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1 Spontaneous rotations in epithelia as an interplay between cell polarity and 2 boundaries

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21 ABSTRACT

22

23 Directed flows of cells in vivo are essential in morphogenesis. They shape living matter in phenomena involving cell mechanics and regulations of the acto-myosin 24 25 cytoskeleton. However the onset of coherent motion is still poorly understood. Here we show that coherence is associated with spontaneous alignments of cell polarity by 26 27 designing cellular rings of controlled dimensions. A tug-of-war between polarities dictates the onset of coherence, as assessed by tracking live cellular shapes and 28 29 motions in various experimental conditions. In addition, we identify an internally driven constraint set by cellular acto-myosin cables at boundaries as essential to ensure 30 coherence, and active force is generated as evaluated by the high RhoA activity. The 31 32 cables are required to trigger coherence as shown by our numerical simulations based 33 on a novel Vicsek-type model including free active boundaries. We quantitatively reproduce in silico coherence onsets and we predict criteria leading to coherence. 34 35 Altogether, spontaneous coherent motion results from basic competitions between cell orientations and active cables at boundaries. 36 37

38 INTRODUCTION

39

40 Morphogenesis is driven by the interplay between Rho GTPases and the cytoskeleton ^{1–4}. In particular, the acto-myosin network drives morphogenesis at the cellular level by 41 elongation or neighbor exchange ^{5,6}, and the cross-talk between Rho signaling and 42 cellular mechanics has emerged as a generic property of morphogenetic systems. 43 44 Interestingly, these dynamics are often associated with directed motions of cells. Directional flows in epithelia are reported during development in a variety of systems 45 ranging from Drosophila to zebrafish 7-9. For example, during the development of 46 spherical mammary acini or during the egg chamber elongation in *Drosophila*, cells 47 exhibit coherent rotation on large scales with speed up to 20µm.h⁻¹ ¹⁰⁻¹³. These 48 motions are proposed to be important for the robust morphogenesis of embryos. 49 50

The collective motion of cells is difficult to understand based on a simple analysis of 1 migrations at the single cell level. Individually, cells can move randomly or directionally. 2 3 However the epithelial layers which connect cells through adherens junctions may or may not coordinate the motion of the group ^{14–16}. The understanding of emergence of 4 collective effects requires theoretical approaches in tight comparison with experiments. 5 6 In addition, although the interplay between RhoA activity and the acto-myosin cytoskeleton is documented at the single cell level ^{1,17,18}, it is not yet fully characterized 7 at the multi-cellular scale. In this context of potential collective effects, the 8 understanding of coherent motion requires to study cellular assembly in simple 9 10 geometries in vitro compared quantitatively to numerical simulations.

11 12

To this aim, we generated rings of epithelial cells, a geometry proposed by Turing in 13 his 1952 article ¹⁹. This initial condition with boundaries is distinct from former work ^{20,21} 14 15 and led to the formation of rings of connected cells, a simple and reproducible periodic 16 configuration with no confinement. This allows the characterization of the spontaneous evolution of the cellular ring. We varied the ring diameter to identify the inherent 17 coherence length of our epithelial MDCK cells. We report that below a threshold 18 19 perimeter, rings undergo spontaneous rotations. We next sought to extract the 20 ingredients generating this coherence. We show that an internal tug-of-war between cell polarities within the ring determines the onset of coherence, as shown by the initial 21 22 polarity distributions and the time required to reach coherence. Tracking of cell division as polarity breaker supports this framework. We also report that coherence is 23 associated with two supracellular acto-myosin cables at the inner and outer boundaries 24 25 of the monolayer: these continuous structures act as autonomous confinements as they exhibit high RhoA activity and are shown to prevent cells from spreading out and 26 27 breaking coherence. Finally, we test in silico our central mechanism of polarity tug-ofwar coupled to the acto-myosin cables with a Vicsek-based model writing the 28 29 fundamental laws of dynamics at cellular levels for polarity, velocity and including forces at boundaries. After calibration, we show that this computational approach 30 predicts the dynamics of all rings with no ad hoc adjustments. We also calculate phase 31 32 diagrams for coherence as a function of cellular parameters combinations. Our results 33 show that activity at boundaries – supported by RhoA activity in experiments – is indispensable to ensure cellular coherence. We propose that cell polarity tug-of-war 34 35 together with self-generated confinement from spontaneously assembled active cables set the tempo for coherent movements in epithelial monolayers. 36 37

38 RESULTS

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40 **Obtaining coherent motion**

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We first needed to identify the natural length over which cells migrate directionally -42 namely the maximal coherence length ξ_{max} - characterizing our system. A circular 43 44 array of cells is expected to undergo rotation if the maximal coherence length ξ_{max} matches the perimeter p. If the coherence length is smaller than the perimeter, non-45 coherent motion is expected ^{21,22}. To obtain ξ_{max} , we prepared multicellular rings with 46 47 free boundaries and decreasing diameters by using micro-contact printing fibronectin 48 regions and differential adhesion (see Methods) : 1000µm, 300µm and 180µm (see Movies S1 to S3, respectively), and we measured the 12-hours velocity fields (see 49 Methods). Without confinement, cells could spread out on passivated and non-coated 50

regions, and rings had different behaviors: large rings - 1000µm - exhibited growth of 1 cellular fingers inwards and outwards whereas smaller rings - 300µm and 180µm -2 3 behaved like cellular assemblies during wound healing with centripetal closure (see 4 Fig.1a and Movies S1-S3). For 1000µm and 300µm rings, we saw local coherent flows 5 of length ξ (Fig. 1b) but no global coherence. However, at 180µm diameter, about a 6 quarter of rings spontaneously rotated with a velocity of ~ 20μ m.h⁻¹, which suggested 7 that we approached the perimeter value potentially leading to coherent motion. To find this perimeter, we plotted the correlation function of tangential velocity, and we 8 9 extracted the maximal coherence length ξ_{max} (see Fig.1c, Fig.S1a and Methods) ²³. We show that ξ_{max} , obtained from the x-intersect of the tangent at origin of the correlation function, is similar in every condition $-\xi_{max} = 315 \mu m$ (Fig. 1c and Fig. S1a) 10 11 –, demonstrating that ξ_{max} is an inherent length of our cellular system. 12

13

14 Based on this ξ_{max} of 315µm, we designed and focused on rings with 80µm diameter corresponding to 250µm perimeter below ξ_{max} . As expected, we "rectified" the motion of cells around the ring and we ended up with 83% of rings spontaneously rotating at 15 16 17 a velocity of 20-25 µm.h⁻¹ (see Movie S4, Fig. 1d and Fig. S1b). All results are then reported in Figure 1e, where $\frac{\xi_{max}}{p}$, the coherence length over the perimeter, is defined 18 as an index of global coherence: it is equal to 1 when the whole ring rotates and gets 19 close to 0 as the global coherence decreases. Interestingly, there is a bias in clockwise 20 rotation which suggests a spontaneous cellular bias as reported in previous works ^{24,25} 21 22 (Fig. S1c).

23

If coherence was obtained for this 80µm ring diameter, the time needed to reach this 24 complete rotation (defined as $\frac{\xi}{p} = 1$, see Materials and Methods) varied from 1 hour to 10 hours and lasted from 1 hour to 10 hours (see Fig. S1d). This large distribution 25 26 impeded quantification of the transition from non-coherent to coherent motions. 27 Therefore, we needed to rescale the time needed to reach coherence starting from the 28 29 initial condition of continuous ring of cells. We decided to align all plots with respect to the onset of coherence defined as $\frac{\xi}{n} = 1$. We could then determine the quantitative 30 behavior of coherence acquisition. This pseudo-time representation allowed to show 31 that coherence acquisition is a process lasting about 1h30 with minor variability among 32 rings (Fig. 1f). This timescale is fast considering the 12-hours duration of the 33 34 experiment and this can be viewed as a quick switch between the two states. At 35 coherence, a continuum of behaviours appeared among the rings populations from rings with persistent rotation over hours to rings with transient coherent motion shorter 36 37 than one hour (Fig. 1f and Fig. S1d-e). To understand the origin of these dynamics, we 38 measured next the ring velocity and persistence of rotation, and saw their correlations (Fig. S1f). This suggests that collective cell speed might be involved in maintaining 39 coherence even though inertia is negligible at this scale. 40

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42 **Tug-of-war between cell polarities sets coherence**

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Next we sought to identify the cellular mechanism at play for the onset of coherent
rotation. Cell polarity is a natural readout for its key role in setting direction of motion.
We thus looked at the distribution of cell polarities inside rings. For this, we used
labeled lamellipodia (see Fig. 2a, see Methods for the measurement of polarity). We
observed selected lamellipodia orientation and direction. Initial polarities showed a bi-

modal distribution peaked around tangential directions with two main orientations, *i.e.* 1 0° and 180° (see Fig. 2b). These two states suggest that a tug-of-war between 2 3 polarities could happen between cells of opposite directions within the same ring. We 4 reasoned that initial polarities could then play a role in the time needed to reach coherent rotation. A large number of cells with the same polarities would minimize the 5 6 tug-of-war, and would decrease the time to coherence. We then followed each cell 7 polarity defined by tight-junction organisation (see Fig. 2c and Movie S5). We had 8 checked that the direction of shape anisotropy defined by cell geometry correlates with the direction of the lamellipodia (Fig. S2Aa-b). Our measurements of percentage of 9 cells with aligned polarities as a function of time to coherence show a decreasing 10 relationship (Fig. 2d). This further indicates that distribution of single cell polarities 11 imposes a tug-of-war and determines the time needed to enter coherence. We tested 12 13 this statement by inhibiting lamellipodia formation with the Arp2/3 inhibitor CK666 and this prevented coherence (Fig. S2B) by suppressing the tug-of-war between polarities. 14

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16 The co-existence of opposite polarities is expected to generate stretching within the 17 ring. From tight junctions contours, we could also extract cell elongation (Fig. 2c and Fig. S2A). Using the pseudo-time as the reference (Fig. 2e), we report three phases: 18 19 (i) 2.5 hours before coherence, cells elongate until (ii) their tangential stretch reach 20 constant values sustained for about 1 hour; (iii) coherence starts shortly within 1h 21 followed by a rapid drop in elongation (see Fig. S2). This is distinct from non coherent rings (see Fig. S2Ac). These measurements substantiate our framework: cell 22 23 lamellipodia "pull" in opposite directions leading to cellular stretch and resolution of this 24 competition induces cell stretch relaxation visualized by the rapid drop in stretch.

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Cell divisions as polarity breakers impede coherence

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To further test the central role for polarity in setting coherence, we tracked cell division 28 events within rings. Right after mitosis, cells have opposite polarities and thus are 29 expected to challenge polarity alignments. These opposite polarities indeed happened 30 at cell division within rings (see Figure 2f). We quantified the effect by plotting the 31 cumulative number of cell divisions within rings. We saw that rings where division 32 regularly occurred were related to poorly coherent motion (Fig. 2g, bottom). In contrast, 33 when a burst of many cell divisions occurred within a short time period (typically 2 34 hours over a total time of experiment of 12 hours), coherence was maintained in its 35 36 optimal value (Fig. 2g, top). Divisions generate cells with opposite polarities and 37 impede coherence (see Fig. S2Ae,q,h). Division as a polarity breaker acts as a coherence breaker. 38

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- 40

Acto-myosin cables as internally self-assembled boundaries imposing 41 42 tangential cell polarity

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So far, we reported that cells were polarized within the ring and we next sought to 44 further understand why tangential orientation was selected (Fig. 2a-b). If the rings were 45 confined by physical walls, this orientation would be favored²⁰. However, in our assay, 46 cells were free to move in any directions suggesting that an additional phenomenon 47 48 biases cell polarities. We first stained for actin and myosin since acto-myosin cables were reported to self-assemble within cells at epithelial colony boundaries ^{17,26,27} (Fig. 49 S3Aa). This generic feature was therefore expected to appear as well in our rings and 50

we hypothesized that these structures could contribute to orient cell polarity. We show
in Figure 3a the presence of these acto-myosin cables and we propose that cells
internally set their "walls" which in turn could potentially make them be oriented along
the perimeter rather than radially.

5

To test this idea, we evaluated the mechanical contributions of these cables and their 6 7 roles in cell confinement. First with live observations, we saw that the inner cable was contractile and led first to the closure of rings within hours prior to extension 'out' of the 8 cellular disk now formed (Fig. 3b, Fig. S3Ab and Movies S3-4). This suggests that 9 10 indeed inner cable pulls inwards as expected for a contracting acto-myosin cable. This dynamic was distinct from larger rings of 1mm (see Fig. 1 and Movie S1) which 11 suggests that cable curvature plays a role in cell motion ²⁸. This curvature dependence 12 was further substantiated by experiments with elliptical geometries (see Fig. S3B). 13 Then, we reasoned that the outer ring may act the same way by pushing cells inwards. 14 To evaluate whether these structures were contractile, we used laser ablation 15 experiments ²⁹. First we observed a fast and large opening of both cables within 16 seconds with a similar extent of ~ 12µm (see Figure 3c and 3d and Movie S6, see also 17 Fig. SA3b, and Methods). This demonstrates that cables are more tensile than cell-cell 18 19 junctions also tested in these experiments which yielded small openings (~ 1µm). In 20 addition, we measured the opening velocity after laser ablation as a read-out for 21 comparing stress between inner and outer cables assuming they bear the same damping coefficients ²⁹. Our results suggest that acto-myosin cables indeed apply 22 23 contractile constraints on the boundary cells and with similar values (see Fig. 3d).

24

Next, we tested the impact of this contraction at boundaries on cell polarity. We followed cells transfected with Lifeact within non labeled rings. We report in Fig. 3e and Movie S7 the interplay between cell polarity and the outer acto-myosin cable: cells could build their own acto-myosin cables while the structure imposes lamellipodia to be oriented tangentially. This supports the notion that acto-myosin cables and tangential polarity are correlated.

31

To further test this coupling, we sought to remove locally the influence of acto-myosin 32 cables. We included within rings single cells expressing caldesmon (CaD) (Fig. 3f), a 33 calmodulin binding protein inhibiting Myosin ATPase ³⁰. Indeed this triggered a local 34 decrease in myosin activity and in cable contractility. These caldesmon expressing 35 cells extended out of the rings with a radial motion (Movie S8). This further confirms 36 the key role played by the cables in confining cell polarity tangentially. This perturbation 37 also impaired rotations in the majority of cases (see Fig. 3g and Suppl. Fig. 3d). On 38 average, we found that coherence was lower on CaD mosaic rings (Fig. 3g) and this 39 40 was correlated to the amount of CaD levels (Fig. S3Ae). Altogether, this suggests that continuity of the acto-myosin rings is important for tangential motion and coherence. In 41 conclusion, cables are essential to confine and orient cells polarities tangentially and 42 further trigger rotations. 43

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45 Force is active at boundaries and cell velocity is corelated with RhoA level.

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Observations and measurements on cell dynamics could hide signaling effects
associated to regulations of the acto-myosin cytoskeleton by the small GTPase
RhoA^{31,32}. To evaluate this potential contribution, we analysed the correlation between
spatio-temporal dynamics of RhoA activity and cell dynamics. For this, we used a

FRET sensor which shows distributions of active RhoA in space and time (Fig. 4a and Ref.^{18,33}, see Methods and Fig. S4a-c). In MDCK rings, we found the largest activity at inner and outer boundaries, where acto-myosin cables are assembled (Movie S9, Fig. 4b and Fig. 3a). This supports the contractile nature of these fibers. Accordingly, we found that the closure time of rings is shorter for large FRET activities in cables (see Fig. S4d-e). We can conclude that regulation by RhoA mediates active forces at boundaries.

8

Building on this result, we sought to test whether correlation between RhoA and cell 9 velocity could be at play in the onset of coherence, knowing that cell velocity plays a 10 key role in collective cell motion. We analyzed locally and globally velocity fields and 11 their associated FRET maps (Fig. 4c and Fig. S4h, f, g, see also Methods). We found 12 13 that high velocity regions for cells were correlated with low FRET levels (Fig. 4d,e and Suppl Mat). This suggests an inverse relationship between the two quantities (see also 14 Fig S4i). Cells move faster with lower levels of FRET. This further supports the notion 15 16 that RhoA activity is essentially encoded in cell velocity.

17

18 We then turned to numerical simulations to check whether the onset of collective 19 motions could happen with basic interactions rules extrapolated from our experimental 20 results, i.e. active force at boundaries and cell velocity rule.

21 22

Numerical simulations reproduce the ring dynamics qualitatively and quantitatively

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We designed numerical simulations based on an original Vicsek type model with active 26 27 boundaries, involving parameters accessible to experiments (see Fig. 5, Fig. S5, Table 1 and Annex_Math). Cells are represented as particles with velocity v and polarity p. 28 29 Backed up by experimental observations (Fig. S5a-b), we assume that cell velocity aligns to its polarity. Cell polarity is allowed to diffuse with a coefficient D (Fig. S5d-e) 30 and aligns with the average polarity around the ring with rate μ (Fig. S5f). Cell polarity 31 32 is also assumed to align with cell velocity direction with rate v. Local springs between boundary cells dynamically describe the inner and outer cables. Active and passive 33 contributions of these cables are incorporated in the polarity dynamics. Table 1 34 summarizes data taken from experiments and inserted as an input to the model. More 35 36 details are provided in Annex Math.

37

We report in Fig. 5 the comparisons in shapes and coherence values across 38 39 conditions. The ring phenotypes are reproduced with multicellular fingers or clusters 40 for distinct colony diameters (Fig. 5a and Movie S10-13). Similarly, the coherence index is guantitatively obtained with excellent precision (see Fig. 5b) together with its 41 typical time dependence (Fig. 5c). Also, the tug-of-war between polarities correlated 42 with the time required to reach coherence for simulated rings with quantitative 43 consistency with experimental times (Fig. 5d). We also found that closure time depends 44 45 on the initial cell alignment (Fig. S6a).

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In addition, we could probe numerically the potential contribution of active forces at
cables: in our model, cables have a passive component corresponding to the stretching
and bending moduli of the acto-myosin structure, and an active component translating
the contribution of cables in setting tangential polarities (as explained above and

shown in Figure 3). Interestingly, the active component was required for the onset of coherence (Fig. 5e). We also tested the effect of having a cell with no cable within the ring, thereby modelling the caldesmon experiment (Fig. 3f): the phenotype of this cell escape was reproduced as well (Fig. 5f and Movie S14), substantiating the confinement role of cables. We checked that extremely stiff cable acted as walls like in Jain et al. and led to coherent motion (Fig. A10 and A11, Annex Math).

7

Finally, we generated phase diagrams to understand the relationship between 8 9 coherence and cell polarity and cables activity. We found the range of values necessary to trigger coherence for the main parameters of the model (cell polarity 10 alignment, cable activity and physical properties) (Fig. 5g and 5h). We show that the 11 coherence value is essentially governed by the cell polarity alignment: a large collective 12 13 alignment increases coherence (Fig. 5g and Fig. S6c-d) while the bending and the stretching moduli (passive terms) do not affect coherence initiation at least in the range 14 15 of considered parameters (Fig. 5h and Fig. S6b). However, the cables properties have 16 a strong impact on the closure time of the ring and passive and active terms have antagonist effects in this regard (Fig. S5g and S5h). 17

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19 Altogether our numerical experiments based on measured cellular parameters and 20 with basic interactions for single cells show that we can capture the main features for 21 the onset of coherence with no need to incorporate parameters other than polarity and 22 active cables at boundaries.

22

24 **DISCUSSION**

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We show that coherence of cellular movements emerges when the system size is 26 27 below the coherence length inherent to MDCK cells as reported previously on epithelial disks ^{21,22,34,35}. Cells align their polarities within the ring and this step sets the onset of 28 29 coherence. Furthermore, acto-myosin cables act as internally driven constrains confining cells tangentially. RhoA activity is larger at boundaries co-localizing with 30 cables and is inversely related to the cell maximum velocity. Finally, with these 31 32 ingredients, experimental and numerical rings share qualitative and quantitative 33 features, supporting the relevance of our minimal framework for cell interactions. We show that active forces at cables are critical to orient cell polarity and contribute to 34 35 coherence.

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7 Internally driven coherence versus externally driven coherence

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39 Emergence of coherent flows has been studied *in vitro* in confined situations ^{20–22}. Cells were chemically or mechanically confined and cannot escape their adhesive patterns 40 ^{21,22}. This led to distinct phenomena – although with similar velocities of 20 μ m.h⁻¹ -41 where the coherence is not driven only by the cellular characteristics but also by the 42 boundaries of confinement as suggested by previous theoretical works ³⁶. In Ref. ²⁰, 43 44 this led to rotations even on rings with a diameter of 1mm, far above the natural coherence length of the epithelial cell line. We reproduced this result numerically (see 45 Sec. 3.4 Annex Math) which further shows that the external walls may impose the 46 rotation for large scales. Intuitively this can be understood by the fact that cell motion 47 48 within a cohesive ring monolayer can only be tangential with solid boundary. In our case, we let cells spontaneously self-organize without confinement and we decreased 49 the pattern size to initiate the onset of coherence. This new configuration makes this 50

rotation spontaneous in essence and not guided by 3D walls which force the motion 1 along the ring. Remarkably, the symmetry of rotation clockwise-counterclockwise is 2 broken on average, in contrast to former studies in confinement²⁰ but in agreement 3 with the bias reported in other studies^{24,25,37} with potential roles for left-right asymmetry 4 during development. We make the hypothesis that chirality at the single cell level -5 6 generated by molecular structures with broken symmetry²⁵ – is conserved through scales and is translated in the emerging collective motion ³⁸. Altogether, our 7 spontaneous broken symmetry reveals inherent cellular properties which convey 8 spatio-temporal order selected by cells. 9

10

11 Coherence length and spatial scales

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13 It is interesting to analyze the potential origin of this natural coherence length. This length is distinct from former works reporting spontaneous flows of active nematics: 14 rotation was not associated with opposite senses of rotation at boundaries, and the 15 16 coherence length is higher compared to these 2D confluent monolayers. Here, cell motions are not impeded by cellular jamming seen in fully confluent monolayers³⁹. 17 Therefore, we propose that the coherence length found in our study is not expected to 18 19 be the same as that defining the crossover from rotation to active turbulence seen in 20 fully two dimensional confluent layers of cells.

21

22 In addition, the passage from single cell to tens of cells forming a new entity necessarily go through adhesion mediated by cell-cell junctions and its interplay with cytoskeleton. 23 We indeed saw that rings with MDCK cells overexpressing cadherins presented a 24 25 larger amount of rotations compared to WT MDCK cells. This suggests that larger adherence between cells either increases the coherence length or/and initiation is 26 27 facilitated due to higher cell polarization rates µ and nu. Therefore, we can conjecture that the spontaneous length could be organ dependent and contribute to the key 28 29 morphogenesis events.

30

31 **RhoA activity and its inverse relation with velocity**

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We report live activity of RhoA integrated over an entire multicellular system. With 33 coarse graining, we considered MDCK rings as a continuum material where RhoA has 34 its own dynamics and extracted FRET levels through time and space. Our results point 35 to a simplification in their connection : RhoA and velocity are inversely related (along 36 other work⁴⁰) and this allows to consider only velocities for the model. This 37 simplification would need to be further tested in other situations but it opens an 38 interesting framework with a simple relation between RhoA activity and cell velocity. In 39 40 future studies, RhoA and other Rho GTPases could be modulated through space and time using photoactivable tools to further understand its implication in collective 41 coherent motion^{41,42}. This will allow to control cell polarity and cell velocity and in turn 42 characterize the coupling between Rho signaling and cell mechanics in specific 43 44 manner with identification of new mechanosensory proteins.

45

46 Implication of coherent motions in vivo

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48 Our velocities found during coherent motion were close to the ones found during 49 *Drosophila* egg chamber development ^{10,11}. In this context, follicle cells collectively 50 rotate along the chamber and the presence of lamellipodia is reported¹⁰. This could

potentially mean that the phenomena described in this work on 2D rings, driven by cell 1 "cryptic" lamellipodia, act also during these in vivo processes. Also, coherent rotations 2 3 have been reported in various morphogenetic events in vivo in mammary acini, in egg chamber and in testis rotation in *Drosophila*^{10–13,43}. We propose that these phenomena 4 could be generic and experienced by any growing tissues as suggested also by a 5 6 recent theoretical study ⁴⁴. If right, spontaneous rotation could occur when coherence 7 lengths of each epithelial layer would be similar to dimensions of tissues. It would be 8 interesting to compare coherence lengths across model systems to evaluate whether 9 this generic property of living matter is physiological and is important for optimal 10 development.

11

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13

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23 24

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1 MATERIAL AND METHODS

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3 Micro-contact printing

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Ring motifs are patterned on glass coverslips using micro-contact printing. 5 6 Polydimethylsiloxane (PDMS; 1:10 w/w cross-linker:pre-polymer) (Sylgard 184 kit, 7 Dow Corning, cat. DC184-1.1). Stamps are produced with UV-photolithography. Stamps are rinsed with 70% ethanol and then rendered hydrophilic by exposure to 8 oxygen plasma (30s) (Diener Electronic, cat. ZeptoB). They are next incubated with a 9 10 µg/mL rhodamine-labelled fibronectin solution (Cytoskeleton, cat. FNR01-A) for 1h 10 and then dried at room temperature for about 5min. In the meantime, glass coverslips 11 are functionalized by vapour phase for 1h with 3-(mercapto)propyltrimethoxysilane 12 13 (FluroChem). After incubation of both the coverslip and PDMS, the stamp is deposited onto the glass slide and kept in contact during 30min. To ensure a proper transfer 14 15 between the two surfaces, a 50g weight is placed on the top of the stamp. Finally, the stamp is removed and the printed coverslip is washed with PBS 1X and stored in Milli-16 Q water. Non-printed areas are passivated with 0.1 mg/mL PLL-g-PEG (in 1mM 17 HEPES pH 7.4, SuSoS AG, cat. SZ33-15) for 20min at room temperature. This 18 19 approach consists in setting differential coating on the surface allowing to plate cells 20 and select cells adhering to the fibronectin printed ring.

21

22 Cell Culture

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MDCK cells stably transfected with E-cadherin-DsRED are cultured in low glucose 24 25 Dulbecco's Modified Eagle's (DMEM) with 10% Foetal Bovine Serum (FBS) and 1% Penicillin-Streptomycin. Cells are kept subconfluent (at ~ 70%). Prior experiments, 26 27 cells are detached with Trypsin-0.25% EDTA (Fisher Scientific, cat. 11570626) and centrifuged at 500rpm during 3min. The pellet is then re-suspended in DMEM 1% FBS. 28 29 This low serum concentration will further impede attachment on the passivated surface during the first hours following seeding (differential adhesion). After 1h incubation, the 30 printed surface is carefully washed out to remove cells from the non-printed area. After 31 washout, DMEM is replaced by L-15 Leibovitz Medium (Fisher Scientific, cat. 32 11540556) supplemented with 1% FBS and 1% Penicillin-Streptomycin and the 33 34 sample is incubated 1h under the microscope at 37°C before acquisition. This last 35 incubation allows cells to spread on patterns and ensures that rings are closed at the onset of the experiment. 36

37

For laser ablation experiments, MDCK stably transfected with GFP-Myosin Regulatory Light Chain (MRLC) were used. Tight junctions were imaged with a MDCK cell line genetically engineered with CRISPR-Cas9 to express ZO1-GFP ⁴⁵. We generated a MDCK cell line stably expressing the RhoA FRET biosensor using Piggy-Bac engineering. Briefly, cells were transfected with the biosensor plasmid together with a transposase. After integration into the genome, fluorescent cells were sorted with flow cytometry and kept under antibiotics pressure for 3 weeks.

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46 Transfection

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Plasmids for mosaic experiments such as Actin-GFP or Caldesmon-GFP were
incubated with cells using Lipofectamin (Invitrogen, cat. 11668030). One day prior
experiment, cells at 50% confluency in a 6-well plate were incubated for 4-6h with 1µg

of DNA and 10µL of lipofectamin mixed in Opti-MEM medium. After incubation, wells 1 are washed out and the medium is replaced by fresh DMEM 10% FBS. 2

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4 **Drug experiments**

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6 Cells were incubated with CK666 50µM (Sigma-Aldrich, cat. SML0006) during the 7 whole course of the experiment (12 hours).

For RhoA inhibition, cells were incubated 2 hours with C3-transferase (Cytoskeleton 8

9 Inc., cat. CT03-A) at a concentration of 1µg/mL. Culture medium was washed out before the start of the experiment. 10

11

Standard time-lapse microscopy 12

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14 Phase contrast images were acquired through a 10x objective (NA = 0.25) with a frame 15 rate of 1 image every 10min. Patterns were systematically checked prior the time-lapse 16 start with a standard epifluorescence lamp (FluoArc Hg Lamp) coupled with a 17 rhodamine fluorescence filter. The very same set-up was used to acquire cells during mosaic experiments (actin-GFP and caldesmon-GFP). Tight junctions (ZO1-GFP) 18 19 were imaged with a confocal microscope (Leica SP8 inverted) and an autofocus 20 system. All z-planes were taken and finally projected onto one single plane.

21

22 **Biosensor FRET activity**

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Images were acquired with a confocal microscope (Leica SP8 inverted) with the 24 25 pinhole opened to the maximum in order to increase slice thickness and the signal to noise ratio for the analysis. We used two Photo Multiplier Tubes (PMTs) as detectors. 26 27 Bandwidths were chosen as follow: 472nm-512nm for mTFP1 (CFP analog, donor) and 523nm-544nm for Venus (YFP analog, acceptor). mTFP1 was excited by an argon 28 29 laser at 468nm with 15% of power and emission for mTFP1 (donor) and Venus (FRET) were simultaneously acquired by the two PMTs. Images were then corrected and 30 processed with Biosensor Package from Danuser Lab (available on the following link: 31 32 https://github.com/DanuserLab/Biosensor). Because it is a unimolecular biosensor, no bleedthrough correction was done. Prior analysis, histograms were manually resliced 33 in order to remove high and close-to-zero boundary artefacts. 34

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36 To check whether the FRET sensor was reliable, we performed additional tests: incubation with 1.0 µg/ml C3-transferase (RhoA inhibitor, Cvtoskeleton, cat, CT04) and 37 with 1.0 µg/ml of RhoA activator (Cytoskeleton, cat. CN03). Drugs led to decrease and 38 increase of activities respectively (Fig. S4a-b). We also used a mutant sensor - F39A, 39 unable to interact with the RBD domain ¹⁸ – with the same acquisition parameters 40 41 detailed above. This was associated with a significant decrease in the FRET signal 42 (Fig. S4c).

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44 Laser ablation

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Laser ablations on acto-myosin cables were done using the FRAP module from a Leica 46 SP-5 inverted microscope. The sample was imaged and ablated through a 40x oil 47 48

- objective (NA = 1.25) and an 800nm infrared laser (80 MHz, pulsed).
- 49 50

Velocity fields and coherence length

3

Velocity fields were generated using PIVlab 1.4 and performing cross-correlations.
Windows of about a cell size, adjusted to the magnification (32x32 or 64x64 in PIVlab)
were taken. No smoothing was performed on the velocity fields.

7 Coherence lengths ξ were extracted from velocity fields with a custom-made Matlab 8 code by computing the spatial correlation function of the tangential velocity v_{θ} :

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$$C_{\nu_{\theta}}(\delta x, t) = \frac{\langle \overrightarrow{\nu_{\theta}}(\vec{x} + \delta \vec{x}, t) . \, \overrightarrow{\nu_{\theta}}(\vec{x}, t) \rangle}{\langle \nu_{\theta}(\vec{x}, t)^2 \rangle}$$

11

Exponential decays are generated from the computations of $C_{v_{\theta}}$ and the intersections between the tangents at origin and x-axis give ξ . Because $C_{v_{\theta}}$ was not always converging to 0, we made linear fits on the 3 first points of $C_{v_{\theta}}$ in order to extract the tangent at origin.

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We selected ξ_{max} to capture the largest length accessible to the cells. To extract this maximal coherence length ξ_{max} presented in Figure 1c and Fig. S1a, velocity fields were averaged over intervals of 10 frames (100min) and the time interval leading to the largest correlation function was considered. Stated differently, we isolated the time window during which the coherent motion was optimal and extracted the associated length over experimental conditions.

24 Image processing

Nuclei in RhoA ratiometric maps were removed using Ilastik and phase contrastimages were processed with Fiji.

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29 Cell polarity was defined by its lamellipodium: the axis nucleus-lamellipodium sets 30 direction and orientation for cell polarity. Since many factors could contribute to define physical polarity and because lamellipodia are not always observable, we decided to 31 track ZO1 marked cells – not in their anisotropy of signal – but for the well-defined 32 33 shapes. In majority of cases, cells could be associated to isocele triangles. Therefore, cell polarity was given by the long axis of the triangle while the sense was defined by 34 the triangle base. We confirmed that this polarity was consistent with the polarity 35 defined by lamellipodia in the large majority of cases (Fig. S2a-b). Segmentation and 36 extraction of single cell parameters in ZO1 experiments were done using Tissue 37 Analyzer ⁴⁶ in Fiji. 38

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40 **Model**

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We designed a mechanistic-based minimal "Vicsek—type model" in which cells are treated as particles with polarity **p** and velocity **v**, initially placed on a ring with two layers of cells matching the cell density and number tested in experiments. Their interaction rules are determined by alignment of polarities and by polarity relaxation to the direction of motion and by random fluctuations of polarities (see Annex Math for details). Velocities are also projected on the directions of polarities to the limit of volume exclusion. The inner and outer supra-cellular acto-myosin cables are modeled as segments connecting boundary cells with two physical elastic properties, stretching and bending energies. In addition to the force exerted by the cables on the cells and its velocities, cables also act on cell polarity. The values of parameters are extracted from measurements and from estimates based on references (see Annex Math and Table 1).

We show (see Fig. 5e) that with this passive treatment of cables and actual experimental values, we do not recapitulate coherent motion. Based on the Rho activity at both cables supporting an active stress generation, we add in the model an active cable force with estimates of the associated experimental values. Simulations based on the theoretical model reveal that cells undergo coherent motion for small rings. Moreover, when we increase the ring diameter keeping the same values for parameters, we reproduce the experimental dynamics with no further adjustments. These results support the relevance of our model.



4 5 Figure 1. Acquisition of coherent motion. (a) MDCK rings of various diameters at initial time t₀. (b) Coherent flows can be extracted from the velocity fields. A coherent 6 flow of length ξ is highlighted in green. Time in hh:mm; Scale bar = 50µm. (c) Average 7 8 correlation functions of tangential velocity v_{θ} for each ring diameter. The angle θ corresponds to the polar coordinate on the ring. (d) 80µm ring with a perimeter below 9 the coherence length undergoes spontaneous rotation. (e) Index of global coherence 10 $\frac{\xi_{max}}{2}$ for each ring diameter. 80µm rings are "rectified" and the majority of rings are 11 coherent $(\frac{\xi_{max}}{p} = 1)$. $n_{1000} = 11$; $n_{300} = 20$; $n_{180} = 20$; $n_{80} = 24$. Medians are shown as 12 lines in the boxplot. (f) Temporal sequences are aligned on the coherence acquisition 13 $(\frac{\xi}{n}=1)$ along a new pseudo-time. The red line corresponds to the mean of all 14 experiments. Coherence is a non-linear process taking place within ~1h30. 15



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2 Figure 2. Cell polarity and density determine dynamics of coherent motion. (a) 3 80µm "mosaic" ring. Arrows indicate cell polarity based on the direction/orientation of 4 cell lamellipodium. Scale bar = 50μ m. (b) Distribution of cell initial orientations within 5 the rings. 0° (counter clockwise) and 180° (clockwise) correspond to tangential 6 orientations. n_{rings} = 12, n_{cells} = 42. (c) Segmentation of multicellular rings based on ZO1 7 distributions. Single cell parameters such as cell elongation (stretch) can be extracted, 8 red and blue largest and lowest stretch respectively. Scale bar = $50\mu m$. (d) Percentage of aligned cells based on the polarity given by ZO1 distributions. Data are binned with 9 respect to the time of coherence onset. Data are represented as Mean \pm SD. N = 10. 10 (e) Average normalized stretch (initial/max) aligned along a new pseudo-time. The 11 12 dashed blue line corresponds to coherence acquisition. Data are represented as Mean \pm SD. N = 10. (f) Division of an actin-GFP labeled cell within a 80µm ring. Cell division 13 generates daughter cells with opposite polarities p_1 and p_2 . Scale bar = 20µm. (g) 14 Cumulative cell divisions as a function of time. Coherent rings exhibit bursts of divisions 15 with large periods without divisions whereas non-coherent rings undergo regular 16 divisions throughout the course of the experiment. For clarity, only 5 representative 17 rings are shown for each case. Full population is available in Fig. S2A. 18

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3 Figure 3. Acto-myosin cables as internally-driven constraints. (a) Immunostaining 4 of a 80µm ring. Myosin and actin are visualized. (b) Tracking of the ring boundaries. 5 The color code indicates time. The ring first closes inwards before extending outwards. 6 (c) Kymographs showing acto-myosin ring retraction after laser ablation and cell-cell 7 junction opening (as a control) after ablation. (d) Retraction velocity as a function of 8 time after laser ablation. Exponential fits give estimates of v₀ defining the relative tension stored in the ring. (e) Actin vizualisation (lifeAct) of a transfected cell within a 9 10 80µm ring. The acto-myosin cable is self-generated by the cell during motion and constrains the polarity in a tangential orientation. White arrow indicates the cable, 11 green contour underlines the lamellipodium boundary. Scale bar = 20µm. (f) Time-12 lapse showing a CaD transfected cell (white arrow) escaping the multicellular ring and 13 challenging coherence. Scale bar = 50µm. (g) Coherence acquisition for non-14 transfected ring and rings with CaD transfected cells. There is a significant decrease 15 in coherence ($p = 7.10^{-4}$) in the CaD rings. 16



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3 Figure 4. RhoA activity correlates with different ring behaviors. (a) RhoA activity on a 80µm ring as described by the FRET ratiometric map (left) associated to a velocity 4 5 field (right). Scale bar = 50µm. (b) Temporal maximal projection showing highest FRET 6 signals at ring boundaries. Scale bar = 50µm. (c) FRET map for each frame is 7 represented with its associated velocity field. Scale bar = 50µm. Comparison is shown in (d) where high FRET regions correlate with low velocity. (e) Maximum velocity of the 8 9 ring (with both radial and tangential components) is represented as a function of the averaged FRET level integrated over the entire experiment. (f) FRET intensity at to 10 averaged over the cellular "bulk" excluding cables. Initial levels of RhoA activity are 11 plotted for different coherent behaviors. High activity is correlated with low coherence. 12 13 Data in (e) are binned; full distributions are shown in Fig. S4h. Same color codes for (a), (b) and (c) for FRET signals. 14

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Figure 5. Theoretical modelling of multicellular rings. Experiments are compared 4 with simulations. (a) Rings of different diameters are represented (top) when typical 5 motifs appear, fingering for large diameters, clusters for intermediate rings, closure for 6 smaller rings. Morphology is reproduced by numerical simulations (bottom). Scale bar 7 = 50 μ m. Time in hh:mm; simulations times (in hh:mm, from left to right): 05:24; 17:56; 8 04:00; 04:57. (b) Coherence index as a function of ring diameters for simulations and experiments, with an inset comparing median values. (c) Dynamics of coherence 9 10 acquisition in silico compared with a typical MDCK ring. (d) Initial polarity correlation as a function of the time of coherence acquisition. The decay observed in experiments 11 is similar to simulated rings. (e) Coherence index for two different populations of MDCK 12 rings: activity within cable facilitates acquisition of coherence. (f) Caldesmon 13 experiment and cellular 'escape' are reproduced with simulations. The yellow particle 14 represents the CaD cell and its cable parameters are set to zero. Scale bar = 50μ m. 15 Time in hh:mm. Simulation times (in hh:mm, from top to bottom): 05:20; 13:03. (g-h) 16 17 Phase diagrams for coherence with respect to the dimensionless parameters associated with the model (active cable force - active alignment, active cable force -18 passive cable force). Index p refers to the passive component of the cable while a 19 corresponds to the active one. On each plot, each point of the surface corresponds to 20 the average value of 50 simulations. 21 22

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