



# Magnet failure-resilient control of a direct-drive tidal turbine

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# CALIBRATING AND MEASURING WAKES AND DRAG FORCES OF INLAND VESSELS IN CONFINED WATER IN A TOWING TANK.

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## SUMMARY

This paper gives a review of the experimental methods developed in the towing tank of the Pprime Institute of the University of Poitiers, France, for the characterization of ship wakes and drag forces in confined waters. Different waterway configurations in calm water and in the presence of a current are reproduced in the experimental facility and small scale ship models of different block coefficients are considered. Stereoscopic optical methods have been developed in the laboratory for the measurement of the free surface deformation around the ship. The full wake generated by the ship is fully characterized and its hydraulic and undulatory properties are analyzed in both real space and spectral domain. In addition, a system for the measurement of the ship drag force has been set up and visualizations of the wakes have been performed in parallel with a high-speed camera, to relate the ship resistance crisis with its visual footprint in the wake.

## NOMENCLATURE

$\alpha_b$	Banks inclination angle (°)
$A_{FFT}$	Normalized amplitude of the Fast Fourier Transform of the ship wake (-)
$A_I$	Normalized amplitude of the transverse waves in calm water (-)
$A_2$	Normalized amplitude of the transverse waves in counter-current (-)
$B$	Beam (width) of the ship hull (m)
$C_b$	Block coefficient of the ship hull (-)
$C_d$	Drag coefficient of the ship hull (-)
$D$	Draft of the ship hull (m)
$F_{h1}$	Critical Froude number (sub.→trans.) (-)
$F_{h2}$	Critical Froude number (trans.→sup.) (-)
$F_{h,s}$	Froude-depth number of the ship (-)
$F_{L,s}$	Froude-length number of the ship (-)
$F_X$	Axial component of ship resistance (N)
$g$	Gravitational acceleration (m.s <sup>-2</sup> )
$H$	Height of the ship hull (m)
$h$	Water depth (m)
$h_b$	Height of the inclined bank (m)
$h_{bottom}$	Height of the double bottom (m)
$I$	Expanded uncertainty ( $k=2$ ) of the ship resistance measurement (N)
$k_{x,y}$	Wavenumber along the $x$ (longitudinal) or $y$ (transversal) axis (m <sup>-1</sup> )
$L_s$	Length of the ship (m)
$L_c$	Length of the canal (m)
$L_1$	Normalized length of the wash zone in calm water (-)
$L_2$	Normalized length of the wash zone in counter-current (-)
$\lambda_{t,1}$	Normalized wavelength of the transverse waves in calm water (-)
$\lambda_{t,2}$	Normalized wavelength of the transverse waves in counter-current (-)
$m$	Blockage ratio of the waterway (-)
$\rho$	Density of water (kg/m <sup>3</sup> )
$S_w$	Wetted surface area of the ship (m <sup>2</sup> )
$U_s$	Ship speed (m.s <sup>-1</sup> )
$u_c$	Velocity of the river current (m.s <sup>-1</sup> )
$u_r$	Velocity of the return current (m.s <sup>-1</sup> )
$W$	Large width of the waterway (m)

$w$	Small width of the waterway (m)
$w_b$	Width of the inclined bank (m)
$X$	Longitudinal dimension of the wake (m)
$\Delta X$	Spatial resolution along the X axis (m)
$Y$	Transversal dimension of the wake (m)
$\Delta Y$	Spatial resolution along the Y axis (m)
$Z$	Vertical dimension of the wake (m)
$\Delta Z$	Spatial resolution along the Z axis (m)

## 1 INTRODUCTION

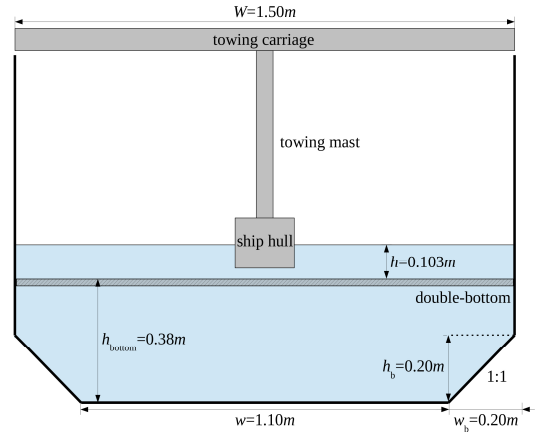
When a ship progresses in a confined waterway, such as a river, a canal or an estuary, it faces an increase in the advancing resistance and also experiences various phenomena in the waterway. There is a lowering of the water level, combined with the generation of a return current around the ship hull. The waves generated in its wake interact with the current of the waterway and reflect on the river banks, causing erosion and sediment transport issues. To prevent their appearance in the waterway, for both economical (reduce fuel consumption) and ecological (reduce bank erosion) reasons, many numerical studies are performed (Linde *et al.*, 2017; Pacuraru and Domnisoru, 2018; Razgallah *et al.*, 2018; Terziev *et al.*, 2018). However, the specific properties of the confined water wakes are not completely described numerically or theoretically. Experimental investigations are still necessary to understand the generation and the propagation of the waves and the flow with respect to the functional and geometrical parameters of the ship and the waterway. This path of research has been investigated in the past few years by the Hydrodynamic and Environmental Flows team of the Pprime Institute of the University of Poitiers in France. A configuration of confined waterway with a presence of current has been reproduced in the towing tank of the laboratory. Several experimental methods have been developed for the measurement of the ship resistance, the characterization of the return current around the hull, the study of the wave reflections and the full-field characterization of the generated ship wake. To investigate the properties of the waves generated by the hulls, a fine characterization of the free surface is indispensable to lead the analysis in the spectral domain. On the basis of the theory of the waves generated

by a uniformly moving source established by (Ekman, 1906) and (Crapper, 1964) and the recent review of the geometrical properties of the emitted patterns in the real and spectral spaces by (Carusotto and Rousseaux, 2013), a spectral analysis method of ship wakes has been developed. Such spectral analysis methods have been proposed by (McKenzie, 1970) and (Lighthill, 1979). (Griffin et al., 1996) and (Arnold-Bos *et al.*, 2007) have used them to estimate the velocity of a ship or the shape of its hull from synthetic aperture radar (SAR) images or high resolution optical images of the wake. However, these methods have never been validated experimentally in the field of ship wakes measured in the laboratory. In the first part of the paper, the waterway configuration set up in the towing tank of the Pprime Institute is presented and the small scale ship models representative of maritime and river ships are introduced. In the second part, the experimental measurement methods are detailed and the spectral analysis method is detailed. Then, the main results of the studies are presented and finally research perspectives will be exposed with the future project of development of the canal.

## 2 THE TOWING TANK AND THE SHIP MODELS

### 2.1 THE WATERWAY

Figure 1 represents the cross-section of the towing tank of the Pprime Institute. It is composed of a bottom trapezoidal section of small width  $w=1.10\text{ m}$  and large width  $W=1.50\text{ m}$ , and a top rectangular section of same width. The inclination of the banks is  $\alpha_b=45^\circ$  and their width and height are  $w_b=h_b=0.20\text{ m}$ . A double bottom of height  $h_{\text{bot}}=0.38\text{ m}$  can be installed in the towing tank to reduce the water depth to reproduce a shallow waterway of rectangular cross-section of depth  $h$ . The water depth has been set up to  $h=0.103\text{ m}$  for the experiments. The rail mounted towing carriage displaces the ship hull at a speed  $U_s$  up to  $2.35\text{ m.s}^{-1}$  along the canal of length  $L_c=20\text{ m}$ . The double-bottom gives also the possibility to generate a current by placing a circulator in the lower section, and two honeycombs structures at the extremities of the canal to laminarize the flow. The current can be generated in both directions with respect to the ship motion (co- or counter-current). The canal is equipped with bottom and lateral windows to perform optical measurements and visualizations.

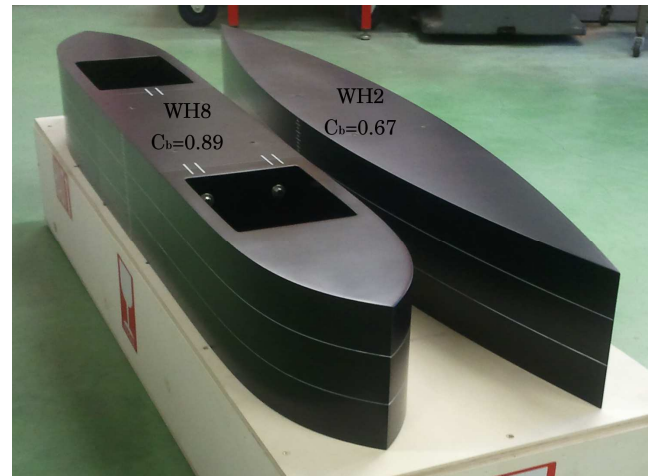


**Figure 1.** Transversal section of the towing tank.  
2.2 THE SMALL SCALE SHIP MODELS

In order to compare the experimental results with numerical calculations of ship wakes and ship resistance, two generic ship hulls of parabolic shape have been considered. They are based on the Wigley (1926) hull form with a rectangular cross-section, mathematically defined by Eq. (1) with  $n=2$  for a classical Wigley hull:

$$y = f(x) = \frac{B}{2} \left[ 1 - \left( \frac{2x}{L_s} \right)^n \right] \quad (1)$$

As the block coefficient of such a Wigley hull is  $C_b=0.67$ , another Wigley-based ship hull with an exponent  $n=8$ , giving a block coefficient  $C_b=0.89$ , has been considered (Caplier *et al.*, 2016). These two ship hulls noted WH2 and WH8 because of their  $n$ -coefficients are then representative of maritime and river ships in terms of block coefficients. The ship hulls dimensions are  $L_s=1.20\text{ m}$ ,  $B=0.18\text{ m}$  and  $H=0.15\text{ m}$ , and their draft is set-up to  $D=0.075\text{ m}$  for the experiments. They are shown on Figure 2. As regards the effects of scale, the ship speeds for the experiments are set high enough to avoid capillary effects (less than 5%). In this range of ship speeds, the effects of the scale on the flow characteristics are limited (Gomit *et al.*, 2015).



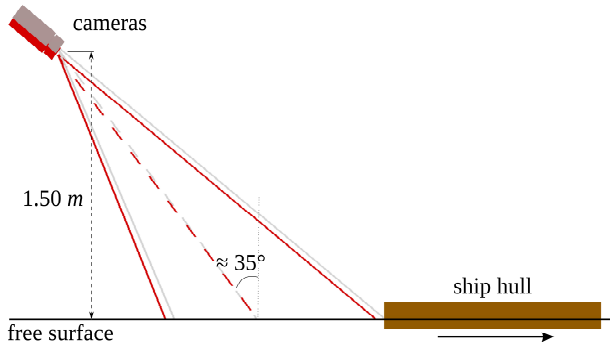
**Figure 2.** The WH8 and WH2 ship hulls.

## 3 THE MEASUREMENT AND THE ANALYSIS OF THE SHALLOW WATER SHIP WAKE

### 3.1 MEASUREMENT OF THE FREE SURFACE DEFORMATION

The free surface deformation is measured with a stereoscopic measurement method, based on the principle of refraction of light rays through the surface of water that is developed in our laboratory (Gomit *et al.*, 2013). The setup is represented on Figure 3. It is composed of two Dantec SpeedSense 1040 cameras that deliver a resolution of  $2320 \times 1726$  px, mounted with Nikkor AF 28 mm 1:2.8 lenses. They focus on the same zone with an opposite angle of  $\pm 15^\circ$  with respect to the longitudinal axis of the canal, and  $\pm 35^\circ$  with respect to the vertical axis. The common field covered by the cameras forms a rectangle of dimensions  $0.75 \times 0.90$  m<sup>2</sup>, corresponding to the half width of the canal. The stereoscopic system is calibrated by translating a dotted calibration plate and using a distortion model. A speckle-pattern is placed at the bottom of the canal and its image with the water surface at rest is recorded on the cameras for the reference. Then the ship is launched and the images of the pattern, deformed by the free surface deformations, are recorded on both cameras at a frequency of 10 frames per second with an exposure time of 10 ms. Each run is performed three times to check the repeatability of the measurement. The image pairs are then processed with a reconstruction algorithm written in C++ and based on the SLIP library (Tremblais *et al.*, 2010) that computes the free surface deformation at each time-step. Then the whole wake is reconstructed around the ship hull with a dedicated reconstruction program, with a spatial resolution  $\Delta X = \Delta Y = 10$  mm and a precision  $\Delta Z = 0.1$  mm on the water level.

Lateral view :



### 3.2 ANALYSIS IN THE REAL SPACE

An example of the wakes measured in calm water and in the presence of a counter-current with the stereo-refraction measurement method are shown on Figure 4 (Caplier *et al.*, 2015). These wakes are generated by the WH2 hull for a ship speed  $U_s = 0.45$  m.s<sup>-1</sup> and a water depth  $h = 0.103$  m, giving a Froude-depth number  $F_{h,s} = U_s / (gh)^{1/2} = 0.45$  and a Froude-length number  $F_{L,s} = U_s / (gL_s)^{1/2} = 0.13$ . The wake on the bottom of the figure is generated in a calm water configuration, whereas the top one is generated in the presence of a counter-current of velocity  $u_c = 0.20$  m.s<sup>-1</sup>, corresponding to an effective Froude-depth number in the referential of the laboratory  $F_{h,s} = (U_s + u_c) / (gh)^{1/2} = 0.65$  (Caplier *et al.*, 2015). A qualitative analysis of these wakes in the real space shows that the transverse wavelength and amplitude are increasing in the presence of the counter-current. The waves generated by the ship in its wake are convected by the current, that results in a widening of the wash zone at the banks of the canal. For a quantitative comparison of the wakes, longitudinal or transverse cuts can be made in the wave fields. Figure 5 represents the longitudinal cuts performed for the calm water and counter-current wakes. For the same ship speed, the length of the wash zone increases from  $0.9L_s$  to  $2L_s$  ( $L_s = 1.2$  m is the ship length) with the counter-current, representing more than a doubling of its length. The transverse waves amplitude and wavelengths at the river banks respectively grows from  $A_1 = 0.012h$  to  $A_2 = 0.059h$  ( $h = 0.103$  m is the initial water depth), and from  $\lambda_{t,1} = 0.1L_s$  to  $\lambda_{t,2} = 0.3L_s$ , an increase of nearly 500% of the amplitude and 30% of the wavelength.

Top view :

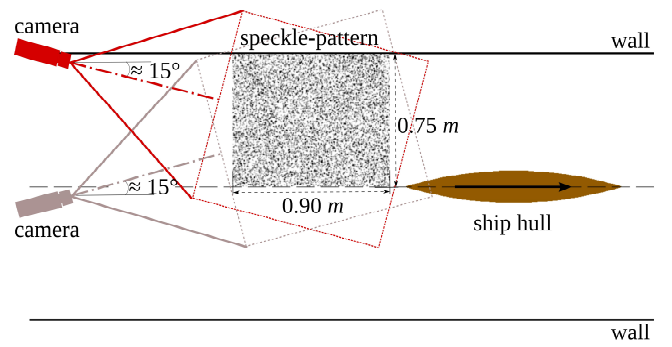


Figure 3. Schematic representation of the experimental setup for the free surface measurement by stereo-refraction.

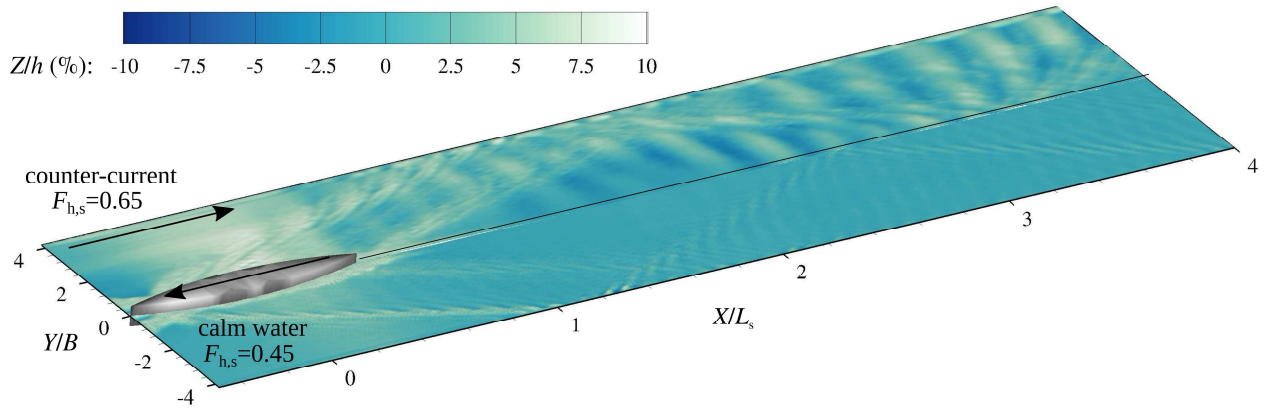


Figure 4. The wakes generated in calm water (bottom) and in the presence of a counter-current (top) by the WH2 hull, measured with the stereorefraction measurement method.

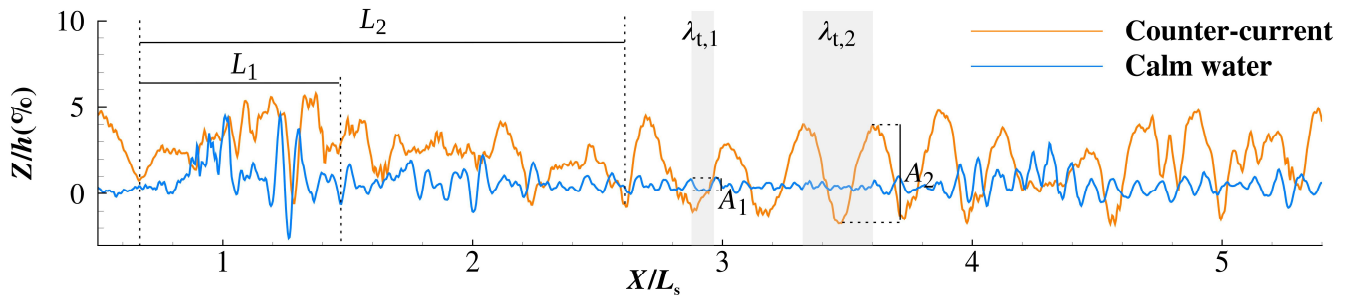
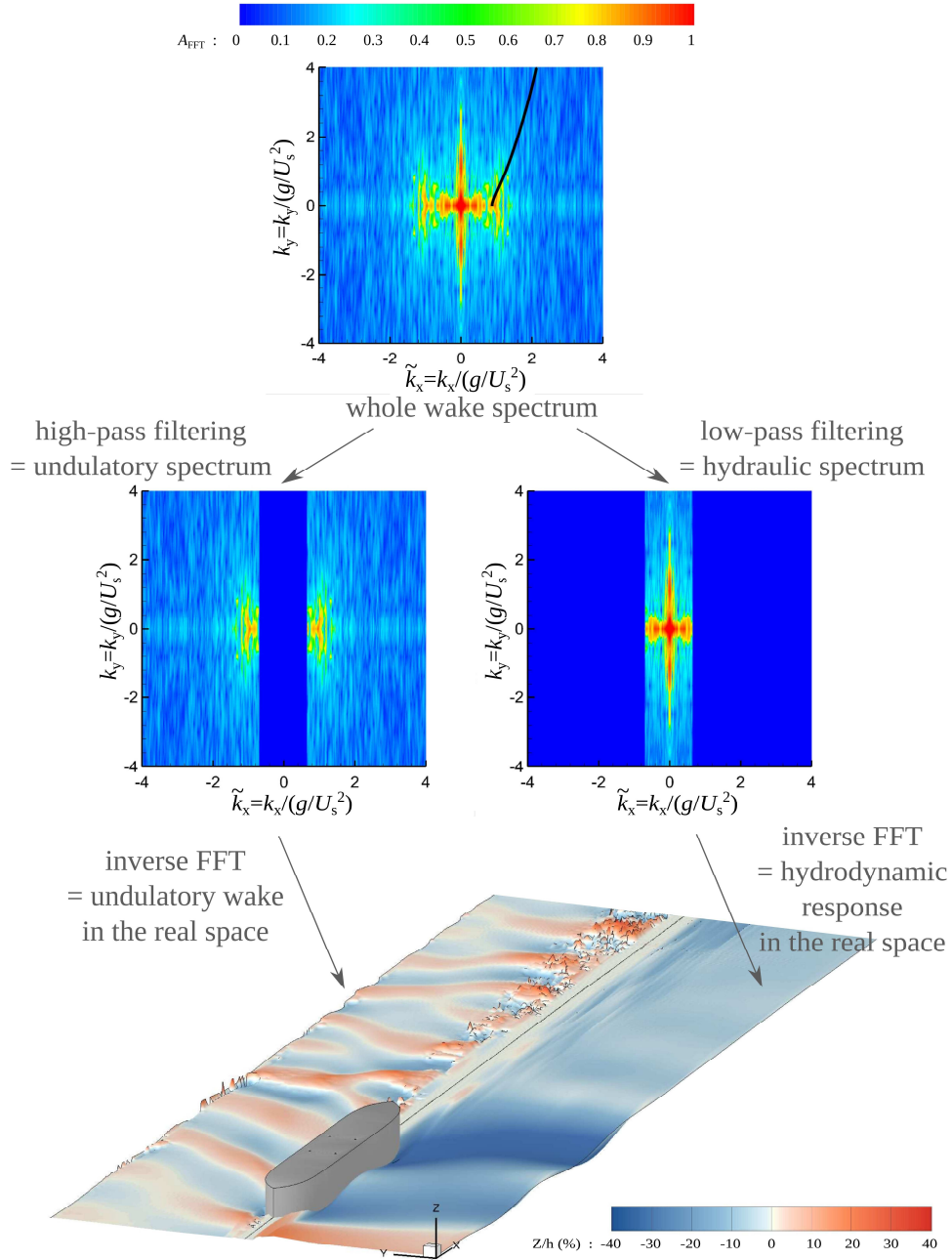


Figure 5. Longitudinal cuts in the wakes generated in calm water and in the presence of a counter-current at a transversal position  $Y/B=3.5$ . ( $L_1$  ;  $A_1$  ;  $\lambda_{t,1}$ ) and ( $L_2$  ;  $A_2$  ;  $\lambda_{t,2}$ ) represent respectively the width of the reflection zone, and the amplitude and the wavelength of the transverse waves, in calm water and in counter-current.



**Figure 6. Spectral analysis of a ship wake. The top figure represents the spectrum of the wake generated by the WH8 hull in a calm and shallow water configuration for a Froude-depth number  $F_{h,s}=0.80$  and a Froude-length number  $F_{L,s}=0.23$ . Then the spectrum is filtered to separate the hydraulic and undulatory components of the wake, which are reconstructed in the real space by computing the inverse bidimensional FFT.**

### 3.3 SPECTRAL ANALYSIS OF SHIP WAKES

The stereo-refraction measurement method gives a full, detailed and fine reconstruction of the ship wake. Then, it is possible to proceed the analysis in the spectral space by computing the bidimensional Fast Fourier Transform (FFT) of the wake. The method has been introduced by (Carusotto and Rousseaux, 2013), developed by (Gomit *et al.*, 2014) for the analysis of ship wakes in deep water and then adapted by (Caplier *et al.*, 2016) for the analysis of ship wakes generated in shallow water.

An example of the spectrum of the wake generated by the WH8 hull, for a ship speed  $U_s=0.80 \text{ m.s}^{-1}$  and a water depth  $h=0.103 \text{ m}$ , giving a Froude-depth number

$F_{h,s}=U_s/(gh)^{1/2}=0.80$  and a Froude-length number  $F_{L,s}=U_s/(gL_s)^{1/2}=0.23$ , is given on the right of Figure 6 (Caplier *et al.*, 2016). The color on the spectrum represents the spectral repartition of the normalized amplitude of the FFT along the different wave lengths and directions in the wake. The high-pass or low-pass filtering of the spectrum and its reconstruction in the real space by computing an inverse bidimensional FFT allows to separate the hydraulic and undulatory components of the wake (Gomit *et al.*, 2014) (Caplier *et al.*, 2016).

### 3.4 MEASUREMENT OF THE RETURN CURRENT

The stereoscopic system can also be used to measure the return current generated around the hull, by computing the displacements of floating particles placed at the surface of the water. The images of these markers can then be processed by a stereo-PIV algorithm to calculate the flow velocity (Chatellier *et al.*, 2013). The result is given on Figure 7 on which the return current is measured around the WH2 hull for a ship speed  $U_s=0.70 \text{ m.s}^{-1}$  and a water depth  $h=0.103 \text{ m}$ , giving a Froude-depth number  $F_{h,s}=U_s/(gh)^{1/2}=0.70$  and a Froude-length number  $F_{L,s}=U_s/(gL_s)^{1/2}=0.20$ . The return current is calculated in the whole field around the hull, it reaches its maximum of amplitude (30% of the ship speed) at the middle of the hull, and extends along the whole width of the waterway. Then its direction alternates between the crests and troughs of the transverse waves, and its amplitude decreases slowly.

#### 4 THE SHIP RESISTANCE AND ITS VISUAL FOOTPRINT

Resistance trials have been carried out in the towing tank of the Pprime Institute. The measurement of the ship drag force is performed with a Kistler 9272 multi-component dynamometer installed between the ship hull and the towing mast (Figure 8). The six-component piezoelectric sensor measures the axial forces in each direction as well as the torques. The ship resistance is taken as the axial force  $F_X$  opposed to the motion of the ship. The maximum measured amplitude is  $F_X=20 \text{ N}$  and the uncertainty is  $I=0.80 \text{ N}$  (Caplier, 2015). Then the non-dimensional drag coefficient  $C_d$  can be derived with Equation 2, where  $S_w$  is the wetted surface area of the ship:

$$C_d = \frac{F_X}{\frac{1}{2}\rho S_w U_s^2} \quad (2)$$

Figure 9 represents the drag coefficients of the WH2 and WH8 hulls measured in a shallow water configuration ( $h=0.103 \text{ m}$ ) at different ship speeds (the Froude-depth number of the ship  $F_{h,s}$  is between 0.60 and 1.31, and the Froude-length number of the ship  $F_{L,s}$  is between 0.18 and 1.38). The evolution of the ship resistance is bounded by

the critical Froude-depth numbers  $F_{h1}$  and  $F_{h2}$  calculated by Schijf's theory (Schijf, 1949). These critical Froude-depth numbers are calculated by Equations 3 and 4:

$$F_{h1} = \left[ 2 \sin \left( \frac{\arcsin(1-m)}{3} \right) \right]^{\frac{3}{2}} \quad (3)$$

$$F_{h2} = \left[ 2 \sin \left( \frac{\pi - \arcsin(1-m)}{3} \right) \right]^{\frac{3}{2}} \quad (4)$$

They depend on the blockage ratio  $m$  (cross section of the ship to cross section of the canal). In the present experiments,  $m=0.0874$ . A sudden increase of the drag coefficient is observed for  $F_{h,s}=F_{h1}=0.64$  for both hulls. This increase referred as “the resistance crisis” appears at the boundary between the sub-critical and the transcritical regime. Finally, there is a decrease of the ship resistance at the entrance in the supercritical regime for  $F_{h,s}=F_{h2}=1.37$ . Parallel visualizations have been made during the resistance trials, with a high-speed camera Photron Fastcam SA1 of resolution  $1024 \times 1024 \text{ px}$  equipped with a Sigma 28 mm F1.8 DG ASP lens (Figure 8). The camera installed on the side of the canal, and captures images of the wave amplitudes at the window during the passage of the ship at a frequency of 125 *fps*. Then a dedicated algorithm assembles the images to give a picture-like representation of the wave amplitudes. Figure 10 represents the visualizations performed during the transition between the subcritical and transcritical regime (Froude-depth number  $F_{h,s}$  from 0.60 to 0.85 and Froude-length number  $F_{L,s}$  from 0.19 to 0.22). These visualizations highlight an increase of the transverse wavelength and amplitude at the boundary between the subcritical and transcritical regimes. A wave breaking is also visible on some waves. So when a ship navigates in a confined waterway, it experiences a sudden increase of its fuel consumption, and the waves that it generates grow, break and reflect on the river banks. That process is destructive for the river banks and needs to be investigated in a future work, to prevent its appearance and to design appropriate bank protections.

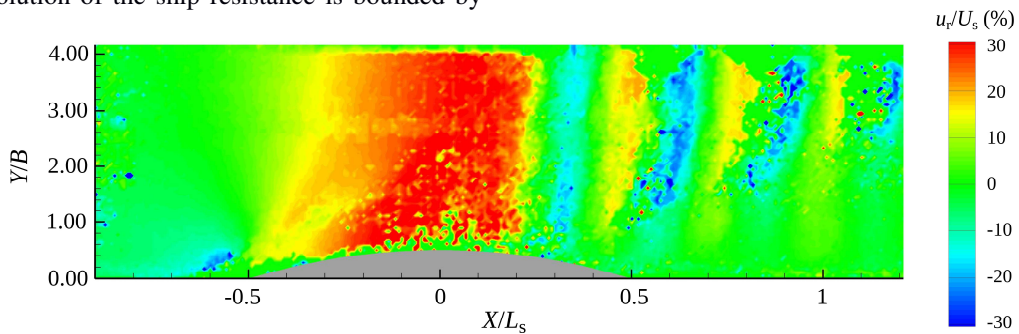


Figure 7. The return current  $u_r$  measured around the WH2 hull for a Froude-depth number  $F_{h,s}=0.70$  with the stereo-correlation measurement method.

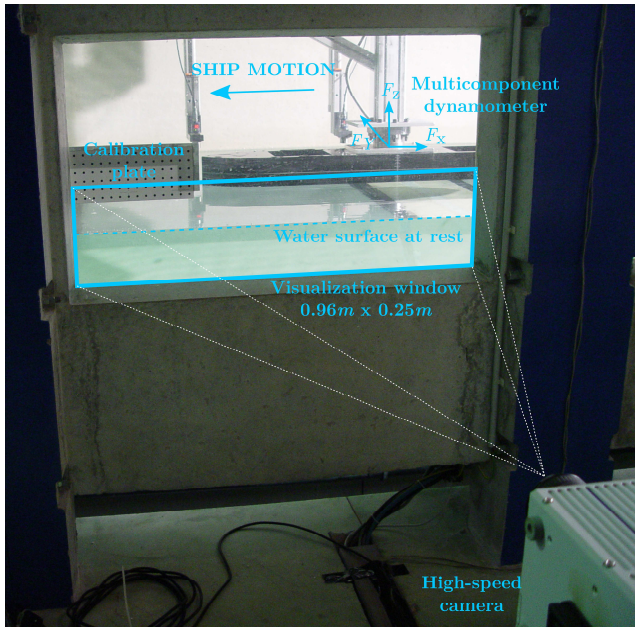


Figure 8. Measurement of the ship resistance with a multi-component dynamometer and lateral visualizations with a high-speed camera.

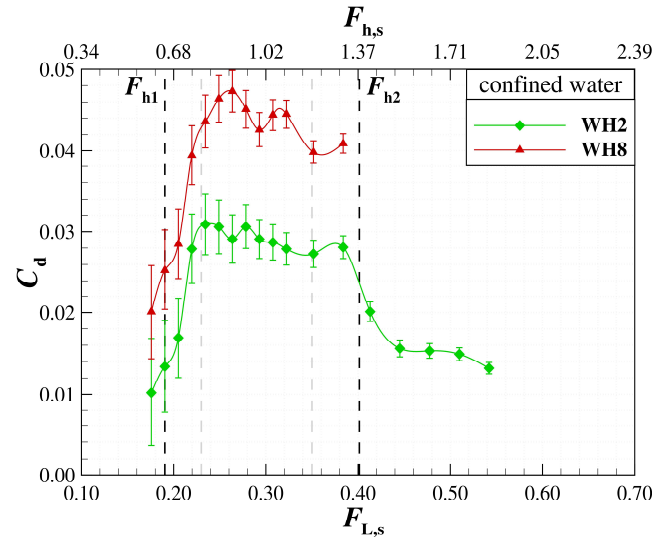


Figure 9. Drag coefficients of the ship hulls measured in a shallow water configuration for different ship speeds. The black dotted lines correspond to the critical Froude numbers  $F_{h1}=0.64$  and  $F_{h2}=1.37$  linked to the blockage of the waterway.

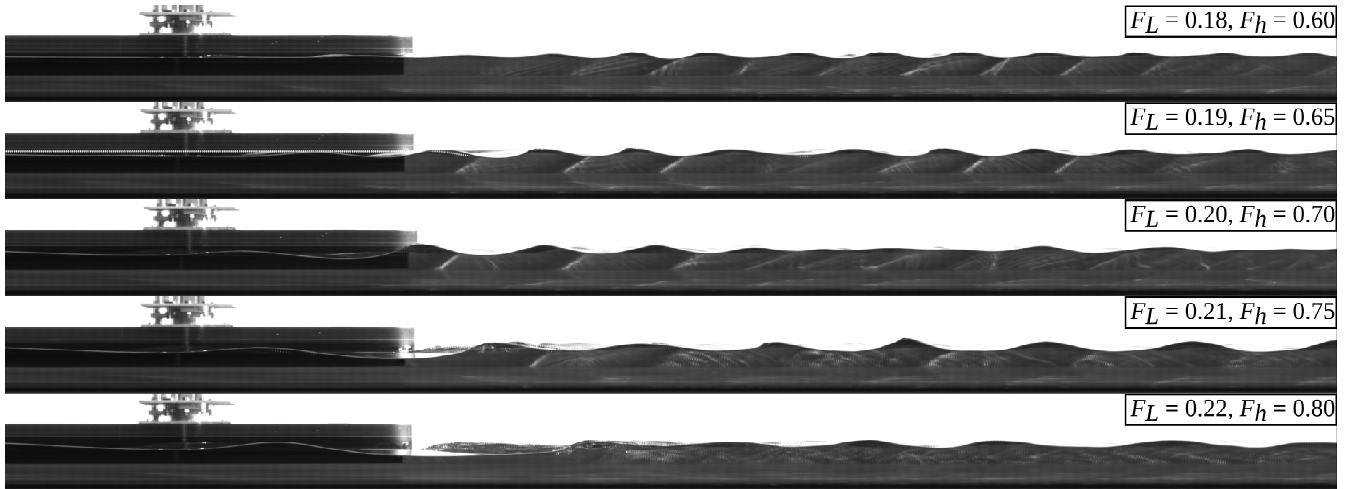


Figure 10. Visualizations of the wave amplitudes generated by the WH8 hull at the window of the canal in a shallow water configuration ( $h=0.103\text{ m}$ ). Ship speed is increasing from the top to the bottom.

## 5 CONCLUSIONS AND PERSPECTIVES

During the past few years, several experimental studies have been made in the towing tank of the Pprime Institute, to investigate the effects of confinement on ships wakes and drag and to understand interaction between the ship and the waterway. Measurement methods have been developed and adapted for this topic, to obtain a full and detailed measurement of the ship wake and to determine the drag forces applying on the hull. These methods give high quality results that allow to perform a fine analysis of the wave properties in both real and spectral spaces. The hydrodynamic effects appearing in the waterway can also be quantified and analyzed. The comparison of the resistance diagrams with the visualizations of the wakes allows to identify the visual footprint of the crisis of ship resistance. The towing tank of the Pprime Institute is currently under work, and will be lengthened of one third of its actual length, to reach 30 m. The towing carriage and the current generation will also be improved. These great improvements on the facility will open the way to future experimental studies, in order to continue the investigations on this path of research.

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