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### Comparison of algorithms for estimating ocean primary production from surface chlorophyll, temperature, and irradiance

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[1] Results of a single-blind round-robin comparison of satellite primary productivity algorithms are presented. The goal of the round-robin exercise was to determine the accuracy of the algorithms in predicting depth-integrated primary production from information amenable to remote sensing. Twelve algorithms, developed by 10 teams, were evaluated by comparing their ability to estimate depth-integrated daily production (IP, mg  $C m^{-2}$ ) at 89 stations in geographically diverse provinces. Algorithms were furnished information about the surface chlorophyll concentration, temperature, photosynthetic available radiation, latitude, longitude, and day of the year. Algorithm results were then compared with IP estimates derived from <sup>14</sup>C uptake measurements at the same stations. Estimates from the best-performing algorithms were generally within a factor of 2 of the <sup>14</sup>C-derived estimates. Many algorithms had systematic biases that can possibly be eliminated by reparameterizing underlying relationships. The performance of the algorithms and degree of correlation with each other were independent of the algorithms' complexity. INDEX TERMS: 4894 Oceanography: Biological and Chemical: Instruments and techniques; 4275 Oceanography: General: Remote sensing and electromagnetic processes (0689); 4805 Oceanography: Biological and Chemical: Biogeochemical cycles (1615); 4806 Oceanography: Biological and Chemical: Carbon cycling; 4853 Oceanography: Biological and Chemical: Photosynthesis; KEYWORDS: primary productivity, algorithms, ocean color, remote sensing, satellite, chlorophyll

#### 1. Introduction

[2] Global maps of the upper-ocean chlorophyll concentration are now being generated routinely by satellite ocean color sensors. These multispectral sensors are able to map the chlorophyll concentration, a measure of phytoplankton

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biomass, by detecting spectral shifts in upwelling radiance. As the chlorophyll concentration increases, blue light is increasingly absorbed, and thus less is scattered back into space. Although global coverage can nominally be achieved every 1-2 days, the actual temporal resolution is reduced to

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 Table 1. Algorithm Testing Subcommittee of NASA's Ocean

 Primary Productivity Working Group<sup>a</sup>

<sup>a</sup>These individuals were responsible for conducting the primary productivity algorithm round-robin experiment. They agreed not to participate by testing algorithms of their own.

 $\sim$ 5–10 days because of cloud cover. Nevertheless, the coverage afforded by satellite remote sensing is vastly greater than that obtainable by any other means.

[3] A principal use of the global ocean chlorophyll data is to estimate oceanic primary production [Behrenfeld et al., 2001]. The mathematical models or procedures for estimating primary production from satellite data are known as primary productivity algorithms. In the early days of the Coastal Zone Color Scanner (CZCS), simple statistical relationships were proposed for calculating primary production from the surface chlorophyll concentration [e.g., Smith and Baker, 1978; Eppley et al., 1985]. Such empirically derived algorithms are still considered useful when applied to annually averaged data [Iverson et al., 2000], but they are not sufficiently accurate to estimate production at seasonal timescales. The surface chlorophyll concentration explains only  $\sim 30\%$  of the variance in primary production at the scale of a single station [Balch et al., 1992; Campbell and O'Reilly, 1988].

[4] Over the past 2 decades, scientists have sought to improve algorithms by combining the satellite-derived chlorophyll data with other remotely sensed fields, such as sea surface temperature (SST) and photosynthetic available radiation (PAR). These algorithms incorporate models of the photosynthetic response of phytoplankton to light, temperature, and other environmental variables, and some also incorporate models of the vertical distribution of these properties within the euphotic zone [*Balch et al.*, 1989; *Morel*, 1991; *Platt and Sathyendranath*, 1993; *Howard*, 1995; *Antoine and Morel*, 1996a; *Behrenfeld and Falkowski*, 1997a; *Ondrusek et al.*, 2001]. Algorithms have been

used to estimate global oceanic primary production from CZCS data [*Antoine and Morel*, 1996b; *Longhurst et al.*, 1995; *Behrenfeld and Falkowski*, 1997a; *Howard and Yoder*, 1997], and more recently from Sea-viewing Wide Field-of-view Sensor (SeaWiFS) data [*Behrenfeld et al.*, 2001]. Global maps of the average daily primary production for varying periods (weeks, months, and years) are now being produced from Moderate Resolution Imaging Spectroradiometer (MODIS) data.

[5] While many of the photosynthetic responses (to light, temperature, etc.) are commonly represented, model-based algorithms differ with respect to structure and computational complexity [*Behrenfeld and Falkowski*, 1997b]. Models may be similar in structure but require different parameters depending on whether they describe daily, hourly, or instantaneous production, and even where these aspects are similar, algorithms often yield different results because of differences in their parameterization. *Balch et al.* [1992] evaluated a variety of algorithms (both empirical and model based), using in situ productivity measurements from a large globally distributed data set, and found that they generally accounted for <50% of the variance in primary production.

[6] In January 1994 the National Aeronautics and Space Administration (NASA) convened an Ocean Primary Productivity Working Group with the goal of developing one or more "consensus" algorithms to be applied to satellite ocean color data. The working group initiated a series of round-robin experiments to evaluate and compare primary productivity algorithms. The approach was to use in situ data to test the ability of algorithms to predict depth-integrated daily production (IP, mg C m<sup>-2</sup>) based on information amenable to remote sensing. It was decided to compare algorithm performances with one another and with estimates based on <sup>14</sup>C incubations.

[7] Our understanding of primary productivity in the ocean is largely based on the assimilation of inorganic carbon from <sup>14</sup>C techniques [Longhurst et al., 1995], and thus it was considered appropriate to compare the algorithm estimates with <sup>14</sup>C-based estimates. However, it was recognized that the <sup>14</sup>C-based estimates are themselves subject to error [Peterson, 1980; Fitzwater et al., 1982; Richardson, 1991]. The <sup>14</sup>C incubation technique measures photosynthetic carbon fixation within a confined volume of seawater, and there are no methods for absolute calibration of bottle incubations [Balch, 1997]. Furthermore, there is no universally

Table 2. Participant Teams Whose Algorithms Were Tested in Round Robin

Participant	Affiliation
David Antoine and Andre Morel	Laboratoire de Physique et Chimie Marines
William Balch and Bruce Bowler	Bigelow Laboratory for Ocean Sciences
Michael Behrenfeld and Paul Falkowski	NASA Goddard Space Flight Center/Rutgers University
Nicolas Hoepffner	Joint Research Centre of the European Commission
Dale Kiefer	University of Southern California
Steven Lohrenz	University of Southern Mississippi
John Marra	Lamont-Doherty Earth Observatory
Vladimir Vedernikov	P.P. Shirshov Institute of Oceanology
Kirk Waters and Bob Bidigare	NOAA Coastal Services Center/University of Hawaii
James Yoder and John Ryan	University of Rhode Island/Monterey Bay Aquarium and Research Institute

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Data Set	Region	п	IP	Latitude	Longitude	Months	Years
AMERIEZ	Antarctica	7	315	-66 -58	-51 -38	March-Nov.	1983-1986
SUPER	North Pacific	10	688	50 53	-145 - 145	June-Aug.	1987-1988
EqPac nonequator	Tropical Pacific	13	724	-12 12	-140 - 140	FebSept.	1996-1996
NÂBE	Northeast Atlantic	12	1027	46 47	-20 -19	April-May	1989-1989
EqPac equator	Equatorial Pacific	8	1170	0 0	-140 - 140	FebOct.	1996-1996
Arabian Sea	Arabian Sea	12	1192	10 19	57 67	March-Aug.	1995-1995
PROBES	Bering Sea	9	1203	55 58	-167 - 164	April-June	1979-1981
MARMAP	Northwest Atlantic	8	1560	40 43	-71 -67	AugSept.	1981-1981

**Table 3.** Data Sets Used to Test Algorithms<sup>a</sup>

Antarctica

Palmer LTER

<sup>a</sup> Columns are the region, number of stations (n), average depth-integrated daily production (IP, mg C m<sup>-2</sup>), and ranges in latitude, longitude, months, and years.

-65 - 65

1795

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accepted method for measuring and verifying vertically integrated production derived from discrete bottle measurements. Despite this fact, here we treat the <sup>14</sup>C-based estimates as "truth" and refer to the differences between algorithm-derived and <sup>14</sup>C-derived estimates as "errors." In all statistical analyses, however, the two are recognized as being subject to error.

[8] Participation in the round robin was solicited through a widely distributed "Dear Colleague" letter. A central ground rule was that the algorithms tested would be identified only by code numbers. The first round-robin experiment involved data from only 25 stations and was thus limited in scope. It was decided that a more comprehensive second round was needed. In this paper, we present results of the second round-robin experiment involving data from 89 stations with wide geographic coverage. Round two was open to all participants of round one, as well as to others who had responded positively to the initial invitation.

[9] The following questions were addressed: (1) How do algorithm estimates of primary production derived strictly from surface information compare with estimates derived from <sup>14</sup>C incubation methods? (2) How does the error in satellite-derived chlorophyll concentration affect the accuracy of the primary productivity algorithms? (3) Are there regional differences in the performance of algorithms? (4) How do algorithms compare with each other in terms of complexity vis-a-vis performance?

#### 2. Methods

[10] A subcommittee of NASA's Ocean Primary Productivity Working Group was formed to administer the roundrobin experiments (Table 1), and there were 10 participant teams (Table 2) who volunteered to test their algorithms. A test data set was assembled to be used for evaluating algorithms. Algorithm developers were provided with only the information accessible to spaceborne sensors, and they subsequently returned predictions of integral production at each station. Results were compared with estimates derived from the <sup>14</sup>C incubations and with the results of other algorithms.

#### 2.1. Test Data

[11] Data from 89 stations were obtained from nine sources (Table 3), representing diverse geographic regions

and a variety of measurement techniques. The acquired station data included the downwelling photosynthetic available radiation incident on the water surface (daily PAR between 400 and 700 nm, in mol photons m<sup>-2</sup>) and measurements of the chlorophyll concentration, temperature, and PAR at discrete depths in the upper water column. From the profile data, we determined surface chlorophyll ( $B_{\rm sfc}$ , mg Chl m<sup>-3</sup>), sea surface temperature (SST, °C), and the euphotic depth or 1% light level ( $Z_m$ , m).

Feb.-Dec.

-64 -64

[12] In addition, we were provided <sup>14</sup>C-based estimates of the daily primary production ( $P_i$ , mg C m<sup>-3</sup>) at discrete depths  $Z_i$  ranging from the surface to the 1% light depth. "Measured" integral production, IP<sub>meas</sub>, was computed for each station by trapezoidal integration, using the formula

$$IP_{meas} = P_1 Z_1 + \sum_{i=2}^{m} 0.5(P_{i-1} + P_i)(Z_i - Z_{i-1}), \qquad (1)$$

where the number of depths (*m*) varied among stations. Integral chlorophyll (IB, mg Chl m<sup>-2</sup>) was also computed over the same layer by a similar formula. The surface information provided to the algorithm developers and other information not provided (e.g., IP<sub>meas</sub>, IB, and  $Z_m$ ) are listed in Table 4.

[13] The measurement methods were consistent within each data set but differed between data sets. The equatorial Pacific (EqPac [Barber et al., 1996]), North Atlantic (NABE [Ducklow and Harris, 1993]), and Arabian Sea [Barber et al., 2001] data were from the Joint Global Ocean Flux Study (JGOFS) [Knudson et al., 1989; Chipman et al., 1993] process studies. Primary production measurements from these campaigns were based on 24-hour, in situ incubations, in accordance with JGOFS protocols. The SUPER data set [Welschmeyer et al., 1993] also used 24hour, in situ incubations. Simulated in situ incubations were used to produce the Antarctic Marine Ecosystem Research at the Ice Edge Zone (AMERIEZ) data (24-hour incubations [Smith and Nelson, 1990]), the PROBES data (dawn-todusk incubations [Codispoti et al., 1982]), and the Marine Resources Monitoring, Assessment, and Prediction (MAR-MAP) data (6-hour incubations scaled by daily PAR measurements [O'Reilly et al., 1987]). The Palmer data from the Long-Term Ecological Research (LTER) site [Moline and Prezelin, 1997] were based on 90-min incubations in photosynthetrons [e.g., Prezelin and Glover, 1991] that were then scaled to estimate daily rates. This methodological diversity

1991 - 1992

Station	Region	Lat.	Long.	Date	SST	PAR	Sfc. Chl	$Z_m$	IB <sub>meas</sub>	IP <sub>meas</sub>
1	EqPac nonequator	12	-140	5 Feb. 1996	25.9	25.2	0.114	85	14.2	309
2		5	-140	13 Feb. 1996	28.5	30.7	0.179	71	14.0	427
3		3	-140	15 Feb. 1996	28.4	36.2	0.210	71	16.1	670
4		$^{-2}$	-140	1 March 1996	28.6	27.0	0.132	106	16.5	586
5		-5	-140	4 March 1996	28.7	36.4	0.170	106	19.9	675
6		12	-140	11 Aug. 96	28.4	41.6	0.063	79	10.0	319
7		5	-140	19 Aug. 1996	27.5	33.7	0.284	79	22.1	561
8		3	-140	22 Aug. 1996	27.0	36.9	0.230	79	17.3	637
9		2	-140	24 Aug. 1996	23.8	38.9	0.355	79	27.7	1030
10		-2	-140	5 Sept. 1990	25.5	35.2	0.225	79	20.4	1047
12		-5	-140	8 Sept. 1990	25.9	30.8	0.274	79	20.2	861
13		-12	-140	13 Sept. 1996	26.4	30.9	0.135	79	14.6	323
14	EqPac equator	0	-140	23 Feb. 1996	28.3	14.6	0.227	71	18.9	513
15	1	0	-140	24 Feb. 1996	28.3	43.8	0.247	71	17.6	867
16		0	-140	29 Aug. 1996	24.8	36.6	0.372	79	28.8	1399
17		0	-140	30 Aug. 1996	24.9	33.2	0.257	79	25.9	1041
18		0	-140	14 Oct. 1996	25.0	33.5	0.240	82	27.9	1573
19		0	-140	16 Oct. 1996	25.3	34.6	0.218	82	25.3	1373
20		0	-140	18 Oct. 1996	25.2	32.7	0.247	82	27.5	1432
21		0	-140	20 Oct. 1996	25.1	32.7	0.242	82	23.1	1163
22	PROBES	55	-165	17 April 1979	3.5	26.3	2.21	32	78.7	1090
23		56	-167	18 April 1979	4.0	28.8	1.92	35	63.2	891
24		57	-166	22 April 1979	3.4	32.4	7.04	27	134.1	15/6
25		55	-165	6 May 1979	5.5	27.3	8.86	14	207.8	2306
20		55 59	-100	20 May 1979	5.0	55.4 50.1	4.05	28	113.1	1200
27		55	-104	6 June 1979	8.4 2.0	28.2	1.00	32 22	20.5	264
20		55	-167	1 June 1981	5.9	26.2	0.90 4 34	18	29.3 82.1	1053
30		56	-166	5 June 1981	7.5	34.3	0.68	28	33.9	214
31	SUPER	50	-145	3 June 1987	7.2	36.7	0.882	59	21.2	595
32	SOLDIC	53	-145	9 June 1987	6.9	26.4	0.659	57	36.8	671
33		50	-145	15 June 1987	7.7	48.2	0.344	60	24.4	913
34		50	-145	18 June 1987	7.4	21.5	0.531	60	27.0	1541
35		50	-145	20 Sept. 1987	11.7	35.5	0.402	56	18.9	887
36		50	-145	8 May 1988	5.6	29.1	0.270	89	26.5	366
37		50	-145	27 May 1988	7.0	36.5	0.166	69	12.1	446
38		53	-145	5 Aug. 1988	11.5	23.5	0.129	81	15.8	360
39		53	-145	19 Aug. 1988	11.8	20.2	0.191	68	14.8	479
40		50	-145	25 Aug. 1988	12.0	39.8	0.297	60	16.0	621
41	AMERIEZ	-58	-38	18 Nov. 1983	-0.1	19.9	2.97	57	146.3	502
42		-60	-38	21 Nov. 1983	-1.4	40.2	0.43	62	29.5	45/
45		-60	-38	25 NOV. 1985 27 Nov. 1983	-1.5	13.0	0.41	22	44.7	633
44		-65	-40 -48	11 March 1986	-0.7	04	4.70	70	7 1	148
46		-66	-49	16 March 1986	-1.8	73	0.08	70	7.1	105
47		-65	-51	23 March 1986	-1.8	7.6	0.07	70	57	88
48	Palmer LTER	-65	-64	10 Dec. 1991	-0.4	45.2	0.72	40	55.3	1259
49		-65	-64	16 Dec. 1991	-0.1	64.2	1.17	25	92.7	3207
50		-65	-64	28 Dec. 1991	2.2	67.1	2.52	19	184.8	6308
51		-65	-64	4 Jan. 1992	0.7	42.9	11.59	12	157.2	3894
52		-65	-64	16 Jan. 1992	0.5	33.1	0.84	35	51.5	994
53		-65	-64	24 Jan. 1992	-0.2	14.1	0.73	29	19.9	187
54		-65	-64	3 Feb. 1992	0.4	35.5	1.06	26	20.2	220
55		-65	-64	10 Feb. 1992	0.3	24.1	0.69	47	34.0	6/3
56		-65	-64	17 Feb. 1992	0.4	17.7	3.45	69	63.2	340
5/	A unit in a Car	-65	-64	27 Feb. 1992	0.2	40.8	2.43	35	58.8	808
28 50	Arabian Sea	19	0/	19 March 1995	23.5	53.4 51.4	0.041	40	20.1	132/
39 60		10	00	24 Iviarch 1995 27 March 1005	29.0 27 9	51.4 52.2	0.079	13	11.1	670
61		14	62	31 March 1005	27.0 27.1	51.5	0.078	40	10.5	841
62		17	60	3 April 1995	26.9	56.3	0.218	30	21.8	1145
63		18	58	6 April 1995	26.9	573	0.164	38	10.8	651
64		19	67	22 July 1995	28.0	40.2	0.308	61	20.8	886
65		14	65	28 July 1995	27.4	52.5	0.521	46	23.8	1455
66		10	65	31 July 1995	28.0	48.8	0.583	48	25.7	1542
67		16	62	4 Aug. 1995	25.8	53.7	0.436	48	21.1	1522

Table 4. In Situ Data Used to Test Primary Productivity Algorithms<sup>a</sup>

 Table 4. (continued)

Station	Region	Lat.	Long.	Date	SST	PAR	Sfc. Chl	$Z_m$	IB <sub>meas</sub>	IP <sub>meas</sub>
68		18	58	11 Aug. 1995	23.2	49.6	1.358	27	26.0	2141
69		18	57	12 Aug. 1995	20.7	51.4	0.569	27	17.8	1518
70	NABE	47	-20	25 April 1989	12.6	49.9	0.565	59	34.4	944
71		47	-20	26 April 1989	12.6	19.6	0.908	61	57.9	876
72		47	-19	27 April 1989	12.6	13.8	0.748	65	52.3	682
73		47	-20	29 April 1989	12.6	30.4	1.061	53	47.3	910
74		46	-20	30 April 1989	12.7	45.9	0.807	55	45.1	1286
75		46	-20	1 May 1989	12.7	13.9	0.879	59	36.5	781
76		47	-20	2 May 1989	12.5	53.6	1.066	50	48.6	1387
77		47	-20	3 May 1989	12.7	24.8	1.135	49	32.9	915
78		47	-20	4 May 1989	12.5	13.7	1.107	50	64.2	852
79		47	-20	5 May 1989	12.4	50.3	1.274	49	61.6	1402
80		46	-19	6 May 1989	13.1	27.1	0.710	49	83.8	1031
81		46	-19	8 May 1989	13.0	21.8	1.724	40	82.2	1253
82	MARMAP	41	-71	27 Aug. 1981	19.6	35.0	3.62	15	47.4	1716
83		43	-71	28 Aug. 1981	13.9	48.6	7.23	14	68.5	3482
84		43	-70	28 Aug. 1981	14.9	48.6	1.72	21	51.5	1161
85		42	-67	29 Aug. 1981	16.1	40.6	1.29	25	37.5	691
86		40	-69	31 Aug. 1981	19.4	33.2	0.52	37	51.4	1248
87		41	-70	2 Sept. 1981	14.4	40.3	3.76	22	63.0	1864
88		41	-70	2 Sept. 1981	18.7	40.3	0.64	40	32.7	1412
89		41	-71	3 Sept. 1981	18.0	21.1	0.59	40	40.7	904

<sup>a</sup> Surface and column-integrated data for the 89 stations that were used to test algorithms are given. Values are listed with the number of significant figures provided in the original data sets. Units are SST, °C; PAR, mol photons m<sup>-2</sup>; Surface (Sfc.) Chl, mg Chl m<sup>-3</sup>; 1% light level  $Z_m$ , m; integral measured chlorophyll IB<sub>meas</sub>, mg Chl m<sup>-2</sup>; and depth-integrated daily production IP<sub>meas</sub>, mg C m<sup>-2</sup>.

introduced a source of variance in the test data, and consequently in the algorithm performance statistics, that was largely confounded with regional effects. However, we accepted the diversity under the premise that a similar diversity might have existed in the data sets used to parameterize algorithms (see section 5).

[14] Integral primary production and surface chlorophyll spanned 2 orders of magnitude in the test data set, while SST and PAR varied over the wide ranges found globally (Figure 1). The symbols shown in Figure 1 denote the various data sets and regions, and these will be used consistently in subsequent figures. The widest ranges in production, biomass, and irradiance and the lowest temperatures were found in the Antarctic data (Palmer LTER and AMERIEZ). There was a general positive correspondence between IP and  $B_{\rm sfc}$ , and between IP and PAR, but there were no simple empirical relationships useful for algorithm purposes. There was no apparent relationship between IP and SST at temperatures below 20°C, but in the equatorial Pacific and Arabian Sea, where surface temperatures were above 20°C, production decreased with increasing surface temperature.

#### 2.2. Evaluation Procedures

[15] The data analysis and evaluation of algorithm results were carried out at the University of New Hampshire (UNH) under the direction of the first author with input from other members of the algorithm testing subcommittee (ATS) (Table 1). The complete test data set was assembled and resident on computers at UNH, but algorithm codes were not exchanged. That is, each participant team was responsible for running its own algorithm code based on input data furnished by the ATS. [16] The information provided for each station included (1) latitude and longitude to the nearest 0.1°, (2) day of the year, (3) incident daily PAR (mole photons m<sup>-2</sup>), (4) SST (°C), and (5) two values for the surface chlorophyll concentration (mg Chl m<sup>-3</sup>). One of the chlorophyll values (randomly assigned) was the measured surface chlorophyll ( $B_{\rm sfc}$ ), and the other was a simulated satellite-derived chlorophyll ( $B_{\rm sat}$ ) computed as

$$B_{\rm sat} = B_{\rm sfc} 10^{\Delta B},\tag{2}$$

where  $\Delta_B$  was a pseudorandom normal (Gaussian) error with zero mean and standard deviation equal to 0.3. This error represents a factor-of-2 uncertainty in satellite-derived chlorophyll that has been reported for open ocean (Case 1) waters [*O'Reilly et al.*, 1998; *Gordon et al.*, 1985]. The 89 values of  $\Delta_B$  were statistically independent.

[17] Participants did not know which chlorophyll was the measured surface chlorophyll,  $B_{\rm sfc}$ , and which was the corrupted "satellite" chlorophyll,  $B_{\rm sat}$ . They were asked to return two algorithm estimates of integral production for each station, one for each chlorophyll value. Their results were then "unscrambled" to identify the integral production estimate based on measured chlorophyll, IP<sub>alg</sub>, and that based on  $B_{\rm sat}$ .

#### 2.2.1. Performance Indices

[18] The performance of each algorithm was based on a log-difference error ( $\Delta$ ) defined as

$$\Delta = \log(\mathrm{IP}_{\mathrm{alg}}) - \log(\mathrm{IP}_{\mathrm{meas}}), \tag{3}$$

which is a measure of relative error. Performance indices were the mean (M), standard deviation (S), and root-meansquare (RMS) of the 89 log-difference errors. Since the units of these indices are decades of log, and not easily



**Figure 1.** Relationships found in in situ data between daily depth-integrated primary production (IP, mg C m<sup>-2</sup>) and properties amenable to remote sensing. (a) Surface chlorophyll concentration ( $B_{\rm sfc}$ , mg Chl m<sup>-3</sup>). (b) Sea surface temperature (SST, °C). (c) Above-water daily photosynthetic available radiation (PAR, mol photons m<sup>-2</sup>). Symbols shown here will be used consistently in all figures.

translated into absolute terms, we also present three inversetransformed values:

$$F_{\rm med} = 10^M, \tag{4}$$

$$F_{\min} = 10^{M-S},$$

$$F_{\max} = 10^{M+S}.$$

[19] Log-difference errors ( $\Delta$ ) for each algorithm tended to be symmetrically distributed about their mean and approximately normally distributed. Assuming an underlying normal distribution for  $\Delta$ ,  $F_{\text{med}}$  would be the median value of the ratio

$$F = \frac{\mathrm{IP}_{\mathrm{alg}}}{\mathrm{IP}_{\mathrm{meas}}} = 10^{\Delta},\tag{6}$$

and 68% of the F values would lie within the "one-sigma" range ( $F_{\min}$  to  $F_{\max}$ ).

#### 2.2.2. Effect of Errors in the Satellite Chlorophyll

[20] The IP<sub>sat</sub> estimate based on the simulated satellite chlorophyll,  $B_{sat}$ , was subject to two errors: the relative error

 $\Delta$  defined in equation (3) and an error due to the satellite chlorophyll error,  $\Delta_B$ , which is

$$\Delta_{sat} = log(IP_{sat}) - log(IP_{alg}).$$
(7)

[21] To investigate the effect of errors in the satellite chlorophyll,  $\Delta_{sat}$  was regressed against  $\Delta_B$ . The slope of this regression yields information about the sensitivity of the IP algorithm to errors in the satellite chlorophyll retrieval. A slope of 1 would indicate that the resulting error in IP is directly proportional to the error in  $B_{sat}$ , whereas a slope less (greater) than 1 shows less (greater) sensitivity.

#### 2.2.3. Regional Analyses

[22] To investigate regional differences, performance indices were computed for each data set separately. Although there were methodological differences between data sets, we treated the different data sets as "regions" for the purpose of this analysis. A two-way analysis of variance (ANOVA) was performed on the  $\Delta$  data to determine whether there



**Figure 2.** Scatterplots of algorithm-derived primary production (IP<sub>alg</sub>, mg C m<sup>-2</sup>) versus production measured in situ (IP<sub>meas</sub>, mg C m<sup>-2</sup>) for 12 algorithms tested. Solid line represents perfect agreement, and dashed lines represent factor-of-2 relative errors. Algorithm category [*Behrenfeld and Falkowski*, 1997b] is shown in upper left corner of each plot.

10<sup>4</sup>

10

102

10

10

10

10<sup>2</sup>

10

10

10

10<sup>2</sup>

10

IP alg

10<sup>1</sup>

IP alg

10

IP alg





Figure 2. (continued)

Table 5. Performance Indices for Relative Errors in Algorithms as Compared With Measured IP<sup>a</sup>

Algorithm	Туре	M	S	RMS	F <sub>med</sub>	$F_{\min}$	F <sub>max</sub>
1	WRM	-0.18	0.19	0.26	0.66	0.42	1.04
3	DIM	-0.01	0.22	0.22	0.98	0.59	1.61
4a	TIM	-0.09	0.25	0.26	0.81	0.46	1.43
4b	TIM	-0.11	0.21	0.24	0.77	0.47	1.26
4c	TIM	0.03	0.32	0.32	1.08	0.52	2.24
5	TIM	0.05	0.28	0.28	1.11	0.58	2.12
6	WRM	0.13	0.24	0.27	1.34	0.78	2.33
7	DIM	-0.36	0.29	0.46	0.44	0.23	0.85
8	WRM	0.15	0.23	0.27	1.40	0.82	2.38
9	WRM	-0.27	0.21	0.35	0.53	0.33	0.86
11	TIM	-0.37	0.34	0.50	0.42	0.20	0.92
12	WRM	-0.36	0.24	0.43	0.44	0.25	0.75

<sup>a</sup> Columns are the mean (*M*), standard deviation (*S*), and root mean square (RMS) of the log-difference error ( $\Delta$ ). The geometric mean and one-sigma range of the ratio (*F* = IP<sub>alg</sub>/IP<sub>meas</sub>) are given by *F*<sub>med</sub>, *F*<sub>min</sub>, and *F*<sub>max</sub>, respectively. The algorithm type is based on the categories defined by *Behrenfeld and Falkowski* [1997b].

Algorithm	RMS, %	$F_{\min}$ , %	F <sub>max</sub> , %	Correlation	Slope	Intercept
1	0.31 (+17)	0.37 (-13)	1.16 (+12)	0.99	0.50	-0.003
3	0.28 (+27)	0.50(-15)	1.80 (+11)	0.98	0.62	-0.008
4a	0.30 (+17)	0.41(-11)	1.57 (+10)	0.99	0.57	-0.001
4b	0.29 (+21)	0.42(-12)	1.41 (+12)	0.99	0.56	-0.001
4c	0.35 (+10)	0.48(-8)	2.40 (+7)	0.99	0.56	0.000
5	0.35 (+22)	0.49(-16)	2.42 (+14)	0.99	0.76	-0.003
6	0.28 (+3)	0.74(-5)	2.35 (+1)	0.94	0.30	-0.006
7	0.47 (+2)	0.22(-4)	0.95 (+13)	0.85	0.37	0.018
8	0.30 (+11)	0.74(-10)	2.56 (+7)	0.98	0.56	-0.004
9	0.39 (+12)	0.28(-13)	0.96 (+11)	0.99	0.58	-0.005
11	0.51 (+2)	0.19(-3)	0.96 (+4)	0.96	0.42	0.004
12	0.49 (+13)	0.23 (-10)	0.82 (+9)	0.97	0.53	-0.001

**Table 6.** Performance Indices When Algorithms Used "Corrupted" Satellite Chlorophyll  $(B_{sat})$  Instead of Measured Chlorophyll<sup>a</sup>

<sup>a</sup> Columns are the resulting values of RMS,  $F_{min}$  and  $F_{max}$ , and (in parentheses) the percentage change relative to the values in Table 4. The correlation, slope, and intercept are based on regressions of  $\Delta_{sat}$  versus  $\Delta_B$ .

were significant differences in algorithms, regions, and "interactions" between algorithms and regions.

#### 2.2.4. Comparing algorithms

[23] To compare algorithms, a correlation coefficient (r) was calculated from the log-transformed results, log(IP<sub>alg</sub>), for each pair of algorithms. We did not use correlations (or  $r^2$  as a measure "percent variance explained") to measure the performance of the algorithms themselves, because high  $r^2$  is not a sufficient condition for good agreement. That is, high linear correlation can exist despite systematic errors. In the case of two algorithms, however, we computed correlations and average ratios, and we also examined all pairwise plots to determine the degree of agreement. Results were considered in the context of differences in algorithm structure and complexity.

#### 3. Algorithms

[24] Twelve algorithms by 10 teams were tested in the round robin. Each participant team was assigned a code number to identify its algorithm's results in subsequent comparisons. Code numbers ranged from 1 to 12. (Teams 2 and 10 dropped out after receiving code numbers). Team 4 submitted results for three algorithms, which were identified by letters (e.g., 4a, 4b, and 4c).

[25] Although the identity of the algorithm developers is not revealed, in accordance with ground rules, paragraphs describing each of the algorithms are provided in Appendix A. Participation in the round robin was voluntary, and thus the nature of the algorithms tested was purely fortuitous. As it turned out, the algorithms belonged to three of the four major categories of complexity described by *Behrenfeld and Falkowski* [1997b]. The category not represented was that of wavelength-integrated models (WIMs). In this category, time and depth are resolved, but light is not spectrally resolved.

[26] Five algorithms (numbers 1, 6, 8, 9, and 12) were from the wavelength-resolved model (WRM) class, which is the most detailed and highly resolved of all algorithm types. In algorithms of this category, the photosynthetic rate is computed at each depth and at various times throughout the day, based on a spectrally resolved underwater light field. In some cases the vertical profile of chlorophyll was modeled (1, 8, and 9), and in others it was assumed to be uniform (6 and 12). Four of the algorithms (1, 8, 9, and 12) applied a photosynthesis-irradiance relationship to calculate the chlorophyllspecific productivity. They required parameterizations of the maximum light-saturated rate of photosynthesis ( $P^B_{max}$ ) and photosynthetic efficiency ( $\alpha$ , the slope of the  $P^B$  versus *E* curve in low light). An alternative approach, used by algorithm 6, was to calculate the radiant energy absorbed by the phytoplankton and then apply a quantum yield ( $\varphi$ , moles carbon fixed per mole photons absorbed) to derive productivity. Temperature is generally used in the parameterization of  $P^B_{max}$  or  $\varphi_{max}$ .

[27] Five algorithms (4a, 4b, 4c, 5, and 11) belonged to the class of time-integrated models (TIMs), in which depth is resolved but both time and wavelength are integrated. These algorithms employed models of the daily production normalized to chlorophyll ( $P_z/B_z$ ) as functions of the daily irradiance  $E_z$  at depth Z. Such models might resemble the photosynthesis-irradiance models ( $P^B$  versus E), as was the case for the 4a–4c algorithms, or they might be based on a



**Figure 3.** Error in satellite-derived production  $[\Delta_{\text{sat}} = \log(\text{IP}_{\text{sat}}/\text{IP}_{\text{alg}})]$  associated with a simulated error in satellite chlorophyll  $[\Delta_B = \log(B_{\text{sat}}/B_{\text{sfc}})]$  for algorithm 4b. This is typical of relationships seen for other algorithms (Table 6).

			U (	,			
Region	n	M	S	RMS	$F_{\rm med}$	$F_{\min}$	$F_{\rm max}$
AMERIEZ	7	-0.02	0.40	0.40	0.95	0.65	1.47
SUPER	10	-0.16	0.23	0.28	0.70	0.68	1.08
EqPac nonequator	13	-0.14	0.28	0.31	0.72	0.65	1.15
NABE	12	-0.07	0.30	0.31	0.84	0.69	1.25
EqPac equator	8	-0.32	0.38	0.50	0.48	0.49	1.06
Arabian Sea	12	-0.19	0.26	0.32	0.65	0.64	1.08
PROBES	9	0.06	0.23	0.23	1.14	0.84	1.33
MARMAP	8	-0.06	0.40	0.40	0.88	0.64	1.40
Palmer LTER	10	-0.12	0.25	0.27	0.76	0.69	1 1 3

0.33

0.31

Table 7. Performance Indices for Pooled Data Within Each Region (Data Set)

-0.12

quantum yield approach (5 and 11). Algorithms 5 and 11 modeled the vertical distribution of chlorophyll, whereas the 4a-4c algorithms assumed a uniform chlorophyll profile. Chlorophyll was multiplied by the modeled  $P_z/B_z$  and then integrated over the water column to estimate depth-integrated production.

89

[28] Two algorithms (3 and 7) belonged to the Depth Integrated Model (DIM) category. In these models, there was no vertical resolution of chlorophyll, light, or other properties, but rather IP was derived from integrated (IB) or average euphotic zone chlorophyll, surface PAR, and SST. Details of the individual algorithms are provided in Appendix A.

#### Results 4.

Total

### 4.1. Comparisons With <sup>14</sup>C-Based Estimates

[29] The 12 algorithms varied widely in performance (Figure 2 and Table 5). Estimates falling within a factor of 2 of the <sup>14</sup>C-based estimates are points bounded by the dashed lines in Figure 2. Many of the estimates fell within this factor-of-2 range, with the most notable exceptions occurring at Antarctic stations (open and solid triangles) and at PROBES stations in the Bering Sea (solid diamonds).

[30] Performance indices are listed in Table 5. As a benchmark, RMS values of <0.3 indicate agreement within a factor of 2. The RMS values comprise a random error (indexed by S) and a systematic error or bias, M. Most algorithms exhibited large biases as indicated by nonzero values of M, which translated to median ratios,  $F_{\rm med}$ , ranging from 0.42 (algorithm 11) to 1.4 (algorithm 8). If the biases could be eliminated, the RMS error would equal S, in which case 10 of the 12 algorithms would be within a factor of 2 (S < 0.3). It may be possible to eliminate biases by reparameterizing the underlying relationships between production, chlorophyll, and light. The sensitivity of the algorithms to model parameterization may be seen by comparing results for algorithms 4a, 4b, and 4c, which differed only in their parameterization of  $P_{opt}^{B}$  (the TIM equivalent of  $P_{max}^{B}$ ).

#### 4.2. Effect of *B*<sub>sat</sub> Error

[31] Errors in the satellite chlorophyll algorithm were simulated using a random number generator that introduced a factor-of-2 error in  $B_{\text{sat}}$ . Considering the magnitude of the  $B_{\text{sat}}$  errors, the resulting increases in IP<sub>sat</sub> errors (Table 6)

were remarkably small. Numbers in parentheses are the relative changes in algorithm performance compared with their corresponding values in Table 5. The RMS differences increased between 3 and 27%, chiefly due to increases in S, as reflected by the expanded one-sigma range of F. Algorithm 6 seemed the least sensitive to the chlorophyll errors, while algorithms 3 and 5 showed the greatest sensitivity.

0.76

0.65

[32] Regressions of  $\Delta_{\text{sat}} = \log(\text{IP}_{\text{sat}}/\text{IP}_{\text{alg}})$  versus  $\Delta_B =$  $log(B_{sat}/B_{sfc})$  provided additional insight concerning the sensitivity of IP estimates to errors in  $B_{sat}$ . The results for algorithm 4b shown in Figure 3 are typical. In all but three cases, correlations between  $\Delta_{sat}$  and  $\Delta_B$  were >0.97; all were >0.85. These high correlations reflect the deterministic nature of the relationships between  $IP_{alg}$  and  $B_{sfc}$ . For any algorithm, if  $IP_{alg}$  were directly proportional to  $B_{sfc}$ , then the regression of  $\Delta_{sat}$  versus  $\Delta_B$  would have a slope of 1. Instead, the slopes ranged from 0.30 to 0.76, indicating that errors in  $B_{\rm sfc}$  produced less-than-proportionate errors in IP. This is due, in part, to the nonlinearity of IP with respect to chlorophyll, which affects the depth of integration as well as the light-harvesting capacity of the phytoplankton. Most slopes fell between 0.5 and 0.6, which is consistent with several studies [Eppley et al., 1985; Morel and Berthon, 1989; Morel, 1988], which found that IP varies approximately as  $\sqrt{B_{\rm sfc}}$ . The algorithm having the smallest slope (algorithm 6) was the one least affected by errors in  $B_{\rm sfc}$ based on changes in its performance indices. Likewise, the two highest slopes correspond to the two algorithms (3 and 5) that showed the greatest sensitivity.

#### 4.3. Regional Comparisons

[33] Performance indices for pooled results from the nine regions are listed in Table 7. The PROBES (Bering Sea) region was the only case where the algorithms, on average, overestimated the <sup>14</sup>C-based estimates (by 14%). In all other regions the algorithms underestimated the 14C-based estimates (between 5 and 52%). The PROBES (Bering Sea) region had the lowest pooled RMS (0.23), whereas the EqPac equator had the highest value (0.50), largely because of a high negative bias (M = -0.32). No region was uniformly better or worse for all algorithms. Individual algorithm RMS values (not shown) ranged from 0.19 to 0.47 in the PROBES region and from 0.13 to 0.79 in the EqPac equator region. The Arabian Sea had the three lowest RMS values (0.07, 0.07, and 0.06, which were for algorithms 6, 7, and 8, respectively).

1.22



**Figure 4.** Scatterplots comparing algorithms 1 (WRM), 3 (DIM), 4a (TIM), 4b (TIM), and 9 (WRM).

[34] The two Antarctica regions (Palmer and AMERIEZ) appeared to have the worst results, judging from outliers in Figure 2, and yet pooled errors from these regions did not have especially high values of RMS or *M*. These regions included the lowest and highest values of primary production, as well as extremes in other variables. The apparent poor performance might actually be a result of the range in the Antarctic data causing high and low values to be more conspicuous.

[35] The two-way (regions and algorithms) ANOVA confirmed what was obvious from Figure 2, namely, that there were highly significant differences among regions  $[F(8,960) = 30.4; p \ll 0.0005]$  and among algorithms  $[F(11,960) = 80.9; p \ll 0.0005]$ . The algorithm-region interaction was also significant  $[F(88,960) = 5.7; p \ll 0.0005]$ , indicating that algorithm performances were region dependent.

#### 4.4. Algorithm Comparisons

[36] Although there were significant differences among algorithms, pairwise comparisons revealed high correlations (>0.9) in many cases. In general, the degree of correlation was unrelated to the algorithm complexity or category [*Behrenfeld and Falkowski*, 1997b]. Examples of several highly correlated pairs are illustrated in Figure 4. The two algorithms most highly correlated were 9 (WRM) and 4b

(TIM). The three best-performing algorithms of each type [1 (WRM), 3 (DIM), and 4b (TIM)] were strongly correlated with one another. From these results it is clear that the structure or complexity of an algorithm seems to have no relationship to its performance.

#### 5. Discussion

[37] Some of the variance in performance is likely due to methodological differences within the test data set itself, particularly in the diversity of <sup>14</sup>C incubation methods. Short-term incubations (e.g., the Palmer LTER data) generally approximate gross primary production, whereas longer-term (e.g., 24-hour) incubations more closely approximate net primary production. If the algorithms were parameterized to yield net primary production, then they should consistently underestimate the Palmer LTER data. From Table 7, we see that the algorithms did, in fact, underestimate Palmer data, but to a lesser extent than the JGOFS data sets (EqPac and Arabian Sea), which were 24hour incubations. There appeared to be no trends relative to the type of incubation (whether in situ, simulated in situ, or in a photosynthetron).

[38] The data furnished to participant teams did not include the year. In retrospect, we think this might have been a mistake, particularly in areas such as the equatorial Pacific where interannual variability is high and well understood. Another reason the year is important is that the "clean techniques" used for the past 2 decades generally produce higher estimates of primary production [Fitzwater et al., 1982]. These considerations would only apply if algorithms somehow adjusted for interannual variability or the technique used. Since the year of the measurement was not provided, the algorithms made no adjustment for these factors. It is interesting that the oldest data set (PROBES, 1979-1981) was the only one in which algorithms overestimated the <sup>14</sup>C-based production, a result that could be explained if the algorithms had been parameterized for clean techniques. The highest negative bias was in the equatorial Pacific, where, on average, algorithm predictions were only half the measured IP values, but these data (Eqpac equator, February-October 1996) were from a "normal" year, before the onset of the 1997-1998 El Niño. This does not explain why the algorithms would be too low, assuming they were also parameterized for normal conditions.

[39] A comparison of algorithm predictions with measurements made at discrete locations does not account for the real value of the remote sensing measurement, namely, the improved spatial and temporal coverage afforded by satellite observations. The coverage and long-term consistency afforded by remote sensing can compensate to some degree for its lack of accuracy. Ideally, both ship-based and satellite measurements will be used to monitor for changes in primary production at large scales. A robust integrative model, assimilating both in situ and remotely sensed data, will likely be required. A relatively simple technique has been demonstrated with CZCS data whereby global satellite maps are adjusted by blending them with in situ measurements [*Gregg and Conkright*, 2001]. The result is to remove biases found in the satellite products. We observed significant biases relative to the <sup>14</sup>C data and also when comparing algorithms with one another. We strongly urge that additional effort be invested to understand why algorithms differ systematically from one another and from the <sup>14</sup>C data.

[40] The round-robin experiments elicited some debate as to whether computationally complex algorithms are worthwhile. The fact that simpler algorithms (DIMs and TIMs) performed as well as or better than complex algorithms (WRMs) suggests that the computational complexity may be unnecessary and, in fact, may be ill advised given concerns about scaling (see below). However, several participants argued in favor of the highly resolved models. They maintain that computational complexity is not an issue, because of the speed of modern computers, whereas the advantage is that it links algorithms to the experimental methods, carried out at the same scales, which inform our understanding of photosynthesis in the ocean [Kirk, 1994; Falkowski and Raven, 1997]. Such detailed algorithms have a greater opportunity to incorporate future advances in remote sensing that might provide information on accessory pigments, absorption by dissolved organic matter, or fluorescence vield. So far, however, there has not been a clear demonstration that additional complexity improves the performance of algorithms.

[41] Scaling issues are potentially an important concern that should be addressed with more rigor [*Bidigare et al.*, 1992; Campbell et al., 1995]. Satellite-derived fields represent mean properties at much larger scales than the in situ data used to parameterize the algorithms. Typically, satellite-derived primary production represents the mean production over an area of at least 1 km<sup>2</sup> (often much larger) and over timescales of a week or longer. Many of the algorithms employ nonlinear relationships that were derived from measurements made at the spatial scale of an incubation bottle and at the timescale of hours. When the same models are applied to chlorophyll, light, and temperature averaged over the satellite scales, the result is not necessarily the mean primary production at the larger scale. Variance existing within the larger "averaging bin" affects the mean IP at the larger scale, but this variance is generally not incorporated into model parameterizations (for a good discussion of this issue see Trela et al. [1995]). This points to the importance of matching the scales at which the models are parameterized to the scales of the satellite products.

[42] Satellite-derived primary production is much more difficult to "validate" than many of the other derived properties such as chlorophyll or SST. The latter can be validated by obtaining in situ measurements at the time of a satellite overpass. Although the spatial scale of the in situ measurement would not match that of the pixel (1 km<sup>2</sup>), at least the two would be simultaneous. Because incubations take several hours, the in situ primary production measurement will never match the timescale of a polar-orbiting satellite. At best, one can compare the estimate for a particular day and pixel. A more elaborate validation effort would be to observe diurnal changes in chlorophyll and

light and then consider how this variability affects the satellite IP estimate.

[43] Knowledge of the vertical distribution of chlorophyll and light should improve primary productivity algorithms. The vertical distribution of light was represented in all algorithms except the DIMs (3 and 7), but only five algorithms modeled the vertical chlorophyll structure (1, 5, 8, 9, and 11). There was no evidence, however, that modeling the vertical structure was advantageous. One of the DIMs (algorithm 3), with no vertical resolution, did as well as or better than the algorithms with depth-resolved properties.

[44] Behrenfeld and Falkowski [1997a] demonstrated that the single most important parameter needed to improve algorithms is information on the maximum light-saturated rate of photosynthesis,  $P_{\text{max}}^{B}$  (or  $P_{\text{opt}}^{B}$ ). In many of the tested algorithms, temperature was used to derive this parameter, but the lack of consistency among available models suggests that temperature alone is not enough [Behrenfeld and Falkowski, 1997b]. Recently, a new  $P_{\text{max}}^{B}$  model has been developed [Behrenfeld et al., 2002] that accounts for the effects of nutrient availability and photoacclimation. For this to be applicable to remote sensing, this model still requires the development of methods to assess the nutrient status and the physical structure, but results are promising. An avenue of current research along these lines involves the use of the natural (solar-stimulated) chlorophyll fluorescence, which can be remotely sensed by a sensor with sufficient spectral and radiometric sensitivity [Letelier and Abbott, 1996]. The MODIS instrument [Esaias et al., 1998] is currently making such measurements. The fluorescence yield may be inversely related to the quantum yield of photosynthesis [Falkowski and Kiefer, 1985; Kiefer and Reynolds, 1992], and thus if reliable measures of chlorophyll, PAR, and chlorophyll fluorescence can be made, these may be used to parameterize  $P_{\text{max}}^{B}$ . A combination of satellite and in situ measurements will be needed to address these issues.

#### 6. Conclusions

[45] Conclusions related to the four questions addresseed by this study are summarized as follows:

[46] 1. How do algorithm estimates of primary production derived strictly from surface information compare with estimates derived from <sup>14</sup>C incubation methods? The 12 algorithms tested varied widely in performance. The best-performing algorithms agreed with the <sup>14</sup>C-based estimates within a factor of 2. Two of these algorithms have been adapted by NASA for producing primary productivity maps with MODIS data. Most of the algorithms had significant biases causing them to differ systematically from the in situ data. A concerted effort should be made to understand the cause of the biases and to eliminate them if possible.

[47] 2. How does the error in satellite-derived chlorophyll concentration affect the accuracy of the primary productivity ity algorithms? The relative errors in primary productivity ( $\Delta_{sat}$ ) resulting from the simulated errors in surface chlorophyll concentration ( $\Delta_B$ ) were highly correlated with  $\Delta_B$ . This fact reflects the deterministic relationship between

production and chlorophyll in the underlying models. The slopes of the regressions ( $\Delta_{sat}$  versus  $\Delta_B$ ) ranged between 0.3 and 0.8, indicating that errors in surface chlorophyll produce less-than-proportionate errors in IP.

[48] 3. Are there regional differences in the performance of algorithms? There were significant regional differences, as well as algorithm-region interactions, indicated by the ANOVA results. No one region was uniformly better or worse for all algorithms. The region with the most serious biases was the equatorial Pacific, where algorithms underestimated in situ measurements by a factor of 2.

[49] 4. How do algorithms compare with each other in terms of complexity vis-a-vis performance? Many of the algorithms were highly correlated with one another. This was not surprising, since several are based on the same models, but what was surprising was that the level of agreement had no apparent relationship to the mathematical structure or complexity of the algorithms. In some cases, complex algorithms based on depth-, time- and wavelength-resolved models were highly correlated with simpler algorithms that were time and/or depth integrated. There were distinct systematic differences between algorithms. A future effort to understand systematic differences is strongly recommended.

#### 7. Future Considerations

[50] Four of the algorithms tested are now being applied operationally to satellite data, or are planned for use with near-future missions. A third round-robin exercise is currently underway. In the third round robin, algorithms are given global fields of satellite-derived chlorophyll, SST, and PAR, and a detailed comparison of the algorithms is being conducted to determine how and where they differ.

[51] In accordance with our recommendation, future round robins will not be blind. The anonymous nature of the results presented here seriously diminishes their usefulness beyond the participants themselves. A more open approach would have facilitated detailed comparisons between algorithms to investigate, for example, why there were systematic differences (e.g., Figure 4). The only way this could have been done under the ground rules of a blind comparison would have been if the ATS ran the codes instead of the development teams. The level of effort involved on the part of the ATS was not feasible at the time this exercise was conducted.

[52] Comparisons with in situ data are also being made in the ongoing round robin. Algorithms will be compared with over 1,000 in situ measurements, all made according to JGOFS protocols. The number of stations (89) used for evaluating algorithms in the second round robin was much too small to adequately characterize the performance of algorithms. The goal of the algorithms should be net primary production, because that is what both land and ocean satellite products are intended to represent [*Behrenfeld et al.*, 2001]. Thus 24-hour in situ incubations are the preferred method.

#### Appendix A: Algorithms

#### A1. Algorithm 1

[53] This algorithm employed a photosynthesis-irradiance relationship with physiological P versus E parameters ( $\alpha$ 

and  $P_{\rm max}$ ) taken from the literature. The relationship of *Eppley* [1972] was used to compute  $P_{\text{max}}$  as a function of temperature. The spectral downwelling irradiance incident at the surface was estimated based on the 5S code [Tanré et al., 1990] and on cloudiness determined as the ratio of the given PAR to clear-sky PAR estimated from the model. Chlorophyll profiles were based on statistical models that were selected based on the upper (surface) chlorophyll concentration as an index of the "trophic level" [Morel and Berthon, 1989; Berthon and Morel, 1992]. A biooptical model, based on optical measurements made at sea, was used to propagate the radiative field through the water column. The shapes of the algal absorption spectra were derived from in vitro experiments. The magnitude of the spectra employed a statistical analysis of chlorophyllspecific absorption of algae as a function of the trophic level [Bricaud et al., 1995] and the Wozniak et al. [1992] results concerning variations in the quantum yield with trophic level [see Morel et al., 1996].

#### A2. Algorithm 3

[54] Chlorophyll concentration was assumed to be uniform over the euphotic layer, and IP was computed as:  $IP_{alg} = P^B B_{sfc} Z_m$ , where  $P^B$  is the daily primary production rate per mg chlorophyll and  $Z_m$  is the depth of the 1% light level. A simple  $P^B$  versus E model was used to compute  $P^B$  as a function of the average PAR within the euphotic layer,  $E = E_0/4.6$ . The  $P^B$  versus E model used a constant value of  $\alpha =$ 0.11 mg C (mg Chl)<sup>-1</sup> h<sup>-1</sup> (W m<sup>-2</sup>)<sup>-1</sup> from *Platt et al.* [1991] for Atlantic noncoastal waters and used a relationship in which  $P^B_{max}$  depends on SST [*Eppley*, 1972].

#### A3. Algorithms 4a–4c

[55] In these algorithms the relationship between daily carbon fixation and daily average PAR at each depth was calculated using a constant slope for the light-limited region of the water column and using various models for the maximum photosynthetic rate  $(P_{opt}^b)$ . The three versions differed with respect to the models used for  $P_{opt}^b$ . Algorithm 4a employed a seventh-order polynomial fit to empirical data as described by *Behrenfeld and Falkowski* [1997a]; algorithm 4b used a modification of the Eppley model as described by *Antoine and Morel* [1996a]; and algorithm 4c assumed a constant value of  $P_{opt}^b$  equal to 4.6 mg C (mg Chl)<sup>-1</sup> h<sup>-1</sup>. The chlorophyll profile was assumed to be constant and equal to the surface value.

#### A4. Algorithm 5

[56] In this algorithm a chlorophyll-specific absorption coefficient for PAR was modeled as a function of time of year, ranging from 0.006 to 0.015 m<sup>2</sup> (mg Chl)<sup>-1</sup>, with the maximum occurring in the summer months. The total attenuation coefficient for PAR included phytoplankton absorption, together with water and detrital attenuation, and then PAR irradiance profiles,  $E_{par}(z)$ , were derived according to Beer's Law. Chlorophyll was assumed to have a Gaussian-shaped subsurface chlorophyll maximum for surface values <0.4 mg m<sup>-3</sup> and was assumed constant with

depth, otherwise. Production as a function of depth was then calculated using an irradiance-dependent formulation for quantum yield together with phytoplankton absorption and  $E_{par}(z)$ , and production was then integrated over depth.

#### A5. Algorithm 6

[57] This algorithm calculates the spectral radiation absorbed by phytoplankton and multiplies that by a quantum yield to compute the hourly rate of primary production at each depth. The solar irradiance is split into spectral components via the 5S radiative transfer code [Tanré et al., 1990], and the spectral light field is propagated through the ocean using very simple two-stream approximations. The absorption and scattering coefficients required for this were obtained from the literature [Smith and Baker, 1981; Pope and Fry, 1997; Bricaud et al., 1995; Gordon and Morel, 1983; Petzold, 1972]. All absorption calculations were carried out spectrally and then integrated (400-700 nm). Quantum yield was calculated using a parameterization based on maximum quantum yield of  $0.03 \text{ mol C} (\text{mol quanta})^{-1}$  and a lightdependent term. The chlorophyll profile was assumed to be vertically uniform.

#### A6. Algorithm 7

[58] This algorithm is based on empirical relationships developed by the author from data obtained on many expeditions in tropical, temperate, and polar regions. The primary production data was from half-day in situ incubations, and chlorophyll was measured by spectrophotometric methods without applying a correction for phaeopigments. Estimation of the daily primary production was obtained using a "psi-based" formulation:  $IP = \psi \cdot E_0 \cdot DL \cdot IB$ , where  $\psi$  ("psi") was empirically modeled as a function of temperature for three trophic zones determined by the surface chlorophyll level.  $E_0$  was the daily incident radiation; DL was the hours of daylight, and IB was empirically modeled from the author's own data, where different models were applied depending on the surface chlorophyll level and the zone (tropic, temperate, or polar).

#### A7. Algorithm 8

[59] This algorithm employed a photosynthesis-irradiance relationship whose parameters were determined statistically for the biogeochemical province in which the station is located [*Longhurst et al.*, 1995]. Similarly, the vertical chlorophyll profile was based on statistical models of profiles for each province. Surface incident irradiance was determined based on cloudiness (in a manner similar to that used by algorithm 1). A full radiative transfer code was then used to propagate spectral irradiance downward through the water column.

#### A8. Algorithm 9

[60] This algorithm is similar to that described by *Morel* [1991]; solar spectral irradiance was estimated using the *Gregg and Carder* [1990] model with a wind speed of 4 m s<sup>-1</sup>, water vapor of 2 cm, and visibility of 23 km. Clear-sky

surface spectral irradiance was scaled to the measured surface PAR. The diffuse downwelling attenuation coefficient was estimated as the sum of the total absorption coefficient plus backscattering coefficient divided by the average cosine. Methods for estimating total absorption and backscattering are from *Morel* [1991, 1988]. The vertical profile of chlorophyll was simulated using the models of *Morel and Berthon* [1989], and the temperature dependence of  $P_{\text{max}}^B$  was based on an Eppley model as modified by *Antoine and Morel* [1996a]. A constant value of 0.033 m<sup>2</sup> (mg Chl)<sup>-1</sup> was used for the chlorophyll-specific absorption coefficient at 440 nm. Daily primary production was determined by trapezoidal integration in hourly time steps over the photoperiod and at 0.5-m-depth intervals.

#### A9. Algorithm 11

[61] This algorithm used input data on surface chlorophyll, temperature, and light and estimated vertical profiles of these three properties over the euphotic zone. The depth distributions of chlorophyll and temperature were estimated using empirical relationships derived from a large globally distributed data set. The daily production at each depth was calculated as the product of chlorophyll, the daily PAR ( $E_{par}$ ), and the chlorophyll-specific light utilization efficiency ( $\psi$ ). The chlorophyll-specific light utilization efficiency,  $\psi$ , was constrained not to exceed a theoretical maximum based on the ambient temperature.

#### A10. Algorithm 12

[62] In this algorithm the light field was spectrally and vertically resolved, but a uniform vertical distribution of chlorophyll was assumed. The algorithm calculation requires knowledge of surface chlorophyll concentration, surface light, temperature, mixed layer depth, and the concentration of a limiting nutrient. From this information, estimates of the P versus E parameters were made, and thus P was determined at each depth and integrated to estimate IP.

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