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# RITT OPERATORS AND CONVERGENCE IN THE METHOD OF ALTERNATING PROJECTIONS 

CATALIN BADEA AND DAVID SEIFERT


#### Abstract

Given $N \geq 2$ closed subspaces $M_{1}, \ldots, M_{N}$ of a Hilbert space $X$, let $P_{k}$ denote the orthogonal projection onto $M_{k}, 1 \leq k \leq N$. It is known that the sequence $\left(x_{n}\right)$, defined recursively by $x_{0}=x$ and $x_{n+1}=P_{N} \cdots P_{1} x_{n}$ for $n \geq 0$, converges in norm to $P_{M} x$ as $n \rightarrow \infty$ for all $x \in X$, where $P_{M}$ denotes the orthogonal projection onto $M=$ $M_{1} \cap \ldots \cap M_{N}$. Moreover, the rate of convergence is either exponentially fast for all $x \in X$ or as slow as one likes for appropriately chosen initial vectors $x \in X$. We give a new estimate in terms of natural geometric quantities on the rate of convergence in the case when it is known to be exponentially fast. More importantly, we then show that even when the rate of convergence is arbitrarily slow there exists, for each real number $\alpha>0$, a dense subset $X_{\alpha}$ of $X$ such that $\left\|x_{n}-P_{M} x\right\|=o\left(n^{-\alpha}\right)$ as $n \rightarrow \infty$ for all $x \in X_{\alpha}$. Furthermore, there exists another dense subset $X_{\infty}$ of $X$ such that, if $x \in X_{\infty}$, then $\left\|x_{n}-P_{M} x\right\|=o\left(n^{-\alpha}\right)$ as $n \rightarrow \infty$ for all $\alpha>0$. These latter results are obtained as consequences of general properties of Ritt operators. As a by-product, we also strengthen the unquantified convergence result by showing that $P_{M} x$ is in fact the limit of a series which converges unconditionally.


## 1. Introduction

The von Neumann-Halperin method of cyclic alternating projections is a general iterative method for finding the best approximation to any given point in a Hilbert space from the intersection of a finite number of closed subspaces. This method and its extensions and variants have been applied in a variety of fields, including solving linear equations, linear prediction theory, image restoration, computed tomography; see [20] for a survey.

The convergence of the algorithm given by the method of cyclic alternating projections in the case of several subspaces in a Hilbert space is based upon the following result. Given $N \geq 2$ closed subspaces $M_{1}, \ldots, M_{N}$ of a Hilbert space $X$, let $P_{k}$ denote the orthogonal projection onto $M_{k}$, $1 \leq k \leq N$, and let $P_{M}$ denote the orthogonal projection onto $M=$ $M_{1} \cap \ldots \cap M_{N}$. Consider the sequence $\left(x_{n}\right)$ defined recursively by $x_{0}=x \in X$ and $x_{n+1}=P_{N} \cdots P_{1} x_{n}$ for $n \geq 0$. We thus alternately project onto one

[^0]subspace, then onto the next one, in cyclic order. It is known that
\[

$$
\begin{equation*}
\lim _{n \rightarrow \infty}\left\|x_{n}-P_{M} x\right\|=0 \tag{1.1}
\end{equation*}
$$

\]

for all initial points $x \in X$. This was first shown for $N=2$ by J. von Neumann in 1933 and published in 50] and then for the general case in [30]; see also [43] for a simpler proof.

A question which arises naturally is whether anything can be said about the rate of convergence in (1.1). We say that the convergence is exponentially fast if there exist $r \in[0,1)$ and, for each $x \in X$, a constant $C_{x}>0$ such that

$$
\left\|x_{n}-P_{M} x\right\| \leq C_{x} r^{n}, \quad n \geq 0
$$

and we say that the convergence is arbitrarily slow if, given any sequence $\left(r_{n}\right)$ of positive real numbers satisfying $r_{n} \rightarrow 0$ as $n \rightarrow \infty$, there exists $x \in X$ such that

$$
\left\|x_{n}-P_{M} x\right\| \geq r_{n}, \quad n \geq 0
$$

By the uniform boundedness principle, exponentially fast convergence is equivalent to the existence of constants $C>0$ and $r \in[0,1)$ such that $\| T^{n}-$ $P_{M} \| \leq C r^{n}$ for all $n \geq 0$, where $T=P_{N} \cdots P_{1}$. In what follows, we shall also use the notions of exponentially fast and arbitrarily slow convergence more generally in cases such as the above, where the powers of an operator converge strongly to a limit.

It was shown in [7, Theorem 1.4] for the case $N=2$ and in [22, Theorem 6.4] for the general case that the convergence in (1.1) is exponentially fast if and only if the subspace $M_{1}^{\perp}+\cdots+M_{N}^{\perp}$ is closed in $X$, and that otherwise the convergence is arbitrarily slow. This dichotomy result, obtained independently in [3, 4, was extended in a number of directions in [4, for instance by giving characterisations of exponentially fast convergence in terms of the geometric relationship between the subspaces $M_{1}, \ldots M_{N}$. Other relevant sources include [6, 22, 23, 24, 52] and [21, Chapter 9].

Suppose that $M_{1}^{\perp}+\cdots+M_{N}^{\perp}$ is not closed in $X$ (for reasons which will become clear later on, we shall say in this case that the subspaces $M_{1}, \cdots, M_{N}$ are aligned). Therefore the convergence of $\left(x_{n}\right)$ can be slow for some initial points $x \in X$. For applications in approximation theory for instance it is vital to have some estimate on the rate of convergence in (1.1) for particular initial vectors $x \in X$; see for instance the discussion in [46, Section 4]. It is also natural to ask, in the case when the subspaces are aligned, where the initial points lie for which the convergence is arbitrarily slow. It was conjectured in [22, Remark 6.5(2)] that in general they must lie in the complement of $M \oplus\left(M_{1}^{\perp}+\cdots+M_{N}^{\perp}\right)$, which is a dense subspace of $X$. The principal purpose of this paper is to prove that even when the convergence in $(\overline{1.1)}$ is arbitrarily slow there exists, for each $\alpha>0$, a dense subspace $X_{\alpha}$ of $X$ such that

$$
\begin{equation*}
\left\|x_{n}-P_{M} x\right\|=o\left(n^{-\alpha}\right), \quad n \rightarrow \infty, \tag{1.2}
\end{equation*}
$$

for all $x \in X_{\alpha}$. We also show that there exists a further dense subspace $X_{\infty}$ of $X$ such that for all initial vectors $x \in X_{\infty}$ the statement in (1.2) holds for all $\alpha>0$. Although we give a fairly explicit description of these subspaces, the question raised in [22, Remark 6.5(2)] remains open.

Our results, presented in Theorem 4.3, are obtained by combining ideas contained in [4] with general results in operator theory arising from works such as [14, 31, 37], including in particular a characterisation of so-called unconditional Ritt operators in terms of the numerical range (field of values); see Theorem 2.2. As a by-product, we also strengthen the unquantified statement (1.1) itself by showing that the limit is in fact the limit of a series which converges unconditionally.

Organisation of the paper. In Section 2 we present some results on (unconditional) Ritt operators, together with a review of Ritt operators. Then in Section 3 we introduce a variant of a geometric quantity, called the inner $\ell^{2}$-inclination, which is related to the Friedrichs number from [3, 4]. We use this geometric quantity to estimate the rate of convergence in the method of alternating projections. This implies an inequality for $\left\|T-P_{M}\right\|$ in terms of some geometric quantities which, along with known results on Ritt operators, will be used in Section 4 to prove the main results of the paper.

Notation. The notation used is standard throughout. In particular, we write $X^{*}$ for the dual space of a complex Banach space $X$ and $\mathcal{B}(X)$ for the algebra of bounded linear operators on $X$. In what follows, all Banach spaces will implicitly be assumed to be complex. An operator $T \in \mathcal{B}(X)$ will be said to be power-bounded if $\sup _{n \geq 0}\left\|T^{n}\right\|<\infty$. Further, we write $\operatorname{Ran}(T)$ for the range of $T, \operatorname{Ker}(T)$ for its kernel and we let $\operatorname{Fix}(T)=\operatorname{Ker}(I-T)$ denote the set of fixed points of $T$. If $X$ is a Hilbert space with inner product $\langle\cdot, \cdot\rangle$ the adjoint operator of $T \in \mathcal{B}(X)$ will be denoted by $T^{*}$. We write $\sigma(T)$ for the spectrum of $T, r(T)$ for its spectral radius and, given $\lambda \in \mathbb{C} \backslash \sigma(T)$, we let $R(\lambda, T)$ denote the resolvent operator $(\lambda-T)^{-1}$. Given two sequences $\left(x_{n}\right)$, $\left(y_{n}\right)$ of non-negative real numbers, we write $x_{n}=O\left(y_{n}\right)$ as $n \rightarrow \infty$ if there exists a constant $C>0$ such that $x_{n} \leq C y_{n}$ for all sufficiently large $n \geq 0$. If $y_{n}>0$ for all sufficiently large $n \geq 0$, we write $x_{n}=o\left(y_{n}\right)$ as $n \rightarrow \infty$ if $x_{n} / y_{n} \rightarrow 0$ as $n \rightarrow \infty$. We write $\mathbb{T}$ for the unit circle $\{\lambda \in \mathbb{C}:|\lambda|=1\}$.

## 2. Ritt operators and unconditional Ritt operators

The aim of this section, partly expository, is to introduce the notions of Ritt operators and unconditional Ritt operators and to present some results about them. These results, some of which may be known to specialists in operator theory, will be crucial in dealing with products of projections in Section 4

An operator $T$ is said to be a Ritt operator if $r(T) \leq 1$ and there exists a constant $C>0$ such that

$$
\begin{equation*}
\|R(\lambda, T)\| \leq \frac{C}{|\lambda-1|}, \quad|\lambda|>1 \tag{2.1}
\end{equation*}
$$

This resolvent estimate, stronger than the Kreiss condition, took its name from [47]. It can be proved that any Ritt operator $T$ is power-bounded and satisfies $\left\|T^{n}(I-T)\right\|=O\left(n^{-1}\right)$ as $n \rightarrow \infty$, and the converse is also true; see for instance 42 and [39]. This estimate shows that Ritt operators are, in a certain sense, discrete analogues of analytic semigroups; see [12] where operators satisfying $\left\|T^{n}(I-T)\right\|=O\left(n^{-1}\right)$ as $n \rightarrow \infty$ are studied and called analytic operators. Moreover, (2.1) implies that $\sigma(T) \cap \mathbb{T} \subset\{1\}$, and it is
clear that if $T$ is a Ritt operator then so is any operator which is similar to $T$, that is to say any operator of the form $Q^{-1} T Q$ for some invertible operator $Q \in \mathcal{B}(X)$. Recall also that for any power-bounded operator $T$, the operator $I-T$ is sectorial of angle (of most) $\pi / 2$, so that the fractional powers $(I-T)^{\alpha}$ are well-defined for all $\alpha \geq 0$, either as a contour integral

$$
(I-T)^{\alpha}=\frac{1}{2 \pi \mathrm{i}} \oint_{\Gamma} \lambda^{\alpha} R(\lambda, I-T) \mathrm{d} \lambda
$$

where $\Gamma$ is any sufficiently smooth contour that contains the origin and otherwise encloses $\sigma(I-T)$ without touching it, or alternatively as the absolutely convergent series

$$
(I-T)^{\alpha}=\sum_{n=0}^{\infty}(-1)^{n}\binom{\alpha}{n} T^{n}
$$

See for instance [29] for details on sectorial operators and fractional powers.
An operator $T$ on a Banach space $X$ is said to be mean ergodic if the averages $\frac{1}{n+1} \sum_{k=0}^{n} T^{k} x, n \geq 0$, converge in norm to a limit as $n \rightarrow \infty$ for each $x \in X$. Details on mean ergodic operators may be found in [35, Section 2.1]. The next result characterises Ritt operators among all powerbounded mean ergodic operators on a Banach space in terms of decay of orbits; see [48, Remark 3.12] for a related result.

Theorem 2.1. Let $X$ be a Banach space and suppose that $T \in \mathcal{B}(X)$ is power-bounded and mean-ergodic. Then $T$ is a Ritt operator if and only if, for each $\alpha>0,\left\|T^{n} x\right\|=o\left(n^{-\alpha}\right)$ as $n \rightarrow \infty$ for all $x \in \operatorname{Ran}(I-T)^{\alpha}$.
Proof. By the uniform boundedness principle, the condition for $\alpha=1 \mathrm{im}-$ plies that $\left\|T^{n}(I-T)\right\|=O\left(n^{-1}\right)$ as $n \rightarrow \infty$. Since $T$ is assumed to be power-bounded, it follows that $T$ is a Ritt operator. The converse is proved in [11, Corollary 6.2] and [12, Proposition 2].

Following [31], an operator $T$ on a Banach space $X$ is said to satisfy the unconditional Ritt condition, or to be an unconditional Ritt operator, if there exists a constant $C>0$ such that, for any $n \geq 0$ and any $a_{0}, \ldots, a_{n} \in \mathbb{C}$,

$$
\begin{equation*}
\left\|\sum_{k=0}^{n} a_{k} T^{k}(I-T)\right\| \leq C \max _{0 \leq k \leq n}\left|a_{k}\right| \tag{2.2}
\end{equation*}
$$

Note that if $T$ satisfies the unconditional Ritt condition then so does any operator which is similar to $T$. Furthermore, it is straightforward to show that 2.2 is equivalent to having

$$
\begin{equation*}
\sum_{n=0}^{\infty}\left|\phi\left(T^{n}(I-T) x\right)\right| \leq C\|x\|\|\phi\| \tag{2.3}
\end{equation*}
$$

for all $x \in X, \phi \in X^{*}$, and it is shown in [31, Proposition 4.3] that if $T$ satisfies the unconditional Ritt condition $(2.2)$, then (2.1) holds, so $T$ is a Ritt operator. Theorem 2.2 below provides a characterisation of unconditional Ritt operators acting on a Hilbert space. Recall that the numerical range (or field of values) $W(T)$ of a bounded linear operator $T$ on a Hilbert space $X$ is defined as $W(T)=\{\langle T x, x\rangle: x \in X$ with $\|x\|=1\}$. Furthermore, given $\theta \in[0, \pi / 2)$, we write $S_{\theta}$ for the Stolz domain with half-angle $\theta$ at 1 ,
that is to say the convex hull of the set $\{\lambda \in \mathbb{C}:|\lambda| \leq \sin \theta\} \cup\{1\}$. Note that some authors reserve the term 'Stolz domain' for slightly different regions.

Theorem 2.2. Let $X$ be a Hilbert space and let $T \in \mathcal{B}(X)$. Then $T$ satisfies the unconditional Ritt condition if and only if $T$ is similar to an operator whose numerical range is contained in a Stolz domain.

Proof. Suppose first that there exists an invertible operator $Q \in \mathcal{B}(X)$ such that the operator $S=Q^{-1} T Q$ satisfies $W(S) \subset S_{\theta}$ for some $\theta \in[0, \pi / 2)$. Let $n \geq 0$ and $a_{1}, \ldots, a_{n} \in \mathbb{C}$ be given, and consider the polynomial $p_{n}$ defined by

$$
p_{n}(\lambda)=\sum_{k=0}^{n} a_{k} \lambda^{k}(1-\lambda), \quad \lambda \in \mathbb{C} .
$$

Then $p_{n}(1)=0$ and, for $|\lambda|<1$,

$$
\left|p_{n}(\lambda)\right| \leq \max _{0 \leq k \leq n}\left|a_{k}\right| \sum_{m \geq 0}|\lambda|^{m}|1-\lambda|=\frac{|1-\lambda|}{1-|\lambda|} \max _{0 \leq k \leq n}\left|a_{k}\right|
$$

Since $W(S) \subset S_{\theta}$, a simple estimate shows that

$$
\sup _{\lambda \in W(S)}\left|p_{n}(\lambda)\right| \leq C \max _{0 \leq k \leq n}\left|a_{k}\right|
$$

for some $C>0$ which is independent of $n \geq 0$ and $a_{1}, \ldots, a_{n} \in \mathbb{C}$. Hence

$$
\left\|p_{n}(S)\right\| \leq 12 C \max _{0 \leq k \leq n}\left|a_{k}\right|
$$

by [13, Theorem 2], so $S$ satisfies (2.2). Since $T$ is similar to $S, T$ itself satisfies the unconditional Ritt condition.

Now suppose conversely that $T$ satisfies the unconditional Ritt condition. Since the notions of 'boundedness' and ' $R$-boundedness' for families of operators coincide in the Hilbert space setting (see for instance [36, Section 1.9]), it follows from [37, Theorem 4.2] that $T$ admits a bounded $H^{\infty}$ functional calculus on $S_{\theta}$ for some $\theta \in[0, \pi / 2)$, which implies that there exists a constant $K \geq 1$ such that

$$
\|q(T)\| \leq K \sup _{\lambda \in S_{\theta}}|q(\lambda)|
$$

for all rational functions $q$ with poles outside $S_{\theta}$. Hence $S_{\theta}$ is a $K$-spectral set for $T$; see for instance [2] for details on (complete) $K$-spectral sets. Let $\theta^{\prime} \in(\theta, \pi / 2)$. By [26, Theorem 6.1] the set $S_{\theta^{\prime}}$ is a complete $K$-spectral set for $T$, and it follows from 44 that there exists an invertible operator $Q \in \mathcal{B}(X)$ such that $S_{\theta^{\prime}}$ is a complete 1-spectral set for $Q^{-1} T Q$. Since Stolz domains are convex, $S_{\theta^{\prime}}$ coincides with the intersection of all half-planes which are 1-spectral for $Q^{-1} T Q$. It follows easily from [51, Section 5.3] that any such half-plane contains the numerical range of $Q^{-1} T Q$, and hence $W\left(Q^{-1} T Q\right) \subset S_{\theta^{\prime}}$.

Remark 2.3. (a) The idea used in the first part of the above proof goes back to [14, Lemma 5.2], [17] and [37, Lemma 4.1]. Furthermore, noting that any operator on a Hilbert space admitting a 1-spectral set contained in the closed unit disc is a contraction, the above proof yields further equivalent conditions in Theorem 2.2, namely that $T$ is similar to a
contraction admitting a Stolz domain as a complete 1 -spectral set, that $T$ admits a Stolz domain as a (complete) $K$-spectral set for some $K \geq$ 1, and that $T$ admits a bounded $H^{\infty}$ functional calculus on a Stolz domain. From the latter it then follows by [40, Theorem 8.1] that these conditions are also equivalent to $T$ being similar to a contractive Ritt operator, and to $T$ being power-bounded and satisfying certain squarefunction estimates; see also [11, 31]. In particular, a contraction on a Hilbert space is a Ritt operator if and only if it is an unconditional Ritt operator. Several extensions to more general Banach spaces can be found for instance in [40]. We choose not to list these equivalent conditions in Theorem 2.2 since they will not be used in what follows.
(b) An alternative way to conclude the proof of Theorem 2.2, having established that $S_{\theta^{\prime}}$ is a complete 1-spectral set for $Q^{-1} T Q$, is as follows. By [1. Section 1.2] there exists a normal operator $S$ on a Hilbert space containing $X$ such that $\sigma(S)$ is contained in the boundary $\partial S_{\theta^{\prime}}$ of the Stolz domain; see also [45, Chapter 4]. Moreover, the closure of $W\left(Q^{-1} T Q\right)$ is contained in the closure of $W(S)$. Since for a normal operator the closure of the numerical range coincides with the convex hull of the spectrum (see for instance [27, Theorem 1.4-4]), it follows that $W\left(Q^{-1} T Q\right) \subset S_{\theta^{\prime}}$. This gives the additional equivalent statement that $T$ is similar to a contraction admitting a normal dilation whose spectrum is contained in the boundary of a Stolz domain. A direct construction of the normal dilation has been given in [15]. For further related results see also [16].

We now come to the main result of this section, Theorem 2.4 below. This requires a little preparation. Let $c_{0}$ denote the space of sequences $\left(a_{n}\right)$ of complex numbers such that $\left|a_{n}\right| \rightarrow 0$ as $n \rightarrow \infty$, endowed with the supremum norm. We say that a Banach space $X$ contains a copy of $c_{0}$ if there exists a closed subspace of $X$ which is isomorphic to $c_{0}$. Recall also that, given a sequence $\left(x_{n}\right)$ in $X$ and given $x \in X$, the formal series $\sum_{n \geq 0} x_{n}$ is said to be weakly unconditionally Cauchy if, for every $\phi \in X^{*}, \sum_{n \geq 0}\left|\phi\left(x_{n}\right)\right|<\infty$. Furthermore, the series $\sum_{n \geq 0} x_{n}$ is said to converge unconditionally to $x$ if the series $\sum_{n \geq 0} x_{\pi(n)}$ converges to $x$ in the usual sense for all permutations $\pi$ of $\mathbb{Z}_{+}$. The series $\sum_{n \geq 0} x_{n}$ is said to be unconditionally convergent if it converges unconditionally to some $x \in X$. The following theorem, then, is a general dichotomy result, which will be applied in the form of Corollary 2.6 to iterated projections in Section 4 . Given a sequence $\left(r_{n}\right)$ of non-negative numbers such that $r_{n} \rightarrow 0$ as $n \rightarrow \infty$, we say that the convergence is superpolynomially fast if $r_{n}=o\left(n^{-\alpha}\right)$ as $n \rightarrow \infty$ for all $\alpha>0$.

Theorem 2.4. Let $X$ be a Banach space which does not contain a copy of $c_{0}$, and suppose that $T \in \mathcal{B}(X)$ satisfies the unconditional Ritt condition. Then the space $X$ splits as $X=\operatorname{Fix}(T) \oplus Z$, where $Z$ is the closure of $\operatorname{Ran}(I-T)$, and the series $\sum_{n \geq 0} T^{n}(I-T) x$ converges unconditionally to $x-P x$ for all $x \in X$, where $P$ is the bounded projection onto $\operatorname{Fix}(T)$ along Z. In particular,

$$
\begin{equation*}
\lim _{n \rightarrow \infty}\left\|T^{n} x-P x\right\|=0 \tag{2.4}
\end{equation*}
$$

for all $x \in X$. Moreover, if $\operatorname{Ran}(I-T)$ is closed then the convergence is exponentially fast for all $x \in X$, while if $\operatorname{Ran}(I-T)$ is not closed the convergence is arbitrarily slow but for each $\alpha>0$ there exists a dense subspace $X_{\alpha}$ of $X$ such that

$$
\begin{equation*}
\left\|T^{n} x-P x\right\|=o\left(n^{-\alpha}\right), \quad n \rightarrow \infty, \tag{2.5}
\end{equation*}
$$

for all $x \in X_{\alpha}$. Furthermore, there exists a dense subspace $X_{\infty}$ of $X$ such that for all $x \in X_{\infty}$ the convergence in (2.4) is super-polynomially fast.

Proof. Since $T$ is an unconditional Ritt operator, (2.3) holds for all $x \in X$ and all $\phi \in X^{*}$. Thus the series $\sum_{n \geq 0} T^{n}(I-T) x$ is weakly unconditionally Cauchy for each $x \in X$. Since $X$ contains no copy of $c_{0}$, it follows from the Bessaga-Pełczyński theorem [8, Theorem 5] that the series converges unconditionally to some $z \in Z$. Noting that the partial sums of the series form a telescoping sum, it follows immediately that $\left\|T^{n} x-x+z\right\| \rightarrow 0$ as $n \rightarrow \infty$. Next we identify $z \in Z$. Since the powers of $T$ converge strongly to a limit, $T$ is mean ergodic. It follows from power-boundedness of $T$ and [35, Chapter 2, Theorem 1.3] that $X=\operatorname{Fix}(T) \oplus Z$. By virtue of $T$ being a Ritt operator we have that $\left\|T^{n}(I-T)\right\| \rightarrow 0$ as $n \rightarrow \infty$. In particular, $\left\|T^{n} x\right\| \rightarrow 0$ as $n \rightarrow \infty$ for all $x \in Y$, and by the power-boundedness of $T$ this result extends to all $x \in Z$. It follows that (2.4) holds and hence that $z=x-P x$, as required.

It remains to prove the quantified statements. Let $Y=\operatorname{Ran}(I-T)$, so that $Z$ is the closure of $Y$, and let $S$ denote the restriction of $T$ to $Z$. Then $\sigma(S) \subset \sigma(T)$ and the operator $I-S$ maps $Z$ bijectively onto $Y$. It follows from the Inverse Mapping Theorem that $1 \in \sigma(S)$ if and only if $Y \neq Z$. Using the fact that $\sigma(T)$ is contained in the closed unit disc with $\sigma(T) \cap \mathbb{T} \subset\{1\}$, we obtain the equivalent statement that $r(S)<1$ if and only if $Y$ is closed. But $\left\|T^{n}-P\right\|=\left\|S^{n}\right\|$ for all $n \geq 0$, so if $Y$ is closed then the convergence in (2.4) is exponentially fast. On the other hand, if $Y$ is not closed and consequently $r(S)=1$, then it follows from [41, Theorem 1] that, given any sequence ( $r_{n}$ ) of positive terms satisfying $r_{n} \rightarrow 0$ as $n \rightarrow \infty$, there exists $x \in Z$ such that $\left\|S^{n} x\right\| \geq r_{n}$ for all $n \geq 0$. Since $S^{n} x=T^{n} x-P_{M} x$ for all $n \geq 0$, the convergence in (2.4) is arbitrarily slow. Given $\alpha>0$, let $X_{\alpha}=\operatorname{Fix}(T) \oplus \operatorname{Ran}(I-T)^{\alpha}$. Since $\operatorname{Ran}(I-T)^{\alpha}$ is dense in $Z$ and $X=\operatorname{Fix}(T) \oplus Z, X_{\alpha}$ is dense in $X$. For $x \in X_{\alpha}$, let $y=x-P x$. Then $y \in \operatorname{Ran}(I-T)^{\alpha}$ and $T^{n} x-P x=T^{n} y$ for all $n \geq 0$. Since $T$ is mean ergodic, (2.5) follows from Theorem 2.1. For the final claim, let $X_{\infty}=\bigcap_{n=1}^{\infty} X_{n}$. It follows from the Esterle-Mittag-Leffler theorem [25, Theorem 2.1] that $X_{\infty}$ is dense in $X$, and it is clear that for initial vectors $x \in X_{\infty}$ the convergence in (2.4) is super-polynomially fast. This completes the proof.

Remark 2.5. (a) As the above proof shows, the dense subspaces $X_{\alpha}$ for $\alpha>0$ are given by $X_{\alpha}=\operatorname{Fix}(T) \oplus \operatorname{Ran}(I-T)^{\alpha}$. Thus it is possible at least in principle to verify whether a given initial vector leads to convergence of a particular polynomial rate. For characterisations of the spaces $\operatorname{Ran}(I-T)^{\alpha}$ for $0<\alpha \leq 1$, see [18, Section 2], [29, Theorem 6.1] and [38. In particular, if $X$ is reflexive then $x \in \operatorname{Ran}(I-T)^{\alpha}$ if and
only if

$$
\sup _{n \geq 1}\left\|\sum_{k=1}^{n} k^{-(1-\alpha)} T^{k} x\right\|<\infty
$$

Note also that by [18, Theorem 2.23] we have that $\bigcup_{0<\alpha<1} \operatorname{Ran}(I-T)^{\alpha}$ is strictly contained in the closure of $\operatorname{Ran}(I-T)$ whenever the latter is not closed.
(b) In showing that the convergence in 2.4 is arbitrarily slow when $\operatorname{Ran}(I-$ $T$ ) is not closed, [41, Theorem 1] in fact yields the stronger statement that, given any $\varepsilon>0$, the vector $x \in Z$ in the above proof can be chosen so as to satisfy $\|x\|<(1+\varepsilon) \sup _{n \geq 0} r_{n}$. See [4] for various other notions of arbitrarily slow convergence which could equally have been used.
(c) The rate $n^{-\alpha}$ in 2.5 is optimal in the sense that if the convergence were any faster for all $x \in X_{\alpha}$, with $X_{\alpha}$ as in the above proof, then the convergence in (4.2) would necessarily be exponentially fast. This follows from [48, Theorem 2.1] combined with the uniform boundedness principle and the moment inequality; see for instance [28, Corollary 7.2]. It follows in particular that the spaces $X_{\alpha}$ are distinct for distinct values of $\alpha>0$ when $\operatorname{Ran}(I-T)$ is not closed; see also [18, Proposition 2.2].

Note that any reflexive space, and particular any Hilbert space, cannot contain a copy of $c_{0}$. Hence combining Theorem 2.4 with Theorem 2.2 immediately leads to the following.

Corollary 2.6. Let $X$ be a Hilbert space and suppose that $T \in \mathcal{B}(X)$ is similar to an operator whose numerical range is contained in a Stolz domain. Then the conclusions of Theorem 2.4 hold.

## 3. INNER INCLINATIONS AND RATES OF CONVERGENCE

The aim in this section is to introduce various quantities describing the geometric relationship between subspaces of a Hilbert space and to understand the connections between these quantities. These quantities will then be used to study the rate of convergence in the method of alternating projections. Throughout this section, we let $X$ be a Hilbert space and we consider a collection of $N \geq 2$ closed subspaces $M_{1}, \ldots, M_{N}$ of $X$. In order to avoid having to distinguish cases, we exclude the uninteresting situation in which all of the subspaces coincide with $X$. Furthermore, we let $M=M_{1} \cap \ldots \cap M_{N}$ and, for $1 \leq k \leq N$, we write $P_{k}$ for the orthogonal projection onto $M_{k}$. We also write $P_{M}$ for the orthogonal projection onto $M$ and we let $T \in \mathcal{B}(X)$ be the operator $T=P_{N} \cdots P_{1}$.

The first quantity we consider, which was introduced in [3, 4], is the Friedrichs number $c\left(M_{1}, \ldots, M_{N}\right)$,

$$
\begin{aligned}
& c\left(M_{1}, \ldots, M_{N}\right)=\sup \left\{\frac{1}{N-1} \sum_{j \neq k}\left\langle m_{j}, m_{k}\right\rangle: m_{k} \in M_{k} \cap M^{\perp}\right. \text { for } \\
& \left.1 \leq k \leq N,\left\|m_{1}\right\|^{2}+\cdots+\left\|m_{N}\right\|^{2}=1\right\}
\end{aligned}
$$

The Friedrichs number can be interpreted as the cosine of the 'angle' between the subspaces $M_{1}, \ldots, M_{N}$. It is well-known from [20, 33] that when $N=2$
the norm $\left\|T^{n}-P_{M}\right\|$ can be nicely expressed in terms of the Friedrichs number as

$$
\left\|T^{n}-P_{M}\right\|=c\left(M_{1}, M_{2}\right)^{2 n-1}, \quad n \geq 1
$$

In the case of more than two subspaces, it is possible to write down certain expressions for $\left\|T^{n}-P_{M}\right\|, n \geq 0$, as for instance in [52, Theorem 4.5], but no exact formula in terms of the Friedrichs number is known. However, it is possible to obtain bounds on these norms in terms of closely related geometric quantities, which can then be used to obtain estimates in terms of the Friedrichs number.

Following [46], we define the inner inclination of the subspaces $M_{1}, \ldots, M_{N}$ as

$$
\iota\left(M_{1}, \ldots, M_{N}\right)=\min _{1 \leq n \leq N} \inf _{x \in M_{n} \backslash M} \max _{1 \leq k \leq N} \frac{\operatorname{dist}\left(x, M_{k}\right)}{\operatorname{dist}(x, M)} .
$$

The inner inclination is closely related to the inclination

$$
\ell\left(M_{1}, \ldots, M_{N}\right)=\inf _{x \notin M} \max _{1 \leq k \leq N} \frac{\operatorname{dist}\left(x, M_{k}\right)}{\operatorname{dist}(x, M)}
$$

of the subspaces $M_{1}, \ldots, M_{N}$ which is studied in [4]. Indeed, it was proved in [4, Proposition 3.9] that

$$
\ell\left(M_{1}, \ldots, M_{N}\right) \leq(N-1)^{1 / 2}\left(1-c\left(M_{1}, \ldots, M_{N}\right)\right)^{1 / 2}
$$

and that

$$
\begin{equation*}
\ell\left(M_{1}, \ldots, M_{N}\right) \geq \frac{(N-1)}{2 N}\left(1-c\left(M_{1}, \ldots, M_{N}\right)\right) \tag{3.1}
\end{equation*}
$$

It also follows from the definitions that

$$
\begin{equation*}
\iota\left(M_{1}, \ldots, M_{N}\right) \geq \ell\left(M_{1}, \ldots, M_{N}\right) \tag{3.2}
\end{equation*}
$$

and it follows from [4] and [46] that $\iota\left(M_{1}, \ldots, M_{N}\right)=0$ if and only if $\ell\left(M_{1}, \ldots, M_{N}\right)=0$, which in turn is equivalent to $c\left(M_{1}, \ldots, M_{N}\right)=1$ (the 'angle' is zero) and to $M_{1}^{\perp}+\cdots+M_{N}^{\perp}$ not being closed in $X$. When these equivalent conditions are satisfied, we shall say that the subspaces $M_{1}, \ldots, M_{N}$ are aligned.

Consider the quantity

$$
\ell_{2}\left(M_{1}, \ldots, M_{N}\right)=\left(\inf _{x \notin M} \frac{\sum_{k=1}^{N} \operatorname{dist}\left(x, M_{k}\right)^{2}}{\operatorname{dist}(x, M)^{2}}\right)^{1 / 2}
$$

which was considered in 32 and which we shall call the $\ell^{2}$-inclination of the subspaces $M_{1}, \ldots, M_{N}$. Thus $\ell_{2}\left(M_{1}, \ldots, M_{N}\right)$ is the smallest constant $C \geq 0$ such that the inequality

$$
\sum_{k=1}^{N} \operatorname{dist}\left(x, M_{k}\right)^{2} \geq C^{2} \operatorname{dist}(x, M)^{2}
$$

holds for all vectors $x \in X$. It follows from [32, Remark 3.25] that we have

$$
\begin{equation*}
\ell_{2}\left(M_{1}, \ldots, M_{N}\right)=(N-1)^{1 / 2}\left(1-c\left(M_{1}, \ldots, M_{N}\right)\right)^{1 / 2} \tag{3.3}
\end{equation*}
$$

In particular, $\ell_{2}\left(M_{1}, \ldots, M_{N}\right)=0$ if and only if the subspaces $M_{1}, \ldots, M_{N}$ are aligned. We define the inner $\ell^{2}$-inclination of the subspaces $M_{1}, \ldots, M_{N}$ by

$$
\iota_{2}\left(M_{1}, \ldots, M_{N}\right)=\left(\min _{1 \leq n \leq N} \inf _{x \in M_{n} \backslash M} \frac{\sum_{k=1}^{N} \operatorname{dist}\left(x, M_{k}\right)^{2}}{\operatorname{dist}(x, M)^{2}}\right)^{1 / 2} .
$$

Thus $\iota_{2}$ is the smallest constant $C \geq 0$ such that the inequality

$$
\sum_{k=1}^{N} \operatorname{dist}\left(x, M_{k}\right)^{2} \geq C^{2} \operatorname{dist}(x, M)^{2}
$$

holds for all vectors $x \in M_{1} \cup \ldots \cup M_{N}$. It follows that

$$
\begin{equation*}
\iota_{2}\left(M_{1}, \ldots, M_{N}\right) \geq \ell_{2}\left(M_{1}, \ldots, M_{N}\right) . \tag{3.4}
\end{equation*}
$$

Remark 3.1. Note that it would be possible to develop the notion of an (inner) $\ell^{p}$-inclination for any $p$ with $1 \leq p \leq \infty$. The usual (inner) inclination would then correspond to taking $p=\infty$. We restrict ourselves here to the choice $p=2$ since this seems the most natural in the Hilbert space setting and since the the $\ell^{2}$-inclination can be expressed exactly in terms of the Friedrichs number by means of (3.3); see also Remark 3.5 below.

We now establish an estimate for the error $\left\|T^{n} x-P_{M} x\right\|$, where $x \in X$ and $n \geq 0$, first in terms of the inner $\ell^{2}$-inclination and then, in Corollary 3.4, in terms of the Friedrichs number of the subspaces $M_{1}, \ldots M_{N}$. We begin by recalling a result proved in [4, Lemma 4.2.].

Lemma 3.2. Given $N \geq 2$ closed subspaces $M_{1}, \ldots, M_{N}$ of a Hilbert space $X$, let $P_{k}$ denote the orthogonal projection onto $M_{k}, 1 \leq k \leq N$. Furthermore, let $P_{M}$ denote the orthogonal projection onto $M=M_{1} \cap \ldots \cap M_{N}$ and let $T=P_{N} \cdots P_{1}$. Fix $x \in X$, and set $u_{0}=x-P_{M} x$ and, for $1 \leq k \leq N$, $u_{k}=P_{k} \cdots P_{1} x-P_{M} x$. Then

$$
\left\|u_{k-1}-u_{k}\right\|^{2} \leq\left\|x-P_{M} x\right\|^{2}-\left\|T x-P_{M} x\right\|^{2}, \quad 1 \leq k \leq N .
$$

The proof of the next theorem is similar to a part of [4, Theorem 4.1] using an improvement of [46, Theorem 2.4].

Theorem 3.3. Consider the setting of Lemma 3.2. Then, given $x \in X$,

$$
\left\|T^{n} x-P_{M} x\right\| \leq\left(1-\frac{3 \iota_{2}^{2}}{N^{3}}\right)^{n / 2}\left\|x-P_{M} x\right\|, \quad n \geq 0
$$

where $\iota_{2}=\iota_{2}\left(M_{1}, \ldots, M_{N}\right)$.
Proof. We begin by establishing an estimate for $\left\|T x-P_{M} x\right\|$. Let $x \in M_{1}$. Then $\operatorname{dist}\left(x, M_{1}\right)=0$. For $2 \leq k \leq N$, keeping in mind that $x=P_{1} x$ and using the notation of Lemma 3.2, we have that

$$
\operatorname{dist}\left(x, M_{k}\right)=\left\|x-P_{k} x\right\| \leq\left\|P_{1} x-P_{k} P_{k-1} \cdots P_{1} x\right\|=\left\|u_{1}-u_{k}\right\|
$$

and hence

$$
\operatorname{dist}\left(x, M_{k}\right) \leq \sum_{j=2}^{k}\left\|u_{j-1}-u_{j}\right\|
$$

Using Lemma 3.2 and the Cauchy-Schwarz inequality we obtain

$$
\operatorname{dist}\left(x, M_{k}\right)^{2} \leq(k-1)^{2}\left(\left\|x-P_{M} x\right\|^{2}-\left\|T x-P_{M} x\right\|^{2}\right)
$$

and therefore

$$
\sum_{k=1}^{N} \operatorname{dist}\left(x, M_{k}\right)^{2} \leq \frac{N^{3}}{3}\left(\left\|x-P_{M} x\right\|^{2}-\left\|T x-P_{M} x\right\|^{2}\right)
$$

Since by definition of the inner $\ell^{2}$-inclination

$$
\sum_{k=1}^{N} \operatorname{dist}\left(x, M_{k}\right)^{2} \geq \iota_{2}^{2}\left\|x-P_{M} x\right\|^{2}
$$

for all $x \in M_{1}$, we obtain

$$
\iota_{2}^{2}\left\|x-P_{M} x\right\|^{2} \leq \frac{N^{3}}{3}\left(\left\|x-P_{M} x\right\|^{2}-\left\|T x-P_{M} x\right\|^{2}\right)
$$

and hence

$$
\begin{equation*}
\left\|T x-P_{M} x\right\| \leq\left(1-\frac{3 c_{2}^{2}}{N^{3}}\right)^{1 / 2}\left\|x-P_{M} x\right\| \tag{3.5}
\end{equation*}
$$

for all $x \in M_{1}$. Now let $x$ be an arbitrary element of $X$. We apply (3.5) with $x$ replaced by $y=P_{1} x$, which is an element of $M_{1}$. We have $P_{1} y=y=P_{1} x$ and $P_{M} y=P_{M} P_{1} x=P_{M} x$. Hence

$$
\left\|T x-P_{M} x\right\|=\left\|P_{N} \cdots P_{1} y-P_{M} y\right\| \leq\left(1-\frac{3 \iota_{2}^{2}}{N^{3}}\right)^{1 / 2}\left\|y-P_{M} y\right\|
$$

Now observe that

$$
\left\|y-P_{M} y\right\|=\left\|P_{1} x-P_{1} P_{M} x\right\| \leq\left\|x-P_{M} x\right\|
$$

and thus the desired inequality, with $n=1$, holds for arbitrary $x \in X$. For $n \geq 2$, notice that $T P_{M} x=P_{M} T x=P_{M} x$. Thus we can write $T^{n} x-P_{M} x=$ $T\left(T^{n-1} x\right)-P_{M}\left(T^{n-1} x\right)$. By iteration, we obtain

$$
\left\|T^{n} x-P_{M} x\right\| \leq\left(1-\frac{3 \iota_{2}^{2}}{N^{3}}\right)^{n / 2}\left\|x-P_{M} x\right\|
$$

for $n \geq 2$ and hence for all $n \geq 0$, as required.
Theorem 3.3 shows that the convergence in (1.1) is exponentially fast whenever $\iota_{2}\left(M_{1}, \ldots, M_{N}\right)>0$. By [4, Theorem 4.1] exponentially fast convergence is equivalent to having $c\left(M_{1}, \ldots, M_{N}\right)<1$, and hence (3.3) and (3.4) together show that $\iota_{2}\left(M_{1}, \ldots, M_{N}\right)=0$ if and only if the spaces $M_{1}, \ldots, M_{N}$ are aligned. The following corollary is also another simple consequence of Theorem 3.3 and the statements in (3.3) and (3.4).

Corollary 3.4. Consider the setting of Lemma 3.2. Then, given $x \in X$,

$$
\begin{equation*}
\left\|T^{n} x-P_{M} x\right\| \leq\left(1-\frac{3(N-1)}{N^{3}}(1-c)\right)^{n / 2}\left\|x-P_{M} x\right\|, \quad n \geq 0 \tag{3.6}
\end{equation*}
$$

where $c=c\left(M_{1}, \ldots, M_{N}\right)$.

Remark 3.5. It follows from [46, Theorem 2.4] that, for all $x \in X$,

$$
\left\|T^{n} x-P_{M} x\right\| \leq\left(1-\frac{\iota^{2}}{(N-1)^{2}}\right)^{n / 2}\left\|x-P_{M} x\right\|, \quad n \geq 0
$$

where $\iota=\iota\left(M_{1}, \ldots, M_{N}\right)$. Using (3.1) and (3.2) it is possible to deduce a bound involving only the Friedrichs number. However, resulting estimate is always worse than (3.6).

## 4. Convergence in the method of alternating projections

Suppose as in Section 3 that $M_{1}, \ldots, M_{N}$ are $N \geq 2$ closed subspaces of a Hilbert space $X$ and, for $1 \leq k \leq N$, write $P_{k}$ for the orthogonal projection onto $M_{k}$. It is shown in [14, Lemma 5.1] that the numerical range $W(T)$ of the product $T=P_{N} \cdots P_{1}$ satisfies $W(T) \subset \Omega_{N}$, where

$$
\begin{equation*}
\Omega_{N}=\left\{\lambda \in \mathbb{C}:\left|\lambda-2^{-N}\right| \leq 1-2^{-N} \text { and }|\arg (1-\lambda)| \leq \theta_{N}\right\} \tag{4.1}
\end{equation*}
$$

and the angle $\theta_{N} \in(0, \pi / 2)$ is defined recursively by $\theta_{1}=0$ and

$$
\theta_{n+1}=\tan ^{-1}\left(\frac{2 \tan \theta_{n}}{1+2^{-n}}+\left(\frac{1-2^{-n}}{1+2^{-n}}\right)^{1 / 2}\right), \quad 1 \leq n<N
$$

Proposition 4.1 below shows that $W(T)$ is also contained in a certain Stolz domain whose opening angle is determined by the geometric relationship between the subspaces $M_{1}, \ldots, M_{N}$.

Proposition 4.1. Given $N \geq 2$ closed subspaces $M_{1}, \ldots, M_{N}$ of a Hilbert space $X$ with $M_{1} \cap \ldots \cap M_{N} \neq X$, let $P_{k}$ denote the orthogonal projection onto $M_{k}, 1 \leq k \leq N$. Furthermore let $T=P_{N} \cdots P_{1}$. Then $W(T) \subset \Omega_{N} \cap S_{\theta_{0}}$, where $\Omega_{N}$ is defined by (4.1) and

$$
\sin \theta_{0}=\left(1-\frac{3(N-1)}{N^{3}}(1-c)\right)^{1 / 2}
$$

with $c=c\left(M_{1}, \ldots, M_{N}\right)$. In particular, $W(T) \subset S_{\theta}$ for all sufficiently large $\theta \in[0, \pi / 2)$.

Proof. Let $Z$ denote the closure of $\operatorname{Ran}(I-T)$. Then $Z^{\perp}=\operatorname{Fix}\left(T^{*}\right)$. Since $T^{*}=P_{1} \cdots P_{N}$, a simple argument shows that $\operatorname{Fix}\left(T^{*}\right)=\operatorname{Fix}(T)=M$, where $M=M_{1} \cap \ldots \cap M_{N}$. Hence $X=M \oplus Z$. Let $S$ denote the restriction of $T$ to $Z$. Then $W(T)$ is the convex hull of $W(S) \cup\{1\}$. Now using the estimate for $\|S\|=\left\|T-P_{M}\right\|$ implied by Corollary 3.4 we obtain $W(S) \subset$ $\left\{\lambda \in \mathbb{C}:|\lambda| \leq \sin \theta_{0}\right\}$. Hence $W(T) \subset \Omega_{N} \cap S_{\theta_{0}}$, as required. The final claim follows from the fact that $\Omega_{N} \cap S_{\theta_{0}} \subset S_{\theta}$ for all sufficiently large $\theta \in[0, \pi / 2)$.
Remark 4.2. (a) The result shows that $W(T)$ is contained in a Stolz domain whose half-angle is determined by the Friedrichs number. For $N=2$, [34, Proposition 1.5] shows that

$$
W(T) \subset\left\{\lambda \in \mathbb{C}:|\arg (1-\lambda)| \leq \tan ^{-1}\left(c\left(4-c^{2}\right)^{-1 / 2}\right)\right\}
$$

where $c=c\left(M_{1}, M_{2}\right)$. This gives a slightly sharper estimate on the angle of the Stolz domain than Proposition 4.1. Note also that by using Theorem 3.3 instead of Corollary 3.4 in the above proof, it is possible
to obtain a slightly sharper bound on the angle $\theta_{0}$ involving the inner $\ell^{2}$-inclination rather than the Friedrichs number.
(b) Combining Proposition 4.1 with Theorem 2.2 shows that the operator $T=P_{N} \cdots P_{1}$ satisfies the unconditional Ritt condition and in particular is a Ritt operator. The latter assertion was first proved in [10, Proposition 2.2] for conditional expectations; see also [11, Proposition 2.3]. A more direct way of showing that $T$ is a Ritt operator is to note that by [49, Theorem 4.20] we have

$$
\|R(\lambda, T)\| \leq \frac{1}{\operatorname{dist}(\lambda, W(T))}
$$

for all $\lambda \in \mathbb{C}$ outside the closure of $W(T)$. Since $W(T)$ is contained in a Stolz domain, a simple estimate establishes (2.1). Note in particular that better knowledge of the location of $W(T)$ leads to sharper estimates on the constant $C$ appearing in (2.1). See [9] for various related results.
(c) Note that if $T$ is a convex combination of operators whose numerical ranges lie in Stolz domains then $W(T)$ also lies in a Stolz domain. Thus the last part of Proposition 4.1 extends straightforwardly to operators $T$ which are convex combinations of finite products of orthogonal projections on a Hilbert space, operators which were studied in [5]. In particular, such operators satisfy the unconditional Ritt condition by Theorem 2.2.

We now come to the main result of this paper, which is a restatement of parts of the dichotomy result [4, Theorem 4.1] but with two important additions. Specifically, the result gives an improved estimate in terms of the Friedrichs number on the actual rate of convergence in (1.1) in the case where it is known to be exponentially fast, and it also shows that, even when the convergence in (1.1) is arbitrarily slow, there exists, for each $\alpha>0$, a rich supply of initial vectors for which the error decays like $o\left(n^{-\alpha}\right)$ as $n \rightarrow \infty$. By showing that the initial vectors leading to very slow decay in (1.1) must therefore come from the complement of a certain dense subspace of $X$, the result provides a partial answer to a question raised in [22, Remark 6.5(2)], where it is conjectured that such initial vectors in general must be chosen from outside $M \oplus\left(M_{1}^{\perp}+\cdots+M_{N}^{\perp}\right)$, which itself is a dense subspace of $X$. The result moreover shows that there exists a further dense subset $X_{\infty}$ of $X$ such that for $x \in X_{\infty}$ the decay is super-polynomially fast in the sense of Section 3. Finally, the result also strengthens the unquantified statement (1.1) by relating it to the convergence of a certain series which is unconditionally convergent.

Theorem 4.3. Given $N \geq 2$ closed subspaces $M_{1}, \ldots, M_{N}$ of a Hilbert space $X$, let $P_{k}$ denote the orthogonal projection onto $M_{k}, 1 \leq k \leq N$. Furthermore, let $P_{M}$ denote the orthogonal projection onto $M=M_{1} \cap \ldots \cap$ $M_{N}$, and assume that $M \neq X$. If the sequence $\left(x_{n}\right)$ is defined recursively by $x_{0}=x$ and $x_{n+1}=P_{N} \cdots P_{1} x_{n}$ for $n \geq 0$, then the series $\sum_{n \geq 0}\left(x_{n}-x_{n+1}\right)$ converges unconditionally to $x-P_{M} x$ for all $x \in X$. In particular,

$$
\begin{equation*}
\lim _{n \rightarrow \infty}\left\|x_{n}-P_{M} x\right\|=0 \tag{4.2}
\end{equation*}
$$

for all $x \in X$. If the subspaces $M_{1}, \ldots, M_{N}$ are not aligned, then the convergence is exponentially fast and in fact

$$
\begin{equation*}
\left\|x_{n}-P_{M} x\right\| \leq\left(1-\frac{3(N-1)}{N^{3}}(1-c)\right)^{n / 2}\left\|x-P_{M} x\right\|, \quad n \geq 0 \tag{4.3}
\end{equation*}
$$

for all $x \in X$, where $c=c\left(M_{1}, \ldots, M_{N}\right)$. On the other hand, if the subspaces $M_{1}, \ldots, M_{N}$ are aligned, then the convergence is arbitrarily slow but for each $\alpha>0$ there exists a dense subspace $X_{\alpha}$ of $X$ such that

$$
\left\|x_{n}-P_{M} x\right\|=o\left(n^{-\alpha}\right), \quad n \rightarrow \infty,
$$

for all $x \in X_{\alpha}$. Furthermore, there exists a dense subspace $X_{\infty}$ of $X$ such that for all $x \in X_{\infty}$ the convergence in (4.2) is super-polynomially fast.

Proof. Let $T \in \mathcal{B}(X)$ be given by $T=P_{N} \cdots P_{1}$, so that $x_{n}=T^{n} x$ for all $n \geq 0$. By Proposition 4.1, $W(T)$ lies in a Stolz domain, and the proof of that result shows that $\operatorname{Fix}(T)=M$. Since $\operatorname{Ran}(I-T)$ is closed if and only if the subspaces are not aligned by [4, Theorem 4.1], the result follows immediately from Corollaries 2.6 and 3.4 .
Remark 4.4. (a) The estimate in (4.3) can be sharpened slightly to an estimate involving the inner $\ell^{2}$-inclination rather than the Friedrichs number by replacing the application of Corollary 3.4 in the above proof with an application of Theorem 3.3, see also Remark 4.2(a).
(b) As was noted in the introduction, exponentially fast convergence in 4.2) is equivalent to the subspace $M_{1}^{\perp}+\cdots+M_{N}^{\perp}$ being closed in $X$; see [22, Theorem 6.4] and also [4, Theorem 4.1] for a number of further equivalent conditions. Thus both $M_{1}^{\perp}+\cdots+M_{N}^{\perp}$ and $\operatorname{Ran}(I-T)$ are closed if and only if $c\left(M_{1}, \ldots, M_{N}\right)<1$. In fact, the identity

$$
\begin{equation*}
I-T=\sum_{k=1}^{N}\left(I-P_{k}\right) \prod_{j=1}^{k-1} P_{j} \tag{4.4}
\end{equation*}
$$

implies that $\operatorname{Ran}(I-T) \subset M_{1}^{\perp}+\cdots+M_{N}^{\perp}$, and in particular both spaces are dense in $M^{\perp}$. However, the inclusion is in general strict when $c\left(M_{1}, \ldots, M_{N}\right)=1$. Indeed, suppose that $N=2$ and that $M_{1} \cap M_{2}=$ $M_{1}^{\perp} \cap M_{2}^{\perp}=\{0\}$. Then the assumption that $\left(I-P_{2}\right)\left(M_{1}^{\perp}\right) \subset \operatorname{Ran}(I-T)$ would already imply, by (4.4), that for each $x \in X$ there exists $y \in X$ such that

$$
\left.\left(I-P_{2}\right)\left(\left(I-P_{1}\right) x-P_{1} y\right)\right)=\left(I-P_{1}\right) y .
$$

But then both sides must lie in $M_{1}^{\perp} \cap M_{2}^{\perp}=\{0\}$, and therefore ( $I-$ $\left.P_{1}\right) x-P_{1} y \in M_{2}$. It follows that $M_{1}^{\perp} \subset M_{1}+M_{2}$, and hence $M_{1}+M_{2}=$ $X$. In particular, $M_{1}+M_{2}$ is closed, and it follows from [19] that $c\left(M_{1}, M_{2}\right)<1$. We do not know whether $c\left(M_{1}, \ldots, M_{N}\right)=1$ implies that $M_{1}^{\perp}+\cdots+M_{N}^{\perp} \subset \operatorname{Ran}(I-T)^{\alpha}$ for some $\alpha \in(0,1)$ or more generally that $M_{1}^{\perp}+\cdots+M_{N}^{\perp} \subset \bigcup_{\alpha>0} \operatorname{Ran}(I-T)^{\alpha}$; see also Remark 2.5(a). A positive answer to either of the above would imply a positive answer to the conjecture made in [22, Remark 6.5(2)].
Corollary 4.5. Given $N \geq 2$ closed subspaces $M_{1}, \ldots, M_{N}$ of a Hilbert space $X$, let $P_{k}$ denote the orthogonal projection onto $M_{k}, 1 \leq k \leq N$.

Furthermore, let $P_{M}$ denote the orthogonal projection onto $M=M_{1} \cap \ldots \cap$ $M_{N}$. If the sequence $\left(x_{n}\right)$ is defined recursively by $x_{0}=x$ and $x_{n+1}=$ $P_{N} \cdots P_{1} x_{n}$ for $n \geq 0$, then

$$
\begin{equation*}
\lim _{n \rightarrow \infty}\left\|x_{n}-P_{M} x\right\|=0 \tag{4.5}
\end{equation*}
$$

for all $x \in X$, and there exists a dense subspace $X_{\infty}$ of $X$ such that for all $x \in X_{\infty}$ the convergence in (4.5) is super-polynomially fast.

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