\text {mis }}\right)^{r},\left(\tau_{i k}\right)^{r}$ and

$$
\left(\tilde{y}_{i, k}\right)^{r}=\left(y_{i}^{\text {obs }},\left(\tilde{\mu}_{i k}^{\text {mis }}\right)^{r}\right) \quad \tilde{\Sigma}_{i k}^{r}=\left(\begin{array}{cc}
0_{i}^{\text {obs }, \text { obs }} & 0_{i}^{\text {obs }, \text { mis }} \\
0_{i}^{\text {mis }, \text { obs }} & \left(\tilde{\Sigma}_{i k}^{\text {mis }}\right)^{r}
\end{array}\right)
$$

- M-step: for $k=1, \ldots, K$, compute

$$
\begin{aligned}
& \pi_{k}^{r+1}=\frac{1}{n} \sum_{i=1}^{n}\left(\tau_{i k}\right)^{r} \quad \mu_{k}^{r+1}=\frac{\sum_{i=1}^{n}\left(\tau_{i k}\right)^{r}\left(\tilde{y}_{k, i}\right)^{r}}{\sum_{i=1}^{n}\left(\tau_{i k}\right)^{r}} \\
& \Sigma_{k}^{r+1}=\frac{\left.\sum_{i=1}^{n}\left[\left(\tau_{i k}\right)^{r}\left(\left(\tilde{y}_{i, k}\right)^{r}-\mu_{k}^{r+1}\right)\left(\left(\tilde{y}_{i, k}\right)^{r}-\mu_{k}^{r+1}\right)^{T}+\tilde{\Sigma}_{i k}^{r}\right)\right]}{\sum_{i=1}^{n}\left(\tau_{i k}\right)^{r}}
\end{aligned}
$$

For $\psi^{r+1}$ : maximization of $Q_{c}\left(\psi ; \theta^{r}, \psi^{r}, \pi^{r}\right)$ over $\psi$ with a Newton-Raphson algorithm (classical procedure for link functions of interest)

An EM algorithm can also be easily derived for categorical data

## Not EM algorithm for MNARy*

MNARy*: needs approximations

$$
\mathbb{P}\left(c_{i j}=1 \mid y_{i}, z_{i k}=1 ; \psi\right)=\rho\left(\alpha_{k j}+\beta_{k j} y_{i j}\right) \quad(\text { not independent of } y)
$$

- Gaussian data:
- $\left(y_{i}^{\text {mis }} \mid y_{i}^{\text {obs }}, z_{i k}=1, c_{i}\right)$ :
$x$ not classical if $\rho$ is Logit, $\checkmark$ truncated Gaussian distribution if $\rho$ is Probit
- No closed form of $E_{i c}^{r}(\psi)$ neither for Probit nor for Logit:

$$
\begin{gathered}
E_{i c}^{r}(\psi)=\sum_{j=1}^{d} c_{i j} \int_{\mathcal{Y}_{i j}^{\text {mis }}} \log \left(\rho\left(\alpha_{k j}+\beta_{k j} y_{i j}^{\text {mis }}\right)\right) \frac{\rho\left(\alpha_{k j}^{r}+\beta_{k j}^{r} y_{j i}^{\text {mis }}\right)^{c_{i j}} \mathbb{P}\left(y_{i j}^{\text {mis }} \mid y_{i}^{\text {obs }}, z_{i k}=1 ; \theta^{r}\right)}{\int_{\mathcal{Y}_{i j}^{\text {mis }}} \rho\left(\alpha_{k j}^{r}+\beta_{k j}^{r x} x{ }^{c_{i j} \mathbb{P}}\left(x \mid y_{i}^{\text {obs }}, z_{i k}=1 ; \theta^{r}\right) d x\right.} d y_{i j}^{\text {mis }} \\
+\left(1-c_{i j}\right) \log \left(1-\rho\left(\alpha_{k j}+\beta_{k j} y_{i j}^{\text {obs }}\right)\right)
\end{gathered}
$$

$X$ not concave function if $\rho$ is Logit

- No closed form of $\left(\tau_{i k}\right)^{r}$ neither for Probit nor for Logit
- In the Gaussian case, there is no closed form [Pirjol, 2013]
- SEM easier? random drawing instead of expectation


## SEM algorithm for MNARy*

- SE-step: draw the missing data $\left(\left(y_{i}^{\text {mis }}\right)^{r+1}, z_{i}^{r+1}\right) \sim\left(. \mid y_{i}^{\text {obs }}, c_{i} ; \theta^{r}, \psi^{r}, \pi^{r}\right)$

Use of One-Gibbs sampling

- $\left(y_{i}^{\mathrm{mis}}\right)^{r+1} \sim\left(\cdot \mid y_{i}^{\text {obs }}, z_{i}^{r}, c_{i} ; \theta^{r}, \psi^{r}\right):$
$X$ not classical if $\rho$ is Logit, $\checkmark$ truncated Gaussian distribution if $\rho$ is Probit
- $z_{i}^{r+1} \sim\left(\cdot \mid y_{i}^{r+1}, c_{i} ; \theta^{r}, \psi^{r}, \pi^{r}\right)$ : draw the membership $k$ of $z_{i}^{r+1}$ from the multinomial distribution with probabilities

$$
\mathbb{P}\left(z_{i k}=1 \mid y_{i}^{r+1}, c_{i} ; \theta^{r}, \psi^{r}, \pi^{r}\right)=\frac{\mathbb{P}\left(c_{i} \mid y_{i}^{r+1}, z_{i k}=1 ; \psi^{r}\right) \mathbb{P}\left(y_{i}^{r+1} \mid z_{i k}=1 ; \theta^{r}\right) \pi_{k}^{r}}{\sum_{h=1}^{K} \mathbb{P}\left(c_{i} \mid y_{i}^{r+1}, z_{i h}=1 ; \psi^{r}\right) \mathbb{P}\left(y_{i}^{r+1} \mid z_{i h}=1 ; \theta^{r}\right) \pi_{h}^{r}}
$$

Let $Y^{r+1}=\left(y_{1}^{r+1}|\ldots| y_{n}^{r+1}\right), Z^{r+1}=\left(z_{1}^{r+1}|\ldots| z_{n}^{r+1}\right)$ be the imputed matrix and the partition

■ M-step: for $k=1, \ldots, K$, compute

- $\pi_{k}^{r+1}$ with the proportion of rows of $Y^{r+1}$ belonging to class $k$
- $\mu_{k}^{r+1}, \Sigma_{k}^{r+1}$ with the mean and covariance matrix of rows of $Y^{r+1}$ belonging to class k
- $\psi^{r+1}$ with a Newton-Raphson algorithm


## Summary for algorithms

|  | EM |  |  | SEM |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Gaussian |  | Categorical | Gaussian |  | Categorical |
| MNARz MNARz ${ }^{j}$ | $\checkmark$ |  | $\checkmark$ |  | $\checkmark$ | $\checkmark$ |
|  | Probit | Logit |  | Probit | Logit |  |
| MNARy* | no closed form | no closed form, optim. pb | not ident. | $\checkmark$ | require algorithms as SIR (costly) | not ident. |

## What about model selection?

Can select between MCAR and MNAR* with any information criterion (BIC, ICL)

Even if the missing mechanism is ignorable for MCAR. . .
... need to model $c$ to compare a MCAR and a MNAR model

## CAUTION

■ It is just a selection between several proposed MNAR models

- It is not deciding if missingness procedure is "genererically" MNAR or not


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## Hospital Data: continuous features case

- Number of patients: $n=5146$
- Number of features: $d=7$
- Age
- Size
- Weight
- Cardiac frequency
- Hemoglobin concentration
- Temperature
- Minimum Diastolic and Systolic Blood Pressure

■ Percentage of missing data: 6.4\%

## ICL comparison

ICL Comparison


- MCAR, MNARy and MNARz are equivalent until $K=3$

■ MNARz and MNARyz clearly indicate presence of an additional cluster $(K=4)$

It seems to be an illustation of the effect of $c$ through MNARz and MNARyz

## Missing Pattern



It seems that MNARz modelling leads to a missing free cluster

Hospital data: mixed features case

- Number of patients: $n=5146$
- Number of features: $d=15$ (7 continuous and 8 categorical)
- Percentage of missing data: $\sim 4 \%$


## Model

Conditional independence of the variables knowing the cluster

## ICL comparison



- MCAR and MNARz are equivalent
- MNARyz seems really inappropriate
- Seems to miss the previous latent structure: requires a specific exploration...

Exploration 1: local independence is not relevant for this data set


Not accounting for possible conditional dependencies between the continuous variables is inappropriate for this dataset.

## Exploration 2: mixture model bias vs missing model bias

A simulated data set with the following parameters:

- Mixture model: varying from diagonal to non diagonal hypotheses
- 2 clusters, dimension 7
- 5000 individuals
- $\pi_{1}=0.3, \pi_{2}=0.7, \mu_{1}=(0,0,0,0,0,0,0), \mu_{2}=(2,2,2,2,2,2,2)$
- Covariance matrices: $r \in\{1, \ldots, 10, \infty\}(r=\infty$ is the diagonal case)

$$
\Sigma_{k}^{(r)}=\left(\begin{array}{ccccccc}
1 & 0.5^{r} & 0.25^{r} & \ldots & . & . & . \\
0.5^{r} & 1 & 0.5^{r} & \ldots & . & . & . \\
0.25^{r} & 0.5^{r} & 1 & \ldots & . & . & . \\
\ldots & \ldots & \ldots & \ldots & \ldots & \ldots & \ldots \\
. & . & . & \ldots & 0.25^{r} & 0.5^{r} & 1
\end{array}\right)
$$

- Missingness model: MNAR hypothesis
- Proportions of missingness: 0.001 for cluster 1 and 0.06 for cluster 2


## Results from exploration 2



- The mixture model bias can not be compensated by the (unbiased) missing mechanism modeling
- It illustrates again the fact that information (on the latent partition) conveys by data is much more important than information conveys by the pattern


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Summary

- Interest to put a model on c
- Interest of the simple but meaningful model MNARz
- Link between our models and usual methods


## Ongoing works

- Deeper analysis of the previous results with doctors...
- Implement the proposed models/algo. in the Mixmod software ${ }^{a}$
- Address the trade-off between biased mixture model and biased missingness mechanism in particular for the mixed data case

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[^0]:    ${ }^{a}$ http://www.mixmod.org

