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Accurate Detection and Discrimination of Pollutant Gases Using a Temperature Modulated MOX Sensor Combined with Feature Extraction and Support Vector Classification

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Abstract

Gas detection and discrimination have been, until recently, sensors-specific, with different sensors and techniques used for each of the gases. In this work, we describe a novel approach relying on a single physical sensor in conjunction with data-driven algorithms for detecting the presence of one of the three dangerous gases: CO, NO₂, and O₃ individually or in mixtures. The approach uses a single Metal Oxide (MOX) sensor coupled with two heaters in its hardware part. Then, its software part uses a supervised machine learning model. The sensor is exposed to the different gases and their mixtures and would react accordingly with a change in its electric signals. These raw signals, along with the readings from the heaters, constitute the primary dataset for the discrimination.

To further enhance the classification results, the raw dataset is augmented by calculating several time-domain features of each of the measurements. Then, the features are ranked, and the ones with the best results to solve the classification problem are selected. Once the pretreatment of the data is finished, the selected features are used to train and validate a multi-support vector machine model. Finally, the results showcased in this paper highlight the effectiveness of the proposed approach.

Keywords: Air pollution, Air quality monitoring, Air quality sensor, Feature extraction, Feature selection, Gas detection, Gas sensors, Metal Oxide sensor, Multi-class classification, Support Vector Machines, ReliefF, Smart sensor, Temperature modulation, Time-domain feature extraction

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1. Introduction

The recent and quickening technological and industrial advancements made by man are a double-edged sword. While they helped elevate the quality of life to its best level, the negative effects of human activities are also observed environmentally and, more crucially, health-wise [1]. The concerns raised by these side effects have led, in part, to the development of monitoring tools [2, 3, 4] and regulation of air quality [5, 6]. In this work, we undertook the issue of detecting and identifying three of the major pollutant particles in the air, those are carbon monoxide (CO), ozone (O₃) and nitrogen dioxide (NO₂).

The study of air quality and the development of sensors for monitoring pollutants is not limited to its environmental aspect such as the detection of CO/CO₂ [7], NO₂ [8], and methane [9, 10] but extends into the scientific [11] and industrial applications such as the detection of volatile organic compounds (VOC) [12, 13, 14]. Additionally, the research in this area is approached out from several angles. Traditionally,

researchers have focused on the materials used in the sensors. Most of these studies are listed in several reviews [1, 15, 16, 17, 18, 19]. Of the more generalized studies, Alrammouz et al. [1] summarized the advancements made in the field of flexible gas sensors, listing several sensing materials in the process such as carbon nanotubes, conducting polymers, and the type of sensors used in this work Metal Oxides (MOX). The latter—alongside Field-effect transistor (FET) devices—were also the focus of a work by Sharma et al. [16] studying the advancement in sensing H_2 , whereas Dey [17] and [18] narrowed their focus into sensors based on Semiconductor Metal Oxide (SOM) and p-type Nickel Oxide, respectively. Alternatively, Yao et al. [20] and Wang [15] analyzed sensors based on metal-organic frameworks (MOFs), with the first work highlighting material design and performance of the sensors [20], and the second showcasing their application and the application of MOF-Based materials.

With the rise of machine learning (ML), data-driven models were combined with the sensors to obtain higher accuracy and achieve multi-gas selectivity [21]. For instance, multicomponent analysis techniques—notably Principal Component Analysis (PCA)—were one of the first techniques used in combination with sensors to monitor air quality [11, 22]. More recently, PCA was also used for the analysis of gas mixtures [23], and the detection of up to three pollutants simultaneously [24]. Besides PCA, Montoliu et al. [25] used multivariate curve resolution to enhance the sensitivity of MOX sensors to different gases.

The complexity of the task, especially in the presence of several gases or mixtures, led the researchers to use more advanced techniques such as neural networks [26] and Bayesian regularization [27]. In cases similar to this study (detection of air pollutants), Chu et al. [28] combined a sensor array with neural networks to detect CO, O₃, and NO₂ amongst other gases. Similarly, Esposito et al. [29] demonstrated a low-cost sensor and used dynamic neural networks to estimate the concentration of these pollutants, while Topalović et al. [30] compared the use of several ML approaches to achieve the same tasks.

The richness of the literature with research exploring different materials and methodologies is proof of the challenges faced in accurately identifying different gases present in gas mixtures, which remains an open issue. Most of the established approaches either focus on a specific pollutant and filter out any interference [9, 31] or try to overcome the challenge of detecting pollutants in gas mixtures by calibrating multiple sensors (sensor arrays) [28, 29, 30, 32, 33].

In this paper, we tackle the problem of identifying multiple gases in mixtures using a single sensor, by combining a temperature modulated MOX microsensor with a data-driven model. The method uses data from the MOX sensor and processes it in 3 steps. The first consists of changing the operating point of the sensors through temperature modulation, in order to increase the available information in the raw dataset. Then, the dataset is further augmented by extracting key temporal features. These features are automatically ranked by the ReliefF algorithm, with the highest-ranked selected by a custom algorithm for the classification step. Finally, Multi-class SVMs are used for the automatic classification of gases as they offer a wide choice of kernel functions allowing for the separation of classes (gases) by hyperplanes of varying

complexity.

Several established works have tackled the problem of discriminating multiple gases using a single sensor. However, they have either exhibited limited accuracy [12] or cannot be confidently generalized due to the weak number of the sample used in testing [34]. The results presented in this work, on the other hand, avoid these shortcomings and showcase the effectiveness of the proposed approach.

This case study focuses on three gases: carbon monoxide (CO), ozone (O₃), and nitrogen dioxide (NO₂). Nevertheless, the discrimination method is intended to be scalable by an automatic selection of new subsequent features depending on the gases, thus increasing the features space that can be used to train new SVM classifiers. Moreover, the wide choice of kernel functions will allow the algorithm to be adapted to the detection and identification of gases in mixtures with a higher number of gases.

This paper is divided into 7 sections. Section 2 is devoted to the description of the test bench, the characteristics of the MOX sensor, and the data acquisition procedure. Then, an overview of the gas discrimination methodology is given in Section 3. In Section 4, the method of augmenting the database by extracting time-domain features is presented. The ranking and selection of relevant features is explained in Section 5, and the gas classification algorithm is presented in Section 6. The results and discussions are detailed and analyzed in Section 7.

2. Sensor description and setup

2.1. The MOX sensor

The detection and identification of the toxic gases in this work are achieved by two components; a microsensor and an ML-Based model. The process starts with the sensor reacting to the presence of a gas with a change in its reading. Then, the model uses the readings to correctly classify the gas.

To generate the measurement, in this study, we rely on a MOX microsensor, that is the result of a newly developed and patented technology by the *Institut Matériaux Microélectronique Nanosciences de Provence* (IM2NP) and manufactured by Nanoz-SAS¹ [35]. The sensor is composed of four detection zones and two heaters. The detection zones can be configured to allow for the use of these sensors either in single or multi-sensor modes.

In this device, the heaters are located with the sensor on a SiO₂ membrane. At first, the heaters and the electrodes are built on a sputtered platinum thin film using photolithography. After which the sensitive Tungsten trioxide (WO₃) layer is deposited through reactive Radio Frequency Magnetron Sputtering. The WO₃ layer is then annealed for two hours at temperatures higher than the operating range for improved nano-crystallization and stability.

¹An operating exclusive worldwide license has been granted to NANOZ SAS, which develops manufactures and sells the sensors.

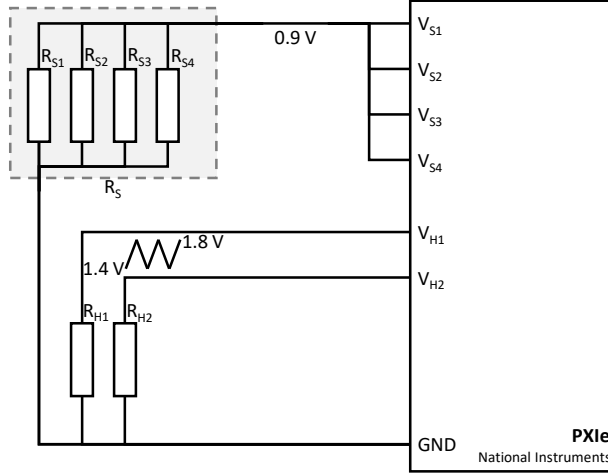


Figure 1: The electric diagram of the MOX sensor [35]. V_{S1} – V_{S4} are the voltages applied to the sensor resistances R_{S1} – R_{S4} , respectively. Similarly, V_{H1} and V_{H2} are the voltage values across heating resistances R_{H1} and R_{H2} , respectively.

The electrical configuration for the MOX sensor is shown in Figure 1. The figure also shows how the device is polarized by a National Instrument PXIe 4140 source meter. In this study, we have chosen to operate the device in a single sensor mode. The sensor is characterized by its resistance R_S and is polarized by 0.9 V [24]. The heaters, on the other hand, are powered by varying voltage—ranging between 1.4–1.8 V, as will explained in the next paragraph.

2.2. Experimental setup and data collection

The characterization and evaluation of the sensors are achieved by exposing it to the studied gases in a controlled environment, to enhance the gas flow hydrodynamics [36]. Therefore, the device is encased in a 3D-printed prototype test chamber that would improve the gas concentration homogeneity and reduce the flow recirculation and dead volumes [37]. The test chamber is then placed in a Faraday cage, in which the sensor is exposed to the different gases to measure its response. For a comprehensive test of the sensor thresholds, the concentration of the tested gases is varied through a dilution system [24]. The latter allows for the concentration of pollutant gas to be adjusted between 20 ppb and 16 ppm, in diluted in dry air under atmospheric pressure and ambient temperature. It is also capable of creating mixtures for a wider range of tests. The concentrations used in this work are displayed in Table 1. They also constitute the base concentrations values for all the possible gas mixtures.

Figure 2 gives an explanatory representation of the experimental setup, where the pollutants are mixed and have their concentration adjusted in the dilution system. The gases are then admitted to the test chamber where the sensor responds with a change in resistance. The response of the sensor as well as the states of heaters are recorded continuously in a dataset composed 7 variables :

- The sensors voltage (V_S , a constant in this study)

Table 1: The different concentrations used for each of the pollutant gases in this study.

Gases	Concentrations		
	C1	C2	C3
CO	2 ppm	8 ppm	16 ppm
NO ₂	20 ppb	100 ppb	200 ppb
O ₃	80 ppb	110 ppb	160 ppb

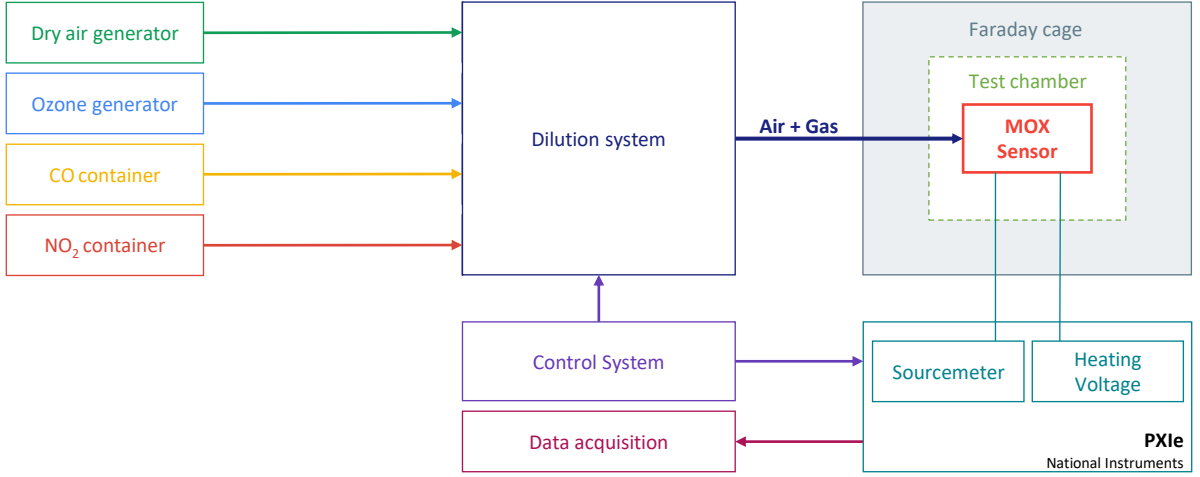


Figure 2: Experimental setup for the microsensor characterization, and the gas classifier training and testing.

- The sensors current (I_S)
- The sensors Resistance (R_S)
- Heater I voltage (V_{H1})
- Heater I current (I_{H1})
- Heater I power (P_{H1})
- Heater II voltage (V_{H2})
- Heater II current (I_{H2})
- Heater II power (P_{H2})

To obtain a larger set of sensor data and generate more accurate results with the classification model, the device is operated with variable heater temperatures, i.e. temperature modulation [19, 38]. In this operating mode, the heating voltage is varied triangularly with a staircase waveform of an amplitude of 0.4 V centered

on 1.6 V. Each step of the staircase signal has a value of ± 0.01 V and a duration of 1 s [24]. The range of the heater voltages (1.4–1.8 V) results in temperatures ranging between 199–252 °C which correspond to the edge of detection and the optimal detection temperatures for the studied gases, respectively [24]. This technique has been proven valuable in the literature. It has been used to increase the experimental data, thus extending the available information for processing and feature extraction by the use of wavelet transform [39] or an energy vector approach [32, 40], for instance. On the other hand, it was also used to enhance the sensitivity and selectivity of the sensors to different gas species [41, 42], with very encouraging results in the case of MOX sensors and sensors arrays [23, 25, 31, 43].

3. Gas discrimination methodology

Raw data provided by the sensor reflect the variation the latter undergoes when the different gases are present in the closed chamber. The idea is that each reading of the sensor’s resistance and current combined with the power information from the two heaters would correspond to a specific gas or a gas mixture, which leads to the classification problem.

Ideally, the readings from the sensors would lead to a direct—and visual—separation between the different classes. However, as seen in Figure 3, initial tests based solely on the readings from the system establish that the gases strongly overlap with each other, particularly in the cases of gas mixtures (CO + NO₂, CO + O₃, NO₂ + O₃, ...). The overlapping of the classes is a complex issue being studied in the literature [44]. It is even more complex in this work since gas mixtures are themselves overlapping classes of the pure gases. Hence, to simplify the classification problem, each of the gas mixtures will be considered as a distinct class, resulting in 7 classes overall: CO, NO₂, O₃, CO + NO₂, CO + O₃, NO₂ + O₃, and All. [In these mixtures, the three levels of concentration indicated in Table 1 are used, to cover all the possible concentrations. For instance, in the case of the CO + NO₂ gas, nine configurations are tested in total, ranging from CO \[2ppm\] + NO₂ \[20ppb\] to CO \[16ppm\] + NO₂ \[200ppb\].](#)

While considering gas mixtures as distinct classes eliminates one level of the overlapping classes problem, the classification problem is further accentuated by the use of a single sensor to generate readings, thus outlining the minimalism of characteristic data that could help distinguish the classes. To overcome this limitation, one viable solution is to extend the available dataset. This is possible through the extraction of the temporal, frequency, and energy features of the signals from the sensor and heaters.

The newly extracted features would, however, greatly increase the number of available features and it would be computationally inefficient to use all of them in the classification model. Thus, the next steps would be to rank the features according to their influence on the output, and select the feature that would generate the best results. These selected features would then be used to train a supervised ML model. The steps of the proposed approach are illustrated in Figure 4.

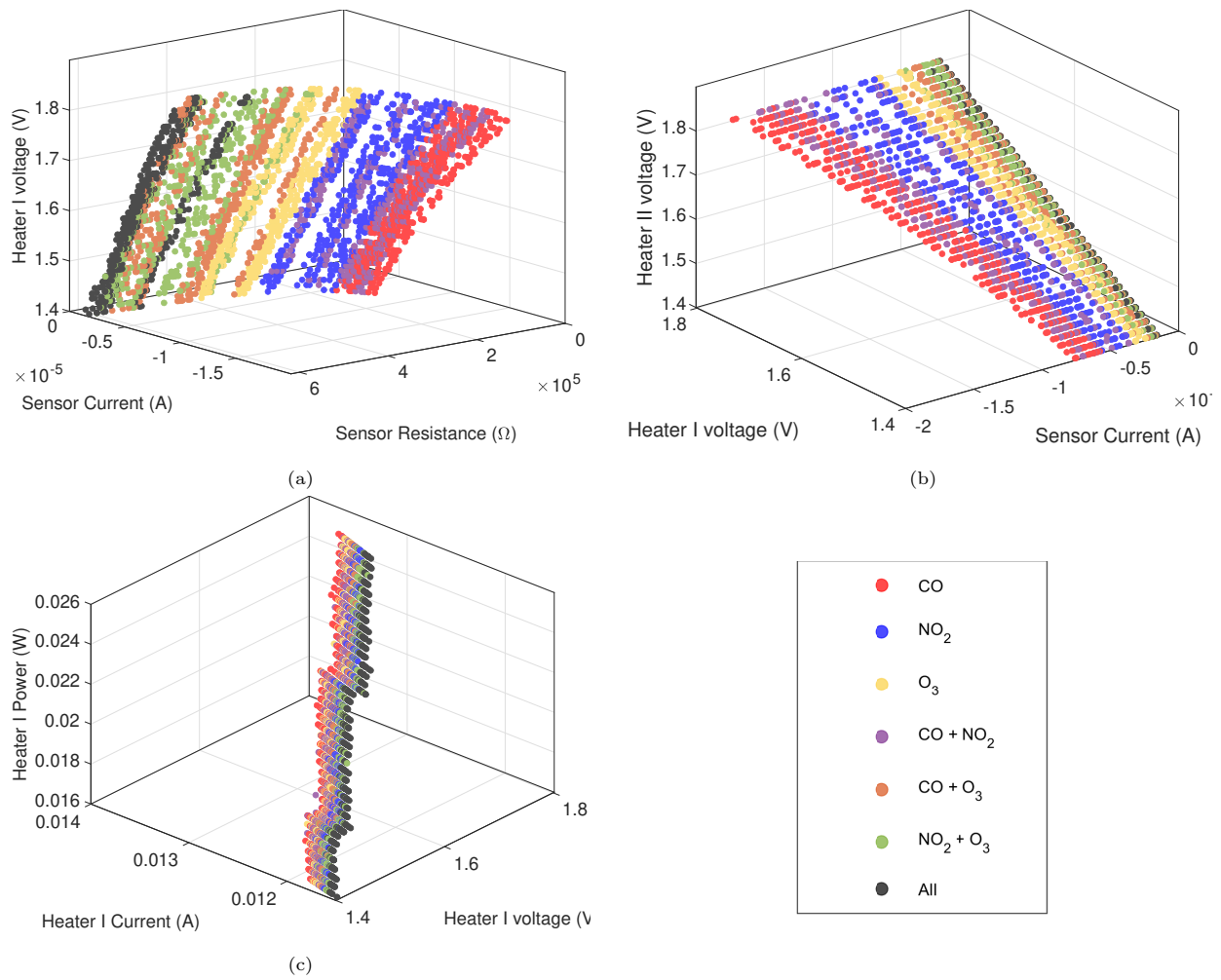


Figure 3: Visual representation of the distribution of the classes according to the initial features. It is impossible to separate the classes linearly.

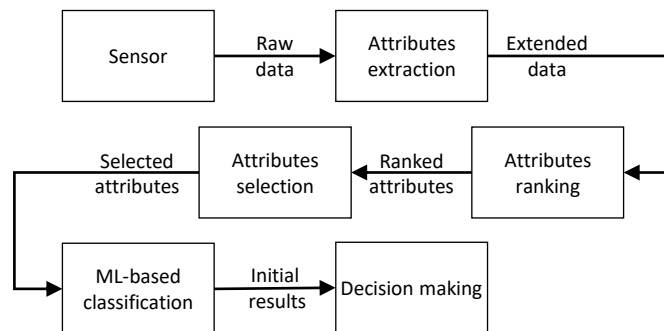


Figure 4: Overview of the gas detection and identification process.

4. Dataset augmentation

Attributes or feature extraction aims to manipulate the data to obtain further information that is not carried by the raw values of the signal but rather by its tendencies, distributions, and frequency-domain characteristics, amongst others [45].

The type and number of features to use depend heavily on the nature of the raw signals. For instance, periodic signals would benefit more from frequency domain analysis rather than time-domain feature extraction. Whereas noisy signal or those used for fault detection—like vibrations—would necessitate both time and frequency feature extraction [46]. The signals in this work, on the other hand, are non-periodic and present no noise, hence making time-domain features the most suitable for the present application. Furthermore, Amir Sattari et al. [34] have recently explored the use of feature extraction in the detection of the type of flow and the concentration of the gas in a two-phase flow meter. Their study yielded great results despite the weak number of testing samples preventing better generalization.

4.1. Chosen time-domain features

The most common time-domain features are statistical features that help differentiate between the different sequences of the signal attached to different classes (gases). These are the means (\bar{x} and the absolute mean $|\bar{x}|$), the standard deviation (σ), and the Root Mean Square (*RMS*) [47]. On the distribution side, Kurtosis and the Skewness are features used to examine the probability density function (PDF) of each signal sequence. Table 2 highlights all the features used to augment the dataset in this study, starting with the aforementioned features and their formulas, and continuing to other dimensionless time-domain features that have been proven useful in the literature to solve problems of detection and identification [45, 47].

4.2. Features calculation

The features presented in Table 2 are all computed over n samples, and each computed feature over these samples would constitute one entry n the extended dataset. Hence, to build the extended dataset, every vector (x) of the raw dataset would be split into k sequences composed of n samples. The number n can either be defined theoretically (using the signal period, for instance) or empirically by tuning it to generate the best results. In this work, the initial number n was set to be approximately one second of data acquisition. However, knowing a sampling period that is equal to $T_s \approx 0.2$ s would result in $n = 5$ which might be insufficient. We doubled the the value of n inspired by inverse of the Nyquist–Shannon sampling theorem. To be able to empirically compare the results of different cases, we doubled n a second time. Thus:

$$\left\{ \begin{array}{l} n_1 = \frac{1}{T_s} = 5 \\ n_2 = \frac{2}{T_s} = 10 \\ n_3 = \frac{4}{T_s} = 20 \end{array} \right. \quad (1)$$

Table 2: Time-domain features of to be computed for each of the data vectors.

Feature	Formula
Mean value (\bar{x})	$\bar{x} = \frac{1}{n} \sum_{i=1}^n x_i$
Absolutes mean value ($ \bar{x} $)	$ \bar{x} = \frac{1}{n} \sum_{i=1}^n x_i $
Standard deviation (σ)	$\sigma = \sqrt{\frac{1}{n} \sum_{i=1}^n (x_i - \bar{x})^2}$
Root mean square (RMS)	$RMS = \sqrt{\frac{1}{n} \sum_{i=1}^n x_i^2}$
Peak value (PV)	$PV = \max(x)$
Kurtosis value (KV)	$KV = \frac{\sum_{i=1}^n (x_i - \bar{x})^4}{n \sigma^4}$
Skewness ($Skew$)	$Skew = \frac{1}{n} \sum_{i=1}^n \frac{(x_i - \bar{x})^3}{\sigma^3}$
Crest Factor (CF)	$CF = \frac{PV}{RMS}$
Margin Factor (MF)	$MF = \frac{PV}{\left(\frac{1}{n} \sum_{i=1}^n \sqrt{ x_i }\right)^2}$
Impulse Factor (IF)	$IF = \frac{PV}{ \bar{x} }$
Form Factor (FF)	$FF = \frac{RMS}{ \bar{x} }$

Such configuration strikes balance between the speed of detection and accuracy. As, theoretically, the three value of n would allow the system to gather enough data to accurately detect and identify the gas, while still being quick to alarm users to the presence of danger. Once the raw vector (x) is split into k sequences, the features of each sequence are computed and organized into a matrix (x_{ext}) of k rows and 11 columns (the number of the features), as shown in Figure 5. Finally, the extended dataset of each class is then composed of the 8 extended matrices, hence raising the number of features from 8 in the raw dataset, into 88 in the extended one.

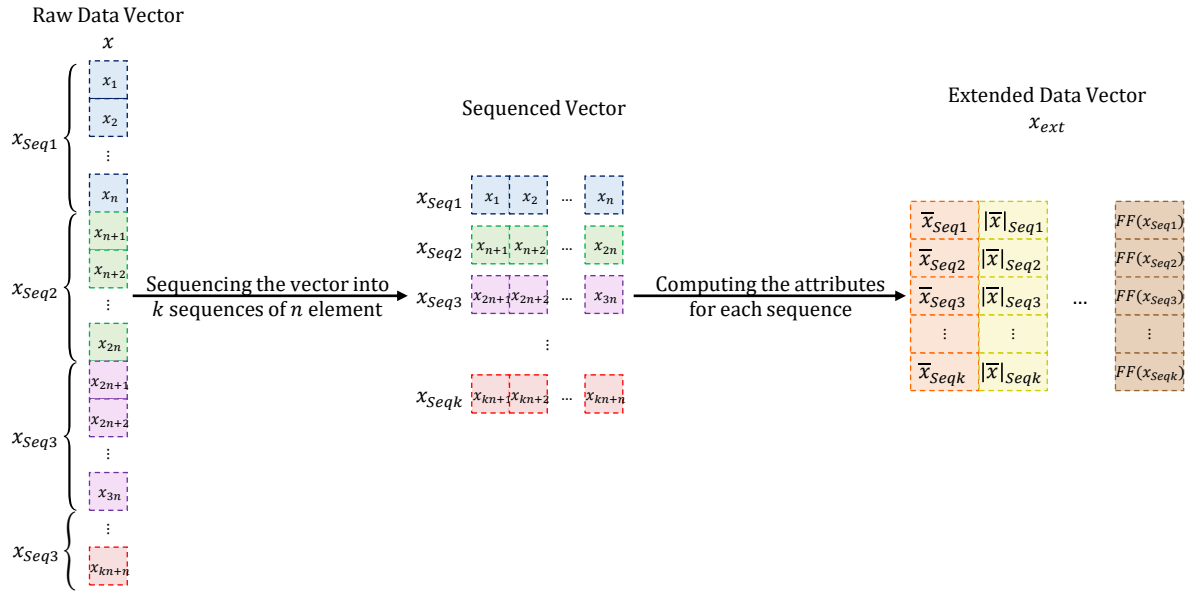


Figure 5: Sequencing and calculation of the features of a raw data vector x .

5. Feature ranking and selection

The extended dataset resulting from the feature extraction has 88 possible predictors for the classification model. While a classification model with an input this size is feasible, it is not computationally efficient both in training and online testing. Thus, its size needs to be reduced with a minimum loss of information.

Reducing the size of a database can be done through several approaches. The most known of which is the PCA [48] and its variants (such as independent component analysis [49]). With these techniques, reducing the size of a database is achieved by projecting the data into a reduced space by a linear or a non-linear mathematical transformation. The key advantage of these methods is preserving most of the variability even with a much-reduced size [11, 22, 50, 33]. However, the dimensions of the reduced space lose their physical meaning.

The literature is also rich with other approaches for the the selection of the features such as the heuristic

and iterative Sequential Forward Selection [51] and Sequential Backward Selection [52], or the graphical Branch and Bound [53] and its subsequent improvements [54, 55], or the algorithmic FOCUS [56, 57].

All of the previously mentioned methods have been used to achieve great results in the literature. However for this study, we aimed to keep the physical meaning of the signals—hence ruling out PCA—and make it computationally possible for an implementation in an embedded system with the sensor—ruling out the heuristic methods. Thus, we have opted to use the ReliefF methods for the ranking and its scores for the selection.

5.1. The ReliefF Features ranking algorithm

The Relief method is a widely used approach for feature ranking and selection, and is based on the nearest neighbor principle [58]. It has had a lot of variance since its release [59, 60, 61]. One of which is its adaptation for multi-class problems; the ReliefF [62].

In a summary, the ReliefF computes a weight for each of the features. The value of the weight depends on the performance of the feature in detecting classes. In the initialization phase, all the weights W are set to 0. Then, for n iteration, the algorithm randomly selects an instance x_r from the feature currently weighted A . With k being a predefined constant, the algorithm proceeds to find the nearest k neighbors to the instance x_r of the same class called Hits (H_{x_r}), and the nearest k neighbors to this instance of different classes (called Misses, M_{x_r}). The k nearest neighbors are computed using the Manhattan distance [62]. The weight of the feature A , during the iteration i , is computed by Equation 2 [59].

$$W[A] = W[A] - \frac{\Delta(A, x_r, H_{x_r})}{n \cdot k} + \frac{\Delta(A, x_r, M_{x_r})}{n \cdot k} \quad (2)$$

In this work, the features are numerical and continuous. Thus, the difference function Δ is equal to [59]:

$$\Delta(A, x_r, I_{x_r}) = \frac{\|A(x_r) - A(I_{x_r})\|}{\max(A) - \min(A)} \quad (3)$$

This operation is repeated for all the available features.

5.2. Features Selection

The ReliefF method would result in the ranking of all the features from best to worst, according to their weights. Nevertheless, the number of features remains unchanged. Some of the features would have negative weights associated with them and can be directly discarded, but the number of the remaining features would remain relatively high. In such cases, the number of features can be selected empirically from the highly ranked ones through trial and error. In this study, on the other hand, the features are selected by applying a median filter to the numerical differentiation of the ranked weights. This method allows us to keep highly ranked features and stop when the values of the weights drop suddenly.

The selection algorithm starts by sorting only the positive features and defining a minimum number of features to be selected. Then, it computes the numerical differentiation (Δ_{SA}) and selects features with

weights greater than the median value of Δ_{SA} . Algorithm 1 describes a pseudo-code of the features selection methodology. In this algorithm, the selection is applied three times generating three levels of features. Each subsequent level contains more information and will be used to build a different model for better accuracy and comparison. The results of each model will be given in Section 7.

Algorithm 1 Pseudo-code of the 3 levels features selection algorithm.

```

1: Begin
2: Define minimumFeatures, k
3: [ranking, weights] = ReliefF(xext, k)           ▷ Run the ReliefF and compute the ranks and weights
4: rankedFeatures = sort(xext, rankings)           ▷ Sort the extended features according to their ranks from best to
   worst
5: rankedWeights = sort(weights)                   ▷ Sort the weights from best to worst
6: rankedWeights(rankedWeights ≤ 0) = [ ]           ▷ Delete the weights less or equal than 0
7: rankedFeatures = rankedFeatures[0 : rankedWeights.length - 1] ▷ Delete the features with negative or zero
   weights
8: selectedFeatures = [0, 0, 0]
9: for j = 1 : selectedFeatures.length do           ▷ Computing the numerical differentiation
10:    $\Delta_{SA}(j) = \textit{rankedFeatures}(j) - \textit{rankedFeatures}(j - 1)$ 
11: currentFeatures = rankedFeatures
12: for i = 0 : (selectedFeatures.length - 1) do
13:   j = 0
14:   while currentFeatures(j) > median( $\Delta_{SA}$ ) do
15:     j = j + 1
16:   if j < minimumFeatures then
17:     selectedFeatures(i) = minimumFeatures
18:   else
19:     selectedFeatures(i) = j
20:   currentFeatures = rankedFeatures[j : rankedFeatures.length]
21: End

```

6. Gas discrimination using Multi-Class Support Vector Machines

Support Vector Machines (SVM) are binary classification methods used for both supervised and unsupervised learning. In this method, the algorithm searches for a separation hyperplane with an optimal margin between the two classes. This approach was proposed by Cortes and Vapnik [63], and is formally described as follows. Let us consider that a training data matrix (x) is composed of m features and a corresponding assigned label vector y of values $C1$ and $C2$, for the two classes. The classifier builds a model which predicts

the target class y from the input data (the features), by searching for an optimal hyperplane optimizing a quadratic problem (Equation 4).

$$\begin{aligned} \min J(a) &= \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N a_i a_j g_i(x) g_j(x) k(x, x) - \sum_{i=1}^N a_i \\ \text{s.t.} : \sum_{i=1}^N a_i g_i(x) &= 0, 0 \leq a_i \leq D \text{ for } i = 1, \dots, N \end{aligned} \quad (4)$$

where $g(x) = 1$ if $x \in C1$ and $g(x) = -1$ if $x \in C2$, $a = [a_1, a_2, \dots, a_N]^T$ are the Lagrange multipliers, D is the penalty parameter, and $k(x, x)$ is the Kernel function. Then, the output is estimated by the decision function :

$$y = \begin{cases} 1 & , \text{ if } \text{sign} \left(\sum_{i=1}^S a_i^S g_i^S k(x_i^S, x) + b \right) = 1 \\ -1 & , \text{ elsewhere} \end{cases} \quad (5)$$

whereas:

$$b = \frac{1}{S} \sum_{j=1}^S \left(g_j^S - \sum_{i=1}^S a_i^S g_i^S k(x_i^S, x_j^S) \right) \quad (6)$$

In this work, since there 7 gases, we use a Multi-Class Support Vector Machine (MC-SVM) classifier. The version used in this work is the error-correcting output codes (ECOC) classifier, which consists of several binary SVM used in tandem to solve the multi class problems [64]. The ECOC is used in both in its "One against One" and "One against All" configurations [65]. In the first configuration, the classifier trains $n * (n - 1)/2$ binary SVM, whereas in the second one n binary SVM classifiers are built, with n being the number of classes. The classification results are obtained by a voting strategy: a pattern is classified to the class where the maximum number of votes is obtained.

7. Experimentation and results

This section is divided into three parts. The first part is dedicated to the division of the data and the extraction of the features. The second one focuses on the ranking and the selection of the features. Finally, the section ends with the results from the SVM classifiers, and comparative analysis of the results between the different approaches.

7.1. Data preprocessing

As described in Section 2, the sensor delivers 9 measurements per sample. One of these measurements—the sensors voltage—is constant and thus carries no information. Consequently, only the other 8 measurements are to be used for feature extraction and classification.

Furthermore, the data gathered from the experimentation are not uniformly distributed. Table 3 shows the number of samples per class and highlights the inequality between them. As it is, this dataset would

cause an issue of imbalanced learning for SVMs. Since, the latter, by design, require the same number of samples for each class [66]. This problem has been and is still being studied in the literature [67, 68], resulting in several creative solutions [69, 70].

Table 3: Raw and Extended datasets distribution amongst the 7 classes. FE: Feature Extraction. * $n = \frac{1}{T_s}$

Class	Label	Raw data samples	Samples after FE		
			$n = 5^*$	$n = 10$	$n = 20$
CO	1	24003	4800	2400	1200
NO ₂	2	24003	4800	2400	1200
O ₃	3	16002	3200	1600	800
CO + NO ₂	4	72009	14401	7200	3600
CO + O ₃	5	72009	14401	7200	3600
NO ₂ + O ₃	6	72009	14401	7200	3600
All	7	40005	8001	4000	2000

The study of imbalanced learning largely comes into play when there is a great difference in the representation of the classes. However, implementing such solutions would add additional processing layers, and is not the purpose of this study, especially with the number of instances for the least represented class is sufficient for training and testing the model. Therefore, to avoid the problems related to imbalanced learning, the classes datasets are balanced by determining the set with the fewest samples N —in this case, O₃—and then dividing it into a 70% training set and 30% test set. For the rest of the classes, the test sets are built by randomly selecting $0.3 \times N$ samples for each class. These sets are set apart and only used to obtain final test results. The training sets, on the other hand, are built by randomly sampling $0.7 \times N$ instances at each new step of the cross-validation. As can be seen in Table 3, from the number of samples after the extraction of the features with different values of n , the class O₃ has the fewest samples. Accordingly, the number of samples used for the training and the test phases will be based on its size.

7.2. Features ranking and selection

Once the features are extracted, the ReliefF algorithm is applied to the resultant training extended sets. During our testings, the best results were obtained with the number of nearest neighbors $k = 12$. The 30 highest ranked are displayed in Table 4. The latter shows that the highest-ranked features are mostly independent of the number of samples per instance (n). It also indicates—counter-intuitively—that the highest-ranked features are not the ones extracted from the sensor’s measurements, but rather from the measurements of the first heater V_{H1} , I_{H1} , with the features of I_S coming after them.

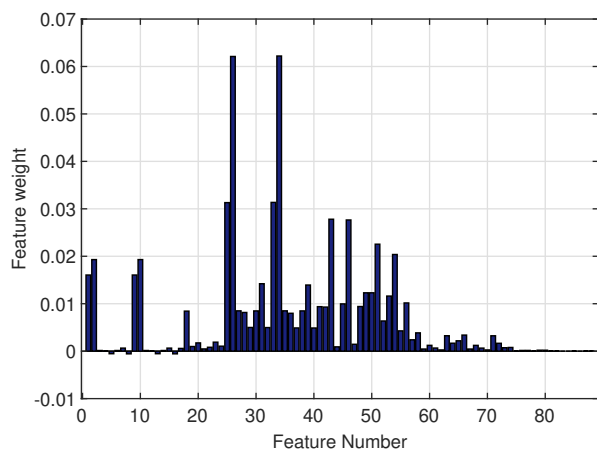
Furthermore, while the highest-ranked features remain largely unchanged for all values of n , their weights vary significantly enough with every value of n to be a major factor in changing the outcome of the selection algorithm. The other major factor is the minimum number of features per iteration, which was set to 4 in

this study (c.f. Algorithm 1). Thus, the number of predictors used to train the Support Vector Classifiers varies with n . In Table 4, row colors indicate the features used to train each of the three models per n value. These features are also shown ranked from highest to lowest in Figure 6, showing the difference between the three levels. The figure also shows the weights of all the 88 features for the three values of n .

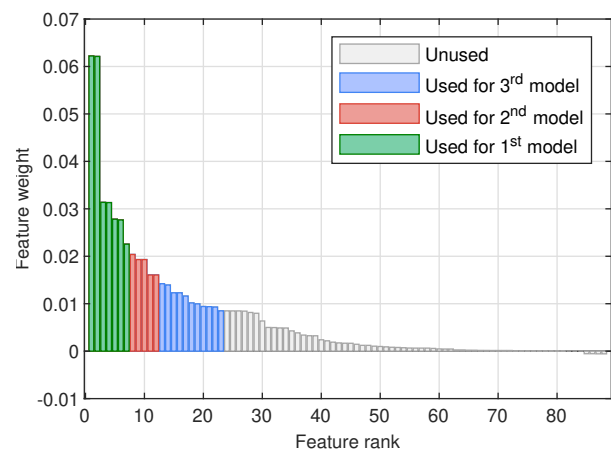
Finally, Figure 7 highlights a better visual separability between the classes according to the highest-ranked features, compared to using raw readings (Figure 3). The separability is especially visible for the classes O_3 and All in Figures 7a and 7c. The classes CO and NO_2 also show better potential for separability in Figures 7c, indicating the potential of achieving high accuracy with the MC-SVM.

Table 4: Results of the ReliefF : the 30 highest ranked features for different values of n . **FN**: Feature Number. **VN**: Variable Name. **FN**: Feature Name. **W**: Weight. **Green**: Features used for the first model. **Green + Red**: Features used for the second model. **Green + Red + Blue**: Features used for the third model. **Grey** : Unused features.

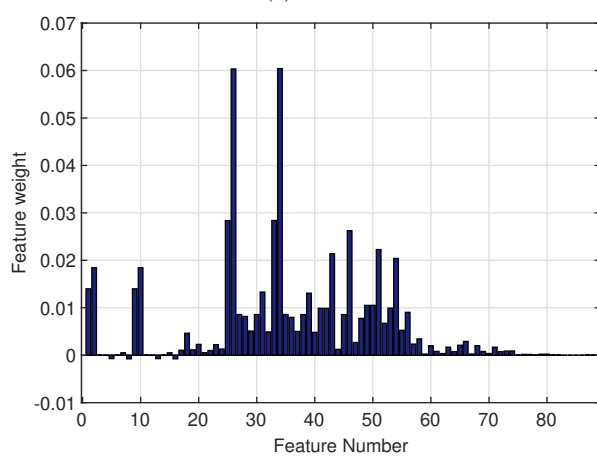
n	5				10				20			
Rank	FN	VN	AN	W	FN	VN	AN	W	FN	VN	AN	W
1	26	$V_{H1}(V)$	PV	0.07658	26	$V_{H1}(V)$	PV	0.06924	26	$V_{H1}(V)$	PV	0.07122
2	34	$I_{H1}(A)$	$ \bar{x} $	0.07616	34	$I_{H1}(A)$	$ \bar{x} $	0.06919	34	$I_{H1}(A)$	$ \bar{x} $	0.07077
3	25	$V_{H1}(V)$	RMS	0.03942	33	$I_{H1}(A)$	\bar{x}	0.03324	33	$I_{H1}(A)$	\bar{x}	0.03476
4	33	$I_{H1}(A)$	\bar{x}	0.03940	25	$V_{H1}(V)$	RMS	0.03310	25	$V_{H1}(V)$	RMS	0.03468
5	2	$I_S(A)$	σ	0.02417	2	$I_S(A)$	σ	0.02265	2	$I_S(A)$	σ	0.02247
6	10	$I_S(A)$	IF	0.02417	10	$I_S(A)$	IF	0.02265	10	$I_S(A)$	IF	0.02247
7	1	$I_S(A)$	$ \bar{x} $	0.01922	31	$V_{H1}(V)$	MF	0.01751	17	$R_S(\Omega)$	$Skew$	0.01812
8	9	$I_S(A)$	MF	0.01922	1	$I_S(A)$	$ \bar{x} $	0.01715	1	$I_S(A)$	$ \bar{x} $	0.01696
9	17	$R_S(\Omega)$	$Skew$	0.01899	9	$I_S(A)$	MF	0.01715	9	$I_S(A)$	MF	0.01696
10	31	$V_{H1}(V)$	MF	0.01619	17	$R_S(\Omega)$	$Skew$	0.01713	31	$V_{H1}(V)$	MF	0.01652
11	39	$I_{H1}(A)$	$Skew$	0.01508	39	$I_{H1}(A)$	$Skew$	0.01623	39	$I_{H1}(A)$	$Skew$	0.01528
12	49	$P_{H1}(W)$	KV	0.01284	49	$P_{H1}(W)$	KV	0.01305	55	$V_{H2}(V)$	\bar{x}	0.01131
13	50	$P_{H1}(W)$	$Skew$	0.01267	50	$P_{H1}(W)$	$Skew$	0.01285	47	$P_{H1}(W)$	RMS	0.01056
14	28	$V_{H1}(V)$	$Skew$	0.01110	28	$V_{H1}(V)$	$Skew$	0.01157	49	$P_{H1}(W)$	KV	0.01032
15	36	$I_{H1}(A)$	RMS	0.01013	36	$I_{H1}(A)$	RMS	0.01062	50	$P_{H1}(W)$	$Skew$	0.01011
16	18	$R_S(\Omega)$	CF	0.00862	47	$P_{H1}(W)$	RMS	0.00845	28	$V_{H1}(V)$	$Skew$	0.01008
17	20	$R_S(\Omega)$	MF	0.00755	18	$R_S(\Omega)$	CF	0.00773	44	$P_{H1}(W)$	\bar{x}	0.01003
18	41	$I_{H1}(A)$	MF	0.00639	41	$I_{H1}(A)$	MF	0.00700	36	$I_{H1}(A)$	RMS	0.00947
19	44	$P_{H1}(W)$	\bar{x}	0.00612	44	$P_{H1}(W)$	\bar{x}	0.00672	18	$R_S(\Omega)$	CF	0.00834
20	42	$I_{H1}(A)$	MF	0.00606	42	$I_{H1}(A)$	MF	0.00669	20	$R_S(\Omega)$	MF	0.00719
21	47	$P_{H1}(W)$	RMS	0.00598	20	$R_S(\Omega)$	MF	0.00660	41	$I_{H1}(A)$	MF	0.00699
22	55	$V_{H2}(V)$	\bar{x}	0.00557	55	$V_{H2}(V)$	\bar{x}	0.00638	42	$I_{H1}(A)$	MF	0.00669
23	32	$V_{H1}(V)$	IF	0.00485	22	$V_{H1}(V)$	\bar{x}	0.00521	52	$P_{H1}(W)$	MF	0.00593
24	52	$P_{H1}(W)$	MF	0.00484	32	$V_{H1}(V)$	IF	0.00501	22	$V_{H1}(V)$	\bar{x}	0.00586
25	22	$V_{H1}(V)$	\bar{x}	0.00442	40	$I_{H1}(A)$	CF	0.00445	45	$P_{H1}(W)$	$ \bar{x} $	0.00468
26	40	$I_{H1}(A)$	CF	0.00434	29	$V_{H1}(V)$	CF	0.00397	23	$V_{H1}(V)$	$ \bar{x} $	0.00457
27	29	$V_{H1}(V)$	CF	0.00404	45	$P_{H1}(W)$	$ \bar{x} $	0.00396	57	$V_{H2}(V)$	σ	0.00418
28	21	$R_S(\Omega)$	IF	0.00379	57	$V_{H2}(V)$	σ	0.00376	65	$V_{H2}(V)$	IF	0.00404
29	37	$I_{H1}(A)$	PV	0.00376	37	$I_{H1}(A)$	PV	0.00361	32	$V_{H1}(V)$	IF	0.00366
30	57	$V_{H2}(V)$	σ	0.00355	65	$V_{H2}(V)$	IF	0.00360	40	$I_{H1}(A)$	CF	0.00312



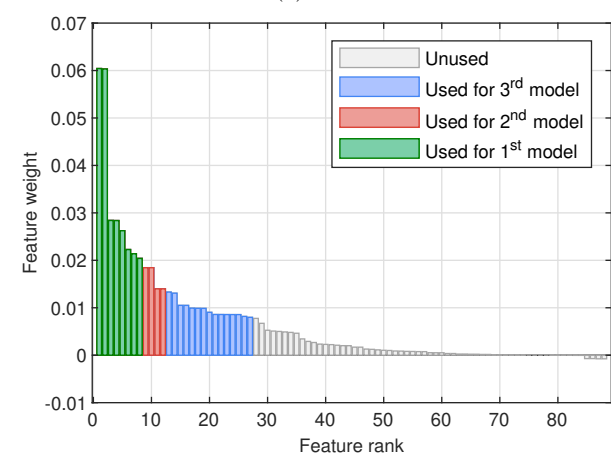
(a) $n = 5$



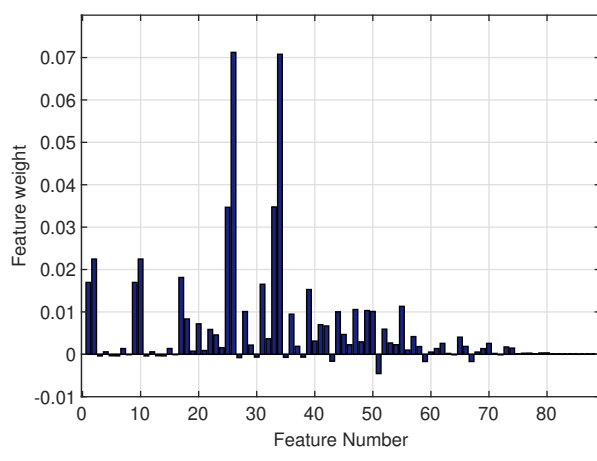
(b) $n = 5$



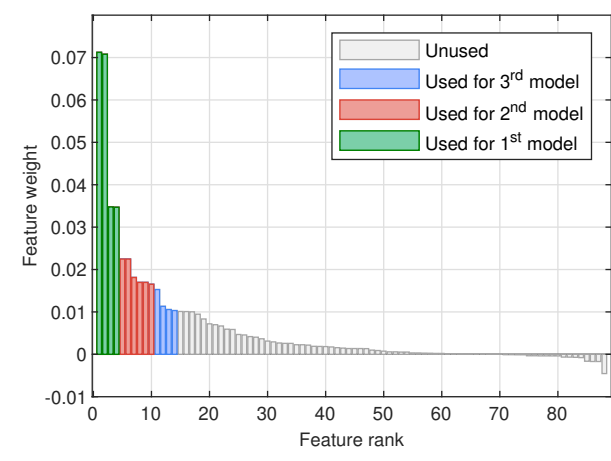
(c) $n = 10$



(d) $n = 10$



(e) $n = 20$



(f) $n = 20$

Figure 6: The rank and the weights of the all features from all the values of n .

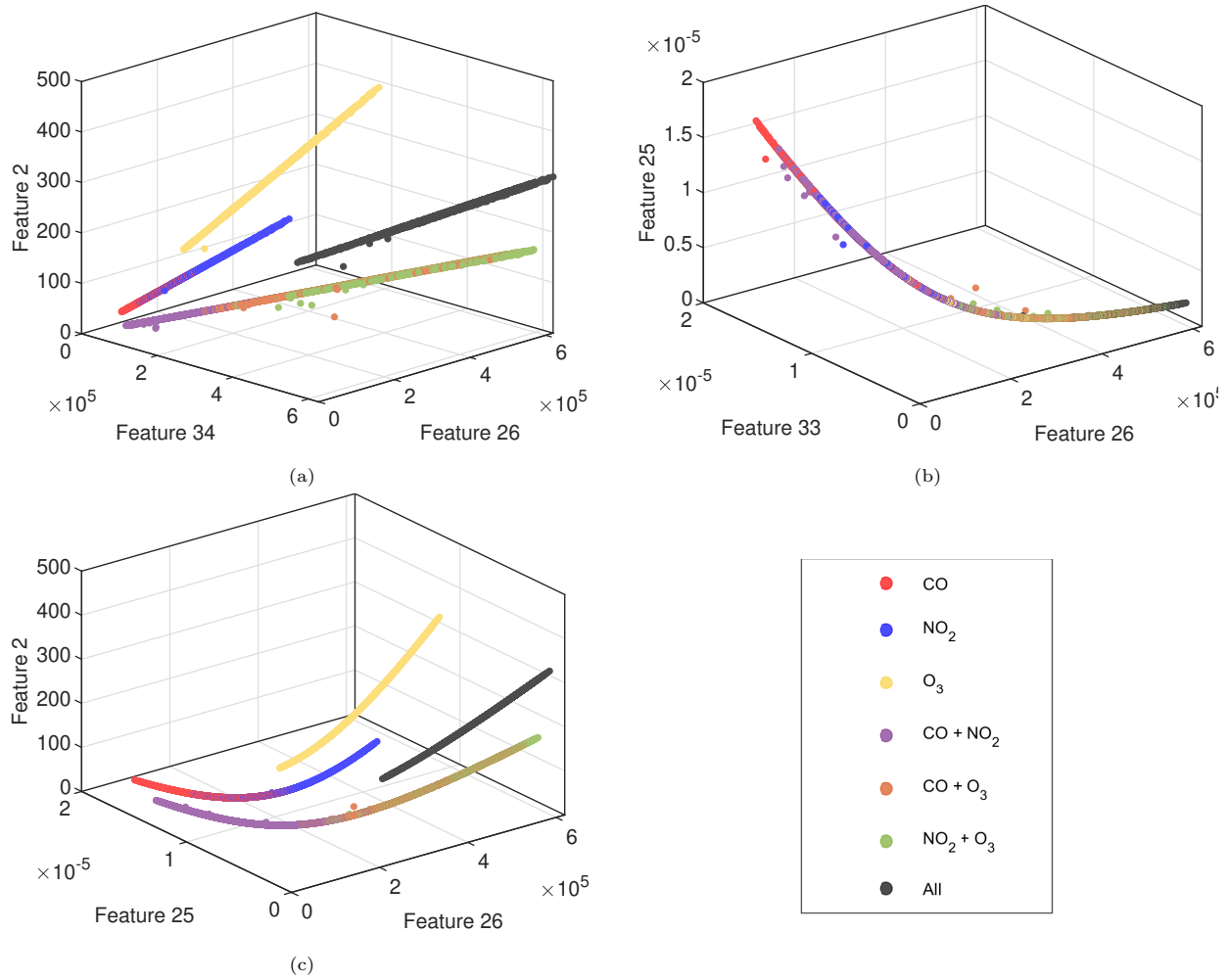


Figure 7: Visual representation of the distribution of the classes according to the highest-ranked features for $n = 20$.

7.3. Support vector classification results

The results presented in this paragraph showcase all the approaches and the tuning done to the classifiers to generate the best possible results. Thus, these results are divided into 4 Tables (Tables 5–8). Each table contains the results of the classification per class, then averaged results of the 7 classes. The training results represent the results after a k -fold cross-validation on the training set ($k = 5$), whereas the test results are gathered from the predictions of the model on a separate test dataset (c.f. Paragraph 7.1). The results are reported in terms of metrics that are well-established in the literature. These metrics are all computed by comparing the model’s predictions and the targets. This comparison results in 4 types of predictions per class: True Positives (TP), True Negatives (TN), False Positives (FP), and False Negatives (FN). Thus, models’ performance metrics are listed below.

- **The Accuracy (ACC):** The most basic metric. It is the ratio of the correctly classified instances

over the total number of the instances.

$$\text{ACC}(\%) = \frac{TP + TN}{TP + TN + FP + FN} \times 100 \quad (7)$$

- **The Mis-classification Rate (MR):**

$$\text{MR}(\%) = 100 - \text{ACC} \quad (8)$$

- **The Precision (PRCN):** The ratio of the correctly identified positive class.

$$\text{PRCN}(\%) = \frac{TP}{TP + FP} \times 100 \quad (9)$$

- **The Recall:** The true positive rate, or the ratio of correctly identified positives of all the positive class instances.

$$\text{Recall}(\%) = \frac{TP}{TP + FN} \times 100 \quad (10)$$

- **The F1_Score (F1):** Most commonly used for the comparison between the models. It takes into account both the Recall and the Precision.

$$\text{F1} = 2 \cdot \frac{\text{PRCN} \cdot \text{Recall}}{\text{PRCN} + \text{Recall}} \quad (11)$$

The results in Tables 5– 8 are the best results with these predictors after all the tuning was done. They are color-coded to facilitate their investigation and the comparison between the different models and configurations. Perfect scores are colored in purple, while the rest of the scores are colored from green (best) to red (worst).

Starting with Table 5, it showcases the results from two preliminary models built to serve as references of base performance. The first model—which we will call Power Model, hereafter—is a classifier that uses the minimum amount of data, with only three inputs: the power readings from the sensor and two heaters. The second model is a support vector classifier that relies on the non-transformed raw data from the sensors. So, it has 8 inputs. This model will be referred to as the Raw Data Model. While both models deliver good performance overall, notably in the case of the *One against all* classifiers, they both take a hit in performance with the binary gas mixtures. However, they still deliver better performance than the first level models that rely on feature extraction and feature selection using the ReliefF. For instance, in Table 6 ($n = 5$), the results of the first models with 6 predictors are far worse than those of the Power the Raw Data Models. The same conclusion can be drawn for the first models in Table 7 (8 predictors) and those in Table 6 (4 predictors).

The low performance of these models cannot be explained by the number of predictors, as the Power Model contains even fewer predictors. It can be explained, however, by the predictors used. In these first

models, most of the predictors come from readings of the first heater (notably V_{H1}). This is especially relevant for $n = 20$, where only 4 features extracted from V_{H1} were used as predictors and no information from the sensor whatsoever.

The first tier of models highlights that—while the ranking of the feature and the difference between their weights are important factors for the selection—the distribution of the information is also a primordial criterion, during the selection of the features. In Algorithm 1, the minimum number of features was included to mitigate such shortcomings. While its value of 4 was not high enough for the first tier of models, nevertheless, it forced the addition of 4 features to the second model for the case of $n = 10$, instead of two as computed by the median filter (Figure 6d), resulting in the use of 12 predictors. Table 7 shows how the performance for this tier of models increased significantly, achieving even perfect test results. As for $n = 20$, results from Table 8 show that, for the second tier of models, the inclusion of features from the sensor’s measurements lead to achieving perfect results, even with fewer predictors compared to the case of $n = 10$, thanks to the greater number of samples per instance.

The duality of the number of predictors and the number of samples per instance is also visible in the case of $n = 5$, where a greater number of predictors (23) is needed to achieve 100% test results because of the fewer samples used to compute every feature instance.

The results presented in this paragraph demonstrate that achieving perfect discrimination is possible with multiple configurations. However, a compromise needs to be struck between the speed of detection and the available computational power, as more samples per instance require more time to be collected, and more features require a greater computational capacity to be computed.

Finally, Figure 8 and Figure 9 show examples for separating hyperplanes for the cases of $n = 10$ and $n = 20$, respectively.

Table 5: Results of the classification of the gases using the minimum amount of data (power measurements as predictors) in a first model test and the raw data set in the second one.

Model	Power Measurements						Raw Data					
	3			8			3			8		
	One vs one		Test Set	One vs all		Test Set	One vs one		Test Set	One vs all		Test Set
CO	ACC (%)	93.18	92.96	97.33	97.33	97.33	93.15	92.92	97.33	97.33	97.33	
	PRCN (%)	70.35	69.68	90.05	90.05	90.05	67.92	67.15	90.05	90.05	90.05	
	MR (%)	6.82	7.04	2.67	2.67	2.67	6.85	7.08	2.67	2.67	2.67	
	Recall (%)	90.29	89.84	91.42	91.42	91.42	98.61	98.69	91.42	91.42	91.42	
	F1 (%)	79.08	78.48	90.73	90.73	90.73	80.44	79.92	90.73	90.73	90.73	
NO2	ACC (%)	93.37	93.45	99.37	99.37	99.37	96.28	96.59	99.37	99.37	99.37	
	PRCN (%)	69.70	69.99	97.28	97.28	97.28	80.01	81.52	97.28	97.28	97.28	
	MR (%)	6.63	6.55	0.63	0.63	0.63	3.72	3.41	0.63	0.63	0.63	
	Recall (%)	94.80	94.77	98.31	98.31	98.31	98.61	98.44	98.31	98.31	98.31	
	F1 (%)	80.34	80.52	97.79	97.79	97.79	88.34	89.19	97.79	97.79	97.79	
O3	ACC (%)	97.73	97.70	99.99	99.99	99.99	97.73	97.77	99.99	99.99	99.99	
	PRCN (%)	87.40	87.17	99.96	99.96	99.96	86.63	86.75	99.96	99.96	99.96	
	MR (%)	2.27	2.30	0.01	0.01	0.01	2.27	2.23	0.01	0.01	0.01	
	Recall (%)	98.31	98.38	99.98	99.98	99.98	99.49	99.56	99.98	99.98	99.98	
	F1 (%)	92.53	92.44	99.97	99.97	99.97	92.62	92.72	99.97	99.97	99.97	
CO + NO2	ACC (%)	86.93	86.79	96.70	96.70	96.70	89.39	89.47	96.70	96.70	96.70	
	PRCN (%)	61.88	60.55	89.48	89.48	89.48	92.96	93.04	89.48	89.48	89.48	
	MR (%)	13.07	13.21	3.30	3.30	3.30	10.61	10.53	3.30	3.30	3.30	
	Recall (%)	22.10	21.64	87.13	87.13	87.13	27.83	28.39	87.13	87.13	87.13	
	F1 (%)	32.56	31.89	88.29	88.29	88.29	42.83	43.50	88.29	88.29	88.29	
CO + O3	ACC (%)	94.00	93.79	99.01	99.01	99.01	93.52	93.49	99.01	99.01	99.01	
	PRCN (%)	89.70	89.13	97.03	97.03	97.03	79.95	79.58	97.03	97.03	97.03	
	MR (%)	6.00	6.21	0.99	0.99	0.99	6.48	6.51	0.99	0.99	0.99	
	Recall (%)	65.56	64.40	95.98	95.98	95.98	72.95	73.23	95.98	95.98	95.98	
	F1 (%)	0.76	0.75	0.97	0.97	0.97	0.76	0.76	0.97	0.97	0.97	
NO2 + O3	ACC (%)	90.62	90.36	98.11	98.11	98.11	89.54	89.59	98.11	98.11	98.11	
	PRCN (%)	69.16	67.79	93.50	93.50	93.50	65.27	65.58	93.50	93.50	93.50	
	MR (%)	9.38	9.64	1.89	1.89	1.89	10.46	10.41	1.89	1.89	1.89	
	Recall (%)	61.94	61.99	93.25	93.25	93.25	57.28	57.11	93.25	93.25	93.25	
	F1 (%)	65.35	64.76	93.38	93.38	93.38	61.01	61.06	93.38	93.38	93.38	
All	ACC (%)	94.67	94.74	99.09	99.09	99.09	94.23	94.32	99.09	99.09	99.09	
	PRCN (%)	75.12	75.60	96.18	96.18	96.18	77.65	77.92	96.18	96.18	96.18	
	MR (%)	5.33	5.26	0.91	0.91	0.91	5.77	5.68	0.91	0.91	0.91	
	Recall (%)	93.76	93.27	97.50	97.50	97.50	83.71	84.07	97.50	97.50	97.50	
	F1 (%)	83.41	83.51	96.83	96.83	96.83	80.57	80.87	96.83	96.83	96.83	
Averaged	ACC (%)	92.93	92.83	98.51	98.51	98.51	93.41	93.45	98.51	98.51	98.51	
	PRCN (%)	74.99	74.73	94.81	94.81	94.81	76.20	76.26	94.81	94.81	94.81	
	Recall (%)	75.25	74.90	94.80	94.80	94.80	76.92	77.07	94.80	94.80	94.80	
	microF1 (%)	75.12	74.81	94.80	94.80	94.80	76.56	76.66	94.80	94.80	94.80	
	macroF1 (%)	72.72	72.34	94.78	94.78	94.78	74.59	74.79	94.78	94.78	94.78	

Table 6: The results from support vector classifiers using Attributes Extraction (AE) from data augmentation and ReliefF for predictor selection. Case of $n = 5$.

Model	AE + ReliefF, $n = 5$											
	7			12			23					
	Linear			RBF			Linear			RBF		
One vs one												
Number of predictors	Linear			RBF			Linear			RBF		
Kernel function	Linear			RBF			Linear			RBF		
Multiclass method	Linear			RBF			Linear			RBF		
Results	Training set	Test set	Training set	Test set	Training set	Test set	Training set	Test set	Training set	Test set	Training set	Test set
CO	ACC (%)	92.67	92.34	98.61	92.22	98.60	98.97	99.50	98.82	99.96	99.96	100.00
	PRCN (%)	71.04	70.73	93.71	72.90	95.82	96.87	98.38	97.42	99.69	99.69	100.00
	MR (%)	7.33	7.66	1.39	7.78	1.40	1.03	0.50	1.18	0.04	0.04	0.00
	Recall (%)	81.97	82.57	96.73	75.75	94.32	96.19	98.12	94.59	100.00	100.00	100.00
NO2	F1 (%)	76.11	76.19	95.20	74.30	95.06	96.53	98.25	95.98	99.84	99.84	100.00
	ACC (%)	92.02	92.31	98.05	92.46	98.65	98.97	99.55	98.78	100.00	100.00	100.00
	PRCN (%)	69.20	69.18	90.34	72.18	94.48	96.07	98.15	94.43	100.00	100.00	100.00
	MR (%)	7.98	7.69	1.95	7.54	1.35	1.03	0.45	1.22	0.00	0.00	0.00
O3	Recall (%)	80.44	83.23	96.81	76.77	96.24	96.77	98.72	97.19	100.00	100.00	100.00
	F1 (%)	74.40	75.56	93.46	74.41	95.35	96.42	98.43	95.79	100.00	100.00	100.00
	ACC (%)	94.41	94.94	98.40	95.27	100.00	100.00	100.00	99.96	100.00	100.00	100.00
	PRCN (%)	77.92	80.11	91.52	79.63	100.00	100.00	100.00	99.78	100.00	100.00	100.00
CO + NO2	MR (%)	5.59	5.06	1.60	4.73	0.00	0.00	0.00	0.04	0.00	0.00	0.00
	Recall (%)	85.34	82.78	97.96	86.89	100.00	100.00	100.00	99.89	100.00	100.00	100.00
	F1 (%)	81.46	81.42	94.63	83.10	100.00	100.00	100.00	99.83	100.00	100.00	100.00
	ACC (%)	86.08	85.85	97.18	86.80	100.00	100.00	100.00	99.99	100.00	100.00	100.00
CO + O3	PRCN (%)	51.93	52.32	94.86	55.25	100.00	100.00	100.00	100.00	100.00	100.00	100.00
	MR (%)	13.92	14.15	2.82	13.20	0.00	0.00	0.00	0.01	0.00	0.00	0.00
	Recall (%)	34.90	32.28	84.87	49.44	100.00	100.00	100.00	99.90	100.00	100.00	100.00
	F1 (%)	41.74	39.92	89.59	52.18	100.00	100.00	100.00	99.95	100.00	100.00	100.00
NO2 + O3	ACC (%)	87.38	87.49	95.78	89.52	89.02	89.14	97.50	91.74	99.99	99.99	99.91
	PRCN (%)	58.02	56.82	91.54	64.11	62.81	63.01	91.86	70.08	100.00	100.00	99.57
	MR (%)	12.62	12.51	4.22	10.48	10.98	10.86	2.50	8.26	0.01	0.01	0.09
	Recall (%)	40.99	43.45	77.55	56.87	56.14	53.89	90.46	71.35	99.96	99.96	99.79
All	F1 (%)	48.04	49.25	83.97	60.27	59.29	58.09	91.15	70.71	99.98	99.98	99.68
	ACC (%)	86.21	85.71	96.55	87.08	89.03	89.14	97.51	91.76	100.00	100.00	99.91
	PRCN (%)	51.90	49.80	89.82	55.57	60.34	60.38	90.63	71.41	100.00	100.00	99.79
	MR (%)	13.79	14.29	3.45	12.92	10.97	10.86	2.49	8.24	0.00	0.00	0.09
Averaged	Recall (%)	41.66	38.56	85.43	46.39	66.73	68.97	91.97	70.22	100.00	100.00	99.58
	F1 (%)	46.22	43.46	87.57	50.57	63.37	64.39	91.30	70.81	100.00	100.00	99.69
	ACC (%)	88.41	88.24	96.55	90.43	99.96	100.00	99.96	100.00	99.96	99.96	100.00
	PRCN (%)	56.49	57.00	83.43	64.68	100.00	100.00	100.00	100.00	100.00	100.00	100.00
Averaged	MR (%)	11.59	11.76	3.45	9.57	0.04	0.00	0.04	0.00	0.04	0.04	0.00
	Recall (%)	79.45	81.26	94.42	76.80	99.73	100.00	99.73	100.00	99.73	99.73	100.00
	F1 (%)	66.03	67.00	88.59	70.22	99.86	100.00	99.86	100.00	99.86	99.86	100.00
	ACC (%)	89.60	89.55	97.30	90.54	96.47	96.60	99.15	97.29	99.99	99.99	99.97
Averaged	PRCN (%)	64.36	64.05	90.37	67.37	87.55	88.01	97.01	90.60	99.96	99.96	99.91
	MR (%)	63.63	63.44	90.58	66.81	87.68	88.25	97.02	90.60	99.96	99.96	99.91
	Recall (%)	63.99	63.75	90.48	67.09	87.61	88.13	97.02	90.60	99.96	99.96	99.91
	macroF1 (%)	62.00	61.83	90.43	66.44	87.56	87.92	97.00	90.44	99.96	99.96	99.91

Table 7: The results from support vector classifiers using Attributes Extraction (AE) from data augmentation and ReliefF for predictor selection. Case of $n = 10$

Model	AE + ReliefF, $n = 10$												
	8				12				27				
	Linear		RBF		Linear		RBF		Linear		RBF		
Number of predictors		Kernel function		Muticlass method		One vs one							
Results	Training set	Test set	Training set	Test set	Training set	Test set	Training set	Test set	Training set	Test set	Training set	Test set	
	CO	ACC (%)	99.02	98.93	99.40	98.78	100.00	100.00	100.00	100.00	100.00	100.00	100.00
PRCN (%)		98.91	98.03	98.76	98.01	100.00	100.00	100.00	100.00	100.00	100.00	100.00	
MR (%)		0.98	1.07	0.60	1.22	0.00	0.00	0.00	0.00	0.00	0.00	0.12	
Recall (%)		94.36	94.33	97.14	93.28	100.00	100.00	100.00	100.00	100.00	100.00	99.16	
NO2	F1 (%)	96.58	96.15	97.94	95.59	100.00	100.00	100.00	100.00	100.00	100.00	99.58	
	ACC (%)	99.02	98.93	99.40	98.72	100.00	100.00	100.00	100.00	100.00	100.00	99.82	
	PRCN (%)	94.50	94.71	97.12	93.42	100.00	100.00	100.00	100.00	100.00	100.00	98.80	
	MR (%)	0.98	1.07	0.60	1.28	0.00	0.00	0.00	0.00	0.00	0.00	0.18	
O3	Recall (%)	98.94	98.17	98.76	98.17	100.00	100.00	100.00	100.00	100.00	100.00	100.00	
	F1 (%)	96.67	96.41	97.93	95.74	100.00	100.00	100.00	100.00	100.00	100.00	99.39	
	ACC (%)	100.00	100.00	100.00	99.94	100.00	100.00	100.00	100.00	100.00	100.00	99.94	
	PRCN (%)	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	
CO + NO2	MR (%)	0.00	0.00	0.00	0.06	0.00	0.00	0.00	0.00	0.00	0.00	0.06	
	Recall (%)	100.00	100.00	100.00	99.60	100.00	100.00	100.00	100.00	100.00	100.00	99.60	
	F1 (%)	100.00	100.00	100.00	99.80	100.00	100.00	100.00	100.00	100.00	100.00	99.80	
	ACC (%)	100.00	100.00	100.00	99.97	100.00	100.00	100.00	100.00	100.00	100.00	99.97	
CO + O3	PRCN (%)	100.00	100.00	100.00	99.78	100.00	100.00	100.00	100.00	100.00	100.00	99.78	
	MR (%)	0.00	0.00	0.00	0.03	0.00	0.00	0.00	0.00	0.00	0.00	0.03	
	Recall (%)	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	
	F1 (%)	100.00	100.00	100.00	99.89	100.00	100.00	100.00	100.00	100.00	100.00	99.89	
NO2 + O3	ACC (%)	89.71	89.97	97.93	94.91	100.00	100.00	100.00	100.00	100.00	100.00	99.52	
	PRCN (%)	67.88	69.25	96.66	84.91	100.00	100.00	100.00	100.00	100.00	100.00	99.79	
	MR (%)	10.29	10.03	2.07	5.09	0.00	0.00	0.00	0.00	0.00	0.00	0.48	
	Recall (%)	52.07	53.85	88.49	78.38	100.00	100.00	100.00	100.00	100.00	100.00	96.88	
All	F1 (%)	58.93	60.58	92.39	81.51	100.00	100.00	100.00	100.00	100.00	100.00	98.31	
	ACC (%)	89.71	89.97	97.93	94.88	100.00	100.00	100.00	100.00	100.00	100.00	99.43	
	PRCN (%)	62.20	61.92	89.72	79.57	100.00	100.00	100.00	100.00	100.00	100.00	96.54	
	MR (%)	10.29	10.03	2.07	5.12	0.00	0.00	0.00	0.00	0.00	0.00	0.57	
Averaged	Recall (%)	76.19	75.84	97.05	85.92	100.00	100.00	100.00	100.00	100.00	100.00	99.58	
	F1 (%)	68.49	68.18	93.24	82.63	100.00	100.00	100.00	100.00	100.00	100.00	98.04	
	ACC (%)	100.00	100.00	100.00	99.94	100.00	100.00	100.00	100.00	100.00	100.00	99.94	
	PRCN (%)	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	
Averaged	MR (%)	0.00	0.00	0.00	0.06	0.00	0.00	0.00	0.00	0.00	0.00	0.06	
	Recall (%)	100.00	100.00	100.00	99.59	100.00	100.00	100.00	100.00	100.00	100.00	99.59	
	F1 (%)	100.00	100.00	100.00	99.79	100.00	100.00	100.00	100.00	100.00	100.00	99.79	
	ACC (%)	96.78	96.83	99.24	98.16	100.00	100.00	100.00	100.00	100.00	100.00	99.79	
Averaged	PRCN (%)	87.98	88.37	97.19	93.46	100.00	100.00	100.00	100.00	100.00	100.00	99.24	
	Recall (%)	88.66	88.92	97.32	93.58	100.00	100.00	100.00	100.00	100.00	100.00	99.25	
	microF1 (%)	88.32	88.65	97.26	93.52	100.00	100.00	100.00	100.00	100.00	100.00	99.25	
	macroF1 (%)	88.67	88.76	97.36	93.56	100.00	100.00	100.00	100.00	100.00	100.00	99.26	

Table 8: The results from support vector classifiers using Attributes Extraction (AE) from data augmentation and ReliefF for predictor selection. Case of $n = 20$

Model	AE + ReliefF, $n = 10$															
	Linear				RBF				Linear				RBF			
	4		10		14		10		14		10		14			
Number of predictors																
Kernel function																
Multiclass method																
Results	Training set		Test set		Training set		Test set		Training set		Test set		Training set		Test set	
CO	ACC (%)	91.66	90.18	97.73	90.95	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00
	PRCN (%)	66.15	57.26	92.59	61.03	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00
	MR (%)	8.34	9.82	2.27	9.05	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
	Recall (%)	74.51	67.34	89.88	65.33	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00
	F1 (%)	70.08	61.89	91.21	63.11	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00
NO2	ACC (%)	91.94	92.44	97.91	92.44	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00
	PRCN (%)	70.18	73.61	90.69	75.76	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00
	MR (%)	8.06	7.56	2.09	7.56	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
	Recall (%)	79.14	80.61	95.69	76.05	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00
	F1 (%)	74.39	76.95	93.12	75.90	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00
O3	ACC (%)	93.44	93.93	99.21	97.02	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00
	PRCN (%)	76.12	80.65	95.25	85.92	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00
	MR (%)	6.56	6.07	0.79	2.98	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
	Recall (%)	74.52	78.74	99.05	96.06	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00
	F1 (%)	75.31	79.68	97.11	90.71	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00
CO + NO2	ACC (%)	84.49	83.10	96.51	85.89	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00
	PRCN (%)	47.75	39.57	89.49	51.80	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00
	MR (%)	15.51	16.90	3.49	14.11	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
	Recall (%)	36.05	30.20	86.90	46.94	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00
	F1 (%)	41.09	34.26	88.18	49.25	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00
CO + O3	ACC (%)	86.53	85.06	95.94	91.43	100.00	100.00	100.00	99.70	100.00	100.00	100.00	100.00	100.00	99.46	100.00
	PRCN (%)	55.37	45.54	90.72	73.80	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00
	MR (%)	13.47	14.94	4.06	8.57	0.00	0.00	0.00	0.30	0.00	0.00	0.00	0.00	0.00	0.54	0.54
	Recall (%)	46.21	39.48	80.86	59.23	100.00	100.00	100.00	97.85	100.00	100.00	100.00	100.00	100.00	96.14	96.14
	F1 (%)	50.38	42.30	85.51	65.71	100.00	100.00	100.00	98.92	100.00	100.00	100.00	100.00	100.00	98.03	98.03
NO2 + O3	ACC (%)	86.56	84.46	95.71	88.57	100.00	100.00	100.00	99.70	100.00	100.00	100.00	100.00	100.00	99.35	100.00
	PRCN (%)	55.53	44.44	86.36	59.52	100.00	100.00	100.00	97.96	100.00	100.00	100.00	100.00	100.00	95.62	100.00
	MR (%)	13.44	15.54	4.29	11.43	0.00	0.00	0.00	0.30	0.00	0.00	0.00	0.00	0.00	0.65	0.65
	Recall (%)	40.31	35.00	83.94	62.50	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00
	F1 (%)	46.71	39.16	85.13	60.98	100.00	100.00	100.00	98.97	100.00	100.00	100.00	100.00	100.00	97.76	100.00
All	ACC (%)	88.44	87.98	97.09	92.50	100.00	100.00	100.00	99.70	100.00	100.00	100.00	100.00	100.00	99.88	100.00
	PRCN (%)	56.40	56.63	86.06	73.26	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00
	MR (%)	11.56	12.02	2.91	7.50	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.12	0.12
	Recall (%)	83.54	76.42	94.99	76.83	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	99.19	99.19
	F1 (%)	67.34	65.05	90.31	75.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00	99.59	99.59
Averaged	ACC (%)	89.01	88.16	97.16	91.26	100.00	100.00	100.00	99.91	100.00	100.00	100.00	100.00	100.00	99.81	100.00
	PRCN (%)	61.70	60.04	89.94	70.16	100.00	100.00	100.00	99.70	100.00	100.00	100.00	100.00	100.00	99.32	100.00
	Recall (%)	61.03	58.96	89.92	69.82	100.00	100.00	100.00	99.71	100.00	100.00	100.00	100.00	100.00	99.36	100.00
	microF1 (%)	61.36	59.49	89.93	69.99	100.00	100.00	100.00	99.71	100.00	100.00	100.00	100.00	100.00	99.34	100.00
	macroF1 (%)	60.76	57.04	90.08	68.66	100.00	100.00	100.00	99.70	100.00	100.00	100.00	100.00	100.00	99.34	100.00

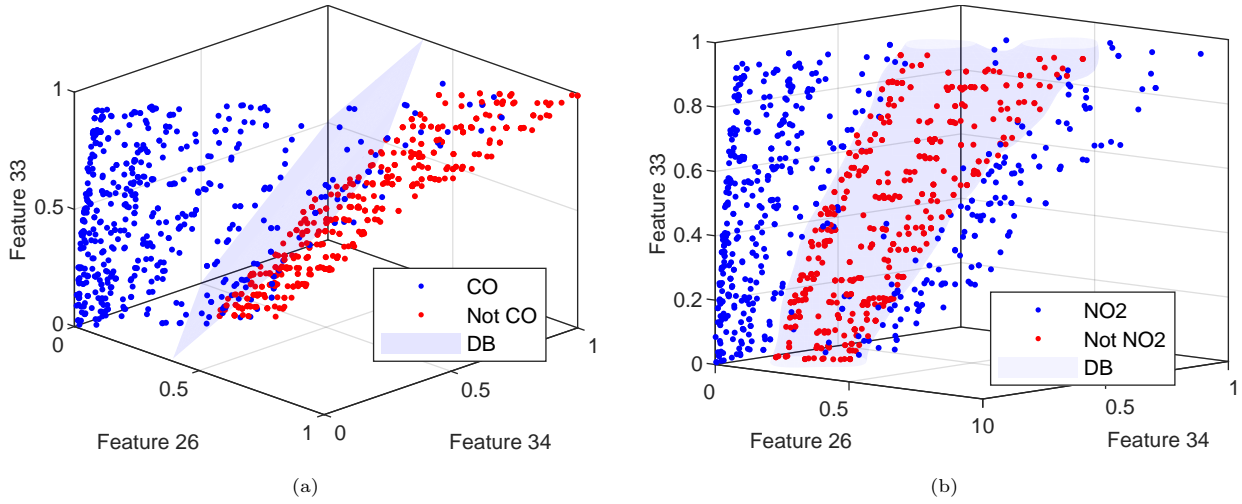


Figure 8: Graphical representation of the separation hyperplanes obtained by the support vector classifiers. Case $n = 10$. (a): Linear kernel function. (b): RBF kernel function.

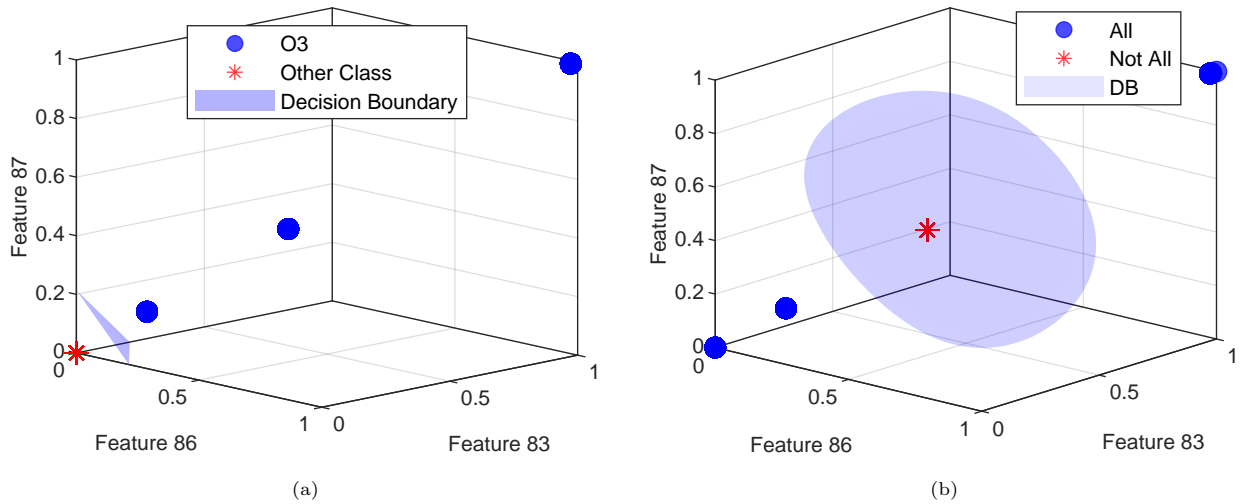


Figure 9: Graphical representation of the separation hyperplanes obtained by the support vector classifiers. Case $n = 20$. (a): Linear kernel function. (b): RBF kernel function.

8. Conclusion

In this paper, we have investigated the use of a single MOX sensor, temperature modulated, to detect and identify multiple gas species and mixtures of these species. The temperature modulation allows the permanent changing of the sensor operating point, and thus its sensitivity to different gases. Then, a data-driven method that exploits and augments the signals delivered by the microsensor is proposed. The data augmentation is achieved through time-domain feature extraction. Increasing the raw database by

extracting temporal features enrich the prior knowledge available while maintaining a clear physical sense of all features. The significant increase in the feature space gives the potential to extend the algorithm to detect and identify a larger number of gases.

The newly extracted features were then ranked by the ReliefF algorithm. The highest-ranking features are then automatically selected as predictors for the MC-SVMs. The automatic selection of the relevant features (which carry the information necessary for the detection and identification of gases) reduces the space of the features used in the learning step and, therefore, the complexity of the MC-SVM classifiers. The Radial Basis Function is used as a kernel and gives promising results.

The experimental results, obtained using data from a test bench of the IM2NP laboratory at Aix-Marseille University show the relevance of temperature modulation, as the most ranked features, selected by the ReliefF algorithm are the heaters current and voltage. The performance analysis results highlights the effectiveness of this method by recording a 100% of accuracy with different metrics (Accuracy, Racall and F1 metric). Additionally, thanks to the availability of a wide choice of kernel functions, using the MC-SVM classifier allowed us to build models able to achieve perfect test scores using several configurations. This flexibility is the result of the well-chosen features that improved the separability of the classes. Furthermore, the ability to use multiple configurations allows us to strike balance between the speed of detection and the number of features necessary for accurate discrimination.

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