

## The reliability of individual vocal signature varies across the bonobo's graded repertoire

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1 The reliability of individual vocal signature varies across the bonobos' 2 graded repertoire 3 4 Sumir Keenan<sup>1,2</sup>, Nicolas Mathevon<sup>1</sup>, Jeroen MG Stevens<sup>3</sup>, Florence Nicolè<sup>4</sup>, 5 Klaus Zuberbühler<sup>2,5</sup>, Jean-Pascal Guéry<sup>6</sup> and Florence Levréro<sup>1</sup> 6 7 8 <sup>1</sup>University of Lyon / Saint-Etienne, Equipe Neuro-Ethologie Sensorielle, ENES 9 10 / CRNL, CNRS, INSERM, Saint-Etienne, 42100, France <sup>2</sup>University of St. Andrews, Department of Psychology & Neuroscience, St. 11 Andrews, Scotland, KY16 9JP, UK 12 13 <sup>3</sup>APELAB - Behavioural Ecology and Ecophysiology Group, Department of 14 Biology, University of Antwerp, Belgium <sup>4</sup>University of Lyon / Saint-Etienne, BVPam Lab, CNRS FRE 3727, Saint-15 Etienne, 42100, France 16 <sup>5</sup>Université de Neuchâtel, Department of Comparative Cognition, Neuchâtel, 17 18 2000, Switzerland 19 <sup>6</sup>Vallée des Singes Zoological Park, Romagne, 86700, France 20 21 22 **Corresponding authors:** 23 Sumir Keenan sumirkeenan@gmail.com 24 Florence Levréro florence.levrero@univ-st-etienne.fr

## 27 Highlights

28	•	Coding of individual signature in a graded vocal repertoire					
29	•	Comparison of the strength of individual vocal signature across bonobo					
30		repertoire.					
31	•	Quantitative analysis revealed a graded structure between the most					
32		common bonobo call types.					
33	•	All call types investigated show significant individual vocal signatures.					
34	•	The individual signature is stronger in one extreme of the vocal					
35		gradation.					
36							

#### 37 Abstract

38

Animal vocalisations often contain both 'dynamic' information, related to short-39 40 term fluctuations in the emitter's emotional states, and 'static' information, 41 related to long-term attributes such as age, sex, weight and body size which 42 define the emitter's "individual vocal signature". While both types of information 43 may be of functional value to receivers, dynamic information requires acoustic 44 versatility, while static information depends on acoustic stability. Here we investigate whether an individual vocal signature is present across the vocal 45 46 repertoire of the bonobo, Pan paniscus. We first emphasize the graded 47 character of the bonobo's repertoire by describing the acoustic structure of its five most common tonal vocalisations. We then evaluate the reliability of 48 49 identity information across these call types. The results show that, while all call 50 types support information related to the emitter's identity, the reliability of these 51 vocal signatures was not consistent along the graded vocal continuum. Caller 52 identity is strongly encoded at one end of the acoustic gradation (high-hoot) and decreases from bark, soft bark, peep-yelp to peep calls. Strikingly, the 53 54 reliability of the individual signature thus decreases from calls used in higharousal contexts to low-arousal contexts. To the best of our knowledge, this is 55 56 the first demonstration that an acoustic gradation that codes for 'dynamic' 57 information can be accompanied by variation of the 'static' information that 58 supports vocal individuality.

59

- **Keywords:** acoustic grading; bonobo; identity information; individual vocal
- 62 signature

#### 63 INTRODUCTION

64

65 Bird and mammal vocalisations usually contain both 'dynamic' information, 66 related to short-term fluctuations in the emitter's physiological and 67 psychological states, and 'static' information, related to idiosyncratic features 68 69 such as age, sex, weight, and body size which define the emitter's "individual 70 vocal signature" (Briefer, 2012, 2020; Charlton, Pisanski, Raine & Reby, 2020; Pisanski, Nowak, & Sorokowski, 2016; Raine, Pisanski & Reby, 2017; Taylor, 71 Charlton & Reby, 2016). Both dynamic and static information likely have 72 73 important roles in a wide range of social contexts (Taylor, Charlton & Reby, 74 2016). The acoustic coding of dynamic information relies on versatile acoustic 75 features that can be modulated depending on the emitter's current internal state (Briefer 2012, 2020; Pisanski, et al., 2016a; Raine, Pisanski & Reby, 76 77 2017; Taylor, Charlton & Reby, 2016), and can be reflected in a repertoire of discreet call types (Bradbury & Vehrencamp, 1998; Cheney & Seyfarth, 2018; 78 79 Maynard-Smith & Harper, 2003;), and/or in more subtle acoustic variations 80 within each call type (graded vocalisations; Briefer, 2012, 2020). Sometimes, 81 the acoustic boundaries between call types are unclear that the whole vocal 82 repertoire can be considered as a graded system (e.g. Fischer, Wadewitz & 83 Hammerschmidt, 2017; Hammerschmidt & Fischer 1998; Keenan, Lemasson 84 & Zuberbühler, 2013; Manser et al., 2014; Marler 1977; Tallet et al., 2013). While dynamic information requires acoustic versatility, static information 85 defining an "individual vocal signature" should depend on acoustic stability. 86 How do animal signals deal with this potential conflict of information coding? 87

88 One solution is temporal segregation, which has been demonstrated in the 89 vocalisations of the banded mongoose (Mungos mungo). This species produces calls containing two successive distinct segments, the first being 90 91 stable and individually distinct, and the second being graded and correlating 92 with the emitter's current behaviour (Jansen, Cant & Manser, 2012). Whether temporal segregation is a rare or a widespread way of separately coding 93 94 dynamic and static information in vocal signals is a question that remains to be 95 answered.

Another solution would be to keep the indexical acoustic cues supporting 96 97 individual signatures stable across the whole vocal repertoire. This would mean a common set of individualized acoustic features, either shared between 98 99 calls when the repertoire is composed by discreet calls or remaining invariable 100 throughout a graded repertoire. Unfortunately, this hypothesis has been barely 101 tested, as the vast majority of studies investigating individual vocal signatures 102 have only focused on a single vocalisation type (e.g. in birds: blue footed boobies, Sula nebouxii, Dentressangle, Aubin & Mathevon, 2012; jungle 103 104 crows, Corvus macrorhynchos, Kondo, Izawa & Watanabe, 2010; multiple 105 species of penguins, Aubin & Jouventin 2002; in mammals: bats, Saccopteryx 106 bilineata and Noctilio albiventris, Knörnschild & Von Helversen 2008; Voigt-107 Heucke, Taborsky & Dechmann, 2010; elephants, Loxodonta africana, Soltis, 108 Leong & Savage, 2005; hyenas, Crocuta crocuta, Mathevon, Koralek, 109 Weldele, Glickman & Theunissen, 2010; marmots, Marmotta sp., Matrosova, Blumstein, Volodin & Volodina, 2011; seals, Arctocephalus tropicalis, Charrier, 110

111 Mathevon & Jouventin, 2003; northern elephant seals, Mirounga 112 Charrier. Mathevon & Reichmuth. angustirostris, Casev. 2015: 113 chimpanzees, Pan troglodytes schweinfurthii, Levréro & Mathevon 2013, and spider monkeys, Ateles geoffroyi, Chapman & Weary 1990). To the best of our 114 knowledge, there has only been one study that has examined the coding of 115 individual signature throughout a whole repertoire composed by discreet calls, 116 117 in the zebra finch Taeniopygia guttata (Elie & Theunissen, 2018). In this 118 songbird, individual recognition is of primary importance for pair bonding 119 (Vignal, Mathevon & Mottin, 2004). Elie & Theunissen (2018) showed that 120 each zebra finch call type displays a distinct individual signature, and, contrary to expectations, there is no common set of static, individualized, acoustic 121 122 features. Instead, the vocal repertoire of a given emitter supports numerous 123 signatures, and receivers have to memorize all of them to perform individual recognition. Moreover, the Elie & Theunissen (2018) zebra finch study, as well 124 125 as the few other studies that have analysed more than one call type within a 126 species' vocal repertoire, have emphasised that the reliability of individual 127 signatures may vary among calls (e.g. putty-nosed monkeys, Cercopithecus nictitans, Price, Arnold, Zuberbuhler & Semple 2009; fallow deer, Dama dama, 128 129 Vannoni & McElligott 2007, but see western gorilla, Gorilla gorilla, Salmi, Hammerschmidt & Doran-Sheehy, 2014). For instance, Charrier, Jouventin, 130 131 Mathevon & Aubin (2001) found that both courtship and contact calls of a 132 marine bird, the South Polar Skua (Catharacta maccormicki), have a higher potentiality of individual identity coding than the alarm call. In the red-capped 133

mangabey (*Cercocebus torquatus*), a monkey living in the African rainforest,
individual distinctiveness is higher in contact and threat calls than in other
vocalisations (Bouchet, Blois-Heulin, Pellier, Zuberbuhler & Lemasson, 2012).
Recently, Rubow, Cherry & Sharpe (2017) found similar results among the
repertoire of the dwarf mongoose (*Helogale parvula*).

139 While a proximal explanation for signature inconstancy within a repertoire 140 likely depends on variations in the shape of the vocal tract accompanying 141 modulation of acoustic production (review in Charlton, Pisanski, Raine & Reby, 142 2020), its functional value remains uncertain. Although it may have no specific 143 functional consequences (e.g. Rendall, Owren & Rodman, 1998), alternative hypotheses state that individual signatures differ across call types as an 144 145 adaptive response to various socio-ecological pressures. On one hand, the 146 'distance communication hypothesis' predicts that in low visibilitv environments, such as dense forests, natural selection will favour individual 147 signatures in vocal signals used to communicate over long distances beyond 148 149 the visible range (Ey & Fischer 2009; Mitani & Stuht 1998). This hypothesis 150 has received some support by comparing two chimpanzees' vocalisations, a 151 long distance and a short-range call (Mitani, Gros-Louis & Macedonia, 1996). 152 On the other hand, the 'social function hypothesis' (Price, Arnold, Zuberbuhler 153 & Semple, 2009; Snowdon & Hausberger, 1997) predicts that the reliability of 154 individual vocal signatures depends on the social role of a call type. If the vocalisation is emitted in a context where being recognized is of primary 155 importance for individual-specific relationships, such as mated pair bonds, 156

157 mother-young bond, or tolerant relationships between neighbours in territorial 158 animals, it should bear reliable information about individual identity (Kondo & Watanabe, 2009; Kreiman & Sidtis, 2011; Wiley, 2013). This hypothesis has 159 160 been supported in birds (Charrier, Jouventin, Mathevon & Aubin, 2001; Elie & Theunissen, 2018) and some non-human primate species (e.g. mouse 161 162 lemurs, Microcebus murinus (Leliveld, Scheumann & Zimmermann, 2011), 163 Campbell's monkeys, Cercopithecus campbelli campbelli (Lemasson & 164 Hausberger, 2011). However, these distant-communication and social function 165 hypotheses may not be mutually exclusive. For instance, distance calls can 166 play a significant role in social regulation, facilitating cooperation, such as the recruitment of conspecifics for support (Gersick, Cheney, Schneider, Seyfarth, 167 & Holekamp, 2015; Mitani & Nishida, 1993), coordinating travel (Schamberg, 168 169 Cheney, Clay, Hohmann & Seyfarth, 2016), signalling food ownership (Gros-Louis 2004; Heinrich & Marzluff, 1991), or conveying the aggressive or 170 171 peaceful intentions of callers (Searcy, Anderson & Nowicki, 2006; Silk 2002).

172 To explore how an animal vocal repertoire can deal with the potential conflict 173 of coding both dynamic information (e.g. expressing motivation. 174 aggressiveness...) and static information (i.e. a vocal signature supporting 175 individual recognition), here we investigate variations in the strength of vocal 176 individual signature throughout the graded vocal repertoire of an ape species, the bonobo. Bonobos display a complex vocal repertoire with highly graded 177 call types used flexibly across contexts (Bermejo & Omedes, 1999; de Waal, 178 1998). Despite growing interest in the acoustic communication of this species, 179

our current knowledge of the information content of bonobo calls is limited, as
only few studies have qualitatively described the bonobo vocal repertoire
(Clay, Archbold & Zuberbuhler, 2015; Clay & Zuberbuhler, 2009, 2011a,
2011b; Keenan et al., 2016; White, Waller, Boose, Merrill & Wood, 2015).

184 Bonobo society is characterised by co-dominance between the sexes 185 (Surbeck & Hohmann, 2013) and complex fission-fusion dynamics which 186 require sophisticated social knowledge and communication (Clay, Archbold & 187 Zuberbuhler, 2015; Furuichi, 2011). It has been suggested that individual vocal 188 recognition is essential for successful social navigation (White, Waller, Boose, 189 Merrill & Wood, 2015). In a recent work (Keenan et al., 2016), we experimentally demonstrated that bonobos can vocally identify familiar to 190 191 unfamiliar individuals using the peep-yelp, a soft vocalisation used in short 192 range interactions. This study already revealed that soft calls convey 193 information about individual signature, which is extracted by conspecifics. 194 Other calls from bonobos' repertoire are good candidates to convey individual 195 signatures regarding their propagation capacity in close habitat and their 196 functions. Bonobos loud call types, e.g. high-hoots, can be heard from a 197 distance of 500 meters in the forest (Hohmann & Fruth, 1994), and are 198 regularly used by community members to communicate with one another when 199 the group splits into foraging parties throughout the day. These vocalisations 200 enable the sub-parties to convene around a resource, such as a fruit-bearing 201 tree or nesting tree, despite potential distances between parties (Bermejo & 202 Omedes, 1999; Hohmann & Fruth, 1994, 1995; Schamberg, Cheney, Clay,

Hohmann & Seyfarth, 2016, 2017; White, 1996; White, Waller, Boose, Merrill & Wood, 2015). High-hoots are also exchanged when different communities encounter one another, and they appear to influence inter-community interactions (Furuchi, 2011; Hohmann & Fruth, 2002). Caller identity signalling may thus be present in the bonobos' calls with various acoustic structure and functions.

In this study, we test the hypothesis that an individual signature does exist across the graded vocal repertoire of the bonobo, but that the reliability of this signature varies along with the variation of the acoustic features defining the call types. We firstly emphasize the graded character of the bonobo's repertoire by providing a quantitative description of the acoustic structure of the five most common tonal call types, as well as their contextual use. We then compare the individual distinctiveness across call types.

216

#### 217 **METHODS**

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#### 219 **Ethics Statement:**

All research conducted for this research paper was observational and no experimental manipulations occurred. All data collection protocols were performed in accordance with the relevant guidelines and regulations, and were approved by the Institutional Animal Ethical Committee of the University of Lyon/Saint-Etienne, under the authorization no. 42-218-0901-38 SV 09 (Lab ENES).

#### 227 Subjects

The bonobos observed for this study were members of three separate captive 228 229 groups housed at three European zoos: Apenheul (Apeldoorn, the Netherlands), Planckendael Zoo (Mechelen, Belgium) and la Vallée des 230 231 Singes (Romagne, France; see Supplemental Table A1 for group composition 232 at each zoo). At each zoo, groups were housed in large indoor enclosures with 233 varying access to off-exhibit rooms and outdoor islands. All individuals 234 included in the study had lived in similar captive zoo environments certified by 235 the European Association of Zoos and Aquaria for a minimum of 10 years prior 236 to recording. Vocal recordings and observations were taken from all areas at 237 all three zoos, except in the off-exhibit enclosures at Apenheul.

238

To avoid the potential confound of differences in vocal tract size due to age, only bonobos over the age of 10 were included in this study. Additionally, one adult male and one female, who had overall low calling rates, were excluded. This led to a total of 21 individuals ranging in age from 10 - 45, with a mean age of 20.5 years old, and comprised of 13 females and 8 males.

244

#### 245 Data Collection

246 Vocal recordings

Vocal recordings were collected between March 2013 and March 2014,
beginning no earlier than 8 a.m. and finishing no later than 6 p.m. Recordings

at Apenheul Zoo were collected from May 14, 2013 – July 6, 2013, as well as
on March 12, 2014, and amounted to 175 hours of total recording time.
Recordings at Planckendael Zoo were collected from March 20, 2013 – May
10, 2013 and from February 20 – March 4, 2014, and amounted to 190 hours
of total recording time. Recordings at la Vallée des Singes were collected from
October 28, 2013 – November 25, 2013, and amounted to 115 hours of total
recording time.

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Audio recordings were taken using a Zoom H4 Digital Multi-track Recorder 257 258 (44.1 kHz sample rate, 16 bits per sample, .wav files) - recording in stereo, with one channel devoted to a Sennheiser MKH70-1 ultra-directional 259 microphone recording any bonobo vocal behaviour and the second channel 260 261 connected to a micro-tie recording device, model AKG MPA III, for comments by the researcher. This allowed for temporal synchronising of each 262 263 vocalisation to information on vocaliser identity and call context, as recorded by the researcher. 264

265

#### 266 Call types

Each call was assigned to one of the 11 types based on classifications described in previous studies (Bermejo & Omedes, 1999; Clay & Zuberbuhler, 2009; de Waal, 1988) by SK. We calculated the frequency with which each call type was produce so that we could assign a proportion to each call type in the entire dataset (relative to the 2,373 measurable calls collected from the 21

272 adults included in the study). Any call type that represented less than 10% of 273 the total number of measurable calls collected was excluded from the analysis. In addition, two call types, screams and grunts, were excluded from the current 274 275 study, due to their noisy acoustic features characterised by non-linear phenomena and lack of clear harmonic structure. Unlike the rest of the adult 276 vocal repertoire, these two call types would require a different set of 277 278 measurements to describe their acoustic features. In total, five call types were 279 retained, which represented the vast majority of calls emitted by all individuals 280 in the study groups (78% of all calls collected, excluding screams and grunts): 281 (1) high-hoots (14%; described as 'staccato-high hoots' by de Waal (1988) and 'high hoots' by Bermejo & Omedes (1999)); (2) barks (18%; described as 282 'barks' and 'wieew barks' by de Waal (1988) and as 'barks' and 'composed 283 284 barks' by Bermejo & Omedes (1999)); (3) soft barks (17%; described as 'soft barks' by Bermejo & Omedes (1999), 'food barks' by Clay & Zuberbuhler, 285 286 (2009) and not described by de Waal (1988); (4) peep-yelps (18%; described as 'peep-yelps' by de Waal (1988); Bermejo & Omedes (1999); Clay & 287 288 Zuberbuhler (2009) and (5) peeps (11%; described as 'peeps' by de Waal (1988); Bermejo & Omedes (1999); Clay & Zuberbuhler (2009); see 289 290 Supplemental Table A2 for full acoustic description of each call type).

291

292 Call contexts

If a caller could be identified, social and individual contextual information wasalso recorded. Each recorded call occurred in one of the following eight

295 contexts: 1) 'pre-feeding' - calls given directly prior to or at the start of 296 scheduled feedings when group/social excitement was extremely high (excitement described as increased sexual activity, displacements, pacing, 297 298 pilo-erection, vocal activity, displays and increased likelihood of aggression); 2) 'feeding' – calls given during scheduled feedings; 3) 'foraging' – calls given 299 when foraging for or eating food found outside or in the inside enclosure 300 301 outside of scheduled feeding times; 4) 'aggression' - calls given during 302 agonistic encounters, including mild aggression (no physical contact), 303 aggression (mild physical contact, such as hitting, kicking or grabbing between 304 only two individuals), conflict (a range of physical contact, including biting, and 305 often between more than two individuals) - agonistic interactions were also classified into calls from victims, from aggressors or from bystanders; 5) 306 307 grooming - calls given during bouts of grooming; 6) contact – calls given when a subject was resting or moving but nothing else; 7) change of environment -308 309 calls given when individuals were shifted from one enclosure to another or 310 from inside to outside; and 8) external event – calls given when an individual 311 was visibly startled by or responding to a disturbance external to the group.

312

#### 313 Acoustic Analysis

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315 Only vocalisations that could unequivocally be assigned to one caller were 316 retained for analysis. Only calls of good, measurable quality were included, 317 while calls that overlapped with background noise (e.g. birds chirping, water

318 falling, zoo visitors speaking or other bonobos calling) were removed from the dataset. In total, 1,850 individual calls were retained for analyses (with an 319 320 average of 88 total calls per individual (N=21), S.D.= 37.87, minimum=45, 321 maximum=227). Raven Pro 1.3 was used to measure automatic and manual parameters on each call and spectrograms were generated using a 512-322 323 sample Hann window (50% frame overlap, frequency resolution of 86.1 Hz and 324 temporal resolution of 11.6 mS). A correlation matrix was produced and very 325 highly correlated variables were removed (0.9 and above), resulting in a total 326 of 16 measurements being retained for analysis – nine manually measured 327 parameters describing the fundamental frequency and its temporal modulation, 328 and seven automatically computed parameters describing the distribution of 329 energy across the frequency spectrum of the entire call (Table 1; Figure 1).

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331

#### 332 Statistical Analysis

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334 Call type distinctiveness

To confirm whether our dataset could be reliably classified into the five main call types proposed by previous studies, we performed a multivariate permuted discriminant function analysis (pDFA) to determine the statistical distinction between the 1,850 individual calls (high-hoots: n=333, barks: n=431, soft barks: n=413, peep-yelp: n=420, peeps: n=253; See Supplemental Table A2 for acoustic description of each call type). The raw values of the 16 acoustical

parameters of interest were centred and normalised by transforming them into
 z-scores as the parameter set consisted of different units.

343

344 Mundry and Sommer (2007) have convincingly argued that using traditional discriminant function analyses (DFA), when analysing non-independent data 345 (e.g. if the same individual contributed multiple calls), is a case of pseudo-346 347 replication and can inflate results. To address this issue, we employed a 348 permuted discriminant function analysis (pDFA - Mathevon et al., 2010; 349 Mundry & Sommer 2007) using the 16 acoustic variables (analysis performed 350 in R, Version 3.2.0). The pDFA takes the classic DFA a step further by 351 comparing the distribution of percent correct classifications obtained after 100 352 iterations (mean effect size) to the distribution of percent correct values 353 obtained by initially randomly assigning the call type to each individual call (for 354 the current analysis this distribution was obtained via 1000 created data sets 355 where the call type of each call was randomly permutated).

356

In detail, we performed the following steps. In the first step of the DFA, a training data set was used to generate a set of linear discriminant functions. The training data set consisted of randomly selected sounds from each individual. The number of sounds selected per individual was the same for all individuals and equal to 2/3 of the smallest number of sounds that we obtained for an animal in our data set. In the second step, the discriminant functions generated from the training data set were used to classify the remaining

364 sounds. For each individual, at least 1/3 of the sound provided by each individual was thus included in the validating data set. This cross-validation 365 step gives a measure of the effect size (the percentage of correctly classified 366 367 sounds; which has to be compared with chance, here 20%, i.e. 1/5 possible 368 call types). We ran 100 iterations of these two-step DFAs with both training and validation data sets chosen at random. The mean effect size (mean 369 370 percentage of correctly classified sounds) was obtained by calculating the 371 average of the percentages of correctly classified sounds obtained with each of the 100 validation data sets. In addition to the cross-validated DFAs 372 373 performed on original data sets, new data sets were also created, where the 374 identity of sounds was randomly permuted between individuals (permuted 375 DFA), to obtain the statistical significance of the mean effect size. From these 376 randomised sets, the same steps, fitting and validation, were consecutively performed. After 1000 iterations, we calculated the proportion of randomized 377 378 validation data sets revealing a number of correctly classified calls being at 379 least as large as the effect size obtained with the non-randomised validation 380 data set. This proportion gives the significance of the discrimination level and 381 is equivalent to a p-value [Dentressangle, Aubin & Mathevon, 2012; Mathevon, 382 Koralek, Weldele, Glickman & Theunissen, 2010; Mundry & Sommer 2007].

383

384 Individual vocal signatures

385 We assessed the reliability of individual signatures for each call type 386 independently using two different approaches: the first approach used a pDFA

(same method as described above, except that calls within each call type were classified according to the identity of the vocaliser; here the chance of correct classification was 10%, i.e. 1/10 possible individual callers), and secondly by calculating the acoustic variation and potential for individual coding (PIC) for each call type overall, as well as for each acoustic parameter describing the calls (Robisson, Aubin & Bremond, 1993).

393

394 The amount of variability across the five call types was determined by calculating the inter- and intra-individual coefficients of variation (CV). Intra-395 396 individual CVs correspond to the variability of each acoustic variable within individuals, and inter-individual CVs correspond to the variability of each 397 398 acoustic variable between individuals (see mathematical formula below). The 399 CV values were then used to calculate potentials of individual coding (PICs) for each acoustic variable in each call type (according to Robisson, Aubin & 400 401 Bremond, 1993). For each considered acoustic parameter, the PIC 402 corresponds to the ratio between the variability between individuals and the 403 mean variability within individuals. A PIC value greater than one suggests that 404 the acoustic parameter considered may be used for individual recognition as 405 its intra-individual variability is smaller than its interindividual variability. 406 Additionally, recent studies investigating individual distinctiveness in non-407 human primates have calculated CV and PIC values, including them here 408 enables direct comparison between species (Bouchet, Blois-Heulin, Pellier, 409 Zuberbuhler & Lemasson, 2012; Lemasson & Hausberger, 2011; Salmi,

410 Hammerschmidt & Doran-Sheehy, 2014). As the coefficient of variation (CV) 411 can only be calculated with variables on a ratio scale, two variables (that were 412 on an interval scale) were not included (Slope- F<sub>0</sub> Start to Mid and Slope- F<sub>0</sub> 413 Mid to End). Therefore, for each of the remaining 14 parameters in each call type separately we first calculated the CV(Inter) = (100 X S.D. calculated 414 415 across all individuals) / (Mean (calculated across all individuals)) and the CV(Intra) = the mean of individual CV values, where the CV (= 100 X 416 417 S.D./Mean) was calculated for each individual separately. PIC values could then be obtained for each parameter (PIC = CV(Inter)/ CV (Intra)). To assess 418 419 the variation of the five call types as a whole, we took the mean of the CV(Inter) and the CV(Intra) across the 14 parameters for each call type 420 separately. These means were then used to calculate the PIC values for each 421 422 call type. To test for call type differences in the levels of variation and potential for individual coding, Friedman tests were done with the CV and PIC values for 423 424 each parameter for each call type respectively.

425

For the acoustic variation and PIC analyses, we included all individuals with 12-20 calls for each call type. For individuals who had more than 20 calls in a given call type, we randomly chose calls to be excluded (however ensuring where possible that a single calling event or calls given in a single day were not over-represented). This ensured that no single individual was overrepresented, as no individual contributed more than 20 calls for each call type.

434 For the pDFA analysis, we retained individuals who had a minimum of 14 calls 435 for each call type (with the exception of one individual who had 13 calls in the 436 peep call type) (See Supplemental Table A1 for the number of calls contributed by each individual for each call type). Not every individual had a 437 sufficient number of calls for each call type to be included in all five-call type 438 439 analyses. The peep call-type had the fewest number of contributing individuals 440 (n=10). To allow for direct comparison across call types, we randomly chose 441 ten individuals for each of the other four call types (balancing the data for 442 individual sex and group), with the majority of individuals contributing to 2 or 3 call type analyses (mean = 2.5, max = 4, min = 1; Supplemental Table A1). 443

444

We considered the identity of callers to assess the individual vocal signature, but not the sex, rank or age. Indeed, sex information is one of the many other elements that constitute individual identity. A receiver may identify the overall identity of a familiar caller and not need to categorize it by its sex. To identify other parameters and their interactions that may influence the identity signature was beyond the scope of this study.

451

#### 452 **RESULTS**

453

454 Call types – Classification and context

The results of the pDFA showed that the acoustic structure of calls supports the initial, human-driven, classification into call types, with an accuracy of 57% (chance = 20%, P < 0.001; Figure 2).

458

A scatterplot using discriminant function 1 and 2 to visualise the grouping of the call types, fails to show any distinct boundaries between the five call types, suggesting acoustic grading (Figure 3). We observed a crescent shape from the soft peep to loud high-hoot, which highlights the strong graded nature of the most common call types in the vocal system of the bonobo.

464

465 Despite the gradedness of the five call types, overall the call types were used significantly differently from one another in different contexts ( $\chi^2 = 930.281$ , P 466 467 < 0.001; results of Chi-square on contingency table of observed vs. expected number of calls emitted in each context for each call type) (Table 2), and post-468 469 hoc tests revealed that each call type was used significantly differently from 470 each other call type (see Supplemental Table A3 for details). The high-hoots 471 were used most often before feeding times (pre-feeding) and by aggressors in 472 agonistic encounters (aggression), but also during changes in environment 473 and to external events (or alarm). Barks were given in similar contexts to high-474 hoots, however, with a marked increase of calls being given during feeding 475 events. Soft barks were given mostly in association with feeding and foraging, 476 but also during pre-feeding events. Peep-yelps and peeps, finally, were used similarly with the main difference being an increased usage of peeps during 477

478 grooming and contact and a decreased usage during feeding or foraging479 (Table 2).

480

#### 481 Individual vocal signature

Five separate pDFA analyses were run on each call type to evaluate the level 482 483 of individual distinctiveness along the graded repertoire. Calls were assigned to the correct emitter 53% of the time for high-hoots (chance level = 10%; P =484 485 0.001), 44% for barks (chance level = 10%; P = 0.001), 30% for soft barks (chance level = 10%; P = 0.001), 25% for peep-yelps (chance level = 10%; P =486 487 0.004) and 23% for peeps (chance level = 10%; P = 0.006) (all percentages were from cross-validated data sets; Figures 3 and 4; Supplemental Tables 488 A4, A5, A6, A7, A8). 489

490

#### 491 Variability and vocal signature

All of the call types had PIC values over 1, indicating that all five have some capacity to code for individuality, however the PIC was significantly stronger in some call types (Friedman test of PIC values:  $\chi^2$  (13) = 49.114, *P* < 0.001). PIC was highest in high-hoots (1.22), followed by barks (1.18), peep-yelps (1.10), soft barks (1.08) and peeps (1.03) (Table 3).

497

We then used this information to investigate which of the acoustic parameters had the highest potential for individual coding. Across all call types the onset frequency of the fundamental frequency ( $F_0$ -Start) (1.20) and the ascending 501 slope (1.22) had the highest PIC values (Table 3). However, when 502 investigating each call type separately, these two parameters did not always 503 have the highest potential for individual coding. The onset frequency of the 504 fundamental frequency ( $F_0$ -Start) had the highest PIC in both the peep and 505 barks, while the maximum frequency reached on the fundamental frequency (F<sub>0</sub>-Peak) had the highest PIC in peep-yelps and high-hoots and the call 506 507 duration and the frequency of the fundamental at the end of the call (F<sub>0</sub>-End) equally had the highest PIC for soft barks. Additionally, for each call type 508 509 separately not all acoustic parameters reached the minimum threshold (PIC  $\leq$ 510 1) of identity coding (Table 3). It is clear that acoustic parameters related to the 511 tonality had consistently higher PIC values than the parameters describing the 512 energy distribution for all five call types.

513

#### 514 **DISCUSSION**

515

516 Our results demonstrate that the bonobo tonal calls investigated show clear 517 individual vocal signatures. Furthermore, the results support our hypothesis 518 that the reliability of this signature varies along the graded vocal continuum 519 formed by these calls. Caller identity signalling is stronger at one end of the 520 acoustic gradation (high-hoot) and then decreases from bark, soft bark, peep-521 yelp to peep calls. The reliability of the individual signature thus decreases 522 from calls mostly used in high-arousal contexts to the ones used in low-arousal contexts. To the best of our knowledge, this is the first demonstration that the 523

acoustic gradation that codes for 'dynamic' information can be accompanied
by a gradation of the strength of the 'static' information that supports vocal
individuality.

527

Individual signatures are the result of idiosyncratic acoustic features 528 529 characterizing each individual. These features are constrained by the 530 biomechanics of sound production, which varies depending on individual 531 morphology, anatomy, and physiology. As such, a proximal explanation for the 532 variation of the strength of individual signature across the vocal repertoire is 533 that the acoustic features of calls do not have the same potential for encoding 534 individual variation. Soft calls, namely characterized by little to no frequency modulation and short durations, may offer reduced possibility for encoding 535 536 identity cues. Conversely, highly frequency modulated calls as the high-hoot 537 may support higher possibilities for individual differences.

538

Importantly, we recently demonstrated with playback experiments that 539 540 bonobos are able to discriminate between the peep-yelps of familiar and unfamiliar individuals (Keenan et al., 2016). This suggests that even the call 541 542 types with a less reliable individual signature may contain enough identity 543 information for individual recognition in bonobos. Similar findings with various 544 species have demonstrated that individuals are able to utilize acoustically 545 encoded identity information to recognise others even in calls with low potential for individuality (e.g. in zebra finches - Elie & Theunissen, 2018; 546

547 northern fur seals, Callorhinus ursinus – Insley, 2000; domestic horses, Equus 548 caballus - Proops, McComb & Reby, 2009; and rhesus macaques Macaca 549 *mulatta* – Rendell, Rodman & Emond, 1996). However, peep-yelps, and other soft calls, may greatly suffer from long range propagation through the forest 550 environment. We assume that the individual signature carried by these calls 551 should be efficient only at short-range. We suggest that the increase in 552 553 signature reliability from peeps to high-hoots may be functionally relevant since it allows louder calls, which propagate further, to maintain the fidelity of 554 individual information ("distance hypothesis", Ey & Fischer, 2009; Fedurek, 555 556 Zuberbühler & Dahl, 2016; Mitani, Gros-Louis & Macedonia, 1996; Mitani & Stuht 1998). It is also possible that the social value of individual recognition 557 increases from peeps to high-hoots ("social function hypothesis", Price, Arnold, 558 559 Zuberbuhler & Semple, 2009; Snowdon & Hausberger, 1997; Snowdon & Hausberger 1997). 560

561

Whether variation in the reliability of individual signatures across a vocal repertoire is an adaptive response to socio-ecological pressures is still debated. Similar to our data, a recent study (Salmi, Hammerschmidt & Doran-Sheehy, 2014) investigating individual distinctiveness in both close and long range call types of female western gorillas (*Gorilla gorilla gorilla*), found that all call types had the same potential for individual coding. The authors concluded that neither the social function nor the distance hypotheses accurately

reflected the possible evolutionary pressures likely acting on female gorillacalls.

571

572 While gorillas are the only other ape species where multiple call types were investigated, Mitani et al. (1996) studied two call types in chimpanzees, the 573 574 bonobo's congener. They found, as in our study, that loud calls contained 575 stronger identity information than soft calls used when in close contact with 576 other individuals. Chimpanzees and bonobos both live in dense rain forests, 577 forming far more complex fluid fission-fusion societies compared to the 578 gorilla's largely stable polygynous group structure (Robbins, Bermejo, 579 Cipolletta, Magliocca, Parnell, & Stokes, 2004). This difference in social structure, and the need to regularly communicate with group members over 580 581 long distances, is likely a driving evolutive pressure for accurate identity signaling over long distance. 582

583

So far acoustically graded calls have been overlooked in animal 584 585 communication research, despite being widespread in the vocal repertoire of terrestrial mammals (Crockford, 2019; Fischer, Wadewitz & Hammerschmidt, 586 2017). This lack of knowledge is mainly due to the complexity of capturing and 587 describing the variations in the signal repertoires without forcing arbitrary 588 589 categorizations (Fischer, Wadewitz & Hammerschmidt, 2017). Yet, a 590 comparative perspective on graded repertoires of non-human primates and 591 other mammals may inform understanding of our own vocal repertoire. Indeed,

the non-verbal vocalisations of humans (e.g. laughter, cries, and screams) 592 593 resemble those of non-human mammals, especially when one considers how they greatly fluctuate in their acoustic structure (Briefer 2012, 2020; Morton, 594 595 1977). Despite their importance in human social regulation, how individual vocal signatures change or are preserved across calls used in a diversity of 596 597 communication contexts -from joy to distress- is also poorly known. A recent 598 study in humans revealed that individual differences in fundamental frequency 599 (F0), which is an important biosocial marker during speech production (for 600 reviews Lavan, Burton, Scott & McGettigan, 2019; Pisanski, Cartei, 601 McGettigan, Raine & Reby, 2016), may be preserved across non-verbal sounds (from laughter to screams) in largely valence-specific manner. For 602 instance, individual differences in F0 were preserved across pain vocalisations 603 604 representing varying levels of pain intensity (Pisanski, Raine & Reby, 2020). 605 Pisanski et al. (2016b) argued that the high ability of humans to voice 606 modulation is likely to predate our ability to articulate the verbal dimension of 607 speech. Here we raise the question whether a vocally graded repertoire is to 608 some extent a form of vocal flexibility.

609

610

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# 946 Table 1. Automatic and manual acoustic parameters947

Acoustic parameters	Description/Calculation			
F <sub>0</sub> -Start	Fundamental frequency at beginning of the call (Hz)			
$F_0$ -End	Fundamental frequency at end of the call (Hz)			
F <sub>0</sub> -Peak	Highest frequency reached on the fundamental (in Hz)			
$F_0$ -Peak Time	Point over the duration of the call at which $F_0$ -Peak is			
	reached. Manually calculated as a proportion: time of $F_{0}$ -			
	Peak(s) / Call Duration (s)			
Call Duration	Length of call (s)			
Ascending Slope	Calculated as: $(F_0$ -Peak – $F_0$ -Start) / $(F_0$ -Peak Time – 0)			
Descending Slope	Calculated as: $(F_0$ -End – $F_0$ -Peak) / $(1 - F_0$ Peak Time)			
Slope- F <sub>0</sub> Start to	Calculated as: ( $F_0$ at midpoint of call duration – $F_0$ -Start) /			
Mid	(Time at midpoint of call duration $-0$ )			
Slope– $F_0$ Mid to	Calculated as: ( $F_0$ -End – $F_0$ at midpoint of call duration) /			
End	(Call duration – Time at midpoint of call duration)			
Q25 Frequency	The frequency at which the call is divided into two			
	intervals, the first quartile contains 25% of the call's			
	energy (Hz)			
Q25 Time	The time at which the call is divided into two			
	intervals, the first quartile contains 25% of the call's			
	energy (s)			
Q50 Frequency	The median - the frequency at which the call is			

	divided into two frequency intervals of equal energy			
	(Hz)			
Q75 Frequency	The third quartile – contains 75% of the call's energy			
	(Hz)			
Q75 Time	The third quartile – contains 75% of the call's energy			
	(s)			
Maximum	The frequency at which the maximum energy occurs			
Frequency	in the call (Hz)			
Maximum Time	The first time point along the call where maximum			
	amplitude occurs on waveform (s)			

- 950 Non-bold text are the manually measured or calculated measurements, and
- 951 bold text are automatically calculated by the Raven program.
- 952

### 953 Table 2. Call type usage in each context

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	Percentage of calls given in each context					
	High-	Bark	Bark Soft Bark		Peen	
Contexts	hoot			yelp	12	
Aggression	23.12	19.03	2.66	0.00	0.00	
Change in	18.02	13.46	9.93	2.86	1.58	
environment						
External Event	13 81	6.96	2 18	2 14	0 79	
(Alarm)	10.01	0.00	2.10	<b>_</b>	0.70	
Pre-feeding	38.74	34.34	21.55	17.38	21.74	
Feeding	1.80	18.10	38.26	36.19	28.46	
Forage	4.50	3.25	18.40	15.95	9.09	
Groom	0.00	0.93	1.45	6.43	9.88	
Contact-general	0.00	3.94	5.57	19.05	28.46	

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957 The two contexts in which each call type is most commonly used are in bold.

958 (Percentages presented for clarity only; chi-square results were generated by

959 analysing observed vs. expected values of call rates.)

# 961 962 Table 3. Potential for individual coding (PIC)

		PIC values by Call Types				S
	Overall PIC					
	value for					
Individual	each		Peep	Soft		High-
Parameters	parameter	Peep	-yelp	bark	Bark	hoot
F <sub>0</sub> -Start	1.20	1.23	1.24	1.12	1.29	1.38
F <sub>0</sub> -End	1.11	1.20	1.18	1.20	1.19	1.43
F <sub>0</sub> -Peak	1.20	1.21	1.25	1.12	1.25	1.46
F <sub>0</sub> -Peak Time	1.08	0.91	1.03	1.04	1.06	1.18
Call Duration	1.16	1.05	1.13	1.20	1.19	1.28
Ascending Slope	1.22	0.97	1.15	1.06	1.19	1.14
Descending Slope	1.03	1.06	1.17	1.08	1.02	1.21
Q25 Frequency	1.17	1.17	1.11	1.12	1.17	1.38
Q25 Time	1.07	0.99	1.01	1.03	1.15	1.06
Q50 Frequency	1.12	1.15	1.11	1.10	1.22	1.36
Q75 Frequency	1.14	1.17	1.08	1.18	1.23	1.34
Q75 Time	1.09	1.00	1.05	1.06	1.12	1.14
Maximum Frequency	1.08	1.12	1.08	1.08	1.11	1.28
Maximum Time	1.10	1.02	1.03	1.03	1.10	1.08
Overall PIC for call type		1.03	1.10	1.08	1.18	1.22

964 Investigation of the potential for individuality in each call type as well as each
965 parameter across all call types and within each call type separately. A PIC
966 greater than or equal to 1 suggests potential for individuality. For each call
967 type, the parameter with the highest PIC is in bold.

Figure 1. Acoustic and temporal measurements. Example of manual measurements taken on a soft bark call: a= F0-Start, b=F0-Midpoint (not included in analysis but used to calculate other measurements), c=F0-Peak, d=F0-End. Call duration=time at b) – time at a).

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975 Figure 2. Spectrographic illustrations of the five most common call types of the 976 bonobo repertoire. Spectrogram images depict: 1) High-hoot; 2) Bark; 3) Soft 977 bark; 4) Peep-yelp; 5) Peep. Panel 6) shows the confusion matrix obtained 978 from the permuted DFA classifying the five call types, which are labelled as 979 just listed. The classification rate was of 60% for High-hoot, 44% for Bark, 48% for Soft bark, 58% for Peep-yelp and 62% for Peep. On the confusion matrix, 980 981 the diagonal shows the rate at which a call type was correctly assigned specifically, what percentage the actual call type and the predicted call type 982 match. The brightness of each diagonal yellow square corresponds to the 983 strength of classification. The off-diagonal cells show percentage of 984 985 misclassification for each call type and which other call type they were misclassified as. 986

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988

Figure 3. Acoustic gradation and individual signature coding in the bonobo
vocal repertoire. Top: The scatterplot illustrates the graded nature of the
acoustic properties of the five call types. The Table displays the factor loadings

on Discriminant function 1 and 2. White asterisks mark the centroid of each
call type. Bottom graph: The mean percentage of correct classification for
individual identity is reported for each call type, illustrating that the reliability of
the vocal signature increases from peeps to high-hoots.

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998 Figure 4. Individual vocal signatures in five different call types. 1) High-hoots 999 (mean correction classification rate: 53%); 2) Barks (mean correction 1000 classification rate: 44%; 3) Soft Barks (mean correction classification rate: 1001 30%); 4) Peep-yelps (mean correction classification rate: 30%); 5) Peeps 1002 (mean correction classification rate: 23%). Each confusion matrix shows the results of five separate permuted DFAs investigating the strength individuality 1003 1004 in each call type. The confusion matrix shows the probability that an 1005 individual's calls were correctly classified after 100 iterations - the legend 1006 shows the percent accuracy for each individual (the accurate percentages are given in Supplementary Table A4; Random classification at 10%). Details on 1007 1008 each individual, age, sex, rank, zoo and number call contributed to each 1009 analysis can be found in Supplemental Table A1.)

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Time (s)







Call	Type	
oun	.,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	

High-hoot
A Bark
I Soft Bark
Peep-yelp
♦ Peep
☆ Group Centroid

	Function 1	Function 2
F <sub>0</sub> -Start	-0.121	0.436
F <sub>0</sub> -End	-0.015	0.146
F <sub>0</sub> -Maximum	0.616	0.024
F <sub>0</sub> -Maximum proportion	0.076	0.293
Call Duration	0.445	-0.003
Ascending Slope	0.59	-0.452
Descending Slope	-0.612	0.151
Slope-Start to Midpoint	0.543	-0.183
Slope-Midpoint to End	-0.467	-0.166
Q1 Frequency	0.244	0.111
Q1 Time	0.195	0.068
Q3 Frequency	0.299	-0.012
Q3 Time	0.34	-0.044
Centre Frequency	0.303	0.006
Maximum Frequency	0.214	0.057
Maximum Time	0.238	0.019



Predicted individual